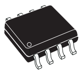
LS204

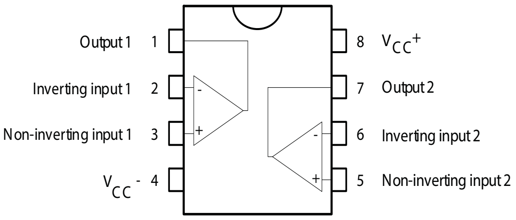
Low-noise bipolar operational amplifier

Datasheet - production data



D
SO-8
(Plastic micro package)

Pin connections
(top view)



Features

- Low power consumption
- Short-circuit protection
- Low distortion, low noise
- High gain-bandwidth product
- High channel separation

Description

The LS204 is a low-noise bipolar operational amplifier with frequency and phase compensation built into the chip. The internal phase compensation allows stable operation as a voltage follower in spite of its high gain-bandwidth product.

The circuit presents very stable electrical characteristics over the entire supply voltage range and is particularly intended for professional and telecom applications (such as active filtering).

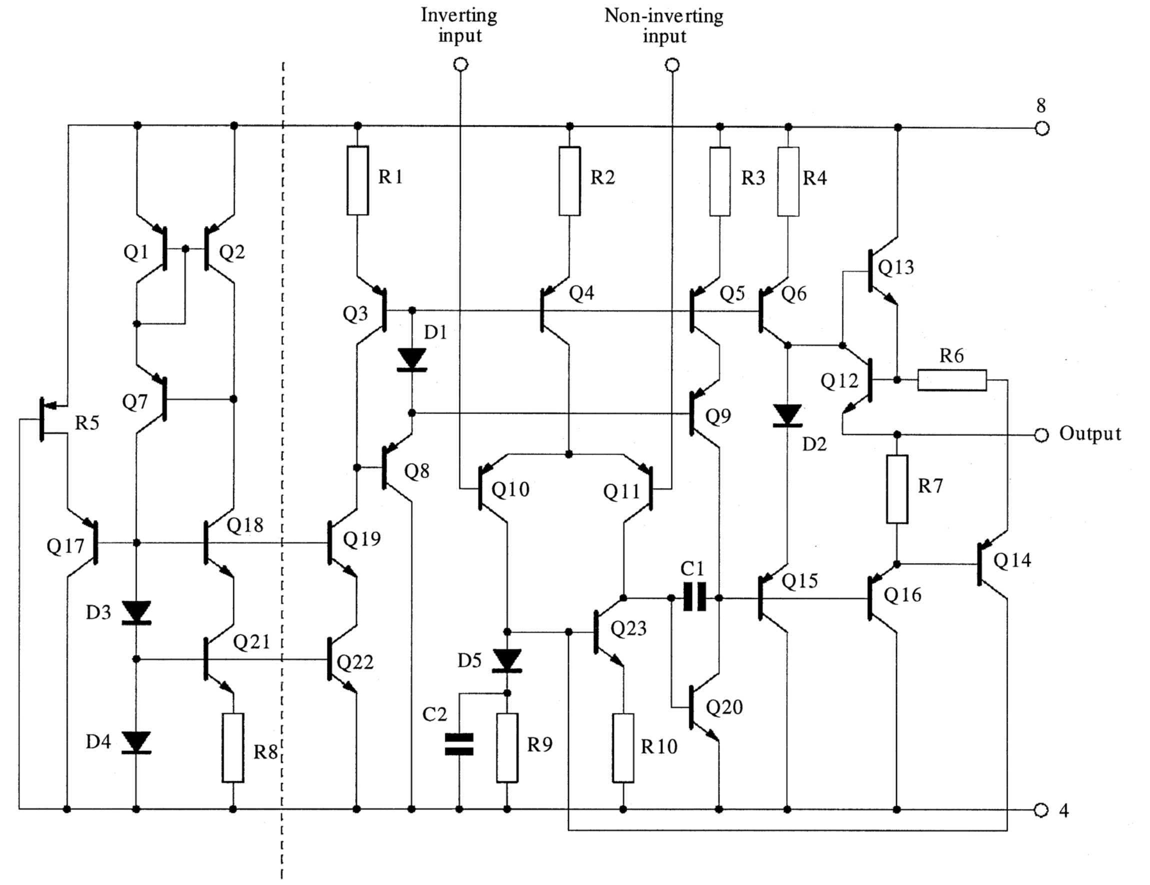
Related products

- See TS512 for equivalent product with automotive grade qualification.

Contents

1 Circuit schematics

Figure 1. Schematic diagram (1/2 LS204)



2 Absolute maximum ratings and operating conditions

Table 1. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V_{CC}	Supply voltage(1)	±18	V
V_i	Input voltage(2)	$\pm V_{CC}$	V
V_{id}	Differential input voltage(3)	$\pm(V_{CC}-1)$	V
R_{thja}	Thermal resistance junction-to-ambient(4)	125	°C/W
R_{thjc}	Thermal resistance junction-to-case(4)	40	°C/W
	Output short-circuit duration(5)	Infinite	
T_j	Junction temperature	150	°C
T_{stg}	Storage temperature range	-65 to +150	°C
ESD	HBM: human body model(6)	2	kV
	MM: machine model(7)	200	V
	CDM: charged device model(8)	1.5	kV

1. All voltage values, except differential voltage, are with respect to the zero reference level (ground) of the supply voltages where the zero reference level is the midpoint between V_{CC}^+ and V_{CC}^-.
2. The magnitude of the input voltage must never exceed the magnitude of the supply voltage or 15 volts, whichever is less.
3. Differential voltages are the non-inverting input terminal with respect to the inverting input terminal.
4. Short-circuits can cause excessive heating and destructive dissipation. Values are typical.
5. The output may be shorted to ground or to either supply. Temperature and/or supply voltages must be limited to ensure that the dissipation rating is not exceeded.
6. Human body model: A 100 pF capacitor is charged to the specified voltage, then discharged through a 1.5 kΩ resistor between two pins of the device. This is done for all couples of connected pin combinations while the other pins are floating.
7. Machine model: A 200 pF capacitor is charged to the specified voltage, then discharged directly between two pins of the device with no external series resistor (internal resistor < 5 Ω). This is done for all couples of connected pin combinations while the other pins are floating.
8. Charged device model: all pins and the package are charged together to the specified voltage and then discharged directly to the ground through only one pin. This is done for all pins.

Table 2. Operating conditions

Symbol	Parameter	LS204C	LS204I	Unit
V_{CC}	Supply voltage	6 to 30		V
V_{icm}	Common mode input voltage range	$V_{CC-}+1.5$ to $V_{CC+}-1.5$		V
T_{oper}	Operating free-air temperature range	0 to +70	-40 to +105	°C

3 Electrical characteristics

Table 3. Electrical characteristics at V_{CC} = ±15 V, T_{amb} = +25° C (unless otherwise specified)

Symbol	Parameter	LS204I			LS204C			Unit
		Min.	Typ.	Max.	Min.	Typ.	Max.	
I_{CC}	Supply current		0.7	1.2		0.8	1.5	mA
I_{ib}	Input bias current $T_{min} < T_{amb} < T_{max}$		50	150 300		100	300 700	nA
R_i	Input resistance (F = 1 kHz)		1			1		MΩ
V_{io}	Input offset voltage ($R_S \leq$ 10 kΩ) $T_{min} < T_{amb} < T_{max}$		0.5	2.5 3.5		0.5	3.5 5	mV
$\Delta V_{IO}/\Delta T$	Input offset voltage drift ($R_S \leq$ 10 kΩ) $T_{min} < T_{amb} < T_{max}$		5			5		µV/°C
I_{io}	Input offset current $T_{min} < T_{amb} < T_{max}$		5	20 40		12	50 100	nA
$\Delta I_{IO}/\Delta T$	Input offset current drift $T_{min} < T_{amb} < T_{max}$		0.08			0.1		nA/°C
I_{os}	Output short-circuit current		23			23		mA
A_{vd}	Large signal voltage gain $T_{min} < T_{amb} < T_{max}$ R_L = 2 kΩ, V_{CC} = ±15 V R_L = 2 kΩ, V_{CC} = ±4 V	90	100 95		86	100 95		dB
GBP	Gain bandwidth product (F =100kHz)	1.8	3		1.5	2.5		MHz
e_n	Equivalent input noise voltage F = 1kHz, R_s = 100Ω R_s = 50 Ω R_s = 1 kΩ R_s = 10 kΩ		8 10 18			10 12 20		$\frac{nV}{\sqrt{Hz}}$
THD	Total harmonic distortion (F = 1 kHz, A_v = 20 dB, R_L = 2 kΩ, V_o = 2 V_{pp})		0.03			0.03		%
$\pm V_{opp}$	Output voltage swing R_L = 2 kΩ, V_{CC} = ±15 V R_L = 2 kΩ, V_{CC} = ±4 V	±13	±3		±13	±3		V
V_{opp}	Large signal voltage swing R_L = 10 kΩ, F= 10 kHz		28			28		V_{pp}
SR	Slew rate (R_L = 2 kΩ, unity gain)	0.8	1.5			1		V/µs
SVR	Supply voltage rejection ratio $T_{min} < T_{amb} < T_{max}$	90			86			dB
CMR	Common mode rejection ratio V_{ic} = ±10 V $T_{min} < T_{amb} < T_{max}$	90			86			dB
V_{o1}/V_{o2}	Channel separation (F= 1 kHz)	100	120			120		dB

Figure 2. Supply current versus supply voltage

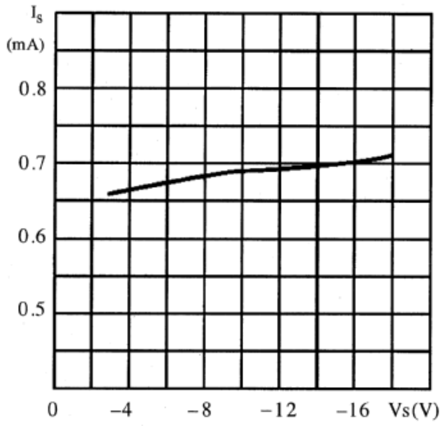


Figure 3. Supply current versus ambient temperature

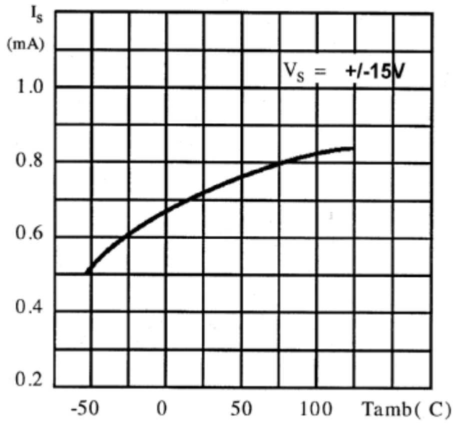


Figure 4. Output short circuit current versus ambient temperature

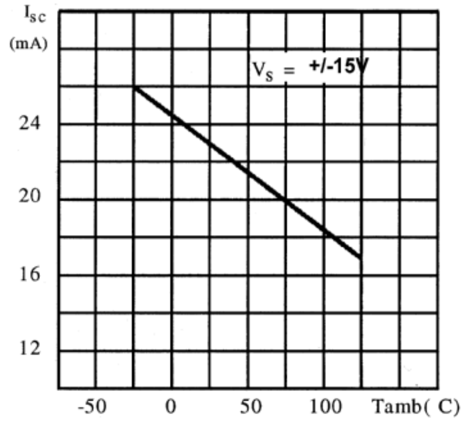


Figure 5. Open loop frequency and phase response

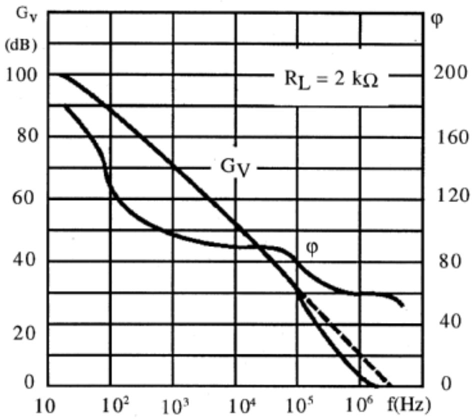


Figure 6. Output loop gain versus ambient temperature

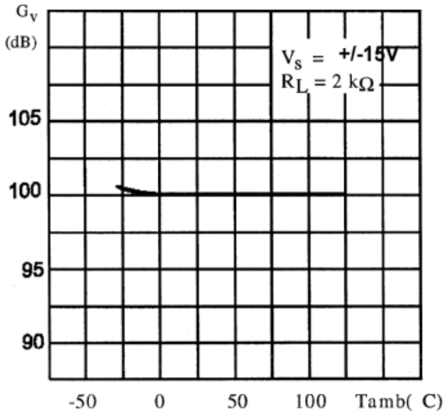


Figure 7. Supply voltage rejection versus frequency

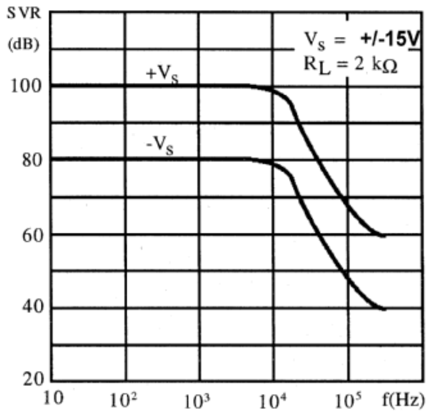


Figure 8. Large signal frequency response

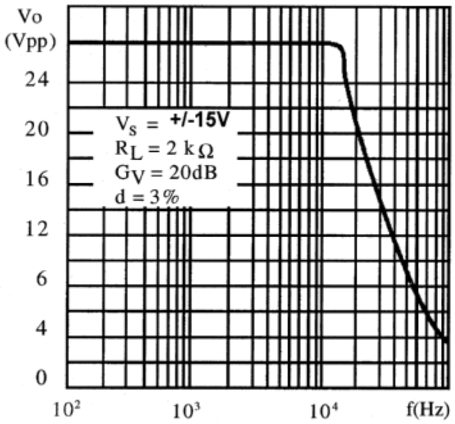


Figure 9. Output voltage swing versus load resistance

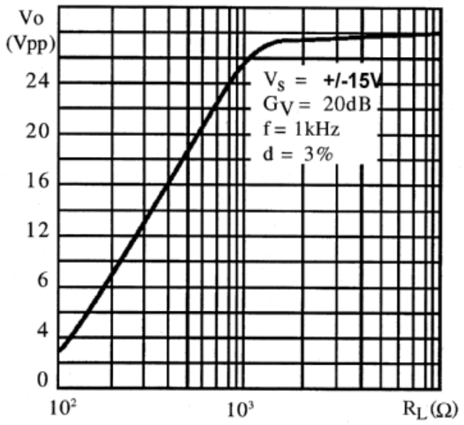


Figure 10. Total input noise versus frequency

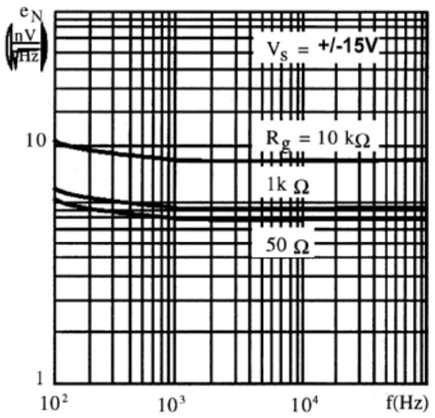


Figure 11. Amplitude response

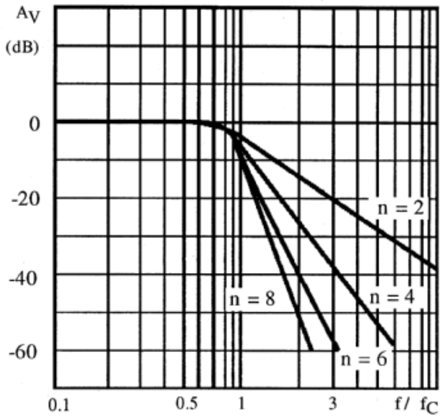
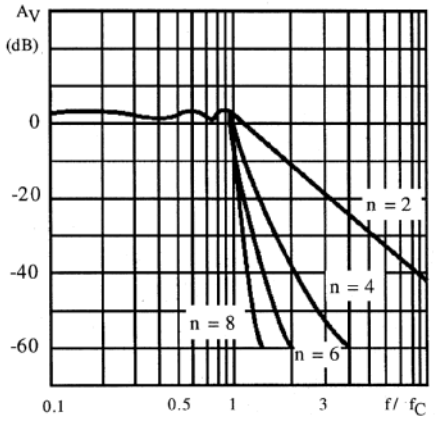


Figure 12. Amplitude response (±1 dB ripple)



4 Application information for active low-pass filters

4.1 Butterworth

The Butterworth is a "maximally flat" amplitude response filter (*Figure 11*).

Butterworth filters are used for filtering signals in data acquisition systems to prevent aliasing errors in samples-data applications and for general purpose low-pass filtering.

The cut-off frequency, Fc, is the frequency at which the amplitude response is down 3 dB. The attenuation rate beyond the cut-off frequency is n6 dB per octave of frequency, where n is the order (number of poles) of the filter.

Other characteristics:

- Flattest possible amplitude response
- Excellent gain accuracy at low-frequency end of passband

4.2 Bessel

The Bessel is a type of “linear phase” filter.

Because of their linear phase characteristics, these filters approximate a constant time delay over a limited frequency range. Bessel filters pass transient waveforms with a minimum of distortion. They are also used to provide time delays for low pass filtering of modulated waveforms and as a “running average” type filter.

The maximum phase shift is $\frac{-n\pi}{2}$ radians,

where n is the order (number of poles) of the filter. The cut-off frequency, Fc, is defined as the frequency at which the phase shift is one half of this value.

For accurate delay, the cut-off frequency should be twice the maximum signal frequency.

Table 4 can be used to obtain the -3 dB frequency of the filter.

Table 4. -3 dB frequency of the filter

	2 Poles	4 Poles	6 Poles	8 Poles
-3 dB frequency	0.77 Fc	0.67 Fc	0.57 Fc	0.50 Fc

Other characteristics:

- Selectivity not as great as Chebyschev or Butterworth
- Very little overshoot response to step inputs
- Fast rise time

4.3 Chebyschev

Chebyschev filters have greater selectivity than either Bessel or Butterworth at the expense of ripple in the passband (*Figure 12*).

Chebyschev filters are normally designed with peak-to-peak ripple values from 0.2 dB to 2 dB.

Increased ripple in the passband allows increased attenuation above the cut-off frequency.

The cut-off frequency is defined as the frequency at which the amplitude response passes through the specified maximum ripple band and enters the stop band.

Other characteristics:

- Greater selectivity
- Very non-linear phase response
- High overshoot response to step inputs

Table 5 shows the typical overshoot and setting time response of the low pass filters to a step input.

Table 5. Overshoot and setting time response of low pass filters to step input

	Number of poles	Peak overshoot	Settling time (% of final value)		
		% Overshoot	±1%	±0.1%	±0.01%
Butterworth	2 4 6 8	4 11 14 14	1.1Fc sec. 1.7/Fc 2.4/Fc 3.1/Fc	1.7Fc sec. 2.8/Fc 3.9S/Fc 5.1/Fc	1.9Fc sec. 3.8/Fc 5.0S/Fc 7.1/Fc
Bessel	2 4 6 8	0.4 0.8 0.6 0.1	0.8/Fc 1.0/Fc 1.3/Fc 1.6/Fc	1.4/Fc 1.8/Fc 2.1/Fc 2.3/Fc	1.7/Fc 2.4/Fc 2.7/Fc 3.2/Fc
Chebyschev (ripple ±0.25dB)	2 4 6 8	11 18 21 23	1.1/Fc 3.0/Fc 5.9/Fc 8.4/Fc	1.6/Fc 5.4/Fc 10.4/Fc 16.4/Fc	- - - -
Chebyschev (ripple ±1dB)	2 4 6 8	21 28 32 34	1.6/Fc 4.8/Fc 8.2/Fc 11.6/Fc	2.7/Fc 8.4/Fc 16.3/Fc 24.8/Fc	 - - -

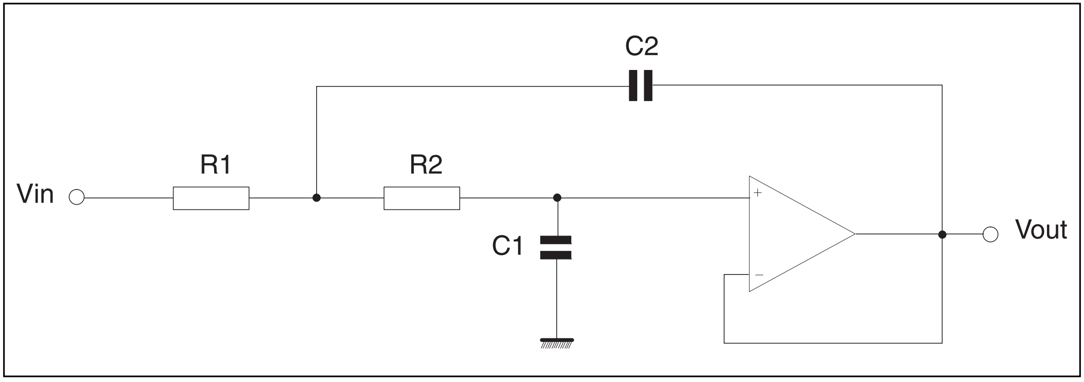
4.4 Design of 2nd order active low pass filter (Sallen and Key configuration unity gain op-amp)

For fixed R = R1 = R2, we have (see *Figure 13*):

$$C1 = \frac{1}{R}\,\frac{\zeta}{\omega c}$$

$$C2 = \frac{1}{R}\,\frac{1}{\xi\omega c}$$

Figure 13. Filter configuration



Three parameters are needed to characterize the frequency and phase response of a 2nd order active filter:

- the gain (Gv),
- the damping factor (ξ) or the Q factor (Q = 2 ξ)1),
- the cut-off frequency (Fc).

The higher order response is obtained with a series of 2nd order sections. A simple RC section is introduced when an odd filter is required.

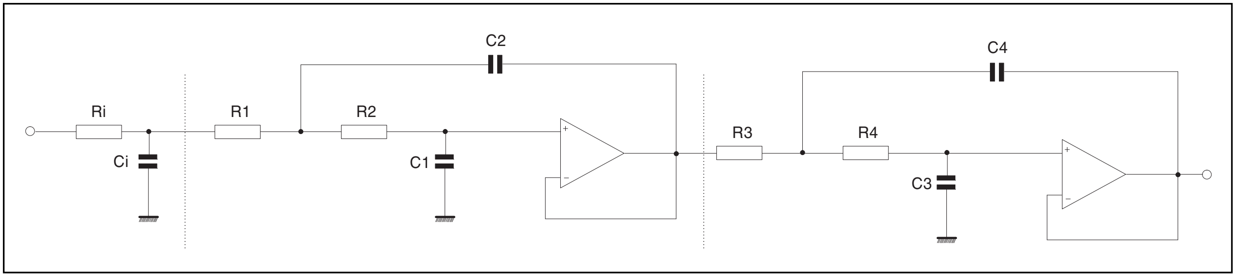
The choice of ξ (or Q factor) determines the filter response (see *Table 6*).

Table 6. Filter response to ξ or Q factor

Filter response	ξ	Q	Cut-off frequency (Fc)
Bessel	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{1}}{3}$	Frequency at which phase shift is -90°C
Butterworth	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{1}}{2}$	Frequency at which Gv = -3 dB
Chebyschev	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{1}}{2}$	Frequency at which the amplitude response passes through specified max. ripple band and enters the stop bank.

4.5 Example

Figure 14. 5th order low-pass filter (Butterworth) with unity gain configuration



In the circuit of *Figure 14*, for Fc = 3.4 kHz and Ri = R1 = R2 = R3 = 10 kΩ, we obtain:

$$Ci = 1.354\frac{1}{R}\frac{1}{2\pi fc} = 6.33nF$$

$$C1 = 0.421\frac{1}{R}\frac{1}{2\pi fc} = 1.97nF$$

$$C2 = 1.753\frac{1}{R}\frac{1}{2\pi fc} = 8.20nF$$

$$C3 = 0.309\frac{1}{R}\frac{1}{2\pi fc} = 1.45nF$$

$$C4 = 3.325\frac{1}{R}\frac{1}{2\pi fc} = 15.14nF$$

The attenuation of the filter is 30 dB at 6.8 kHz and better than 60 dB at 15 kHz.

The same method, referring to *Table 7* and *Figure 15* is used to design high-pass filters. In this case the damping factor is found by taking the reciprocal of the numbers in *Table 7*.

For Fc = 5 kHz and Ci = C1 = C2 = C3 = 1 nF we obtain:

$$Ri = \frac{1}{0.354}\frac{1}{C}\frac{1}{2\pi fc} = 25.5k\Omega$$

$$R1 = \frac{1}{0.421}\frac{1}{C}\frac{1}{2\pi fc} = 75.6k\Omega$$

$$R2 = \frac{1}{1.753}\frac{1}{C}\frac{1}{2\pi fc} = 18.2k\Omega$$

$$R3 = \frac{1}{0.309}\frac{1}{C}\frac{1}{2\pi fc} = 103k\Omega$$

$$R4 = \frac{1}{3.325}\frac{1}{C}\frac{1}{2\pi fc} = 9.6k\Omega$$

Figure 15. 5th order high-pass filter (Butterworth) with unity gain configuration

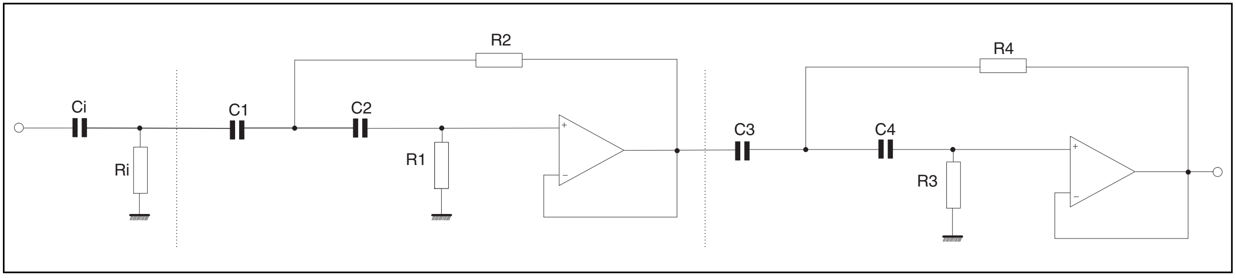


Table 7. Damping factor for low-pass Butterworth filters

Order	Ci	C1	C2	C3	C4	C5	C6	C7	C8
2		0.707	1.41						
3	1.392	0.202	3.54						
4		0.92	1.08	0.38	2.61				
5	1.354	0.421	1.75	0.309	3.235				
6		0.966	1.035	0.707	1.414	0.259	3.86		
7	1.336	0.488	1.53	0.623	1.604	0.222	4.49		
8		0.98	1.02	0.83	1.20	0.556	1.80	0.195	5.125

5 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK® is an ST trademark.

Figure 16. SO-8 package mechanical drawing

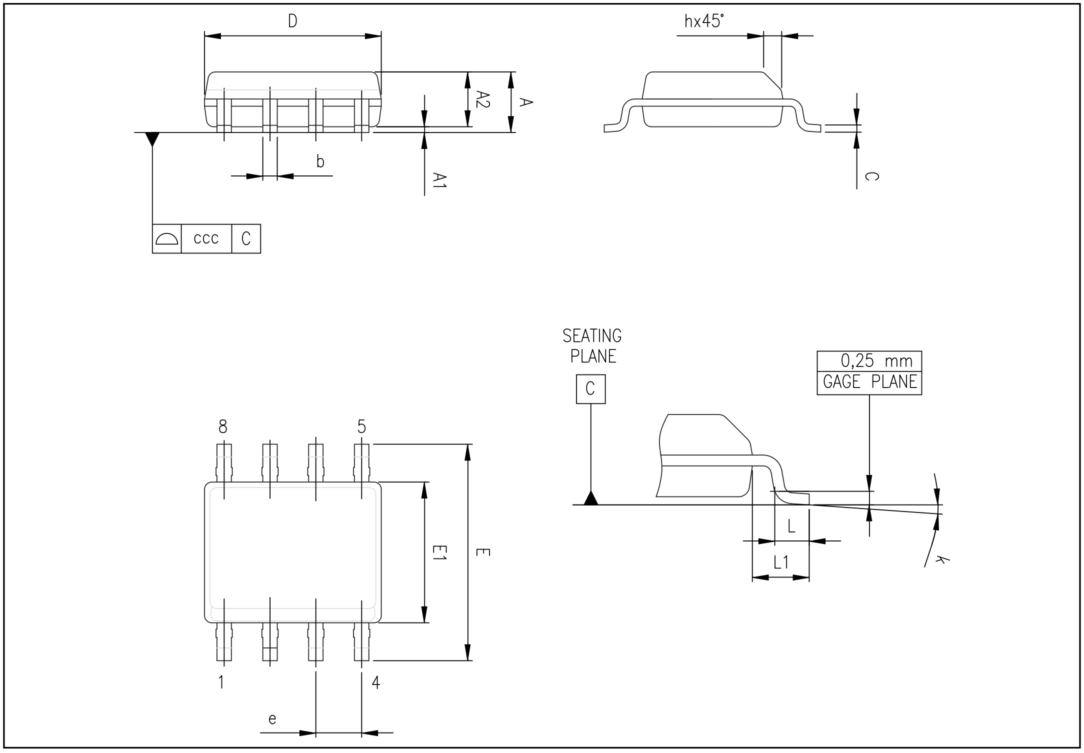


Table 8. SO-8 package mechanical data

Ref.	Dimensions					
	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			1.75			0.069
A1	0.10		0.25	0.004		0.010
A2	1.25			0.049		
b	0.28		0.48	0.011		0.019
c	0.17		0.23	0.007		0.010
D	4.80	4.90	5.00	0.189	0.193	0.197
E	5.80	6.00	6.20	0.228	0.236	0.244
E1	3.80	3.90	4.00	0.150	0.154	0.157
e		1.27			0.050	
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k	1°		8°	1°		8°
ccc			0.10			0.004

6 Ordering information

Table 9. Order codes

Order code	Temperature range	Package	Packing	Marking
LS204CDT	0°C, +70°C	SO-8	Tape & reel	204C
LS204IDT	-40°C, +105°C	SO-8	Tape & reel	204I

7 Revision history

Table 10. Document revision history

Date	Revision	Changes
29-Nov-2001	1	Initial release.
4-Jun-2008	2	Updated document format. Added automotive grade order codes.
27-Jun-2014	3	Updated title of datasheet and *Description* Added *Related products on page 1* Updated *Section 5: Package information* Updated *Table 9: Order codes* Removed DIP8 package and related specifications from datasheet

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