

# NM27LV210

## 1,048,576-Bit (64K x 16) Low Voltage EPROM

### General Description

The NM27LV210 is a high performance Low Voltage Electrical Programmable read only memory. It is manufactured using Fairchild's latest EPROM technology. This technology allows the part to operate at high speeds.

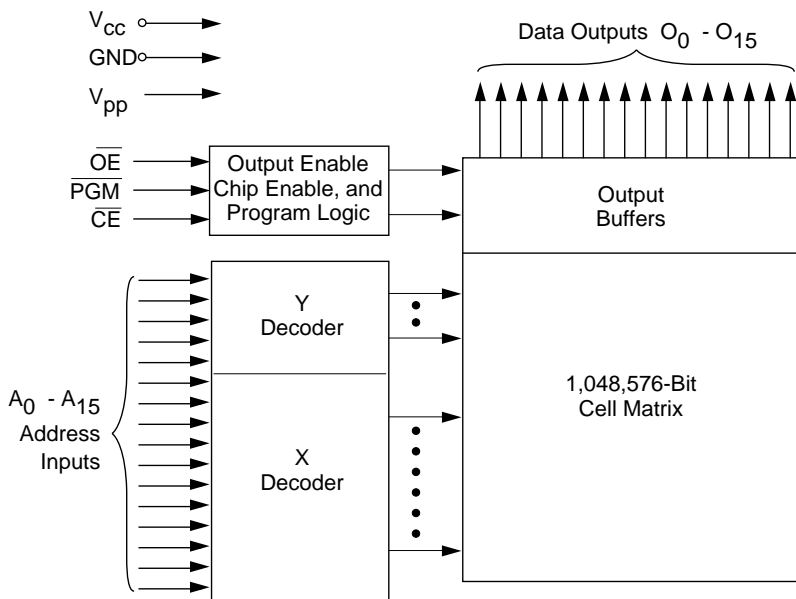
This Low Voltage and Low Power EPROM is designed with power sensitive hand held and portable battery products in mind. This allows for code storage of firmware for applications like notebook computers, palm top computers, cellular phones, and HDD.

The NM27LV210 is one member of Fairchild's growing Low Voltage product family.

### Features

- 3.0V to 3.6V operation
- 200 ns, 250 ns maximum access time
- Low current operation
  - 20mA  $I_{CC}$  active current @ 5 MHz
  - 50 $\mu$ A  $I_{CC}$  standby current @ 5 MHz
- Ultra low power operation
  - 60  $\mu$ A standby power @ 3.3V
  - 50 mW active power @ 3.3V
- Surface mount package option
  - 44-Pin PLCC

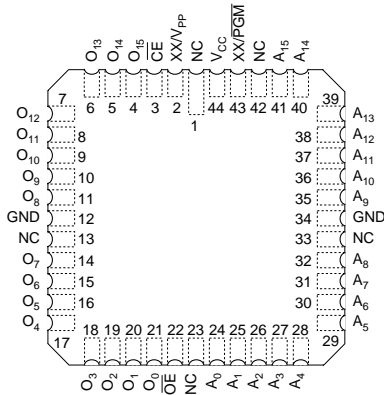
### Block Diagram



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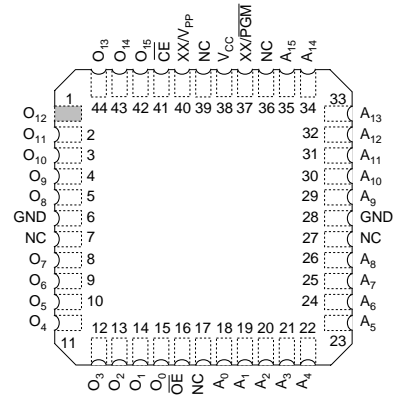
## Connection Diagrams

### PLCC Pin Configuration



Top View

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### Commercial Temperature Range

(0°C to +70°C)  $V_{CC} = 3.3V \pm 0.3$

Parameter/Order Number	Access Time (ns)
NM27LV210 V 200	200
NM27LV210 V 250	250

### Extended Temperature Range

(-40°C to +85°C)  $V_{CC} = 3.3V \pm 0.3$

Parameter/Order Number	Access Time (ns)
NM27LV210 VE 250	250

- All packages conform to JEDEC standard.
- All versions are guaranteed to function in slower applications.
- Consult the FSC representative for newly released products/packages.

### Pin Names

A0–A15	Addresses
$\overline{CE}$	Chip Enable
$\overline{OE}$	Output Enable
O0–O15	Outputs
$\overline{PGM}$	Program
XX	Don't Care (During Read)
NC	No Connect
$V_{PP}$	Programming Voltage

### Absolute Maximum Ratings (Note 2)

Storage Temperature	-65°C to +150°C
All Input Voltages except A9 with Respect to Ground (Note 12)	-0.6V to +7V
V <sub>PP</sub> and A9 with Respect to Ground	-0.6V to +14V
V <sub>CC</sub> Supply Voltage with Respect to Ground	-0.6V to +7V
ESD Protection	>2000V

All Output Voltages with Respect to Ground (Note 11) V<sub>CC</sub> + 1.0V to GND - 0.6V

### Operating Range

Range	Temperature	V <sub>CC</sub>	Tolerance
Commercial	0°C to +70°C	3.3	±0.3
Extended	-40°C to +85°C	3.3	±0.3

### DC Read Characteristics Over Operating Range with V<sub>PP</sub> = V<sub>CC</sub>

Symbol	Parameter	Test Conditions	Min	Max	Units
V <sub>IL</sub>	Input Low Level		-0.3	0.7	V
V <sub>IH</sub>	Input High Level		2.0	V <sub>CC</sub> + 0.3	V
V <sub>OL1</sub>	Output Low Voltage (TTL)			0.4	V
V <sub>OH1</sub>	Output High Voltage (TTL)		2.4		V
V <sub>OL2</sub>	Output Low Voltage (CMOS)			0.2	V
V <sub>OH2</sub>	Output High Voltage (CMOS)		V <sub>CC</sub> - 0.3		V
I <sub>SB1</sub>	V <sub>CC</sub> Standby Current (TTL)	CE = V <sub>IH</sub>		150	μA
I <sub>SB2</sub>	V <sub>CC</sub> Standby Current (CMOS)	CE = V <sub>CC</sub> ±0.3V		50	μA
I <sub>CC</sub>	V <sub>CC</sub> Active Current	CE = OE = V <sub>IL</sub> , I/O = 0 μA	f = 5 MHz	20	mA
I <sub>PP</sub>	V <sub>PP</sub> Supply Current	V <sub>PP</sub> = V <sub>CC</sub>		10	μA
I <sub>LI</sub>	Input Load Current	V <sub>IN</sub> = 3.3 or GND	-1	1	μA
I <sub>LO</sub>	Output Leakage Current	V <sub>OUT</sub> = 3.3V or GND	-1	10	μA

### AC Read Characteristics Over Operating Range with V<sub>PP</sub> = V<sub>CC</sub>

Symbol	Parameter	200		250		Units
		Min	Max	Min	Max	
t <sub>ACC</sub>	Address to Output Delay		200		250	
t <sub>CE</sub>	$\overline{CE}$ to Output Delay		200		250	
t <sub>OE</sub>	$\overline{OE}$ to Output Delay		70		75	
t <sub>DF</sub> (Note 3)	Output Disable to Output Float	0	50	0	60	ns
t <sub>OH</sub> (Note 3)	Output Hold from Addresses, $\overline{CE}$ or $\overline{OE}$ , Whichever Occurred First	0		0		

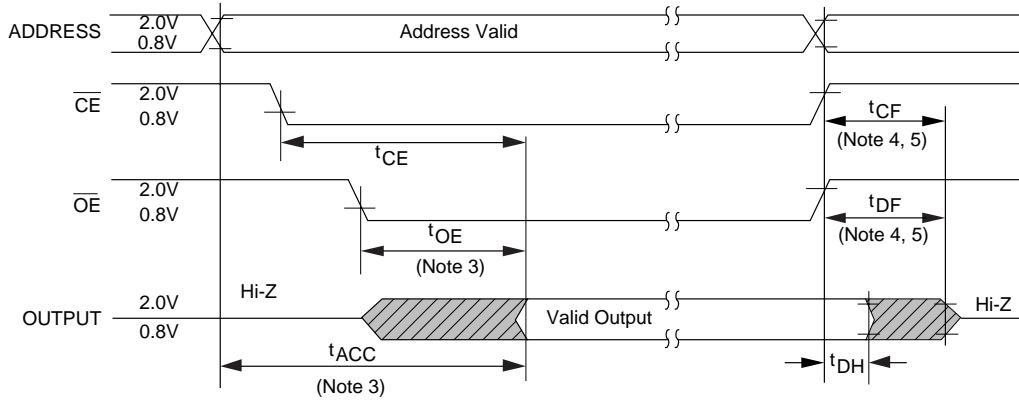
### Capacitance (Note 3) T<sub>A</sub> = +25°C, f = 1 MHz

Symbol	Parameter	Conditions	Typ	Max	Units
C <sub>IN</sub>	Input Capacitance	V <sub>IN</sub> = 0V	12	20	pF
C <sub>OUT</sub>	Output Capacitance	V <sub>OUT</sub> = 0V	13	20	pF

## AC Test Conditions

Output Load	1 TTL Gate and $C_L = 100$ pF (Note 9)
Input Rise and Fall Times	$\leq 5$ ns
Input Pulse Levels	0.45V to 2.4V
Timing Measurement Reference Level	
Inputs	0.8V and 2V
Outputs	0.8V and 2V

## AC Waveforms (Note 7) (Note 8) (Note 10)



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**Note 2:** Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Note 3:** This parameter is only sampled and is not 100% tested.

**Note 4:**  $\overline{OE}$  may be delayed up to  $t_{ACC} - t_{OE}$  after the falling edge of  $\overline{CE}$  without impacting  $t_{ACC}$ .

**Note 5:** The  $t_{DF}$  and  $t_{CF}$  compare level is determined as follows:  
High to TRI-STATE™, the measured  $V_{OH1}$  (DC) - 0.10V;  
Low to TRI-STATE, the measured  $V_{OL1}$  (DC) + 0.10V.

**Note 6:** TRI-STATE may be attained using  $\overline{OE}$  or  $\overline{CE}$ .

**Note 7:** The power switching characteristics of EPROMs require careful device decoupling. It is recommended that at least a 0.1  $\mu$ F ceramic capacitor be used on every device between  $V_{CC}$  and GND.

**Note 8:** The outputs must be restricted to  $V_{CC} + 1.0$ V to avoid latch-up and device damage.

**Note 9:** 1 TTL Gate:  $I_{OL} = 1.6$  mA,  $I_{OH} = -400$   $\mu$ A.  
 $C_L$ : 100 pF includes fixture capacitance.

**Note 10:**  $V_{PP}$  may be connected to  $V_{CC}$  except during programming.

**Note 11:** Inputs and outputs can undershoot to -2.0V for 20 ns Max.

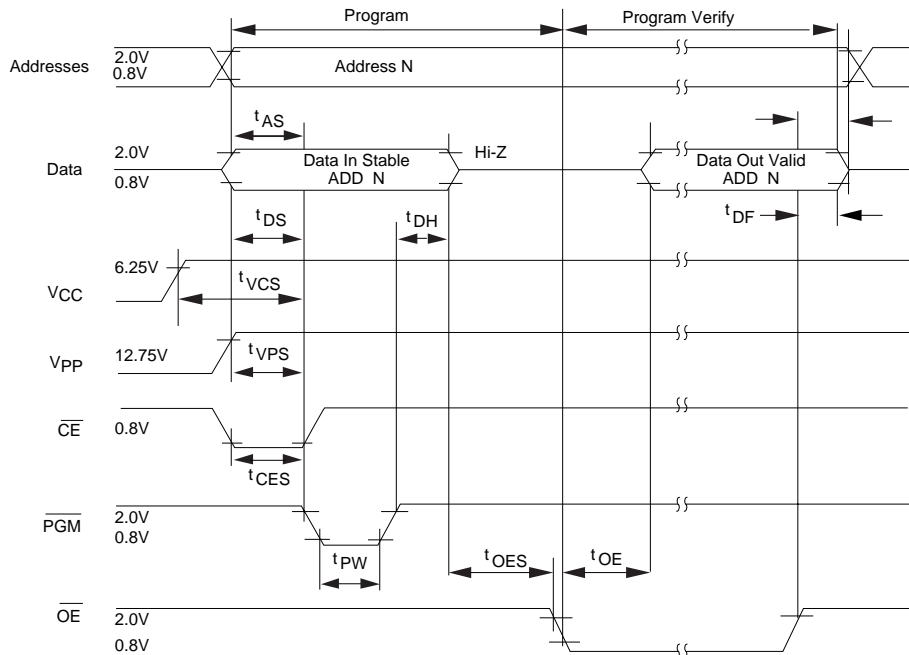
## Programming Characteristics (Note 12) (Note 13) (Note 14) (Note 15)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{AS}$	Address Setup Time		1			$\mu$ s
$t_{OES}$	$\overline{OE}$ Setup Time		1			$\mu$ s
$t_{CES}$	$\overline{CE}$ Setup Time	$\overline{OE} = V_{IH}$	1			$\mu$ s
$t_{DS}$	Data Setup Time		1			$\mu$ s
$t_{VPS}$	$V_{PP}$ Setup Time		1			$\mu$ s
$t_{VCS}$	$V_{CC}$ Setup Time		1			$\mu$ s
$t_{AH}$	Address Hold Time		0			$\mu$ s
$t_{DH}$	Data Hold Time		1			$\mu$ s
$t_{DF}$	Output Enable to Output Float Delay	$\overline{CE} = V_{IL}$	0		60	ns

### Programming Characteristics (Note 12) (Note 13) (Note 14) (Note 15) (Continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{PW}$	Program Pulse Width		45	50	105	$\mu$ s
$t_{OE}$	Data Valid from $\overline{OE}$	$\overline{CE} = V_{IL}$			100	ns
$I_{PP}$	$V_{PP}$ Supply Current during Programming Pulse	$\overline{CE} = V_{IL}$ $PGM = V_{IL}$			40	mA
$I_{CC}$	$V_{CC}$ Supply Current				50	mA
$T_A$	Temperature Ambient		20	25	30	$^{\circ}$ C
$V_{CC}$	Power Supply Voltage		6.25	6.5	6.75	V
$V_{PP}$	Programming Supply Voltage		12.5	12.75	13.0	V
$t_{FR}$	Input Rise, Fall Time		5			ns
$V_{IL}$	Input Low Voltage			0.0	0.45	V
$V_{IH}$	Input High Voltage		2.4	4.0		V
$t_{IN}$	Input Timing Reference Voltage		0.8		2.0	V
$t_{OUT}$	Output Timing Reference Voltage		0.8		2.0	V

### Programming Waveforms (Note 14)



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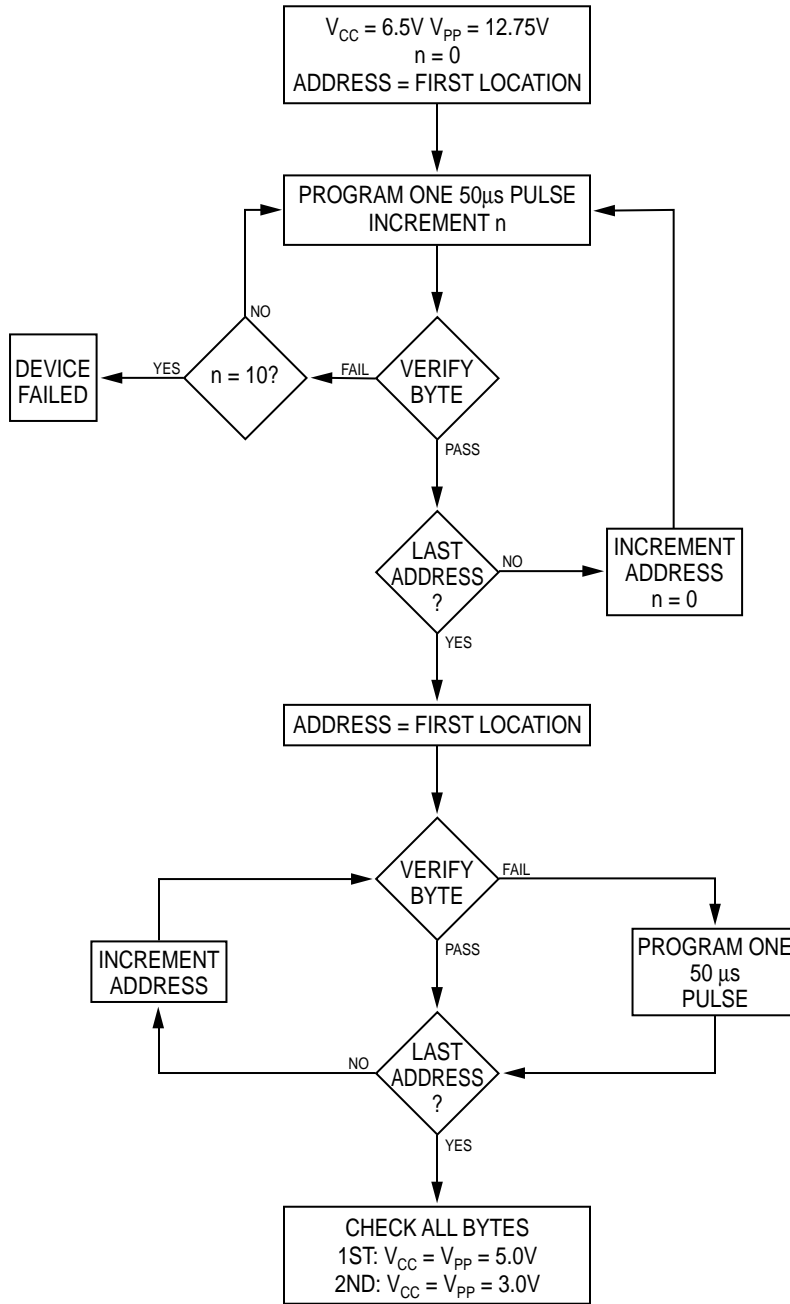
**Note 12:** Fairchild's standard product warranty applies only to devices programmed to specifications described herein.

**Note 13:**  $V_{CC}$  must be applied simultaneously or before  $V_{PP}$  and removed simultaneously or after  $V_{PP}$ . The EPROM must not be inserted into or removed from a board with voltage applied to  $V_{PP}$  or  $V_{CC}$ .

**Note 14:** The maximum absolute allowable voltage which may be applied to the  $V_{PP}$  pin during programming is 14V. Care must be taken when switching the  $V_{PP}$  supply to prevent any overshoot from exceeding this 14V maximum specification. At least a 0.1  $\mu$ F capacitor is required across  $V_{PP}$ ,  $V_{CC}$  to GND to suppress spurious voltage transients which may damage the device.

**Note 15:** During power up the  $\overline{PGM}$  pin must be brought high ( $\geq V_{IH}$ ) either coincident with or before power is applied to  $V_{PP}$ .

### Turbo LV Programming Algorithm Flow Chart



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**Note:** The standard National Semiconductor algorithm may also be used but it will have longer programming time.

**FIGURE 1.**

## Functional Description

### DEVICE OPERATION

The six modes of operation of the EPROM are listed in . It should be noted that all inputs for the six modes are at TTL levels. The power supplies required are  $V_{CC}$  and  $V_{PP}$ . The  $V_{PP}$  power supply must be at 12.75V during the three programming modes, and must be at 3.3V in the other three modes. The  $V_{CC}$  power supply must be at 6.5V during the three programming modes, and at 3.3V in the other three modes.

### Read Mode

The EPROM has two control functions, both of which must be logically active in order to obtain data at the outputs. Chip Enable ( $\overline{CE}$ ) is the power control and should be used for device selection. Output Enable ( $\overline{OE}$ ) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that the addresses are stable, address access time ( $t_{ACC}$ ) is equal to the delay from  $\overline{CE}$  to output ( $t_{CE}$ ). Data is available at the outputs  $t_{OE}$  after the falling edge of  $\overline{OE}$ , assuming that  $\overline{CE}$  has been low and addresses have been stable for at least  $t_{ACC} - t_{OE}$ .

### Standby Mode

The EPROM has a standby mode which reduces the active power dissipation by over 99%, from 66 mW to 66  $\mu$ W. The EPROM is placed in the standby mode by applying a CMOS high signal to the  $\overline{CE}$  input. When in standby mode, the outputs are in a high impedance state, independent of the  $\overline{OE}$  input.

### Output Disable

The EPROM is placed in output disable by applying a TTL high signal to the  $\overline{OE}$  input. When in output disable all circuitry is enabled, except the outputs are in a high impedance state (TRI-STATE).

### Output OR-Tying

Because the EPROM is usually used in larger memory arrays, Fairchild has provided a 2-line control function that accommodates this use of multiple memory connections. The 2-line control function allows for:

1. the lowest possible memory power dissipation, and
2. complete assurance that output bus contention will not occur.

To most efficiently use these two control lines, it is recommended that  $\overline{CE}$  be decoded and used as the primary device selecting function, while  $\overline{OE}$  be made a common connection to all devices in the array and connected to the READ line from the system control bus. This assures that all deselected memory devices are in their low power standby modes and that the output pins are active only when data is desired from a particular memory device.

## Programming

CAUTION: Exceeding 14V on the  $V_{PP}$  or A9 pin will damage the EPROM.

Initially, and after each erasure, all bits of the EPROM are in the "1's" state. Data is introduced by selectively programming "0's" into the desired bit locations. Although only "0's" will be programmed, both "1's" and "0's" can be presented in the data word. The only way to change a "0" to a "1" is by ultraviolet light erasure.

The EPROM is in the programming mode when the  $V_{PP}$  power supply is at 12.75V and  $\overline{OE}$  is at  $V_{IH}$ . It is required that at least a 0.1  $\mu$ F capacitor be placed across  $V_{PP}$ ,  $V_{CC}$  to ground to suppress spurious voltage transients which may damage the device. The data to be programmed is applied 16 bits in parallel to the data output pins. The levels required for the address and data inputs are TTL.

When the address and data are stable, an active low, TTL program pulse is applied to the  $\overline{PGM}$  input. A program pulse must be applied at each address location to be programmed. The EPROM is programmed with the Turbo Programming Algorithm shown in Figure 1. Each Address is programmed with a series of 50  $\mu$ s pulses until it verifies good, up to a maximum of 10 pulses. Most memory cells will program with a single 50  $\mu$ s pulse. (The standard National Semiconductor Algorithm may also be used but it will have longer programming time.)

The EPROM must not be programmed with a DC signal applied to the  $\overline{PGM}$  input.

Programming multiple EPROM in parallel with the same data can be easily accomplished due to the simplicity of the programming requirements. Like inputs of the parallel EPROM may be connected together when they are programmed with the same data. A low level TTL pulse applied to the  $\overline{PGM}$  input programs the paralleled EPROM.

## Functional Description (Continued)

### MODE SELECTION

The modes of operation of the NM27LV210 are listed in Table 1. A single power supply is required in the read mode. All inputs are TTL levels except for  $V_{PP}$  and A9 for device signature.

**TABLE 1. Modes Selection**

Pins	$\overline{CE}$	$\overline{OE}$	$\overline{PGM}$	$V_{PP}$	$V_{CC}$	Outputs
<b>Mode</b>						
Read	$V_{IL}$	$V_{IL}$	X (Note 16)	X	3.3V	$D_{OUT}$
Output Disable	X	$V_{IH}$	X	X	3.3V	High Z
Standby	$V_{IH}$	X	X	X	3.3V	High Z
Programming	$V_{IL}$	$V_{IH}$	$V_{IL}$	12.75V	6.25V	$D_{IN}$
Program Verify	$V_{IL}$	$V_{IL}$	$V_{IH}$	12.75V	6.25V	$D_{OUT}$
Program Inhibit	$V_{IH}$	X	X	12.75V	6.25V	High Z

**Note 16:** X can be  $V_{IL}$  or  $V_{IH}$ .

### Program Inhibit

Programming multiple EPROM's in parallel with different data is also easily accomplished. Except for  $\overline{CE}$  all like inputs (including  $\overline{OE}$  and  $\overline{PGM}$ ) of the parallel EPROM may be common. A TTL low level program pulse applied to an EPROM's  $\overline{PGM}$  input with  $\overline{CE}$  at  $V_{IL}$  and  $V_{PP}$  at 12.75V will program that EPROM. A TTL high level  $\overline{CE}$  input inhibits the other EPROM's from being programmed.

### Program Verify

A verify should be performed on the programmed bits to determine whether they were correctly programmed. The verify may be performed with  $V_{PP}$  at 6.25V.  $V_{PP}$  must be at  $V_{CC}$ , except during programming and program verify.

### MANUFACTURER'S IDENTIFICATION CODE

The EPROM has a manufacturer's identification code to aid in programming. When the device is inserted in an EPROM programmer socket, the programmer reads the code and then automatically calls up the specific programming algorithm for the part. This automatic programming control is only possible with programmers which have the capability of reading the code.

The Manufacturer's Identification code, shown in Table 2, specifically identifies the manufacturer and device type. The code for the NM27LV210 is "8FD6", where "8F" designates that it is made by Fairchild Semiconductor, and "D6" designates a 1 Megabit (64K x 16) part.

The code is accessed by applying 12V  $\pm$ 0.5V to address pin A9. Addresses A1 –A8, A10 –A15, and all control pins are held at  $V_{IL}$ . Address pin A0 is held at  $V_{IL}$  for the manufacturer's code, and held at  $V_{IH}$  for the device code. The code is read on the lower eight data pins, O0 –O7. Proper code access is only guaranteed at 25°C  $\pm$  5°C.

### SYSTEM CONSIDERATION

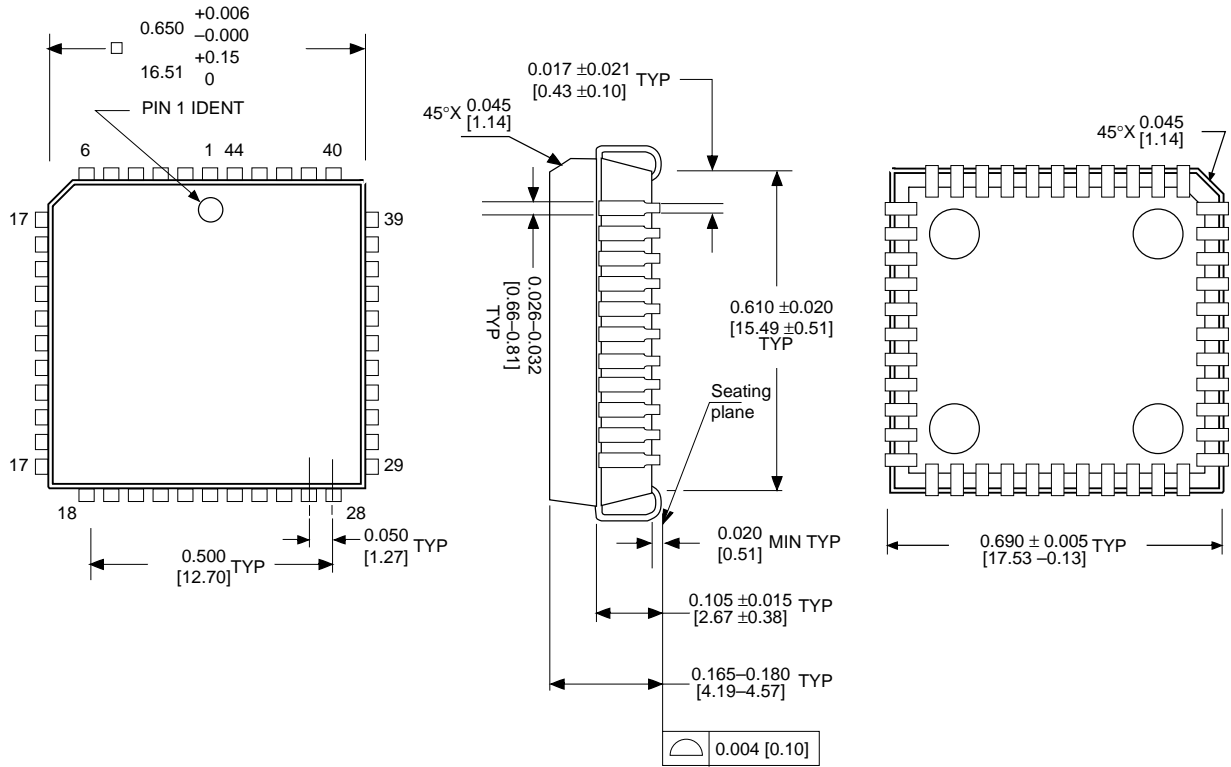
The power switching characteristics of EPROMs require careful decoupling of the devices. The supply current,  $I_{CC}$ , has three segments that are of interest to the system designer: the standby current level, the active current level, and the transient current peaks that are produced by voltage transitions on input pins. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. The associated  $V_{CC}$  transient voltage peaks can be suppressed by properly selected decoupling capacitors. It is recommended that at least a 0.1  $\mu$ F ceramic capacitor be used on every device between  $V_{CC}$  and GND. This should be a high frequency capacitor of low inherent inductance. In addition, at least a 4.7  $\mu$ F bulk electrolytic capacitor should be used between  $V_{CC}$  and GND for each eight devices. The bulk capacitor should be located near where the power supply is connected to the array. The purpose of the bulk capacitor is to overcome the voltage drop caused by the inductive effects of the PC board traces.

**TABLE 2. Manufacturer's Identification Code**

Pins	A0 (21)	A9 (31)	O7 (12)	O6 (13)	O5 (14)	O4 (15)	O3 (16)	O2 (17)	O1 (18)	O0 (19)	Hex Data
Manufacturer Code	$V_{IL}$	12V	1	0	0	0	1	1	1	1	8F
Device Code	$V_{IH}$	12V	1	1	0	1	0	1	1	0	D6



**Physical Dimensions** inches (millimeters) unless otherwise noted



**44-Lead Plastic Chip Carrier (V)  
 Order Number NM27LV210XXX  
 Package Number V44A**

**Life Support Policy**

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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