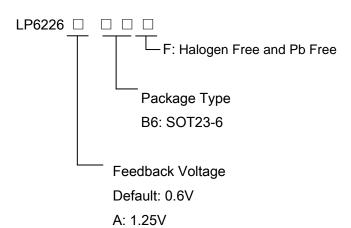
### **High Efficiency Boost DC/DC Convertor**

### **General Description**

The LP6320A is a 1MHz PWM boost switching regulator designed for constant-voltage boost applications. The LP6226 can drive a string of up to 30V. The LP6226 implements a constant frequency 1MHz PWM control scheme. The high frequency PWM operation also saves board space by reducing external component sizes. The LP6226 features automatic shifting to pulse frequency modulation mode at light loads. Highly integration and internal compensation network minimizes as 6 external component counts. Optimized operation frequency can meet the requirement of small LC filters value and low operation current with high efficiency.

The LP6226 includes under-voltage lockout, current limiting, and thermal overload protection to prevent damage in the event of an output overload. The LP6226 is available in a small SOT23-6 package.

#### **Order Information**



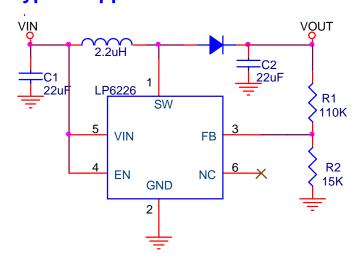
#### **Features**

- ◆ Up to 94% efficiency
- Output to Input Disconnect at Shutdown Mode
- ◆ Shut-down current:<1uA
- ◆ Output voltage Up to 28V
- Internal Compensation, Soft-start
- ◆ 1MHz fixed frequency switching
- High switch on current:1.5A
- Available in sot23-6 Package

### **Applications**

- ♦ Battery products
- ♦ Host Products
- ♦ Panel

### **Typical Application Circuit**



### **Marking Information**

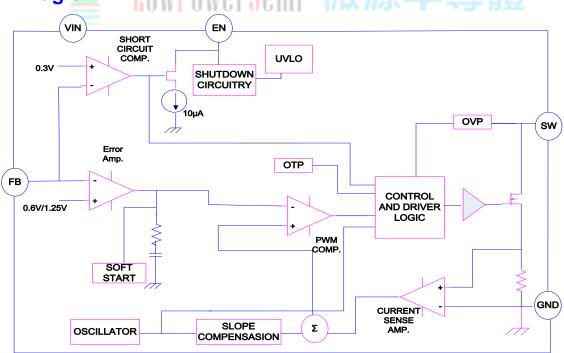
Device	Marking	Package	Shipping
LP6226B6F	LPS	SOT23-6	3K/REEL
	5AXXX		

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## **Functional Pin Description**

Packa	Package Type Pin Configurations			
SOT23-6				
Pin	Name	Description		
1	SW	switching pin.		
2	GND	Ground.		
3	FB	Regulation Feedback Input. Connect to an external resistive voltage divider from the output to FB to set the output voltage.		
4 EN		Regulator ON/OFF Control Input. A logic high input(V <sub>EN</sub> >1.4V) turns on the regulator. A		
4	LIN	logic low input(V <sub>EN</sub> <0.4V) puts the LP6226 into low current shutdown mode.		
5	VIN	Power Supply pin.		
6	NC LPS	No Connecter.		

## **Function Diagram**



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**Preliminary Datasheet** 

# **Absolute Maximum Ratings** Note 1

$\Rightarrow$	Input to GND	03V to 6V
<b></b>	SW Voltage to GND	30V
<b></b>	Other Pin Voltage to GND	6V
<b></b>	Maximum Junction Temperature	150°C
<b></b>	Operating Ambient Temperature Range (T <sub>A</sub> )	40°C to 85°C
<b></b>	Maximum Soldering Temperature (at leads, 10 sec)	260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress Note 1. ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### Thermal Information

- Maximum Power Dissipation (PD,TA=25°C) ------ 0.45W
- Thermal Resistance (J<sub>A</sub>) ------ 250°C/W

### **ESD Susceptibility**

- HBM(Human Body Mode) ------ 2KV
- MM(Machine Mode) ------ 200V

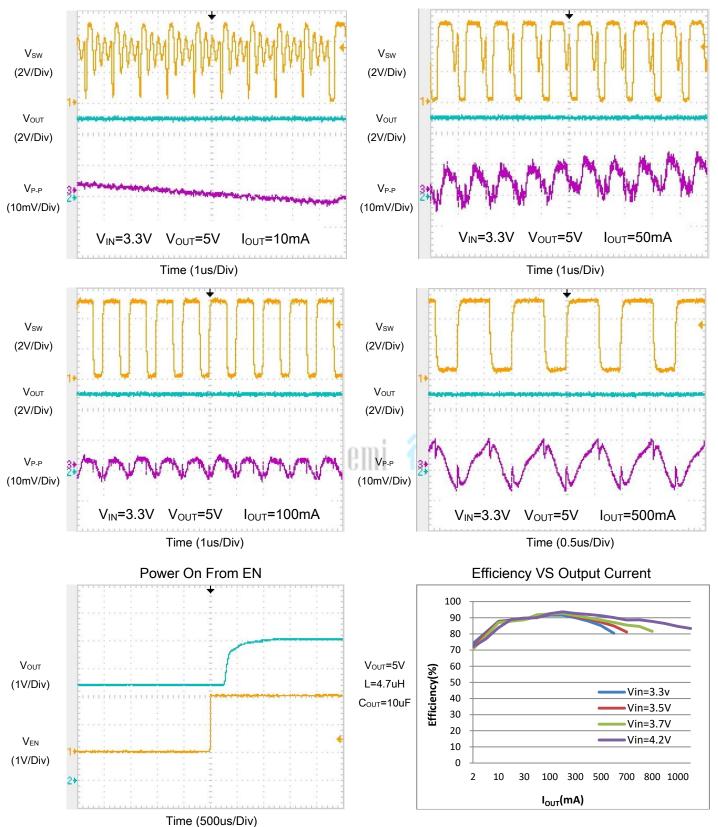
### **Electrical Characteristics**

 $(V_{IN} = 3.3V, V_{OUT} = 5V, C_{IN} = 10uF, C_{OUT} = 22uF, L_1 = 4.7uH, R_1 = 110K, R_2 = 15K)$ 

Parameter	Condition	Min	Тур	Max	Units
Supply Voltage		2.5		5.5	V
Output Voltage Range		2.5		28	V
Supply Current(Shutdown)	V <sub>EN</sub> = 0V,V <sub>SW</sub> =5V		0.05	1	uA
Supply Current	V <sub>FB</sub> =0.7V			60	uA
- "	LP6226B6F		0.6		V
Feedback Voltage	LP6226AB6F		1.25		V
Feedback Input Current	V <sub>FB</sub> =0.7V		50		nA
Switching Frequency			1		MHz
Maximum Duty Cycle		80	90	95	%
EN Input Low Voltage				0.4	V
EN Input High Voltage		1.4			V
High-side On Resistance	V <sub>OUT</sub> =3.3V		300		mΩ
MOSFET Current			1.5		Α

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### **Typical Operating Characteristics**



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### **Operation Information**

The LP6226 uses a fixed frequency, peak current mode boost regulator architecture to regulate voltage at the feedback pin. At the start of each oscillator cycle the MOSFET is turned on through the control circuitry. To prevent sub-harmonic oscillations at duty cycles greater than 50 percent, a stabilizing ramp is added to the output of the current sense amplifier and the result is fed into the negative input of the PWM comparator. When this voltage equals The output voltage of the error amplifier the power MOSFET is turned off. The voltage at the output of the error amplifier is an amplified version of the difference between the 0.6V bandgap reference voltage and the feedback voltage. In this way the peak current level keeps the output in regulation. If the feedback voltage starts to drop, the output of the error amplifier increases. These results in more current to flow through the power MOSFET, thus increasing the power delivered to the output. TheLP6226 has internal soft start to limit the amount of input current at startup and to also limit the amount of overshoot on the output.

#### Setting the Output Voltage

Set the output voltage by selecting the resistive voltage divider ratio. The voltage divider drops the output voltage to the 0.6V/1.25V feedback voltage. Use a 100K resistor for  $R_2$  of the voltage divider. Determine the high-side resistor  $R_1$  by the equation:

$$V_{OUT} = (R_1 / R_2 + 1) \times V_{FB}$$

#### **Current Limitation**

The internal power-MOS switch current is monitored cycle-by-cycle and is limited to the value not exceed 1.5A(Typ.). When the switch current reaches the limited value, the internal power-MOS is turned off immediately until the next cycle.

#### Inductor Selection

For a better efficiency in high switching frequency converter, the inductor selection has to use a proper core material such as ferrite core to reduce the core loss and choose low ESR wire to reduce copper loss. The most important point is to prevent the core saturated when handling the maximum peak current. Using a shielded inductor can minimize radiated noise in sensitive applications. The maximum peak inductor current is the maximum input current plus the half of inductor ripple current. The calculated peak current has to be smaller than the current limitation in the electrical characteristics. A typical setting of the inductor ripple current is 20% to 40% of the maximum input current. If the selection is 40%, the maximum peak inductor current is

$$\begin{split} I_{PEAK} &= I_{IN(MAX)} + \frac{1}{2}I_{RIPPLE} = 1.2 \times I_{IN(MAX)} \\ &= 1.2 \times \left[ \frac{I_{OUT(MAX)} \times V_{OUT}}{\eta \times V_{IN(MIN)}} \right] \end{split}$$

The minimum inductance value is derived from the following equation:

$$L = \frac{\eta \times V_{IN(MIN)}^2 \times \left[V_{OUT}\text{-}V_{IN(MIN)}\right]}{0.4 \times I_{OUT(MAX)} \times V_{OUT}^2 \times f_{OSC}}$$

Depending on the application, the recommended inductor value is between 2.2µH to 4.7µH.

**Diode Selection** 

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To achieve high efficiency, Schottky diode is good choice for low forward drop voltage and fast switching time. The output diode rating should be able to handle the maximum output voltage, average power dissipation and the pulsating diode peak current.

#### **Output Capacitor Selection**

For lower output voltage ripple, low-ESR ceramic capacitors are recommended. The tantalum capacitors can be used as well, but the ESR is bigger than ceramic capacitor. The output voltage ripple consists of two components: one is the pulsating output ripple current flows through the ESR, and the other is the capacitive ripple caused by charging and discharging.

$$\begin{split} V_{RIPPLE} &= V_{RIPPLE\_ESR} + V_{RIPPLE\_C} \\ &\cong I_{PEAK} \times R_{ESR} + \frac{I_{PEAK}}{C_{OUT}} \bigg( \frac{V_{OUT} - V_{IN}}{V_{OUT} \times f_{OSC}} \bigg) \end{split}$$

#### **Input Capacitor Selection**

For better input bypassing, low-ESR ceramic capacitors are recommended for performance. A 10µF input capacitor is sufficient for most applications. For a lower output power requirement application, this value can be decreased.

#### **Layout Guideline**

For high frequency switching power supplies, the PCB layout is important step in system application design. In order to let IC achieve good regulation, high efficiency and stability, it is strongly recommended the power components should be placed as close as possible. The set races should be wide and short. The feedback pin and then works of feedback and compensation should keep away from the power loops, and be shielded with a ground trace or plane to prevent noise coupling.



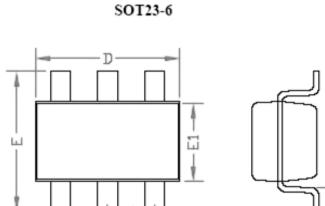
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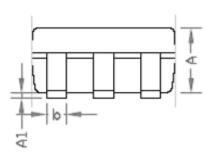
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# **Packaging Information**





SYMBOLS	MILLIMETERS		INCHES		
	MIN.	MAX.	MIN.	MAX.	
Α	-	1.45	-	0.057	
A1	0.00	0.15	0.000	0.006	
b	0.30	0.50	0.012	0.020	
D	2.90		0.114		
E1	1.60		0.063		
e	0.95		0.037		
E	2.60	3.00	0.102	0.118	
L	0.3	0.60	0.012	0.024	

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