

R2A30440NP

R19DS0063EJ0100

Rev.1.00

May 10, 2012

6-Channel Motor Driver IC for DSC, DVC and Surveillance Cameras

Overview

The R2A30440NP is a semiconductor integrated circuit that incorporates driver circuits suitable for motors in digital cameras. The terminal arrangements are basically identical to that of R2A30423NP.

Features

- CMOS process adoption and 1ch-4ch using D class amplifier to achieve low power consumption.
- A small 40-pin QFN package 5mm x 5mm, t=0.80mm (max) is used.
- Built-in autonomous drive circuit controlled by serial settings (self propelled control)
- 1ch/2ch and 3ch/4ch are capable of 2-2 phase stepper drive, 1-2 phase (100%) stepper drive, 1-2 phase (70%) stepper drive and 256/512/1024 resolution micro-steps.
- 3ch/4ch is capable of constant voltage drive.
- 5ch is capable of constant current drive and FLL control.
- 6ch is capable of constant current drive.
- By using exclusive control mode on 5ch and 6ch, it resembles 7ch drive.
- Built-in 3 PI drivers channels
- Built-in 2 comparators and 1 Schmitt buffer.
- Built-in low-voltage malfunction prevention and thermal shutdown circuit.
- Power supplies VCC and VM are internally isolated and include a function to prevent reverse current between the power supplies.

Application

Motor driver for digital still cameras

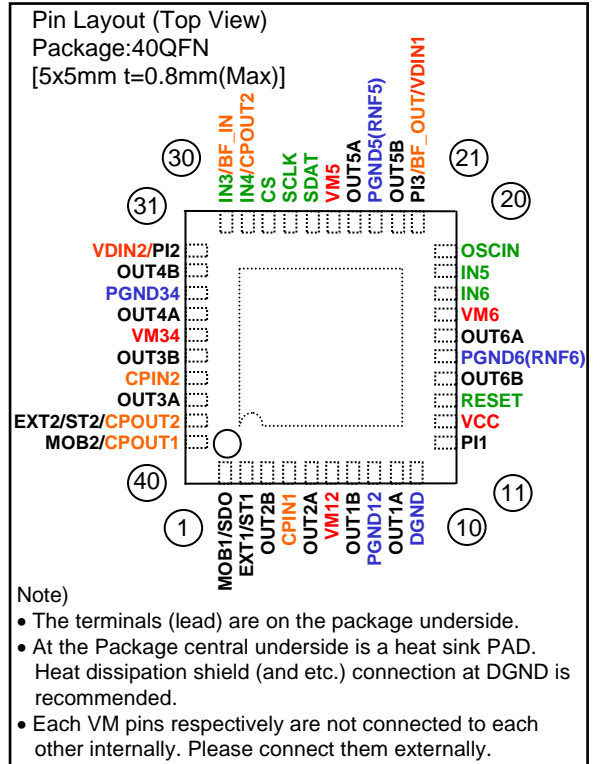
Recommended operating conditions

Power-supply voltage range VCC: 2.7V~3.6V

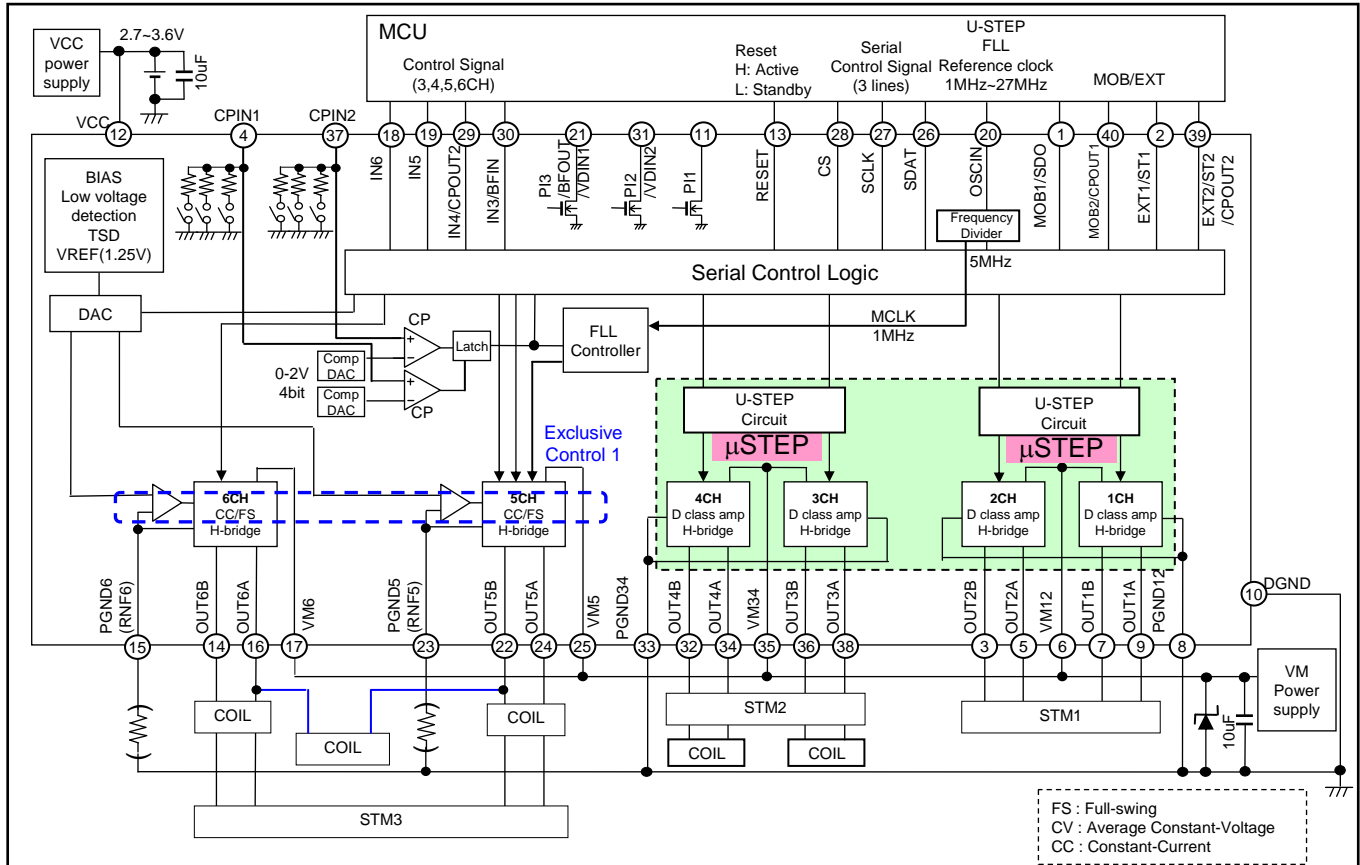
VM: 2.7V~5.5V

Rated power-supply voltage VCC: 3.3V

VM: 5.0V



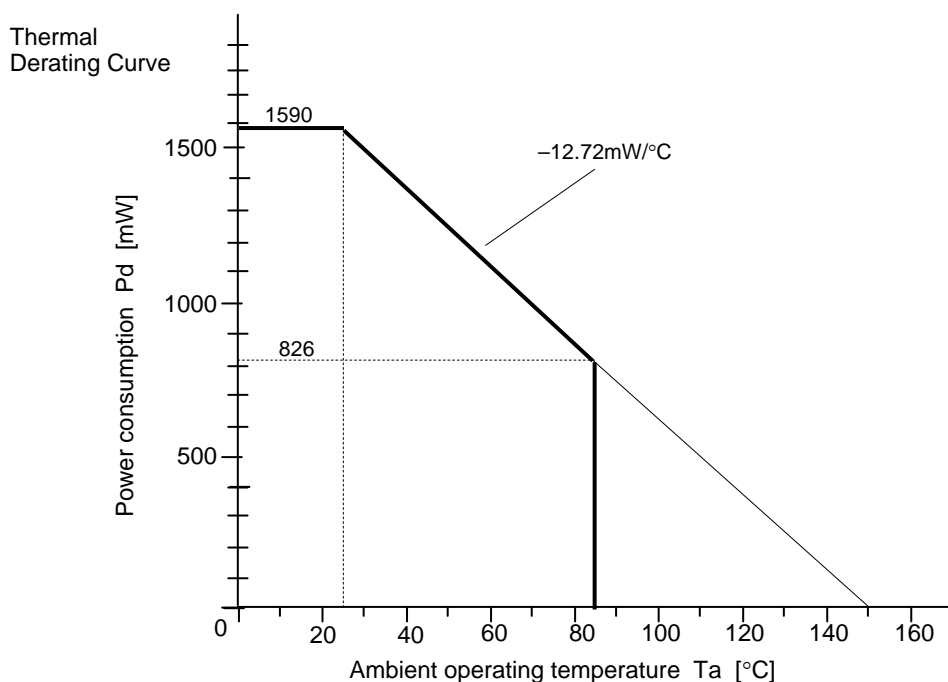
Block diagram and example of application circuit



Absolute Maximum Ratings (Unless specified, the ambient temperature is 25°C)

| Item | Symbol | Rated Value | Unit | Remarks |
|--|------------------|--------------|-------|-------------------------------|
| Power-supply voltage 1 | VCC | 6.5 | V | Note1 |
| Power-supply voltage 2 | VM | 6.5 | V | Note1 |
| Direct current (1ch~2ch) | I _{od} | ±600 | mA/ch | Note4 DC |
| Instantaneous output current (1ch~2ch) | I _{op} | ±800 | mA/ch | Note4 PW < 10ms, Duty ≤ 20% |
| Direct current (3ch~6ch) | I _{od} | ±800 | mA/ch | Note4 DC |
| Allowable power consumption | P _d | 1590 | mW | Note2 (T _a = 25°C) |
| Thermal derating ratio | K _θ | -12.72 | mW/°C | Note2 (T _a ≥ 25°C) |
| Max. junction temperature | T _j | 150 | °C | |
| Applied input voltages | V _{in} | -0.3~VCC+0.3 | V | Note3 |
| Ambient operating temperature | T _{opr} | -30~85 | °C | |
| Storage temperature | T _{stg} | -40~150 | °C | |

- Notes:
- As a rule, do not apply reverse power-supply voltages.
 - Glass epoxy board: 76.2mm x 114.5mm x 1.6mm,
copper-occupancy ratio in a 4-layer board: 20% in layers 1 and 4, 100% in layers 2 and 3.
Note that the allowable power consumption changes according to the conditions imposed on the board.
 - As a rule, do not apply voltages above the power-supply voltage or below the GND voltage.
 - The total output current does not exceed the rated value in usage with multiple channels simultaneously turned on.



[Remarks]

The electric power which the power consumption of this IC with the output transistor of 1ch - 6ch becomes dominant.

Output transistor power consumption formula

<Full Swing/Constant Voltage>: (output current)² x ON resistance E.g. (500mA)² x 2.0ohm=500mW

<Constant current>: output current x {VM - RNF5 - output current x RM}

Note: In constant current control, the on resistance is not included in the calculation

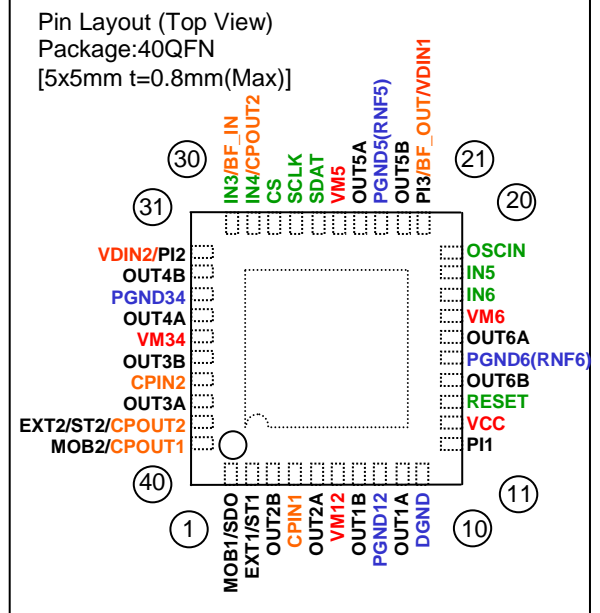
We recommend that you solder to connect the heatsink at the bottom of the package.

(To fix it to a potential, please connect with pin 10: DGND)

When the ambient temperature is 25°C or more, refer to the above figure in selecting the required heat sink.

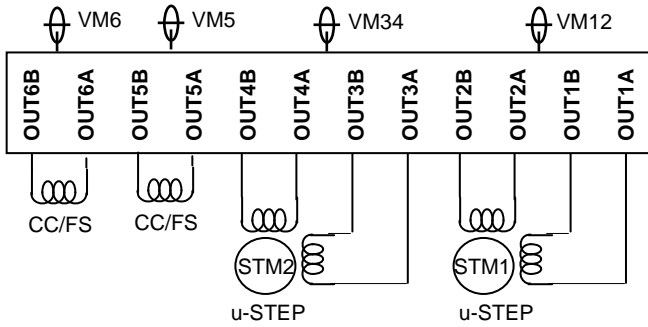
Terminal Function Explanation

| Pin No. | Pin Name | I/O | Pin Function |
|---------|-------------------|--------------|---|
| 1 | MOB1/SDO | O | MOB1/SDO output |
| 2 | EXT1/ST1 | O | EXT1/ST1 output |
| 3 | OUT2B | O | Channel 2 B output |
| 4 | CPIN1 | I | Comparator 1 input |
| 5 | OUT2A | O | Channel 2 A output |
| 6 | VM12 | Power supply | Motor power supply for channels 1, 2 |
| 7 | OUT1B | O | Channel 1 B output |
| 8 | PGND12 | GND | Motor power GND for channels 1, 2 |
| 9 | OUT1A | O | Channel 1 A output |
| 10 | DGND | GND | Control GND |
| 11 | PI1 | O | PI driver output |
| 12 | VCC | Power supply | Control power supply |
| 13 | RESET | I | Internal logic reset |
| 14 | OUT6B | O | Channel 6 B output |
| 15 | PGND6(RNF6) | GND | Motor power GND for channel 6 |
| 16 | OUT6A | O | Channel 6 A output |
| 17 | VM6 | Power supply | Motor power supply for channel 6 |
| 18 | IN6 | I | Channels 5, 6 control |
| 19 | IN4 | I/O | Channels 4, 5, 6 control /Comparator 2 output |
| 20 | OSCIN | I | Clock |
| 21 | PI3/BF_OUT /VDIN1 | I/O | PI driver output/Buffer Output /VD signal input 1 |
| 22 | OUT5B | O | Channel 5 B output |
| 23 | PGND5(RNF5) | GND | Motor power GND for channel 5 |
| 24 | OUT5A | O | Channel 5 A output |
| 25 | VM5 | Power supply | Motor power supply for channel 5 |
| 26 | SDAT | I | Serial control signal |
| 27 | SCLK | I | Serial control signal |
| 28 | CS | I | Serial control signal |
| 29 | IN4 | I | Channels 3, 4, 5, 6 control |
| 30 | IN3/BF_IN | I | Channels 3, 5 control/Buffer input |
| 31 | PI2/VDIN2 | I/O | PI driver output/ VD signal input 2 |
| 32 | OUT4B | O | Channel 4 B output |
| 33 | PGND34 | GND | Motor power GND for channels 3, 4 |
| 34 | OUT4A | O | Channel 4 A output |
| 35 | VM34 | Power supply | Motor power supply for channels 3, 4 |
| 36 | OUT3B | O | Channel 3 B output |
| 37 | CPIN2 | I | Comparator 2 input |
| 38 | OUT3A | O | Channel 3 A output |
| 39 | EXT2/ST2 /CPOUT2 | O | EXT2/ST2 output /Comparator 2 output |
| 40 | MOB2 /CPOUT1 | O | MOB2 output /Comparator 1 output |



Actuator connection pattern(1)

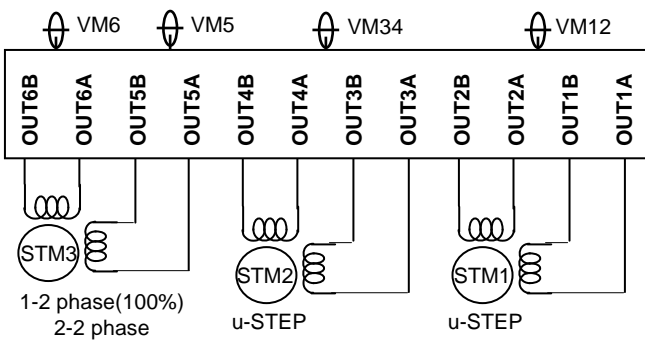
[Connection pattern 1]



| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch |
|---------------------------|---------------------------|---|-----|--|-------|
| STM1 | STM2 | CC/FS | | CC/FS | CC/FS |
| Serial autonomous control | Serial autonomous control | 1line control (IN3 or IN4 or IN5) or 2line control (IN3/IN4) (IN3/IN5) (IN4/IN5) or Serial or serial (automatic PWM) or 1line control (IN3or IN4 or IN5) FLL control serial+1line (IN3 or IN4 or IN5) | | 1line control (IN6) or 2line control (IN5/IN6) | |

The control method of each CH is set through serial.
5ch FLL control/ automatic PWM control is only valid after FS mode is selected.

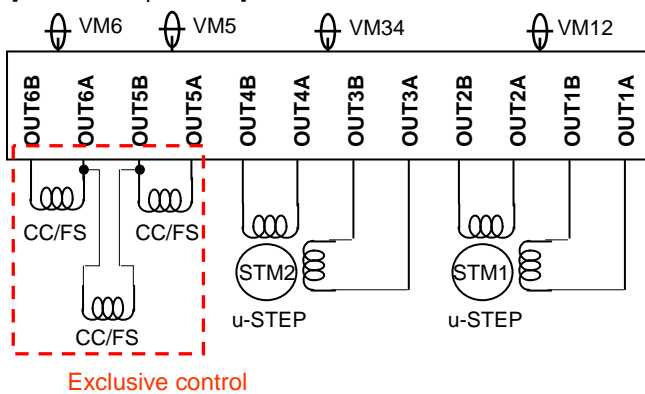
[Connection pattern 2]



| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch |
|---------------------------|---------------------------|--|-----|-------|-----|
| STM1 | STM2 | STM3 | | CC/FS | |
| Serial autonomous control | Serial autonomous control | 3line control (IN4/IN5/IN6) or (IN3/IN5/IN6) | | | |

The control method of each CH is set through serial.

[Connection pattern 3]



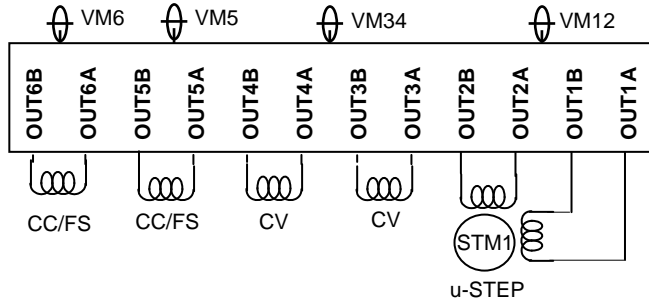
| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch | 7ch |
|---------------------------|---------------------------|---|-----|--|-------|--------|
| STM1 | STM2 | CC/FS | | CC/FS | CC/FS | CC/FS |
| Serial autonomous control | Serial autonomous control | 1line control (IN3 or IN4 or IN5) or 2line control (IN3/IN4) (IN3/IN5) (IN4/IN5) or serial or serial (automatic PWM) or 1line control (IN3or IN4 or IN5) FLL control serial+1line (IN3 or IN4 or IN5) | | 1line control (IN6) or 2line control (IN5/IN6) | | Serial |

The control method of each CH is set through serial.
5ch FLL control/ automatic PWM control is only valid after FS mode is selected.

Exclusive Control
5ch,6ch,7ch cannot be simultaneously operated.
Only one channel is operated at a time.

Actuator connection pattern(2)

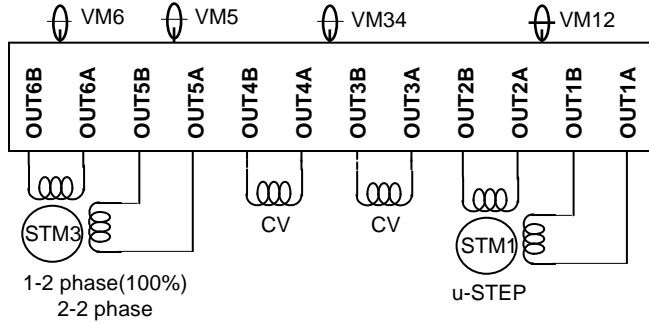
[Connection pattern 4]



| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch |
|---------------------------|---|---|---|---|---|
| STM1 | CV | CV | CV | CC/FS | CC/FS |
| Serial autonomous control | 1line control (IN3 or IN4 or IN5) or serial | 1line control (IN3 or IN4 or IN5) or serial | 1line control (IN3 or IN4 or IN5) or serial | 1line control (IN3 or IN4 or IN5) or 2line control (IN3/IN4) (IN3/IN5) (IN4/IN5) or serial or serial (automatic PWM) or 1 line control (IN3or IN4 or IN5) | 1line control (IN6) or 2 line control (IN5/IN6) |
| | | | | FLL control serial +1line (IN3 or IN4 or IN5) | |

The control method of each CH is set through serial.
 5ch FLL/automatic PWM control is only valid after FS mode is selected.
 For CH3 & CH4 CV, the output is from a D-class amplifier and therefore the output is full swing PWM.

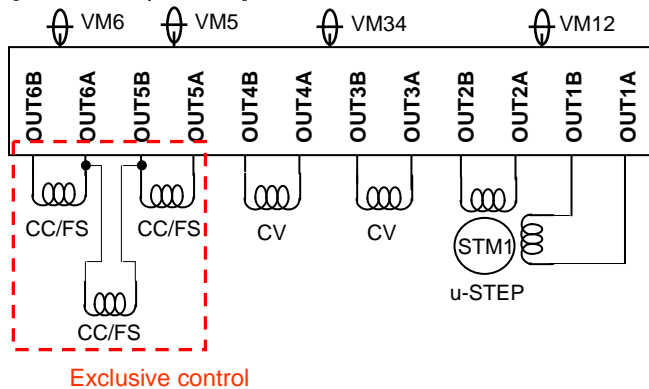
[Connection pattern 5]



| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch |
|---------------------------|--|--|--|--|-----|
| STM1 | CV | CV | CV | STM3 CC/FS | |
| Serial autonomous control | 1line control (IN3or IN4 or IN5) or serial | 1line control (IN3or IN4 or IN5) or serial | 1line control (IN3or IN4 or IN5) or serial | 3line control (IN4/IN5/IN6) or (IN3/IN5/IN6) | |

The control method of each CH is set through serial.
 For CH3 & CH4 CV, the output is from a D-class amplifier and therefore the output is full swing PWM.

[Connection pattern 6]

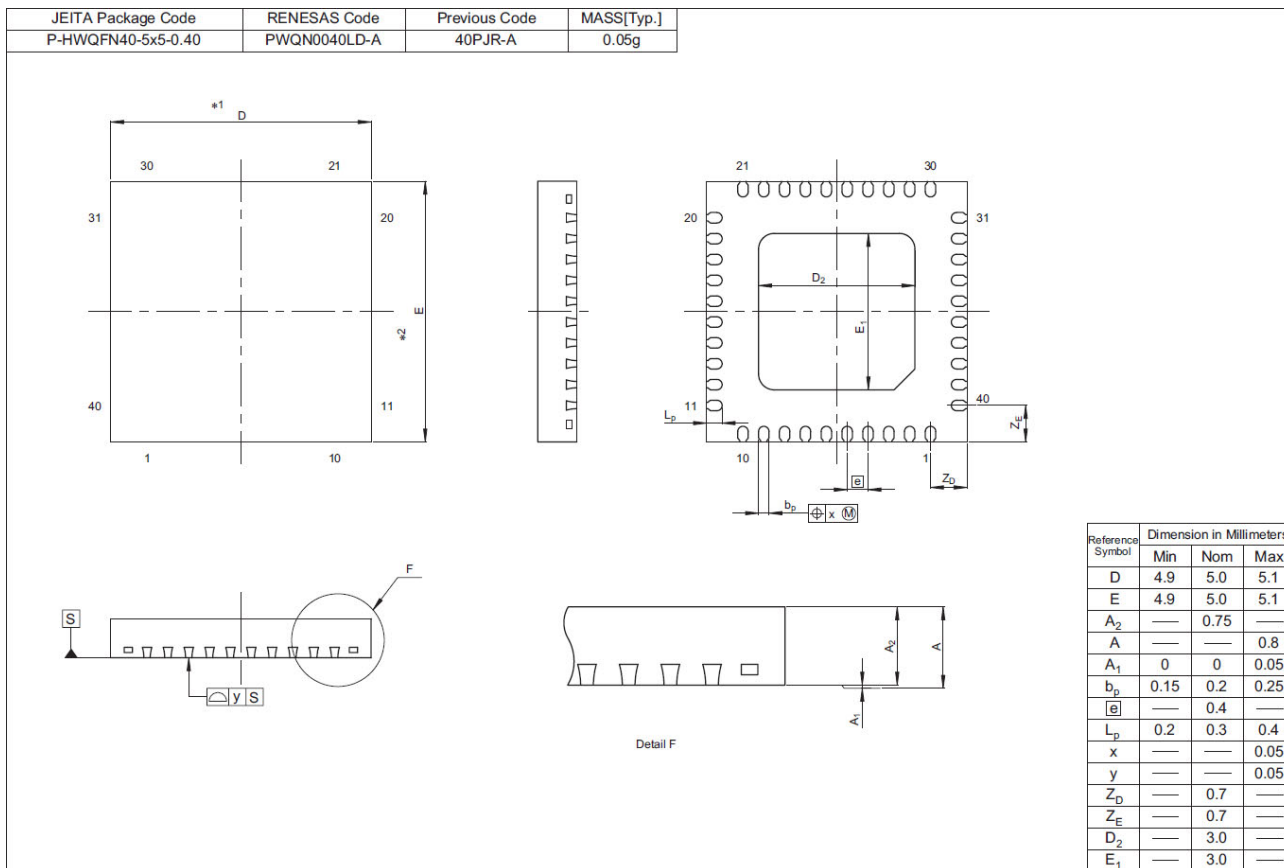


| 1ch | 2ch | 3ch | 4ch | 5ch | 6ch | 7ch |
|---------------------------|--|--|--|--|--|--------|
| STM1 | CV | CV | CV | CC/FS | CC/FS | CC/FS |
| Serial autonomous control | 1line control (IN3or IN4 or IN5) or serial | 1line control (IN3or IN4 or IN5) or serial | 1line control (IN3or IN4 or IN5) or serial | 1line control (IN3 or IN4 or IN5) or 2line control (IN3/IN4) (IN3/IN5) (IN4/IN5) or serial or Serial (automatic PWM) or 1line control (IN3or IN4 or IN5) | 1line control (IN6) or 2line control (IN5/IN6) | Serial |
| | | | | FLL control serial +1line (IN3 or IN4 or IN5) | | |

The control method of each CH is set through serial.
 5ch FLL/automatic PWM control is only valid after FS mode is selected.
 For CH3 & CH4 CV, the output is from a D-class amplifier and therefore the output is full swing PWM.

Exclusive Control
 5ch,6ch,7ch cannot be simultaneously operated.
 Only one channel is operated at a time.

Package Dimensions



Ordering Information

| Orderable Part No. | Package Code | Quantity |
|--------------------|--------------|----------|
| R2A30440NP#W0 | PWQN0040LD-A | 5000 pcs |
| R2A30440NP#U0 | PWQN0040LD-A | 1 pc |

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