



**Preliminary**

**SPCA533A**  
**User Guide**

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**DIGITAL STILL CAMERA CONTROLLER**

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*Scatch*<sup>TM</sup>

**Sunplus Camera Solution**

**SPCA533A**

**User Guide**

Version 0.2.0

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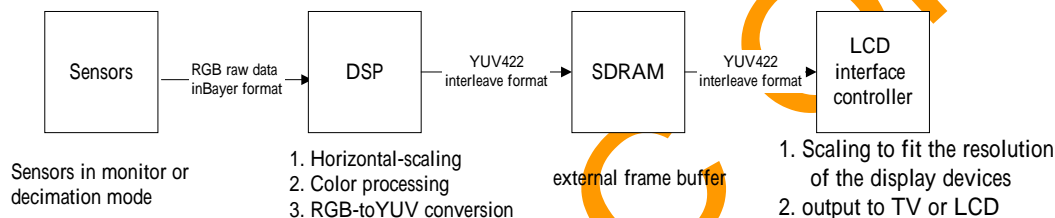
## 1. Operational Descriptions

### 1.1 Operation modes

The main operation modes of the SPCA533A are *preview*, *capture*, *videoclip* and *playback* modes. These modes are mutually exclusive. The SPCA533A can only operated in one of these modes at a time. There are many tasks that can be excuted concurrently with these modes. For example, data transfer between the PC and the camera can take place while the camera is in any of these operation modes. Also, data transfer between the camera and the storage media can also be performed while the SPCA533A is operated in any operation modes. These concurrence operations are useful when the application need to put the time-consuming tasks to the background execution.

#### 1.1.1 Preview mode

In the preview mode, the SPCA533A receives raw image data from the sensor. It processes the data in real time with the CDSP (Color DSP) and stores the data in the frame buffer of the SDRAM. Then, the data is read from the SDRAM and sent to the display device. The SPCA533A supports TFT LCD panels, STN LCD panels, digital TV output and analog TV output. The following diagram demonstrates the data flow in the preview mode.



The sensor's fame rate are normally adjusted to 30 fps in the preview mode. For the CCD sensors, the user need to adjust the parameters in the built-in timing generator to make the SPCA533A drive out 30 fps timing. For the CMOS sensors, the frame rate may be dominated by the SPCA533A or by the sensors, depending on the operation mode of the CMOS sensors. If the CMOS sensors is operated in the master mode, the SPCA533A programs the internal registers of the sensors to control the timing. On the other hand, if CMOS sensors is operated is operated in the slave mode, the users need to adjust the parameters in the CMOS interface controller of the SPCA533A to control the frame rate. Mega-pixel sensors usually supports monitor mode (CCD) or decimation mode (CMOS) to allow the pixel data to be read at 30 fps frame rate.

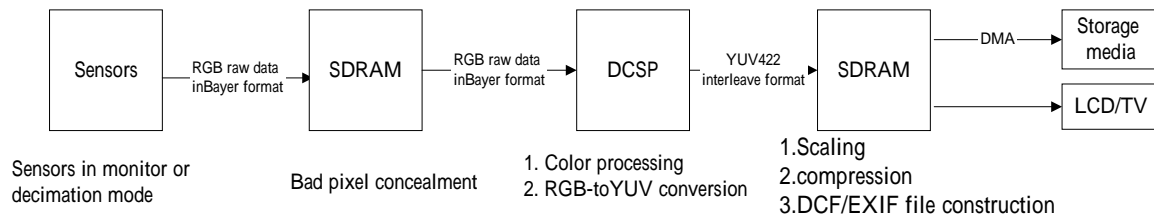
The SPCA533A provides many programmable parameters in the CDSP to achieve the best image quality. The image is horizontally scaled-down by the CDSP, too. The horizontal scaling-down function in the DSP not only reduces the bandwidth requirement of the SDRAM but also maintain the appropriate aspect ratio of the image in a CCD system. For example, if the a CCD sensor vertically subsampled the image by 4, then the CDSP will need to scale down the image horizontally by 4 to maintain the correct aspect ratio. After color processing, the CDSP convert the image data from the RGB domain to the YUV domain. The AE (auto-exposure) and AWB (auto-white balance firmware) algorithm is executed at the background in the preview mode. The CDSP provides statistics on the image data for the AE/AWB algorithm's reference.

The data stored in the SDRAM is in YUV422 format. The SDRAM controller maintains two frame buffers to convert the frame rate if the sensor's frame rate is different from the frame rate of the display device.

To fit a wide range of the resolutions of the display devices, The LCD/TV interface controller has built-in scaling function. The scaling ratio of the LCD/TV scaling function can be adjusted independently in the vertical direction and the horizontal direction. However, it is important to maintain the appropriate aspect ratio of the original image. For TV output, the PAL frame rate fixed at 25 fps, the NTSC is 30fps. The frame rates of the LCD panels are usually fiixed by the panel makers.

#### 1.1.2 Capture mode

The capture mode allows the user to capture image output from the sensors. Depending on the setting of the camera, the SPCA533A is able to capture a single image, multiple images and video. The simplest flow is the single image capture. The following diagram shows the data flow of snapping a single image.



In the capture mode, the sensor should be operated in the full resolution mode. This requires adjusting the parameters in the timing generator in the CCD system. In the CMOS system, the sensor's control registers must be adjusted accordingly.

The RGB raw data (in Bayer pattern format) is stored in the SDRAM frame buffer without any image processing. Only optical black value is measured when the data is written into the SDRAM. For interlace CCD sensors, the data sequence of the image data is re-arranged at the same time when the raw data is written into the SDRAM. This is necessary because the this type of sensors separate the image into R-field and B-field. Also, 12 extra lines must be captured. This is necessary for the color processing in the SPCA533. For example, to get a 1280 by 960 final image, the users must capture a 1296 by 972 image first. Some sensors might not have enough number of valid pixels to meet the requirement of the SPCA533's color processing. An alternative approach is to mirror the image at the boundaries of the incoming data. Please reference to the CDSP section for details. The bad pixel concealment can be done in the SDRAM before color processing. The coordinates of the bad pixels are usually stored in the external ROM. The SPCA533A has built-in a hardwired engine for the bad pixel concealment to speed up this step.

After bad pixel concealment, the data is sent to the CDSP for color processing. In the color processing, the optical black value measure in the previous step is used. The color processing can be done many times with different parameter setting of the CDSP. This is useful when the flash light is applied to the image in which the preview mode AE/AWB window statistics cannot be used in the image processing.

After the image processing, the image is converted into YUV422 format and stored in the SDRAM again. The YUV422 image may be optionally scaled to the desired size. This step is necessary when the image is digitally zoomed or when a low resolution image is required. The scale function can be used to generate the thumbnail data, too. If a *quick-view of the snapped image* is requires, the YUV422 image should be scaled to fit the resolution of the display device before viewing. Image compression and file format (EXIF2.1 , DCF) construction are also done in the SDRAM. The SPCA533's JPEG engine process only the VLC stream. If the users intend to generate the DCF/EXIF file, the header must be generated and combined in the SDRAM. The files is then saved to the storage media via the SPCA533's built-in DMA controller. The file saing can be executed in the background, meaning the SPCA533A may switch back to the preview mode before the file is not completed written to the storage media.

### 1.1.3 Continuous shot

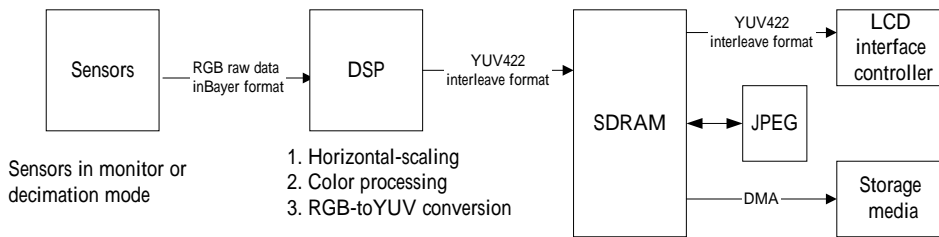
The continuous shot is also supported by the SPCA533. To minimize the time interval between frame, the multiple raw images are stored in the SDRAM before any processing. The size of the SDRAM determines the maximum number of the raw images in the continuous shot. The maximum frame rate in the continuous shot is the maximum frame rate of the sensors. After the required raw images are captured, they are process one by one. The precessing includes bad pixel concealment, all the color processing, scaling, compression, and file saving. It is exactly the same as snapping a single image.

In the CCD system, there is usually an exposure frame between data dumping frames. In the exposure frame, no data is read out from the sensos. This exposure frame can be used to perform CDSP color processing. In this case, the overall performace of the continuous shot will be improved. Also the images after CDSP color processing can be sent to the display device. The SPCA533's LCD/TV controller can only display the iamge in YUV422 format. RGB data can not be viewed.

There are many possibilities for the display in the continuous shot. The snapped image can be shown one by one on the LCD(or TV) after they are captured. Alternatively, the thumbnails can be shown together. This is up to the system application.

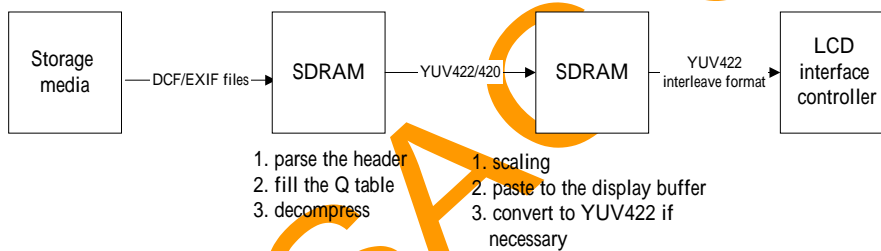
### 1.1.4 Video Clip

The video capture function operates similar to the preview mode, except that the data in the SDRAM is sent to the JPEG engine for compression and tehn stored in the storage media. The bandwidth requirement in the videoclip is the highest among all the operations of the SPCA533. To construct a video file of the AVI format, the firmware must maintain the header of the AVI. The following diagram shows the data flow of the videoclip.



### 1.1.5 Playback

In the playback mode, the SPCA533A fetches the compressed image in the storage media. The headers of the image files are parsed by the firmware. The JPEG quantization table must be programmed before decompression starts. The decompressed image is written into the display buffer for viewing. For mega-pixel sensors, the image normally needs to be scaled down before sending to the display devices because the resolution of the display device is smaller than the resolution of the images. The SPCA533A can display multiple images at the same time, too. When this feature is to be implemented, thumbnail images can be used to speedup the playback. Also the *copy&past* engine in the DRAM controller can help the firmware to construct the image in the display buffer. The LCD/TV interface controller can only display YUV422 image. If the original file is in YUV420 format, it must be converted to YUV422 format before viewing. The following diagram is the data flow in the playback mode.



Decompressing a full-size image may take some time, depending on the image resolution. The bottleneck is often located in the access speed of the storage media. Another approach in the playback mode is to decompress and display the thumbnail image first (resolution 160 by 120). The decompression of the full-size image can be done in the background while the users are viewing the thumbnails. Displaying the thumbnail image requires the LCD/TV interface to scale up the image. This can be done by adjusting the scale factors of the LCD/TV interface controller. Once the full size image is decompressed and scaled to the appropriate size, the firmware may switch the display buffer to display the image of better quality.

## 1.2 Global

### 1.2.1 Clocks

The SPCA533A connects to three external crystals. The first one (RTC crystal) is 32.768KHz, which is used in the built-in RTC module. This crystal could be spared when the RTC module is not used. The second crystal (TV crystal) is 27 MHz. This crystal is necessary when the SPCA533's built-in video CODEC is used. The third crystal (USB crystal) is to provide the main operating frequency of the SPCA533. The main operating frequency is generated by the main phase lock loop (MPLL). The input clock frequency of the MPLL could be 6MHz, 12MHz, or 24 MHz, depending on the IO-trap values. To reduce the counts of the external components, the SPCA533's MPLL can also take the 27MHz clock as its input source. This configuration is selected by a dedicated input pin. The following table lists the main clock settings.

Onextal Pin-B13(280), pin-134(216)	IO-trap{4:3}	USB crystal	TV crystal
0	0	6MHz	NC
0	1	12MHz	NC
0	2	24MHz	NC
0	3	48MHz	NC
1	Don't care	NC	27MHz

Note when 48MHz USB crystal is used, the main internal phase lock loop will be disabled to reference the external clock directly.

The clock supply to the CMOS sensors and to the internal timing generator (for the CCD systems) is a critical factor in the determination of the frame rate and exposure time. The SPCA533A can supply this clock by the main phase lock loop (MPLL). Alternatively, the SPCA533A can supply this clock by a dedicated phase lock loop (TGPLL). The clock source is chosen based on the pixel clock of the sensors. If the pixel clock is 12MHz, choose the MPLL and disable the TGPLL to conserve power. If the pixel clock of the sensors is 18MHz, choose the TGPLL to supply the clock. The TGPLL can also output other frequencies such as 21MHz, it is controlled by the input parameters of the TGPLL.

The output clock frequency of the TGPLL is  $3\text{MHz} \times (\text{TGPLLNS1} + 1) \times (\text{TGPLLNS2} + 1) / (\text{TGPLLS} + 1) \times 2$

TGPLLS	TGPLLNS1	TGPLLNS2	TGPLL
0	3	5	144 MHz
0	3	6	168 MHz

The 8XCK (8X pixel clock) is the input clock of the timing generator, which could be selected by the following setting.

TVDecMode (register 0X2018[0])	TGPllEn (register 0X2080[0])	8XCK
1	Don't care	27 MHz
0	0	96 MHz
0	1	TGPLL output

The 2XCK (2X pixel clock) is selected by the following setting.

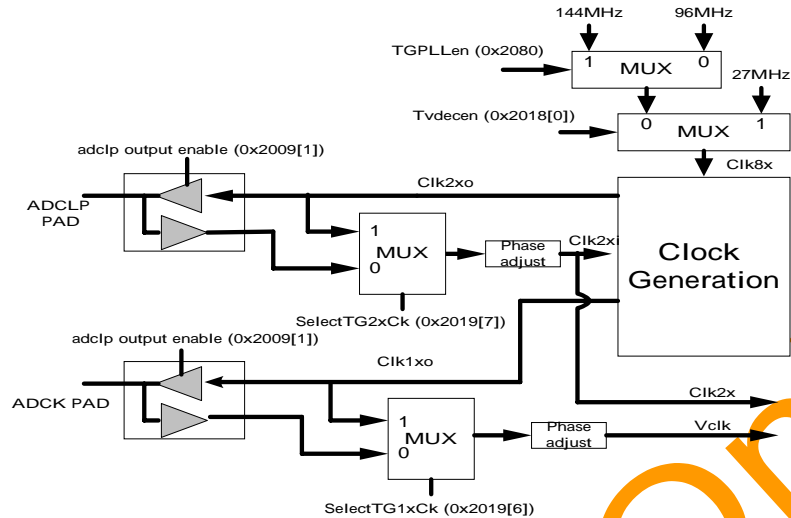
Extclk2xdiv (register 0X2A82[7:0])	2XCK
0	8XCK / 1
1	8XCK / 2
2	8XCK / 3
...	...
254	8XCK / 255
255	8XCK / 256

The 1XCK (pixel clock) is selected by the following setting.

Extclk1xdiv (register 0X2A81[3:0])	1XCK (pixel clock)
0	2XCK / 1
1	2XCK / 2
2	2XCK / 3
...	...
15	2XCK / 15
16	2XCK / 16

The following diagram summarizes the clock selection of pixel clock.





The operation clocks of the TV/LCD interface controller can be programmed by the following settings. The detail information is described in section 5.13.

SelectTVEnc2xCk (reg 0X201C bit 1)	TVEnc2XCK
0	27 MHz
1	24 MHz

SelectTVEnc1xCk (reg 0X201C bit 0)	TVEnc1XCK
0	TVEnc2XCK / 2
1	TVEnc2XCK

The operating clock of the embedded CPU can be programmed dynamically via cpufreq[2:0] register. The default frequency is 12MHz and the highest frequency is 32 MHz. The register design allows the frequency to be changed at run time. The base clock is 96MHz.

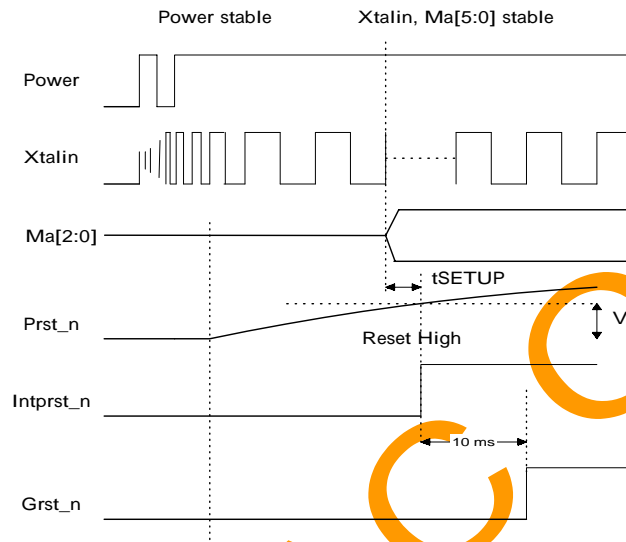
Cpufreq[2:0]	CPU clock
0	32Mz
1	24MHz
2	12MHz
3	6MHz
4	3MHz
5	1.5MHz
6	750KHz
7	375KHz

The SPCA533A can also output a clock for AC97 CODEC or Sunplus's MP3 decoder(SPCA751). The AC97 CODEC takes 24 MHz clock as its input and the SPCA751 usually operated at 13.5MHz. The Audio clock output is an multiplex pin (with GPIO[41]). To select the audio clock output function, set register 0X2019[3]. The audio clock frequency can be programmed by the following register.

AUDCKfreq (register 0X2021[1:0])	AUDCK
0	12 MHz
1	13.5 MHz
2	24 MHz
3	27 MHz

### 1.2.2 Power On Sequence

The power-on reset to the SPCA533A can be designed by a simple RC-delay circuit. The SPCA533's reset pin connects to an internal Schmitt-triggered buffer, which provides about 1 volt hysteresis to the reset pin. The SPCA533's internal reset circuitry delayed the external reset for 10 ms, allowing the stabilization of the phase lock loops. During this delay period, the IO-trap values are latched. The pull-up circuitry attached to the MA pins must be ready before the internal reset terminates.



The SPCA533A must be properly initialized before any camera operation is possible. The following initialization tasks are performed (once) after the SPCA533A is powered on.

#### 1. RTC initialization

- Enable RTC (RTC register 0X00 = 8'h05)
- Check the RTC reliability (RTC register 0X02)
- Load RTC timer (RTC register 0X10 ~ 0X15, 0Xb0 bit 0)
- Load RTC alarm if necessary (RTC register 0X20 ~ 0X25)
- Clear RTC interrupt event (RTC register 0XC0)
- Enable RTC interrupt if necessary (RTC register 0XD0)

#### 2. GPIO initialization:

- Select alternative functions of the GPIO if necessary (register 0X2019 ~ 0X201c)
- Select the GPIO direction (input or output) (register 0X2038 ~ 0X203d)
- Clear interrupts (register 0X2048 ~ 0X204d, 0X2058 ~ 0X205d)
- Set interrupt enable if necessary (register 0X2051 ~ 0X2055, 0X2058 ~ 0X205d)

#### 3. SDRAM initialization:

- Turn on the output enable bit of the SDRAM bus (register 0X2006).
- Select the sdram type(16M, 64M, 128M or 256M)(register 0X2707).
- Adjust the sdram clock phase(register 0X2709).
- Initialize SDRAM (register 0X27A0[2]). The SPCA533A accesses the SDRAM via a 48MHz clock and the CAS latency is 2.
- Set the refresh rate(register 0X270a)

4. Sensor interface initialization: reference to the CMOS sensor and CCD sensor sections for details.

#### 5. Storage media interface initialization:

- Storage media type (0x2400[2:0])
- FMgpio setting (0x2405 ~ 0x2408, 0x2410 ~0x241F)

Note that the media type can be programmed dynamically during camera operation so that switching memory media is possible.

6. Audio initialization:

- a) Set the audio buffer mode (register 0x2605)
- b) Set the audio data format (register 0x2606)
- c) Enable the AC'97 codec or the embedded codec

7. CPU initialization

- a) enable 0x0000 – 0x0fff 4K SRAM (register 0x2C00[0])
- b) enable 0x1000 – 0x1fff 4K SRAM (register 0x2C00[1])
- c) enable banking of the ROM space RompageEn (register 0x2C00[3])
- d) enable RAM space to ROM space mapping via RampageEn (register 0x2C00[2])
- e) Port 1 output enable mode selection via P1oesel[7:0] (register 0x2C02), SFR 8'h90 and 0x201A[4].
- f) Port 3 output enable mode selection via P3oesel[5:0] (register 0x2C03) and **SFR** 8'hB0

8. TV/LCD interface initialization:

- a) Set the display mode (register 0X2D00)
- b) Set vertical line count per frame (register 0X2D02~0X2D03)
- c) Set horizontal pixel count per line (register 0X2D04~0X2D05)
- d) Set vertical sync width (register 0X2D06)
- e) Set horizontal sync width (register 0X2D07)
- f) Set active region for display (register 0X2D08~0X2D08)
- g) Turn on the TV/LCD encoder function (register 0X2001)

9. Other initialization tasks:

- a) The font-base OSD must be upload to the SDRAM
- b) The graphic-based OSD must be upload to the SDRAM and decompressed
- c) The FAT of the storage media must be uploaded to the SDRAM. It is much faster to operate the FAT in the SDRAM(with the DMA to SRAM function) than from the storage media directly.
- d) The audio sound library (if any) must be uploaded to the SDRAM.
- e) The EXIF file header (if any) must be uploaded to the SDRAM for later use.

### 1.2.3 Suspend/resume control

To put the system into suspend state, the CPU must set the “*swsuspend*” control bit in the global control register section. When the camera is connected to the PC, the CPU should program the “*swsuspend*” bit after it received an USB suspend interrupt. When the camera is not connected to the PC, the CPU itself should setup a timer to put the system into suspend state within a reasonable period of time. Both the timer in the built-in 8032 and the timer in the global module can be used to perform the time counting.

In the suspend state, the crystal pads of the SPCA533A is disabled. All the internal clocks are stopped. The firmware should put all the IO pins into low (or high) state to prevent current leakage causing by interfacing to the external modules. The following table shows the ideal state of each pin in typical applications.

CPU interface (note 1)	
Psen	HW driving low
Ale	HW driving high
P0[7:0]	Next instruction address
P1[7:0]	FW programmable
P2[7:0]	Next instruction address
P3[7:0]	FW programmable
Storage media Interface (Note 3)	
Fmgpio[29:0]	Driving Low/Driving high/Floating
SDRAM interface (Note 2)	
	SDRAM power cut-off (Set register 0x2708 to high)
	SDRAM is used as storage media and in self-refresh state

rasnn	HW driving low	HW driving low
casnn	HW driving low	HW driving low
mwenn	HW driving low	HW driving low
md[15:0]	HW driving low	HW driving low
sdclk	HW driving low	HW driving low
ldqm	HW driving low	HW driving low
udqm	HW driving low	HW driving low
cke	HW driving low	HW driving low
ma[13:0]	HW driving low	HW driving low
trap	HW driving low	HW driving low
<b>System</b>		
prstnn	External pull-high	
xtalusbi	NA	
xtalusbo	HW driving high	
Xtal27i	NA	
Xtal27o	HW driving high	
<b>General purpose IO pins (Note 3)</b>		
Gpio[41:0]	Driving Low/Driving high/Floating	
<b>Sensor interface</b>		
rgb[9:0]	Internal pull-low	
<b>Digital TV interface (note 3)</b>		
digtv[21:0]	Driving Low/Driving high/Floating	
<b>Timing generator (Note 4)</b>		
v1	Floating. The firmware must turn off the TG output enable register to make the TG signals floating. Also, all the Bi-direction pins are gated internally by a register bit before it is fed into the core of SPCA533. This will prevent current leak inside the SPCA533.	
v2	Floating	
v3	Floating	
V4	Floating	
sg1a	Floating	
sg3a	Floating	
sg1b	Floating	
sg3b	Floating	
sub	Floating	
fr	Floating	
fh1	Floating	
fh2	Floating	
mshutter	Floating	
vsubctrl	Floating	
pblk	Floating	
fs	Floating	
fcds	Floating	
adclp	Floating	
obclp	Floating	
adck	Floating	
sen	Floating	
sck	Floating	
sdo	Floating	
<b>Analog TV signal interface</b>		
rset		
cbl		
cbu		

vref		
cout		
<b>Audio Codec</b>		
micp		
micn		
opi		
opo		
agc		
agcout		
daca		
audvref		
<b>RTC</b>		
xtalrtci		
xtalrtco		
<b>USB interface</b>		
	Connecting to PC	Stand-alone
dp	Pull-up externally (by camera)	Pull-up externally
dm	Pull-down externally (by host)	Floating (the FW must disable the built-in USB transceiver to prevent current leak)
suspend	HW driving high	

**Note 1.** 8032 port 1 and port 3 can be programmed to drive-low, drive-high or tri-state by the firmware before the systems enters suspend state. The port 0 and port 2 will be driven the address of the next instruction after the one that sets the "SWsuspend" bit. The power of address latch TTL and external ROM must be supplied in the resume period.

**Note 2.** There are two possible states regarding to the DRAM interface signals. If the DRAM's power is cut off during the suspend state, then the firmware should set the "srefresh" bit to high before entering the suspend state. By doing this, all the DRAM interface signals are driven low by the SPCA533. This will consumes the least power. The other case is when DRAM is used as the storage media and the power is not cut-off during the suspend state. In this case, the SDRAM must be put into the self-refresh state by setting the "srefresh" to high to conserve power. The standard synchronous DRAM power consumption in self-refresh is 1.5 mA for 128M SDRAM and 4 mA for 256M SDRAM.

**Note 3.** All the "fmgpio" bus, "gpio" bus and "digtv" bus can be used as GPIO function. So it is easy to programmed this pins to "driving high", "driving low", or "floating" state before the system entering the suspend state. Just which state will consume the least power depends on the application because the application may pull-up or pull-low these pins externally. If the pin is pulled-up externally, then the application, in the suspend state, should let it floating or driving it high. If the pin is pulled-low externally, then the application should let it floating or driving it low in the suspend state. If the pin is neither pulled-high nor pulled-low externally, then the firmware must the set the appropriate registers to make SPCA533A driving it low. Do not let it floating in this case, otherwise, the floating input will cause current leakage inside the SPCA533.

**Note 4.** In a typically application, the sensors and CDS/AGC must be powered-off in the suspend state. The TG interface can be set to floating by turning off the corresponding output-enable registers. Even though some of the TG control pins have alternative function as input pins, the SPCA533A will gate the internal signal to prevent from internal nodes floating.

Once the camera is into the suspend state, it returns to the normal operation state in the following conditions.

A. When the camera is not connected to the PC (stand alone application)

1. SPCA533A has detected a status change on the GPIO pins. The "uirmsen" must be turned on before entering suspend state.
2. The camera is plug into the USB port. Note that the internal USB transceiver might be turned off when the camera is not connected to the PC. In this case, the first thing for the CPU to do is to turn on the internal USB transceiver again. This approach is the same as previous one except the GPIO pin is connected to the USB connector power.

B. When the camera is connected to the PC (on-line application)

1. Host resumes the USB device.

- The camera is disconnected from the PC
- SPCA533A has detected a status change on GPIO pins. This is the remote wake up function. The "uirmsen" must be turned on to perform remote wakeup. Both approach 2 and 3 need a GPIO pin to be connected to the USB power.

### 1.2.4 Power Saving Consideration

The clocks supplied to the internal modules are controlled by register 0X2010 ~ 0X2013. To conserve power during camera operation, these clocks can be turned off when the corresponding modules are not in operation. The analog macros, like the video DAC, can also be put into the power saving mode when it is not used. The following table summarizes the operating condition of the internal modules according to the camera operation modes. In this table, 'N' represents the corresponding module is not in operation, 'Y' represents the corresponding module should be in operation, and 'O' represents the operation is optional.

Camera operation mode	Sensor interface controller	Color DSP	DRAM controller	LCD/TV interface controller	Storage media interface	Audio controller	USB controller	DMA	JPEG engine	CPU
Idle	N	N	N	N	N	N	N	N	N	Y (1)
Preview	Y	Y	Y	Y	O (2)	N	N	O (2)	N	Y
Capture	Y	Y	Y	Y	Y	O (3)	N	Y	Y	Y
Playback	N	N	Y	Y	Y	O (3)	N	Y	Y	Y
Data transfer (4)	N	N	Y (5)	N	Y	N	Y	Y	N	Y

- The CPU should operate at the lowest frequency to conserve power. In this mode, all the GPIO events still generate interrupts to the CPU. So the CPU can still receive events of the user interface buttons and the event of a USB plug-in.
- If the data access to the storage media is executed at background while previewing the image, the clock should be supplied to the storage media interface controller.
- If the camera does not support audio function, the audio controller should be put into the power-down mode. Otherwise, it should be turned on when capturing video, recoding an audio annotation and audio playback.
- Here, the data transfer means transferring data between the PC and the camera via the USB bus.
- The DRAM controller is usually in operation when accessing the storage media. The DRAM can be used in constructing and maintaining the FAT. It can be used as the temporary buffer in the data transfer.

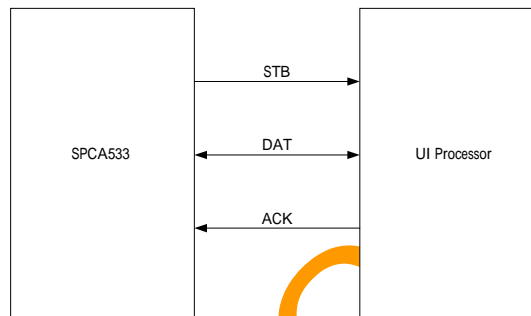
The following table summarizes the register settings to power-down individual modules and their corresponding analog macros.

Module name	Power Saving Description	Register Setting
Sensor interface controller	Stop timing generator input clocks Power down TG PLL	0X2013[2:0] = 3'h0 0X2080 = 8'h00
Color DSP	Stop the 48 MHz clock input of this module Stop the pixel clock	0X2010[0] = 0 0X2012[1] = 0
DRAM controller	Stop the 48MHz clock input to this module	0x2010[5]=0
LCD/TV controller	Stop the 48 MHz clock input to this module Stop the TV/LCD pixel clocks Power down TV encoder DAC	0X2010[7] = 1'b0 0X2013[4:3] = 2'b0 0X2001 = 8'h0C
Storage media interface	Stop the clock input to this module	0X2010[2]=0
Audio controller	Stop the 48 MHz clock input of the audio controller Stop the 12MHz clock input of the audio controller Gate the AC-link input clock Power down Audio CODEC	0X2010[4] = 1'b0 0X2011[1] = 1'b0 0X2013[7] = 1'b0 0X2670[0] = 1
USB controller	Stop the 48 MHz clock input of the USB controller Stop the 12 MHz clock input of the USB controller	0X2010[3] = 0 0X2011[0] = 0

	Power down USB transceiver	0X2005[0] = 1
DMA	Stop the clock input to this module	0x2010[1] = 0
JPEG	Stop the 48 MHz clock input to this module	0X2010[6] = 0
CPU	Set the CPU operating clock to the lowest frequency	0X2024[2]=3'h7

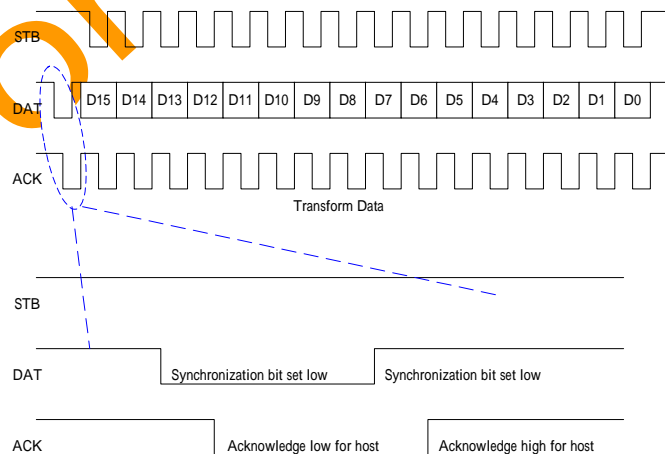
### 1.2.5 User Interface

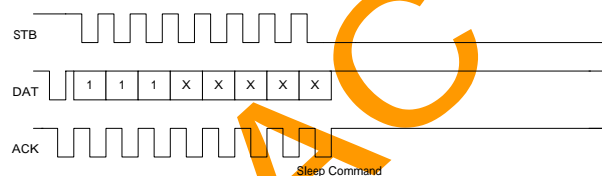
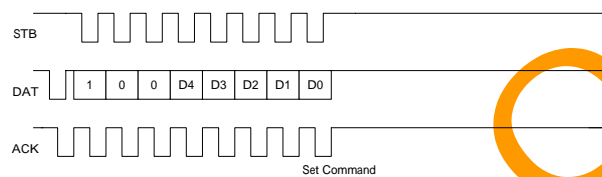
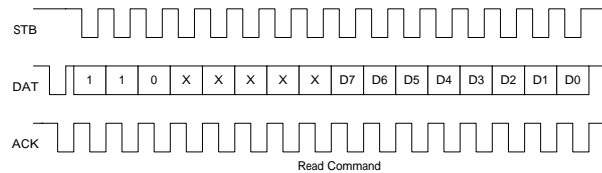
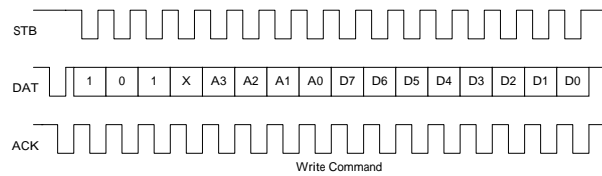
The SPCA533A communicates with the UI module (Sunplus SPL10A) via a 3-pin serial interface. The SPL10A is the Sunplus UI module, which integrates a status LCD and the key-scan function. The SPCA533A may send data to the UI module. For example the picture count can be sent to the UI module and displayed on the status LCD. The SPCA533A can also read the key status from the UI module. The interconnection between the SPCA533A and SPL10A is shown below.



The SPL10A acts as a slave in the camera system. It does not send data to the SPCA533A spontaneously. The SPCA533A reads the key status on the UI module periodically and interrupts the micro-controller. This polling procedure is done by hardware and the polling interval is programmable. In cases that user inputs be sent to the micro-controller in real time, the GPIO pins of the SPCA533A should be connected to the user input instead. Because the user input via the UI module is read by the SPCA533A periodically and does not guarantee to be delivered in real time. Also, if the user input is used to wake up the SPCA533A from the suspend state, it should also be connected to the SPCA533A GPIO pins, too. Because the SPCA533A stops the polling procedure in the suspend state.

The following timing diagram shows the communication protocol between the SPCA533A and SPL10A.





**Transmit data to the UI module :** set the UITxReq high and then poll for the UITxRxCmplt bit. After the UITxRxCmplt bit is detected high, write the data to the UITxData port and poll for the UITxRxCmplt again. After the UITxRxCmplt becomes high, the data has been successfully transmitted to the UI module. The firmware must deassert the UITxReq at the end.

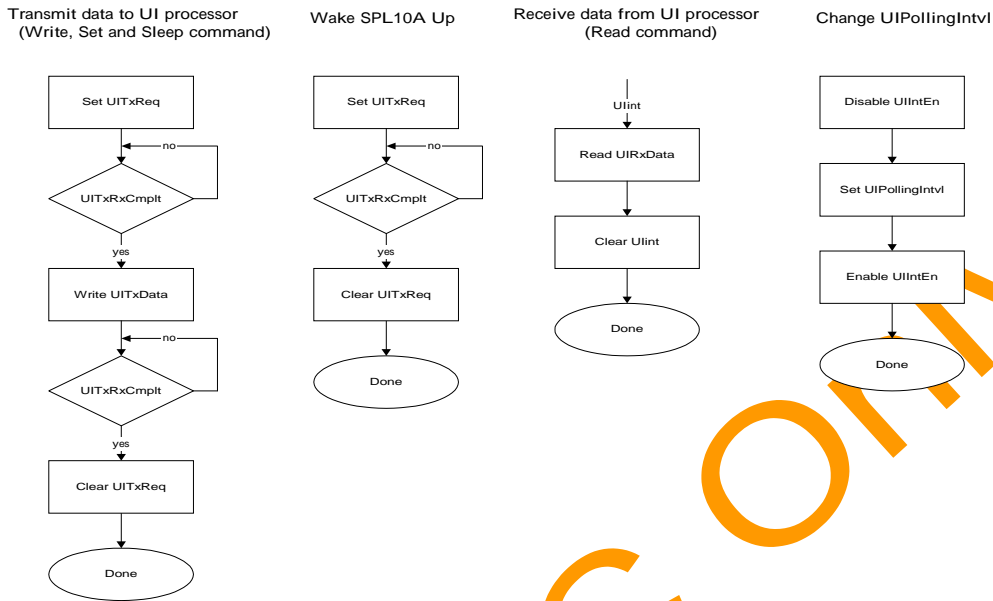
**Put the UI module into sleep :** The STB signal stays low after 8-bit data is transferred.

**Wakeup the UI module :** Set the UITxReq high and wait for the UITxRxCmplt bit becomes high. The UITxRxCmplt bit will become high after the UI module is back to its normal operation state.

**Read data from the UI module:** The hardware of the SPCA533A polls the UI module automatically. If a non-zero data is read, an interrupt will be generated to inform the CPU. The CPU then read the data and clear the interrupt. To change the polling interval, disable the UIIntEn first and write the desired value to the UIPollingIntval in millisecond. The default value of the UIPollingIntval is 1 ms and the range is from 1 to 255 ms. Enable the UIIntEn before returning to the normal polling operation.

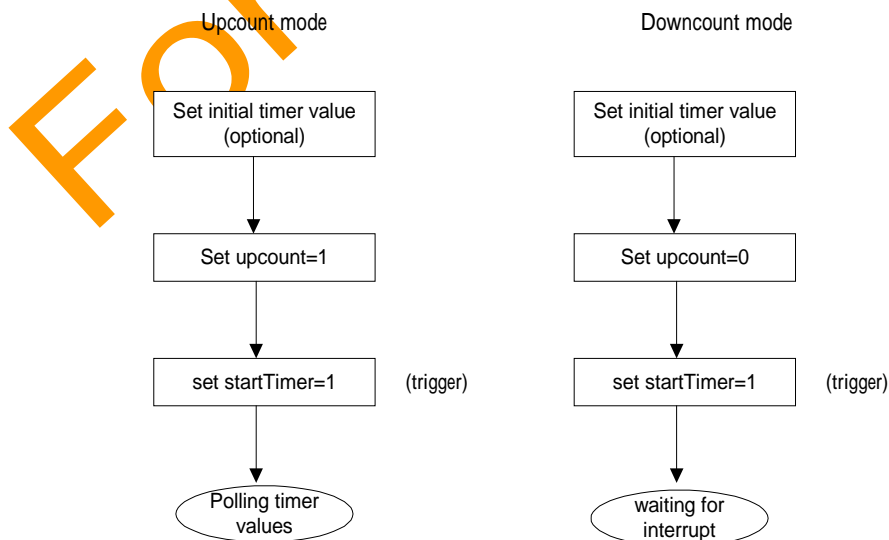


### UI control flow



### 1.2.6 Global Timer Control

The SPCA533A has built-in a global timer, which counts based on 1 ms interval. This timer is a general-purpose timer. The application may use it to do time measurement or uses it a watch-dog timer. The timer is operated either in the upcount mode or the downcount mode. In the upcount mode, the timer simply reports how many ms have passed after it is triggered. In the downcount mode, an initial timer value must be programmed before the timer is triggered, then the timer will decrement for every 1 ms. The downcount mode can be use as an watch-dog timer, which reset the CPU while the timer value downcounts to 0.

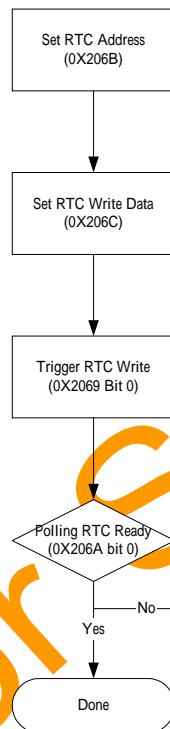


### 1.2.7 RTC

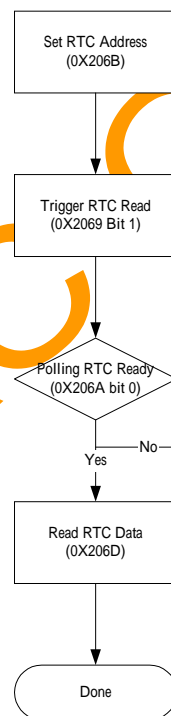
The SPCA533's built-in RTC (real time clock) consists of an 48-bit counter. The frequency of the input clock to the RTC is 32.768 kHz. The value of the counter is translated to year, date, and time by the firmware. Sunplus provides the translation firmware to the customers. The power supply to the RTC module is separated from the power supply to the other part of the SPCA533. While the SPCA533A is powered down, the application must keep supplying power to the RTC to maintain RTC operation. Separating the powers guarantees minimum current leakage.

The internal registers of the RTC module can be accessed according to the flow below.

Write RTC Internal Register



Read RTC Internal Register

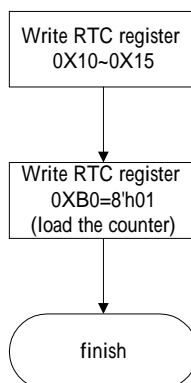


RTC module registers

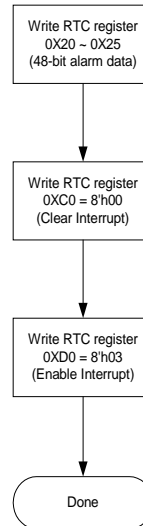
Address	Bit	Att	Name	Description	Default value
0X00	0	r/w	RTCEn	RTC 0: disable 1: enable	1'b1
	1	r/w	RTCRst	RTC 0: normal 1: reset	1'b0
	2	r/w	TimerDir	Timer direction (the count of the timer is to down count or to up count when the RTC clock is from high to low) 0: down count 1: up count	1'b1
0X01	0	r/w	RRP	RTC RRP (register reduce power) signal. 0: disable	1'b0

				1: enable	
0X02	7:0	r/w	reliable	RTC reliable. The RTC value is unreliable when the read out data is different from setting data.	1'b1
0X10	7:0	r/w	LoadCnt	The bit [7:0] of load count of RTC timer	NC
0X11	7:0	r/w		The bit [15:8] of load count of RTC timer	NC
0X12	7:0	r/w		The bit [24:16] of load count of RTC timer	NC
0X13	7:0	r/w		The bit [31:25] of load count of RTC timer	NC
0X14	7:0	r/w		The bit [39:32] of load count of RTC timer	NC
0X15	7:0	r/w		The bit [47:40] of load count of RTC timer	NC
0X20	7:0	r/w	AlarmData	The bit [7:0] of alarm data	NC
0X21	7:0	r/w		The bit [15:8] of alarm data	NC
0X22	7:0	r/w		The bit [24:16] of alarm data	NC
0X23	7:0	r/w		The bit [31:25] of alarm data	NC
0X24	7:0	r/w		The bit [39:32] of alarm data	NC
0X25	7:0	r/w		The bit [47:40] of alarm data	NC
0Xa0	7:0	r	Timer	The bit [7:0] of timer	NC
0Xa1	7:0	r		The bit [15:8] of timer	NC
0Xa2	7:0	r		The bit [24:16] of timer	NC
0Xa3	7:0	r		The bit [31:25] of timer	NC
0Xa4	7:0	r		The bit [39:32] of timer	NC
0Xa5	7:0	r		The bit [47:40] of timer	NC
0Xb0	0	w	TimerLoad	When write one, the write timer data will be loaded to the timer of RTC.	NC
0Xc0	0	r/w	Sec	The interrupt event of the RTC counter reaching to a second. Write zero , the interrupt will be cleared.	1'b0
	1	r/w	Alarm	The interrupt event of alarm data match. Write zero , the interrupt will be cleared.	1'b0
0Xd0	0	r/w	SecEn	The interrupt of reaching to a second. 0: disable 1: enable	1'b0
	1	r/w	AlarmEn	The interrupt of alarm data match. 0: disable 1: enable	1'b0

Following the above read/write flow, the CPU can access the internal registers of the RTC module. The *Timer* register is the actual value reflects the 48-bit counter value. The CPU may read this register and convert it to the year, date, hour, minute and second. The *LoadCnt* register must be updated first before the RTC counter being reloaded. The following flow chart depicts the control sequence to reload the counter value of the RTC.



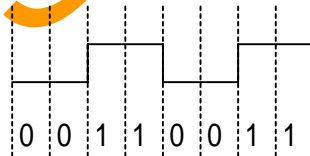
To use the alarm function of the RTC module, follow the control sequence below. The *alarm interrupt* is generated when the timer value reach the alarm value.



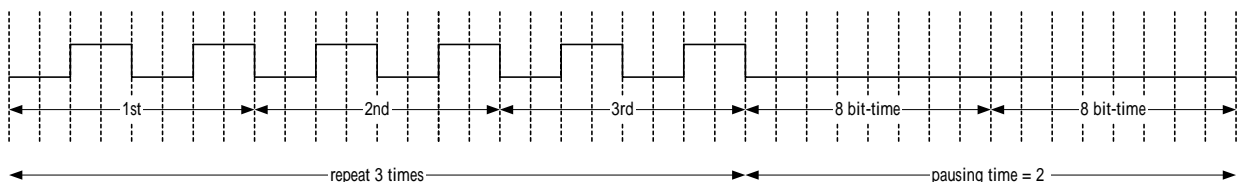
The RTC module of the SPCA533A can also generate interrupts for each second. This interrupt is enabled by RTC register 0XD0[0].

### 1.2.8 Pattern Generator

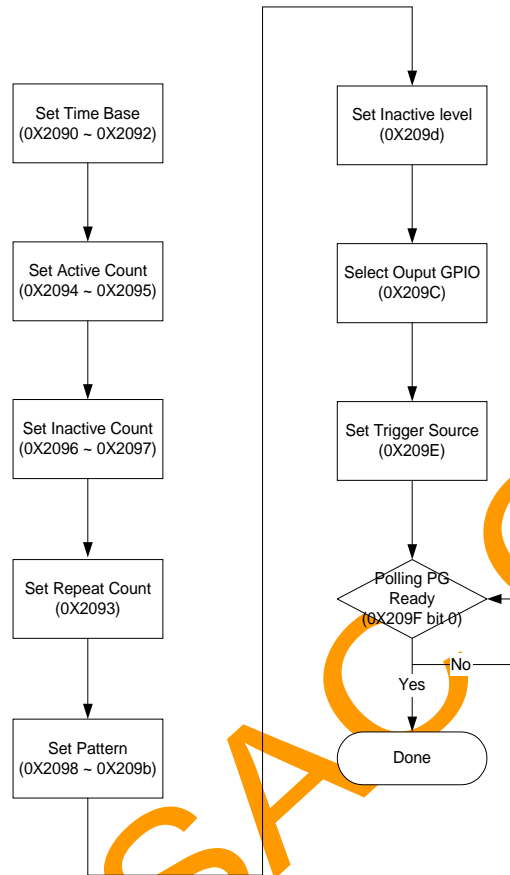
The pattern generator allows the SPCA533A to output a predefined pattern. This function can be used when the system application requires a PWM pulse control. The SPCA533A supports four *pattern registers* (register 0X2098 ~ 0X209B), each of these registers defines a 8-bit *basic pattern*. For example, 33 (Hex) defines the pattern below.



The macro pattern is constructed by assembling the basic patterns. Register 0X2094~0x2095 define how many times the basic pattern is repeated. Register 0X2096~0X2097 defines how long the pattern generator should pass after the basic pattern is output. The pausing time defined in register 0X2096~0X2097 is based on 8 bit-time. The *bit-time* is also programmable (register 0X2090~0X2092). The minimum *bit-time* is 20ns, and the maximum *bit-time* is 336ms. In the pausing period, the pattern generator can be programmed to output 0 or 1. The following example shows a macro pattern repeating the basic pattern 3 times and pausing time is 2. And the pattern generator drives 0 in the pausing period.

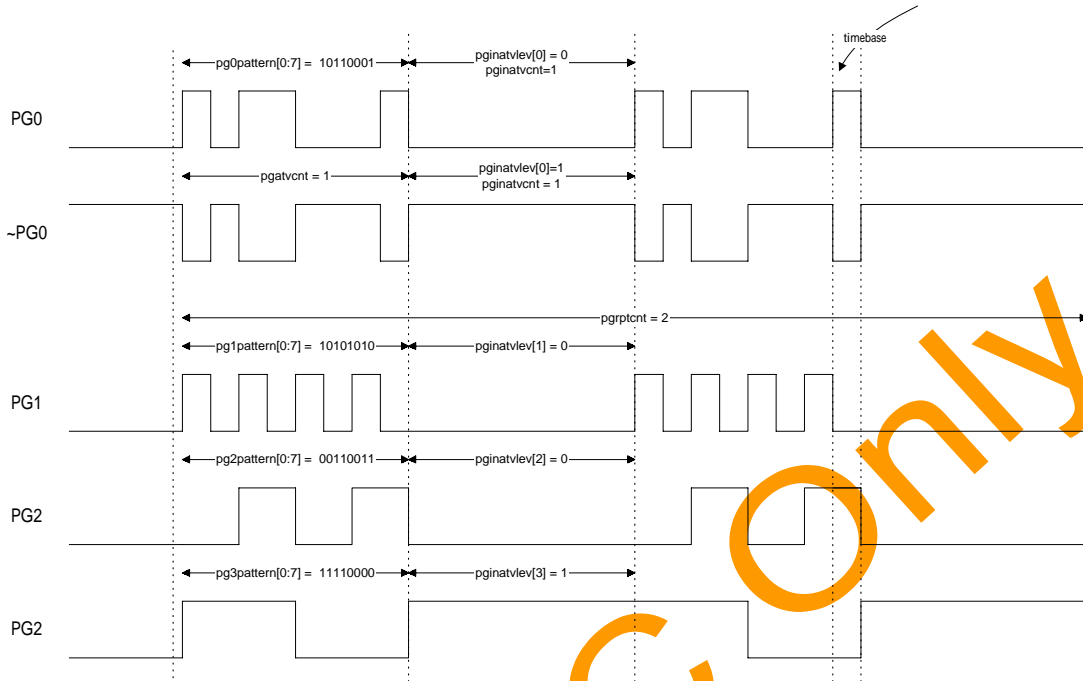


Finally, register 0X2093 defines how many times the macro pattern is to be repeated. The following diagram shows the control flow of triggering a PWM pulse. The generator start to send the timing after register 0X209E[1] is set. Register 0X209f[0] reports whether all the predefined waveform has been sent.



The above diagram shows triggering the pattern generator in manual mode. The pattern generator can also be triggered by the mechanical shutter control signal. Register 0X209E[0] controls whether to select the trigger source as the mechanical shutter control signal (*mshutter*). The timing of *mshutter* is defined in the CCD sensor section. If the *mshutter* is selected as the triggering source, the predefined pattern will be sent whenever the state of the *mshutter* changes (from high to low or from low to high).

The following diagram is an example of programming the pattern generator:



The outputs of the pattern generator are multiplexed with GPIO[24:17]. Register 0X209C determines whether to select the GPIO function or the pattern generation function. The inverse waveform of the pattern generator's output can also be selected.

### 1.2.9 Interrupt Events

Most of the internal modules of SPCA533A generate interrupts to the CPU during operation. The interrupts are routed to the INT0 of the internal CPU. While using an external CPU (or ICE), the SPCA533A routes its interrupt signal to P32. All interrupts sources are listed in the following table. Register 0X2C04 provides information about which interrupt source is asserting the interrupt. This is the first register the firmware has to check whenever an interrupt asserted. There might be many sub-sources of the interrupts. The firmware has to check out the individual sections of the registers to identify exactly where the interrupt event comes from.

Interrupt name	Event description	Corresponding Register
USBint	This interrupt is generated only when the camera is connected to the USB port of a PC.	Event: 0X25C0 ~0X25C2 Enable: 0X25D0 ~ 0X25D2
DMAint	DMA controller interrupt. It is generated when a DMA cycle is completed.	Event: 0X23C0[0] Enable: 0X23D0[0]
FMint	Flash memory interrupt. It is generated when an Flash memory operation is done.	Event: 0X24C0[0], 0x2418 ~ 0x241F Enable: 0X24D0[0], 0x2410 ~ 0x2417
DRAMint	This interrupt is used only in the VideoClip mode. The interrupt is generated each time when the JPEG engine has compressed a complete image. The firmware ISR (interrupt service routine) must record the size of the compressed image for the future use. The size of the compressed image can be read from the size register in the DRAM controller section.	Event: 0X27C0 Enable: 0X27D0
GLOBALint	Global interrupt includes the following interrupt sources 1. VD interrupt, VD is the SPCA533A vertical synchronization signal, this interrupt is generated whenever the signal goes from high to low or from low to high. 2. UI module interrupt, this interrupt is generated whenever the UI interface controller has read a non-zero byte of data from the UI module. 3. GPIO interrupt, the interrupt is generated when any one of the GPIO has a status change.	Event: 0X20C0 Enable 0X20D0

	<p>4. Global timer interrupt. This interrupt is generated when the global timer down counts to zero.</p> <p>5. RTC event interrupt: This interrupt is generated when the bit of "second" of the RTC counter is changed or the counter reaches to the setting of alarm.</p>	
Digtvint	<p>Digital TV interrupt includes the following interrupt sources</p> <ol style="list-style-type: none"> <li>1. TVENC VD interrupt, TVENC VD is the SPCA533A TV encoder vertical synchronization signal, this interrupt is generated whenever the signal goes from high to low or from low to high.</li> <li>2. GPIO interrupt, the interrupt is generated when any one of the digital TV port has a status change.</li> </ol>	<p>Event: 0X2DC0~0X2DC6 Enable 0X2DD0~0X2DD6</p>
Audioint	<p>Audio interrupt sources are the following:</p> <ol style="list-style-type: none"> <li>1. Audio buffer over high threshold or audio buffer under low threshold</li> <li>2. MPFCEB from the MP3 processor goes from low to high</li> </ol>	<p>Event: 0X26C0 ~ 0X26C1 Enable: 0X26D0 ~ 0X26D1</p>

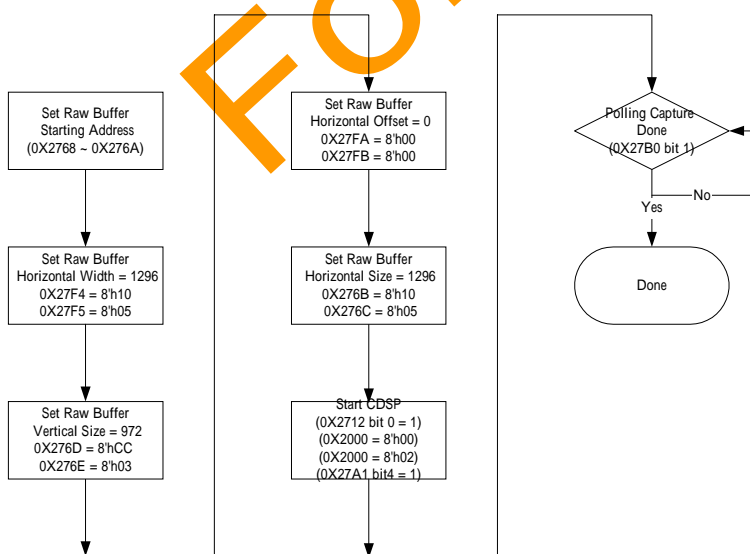
### 1.3 CDSP

The CDSP (Color DSP) of the SPCA533A is a hard-wired image processing engine. In the preview mode, the image with width over 480 pixels must be scaled down in the RGB domain as the first step of the image processing. This is for speeding up the image processing. In the full frame capture mode, the raw data can be stored in the SDRAM first and waited for further process. There is a horizontal scale-down engine in SPCA533A that can be programmed to scale the image to the required size. The image processing is a pipelined architecture, which will be described in the hardwired processor sub-section.

#### 1.3.1 Image size limitation

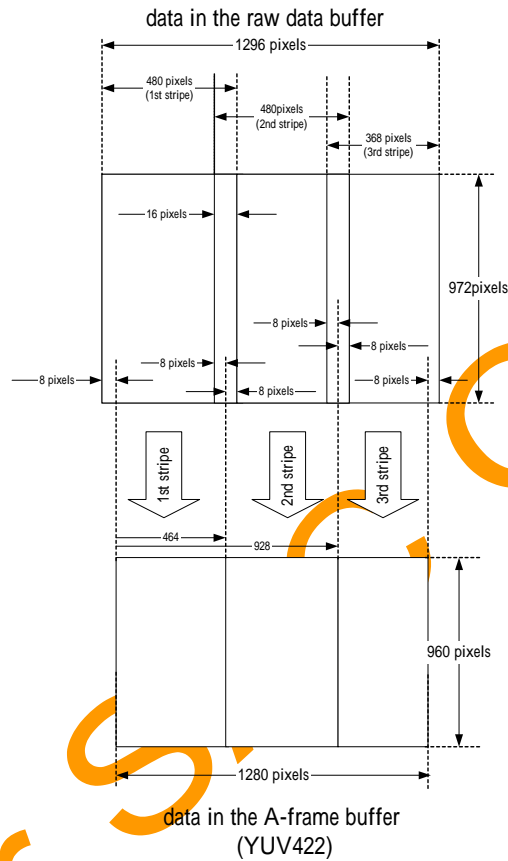
The first step to snap an image is to capture the raw data and store it into the SDRAM. The following diagram shows the control flow. This control flow applies to both progressive sensors and the interlace sensors. If the interlace sensors is connected to the SPCA533, the line sequence is adjusted automatically to make the final raw data fit the Bayer pattern format. The result is stored in the *raw data buffer*. The starting address of the *raw data buffer* is defined in the register 0X2768~0X276A. The following diagram shows an example to capture an 1296x972 raw data.

Capture 1296x972 Image of Raw data



The next step of snapping an image is partitioning the image into stripes with width 480 pixels, putting them in to the CDSP and store the output data to the SDRAM again. After the processing, the image is converted into the YUV domain and will be stored into the *A-frame buffer*.

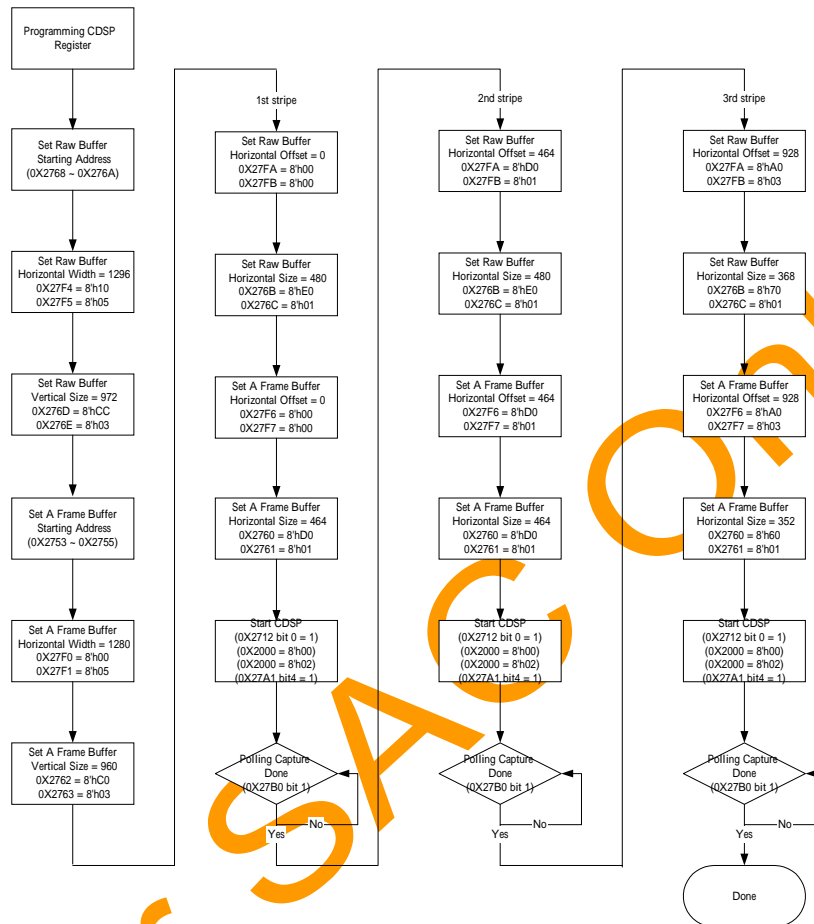
The starting address of the *A-frame buffer* is defined in register 0X2753~0X2755. In the partition, each stripe must have 16 pixels' overlap area with the adjacent stripe to cover the boundaries condition. The following diagram shows an example of partitioning an 1296x972 raw data. The target is to generate a 1280x960 YUV data.



The width of the raw data is 1296, which needs to be partitioned into 3 stripes. The control flow is in the following in the following diagram. Note that the width of the last stripe is only 268 pixels.



Cut and Paste from 1296x972 to 1280x960 Image without Horizontal Mirror



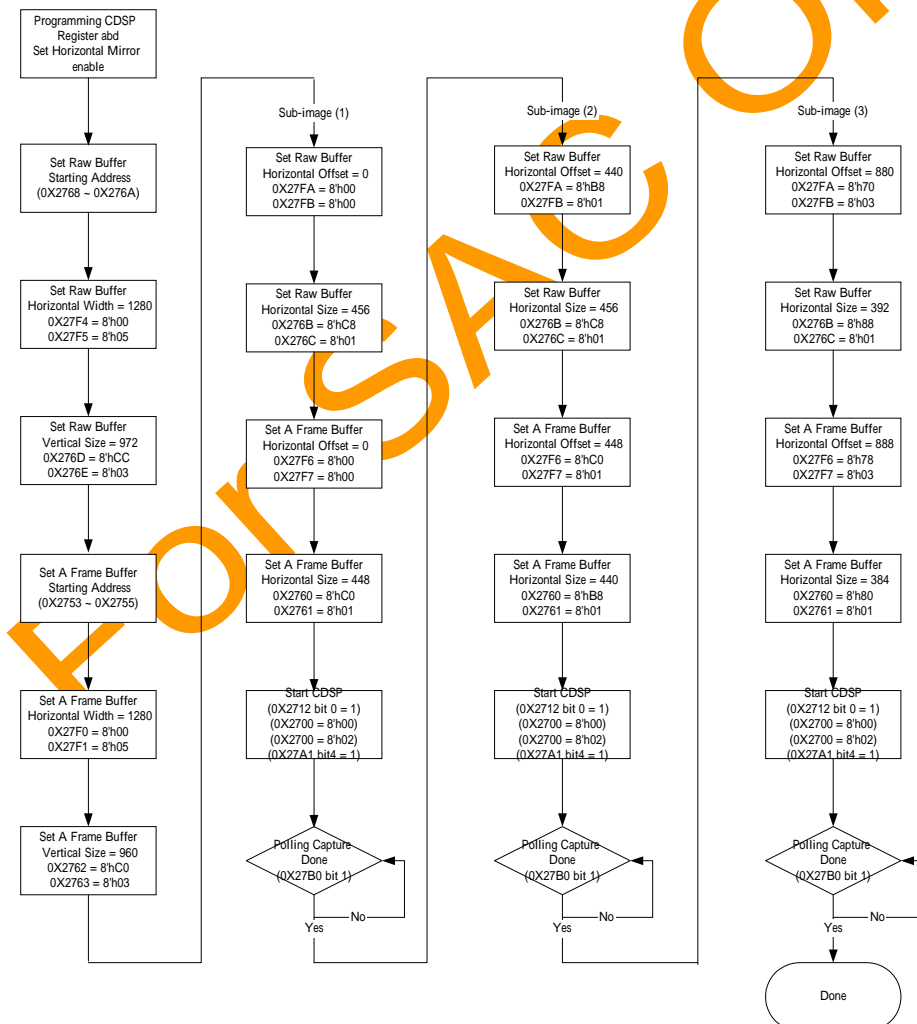
The exposure and white-balance control registers are usually programmed when the camera is in preview mode. The snapped image will use the AE/AWB window values measured in the preview mode. However, when the flash light is applied to the image, the white-balance might need to be adjusted further due to the color temperature change. The SPCA533A allows the user to repeatedly programming the exposure and white-balance control registers, performing the window measurement and read back the window values. This task is executed similar to a standard image processing stated above, but the YUV data is not written back to the SDRAM (controlled by register 0x27F0[0]). Also, the raw data must be sub-sampled if the width of the raw image is over 480 pixels (controlled by register 0x27FC). The following diagram shows the control sequence.

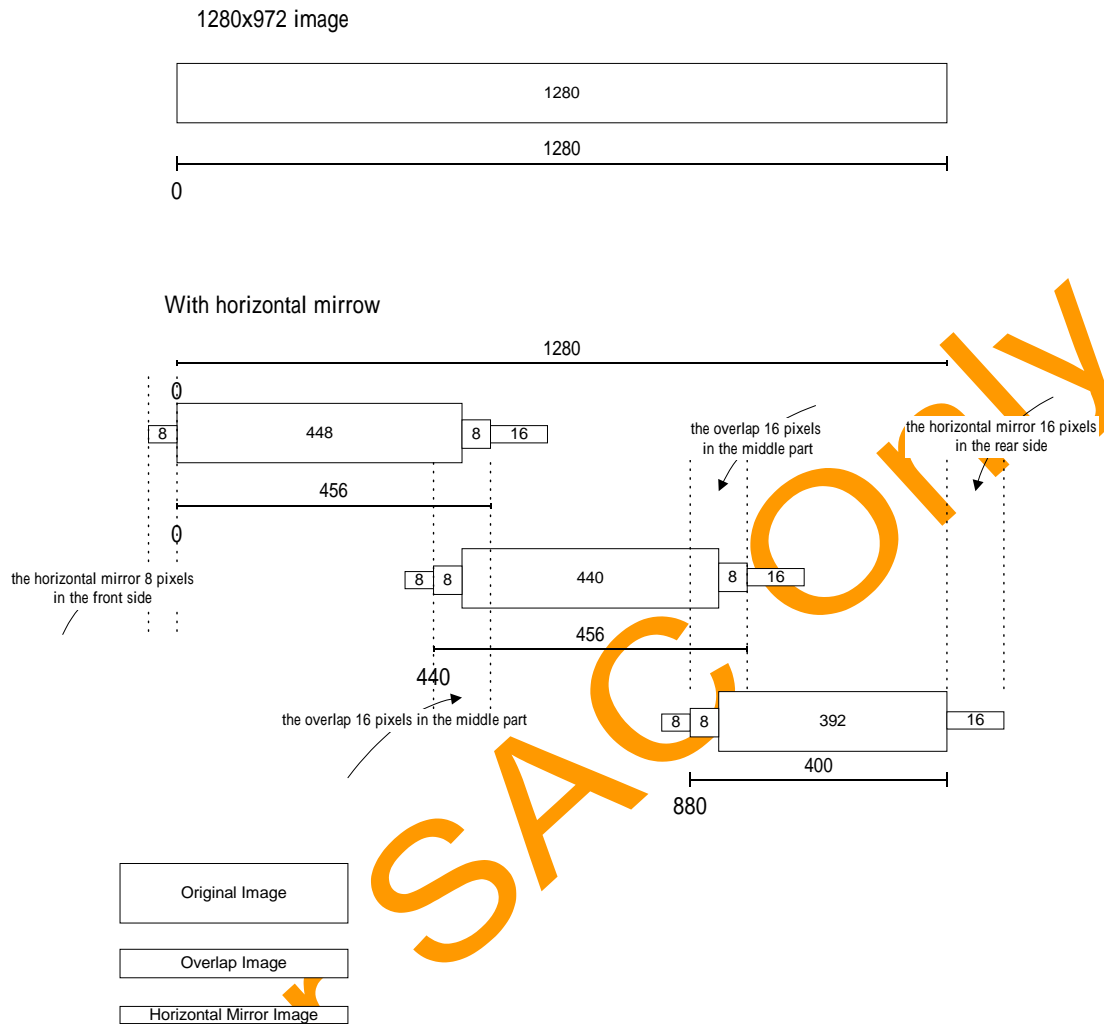


controller.

1. Cut the 456x972 sub-image from the horizontal offset 0 of a 1280x972 image of raw data
2. do CDSP (the first sub-image)
3. Paste the 448x960 image of YUV 422 to the horizontal offset 0 of another 1280x960 image frame buffer
4. Cut the 456x972 sub-image from the horizontal offset 440 of the 1280x972 image of raw data
5. do CDSP (the second sub-image)
6. Paste the 440x960 image of YUV 422 to the horizontal offset 448 of the 1280x960 image frame buffer
7. Cut the 392x972 sub-image from the horizontal offset 880 of the 1290x972 image of raw data
8. do CDSP (the last sub-image)
9. Paste the 384x960 image of YUV 422 to the horizontal offset 888 of the 1280x960 image frame buffer

Cut and Paste from 1280x972 to 1280x960 Image with Horizontal Mirror





### 1.3.3 Horizontal Scale Down on Raw Data

SPCA533A builds in a real-time horizontal scale down engine in the CDSP to scale down the width of the raw image. This function is used in the preview mode or PC-camera mode in which real time image rendering is required. To enable the scale down function, set register 0X271A[0] to 1. The target-to-source image size ratio, is programmable in register 0X271B and 0X21C, which is a 16 bit fractional number.

Example: , horizontally scale down a 1280x240 image to a 320x240 image.

scale down ratio =  $320/1280$

scale down ratio factor = the upper bound integer of  $(320/1280)*65536 = 16384$  (0X4000)

Set register 0X211B = 8'h00

register 0X211C = 8'h40

### 1.3.4 Hardwired Color Processor

The hardwired color DSP performs following tasks: optical black compensation, bad pixel compensation, white balance adjustment, color interpolation, color correction, gamma correction, RGB-to-YUV conversion, 2D-edge enhancement, bright adjustment, contrast adjustment, saturation adjustment, hue adjustment, white balance window statistics, exposure window statistics and focus window statistics.

#### Data Format.

The Color DSP receives 10-bit RGB Bayer pattern data, and output 8-bit YUV 422 data.

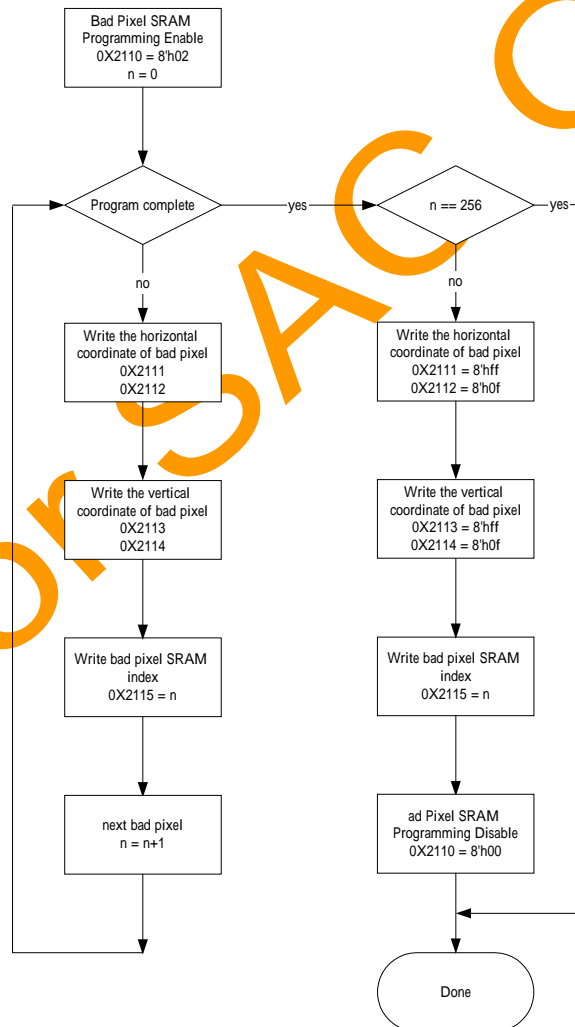
*Register Update:*

All of the CDSP registers take effect right after they are programmed except registers for white balance (0x2120 ~ 2128) and auto focusing (0x2210 ~ 2215) windows, which are effective until the next the start of the next image frame.

*Real time Bad Pixel Correction:*

At the power-on stage of the SPCA533A, the coordinates of the bad pixels must be loaded into the internal registers of the CDSP. This information is used for the real time bad-pixel correction. The SPCA533A can correct up to 256 bad pixels in the real time bad pixel correction. The value of the bad pixel is replaced by the value nearest pixel of the same type. The following diagrams shows the control flow to load the bad pixel coordinates. The programming sequence of bad pixel coordinates must be from left to right and from up to down that is the same as the processing sequence of CDSP. If the bad pixel number is small than 256, the content of the next index after the last bad-pixel on the bad-pixel SRAM must be programmed to the value of 0xFFFFFFFF that is as a terminator of bad-pixel SRAM.

Bad Pixel SRAM Programming



For the still image capture, the bad-pixel correction engine in the DRAM controller can fix the bad-pixel with better quality. The number of the bad pixels that can be fixed in the still image capture is unlimited.

**Optical Black:**

The optical black compensation is applied to the raw data image as the first step of the color processing. The SPCA533A supports two methods of optical black compensation. The first method requires the user to define a value in the *manual optical black level* register. The CDSP subtract this value from all the input pixel values. The other method requires the user to define a rectangle region named *optical black window*. The *optical black window* should locate in the sensor area where pixel cells are shield from the light source. It could be at the top side, left side, right side or bottom side of the pixel array of the sensor. The CDSP automatically calculate the mean value of the pixel data in the *optical black window* and subtract the mean value from all the incoming pixel value. The size and shape of the *optical black window* are also programmable. The type of OB window is defined in register 0X210A[6:4], the horizontal offset of OB window is defined in register 0X210C and 0X210B[3:0] and the vertical offset of OB window is defined in register 0X210D and 0X210B[7:4].

(obhoff,obvoff)

obtype=0	1x256
obtype=1	2x256
obtype=2	4x256
obtype=3	8x256

(obhoff,obvoff)

obtype=4	: 256x1
obtype=5	: 256x2
obtype=6	: 256x4
obtype=7	: 256x8

The manual and automatic methods of the optical black compensation are turned on by individual control bits (register 0X201A[1:0]). They can be turned simultaneously.

**White Balance Adjustment:**

Each component of the image raw data (R, Gr, B, Gb) may be respectively adjusted by programming its corresponding offset and gain. The adjustment is done according to the following equation.

$$\text{Output value} = (\text{Input value} + \text{offset}) * \text{gain}$$

The offsets and gains are derived from the AWB (auto white balance) algorithm. The customers may customize their own AWB algorithm. The offsets are defined in register 0X2120 ~ 0X2123 and the gains are defined in register 0X2124 ~ 0X2128.

**ROM Gamma Correction:**

After the white balance adjustment, the CDPS applies a gamma correction to the data. This gamma function is applied to all four components (R, B, Gr and Gb) of the image data with the same fixed curve. A gamma ROM is embedded for this function. The ROM gamma correction function can be turned on by setting register 0X2130[0] to 1.

**Color Interpolation:**

The missing color components in the Bayer pattern are derived in this stage with a SUNPLUS proprietary algorithm.

**Color Correction:**

The equation of the color correction is shown below. The parameters of the 3x3 matrix are programmable.

$$R_{out} = A_{11} * R_{in} + A_{12} * G_{in} + A_{13} * B_{in}$$

$$G_{out} = A_{21} * R_{in} + A_{22} * G_{in} + A_{23} * B_{in}$$

$$B_{out} = A_{31} * R_{in} + A_{32} * G_{in} + A_{33} * B_{in}$$

These coefficients are defined in register 0X2140 ~ 0X2149.

**LUT Gamma Correction:**

The users can optionally choose to do gamma correction after the color correction. The R, G, B components share the same gamma curve. The gamma curve is constructed by a look-up table. The look-up table defines 17 points which represent 16 line segments. The y coordinates of the 17 points are programmable with range from 0 to 255. the x coordinates of the 17 points are equal distance (16) to place between 0 and 256 (the first point is 0 and the last point is to 256, the unit is 4 gray levels).

A programmable low-pass filter is applied to the gamma curve to smooth it. The low-pass filter is enabled by setting register 0X2130[1:0] = 2'b10. The low-pass filter is controlled by a smoothing factor d, which is programmed through register 0X2151.

**R-B Clamping:**

There is a programming clamping value (register 0X2131) to clamp R and B values. The clamping value is shared by R and B and there is a bit (register 0X2130[1]) to enable the R and B clamping function.

**RGB-to-YUV Transform:**

RGB-to-YUV transform equation is shown below:

$$Y = G + 19 * [(R-G) + 24 * (B-G) / 64] / 64$$

$$U = 32 * [(B-G) - 22 * (R-G) / 64] / 64$$

$$V = 32 * [(R-G) - 10 * (B-G) / 64] / 64$$

**2D-Edge Enhancement:**

This chip uses a SUNPLUS-proprietary algorithm for 2D-edge enhancement.

**Low-pass filtering:**

For Y component, a horizontal low-pass filtering can be applied to two adjacent pixels, three adjacent pixels or four adjacent pixels that are programmed by register 0X21A5[1:0]. For U/V components, a low-pass filter can be applied to two horizontally adjacent pixels that is enabled by register 0X21AB[0]. It can also be applied to two vertically adjacent pixels that is enabled by register 0X21AB[1].

**Bright and Contrast Adjustment:**

The function is enabled by register 0X21A6[0]. Y bright/contrast equation: (Y ranges from -512~511) The *Contrast* and *Bright* are programmable in register 0X21A6 ~ 0X21A8.

$$Y_{out} = Contrast * (Y_{in} + Bright)$$

**Saturation and Hue Adjustment:**

The function is enabled by register 0X21AC[0]. UV saturation/hue equation: (U, V ranges from -512~511) The *Sat* and *Hue* are programmable in 0X21AC ~ 0X21AE.

$$U_{out} = Sat * [ U_{in} * Cos(Hue) - V_{in} * Sin(Hue) ]$$

$$V_{out} = Sat * [ U_{in} * Sin(Hue) + V_{in} * Cos(Hue) ]$$

**R, B Clamping for AWB Window Measurement:**

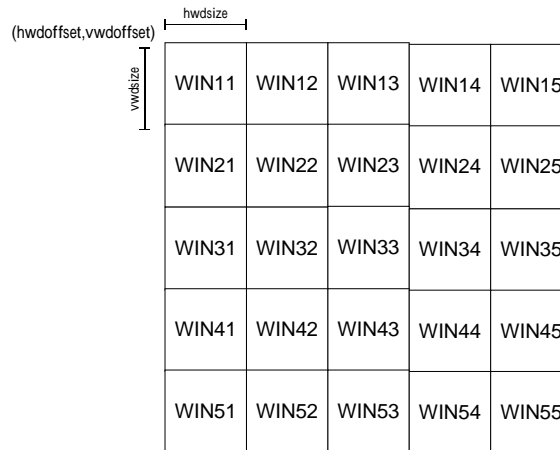
There is a programming clamping value (register 0X2207) to clamp R and B value according to the following equations. The clamping value is shared by R and B and there is a bit (register 0X2206[2]) to enable the R and B clamping function for AWB window measurement. The clamping method is the as in the R-B clamping paragraph.

**R-Y, B-Y Clamping to zero for AWB Window Measurement:**

There is a programming luminance (Y) range (register 0X2208 ~ 0X2209) in SPCA533. If the luminance of a pixel is out of the programming range, the values of R-Y and B-Y will be forced to zero. There is a bit (register 0X2206[2]) to enable the for AWB window measurement.

### AE/AWB Window Measurement:

The SPCA533A partitions the active image region into 25 rectangle windows. The offset and size of the window are programmable by register (register 0X2200 ~ 0X2204).



The CDSP automatically calculates the average value of Y, (R-Y) and (B-Y) components. The average value of Y component is represented by unsigned number and the average value of (R-Y) and (B-Y) components is represented by 2's complementary number. The calculated Y values of 25 windows can be read via register 0X2280 ~ 0X2298 and The average Y value of 25 windows can be read via register 0X2299. The calculated R-Y values of 25 windows can be read via register 0X22A0 ~ 0X22BC and The average R-Y value of 25 windows can be read via register 0X22BD ~ 0X22BE[0]. The calculated B-Y values of 25 windows can be read via register 0X22C0 ~ 0X22DC and The average B-Y value of 25 windows can be read via register 0X22DD ~ 0X22DE[0]. These values are used to implement the AE/AWB functions.

The average value of Y, (R-Y) or (B-Y) component (VAvg) is calculated by the following equation.

- (1) The horizontal sum of the average value of Y, (R-Y) or (B-Y) component on the window: HSum
- (2) The horizontal size of pseudo window (register 0X2205[2:0]): PWHSIZE
- (3) The horizontal average:  $HAvg = HSum / PWHSIZE$
- (4) The vertical sum of the horizontal average: VSum
- (5) The vertical size of pseudo AF window (register 0X2205[6:4]): PWVSIZE
- (6) The average value of Y, (R-Y) or (B-Y) component.:  $VAvg = VSum / PWVSIZE$

The exact average value of Y, (R-Y) or (B-Y) component (Avg)

- (1) The horizontal window size (0X2202[6:0]): WHSIZE
- (2) The vertical size of window (0X2203 and 0X2204[1:0]): WVSIZE
- (3) The exact average value of AF window:  $Avg = VAvg * (PWHSIZE * PWVSIZE) / (WHSIZE * WVSIZE)$

The horizontal width of an image must be less than 480 to do AE/AWB window value calculation. So if the horizontal width of an image is over than 480, it must be scaled down before AE/AWB window value calculation.

### Focus Measurement:

For the focus measurement, the users must define the rectangle region to be measured. The rectangle region is defined by the horizontal offset registers (0X2210 and 0X2212[0]), the vertical offset registers (0X2211 and 0X2212[7:4]), the horizontal size register (0X2213 and 0X2215[0]) and the vertical size register (0X2214 and 0X2215[7:4]). The SPCA533A accumulates all *focus values* of each pixel in this working region. The *focus value* is defined in the following equation. The best focus should derive the maximum average of focus values.



A1	A2	A3
A4	A5	A6
A7	A8	A9

Focus value of pixel A5:

$$FV = |(A7+A8+A9)-(A1+A2+A3)| + |(A3+A6+9)-(A1+A4+A7)|$$

The average value of AF window (VFvAvg) can be read from register (0X2117 and 0X2118[4:0]). The value is represented by 2's complementary number that is calculated by the following equation.

- (7) The horizontal sum of focus value on the AF window: HFvSum
- (8) The horizontal size of pseudo AF window (register 0X2216[2:0]): PAFWHSIZE
- (9) The horizontal average of focus value: HFvAvg = HFvSum / PAFWHSIZE
- (10) The vertical sum of the horizontal average of focus value: VFvSum
- (11) The vertical size of pseudo AF window (register 0X2216[7:4]): PAFVSIZE
- (12) The vertical average of focus value (0X2117 and 0X2118[4:0]): VFvAvg = VFvSum / PAFVSIZE

The exact average value of AF window (AFvAvg)

- (4) The horizontal size of AF window (0X2213 and 0X2215[0]): AFWHSIZE
- (5) The vertical size of AF window (0X2214 and 0X2215[7:4]): AFWVSIZE
- (6) The exact average value of AF window: AFvAvg = VFvAvg \* (PAFWHSIZE \* PAFVSIZE) / (AFWHSIZE \* AFWVSIZE)

The horizontal width of an image must be less than 480 to do AF window value calculation. So if the horizontal width of an image is over than 480, it must be scaled down before AF window value calculation.

## 1.4 DMA controller

The DMA controller in the SPCA533A is in charge of moving data between different modules. It is very flexible and fast.

The DMA data transfer can be performed among six different modules. They are SDRAM, SRAM (address 0x1000~0x1FFF), 1K audio buffer, USB bulk-pipe buffer, the storage media and the CPU PIO. Before each DMA data transfer, the source and destination of the DMA transfer must be assigned first (register 0x2301).

The CPU PIO is a data port at register 0x2300, through which the CPU can access the internal FIFO of the DMA controller. There are 4-byte FIFO in the DMA controller. The size is adjustable via register 0x2304[3:2]. When the CPU PIO is set to be the source of a DMA transfer, the CPU must check the *DMAFULL* flag (register 0x23A0[3]). No more data can be written in to the DMA controller if this flag is high. On the other hand, if the CPU PIO is set to be the destination of a DMA transfer, the CPU must check the *DMAEMPTY* flag (register 0x23A0[4]). No more data can be read from the DMA controller if the flag is high. These flags need to be checked only when the CPU PIO is involved. DMA transfer among other modules are automatically handled by hardware. The firmware need only check the DMA complete flag (register 0x23C0).

It is prohibited to set the source and the destination of a DMA transfer to the same module. To move data to different locations inside the SDRAM, the SPCA533A provide another type of DMA control flow, which is discussed in the SDRAM controller section.

### 1.4.1 Direction of the DMA

The following table lists all the combination of different DMA sources and targets. All these DMA operations are performed in all camera operation modes, except the PC-camera mode. In the PC-camera mode the data flow is manipulated by hardware, the firmware needs only initializing the data path.

Source (data provider)	Destination (data consumer)	Function description
DRAM	CPUIO	For internal diagnostic
DRAM	SRAM	Copy data from the DRAM to the SRAM Useful in FAT manipulation.
DRAM	Storage media	Save the image/audio data in the DRAM to the Storage media.
DRAM	AUDIO	Playback an audio file that is already exists in the DRAM.
DRAM	USB (Bulk)	Upload data from the DRAM to the PC
CPU PIO	Any	The CPU can prepare random data to be moved to the designated destination.
SRAM	CPUIO	This mode is redundant, because the CPU can directly access the SRAM.
	DRAM	Copy data from the SRAM to the DRAM. Useful in the FAT manipulation.
	Storage media	Copy data from the SRAM to the storage media. Useful when the file header is constructed in the SRAM.
	AUDIO	Playback audio file from the SRAM.
	USB (Bulk)	Upload SRAM data to the PC. If the ECC correction is implemented in the firmware while uploading files to the PC, the data is first moved from the storage media to SRAM. Then the ECC correction is done in the SRAM. Finally, the corrected data is sent to the PC from the SRAM to the USB. Basically, any DMA data transfer can be divided into two DMA data transfer with the SRAM as the bridge, so that the CPU has the opportunity to modify the data in the midway.
Storage media	CPUIO	For internal diagnostic
	DRAM	Fetch an image/audio file and stores in the DRAM for playback. Load the FAT from the storage media to the DRAM for further processing.
	SRAM	To speed up the playback tasks, the header of the image file (or audio file) is loaded from the storage media to the SRAM first. And the header parsing is done in the SRAM. After the size of the file is determined, the remaining of the file is loaded to the DRAM.
	AUDIO	Not useful. Normally, the header of the audio file must be stripped by the firmware before playback. However, it is possible to playback the audio file directly from the storage media when the file is a raw PCM data file.
	USB (Bulk)	Upload captured image/audio file to the PC.
AUDIO	CPUIO	Internal diagnostic only
	DRAM	Record the audio data to the DRAM. This is used in the Video Clip and in the audio recording.
	SRAM	Record short sound file only. The size must be under 4K bytes.
	Storage media	Not practical. The access speed of the storage media might cause the recording to pause.
	USB (Bulk)	Used in the PC-camera mode. The SPCA533A can acts as a PC-camera with a microphone input.
USB(Bulk)	CPUIO	Internal diagnostic only
	DRAM	Download data from the PC to the DRAM. Might be used in the ISP function, in which the complete firmware is downloaded in to the DRAM first.
	SRAM	Download data from the PC to the DRAM. Might be used in the ISP function, in which the new firmware is partitioned to blocks of 4K-byte. Each time, the 4K-byte of the ROM code is updated.
	Storage media	Download image/audio file from the PC to the storage media.
	Audio	The SPCA533A can act as an USB speaker in this mode. This is not practical in real application, but very useful while developing the sound data base.

### 1.4.2 Page size adjustment of the DMA

The maximum size of each DMA transfer is limited to 1K-byte. The size is programmable via register 0x2302, 0x2303[1:0]. If the destination of the DMA transfer is the storage media and the DMA size is not aligned to the page size of that storage media, the SPCA533A can automatically padding 0's to make the last data transfer a complete page. This is done through enabling the padding function of the DMA controller. (register 0x2304[1]). On the other hand, if the source of a DMA transfer is the storage media and the DMA size is not aligned to the page size, the DMA controller will issue dummy read to the storage media but the data (of the dummy read) is never sent to the destination. When there are padding 0's or dummy reads, the DMA complete flag will not be high until all the padding and dummy reads are done. The page size refers to the register 0x24A3.

### 1.4.3 Matching pattern in DMA

The DMA controller provides a pattern-search function during a DMA data transfer. The pattern-search is done by peeping the data during data transfer. After a DMA transfer is completed, the DMA controller will report the number of matched pattern (register 0x2313) and the location of the first matched pattern in current DMA transfer (register 0x23A1, 0x23A2[1:0]). This function is useful to help the firmware searching the empty clusters in the FAT. Normally, an empty cluster is represented by a special code in the FAT. The SPCA533A supports both 12-bit and 16-bit pattern search, which correspond FAT12 and FAT16 system. The pattern to be searched is programmable via register 0x2311 and 0x2312.

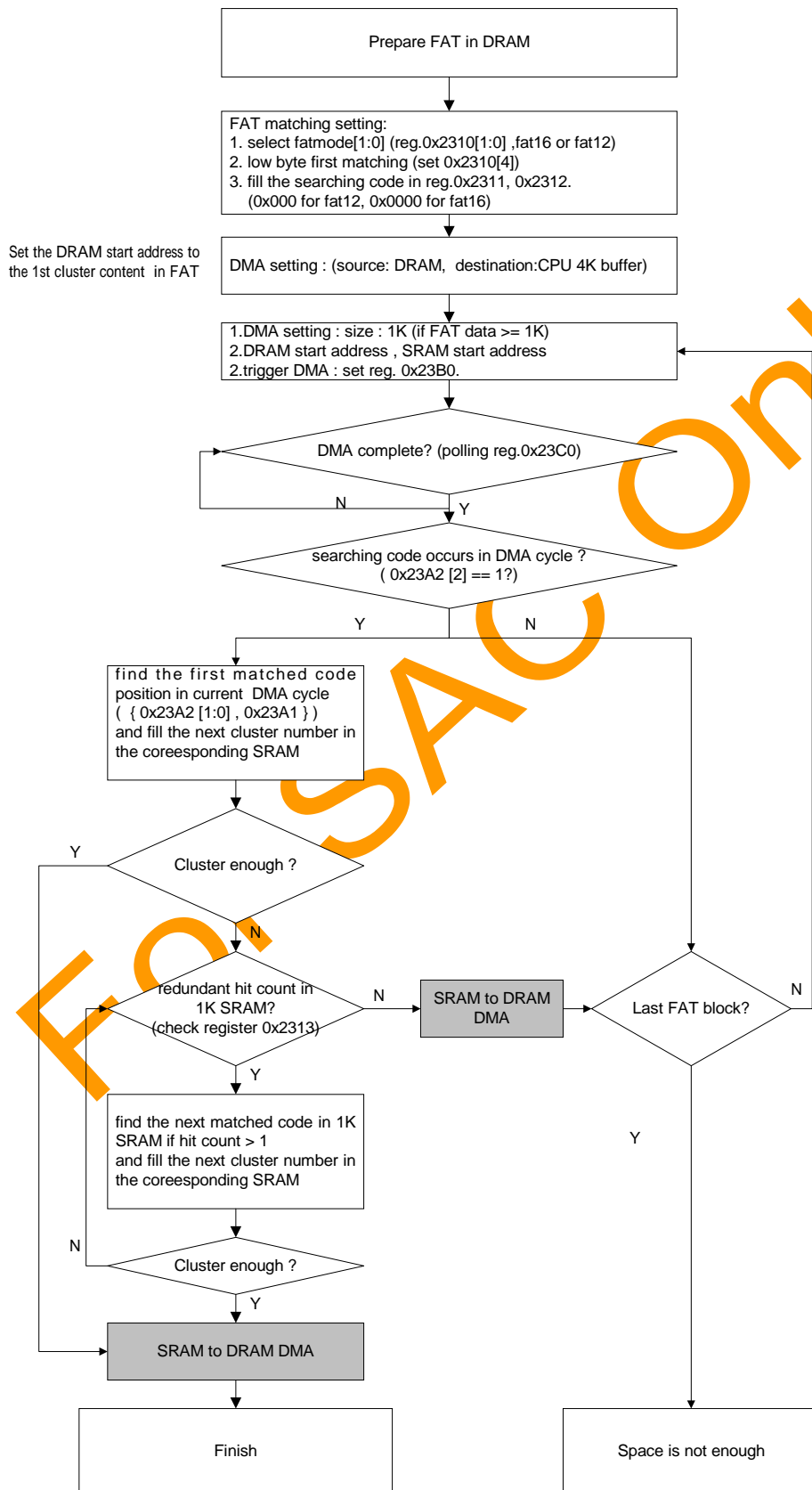
For 16-bit pattern, register 0x2311 is the low-byte pattern and register 0x2312 is the high-byte pattern. For 12-bit pattern, register 0x2311 is the low-byte pattern and register 0x2312[7:4] is neglected. Byte-order bit (register 0x2310[4]) indicates whether the transfer sequence is high-byte first or low-byte first.

The following is an example of the pattern-search.

Transfer Order:	0	1	2	3	4	5	6	7	8	9	10	11	12		
Data:	{	00	04	0F	01	04	05	01	0F	08	01	0F	0B	0C	}

Assume a 16-bit pattern of 0x0F01 is to be searched and the data sequence is low-byte first, the DMA controller will report the first match at location 7 and the matched count is 2. Byte6 and Byte7 form a matched pair while byte 9 and byte 10 form another. Note that byte 2 and byte 3 do not match the pattern since the sequence is reversed. A match flag in register 0x23A2[2] is asserted right after the pattern matches. The number of the matched count is in register 0x23A2[1:0] and register 0x23A1.

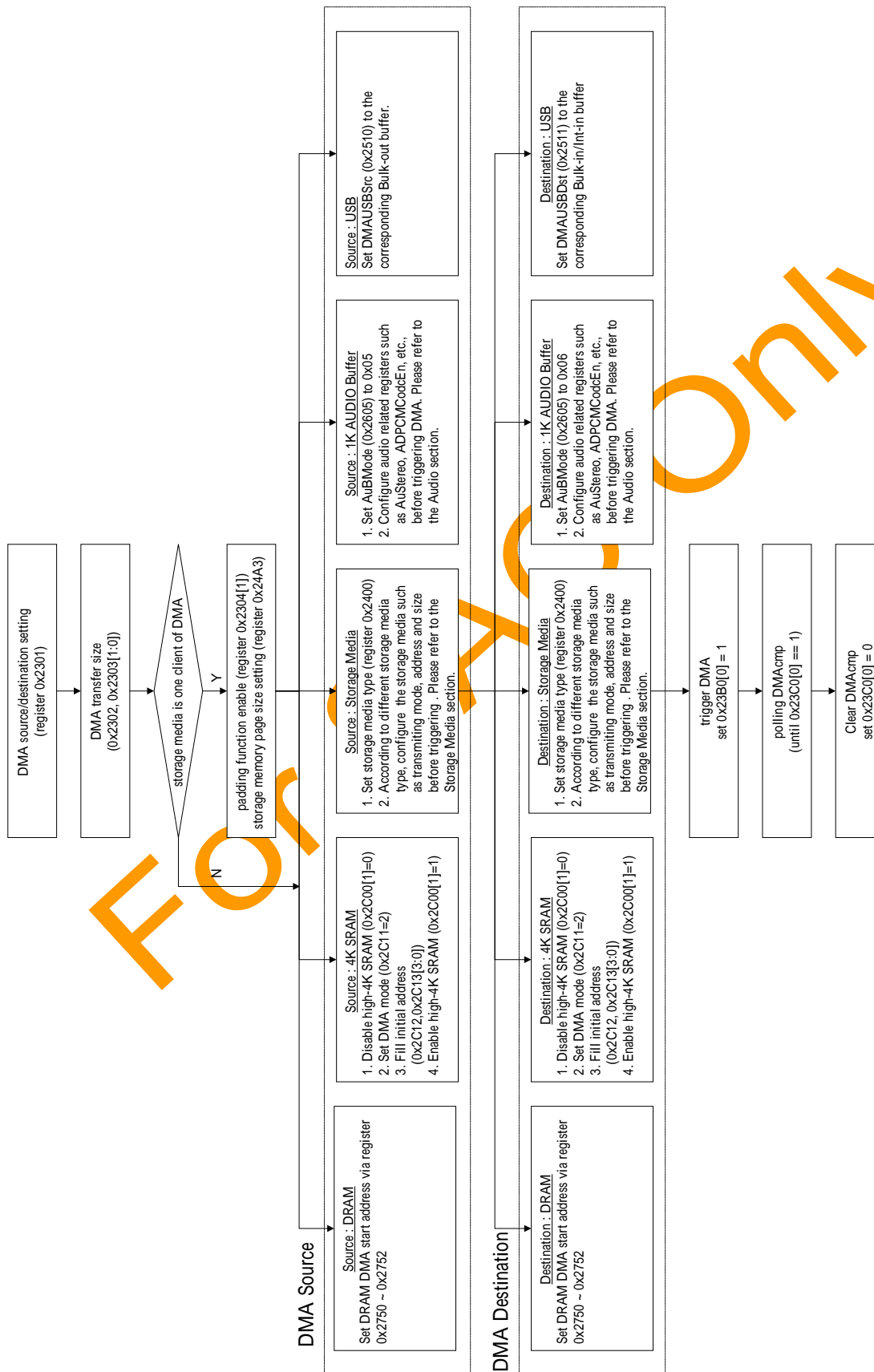
An example of manipulating the FAT is shown in the following diagram.



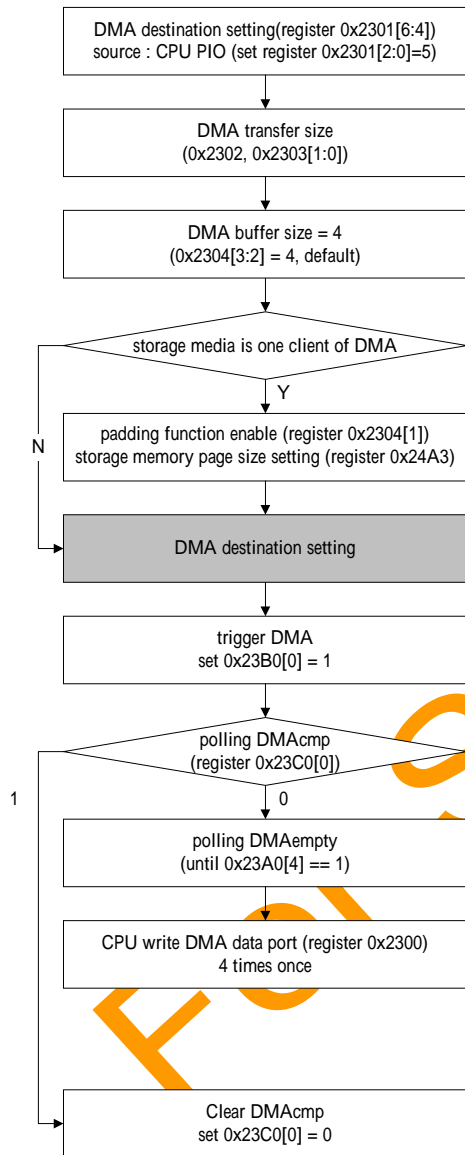
**1.4.4 DMA control flow**

To start a DMA data transfer, the starting address of the related modules must be set before the DMA operation is triggered. The following flow charts shows the related register setting and checking sequence. However, if CPU PIO is the source or the destination of DMA, the sequence is different from the flow chart. The sequence is right after the DMA flow chart.

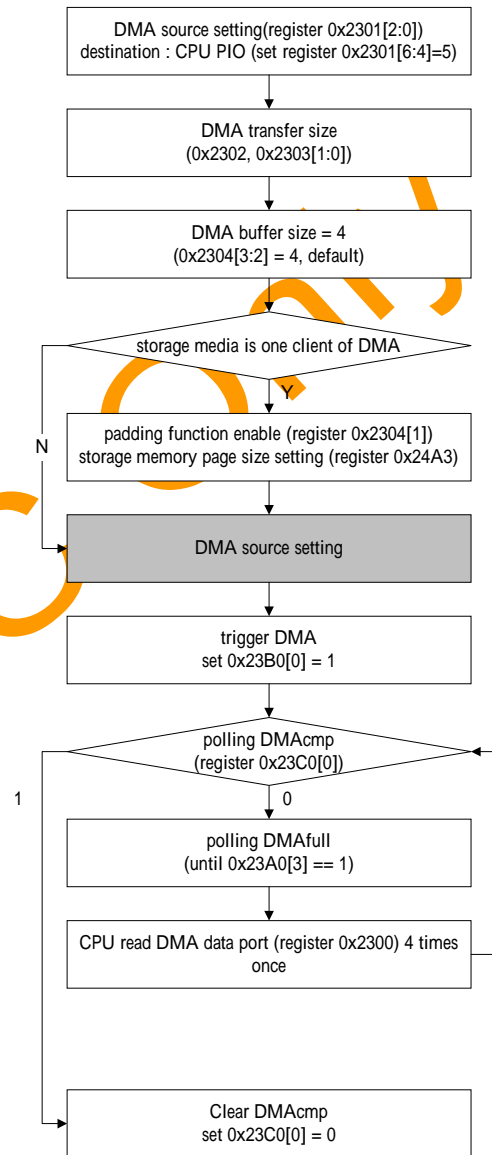
For SAC Only



### DMA CPU PIO Write Flow



### DMA CPU PIO Read Flow



## 1.5 Storage media

Except from the SDRAM, the SPCA533A supports 5 types of storage media, which are controlled by the flash memory controller. There are two accessing modes to read/write the flash memory. One is the PIO mode and the other is the DMA mode. The storage media interfaces are listed below

1. Nand-gate flash memory interface, this interface is also applicable to the SmartMedia.
2. The interface to the CompactFlash cards. It supports the PC card memory mode and the true IDE mode. The true IDE mode also applies to the IDE CDRW such that the SPCA533A can save/restore data to/from the IDE CDRW.
3. SPI interface to the SPI-type serial flash memory with mode 0 and mode 3 supported. This interface also applies to the SPI mode of

MultiMediaCard.

4. The serial interface to the NextFlash serial flash memory.
5. The interface to the SD memory cards.

Although most of the storage media have various operation modes, the SPCA533A supports only SPI mode for the MultiMediaCard, supports PC card memory mode and true IDE mode for the CompactFlash memory cards, and supports only SD mode for the SD memory cards. The SPCA533A has 30 dedicated pins for storage media interface. The pin definitions are different according to the type of the selected storage media.

### 1.5.1 PIO mode and DMA mode

In PIO mode, the SPCA533A reads or writes the corresponding registers for reading/writing storage media byte by byte. Thus the data throughput is limited by the CPU speed. While in DMA mode, the built-in flash DMA controllers can read/write data automatically.

When writing a page of data to the storage media, write data to the DMA source first and then start the DMA controller to move data from the DMA source to the storage media. When reading a page of data from the storage media, start the DMA controller to move data from storage media to the DMA destination. Reference to the DMA section to see the setting of DMA controller. The difference of PIO and DMA mode is the data transferring but not command or address setting. To communicate with different storage media, the protocol is made by the storage media interface module but not DMA controller. In the next section, the PIO and DMA mode for Nand-gate flash is described below. Actually, the setting of DMA mode in other storage media, such as SmartMediaCard, SPI flash, SD memory cards and NextFlash is similar.

### 1.5.2 Nand-gate flash memory and SmartMediaCard

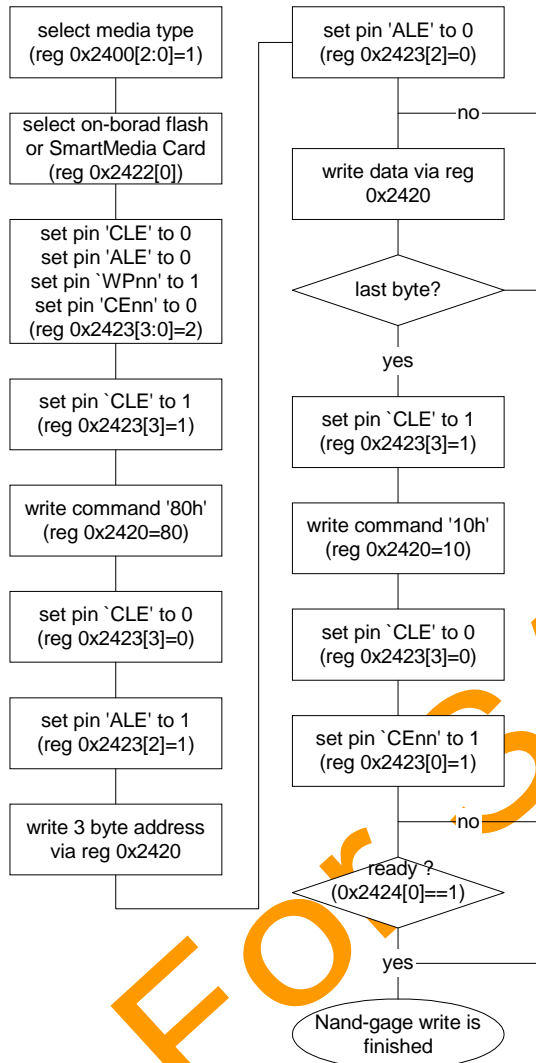
The interfaces of the Nand-gate flash and the SmartMedia memory card are almost alike except that there is an additional card detection function in the interface of SmartMedia memory card. Thus, we only consider the Nand-type flash memory.

The SPCA533A supports Nand-gate flash memory in two ways. The first one is PIO mode and the other is DMA mode. In PIO mode, the CPU write command, address and data to the Nand-gate flash memory via register 0X2420. The CPU also read data and the status byte from the Nand-gate flash memory via register 0X2420. In addition, it also can read the status pin from register 0x2424.

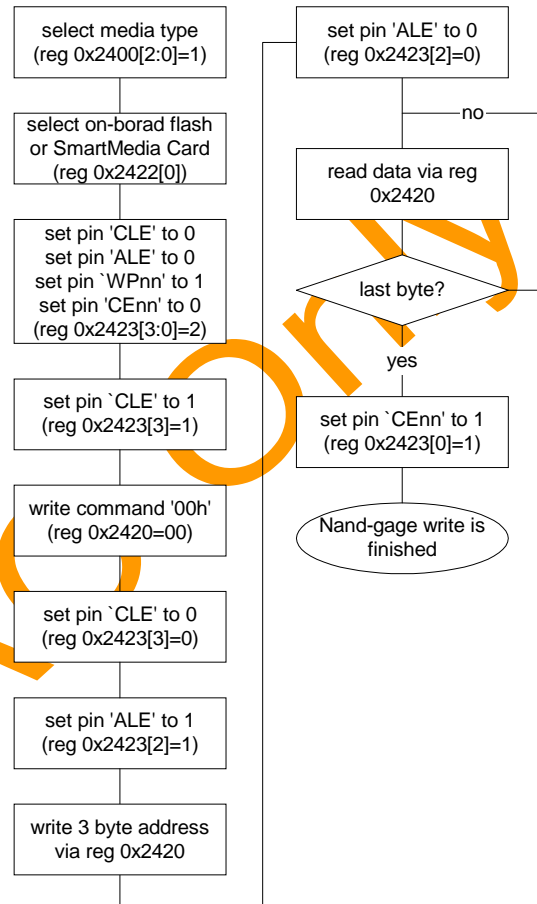
In DMA mode, the CPU write command and address to the Nand-gate flash memory via register 0X2420. It reads the status byte via register 0x2420. For data read and write, the CPU does not need to read/write byte by byte. Instead it triggers the built-in DMA controller. Note that the card detection interrupt function of SmartMedia memory cards interface can be enabled by the fmgpio interrupt function. Setting register 0x2410 bit5 to 1 for rising edge interrupt, register 0x2414 bit5 for falling edge interrupt and the interrupt status is reported in the register 0x2418 bit5. The following flowcharts described the details of control flow in PIO mode and in DMA mode.



### Nand-gate flash write in PIO mode

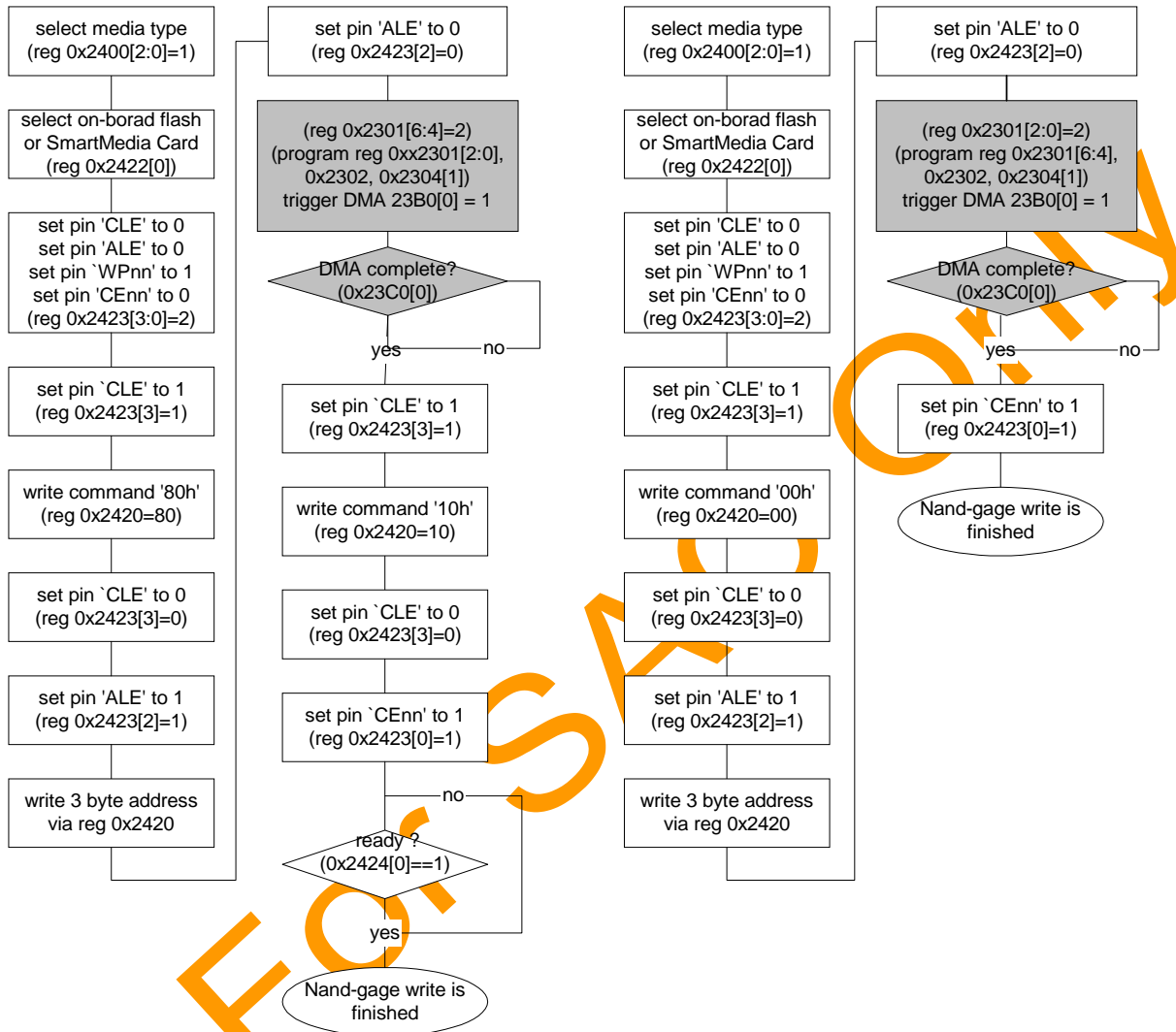


### Nand-gate flash read in PIO mode

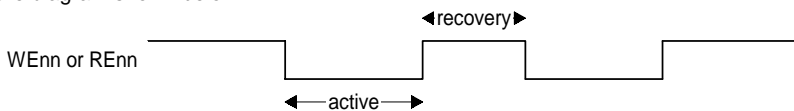


**Nand-gate flash write in DMA mode**

**Nand-gate flash read in DMA mode**



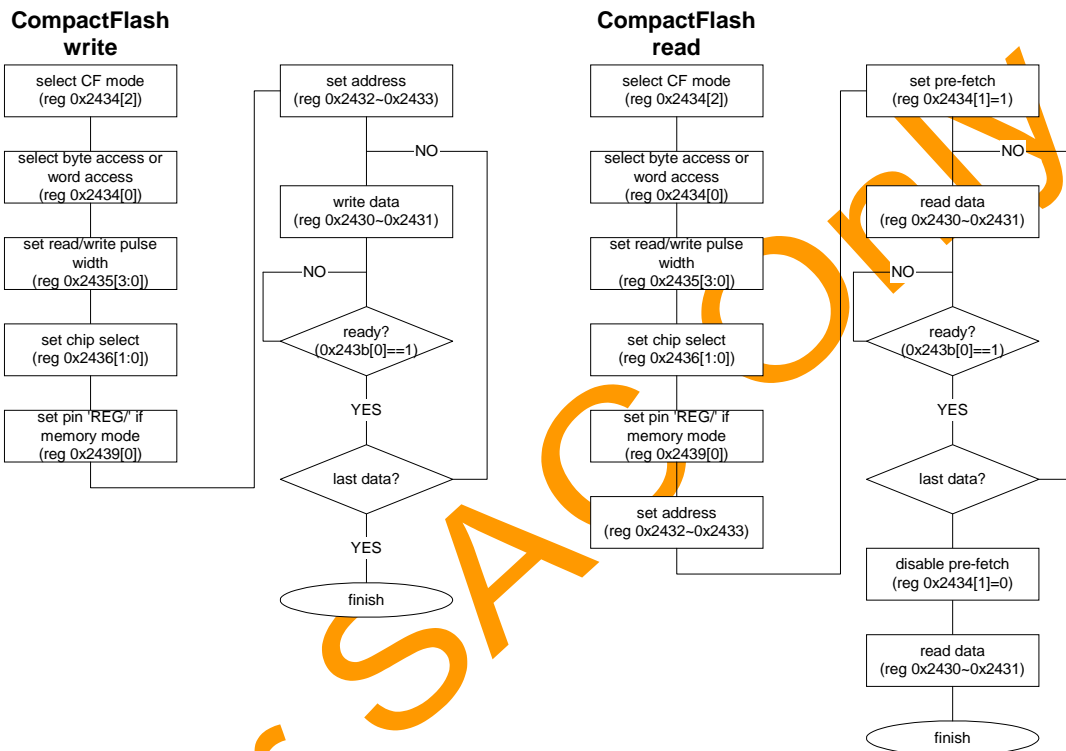
Note that for operating in DMA mode, the active time and recovery time of read/write pulse can be programmed via register 0x2421. See the diagram shown below.



**1.5.3 CompactFlash cards interface**

The CompactFlash cards interface of SPAC533 supports PC-card memory mode and true IDE mode. The true IDE mode also applies to the IDE CDRW machine. Both in memory mode and true IDE mode, the ATA standard is applied and it defines a set of registers. In the PC-card memory mode, ATA registers and memory are selected by 1 chip select pins, 1 register pin and 11 address pins. While in the true IDE mode, ATA registers are selected by 2 chip select pins and 3 address pins. Thus, the firmware must program register 0x2434 bit2 first to select the memory mode or the true IDE mode. Then, the firmware must program register 0x2436 for chip select pins, register 0x2439 for register pin, and registers 0x2432-0x2433 for address pins. Registers 0x2430-0x2431 are the data port for the data transfer. The

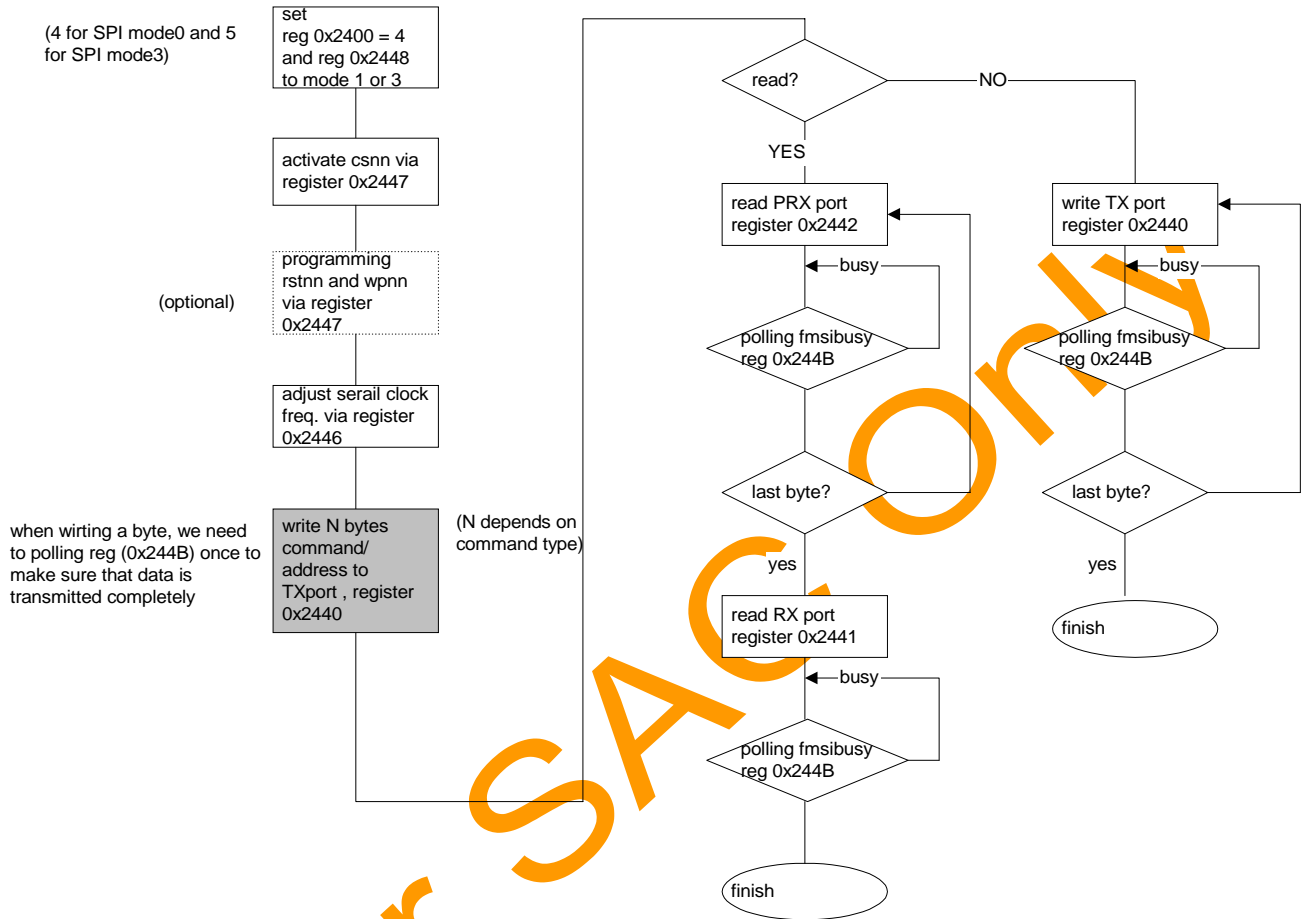
SPCA533A supports the byte access and word access in the true IDE mode while only supports the byte access in the memory mode. The firmware can set register 0X2434 to determine whether to perform a 16-bit or 8-bit data transfer. Due to the different operating modes of CompactFlash cards, the specification of read/write pulse may be different. The firmware can set register 0X2435 to configure the active time and recovery time of the read/write pulse. The detailed information about how to control the ATA device, including the ATA command sets, could be referenced in ATA specification. The following flowchart shows how to control the CompactFlash interface in the SPCA533. The interrupt generated from the CompactFlash card is also routed into the SPCA533. The interrupt status can be polled by reading register 0X24C0 bit 0.



### 1.5.4 SPI interface to the Serial flash memory

The SPCA533A supports an SPI serial interface to access the SPI-type serial flash memory. Both SPI mode 0 and SPI mode 3 are supported. The SPI interface also enables the SPCA533A to access the MultiMediaCard operating in SPI mode. The serial clock frequency is adjustable from 12 MHz to 200KHz. The CPU writes data to the serial flash memory via the TXport (register 0x2440) and read data from the flash memory via the RXport and PRXport. Reading data from the PRXport will invoke a sequence of serial clocks to pre-fetch the next byte of data. Reading data from the RXport merely gets the data that is already received and latched in the SPCA533. Each read sequence starts with a dummy read to the PRXport, followed by multiple read from the PRXport, and finally end up with a read to the RXport. Note that the data read by the first dummy read to the PRXport should be discarded. Each time before the CPU write to the TXport or read from the PRXport, the CPU must wait until the SPI interface is ready. This could be achieved by polling the status bit (FMSIbusy, register 0X244b bit 0) each time before read or write. The following diagram shows the control flow of the SPI interface.

## Serial Flash memory control flow (SPI interface)



### 1.5.5 Next flash serial interface control

For the Next flash serial interface, the CPU has to control the output enable of the serial data bit because the data pin is bi-directional. Also, the CPU has to explicitly start and stop the transfer in order to control the status of the clock pin. There are 2 extra ports for the CPU to read. The first one is PRX1 port. After this port is read, the SPCA533A asserts a signal clock and forces the clock pin stay at high state. The second port is PRX7 port. After this port is read, the SPCA533A will assert the next seven clocks to complete the byte read. This special timing is required by the Next flash memory. The CPU should wait for 30 to 100 us between reading PRX1 and PRX7. Please reference to the Next flash data sheet for the timing requirement.



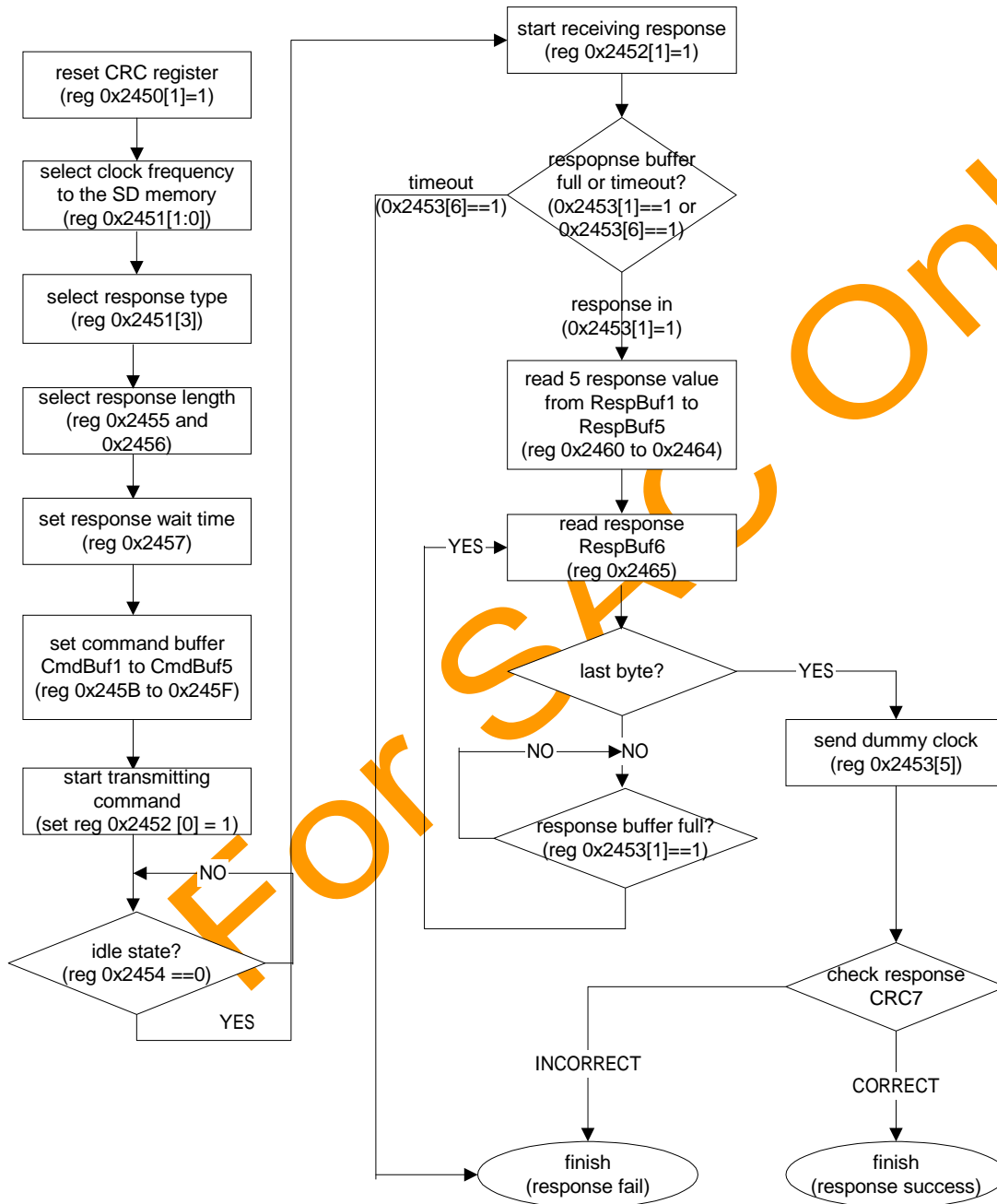
(0x2410 bit2 for rising edge interrupt enable and 0x2414 bit2 for falling edge interrupt enable), the detection of SD memory card will generate an interrupt request to the CPU and it will be reported in the register 0x2418 bit 2.

The dummy clock is applied when the SD memory card needs the dummy clock to complete its operating. Setting register 'TxDummy' to 1 will generate 8 clock cycles. The firmware can get the state status by reading the register 'SDState'. Note that the SD software reset can reset the SD memory interface.

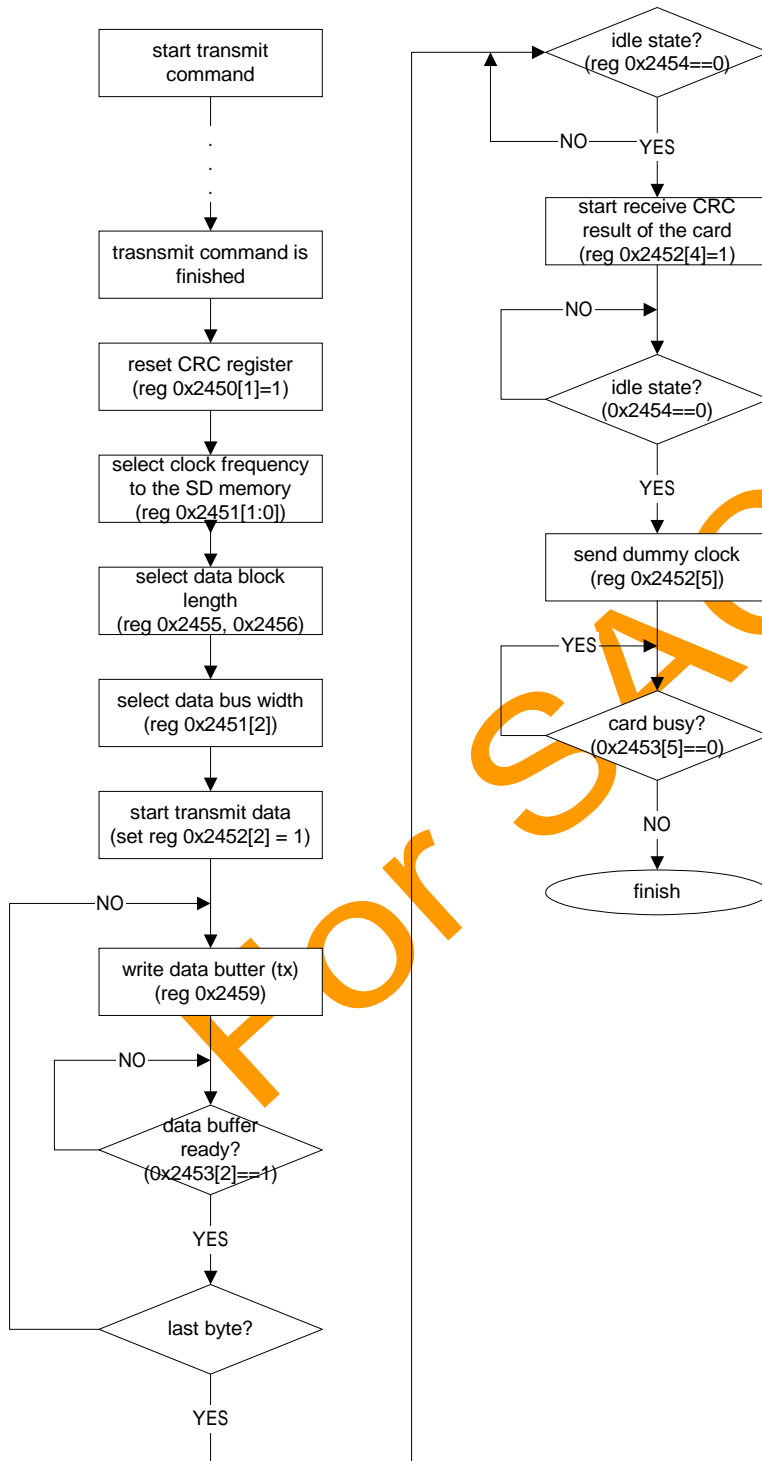
For more details of the SD memory card, including the command, response and register set, please refer to the specification of the SD memory card. The following flowchart will describe how the control the command/response and read/write data.

For SAC Only

SD flash command and response

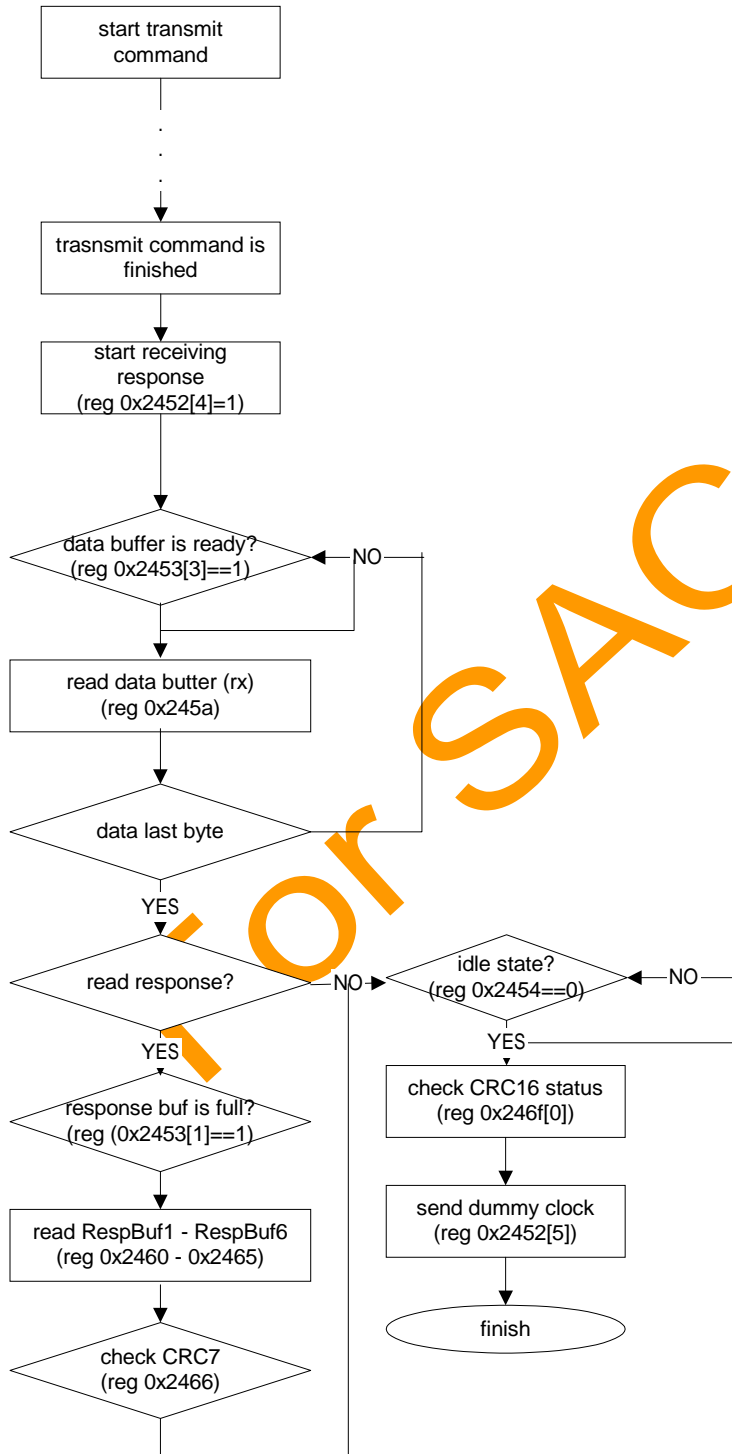


SD flash write data





SD flash read data



1.5.7 The ECC generation

When data is written into the storage media or read from them, a set of ECC codes are generated automatically by the SPCA533. The ECC code is 1-bit error correctable and two-bit error detectable. If the number of error bits exceeds 2 bits, the ECC check fails. The ECC

codes are compatible to the one used in the SmartMedia cards. For every 256 bytes of data, 22 bits of ECC code are generated. Since the SPCA533A allows the application to set the storage media page size to 1024 bytes, there are 12 ECC bytes in total. They could be referenced in register 0X24a4 to 0X24af.

The ECC codes are generated automatically when the CPU read/write the data port corresponding to each storage media. They are also generated when the flash memory operated in the DMA mode. To avoid unnecessary ECC codes generation, the ECC code generation may be disabled by setting register "ECCMask" (register 0X24a2 bit 0). For example, while writing command and address to the nand-gate flash memory, the ECC generation is unnecessary. The ECC code must also be cleared each time a new page is written to or read from the storage media. To clear the ECC code, write 1 to register 0X24a0 bit 0.

### 1.6 JPEG engine

The JPEG CODEC in the SPCA533A is a hard-wired engine. It can perform real time image compression and decompression. The SPCA533's JPEG engine supports YUV422, YUV420 and YUV400 (black & white) formats. The JPEG engine works on VLC stream data. To generate a file compatible to the commonly-used standards, like JFIF, EXIF and DCF, the firmware must prepare the headers of these file formats and integrates them with the VLC stream data. To decode a JPEG file with these formats, the firmware must parse the headers of these files, and strips the header in advance.

The JPEG engine always works with the data stored in the SDRAM. In compression, the JPEG fetches data in the frame buffer, compresses the data and writes back the compressed data to the VLC (variable length coding) buffer. Both the frame buffer and the VLC buffer reside in the SDRAM and their locations are predefined by the users before starting the compression. In decompression, the JPEG engine fetches VLC data from the VLC buffer, decompressed it, and writes the decompressed image data to a predefined frame buffer.

#### 1.6.1 Quantization table

The quantization table is a key factor to determine the quality of the JPEG compression. The SPCA533A has built-in two SRAM's for the quantization tables. One for the luminance quantization table and the other for chrominance quantization table. These tables can be customized by the users to meet any image quality level. The commonly-used quantization tables can be derived by the following formula.

$$\begin{aligned}
 & \text{IF}(\text{quality} < 50) \quad sf = 5000 / \text{quality}, \\
 & \text{Else} \quad sf = 200 - \text{quality} * 2; \\
 & \text{Quantize value of } Y = ((\text{std\_luminance\_table} * sf) + 50) / 100; \\
 & \text{Quantize value of } U, V = ((\text{std\_chrominance\_table} * sf) + 50) / 100;
 \end{aligned}$$

std\_chrominance\_table

17	18	24	47	99	99	99	99
18	21	26	66	99	99	99	99
24	26	56	99	99	99	99	99
47	66	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99

std\_luminance\_table

16	11	10	16	24	40	51	61
12	12	14	19	26	58	60	55
14	13	16	24	40	57	69	56
14	17	22	29	51	87	80	62
18	22	37	56	68	109	103	77
24	35	55	64	81	104	113	92
49	64	78	87	103	121	120	101
72	92	95	98	112	100	103	99

For example: Q50 (quality=50)

Y component ( Q50 )

16	11	10	16	24	40	51	61
12	12	14	19	26	58	60	55
14	13	16	24	40	57	69	56
14	17	22	29	51	87	80	62
18	22	37	56	68	109	103	77
24	35	55	64	81	104	113	92
49	64	78	87	103	121	120	101
72	92	95	98	112	100	103	99

U, V component (Q50)

17	18	24	47	99	99	99	99
18	21	26	66	99	99	99	99
24	26	56	99	99	99	99	99
47	66	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99
99	99	99	99	99	99	99	99

To get an image with the best quality, the quantization tables should be filled with all 1's. The SPCA533A provides a register in 0x2881[0] to force the quantization values to 1's without changing the contents of the SRAM's. This is also applied to the graphic-based OSD function in the SPCA533. In the graphic-based OSD, the minimum quantization values are recommended to maintain the best quality of the graphic icons.

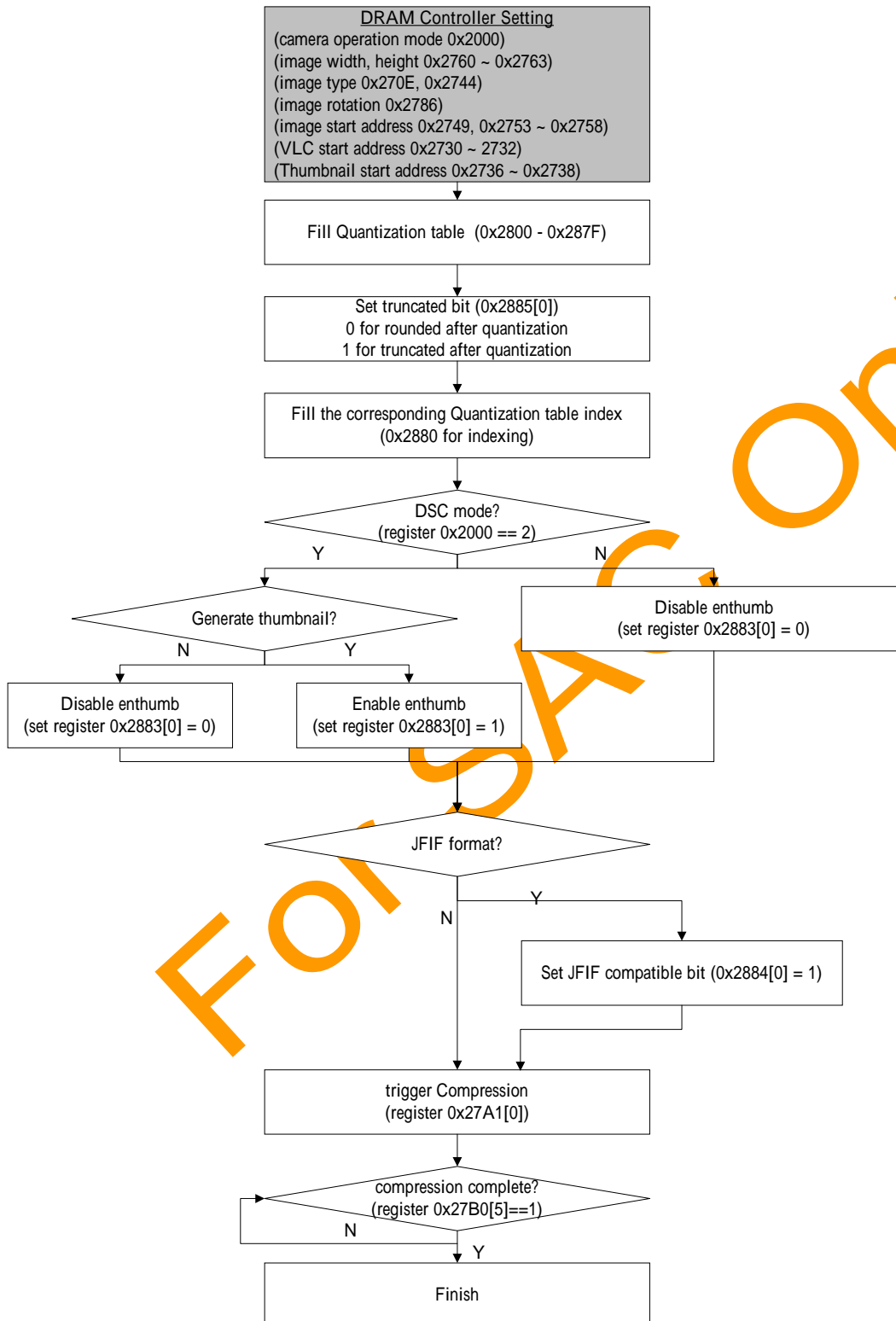
### 1.6.2 JPEG compression

In the following flow chart, the users can choose to generate thumbnail image or not. The thumbnails are a side-product of the JPEG compression. It is generated by collecting all the DC values of each 8x8 block. The size of the thumbnail image is 1/64 of the original image. For example, if an image of size 1280x960 is to be compressed, the size of the thumbnail is 160x120. In a typical application, the size of the thumbnails are fixed. Extracting the DC-terms during JPEG compression results in different thumbnail sizes once the size of the source image changes. The users need to scale the thumbnails generated by the JPEG to the desired size after compression. The format of the thumbnail depends on the image type the users choose in the compression. For example, if the image type is YUV422, the thumbnail's format is also YUV422.

In a file of the JFIF format, the code 0xFF is a special code to indicate a variety of markers. For example, the 0xFFD9 is the marker representing the end of the image data. If there is a data byte 0xFF in the VLC data stream, a code 0X00 must be appended in order to distinguish between the VLC data and marker. This will make the size of the data stream a little bigger. The SPCA533A also supports automatic insertion of the 0X00 code whenever a 0xFF code is detected in the VLC stream. This function is controlled by the *JFIF compatible bit* at register 0x2884[0]. Also, the JPEG compression engine appends the 0xFFD9 EOI code (end of Image) at the end of the VLC stream. The VLC stream is a bit stream. The SPCA533's JPEG compression engine stuffs all 1's to the end of the VLC stream (before the EOI code) if the stream does not align to the byte boundary.

The size of the compressed image can be read from register 0x2720 ~ 0x2722 and register 0x2886. These registers can be read once the compression is completed. Register 0x2720 ~ 0x2722 represents how many bytes are generated in the VLC data stream, including all the stuffing byte and EOI code. Register 0x2886 represents how many bits is stuffing in the last bytes of data. The compression size information is necessary in calculating to total size of the JPEF file. The size should be updated in the file header.

The JPEG engine in the SPCA533A does not insert any markers except the EOI marker. However, some markers are necessary in the file header region. However, these marker are prepared by the firmware. They are not generated by the JPEG engine.



### 1.6.3 JPEG decompression

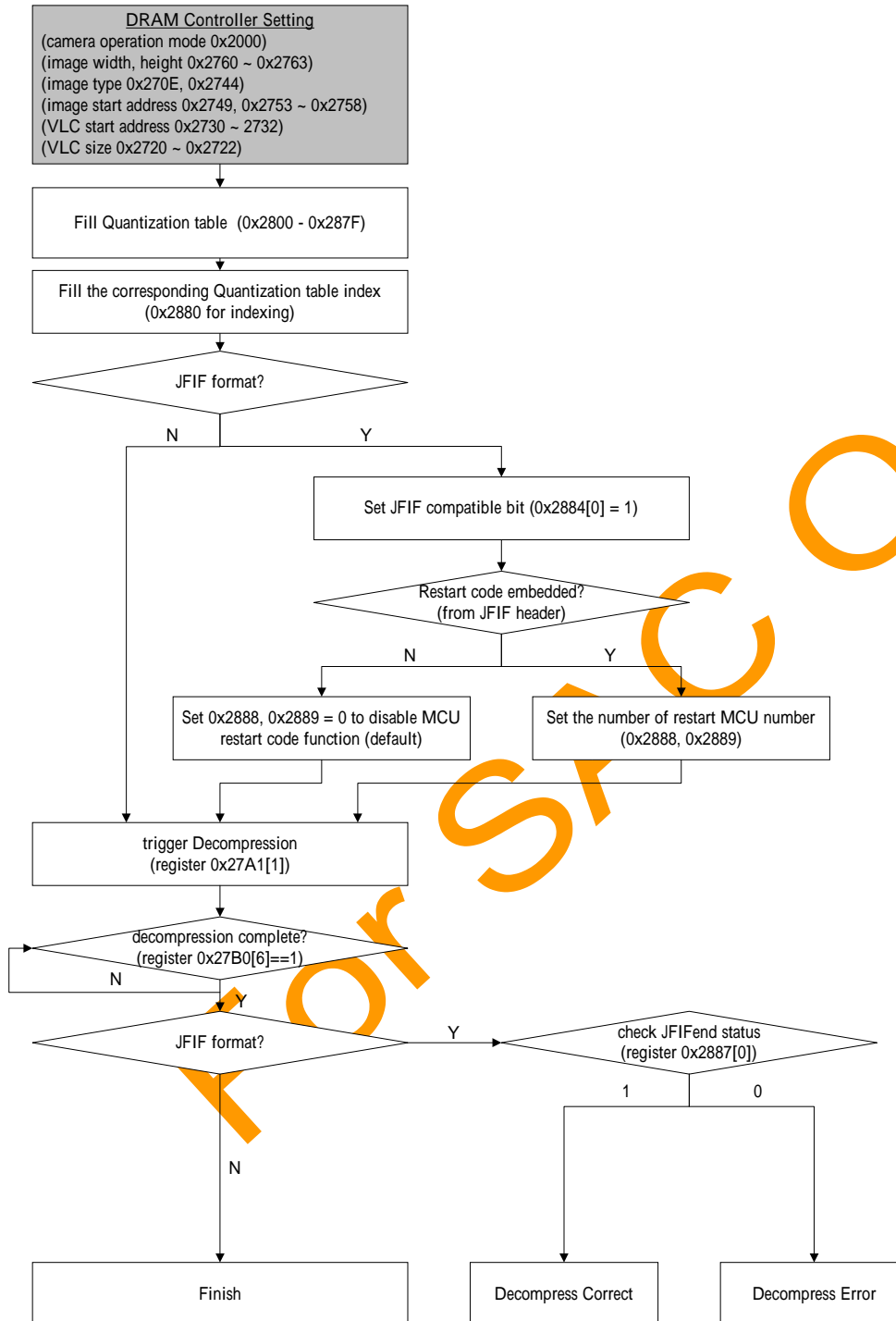
The first step of decompressing a JPEG file is parsing the header. The users must extract the quantization table from the header of the JPEG file and fill them to the internal quantization table of the SPCA533. The image format (YUV422 or YUV420), restart code (if any) information are derived from the header, too. These information must be determined and filled into the related registers before triggering decompression. Again, The JPEG decompression engine works on the VLC data stream only, the header must be stripped by the firmware in advance.

Even though the SPCA533A JPEG compression engine does not generated the restart codes, the decompression engine may decode a file with restart codes. The restart code information resides in the header of the JFIF file which is lead by a marker of 0xFFDD. The users get the information of how many MCU is inserted a restart code and write them into register 0x2888, 0x2889 to enable the restart code stripping function. The *JFIF compatible* bit (register 0x2884[0]), while enabled, instruct the decompression engine to strip the 0X00 code after each 0Xff code in the VLC data stream.

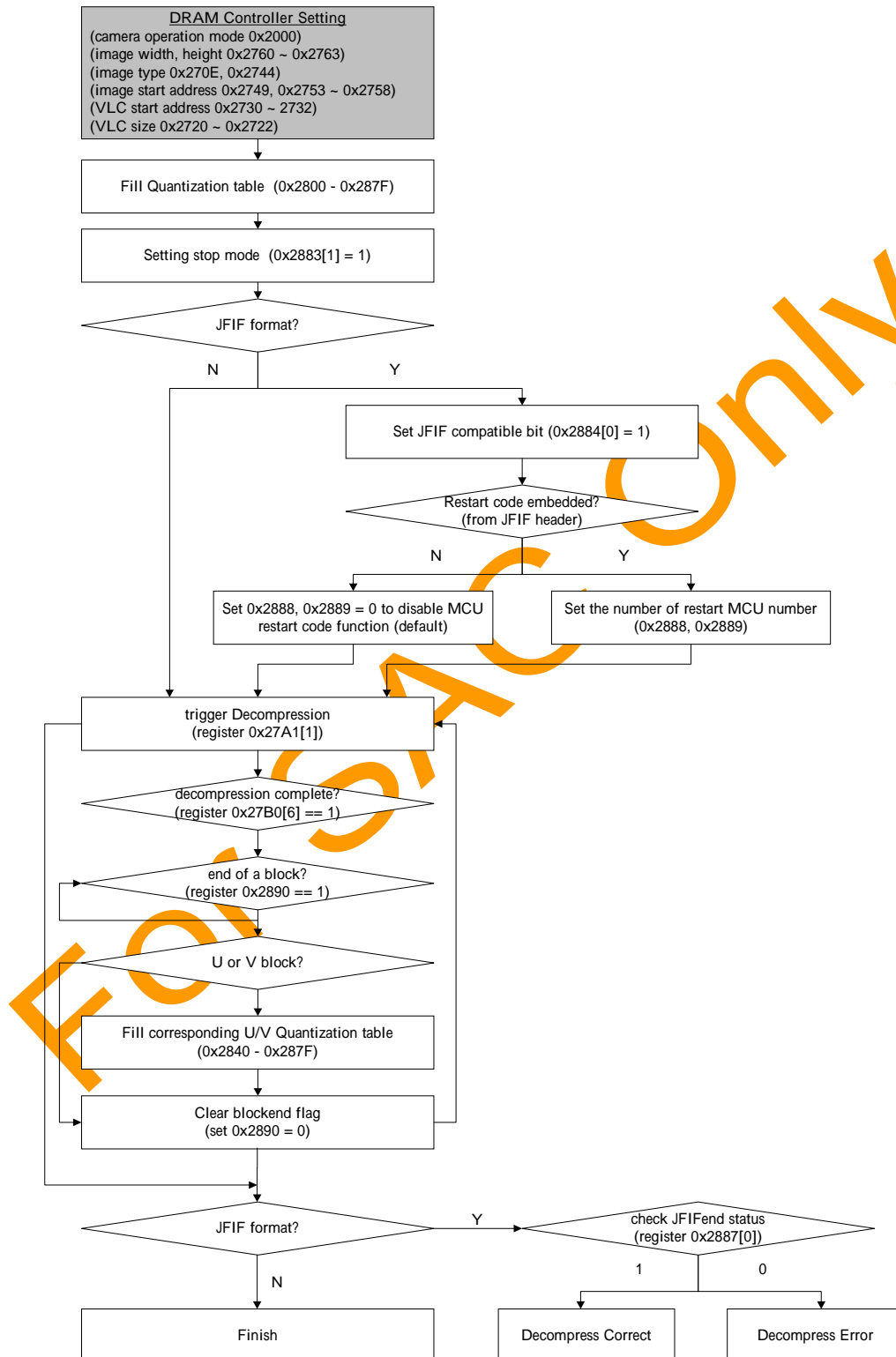
The only way to check if the decompression is done without any error is checking the data size of the VLC data stream. If a file is decompressed without any error, the total number of bits in the VLC data stream is the exact data size needed to recover the whole image. The SPCA533A provides a flag *JFIFend* in register 0x2887[0] to check if there're extra bits left in the VLC buffer after the decoding is done. After the decompression is done, the *JFIFend* flag will be set if the EOI marker presents.

As the SPCA533A only embeds two quantization tables, the U/V components share the same table. This is enough for most applications. If the users are going to decode a file with different quantization table for U and V component, the decompression task could be paused whenever each block (8x8 Y, U or V) is done. This allows the firmware to replace the quantization tables during decompression. However, this will make the decompression time longer. It is not necessary in the normal case in which U and V components share the same quantization table. Set *StopEN* bit ( register 0x2883[1]) to pause the JPEG engine while each block is done. Whenever each block is done, the *Blockend* flag (register 0x2890[0]) will be set. After the quantization table is prepared, clear this flag to continue the decompress flow until the end of next block.

The following flow chart are the control flow of JPEG decompression without stop and JPEG decompression in stop mode.



If Y,U,V use different Q-table, the JPEG engine stops in the end of each block by setting the stopen bit (register 0x2883[1]). Here is the flow chart.



### 1.7 USB bus interface

The SPCA533A implements ten USB endpoints. The main features of the endpoints are described in the following table.

Interface	Endpoint	Type	Function
NA	0	Control	Handles standard and vendor command data
0	1	Iso-in	Transmits video image to the host
1	2	Bulk-in	Transmits data to the host
1	3	Bulk-out	Receives data from the host
1	4	Interrupt-in	Transmits event data to the host
2	5	Interrupt-in	Transmits audio events to the host
3	6	Iso-in	Transmit audio data to the host
4	7	Bulk-in	Transmits data to the host
4	8	Bulk-out	Receives data from the host
4	9	Interrupt-in	Transmits event data to the host

#### 1.7.1 USB Vendor Command

In the SPCA533, all standard commands but Get-Descriptor are processed by hardware state machine. For Get-Descriptor and the vendor command, the embedded USB controller latches the 8-byte data in the SETUP packet and then interrupts the CPU. After being interrupted, the CPU reads the 8-byte data, interprets it, and executes the command or prepares the appropriate data if necessary.

USB Vendor Command for Register Read/Write (example)

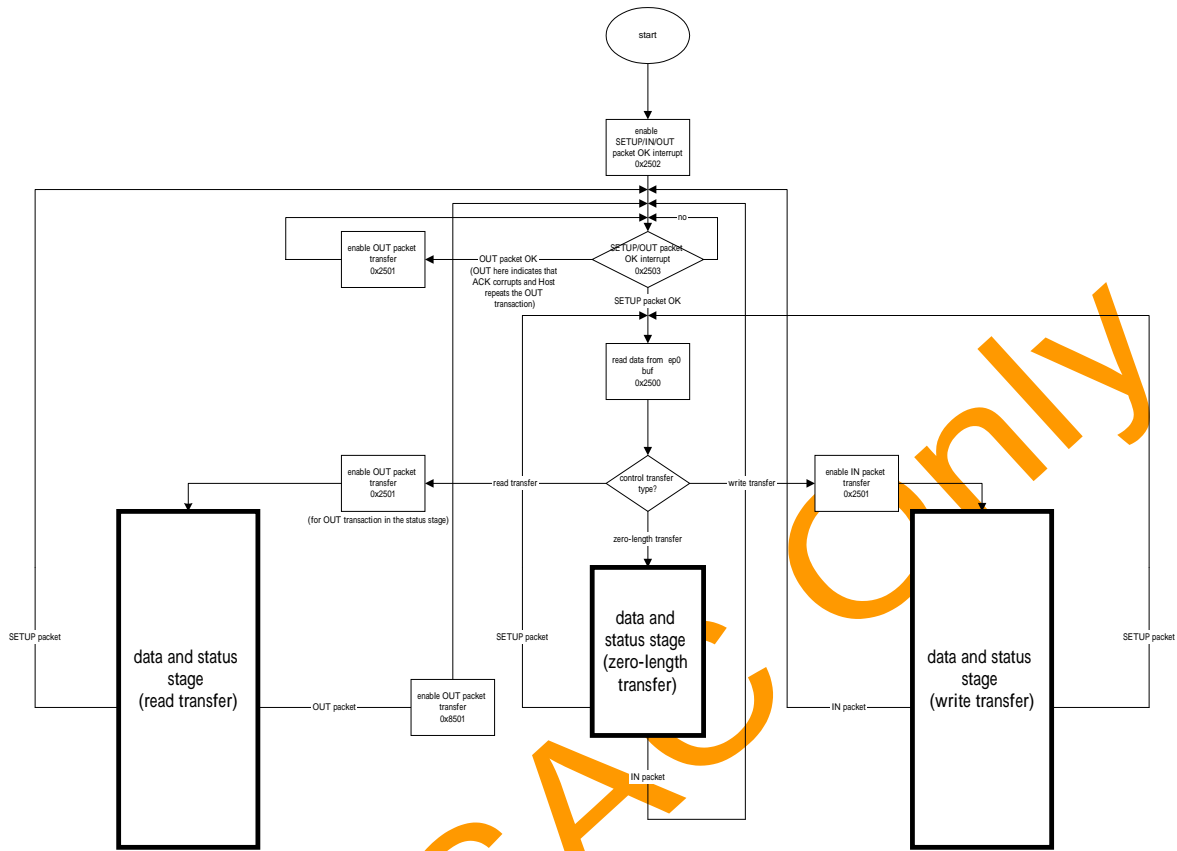
Command	BmReqType	BRequest	WValue	WIndex	Wlength
Read	0Xc0	0X00	Reserved	address	1
Write	0X40	0X00	High byte: reserved Low byte: write value	address	0

USB Vendor Command for Image Upload (example)

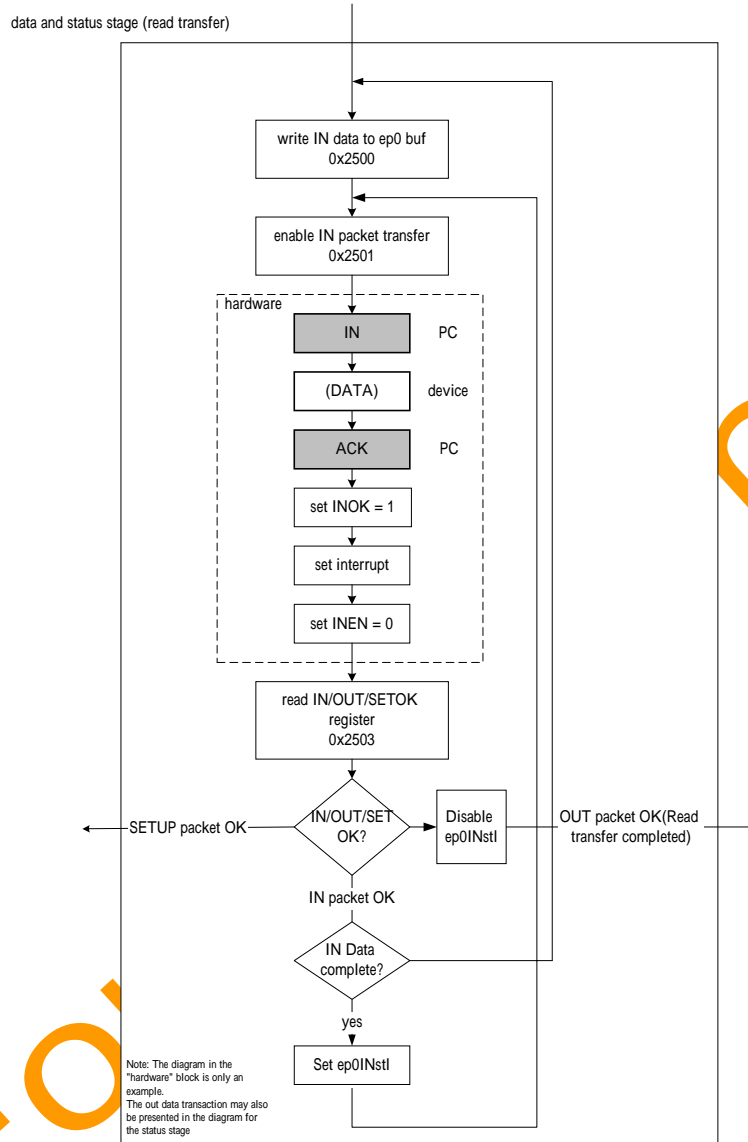
Command	BmReqType	Brequest	WValue	Windex	Wlength
get thumbnail	0X40	0X01	Image index	0X0000	0X0000
get image	0X40	0X01	Image index	0X0001	0X0000
get FAT	0X40	0X01	Reserved	0X0002	0X0000
get status	0Xc0	0X01	Reserved	0X0003	0X0001

The vendor commands may presents Data-in, Data-out or just the response phase. The flowing diagram shows the control flow for all type of transfers for Vendor Commands:





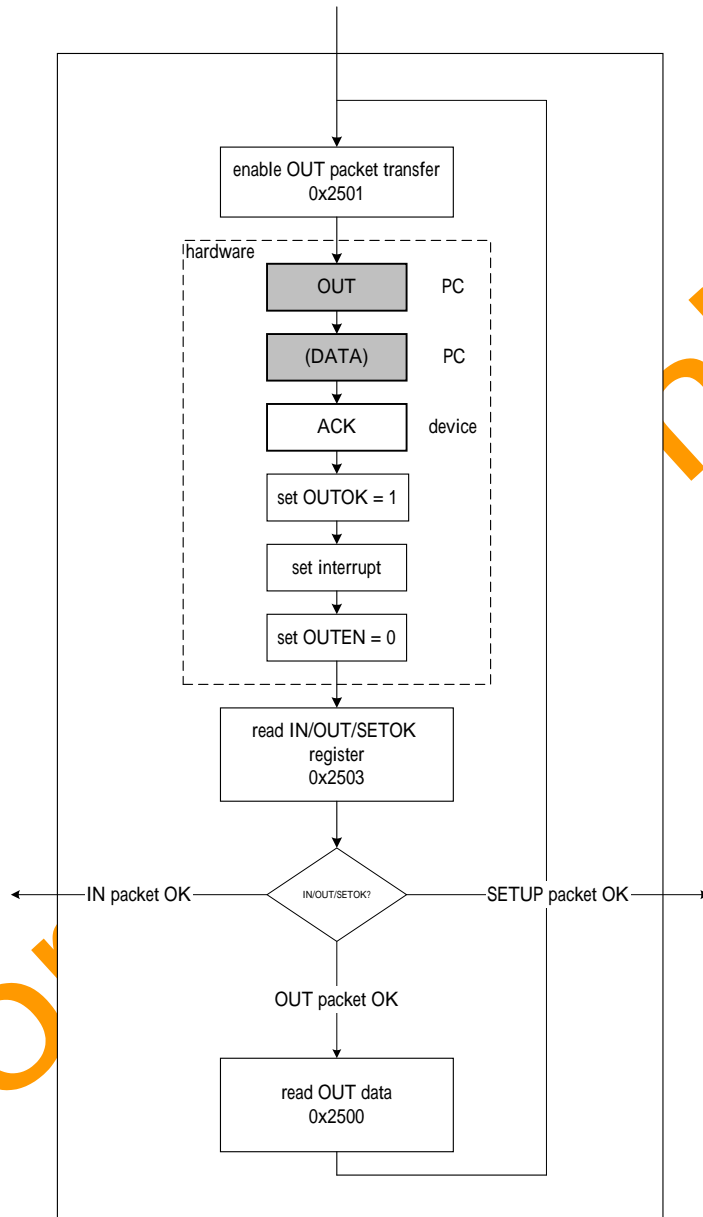
For Sale Only



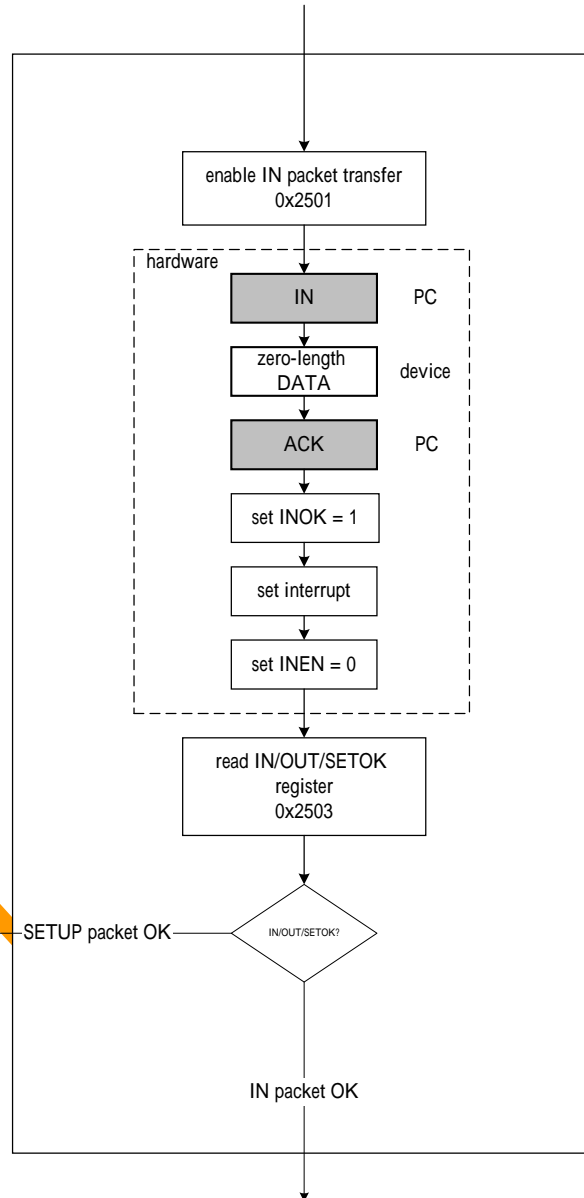
FO

nly

data and status stage (write transfer)



data and status stage (zero-length transfer)



## 1.7.2 USB Packet Format

### 1.7.2.1 USB Video Iso-in Packet (endpoint 1)

For the video Iso-in endpoint, the host may issue standard commands to change its maximum packet size. To achieve the optimal system performance, the user should adjust the alternative interface setting based on the image size and compression rate. The SPCA533A supports the following alternative settings for the Iso-in pipe.

Alternative Interface Setting	Maximum Packet Size (bytes)
0	0
1	128
2	384
3	512
4	640
5	768
6	896
7	1023

The SPCA533A transmits the video isochronous packets with the full-size (maximum packet size) when the VidFulPktEn register is set to 1. When there is not sufficient data to construct a full-size packet, the SPCA533A sends a zero-length data packet. The video Iso packets are divided into two types: SOF (start of frame) packet and normal image packet. When VidFulPktEn register is cleared, short packets are sent and no stuffing zero is applied to the end of the packets.

#### 1.7.2.2 USB BULK-IN Packet (endpoint 2, 7)

The maximum packet size is fixed at 64 bytes. Short packets transmission and STALL response for the pipe are supported.

#### 1.7.2.3 USB BULK-OUT Packet (endpoint 3, 8)

The maximum packet size is fixed at 64 bytes. Short packets transmission and STALL response for the pipe are supported.

#### 1.7.2.4 USB Interrupt-IN Packet (endpoint 4, 9)

The maximum packet size is fixed at 64 bytes. Short packets transmission and STALL response for the pipe are supported.

#### 1.7.2.5 Audio INTERRUPT-IN pipe (endpoint 5)

The maximum packet size is fixed at two bytes. The CPU should program the AudIntDataL/AudIntDataH registers (register 0x2504 and 0x2505) after it detects a new event. The USB controller sends the interrupt data to the host only after AudIntDataH register 0x2505 is written.

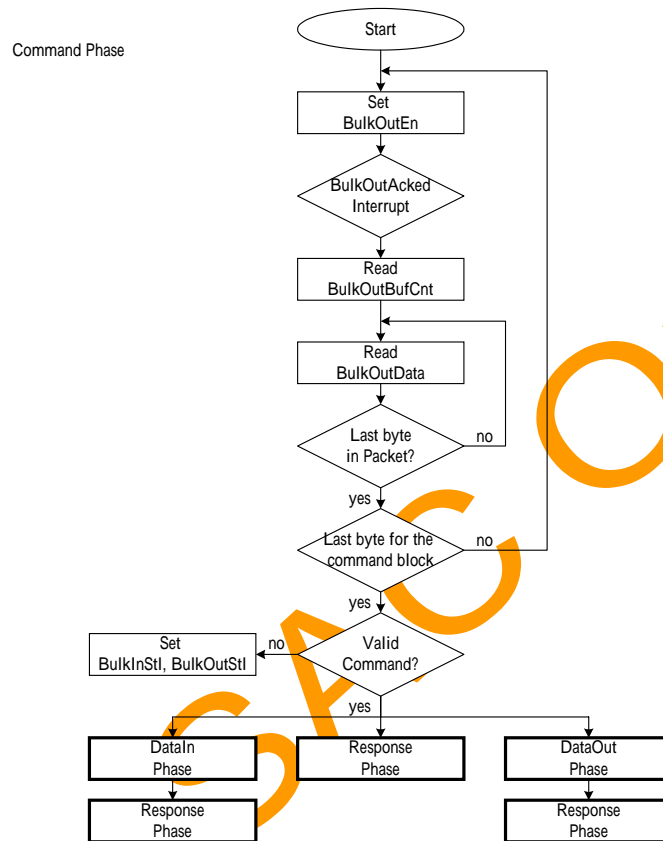
#### 1.7.2.6 Audio ISO-IN Pipe (endpoint 6)

For the audio Iso-in pipe, the host may issue standard commands to change its maximum packet size. The following table shows the maximum packet sizes for the available alternative interface settings.

Alternative Interface Setting	Maximum Packet Size (bytes)
0	0
1	16
2	32
3	48
4	64
5	80
6	96
7	112
8	128
9	144
10	160
11	176
12	192
13	208
14	256
15	512

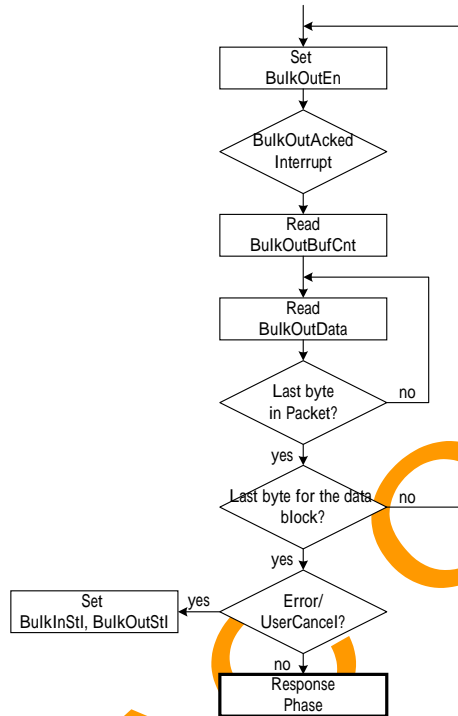
### 1.7.3 Bulk-Only Protocol Support

The SPCA533A supports Bulk-Only protocol used in MSDC and SIDC. In the command phase, Bulk-out pipe should be enabled. The CPU reads the data in the Bulk-out buffer and decodes the command. The sequence is shown as follows:



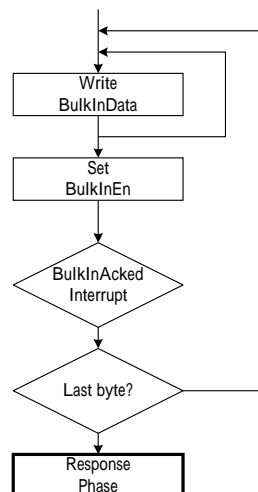
If the command is an unknown command, the Bulk-out and Bulk-in pipes can be stalled by setting the BulkInStl/BulkOutStl registers. If the command is otherwise an OUT command, the host sends data to the SPCA533A and there exists a data out phase. In the data out phase, the CPU reads data in the Bulk-out buffer. The Bulk-out buffer data can also be moved to some other buffers by the DMA mechanism. Note that the DMA source (DMAUUSBSrc register 0x2510) should be specified when the DMA function is applied.

DataOut Phase



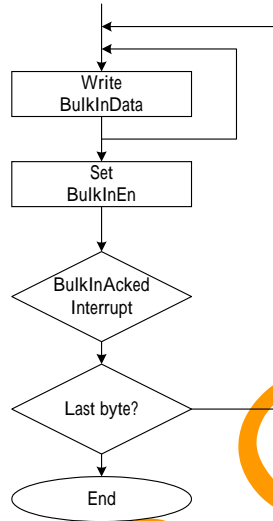
If the command is instead an in command, the CPU should writes data in the Bulk-in buffer and enable the Bulk-in pipe. The BulkInAked interrupt indicates the data has been successfully transmitted to the host. As well as for the Bulk-out pipe, the DMA mechanism can be applied here to move data to the Bulk-in buffer. Still note that DMAUSBDst should be specified.

DataIn Phase



In the response phase, the CPU writes the response data to the Bulk-in buffer and enable the Bulk-in pipe. The BulkInAked interrupt indicates the host has successfully received the response and sent an ACK packet to SPCA533. For unknown commands, a response phase would be presented after the standard Clear-Feature command and thus the stall condition can be cleared in the response phase.

Response Phase



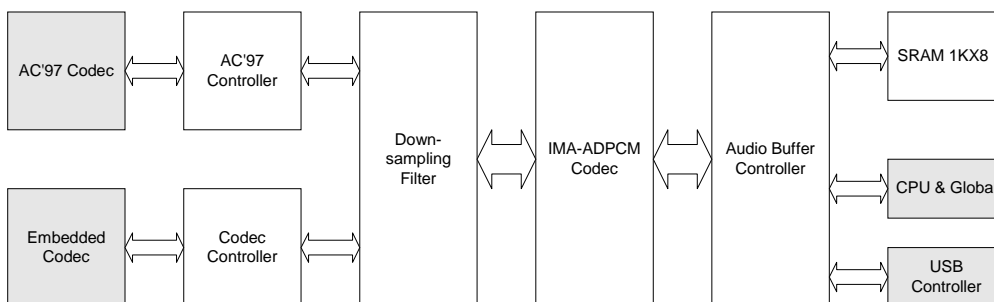
#### 1.7.4 Waking up the camera by the USB plug in/out

While the device is in suspend state, it is possible to wake up the camera by plugging-in (or plugging-out) the USB connector to (from) the PC. The wakeup procedure is exactly the same as any GPIO that wakes up the camera. Since all the GPIO pins of SPCA533A are able to wake up the device, the application may connect any of the GPIO to the USB power for waking up the device. Every time when the USB plug is connected to (or disconnected from) the PC (or USB hub), the GPIO pin will generate an interrupt that wakes up the device. Note that the corresponding interrupt enable bit must be set and the *UIRSMINT* bit must also be set.

#### 1.8 Audio function

The audio module provides audio record and playback functions in DSC mode as well as audio stream to USB in PC-camera mode. The audio module supports both AC'97 codec and an embedded codec interfaces for the audio record/playback and stream functions. The audio module also provides an SPCA751 interface for MP3 playing and recording. Moreover, a down-sampling filter and an IMA-ADPCM codec are included in the audio module to reduce the data rate.

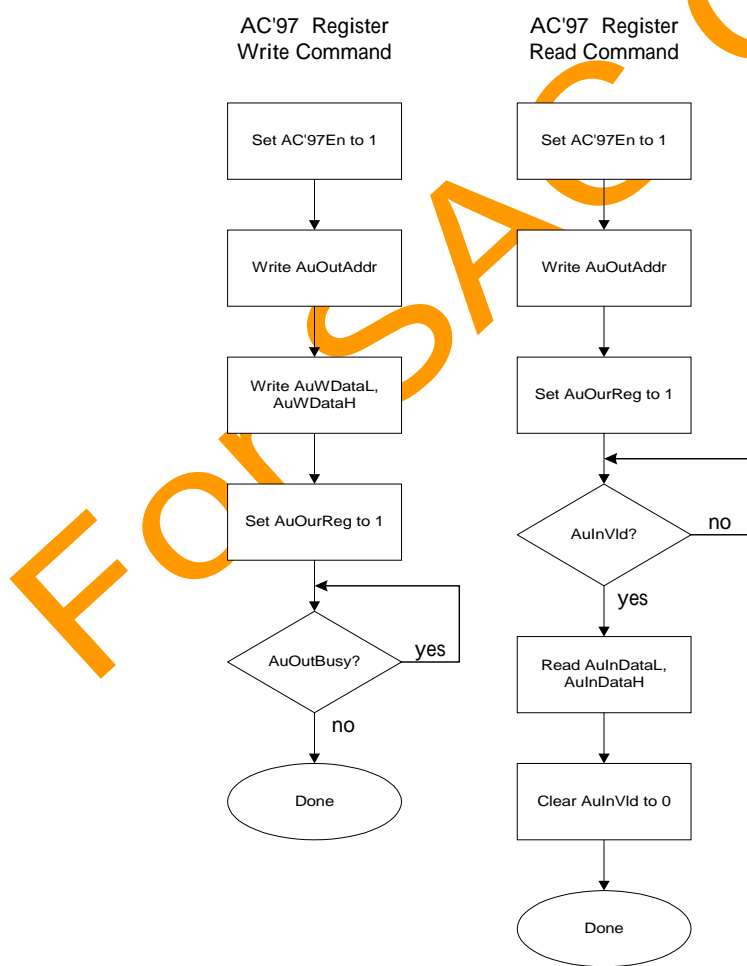
The following diagram illustrates the major blocks in the audio module. The AC '97 controller handles the interface with the AC '97 codec. The codec controller provides control signals to the codec and receives/transmits audio data. The down-sampling filter downsamples data to 1/2 or 1/6 data rate. The IMA-ADPCM codec implements the standard IMA-ADPCM algorithm and reduce the audio data to one-fourth of its original size. The audio buffer controller controls different data paths for the audio data buffer.





### 1.8.1 AC '97 Controller

The AC'97 controller is fully compatible with the AC'97 specification. It provides a digital interface (AC-link) to access an AC'97 codec. The AC-link is a bi-directional, fixed rate, serial PCM digital stream. It handles multiple input and output audio streams, as well as control register accesses. The audio stream format can be programmed to be as stereo or mono with 8-bit or 16-bit PCM precision. The diagram shown below depicts the control flow to access registers of the AC '97 codec. DO select the correct multiplexed pins by setting the corresponding global registers before any further action. The write command provides write function to the AC'97 registers while the read command provides the read counterpart. For write commands, set AC97En to 1 to enable the AC '97 controller. Write the desired AC '97 register address and data in the AuOutAddr and AuWData(L and H) registers respectively. Write 1 to the AuOutReg, then, to trigger the outgoing process in the next AC-link frame. AuOutBusy is then polled to check whether the data has been written to the AC'97 codec. In the AC-link interface, the command can be either write or read, as determined by the MSB of the register address specified. Thus write the desired AC '97 register address to the AuOutAddr with 1 for the MSB when reading the register value from the AC '97 codec. Write 1 to the AuOutReg as in the write command. Check the AuInVld, then, to see if the register data has been stored in the AuInData(L and H) register. Remember to clear AuInVld to 0 after you read the AuInData. Any further register data from the AC '97 would be blocked if the AuInVld remains 1.



### 1.8.2 Codec Controller

The Codec controller collects the 8-bit audio data from/to the embedded codec. The sampling rate/ playback rate for the codec can be 8KHz, 24KHz, 44.1KHz and 48KHz. To enable the ADC, write 0 to ADCceb and 1 to ADCshe, ADCcage and ADCade.

### 1.8.3 Down-sampling Filter

The down-sampling filter provides two down-sample modes: 2-times and 6-times. Low pass filters are used to avoid aliasing errors. The low-pass filter gain is  $15/16$ ,  $(15/16)^2$  for 2-times and 6-times down-sampling respectively.

### 1.8.4 ADPCM Codec

The ADPCM Codec implements the standard IMA-ADPCM algorithm. The encoder encodes a stream of data into a series of pages (or packets). Each page contains a 4-byte header with state information and a series of 4-bit compressed samples (as depicted in the following table). Each 4-bit value encodes the differences between two successive 16-bit uncompressed audio data. The decoder decodes pages of compressed data into a series of 16-bit PCM audio data.

Two page modes are supported. For 512-byte page mode, one single page accounts for 1017 data samples (one sample in the header and 1016 samples in the remaining 508 bytes of compressed data) while 505 samples for 256-byte mode.

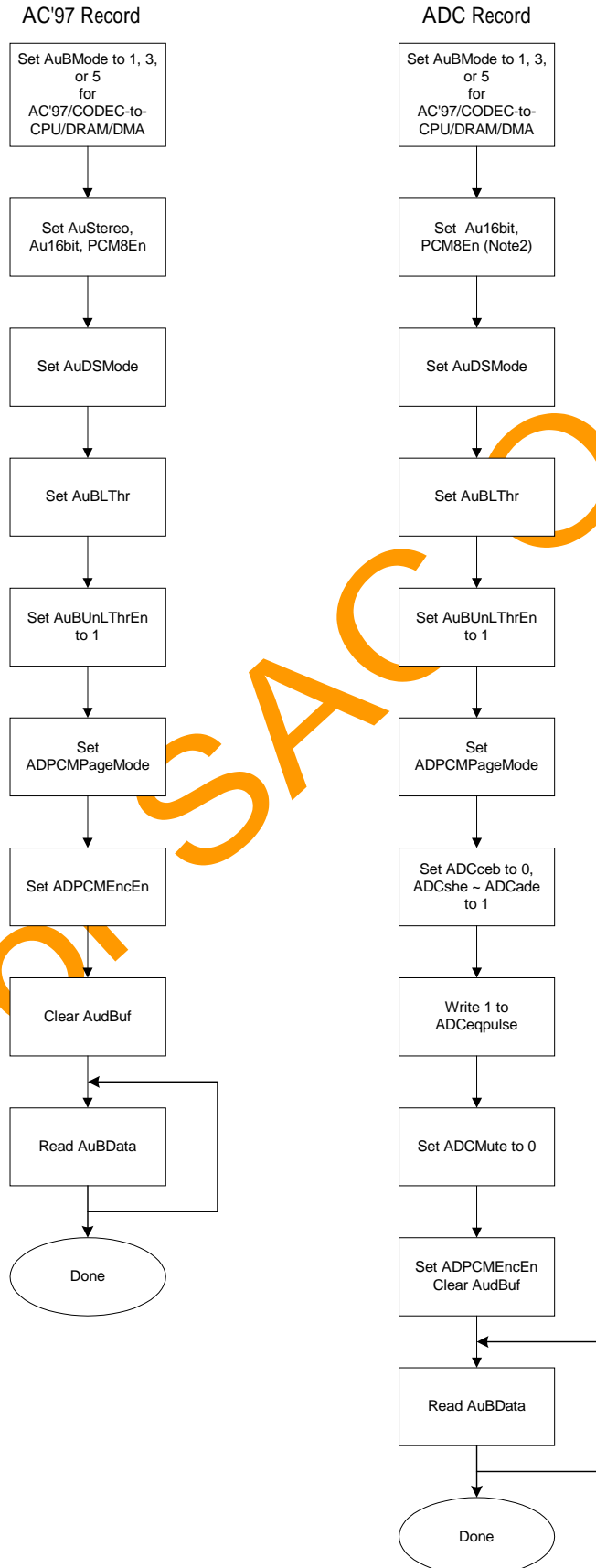
Header Bytes				Compressed Data Bytes				
byte0	byte1	byte2	byte3	byte4	byte5	...	byte510	byte511
sample0 (low byte)	sample0 (high byte)	index	0	encoded data for sample 1 & 2	encoded data for sample 3 & 4		encoded data for sample 1014 & 1015	encoded data for sample 1016 & 1017

**Note.** the table illustrates a page in the 512-byte page mode

### 1.8.5 Audio Buffer Controller

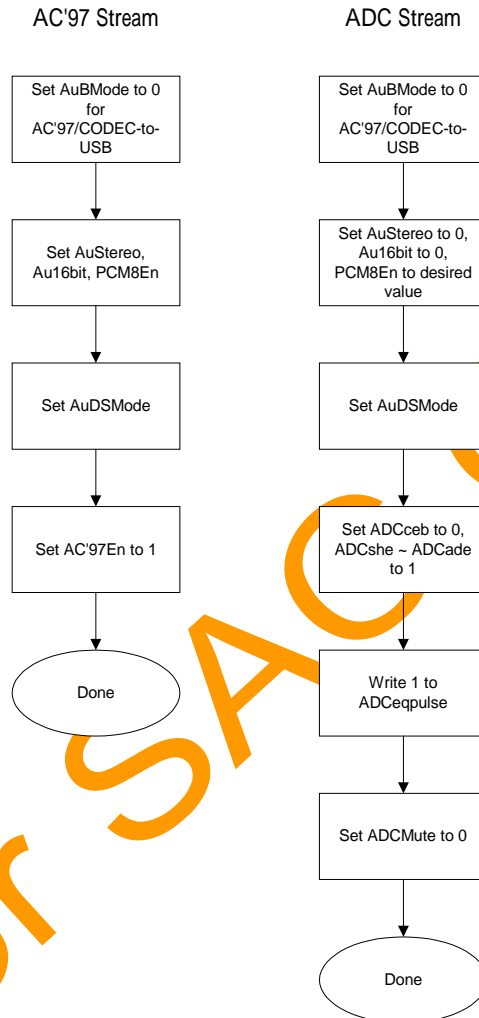
The audio buffer controller handles seven different data paths for the audio buffer: AC'97/CODEC-to-CPU(record), AC'97/CODEC-to-USB(stream) and CPU-to-AC'97/CODEC(playback), AC'97/CODEC-to-DMA(record), AC'97/CODEC-to-DRAM(record), DRAM-to-AC'97/CODEC(playback) and DMA-to-AC'97/CODEC(playback). or the record function, the audio data is written to the audio buffer by the AC'97/CODEC controller and then read out by CPU/DRAM/DMA. The corresponding control flow is shown below. If an AC'97 codec is used, set AuBMode(audio buffer mode) to 1, 3 or 5 first to select the AC'97/CODEC-to-CPU/DRAM/DMA data path. Set AuStereo, Au16bit and PCM8En to the desired value. Set AuDSMode(down-sampling mode) to the desired down-sampling ratio. Set AuBLThr(audio buffer low threshold) for a low threshold interrupt. This helps CPU control the amount of data in the audio buffer. If ADPCM codec is used, set ADPCMPageMode to 256bytes/page or 512bytes/page. The last but not the least, set AC'97En and ADPCMEncEn(ADPCM encoder enable) to enable the whole function. CPU is now responsible for reading the data in the audio buffer. It can keep reading the buffer until the AuBUUnLThr(under low threshold) interrupt is invoked.

The control flow of the ADC record function is basically the same as the AC'97 record. Yet, the embedded ADC needs a few more steps when starting to function. DO set ADCceb to 0 and ADCshe – ADCade to 1 to configure the ADC. Unmute the ADC by setting ADCMute to 0. Note that if ADPCM codec is used, set the Au16bit to 1 since the ADPCM codec converts only the 16bit data.

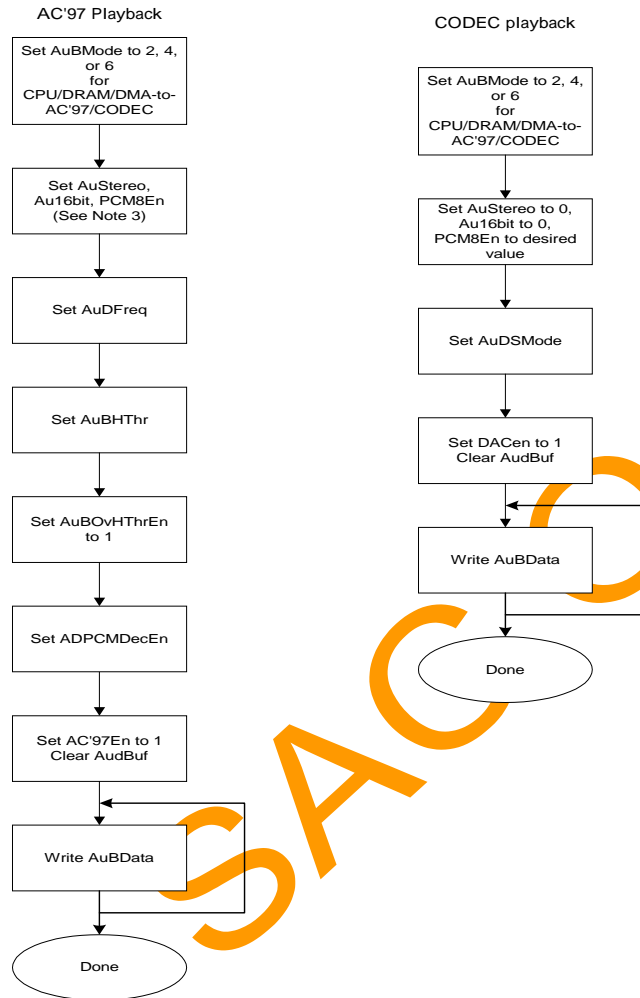


FOR SAC ONLY

The diagram below illustrates the control flow of AC'97 and ADC stream (data path AC'97/CODEC-to-USB) function. The major steps are identical with that of the record function except that the USB controller here reads the audio buffer automatically.



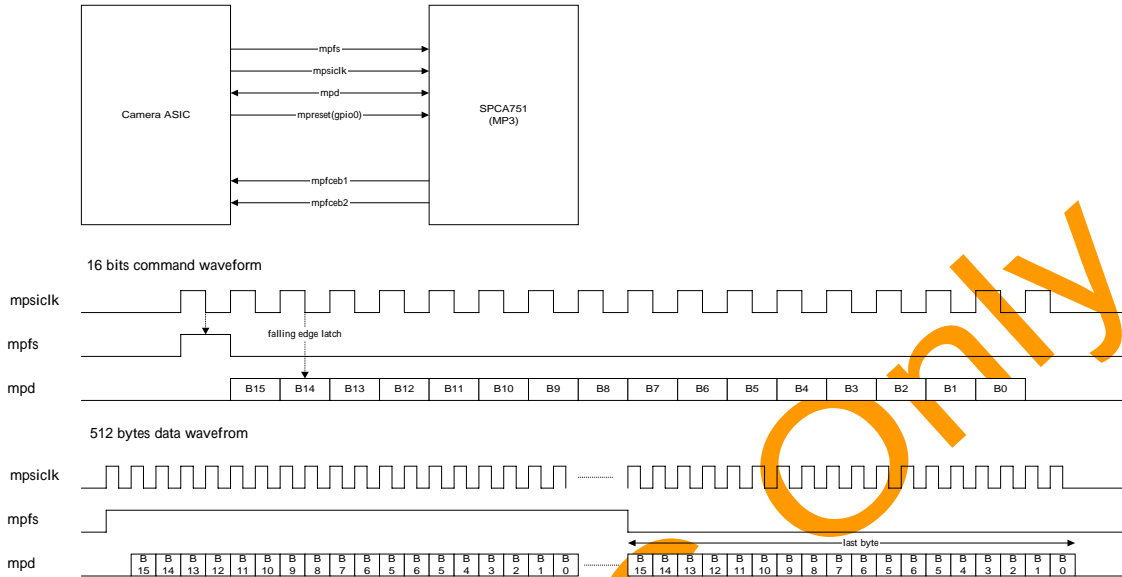
To enable the playback function, set AuBMode to 2, 4 or 6 for data path CPU/DRAM/DMA-to-AC'97. Set AuStereo, Au16bit and PCM8En to the desired value. Set AuDFreq to select the playback frequency. Set AuBHThr (audio buffer high threshold) and AuBOvHThrEn (over high threshold enable) to enable the interrupt function when the amount of data in the audio buffer is over the high threshold. If ADPCM decoder is used, set the ADPCMPageMode and ADPCMDecEn (ADPCM decoder enable). Set AC'97En at last to enable the function. The CPU/DRAM/DMA is now responsible for writing data (uncompressed or compressed) to the audio buffer. It can keep writing until the AuBOvHThr interrupt is detected.



### 1.8.6 MP3 Processor Interface

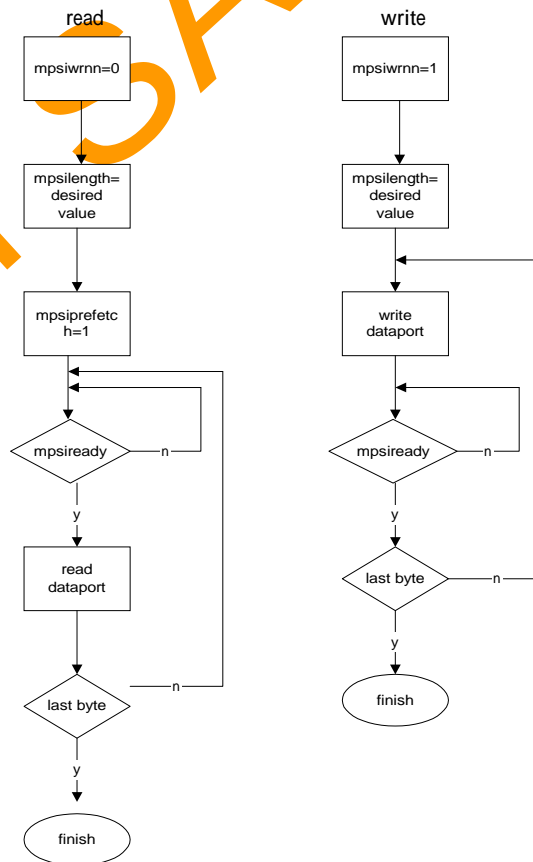
The audio module has a serial interface to communicate with SPCA751. SPCA751 is an MP3 processor. It also supports audio recording and compression. Integrating SPCA751 results in a complete MP3 player and a digital recorder. While operating as an MP3 player, the audio module fetches the MP3 bit stream from the flash memory and send it to the SPCA751 for playback. While operating as a digital recorder, the SPCA751 records and compresses the audio data and sends the data to audio module. Then, the audio module stores the compressed audio data into the flash memory. Both of the operation is done via the serial interface. In both cases, the audio module acts as a master. It sends commands , and data if necessary, to the SPCA751. It also requests data from the SPCA751.

The following diagram shows how the audio module communicates with SPCA751. Each data transaction to the SPCA751 starts with a TX frame sync signal (mptxf), and the de-assertion of the frame sync signal indicates the transfer of the last word. Each data transaction from the SPCA751A starts with an RX frame sync (mprxf), and the signal is de-asserted at the last word of data transfer. Notes that the communication to SPCA751 is based on word unit. The serial clock is driven by the audio module. Both the audio module and SPCA751 sample the data at the falling edge of the serial clock.



### 1.8.7 Programming flow of the MP3 processor serial interface

Communication with the MP3 processor



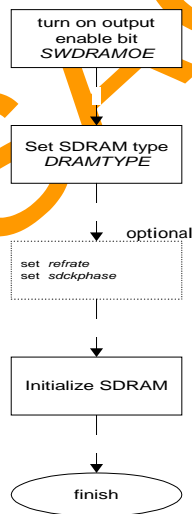
### 1.9 SDRAM controller

The SPCA533A supports 16M bits, 64M bits, 128M bits and 256M bits SDRAM. The following table shows the SDRAM configuration. Note the type of SDRAM must be set before SDRAM initialization. The functions of MA[14:11] are different according to the type of SDRAM chosen. While using two 16M bits SDRAM, the first and second SDRAM have their own *DQM* control signals.

Dramtype[1:0]		MA[11]	MA[12]	MA[13]	MA[14]
0	16M bits x 1	BA	NA	NA	X
	16M bits x 2	BA	LDQM1	UDQM1	X
1	64M bits x 1, 4 banks		BA0	BA1	X
2	128M bits x 1, 4 banks		BA0	BA1	X
3	256M bits x1, 4 banks			BA0	BA1

#### 1.9.1 SDRAM initialization

The SDRAM must be initialized before it can be accessed. The SDRAM initialization needs only to be performed once after the SPCA533A is powered on. The SPCA533A issues the *MRS* command to the SDRAM to initialize the SDRAM. After the SDRAM initialization, the SDRAM is operated at 48MHz clock, the *CAS latency* is fixed at two. The SPCA533A access the SDRAM in full-page linear address increment burst mode. The phase of the clock supplied to the SDRAM is programmable. This is necessary to compensate the trace delay on the application circuit board. The refresh rate is also programmable. The following is the control flow to initialize the SDRAM. Note that the output enables of the SDRAM control signals must be turned on before initializing the SDRAM.



#### 1.9.2 SDRAM refresh

To optimize the bandwidth allocation, the SPCA533A refreshes the SDRAM at the blanking period of image lines. It is possible to select the blanking period of the sensor or the blanking period of the LCD(TV) output. In the preview (or video clip) mode when the sensor interface is turned on, the SDRAM refresh cycles should be executed in the blanking period of the sensor (set *refsrc* register 0X2717 to 0). In the playback mode, the SDRAM refresh should be executed in the blanking period of the LCD (TV) because the sensor interface may be turned off to conserved power(set *refsrc* register 0X2717 to 1). If both the sensor interface and the LCD/TV interface are turned off, the SDRAM controller should refresh the SDRAM based on its internal counter(set *refsrc* register 0X2717 to 2).

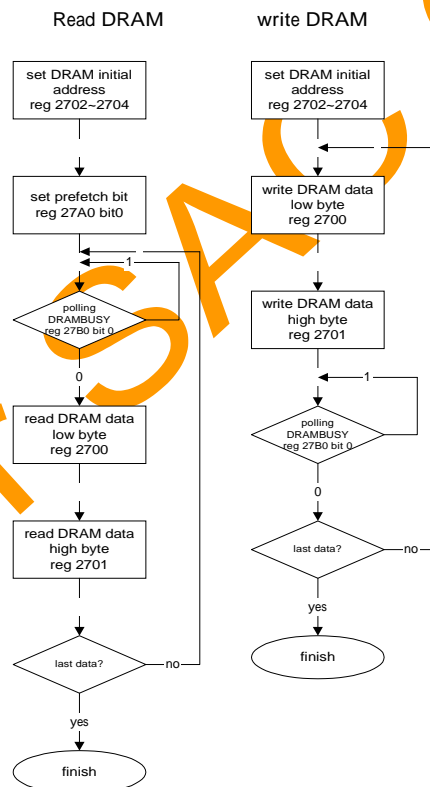
The refresh rate is also an important factor in the SDRAM operation. If the refresh cycle is based on the blanking period of the sensor (or the display device), the refresh rate will change according to the frame rate of the sensor(or display device). In the default setting, the SPCA533A refreshes the SDRAM 7 times for each blanking period. If the sensor (or display device) is operated at the nominal 30 fps frame rate, the default refresh rate is 3.2K cycles per 64ms, which is enough for some SDRAM types. The user could change the number of refresh

cycles for each horizontal blanking by setting the register 0X270a if default setting is not enough. Note if the operating frequency of the sensor (or display devices) change, the SPCA533A also needs to change the number of refresh cycles for each image line. If the refresh cycle is based on the SDRAM controller built-in counter, the refresh rate is 34K cycles per 64ms.

The SPCA533A can also issue a *SELF-REFRESH* command to the SDRAM. By doing so, the SDRAM will generate refresh cycles internally. The SPCA533A drives all the SDRAM control pins to 0. To enter this mode, set register *srefresh* (0X2708) to 1. This function is generally applied in the camera suspend mode to conserve power. Note that the power of SPCA533A should not be cut off if the data in the SDRAM is to be maintained. Since cutting off the power will make the SDRAM control pins floating and that will drive the SDRAM into unknown state. Self-refresh is only needed when the SDRAM is chosen to store the data. For the system with non-volatile storage media, the SDRAM may be powered-off in suspend state in order to conserve power.

### 1.9.3 CPU access SDRAM

The SPCA533A allows the CPU to access the content of any address in the SDRAM via an indirect-addressing approach. Since the SDRAM is shared between the other internal modules, the CPU access SDRAM is not real time. The CPU must poll the "DRAMBUSY" status bit to determine whether the access has completed or not. The flowcharts below shows the SDRAM read and write via indirect-addressing.



Each access to the SDRAM, both read and write, is based on a word (16 bits) unit. Register 0X2700 is the low byte data port and register 0X2701 is the high byte data port. The maximum length of the address is 24-bit which yields to a 16M words SDRAM space. The address register, register 0X2702 ~ register 0X2704, must be filled before each access. After each read/write from/to the high byte data port, the address register will be incremented automatically. So the CPU needs only to set the address once (the initial address) for accessing a consecutive section of SDRAM space.

For SDRAM-write operation, the SDRAM controller utilizes a post-write mechanism. The data is written to the SDRAM after the high byte data port is written. The CPU must poll the "DRAMBUSY" status bit to see if the post-write is completed.

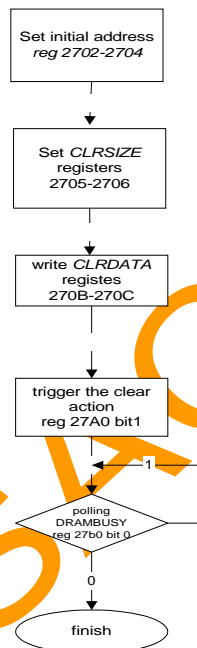
For SDRAM-read operation, The CPU must set the "pre-fetch" control bit to trigger the first word read cycle. After the high byte data port is read, the next word is automatically pre-fetched (with the incremented address). So the CPU must polling the "DRAMBUSY" bit to see if the next word pre-fetch operation is completed.



#### 1.9.4 Filling constant data to the SDRAM

The SPCA533A provides a fast operation to fill a constant value to the SDRAM. The address of the SDRAM to be filled must be continuous. Only the initial address and the size of the SDRAM need to be specified. This hardware operation is much faster than filling the data by firmware word by word. The following is the flow control. In the diagram below, the *CLRSIZE* represent the size to be filled which is based on the number of words. Register 0X270B specifies the low bytes of the constant and register 0X270C specifies the high bytes of the constant.

Fill constant value to the SDRAM



#### 1.9.5 Interface with DMA controller

The data stored in the SDRAM can be moved to the other internal module of the SPCA533A by the DMA controller. The DMA control flow is discussed in section 5.4. While most of the controls are done by the DMA controller, the SDRAM starting address must be specified before starting the DMA operation. The starting address is programmed in registers (0X2750~0X2752).

#### 1.9.6 Image data input control

The SDRAM is used as a temporary buffer during the camera operation. There are many options to control how the data is stored in the SDRAM.

**ImgType** : The image type option chose between raw data, YUV422 data, YUV420 data, compressed data and non-compressed data. Depending on the operation stage, this registers must be specified accordingly.

**CapInt** : The capture interval control. The control the input frame rate, especially in capturing the video data, the SPCA533A allows the user to change the input frame rate. The SDRAM controller will drops the unwanted frames.

**Size** : The SDRAM controller requires the user to specify the image size in both the vertical and horizontal direction. The size is specified based on the number of pixels, which must be multiples of 16. Since the JPEG engines work on 8x8 basic coding units. The size of the image must complies to this criteria.

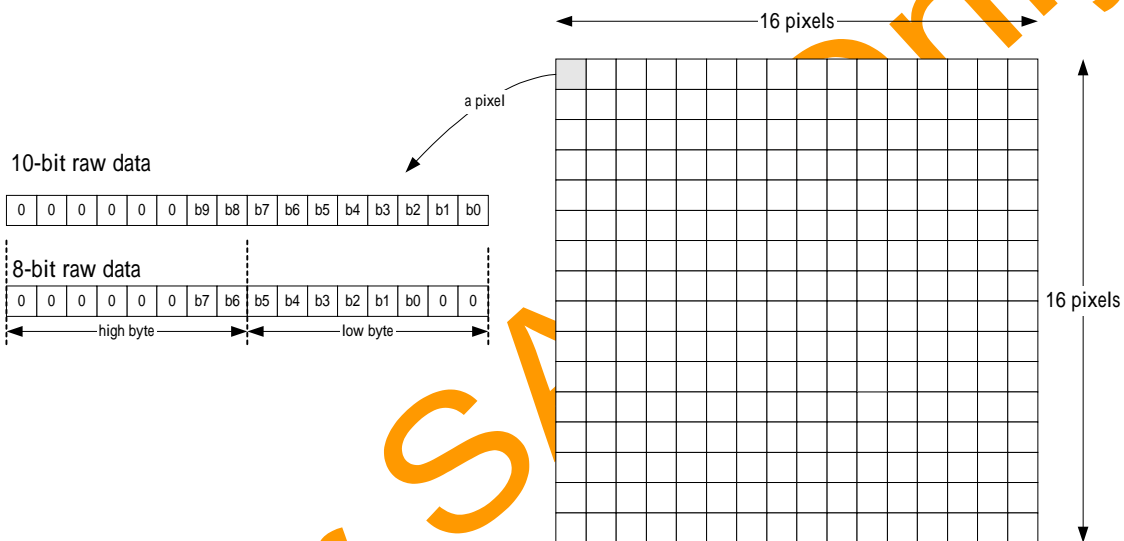
**Fieldmode**: The field mode register determines whether to re-arrange the line sequence while writing the raw data in to the SDRAM buffer. This is used in the interlaced CCD sensors. This option is only applied in the full frame raw data capture of an

interlaced CCD sensor. In PC-camera or video clip mode, the users should always select one-field mode. The SPCA533A also supports interlace-type CCD sensor operation, section 5.9.10 has more details.

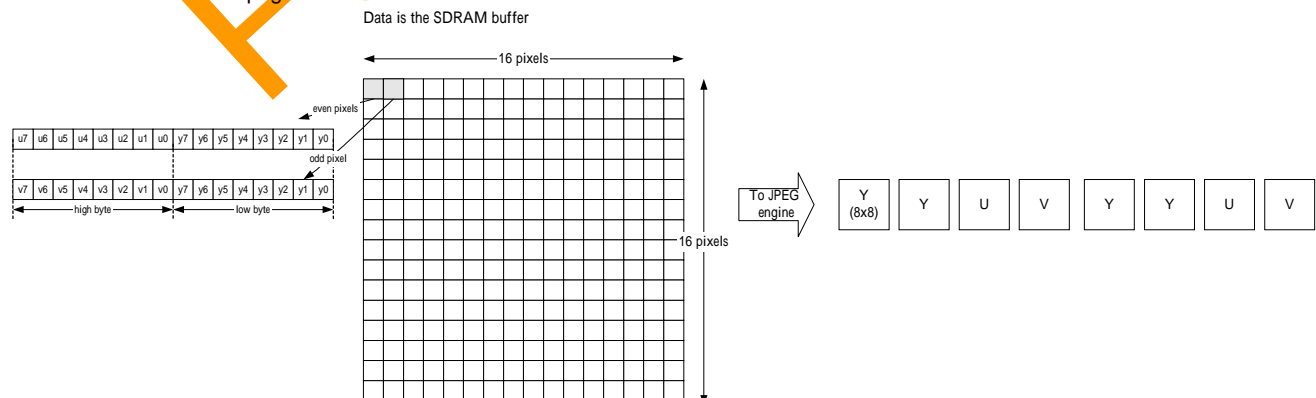
### 1.9.7 Data format

The SDRAM controller is also responsible to generate the data formats for different applications. Three basic formats are implemented in the SDRAM controller according to the data type selected. During uploading data to the PC via the USB bus or writing data to the flash memory, the data are output according to the formats.

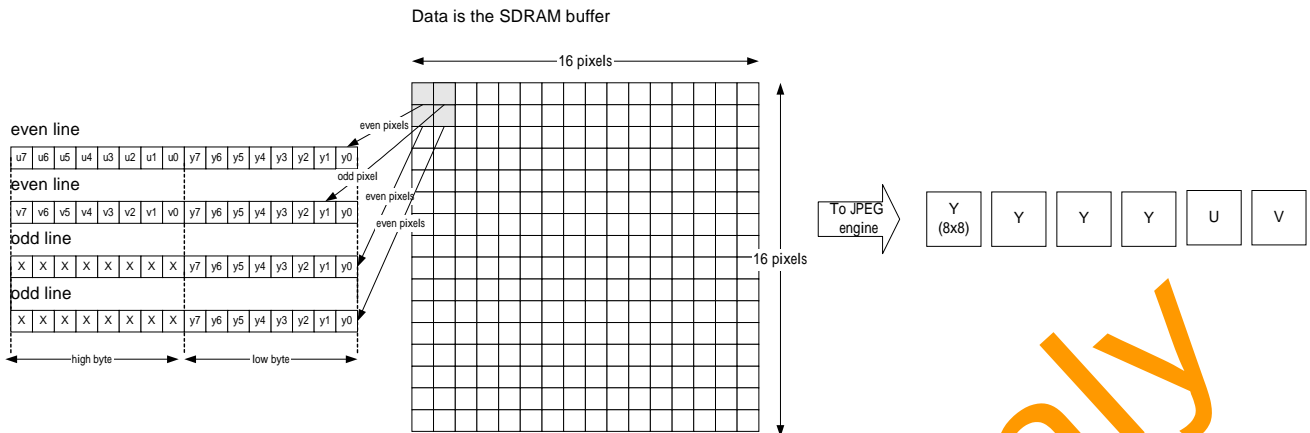
**Raw data format :** The raw data format is in the raster-scan sequence. If 10-bit raw data mode is selected, each pixel contains 2 bytes of data. The first byte is low byte raw data, the second byte is high byte raw data. There are 6 zero-bit stuffed in the MSB of the high byte. If 8-bit raw data mode is selected, each byte represents one pixel of raw data. The following diagram shows an example of a 16-pixel by 16-pixel raw data. Each pixel (for both 8-bit raw data and 10-bit raw data) occupies a word of the SDRAM.



**YUV 422 format :** The SPCA533A utilizes the standard JPEG compression algorithm. In the YUV422 format, the minimum coding unit (MCU) is consisted of two Y-blocks, one U-block and one V-block. The size of each block is 8 pixels by 8 pixels. So the data sequence sent to the JPEG engine is YYUVYYUVYYU...etc. Note that if the final data size is not multiples of the flash memory page size, The DMA controller will stuff 0's to the end of the page.



**YUV420 format :** The YUV420 format is similar to YUV422 format, except that each MCU is consisted of four Y blocks, one U block and one V block. The block sequence is YYYYUVYYYYUV...etc. The following diagram shows an example of a 16-pixel by 16-pixel YUV420 image in the SDRAM buffer. Note that in the odd lines, the UV data is not valid because in UV is subsampled in the vertical direction in the YUV420 format.



### 1.9.8 JPEG interface

While capturing a video, the SDRAM controller can automatically insert lines (or drop lines) of the image before it send the data to the JPEG engine for compression. This function is designed to adjust the vertical resolution of the incoming image because the sensors may not provides enough number of image lines in the monitor mode. For example, if the sensor provides only 238 lines in the monitor mode and a 320x240 size video is required, the DRAM controller need to automatically inserts 2 lines in every frame. Note that the horizontal resolution can be scaled by the scale-down engine built in the CSP.

Register *Vscalevsize* (0X2792 ~ 0X2793) defines the target number of lines for the SDRAM controller to send to the JPEG. Register *dramvscaleen* (0X2790[1]) controls whether to turn on this insert-line or drop-line function. Register *vscalemode* (0X2790[0]) determines whether to insert liens or drop lines. Register *vscalecnt* (0X2791) determines how many lines to be count before inserting(dropping) a line. For the above example, where the application requires to insert two lines between 238 lines of the source image, the *vscalecnt* register should be set to 118. The SDRAM controller will count 119 (118+1) lines before insert a line. This counting-inserting procedure is repeated until the target number of lines is sent to the JPEG.

The drop-line function behaves similarly as the inset-line function, except that the SDRAM controller automatically drop a line after it counts a specified number of lines.

In the playback mode, the JPEG engine is able to perform a scale down function at the same time when it decompresses an image. The scaledown function of the JPEG is based on the MCU (minimum coding unit). Normally, decompressing a MCU produces a 8x8 image block. If the JPEG scaledown function is turned on, the JPEG engine can produce image blocks of size 7x7, 6x6, 5x5,.....etc. Since the JPEG scaledown function is based on the MCU, the scale ratio can only be 1/8, 2/8, 3/8, ...7/8. Register *Pbrescale* (0X2745[2:0]) controls the scaledown ratio. If this register is set to 0, then the JPEG scaledown function is disabled. The JPEG scaledown function is usfule in the playback mode, especially when decompressing a mega-pixel image. This size of image normally requires to be scaledown further to fit the resolution of the display size. Eventhough the SDRAM controller's built-in scaling engine can be used to achieve this, it takes longer processing time. The JPEG scale down function does not take extra time when it is turned on, comparing with decompressing withouth scaling down.

For example, if a 2048x1536 image is to be decompressed and display on a 280x220 LCD panel, the *PBrescal* should be set to 2. After decompression, a 512x384(2/8 of the 1048x1536) image is generated. Then use the sclae engine to scaledown the image further, to 280x220. The execution speed is much faster than directly scale the image from 2048x1536 to 280x220.

### 1.9.9 Thumbnail generation

Thumbnail image can be generated by scaling down the original image. It usually take longer processing time. Another approach to generate thumbnail is using the DC-terams of the JPEG compression. The SPCA533A automatically collect all the DC-terms of each MCU when it compresses an image. Register *enthumb* (0X2883) determines whether to turn on this function. The size of the thumbail (generated by the DC-term collection) is 1/8 of the original image size in both the verticvl and horizontal direction. For example, compressing a 2048x1536 image will produce a thumbnail of size 256x192. The location to store this thumbnail could be specified in register *tmbstart* (0X2736~0X2738). This thumbnail can be scaled to the desired size further using the scale engine. It can also be compressed by the JPEG

engine.

### 1.9.10 Image-Processing engine

The image-processing engine embedded in the SDRAM controller performs a wide range of tasks to assist the firmware during the camera operation. Many specialized camera features can be achieved by the image-processing engine. The image-process engine also boosts the overall performance of the SPCA533. The image-process engine provides the following functions.

- (a) Image-scaling operation
- (b) Image-rotation operation
- (c) Copy & paste operation
- (d) Date-stamping operation
- (e) DRAM-to-DRAM DMA operation
- (f) bad-pixel correction
- (g) inter-frame raw data subtraction
- (h) YUV420-to-YUV422 conversion

Among the functions supported by the image-process engine, many of them operate on two image buffers. For example, the scaling function scales the image in the source image buffer and stores the result into another image buffer. There are also functions which operated on a single image buffer. For example, the bad pixel correction function. The SPCA533A defines two indices to indicate the starting address (in the SDRAM) of the source image buffer (usually image buffer A) and the target image buffer (image buffer B). The offsets of the image buffer are also defined. The offsets are useful in functions like the copy & past function, in which the copy location of the source image buffer and paste location of the target image buffer must be specified. Also the sizes of the image buffer are also defined. The size parameters are useful for the image-processing engine to calculate the SDRAM address.

The general operation flow of the image-process engine is

- 1) Select the function in register 0x2770[7:4]
- 2) Programming the starting addresses, buffer size, offsets of both source and target (if any) image buffer.
- 3) Trigger the operation by writing 1 to 0x27A1[7]
- 4) Polling the register 0x27B0[7] to check if the operation is done.

#### 1.9.10.1 Image-scaling operation

The scaling function provides both image scaling-up and scaling-down operations in the YUV422 domain. The engine performs one-dimension scaling. To scale up/down an image, the engine must be triggered twice. One for the horizontal scaling, the other for the vertical scaling. Appropriated filters are applied in the scaling function to achieve good image quality. The scaling function is usually executed after the image is captured and converted to the YUV format by the CDSP. It can be used to generate an image of the resolution the application intends or generate a 160x120 thumbnail image. The scaling function also enables the SPCA533A to do digital zoom. In the playback modes, the scaling function enables the SPCA533A to generate an image of size exactly fitting the resolution of the display devices.

While performing the scaling function, the Image buffer A always points to the source image and image buffer B always points to the target image. Both the image width and height must be a multiple of 4. The scaling factor is defined in register 0X277F and 0X2780, which is a 16 bit fractional number. For image scaling down, the scale factor represents the target-to-source image size ratio. For image scaling up, the scaling factor represents the source-to-target image size ratio. Accessing the image buffer in the vertical direction takes longer time than accessing the buffer in the horizontal direction. In the application, the firmware must reduce the data access to the image buffer in the vertical direction to speedup the scaling. The following rules must be followed.

- 1) Scaling-down: horizontal scaling first, then vertical scaling
- 2) Scaling-up: vertical scaling first, then horizontal scaling

Example of image scaling-down :

The source image size is 1600x1200, locates in the SDRAM starting from address 0x000000 to 0x1D4BFF.

The target image size is 280x220, locates in the SDRAM starting from address 0x000000 to 0x00F099.

The scaling factors:

Horizontal:  $280/1600 = 0.175$  => represented as 16-bit fraction = 11468.8 (0.175x65536)

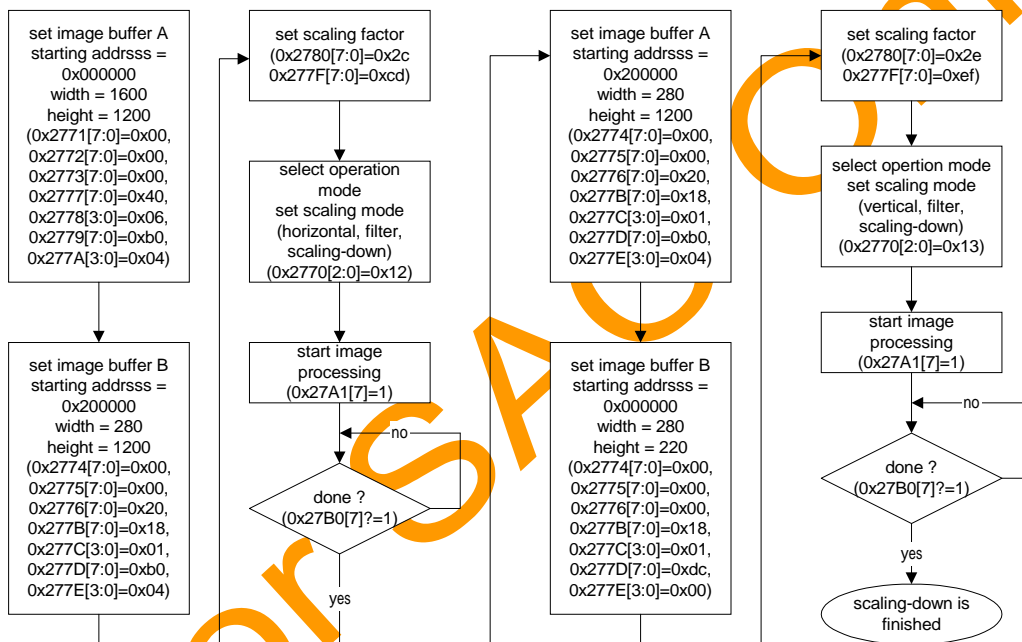
=> round up = 11469

=> represented as hexadecimal digits = 0x2CCD

Vertical:  $220/1200 = 0.183...$  => represented as 16-bit fraction = 12014.9 (0.183... x65536)

=> round up = 12015

=> represented as hexadecimal digits = 0x2EEF



scaling-down flow chart

### Example of the image scaling-up

The source image size is 160x120, locates in the SDRAM starting from address 0x000000 to 0x004AFF.

The target image size is 280x220, locates in the SDRAM starting from address 0x000000 to 0x00F099.

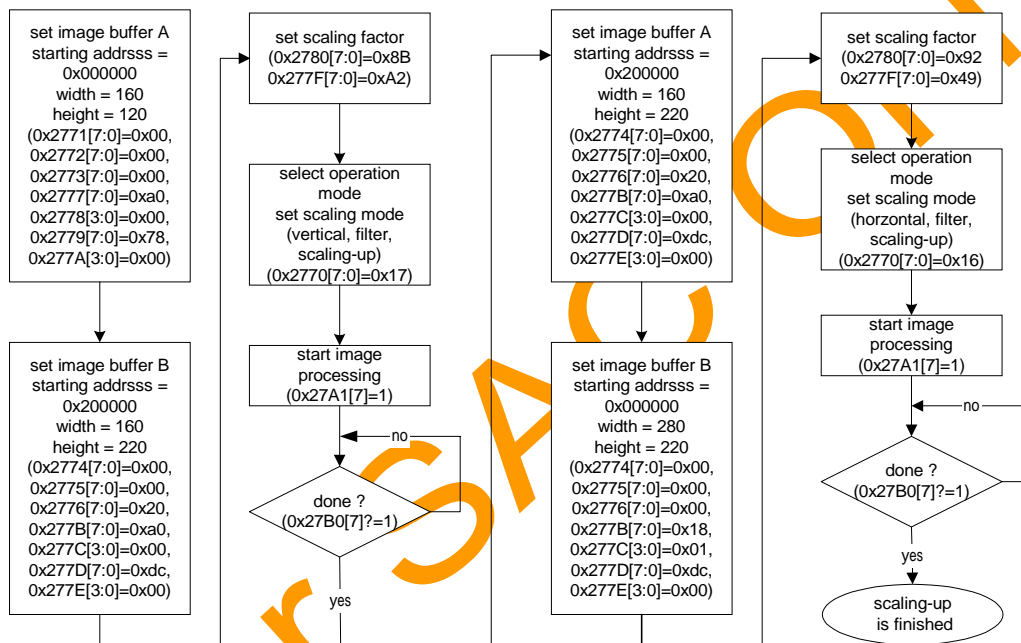
The scaling factors:

Horizontal:  $160/280 = 0.571\dots$  => represented as 16-bit fraction = 37449.1 (0.571...x65536)  
=> round down = 37449

=> represented as hexadecimal digits = 0x9249

Vertical:  $120/220 = 0.545\dots$  => represented as 16-bit fraction = 35746.9 (0.545...x65536)  
=> round down = 35746

=> represented as hexadecimal digits = 0x8BA2

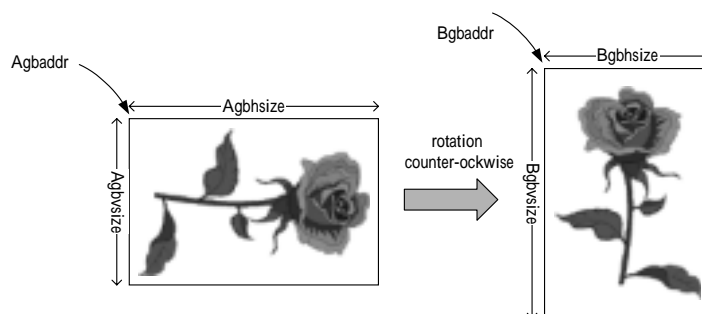


scaling-up flow chart

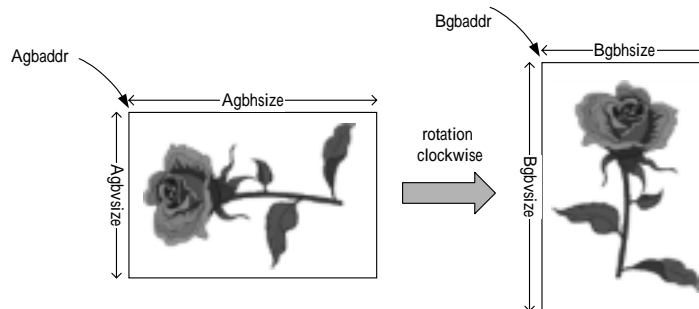
### 1.9.10.2 Image rotation operation

Image in the SDRAM can be rotated in both directions. This operation is only necessary when the image is already generated and stored in the SDRAM and the result image (of the rotation) is required. The JPEG compression engine in the SPCA533A also has the rotation function. The application can use the rotation function is the JPEG to speed up the execution. Rotation in the JPEG compression (decompression) does not take extra time while the JPEG engine performs compression/decompression.

Rotation (counter-clockwise)



Rotation (clockwise)



Example of Image rotation flow control

The source image size is 320x240, which locates in the SDRAM starting from address 0x000000 to 0x012BFF.

The target image size is 240x320, which locates in the SDRAM starting from address 0x200000 to 0x212BFF

Rotate the image counter-clockwise.

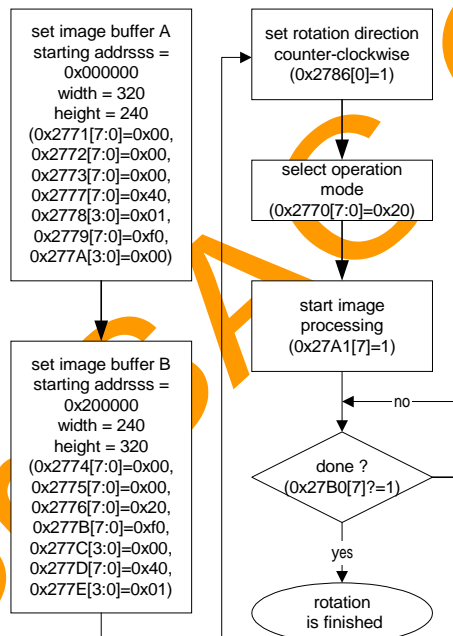
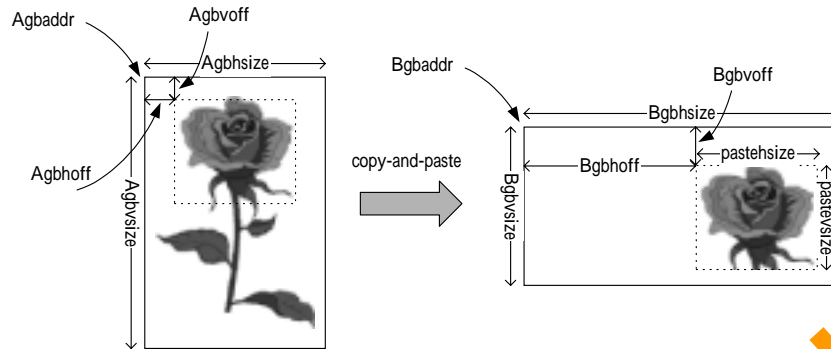


image rotation flow chart

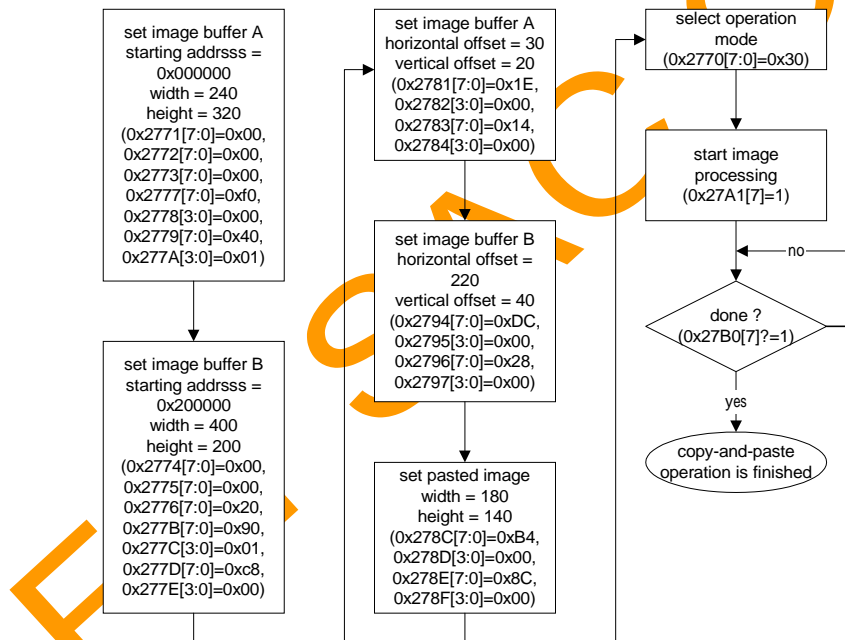
### 1.9.10.3 Copy & paste operation

The Copy & paste function is used in the graphic-based OSD. The source image buffer (image buffer A) stores the database of the graphic icons. The target image buffer (image buffer B) is the display buffer. The engine can copy a portion of image from the source image buffer and paste it to any location of the target image buffer. The location and size of the copied portion can also be programmed.



Example of copy-and-paste control flow

The source image size is 240x320. The target image size is 400x200. The size of the copied area is 180x140. The location of the copied region in the source image is at offset (30,20). The location in the target image buffer is at offset (220,40).



copy-and-paste flow chart

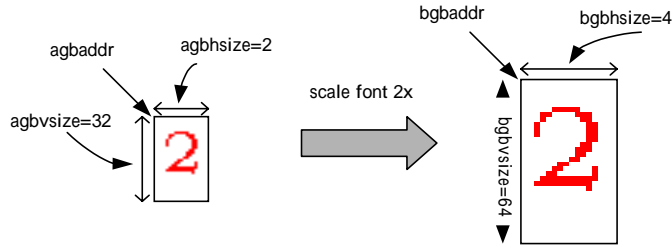
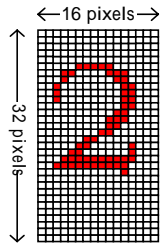
The copy & paste engine also supports color key checking. A color key is defined as the luminance value is under a predefined threshold. The black color is the used in color key in default. The copy & paste engine does not paste the color key area of the pasting image and leave the image as it is before the pasting. With the color key checking, the SPCA533A can paste virtually any shape of image onto another image. The color key threshold is defined in register 0x2998[6:0]. Bit 7 of the same register determines whether to turn on the color key checking feature.

1.9.10.4 Date stamping operation

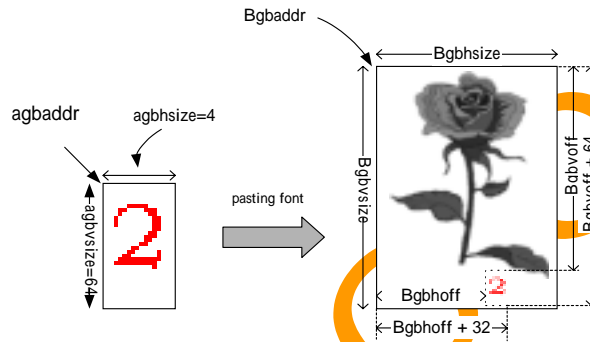
This function is to put a date-stamp on the captured image. It is a non-reversible operation. Once the date fonts stamp are put on the image, it is not possible to remove it. The date information can be read from the SPCA533's built-in RTC module. The font data base is the one used in the font-based OSD. The resolution of the font is 16 by 32 pixels. Depending the size of the captured image, the font might be scaled-up before stamping. The stamping function provides x2, x3 and x4 font scaling up. The color of the fonts is defined in register 0X2787. Refer to the SDRAM controller register section for detailed color definition.



Scaling-up the fonts (optional)  
OSD data  
one pixel = 2 bits

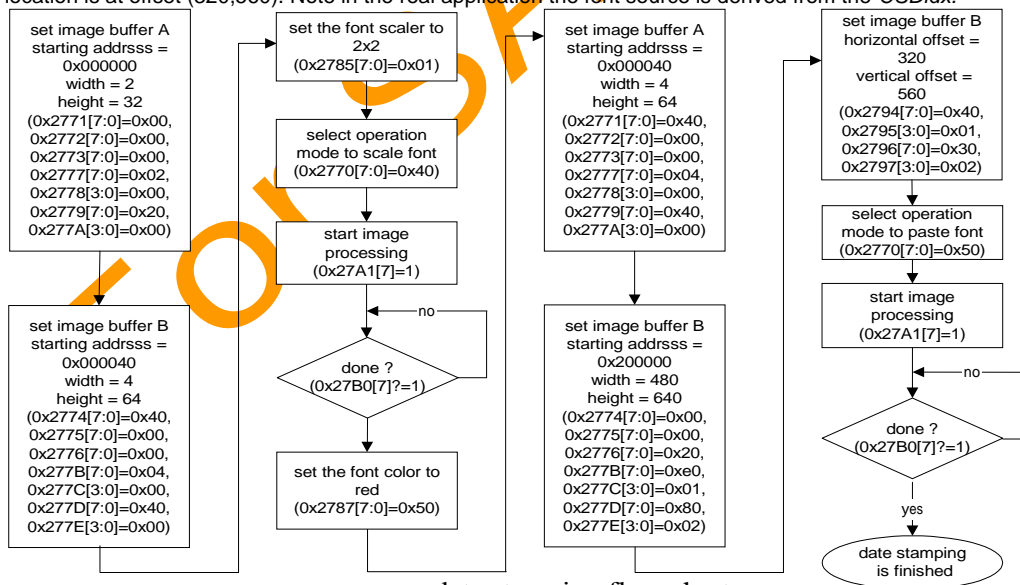


Stamping the fonts



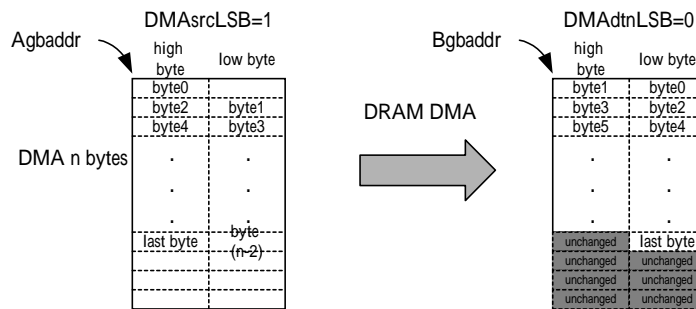
Example of date-stamping flow

Perform 2x scaling-up operation to the font and stamping it to the image from 0x200000 to 0x24AFFE. The size of the image is 480x640. The stamping location is at offset (320,560). Note in the real application the font source is derived from the *OSDidx*.



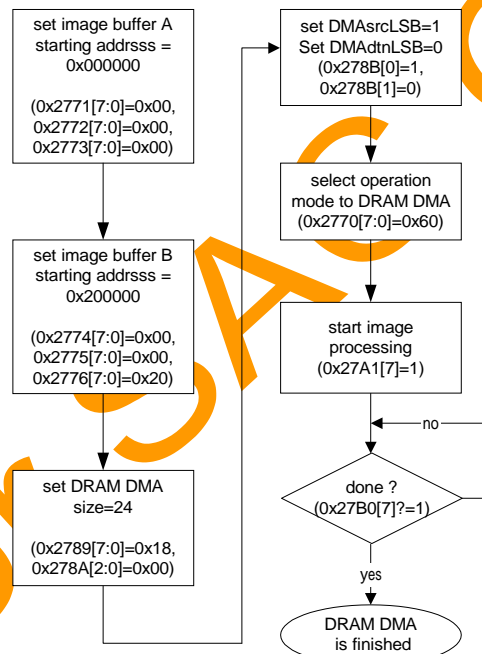
### 1.9.10.5 DRAM-to-DRAM DMA operation

The DRAM-to-DRAM DMA is the byte-addressing operation. This is the only part of design in the SPCA533A that uses byte address, all the other part of the SPCA533A use word address. The LSB of the byte address is specified in *DMAsrcLSB* register and *DMAatnLSB* register (0x278B). The *DRAMDMAsize* register (0x2789, 0x278A) specifies how many bytes will be transferred in a DRAM-to-DRAM DMA data transfer. The DRAM-to-DRAM DMA is not only useful in moving data inside the SDRAM but also useful to align the data to a byte-boundary.



Example of the DRAM-to-DRAM DMA control flow

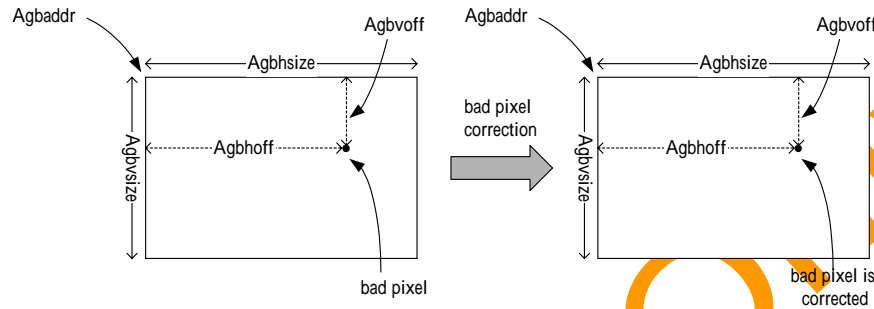
DMA 25 bytes of data from SDRAM space 0x000000 (high byte) to SDRAM space 0x200000 (low byte).



DRAM-to-DRAM DMA  
flow chart

### 1.9.10.6 Bad-Pixel correction

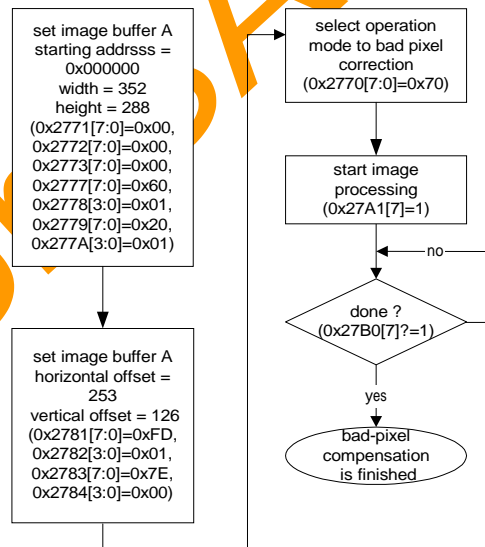
The SPCA533A has implemented two types of bad pixel corrections. The first one is implemented in the CDSP for real-time correction. It is used in the preview mode and video capture. The second one is implemented in the image-processing engine. The latter is more complex and results in better image quality. The coordinates of the bad pixel location is downloaded to the SDRAM from the external ROM after the SPCA533A is powered-on. The bad-pixel correction engine performs correction of one pixel each time as it is triggered.



The bad-pixel address is specified by the offset of the "image buffer A". After the engine is finished, the corrected pixel value is saved to the original location. The register "badpixthd" (0x2788) is the threshold value for determining the correction method.

Example of bad pixel correction control flow

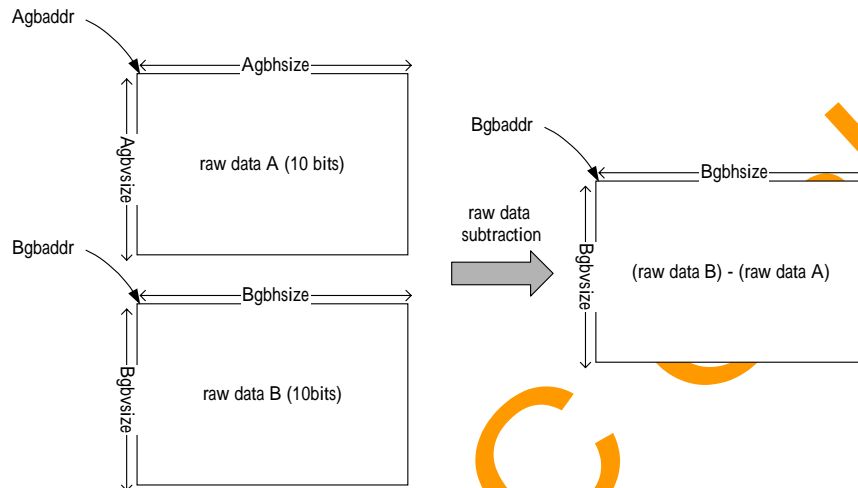
Bad pixel is located at the offset (253,126) of the source image (352,288), which locates in the SDRAM starting from address 0x000000 to 0x018BFF



bad-pixel correction flow chart

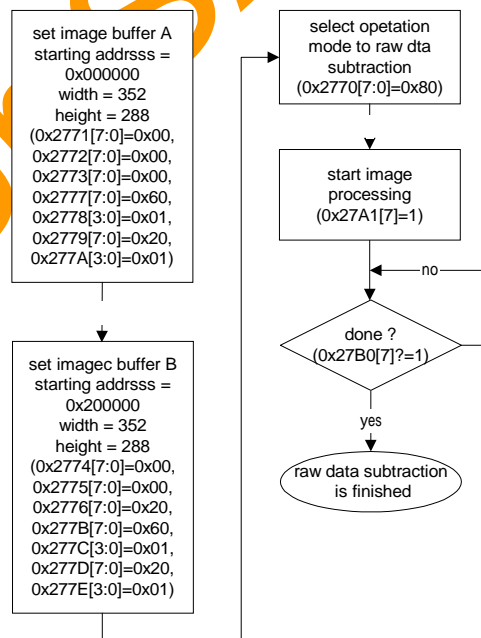
### 1.9.10.7 Inter-frame raw data subtraction operation

The CMOS sensors usually suffer a huge noise in a low-light environment. It is useful to enhance the image quality if the dark noise can be removed from the captured image. The SPCA533A has implemented the function to subtract a dark frame from the captured frame. The subtraction is based on 10-bit raw data. This operation uses two image buffers. The data in the image buffer B is subtracted by the data in the image buffer A and the result is stored in the image buffer B.



Example of raw data subtraction control flow

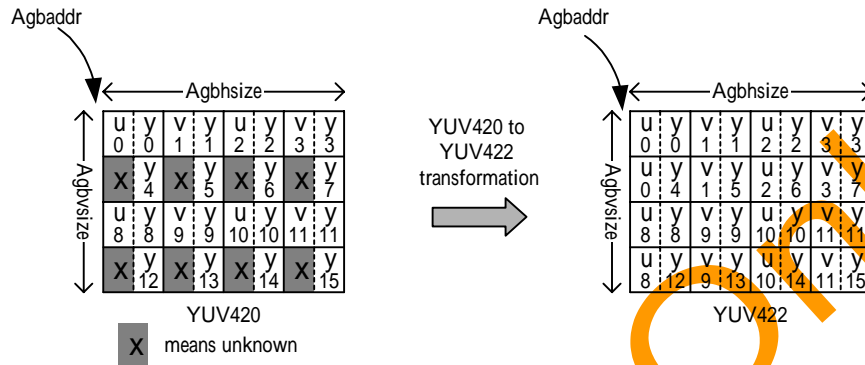
Subtract the raw data of two images (352x288).



raw data subtraction  
flow control

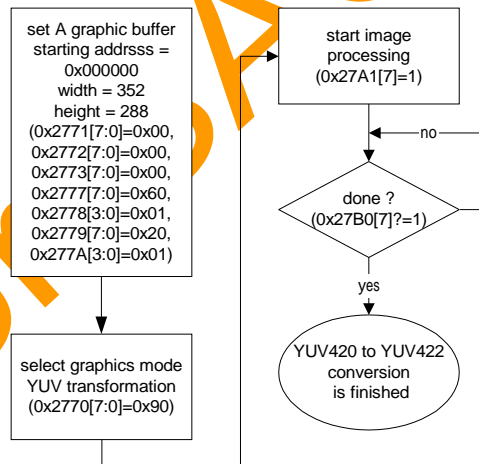
### 1.9.10.8 YUV420-to-YUV422 conversion

The LCD/TV controller can only display an image in YUV422 format. If a YUV420 image is decompressed for viewing, it must be converted to the YUV422 format before being sent to the LCD/TV. This operation uses only one image buffer (image buffer A), the UV data is duplicated in the vertical direction.



Example of YUV420-to-YUV422 conversion control flow

Convert a YUV420 image of size 352x288 to YUV422 image. The location of the image is in address from 0x000000 to 0x18BFF.



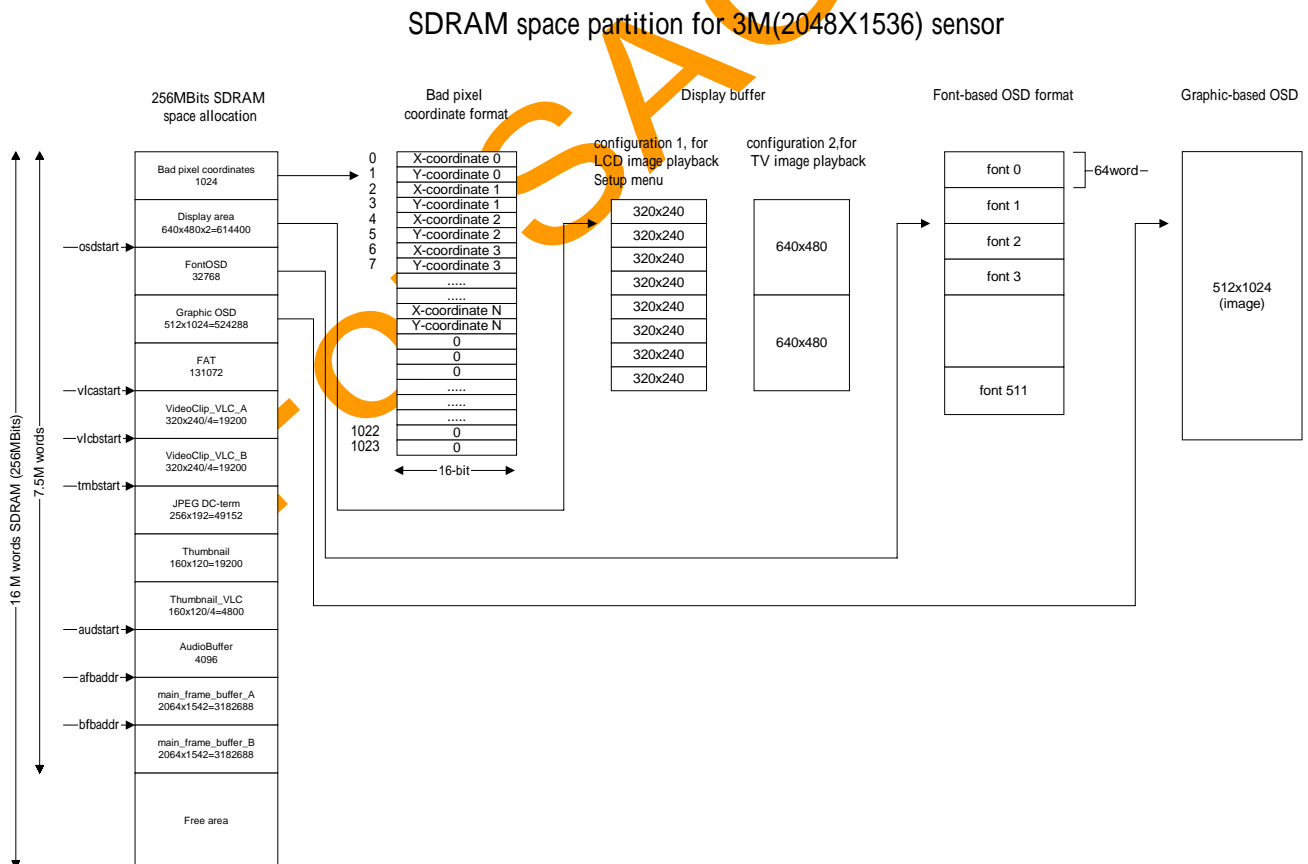
YUV420 to YUV422 conversion  
flow control

### 1.9.11 SDRAM space partition in different operation mode

The SDRAM space is partitioned to many regions during camera operation. The size of these regions can be very different among applications. For example, a 3M CCD system and 1.4M CCD system have different sizes of the frame buffer. The locations of these regions are programmable via the internal registers of the SDRAM controller. The following diagram demonstrates a typical SDRAM space partition and the pointers (starting address of the regions). The following address pointer are used in the SDRAM controller of the SPCA533.

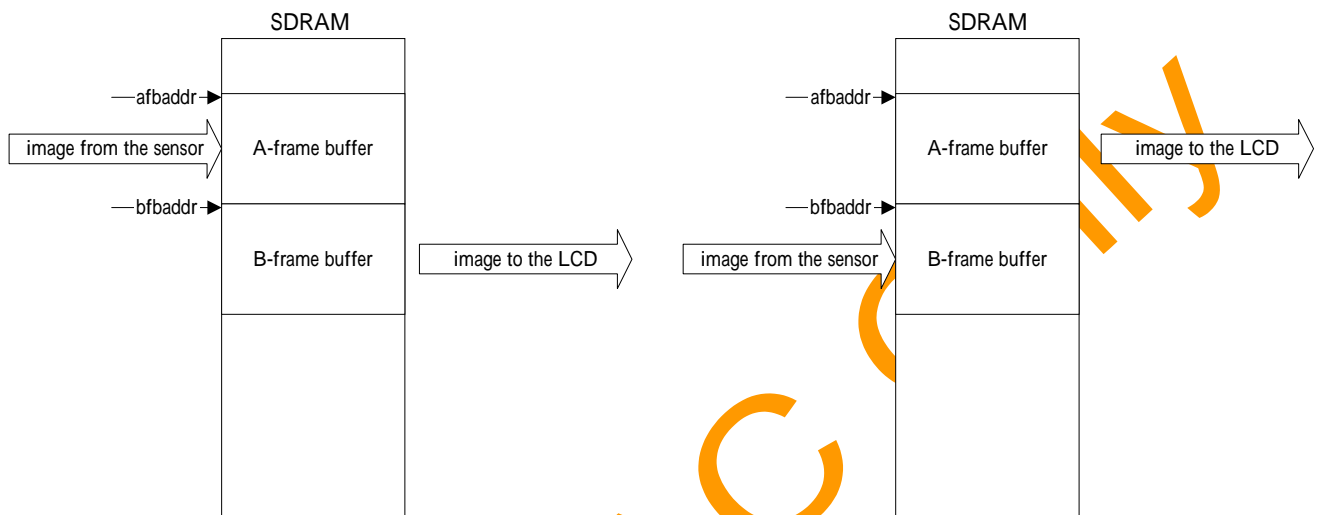
- Afbaddr* The starting address of A-frame buffer (the data of this buffer is YUV422/YUV420 format)
- Bfbaddr* The starting address of B-frame buffer (the data of this buffer is YUV422/YUV420 format)
- Rfbaddr* The starting address of the raw data frame buffer
- VLCastart* The starting address of the first VLC stream
- VLCBstart* The starting address of the second VLC stream
- TMBstart* The starting address to save the thumbnail data (generated by the JPEG compression)
- AUDstart* The starting address of audio buffer
- OSDaddr* The OSD fonts database starting address
- AGBaddr* The starting address of A image buffer, used in the image process engine
- BGBaddr* The starting address of B image buffer, used in the image process engine

The following diagram shows an example of the SDRAM space allocation. Some of the partitions are not explicitly pointed by a pointer. But they are necessary in a practical allocation.



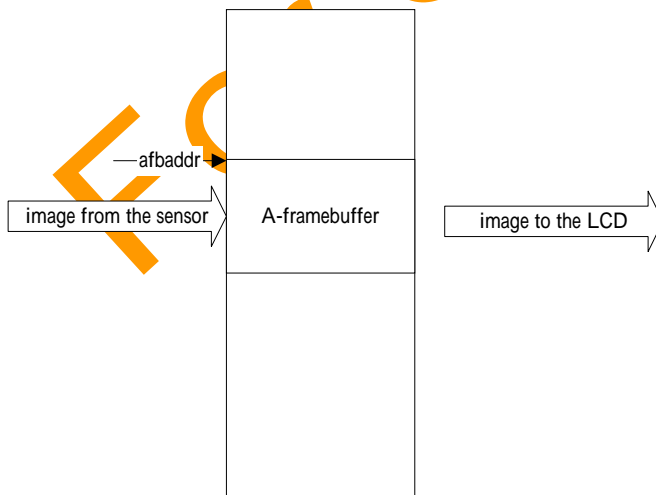
**PREVIEW mode :**

Two frame buffers are needed while the camera is operating in the Preview mode. The double is required for the frame rate conversion if the sensor frame rate is different from the LCD(TV) frame rate. The data in the frame buffers are in YUV422 format. The image data from the sensors are processed and written into the A/B frame buffer sequentially. While the image data is written into the A-frame buffer, the data in the B-frame buffer is read out for display. While the data is written into the B-frame buffer, the data in the A-frame buffer is read out for display.



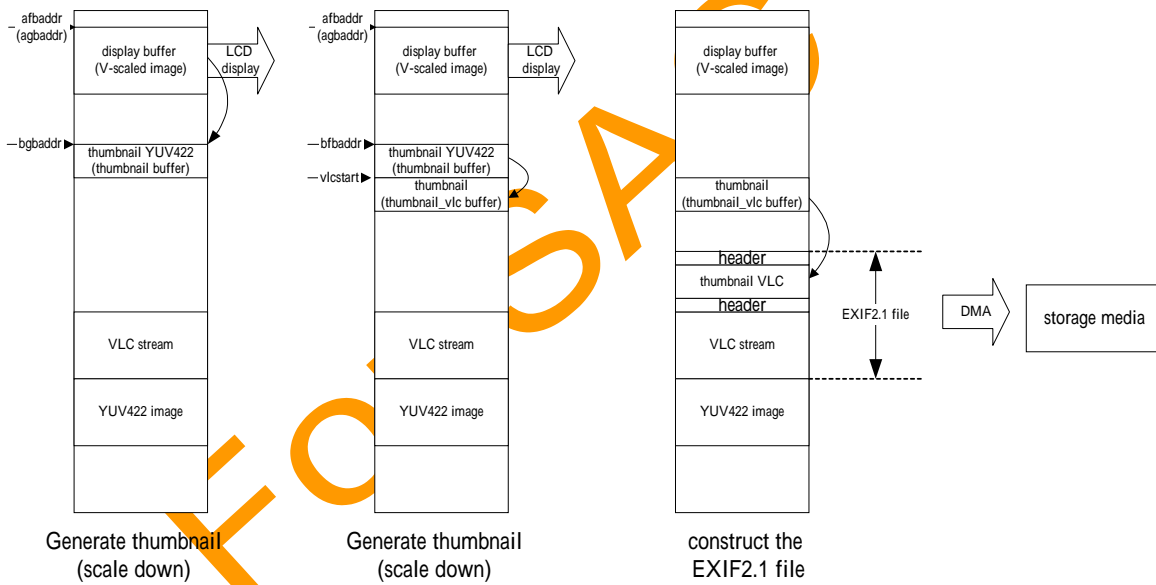
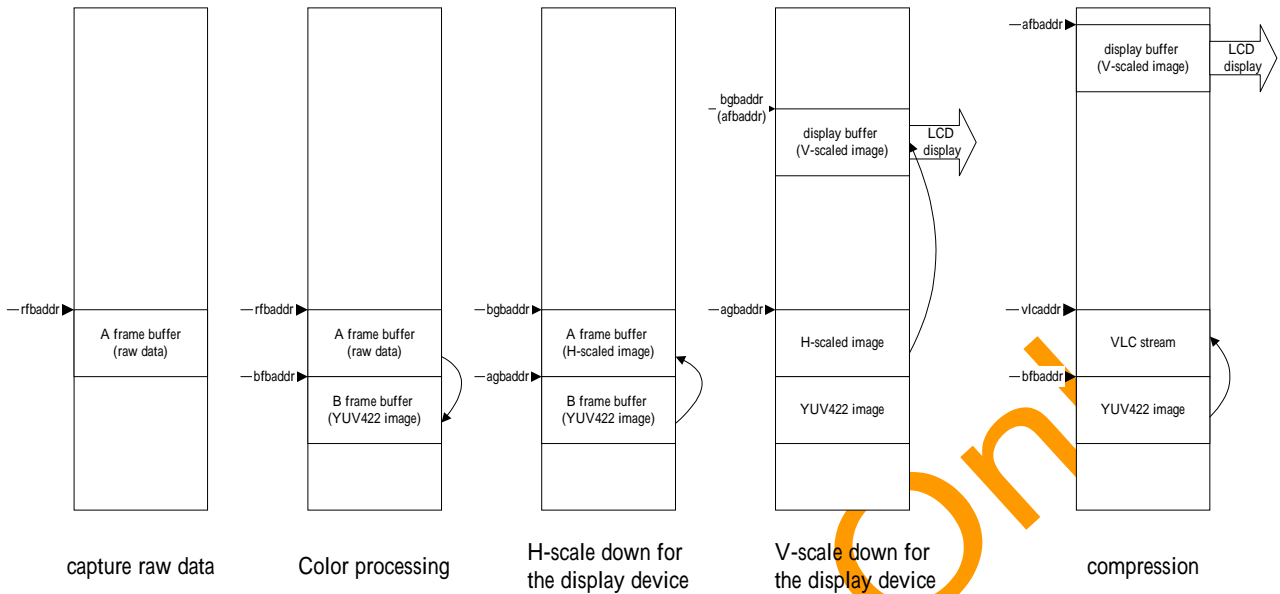
**PC-CAM mode :**

The LCD(TV) interface should be turned off in the *PC-Cam* mode. Only A-frame buffer is required. If the USB bandwidth is not sufficient to transmit the image at the input frame rate, the SPCA533A drops frames when necessary. The data in the A-frame buffer could be raw data or the YUV422 data, depending on the *imgtype* selection.



**Snap a single image :**

Snapping a single image requires three buffers. The first one is the raw data buffer which is used to hold the raw data from the sensor. After bad-pixel concealment, the raw data is sent to the CDSP for color processing. The output of the CDSP is written back to the A-frame buffer in the SDRAM. Then JPEG compression is performed on the YUV422 format data. The compressed data (VLC stream) is written into the B-frame buffer. After compression, the file header and the compressed thumbnail image is saved in front of the VLC stream to construct an EXIF2.1 JPEG file.

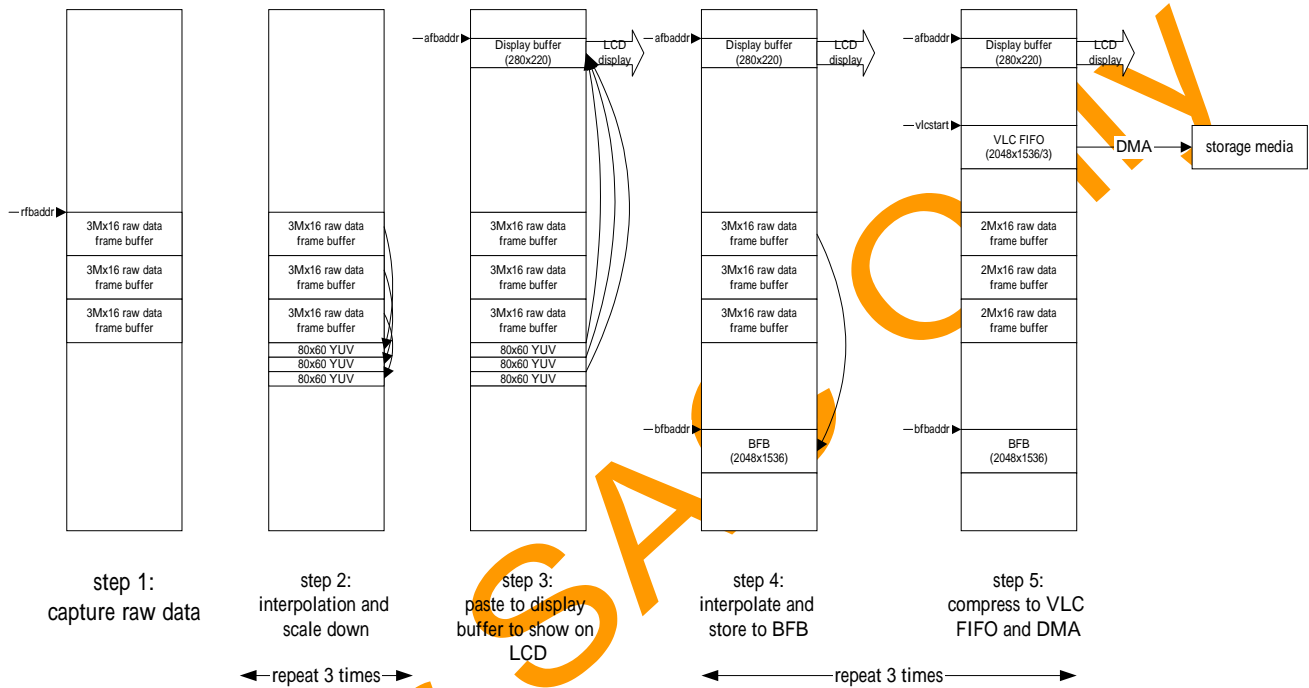




### Continuous shot :

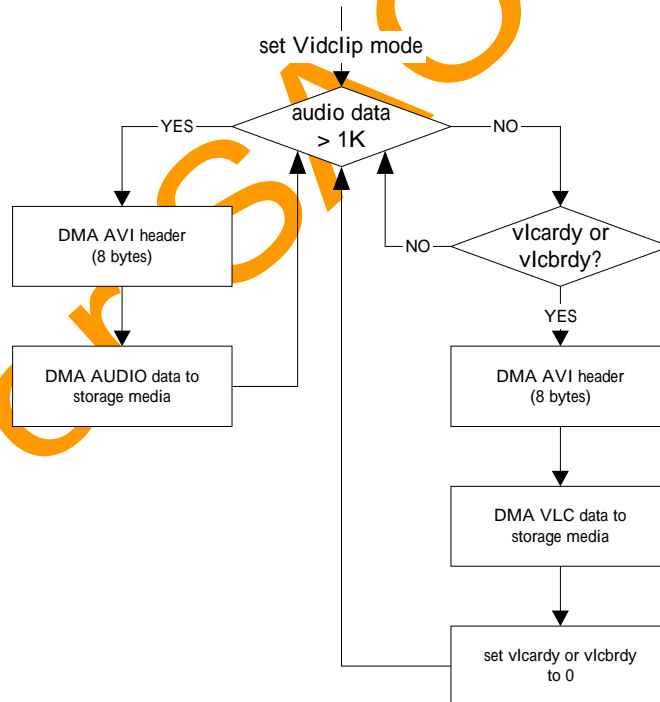
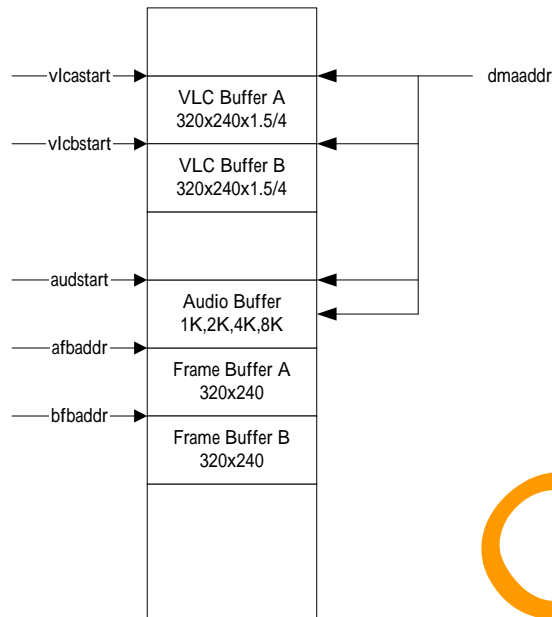
The continuous shot is also performed in the DSC mode. The number of pictures taken in a continuous shot is determined by register *snaphum* (0X2B05). The raw image data is stored in the SDRAM raw data buffer, which is pointed by *rfbaddr* register (0X2768 ~ 0X276A) . The maximum number of pictures that can be taken in a continuous shot is limited by the capacity of the SDRAM. After all the raw data is captured, the data is processed frame by frame. This includes the color processing, compression and file saving. The following diagram demonstrates the operation flow and the SDRAM space allocation.

Continuous Shot SDRAM partition



### VIDEOCLIP :

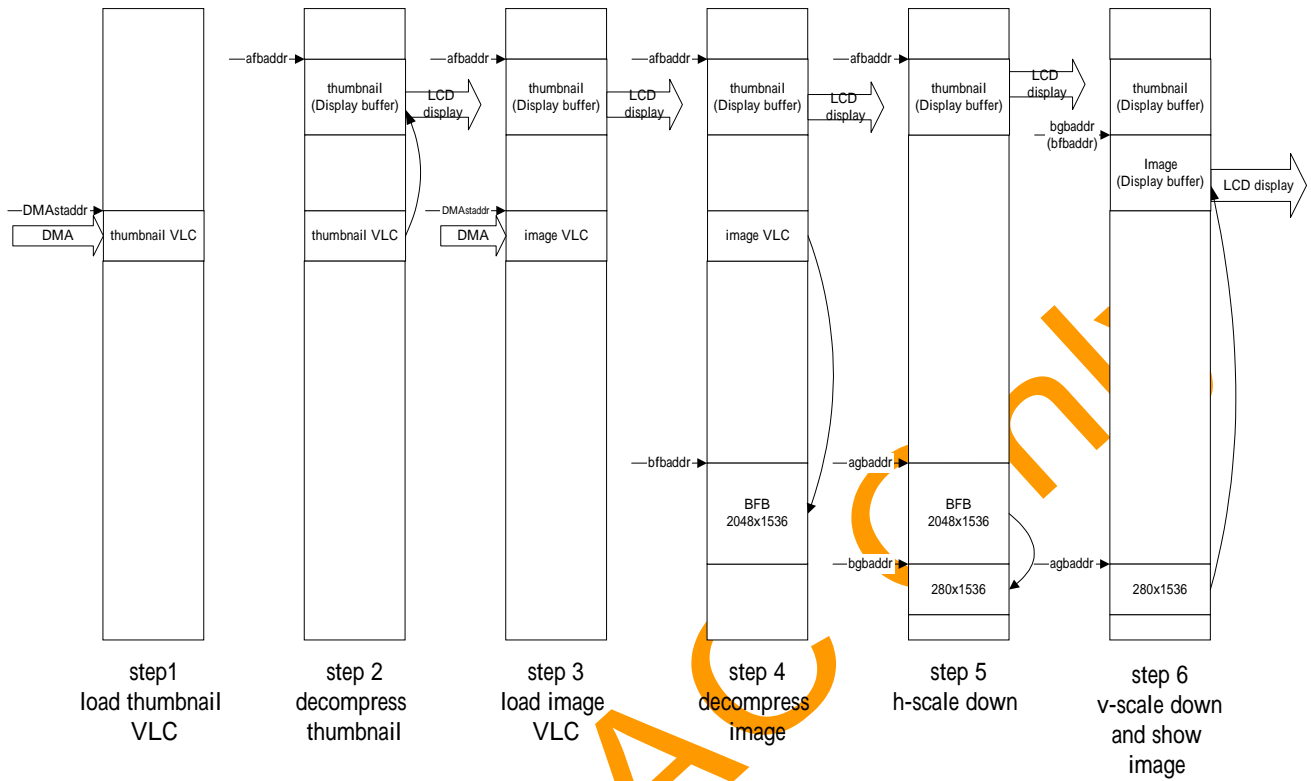
The SPCA533A can capture the video and audio data at the same time. The captured data is tailored and format to an AVI file. In videoclip, two frame buffers, two VLC buffers and one audio buffer are allocated. Dual frame buffer allows the SPCA533A to perform the frame rate conversion during the videoclip. The size of the audio buffer is porgammabl. It could be 1K, 2K, 4K or 8K bytes.



**PLAY BACK mode :**

Because it takes longer time to decompress and playback a large size image on the LCD, the user may decompress the thumbnail to reduce the playback time. The decompressed thumbnail data is put in the display buffer first, then turn on the LCD to show the thumbnail. After that, the primary image can be loaded to the SDRAM and decompressed to another display buffer. Up to this step, the primary image is in the frame buffer B. But this image size is too large to show on the LCD. So it is recommended to scale down the primary image to the size fitting to show on the LCD. After that, program the "lcdsrcidx" to one to show this image.

The following diagram illustrates the procedure of playback a single image.

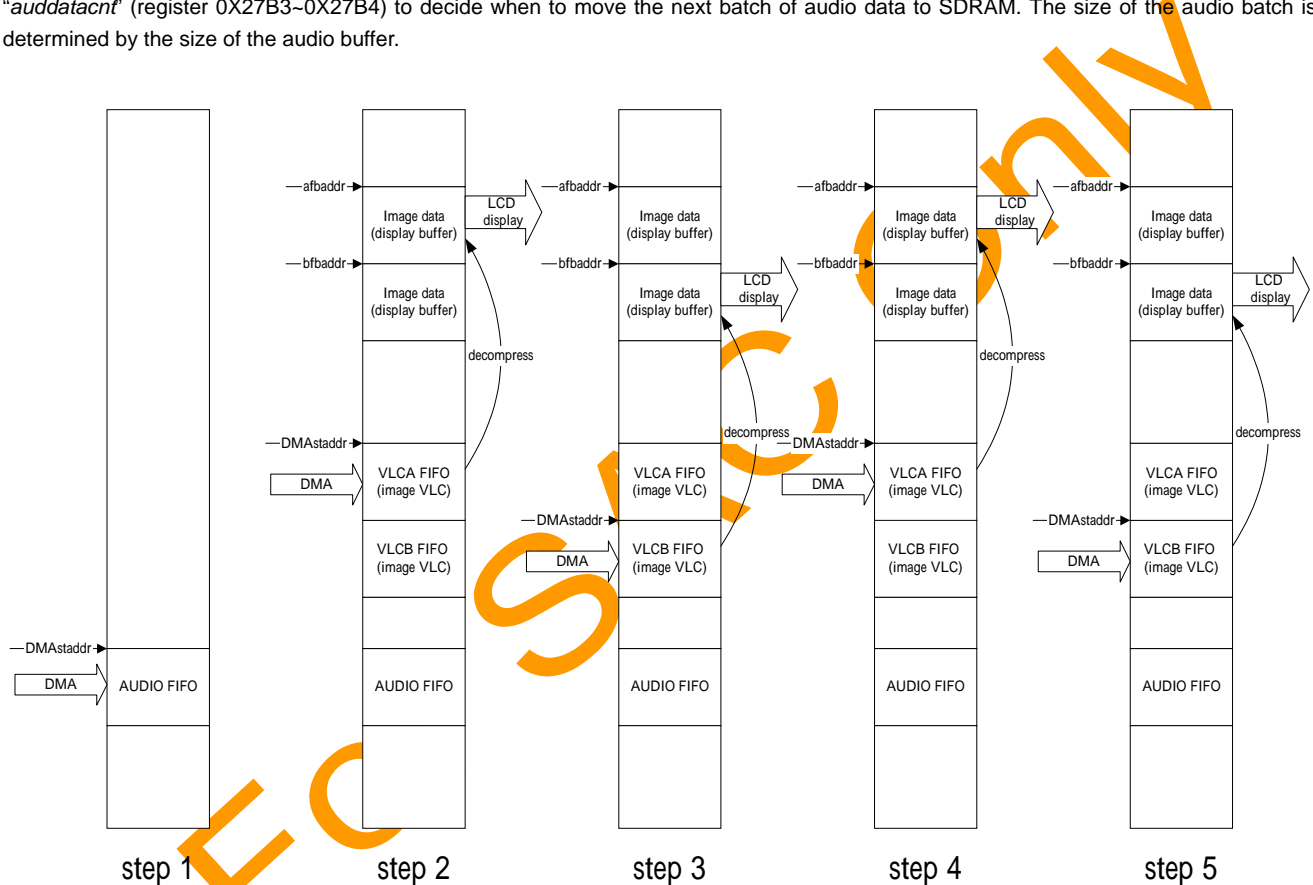


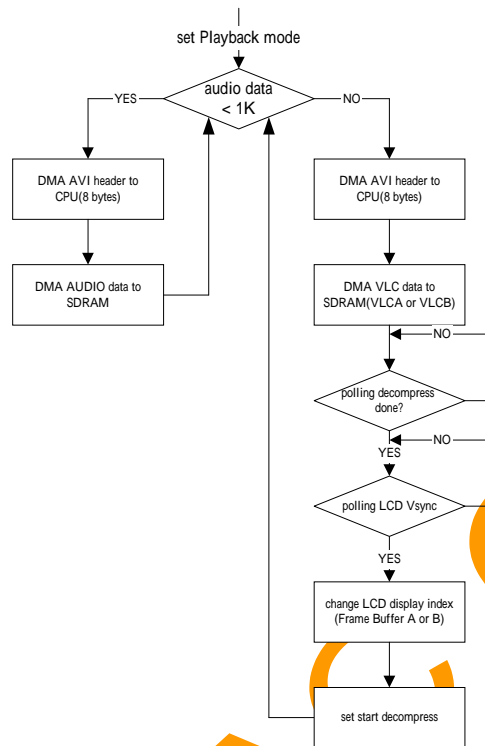
For SA

### Video playback :

The SDRAM space allocation in the video playback is similar to capturing the video. Two frames buffers, two VLC buffers and one audio buffer are used. The JPEG VLC stream is moved into one of the VLC buffer and decompressed to one of the frame buffer for display. When the user is viewing the decompressed image in the first frame buffer, the next image is being decompressed at the background and the decompressed image is stored into the other frame buffer.

For the audio part, the audio file in the storage media is moved to the audio buffer first. Then turn on the control bit "audclipen" (register 0X273E[0]) to direct the SDRAM controller to send the audio data to the AUDIO controller. The firmware must poll the register "auddatacnt" (register 0X27B3-0X27B4) to decide when to move the next batch of audio data to SDRAM. The size of the audio batch is determined by the size of the audio buffer.





## 1.10 Serial interface

The SPCA533A supports two types of serial interfaces. The first type is synchronous serial interface, and the other type is three-wire serial interface. Synchronous serial interface (SSC) is usually used to control a TV decoder or CMOS sensors. The three-wire serial interface is usually used to program the registers of a CDSAGC used in a CCD camera system.

### 1.10.1 Synchronous Serial interface (SSC)

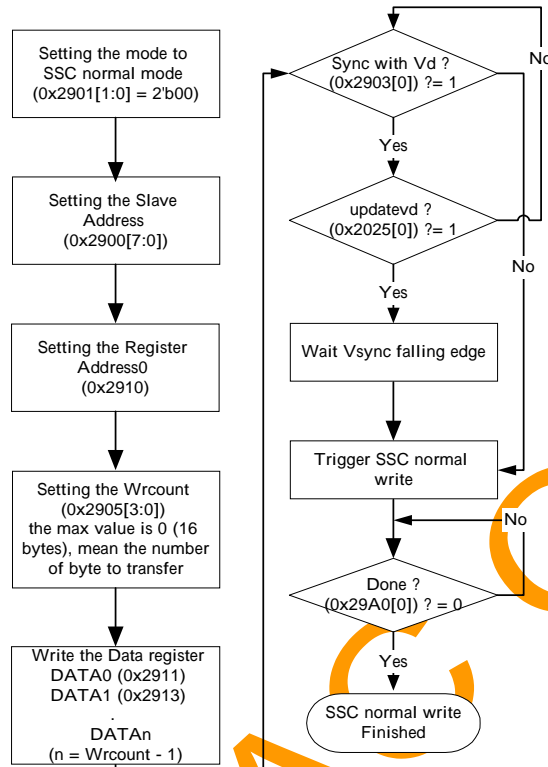
The synchronous serial interface has a data pin and a clock pin. The clock pin is driven by the SPCA533A and the data pin is a bi-directional pin. Both pins are pulled-up by external resistors. Before using the SSC to program the CMOS sensors (or TV decoders), the clock frequency on the clock pin must be determined. It is programmable via registers 0X2904. The SSC of the SPCA533A supports several types of protocol as described below.

**Normal write protocol** In this mode, the sub-address of the CMOS sensor is transmitted only once. This sub-address usually represents which register in the CMOS sensors is to be programmed. Register 0x2905[3:0] determines how many bytes are to be transmitted to the CMOS sensor. The maximum number of bytes in a single transmission is 16 bytes. If the CMOS sensor supports linear sub-address increment, the SPCA533A can write several bytes of data to the CMOS sensor in a single transmission. The transmission is started right after the last data register is written. For example, if the write count is 2, the SPCA533A will start transmission once DATA1 register is written. There might be some side effects if the CMOS sensor's registers are programmed in the middle of an image frame. For example, changing the gain registers might cause different gain values in the same frame of data. The SPCA533A is able to delay the serial interface programming until the start of the next frame. To do this, register 0X2903[0] must be set to 1

Normal write control flow



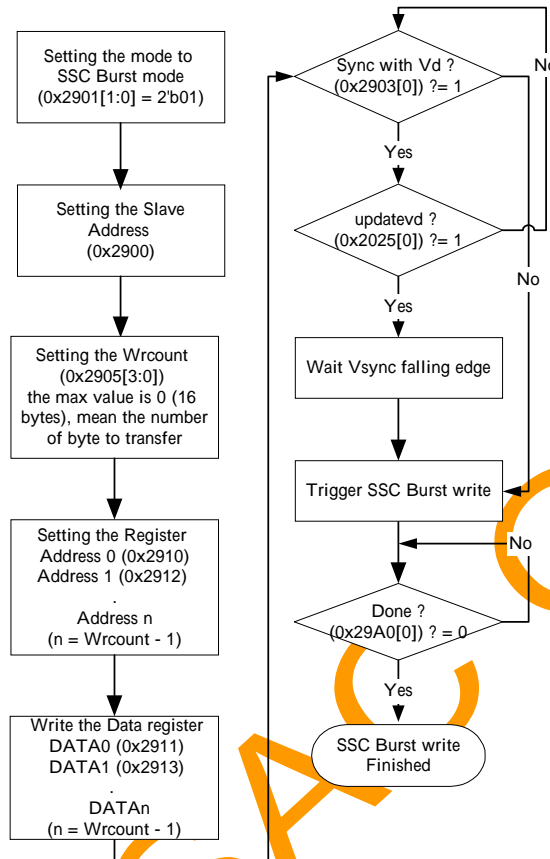
(Note: S represents the start bit and P represents the stop bit)



Normal write flow chart

**Burst write protocol** This mode allows the user to write several bytes of data to the CMOS sensors in a single transmission, each byte with a different sub-address. The burst write transmission can also be delayed to the start of the next image frame.

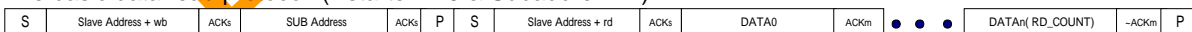




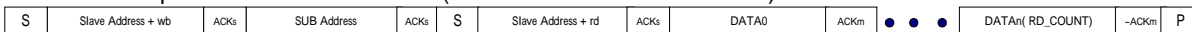
Burst write flow chart

**Data read protocol** The SPCA533A supports three types of read protocols as shown below. Depending on the CMOS sensors, the users may select any of these protocols that most fit the CMOS sensors' requirement. The first protocol is the basic type. It sends a *stop* code before any *start* code. The second one omits the *stop* code. And the last one omits the sub-address field. All these types of read require the CMOS sensor to support the linear address increment. Again, the read transmission can be delayed to the start of the next frame. However, this is usually not necessary.

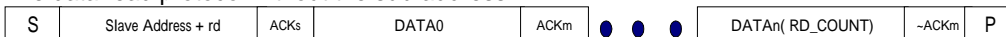
The basic data read protocol: (Rstarten = 0 & Subaddren= 1)

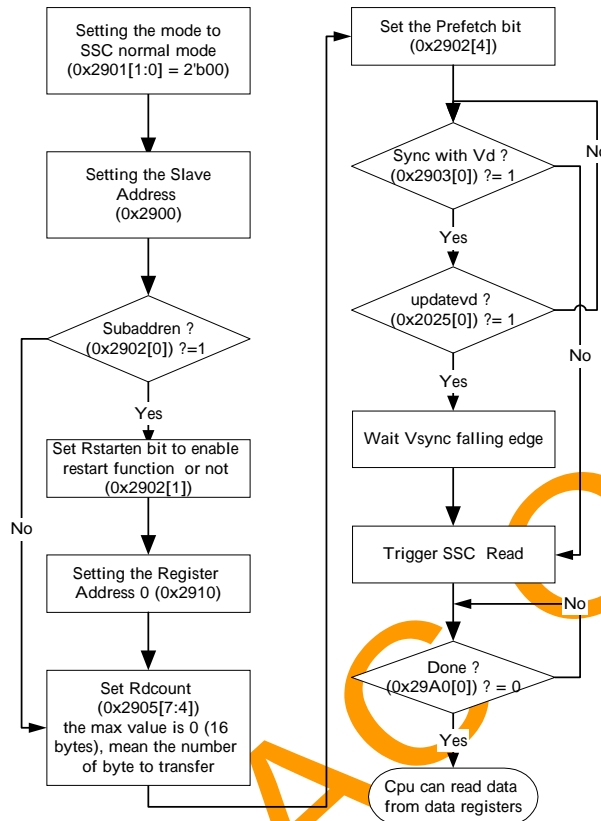


The data read protocol with restart code: (Rstarten = 1 & Subaddren = 1)



The data read protocol without the sub-address

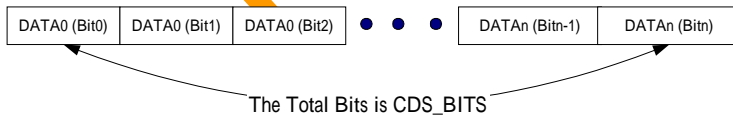




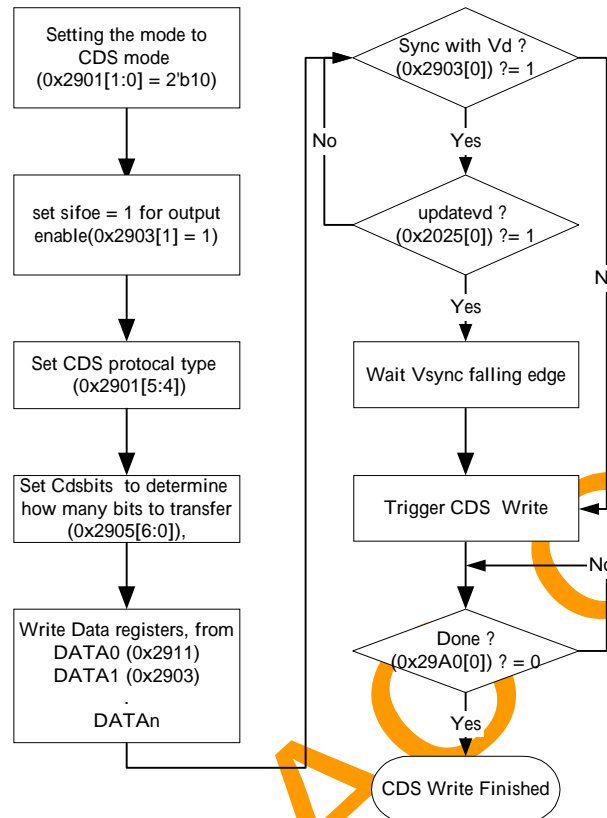
SSC read flow chart

### 1.10.2 Three-wire interface

SPCA533A supports 4 types of three-wire protocols. These protocols conform to the most frequently used CDSAGC chips in a CCD camera system. In the application, this interface can only write register values to the CDSAGC but not read from them. Like the SSC, the clock frequency has to be selected before using the three-wire serial interface. Register 0x2504[7:0] determines the clock frequency used in transmission. The SPCA533A can transmit up to 80 bits to the CDSAGC in a single transmission. However, the real number of bits acceptable is determined by the CDSAGC. The users have to pay attention to the bit-sequence of transmission. The SPCA533A transmits low byte first and LSB first. Refer to the following diagram. The bit 0 of the DATA0 is the first bit to be sent to the CDSAGC.







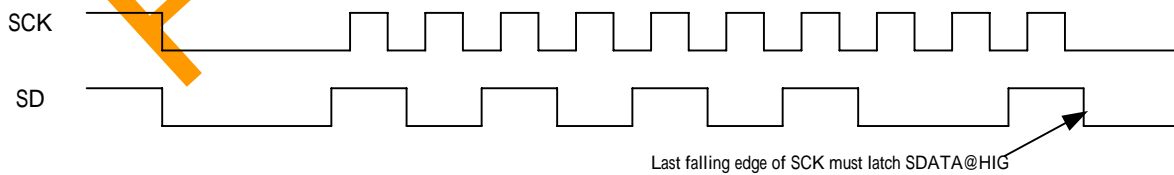
CDS write control flow chart

(Notice: SPA533 must write from DATA0 (0x2911) → DATA1 (0x2903) → ..... → DATAn, when write the number of Data register bits >= Cdsbits, the three-wire interface will trigger to send out data.

EX: If you setting the Cdsbits is 19, then when you write DATA0 → DATA1 → DATA2, then the three wire interface will send out the data)

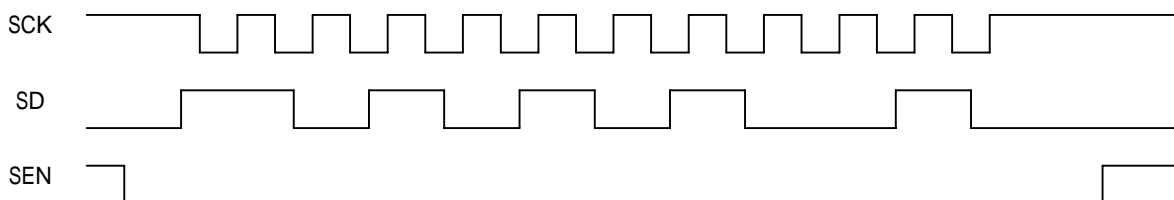
The SPCA533A supports 4 types of serial timing in the three-wired protocol. The type can be set in register 0x2901[5:4].

*Type 0 timing* (for SHARP Family CDSAGC chips)



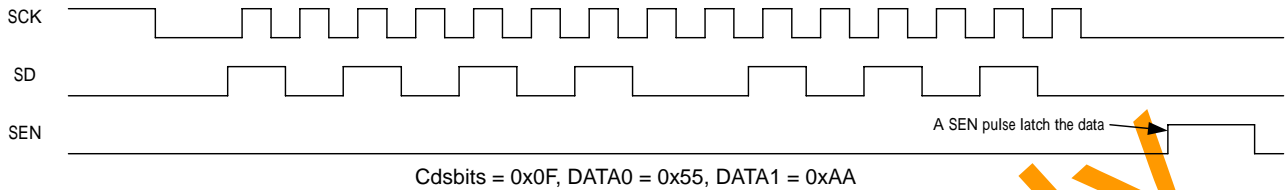
Cdsbits = 0x0A, DATA0 = 0x55, DATA1 = 0xAA

*Type 1 timing* (for HITACHI HD49322F, ADI AD9803, EXAR XRD44L61/2 chips)

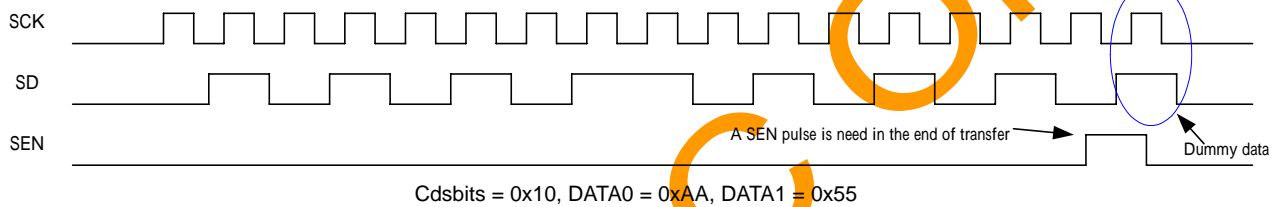


Cdsbits = 0x0B, DATA0 = 0x55, DATA1 = 0xAA

Type 2 timing (for PANASONIC AN2104FHQ CDSAGC chips)



Type 3 timing (for FUJITSU VGA chips)



### 1.10.3 Manual control of the serial interface

In the manual controlled mode, the signal SCLK, SD, and SEN are controlled like a general-purpose output. The timing can be generated by the firmware. This mode is used when the CMOS sensors or the CDSAGC chips use special protocols that the SPCA533A does not support. Follow the steps below in the manual control mode.

- Step 1: Setting *trans mode register* 0x2901[1:0] to 3, this will select the manual control mode
- Step 2: Set register 0x2903[1] = 1 to turn on the output buffer of SCLK, SD and SCK.
- Step 3: Writing register 0x290A[0] to drive SCLK (write 0 to drive low, and 1 to drive high)
  - Writing register 0x290B[0] to drive SDO
  - Writing register 0x290C[0] to drive SEN

### 1.11 TV-IN / CMOS Sensor interface

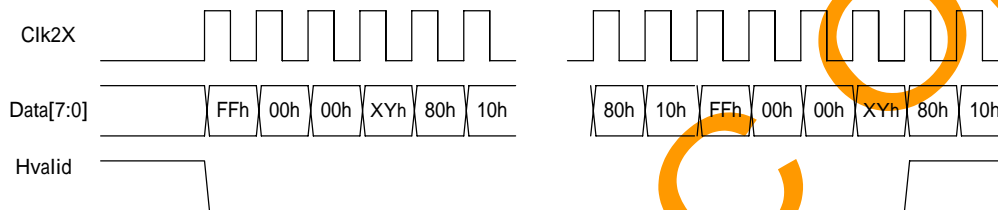
Connection a TV decoder to the SPCA533A is similar to connecting a CMOS sensor to the SPCA533. This section explains the interfaces of these external devices.

#### 1.11.1 TV input interface

The SPCA533A supports both CCIR601 and CCIR656 TV signals as its input image source

**CCIR 601 format:** The SPCA533A requires the external TV decoder to supply Hsync, Vsync, hvalid, dvalid, vvalid, field control signal and data signals.

**CCIR 656 format:** The control signal is encoded in the data stream. The SPCA533A decode the image data stream to extract the control signals. The following diagram shows the data encoding of the CCIR656 standard.



	Data7	Data6	Data5	Data4	Data3	Data2	Data1	Data0
First word	1	1	1	1	1	1	1	1
Second word	0	0	0	0	0	0	0	0
Third word	0	0	0	0	0	0	0	0
Forth word	1	F	V	H	P3	P2	P1	P0

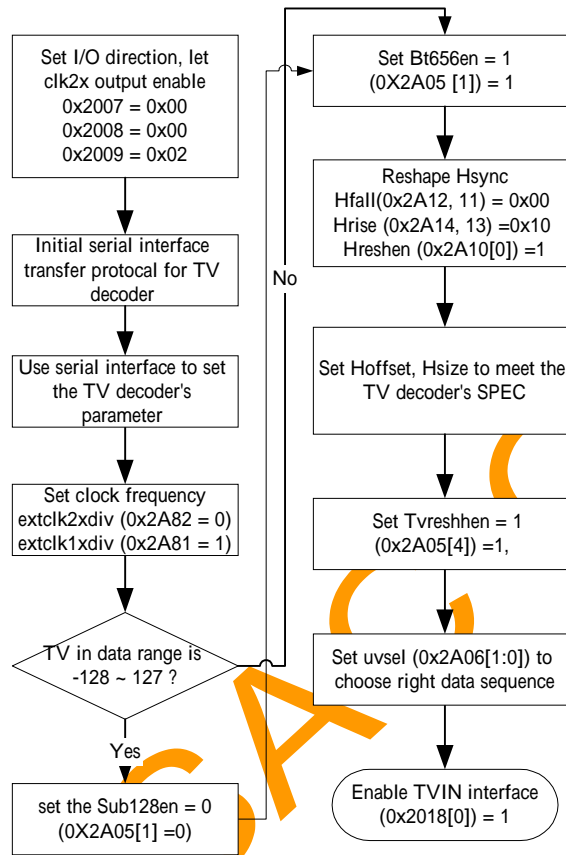
H: 0 - SAV, 1 - EAV

V: 1 - blanking, 0 - elsewhere

F: 0 - field 1, 1 - field 2

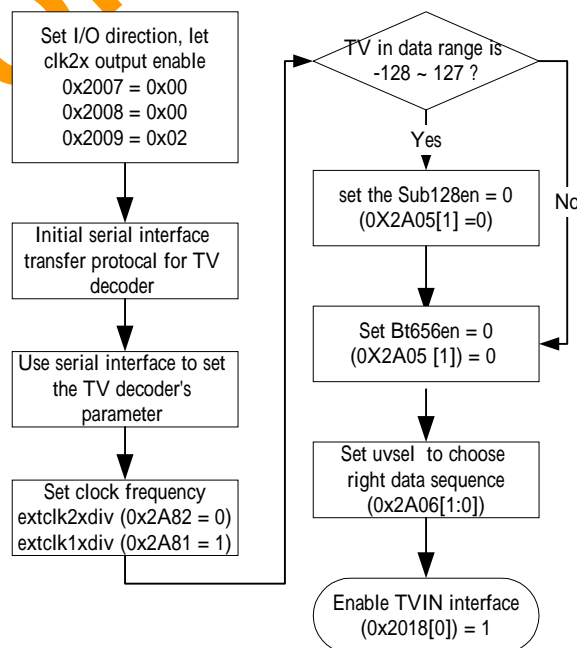
P3: V XOR H; P2: F XOR H; P1: F XOR V; P0: F XOR V XOR H

Initialize the CCIR656 interface



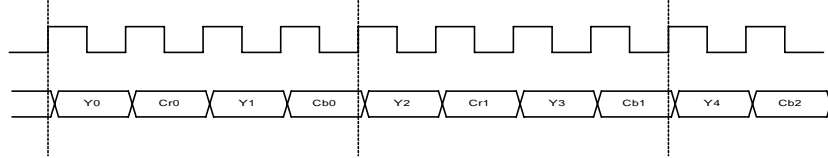
CCIR656 interface initialize flow chart

Initialize the CCIR601 interface:

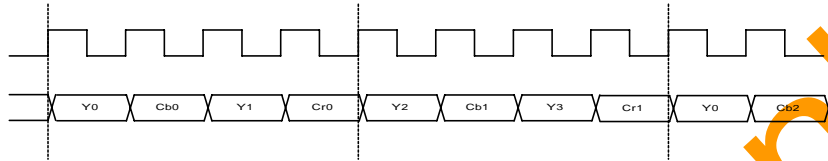


CCIR601 interface initialize flow chart

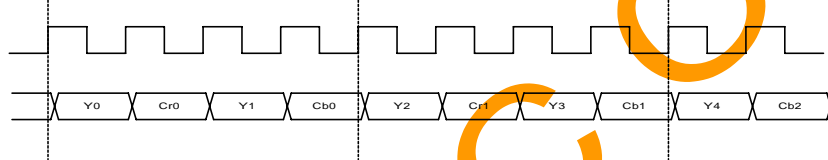
Data sequence: The *order* bits in register *uvsel* (0X2906) is used to select one of the data sequence



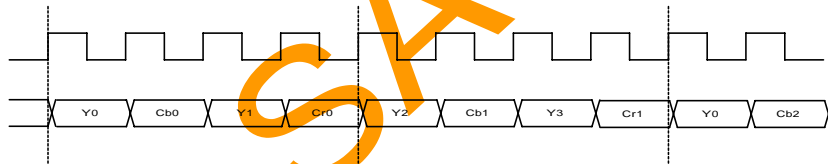
$Uvsel = 2'b01$   
After interplation :  $Cbout = Cb$ ,  $Yout = Y_{1d}$ ,  $Crout = Cr_{2d}$



$Uvsel = 2'b11$   
After interplation :  $Cbout = Cb_{2d}$ ,  $Yout = Y_{1d}$ ,  $Crout = Cr$



$Uvsel = 2'b01$   
After interplation :  $Cbout = Cb$ ,  $Yout = Y_{1d}$ ,  $Crout = Cr_{2d}$



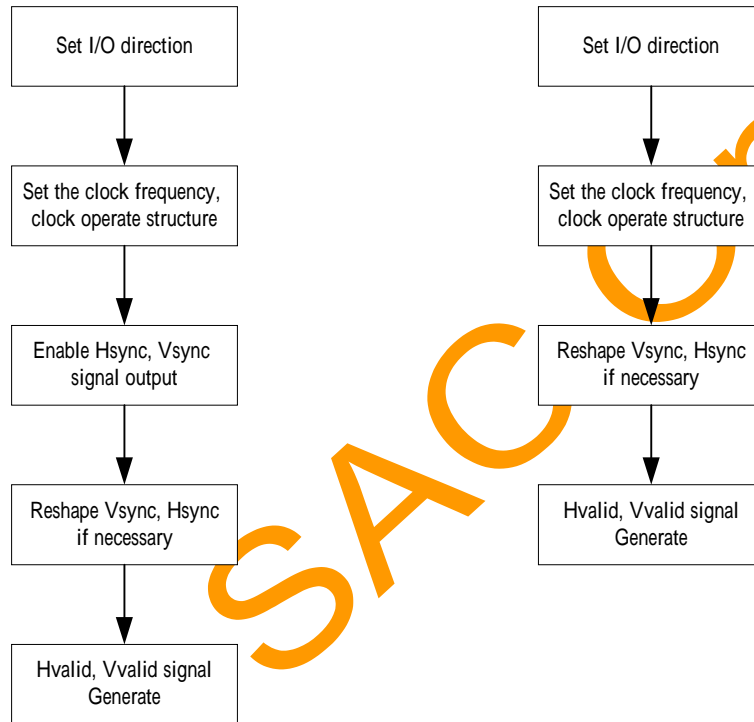
$Uvsel = 2'b11$   
After interplation :  $Cbout = Cb_{2d}$ ,  $Yout = Y_{1d}$ ,  $Crout = Cr$

For SAC Only

### 1.11.2 CMOS interface

The SPCA533A CMOS sensor interface supports both master mode and slave mode. In the master mode, the control signals (vertical synchronization signal and horizontal synchronization signal) are supplied by the CMOS sensors. In the slave mode the synchronizations signals are supplied by the SPCA533.

Program flow chart for slave type CMOS sensor      Program flow chart for master type CMOS sensor



#### 1.11.2.1 I/O direction for sensor interface

The interface pins of the SPCA533A to the CMOS sensors are bi-directional. These signals could be driven by the CMOS sensors or by the SPCA533, which depends on the type of the CMOS sensors. Register 0x2007[0] controls the direction of the vertical synchronization signal. Register 0x2007[1] controls the direction of the direction of the horizontal synchronization signal. Register 0x2009[1] controls the direction of the 2X pixel clock. And register 0x2009[3] controls the direction of the pixel clock.

For example, to connect a slave-type CMOS sensor to the SPCA533, register 0x2007[1:0] must set to 2'b11. Set this register to 2'00 for the master-type CMOS sensor. The direction control of 2X pixel clock and pixel clock are described in section 5.11.2.2

#### 1.11.2.2 Clock system for sensor interface

The SPCA533A supports three types of clock structure for the CMOS sensors. The SPCA533A has built-in two PLL (phase lock loop) to generate the source clocks used in the sensor interface. The first PLL output 96MHz, the second PLL output 144MHz. These frequencies are usually 8X of the pixel clock. Depending on the frequency of the pixel clock, the appropriate clock source should be selected prior to operation. The 2X pixel clock and pixel clock are derived by dividing the 8X pixel clock. The frequency of the 2X pixel clock is adjustable via register 0x2A82. And the pixel clock frequency can be adjusted via register 0x2A81. The frequency settings of the 2X pixel clock may take effect immediately after it is changed or delayed until the next frame. When register Clk2divsvden (0x2980[1]) is cleared, the frequency changes immediately after programming. When register Clk2divsvden (0x2980[1]) is set and the global control register *vdupdate* (0x2025[0]) is set, the frequency change will be delayed until the start of the next frame.

*Type 1:* The SPCA533A supplies 2X pixel clock to the sensor, and the sensor returns the pixel clock. The register setting is described below. The SPCA533A samples the sensors' data with the clock output from the CMOS sensors.

Set TGPLLen (0x2080) , select 96MHz/144MHz clock source  
 Set Extclk2xdiv (0x2A82), 2X pixel clock frequency= the source clock frequency/ (Extclk2xdiv +1)  
 Set clk2x output enable (0x2009[1]) = 1, enable 2X pixel clock output  
 Set clk1x input (0x2009[3]) = 0, set the pixel clock as input  
 Set SelectTG1xCk (0x2019[7]) = 0, select pixel clock from the PAD

The frequency of the 2X pixel clock is adjustable via register 0x2A82. For example, TGPLLen = 0, Extclk2xdiv = 7, then  $clk2x = 96 / (7+1) = 12MHz$

*Type 2:* The SPCA533A supplied the pixel clock to the sensors and samples the data with the same clock. The register settings are described below.

Set TGPLLen (0x2080), select 96MHz/144MHz clock source  
 SelectTG2xCk (0x2019[7]) = 1 select the internal 2X pixel clock source  
 Set Extclk2xdiv (0x2A82), 2X pixel clock frequency=source clock frequency / (Extclk2xdiv +1),  
 Set Extclk1xdiv (0x2A81), pixel clock frequency=2X pixel clock frequency/ (Extclk1xdiv + 1),  
 Set clk1x output (0x2009[3]), enable the pixel clock output

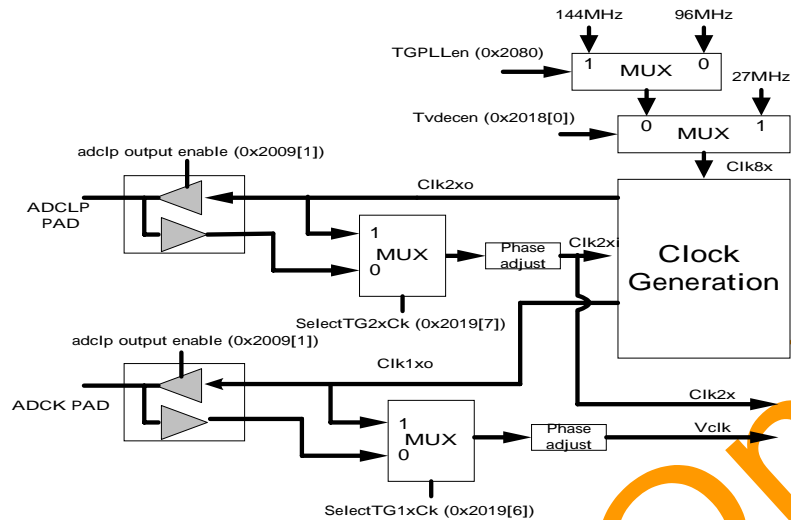
*Type 3:* Special mode for the HP CMOS sensor

The HP CMOS sensors provide "DRDY" signal for the backend system to sample the data. But this signal is paused during the blanking period of a line. The SPCA533A accepts only periodic clock source. In this case, the pixel clock must be generated internally. The SPCA533A automatically generates a periodical pixel clock, which is synchronized to the "DRDY" signal. The register settings are described below.

Set TGPLLen (0x2080) select the 144MHz/96MHz clock source  
 Set Extclk2xdiv (0x2A82) set the 2X pixel clock frequency  
 Set Extclk1xdiv (0x2A81), set the pixel clock frequency  
 Set Hpen (0x2A80[0]) = 1 enable the HP CMOS sensor mode  
 Set (0x2009[1]) = 1, set the 2X pixel clock as output pin  
 Set (0x2009[3]) = 0, set the pixel clock as input pin  
 Set (0x2019[7]) = 1, select the clock generator as the source of the pixel clock

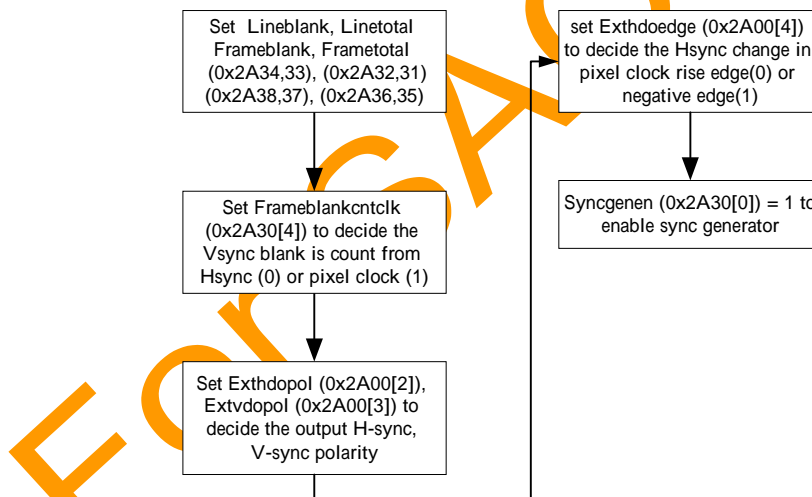
The following diagram shows the clock routing of the CMOS sensor interface. Besides the function of the CCD's driving clocks, the ADCLP and ADCK pins are used as the clocks pins in a CMOS sensor system. In a CMOS sensor system, The ADCLP pin is used as the 2X pixel clock and the ADCK is used as the pixel clock.

The 2X pixel clock has two sources. The first one is from the IO pad and the other one is from the internal clock generator. The source of 2X pixel clock is selected by register 0x2019[7]. The pixel clock has also two sources. One is from the IO pad; the other is from the internal timing generator. This could be selected by register 0x2019[6].



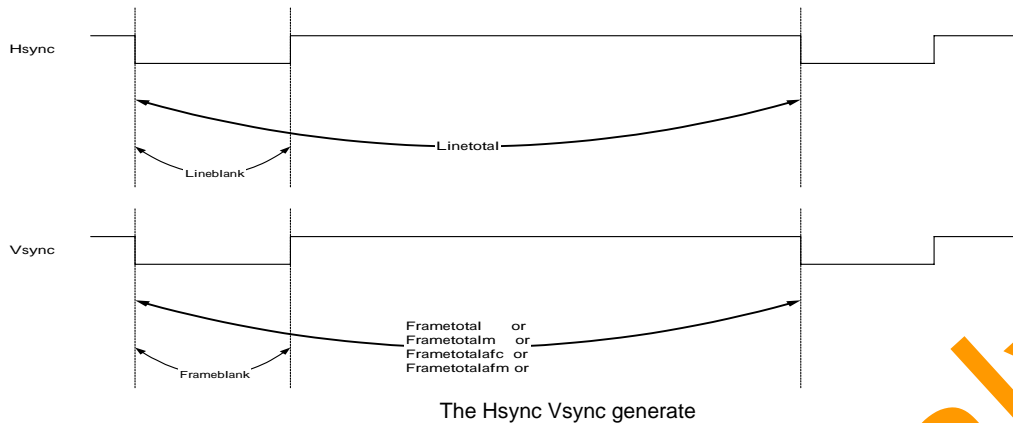
### 1.11.2.3 Hsync, Vsync output signal generate:

For the slave-type CMOS sensor, the SPCA533A generates the vertical (and horizontal) synchronization signal according to the following flow.



The time period of a frame is determined by register *Linetotal* and *Frametotal*. Both registers, when changed, may take effect immediately or until the start of the next frame. To delay the effective time, both register *Totalsvden* (0x2A30[1]) and *vdupdate* (0x2025[0]) must be set.



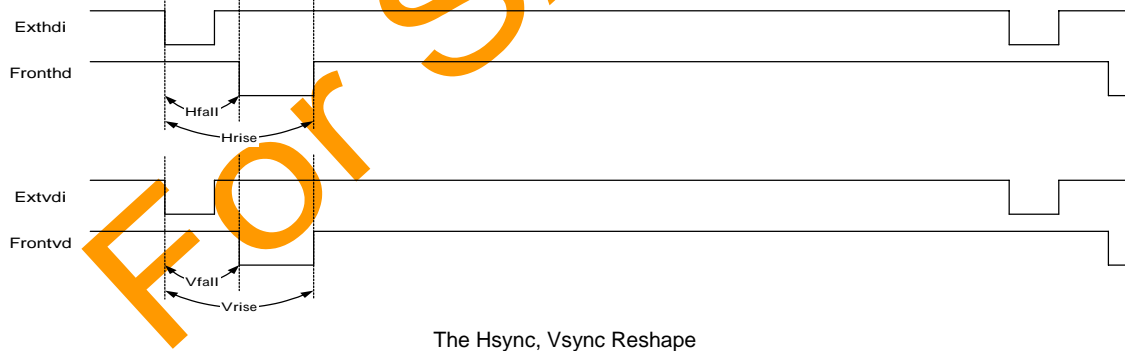


#### 1.11.2.4 Hsync, Vsync Reshape

Due to the pipeline architecture of the image-processing module in the SPCA533, the active region of the image may accidentally overlay with the external synchronization signals. This is not acceptable for the SPCA533. The synchronization signals might be reshaped before using by the internal modules of the SPCA533. The procedure is described below.

- Set Hfall (0x2A12, 11), Hrise (0x2A14, 13), reshape Hsync.
- Set Vfall (0x2A16, 15), Vrise (0x2A18, 17), reshape Vsync.
- Set Vreshcntclk (0x2A10[4]), select reshape unit in the Vsync. reshape (pixel or line)
- Set Hreshen (0x2A10[0]) = 1, enable Hsync reshape
- Set Vreshen (0x2A10[1]) = 1, enable Vsync reshape

Reference to the following timing diagram for details.

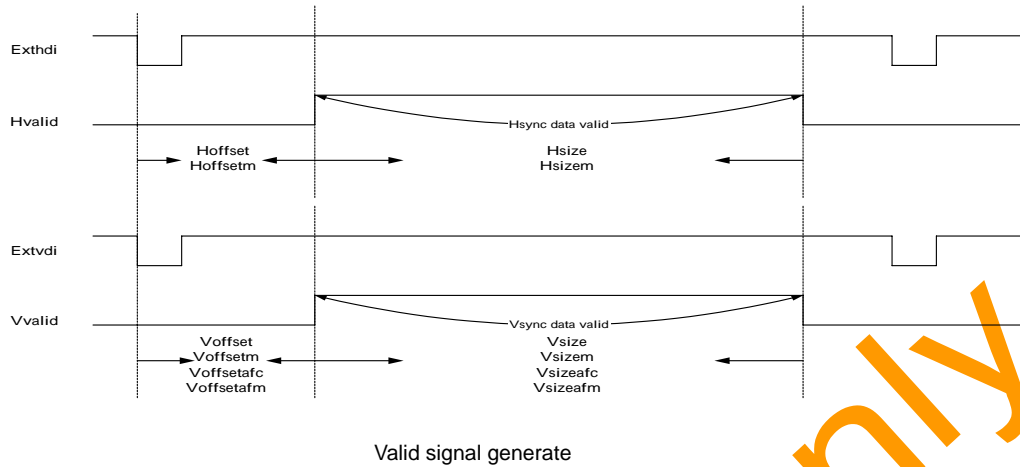


#### 1.11.2.5 Hvalid, Vvalid generation

Both Hvalid and Vvalid signals are used internally. The SPCA533A determines active region of the image by these two signals. To generate these signals, the following parameters must be programmed.

For capture mode, set Hoffset (0x2A21, 20), Hsize (0x2A25, 24), Voffset (0x2A21, 20), Vsize (0x2A25, 24).

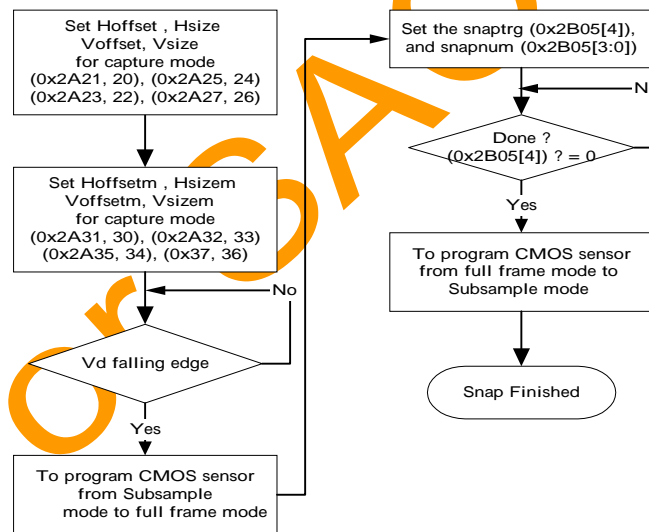
For monitor mode, set Hoffsetm (0x2A31, 30), Hsizem (0x2A33, 32), Voffsetm (0x2A35, 34), Vsizem (0x2A37, 36).



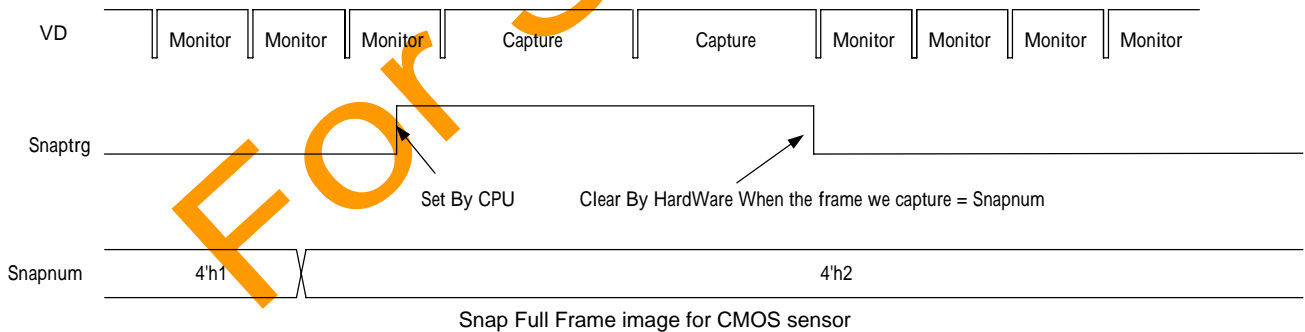
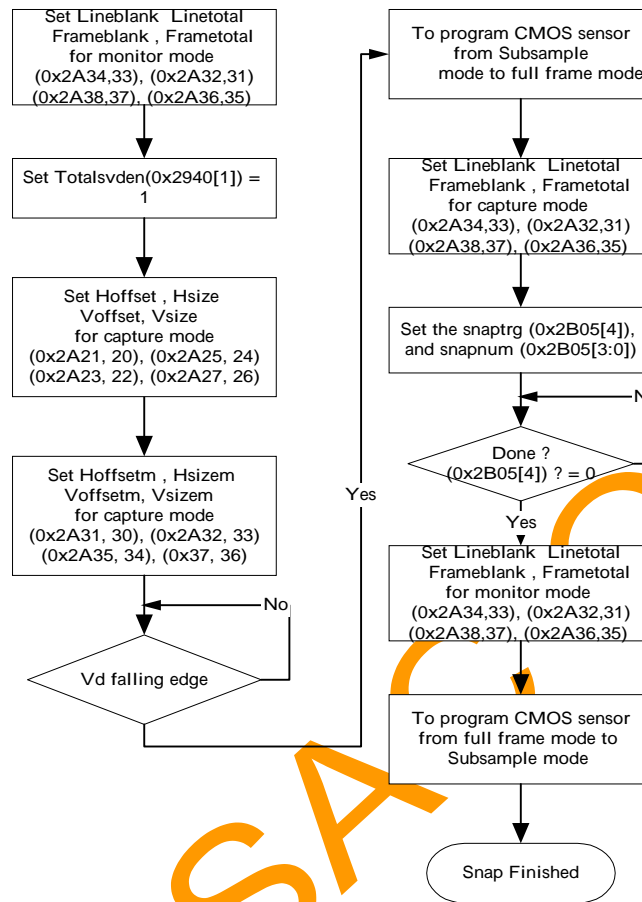
### 1.11.3 Image Capture:

Image capture flow in the master mode CMOS sensor is different from the one in the slave mode CMOS sensor. The following diagrams show both control flows.

Master type CMOS sensor snap flow chart:



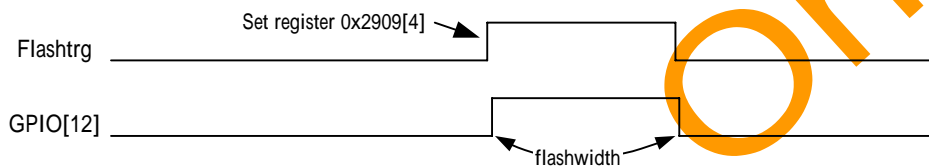
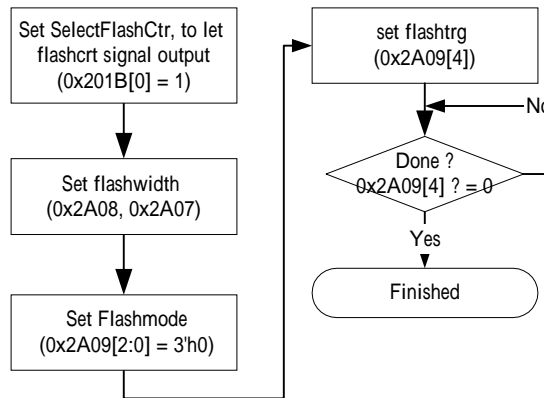
Slave type CMOS sensor snap flow chart:



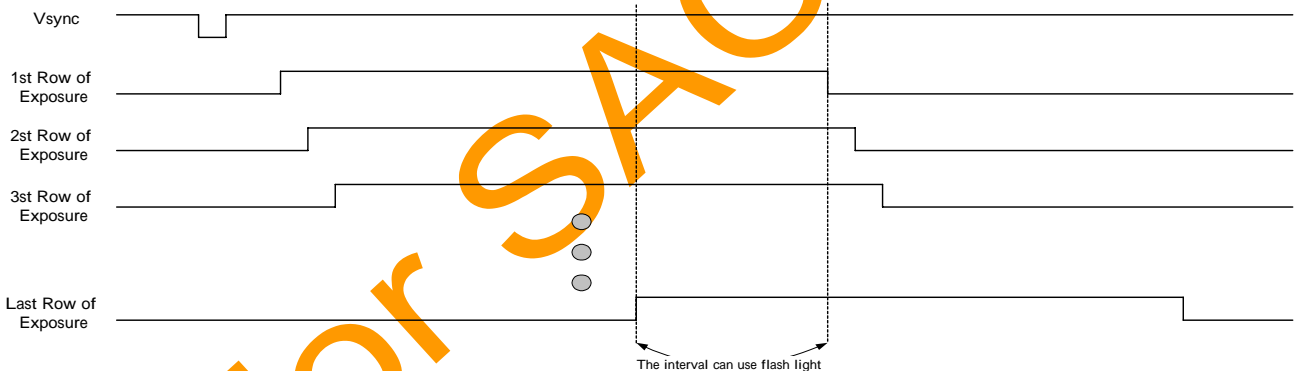
#### 1.11.4 Flash light control for CMOS sensor

The SPCA533A supports five flash light control modes. In a CMOS sensor system, only mode 0 is used. In this mode, the flashlight is trigger immediately after register 0x2A09[4] is set. The polarity of the flashlight-triggering signal is programmable via register 0x2A09[3]. The assertion period of the flash light control pin (multiplexed with GPIO [12]) is programmable via register 0x2A07 and 0x2A08. The value is calculated based on 2-pixel time. For example, if the frequency of the pixel clock is 20 MHz and the *flashwidth* registers is set to 100, the triggering period is 10us.

Programming flow of the mode 0 flash light control



Note that the flashlight should be triggered when all lines of a CMOS sensor are accumulating charge.



The period that can use flash light for CMOS sensor exposure

## 1.11 CCD Interface

The CCD sensors' interface is more complicated than the CMOS sensor interface. Sunplus provides initialization firmware routines to setup the interface for all the supported CCD sensors.

### 1.12.1 Operation modes:

The SPCA533A support both progressive-type CCD sensors and interlaced-type CCD sensors. Setting the *Progressen* register (0x2B00[1]) to select the CCD type, 1 for Progressive CCD sensor, 0 for Interlace CCD sensor.

The built-in timing generator can output four modes of the CCD clock timings.

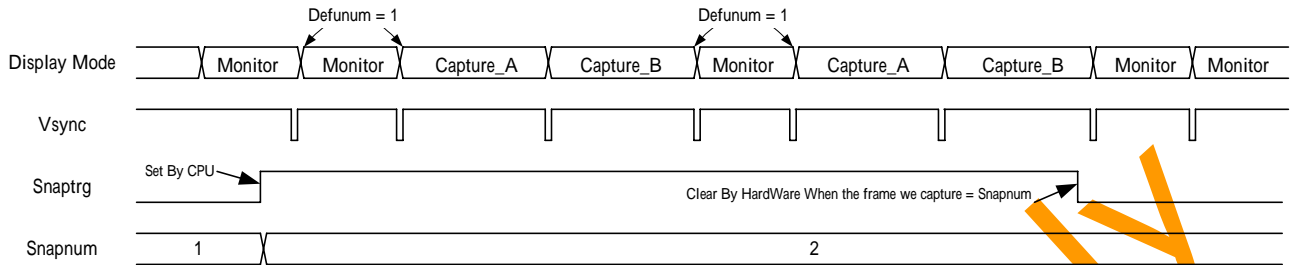
**Mode 0:** Monitor mode. This is the default mode and usually used in the preview of the camera.

**Mode 1:** Full frame capture mode. The timing generator goes into this mode after the *Snaptrg* register (0x2B05[4]) is set. The timing generator automatically goes back to mode 0 after the frame is captured.

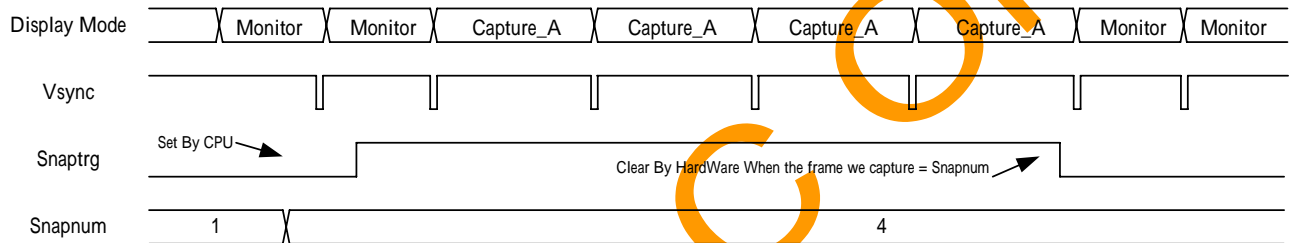
**Mode 2:** AF Monitor mode. The timing generator goes into this mode (from the monitor mode) after *Afen* register 0x2B00[2] is set. It returns to the monitor mode after *Afen* is cleared. This mode is often used in the power-on stage of the

camera to focus the lens. The AF monitor mode outputs only the data of small window to achieve high frame rate.

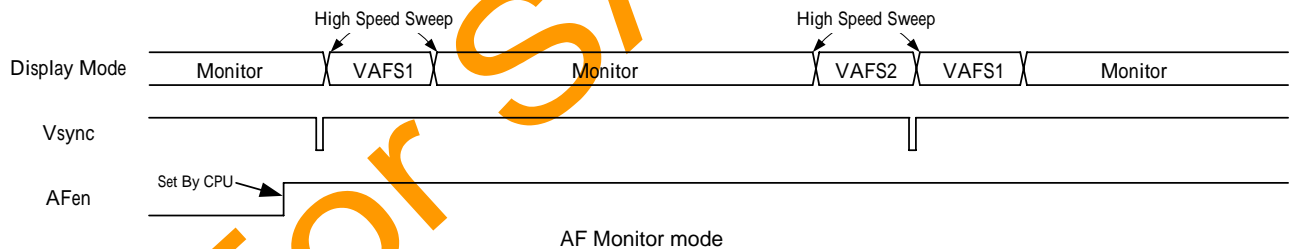
**Mode 3:** AF Capture mode, the timing generator enters this mode if *Afen* (0x2B00[2]) is set in Capture mode. This mode is used to capture the data with a higher frame rate by cropping part of the lines.



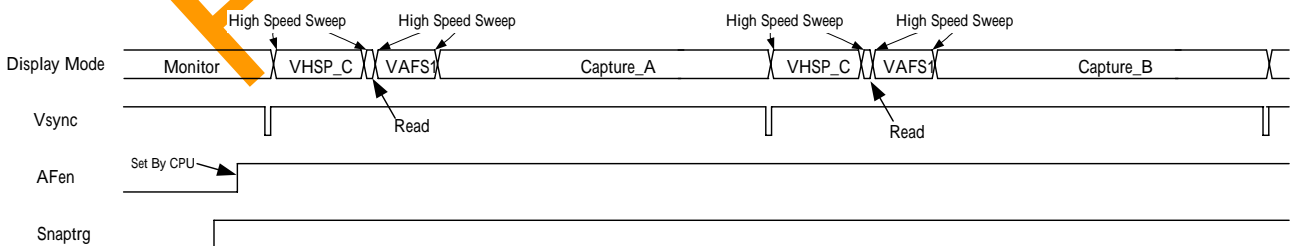
From monitor mode to capture mode for interlace CCD Sensor



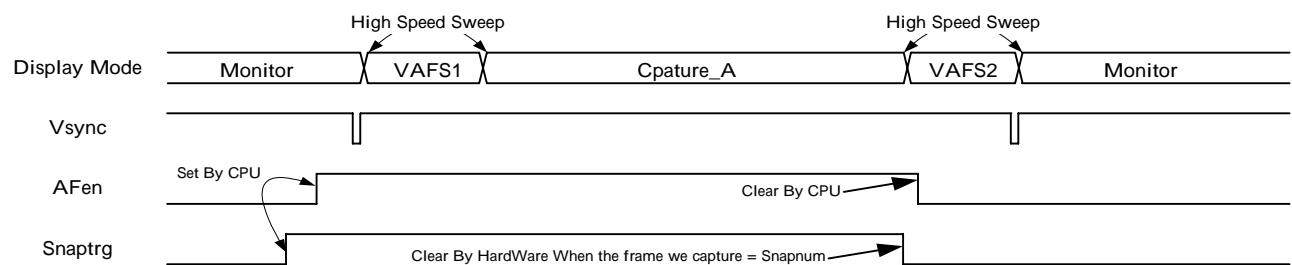
From monitor mode to capture mode for Progressive CCD Sensor



AF Monitor mode



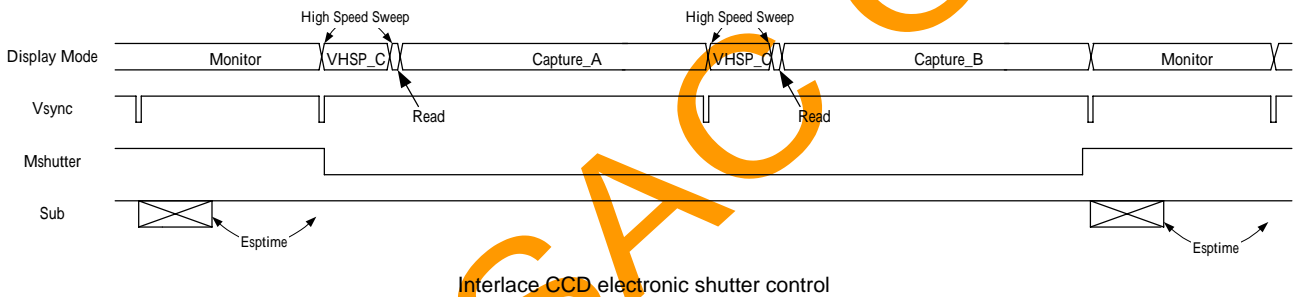
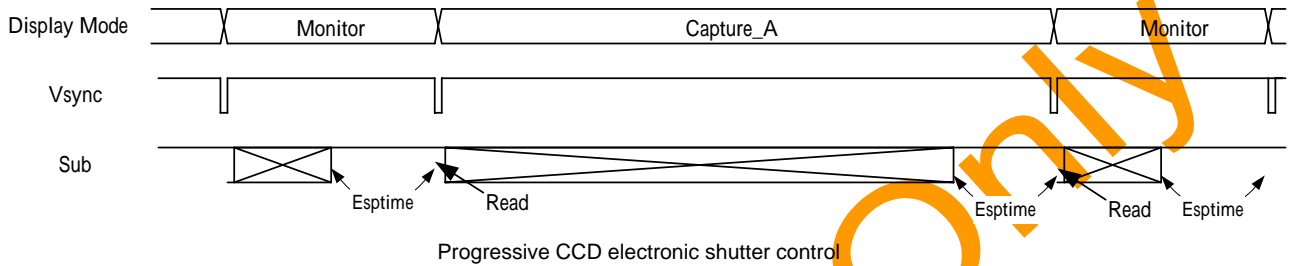
AF Capture mode for interlace CCD Sensor



AF Capture mode for Progressive CCD Sensor

1.12.2 Electronic shutter control

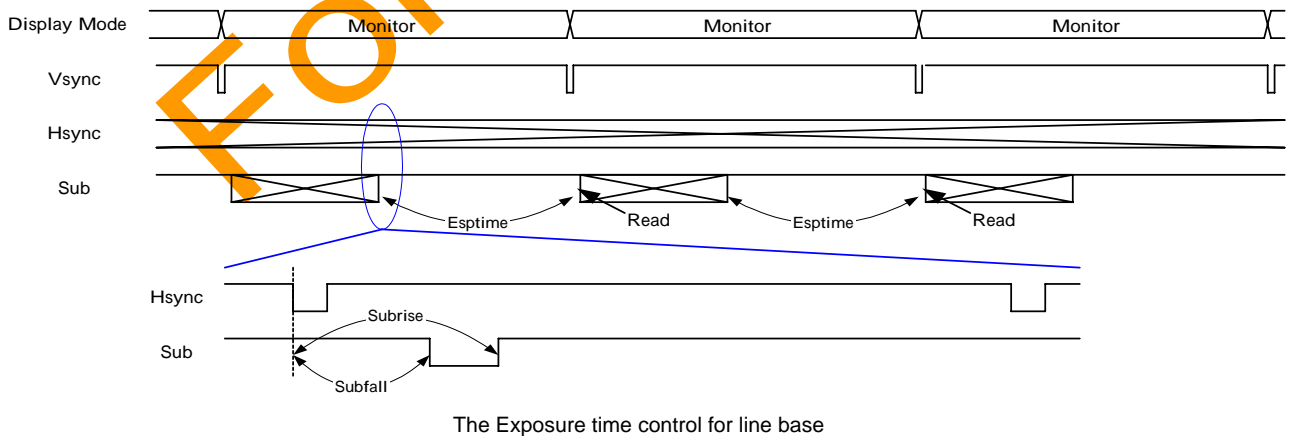
The electronic shutter is used to control the exposure time for the CCD sensors.



There are four methods to adjust exposure time in the SPCA533.

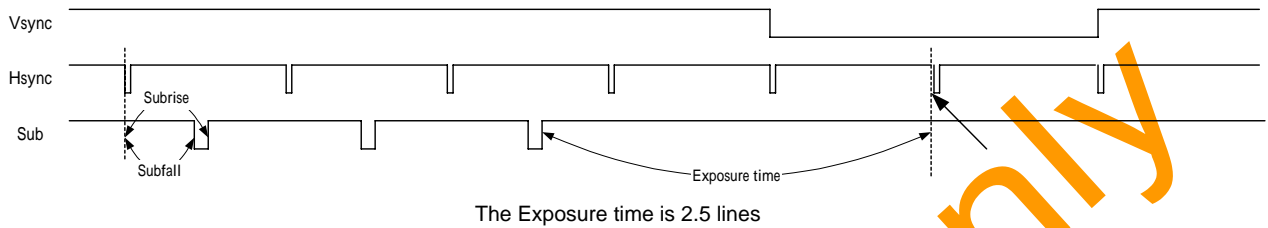
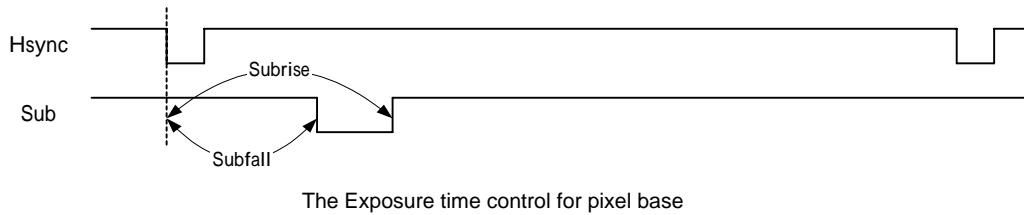
1. Adjusting the exposure time based on line:

Set Esptime (0x2B0B, 0A) to determinate the exposure time unit by line.



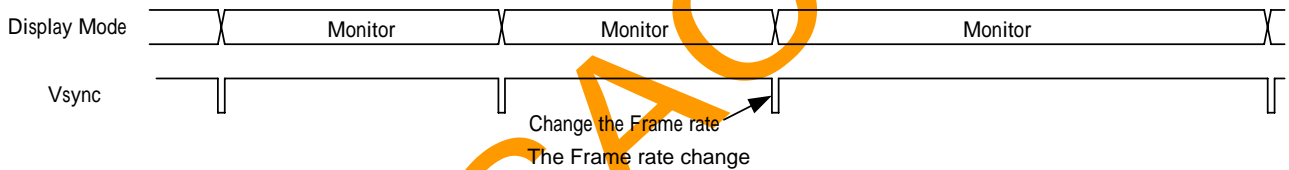
2. Adjusting the exposure time based on pixel:

Adjust subrise (0x2B24, 23) and subfall (0x2B26, 25) can change the exposure position unit by pixel.



3. Adjust the exposure time by extending a frame:

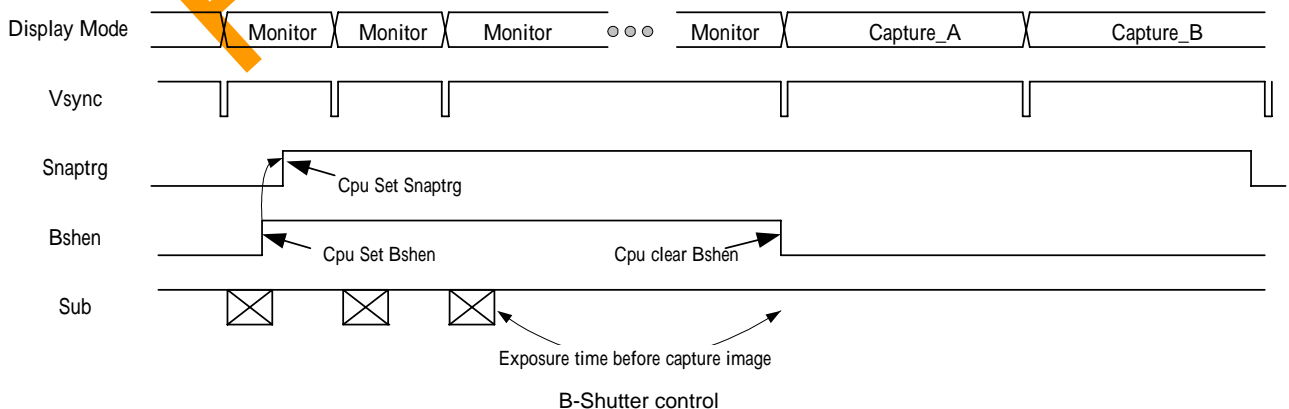
Usually a frame time (monitor mode) is 1/30 ms (for 60 Hz power system), 1/25 ms (for 50Hz power system), when the exposure time of over 1/30 ms is required, the users can set Extclk2xdiv (0x2A82) and Clk2divsvden (0x2A80[1]) to change the frequency of the pixel clock to derive a longer frame time.



(Note: To avoid the flicker under a fluorescent light source, the frame rate must be equal to  $1/120 * N$  in the 60Hz power system, and  $1/100 * N$  in the 50Hz power system.)

4. B-Shutter function:

The B-Shutter function allows the users to extend the exposure time as long as required. Setting *Bshen* (0x2B07[5]) to 1 enables this function, and clear this bit stops exposure. *Bshen* bit must set before *Snaptrg* bit is set



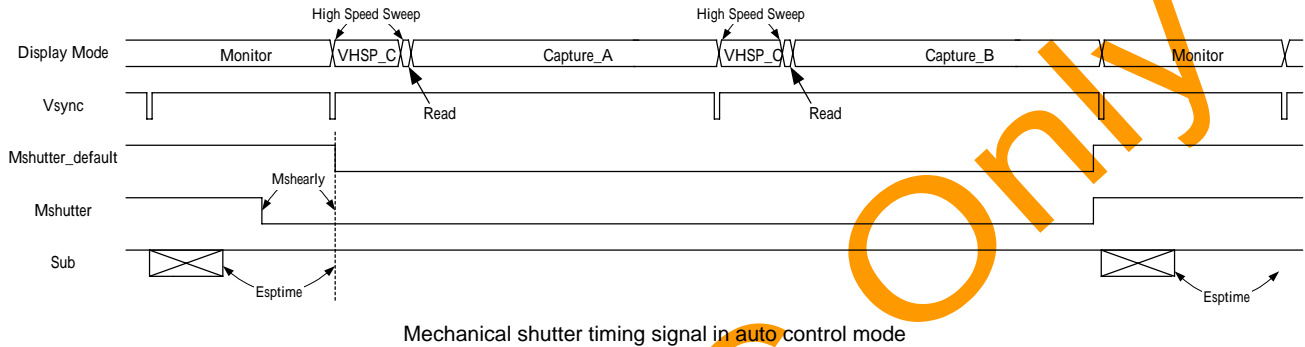
1.12.3 Mechanical shutter control

In the application with an interlace-type CCD sensor, the mechanical shutter is indispensable. The mechanical shutter control signal can be generated by two methods.

**Manual control:** Set Mshmanuen (0x2B07[4]) = 1, and Mshvalue (0x2B07[0]) to decide the Mshutter signal value.

In this mode, the firmware controls the mechanical signal like a GPIO.

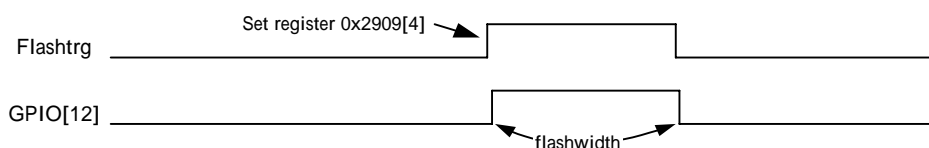
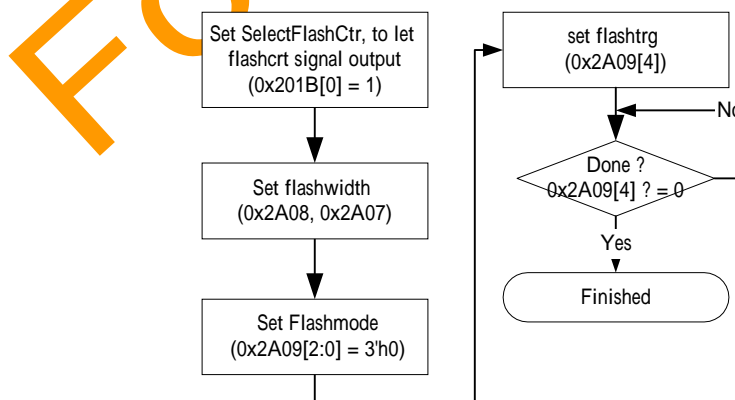
**Auto Control:** Set Mshmanuen (0x2B07[4]) = 0, and Mshearly (0x2B08) for Mechanical shutter delay (based on number of lines), register *Mshutterpol* (0x2B12[3]) set the polarity of the mechanical shutter control signal. The mechanical shutter delay is defined to compensate the response time of the mechanical shutter. The exact value must be characterized at camera manufacturing stage.



#### 1.12.4 Flash light control for the CCD sensor

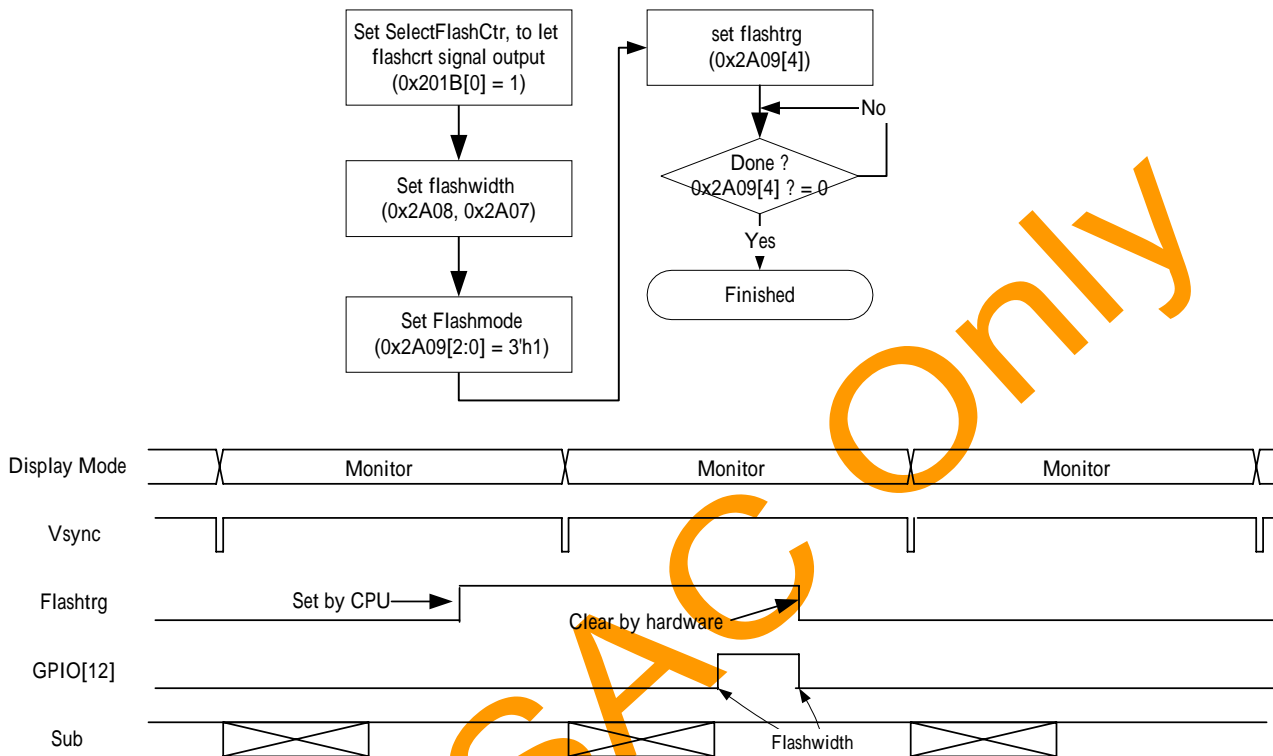
The SPCA533A supports five types of flashlight control timings. The period of the flashlight-triggering signal is programmable based on two-pixel clock time. For example, if the frequency of the pixel clock is 20 MHz, setting *flashwidth* register to 500 results in a 50us flash period.

**Immediate mode:** This mode could be used to eliminate red eyes. In this mode, the flash control signal (multiplexed with GPIO12) outputs a pulse immediately after register 0x2A09[4] is set.

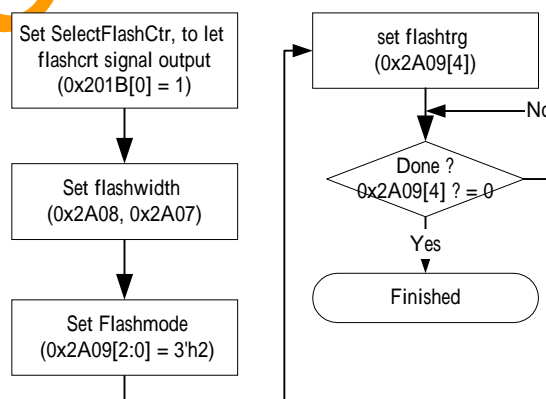


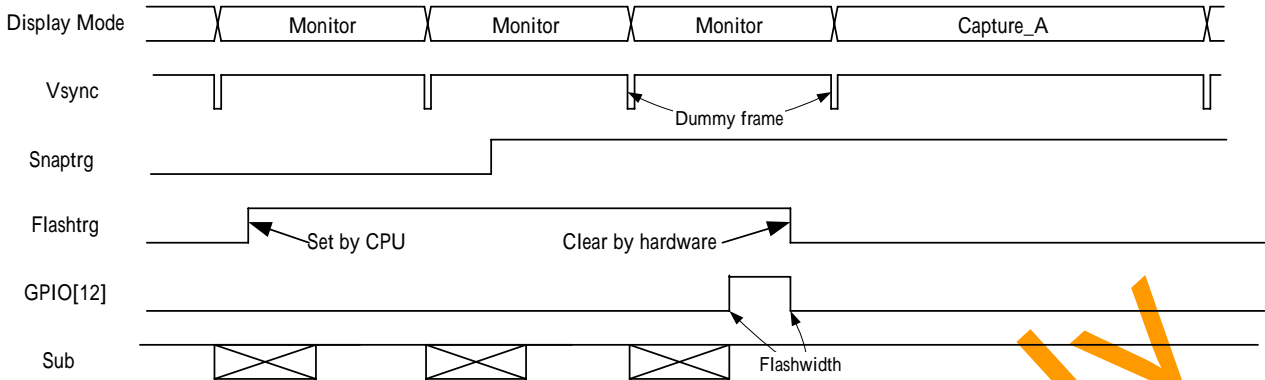


**Synchronize-to-sub mode:** This mode could be used in distance (or luminance) measurement. The output pulse is delayed to the exposure period of the CCD sensors.

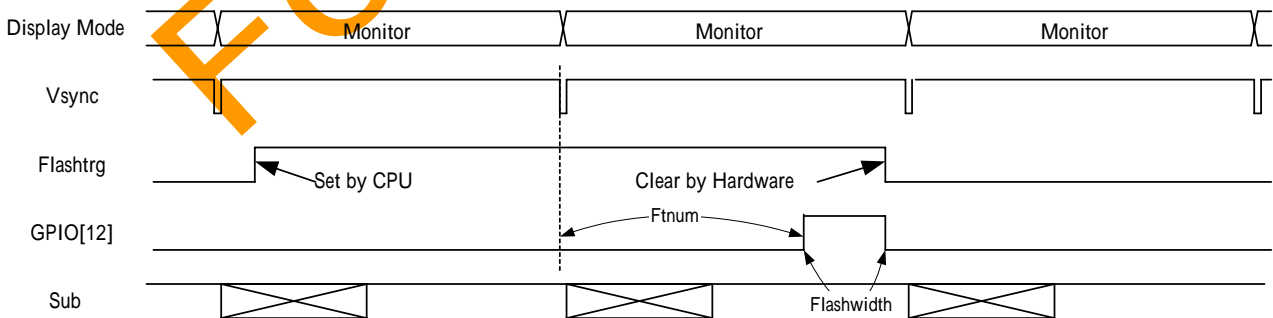
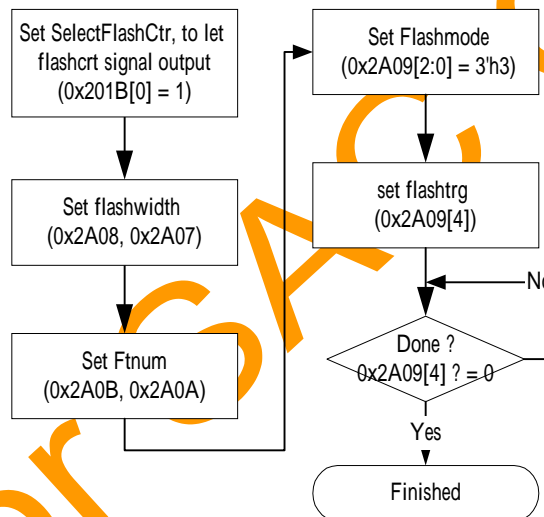


**Synchronize-to-capture mode:** This mode is used in image capture. The *flashtg* register must be set before the *snaptg* register being set. The flash light pulse is asserted at the exposure period of the exposure frame. The exposure frame is the last dummy frame before CCD data transfer.

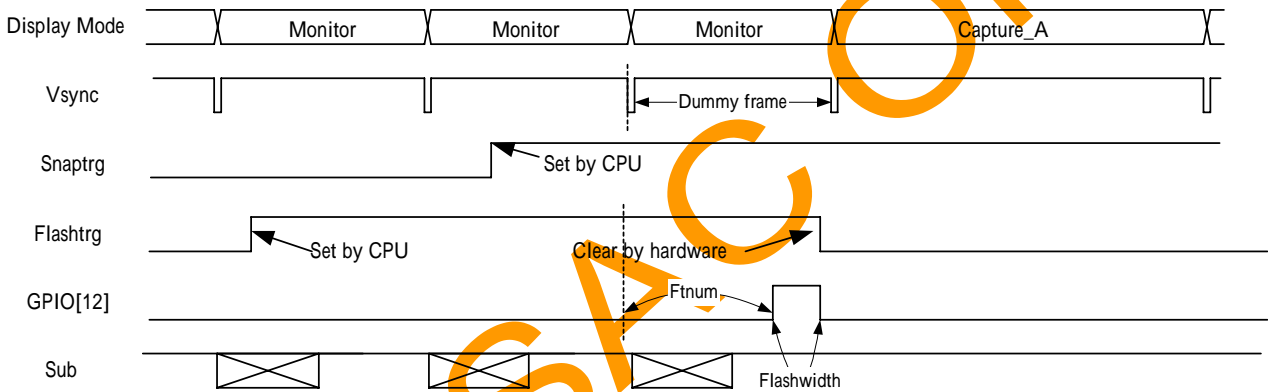
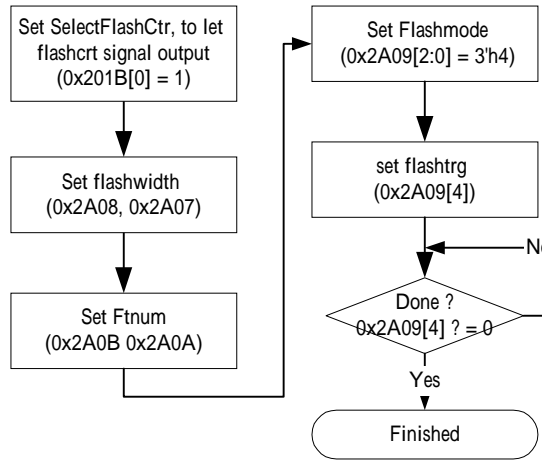




**Synchronize-to-Ftnum mode:** This mode is more flexible than *Synchronize-to-sub mode*. The users need to calculate the timing and set *Ftnum* register (0x2A0B and 0x2A0A). It allows the user to assert the flash pulse at any time in a frame. The *Ftnum* represents the number of lines after Vsync signal's falling edge.



**Synchronize-to-Ftnum in capture mode:** This mode is the same the *Synchronize-to-Ftnum mode* except that it is operated in the full frame capture.

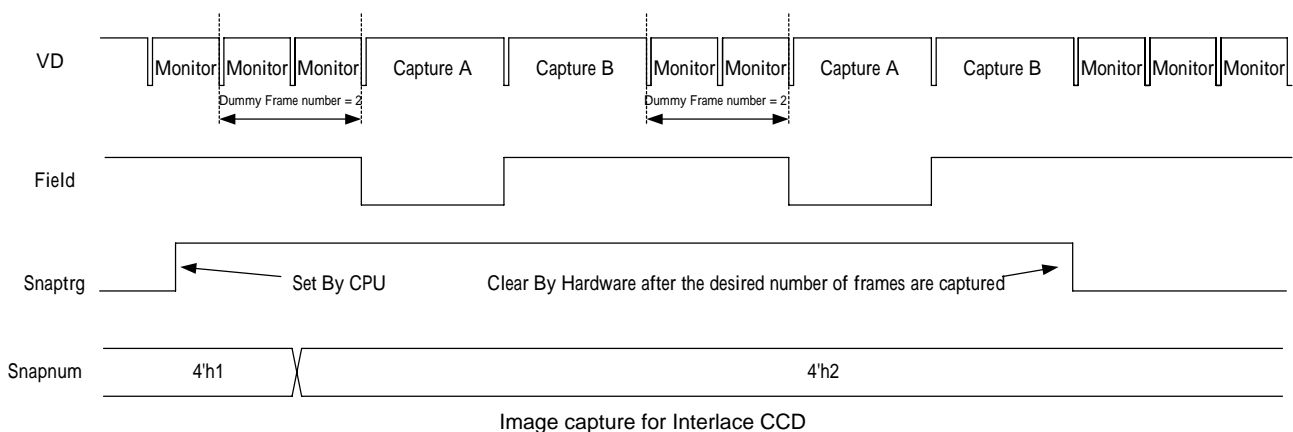
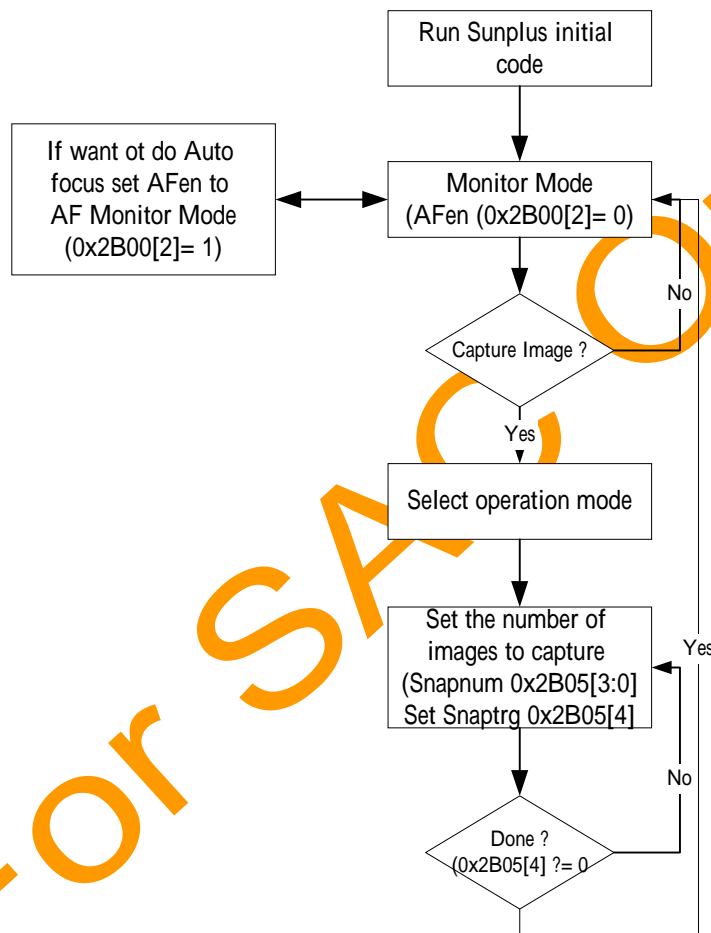


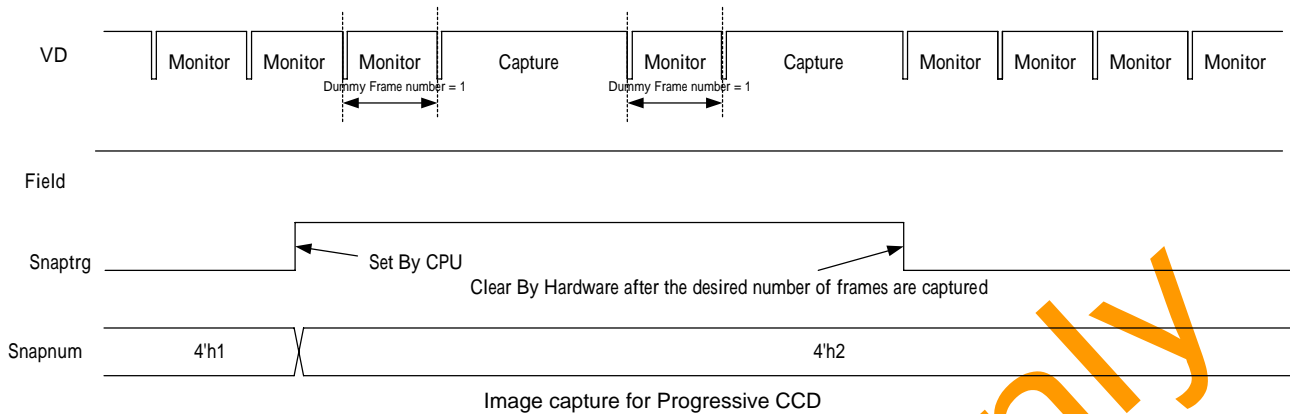
For SWG Only

### 1.12.5 Image capture

When the SPCA533A is operated with a CCD sensor, the default operating mode of the CCD is monitor mode. The full frame image capture is started by setting the *snaptrg* register (0x2B05[4]). The *snapnum* register (0x2B05[3:0]) defines how many frames are going to be captured. The *Dufenum* register (0x2B06[1:0]) defines the number of the dummy frames before capture. Note that the last dummy frame is the sensors' exposure frame. The value of the *Dufenum* register is defined in the CCD sensors' specification.

Image captures flow

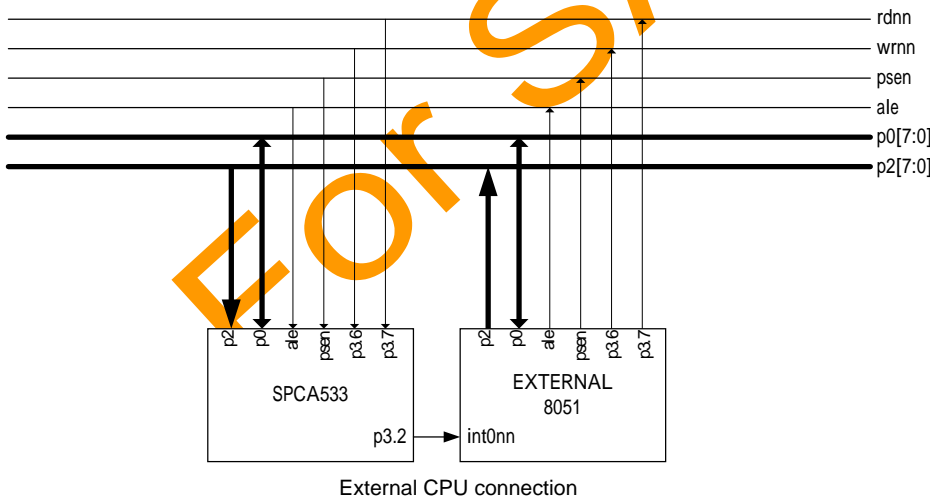




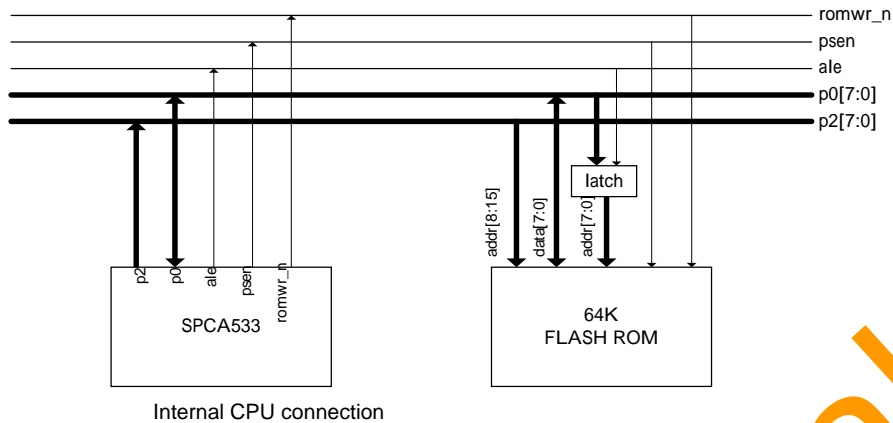
### 1.13 Embedded micro-controller

#### 1.13.1 Hardware interface

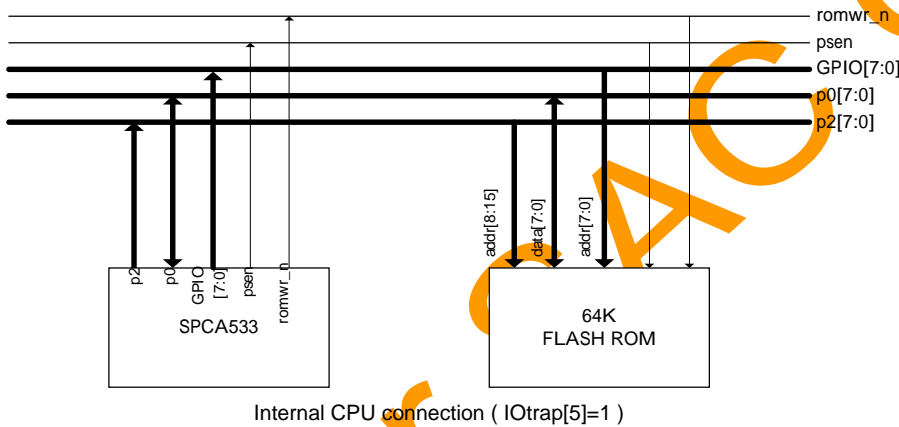
The operation flow of the SPCA533A is controlled by an embedded 8032-compatible CPU. It is also possible to control the SPCA533A via an external 8032 ICE during firmware development. Whether to use an external or an internal CPU is determined at the power-on stage of the SPCA533A via IOTRAP[0]. If IOTRAP[0] is 1, the external CPU is selected. Otherwise, the internal CPU is enabled. The following diagram shows the interface connection of the SPCA533A to an external CPU (ICE).



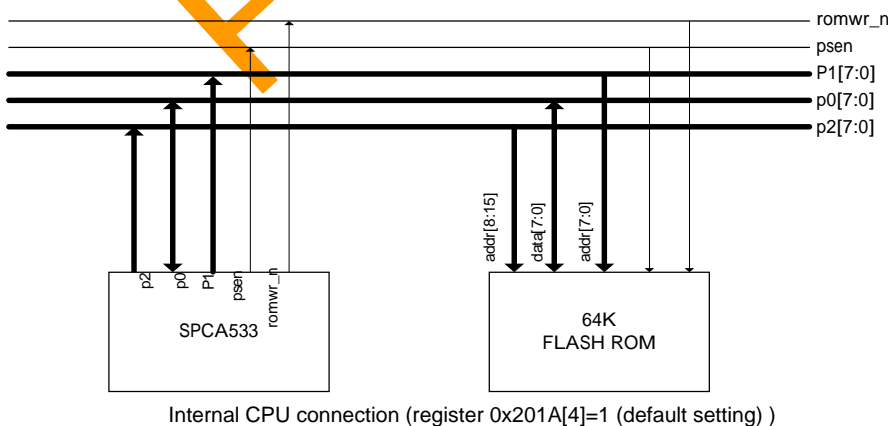
While the internal CPU option is chosen, the firmware must be stored in an external ROM. As the 8032 CPU multiplexes low-byte address bus with the data bus, there must be an external latch to latch the low-byte address. The interface connection is shown in the following diagram.



To reduce the cost the system design, the latch of the low-byte address can be removed if IOTrap[5] is 1. When IOTrap[5] is set to 1, the GPIO[7:0] output the low-byte address of the ROM. See the following diagram.



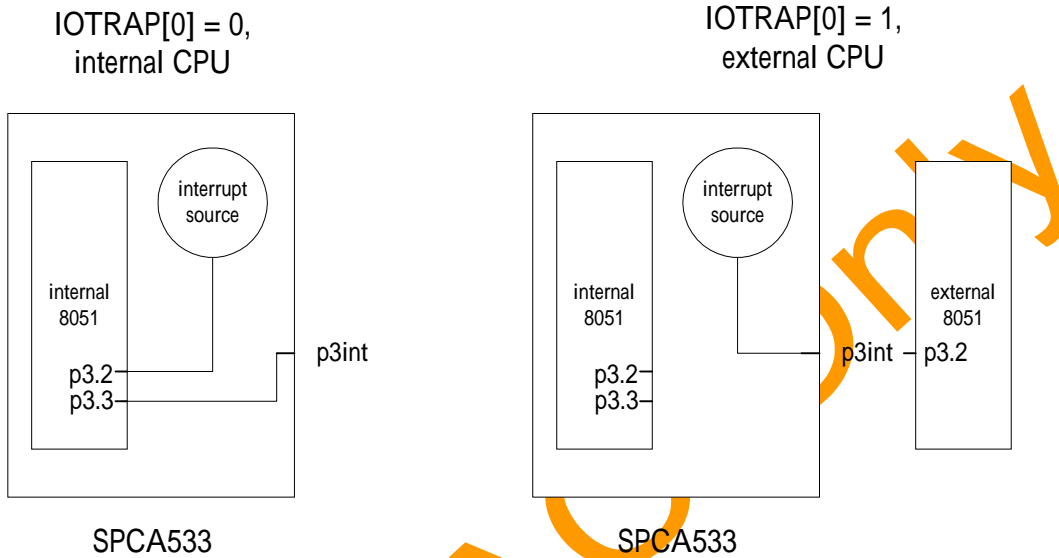
The default setting of P1[7:0] in the SPCA533A is low-byte address too. P1[7:0] output the low-byte address of ROM. See the following diagram. P1[7:0] can be changed to general purpose IO pins If register 0x201A [4] is set to 0.



The 64K-byte program space provided by a standard 8032 CPU might not be sufficient for a complex camera design. The SPCA533A can extend the program space up to 1M bytes. More ROM address pins are needed when the ROM size is over 64K-byte. GPIO[11:8] is selected as ROMaddr[19:16] by default. These pins output all 0's after power-on. If the address bits are not necessary (ROM size under 64K bytes), these pins can be changed to general purpose IO pins via register 0x201A[3:0] after power-on.

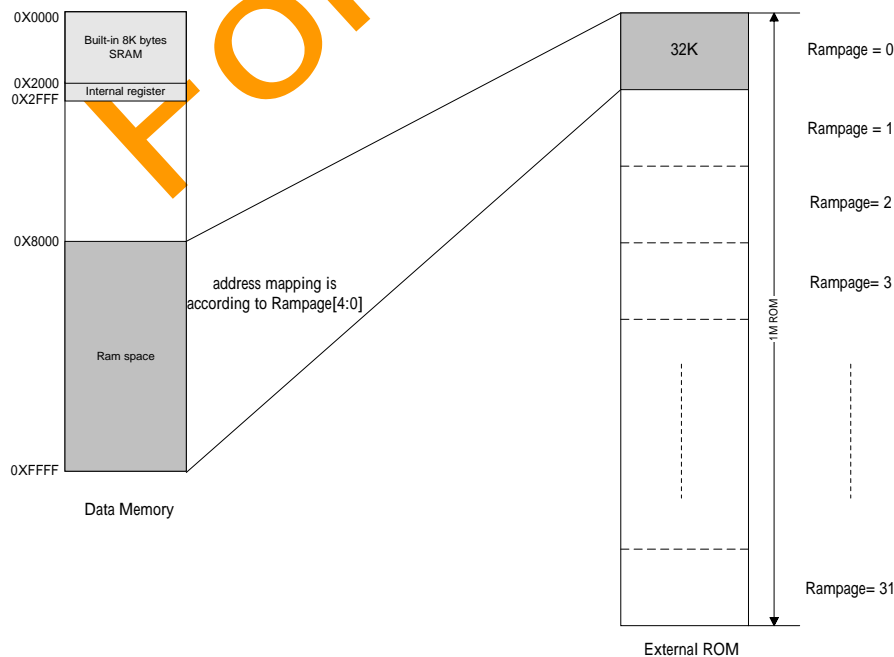
**Multi-function pin 'P3INT'**

When IOTRAP[0] = 0, the pin 'p3int' is connected to the embedded 8051 P3.3. However, if IOTRAP[0] = 1, the pin 'p3int' is connected to the internal interrupt event. To make ICE function works the same way as embedded 8051, 'p3int' have to be connected to external P3.2. The interface is shown below.



**1.13.2 RAM space**

The 8032 CPU can address up to 64K-byte memory. SPCA533A has built-in an 8K-byte SRAM which occupies the lowest 8K-byte address space. From address 0X2000 to 0X2FFF is 4K-byte space reserved for the camera control. The upper 32K-byte space, from address 0X8000 to 0XFFFF, can be remapped to the ROM space to access ROM data directly. All the unused space can be used by the external device with additional decoding circuit.



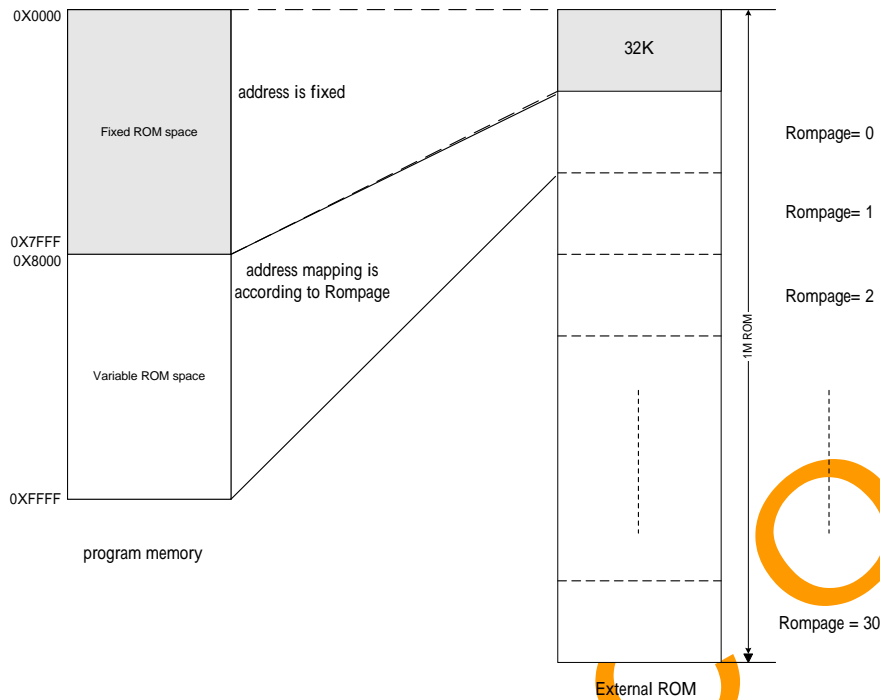
The embedded 8K-byte SRAM is partitioned to low 4K-byte(address 0X0000 ~ 0X0FFF) and high 4K-byte (address 0X1000 ~ 0X1FFF). Setting register 0X2C00[0] to 1 will enable the low 4K-byte SRAM. Setting register 0X2C00[1] to 1 will enable the high 4K-byte SRAM. While the low 4K-byet SRAM can only be accessed via the corresponding address space, the high 4K-byte SRAM have three access modes. The mode register is in register 0X2C11[1:0]. When 0X2C11[1:0] is set to 0, the CPU can access this SRAM via address space 0X1000 to 0X1FFF. When 0X2C11[1:0] is set to 1, the CPU access this SRAM via the data port 0X2C10. The address of SRAM is automatically incremental by one each time the CPU accessed the data port. This will speed up the firmware execution because the the address increment is done by hardware. Setting register 0x2C11[2] will reset the address to initial address (register 0x2C12 , 0x2C13). When 0X2C11[1:0] is set to 2, the CPU cannot access the SRAM. The SRAM access right is granted to the DMA controller in this mode. This will allowed a fast data swap between the high 4K-byte SRAM and other DMA clients. For example, to swap the data between the DRAM and SRAM. This feature is useful especially when the firmware needs to construct the FAT in the DRAM. The DRAM in an SPCA533-based application can only be accessed by an indirect addressing method. It is relatively slow comparing with access to the SRAM.

Address 0X8000 to 0XFFFF can be mapped to the ROM space if register 0X2C00[2] is set to 1. This feature allows the CPU to access the contents of the external ROM via the RAM space. The size of this space is 32K-byte, which corresponds to a ROM bank. Which bank of the external ROM will be mapped to this RAM space is determined by RAMpage register (**SFR 8'h9B**). As the SPCA533A support up to 1M-byte ROM space, there are 32 banks to be chosen. In a typical application, the OSD font or some graphic icons are placed in the higher banks of the external ROM. It is more convenient to access the data via the RAM space. Another application of this feature is when the firmware needs to be updated. The CPU can write the external ROM (flash-type) via this RAM space. This ISP (In-system-programming) function will be described more later.

### 1.13.3 ROM space

The SPCA533A supports 1M-byte physical programming space by bank-switching method. The 1M-byte space is partitioned into 32 banks. The size of each bank is 32K-bytes. The size of the logical space of the 8032 is only 64K-byte. The first bank of the logical programming space(address 0X0000~X7FFF) is mapped to the physical ROM address 0X0000 to 0X7FFF. The second bank of the logical programming space can be mapped to any bank of the physical ROM space if register 0X2C00[3] is set to 1. ROMpage (**SFR 8'h9A**) determines which bank to be mapped. By using this bank-switching approach, the programming space is extended to 1M-byte. The following diagram shows the ROM space mapping method.





Depending on the size of the external ROM, extra address pins should be connected to the external ROM. The extra ROM address pins are shared multiplexed with the GPIO[11:8]. The function of these pins must be set right after power-on. The SPCA533A assume 1M-byte external ROM is selected by default. The following table shows the pin configuration for different ROM sizes. The function selection is controlled by register 0X201A[3:0]

ROM size (bytes)	Pin function			
	GPIO[11]	GPIO[10]	GPIO[9]	GPIO[8]
64K	GPIO	GPIO	GPIO	GPIO
128K	GPIO	GPIO	GPIO	Romaddr[16]
256K	GPIO	GPIO	Romaddr[17]	Romaddr[16]
512K	GPIO	Romaddr[18]	Romaddr[17]	Romaddr[16]
1M	Romaddr[19]	Romaddr[18]	Romaddr[17]	Romaddr[16]

### 1.13.4 ISP (In-system-programming)

The In-system-programming is achieved by downloading a new version of firmware and writing it to the external flash-type ROM. The key concept of the ISP is to shadow the ISP firmware code to the RAM space before updating the ROM. While updating the ROM code, the CPU execute the program from the SRAM. The shadow space is fixed at 4K. This means the size of the shadow program must be under 4K-byte. Normally the source of the new code is sent by a PC via the USB Bulk pipe, so the ISP firmware code must include the USB-processing part. The ShadowMap register (0X2C01[7:0]) determined which section of program is to be shadowed. The default is to shadow the lowest 4K-byte.

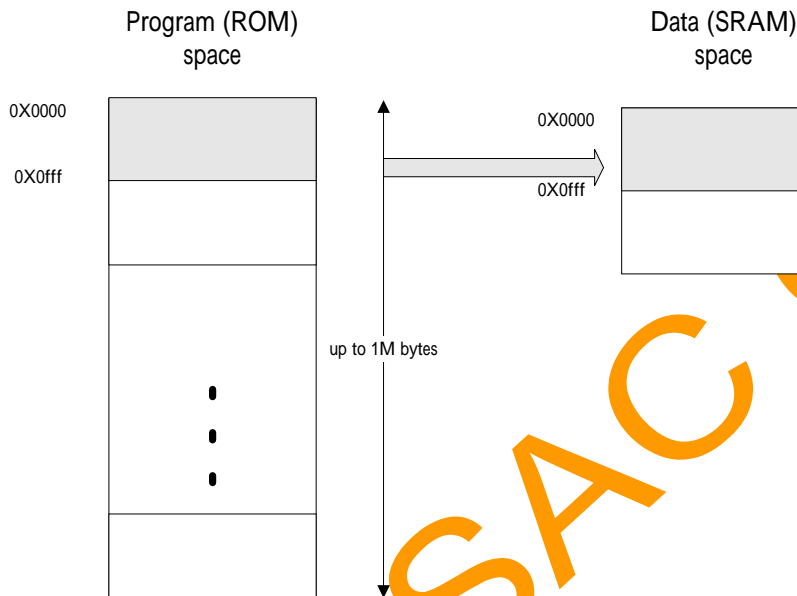
The ISP procedures is described below.

1. Moving the ISP section of program to the SRAM (from ROM),

The SRAM shadow space is from address 0x0000 to 0x0fff. So the user must move the code into this region.

2. Enable shadow function. ( register 0x2C00[4] )
3. Jump to the starting address of the shadow area. Hereafter, the CPU will execute the program from the SRAM, instead of the ROM. The SPCA533A transforms the ROM read cycle to SRAM read cycle when the access address hit the shadow space and the shadow function is enabled.
4. The CPU executes the ISP firmware code, which update the external ROM's contents.
5. Disable shadow function.

The following diagram shows the default mapping of the shadow space.



### 1.13.5 The difference between the standard 8032 and the embedded 8032

The standard 8032 uses open-drained IO buffers. The embedded 8032 CPU does not implement the pull-up mechanism on all CPU-related pins. To be compatible with the standard 8032, the external pull-up resistors must be connected to P1 and P3[5:0]. P0 of the CPU interface will be driven high (or low) when the CPU needs to output data. P3[6], P3[7] and P2 of the CPU interface is always driven by the SPCA533A in embedded 8032 operation mode.

For P1 and P3[5:0], the SPCA533A has implemented an alternative approach, which drives P1 and P3[5:0] all the time. The external pull-up resistors can be spared. This is controlled by register 0x2C02 and 0x2C03. When these registers are set to 1, the corresponding pin is a general purpose output. To use these pins as general purpose inputs, the corresponding registers must be set to 0 and the corresponding special function register must be set, too. For example, if P1[7:1] is used for output pins, P1[0] is used input. Fill 0x2C02 as 8'b11111110 and SETB P1.0.

### 1.13.6 Suspend state power control of CPU

In suspend state, embedded 8032 clock is stopped. Before that, the CPU related pin must be programmed in the appropriate state to save power. The powerdown bit (register 0x2C05[0]) is used for shutting down the external ROM while suspend asserted. The related setting and pin state of CPU in suspend mode is described below. Note that ROM low byte address can be driven from GPIO[7:0] or P1[7:0] and connect with the external ROM by configuration of IOtrap[5] or programming the register 0x201A[4].

	Powerdown = 0 (register 0x2C05[0]=0)	Powerdown = 1 (register 0x2C05[0]=1)
Ale	LOW	LOW
Psen	HIGH	LOW

Romwr_n	HIGH	LOW
P3[6]	HIGH	HIGH
P3[7]	HIGH	HIGH
P0[7:0]	State at suspend signal asserted	LOW
P2[7:0]	State at suspend signal asserted	LOW
P1[7:0]	Programmable via ( <b>SFR</b> 8'h90, 0x2C02, 0x201A[4])	Programmable via ( <b>SFR</b> 8'h90, 0x2C02, 0x201A[4])
P3[5:0]	Programmable via ( <b>SFR</b> 8'hB0, 0x2C03[5:0])	Programmable via ( <b>SFR</b> 8'hB0, 0x2C03[5:0])
Low byte address[7:0]	State at suspend signal asserted	LOW

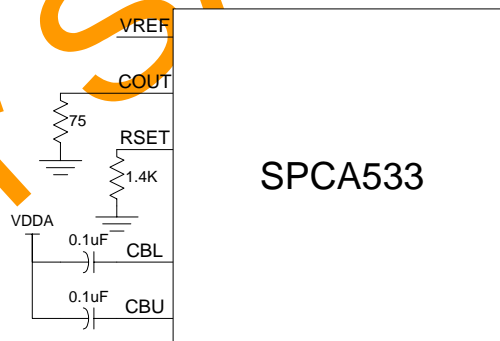
### 1.14 TV output interface

The SPCA533A supports a wide range of display devices, including analog TV output, digital TV output, TFT LCD interface and STN LCD interface. The type of the display devices can be selected by registers 0X2D00. To fit the resolution of the display device the SPCA533A has built-in the scaling function in the LCD/TV interface controller. The firmware of the SPCA533A is obligated to change scaling factors whenever the display device changes.

While connecting to GRAINTPLUS STN-LCD or PRIME VIEW TFT LCD, the tvenc1xck clock must be change to 27MHz (register 0X201C). It is different from another interface.

#### 1.14.1 Analog TV interface (tvdspmode=0~1, register 0X2D00)

The built-in TV encoder of the SPCA533A can generate standard NTSC and PAL composite video signals. The SPCA533A has also built-in a video DAC for the TV signal output. During operation, the DAC consumes about 30mA current. It is important to turn off the DAC while it is not in operation. The DAC can be turned on by setting register 0X2001. The application circuit of the DAC interface is shown below.



#### 1.14.2 Digital TV interface

In this chapter, we discuss the digital TV interface including the CCIR601, CCIR656, UPS051, STN-LCD, CASIO, VGA TFT-LCD and EPSON interface.

##### 5.14.2.1 CCIR 656 interface (dspmode=2~3, register 0X2D00)

The CCIR656 digital video protocol does not transmit the whole horizontal blanking interval. Instead, it inserts a special four-word codes into the digital video stream to indicate the start of active video (SAV) and end of active video (EAV). These EAV and SAV codes indicate when horizontal and vertical blanking are present and which field is being transmitted, enabling most of the horizontal blanking interval to be used to transmit ancillary data such as line numbering, digital audio data, error checking data, and so on. When this mode is selected, the SPCA533A encodes the video stream by inserting SAV and EAV code to the video data stream, no ancillary data is encoded. The data bus is 8-bit wide.

#### 5.14.2.2 CCIR 601 interface (tvdspmode=4-7, register 0X2D00)

In this display mode, a 16-bit data bus is used. Digtv[7:0] transmits the luminance data and Digtv[15:8] transmits the chrominance data.

RGB2YCbCr matrix:

$$Y = (77/256)R + (150/256)G + (29/256)B$$

$$Cb = -(44/256)R - (87/256)G + (131/256)B + 128$$

$$Cr = (131/256)R - (110/256)G - (21/256)B + 128$$

YCbCr2YUV matrix:

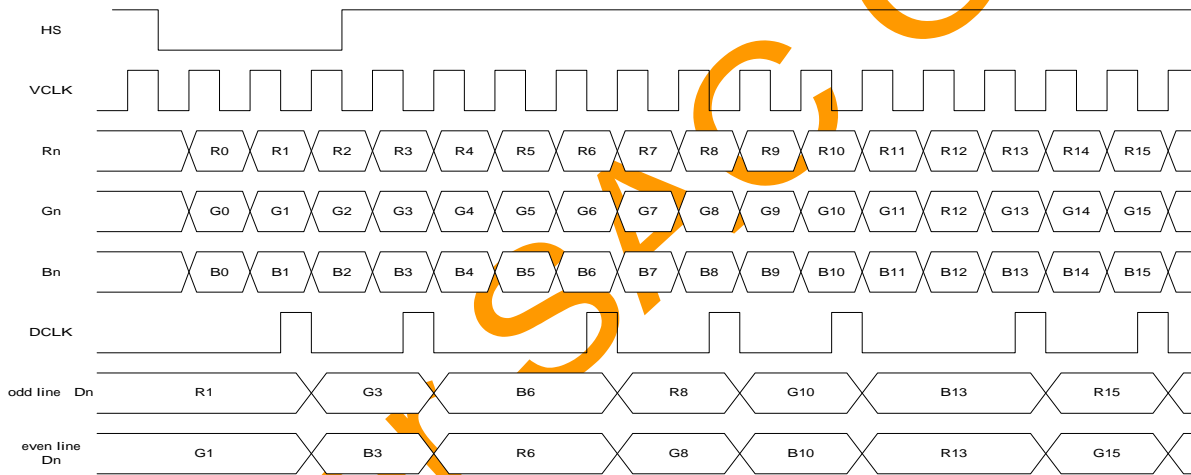
$$Y = (1/2)(Y-16) + (1/8)(Y-16)$$

$$U = (1/2)(Cb-128) + (1/32)(Cb-128)$$

$$V = (1/2)(Cr-128) + (1/4)(Cr-128)$$

#### 1.14.2.3 Unipac UPS051 (TFT-LCD interface, dspmode=8, register 0X2D00)

SPCA533A can interface to the Unipac's UPS051 LCD controller, which in turns, drives Unipac's TFT LCD panel. The following diagram shows the interface timing.



#### 1.14.2.4 EPSON D-TFD LCD interface (tvdspmode=10, register 0X2D00)

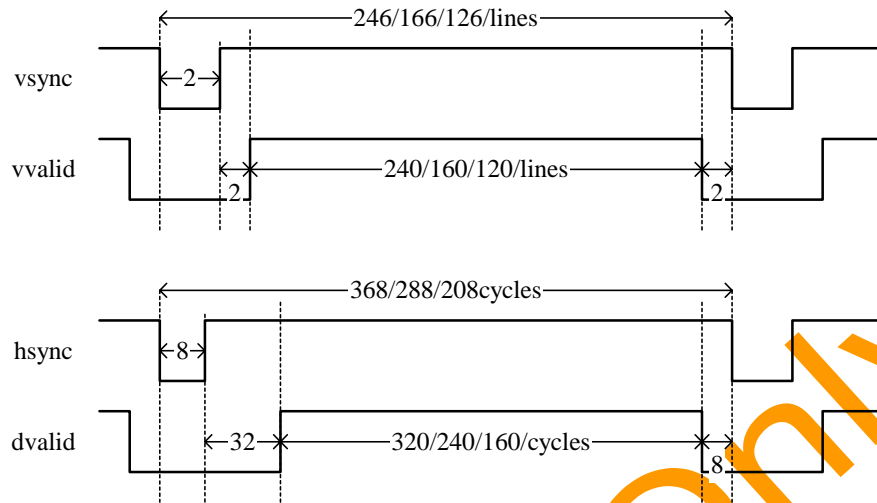
SPCA533 had build in em1812b for control of the D-TFD liquid crystal panel module LF18DB series. The D-TFD liquid crystal panel block uses active matrix panel. By the way, SPCA533A need extra control circuit for driving the panel module. And SPCA533A is not equipped with an inverter for driving the backlight module. Register 0X2D02-0X2D0F must be redefined reference as section 5.14.2.8. The resolution of EPSON LCD panel is 312 (horizontal) X 230 (vertical) dots.

#### 1.14.2.5 CASIO TFD LCD interface (tvdspmode=11, register 0X2D00)

The driving timing has 263 lines per frame and 858 pixel per line. To prevent display retention, please set up stand-by mode or cut off the power after writing white display data at least 2 field. (Register 0X2D25, bit 4) After power-on, the GRES must be kept low for at least 2 field periods while sending normal signals to the other inputs. (Register 0X2D25, bit 5)

#### 1.14.2.6 GIANTPLUS STN-LCD interface (tvdspmode=12, register 0X2D00)

SPCA533A support multiple resolution STN-LCD panel including 320x240, 240x160 and 160x120. In other words, register 0X2B02-0X2B0F must be programmable. The timing diagram of STN-LCD had shown in below. However, its frame rate depends on the register setting. You can insert a few pixels in vsync or hsync interval to reduce the panel frame rate.



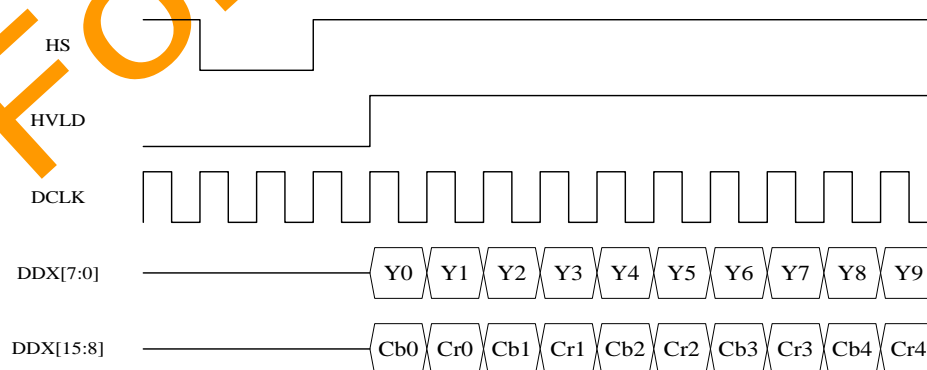
#### 1.14.2.7 PRIME VIEW TFT-LCD interface (tvdspmode=14, register 0X2D00)

The timing of the control signals is compatible with VGA-480, VGA-400, VGA350 and free format. The color depth is 6 bits, which can display 262144 colors at the same time. And the polarization of Hsync and Vsync determine the timings, following table as shown the definition of PRIME VIEW TFT-LCD panel. As the color depth is only 6 bits, there might be contours in the displayed image. The SPCA533A has implemented a dithering option in the LCD controller to enhance the image quality (register 0X2D2B, bit 1). The operating clock tvenc1xck must be set to 27MHz (register 0X201C). Lower frequency will cause image flicker.

	VGA-480	VGA-400	VGA-350	Freedom mode
Hsync Polarization	Negative	Negative	Positive	Positive
Vsync Polarization	Negative	Positive	Negative	Positive

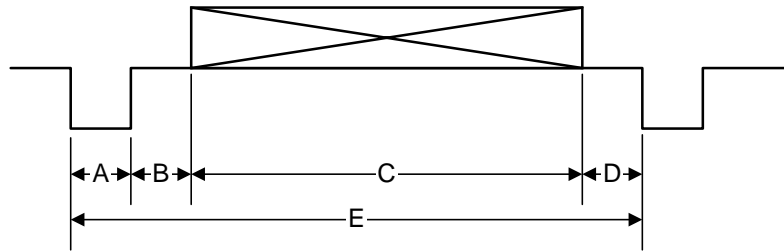
#### 1.14.2.8 User define output interface (tvdspmode=15, register 0X2D00)

User can define the special timing. When the tvdspmode=15, the timing will be controlled by user define. The horizontal pixels and vertical lines are defined in register (0X2b02~0X2B07). So the frame rate is programmable. And the color space is compatible with H.261 (YCbCr). The luminance (Y) is defined in DDX0~DDX7, and the chrominance (Cb/Cr) is defined in DDX8~DDX15. The timing diagram is shown as below.



#### 1.14.2.9 Horizontal and Vertical Timing and Corresponding Register

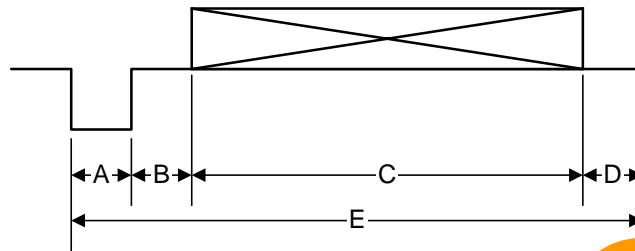
Detail of horizontal timing:



mode	Item	Description	Clock Cycles	Time	register
NTSC (analog & CCIR)	A	Horizontal Width	63	4.66 $\mu$ s	hsyncw=63(default)
	B	Horizontal B-porch	65	4.81 $\mu$ s	vldx0=128
	C	Horizontal Display	720	53.28 $\mu$ s	vldx1=847
	D	Horizontal F-porch	10	0.75 $\mu$ s	
	E	Horizontal Total	858	63.5 $\mu$ s	hpixel=857(default)
PAL (analog & CCIR)	A	Horizontal Width	64	4.7 $\mu$ s	hsyncw=64(default)
	B	Horizontal B-porch	64	4.7 $\mu$ s	vldx0=128
	C	Horizontal Display	720	53.28 $\mu$ s	vldx1=847
	D	Horizontal F-porch	16	1.32 $\mu$ s	
	E	Horizontal Total	864	64 $\mu$ s	hpixel=863(default)
UNIPAC	A	Horizontal Width	98	7.26 $\mu$ s	hsyncw=98
	B	Horizontal B-porch	36	2.67 $\mu$ s	vldx0=134
	C	Horizontal Display	689	51.04 $\mu$ s	vldx1=822
	D	Horizontal F-porch	35	2.53 $\mu$ s	
	E	Horizontal Total	858	63.5 $\mu$ s	hpixel=857
EPSON	A	Horizontal Width	32	2.37 $\mu$ s	hsyncw=32
	B	Horizontal B-porch	52	3.85 $\mu$ s	vldx0=84
	C	Horizontal Display	624	46.22 $\mu$ s	vldx1=708
	D	Horizontal F-porch	202	14.96 $\mu$ s	
	E	Horizontal Total	910	67.4 $\mu$ s	hpixel=909
CASIO	A	Horizontal Width	4	0.3 $\mu$ s	hsyncw=4
	B	Horizontal B-porch	18	1.33 $\mu$ s	vldx0=20
	C	Horizontal Display	708	52.44 $\mu$ s	vldx1=728
	D	Horizontal F-porch	128	9.43 $\mu$ s	
	E	Horizontal Total	858	63.5 $\mu$ s	hpixel=857
STN-LCD 320x240	A	Horizontal Width	8	0.3 $\mu$ s	hsyncw=8
	B	Horizontal B-porch	32	1.18 $\mu$ s	vldx0=40
	C	Horizontal Display	320	11.85 $\mu$ s	vldx1=359
	D	Horizontal F-porch	8	0.3 $\mu$ s	
	E	Horizontal Total	368	13.63 $\mu$ s	hpixel=367
STN-LCD 240x160	A	Horizontal Width	8	0.3 $\mu$ s	hsyncw=8
	B	Horizontal B-porch	32	1.18 $\mu$ s	vldx0=40
	C	Horizontal Display	240	8.89 $\mu$ s	vldx1=279
	D	Horizontal F-porch	8	0.3 $\mu$ s	
	E	Horizontal Total	288	10.67 $\mu$ s	hpixel=287
STN-LCD 160x120	A	Horizontal Width	8	0.3 $\mu$ s	hsyncw=8
	B	Horizontal B-porch	32	1.18 $\mu$ s	vldx0=40
	C	Horizontal Display	160	5.92 $\mu$ s	vldx1=199
	D	Horizontal F-porch	8	0.3 $\mu$ s	
	E	Horizontal Total	208	7.7 $\mu$ s	hpixel=207
VGA-480	A	Horizontal Width	96	3.813 $\mu$ s	hsyncw=96
VGA-400					

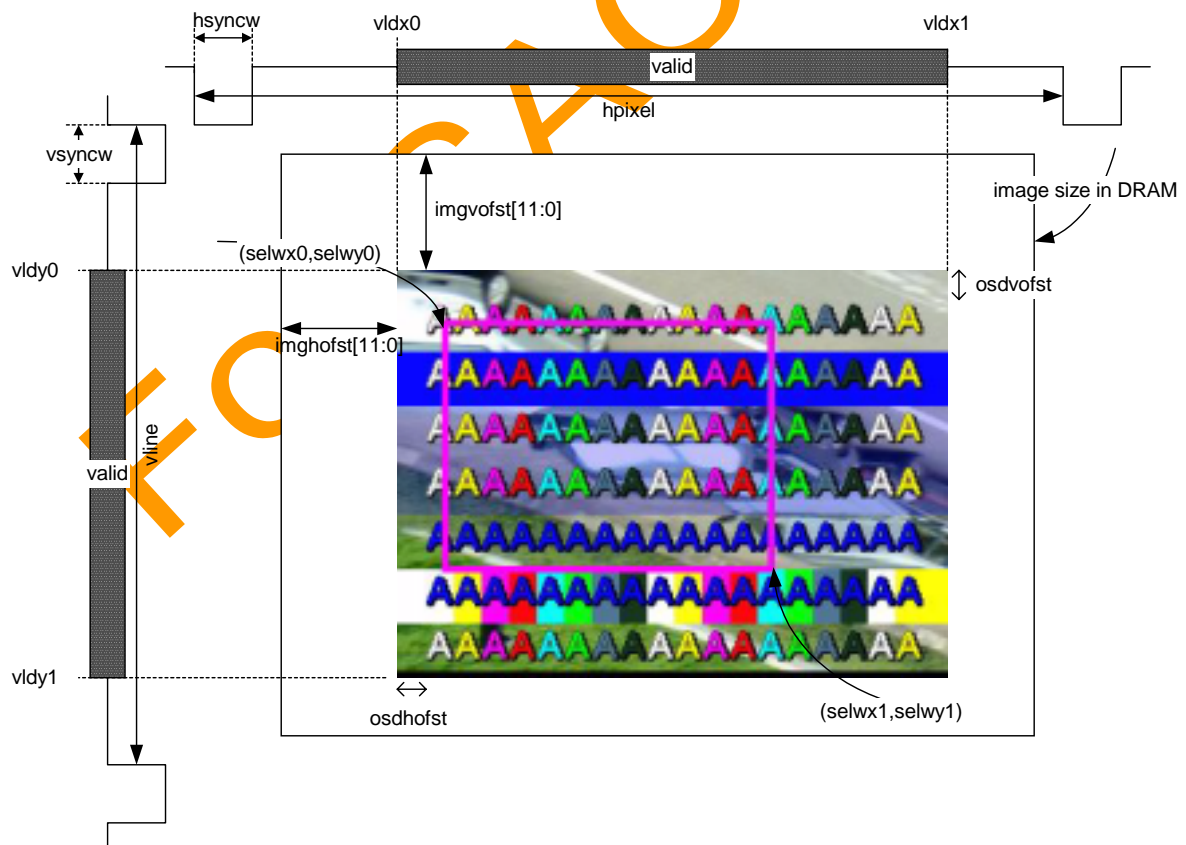
B	Horizontal B-porch	48	1.907 $\mu$ s	vldx0=144
C	Horizontal Display	640	25.422 $\mu$ s	vldx1=783
D	Horizontal F-porch	16	0.636 $\mu$ s	
E	Horizontal Total	800	31.778 $\mu$ s	hpxel=799

Detail of vertical timing:



mode	Item	Description	Horizontal Lines	Time	register
NTSC (analog& CCIR)	A	Vertical Width	3	190.5 $\mu$ s	vsyncw (default)
	B	Vertical B-porch	16	1.02 ms	vldy0=16
	C	Vertical Display	240	15.24 ms	vldy1=255
	D	Vertical F-porch	3.5	219.5 $\mu$ s	
	E	Vertical Total	262.5	16.67 ms	vline (default)
PAL (analog& CCIR)	A	Vertical Width	3	192 $\mu$ s	vsyncw (default)
	B	Vertical B-porch	19	1.22 ms	vldy0=19
	C	Vertical Display	288	18.43 ms	vldy1=306
	D	Vertical F-porch	2.5	158 $\mu$ s	
	E	Vertical Total	312.5	20 ms	vline (default)
UNIPAC	A	Vertical Width	3	190.5 $\mu$ s	vsyncw=3
	B	Vertical B-porch	25	1.59 ms	vldy0=25
	C	Vertical Display	220	13.97 ms	vldy1=244
	D	Vertical F-porch	14	849.5 $\mu$ s	
	E	Vertical Total	262	16.6 ms	vline=261
EPSON	A	Vertical Width	4	269.6 $\mu$ s	vsyncw=4
	B	Vertical B-porch	19	1.28 ms	vldy0=19
	C	Vertical Display	230	15.5 ms	vldy1=248
	D	Vertical F-porch	9	610.4 $\mu$ s	
	E	Vertical Total	262	17.66 ms	vline=261
CASIO	A	Vertical Width	3	190.5 $\mu$ s	vsyncw=3
	B	Vertical B-porch	16	1.02 ms	vldy0=16
	C	Vertical Display	240	15.24 ms	vldy1=255
	D	Vertical F-porch	3.5	219.5 $\mu$ s	
	E	Vertical Total	262.5	16.67 ms	vline=262
STN-LCD 320x240	A	Vertical Width	2	27.26 $\mu$ s	vsyncw=2
	B	Vertical B-porch	2	27.26 $\mu$ s	vldy0=2
	C	Vertical Display	240	3.27 ms	vldy1=241
	D	Vertical F-porch	2	27.26 $\mu$ s	
	E	Vertical Total	246	3.35 ms	vline=245
STN-LCD 240x160	A	Vertical Width	2	21.34 $\mu$ s	vsyncw=2
	B	Vertical B-porch	2	21.34 $\mu$ s	vldy0=2
	C	Vertical Display	160	1.71 ms	vldy1=161
	D	Vertical F-porch	2	21.34 $\mu$ s	
	E	Vertical Total	166	1.77 ms	vline=165

STN-LCD 160x120	A	Vertical Width	2	15.4 $\mu$ s	vsyncw=2
	B	Vertical B-porch	2	15.4 $\mu$ s	vldy0=2
	C	Vertical Display	120	924 $\mu$ s	vldy1=121
	D	Vertical F-porch	2	15.4 $\mu$ s	
	E	Vertical Total	126	970 $\mu$ s	vline=125
VGA-480	A	Vertical Width	2	63.5 $\mu$ s	vsyncw=2
	B	Vertical B-porch	33	1.049 ms	vldy0=35
	C	Vertical Display	480	15.253 ms	vldy1=514
	D	Vertical F-porch	10	317.8 $\mu$ s	
	E	Vertical Total	525	16.683 ms	vline=524
VGA-400	A	Vertical Width	2	63.5 $\mu$ s	vsyncw=2
	B	Vertical B-porch	35	1.112 ms	vldy0=37
	C	Vertical Display	400	12.711 ms	vldy1=436
	D	Vertical F-porch	12	381.0 $\mu$ s	
	E	Vertical Total	449	14.268 ms	vline=448
VGA-350	A	Vertical Width	2	63.5 $\mu$ s	vsyncw=2
	B	Vertical B-porch	60	1.907 ms	vldy0=62
	C	Vertical Display	350	11.122 ms	vldy1=411
	D	Vertical F-porch	37	1.176 ms	
	E	Vertical Total	449	14.268 ms	vline=448



A field/frame timing and corresponding register diagram

### 1.14.3 On Screen Display (OSD)

The SPCA533A supports two types of OSD functions. The first one is font-based OSD, the other one is graphic-based OSD. The font-based OSD is based on the fixed pitched (15x32) fonts. The advantage of the font-based OSD is smaller storage size requirement. And it is fast to



operate when the OSD changes. The graphic-based OSD allows the users to design colorful icons with 16-bit color depth. It consumes more storage space.

### 1.14.3.1 Font-Based OSD

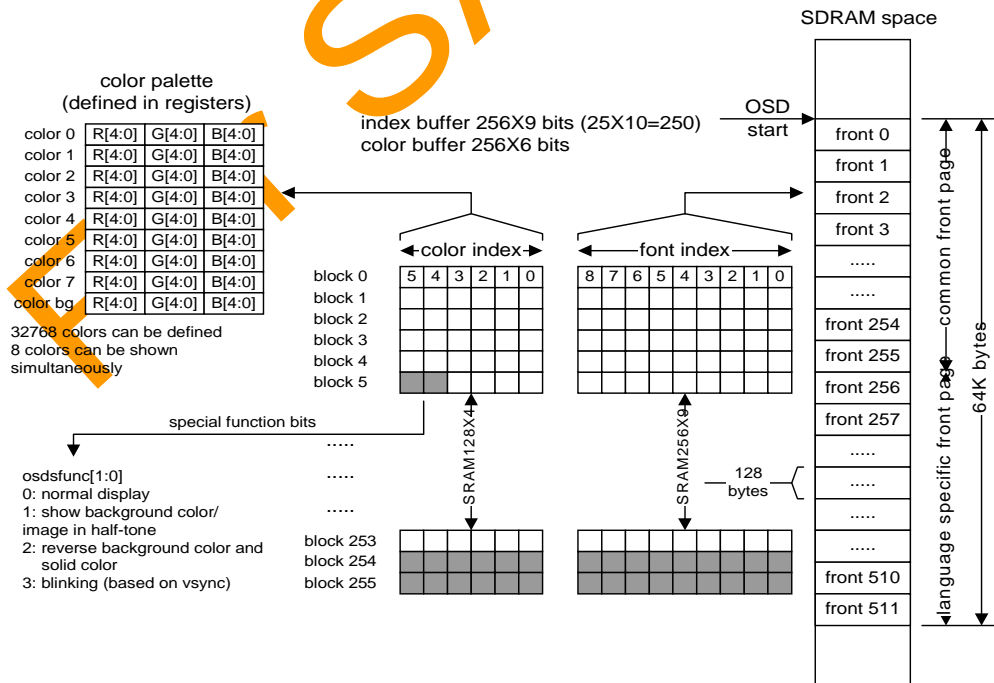
The font-based OSD function of the SPCA533A allows the users to define 512 fonts in the SDRAM. Each font is defined by 16x32 pixel array; each pixel is represented by two bits. The OSD font data base occupies 64K bytes SDRAM space in total. Register 0X2759~0x275B defines the starting address of the OSD data base in the SDRAM.

Just how many pixels on the display device will be mapped by an OSD pixel depends on the resolution of the display device. According to the register 0X2D21 definition, you can program how many pixels on display device. In TV or larger LCD panel, you can change the register (0X2D21) to 0X20(default 0X40), so display size will be mapped to 32x32 pixel array.

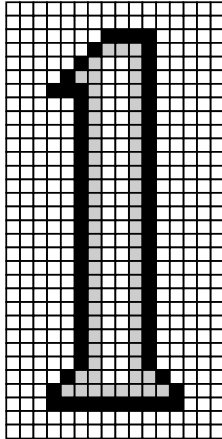
The display space is partitioned into blocks of 25 columns by 7 rows. Normally, the display devices cannot display so many rows at the same time due to the resolution. However, it is easier to use the extra rows to prepare the OSD data for the display especially when the application is to implement a menu-scrolling function. Each partitioned block is assigned by a font index and a display attribute. The font index is 9-bit long, allowing the controller to index to one of the selected 512 fonts. The display attribute determines the color and other special effects while rendering the OSD pattern.

The color palette of the SPCA533A defines 9 colors. Eight of them are used in the pattern display (foreground color); the remaining one is used for background color. Each color is defined by 15-bit registers. The user may define 32768 colors in total. However, only 8 foreground colors and one background color can be shown on the display device at the same time.

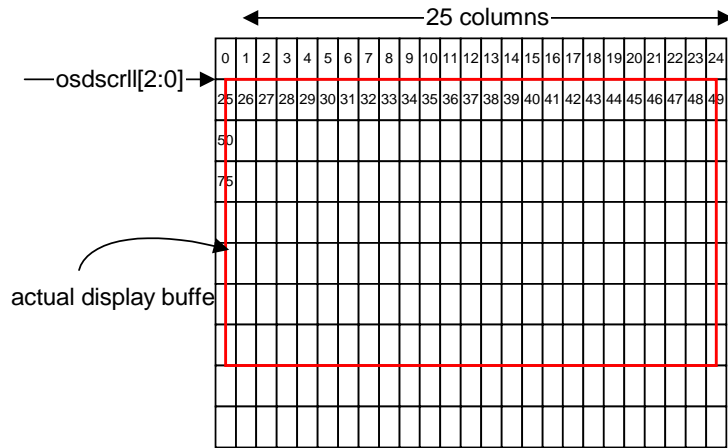
Bit [2:0] of the display attribute buffer defines the (foreground) color. Bit [3] determines whether to turn on the background color. Bit [5:4] specifies the special display effects, including normal, half tone, foreground/background color exchange and blanking. In other words, the background color control is independence to special display effect. By the way, font index and color attribute mapping is one-by-one. Every display block region in SPCA533A has own attribute. The following diagram has shown as the display attribute buffer.



Each font is defined by 16X32 bitmap array



The LCD screen is partitioned into 25x7 blocks.  
Each block is linked to a font by an index

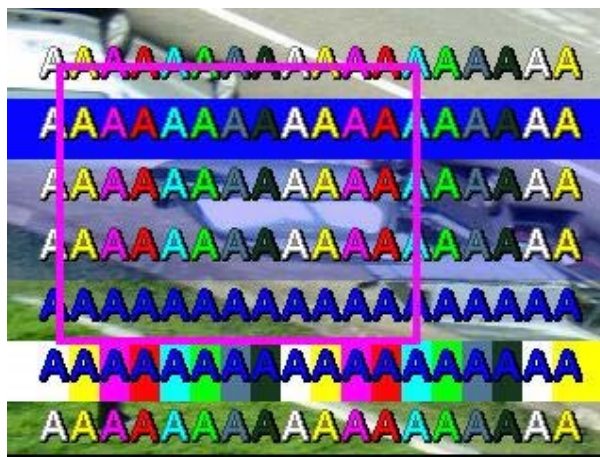


In font-based OSD, each pixel is defined by 2 bits.

- 0: empty (show background color or image)
- 1: black
- 2: foreground color blended with image or background color
- 3: foreground color

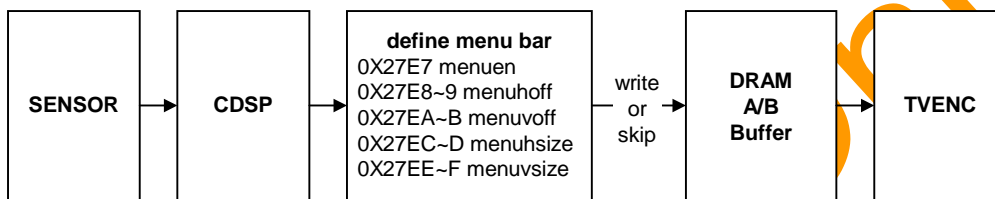
To avoid false color, the font-based OSD defines the blending level between foreground color and image (or blending with background color). Register 0X2D52 define the blending level. Furthermore, the TV/LCD interface controller has built in a low-pass filter to avoid the false color. Set the register 0X2D2B bit 1 to turn on the filter. The OSD also defines a select window function, which display a highlighted frame. The size and position of the frame are programmable via register (0X2D10-0X2D18). The following picture demonstrates the special display effects defined by the attributes.

ROW	Attribute[5:3]	Effect
1	0	Normal mode and background color disable.
2	1	Normal mode and background color enable. (background color set to blue)
3,4	2	Half-tone mode
5	4	Exchange foreground/background color and background color disable.
6	5	Exchange foreground/background color and background color enable.
7	6	Blinking mode and background color disable.



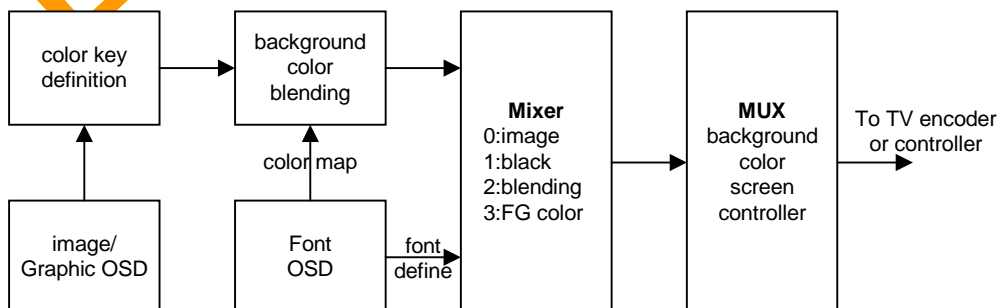
### 1.14.3.2 graphic-based OSD

The graphic-based OSD utilizes the copy&paste engine (in the DRAM controller) to paste the graphic icons to the display buffer. As the graphic icons are prepared in advance, any image is possible to be used in the graphic OSD. In a practical application, the database of the graphic-based OSD must be compressed to a JPEG VLC data stream to reduce the size. This database is uploading from the external ROM to the SDRAM and decompressed at the initialization stage of the SPCA533. The quantization factor in the JPEG compression should be set to all 1's to maintain the quality. In the playback mode, pasting a graphic icon to the decompressed image buffer may destroy the image. It is up to the firmware to backup the original image for image restore later. In the preview mode, it is possible to paste the graphic OSD to the four side of the image buffer. The CDSP may skip these regions when the incoming image is to be filled into the frame buffer. The following diagram shows the frame buffer allocation while using the graphic-based OSD in the preview mode.



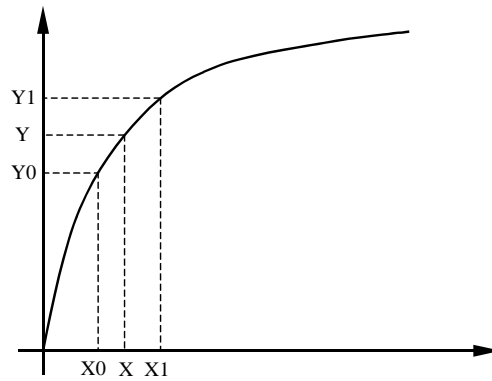
The SPCA533A has also implemented the color key function to make the graphic-based OSD more flexible. A color key is defined as the luminance lower than a pre-defined threshold. It means a black color is the pre-defined color key. The threshold is designed to compensate image distortion in the JPEG compression/decompression. When the color key function is turned-on, the pixels with the key color (normally black) will be replaced by the foreground color assigned to the corresponding blocks. Note that even in the graphic systems, the foreground color is still defined block by block. And the block definition is the same as the one used in the font-based OSD. As SPCA533A treats the graphic OSD data as image, it is possible to show the graphic-based OSD and font-based OSD at the same time. The font-based OSD will overlap with the graphic icons when it exists. If the user is to show a pure graphic icon, the font indices on the corresponding blocks must link to a space (empty) font.

The following diagram depicts the constructing sequence of the image and the OSD. The image or graphic OSD data, which received from DRAM, will through the color key controller. When the color key function turns on, the luminance lower than the color key definition will replace by the background color. The background color information is getting from color attribute definition in display buffer. So the image data will mix with the font definition data by mixer. The mixer controller's effect was defined by the 2-bit font pixel array. And then, the register 0X2D30 bit 0 control the real display data whether the mixer data or the background color.



### 1.14.4 Gamma correction

The data output of TV/LCD interface can be remapped by a programmable gamma curve. The curve is constructed by The range of the input data is from 0 to 255, which is partitioned evenly into 16 section. Each section corresponds to a point. The X-coordinates of these points are fixed, and the Y coordinates are programmable. The output value is calculated by linear interpolation.



Gamma correction method

$$Y = \left( \frac{Y1 - Y0}{X1 - X0} \right) \times (X - X0) + Y0$$

#### 1.14.4 vertical and horizontal scaling function

The TV/LCD interface controller has built-in scaling function in both vertical and horizontal direction. The scaling function enables the SPCA533 to adapt to display devices of different sizes and aspect ratios.

In the vertical direction, the SPCA533A supports not only scaling-down function but also scaling-up function. The scaling factor is calculated according to the following equation. This scaling function only inserts (or removes) lines when necessary. It is used only in the preview mode or video clip mode when real time scaling is necessary. In the playback mode, the users should use the scaling function in the DRAM controller to get a high quality scaled image.

$$\frac{B}{A} = \frac{imgvzfac}{32}$$

In the above equation, A represents the number of lines for display size (vertical lines) and B represents the number of lines for image size (vertical lines). For example, if the number of lines to be displayed is 240 and the number of lines in the source image lines is 309, the zoomvfac is

$$zoomvfac = \lfloor 32(B) / A \rfloor = \lfloor 32(309) / 240 \rfloor = 41$$

The horizontal scaling factor can be derived as the same way of the vertical scaling factor.

$$\frac{B}{A} = \frac{imghzfac}{128}$$

Where A represents the number of pixels to be displayed in a line and B represents the number of pixels in a line of the source image.

## 2. Register Descriptions

### 2.1 Register Category

Address	Description
0X2000 ~ 0X20ff	Global Registers
0X2100 ~ 0X21ff	CDSP Registers
0X2200 ~ 0X22ff	CDSP Window Registers
0X2300 ~ 0X23ff	DMA Control Registers
0X2400 ~ 0X24ff	Storage Media Control Registers
0X2500 ~ 0X25ff	USB Control Registers
0X2600 ~ 0X26ff	Audio Control Registers
0X2700 ~ 0X27ff	SDRAM Control Registers
0X2800 ~ 0X28ff	JPEG Control Registers
0X2900 ~ 0X29ff	Synchronous Serial Interface Registers
0X2a00 ~ 0X2aff	CMOS Sensor Control Registers
0X2b00 ~ 0X2bff	CCD Control Registers
0X2c00 ~ 0X2cff	CPU Interface Registers
0X2d00 ~ 0X2dff	TV Encode Control Registers

### 2.2 Global Registers

address	bit	attar	Name	Description	Default value
0X2000	2:0	rw	Cammode[2:0]	Camera operation mode 0: camera idle 1: Preview 2: Digital Still camera mode 3: Video clip mode 4: PC-camera mode 5: Playback mode 6: Upload/Download mode others: reserved	3'h0
0X2001	0	rw	TVEn	TV encoder enable bit 0: disable the embedded TV encoder 1: enable the embedded TV encoder	1'b0
	1	rw	DACTest	Embedded DAC test mode 0: normal operation 1: force the DAC into test mode	1'b0
	2	rw	DACPd	Embedded DAC power-down mode 0: normal operation 1:force DAC into power-down mode	1'b1
	3	rw	DACBGpd	DAC reference voltage selection 0: internal 1: external	1'b1
0X2002	0	rw	SWTCRst	Software reset to Timing generator and CMOS interface 0: normal operation 1:S/W reset	1'b0
	1	rw	SWCDSRst	Software reset to Color processing engine 0: normal operation 1: S/W reset	1'b0
	2	rw	SWTVRst	Software reset to Color processing engine 0: normal operation	1'b0

				1: S/W reset	
	3	rw	SWUSBRst	Software reset to USB controller 0: normal operation 1: S/W reset	1'b0
	4	rw	SWDRAMPRst	Software reset to DRAM controller engine 0: normal operation 1: S/W reset	1'b0
	5	rw	SWJPEGRst	Software reset to JPEG compression engine 0: normal operation 1: S/W reset	1'b0
	6	rw	SWFMRst	Software reset to storage media interface 0: normal operation 1: S/W reset	1'b0
	7	rw	SWAUDRst	Software reset to audio interface 0: normal operation 1: S/W reset	1'b0
0X2003	0	rw	SwSuspend	Software suspend bit. 0: Normal operation 1: force the chip into suspend state. When this bit is set to 1, Both the crystal pads oscillation will be stopped.	1'b0
	1	rw	RSMRstEn	Embedded CPU resume reset enable bit. 0: Normal 1: After the camera chip is returned to normal operation state from the suspend state, the embedded CPU is automatically reset.	1'b0
0X2004	2:0	rw	TResume	Resume length selection 0: 1ms 1: 2ms 2: 3 ms 3: 5 ms 4: 7 ms 5: 10 ms 6: 15 ms 7: reserved The embedded PLL needs a period of time to become stable after the chip returns to the normal operation state from suspend state. The <i>TResume</i> register determines how long should the camera wait until it resume all the clock sources to the internal modules. In normal cases, 10ms is enough.	2'h0
0X2005	0	rw	IntTrxEn	Internal USB transceiver enable. 0: disable the internal USB transceiver 1:enable the internal USB transceiver When the camera is operated off-line (disconnected from the PC), this bit must be cleared to 0 to conserve power.	1'b1
0x2006	0	rw	SWDRAMOe	DRAM signal output enable control bits. 0: All DRAM pins are tri-stated. 1: for DRAM normal operation.	1'b0
0X2007	7:0	rw	SWTGOe[7:0]	TG control signal output enable register. 0: output disabled 1: enable output [0]: control v1 [1]: control v2 [2]: control v3 [3]: control v4	8'h0

				[4]: control sg1a [5]: control sg3a [6]: control sg1b [7]: control sg3b	
0X2008	7:0	rw	SWTGOe[15:8]	[8]: control sub [9]: control fr [10]: control fh1 [11]: control fh2 [12]: control mshutter [13]: control vsubctrl [14]: control pblk [15]: control fs	8'h0
0X2009	3:0	rw	SWTGOe[19:16]	[16]: control fcds [17]: control adclp [18]: control obclp [19]: control adck	4'b0
0X200a	7:0	rw	SWTGlg[7:0]	TG control signal input 0: Disable gated to zero. 1: Enable gated to zero. [0]: control v1 [1]: control v2 [2]: control v3 [3]: control v4 [4]: control sg1a [5]: control sg3a [6]: control sg1b [7]: control adclp	8'hff
0X200b	2:0	rw	SWTGlg[9:8]	TG control signal input gated to zero register. [8]: control adck [9]: control sd	2'h3
0X2010	7:0	rw	Clk48mEn	The 48MHz Clock 0: disable 1: enable [0]: CDSP module [1]: DMA module [2]: FM module [3]: USB module [4]: Audio module [5]: SDRAM module [6]: JPEG module [7]: TVEnc module	8'hff
0X2011	1:0	rw	UclkEn	The uclk Clock (12MHz) 0: disable 1: enable [0]: USB module [1]: Audio module	2'h3
0X2012	1:0	rw	B1xckEn	The b1xck Clock 0: disable 1: enable [0]: Front module [1]: CDSP module	2'h3
0X2013	7:0	rw	PhaseckEn	The phase Clock 0: disable	8'hff

				1: enable [0]: p1xck [1]: p2xck [2]: p8xck [3]: ptvenc1xck [4]: ptvenc2xck [5]: pmclk [6]: puclk [7]: pauclk	
0X2018	0	rw	TVDecmode	0: CCD or CMOS sensor is connected 1: TV decoder is connected This control bit determines the SYNC source and YUV data source of the SPCA751.	1'b0
0X2019	0	rw	SelectDTV	Digital TV selection	1'b0
	1	rw	SelectMP3	Control GPIO[39:34] function 0: GPIO function 1: Select MP3 function	1'b0
	2	rw	SelectAC97	Control GPIO[38:34] function 0: GPIO function 1: AC-97 interface Note SelectMP3 and SelectAC97 are mutual-exclusive, only one of them may be set to high.	1'b0
	3	rw	SelectAudck	Control GPIO[41] function 0: GPIO function 1: the audio clock output, the frequency is determined by register of "AUDCKfreq"	1'b0
	4	rw	SelectUI	Control GPIO[33:31] function SelectUI=0, GPIO function SelectUI=1, UI function	1'b0
	6	rw	SelectTG1xCk	TG 1X clock selection 0: external 1: internal	1'b1
	7	rw	SelectTG2xCk	TG 2X clock selection 0: external 1: internal	1'b1
0X201a	0	rw	SelectA16	Mux-pin function selection 0: GPIO[8] 1: external ROM address bit 16	1'b1
	1	rw	SelectA17	Mux-pin function selection 0: GPIO[9] 1: external ROM address bit 17	1'b1
	2	rw	SelectA18	Mux-pin function selection 0: GPIO[10] 1: external ROM address bit 16	1'b1
	3	rw	SelectA19	Mux-pin function selection 0: GPIO[11] 1: external ROM address bit 17	1'b1
	4	rw	SelectAdrl	CPU latch address selection SelectAdrl=0, GPIO function SelectAdrl =1, CPU latch address	1'b1
0X201b	0	rw	SelectFlashCtr	Flash light control selection 0: GPIO[12] 1: Flash light control signal	1'b0



0X201c	0	rw	SelectTVEnc1xCk	TV Encoder 1X clock selection 0: TV Encoder 2X clock / 2 1: TV Encoder 2X clock	1'b0
	1	rw	SelectTVEnc2xCk	TV Encoder 2X clock selection 0: 27 MHz 1: 24 MHz	1'b0
0X2021	1:0	rw	AUDCKfreq	Audio clock selection 0: 12 MHz 1: 13.5MHz(applicable only when 27MHz crystal is connected) 2: 24 MHz (for AC-97 CODEC) 3: 27 MHz(applicable only when 27MHz crystal is connected)	2'h0
0X2022	4:0	rw	Phase2xCk	Phase adjustment of the internal 2XCK clock Each step is 2ns, Bit[4] reverse the clock. 2XCK is used in the chip only when HP CMOS sensor is connected or when TV decoder is connected.	5'h0
0X2023	5:0	rw	Phase 1XCK	Internal 1X CK clock adjustment. Each step is 2ns . bit[5] reverse the clock. 1XCK is used as the pixel clock in the chip.	6'h0
0X2024	2:0	rw	CPUfreq[2:0]	CPU operating frequency 0: 32 MHz 1: 24 MHz 2: 12 MHz (default) 3: 6 MHz 4: 3 MHz 5: 1.5 MHz 6: 750KHz 7: 375KHz	3'h2
0X2025	0	rw	VdUpdate	Vd update register control 0: update disable 1: update when V sync is asserted	1'b1
0X2030	7:0	rw	Gpioo[7:0]	General purpose IO output values	8'h0
0X2031	7:0	rw	Gpioo[15:8]		8'h0
0X2032	7:0	rw	Gpioo[23:16]		8'h0
0X2033	7:0	rw	Gpioo[31:24]		8'h0
0X2034	7:0	rw	Gpioo[39:32]		8'h0
0X2035	1:0	rw	Gpioo[41:40]		2'h0
0X2038	7:0	rw	Gpiooe[7:0]	General purpose IO output enable	8'h0
0X2039	7:0	rw	Gpiooe[15:8]		8'h0
0X203a	7:0	rw	Gpiooe[23:16]		8'h0
0X203b	7:0	rw	Gpiooe[31:24]		8'h0
0X203c	7:0	rw	Gpiooe[39:32]		8'h0
0X203d	1:0	rw	Gpiooe[41:40]		2'h0
0X2040	7:0	rw	Gpioi[7:0]	General purpose IO input values	NA
0X2041	7:0	rw	Gpioi[15:8]		NA
0X2042	7:0	rw	Gpioi[23:16]		NA
0X2043	7:0	rw	Gpioi[31:24]		NA
0X2044	7:0	rw	Gpioi[39:32]		NA
0X2045	1:0	rw	Gpioi[41:40]		NA
0X2048	7:0	rw	GpioREvt[7:0]	GPIO rising event The event is generated when the corresponding GPIO goes from low to high	8'h0

				Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	
0X2049	7:0	rw	GpioREvt [15:8]		8'h0
0X204a	7:0	rw	GpioREvt [23:16]		8'h0
0X204b	7:0	rw	GpioREvt [31:24]		8'h0
0X204c	7:0	rw	GpioREvt [39:32]		8'h0
0X204d	1:0	rw	GpioREvt [41:40]		2'h0
0X2050	7:0	rw	GpioRinten[7:0]	GPIO interrupt rising edge enable register 0: disable 1: enable	8'h0
0X2051	7:0	rw	GpioRinten [15:8]		8'h0
0X2052	7:0	rw	GpioRinten [23:16]		8'h0
0X2053	7:0	rw	GpioRinten [31:24]		8'h0
0X2054	7:0	rw	GpioRinten [39:32]		8'h0
0X2055	1:0	rw	GpioRinten [41:40]		2'h0
0X2058	7:0	rw	GpioFinten [7:0]	GPIO interrupt falling edge enable register 0: disable 1: enable	8'h0
0X2059	7:0	rw	GpioFinten [15:8]		8'h0
0X205a	7:0	rw	GpioFinten [23:16]		8'h0
0X205b	7:0	rw	GpioFinten [31:24]		8'h0
0X205c	7:0	rw	GpioFinten [39:32]		8'h0
0X205d	1:0	rw	GpioFinten [41:40]		2'h0
0X2060	7:0	rw	UITxData[7:0]	UI data to be transmitted to the UI module	8'h0
0X2061	7:0	rw	UITxData[15:8]		8'h0
0X2062	0	rw	UITxrqst	UI data transfer request. This register must be set to high before writing register UITXdata.	1'b0
	2	rw	ClrUIMsCnt	Clear UI mini-second counter 0: disable 1: enable	1'b0
0X2063	7:0	rw	UiPITime	Time interval(ms) to poll the UI module. The default polling interval is 1 ms. Disable the Uiinten first before changing Uipollingintval.	8'h1
0X2064	0	r	UITxRxCmplt	UI interface transmission/receiving completed flag.	1'b1
0X2065	7:0	r	UIRxData	UI data received from the UI module	NA
0X2068	0	rw	SWExtRTCRst	When one, the external RTC reset will be active that only reset the serial interface and interrupt of RTC.	1'b0
0X2069	0	w	RTCWReq	When write one, the RTC register specified by the register of "RTCAddr" will be written the data specified by the register of "RTCWData". The CPU must poll the register of "RTCRDY" to know the RTC write cycle has been complete.	NA
	1	w	RTCRReq	When write one, the RTC register specified by the register of "RTCAddr" will be read. The CPU must poll the register of "RTCRDY" to know the RTC read cycle has been complete. Then the CPU reads the register of "RTCRData" to obtain the data of the specified RTC register.	NA
0X206a	0	r	RTCRdy	When one, it indicates the previous cycle of accessing RTC have been complete.	1'b1
0X206b	7:0	rw	RTCAddr	The address of RTC register will be accessed.	8'h0
0X206c	7:0	rw	RTCWData	The data of RTC register will be written.	8'h0
0X206d	7:0	r	RTCRData	The data of RTC register <b>has been read</b> .	NA
0X2070	7:0	rw	Timer[7:0]	The timer counts based on 1ms or 10us time unit determined by the	8'h0

				register of "TimerTBSel". To use the timer, the CPU write an initial value to this register, then trigger the timer by writing 1 to register of "StartTimer". To stop the timer, write 1 to register of "StopTimer".	
0X2071	7:0	rw	Timer[15:8]		8'h0
0X2072	7:0	rw	Timer[23:16]		8'h0
0X2073	0	rw	Upcount	Timer counting mode 0: downcount mode 1: upcount mode	1'b0
	1	rw	TimerRstEn	Timer reset enable 0: disable 1: reset the CPU when the timer reaches zero. This bit must be used in conjunction with the global timer. The global timer can act as an watch dog timer which reset the CPU after a certain period of time.	1'b0
	2	rw	TimerTBSel	The timebase selection of timer <b>0: 10 us</b> <b>1: 1 ms</b>	1'b0
0X2074	0	w	StartTimer	Write 1 to start the timer.	NA
	1	w	StopTimer	Write 1 to stop the timer	NA
0X2078	7:0	rw	GpioFEvt[7:0]	GPIO falling event The event is generated when the corresponding GPIO goes from high to low Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	8'h0
0X2079	7:0	rw	GpioFEvt [15:8]		8'h0
0X207a	7:0	rw	GpioFEvt [23:16]		8'h0
0X207b	7:0	rw	GpioFEvt [31:24]		8'h0
0X207c	7:0	rw	GpioFEvt [39:32]		8'h0
0X207d	1:0	rw	GpioFEvt [41:40]		2'h0
0X2080	0	rw	TGPLLen	PLL for TG enable bit 0: disable 1: enable The input clock frequency of this PLL is 3 MHz. This bit is also used to select the clock source of the TG. When set to 1, the clock source of TG is the TGPLL. When set to 0, the clock source of TG is 48MHz clock.	1'b0
0X2081	2:0	rw	TGPLLS[2:0]	The output clock frequency of the TGPLL is $3\text{MHz} * (\text{TGPLLS1} + 1) * (\text{TGPLLS2} + 1) / (\text{TGPLLS} + 1) * 2$ The pixel clock frequency of SPCA533A is 1/8 of the TG output clock frequency. For example, to derive a 18MHz pixel clock, the output clock of TG PLL is 144MHz. $\text{TGPLLS1}[2:0] = 3'h3$ and $\text{TGPLLS2}[2:0] = 3'h5$ .	3'h0
0X2082	2:0	rw	TGPLLS1		<b>3'h3</b>
	6:4	rw	TGPLLS2		3'h5
0X2090	7:0	rw	PGTimeBase[7:0]	The time base of pattern generator (20 ns ~ 336 ms)	8'h0
0X2091	7:0	rw	PGTimeBase[15:8]		
0X2092	7:0	rw	PGTimeBase[23:16]		
0X2093	7:0	rw	PGRptCnt[7:0]	The repeat count of pattern generator (1 ~ 256). The setting is zero, the count is 256.	8'h0
0X2094	7:0	rw	PGAtvCnt[7:0]	The active count of pattern generator (1 ~ 65536). The setting is zero, the count is 65536.	8'h0

0X2095	7:0	rw	PGAtvCnt[15:8]		8'h0
0X2096	7:0	rw	PGInAtvCnt[7:0]	The inactive count of pattern generator (0 ~ 65535). The setting is zero, there is no inactive period.	8'h0
0X2097	7:0	rw	PGInAtvCnt[15:8]		8'h0
0X2098	7:0	rw	PG0pattern	The pattern of pattern generator 0	8'h0
0X2099	7:0	rw	PG1pattern	The pattern of pattern generator 1	8'h0
0X209a	7:0	rw	PG2pattern	The pattern of pattern generator 2	8'h0
0X209b	7:0	rw	PG3pattern	The pattern of pattern generator 3	8'h0
0X209c	7:0	rw	SelectPG	Selection of pattern generator 0: the signal of pattern generator 0 to GPIO 17 1: the invert signal of pattern generator 0 to GPIO 18 2: the signal of pattern generator 1 to GPIO 19 3: the invert signal of pattern generator 1 to GPIO 20 4: the signal of pattern generator 2 to GPIO 21 5: the invert signal of pattern generator 2 to GPIO 22 6: the signal of pattern generator 3 to GPIO 23 7: the invert signal of pattern generator 3 to GPIO 24	8'b0
0X209d	3:0	rw	PGInAtvLev	The level of pattern generator in the inactive period.	4'b0
0X209e	0	rw	PGMSTrigEn	When one, the pattern generation will be triggered when the signal of mechanical shutter changes.	1'b0
	1	w	PGSwTrig	When write one, the pattern generation will be triggered.	NA
0X209f	0	r	PGRdy	The pattern generator ready	1'b1
0X20B0	0	r	VD	Chip internal vertical synchronization signal. This signal is useful when the control of the SPCA533A must synchronize to the vertical synchronization.	NA
0X20B1	5:0	r	IOtrap	IO trap value read-back register	NA
0X20B3	7:0	r	Probe	Probe signal read back register	NA
0X20C0	0	rw	Ulint	UI interrupt register, the interrupt is generated when the SPCA533A has read a non-zero byte from the UI module.. Write 0 to this bit will clear it.	1'b0
	1	rw	Ulresumelnt	UI resume interrupt. This interrupt is generated when the any of the GPIO value changes. It is used to wake up the SPCA533A from the suspend state. Write 0 to this register will clear it. This interrupt is designed to wake up the SPCA533.	1'b0
	2	rw	Timerint	When the timer is operated in down count mode, and the count values reaches 0, this interrupt is generated. Write 0 to this bit will clear the interrupt.	1'b0
	4	rw	VDRint	Vertical synchronization signal interrupt. It is generated when the signal changes from low to high. This interrupt is aimed at synchronize the camera control events. For example, the control of the flash light. Write 0 to this register will clear it.	1'b0
	5	rw	VDFint	Vertical synchronization signal interrupt. It is generated when the signal changes from high to low. This interrupt is aimed at synchronize the camera control events. For example, the control of the flash light. Write 0 to this register will clear it.	1'b0
	6	rw	MShRint	Mechanical shutter signal interrupt. It is generated when the signal changes from low to high.	1'b0
	7	rw	MShFint	Mechanical shutter signal interrupt. It is generated when the signal changes from high to low.	1'b0
0X20D0	0	rw	Ulinten	UI interrupt enable bit 0: disable , 1: enable	1'b0

	1	rw	UIRsminten	UI resume interrupt enable bit 0: disable , 1: enable	1'b0
	2	rw	Timerinten	Timer interrupt enable bit 0: disable 1: enable	1'b0
	4	rw	VDRinten	VD rising edge interrupt enable bit 0: disable 1: enable	1'b0
	5	rw	VDFinten	VD falling edge interrupt enable bit 0: disable 1: enable	1'b0
	6	rw	MShRinten	Mechanical shutter control signal rising edge interrupt enable bit 0: disable 1: enable	1'b0
	7	rw	MSFinten	Mechanical shutter control signal falling edge interrupt enable bit 0: disable 1: enable	1'b0
0X20E8	0	rw	PGFRStart	When set one, the pattern generator will be repeat forever. The repeat count (register 0X2093) will be ignored.	1'b0
	1	rw	PGFRStop	When set one, the pattern generator will be forced to reset state. If the pattern generator is set to the repeat forever mode, only set the bit to one to stop the repeat forever mode. The bit must be cleared to zero when the pattern generator will be started again.	1'b0
	2		reserved		
	3	rw	USBPwrCfg	0: Bus-powered for USB getstatus command 1: Self-powered for USB getstatus command	1'b0
0X20FF	7:0	r	RevID[7:0]	Chip revision ID	NA

### 2.3 CDSP Registers

Address	bit	attr	name	description	Default value
0X2100	0	rw	pix_sw	pixel switch for input image type	1'b1
	1	rw	line_sw	line switch for input image type	1'b1
0X2103	7:0	rw	hvalidshift	Horizontal valid shift by CDSP	8'h24
0X2104	7:0	rw	vvalidshift	Vertical valid shift by CDSP	8'h16
0X2105	0	rw	hmen	Horizontal mirror enable (front 8, rear 16)	1'b0
0X210a	0	rw	ObManuen	Optical black manual reduction enable	1'b1
	1	rw	ObAutoen	Optical black auto reduction enable	1'b0
	2	rw	CurrentFrameOb	Current Frame OB	1'b0
	6:4	rw	Obtype	OB Block Type (X x Y) 0: 1 x 256 1: 2 x 256 2: 4 x 256 3: 8 x 256 4: 256 x 1 5: 256 x 2 6: 256 x 4 7: 256 x 8	3'h0
0X210b	3:0	rw	OBHoffH	OB block horizontal offset (H)	4'h0
	7:4	rw	OBVoffH	OB block vertical offset (H)	4'h0
0X210c	7:0	rw	OBHoffL	OB block horizontal offset (L)	8'h0
0X210d	7:0	rw	OBVoffL	OB block vertical offset (L)	8'h0

0X210e	7:0	rw	ManuOb[7:0]	Manual optical black level	8'h20
0X210f	1:0	rw	ManuOb[9:8]		2'h0
0X2110	0	rw	BadPixFunEn	Bad Pixel Compensation Function Enable	1'b0
	1	rw	PgBPen	Program bad pixel information to Bad Pixel SRAM; should be set to 0 when Bad Pixel Compensation Function Enable	1'b0
	2	rw	PgBPread	When high, the bad pixel SRAM is in the read mode; otherwise the bad pixel SRAM is in the write mode.	1'b0
0X2111	7:0	rw	BadPixInXL	Bad Pixel download data X(L)	8'h0
0X2112	3:0	rw	BadPixInXH	Bad Pixel download data X(H)	4'h0
0X2113	7:0	rw	BadPixInYL	Bad Pixel download data Y(L)	8'h0
0X2114	3:0	rw	BadPixInYH	Bad Pixel download data Y(H)	4'h0
0X2115	7:0	rw	BadPixAddr	Bad Pixel SRAM Address A write to this register will also trigger the actual action to write download data X,Y to Bad Pixel SRAM when the register bit of "PgBPread" is 0.	8'h0
0X2116	7:0	r	BadPixXL	Bad Pixel SRAM data X(L)	NA
0X2117	3:0	r	BadPixXH	Bad Pixel SRAM data X(H)	NA
0X2118	7:0	r	BadPixYL	Bad Pixel SRAM data Y(L)	NA
0X2119	3:0	r	BadPixYH	Bad Pixel SRAM data Y(H)	NA
0X211a	0	rw	RawDen	Raw data scale function 0: disable 1: enable	1'b0
	1	rw	RawDMode	Raw data scale mode 0: drop pixel 1: filter pixel	1'b0
0X211b	7:0	rw	RawDF[7:0]	Raw data scale factor (low byte)	8'h0
0X211c	7:0	rw	RawDF[15:8]	Raw data scale factor (high byte)	8'h0
0X211e	7:0	r	AutoOb[7:0]	Average optical black level of the built-in accumulator	NA
0X211f	1:0	r	AutoOb[9:8]		NA
0X2120	7:0	rw	Roffset	R offset for white balance (1 sign +7 bit)	8'h8
0X2121	7:0	rw	Groffset	Gr offset for white balance (1 sign + 7 bit)	8'h0
0X2122	7:0	rw	Boffset	B offset for white balance (1 sign + 7 bit)	8'h4
0X2123	7:0	rw	Gboffset	Gb offset for white balance (1 sign + 7 bit)	8'h0
0X2124	7:0	rw	Rgain(L)	R gain for white balance (3.6 bit) (L byte)	8'ha5
0X2125	7:0	rw	Grgain(L)	Gr gain for white balance (3.6 bit) (L byte)	8'h40
0X2126	7:0	rw	Bgain(L)	B gain for white balance (3.6 bit) (L byte)	8'h5d
0X2127	7:0	rw	Gbgain(L)	Gb gain for white balance (3.6 bit) (L byte)	8'h40
0X2128	0	rw	Gbgain(H)	Gb gain for white balance (3.6 bit) (H byte)	1'b0
	1	rw	Bgain(H)	B gain for white balance (3.6 bit) (H byte)	1'b0
	2	rw	Grgain(H)	Gr gain for white balance (3.6 bit) (H byte)	1'b0
	3	rw	Rgain(H)	R gain for white balance (3.6 bit) (H byte)	1'b0
0X2130	0	rw	Romgammaen	ROM Gamma Enable	1'b0
0X2140	7:0	rw	A11(L)	A11 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'h60
0X2141	7:0	rw	A12(L)	A12 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2142	7:0	rw	A13(L)	A13 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2143	7:0	rw	A21(L)	A21 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2144	7:0	rw	A22(L)	A22 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'h60
0X2145	7:0	rw	A23(L)	A23 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2146	7:0	rw	A31(L)	A31 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2147	7:0	rw	A32(L)	A32 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'hf0
0X2148	7:0	rw	A33(L)	A33 coefficient for color correction (1 sign+2.6 bit) (Low byte)	8'h60

0X2149	7:0	rw	A32,A31,A23,A22,A21,A13, A12,A11(H)	A32~A11 coefficient for color correction (1 sign+2.6 bit) (H byte)	8'hee
0X214a	0	rw	A33(H)	A33 coefficient for color correction (1 sign+2.6 bit) (H byte)	1'b0
0X2150	1:0	rw	LutGammaMode	LUT gamma mode 0: disable 1: enable LUT gamma 2: enable LUT gamma with low pass filter	2'h2
0X2151	7:0	rw	Gammalfd	The point distance in the low pass filter of LUT gamma.	8'h20
0X2160	7:0	rw	Ylut0	Y look-up table for gamma correction (unit: 4)	8'h0
0X2161	7:0	rw	Ylut1		8'h17
0X2162	7:0	rw	Ylut2		8'h4a
0X2163	7:0	rw	Ylut3		8'h69
0X2164	7:0	rw	Ylut4		8'h83
0X2165	7:0	rw	Ylut5		8'h99
0X2166	7:0	rw	Ylut6		8'hab
0X2167	7:0	rw	Ylut7		8'hbb
0X2168	7:0	rw	Ylut8		8'hc7
0X2169	7:0	rw	Ylut9		8'hd1
0X216a	7:0	rw	Ylut10		8'hd9
0X216b	7:0	rw	Ylut11		8'he0
0X216c	7:0	rw	Ylut12		8'he7
0X216d	7:0	rw	Ylut13		8'hee
0X216e	7:0	rw	Ylut14		8'hf5
0X216f	7:0	rw	Ylut15		8'hfc
0X2170	7:0	rw	Ylut16		8'hff
0X2180	3:0	rw	Fh00	The factor of horizontal edge filter [3]: sign bit (0: positive, 1:negtive) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4	4'h0
	7:4	rw	Fh01		4'h0
0X2181	3:0	rw	Fh02		4'h0
	7:4	rw	Fh03		4'h0
0X2182	3:0	rw	Fh04		4'h0
	7:4	rw	Fh10		4'h0
0X2183	3:0	rw	Fh11		4'h9
	7:4	rw	Fh12	The factor of horizontal edge filter [3]: sign bit (0: positive, 1:negtive) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h9
0X2184	3:0	rw	Fh13		4'h9
	7:4	rw	Fh14		4'h0
0X2185	3:0	rw	Fh20		4'h0

	7:4	rw	Fh21		4'h9
0X2186	3:0	rw	Fh22	The factor of horizontal edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h5
	7:4	rw	Fh23		4'h9
0X2187	3:0	rw	Fh24		4'h0
	7:4	rw	Fh30		4'h0
0X2188	3:0	rw	Fh31		4'h9
	7:4	rw	Fh32	The factor of horizontal edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h9
0X2189	3:0	rw	Fh33		4'h9
	7:4	rw	Fh34		4'h0
0X218a	3:0	rw	Fh40		4'h0
	7:4	rw	Fh41		4'h0
0X218b	3:0	rw	Fh42	The factor of horizontal edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h0
	7:4	rw	Fh43		4'h0
0X218c	3:0	rw	Fh44		4'h0
	6:4	rw	Fha	The division factor of horizontal edge filter 0: 1 1: 2 2: 4 3: 8 4: 16 5: 32 6: 64 7: 128	3'h4
0X2190	3:0	rw	Fv00	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude	8'h0





				0: 0 1: 1 2: 2 3: 3 4: 4	
	7:4	rw	Fv01		4'h0
0X2191	3:0	rw	Fv02		4'h0
	7:4	rw	Fv03		4'h0
0X2192	3:0	rw	Fv04		4'h0
	7:4	rw	Fv10		4'h0
0X2193	3:0	rw	Fv11		4'h0
	7:4	rw	Fv12		4'h0
0X2194	3:0	rw	Fv13		4'h0
	7:4	rw	Fv14		4'h0
0X2195	3:0	rw	Fv20	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h0
	7:4	rw	Fv21	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h0
0X2196	3:0	rw	Fv22	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h0
	7:4	rw	Fv23	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8	4'h0

				6: 16	
0X2197	3:0	rw	Fv24	The factor of vertical edge filter [3]: sign bit (0: positive, 1:negative) [2:0]: magnitude 0: 0 1: 1 2: 2 3: 3 4: 4 5: 8 6: 16	4'h0
	7:4	rw	Fv30		4'h0
0X2198	3:0	rw	Fv31		4'h0
	7:4	rw	Fv32		4'h0
0X2199	3:0	rw	Fv33		4'h0
	7:4	rw	Fv34		4'h0
0X219a	3:0	rw	Fv40		4'h0
	7:4	rw	Fv41		4'h0
0X219b	3:0	rw	Fv42		4'h0
	7:4	rw	Fv43		4'h0
0X219c	3:0	rw	Fv44		4'h0
	6:4	rw	Fva	The division factor of vertical edge filter 0: 1 1: 2 2: 4 3: 8 4: 16 5: 32 6: 64 7: 128	3'h0
0X21a0	0	rw	YedgeEn	Y Edge Enable	1'b1
0X21a5	1:0	rw	YhAvgMode	Y horizontal average mode 00: no average 01: 2 pixel average 10: 3 pixel average 11: 4 pixel average	2'b0
0X21a6	0	rw	BTCTEn	Brightness and Contrast adjustment enable	1'b0
0X21a7	7:0	rw	BT	Brightness adjustment (1 sign+7 bit, unit 2)	8'h0
0X21a8	7:0	rw	CT	Contrast adjustment (3.5 bit)	8'h20
0X21ab	0	rw	UVHAvg	UV Horizontal Average	1'b1
	1	rw	UVVAvg	UV Vertical Average	1'b1
0X21ac	0	rw	STHueEn	Saturation and Hue adjustment enable	1'b0
	7:6	rw	Hue(H)	Hue adjustment (H byte)	2'h0
0X21ad	7:0	rw	Hue(L)	Hue adjustment (L byte) (divide by 2 = degree)	8'h00
0X21ae	7:0	rw	Sat	Saturation adjustment (3.5 bit)	8'h20

## 2.4 CDSP Window Registers

Address	bit	attr	name	description	Default value
0X2200	7:0	rw	HwdOffset	Window horizontal offset	8'h1b
0X2201	7:0	rw	VwdOffset	Window vertical offset	8'h15

0X2202	6:0	rw	HwdSize	Window horizontal size	7'h33
0X2203	7:0	rw	VwdSize[7:0]	Window vertical size	8'h26
0X2204	1:0	rw	VwdSize[9:8]		2'h0
0X2205	2:0	rw	PseudoHwdSize	Pseudo Horizontal Window Size (Horizontal Accumulator Normalizing Factor) 0: 8 1: 16 2: 32 3: 64 4: 128	3'h3
	6:4	rw	PseudoVwdSize	Pseudo Vertical Window Size (Vertical Accumulator Normalizing Factor) 0: 8 1: 16 2: 32 3: 64 4: 128 5: 256 6: 512 7: 1024	3'h3
0X2206	0	rw	windowhold	When one, the window value will be held.	1'b0
	1	rw	wbrbclampen	White Balance RB clamping enable	1'b1
	2	rw	WBYThrEn	White Balance Y threshold enable	1'b1
0X2207	7:0	rw	WB_RBClamp	RB clamp value for white balance	8'hc8
0X2208	7:0	rw	WB_YthrL	Low luminance threshold for white balance (unit: 4)	8'h32
0X2209	7:0	rw	WB_YthrH	High luminance threshold for white balance (unit: 4)	8'hc8
0X2210	7:0	rw	AFWOffX[7:0]	Focus measurement window X offset	8'h61
0X2211	7:0	rw	AFWOffY[7:0]	Focus measurement window Y offset	8'h36
0X2212	0	rw	AFWOffX[8]		1'b0
	7:4	rw	AFWOffY[11:8]		2'h0
0X2213	7:0	rw	AFWX[7:0]	Focus measurement window X size	8'h80
0X2214	7:0	rw	AFWY[7:0]	Focus measurement window Y size	8'h80
0X2215	0	rw	AFWX[8]		1'b0
	7:4	rw	AFWY[11:8]		4'h0
0X2216	2:0	rw	PAFWXAccF	Pseudo AF Window X Size (Horizontal Accumulator Normalizing Factor) 0: 8 1: 16 2: 32 3: 64 4: 128 5: 256 6: 512	3'h4
	7:4	rw	PAFWYAccF	Pseudo AF Vertical Window Size (Vertical Accumulator Normalizing Factor) 0: 8 1: 16 2: 32 3: 64 4: 128 5: 256 6: 512	4'h4

				7: 1024 8: 2048 9: 4096	
0X2217	7:0	r	AFWDO [7:0]	Focus measurement window out	NA
0X2218	4:0	r	AFWDO[12:8]		NA
0X2280	7:0	r	YWD11	Y window 11 data (unit: 4)	NA
0X2281	7:0	r	YWD12	Y window 12 data (unit: 4)	NA
0X2282	7:0	r	YWD13	Y window 13 data (unit: 4)	NA
0X2283	7:0	r	YWD14	Y window 14 data (unit: 4)	NA
0X2284	7:0	r	YWD15	Y window 15 data (unit: 4)	NA
0X2285	7:0	r	YWD21	Y window 21 data (unit: 4)	NA
0X2286	7:0	r	YWD22	Y window 22 data (unit: 4)	NA
0X2287	7:0	r	YWD23	Y window 23 data (unit: 4)	NA
0X2288	7:0	r	YWD24	Y window 24 data (unit: 4)	NA
0X2289	7:0	r	YWD25	Y window 25 data (unit: 4)	NA
0X228a	7:0	r	YWD31	Y window 31 data (unit: 4)	NA
0X228b	7:0	r	YWD32	Y window 32 data (unit: 4)	NA
0X228c	7:0	r	YWD33	Y window 33 data (unit: 4)	NA
0X228d	7:0	r	YWD34	Y window 34 data (unit: 4)	NA
0X228e	7:0	r	YWD35	Y window 35 data (unit: 4)	NA
0X228f	7:0	r	YWD41	Y window 41 data (unit: 4)	NA
0X2290	7:0	r	YWD42	Y window 42 data (unit: 4)	NA
0X2291	7:0	r	YWD43	Y window 43 data (unit: 4)	NA
0X2292	7:0	r	YWD44	Y window 44 data (unit: 4)	NA
0X2293	7:0	r	YWD45	Y window 45 data (unit: 4)	NA
0X2294	7:0	r	YWD51	Y window 51 data (unit: 4)	NA
0X2295	7:0	r	YWD52	Y window 52 data (unit: 4)	NA
0X2296	7:0	r	YWD53	Y window 53 data (unit: 4)	NA
0X2297	7:0	r	YWD54	Y window 54 data (unit: 4)	NA
0X2298	7:0	r	YWD55	Y window 55 data (unit: 4)	NA
0X2299	7:0	r	YWDAvg	Y window average (unit: 4)	NA
0X22a0	7:0	r	RYWD11[7:0]	RY window 11 data (unit: 4)	NA
0X22a1	7:0	r	RYWD12[7:0]	RY window 12 data (unit: 4)	NA
0X22a2	7:0	r	RYWD13[7:0]	RY window 13 data (unit: 4)	NA
0X22a3	7:0	r	RYWD14[7:0]	RY window 14 data (unit: 4)	NA
0X22a4	7:0	r	RYWD15[7:0]	RY window 15 data (unit: 4)	NA
0X22a5	7:0	r	RYWD21[7:0]	RY window 21 data (unit: 4)	NA
0X22a6	7:0	r	RYWD22[7:0]	RY window 22 data (unit: 4)	NA
0X22a7	7:0	r	RYWD23[7:0]	RY window 23 data (unit: 4)	NA
0X22a8	7:0	r	RYWD24[7:0]	RY window 24 data (unit: 4)	NA
0X22a9	7:0	r	RYWD25[7:0]	RY window 25 data (unit: 4)	NA
0X22aa	7:0	r	RYWD31[7:0]	RY window 31 data (unit: 4)	NA
0X22ab	7:0	r	RYWD32[7:0]	RY window 32 data (unit: 4)	NA
0X22ac	7:0	r	RYWD33[7:0]	RY window 33 data (unit: 4)	NA
0X22ad	7:0	r	RYWD34[7:0]	RY window 34 data (unit: 4)	NA
0X22ae	7:0	r	RYWD35[7:0]	RY window 35 data (unit: 4)	NA
0X22af	7:0	r	RYWD41[7:0]	RY window 41 data (unit: 4)	NA
0X22b0	7:0	r	RYWD42[7:0]	RY window 42 data (unit: 4)	NA
0X22b1	7:0	r	RYWD43[7:0]	RY window 43 data (unit: 4)	NA
0X22b2	7:0	r	RYWD44[7:0]	RY window 44 data (unit: 4)	NA
0X22b3	7:0	r	RYWD45[7:0]	RY window 45 data (unit: 4)	NA

0X22b4	7:0	r	RYWD51[7:0]	RY window 51 data (unit: 4)	NA
0X22b5	7:0	r	RYWD52[7:0]	RY window 52 data (unit: 4)	NA
0X22b6	7:0	r	RYWD53[7:0]	RY window 53 data (unit: 4)	NA
0X22b7	7:0	r	RYWD54[7:0]	RY window 54 data (unit: 4)	NA
0X22b8	7:0	r	RYWD55[7:0]	RY window 55 data (unit: 4)	NA
0X22b9	7:0	r	RYWDSign[7:0]	RY window 11 to 15 and window 21 to 23 sign bit	NA
0X22ba	7:0	r	RYWDSign[15:8]	RY window 24 to 25, window 31 to 35 and window 41 sign bit	NA
0X22bb	7:0	r	RYWDSign [23:16]	RY window 42 to 45 and window 51 to 54 sign bit	NA
0X22bc	0	r	RYWDSign[24]	RY window 55 sign bit	NA
0X22bd	7:0	r	RYWDAvg[7:0]	RY window average (unit: 4)	NA
0X22be	0	r	RYWDAvg[8]		NA
0X22c0	7:0	r	BYWD11[7:0]	BY window 11 data (unit: 4)	NA
0X22c1	7:0	r	BYWD12[7:0]	BY window 12 data (unit: 4)	NA
0X22c2	7:0	r	BYWD13[7:0]	BY window 13 data (unit: 4)	NA
0X22c3	7:0	r	BYWD14[7:0]	BY window 14 data (unit: 4)	NA
0X22c4	7:0	r	BYWD15[7:0]	BY window 15 data (unit: 4)	NA
0X22c5	7:0	r	BYWD21[7:0]	BY window 21 data (unit: 4)	NA
0X22c6	7:0	r	BYWD22[7:0]	BY window 22 data (unit: 4)	NA
0X22c7	7:0	r	BYWD23[7:0]	BY window 23 data (unit: 4)	NA
0X22c8	7:0	r	BYWD24[7:0]	BY window 24 data (unit: 4)	NA
0X22c9	7:0	r	BYWD25[7:0]	BY window 25 data (unit: 4)	NA
0X22ca	7:0	r	BYWD31[7:0]	BY window 31 data (unit: 4)	NA
0X22cb	7:0	r	BYWD32[7:0]	BY window 32 data (unit: 4)	NA
0X22cc	7:0	r	BYWD33[7:0]	BY window 33 data (unit: 4)	NA
0X22cd	7:0	r	BYWD34[7:0]	BY window 34 data (unit: 4)	NA
0X22ce	7:0	r	BYWD35[7:0]	BY window 35 data (unit: 4)	NA
0X22cf	7:0	r	BYWD41[7:0]	BY window 41 data (unit: 4)	NA
0X22d0	7:0	r	BYWD42[7:0]	BY window 42 data (unit: 4)	NA
0X22d1	7:0	r	BYWD43[7:0]	BY window 43 data (unit: 4)	NA
0X22d2	7:0	r	BYWD44[7:0]	BY window 44 data (unit: 4)	NA
0X22d3	7:0	r	BYWD45[7:0]	BY window 45 data (unit: 4)	NA
0X22d4	7:0	r	BYWD51[7:0]	BY window 51 data (unit: 4)	NA
0X22d5	7:0	r	BYWD52[7:0]	BY window 52 data (unit: 4)	NA
0X22d6	7:0	r	BYWD53[7:0]	BY window 53 data (unit: 4)	NA
0X22d7	7:0	r	BYWD54[7:0]	BY window 54 data (unit: 4)	NA
0X22d8	7:0	r	BYWD55[7:0]	BY window 55 data (unit: 4)	NA
0X22d9	7:0	r	BYWDSign[7:0]	BY window 11 to 15 and window 21 to 23 sign bit	NA
0X22da	7:0	r	BYWDSign[15:8]	BY window 24 to 25, window 31 to 35 and window 41 sign bit	NA
0X22db	7:0	r	BYWDSign [23:16]	BY window 42 to 45 and window 51 to 54 sign bit	NA
0X22dc	0	r	BYWDSign[24]	BY window 55 sign bit	NA
0X22dd	7:0	r	BYWDAvg[7:0]	BY window average (unit: 4)	NA
0X22de	0	r	BYWDAvg[8]		NA

## 2.5 DMA Controller Registers

Address	bit	Attr	Name	Description	Default value
0X2300	7:0	r/w	DMAdata	DMA data port	NA
0X2301	2:0	r/w	DMAsrc	DMA source(provider) selection: 0: DRAM controller	3'b0

				1: 4K SRAM 8032 buffer 2: Flash memory in DMA mode 3: 1K SRAM audio buffer 4: USB 5: CPU	
	6:4	r/w	DMAdst	DMA destination(consumer) selection: 0: DRAM controller 1: 4K SRAM 8032 buffer 2: Flash memory in DMA mode 3: 1K SRAM audio buffer 4: USB 5: CPU	3'b0
0X2302	7:0	r/w	DMAsize[7:0]	Define the size of data in DMA transfer. The actual size(bytes) to be transferred is DMAsize+1.	8'b0
0X2303	1:0	r/w	DMAsize[9:8]		2'b0
0X2304	0	r/w	DMAidle	0: normal state 1: idle state (reset the DMA machine)	1'b0
	1	r/w	PadeEn	Padding dummy bit 0's to fill a whole page for flash access (refer register 0x24a3 for page size) 0: disable padding function 1: enable padding function	1'b1
	3:2	r/w	Bufsize[1:0]	Select internal buffer size: 0: 1 byte buffer inside. 1: 2 bytes buffer inside. 2: 4 bytes buffer inside.	2'b10
0X2310	1:0	r/w	Fatmode[1:0]	0: reset the DMA code-matching machine. 1: fat16 code-matching 2: fat12 code-matching	2'b0
	4	r/w	Byte-order	0: high-byte first in matching sequence. 1: low-byte first in matching sequence.	1'b1
0X2311	7:0	r/w	Fatcode[7:0]	The searching fatcode.	8'b0
0X2312	15:8	r/w	Fatcode[15:8]		8'b0
0X2313	6:0	r/w	Hitcnt[6:0]	The number of matching fatcode. The maximum matching number is 127. If the matching number is over 127, this register shows 127 hits.	7'b0
0X23A0	2:0	r	Bufindex	Remaining data amount in DMA buffer	NA
	3	r	DMAfull	0: internal buffer is not full 1: internal buffer is filled with data	NA
	4	r	DMAempty	0: internal buffer is empty 1: none of the internal buffer is filled with data	NA
0X23A1	7:0	r	Fataddr[7:0]	The position of the first matched code happened in current DMA cycle.	NA
0X23A2	1:0	r	Fataddr[9:8]		NA
	2	r	Fathit	Active high if the fatcode occurs.	NA
	5:4	r	Fatstate[1:0]	The matching state for internal check only.	NA
0X23B0	0	w	DMAstart	Write 1 to this bit will trigger a DMA cycle	NA
0X23C0	0	r/w	DMAcmp	This interrupt will be generated when the DMA cycle is completed. To clear the interrupt, write 0 to this bit.	1'b0
0X23D0	0	r/w	DMAcmpEn	0: disable the DMA cycle complete interrupt 1: enable the interrupt	1'b0

### 2.6 Flash Memory Control Registers

Address	bit	Attr	Name	Description	Default value
0X2400	2:0	r/w	MediaType	This register determines the storage media 0:none. The data is stored in the SDRAM, and all the flash memory control pins are used as GPIOs. 1: NAND-gate flash memory 2: reserved 3: CompactFlash cards interface 4: SPI serial interface 5: The NextFlah serial interface 6: SD memory card others: reserved	3'b0
	4	w	NANDrst	Writing 1 to this bit will reset the NAND type and SmartMedia Card interface	NA
	5	w	FMSrst	Writing 1 to this bit will reset the SPI and Next flash interface	NA
	6	w	CFrst	Writing 1 to this bit will reset the Compact flash interface	NA
0X2401	7:0	r/w	Fmctrlo[7:0]	Flash memory control interface output signals. The control signals, except the read/write pulses, are directly programmed by the CPU. When the control pins are not used by the selected storage media, the control pins are used as a GPIO signals in application signals.	8'b0
0X2402	7:0	r/w	Fmctrlo[15:8]		8'b0
0X2403	7:0	r/w	Fmctrlo[23:16]		8'b0
0X2404	5:0	r/w	Fmctrlo[29:24]		6'b0
0X2405	7:0	r/w	Fmctrloe[7:0]	Output enable controls of the flash memory interface. 0: tri-state 1: drive the control pins	8'b0
0X2406	7:0	r/w	Fmctrloe[15:8]		8'b0
0X2407	7:0	r/w	Fmctrloe[23:16]		8'b0
0X2408	5:0	r/w	Fmctrloe[29:24]		6'b0
0X2409	7:0	R	Fmctrli[7:0]	Input signals from the flash memory control interface. When the control pins are used as input signals from the storage media, its corresponding output enable bit must be turned off. And the CPU can read the input value from this register. For example, the IORDY signal in the CompactFlash interface must be treated in this way.	NA
0X240A	7:0	r	Fmctrli[15:8]		NA
0X240B	7:0	r	Fmctrli[23:16]		NA
0X240C	5:0	r	Fmctrli[29:24]		NA
0X2410	7:0	r/w	FmgpioRinten[7:0]	gpio rising edge interrupt function enable enable : 1    disable : 0	8'b0
0X2411	7:0	r/w	FmgpioRinten[15:8]		8'b0
0X2412	7:0	r/w	FmgpioRinten[23:16]		8'b0
0X2413	5:0	r/w	FmgpioRinten[29:24]		6'b0
0X2414	7:0	r/w	FmgpioFinten[7:0]	gpio falling edge interrupt function enable enable : 1    disable : 0	8'b0
0X2415	7:0	r/w	FmgpioFinten[15:8]		8'b0
0X2416	7:0	r/w	FmgpioFinten[23:16]		8'b0
0X2417	5:0	r/w	FmgpioFinten[29:24]		6'b0
0X2418	7:0	r/w	FmgpioRint[7:0]	Write 0 to clear rising edge event but write 1 is invalid	NA
0X2419	7:0	r/w	FmgpioRint[15:8]	Write 0 to clear rising edge event but write 1 is invalid	NA

0X241a	7:0	r/w	FmgpioRint[23:16]	Write 0 to clear rising edge event but write 1 is invalid	NA
0X241b	5:0	r/w	FmgpioRint[29:24]	Write 0 to clear rising edge event but write 1 is invalid	NA
0X241c	7:0	r/w	FmgpioFint[7:0]	Write 0 to clear falling edge event but write 1 is invalid	NA
0X241d	7:0	r/w	FmgpioFint[15:8]	Write 0 to clear falling edge event but write 1 is invalid	NA
0X241e	7:0	r/w	FmgpioFint[23:16]	Write 0 to clear falling edge event but write 1 is invalid	NA
0X241f	5:0	r/w	FmgpioFint[29:24]	Write 0 to clear falling edge event but write 1 is invalid	NA
Nand-gate flash memory					
0X2420	7:0	r/w	NandData	Nand-gate flash memory command/ address/ data port	NA
0X2421	3:0	r/w	NandActTime	This register applies to DMA mode only. It is used to determine the length of the read/write pulses active(low) and recovery(high) period. The flash memory active time: 0 ~ 15 : 1 T (20.83ns) ~16T(333.28ns)	4'b0
	7:4	r/w	NandRcvTime	The flash memory recovery time: 0 ~ 15 : 1 T (20.83ns) ~16T(333.28ns)	4'b0
0X2422	0	r/w	NandMode	0: on-board nand-gate flash 1: smart media card	1'b0
0X2423	0	r/w	Nandcsnn	Nand interface chip select signal, low active	1'b1
	1	r/w	Nandwpnn	Nand interface write protection signal, low active	1'b1
	2	r/w	Nandale	Nand interface ALE signal	1'b0
	3	r/w	Nandcle	Nand interface CLE signal	1'b0
0X2424	0	r	Nandrdy	Nand interface RDY signal	NA
CompactFlash interface					
0X2430	7:0	r/w	CFdatalow	Low byte data of the CompactFlash interface In byte access, the CPU may read/write the data via this register. A write cycle is triggered after this register is written. If the pre-fetch function is turned on, the next read cycle is automatically launched after this register is read. In a word-access cycle, the CPU may read/write the low byte data via this register. No actual read/write cycle is triggered on the bus in this case.	8'b0
0X2431	7:0	r/w	CFdatahigh	High byte data of the CompactFlash interface. This register is useful only in word access. In a write cycle, the data is written out to the bus after this register is written. In a read cycle, the CPU gets the high byte data by reading register. If the pre-fetch function is turned on, the next read cycle will be launched automatically after this register is read.	8'b0
0X2432	2:0	r/w	CFaddr[2:0]	CompactFlash interface address	3'b0
0X2433	2:0	r/w	CFaddr[10:3]	CompactFlash interface address	8'b0
0X2434	0	r/w	CFword	This bit determine byte or word access 0: byte access 1: word access (not supported in memory mode)	1'b0
	1	r/w	CFpfetch	This bit determine whether to turn on pre-fetch function 0: disable the pre-fetch function 1:turn on the prefetch function	1'b0
	2	r/w	CFmode	0: IDE mode 1: memory mode	1'b0
	3	r/w	CFbyteorder	This bit is used in word access DMA mode. 0: first byte is transmitted via cfdatahigh, last byte is transmitted via cfdatalow. 1: first byte is transmitted via cfdatalow,	1'b0



				last byte is transmitted via cfdatahigh.	
0X2435	3:0	r/w	Cfpulswd[3:0]	Active time of the CFwrnn / CFrdnn signal. 0: 1 clock cycle 1: 2 clock cycle 2: 3 clock cycle ..... f: 16 clock cycle	4'b0
	7:4	r/w	Cfrcvtime[3:0]	Recovery time of the CFwrnn / CFrdnn signal. 0: 1 clock cycle 1: 2 clock cycle 2: 3 clock cycle ..... f: 16 clock cycle	4'b0
0X2436	1:0	r/w	CFcs[1:0]	CompactFlash interface chip select In true IDE mode, CFcs[1:0] controls the pins 'CS1/' and 'CS2/'. In memory mode, only CFcs[0] controls the pin 'CE/'.	2'b11
0X2439	0	r/w	CFregnn	CF interface reg signal This register is only applied to memory mode, and it controls the pin 'REG/'.	1'b1
0X243a	0	r/w	CFrstnn	CompactFlash interface reset signal	1'b1
0X243b	0	r	CFready	CompactFlash interface ready 0: The CompactFlash interface is busy and the CPU must wait 1: The CPU may read/write the data port	1'b1
0X243c	0	r	CFrdybsynn	This is a status pin routed directly from the CompactFlash card	NA
Serial interface (including the SPI Serial interface and the NextFlash serial interface)					
0X2440	7:0	r/w	FMsitxd[7:0]	Serial flash memory TX data port	8'b0
0X2441	7:0	r	FMsirxd[7:0]	Serial flash memory RX data port. Reading from this register will get the data received from the serial flash memory. No serial clock timing is asserted.	8'b0
0X2442	7:0	r	FMsiprx[7:0]	Reading from this register will get the data received from the serial flash memory. It will also invoke a read timing to pre-fetch the next byte of data.	8'b0
0X2443	7:0	r	FMsiprx1[7:0]	Reading from this register causes the SPCA533A to assert the first serial clock to the flash memory. The data being read could be discarded. It is aimed to meeting the timing requirement for reading the NextFlash status word. The CPU should wait 30 ~ 100 us after reading this register.	8'b0
0X2444	7:0	r	FMsiprx7[7:0]	After this register is read, the SPCA533A asserts the remaining 7 clocks to get the 2nd status byte of the NextFlash serial flash memory. The CPU may read the Fmsirxd register to get the status word after the FMSlbusy status is de-asserted.	8'b0
0X2446	1:0	r/w	FMSlfreq[1:0]	Serial clock frequency selecton If NextFlash 0: 24 MHz 1: 12 MHz 2: 8 MHz 3: 6 MHz If SPI 0: 12 MHz 1: 6MHz 2: 3MHz 3: 200 KHz	2'b0
0X2447	0	r/w	FMSldoenn	Nextflash data output enable	1'b1

				0: enable 1: disable	
	1	r/w	SPIcsnn	Chip select for the SPI interface 0: activated 1: inactive this bit only applied to the SPI interface	1'b1
	2	r/w	SPIrstnn	SPI reset signal, active low.	1'b0
	3	r/w	SPIwpnn	SPI write protection, active low.	1'b0
0X2448	0	r/w	SPImode	0: SPI mode 0 1: SPI mode 3	1'b0
0X244a	0	w	NXstart	Write 1 to start the transfer sequence of the the NextFlash memory serial interface.	NA
	1	w	NXstop	Write 1 to stop the transfer sequence of the NextFlash memory serial interface.	NA
0X244b	0	r	FMSIbusy	Flash memory serial interface busy. The CPU should wait until the FMSIbusy is de-asserted each time before it intends to read or write the data port.	NA
	1	r	SPIready	This is a status pin routed directly from the SPI interface.	NA
<b>SD memory interface</b>					
0X2450	0	w	SDrst	Writing 1 to this bit will reset the SD interface to default state	NA
	1	w	SDCRCRst	Writing 1 to this bit will reset the CRC7 and the CRC16 registers	NA
0X2451	1:0	r/w	SDfreq	The clock frequency for the SD flash memory 0: 24 MHz 1: 12 MHz 2: 6 MHz 3: 375 KHz	2'b0
	2	r/w	DataBusWidth	Data bus width 0: one bit data bus 1: four bit data bus	1'b0
	3	r/w	RspType	Response type 0: total length of 48 bits 1: total length of 136 bits	1'b0
	4	r/w	RspTmEn	Enable the timer for getting response 0: disable the timer 1: enable the timer	1'b1
	5	r/w	CRCTmEn	Enable the timer for getting card's CRC16 check result 0: disable the timer 1: enable the timer	1'b1
	6	r/w	MMCmode	0: SD memory card mode 1: multimedia card mode	1'b0
0X2452	0	w	TxCmd	Writing 1 to this bit will generate trigger signal for transmitting command	NA
	1	w	RxRsp	Writing 1 to this bit will generate trigger signal for receiving response	NA
	2	w	TxData	Writing 1 to this bit will generate trigger signal for transmitting one block data. (PIO mode)	NA
	3	w	RxData	Writing 1 to this bit will generate trigger signal for receiving one block data. (PIO mode)	NA
	4	w	RxCARDCRC	Writing 1 to this bit will generate trigger signal for receiving the CRC check result of the card	NA

	5	w	TxDummy	Writing 1 to this bit will generate trigger signal for transmitting 8 dummy clock cycles	NA
0X2453	0	r		Reserved	NA
	1	r	RspBufFul	Response buffer status 0: the buffer is not full 1: the buffer is full. The received response is in the RspBuf1 ~ RspBuf6	1'b0
	2	r	DataBufEmpty	Transmitted data buffer status 0: the buffer is not empty 1: the buffer is empty. It can transmit data via the DataBufTx	1'b1
	3	r	DataBufFull	Received data buffer status 0: the buffer is not full 1: the buffer is full. One byte of received data is in DataBufRx	1'b0
	4	r	SDCmd	The status of pin 'cmd'	NA
	5	r	SDData0	The status of pin 'd0'	NA
	6	r	RspTimeout	The timeout condition of waiting response. Note that this flag won't be cleared until the next time to wait response 0: timeout condition is not occurred 1: timeout condition is occurred	1'b0
	7	r	CRCTimeout	The timeout condition of waiting card's CRC check result. Note that this flag won't be cleared until the next time to wait card's CRC 0: timeout condition is not occurred 1: timeout condition is occurred	1'b0
0X2454	3:0	r	SDState	The state of the SD interface 0: Idle 1: Transmit command 2: Receiving response 3: Generate dummy clock cycles 4: Transmit data 5: Receiving data 6: Transmit CRC16 7: Receiving CRC16 8: Receive the CRC check result of the card others: reserved	4'b0
	6:4	r	CardCRCSts	The CRC check result of the card 010: check result is correct 101: check result is incorrect	3'b0
0X2455	7:0	r/w	DataLen[7:0]	Data length of read/write one block Default value is 512	8'h00
0X2456	1:0	r/w	DataLen[9:8]	Data length of read/write one block	2'b10
0X2457	7:0	r/w	WaitRspTime	The maximal time for waiting response When waiting response, the H/W won't go to the "idle state" until (RspTime) clock cycles are passed.	8'hff
0X2458	7:0	r/w	WaitCRCTime	The maximal time for waiting card's CRC check result. When waiting check result, the H/W won't go to the "idle state" until (CRCTime) clock cycles are passed.	8'h08
0X2459	7:0	r/w	DataBufTx	Buffer for transmitting data (PIO mode) When writing data to this register, the H/W will generate clock cycles to transmit the data out via pin 'd0' (d1~d3)'. The H/W will put the received data to this register	8'bff
0X245A	7:0	r	DataBufRx	Buffer for receiving data (PIO mode) The H/W will put the received data to this register	
0X245B	7:0	r/w	CmdBuf1	Buffer for store the 1st byte of command	8'hff
0X245C	7:0	r/w	CmdBuf2	Buffer for store the 2nd byte of command	8'hff

0X245D	7:0	r/w	CmdBuf3	Buffer for store the 3rd byte of command	8'hff
0X245E	7:0	r/w	CmdBuf4	Buffer for store the 4th byte of command	8'hff
0X245F	7:0	r/w	CmdBuf5	Buffer for store the 5th byte of command	8'hff
0X2460	7:0	r	RespBuf1	Buffer for store the 1st byte of response	NA
0X2461	7:0	r	RespBuf2	Buffer for store the 2nd byte of response	NA
0X2462	7:0	r	RespBuf3	Buffer for store the 3rd byte of response	NA
0X2463	7:0	r	RespBuf4	Buffer for store the 4th byte of response	NA
0X2464	7:0	r	RespBuf5	Buffer for store the 5th byte of response	NA
0X2465	7:0	r	RespBuf6	Buffer for store the 6th byte of response	NA
0X2466	7:0	r	CRC7buf	{CRC7buf[6:0],1'b1} for SD	8'b1;
0X2467	7:0	r	CRC16buf0L	Low byte CRC16 code 0 for SD	8'b0
0X2468	7:0	r	CRC16buf0H	High byte CRC16 code 0 for SD	8'b0
0X2469	7:0	r	CRC16buf1L	Low byte CRC16 code 1 for SD	8'b0
0X246A	7:0	r	CRC16buf1H	High byte CRC16 code 1 for SD	8'b0
0X246B	7:0	r	CRC16buf2L	Low byte CRC16 code 2 for SD	8'b0
0X246C	7:0	r	CRC16buf2H	High byte CRC16 code 2 for SD	8'b0
0X246D	7:0	r	CRC16buf3L	Low byte CRC16 code 3 for SD	8'b0
0X246E	7:0	r	CRC16buf3H	High byte CRC16 code 3 for SD	8'b0
0X246F	0	r	CRC16cor	The CRC16 correct status 0: incorrect 1: correct (all CRC16 registers are 0)	1'b1
<b>ECC</b>					
0X24a0	0	w	ECCRst	Write 1 to this bit will clear the ECC registers and reset the ECC-generation circuit.	NA
0X24a1	7:0	w	PsFMDData	This register is designed to help the CPU to calculate the ECC values. Every byte written to this register will be put into ECC-calculation.	NA
0X24a2	0	r/w	ECCMask	0: Enable the ECC generation. 1: disable the ECC generation.	1'b0
0X24a3	1:0	r/w	ECCMode	The ECC-generation mode 0: 256 bytes/page 1: 512 bytes/page 2: 1024 bytes/page	2'b0
0X24a4	7:0	r	ECC1	ECC 1 byte for 256/512/1024 flash memory page	NA
0X24a5	7:0	r	ECC0	ECC 0 byte for 256/512/1024 flash memory page	NA
0X24a6	7:0	r	ECC2	ECC 2 byte for 256/512/1024 flash memory page	NA
0X24a7	7:0	r	ECC4	ECC 4 byte for 512/1024 flash memory page	NA
0X24a8	7:0	r	ECC3	ECC 3 byte for 512/1024 flash memory page	NA
0X24a9	7:0	r	ECC5	ECC 5 byte for 512/1024 flash memory page	NA
0X24aa	7:0	r	ECC7	ECC 7 byte for 1024 flash memory page	NA
0X24ab	7:0	r	ECC6	ECC 6 byte for 1024 flash memory page	NA
0X24ac	7:0	r	ECC8	ECC 8 byte for 1024 flash memory page	NA
0X24ad	7:0	r	ECCa	ECC a byte for 1024 flash memory page	NA
0X24ae	7:0	r	ECC9	ECC 9 byte for 1024 flash memory page	NA
0X24af	7:0	r	ECCb	ECC b byte for 1024 flash memory page	NA
<b>SPI CRC</b>					
0X24b0	0	w	SPICRCRst	Write 1 to this bit will clear the CRC registers and reset the CRC-generation circuit.	NA
0X24b1	7:0	r	SPICRC7buf	{CRC7buf[6:0],1'b1} for SPI	NA
0X24b2	7:0	r	SPICRC16buf[7:0]	Low byte CRC16 code for SPI	NA
0X24b3	7:0	r	SPICRC16buf[15:8]	High byte CRC16 code for SPI	NA

Interrupt					
0X24c0	0	r/w	CFIRQ	CompactFlash interface IRQ, this signal is routed directly from the CompactFlash interface. Write 0 to clear this register.	1'b0
0X24d0	0	r/w	CFIRQEn	0: disable the CompactFlash interrupt. 1: enable the CompactFlash interrupt	1'b0

### 2.7 USB Control Registers

Address	Bit	Attr	Name	Description	Default value
0X2500	7:0	r/w	Ep0BufData	The data port for the USB ep0 buffer.	NA
0X2501	1:0		Reserved	Reserved for future use	NA
	2	r/w	AudShtPktEn	When high, the audio short packet is allowed; otherwise only the size of maximum or zero packet is allowed.	1'h0
	3	r/w	RmWakeEn	When high, the remote wake event can generate USB remote wakeup cycle; otherwise the remote wake up event is effectless.	1'h0
0X2504	7:0	r/w	AudIntDataL	The data port of audio interrupt in endpoint(low byte).	8'h0
0X2505	7:0	r/w	AudIntDataH	The data port of audio interrupt in endpoint(high byte). When AulntDataH is written, the audio interrupt packet is enabled.	8'h0
0X2506	7:0	r/w	BulkInData	Bulk in buffer (endpoint 2) data port	NA
0X2507	7:0	r	BulkOutData	Bulk out buffer (endpoint 3) data port	NA
0X2508	7:0	r/w	IntInData	Interrupt in buffer (endpoint 4) data port	NA
0X2509	7:0	r/w	BulkIn2Data	Bulk in buffer (endpoint 7) data port	NA
0X250a	7:0	r	BulkOut2Data	Bulk out buffer (endpoint 8) data port	NA
0X250b	7:0	r/w	IntIn2Data	Interrupt in buffer (endpoint 9) data port	NA
0X2510	1:0	r/w	dmausbsrc	0: Bulk out buffer (endpoint 3) 1: Bulk out buffer (endpoint 8)	2'h0
0x2511	1:0	r/w	dmausbdst	0: Bulk in buffer (endpoint 2) 1: Int in buffer (endpoint 4) 2: Bulk in buffer (endpoint 7) 3: Int in buffer (endpoint 9)	2'h0
0x2520	7:0	r/w	Img0inf	Property byte	8'h0
0x2521	7:0	r/w	Img1inf	Property byte	8'h0
0x2522	7:0	r/w	Img2inf	Property byte	8'h0
0x2523	7:0	r/w	Img3inf	Property byte	8'h0
0x2524	7:0	r/w	Img4inf	Property byte	8'h0
0x2525	7:0	r/w	Img5inf	Property byte	8'h0
0x2526	7:0	r/w	Img6inf	Property byte	8'h0
0x2527	7:0	r/w	Img7inf	Property byte	8'h0
0x2531	0	r/w	bulkinbsramen	The first bulk in buffer sram enable	1'h1
	1	r/w	bulkoutbsramen	The first bulk out buffer sram enable	1'h1
	2	r/w	intinbsramen	The first interrupt in buffer sram enable	1'h1
	3	r/w	bulkin2bsramen	The second bulk in buffer sram enable	1'h1
	4	r/w	bulkout2bsramen	The second bulk out buffer sram enable	1'h1
	5	r/w	intin2bsramen	The second interrupt in buffer sram enable	1'h1
	6	r/w	vidbsramen	Video buffer sram enable	1'h1
0x2540	7:0	r	BulkInAckCnt[7:0]	The number of bulk in transactions (endpoint 2) being acked by the device	8'h0
0x2541	7:0	r	BulkInAckCnt[15:8]	The number of bulk in transactions (endpoint 2) being acked by the device	8'h0
0x2542	7:0	r	BulkInAckCnt[23:16]	The number of bulk in transactions (endpoint 2) being acked by the device	8'h0

				device	
0x2543	7:0	r	BulkOutAckCnt[7:0]	The number of bulk out transactions (endpoint 3) being acked by the device	8'h0
0x2544	7:0	r	BulkOutAckCnt[15:8]	The number of bulk out transactions(endpoint 3) being acked by the device	8'h0
0x2545	7:0	r	BulkOutAckCnt[23:16]	The number of bulk out transactions(endpoint 3) being acked by the device	8'h0
0x2546	7:0	r	IntInAckCnt[7:0]	The number of interrupt in (endpoint 4) transactions being acked by the device	8'h0
0x2547	7:0	r	IntInAckCnt[15:8]	The number of interrupt in transactions(endpoint 4) being acked by the device	8'h0
0x2548	7:0	r	IntInAckCnt[23:16]	The number of interrupt in transactions (endpoint 4) being acked by the device	8'h0
0x2549	0	r/w	BulkInAckCntRst	Bulk in transaction count reset. Reset the number of bulk in transactions (endpoint 2) acked by the device.	1'h0
	1	r/w	BulkOutAckCntRst	Bulk out transaction count reset. Reset the number of bulk out transactions (endpoint 3) acked by the device.	1'h0
	2	r/w	IntInAckCntRst	Interrupt in transaction count reset. Reset the number of bulk out transactions (endpoint 4) acked by the device.	1'h0
0x2550	7:0	r	BulkIn2AckCnt[7:0]	The number of bulk in transactions (endpoint 7) being acked by the device	8'h0
0x2551	7:0	r	BulkIn2AckCnt[15:8]	The number of bulk in transactions (endpoint 7) being acked by the device	8'h0
0x2552	7:0	r	BulkIn2AckCnt[23:16]	The number of bulk in transactions (endpoint 7) being acked by the device	8'h0
0x2553	7:0	r	BulkOut2AckCnt[7:0]	The number of bulk out transactions (endpoint 8) being acked by the device	8'h0
0x2554	7:0	r	BulkOut2AckCnt[15:8]	The number of bulk out transactions (endpoint 8) being acked by the device	8'h0
0x2555	7:0	r	BulkOut2AckCnt[23:16]	The number of bulk out transactions (endpoint 8) being acked by the device	8'h0
0x2556	7:0	r	IntIn2AckCnt[7:0]	The number of bulk out transactions (endpoint 8) being acked by the device	8'h0
0x2557	7:0	r	IntIn2AckCnt[15:8]	The number of interrupt in transactions (endpoint 9) being acked by the device	8'h0
0x2558	7:0	r	IntIn2AckCnt[23:16]	The number of interrupt in transactions (endpoint 9) being acked by the device	8'h0
0x2559	0	r/w	BulkIn2AckCntRst	Bulk in transaction count reset. Reset the number of bulk in transactions (endpoint 7) acked by the device	1'h0
	1	r/w	BulkOut2AckCntRst	Bulk out transaction count reset. Reset the number of bulk in transactions (endpoint 8) acked by the device	1'h0
	2	r/w	IntIn2AckCntRst	Interrupt in transaction count reset. Reset the number of bulk in transactions (endpoint 9) acked by the device	1'h0
0x25a0	0	r/w	Ep0OutEn	When write one, it indicates the chip will accept the next ep0 OUT packet; otherwise the packet will be rejected.	1'h0
	1	r/w	Ep0InEn	When write one, the CPU has completely written data into the ep0 buffer for the next ep0 IN packet cycle; otherwise the cycle will be rejected.	1'h0
0x25a1	0	r/w	BulkInEn	Write one to allow the next bulk in transaction (endpoint 2)	1'h0
	1	r/w	BulkOutEn	Write one to allow the next bulk out transaction (endpoint 3)	1'h0
	2	r/w	IntInEn	Write one to allow the next interrupt in transaction (endpoint 4)	1'h0
	3	r/w	BulkIn2En	Write one to allow the next bulk in transaction (endpoint 7)	1'h0

	4	r/w	BulkOut2En	Write one to allow the next bulk out transaction (endpoint 8)	1'h0
	5	r/w	IntIn2En	Write one to allow the next interrupt in transaction (endpoint 9)	1'h0
	6	r/w	BulkOutBufDMABlk	1: Block the data path from the Bulk-out buffer (endpoint3) to DMA	1'h0
	7	r/w	BulkOutBuf2DMABlk	1: Block the data path from the Bulk-out buffer (endpoint8) to DMA	1'h0
0X25a2	1	r	RmWakeFeat	The USB remote wakeup feature	1'h0
0X25b1	3:0	r	Ep0BufCnt	The data count in the ep0 buffer.	4'h0
	7:4	r	USBCfg	The USB configuration for the device.	4'h0
0X25b2	3:0	r	USBVidAs	The alternative setting of video iso in endpoint.	4'h0
	7:4	r	USBAudAs	The alternative setting of audio iso in endpoint.	4'h0
0X25b3	6:0	r	BulkInBufInPtr	The number of bytes written into the bulk in buffer (endpoint 2)	7'h0
0X25b4	6:0	r	BulkOutBufInPtr	The number of bytes written into the bulk out buffer (endpoint 3)	7'h0
0X25b5	6:0	r	IntInBufInPtr	The number of bytes written into the interrupt in buffer (endpoint 4)	7'h0
0X25b6	6:0	r	BULKIn2BufInPtr	The number of bytes written into the bulk in buffer (endpoint 7)	7'h0
0X25b7	6:0	r	BULKOut2BufInPtr	The number of bytes written into the bulk out buffer (endpoint 8)	7'h0
0X25b8	6:0	r	INT2BufInPtr	The number of bytes written into the interrupt in buffer (endpoint 9)	7'h0
0X25ba	6:0	r	BulkOutBufOutPtr	The number of bytes read from the bulk out buffer (endpoint 3)	7'h0
0X25bd	6:0	r	BulkOut2BufOutPtr	The number of bytes read from the bulk out buffer (endpoint 8)	7'h0
0X25c0	0	r/w	Ep0SetupAck	When high, it indicates a SETUP packet is put in the ep0 buffer. When write zero, the event will be cleared.	1'h0
	1	r/w	Ep0OutAck	When high, it indicates an OUT packet is put in the ep0 buffer. When write zero, the event will be cleared.	1'h0
	2	r/w	Ep0InAck	When high, it indicates an IN packet is removed from the ep0 buffer. When write zero, the event will be cleared.	1'h0
	3	r/w	USBResetEvt	When high, it indicates the USB reset event is detected. When write zero, the event will be cleared.	1'h0
	4	r/w	USBSusEvt	When high, it indicates the USB suspend event is detected. When write zero, the event will be cleared.	1'h0
	5	r/w	USBCfgChg	When high, it indicates the USB configuration is changed. When write zero, the event will be cleared.	1'h0
	6	r/w	RmWakeChg	When high, it indicates the remote wakeup feature is changed. When write zero, the event will be cleared.	1'h0
	7	r/w	USBRsmEvt	USB resume event 1: USB host resume event Write 0 to clear the signal	1'h0
0X25c1	0	r/w	VidASChg	When high, it indicates the alternative setting of video ISO-IN pipe is changed. When write zero, the event will be cleared.	1'h0
	1	r/w	AudASChg	When high, it indicates the alternative setting of audio ISO-IN pipe is changed. When write zero, the event will be cleared.	1'h0
	5:2		Reserved	Reserved for future use	4'h0
	6	r/w	AudIntInAck	When high, it indicates an audio interrupt in packet is accepted. When write zero, the event will be cleared.	1'h0
	7	r/w	AudIntInNak	When high, it indicates an audio interrupt in packet is rejected. When write zero, the event will be cleared.	1'h0
0X25c2	0	r/w	BulkInAck	Bulk in transaction (endpoint 2) acked 1: the bulk in transaction was acked. Write 0 to clear the signal.	1'h0
	1	r/w	BulkOutAck	Bulk out transaction (endpoint 3) acked 1: the bulk out transaction was acked. Write zero to clear the signal.	1'h0

	2	r/w	IntInAck	Bulk in transaction (endpoint 4) acked 1: the bulk in transaction was acked. Write zero to clear the signal.	1'h0
	3	r/w	BulkIn2Ack	Bulk in transaction (endpoint 7) acked 1: the bulk in transaction was acked. Write zero to clear the signal.	1'h0
	4	r/w	BulkOut2Ack	Bulk out transaction (endpoint 8) acked 1: the bulk out transaction was acked. Write zero to clear the signal.	1'h0
	5	r/w	INT2Ack	Bulk in transaction (endpoint 9) acked 1: the bulk in transaction was acked. Write zero to clear the signal.	1'h0
0X25d0	0	r/w	EP0SetupOKEn	When high, it indicates the interrupt for the EP0 SETUP packet OK event is enabled.	1'b0
	1	r/w	EP0OutOKEn	When high, it indicates the interrupt for the EP0 OUT packet OK event is enabled.	1'b0
	2	r/w	EP0InOKEn	When high, it indicates the interrupt for the EP0 IN packet OK event is enabled.	1'b0
	3	r/w	USBResetEvtEn	When high, it indicates the interrupt for the USB reset event is enabled.	1'b0
	4	r/w	USBSusEvtEn	When high, it indicates the interrupt for the USB suspend is enabled.	1'b0
	5	r/w	USBCfgChgEn	When high, it indicates the interrupt for the USB configuration change event is enabled.	1'b0
	6	r/w	RmWakeChgEn	When high, it indicates the interrupt for the remote wakeup feature change is enabled.	1'b0
	7	r/w	USBRsmEvt	When high, it indicates the interrupt for the USB resume is enabled.	
0X25d1	0	r/w	VidASChgEn	When high, it indicates the interrupt for the change event of video iso in alternative setting is enabled.	1'h0
	1	r/w	AudASChgEn	When high, it indicates the interrupt for the change event of audio iso in alternative setting is enabled.	1'h0
	5:2	r/w	Reserved	Reserved for future use	
	6	r/w	AudIntInAckEn	When high, it indicates the interrupt for the audio interrupt in packet OK event is enabled.	1'h0
	7	r/w	AudIntInNakEn	When high, it indicates the interrupt for the audio interrupt in packet NAK event is enabled.	1'h0
0X25d2	0	r/w	BulkInAckEn	Bulk in transaction acked interrupt enable Write 1 to enable the bulk in transaction (endpoint 2) acked interrupt Write 0 to disable the interrupt	1'h0
	1	r/w	BulkOutAckEn	Bulk out transaction acked interrupt enable Write 1 to enable the bulk out transaction (endpoint 3) acked interrupt Write 0 to disable the interrupt	1'h0
	2	r/w	IntInAckEn	Interrupt in transaction acked interrupt enable Write 1 to enable the interrupt in transaction (endpoint 2) acked interrupt Write 0 to disable the interrupt	1'h0
	3	r/w	BulkIn2AckEn	Bulk in transaction acked interrupt enable Write 1 to enable the bulk in transaction (endpoint 7) acked interrupt Write 0 to disable the interrupt	1'h0
	4	r/w	BulkOut2AckEn	Bulk out transaction acked interrupt enable Write 1 to enable the bulk out transaction (endpoint 8) acked interrupt Write 0 to disable the interrupt	1'h0
	5	r/w	IntIn2AckEn	Interrupt in transaction acked interrupt enable Write 1 to enable the interrupt in transaction (endpoint 9) acked interrupt Write 0 to disable the interrupt	1'h0



0X25e8	0	r/w	Ep0InStall	Endpoint 0 in transaction stall bit 0: normal operation 1: stall the in transaction for the control pipe	1'h0
	1	r/w	Ep0OutStall	Endpoint 0 out transaction stall bit 0: normal operation 1: stall the out transaction for the control pipe	1'h0
	2	r/w	BulkInStall	Bulk in pipe (endpoint 2) stall bit 0: normal operation 1: stall the bulk in pipe	1'h0
	3	r/w	BulkOutStall	Bulk out pipe (endpoint 3) stall bit 0: normal operation 1: stall the bulk out pipe	1'h0
	4	r/w	IntInStall	Interrupt in pipe (endpoint 4) stall bit 0: normal operation 1: stall the interrupt in pipe	1'h0
	5	r/w	BulkIn2Stall	Bulk in pipe (endpoint 7) stall bit 0: normal operation 1: stall the bulk in pipe	1'h0
	6	r/w	BulkOut2Stall	Bulk out pipe (endpoint 8) stall bit 0: normal operation 1: stall the bulk out pipe	1'h0
	7	r/w	IntIn2Stall	Interrupt in pipe (endpoint 9) stall bit 0: normal operation 1: stall the interrupt in pipe	1'h0
0X25e9	0	w	BulkInBufClr	Bulk in buffer (endpoint 2) clear 1: clear the bulk in buffer	1'h0
	1	w	BulkOutBufClr	Bulk out buffer (endpoint 3) clear 1: clear the bulk in buffer	1'h0
	2	w	IntInBufClr	Interrupt in buffer (endpoint 4) clear 1: clear the interrupt in buffer	1'h0
	3	w	BulkIn2BufClr	Bulk in buffer (endpoint 7) clear 1: clear the bulk in buffer	1'h0
	4	w	BulkOut2BufClr	Bulk out buffer (endpoint 8) clear 1: clear the bulk in buffer	1'h0
	5	w	IntIn2BufClr	Interrupt in buffer (endpoint 9) clear 1: clear the interrupt in buffer	1'h0
	0	w	VidCtlRst	Video control block reset 1: reset the video control block	1'h0
	0	w	VidBufClr	Video buffer clear 1: clear the video buffer	1'h0
0X25ea	0	w	EP0BufClr	Ep0 buffer clear 1: clear the endpoint 0 buffer	1'h0
0X25eb	0	w	BulkInNakClr	Bulk in pipe (endpoint 2) nak status clear Write 1 to clear the status register 0x25ee bit 0	NA
	1	w	BulkOutNakClr	Bulk out pipe (endpoint 3) nak status clear Write 1 to clear the status register 0x25ee bit 1	NA
	2	w	IntInNakClr	Interrupt in pipe (endpoint 4) nak status clear Write 1 to clear the status register 0x25ee bit 2	NA
	3	w	BulkIn2NakClr	Bulk in pipe (endpoint 7) nak status clear Write 1 to clear the status register 0x25ee bit 3	NA
	4	w	BulkOut2NakClr	Bulk out pipe (endpoint 8) nak status clear Write 1 to clear the status register 0x25ee bit 4	NA

	5	w	IntIn2NakClr	Interrupt in pipe (endpoint 9) nak status clear Write 1 to clear the status register 0x25ee bit 5	NA
0X25ec	1:0		Reserved	Reserved for future use	
	2	r	Ep0OutNak	When high, it indicates the endpoint 0 OUT packet is rejected. It will be cleared when the chip accepts another EP0 packet.	1'h0
	3	r	Ep0InNak	When high, it indicates the endpoint 0 IN packet is rejected. it will be cleared when the chip accepts another ep0 packet.	1'h0
0X25ed	3:0	r	Ep0BufOutPtr	The out pointer of the EP0 buffer.	4'h0
0X25ee	0	r	BulkInNak	When high, it indicates the bulk in (endpoint 2) packet is rejected. It will be cleared when the chip accepts another bulk in packet.	1'h0
	1	r	BulkOutNak	When high, it indicates the bulk out (endpoint 3) packet is rejected. It will be cleared when the chip accepts another bulk out packet.	1'h0
	2	r	InterruptInNak	When high, it indicates the interrupt in (endpoint 4) packet is rejected. It will be cleared when the chip accepts another interrupt in packet.	1'h0
	3	r	BulkIn2Nak	When high, it indicates the bulk in (endpoint 7) packet is rejected. It will be cleared when the chip accepts another bulk in packet.	1'h0
	4	r	BulkOut2Nak	When high, it indicates the bulk out (endpoint 8) packet is rejected. It will be cleared when the chip accepts another bulk out packet.	1'h0
	5	r	IntIn2Nak	When high, it indicates the interrupt in (endpoint 9) packet is rejected. It will be cleared when the chip accepts another interrupt in packet.	1'h0

### 2.8 Audio Control Registers

Address	Bit	Attr	Name	Description	Default value
0x2600	7:0	r/w	AuBData	The audio data port The CPU read/write the audio FIFO via this register.	NA
0x2601	7:0	r/w	AuOutAddr	6:0: the output address to read/write AC97 Codec register 7: (. 1 = read, 0 = write)	8'h0
0x2602	7:0	r/w	AuWDataL	the data to be programmed to the AC97 Codec register	8'h0
0x2603	7:0	r/w	AuWDataH	the data to be programmed to the AC97 Codec register	8'h0
0x2604	0	r/w	AC97En	0: disable the AC97 interface 1: enable the AC97 interface Either AudioEn(when set to 0) or AUCRst(when set to high) causes RESET# on the AC97 interface low.	1'h0
	1	r/w	AuWRst	If the bit is set to 1, AC-link sync signal is driven to 1 and the AC97 Codec is in warm reset state.	1'h0
	2	r/w	AuCRst	If this bit is set to 1, the AC-link reset signal is driven to 0 and the AC97 Codec is in cold reset state.	1'h0
	3	r/w	AuATETest	If this bit is set to 1, the SPCA504A drives the AC-link SDATA_OUT signal to 1. This register is used to place the AC97 codec in the ATE in circuit test mode. To perform ATE in circuit test, follow the steps below 1. set AuCRst to 1 2. set AuATETest to 1 3. set AuCRst to 0	1'h0
	4	r	CodecRdy	0: AC97 codec is not ready 1: AC97 codec is ready	NA
0x2605	2:0	r/w	AuBMode	Audio buffer mode 0: AC97/CODEC-to-USB, used in PCCAM mode 1:AC97/CODEC-to-CPU, used to record audio 2:CPU-to-AC97/DAC, used in audio playback 3:AC97/CODEC-to-DRAM, used to record audio	2'h0

				4:DRAM-to-AC97/DAC, used in audio playback 5:AC97/CODEC-to-DMAC, used to record audio 6:DMAC-to-AC97/DAC, used in audio playback	
0x2606	0	r/w	AuStereo	AC97/Codec link audio data capture option 0: capture only the left channel audio data 1: capture both left and right channel audio data.	1'h0
	1	r/w	Au16bit	AC97/Codec link audio data capture option 0: 8 bits per audio sample (MSB) 1: 16 bits per audio sample the data is 2's complement values. Note that for the embedded audio codec, 16-bit mode means appending 8 bits "0" to the LSB	1'h0
	2	r/w	PCM8En	AC97/Codec PCM8 format 0: the audio data format is defined in bit 3 1: use PCM8 format, which is 8 bits per sample and the data range is from 0 to 255. PCM8En can be set to 1 only in the audio playback mode	1'h0
	3		reserved	Reserved	
	5:4	r/w	AuDSMode	AC97/Codec audio data capture option. This feature is design to conserve the space of the storage media when the SPCA504A records the audio data via the AC-link. 0: no down sample 1: 2 times down sample 2: 6 times down sample please set AuDSMode 0 when playing back	2'h0
0x2607	2:0	r/w	AuDFreq	Data to AC97 codec (audio playback) frequency 0: 48 KHz 1: 24 KHz 4: 8 KHz please set AuDSMode 0 when playing back	3'h0
0x2608	8:0	r/w	AuBLThrL	Audio FIFO low threshold (low byte). During operation, the CPU may get the audio buffer status by reading the data count in register 0x26b5 and 0x26b4, or sets the threshold of the data count ,then wait for the interrupt. The CPU will be interrupted when the amount of data in the audio FIFO is less then the low threshold.	8'h0
0x2609	0	r/w	AuBLThrH	Audio FIFO low threshold(high byte). During operation, the CPU may get the audio buffer status by reading the data count in register 0x26b5 and 0x26b4, or sets the threshold of the data count ,then wait for the interrupt. The CPU will be interrupted when the amount of data in the audio FIFO is less then the low threshold.	1'h0
0x260a	7:0	r/w	AuBThrL	Audio FIFO high threshold (low byte). In the other way, the CPU will be interrupted when the amount of data in the audio FIFO exceeds the one defined in AuBThr.	8'h0
0x260b	7:0	r/w	AuBThrH	Audio FIFO high threshold (high byte). In the other way, the CPU will be interrupted when the amount of data in the audio FIFO exceeds the one defined in AuBThr.	1'h0
0x2660	7:0	r/w	MPTxDataL	MP3 processor serial interface TX data word (low byte).	8'h0
0x2661	7:0	r/w	MPTxDataH	MP3 processor serial interface TX data word (high byte). Each time when this byte is written, the data(in word) is transferred to the MP3 processor. Writing to this register will trigger a TX cycle to the MP3	8'h0

				processor.	
0x2662	7:0	r	MPRxDataL	MP3 processor serial interface RX data word (low byte).	NA
0x2663	7:0	r	MPRxDataH	MP3 processor serial interface RX data word (high byte). Reading this register will trigger the next RX cycle from the MP3 processor.	NA
0x2664	0	r/w	MP3en	MP3 processor interface enable bit 0: disable the serial interface to MP3 processor 1: enable the serial interface to MP3 processor	1'h0
0x2665	0	r/w	MPSlwrnn	Data transfer direction 0: data from MP3 processor to the camera ASIC 1: data from the camera ASIC to the MP3 processor	1'h0
0x2666	1:0	r/w	MPSlfreq[1:0]	MP3 processor serial interface, serial clock frequency selection 0: 1.5 MHz 1: 3 MHz 2: 6 MHz	2'b0
0x2667	7:0	r/w	MplengthL	MP3 processor interface, data transfer length (low byte). This register combined with MplengthH indicates how many words is going to be sent/received from the MP3 processor.	8'h0
0x2668	1:0	r/w	MplengthH	MP3 processor interface, data transfer length. This register combined with MplengthL indicates how many words is going to be sent/received from the MP3 processor.	2'b0
0x2669	0	r	MPSlready	During a TX cycle, MPSlready indicates the data has been transferred to the MP3 processor, the CPU may write the next data. During an RX cycle, MPSlready indicates a word of data is received from the MP3 processor, the CPU may read the data from register 0x2662 and 0x2663.	1'h0
	1	r	MPFCEB1	MP3 processor flag, this flag indicates whether the processor is ready.	NA
	2	r	MPFCEB2	MP3 processor flag, this flag is a periodical clock for record time stamp.	NA
0x266a	0	w	MPpprefetch	Write 1 to pre-fetch a word of data from the MP3 processor	NA
	1	w	MPSldummy	Write 1 to output 8 dummy clocks	NA
0x266b	0	r/w	MPrstnn	reset signal for the MP3 processor (active low)	1'h1
0x2670	0	r/w	ADCceb	ADC chip enable bit(low active) Write 0 to enable ADC Write 1 to disable ADC Please enable ADCceb, ADCshe, ADCagce, and ADCcade all together when using ADC	1'h1
	1	r/w	ADCade	ADC ad enable Write 1 to enable ADC ad Write 0 to disable ADC ad	1'h0
	2	r/w	ADCagce	ADC auto gain control enable Write 1 to enable ADC auto gain control Write 0 to disable ADC auto gain control	1'h0
	3	r/w	ADCshe	ADC sample and hold enable Write 1 to enable ADC sample and hold Write 0 to disable ADC sample and hold	1'h0
0x2671	0	r/w	ADCMute	ADC Mute control Write 1 to mute the ADC input Write 0 to unmute the ADC input	1'h1
0x2674	1:0	r/w	CodecFrqSel	0: 48KHz 1: 24KHz 2: 8KHz 3: 44.1KHz	4'h0
0x2675	0	r/w	DACEn	0: DAC disable	1'h0

				1: DAC enable	
	1	r/w	DACInvOut	0: Signed data for DAC 1: Unsigned data for DAC	1'b0
0x2676	7:0	r/w	EmbDACVolume	Volume control for the embedded audio DAC 0: mute 1: default setting 2~255: audio pcm value * EmbDACVolume	8'h1
0x2680	0	r/w	ADPCMEncEn	Write 1 to enable the ADPCM encoder	1'h0
	1	r/w	ADPCMDecEn	Write 1 to enable the ADPCM decoder	1'h0
0x2681	0	r/w	ADPCMPageMode	0: 512 bytes per page 1: 256 bytes per page	1'h0
0x26a0	0	w	AuOutReg	When write one, the value in the output address and data (only for the write mode) will be transmitted in the next audio frame. Do write one again when another data needs to be transmitted to the AC97 register.	NA
	1	w	AuBClr	When write one, all status about the audio buffer will be cleared. Do write one again when the audio needs to be cleared.	NA
0x26b0	6:0	r	AuInAddr	the register address in audio input frame	7'h0
0x26b1	7:0	r	AuInDataL	The register data(low byte) in audio input frame	8'h0
0x26b2	7:0	r	AuInDataH	The register data(high byte) in audio input frame	8'h0
0x26b3	0	r	AuOutBsy	When high, it indicates the process to out audio register is still going.	1'h0
	1	r/w	AuInVld	When high, it indicates there is valid data in the audio input address and data registers and the following input register data will be skipped. When write zero, the bit will be cleared.	1'h0
0x26b4	7:0	r	AuBCntL	The count of available data(low byte) in the audio buffer	8'h0
0x26b5	7:0	r	AuBCntH	The count of available data(high byte) in the audio buffer	8'h0
0x26c0	0	r/w	AuBUlLThr	When high, it indicates the audio buffer count is just under the low threshold. When write zero, the event will be cleared.	1'h0
	1	r/w	AuBOvHThr	When high, it indicates the audio buffer count is just over the high threshold. When write zero, the event will be cleared.	1'h0
0x26c1	0	R	MP3int	MP3 processor interrupt, the interrupt is generated when MPFCEB goes from low to high.	1'h0
0x26d0	0	r/w	AuBUlLThrEn	When high, it indicates the interrupt event for audio buffer count just under the low threshold is enabled.	1'h0
	1	r/w	AuBOvHThrEn	When high, it indicates the interrupt event for audio buffer count just over the high threshold is enabled.	1'h0
0x26d1	0	r/w	MP3inten	MP3 processor interrupt enable bit 0: disable , 1: enable	1'h0

## 2.9 SDRAM Control Registers

Address	bit	Attr	Name	Description	Default value
0X2700	7:0	r/w	DRAMdata[7:0]	DRAM data port low byte	8'b0
0X2701	7:0	r/w	DRAMdata[15:8]	DRAM data port high byte	8'b0
0X2702	7:0	r/w	DRAMaddr[7:0]	DRAM access address bit [7:0]	8'b0
0X2703	7:0	r/w	DRAMaddr[15:8]	DRAM access address bit [15:8]	8'b0
0X2704	7:0	r/w	DRAMaddr[23:16]	DRAM access address bit [23:16]	86b0
0X2705	7:0	rw	CLRsize[7:0]	During clear DRAM operation, this register indicates how many words will be cleared. The maximum size of each Clear DRAM operation is 64K words.	8'b0

0X2706	7:0	rw	CLRsize[15:8]		8'b0
0X2707	1:0	rw	DRAMtype[1:0]	DRAM type selection 0: SDRAM 1Mx16 bits x1 1: SDRAM 4Mx16 bits,4-bank 2: SDRAM 8M x 16 bits , 4-bank 3: SDRAM 16M x 16 bits, 4-bank	2'b0
	2	rw	Casmode	SDRAM casnn control signal type selection 0: only asserted during the first clock of access 1: assert for every access clock. This allows the DRAM controller to change the column address jumping sequence during a burst access. It is used when the horizontal sub-sampling of TV display is applied.	1'b0
0X2708	0	rw	Srefresh	0: normal operation 1: force SDRAM into self refresh state	1'b0
0X2709	3:0	rw	SDCKphase[3:0]	SDRAM clock phase adjustment. Each step is 1.3 ns , bit[3] reverse the clock	4'b0
	4	rw	sdckmode	0:stop the sdram clock while in the idle mode 1:always output the sdram clock	1'b0
0X270a	6:0	rw	Refrate[6:0]	DRAM refresh rate. The DRAM refresh is based on the Horizontal sync signal. The sdram will perform refrate[6:0] times of refresh cycles for a Horizontal sync signal.	7'd7
0X270b	7:0	rw	ClrData[7:0]	The value to filled into the DRAM when the clear DRAM operation is performed.	8'b0
0X270c	7:0	rw	ClrData[15:8]		8'b0
0X270e	2:0	rw	Imgtype[2:0]	3'b000: raw data 3'b001: YUV422 Non-compression 3'b010: YUV422 compression 3'b011: YUV420, Non-compression 3'b100: reserved 3'b101: YUV420, compression 3'b110: reserved 3'b111: reserved	3'b0
0X270f	1:0	rw	Fieldmode[1:0]	Image input mode selection 0: single field input. 1: reserved 2: 2-field mode, for interlace CCD 3: Special 2-field mode, for Sharp LZ23J3V In PCCAM mode, this register must always be set to 0. If an interlace CCD is connected to the SPCA533, then the sensor must be operated in the monitor (filed-accumulation) mode. If a TV decoder is connected to the SPCA533, then every filed is regarded as a complete image. In DSC mode, this register is set to 2 or 3 to get a full image of two fields. Set this register to 2 when SPCA503 is connected to a TV decoder.	2'b0
0X2711	0	rw	tmbformat	The DRAMCTRL will put the DCT DC value to the SDRAM. The "tmbformat" will determine the format that the DC value is arranged in the SDRAM. 0: in the order that the JPEG output the DC to the DRAMCTRL, that is the YYUV format. 1: in the order that the frame buffer arrange the YUV data, that is	1'b0

				the YUYV format.	
0X2712	0	rw	DoCDSP	This bit is used if a interlaced-type CCD is connected to the SPCA503. It must be set to 1 before starting the CDSP processing of the image. In other operation it must be set to 0.	1'b0
0X2713	0	rw	lcdpbmode	0: The LCD displayed data address is calculated from the LCD module. 1: The LCD displayed data address is calculated from the DRAMCTRL module.	1'b0
0X2715	0	rw	vlcardy	Status bit for the video clip buffer A. If the entire clipped frame is in buffer A, the hardware will set this bit to 1. Then the firmware can perform DMA to get the image data. After that, the firmware must reset this bit to 0 to allow another image coming.	1'b0
0X2716	0	rw	Vlcbrdy	Status bit for the video clip buffer B. If the entire clipped frame is in buffer B, the hardware will set this bit to 1. Then the firmware can perform DMA to get the image data. After that, the firmware must reset this bit to 0 to allow another image coming.	1'b0
0X2717	0	rw	refsrc	SDRAM refresh source 0: generate the refresh cycle from the TG h-sync signal 1: generate the refresh cycle from the LCD h-sync signal	1'b0
0X2720	7:0	rw	Size[7:0]	During compression, the size record the final size of the compressed image. During playback (decompress), the size register must filled with the size of the VLC data before moving data from flash memoty to the DARM VLC FIFO.	8'b0
0X2721	7:0	rw	Size[15:8]		8'b0
0X2722	7:0	rw	Size[23:16]		8'b0
0X2723	2:0	rw	Audbufsize[2:0]	The allocation size of the audio buffer in SDRAM 0: 1K bytes 1: 2K bytes 2: 4K bytes 3: 8K bytes 4: 128 bytes(for testing)	3'b0
0X2730	7:0	rw	VLCstart[7:0]	The starting address of the VLC FIFO.	8'b0
0X2731	7:0	rw	VLCstart[15:8]		8'b0
0X2732	7:0	rw	VLCstart[23:16]		8'b0
0X2733	7:0	rw	VLCBstart[7:0]	The starting address of the VLCB FIFO.	8'b0
0X2734	7:0	rw	VLCBstart[15:8]		8'b0
0X2735	7:0	rw	VLCBstart[23:16]		8'b0
0X2736	7:0	rw	TMBstart[7:0]	Define the Thumbnail buffer starting address.	8'b0
0X2737	7:0	rw	TMBstart[7:0]		8'b0
0X2738	7:0	rw	TMBstart[23:16]		8'b0
0X2739	7:0	rw	CAPint[7:0]	Image capture interval. The DRAMCTRL will get one frame out of every "capint" input frames	8'b0
0X273A	7:0	rw	AUDstaddr[7:0]	The starting address of audio FIFO	8'b0
0X273B	7:0	rw	AUDstaddr[15:8]		8'b0
0X273C	7:0	rw	AUDstaddr[23:16]		8'b0
0X273D	0	rw	Audiodma	Indicates the DRAM DMA is for the audio FIFO. This bit must be asserted before triggering the audio dma to SDRAM.	1'b0
0X273E	0	rw	Audclipen	Actives the audio clip function	1'b0
	1	rw	Audir	The audio data path direction	1'b0

				0: from sdram to audio block 1: from audio block to sdram	
0X2744	0	rw	Bwmode	0: Color moode 1:Black and white mode	1'b0
	1	rw	Raw8bit	0:10-bit raw data 1: 8-bit raw data	1'b0
0X2745	2:0	rw	Pbrescale[2:0]	Scaling of the image in the playback mode. 0: full size playback 1: 1/8 size playback 2: 2/8 size playback 3: 3/8 size playback 4: 4/8 size playback 5: 5/8 size playback 6: 6/8 size playback 7: 7/8 size playback	3'b0
0X2746	0	rw	Frcen	Frame rate concersion enable 0: disable frame rate conversion 1: enable frame rate conversion	1'b0
0X2747	0	rw	Frcmode	Frame rate conversion mode 0: CCD is faster than LCD display 1: CCD is slower than LCD display	1'b0
0X2748	0	rw	Lcdsrcidx	LCD frame buffer display index 0: Frame buffer A 1: Frame bugger B	1'b0
0X2749	0	rw	Ccdsrcidx	CCD frame buffer write index 0: Frame buffer A 1: Frame bugger B	1'b0
0X274A	0	rw	Jpgsrcidx	JPEG source frame buffer index 0: Frame buffer A 1: Frame bugger B	1'b0
0X2750	7:0	Rw	Dmastaddr[7:0]	The DMAstaddr[23:0] indicates the starting address that the dma controller will access DRAM.	8'b0
0X2751	7:0	Rw	Dmastaddr[15:8]		8'b0
0X2752	7:0	Rw	Dmastaddr[23:16]		8'b0
0X2753	7:0	rw	Afbaddr[7:0]	Fram buffer A starting address low byte	8'b0
0X2754	7:0	rw	Afbaddr[15:8]	Fram buffer A starting address middle byte	8'b0
0X2755	7:0	rw	Afbaddr[23:16]	Fram buffer A starting address high byte	8'b0
0X2756	7:0	rw	Bfbaddr[7:0]	Fram buffer B starting address low byte	8'b0
0X2757	7:0	rw	Bfbaddr[15:8]	Fram buffer B starting address middle byte	8'b0
0X2758	7:0	rw	Bfbaddr[23:16]	Fram buffer B starting address high byte	8'b0
0X2759	7:0	rw	osdaddr[7:0]	Osd buffer starting address low byte	8'b0
0X275A	7:0	rw	osdaddr[15:8]	Osd buffer starting address middle byte	8'b0
0X275B	7:0	rw	osdaddr[23:16]	Osd buffer starting address high byte	8'b0
0X2760	7:0	rw	Afbhsize[7:0]	Frame buffer A image width low byte	8'b0
0X2761	3:0	rw	Afbhsize[11:8]	Frame buffer A image width high byte	8'b0
0X2762	7:0	rw	Afvhsize[7:0]	Frame buffer A image height low byte	8'b0
0X2763	3:0	rw	Afvhsize[11:8]	Frame buffer A image height high byte	8'b0
0X2764	7:0	rw	Bfbhsize[7:0]	Frame buffer B image width low byte	8'b0
0X2765	3:0	rw	Bfbhsize[11:8]	Frame buffer B image width high byte	8'b0
0X2766	7:0	rw	Bfbvsize[7:0]	Frame buffer B image height low byte	8'b0
0X2767	3:0	rw	Bfbvsize[11:8]	Frame buffer B image height high byte	8'b0
0X2768	7:0	rw	Rfbaddr[7:0]	Raw data frame buffer starting address low byte	8'b0



0X2769	7:0	rw	Rfbaddr[15:8]	Raw data frame buffer starting address middle byte	8'b0
0X276A	7:0	rw	Rfbaddr[23:16]	Raw data frame buffer starting address high byte	8'b0
0X276B	7:0	rw	Rfbhsize[7:0]	Raw data frame buffer image width low byte	8'b0
0X276C	3:0	rw	Rfbhsize[11:8]	Raw data frame buffer image width high byte	4'b0
0X276D	7:0	rw	Rfbvsize[7:0]	Raw data frame buffer image height low byte	8'b0
0X276E	3:0	rw	Rfbvsize[11:8]	Raw data frame buffer image height low byte	4'b0
0X2770	2:0	rw	Scamode[2:0]	Scamode[0] 0: horizontal scaling function 1: vertical scaling function scamode[1] 0: scaled by dropping the pixel or line 1: scaled by the built-in filter scamode[2] 0: scaled down function 1: scaled up function	3'b010
	7:4	rw	Gprmode[3:0]	Graphic Processing mode 0: graphics idle mode 1: Image-scaling operation 2: Image-rotation operation 3: copy & paste operation 4: osd font scaling operation 5: osd font stamping operation 6: DRAM-to-DRAM DMA operation 7: bad-pixel correction 8: inter-frame raw data subtraction 9: YUV420-to-YUV422 conversion others : reserved	4'b0
0X2771	7:0	rw	Agbaddr[7:0]	Image processing buffer A starting address low byte	8'b0
0X2772	7:0	rw	Agbaddr[15:8]	Image processing buffer A starting address middle byte	8'b0
0X2773	7:0	rw	Agbaddr[23:16]	Image processing buffer A starting address high byte	8'b0
0X2774	7:0	rw	Bgbaddr[7:0]	Image processing buffer B starting address low byte	8'b0
0X2775	7:0	rw	Bgbaddr[15:8]	Image processing buffer B starting address middle byte	8'b0
0X2776	7:0	rw	Bgbaddr[23:16]	Image processing buffer B starting address high byte	8'b0
0X2777	7:0	rw	Agbhsize[7:0]	Image processing buffer A image width low byte	8'b0
0X2778	3:0	rw	Agbhsize[11:8]	Image processing buffer A image width high byte	4'b0
0X2779	7:0	rw	Agbvsize[7:0]	Image processing buffer A image height low byte	8'b0
0X277A	3:0	rw	Agbvsize[11:8]	Image processing buffer A image height high byte	4'b0
0X277B	7:0	rw	Bgbhsize[7:0]	Image processing buffer B image width low byte	8'b0
0X277C	3:0	rw	Bgbhsize[11:8]	Image processing buffer B image width high byte	4'b0
0X277D	7:0	rw	Bgbvsize[7:0]	Image processing buffer B image height low byte	8'b0
0X277E	3:0	rw	Bgbvsize[11:8]	Image processing buffer B image height high byte	4'b0
0X277F	7:0	rw	Scalefactor[7:0]	The scaling factor low byte	8'b0
0X2780	7:0	rw	Scalefactor[15:8]	The scaling factor high byte	8'b0
0X2781	7:0	rw	agbhoff[7:0]	The X-coordinate offset to copy the image from the Image processing buffer A	8'b0
0X2782	2:0	rw	agbhoff[11:8]		4'b0
0X2783	7:0	rw	agbvoff[7:0]	The Y-coordinate offset to copy the image from the Image processing buffer A	8'b0
0X2784	2:0	rw	agbvoff[11:8]		4'b0
0X2785	1:0	rw	Fontzoom[1:0]	Font scaling option 0: reserved 1: 2x2	2'b1

				2: 3x3 3: 4x4	
0X2786	0	rw	rotatedir	The rotation direction of DRAM rotation engine 0: rotate clockwise 1: rotate counter-clockwise	1'b0
	1	rw	jpgroten	Perform jpeg rotation function 0: disable 1: enable	1'b0
0X2787	1:0	rw	Bordercolr[1:0]	Color of the border font 0: as the background color 1: as the foreground color 2: black color	2'b0
	3:2	rw	Hlforecolr[1:0]	Color of the half-tone font 0: as the background color 1: as the foreground color 2: black color	2'b0
	6:4	rw	Forecolr[2:0]	Color of the foreground font 0: white 1: yellow 2: cyan 3: green 4: magenta 5: red 6: blue 7: black	3'b1
0X2788	7:0	rw	Badpixthd	The threshold value for the bad pixel correction engine	8'b0
0X2789	7:0	Rw	Dramdmasize[7:0]	The size (bytes) transferred in DRAM-to-DRAM DMA engine. The actual number of bytes is (Dramdmasize+1).	8'b0
0X278A	1:0	Rw	Dramdmasize[9:8]		2'b0
0X278B	0	Rw	DmasrcLSB	The DRAM to DRAM DMA source address LSB bit. The byte address[24:0] of source is { Agbaddr[23:0], DmasrcLSB }	1'b0
	1	Rw	DmadtnLSB	The DRAM to DRAM DMA destination address LSB bit. The byte address[24:0] of destination is { Bgbaddr[23:0], DmadtnLSB }	1'b0
0X278C	7:0	Rw	Pastehsz[7:0]	The width of the copied portion of the copied & paste engine	8'b0
0X278D	3:0	Rw	Pastehsz[11:8]		4'b0
0X278E	7:0	Rw	Pastevsz[7:0]	The height of the copied portion of the copied & paste engine	8'b0
0X278F	3:0	Rw	Pastevsz[11:8]		4'b0
0X2790	0	rw	vscalemode	0: dram vertical scaled down function 1: dram vertical scaled up function	1'b0
	1	rw	dramvscalesn	0: disable dram vertical scaled function 1: enable dram vertical scaled function	
0X2791	7:0	Rw	vscalcnt	The DRAMCTRL will duplicate one line every "vscalcnt+1" lines if the dram vertical scale up function is enable. And it will cut a line every "vscalcnt+1" lines if the dram vertical down function is enable.	8'b0
0X2792	7:0	Rw	Vscalevsz[7:0]	The target line number after the dram vertical scale up or scale down function.	8'b0
0X2793	3:0	Rw	Vscalevsz[11:8]		4'b0
0X2794	7:0	Rw	Bgbhoff[7:0]	The X-coordinate offset to paste the image to the Image processing buffer B	8'b0
0X2795	3:0	Rw	Bgbhoff[11:8]		4'b0

0X2796	7:0	Rw	Bgbvoff[7:0]	The Y-coordinate offset to paste the image to the Image processing buffer	8'b0
0X2797	3:0	Rw	Bgbvoff[11:8]		4'b0
0X2798	7:0	Rw	Pastethd[7:0]	Bit7: set 1 to enable the color key function of the copy&paste engine. Bit[6:0]: the threshold value for the color key attribute.	8'b0
0X27A0	0	w	Prefetch	Write 1 to prefetch a word from SDRAM	NA
	1	w	CLRmem	Write 1 to Clear the DRAM	NA
	2	w	INITsdram	Write 1 to Initalize SDRAM	NA
0X27A1	0	w	STcomp	Write 1 to trigger compression of the captured image.	NA
	1	w	STdecomp	Write 1 to start decompression	NA
	4	w	STcdsp	Write 1 to start the color processing. This control bit applied only to the interlace-type CCD sensors.	NA
	5	w	StopClip	Write 1 to this bit will stop the video clip procedure. The Video clip procedure stop when this bit is written to 1 or when the predefined VLC buffer is full.	NA
	6	w	Audcliprst	Write 1 to reset the audclip function	NA
	7	w	STgraproc	Write 1 to this bit will start the graphic processing function	NA
0X27B0	0	R	DRAMbusy	The DRAM controller is busy reading/write data	1'b0
	1	R	CAPdone	Image is captured and stored in the DRAM	NA
	2	R	ClipDone	Video clip is done, it indicates the predefined buffer is full.	NA
	3	R	Precdspdone		NA
	5	R	CompDone	Compression completed	NA
	6	R	DecoDone	Decompression completed	NA
	7	R	gpdone	Graphic processed done	NA
0X27B1	7:0	R	Clipcnt[7:0]	Video clip frame count. This register is used in Video clip mode. It indicates how many frames has been processed and stored in the SDRAM. This register is automatically cleared when the camera is set into the IDLE mode.	NA
0X27B3	7:0	R	Auddatacnt[7:0]	The accumulation audio data size in the sdram audio buffer	NA
0X27B4	5:0	R	Auddatacnt[13:8]	The accumulation audio data size in the sdram audio buffer	NA
0X27B5	0	R	Audbufov	Indicates the audio buffer in SDRAM is overflow	NA
0X27B6	7:0	R	Jpghsz[7:0]	The target image width. Software could refer to the jpghsz to show the picture.	
0X27B7	3:0	R	Jpghsz[11:8]		
0X27B8	7:0	R	Jpgvsize[7:0]	The target image height. Software could refer to the jpgvsize to show the picture.	
0X27B9	3:0	R	Jpgvsize[11:8]		
0X27C0	0	rw	DRAMint	Frame done interrupt. This interrupt is generated in the Video clip mode after each frame is compressed and stored in the SDRAM. Write 0 to clear the interrupt.	1'b0
0X27D0	0	rw	DRAMinten	Frame done interrupt enable bit. 0: disable 1: enable	1'b0
0X27E1	0	rw	Siggenen	Embedded signal generator enable bit 0: disable 1: enable	1'b0
	1	rw	Sigyuven	If turned on, the CDSP module will input the RGB raw data from the signal generator and output the YUV data to the DRAMCTRL.	1'b0
0X27E2	1:0	rw	HVadj[1:0]	Horizontal and vertical offset adjustment This register is used to match the raw data RGB plane origin.	2'b0

0X27E3	4:0	rw	Sigmode[4:0]	Signal generator pattern mode Sigmode[4] determin the color saturation 0: saturation 1: 75% saturation Sigmode[3:0] 0000: Still, White 0001: Still, Yellow 0010: Still, Cyan 0011: Still, Green 0100: Still, Magenta 0101: Still, Red 0110: Still, Blue 0111: Still, Black 1000: Gray level 1001: hcnt 1010: vcnt 1011: hcnt-17 (0,1,2,3.....) 1100: Still vertical color bar 1101: Still horizontal color bar 1110: R, G, B, and W flashing 1111: Moving horizontal color bar others : reserved	4'b0
0X27E7	0	rw	menuen	Turn on this bit will enable the menu bar function in PREVIEW mode	1'b0
0X27E8	7:0	rw	Menuhoff[7:0]	Define the the X-coordinate of the menu bar area starting point	8'b0
0X27E9	3:0	Rw	Menuhoff[11:8]		4'b0
0X27EA	7:0	Rw	Menuvoff[7:0]	Define the the Y-coordinate of the menu bar area starting point	8'b0
0X27EB	3:0	Rw	Menuvoff[11:8]		4'b0
0X27EC	7:0	Rw	Menussize[7:0]	Define the width of the menu bar	8'b0
0X27ED	3:0	Rw	Menussize[11:8]		4'b0
0X27EE	7:0	Rw	Menussize[7:0]	Degine the height of the menu bar	8'b0
0X27EF	3:0	Rw	Menussize[11:8]		4'b0
0X27F0	7:0	Rw	Afbhwidth[7:0]	The horizontal width of A frame buffer. The value is equal to "Afbhsize" when the whole data is accessed in one time. If only sub-image is accessed in this buffer, the value of "Afbhwidth" is defined as the horizontal size of whole image and the value of "Afbhsize" is defined as the horizontal size of sub-image.	8'h0
0X27F1	3:0	Rw	Afbhwidth[11:8]		4'h0
0X27F2	7:0	Rw	Bfbhwidth[7:0]	The horizontal width of B frame buffer.	8'h0
0X27F3	3:0	Rw	Bfbhwidth[11:8]		4'h0
0X27F4	7:0	Rw	Rfbhwidth[7:0]	The horizontal width of R frame buffer. (for image raw data)	8'h0
0X27F5	3:0	Rw	Rfbhwidth[11:8]		4'h0
0X27F6	7:0	Rw	Afbhoff[7:0]	The horizontal offset of A frame buffer. When only sub-image is accessed in A frame buffer, the value of "Afbhoff" is defined as the horizontal starting point of the whole image	8'h0
0X27F7	3:0	Rw	Afbhoff[11:8]		4'h0
0X27F8	7:0	Rw	Bfbhoff[7:0]	The horizontal offset of B frame buffer.	8'h0
0X27F9	3:0	Rw	Bfbhoff[11:8]		4'h0
0X27FA	7:0	Rw	Rfbhoff[7:0]	The horizontal offset of R frame buffer.	8'h0
0X27FB	3:0	Rw	Rfbhoff[11:8]		4'h0
0X27FC	1:0	Rw	Winhsub[1:0]	The horizontal raw data subsample rate in calculating the AE/AWB	2'h0

				window value. 0: 1 1: 2 2: 4 3: 8	
	5:4	Rw	Winvsub[1:0]	The vertical raw data subsample rate in calculating the AE/AWB window value. 0: 1 1: 2 2: 4 3: 8	2'h0
0X27FD	0	Rw	winskyuv	The YUV data generated in calculating the AE/AWB window value. 0: store to SDRAM 1: skip	1'b0
	1	rw	cdsprawen	The raw data generated by CDSP to store to SDRAM 0: disable 1: enable	1'b0
	2	rw	Frcimgfirst	When one, force to indicate the current accessing part is the first part of an image. The bit must be set when the offset of the first part of accessing image doesn't start from zero.	1'b0
	3	rw	Frcimglast	When one, force to indicate the current accessing part is the last part of an image. The bit must be set when the horizontal boundary of the last part of accessing image doesn't end in the horizontal boundary of an image.	1'b0

## 2.10 JPEG Control Registers

Address	Bit	Attr	Name	Description	Default value
0X2800	7:0	r/w	Yqtable	Quantization table for Y-component The values of Q are filled in the raster-scan format.	
0X283F	7:0	r/w			
0X2840	7:0	r/w	Cqtable	Quantization table for C-component	
0X287F	7:0	r/w			
0X2880	7:0	r/w	Noqtbl	Index of the Q-table currently used This register is for internal check only.	8'b0
0X2881	0	r/w	Qvalueone	0: original 1: quantizer coefficients are set to one	1'b0
0X2882	0	r/w	AccQtableEn	0: Normal operation (Q-table is not allowed to access) 1: Write 1 to this bit, Q-table (0x2800 – 0x287F) is accessible by CPU.	1'b0
0X2883	0	r/w	Enthumb	1: Enable thumbnail image generation. 0: disable thumbnail image generation Thumbnail image is a by-product of the JPEG compression. The SPCA533 extract the DC value of each JPEG MCU (minimum coding unit) to construct the thumbnail image. If the image type is raw data or non-compression, then there is no thumbnail image available. Note this bit is used in the DSC mode only. In the Video mode, this bit should always be turned off.	1'b0
	1	r/w	StopEN	0: Normal operation. 1: Set this bit to enable stop mode. The decompression engine stops for	1'b0

				every block until the flag "blockend" is cleared (reg 0x2890 bit 0).	
0X2884	0	r/w	JFIF	JFIF compatible bit. 0: Original 1: Compatible with JFIF bit stream. In a standard JFIF bit stream, 0XFF is used as a marker to indicated the start point of a special control sequence. To represent VLC data 0XFF, 0X00 must be appended to distinguish from the marker.	1'b0
0X2885	0	r/w	Truncated	0: Rounded after quantization 1: Truncated after quantization	1'b0
0X2886	2:0	r	Vlcbit	Indicates the number of stuffing 1's in the last byte of the VLC stream. 0: non-stuffing 1's 1: 1 stuffing 1. ..... 7: 7 stuffing 1's. This information is passed to the PC in the Video mode for the software decoding to double-check the JPEG VLC stream data integrity.	
0X2887	0	r	JFIFend	After JFIF-compliant data is decompressed, check this bit to identify if data stream is decompressed completely or not. 0: error happened. 1: decompressed completely.	NA
0X2888	7:0	r/w	Restartmcu[7:0]	If the vlc stream include MCU restart code, fill the restart MCU number. Otherwise, set rstmcuno as 0 to disable restart code decompression.	8'b0
0X2889	7:0	r/w	Restartmcu[15:8]		8'b0
0X2890	0	r/w	Blockend	In stop mode, active high after end of block. Write 0 to clear this flag.	1'b0

### 2.11 Serial Interface Control Registers

Address	Bit	Attr	Name	Description	Default value
0x2900	6:0	R/W	Slaveaddr	The Slave Address (the device address)	7'h0
0x2901	1:0	R/W	Transmode	Decide the serial transfer way 2'b00: Synchronous Serial Normal mode 2'b01: Synchronous Serial Burst mode 2'b10: Using Three wire interface 2'b11: Using Three wire interface by manual control	2'h0
	5:4	R/W	CDSmode	This register determines different types of 'SEN', 'SDO', 'SCK' behavior 2'b00: (1) Need no SEN signal. ONLY SCK, SDO (2) Every rising SCK to latch SDO (3) Last falling edge of SCK must latch SDO@HIGH (4) After (3), a negedge@SDO will actually activate the programmed data into internal registers, EXAMPLE: SHARP IR3Y38M, 10-bit series data 2'b01: (1) Need SCK, SDATA, SEN signals (2) Every rising SCK to latch SDO (3) Rising of SEN to actually activate the programmed data into internal registers EXAMPLE: HITACHI HD49322F, 16-bit series data, ADI AD9803, 14-bit series data, EXAR XRD44L61/2, 10-bit series data	2'b00

				<p>2'b10:            (1) Need SCK, SDATA, SEN signals            (2) Every rising SCK to latch DATA            (3) SEN stays LOW during SCK CLOCKING, then one PULSE, to actually activate the programmed data into internal registers            EXAMPLE: PANASONIC AN2104FHQ, 11-bit series data</p> <p>2'b11:            (1) Need SCK, SDO, SLOAD signals            (2) Every rising SCK to latch DATA            (3) SEN stays LOW during SCK CLOCKING            (4) At the end of transfer, need a SEN pulse            EXAMPLE: FUJITSU VGA Sensor</p>	
0x2902	0	R/W	Subadden	<p>Decide SUBADDR need or not in READ            0: No sub address            1: Has subaddress</p>	1'b1
	1	R/W	Restarten	<p>This bit determines whether the Synchronous Serial interface's repeat start condition. (Only work in Synchronous Serial interface read).            0: Do not Repeat Start.            1: Repeat Start.</p>	1'b0
	4	R/W	Prefetch	<p>Writing this bit will initiate Synchronous Serial interface read sequence, it will auto clear after BUSY signal go Low, then the user can read the data buffer</p>	1'b0
0x2903	0	R/W	Syncvsync	<p>This bit determines whether the serial interface read/write will synchronize with VSYNC falling edge or not.            0: Read/write will occur immediately.            1: Waiting the frontvd falling edge, then transfer.</p>	1'b0
	1	R/W	Sifoe	<p>This bit determine the sen, sclk Pin output enable or not</p>	1'b0
	4	R/W	Senpol	<p>SEN polarity select</p>	1'b0
0x2904	2:0	R/W	Freq	<p>Synchronous serial interface speed selection (Use in Synchronous Serial interface)            3'b000: CPUCLK div 2048            3'b001: CPUCLK div 1024            3'b010: CPUCLK div 512            3'b011: CPUCLK div 256            3'b100: CPUCLK div 128            3'b101: CPUCLK div 64            3'b110: CPUCLK div 32            3'b111: CPUCLK div 16</p>	3'b010
	7:0	R/W	Cntdiv	<p>The CPUCLK / CNT_DIV to generation the three wire clock (Used in CDS)</p>	
0x2905	3:0	R/W	Wrcount	<p>Decide how many byte to write (Used in SSC mode)            4'h0: 16 Bytes            4'h1: 1 Bytes            .            .            4'hF: 15 Bytes</p>	4'h1
	7:4	R/W	Rdcount	<p>Decide how many byte to read (Used in SSC mode)</p>	4'h1
	6:0	R/W	Cdsbits	<p>The bits transfer to three wire interface (used in CDS mode)</p>	7'h11
0x290A	0	R/W	Mscclk	<p>The serial interface sclk value, when Transmode = 2'b11 (manual enable)</p>	1'b1
0x290B	0	R/W	Msdso	<p>The serial interface sd value, when Transmode = 2'b11 (manual enable)</p>	1'b1

0x290C	0	R/W	Msen	The serial interface sen value, when Transmode = 2'b11 (manual enable)	1'b1
0x2910	7:0	R/W	Addr0	The Address0 in BURST MODE (also the register address in normal mode)	8'h0
0x2911	7:0	R/W	Data0	The data buffer0	8'h0
0x2912	7:0	R/W	Addr1	The BURST Address1 in BURST MODE	8'h0
0x2913	7:0	R/W	Data1	The data buffer1	8'h0
0x2914	7:0	R/W	Addr2	The BURST Address2 in BURST MODE	8'h0
0x2915	7:0	R/W	Data2	The data buffer2	8'h0
0x2916	7:0	R/W	Addr3	The BURST Address3 in BURST MODE	8'h0
0x2917	7:0	R/W	Data3	The data buffer3	8'h0
0x2918	7:0	R/W	Addr4	The BURST Address4 in BURST MODE	8'h0
0x2919	7:0	R/W	Data 4	The data buffer4	8'h0
0x291A	7:0	R/W	Addr 5	The BURST Address5 in BURST MODE	8'h0
0x291B	7:0	R/W	Data 5	The data buffer5	8'h0
0x291C	7:0	R/W	Addr 6	The BURST Address6 in BURST MODE	8'h0
0x291D	7:0	R/W	Data 6	The data buffer6	8'h0
0x291E	7:0	R/W	Addr 7	The BURST Address7 in BURST MODE	8'h0
0x291F	7:0	R/W	Data 7	The data buffer7	8'h0
0x2910	7:0	R/W	Addr 8	The BURST Address8 in BURST MODE	8'h0
0x2921	7:0	R/W	Data 8	The data buffer8	8'h0
0x2922	7:0	R/W	Addr 9	The BURST Address9 in BURST MODE	8'h0
0x2923	7:0	R/W	Data 9	The data buffer9	8'h0
0x2924	7:0	R/W	Addr 10	The BURST Address10 in BURST MODE	8'h0
0x2924	1:0	R/W	thrfldmode	The Field number of three field CCD	2'h0
	4	R/W	thrflden	The Three field CCD enable	1'h0
	5	R/W	Inc3en	The dram address control signal to CDSP	1'h0
	7	R/W	sony3field	The SONY 3 Field CCD enable	1'h0
0x2925	7:0	R/W	Data 10	The data buffer10	8'h0
0x2926	7:0	R/W	Addr 11	The BURST Address11 in BURST MODE	8'h0
0x2926	1:0	R/W	hoffsetmhi	The Number of Pix clock for H-sync to Fronthdvalid when in monitor mode, is the hoffsetm[11:10]	2'h0
0x2927	7:0	R/W	Data 11	The data buffer11	8'h0
0x2928	7:0	R/W	Addr 12	The BURST Address12 in BURST MODE	8'h0
0x2929	7:0	R/W	Data 12	The data buffer12	8'h0
0x292A	7:0	R/W	Addr 13	The BURST Address13 in BURST MODE	8'h0
0x292B	7:0	R/W	Data 13	The data buffer13	8'h0
0x292C	7:0	R/W	Addr 14	The BURST Address14 in BURST MODE	8'h0
0x292D	7:0	R/W	Data 14	The data buffer14	8'h0
0x292E	7:0	R/W	Addr 15	The BURST Address15 in BURST MODE	8'h0
0x292F	7:0	R/W	Data 15	The data buffer15	8'h0
0x29A0	0	R	Busy	The status when Serial interface R/W register 1:Busy 0:Not Busy	NA
0x29B0	0	R/W	Rstsif	Write 1 to this bit will reset the serial interface	1'b0



### 2.12 TV-IN / CMOS Sensor Control register

Address	Bit	Attr	Name	Description	Default value
0x2A00	0	R/W	Exthdipol	The input H-sync polarity will be inverted when hi	1'b0
	1	R/W	Extvdipol	The input H-sync polarity will be inverted when hi	1'b0
	2	R/W	Exthdopol	The output V-sync polarity will be inverted when hi	1'b0
	3	R/W	Extvdopol	The output V-sync polarity will be inverted when hi	1'b0
	4	R/W	Extthdoedge	Decide output H-sync will work in Vclk positive edge or negative edge 0: Positive edge 1: Negative edge	1'b0
0x2A01	1:0	R/W	Nibborder	Select the input order for nibble mode	2'b00
	4	R/W	Nibben	Enable nibble data input 0: Disable 1: Enable	1'b0
0x2A02	0	R/W	Tasc5130aen	Enable Tasc5130a CMOS sensor for exposure control	1'b0
0x2A05	0	R/W	Bt656en	The 656 mode enable 0: 601 mode 1: 656 mode	1'b0
	1	R/W	Sub128en	The Y, Cb, Cr, value will sub 128 when this bit set 1	1'b1
	2	R/W	Selflden	When in 601 mode, if the bit set to 1, then field signal will generate by it self	1'b0
	4	R/W	Tvreshhen	This bit determinate the hvalid will set by Hoffset, or direct from Tvctr interface 0: the signal direct from Tvctr interface 1: You can set Hoffset, Hsize to get valid signal.	1'b0
	5	R/W	Tvreshven	This bit determinate the vvalid will set by Voffset or direct from Tvctr interface 0: the signal direct from Tvctr interface 1: You can set Voffset, Vsize, to get valid signal.	1'b0
0x2A06	1:0	R/W	Uvsel	This will decide the first pixel is Cb, Cr, Y1or Y2 2'b00: Cb 2'b01: Y1 2'b10: Cr 2'b11: Y2	2'b00
	4	R/W	Fldpol	0: The Fld signal will not invert. 1: The Fld signal will invert	1'b0
0x2A08, 07	15:0	R/W	Flashwidth	The Out put Flash control width	16'h60
0x2A09	2:0	R/W	Flashmode	3'b000: The flash control output signal will out immediately.	3'h0
				3'b001: The flash control output signal will sync with Sub in monitor mode	
				3'b010: The flash output signal will sync with sub in snap capture mode	
	3	R/W	Flashpol	Flash control polarity control	1'b0
	4	R/W	Flasgtrg	When Set it, will trigger the flash function (flashen = 1 & flashmode = 1), it will auto clear after control	1'b0
0x2A0B, 0A	11:0	R/W	Ftnum	The flash light will trigger in this line number define after Vd falling edge when Flashmode = 2'b11	12'h60

0x2A10	0	R/W	Hreshen	Enable reshape H-Sync to generation a new H-Sync signal to CDSP or others 0: Disable 1: Enable	1'b0
	1	R/W	Vreshen	Enable reshape V-Sync to generation a new V-Sync signal to CDSP or others 0: Disable 1: Enable	1'b0
	4	R/W	Vreshcntclk	Reshape V-sync counter clock select: 0: H-sync 1: vclk	1'b0
0x2A12, 11	11:0	R/W	Hfall	Control the position of internal H-sync falling edge, when H-sync reshape enable	12'h020
0x2A14, 13	11:0	R/W	Hrise	Control the position of internal H-sync rising edge, when H-sync reshape enable	12'h030
0x2A16, 15	11:0	R/W	Vfall	Control the position of internal V-sync falling edge, when V-sync reshape enable	12'h010
0x2A18, 17	11:0	R/W	Vrise	Control the position of internal V-sync rising edge, when V-sync reshape enable	12'h020
0x2A21, 20	11:0	R/W	Hoffset [11:0]	The Number of Pix clock for H-sync to Fronthdvalid in capture mode)	12'h29E
0x2A23, 22	11:0	R/W	Voffset [11:0]	The Number of H-sync for V-sync to frontvdvalid in CCD capture mode	12'h32
0x2A25, 24	11:0	R/W	Hsize [11:0]	The HSIZE of a frame in CCD capture mode	12'h640
0x2A27, 26	11:0	R/W	Vsize [11:0]	The VSIZE of a frame in CCD capture mode	12'h258
0x2A28	7:0	R/W	Vdvalidpos [7:0]	Define the Vdvalid rise and fall position after H-sync falling,(unit pixel clock)	8'h01
0x2A31, 30	9:0	R/W	Hoffsetm	The Number of Pix clock for H-sync to Fronthdvalid when in monitor mode	12'h29E
0x2A33, 32	11:0	R/W	Hsizem	The HSIZE of a frame in monitor mode	12'h640
0x2A35, 34	9:0	R/W	Voffsetm	The Number of H-sync for V-sync to frontvdvalid in monitor mode	8'h03
0x2A37, 36	11:0	R/W	Vsizem	The VSIZE of a frame when in monitor mode	12'hF0
0x2A39, 38	9:0	R/W	Voffsetafc	The Number of H-sync for V-sync to frontvdvalid when CCD enable in AF capture mode mode	8'h60
0x2A3B, 3A	11:0	R/W	Vsizeafc	The VSIZE of a frame when CCD enable in AF capture mode	12'h100
0x2A3D, 3C	9:0	R/W	Voffsetafm	The Number of H-sync for V-sync to frontvdvalid when CCD enable in Af monitor mode mode	8'h10
0x2A3F, 3E	11:0	R/W	Vsizeafm	The VSIZE of a frame when CCD enable in AF monitor mode	12'h50
0x2A40	0	R/W	Syncgenen	Enable the sync generator module; means the CMOS sensor need to give hd, vd. 0: Disable 1: Enable	1'b0
	1	R/W	Totalsvden	When set, the Linetotal, Frametotal, Frametotalm, Frametotalafc, Frametotalafm change will sync with frontvd fall edge	1'b0
	4	R/W	Frameblankcntclk	Frame blank counter clock select: 0: H-sync 1: vclk	1'b0
0x2A42, 41	11:0	R/W	Linetotal	The Number of Pix clock in a line, to TG (also the value in capture mode)	12'h8E8
0x2A44, 43	9:0	R/W	Lineblank	The Number of Pix clock in H-sync blank, to TG (also the value in capture mode)	10'hE4
0x2A46, 45	11:0	R/W	Frametotal	The Number of H-sync in a frame to TG (also the value in capture mode)	12'h290
0x2A48, 47	9:0	R/W	Frameblank	The width of frame blank, the counter is base on H-sync when Frameblankcntclk = 0, else base on vclk (also the	10'h02

				value in capture mode)	
0x2A4A, 49	10:0	R/W	Hdvdopos	This defines the exthdo and extvdo should separate how many pixels.	11'h1
0x2A51, 50	11:0	R/W	Frametotalm	The Number of H-sync in a frame, when CCD enable in monitor mode	12'h108
0x2A53, 52	11:0	R/W	Frametotalafc	The Number of H-sync in a frame, when CCD enable in AF capture mode	12'h200
0x2A55, 54	11:0	R/W	Frametotalafm	The Number of H-sync in a frame, when CCD enable in AF monitor mode	12'h70
0x2A80	0	R/W	Hpen	0: Not HP sensor 1: Hp sensor enable	1'b0
	1	R/W	Clk2divsvden	When Set, the Extclk2xdiv change will sync with Frontvd fall edge	1'b0
0x2A81	3:0	R/W	Extclk1xdiv	The factor of Extclk1x divide from Extclk2x 4'h0: Extclk2 / 1 4'h1: Extclk2 / 2 4'h2: Extclk2 / 3 . 4'hF: Extclk2 / 16	4'h3
0x2A82	7:0	R/W	Extclk2xdiv	The factor of Extclk2x divide from clk96m 8'h00: clk8x / 1 8'h01: clk8x / 2 8'h02: clk8x / 3 . 8'hFF: clk8x / 256	8'h1
0x2A83	4:0	R/W	Clk1xodelay	The factor decide the vclko is delay from extclk1xi 5'h0: No delay 5'h1: 1 * Delay2 ns 5'h2: 2 * Delay2 ns . 5'h1F: 31 * Delay2 ns	0
	7	R/W	Clk1xopol	Decide the vclko is inviter from extclk1xi or not 1'b0: Not inverse 1'b1: Inverse	0
0x2AA0	0	R	Hsync	The Hsync value	NA
	1	R	Vsync	The Vsync value	NA
	2	R	Hvalid	The Hsync valid signal	NA
	3	R	Vvalid	The Vsync valid signal	NA
	4	R	Field	The Field of sensor	NA
0x2AA1	0	R	Mshutter	The mshutter signal	NA
	1	R	Vsubctr	The Vsubctr signal	NA
0x2AB0	0	R/W	Senrst	Write 1 to this bit will reset the sensor interface (also the ccdtg register)	1'b0

### 2.13 CCD Control Registers

Address	Bit	Att	Name	Description	Default value
0x2B00	0	R/W	Ccdtgen	CCD sensor timing generator enable 0: Disable 1: Enable	1'b0
	1	R/W	Progressen	Progressive mode enable 0: Disable 1: Enable	1'b0
	2	R/W	Afen	High frame rate read out mode enable 0: Disable 1: Enable	1'b0
0x2B02,01	10:0	R/W	Afnum1	The number of line will be shift when High frame rate enable (Shift fist line)	11'h0
0x2B04,03	10:0	R/W	Afnum2	The number of line will be shift when High frame rate enable (Shift last line)	11'h0
0x2B05	3:0	R/W	Snapnum	The Number of frame want to capture one time 4'h0: 16 Picture 4'h1: 1 Picture 4'h2: 2 Picture . . 4'hF: 15 Picture	4'h1
	4	R/W	Snaptrg	Snap trigger signal, it will auto clear after snap complete	1'b0
0x2B06	1:0	R/W	Dufenum	The Dummy monitor mode frame Before Capture 2'h0: No Dummy frame 2'h1: 1 monitor frame . . 2'h3: 3 monitor frame	2'h2
	5:4	R/W	Rlinenum	The read line num 2'h0: 4 line width 2'h1: 1 line width 2'h2: 2 line width 2'h3: 3 line width	2'h2
0x2B07	0	R/W	Mshvalue	Mechanical shutter value, when Mshmanuen = 1	1'b1
	4	R/W	Mshmanuen	Mechanical shutter manu enable 1'b0: Auto contronl 1'b1: Menu Control	1'b0
	5	R/W	Bshen	B shutter enable	1'b0
0x2B08	7:0	R/W	Mshearly	Mechanical shutter will close by early line then default value 8'h00: default position 8'h01: early 1 line . . 8'hFF: early 255 line	8'h0
0x2B09	0	R/W	Vsubctrvalue	Vsubctr value, when Vsubctrmenuen = 1	1'b0

	4	R/W	Vsubctrmenuen	Vsubctr menu enable 1'b0: Auto control 1'b1: Menu Control	1'b0
0x2B0B,0A	11:0	R/W	Esptime	Exposure time (The unit is line)	12'h64
0x2B10	0	R/W	Fh1pol	The Fh1 polarity will be inverted when this bit set	1'b0
	1	R/W	Fh2pol	The Fh2 polarity will be inverted when this bit set	1'b0
	2	R/W	Subpol	The Sub polarity will be inverted when this bit set	1'b0
	3	R/W	Clpobpol	The Clpob polarity will be inverted when this bit set	1'b0
	4	R/W	Clpdmpol	The Clpdm polarity will be inverted when this bit set	1'b0
	5	R/W	Pblkpol	The pblk polarity will be inverted when this bit set	1'b0
	6	R/W	CCDFldpol	The CCD field pol	1'b0
0x2B11	0	R/W	Xv1pol	The Xv1 polarity will be inverted when this bit set	1'b0
	1	R/W	Xv2pol	The Xv2 polarity will be inverted when this bit set	1'b0
	2	R/W	Xv3pol	The Xv3 polarity will be inverted when this bit set	1'b0
	3	R/W	Xv4pol	The Xv4 polarity will be inverted when this bit set	1'b0
	4	R/W	Xsg1apol	The Xsg1a polarity will be inverted when this bit set	1'b0
	5	R/W	Xsg1bpol	The Xsg1b polarity will be inverted when this bit set	1'b0
	6	R/W	Xsg3apol	The Xsg3a polarity will be inverted when this bit set	1'b0
	7	R/W	Xsg3bpol	The Xsg3b polarity will be inverted when this bit set	1'b0
0x2B12	0	R/W	Rgpol	The Rg polarity will be inverted when this bit set	1'b0
	1	R/W	Xshppol	The Xshp polarity will be inverted when this bit set	1'b0
	2	R/W	Xshdpol	The Xshd polarity will be inverted when this bit set	1'b0
	3	R/W	Mshutterpol	The mechanical shutter control signal polarity will be inverted when this bit set	1'b0
	4	R/W	Vsubctrpol	The Vsubctr control signal polarity will be inverted when this bit set	1'b0
0x2B13	4:0	R/W	RgDelay	The Rg signal delay parameter: 5'h00: No delay 5'h01: Delay 1ns . 5'h0F: Delay 31ns	5'h0
0x2B14	1:0	R/W	Rgpos	The Rg signal Low Position between clk	2'h3
0x2B15	4:0	R/W	Xshpdelay	The Xshp signal delay parameter: 5'h00: No delay 5'h01: Delay 1ns . 5'h1F: Delay 31s	5'h0
0x2B16	1:0	R/W	Xshppos	The Xshp signal Low Position between clk	2'h0
0x2B17	4:0	R/W	Xshddelay	The Xshd signal delay parameter: 5'h00: No delay 5'h01: Delay 1s . 5'h1F: Delay 31ns	5'h0
0x2B18	1:0	R/W	Xshdpos	The Xshd signal Low Position between clk	2'h2

0x2B19	3:0	R/W	Fh1delay	The Xfh1 signal delay parameter: 4'h0: No delay 4'h1: Delay 1ns . 4'hF: Delay 15ns	4'h0
0x2B1A	3:0	R/W	Fh2delay	The Xfh2 signal delay parameter: 4'h0: No delay 4'h1: Delay 1ns . 4'hF: Delay 15ns	4'h0

## 2.14 CPU Control Registers

Address	Bit	Attr	Name	Description	Default value
0X2C00	0	r/w	LSRAM4Ken	Low bank (0x0000–0x0FFF) SRAM4K access enable 0: disable 1: enable	1'b0
	1	r/w	HSRAM4Ken	High bank (0x1000–0x1FFF) SRAM4K access enable 0: disable 1: enable	1'b0
	2	r/w	Rampageen	0: Normal 8051 addressing method 1: Redirect unused RAM space to ROM space	1'b0
	3	r/w	Rompageen	0: 64K ROM space 1: 256 K ROM space	1'b0
	4	r/w	Shadowen	0: execute the program from the external ROM. 1: execute the program from the shadow memory if the address hit the shadow area. The shadow memory is the low 4K bytes of embedded 8K SRAM.	1'b0
0X2C01	7:0	r/w	Shadowmap[7:0]	This register determined which section of program space will be shadowed to the SRAM. It is based on 4K bytes block. For Example, if Shadowmap [7:0]=1, address 0X1000 to address 0X1FFF will be shadowed.	8'b0
0X2C02	7:0	r/w	P1oeSel[7:0]	Port 1 output enable mode selection 0: tri-state mode, the data is driven out when it is 0 and tri-state when it is 1. 1: Always enable the output.	8'b0
0X2C03	5:0	r/w	P3oeSel[5:0]	Port 3 output enable mode selection 0: tri-state mode, the data is driven out when it is 0 and tri-state when it is 1. 1: Always enable the output.	6'b0
0X2C04	7:0	r	Interrupt	{dmaint,tvencint,dramint,usbint,fint,auint,globalint,~int0_n} Int0_n : active low if any interrupt happens.	NA
0X2C05	0	r/w	Powerdown	This bit indicate the pin out signals status in suspend mode. 0: normal status 1: force P0 , P2, low byte address, ale, psen, romwr_n low in case of current leakage in power down mode.	1'b0
0X2C10	7:0	r/w	Hsram4Kdata	High bank 4K sram data port If Hsram4Kmode = 1, the CPU may access the high bank 4K sram via the	NA

Address	bit	Attr	Name	Description	Default value
0X2C11	1:0	r/w	Hsram4Kmode	High bank 4K sram mode 0: The 4K sram address is from 0x1000 to 0x1FFF. 1: CPU may access the 4K sram via 0x2C10 successively. 2: DMA mode	2'b0
	2	r/w	RstldxInfo	0: normal operation 1: restart high bank 4K sram address to Hsram4Kidx when Hsram4Kmode =1 or Hsram4Kmode = 2.	1'b1
0X2C12	7:0	r/w	Hsram4Kidx[7:0]	To indicate the initial address of high bank 4K sram.	7'b0
0X2C13	3:0	r/w	Hsram4Kidx[11:8]		4'b0
0X2CA0	7:0	r	Hsram4KwrlIdx[7:0]	The high bank 4K sram input index. Register 0x2CA0 ~ 0x2CA1 are the current input pointer.	7'b0
0X2CA1	3:0	r	Hsram4KwrlIdx[11:8]		4'b0
0X2CA2	7:0	r	Hsram4KrdldIdx[7:0]	The high bank 4K sram output index. Register 0x2CA2 ~ 0x2CA3 are the current output pointer.	7'b0
0X2CA3	3:0	r	Hsram4KrdldIdx[11:8]		4'b0

### 2.15 TV Output Interface Registers

Address	bit	Attr	Name	Description	Default value
0X2D00	7:0	r/w	tvdspmode	TV encoder output control. 4'h0: composite TV output (NTSC) 4'h1: composite TV output (PAL) 4'h2: CCIR656 NTSC output 4'h3: CCIR656 PAL output 4'h4: CCIR601 NTSC output (8-bit) 4'h5: CCIR601 PAL output (8-bit) 4'h6: CCIR601 NTSC output (16-bit) 4'h7: CCIR601 PAL output (16-bit) 4'h8: UPS051 output 4'h9: AU 1.5" color TFT-LCD interface (A015AN02) 4'ha: EPSON output 4'hb: CASIO output 4'hc: STN-LCD output 4'he: VGA TFT-LCD output 4'hf: user defined output(YCbCr) By the way, The register 0X2B02~0X2B07 must be redefined for that the output mode are not NTSC or PAL.	8'b0
	4	r/w	hflip	Horizontal flips. 0: normal operation. 1: horizontal flip effect. In this mode, you must redefine the image horizontal offset and UV exchange. In other words, if image horizontal offset is 0 and image size is 320x240 in normal mode, you must change image horizontal offset to 320 and the register 2B01 must be 2 in horizontal flip mode.	1'b0
	5	r/w	vflip	Vertical flips. 0: normal operation. 1: vertical flip effect. In this mode, you must redefine the image vertical offset. For example, if image vertical offset is 0 and image size is 320x240 in normal mode, you must change image vertical offset to 240.	1'b0
0X2D01	0	r/w	hpolar	Horizontal sync polarity	1'b0

				0: negative 1: positive	
	1	r/w	vpolar	Vertical sync polarity 0: negative 1: positive	1'b0
	2	r/w	invfield	Inverse field signal 0: no inverted 1: inverted	1'b0
	3	r/w	uvchg	image UV data exchange 0: no exchanged. 1: exchanged.	1'b0
	4	r/w	tvimgen	image request enable 0: disable 1: enable	1'b1
0X2D02	7:0	r/w	vline[7:0]	User defined vertical line count per frame.	10'h105
0X2D03	1:0	r/w	vline[9:8]	If the register 0X2B00 setting: 4'h8: vline=10'd261 4'ha: vline=10'd261 4'hc: vline = user defined 4'he: vline = user defined 4'hf: vline = user defined	
0X2D04	7:0	r/w	hpixel[7:0]	User defined horizontal pixel count per line.	10'h359
0X2D05	1:0	r/w	hpixel[9:8]	If the register 0X2B00 setting: 4'h8: hpixel =10'd857 4'ha: hpixel =10'd909 4'hc: hpixel = user defined 4'he: hpixel = user defined 4'hf: hpixel = user defined	
0X2D06	7:0	r/w	vsyncw[7:0]	User defined vertical sync width (line-base) If the register 0X2B00 setting: 4'h8: vsyncw = 8'd3 4'ha: vsyncw = 8'd17 4'hc: vsyncw = 8'd2 4'he: vsyncw = user defined 4'hf: vsyncw = user defined	8'h03
0X2D07	1:0	r/w	hsyncw[7:0]	User defined horizontal sync width.(pixel-base) If the register 0X2B00 setting: 4'h8: hsyncw = 8'h62 4'ha: hsyncw = 8'h20 4'hc: hsyncw = 8'h8 4'he: hsyncw = user defined 4'hf: hsyncw = user defined	8'h40
0X2D08	7:0	r/w	vldx0[7:0]	Horizontal start point (low byte).	8'h80
0X2D09	1:0	r/w	vldx0[9:8]	Horizontal start point (high byte).	2'b0
0X2D0A	7:0	r/w	vldy0[7:0]	Vertical start point (low byte).	8'h13
0X2D0B	1:0	r/w	vldy0[9:8]	Vertical start point (high byte).	2'b0
0X2D0C	7:0	r/w	vldx1[7:0]	Horizontal stop point (low byte).	8'h50
0X2D0D	1:0	r/w	vldx1[9:8]	Horizontal stop point (high byte).	2'b11
0X2D0E	7:0	r/w	vldy1[7:0]	Vertical stop point (low byte).	8'h02
0X2D0F	1:0	r/w	vldy1[9:8]	Vertical stop point (high byte). The register 0X2B08 ~ 0X2B0F may define the valid region for display.	2'b01
0X2D10	7:0	r/w	selwx0[7:0]	Select window horizontal start point.	8'h0
0X2D11	1:0	r/w	selwx0[9:8]	Select window horizontal start point.	2'b0



0X2D12	7:0	r/w	selwy0[7:0]	Select window vertical start point.	8'h0
0X2D13	1:0	r/w	selwy0[9:8]	Select window vertical start point.	2'b0
0X2D14	7:0	r/w	selwx1[7:0]	Select window horizontal stop point.	8'h0
0X2D15	1:0	r/w	selwx1[9:8]	Select window horizontal stop point.	2'b0
0X2D16	7:0	r/w	selwy1[7:0]	Select window vertical stop point.	8'h0
0X2D17	1:0	r/w	selwy1[9:8]	Select window vertical stop point.	2'b0
0X2D18	3:0	r/w	selwsiz[3:0]	Select window width. If selwsiz=4'hf, the selected region will perform in OSD special function effect.	4'b0
	6:4	r/w	selwclr[2:0]	Select window color. 0:R=color0r; G=color0g; B=color0b 1:R=color1r; G=color1g; B=color1b 2:R=color2r; G=color2g; B=color2b 3:R=color3r; G=color3g; B=color3b 4:R=color4r; G=color4g; B=color4b 5:R=color5r; G=color5g; B=color5b 6:R=color6r; G=color6g; B=color6b 7:R=color7r; G=color7g; B=color7b	3'b0
	7	r/w	selwen	Select window enable. 0: disable 1: enable	2'b0
0X2D19	7:0	r/w	imgvzfac[7:0]	Image vertical zoom factor. imgvzfac = (image lines)/(display lines)*32. For example, image size is 320x240 and display size is 280x220, the imgvzfac is (240/220)*32 = 34	8'h40
0X2D1A	7:0	r/w	imghzfac[7:0]	Image horizontal zoom factor. imghzfac = (image pixels)/(display dots)*128. For example, image size is 320x240 and display size is 280x220, the imghzfac is (320/280)*128 = 146.	8'h80
0X2D1B	7:0	r/w	imgvofst[7:0]	Image vertical offset.	8'h0
0X2D1C	3:0	r/w	imgvofst[11:8]	Image vertical offset.	4'h0
0X2D1D	7:0	r/w	imghofst[7:0]	Image horizontal offset.	8'h0
0X2D1E	3:0	r/w	imghofst[11:8]	Image horizontal offset.	4'h0
0X2D1F	5:0	r/w	imghpix[5:0]	Image horizontal pixel counts. imghpix = (image pixels/16). For example, image size is 320x240, imghpix = (320/16) = 20	6'h0
0X2D20	6:0	r/w	imgsubsamp[6:0]	Image sub-sample factor. (for future use)	7'h40
0X2D21	6:0	r/w	osdsubsamp[6:0]	OSD sub-sample factor. osdsubsamp = 7'h20 for TV and osdsubsamp = 7'h40 for LCD.	7'h40
0X2D22	7:0	r/w	saturate	Saturation adjustment (only for analog TV)	8'h1c
0X2D23	7:0	r/w	hueadjust	Hue adjustment (only for analog TV)	8'h0
0X2D25	2:0	r/w	xsclstate	EPSON XSCL state defines.	3'h0
	3	r/w	em1812en	EPSON LCD controller em1812b function enable.	1'h0
	4	r/w	wscrnen	CASIO white screen enable. 0: disable 1:enable	1'h0
	5	r/w	gresctrl	CASIO GRES signal controller. 0: output low. 1:normal operation	1'h0
	6	r/w	stbybctrl	CASIO stand-by controller. 0:normal operation 1: stand-by mode.	1'h0
	7	r/w	ritctrl	CASIO RIT signal controller. 0: Normal display mode.	1'h0

				1:Horizontally flipped display mode.	
0X2D26	1:0	r/w	oddrgb	TFT-LCD odd lines RGB cycle define. 0: RGB 1: RGB 2: GBR 3: BRG	2'h0
	3:2	r/w	evenrgb	TFT-LCD even lines RGB cycle define. 0: GBR 1: GBR 2: BRG 3: RGB	2'h0
0X2D27	3:0	r/w	lp_position	STN-LCD LP signal position defines.	8'h0
	7:4	r/w	eio1_position	STN-LCD EIO1 signal position defines.	8'h0
0X2D28	7:0	r/w	fr_ctrl	STN-LCD FR control signal.	8'h0
0X2D29	1:0	r/w	xck_sel	STN-LCD XCK select signal.	2'h0
	3:2	r/w	filter_type	STN-LCD filter type select signal 0: RGBRGB BRGBRG 1: RGRGRG GBGBGB BRBRBR 2: RGBRGB RGBRGR 3: RBRBRB GRGRGR BGBGBG	2'h0
0X2D2A	1:0	r/w	ccirtype	define CCIR output sequence 0: YCrYCb 1: CrYCbY 2: YCbYCr 3: CbYCrY	2'h0
0X2D2B	0	r/w	gammaen	Gamma enable. 0: disable. 1: enable.	1'h0
	1	r/w	dien	Dither enable. 0: disable 1:enable	1'h0
	2	r/w	osdlpfen	OSD low-pass filter enable 0: disable 1: enable	1'h0
0X2D2C	0	r/w	sramhbyte	SRAM high byte value (only for SRAM256x9).	1'h0
	1	r/w	sram256x9en	SRAM256x9 access enable.	1'h0
	2	r/w	sram256x6en	SRAM256x6 access enable.	1'h0
0X2D2D	7:0	r/w	sramaddr	SRAM address	8'h0
0X2D2E	7:0	r/w	sramdata	SRAM data. For example, write 9'h120 to SRAM256x9, the register 2B62=3 first and then write the register 2B64=20.	8'h0
0X2D2F	6:0	r/w	colorkey	Color key defines. If image's luminance smaller than color key defined value, encoder will show the OSD color.	8'h0
	7	r/w	colorkeyen	Color key enable. 0: disable 1: enable	8'h0

0X2D30	0	r/w	bgcrscn	background color screen enable. 0: show images. 1: show background colors.	1'b0
	1	r/w	glbosden	Global OSD enable. 0: disable 1:enable	1'b0
0X2D31	7:0	r/w	osdscrl	OSD scrolling index.	8'b0
0X2D32	7:0	r/w	osdvzfac	OSD vertical zoom factor.	8'b0
0X2D33	7:0	r/w	osdvofst	OSD vertical offset.	8'b0
0X2D34	7:0	r/w	osdhofst	OSD horizontal offset.	8'b0
0X2D35	1:0	r/w	osdblkspd	OSD blanking speed. 0: 1 second 1: 1/2 second 2: 1/4 second 3: 1/8 second	2'b0
	4:2	r/w	htonefac	OSD half-tone mix factor	3'b0
0X2D36	3:0	r/w	fonthbits	OSD pattern horizontal bits.	4'hf
0X2D37	4:0	r/w	color0r	OSD foreground color 0 (R)	5'h0
0X2D38	4:0	r/w	color0g	OSD foreground color 0 (G)	5'h0
0X2D39	4:0	r/w	color0b	OSD foreground color 0 (B)	5'h0
0X2D3A	4:0	r/w	color1r	OSD foreground color 1 (R)	5'h0
0X2D3B	4:0	r/w	color1g	OSD foreground color 1 (G)	5'h0
0X2D3C	4:0	r/w	color1b	OSD foreground color 1 (B)	5'h0
0X2D3D	4:0	r/w	color2r	OSD foreground color 2 (R)	5'h0
0X2D3E	4:0	r/w	color2g	OSD foreground color 2 (G)	5'h0
0X2D3F	4:0	r/w	color2b	OSD foreground color 2 (B)	5'h0
0X2D40	4:0	r/w	color3r	OSD foreground color 3 (R)	5'h0
0X2D41	4:0	r/w	color3g	OSD foreground color 3 (G)	5'h0
0X2D42	4:0	r/w	color3b	OSD foreground color 3 (B)	5'h0
0X2D43	4:0	r/w	color4r	OSD foreground color 4 (R)	5'h0
0X2D44	4:0	r/w	color4g	OSD foreground color 4 (G)	5'h0
0X2D45	4:0	r/w	color4b	OSD foreground color 4 (B)	5'h0
0X2D46	4:0	r/w	color5r	OSD foreground color 5 (R)	5'h0
0X2D47	4:0	r/w	color5g	OSD foreground color 5 (G)	5'h0
0X2D48	4:0	r/w	color5b	OSD foreground color 5 (B)	5'h0
0X2D49	4:0	r/w	color6r	OSD foreground color 6 (R)	5'h0
0X2D4A	4:0	r/w	color6g	OSD foreground color 6 (G)	5'h0
0X2D4B	4:0	r/w	color6b	OSD foreground color 6 (B)	5'h0
0X2D4C	4:0	r/w	color7r	OSD foreground color 7 (R)	5'h0
0X2D4D	4:0	r/w	color7g	OSD foreground color 7 (G)	5'h0
0X2D4E	4:0	r/w	color7b	OSD foreground color 7 (B)	5'h0
0X2D4F	4:0	r/w	colorbgr	OSD background color (R)	5'h0
0X2D50	4:0	r/w	colorbgg	OSD background color (G)	5'h0
0X2D51	4:0	r/w	colorbgb	OSD background color (B)	5'h0
0X2D52	4:0	r/w	fbfac	Fbfac [4] is blending color controller. 0: image, 1: black. And fbfac [3:0] is foreground and blending color mix level. The equation is (fbfac*(blending color)+(16-fbfac)*(foreground color))/16.	5'h0
0X2D60	7:0	r/w	luty0	Gamma look-up table.	8'h00
0X2D61	7:0	r/w	luty1	Gamma look-up table.	8'h10
0X2D62	7:0	r/w	luty2	Gamma look-up table.	8'h20
0X2D63	7:0	r/w	luty3	Gamma look-up table.	8'h30

0X2D64	7:0	r/w	luty4	Gamma look-up table.	8'h40
0X2D65	7:0	r/w	luty5	Gamma look-up table.	8'h50
0X2D66	7:0	r/w	luty6	Gamma look-up table.	8'h60
0X2D67	7:0	r/w	luty7	Gamma look-up table.	8'h70
0X2D68	7:0	r/w	luty8	Gamma look-up table.	8'h80
0X2D69	7:0	r/w	luty9	Gamma look-up table.	8'h90
0X2D6A	7:0	r/w	lutya	Gamma look-up table.	8'ha0
0X2D6B	7:0	r/w	lutyb	Gamma look-up table.	8'hb0
0X2D6C	7:0	r/w	lutyc	Gamma look-up table.	8'hc0
0X2D6D	7:0	r/w	lutyd	Gamma look-up table.	8'hd0
0X2D6E	7:0	r/w	lutye	Gamma look-up table.	8'he0
0X2D6F	7:0	r/w	lutyf	Gamma look-up table.	8'hf0
0X2D70	7:0	r/w	luty10	Gamma look-up table.	8'hff
0X2D71	7:0	r/w	tvegpioo[7:0]	TV encoder GPIO output data.	8'h0
0X2D72	7:0	r/w	tvegpioo[15:8]	TV encoder GPIO output data.	8'h0
0X2D73	5:0	r/w	tvegpioo[21:16]	TV encoder GPIO output data.	6'h0
0X2D74	7:0	r/w	tvegpiooe[7:0]	TV encoder GPIO output enable.	8'h0
0X2D75	7:0	r/w	tvegpiooe[15:8]	TV encoder GPIO output enable.	8'h0
0X2D76	5:0	r/w	tvegpiooe[21:16]	TV encoder GPIO output enable.	6'h0
0X2DA0	0	r	hvalid	TV encoder horizontal valid signal.	
	1	r	hsync	TV encoder horizontal sync signal.	
	2	r	vvalid	TV encoder vertical valid signal.	
	3	r	vsync	TV encoder vertical sync signal.	
	4	r	tvencframe	TV encoder frame signal.	
0X2DC0	0	w	vdrevt	TV encoder vsync interrupt signal. The interrupt is generated when the corresponding vsync goes from low to high. Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	
	1	w	vdfevt	TV encoder vsync interrupt signal. The interrupt is generated when the corresponding vsync goes from high to low. Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	
0X2DC1	7:0	r/w	digrevt[7:0]	TV encoder digtvi[7:0] interrupt signal. The interrupt is generated when the corresponding digtvi ports goes from low to high. Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	
0X2DC2	7:0	r/w	digrevt [15:8]	TV encoder digtvi[15:8] interrupt signal.	
0X2DC3	5:0	r/w	digrevt [21:16]	TV encoder digtvi[21:16] interrupt signal.	
0X2DC4	7:0	r/w	digfevt[7:0]	TV encoder digtvi[7:0] interrupt signal. The interrupt is generated when the corresponding digtvi ports goes from high to low. Write 0 to the register will clear the interrupt. Write 1 to the register has no impact on the interrupt values.	
0X2DC5	7:0	r/w	digfevt [15:8]	TV encoder digtvi[15:8] interrupt signal.	
0X2DC6	5:0	r/w	digfevt [21:16]	TV encoder digtvi[21:16] interrupt signal.	
0X2DC7	7:0	r/w	digtvi[7:0]	TV encoder digtvi[7:0] input values.	
0X2DC8	7:0	r/w	digtvi[15:8]	TV encoder digtvi[15:8] input values.	
0X2DC9	5:0	r/w	digtvi[21:16]	TV encoder digtvi[21:16] input values.	
0X2DD0	0	r/w	vdrinten	TV encoder vertical sync falling edge interrupt enable.	1'h0
	1	r/w	vdrinten	TV encoder vertical sync rising edge interrupt enable.	1'h0
0X2DD1	7:0	r/w	rinten[7:0]	TV encoder digtvi[7:0] rising edge interrupt enable.	8'h0
0X2DD2	7:0	r/w	rinten[15:8]	TV encoder digtvi[15:8] rising edge interrupt enable.	8'h0



0X2DD3	5:0	r/w	rinten[21:16]	TV encoder digtvi[21:16] rising edge interrupt enable.	6'h0
0X2DD4	7:0	r/w	finten[7:0]	TV encoder digtvi[7:0] falling edge interrupt enable.	8'h0
0X2DD5	7:0	r/w	finten[15:8]	TV encoder digtvi[15:8] falling edge interrupt enable.	8'h0
0X2DD6	5:0	r/w	finten[21:16]	TV encoder digtvi[21:16] falling edge interrupt enable.	6'h0
0X2DE2	7:0	r/w	tverctrl[7:0]	Bit[0]: frame rate conversion control. 0: field mode, 1: frame mode. Bit[1]: luminance filter controller. 0: enable. 1: disable Bit[2]: CASIO interface option.	8'h0

### 3. Application/Usage Descriptions (by FAE)

For SAC Only

## REVISION HISTORY

Date	Revision #	Description	Page
Nov. 01, 2001	0.1.0	First draft	
Jan. 02, 2002	0.1.2	Editorial Modification	
Mar. 11, 2002	0.1.3	The onextal pin number shall be B13(280) instead of V11(280) in the clock setting table	p. 7
Jun. 14, 2002	0.2.0	Add 3-field CCD control registers (0x2924 and 0x2926) Add video control register 0x2DE2 Add volume control register 0x2676 Add USB power configuration register 0x20E8 Add Q-Table access register 0x2882	p. 176 p. 189 p.165 p.141 p.173

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