P5522 Programmable LED Driver



# LP5522 Programmable LED Driver General Description

The LP5522 is a simple single wire programmable LED controller in six bump micro SMD package. It provides constant current flow through high side driver. Output current can be set from 1 mA to 20 mA by using an external resistor on the ISET pin. If no external resistor is used, output current is set to 5 mA default current. The LP5522 is controlled using only one signal. The signal controls either directly the LED driver or it launches previously programmed blinking sequence.

The LP5522 works autonomously without a clock signal from the master device. Very low LED driver headroom voltage makes possible to use supply voltages close to LED forward voltage. Current consumption of the LP5522 is minimized when LED is turned off and once controller is disabled all supporting functions are also shut down. Very small micro SMD package together with minimum number of external components is a best fit for handheld devices.

### Features

- Programmable blinking sequence
  - 1 to 3 programmable pulses
  - 1 ms to 255 ms LED on time
  - 10 ms to 2500 ms LED off time
  - Single or continuous run of programmed blinking sequence
- Constant current high side output driver
- Adjustable current with external resistor
- 0.2 uA typical shutdown current
- Autonomous operation without external clock
- Micro SMD-6 package with 0.4 mm pitch: 1.215 mm x 0.815 mm x 0.6 mm (LxWxH)

### Applications

- Indicator lights
- Phone cosmetics
- Toys

## **Typical Application**



# LP5522

### **Connection Diagrams and Package Mark Information**

### **Connection Diagrams**

Micro SMD-6 package, 0.815 x 1.215 x 0.60 mm body size, 0.4 mm pitch NS Package Number TMD06AAA





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#### PACKAGE MARK



#### **ORDERING INFORMATION**

Order Number	Package Marking	Supplied As	Spec/Flow
LP5522TM	6	TNR 250	NOPB
LP5522TMX	6	TNR 3000	NOPB

#### **PIN DESCRIPTIONS**

Pin	Name	Туре	Description	
A1	VDD	Р	Power supply pin	
B1	ISET	AI	Current set input	
C1	CTRL	DI	Digital control input	
A2	LED	AO	Current source output	
B2	GND	G	Ground	
C2	GNDT	G	Ground	

#### A: Analog Pin D: Digital Pin G: Ground Pin P: Power Pin

I: Input Pin O: Output Pin

### Absolute Maximum Ratings (Notes 1, 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

V (VDD, LED, ISET)	-0.3V to +6.0V
Voltage on logic pin (CTRL)	-0.3V to VDD +0.3V
	with 6.0V max
Continuous Power Dissipation (Note 3)	Internally Limited
Junction Temperature (T <sub>J-MAX</sub> )	125°C
Storage Temperature Range	-65°C to +150°C
Maximum Lead Temperature (Reflow soldering, 3 times) (Note 4)	260°C
ESD Rating (Note 5) Human Body Model Sheet4U.com	2 kV

### Operating Ratings (Notes 1, 2)

Voltage on power pin (VDD)2.7V to 5.5VRecommended Load Current1 mA to 20 mAJunction Temperature (T<sub>J</sub>) Range $-30^{\circ}$ C to  $+125^{\circ}$ CAmbient Temperature (T<sub>A</sub>) Range $-30^{\circ}$ C to  $+85^{\circ}$ C(Note 6) $-30^{\circ}$ C to  $+85^{\circ}$ C

### **Thermal Properties**

Junction-to-Ambient Thermal Resistance  $(\theta_{JA})$ , TMD06 Package (Note 7) 87°C/W

### Electrical Characteristics (Notes 2, 8)

Limits in standard typeface are for  $T_J = 25^{\circ}$ C. Limits in **boldface** type apply over the operating ambient temperature range (-30°C <  $T_A < +85^{\circ}$ C). Unless otherwise noted, specifications apply to the LP5522 Block Diagram with:  $V_{IN} = 3.6$ V,  $R_{ISET} = 24$  k $\Omega$ ,  $C_{IN} = 100$  nF.

Symbol	Parameter	Condition	Min	Тур	Мах	Units
I <sub>VDD</sub>	Standby supply current	CTRL = L		0.2	1	μA
	Active Mode Supply Current	CTRL = H, LED = off		40	55	μA
ILEAKAGE	LED Pin Leakage Current				1	μA
I <sub>OUT</sub>	LED Output Current	Without external resistor		5		mA
			-8		+8	%
	LED Output Current	With external $24k\Omega$ 0.04% resistor		20		mA
			-8		+8	%
IMIRROR	External R <sub>ISET</sub>			1:400		
	Mirroring Ratio					
V <sub>ISET</sub>	ISET Reference Voltage			1.23		V
V <sub>HR</sub>	Minimum Headroom Voltage	I <sub>OUT</sub> set to 10 mA		35	50	mV
	(V <sub>IN</sub> - V <sub>LED</sub> )(Note 9)	I <sub>OUT</sub> set to 20 mA		70	100	mV
T_CYCLE_H	Minimum LED On Time		0.9	1.0	1.1	ms
T_CYCLE_L	Minimum LED Off Time		9	10	11	ms
ONRESOLUTION	LED On Time Resolution			1		ms
OFFRESOLUTION	LED Off Time Resolution			10		ms
T_Timeout_H	LED Timeout On Time		287	319	351	ms
T_Timeout_L	LED Timeout Off Time		2.87	3.19	3.51	s
V <sub>IL</sub>	Logic Input Low Level				0.5	V
V <sub>IH</sub>	Logic Input High Level		1.2			V
I <sub>IN</sub>	CTRL Input Current		-1		1	μA
t <sub>on</sub>	CTRL Pulse ON Time		15			μs
t <sub>OFF</sub>	CTRL Pulse OFF Time		30			μs
t <sub>ENTER</sub>	Command Entering Period		500			μs
	Command Entering Period + Blank Period				1500	μs

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the component may occur. Operating Ratings are conditions under which operation of the device is guaranteed. Operating Ratings do not imply guaranteed performance limits. For guaranteed performance limits and associated test conditions, see the Electrical Characteristics tables.

Note 2: All voltages are with respect to the potential at the GND pins.

**Note 3:** Internal thermal shutdown circuitry protects the device from permanent damage. Thermal shutdown engages at  $T_J=160^{\circ}C$  (typ.) and disengages at  $T_J=140^{\circ}C$  (typ.).

Note 4: For detailed soldering specifications and information, please refer to National Semiconductor Application Note AN1112 : Micro SMD Wafer Level Chip Scale Package.

Note 5: The Human body model is a 100 pF capacitor discharged through a 1.5 k $\Omega$  resistor into each pin. MIL-STD-883 3015.7

**Note 6:** In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature ( $T_{A-MAX}$ ) is dependent on the maximum operating junction temperature ( $T_{J-MAX-OP} = 125^{\circ}C$ ), the maximum power dissipation of the device in the application ( $P_{D-MAX}$ ), and the junction-to ambient thermal resistance of the part/package in the application ( $\theta_{JA}$ ), as given by the following equation:  $T_{A-MAX} = T_{J-MAX-OP} - (\theta_{JA} \times P_{D-MAX})$ .

Note 7: Junction-to-ambient thermal resistance is highly application and board-layout dependent. In applications where high maximum power dissipation exists, special care must be paid to thermal dissipation issues in board design.

**Note 8:** Min and Max limits are guaranteed by design, test, or statistical analysis. Typical numbers are not guaranteed, but do represent the most likely norm. **Note 9:** The current source is connected internally between  $V_{IN}$  an  $V_{LED}$ . The voltage across the current source,  $(V_{IN} - V_{LED})$ , is referred to a headroom voltage ( $V_{HB}$ ). Minimum headroom voltage is defined as the  $V_{HB}$  voltage when the LED current has dropped 10% from the value measured at  $V_{LED} = V_{IN} - 1V$ .

### LP5522 Block Diagram

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	on
ataSheet4U.com	POR RESET POR = L POR = L Control command ends ACTIVE
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RESET	In the reset mode all functions are off and all registers are reset to the default values. Reset is entered always if internal Power On Reset (POR) is active. Power On Reset will activate during the device startup or when the supply voltage V <sub>IN</sub> falls below 1.5V (typ.).
STANDBY:	After Power On Reset device is in Standby mode. This is the low power consumption mode, whe all circuit functions are disabled.
ACTIVE:	Once rising edge of CTRL signal is detected device goes into Active mode. In Active mode four su modes are present:
RUN:	Run mode is divided into two sub modes depending on whether a blinking sequence is programme into memory or not.
Non-programmed mode:	No blinking sequence programmed to memory. LED output follows CTRL input
Programmed mode:	Blinking sequence programmed to memory. LED output follows the programmed blinking sequence
RUN ONCE:	In Run once mode, programmed blinking sequence is performed once and after that device return into Standby mode. Run once mode is available only if a blinking sequence is programmed in memory.
	In Training mode new blinking sequence can be programmed. LED output follows CTRL sign during the programming
TRAINING:	

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### **LED Driver Operational Description**

The LP5522 LED driver is constant current source. Current can be set with external resistor ( $R_{ISET}$ ) so that the current ratio between resistor and LED is 1:400.  $R_{ISET}$  current correlates to ISET reference voltage ( $V_{ISET}$ ). Consequently, current through LED can be adjusted using equation  $I_{OUT} = 480/R_{ISET}$ .

Use of external resistor is optional. If external resistor is not connected, default output current is 5 mA. When external resistor is not used ISET pin should be connected to VDD.

### **LED Driver Typical Performance Characteristics**

 $T_J = 25^{\circ}$ C. Unless otherwise noted, typical performance characteristics apply to the LP5522 Block Diagram with:  $V_{IN} = 3.6V$ ,  $R_{ISET} = 24 \text{ k}\Omega$ ,  $C_{IN} = 100 \text{ nF}$ .





**Output Current vs Headroom Voltage** 



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### **Control Interface Operational Description**

LP5522 has one digital control input, CTRL. Threshold levels of CTRL input are fixed to enable control from low voltage controller. CTRL signal is used to control the mode of the circuit. A rising edge of the CTRL signal activates the circuit and starts a command entering period. During the command entering period all rising edges are counted. After command entering period there is a blank period when no rising edges are allowed. If CTRL is left high after command entering period, the consequent command is performed right after the blank period.

Note that timing diagrams are not on scale!



If CTRL signal is low after command entering period, command execution starts when CTRL is pulled high. This does not apply to Run command. With Run command CTRL must be high. Note that no rising edges are allowed during blank period.



### **LED Controller Commands and Operation**

There are four commands available for LP5522.

Command	Number of rising edges during command entering period		
Run	One rising edge		
Training start	Two rising edges		
Training end	Three rising edges		
Run once	Four rising edges		

### **RUN COMMAND**

One rising edge of CTRL signal within command entering period is interpreted as Run command. In programmed mode blinking sequence is started right after Blank period and it is repeated as long as CTRL signal is kept high. When CTRL signal is set low device goes into Standby mode.

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In non-programmed mode LED is on as long as CTRL is kept high. When CTRL signal is set low device goes into Standby mode.



#### RUN ONCE COMMAND

Programmed blinking sequence is performed once after Run Once command. Four rising edges of CTRL signal within command entering period is interpreted as Run Once command. If CTRL is kept high after command entering period the programmed blinking sequence starts right after the blank period has elapsed. CTRL signal must stay high as long as programmed blinking sequence is executed. If CTRL is set low during execution of blinking sequence, device goes to standby and execution of blinking sequence is stopped.



If CTRL signal is low after command entering period, Run Once command is executed once the CTRL is set high.



#### TRAINING START COMMAND

Blinking sequence is programmed into memory in training mode. Blinking sequence is stored into volatile memory, thus removing input voltage V<sub>IN</sub> resets the memory. Memory can also be reset by giving Training Start and Training End commands without any valid LED ON/OFF times.

LP5522 enters to Training mode after Training Start command. Two rising edges within command entering period is interpreted as the Training Start command. The first LED ON time capturing is started once the rising edge of CTRL signal is detected after the blank period. LED output follows CTRL signal during the programming.

The first LED ON time is recorded once CTRL signal is set low. Same time the first LED OFF time capturing is started. Programmed blinking sequence can have one to three LED ON/OFF times. In order to be programmed correctly, at least one valid LED ON and LED OFF time must be recorded.



#### TRAINING END COMMAND

Blinking sequence programming ends once Training End command is introduced. Three rising edges within time period of  $t_{EN-TER}$  is interpreted as Training End command. Note that blank period is also reguired after Training End command. During blanc period no rising edges are allowed.

When Training End command is introduced during LED OFF time capturing, LED OFF time is recorded and chip goes to standby mode.



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If Training End command is introduced during LED ON time capturing, the associated LED ON period is not recorded and hence neither OFF time. Notice that valid OFF time before Training End is longer than half of Minimum LED OFF period (T\_CYCLE\_L).



#### LED TIMEOUT ON/OFF TIMES

When LP5522 is in training mode and CTRL signal is high longer than LED Timeout ON time, the ON time counter saturates. In this case saturated ON time is recorded and LED OFF time capturing is started. At the same time LED is switched off even if the CTRL signal is still high.

If ON time counter has saturated, LED OFF time recording is terminated either by giving a Train End command or setting the CTRL signal to low and back to high. Setting the CTRL signal back to high records the LED OFF time and starts next ON time capturing.

If anyhow CTRL is still high after the LED Timeout OFF time has been elapsed the OFF time counter saturates and saturated OFF time is recorded. After that chip waits the CTRL signal to go low which cause the chip to go Standby.



LED OFF time counter can saturate also if Training end command is not given or no new ON time has been started. In this case saturated OFF time is recorded and chip goes to Standby.



# **Recommended External Components**

### INPUT CAPACITOR, C<sub>IN</sub>

Although not required for normal operation, a capacitor can be added to  $V_{\rm IN}$  to reduce line noise. A surface-mount multilayer ceramic capacitor (MLCC) is recommended. MLCCs with a X7R or X5R temperature characteristic are preferred.

### CURRENT SET RESISTOR, RISET

If other than 5 mA current is required,  $R_{\text{ISET}}$  resistor can be used to adjust the current. For 20 mA current 24  $k\Omega$  resistor

#### List of Recommended External Components

is required. Accuracy of the resistor directly effects to the accuracy of the LED current. 1% or better is recommended.

### LED

Forward voltage of LED must be less than minimum input voltage minus minimum headroom voltage ( $V_{HR}$ ). For example with 2.7V input voltage and 20 mA LED current the maximum LED forward voltage is 2.7V - 100 mV = 2.6V.

Symbol	Symbol Explanation	Value	Unit	Туре
C <sub>IN</sub>	VDD Bypass Capacitor	100	nF	Ceramic, X7R or X5R
R <sub>ISET</sub>	Current Set Resistor for 20 mA LED Current	24	kΩ	1%
LED		User defined		



# Notes

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