

# PAT9130EW-TKMT: Optical Tracking Miniature Chip

## General Description

The PAT9130EW-TKMT is a high performance and high tracking speed optical tracking miniature chip using PixArt LASER-based optical navigation technology enabling surface tracking without an optical lens. It integrates an optical chip with a LASER light source in a single miniature package, providing wide depth of field (DOF) range, and design flexibility into highly space constraint devices. This tracking system also does not require a code wheel, a code strip and any special marking on the tracking surface for motion control or tracking purposes. Since the chip's tracking performance is susceptible to the contamination on the optical sensing area, it is recommended for use in hermetic or enclosed mechanical system design and applications.

## Key Features

- Reflowable SMT package with built-in VCSEL LASER light source in a single package
- No lens is needed to work with the chip
- Wide DOF range on glossy metal surfaces
- High accuracy of tracking on glossy metal surfaces
- Tracking speed is up to 90 ips on glossy metal surfaces
- Support 3-wire SPI interface
- Programmable resolution up to 6,700 cpi with 50 counts/step
- Motion detection interrupt output
- Internal oscillator – no external clock input needed

## Applications

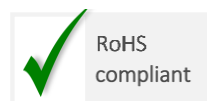
- Devices that requires tracking on surfaces with wide DOF working range
- Devices that requires detecting the speed of fast moving surfaces
- Suitable for space-constraint devices

## Key Parameters

Parameter	Value
Supply Voltage	VDD : 2.7 ~ 3.6V
	VDDA : 1.93V +/-0.05V (+/-2.5% voltage variation)
Control Interface	3-wire SPI
Max .Tracking Speed	Up to 90 ips on glossy metal surface Up to 35 ips on white copy paper
Max Resolution	Up to ~6,700 cpi
Operating current (@ VDD=3.3V and VDDA=1.9V)	Run : I <sub>VDD</sub> = 0.5 mA, I <sub>VDDA</sub> = 15 mA Power down : I <sub>VDD</sub> = 2 μA, I <sub>VDDA</sub> = 18 μA
Distance from chip top to tracking surface	5 ~ 60 mm on glossy metal surfaces 20 ~ 40mm on white copy paper
Light Source	VCSEL LASER 850 nm
Package Size L x W x H	4.4 x 4.6 x 1.0 mm

## Ordering Information

Part Number	Package Type
PAT9130EW-TKMT	LGA 10-pin



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## 1.0 Introduction

### 1.1 Overview

PAT9130EW-TKMT is a high performance CMOS-processed optical image chip with integrated digital image process circuits. It is based on PixArt LASER-based optical navigation technology which measures changes in position by optically acquiring sequential surface images (frames) and mathematically determining the speed, the direction and the magnitude of motion. The displacement X and Y information are available in registers. A host controller can read and translate the displacement X and Y information from the SPI serial interface.

**Note:** Throughout this document PAT9130EW-TKMT is referred to as the chip.

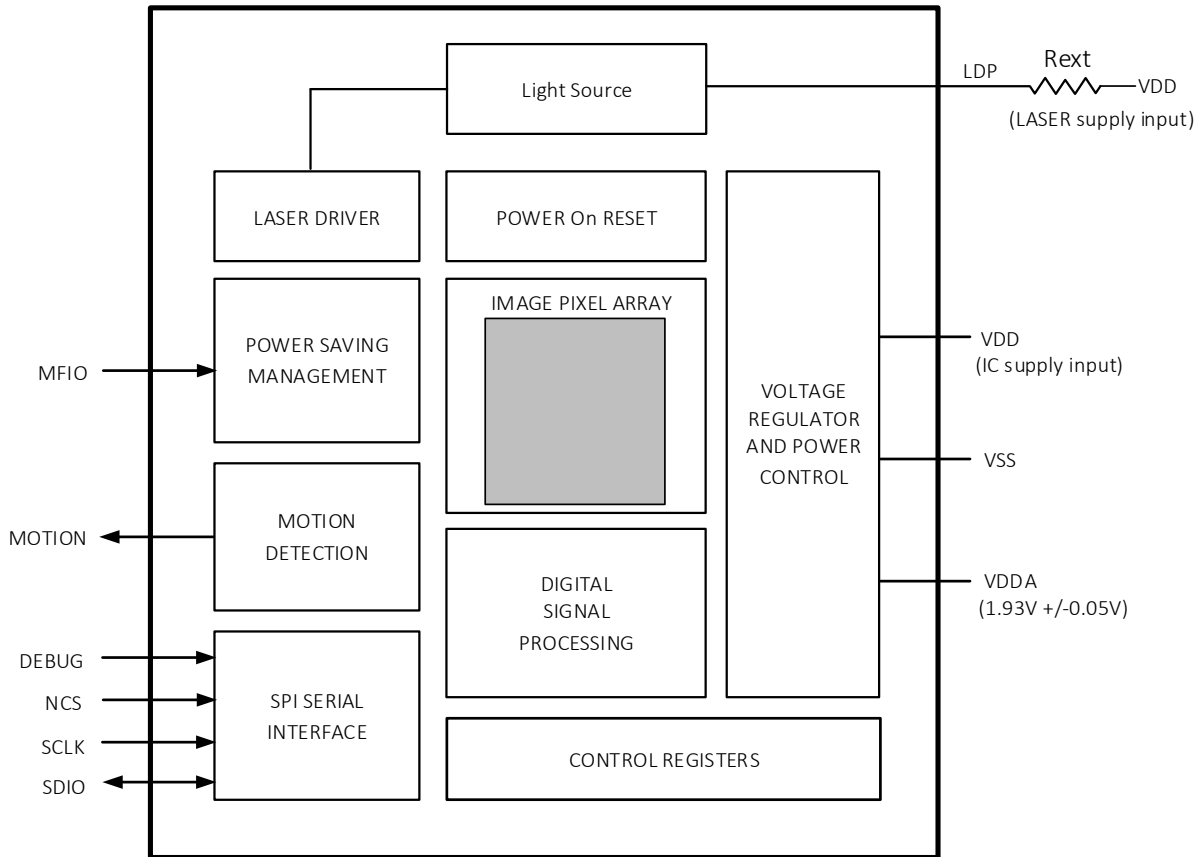


Figure 1. Chip Architecture Functional Block Diagram

1.2 Signal Description

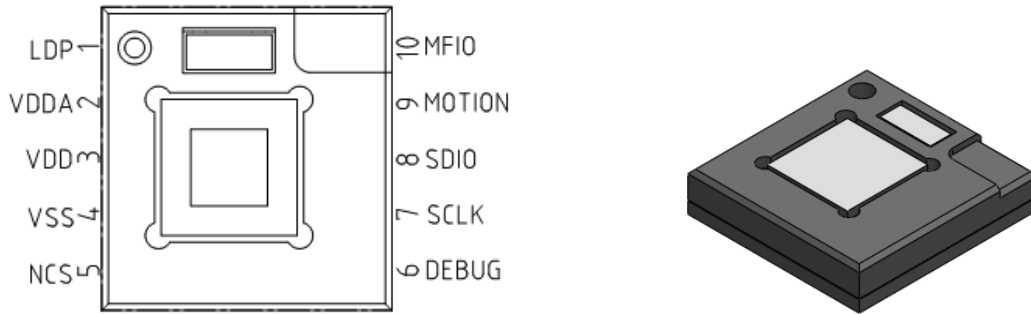


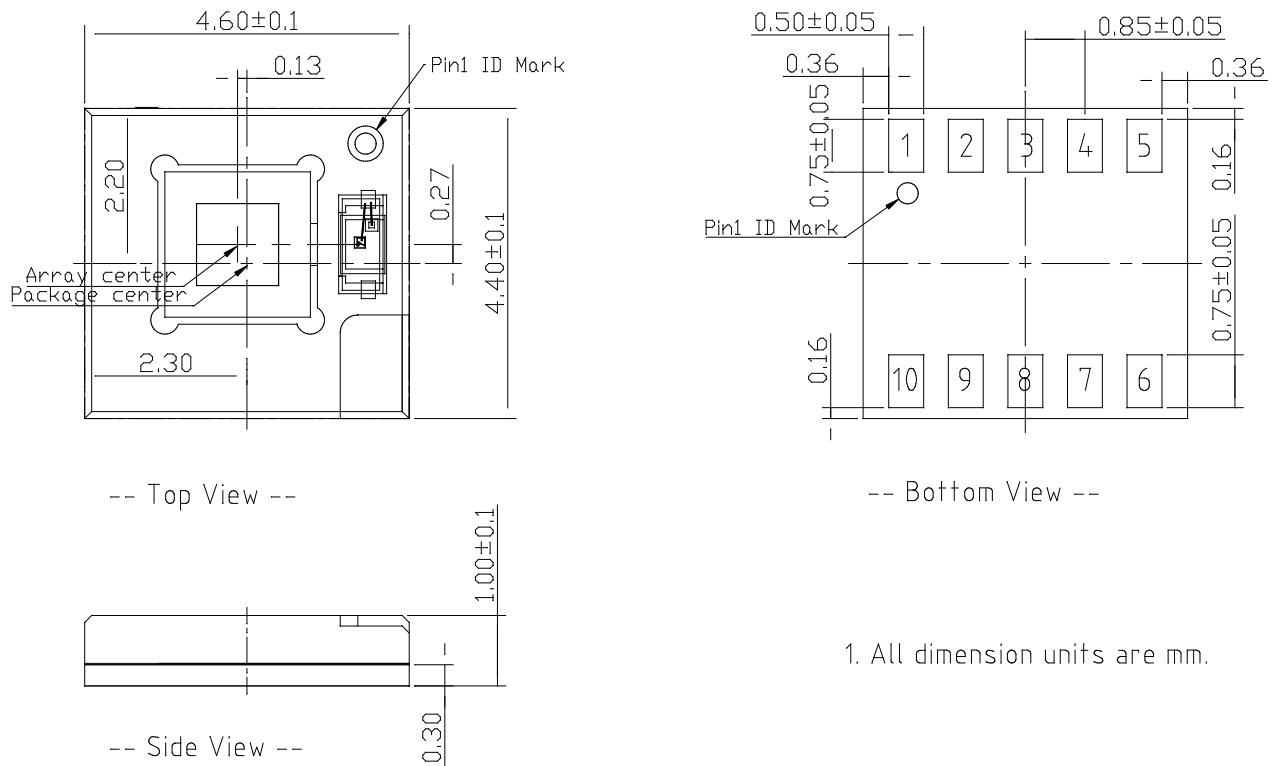
Figure 2. Pinout Configuration

Table 1. Signal Pins Description

Pin No.	Signal Name	Type	Description
1	LDP	PWR	Anode of the VCSEL LASER. This pin should be connected to VDD power supply (2.7V - 3.6V) through a resistor (Rext)
2	VDDA	PWR	Power supply for core circuitry, voltage range : 1.93V +/- 0.05V
3	VDD	PWR	Power supply for I/O and LASER, voltage range : 2.7V ~ 3.6V
4	VSS	GND	Chip ground
5	NCS	IN	Chip select for 3-wire SPI interface (active low)
6	DEBUG	IN	This pin is for debug purpose and is only for PixArt internal use. In normal operation, this pin should connect a 100k ohm resistor to GND.
7	SCLK	IN	Clock input for SPI interface
8	SDIO	I/O	Bi-directional I/O for SPI interface
9	MOTION	OUT	Interrupt output for motion detection (active low)
10	MFIO	IN	Multi-function input pin. This pin can be configured as Power-Down, Reset or Quick-Burst function. Default is Null function. Please tie to GND if this pin is not used (Null function).

2.0 Mechanical Specifications

2.1 Mechanical Dimension



1. All dimension units are mm.

Figure 3. Chip Package Outline Diagram

### 3.0 Operating Specifications

#### 3.1 Absolute Maximum Ratings

Table 2. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit	Notes
Supply Voltage	VDD	-0.3	3.9	V	I/O and LASER power
	VDDA	-0.2	2.3	V	Core circuitry power
ESD	ESD <sub>HBM</sub>		2	kV	Class 2 on all pins, as per human body model. JESD22-A114E with 15 sec zap interval.

**Notes:**

1. At room temperature.
2. Maximum Ratings are those values beyond which damage to the device may occur.
3. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation under absolute maximum-rated conditions is not implied.

#### 3.2 Recommended Operating Conditions

Table 3. Recommended Operating Conditions

Description	Symbol	Min.	Typ.	Max.	Unit	Notes
Storage Temperature	T <sub>STG</sub>	-40	-	85	°C	
Operating Temperature	T <sub>A</sub>	-20	25	60	°C	
Power Supply Voltage	VDD	2.7	3.3	3.6	V	I/O and LASER power supply
	VDDA	1.88V	1.93V	1.98V	V	Core circuitry power supply
Supply Noise (peak to peak)	V <sub>pp</sub>	-	-	100	mV	Peak to peak voltage within 100KHz – 80MHz
SPI Clock Frequency	SCLK	-	-	2	MHz	
Tracking Speed	SP	-	-	90	IPS	on glossy metal surfaces
				35		on white copy paper
Laser Drive Current (DC)	I <sub>LD</sub>	5.0	7.0	8.0	mA	Configured via LD_SRC register

**Note:** PixArt does not guarantee the performance if the operating temperature is beyond the specified limit.

#### 3.3 DC Characteristics

Table 4. DC Electrical Specifications

Parameters	Symbol	Min.	Typ.	Max.	Unit	Conditions
Power Consumption	I <sub>VDDRN</sub>	-	0.5	-	mA	VDD current @ run mode
	I <sub>VDDARN</sub>	-	15	-	mA	VDDA current @run mode
	I <sub>VDDPD</sub>	-	2	-	μA	VDD current @power down
	I <sub>VDDAPD</sub>	-	18	-	μA	VDDA current @power down
I/O Input High Voltage	V <sub>IH</sub>	0.7* V <sub>DD</sub>	-	-	V	
I/O Input Low Voltage	V <sub>IL</sub>	-	-	0.3* V <sub>DD</sub>	V	
I/O Output High Voltage	V <sub>OH</sub>	V <sub>DD</sub> -0.4	-	-	V	@I <sub>OH</sub> = 2mA
I/O Output Low Voltage	V <sub>OL</sub>	-	-	0.4	V	@I <sub>OL</sub> = 2mA

**Notes:** All the parameters are tested under operating conditions: V<sub>DD</sub> = 3.3V (including LASER current), T<sub>A</sub> = 25°C

### 4.0 Design Reference

#### 4.1 Reference Application Schematics

The chip only supports simplified 3-wire SPI slave mode, while some host controllers may only support standard 4-wire SPI master mode. In this case, users can connect the host controller to the chip using the method shown below to communicate with each other. Take note that the 3.3K ohm resistor is for reference only and the resistance may have to be modified according to different I/O capability as per the specification of the host controllers. The resistor Rext is mandatory to keep the current flowing through the LASER less than 8mA (the LASER max. rating) during the system power-up stage and at any operation condition. Please choose a correct resistance for Rext to match the VDD voltage according to the table below.

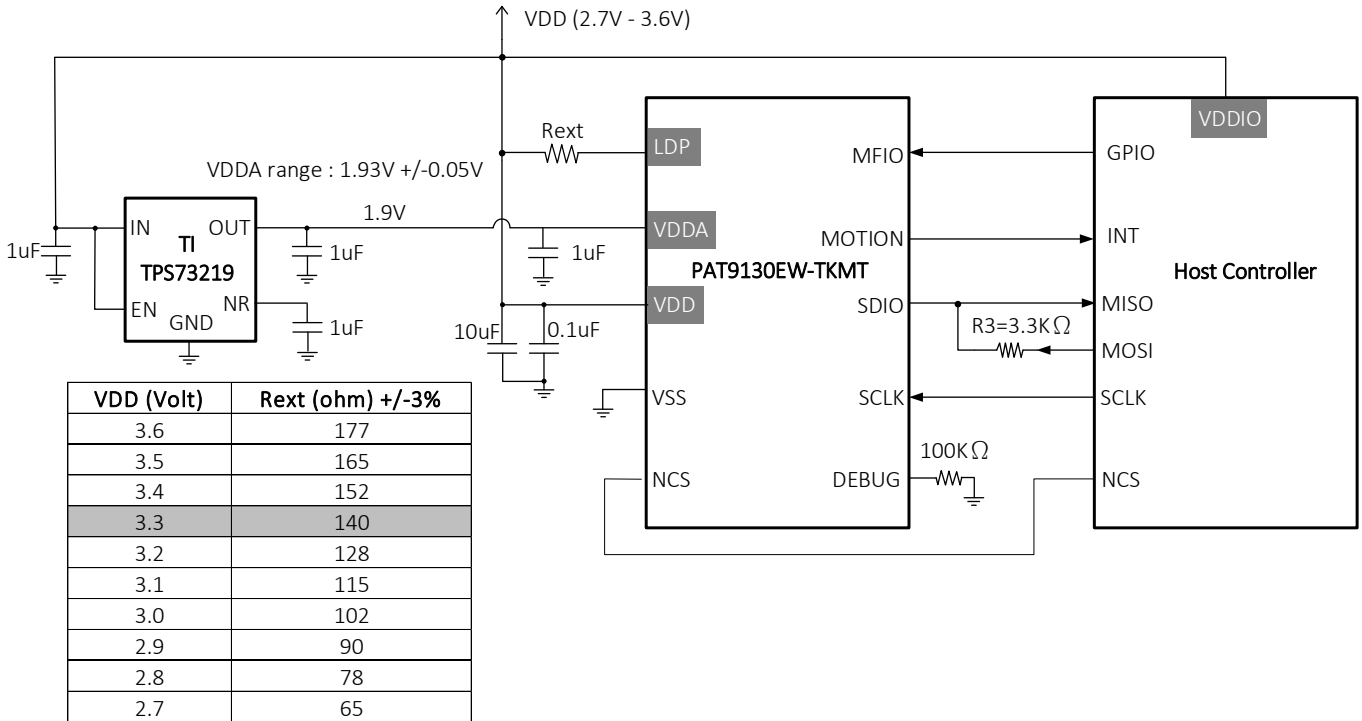


Figure 4. Reference Application Schematics

## 5.0 Registers

### 5.1 Registers Summary

Table 5. Registers List

Address	Register Name	Access	Reset	Brief Description
0x00	Product_ID1	R	0x31	Product Identifier [11:4]
0x01	Product_ID2	R	0x61	Upper 4 bits for Product Identifier, PID [3:0] Lower 4 bits for Product Version, VID [3:0]
0x02	Motion_Status	R	-	Motion Status information
0x03	Delta_XL	R	-	Low Byte of X-movement for 16-bit 2's complement data X-movement[15:0] = {Delta_XH[7:0], Delta_XL[7:0]}
0x04	Delta_YL	R	-	Low Byte of Y-movement for 16-bit 2's complement data Y-movement[15:0] = {Delta_YH[7:0], Delta_YL[7:0]}
0x06	Configuration	R/W	0x10	Software power down and reset
0x09	Write_Protect	R/W	0x00	Write Protect to avoid missed-writing registers
0x0D	RES_X	R/W	0x27	CPI resolution setting for X-direction
0x0E	RES_Y	R/W	0x2B	CPI resolution setting for Y-direction
0x11	Delta_XH	R	-	High Byte of X-movement for 16-bit 2's complement data X-movement[15:0] = {Delta_XH[7:0], Delta_XL[7:0]}
0x12	Delta_YH	R	-	High Byte of Y-movement for 16-bit 2's complement data Y-movement[15:0] = {Delta_YH[7:0], Delta_YL[7:0]}
0x13	IQ	R	-	Image Quality[7:0]
0x15	Shutter	R	-	Shutter value[7:0]
0x17	Frame_Avg	R	-	Average brightness of a frame
0x26	MFIO_Config	R/W	0x34	Configuration the function of MFIO pin
0x51	LD_SRC	R/W	0x0E	Programmable current source for LASER



Document Revision History

Revision Number	Date	Description
1.0	12 Jun. 2017	New creation based on DS v1.0