

## 150KHz, 2A / 40V Step-Down LED Driver

### General Description

LN2103 is a step down LED driver that is designed to meet least 2A continuous output current for high power LED application, and utilizes PWM control scheme that switches with 150KHz fixed frequency.

The input voltage range of LN2103 is from 4.2V to 40V. It is suitable for series-parallel 1W, 3W, or 5W high power LED application due to the high operation voltage and output capability. At 24V input voltage, this device can drive up to 30pcs 1W LED(6S-5P) with constant 350mA LED current.

The PWM control circuit is able to vary the duty ratio linearly from 0 up to 100%. This device also contains an error amplifier circuit as well as a soft-start circuit that prevents overshoot at startup. An enable function, an over current protect function and a short circuit protect function are built inside, and when OCP or SCP happens, the operation frequency will be reduced from 150KHz to 30KHz. Also, an internal compensation block is built in to minimum external component count.

The package is available in a standard SOP-8.

### Package

- SOP-8

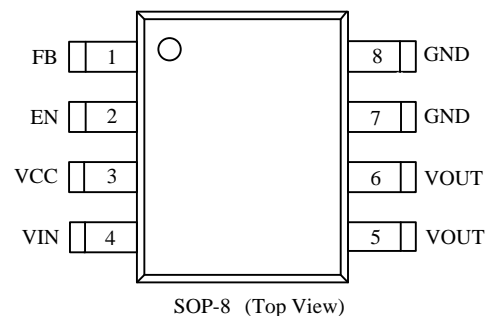


### Features

- Input voltage: 4.2V to 40V.
- Low Feedback Voltage 0.23V.
- Driving up to 30 LEDs (1W 6S-5P) at 24 V<sub>IN</sub>
- Oscillation frequency: 150KHz typ.
- Soft-start, Current limit, Enable function
- Great Output Capability
- PWM or Analog Dimming Control
- Thermal Shutdown function
- Built-in internal P-channel MOS
- SOP-8 Package.

### Applications

- High Power LED Driver
- Backlight Application
- General Lighting Solution
- Constant Current Source



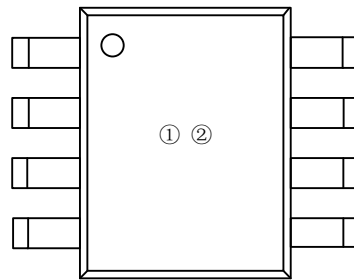
### Ordering Information

Ordering Number	Package	Unit	Quantity
LN2103	SOP-8	Tape&Reel	2500EA

## Pin Assignment

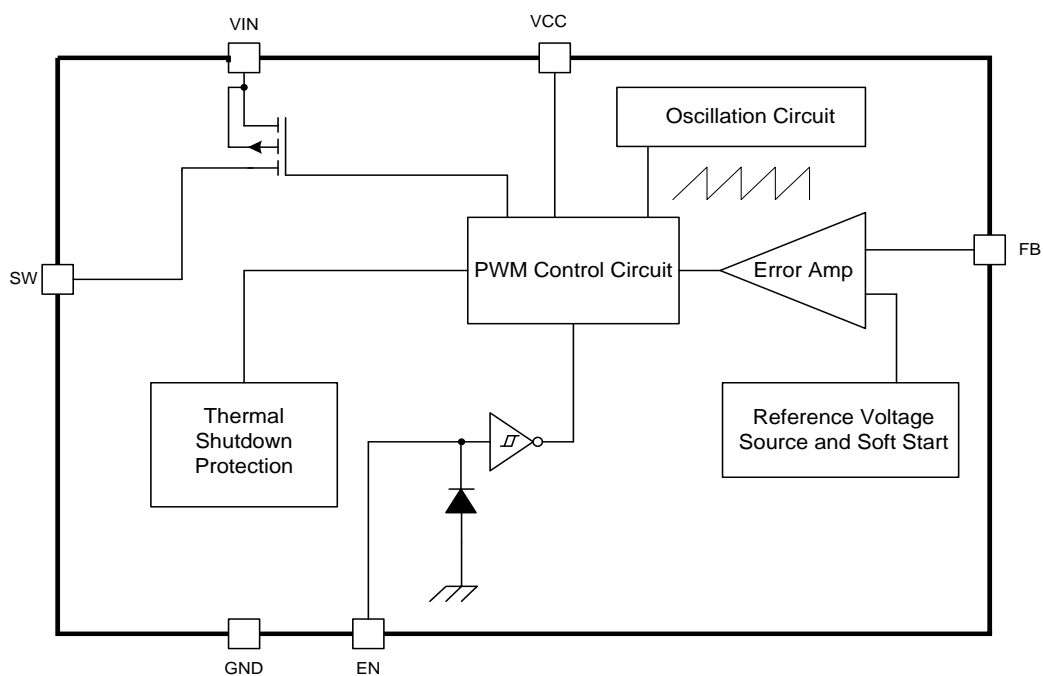
Pin Number	Pin Name	Function
1	FB	Feedback pin connect to a resistor to set LED current by following formula: $I_{LED}=0.23V/R_{FB}$
2	EN	Enable/Disable pin H:Normal operation mode(Step-down operation) L:Shutdown mode(All circuits deactivated)
3	VCC	Add an external capacitor to $V_{IN}$ .It's voltage is set to $V_{IN}-7V$
4	VIN	IC power supply pin
5、6	VOUT	Switch Pin.Connect external inductor/diode here.Minimize trace area at this pin to reduce EMI
7、8	GND	GND pin

## Marking Rule



- ① Represent the Lot number
- ② Represent the code number

## Function Block Diagram

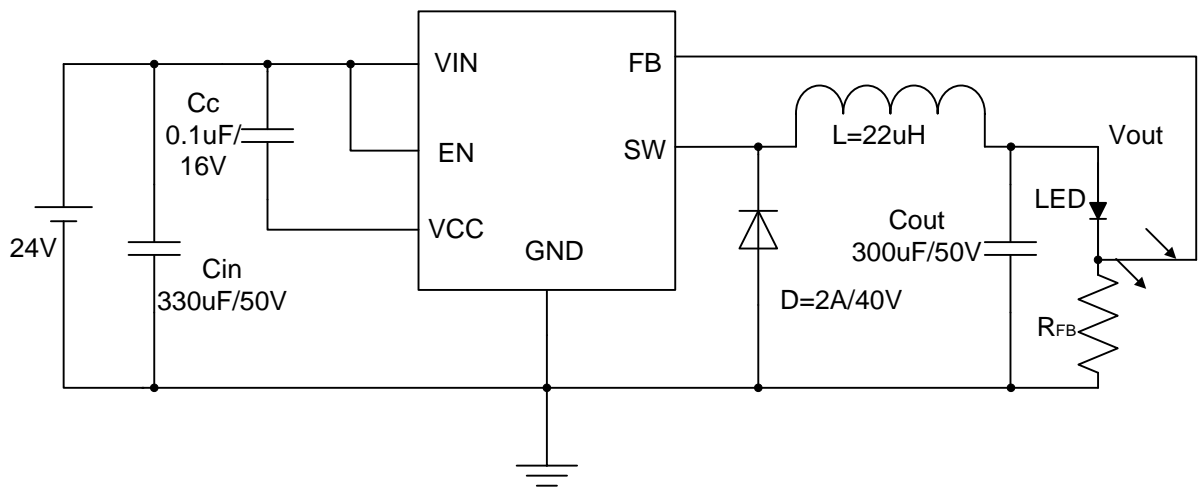


## Absolute Maximum Ratings

Parameter	Symbol	Maximum Rating	Unit
$V_{IN}$ Pin voltage	$V_{IN}$	GND-0.3~GND+42	V
Feedback Pin Voltage	$V_{FB}$	GND-0.3~ $V_{IN}$	
ON/OFF Pin Voltage	$V_{ON/OFF}$	GND-0.3~ $V_{IN}+0.3$	
Switch Pin Voltage	$V_{OUTPUT}$	GND-0.3~ $V_{IN}+0.3$	
Power Dissipation	$P_D$	Internally Limited	mW
Operating Temperature Range	$T_{opr}$	-40~+125	°C
Storage Temperature Range	$T_{stg}$	-40~+150	

**Caution :** The absolute maximum ratings are rated values exceeding which the product could suffer physical damage. These values must therefore not be exceeded under any conditions.

## Typical Application Circuit



**Electrical Characteristics**

 (V<sub>CC</sub>=24V, T<sub>A</sub>=25°C, unless otherwise noted)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Input Voltage	V <sub>IN</sub>		4.2		40	V
En Pin Input Voltage	V <sub>ENH</sub>	Evaluate oscillation at SW pin	2.0			V
	V <sub>ENL</sub>	Evaluate oscillation stop at SW pin			0.8	
Feedback Voltage	V <sub>FB</sub>	I <sub>OUT</sub> =0.1A	0.2185	0.23	0.2415	V
Feedback Bias Current	I <sub>FB</sub>	I <sub>OUT</sub> =0.1A		0.1	0.5	μA
Current Limit	I <sub>CL</sub>		2.5			A
Quiescent Current (Switch Off)	I <sub>GND</sub>	EN ≥ VEN_H, VFB=1V		1	2	mA
Current Consumption During Power Off	I <sub>GND_OFF</sub>	EN ≤ VEN_L		1	10	μA
Voltage Clamp	V <sub>C</sub>	No load	V <sub>IN</sub> -6	V <sub>IN</sub> -7	V <sub>IN</sub> -8	V
Oscillation Frequency	F <sub>OSC</sub>	Measure waveform at SW pin	120	150	180	KHz
Frequency Of Current Limit Or Short Circuit Protect	F <sub>OSC1</sub>	Measure waveform at SW pin	20	30	40	KHz
Line Regulation	ΔV <sub>OUT</sub> /V <sub>OUT</sub>	V <sub>IN</sub> =12~40V, I <sub>OUT</sub> =0.2A		1	2	%
Load Regulation	ΔV <sub>OUT</sub> /V <sub>OUT</sub>	I <sub>OUT</sub> =0.1 to 2A		0.2	0.5	%
Internal Mosfet Rdson	R <sub>DS(ON)</sub>	V <sub>FB</sub> =0V, I <sub>OUT</sub> =1A		80	100	mΩ
Efficiency	η	V <sub>IN</sub> =24V, 6pcs LED, I <sub>OUT</sub> =2A	95			%

## Function Description

### ● PWM Control

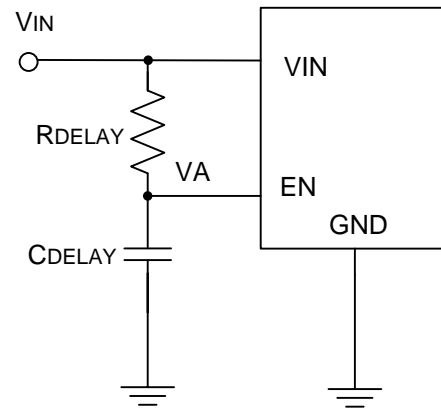
The LN2103 consists of DC/DC converters that employ a pulse-width modulation (PWM) system. In converters of the LN2103 the pulse width varies in a range from 0 to 100%, according to the load current. The ripple voltage produced by the switching can easily be removed through a filter because the switching frequency remains constant. Therefore, these converters provide a low-ripple power over broad ranges of input voltage and load current.

### ● Current Limit and short circuit protection

The device includes current limit and short protection. When inductor current large than current limit threshold or the VO is shorted to GND, then the protection circuit will be triggered and force the oscillation frequency down to approximately 30KHz. The oscillation frequency will return to the normal value once the feedback voltage rises above 0.23V.

### ● Delay Start-up

The following circuit uses the EN pin to provide a time delay between the input voltages is applied and the output voltage comes up. As the instant of the input voltage rises, the charging of the capacitor C<sub>DELAY</sub> pulls the EN pin low, keeping the device of. Once the capacitor voltage rises above the EN pin threshold voltage, the device will start to operate.



For example, setting  $V_{IN}=24V$ ,  $R_{DELAY}=100K\Omega$ ,  $C_{DELAY}=0.1\mu F$ . The start-up delay time can be calculated as below:

$$V_A = V_{IN} \times (1 - e^{-t/t}) \geq V_{EN}$$

$$t = R_{DELAY} \times C_{DELAY}$$

$$T \geq 1.147ms$$

Where  $V_A$  is the capacitor voltage,  $V_{EN}$  is the EN threshold voltage (1.3V\_TYP), T is the delay time, and t is the RC time constant.

This feature is useful in the situations where the input power source is limited in the amount of current it can deliver. It allows the input voltage to rise to higher voltage before the device starts operating.

## Application Information

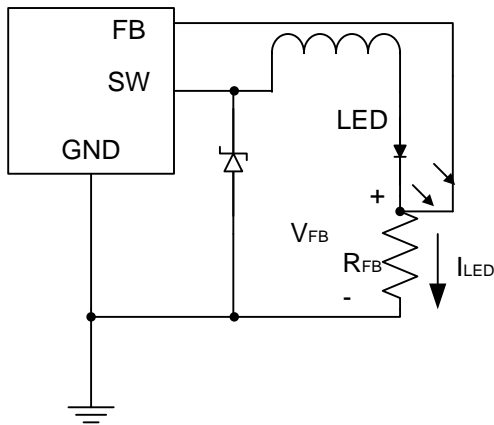
### LED Current Sensing

This device is a constant current buck regulator that develops 0.23V reference voltage between the feedback pin and GND pin. Therefore, the use 1% chip resistors to attain the better current accuracy.

The LED current is given by the following equation:

$$I_{LED} = \frac{V_{FB}}{R_{FB}}; V_{FB} = 0.23V$$

The resistor's power dissipation can be calculation by the following equation:  $P_{RFB} = I_{LED} \times V_{FB}$

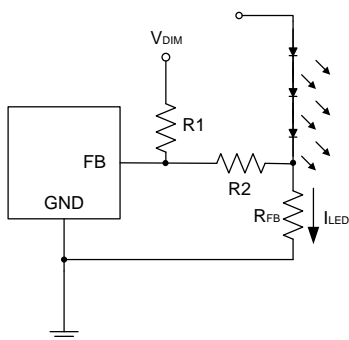


### Dimming Control (Analog Dimming control )

The analog dimming control using a DC voltage ( $V_{DIM}$ ) is shown in the following circuit. As the  $V_{DIM}$  increases, the voltage drop on  $R_2$  increases. Thus the LED current decreases. The  $R_1$  and  $R_2$  must take the DC source current much larger than FB bias current and much smaller than the LED current.

The LED current can be calculated by the following equation:

$$I_{LED} = \frac{V_{FB} \times (R_1 + R_2) - V_{DIM} \times R_2}{R_1 \times R_{FB}}$$



If the  $V_{DIM}$  is taken below the  $V_{FB}$ , the inverse will happen and brightness will increase.

The analog dimming circuit can be tailored for different resistor value using the following equation:

$$R_1 = \frac{(V_{DIM\_MAX} - V_{FB}) \times R_2}{V_{FB} \times \left(1 - \frac{I_{LED\_DIMMED\_MIN}}{I_{LED\_UNDIMMED}}\right)}$$

Example:

$$V_{DIM\_MAX} = 5V$$

$$I_{LED\_DIMMED\_MIN} = 17.5mA; V_{DIM} = 5V$$

$$I_{LED\_UNDIMMED\_MIN} = 350mA; V_{DIM} = V_{FB} = 0.23V$$

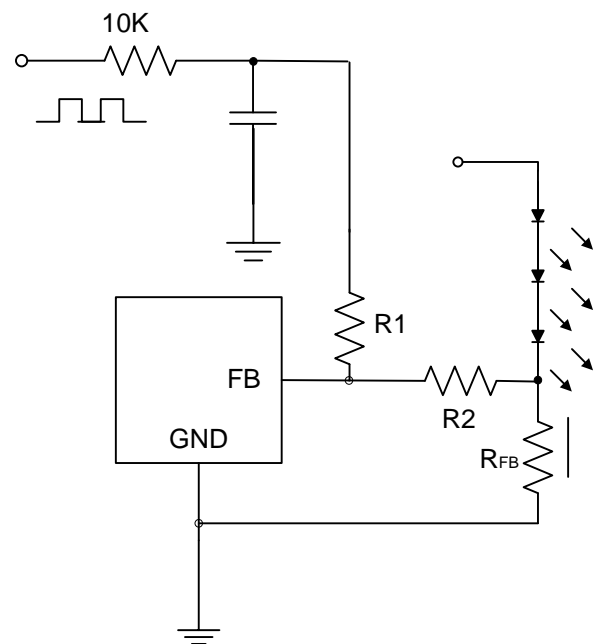
$$R_2 = 5K\Omega \rightarrow R_1 = 120k\Omega$$

The analog dimming circuit can be tailored for different dimming voltage range using the following equation:

$$V_{DIM} = V_{FB} \times \frac{R_1}{R_2} \times \left(1 + \frac{R_1}{R_2} - \frac{I_{LED\_DIMMED\_MIN}}{I_{LED\_UNDIMMED}}\right)$$

### Filtered PWM Dimming from FB

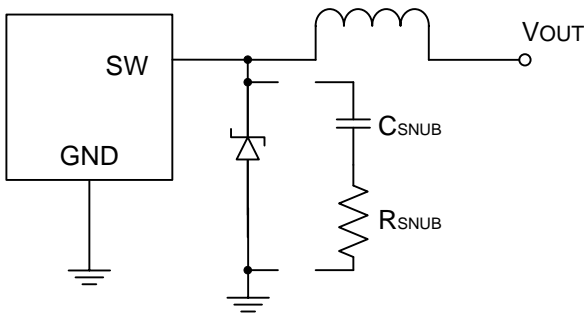
Filtered PWM circuit can be used to place the DC voltage in the dimming control. The circuit is shown in the following figure that is suitable for the high frequency PWM control signal.



### ● Snubber Circuit

The simple RC snubber is used for the voltage transient and ringing suppression. The high frequency ringing and voltage overshooting at the SW pin is caused by the fast switching transition and resonating circuit parasitical elements in the power circuit. It maybe generates EMI and interferes with circuit performance.

Reserve a snubber circuit in the PC board is preferred to damp the ringing due to the parasitical capacitor and inductor of layout. The following circuit is a simple RC snubber.



Choose the value of RC network by the following procedure:

1. Measure the voltage ringing by the frequency ( $f_R$ ) of the SW pin.
2. Find a small capacitor and place it across the SW pin and the GND pin to damp the ringing frequency by half.
3. The parasitical capacitor ( $C_{PAR}$ ) at the SW pin is 1/3 the value of the added capacitor above. The parasitical inductance ( $L_{PAR}$ ) at the SW pin is:

$$L_{PAR} = \frac{1}{(2\pi f_R)^2 \times C_{PAR}}$$

4. Select the value of  $C_{SNUB}$  that should be more than 2~4 times the value of  $C_{PAR}$  but must be small enough so that the power dissipation of  $R_{SNUB}$  is kept to a minimum. The power rating of  $R_{SNUB}$  can be calculated by follow equation:

$$P_{\_SNUB} = C_{SNUB} \times V_{IN}^2 \times f_s$$

5. Calculate the value of  $R_{SNUB}$  by the following equation and adjust the value to meet the expectative peak voltage.

$$R_{SNUB} = 2\pi \times f_R \times L_{PAR}$$

### ● Thermal Considerations

Thermal protection limits total power dissipation in the

device. When the junction temperature reaches approximately 150 °C the thermal sensor signals the shutdown logic turning off this device. The thermal sensor will turn this device on again after the IC's junction temperature cools by 55°C. For continuous operation, do not exceed the maximum operation junction temperature 125°C.

The power dissipation across this device can be calculated by following equation:

$$P_D = I_{LED}^2 \times R_{DS(ON)} \times D + \frac{1}{2} \times V_{IN} \times I_{LED} \times (tr + tf) \times fs + Q_{GATE} \times V_{GS} \times fs + I_Q \times V_{IN}$$

Where:

D : Duty Cycle

fs: Switching Frequency

$V_{GS}$  : Power MOSFET Gate Voltage

$I_Q$  : Quiescent Current

The  $tr$ ,  $tf$  and  $Q_{GATE}$  are the rising, falling time, and gate charge of the power MOSFET. The typical value of ( $tr+tf$ ) is approximately 30ns, and the  $Q_{GATE}$  is approximately 10nC. The  $V_{GS}$  is approximately equal  $V_{IN}$ .

The Maximum power dissipation of this device depends on the thermal resistance of the IC package and PCB layout, the temperature difference between the junction and ambient air, and the rate of airflow. The maximum power dissipation can be calculated by the following equation:

$$P_{D(MAX)} = \frac{T_J - T_A}{\theta_{JA}}$$

Where  $T_J - T_A$  is the temperature difference between the junction and surrounding environment. The value of junction to case thermal resistance  $\theta_{JC}$  is also popular to users. This thermal parameter is convenient for users to estimate the internal junction operated temperature of packages while IC operating. The operated junction temperature can be calculated by the following equation :

$$T_J = T_C + P_D \times \theta_{JC}$$

$T_C$  is the package case temperature measured by thermal sensor. Therefore it's easy to estimate the junction temperature by any condition.

There are many factors affect the thermal resistance. Some of the factors include trace width, copper thickness, total PCB copper area, and etc.

For the best thermal performance, wide copper tracks and generous amounts of PCB copper should be used in board layout. If further improve thermal characteristics are needed, double sided and multi-layer PCB with large copper areas and airflow will be recommended.

● **Layout consideration**

PC board layout is very important, especially for switching regulators of high frequencies and large peak currents. A good layout minimizes EMI on the feedback path and provides best efficiency. The following layout guides should be used to ensure proper operation of this device.

1. The power charge path that consists of the  $V_{IN}$  trace, SW trace, external inductor, and the GND trace should be kept wide and as short as possible.
2. The power discharge path that consists of SW trace, external inductor, external diode and the GND trace should be kept wide and as short as possible.
3. The feedback path of the voltage divider should be close to FB pin and keep noisy traces away; also keep them separate using grounded copper.
4. The input capacitors should be close to the regulator and rectifier diode. The output capacitors should be close to the load.
5. Keep the (-) plates of input and output capacitor as close as possible.

● **Inductor Selection**

The conduction mode of power stage depends on input voltage, output voltage, LED current, and the value of the inductor. Select an inductor to maintain this device operating in continuous conduction mode (CCM). The minimum value of inductor can be determined by the following procedure.

1. Calculate the minimum duty ratio

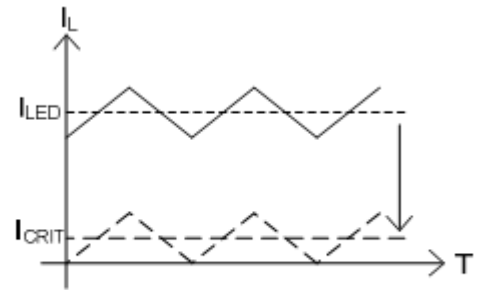
$$D_{(MIN)} = \frac{V_{OUT} + I_{LED} \times R_L + V_F}{V_{IN(MAX)} - I_{LED} \times R_{DS(ON)} + V_F} = \frac{T_{ON}}{T_S}$$

Where  $R_L$  is the DC resistance of the external inductor,  $V_F$  is the forward voltage of external diode, and  $T_S$  is the switching period. This equation can be simplified to

$$D_{(MIN)} = \frac{V_{OUT}}{V_{IN(MAX)}} = \frac{T_{ON}}{T_S}; 0 \leq D \leq 1$$

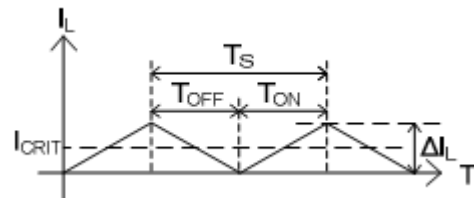
2. Defined a value of minimum LED current that is approximately 10%~30%of full LED current to maintain

continuous conduction mode, usually referred to as the critical current( $I_{CRIT}$ ).



$$I_{CRIT} = \delta \times I_{LED}; \delta = 0.1 \sim 0.3$$

3. Calculate the inductor ripple current( $\Delta I_L$ ). In steady state conditions, the inductor ripple current increase, ( $\Delta I_L +$ ), during the ON time and the current decrease, ( $\Delta I_L -$ ), during the OFF time must be equal.



4. Calculate the minimum value of the inductor use maximum input voltage. That is the worst case condition because it gives the maximum  $\Delta I_L$ .

$$L \geq \frac{[V_{IN(MAX)} - I_{LED} \times (R_{DS(ON)} + R_L) - V_{OUT}] \times D_{(MIN)}}{\Delta I_L \times f_s}$$

This equation can be simplified to

$$\geq \frac{(V_{IN(MAX)} - V_{OUT}) \times D_{(MIN)}}{\Delta I_L \times f_s}$$

The higher value inductor results in lower output ripple current and ripple voltage. It also reduces the conduction loss. But higher value inductor requires larger physical size and price.

5. Calculate the inductor peak current and choose a suitable inductor to prevent saturation.

$$I_{L(PEAK)} = I_{LED} + \frac{\Delta I_L}{2}$$

Coil inductor and surface mount inductors are all available. The surface mount inductors can reduce the board size but they are more expensive and its larger DC resistance results in more conduction loss. The power dissipation is due to the DC resistance can be calculated as below :

$$P_{D\_INDUCTOR} = I_{LED}^2 \times R_L$$



### ● Output Capacitor Selection

The functions of the output capacitor are to store energy and maintain the output voltage. The low ESR (Equivalent Series resistance) capacitors are preferred to reduce the output ripple voltage ( $\Delta V_{OUT}$ ) and conduction loss. The output ripple voltage can be calculated as below:

$$\Delta V_{OUT} = \Delta I_L \times \left( ESR_{-COUT} + \frac{1}{8 \times f_s \times C_{OUT}} \right)$$

The ESR of the aluminum electrolytic or tantalum output capacitor is an important parameter to determine the output ripple voltage. But the manufactures usually do not specify ESR in the specifications, Assuming the capacitor is enough results in the output ripple voltage is due to the capacitor can be ignored, the ESR can be calculated as below :

$$ESR_{-COUT} \leq \frac{\Delta V_{OUT}}{\Delta I_L}$$

Choose the output capacitor by the average value of the RC product as below :

$$C_{OUT} \approx \frac{50 \sim 80 \times 10^{-6}}{ESR_{-COUT}}$$

The ESR and ripple current results power dissipation in the capacitor. It will increase the internal temperature. Usually, the capacitors manufactures specify ripple current ratings and should not exceeds to prevent excessive temperature shorten the lift time. Choose a smaller inductor causes higher ripple current which maybe result in the capacitor overstress. The RMS ripple current flowing through the output capacitor and power dissipation can be calculated as below :

$$I_{RMS\_COUT} = \frac{\Delta I_L}{\sqrt{12}} = \Delta I_L \times 0.289$$

$$P_{D\_COUT} = (I_{RMS\_COUT})^2 \times ESR_{-COUT}$$

Besides, the capacitor's ESL (Equivalent Series inductance) maybe causes ringing in the low MHz region. Choose low ESL capacitors, and parallel connecting several smaller capacitors to replace with a larger one will reduce the ringing phenomenon.

### ● Input Capacitor Selection

The input capacitor is required to supply current to regulator and maintain the DC input voltage. Low ESR capacitors are preferred those provide the better performance and the less ripple voltage.

1. The input capacitors need an adequate RMS current rating. It can be calculated by following equation and should not be exceed.

$$I_{RMS\_CIN} = I_{LED(MAX)} \times \sqrt{D \times (1-D)}$$

This equation has a maximum at  $V_{IN}=2V_{OUT}$ . That is the worse case and the above equation can be simplified to :

$$I_{RMS\_CIN} = \frac{I_{LED(MAX)}}{2}$$

Therefore, choose a suitable capacitor at input whose ripple current rating must greater than half of the maximum LED current.

2. The input ripple voltage( $\Delta V_{IN}$ ) mainly depends on the input capacitor's ESR and its capacitance. Assuming the input current of the regulator is constant, the required input capacitance for a given input ripple voltage can be calculated as below :

$$C_{IN} = \frac{I_{LED(MAX)} \times D \times (1-D)}{f_s \times (V_{IN} - I_{LED(MAX)} \times ESR_{-CIN})}$$

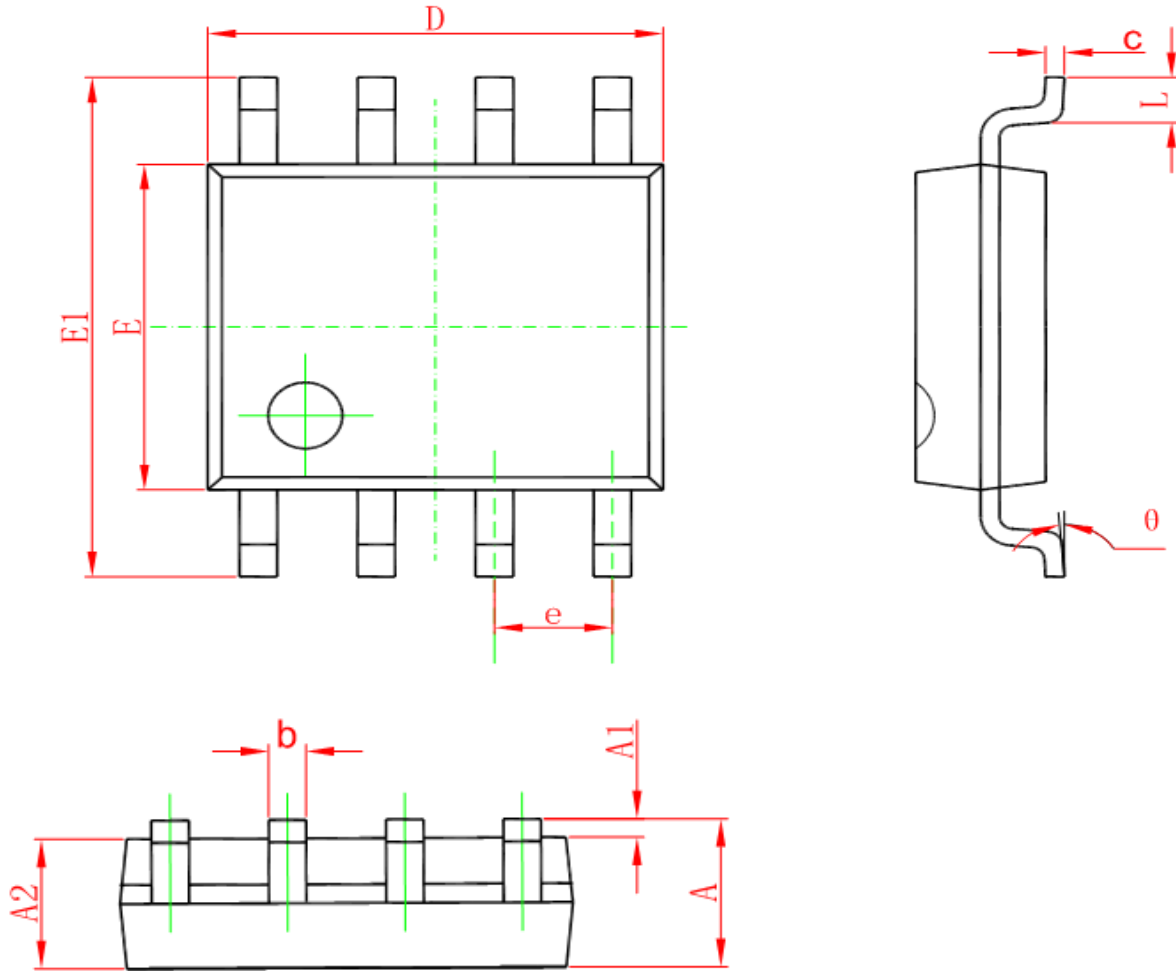
If using aluminum electrolytic or tantalum input capacitors, parallel connecting a 0.1uF ceramic capacitor as close to the VIN pin of the regulator as possible. If using ceramic capacitor, make sure the capacitance is enough to prevent the excessive input ripple current.

3. The power dissipation of the input capacitor causes a small conduction loss can be calculated as below :

$$P_{D\_CIN} = (I_{RMS\_CIN})^2 \times ESR_{-CIN}$$

■ Package Information

- SOP-8



Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min	Max	Min	Max
A	1.350	1.750	0.053	0.069
A1	0.100	0.250	0.004	0.010
A2	1.350	1.550	0.053	0.061
b	0.330	0.510	0.013	0.020
c	0.170	0.250	0.006	0.010
D	4.700	5.100	0.185	0.200
E	3.800	4.000	0.150	0.157
E1	5.800	6.200	0.228	0.244
e	1.270 (BSC)		0.050 (BSC)	
L	0.400	1.270	0.016	0.050
θ	0°	8°	0°	8°