

MX29LV161D T/B

16M-BIT [1M x 16] 3V SUPPLY FLASH MEMORY

MX29LV161D T/B DATASHEET



MX29LV161D T/B

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16M-BIT [1M x 16] 3V SUPPLY FLASH MEMORY

FEATURES

GENERAL FEATURES

- Word mode only
- 1,048,576 x 16
- Sector Structure
 - 8K-Word x 1, 4K-Word x 2, 16K-Word x 1, 32K-Word x 31
 - Provides sector protect function to prevent program or erase operation in the protected sector
 - Provides chip unprotect function to allow code changing
 - Provides temporary sector unprotect function for code changing in previously protected sector
- Power Supply Operation
 - Vcc 2.7 to 3.6 volt for read, erase, and program operations
 - VI/O 1.65V to 3.6V for Input/Output
- Latch-up protected to 100mA from -1V to 1.5xVcc
- Low Vcc write inhibit : Vcc <= Vlko
- Compatible with JEDEC standard
- Pinout and software compatible to single power supply Flash

PERFORMANCE

- High Performance
 - Fast access time: 90ns
 - Word program time: 11us/word (typical)
 - Fast erase time: 0.7s/sector, 15s/chip (typical)
- Low Power Consumption
 - Low active read current: 5mA (typical) at 5MHz - Low standby current: 5uA (typical)
- 100,000 erase/program cycle (typical)
- 10 years data retention

SOFTWARE FEATURES

- Erase Suspend/ Erase Resume
- Suspends sector erase operation to read data from or program data to another sector which is not being erased
- Status Reply
 - Data# Polling & Toggle bits provide detection of program and erase operation completion
- Support Common Flash Interface (CFI)

HARDWARE FEATURES

- Ready/Busy# (RY/BY#) Output
 - Provides a hardware method of detecting program and erase operation completion
- Hardware Reset (RESET#) Input
- Provides a hardware method to reset the internal state machine to read mode
- WP#/ACC
 - Provide accelerated program capability

PACKAGE

- 48-Pin TSOP
- 48-Ball CSP (TFBGA)
- 48-Ball WFBGA/XFLGA
- All Pb-free devices are RoHS Compliant



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GENERAL DESCRIPTION

MX29LV161DT/B is a 16Mbit flash memory that can be organized as 1,048,576 words. These devices operate over a voltage range of 2.7V to 3.6V typically using a 3V power supply input. The memory array is divided into 32 equal 64 Kilo byte blocks. However, depending on the device being used as a Top-Boot or Bottom-Boot device. The outermost two sectors at the top or at the bottom are respectively the boot blocks for this device.

The MX29LV161DT/B is offered in a 48-pin TSOP, 48-ball XFLGA/WFBGA and a 48-ball CSP(TFBGA) JEDEC standard package. These packages are offered lead-free versions that are compliant to the RoHS specifications. The software algorithm used for this device also adheres to the JEDEC standard for single power supply devices. These flash parts can be programmed in system or on commercially available EPROM/Flash programmers.

Separate OE# and CE# (Output Enable and Chip Enable) signals are provided to simplify system design. When used with high speed processors, the 90ns read access time of this flash memory permits operation with minimal time lost due to system timing delays.

The automatic write algorithm provided on Macronix flash memories perform an automatic erase prior to write. The user only needs to provide a write command to the command register. The on-chip state machine automatically controls the program and erase functions including all necessary internal timings. Since erase and write operations take much longer time than read operations, erase/write can be interrupted to perform read operations in other sectors of the device. For this, Erase Suspend operation along with Erase Resume operation are provided. Data# polling or Toggle bits are used to indicate the end of the erase/write operation.

These devices are manufactured at the Macronix fabrication facility using the time tested and proven MXIC's advance technology. This proprietary non-epi process provides a very high degree of latch-up protection for stresses up to 100 milliamperes on address and data pins from -1V to 1.5xVCC.

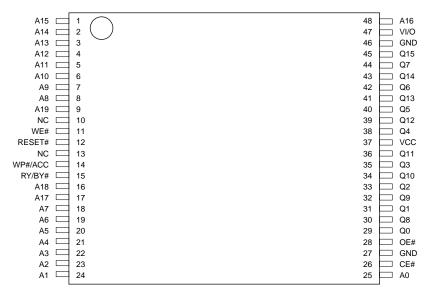
With low power consumption and enhanced hardware and software features, this flash memory retains data reliably for at least ten years. Erase and programming functions have been tested to meet a typical specification of 100,000 cycles of operation.



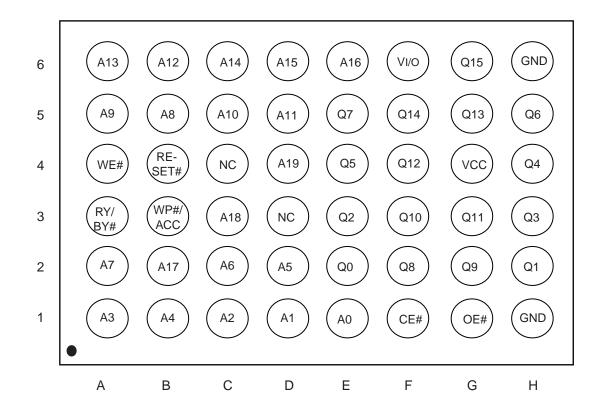
MX29LV161D T/B

PIN CONFIGURATIONS

48 TSOP (Standard Type) (12mm x 20mm)



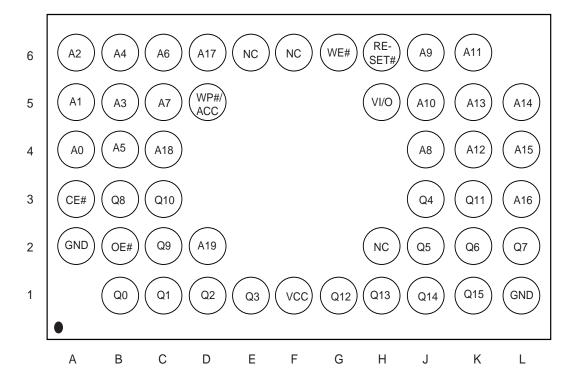
48-Ball CSP (TFBGA) (Ball Pitch =0.8mm, Top View, Balls Facing Down, 6 x 8 mm)



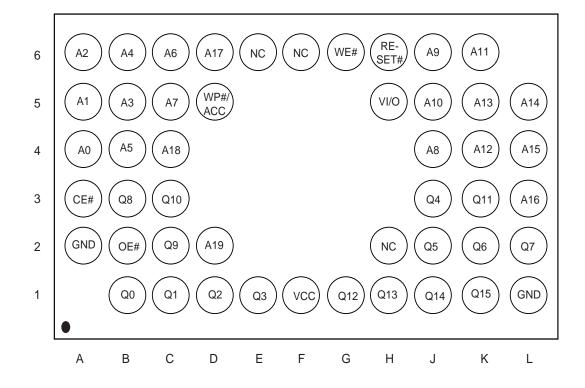


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48-Ball WFBGA (Balls Facing Down, 4 x 6 x 0.75 mm)



48-Ball XFLGA (Balls Facing Down, 4 x 6 x 0.5 mm)

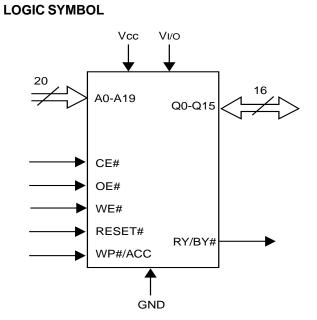




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PIN DESCRIPTION

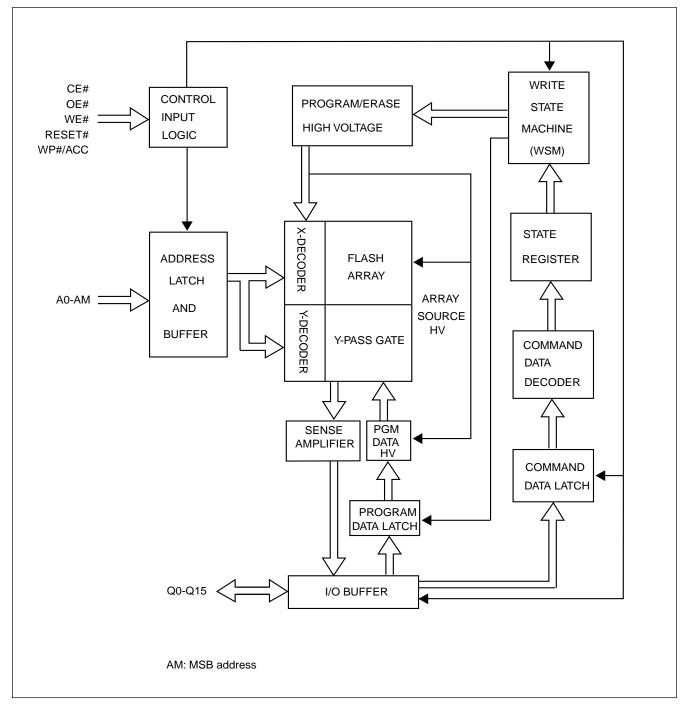
SYMBOL	PIN NAME
A0~A19	Address Input
Q0~Q15	Data Input/Output
CE#	Chip Enable Input
WE#	Write Enable Input
RESET#	Hardware Reset Pin/Sector Protect Unlock
OE#	Output Enable Input
RY/BY#	Ready/Busy Output
VCC	Power Supply Pin (2.7V~3.6V)
GND	Ground Pin
VI/O	Power Supply for Input/Output
WP#/ACC	Hardware write Protect/Acceleration Pin
NC	Pin Not Connected Internally





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BLOCK DIAGRAM





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BLOCK DIAGRAM DESCRIPTION

The block diagram on Page 10 illustrates a simplified architecture of MX29LV161D T/B. Each block in the block diagram represents one or more circuit modules in the real chip used to access, erase, program, and read the memory array.

The "CONTROL INPUT LOGIC" block receives input pins CE#, OE#, WE#, RESET# and WP#/ACC. It creates internal timing control signals according to the input pins and outputs to the "ADDRESS LATCH AND BUFFER" to latch the external address pins A0-AM(A19). The internal addresses are output from this block to the main array and decoders composed of "X-DECODER", "Y-DECODER", "Y-PASS GATE", and "FLASH ARRAY". The X-DECODER decodes the word-lines of the flash array, while the Y-DECODER decodes the bit-lines of the flash array. The bit lines are electrically connected to the "SENSE AMPLIFIER" and "PGM DATA HV" selectively through the y-pass gates. Sense amplifiers are used to read out the contents of the flash memory, while the "PGM DATA HV" block is used to selectively deliver high power to bit-lines during programming. The "I/O BUFFER" controls the input and output on the Q0-Q15 pads. During read operation, the I/O buffer receives data from sense amplifiers and drives the output pads accordingly. In the last cycle of program command, the I/O buffer transmits the data on Q0-Q15 to "PROGRAM DATA LATCH", which controls the high power drivers in "PGM DATA HV" to selectively program the bits in a word according to the user input pattern.

The "PROGRAM/ERASE HIGH VOLTAGE" block comprises the circuits to generate and deliver the necessary high voltage to the "X-DECODER", "FLASH ARRAY", and "PGM DATA HV" block. The logic control module comprises of the "WRITE STATE MACHINE(WSM)", "STATE REGISTER", "COMMAND DATA DECODER", and "COMMAND DATA LATCH". When the user issues a command by toggling WE#, the command on Q0-Q15 is latched in the command data latch and is decoded by the command data decoder. The state register receives the command and records the current state of the device. The WSM implements the internal algorithms for program or erase according to the current command state by controlling each block in the block diagram.





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BLOCK STRUCTURE

The main flash memory array can be organized as 1M Words. The details of the address ranges and the corresponding sector addresses are shown in Table 1-1&1-2. Table 1-1. shows the sector architecture for the Top Boot part, whereas Table 1-2. shows the sector architecture for the Bottom Boot part.

Table 1-1. MX29LV161DT SECTOR ARCHITECTURE

Sector Size Word Mode	Sector	Sector Address A19-A12	Address Range Word Mode (x16)
(Kwords)			
32	SA0	00000xxx	000000h-07FFFh
32	SA1	00001xxx	008000h-0FFFFh
32	SA2	00010xxx	010000h-17FFFh
32	SA3	00011xxx	018000h-01FFFFh
32	SA4	00100xxx	020000h-027FFFh
32	SA5	00101xxx	028000h-02FFFFh
32	SA6	00110xxx	030000h-037FFFh
32	SA7	00111xxx	038000h-03FFFFh
32	SA8	01000xxx	040000h-047FFFh
32	SA9	01001xxx	048000h-04FFFFh
32	SA10	01010xxx	050000h-057FFFh
32	SA11	01011xxx	058000h-05FFFFh
32	SA12	01100xxx	060000h-067FFFh
32	SA13	01101xxx	068000h-06FFFFh
32	SA14	01110xxx	070000h-077FFFh
32	SA15	01111xxx	078000h-07FFFFh
32	SA16	10000xxx	080000h-087FFFh
32	SA17	10001xxx	088000h-08FFFFh
32	SA18	10010xxx	090000h-097FFFh
32	SA19	10011xxx	098000h-09FFFFh
32	SA20	10100xxx	0A0000h-0A7FFFh
32	SA21	10101xxx	0A8000h-0AFFFFh
32	SA22	10110xxx	0B0000h-0B7FFFh
32	SA23	10111xxx	0B8000h-0BFFFFh
32	SA24	11000xxx	0C0000h-0C7FFFh
32	SA25	11001xxx	0C8000h-0CFFFFh
32	SA26	11010xxx	0D0000h-0D7FFFh
32	SA27	11011xxx	0D8000h-0DFFFFh
32	SA28	11100xxx	0E0000h-0E7FFFh
32	SA29	11101xxx	0E8000h-0EFFFFh
32	SA30	11110xxx	0F0000h-0F7FFFh
16	SA31	111110xx	0F8000h-0FBFFFh
4	SA32	1111100	0FC000h-0FCFFFh
4	SA33	1111101	0FD000h-0FDFFFh
8	SA34	1111111x	0FE000h-0FFFFFh



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Table 1-2. MX29LV161DB SECTOR ARCHITECTURE

Sector Size Word Mode (Kwords)	Sector	Sector Address A19-A12	Address Range Word Mode (x16)
8	SA0	0000000x	000000h-001FFFh
4	SA1	0000010	002000h-002FFFh
4	SA2	00000011	003000h-003FFFh
16	SA3	000001xx	004000h-007FFFh
32	SA4	00001xxx	008000h-00FFFFh
32	SA5	00010xxx	010000h-017FFFh
32	SA6	00011xxx	018000h-01FFFFh
32	SA7	00100xxx	020000h-027FFFh
32	SA8	00101xxx	028000h-02FFFFh
32	SA9	00110xxx	030000h-037FFFh
32	SA10	00111xxx	038000h-03FFFFh
32	SA11	01000xxx	040000h-047FFFh
32	SA12	01001xxx	048000h-04FFFFh
32	SA13	01010xxx	050000h-057FFFh
32	SA14	01011xxx	058000h-05FFFFh
32	SA15	01100xxx	060000h-067FFFh
32	SA16	01101xxx	068000h-06FFFFh
32	SA17	01110xxx	070000h-077FFFh
32	SA18	01111xxx	078000h-07FFFFh
32	SA19	10000xxx	080000h-087FFFh
32	SA20	10001xxx	088000h-08FFFFh
32	SA21	10010xxx	090000h-097FFFh
32	SA22	10011xxx	098000h-09FFFFh
32	SA23	10100xxx	0A0000h-0A7FFFh
32	SA24	10101xxx	0A8000h-0AFFFFh
32	SA25	10110xxx	0B0000h-0B7FFFh
32	SA26	10111xxx	0B8000h-0BFFFFh
32	SA27	11000xxx	0C0000h-0C7FFFh
32	SA28	11001xxx	0C8000h-0CFFFFh
32	SA29	11010xxx	0D0000h-0D7FFFh
32	SA30	11011xxx	0D8000h-0DFFFFh
32	SA31	11100xxx	0E0000h-0E7FFFh
32	SA32	11101xxx	0E8000h-0EFFFFh
32	SA33	11110xxx	0F0000h-0F7FFFh
32	SA34	11111xxx	0F8000h-0FFFFFh



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BUS OPERATIONS

Table 2-1. BUS OPERATION

Mode Select	RESET#	CE#	WE#	OE#	Address	Data (I/O)	WP#/
						Q0~Q15	ACC
Device Reset	L	Х	Х	Х	Х	HighZ	L/H
Standby Mode	Vcc±0.3V	Vcc±0.3V	Х	Х	Х	HighZ	Н
Output Disable	Н	L	Н	Н	Х	HighZ	L/H
Read Mode	Н	L	Н	L	AIN	DOUT	L/H
Write (Note 1)	Н	L	L	Н	AIN	DIN	Note 3
Accelerate Program	Н	L	L	Н	AIN	DIN	Vhv
Temporary Sector	Vhv	Х	Х	Х	AIN	DIN	Note 3
Unprotect							
Sector Protect	Vhv	L	L	Н	Sector Address,	DIN, DOUT	L/H
(Note 2)					A6=L, A1=H,		
					A0=L		
Chip Unprotect	Vhv	L	L	Н	Sector Address,	DIN, DOUT	Note 3
(Note 2)					A6=H, A1=H,		
					A0=L		

Notes:

1. All sectors will be unprotected if WP#/ACC=Vhv.

2. The one outmost boot sectors are protected if WP#/ACC=Vil.

3. When WP#/ACC = Vih, the protection conditions of the one outmost boot sectors depend on previous protection conditions."Sector/Sector Block Protection and Unprotection" describes the protect and unprotect method.

4. Q0~Q15 are input (DIN) or output (DOUT) pins according to the requests of command sequence, sector protection, or data polling algorithm.



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Table 2-2. BUS OPERATION

ltem	Co	ntrol Ir	nput	AM	A11		A 8		A5				
	CE#	WE#	OE#	to	to	A9	to	A6	to	A1	A0	Q0~Q7	Q8~Q15
				A12	A10		A7		A2				
Sector Lock Status	L	Н	L	SA	х	$V_{\rm hv}$	х	L	х	Н	L	01h or	х
Verification												00h	
												(Note1)	
Read Silicon ID	L	Н	L	х	х	$V_{\rm hv}$	х	L	х	L	L	C2h	х
Manufacturer Code													
Read Silicon ID	L	Н	L	х	х	$V_{\rm hv}$	х	L	х	L	н	C4h	22h
MX29LV161DT													
Read Silicon ID	L	Н	L	х	х	$V_{\rm hv}$	х	L	х	L	Н	49h	22h
MX29LV161DB													

Notes:

1. Sector unprotected code:00h. Sector protected code:01h.

2. AM: MSB of address.



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FUNCTIONAL OPERATION DESCRIPTIONS

WRITE COMMANDS/COMMAND SEQUENCES

To write a command to the device, system must drive WE# and CE# to Vil, and OE# to Vih. In a command cycle, all addresses are latched at the later falling edge of CE# and WE#, and all data are latched at the earlier rising edge of CE# and WE#.

Figure 1 illustrates the AC timing waveform of a write command, and Table 3 defines all the valid command sets of the device. System is not allowed to write invalid commands not defined in this datasheet. Writing an invalid command will bring the device to an undefined state.

REQUIREMENTS FOR READING ARRAY DATA

Read array action is to read the data stored in the array. While the memory device is in powered up or has been reset, it will automatically enter the status of read array. If the microprocessor wants to read the data stored in array, it has to drive CE# (device enable control pin) and OE# (Output control pin) as Vil, and input the address of the data to be read into address pins at the same time. After a period of read cycle (Tce or Taa), the data being read out will be displayed on output pins for microprocessor to access. If CE# or OE# is Vih, the output will be in tri-state, and there will be no data displayed on output pin at all.

After the memory device completes embedded operation (automatic Erase or Program), it will automatically return to the status of read array, and the device can read the data in any address in the array. In the process of erasing, if the device receives the Erase suspend command, erase operation will be stopped temporarily after a period of time no more than Tready1 and the device will return to the status of read array. At this time, the device can read the data stored in any address except the sector being erased in the array. In the status of erase suspend, if user wants to read the data in the sectors being erased, the device will output status data onto the output. Similarly, if program command is issued after erase suspend, after program operation is completed, system can still read array data in any address except the sectors to be erased.

The device needs to issue reset command to enable read array operation again in order to arbitrarily read the data in the array in the following two situations:

1. In program or erase operation, the programming or erasing failure causes Q5 to go high.

2. The device is in auto select mode or CFI mode.

In the two situations above, if reset command is not issued, the device is not in read array mode and system must issue reset command before reading array data.





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RESET# OPERATION

Driving RESET# pin low for a period more than Trp will reset the device back to read mode. If the device is in program or erase operation, the reset operation will take at most a period of Tready1 for the device to return to read array mode. Before the device returns to read array mode, the RY/BY# pin remains low (busy status).

When RESET# pin is held at GND±0.3V, the device consumes standby current(Isb).However, device draws larger current if RESET# pin is held at Vil but not within GND±0.3V.

It is recommended that the system to tie its reset signal to RESET# pin of flash memory, so that the flash memory will be reset during system reset and allows system to read boot code from flash memory.

SECTOR PROTECT OPERATION

When a sector is protected, program or erase operation will be disabled on that protected sector. MX29LV161D T/B provides two methods for sector protection.

Once the sector is protected, the sector remains protected until next chip unprotect, or is temporarily unprotected by asserting RESET# pin at Vhv. Refer to temporary sector unprotect operation for further details.

The first method is by applying Vhv on RESET# pin. Refer to Figure 12 for timing diagram and Figure 13 for the algorithm for this method.

The other method is asserting Vhv on A9 and OE# pins, with A6 and CE# at Vil. The protection operation begins at the falling edge of WE# and terminates at the rising edge. Contact Macronix for details.

CHIP UNPROTECT OPERATION

MX29LV161D T/B provides two methods for chip unprotect. The chip unprotect operation unprotects all sectors within the device. It is recommended to protect all sectors before activating chip unprotect mode. All sectors are unprotected when shipped from the factory.

The first method is by applying Vhv on RESET# pin. Refer to Figure 12 for timing diagram and Figure 14 for algorithm of the operation.

The other method is asserting Vhv on A9 and OE# pins, with A6 at Vih and CE# at Vil. The unprotect operation begins at the falling edge of WE# and terminates at the rising edge. Contact Macronix for details.

HARDWARE WRITE PROTECT

By driving the WP#/ACC pin LOW, the outermost one boot sectors are protected from all erase/program operations. If WP#/ACC is held HIGH (Vih to VCC), these one outermost sectors revert to their previously protected/unprotected status.

ACCELERATED PROGRAMMING OPERATION

By applying high voltage (Vhv) to the WP#/ACC pin, the device will enter the Accelerated Programming mode. This mode permits the system to skip the normal command unlock sequences and program word locations directly.



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Typically, this mode provides a 30% reduction in overall programming times. During accelerated programming, the current drawn from the WP#/ACC pin is no more than ICP1.

TEMPORARY SECTOR UNPROTECT OPERATION

System can apply RESET# pin at Vhv to place the device in temporary unprotect mode. In this mode, previously protected sectors can be programmed or erased just as it is unprotected. The devices return to normal operation once Vhv is removed from RESET# pin and previously protected sectors are again protected.

AUTOMATIC SELECT OPERATION

When the device is in Read array mode, erase-suspended read array mode or CFI mode, user can issue read silicon ID command to enter read silicon ID mode. After entering read silicon ID mode, user can query several silicon IDs continuously and does not need to issue read silicon ID mode again. When A0 is Low, device will output Macronix Manufacture ID C2h. When A0 is high, device will output Device ID. In read silicon ID mode, issuing reset command will reset device back to read array mode or erase-suspended read array mode.

Another way to enter read silicon ID is to apply high voltage on A9 pin with CE#, OE#, A6 and A1 at Vil. While the high voltage of A9 pin is discharged, device will automatically leave read silicon ID mode and go back to read array mode or erase-suspended read array mode. When A0 is Low, device will output Macronix Manufacture ID C2h. When A0 is high, device will output Device ID.

VERIFY SECTOR PROTECT STATUS OPERATION

MX29LV161D T/B provides hardware sector protection against Program and Erase operation for protected sectors. The sector protect status can be read through Sector Protect Verify command. This method requires Vhv on A9 pin, Vih on WE# and A1 pins, Vil on CE#, OE#, A6 and A0 pins, and sector address on A12 to AM pins. If the read out data is 01h, the designated sector is protected. Oppositely, if the read out data is 00h, the designated sector is not protected.

DATA PROTECTION

To avoid accidental erasure or programming of the device, the device is automatically reset to read array mode during power up. Besides, only after successful completion of the specified command sets will the device begin its erase or program operation.

Other features to protect the data from accidental alternation are described as followed.

LOW VCC WRITE INHIBIT

The device refuses to accept any write command when Vcc is less than Vlko. This prevents data from spuriously altered. The device automatically resets itself when Vcc is lower than Vlko and write cycles are ignored until Vcc is greater than Vlko. System must provide proper signals on control pins after Vcc is larger than Vlko to avoid unintentional program or erase operation



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WRITE PULSE "GLITCH" PROTECTION

CE#, WE#, OE# pulses shorter than 5ns are treated as glitches and will not be regarded as an effective write cycle.

LOGICAL INHIBIT

A valid write cycle requires both CE# and WE# at Vil with OE# at Vih. Write cycle is ignored when either CE# at Vih, WE# at Vih, or OE# at Vil.

POWER-UP SEQUENCE

Upon power up, MX29LV161D T/B is placed in read array mode. Furthermore, program or erase operation will begin only after successful completion of specified command sequences.

POWER-UP WRITE INHIBIT

When WE#, CE# is held at Vil and OE# is held at Vih during power up, the device ignores the first command on the rising edge of WE#.

POWER SUPPLY DECOUPLING

A 0.1uF capacitor should be connected between the Vcc and GND to reduce the noise effect.



MX29LV161D T/B

COMMAND OPERATIONS

TABLE 3. MX29LV161DT/B COMMAND DEFINITIONS

				Automatic Select				
				Manifacture		Protect		
Command		Read Mode	Reset Mode	ID	Device ID	Verify	Program	Chip Erase
	Hex							
1st Bus	Address	Addr	XXX	555	555	555	555	555
Cycle	Data	Data	F0	AA	AA	AA	AA	AA
2nd Bus	Address			2AA	2AA	2AA	2AA	2AA
Cycle	Data			55	55	55	55	55
3rd Bus	Address			555	555	555	555	555
Cycle	Data			90	90	90	A0	80
4th Bus	Address			X00	X01	(Sector)X02	Address	555
Cycle	Data			C2h	ID	00/01	Data	AA
5th Bus	Address							2AA
Cycle	Data							55
6th Bus	Address							555
Cycle	Data							10

Command		Sector Erase	CFI Read	Erase Suspend	Erase Resume
	Hex				
1st Bus	Address	555	55	XXX	XXX
Cycle	Data	AA	98	В0	30
2nd Bus	Address	2AA			
Cycle	Data	55			
3rd Bus	Address	555			
Cycle	Data	80			
4th Bus	Address	555			
Cycle	Data	AA			
5th Bus	Address	2AA			
Cycle	Data	55			
6th Bus	Address	Sector			
Cycle	Data	30			

Notes:

1. Device ID : MX29LV161DT: 22C4h; MX29LV161DB: 2249h.

2. For sector protect verify result, XX00h/00h means sector is not protected, XX01h/01h means sector has been protected.

3. Sector Protect command is valid during Vhv at RESET# pin, Vih at A1 pin and Vil at A0, A6 pins. The last Bus cycle is for protect verify.

4. It is not allowed to adopt any other code which is not in the above command definition table.



MX29LV161D T/B

COMMAND OPERATIONS (cont'd)

AUTOMATIC PROGRAMMING OF THE MEMORY ARRAY

The MX29LV161D T/B provides the user the ability to program the memory array in Word mode. As long as the users enters the correct cycle defined in the Table 3 (including 2 unlock cycles and the A0h program command), any word data provided on the data lines by the system will automatically be programmed into the array at the specified location.

After the program command sequence has been executed, the internal write state machine (WSM) automatically executes the algorithms and timings necessary for programming and verification, which includes generating suitable program pulses, checking cell threshold voltage margins, and repeating the program pulse if any cells do not pass verification or have low margins. The internal controller protects cells that do pass verification and margin tests from being over-programmed by inhibiting further program pulses to these passing cells as weaker cells continue to be programmed.

With the internal WSM automatically controlling the programming process, the user only needs to enter the program command and data once.

Programming will only change the bit status from "1" to "0". It is not possible to change the bit status from "0" to "1" by programming. This can only be done by an erase operation. Furthermore, the internal write verification only checks and detects errors in cases where a "1" is not successfully programmed to "0".

Any commands written to the device during programming will be ignored except hardware reset, which will terminate the program operation after a period of time no more than Tready1. When the embedded program algorithm is complete or the program operation is terminated by a hardware reset, the device will return to Read mode.

After the embedded program operation has begun, the user can check for completion by reading the following bits in the status register:

Status	Q7*1	Q6 ^{*1}	Q5	RY/BY# [™] 2
In progress *3	Q7#	Toggling	0	0
Finished	Q7	Stop toggling	0	1
Exceed time limit	Q7#	Toggling	1	0

*1: When an attempt is made to program a protected sector, the program operation will abort thus preventing any data changes in the protected sector. Q7 will output complement data and Q6 will toggle briefly (1us or less) before aborting and returning the device to Read mode.

*2: RY/BY# is an open drain output pin and should be connected to VCC through a high value pull-up resistor.

*3: The status "in progress" means both program and erase-suspended program mode.

ERASING THE MEMORY ARRAY

There are two types of erase operations performed on the memory array -- Sector Erase and Chip Erase. In the Sector Erase operation, one or more selected sectors may be erased simultaneously. In the Chip Erase operation, the complete memory array is erased except for any protected sectors.



MX29LV161D T/B

COMMAND OPERATIONS (cont'd)

SECTOR ERASE

The sector erase operation is used to clear data within a sector by returning all of its memory locations to the "1" state. It requires six command cycles to initiate the erase operation. The first two cycles are "unlock cycles", the third is a configuration cycle, the fourth and fifth are also "unlock cycles", and the sixth cycle is the Sector Erase command. After the sector erase command sequence has been issued, an internal 50us time-out counter is started. Until this counter reaches zero, additional sector addresses and Sector Erase commands may be issued thus allowing multiple sectors to be selected and erased simultaneously. After the 50us time-out counter has expired, no new commands will be accepted and the embedded sector erase operation will begin. Note that the 50us timer-out counter is restarted after every erase command sequence. If the user enters any command other than Sector Erase or Erase Suspend during the time-out period, the erase operation will abort and the device will return to Read mode.

After the embedded sector erase operation begins, all commands except Erase Suspend will be ignored. The only way to interrupt the operation is with an Erase Suspend command or with a hardware reset. The hardware reset will completely abort the operation and return the device to Read mode.

Status	Q7	Q6	Q5	Q3 (note 1)	Q2	RY/BY#(note 2)
Time-out period	0	Toggling	0	0	Toggling	0
In progress	0	Toggling	0	1	Toggling	0
Finished	1	Stop toggling	0	1	1	1
Exceeded time limit	0	Toggling	1	1	Toggling	0

The system can determine the status of the embedded sector erase operation by the following methods:

Note :

- 1. The Q3 status bit is the time-out indicator. When Q3=0, the time-out counter has not yet reached zero and a new Sector Erase command may be issued to specify the address of another sector to be erased. When Q3=1, the time-out counter has expired and the Sector Erase operation has already begun. Erase Suspend is the only valid command that may be issued once the embedded erase operation is underway.
- 2. RY/BY# is an open drain output pin and should be connected to VCC through a high value pull-up resistor.
- 3. When an attempt is made to erase only protected sector(s), the program operation will abort thus preventing any data changes in the protected sector(s). Q7 will output its complement data and Q6 will toggle briefly (100us or less) before aborting and returning the device to Read mode. If unprotected sectors are also specified, however, they will be erased normally and the protected sector(s) will remain unchanged.
- 4. Q2 is a localized indicator showing a specified sector is undergoing erase operation or not. Q2 toggles when user reads at addresses where the sectors are actively being erased (in erase mode) or to be erased (in erase suspend mode). When a sector has been completely erased, Q2 stops toggling at the sector even when the device is still in erase operation for remaining selected sectors. At that circumstance, Q2 will still toggle when device is read at any other sector that remains to be erased.



MX29LV161D T/B

COMMAND OPERATIONS (cont'd)

CHIP ERASE

The Chip Erase operation is used erase all the data within the memory array. All memory cells containing a "0" will be returned to the erased state of "1". This operation requires 6 write cycles to initiate the action. The first two cycles are "unlock" cycles, the third is a configuration cycle, the fourth and fifth are also "unlock" cycles, and the sixth cycle initiates the chip erase operation.

During the chip erase operation, no other software commands will be accepted, but if a hardware reset is received or the working voltage is too low, that chip erase will be terminated. After Chip Erase, the chip will automatically return to Read mode.

The system can determine the status of the embedded chip erase operation by the following methods:

Status	Q7	Q6	Q5	Q2	RY/BY#⁵1
In progress	0	Toggling	0	Toggling	0
Finished	1	Stop toggling	0	1	1
Exceed time limit	0	Toggling	1	Toggling	0

*1: RY/BY# is an open drain output pin and should be connected to VCC through a high value pull-up resistor.

SECTOR ERASE SUSPEND

After beginning a sector erase operation, Erase Suspend is the only valid command that may be issued. If system issues an Erase Suspend command during the 50us time-out period following a Sector Erase command, the time-out period will terminate immediately and the device will enter Erase-Suspended Read mode. If the system issues an Erase Suspend command after the sector erase operation has already begun, the device will not enter Erase-Suspended Read mode until Tready1 time has elapsed. The system can determine if the device has entered the Erase-Suspended Read mode through Q6, Q7, and RY/BY#.

After the device has entered Erase-Suspended Read mode, the system can read or program any sector(s) except those being erased by the suspended erase operation. Reading any sector being erased or programmed will return the contents of the status register. Whenever a suspend command is issued, user must issue a resume command and check Q6 toggle bit status, before issue another erase command. The system can use the status register bits shown in the following table to determine the current state of the device:

Status	Q7	Q6	Q5	Q3	Q2	RY/BY#
Erase suspend read in erase suspended sector	1	No toggle	0	N/A	Toggle	1
Erase suspend read in non-erase suspended sector	Data	Data	Data	Data	Data	1
Erase suspend program in non-erase suspended sector	Q7#	Toggle	0	N/A	N/A	0

When the device has suspended erasing, user can execute the command sets except sector erase and chip erase, such as read silicon ID, sector protect verify, program, CFI query and erase resume.



MX29LV161D T/B

COMMAND OPERATIONS (cont'd)

SECTOR ERASE RESUME

The sector Erase Resume command is valid only when the device is in Erase-Suspended Read mode. After erase resumes, the user can issue another Ease Suspend command, but there should be a 4ms interval between Ease Resume and the next Erase Suspend command. If the user enters an infinite suspend-resume loop, or suspend-resume exceeds 1024 times, erase times will increase dramatically.

AUTOMATIC SELECT OPERATIONS

When the device is in Read mode, Erase-Suspended Read mode, or CFI mode, the user can issue the Automatic Select command shown in Table 3 (two unlock cycles followed by the Automatic Select command 90h) to enter Automatic Select mode. After entering Automatic Select mode, the user can query the Manufacturer ID, Device ID, or Sector protected status multiple times without issuing a new Automatic Select command.

While In Automatic Select mode, issuing a Reset command (F0h) will return the device to Read mode (or Erase-Suspended Read mode if Erase-Suspend was active).

Another way to enter Automatic Select mode is to use one of the bus operations shown in Table 2-2. BUS OPERATION. After the high voltage (Vhv) is removed from the A9 pin, the device will automatically return to Read mode or Erase-Suspended Read mode.

AUTOMATIC SELECT COMMAND SEQUENCE

Automatic Select mode is used to access the manufacturer ID, device ID and to verify whether or not a sector is protected. The automatic select mode has four command cycles. The first two are unlock cycles, and followed by a specific command. The fourth cycle is a normal read cycle, and user can read at any address any number of times without entering another command sequence. The reset command is necessary to exit the Automatic Select mode and back to read array. The following table shows the identification code with corresponding address.

	Address (Hex)	Data (Hex)	Representation
Manufacturer ID	X00	00C2	
Device ID	X01	22C4/2249	Top/Bottom Boot Sector
Sector Protect Verify	(Sector address) X 02	00/01	Unprotected/protected

After entering automatic select mode, no other commands are allowed except the reset command.



MX29LV161D T/B

COMMAND OPERATIONS (cont'd)

READ MANUFACTURER ID OR DEVICE ID

The Manufacturer ID (identification) is a unique hexadecimal number assigned to each manufacturer by the JEDEC committee. Each company has its own manufacturer ID, which is different from the ID of all other companies. The number assigned to Macronix is C2h.

The Device ID is a unique hexadecimal number assigned by the manufacturer for each one of the flash devices made by that manufacturer.

The above two ID types are stored in a 16-bit register on the flash device -- eight bits for each ID. This register is normally read by the user or by the programming machine to identify the manufacturer and the specific device.

After entering Automatic Select mode, performing a read operation with A1 & A0 held LOW will cause the device to output the Manufacturer ID on the Data I/O (Q7 to Q0) pins. Performing a read operation with A1 LOW and A0 HIGH will cause the device to output the Device ID.

VERIFY SECTOR PROTECTION

After entering Automatic Select mode, performing a read operation with A1 held HIGH and A0, A6 held LOW and the address of the sector to be checked applied to A19 to A12, data bit Q0 will indicate the protected status of the addressed sector. If Q0 is HIGH, the sector is protected. Conversely, if Q0 is LOW, the sector is unprotected.

RESET

In the following situations, executing reset command will reset device back to read array mode:

- Among erase command sequence (before the full command set is completed)
- Sector erase time-out period
- Erase fail (while Q5 is high)
- Among program command sequence (before the full command set is completed, erase-suspended program included)
- Program fail (while Q5 is high, and erase-suspended program fail is included)
- Read silicon ID mode
- Sector protect verify
- CFI mode

While device is at the status of program fail or erase fail (Q5 is high), user must issue reset command to reset device back to read array mode. While the device is in read silicon ID mode, sector protect verify or CFI mode, user must issue reset command to reset device back to read array mode.

When the device is in the progress of programming (not program fail) or erasing (not erase fail), device will ignore reset command.



MX29LV161D T/B

COMMON FLASH MEMORY INTERFACE (CFI) MODE

QUERY COMMAND AND COMMON FLASH INTERFACE (CFI) MODE

MX29LV161D T/B features CFI mode. Host system can retrieve the operating characteristics, structure and vendorspecified information such as identifying information, memory size, byte/word configuration, operating voltages and timing information of this device by CFI mode. If the system writes the CFI Query command "98h", to address "55h"/ "AAh" (depending on Word/Byte mode), the device will enter the CFI Query Mode, any time the device is ready to read array data. The system can read CFI information at the addresses given in Table 4.

Once user enters CFI query mode, user can not issue any other commands except reset command. The reset command is required to exit CFI mode and go back to the mode before entering CFI. The system can write the CFI Query command only when the device is in read mode, erase suspend, standby mode or automatic select mode.

Table 4-1. CFI mode: Identification Data Values

(All values in these tables are in hexadecimal)

Description	Address(h)	Data (h)
	(Word Mode)	
Query-unique ASCII string "QRY"	10	0051
	11	0052
	12	0059
Primary vendor command set and control interface ID code	13	0002
	14	0000
Address for primary algorithm extended query table	15	0040
	16	0000
Alternate vendor command set and control interface ID code	17	0000
	18	0000
Address for alternate algorithm extended query table	19	0000
	1A	0000

Table 4-2. CFI Mode: System Interface Data Values

Description	Address(h)	Data (h)
	(Word Mode)	
Vcc supply minimum program/erase voltage	1B	0027
Vcc supply maximum program/erase voltage	1C	0036
VPP supply minimum program/erase voltage	1D	0000
VPP supply maximum program/erase voltage	1E	0000
Typical timeout per single word write, 2 ⁿ us	1F	0004
Typical timeout for maximum-size buffer write, 2 ⁿ us	20	0000
Typical timeout per individual block erase, 2 ⁿ ms	21	000A
Typical timeout for full chip erase, 2 ⁿ ms	22	0000
Maximum timeout for word write, 2 ⁿ times typical	23	0005
Maximum timeout for buffer write, 2 ⁿ times typical	24	0000
Maximum timeout per individual block erase, 2 ⁿ times typical	25	0004
Maximum timeout for chip erase, 2 ⁿ times typical	26	0000



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Table 4-3. CFI Mode: Device Geometry Data Values

Description	Address(h)	Data (h)
	(Word Mode)	
Device size = 2^n in number of bytes (MX29LV161D)	27	0015
Flash device interface description (01=asynchronous x16)	28	0001
	29	0000
Maximum number of bytes in buffer write = 2 ⁿ (not support)	2A	0000
	2B	0000
Number of erase regions within device	2C	0004
Index for Erase Bank Area 1	2D	0000
[2E,2D] = # of same-size sectors in region 1-1	2E	0000
[30, 2F] = sector size in multiples of 256-bytes	2F	0040
	30	0000
Index for Erase Bank Area 2	31	0001
	32	0000
	33	0020
	34	0000
Index for Erase Bank Area 3	35	0000
	36	0000
	37	0080
	38	0000
Index for Erase Bank Area 4 (for MX29LV161D)	39	001E
	3A	0000
	3B	0000
	3C	0001



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Table 4-4. CFI Mode: Primary Vendor-Specific Extended Query Data Values

Description	Address(h)	Data (h)
	(Word Mode)	
Query - Primary extended table, unique ASCII string, PRI	40	0050
	41	0052
	42	0049
Major version number, ASCII	43	0031
Minor version number, ASCII	44	0030
Unlock recognizes address (0= recognize, 1= don't recognize)	45	0000
Erase suspend (2= to both read and program)	46	0002
Sector protect (N= # of sectors/group)	47	0001
Temporary sector unprotect (1=supported)	48	0001
Sector protect/Chip unprotect scheme	49	0004
Simultaneous R/W operation (0=not supported)	4A	0000
Burst mode (0=not supported)	4B	0000
Page mode (0=not supported)	4C	0000
Minimum acceleration supply (0= not supported), [D7:D4] for volt,	4D	00A5
[D3:D0] for 100mV		
Maximum acceleration supply (0= not supported), [D7:D4] for volt,	4E	00B5
[D3:D0] for 100mV		
Top/Bottom boot block indicator	4F	0002/
02h=bottom boot device 03h=top boot device		0003



MX29LV161D T/B

ELECTRICAL CHARACTERISTICS

ABSOLUTE MAXIMUM STRESS RATINGS

Surrounding Temperature with Bias	65°C to +125°C
Storage Temperature	
Voltage Range	
Vcc	
VI/O	
RESET#, A9 and OE#	0.5 V to +11.5 V
The other pins	
Output Short Circuit Current (less than one second)	

Note:

1. Minimum voltage may undershoot to -2V during transition and for less than 20ns during transitions.

2. Maximum voltage may overshoot to Vcc+2V during transition and for less than 20ns during transitions.

OPERATING TEMPERATURE AND VOLTAGE

Commercial (C) Grade	
Surrounding Temperature (TA)	0°C to +70°C
Industrial (I) Grade	
Surrounding Temperature (TA)	-40° C to +85° C
Vcc Supply Voltages	
Vcc range	+2.7 V to 3.6 V



MX29LV161D T/B

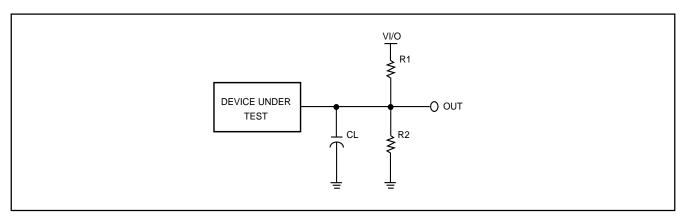
DC CHARACTERISTICS

Symbol	Description	Min	Тур	Max	Remark
lilk	Input Leak			±1.0uA	
lilk9	A9 Leak			35uA	A9=10.5V
lolk	Output Leak			±1.0uA	
lcr1	Read Current(5MHz)		5mA	12mA	CE#=Vil,
					OE#=Vih
lcr2	Read Current(1MHz)		2mA	4mA	CE#=Vil,
					OE#=Vih
Icw	Write Current		15mA	30mA	CE#=Vil,
					OE#=Vih,
					WE#=Vil
lsb	Standby Current		5uA	15uA	Vcc=Vcc max,
					other pins disable
lsbr	Reset Current		5uA	15uA	Vcc=Vccmax,
					Reset# enable,
					other pins disable
lsbs	Sleep Mode Current		5uA	15uA	
lcp1	Accelerated Pgm Current,		5mA	10mA	CE#=Vil,
	WP#/Acc pin				OE#=Vih
lcp2	Accelerated Pgm Current,		15mA	30mA	CE#=Vil,
	Vcc pin				OE#=Vih
Vil	Input Low Voltage	-0.1V		0.3xVI/O	
Vih	Input High Voltage	0.7xVI/O		VI/O+0.3V	
Vhv	Very High Voltage for hardware	9.5V		10.5V	
	Protect/Unprotect/				
	/Auto Select/Temporary Unprotect				
Vol	Output Low Voltage			0.15 x VI/O	lol=100uA
Voh	Output High Voltage	0.85 x VI/O			loh=-100uA
Vlko	Low Vcc Lock-out Voltage	2.3V		2.5V	



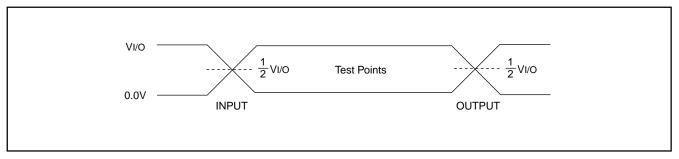
MX29LV161D T/B

SWITCHING TEST CIRCUIT



Test Condition Output Load Capacitance,CL : 30pF(90ns)R1=R2=25K Ω Rise/Fall Times : 5ns In/Out reference levels :VI/O / 2

SWITCHING TEST WAVEFORM





MX29LV161D T/B

AC CHARACTERISTICS

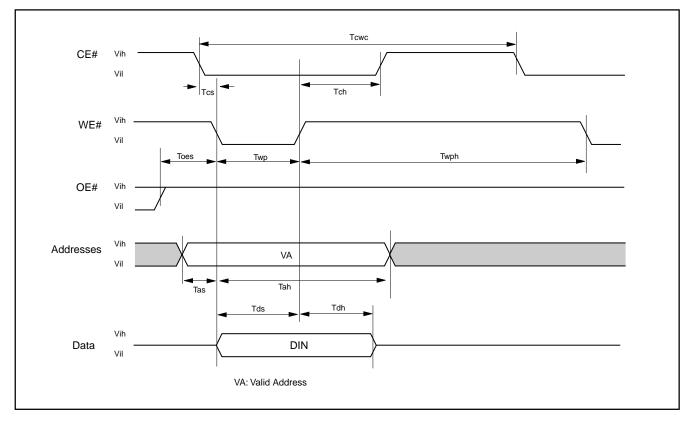
Symbol	Description		Min	Тур	Max	Unit
Taa	Valid data output after address				90	ns
Тсе	Valid data output after CE# low				90	ns
Toe	Valid data output after OE# low				40	ns
Tdf	Data output floating after OE# high				30	ns
Toh	Output hold time from the earliest rising e CE#, OE#	dge of address,	0			ns
Trc	Read period time		90			ns
Twc	Write period time		90			ns
Tcwc	Command write period time		90			ns
Tas	Address setup time		0			ns
Tah	Address hold time		45			ns
Tds	Data setup time		35			ns
Tdh	Data hold time		0			ns
Tvcs	Vcc setup time		200			us
Tcs	Chip enable Setup time		0			ns
Tch	Chip enable hold time		0			ns
Toes	Output enable setup time		0			ns
Toeh		Read	0			ns
Toeh	Output enable hold time	Toggle & Data# Polling	10			ns
Tws	WE# setup time		0			ns
Twh	WE# hold time		0			ns
Тсер	CE# pulse width		35			ns
Tceph	CE# pulse width high		30			ns
Тwp	WE# pulse width		35			ns
Twph	WE# pulse width high		30			ns
Tbusy	Program/Erase active time by RY/BY#				90	ns
Tghwl	Read recover time before write		0			ns
Tghel	Read recover time before write		0			ns
Twhwh1	Program operation			11		us
Twhwh1	Accelerated program operation			7	210	us
Twhwh2	Sector Erase operation			0.7		sec
Tbal	Sector Add hold time				50	us



MX29LV161D T/B

WRITE COMMAND OPERATION

Figure 1. COMMAND WRITE OPERATION

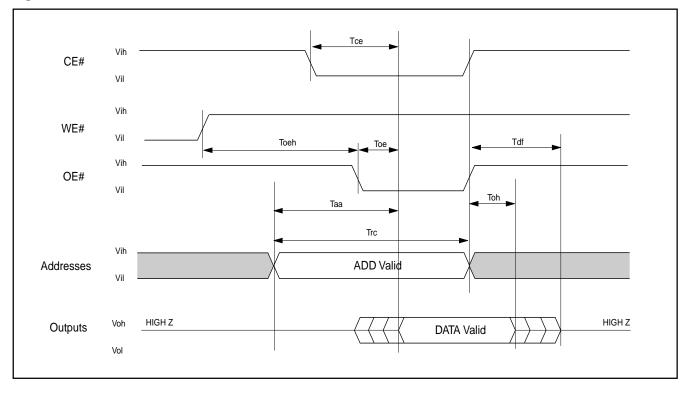




MX29LV161D T/B

READ/RESET OPERATION

Figure 2. READ TIMING WAVEFORM



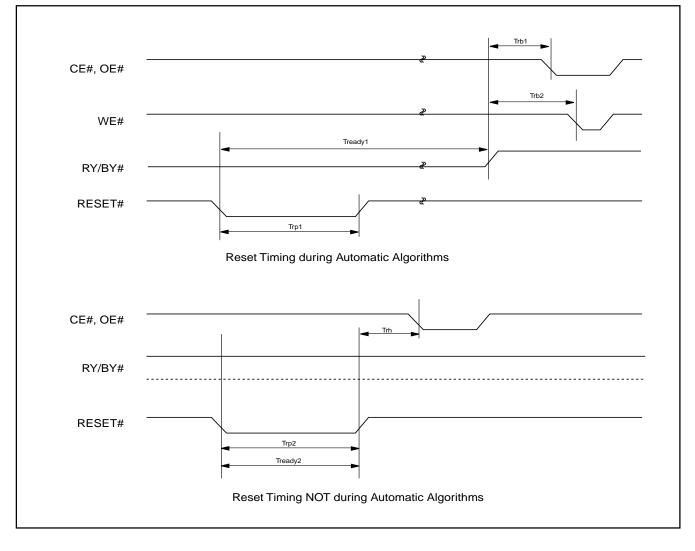


MX29LV161D T/B

AC CHARACTERISTICS

ltem	Description	Setup	Speed	Unit
Trp1	RESET# Pulse Width (During Automatic Algorithms)	MIN	10	us
Trp2	RESET# Pulse Width (NOT During Automatic Algorithms)	MIN	500	ns
Trh	RESET# High Time Before Read	MIN	70	ns
Trb1	RY/BY# Recovery Time (to CE#, OE# go low)	MIN	0	ns
Trb2	RY/BY# Recovery Time (to WE# go low)	MIN	50	ns
Tready1	RESET# PIN Low (During Automatic Algorithms)	MAX	20	us
	to Read or Write			
Tready2	RESET# PIN Low (NOT During Automatic	MAX	500	ns
	Algorithms) to Read or Write			

Figure 3. RESET# TIMING WAVEFORM

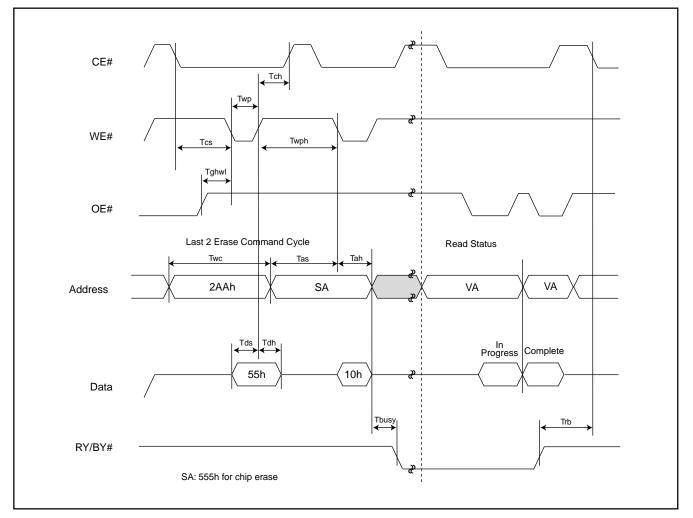




MX29LV161D T/B

ERASE/PROGRAM OPERATION

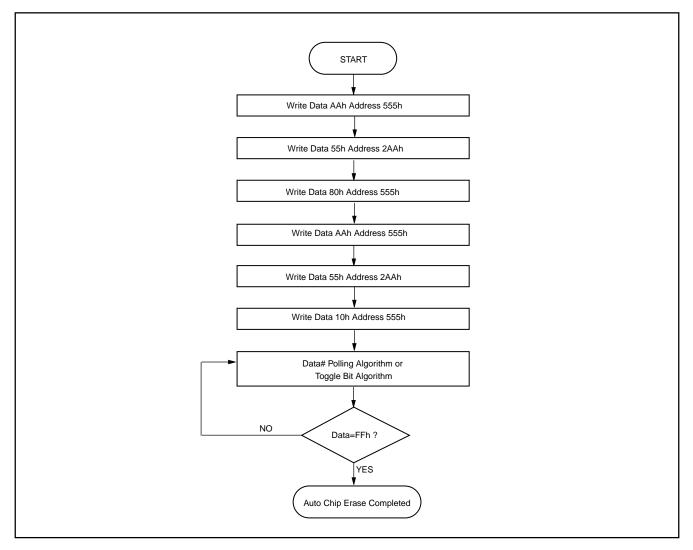
Figure 4. AUTOMATIC CHIP ERASE TIMING WAVEFORM





MX29LV161D T/B

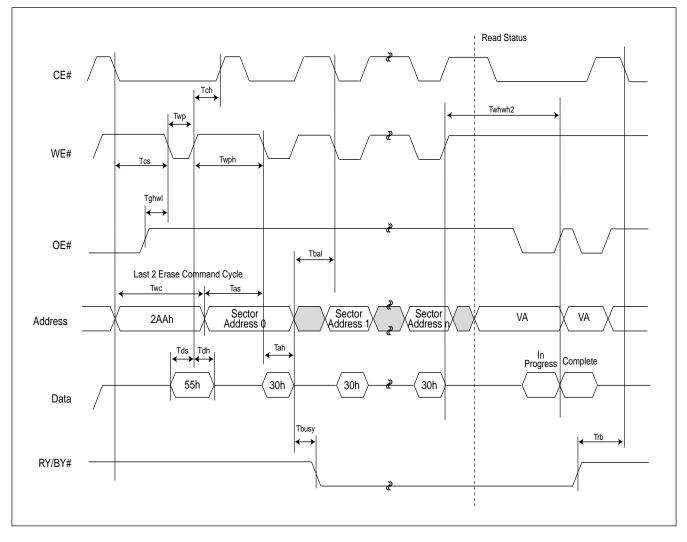
Figure 5. AUTOMATIC CHIP ERASE ALGORITHM FLOWCHART





MX29LV161D T/B

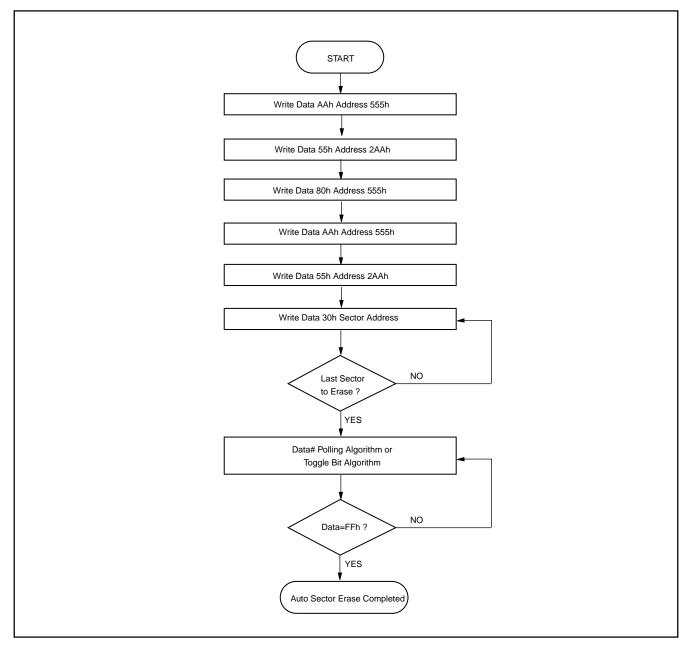
Figure 6. AUTOMATIC SECTOR ERASE TIMING WAVEFORM





MX29LV161D T/B

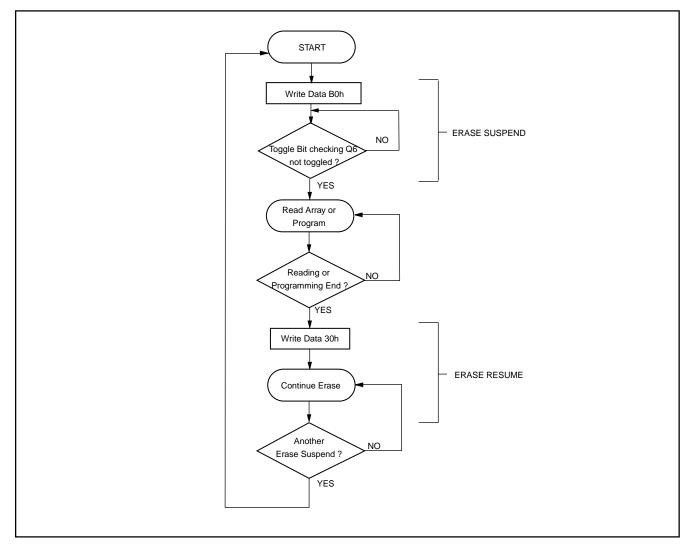
Figure 7. AUTOMATIC SECTOR ERASE ALGORITHM FLOWCHART





MX29LV161D T/B

Figure 8. ERASE SUSPEND/RESUME FLOWCHART





MX29LV161D T/B

Figure 9. AUTOMATIC PROGRAM TIMING WAVEFORM

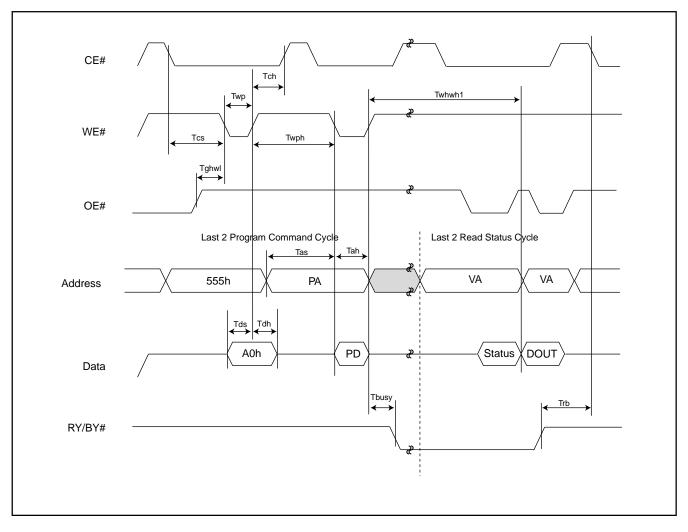
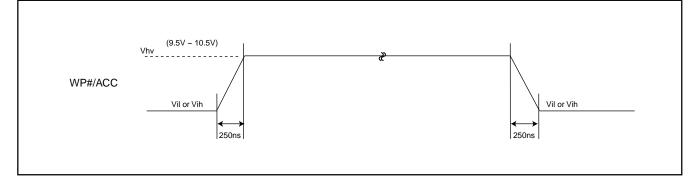


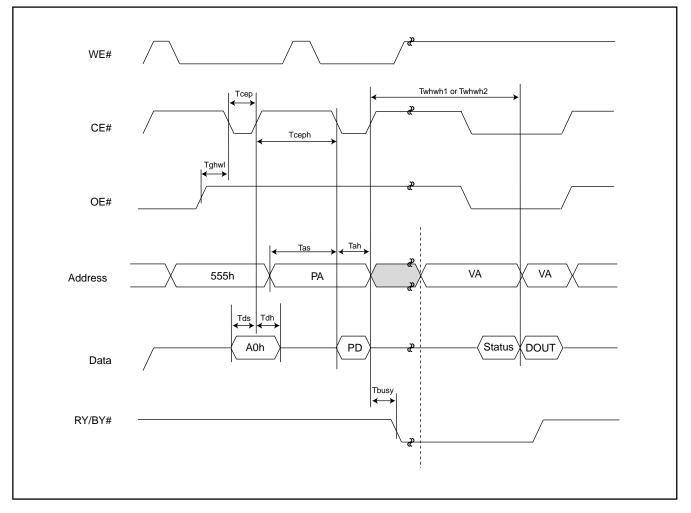
Figure 10. ACCELERATED PROGRAM TIMING DIAGRAM





MX29LV161D T/B

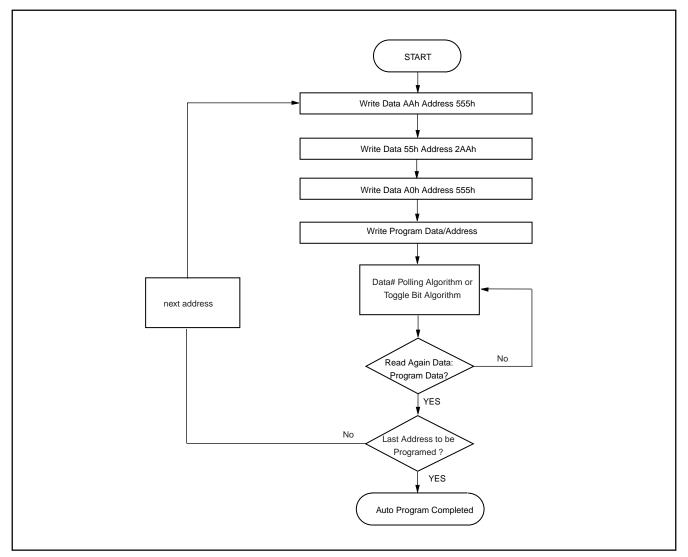
Figure 11. CE# CONTROLLED WRITE TIMING WAVEFORM





MX29LV161D T/B

Figure 12. AUTOMATIC PROGRAMMING ALGORITHM FLOWCHART

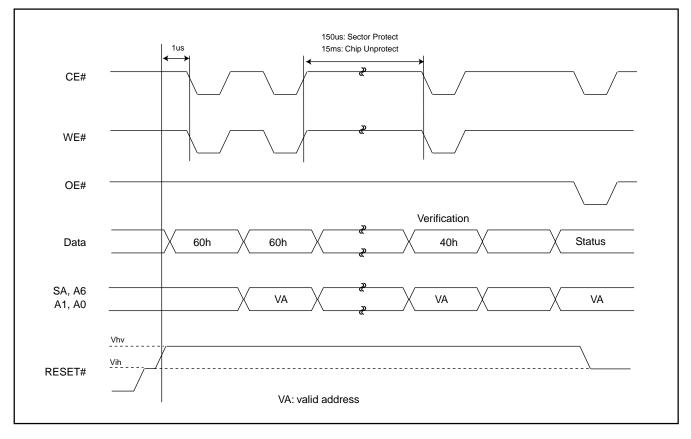




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SECTOR PROTECT/CHIP UNPROTECT

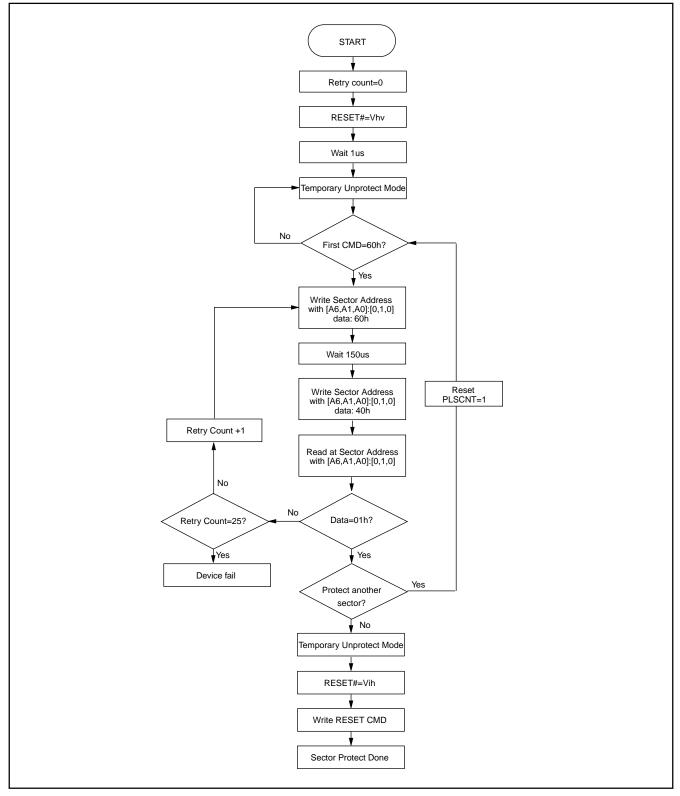
Figure 13. SECTOR PROTECT/CHIP UNPROTECT WAVEFORM (RESET# Control)





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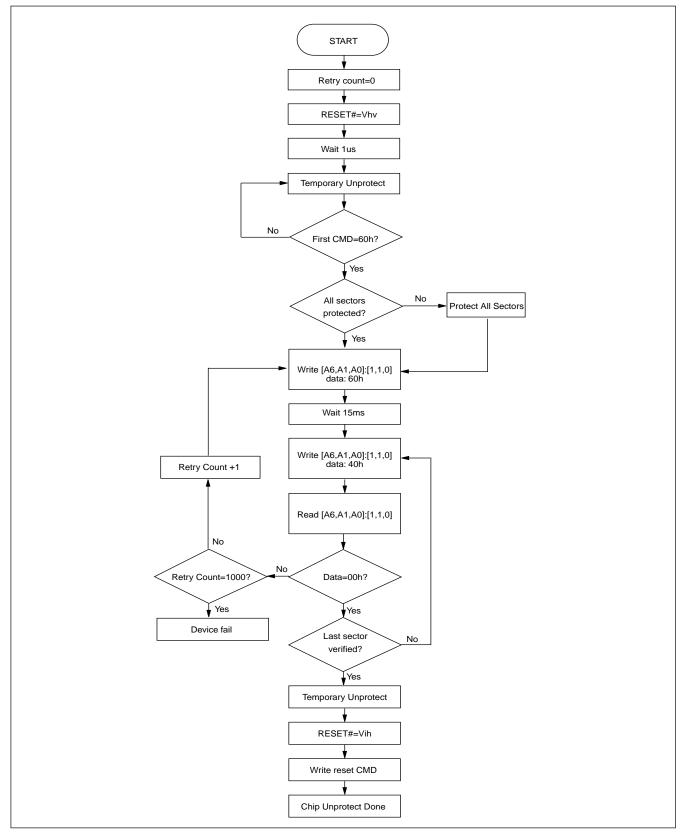
Figure 14. IN-SYSTEM SECTOR PROTECT WITH RESET#=Vhv





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Figure 15. CHIP UNPROTECT ALGORITHM WITH RESET#=Vhv



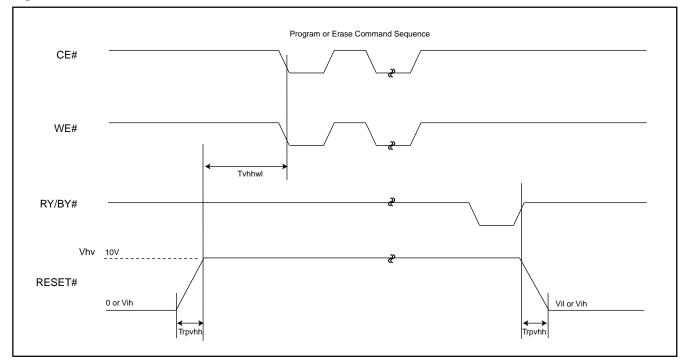


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Table 5. TEMPORARY SECTOR UNPROTECT

Parameter	Alt	Description	Condition	Speed	Unit
Trpvhh	Tvidr	RESET# Rise Time to Vhv and Vhv Fall Time to RESET#	MIN	500	ns
Tvhhwl	Trsp	RESET# Vhv to WE# Low	MIN	4	us

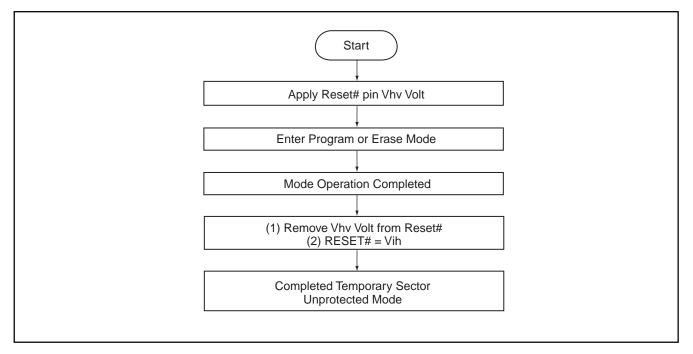
Figure 16. TEMPORARY SECTOR UNPROTECT WAVEFORM





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Figure 17. TEMPORARY SECTOR UNPROTECT FLOWCHART



Notes:

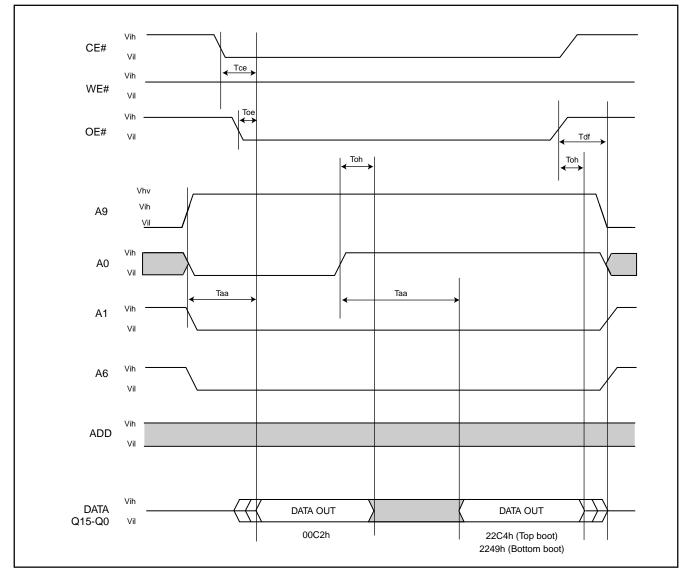
1. Temporary unprotect all protected sectors Vhv=9.5~10.5V.

2. After leaving temporary unprotect mode, the previously protected sectors are again protected.



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Figure 18. SILICON ID READ TIMING WAVEFORM

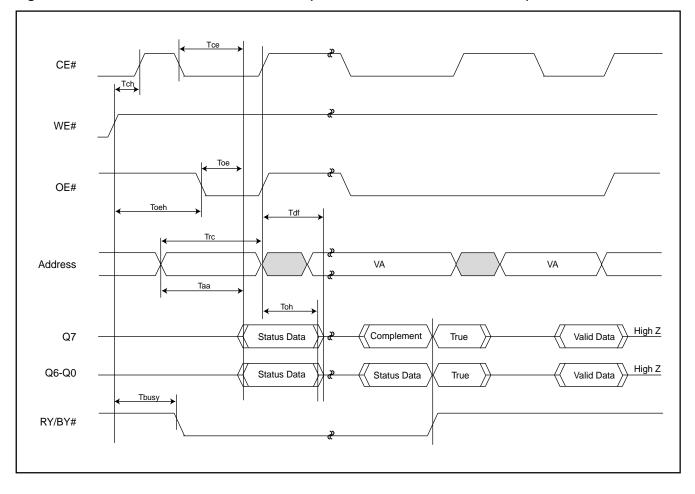




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WRITE OPERATION STATUS

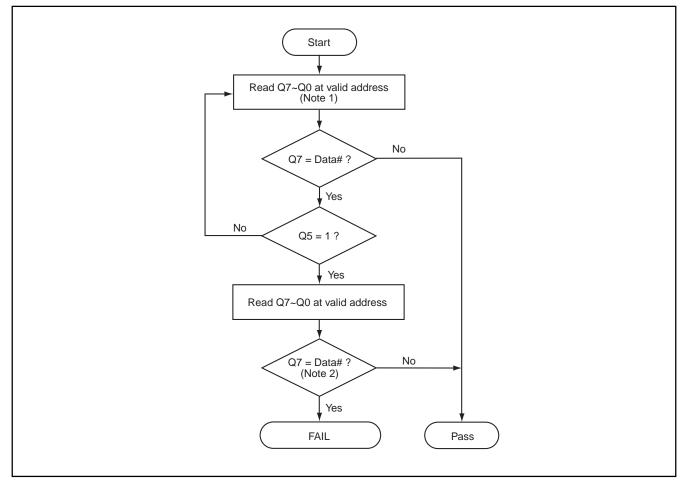
Figure 19. DATA# POLLING TIMING WAVEFORM (DURING AUTOMATIC ALGORITHM)





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Figure 20. DATA# POLLING ALGORITHM



Notes:

- 1. For programming, valid address means program address.
- For erasing, valid address means erase sectors address.
- 2. Q7 should be rechecked even Q5="1" because Q7 may change simultaneously with Q5.



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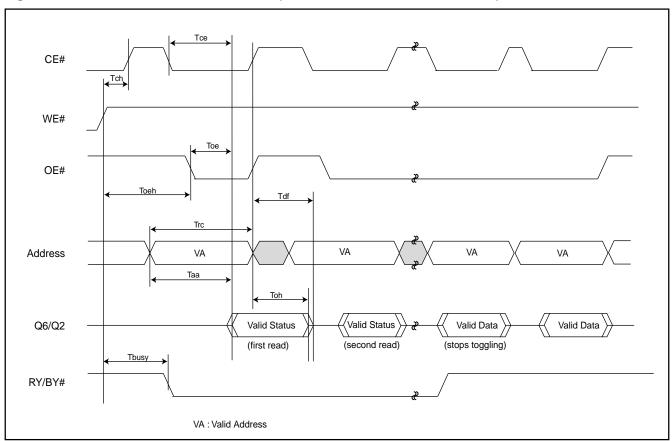
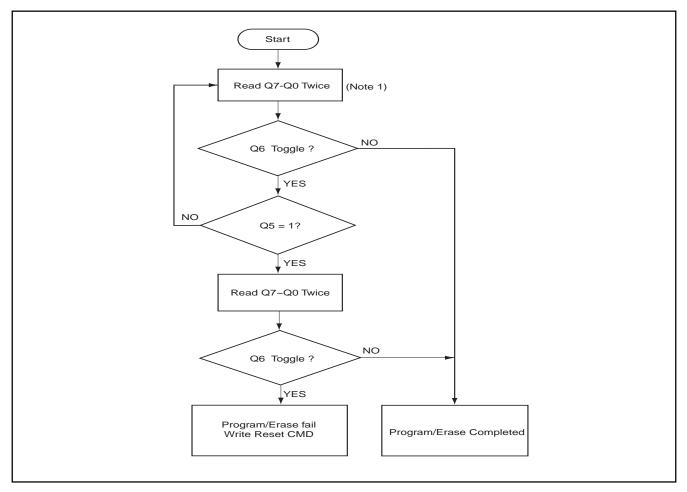


Figure 21.TOGGLE BIT TIMING WAVEFORM (DURING AUTOMATIC ALGORITHM)



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Figure 22. TOGGLE BIT ALGORITHM



Notes:

1. Read toggle bit twice to determine whether or not it is toggling.

2. Recheck toggle bit because it may stop toggling as Q5 changes to "1".



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RECOMMENDED OPERATING CONDITIONS

At Device Power-Up

AC timing illustrated in Figure A is recommended for the supply voltages and the control signals at device power-up. If the timing in the figure is ignored, the device may not operate correctly.

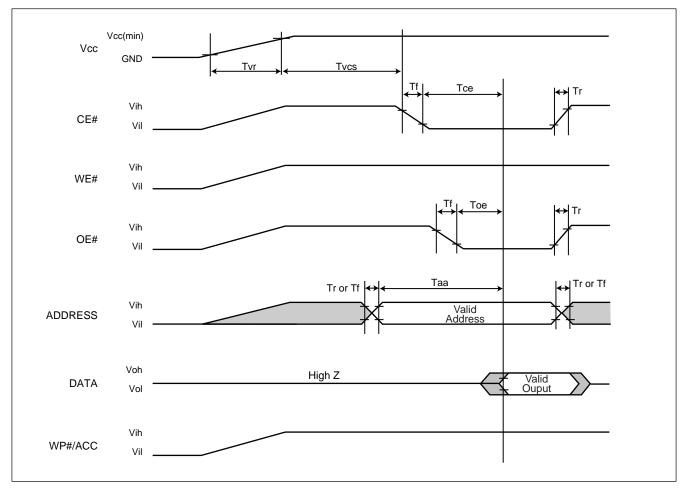


Figure A. ACTiming at Device Power-Up

Symbol	Parameter	Min.	Max.	Unit
Tvr	Vcc Rise Time	20	500000	us/V
Tr	Input Signal Rise Time		20	us/V
Tf	Input Signal Fall Time		20	us/V
Tvcs	Vcc Setup Time	200		us



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ERASE AND PROGRAMMING PERFORMANCE

		LIMITS					
PARAMETER	MIN.	TYP.	MAX.	UNITS			
Chip Erase Time		15	32	sec			
Sector Erase Time		0.7	2	sec			
Erase/Program Cycles		100,000		Cycles			
Word Program Time		11	360	us			
Accelerated Program Time		7	210	us			

Notes:

1. Erase/Program cycles comply with JEDEC JESD-47E & A117A standard.

LATCH-UP CHARACTERISTICS

	MIN.	MAX.					
Input voltage difference with GND on all pins except I/O pins	-1.0V	11.5V					
Input voltage difference with GND on all I/O pins	-1.0V	1.5 x Vcc					
Vcc Current	-100mA	+100mA					
All pins included except Vcc. Test conditions: Vcc = 3.0V, one pin per testing							

TSOP PIN CAPACITANCE

Parameter Symbol	Parameter Description	Test Set	TYP	MAX	UNIT
CIN2	Control Pin Capacitance	VIN=0	7.5	9	pF
COUT	Output Capacitance	VOUT=0	8.5	12	pF
CIN	Input Capacitance	VIN=0	6	7.5	pF



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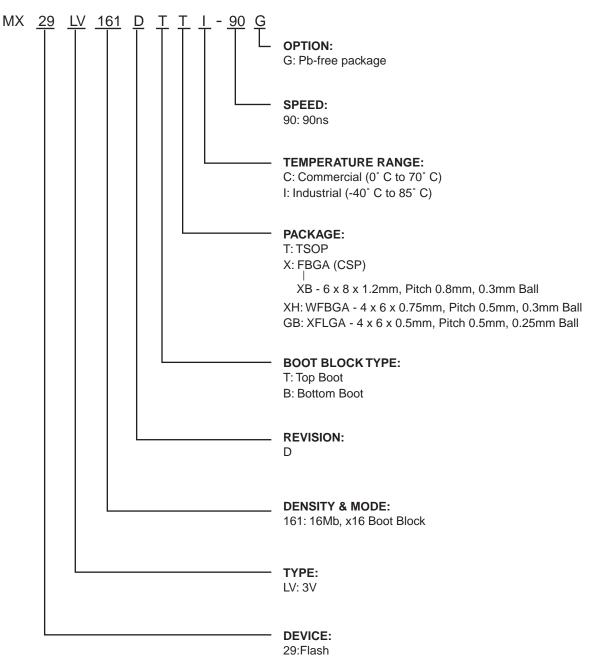
ORDERING INFORMATION

PART NO.	ACCESS	Ball Pitch/	PACKAGE	Remark
	TIME (ns)	Ball Size		
MX29LV161DTTI-90G	90		48 Pin TSOP	PB free
			(Normal Type)	
MX29LV161DBTI-90G	90		48 Pin TSOP	PB free
			(Normal Type)	
MX29LV161DTXBI-90G	90	0.8mm/0.3mm	48 Ball BGA	PB free
			(ball size:0.3mm)	
MX29LV161DBXBI-90G	90	0.8mm/0.3mm	48 Ball BGA	PB free
			(ball size:0.3mm)	
MX29LV161DTGBI-90G	90		48 Ball XFLGA	PB free
			(4 x 6 x 0.5mm)	
MX29LV161DBGBI-90G	90		48 Ball XFLGA	PB free
			(4 x 6 x 0.5mm)	
MX29LV161DTXHI-90G	90		48 Ball WFBGA	PB free
			(4 x 6 x 0.75mm)	
MX29LV161DBXHI-90G	90		48 Ball WFBGA	PB free
			(4 x 6 x 0.75mm)	



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PART NAME DESCRIPTION

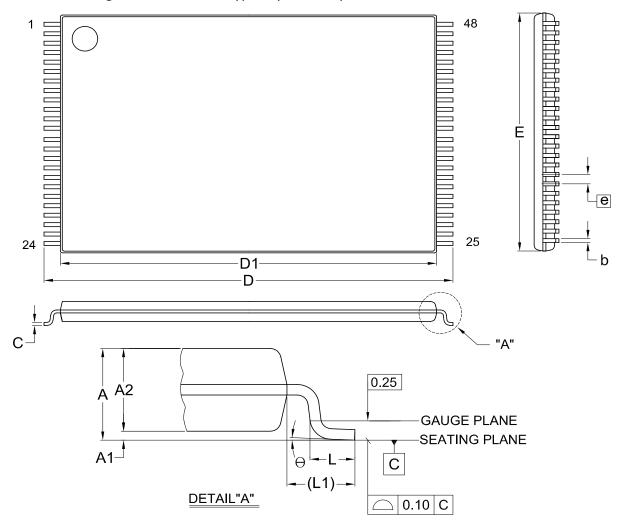




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PACKAGE INFORMATION

Title: Package Outline for TSOP(I) 48L (12X20mm)NORMAL FORM



Dimensions (inch dimensions are derived from the original mm dimensions)

SY	MBOL	_			-	_	_		_		_		-
		Α	A1	A2	b	С	D	D1	E	е	L	L1	Θ
	Min.	-	0.05	0.95	0.17	0.10	19.80	18.30	11.90		0.50	0.70	0
mm	Nom.		0.10	1.00	0.20	0.13	20.00	18.40	12.00	0.50	0.60	0.80	5
	Max.	1.20	0.15	1.05	0.27	0.21	20.20	18.50	12.10		0.70	0.90	8
	Min.		0.002	0.037	0.007	0.004	0.780	0.720	0.469	-	0.020	0.028	0
Inch	Nom.		0.004	0.039	0.008	0.005	0.787	0.724	0.472	0.020	0.024	0.031	5
	Max.	0.047	0.006	0.041	0.011	0.008	0.795	0.728	0.476		0.028	0.035	8

	DEVISION		REFERENCE	ISSUE DATE	
DWG.NO. REVISION		JEDEC	EIAJ		ISSUE DATE
6110-1607	8	MO-142			2007/08/03



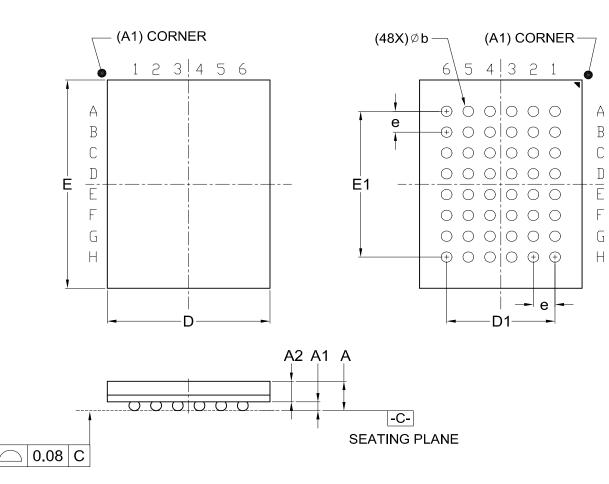
MX29LV161D T/B

48-BallTFBGA (for MX29LV161D TXBI/BXBI)

Title: Package Outline for CSP 48BALL(6X8X1.2MM,BALL PITCH 0.8MM,BALL DIAMETER 0.3MM)

TOP VIEW

BOTTOM VIEW



Dimensions (inch dimensions are derived from the original mm dimensions)

SY UNIT		Α	A1	A2	b	D	D1	Е	E1	е
	Min.		0.18	0.65	0.25	5.90		7.90		
mm	Nom.		0.23		0.30	6.00	4.00	8.00	5.60	0.80
	Max.	1.20	0.28		0.35	6.10		8.10		
	Min.		0.007	0.026	0.010	0.232		0.311		
Inch	Nom.		0.009		0.012	0.236	0 <u>.</u> 157	0.315	0.220	0.031
	Max.	0.047	0.011		0.014	0.240		0.319		

	BEVISION		REFERENCE	ISSUE DATE
DWG.NO.	DWG.NO. REVISION		EIAJ	ISSUE DATE
6110-4201	6	MO-210		03-29-'06

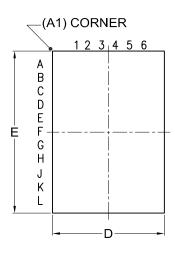


MX29LV161D T/B

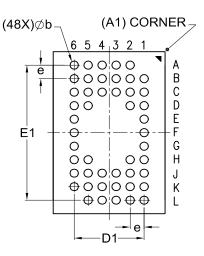
48-Ball WFBGA (for MX29LV161D TXHI/BXHI)

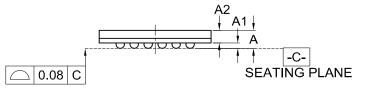
Title: Package Outline for CSP 48BALL(4X6X0.75MM,BALL PITCH 0.5MM,BALL DIAMETER 0.3MM)

TOP VIEW



BOTTOM VIEW





Dimensions (inch dimensions are derived from the original mm dimensions)

SY UNIT		Α	A1	A2	b	D	D1	E	E1	е
	Min.		0.16	0.41	0.25	3.90		5.90		
mm	Nom.		0.21		0.30	4.00	2.50	6.00	5.00	0.50
	Max.	0.75	0.26		0.35	4.10		6.10		
	Min.		0.006	0.016	0.010	0.154		0.232		
Inch	Nom.		0.008		0.012	0.157	0.098	0.236	0.197	0.020
	Max.	0.030	0.010	_	0.014	0.161		0.240		

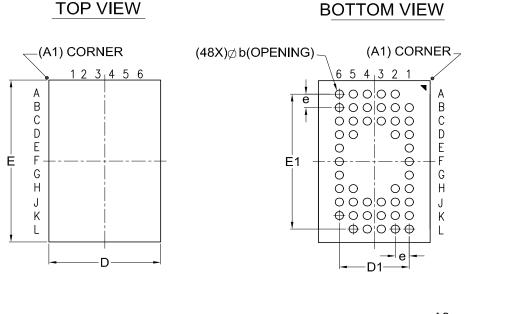
	BEVISION		REFERENCE	ISSUE DATE
DWG.NO.	DWG.NO. REVISION		EIAJ	1550E DATE
6110-4250	1			02-14-'06



MX29LV161D T/B

48-Ball XFLGA (for MX29LV161D TGBI/BGBI)

Title: Package Outline for XFLGA 48L (4x6x0.5MM,LAND PITCH 0.5MM,LAND OPENING 0.25MM)





Dimensions (inch dimensions are derived from the original mm dimensions)

SY UNIT		Α	A1	A2	b	D	D1	E	E1	е
mm	Min.		0.02	0.33	0.20	3.90	_	5.90	_	Ι
	Nom.		0.05		0.25	4.00	2.50	6.00	5.00	0.50
	Max.	0.50	0.08		0.30	4.10	_	6.10	_	_
	Min.		0.001	0.013	0.008	0.154	_	0.232	_	Ι
Inch	Nom.		0.002	_	0.010	0.157	0.098	0.236	0.197	0.020
	Max.	0.020	0.003	_	0.012	0.161	_	0.240	_	_

DWG.NO.	REVISION					
DWG.NO.	REVISION	JEDEC	EIAJ		ISSUE DATE	
6110-3501	0	MO-222			08-16-'06	



MX29LV161D T/B

REVISION HISTORY

	Description	Page	Date	
0.01	 Modified Pin Configurations 48-ball WFBGA/XFLGA from RY/BY# to NC 	P7	OCT/17/2007	
	2. Modified Output Load Capacitance, CL from 100pF to 30pF	P30		
	3. Added WP#/ACC function	P5,7,8,9,14		
		P17,30,32,4	.1	
		P55		
	Modified Output Load Capacitance, CL from 100pF to 30pF	P31		
0.02	1. Modified Tvcs from 100us to 200us	P54	OCT/23/2007	
0.03	1. Table 4-4. CFI added address 4D~4F	P28	NOV/29/2007	
0.04	1. Modified Tvcs from 100us to 200us	P32	DEC/07/2007	
0.05	1. Modified table 4-4. address 4D data from 00B5 to 00A5;	P28	DEC/18/2007	
	address 4E data from 00C5 to 00B5			
0.06	1. Swapped A19 with VI/O Ball Location	P8	JAN/15/2008	
0.07	 Modified WFBGA & XFLGA for WP#/ACC pin 	P8	JAN/29/2008	
0.08	1. Changed Toe spec from 30ns to 40ns	P32	JUN/16/2008	
	 Revised Vhv data from 10.5V~11.5V to 9.5V~10.5V 	P30,41,47,4	.8	
	3. Changed Vol/Voh spec	P30		
	 Modified switching test circuit 	P31		
	5. Changed output load capacitance, CL from 50pF to 30pF	P31		
0.09	1. Changed lcr1 from 7mA(typ.) to 5mA(typ.)	P5,30	JUL/29/2008	



MX29LV161D T/B

Macronix's products are not designed, manufactured, or intended for use for any high risk applications in which the failure of a single component could cause death, personal injury, severe physical damage, or other substantial harm to persons or property, such as life-support systems, high temperature automotive, medical, aircraft and military application. Macronix and its suppliers will not be liable to you and/or any third party for any claims, injuries or damages that may be incurred due to use of Macronix's products in the prohibited applications.

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