

# 2<sup>nd</sup> Generation Quasi-Resonant (QR-II<sup>TM</sup>) PWM Controller

#### **FEATURES**

- ♦ Easily Meet EPS Level 6
- ◆ Proprietary QR-II<sup>TM</sup> Technology:
  - •Digital Anti-jitter for Audio Noise Free Operation
  - Digital Frequency Foldback
  - Digital Frequency Jittering for Better EMI
- ♦ Less than 100mW Standby Power
- **♦** Multi-Mode Operation for High Efficiency
- ♦ 12.7us Maximum On Time
- ♦ 80KHz Maximum Frequency Limit
- ◆ 52KHz Frequency Low Clamping in QR Mode
- ♦ 65% Maximum Duty Cycle
- **♦** Adaptive Slope Compensation for CCM Mode
- ◆ Built-in Soft Start Function
- Pin Floating Protection
- ♦ Built-in Synchronous Slope Compensation
- ◆ Cycle-by-Cycle Current Limiting
- ◆ Leading Edge Blanking (LEB)
- ◆ Constant Power Limiting
- VDD UVLO, OVP & Clamp

## **APPLICATIONS**

Offline AC/DC Flyback Converter for

- ♦ AC/DC Adaptors
- ♦ SMPS Power Supply

#### **GENERAL DESCRIPTION**

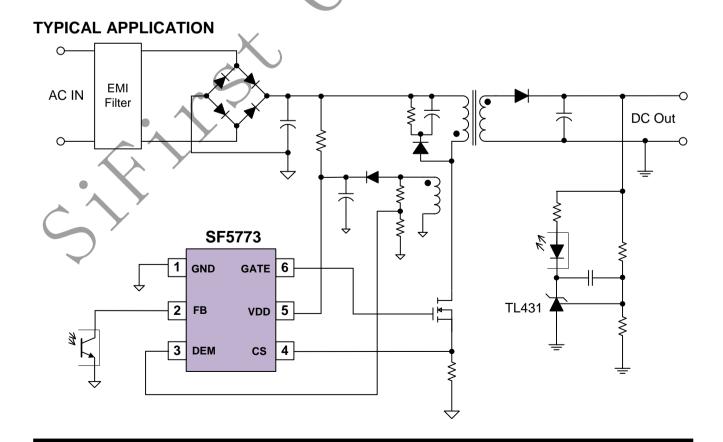
SF5773 is a high performance, 2<sup>nd</sup> Generation Quasi-Resonant (QR-II<sup>TM</sup>) PWM controller for offline flyback power converter applications. The built-in proprietary **QR-II<sup>TM</sup>** technology with high level protection features improves the SMPS reliability and performance.

In SF5773, the "Digital Anti-Jitter" function can automatically select and lock a valley at a given loading, which can achieve audio noise free operation. On the other hand, the "Digital Frequency Jittering" function makes the system have superior EMI performance than conventional QR system.

SF5773 is a multi mode controller. When full loadings, the IC works in CCM mode or QR mode based on the AC line input. When the loading goes low, the IC enters into "Digital Frequency Foldback" mode to boost power conversion efficiency. When the output power is very small, the IC enters into burst mode and can achieve less than 100mW no load power.

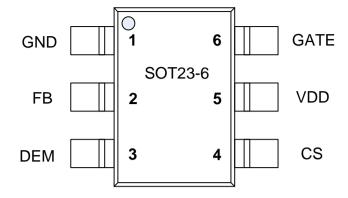
SF5773 integrates functions and protections of Under Voltage Lockout (UVLO), VCC Over Voltage Protection (OVP), Output Over Voltage Protection (Output OVP), Cycle-by-cycle Current Limiting (OCP), Pin Floating Protection, Over Load Protection (OLP), Soft Start, VCC Clamping, Gate Clamping, etc. In SF5773, the protection functions are auto-recovery mode protection.

SF5773 is available in SOT23-6 package.





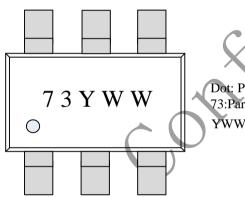
# **Pin Configuration**



**Ordering Information** 

Part Number	Top Mark Package		Tape & Reel	
SF5773LGT	.73YWW	SOT26	Green	Yes

# **Marking Information**



Dot: Pin1 Mark 73:Part number SF5773

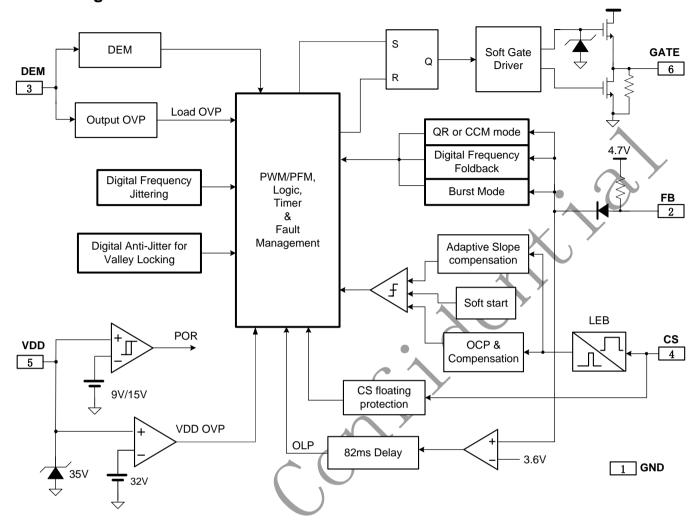
YWW: Year&Week Code

# **Pin Description**

Pin Num	Pin Name	1/0	Description
1	GND	P	IC ground pin.
2	FB	I	Voltage feedback pin. The loop regulation is achieved by connecting a photo-coupler to this pin. PWM duty cycle is generated by this pin voltage and the current sense signal at Pin 4.
3	DEM	I	Transformer core demagnetization detection pin. This pin is also used for output over voltage protection (Output OVP).
4	CS	1	Current sense input pin.
5	VDD	Р	IC power supply pin.
6	GATE	0	Totem-pole gate driver output to drive the external MOSFET.



# **Block Diagram**



Absolute Maximum Ratings (Note 1)

Absolute Maximum Natings (Note 1)						
Parameter	Value	Unit				
VDD DC Supply Voltage	35	V				
VCC DC Clamp Current	10	mA				
DEM Voltage Range	-0.7 to 6	V				
FB, CS Voltage Range	-0.3 to 7	V				
Package Thermal Resistance (SOT-26)	250	°C/W				
Maximum Junction Temperature	150	°C				
Operating Temperature Range	-40 to 85	°C				
Storage Temperature Range	-65 to 150	°C				
Lead Temperature (Soldering, 10sec.)	260	°C				
ESD Capability, HBM (Human Body Model)	3	kV				
ESD Capability, MM (Machine Model)	250	V				

**Recommended Operation Conditions** (Note 2)

Parameter	Value	Unit
Supply Voltage, VDD	11 to 29	V
Operating Ambient Temperature	-40 to 85	°C



# **ELECTRICAL CHARACTERISTICS**

 $(T_A = 25^{\circ}C, VDD=18V, if not otherwise noted)$ 

Symbol	Parameter	Test Conditions	Min	Тур	Max	Unit
	Section (VDD Pin)	100t Conditions	14	יאףי	IVIUX	Oint
	VDD Start up Current				20	Ι
I_Startup		V 22V CATE 4=E		5	20	uA
I_VDD_Op	Operation Current	V <sub>FB</sub> =3.2V, GATE=1nF	4.4	1.8	3.5	mA V
UVLO(ON)	VDD Under Voltage		14	15	16	V
11)/1 0/055)	Lockout Exit (Startup)				40	V
UVLO(OFF)	VDD Under Voltage		8	9	10	V
\/DD_	Lockout Enter		30	20	34	V
VDD_OVP	VDD Over Voltage		30	32	34	V
V Olama	Protection trigger	1/1/ \ 40 4	00	0.5		2/
V <sub>DD</sub> _Clamp	VDD Zener Clamp	$I(V_{DD}) = 10mA$	33	35	(	<b>Y</b>
T. O. Catalant	Voltage			4	• •	
T_Softstart	Soft Start Time			4		mSec
Feedback Input	· ,		1			/
V <sub>FB</sub> Open	FB Open Voltage		4.2	4.7	5.5	V
					$\cup$	
I <sub>FB</sub> _Short	FB short circuit	Short FB pin to GND,		0.4		mA
	current	measure current		Y		
A <sub>VCS</sub>	PWM Input Gain	$\Delta V_{FB} / \Delta V_{cs}$		3		V/V
VFB_foldback	FB under voltage		V	1.6		V
	foldback mode is			ľ		
	entered	•	<b>Y</b>			
VFB_min_duty	FB under voltage gate	_ ^		1.1		V
,	clock is off.					
VFB_PL	Power Limiting FB	X		3.6		V
_	Threshold Voltage					
T <sub>D</sub> _PL	Power limiting	Note 3		82		mSec
· <u>D_</u> · _	Debounce Time	<b>Y</b>				
Z <sub>FB</sub> _IN	Input Impedance			10		Kohm
	nput Section (CS Pin)			1.0		rtoriii
Vth_OC_min	Internal current	Zero duty cycle	0.44	0.45	0.46	V
VIII_OO_IIIIII	limiting threshold	Zero duty cycle	0.44	0.43	0.40	V
Vth_OC_max	Internal current			0.77		V
VIII_OC_IIIax	limiting threshold			0.77		V
T_blanking	SENSE Input Leading			250		nSec
I_blatikitig				250		nsec
T 00	Edge Blanking Time Over Current			60		nSec
T <sub>D</sub> OC				60		nsec
	Detection and Control					
D	Delay	DEM D:\				
Demagnetizatio	n Detection Section (I	JEMI PIN)	1	T	1	1
Var. DEM	DEM Comparator			125		mV
VTH_DEM	Threshold Voltage		1	1	1	
	(Negative going edge)		1		1	.,
VDEM_clamp_H	High clamp voltage		1	5.8	1	V
VDEM_clamp_L	Low clamp voltage			-0.7		V
V <sub>TH</sub> _OVP	Output over voltage			3.4		V
	protection threshold					
	Number of					
N <sub>TRUE</sub> OVP	subsequent cycles to			3		Cycle
	be true OVP					
T <sub>supp</sub>	Suppression of the	Note 4		2.5		uSec
	transformer ringing at					
	start of secondary					
	stroke					
T <sub>DEM_OUT</sub>	Timeout after last	Note 4		5		uSec
	Demag Transition					
Timer Section	<del>_</del>					
T_counter	Sampling Time for			40		mSec
004.1101	- Sampling Tillio for		I.		I.	



				1		
	Digital Anti-jitter					
	Function					
N_counter_max	Maximum Number for			8		
	Valley Locking					
F_BM	Burst Mode Base			22		KHz
	Frequency					
Duty_max	Maximum Duty cycle	Note 4		65		%
Fmax_QR_H	Frequency High		72	80	88	KHz
	Clamp in QR Mode		12	00	00	NΠZ
Fmin_QR_L	Frequency Low		47	52	57	KHz
FIIIII_QK_L	Clamp in QR Mode		47	52	37	KIIZ
∆F(jitter)/Fsw	Frequency Jittering	Note 4	-4		4	%
	range					
Ton_max	Maximum ON Time		11.5	12.7	14	us
Toff_max	Maximum OFF Time		52	57	64	us
Toff_min	Minimum OFF Time	Note 4		2.5		uSec
Gate Drive Outp	ut (GATE Pin)			\/		*
VOL	Output Low Level	lo = 20 mA (sink)		X	1,	V
VOH	Output High Level	lo = 20 mA (source)	7.5			V
VG_Clamp	Output Clamp Voltage	VDD=24V	1	16		V
	Level					
T_r	Output Rising Time	GATE= 1nF		150		nSec
T_f	Output Falling Time	GATE= 1nF		60		nSec

Note 1. Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Note 2.** The device is not guaranteed to function outside its operating conditions.

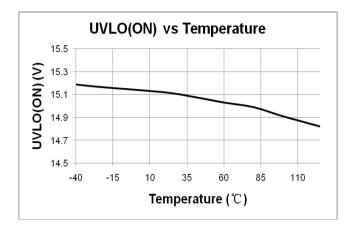
**Note 3.** The OLP debounce time is proportional to the period of switching cycle.

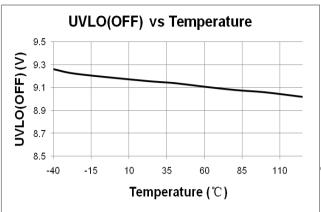
Note 4. Guaranteed by design.

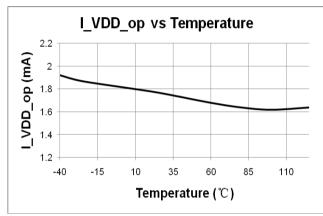


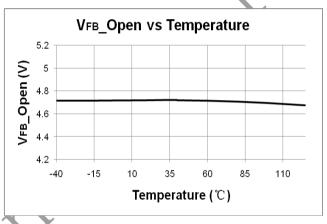


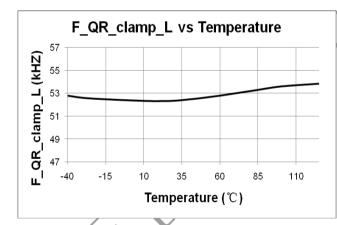
# **CHARACTERIZATION PLOTS**

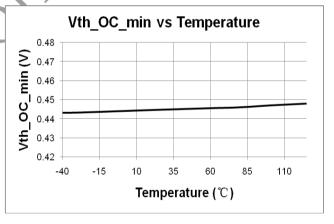












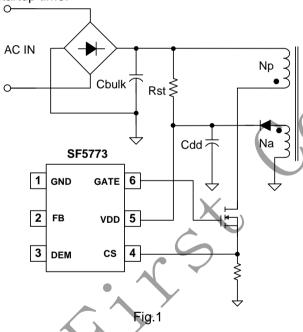


## **OPERATION DESCRIPTION**

SF5773 is a high performance, 2<sup>nd</sup> Generation Quasi-Resonant (QR) PWM controller for offline flyback power converter applications. The built-in proprietary **QR-II**<sup>TM</sup> technology with high level protection features improves the SMPS reliability and performance without increasing the system cost.

### UVLO and Startup Operation

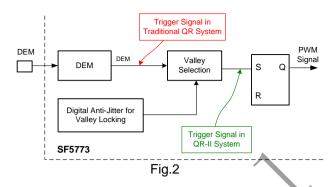
Fig.1 shows a typical startup circuit. Before the IC begins switching operation, it consumes only startup current (typically 5uA) and current supplied through the startup resistor Rst charges the VDD hold-up capacitor Cdd. When VDD reaches UVLO turn-on voltage of 15V(typical), SF5773 begins switching and the IC current consumed increased to 1.8mA (typical). The hold-up capacitor Cdd continues to supply VDD before the energy can be delivered from auxiliary winding Na. During this process, VDD must not drop below UVLO turn-off voltage (typical 9V). The selection of Rst and Cdd should be a trade off between the power loss and startup time.



# ◆ QR-II<sup>TM</sup> Technology Introduction ◆ Digital Anti-Jitter for Valley Locking

Traditional QR system suffers from audio noise issues. As shown in Fig.2, traditional QR system triggers new PWM cycle using pure demagnetization information by sensing DEM pin voltage. However, the PWM triggering signal may toggle between different valleys at a given loading, which may cause audio noise issue.

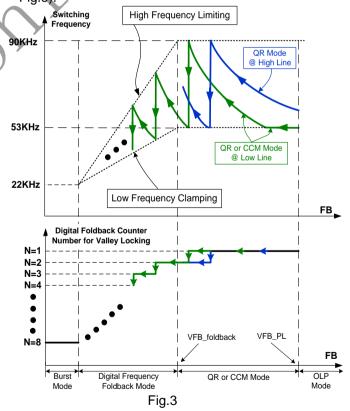
In SF5773, a "**Digital Anti-Jitter**" function is integrated to lock and select a valley at a given loading, which can achieve audio noise free operation.



# "Digital Frequency Foldback" and Multi-Mode Operation

SF5773 is a multi-mode QR controller. The proprietary "**Digital Frequency Foldback**" can achieve high efficiency when the loading is light.

■ At normal or full loading conditions, the operating mode is CCM when the input is in low line range since the low clamping frequency (52KHz typical) is touched. Thus, small size transformer can be used with high power conversion efficiency. When the input is in high line input range, the IC work in QR mode with high frequency clamping (typical 80KHz), as shown in Fig.3. When FB voltage is larger than VFB\_PL, the system enters into OLP mode with auto recovery protection (as illustrated in Fig.8 and Fig.9).



■ At light loading conditions (FB voltage is below VFB\_foldback), the IC works in "Digital Frequency Foldback" mode. The system frequency is limited between "High Frequency Limiting" and "Low Frequency Clamping", as shown with the dashed line in Fig.3. In "Digital Frequency Foldback"



mode, the IC automatically selects and locks the switching valley according to the load changes. In SF5773, a digital counter is integrated to register a counting number, the system will select the valleys based on the registered counter number. In SF5773, the maximum counting number is 8.

■ When zero or very light load conditions, the IC enters into burst mode. In the burst mode (as illustrated in Fig.5), the valley locking counting number is fixed at 8. In this way, a small standby power can be achieved.

## Digital Frequency Jittering

Traditional QR system suffers from EMI issues since the PWM switching frequency is actually fixed with a given loading. To improve system EMI performance. SF5773 integrates а "Digital Frequency Jittering" block to operate the system with  $\pm 4\%$  frequency jittering around the PWM switching frequency. The digital frequency jittering is active on all working modes.

### **♦** Low Operating Current

The operating current in SF5773 is as small as 1.8mA (typical). The small operating current results in higher efficiency and reduces the VDD hold-up capacitance requirement.

#### ♦ Soft Start

SF5773 features an internal 4ms (typical) soft start that slowly increases the threshold of cycle-bycycle current limiting comparator during startup sequence. It helps to prevent transformer saturation and reduce the stress on the secondary diode during startup. Every restart attempt is followed by a soft start activation.

### Demagnetization Detection

The transformer core demagnetization is detected by monitoring the voltage activity on the auxiliary windings through DEM pin. When the stored energy is fully released to the output, the voltage on DEM goes down. If DEM pin voltage drops below 0.125V, an internal DEM comparator is triggered and a new switching cycle is initiated following the DEM triggering. The power MOSFET is always turned on with zero inductor current such that the turn-on loss and noise can be minimized.

# **Ringing Suppression Timer**

After power MOSFET is turned off, there will be some oscillation on Vds, which will also appear on the voltage on DEM pin. To avoid that the power MOSFET is turned on mistriggered by such oscillations, a ringing suppression timer Tsupp is implemented in SF5773. In normal operation, Tsupp starts when CS reaches the feedback voltage FB, the external power MOSFET is set to OFF state. During Tsupp, the external power MOSFET remains in OFF state and cannot be

turned on gain. In SF5773, the ringing suppression timer Tsupp is set to 2.5us internally.

## Leading Edge Blanking (LEB)

Each time the power MOSFET is switched on, a turn-on spike occurs across the sensing resistor. The spike is caused by primary side capacitance and secondary side rectifier reverse recovery. To avoid premature termination of the switching pulse, an internal leading edge blanking circuit is built in. During this blanking period (250ns, typical), the PWM comparator is disabled and cannot switch off the gate driver.

### **♦** OCP Compensation

The variation of maximum output power in QR system can be rather large if no compensation is provided. In SF5773, a proprietary OCP compensation block is integrated and no external components are needed. The OCP threshold in SF5773 is a function of the switching ON time. For the ON time less than 12.7us, the OCP threshold changes linearly from 0.45V to 0.77V. For the ON time larger than 12.7us, the OCP threshold is clamped to 0.77V, as shown in Figure 4.

The maximum PWM duty cycle is about 65% in **S**F5773.

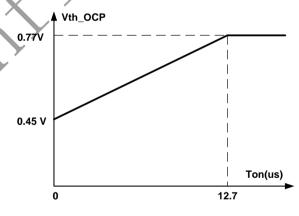


Fig.4

#### Adaptive Slope Compensation

InSF5773, the synchronous slope compensation circuit is integrated by adding voltage ramp onto the current sense input voltage for PWM generation. This greatly improves the close loop stability at CCM and prevents the sub-harmonic oscillation and thus reduces the output ripple voltage.

In SF5773, when the fix frequency CCM mode is touched (as show in Fig.2), the slope compensation will be automatically added to the system to improve current loop stability. When the system leaves fix frequency CCM mode, the slope compensation will automatically disappear.

#### Maximum Frequency Clamp

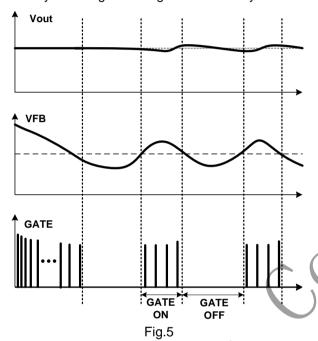
According to the QR operation principle, the switching frequency is inversely proportional to the output power. Therefore, when the output power



decreases, the switching frequency can become rather high without limiting. To meet EMI limit and to achieve high efficiency at light loading conditions, the maximum switching frequency in SF5773 is internally limited to 80KHz in QR mode.

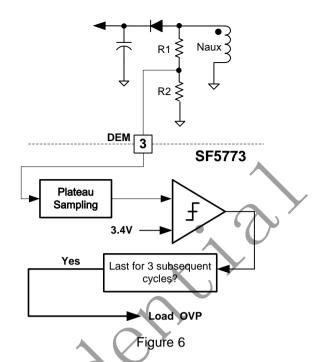
#### **♦** Burst Mode Control

When the loading is very small, the system enters into burst mode. When VFB drops below VFB\_min\_duty, SF5773 will stop switching and output voltage starts to drop, which causes the VFB to rise, as shown in Fig.5. Once VFB rises above VFB\_min\_duty, switching resumes. Burst mode control alternately enables and disables switching, thereby reducing switching loss in standby mode.



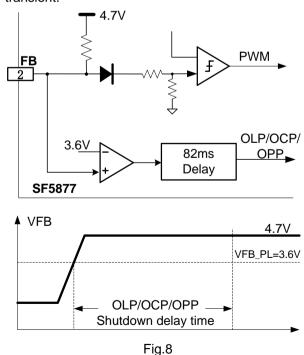
# Output Over Voltage Protection (Output OVP)

In SF5773, the output OVP is integrated by plateau sampling the auxiliary winding in flyback phase. An internal 2.5us sampling delay guarantees a clean plateau, provided that the leakage inductance ringing has been fully damped. The threshold voltage for output OVP is 3.4V, as shown in Fig.6 If the sampled plateau voltage exceeds the OVP threshold (3.4V), an internal counter starts counting subsequent OVP events. If OVP events are detected in successive 3 cycles, the controller assumes a true output OVP and it stops all switching operations. The counter has been added to prevent incorrect OVP detection which might occur during ESD or lightning events. If the output voltage exceeds the OVP threshold less than 3 successive cycles, the internal counter will be cleared and no fault is asserted. Output OVP is auto-recovery mode protection (mentioned below).



# Over Load Protection (OLP) / Over Current Protection (OCP) / Over Power Protection (OPP) / Open Loop Protection (OLP)

When OLP/OCP/OPP/Open Loop occurs, a fault is detected. If this fault is present for more than 82ms (typical), the protection will be triggered, the IC will experience an auto-recovery mode protection, as shown in Fig.8. The 82ms delay time is to prevent the false trigger from the power-on and turn-off transient.





### Auto Recovery Mode Protection

As shown in Fig.9, once a fault condition is detected, switching will stop. This will cause VDD to fall because no power is delivered form the auxiliary winding. When VDD falls to UVLO(off) (typical 9V), the protection is reset and the operating current reduces to the startup current, which causes VDD to rise, as shown in Fig.9. However, if the fault still exists, the system will experience the above mentioned process. If the fault has gone, the system resumes normal operation. In this manner, the auto restart can alternatively enable and disable the switching until the fault condition is disappeared.

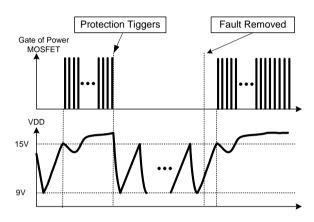


Fig.9

## VDD OVP(Over Voltage Protection)

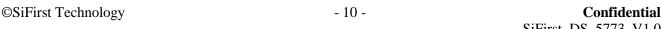
OVP (Over Voltage Protection) implemented in SF5773 and it is a protection of auto-recovery mode.

## **♦** Pin Floating Protection

In SF5773, if pin floating situation occurs, the protection is triggered immediately and the system will experience the process of auto-recovery mode protection.

#### **♦** Soft Gate Drive

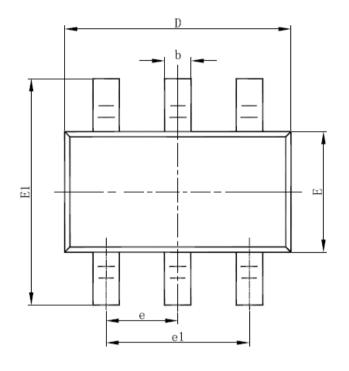
The driving stage of SF5773 is a soft totem-pole gate driver to minimize EMI. Cross conduction has been avoided to minimize heat dissipation, increase efficiency, and enhance reliability.

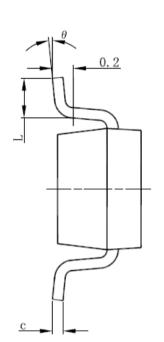


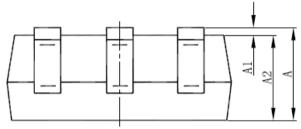


# **PACKAGE MECHANICAL DATA**

# SOT-23-6L PACKAGE OUTLINE DIMENSIONS







Symbol	Dimensions I	n Millimeters	Dimension	s In Inches	
Symbol	Min	Max	Min	Max	
Α	1.000	1.300	0.039	0.051	
A1	0.000	0.150	0.000	0.006	
A2	1.000	1.200	0.039	0.047	
b	0.300	0.500	0.012	0.020	
C	0.100	0.200	0.004	0.008	
D	2.800	3.020	0.110	0.119	
E	1.500	1.700	0.059	0.067	
E)	2.600	3.000	0.102	0.118	
e	0.950	(BSC)	0.037 (BSC)		
e1	1.800	2.000	0.071	0.079	
L	0.300	0.600	0.012	0.024	
θ	O°	8º	00	80	



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