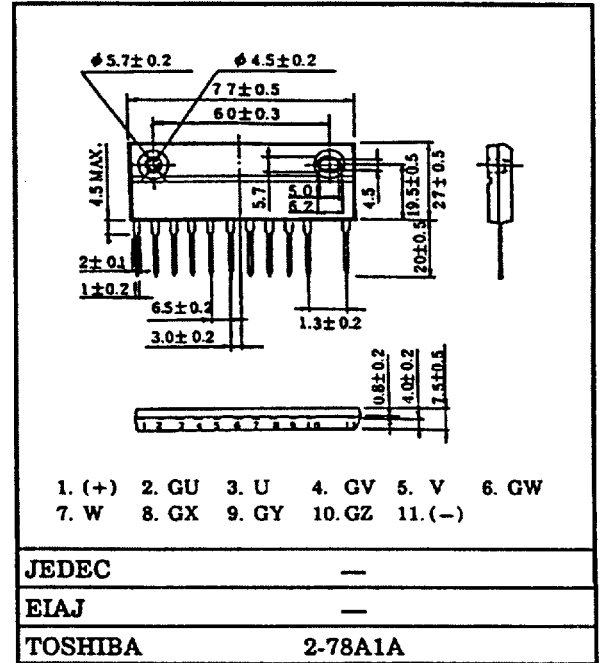


### High Power Switching Applications

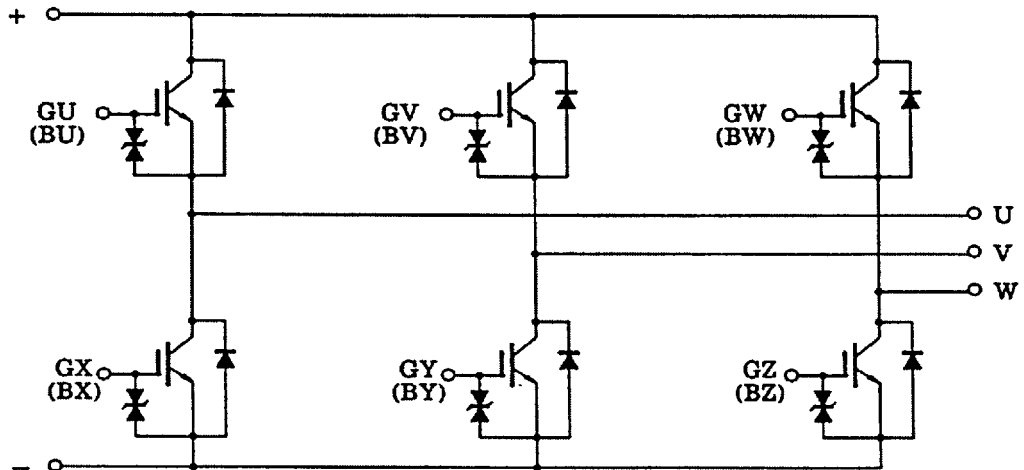
#### Motor Control Applications

- The Electrodes are Isolated from Case.
- 6 IGBTs are Built Into 1 Package.
- Enhancement-Mode
- Low Saturation Voltage
  - :  $V_{CE(sat)} = 2.7V$  (Max.) ( $I_C = 20A$ )
- High Speed
  - :  $t_f = 1.0\mu s$  (Max.) ( $I_C = 20A$ )
  - :  $t_{rr} = 0.15\mu s$  (Max.) ( $I_F = 20A$ )



Weight : 44g

### Equivalent Circuit

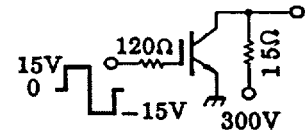


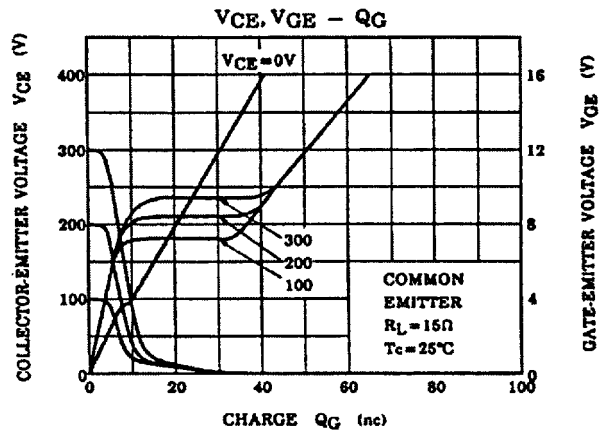
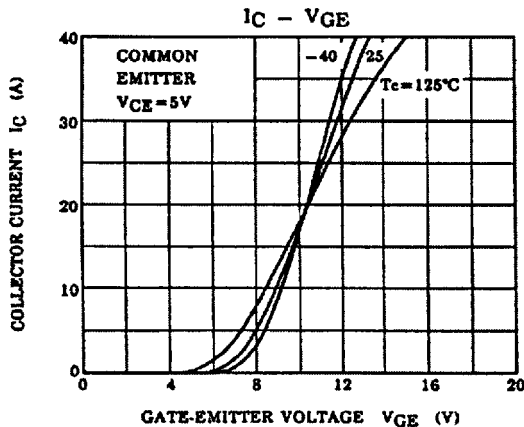
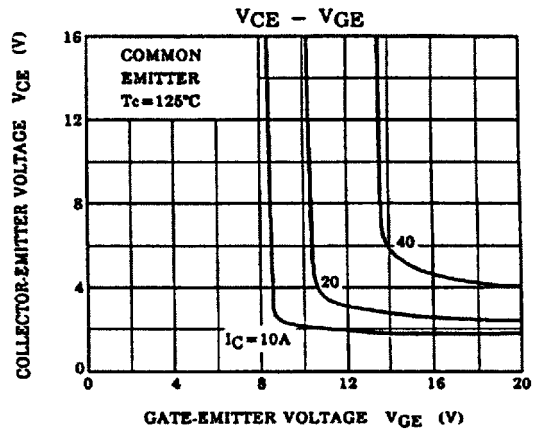
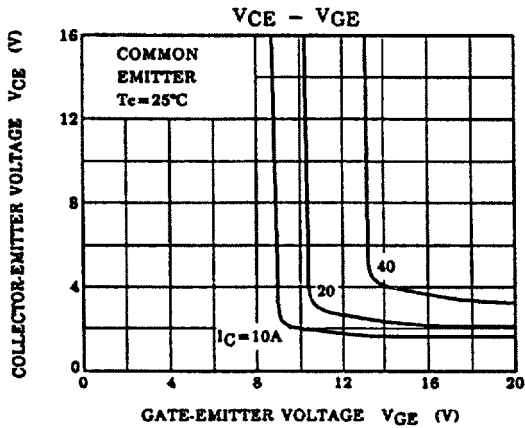
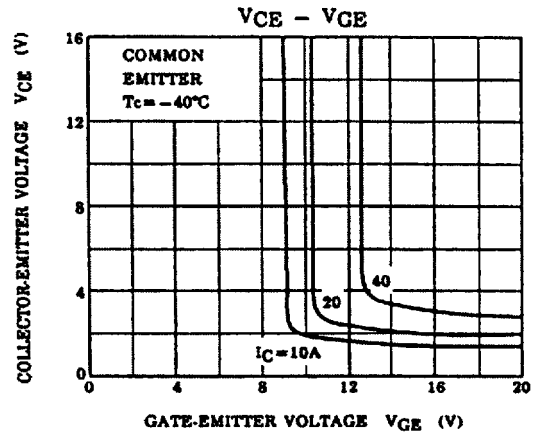
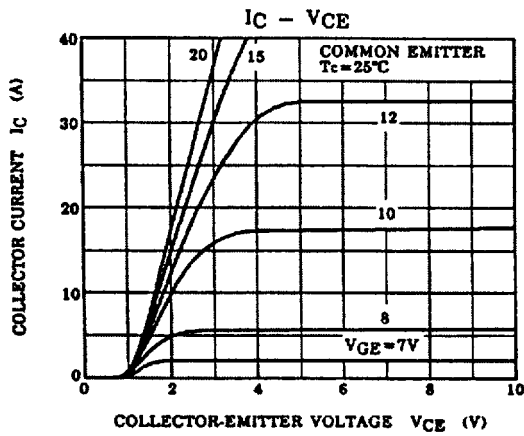
# MP6753

## Maximum Ratings (Ta = 25°C)

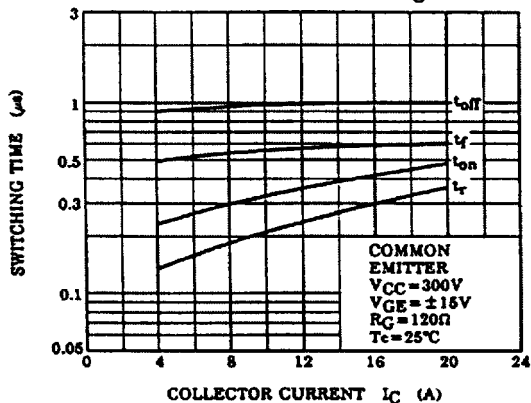
CHARACTERISTIC		SYMBOL	RATINGS	UNIT
Collector-Emitter Voltage		$V_{CES}$	600	V
Gate-Emitter Voltage		$V_{GES}$	$\pm 20$	V
Collector Current	DC	$I_C$	20	A
	1ms	$I_{CP}$	40	
Forward Current	DC	$I_F$	20	A
	1ms	$I_{FM}$	40	
Collector Power Dissipation (Tc = 25°C)		$P_C$	60	W
Junction Temperature		$T_j$	150	°C
Storage Temperature Range		$T_{stg}$	-40 ~ 125	°C
Isolation Voltage		$V_{Isol}$	2500 (AC 1 minute)	V
Screw Torque		–	1.5	N•m

## Electrical Characteristics (Ta = 25°C)

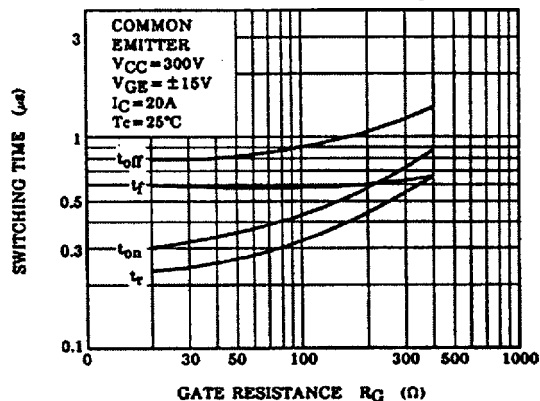
CHARACTERISTIC		SYMBOL	TEST CONDITION	MIN.	TYP.	MX.	UNIT
Gate Leakage Current		$I_{GES}$	$V_{GE} = \pm 20V, V_{CE} = 0$	–	–	$\pm 20$	$\mu A$
Collector Cut-off Current		$I_{CES}$	$V_{CE} = 600V, V_{GE} = 0$	–	–	1.0	mA
Collector-Emitter Breakdown Voltage		$V_{(BR)CES}$	$I_C = 10mA, B_{GE} = 0$	600	–	–	V
Gate-Emitter Cut-off Voltage		$V_{GE(OFF)}$	$V_{CE} = 5V, I_C = 20mA$	3.0	–	6.0	V
Collector-Emitter Saturation Voltage		$V_{CE(sat)}$	$I_C = 20A, V_{GE} = 15V$	–	2.3	2.8	V
Input Capacitance		$C_{ies}$	$V_{CE} = 10V, V_{GE} = 0, f = 1MHz$	–	1300	–	pF
Switching Time	Rise Time	$t_r$		–	0.3	0.6	$\mu s$
	Turn-on Time	$t_{on}$		–	0.4	0.8	
	Fall Time	$t_f$		–	0.6	1.0	
	Turn-off Time	$t_{off}$		–	1.0	1.6	
Forward Voltage		$V_F$	$I_F = 15A, V_{GE} = 0$	–	1.7	2.5	V
Reverse Recovery Time		$t_{rr}$	$I_F = 20A, V_{GE} = -10V$ $di/dt = 50A/\mu s$	–	0.08	0.15	$\mu s$
Thermal Resistance		$R_{th(j-c)}$	Transistor	–	–	2.08	°C/W
			Diode	–	–	3.09	



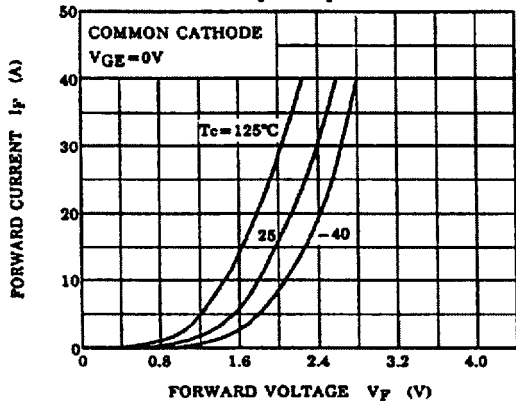
SWITCHING TIME -  $I_C$



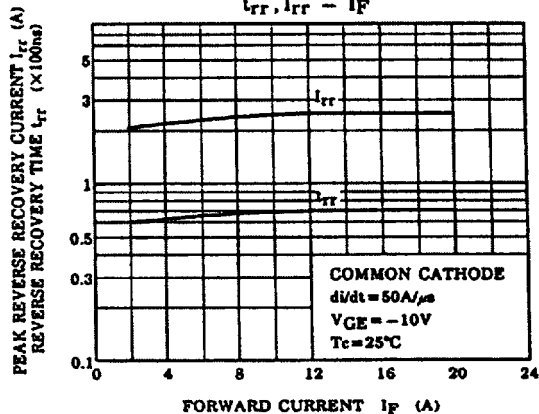
SWITCHING TIME -  $R_G$



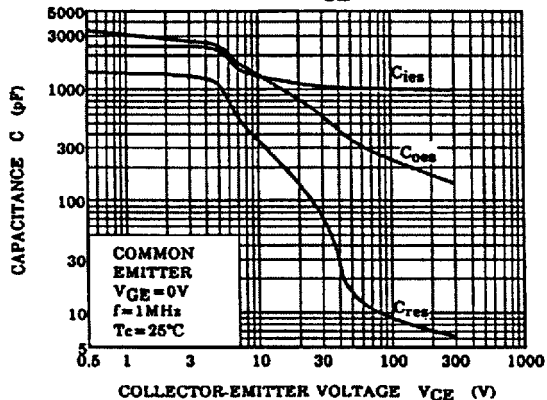
$I_F - V_F$



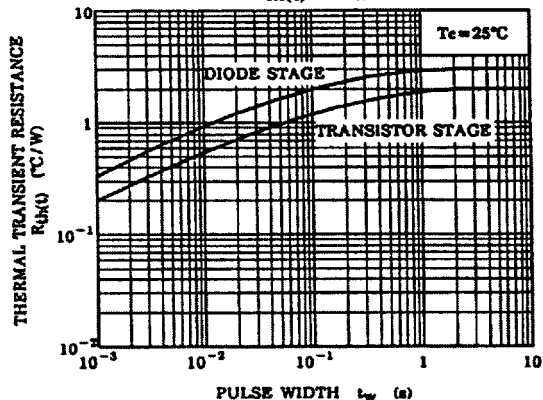
$t_{rr}, I_{rr} - I_F$



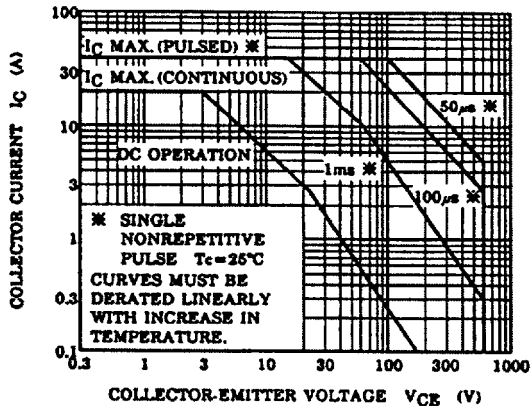
C -  $V_{CE}$



$R_{th}(t) - t_w$



## SAFE OPERATING AREA



## REVERSE BIAS SOA

