

Triple Channel PWM Controller with I²C Interface Control for IMVP9.2 CPU Core Power Supply

1 General Description

The RT3638AE is an IMVP9.2 compliant CPU power controller which includes three voltage rails: an 8-phase synchronous buck controller for VCCCORE VR, a single-phase synchronous buck controller for VCCGT VR and a single -phase synchronous buck controller for VCCSA VR. The output of each rail can be configured to support desired phase assignments up to a maximum phase count of 8 phases for VCCCORE, single phase for VCCGT and single phase for VCCSA. For example, the RT3638AE supports output operations of 8+1+1, 7+1+1, 6+1+1, etc. The RT3638AE supports Smart Phase Management (SPM) feature, to achieve maximum efficiency in all load range. Thresholds for automatic phase add/drop are user-programmable via I²C protocol interface. The RT3638AE adopts G-NAVP[™] (Green Native AVP), which is Richtek's proprietary topology derived from finite DC gain of EA amplifier with current mode control, making it easy to set the droop to meet all Intel CPU requirements of AVP (Adaptive Voltage Positioning). Based on the G-NAVP[™] topology, the RT3638AE features a new generation of quick response mechanism (Adaptive Quick Response, AQR) to optimize AVP performance during load transient and reduce output capacitors. The RT3638AE supports mode transition function with various operating states.

A serial VID (SVID) interface is built in to communicate with Intel IMVP9.2 compliant CPU. The RT3638AE offers built-in non-volatile memory (NVM) for platform setting functions, such as ICCMAX, switching frequency or AQR trigger level. The RT3638AE provides VR ready output signals. It also features complete fault protection functions including overvoltage (OV), overcurrent (OC), undervoltage (UV) and undervoltage lockout (UVLO). The RT3638AE is available in the WQFN-68L 8x8 foot print package. The recommended junction temperature is -40°C to 125°C.

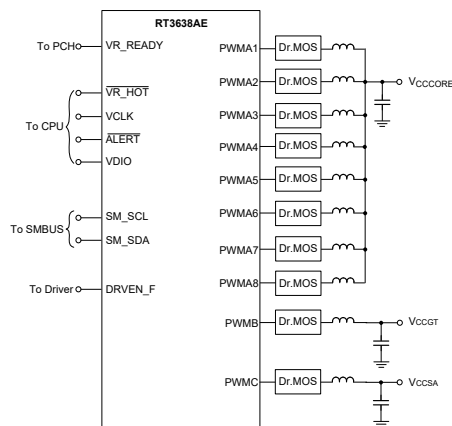
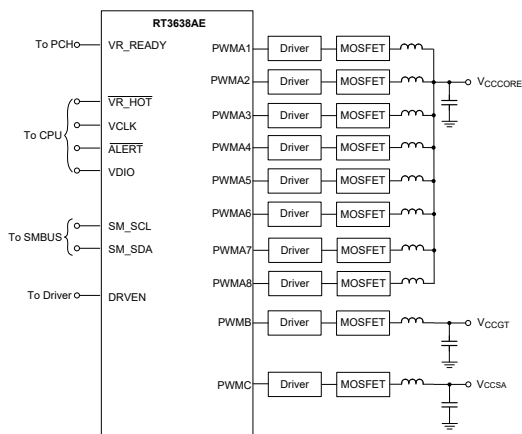
2 Features

- Intel IMVP9.2 Compliant
- 8/7/6/5/4/3/2/1/0 Phase (VCCCORE VR) + 1/0 Phase (VCCGT VR) + 1/0 Phase (VCCSA VR) PWM Configuration
- Support SPS with Current Sensing by Either Current Type or Voltage Type
- Support 1 PWM Drive 2 Power Stage and Phase Doubler RT9637 for Core Rail Up to 16-Phase Operation
- Easy-Set G-NAVP[™] Control
- 0.5% DAC Accuracy
- Differential Remote Voltage Sense
- Internal Non-Volatile Memory to Store Custom Configuration
- Accurate Current Balance
- Diode Emulation Mode at Light-Load Condition
- Fast Transient Response-Adaptive Quick Response
- VR Ready Indicator
- Output Current Monitoring
- Protection Flag for OVP, OCP, UVP
- Switching Frequency Setting
- Slew Rate Setting
- DVID Enhancement
- Acoustic Noise Suppression Function
- Support Fast V-Mode (FVM)
- Zero Loadline
- Rail Disable
- Smart Phase Management Adjustment
- Standard I²C Protocol Interface
 - Thermal Balance Adjustment
- Soldering Good Detection
- Small 68-Lead WQFN Package

3 Applications

- IMVP9.2 Intel Core Supply
- Desktops/Notebook Computer
- AVP Step-Down Converter

4 Simplified Application Circuit



5 Ordering Information

RT3638AE □□-□

The configuration code identifier for the register setting stored in the internal NVM

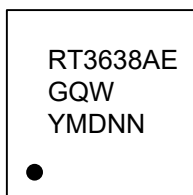
Package Type
QW: WQFN-68L 8x8 (W-Type)

Lead Plating System
G: Richtek Green Policy Compliant

Note:

Richtek products are Richtek Green Policy compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.

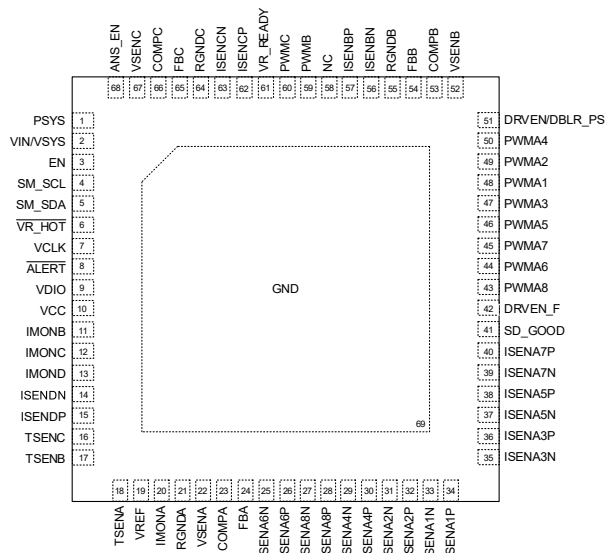
6 Marking Information



RT3638AEGQW : Product Code
YMDNN : Date Code

7 Pin Configuration

(TOP VIEW)



WQFN-68L 8x8

8 Functional Pin Description

Pin No.	Pin Name	Pin Function
1	PSYS	System input power monitor. Place the PSYS resistor as close to the IC as possible. The PSYS function can be disabled by pulling the voltage at the PSYS pin > (VCC – 0.5V). If the platform does not support PSYS function, it is recommended to connect the PSYS pin to GND to avoid affecting system performance. The full scale 1.6V/3.2V of PSYS is programmable via configuration register in NVM.
2	VIN/VSYS	Input voltage pin. Connect a low-pass filter of which time constant is at the switching frequency to this pin for setting on-time.
3	EN	VR enable control input.
4	SM_SCL	Clock input for the I ² C interface. If the I ² C communication is not used, connect the SM_SCL and SM_SDA pins to higher than 3.3V to achieve power saving.
5	SM_SDA	Data line for the I ² C interface. If the I ² C communication is not used, connect the SM_SCL and SM_SDA pins to higher than 3.3V to achieve power saving.
6	VR_HOT	Thermal monitor output. (Active low).
7	VCLK	Synchronous clock from the CPU.
8	ALERT	SVID alert. (Active low).
9	VDIO	VR and CPU data transmission interface.
10	VCC	Controller power supply. Connect this pin to 5V and place RC filter, R = 1Ω and C = 2.2μF. The decoupling capacitor should be placed as close to PWM controller as possible. The recommended size of Rvcc is 0603.
11	IMONB	Rail B VR current monitor output for controller. This pin outputs a voltage proportional to the output current.
12	IMONC	Rail C VR current monitor output for controller. This pin outputs a voltage proportional to the output current.
13	IMOND	Rail D VR current monitor output for controller. This pin outputs a voltage proportional to the output current.
14	ISENDN	Negative input of current-sense amplifier for rail D.
15	ISENDP	Positive input of current-sense amplifier for rail D.
16	TSENC	Thermal sense input for rail C.
17	TSENB	Thermal sense input for rail B.
18	TSENA	Thermal sense input for rail A.
19	VREF	Fixed 0.6V output reference voltage. This voltage is used to offset the output voltage of all IMON pins. When the controller shuts down or sets all rail in PS4, voltage source shuts down. An exact 0.47μF decoupling capacitor and a 3.9Ω resistor must be placed between this pin and GND.
20	IMONA	Rail A VR current monitor output for controller. This pin outputs a voltage proportional to the output current.
21	RGNDA	Return ground for rail A VR. This pin is the negative node of the differential remote voltage sense.
22	VSENA	Rail A VR voltage sense input. This pin is connected to the terminal of rail A VR output voltage.
23	COMPA	Rail A VR compensation. This pin is the error amplifier output pin.

Pin No.	Pin Name	Pin Function
24	FBA	Negative input of the error amplifier. This pin is for rail A VR output voltage feedback to controller.
25	ISENA6N	Negative input of current-sense amplifier of phase 6 of rail A.
26	ISENA6P	Positive input of current-sense amplifier of phase 6 of rail A. Connect this pin to 5V can disable phase 6 of rail A.
27	ISENA8N	Negative input of current-sense amplifier of phase 8 of rail A.
28	ISENA8P	Positive input of current-sense amplifier of phase 8 of rail A. Connect this pin to 5V can disable phase 8 of rail A.
29	ISENA4N	Negative input of current-sense amplifier of phase 4 of rail A.
30	ISENA4P	Positive input of current-sense amplifier of phase 4 of rail A. Connect this pin to 5V can disable phase 4 of rail A.
31	ISENA2N	Negative input of current-sense amplifier of phase 2 of rail A.
32	ISENA2P	Positive input of current-sense amplifier of phase 2 of rail A. Connect this pin to 5V can disable phase 2 of rail A.
33	ISENA1N	Negative input of current-sense amplifier of phase 1 of rail A.
34	ISENA1P	Positive input of current-sense amplifier of phase 1 of rail A. Connect this pin to 5V can disable rail A.
35	ISENA3N	Negative input of current-sense amplifier of phase 3 of rail A.
36	ISENA3P	Positive input of current-sense amplifier of phase 3 of rail A. Connect this pin to 5V can disable phase 3 of rail A.
37	ISENA5N	Negative input of current-sense amplifier of phase 5 of rail A.
38	ISENA5P	Positive input of current-sense amplifier of phase 5 of rail A. Connect this pin to 5V can disable phase 5 of rail A.
39	ISENA7N	Negative input of current-sense amplifier of phase 7 of rail A.
40	ISENA7P	Positive input of current-sense amplifier of phase 7 of rail A. Connect this pin to 5V can disable phase 7 of rail A.
41	SD_GOOD	For soldering check, connect this pin to 5V and turn on the EN pin. If the soldering is good, all rails outputs are Non-zero VBOOT. For I2C address setting, connect this pin to GND with a resistor.
42	DRVEN_F	External driver mode control and the output high level is VCC. After receiving PS4 command, this pin will be in floating state. For discrete power MOSFET driver application, connecting 100-k Ω resistor to GND is required.
43	PWMA8	PWM output of phase 8 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
44	PWMA6	PWM output of phase 6 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
45	PWMA7	PWM output of phase 7 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
46	PWMA5	PWM output of phase 5 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
47	PWMA3	PWM output of phase 3 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
48	PWMA1	PWM output of phase 1 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
49	PWMA2	PWM output of phase 2 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
50	PWMA4	PWM output of phase 4 of rail A. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.

Pin No.	Pin Name	Pin Function
51	DRVEN/DBLR_PS	The DRVEN/DBLR_PS pin can be configured as driver enable pin (DRVEN) or phase doubler power state pin (DBLR_PS) by internal NVM. As DRVEN, which is an external driver mode control when PS4 command is received, this pin will be in low state. The output high level is VCC. As DBLR_PS, which is an external driver mode control when PS4 command is received, this pin will be in high state. This pin can work with RT9637 on 1 PWM drive 2 power stage. As PS0 command is received, this pin will be in low state. As PS1 command is received, this pin will be in floating state. As PS2/3 command is received, this pin will be in high state.
52	VSENB	Rail B VR voltage sense input. This pin is connected to the terminal of rail B VR output voltage.
53	COMPB	Rail B VR compensation. This pin is an error amplifier output pin.
54	FBB	Negative input of the error amplifier. This pin is for rail B VR output voltage feedback to controller.
55	RGNDB	Return ground for rail B VR. This pin is the negative node of the differential remote voltage sense.
56	ISENBN	Negative input of current-sense amplifier of rail B.
57	ISENBP	Positive input of current-sense amplifier of rail B. Connect this pin to 5V can disable rail B.
58	NC	No internal connection. This pin is recommended to be floating.
59	PWMB	PWM output of rail B. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
60	PWMC	PWM output of rail C. The tri-state window 1.6V-2.2V/1.4V-2.1V is programmable via NVM.
61	VR_READY	VR ready indicator.
62	ISENCP	Positive input of current-sense amplifier of rail C. Connect this pin to 5V can disable rail C.
63	ISENCN	Negative input of current-sense amplifier of rail C.
64	RGNDC	Return ground for rail C VR. This pin is the negative node of the differential remote voltage sense.
65	FBC	Negative input of the error amplifier. This pin is for rail C VR output voltage feedback to controller.
66	COMPC	Rail C VR compensation. This pin is the error amplifier output pin.
67	VSENC	Rail C VR voltage sense input. This pin is connected to the terminal of rail C VR output voltage.
68	ANS_EN	Acoustic noise suppression function setting. Pull to VCC and configuration enabled, this function can be activated. This pin is not allowed to be floating.
69 (Exposed Pad)	GND	Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.

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10 Absolute Maximum Ratings

(Note 1)

- VIN/VSYS to GND ----- -0.3V to 28V
- VCC to GND ----- -0.3V to 6.5V
- VDIO, VCLK, $\overline{\text{ALERT}}$ to GND
DC----- -0.3V to 6.8V
< 10ns----- -0.45V to 7.5V
- RGND to GND ----- -0.3V to 0.3V
- Other Pins----- -0.3V to 6.8V
- Lead Temperature (Soldering, 10 sec.)----- 260°C
- Junction Temperature----- 150°C
- Storage Temperature Range----- -65°C to 150°C

11 ESD Ratings

(Note 2)

- HBM (Human Body Model) -----2kV

12 Recommended Operating Conditions

(Note 3)

- VIN/VSYS to GND ----- 4.5V to 24V
- Supply Input Voltage, VCC ----- 4.5V to 5.5V
- Junction Temperature Range ----- -40°C to 125°C

13 Thermal Information

(Note 4)

- WQFN-68L 8x8, θ_{JA} -----26.3°C/W
- WQFN-68L 8x8, $\theta_{JC(Top)}$ ----- 4.6°C/W

14 Electrical Characteristics

(VCC = 5V, typical values are referenced to T_J = 25°C, Min and Max values are referenced to T_J from -10°C to 105°C, unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Supply Input						
Controller Supply Current	I _{VCC}	VCC = 5V, EN = H, no switching	--	12	--	mA
Controller Supply Current under PS4 all call	I _{VCC_PS4}	VCC = 5V, EN = H, PS4 all call	--	85	--	μA
VR Shutdown Current	I _{SHDN}	VCC = 5V, EN = L	--	110	--	μA
Per Phase Current Sense Amplifier						
Recommended Input Voltage Range for High Accuracy	V _{IN_PCS}	Recommend Input Voltage Range for High Accuracy	-10	--	80	mV

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Current Sense Gain	GAIN_PCS		0.97	1	1.03	V/V
Current Sense Resistor	R _{INT}		--	1	--	kΩ
TON Setting Rail A						
ON-Time Setting	t _{ON}	V _{IN} = 12V, V _{ID} = 0.9V, freq. = 350kHz (K _{TONA} = 0.735)	--	214	--	ns
TON Setting Rail B/C						
ON-Time Setting	t _{ON}	V _{IN} = 12V, V _{ID} = 0.9V, freq. = 356kHz (K _{TONB} /K _{TONC} = 0.82)	--	233	--	ns
Protections						
VCC Power-ON Reset (POR)	VCC_POR_R	Rising edge	4	4.3	4.45	V
	ΔVCC_POR_F_HYS	Falling edge hysteresis	120	210	300	mV
VCC Power-ON Reset for NVM (POR_NVM)	VCC_POR_NVM_R	Rising edge	--	3.75	3.9	V
	VCC_POR_NVM_F	Falling edge	3.4	3.5	--	
Overvoltage Protection Threshold	VROVP	Respect to V _{ID} voltage V _{ID} > 1V	V _{ID} + 300	V _{ID} + 350	V _{ID} + 400	mV
	VAOVP	V _{ID} ≤ 1V	1.3	1.35	1.4	V
Soft-start Overvoltage Protection Threshold (SS-OVP)	VSS-OVP	Active while VRON recycle or PS4 exit and until PWM turn-on	2.42	2.45	2.48	V
De-bounce Time of all OVP	DT _{OVP}		--	0.5	--	μs
Undervoltage Protection Threshold (UVP)	V _{UVP}	Active while V _{ID} settle and non-DACOFF	-700	-650	-600	mV
De-bounce Time of UVP	DT _{UVP}		--	3	--	μs
EN and VR_READY						
VR Enable Threshold	V _{IH_EN}		0.7	--	--	V
VR Disable Threshold	V _{IL_ENF}		--	--	0.3	V
Leakage Current of EN	I _{LEAK_EN}		-1	--	1	μA
Output Voltage Low of VR_READY	V _{OL_VR_READY}	I _{VR_READY} = 10mA	--	--	0.13	V
Acoustic Noise Suppression (ANS)						
ANS Enable Threshold	V _{TH_H_ANS}	VCC-V _{ANS} < 0.5V, ANS is enabled	--	--	0.5	V
ANS Disable Threshold	V _{TH_L_ANS}	VCC-V _{ANS} > 1V, ANS is disabled	1	--	--	V
Serial VID and VR_HOT						
SVID VCLK/VDIO Logic High Threshold	V _{IH_SVID}		0.65	--	--	V
SVID VCLK/VDIO Logic Low Threshold	V _{IL_SVID}		--	--	0.45	V
Leakage Current of VCLK/VDIO / ALERT / VR_HOT	I _{LEAK_SVID}	V _{VDIO} = H, $\overline{\text{ALERT}}$ = H, VR_HOT = H	-1	--	1	μA

Parameter		Symbol	Test Conditions	Min	Typ	Max	Unit
Output Voltage Low of VDIO / ALERT / VR_HOT		VOL_VDIO	IVDIO = 10mA	0.04	--	0.13	V
		VOL_ALERT	I _{ALERT} = 10mA				
		VOL_VRHOT	I _{VR_HOT} = 10mA				
I ² C Interface							
SCL, SDA	Logic-High	V _{IH_I2C}		1	--	--	V
	Logic-Low	V _{IL_I2C}		--	--	0.6	
Standard/Fast Mode							
SCL Clock Rate		f _{SCL}	Standard mode	--	--	100	kHz
			Fast mode	--	--	400	
Hold Time (Repeated) Start Condition. After this Period, the First Clock Pulse is Generated		t _{HD;STA}		0.6	--	--	μs
Low Period Of the SCL Clock		t _{LOW}		1.3	--	--	μs
High Period Of the SCL Clock		t _{HIGH}		0.6	--	--	μs
Set-Up Time for a Repeated START Condition		t _{SU;STA}		0.6	--	--	μs
Data Hold Time		t _{HD;DAT}	Standard mode	0	--	--	μs
			Fast mode	0	--	0.9	
Data Set-Up Time		t _{SU;DAT}	Standard mode	250	--	--	ns
			Fast mode	100	--	--	
Set-Up Time for STOP Condition		t _{SU;STO}		0.6	--	--	μs
Bus Free Time Between a STOP and START Condition		t _{BUF}		1.3	--	--	μs
Rising Time of Both SDA and SCL Signals		t _R	Standard mode	--	--	300	ns
			Fast mode	20	--	300	
Falling Time of Both SDA and SCL signals		t _F	Standard mode	--	--	300	ns
			Fast mode	20	--	300	
SDA Output Low Sink Current		I _{OL}	SDA voltage = 0.4V	2	--	--	mA
DIMON							
Digital IMON Set		dVIMONA_ICC _{MAX}	V _{IMONA} – V _{VREF} = 0.4V; V _{VREF} = 0.6V	--	255	--	Decimal
		dVIMONB_ICC _{MAX}	V _{IMONB} – V _{VREF} = 0.4V; V _{VREF} F = 0.6V	--	255	--	
		dVIMONC_ICC _{MAX}	V _{IMONC} – V _{VREF} = 0.4V; V _{VREF} = 0.6V	--	255	--	
		dVIMOND_ICC _{MAX}	V _{IMOND} – V _{VREF} =1.6V; V _{VREF} = 0.6V	--	255	--	

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Thermal Monitor						
TSEN Voltage Threshold to Pull Low $\overline{VR_HOT}$ (Asserts $\overline{VR_HOT}$)	$V_{TSEN_VR_HOT_L}$	Within the range, $\overline{VR_HOT} = L$ (1% resistance tolerance is considered)	--	0.600	0.620	V
TSEN Voltage Threshold to Pull High $\overline{VR_HOT}$ (De-Asserts $\overline{VR_HOT}$)	$V_{TSEN_VR_HOT_H}$	Within the range, $\overline{VR_HOT} = H$ (1% resistance tolerance is considered)	0.608	0.628	0.649	V
TSEN Rises to Pull Low ALERT	$V_{TSEN_Status_H}$	$\overline{ALERT} = L$	0.608	0.628	0.649	V
TSEN Down to Pull Low ALERT	$V_{TSEN_Status_L}$	$\overline{ALERT} = L$	0.637	0.658	0.680	V
ITSEN						
Current Source from TSEN	ITSEN	$V_{TSEN} = 1.6V$	78.8	80	81.2	μA
PSYS						
Digital IMON Reporting Code for PMAX	DPSYS_PMAX	$V_{PSYS} = 1.6V$	--	255	--	Decimal
VSYS						
VSYS Input Voltage	V_{SYS_TH}	As $V_{IN} = 24V$, high byte	--	255	--	Decimal
		As $V_{IN} = 12V$, high byte	--	128	--	
PWM Driving Capability						
PWM Source Resistance	RPWM_SRC		--	30	--	Ω
PWM Sink Resistance	RPWM_SNK		--	10	--	Ω
PWM Output						
PWMx Output High Level		$I_{OUT} = 4mA$	$V_{CC} - 0.16$	--	--	V
PWMx Output Low Level		$I_{OUT} = 4mA$	--	--	0.08	
OSC						
Oscillator Frequency 20kHz			-5	--	5	%
VREF						
VREF Voltage	VVREF	Normal operation	0.59	0.6	0.61	V

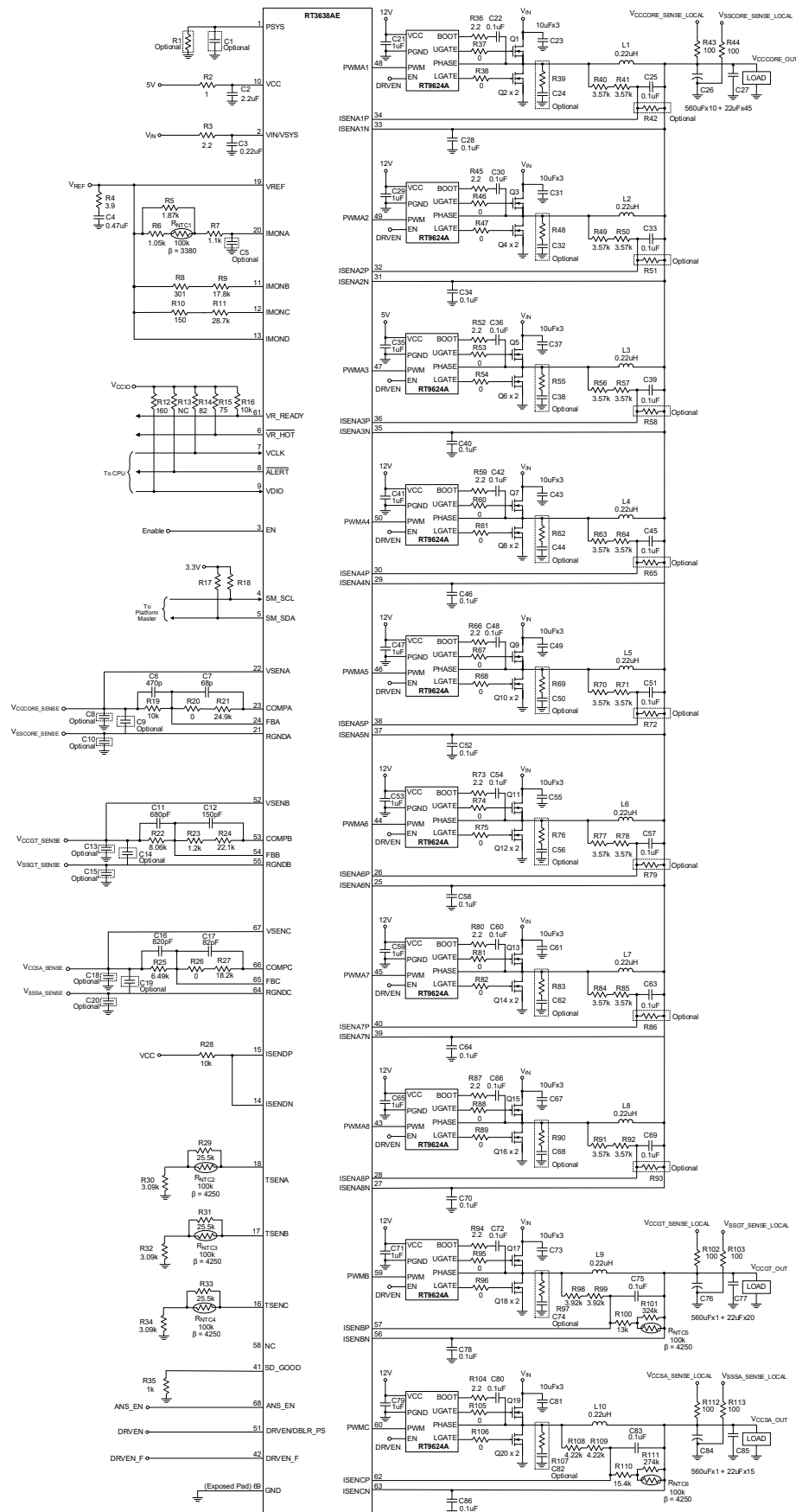
Note 1. Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

Note 2. Devices are ESD sensitive. Handling precautions are recommended.

Note 3. The device is not guaranteed to function outside its operating conditions.

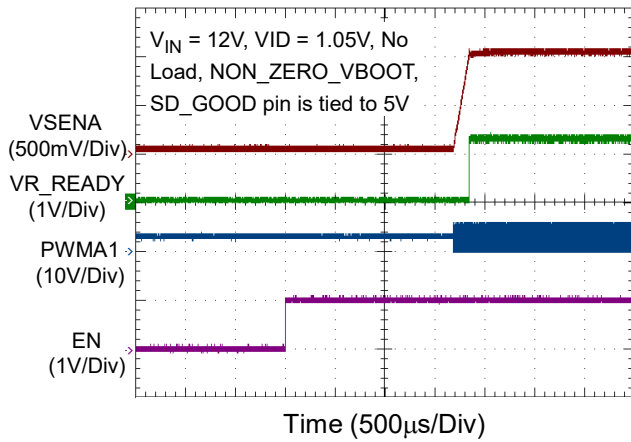
Note 4. For more information about thermal parameters, see the Application and Definition of Thermal Resistances report, [AN061](#).

15 Typical Application Circuit

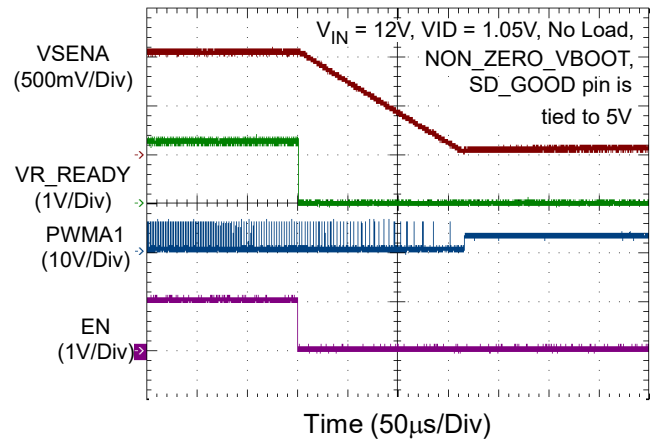


16 Typical Operating Characteristics

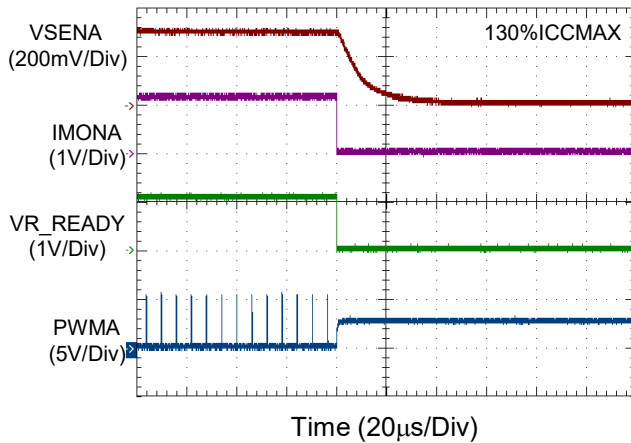
CORE VR Power On from EN



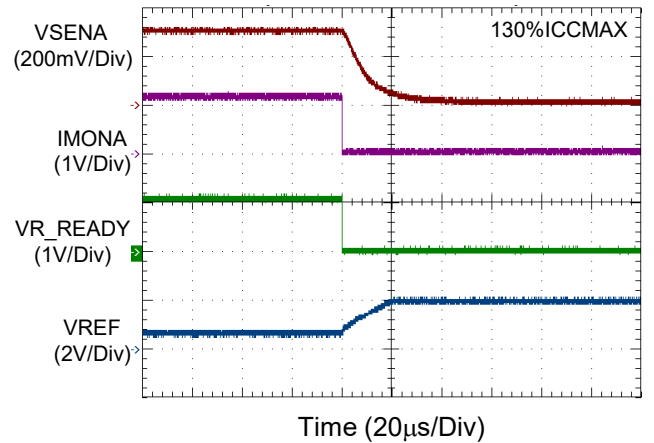
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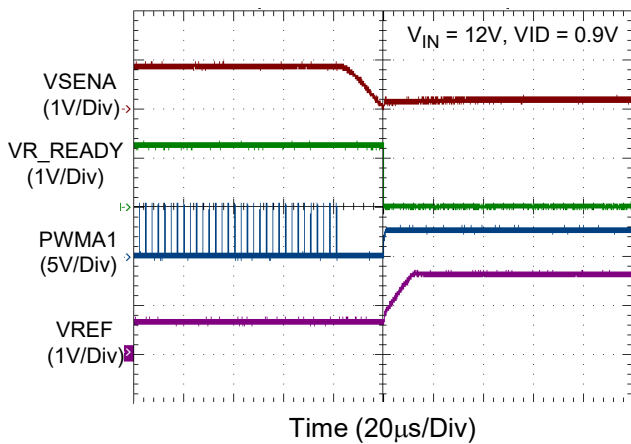
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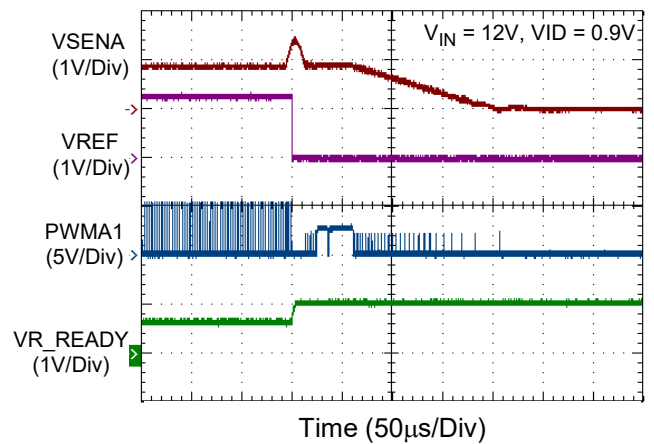
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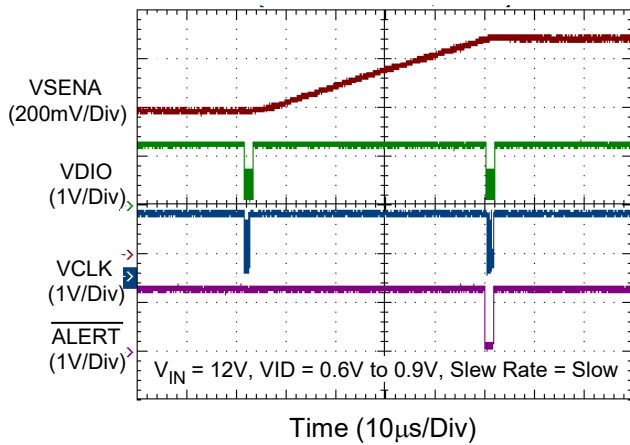
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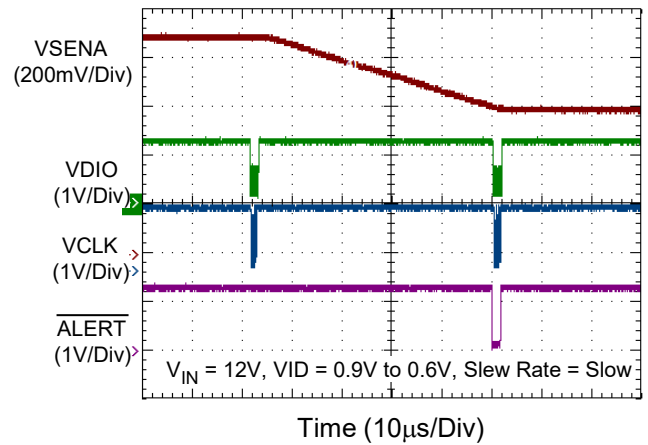
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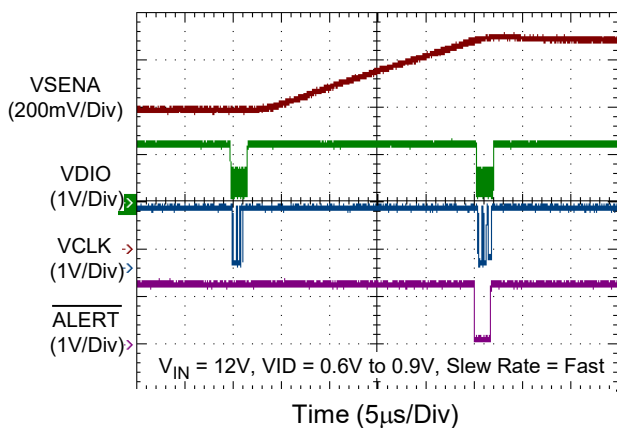
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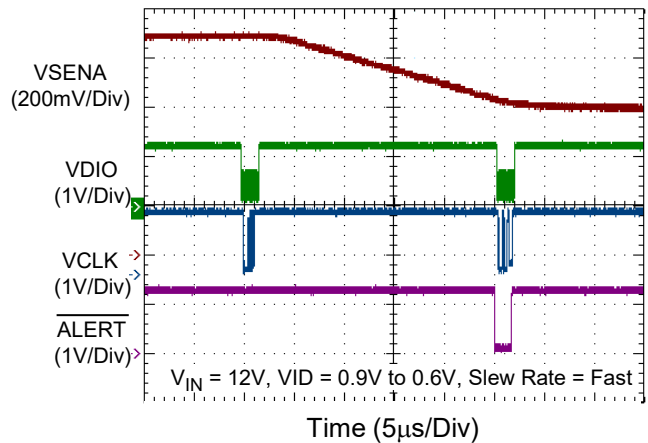
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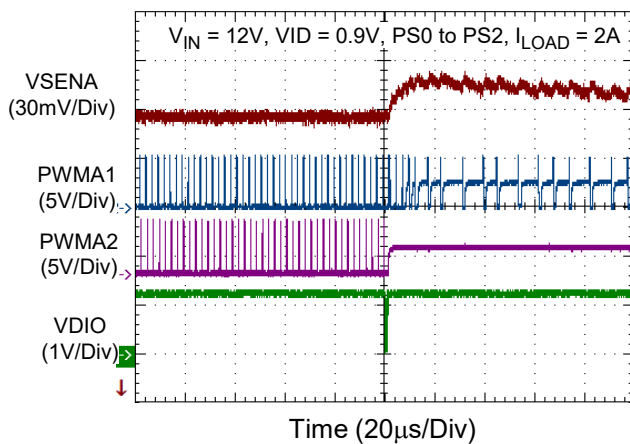
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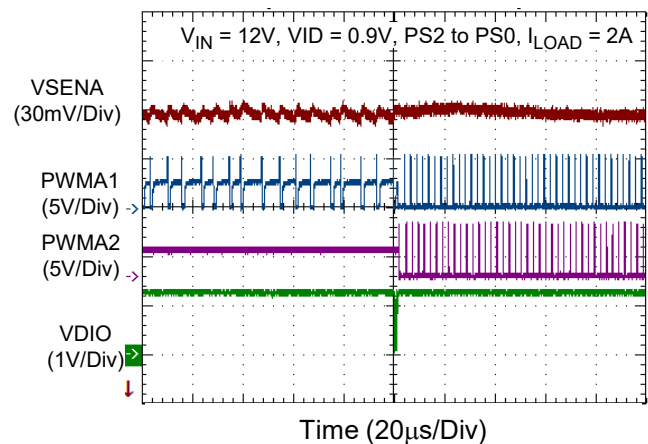
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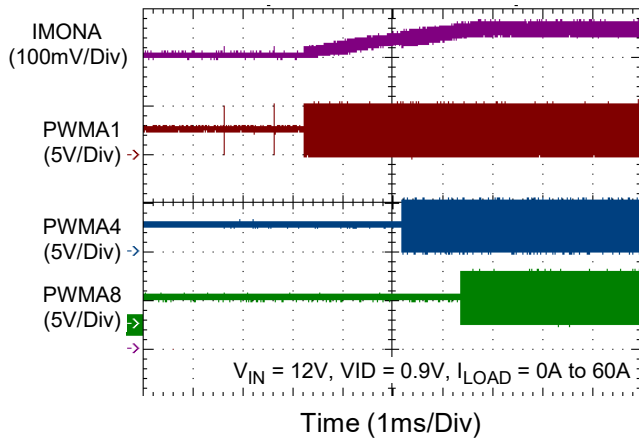
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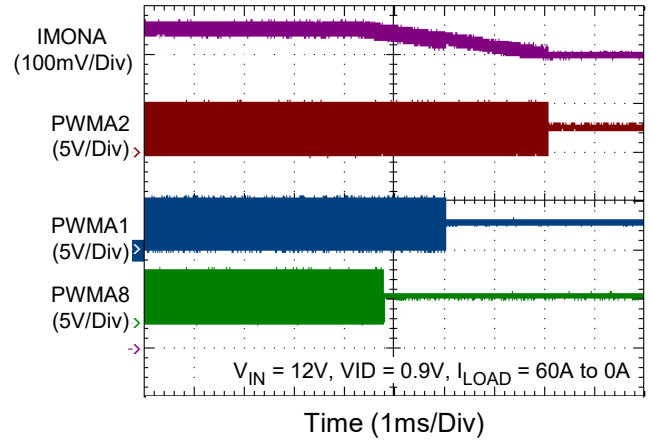
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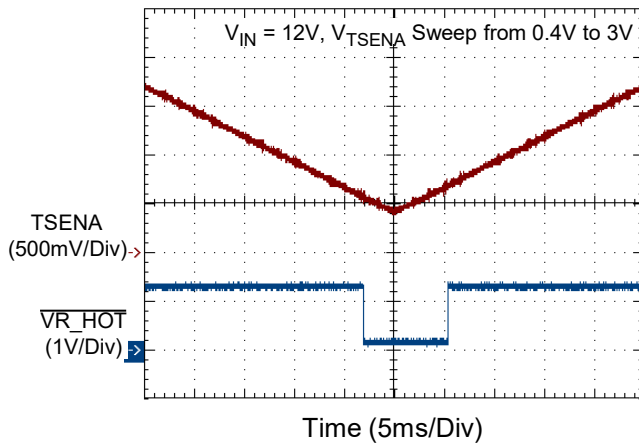
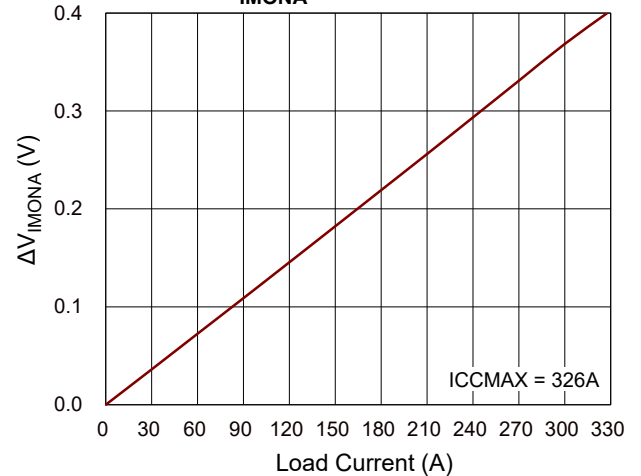
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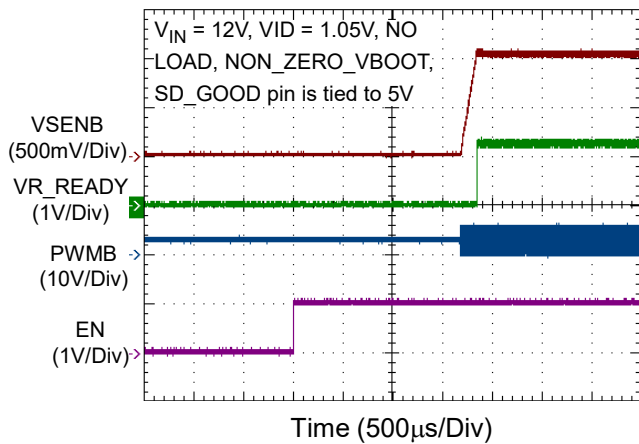
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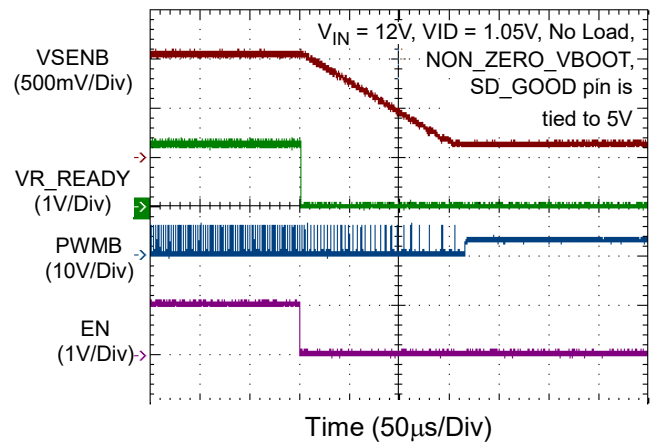
CORE VR Thermal Monitoring

 ΔV_{IMONA} vs. Load Current

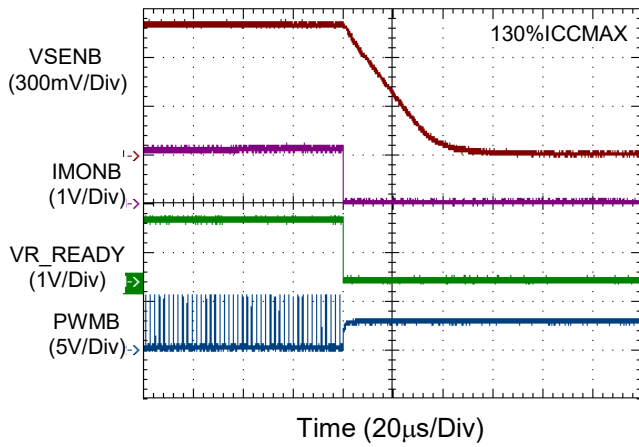
GT VR Power On from EN



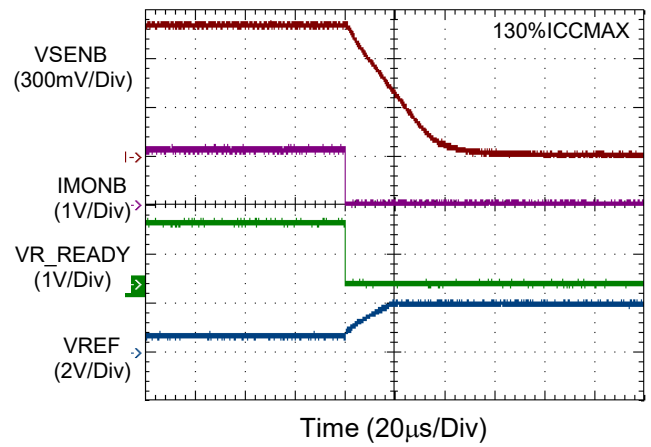
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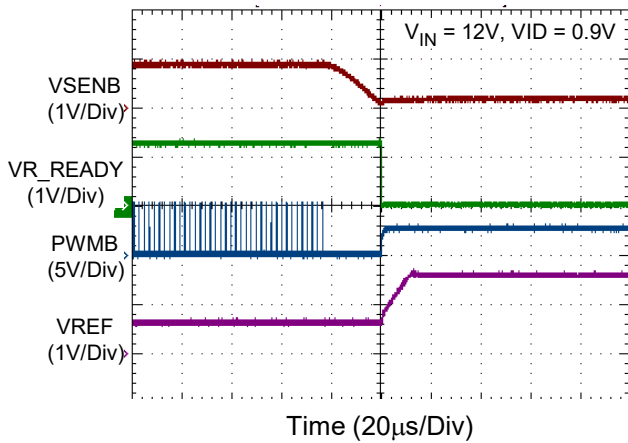
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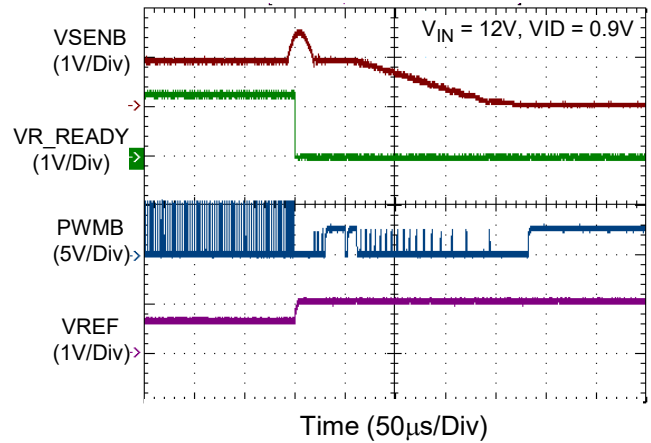
GT VR OCP



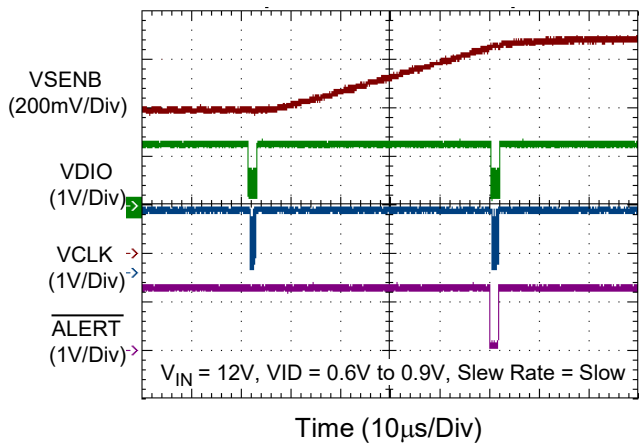
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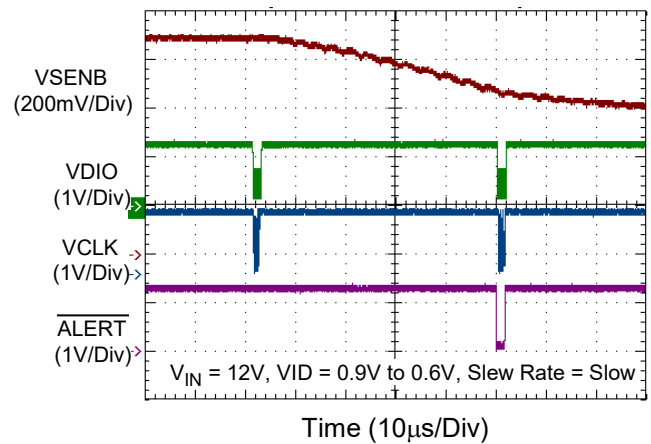
GT VR OVP



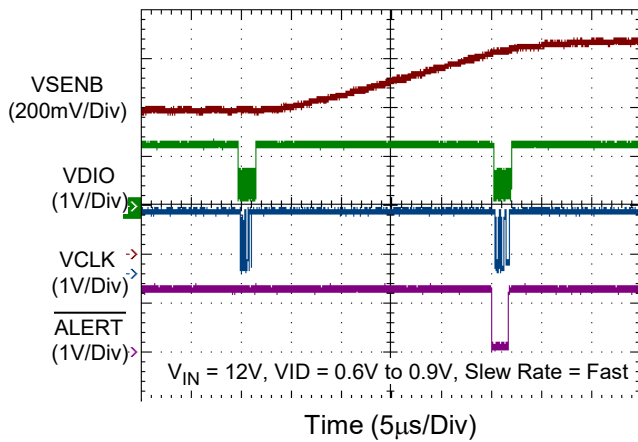
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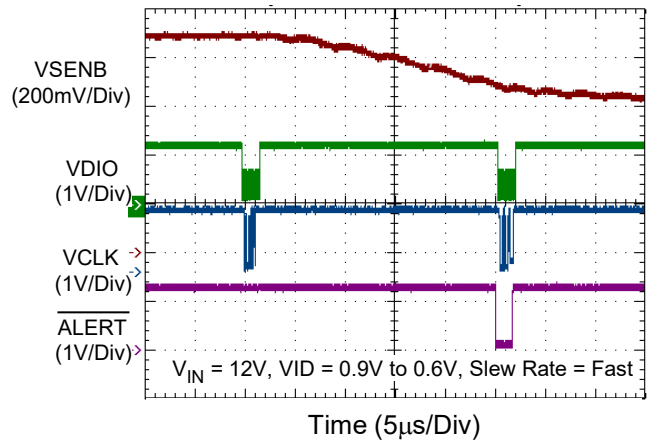
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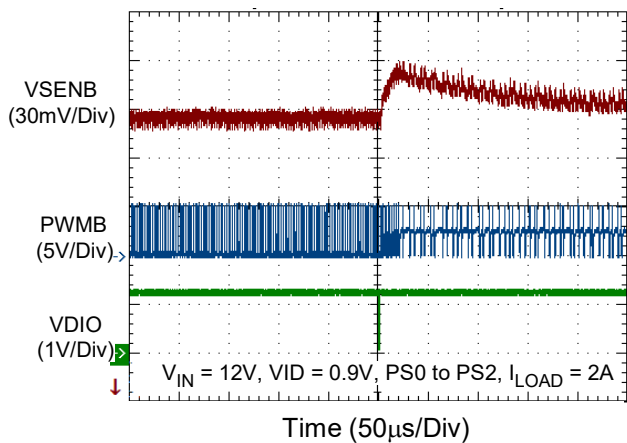
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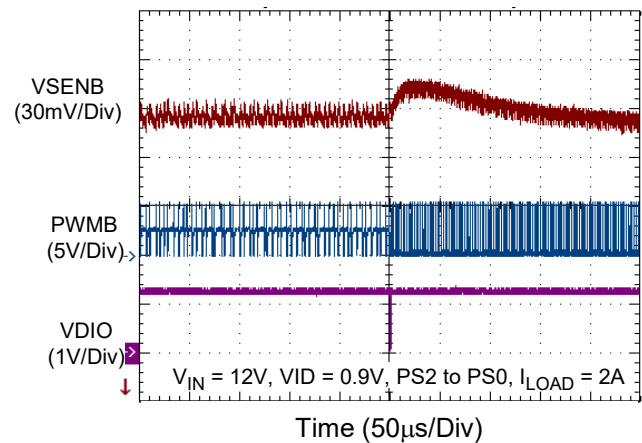
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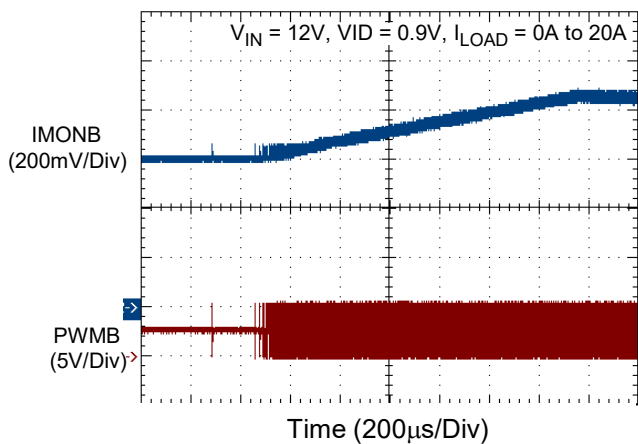
GT VR Mode Transient



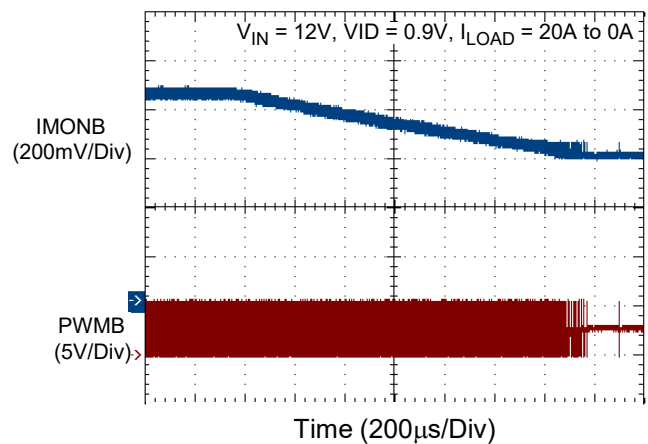
GT VR Mode Transient



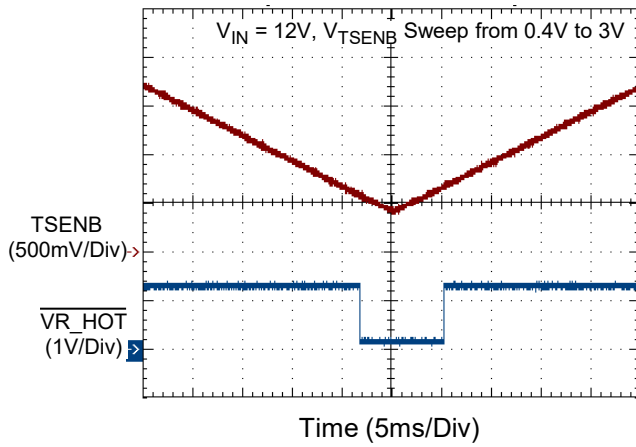
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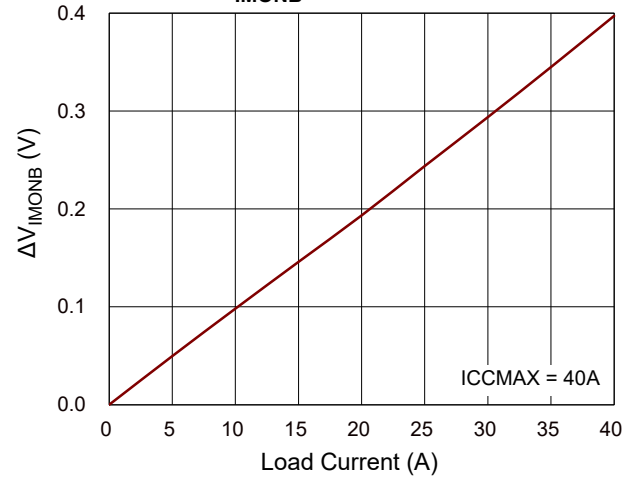
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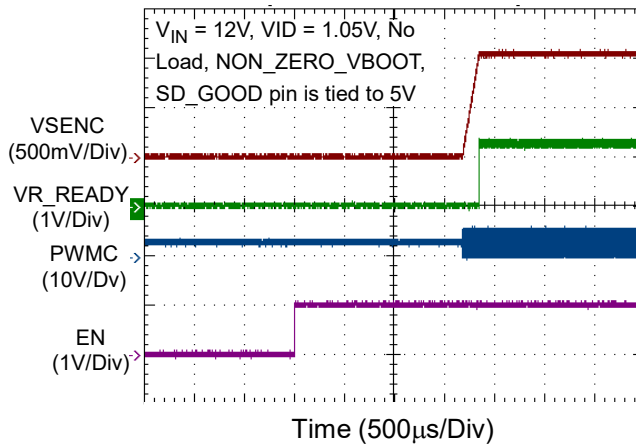
GT VR Thermal Monitoring



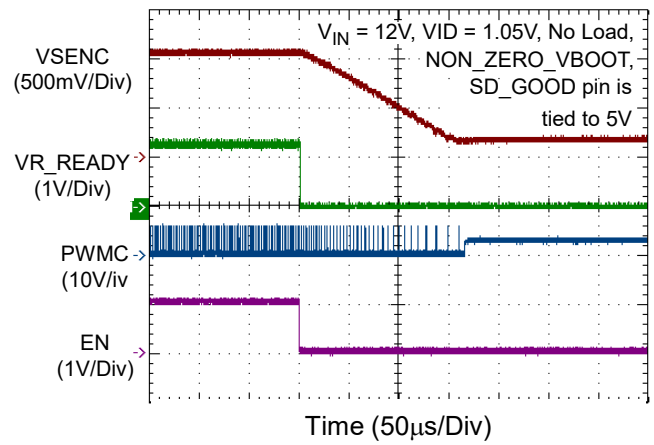
ΔV_{IMONB} vs. Load Current



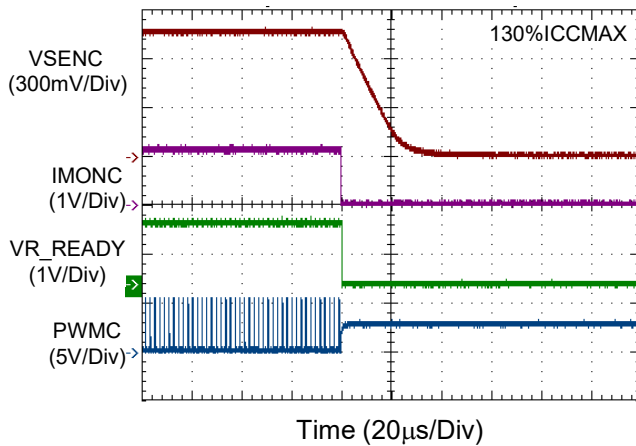
SA VR Power On from EN



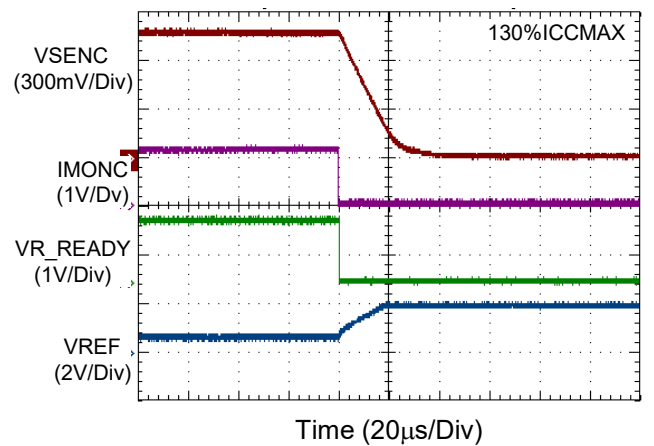
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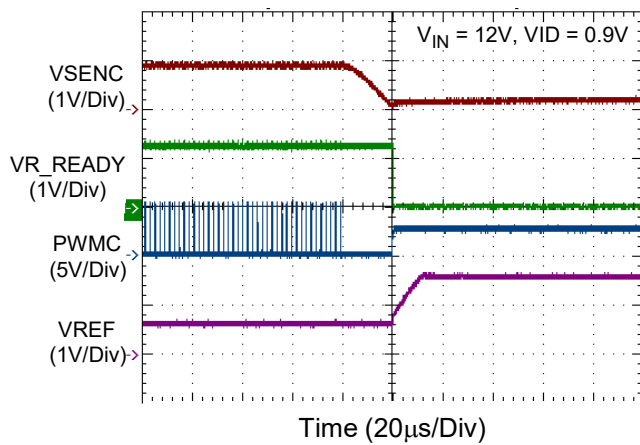
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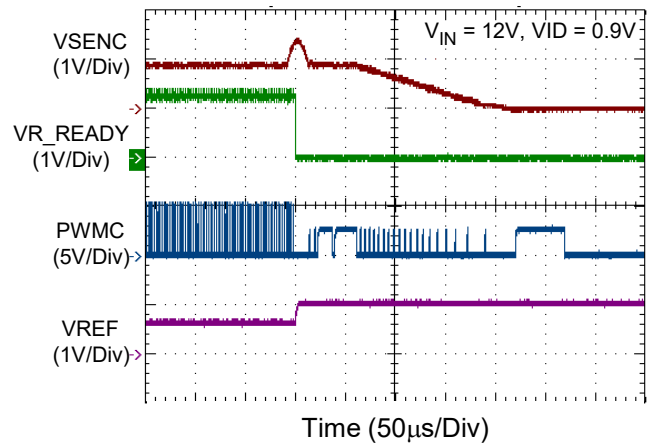
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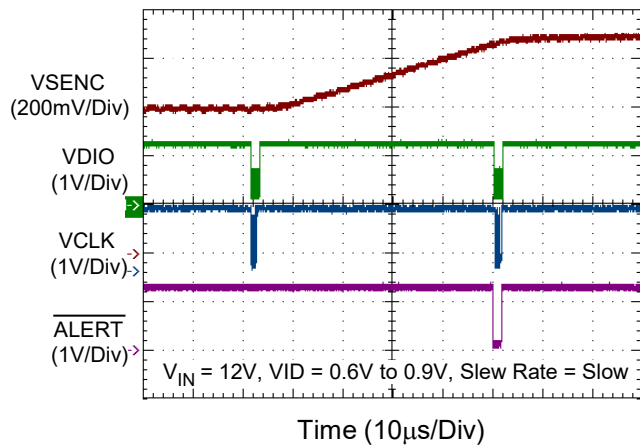
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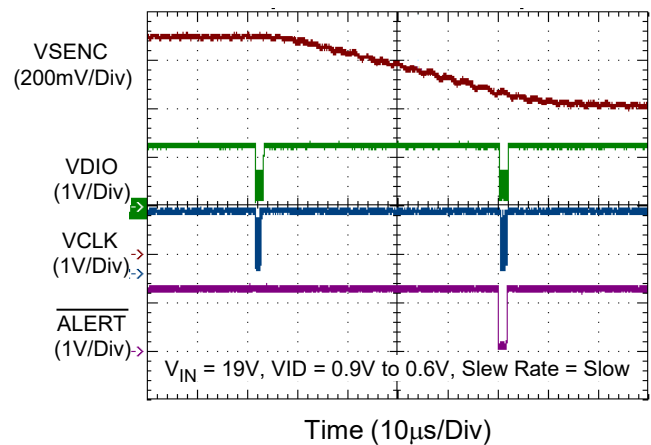
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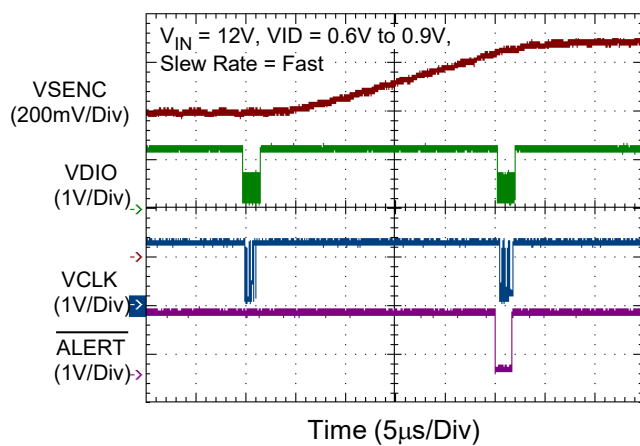
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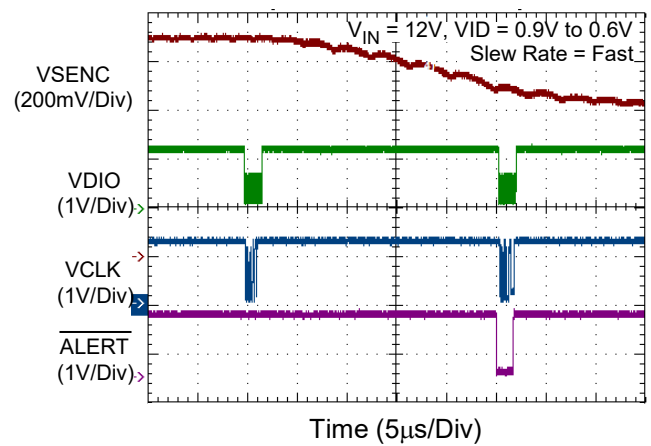
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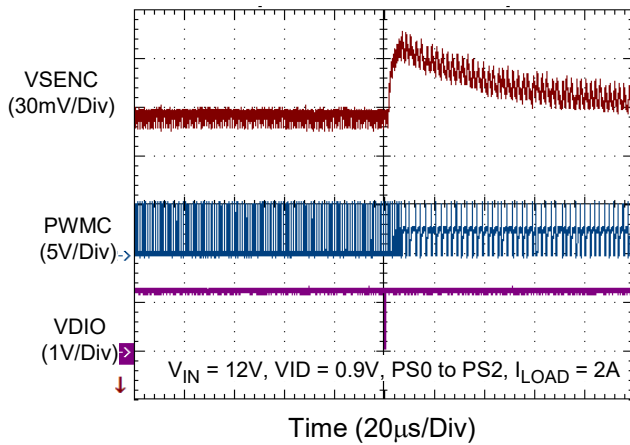
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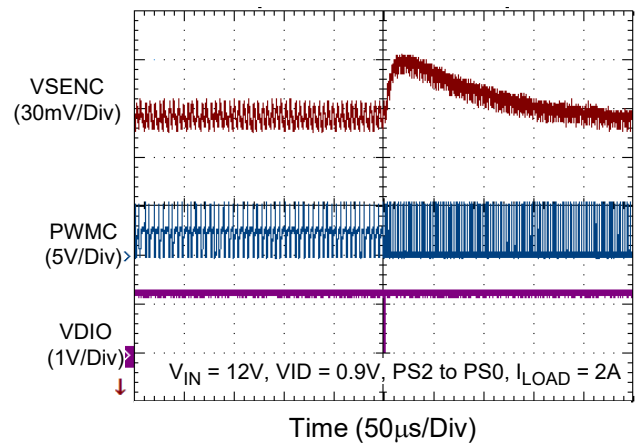
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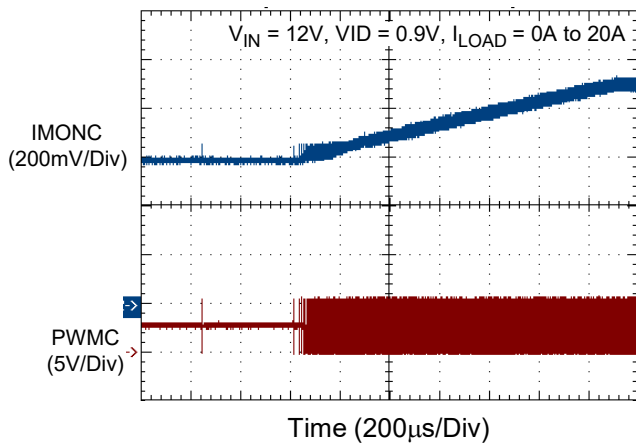
SA VR Mode Transient



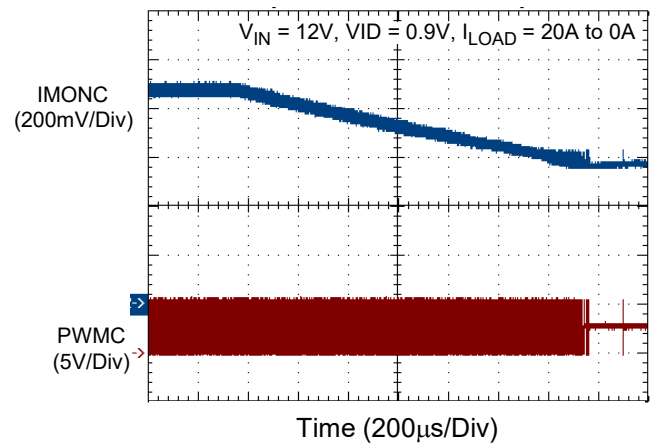
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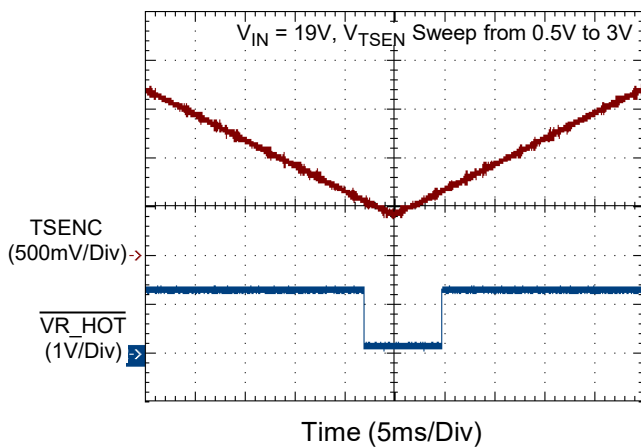
SA VR Smart Phase Management



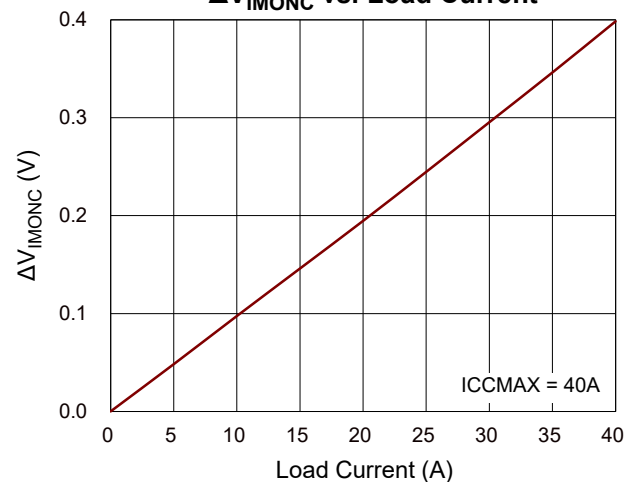
SA VR Smart Phase Management



SA VR Thermal Monitoring



ΔV_{IMONC} vs. Load Current



17 Operation

17.1 G-NAVP™ Control Mode

The RT3638AE adopts G-NAVP™ (Green Native AVP), which is Richtek's proprietary topology. It is derived from current mode constant on-time control with finite DC gain of error amplifier and DC offset cancellation. The topology can achieve easy loadline design and provide high DC accuracy and fast transient response. When sensed current signal reaches sensed voltage signal, the RT3638AE generates a PWM pulse to achieve loop modulation. Figure 1 shows the basic G-NAVP™ behavior waveforms. The COMP signal is the sensed voltage that is inverted and amplified signal of output voltage. While current loading is increasing, referring to Figure 1, COMP rises due to output voltage drop. Then, rising COMP forces PWM to turn on earlier and closer. While inductor current reaches loading current, COMP enters another steady state of higher voltage and the corresponding output voltage is in the steady state of lower voltage. The loadline, output voltage drooping by an amount proportional to loading current is achieved.

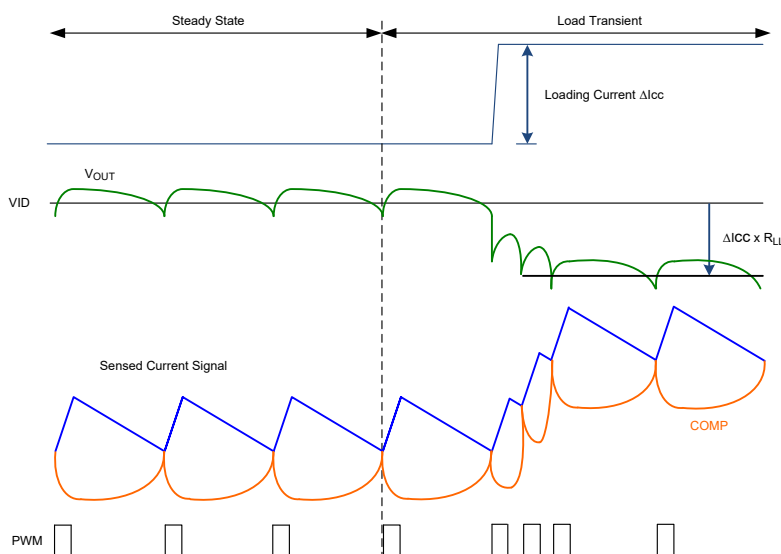


Figure 1. G-NAVP™ Behavior Waveform

17.2 SVID Interface, Control Logic and Configuration Registers

SVID Interface receives or transmits SVID signal with CPU. Control Logic executes command (Read/Write registers, SetVID, SetPS) and sends related signals to control VR. Configuration registers include function setting registers and CPU required registers.

17.3 IMON Filter

IMON Filter is used to average current signal by analog low-pass filter. It outputs IMONAVG to the MUX of ADC for current reporting.

17.4 MUX and ADC

The MUX supports the inputs for TSENA, TSENB, TSENC, PSYS, IMONAVG, IMONBAVG, IMONCAVG and IMONDAVG. The ADC converts these analog signals to digital codes for reporting or function settings.

17.5 UVLO

The UVLO detects the VCC voltage. As VCC exceeds threshold, the controller issues POR = high and waits EN. After both POR and EN are ready, the controller is enabled.

17.6 Loop Control and Protection Logic

It controls power-on/off sequence, protections, power state transition and PWM sequence.

17.7 DAC

The DAC generates a reference VID voltage according to the VID code sent by Control Logic. According to SetVID command, Control Logic dynamically changes VID voltage to target voltage with required slew rate.

17.8 ERROR AMP

The ERROR AMP inverts and amplifies the difference between output voltage and VID with externally setting finite DC gain. The output signal is COMP for PWM triggers.

17.9 PER CSGM

The PER CSGM senses per-phase inductor current. The outputs are used for loop response, Current Balance, Zero Current Detection, current reporting and overcurrent protection.

17.10 SUM CSGM

The SUM CSGM senses total inductor current with RIMON gain adjustment. SUM CSGM output current ratio can also be selected by the configuration registers. It helps wide application range of DCR and loadline. SUM CSGM output is used for PWM trigger.

17.11 RAMP

The RAMP helps loop stability and transient response.

17.12 PWM CMP

The PWM comparator compares COMP signal and sum current signal based on RAMP to trigger PWM.

17.13 Offset Cancellation

The offset cancellation is based on VID, COMP voltage and current signal from SUM CSGM to control output voltage accuracy.

17.14 Current Balance

Per-phase current sense signal is compared with sensed average current. The comparison result adjusts each phase PWM width to optimize current and thermal balance.

17.15 Zero Current Detection

Indicate when the inductor current of each phase crosses the predetermined threshold. The result is used for DEM power saving and overshoot reduction (Anti-overshoot Function).

17.16 AQR and ANTI-OVS

The AQR is a new generation of quick response mechanism (Adaptive Quick Response, AQR) which detects loading rising edge and allows all PWMs to turn on. The PWM pulse width triggered by AQR is adaptive to loading level. The AQR trigger level can be set by the configuration registers. ANTI-OVS can help overshoot reduction which detects loading falling edge and forces all PWMs in tri-state until the zero current is detected.

17.17 TONGEN and Driver Interface

The PWM comparator output signal triggers TONGEN to generate PWM pulse. The PWM sequence is controlled by Loop Control. The PWM pulse width is determined by frequency setting, current balance output and Adaptive Quick Response (AQR) settings. Once AQR is triggered, VR allows all PWMs to turn on at the same time. Driver interface provides high/low/tri-state to drive external driver. In power saving mode, Driver Interface forces PWM in tri-state to turn off high-side and low-side power MOSFETs according to Zero Current Detection output. In addition, PWM state is controlled by Protection Logic. Different protections force required PWM state.

17.18 SS-OVP OVP, UVP, SS-OCP and OCP

Soft-start overvoltage protection, overvoltage protection, undervoltage protection, soft-start overcurrent protection and overcurrent protection.

17.19 CRC Failure and Communication Failure

Cyclic redundancy check (CRC) failure and Communication failure.

18 Application Information

Richtek's component specification does not include the following information in the Application Information section. Thereby no warranty is given regarding its validity and accuracy. Customers should take responsibility to verify their own designs and reserve suitable design margin to ensure the functional suitability of their components and systems.

The RT3638AE includes three voltage rails: an 8-phase synchronous buck controller for rail A, a single-phase synchronous buck controller for rail B and a single phase synchronous buck controller for rail C. The output of each rail can be configured to support desired phase assignments up to a maximum phase count of 8 phases for rail A, single phases for rail B and single phase for rail C. For example, output operation of 8+1+1, 7+1+1, 6+1+1, etc. are supported. The RT3638AE is designed to meet Intel IMVP9.2 compatible CPUs specification with a serial SVID control interface. The controller offers built-in non-volatile memory (NVM) and I²C interface to store customized configuration. The RT3638A is used in desktop computers or notebook computers.

18.1 Power-ON Sequence

In order to confirm sufficient power supply for proper operation, the VR triggers UVLO if VCC voltage drops below $VCC_POR_R - \Delta VCC_POR_F_HYS$. The UVLO protection shuts down controller and forces high-side MOSFET and low-side MOSFET off. When $VCC > VCC_POR_R$, the RT3638AE issues POR=high and waits for EN signal. After POR = high and EN > 0.7V, the controller powers on (Chip Enable = H) and starts VR internal settings, which include internal circuit offset correction and loading the data from the NVM to the configuration registers. Users can set multi-functions through the configuration registers via I²C interface. Figure 2 shows the typical timing of controller power-on. Driver power (PVCC) is strongly suggested to be ready after controller VCC. This can prevent current flowing back to VCC from PVCC through PWMx pin or DRVEN/ DRVEN_F pin

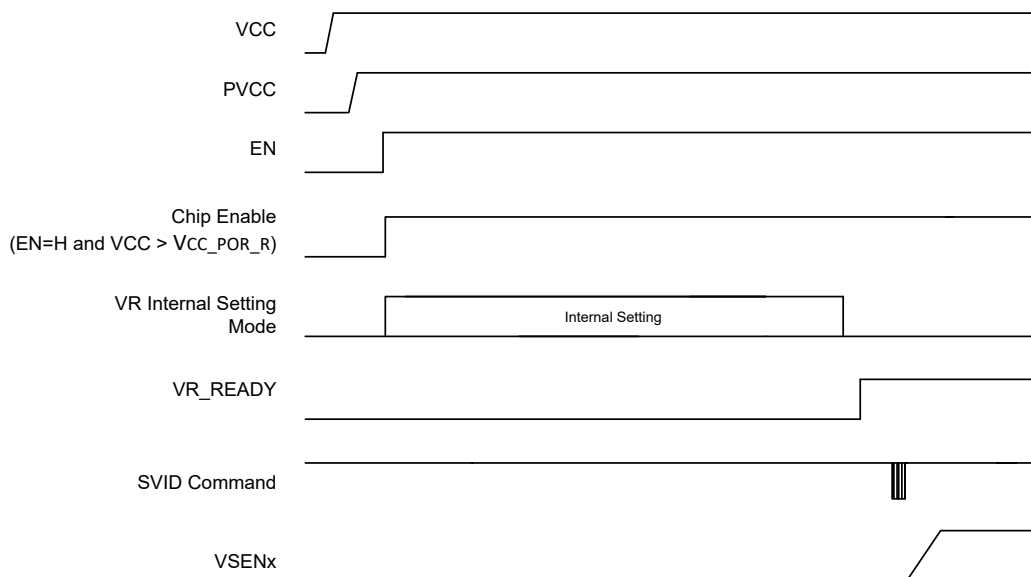


Figure 2. Typical Timing of Controller Power-ON

18.2 Maximum Active Phases Number Setting

The number of active phases is determined by the ISENxP voltage. The detection is only active and latched at Chip Enable rising edge (EN = H and VCC > 4.45V). If voltage of ISENxP > (VCC – 0.5V), maximum active phase number is (x-1). For example, connect ISENA8P to VCC for setting a 7-phase operation or connect ISEN7AP to VCC for setting a 6-phase operation. The unused ISENxN pins are recommended to be connect to VCC. For the SPS application, the unused ISENxN pins must be floating. The unused PWMx pins can be floating. Figure 3 is a 7-phase operation example.

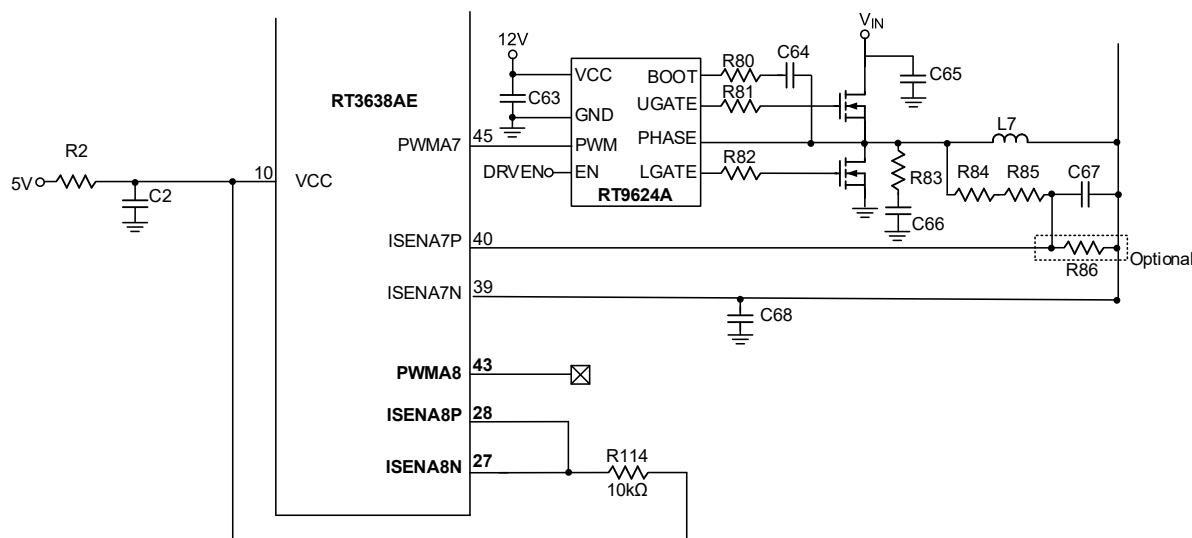


Figure 3. 7-Phases Operation Setting

18.3 Rail Disable

Connect ISENA1P to VCC for disabling rail A. The unused ISENxN pins are recommended to connect to VCC. The unused RGND pin is recommended to GND and the unused PWMx pins can be floating. Connect ISENB1P to VCC for disabling rail B. The unused ISENB1N pin is recommended to connect to VCC. The unused RGND pin is recommended to GND and the unused PWMB pin can be floating. Connect ISENC1P to VCC programs for disabling rail C. The unused ISENC1N pin is recommended to connect to VCC. The unused RGND pin is recommended to GND and the unused PWMC pin can be floating. Connect the PSYS pin to (VCC – 0.5V) for disabling input power domain rail. Hence, any commands about this rail will be rejected. The unused ISENDP pin and ISENDN pin are recommended to connect to VCC.

18.4 Acoustic Noise Suppression

The RT3638AE supports acoustic noise suppression function for reducing acoustic noise induced by piezoelectric effect from MLCC. As output voltage transition occurs, especially in dynamic VID, the vibrating MLCC produces acoustic noise if the vibrating frequency falls into audible band and the noise level is related to the output voltage transition amplitude. Therefore, the RT3638AE adopts acoustic noise suppression function which can be enabled through the configuration register via I²C to reduce ΔV when SetVID down and SetVID Decay down in DEM mode.

18.5 NVM Configuration Mechanism

The RT3638AE provides multiple parameters for platform setting and BOM optimization. These parameters can be set through the configuration registers via I²C. While POR = high and enable loading NVM command is received, VR

starts loading data from the NVM to the configuration registers and function settings. Once the loading process is done, user configuration and NVM programing are available. Keep EN = L when NVM is programing. When EN > 0.7V, VR loads the data from NVM again. After loading, VR proceeds internal setting.

Figure 4 shows the simplified VR initialization and programing timing diagram. Richtek provides a Microsoft Excel-based design tool for user configuration, including unlocking, page setting and programming, etc. All setting functions are summarized in the section of Functional Register Description. When in setting page (0xEF = 0x82), any SVID command will be rejected. The setting functions that support on-line tuning are summarized in Table 2. To change power-on default value, it still needs to enter setting page.

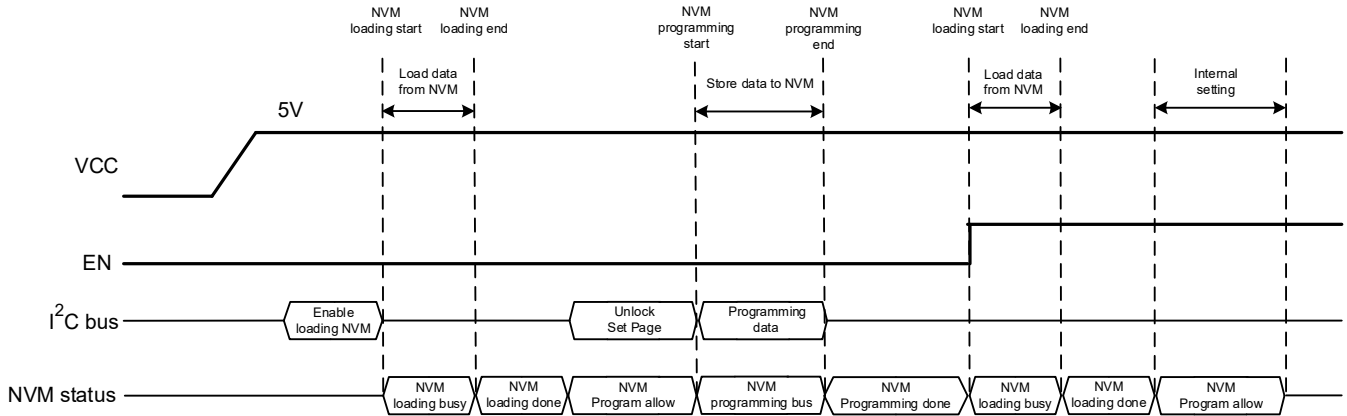


Figure 4. Simplified VR Initialization and Programing Timing Diagram

18.6 I²C Address Setting

The RT3638AE provides multiple I²C addresses to support multiple devices connected in one I²C bus. To properly set the I²C address (7-bit and 8-bit format), resistors with 1% tolerance must be connected from SD_GOOD pin to ground. The required resistance is listed in Table 1. The controller sends the first target address followed by write bit (0b). For example, the 8-bit target address combines 7-bit address and write bit (0b):

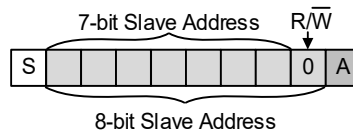


Table 1. I²C Address Setting (7-bit and 8-bit format)

I²C Address (7-bit)	I²C Address (8-bit)	Resistance (kΩ)
		Typ.
20	40	1
21	42	24.9
22	44	60.4
23	46	121

Table 2. Setting Function that Support On-line Tuning

Register Address	Function	Support On-line Tuning by General Register
0x2B[7]	SEL_SUM_OCP_DEB_TIMEA	0x98[5]
0x2F[2]	EN_SS_OCPA	0x98[4]
0x2B[6]	SEL_SUM_OCP_DEB_TIMEB	0xAF[5]
0x2F[1]	EN_SS_OCPB	0xAF[4]
0x2C[7]	SEL_SUM_OCP_DEB_TIMEC	0xBF[5]
0x2F[0]	EN_SS_OCPC	0xBF[4]
0x15[6:4]	SEL_KTONA	0x9F[2:0]
0x46[2]	EN_ANSA	0xA7[4]
0x17[3:0]	SEL_SMALL_LLA	0xA7[3:0]
0x15[2:0]	SEL_KTONB	0xB5[2:0]
0x46[1]	EN_ANSB	0xB6[4]
0x18[7:4]	SEL_SMALL_LLBB	0xB6[3:0]
0x16[6:4]	SEL_KTONC	0xC5[2:0]
0x46[0]	EN_ANSC	0xC6[4]
0x18[3:0]	SEL_SMALL_LLC	0xC6[3:0]
0x1B[7]	SEL_ANS_BEHAV	0xCC[3]

18.7 Thermal Monitoring and Indicator

Thermal monitoring is processed by TSENx pin. Block diagram of thermal monitoring network is shown in Figure 5. The voltage of TSENx pin is defined as Thermal Voltage which can be calculated by the following formula. Thermal Voltage = $80\mu\text{A} \times (R1 + R2 // R_{NTC})$. Higher temperature causes lower Thermal Voltage. $R_{NTC} = 100\text{k}\Omega$ with $\beta = 4250\text{K}$ is recommended. With proper R2 network design, Thermal Voltage versus temperature can meet Table 3. Among them, 97°C and 100°C must be followed to ensure the function of thermal alert and $\overline{\text{VR_HOT}}$. For example, when Thermal Voltage is equal to 0.6V, it means the temperature reaches 100°C. $\overline{\text{VR_HOT}}$ is pulled to low accordingly. The RT3638AE is based on Thermal Voltage to report temperature zone register. The data is updated every 75μs and the averaging period is 600μs. The resistance tolerance of thermal monitoring network is recommended to be less than 1%. The NTC thermistor is recommended to be placed near the hot spot of PCB. Richtek provides a design tool for designing thermal monitoring network.

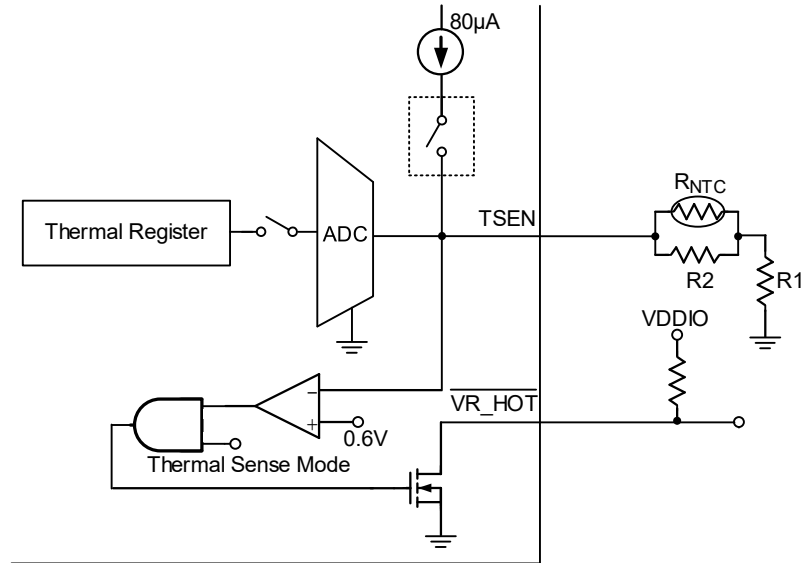


Figure 5. Thermal Monitoring Block Diagram

Table 3. Temperature zone versus Thermal Voltage and Temperature ($R_{NTC} = 100k\Omega$, $\beta = 4250K$)

Temperature Zone	Thermal Voltage	Temperature
FFh	0.600V	100°C
7Fh	0.628V	97°C
3Fh	0.658V	94°C
1Fh	0.690V	91°C
0Fh	0.725V	88°C
07h	0.761V	85°C
03h	0.800V	82°C
01h	0.900V	75°C

18.8 System Input Power Monitoring (PSYS)

The RT3638AE provides PSYS function to monitor system input power and reports to the CPU via SVID interface. The block diagram is shown as Figure 6. PSYS meter measures system input current and outputs a proportional current signal I_{PSYS} . R_{PSYS} is designed for the maximum PSYS voltage = 1.6V corresponding 100% system input power. The PSYS threshold can be set through SVID (0 to 1.6V corresponding to 00h to FFh). If input power is higher than critical threshold, controller asserts $\overline{VR_HOT}$.

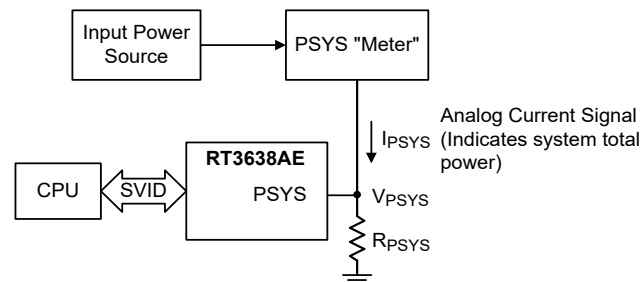


Figure 6. PSYS Function Block Diagram

18.9 System Input Voltage Monitoring (VSYS)

The RT3638AE provides optional VSYS function to monitor system input voltage. The VSYS threshold can be set through SVID (0 to 24V corresponding to 00h to FFh). If input voltage is lower than critical threshold, controller asserts $\overline{VR_HOT}$.

18.10 Zero Loadline

The RT3638AE supports zero loadline function. When zero loadline is enabled, the output voltage is determined only by VID target and does not droop along with loading current. Moreover, The RT3638AE provides AC-droop control to effectively suppress load transient ring back and reduce overshoot at zero loadline application. Figure 7 shows the load transient without AC-droop control. Without AC-droop control, extra ring back $\Delta V2$ on output voltage can be seen due to the charging of C area. Figure 8 shows the condition with AC-droop control. When output loading increases, the controller changes VID target to short-term voltage target temporarily. Short-term voltage target is related to transient loading current ΔI_{CC} and can be represented as following:

$$\text{Short_Term_Voltage_Target} = \text{VID} - \Delta I_{CC} \times \text{RLL}$$

The setting method of RLL is the same as loadline system. Then, the voltage target recovers to original VID target slowly. AC-droop control can help to decrease the peak inductor current. Hence, the ring back $\Delta V2$ can be suppressed. The overshoot amplitude is reduced to only $\Delta V3$

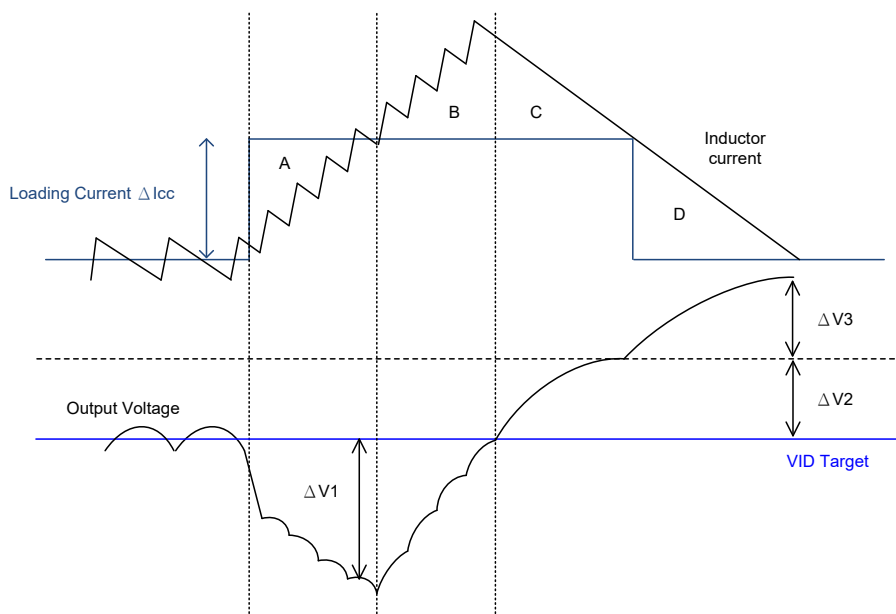


Figure 7. Zero Loadline without AC-droop Control

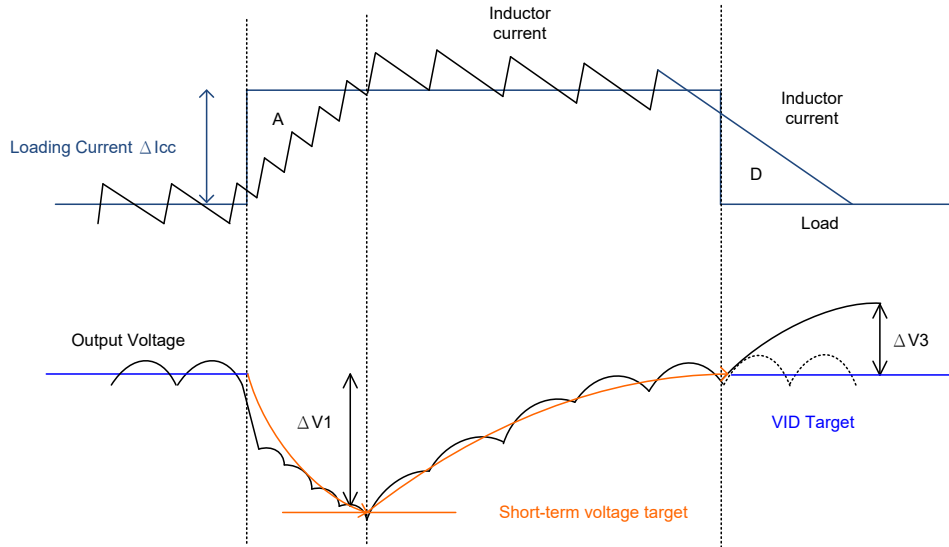


Figure 8. Zero Loadline with AC-droop Control

18.11 Current Sensing

RT3638AE supports two different current sense mechanisms, one is DCR current sensing and the other is Smart Power Stage (SPS) current sensing.

18.12 DCR Current Sense

To achieve higher efficiency, the RT3638AE adopts inductor DCR current sense to acquire per phase current signal, as illustrated in Figure 9. An external low-pass filter (Rx1, Rx2 and Cx) reconstructs the inductor current I_{Lx} . The RC time constant $(R_{x1}/R_{x2}) \times C_x$ should match inductor time constant $\frac{L_x}{DCR}$. In order to get better transient performance and current reporting, Rx1, Rx2 and Cx may need to adjust case-by-case. If the RC network time constant is equal to the inductor time constant, an ideal load transient waveform can be achieved. If the RC network time constant is larger than the inductor time constant, sluggish droop can be seen on VSEN during load transient. On the other hand, if the RC network is smaller than the inductor time constant, undesired current spike during load transient induces undershoot on VSEN. This undershoot fails the specification and may false trigger overcurrent protection (SUM-OCP). Figure 10 shows the output waveforms of these three cases RC network time constant. The Rx1 is highly recommended as two 0603 size resistors in series to enhance the IOUT reporting accuracy. The Cx is suggested to be 0.1μF X7R/0603 due to low de-rating value at high frequency. Per phase current is derived as below,

$$I_{CS,PERx} = \frac{V_{CSIN}}{R_{INT.}} = \frac{I_{Lx} \times DCR}{R_{INT.}}$$

The Rx2 is optional for preventing VCSIN exceeding input range of current sense amplifier. With Rx2, per phase current is modified as below,

$$I_{CS,PERx} = \frac{V_{CSIN}}{R_{INT.}} = \frac{I_{Lx} \times DCR}{R_{INT.}} \times \frac{R_{x2}}{R_{x1} + R_{x2}}$$

The current signal $I_{CS,PERx}$ is mirrored for loadline control, current reporting, current balance and zero current detection. The mirrored current I_{MONx} is 1.25 times of $I_{CS,PERx}$

$$(I_{MONx} = A_{MIRROR} \times I_{CS,PERx}, A_{MIRROR} = 1.25)$$

The current sense lines must be routed as differential pair from the inductor to the controller on the same layer.

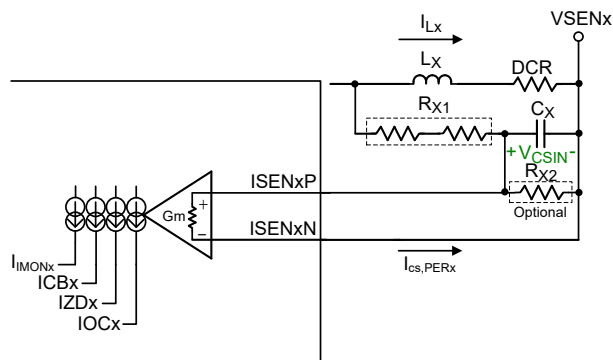


Figure 9. Inductor DCR Current Sense

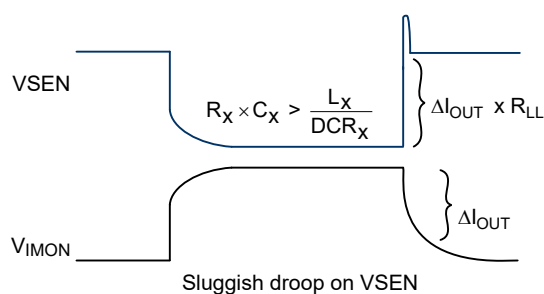
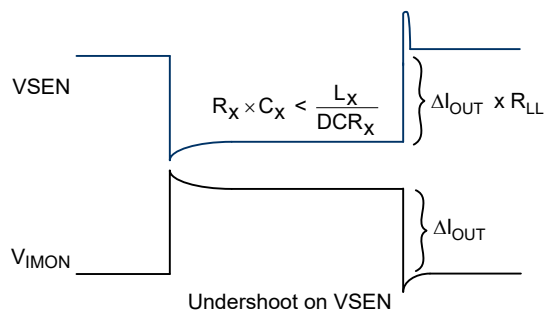
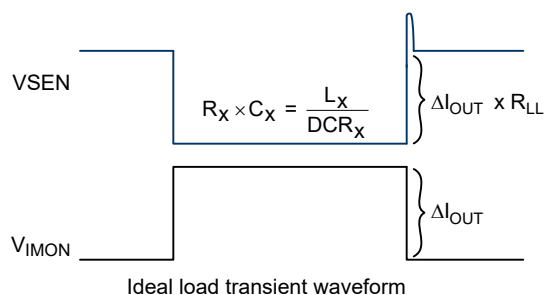


Figure 10. Three Cases of RC Network Time Constant

18.13 Total Current Sense

Total current is the sum of per phase current. With $R_{IMONx,EQ}$ network, I_{IMONx} is converted to voltage signal V_{IMONx} and offsets V_{VREF} for better accuracy. V_{VREF} is a 0.6-V voltage source from V_{REF} pin in normal operation. Figure 11 shows an 8-phase total current sense configuration. The relationship between V_{IMONx} and inductor current I_{Lx} is as below,

$$V_{IMONx} - V_{VREF} = (I_{Lx1} + I_{Lx2} + \dots + I_{Lx8}) \times \frac{DCR}{R_{INT.}} \times 1.25 \times R_{IMONx}$$

$V_{IMONx} - V_{VREF}$ is proportional to output current and is used for output current reporting, loadline loop-control and protection. For the reporting, $V_{IMONx} - V_{VREF}$ is averaged by analog low-pass filter, then sensed by an 8-bit ADC. ICCMAXx is corresponding to 0xFF. The $R_{IMONx,EQ}$ should follow dV_{IMONx_ICCMAX} to design. The RT3638AE provides customized ICCMAXx setting up to 510A. Refer to SET_ICCMAXx and SET_ICCMAX_ADDx. For loadline loop-control, $V_{IMONx} - V_{VREF}$ is scaled by Ai gain which can be selected by SEL_Ai_GAINx. The detailed application is in the section of Loadline Setting.

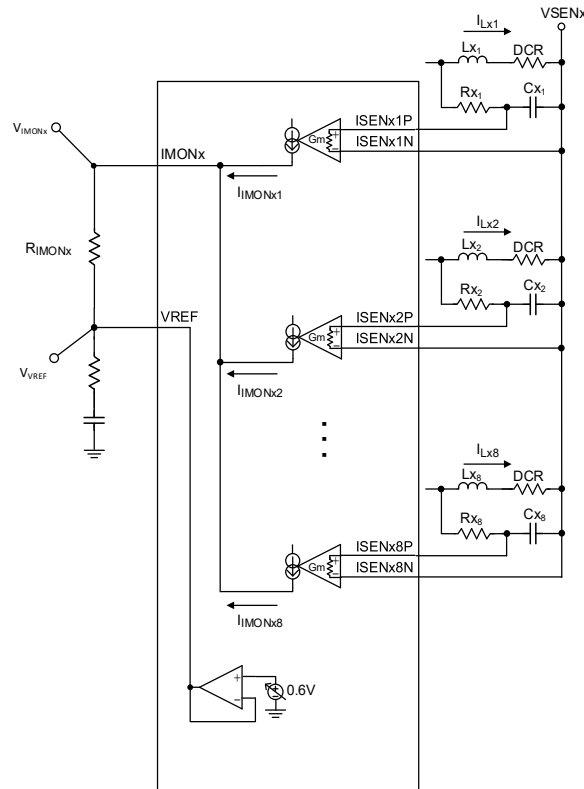


Figure 11. Total DCR Current Sense

18.14 Smart Power Stage (SPS) Current Sensing

To SPS current sensing, the setting function SEL_CS_TYPEx needs to be enabled and I_SENxN operates as the output terminals which offer the reference voltage of 1.3V for the reference inputs of SPS. A capacitor of 0.22μF to 1μF is suggested to be connected between I_SENxN to GND. Figure 12 shows the implementation of single-phase SPS current sensing report. The V_{IMON_x} and current reporting from SPS can be calculated as:

$$V_{IMONx} - V_{VREF} = I_{OUT_SPS} \times \frac{R_{SENSE}}{1k\Omega} \times 1.25 \times R_{IMONx}$$

For multi-phase consideration, the I_SENxN of each phase is suggested to be connected together. Figure 13 shows the implementation of multi-phase SPS current sensing report. The V_{IMON} and current reporting from SPS can be calculated as:

$$V_{IMONx} - V_{VREF} = (I_{OUT_SPS1} + I_{OUT_SPS2} + \dots + I_{OUT_SPS8})$$

$$\times \frac{R_{SENSE}}{1k\Omega} \times 1.25 \times R_{IMONx}$$

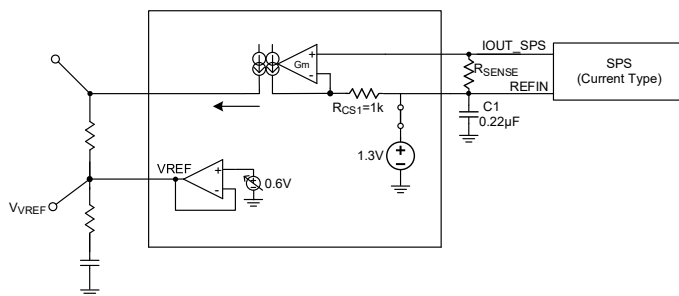


Figure 12. SPS Current Sensing

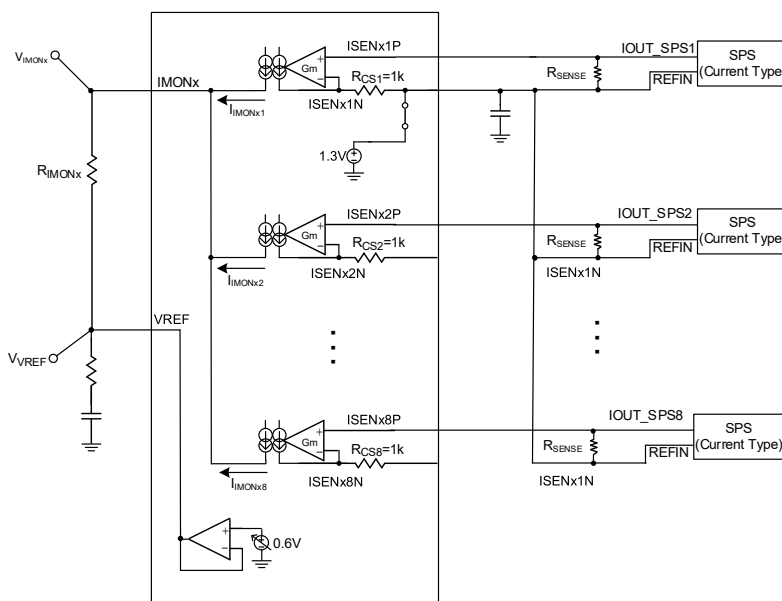


Figure 13. Total SPS Current Sensing

18.15 Thermal Compensation for Current Sense

Since the copper wire of inductor is a positive temperature coefficient component, temperature compensation is necessary for the DCR inductor current sense. For single-phase design like rail B, a simple and effective way is adopted as Figure 14. A NTC thermistor is added into the current sense network. It is suggested to be placed near the inductor of power stage to be well-compensated. Single-phase thermal compensation equation can be derived as below,

$$V_{IMONB} - V_{VREF} = I_{LB} \times \frac{DCR}{R_{INT.}} \times \frac{R_S + R_P // R_{NTC}}{R + (R_S + R_P // R_{NTC})} \times 1.25 \times R_{IMONB}$$

Refer to design tool for details and design suggestions.

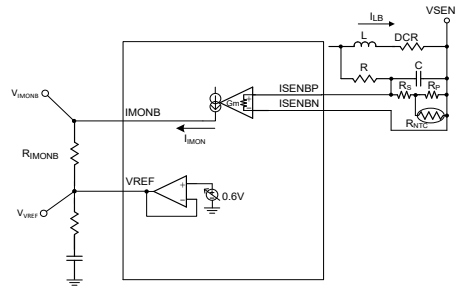


Figure 14. Single-Phase Thermal Compensation

As for multi-phase design like rail A, The RT3638AE adopts a patented total current sense method with thermal compensation as shown in Figure 15, which requires only one NTC thermistor. The NTC thermistor is combined in the network of IMONA pin. It is suggested to be put around the inductor of the first phase as close as possible. Refer to design tool for details and design suggestions. Multi-phase thermal compensation equation can be derived as below,

$$V_{IMONA} - V_{VREF} = (I_{LA1} + I_{LA2} + \dots + I_{LA8}) \times \frac{DCR}{R_{INT.}} \times 1.25 \times R_{IMON, EQA}$$

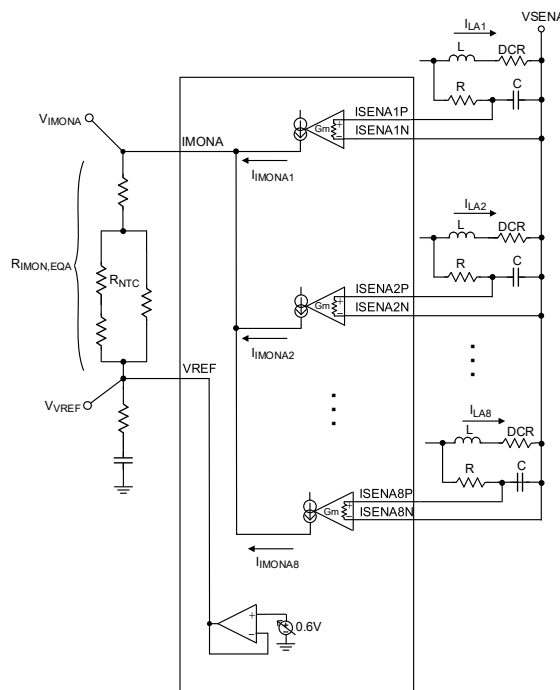


Figure 15. Multi-Phase Thermal Compensation

18.16 Loadline Setting (RLL)

Loadline is adopted in CPU VR application for power saving and output capacitance reduction. With loadline system, the output voltage decreases proportional to the increasing load current. The RLL is defined as the slope of the straight line of V-I curve as shown in Figure 16. The RT3638AE provides voltage and current loop gain for adjusting RLL. Figure 17 shows the voltage and current loop circuits. The RLL formula is described as below,

$$R_{LL} = \frac{\text{Current Loop Gain}}{\text{Voltage Loop Gain}} = \frac{DCR}{R_{INT.}} \times R_{IMON,EQ} \times \frac{A_i}{\frac{R_{EA2}}{R_{EA1}}} \times \frac{15}{4}$$

, where A_i is the current gain which can be selected by SEL_Ai_GAINx. $\frac{R_{EA2}}{R_{EA1}}$ is the ERROR AMP gain and suggested to design within 2.5 to 3.5 for better transient response. Desired RLL can be designed with proper A_i and $\frac{R_{EA2}}{R_{EA1}}$.

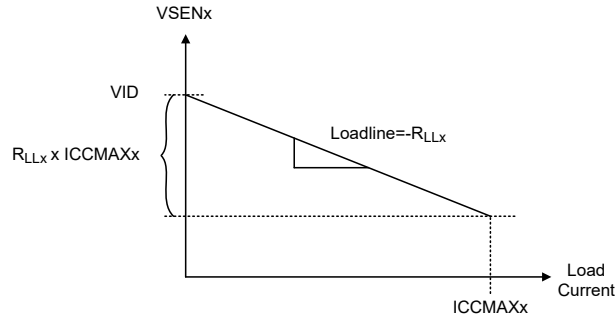


Figure 16. V-I Curve

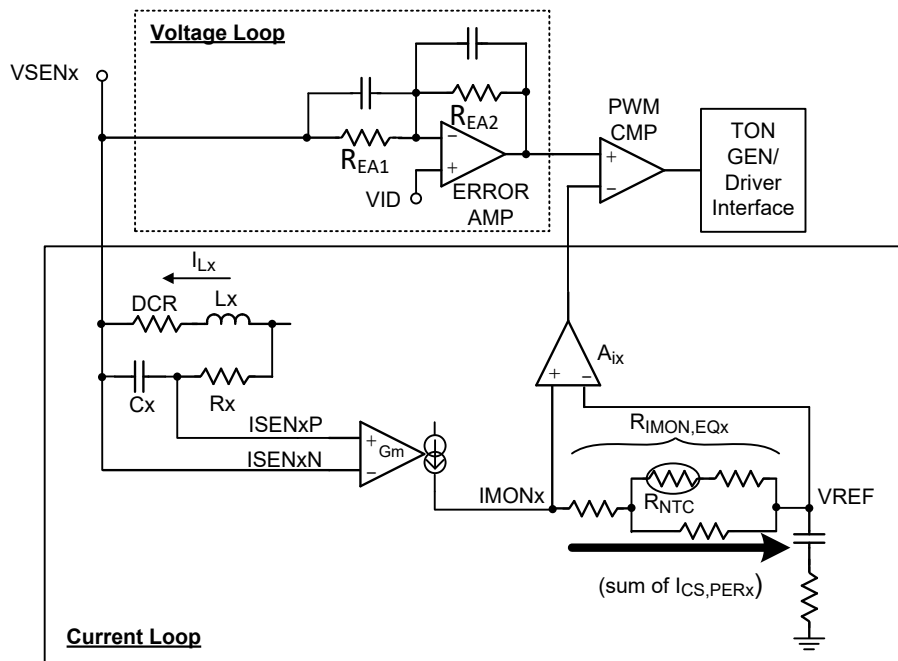


Figure 17. Voltage and Current Loop Circuit

18.17 Dynamic VID (DVID) Compensation

During DVID up or down transition, additional current is required to charge or discharge output capacitors. This charging or discharging current approximates to DVID slew rate x output capacitance. With loadline system, the additional charging or discharging current results in undesired voltage droop so that the output voltage may not get in the tolerance band within the specified time. This voltage droop or lift approximates to DVID Slew Rate x Output Capacitance x R_{LL} . This phenomenon is called droop effect. Figure 18 shows the droop effect during DVID up and down. The RT3638AE provides an internal current source of FBx pin to compensate droop effect. Compensation is equal to I_{DVID_LIFT} or I_{DVID_DROOP} times of R_{EA1} . For DVID up, the amount of I_{DVID_LIFT} can be selected by SEL_I_DVID_LIFTx. Figure 19 reveals how the DVID up compensation works. Similarly, the amount of I_{DVID_DROOP}

is also changeable via SEL_I_DVID_DROOPx for DVID down as shown in Figure 20. Compensation is also adjustable by changing REA1. When DAC settles, a recovery time is needed for inductor current settling to DC load current. Output capacitors keep charging or discharging during this period (The magnitude is related to inductor, capacitors and VID). Thus, the DVID compensation is suggested to be less than DVID slew rate x output capacitance (de-rating should be considered). However, if the output capacitance is too large to compensate, adding a resistor and capacitor in series from FBx to GND can also lead to similar effect. Moreover, the compensator, RC network of ERROR AMP, also affects the behavior of DVID. DVID compensation should be adjusted case-by-case.

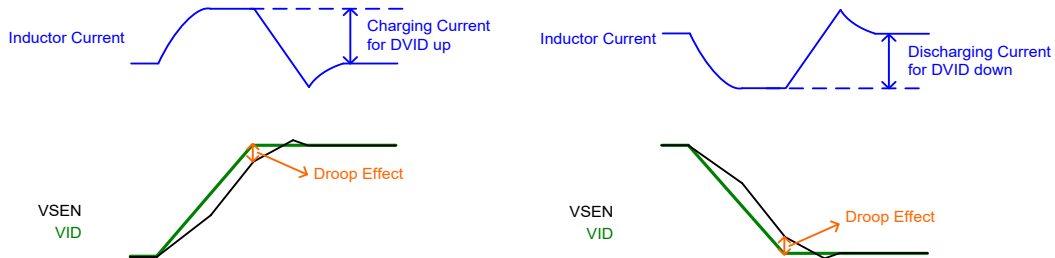


Figure 18. Droop Effect of DVID Up and Down Transition

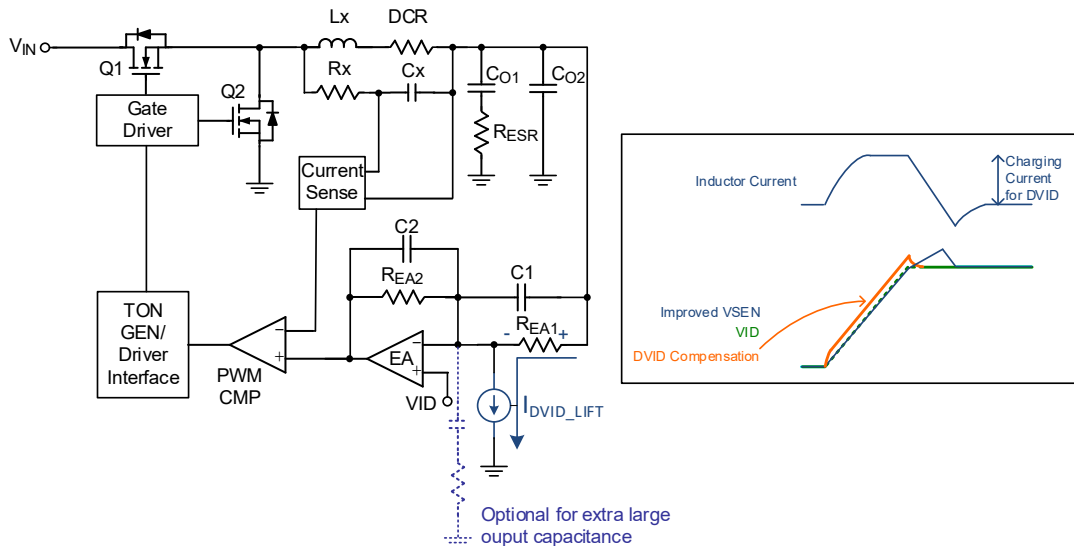


Figure 19. DVID Up Compensation

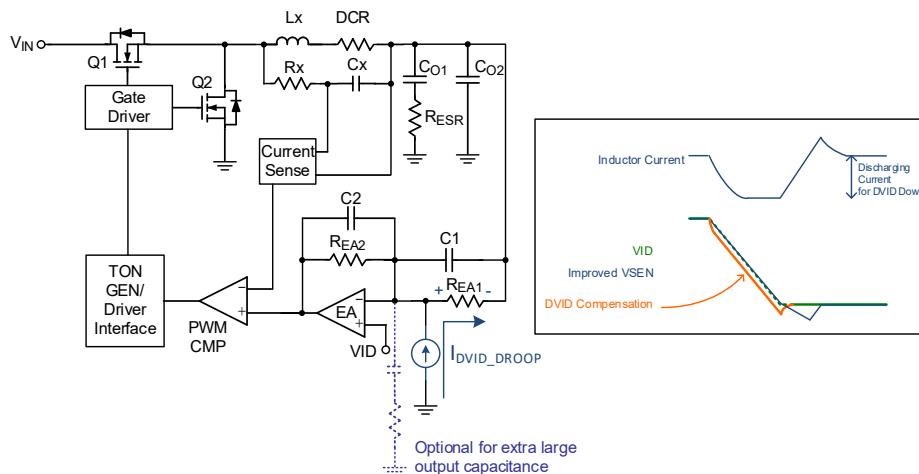


Figure 20. DVID Down Compensation

18.18 Compensator Design

Benefiting from the G-NAVP™ topology, a simple type II compensator is sufficient for The RT3638AE to meet ACLL requirement. This one-pole one-zero compensator is illustrated in Figure 21. In order to meet IMVP9.2 specifications, it is suggested to adjust the position of pole and zero based on the ring back level during load transient. Refer to design tool for compensator design.

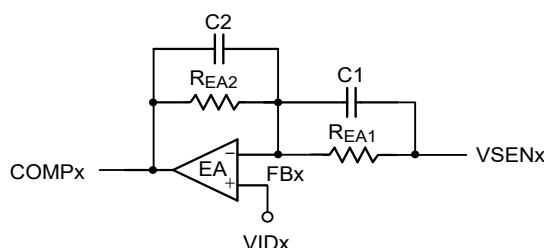


Figure 21. Type II Compensator

18.19 Differential Remote Sense

The RT3638AE provides differential remote sense to eliminate the effects of voltage drops due to the PCB traces, CPU internal power routes and socket contacts. The RT3638AE senses the on-die pins of CPU, VCC_SENSE and VSS_SENSE, to provide accurate voltage at remote CPU side. While CPU is not mounted on the system, typically two 100-Ω resistors are required to provide output voltage feedback. The circuit of remote sense is shown in Figure 22.

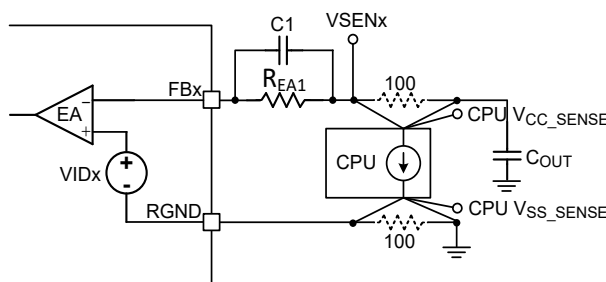


Figure 22. Remote Sense Circuit

18.20 Switching Frequency Setting

The G-NAVP™ topology is a kind of current-mode constant on-time control. It generates an adaptive TON of PWM according to input voltage VIN for better line regulation. TON is also adaptive to VID voltage to achieve constant frequency concept. The constant switching frequency operation makes the thermal estimation easier. KTON is also a factor of TON which is selectable via SEL_KTONx. The bit field definition and TON formula is listed in Table 4 and Table 5.

Table 4. TON Formula

Rail A	Rail B and C (VID Table = 5mV)	Rail B and C (VID Table = 10mV)
$VID > 0.9V,$ $t_{ON} = 2\mu \times \frac{VID}{k_{TONA} \times V_{IN}} + 10ns$	$VID > 0.9V,$ $t_{ON} = 2.206\mu \times \frac{VID}{k_{TONx} \times (V_{IN} - 0.9V)} + 15ns$	$VID > 1.8V,$ $t_{ON} = 2.206\mu \times \frac{VID}{k_{TONx} \times (V_{IN} - 1.8V)} + 15ns$
$VID \leq 0.9V,$ $t_{ON} = 2\mu \times \frac{0.9V}{k_{TONA} \times V_{IN}} + 10ns$	$0.3V < VID \leq 0.9V,$ $t_{ON} = 1.9854\mu \times \frac{1}{k_{TONx} \times (V_{IN} - VID)} + 15ns$	$0.3V < VID \leq 1.8V,$ $t_{ON} = 1.9854\mu \times \frac{2}{k_{TONx} \times (V_{IN} - VID)} + 15ns$
	$VID \leq 0.3V,$ $t_{ON} = 1.9854\mu \times \frac{1}{k_{TONx} \times (V_{IN} - 0.3V)} + 15ns$	$VID \leq 0.3V,$ $t_{ON} = 1.9854\mu \times \frac{2}{k_{TONx} \times (V_{IN} - 0.3V)} + 15ns$

Table 5. Bit Field Definition of KTONx

Field Name Bits	KTONA	KTONB and KTONC
000	0.525	0.82
001	0.630	0.91
010	0.735	1.00
011	0.840	1.09
100	0.945	1.18
101	1.050	1.27
110	1.153	1.36
111	1.260	1.55

The switching frequency can be derived from tON as below. The losses of power stage and driver are considered.

$$Freq = \frac{VID + \frac{I_{CC}}{N} \times (DCR + \frac{R_{ONLS,max}}{n_{LS}} - N \times R_{LL})}{\left[V_{IN} + \frac{I_{CC}}{N} \times \left(\frac{R_{ONLS,max}}{n_{LS}} - \frac{R_{ONHS,max}}{n_{HS}} \right) \right] \times (t_{ON} - t_D + t_{ON,VAR}) + \frac{I_{CC}}{N} \times \frac{R_{ONLS,max}}{n_{LS}} \times t_D}$$

- VID : VID voltage
 VIN : Input voltage
 Icc : Load current
 N : Phase numbers
 RONHS,max : Maximum high-side RDS,ON
 nHS : High-side MOSFET numbers
 RONLS,max : Maximum low-side RDS,ON
 nLS : Low-side MOSFET numbers
 tD : High-side MOSFET delay time plus rising time
 tON,VAR : Variation of tON
 DCR : Inductor DCR
 RLL : Loadline

18.21 Adaptive Quick Response (AQR)

The RT3638AE provides Adaptive Quick Response (AQR) for optimizing transient response. Output voltage falling slew rate is detected and compared with the AQR threshold. When the slew rate is larger than the threshold, PWM turns on to deliver more power to output portion. The PWM width is adaptive to the load step. Register SEL_MPH_AQR_THx and SEL_1PH_AQR_THx are provided to select the threshold in multi-phase and single-phase operation. Refer the following equation to set the initial AQR threshold. Note, falling slew rate at steady state and recovery of overshoot should be considered for preventing false triggering AQR.

$$\text{AQR threshold} = -4\mu\text{x} \frac{dV_{SENx}}{dt}$$

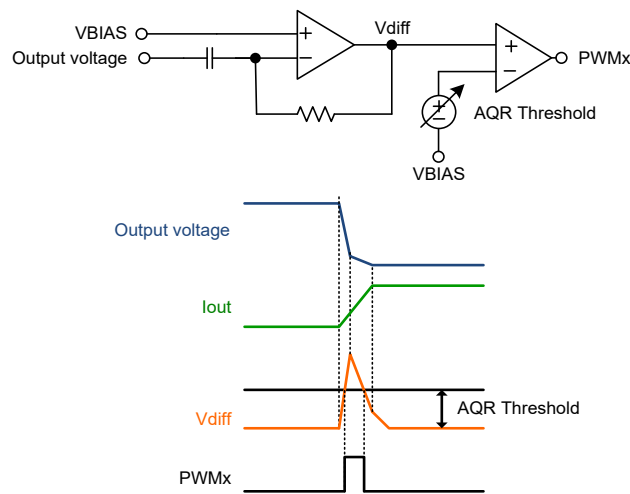


Figure 23. Adaptive Quick Response Mechanism

18.22 Anti-Overshoot (ANTI-OVS)

RT3638AE provides Anti-overshoot function (ANTI-OVS) to suppress output voltage overshoot. The variation of COMPx is used to compared with the ANTI-OVS threshold. When overshoot exceeds the threshold, all PWM enter tri-state to turn off high-side and low-side MOSFETs. Since low-side MOSFET is turned off, the continued positive inductor current flows through the body diode. The forward voltage of the body diode helps to discharge the inductor current faster and decrease the overshoot. Use register SEL_ANTI_OVS_THx to select the threshold. Note, COMPx is affected by the compensator, the final settings needs to be adjusted case-by-case.

$$\Delta \text{COMPx} \times \frac{4}{3} = \Delta V_{SENx} \times \frac{R_{EA2}}{R_{EA1}} \times \frac{4}{3} > \text{ANTI-OVS Threshold}$$

18.23 ACLL Performance Enhancement

The RT3638AE provides another function Adaptive Ramp (AR) for improving undershoot of ACLL. Two AR thresholds for multi-phase and single-phase are compared with COMPx. In multi-phase operation, when COMPx goes up and hits the threshold then triggers AR, the falling slew rate of RAMPx becomes sharper so that the next PWM is generated earlier. The operation principle is in Figure 24. In single-phase operation, when AR is triggered, an additional PWM pulse is generated directly as shown in Figure 25. Register SEL_MPH_AR_THx and SEL_1PH_AR_THx are provided for setting the threshold in multi-phase and single-phase operation. Moreover, a positive offset can be added on DAC or LPF. Refer to register 0x32 and 0x33 for detailed settings. Note, the final settings needs to be adjusted case-by-case.

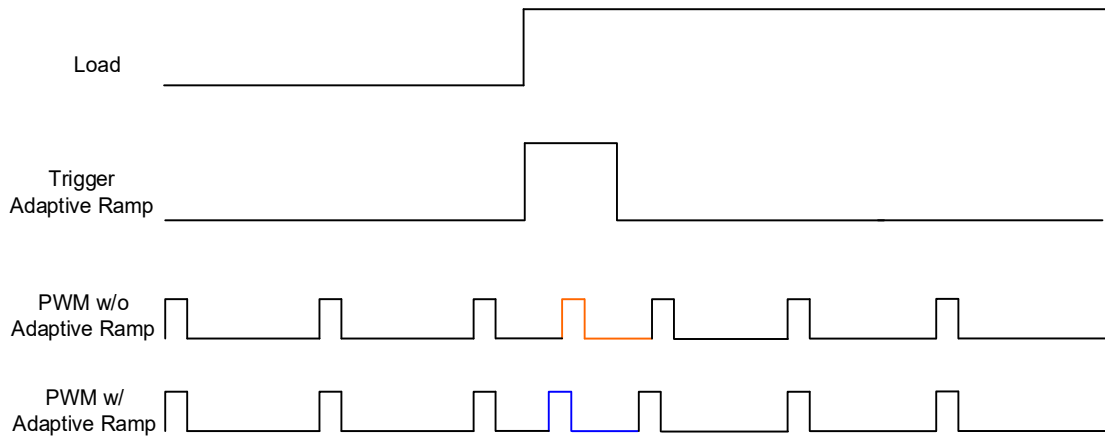


Figure 24. Adaptive Ramp Behavior in Multi-Phase Operation

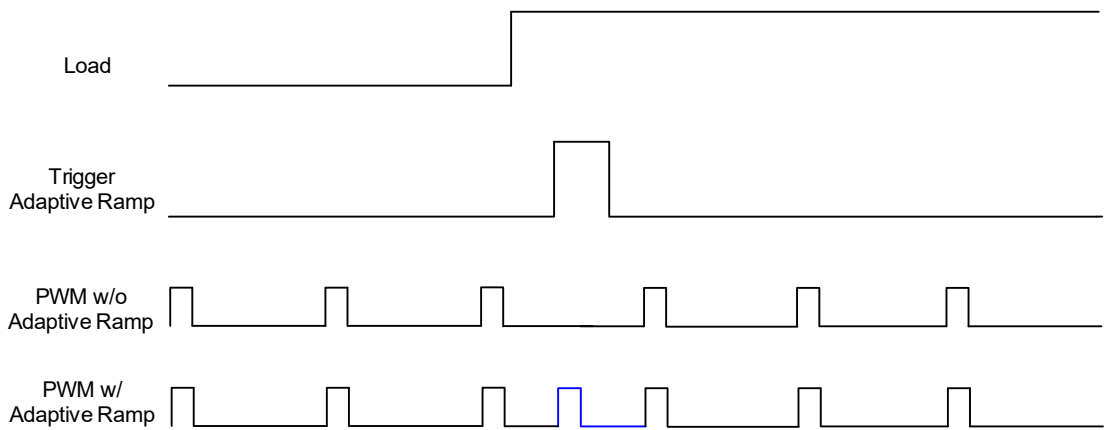


Figure 25. Adaptive Ramp Behavior in Single-Phase Operation

18.24 Current Limit

This function is for intel Fast V-Mode. When the load current exceeds the VR current threshold set in SVID register, the VR will limit the output current to the value set in SVID register and increment one count value in the SVID register. The RT3638AE supports $\overline{\text{VRHOT}}$ behavior during current Limit. It can be disabled by EN_FASTV_VRHOT_ASSERTION, and has different logic while receiving SetVID command by setting EN_FASTV_VRHOT_DEASSERTION.

18.25 Smart Phase Management (SPM)

The RT3638AE provides the Smart Phase Management (SPM) to improve light load efficiency and for the fast phase adding and phase shedding. The SPM function can be enabled and disabled via I²C register EN_SPMx. The controller compares V_{IMON} with threshold and hysteresis of SPM to decide the number of phase adding and phase shedding. The IMON pin voltage (V_{IMON}) represents the total current. The threshold and hysteresis of SPM can be adjusted through the NVM registers of SEL_SPM_THx and SEL_SPM_HYSx as shown in Figure 26. Take rail A for example, set the SEL_SPM_THA7 = 40% of ICCMAXA to drive the 8-phase operation when the V_{IMON} is higher than the 40% of ICCMAX of rail A. Moreover, the SEL_SPM_THx can be derating by SEL_SPM_TH_RATIO in setting function. The hysteresis of SPM can be adjusted through the NVM register of SEL_SPM_HYSx. For example, set

the SEL_SPM_HYSA7 = 5% of ICCMAXA with SEL_SPM_THA7 = 40% of ICCMAXA to drive the 7-phase operation when the V_{IMON} is less than the 35% of ICCMAXA (SEL_SPM_THA7 – SEL_SPM_HYSA7). Moreover, the SEL_SPM_HYSx can be extended by EN_2X_SPM_HYS in setting function. The controller enters the diode emulation mode (DEM) automatically when the inductor current is lower than the zero current detection threshold (ZCD). There is no delay time during phase adding from lower to higher phase number operation. The delay time during the phase shedding from higher to lower phase number operation can be set through the SEL_SPM_SHED_DLYx in setting function as shown in Figure 27. In addition to the output current comparison, the RT3638AE provides three events to operate in full phase immediately. One is DVID up, another is DVID down, the other is the AQR function be triggered during transient response.

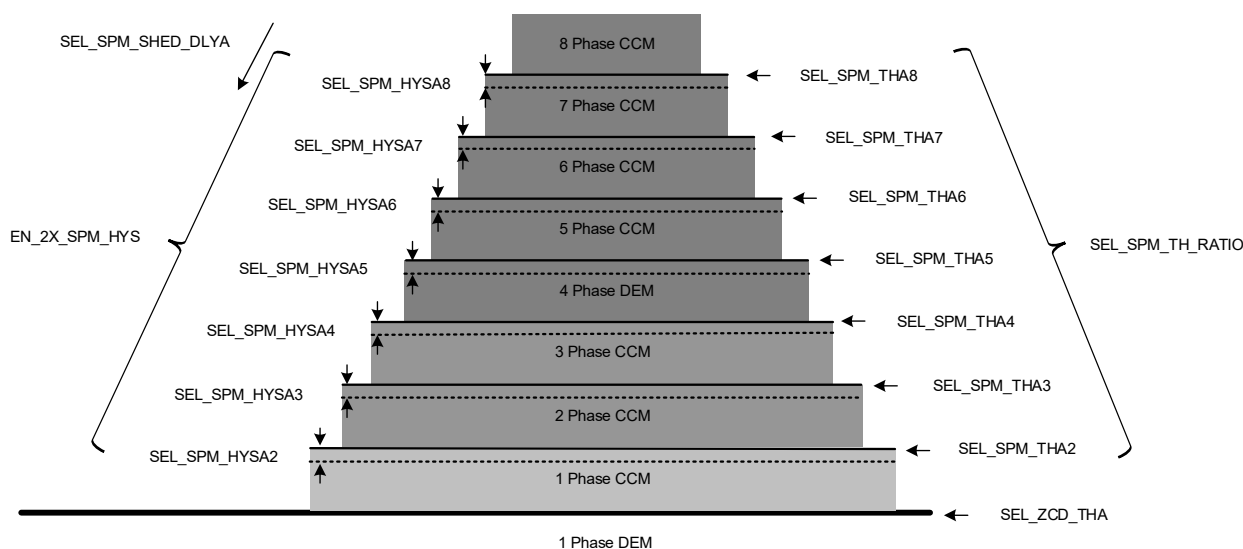


Figure 26. Smart Phase Management Rail A 8-phase Operator Phase Diagram

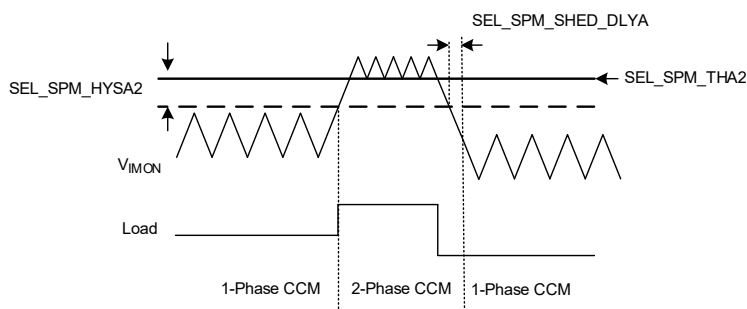


Figure 27. Smart Phase Management Up and Down Phase Diagram

18.26 Overcurrent Protection (OCP)

The RT3638AE provides two overcurrent protection mechanism for soft-start period (SS-OCP) and normal operation (SUM-OCP) for protecting the power stage. Once OCP is triggered, VR_READY is de-asserted and PWM is in tri-state to turn high-side and low-side MOSFETs off. Also, protection flag rises to 2V of VREF and asserts OCx bit in I²C command PROT_FLAGx.

SS-OCP threshold can be configured via SET_SS_OCPx. The de-bounce time of SS-OCP is around 0.5μs. The detection window of SS-OCP is soft-start period plus extra 60μs. The threshold formula is shown as below,

$$V_{IMONx} = \frac{SET_SS_OCPx}{ICCMAXx} \times dVIMONx_ICCMAX + V_{VREF}$$

Take rail A as an example, parameters are assumed as below,

ICCMAXA = 280A,

SET_SS_OCPA = 560A = 0x8C,

$$V_{IMONA} = \frac{560}{280} \times 0.4 + 0.6 = 1.4V$$

SUM-OCP threshold can be configured via SET_SUM_OCPx. The de-bounce time is also adjustable via SUM_OCP_DEB_TIMEx. SUM-OCP is masked for 80μs after settling of DVID transition. SUM-OCP behavior is depicted in Figure 28. The threshold formula is shown as below,

$$V_{IMONx} = \frac{SET_SUM_OCPx}{ICCMAXx} \times dVIMONx_ICCMAX \times \frac{\text{Current Operation Phase}}{\text{Maximum Operation Phase}} + V_{VREF}$$

Take rail A as an example, parameters are assumed as below,

ICCMAXA = 280A,

SET_SUM_OCPA = 280x1.3 = 364A = 0x5B,

Current Operation Phase = 8,

Maximum Operation Phase = 8,

$$V_{IMONA} = \frac{364}{280} \times 0.4 \times \frac{8}{8} + 0.6 = 1.12V$$

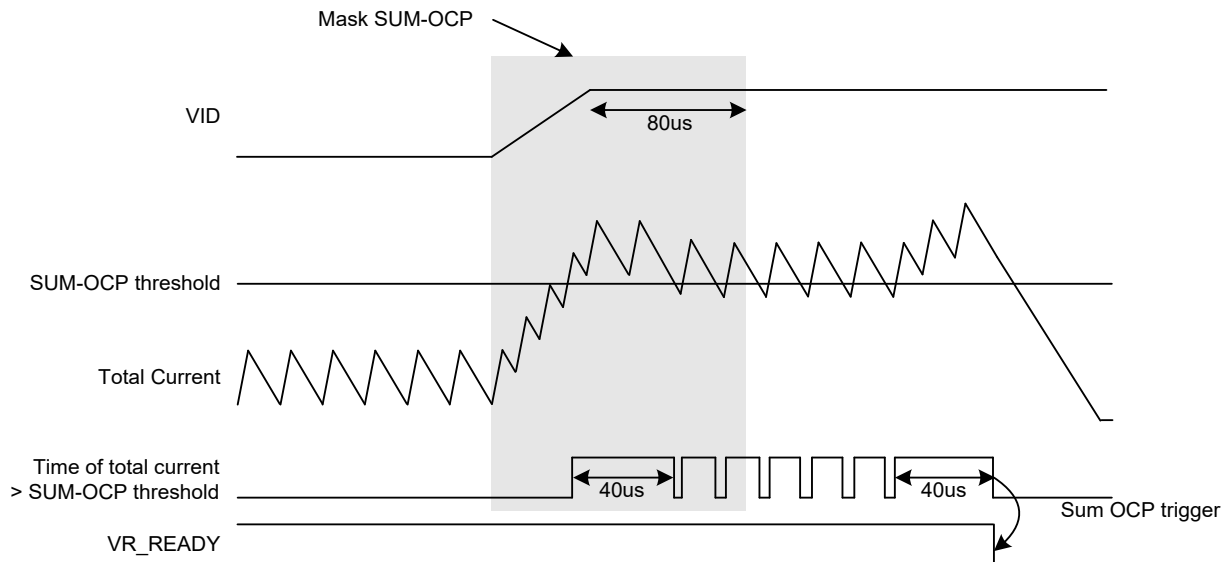


Figure 28. SUM-OCP Behavior

18.27 Undervoltage Protection (UVP)

UVP is built-in RT3638AE. The UVP threshold is set to DAC minus 650mV. De-bounce time is 3μs. When UVP is triggered, PWM is in tri-state to turn high-side and low-side MOSFETs off. Also, protection flag rises to 1.5V of VREF and asserts UVx bit in I²C command PROT_FLAGx. UVP is masked for 80μs after DVID settles. The mechanism is illustrated in Figure 29.

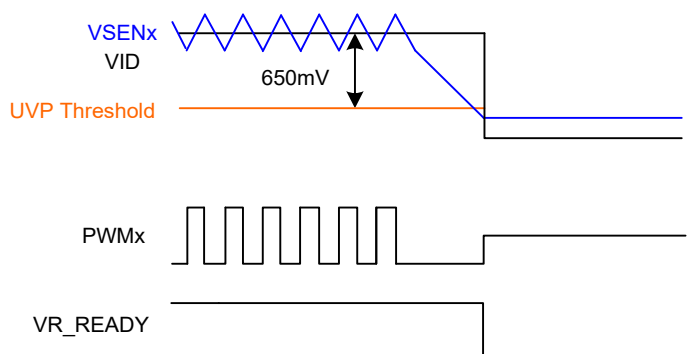


Figure 29. UVP Behavior

Table 6. Summary of OVP and UVP

Protection Type	Protection Threshold	Protection Flag	Protection Action	DVID Mask Time	Protection Reset
SS-OCP	$V_{IMONx} = \frac{SET_SS_OCPx}{ICCMAXx} \times dV_{IMONx_ICCMAX} + V_{VREF}$	$V_{VREF} = 2V$	PWM tri-state, VR_READY latched low	DVID+ 80μs	VCC/EN Toggle
SUM-OCP	$V_{IMONx} = \frac{SET_SUM_OCPx}{ICCMAXx} \times dV_{IMONx_ICCMAX} \times \frac{\text{Current Operation Phase}}{\text{Maximum Operation Phase}} + V_{VREF}$				
UVP	VID-650mV Rail A supports 650mV and 850mV UV threshold in SEL_UV_THA	$V_{VREF} = 1.5V$			

18.28 Overvoltage Protection (OVP)

The RT3638AE provides two overvoltage protection mechanisms which are absolute overvoltage protection (AOVP) for soft-start period and relative overvoltage protection (ROVP) for normal operation. The de-bounce time of OVP is around 0.5μs. Once OVP is triggered, VR_READY is de-asserted and PWM outputs low state first. When VID is below the OVP threshold minus 0.35V, PWM turns to tri-state. After 60μs since OVP is triggered, PWM outputs pulse with limited high level at tri-state level to decrease VID with slow slew rate. Also, protection flag rises to 1V of VREF and asserts OVx bit in I²C command PROT_FLAGx. OVP is masked in internal setting mode, DAC off and in PS4. The OVP summary is in Table 7.

AOVP is used to detect the soft-start period and ends at the first PWM pulse of DVID settles. AOVP threshold can be configured via SEL_SS_OVPx. The behavior is illustrated in Figure 30.

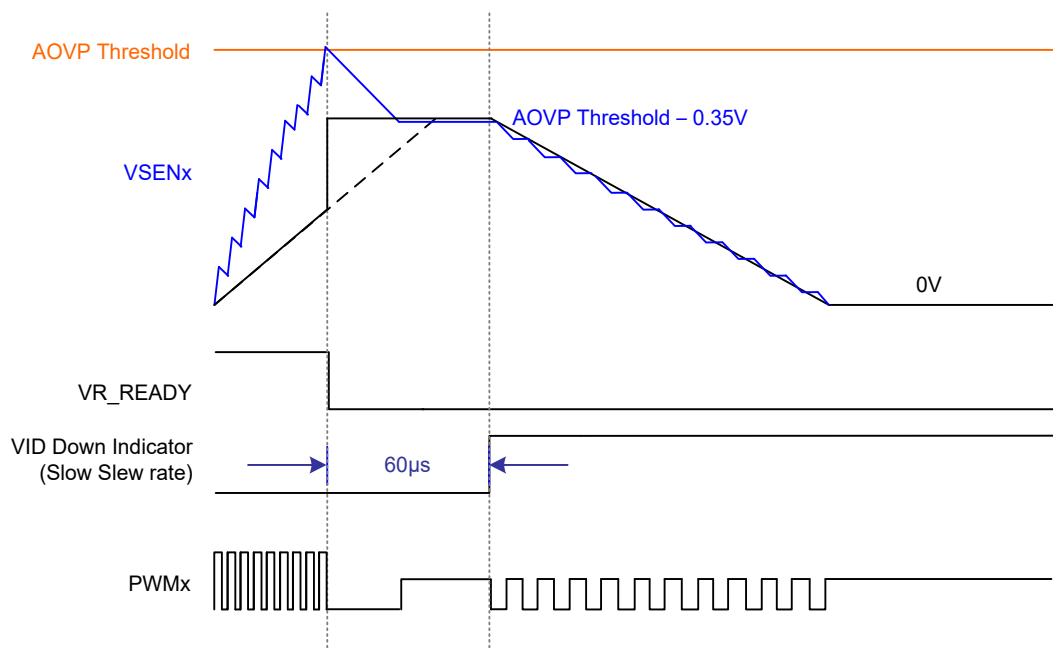


Figure 30. AOVP Behavior

ROVP is functional at normal operation. The threshold is set to DAC plus 350mV. The behavior is illustrated in Figure 31.

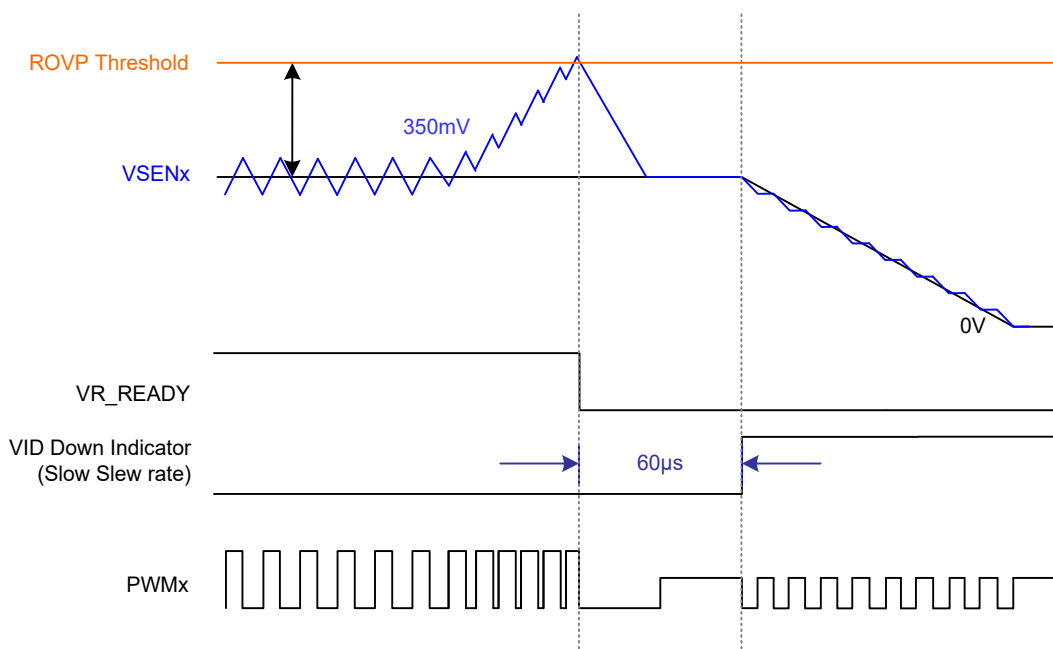


Figure 31. ROVP Behavior

Table 7. Summary of OVP

VID Condition	OVP Threshold	Example	Protection Flag	Protection Reset
VID = 0 (EN = L, internal setting mode, DAC off, PS4)	OVP is masked	NA	V _{VREF} = 1V	VCC/EN Toggling
DVID up from 0V to 1st PWM pulse of DVID settles	Set by SEL_SS_OVPx + SEL_DELTA_OVPx	SEL_SS_OVPx = 2.1V SEL_DELTA_OVPx = 350mV SS-OVP Threshold = 2.45V		
DVID period from non-zero VID (DAC ≠ 0)	DAC > 1.0V, DAC + SEL_DELTA_OVPx DAC ≤ 1.0V, 1V + SEL_DELTA_OVPx	DAC = 1.2V SEL_DELTA_OVPx = 350mV ROVP Threshold = 1.55V DAC = 0.9V SEL_DELTA_OVPx = 400mV AOVP Threshold = 1.4V		

18.29 CRC Failure

NVM loading of the RT3638AE begins after VCC crosses its rising POR_NVM threshold. The RT3638AE will download NVM into the control registers. CRC check ensures the completion of configuration download from NVM to the RT3638AE control register. A configuration download CRC failure prevents the controller from leaving the Inactive state and asserts I²C register NVM_PROGRAM_STATUS [0].

18.30 Thermal Considerations

The junction temperature should never exceed the absolute maximum junction temperature T_{J(MAX)}, listed under Absolute Maximum Ratings, to avoid permanent damage to the device. The maximum allowable power dissipation depends on the thermal resistance of the IC package, the PCB layout, the rate of surrounding airflow, and the difference between the junction and ambient temperatures. The maximum power dissipation can be calculated using the following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

where T_{J(MAX)} is the maximum junction temperature, T_A is the ambient temperature, and θ_{JA} is the junction-to-ambient thermal resistance.

For continuous operation, the maximum operating junction temperature indicated under Recommended Operating Conditions is 125°C. The junction-to-ambient thermal resistance, θ_{JA} , is highly package dependent. For a WQFN-68L 8x8 package, the thermal resistance, θ_{JA} , is 26.3°C/W on a standard JEDEC 51-7 high effective-thermal-conductivity four-layer test board. The maximum power dissipation at T_A = 25°C can be calculated as below:

$$P_{D(MAX)} = (125^\circ\text{C} - 25^\circ\text{C}) / (26.3^\circ\text{C/W}) = 3.8\text{W for a WQFN-68L 8x8 package.}$$

The maximum power dissipation depends on the operating ambient temperature for the fixed T_{J(MAX)} and the thermal resistance, θ_{JA} . The derating curves in Figure 32 allows the designer to see the effect of rising ambient temperature on the maximum power dissipation.

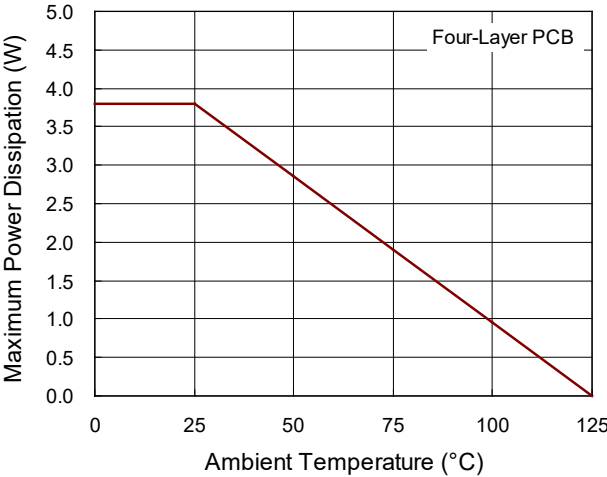


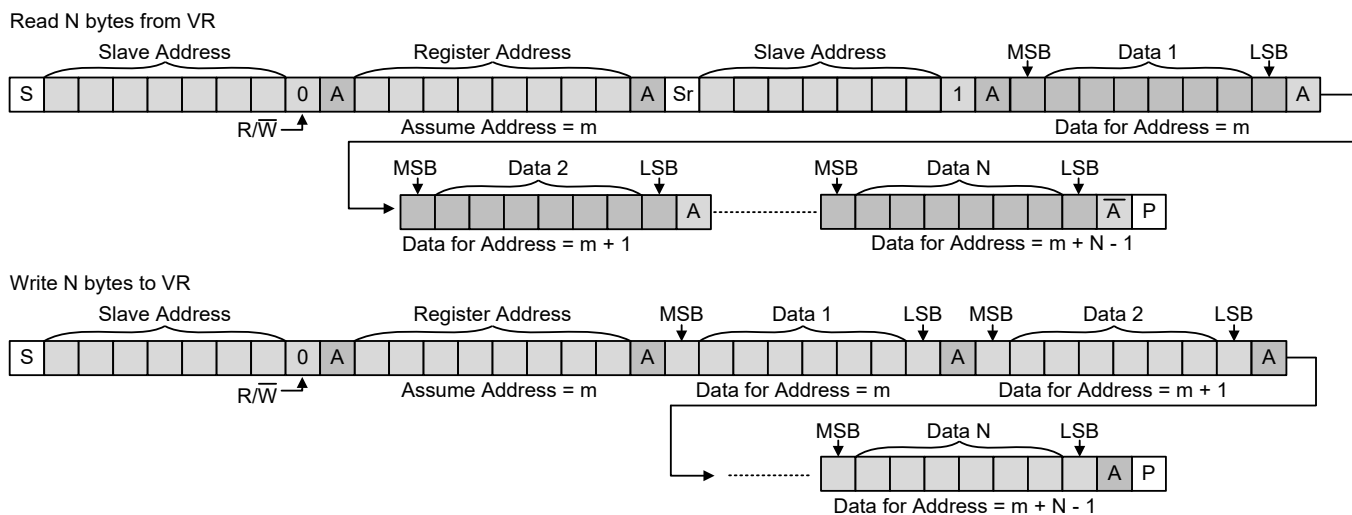
Figure 32. Derating Curve of Maximum Power Dissipation

19 Functional Register Description

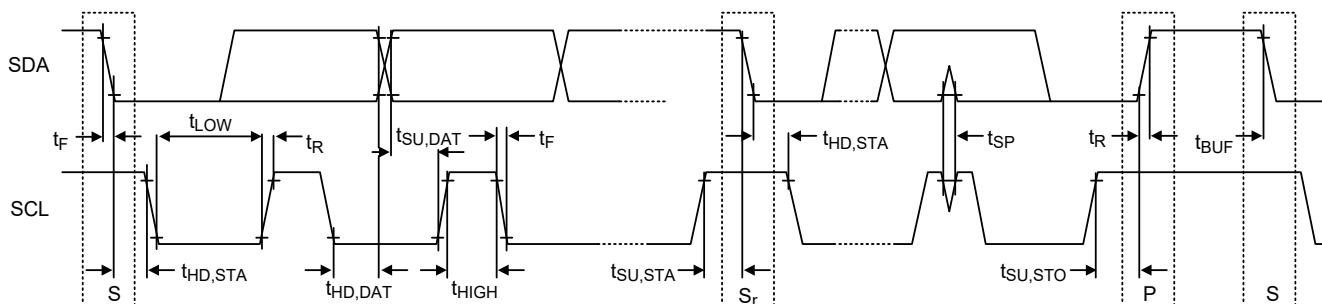
The I²C target address is configured by connecting the SD_GOOD pin to GND with a resistor. Refer to Table 1 for detailed descriptions.

This I²C does not have a stretch function.

The I²C interface supports standard target mode (100kbps), and fast mode (400kbps). The write or read bit stream (N>1) is shown below,



Driven by Master,
 Driven by Slave (VR),
 P Stop,
 S Start,
 Sr Repeat Start



All reserved bit(s) must be kept at their default values.

Table 8. Register List

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x10	SET_ICCMAXA	0xC8	RW	Yes	Yes
0x82	0x11	SET_ICCMAX_RATIOA & EN_0LLA & EN_0LLB & EN_0LLC & EN_FASTV_VRHOT_ASSERTION & SEL_FAST_SR	0x8C	RW	Yes	Yes
0x82	0x12	SET_ICCMAXB	0x3D	RW	Yes	Yes
0x82	0x13	SET_ICCMAXC	0x27	RW	Yes	Yes
0x82	0x14	SET_ICCMAXD	0x21	RW	Yes	Yes
0x82	0x15	SEL_VBOOT_CONFIGA & SEL_KTONA & SEL_VBOOT_CONFIGB & SEL_KTONB	0x34	RW	Yes	Yes
0x82	0x16	SEL_VBOOT_CONFIGC & SEL_KTONC & SEL_PWM_HIZ_VOL & SEL_CS_TYPEA & SEL_CS_TYPEB & SEL_CS_TYPEC	0x48	RW	Yes	Yes
0x82	0x17	EN_FASTV_VRHOT_DEASSERTION & SEL_VID_TABLEA & SEL_VID_TABLEB & SEL_VID_TABLEC & SEL_SMALL_LLA	0x80	RW	Yes	Yes
0x82	0x18	SEL_SMALL_LLB & SEL_SMALL_LLC	0x00	RW	Yes	Yes
0x82	0x19	SEL_Ai_GAINA & SEL_Ai_GAINB & SEL_Ai_GAINC	0x3B	RW	Yes	Yes
0x82	0x1A	SEL_MPH_AR_THA & SEL_MPH_AQR_THA	0x43	RW	Yes	Yes
0x82	0x1B	SEL_ANS_BEHAV & SEL_1PH_AR_THA & SEL_1PH_AQR_THA	0x23	RW	Yes	Yes
0x82	0x1C	SEL_1PH_AR_THB & SEL_1PH_AQR_THB	0x1F	RW	Yes	Yes
0x82	0x1D	SEL_1PH_AR_THC & SEL_1PH_AQR_THC	0x1F	RW	Yes	Yes
0x82	0x1E	SEL_ZCD_THA	0x24	RW	Yes	Yes
0x82	0x1F	EN_MT_TO_X1_RAMPA & SEL_ZCD_THB	0x1D	RW	Yes	Yes
0x82	0x20	EN_EX_1UA_LPF_INITA & SEL_ZCD_THC	0x1D	RW	Yes	Yes
0x82	0x21	SET_SS_OCPA	0x8C	RW	Yes	Yes

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x22	SEL_LPF_INITA & SET_SS_OCPB	0x12	RW	Yes	Yes
0x82	0x23	SET_SS_OCPC	0x12	RW	Yes	Yes
0x82	0x24	Reserved	0x00	RW	Yes	Yes
0x82	0x25	Reserved	0x00	RW	Yes	Yes
0x82	0x26	SEL_I_DVID_LIFTA & SEL_I_DVID_LIFTB	0x54	RW	Yes	Yes
0x82	0x27	SEL_I_DVID_LIFTC & SEL_UV_THA & EN_UVA	0x53	RW	Yes	Yes
0x82	0x28	SEL_DELTA_OVPA & SEL_DELTA_OVPB & SEL_DELTA_OVPC	0x00	RW	Yes	Yes
0x82	0x29	Reserved	0x80	RW	Yes	Yes
0x82	0x2A	SEL_PSYS_LEVEL & SEL_DRVEN_F & EN_DRVEN_TO_DRVEN_F EN_RT_SPS	0x00	RW	Yes	Yes
0x82	0x2B	SEL_SUM_OCP_DEB_TIMEA & SEL_SUM_OCP_DEB_TIMEB & SET_SUM_OCPB	0xD4	RW	Yes	Yes
0x82	0x2C	SEL_SUM_OCP_DEB_TIMEC & SET_SUM_OCPC	0xCC	RW	Yes	Yes
0x82	0x2D	EN_2X_KTON & EN_AR_LIFT_VIDB & SEL_SS_OVPA & SEL_SS_OVPB & SEL_SS_OVPC	0x40	RW	Yes	Yes
0x82	0x2E	SEL_ANTI_OVS_THA & SEL_ANTI_OVS_THB	0xBF	RW	Yes	Yes
0x82	0x2F	EN_AR_LIFT_VIDC & SEL_ANTI_OVS_THC & EN_QR_LIFT_VIDB & EN_SS_OCPA & EN_SS_OCPB & EN_SS_OCPC	0xF7	RW	Yes	Yes
0x82	0x30	EN_EX_10MV_LIFT_VIDA & SEL_1PH_QR_MODEA & SEL_1PH_QR_WIDTHA & SEL_LIFT_VIDA & SEL_MPH_QR_MODEA & SEL_MPH_QR_WIDTHA	0x0E	RW	Yes	Yes
0x82	0x31	EN_EX_TONA & SEL_EX_TON_WIDTHA & SEL_EX_TON_THA	0xE7	RW	Yes	Yes

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x32	EN_MPH_QR_LIFT_VIDA & EN_1PH_QR_LIFT_VIDA & EN_MPH_AR_LIFT_VIDA & EN_1PH_AR_LIFT_VIDA & SEL_QR_LIFT_VID_RECOVERY_TIMEA & SEL_AR_LIFT_VID_RECOVERY_TIMEA & SEL_QR_LIFT_VIDA & SEL_AR_LIFT_VIDA	0x1B	RW	Yes	Yes
0x82	0x33	EN_MPH_QR_LIFT_LPFA & EN_1PH_QR_LIFT_LPFA & EN_MPH_AR_LIFT_LPFA & EN_1PH_AR_LIFT_LPFA & EN_MPH_LIFT_LPFA & EN_1PH_LIFT_LPFA	0x91	RW	Yes	Yes
0x82	0x34	EN_HF_ACLL_QRA & SEL_HF_ACLL_QR_FREQA & EN_HF_ACLL_SQRA & SEL_HF_ACLL_SQR_FREQA	0xCA	RW	Yes	Yes
0x82	0x35	EN_EX_25MV_FLT_RAMPB & SEL_HF_ACLL_QR_FREQB	0x79	RW	Yes	Yes
0x82	0x36	SEL_QR_WIDTHHB & SEL_FLT_RAMPB	0xC7	RW	Yes	Yes
0x82	0x37	EN_QR_LIFT_VIDC & EN_EX_TONB & SEL_EX_TON_WIDTHHB & SEL_EX_TON_THB	0x01	RW	Yes	Yes
0x82	0x38	EN_EX_25MV_FLT_RAMPC & SEL_HF_ACLL_QR_FREQC	0x79	RW	Yes	Yes
0x82	0x39	SEL_QR_WIDTHHC & SEL_FLT_RAMPC	0xC7	RW	Yes	Yes
0x82	0x3A	EN_EX_TONC & SEL_EX_TON_WIDTHHC & SEL_EX_TON_THC	0x01	RW	Yes	Yes
0x82	0x3B	SEL_PH_TYPEA & SEL_PH_TYPEB & SEL_PH_TYPEC	0x00	RW	Yes	Yes
0x82	0x3C	SET_SUM_OCPA	0x82	RW	Yes	Yes
0x82	0x3D	SET_IMON_RPT_OFSA	0x80	RW	Yes	Yes
0x82	0x3E	SET_IMON_RPT_OFSB	0x00	RW	Yes	Yes
0x82	0x3F	SET_IMON_RPT_OFSC	0x00	RW	Yes	Yes
0x82	0x40	SEL_PSK_LIFT_VID	0xCF	RW	Yes	Yes
0x82	0x41	EN_AUTO_TONA & SEL_AUTO_TON_MAXA & EN_AUTO_TONB & SEL_AUTO_TON_MAXB	0xBB	RW	Yes	Yes
0x82	0x42	EN_AUTO_TONC & SEL_AUTO_TON_MAXC	0xB8	RW	Yes	Yes
0x82	0x43	Reserved	0xFF	RW	Yes	Yes

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x44	SEL_HOLD_LPF_THA & SEL_HOLD_LPF_THB & SEL_HOLD_LPF_THC	0xCB	RW	Yes	Yes
0x82	0x45	SEL_RST_LPF_CURRA & SEL_RST_LPF_CURRB & SEL_RST_LPF_CURRC	0xB3	RW	Yes	Yes
0x82	0x46	EN_ANSA & EN_ANSB & EN_ANSC	0xF8	RW	Yes	Yes
0x82	0x47	SEL_I_DVID_DROOPA & SEL_LIFT_VIDB & SEL_I_DVID_DROOPB	0x82	RW	Yes	Yes
0x82	0x48	SEL_LIFT_VIDC & SEL_I_DVID_DROOPC	0x1F	RW	Yes	Yes
0x82	0x49	SEL_MPH_LPF_LIMITA & SEL_MPH_LPF_LIMIT_HYSA	0x72	RW	Yes	Yes
0x82	0x4A	SEL_1PH_LPF_LIMITA & SEL_1PH_LPF_LIMIT_HYSA	0x34	RW	Yes	Yes
0x82	0x4B	Reserved	0x17	RW	Yes	Yes
0x82	0x4C	Reserved	0x71	RW	Yes	Yes
0x82	0x4D	SEL_1PH_LPF_LIMITB & SEL_1PH_LPF_LIMITC	0x47	RW	Yes	Yes
0x82	0x4E	SEL_LPF_INITB & SEL_LPF_INITC	0x22	RW	Yes	Yes
0x82	0x50	SET_VBOOTA	0x00	RW	Yes	Yes
0x82	0x51	Reserved	0xA1	RW	Yes	Yes
0x82	0x52	SET_VBOOTB	0x00	RW	Yes	Yes
0x82	0x53	Reserved	0xA1	RW	Yes	Yes
0x82	0x54	SET_VBOOTC	0x00	RW	Yes	Yes
0x82	0x55	Reserved	0xA1	RW	Yes	Yes
0x82	0x56	Reserved	0x00	RW	Yes	Yes
0x82	0x57	SEL_SPM_HYSA2 & SEL_SPM_THA2	0x5E	RW	Yes	Yes
0x82	0x58	SEL_SPM_HYSA3 & SEL_SPM_THA3	0x3C	RW	Yes	Yes
0x82	0x59	SEL_SPM_HYSA4 & SEL_SPM_THA4	0x3A	RW	Yes	Yes
0x82	0x5A	SEL_SPM_HYSA5 & SEL_SPM_THA5	0x39	RW	Yes	Yes
0x82	0x5B	SEL_SPM_HYS6 & SEL_SPM_THA6	0x38	RW	Yes	Yes
0x82	0x5C	SEL_SPM_HYS7 & SEL_SPM_THA7	0x35	RW	Yes	Yes
0x82	0x5D	SEL_SPM_HYS8 & SEL_SPM_THA8	0x33	RW	Yes	Yes

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x5E	EN_2X_SPM_HYS & SEL_SPM_TH_RATIO & SEL_SPM_SHED_DLYA	0xAC	RW	Yes	Yes
0x82	0x5F	SEL_ZCD_HYSB & SEL_ZCD_HYSC	0x05	RW	Yes	Yes
0x82	0x60	SEL_ANS_PS4_BEHAV & EN_DBLR_SPM_1PH_CCM & EN_SPS_TSEN _A & EN_SPS_TSEN _B & EN_SPS_TSEN _C	0x38	RW	Yes	Yes
0x82	0x61	SEL_SPM_SHED_DLYB & SEL_SPM_SHED_DLYC & SEL_PIN51_CONFIG & EN_2X_Ai_GAINA	0x00	RW	Yes	Yes
0x82	0x62	SET_SPS_TSEN_RPT_OFSA	0x20	RW	Yes	Yes
0x82	0x63	SET_SPS_TSEN_RPT_OFSB	0x20	RW	Yes	Yes
0x82	0x64	SET_SPS_TSEN_RPT_OFSC	0x20	RW	Yes	Yes
0x82	0x65	Reserved	0x00	RW	Yes	Yes
0x82	0x66	Reserved	0x00	RW	Yes	Yes
0x82	0x67	Reserved	0x00	RW	Yes	Yes
0x82	0x68	Reserved	0x00	RW	Yes	Yes
0x82	0x69	Reserved	0x00	RW	Yes	Yes
0x82	0x6A	Reserved	0x00	RW	Yes	Yes
0x82	0x6B	Reserved	0x00	RW	Yes	Yes
0x82	0x6C	Reserved	0x00	RW	Yes	Yes
0x82	0x6D	Reserved	0x00	RW	Yes	Yes
0x82	0x6E	Reserved	0x00	RW	Yes	Yes
0x82	0x6F	Reserved	0x00	RW	Yes	Yes
0x82	0x70	SET_CODE_VER_LB	0x00	RW	Yes	Yes
0x82	0x71	SET_CODE_VER_HB	0x00	RW	Yes	Yes
0x82	0x72	Reserved	0x00	RW	Yes	Yes
0x82	0x73	Reserved	0x00	RW	Yes	Yes
0x82	0x74	SET_PRODUCT_ID	0x38	RW	Yes	Yes
0x82	0x75	Reserved	0x00	RW	Yes	Yes
0x82	0x76	Reserved	0x00	RW	Yes	Yes
0x82	0x77	Reserved	0x00	RW	Yes	Yes
0x82	0x78	Reserved	0x00	RW	Yes	Yes
0x82	0x79	Reserved	0x00	RW	Yes	Yes
0x82	0x7A	Reserved	0x00	RW	Yes	Yes
0x82	0x7B	Reserved	0x00	RW	Yes	Yes
0x82	0x7C	Reserved	0x00	RW	Yes	Yes

Page	Address	Register Name	Default	Type	Paged	NVM
0x82	0x7D	Reserved	0x00	RW	Yes	Yes
0x82	0x7E	Reserved	0x00	RW	Yes	Yes
0x82	0x7F	CRC	N/A	R	Yes	No
Global	0x90	CBGA12	0x44	RW	No	No
Global	0x91	CBGA34	0x44	RW	No	No
Global	0x92	CBGA56	0x44	RW	No	No
Global	0x93	CBGA78	0x44	RW	No	No
Global	0x94	VFIXA_LB	0x83 (VID1) 0xA1 (VID2)	RW	No	No
Global	0x95	VFIXA_HB	0x00	RW	No	No
Global	0x96	VOFSA	0x00	RW	No	No
Global	0x97	TEMP_ALERTA & TEMP_VRHOTA	0x66	RW	No	No
Global	0x98	EN_PROTA	0x63	RW	No	No
Global	0x99	PROT_FLAGA	0x00	R	No	No
Global	0x9A	ILOAD_RPTA	N/A	R	No	No
Global	0x9B	PSYS_RPT	N/A	R	No	No
Global	0x9C	TEMP_RPTA	N/A	R	No	No
Global	0x9E	VOFS_LOADA	0x80	RW	No	No
Global	0x9F	ILOAD_RPT_RATIOA & FORCE_PS0A & KTONA	N/A	RW	No	No
Global	0xA0	EN_FVM	0x70	RW	No	No
Global	0xA3	EN_SPMA	0x00	RW	No	No
Global	0xA7	EN_ANSA & SEL_SMALL_LLA	0x00	RW	No	No
Global	0xA8	VOFS_LOAD_OFSA	0x00	RW	No	No
Global	0xA9	LLA	0x0A	RW	No	No
Global	0xAA	EN_VFIX	0x00	RW	No	No
Global	0xAB	VFIXB_LB	0x83 (VID1) 0xA1 (VID2)	RW	No	No
Global	0xAC	VFIXB_HB	0x00	RW	No	No
Global	0xAD	VOFSB	0x00	RW	No	No
Global	0xAE	TEMP_ALERTB & TEMP_VRHOTB	0x66	RW	No	No
Global	0xAF	EN_PROTB	0x63	RW	No	No
Global	0xB0	PROT_FLAGB	0x00	R	No	No
Global	0xB1	ILOAD_RPTB	N/A	R	No	No
Global	0xB2	TEMP_RPTB	N/A	R	No	No
Global	0xB4	VOFS_LOADB	0x80	RW	No	No
Global	0xB5	ILOAD_RPT_RATIOB & FORCE_PS0B & KTONB	N/A	RW	No	No

Page	Address	Register Name	Default	Type	Paged	NVM
Global	0xB6	EN_SPMB & EN_ANSB & SMALL_LLB	N/A	RW	No	No
Global	0xB8	VOFS_LOAD_OFSB	0x00	RW	No	No
Global	0xB9	LLB	0x0A	RW	No	No
Global	0xBA	LLC	0x0A	RW	No	No
Global	0xBB	VFIXC_LB	0x83 (VID1) 0xA1 (VID2)	RW	No	No
Global	0xBC	VFIXC_HB	0x00	RW	No	No
Global	0xBD	VOFSC	0x00	RW	No	No
Global	0xBE	TEMP_ALERTC & TEMP_VRHOTC	0x66	RW	No	No
Global	0xBF	EN_PROTC	0x63	RW	No	No
Global	0xC0	PROT_FLAGC	00h	R	No	No
Global	0xC1	ILOAD_RPTC	N/A	R	No	No
Global	0xC2	TEMP_RPTC	N/A	R	No	No
Global	0xC4	VOFS_LOADC	0x80	RW	No	No
Global	0xC5	ILOAD_RPT_RATIOC & FORCE_PS0C & KTONC	N/A	RW	No	No
Global	0xC6	EN_SPMC & EN_ANSC & SMALL_LLC	N/A	RW	No	No
Global	0xC7	ILOAD_RPT_RATIOD	0x00	RW	No	No
Global	0xC8	VOFS_LOAD_OFSC	0x00	RW	No	No
Global	0xCC	SEL_ANS & WD_STAT & EN_WD & WDT	N/A	R/RW	No	No
Global	0xCD	ILOAD_RPTD	N/A	R	No	No
Global	0xEC	NVM_PROGRAM_STATUS	N/A	R	No	No
Global	0xEF	PAGE	0x80	RW	No	No

Table 9. SET_ICCMAXA

Address: 0x10								
Bit	7	6	5	4	3	2	1	0
Field	SET_ICCMAXA							
Default	1	1	0	0	1	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_ICCMAXA	Set ICCMAX of rail A which can be set from 00h to FFh representing 0A to 255A. [e.g.] SET_ICCMAXA = 0x64, ICCMAXA = 100A SET_ICCMAXA = 0xFF, ICCMAXA = 255A

Table 10. SET_ICCMAX_RATIOA & EN_0LLA & EN_0LLB & EN_0LLC & EN_FASTV_VRHOT_ASSERTION & SEL_FAST_SR

Address: 0x11								
Bit	7	6	5	4	3	2	1	0
Field	SET_ICCMAX_RATIOA	EN_0LLA	EN_0LLB	EN_0LLC	EN_FASTV_VRHOT_ASSERTION	Reserved	SEL_FAST_SR	
Default	1	0	0	0	1	1	0	0
Type	RW	RW	RW	RW	RW	RW	RW	

Bit	Name	Description
7	SET_ICCMAX_RATIOA	Extend ICCMAX range of rail A. The effective ICCMAX can be encoded at 2 Amps per bit by setting ICCMAX_ADDA 0: ICCMAX = SET_ICCMAXA, 1: ICCMAX = SET_ICCMAXA x 2 [e.g.] SET_ICCMAX_RATIOA = 1 and SET_ICCMAXA = 0x64 ICCMAXA = 100 x 2 = 200A
6	EN_0LLA	Enable zero loadline of rail A 0: Disable, 1: Enable
5	EN_0LLB	Enable zero loadline of rail B 0: Disable, 1: Enable
4	EN_0LLC	Enable zero loadline of rail C 0: Disable, 1: Enable
3	EN_FASTV_VRHOT_ASSERTION	Enable $\overline{\text{VR_HOT}}$ assertion during Fast V-Mode current limiting 0: Disable, 1: Enable
2	Reserved	Default value is 1
1:0	SEL_FAST_SR	Select DVID fast slew rate 00: 10mV/ μ s, 01: 24mV/ μ s, 10: 36mV/ μ s, 11: 48mV/ μ s

Table 11. SET_ICCMAXB

Address: 0x12								
Bit	7	6	5	4	3	2	1	0
Field	SET_ICCMAXB							
Default	0	0	1	1	1	1	0	1
Type	RW							

Bit	Name	Description
7:0	SET_ICCMAXB	Set ICCMAX of rail B which can be set from 00h to FFh representing 0A to 255A. [e.g.] SET_ICCMAXB = 0x64, ICCMAXB = 100A SET_ICCMAXB = 0xFF, ICCMAXB = 255A

Table 12. SET_ICCMAXC

Address: 0x13								
Bit	7	6	5	4	3	2	1	0
Field	SET_ICCMAXC							
Default	0	0	1	0	0	1	1	1
Type	RW							

Bit	Name	Description
7:0	SET_ICCMAXC	Set ICCMAX of rail C which can be set from 00h to FFh representing 0A to 255A. [e.g.] SET_ICCMAXC = 0x64, ICCMAXC = 100A SET_ICCMAXC = 0xFF, ICCMAXC = 255A

Table 13. SET_ICCMAXD

Address: 0x14								
Bit	7	6	5	4	3	2	1	0
Field	SET_ICCMAXD							
Default	0	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	SET_ICCMAXD	Set ICCMAX of rail D which can be set from 00h to FFh representing 0A to 255A. [e.g.] SET_ICCMAXD = 0x64, ICCMAXD = 100A SET_ICCMAXD = 0xFF, ICCMAXD = 255A

Table 14. SEL_VBOOT_CONFIGA & SEL_KTONA & SEL_VBOOT_CONFIGB & SEL_KTONB

Address: 0x15								
Bit	7	6	5	4	3	2	1	0
Field	SEL_VBOOT_CONFIGA	SEL_KTONA			SEL_VBOOT_CONFIGB	SEL_KTONB		
Default	0	0	1	1	0	1	0	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	SEL_VBOOT_CONFIGA	Select VBOOT configuration of rail A 0: VBOOTA = 1.05V when connecting SD_GOOD pin to 5V VBOOTA = 0V when connecting SD_GOOD pin to GND with a resistor 1: VBOOTA = 1.05V when connecting SD_GOOD pin to 5V VBOOTA = SET_VBOOTA (Non-zero VBOOT) when connecting SD_GOOD pin to GND with a resistor
6:4	SEL_KTONA	Select SEL_KTONA for required switching frequency of rail A. Refer to the section Switching Frequency Setting for the details
3	SEL_VBOOT_CONFIGB	Select VBOOT configuration of rail B 0: VBOOTB = 1.05V when connecting SD_GOOD pin to 5V VBOOTB = 0V when connecting SD_GOOD pin to GND with a resistor 1: VBOOTB = 1.05V when connecting SD_GOOD pin to 5V VBOOTB = SET_VBOOTB (Non-zero VBOOT) when connecting SD_GOOD pin to GND with a resistor
2:0	SEL_KTONB	Select SEL_KTONB for required switching frequency of rail B. Refer to the section Switching Frequency Setting for the details

Table 15. SEL_VBOOT_CONFIGC & SEL_KTONC & SEL_PWM_HIZ_VOL & SEL_CS_TYPEA & SEL_CS_TYPEB & SEL_CS_TYPEC

Address: 0x16								
Bit	7	6	5	4	3	2	1	0
Field	SEL_VBOOT_CONFIGC	SEL_KTONC			SEL_PWM_HIZ_VOL	SEL_CS_TYPEA	SEL_CS_TYPEB	SEL_CS_TYPEC
Default	0	1	0	0	1	0	0	0
Type	RW	RW			RW	RW	RW	RW

Bit	Name	Description
7	SEL_VBOOT_CONFIGC	Select VBOOT configuration of rail C 0: VBOOTC = 1.05V when connecting SD_GOOD pin to 5V VBOOTC = 0V when connecting SD_GOOD pin to GND with a resistor 1: VBOOTC = 1.05V when connecting SD_GOOD pin to 5V VBOOTC = SET_VBOOTC (Non-zero VBOOT) when connecting SD_GOOD pin to GND with a resistor
6:4	SEL_KTONC	Select SEL_KTONC for required switching frequency of rail C. Refer to the section Switching Frequency Setting for the details
3	SEL_PWM_HIZ_VOL	Select the tri-state voltage level of PWM 0: 1.6V to 2.2V, 1: 1.4V to 2.1V
2	SEL_CS_TYPEA	Select current sense type of rail A 0: DCR current sense is adopted, 1: SPS module is adopted.
1	SEL_CS_TYPEB	Select current sense type of rail B 0: DCR current sense is adopted, 1: SPS module is adopted.
0	SEL_CS_TYPEC	Select current sense type of rail C 0: DCR current sense is adopted, 1: SPS module is adopted.

Table 16. EN_FASTV_VRHOT_DEASSERTION & SEL_VID_TABLEA & SEL_VID_TABLEB & SEL_VID_TABLEC & SEL_SMALL_LLA

Address: 0x17								
Bit	7	6	5	4	3	2	1	0
Field	EN_FASTV_VRHOT_DEASSERTION	SEL_VID_TABLEA	SEL_VID_TABLEB	SEL_VID_TABLEC	SEL_SMALL_LLA			
Default	1	0	0	0	0	0	0	0
Type	RW	RW	RW	RW	RW			

Bit	Name	Description
7	EN_FASTV_VRHOT_DEASSERTION	Enable revisiting the status of Fast V-Mode to de-assert VR_HOT while receiving SetVID command 0: Disable, 1: Enable
6	SEL_VID_TABLEA	Select VID table of rail A 0: 5mV VID table, 1: 10mV VID table
5	SEL_VID_TABLEB	Select VID table of rail B 0: 5mV VID table, 1: 10mV VID table
4	SEL_VID_TABLEC	Select VID table of rail C 0: 5mV VID table, 1: 10mV VID table
3:0	SEL_SMALL_LLA	Select small loadline of rail A 0000: 100%, 0001: 95%, 0010: 90%, 0011: 85%, 0100: 80%, 0101: 75%, 0110: 70%, 0111: 65%, 1000: 60%, 1001: 55%, 1010: 50%, 1011: 40%, 1100: 30%, 1101: 20%, 1110: 10%, 1111: 0%

Table 17. SEL_SMALL_LLB & SEL_SMALL_LLC

Address: 0x18								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SMALL_LLB				SEL_SMALL_LLC			
Default	0	0	0	0	0	0	0	0
Type	RW				RW			

Bit	Name	Description
7:4	SEL_SMALL_LLB	Select small loadline of rail B 0000: 100%, 0001: 95%, 0010: 90%, 0011: 85%, 0100: 80%, 0101: 75%, 0110: 70%, 0111: 65%, 1000: 60%, 1001: 55%, 1010: 50%, 1011: 40%, 1100: 30%, 1101: 20%, 1110: 10%, 1111: 0%
3:0	SEL_SMALL_LLC	Select small loadline of rail C 0000: 100%, 0001: 95%, 0010: 90%, 0011: 85%, 0100: 80%, 0101: 75%, 0110: 70%, 0111: 65%, 1000: 60%, 1001: 55%, 1010: 50%, 1011: 40%, 1100: 30%, 1101: 20%, 1110: 10%, 1111: 0%

Table 18. SEL_Ai_GAINA & SEL_Ai_GAINB & SEL_Ai_GAINC

Address: 0x19								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_Ai_GAINA		SEL_Ai_GAINB		SEL_Ai_GAINC	
Default	0	0	1	1	1	0	1	1
Type	RW		RW		RW		RW	

Bit	Name	Description
7:6	Reserved	Default value 0b00, not change
5:4	SEL_Ai_GAINA	Select Ai gain of rail A 00: 0.25, 01: 0.5, 10: 0.75, 11: 1
3:2	SEL_Ai_GAINB	Select Ai gain of rail B 00: 1, 01: 1.25, 10: 1.5, 11: 2
1:0	SEL_Ai_GAINC	Select Ai gain of rail C 00: 1, 01: 1.25, 10: 1.5, 11: 2

Table 19. SEL_MPH_AR_THA & SEL_MPH_AQR_THA

Address: 0x1A								
Bit	7	6	5	4	3	2	1	0
Field	SEL_MPH_AR_THA			SEL_MPH_AQR_THA				
Default	0	1	0	0	0	0	1	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_MPH_AR_THA	Select multi-phase adaptive ramp threshold of rail A SEL_MPH_AR_THA[7] = 0, 000: 275mV, 001: 225mV, 010: 175mV, 011: Disable SEL_MPH_AR_THA[7] = 1, 100: 300mV, 101: 250mV, 110: 200mV, 111: Disable
4:0	SEL_MPH_AQR_THA	Select multi-phase adaptive quick response threshold of rail A 00000: 240mV, 00001: 320mV, 00010: 400mV, 00011: 480mV, 00100: 560mV, 00101: 640mV, 00110: 720mV, 00111: 800mV, 01000: 880mV, 01001: 960mV, 01010: 1040mV, 01011: 1120mV, 01100: 1200mV, 01101: 1280mV, 01110: 1360mV, 01111: 1440mV, 10000: 1520mV, 10001: 1600mV, 10010: 1680mV, 10011: 1760mV, 10100: 1840mV, 10101: 1920mV, 10110: 2000mV, 10111: 2080mV, 11000: 2160mV, 11001: 2240mV, 11010: 2320mV, 11011: 2400mV, 11100: Disable, 11101: Disable, 11110: Disable, 11111: Disable

Table 20. SEL_ANS_BEHAV & SEL_1PH_AR_THA & SEL_1PH_AQR_THA

Address: 0x1B								
Bit	7	6	5	4	3	2	1	0
Field	SEL_ANS_BEHAV	SEL_1PH_AR_THA		SEL_1PH_AQR_THA				
Default	0	0	1	0	0	0	1	1
Type	RW	RW		RW				

Bit	Name	Description
7	SEL_ANS_BEHAV	Acoustic noise suppression function behavior 0: Only DVID up is allowed, no action for DVID down 1: DVID down with extremely slow slew rate (0.00613mV/μs)
6:5	SEL_1PH_AR_THA	Select single-phase adaptive ramp threshold of rail A 00: 175mV, 01: 150mV, 10: 125mV, 11: Disable
4:0	SEL_1PH_AQR_THA	Select single-phase adaptive quick response threshold of rail A 00000: 40mV, 00001: 80mV, 00010: 120mV, 00011: 160mV, 00100: 200mV, 00101: 240mV, 00110: 280mV, 00111: 320mV, 01000: 360mV, 01001: 400mV, 01010: 440mV, 01011: 480mV, 01100: 520mV, 01101: 560mV, 01110: 600mV, 01111: 640mV, 10000: 680mV, 10001: 720mV, 10010: 760mV, 10011: 800mV, 10100: 840mV, 10101: 880mV, 10110: 920mV, 10111: 960mV, 11000: 1000mV, 11001: 1040mV, 11010: 1080mV, 11011: 1120mV, 11100: 1160mV, 11101: 1200mV, 11110: 1240mV, 11111: Disable

Table 21. SEL_1PH_AR_THB & SEL_1PH_AQR_THB

Address: 0x1C								
Bit	7	6	5	4	3	2	1	0
Field	SEL_1PH_AR_THB			SEL_1PH_AQR_THB				
Default	0	0	0	1	1	1	1	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_1PH_AR_THB	Select adaptive ramp threshold of rail B 000: Disable, 001: 125mV, 010: 150mV, 011: 175mV, 100: 200mV, 101: 225mV, 110: 250mV, 111: 275mV
4:0	SEL_1PH_AQR_THB	Select adaptive quick response threshold of rail B 00000: 240mV, 00001: 320mV, 00010: 400mV, 00011: 480mV, 00100: 560mV, 00101: 640mV, 00110: 720mV, 00111: 800mV, 01000: 880mV, 01001: 960mV, 01010: 1040mV, 01011: 1120mV, 01100: 1200mV, 01101: 1280mV, 01110: Disable, 01111: Disable, 10000: 720mV, 10001: 800mV, 10010: 880mV, 10011: 960mV, 10100: 1040mV, 10101: 1120mV, 10110: 1200mV, 10111: 1280mV, 11000: 1360mV, 11001: 1440mV, 11010: 1520mV, 11011: 1600mV, 11100: 1680mV, 11101: 1760mV, 11110: Disable, 11111: Disable

Table 22. SEL_1PH_AR_THC & SEL_1PH_AQR_THC

Address: 0x1D								
Bit	7	6	5	4	3	2	1	0
Field	SEL_1PH_AR_THC			SEL_1PH_AQR_THC				
Default	0	0	0	1	1	1	1	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_1PH_AR_THC	Select adaptive ramp threshold of rail C 000: Disable, 001: 125mV, 010: 150mV, 011: 175mV, 100: 200mV, 101: 225mV, 110: 250mV, 111: 275mV
4:0	SEL_1PH_AQR_THC	Select adaptive quick response threshold of rail C 00000: 240mV, 00001: 320mV, 00010: 400mV, 00011: 480mV, 00100: 560mV, 00101: 640mV, 00110: 720mV, 00111: 800mV, 01000: 880mV, 01001: 960mV, 01010: 1040mV, 01011: 1120mV, 01100: 1200mV, 01101: 1280mV, 01110: Disable, 01111: Disable, 10000: 720mV, 10001: 800mV, 10010: 880mV, 10011: 960mV, 10100: 1040mV, 10101: 1120mV, 10110: 1200mV, 10111: 1280mV, 11000: 1360mV, 11001: 1440mV, 11010: 1520mV, 11011: 1600mV, 11100: 1680mV, 11101: 1760mV, 11110: Disable, 11111: Disable

Table 23. SEL_ZCD_THA

Address: 0x1E								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_ZCD_THA					
Default	0	0	1	0	0	1	0	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5:0	SEL_ZCD_THA	Select the ZCD threshold of rail A. [5]: sign bit, 0 is positive [4:0]: 0.208mV/step [e.g.] SEL_ZCD_THA = 0b011111, ZCD_THA = 6.4573mV SEL_ZCD_THA = 0b000000 or 0b100000, ZCD_THA = 0mV SEL_ZCD_THA = 0b111111, ZCD_THA = -6.4573mV

Table 24. EN_MT_TO_X1_RAMPA & SEL_ZCD_THB

Address: 0x1F								
Bit	7	6	5	4	3	2	1	0
Field	EN_MT_TO_X1_RAMPA	Reserved	SEL_ZCD_THB					
Default	0	0	0	1	1	1	0	1
Type	RW	RW	RW					

Bit	Name	Description
7	EN_MT_TO_X1_RAMPA	Enable ramp slop reduction to 1 times ramp slop of rail A. When power state transfer from PS0 to PS1 0: Disable, 1: Enable
6	Reserved	Default value 0, not change
5:0	SEL_ZCD_THB	Select the ZCD threshold of rail B. $ZCD_THB = -2mV + [5:0] \times 0.0625mV$ [e.g.] SEL_ZCD_THB = 0b111111, ZCD_THB = 1.9375mV SEL_ZCD_THB = 0b100000, ZCD_THB = 0mV SEL_ZCD_THB = 0b000000, ZCD_THB = -2mV

Table 25. EN_EX_1UA_LPF_INITA & SEL_ZCD_THC

Address: 0x20								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	EN_EX_1UA_LPF_INITA	SEL_ZCD_THC					
Default	0	0	0	1	1	1	0	1
Type	RW	RW	RW					

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6	EN_EX_1UA_LPF_INITA	Enable extra +1μA on initial current of LPF of rail A 0: Disable, 1: Enable [e.g.] EN_EX_1UA_LPF_INITA = 1, SEL_LPF_INITA = 00: -0.5μA, 01: 0μA, 10: +0.5μA, 11: +1μA
5:0	SEL_ZCD_THC	Select the ZCD threshold of rail C. ZCD_THC = -4mV + [5:0] x 0.125mV [e.g.] SEL_ZCD_THC = 0b111111, ZCD_THC = 3.875mV SEL_ZCD_THC = 0b100000, ZCD_THC = 0mV SEL_ZCD_THC = 0b000000, ZCD_THC = -4mV

Table 26. SET_SS_OCPA

Address: 0x21								
Bit	7	6	5	4	3	2	1	0
Field	SET_SS_OCPA							
Default	1	0	0	0	1	1	0	0
Type	RW							

Bit	Name	Description
7:0	SET_SS_OCPA	Set soft-start OCP of rail A which can be set from 00h to FFh representing 0A to 1020A. Resolution = 4A/LSB. Maximum ratio value SET_SS_OCPA/ICCMAXA is limited at 6.5 [e.g.] SET_SS_OCPA = 0x64, SS_OCPA = 400A SET_SS_OCPA = 0xFF, SS_OCPA = 1020A

Table 27. SEL_LPF_INITA & SET_SS_OCPB

Address: 0x22								
Bit	7	6	5	4	3	2	1	0
Field	SEL_LPF_INITA		SET_SS_OCPB					
Default	0	0	0	1	0	0	1	0
Type	RW		RW					

Bit	Name	Description
7:6	SEL_LPF_INITA	Set initial current of LPF of rail A 00: $-1.5\mu\text{A}$, 01: $-1\mu\text{A}$, 10: $-0.5\mu\text{A}$, 11: $0\mu\text{A}$
5:0	SET_SS_OCPB	Set soft-start OCP of rail B which can be set from 00h to 3Fh representing 0A to 252A. Resolution = 4A/LSB. Maximum ratio value SET_SS_OCPB/ICCMAXB is limited at 6.5 [e.g.] SET_SS_OCPB = 0x14, SS_OCPB = 80A SET_SS_OCPB = 0x3F, SS_OCPB = 252A

Table 28. SET_SS_OCPC

Address: 0x23								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_SS_OCPC					
Default	0	0	0	1	0	0	1	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Default value 00h, not change
5:0	SET_SS_OCPC	Set soft-start OCP of rail C which can be set from 00h to 3Fh representing 0A to 252A. Resolution = 4A/LSB. Maximum ratio value SET_SS_OCPC/ICCMAXC is limited at 6.5 [e.g.] SET_SS_OCPC = 0x14, SS_OCPC = 80A SET_SS_OCPC = 0x3F, SS_OCPC = 252A

Table 29. Reserved

Address: 0x24 to 0x25								
Description: Registers of 0x24 to 0x25 are reserved and with same default value.								
Bit	7	6	5	4	3	2	1	0
Field	Reserved							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	Reserved	Unimplemented, default value is 00h

Table 30. SEL_I_DVID_LIFTA & SEL_I_DVID_LIFTB

Address: 0x26								
Bit	7	6	5	4	3	2	1	0
Field	SEL_I_DVID_LIFTA				SEL_I_DVID_LIFTB			
Default	0	1	0	1	0	1	0	0
Type	RW				RW			

Bit	Name	Description
7:4	SEL_I_DVID_LIFTA	Select the compensation current I_{DVID_LIFT} during DVID up period of rail A 0000: 0 μ A, 0001: 2 μ A, 0010: 4 μ A, 0011: 6 μ A, 0100: 8 μ A, 0101: 10 μ A, 0110: 12 μ A, 0111: 14 μ A, 1000: 16 μ A, 1001: 18 μ A, 1010: 20 μ A, 1011: 24 μ A, 1100: 28 μ A, 1101: 32 μ A, 1110: 36 μ A, 1111: 40 μ A
3:0	SEL_I_DVID_LIFTB	Select the compensation current I_{DVID_LIFT} during DVID up period of rail B 0000: 0 μ A, 0001: 2 μ A, 0010: 4 μ A, 0011: 6 μ A, 0100: 8 μ A, 0101: 10 μ A, 0110: 12 μ A, 0111: 14 μ A, 1000: 16 μ A, 1001: 18 μ A, 1010: 20 μ A, 1011: 24 μ A, 1100: 28 μ A, 1101: 32 μ A, 1110: 36 μ A, 1111: 40 μ A

Table 31. SEL_I_DVID_LIFTC & SEL_UV_THA & EN_UVA

Address: 0x27								
Bit	7	6	5	4	3	2	1	0
Field	SEL_I_DVID_LIFTC				Reserved	SEL_UV_THA	EN_UVA	Reserved
Default	0	1	0	1	0	0	1	1
Type	RW				RW	RW	RW	RW

Bit	Name	Description
7:4	SEL_I_DVID_LIFTC	Select the compensation current I_{DVID_LIFT} during DVID up period of rail C 0000: 0 μ A, 0001: 2 μ A, 0010: 4 μ A, 0011: 6 μ A, 0100: 8 μ A, 0101: 10 μ A, 0110: 12 μ A, 0111: 14 μ A, 1000: 16 μ A, 1001: 18 μ A, 1010: 20 μ A, 1011: 24 μ A, 1100: 28 μ A, 1101: 32 μ A, 1110: 36 μ A, 1111: 40 μ A
3	Reserved	Default value 0, not change
2	SEL_UV_THA	Select UV threshold of rail A 0: 650mV, 1: 850mV
1	EN_UVA	Enable UV protection of rail A 0: Disable, 1: Enable
0	Reserved	Default value 1, not change

Table 32. SEL_DELTA_OVPA, SEL_DELTA_OVPB & SEL_DELTA_OVPC

Address: 0x28								
Bit	7	6	5	4	3	2	1	0
Field	SEL_DELTA_OVPA		SEL_DELTA_OVPB		SEL_DELTA_OVPC		Reserved	
Default	0	0	0	0	0	0	0	0
Type	RW		RW		RW		RW	

Bit	Name	Description
7:6	SEL_DELTA_OVPA	Select delta OVP threshold of rail A 00: 350mV, 01: 400mV, 10: 450mV, 11: 500mV
5:4	SEL_DELTA_OVPB	Select delta OVP threshold of rail B 00: 350mV, 01: 400mV, 10: 450mV, 11: 500mV
3:2	SEL_DELTA_OVPC	Select delta OVP threshold of rail C 00: 350mV, 01: 400mV, 10: 450mV, 11: 500mV
1:0	Reserved	Unimplemented, default value is 0b00

Table 33. Reserved

Address: 0x29								
Bit	7	6	5	4	3	2	1	0
Field	Reserved							
Default	1	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	Reserved	Default value 80h, not change

Table 34. SEL_PSYS_LEVEL, SEL_DRVEN_F, EN_DRVEN_TO_DRVEN_F & EN_RT_SPS

Address: 0x2A								
Bit	7	6	5	4	3	2	1	0
Field	SEL_PSYS_LEVEL	SEL_DRVEN_F	EN_DRVEN_TO_DRVEN_F	EN_RT_SPS	Reserved			
Default	0	0	0	0	0	0	0	0
Type	RW	RW	RW	RW	RW			

Bit	Name	Description
7	SEL_PSYS_LEVEL	Select the full scale of PSYS 0: 1.6V, 1: 3.2V
6	SEL_DRVEN_F	Select DRVEN_F behavior for applicated rail 0: For rail A and rail B 1: For all rail
5	EN_DRVEN_TO_DRVEN_F	Enable DRVEN behavior as DRVEN_F behavior for all rail 0: Disable, 1: Enable
4	EN_RT_SPS	Enable DRVEN_F behavior as: This pin will be in low state when VID = 0V 0: Disable, 1: Enable
3:0	Reserved	Unimplemented, default value is 0b0000

Table 35. SEL_SUM_OCP_DEB_TIMEA, SEL_SUM_OCP_DEB_TIMEB & SET_SUM_OCPB

Address: 0x2B								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SUM_OCP_DEB_TIMEA	SEL_SUM_OCP_DEB_TIMEB	SET_SUM_OCPB					
Default	1	1	0	1	0	1	0	0
Type	RW	RW	RW					

Bit	Name	Description
7	SEL_SUM_OCP_DEB_TIMEA	Select the de-bounce time of sum OCP of rail A 0: 20 μ s, 1: 40 μ s
6	SEL_SUM_OCP_DEB_TIMEB	Select the de-bounce time of sum OCP of rail B 0: 20 μ s, 1: 40 μ s
5:0	SET_SUM_OCPB	Set sum OCP of rail B which can be set from 00h to 3Fh representing 0A to 252A. Resolution = 4A/LSB. Maximum ratio value SET_SUM_OCPB /ICCMAXB is limited at 6.5 [e.g.] SET_SUM_OCPB = 0x14, SUM_OCPB = 80A SET_SUM_OCPB = 0x3F, SUM_OCPB = 252A

Table 36. SEL_SUM_OCP_DEB_TIMEC & SET_SUM_OCPC

Address: 0x2C								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SUM_OCP_DEB_TIMEC	Reserved	SET_SUM_OCPC					
Default	1	1	0	0	1	1	0	0
Type	RW	RW	RW					

Bit	Name	Description
7	SEL_SUM_OCP_DEB_TIMEC	Select the de-bounce time of sum OCP of rail C 0: 20 μ s, 1: 40 μ s
6	Reserved	Default value 1, not change
5:0	SET_SUM_OCPC	Set sum OCP of rail C which can be set from 00h to 3Fh representing 0A to 252A. Resolution = 4A/LSB. Maximum ratio value SET_SUM_OCPC /ICCMAXC is limited at 6.5 [e.g.] SET_SUM_OCPC = 0x14, SUM_OCPC = 80A SET_SUM_OCPC = 0x3F, SUM_OCPC = 252A

Table 37. EN_2X_KTON, EN_AR_LIFT_VIDB, SEL_SS_OVPA, SEL_SS_OVPB & SEL_SS_OVPC

Address: 0x2D								
Bit	7	6	5	4	3	2	1	0
Field	EN_2X_KTON	EN_AR_LIFT_VIDB	SEL_SS_OVPA		SEL_SS_OVPB		SEL_SS_OVPC	
Default	0	1	0	0	0	0	0	0
Type	RW	RW	RW		RW		RW	

Bit	Name	Description
7	EN_2X_KTON	Enable 2X K _{TON} 0: Disable, 1: Enable
6	EN_AR_LIFT_VIDB	Enable lifting VID in adaptive ramp of rail B 0: Disable, 1: Enable
5:4	SEL_SS_OVPA	Select soft-start OVP threshold of rail A 00: 2.1V, 01: 2.3V, 10: 2.5V, 11: 2.7V
3:2	SEL_SS_OVPB	Select soft-start OVP threshold of rail B 00: 2.1V, 01: 2.3V, 10: 2.5V, 11: 2.7V
1:0	SEL_SS_OVPC	Select soft-start OVP threshold of rail C 00: 2.1V, 01: 2.3V, 10: 2.5V, 11: 2.7V

Table 38. SEL_ANTI_OVS_THA & SEL_ANTI_OVS_THB

Address: 0x2E								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_ANTI_OVS_THA			SEL_ANTI_OVS_THB		
Default	1	0	1	1	1	1	1	1
Type	RW		RW			RW		

Bit	Name	Description
7:6	Reserved	Default value 0b10, not change
5:3	SEL_ANTI_OVS_THA	Select anti-overshoot threshold of rail A 000: 180mV, 001: 240mV, 010: 300mV, 011: 360mV, 100: 420mV, 101: 480mV, 110: Disable, 111: Disable
2:0	SEL_ANTI_OVS_THB	Select anti-overshoot threshold of rail B 000: 90mV, 001: 120mV, 010: 150mV, 011: 180mV, 100: 210mV, 101: 240mV, 110: Disable, 111: Disable

Table 39. EN_AR_LIFT_VIDC, SEL_ANTI_OVS_THC, EN_QR_LIFT_VIDB, EN_SS_OCPA, EN_SS_OCPB, EN_SS_OCPC

Address: 0x2F							
Bit	7	6	5	4	3	2	1 0
Field	EN_AR_LIFT_VIDC	SEL_ANTI_OVS_THC			EN_QR_LIFT_VIDB	EN_SS_OCPA	EN_SS_OCPB EN_SS_OCPC
Default	1	1	1	1	0	1	1 1
Type	RW	RW			RW	RW	RW RW

Bit	Name	Description
7	EN_AR_LIFT_VIDC	Enable lifting VID in adaptive ramp of rail C 0: Disable, 1: Enable
6:4	SEL_ANTI_OVS_THC	Select anti-overshoot threshold of rail C 000: 90mV, 001: 120mV, 010: 150mV, 011: 180mV, 100: 210mV, 101: 240mV, 110: Disable, 111: Disable
3	EN_QR_LIFT_VIDB	Enable lifting VID in quick response of rail B 0: Disable, 1: Enable
2	EN_SS_OCPA	Enable soft-start OCP of rail A 0: Disable, 1: Enable
1	EN_SS_OCPB	Enable soft-start OCP of rail B 0: Disable, 1: Enable
0	EN_SS_OCPC	Enable soft-start OCP of rail C 0: Disable, 1: Enable

Table 40. EN_EX_10MV_LIFT_VIDA, SEL_1PH_QR_MODEA, SEL_1PH_QR_WIDTHA, SEL_LIFT_VIDA, SEL_MPH_QR_MODEA & SEL_MPH_QR_WIDTHA

Address: 0x30								
Bit	7	6	5	4	3	2	1	0
Field	EN_EX_10MV_LIFT_VIDA	SEL_1PH_QR_MODEA	SEL_1PH_QR_WIDTHA		SEL_LIFT_VIDA	SEL_MPH_QR_MODEA	SEL_MPH_QR_WIDTHA	
Default	0	0	0	0	1	1	1	0
Type	RW	RW	RW		RW	RW	RW	

Bit	Name	Description
7	EN_EX_10MV_LIFT_VIDA	Enable extra 10mV lifting VID amount for SEL_LIFT_VIDA 0: Disable, 1: Enable
6	SEL_1PH_QR_MODEA	Select single-phase quick response mode of rail A 0: Fixed PWM width in quick response mode 1: Adaptive PWM width in quick response mode
5:4	SEL_1PH_QR_WIDTHA	Select PWM width in single-phase quick response mode of rail A 00: 0.5 x t _{ON} , 01: 0.75 x t _{ON} , 10: 1.0 x t _{ON} , 11: 1.25 x t _{ON}
3	SEL_LIFT_VIDA	Select lifting VID amount of rail A 0: 5mV, 1: 10mV EN_EX_10mV_LIFT_VIDA = 1, 0: 15mV, 1: 20mV
2	SEL_MPH_QR_MODEA	Select multi-phase quick response mode of rail A 0: Fixed PWM width in quick response mode 1: Adaptive PWM width in quick response mode
1:0	SEL_MPH_QR_WIDTHA	Select PWM width in multi-phase quick response mode of rail A 00: 0.5 x t _{ON} , 01: 0.75 x t _{ON} , 10: 1.0 x t _{ON} , 11: 1.25 x t _{ON}

Table 41. EN_EX_TONA, SEL_EX_TON_WIDTHA & SEL_EX_TON_THA

Address: 0x31								
Bit	7	6	5	4	3	2	1	0
Field	EN_EX_TONA	Reserved			SEL_EX_TON_WIDTHA		SEL_EX_TON_THA	
Default	1	1	1	0	0	1	1	1
Type	RW	RW			RW		RW	

Bit	Name	Description
7	EN_EX_TONA	Enable the extend ton of rail A 0: Disable, 1: Enable
6:4	Reserved	Default value is 0b110. All other combinations are not defined.
3:2	SEL_EX_TON_WIDTHA	Select extend ton width of rail A 00: 4 x ton, 01: 2.66 x ton, 10: 2 x ton, 11: 1.6 x ton
1:0	SEL_EX_TON_THA	Select extend ton threshold of rail A 00: 2.4V + 150mV, 01: 2.4V + 200mV, 10: 2.4V + 250mV, 11: 2.4V + 300mV

Table 42. EN_MPH_QR_LIFT_VIDA, EN_1PH_QR_LIFT_VIDA, EN_MPH_AR_LIFT_VIDA, EN_1PH_AR_LIFT_VIDA, SEL_QR_LIFT_VID_RECOVERY_TIMEA, SEL_AR_LIFT_VID_RECOVERY_TIMEA, SEL_QR_LIFT_VIDA & SEL_AR_LIFT_VIDA

Address: 0x32								
Bit	7	6	5	4	3	2	1	0
Field	EN_MPH_QR_LIFT_VIDA	EN_1PH_QR_LIFT_VIDA	EN_MPH_AR_LIFT_VIDA	EN_1PH_AR_LIFT_VIDA	SEL_QR_LIFT_VID_RECOVERY_TIMEA	SEL_AR_LIFT_VID_RECOVERY_TIMEA	SEL_QR_LIFT_VIDA	SEL_AR_LIFT_VIDA
Default	0	0	0	1	1	0	1	1
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7	EN_MPH_QR_LIFT_VIDA	Enable lifting VID in multi-phase quick response mode of rail A 0: Disable, 1: Enable
6	EN_1PH_QR_LIFT_VIDA	Enable lifting VID in single-phase quick response mode of rail A 0: Disable, 1: Enable
5	EN_MPH_AR_LIFT_VIDA	Enable lifting VID in multi-phase adaptive ramp mode of rail A 0: Disable, 1: Enable
4	EN_1PH_AR_LIFT_VIDA	Enable lifting VID in single-phase adaptive ramp mode of rail A 0: Disable, 1: Enable
3	SEL_QR_LIFT_VID_RECOVERY_TIMEA	Select lifting VID recovery time in quick response mode of rail A 0: 150μs, 1: 40μs
2	SEL_AR_LIFT_VID_RECOVERY_TIMEA	Select lifting VID recovery time in adaptive ramp mode of rail A 0: 150μs, 1: 40μs
1	SEL_QR_LIFT_VIDA	Select lift VID amount in quick response mode of rail A 0: 5mV, 1: 10mV
0	SEL_AR_LIFT_VIDA	Select lift VID amount in adaptive ramp mode of rail A 0: 5mV, 1: 10mV

Table 43. EN_MPH_QR_LIFT_LPFA, EN_1PH_QR_LIFT_LPFA, EN_MPH_AR_LIFT_LPFA, EN_1PH_AR_LIFT_LPFA, EN_MPH_LIFT_LPFA & EN_1PH_LIFT_LPFA

Address: 0x33								
Bit	7	6	5	4	3	2	1	0
Field	EN_MPH_QR_LIFT_LPFA	EN_1PH_QR_LIFT_LPFA	EN_MPH_AR_LIFT_LPFA	EN_1PH_AR_LIFT_LPFA	Reserved	EN_MPH_LIFT_LPFA	Reserved	EN_1PH_LIFT_LPFA
Default	1	0	0	1	0	0	0	1
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7	EN_MPH_QR_LIFT_LPFA	Enable lifting LPF in quick response mode with multi-phase operation of rail A. To enable this function, EN_MPH_LIFT_LPFA must be enabled also. 0: Disable, 1: Enable
6	EN_1PH_QR_LIFT_LPFA	Enable lifting LPF in quick response mode with single-phase operation of rail A. To enable this function, EN_1PH_LIFT_LPFA must be enabled also. 0: Disable, 1: Enable
5	EN_MPH_AR_LIFT_LPFA	Enable lifting LPF in adaptive ramp mode with multi-phase operation of rail A. To enable this function, EN_MPH_LIFT_LPFA must be enabled also. 0: Disable, 1: Enable
4	EN_1PH_AR_LIFT_LPFA	Enable lifting LPF in adaptive ramp mode with single-phase operation of rail A. To enable this function, EN_1PH_LIFT_LPFA must be enabled also. 0: Disable, 1: Enable
3	Reserved	Unimplemented, default value is 0
2	EN_MPH_LIFT_LPFA	Enable lifting LPF in quick response or adaptive ramp mode with multi-phase operation of rail A 0: Disable, 1: Enable
1	Reserved	Unimplemented, default value is 0
0	EN_1PH_LIFT_LPFA	Enable lifting LPF in quick response or adaptive ramp mode with single-phase operation of rail A 0: Disable, 1: Enable

Table 44. EN_HF_ACLL_QRA, SEL_HF_ACLL_QR_FREQA, EN_HF_ACLL_SQRA, SEL_HF_ACLL_SQR_FREQA

Address: 0x34								
Bit	7	6	5	4	3	2	1	0
Field	EN_HF_ACLL_QRA	SEL_HF_ACLL_QR_FREQA			EN_HF_ACLL_SQRA	SEL_HF_ACLL_SQR_FREQA		
Default	1	1	0	0	1	0	1	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	EN_HF_ACLL_QRA	Enable quick response at ACLL frequency is larger than SEL_HF_ACLL_QR_FREQ of rail A 0: Enable 1: Disable
6:4	SEL_HF_ACLL_QR_FREQA	Select the ACLL frequency threshold that will disable quick response of rail A 000: 402kHz, 001: 443kHz, 010: 483kHz, 011: 523kHz, 100: 564kHz, 101: 604kHz, 110: 644kHz, 111: 684kHz
3	EN_HF_ACLL_SQRA	Shrink quick response of rail A when ACLL frequency is larger than SEL_HF_ACLL_SQR_FREQA 0: Disable, 1: Enable
2:0	SEL_HF_ACLL_SQR_FREQA	Select ACLL frequency that will shrink quick response of rail A 000: 161kHz, 001: 201kHz, 010: 241kHz, 011: 282kHz, 100: 322kHz, 101: 362kHz, 110: 402kHz, 111: 443kHz

Table 45. EN_EX_25MV_FLT_RAMPB & SEL_HF_ACLL_QR_FREQB

Address: 0x35								
Bit	7	6	5	4	3	2	1	0
Field	EN_EX_25MV_FLT_RAMPB	SEL_HF_ACLL_QR_FREQB			Reserved			
Default	0	1	1	1	1	0	0	1
Type	RW	RW			RW			

Bit	Name	Description
7	EN_EX_25MV_FLT_RAMPB	Enable extra 25mV on floating ramp of rail B 0: Disable, 1: Enable
6:4	SEL_HF_ACLL_QR_FREQB	Select the ACLL frequency threshold that will disable quick response of rail B 000: Disable, 001: 475kHz, 010: 517kHz, 011: 559kHz, 100: 601kHz, 101: 642kHz, 110: 682kHz, 111: 724kHz
3:0	Reserved	Default value 0b1001, not change

Table 46. SEL_QR_WIDTHB & SEL_FLT_RAMPB

Address: 0x36								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				SEL_QR_WIDTHB		SEL_FLT_RAMPB	
Default	1	1	0	0	0	1	1	1
Type	RW				RW		RW	

Bit	Name	Description
7:4	Reserved	Default value 0b1100, not change
3:2	SEL_QR_WIDTHB	Select PWM width in quick response mode of rail B 00: 0.475 x tON, 01: 0.533 x tON, 10: 0.615 x tON, 11: 0.726 x tON
1:0	SEL_FLT_RAMPB	Select floating ramp threshold of rail B EN_EX_25MV_FLT_RAMPB = 0, 00: 125mV, 01: 175mV, 10: 225mV, 11: Disable EN_EX_25MV_FLT_RAMPB = 1, 00: 150mV, 01: 200mV, 10: 250mV, 11: Disable

Table 47. EN_QR_LIFT_VIDC, EN_EX_TONB, SEL_EX_TON_WIDTHB & SEL_EX_TON_THB

Address: 0x37								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		EN_QR_LIFT_VIDC	EN_EX_TONB	SEL_EX_TON_WIDTHB		SEL_EX_TON_THB	
Default	0	0	0	0	0	0	0	1
Type	RW		RW	RW	RW		RW	

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	EN_QR_LIFT_VIDC	Enable lifting VID in quick response of rail C 0: Enable, 1: Disable
4	EN_EX_TONB	Enable the extend ton of rail B 0: Disable, 1: Enable
3:2	SEL_EX_TON_WIDTHB	Select extend ton width of rail B 00: 4 x ton, 01: 2.66 x ton, 10: 2 x ton, 11: 1.6 x ton
1:0	SEL_EX_TON_THB	Select extend ton threshold of rail B 00: 2.4V + 150mV, 01: 2.4V + 200mV, 10: 2.4V + 250mV, 11: 2.4V + 300mV

Table 48. EN_EX_25MV_FLT_RAMPC & SEL_HF_ACLL_QR_FREQC

Address: 0x38								
Bit	7	6	5	4	3	2	1	0
Field	EN_EX_25MV_FLT_RAMPC		SEL_HF_ACLL_QR_FREQC			Reserved		
Default	0		1	1	1	1	0	0
Type	RW		RW			RW		

Bit	Name	Description
7	EN_EX_25MV_FLT_RAMPC	Enable extra 25mV on floating ramp of rail C 0: Disable, 1: Enable
6:4	SEL_HF_ACLL_QR_FREQC	Select the ACLL frequency threshold that will disable quick response of rail C 000: Disable, 001: 475kHz, 010: 517kHz, 011: 559kHz, 100: 601kHz, 101: 642kHz, 110: 682kHz, 111: 724kHz
3:0	Reserved	Default value 0b1001, not change

Table 49. SEL_QR_WIDTHC & SEL_FLT_RAMPC

Address: 0x39								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				SEL_QR_WIDTHC		SEL_FLT_RAMPC	
Default	1	1	0	0	0	1	1	1
Type	RW				RW		RW	

Bit	Name	Description
7:4	Reserved	Default value 0b1100, not change
3:2	SEL_QR_WIDTHC	Select PWM width in quick response mode of rail C 00: 0.475 x tON, 01: 0.533 x tON, 10: 0.615 x tON, 11: 0.726 x tON
1:0	SEL_FLT_RAMPC	Select floating ramp threshold of rail C EN_EX_25MV_FLT_RAMPC = 0 00: 125mV, 01: 175mV, 10: 225mV, 11: Disable EN_EX_25MV_FLT_RAMPC = 1 00: 150mV, 01: 200mV, 10: 250mV, 11: Disable

Table 50. EN_EX_TONC, SEL_EX_TON_WIDTHC & SEL_EX_TON_THC

Address: 0x3A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved			EN_EX_TONC	SEL_EX_TON_WIDTHC		SEL_EX_TON_THC	
Default	0	0	0	0	0	0	0	1
Type	RW			RW	RW		RW	

Bit	Name	Description
7:5	Reserved	Unimplemented, default value is 0b000
4	EN_EX_TONC	Enable the extend tON of rail C 0: Disable, 1: Enable
3:2	SEL_EX_TON_WIDTHC	Select extend tON width of rail C 00: 4 x tON, 01: 2.66 x tON, 10: 2 x tON, 11: 1.6 x tON
1:0	SEL_EX_TON_THC	Select extend tON threshold of rail C 00: 2.4V + 150mV, 01: 2.4V + 200mV, 10: 2.4V + 250mV, 11: 2.4V + 300mV

Table 51. SEL_PH_TYPEA & SEL_PH_TYPEB & SEL_PH_TYPEC

Address: 0x3B								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_PH_TYPEA		SEL_PH_TYPEB		SEL_PH_TYPEC	
Default	0	0	0	0	0	0	0	0
Type	RW		RW		RW		RW	

Bit	Name	Description
7:6	Reserved	Default value 0b00, not change
5:4	SEL_PH_TYPEA	Select the phase type of rail A 00: Normal 01: One PWM to two phases with phase doubler 10: One PWM to two phases without phase doubler 11: Extend to nine phases with phase doubler
3:2	SEL_PH_TYPEB	Select the phase type of rail B 00: Normal 01: Unimplemented 10: One PWM to two phases without phase doubler 11: Unimplemented
1:0	SEL_PH_TYPEC	Select the phase type of rail C 00: Normal 01: Unimplemented 10: One PWM to two phases without phase doubler 11: Unimplemented

Table 52. SET_SUM_OCPA

Address: 0x3C								
Bit	7	6	5	4	3	2	1	0
Field	SET_SUM_OCPA							
Default	1	0	0	0	0	0	1	0
Type	RW							

Bit	Name	Description
7:0	SET_SUM_OCPA	Set sum OCP of rail A which can be set from 00h to FFh representing 0A to 1020A. Resolution = 4A/LSB. Maximum ratio value SET_SUM_OCPA / ICCMAXA is limited at 6.5 [e.g.] SET_SUM_OCPA = 0x64, SUM_OCPA = 400A SET_SUM_OCPA = 0xFF, SUM_OCPA = 1020A

Table 53. SET_IMON_RPT_OFSA

Address: 0x3D								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_IMON_RPT_OFSA					
Default	1	0	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Default value 0b10, not change
5:0	SET_IMON_RPT_OFSA	Set the offset of IMONA in the range from –32 to +31, representing by 2's complement method [e.g.] SET_IMON_RPT_OFSTA = 0b000101, IMON_RPT_OFSTA = +5 SET_IMON_RPT_OFSTA = 0b111011, IMON_RPT_OFSTA = –5

Table 54. SET_IMON_RPT_OFSB

Address: 0x3E								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_IMON_RPT_OFSB					
Default	0	0	0	0	0	0	0	0
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7:6	Reserved	Default value 0b00, not change
5:0	SET_IMON_RPT_OFSB	Set the offset of IMONB in the range from –32 to +31, representing by 2's complement method [e.g.] SET_IMON_RPT_OFSTB = 0b000101, IMON_RPT_OFSTB = +5 SET_IMON_RPT_OFSTB = 0b111011, IMON_RPT_OFSTB = –5

Table 55. SET_IMON_RPT_OFSC

Address: 0x3F								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_IMON_RPT_OFSC					
Default	0	0	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Default value 0b00, not change
5:0	SET_IMON_RPT_OFSC	Set the offset of IMONC in the range from -32 to +31, representing by 2's complement method [e.g.] SET_IMON_RPT_OFSTC = 0b000101, IMON_RPT_OFSTC = +5 SET_IMON_RPT_OFSTC = 0b111011, IMON_RPT_OFSTC = -5

Table 56. SEL_PSK_LIFT_VID

Address: 0x40								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	SEL_PSK_LIFT_VID			Reserved			
Default	1	1	0	0	1	1	1	1
Type	RW	RW			RW			

Bit	Name	Description
7	Reserved	Default value 1, not change
6:4	SEL_PSK_LIFT_VID	Select lift VID amount in PSK mode 000: 0mV for rail A, B and C 001: 0mV for rail A, 5mV for rail B and C 010: 5mV for rail A, 0mV for rail B and C 011: 0mV for rail A, 10mV for rail B and C 100: 5mV for rail A, B and C 101: 5mV for rail A, 10mV for rail B and C 110: 10mV for rail A, 5mV for rail B and C 111: 10mV for rail A, B and C
3:0	Reserved	Default value 0b1111, not change

Table 57. EN_AUTO_TONA, SEL_AUTO_TON_MAXA, EN_AUTO_TONB & SEL_AUTO_TON_MAXB

Address: 0x41								
Bit	7	6	5	4	3	2	1	0
Field	EN_AUTO_TONA	SEL_AUTO_TON_MAXA			EN_AUTO_TONB	SEL_AUTO_TON_MAXB		
Default	1	0	1	1	1	0	1	1
Type	RW	RW			RW	RW		

Bit	Name	Description
7	EN_AUTO_TONA	Enable limit the switching frequency in the range from 10 to 20kHz in PSK mode of rail A 0: Enable, 1: Disable
6:4	SEL_AUTO_TON_MAXA	Select the ton derating percentage in PSK mode of rail A 000: 100%, 001: 91.67%, 010: 83.33%, 011: 75%, 100: 66%, 101: 58.33%, 110: 50%, 111: 42%
3	EN_AUTO_TONB	Enable limit the switching frequency in the range from 10 to 20kHz in PSK mode of rail B 0: Enable, 1: Disable
2:0	SEL_AUTO_TON_MAXB	Select the ton derating percentage in PSK mode of rail B 000: 100%, 001: 91.67%, 010: 83.33%, 011: 75%, 100: 66%, 101: 58.33%, 110: 50%, 111: 42%

Table 58. EN_AUTO_TONC & SEL_AUTO_TON_MAXC

Address: 0x42								
Bit	7	6	5	4	3	2	1	0
Field	EN_AUTO_TONC	SEL_AUTO_TON_MAXC			Reserved			
Default	1	0	1	1	1	0	0	0
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7	EN_AUTO_TONC	Enable limit the switching frequency in the range from 10 to 20kHz in PSK mode of rail C 0: Enable, 1: Disable
6:4	SEL_AUTO_TON_MAXC	Select the ton derating percentage in PSK mode of rail C 000: 100%, 001: 91.67%, 010: 83.33%, 011: 75%, 100: 66%, 101: 58.33%, 110: 50%, 111: 42%
3:0	Reserved	Default value 0b1000, not change

Table 59. SEL_HOLD_LPF_THA, SEL_HOLD_LPF_THB & SEL_HOLD_LPF_THC

Address: 0x44								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_HOLD_LPF_THA		SEL_HOLD_LPF_THB		SEL_HOLD_LPF_THC	
Default	1	1	0	0	1	0	1	1
Type	RW		RW		RW		RW	

Bit	Name	Description
7:6	Reserved	Default value 0b11, not change
5:4	SEL_HOLD_LPF_THA	Select the threshold of difference between VSENA and VFBA to hold LPF in PSK mode of rail A 00: 0mV, 01: 2.5mV, 10: 5mV, 11: 7.5mV
3:2	SEL_HOLD_LPF_THB	Select the threshold of difference between VSENB and VFBB to hold LPF in PSK mode of rail B 00: 0mV, 01: 2.5mV, 10: 5mV, 11: 7.5mV
1:0	SEL_HOLD_LPF_THC	Select the threshold of difference between VSENC and VFBC to hold LPF in PSK mode of rail C 00: 0mV, 01: 2.5mV, 10: 5mV, 11: 7.5mV

Table 60. SEL_RST_LPF_CURRA & SEL_RST_LPF_CURB & SEL_RST_LPF_CURRC

Address: 0x45								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SEL_RST_LPF_CURRA		SEL_RST_LPF_CURRB		SEL_RST_LPF_CURRC	
Default	1	0	1	1	0	0	1	1
Type	RW		RW		RW		RW	

Bit	Name	Description
7:6	Reserved	Default value 0b10, not change
5:4	SEL_RST_LPF_CURRA	Select the reset LPF current of rail A 00: 0.5 μ A, 01: 1 μ A, 10: 1.5 μ A, 11: 2 μ A
3:2	SEL_RST_LPF_CURRB	Select the reset LPF current of rail B 00: 0.5 μ A, 01: 1 μ A, 10: 1.5 μ A, 11: 2 μ A
1:0	SEL_RST_LPF_CURRC	Select the reset LPF current of rail C 00: 0.5 μ A, 01: 1 μ A, 10: 1.5 μ A, 11: 2 μ A

Table 61. EN_ANSA, EN_ANSB & EN_ANSC

Address: 0x46								
Bit	7	6	5	4	3	2	1	0
Field	Reserved					EN_ANSA	EN_ANSB	EN_ANSC
Default	1	1	1	1	1	0	0	0
Type	RW					RW	RW	RW

Bit	Name	Description
7:3	Reserved	Default value 0b11111, not change
2	EN_ANSA	Enable acoustic noise suppression function of rail A 0: Disable, 1: Enable
1	EN_ANSB	Enable acoustic noise suppression function of rail B 0: Disable, 1: Enable
0	EN_ANSC	Enable acoustic noise suppression function of rail C 0: Disable, 1: Enable

Table 62. SEL_I_DVID_DROOPA, SEL_LIFT_VIDB & SEL_I_DVID_DROOPB

Address: 0x47								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	SEL_I_DVID_DROOPA			SEL_LIFT_VIDB		SEL_I_DVID_DROOPB	
Default	1	0	0	0	0	0	1	0
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7	Reserved	Default value 1, not change
6:4	SEL_I_DVID_DROOPA	Select the ratio of compensation current I_{DVID_DROOP} to I_{DVID_LIFT} during DVID down period of rail A 000: 0.6, 001: 0.7, 010: 0.8, 011: 0.9, 100: 1.0, 101: 1.1, 110: 1.2, 111: 1.3
3	SEL_LIFT_VIDB	Select lifting VID amount of rail B 0: 5mV, 1: 10mV
2:0	SEL_I_DVID_DROOPB	Select the ratio of compensation current I_{DVID_DROOP} to I_{DVID_LIFT} during DVID down period of rail B 000: 0.6, 001: 0.7, 010: 0.8, 011: 0.9, 100: 1.0, 101: 1.1, 110: 1.2, 111: 1.3

Table 63. SEL_LIFT_VIDC & SEL_I_DVID_DROOPC

Address: 0x48								
Bit	7	6	5	4	3	2	1	0
Field	SEL_LIFT_VIDC	SEL_I_DVID_DROOPC			Reserved			
Default	0	0	0	1	1	1	1	1
Type	RW	RW			RW			

Bit	Name	Description
7	SEL_LIFT_VIDC	Select lifting VID amount of rail C 0: 5mV, 1: 10mV
6:4	SEL_I_DVID_DROOPC	Select the ratio of compensation current I_{DVID_DROOP} to I_{DVID_LIFT} during DVID down period of rail C 000: 0.6, 001: 0.7, 010: 0.8, 011: 0.9, 100: 1.0, 101: 1.1, 110: 1.2, 111: 1.3
3:0	Reserved	Default value 0b1111, not change

Table 64. SEL_MPH_LPF_LIMITA & SEL_MPH_LPF_LIMIT_HYSA

Address: 0x49								
Bit	7	6	5	4	3	2	1	0
Field	SEL_MPH_LPF_LIMITA				SEL_MPH_LPF_LIMIT_HYSA			
Default	0	1	1	1	0	0	1	0
Type	RW				RW			

Bit	Name	Description
7:4	SEL_MPH_LPF_LIMITA	Select multi-phase LPF limit of rail A 0000: 100mV, 0001: 120mV, 0010: 140mV, 0011: 160mV, 0100: 180mV, 0101: 200mV, 0110: 220mV, 0111: 240mV, 1000: 260mV, 1001: 280mV, 1010: 300mV, 1011: 320mV, 1100: 340mV, 1101: 360mV, 1110: 380mV, 1111: 400mV
3:0	SEL_MPH_LPF_LIMIT_HYSA	Select multi-phase hysteresis of LPF limit of rail A 0000: 0mV, 0001: 20mV, 0010: 40 mV, 0011: 60 mV, 0100: 80mV, 0101: 100mV, 0110: 120mV, 0111: 140mV, 1000: 160mV, 1001: 180mV, 1010: 200mV, 1011: 220mV, 1100: 240mV, 1101: 260mV, 1110: 280mV, 1111: 300mV

Table 65. SEL_1PH_LPF_LIMITA & SEL_1PH_LPF_LIMIT_HYSA

Address: 0x4A								
Bit	7	6	5	4	3	2	1	0
Field	SEL_1PH_LPF_LIMITA				SEL_1PH_LPF_LIMIT_HYSA			
Default	0	0	1	1	0	1	0	0
Type	RW				RW			

Bit	Name	Description
7:4	SEL_1PH_LPF_LIMITA	Select single-phase LPF limit of rail A 0000: 50mV, 0001: 60mV, 0010: 70mV, 0011: 80mV, 0100: 90mV, 0101: 100mV, 0110: 110mV, 0111: 120mV, 1000: 130mV, 1001: 140mV, 1010: 150mV, 1011: 160mV, 1100: 170mV, 1101: 180mV, 1110: 190mV, 1111: 200mV
3:0	SEL_1PH_LPF_LIMIT_HYSA	Select single-phase hysteresis of LPF limit of rail A 0000: 0mV, 0001: 10mV, 0010: 20mV, 0011: 30mV, 0100: 40mV, 0101: 50mV, 0110: 60mV, 0111: 70mV, 1000: 80mV, 1001: 90mV, 1010: 100mV, 1011: 110mV, 1100: 120mV, 1101: 130mV, 1110: 140mV, 1111: 150mV

Table 66. SEL_1PH_LPF_LIMITB & SEL_1PH_LPF_LIMITC

Address: 0x4D								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	SEL_1PH_LPF_LIMITB			Reserved	SEL_1PH_LPF_LIMITC		
Default	0	1	0	0	0	1	1	1
Type	RW	RW			RW	RW		

Bit	Name	Description
7	Reserved	Default value 0, not change
6:4	SEL_1PH_LPF_LIMITB	Select LPF limit of rail B 000: Disable, 001: 150mV, 010: 200mV, 011: 250mV, 100: 300mV, 101: 350mV, 110: 400mV, 111: 450mV
3	Reserved	Default value 0, not change
2:0	SEL_1PH_LPF_LIMITC	Select LPF limit of rail C 000: Disable, 001: 150mV, 010: 200mV, 011: 250mV, 100: 300mV, 101: 350mV, 110: 400mV, 111: 450mV

Table 67. SEL_LPF_INITB & SEL_LPF_INITC

Address: 0x4E								
Bit	7	6	5	4	3	2	1	0
Field	SEL_LPF_INITB				SEL_LPF_INITC			
Default	0	0	1	0	0	0	1	0
Type	RW				RW			

Bit	Name	Description
7:4	SEL_LPF_INITB	Set initial current of LPF of rail B 0000: -1.5μA, 0001: -0.5μA, 0010: -5μA, 0011: -4μA, 0100: -1μA, 0101: 0μA, 0110: -4μA, 0111: -3μA, 1000: -0.5μA, 1001: +0.5μA, 1010: -3.5μA, 1011: -2.5μA, 1100: 0μA, 1101: +1μA, 1110: -3μA, 1111: -2μA
3:0	SEL_LPF_INITC	Set initial current of LPF of rail C 0000: -1.5μA, 0001: -0.5μA, 0010: -5μA, 0011: -4μA, 0100: -1μA, 0101: 0μA, 0110: -4μA, 0111: -3μA, 1000: -0.5μA, 1001: +0.5μA, 1010: -3.5μA, 1011: -2.5μA, 1100: 0μA, 1101: +1μA, 1110: -3μA, 1111: -2μA

Table 68. SET_VBOOTA

Address: 0x50								
Bit	7	6	5	4	3	2	1	0
Field	SET_VBOOTA							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_VBOOTA	Set VBOOT of rail A, when connecting SD_GOOD pin to GND with resistor. The VID step is setting by SEL_VID_STEP A

Table 69. Reserved

Address: 0x51								
Bit	7	6	5	4	3	2	1	0
Field	Reserved							
Default	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	Reserved	Default value A1h, not change

Table 70. SET_VBOOTB

Address: 0x52								
Bit	7	6	5	4	3	2	1	0
Field	SET_VBOOTB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_VBOOTB	Set VBOOT of rail B, when connecting SD_GOOD pin to GND with resistor. The VID step is setting by SEL_VID_STEP B

Table 71. Reserved

Address: 0x53								
Bit	7	6	5	4	3	2	1	0
Field	Reserved							
Default	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	Reserved	Default value A1h, not change

Table 72. SET_VBOOTC

Address: 0x54								
Bit	7	6	5	4	3	2	1	0
Field	SET_VBOOTC							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_VBOOTC	Set VBOOT of rail C, when connecting SD_GOOD pin to GND with resistor. The VID step is setting by SEL_VID_STEPC

Table 73. Reserved

Address: 0x55								
Bit	7	6	5	4	3	2	1	0
Field	Reserved							
Default	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	Reserved	Default value A1h, not change

Table 74. SEL_SPM_HYSA2 & SEL_SPM_THA2

Address: 0x57								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA2			SEL_SPM_THA2				
Default	0	1	0	1	1	1	1	0
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA2	Select smart phase management hysteresis from 2 phases to 1 phase of rail A [e.g.] SEL_SPM_HYSA2 = 0b010, EN_2X_SPM_HYS = 0, hysteresis = 2.5% of ICCMAXA EN_2X_SPM_HYS = 0, 000: 0%, 001: 1.25%, 010: 2.5%, 011: 3.75%, 100: 5%, 101: 6.25%, 110: 7.5%, 111: 8.75% EN_2X_SPM_HYS = 1, 000: 0%, 001: 2.5%, 010: 5%, 011: 7.5%, 100: 10%, 101: 12.5%, 110: 15%, 111: 17.5%
4:0	SEL_SPM_THA2	Select smart phase management threshold from 1 phase to 2 phases of rail A [e.g.] SEL_SPM_THA2 = 0b00001, threshold = 94% of ICCMAXA 00000: 100%, 00001: 94%, 00010: 88%, 00011: 82%, 00100: 76%, 00101: 70%, 00110: 66%, 00111: 62%, 01000: 58%, 01001: 54%, 01010: 50%, 01011: 48%, 01100: 46%, 01101: 44%, 01110: 42%, 01111: 40%, 10000: 38%, 10001: 36%, 10010: 34%, 10011: 32%, 10100: 30%, 10101: 28%, 10110: 26%, 10111: 24%, 11000: 22%, 11001: 20%, 11010: 18%, 11011: 16%, 11100: 14%, 11101: 12%, 11110: 10%, 11111: 8%

Table 75. SEL_SPM_HYSA3 & SEL_SPM_THA3

Address: 0x58								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA3			SEL_SPM_THA3				
Default	0	0	1	1	1	1	0	0
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA3	Select smart phase management hysteresis from 3 phases to 2 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA3	Select smart phase management threshold from 2 phases to 3 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 76. SEL_SPM_HYSA4 & SEL_SPM_THA4

Address: 0x59								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA4			SEL_SPM_THA4				
Default	0	0	1	1	1	0	1	0
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA4	Select smart phase management hysteresis from 4 phases to 3 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA4	Select smart phase management threshold from 3 phases to 4 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 77. SEL_SPM_HYSA5 & SEL_SPM_THA5

Address: 0x5A								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA5			SEL_SPM_THA5				
Default	0	0	1	1	1	0	0	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA5	Select smart phase management hysteresis from 5 phases to 4 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA5	Select smart phase management threshold from 4 phases to 5 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 78. SEL_SPM_HYSA6 & SEL_SPM_THA6

Address: 0x5B								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA6			SEL_SPM_THA6				
Default	0	0	1	1	1	0	0	0
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA6	Select smart phase management hysteresis from 6 phases to 5 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA6	Select smart phase management threshold from 5 phases to 6 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 79. SEL_SPM_HYSA7 & SEL_SPM_THA7

Address: 0x5C								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA7			SEL_SPM_THA7				
Default	0	0	1	1	0	1	0	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA7	Select smart phase management hysteresis from 7 phases to 6 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA7	Select smart phase management threshold from 6 phases to 7 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 80. SEL_SPM_HYSA8 & SEL_SPM_THA8

Address: 0x5D								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_HYSA8			SEL_SPM_THA8				
Default	0	0	1	1	0	0	1	1
Type	RW			RW				

Bit	Name	Description
7:5	SEL_SPM_HYSA8	Select smart phase management hysteresis from 8 phases to 7 phases of rail A. Bit field definition is the same as SEL_APS_HYSA2
4:0	SEL_SPM_THA8	Select smart phase management threshold from 7 phases to 8 phases of rail A. Bit field definition is the same as SEL_SPM_THA2

Table 81. EN_2X_SPM_HYS & SEL_SPM_TH_RATIO & SEL_SPM_SHED_DLYA

Address: 0x5E								
Bit	7	6	5	4	3	2	1	0
Field	EN_2X_SPM_HYS	SEL_SPM_TH_RATIO		SEL_SPM_SHED_DLYA			Reserved	
Default	1	0	1	0	1	1	0	0
Type	RW	RW		RW			RW	

Bit	Name	Description
7	EN_2X_SPM_HYS	Enable 2X hysteresis of smart phase management 0: Disable, 1: Enable
6:5	SEL_SPM_TH_RATIO	Derating the threshold of smart phase management 00: 100%, 01: 50%, 10: 37.5%, 11: 25%
4:2	SEL_SPM_SHED_DLYA	Select the delay when phase down in smart phase management of rail A 000: 5μs, 001: 3.75μs, 010: 2.5μs, 011: 1.25μs, 100: 20μs, 101: 15μs, 110: 10μs, 111: 5μs
1:0	Reserved	Default value 0b00, not change

Table 82. SEL_ZCD_HYSB & SEL_ZCD_HYSC

Address: 0x5F								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				SEL_ZCD_HYSB		SEL_ZCD_HYSC	
Default	0	0	0	0	0	1	0	1
Type	RW				RW		RW	

Bit	Name	Description
7:4	Reserved	Default value 0b0000, not change
3:2	SEL_ZCD_HYSB	Select the ZCD hysteresis of rail B 00: 0.25mV, 01: 0.5mV, 10: 0.75mV, 11: 1mV
1:0	SEL_ZCD_HYSC	Select the ZCD hysteresis of rail C 00: 0.25mV, 01: 0.5mV, 10: 0.75mV, 11: 1mV

Table 83. SEL_ANS_PS4_BEHAV, EN_DBLR_SPM_1PH_CCM, EN_SPS_TSENA, EN_SPS_TSENB & EN_SPS_TSENC

Address: 0x60								
Bit	7	6	5	4	3	2	1	0
Field	SEL_ANS_PS4_BEHAV	EN_DBLR_SPM_1PH_CCM	Reserved			EN_SPS_TSENA	EN_SPS_TSENB	EN_SPS_TSENC
Default	0	0	1	1	1	0	0	0
Type	RW	RW	RW			RW	RW	RW

Bit	Name	Description
7	SEL_ANS_PS4_BEHAV	Select the SetPS4 behavior when ANS is enable and no action for DVID down (SEL_ANS_BEHAV = 0) 0: ACK for SetPS4 and enter the PS4 1: ACK for SetPS4 and not enter the PS4
6	EN_DBLR_SPM_1PH_CCM	Enable single-phase CCM detection in smart phase management when using phase doubler 0: Disable, 1: Enable
5:3	Reserved	Default value 0b111, not change
2	EN_SPS_TSENA	Enable SPS TSEN table with positive temperature coefficient of rail A 0: Disable, 1: Enable
1	EN_SPS_TSENB	Enable SPS TSEN table with positive temperature coefficient of rail B 0: Disable, 1: Enable
0	EN_SPS_TSENC	Enable SPS TSEN table with positive temperature coefficient of rail C 0: Disable, 1: Enable

Table 84. SEL_SPM_SHED_DLYB, SEL_SPM_SHED_DLYC, SEL_PIN51_CONFIG & EN_2X_Ai_GAINA

Address: 0x61								
Bit	7	6	5	4	3	2	1	0
Field	SEL_SPM_SHED_DLYB			SEL_SPM_SHED_DLYC			SEL_PIN51_CONFIG	EN_2X_Ai_GAINA
Default	0	0	0	0	0	0	0	0
Type	RW			RW			RW	RW

Bit	Name	Description
7:5	SEL_SPM_SHED_DLYB	Select the delay from CCM to DCM in smart phase management of rail B 000: 5 μ s, 001: 3.75 μ s, 010: 2.5 μ s, 011: 1.25 μ s, 100: 20 μ s, 101: 15 μ s, 110: 10 μ s, 111: 5 μ s
4:2	SEL_SPM_SHED_DLYC	Select the delay from CCM to DCM in smart phase management of rail C 000: 5 μ s, 001: 3.75 μ s, 010: 2.5 μ s, 011: 1.25 μ s, 100: 20 μ s, 101: 15 μ s, 110: 10 μ s, 111: 5 μ s
1	SEL_PIN51_CONFIG	Select the configuration of the DRVEN/DBLR_PS pin 0: The DRVEN/DBLR_PS pin is configured as DRVEN, 1: The DRVEN/DBLR_PS pin is configured as DBLR_PS
0	EN_2X_Ai_GAINA	Enable double Ai gain of rail A 0: Disable, 1: Enable

Table 85. SET_SPS_TSEN_RPT_OFSA

Address: 0x62								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_SPS_TSEN_RPT_OFSA					
Default	0	0	1	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5:0	SET_SPS_TSEN_RPT_OFSA	Set the reporting offset of SPS TSEN of rail A in the range from –32 to +31. 000000: –31, 000001: –31, 000010: –30, 000011: –29, 000100: –28, 000101: –27, 000110: –26, 000111: –25, 001000: –24, 001001: –23, 001010: –22, 001011: –21, 001100: –20, 001101: –19, 001110: –18, 001111: –17, 010000: –16, 010001: –15, 010010: –14, 010011: –13, 010100: –12, 010101: –11, 010110: –10, 010111: –9, 011000: –8, 011001: –7, 011010: –6, 011011: –5, 011100: –4, 011101: –3, 011110: –2, 011111: –1 100000: 0, 100001: 1, 100010: 2, 100011: 3, 100100: 4, 100101: 5, 100110: 6, 100111: 7, 101000: 8, 101001: 9, 101010: 10, 101011: 11, 101100: 12, 101101: 13, 101110: 14, 101111: 15, 110000: 16, 110001: 17, 110010: 18, 110011: 19, 110100: 20, 110101: 21, 110110: 22, 110111: 23, 111000: 24, 111001: 25, 111010: 26, 111011: 27, 111100: 28, 111101: 29, 111110: 30, 111111: 31

Table 86. SET_SPS_TSEN_RPT_OFSB

Address: 0x63								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_SPS_TSEN_RPT_OFSB					
Default	0	0	1	0	0	0	0	0
Type	RW	RW	RW	RW	RW	RW	RW	RW

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5:0	SET_SPS_TSEN_RPT_OFSB	Set the reporting offset of SPS TSEN of rail B in the range from –32 to +31. Bit field definition is the same as SET_SPS_TSEN_RPT_OFSA

Table 87. SET_SPS_TSEN_RPT_OFSC

Address: 0x64								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SET_SPS_TSEN_RPT_OFSC					
Default	0	0	1	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5:0	SET_SPS_TSEN_RPT_OFSC	Set the reporting offset of SPS TSEN of rail C in the range from -32 to +31. Bit field definition is the same as SET_SPS_TSEN_RPT_OFSA

Table 88. SET_CODE_VER_LB

Address: 0x70								
Bit	7	6	5	4	3	2	1	0
Field	SET_CODE_VER_LB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_CODE_VER_LB	Set the low byte of the code version

Table 89. SET_CODE_VER_HB

Address: 0x71								
Bit	7	6	5	4	3	2	1	0
Field	SET_CODE_VER_HB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_CODE_VER_HB	Set the high byte of the code version

Table 90. SET_PRODUCT_ID

Address: 0x74								
Bit	7	6	5	4	3	2	1	0
Field	SET_PRODUCT_ID							
Default	0	0	1	1	1	0	0	0
Type	RW							

Bit	Name	Description
7:0	SET_PRODUCT_ID	Set the product ID. Default value is 0x38

Table 91. CRC

Address: 0x7F								
Bit	7	6	5	4	3	2	1	0
Field	CRC							
Default	--	--	--	--	--	--	--	--
Type	R							

Bit	Name	Description
7:0	CRC	Cyclic redundancy check

Table 92. CBGA1 & CBGA2

Address: 0x90								
Description: Adjust current balance gain of phase 1 and 2 of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	CBGA1			Reserved	CBGA2		
Default	0	1	0	0	0	1	0	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6:4	CBGA1	000: 69.2%, 001: 76.9%, 010: 84.6%, 011: 92.3%, 100: 100% (default), 101: 107.69%, 110: 115.38%, 111: 123.08%
3	Reserved	Unimplemented, default value is 0
2:0	CBGA2	Bit field definition and default value is the same as CBGA1

Table 93. CBGA3 & CBGA4

Address: 0x91								
Description: Adjust current balance gain of phase 3 and 4 of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	CBGA3			Reserved	CBGA4		
Default	0	1	0	0	0	1	0	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6:4	CBGA3	Bit field definition and default value is the same as CBGA1
3	Reserved	Unimplemented, default value is 0
2:0	CBGA4	Bit field definition and default value is the same as CBGA1

Table 94. CBGA5 & CBGA6

Address: 0x92								
Description: Adjust current balance gain of phase 5 and 6 of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	CBGA5			Reserved	CBGA6		
Default	0	1	0	0	0	1	0	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6:4	CBGA5	Bit field definition and default value is the same as CBGA1
3	Reserved	Unimplemented, default value is 0
2:0	CBGA6	Bit field definition and default value is the same as CBGA1

Table 95. CBGA7 & CBGA8

Address: 0x93								
Description: Adjust current balance gain of phase 7 and 8 of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	CBGA7			Reserved	CBGA8		
Default	0	1	0	0	0	1	0	0
Type	RW	RW			RW	RW		

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6:4	CBGA7	Bit field definition and default value is the same as CBGA1
3	Reserved	Unimplemented, default value is 0
2:0	CBGA8	Bit field definition and default value is the same as CBGA1

Table 96. VFIXA_LB

Address: 0x94								
Description: 9-bit fixed VID (Reg. 0x94 + Reg. 0x95). Set voltage in fixed VID mode of rail A. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts $\overline{\text{ALERT}}$ immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXA_LB							
Default (VID1)	1	0	0	0	0	0	1	1
Default (VID2)	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	VFIXA_LB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXA_HB [0] = 00h + VFIXA_LB[7:0] = 00h) SEL_VID_STEPA = 0, Voltage of fixed VID mode = 0.245V + (VFIXA_HB [0]+VFIXA_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPA = 1, Voltage of fixed VID mode = 0.19V + (VFIXA_HB [0] + VFIXA_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

Table 97. VFIXA_HB

Address: 0x95								
Description: 9-bit fixed VID (Reg. 0x94 + Reg. 0x95). Set voltage in fixed VID mode of rail A. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts $\overline{\text{ALERT}}$ immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXA_HB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VFIXA_HB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXA_HB [0] = 00h + VFIXA_LB[7:0] = 00h) SEL_VID_STEPA = 0, Voltage of fixed VID mode = 0.245V + (VFIXA_HB [0]+VFIXA_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPA = 1, Voltage of fixed VID mode = 0.19V + (VFIXA_HB [0] + VFIXA_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

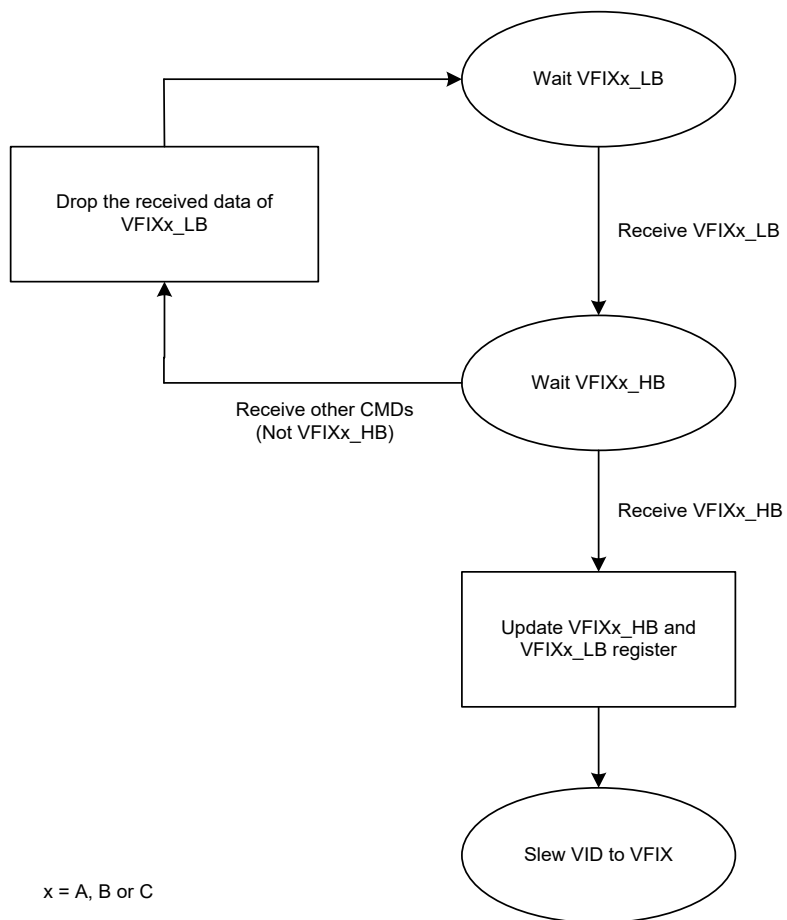


Figure 32. Control Logic of Command VFIX

Table 98. VOFS A

Address: 0x96								
Description: Setting offset voltage of rail A. For VID1 the final voltage limiting range 0.25V to 2.17V. (i.e., $0.25V \leq \text{VID setting} \pm \text{SVID offset voltage} \pm \text{I}^2\text{C offset voltage} \leq 2.17V$) For VID2 the final voltage limiting range 0.2V to 3.04V. The offset slew rate is 1/2 of the fast slew rate. While setting voltage offset, the VR should return to power state PS0. After VSEN settles at the target offset voltage, the power state (PS) goes back to the original PS. If CPU sends SetPS1/2/3 command, the controller follows PS and the voltage offset still exists. If CPU sends SetVID off code command ($\text{VID setting} \pm \text{SVID offset voltage} \pm \text{I}^2\text{C offset voltage}$), the controller sets output voltage to 0V.								
Bit	7	6	5	4	3	2	1	0
Field	VOFS A							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFS A	[7:0] = 00h: No offset [7]: Sign bit (as part of two's complement) [6:0]: 5mV/step (SEL_VID_STEPA = 0) or 10mV/step (SEL_VID_STEPA = 1) [e.g.] 0b00000001 = current VID + (1 x VID step) 0b00000011 = current VID + (3 x VID steps) 0b11111111 = current VID - (1 x VID step)

Table 99. TEMP_ALERT & TEMP_VRHOT

Address: 0x97								
Description: Setting rail A's ALERT temperature and thermal VRHOT temperature. VRHOT temperature should be higher than ALERT temperature. While VRHOT temperature smaller than the thermal ALERT temperature. VR will force ALERT temperature smaller than VRHOT temperature (TEMP_VRHOTA[7:4] = TEMP_ALERTA[3:0]).								
Bit	7	6	5	4	3	2	1	0
Field	TEMP_ALERTA				TEMP_VRHOTA			
Default	0	1	1	0	0	1	1	0
Type	RW							

Bit	Name	Description
7:4	TEMP_ALERTA	Select thermal ALERT temperature of rail A. Temperature versus V _{THERMAL} refer to Table 105. 0000: 75°C, 0001: 82°C, 0010: 85°C, 0011: 88°C, 0100: 91°C, 0101: 94°C, 0110: 97°C, 0111: 100°C, 1000: 103°C, 1001: 106°C, 1010: 109°C, 1011: 112°C, 1100: 115°C, 1101: 118°C, 1110: 121°C, 1111: 124°C
3:0	TEMP_VRHOTA	Select VRHOT temperature of rail A. Temperature versus V _{THERMAL} refer to Table 105. 0000: 82°C, 0001: 85°C, 0010: 88°C, 0011: 91°C, 0100: 94°C, 0101: 97°C, 0110: 100°C, 0111: 103°C, 1000: 106°C, 1001: 109°C, 1010: 112°C, 1011: 115°C, 1100: 118°C, 1101: 121°C, 1110: 124°C, 1111: 127°C

Table 100. SUM_OCP_DEB_TIMEA & EN_SS_OCPA & EN_SUM_OCPA & EN_NVA & EN_OVA

Address: 0x98								
Description: Enable protection function of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SUM_OCP_DEB_T IMEA	EN_SS_ OCPA	EN_SUM_ _OCPA	EN_NVA	Reserved	EN_OVA
Default	0	0	-	-	1	0	1	1
Type	RW		RW	RW	RW	RW	RW	RW

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	SUM_OCP_DEB_TIMEA	0: 20 μ s, 1: 40 μ s Default value is from SEL_SUM_OCP_DEB_TIMEA (0x2B[7]) in setting function table
4	EN_SS_OCPA	0: Disable soft-start OC protection, 1: Enable soft-start OC protection Default value is from EN_SS_OCPA (0x2F[2]) in setting function table
3	EN_SUM_OCPA	0: Disable sum OC protection, 1: Enable sum OC protection (default)
2	EN_NVA	0: Disable NV protection, 1: Enable NV protection
1	Reserved	Default value 1, not change
0	EN_OVA	0: Disable OV protection, 1: Enable OV protection (default)

Table 101. OCA, NVA & UVA & OVA

Address: 0x99								
Description: Protection indicator of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				OCA	NVA	UVA	OVA
Default	0	0	0	0	0	0	0	0
Type	R				R	R	R	R

Bit	Name	Description
7:4	Reserved	Unimplemented, default value is 0b0000
3	OCA	0: No occurrence of OCP, 1: Occurrence of OCP
2	NVA	0: No occurrence of negative-voltage protection (NVP), 1: Occurrence of NVP
1	UVA	0: No occurrence UVP, 1: Occurrence UVP
0	OVA	0: No occurrence of OVP, 1: Occurrence of OVP

Table 102. ILOAD_RPTA

Address: 0x9A								
Description: Output current reporting of rail A								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPTA							
Default	-	-	-	-	-	-	-	-
Type	R							

Bit	Name	Description
7:0	ILOAD_RPTA	Output current reporting

Table 103. PSYS_RPT

Address: 0x9B								
Description: PSYS reporting								
Bit	7	6	5	4	3	2	1	0
Field	PSYS_RPT							
Default	-	-	-	-	-	-	-	-
Type	R							

Bit	Name	Description
7:0	PSYS_RPT	PSYS reporting

Table 104. TEMP_RPTA

Address: 0x9C								
Description: Temperature reporting of rail A								
Bit	7	6	5	4	3	2	1	0
Field	TEMP_RPTA							
Default	--	--	--	--	--	--	--	--
Type	R							

Bit	Name	Description
7:0	TEMP_RPTA	$V_{THERMAL} = TEMP_RPTA \times 6.25mV$. Temperature versus $V_{THERMAL}$ refer to Table 105.

Table 105. V_{THERMAL} vs Temperature (based on the R_{NTC} = 100k/Beta = 4250K)

Temperature (°C)	V _{THERMAL} (V)	Temperature (°C)	V _{THERMAL} (V)	Temperature (°C)	V _{THERMAL} (V)	Temperature (°C)	V _{THERMAL} (V)
61	1.133	81	0.814	101	0.591	121	0.453
62	1.116	82	0.800	102	0.582	122	0.447
63	1.098	83	0.787	103	0.574	123	0.442
64	1.080	84	0.774	104	0.566	124	0.437
65	1.063	85	0.761	105	0.558	125	0.432
66	1.046	86	0.749	106	0.550	126	0.428
67	1.029	87	0.737	107	0.542	127	0.423
68	1.012	88	0.725	108	0.534	128	0.419
69	0.995	89	0.713	109	0.527	129	0.414
70	0.979	90	0.702	110	0.520	130	0.410
71	0.963	91	0.690	111	0.513		
72	0.947	92	0.679	112	0.506		
73	0.931	93	0.669	113	0.500		
74	0.916	94	0.658	114	0.493		
75	0.900	95	0.648	115	0.487		
76	0.885	96	0.638	116	0.481		
77	0.871	97	0.628	117	0.475		
78	0.856	98	0.618	118	0.469		
79	0.842	99	0.609	119	0.463		
80	0.828	100	0.600	120	0.458		

Table 106. VOFS_LOAD_HYSA & VOFS_LOAD_THA

Address: 0x9E								
Description: Load condition for VID offset of rail A								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_HYSA		VOFS_LOAD_THA					
Default	1	0	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	VOFS_LOAD_HYSA	Select the current hysteresis 00: 4A, 01: 8A, 10: 12A, 11: 16A
5:0	VOFS_LOAD_THA	Set the current threshold from 0A to 504A with 8A/LSB

Table 107. ILOAD_RPT_RATIOA & FORCE_PS0A & KTONA

Address: 0x9F								
Description: Adjust output current reporting ratio, enable or disable force PS0 function and K _{TON} of rail A								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPT_RATIOA		Reserved	FORCE_PS0A	Reserved	KTONA		
Default	0	0	0	0	0	0	0	0
Type	RW		RW	RW	RW	RW		

Bit	Name	Description
7:6	ILOAD_RPT_RATIOA	Output current reporting ratio 00: 100%, 01: 87.5%, 10: 75%, 11: 50%
5	Reserved	Unimplemented, default value is 0
4	FORCE_PS0A	Enable this function, VR will stay at PS0 even though SetPS PS1, PS2 or PS3 command is received 0: Disable, 1: Enable
3	Reserved	Unimplemented, default value is 0
2:0	KTONA	On time factor K _{TON} . Refer to the section Switching Frequency Setting for the details. Default value is from SEL_KTONA (0x15[6:4]) in setting function table

Table 108. EN_FVMA & EN_FVMB & EN_FVMC

Address: 0xA0								
Description: Enable Fast V-Mode current limit function								
Bit	7	6	5	4	3	2	1	0
Field	Reserved	EN_FVMA	EN_FVMB	EN_FVMC	Reserved			
Default	0	1	1	1	0	0	0	0
Type	RW	RW	RW	RW	RW			

Bit	Name	Description
7	Reserved	Unimplemented, default value is 0
6	EN_FVMA	Enable Fast V-Mode current limit function of rail A 0: Disable, 1: Enable
5	EN_FVMB	Enable Fast V-Mode current limit function of rail B 0: Disable, 1: Enable
4	EN_FVMC	Enable Fast V-Mode current limit function of rail C 0: Disable, 1: Enable
3:0	Reserved	Unimplemented, default value is 0b0000

Table 109. EN_SPMA

Address: 0xA3								
Description: SPM threshold, enable and hysteresis related settings of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				EN_SPMA	Reserved		
Default	0	0	0	0	--	0	0	0
Type	RW				RW	RW		

Bit	Name	Description
7:4	Reserved	Unimplemented, default value is 0b0000
3	EN_SPMA	Enable smart phase management function. Default value is 0.
2:0	Reserved	Unimplemented, default value is 0b000

Table 110. EN_ANSA & SMALL_LLA

Address: 0xA7								
Description: Enable acoustic noise suppression function and select small loadline of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved			EN_ANSA	SMALL_LLA			
Default	0	0	0	--	--	--	--	--
Type	RW			RW	RW			

Bit	Name	Description
7:5	Reserved	Unimplemented, default value is 0b000
4	EN_ANSA	Enable acoustic noise suppression function. Bit field definition and default value are from EN_ANSA (0x46[2]) in setting function table
3:0	SMALL_LLA	Small loadline. Bit field definition and default value are from SEL_SMALL_LLA (0x17[3:0]) in setting function table

Table 111. VOFS_LOAD_OFSA

Address: 0xA8								
Description: VID offset for load condition VOFS_LOADA (0x9E) of rail A								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_OFSA							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFS_LOAD_OFSA	Set the VID offset for load condition VOFS_LOADA (0x9E) [7:0]: 5mV/step (SEL_VID_STEPA = 0) or 10mV/step (SEL_VID_STEPA = 1) [e.g.] 0b00000001 = current VID + (1 x VID step)

Table 112. LLA

Address: 0xA9								
Description: Select loadline of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved			LLA				
Default	0	0	0	0	1	0	1	0
Type	RW			RW				

Bit	Name	Description
7:5	Reserved	Unimplemented, default value is 0b000
4:0	LLA	Loadline setting. 1LSB = 10%. Range is from 0% to 200%. When LLA is above 15h, loadline will be 0%. [e.g.] LLA = 0b01010, loadline = 100%, LLA = 0b10100, loadline = 200%, LLA = 0b10101, loadline = 0%

Table 113. EN_VFIXA, EN_VFIXB & EN_VFIXC

Address: 0xAA								
Description: Enable fixed VID mode of rail A								
Bit	7	6	5	4	3	2	1	0
Field	Reserved					EN_VFIXA	EN_VFIXB	EN_VFIXC
Default	0	0	0	0	0	0	0	0
Type	RW					RW	RW	RW

Bit	Name	Description
7:3	Reserved	Unimplemented, default value is 0b00000
2	EN_VFIXA	0: Disable, 1: Enable
1	EN_VFIXB	0: Disable, 1: Enable
0	EN_VFIXC	0: Disable, 1: Enable

Table 114. VFIXB_LB

Address: 0xAB								
Description: 9-bit fixed VID (Reg. 0xAB + Reg. 0xAC). Set voltage in fixed VID mode of rail B. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts $\overline{\text{ALERT}}$ immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXB_LB							
Default (VID1)	1	0	0	0	0	0	1	1
Default (VID2)	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	VFIXB_LB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXB_HB [0] = 00h + VFIXB_LB[7:0] = 00h) SEL_VID_STEPB = 0, Voltage of fixed VID mode = 0.245V + (VFIXB_HB [0] + VFIXB_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPB = 1, Voltage of fixed VID mode = 0.19V + (VFIXB_HB [0] + VFIXB_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

Table 115. VFIXB_HB

Address: 0xAC								
Description: 9-bit fixed VID (Reg. 0xAB + Reg. 0xAC). Set voltage in fixed VID mode of rail B. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts $\overline{\text{ALERT}}$ immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXB_HB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VFIXB_HB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXB_HB [0] = 00h + VFIXB_LB[7:0] = 00h) SEL_VID_STEPB = 0, Voltage of fixed VID mode = 0.245V + (VFIXB_HB [0] + VFIXB_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPB = 1, Voltage of fixed VID mode = 0.19V + (VFIXB_HB [0] + VFIXB_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

Table 116. VOFSB

Address: 0xAD								
Description: Setting offset voltage of rail B. For VID1 the final voltage limiting range 0.25V to 2.17V. (i.e., 0.25V ≤ VID setting ± SVID offset voltage ± I ² C offset voltage ≤ 2.17V) For VID2 the final voltage limiting range 0.2V to 3.04V. The offset slew rate is 1/2 of the fast slew rate. While setting voltage offset, the VR should return to power state PS0. After VSEN settles at the target offset voltage, the power state (PS) goes back to the original PS. If CPU sends SetPS1/2/3 command, the controller follows PS and the voltage offset still exists. If CPU sends SetVID off code command (VID setting ± SVID offset voltage ± I ² C offset voltage), the controller sets output voltage to 0V.								
Bit	7	6	5	4	3	2	1	0
Field	VOFSB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFSB	[7:0] = 00h: No offset [7]: Sign bit (as part of two's complement) [6:0]: 5mV/step (SEL_VID_STEPB = 1) or 10mV/step (SEL_VID_STEPB = 1) [e.g.] 0b00000001 = current VID + (1 x VID step) 0b00000011 = current VID + (3 x VID steps) 0b11111111 = current VID - (1 x VID step)

Table 117. TEMP_ALERTB & TEMP_VRHOTB

Address: 0xAE

Description: Setting rail B's ALERT temperature and thermal VRHOT temperature. VRHOT temperature should be higher than ALERT temperature. While VRHOT temperature smaller than the thermal ALERT temperature. VR will force ALERT temperature smaller than VRHOT temperature (TEMP_VRHOTB[7:4] = TEMP_ALERTB[3:0]).

Bit	7	6	5	4	3	2	1	0
Field	TEMP_ALERTB				TEMP_VRHOTB			
Default	0	1	1	0	0	1	1	0
Type	RW							

Bit	Name	Description
7:4	TEMP_ALERTB	Select thermal ALERT temperature of rail B. Temperature versus V _{THERMAL} refer to Table 105. 0000: 75°C, 0001: 82°C, 0010: 85°C, 0011: 88°C, 0100: 91°C, 0101: 94°C, 0110: 97°C, 0111: 100°C, 1000: 103°C, 1001: 106°C, 1010: 109°C, 1011: 112°C, 1100: 115°C, 1101: 118°C, 1110: 121°C, 1111: 124°C
3:0	TEMP_VRHOTB	Select VRHOT temperature of rail B. Temperature versus V _{THERMAL} refer to Table 105. 0000: 82°C, 0001: 85°C, 0010: 88°C, 0011: 91°C, 0100: 94°C, 0101: 97°C, 0110: 100°C, 0111: 103°C, 1000: 106°C, 1001: 109°C, 1010: 112°C, 1011: 115°C, 1100: 118°C, 1101: 121°C, 1110: 124°C, 1111: 127°C

Table 118. SUM_OCP_DEB_TIME B, EN_SS_OCPB, EN_SUM_OCPB, EN_NV B, Reserved & EN_OVB

Address: 0xAF								
Description: Enable protection function of rail B								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SUM_OCP_DEB_TIME B	EN_SS_OCPB	EN_SUM_OCPB	EN_NV B	Reserved	EN_OVB
Default	0	0	--	--	1	1	1	1
Type	RW		RW	RW	RW	RW	RW	RW

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	SUM_OCP_DEB_TIME B	0: 20μs, 1: 40μs Default value is from SEL_SUM_OCP_DEB_TIMEB (0x2B[6]) in setting function table
4	EN_SS_OCPB	0: Disable soft-start OC protection, 1: Enable soft-start OC protection Default value is from EN_SS_OCPB (0x2F[1]) in setting function table
3	EN_SUM_OCPB	0: Disable sum OC protection, 1: Enable sum OC protection (default)
2	EN_NV B	0: Disable NV protection, 1: Enable NV protection (default)
1	Reserved	Default value 1, not change
0	EN_OVB	0: Disable OV protection, 1: Enable OV protection (default)

Table 119. OCB & NVB & UVB & OVB

Address: 0xB0								
Description: Protection indicator of rail B								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				OCB	NVB	UVB	OVB
Default	0	0	0	0	0	0	0	0
Type	R				R	R	R	R

Bit	Name	Description
7:4	Reserved	Unimplemented, default value is 0b0000
3	OCB	0: No occurrence of OCP, 1: Occurrence of OCP
2	NVB	0: No occurrence of NVP, 1: Occurrence of NVP
1	UVB	0: No occurrence UVP, 1: Occurrence UVP
0	OVB	0: No occurrence of OVP, 1: Occurrence of OVP

Table 120. ILOAD_RPTB

Address: 0xB1								
Description: Output current reporting of rail B								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPTB							
Default	--	--	--	--	--	--	--	--
Type	R							

Bit	Name	Description
7:0	ILOAD_RPTB	Output current reporting

Table 121. TEMP_RPTB

Address: 0xB2								
Description: Temperature reporting of rail B								
Bit	7	6	5	4	3	2	1	0
Field	TEMP_RPTB							
Default	--	--	--	--	--	--	--	--
Type	R							

Bit	Name	Description
7:0	TEMP_RPTB	$V_{THERMAL} = TEMP_RPTB \times 6.25mV$. Temperature versus $V_{THERMAL}$ refer to Table 103.

Table 122. VOFS_LOAD_HYSB & VOFS_LOAD_THB

Address: 0xB4								
Description: Load condition for VID offset of rail B								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_HYSB		VOFS_LOAD_THB					
Default	0	0	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	VOFS_LOAD_HYSB	Select the current hysteresis 00: 4A, 01: 8A, 10: 12A, 11: 16A
5:0	VOFS_LOAD_THB	Set the current threshold from 0A to 126A with 2A/LSB

Table 123. ILOAD_RPT_RATIOB, FORCE_PS0B & KTONB

Address: 0xB5								
Description: Adjust output current reporting ratio, enable or disable force PS0 function and K _{TON} of rail B								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPT_RATIOB		Reserved	FORCE_PS0B	Reserved	KTONB		
Default	--	--	0	--	0	--	--	--
Type	RW		RW	RW	RW	RW		

Bit	Name	Description
7:6	ILOAD_RPT_RATIOB	Output current reporting ratio 00: 100%, 01: 87.5% 10: 75%, 11: 50%
5	Reserved	Unimplemented, default value is 0
4	FORCE_PS0B	Enable this function, VR will stay at PS0 even though SetPS PS1, PS2 or PS3 command is received 0: Disable, 1: Enable
3	Reserved	Unimplemented, default value is 0
2:0	KTONB	On-time factor K _{TON} . Refer to the section Switching Frequency Setting for the details. Default value is from SEL_KTONB (0x15[2:0]) in setting function table

Table 124. EN_SPMB, EN_ANSB & SMALL_LLB

Address: 0xB6								
Description: Enable acoustic noise suppression function and select small loadline of rail B								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		EN_SPMB	EN_ANSB	SMALL_LLB			
Default	0	0	--	--	--	--	--	--
Type	RW		RW	RW	RW			

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	EN_SPMB	Enable smart phase management function. Default value is 0.
4	EN_ANSB	Enable acoustic noise suppression function. Bit field definition and default value are from EN_ANSB (0x46[1]) in setting function table
3:0	SMALL_LLB	Small loadline. Bit field definition and default value are from SEL_SMALL_LLB (0x18[7:4]) in setting function table

Table 125. VOFS_LOAD_OFSB

Address: 0xB8								
Description: VID offset for load condition VOFS_LOADB (0xB4) of rail B								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_OFSB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFS_LOAD_OFSB	Set the VID offset for load condition VOFS_LOADB (0xB4) [7:0]: 5mV/step (SEL_VID_STEPB = 0) or 10mV/step (SEL_VID_STEPB = 1) [e.g.] 0b00000001 = current VID + (1 x VID step)

Table 126. LLB

Address: 0xB9								
Description: Select loadline of rail B								
Bit	7	6	5	4	3	2	1	0
Field	Reserved			LLB				
Default	0	0	0	0	1	0	1	0
Type	RW			RW				

Bit	Name	Description
7:5	Reserved	Unimplemented, default value is 0b000
4:0	LLB	Loadline setting. 1LSB = 10%. Range is from 0% to 200%. When LLB is above 15h, loadline will be 0%. [e.g.] LLB = 0b01010, loadline = 100%, LLB = 0b10100, loadline = 200%, LLB = 0b10101, loadline = 0%

Table 127. LLC

Address: 0xBA								
Description: Select loadline of rail C								
Bit	7	6	5	4	3	2	1	0
Field	Reserved			LLC				
Default	0	0	0	0	1	0	1	0
Type	RW			RW				

Bit	Name	Description
7:5	Reserved	Unimplemented, default value is 0b000
4:0	LLC	Loadline setting. 1LSB = 10%. Range is from 0% to 200%. When LLC is above 15h, loadline will be 0%. [e.g.] LLC = 0b01010, loadline = 100%, LLC = 0b10100, loadline = 200%, LLC = 0b10101, loadline = 0%

Table 128. VFIXC_LB

Address: 0xBB								
Description: 9-bit fixed VID (Reg. 0xBB + Reg. 0xBC). Set voltage in fixed VID mode of rail C. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts ALERT immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXC_LB							
Default (VID1)	1	0	0	0	0	0	1	1
Default (VID2)	1	0	1	0	0	0	0	1
Type	RW							

Bit	Name	Description
7:0	VFIXC_LB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXC_HB [0] = 00h + VFIXC_LB[7:0] = 00h) SEL_VID_STEPC = 0, Voltage of fixed VID mode = 0.245V + (VFIXC_HB [0] + VFIXC_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPC = 1, Voltage of fixed VID mode = 0.19V + (VFIXC_HB [0] + VFIXC_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

Table 129. VFIXC_HB

Address: 0xBC								
Description: 9-bit fixed VID (Reg. 0xBB + Reg. 0xBC). Set voltage in fixed VID mode of rail C. In fixed VID mode, VR skips SetVID/SetPS command. (VR has no actions but still asserts ALERT immediately after receiving SetVID command, while the VR output voltage stays at the fixed VID.) While fixed VID is enabled, VR does not act for I ² C voltage offset as well. After disabling fixed VID mode, VID returns to the last SetVID target and last power state. When entering/exiting fixed VID mode, VID slew rate is 1/2 of the fast slew rate.								
Bit	7	6	5	4	3	2	1	0
Field	VFIXC_HB							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VFIXC_HB	Voltage of fixed VID mode = 0.0V when receives an off code (VFIXC_HB [0] = 00h + VFIXC_LB[7:0] = 00h) SEL_VID_STEPC = 0, Voltage of fixed VID mode = 0.245V + (VFIXC_HB [0] + VFIXC_LB[7:0]) x 5mV, (VID1), voltage range from 0.25V to 2.17V. SEL_VID_STEPC = 1, Voltage of fixed VID mode = 0.19V + (VFIXC_HB [0] + VFIXC_LB[7:0]) x 10mV, (VID2), voltage range from 0.2V to 3.04V. Refer to Figure 32 for Control Logic.

Table 130. VOFSC

Address: 0xBD								
Description: Setting offset voltage of rail C. For VID1 the final voltage limiting range 0.25V to 2.17V. (i.e., $0.25V \leq \text{VID setting} \pm \text{SVID offset voltage} \pm I^2C \text{ offset voltage} \leq 2.17V$) For VID2 the final voltage limiting range 0.2V to 3.04V. The offset slew rate is 1/2 of the fast slew rate. While setting voltage offset, the VR should return to power state PS0. After VSEN settles at the target offset voltage, the power state (PS) goes back to the original PS. If CPU sends SetPS1/2/3 command, the controller follows PS and the voltage offset still exists. If CPU sends SetVID off code command ($\text{VID setting} \pm \text{SVID offset voltage} \pm I^2C \text{ offset voltage}$), the controller sets output voltage to 0V.								
Bit	7	6	5	4	3	2	1	0
Field	VOFSC							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFSC	[7:0] = 00h: No offset [7]: Sign bit (as part of two's complement) [6:0]: 5mV/step (SEL_VID_STEP = 0) or 10mV/step (SEL_VID_STEP = 1) [e.g.] 0b00000001 = current VID + (1 x VID step) 0b00000011 = current VID + (3 x VID steps) 0b11111111 = current VID - (1 x VID step)

Table 131. TEMP_ALERTC & TEMP_VRHOTC

Address: 0xBE								
Description: Setting rail C's ALERT temperature and thermal VRHOT temperature. VRHOT temperature should be higher than ALERT temperature. While VRHOT temperature smaller than the thermal ALERT temperature. VR will force ALERT temperature smaller than VRHOT temperature ($\text{TEMP_VRHOTC}[7:4] = \text{TEMP_ALERTC}[3:0]$).								
Bit	7	6	5	4	3	2	1	0
Field	TEMP_ALERTC				TEMP_VRHOTC			
Default	0	1	1	0	0	1	1	0
Type	RW							

Bit	Name	Description
7:4	TEMP_ALERTC	Select thermal ALERT temperature of rail C. Temperature versus V _{THERMAL} refer to Table 105. 0000: 75°C, 0001: 82°C, 0010: 85°C, 0011: 88°C, 0100: 91°C, 0101: 94°C, 0110: 97°C, 0111: 100°C, 1000: 103°C, 1001: 106°C, 1010: 109°C, 1011: 112°C, 1100: 115°C, 1101: 118°C, 1110: 121°C, 1111: 124°C
3:0	TEMP_VRHOTC	Select VRHOT temperature of rail C. Temperature versus V _{THERMAL} refer to Table 105. 0000: 82°C, 0001: 85°C, 0010: 88°C, 0011: 91°C, 0100: 94°C, 0101: 97°C, 0110: 100°C, 0111: 103°C, 1000: 106°C, 1001: 109°C, 1010: 112°C, 1011: 115°C, 1100: 118°C, 1101: 121°C, 1110: 124°C, 1111: 127°C

Table 132. SUM_OCP_DEB_TIMEC, EN_SS_OCPC, EN_SUM_OCPC, EN_NVC & EN_OVC

Address: 0xBF								
Description: Enable protection function of rail C								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		SUM_OCP_DEB_TIMEC	EN_SS_OCPC	EN_SUM_OCPC	EN_NVC	Reserved	EN_OVC
Default	0	0	--	--	1	1	1	1
Type	RW		RW	RW	RW	RW	RW	RW

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	SUM_OCP_DEB_TIMEC	0: 20μs, 1: 40μs Default value is from SEL_SUM_OCP_DEB_TIMEC (0x2C[7]) in setting function table
4	EN_SS_OCPC	0: Disable soft-start OC protection, 1: Enable soft-start OC protection Default value is from EN_SS_OCPC (0x2F[0]) in setting function table
3	EN_SUM_OCPC	0: Disable sum OC protection, 1: Enable sum OC protection (default)
2	EN_NVC	0: Disable NV protection, 1: Enable NV protection (default)
1	Reserved	Default value 1, not change
0	EN_OVC	0: Disable OV protection, 1: Enable OV protection (default)

Table 133. OCC, NVC, UVC & OVC

Address: 0xC0								
Description: Protection indicator of rail C								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				OCC	NVC	UVC	OVC
Default	0	0	0	0	0	0	0	0
Type	R				R	R	R	R

Bit	Name	Description
7:4	Reserved	Unimplemented, default value is 0b0000
3	OCC	0: No occurrence of OCP, 1: Occurrence of OCP
2	NVC	0: No occurrence of NVP, 1: Occurrence of NVP
1	UVC	0: No occurrence UVP, 1: Occurrence UVP
0	OVC	0: No occurrence of OVP, 1: Occurrence of OVP

Table 134. ILOAD_RPTC

Address: 0xC1								
Description: Output current reporting of rail C								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPTC							
Default	--	--	--	--	--	--	---	--
Type	R							

Bit	Name	Description
7:0	ILOAD_RPTC	Output current reporting

Table 135. TEMP_RPTC

Address: 0xC2								
Description: Temperature reporting of rail C								
Bit	7	6	5	4	3	2	1	0
Field	TEMP_RPTC							
Default	--	--	--	--	--	--	--	--
Type	RW							

Bit	Name	Description
7:0	TEMP_RPTC	V _{THERMAL} = TEMP_RPTC x 6.25mV. For temperature versus V _{THERMAL} , refer to Table 103.

Table 136. VOFS_LOAD_HYSC & VOFS_LOAD_THC

Address: 0xC4								
Description: Load condition for VID offset of rail C								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_HYSC		VOFS_LOAD_THC					
Default	1	0	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	VOFS_LOAD_HYSC	Select the current hysteresis 00: 4A, 01: 8A, 10: 12A, 11: 16A
5:0	VOFS_LOAD_THC	Set the current threshold from 0A to 126A with 2A/LSB

Table 137. ILOAD_RPT_RATIOC, FORCE_PS0C & KTONC

Address: 0xC5								
Description: Adjust output current reporting ratio, enable or disable force PS0 function and K _{TON} of rail C								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPT_RATIOC		Reserved	FORCE_PS0C	Reserved	KTONC		
Default	--	--	0	--	0	--	--	--
Type	RW		RW	RW	RW	RW		

Bit	Name	Description
7:6	ILOAD_RPT_RATIOC	Output current reporting ratio 00: 100%, 01: 87.5%, 10: 75%, 11: 50%
5	Reserved	Unimplemented, default value is 0
4	FORCE_PS0C	Enable this function, VR will stay at PS0 even though SetPS PS1, PS2 or PS3 command is received 0: Disable, 1: Enable
3	Reserved	Unimplemented, default value is 0
2:0	KTONC	On-time factor K _{TON} . Refer to the section Switching Frequency Setting for the details. Default value is from SEL_KTONC (0x16[6:4]) in setting function table

Table 138. EN_SPMC, EN_ANSC & SMALL_LLC

Address: 0xC6								
Description: Enable acoustic noise suppression function and select small loadline of rail C								
Bit	7	6	5	4	3	2	1	0
Field	Reserved		EN_SPMC	EN_ANSC	SMALL_LLC			
Default	0	0	0	--	--	--	--	--
Type	RW		RW	RW	RW			

Bit	Name	Description
7:6	Reserved	Unimplemented, default value is 0b00
5	EN_SPMC	Enable smart phase management. Default value is 0.
4	EN_ANSC	Enable acoustic noise suppression function. Bit field definition and default value are from EN_ANSC (0x46[0]) in setting function table
3:0	SMALL_LLC	Small loadline. Bit field definition and default value are from SEL_SMALL_LLC (0x18[3:0]) in setting function table

Table 139. ILOAD_RPT_RATIO_D

Address: 0xC7								
Description: Adjust output current reporting ratio of rail D								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPT_RATIO_D		Reserved					
Default	--	--	0	0	0	0	0	0
Type	RW		RW					

Bit	Name	Description
7:6	ILOAD_RPT_RATIO_D	Output current reporting ratio 00: 100%, 01: 87.5% 10: 75%, 11: 50%
5:0	Reserved	Unimplemented, default value is 0b000000

Table 140. VOFS_LOAD_OFSC

Address: 0xC8								
Description: VID offset for load condition VOFS_LOADC (0xC4) of rail C								
Bit	7	6	5	4	3	2	1	0
Field	VOFS_LOAD_OFSC							
Default	0	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	VOFS_LOAD_OFSC	Set the VID offset for load condition VOFS_LOADC (0xC4) [7:0]: 5mV/step (SEL_VID_STEP_C = 0) or 10mV/step (SEL_VID_STEP_C = 1) [e.g.] 0b00000001 = current VID + (1 x VID step)

Table 141. SEL_ANS, WD_STAT, EN_WD & WDT

Address: 0xCC								
Description: Acoustic noise suppression behavior and I ² C watchdog related function								
Bit	7	6	5	4	3	2	1	0
Field	Reserved				SEL_ANS	WD_STAT	EN_WD	WDT
Default	0	0	0	0	--	--	--	--
Type	R				R	R	R	R

Bit	Name	Description
7:4	Reserved	Default value is 0b0000
3	SEL_ANS	Acoustic noise suppression behavior. Bit definition and default value are from SEL_ANS_BEHAV (0x1B[7]) in setting function table
2	WD_STAT	I ² C watchdog status 0: I ² C transmission normal 1: I ² C transmission abnormal, watch dog is triggered
1	EN_WD	Enable I ² C watchdog 0: Disable watchdog. If I ² C bus hangs over 30ms, VR will reset I ² C state machine but keep the latest value of all registers 1: Enable watchdog. If I ² C bus hangs over watchdog time (WDT, 0xCC[0]), VR will reset all the registers to default value except protection flag PROT_FLAGA, PROT_FLAGB and PROT_FLAGC.
0	WDT	Watchdog time 0: 800ms, 1: 1600ms

Table 142. ILOAD_RPTD

Address: 0xCD								
Description: Output current reporting of rail D								
Bit	7	6	5	4	3	2	1	0
Field	ILOAD_RPTD							
Default	--	--	--	--	--	--	--	--
Type	R							

Bit	Name	Description
7:0	ILOAD_RPTD	Output current reporting

Table 143. RESTORE_FLAG, STORE_FLAG, STORE_ALLOW, RESTORE_BUSY, STORE_BUSY, CRC_NVM & CRC_NVM_TOTAL

Address: 0xEC								
Description: The NVM_PROGRAM_STATUS command returns one byte of information regarding the NVM program status								
Bit	7	6	5	4	3	2	1	0
Field	RESTORE_FLAG	STORE_FLAG	STORE_ALLOW	RESTORE_BUSY	STORE_BUSY	CRC_NVM	Reserved	CRC_NVM_TOTAL
Default	--	--	--	--	--	--	--	--
Type	RW	RW	RW	RW	RW	RW	RW	RW

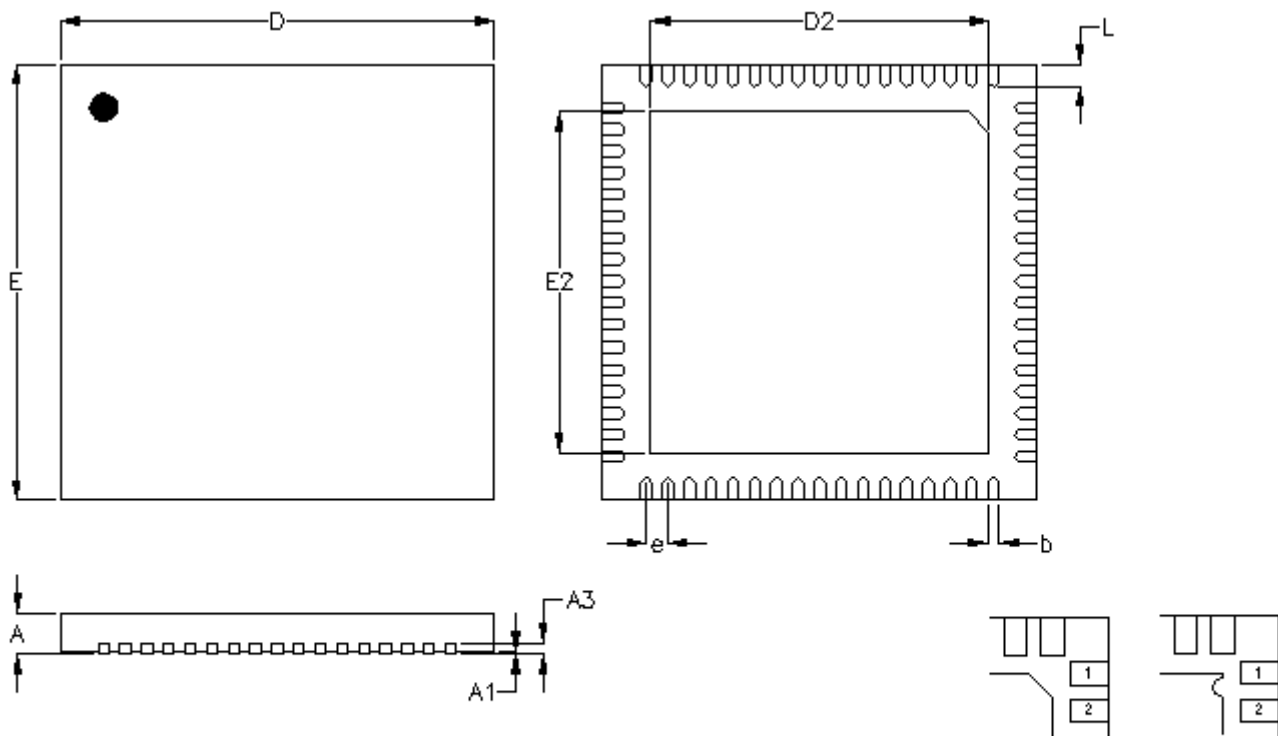
Bit	Name	Description
7	RESTORE_FLAG	Restore process done
6	STORE_FLAG	Store process done
5	STORE_ALLOW	Store process allowed
4	RESTORE_BUSY	NVM restore busy
3	STORE_BUSY	NVM store busy
2	CRC_NVM	NVM check fail
1	Reserved	Default value is 0
0	CRC_NVM_TOTAL	Total NVM check fail

Table 144. PAGE

Address: 0xEF								
Description: The PAGE command provides the ability to configure, control and monitor multiple PWM channels through setting registers and general registers.								
Bit	7	6	5	4	3	2	1	0
Field	PAGE							
Default	1	0	0	0	0	0	0	0
Type	RW							

Bit	Name	Description
7:0	PAGE	[7:0] = 80h: Page X. General registers (Default) [7:0] = 82h: Page 02. Setting registers All the other combinations are not defined.

20 Outline Dimension

**DETAIL A**

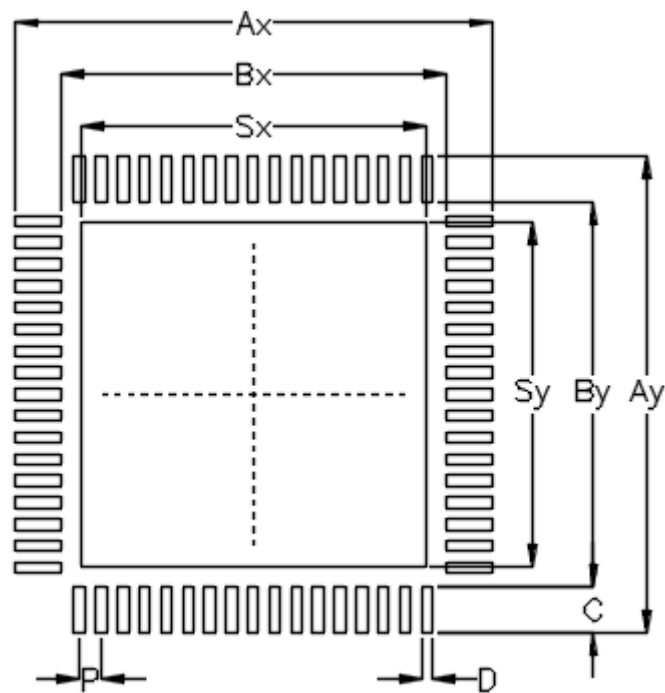
Pin #1 ID and Tie Bar Mark Options

Note : The configuration of the Pin #1 identifier is optional, but must be located within the zone indicated.

Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min.	Max.	Min.	Max.
A	0.700	0.800	0.028	0.031
A1	0.000	0.050	0.000	0.002
A3	0.175	0.250	0.007	0.010
b	0.150	0.250	0.006	0.010
D	7.900	8.100	0.311	0.319
D2	6.200	6.300	0.244	0.248
E	7.900	8.100	0.311	0.319
E2	6.200	6.300	0.244	0.248
e	0.400		0.016	
L	0.350	0.450	0.014	0.018

W-Type 68L QFN 8x8 Package

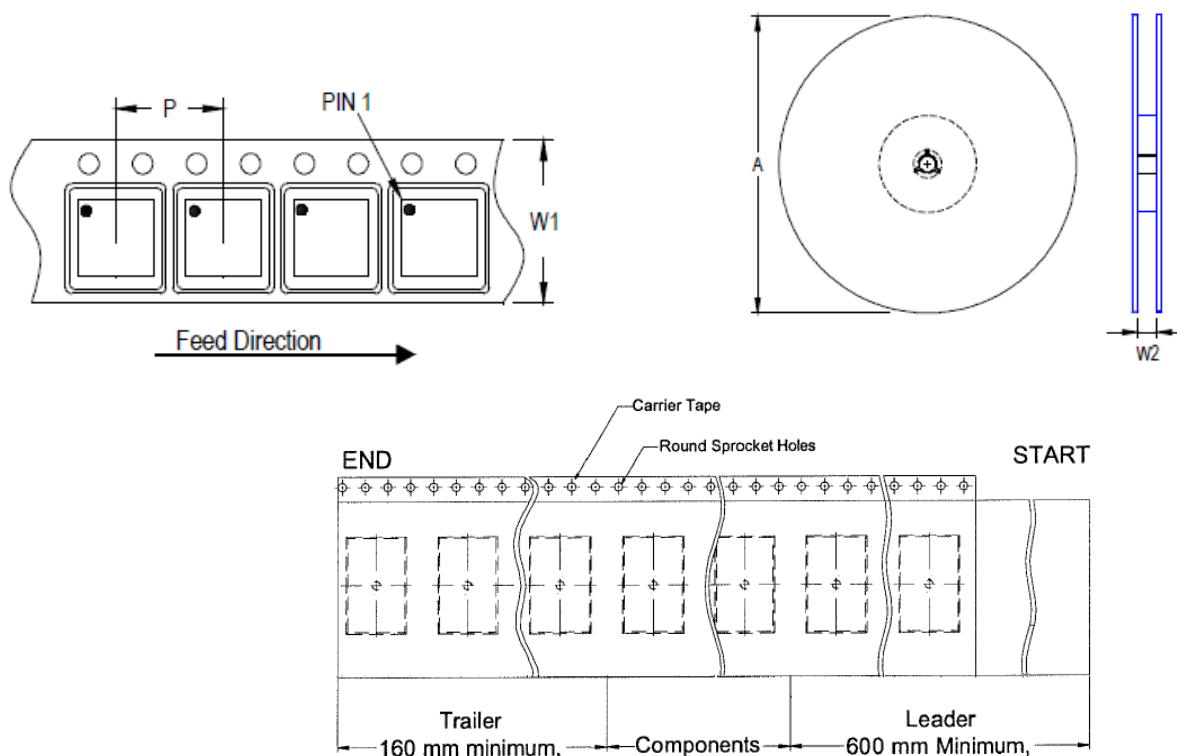
21 Footprint Information



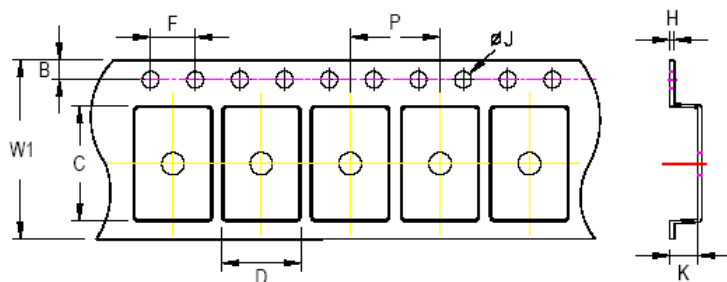
Package	Number of Pin	Footprint Dimension (mm)									Tolerance
		P	Ax	Ay	Bx	By	C	D	Sx	Sy	
V/W/U/XQFN8*8-68	68	0.40	8.80	8.80	7.10	7.10	0.85	0.20	6.35	6.35	±0.05

22 Packing Information

22.1 Tape and Reel Data



Package Type	Tape Size (W1) (mm)	Pocket Pitch (P) (mm)	Reel Size (A)		Units per Reel	Trailer (mm)	Leader (mm)	Reel Width (W2) Min./Max. (mm)
			(mm)	(in)				
QFN/DFN 8x8	16	12	330	13	2,500	160	600	16.4/18.4



C, D and K are determined by component size.
The clearance between the components and the cavity is as follows:
- For 16mm carrier tape: 1.0mm max.

Tape Size	W1	P		B		F		ØJ		H
	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	Max.
16mm	16.3mm	11.9mm	12.1mm	1.65mm	1.85mm	3.9mm	4.1mm	1.5mm	1.6mm	0.6mm

22.2 Tape and Reel Packing

Step	Photo/Description	Step	Photo/Description
1	 Reel 13"	4	 1 reel per inner box Box G
2	 HIC & Desiccant (2 Unit) inside	5	 6 inner boxes per outer box
3	 Caution label is on backside of Al bag	6	 Outer box Carton A

Container Package	Reel		Box			Carton		
	Size	Units	Item	Reels	Units	Item	Boxes	Units
QFN and DFN 8x8	13"	2,500	Box G	1	2,500	Carton A	6	15,000

22.3 Packing Material Anti-ESD Property

Surface Resistance	Aluminum Bag	Reel	Cover tape	Carrier tape	Tube	Protection Band
Ω/cm^2	10^4 to 10^{11}	10^4 to 10^{11}	10^4 to 10^{11}	10^4 to 10^{11}	10^4 to 10^{11}	10^4 to 10^{11}

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DS3638AE-00 December 2023

23 Datasheet Revision History

Version	Date	Description	Item
00	2023/11/30	Final	Functional Pin Description on P3, P4, P5 Electrical Characteristics on P10 Typical Application Circuit on P11 Typical Operating Characteristics on P12, P13, P14, P15, P16, P17, P18, P19 Operation on P20 Application Information on P24, P25, P26, P32, Functional Register Description on P51, P52, P59, P63, P65, P66, P68, P69, P70, P76, P77, P78, P79, P81, P82, P83, P84, P85, P86, P87, P89, P90, P91, P95, P96, P104, P105, P113, P114, P121