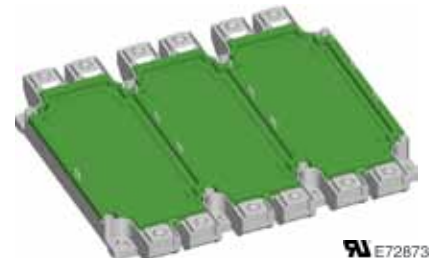
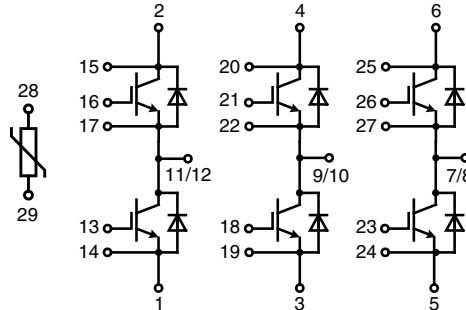


IGBT Modules

Sixpack

NPT³ IGBT

$$\begin{aligned} I_{C80} &= 250 \text{ A} \\ V_{CES} &= 1200 \text{ V} \\ V_{CE(sat) \text{ typ.}} &= 2.1 \text{ V} \end{aligned}$$



See outline drawing for pin arrangement

IGBTs			
Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$ to 125°C	1200	V
V_{GES}		± 20	V
I_{C25}	$T_C = 25^{\circ}\text{C}$	355	A
I_{C80}	$T_C = 80^{\circ}\text{C}$	250	A
RBSOA	$R_G = 5 \Omega$; $T_{VJ} = 125^{\circ}\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 500$ $V_{CEK} \leq V_{CES}$	A
t_{SC} (SCSOA)	$V_{CE} = 900 \text{ V}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 5 \Omega$ $T_{VJ} = 125^{\circ}\text{C}$; non-repetitive; $V_{CEmax} \leq V_{CES}$	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	1.4	kW

Features

- NPT³ IGBT technology
- low saturation voltage
- low switching losses
- square RBSOA, no latch up
- high short circuit capability
- positive temperature coefficient for easy paralleling
- MOS input, voltage controlled
- ultra fast free wheeling diodes
- solderable pins for PCB mounting
- package with copper base plate

Advantages

- space savings
- reduced protection circuits
- package designed for wave soldering

Typical Applications

- AC motor control
- AC servo and robot drives
- power supplies

Symbol	Conditions	Characteristic Values			
		$(T_{VJ} = 25^{\circ}\text{C}, \text{ unless otherwise specified})$			
		min.	typ.	max.	
$V_{CE(sat)}$	$I_C = 225 \text{ A}$; $V_{GE} = 15 \text{ V}$				
	$T_{VJ} = 25^{\circ}\text{C}$		2.1	2.5	V
	$T_{VJ} = 125^{\circ}\text{C}$		2.4	2.9	V
$V_{GE(th)}$	$I_C = 8 \text{ mA}$; $V_{GE} = V_{CE}$	4.5		6.5	V
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$				
	$T_{VJ} = 25^{\circ}\text{C}$			1	mA
	$T_{VJ} = 125^{\circ}\text{C}$		1	8	mA
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$			400	nA
$t_{d(on)}$	Inductive load, $T_{VJ} = 125^{\circ}\text{C}$ $V_{CE} = 600 \text{ V}$; $I_C = 200 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$; $R_G = 3.6 \Omega$		180		ns
t_r			100		ns
$t_{d(off)}$			650		ns
t_f			120		ns
E_{on}			13		mJ
E_{off}			21		mJ
C_{ies}	$V_{CE} = 25 \text{ V}$; $V_{GE} = 0 \text{ V}$; $f = 1 \text{ MHz}$		14		nF
Q_{Gon}	$V_{CE} = 600 \text{ V}$; $V_{GE} = 15 \text{ V}$; $I_C = 300 \text{ A}$		1.5		μC
R_{thJC}				0.09	K/W

Diodes

Symbol	Conditions	Maximum Ratings	
I_{F80}	$T_C = 80^\circ\text{C}$	205	A
I_{FRM}	$t_p = 1\text{ ms}$	400	A
I^2t	$T_{VJ} = 125^\circ\text{C}; t = 10\text{ ms}; V_R = 0\text{ V}$	10000	A ² s

Symbol Conditions**Characteristic Values**(T_{VJ} = 25°C, unless otherwise specified)

		min.	typ.	max.	
V_F	$I_F = 225\text{ A}; V_{GE} = 0\text{ V}; T_{VJ} = 25^\circ\text{C}$			2.2	V
I_{RM}	$I_F = 225\text{ A}; di_F/dt = 1800\text{ A}/\mu\text{s}; T_{VJ} = 125^\circ\text{C}; V_R = 800\text{ V}$		160		A
R_{thJC}			0.165		K/W

Temperature Sensor NTC

Symbol	Conditions	Characteristic Values			
		min.	typ.	max.	
R_{25}	$T = 25^\circ\text{C}$	4.75	5.0	5.25	kΩ
$B_{25/50}$			3375		K

Module

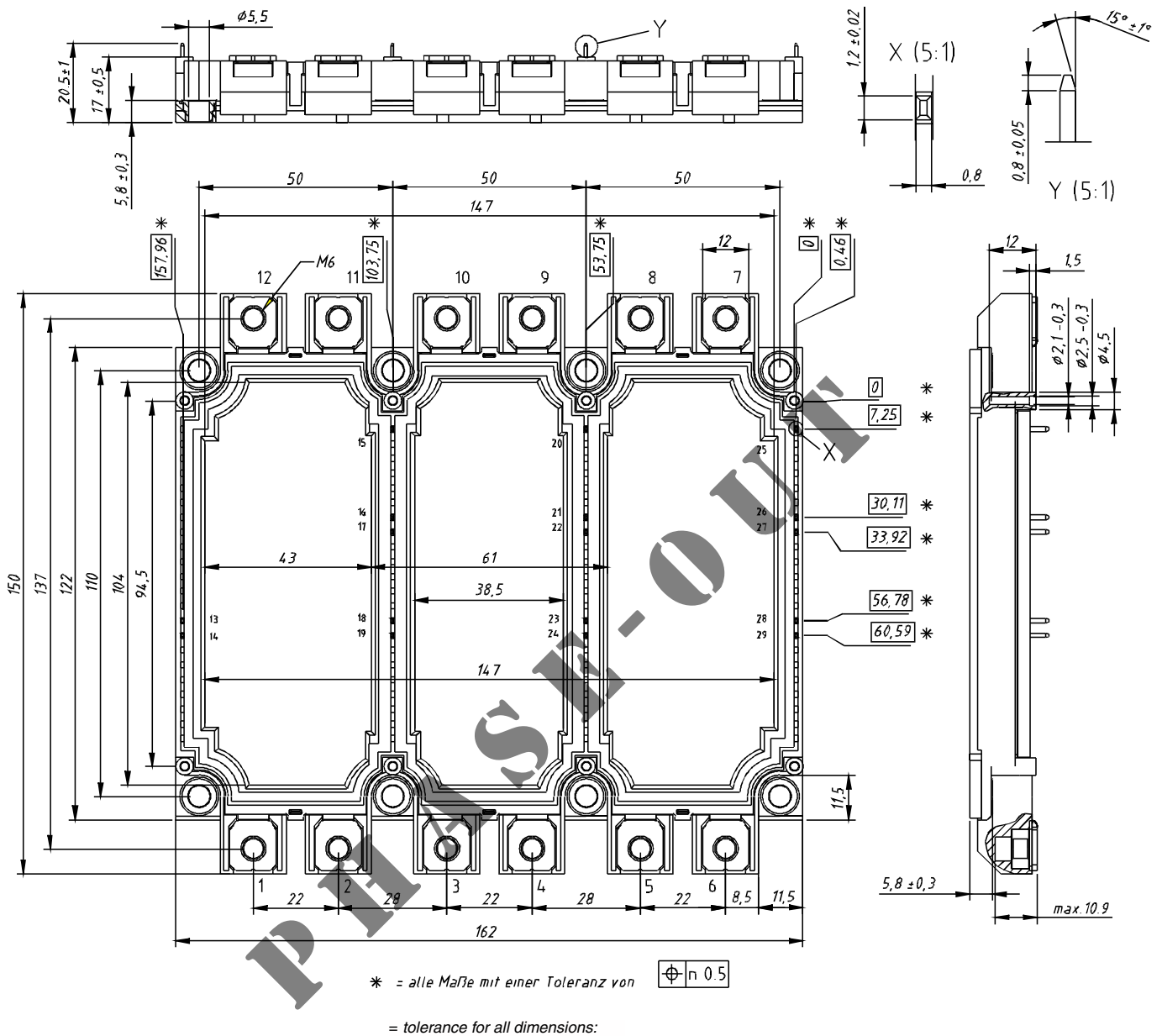
Symbol	Conditions	Maximum Ratings	
T_{VJ}	operating	-40...+125	°C
T_{JM}		+150	°C
T_{stg}		-40...+125	°C
V_{ISO}	$I_{ISOL} \leq 1\text{ mA}; 50/60\text{ Hz}$	3400	V~
M_d	Mounting torque (M5)	3 - 6	Nm
	Terminal connection torque (M6)	3 - 6	Nm

Symbol Conditions**Characteristic Values**

		min.	typ.	max.	
$R_{therm-chip}^{*)}$	Resistance terminal to chip		0.55		mΩ
d_S	Creepage distance on surface	12.7			mm
d_A	Strike distance in air	10			mm
R_{thCH}	with heatsink compound		0.01		K/W
Weight			900		g

*) $V = V_{CEsat} + 2x R_{therm-chip} \cdot I_C$ resp. $V = V_F + 2x R \cdot I_F$

Dimensions in mm (1 mm = 0.0394")



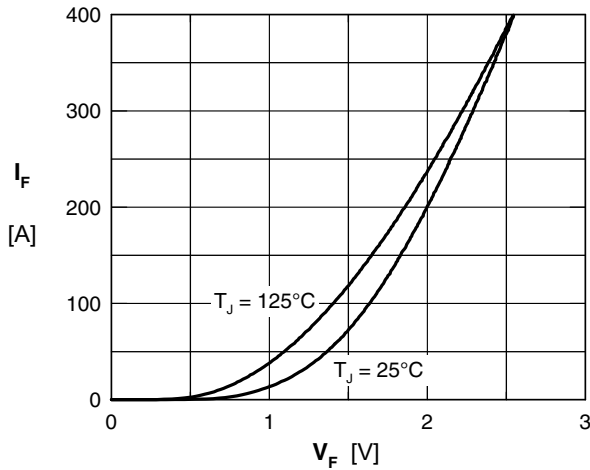


Fig. 1 Typ. forward characteristics of free wheeling diode

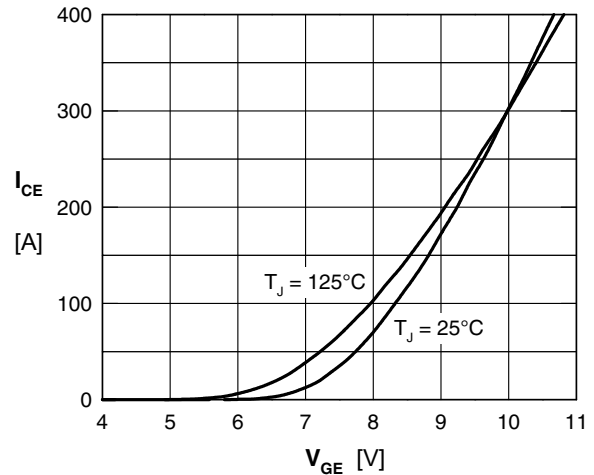


Fig. 2 Typ. transfer characteristics

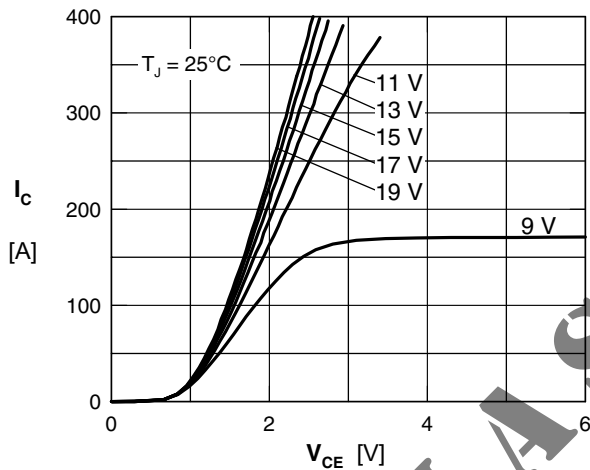


Fig. 3 Typ. output characteristics

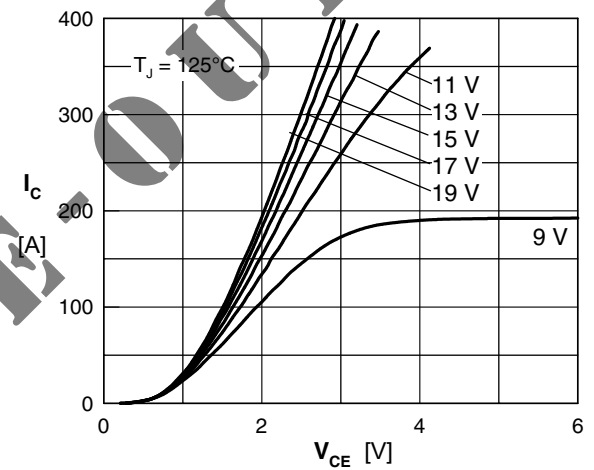


Fig. 4 Typ. output characteristics

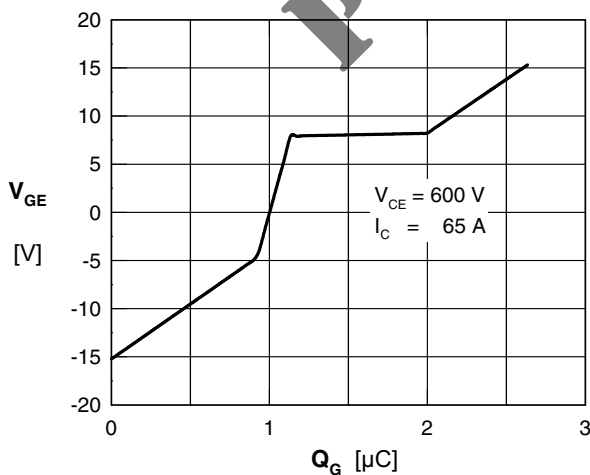


Fig. 5 Typ. turn on gate charge

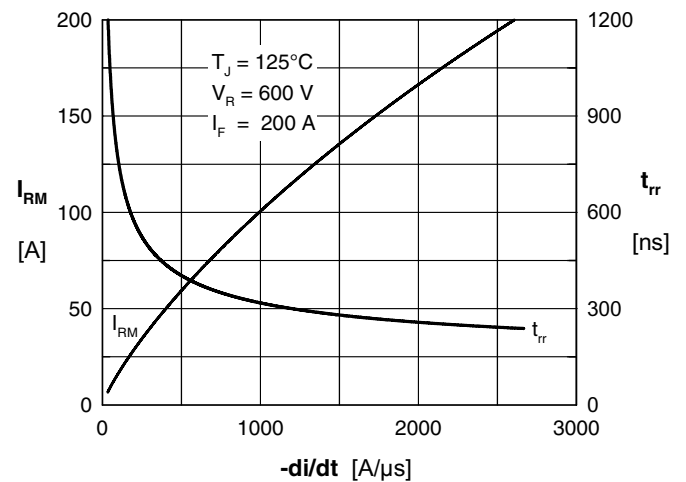


Fig. 6 Typ. turn off characteristics of free wheeling diode

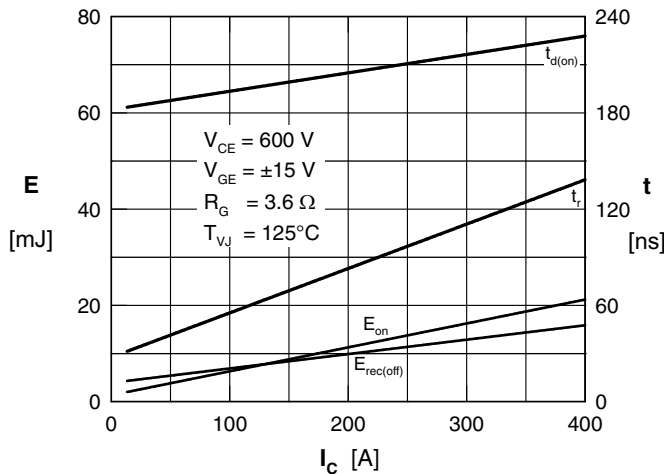


Fig. 7 Typ. turn on energy and switching times versus collector current

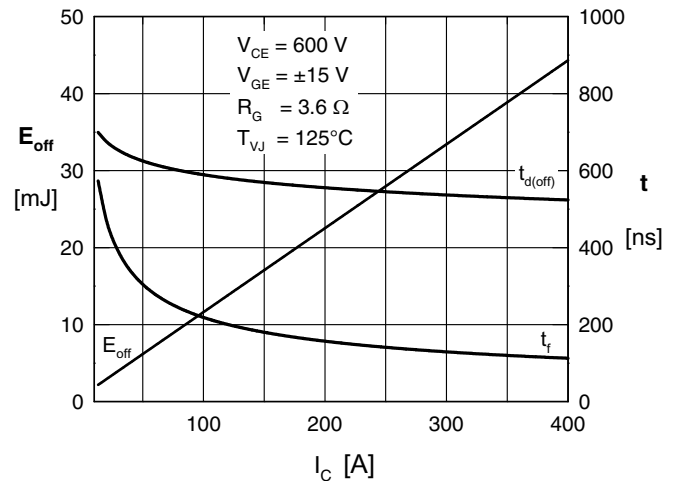


Fig. 8 Typ. turn off energy and switching times versus collector current

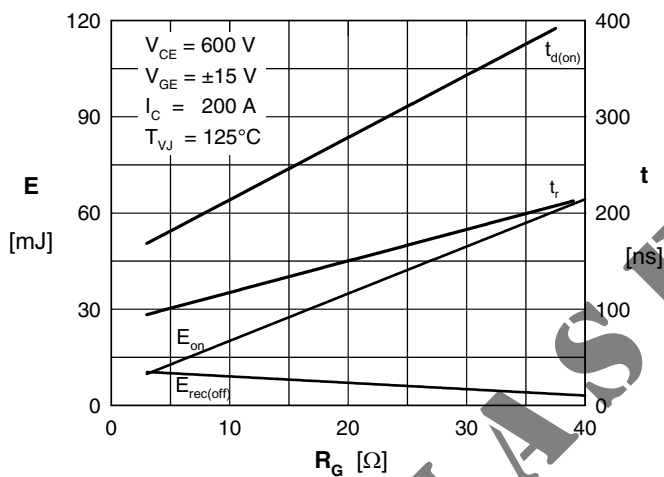


Fig. 9 Typ. turn on energy and switching times versus gate resistor

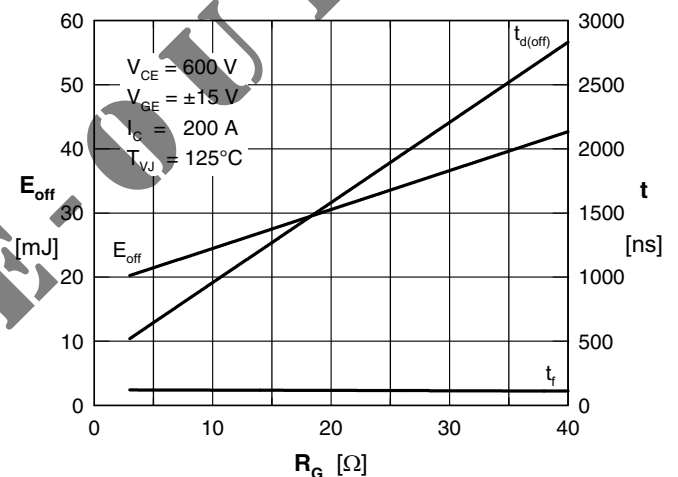


Fig. 10 Typ. turn off energy and switching times versus gate resistor

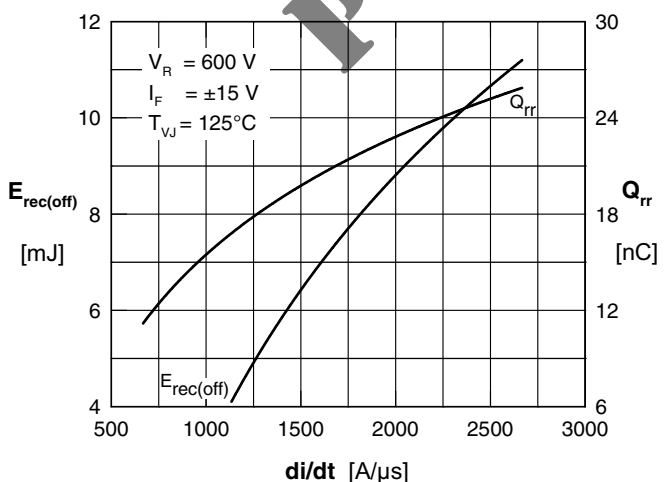


Fig. 11 Typ. turn off energy and recovered charge of free wheeling diode

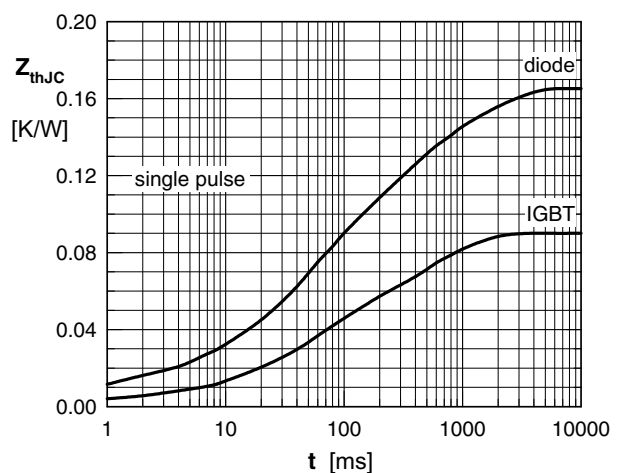


Fig. 12 Typ. transient thermal impedance