

SM72501

SM72501 SolarMagic Precision, CMOS Input, RRIO, Wide Supply Range Amplifier



Literature Number: SNIS157B

SM72501

SolarMagic Precision, CMOS Input, RRIO, Wide Supply Range Amplifier

General Description

The SM72501 is a low offset voltage, rail-to-rail input and output precision amplifier with a CMOS input stage and a wide supply voltage range. The SM72501 is ideal for sensor interface and other instrumentation applications.

The guaranteed low offset voltage of less than $\pm 200 \mu\text{V}$ along with the guaranteed low input bias current of less than $\pm 1 \text{ pA}$ makes the SM72501 ideal for precision applications. The SM72501 is built utilizing VIP50 technology, which allows the combination of a CMOS input stage and a 12V common mode and supply voltage range. This makes the SM72501 a great choice in many applications where conventional CMOS parts cannot operate under the desired voltage conditions.

The SM72501 has a rail-to-rail input stage that significantly reduces the CMRR glitch commonly associated with rail-to-rail input amplifiers. This is achieved by trimming both sides of the complimentary input stage, thereby reducing the difference between the NMOS and PMOS offsets. The output of the SM72501 swings within 40 mV of either rail to maximize the signal dynamic range in applications requiring low supply voltage.

The SM72501 is offered in the space saving 5-Pin SOT23. This small package is an ideal solution for area constrained PC boards and portable electronics.

Features

- Renewable Energy Grade

Unless otherwise noted, typical values at $V_S = 5\text{V}$

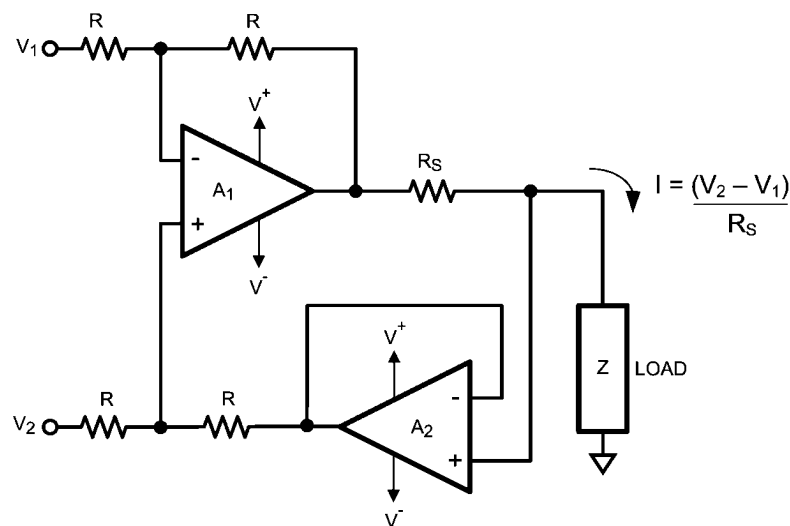
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|---------------------------------|--|
| ■ Input offset voltage | $\pm 200 \mu\text{V}$ (max) |
| ■ Input bias current | $\pm 200 \text{ fA}$ |
| ■ Input voltage noise | 9 nV/ $\sqrt{\text{Hz}}$ |
| ■ CMRR | 130 dB |
| ■ Open loop gain | 130 dB |
| ■ Temperature range | -40°C to 125°C |
| ■ Unity gain bandwidth | 2.5 MHz |
| ■ Supply current (SM72501) | 715 μA |
| ■ Supply voltage range | 2.7V to 12V |
| ■ Rail-to-rail input and output | |

Applications

- High impedance sensor interface
- Battery powered instrumentation
- High gain amplifiers
- DAC buffer
- Instrumentation amplifier
- Active filters



Typical Application



Precision Current Source

30142105

Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

ESD Tolerance (Note 2)

| | |
|--------------------------------------|---------------------------|
| Human Body Model | 2000V |
| Machine Model | 200V |
| Charge-Device Model | 1000V |
| V_{IN} Differential | ± 300 mV |
| Supply Voltage ($V_S = V^+ - V^-$) | 13.2V |
| Voltage at Input/Output Pins | $V^{++} 0.3V, V^- - 0.3V$ |
| Input Current | 10 mA |

| | |
|------------------------------------|---|
| Storage Temperature Range | -65°C to $+150^\circ\text{C}$ |
| Junction Temperature (Note 3) | $+150^\circ\text{C}$ |
| Soldering Information | |
| Infrared or Convection (20 sec) | 235°C |
| Wave Soldering Lead Temp. (10 sec) | 260°C |

Operating Ratings (Note 1)

| | |
|--|---|
| Temperature Range (Note 3) | -40°C to $+125^\circ\text{C}$ |
| Supply Voltage ($V_S = V^+ - V^-$) | 2.7V to 12V |
| Package Thermal Resistance (θ_{JA} (Note 3)) | |
| 5-Pin SOT23 | 265°C/W |

3V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 3V$, $V^- = 0V$, $V_{CM} = V^+/2$, and $R_L > 10\text{ k}\Omega$ to $V^+/2$. **Boldface** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|------------|--|---|--------------------------------------|-----------------|---|------------------------------|
| V_{OS} | Input Offset Voltage | | | ± 37 | ± 200 ± 500 | μV |
| TCV_{OS} | Input Offset Voltage Temperature Drift | (Note 7) | | ± 1 | ± 5 | $\mu\text{V}/^\circ\text{C}$ |
| I_B | Input Bias Current | (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ | | ± 0.2 | ± 1 ± 50 ± 1 ± 400 | pA |
| I_{OS} | Input Offset Current | | | 40 | | fA |
| CMRR | Common Mode Rejection Ratio | $0V \leq V_{CM} \leq 3V$ | 86 80 | 130 | | dB |
| PSRR | Power Supply Rejection Ratio | $2.7V \leq V^+ \leq 12V, V_O = V^+/2$ | 86 82 | 98 | | dB |
| CMVR | Common Mode Voltage Range | CMRR ≥ 80 dB CMRR ≥ 77 dB | -0.2 -0.2 | | 3.2 3.2 | V |
| A_{VOL} | Open Loop Voltage Gain | $R_L = 2\text{ k}\Omega$ $V_O = 0.3V$ to $2.7V$ $R_L = 10\text{ k}\Omega$ $V_O = 0.2V$ to $2.8V$ | 100 96 100 96 | 114 124 | | dB |
| V_{OUT} | Output Voltage Swing High | $R_L = 2\text{ k}\Omega$ to $V^+/2$ $R_L = 10\text{ k}\Omega$ to $V^+/2$ | | 40 30 | 80 120 40 60 | mV from V^+ |
| | Output Voltage Swing Low | $R_L = 2\text{ k}\Omega$ to $V^+/2$ $R_L = 10\text{ k}\Omega$ to $V^+/2$ | | 40 20 | 60 80 40 50 | mV |
| I_{OUT} | Output Current (Note 3, Note 9) | Sourcing $V_O = V^+/2$ $V_{IN} = 100\text{ mV}$ Sinking $V_O = V^+/2$ $V_{IN} = -100\text{ mV}$ | 25 15 25 20 | 42 42 | | mA |
| I_S | Supply Current | | | 0.670 | 1.0 1.2 | mA |
| SR | Slew Rate (Note 10) | $A_V = +1, V_O = 2 V_{PP}$ 10% to 90% | | 0.9 | | V/ μs |

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|--------|--------------------------------------|--|-----------------|-----------------|-----------------|------------------------------|
| GBW | Gain Bandwidth | | | 2.5 | | MHz |
| THD+N | Total Harmonic Distortion + Noise | $f = 1 \text{ kHz}$, $A_V = 1$, $R_L = 10 \text{ k}\Omega$ | | 0.02 | | % |
| e_n | Input Referred Voltage Noise Density | $f = 1 \text{ kHz}$ | | 9 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| i_n | Input Referred Current Noise Density | $f = 100 \text{ kHz}$ | | 1 | | $\text{fA}/\sqrt{\text{Hz}}$ |

5V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = 0\text{V}$, $V_{\text{CM}} = V^+/2$, and $R_L > 10 \text{ k}\Omega$ to $V^+/2$.

Boldface limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units | |
|--------------------------|--|---|------------------------------------|-----------------|--|------------------------------|----|
| V_{OS} | Input Offset Voltage | | | ± 37 | ± 200 ± 500 | μV | |
| TCV_{OS} | Input Offset Voltage Temperature Drift | (Note 7) | | ± 1 | ± 5 | $\mu\text{V}/^\circ\text{C}$ | |
| I_B | Input Bias Current | (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ | | ± 0.2 | ± 1 ± 50 | pA | |
| | | (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ | | ± 0.2 | ± 1 ± 400 | | |
| I_{OS} | Input Offset Current | | | 40 | | fA | |
| CMRR | Common Mode Rejection Ratio | $0\text{V} \leq V_{\text{CM}} \leq 5\text{V}$ | 88 83 | 130 | | dB | |
| PSRR | Power Supply Rejection Ratio | $2.7\text{V} \leq V^+ \leq 12\text{V}$, $V_O = V^+/2$ | 86 82 | 100 | | dB | |
| CMVR | Common Mode Voltage Range | CMRR $\geq 80 \text{ dB}$ CMRR $\geq 78 \text{ dB}$ | -0.2 -0.2 | | 5.2 5.2 | V | |
| A_{VOL} | Open Loop Voltage Gain | $R_L = 2 \text{ k}\Omega$ $V_O = 0.3\text{V to } 4.7\text{V}$ | 100 96 | 119 | | dB | |
| | | $R_L = 10 \text{ k}\Omega$ $V_O = 0.2\text{V to } 4.8\text{V}$ | 100 96 | 130 | | | |
| V_{OUT} | Output Voltage Swing High | $R_L = 2 \text{ k}\Omega$ to $V^+/2$ | | 60 | 110 130 | mV from V^+ | |
| | | $R_L = 10 \text{ k}\Omega$ to $V^+/2$ | | 40 | 50 70 | | |
| | Output Voltage Swing Low | $R_L = 2 \text{ k}\Omega$ to $V^+/2$ | | | 50 | 80 90 | mV |
| | | $R_L = 10 \text{ k}\Omega$ to $V^+/2$ | | | 30 | 40 50 | |
| I_{OUT} | Output Current (Note 3, Note 9) | Sourcing $V_O = V^+/2$ $V_{\text{IN}} = 100 \text{ mV}$ | 40 28 | 66 | | mA | |
| | | Sinking $V_O = V^+/2$ $V_{\text{IN}} = -100 \text{ mV}$ | 40 28 | 76 | | | |
| I_S | Supply Current | | | 0.715 | 1.0 1.2 | mA | |
| SR | Slew Rate (Note 10) | $A_V = +1$, $V_O = 4 V_{\text{PP}}$ 10% to 90% | | 1.0 | | $\text{V}/\mu\text{s}$ | |
| GBW | Gain Bandwidth | | | 2.5 | | MHz | |
| THD+N | Total Harmonic Distortion + Noise | $f = 1 \text{ kHz}$, $A_V = 1$, $R_L = 10 \text{ k}\Omega$ | | 0.02 | | % | |

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|--------|--------------------------------------|-----------------------|-----------------|-----------------|-----------------|------------------------------|
| e_n | Input Referred Voltage Noise Density | $f = 1 \text{ kHz}$ | | 9 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| i_n | Input Referred Current Noise Density | $f = 100 \text{ kHz}$ | | 1 | | $\text{fA}/\sqrt{\text{Hz}}$ |

±5V Electrical Characteristics (Note 4)

Unless otherwise specified, all limits are guaranteed for $T_A = 25^\circ\text{C}$, $V^+ = 5\text{V}$, $V^- = -5\text{V}$, $V_{\text{CM}} = 0\text{V}$, and $R_L > 10 \text{ k}\Omega$ to 0V . **Bold-face** limits apply at the temperature extremes.

| Symbol | Parameter | Conditions | Min (Note 6) | Typ (Note 5) | Max (Note 6) | Units |
|--------------------------|--|---|------------------|-----------------|---------------------|------------------------------|
| V_{OS} | Input Offset Voltage | | | ±37 | ±200 ±500 | μV |
| TCV_{OS} | Input Offset Voltage Temperature Drift | (Note 7) | | ±1 | ±5 | $\mu\text{V}/^\circ\text{C}$ |
| I_B | Input Bias Current | (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 85^\circ\text{C}$ | | ±0.2 | 1 ±50 | pA |
| | | (Note 7, Note 8) $-40^\circ\text{C} \leq T_A \leq 125^\circ\text{C}$ | | ±0.2 | 1 ±400 | |
| I_{OS} | Input Offset Current | | | 40 | | fA |
| CMRR | Common Mode Rejection Ratio | $-5\text{V} \leq V_{\text{CM}} \leq 5\text{V}$ | 92 88 | 138 | | dB |
| PSRR | Power Supply Rejection Ratio | $2.7\text{V} \leq V^+ \leq 12\text{V}$, $V_O = 0\text{V}$ | 86 82 | 98 | | dB |
| CMVR | Common Mode Voltage Range | CMRR ≥ 80 dB | -5.2 | | 5.2 | V |
| | | CMRR ≥ 78 dB | -5.2 | | 5.2 | |
| A_{VOL} | Open Loop Voltage Gain | $R_L = 2 \text{ k}\Omega$ $V_O = -4.7\text{V}$ to 4.7V | 100 98 | 121 | | dB |
| | | $R_L = 10 \text{ k}\Omega$ $V_O = -4.8\text{V}$ to 4.8V | 100 98 | 134 | | |
| V_{OUT} | Output Voltage Swing High | $R_L = 2 \text{ k}\Omega$ to 0V | | 90 | 150 170 | mV from V^+ |
| | | $R_L = 10 \text{ k}\Omega$ to 0V | | 40 | 80 100 | |
| | Output Voltage Swing Low | $R_L = 2 \text{ k}\Omega$ to 0V | | 90 | 130 150 | mV from V^- |
| | | $R_L = 10 \text{ k}\Omega$ to 0V | | 40 | 50 60 | |
| I_{OUT} | Output Current (Note 3, Note 9) | Sourcing $V_O = 0\text{V}$ $V_{\text{IN}} = 100 \text{ mV}$ | 50 35 | 86 | | mA |
| | | Sinking $V_O = 0\text{V}$ $V_{\text{IN}} = -100 \text{ mV}$ | 50 35 | 84 | | |
| I_S | Supply Current | | | 0.790 | 1.1 1.3 | mA |
| SR | Slew Rate (Note 10) | $A_V = +1$, $V_O = 9 V_{\text{PP}}$ 10% to 90% | | 1.1 | | $\text{V}/\mu\text{s}$ |
| GBW | Gain Bandwidth | | | 2.5 | | MHz |
| THD+N | Total Harmonic Distortion + Noise | $f = 1 \text{ kHz}$, $A_V = 1$, $R_L = 10 \text{ k}\Omega$ | | 0.02 | | % |
| e_n | Input Referred Voltage Noise Density | $f = 1 \text{ kHz}$ | | 9 | | $\text{nV}/\sqrt{\text{Hz}}$ |
| i_n | Input Referred Current Noise Density | $f = 100 \text{ kHz}$ | | 1 | | $\text{fA}/\sqrt{\text{Hz}}$ |

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics Tables.

Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC).

Note 3: The maximum power dissipation is a function of $T_{J(MAX)}$, θ_{JA} . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / \theta_{JA}$. All numbers apply for packages soldered directly onto a PC Board.

Note 4: Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that $T_J = T_A$. No guarantee of parametric performance is indicated in the electrical tables under conditions of internal self-heating where $T_J > T_A$.

Note 5: Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

Note 6: Limits are 100% production tested at 25°C. Limits over the operating temperature range are guaranteed through correlations using the Statistical Quality Control (SQC) method.

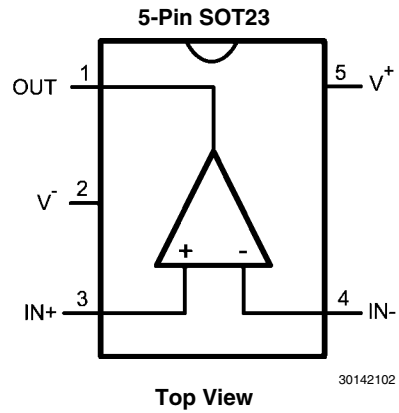
Note 7: This parameter is guaranteed by design and/or characterization and is not tested in production.

Note 8: Positive current corresponds to current flowing into the device.

Note 9: The short circuit test is a momentary test.

Note 10: The number specified is the slower of positive and negative slew rates.

Connection Diagram

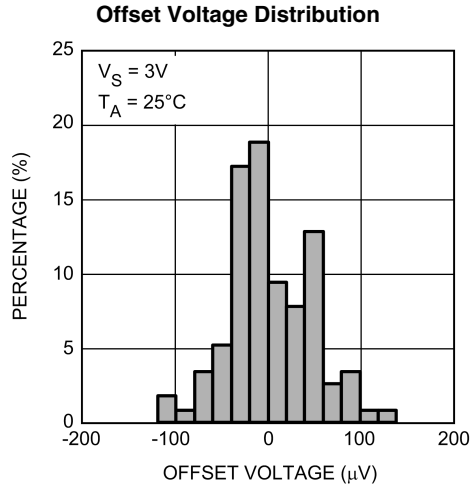


Ordering Information

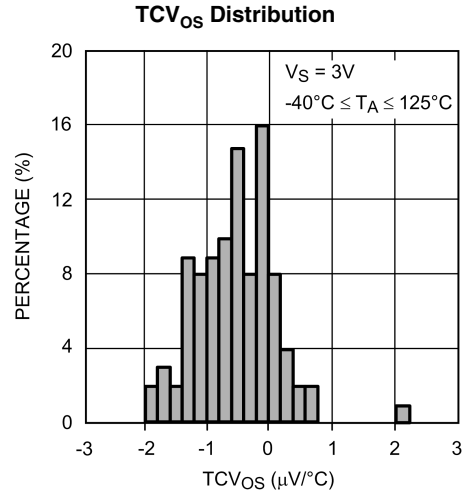
| Package | Part Number | Package Marking | Transport Media | NSC Drawing |
|-------------|-------------|-----------------|--------------------------|-------------|
| 5-Pin SOT23 | SM72501MFE | S501 | 250 Units Tape and Reel | MF05A |
| 5-Pin SOT23 | SM72501MF | S501 | 1000 Units Tape and Reel | MF05A |
| 5-Pin SOT23 | SM72501MFX | S501 | 3000 Units Tape and Reel | MF05A |

Typical Performance Characteristics

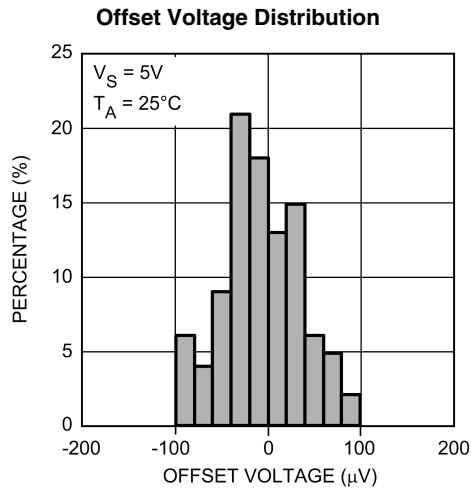
Unless otherwise noted: $T_A = 25^\circ\text{C}$, $V_{CM} = V_S/2$, $R_L > 10\text{ k}\Omega$.



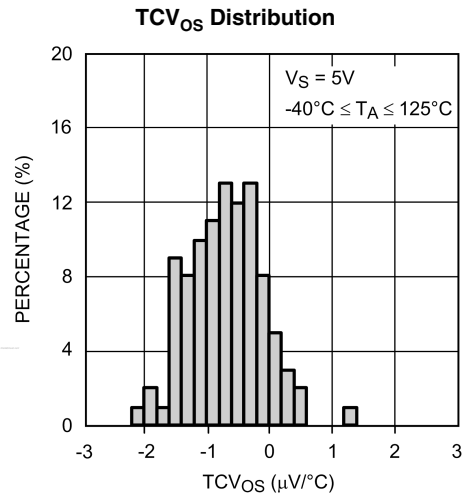
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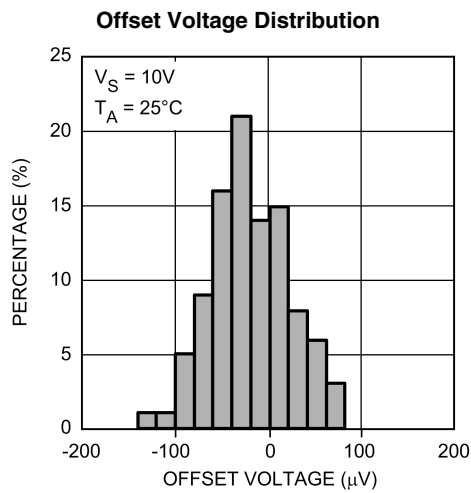
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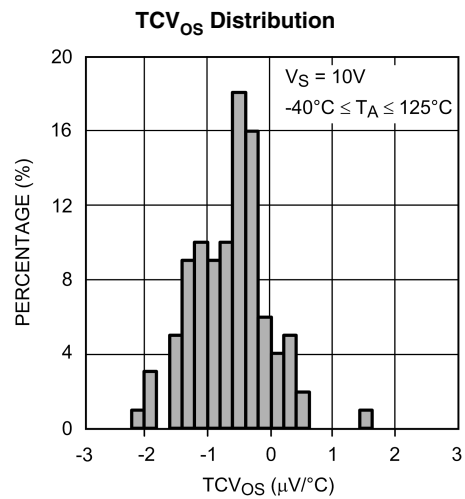
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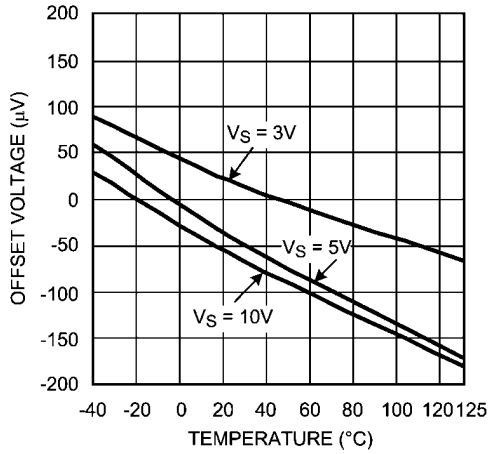


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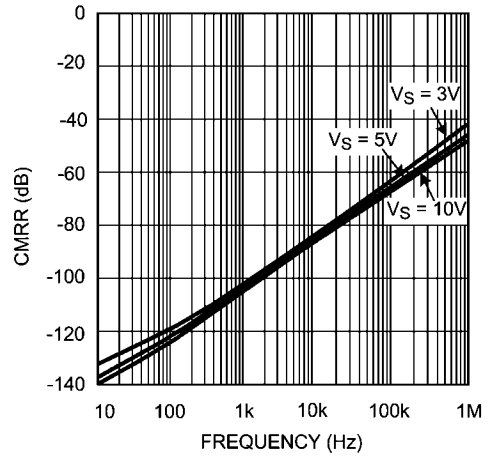
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Offset Voltage vs. Temperature



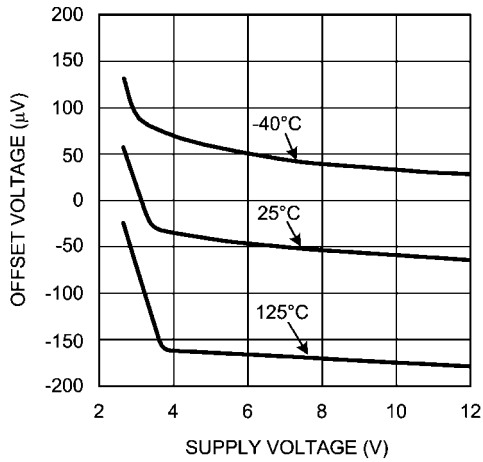
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CMRR vs. Frequency



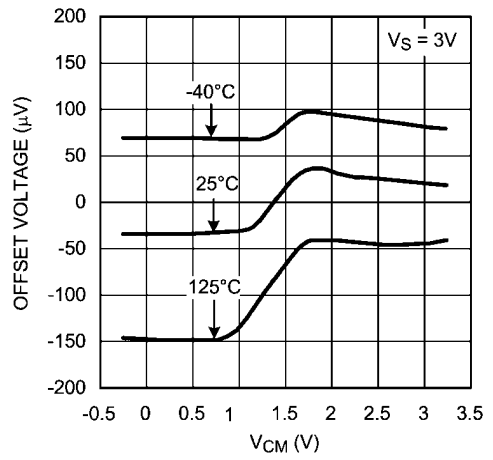
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Offset Voltage vs. Supply Voltage



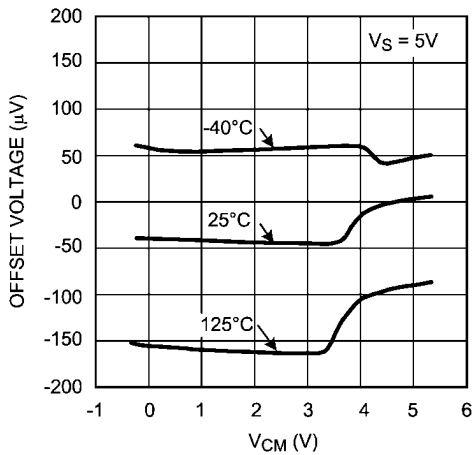
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Offset Voltage vs. V_{CM}



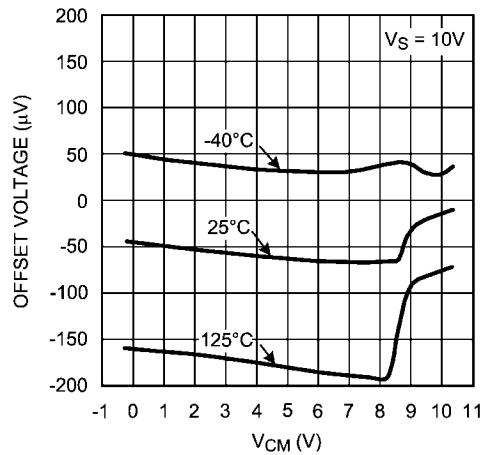
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Offset Voltage vs. V_{CM}

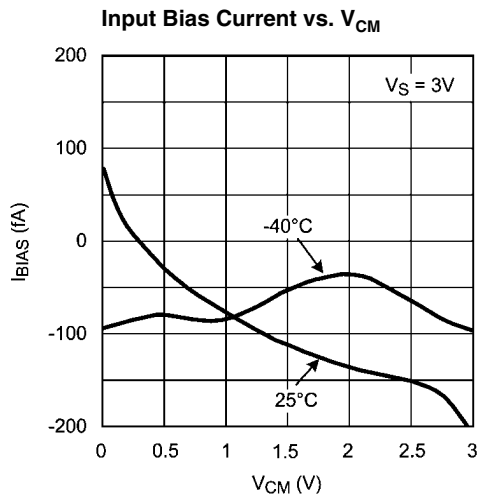


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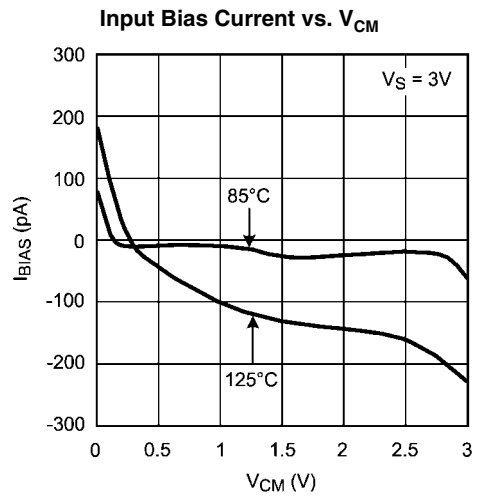
Offset Voltage vs. V_{CM}



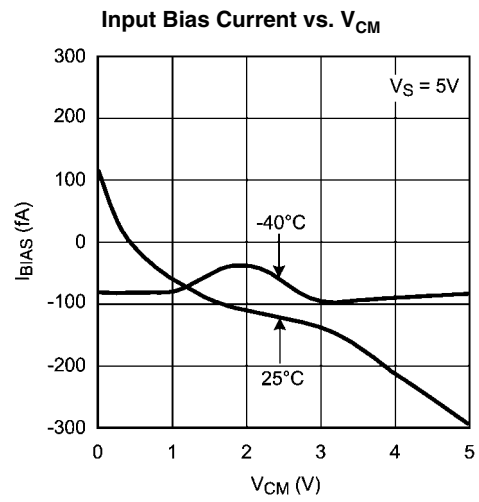
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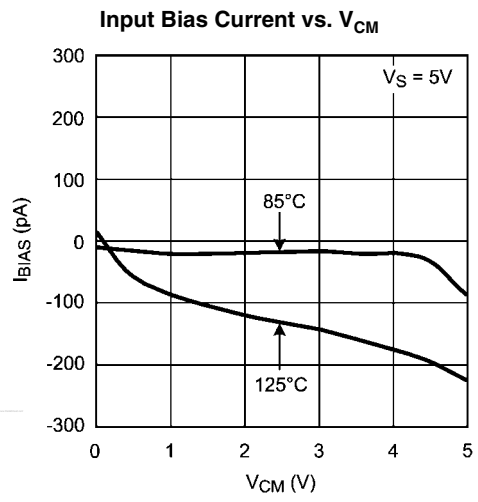
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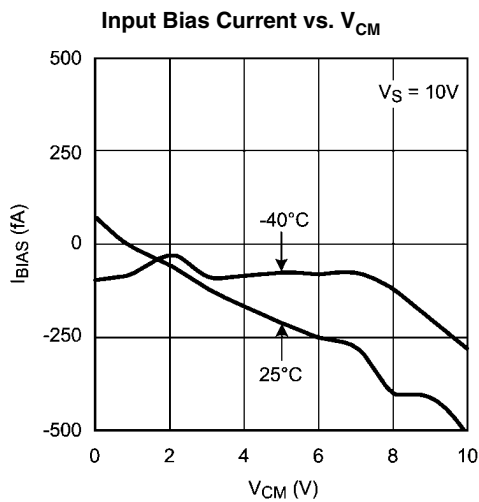
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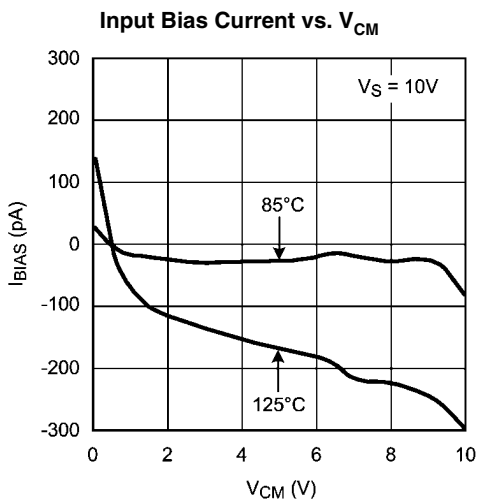
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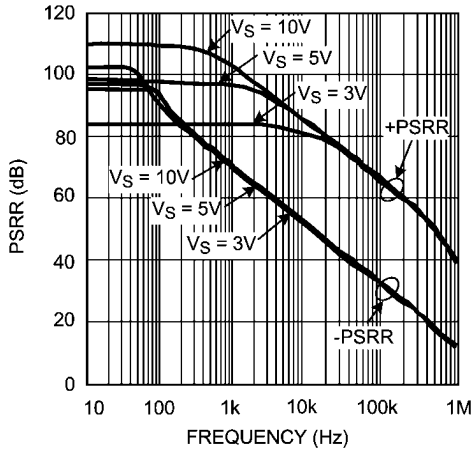


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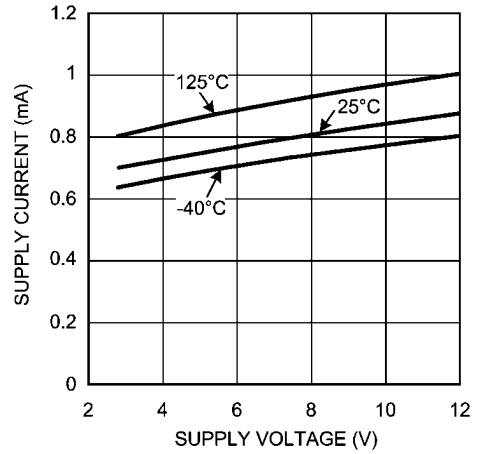
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PSRR vs. Frequency



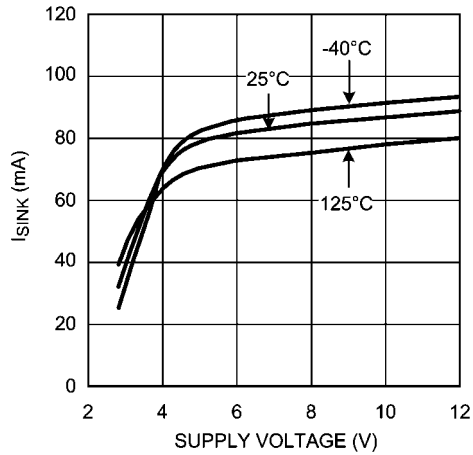
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Supply Current vs. Supply Voltage (Per Channel)



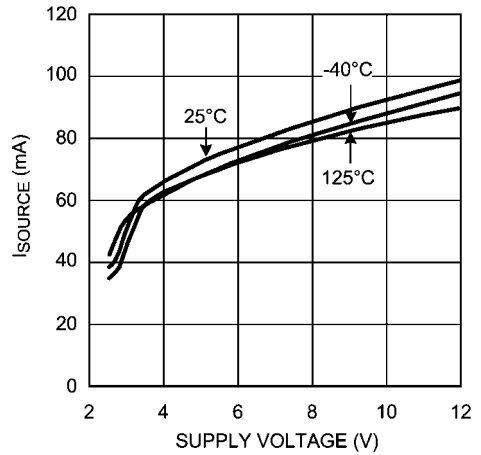
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Sinking Current vs. Supply Voltage



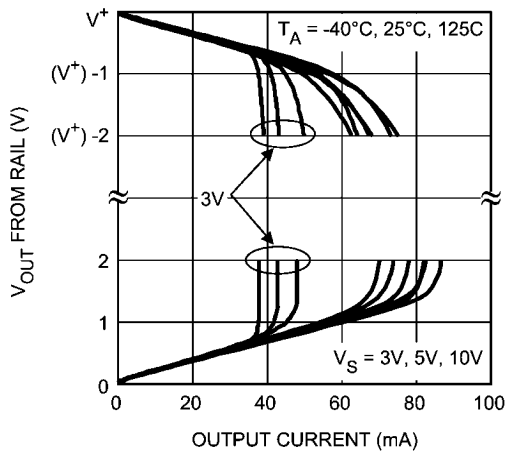
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Sourcing Current vs. Supply Voltage



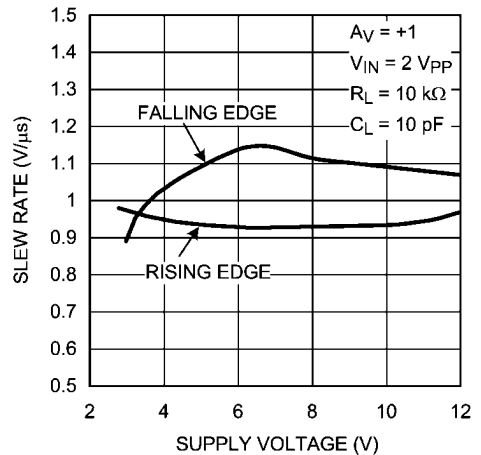
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Output Voltage vs. Output Current



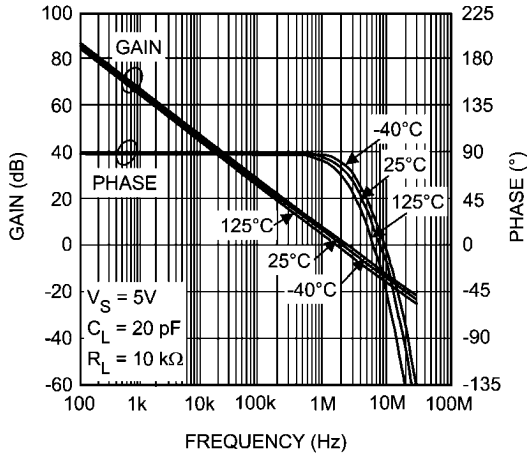
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Slew Rate vs. Supply Voltage



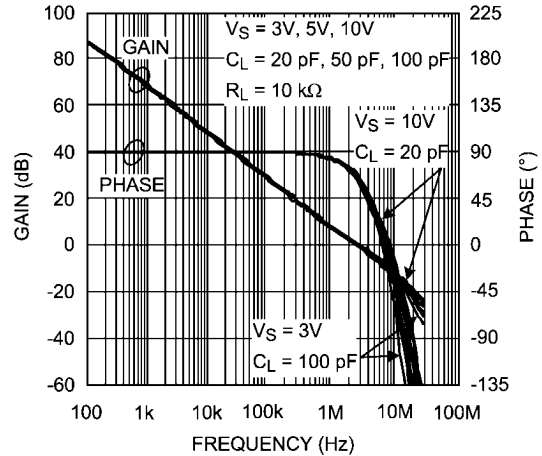
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Open Loop Frequency Response



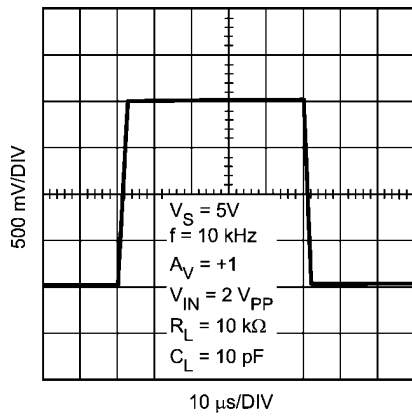
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Open Loop Frequency Response



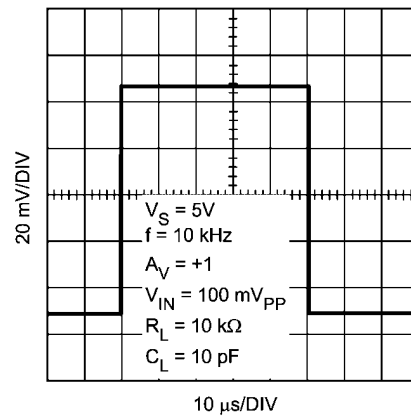
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Large Signal Step Response



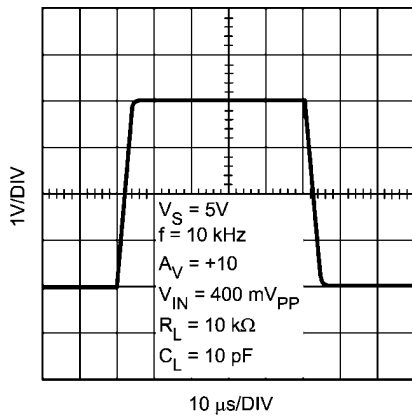
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Small Signal Step Response



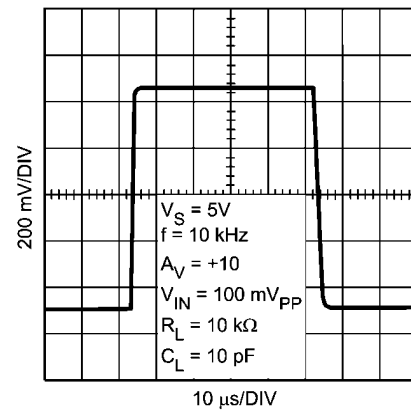
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Large Signal Step Response



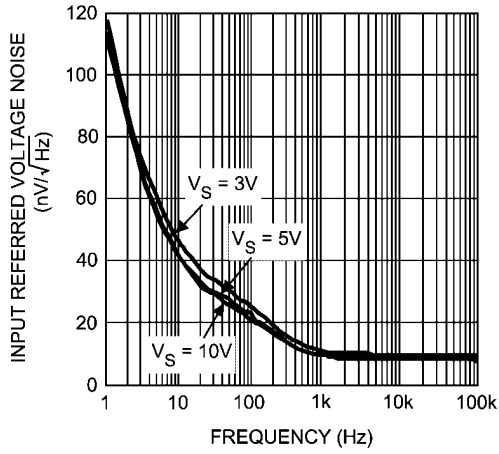
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Small Signal Step Response



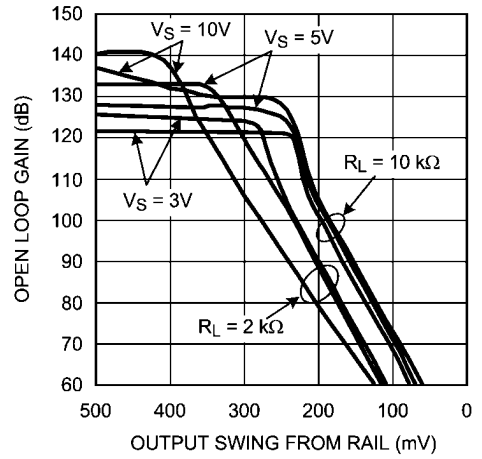
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Input Voltage Noise vs. Frequency



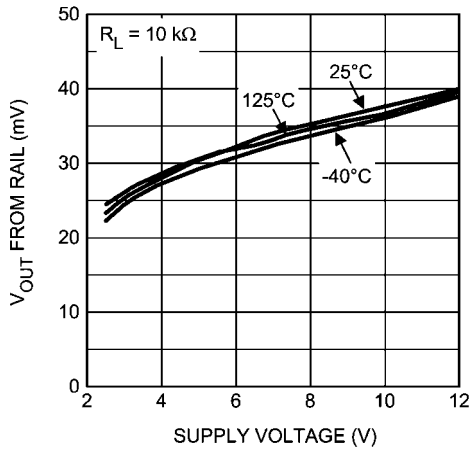
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Open Loop Gain vs. Output Voltage Swing



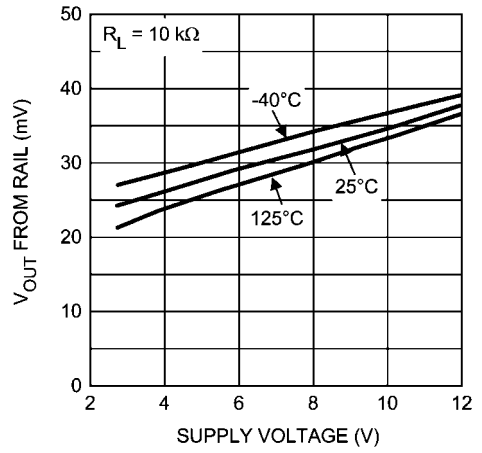
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Output Swing High vs. Supply Voltage



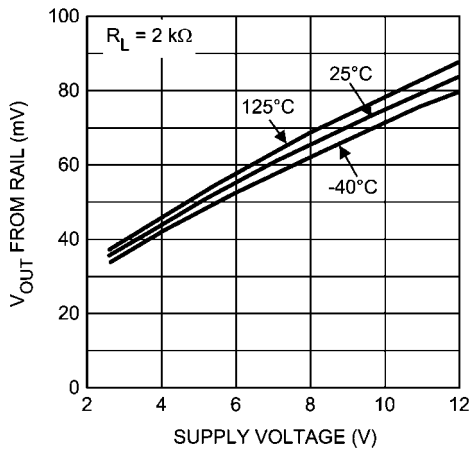
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Output Swing Low vs. Supply Voltage



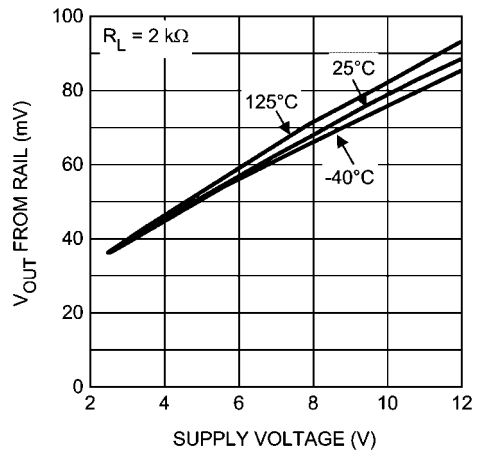
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Output Swing High vs. Supply Voltage

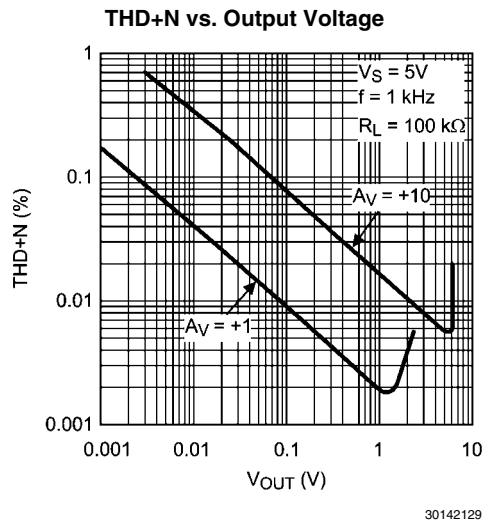
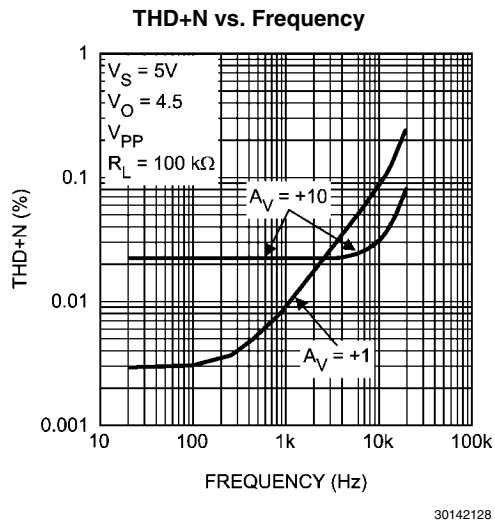


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Output Swing Low vs. Supply Voltage



30142134



Application Information

SM72501

The SM72501 is a low offset voltage, rail-to-rail input and output precision amplifier with a CMOS input stage and wide supply voltage range of 2.7V to 12V. The SM72501 has a very low input bias current of only ± 200 fA at room temperature.

The wide supply voltage range of 2.7V to 12V over the extensive temperature range of -40°C to 125°C makes the SM72501 an excellent choice for low voltage precision applications with extensive temperature requirements.

The SM72501 has only ± 37 μV of typical input referred offset voltage and this offset is guaranteed to be less than ± 500 μV over temperature. This minimal offset voltage allows more accurate signal detection and amplification in precision applications.

The low input bias current of only ± 200 fA along with the low input referred voltage noise of 9 nV/ $\sqrt{\text{Hz}}$ gives the SM72501 superiority for use in sensor applications. Lower levels of noise from the SM72501 means better signal fidelity and a higher signal-to-noise ratio.

National Semiconductor is heavily committed to precision amplifiers and the market segment they serve. Technical support and extensive characterization data is available for sensitive applications or applications with a constrained error budget.

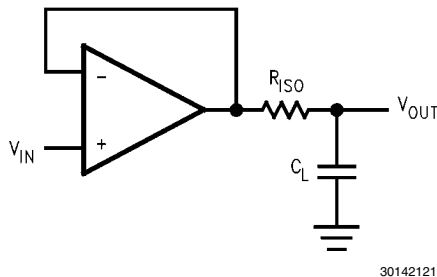
The SM72501 is offered in the space saving 5-Pin SOT23. This small package is an ideal solution for area constrained PC boards and portable electronics.

CAPACITIVE LOAD

The SM72501 can be connected as a non-inverting unity gain follower. This configuration is the most sensitive to capacitive loading.

The combination of a capacitive load placed on the output of an amplifier along with the amplifier's output impedance creates a phase lag which in turn reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response will be either underdamped or it will oscillate.

In order to drive heavier capacitive loads, an isolation resistor, R_{ISO} , in [Figure 1](#) should be used. By using this isolation resistor, the capacitive load is isolated from the amplifier's output, and hence, the pole caused by C_L is no longer in the feedback loop. The larger the value of R_{ISO} , the more stable the output voltage will be. If values of R_{ISO} are sufficiently large, the feedback loop will be stable, independent of the value of C_L . However, larger values of R_{ISO} result in reduced output swing and reduced output current drive.



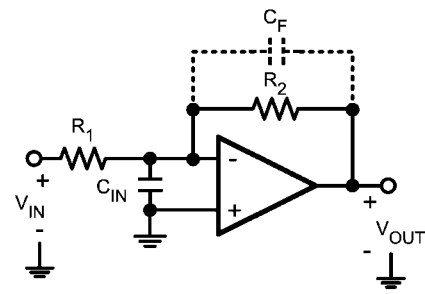
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FIGURE 1. Isolating Capacitive Load

INPUT CAPACITANCE

CMOS input stages inherently have low input bias current and higher input referred voltage noise. The SM72501 enhances this performance by having the low input bias current of only ± 200 fA, as well as, a very low input referred voltage noise of 9 nV/ $\sqrt{\text{Hz}}$. In order to achieve this a larger input stage has been used. This larger input stage increases the input capacitance of the SM72501. The typical value of this input capacitance, C_{IN} , for the SM72501 is 25 pF. The input capacitance will interact with other impedances such as gain and feedback resistors, which are seen on the inputs of the amplifier, to form a pole. This pole will have little or no effect on the output of the amplifier at low frequencies and DC conditions, but will play a bigger role as the frequency increases. At higher frequencies, the presence of this pole will decrease phase margin and will also cause gain peaking. In order to compensate for the input capacitance, care must be taken in choosing the feedback resistors. In addition to being selective in picking values for the feedback resistor, a capacitor can be added to the feedback path to increase stability.

The DC gain of the circuit shown in [Figure 2](#) is simply $-R_2/R_1$.



$$A_V = -\frac{V_{\text{OUT}}}{V_{\text{IN}}} = -\frac{R_2}{R_1}$$

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FIGURE 2. Compensating for Input Capacitance

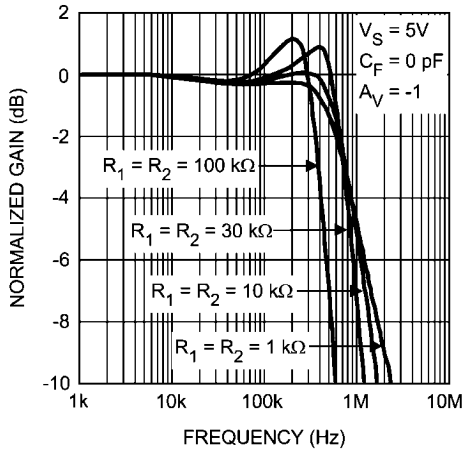
For the time being, ignore C_F . The AC gain of the circuit in [Figure 2](#) can be calculated as follows:

$$\frac{V_{\text{OUT}}}{V_{\text{IN}}}(s) = \frac{-R_2/R_1}{1 + \frac{s}{\left(\frac{A_0 R_1}{R_1 + R_2}\right)} + \frac{s^2}{\left(\frac{A_0}{C_{\text{IN}} R_2}\right)}}$$

This equation is rearranged to find the location of the two poles:

$$P_{1,2} = \frac{-1}{2C_{\text{IN}}} \left[\frac{1}{R_1} + \frac{1}{R_2} \pm \sqrt{\left(\frac{1}{R_1} + \frac{1}{R_2}\right)^2 - \frac{4A_0 C_{\text{IN}}}{R_2}} \right] \quad (1)$$

As shown in [Equation 1](#), as values of R_1 and R_2 are increased, the magnitude of the poles is reduced, which in turn decreases the bandwidth of the amplifier. Whenever possible, it is best to choose smaller feedback resistors. [Figure 3](#) shows the effect of the feedback resistor on the bandwidth of the SM72501.



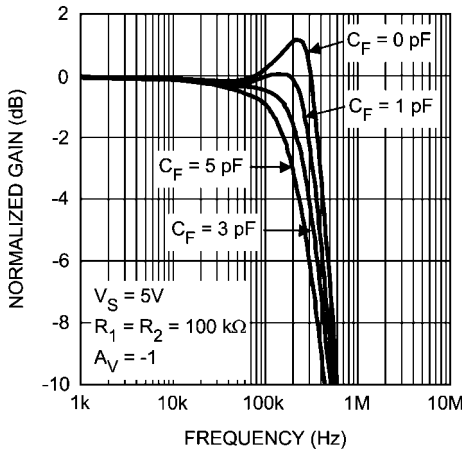
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FIGURE 3. Closed Loop Gain vs. Frequency

Equation 1 has two poles. In most cases, it is the presence of pairs of poles that causes gain peaking. In order to eliminate this effect, the poles should be placed in Butterworth position, since poles in Butterworth position do not cause gain peaking. To achieve a Butterworth pair, the quantity under the square root in Equation 1 should be set to equal -1 . Using this fact and the relation between R_1 and R_2 , $R_2 = -A_V R_1$, the optimum value for R_1 can be found. This is shown in Equation 2. If R_1 is chosen to be larger than this optimum value, gain peaking will occur.

$$R_1 < \frac{(1 - A_V)^2}{2A_0 A_V C_{IN}} \quad (2)$$

In Figure 2, C_F is added to compensate for input capacitance and to increase stability. Additionally, C_F reduces or eliminates the gain peaking that can be caused by having a larger feedback resistor. Figure 4 shows how C_F reduces gain peaking.

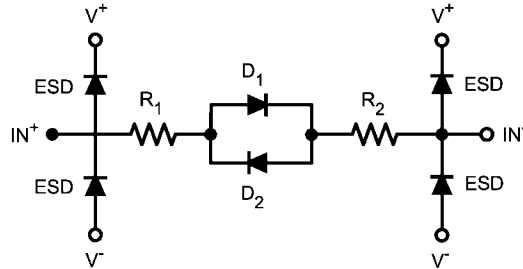


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FIGURE 4. Closed Loop Gain vs. Frequency with Compensation

DIODES BETWEEN THE INPUTS

The SM72501 has a set of anti-parallel diodes between the input pins, as shown in Figure 5. These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins. A differential signal larger than one diode voltage drop might damage the diodes. The differential signal between the inputs needs to be limited to ± 300 mV or the input current needs to be limited to ± 10 mA.

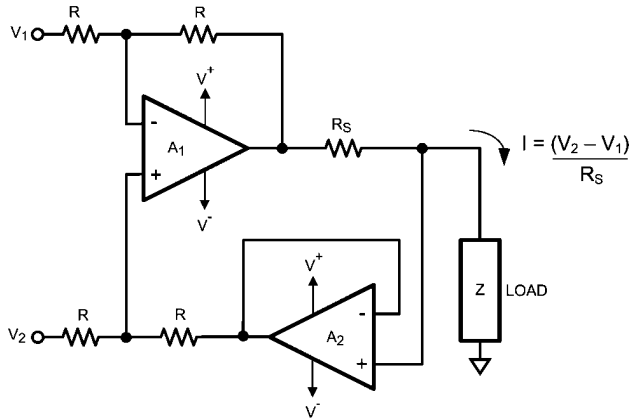


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FIGURE 5. Input of SM72501

PRECISION CURRENT SOURCE

The SM72501 can be used as a precision current source in many different applications. *Figure 6* shows a typical precision current source. This circuit implements a precision voltage controlled current source. Amplifier A1 is a differential amplifier that uses the voltage drop across R_S as the feedback signal. Amplifier A2 is a buffer that eliminates the error current from the load side of the R_S resistor that would flow in the feedback resistor if it were connected to the load side of the R_S resistor. In general, the circuit is stable as long as the closed loop bandwidth of amplifier A2 is greater than the closed loop bandwidth of amplifier A1. Note that if A1 and A2 are the same type of amplifiers, then the feedback around A1 will reduce its bandwidth compared to A2.



30142105

FIGURE 6. Precision Current Source

The equation for output current can be derived as follows:

$$\frac{V_2 R}{R + R} + \frac{(V_0 - I R_S) R}{R + R} = \frac{V_1 R}{R + R} + \frac{V_0 R}{R + R}$$

Solving for the current I results in the following equation:

$$I = \frac{V_2 - V_1}{R_S}$$

LOW INPUT VOLTAGE NOISE

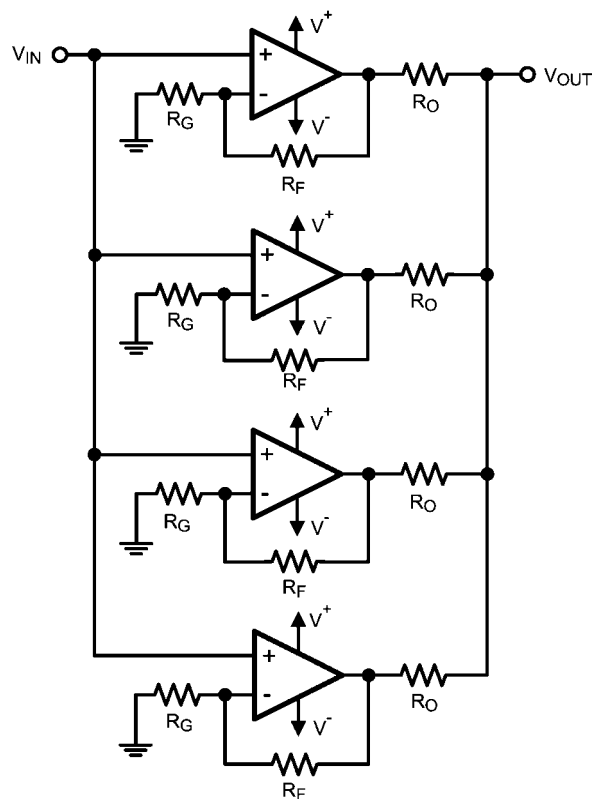
The SM72501 has a very low input voltage noise of 9 nV/√Hz. This input voltage noise can be further reduced by placing N amplifiers in parallel as shown in *Figure 7*. The total voltage noise on the output of this circuit is divided by the square root of the number of amplifiers used in this parallel

combination. This is because each individual amplifier acts as an independent noise source, and the average noise of independent sources is the quadrature sum of the independent sources divided by the number of sources. For N identical amplifiers, this means:

$$\begin{aligned} \text{REDUCED INPUT VOLTAGE NOISE} &= \frac{1}{N} \sqrt{e_{n1}^2 + e_{n2}^2 + \dots + e_{nN}^2} \\ &= \frac{1}{N} \sqrt{N e_n^2} = \frac{\sqrt{N}}{N} e_n \\ &= \frac{1}{\sqrt{N}} e_n \end{aligned}$$

Figure 7 shows a schematic of this input voltage noise reduction circuit. Typical resistor values are:

$R_G = 10\Omega$, $R_F = 1\text{ k}\Omega$, and $R_O = 1\text{ k}\Omega$.



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FIGURE 7. Noise Reduction Circuit

TOTAL NOISE CONTRIBUTION

The SM72501 has very low input bias current, very low input current noise, and very low input voltage noise. As a result, these amplifiers are ideal choices for circuits with high impedance sensor applications.

Figure 8 shows the typical input noise of the SM72501 as a function of source resistance where:

e_n denotes the input referred voltage noise

e_i is the voltage drop across source resistance due to input referred current noise or $e_i = R_S \cdot i_n$

e_t shows the thermal noise of the source resistance

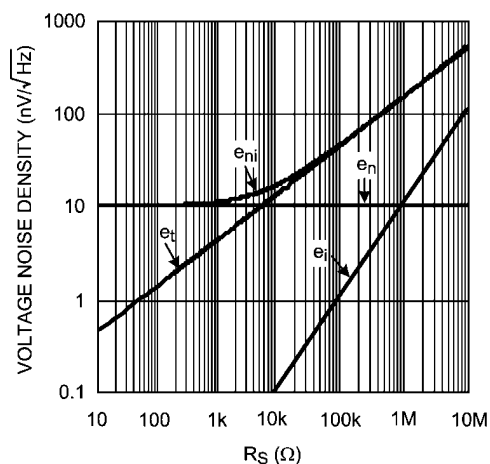
e_{ni} shows the total noise on the input.

Where:

$$e_{ni} = \sqrt{e_n^2 + e_i^2 + e_t^2}$$

The input current noise of the SM72501 is so low that it will not become the dominant factor in the total noise unless source resistance exceeds 300 M Ω , which is an unrealistically high value.

As is evident in Figure 8, at lower R_S values, total noise is dominated by the amplifier's input voltage noise. Once R_S is larger than a few kilo-Ohms, then the dominant noise factor becomes the thermal noise of R_S . As mentioned before, the current noise will not be the dominant noise factor for any practical application.



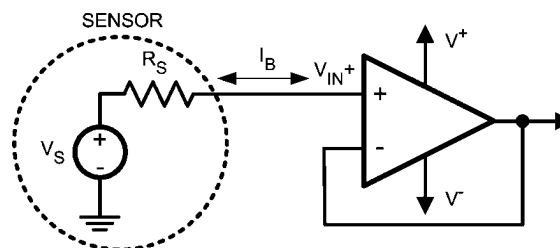
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FIGURE 8. Total Input Noise

HIGH IMPEDANCE SENSOR INTERFACE

Many sensors have high source impedances that may range up to 10 M Ω . The output signal of sensors often needs to be amplified or otherwise conditioned by means of an amplifier. The input bias current of this amplifier can load the sensor's output and cause a voltage drop across the source resistance as shown in Figure 9, where $V_{IN^+} = V_S - I_{BIAS} \cdot R_S$.

The last term, $I_{BIAS} \cdot R_S$, shows the voltage drop across R_S . To prevent errors introduced to the system due to this voltage, an op amp with very low input bias current must be used with high impedance sensors. This is to keep the error contribution by $I_{BIAS} \cdot R_S$ less than the input voltage noise of the amplifier, so that it will not become the dominant noise factor.

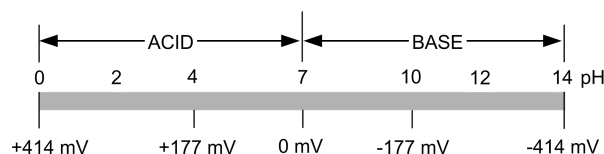


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FIGURE 9. Noise Due to I_{BIAS}

pH electrodes are very high impedance sensors. As their name indicates, they are used to measure the pH of a solution. They usually do this by generating an output voltage which is proportional to the pH of the solution. pH electrodes are calibrated so that they have zero output for a neutral solution, pH = 7, and positive and negative voltages for acidic or alkaline solutions. This means that the output of a pH electrode is bipolar system and has to be level shifted to be used in a single supply system. The rate of change of this voltage is usually shown in mV/pH and is different for different pH sensors. Temperature is also an important factor in a pH electrode reading. The output voltage of the sensor will change with temperature.

Figure 10 shows a typical output voltage spectrum of a pH electrode. Note that the exact values of output voltage will be different for different sensors. In this example, the pH electrode has an output voltage of 59.15 mV/pH at 25°C.



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FIGURE 10. Output Voltage of a pH Electrode

The temperature dependence of a typical pH electrode is shown in Figure 11. As is evident, the output voltage changes with changes in temperature.

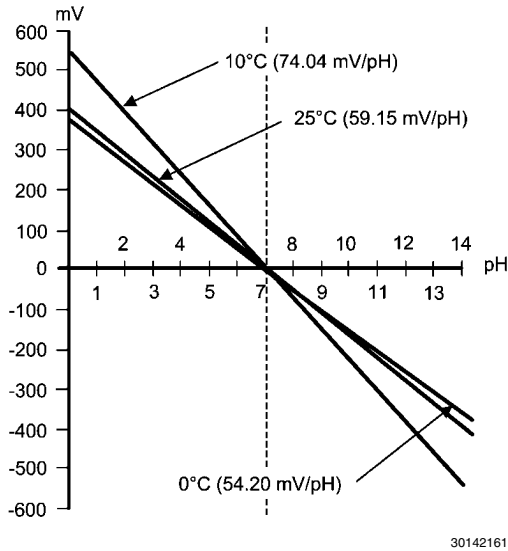


FIGURE 11. Temperature Dependence of a pH Electrode

The schematic shown in Figure 12 is a typical circuit which can be used for pH measurement. The LM35 is a precision integrated circuit temperature sensor. This sensor is differentiated from similar products because it has an output voltage linearly proportional to Celcius measurement, without the need to convert the temperature to Kelvin. The LM35 is used to measure the temperature of the solution and feeds this reading to the Analog to Digital Converter, ADC. This infor-

mation is used by the ADC to calculate the temperature effects on the pH readings. The LM35 needs to have a resistor, R_T in Figure 12, to $-V^+$ in order to be able to read temperatures below 0°C. R_T is not needed if temperatures are not expected to go below zero.

The output of pH electrodes is usually large enough that it does not require much amplification; however, due to the very high impedance, the output of a pH electrode needs to be buffered before it can go to an ADC. Since most ADCs are operated on single supply, the output of the pH electrode also needs to be level shifted. Amplifier A1 buffers the output of the pH electrode with a moderate gain of +2, while A2 provides the level shifting. V_{OUT} at the output of A2 is given by: $V_{OUT} = -2V_{pH} + 1.024V$.

The LM4140A is a precision, low noise, voltage reference used to provide the level shift needed. The ADC used in this application is the ADC12032 which is a 12-bit, 2 channel converter with multiplexers on the inputs and a serial output. The 12-bit ADC enables users to measure pH with an accuracy of 0.003 of a pH unit. Adequate power supply bypassing and grounding is extremely important for ADCs. Recommended bypass capacitors are shown in Figure 12. It is common to share power supplies between different components in a circuit. To minimize the effects of power supply ripples caused by other components, the op amps need to have bypass capacitors on the supply pins. Using the same value capacitors as those used with the ADC are ideal. The combination of these three values of capacitors ensures that AC noise present on the power supply line is grounded and does not interfere with the amplifiers' signal.

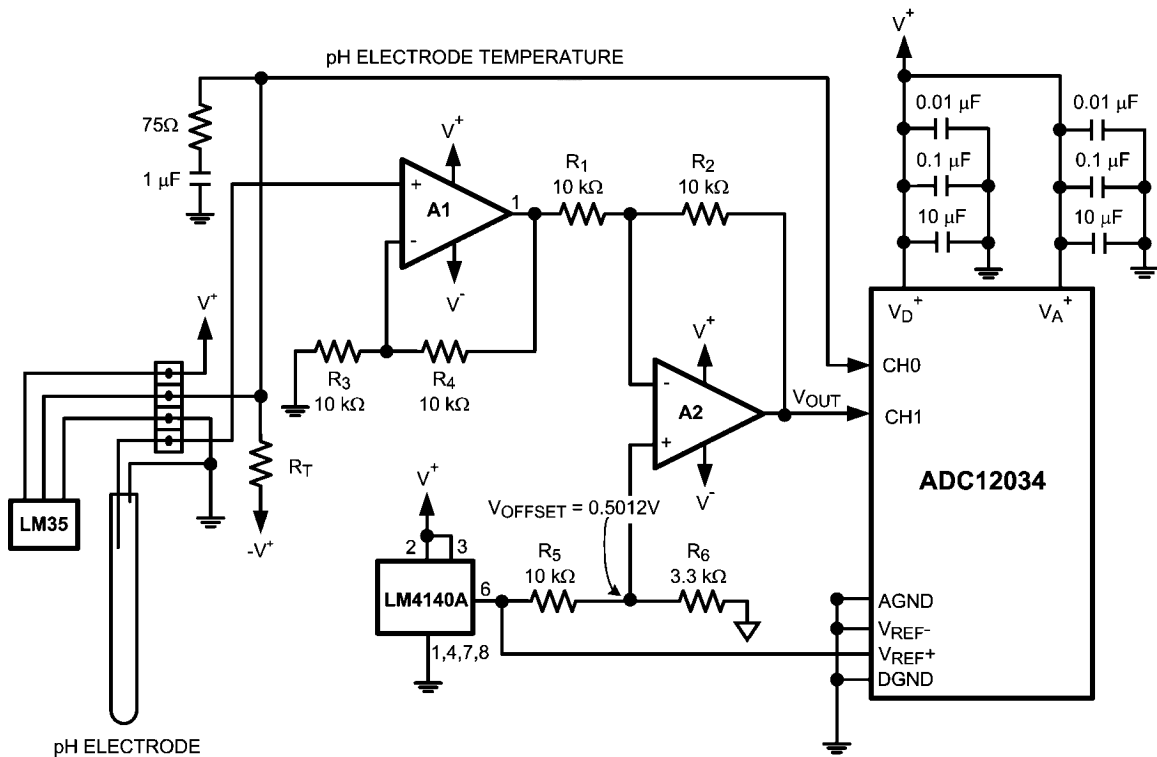
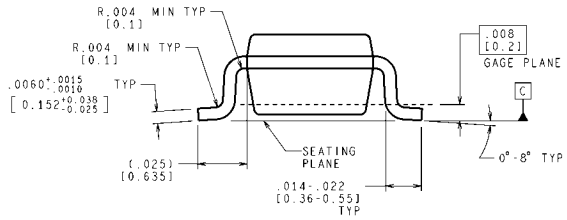
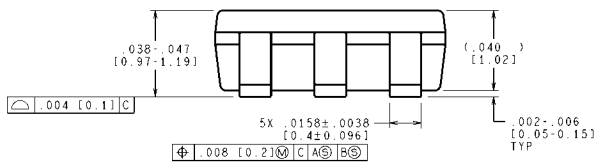
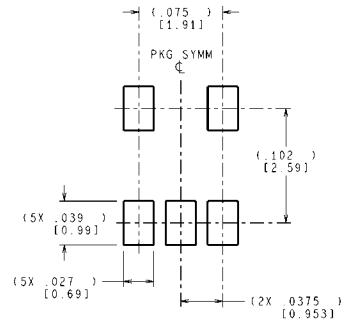
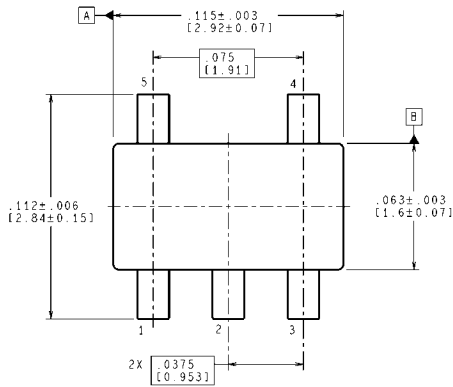


FIGURE 12. pH Measurement Circuit

Physical Dimensions inches (millimeters) unless otherwise noted



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5-Pin SOT23
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