



35 mm sq.

1.8°/step **RoHS**

Unipolar winding, Lead wire type

Customizing

Hollow **Shaft modification**

Varies depending on the model number and quantity. Contact us for details.

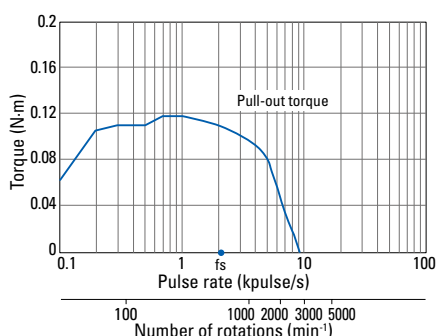
Unipolar winding, Lead wire type

Model no.		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass	Motor length (L)
Single shaft	Dual shaft	N·m min.	A/phase	Ω/phase	mH/phase	×10 ⁻⁴ kg·m ²	kg	mm
SH3533-12U40	SH3533-12U10	0.12	1.2	2.4	1.3	0.02	0.17	33
SH3537-12U40	SH3537-12U10	0.15	1.2	2.7	2	0.025	0.2	37
SH3552-12U40	SH3552-12U10	0.23	1.2	3.4	2.8	0.043	0.3	52

Characteristics diagram

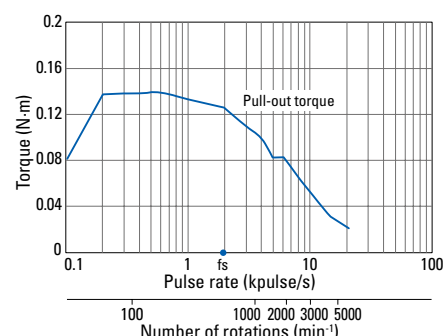
SH3533-12U40 SH3533-12U10

Constant current circuit
Source voltage: 24 VDC
Operating current:
1.2 A/phase, 2-phase
energization (full-step)
Pull-out torque:
 $J_L=0.33 \times 10^{-4} \text{ kg} \cdot \text{m}^2$ (use the
rubber coupling)
fs: Maximum self-start
frequency when not
loaded



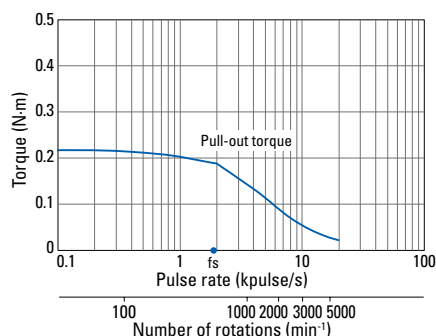
SH3537-12U40 SH3537-12U10

Constant current circuit
Source voltage: 24 VDC
Operating current:
1.2 A/phase, 2-phase
energization (full-step)
Pull-out torque:
 $J_L=0.33 \times 10^{-4} \text{ kg} \cdot \text{m}^2$ (use the
rubber coupling)
fs: Maximum self-start
frequency when not
loaded

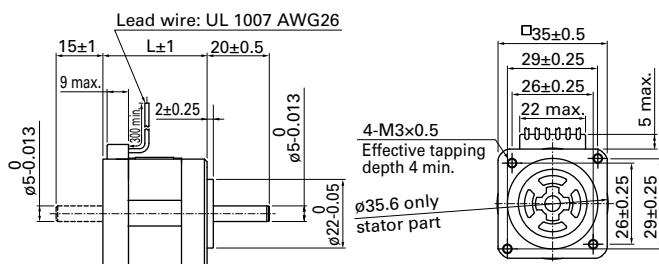


SH3552-12U40 SH3552-12U10

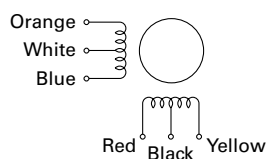
Constant current circuit
Source voltage: 24 VDC
Operating current:
1.2 A/phase, 2-phase
energization (full-step)
Pull-out torque:
 $J_L=0.94 \times 10^{-4} \text{ kg} \cdot \text{m}^2$ (use the
rubber coupling)
fs: Maximum self-start
frequency when not
loaded



Dimensions (Unit: mm)



Internal wiring



Compatible drivers

Model no.: US1D200P10 (DC input)

Operating current select switch setting: 8

The characteristics diagram shown above is from our experimental circuit.