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# 2.5 V/3.3 V ECL/PECL/LVDS Dual Differential 2:1 Multiplexer

The MC100ES6056 is a dual, fully differential 2:1 multiplexer. The differential data path makes the device ideal for multiplexing low skew clock or other skew sensitive signals. Multiple  $V_{BB}$  pins are provided.

The  $V_{BB}$  pin, an internally generated voltage supply, is available to this device only. For single-ended input conditions, the unused differential input is connected to  $V_{BB}$  as a switching reference voltage.  $V_{BB}$  may also rebias AC coupled inputs. When used, decouple  $V_{BB}$  and  $V_{CC}$  via a 0.01  $\mu F$  capacitor and limit current sourcing or sinking to 0.5 mA. When not used,  $V_{BB}$  should be left open.

The device features both individual and common select inputs to address both data path and random logic applications.

The 100ES Series contains temperature compensation.

#### **Features**

- 360 ps Typical Propagation Delays
- Maximum Frequency > 3 GHz Typical
- PECL Mode Operating Range:  $V_{CC}$  = 2.375 V to 3.8 V with  $V_{EE}$  = 0 V
- ECL Mode Operating Range: V<sub>CC</sub> = 0 V with V<sub>EE</sub> = -2.375 V to -3.8 V
- · Open Input Default State
- Separate and Common Select
- Q Output Will Default LOW with Inputs Open or at V<sub>EE</sub>
- V<sub>BB</sub> Outputs
- · LVDS Input Compatible
- 20-Lead Pb-Free Package Available

## MC100ES6056

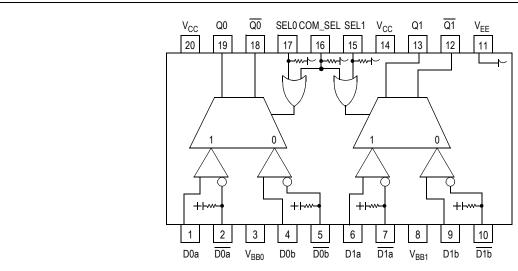


DT SUFFIX 20-LEAD TSSOP PACKAGE CASE 948E-03



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ORDERING INFORMATION					
Device Package					
MC100ES6056DT	TSSOP-20				
MC100ES6056DTR2	TSSOP-20				
MC100ES6056EJ	TSSOP-20 (Pb-Free)				
MC100ES6056EJR2	TSSOP-20 (Pb-Free)				



Warning: All  $V_{CC}$  and  $V_{EE}$  pins must be externally connected to Power Supply to guarantee proper operation.

Figure 1. 20-Lead Pinout (Top View) and Logic Diagram

**Table 1. Pin Description** 

Pin	Function
D0a* – D1a*	ECL Input Data a
D0a* – D1a*	ECL Input Data a Invert
D0b* – D1b*	ECL Input Data b
D0b* - D1b*	ECL Input Data b Invert
SEL0* – SEL1*	ECL Indiv. Select Input
COM_SEL*	ECL Common Select Input
V <sub>BB0</sub> , V <sub>BB1</sub>	Output Reference Voltage
Q0 – Q1	ECL True Outputs
Q0 – Q1	ECL Inverted Outputs
V <sub>CC</sub>	Positive Supply
V <sub>EE</sub>	Negative Supply

**Table 2. Function Table** 

Table 2. Ful	nction rable	,	www.DataSh	eet4U.com
SEL0	SEL1	COM_SEL	Q0, Q0	Q1, Q1
Х	Х	Н	а	а
L	L	L	b	b
L	Н	L	b	а
Н	Н	L	а	а
Н	L	L	а	b

## **Table 3. General Specifications**

	Value	
Internal Input Pulldown Resistor	75 kΩ	
Internal Input Pullup Resistor	75 kΩ	
ESD Protection	Human Body Model Machine Model Charged Device Model	> 4 kV > 400 V > 2 kV
Thermal Resistance 0 LFPM, 20 TSSOP (Junction-to-Ambient) 500 LFPM, 20 TSSOP		140°C/W 100°C/W

Meets or exceeds JEDEC Spec EIA/JESD78 IC Latchup Test

<sup>\*</sup> Input function will default LOW when left open.

Table 4. Absolute Maximum Ratings<sup>(1)</sup>

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Symbol	Characteristic	Conditions	Rating	Units
V <sub>SUPPLY</sub>	Power Supply Voltage	Difference between V <sub>CC</sub> & V <sub>EE</sub>	3.9	V
V <sub>IN</sub>	Input Voltage	$V_{CC} - V_{EE} \le 3.6 \text{ V}$	V <sub>CC</sub> + 0.3 V <sub>EE</sub> - 0.3	V
I <sub>OUT</sub>	Output Current	Continuous Surge	50 100	mA mA
I <sub>BB</sub>	V <sub>BB</sub> Sink/Source Current		±0.5	°C
$T_A$	Operating Temperature Range		-40 to +85	°C
T <sub>STG</sub>	Storage Temperature Range		-65 to +150	°C

<sup>1.</sup> Absolute maximum continuous ratings are those maximum values beyond which damage to the device may occur. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation at absolute-maximum-rated conditions is not implied.

**Table 5. DC Characteristics** ( $V_{CC} = 0 \text{ V}, V_{EE} = -2.5 \text{ V} \pm 5\% \text{ or } 3.8 \text{ V to } -3.135 \text{ V}; V_{CC} = 2.5 \text{ V} \pm 5\% \text{ or } 3.135 \text{ V to } 3.8 \text{ V}, V_{EE} = 0 \text{ V})$ 

Symbol	Characteristics	-40°C		0°C to 85°C			Unit	
Syllibol	Characteristics	Min	Тур	Max	Min	Тур	Max	Offic
I <sub>EE</sub>	Power Supply Current		30	60		30	60	mA
V <sub>OH</sub>	Output HIGH Voltage <sup>(1)</sup>	V <sub>CC</sub> -1085	V <sub>CC</sub> -960	V <sub>CC</sub> -880	V <sub>CC</sub> -1025	V <sub>CC</sub> -930	V <sub>CC</sub> -860	mV
V <sub>OL</sub>	Output LOW Voltage <sup>(1)</sup>	V <sub>CC</sub> -1950	V <sub>CC</sub> -1695	V <sub>CC</sub> -1500	V <sub>CC</sub> -1950	V <sub>CC</sub> -1705	V <sub>CC</sub> -1500	mV
V <sub>IH</sub>	Input HIGH Voltage	V <sub>CC</sub> -1165		V <sub>CC</sub> -880	V <sub>CC</sub> -1165		V <sub>CC</sub> -880	mV
V <sub>IL</sub>	Input LOW Voltage	V <sub>CC</sub> -1810		V <sub>CC</sub> -1475	V <sub>CC</sub> -1810		V <sub>CC</sub> -1475	mV
$V_{BB}$	Output Reference Voltage	V <sub>CC</sub> -1380	V <sub>CC</sub> -1290	V <sub>CC</sub> -1220	V <sub>CC</sub> -1380	V <sub>CC</sub> -1290	V <sub>CC</sub> -1200	mV
V <sub>PP</sub>	Differential Input Voltage <sup>(2)</sup>	0.15		1.3	0.15		1.3	V
V <sub>CMR</sub>	Differential Cross Point Voltage <sup>(3)</sup>	V <sub>CC</sub> -2.3		V <sub>CC</sub> -0.8	V <sub>CC</sub> -2.3		V <sub>CC</sub> -0.8	V
I <sub>IH</sub>	Input HIGH Current			150			150	μΑ
I <sub>IL</sub>	Input LOW Current	0.5			0.5			μА

<sup>1.</sup> Output termination voltage  $V_{TT} = 0 \text{ V for } V_{CC} = 2.5 \text{ V}$  operation is supported but the power consumption of the device will increase.

<sup>2.</sup> V<sub>PP</sub> (DC) is the minimum differential input voltage swing required to maintain device functionality.

<sup>3.</sup>  $V_{CMR}$  (DC) is the crosspoint of the differential input signal. Functional operation is obtained when the crosspoint is within the  $V_{CMR}$  (DC) range and the input swing lies within the  $V_{PP}$  (DC) specification.

**Table 6. AC Characteristics** ( $V_{CC}$  = 0 V;  $V_{EE}$  = -2.5 V ± 5% or -3.8 V to -3.135 V;  $V_{CC}$  = 2.5 V ± 5% or 3.135 V to 3.8 V;  $V_{EE}$  = 0 V)<sup>(1)</sup>

			-	40°C to 85°	С	
Symbol	Characteristics		Min	Тур	Max	Unit
f <sub>max</sub>	Maximum Frequency			> 3		GHz
t <sub>PLH</sub> , t <sub>PHL</sub>	Propagation Delay to Output Differential	D to Q, $\overline{\underline{Q}}$ SEL to Q, $\overline{\underline{Q}}$ COM_SEL to Q, $\overline{Q}$	300 300 300	400 430 490	500 600 650	ps ps ps
t <sub>SKEW</sub>	Skew	Output-to-Output <sup>(2)</sup> Part-to-Part		10	50 200	ps ps
t <sub>JITTER</sub>	Cycle-to-Cycle Jitter	RMS (1σ)			1	ps
$V_{PP}$	Minimum Input Swing		200	800	1200	mV
$V_{CMR}$	Differential Cross Point Voltage		V <sub>CC</sub> -2.1		V <sub>CC</sub> -1.1	V
t <sub>r</sub> / t <sub>f</sub>	Output Rise/Fall Time (20%–80%)		70	120	230	ps

- 1. Measured using a 750 mV source, 50% duty cycle clock source. All loading with 50 $\Omega$  to V<sub>CC</sub>-2.0 V.
- 2. Skew is measured between outputs under identical transitions. Duty cycle skew is defined only for differential operation when the delays are measured from the cross point of the inputs to the cross point of the outputs.

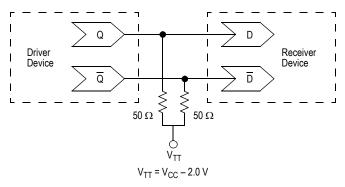
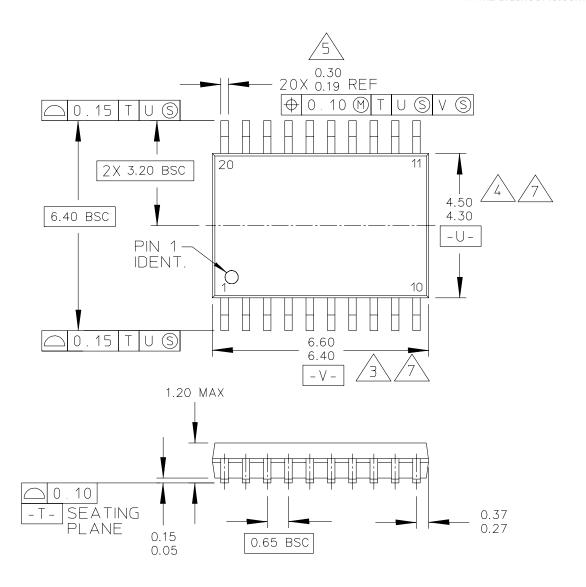


Figure 2. Typical Termination for Output Driver and Device Evaluation

## **PACKAGE DIMENSIONS**

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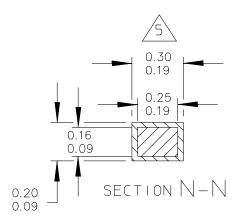
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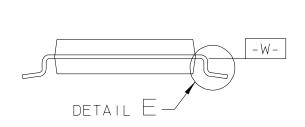
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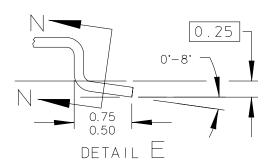
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#### NOTES:

- 1. CONTROLLING DIMENSION: MILLIMETER
- 2. DIMENSIONS AND TOLERANCES PER ANSI Y14.5M-1982.



DIMENSION DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH OR GATE BURRS SHALL NOT EXCEED 0.15 PER SIDE.



DIMENSION DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.25 PER SIDE.



DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 TOTAL IN EXCESS OF THE DIMENSION AT MAXIMUM MATERIAL CONDITION.

6. TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.

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#### Europe, Middle East, and Africa:

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#### Japan:

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