Si**I** 154

Preliminary Data Sheet



General Description

The Sil154 transmitter uses PanelLink® Digital technology to support displays ranging from VGA to SXGA resolutions (25-112MPps) in a single link interface. The Sil154 transmitter has a highly flexible interface with 12-bit (½ pixel) or 24-bit 1 pixel/clock input for true color (16.7 million) support. In 24-bit mode, the data may be latched on the positive or negative edge of the clock. In 12-bit mode, multiple clocking options exist: with a single clock, data will be clocked on the falling and the rising edge; with dual clocks data can be clocked on either the falling edge of the rising edge of both clocks.

PanelLink Digital technology simplifies PC design by resolving many of the system level issues associated with high-speed digital design, providing the system designer with a digital interface solution that is quicker to market and lower in cost.

Features

- Scaleable Bandwidth: 25-112 Mega-pixels/sec (VGA to SXGA)
- Flexible Panel Interface: 12-bit (½ pixel) or 24-bit 1 pixel/clock inputs
- I²C Slave Programming Interface
- Low Voltage Interface: 1.0 to 1.8V capable
- Receiver Detection: Supports Hot Plug Detection through RxDetect feature
- De-skewing Option: varies clock to data timing
- High Inter-Pair Skew Tolerance: 1 full input clock cycle (9 ns at 108MHz)
- Low Power: 3.3V core operation and power down mode
- Cable Distance Support: over 5m with twisted pair, fiber-optics ready
- Standards Compliant with DVI 1.0 (DVI is backwards compliant with VESA® P&D™ and DFP)

SiI 154 Pin Diagram

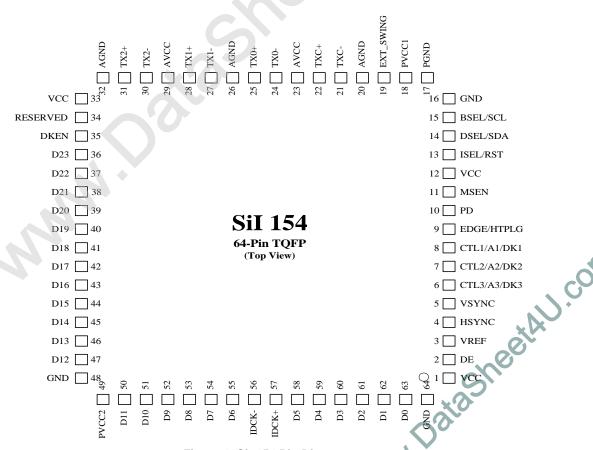
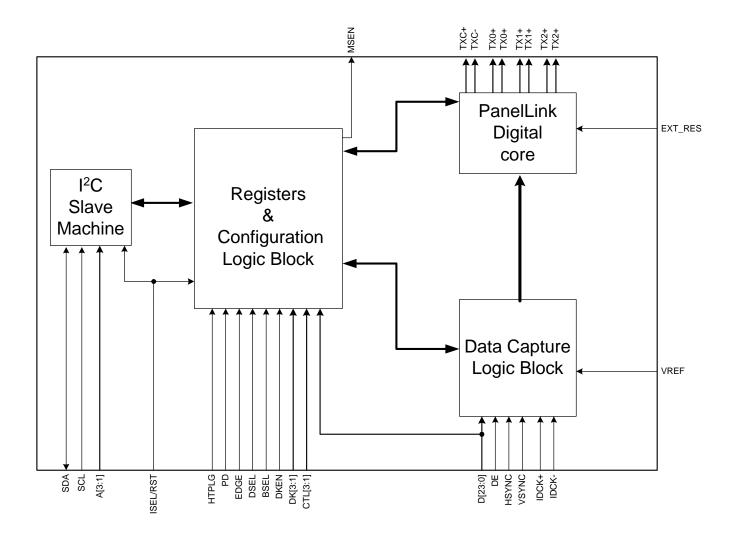


Figure 1. SiI 154 Pin Diagram



Functional Block Diagram



Electrical Specifications

Absolute Maximum Conditions

Symbol	Parameter	Min	Тур	Max	Units
V_{CC}	Supply Voltage 3.3V	-0.3		4.0	V
V_{I}	Input Voltage	-0.3		V _{CC} + 0.3	V
Vo	Output Voltage	-0.3		V _{CC} + 0.3	V
T _A	Ambient Temperature (with power applied)	-25		105	°C
T _{STG}	Storage Temperature	-40		125	°C
P_{PD}	Package Power Dissipation			1	W

Notes: ¹ Permanent device damage may occur if absolute maximum conditions are exceeded. ² Functional operation should be restricted to the conditions described under Normal Operating Conditions.

Normal Operating Conditions

Symbol	Parameter	Min	Тур	Max	Units
V_{CC}	Supply Voltage	3.0	3.3	3.6	V
V _{CCN}	Supply Voltage Noise ¹			100	mV_{P-P}
T _A	Ambient Temperature (with power applied)	0	25	70	°C

Notes: ¹Guaranteed by design.

DC Digital I/O Specifications

Under normal operating conditions unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
V _{IH}	High Swing High-level Input Voltage	$V_{REF} = V_{CC}$	2			V
V _{IL}	High Swing Low-level Input Voltage	$V_{REF} = V_{CC}$			0.8	V
V_{DDQ}^{2}	Low Swing Voltage		1		1.8	V
V _{SH}	Low Swing High-level Input Voltage	$V_{REF} = V_{DDQ}/2$		V _{DDQ} /2 + 300mV		V
V _{SL}	Low Swing Low-level Input Voltage	$V_{REF} = V_{DDQ}/2$		V _{DDQ} /2 – 100mV		V
V_{CINL}	Input Clamp Voltage ¹	$I_{CL} = -18mA$			GND -0.8	V
V_{CIPL}	Input Clamp Voltage ¹	$I_{CL} = 18mA$			VCC + 0.8	V
I _{IL}	Input Leakage Current		-10		10	μΑ

DC Specifications

Under normal operating conditions unless otherwise specified.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
V_{OD}	Differential Voltage	$R_{LOAD} = 50\Omega$				
	Single ended peak to peak amplitude	$R_{\text{EXT_SWING}} = 850\Omega$	250	300	350	mV
		$R_{EXT SWING} = 680\Omega$	310	370	430	mV
		$R_{EXT_SWING} = 400\Omega$	580	650	720	mV
V_{DOH}	Differential High-level Output Voltage ¹			AVCC		V
V_{REF}	Input Reference Voltage	Low Swing	0.45	V _{DDQ} /2	1	V
		High Swing		VCC		V
I _{DOS}	Differential Output Short Circuit Current ¹	$V_{OUT} = 0V$			5	μΑ
I_{PD}	Power-down Current ²				4	mΑ
I _{CCT}	Transmitter Supply Current	DCLK = 112 MHz, 1 pixel/clock mode, R _{EXT_SWING} = 680Ω				
		Worse Case Pattern ³		68	90	mA

Notes: ¹Guaranteed by design. ²V_{DDQ} Defines max voltage level of low swing input. It is not an actual input voltage.

Notes: ¹Guaranteed by design.

²Assumes all inputs to the transmitter are not toggling.

³Black and white checkerboard pattern, each checker is one pixel wide.

AC Specifications

Under normal operating conditions unless otherwise specified.

Symbol	nal operating conditions unless otherwis Parameter	Conditions	Min	Тур	Max	Units
T _{CIP}	IDCK Period, 1-pixel/clock		8.93		50	ns
F _{CIP}	IDCK Frequency, 1-pixel/clock		20		112	MHz
T _{CIH}	IDCK High Time at 112MHz		3			ns
T _{CIL}	IDCK Low Time at 112MHz		3			ns
T _{IJIT}	Worst Case IDCK Clock Jitter ^{2,3}				2	ns
T _{SIDF}	Data, DE Setup Time to IDCK falling edge (VSYNC and HSYNC are clocked on the rising edge with equal setup and hold times)	Single Edge (DSEL = 0, DKEN = 0, EDGE = 0)	1.5			ns
T _{HIDF}	Data, DE, VSYNC, HSYNC Hold Time from IDCK falling edge (VSYNC and HSYNC are clocked on the rising edge with equal setup and hold times)	Single Edge (DSEL = 0, DKEN = 0, EDGE = 0)	0.9			ns
T_{SIDR}	Data, DE, VSYNC, HSYNC Setup Time to IDCK rising edge ¹ (VSYNC and HSYNC are clocked on the falling edge with equal setup and hold times)	Single Edge (DSEL = 0, DKEN = 0, EDGE = 1)	1.5			ns
T _{HIDR}	Data, DE, VSYNC, HSYNC Hold Time from IDCK rising edge ¹ (VSYNC and HSYNC are clocked on the falling edge with equal setup and hold times)	Single Edge (DSEL = 0, DKEN = 0, EDGE = 1)	0.9			ns
T _{SID}	Data Setup Time to IDCK falling/rising edge ¹ (VSYNC and HSYNC are clocked on the secondary edge with equal setup and hold times)	Dual Edge (DSEL = 1, DKEN = 0, BSEL = 0)	0.6			ns
T _{HID}	Data Hold Time from IDCK falling/rising edge ¹ (VSYNC and HSYNC are clocked on the secondary edge with equal setup and hold times)	Dual Edge (DSEL = 1, DKEN = 0, BSEL = 0)	1.5			ns
T_{DDF}	VSYNC, HSYNC Delay from DE falling edge ¹		1 T _{CIP}			ns
T_{DDR}	VSYNC, HSYNC Delay to DE rising edge ¹		1 T _{CIP}			ns
T _{HDE}	DE high time ¹				8000 T _{CIP}	ns
T_LDE	DE low time ¹		10 T _{CIP}		5	ns
T _{STEP}	De-skew step size increment	DKEN = 1		240		ps
S _{LHT}	Differential Swing Low-to-High Transition Time	$C_{LOAD} = 5pF, R_{LOAD} = 50\Omega$ $R_{EXT~SWING} = 680\Omega$	0.3	0.5	0.7	ns
S _{HLT}	Differential Swing High-to-Low Transition Time	$C_{LOAD} = 5pF, R_{LOAD} = 50\Omega$ $R_{EXT~SWING} = 680\Omega$	0.3	0.5	0.7	ns

Notes: ¹Guaranteed by design.

²Jitter can be estimated by 1) triggering a digital scope at the rising of input clock and 2) measuring the peak to peak time spread of the rising edge of the input clock 1us after the trigger.

³Actual jitter tolerance may be higher depending on the frequency of the jitter.

Input Timing Diagrams

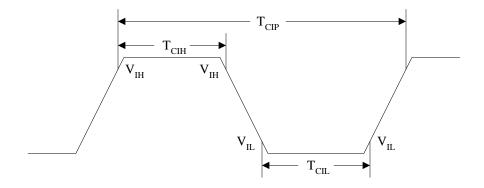


Figure 2. Clock Cycle/High/Low Times

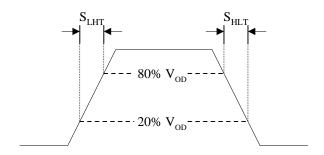


Figure 3. Differential Transition Times

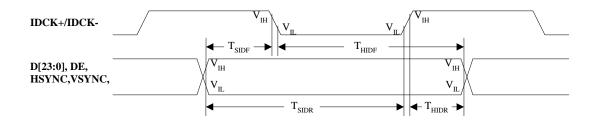


Figure 4. Control and Single-Edge-Data Setup/Hold Times to IDCK+/IDCK-

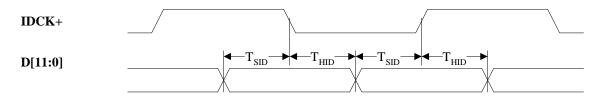


Figure 5. Dual Edge Data Setup/Hold Times to IDCK+

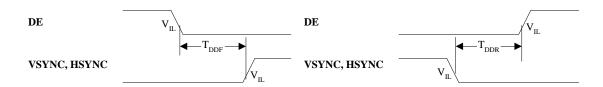


Figure 6. VSYNC, HSYNC Delay Times from/to DE

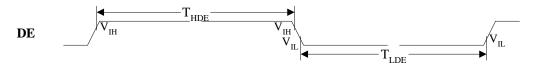


Figure 7. DE High/Low Times

Data Mapping

12-bit Input Mode (BSEL = 0)

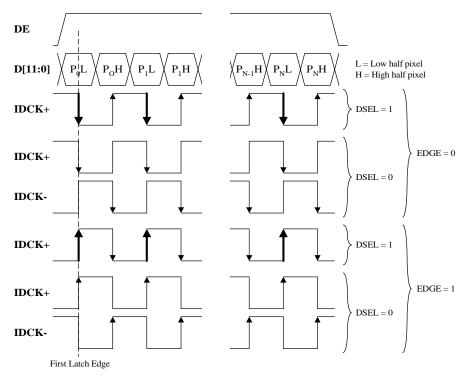


Figure 8. Logical Interface Options for 12-bit Mode

12-bit Mode Data Mapping

		P0	P1		P	2
	P0L	P0H	P1L	P1H	P2L	P2H
Pin Name	Low	High	Low	High	Low	High
D11	G0[3]	R0[7]	G1[3]	R1[7]	G2[3]	R2[7]
D10	G0[2]	R0[6]	G1[2]	R1[6]	G2[2]	R2[6]
D9	G0[1]	R0[5]	G1[1]	R1[5]	G2[1]	R2[5]
D8	G0[0]	R0[4]	G1[0]	R1[4]	G2[0]	R2[4]
D7	B0[7]	R0[3]	B1[7]	R1[3]	B2[7]	R2[3]
D6	B0[6]	R0[2]	B1[6]	R1[2]	B2[6]	R2[2]
D5	B0[5]	R0[1]	B1[5]	R1[1]	B2[5]	R2[1]
D4	B0[4]	R0[0]	B1[4]	R1[0]	B2[4]	R2[0]
D3	B0[3]	G0[7]	B1[3]	G1[7]	B2[3]	G2[7]
D2	B0[2]	G0[6]	B1[2]	G1[6]	B2[2]	G2[6]
D1	B0[1]	G0[5]	B1[1]	G1[5]	B2[1]	G2[5]
D0	B0[0]	G0[4]	B1[0]	G1[4]	B2[0]	G2[4]

Notes: ¹In the figure, clock edges represented by arrows signify the latching edge. The primary latch edge is indicated by the dark rows. The lower half of the pixel (L) is latched by the primary clock edge. ²HSYNC and VSYNC are latched on the secondary clock edge in dual edge mode.

³Color Pixel Components: R = RED, G = GREEN, B = BLUE

⁴Bit significance within a color: [7:0] = [MSB:LSB]

24-bit Input Mode (BSEL = 1)

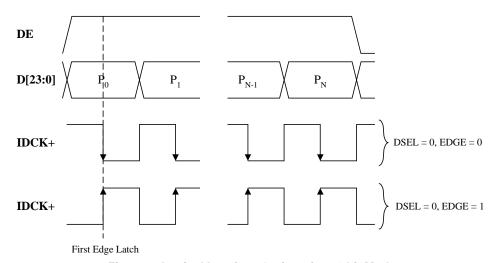


Figure 9. Logical Interface Options for 24-bit Mode

24-bit Mode Data Mapping

Pin Name	P0	P1	P2
D23	R0[7]	R1[7]	R2[7]
D22	R0[6]	R1[6]	R2[6]
D21	R0[5]	R1[5]	R2[5]
D20	R0[4]	R1[4]	R2[4]
D19	R0[3]	R1[3]	R2[3]
D18	R0[2]	R1[2]	R2[2]
D17	R0[1]	R1[1]	R2[1]
D16	R0[0]	R1[0]	R2[0]
D15	G0[7]	G1[7]	G2[7]
D14	G0[6]	G1[6]	G2[6]
D13	G0[5]	G1[5]	G2[5]
D12	G0[4]	G1[4]	G2[4]
D11	G0[3]	G1[3]	G2[3]
D10	G0[2]	G1[2]	G2[2]
D9	G0[1]	G1[1]	G2[1]
D8	G0[0]	G1[0]	G2[0]
D7	B0[7]	B1[7]	B2[7]
D6	B0[6]	B1[6]	B2[6]
D5	B0[5]	B1[5]	B2[5]
D4	B0[4]	B1[4]	B2[4]
D3	B0[3]	B1[3]	B2[3]
D2	B0[2]	B1[2]	B2[2]
D1	B0[1]	B1[1]	B2[1]
D0	B0[0]	B1[0]	B2[0]

Notes: ¹ In the figure, clock edges represented by arrows signify the latching edge.
² In 24 bit mode, dual edge mode (DSEL = 1) is not supported.
³ Color Pixel Components: R = RED, G = GREEN, B = BLUE
⁴ Bit significance within a color: [7:0] = [MSB:LSB]
⁵ HSYNC and VSYNC are latched by the opposite edge of where data is latched.

Data De-skew

Input clock to data setup/hold time can be adjusted through the use of the de-skew feature. It should be noted that it is the clock that is being adjusted. When DKEN is high, the configuration pins DK[3:1] or applicable I^2C registers can be used to vary the input setup/hold time by an amount T_{CD} given by the formula

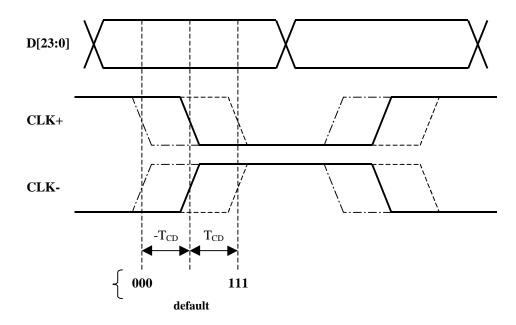
 $T_{CD} = (DK[3:1] - 4)*T_{STEP}.$

Where:

 T_{CD} is the amount setup/hold timing variation DK[3:1] is the setting of the de-skew configuration pins T_{STEP} is the step size

This feature can be used in both 12-bit or 24-bit mode.

If DKEN is set low, the DK[3:1] inputs are ignored, and the default setting of $T_{CD} = 0$ is used.



10. SiI 154 De-skewing feature timing

Pins Descriptions

Input Pin

Pin Name	Pin#	Туре	Description
D23-D12	36-47	In	Top half of 24-bit pixel bus. When BSEL = HIGH, this bus inputs the top half of the 24-bit pixel bus. When BSEL = LOW, these bits are not used to input pixel data. In this mode, the state of D[23:16] is input to the I²C register CFG. This allows 8-bits of user configuration data to be read by the graphics controller through the I2C interface (see I²C register definition). D[15:12] are reserved for Sil use only and should be tied to GND when not in use.
D11-D0	50-55, 58-63	In	Bottom half of 24-bit pixel bus / 12-bit pixel bus input. When BSEL = HIGH, this bus inputs the bottom half of the 24-bit pixel bus. When BSEL = LOW, this bus inputs ½ a pixel at every latch edge (both falling and/or rising).
IDCK+	57	In	Input Data Clock +.
IDCK-	56	In	Input Data Clock –. This clock is only used in 12-bit mode when dual edge clocking is turned off (DSEL = LOW). It is used to provide the ODD latching edges for multi-phased clocking. If (BSEL = HIGH) or (DSEL = HIGH) this pin is unused and should be tied to GND.
DE	2	ln	Data enable. This signal is high when input pixel data is valid to the transmitter and low otherwise. It is critical that this signal have the same setup/hold timing as the data bus.
HSYNC	4	In	Horizontal Sync input control signal.
VSYNC	5	ln	Vertical Sync input control signal. Note: In 12 bit mode the HSYNC and VSYNC signals are latched by the
			secondary clock edge.
CTL1/A1/DK1 CTL2/A2/DK2 CTL3/A3/DK3	8 7 6	In	The use of these multi-function inputs depends on the settings of ISEL and DKEN. These inputs are regular high-swing CMOS level inputs. These pins contain weak pull-down resistors so that if left unconnected, they will be LOW. ISEL = LOW, DKEN = LOW General Purpose Input CTL[3:1] are active, for backward compatibility. These pins must be used to send DC signals only. ISEL = LOW, DKEN = HIGH DK[3:1] are active, these inputs are used to select the de-skewing setting for the input bus. ISEL = HIGH, DKEN = HIGH A[3:1] are active, these bits are used to set the lower 3 bits of the I ² C device address.

Status Pin

Pin Name	Pin #	Туре	Description
MSEN	11	Out	Monitor Sense. This pin is an open collector output. The behavior of this
			output depends on whether I ² C interface is enabled or disabled.
			I ² C bus is disabled (ISEL = LOW)
			A HIGH level indicates a powered on receiver is detected at the
			differential outputs.
			A LOW level indicates a powered on receiver is not detected.
			This function can only be used in DC-coupling systems.
			I ² C bus is enabled (ISEL = HIGH)
			The output is programmable through the I ² C interface (see I ² C
			register definitions).
			This function can only be used in DC-coupling systems.
			An external 5K pull-up resistor is required on this pin.

Configuration/Programming Pins

Din Name			
Pin Name	Pin #	Туре	Description
ISEL/RST	13	In	I ² C Interface Select. If HIGH, then the I ² C interface is active. If LOW, the I ² C is inactive and the chip configuration is read from the configuration strapping pins. This pin also acts as an asynchronous reset to the I ² C interface controller. The reset is active when this input is held LOW.
		_	Note: When then the I ² C interface is active, DKEN must be set high.
BSEL/SCL	15	In	Input bus select / I ² C clock. This pin is an open collector input. If I ² C bus is enabled (ISEL = HIGH), then this pin is the I ² C clock input. If the I ² C is disabled (ISEL = LOW), then this pin selects the input bus width. Input Bus Select: HIGH selects 24-bit input mode LOW selects 12-bit input mode
DSEL/SDA	14	In	Dual edge clock select / I ² C Data. This pin is an open collector input. If I ² C bus is enabled (ISEL = HIGH), then this pin is the I ² C data line. If the I ² C bus is disabled (ISEL = LOW), then this pin selects whether dual edge clocking is used. Dual edge clock select: When HIGH, IDCK+ latches input data on both falling and rising clock edges. When LOW, IDCK+/IDCK- latches input data on only falling or rising clock edges. See the differences between 12 and 24 bit mode below: In 12-bit mode (BSEL = LOW): If HIGH (dual edge), IDCK+ is used to latch data on both falling and rising edges. If LOW (single edge), IDCK+ latches 1 st half data and IDCK- latches 2 nd half data. In 24-bit mode (BSEL = HIGH): DSEL must be set LOW
EDGE/HTPLG	9	In	Edge select / Hot Plug input. If the I²C bus is enabled (ISEL = HIGH), then this pin is used to monitor the "Hot Plug" detect signal (Please refer to the DVI TM or VESA® P&D TM and DFP standards). NOTE: This Input is ONLY 3.3V tolerant and has no internal debouncer circuit. If I²C bus is disabled (ISEL = LOW), then this pin selects the clock edge that will latch the data. How the EDGE setting works depends on whether dual or single edge latching is selected: Dual Edge Mode (DSEL = HIGH) EDGE = LOW, the primary edge (first/even latch edge after DE is asserted) is the falling edge. EDGE = HIGH, the primary edge (first/odd latch edge after DE is asserted) is the rising edge. Note: In dual edge mode, the control signals HS and VS are only latched on the secondary clock edge. Single Edge Mode (DSEL = LOW) EDGE = LOW, the falling edge of the clock is used to latch data. EDGE = HIGH, the rising edge of the clock is used to latch data.
DKEN	35	In	De-Skewing enable. This pin determines whether the de-skewing increments are to be read in through the DK[3:1] pins or the General Purpose Input CTL[3:1] are active. DKEN = LOW, ISEL = LOW Default de-skewing setting is used and General Purpose Input CTL[3:1] are active. DKEN = HIGH, ISEL = LOW DK[3:1] is used as the de-skewing setting. The de-skewing increments are T _{STEP} DKEN = HIGH, ISEL = HIGH If I ² C bus is enabled (ISEL = HIGH), then DKEN must be set high, DK[3:1] are ignored and the de-skewing increments are selected through the I ² C interface (see the I ² C register definitions).

Input Voltage Reference Pin

Pin Name	Pin#	Type	Description
VREF	3	Analog	Input Reference Voltage. Selects the swing range of the digital parallel
		In	data inputs (D[23:0], DE, VSYNC, and HSYNC).
			When VREF is HIGH, the digital parallel data inputs are normal high swing
			CMOS inputs.
			When VREF is below 1.8V, the digital parallel data inputs are low swing
			inputs. In low swing mode, VREF must be set to ½ of \bigvee_{DQ} .

Power Management Pin

Pin Name	Pin#	Туре	Description
PD	10	In	Power Down (active low). A High level indicates normal operation and a
			Low level indicates power down mode. During power down mode,
			digital input, output buffers and I2C interface are NOT disabled. The
			PanelLink Digital core is powered down. Note that when ISEL = HIGH,
			this pin should be tied LOW to ensure the chip is powered off when reset is
			asserted.

Reserved

Pin Name	Pin#	Type	Description
RESERVED	34	In	Must be tied LOW for normal operation.

Differential Signal Data Pins

Pin Name	Pin#	Type	Description
TX0+	25	Analog	TMDS [™] Low Voltage Differential Signal output data pairs.
TX0-	24	Analog	
TX1+	28	Analog	
TX1-	27	Analog	
TX2+	31	Analog	
TX2-	30	Analog	
TXC+	22	Analog	TMDS [™] Low Voltage Differential Signal output clock pairs.
TXC-	21	Analog	
EXT_SWING	19	Analog	Voltage Swing Adjust. A resistor should tie this pin to AVCC. This
			resistance determines the amplitude of the voltage swing. For remote
			display applications, 400Ω is recommended. For notebook computers,
			680Ω is recommended.

Power and Ground Pin

Pin Name	Pin #	Туре	Description
VCC	1,12,33	Power	Digital VCC, must be set to 3.3V nominal.
GND	16,48,64	Ground	Digital GND.
AVCC	23,29	Power	Analog VCC, must be set to 3.3V nominal.
AGND	20,26,32	Ground	Analog GND.
PVCC1	18	Power	PLL Analog VCC, must be set to 3.3V nominal.
PVCC2	49	Power	PLL Analog VCC, must be set to 3.3V nominal.
PGND	17	Ground	PLL Analog GND.

Please refer to PanelLink Digital Basic Design/Application Guide (Sil-AN-0005)

I²C Register

Addr.	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x0	VND_IDL (RO)							
0x1	VND_IDH (RO)							
0x2	DEV_IDL (RO)							
0x3	DEV_IDH (RO)							
0x4	DEV_REV (RO)							
0x5	RSVD[7:0] (RO)							
0x6	FRQ_LOW (RO)							
0x7	FRQ_HIGH (RO)							
0x8	RSVD[1:	:0]	VEN (R/W)	HEN (R/W)	DSEL	BSEL	EDGE (RW)	PD (RW)
					(RW)	(RW)		
0x9	VLOW (RO) MSEL[2:0]		(RW)	TSEL	RSEN	HTPLG	MDI (RW)	
					(RW)	(RO)	(RO)	
0xA	DK[3:1] (RW) DKEN (R)			DKEN (RW)	CTL[3:1] (RW)			RSVD
	(RW)						(RW)	
0xB	CFG[7:0] (D[23:16]) (RO)							
0xC	VDJK [7:0] (RW) Please see SiI-AN-0022 for application specific values of this register.8							
0xD	RSVD[3:0] (RW) RSVD[3:0] (RO)							
0xE	RSVD[7:0] (RW)							
0xF	RSVD[7:0] (RW)							

Notes: ¹All values are Bit 7 [MSB] and Bit 0 [LSB].

All values are Bit 7 [MSB] and Bit 0 [LSB].

²RW = Read/Write register, RO = Read Only register.

³RSVD = Reserved register. It is available for future use by Silicon Image, Inc.

⁴Values in *Bold/Italics* are for Silicon Image, Inc. test and characterization.

⁵Any read/write register that is RESERVED will require that the user always write the SiI recommended values.

⁶There is no default value on reset. All registers must be written at least once before enabling.

⁷All registers retain their values after a reset except PD and MSEL.

⁸Please see Application Note "SiI154: Setting the VDJK I²C Register Value" (SiI-AN-0022) for application specific values of this register.

I²C Register Definitions

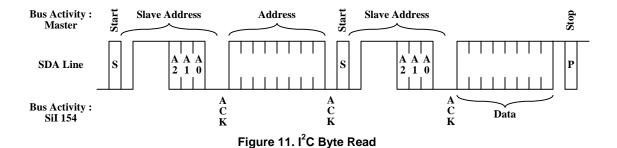
Register Name	Access	Description			
VND IDL	RO	Vendor ID Low byte (0x01)			
VND_IDL	RO	Vendor ID High byte (0x00)			
		Device ID Low byte (0x04)			
DEV_IDL	RO				
DEV_IDH	RO	Device ID High byte (0x00)			
DEV_REV	RO	Device Revision (0x00)			
FRQ_LOW	RO	Low frequency limit at 1-pixel/clock mode (MHz)			
FRQ_HIGH	RO	High frequency limit at 1-pixel/clock mode MHz minus 65MHz (MHz)			
PD	RW	Power Down mode(same function as PD pin)			
		0 – Power Down			
		1 – Normal operation			
EDGE	RW	Edge Select (same function as EDGE pin)			
		0 – Input data is falling edge latched (falling edge latched first in dual edge			
		mode)			
		1 – Input data is rising edge latched (rising edge latched first in dual edge			
		mode)			
BSEL	RW	Input Bus Select (same function as BSEL pin)			
		0 – Input data bus is 12-bits wide			
	5144	1 – Input data bus is 24-bits wide			
DSEL	RW	Dual Edge Clock Select (same function as DSEL pin)			
		0 – Input data is single edge latched			
	D) 4/	1 – Input data is dual edge latched			
HEN	RW	Horizontal Sync Enable:			
		0 – HSYNC input is transmitted as fixed LOW			
VEN	DW	1 – HSYNC input is transmitted as is			
VEN	RW	Vertical Sync Enable:			
		0 – VSYNC input is transmitted as fixed LOW			
MDI	RW	1 – VSYNC input is transmitted as is			
MDI	KVV	Monitor Detect Interrupt O Detection signal has shanged logic level (write one to this hit to clear)			
		 0 – Detection signal has changed logic level (write one to this bit to clear) 1 – Detection signal has not changed state 			
HTPLG	RO	Hot Plug Detect input, the state of HTPLG pin can be read from this bit			
	RO	This bit is HIGH if a powered on receiver is connected to the transmitter			
RSEN	, KO	outputs, LOW otherwise. This function is only available for use in DC-coupled			
		systems.			
TSEL	RW	Interrupt Generation Method			
ISEL	IXVV	0 – Interrupt bit (MDI) is generated by monitoring RSEN			
		pt bit (MDI) is generated by monitoring HTPLG			
MSEL[2:0]	RW	Select source of the MSEN output pin			
WOLL[Z.0]	1000	000 – Force MSEN outputs high (disabled)			
		001 – Outputs the MDI bit (interrupt)			
		010 – Output the RSEN bit (receiver detect)			
		011 – Outputs the HTPLG bit (hot plug detect)			
		1xx – RESERVED			
VLOW	RO	This bit is a 1 if the VREF signal indicates low swing inputs. It is a 0 if VREF			
-		indicates high swing inputs			
CTL[3:1]	RW	General purpose inputs (same as CTL[3:1] pins)			
CFG[7:0]	RO	Contains state of inputs D[23:16]. These pins can be used to provide user			
- <u>-</u>		selectable configuration data through the I ² C bus. Only available in 12-bit			
		mode			
VDJK[7:0]	RW	Please see Application Note "SiI154: Setting the VDJK I ² C Register Value"			
		(SiI-AN-0022) for application specific values of this register.			
	1	1 (2.2.1 0.2.2) for approximant opening raided of the regioner.			

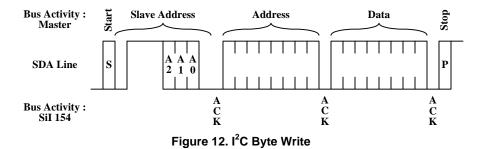
I²C Register Definitions (cont'd)

Register Name	Access	Description
DK[3:1]	RW	De-Skewing Setting. Increment T _{STEP} psec.
		000 : 1 step -> minimum setup / maximum hold
		001 : 2 step
		010 : 3 step
		011: 4 step
		100 : 5 step -> default
		101 : 6 step
		110 : 7 step
		111 : 8 step -> maximum setup / minimum hold
DKEN	RW	De-Skewing Enable through DK[3:1] bits. High when enabled, Low otherwise.

I²C Slave Interface

The SiI154 slave state machine does not require an internal clock and supports only byte read and write (see Figures below). Page mode is not supported. The 7-bit binary address of the I^2C machine is "0111 $A_3A_2A_1X$ ", where A[3:1] are pin programmable or set to "000" by default.



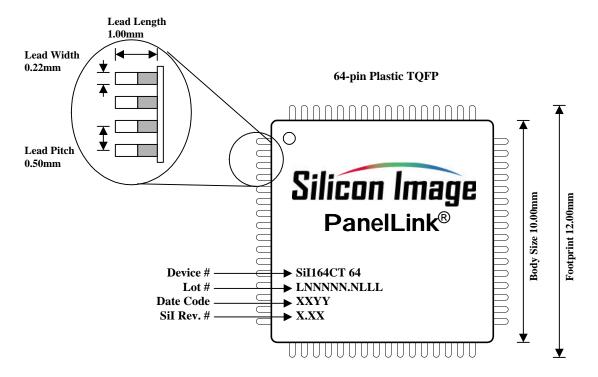


RESET Description

The input pin ISEL/RST serves as an asynchronous reset (active LOW) for the I^2C slave controller in I^2C mode. The programming registers, that are accessible over the I^2C bus, retain their previous values during and after the reset except for PD and MSEL[2:0] register bits. All of the I^2C registers must be manually set to ensure proper operation. There are no default settings for the I^2C registers. The minimum low time for proper reset is T_{CIP} . The state of these bits is set during the reset period according to the following rules:

- After a RESET, the SiI154 will be turned OFF. When reset is asserted, the SiI154 power down control bit, PD, is forced LOW. When the SiI154 comes out of reset (ISEL/RST is set HIGH), the SiI154 will be turned OFF. To turn the SiI154 back ON, the PD bit must be set HIGH over the I²C bus.
- After a RESET, MSEN output is disabled. When reset is asserted, MSEN[2:1] is forced to '000'. This
 causes the MSEN output to be tri-stated.

Package Dimensions 64-pin TQPF Package Dimensions



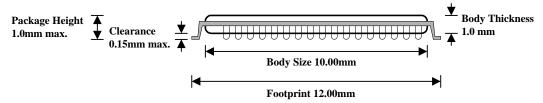


Figure 13. SiI154 Package Diagram

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