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Analog Semiconductor IC MRX1518HXA

CMOS MR MAGNETIC SENSOR SWITCH

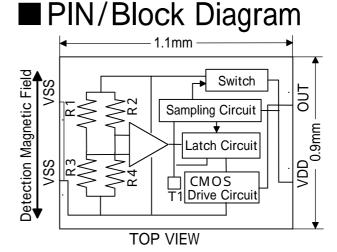
Feature

CMOS+MR Monolithic Structure

Ultra small SMD package: $1.1 \times 0.9 \times 0.47$ mm Low current consumption: $1.6 \mu A/1.8V$ High-Sensitivity MR sensor: 1.5mT/Typ Magnetic Direction: Both direction/CMOS

inverter one output

Detection Magnetic Field: Horizontal direction of package (electrode parallel both direction) Operating Temperature Range: 40~ + 85 Operating Voltage Range: 1.6~ 3.5V



Outline

MRX series is a monolithic IC with built-in MR magnet resistive element and CMOS switch. It becomes the switch of the noncontact of low current consumption, high sensitivity, and high reliability by combining with the magnet.

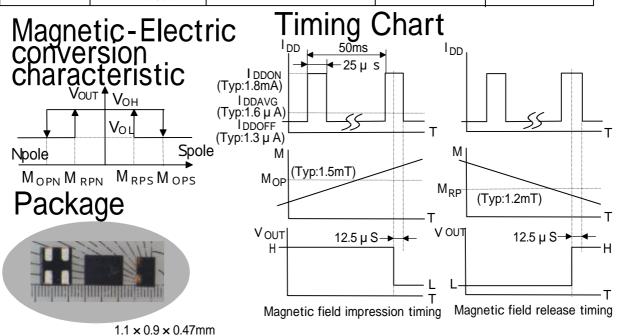
A parallel to the electrode of the package horizontal magnetic field can be detected by an arbitrary polarity (N pole S pole).

Even 1.5mT ~ 6mT can detect a wide magnetic field in the MRX series.

There are two CMOS output and **opendrain** output types that can individually detect N and S pole in MR series.

Type Name: MRX1518HXA/Product Number Rule/List

| MRX | 1518:Sensitivity /Voltage | H :Operation voltage/ Output cycle | X :Package | A:Version |
|-------------------------------|--------------------------------|---------------------------------------|---------------------------------|--------------|
| Anasem Product Series Name | 15:1.5mT(Typ)/ 18:1.8V(Typ) | H :1.6 ~ 3.5V/25 μ s:50ms | X: XLP/1.1 × 0.9 × 0.47mm/4L | A :CMOS/1out |



Electric Characteristics

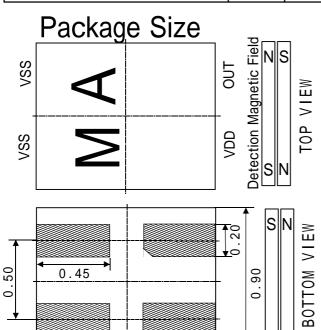
 $(Ta= 25 , V_{DD} = 1.8V)$

| Item | Sign | Measurement condition | Min | Тур | Max | Unit |
|--|--------------|---------------------------------------|--------------------|------|--------------------|------|
| Operation Voltage | V_{DD} | | 1.6 | 1.8 | 3.5 | V |
| Current consumption | I AVG | Average Current V _{DD} =1.8V | | 1.6 | 3.0 | μА |
| Output reversing magnetic | Mops | | (1.0) | 1.5 | 2.2 | mT |
| induction (H L) | Mopn | | -2.2 | -1.5 | (-1.0) | |
| Output reversing magnetic | Mrps | | 0.8 | 1.2 | (1.9) | Т |
| induction (L H) | Mrpn | | (-1.9) | -1.2 | -0.8 | mT |
| Width of reversing magnetic induction hysteresis | MHYS | | (0.1) | 0.3 | (0.8) | mT |
| Pulse drive cycle | t s | | | 50 | 90 | ms |
| High-level output voltage | Vон | I OUT=+1.0mA | 0.9V _{DD} | | | V |
| Low-level output voltage | Vol | I _{OUT} =-1.0mA | | | 0.1V _{DD} | ٧ |

()Design guarantee value

Absolute Maximum Rating

| Operating temperature range | T _{OPR} | | -40 | | +85 | |
|--------------------------------|------------------|-----------------|----------------------|-----|----------------------|---|
| Storage temperature range | T _{STG} | | -50 | | +125 | |
| Absolute maximum voltage range | V _{MAX} | | V _{SS} -0.3 | | V _{SS} +6.0 | ٧ |
| Assembly temperature condition | T _{ASY} | t=max:5sec/Tmax | | 255 | 260 | |

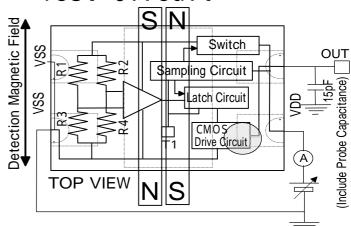


1.10

Magnetic Strength and Output Voltage

| Magnet & Power | Magnet Condition | | Output Voltage | | |
|------------------------|---------------------|-------|----------------|--|--|
| Magnet=OFF Power=ON | M=0mT | | High-Level | | |
| Magnet =ON Power=ON | М | 2.2mT | Low-Level | | |
| Magnet=OFF Power=ON | М | 0.5mT | High-Level | | |

Test Circuit



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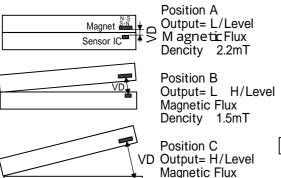
0.47 NSN

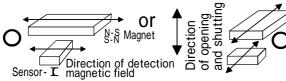
(Units:mm)

Use Example (Cellular Phone)

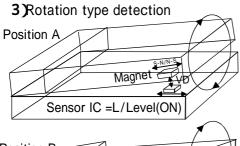
Dencity 0.5mT

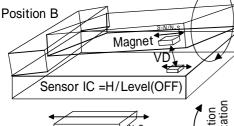
1) Opening and shutting type detection

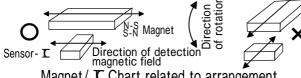




Magnet / IC Chart related to arrangement







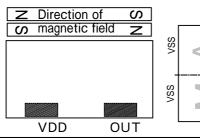
Magnet / T Chart related to arrangement

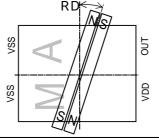
Magnetic field detection

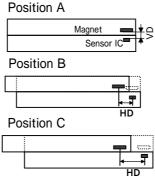
When an enough magnetic induction is added in parallel to the sensor side in the direction of marking, the output is ON(Low). Magnetic field strength of each 50msec for 25 μ sec is detected. The direction of the magnetic field is detected regardless of N pole S pole.
A reverse-magnetic field doesn't influence it for

the detection of horizontal direction.

Because the marking side and the vertical direction are perceived according to the size of the magnetic induction, it is possible to apply also to the slide type in a parallel direction and the fold type in the vertical direction.



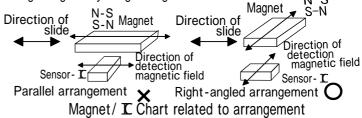




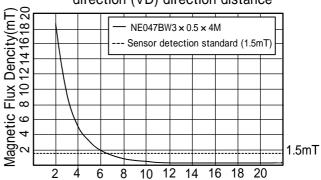
2) Slide type detection There is right-angled or parallel arrangement in the relation between the direction of the magnetic field and the direction of the slide in the slide type cellular phone.

Both become switches ON in Position A, too. It is likely to become turning off in parallel arrangement in Position B It becomes switch ON again by a reverse-magnetic field if swerving in the direction of Position C in parallel arrangement, and when the distance parts enough, it becomes switch OFF.

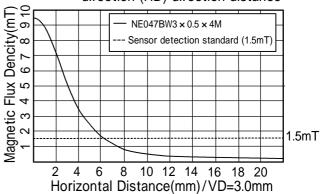
It doesn't become OFF by Position B in right-angled arrangement but it becomes OFF by Position C to which the distance parts enough. The meaning that prevents the malfunction recommends being designed by a right-angled method.



4 Neodymium standard magnet vs. vertical direction (VD) direction distance



Vertical Distance(mm)/HD=0mm 5 Neodymium standard magnet vs. horizontal direction (HD) direction distance



Standard magnet

P point: Magnetic induction measurement position 3mm

Sensor reaction/ direction of magnetization specification

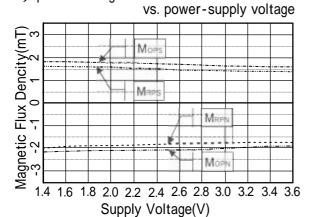
Magnet maker: TDK Corp Neodymium magnet Product number: NE047B $W3 \times 0.5 \times 4M$

Size: $4 \times 3 \times 0.5$ mm

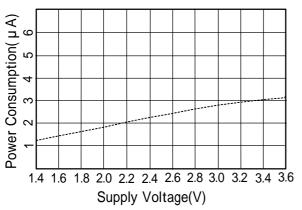
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Electric Characteristics Data

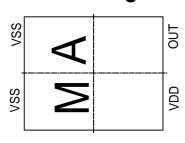
1 Operation magnetic induction



3)Current consumption vs. power-supply voltage

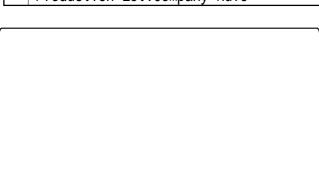


Marking

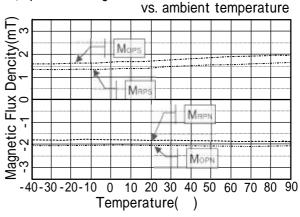


Products Name: MA/MRX1518HXA

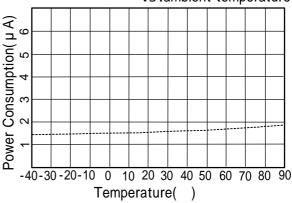
b Production Lot:Company Rule



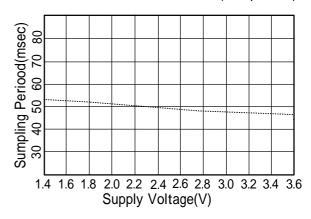
2 Operation magnetic induction



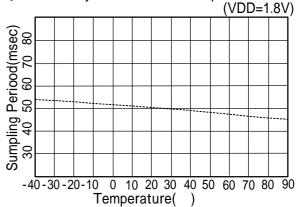
4)Current consumption (average current)
vs.ambient temperature



5)Detection cycle vs. power-supply voltage (Temp=25)



6 Detection cycle vs. ambient temperature



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