# 8-bit Proprietary Microcontrollers

**CMOS** 

# F<sup>2</sup>MC-8FX MB95110M series

MB95117M/F114MS/F114NS/F116MS/F116NS/ MB95F118MS/F118NS/F114MW/F114NW/F116MW/F116NW/ MB95F118MW/F118NW/FV100D-103

#### **■** DESCRIPTION

The MB95110M series is general-purpose, single-chip microcontrollers. In addition to a compact instruction set, the microcontrollers contain a variety of peripheral functions.

Note: F2MC is the abbreviation of FUJITSU Flexible Microcontroller.

#### **■ FEATURES**

- F2MC-8FX CPU core
  - Instruction set optimized for controllers
  - Multiplication and division instructions
  - 16-bit arithmetic operations
  - · Bit test branch instruction
  - Bit manipulation instructions etc.
- Clock
  - · Main clock
  - · Main PLL clock
  - Sub clock (for dual clock product)
  - Sub PLL clock (for dual clock product)
- Timer
  - 8/16-bit compound timer × 2 channels
  - 8/16-bit PPG × 2 channels
  - 16-bit PPG
  - · Timebase timer
  - · Watch prescaler (for dual clock product)

(Continued)

Be sure to refer to the "Check Sheet" for the latest cautions on development.

"Check Sheet" is seen at the following support page

URL: http://www.fujitsu.com/global/services/microelectronics/product/micom/support/index.html

"Check Sheet" lists the minimal requirement items to be checked to prevent problems beforehand in system development.



#### (Continued)

- LIN-UART
  - Full duplex double buffer
  - Clock asynchronous (UART) or clock synchronous (SIO) serial data transfer capable
- UART/SIO
  - Full duplex double buffer
  - Clock asynchronous (UART) or clock synchronous (SIO) serial data transfer capable
- I2C\*

Built-in wake-up function

- External interrupt
  - Interrupt by edge detection (rising, falling, or both edges can be selected)
  - Can be used to recover from low-power consumption (standby) modes.
- 8/10-bit A/D converter

8-bit or 10-bit resolution can be selected

- Low-power consumption (standby) mode
  - Stop mode
  - Sleep mode
  - Watch mode (for dual clock product)
  - Timebase timer mode
- I/O port
  - The number of maximum ports
    - Single clock product : 39 ports
    - Dual clock product : 37 ports
  - Configuration
    - General-purpose I/O ports (N-ch open drain) : 2 ports
    - General-purpose I/O ports (CMOS) : Single clock product : 37 ports

      Dual clock product : 35 ports
- Programmable input voltage levels of port

Automotive input level / CMOS input level / hysteresis input level

Flash memory security function

Protects the content of Flash memory (Flash memory device only)

\*: Purchase of Fujitsu I<sup>2</sup>C components conveys a license under the Philips I<sup>2</sup>C Patent Rights to use, these components in an I<sup>2</sup>C system provided that the system conforms to the I<sup>2</sup>C Standard Specification as defined by Philips.

## **■ MEMORY LINEUP**

	Flash memory	RAM	
MB95F114MS/F114NS	16 Khyton	F12 bytes	
MB95F114MW/F114NW	16 Kbytes	512 bytes	
MB95F116MS/F116NS	22 Khutaa	4 Khuto	
MB95F116MW/F116NW	- 32 Kbytes	1 Kbyte	
MB95F118MS/F118NS	CO Khutaa	2 Khutaa	
MB95F118MW/F118NW	- 60 Kbytes	2 Kbytes	

## **■ PRODUCT LINEUP**

	Part number	MB95117M	MB95F114MS MB95F116MS	MB95F116NS	MB95F114MW MB95F116MW	MB95F114NW MB95F116NW
Parameter		14404504			MB95F118NW	
Тур		MASK ROM product			nory product	
RO	M capacity*1	48 Kbytes		60 Kby	tes (Max)	
RAI	M capacity*1	2 Kbytes		2 Kbyt	es (Max)	
Res	set output			Yes		
Option*2	Clock system	Selectable single/ dual clock*3	Single	clock	Dual	clock
Opti	Low voltage detection reset	Yes / No	No	Yes	No	Yes
CP	U functions	Number of basic instr Instruction bit length Instruction length Data bit length Minimum instruction of Interrupt processing t	: : : execution time :			
	General purpose I/O ports	<ul> <li>Single clock product : 39 ports (N-ch open drain : 2 ports, CMOS : 37 ports)</li> <li>Dual clock product : 37 ports (N-ch open drain : 2 ports, CMOS : 35 ports)</li> <li>Programmable input voltage levels of port :         <ul> <li>Automotive input level / CMOS input level / hysteresis input level</li> </ul> </li> </ul>				
	Timebase timer	Interrupt cycle: 0.5 ms, 2.1 ms, 8.2 ms, 32.8 ms (at main oscillation clock 4 MHz)				
ions	Watchdog timer	Reset generated cycle At main oscillation clock 10 MHz : Min 105 ms At sub oscillation clock 32.768 kHz (for dual clock product) : Min 250 ms				
nct	Wild register Capable of replacing 3 bytes of ROM data					
Peripheral functions	I <sup>2</sup> C	Master/slave sending and receiving Bus error function and arbitration function Detecting transmitting direction function Start condition repeated generation and detection functions Built-in wake-up function				
	UART/SIO	Data transfer capable in UART/SIO Full duplex double buffer, variable data length (5/6/7/8-bit), built-in baud rate generator NRZ type transfer format, error detected function LSB-first or MSB-first can be selected. Clock asynchronous (UART) or clock synchronous (SIO) serial data transfer capable				

### (Continued)

Pa	Part number	MB95117M	MB95F116MS	MB95F116NS	MB95F114MW MB95F116MW MB95F118MW	MB95F116NW
	LIN-UART	Full duplex double Clock asynchronou capable.	Dedicated reload timer allowing a wide range of communication speeds to be set. Full duplex double buffer. Clock asynchronous (UART) or clock synchronous (SIO) serial data transfer capable. LIN functions available as the LIN master or LIN slave.			
	8/10-bit A/D converter (8 channels)	8-bit or 10-bit resol	3-bit or 10-bit resolution can be selected.			
nctions	8/16-bit compound timer (2 channels)	× 1 channel". Built-in timer function waveform output	Built-in timer function, PWC function, PWM function, capture function, and square			
Peripheral functions	16-bit PPG	PWM mode or one-shot mode can be selected. Counter operating clock : 8 selectable clock sources Support for external trigger start				
Pe	8/16-bit PPG (2 channels)	Each channel of the 1 channel". Counter operating				or "16-bit PPG×
	Watch counter (for dual clock product)	Count clock : 4 sele Counter value can selecting clock sou	be set from 0 to	63. (Capable of	counting for 1m	
	Watch prescaler (for dual clock product)	4 selectable interva	al times (125 ms	, 250 ms, 500 m	ns, or 1 s)	
	External interrupt (8 channels)	Interrupt by edge detection (rising, falling, or both edges can be selected.) Can be used to recover from standby modes.			ected.)	
Flash memory		Supports automatic programming, Embedded Algorithm <sup>TM</sup> *4 Write/Erase/Erase-Suspend/Resume commands A flag indicating completion of the algorithm Number of write/erase cycles (Minimum): 10000 times Data retention time: 20 years Erase can be performed on each block Block protection with external programming voltage Flash Security Feature for protecting the content of the Flash				
Sta	ndby mode	Sleep, stop, watch	(for dual clock p	roduct), and tin	nebase timer	

<sup>\*1 :</sup> For ROM capacity and RAM capacity, refer to "1. Memory space" in "■ CPU CORE".

Note: Part number of the evaluation device in MB95110M series is MB95FV100D-103. When using it, the MCU board (MB2146-303A) is required.

<sup>\*2 :</sup> For details of option, refer to "■ MASK OPTION".

<sup>\*3 :</sup> Specify clock mode when ordering MASK ROM.

<sup>\*4 :</sup> Embedded Algorithm is a trade mark of Advanced Micro Devices Inc.

## **■ OSCILLATION STABILIZATION WAIT TIME**

The initial value of the main clock oscillation stabilization wait time is fixed to the maximum value. The maximum value is shown as follows.

Oscillation stabilization wait time	Remarks
(2 <sup>14</sup> –2) /Fcн	Approx. 4.10 ms (at main oscillation clock 4 MHz)

## ■ PACKAGES AND CORRESPONDING PRODUCTS

Part number Package	MB95117M	MB95F116MS/F116NS	MB95F114MW/F114NW MB95F116MW/F116NW MB95F118MW/F118NW	MB95FV100D-103
FPT-52P-M01	0	0	0	×
BGA-224P-M08	×	×	X	0

○ : Available× : Unavailable

#### ■ DIFFERENCES AMONG PRODUCTS AND NOTES ON SELECTING PRODUCTS

#### Notes on Using Evaluation Products

The Evaluation product has not only the functions of the MB95110M series but also those of other products to support software development for multiple series and models of the F²MC-8FX family. The I/O addresses for peripheral resources not used by the MB95110M series are therefore access-barred. Read/write access to these access-barred addresses may cause peripheral resources supposed to be unused to operate, resulting in unexpected malfunctions of hardware or software.

Particularly, do not use word access to odd numbered byte address in the prohibited areas (If these access are used, the address may be read or write unexpectedly).

Note that the values read from barred addresses are different between the Evaluation product and the Flash memory or MASK ROM product. Therefore, the data must not be used for software processing.

The Evaluation product do not support the functions of some bits in single-byte registers. Read/write access to these bits does not cause hardware malfunctions. Since the Evaluation, Flash memory, and MASK ROM products are designed to behave completely the same way in terms of hardware and software.

#### Difference of Memory Spaces

If the amount of memory on the Evaluation product is different from that of the Flash memory or MASK ROM product, carefully check the difference in the amount of memory from the model to be actually used when developing software.

For details of memory space, refer to "■ CPU CORE".

### Current Consumption

- The current consumption of Flash memory product is typically greater than for MASK ROM product.
- For details of current consumption, refer to "■ ELECTRICAL CHARACTERISTICS".

#### Package

For details of information on each package, refer to "■ PACKAGE AND CORRESPONDING PRODUCTS" and "■ PACKAGE DIMENSIONS".

#### Operating Voltage

The operating voltage are different among the Evaluation, Flash memory, and MASK ROM products.

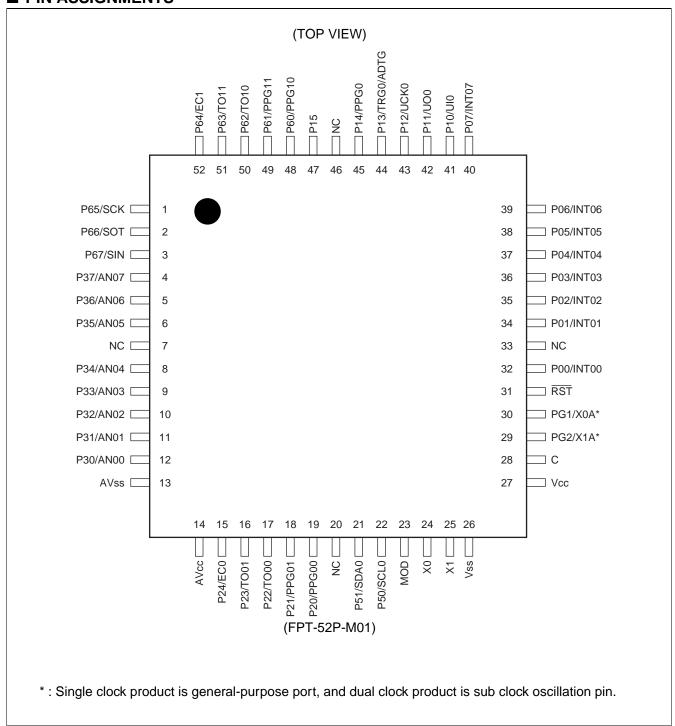
For details of operating voltage, refer to "■ ELECTRICAL CHARACTERISTICS"

#### • Difference between RST and MOD Pins

The input type of RST and MOD pins is CMOS inputs on the Flash memory product.

The  $\overline{RST}$  and MOD pins are hysteresis inputs on the MASK ROM product. A pull-down resistor is provided for the MOD pin of the MASK ROM product.

### **■ PIN ASSIGNMENTS**



## **■ PIN DESCRIPTION**

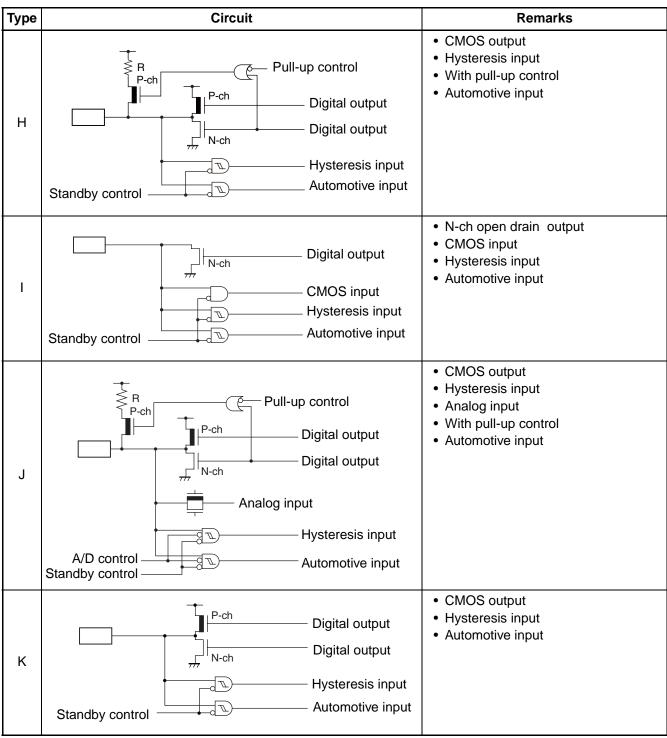
Pin no.	Pin name	I/O Circuit type*	Function
1	P65/SCK	К	General-purpose I/O port. The pin is shared with LIN-UART clock I/O.
2	P66/SOT		General-purpose I/O port. The pin is shared with LIN-UART data output.
3	P67/SIN	L	General-purpose I/O port. The pin is shared with LIN-UART data input.
4	P37/AN07		
5	P36/AN06		
6	P35/AN05		
8	P34/AN04		General-purpose I/O port.
9	P33/AN03	J	The pins are shared with A/D converter analog input.
10	P32/AN02		
11	P31/AN01		
12	P30/AN00		
13	AVss	_	A/D converter power supply pin (GND)
14	AVcc	_	A/D converter power supply pin
15	P24/EC0		General-purpose I/O port. The pin is shared with 8/16-bit compound timer ch.0 clock input.
16	P23/TO01	l	General-purpose I/O port.
17	P22/TO00	Н	The pins are shared with 8/16-bit compound timer ch.0 output.
18	P21/PPG01		General-purpose I/O port.
19	P20/PPG00		The pins are shared with 8/16-bit PPG ch.0 output.
21	P51/SDA0	ı	General-purpose I/O port. The pin is shared with I <sup>2</sup> C ch.0 data I/O.
22	P50/SCL0	'	General-purpose I/O port. The pin is shared with I <sup>2</sup> C ch.0 clock I/O.
23	MOD	В	Operating mode designation pin
24	X0	Α	Main clock oscillation input pin
25	X1	_ ^	Main clock oscillation I/O pin
26	Vss	_	Power supply pin (GND)
27	Vcc	_	Power supply pin
28	С	_	Capacitor connection pin
29	PG2/X1A	H/A	Single clock product is general-purpose port (PG2).  Dual clock product is sub clock I/O oscillation pin (32 kHz).
30	PG1/X0A	11/7	Single clock product is general-purpose port (PG1).  Dual clock product is sub clock input oscillation pin (32 kHz).
31	RST	B'	Reset pin

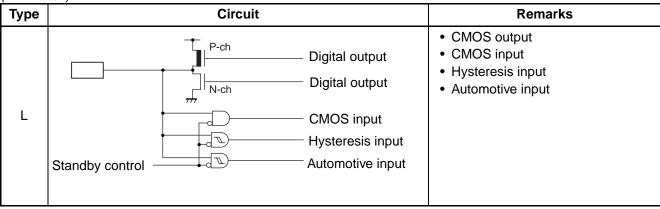
Pin no.	Pin name	I/O Circuit type*	Function	
32	P00/INT00			
34	P01/INT01			
35	P02/INT02			
36	P03/INT03	С	General-purpose I/O port.	
37	P04/INT04	C	The pins are shared with external interrupt input. Large current port.	
38	P05/INT05			
39	P06/INT06			
40	P07/INT07			
41	P10/UI0	G	General-purpose I/O port. The pin is shared with UART/SIO ch.0 data input.	
42	P11/UO0	General-purpose I/O port. The pin is shared with UART/SIO ch.0 data output.  General-purpose I/O port. The pin is shared with UART/SIO ch.0 clock I/O.		
43	P12/UCK0			
44	P13/TRG0/ ADTG	н	General-purpose I/O port. The pin is shared with 16-bit PPG ch.0 trigger input (TRG0) and A/D trigger input (ADTG).	
45	P14/PPG0		General-purpose I/O port. The pin is shared with 16-bit PPG ch.0 output.	
47	P15		General-purpose I/O port.	
48	P60/PPG10		General-purpose I/O port.	
49	P61/PPG11		The pins are shared with 8/16-bit PPG ch.1 output.	
50	P62/TO10	K	General-purpose I/O port.	
51	P63/TO11		The pins are shared with 8/16-bit compound timer ch.1 output.	
52	P64/EC1		General-purpose I/O port. The pin is shared with 8/16-bit compound timer ch.1 clock input	
7, 20, 33, 46	NC	_	Internal connect pin. Be sure this pin is left open.	

<sup>\*:</sup> For the I/O circuit type, refer to "■ I/O CIRCUIT TYPE"

## ■ I/O CIRCUIT TYPE

Туре	Circuit	Remarks
Α	X1 (X1A) Clock input X0 (X0A) Standby control	<ul> <li>Oscillation circuit</li> <li>High-speed side         Feedback resistance : approx. 1 MΩ</li> <li>Low-speed side         Feedback resistance : approx. 24 MΩ         (Evaluation product : approx. 10 MΩ)         Dumping resistance : approx. 144 MΩ)         (Evaluation product : without dumping resistance)</li> </ul>
В	Mode input	Only for input     Hysteresis input only for MASK ROM     product     With pull-down resistor only for MASK     ROM     product
B'	Reset input  N-ch Reset output	Reset output     Hysteresis input
С	Digital output  N-ch  Hysteresis input  Standby control  External interrupt enable	CMOS output     Hysteresis input     Automotive input
G	Pull-up control  Pigital output  Digital output  CMOS input  Hysteresis input  Automotive input	CMOS output CMOS input Hysteresis input With pull-up control Automotive input





#### **■ HANDLING DEVICES**

#### Preventing Latch-up

Care must be taken to ensure that maximum voltage ratings are not exceeded when they are used.

Latch-up may occur on CMOS ICs if voltage higher than  $V_{\text{CC}}$  or lower than  $V_{\text{SS}}$  is applied to input and output pins other than medium- and high-withstand voltage pins or if higher than the rating voltage is applied between  $V_{\text{CC}}$  pin and  $V_{\text{SS}}$  pin.

When latch-up occurs, power supply current increases rapidly and might thermally damage elements.

Also, take care to prevent the analog power supply voltage (AVcc) and analog input voltage from exceeding the digital power supply voltage (Vcc) when the analog system power supply is turned on or off.

### • Stable Supply Voltage

Supply voltage should be stabilized.

A sudden change in power-supply voltage may cause a malfunction even within the guaranteed operating range of the Vcc power-supply voltage.

For stabilization, in principle, keep the variation in Vcc ripple (p-p value) in a commercial frequency range (50/60 Hz) not to exceed 10% of the standard Vcc value and suppress the voltage variation so that the transient variation rate does not exceed 0.1 V/ms during a momentary change such as when the power supply is switched.

#### Precautions for Use of External Clock

Even when an external clock is used, oscillation stabilization wait time is required for power-on reset, wake-up from sub clock mode or stop mode.

#### **■ PIN CONNECTION**

#### Treatment of Unused Pin

Leaving unused input pins unconnected can cause abnormal operation or latch-up, leaving to permanent damage. Unused input pins should always be pulled up or down through resistance of at least  $2 \text{ k}\Omega$ . Any unused input/output pins may be set to output mode and left open, or set to input mode and treated the same as unused input pins. If there is unused output pin, make it open.

### • Treatment of Power Supply Pins on A/D Converter

Connect to be AVcc = Vcc and AVss = Vss even if the A/D converter is not in use.

Noise riding on the AVcc pin may cause accuracy degradation. So, connect approx. 0.1 µF ceramic capacitor as a bypass capacitor between AVcc and AVss pins in the vicinity of this device.

### • Power Supply Pins

In products with multiple  $V_{CC}$  or  $V_{SS}$  pins, the pins of the same potential are internally connected in the device to avoid abnormal operations including latch-up. However, you must connect the pins to external power supply and a ground line to lower the electro-magnetic emission level, to prevent abnormal operation of strobe signals caused by the rise in the ground level, and to conform to the total output current rating.

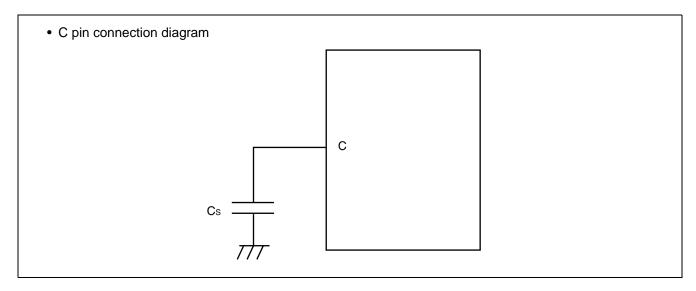
Moreover, connect the current supply source with the  $V_{\text{CC}}$  and  $V_{\text{SS}}$  pins of this device at the low impedance. It is also advisable to connect a ceramic bypass capacitor of approximately 0.1  $\mu\text{F}$  between  $V_{\text{CC}}$  and  $V_{\text{SS}}$  pins near this device.

#### Mode Pin (MOD)

Connect the mode pin directly to Vcc or Vss pins.

To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pins to Vcc or Vss pins and to provide a low-impedance connection.

Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. A bypass capacitor of  $V_{\text{CC}}$  pin must have a capacitance value higher than  $C_{\text{S}}$ . For connection of smoothing capacitor  $C_{\text{S}}$ , refer to the diagram below.



#### • NC Pins

Any pins marked "NC" (not connected) must be left open.

#### Analog Power Supply

Always set the same potential to AVcc and Vcc. When Vcc > AVcc, the current may flow through the AN00 to AN07 pins.

# ■ PROGRAMMING FLASH MEMORY MICROCONTROLLERS USING PARALLEL PROGRAMMER

#### Supported Parallel Programmers and Adapters

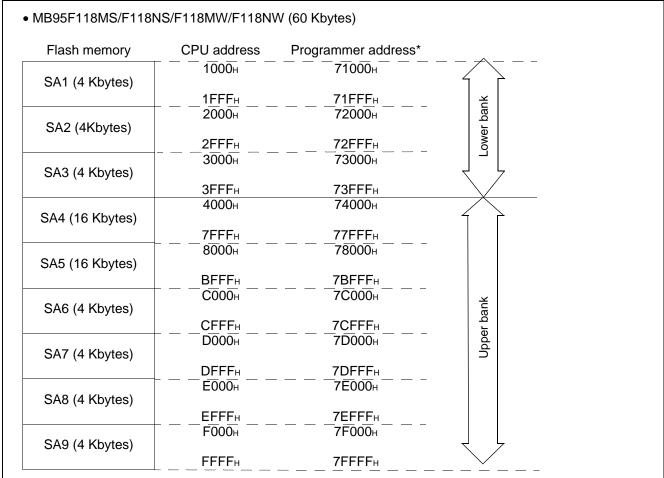
The following table lists supported parallel programmers and adapters.

Package	Applicable adapter model	Parallel programmers
FPT-52P-M01	TEF110-95118PMC	AF9708 (Ver 02.35G or more) AF9709/B (Ver 02.35G or more) AF9723+AF9834 (Ver 02.08E or more)

Note: For information on applicable adapter models and parallel programmers, contact the following: Flash Support Group, Inc. TEL: +81-53-428-8380

#### Sector Configuration

The individual sectors of Flash memory correspond to addresses used for CPU access and programming by the parallel programmer as follows:



<sup>\*:</sup> Programmer addresses are corresponding to CPU addresses, used when the parallel programmer programs data into Flash memory.

These programmer addresses are used for the parallel programmer to program or erase data in Flash memory.

### MB95F116MS/F116NS/F116MW/F116NW (32 Kbytes)

Flash memory	CPU address	Programmer address*
SA5 (16 Kbytes)	8000н	
	BFFF <sub>H</sub>	7BFFF <sub>H</sub>
SA6 (4 Kbytes)	С000н	7С000н
	СFFFн	7CFFF <sub>H</sub>
SA7 (4 Kbytes)		7 <u>D</u> 000н
	DFFFH	7DFFF <sub>H</sub>
SA8 (4 Kbytes)	Е000н	7 <u>Е</u> 000 <sub>н</sub>
	EFFFH	7EFFF <sub>H</sub>
SA9 (4 Kbytes)	F000 <sub>H</sub>	7F000 <sub>H</sub>
	FFFF <sub>H</sub>	7FFFF <sub>H</sub>

<sup>\*:</sup> Programmer addresses are corresponding to CPU addresses, used when the parallel programmer programs data into Flash memory.

These programmer addresses are used for the parallel programmer to program or erase data in Flash memory.

## • MB95F114MS/F114NS/F114MW/F114NW (16 Kbytes)

Flash memory	CPU address	Programmer address*
SA6 (4 Kbytes)	С000н	
	CFFFH	7CFFFн
SA7 (4 Kbytes)		7D000 <sub>H</sub>
	DFFFH	7DFFF <sub>H</sub>
SA8 (4 Kbytes)	Е000н	7 <u>Е</u> 000н
	EFFFH	7EFFF <sub>H</sub>
SA9 (4 Kbytes)	F000 <sub>H</sub>	7 <u>F</u> 000 <sub>н</sub>
	<u>_ FFFF</u> +	<u>7FFF</u> +

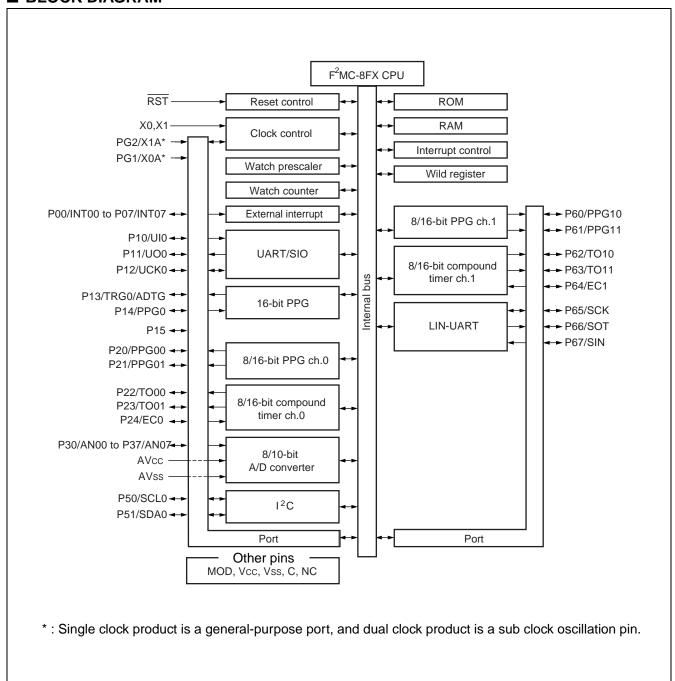
<sup>\*:</sup> Programmer addresses are corresponding to CPU addresses, used when the parallel programmer programs data into Flash memory.

These programmer addresses are used for the parallel programmer to program or erase data in Flash memory.

#### • Programming Method

- 1) Set the type code of the parallel programmer to "17222".
- 2) Load program data to programmer addresses 71000H to 7FFFFH.
- 3) Programmed by parallel programmer

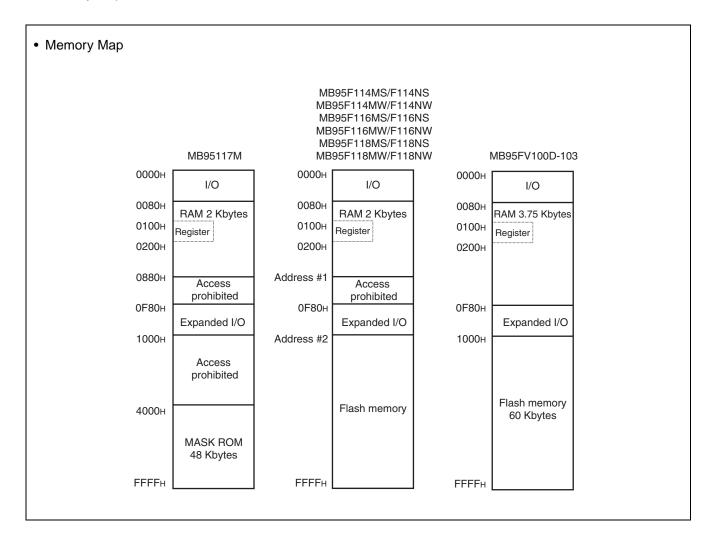
### **■ BLOCK DIAGRAM**



#### **■ CPU CORE**

#### 1. Memory space

Memory space of the MB95110M series is 64 Kbytes and consists of I/O area, data area, and program area. The memory space includes special-purpose areas such as the general-purpose registers and vector table. Memory map of the MB95110M series is shown below.



	Flash memory	RAM	Address #1	Address #2
MB95F114MS/F114NS	16 Kbytes	512 bytes	0280н	С000н
MB95F114MW/F114NW	10 Kbytes	512 bytes	0200H	Сооон
MB95F116MS/F116NS	22 Khyton	1 Kbyte	0480н	8000н
MB95F116MW/F116NW	32 Kbytes			
MB95F118MS/F118NS	60 Khyton	0.1/1	0000	4000
MB95F118MW/F118NW	60 Kbytes	2 Kbytes	0880н	1000н

### 2. Register

The MB95110M series has two types of registers; dedicated registers in the CPU and general-purpose registers in the memory. The dedicated registers are as follows:

Program counter (PC) : A 16-bit register to indicate locations where instructions are stored.

Accumulator (A) : A 16-bit register for temporary storage of arithmetic operations. In the case of

an 8-bit data processing instruction, the lower 1 byte is used.

Temporary accumulator (T) : A 16-bit register which performs arithmetic operations with the accumulator.

In the case of an 8-bit data processing instruction, the lower 1 byte is used.

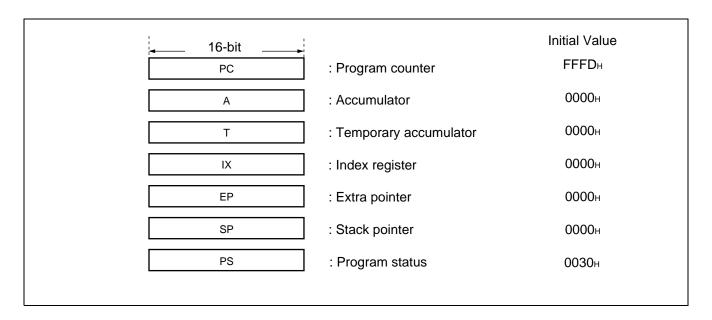
Index register (IX) : A 16-bit register for index modification.

Extra pointer (EP) : A 16-bit pointer to point to a memory address.

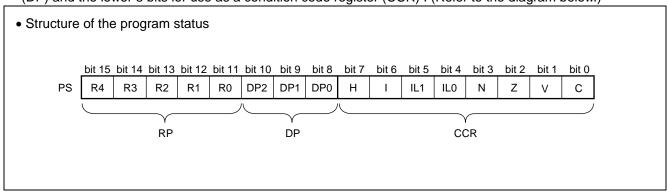
Stack pointer (SP) : A 16-bit register to indicate a stack area.

Program status (PS) : A 16-bit register for storing a register bank pointer, a direct bank pointer, and

a condition code register.



The PS can further be divided into higher 8 bits for use as a register bank pointer (RP) and a direct bank pointer (DP) and the lower 8 bits for use as a condition code register (CCR). (Refer to the diagram below.)



The RP indicates the address of the register bank currently being used. The relationship between the content of RP and the real address conforms to the conversion rule illustrated below:

 Rule for Conversion of Actual Addresses in the General-purpose Register Area RP upper OP code lower "1" R4 R3 R2 R1 R0 b2 b0 ¥ ¥ ¥ ¥ ¥ Generated address A<sub>15</sub> A14 A13 A12 A11 A10 Α9 **A8** Α7 A6 A5 Α4 АЗ A2 Α1 A0

The DP specifies the area for mapping instructions (16 different instructions such as MOV A, dir) using direct addresses to 0080<sub>H</sub> to 00FF<sub>H</sub>.

Direct bank pointer (DP2 to DP0)	Specified address area	Mapping area		
XXX <sub>B</sub> (no effect to mapping)	0000н to 007Fн	0000н to 007Fн (without mapping)		
000 <sub>B</sub> (initial value)		0080н to 00FFн (without mapping)		
001в		0100н to 017Fн		
010в		0180н to 01FFн		
011в	0080н to 00FFн	0200н to 027Fн		
100в	- 0000H 10 00FFH	0280н to 02FFн		
101в		0300н to 037Fн		
110в		0380н to 03FFн		
111в	111в			

The CCR consists of the bits indicating arithmetic operation results or transfer data contents and the bits that control CPU operations at interrupt.

H flag : Set to "1" when a carry or a borrow from bit 3 to bit 4 occurs as a result of an arithmetic operation.

Cleared to "0" otherwise. This flag is for decimal adjustment instructions.

I flag : Interrupt is enabled when this flag is set to "1". Interrupt is disabled when this flag is set to "0".

The flag is set to "0" when reset.

IL1, IL0 : Indicates the level of the interrupt currently enabled. Processes an interrupt only if its request level is higher than the value indicated by these bits.

IL1	IL0	Interrupt level	Priority
0	0	0	High
0	1	1	<b>↑</b>
1	0	2	<u> </u>
1	1	3	Low = no interruption

N flag : Set to "1" if the MSB is set to "1" as the result of an arithmetic operation. Cleared to "0" when the bit is set to "0".

Z flag : Set to "1" when an arithmetic operation results in "0". Cleared to "0" otherwise.

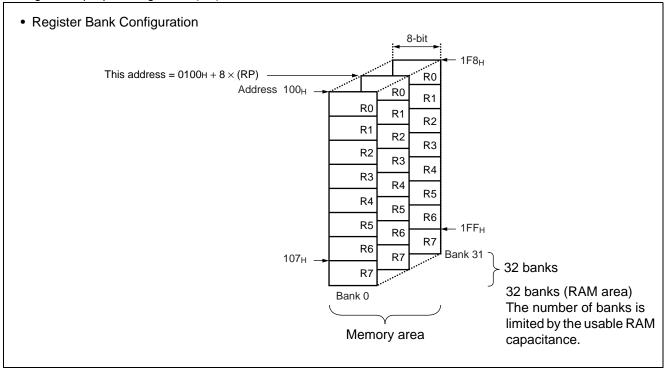
V flag : Set to "1" if the complement on 2 overflows as a result of an arithmetic operation. Cleared to "0" otherwise.

C flag : Set to "1" when a carry or a borrow from bit 7 occurs as a result of an arithmetic operation. Cleared to "0" otherwise. Set to the shift-out value in the case of a shift instruction.

The following general-purpose registers are provided:

General-purpose registers: 8-bit data storage registers

The general-purpose registers are 8 bits and located in the register banks on the memory. 1-bank contains 8-register. Up to a total of 32 banks can be used on the MB95110M series. The bank currently in use is specified by the register bank pointer (RP), and the lower 3 bits of OP code indicates the general-purpose register 0 (R0) to general-purpose register 7 (R7).



## ■ I/O MAP

Address	Register abbreviation	Register name	R/W	Initial value
0000н	PDR0	Port 0 data register	R/W	0000000в
0001н	DDR0	Port 0 direction register	R/W	0000000в
0002н	PDR1	Port 1 data register	R/W	0000000в
0003н	DDR1	Port 1 direction register	R/W	0000000в
0004н	_	(Disabled)	_	_
0005н	WATR	Oscillation stabilization wait time setting register	R/W	111111111
0006н	PLLC	PLL control register	R/W	0000000в
0007н	SYCC	System clock control register	R/W	1010Х011в
0008н	STBC	Standby control register	R/W	0000000в
0009н	RSRR	Reset source register	R	XXXXXXXX
000Ан	TBTC	Timebase timer control register	R/W	0000000в
000Вн	WPCR	Watch prescaler control register	R/W	0000000в
000Сн	WDTC	Watchdog timer control register	R/W	0000000в
000Дн	_	(Disabled)	<u> </u>	_
000Ен	PDR2	Port 2 data register	R/W	0000000в
000Fн	DDR2	Port 2 direction register	R/W	0000000в
0010н	PDR3	Port 3 data register	R/W	0000000в
0011н	DDR3	Port 3 direction register	R/W	0000000в
0012н, 0013н	_	(Disabled)	_	_
0014н	PDR5	Port 5 data register	R/W	0000000В
0015н	DDR5	Port 5 direction register	R/W	0000000в
0016н	PDR6	Port 6 data register	R/W	0000000в
0017н	DDR6	Port 6 direction register	R/W	0000000в
0018н to 0029н	_	(Disabled)	_	_
002Ан	PDRG	Port G data register	R/W	0000000в
002Вн	DDRG	Port G direction register	R/W	0000000в
002Сн	_	(Disabled)		_
002Dн	PUL1	Port 1 pull-up register	R/W	0000000в
002Ен	PUL2	Port 2 pull-up register	R/W	0000000в
002Fн	PUL3	Port 3 pull-up register	R/W	0000000В
0030н to 0034н	_	(Disabled)	_	_

Address	Register abbreviation	Register name	R/W	Initial value
0035н	PULG	Port G pull-up register	R/W	0000000В
0036н	T01CR1	8/16-bit compound timer 01 control status register 1 ch.0	R/W	0000000в
0037н	T00CR1	8/16-bit compound timer 00 control status register 1 ch.0	R/W	00000000В
0038н	T11CR1	8/16-bit compound timer 11 control status register 1 ch.1	R/W	0000000В
0039н	T10CR1	8/16-bit compound timer 10 control status register 1 ch.1	R/W	0000000В
003Ан	PC01	8/16-bit PPG1 control register ch.0	R/W	0000000
003Вн	PC00	8/16-bit PPG0 control register ch.0	R/W	0000000
003Сн	PC11	8/16-bit PPG1 control register ch.1	R/W	0000000В
003Dн	PC10	8/16-bit PPG0 control register ch.1	R/W	0000000
003Ен to 0041н	_	(Disabled)	_	_
0042н	PCNTH0	16-bit PPG status control register (Upper byte) ch.0	R/W	0000000в
0043н	PCNTL0	16-bit PPG status control register (Lower byte) ch.0	R/W	0000000в
0044н to 0047н	_	(Disabled)	_	_
0048н	EIC00	External interrupt circuit control register ch.0/1	R/W	0000000В
0049н	EIC10	External interrupt circuit control register ch.2/3	R/W	0000000В
004Ан	EIC20	External interrupt circuit control register ch.4/5	R/W	0000000В
004Вн	EIC30	External interrupt circuit control register ch.6/7	R/W	0000000В
004Сн to 004Fн	_	(Disabled)	_	_
0050н	SCR	LIN-UART serial control register	R/W	00000000В
0051н	SMR	LIN-UART serial mode register	R/W	00000000в
0052н	SSR	LIN-UART serial status register	R/W	00001000в
0053н	RDR/TDR	LIN-UART reception/transmission data register	R/W	0000000В
0054н	ESCR	LIN-UART extended status control register	R/W	00000100в
0055н	ECCR	LIN-UART extended communication control register	R/W	000000XXB
0056н	SMC10	UART/SIO serial mode control register 1 ch.0	R/W	00000000В
0057н	SMC20	UART/SIO serial mode control register 2 ch.0	R/W	00100000в
0058н	SSR0	UART/SIO serial status register ch.0	R/W	0000001в
0059н	TDR0	UART/SIO serial output data register ch.0	R/W	0000000в
005Ан	RDR0	UART/SIO serial input data register ch.0	R	00000000В
005Вн to 005Fн	_	(Disabled)	_	_

Address	Register abbreviation	R/W	Initial value	
0060н	IBCR00	I <sup>2</sup> C bus control register 0 ch.0	R/W	0000000В
0061н	IBCR10	I <sup>2</sup> C bus control register 1 ch.0	R/W	0000000В
0062н	IBSR0	I <sup>2</sup> C bus status register ch.0	R	00000000в
0063н	IDDR0	I <sup>2</sup> C data register ch.0	R/W	00000000в
0064н	IAAR0	I <sup>2</sup> C address register ch.0	R/W	00000000в
0065н	ICCR0	I <sup>2</sup> C clock control register ch.0	R/W	00000000в
0066н to 006Вн	_	(Disabled)		_
006Сн	ADC1	8/10-bit A/D converter control register 1	R/W	00000000в
006Dн	ADC2	8/10-bit A/D converter control register 2	R/W	00000000в
006Ен	ADDH	8/10-bit A/D converter data register (Upper byte)	R/W	00000000в
006Fн	ADDL	8/10-bit A/D converter data register (Lower byte)	R/W	00000000в
0070н	WCSR	Watch counter status register	R/W	00000000в
0071н	_	(Disabled)	_	_
0072н	FSR	Flash memory status register	R/W	000X0000B
0073н	SWRE0	Flash memory sector writing control register 0	R/W	00000000в
0074н	SWRE1	Flash memory sector writing control register 1	R/W	00000000В
0075н	_	(Disabled)	_	_
0076н	WREN	Wild register address compare enable register	R/W	00000000В
0077н	WROR	Wild register data test setting register	R/W	00000000В
0078н	_	(Mirror of register bank pointer (RP) and direct bank pointer (DP))	_	_
0079н	ILR0	Interrupt level setting register 0	R/W	11111111В
007Ан	ILR1	Interrupt level setting register 1	R/W	11111111В
007Вн	ILR2	Interrupt level setting register 2	R/W	11111111в
007Сн	ILR3	Interrupt level setting register 3	R/W	11111111В
007Dн	ILR4	Interrupt level setting register 4	R/W	11111111в
007Ен	ILR5	Interrupt level setting register 5	R/W	11111111В
007Fн	_	(Disabled)	_	_
0F80н	WRARH0	Wild register address setting register (Upper byte) ch.0		0000000В
0F81н	WRARL0	Wild register address setting register (Lower byte) ch.0	R/W	00000000в
0F82н	WRDR0	Wild register data setting register ch.0	R/W	00000000в
0F83н	WRARH1	Wild register address setting register (Upper byte) ch.1	R/W	00000000В
0F84н	WRARL1	Wild register address setting register (Lower byte) ch.1	R/W	00000000в
0F85н	WRDR1	Wild register data setting register ch.1	R/W	00000000в

Address	Register abbreviation	Register name	R/W	Initial value
0F86н	WRARH2	Wild register address setting register (Upper byte) ch.2	R/W	0000000В
0F87н	WRARL2	Wild register address setting register (Lower byte) ch.2	R/W	0000000В
0F88н	WRDR2	Wild register data setting register ch.2	R/W	0000000В
0F89н to 0F91н	_	(Disabled)		_
0F92н	T01CR0	8/16-bit compound timer 01 control status register 0 ch.0	R/W	0000000В
0F93н	T00CR0	8/16-bit compound timer 00 control status register 0 ch.0	R/W	0000000В
0F94н	T01DR	8/16-bit compound timer 01 data register ch.0	R/W	0000000В
0F95н	T00DR	8/16-bit compound timer 00 data register ch.0	R/W	0000000В
0F96н	TMCR0	8/16-bit compound timer 00/01 timer mode control register ch.0	R/W	0000000В
0F97н	T11CR0	8/16-bit compound timer 11 control status register 0 ch.1	R/W	0000000В
0F98н	T10CR0	8/16-bit compound timer 10 control status register 0 ch.1	R/W	0000000В
0F99н	T11DR	8/16-bit compound timer 11 data register ch.1	R/W	0000000В
0F9Ан	T10DR	8/16-bit compound timer 10 data register ch.1	R/W	0000000В
0F9Вн	TMCR1	8/16-bit compound timer 10/11 timer mode control register ch.1	R/W	00000000В
0F9Сн	PPS01	8/16-bit PPG1 cycle setting buffer register ch.0	R/W	11111111В
0F9Dн	PPS00	8/16-bit PPG0 cycle setting buffer register ch.0	R/W	11111111в
0F9Ен	PDS01	8/16-bit PPG1 duty setting buffer register ch.0	R/W	111111111в
0F9Fн	PDS00	8/16-bit PPG0 duty setting buffer register ch.0	R/W	11111111в
0FА0н	PPS11	8/16-bit PPG1 cycle setting buffer register ch.1	R/W	11111111В
0FA1н	PPS10	8/16-bit PPG0 cycle setting buffer register ch.1	R/W	11111111в
0FA2н	PDS11	8/16-bit PPG1 duty setting buffer register ch.1	R/W	11111111В
0FА3н	PDS10	8/16-bit PPG0 duty setting buffer register ch.1	R/W	11111111В
0FA4н	PPGS	8/16-bit PPG starting register	R/W	0000000В
0FА5н	REVC	8/16-bit PPG output inversion register	R/W	0000000В
0FA6н to 0FA9н	_	(Disabled)		_
0ГААн	PDCRH0	16-bit PPG down counter register (Upper byte) ch.0	R	0000000В
0ҒАВн	PDCRL0	16-bit PPG down counter register (Lower byte) ch.0	R	0000000В
0FACн	PCSRH0	16-bit PPG cycle setting buffer register (Upper byte) ch.0	R/W	11111111в
0FADн	PCSRL0	16-bit PPG cycle setting buffer register (Lower byte) ch.0	R/W	111111111в
0FAEн	PDUTH0	16-bit PPG duty setting buffer register (Upper byte) ch.0	R/W	111111111в
0FAFн	PDUTL0	16-bit PPG duty setting buffer register (Lower byte) ch.0	R/W	11111111В

## (Continued)

Address	Register abbreviation	Register name	R/W	Initial value
0FB0н to 0FBBн	_	(Disabled)	_	_
0FBCн	BGR1	LIN-UART baud rate generator register 1	R/W	0000000в
0FBDн	BGR0	LIN-UART baud rate generator register 0	R/W	0000000В
0FBЕн	PSSR0	UART/SIO dedicated baud rate generator prescaler selection register ch.0	R/W	0000000В
0FBFн	BRSR0	UART/SIO dedicated baud rate generator baud rate setting register ch.0	R/W	0000000В
0FC0н to 0FC2н	_	(Disabled)	_	_
0FС3 <sub>н</sub>	AIDRL	A/D input disable register (Lower byte)	R/W	0000000В
0FC4н to 0FE2н	_	(Disabled)	_	_
0FE3н	WCDR	Watch counter data register	R/W	00111111в
0FE4н to 0FE6н		(Disabled)	_	_
<b>0FE7</b> н	ILSR2	Input level select register 2	R/W	0000000В
0FE8н to 0FEDн		(Disabled)	_	_
0FEEн	ILSR	Input level select register	R/W	0000000В
0FEFн	WICR	Interrupt pin control register	R/W	01000000в
0FF0н to 0FFFн	_	(Disabled)	_	_

## • R/W access symbols

R/W : Readable/Writable

R : Read only W : Write only

## • Initial value symbols

0 : The initial value of this bit is "0".1 : The initial value of this bit is "1".

X : The initial value of this bit is undefined.

Note: Do not write to the "(Disabled)". Reading the "(Disabled)" returns an undefined value.

## **■ INTERRUPT SOURCE TABLE**

	Interrupt	Vector tab	le address	Bit name of	Same level
Interrupt source	request number	Upper	Lower	interrupt level setting register	priority order (atsimultaneous occurrence)
External interrupt ch.0	IRQ0	FFFA <sub>H</sub>	FFFB⊦ı	L00 [1 : 0]	High
External interrupt ch.4	IKQU	FFFAH	ГГГОН	L00 [1.0]	<b>A</b>
External interrupt ch.1	IRQ1	FFF8 <sub>H</sub>	FFF9 <sub>H</sub>	L01 [1 : 0]	
External interrupt ch.5	INQI	ГГГОН	ГГГЭН	LOT [T.O]	
External interrupt ch.2	IRQ2	FFF6 <sub>H</sub>	FFF7 <sub>H</sub>	L02 [1 : 0]	
External interrupt ch.6	IRQZ	ГГГОН	FFF/H	L02 [1 . 0]	
External interrupt ch.3	IRQ3	FFF4 <sub>H</sub>	FFF5 <sub>H</sub>	1.02 [4 - 0]	
External interrupt ch.7	IRQS		ГГГЭН	L03 [1 : 0]	
UART/SIO ch.0	IRQ4	FFF2 <sub>H</sub>	FFF3 <sub>H</sub>	L04 [1 : 0]	
8/16-bit compound timer ch.0 (Lower)	IRQ5	FFF0 <sub>H</sub>	FFF1 <sub>H</sub>	L05 [1 : 0]	
8/16-bit compound timer ch.0 (Upper)	IRQ6	FFEEH	FFEFH	L06 [1 : 0]	
LIN-UART (reception)	IRQ7	FFECH	FFEDH	L07 [1:0]	
LIN-UART (transmission)	IRQ8	FFEAH	FFEBH	L08 [1 : 0]	
8/16-bit PPG ch.1 (Lower)	IRQ9	FFE8 <sub>H</sub>	FFE9 <sub>H</sub>	L09 [1 : 0]	
8/16-bit PPG ch.1 (Upper)	IRQ10	FFE6 <sub>H</sub>	FFE7 <sub>H</sub>	L10 [1 : 0]	
(Unused)	IRQ11	FFE4 <sub>H</sub>	FFE5 <sub>H</sub>	L11 [1 : 0]	
8/16-bit PPG ch.0 (Upper)	IRQ12	FFE2 <sub>H</sub>	FFE3 <sub>H</sub>	L12 [1 : 0]	
8/16-bit PPG ch.0 (Lower)	IRQ13	FFE0 <sub>H</sub>	FFE1 <sub>H</sub>	L13 [1 : 0]	
8/16-bit compound timer ch.1 (Upper)	IRQ14	FFDEH	FFDF <sub>H</sub>	L14 [1 : 0]	
16-bit PPG ch.0	IRQ15	FFDCH	FFDDH	L15 [1 : 0]	
I <sup>2</sup> C ch.0	IRQ16	FFDA <sub>H</sub>	FFDB <sub>H</sub>	L16 [1 : 0]	
(Unused)	IRQ17	FFD8 <sub>H</sub>	FFD9 <sub>H</sub>	L17 [1 : 0]	
8/10-bit A/D converter	IRQ18	FFD6 <sub>H</sub>	FFD7 <sub>H</sub>	L18 [1 : 0]	
Timebase timer	IRQ19	FFD4 <sub>H</sub>	FFD5⊦	L19 [1 : 0]	
Watch timer/counter	IRQ20	FFD2 <sub>H</sub>	FFD3 <sub>H</sub>	L20 [1 : 0]	
(Unused)	IRQ21	FFD0 <sub>H</sub>	FFD1 <sub>H</sub>	L21 [1 : 0]	
8/16-bit compound timer ch.1 (Lower)	IRQ22	FFCEH	FFCFH	L22 [1 : 0]	▼
Flash memory	IRQ23	FFCCH	FFCDH	L23 [1 : 0]	Low

## **■ ELECTRICAL CHARACTERISTICS**

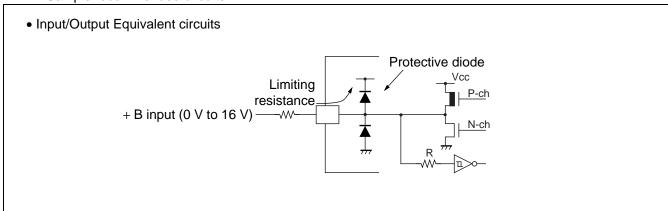
## 1. Absolute Maximum Ratings

Parameter	Cumbal	Rating		Unit	Domouleo		
Farameter	Symbol	Min	Max	Unit	Remarks		
Power supply voltage*1	Vcc AVcc	Vss - 0.3	Vss + 6.0	V	*2		
Input voltage*1	Vı	Vss - 0.3	Vss + 6.0	V	*3		
Output voltage*1	Vo	Vss - 0.3	Vss + 6.0	V	*3		
Maximum clamp current	CLAMP	- 2.0	+ 2.0	mA	Applicable to pins*4		
Total maximum clamp current	$\Sigma  I_CLAMP $	_	20	mA	Applicable to pins*4		
"L" level maximum	lol1		15	mΛ	Other than P00 to P07		
output current	l <sub>OL2</sub>	] —	15	mA	P00 to P07		
"L" level average	lolav1		4	mA	Other than P00 to P07 Average output current = operating current × operating ratio (1 pin)		
current	lolav2		12	IIIA	P00 to P07 Average output current = operating current × operating ratio (1 pin)		
"L" level total maximum output current	$\Sigma$ loL	_	100	mA			
"L" level total average output current	$\Sigma$ lolav	_	50	mA	Total average output current = operating current × operating ratio (Total of pins)		
"H" level maximum	<b>І</b> он1		<b>– 15</b>	Л	Other than P00 to P07		
output current	<b>I</b> OH2	<u> </u>	<b>– 15</b>	mA	P00 to P07		
"H" level average	Iонаv1		- 4	· mA	Other than P00 to P07 Average output current = operating current × operating ratio (1 pin)		
current	Iонаv2			1 IIIA	P00 to P07 Average output current = operating current × operating ratio (1 pin)		
"H" level total maximum output current	$\Sigma$ Іон	_	- 100	mA			
"H" level total average output current	$\Sigma$ lohav	_	- 50	mA	Total average output current = operating current × operating ratio (Total of pins)		

### (Continued)

Parameter	Symbol	Rat	Rating		Remarks
rarameter	Syllibol	Min	Max	Unit	Kemarks
Power consumption	Pd	_	320	mW	
Operating temperature	TA	<b>- 40</b>	+ 85	°C	
Storage temperature	Tstg	<b>– 55</b>	+ 150	°C	

- \*1 : The parameter is based on AVss = Vss = 0.0 V.
- \*2 : Apply equal potential to AVcc and Vcc.
- \*3 :  $V_1$  and  $V_2$  should not exceed  $V_{CC} + 0.3$  V.  $V_1$  must not exceed the rating voltage. However, if the maximum current to/from an input is limited by some means with external components, the  $I_{CLAMP}$  rating supersedes the  $V_1$  rating.
- \*4 : Applicable to pins : P00 to P07, P10 to P15, P20 to P24, P30 to P37, P60 to P67
  - Use within recommended operating conditions.
  - Use at DC voltage (current).
  - +B signal is an input signal that exceeds Vcc voltage. The + B signal should always be applied a limiting resistance placed between the + B signal and the microcontroller.
  - The value of the limiting resistance should be set so that when the + B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
  - Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input
    potential may pass through the protective diode and increase the potential at the Vcc pin, and this affects
    other devices.
  - Note that if the + B signal is inputted when the microcontroller power supply is off (not fixed at 0 V), the power supply is provided from the pins, so that incomplete operation may result.
  - Note that if the + B input is applied during power-on, the power supply is provided from the pins and the resulting power supply voltage may not be sufficient to operate the power-on reset.
  - Care must be taken not to leave the + B input pin open.
  - Sample recommended circuits :



WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

## 2. Recommended Operating Conditions

(AVss = Vss = 0.0 V)

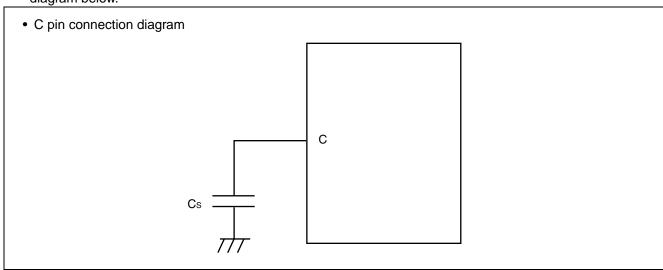
Parameter	Symbol Pin name		Condi- Value		Unit	it Remarks		
Parameter	Syllibol	Pili liaille	tions	Min	Max	Offic	Remarks	
				2.5*1	5.5	V	In normal operation	Other than
Power supply	Vcc,			2.3	5.5	V	Hold condition in STOP mode	MB95FV100D- 103
voltage	AVcc	_	_	2.7	5.5	V	In normal operation	MB95FV100D-
				2.3	5.5	٧	Hold condition in STOP mode	103
	V <sub>IH1</sub>	P10, P67	*2	0.7 Vcc	Vcc + 0.3	V	At selecting of CMOS input level	
	V <sub>IH2</sub>	P50, P51	*2	0.7 Vcc	Vss + 5.5	V	At selecting of CMOS inpulevel	
	VIHA	_	_	0.8 Vcc	Vcc + 0.3	V	Pin input at s	electing of /E input level
"H" level input voltage	V <sub>IHS1</sub>	P00 to P07, P10 to P15, P20 to P24, P30 to P37, P60 to P67, PG1*3, PG2*3	*2	0.8 Vcc	Vcc + 0.3	V	Hysteresis input	
	V <sub>IHS2</sub>	P50, P51	*2	0.8 Vcc	Vss + 5.5	V	Hysteresis in	put
	V <sub>IHM</sub> RS	RST, MOD		0.7 Vcc	Vcc + 0.3	V	CMOS input (Flash memo	ory product)
		#W KSI, WOD		0.8 Vcc	Vcc + 0.3	V	Hysteresis input (MASK ROM product)	

(Continued)

(AVss = Vss = 0.0 V)

Parameter	Symbol Pin name		Condi-	Val	lue	Unit	Remarks
Farameter	Syllibol	riii iiaiiie	tions	Min	Max	Oilit	Kemarks
	VIL	P10, P50, P51, P67	*2	Vss - 0.3	0.3 Vcc	V	At selecting of CMOS input level
	VILA	_	_	Vss - 0.3	0.5 Vcc	V	Pin input at selecting of AUTOMOTIVE input level
"L" level input voltage	VILS	P00 to P07, P10 to P15, P20 to P24, P30 to P37, P50, P51, P60 to P67, PG1*3, PG2*3	*2	Vss - 0.3	0.2 Vcc	V	Hysteresis input
	VILM	DST MOD	_	Vss - 0.3	0.3 Vcc	V	CMOS input (Flash memory product)
		RST, MOD	_	Vss - 0.3	0.2 Vcc	V	Hysteresis input (MASK ROM product)
Smoothing capacitor	Cs	_	_	0.1	1.0	μF	*4
Operating	TA			- 40	+ 85	°C	Other than MB95FV100D-103
temperature	IA			+ 5	+ 35	°C	MB95FV100D-103

- \*1 : The value is 2.9 V when the low voltage detection reset is used.
- \*2 : P10, P50, P51, and P67 can switch the input level to either the "CMOS input level" or "hysteresis input level". The switching of the input level can be set by the input level selection register (ILSR).
- \*3: Single clock products only
- \*4: Use a ceramic capacitor or a capacitor with equivalent frequency characteristics. A bypass capacitor of Vcc pin must have a capacitance value higher than Cs. For connection of smoothing capacitor Cs, refer to the diagram below.



WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

## 3. DC Characteristics

(Vcc = AVcc = 5.0 V  $\pm$  10%, AVss = Vss = 0.0 V, T<sub>A</sub> = - 40 °C to + 85 °C)

Downwater	Sym- bol	Din name	(VCC = AVCC = 3.0	Value				,
Parameter		Pin name	Conditions	Min Typ		Max	Unit	Remarks
"H" level output voltage	Vон1	Output pin other than P00 to P07	Іон = - 4.0 mA	Vcc - 0.5	_	_	٧	
	V <sub>OH2</sub>	P00 to P07	$I_{OH} = -8.0 \text{ mA}$	Vcc - 0.5	_	_	V	
"L" level output voltage	V <sub>OL1</sub>	Output pin other than P00 to P07	IoL = 4.0 mA	_		0.4	V	
	V <sub>OL2</sub>	P00 to P07	IoL = 12 mA			0.4	٧	
Open-drain out- put application voltage	VD	P50, P51	_	Vss - 0.3		Vss + 5.5	V	
Input leakage current (Hi-Z output leakage current)	lu	Port other than P50, P51	0.0 V < Vı < Vcc	- 5	_	+ 5	μА	When the pull-up prohibition setting
Open-drain output leakage current	ILIOD	P50, P51	0.0 V < V <sub>I</sub> < Vss + 5.5 V	_	_	5	μΑ	
Pull-up resistor	Rpull	P10 to P15, P20 to P24, P30 to P37, PG1*1, PG2*1	Vı = 0.0 V	25	50	100	kΩ	When the pull-up permission setting
Pull-down resistor	Rмор	MOD	Vı = Vcc	25	50	100	kΩ	MASK ROM product
Power supply current*2	lcc	Vcc (External clock operation)	Vcc = 5.5 V FcH = 20 MHz FMP = 10 MHz Main clock mode (divided by 2)		9.5	12.5	mA	Flash memory product (at other than Flash memory writing and erasing)
				_	30	35	mA	Flash memory product (at Flash memory writing and erasing)
					7.2	9.5	mA	MASK ROM product
			Vcc = 5.5 V FcH = 32 MHz FMP = 16 MHz Main clock mode (divided by 2)	_	15.2	20.0	mA	Flash memory product (at other than Flash memory writing and erasing)
				_	35.7	42.5	mA	Flash memory product (at Flash memory writing and erasing)
				_	11.6	15.2	mA	MASK ROM product

(Vcc = AVcc = 5.0 V  $\pm$  10%, AVss = Vss = 0.0 V, T\_A = - 40 °C to + 85 °C)

Parameter	Sym- bol	Pin name	Conditions	Value			Unit	Domorko
			Conditions	Min	Тур	Max	Unit	Remarks
Power supply current*2	Iccs	Vcc (External clock operation) *2	Vcc = 5.5 V FcH = 20 MHz FMP = 10 MHz Main sleep mode (divided by 2)	_	4.5	7.5	mA	
			Vcc = 5.5 V FcH = 32 MHz FMP = 16 MHz Main sleep mode (divided by 2)	_	7.2	12.0	mA	
	IccL		$Vcc = 5.5 V$ $FcL = 32 \text{ kHz}$ $F_{MPL} = 16 \text{ kHz}$ Sub clock mode (divided by 2), $T_{A} = +25 \text{ °C}$	_	45	100	μΑ	
	Iccls		$V_{CC} = 5.5 \text{ V}$ $F_{CL} = 32 \text{ kHz}$ $F_{MPL} = 16 \text{ kHz}$ Sub sleep mode (divided by 2), $T_{A} = +25 \text{ °C}$	_	10	81	μА	
	Ісст		Vcc = 5.5 V FcL = 32 kHz Watch mode Main stop mode T <sub>A</sub> = +25 °C	_	4.6	27	μΑ	
	ICCMPLL		Vcc = 5.5 V FcH = 4 MHz FMP = 10 MHz Main PLL mode (multiplied by 2.5)		9.3	12.5	mA	Flash memory product
				_	7.0	9.5	mA	MASK ROM product
			Vcc = 5.5 V FcH = 6.4 MHz FMP = 16 MHz Main PLL mode (multiplied by 2.5)		14.9	20.0	mA	Flash memory product
				_	11.2	15.2	mA	MASK ROM product

(Continued)

(Vcc = AVcc = 5.0 V  $\pm$  10%, AVss = Vss = 0.0 V, T<sub>A</sub> = -40 °C to +85 °C)

Parameter	Sym- bol	Pin name	Conditions	Value			Unit	Remarks
				Min	Тур	Max	UIII	Remarks
Power supply current*2	Iccspll	Vcc (External clock operation) *2	$V_{CC} = 5.5 \text{ V}$ $F_{CL} = 32 \text{ kHz}$ $F_{MPL} = 128 \text{ kHz}$ Sub PLL mode (multiplied by 4) $T_A = +25 \text{ °C}$		160	400	μА	
	Істѕ		$V_{CC} = 5.5 \text{ V}$ $F_{CH} = 10 \text{ MHz}$ Timebase timer mode $T_A = +25 \text{ °C}$	_	0.15	1.10	mA	
			Vcc = 5.5 V FcH = 16 MHz Timebase timer mode TA = +25 °C	_	0.24	1.76	mA	
	Іссн		$V_{CC} = 5.5 \text{ V}$ Sub stop mode $T_A = +25 \text{ °C}$		5	20	μΑ	Main stop mode for single clock product
	ILVD	Vcc	Current consumption for low voltage detection circuit only	_	38	50	μΑ	
	la	AVcc	Vcc = 5.5 V FcH = 16 MHz At operating of A/D conversion	_	2.4	4.7	mA	
	Іан		Vcc = 5.5 V FcH = 16 MHz At stopping A/D conversion TA = +25 °C	_	1	5	μА	
Input capacitance	Cin	Other than AVcc, AVss, Vcc, Vss	f = 1 MHz		5	15	pF	

<sup>\*1:</sup> Single clock product only

<sup>\*2: •</sup> The power-supply current is determined by the external clock. When both low voltage detection option is selected, the power-supply current will be a value of adding current consumption of the low voltage detection circuit (ILVD) to the specified value.

<sup>•</sup> Refer to "4. AC Characteristics (1) Clock Timing" for Fch and Fcl.

<sup>•</sup> Refer to "4. AC Characteristics (2) Source Clock/Machine Clock" for FMP and FMPL.

### 4. AC Characteristics

### (1) Clock Timing

(Vcc = 2.5 V to 5.5 V, AVss = Vss = 0.0 V,  $T_A = -40$  °C to +85 °C)

Parameter	Sym-	Pin name	Condi-		Value		Unit	Remarks
Parameter	bol	Pili liallie	tions	Min	Тур	Max	Offic	Remarks
				1.00	_	16.25	MHz	When using main oscillation circuit
	_	V0 V4		1.00		32.50	MHz	When using external clock
	Fсн	X0, X1		3.00		16.25	MHz	Main PLL multiplied by 1
Clock frequency				3.00		8.13	MHz	Main PLL multiplied by 2
, , ,				3.00		6.50	MHz	Main PLL multiplied by 2.5
	FcL	X0A, X1A		_	32.768		kHz	When using sub oscillation circuit
					32.768		kHz	When using sub PLL Vcc = 2.3 V to 3.6 V
	<b>t</b> HCYL	X0, X1	_	61.5	_	1000	ns	When using main oscillation circuit
Clock cycle time				30.8		1000	ns	When using external clock
	<b>t</b> LCYL	X0A, X1A		_	30.5		μs	When using sub oscillation circuit
Input clock pulse width	twH1	X0		61.5	_		ns	When using external clock  Duty ratio is about 30% to
input clock pulse width	twH2	X0A			15.2		μs	70%.
Input clock rise time and fall time	tcr tcf	X0, X0A				5	ns	When using external clock

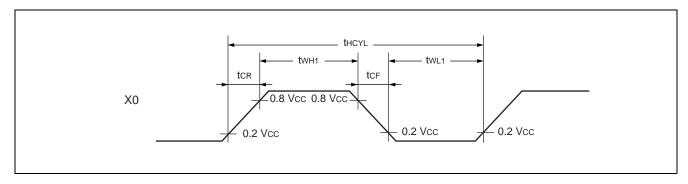


Figure of main clock input port external connection

When using a crystal or ceramic oscillator

Microcontroller

X0 X1

When using external clock

Microcontroller

X0 X1

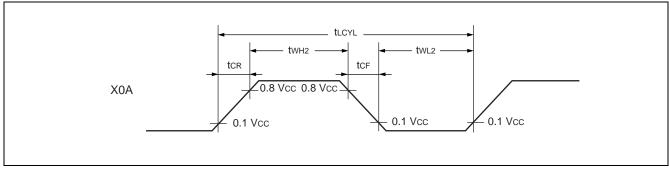
Open

FCH

FCH

FCH

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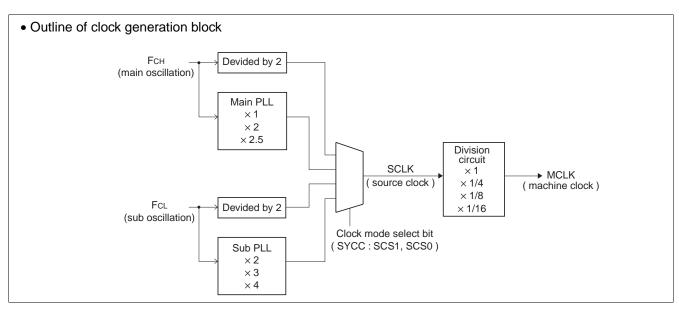


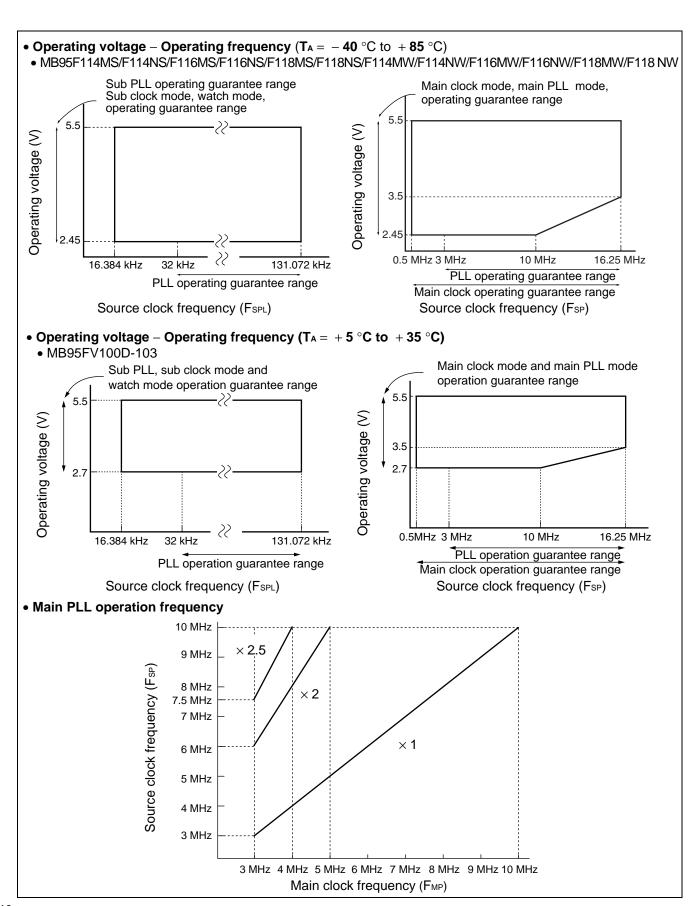
#### (2) Source Clock/Machine Clock

$$(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$$

Parameter	Sym-	Pin		Value		Unit	Remarks
rarameter	bol	name	Min	Тур	Max	Oiii	Remarks
Source clock cycle time*1	<b>t</b> sclk		61.5	_	2000	ns	When using main clock Min: FcH = 16.25 MHz, PLL multiplied by 1 Max: FcH = 1 MHz, divided by 2
(Clock before setting division)	ISCLK	_	7.6	_	61.0	μs	When using sub clock Min: FcL = 32 kHz, PLL multiplied by 4 Max: FcL = 32 kHz, divided by 2
Source clock frequency	Fsp		0.50		16.25	MHz	When using main clock
Source clock frequency	FSPL		16.384		131.072	kHz	When using sub clock
Machine clock cycle time*2	<b>t</b> MCLK		61.5	_	32000	ns	When using main clock Min: F <sub>SP</sub> = 16.25 MHz, no division Max: F <sub>SP</sub> = 0.5 MHz, divided by 16
(Minimum instruction execution time)	IMCLK		7.6	_	976.5	•	When using sub clock Min: F <sub>SPL</sub> = 131 kHz, no division Max: F <sub>SPL</sub> = 16 kHz, divided by 16
Machine clock	F <sub>MP</sub>		0.031		16.250	MHz	When using main clock
frequency	FMPL		1.024		131.072	kHz	When using sub clock

- \*1: Clock before setting division due to machine clock division ratio selection bit (SYCC: DIV1 and DIV0). This source clock is divided by the machine clock division ratio selection bit (SYCC: DIV1 and DIV0), and it becomes the machine clock. Further, the source clock can be selected as follows.
  - Main clock divided by 2
  - PLL multiplication of main clock (select from 1, 2, 2.5 multiplication)
  - Sub clock divided by 2
  - PLL multiplication of sub clock (select from 2, 3, 4 multiplication)
- \*2: Operation clock of the microcontroller. Machine clock can be selected as follows.
  - Source clock (no division)
  - · Source clock divided by 4
  - Source clock divided by 8
  - Source clock divided by 16



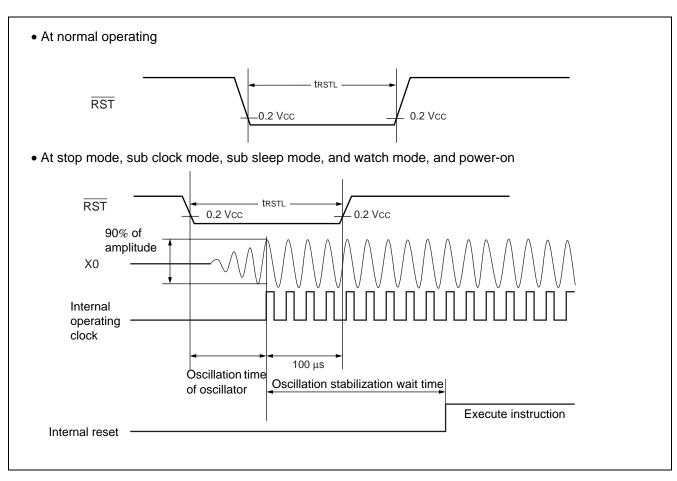


#### (3) External Reset

$$(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$$

Parameter	Symbol	Value		Unit	Remarks
Farameter	Symbol	Min	Max	Oilit	Kemarks
		2 tмськ*1	_	ns	At normal operating
RST "L" level pulse width	<b>t</b> RSTL	trestl Oscillation time of oscillator* + 100		μs	At stop mode, sub clock mode, sub sleep mode, and watch mode
		100		μs	At timebase timer mode

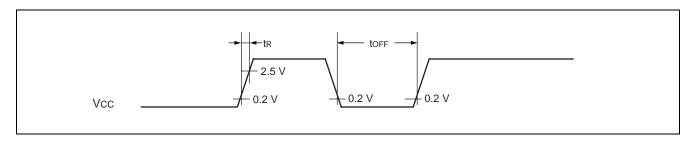
- \*1 : Refer to "(2) Source Clock/Machine Clock" for tmclk.
- $^*2$ : Oscillation start time of oscillator is the time that the amplitude reaches 90 %. In the crystal oscillator, the oscillation time is between several ms and tens of ms. In ceramic oscillators, the oscillation time is between hundreds of  $\mu$ s and several ms. In the external clock, the oscillation time is 0 ms.



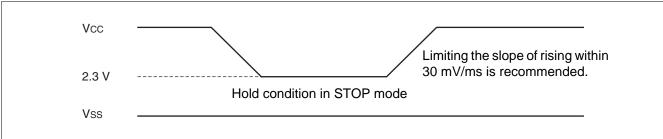
#### (4) Power-on Reset

(AVss = Vss = 0.0 V, 
$$T_A = -40 \, ^{\circ}\text{C}$$
 to  $+85 \, ^{\circ}\text{C}$ )

Parameter	Symbol	Conditions	Val	lue	Unit	Remarks	
Faranteter	Syllibol	Conditions	Min	lin Max		Nemarks	
Power supply rising time	<b>t</b> R		_	50	ms		
Power supply cutoff time	toff	_	1		ms	Waiting time until power-on	



Note: Sudden change of power supply voltage may activate the power-on reset function. When changing power supply voltages during operation, set the slope of rising within 30 mV/ms as shown below.

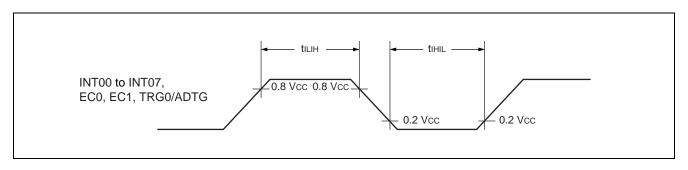


#### (5) Peripheral Input Timing

(Vcc = 5.0 V  $\pm$  10%, AVss = Vss = 0.0 V, T<sub>A</sub> = -40 °C to +85 °C)

Parameter	Symbol	Pin name	Va	lue	Unit	Remarks
raiailletei	Symbol	r III IIailie	Min	Max	Oilit	
Peripheral input "H" pulse width	tı∟ıн	INT00 to INT07,	2 tмськ*	_	ns	
Peripheral input "L" pulse width	tıнı∟	EC0, EC1, TRG0/ADTG	2 tмськ*	_	ns	

<sup>\*:</sup> Refer to "(2) Source Clock/Machine Clock" for tmclk.

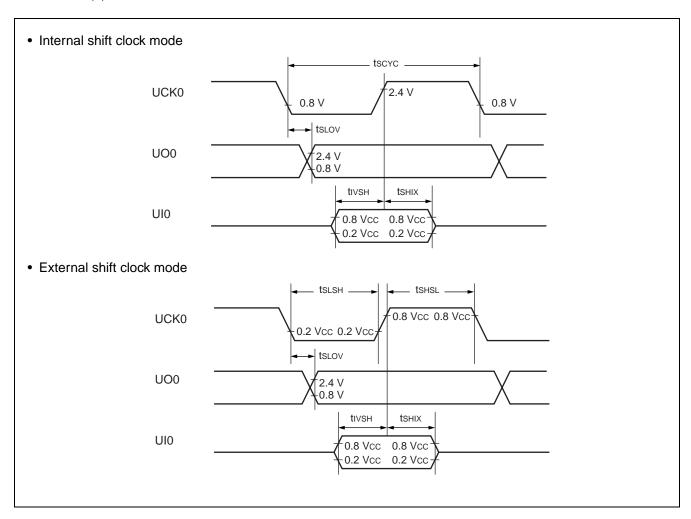


#### (6) UART/SIO, Serial I/O Timing

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_A = -40 \,^{\circ}\text{C to } +85 \,^{\circ}\text{C})$ 

Parameter	Symbol	Pin name	Conditions	Va	lue	Unit	Remarks	
Parameter	Symbol	riii iiaiiie	Conditions	Min	Max	Ullit	ixemarks	
Serial clock cycle time	tscyc	UCK0	Internal	<b>4 t</b> мськ*	_	ns		
$UCK\ \downarrow \to UO\ time$	tsLov	UCK0, UO0	clock operation	- 190	+ 190	ns		
Valid UI → UCK ↑	tıvsн	UCK0, UI0	Output pin:	2 <b>t</b> мськ*	_	ns		
UCK $\uparrow \rightarrow$ valid UI hold time	<b>t</b> shix	UCK0, UI0	C∟ = 80 pF + 1TTL.	2 <b>t</b> mcLK*	_	ns		
Serial clock "H" pulse width	<b>t</b> shsl	UCK0	External	<b>4 t</b> мськ*	_	ns		
Serial clock "L" pulse width	<b>t</b> slsh	UCK0	clock	<b>4 t</b> мськ*	_	ns		
$UCK\downarrow \to UO$ time	<b>t</b> sLov	UCK0, UO0	operation Output pin:		190	ns		
Valid UI → UCK ↑	<b>t</b> ıvsh	UCK0, UI0	C <sub>L</sub> = 80 pF	<b>2 t</b> мськ*	_	ns		
UCK $\uparrow \rightarrow$ valid UI hold time	<b>t</b> shix	UCK0, UI0	+ 1TTL.	2 <b>t</b> мськ*	_	ns		

<sup>\*:</sup> Refer to "(2) Source Clock/Machine Clock" for tmclk.



#### (7) LIN-UART Timing

Sampling at the rising edge of sampling clock\*1 and prohibited serial clock delay\*2

(ESCR register : SCES bit = 0, ECCR register : SCDE bit = 0)

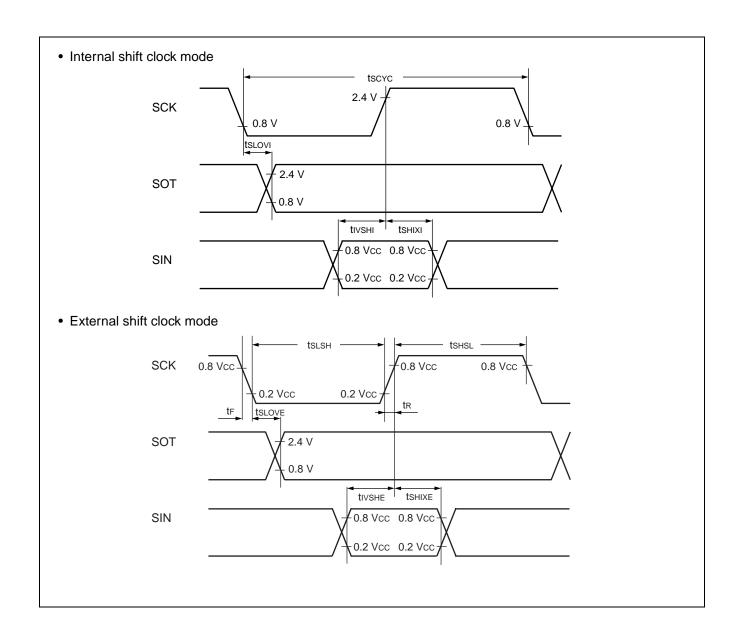
 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$ 

Parameter	Sym-	Pin name	Conditions	Va	lue	Unit
Farameter	bol	Fill Hallie	Conditions	Min	Max	Oilit
Serial clock cycle time	tscyc	SCK		<b>5 t</b> мськ* <sup>3</sup>	_	ns
$SCK \downarrow \to SOT$ delay time	tslovi	SCK, SOT	Internal clock operation output pin:	-95	+ 95	ns
Valid SIN $\rightarrow$ SCK $↑$	tıvsнı	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	tмськ*3 + 190	_	ns
$SCK \uparrow \rightarrow valid SIN hold time$	<b>t</b> shixi	SCK, SIN		0	_	ns
Serial clock "L" pulse width	<b>t</b> slsh	SCK		3 tмськ*3 — tR	_	ns
Serial clock "H" pulse width	tshsl	SCK		tмськ*3 + 95	_	ns
$SCK \downarrow \to SOT$ delay time	tslove	SCK, SOT	External clock	_	2 tmclk*3 + 95	ns
Valid SIN → SCK ↑	tivshe	SCK, SIN	operation output pin:	190	_	ns
$SCK \uparrow \rightarrow valid SIN hold time$	tshixe	SCK, SIN	C <sub>L</sub> = 80 pF + 1 TTL.	tмськ*3 + 95	_	ns
SCK fall time	t⊧	SCK		_	10	ns
SCK rise time	<b>t</b> R	SCK			10	ns

<sup>\*1 :</sup> Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.

<sup>\*2 :</sup> Serial clock delay function is used to delay half clock for the output signal of serial clock.

<sup>\*3:</sup> Refer to "(2) Source Clock/Machine Clock" for tmclk.



#### Sampling at the falling edge of sampling clock<sup>1</sup> and prohibited serial clock delay<sup>2</sup>

(ESCR register : SCES bit = 1, ECCR register : SCDE bit = 0)

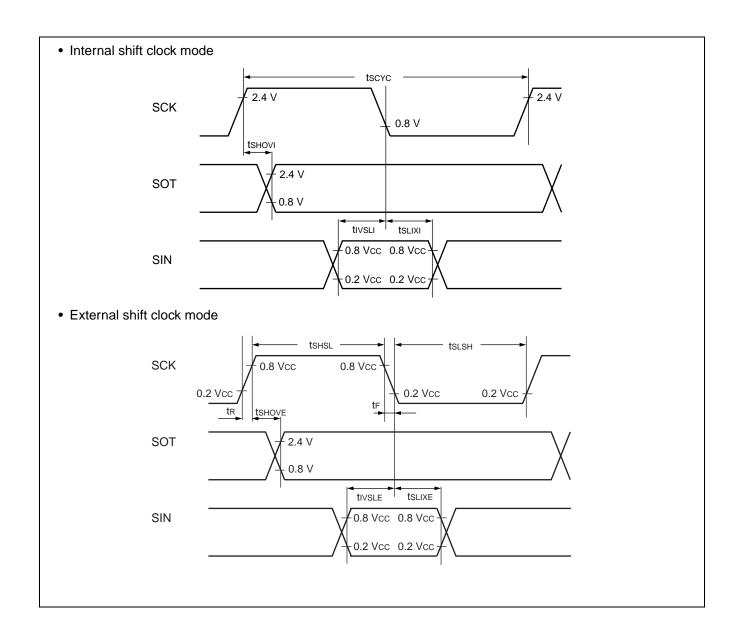
 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$ 

Parameter	Sym-	Pin name	n name Conditions		lue	Unit
Farameter	bol	Finitianie	Conditions	Min	Max	Ollit
Serial clock cycle time	tscyc	SCK		<b>5 t</b> мськ* <sup>3</sup>	_	ns
$SCK \uparrow \rightarrow SOT$ delay time	<b>t</b> shovi	SCK, SOT	Internal clock operation output pin:	<b>-95</b>	+ 95	ns
Valid SIN $\rightarrow$ SCK $↓$	<b>t</b> ıvslı	SCK, SIN	C <sub>L</sub> = 80 pF + 1 TTL.	tмськ*3 + 190	_	ns
$SCK \downarrow \to valid \; SIN \; hold \; time$	<b>t</b> slixi	SCK, SIN		0		ns
Serial clock "H" pulse width	<b>t</b> shsl	SCK		3 tмсLк*3 − tR	_	ns
Serial clock "L" pulse width	<b>t</b> slsh	SCK		<b>t</b> мськ*3 + 95	_	ns
$SCK \uparrow \to SOT$ delay time	<b>t</b> shove	SCK, SOT	External clock	_	2 tmclk*3 + 95	ns
Valid SIN $\rightarrow$ SCK $↓$	tivsle	SCK, SIN	operation output pin :	190	_	ns
$SCK \downarrow \to valid \; SIN \; hold \; time$	<b>t</b> SLIXE	SCK, SIN	C <sub>L</sub> = 80 pF + 1 TTL.	<b>t</b> мськ*3 + 95	_	ns
SCK fall time	t⊧	SCK		_	10	ns
SCK rise time	<b>t</b> R	SCK			10	ns

<sup>\*1 :</sup> Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.

<sup>\*2 :</sup> Serial clock delay function is used to delay half clock for the output signal of serial clock.

<sup>\*3:</sup> Refer to "(2) Source Clock/Machine Clock" for tmclk.



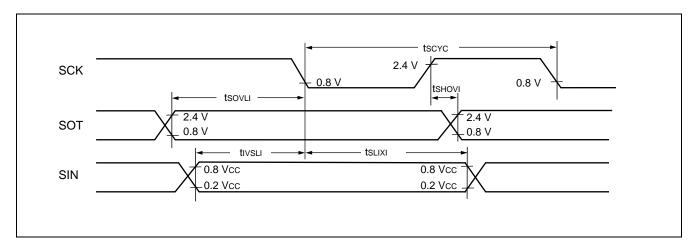
#### Sampling at the rising edge of sampling clock\*1 and enabled serial clock delay\*2

(ESCR register : SCES bit = 0, ECCR register : SCDE bit = 1)

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$ 

Parameter	Sym-	Pin name	Conditions	Val	Unit		
Parameter	bol	Pin name	Conditions	Min	Max	Oilit	
Serial clock cycle time	tscyc	SCK		<b>5 t</b> мськ* <sup>3</sup>	_	ns	
$SCK \uparrow \to SOT$ delay time	<b>t</b> shovi	SCK, SOT	Internal clock	-95	+ 95	ns	
Valid SIN $\rightarrow$ SCK $↓$	tıvslı	SCK, SIN	operation output pin :	tмськ*3 + 190		ns	
$SCK \downarrow \rightarrow valid SIN hold time$	<b>t</b> slixi	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	0		ns	
$SOT \to SCK \downarrow delay \; time$	<b>t</b> sovli	SCK, SOT		_	4 tmclk*3	ns	

- \*1 : Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.
- \*2 : Serial clock delay function is used to delay half clock for the output signal of serial clock.
- \*3: Refer to "(2) Source Clock/Machine Clock" for tmclk.



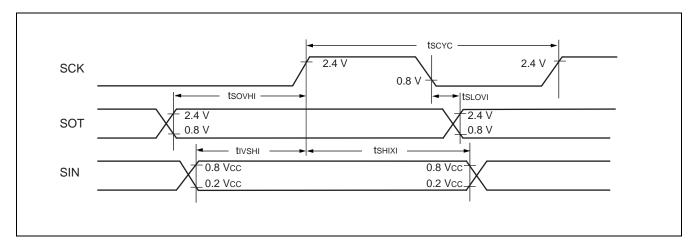
#### Sampling at the falling edge of sampling clock<sup>1</sup> and enabled serial clock delay<sup>2</sup>

(ESCR register : SCES bit = 1, ECCR register : SCDE bit = 1)

 $(Vcc = 5.0 \text{ V} \pm 10\%, \text{ AVss} = \text{Vss} = 0.0 \text{ V}, \text{ T}_{A} = -40 \,^{\circ}\text{C to } + 85 \,^{\circ}\text{C})$ 

Parameter	Sym-	Din nama	Conditions	Valu	Unit	
Parameter	bol	Pin name	Conditions	Min	Max	Onit
Serial clock cycle time	tscyc	SCK		<b>5 t</b> мськ* <sup>3</sup>	_	ns
$SCK \downarrow \to SOT$ delay time	tslovi	SCK, SOT	Internal clock	-95	+ 95	ns
Valid SIN → SCK ↑	tıvsнı	SCK, SIN	operating output pin:	tмськ*3 + 190	_	ns
$SCK \uparrow \to valid \; SIN \; hold \; time$	<b>t</b> shixi	SCK, SIN	$C_L = 80 \text{ pF} + 1 \text{ TTL}.$	0	_	ns
SOT → SCK ↑ delay time	<b>t</b> sovнı	SCK, SOT			4 tmclk*3	ns

- \*1 : Provide switch function whether sampling of reception data is performed at rising edge or falling edge of the serial clock.
- \*2 : Serial clock delay function is used to delay half clock for the output signal of serial clock.
- \*3: Refer to "(2) Source Clock/Machine Clock" for tmclk.

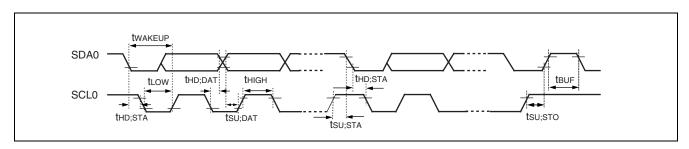


#### (8) I2C Timing

(Vcc = 5.0 V 
$$\pm$$
 10%, AVss = Vss = 0.0 V, TA =  $-40$  °C to  $+85$  °C)

					Val	ue			
Parameter	Symbol	Pin name	Conditions	Standard- mode		Fast-mode		Unit	Remarks
				Min	Max	Min	Max		
SCL clock frequency	fscL	SCL0		0	100	0	400	kHz	
(Repeat) Start condition hold time SDA $\downarrow$ $\rightarrow$ SCL $\downarrow$	<b>t</b> hd;sta	SCL0 SDA0		4.0	_	0.6	_	μs	
SCL clock "L" width	<b>t</b> LOW	SCL0		4.7	_	1.3	_	μs	
SCL clock "H" width	<b>t</b> HIGH	SCL0		4.0	_	0.6	_	μs	
(Repeat) Start condition setup time SCL $\uparrow \rightarrow$ SDA $\downarrow$	<b>t</b> su;sta	SCL0 SDA0	$R = 1.7 \text{ k}\Omega,$	4.7	_	0.6	_	μs	
Data hold time SCL $\downarrow$ $\rightarrow$ SDA $\downarrow$ $\uparrow$	<b>t</b> hd;dat	SCL0 SDA0	$C = 50 \text{ pF}^{*1}$	0	3.45*2	0	0.9*3	μs	
Data setup time SDA $\downarrow \uparrow \rightarrow$ SCL $\uparrow$	<b>t</b> su;dat	SCL0 SDA0		0.25	_	0.1		μs	
Stop condition setup time SCL $\uparrow \rightarrow$ SDA $\uparrow$	<b>t</b> su;sто	SCL0 SDA0		4		0.6		μs	
Bus free time between stop condition and start condition	<b>t</b> BUF	SCL0 SDA0		4.7		1.3		μs	

- \*1: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.
- \*2: The maximum thd; DAT have only to be met if the device dose not stretch the "L" width (tLOW) of the SCL signal.
- \*3 : A fast-mode I<sup>2</sup>C-bus device can be used in a standard-mode I<sup>2</sup>C-bus system, but the requirement  $t_{SU;DAT} \ge 250$  ns must then be met.



(Vcc = 5.0 V  $\pm$  10%, AVss = Vss = 0.0 V, T<sub>A</sub> = -40 °C to + 85 °C)

Barramatar	Sym-	Pin	0 110	Valu	ıe*²	11	B
Parameter	bol	name	Condition	Min	Max	Unit	Remarks
SCL clock "L" width	tLOW	SCL0		(2 + nm / 2) tmclk - 20	_	ns	Master mode
SCL clock "H" width	<b>t</b> HIGH	SCL0		(nm / 2) tmclk - 20	(nm / 2 ) tmcLK + 20	ns	Master mode
Start condition hold time	thd;sta	SCL0 SDA0		(-1 + nm / 2) tmcLK - 20	(-1 + nm) t <sub>MCLK</sub> + 20	ns	Master mode Maximum value is applied when m, n = 1, 8. Otherwise, the minimum value is applied.
Stop condition setup time	<b>t</b> su;sто	SCL0 SDA0		(1 + nm / 2) tmcLK - 20	(1 + nm / 2) t <sub>MCLK</sub> + 20	ns	Master mode
Start condition setup time	<b>t</b> su;sta	SCL0 SDA0		(1 + nm / 2) tmcLK - 20	(1 + nm / 2) t <sub>MCLK</sub> + 20	ns	Master mode
Bus free time between stop condition and start condition	<b>t</b> BUF	SCL0 SDA0		(2 nm + 4) tmcLK - 20		ns	
Data hold time	<b>t</b> hd;dat	SCL0 SDA0		3 tмс∟к — 20	_	ns	Master mode
Data setup time	tsu;dat	SCL0 SDA0	$R = 1.7 \text{ k}\Omega$ , $C = 50 \text{ pF}^{*1}$	(-2 + nm / 2) t <sub>MCLK</sub> - 20	(-1 + nm / 2) tmcLK + 20	ns	Master mode When assuming that "L" of SCL is not extended, the minimum value is applied to first bit of continuous data. Otherwise, the maximum value is applied.
Setup time between clearing interrupt and SCL rising	tsu;int	SCL0		(nm / 2) t <sub>MCLK</sub> — 20	(1 + nm / 2) tmcLK + 20	ns	Minimum value is applied to interrupt at 9th SCL↓. Maximum value is applied to interrupt at 8th SCL↓.
SCL clock "L" width	tLOW	SCL0		4 tmclk - 20	_	ns	At reception
SCL clock "H" width	<b>t</b> HIGH	SCL0		4 tmclk — 20	<u> </u>	ns	At reception
Start condition detection	<b>t</b> hd;sta	SCL0 SDA0		2 tmclk - 20	_	ns	Undetected when 1 tmclk is used at reception
Stop condition detection	<b>t</b> su;sто	SCL0 SDA0		2 tmcLK - 20	_	ns	Undetected when 1 tmclk is used at reception
Restart condition detection condition	<b>t</b> su;sta	SCL0 SDA0		2 tmcLK - 20	_	ns	Undetected when 1 t <sub>MCLK</sub> is used at reception
Bus free time	<b>t</b> BUF	SCL0 SDA0		2 tmclk - 20	_	ns	At reception
Data hold time	<b>t</b> hd;dat	SCL0 SDA0		2 tmclk - 20	_	ns	At slave transmission mode
Data setup time	<b>t</b> su;dat	SCL0 SDA0		tLOW - 3 tMCLK - 20	_	ns	At slave transmission mode

(Continued)

#### (Continued)

(Vcc = 5.0 V 
$$\pm$$
 10%, AVss = Vss = 0.0 V, TA = -40 °C to +85 °C)

Parameter	Sym-	Pin	Condition	Value*2	Unit	Remarks	
i arameter	bol	name	Condition	Min	Max	Oilit	Kemarks
Data hold time	thd;dat	SCL0 SDA0		0	_	ns	At reception
Data setup time	tsu;dat		$R = 1.7 \text{ k}\Omega,$ $C = 50 \text{ pF}^{*1}$	tмськ — 20	_	ns	At reception
SDA↓→SCL↑ (at wake-up function)	<b>t</b> WAKEUP	SCL0	о оор.	Oscillation stabilization wait time + 2 tmclk - 20	_	ns	

- \*1: R, C: Pull-up resistor and load capacitor of the SCL and SDA lines.
- \*2: Refer to "(2) Source Clock/Machine Clock" for tmclk.
  - m is CS4 bit and CS3 bit (bit 4 and bit 3) of clock control register (ICCR0).
  - n is CS2 bit to CS0 bit (bit 2 to bit 0) of clock control register (ICCR0) .
  - Actual timing of I<sup>2</sup>C is determined by m and n values set by the machine clock (t<sub>MCLK</sub>) and CS4 to CS0 of ICCR0 register.
  - Standard-mode:

m and n can be set at the range : 0.9 MHz < t<sub>MCLK</sub> (machine clock) < 10 MHz.

Setting of m and n limits the machine clock that can be used below.

$$(m, n) = (1, 8)$$
 : 0.9 MHz < tmclk  $\leq$  1 MHz

$$(m, n) = (1, 38), (3, 6), (6, 6), (7, 8), (6, 6) = 0.9 \text{ MHz} < t \text{mode} \le 4 \text{ NH I} \ge 4 \text{ MHz}$$

• Fast-mode :

m and n can be set at the range :  $3.3~\text{MHz} < t_{\text{MCLK}}$  (machine clock) < 10~MHz.

Setting of m and n limits the machine clock that can be used below.

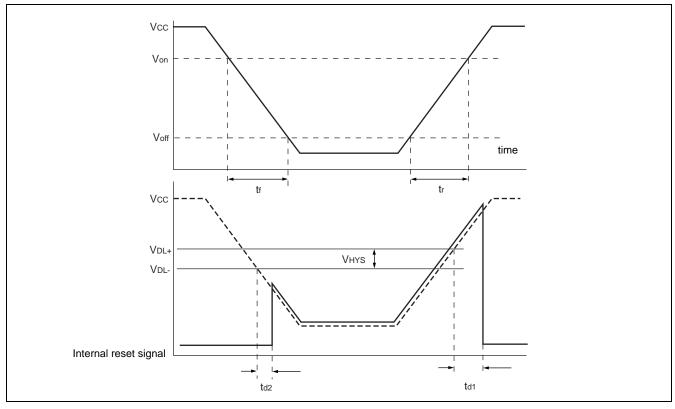
$$\begin{array}{ll} (m,\,n) \,=\, (1,\,8) & : 3.3 \; \text{MHz} < t_{\text{MCLK}} \leq 4 \; \text{MHz} \\ (m,\,n) \,=\, (1,\,22) \;,\; (5,\,4) \; : 3.3 \; \text{MHz} < t_{\text{MCLK}} \leq 8 \; \text{MHz} \end{array}$$

$$(m, n) = (6, 4)$$
 : 3.3 MHz < tmcLK  $\leq$  10 MHz

### (9) Low Voltage Detection

(AVss = Vss = 0.0 V,  $T_A = -40 \, ^{\circ}\text{C}$  to  $+85 \, ^{\circ}\text{C}$ )

		Value			`	33 = V33 = 0.0 V, IA = 40 0 to 1 00 0	
Parameter	Symbol	Min	Тур	Max	Unit	Remarks	
Release voltage	V <sub>DL+</sub>	2.55	2.70	2.85	V	At power-supply rise	
Detection voltage	V <sub>DL</sub> -	2.45	2.60	2.75	V	At power-supply fall	
Hysteresis width	V <sub>H</sub> ys	70	100	_	mV		
Power-supply start voltage	Voff	_		2.3	V		
Power-supply end voltage	Von	4.9		_	V		
Power-supply voltage	4	0.3	_	_	μs	Slope of power supply that reset release signal generates	
change time (at power supply rise)	t <sub>r</sub>	_	3000	_	μs	Slope of power supply that reset release signal generates within rating (V <sub>DL+</sub> )	
Power-supply voltage		300	_	_	μs	Slope of power supply that reset detection signal generates	
change time (at power supply fall)	t <sub>f</sub>	_	300		μs	Slope of power supply that reset detection signal generates within rating (V <sub>DL</sub> -)	
Reset release delay time	<b>t</b> d1	_	_	400	μs		
Reset detection delay time	<b>t</b> d2	_	_	30	μs		
Current consumption	ILVD	_	38	50	μА	Current consumption for low voltage detection circuit only	



#### 5. A/D Converter

### (1) A/D Converter Electrical Characteristics

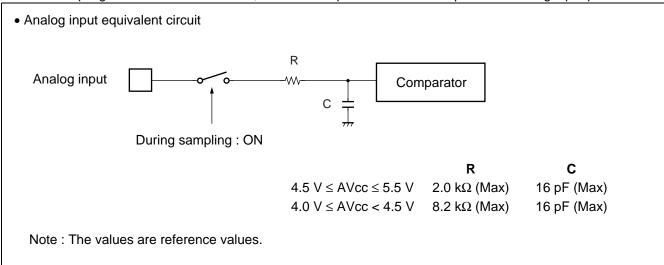
(AVcc = Vcc = 4.0 V to 5.5 V, AVss = Vss = 0.0 V,  $T_A = -40 \, ^{\circ}\text{C}$  to  $+85 \, ^{\circ}\text{C}$ )

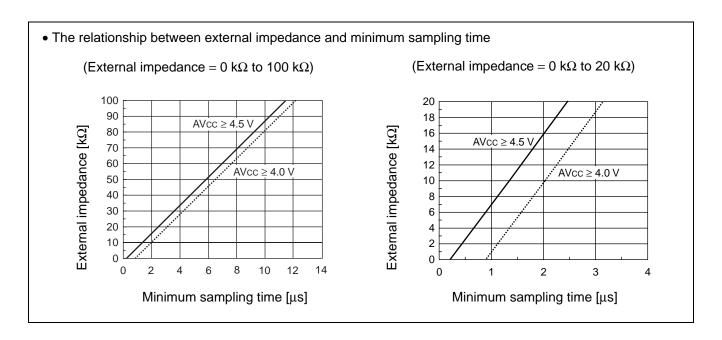
Donomotor	Cumb al		Value	1111111	Domonico		
Parameter	Symbol	Min	Тур	Max	Unit	Remarks	
Resolution		_	_	10	bit		
Total error	_	- 3.0	_	+ 3.0	LSB		
Linearity error		- 2.5	_	+ 2.5	LSB		
Differential linear error		<b>– 1.9</b>	_	+ 1.9	LSB		
Zero transition voltage	Vот	AVss – 1.5 LSB	AVss + 0.5 LSB	AVss + 2.5 LSB	V		
Full-scale transition voltage	VFST	AVcc – 3.5 LSB	AVcc – 1.5 LSB	AVcc + 0.5 LSB	V		
Compare time	_	0.9	_	16500	μs	4.5 V ≤ AVcc ≤ 5.5 V	
Compare time		1.8	_	16500	μs	4.0 V ≤ AVcc < 4.5 V	
Sampling time	_	0.6	_	∞	μs	$4.5 \text{ V} \leq \text{AVcc} \leq 5.5 \text{ V},$ At external impedance < $5.4 \text{ k}\Omega$	
		1.2	_	∞	μs	$4.0~\text{V} \leq \text{AVcc} < 4.5~\text{V},$ At external impedance < $2.4~\text{k}\Omega$	
Analog input current	lain	-0.3	_	+ 0.3	μΑ		
Analog input voltage	Vain	AVss	_	AVcc	V		
Reference voltage	_	AVss + 4.0	_	AVcc	V	AVcc pin	
Reference voltage	lR	_	600	900	μΑ	AVcc pin, During A/D operation	
supply current	Іпн			5	μΑ	AVcc pin, At stop mode	

#### (2) Notes on Using A/D Converter

#### . About the external impedance of analog input and its sampling time

A/D converter with sample and hold circuit. If the external impedance is too high to keep sufficient sampling time, the analog voltage charged to the internal sample and hold capacitor is insufficient, adversely affecting A/D conversion precision, Therefore, to satisfy the A/D conversion precision standard, consider the relationship between the external impedance and minimum sampling time and either adjust the register value and operating frequency or decrease the external impedance so that the sampling time is longer than the minimum value. Also, if the sampling time cannot be sufficient, connect a capacitor of about  $0.1~\mu F$  to the analog input pin.





#### About errors

As |AVcc - AVss| becomes smaller, values of relative errors grow larger.

#### (3) Definition of A/D Converter Terms

Resolution

The level of analog variation that can be distinguished by the A/D converter.

When the number of bits is 10, analog voltage can be divided into  $2^{10} = 1024$ .

• Linearity error (unit: LSB)

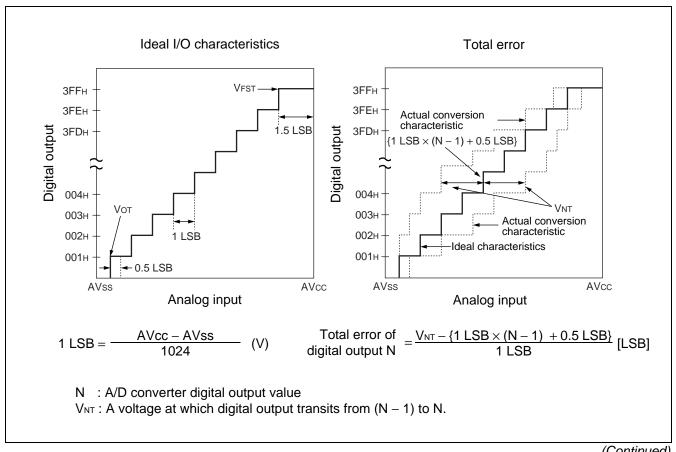
The deviation between the value along a straight line connecting the zero transition point ("00 0000 0000"  $\leftarrow \rightarrow$  "00 0000 0001") of a device and the full-scale transition point ("11 1111 1111"  $\leftarrow$   $\rightarrow$  "11 1111 1110") compared with the actual conversion values obtained.

• Differential linear error (Unit : LSB)

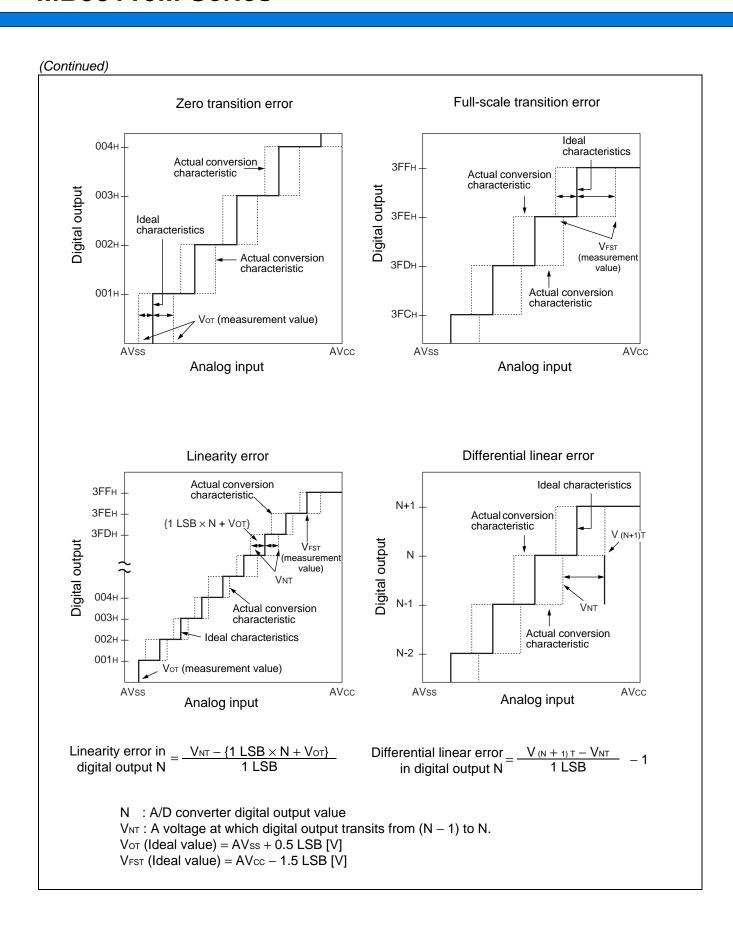
Deviation of input voltage, which is required for changing output code by 1 LSB, from an ideal value.

Total error (unit: LSB)

Difference between actual and theoretical values, caused by a zero transition error, full-scale transition error, linearity error, quantum error, and noise.



(Continued)



#### 6. Flash Memory Program/Erase Characteristics

Parameter	Value			Unit	Remarks	
Parameter	Min	Тур	Max	Offic	Remarks	
Sector erase time (4 Kbytes sector)		0.2*1	0.5*2	s	Excludes 00 <sub>H</sub> programming prior erasure.	
Sector erase time (16 Kbytes sector)	_	0.5*1	7.5*2	s	Excludes 00 <sub>H</sub> programming prior erasure.	
Byte programming time	_	32	3600	μs	Excludes system-level overhead.	
Program/erase cycle	10000	_	_	cycle		
Power supply voltage at program/erase	4.5	_	5.5	V		
Flash memory data retention time	20*3	_	_	year	Average T <sub>A</sub> = +85 °C	

<sup>\*1 :</sup>  $T_A = +25$  °C,  $V_{CC} = 5.0$  V, 10000 cycles

<sup>\*2 :</sup>  $T_A = +85 \, ^{\circ}\text{C}$ ,  $V_{CC} = 4.5 \, \text{V}$ , 10000 cycles

 $<sup>^*3</sup>$ : This value comes from the technology qualification (using Arrhenius equation to translate high temperature measurements into normalized value at +85  $^{\circ}$ C).

### ■ MASK OPTION

No.	Part number	MB95117M	MB95F114MS/F114NS MB95F116MS/F116NS MB95F118MS/F118NS	MB95F114MW/F114NW MB95F116MW/F116NW MB95F118MW/F118NW	MB95FV100D-103	
	Specifying procedure	Setting disabled	Setting disabled	Setting disabled	Setting disabled	
1	Clock mode select • Single-system clock mode • Dual-system clock mode	Specify when ordering MASK	Single-system clock mode	Dual-system clock mode	Changing by the switch on MCU board	
2	Low voltage detection reset* • With low voltage detection reset • Without low voltage detection reset	Specify when ordering MASK	Specified by part number	Specified by part number	Changing by the switch on MCU board	
3	Oscillation stabilization wait time	Fixed to oscillation stabilization wait time of (2 <sup>14</sup> –2) /FcH	Fixed to oscillation stabilization wait time of (2 <sup>14</sup> –2) /FcH	Fixed to oscillation stabilization wait time of (2 <sup>14</sup> –2) /FcH	Fixed to oscillation stabilization wait time of (2 <sup>14</sup> –2) /FcH	

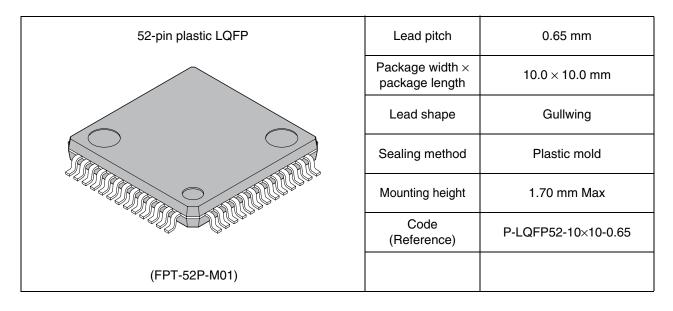
<sup>\*:</sup> Refer to table below about clock mode select, low voltage detection reset and reset output.

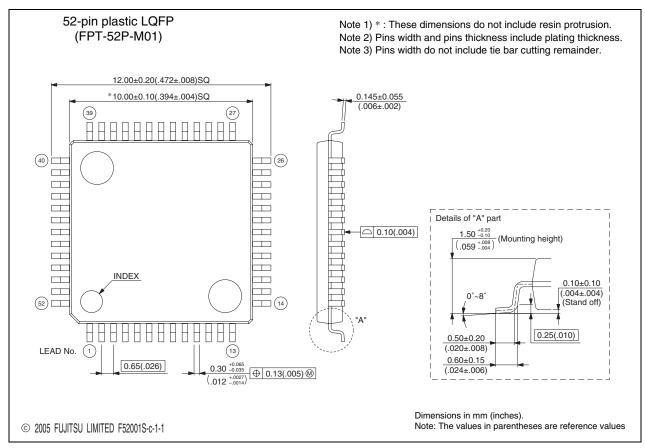
Part number	Clock mode select	Low voltage detection reset
	Single quetem	No
MB95117M	Single-system	Yes
INID95117IVI	Dual avatam	No
	Dual-system	Yes
MB95F114MS		No
MB95F114NS		Yes
MB95F116MS	Cin ale aveters	No
MB95F116NS	Single-system	Yes
MB95F118MS		No
MB95F118NS		Yes
MB95F114MW		No
MB95F114NW		Yes
MB95F116MW	Dual-system	No
MB95F116NW		Yes
MB95F118MW		No
MB95F118NW		Yes
		No
	Single-system	Yes
MD0551/400D 402		Yes
MB95FV100D-103		No
	Dual-system	Yes
		Yes

### **■** ORDERING INFORMATION

Part number	Package	Remarks
MB95117MPMC MB95F114MSPMC MB95F114NSPMC MB95F116MSPMC MB95F116NSPMC MB95F118MSPMC MB95F118NSPMC MB95F114MWPMC MB95F114NWPMC MB95F116NWPMC MB95F116NWPMC MB95F118MWPMC MB95F118NWPMC MB95F118NWPMC	52-pin plastic LQFP (FPT-52P-M01)	
MB2146-303A (MB95FV100D-103PBT)	MCU board (224-pin plastic PFBGA (BGA-224P-M08)	

#### **■ PACKAGE DIMENSION**





Please confirm the latest Package dimension by following URL. http://edevice.fujitsu.com/fj/DATASHEET/ef-ovpklv.html

The information for microcontroller supports is shown in the following homepage. http://www.fujitsu.com/global/services/microelectronics/product/micom/support/index.html

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