

**3-PHASE BRUSHLESS MOTOR PRE-DRIVER**

**DESCRIPTION**

The M51724P,FP are semiconductor integrated circuits designed for use in 3-phase DC brushless motor.

**FEATURES**

- Suitable for various kind of motor system by selecting the external power transistors
- Internal current distribution circuit
- Good balance in output current between each phase
- Few externally connected parts

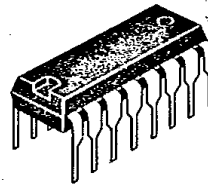
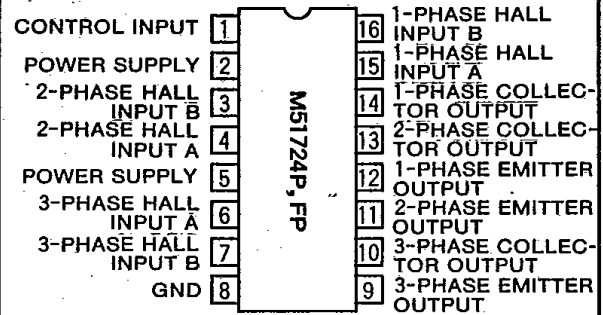
**APPLICATION**

Brushless motor driver for VTR, cassette tape deck, floppy-disk drive.

**RECOMMENDED OPERATING CONDITIONS**

Supply voltage range ..... 10V~20V  
 Rated supply voltage ..... 15V

**PIN CONFIGURATION (TOP VIEW)**

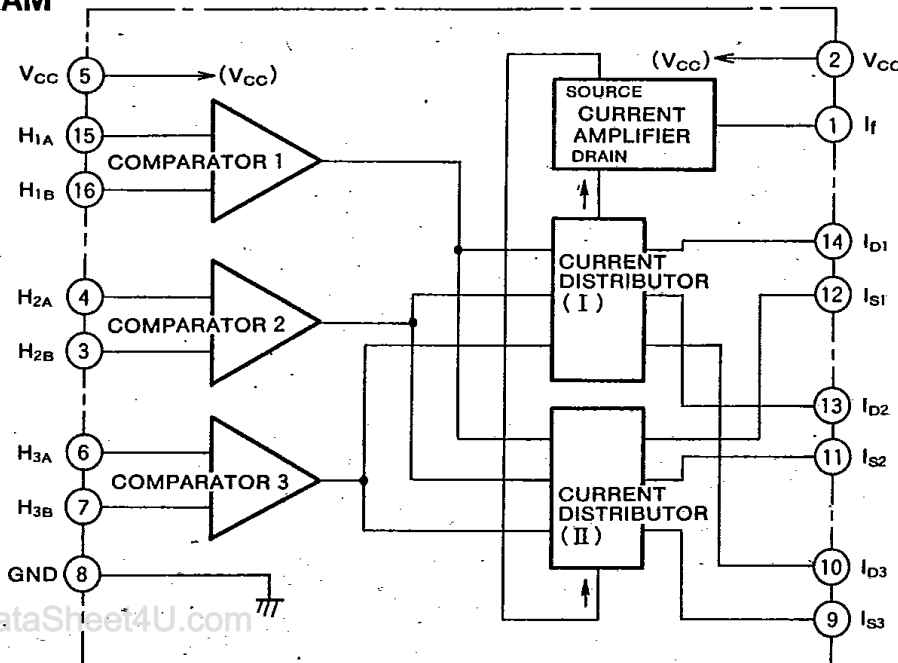


16-pin molded plastic DIP



16-pin molded plastic FLAT

**BLOCK DIAGRAM**



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## ABSOLUTE MAXIMUM RATINGS (T<sub>a</sub>=25°C, unless otherwise noted)

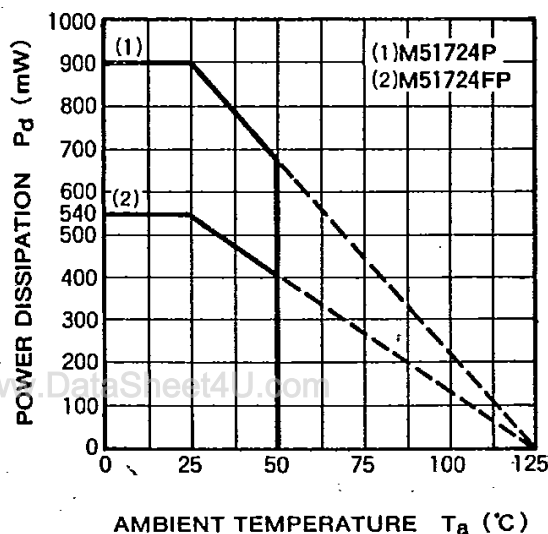
Symbol	Parameter	Conditions	Ratings	Unit
V <sub>CC</sub>	Supply voltage		20	V
I <sub>f</sub>	Control input current		1	mA
V <sub>D</sub>	Applied voltage at collector output pin		24	V
V <sub>S</sub>	Applied voltage at emitter output pin		6.5	V
V <sub>H</sub>	Applied voltage at hall output pins		6.5	V
f <sub>in</sub>	Hall input frequency		DC~1	kHz
P <sub>d</sub>	Power dissipation	( )=M51724FP	900(540)	mW
K <sub>θ</sub>	Thermal derating(T≥25°C)	( )=M51724FP	110(185)	°C/W
T <sub>opr</sub>	Operating temperature		-10~+50	°C
T <sub>stg</sub>	Storage temperature		-40~+125	°C

## ELECTRICAL CHARACTERISTICS (T<sub>a</sub>=25°C, V<sub>CC</sub>=15V, unless otherwise noted)

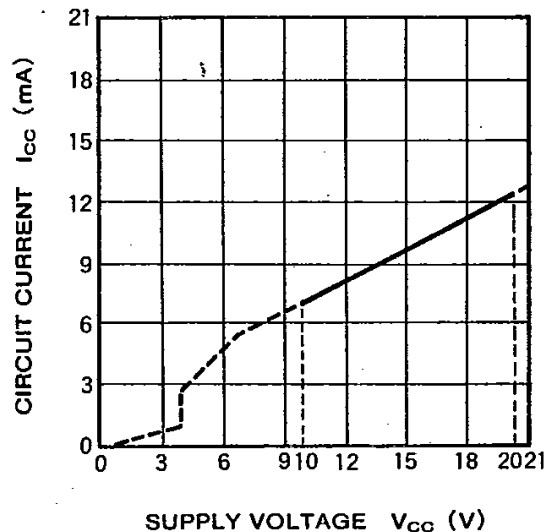
Symbol	Parameter	Test conditions	Limits			Unit
			Min	Typ	Max	
I <sub>CC</sub>	Circuit current		5	12	27	mA
V <sub>offset</sub>	Comparator input offset voltage			5	20	mV
K <sub>D</sub>	Collector output current gain		10	15	20	A/A
K <sub>S</sub>	Emitter output current gain		11	16	21	A/A
I <sub>D(max1)</sub>	Maximum output current of collector output (1)		3	4		mA
I <sub>D(max2)</sub>	Maximum output current of collector output (2)		5.5	7		mA
I <sub>S(max1)</sub>	Maximum output current of emitter output (1)		3	4		mA
I <sub>S(max2)</sub>	Maximum output current of emitter output (2)		5	7		mA
M <sub>D</sub>	Current gain ratio between collector output phases		0.75	1	1.33	A/A
M <sub>S</sub>	Current gain ratio between emitter output phases		0.75	1	1.33	A/A
I <sub>in</sub>	Comparator input current		0.1	1.5	6	μA
I <sub>LD</sub>	Collector output leak current				200	nA
I <sub>LS</sub>	Emitter output leak current				200	nA

## TYPICAL CHARACTERISTICS (T<sub>a</sub>=25°C, unless otherwise noted)

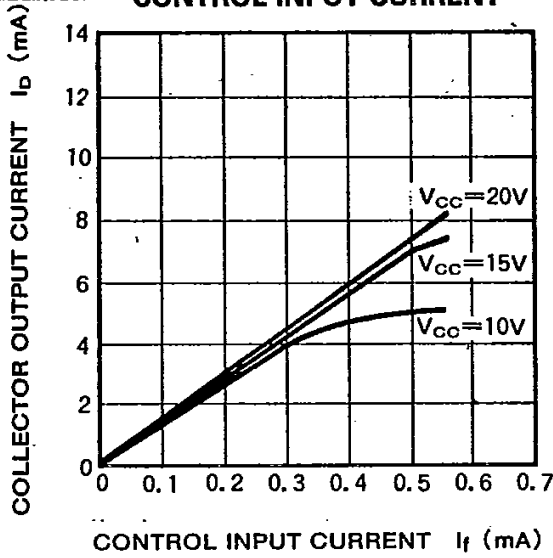
### THERMAL DERATING (MAXIMUM RATING)



### CIRCUIT CURRENT VS. SUPPLY VOLTAGE

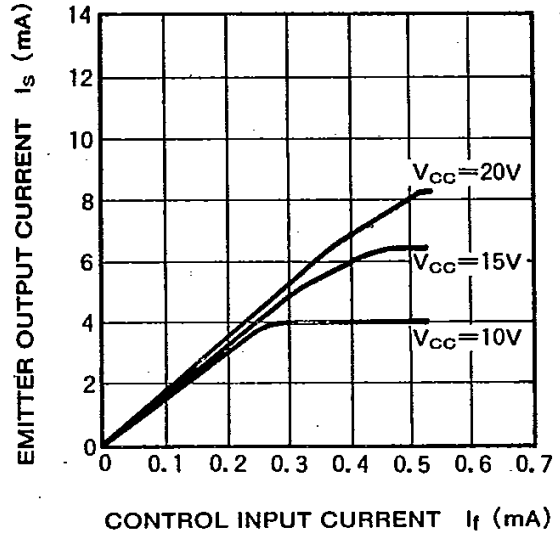


**COLLECTOR OUTPUT CURRENT VS. CONTROL INPUT CURRENT**



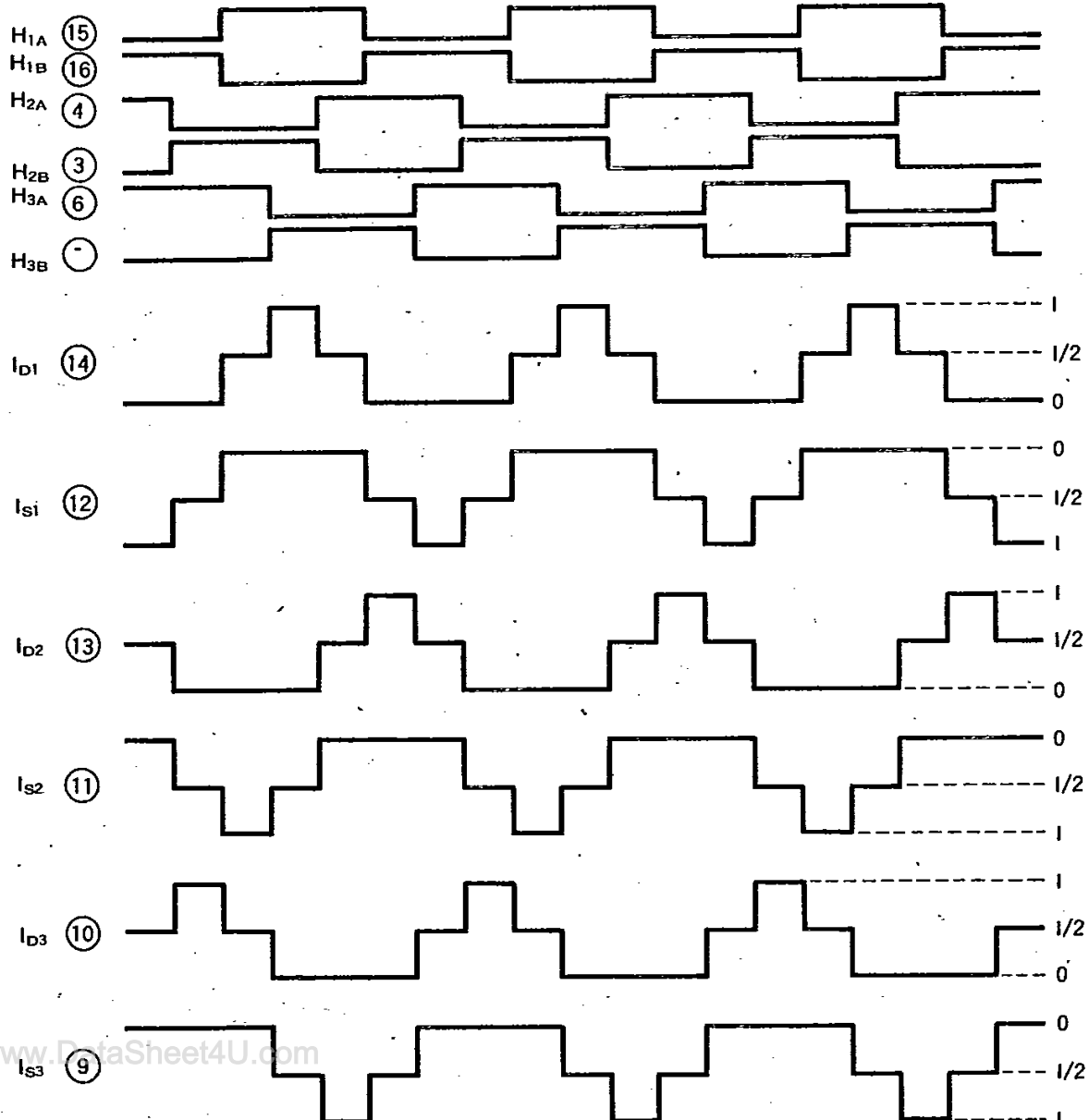
Note. when collector output 1 system and emitter output 2 system are ON

**EMITTER OUTPUT CURRENT VS. CONTROL INPUT CURRENT**



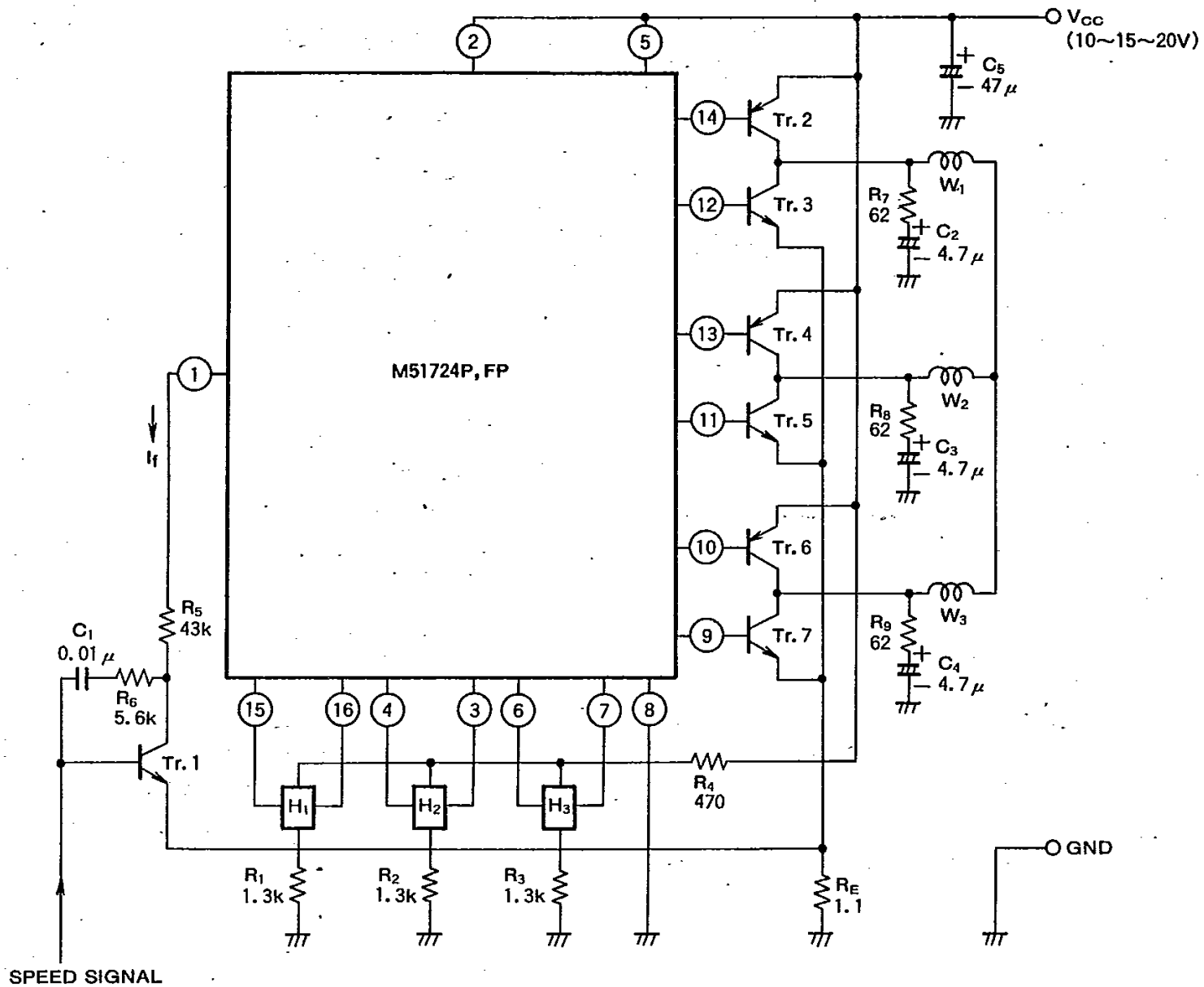
Note. when collector output 2 system and emitter output 1 system are ON

## INPUT/OUTPUT TIMING CHART OF THE M51724P,FP



- Note : 1. In the output current value ( $I_D$ ,  $I_S$ ), + indicates source current and - indicates sink current.  
 2. All the input pins are biased.  
 3. Care must be taken to connect a load (low impedance) to all the output pins according to the current at the control input Pin ①.

## APPLICATION EXAMPLE



※All constants are tentative.

Unit Resistance :  $\Omega$   
Capacitance : F

### NOTE :

1.  $R_1 \sim R_4$  : For hall element bias
2.  $R_5$  : For output (input) current limiting
3.  $R_6, C_1$  : For oscillation prevention
4.  $R_7 \sim R_9, C_2, C_4$  : For reduction of driver noise
5.  $C_5$  : For power supply stabilizing
6.  $R_E$  : For current feedback
7. Tr.1 : Control transistor (S. S.)
8. Tr.2-Rr.7 : Power transistors
9.  $H_1 \sim H_3$  : Hall elements for position detection
10. The same power supply ( $V_{CC}$ ) must be connected to Pin ② and Pin ⑤.