

PI6C5930

Low Skew CMOS PLL Clock Driver

Features

- Wide frequency range: 100 MHz max.
- Five Q and one Q/2 outputs
- Output skew < 250ps (rising edges)
- Internal RC loop filter network
- Low noise TTL-compatible outputs
- Balanced drive outputs: $\pm 24\text{mA}$
- Outputs Hi-Z and registers reset when OE = LOW
- PLL bypass for testing and low-frequency applications
- Small footprint 20-pin QSOP package (Q)

Description

The PI6C5930 clock driver uses a PLL (phase-locked loop) to reduce time skew between a reference clock input (SYNC) and the outputs. An internal loop filter eliminates the need for external compensation. This driver generates six clock outputs: Q0 through Q4 running at the same frequency, plus Q/2 which runs at one half the frequency of Q0-Q4.

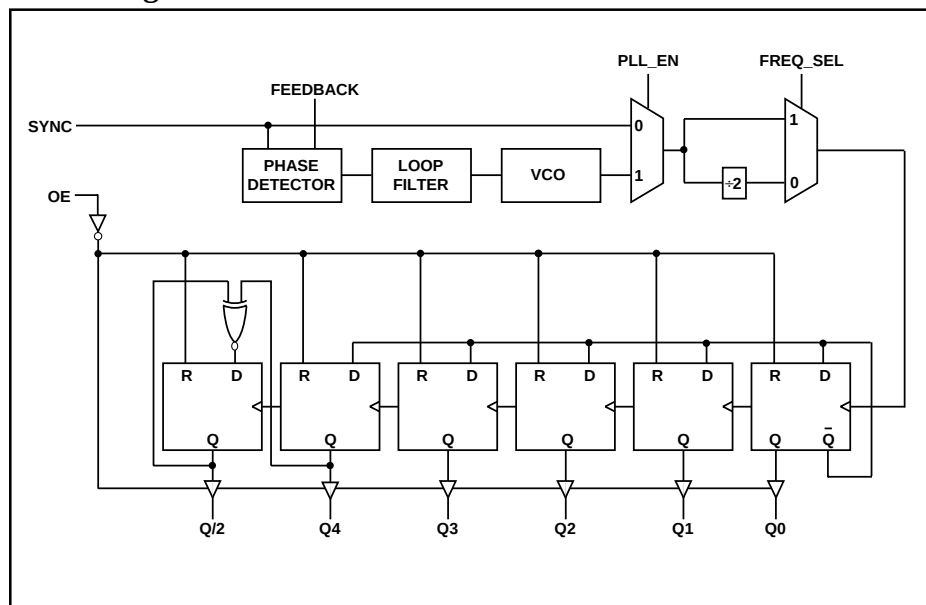
Thanks to design improvements, the PI6C5930 is capable of generating highly stable frequencies up to 100 MHz, while maintaining less than 250 ps skew between outputs.

When $\text{FREQ_SEL} = \text{HIGH}$, applying either one of the Q0-Q4 outputs to the FEEDBACK pin results in five copies of the reference input. If Q/2 is applied to the FEEDBACK pin, five clocks at double the reference input are created.

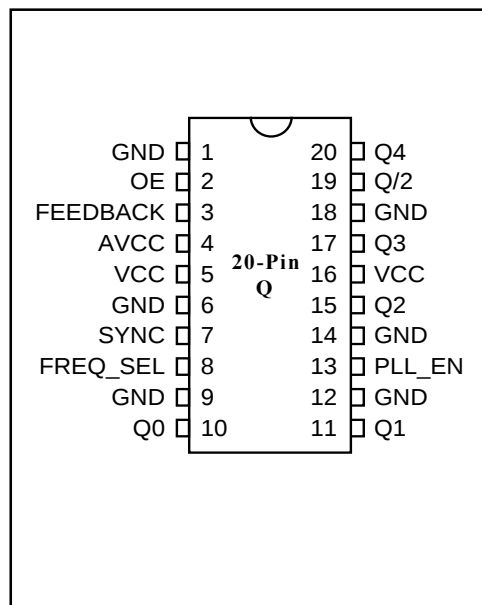
The output enable (OE) function may be used to turn all outputs off and save power. The FREQ_SEL input is set to LOW if the SYNC frequency is lower than 30 MHz, otherwise it should be set HIGH.

The PLL_EN function can be used for testing and to bypass the PLL in low frequency applications.

Block Diagram



Pin Configuration



Absolute Maximum Ratings

Supply Voltage to Ground	–0.5V to +7.0V
DC Input Voltage V_{IN}	–0.5V to +7.0V
AC Input Voltage (for a pulse width ≤ 20 ns)	–3.0V
Maximum Power Dissipation	1.0 W
Storage Temperature	–65°C to +150°C

Note:

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Pin Description

Pin Name	I/O	Functional Description
SYNC	I	Synchronizing Reference Clock Input.
FREQ_SEL	I	Frequency Select. Chooses optimal VCO operating frequency. HIGH is for frequencies >30 MHz, LOW is for frequencies <30 MHz.
FEEDBACK	I	Feedback Input. Connected to either a Q or a Q/2 output. See the Frequency Selection Table for more information.
Q0-Q4	O	Clock Outputs.
Q/2	O	Clock Output. Synchronized, but runs at half the Q frequency.
OE	I	Output Enable. HIGH = outputs active. LOW = all outputs held in a tri-stated condition and output registers are reset.
PLL_EN	I	PLL Enable. Enables and disables the PLL. When LOW it allows the SYNC input to be passed through for system testing.

Output Frequency Specifications (Commercial: $T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5.0\text{V} \pm 5\%$)

Symbol	Description	PI6C5930	Units
FQ	Maximum frequency, Q0-Q4 outputs	100	MHz
FQ/2	Maximum frequency, Q/2 output	50	

Frequency Selection Table

FREQ_SEL	Output Used for Feedback	Allowable SYNC ⁽¹⁾ Range (MHz)		Output Frequency Relationships	
		Min.	Max.	Q Outputs	Q/2
1	Q/2	5	$FQ \div 2$	$SYNC \times 2$	SYNC
1	Q0-Q4	10	FQ	SYNC	$SYNC \div 2$
0	Q/2	2.5	$FQ \div 4$	$SYNC \times 2$	SYNC
0	Q0-Q4	5	$FQ \div 2$	SYNC	$SYNC \div 2$

Notes:

1. Operation in the specified SYNC frequency range guarantees that the VCO will operate in its optimal frequency range. Operation with SYNC outside the specified frequency ranges may result in invalid or out-of-lock outputs.

DC Electrical Characteristics Over Operating Range ($T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5.0\text{V} \pm 5\%$)

Symbol	Parameter	Test Conditions	Min.	Typ. ⁽¹⁾	Max.	Units
V_{IH}	Input HIGH Voltage	Guaranteed Logic HIGH Level	2.0	—	—	V
V_{IL}	Input LOW Voltage	Guaranteed Logic LOW Level	—	—	0.8	
V_{OH}	Output HIGH Voltage	$V_{CC} = \text{Min.}, I_{OH} = -24\text{mA}$ $V_{CC} = \text{Min.}, I_{OH} = -100\mu\text{A}$	2.4 3.0	— —	— —	
V_{OL}	Output LOW Voltage	$V_{CC} = \text{Min.}, I_{OH} = 24\text{mA}$ $V_{CC} = \text{Min.}, I_{OH} = 100\mu\text{A}$	— —	— —	0.55 0.2	
I_{OZ}	Output Leakage Current	$V_{OUT} = V_{CC}$ or $V_{OUT} = \text{GND}$, $V_{CC} = \text{Max.}$, Outputs Disabled	-5	—	5	μA
I_{IN}	Input Leakage Current	$V_{IN} = V_{CC}$ or $V_{IN} = \text{GND}$ $V_{CC} = \text{Max}$	-5	—	5	

Note:

1. Typical values indicate $V_{CC} = 5.0\text{V}$ and $T_A = 25^\circ\text{C}$.

Power Supply Characteristics

Symbol	Parameter	Test Conditions ⁽¹⁾	Typ.	Max.	Units
ΔI_{CC}	Input Power Supply Current per TTL Input HIGH	$V_{CC} = \text{Max.}$, $V_{IN} = 3.4\text{V}$	—	1.5	mA
I_{CCD}	Dynamic Power Supply Current per Output ⁽²⁾	$V_{CC} = \text{Max.}$	—	0.1	mA/MHz

Notes:

1. For Min. or Max. conditions, use the appropriate values specified under DC specifications.
2. Guaranteed but not tested.
3. For all DC parameters, test conditions assume no output loading.

Input Timing Requirements ($T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5.0\text{V} \pm 5\%$)

Symbol	Description ⁽¹⁾	Min.	Max.	Units
t_R, t_F	Maximum Input Rise and Fall Times, 0.8V to 2.0V	—	3.0	ns
F_I	Input Clock Frequency, SYNC ⁽¹⁾	5	FQ	MHz
t_{PWC}	Input Clock Pulse, HIGH or LOW	2	—	ns
D_H	Duty Cycle, SYNC	25%	75%	%

Note:

1. The F_I specification is based on Q output feedback. See Frequency Selection Table for more detail on allowable SYNC input frequencies for different feedback combinations.

Capacitance ($T_A = 25^\circ\text{C}$, $f = 1\text{ MHz}$, $V_{IN} = 0\text{V}$, $V_{OUT} = 0\text{V}$)

Pins	QSOP		Units
	Typ.	Max.	
C_{IN}	3	4	pF
C_{OUT}	7	9	

Note:

Capacitance is characterized but not tested.

Switching Characteristics Over Operating Range

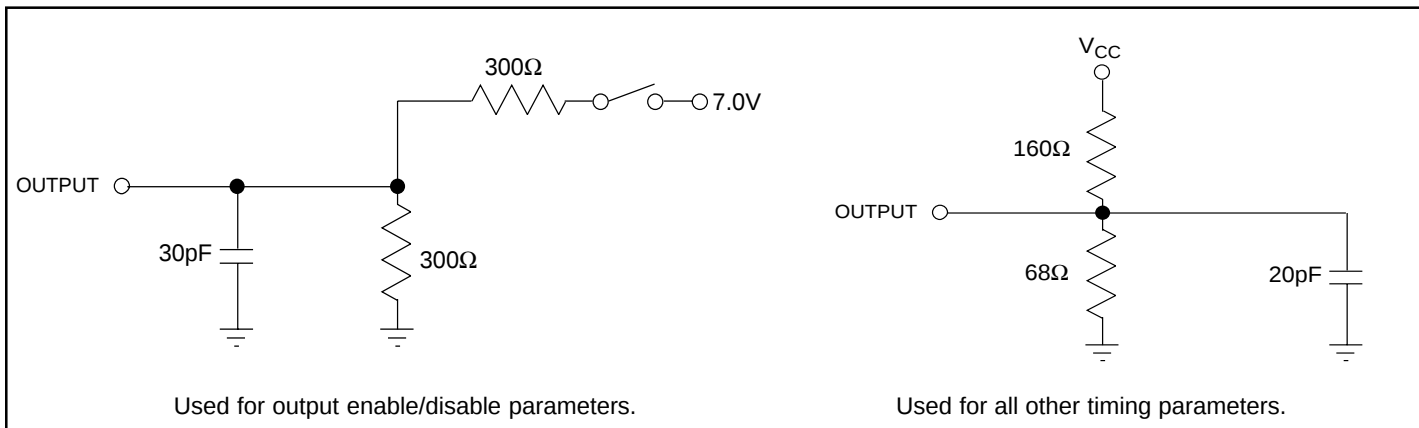
($T_A = 0^\circ\text{C}$ to 70°C , $V_{CC} = 5.0\text{V} \pm 5\%$)

Symbol	Description ⁽¹⁾	Min.	Typ.	Max.	Units
t_{SKR}	Output Skew Between Rising Edges, Q4-Q0 and Q/2 ^(2,3)	—	—	250	ps
t_{SKF}	Output Skew Between Falling Edges, Q4-Q0 ^(2,3)	—	—	350	
t_{PW}	Pulse Width ⁽²⁾	$T_{CY}/2-0.4$	—	$T_{CY}/2+0.4$	ns
t_J	Cycle to Cycle Jitter, 33 MHz ⁽⁵⁾	—	—	250	ps
t_{PD}	SYNC Input Feedback Delay, 10 MHz	-100	—	400	
t_{PD}	SYNC Input Feedback Delay, 33 MHz, 50Ω to $1.5\text{V}^{(2)}$	-100	—	400	
t_{LOCK}	SYNC to Phase Lock ⁽²⁾	—	—	10	ms
t_{PZH} , t_{PZL}	Output Enable Time, OE HIGH to Low-Z ⁽⁴⁾	0	—	7	ns
t_{PHZ} , t_{PLZ}	Output Disable Time, OE LOW to High-Z ⁽⁴⁾	0	—	6	
t_R , t_F	Output Rise and Fall Times, 0.8V to $2.0\text{V}^{(2)}$	0.4	—	1.5	

Notes:

1. See Test Circuit and Waveforms. Minimums guaranteed but not tested.
2. This parameter is guaranteed by design but not tested.
3. Skew specifications apply under identical environments (loading, temperature, V_{CC} , device speed grade).
4. Measured in open loop mode $PLL_EN = 0$.
5. Jitter is characterized using a time interval analyzer. Characterized but not tested.
See FREQUENCY SELECTION TABLE for information on proper $FREQ_SEL$ level for specified SYNC input frequencies.

Test Loads



Ordering Information

P/N	Max. Output Freq.	Pkg.
PI6C5930Q	100 MHz	20-pin QSOP