M3806x Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

DESCRIPTION

The M3806x group is made up of 8-bit microcomputers based on the MELPS 740 core.

The M3806x group is designed for controlling systems that require analog signal processing and include two serial I/O functions, A-D converters, and D-A converters.

The various microcomputers in the M3806x group include variations of internal memory size and packaging. For details, see the section on part numbering.

For details on availability of microcomputers in the M3806x group, see the section on group expansion.

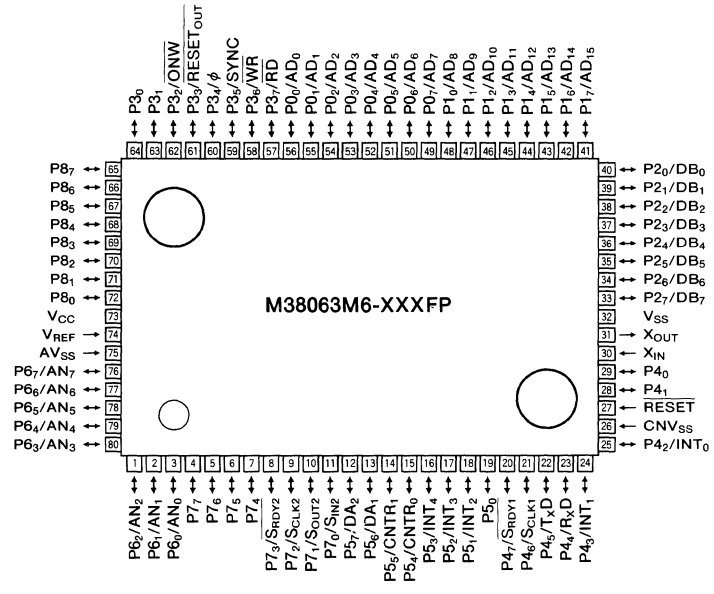
FEATURES

- Basic machine-language instructions 71
- Instruction execution time 0.5μs
  (shortest instruction at 8MHz oscillation frequency)
- Memory size
  ROM ..... 4K to 32K bytes
  RAM ..... 192 to 1024 bytes
- Programmable input/output ports 72
- Interrupts ..... 16 sources, 16 vectors
- Timers ..... 8 bit×4
- Serial I/O1 ..... 8-bit×1(UART or Clock-synchronized)
- Serial I/O2 ..... 8-bit×1(Clock-synchronized)
- A-D converter ..... 8-bit×8 channels
- D-A converter ..... 8-bit×2 channels
- Clock generation circuit ..... Internal feedback amplifier
  (connect to external ceramic resonator or quartz crystal)
- Supply voltage ..... 3.0 to 5.5V
- Low power dissipation 32mW
- Memory expansion possible
- Operating temperature range ..... −20 to 85℃

APPLICATIONS

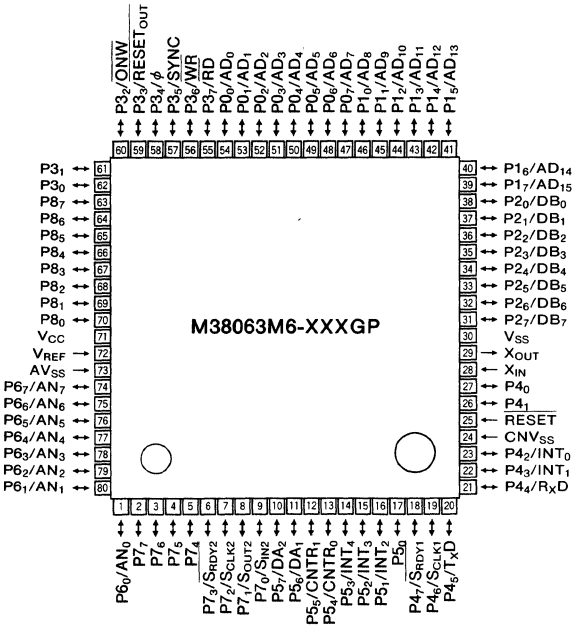
Office automation, VCRs, tuners, musical instruments, cameras, air conditioners, etc.

PIN CONFIGURATION (TOP VIEW)



Package type : 80P6N
80-pin plastic-molded QFP

PIN CONFIGURATION (TOP VIEW)



Package type : 80P6S
80-pin plastic-molded QFP

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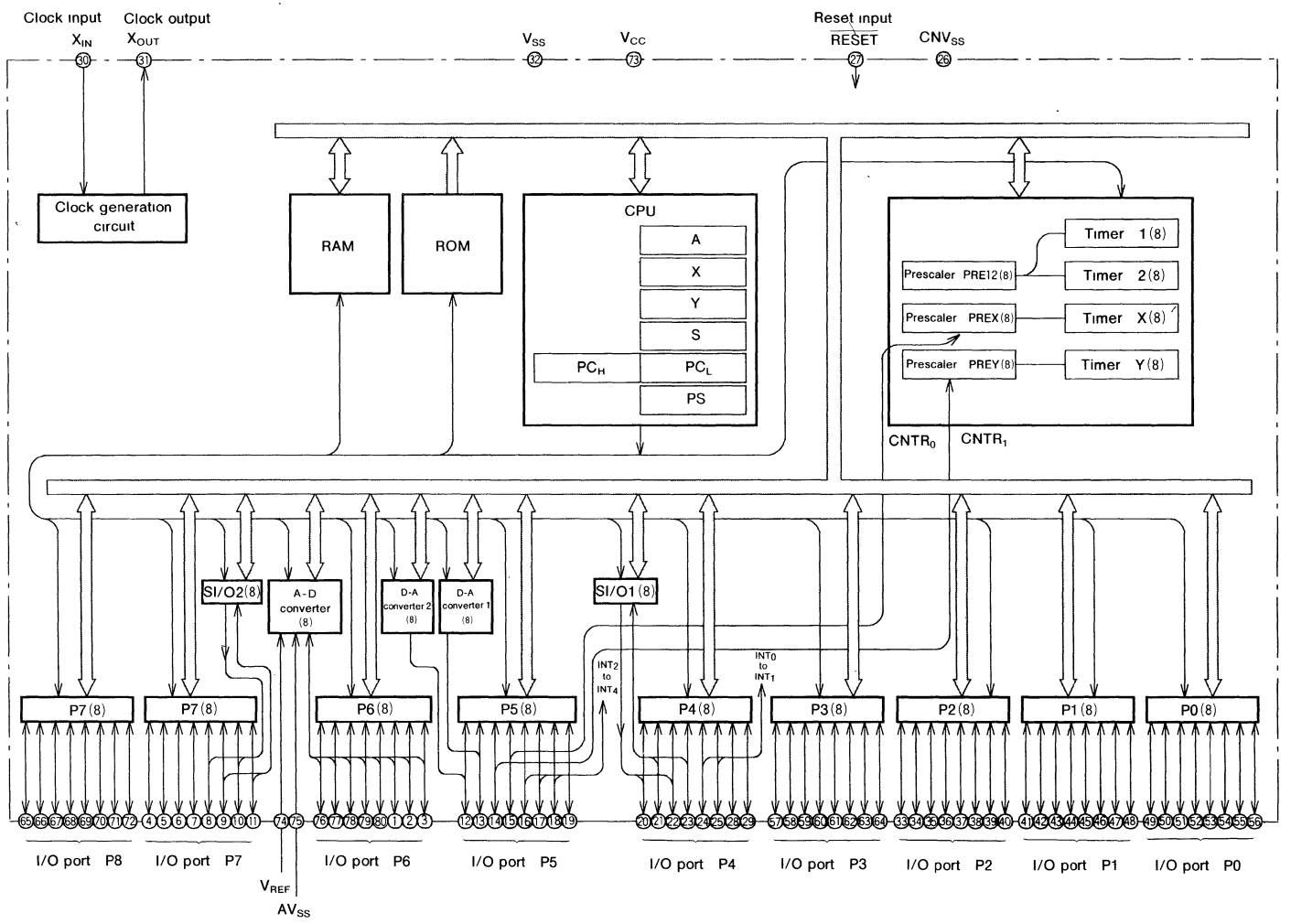
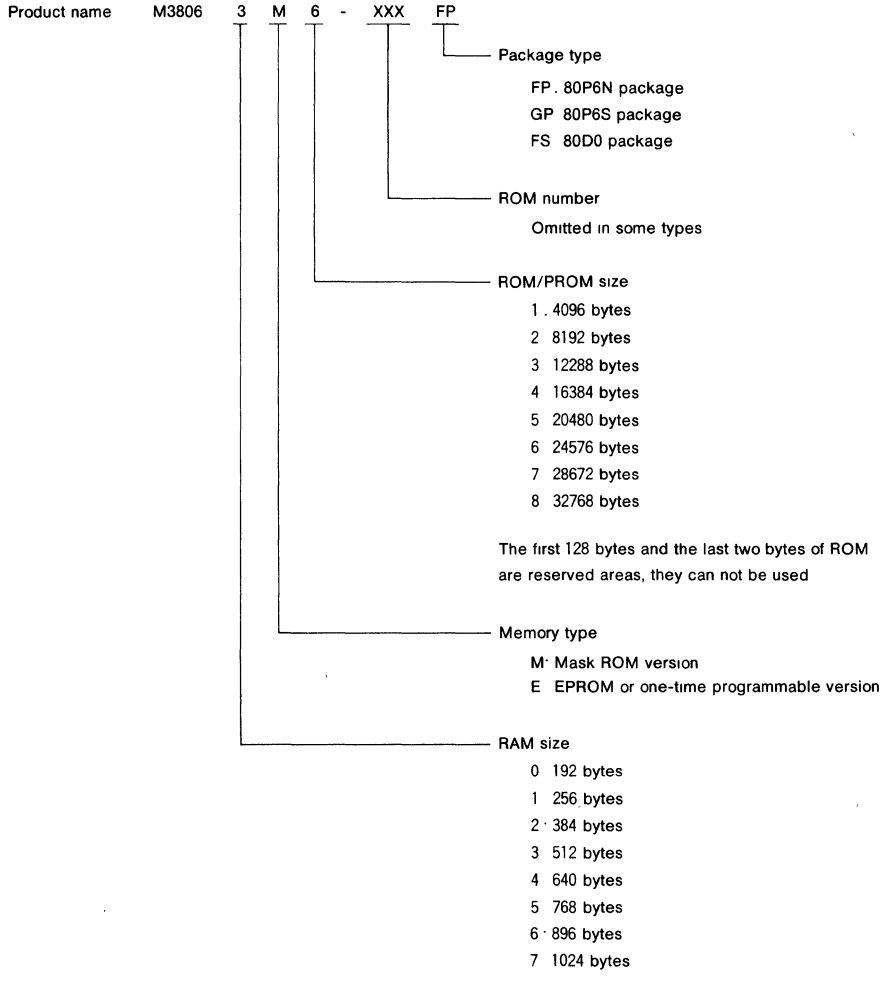
FUNCTIONAL BLOCK DIAGRAM (Package : 80P6N)



PIN DESCRIPTION

Pin	Name	Function	Alternate Function
V_{CC}	Power supply	Power supply inputs 4 0 to 5 5V to V_{CC}, and 0V to V_{SS}.	
V_{SS}			
CNV_{SS}	CNV_{SS}	This pin controls the operation mode of the chip Normally connected to V_{SS} If this pin is connected to V_{CC}, the internal ROM is inhibited and external memory is accessed	
V_{REF}	Analog reference voltage	Reference voltage input pin for A-D and D-A converters	
AV_{SS}	Analog power supply	GND input pin for A-D and D-A converter Keep at the same potential as V_{SS}	
$\overline{RESET}$	Reset input	To reset the microcomputer, this pin should be kept at an "L" level for more than 2μs under normal operating conditions	
X_{IN}	Clock input	Input and output signals for the internal clock generation circuit Connect a ceramic resonator or quartz crystal between the X_{IN} and X_{OUT} pins to set the oscillation frequency If an external clock is used, connect the clock source to the X_{IN} pin and leave the X_{OUT} pin open	
X_{OUT}	Clock output		
$P0_0$—$P0_7$	I/O port P0	An 8 bit CMOS I/O port An I/O direction register allows each pin to be individually programmed as either input or output At reset this port is set to input mode In modes other than single-chip, these pins are used as address, data, and control bus I/O pins	
$P1_0$—$P1_7$	I/O port P1		
$P2_0$—$P2_7$	I/O port P2		
$P3_0$—$P3_7$	I/O port P3		
$P4_0$, $P4_1$	I/O port P4	An 8-bit CMOS I/O port with the same function as port P0	
$P4_2/INT_0$, $P4_3/INT_1$			External interrupt input pin
$P4_4/R_XD$, $P4_5/T_XD$, $P4_6/S_{CLK1}$, $P4_7/\overline{S_{RDY1}}$			Serial I/O1 I/O pins
$P5_0$	I/O port P5	An 8-bit CMOS I/O port with the same function as port P0	
$P5_1/INT_2$—$P5_3/INT_4$			External interrupt input pin
$P5_4/CNTR_0$, $P5_5/CNTR_1$			Timer X and Timer Y I/O pins
$P5_6/DA_1$, $P5_7/DA_2$			D-A converter output pins
$P6_0/AN_0$—$P6_7/AN_7$	I/O port P6	An 8-bit CMOS I/O port with the same function as port P0	A-D converter input pins
$P7_0/S_{IN2}$, $P7_1/S_{OUT2}$, $P7_2/S_{CLK2}$, $P7_3/\overline{S_{RDY2}}$	I/O port P7	An 8-bit I/O port with the same function as port P0 The output structure of this port is N-channel open drain, and the input levels are CMOS compatible	Serial I/O2 I/O pins
$P7_4$—$P7_7$			
$P8_0$—$P8_7$	I/O port P8	An 8-bit CMOS I/O port with the same function as port P0	

PART NUMBERING



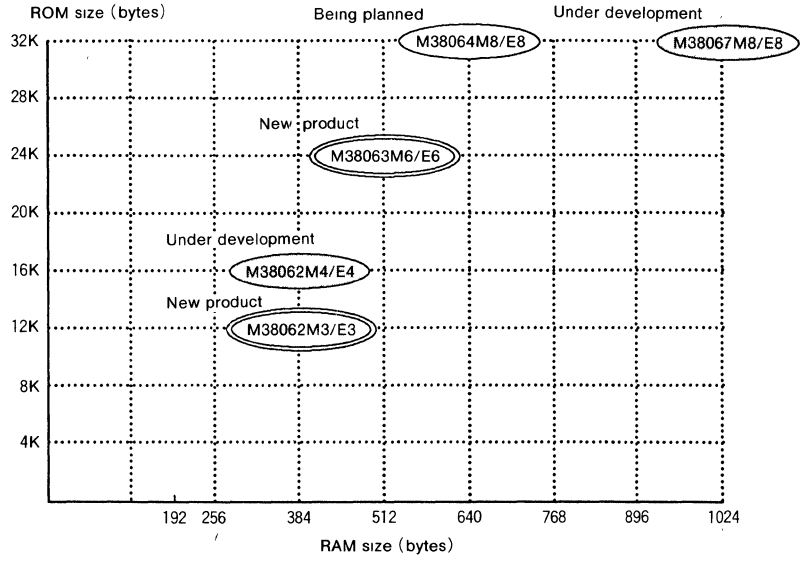
GROUP EXPANSION

Mitsubishi plans to expand the M3806x group as follows:

(1) Support for mask ROM, one-time programmable, and EPROM versions
ROM/PROM capacity ..... 12K to 32K bytes
RAM capacity ..... 384 to 1024 bytes

(2) Packages
80P6N ..... 0.8mm-pitch plastic molded QFP
80P6S ..... 0.65mm-pitch plastic molded QFP
80D0 ..... 0.8mm-pitch ceramic LCC

Memory expansion plan



The development schedule and other details of products under development may be revised without notice
Currently supported products are listed below

As of March 1992

Product name	(P) ROM size (bytes)	RAM size (bytes)	Package	Remarks
M38062M3-XXXFP	12K	384	80P6N	Mask ROM version
M38062E3-XXXFP				One-time programmable version
M38062E3FP				One-time programmable version (blank)
M38062M3-XXXGP			80P6S	Mask ROM version
M38062E3-XXXGP				One-time programmable version
M38062E3GP				One-time programmable version (blank)
M38062E3FS			80D0	EPROM version
M38062M6-XXXFP	24K	512	80P6N	Mask ROM version
M38062E6-XXXFP				One-time programmable version
M38063E6FP				One-time programmable version (blank)
M38063M6-XXXGP			80P6S	Mask ROM version
M38063E6-XXXGP				One-time programmable version
M38063E6GP				One-time programmable version (blank)
M38063E6FS			80D0	EPROM version

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FUNCTIONAL DESCRIPTION

Central Processing Unit (CPU)

Microcomputers of the M3806x group use the standard MELPS 740 instruction set. Refer to the table of MELPS 740 addressing modes and machine instructions or the MELPS 740 Software Manual for details on the instruction set.

Machine-resident MELPS 740 instructions are as follows:

The FST and SLW instructions are not available for use.

The STP, WIT, MUL, and DIV instructions can be used.

CPU Mode Register

The CPU mode register (address $003B_{16}$) contains processor mode bits that specify the operating mode of the chip. The CPU mode register also contains the stack page select bit.

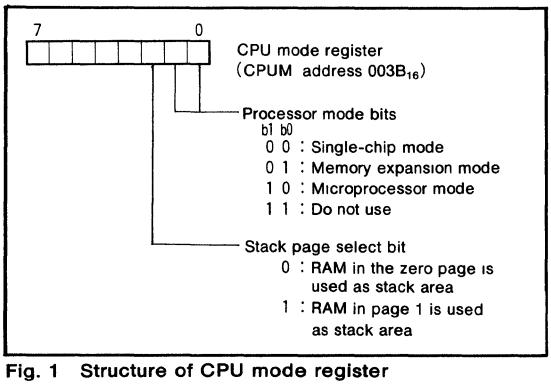

Fig. 1 Structure of CPU mode register

MEMORY

- **Special Function Register (SFR) Area**
  The Special Function Register area contains registers which control functions such as I/O ports and timers, and is located in the zero page area.
- **RAM**
  RAM is used for data storage as well for stack area.
- **ROM**
  The first 128 bytes and the last two bytes of ROM are reserved for device testing and the rest is user area for storing programs.
- **Interrupt Vector Area**
  The interrupt vector area contains reset and interrupt vectors.
- **Zero Page**
  The 256 bytes from addresses 0000_{16} to $00FF_{16}$ are called the zero page area. The internal RAM and the special function registers (SFR) are allocated to this area.
  The zero page addressing mode can be used to specify memory and register addresses in the zero page area. This dedicated zero page addressing mode enables access to this area with only 2 bytes.
- **Special Page**
  The 256 bytes from addresses $FF00_{16}$ to $FFFF_{16}$ are called the special page area. The special page addressing mode can be used to specify memory addresses in the special page area. This dedicated special page addressing mode enables access to this area with only 2 bytes.

RAM area

RAM capacity (bytes)	Address $XXXX_{16}$
192	$00FF_{16}$
256	$013F_{16}$
384	$01BF_{16}$
512	$023F_{16}$
640	$02BF_{16}$
768	$033F_{16}$
896	$03BF_{16}$
1024	$043F_{16}$

ROM area

ROM capacity (bytes)	Address $YYYY_{16}$	Address $ZZZZ_{16}$
4096	$F000_{16}$	$F080_{16}$
8192	$E000_{16}$	$E080_{16}$
12288	$D000_{16}$	$D080_{16}$
16384	$C000_{16}$	$C080_{16}$
20480	$B000_{16}$	$B080_{16}$
24576	$A000_{16}$	$A080_{16}$
28672	9000_{16}	9080_{16}
32768	8000_{16}	8080_{16}

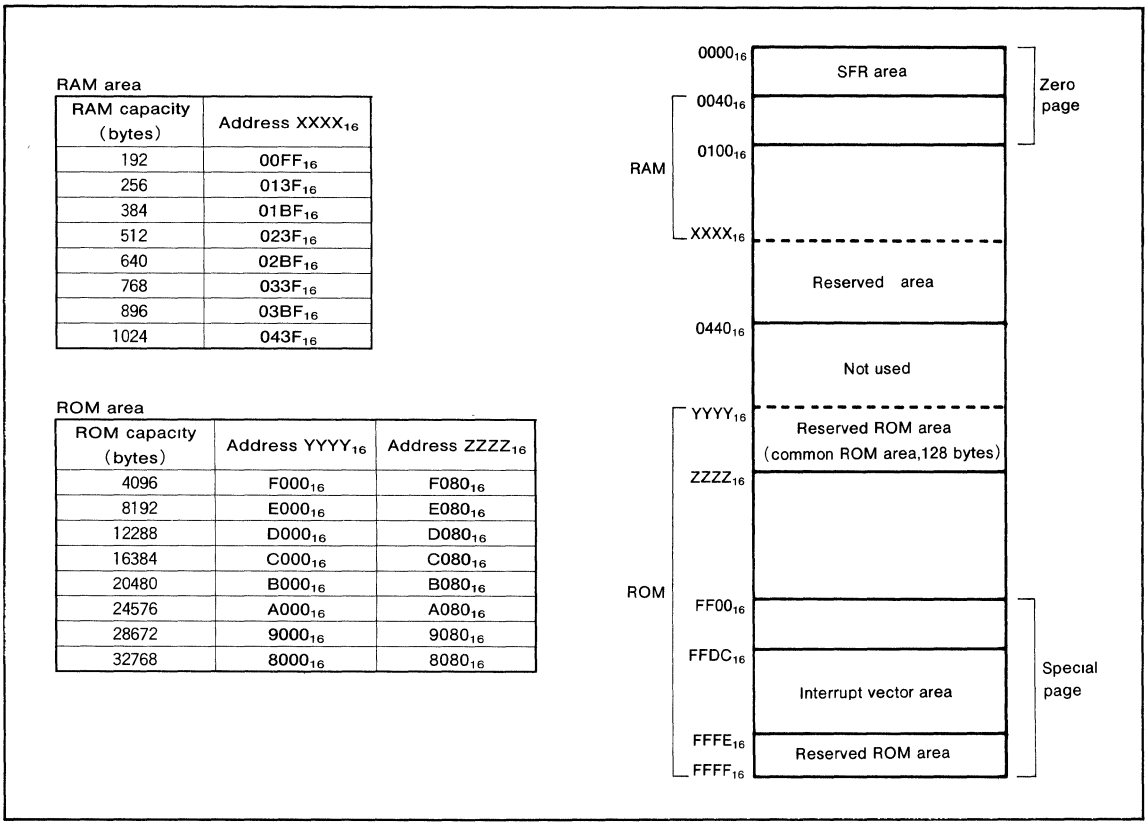

Fig. 2 Memory map diagram

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0000_{16}	Port P0 (P0)
0001_{16}	Port P0 direction register (P0D)
0002_{16}	Port P1 (P1)
0003_{16}	Port P1 direction register (P1D)
0004_{16}	Port P2 (P2)
0005_{16}	Port P2 direction register (P2D)
0006_{16}	Port P3 (P3)
0007_{16}	Port P3 direction register (P3D)
0008_{16}	Port P4 (P4)
0009_{16}	Port P4 direction register (P4D)
$000A_{16}$	Port P5 (P5)
$000B_{16}$	Port P5 direction register (P5D)
$000C_{16}$	Port P6 (P6)
$000D_{16}$	Port P6 direction register (P6D)
$000E_{16}$	Port P7 (P7)
$000F_{16}$	Port P7 direction register (P7D)
0010_{16}	Port P8 (P8)
0011_{16}	Port P8 direction register (P8D)
0012_{16}	
0013_{16}	
0014_{16}	
0015_{16}	
0016_{16}	
0017_{16}	
0018_{16}	Transmit/receive buffer 1 (TB1/RB1)
0019_{16}	Serial I/O1 status register (SIO1STS)
$001A_{16}$	Serial I/O1 control register (SIO1CON)
$001B_{16}$	UART control register (UARTCON)
$001C_{16}$	Baud rate generator (BRG)
$001D_{16}$	Serial I/O2 control register (SIO2CON)
$001E_{16}$	
$001F_{16}$	Serial I/O2 register (SIO2)

0020_{16}	Prescaler 12 (PRE12)
0021_{16}	Timer 1 (T1)
0022_{16}	Timer 2 (T2)
0023_{16}	Timer XY mode register (TM)
0024_{16}	Prescaler X (PREX)
0025_{16}	Timer X (TX)
0026_{16}	Prescaler Y (PREY)
0027_{16}	Timer Y (TY)
0028_{16}	
0029_{16}	
$002A_{16}$	
$002B_{16}$	
$002C_{16}$	
$002D_{16}$	
$002E_{16}$	
$002F_{16}$	
0030_{16}	
0031_{16}	
0032_{16}	
0033_{16}	
0034_{16}	AD/DA control register (ADCON)
0035_{16}	A-D conversion register (AD)
0036_{16}	D-A1 conversion register (DA1)
0037_{16}	D-A2 conversion register (DA2)
0038_{16}	
0039_{16}	
$003A_{16}$	Interrupt edge selection register (INTEDGE)
$003B_{16}$	CPU mode register (CPUM)
$003C_{16}$	Interrupt request register 1 (IREQ1)
$003D_{16}$	Interrupt request register 2 (IREQ2)
$003E_{16}$	Interrupt control register 1 (ICON1)
$003F_{16}$	Interrupt control register 2 (ICON2)

Fig. 3 Memory map of special function register (SFR)

I/O PORTS

Direction Registers

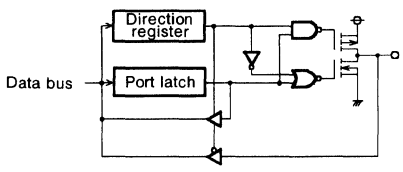
The M3806x group microprocessors have 72 programmable I/O pins arranged in nine I/O ports (ports P0 to P8). The I/O ports have direction registers which determine the input/output direction of each individual pin. Each bit in a direction register corresponds to one pin, each pin can be set to be input or output. When "0" is written to the bit corresponding to a pin, that pin becomes an input pin. When "1" is written to that bit, that pin becomes an output pin.

If data is read from a pin which is set for output, the value of the port output latch is read, not the value of the pin itself. Pins set to input are floating. If a pin set to input is written to, only the port output latch is written to and the pin remains floating.

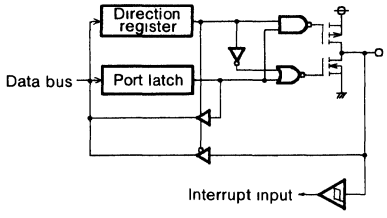
Pin	Name	Input/Output	I/O Format	Non-Port Function	Related SFRs	Ref No
$P0_0$—$P0_7$	Port P0	Input/output, individual bits	CMOS 3-state output CMOS level input	Address lower-byte output	CPU mode register	(1)
$P1_0$—$P1_7$	Port P1	Input/output, individual bits	CMOS 3-state output CMOS level input	Address upper-byte output	CPU mode register	
$P2_0$—$P2_7$	Port P2	Input/output, individual bits	CMOS 3-state output CMOS level input	Data bus I/O	CPU mode register	
$P3_0$—$P3_7$	Port P3	Input/output, individual bits	CMOS 3-state output CMOS level input	Control signal I/O	CPU mode register	
$P4_0$, $P4_1$	Port P4	Input/output, individual bits	CMOS 3-state output CMOS level input			
$P4_2/INT_0$, $P4_3/INT_1$				External interrupt input	Interrupt edge selection register	(2)
$P4_4/R_xD$,				Serial I/O1 function I/O	Serial I/O control register UART control register	(3)
$P4_5/T_xD$,						(4)
$P4_6/S_{CLK1}$,						(5)
$P4_7/\overline{S_{RDY1}}$						(6)
$P5_0$	Port P5	Input/output, individual bits	CMOS 3-state output CMOS level input			(1)
$P5_1/INT_2$, $P5_2/INT_3$, $P5_3/INT_4$				External interrupt input	Interrupt edge selection register	(2)
$P5_4/CNTR_0$, $P5_5/CNTR_1$				Timer XY function I/O		(7)
$P5_6/DA_1$, $P5_7/DA_2$				D-A converter output	AD/DA control register	(8)
$P6_0/AN_0$— $P6_7/AN_7$	Port P6	Input/output, individual bits	CMOS 3-state output CMOS level input	A-D converter input		(9)
$P7_0/S_{IN2}$,	Port P7	Input/output, individual bits	N-channel open-drain output CMOS level input	Serial I/O2 function I/O	Serial I/O2 control register	(10)
$P7_1/S_{OUT2}$,						(11)
$P7_2/S_{CLK2}$,						(12)
$P7_3/\overline{S_{RDY2}}$						(13)
$P7_4$—$P7_7$						(14)
$P8_0$—$P8_7$	Port P8	Input/output, individual bits	CMOS 3-state output CMOS level input			(1)

Note : For details of the functions of ports P0 to P3 in modes other than single-chip mode, and how to use double-function ports as function I/O ports, see the applicable sections.

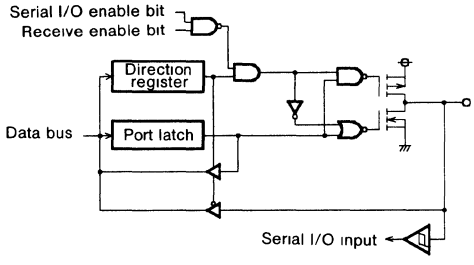
(1) Port P0, P1, P2, P3, $P4_0$, $P4_1$, $P5_0$, or P8



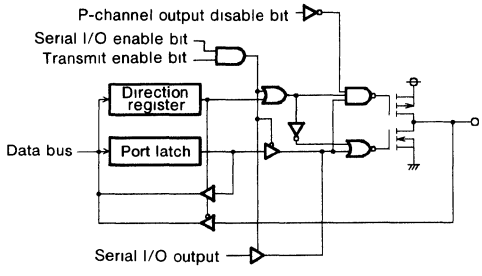
(2) Port $P4_2$, $P4_3$, $P5_1$, $P5_2$, or $P5_3$



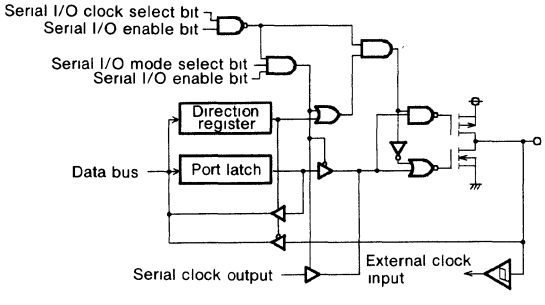
(3) Port $P4_4$



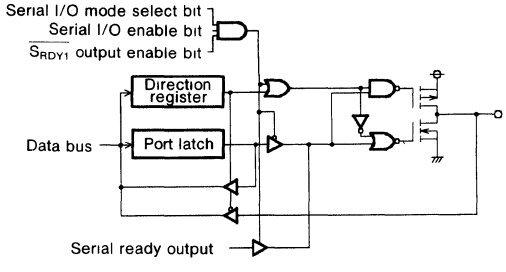
(4) Port $P4_5$



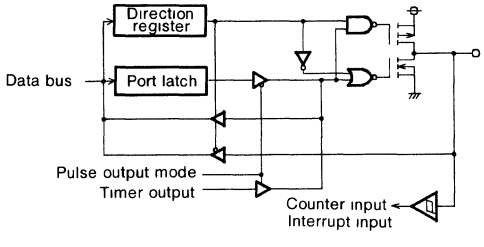
(5) Port $P4_6$



(6) Port $P4_7$



(7) Port $P5_4$ or $P5_5$



(8) Port $P5_6$ or $P5_7$

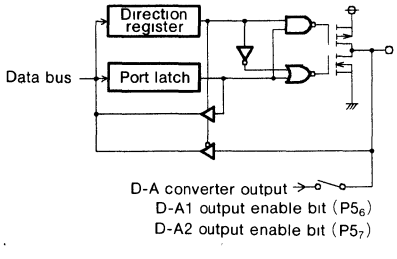
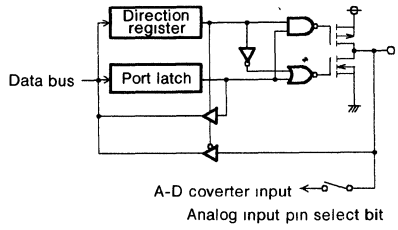
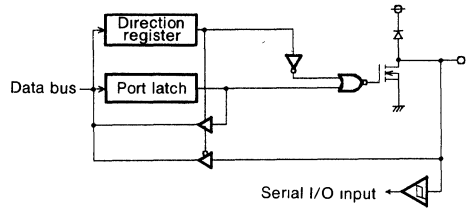


Fig. 4 Port block diagram (single-chip mode) (1)

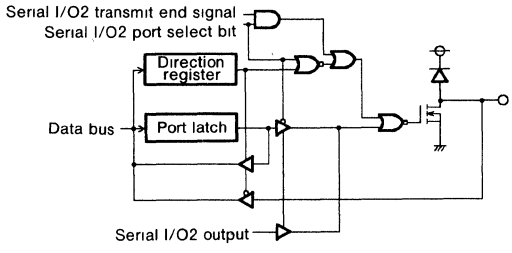
(9) Port P6



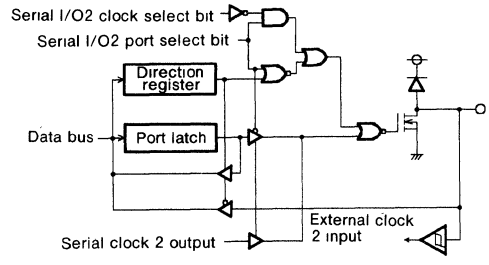
(10) Port $P7_0$



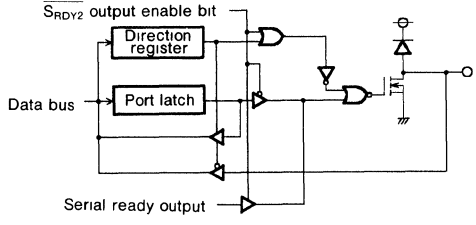
(11) Port $P7_1$



(12) Port $P7_2$



(13) Port $P7_3$



(14) Port $P7_4$ to Port $P7_7$

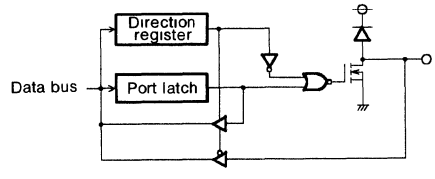


Fig. 5 Port block diagram (single-chip mode) (2)

INTERRUPTS

A total of 16 sources can generate interrupts: 7 external, 8 internal, and 1 software.

● **Interrupt Control**

Each interrupt is controlled by an interrupt request bit, an interrupt enable bit, and the interrupt disable flag-except for the software interrupt set by the BRK instruction. An interrupt is generated if the corresponding interrupt request and enable bits are "1" and the interrupt disable flag is "0".

Interrupt enable bits can be set or cleared by software.

Interrupt request bits can be cleared by software, but cannot be set by software.

The I flag disables all interrupts except for the BRK instruction interrupt.

● **Interrupt Operation**

When an interrupt is received, the program counter and processor status register are automatically pushed onto the stack. The interrupt disable flag is set to inhibit other interrupts from interfering. The corresponding interrupt request bit is cleared and the interrupt jump destination address is read from the vector table into the program counter.

● **Notes on Use**

When the active edge of an external interrupt (INT_0 to INT_4, $CNTR_0$, or $CNTR_1$) is changed, the corresponding interrupt request bit may also be set. To insure proper operation when selecting the active edge, disable interrupts before setting the interrupt edge selection.

Table 1 Interrupt vector addresses and priorities

Interrupt cause	Priority	Vector address (Note 1)		Interrupt request generation conditions	Remarks
		High	Low		
Reset (Note 2)	1	$FFFD_{16}$	$FFFC_{16}$	At reset	Non-maskable
INT_0	2	$FFFB_{16}$	$FFFA_{16}$	At detection of either rising or falling edge of INT_0 input	External interrupt (active edge selectable)
INT_1	3	$FFF9_{16}$	$FFF8_{16}$	At detection of either rising or falling edge of INT_1 input	External interrupt (active edge selectable)
Serial I/O1 reception	4	$FFF7_{16}$	$FFF6_{16}$	At end of serial I/O1 data reception	Valid when serial I/O1 is selected
Serial I/O1 transmission	5	$FFF5_{16}$	$FFF4_{16}$	At end of serial I/O1 transfer shift or when transmission buffer is empty	Valid when serial I/O1 is selected
Timer X	6	$FFF3_{16}$	$FFF2_{16}$	At timer X overflow	
Timer Y	7	$FFF1_{16}$	$FFF0_{16}$	At timer Y overflow	
Timer 1	8	$FFEF_{16}$	$FFEE_{16}$	At timer 1 overflow	STP release timer overflow
Timer 2	9	$FFED_{16}$	$FFEC_{16}$	At timer 2 overflow	
$CNTR_0$	10	$FFEB_{16}$	$FFEA_{16}$	At detection of either rising or falling edge of $CNTR_0$ input	External interrupt (active edge selectable)
$CNTR_1$	11	$FFE9_{16}$	$FFE8_{16}$	At detection of either rising or falling edge of $CNTR_1$ input	External interrupt (active edge selectable)
Serial I/O2	12	$FFE7_{16}$	$FFE6_{16}$	At end of serial I/O2 data transfer	Valid when serial I/O2 is selected
INT_2	13	$FFE5_{16}$	$FFE4_{16}$	At detection of either rising or falling edge of INT_2 input	External interrupt (active edge selectable)
INT_3	14	$FFE3_{16}$	$FFE2_{16}$	At detection of either rising or falling edge of INT_3 input	External interrupt (active edge selectable)
INT_4	15	$FFE1_{16}$	$FFE0_{16}$	At detection of either rising or falling edge of INT_4 input	External interrupt (active edge selectable)
A-D converter	16	$FFDF_{16}$	$FFDE_{16}$	At end of A-D conversion	
BRK instruction	17	$FFDD_{16}$	$FFDC_{16}$	At BRK instruction execution	Non-maskable software interrupt

Note 1 : Vector addresses contain interrupt jump destination addresses
2 : Reset function in the same way as an interrupt with the highest priority

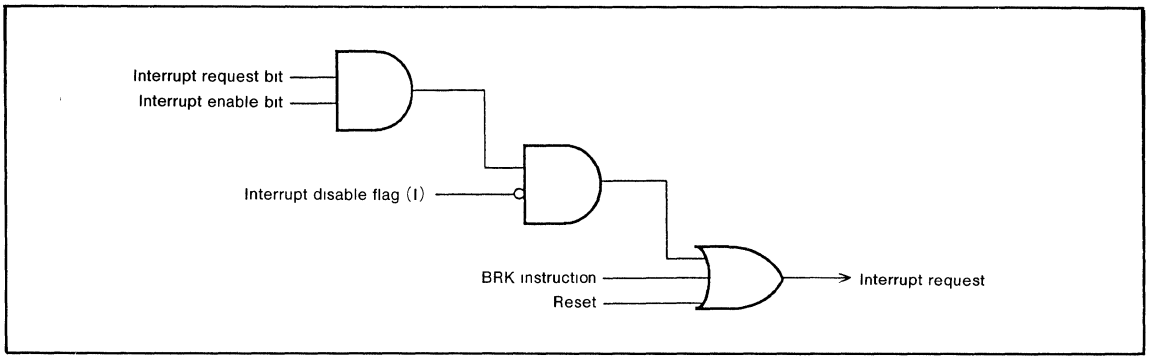


Fig. 6 Interrupt control

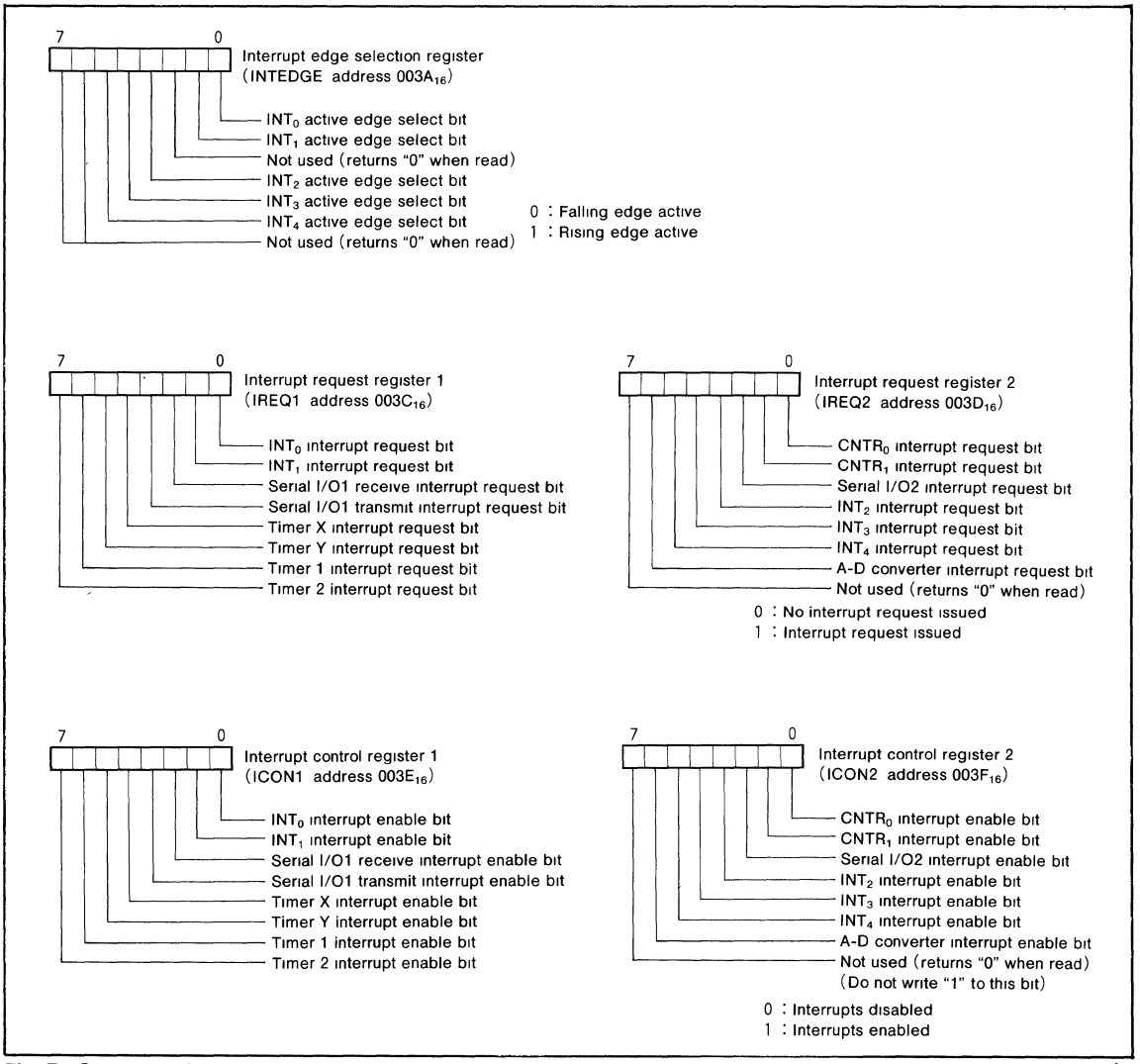


Fig. 7 Structure of interrupt-related registers

TIMERS

Microcomputers of the M3806x group have 4 timers: timer X, timer Y, timer 1, and timer 2.

The timers count down. Once a timer reaches 00_{16}, the next count pulse reloads the contents of the corresponding timer latch into the timer, and sets the corresponding interrupt request bit to 1.

The divide ratio of each timer or prescaler is given by $1/(n+1)$, where n is the value in the corresponding timer or prescaler latch.

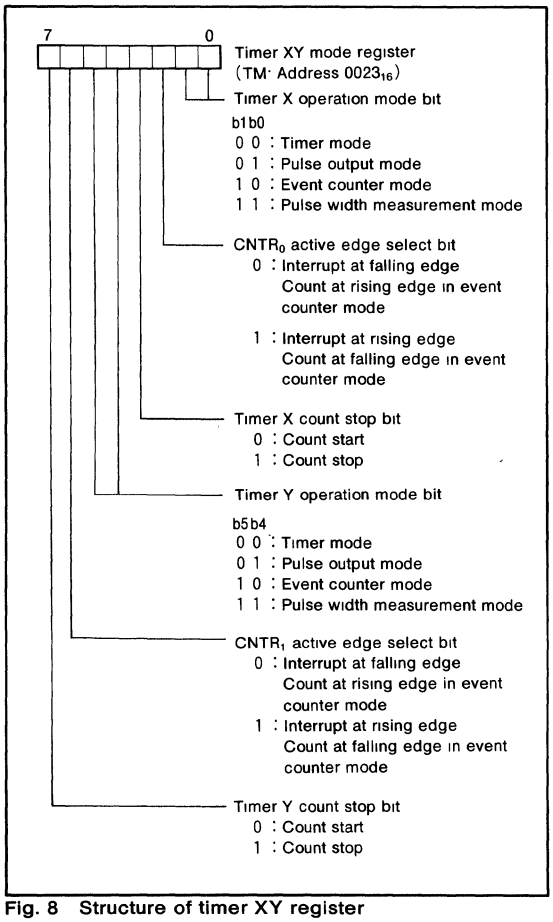


Fig. 8 Structure of timer XY register

Timer 1 and Timer 2

The count source of prescaler 12 is the oscillation frequency divided by 16. The output of prescaler 12 is counted by timer 1 and timer 2, and a timer overflow sets the interrupt request bit.

Timer X and Timer Y

Timer X and Timer Y can each be set to operate in one of four operating modes by setting the timer XY mode register.

1. Timer Mode
   In timer mode, the timer counts a signal that is the oscillation frequency divided by 16.
2. Pulse Output Mode
   Timer X (or timer Y) counts a signal which is the oscillation frequency divided by 16. Whenever the contents of the timer reach "0", the signal output from the $CNTR_0$ (or $CNTR_1$) pin is inverted. If the $CNTR_0$ (or $CNTR_1$) active edge select bit is "0", output begins at "H". If it is "1", output starts at "L" When using a timer in this mode, set the corresponding port $P5_4$ (or port $P5_5$) direction register to output mode.
3. Event Counter Mode
   Operation in event counter mode is the same as in timer mode, except the timer counts signals input through the $CNTR_0$ or $CNTR_1$ pin.
4. Pulse Width Measurement Mode
   If the $CNTR_0$ (or $CNTR_1$) active edge select bit is "0", the timer counts at the oscillation frequency divided by 16 while the $CNTR_0$ (or $CNTR_1$) pin is at "H". If the $CNTR_0$ (or $CNTR_1$) active edge select bit is "1", the count continues during the time that the $CNTR_0$ (or $CNTR_1$) pin is at "L".

In all of these modes, the count can be stopped by setting the timer X (timer Y) count stop bit to "1". Every time a timer overflows, the corresponding interrupt request bit is set.

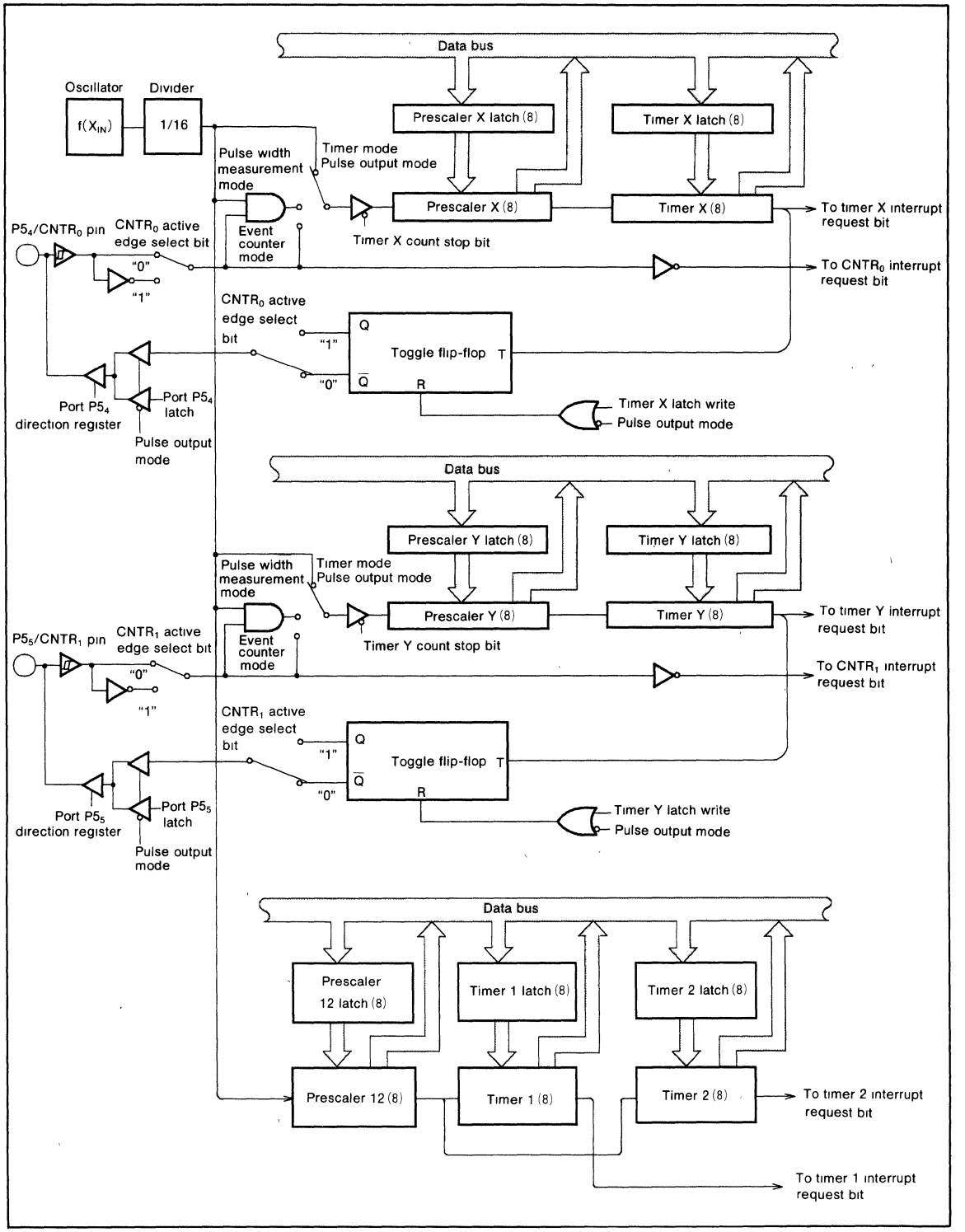


Fig. 9 Block diagram of timer X, timer Y, timer 1, and timer 2

SERIAL I/O1

Serial I/O1 can be used as either clock synchronous or asynchronous (UART) serial I/O. A dedicated timer is also provided for baud rate generation.

(1) Clock Synchronous Serial I/O

Clock synchronous serial I/O1 mode can be selected by setting the mode select bit of the serial I/O1 control register to "1"

For clock-synchronized serial I/O1, the transmitter and the receiver must use the same clock. If an internal clock is used, transfer is started by a write signal to the transmit or receive buffer.

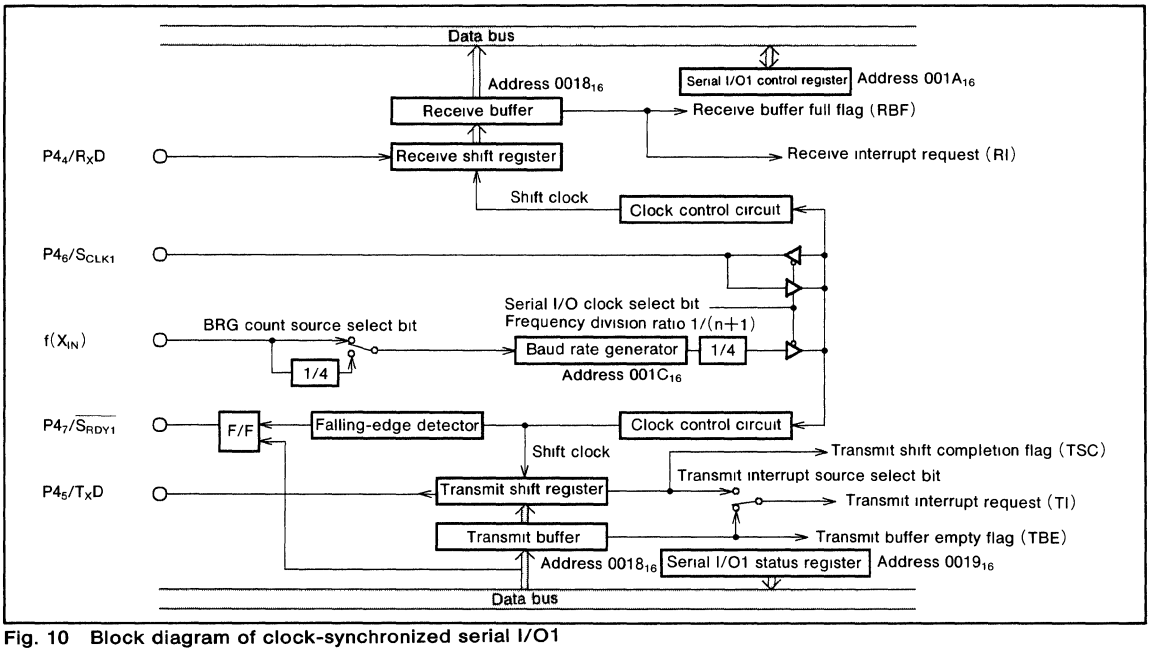
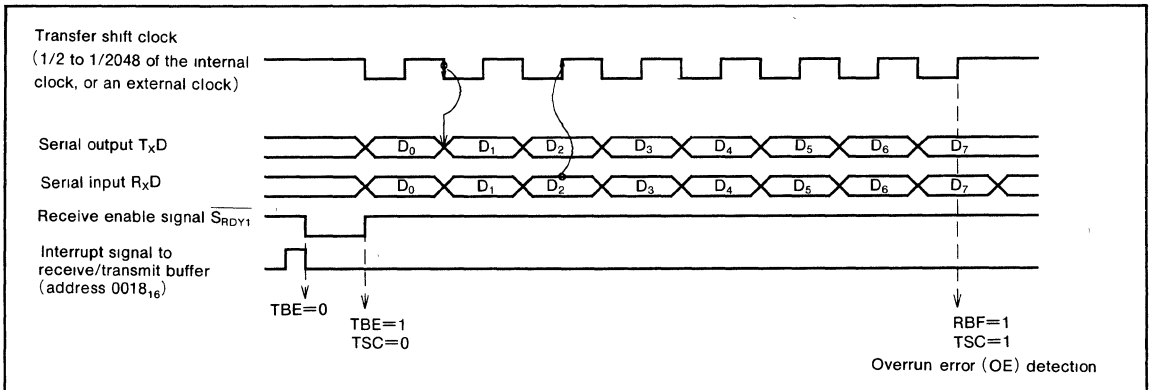


Fig. 10 Block diagram of clock-synchronized serial I/O1



Note 1 : The transmit interrupt (TI) can be selected to occur either when the transmit buffer has emptied (TBE=1) or after the transmit shift operation has ended (TSC=1), by setting the transmit interrupt source select bit (TIC) of the serial I/O1 control register

2 : If data is written to the transfer buffer when TSC=0, the transmit clock is generated continuously and serial data is output continuously from the TxD pin

3 : The receive interrupt (RI) is set when the receive buffer full (RBF) flag becomes "1"

Fig. 11 Operation of clock-synchronized serial I/O1 function

(2) Asynchronous serial I/O (UART) mode

Clock asynchronous serial I/O mode (UART) can be selected by clearing the serial I/O mode select bit of the serial I/O control register to "0".

Eight serial data transfer formats can be selected, and the transfer formats used by a transmitter and receiver must be identical.

The transmit and receive shift registers each have a buffer, but the two buffers have the same address in memory. Since the shift register cannot be written to or read from directly, transmit data is written to the transmit buffer, and receive data is read from the receive buffer. The transmit buffer can also hold the next data to be transmitted, and the receive buffer can hold a character while the next character is being received.

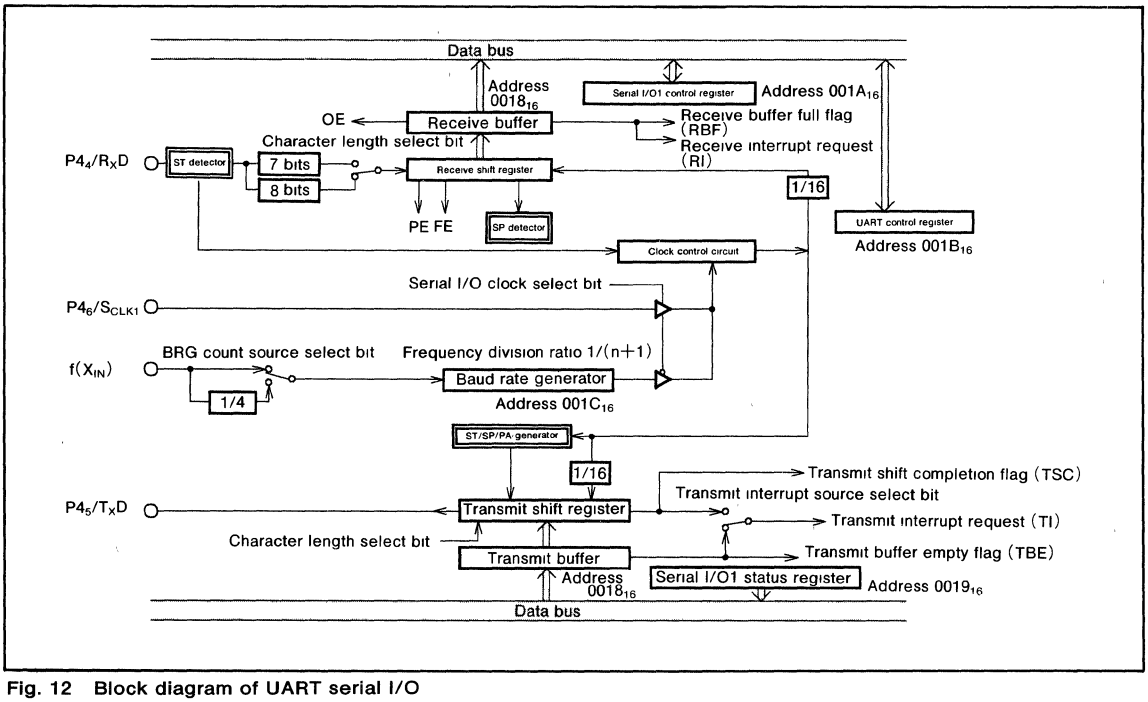
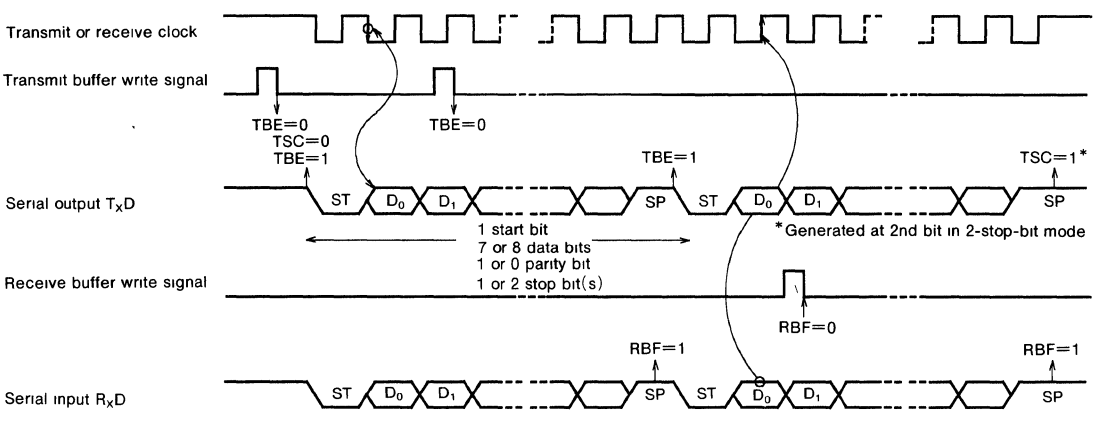


Fig. 12 Block diagram of UART serial I/O



Note 1 : Error flag detection occurs at the same time that the RBF flag becomes "1" (at 1st stop bit, during reception)
2 : The transmit interrupt (TI) can be selected to occur when either the TBE or TSC flag becomes "1", depending on the setting of the transmit interrupt source select bit (TIC) of the serial I/O control register
3 : The receive interrupt (RI) is set when the RBF flag becomes "1"

Fig. 13 Operation of UART serial I/O function

[Serial I/O Control Register (SIO1CON) $001A_{16}$]

The serial I/O control register contains eight control bits for the serial I/O function.

[UART Control Register (UARTCON) $001B_{16}$]

The UART control register consists of four control bits (bits 0 to 3) which are valid when asynchronous serial I/O is selected and set the data format of an data transfer. One bit in this register (bit 4) is always valid and sets the output structure of the $P4_5/T_XD$ pin.

[Serial I/O1 Status Register (SIO1STS) 0019_{16}]

The read-only serial I/O1 status register consists of seven flags (bits 0 to 6) which indicate the operating status of the serial I/O function and various errors.

Three of the flags (bits 4 to 6) are valid only in UART mode.

The receive buffer full flag (bit 1) is cleared to "0" when the receive buffer is read.

If there is an error, it is detected at the same time that data is transferred from the receive shift register to the receive buffer, and the receive buffer full flag is set. A write to the serial I/O status register clears all the error flags OE, PE, FE, and SE (bit 3 to bit six, respectively). Writing "0" to the serial I/O enable bit SIOE (bit 7 of the Serial I/O Control Register) also clears all the status flags, including the error flags.

All bits of the serial I/O1 status register are initialized to "0" at reset, but if the transmit enable bit (bit 4) of the serial I/O control register has been set to "1", the transmitter shift completion flag (bit 2) and the transmitter buffer empty flag (bit 0) become "1".

[Transmit Buffer/Receive Buffer (TB/RB) 0018_{16}]

The transmit buffer and the receive buffer are located at the same address. The transmit buffer is write-only and the receive buffer is read-only. If a character bit length is 7 bits, the MSB of data stored in the receive buffer is "0".

[Baud Rate Generator (BRG) $001C_{16}$]

The baud rate generator determines the baud rate for serial transfer.

The baud rate generator divides the frequency of the count source by $1/(n+1)$, where n is the value written to the Baud Rate Generator

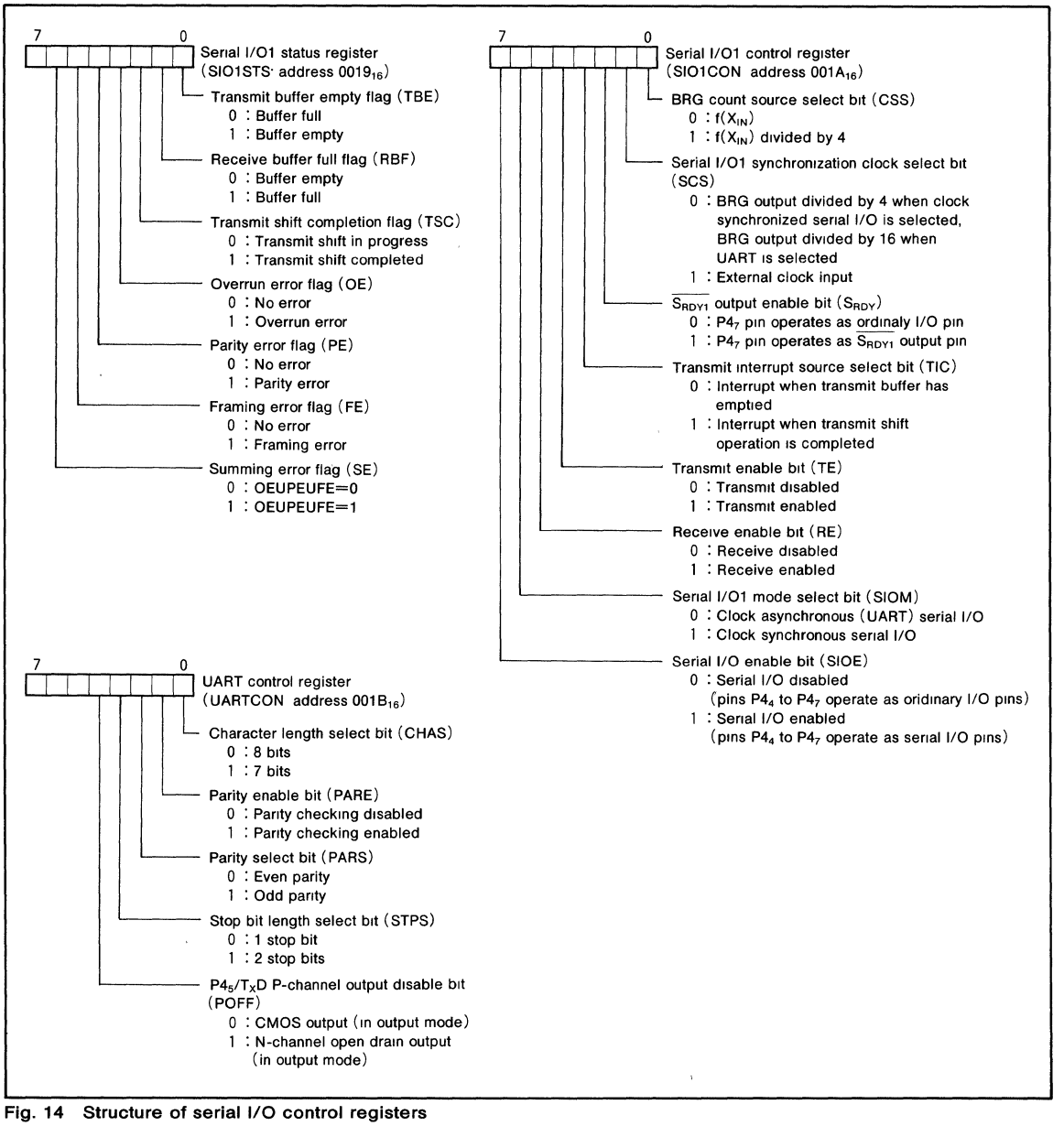


Fig. 14 Structure of serial I/O control registers

SERIAL I/O2

The serial I/O2 function can be used only for clock synchronous serial I/O.

For clock synchronous serial I/O the transmitter and the receiver must use the same clock. If the internal clock is used, transfer is started by a write signal to the serial I/O2 register.

Serial I/O2 Control Register (SIO2CON) $001D_{16}$

The serial I/O2 control register contains seven bits which control various serial I/O functions.

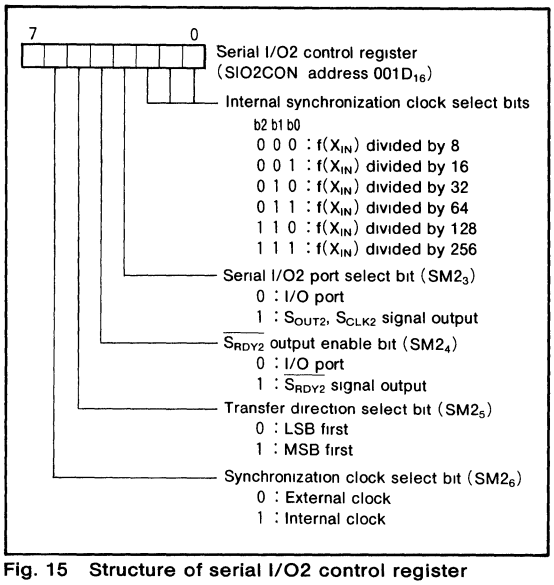


Fig. 15 Structure of serial I/O2 control register

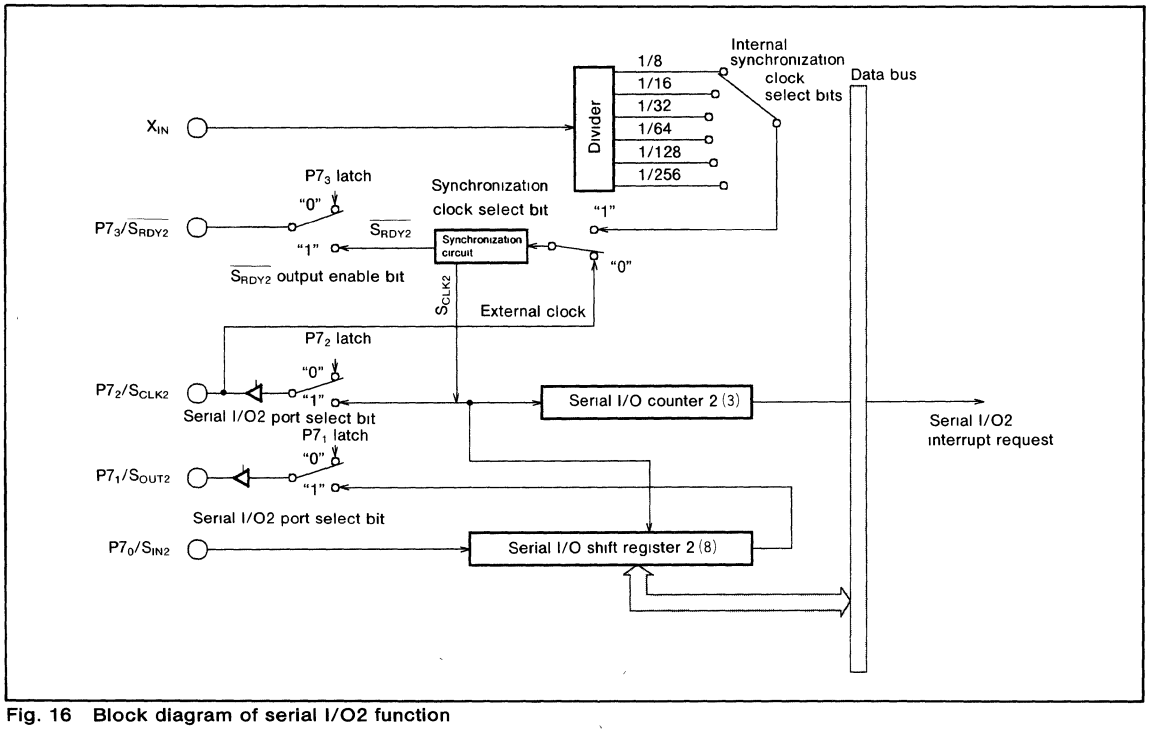
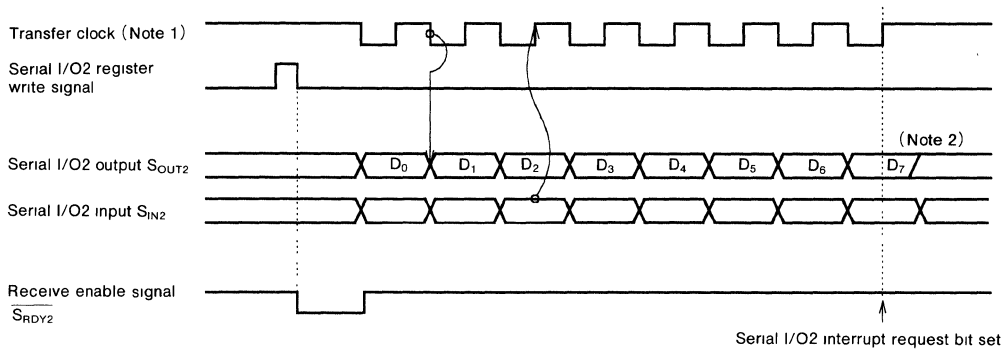


Fig. 16 Block diagram of serial I/O2 function



Note 1. When the internal clock is selected as the transfer clock, the divide ratio can be selected by setting bits 0 to 2 of the serial I/O2 control register
2. When the internal clock is selected as the transfer clock, the S_{OUT2} pin goes to high impedance after transfer completion

Fig. 17 Timing of serial I/O2 function

A-D CONVERTER

The functional blocks of the A-D converter are described below.

[A-D Conversion Register]

The A-D conversion register is a read-only register which contains the result of an A-D conversion. This register should not be read during an A-D conversion.

[AD/DA Control Register]

The AD/DA control register controls the A-D conversion process. Bits 0 to 2 select a specific analog input pin. Bit 3 signals the completion of an A-D conversion. The value of this bit remains at "0" during an A-D conversion, and changes to "1" when an A-D conversion ends. Writing "0" to this bit starts the A-D conversion. Bits 6 and 7 are used to control the output of the D-A converter.

[Comparison Voltage Generator]

The comparison voltage generator divides the voltage between AV_{SS} and V_{REF} into 256 steps for comparison to the analog input.

[Channel Selector]

The channel selector selects one of the ports $P6_0/AN_0$ to $P6_7/AN_7$, and inputs the voltage to the comparator.

[Comparator and Control Circuit]

The comparator and control circuit compares an analog input voltage with the comparison voltage, then stores the result in the A-D conversion register. When an A-D conversion is complete, the control circuit sets the A-D conversion completion bit and the A-D interrupt request bit to "1".

The comparator contains a capacitor, so $f(X_{IN})$ should be at least 500kHz during an A-D conversion.

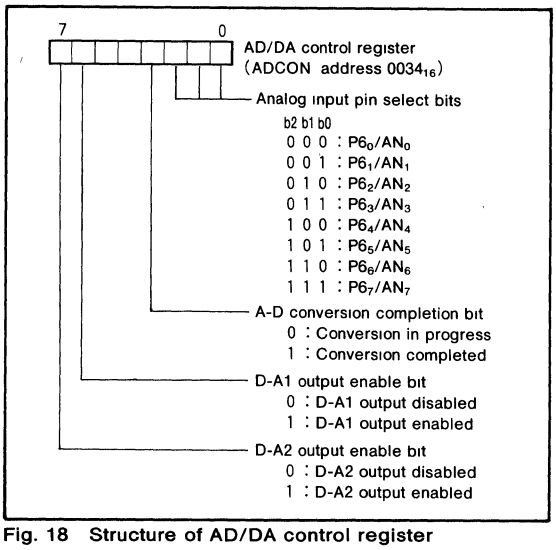


Fig. 18 Structure of AD/DA control register

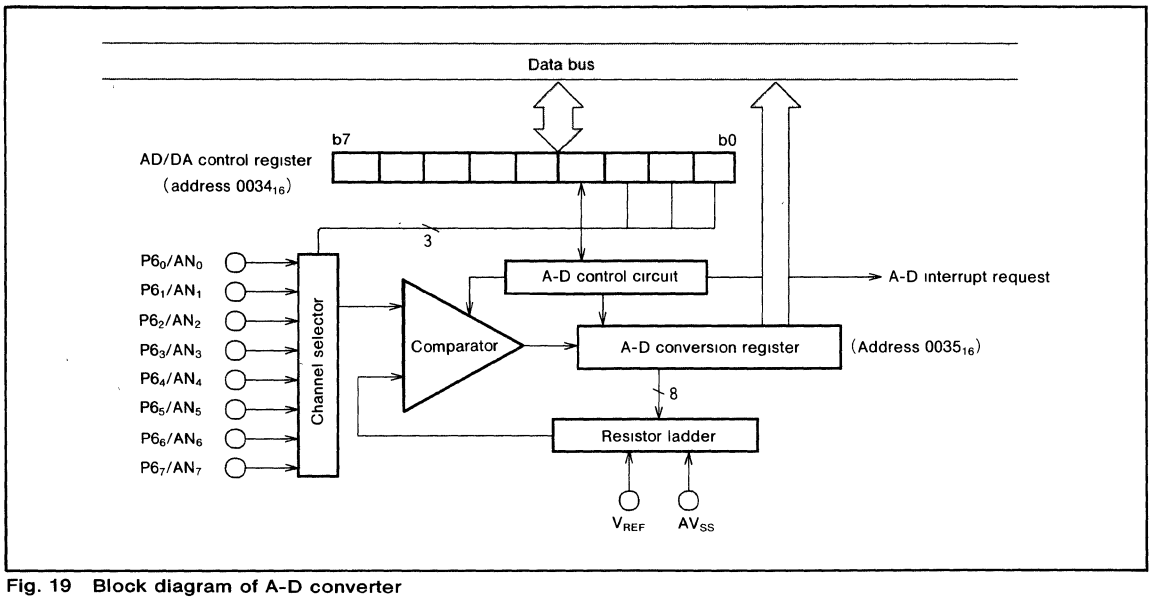


Fig. 19 Block diagram of A-D converter

D-A CONVERTER

Microcomputers of the M3806x group have two internal D-A converters (D-A1 and D-A2) with 8-bit resolutions.

The D-A converter outputs a voltage corresponding to the value in the D-A conversion register. The voltage is output from the DA_1 or DA_2 pin by setting the D-A output enable bit to "1".

When using the D-A converter,. the corresponding port direction register bit ($DA_1/P5_6$ or $DA_2/P5_7$) should be set to "0" (input status).

The output analog voltage V is determined by the value n (base 10) in the D-A conversion register as follows:

$V=V_{REF} \times n/256$ (n=0 to 255)

Where V_{REF} is the reference voltage.

At reset, the D-A conversion registers are cleared to "00", the D-A output enable bits are cleared to "0", and the $P5_6/DA_1$ and $P5_7/DA_2$ pins are set to input (high impedance). The D-A output is not buffered, so the user must supply an external buffer when driving a low-impedance load.

Set V_{CC} to at least 4.0V, when using the D-A converter.

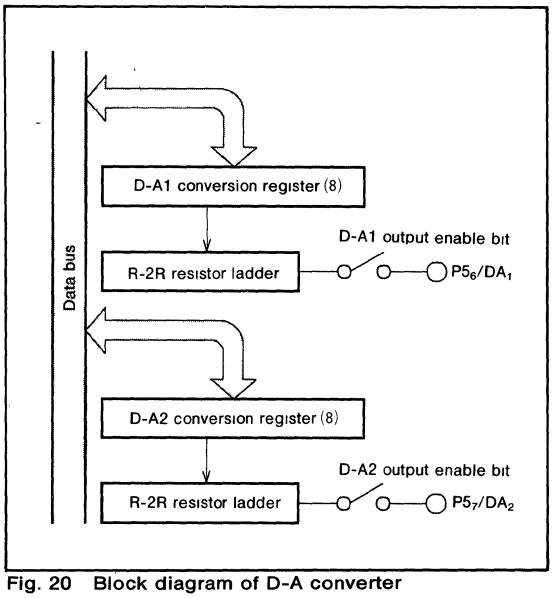


Fig. 20 Block diagram of D-A converter

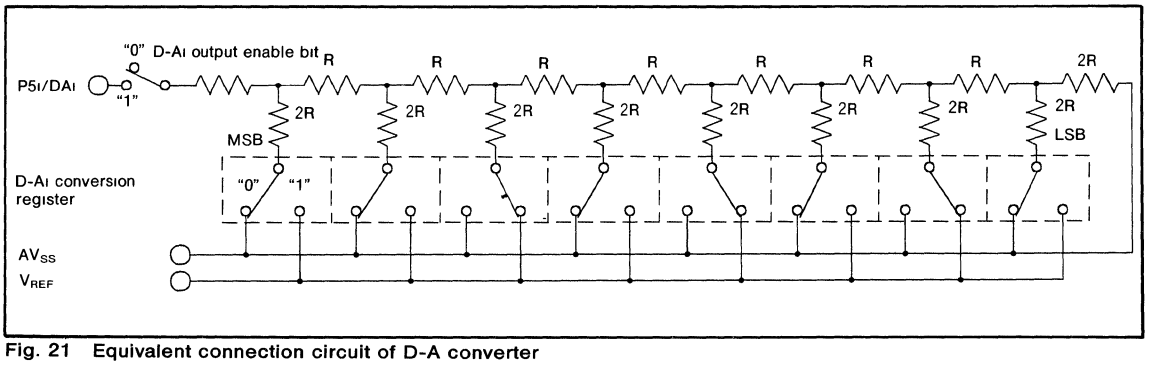


Fig. 21 Equivalent connection circuit of D-A converter

MITSUBISHI ELECTRIC

RESET CIRCUIT

A microcomputer in the M3806x group is reset if the $\overline{\text{RESET}}$ pin is held at a "L" level for at least 2μs then is returned to a "H" level (the power supply voltage should be between 4.0V and 5.5V). In order to give the X_{IN} clock time to stabilize, internal operation does not begin until after 8 to 12 X_{IN} clock cycles are complete. After the reset is completed, the program starts from the address contained in address $FFFD_{16}$ (upper byte) and address $FFFC_{16}$ (lower byte).
Make sure that the reset input voltage is no more than 0.8V for a power supply voltage of 4.0V.

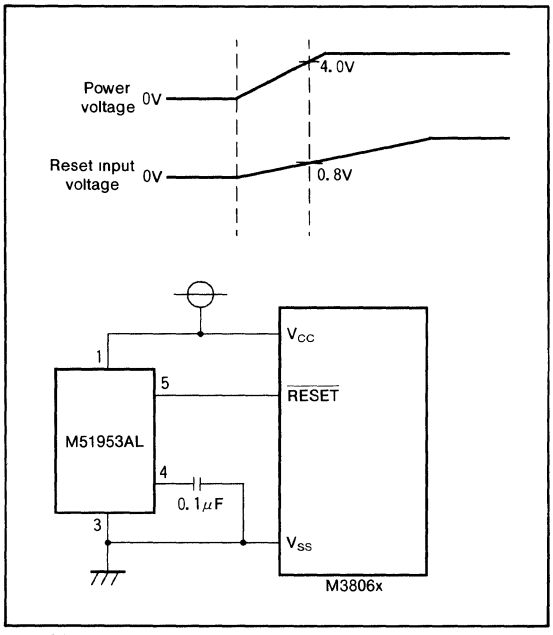


Fig. 22 Example of reset circuit

	Address	Register contents
(1) Port P0 direction register	$(0001_{16})\cdots$	00_{16}
(2) Port P1 direction register	$(0003_{16})\cdots$	00_{16}
(3) Port P2 direction register	$(0005_{16})\cdots$	00_{16}
(4) Port P3 direction register	$(0007_{16})\cdots$	00_{16}
(5) Port P4 direction register	$(0009_{16})\cdots$	00_{16}
(6) Port P5 direction register	$(000B_{16})\cdots$	00_{16}
(7) Port P6 direction register	$(000D_{16})\cdots$	00_{16}
(8) Port P7 direction register	$(000F_{16})\cdots$	00_{16}
(9) Port P8 direction register	$(0011_{16})\cdots$	00_{16}
(10) Serial I/O1 status register	$(0019_{16})\cdots$	1 0 0 0 0 0 0 0
(11) Serial I/O1 control register	$(001A_{16})\cdots$	00_{16}
(12) UART control register	$(001B_{16})\cdots$	1 1 1 0 0 0 0 0
(13) Serial I/O2 control register	$(001D_{16})\cdots$	00_{16}
(14) Prescaler 12	$(0020_{16})\cdots$	FF_{16}
(15) Timer 1	$(0021_{16})\cdots$	01_{16}
(16) Timer 2	$(0022_{16})\cdots$	FF_{16}
(17) Timer XY mode register	$(0023_{16})\cdots$	00_{16}
(18) Prescaler X	$(0024_{16})\cdots$	FF_{16}
(19) Timer X	$(0025_{16})\cdots$	FF_{16}
(20) Prescaler Y	$(0026_{16})\cdots$	FF_{16}
(21) Timer Y	$(0027_{16})\cdots$	FF_{16}
(22) AD/DA control register	$(0034_{16})\cdots$	0 0 0 0 1 0 0 0
(23) D-A1 conversion register	$(0036_{16})\cdots$	00_{16}
(24) D-A2 conversion register	$(0037_{16})\cdots$	00_{16}
(25) Interrupt edge selection register	$(003A_{16})\cdots$	00_{16}
(26) CPU mode register	$(003B_{16})\cdots$	0 0 0 0 0 0 ※ 0
(27) Interrupt control register 1	$(003E_{16})\cdots$	00_{16}
(28) Interrupt control register 2	$(003F_{16})\cdots$	00_{16}
(29) Processor status register	(PS)	X X X X X 1 X X
(30) Program counter	(PC_H)	Contents of address $FFFD_{16}$
	(PC_L)	Contents of address $FFFC_{16}$

Note : X : Undefined
※ : The initial values of CM_1 are determined by the level at the CNV_{SS} pin
The contents of all other registers and RAM are undefined after a reset, so they must be initialized by software

Fig. 23 Internal status of microcomputer after reset

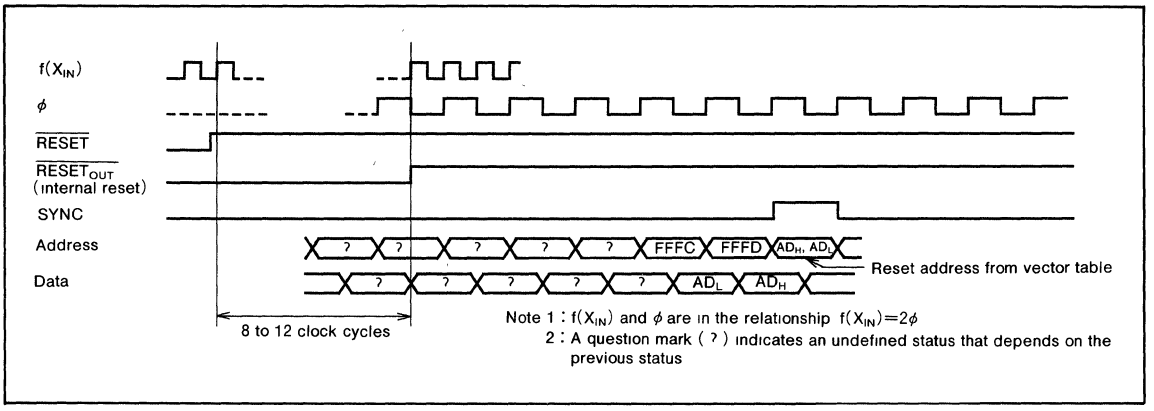


Fig. 24 Timing of reset

CLOCK GENERATION CIRCUIT

An oscillation circuit can be created by connecting a resonator between X_{IN} and X_{OUT}. When using an external clock signal, input the clock signal to the X_{IN} pin and leave the X_{OUT} pin open.

Oscillation Control

(1) Stop Mode

If the STP instruction is executed, oscillation stops with the internal clock ϕ at "H". Timer 1 is set to "FF_{16}" and prescaler 12 is set to "01_{16}".

Oscillation restarts when an external interrupt is received, but the internal clock ϕ remains at "H" until timer 1 overflows.

This allows time for the clock circuit oscillation to stabilize. If oscillation is restarted by a reset, no wait time is generated, so keep the $\overline{RESET}$ pin at "L" level until oscillation has stabilized.

(2) Wait Mode

If the WIT instruction is executed, the internal clock ϕ stops at a "H" level, but the oscillator itself does not stop. The internal clock restarts if a reset occurs or when an interrupt is received.

Since the oscillator does not stop, normal operation can be started immediately after the clock is restarted.

To ensure that interrupts will be received to release the STP or WIT state, interrupt enable bits must be set to "1" before the STP or WIT instruction is executed.

When the STP status is released, prescaler 12 and timer 1 will start counting and reset will not be released until timer 1 overflows, so set the timer 1 interrupt enable bit to "0" before the STP instruction is executed.

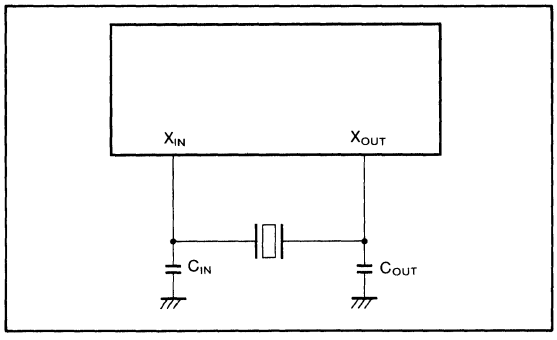


Fig. 25 Ceramic resonator circuit

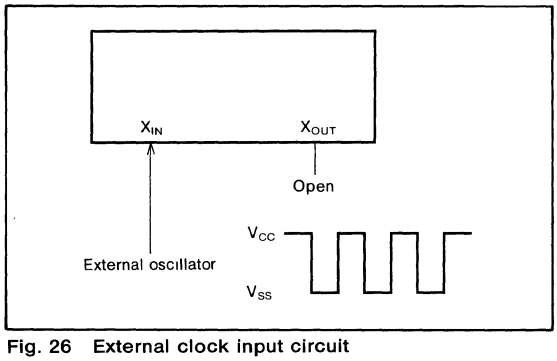


Fig. 26 External clock input circuit

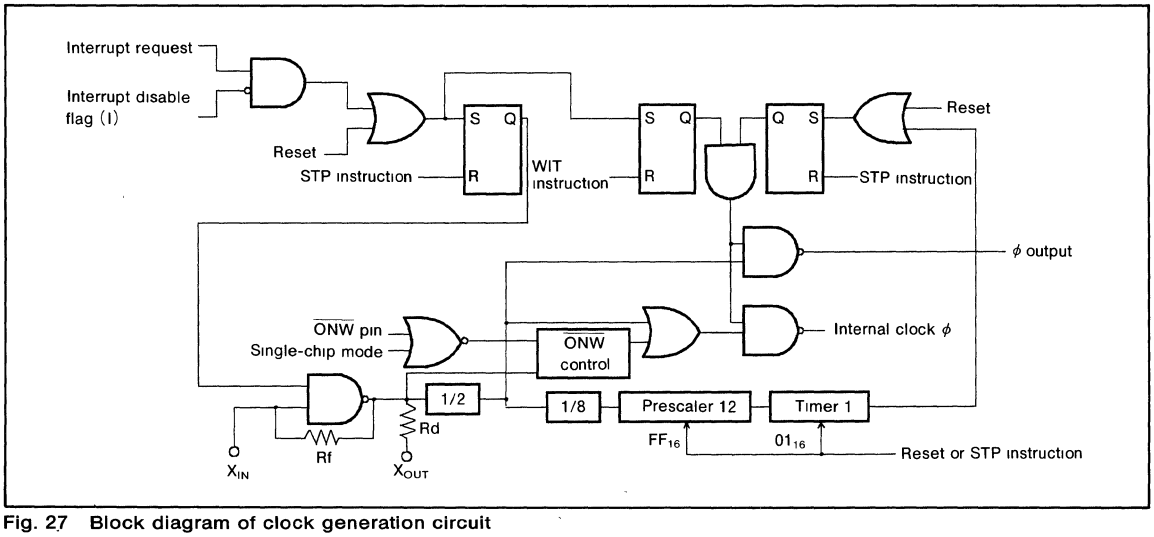


Fig. 27 Block diagram of clock generation circuit

PROCESSOR MODES

Single-chip mode, memory expansion mode, and microprocessor mode can be selected by changing the contents of the processor mode bits CM_0 and CM_1 (bits 0 and 1 of address $003B_{16}$). In memory expansion mode and microprocessor mode, memory can be expanded externally through ports P0 to P3. In these modes, ports P0 to P3 lose their I/O port functions and become bus pins.

Table 2 Functions of ports in memory expansion mode and microprocessor mode

Port Name	Function
Port P0	Outputs lower byte of address.
Port P1	Outputs upper byte of address
Port P2	Operates as I/O pins for data D_7 to D_0 (including instruction codes)
Port P3	$P3_0$ and $P3_1$ function only as output pins (except that the port latch cannot be read) $P3_2$ is the $\overline{ONW}$ input pin. $P3_3$ is the $\overline{RESET}_{OUT}$ output pin (Note) $P3_4$ is the ϕ output pin. $P3_5$ is the SYNC output pin. $P3_6$ is the $\overline{WR}$ output pin, and $P3_7$ is the $\overline{RD}$ output pin

Note : If CNV_{SS} is connected to V_{SS}, the microcomputer goes to single-chip mode after a reset, so this pin cannot be used as the $\overline{RESET}_{OUT}$ output pin

- **Single-Chip Mode**
  Select this mode by resetting the microcomputer with CNV_{SS} connected to V_{SS}.
- **Memory Expansion Mode**
  Select this mode by setting the processor mode bits to "01" in software with CNV_{SS} connected to V_{SS}. This mode enables external memory expansion while maintaining the validity of the internal ROM. Internal ROM will take precedence over external memory if addresses conflict.
- **Microprocessor Mode**
  Select this mode by resetting the microcomputer with CNV_{SS} connected to V_{CC}, or by setting the processor mode bits to "10" in software with CNV_{SS} connected to V_{SS}. In microprocessor mode, the internal ROM is no longer valid and external memory must be used.

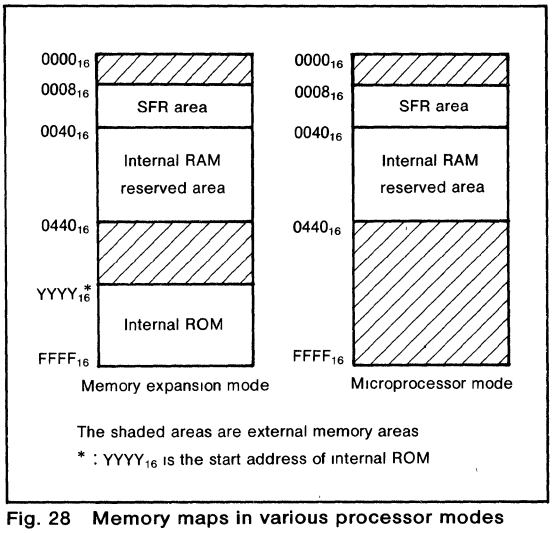


Fig. 28 Memory maps in various processor modes

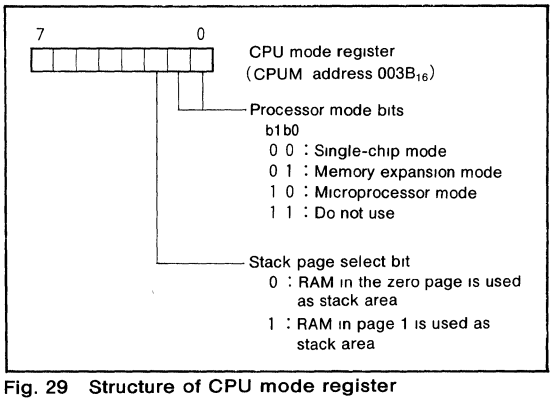
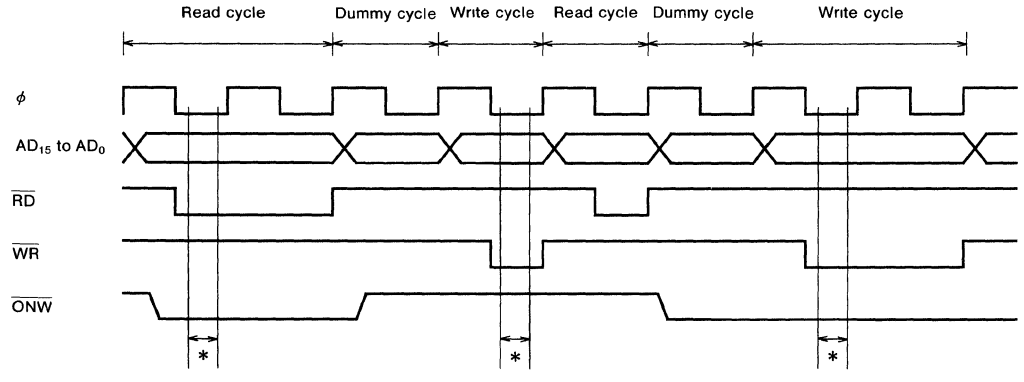


Fig. 29 Structure of CPU mode register

Bus Control with Memory Expansion

Microcomputers of the M3806x group have a built-in $\overline{ONW}$ function to facilitate access to extra memory and I/O functions in memory expansion mode or microprocessor mode.

If an "L" level signal is input to the $\overline{ONW}$ pin when the CPU is in a read or write state, the corresponding read or write cycle is extended by one cycle of ϕ. During this extended period, the $\overline{RD}$ or $\overline{WR}$ signal remains at "L". This extension period is valid only for writing to and reading from addresses 0000_{16} to 0007_{16} and 0440_{16} to $FFFF_{16}$, and only read and write cycles are extended.



* : Period during which $\overline{ONW}$ input signal is received
During this period, the $\overline{ONW}$ signal must be fixed at either "H" or "L" At all other times, the input level of the $\overline{ONW}$ signal has no affect on operations.
The bus cycles is not extended for an address in the area 0008_{16} to $043F_{16}$, regardless of whether the $\overline{ONW}$ signal is received

Fig. 30 $\overline{ONW}$ function timing

NOTES ON PROGRAMMING

Processor Status Register

The contents of the processor status register (PS) after a reset are undefined, except for the interrupt disable flag (I) which is "1". Therefore, flags that affect program execution must be initialized after a reset.
In particular, it is essential to initialize the T and D flags because of their effect on calculations.

Interrupts

The contents of the interrupt request bits do not change immediately after they have been written. After writing to an interrupt request register, execute at least one instruction before performing a BBC or BBS instruction.

Decimal Calculations

To calculate in decimal notation, set the decimal mode flag (D) to "1", then execute a ADC or SBC instruction. Only the ADC and SBC instructions yield proper decimal results. After executing an ADC or SBC instruction, execute at least one instruction before executing a SEC, CLC, or CLD instruction.

In decimal mode, the values of the negative (N), overflow (V), and zero (Z) flags are invalid.
The carry flag can be used to indicate whether a carry or borrow has occurred, but must be initialized before each calculation. Clear the carry flag before an ADC and set the flag before an SBC.

Timers

If a value n (between 0 and 255) is written to a timer latch, the frequency division ratio is 1/(n+1).

Multiplication and Division Instructions

The MUL and DIV instructions do not affect the T and D flags.
The execution of these instructions does not change the contents of the processor status register.

Ports

The contents of the port direction registers cannot be read. Programs can not use the value of a direction register as an index, or bit-test a direction register (BBC or BBS), or perform a read-modify-write instruction such as ROR, CLB, or SEB. Use instructions such as LDM and STA to set the port direction registers.

Serial I/O

In clock synchronous serial I/O, if the receive side is using an external clock and it is to output the $\overline{S_{RDY1}}$ signal, set the transmit enable bit, the receive enable bit, and the $\overline{S_{RDY1}}$ output enable bit to "1".
Serial I/O1 continues to output the final bit from the T_XD pin after transmission is completed. The S_{OUT2} pin from serial I/O2 goes to high impedance after transmission is completed

A-D Converter

The comparator uses internal capacitors whose charge will be lost if the clock frequency is too low.
Make sure that $f(X_{IN})$ is at least 500kHz during an A-D conversion. (If the $\overline{ONW}$ pin has been set to "L", the A-D conversion will take twice as long to match the longer bus cycle, and so $f(X_{IN})$ must be at least 1MHz.)
Do not execute the STP or WIT instruction during an A-D conversion.

D-A Converter

The accuracy of the D-A converter becomes poor rapidly under the V_{CC} =4.0V or less condition. So set V_{CC} to at least 4.0V, when using the D-A converter.

Instruction Execution Time

The instruction execution time is obtained by multiplying the frequency of the internal clock ϕ by the number of cycles needed to execute an instruction.
The number of cycles required to execute an instruction is shown in the list of machine instructions.
The frequency of the internal clock ϕ is half of the X_{IN} frequency.
When the $\overline{ONW}$ function is used in modes other than single-chip mode, the frequency of the internal clock ϕ may be one fourth the X_{IN} frequency.

DATA REQUIRED FOR MASK ORDERS

The following are necessary when ordering a mask ROM production:

1. Mask ROM Order Confirmation Form
2. Mask Specification Form
3. Data to be written to ROM, in EPROM form (three identical copies)

ROM Writing Method

The built-in PROM of the blank one-time programmable version and built-in EPROM version can be read from and written to with an normal EPROM writer using a special write adapter.

Package	Name of Write Adapter
80P6N	PCA4738F-80
80P6S	PCA4738G-80
80D0	PCA4738L-80

The PROM of the blank one-time programmable version is not tested or screened after assembly. To ensure proper operation after writing, the procedure shown in Figure 31 is recommended to verify programming.

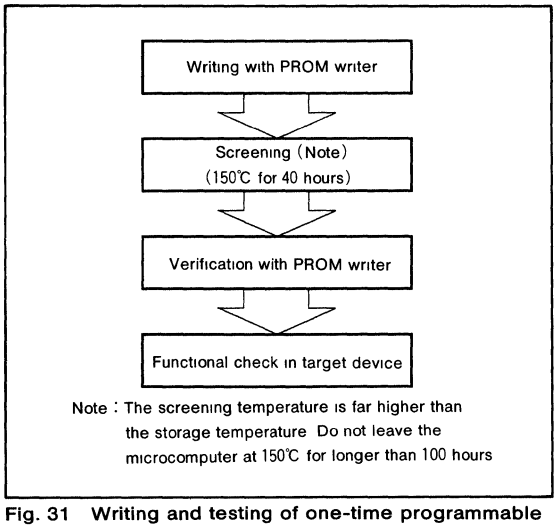


Fig. 31 Writing and testing of one-time programmable version

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Conditions	Ratings	Unit
V_{CC}	Supply voltage	All voltages measured with reference to the V_{SS} pin, output transistors isolated	−0.3 to 7.0	V
V_I	Input voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$, V_{REF}		−0.3 to V_{CC}+0.3	V
V_I	Input voltage $\overline{RESET}$, X_{IN}		−0.3 to V_{CC}+0.3	V
V_I	Input voltage CNV_{SS}		−0.3 to 13	V
V_O	Output voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$, X_{OUT}		−0.3 to V_{CC}+0.3	V
P_d	Power dissipation	T_a = 25°C	500	mW
T_{opr}	Operating temperature		−20 to 85	°C
Tstg	Storage temperature		−40 to 125	°C

RECOMMENDED OPERATING CONDITIONS (V_{CC} = 3.0 to 5.5V, T_a = −20 to 85°C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max	
V_{CC}	Supply voltage ($f(X_{IN})$≦2MHz)	3.0	5.0	5.5	V
	Supply voltage ($f(X_{IN})$>2MHz)	4.0	5.0	5.5	
	Supply voltage (when D-A converter is used)	4.0	5.0	5.5	
V_{SS}	Supply voltage		0		V
V_{REF}	Analog reference voltage (when A-D converter is used)	2.0		V_{CC}	V
	Analog reference voltage (when D-A converter is used)	4.0		V_{CC}	
AV_{SS}	Analog power voltage		0		V
V_{IA}	Analog input voltage AN_0-AN_7	AV_{SS}		V_{CC}	V
V_{IH}	"H" input voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$	0.8V_{CC}		V_{CC}	V
V_{IH}	"H" input voltage $\overline{RESET}$, X_{IN}, CNV_{SS}	0.8V_{CC}		V_{CC}	V
V_{IL}	"L" input voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$	0		0.2V_{CC}	V
V_{IL}	"L" input voltage $\overline{RESET}$	0		0.2V_{CC}	V
V_{IL}	"L" input voltage X_{IN}	0		0.16V_{CC}	V
V_{IL}	"L" input voltage CNV_{SS}	0		0.2V_{CC}	V
$\Sigma I_{OH(peak)}$	"H" total peak output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P8_0$-$P8_7$ (Note 1)			−80	mA
$\Sigma I_{OH(peak)}$	"H" total peak output current $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$ (Note 1)			−80	mA
$\Sigma I_{OL(peak)}$	"L" total peak output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P8_0$-$P8_7$ (Note 1)			80	mA
$\Sigma I_{OL(peak)}$	"L" total peak output current $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$ (Note 1)			80	mA
$\Sigma I_{OH(avg)}$	"H" total average output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P8_0$-$P8_7$ (Note 1)			−40	mA
$\Sigma I_{OH(avg)}$	"H" total average output current $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$ (Note 1)			−40	mA
$\Sigma I_{OL(avg)}$	"L" total average output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P8_0$-$P8_7$ (Note 1)			40	mA
$\Sigma I_{OL(avg)}$	"L" total average output current $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$ (Note 1)			40	mA
$I_{OH(peak)}$	"H" peak output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P8_0$-$P8_7$ (Note 2)			−10	mA
$I_{OL(peak)}$	"L" peak output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$ (Note 2)			10	mA
$I_{OH(avg)}$	"H" average output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P8_0$-$P8_7$ (Note 3)			−5	mA
$I_{OL(avg)}$	"L" average output current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$ (Note 3)			5	mA
$f(X_{IN})$	Internal clock oscillation frequency (V_{CC}=4.0~5.5V)			8	MHz
	Internal clock oscillation frequency (V_{CC}=3.0~5.5V)			2	

Note 1 The total output current is the sum of all the currents flowing through all the applicable ports The total average current is an average value measured over 100ms The total peak current is the peak value of all the currents
2 The peak output current is the peak current flowing in each port
3 The average output current I_{OL} (avg), I_{OH} (avg) in an average value measured over 100ms

ELECTRICAL CHARACTERISTICS (V_{CC} = 3.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85℃, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits Min.	Limits Typ.	Limits Max	Unit
V_{OH}	"H" output voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P8_0$-$P8_7$ (Note 1)	I_{OH}=−10mA, V_{CC}=4.0~5.5V	V_{CC}−2.0			V
		I_{OH}=−1.0mA, V_{CC}=3.0~5.5V	V_{CC}−1.0			
V_{OL}	"L" output voltage $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$	I_{OL}=10mA, V_{CC}=4.0~5.5V			2.0	V
		I_{OL}=1.0mA, V_{CC}=3.0~5.5V			1.0	
V_{T+}−V_{T-}	Hysteresis $CNTR_0$, $CNTR_1$, INT_0-INT_4			0.4		V
V_{T+}−V_{T-}	Hysteresis R_XD, S_{CLK1}, S_{IN2}, S_{CLK2}			0.5		V
V_{T+}−V_{T-}	Hysteresis $\overline{RESET}$			0.5		V
I_{IH}	"H" input current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$	V_I=V_{CC}			5.0	μA
I_{IH}	"H" input current $\overline{RESET}$, CNV_{SS}	V_I=V_{CC}			5.0	μA
I_{IH}	"H" input current X_{IN}	V_I=V_{CC}		4		μA
I_{IL}	"L" input current $P0_0$-$P0_7$, $P1_0$-$P1_7$, $P2_0$-$P2_7$, $P3_0$-$P3_7$, $P4_0$-$P4_7$, $P5_0$-$P5_7$, $P6_0$-$P6_7$, $P7_0$-$P7_7$, $P8_0$-$P8_7$, $\overline{RESET}$, CNV_{SS}	V_I=V_{SS}			−5.0	μA
I_{IL}	"L" input current X_{IN}	V_I=V_{SS}		−4		μA
V_{RAM}	RAM hold voltage	With clock stopped	2.0		5.5	V
I_{CC}	Supply current	f(X_{IN})=8MHz, V_{CC}=5V		6.4	13	mA
		f(X_{IN})=5MHz, V_{CC}=5V		4	8	
		f(X_{IN})=2MHz, V_{CC}=3V		0.8	2.0	
		When WIT instruction is executed with f(X_{IN})=8MHz, V_{CC}=5V		1.5		
		When WIT instruction is executed with f(X_{IN})=5MHz, V_{CC}=5V		1		
		When WIT instruction is executed with f(X_{IN})=2MHz, V_{CC}=3V		0.2		
		When STP instruction is executed with clock stopped, output transistors isolated, T_a=25℃ (Note 2)		0.1	1	μA
		When STP instruction is executed with clock stopped, output transistors isolated, T_a=85℃ (Note 2)			10	

Note 1 : $P4_5$ is measured when the $P4_5/T_XD$ P-channel output disable bit of the UART control register (bit 4 of address $001B_{16}$) is "0"
2 : With output transistors isolated and A-D converter having completed conversion, and not including current flowing through V_{REF} pin

A-D CONVERTER CHARACTERISTICS

(V_{CC}=3.0 to 5.5V, V_{SS}=AV_{SS}=0V, V_{REF}=2.0V to V_{CC}, T_a=−20 to 85℃, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits Min	Limits Typ	Limits Max	Unit
—	Resolution				8	Bits
—	Absolute accuracy (excluding quantization error)			±1	±2.5	LSB
t_{CONV}	Conversion time				50	t_C (ϕ)
R_{LADDER}	Ladder resistor			35		kΩ
I_{VREF}	Reference power source input current (Note)	V_{REF}=5.0V	50	150	200	μA
$I_{I(AD)}$	A-D port input current			0.5		μA

Note : When D-A conversion registers (addresses 0036_{16} and 0037_{16}) contain "00_{16}"

D-A CONVERTER CHARACTERISTICS

(V_{CC}=4.0 to 5.5V, V_{SS}=AV_{SS}=0V, V_{REF}=4.0V to V_{CC}, T_a=−20 to 85℃, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits Min	Limits Typ	Limits Max	Unit
—	Resolution				8	Bits
—	Absolute accuracy				1.0	%
t_{SU}	Setting time				3	μs
R_O	Output resistor		1	2.5	4	kΩ
I_{VREF}	Reference power source input current (Note)				3.2	mA

Note : Using one D-A converter, with the value in the D-A conversion register of the other D-A converter being "00_{16}", and excluding currents flowing through the A-D resistance ladder

TIMING REQUIREMENTS 1 (V_{CC} =4.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85℃, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max.	
$t_{W(\overline{RESET})}$	Reset input "L" pulse width	2			μs
$t_{C(X_{IN})}$	External clock input cycle time	125			ns
$t_{WH(X_{IN})}$	External clock input "H" pulse width	50			ns
$t_{WL(X_{IN})}$	External clock input "L" pulse width	50			ns
$t_{C(CNTR)}$	$CNTR_0$, $CNTR_1$ input cycle time	200			ns
$t_{WH(CNTR)}$	$CNTR_0$, $CNTR_1$ input "H" pulse width	80			ns
$t_{WH(INT)}$	INT_0 to INT_4 input "H" pulse width	80			ns
$t_{WL(CNTR)}$	$CNTR_0$, $CNTR_1$ input "L" pulse width	80			ns
$t_{WL(INT)}$	INT_0 to INT_4 input "L" pulse width	80			ns
$t_{C(S_{CLK1})}$	Serial I/O1 clock input cycle time (Note)	800			ns
$t_{C(S_{CLK2})}$	Serial I/O2 clock input cycle time	1000			ns
$t_{WH(S_{CLK1})}$	Serial I/O1 clock input "H" pulse width (Note)	370			ns
$t_{WH(S_{CLK2})}$	Serial I/O2 clock input "H" pulse width	400			ns
$t_{WL(S_{CLK1})}$	Serial I/O1 clock input "L" pulse width (Note)	370			ns
$t_{WL(S_{CLK2})}$	Serial I/O2 clock input "L" pulse width	400			ns
$t_{su(R_XD\text{-}S_{CLK1})}$	Serial I/O1 input set up time	220			ns
$t_{su(S_{IN2}\text{-}S_{CLK2})}$	Serial I/O2 input set up time	200			ns
$t_{h(S_{CLK1}\text{-}R_XD)}$	Serial I/O1 input hold time	100			ns
$t_{h(S_{CLK2}\text{-}S_{IN2})}$	Serial I/O2 input hold time	200			ns

Note : When $f(X_{IN})$=8MHz and bit 6 of address $001A_{16}$ is "1" Divide this value by four when $f(X_{IN})$=8MHz and bit 6 of address $001A_{16}$ is "0"

TIMING REQUIREMENTS 2 (V_{CC} =3.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85℃, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max	
$t_{W(\overline{RESET})}$	Reset input "L" pulse width	2			μs
$t_{C(X_{IN})}$	External clock input cycle time	500			ns
$t_{WH(X_{IN})}$	External clock input "H" pulse width	200			ns
$t_{WL(X_{IN})}$	External clock input "L" pulse width	200			ns
$t_{C(CNTR)}$	$CNTR_0$, $CNTR_1$ input cycle time	500			ns
$t_{WH(CNTR)}$	$CNTR_0$, $CNTR_1$ input "H" pulse width	230			ns
$t_{WH(INT)}$	INT_0 to INT_4 input "H" pulse width	230			ns
$t_{WL(CNTR)}$	$CNTR_0$, $CNTR_1$ input "L" pulse width	230			ns
$t_{WL(INT)}$	INT_0 to INT_4 input "L" pulse width	230			ns
$t_{C(S_{CLK1})}$	Serial I/O1 clock input cycle time (Note)	2000			ns
$t_{C(S_{CLK2})}$	Serial I/O2 clock input cycle time	2000			ns
$t_{WH(S_{CLK1})}$	Serial I/O1 clock input "H" pulse width (Note)	950			ns
$t_{WH(S_{CLK2})}$	Serial I/O2 clock input "H" pulse width	950			ns
$t_{WL(S_{CLK1})}$	Serial I/O1 clock input "L" pulse width (Note)	950			ns
$t_{WL(S_{CLK2})}$	Serial I/O2 clock input "L" pulse width	950			ns
$t_{su(R_XD\text{-}S_{CLK1})}$	Serial I/O1 input set up time	400			ns
$t_{su(S_{IN2}\text{-}S_{CLK2})}$	Serial I/O2 input set up time	400			ns
$t_{h(S_{CLK1}\text{-}R_XD)}$	Serial I/O1 input hold time	200			ns
$t_{h(S_{CLK2}\text{-}S_{IN2})}$	Serial I/O2 input hold time	300			ns

Note : When $f(X_{IN})$=2MHz and bit 6 of address $001A_{16}$ is "1" Divide this value by four when $f(X_{IN})$=2MHz and bit 6 of address $001A_{16}$ is "0"

SWITCHING CHARACTERISTICS 1 (V_{CC} = 4.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85℃, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max	
$t_{WH(S_{CLK1})}$	Serial I/O1 clock output "H" pulse width	$t_{C(S_{CLK1})}/2-30$			ns
$t_{WH(S_{CLK2})}$	Serial I/O2 clock output "H" pulse width	$t_{C(S_{CLK2})}/2-160$			ns
$t_{WL(S_{CLK1})}$	Serial I/O1 clock output "L" pulse width	$t_{C(S_{CLK1})}/2-30$			ns
$t_{WL(S_{CLK2})}$	Serial I/O2 clock output "L" pulse width	$t_{C(S_{CLK2})}/2-160$			ns
$t_{d(S_{CLK1}-T_XD)}$	Serial I/O1 output delay time (Note 1)			140	ns
$t_{d(S_{CLK2}-S_{OUT2})}$	Serial I/O2 output delay time			$0.2\times t_{C(S_{CLK2})}$	ns
$t_{v(S_{CLK1}-T_XD)}$	Serial I/O1 output valid time (Note 1)	−30			ns
$t_{v(S_{CLK2}-S_{OUT2})}$	Serial I/O2 output valid time	0			ns
$t_{r(S_{CLK1})}$	Serial I/O1 clock output rise time			30	ns
$t_{f(S_{CLK1})}$	Serial I/O1 clock output fall time			30	ns
$t_{f(S_{CLK2})}$	Serial I/O2 clock output fall time			40	ns
$t_{r(CMOS)}$	CMOS output rise time (Note 2)		10	30	ns
$t_{f(CMOS)}$	CMOS output fall time (Note 2)		10	30	ns

Note 1 : When the $P4_5/T_XD$ P-channel output disable bit of the UART control register (bit 4 of address $001B_{16}$) is "0"
2 : X_{OUT} pin excluded.

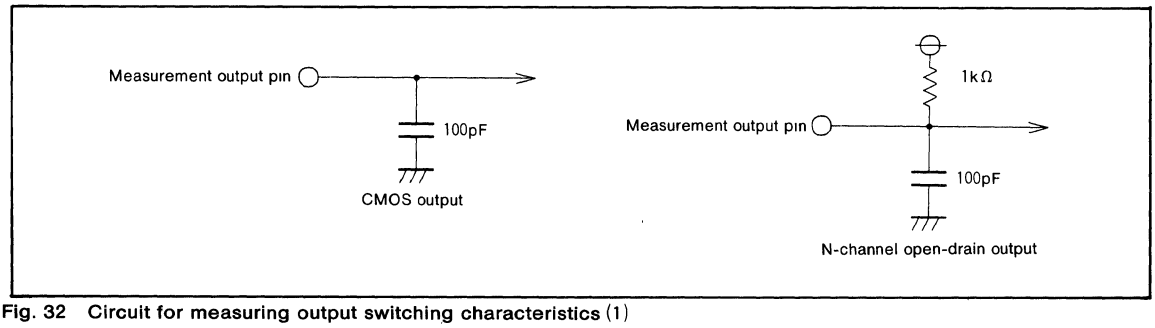


Fig. 32 Circuit for measuring output switching characteristics (1)

SWITCHING CHARACTERISTICS 2 (V_{CC} = 3.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85℃, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max	
$t_{WH(S_{CLK1})}$	Serial I/O1 clock output "H" pulse width	$t_{C(S_{CLK1})}/2-50$			ns
$t_{WH(S_{CLK2})}$	Serial I/O2 clock output "H" pulse width	$t_{C(S_{CLK2})}/2-240$			ns
$t_{WL(S_{CLK1})}$	Serial I/O1 clock output "L" pulse width	$t_{C(S_{CLK1})}/2-50$			ns
$t_{WL(S_{CLK2})}$	Serial I/O2 clock output "L" pulse width	$t_{C(S_{CLK2})}/2-240$			ns
$t_{d(S_{CLK1}-T_XD)}$	Serial I/O1 output delay time (Note 1)			350	ns
$t_{d(S_{CLK2}-S_{OUT2})}$	Serial I/O2 output delay time			$0.2\times t_{C(S_{CLK2})}$	ns
$t_{v(S_{CLK1}-T_XD)}$	Serial I/O1 output valid time (Note 1)	−30			ns
$t_{v(S_{CLK2}-S_{OUT2})}$	Serial I/O2 output valid time	0			ns
$t_{r(S_{CLK1})}$	Serial I/O1 clock output rise time			50	ns
$t_{f(S_{CLK1})}$	Serial I/O1 clock output fall time			50	ns
$t_{f(S_{CLK2})}$	Serial I/O2 clock output fall time			50	ns
$t_{r(CMOS)}$	CMOS output rise time (Note 2)		20	50	ns
$t_{f(CMOS)}$	CMOS output fall time (Note 2)		20	50	ns

Note 1 : When the $P4_5/T_XD$ P-channel output disable bit of the UART control register (bit 4 of address $001B_{16}$) is "0"
2 : X_{OUT} pin excluded.

TIMING REQUIREMENTS IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 4.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85°C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ	Max	
$t_{su(\overline{ONW}-\phi)}$	$\overline{ONW}$ input set up time	−20			ns
$t_{h(\phi-\overline{ONW})}$	$\overline{ONW}$ input hold time	−20			ns
$t_{su(DB-\phi)}$	Data bus set up time	60			ns
$t_{h(\phi-DB)}$	Data bus hold time	0			ns

SWITCHING CHARACTERISTICS IN MEMORY EXPANSION MODE AND MICROPROCESSOR MODE

(V_{CC} = 4.0 to 5.5V, V_{SS} = 0V, T_a = −20 to 85°C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min	Typ	Max	
$t_{C(\phi)}$	ϕ clock cycle time		$2Xt_{C(X_{IN})}$		ns
$t_{WH(\phi)}$	ϕ clock "H" pulse width	$t_{C(X_{IN})}-10$			ns
$t_{WL(\phi)}$	ϕ clock "L" pulse width	$t_{C(X_{IN})}-10$			ns
$t_{d(\phi-AH)}$	AD_{15} to AD_8 delay time		20	40	ns
$t_{v(\phi-AH)}$	AD_{15} to AD_8 valid time	6	10		ns
$t_{d(\phi-AL)}$	AD_7 to AD_0 delay time		25	45	ns
$t_{v(\phi-AL)}$	AD_7 to AD_0 valid time	6	10		ns
$t_{d(\phi-SYNC)}$	SYNC delay time		20		ns
$t_{v(\phi-SYNC)}$	SYNC valid time		10		ns
$t_{d(\phi-\overline{WR})}$	$\overline{RD}$ and $\overline{WR}$ delay time		10	20	ns
$t_{v(\phi-\overline{WR})}$	$\overline{RD}$ and $\overline{WR}$ valid time	3	5	10	ns
$t_{d(\phi-DB)}$	Data bus delay time		20	70	ns
$t_{v(\phi-DB)}$	Data bus valid time	15			ns
$t_{d(\overline{RESET}-\overline{RESET_{OUT}})}$	$\overline{RESET_{OUT}}$ output delay time (Note 1)			200	ns
$t_{v(\phi-\overline{RESET})}$	$\overline{RESET_{OUT}}$ output valid time (Note 1)	0		200	ns

Note 1 : The $\overline{RESET_{OUT}}$ output goes "H" in sync with the rise of the ϕ clock that is anywhere between about 1 cycle and 19 cycles after the RESET input goes "H"

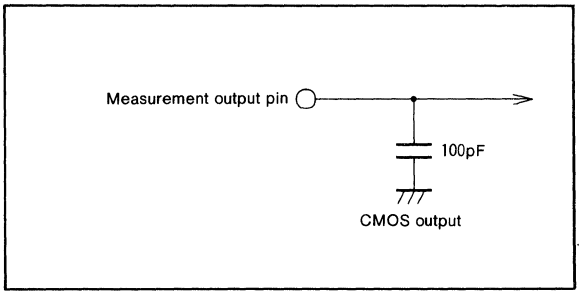
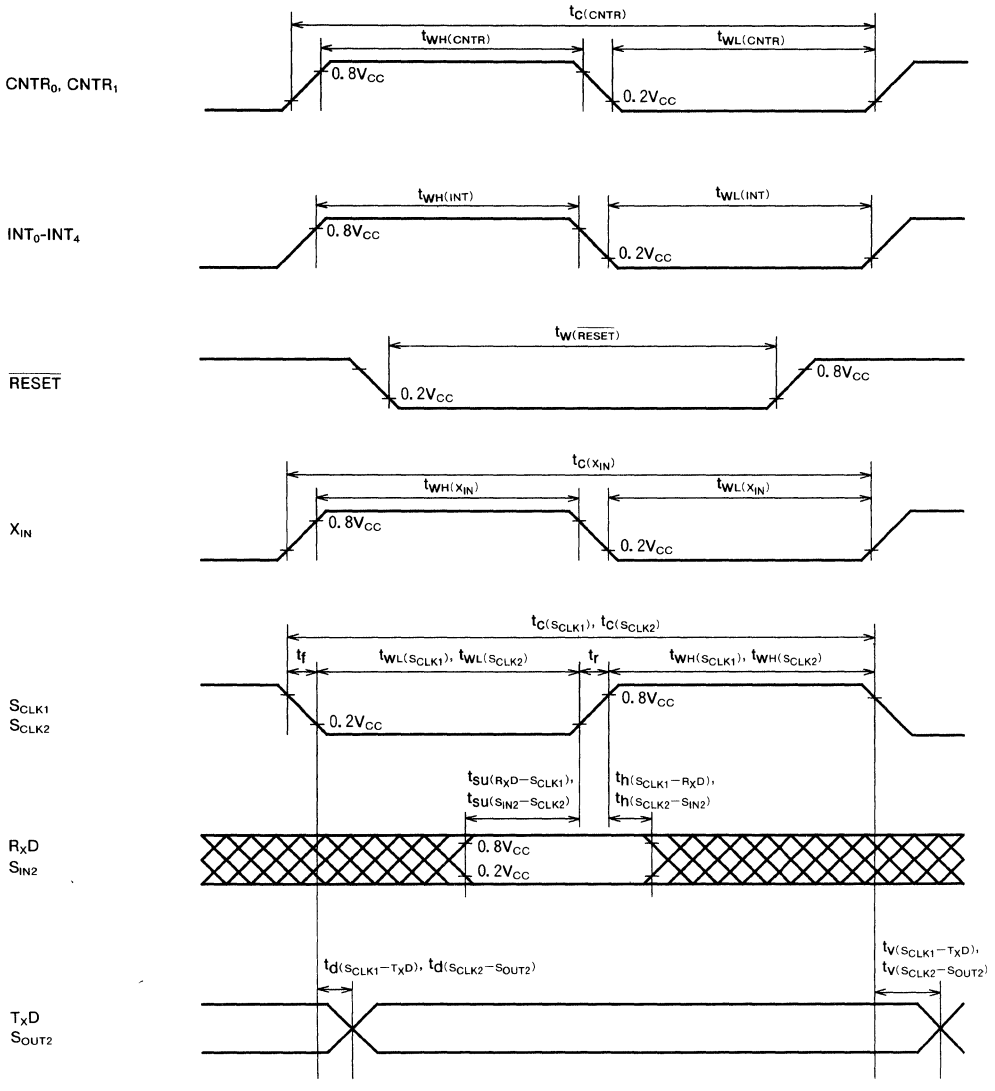


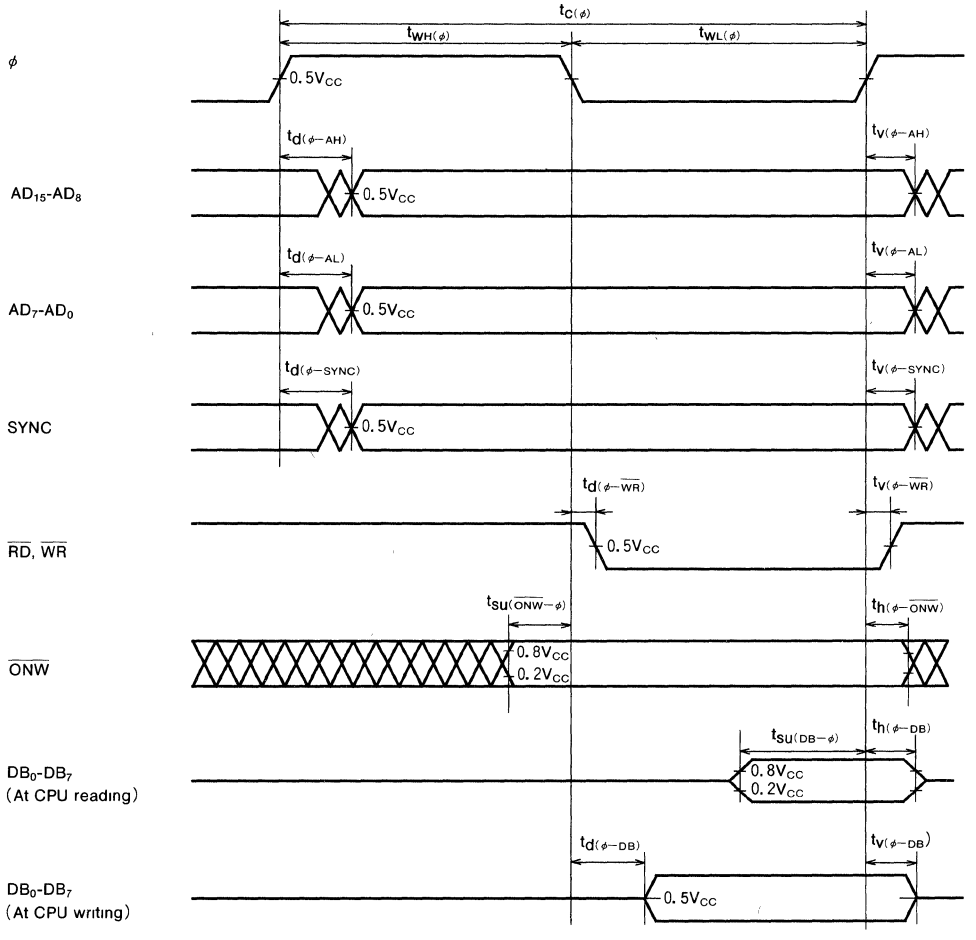
Fig. 33 Circuit for measuring output switching characteristics (2)

TIMING DIAGRAM

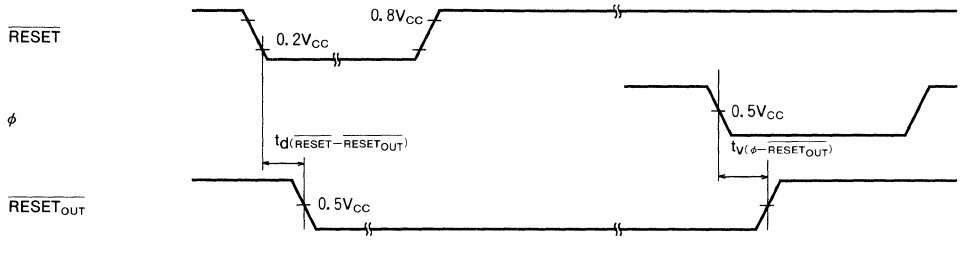
(1) Timing diagram



(2) Timing diagram in memory expansion mode and microprocessor mode



(3) Timing diagram in microprocessor mode



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