



STw5093

2.7V SUPPLY 14-BIT LINEAR CODEC WITH HIGH-PERFORMANCE AUDIO FRONT-END

FEATURES:

Complete CODEC and FILTER system including:

- 14 BIT LINEAR ANALOG TO DIGITAL AND DIGITAL TO ANALOG CONVERTERS.
- 8 BIT COMPANDED ANALOG TO DIGITAL AND DIGITAL TO ANALOG CONVERTERS A-LAW OR μ -LAW.
- TRANSMIT AND RECEIVE BAND-PASS FILTERS
- ACTIVE ANTIALIAS NOISE FILTER.

Phone Features:

- ONE MICROPHONE BIASING OUTPUT
- REMOTE CONTROL (REMOCON) FUNCTION
- THREE SWITCHABLE MICROPHONE AMPLIFIER INPUTS. GAIN PROGRAMMABLE: 0 . . 42.5 dB AMPLIFIER, 1.5 dB STEPS (+ MUTE).
- EARPIECE AUDIO OUTPUT. ATTENUATION PROGRAMMABLE: 0 . . 30 dB, 2 dB STEPS.
- EXTERNAL AUDIO OUTPUT. ATTENUATION PROGRAMMABLE: 0 . . 30 dB, 2 dB STEPS.
- DRIVING CAPABILITY: 140mW OVER 8 Ω
- TRANSIENT SUPPRESSION SIGNAL DURING POWER ON AND DURING AMPLIFIER SWITCHING.
- INTERNAL PROGRAMMABLE SIDETONE CIRCUIT. ATTENUATION PROGRAMMABLE: 16 dB RANGE, 1 dB STEP.
- INTERNAL RING, TONE AND DTMF GENERATOR, SINEWAVE OR SQUAREWAVE WAVEFORMS. ATTENUATION PROGRAMMABLE: 27dB RANGE, 3dB STEP. THREE FREQUENCY RANGES:
 - a) 3.9Hz 996Hz, 3.9Hz STEP
 - b) 7.8Hz 1992Hz, 7.8Hz STEP
 - c) 15.6Hz 3984Hz, 15.6Hz STEP
- PROGRAMMABLE PULSE WIDTH MODULATED BUZZER DRIVER OUTPUT.

General Features:

- SINGLE 2.7V to 3.3V SUPPLY
- EXTENDED TEMPERATURE RANGE OPERATION (*) -40°C to 85°C.
- 1.0 μ W STANDBY POWER (TYP. AT 2.7V).
- 13mW OPERATING POWER (TYP. AT 2.7V).



- 1.8V TO 3.3V CMOS COMPATIBLE DIGITAL INTERFACES.
- PROGRAMMABLE PCM AND CONTROL INTERFACE MICROWIRE COMPATIBLE.

APPLICATIONS:

- GSM/DCS1800/PCS1900/JDC DIGITAL CELLULAR TELEPHONES.
- CDMA CELLULAR TELEPHONES.
- DECT/CT2/PHS DIGITAL CORDLESS TELEPHONES.
- BATTERY OPERATED AUDIO FRONT-ENDS FOR DSPs.

(*) Functionality guaranteed in the range - 40°C to +85°C; Timing and Electrical Specifications are guaranteed in the range - 30°C to +85°C.

GENERAL DESCRIPTION

STw5093 is a high performance low power combined PCM CODEC/FILTER device tailored to implement the audio front-end functions required by low voltage/low power consumption digital cellular terminals. STw5093 offers a number of programmable functions accessed through a serial control channel that easily interfaces to any classical microcontroller. The PCM interface supports both non-delayed (normal and reverse) and delayed frame synchronization modes.

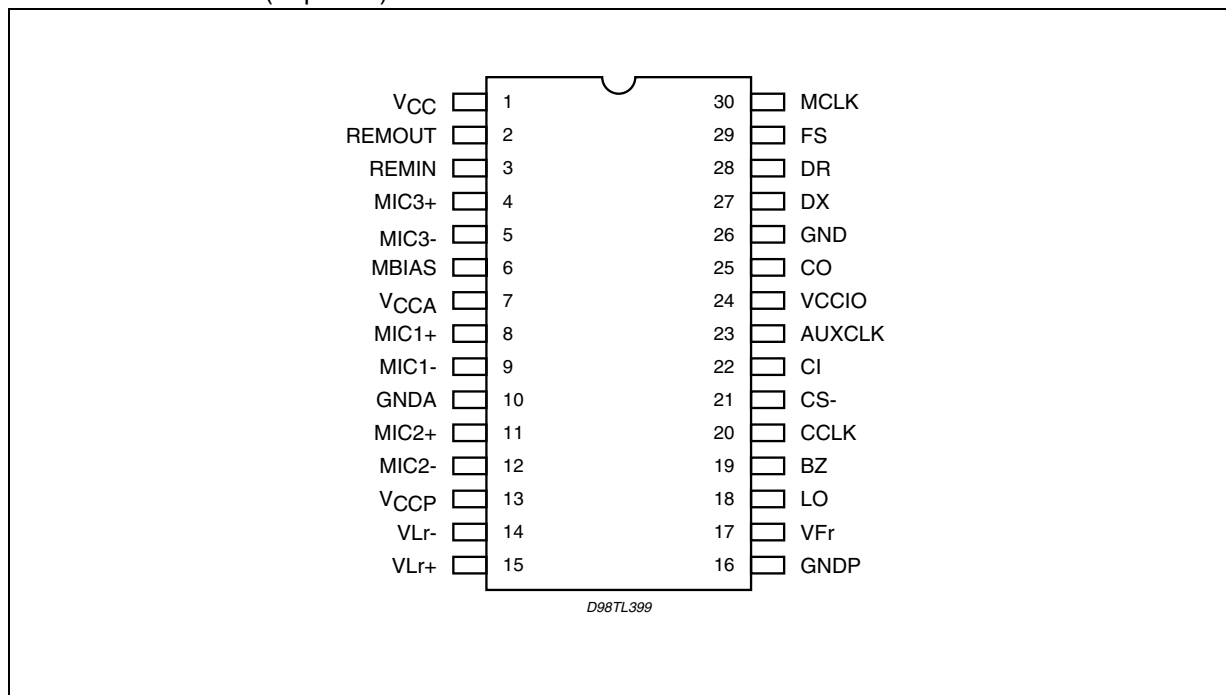
STw5093 can be configured either as a 14-bit linear or as an 8-bit companded PCM coder.

Additionally to the CODEC/FILTER function, STw5093 includes a Tone/Ring/DTMF generator, a sidetone generation, and a buzzer driver output. STw5093 fulfills and exceeds D3/D4 and CCITT recommendations and ETSI requirements for digital handset terminals.

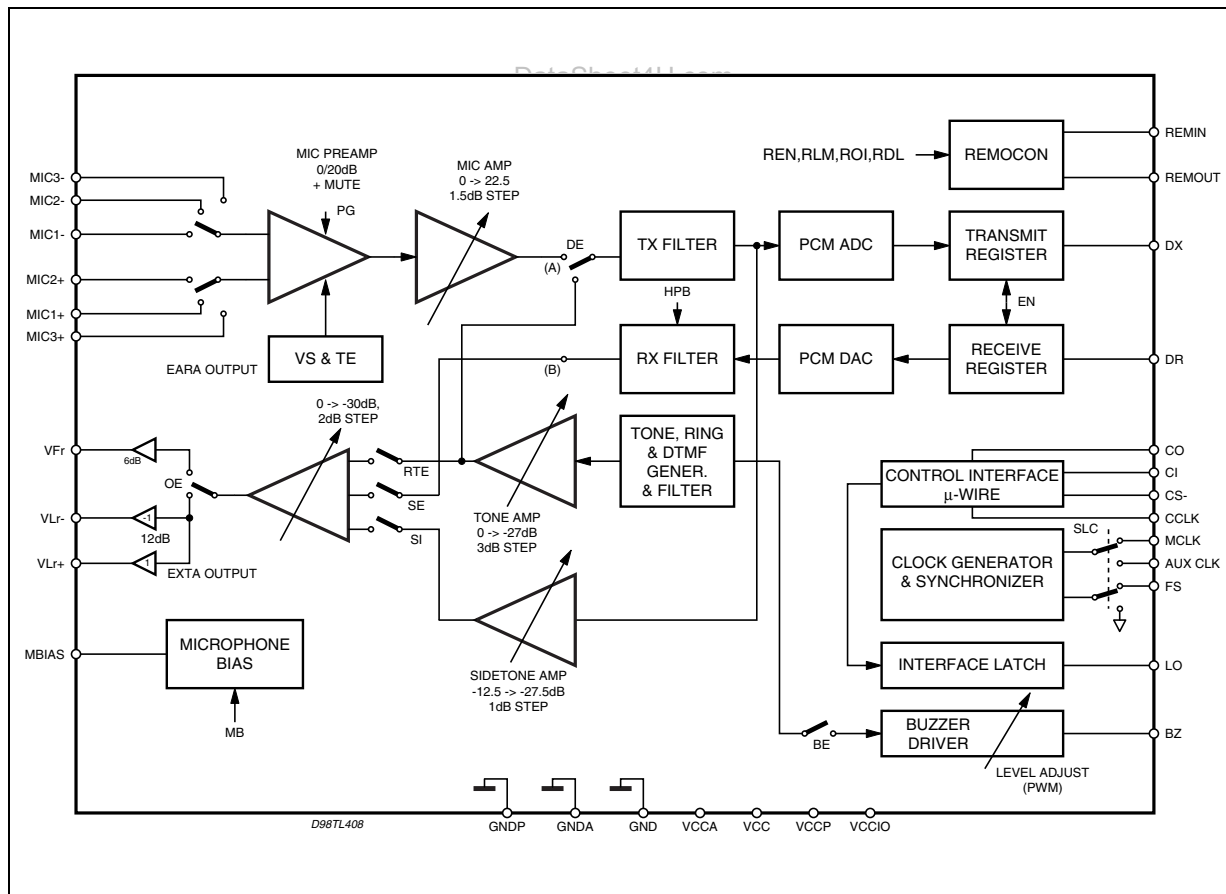
Main applications include digital mobile phones, as cellular and cordless phones, or any battery powered equipment that requires audio codecs operating at low single supply voltages.

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PIN CONNECTIONS (Top view)



BLOCK DIAGRAM



PIN FUNCTION

| N° | Pin | Description |
|-------|--|---|
| 1 | V _{CC} | Power supply input for the digital section. |
| 2 | REMOOUT | Remocon function digital output. |
| 3 | REMIN | Remocon function input. An high level at this pin is detected as a non pressed key, while a low level is detected as a pressed key. |
| 4 | MIC3+ | Third positive high impedance input to transmit preamplifier for microphone connection. |
| 5 | MIC3- | Third negative high impedance input to transmit preamplifier for microphone connection. |
| 6 | MBIAS | Microphone Biasing Switch. |
| 7 | V _{CCA} | Power supply input for the analog section. V _{CC} and V _{CCA} can be directly connected together for low cost applications (see STw5093 Power Supply Notes). |
| 8 | MIC1+ | Positive high impedance input to transmit pre-amplifier for microphone connection. |
| 9 | MIC1- | Negative high impedance input to transmit pre-amplifier for microphone connection. |
| 10 | GNDA | Analog Ground: All analog signals are referenced to this pin. GND and GNDA can be connected together for low cost applications (see STw5093 Power Supply Notes). |
| 11 | MIC2+ | Second Positive high impedance input to transmit pre-amplifier for microphone connection. |
| 12 | MIC2- | Second negative high impedance input to transmit pre-amplifier for microphone connection. |
| 13 | V _{CCP} | Power supply input for the V _{Fr} and V _{Lr} drivers. V _{CCP} and V _{CCA} must be connected together. |
| 14,15 | V _{Lr-} , V _{Lr+} | Receive analog extra amplifier complementary outputs. These outputs can drive directly earpiece transductor of 8Ω or 50nF. The signal at these outputs can be the sum of: - Receive Speech signal from DR, - Internal Tone generator, - Sidetone signal. |
| 16 | GNDP | Power ground. V _{Fr} and V _{Lr} drivers are referenced to this pin. GNDP and GNDA must be connected together. |
| 17 | V _{Fr} | Receive analog earpiece amplifier output. This output can drive directly earpiece transductor of 30Ω or 50nF. The signal at this output can be the sum of: - Receive Speech signal from DR, - Internal Tone Generator, - Sidetone signal. |
| 18 | LO | A logic 1 written into DO (CR1) appears at LO pin as a logic 0 A logic 0 written into DO (CR1) appears at LO pin as a logic 1. |
| 19 | BZ | Pulse width modulated buzzer driver output. |
| 20 | CCLK | Control Clock input: This clock shifts serial control information into CI and out from CO when the CS- input is low, depending on the current instruction. CCLK may be asynchronous with the other system clocks. |
| 21 | CS- | Chip Select input: When this pin is low, control information is written into and out from the STw5093 via CI and CO pins. |
| 22 | CI | Control data Input: Serial Control information is shifted into the STw5093 on this pin when CS- is low on the rising edges of CCLK. |
| 23 | AUXCLK | Auxiliary Clock Input. Values must be 512 kHz, 1.536 MHz, 2.048 MHz or 2.56 MHz selected by means of Control Register CR0. AUXCLK is not used to shift in and out data |

STw5093**PIN FUNCTION** (continued)

| N° | Pin | Description |
|----|-------|---|
| 24 | VCCIO | Power supply Input for the Digital I/O's. |
| 25 | CO | Control data Output: Serial control/status information is shifted out from the STw5093 on this pin when CS- is low on the falling edges of CCLK. |
| 26 | GND | Ground: All digital signals are referenced to this pin. |
| 27 | DX | Transmit Data output: Data is shifted out on this pin during the assigned transmit time slots. Elsewhere DX output is in the high impedance state. In delayed and non-delayed normal frame synchr. modes, voice data byte is shifted out from TRISTATE output DX at the MCLK on the rising edge of MCLK, while in non-delayed reverse frame synchr mode voice data byte is shifted out on the falling edge of MCLK. |
| 28 | DR | Receive data input: Data is shifted in during the assigned Received time slots In delayed and non-delayed normal frame synchr. modes voice data byte is shifted in at the MCLK frequency on the falling edges of MCLK, while in non-delayed reverse frame synchr. mode voice data byte is shifted in at the MCLK frequency on the rising edges of MCLK. |
| 29 | FS | Frame Sync input: This signal is a 8kHz clock which defines the start of the transmit and receive frames. Any of three formats may be used for this signal: non delayed normal mode, delayed mode, and non delayed reverse mode. |
| 30 | MCLK | Master Clock Input: This signal is used by the switched capacitor filters and the encoder/decoder sequencing logic. Values must be 512 kHz, 1.536 MHz, 2.048 MHz or 2.56 MHz selected by means of Control Register CR0. MCLK is used also to shift-in and out data. |

1.0 FUNCTIONAL DESCRIPTION

1.1 DEVICE OPERATION

1.1.1 Power on initialization:

When power is first applied, power on reset circuitry initializes STw5093 and puts it into the power down state. Gain Control Registers for the various programmable gain amplifiers and programmable switches are initialized as indicated in the Control Register description section. All CODEC functions are disabled.

The desired selection for all programmable functions may be initialized prior to a power up command using the MICROWIRE control channel.

Note: after register programming, a subsequent activation of the internal Power on Reset can be detected by programming to 1 the DO bit in the CR1 register; this sets to the logic level 0 the LO output. If an internal Power on Reset occurs, LO automatically switches to logic level 1.

1.1.2 Power up/down control:

Following power-on initialization, power up and power down control may be accomplished by writing any of the control instructions listed in Table 1 into STw5093 with "P" bit set to 0 for power up or 1 for power down.

Normally, it is recommended that all programmable functions be initially programmed while the device is powered down. Power state control can then be included with the last programming instruction or in a separate single byte instruction.

Any of the programmable registers may also be modified while STw5093 is powered up or down by setting "P" bit as indicated. When power up or down control is entered as a single byte instruction, bit 1 must be set to a 0.

When a power up command is given, all de-activated circuits are activated, but output DX will remain in the high impedance state until the second Fs pulse after power up.

1.1.3 Power down state:

Following a period of activity, power down state may be reentered by writing a power down instruction.

Control Registers remain in their current state and can be changed by MICROWIRE control interface.

In addition to the power down instruction, detection of loss MCLK (no transition detected) automatically enters the device in "reset" power down state with DX output in the high impedance state.

1.1.4 Transmit section:

Transmit analog interface is designed in two stages to enable gains up to 42.5 dB to be realized. Stage 1 is a low noise differential amplifier providing a selectable 0 or 20 dB gain via bit 1 (PG) of register CR4. A microphone may be capacitively connected to MIC1+, MIC1- inputs, while the MIC2+ MIC2A and MIC3+ MIC3- inputs may be used to capacitively connect a second microphone or a third microphone respectively or an auxiliary audio circuit. MIC1 or MIC2 or MIC3 or transmit mute is selected with bits 6 and 7 of register CR4.

In the mute case, the analog transmit signal is grounded and the sidetone path is also disabled. Following the first stage is a programmable gain amplifier which provides from 0 to 22.5 dB of additional gain in 1.5dB step. The total transmit gain should be adjusted so that, at reference point A, see Block Diagram description, the internal 0 dBm0 voltage is 0.49 Vrms (overload level is 0.7 Vrms). Second stage amplifier gain can be programmed with bits 4 to 7 of CR5.

An active RC prefilter then precedes the 8th order band pass switched capacitor filter. A/D converter can be either a 14-bit linear (bit CM = 0 in register CR0) or can have a compressing characteristics (bit CM = 1 in register CR0) according to CCITT A or MU255 coding laws. A precision on chip voltage reference ensures accurate and highly stable transmission levels.

Any offset voltage arising in the gain-set amplifier, the filters or the comparator is cancelled by an internal autozero circuit.

Each encode cycle begins immediately at the beginning of the selected Transmit time slot. The total signal delay referenced to the start of the time slot is approximately 195 μ s (due to the transmit filter) plus 125 μ s (due to encoding delay), which totals 320 μ s. Voice data is shifted out on DX during the selected time slot on the trans-

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mit rising edges of MCLK in delayed or non-delayed normal mode or on the falling edges of MCLK in non-delayed reverse mode. A separate MBIAS output can be used to bias a microphone (bit MB = 1 in register CR10)

1.1.5 Receive section:

Voice Data is shifted into the decoder's Receive voice data Register via the DR pin during the selected time slot on the falling edges of MCLK in delayed or non-delayed normal mode or on the rising edges of MCLK in non-delayed reverse mode.

The decoder consists of either a 14-bit linear or an expanding DAC with A or MU255 law decoding characteristic. Following the Decoder is a 3400 Hz 8th order band-pass switched capacitor filter with integral Sin X/X correction for the 8 kHz sample and hold.

0 dBmO voltage at this (B) reference point (see Block Diagram description) is 0.49 Vrms. A transient suppressing circuitry ensure interference noise suppression at power up.

The analog speech signal output can be routed either to earpiece (VFR output) or to an extra analog output (V_{Lr+} , V_{Lr-} outputs) by setting bits OE1, OE2, and SE (4, 3, and 0 of CR4).

Total signal delay is approximately 190 μ s (filter plus decoding delay) plus 62.5 μ s (1/2 frame) which gives approximately 252 μ s.

Output VFR is intended to directly drive an earpiece. Preceding the outputs is a programmable attenuation amplifier, which must be set by writing to bits 4 to 7 in register CR6. Attenuations in the range 0 to -30 dB relative to the maximum level in 2 dB step can be programmed. The input of this programmable amplifier is the sum of several signals which can be selected by writing to register CR4.:

- Receive speech signal which has been decoded and filtered,
- Internally generated tone signal, (Tone amplitude is programmed with bits 4 to 7 of register CR7),
- Sidetone signal, the amplitude of which is programmed with bits 0 to 3 of register CR5

V_{Fr} is capable of driving output power levels up to 16.5mW into a 30 Ω load impedance capacitively connected between V_{Fr+} and GND. Piezoceramic receivers up to 50nF can also be driven.

Differential outputs V_{Lr+} , V_{Lr-} are intended to directly drive an extra output. Preceding the outputs is a programmable attenuation amplifier, which must be set by writing to bits 0 to 3 in register CR6. Attenuations in the range 0 to -30 dB relative to the maximum level in 2.0 dB step can be programmed. The input of this programmable amplifier can be the sum of signals which can be selected by writing to register CR4:

- Receive speech signal which has been decoded and filtered,
- Internally generated tone signal, (Tone amplitude is programmed with bits 4 to 7 of register CR7),
- Sidetone signal, the amplitude of which is programmed with bits 0 to 3 of register CR5.

V_{Lr+} and V_{Lr-} outputs are capable of driving output power level up to 140mW into differentially connected load impedance of 8 Ω . Piezoceramic receivers up to 50nF can also be driven.

BUZZER OUTPUT:

Single ended output BZ is intended to drive a buzzer, via an external BJT, with a squarewave pulse width modulated (PWM) signal the frequency of which is stored into register CR8.

For some applications it is also possible to amplitude modulate this PWM signal with a squarewave signal having a frequency stored in register CR9.

Maximum load for BZ is 5k Ω and 50pF.

1.1.6 Digital Interface (Fig. 1)

F_S Frame Sync input determines the beginning of frame. It may have any duration from a single cycle of MCLK to a squarewave. Three different relationships may be established between the Frame Sync input and the first time slot of frame by setting bits DM1 and DM0 in register CR1. In non delayed data mode (long frame timing) the first time slot begins nominally coincident with the rising edge of F_S . Alternative is to use delayed data mode (short frame sync timing) in which FS input must be high at least a half cycle of MCLK earlier the frame beginning. In the case of linear code (bit CM = 0 in register CR0) the MSB is the first bit that is transmitted and received.

In the case of companded code only (bit CM = 1 in register CR0) a time slot assignment circuit on chip may be used with all timing modes, allowing connection to one of the two B1 and B2 voice data channels.

Two data formats are available: in Format 1, time slot B1 corresponds to the 8 MCLK cycles following immediately the rising edge of FS, while time slot B2 corresponds to the 8 MCLK cycles following immediately time slot B1.

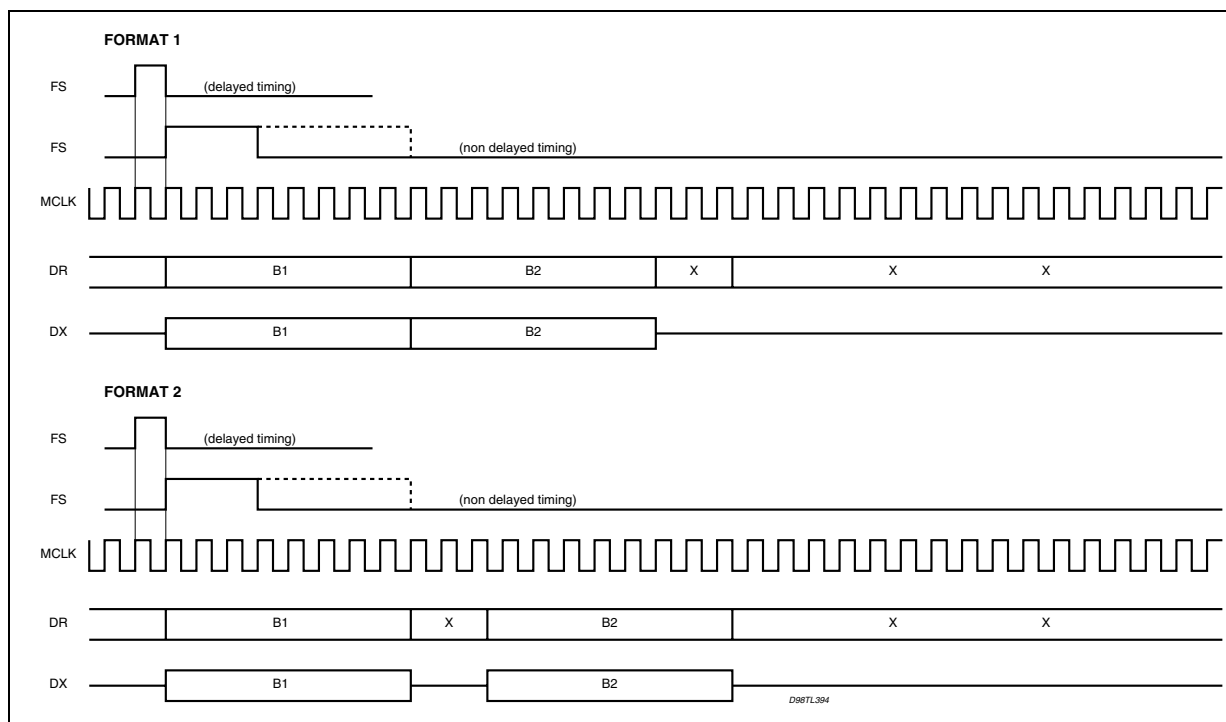
In Format 2, time slot B1 is identical to Format 1. Time slot B2 appears two bit slots after time slot B1. This two bits space is left available for insertion of the D channel data.

Data format is selected by bit FF (2) in register CR0. Time slot B1 or B2 is selected by bit TS (1) in Control Register CR1.

Bit EN (2) in control register CR1 enables or disables the voice data transfer on D_X and D_R as appropriate. During the assigned time slot, D_X output shifts data out from the voice data register on the rising edges of MCLK in the case of delayed and non-delayed normal modes or on the falling edges of MCLK in the case of non-delayed reverse mode. Serial voice data is shifted into D_R input during the same time slot on the falling edges of MCLK in the case of delayed and non-delayed normal modes or on the rising edges of MCLK in the case of non-delayed reverse mode.

D_X is in the high impedance Tristate condition when in the non selected time slots.

Figure 1. Digital Interface Format (significant only for companded code)



1.1.7 Control Interface:

Control information or data is written into or read-back from STw5093 via the serial control port consisting of control clock CCLK, serial data input CI and output CO, and Chip Select input, CS-. All control instructions require 2 bytes as listed in Table 1, with the exception of a single byte power-up/down command.

To shift control data into STw5093, CCLK must be pulsed high 8 times while CS- is low. Data on CI input is shifted into the serial input register on the rising edge of each CCLK pulse. After all data is shifted in, the content of the input shift register is decoded, and may indicate that a 2nd byte of control data will follow. This second byte may either be defined by a second byte-wide CS- pulse or may follow the first contiguously, i.e. it is not mandatory for CS- to return high in between the first and second control bytes. At the end of the 2nd control byte, data is loaded into the appropriate programmable register. CS- must return high at the end of the 2nd byte.

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To read-back status information from STw5093, the first byte of the appropriate instruction is strobed in during the first CS- pulse, as defined in Table 1. CS- must be set low for a further 8 CCLK cycles, during which data is shifted out of the CO pin on the falling edges of CCLK.

When CS- is high, CO pin is in the high impedance Tri-state, enabling CO pins of several devices to be multiplexed together.

Thus, to summarise, 2 byte READ and WRITE instructions may use either two 8-bit wide CS- pulses or a single 16 bit wide CS- pulse.

1.1.8 Control channel access to PCM interface:

It is possible to access the B channel previously selected in Register CR1 in the case of companded code only.

A byte written into Control Register CR3 will be automatically transmitted from DX output in the following frame in place of the transmit PCM data.

A byte written into Control Register CR2 will be automatically sent through the receive path to the Receive amplifiers.

In order to implement a continuous data flow from the Control MICROWIRE interface to a B channel, it is necessary to send the control byte on each PCM frame.

A current byte received on DR input can be read in the register CR2. In order to implement a continuous data flow from a B channel to MICROWIRE interface, it is necessary to read register CR2 at each PCM frame.

1.1.9 AUXCLK usage:

The Auxiliary clock AUXCLK is only used to keep active the tone and buzzer generation functions to the Ear-piece or to the Extra amplifier outputs when the Master Clock MCLK is not available, and there is no voice activity both in transmit and receive channels. When AUXCLK is selected, the PCM digital interface is inactive (DX in tristate and DR is not read). The selection between AUXCLK and MCLK is done by bit SLC in register CR1. The input frequency of AUXCLK is selected via bits F1 and F0 of register CR0 as for the MCLK signal.

1.1.10 REMOCON function:

The REMOCON (Remote Control) function can be used to detect the status of an headset button.

The REMOCON function is enabled by setting bit REN (7 of CR10). If enabled, this function is active also when the STw5093 is in Power-down state.

At REMIN input a high level is detected as a non pressed button, while a low level is detected as a pressed button.

The "Pressed Button" information can be treated in 2 ways depending on bit RLM (6 of CR10):

if RLM = 0 (Transparent mode) the information at REMIN is seen at REMOUT after a debounce time of 50ms maximum.

if RLM = 1 (Latched Mode) the information stored in bit RDL (4 of CR10) is seen at REMOUT. When a low level at REMIN is detected RDL is set after a debounce time of 50ms maximum. RDL is reset at power on reset and can also be reset writing CR10.

The REMOUT output polarity can be inverted setting bit ROI (5 of CR10): the pressed button information is presented at REMOUT output as a logic 1 if bit ROI = 0. If ROI = 1 the polarity is inverted.

2.0 PROGRAMMABLE FUNCTIONS

The programmable functions are configured by writing to a number of registers using a 2-byte write cycle. Most of these registers can also be read-back for verification. Byte one is always register address, while byte two is Data. Table 1 lists the register set and their respective addresses.

Table 1. Programmable Register Instructions

| Function | Address byte | | | | | | | | Data byte |
|----------------------------|--------------|---|---|---|---|---|---|---|-------------------|
| | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| Single byte Power up/down | P | X | X | X | X | X | 0 | X | none |
| Write CR0 | P | 0 | 0 | 0 | 0 | 0 | 1 | X | see CR0 TABLE 2 |
| Read-back CR0 | P | 0 | 0 | 0 | 0 | 1 | 1 | X | see CR0 |
| Write CR1 | P | 0 | 0 | 0 | 1 | 0 | 1 | X | see CR1 TABLE 3 |
| Read-back CR1 | P | 0 | 0 | 0 | 1 | 1 | 1 | X | see CR1 |
| Write Data to receive path | P | 0 | 0 | 1 | 0 | 0 | 1 | X | see CR2 TABLE 4 |
| Read data from DR | P | 0 | 0 | 1 | 0 | 1 | 1 | X | see CR2 |
| Write Data to DX | P | 0 | 0 | 1 | 1 | 0 | 1 | X | see CR3 TABLE 5 |
| Write CR4 | P | 0 | 1 | 0 | 0 | 0 | 1 | X | see CR4 TABLE 6 |
| Read-back CR4 | P | 0 | 1 | 0 | 0 | 1 | 1 | X | see CR4 |
| Write CR5 | P | 0 | 1 | 0 | 1 | 0 | 1 | X | see CR5 TABLE 7 |
| Read-back CR5 | P | 0 | 1 | 0 | 1 | 1 | 1 | X | see CR5 |
| Write CR6 | P | 0 | 1 | 1 | 0 | 0 | 1 | X | see CR6 TABLE 8 |
| Read-back CR6 | P | 0 | 1 | 1 | 0 | 1 | 1 | X | see CR6 |
| Write CR7 | P | 0 | 1 | 1 | 1 | 0 | 1 | X | see CR7 TABLE 9 |
| Read-back CR7 | P | 0 | 1 | 1 | 1 | 1 | 1 | X | see CR7 |
| Write CR8 | P | 1 | 0 | 0 | 0 | 0 | 1 | X | see CR8 TABLE 10 |
| Read-back CR8 | P | 1 | 0 | 0 | 0 | 1 | 1 | X | see CR8 |
| Write CR9 | P | 1 | 0 | 0 | 1 | 0 | 1 | X | see CR9 TABLE 11 |
| Read-back CR9 | P | 1 | 0 | 0 | 1 | 1 | 1 | X | see CR9 |
| Write CR10 | P | 1 | 0 | 1 | 0 | 0 | 1 | X | see CR10 TABLE 12 |
| Read-back CR10 | P | 1 | 0 | 1 | 0 | 1 | 1 | X | see CR10 |
| Write CR11 | P | 1 | 0 | 1 | 1 | 0 | 1 | X | see CR11 TABLE 13 |
| Read-back CR11 | P | 1 | 0 | 1 | 1 | 1 | 1 | X | see CR11 |
| Write Test Register CR12 | P | 1 | 1 | 0 | 0 | 0 | 1 | X | reserved |
| Write Test Register CR13 | P | 1 | 1 | 0 | 1 | 0 | 1 | X | reserved |
| Write Test Register CR14 | P | 1 | 1 | 1 | 0 | 0 | 1 | X | reserved |

Notes: 1. bit 7 of the address byte and data byte is always the first bit clocked into or out from: CI and CO pins when MICROWIRE serial port is enabled.

X = reserved: write 0

2. "P" bit is Power up/down Control bit. P = 1 Means Power Down. Bit 1 indicates, if set, the presence of a second byte.

3. Bit 2 is write/read select bit.

4. Registers CR12, CR13, and CR14 are not accessible.

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Table 2. Control Register CR0 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|----|----|----|----|----|----|----|----|--|
| F1 | F0 | CM | MA | IA | FF | B7 | DL | |
| 0 | 0 | | | | | | | MCLK or AUXCLK = 512 kHz * |
| 0 | 1 | | | | | | | MCLK or AUXCLK = 1.536 MHz |
| 1 | 0 | | | | | | | MCLK or AUXCLK = 2.048 MHz |
| 1 | 1 | | | | | | | MCLK or AUXCLK = 2.560 MHz |
| | | 0 | | | | | | Linear code * |
| | | 1 | | | | | | Companded code |
| | | | | | | | | Linear Code |
| | | | | | | | | Companded Code |
| | | | 0 | 0 | | | | 2-complement * sign and magnitude |
| | | | 0 | 1 | | | | 2-complement |
| | | | 1 | 0 | | | | 1-complement |
| | | | 1 | 1 | | | | MU-law: CCITT D3-D4 * MU-law: Bare Coding A-law including even bit inversion A-law: Bare Coding |
| | | | | | 0 | | | B1 and B2 consecutive * (1) |
| | | | | | 1 | | | B1 and B2 separated (1) |
| | | | | | | 0 | | 8 bits time-slot * (1) |
| | | | | | | 1 | | 7 bits time-slot (1) |
| | | | | | | | 0 | Normal operation * |
| | | | | | | | 1 | Digital Loop-back * |

*: state at power on initialization

(1): significant in companded mode only

Table 3. Control Register CR1 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|-----|-----|----|----|----|----|----|-----|---|
| DM1 | DM0 | DO | MR | MX | EN | TS | SLC | |
| 0 | X | | | | | | | delayed data timing * |
| 1 | 0 | | | | | | | non-delayed normal data timing |
| 1 | 1 | | | | | | | non-delayed reverse data timing |
| | | 0 | | | | | | L0 latch set to 1 * |
| | | 1 | | | | | | L0 latch set to 0 |
| | | | 0 | | | | | D _R connected to rec. path * |
| | | | 1 | | | | | CR2 connected to rec. path (1) |
| | | | | 0 | | | | Trans path connected to D _X * |
| | | | | 1 | | | | CR3 connected to D _X (1) |
| | | | | | 0 | | | voice data transfer disable * |
| | | | | | 1 | | | voice data transfer enable |
| | | | | | | 0 | | B1 channel selected * |
| | | | | | | 1 | | B2 channel selected (1) |
| | | | | | | | 0 | MCLK Master Clock and FS Frame Sync inputs are selected * |
| | | | | | | | 1 | AUXCLK Auxiliary Clock input is selected |

*: state at power on initialization

(1): significant in companded mode only

X: reserved: write 0

Table 4. Control Register CR2 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|-----|----|----|----|----|----|----|-----|--|
| d7 | d6 | d5 | d4 | d3 | d2 | d1 | d0 | |
| msb | | | | | | | lsb | Data sent to Receive path or Data received from DR input (1) |

(1) Significant in companded mode only.

Table 5. Control Registers CR3 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|-----|----|----|----|----|----|----|-----|-------------------------|
| d7 | d6 | d5 | d4 | d3 | d2 | d1 | d0 | |
| msb | | | | | | | lsb | DX data transmitted (1) |

(1) Significant in companded mode only.

Table 6. Control Register CR4 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|------------------|------------------|--------|------------------|------------------|--------|--------|--------|---|
| VS | TE | SI | OE1 | OE2 | RTE | HPB | SE | |
| 0 0 1 1 | 0 1 0 1 | | | | | | | Transmit input muted * MIC1 Selected MIC2 Selected MIC3 Selected |
| | | 0 1 | | | | | | Internal sidetone disabled * Internal sidetone enabled |
| | | | 0 0 1 1 | 0 1 0 1 | | | | Receive output muted * VFr output selected VLr output selected NOT ALLOWED |
| | | | | | 0 1 | | | Ring / Tone to VFr or VLr disabled * Ring / Tone to VFr or VLr enabled |
| | | | | | | 0 1 | | Receive High Pass filter enabled * Receive High Pass filter disabled |
| | | | | | | | 0 1 | Receive Signal to VFr or VLr disabled * Receive Signal to VFr or VLr enabled |

*: state at power on initialization

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Table 7. Control Register CR5 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function | | |
|--------------------|---|---|---|--------------------|---|---|-----|----------------|---|--|
| Transmit amplifier | | | | Sidetone amplifier | | | | | | |
| 0 | 0 | 0 | 0 | | | | lsb | 0 dB gain | * | |
| 0 | 0 | 0 | 1 | | | | | 1.5 dB gain | | |
| - | - | - | - | | | | | in 1.5 dB step | | |
| 1 | 1 | 1 | 1 | | | | | 22.5 dB gain | | |
| | | | | 0 | 0 | 0 | 0 | -12.5 dB gain | * | |
| | | | | 0 | 0 | 0 | 1 | -13.5 dB gain | | |
| | | | | - | - | - | - | in 1 dB step | | |
| | | | | 1 | 1 | 1 | 1 | -27.5 dB gain | | |

*: state at power on initialization

Table 8. Control Register CR6 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function | | |
|---------------------------|---|---|---|------------------------|---|---|-----|--------------|---|--|
| Earpiece amplifier [EARA] | | | | Extra amplifier [EXTA] | | | | | | |
| 0 | 0 | 0 | 0 | | | | lsb | 0 dB gain | * | |
| 0 | 0 | 0 | 1 | | | | | -2 dB gain | | |
| - | - | - | - | | | | | in 2 dB step | | |
| 1 | 1 | 1 | 1 | | | | | -30 dB gain | | |
| | | | | 0 | 0 | 0 | 0 | 0 dB gain | * | |
| | | | | 0 | 0 | 0 | 1 | -2 dB gain | | |
| | | | | - | - | - | - | in 2 dB step | | |
| | | | | 1 | 1 | 1 | 1 | -30 dB gain | | |

*: state at power on initialization

Table 9. Control Register CR7 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function | | |
|-----------|---|---|---|----|----|----|----|--|--------------------|--------------------|
| Tone gain | | | | F1 | F2 | SN | DE | Attenuation | f1 V _{PP} | f2 V _{PP} |
| 0 | 0 | 0 | 0 | | | | | 0 dB * | 1.6(2) | 1.26(2) |
| 0 | 0 | 0 | 1 | | | | | -3 dB | | |
| 0 | 0 | 1 | 0 | | | | | -6 dB | | |
| 0 | 0 | 1 | 1 | | | | | -9 dB | | |
| 0 | 1 | 0 | 0 | | | | | -12 dB | | |
| 0 | 1 | 0 | 1 | | | | | -15 dB | | |
| 0 | 1 | 1 | 0 | | | | | -18 dB | | |
| 0 | 1 | 1 | 1 | | | | | -21 dB | | |
| 1 | X | X | 0 | | | | | -24 dB | | |
| 1 | X | X | 1 | | | | | -27 dB | 0.066 | 0.053 |
| | | | | 0 | 0 | | | f1 and f2 muted | * | |
| | | | | 0 | 1 | | | f2 selected | | |
| | | | | 1 | 0 | | | f1 selected | | |
| | | | | 1 | 1 | | | f1 and f2 in summed mode | | |
| | | | | | | 0 | | Squarewave signal selected | * | |
| | | | | | | 1 | | Sinewave signal selected | | |
| | | | | | | | 0 | Normal operation | | |
| | | | | | | | 1 | Tone / Ring Generator connected to Transmit path | * | |

*: state at power on initialization

(2): value provided if f1 or f2 is selected alone. if f1 and f2 are selected in the summed mode, f1=0.89 V_{pp} while f2=0.7 V_{pp}.

X reserved: write 0

Table 10. Control Register CR8 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|-----|-----|-----|-----|-----|-----|-----|-----|--|
| f17 | f16 | f15 | f14 | f13 | f12 | f11 | f10 | |
| msb | | | | | | | lsb | Binary equivalent of the decimal number used to calculate f1 |

Table 11. Control Register CR9 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function |
|-----|-----|-----|-----|-----|-----|-----|-----|--|
| f27 | f26 | f25 | f24 | f23 | f22 | f21 | f20 | |
| msb | | | | | | | lsb | Binary equivalent of the decimal number used to calculate f2 |

Table 12. Control Register CR10 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function | |
|--------|--------|--------|--------|--------|--------|------------------|------------------|---|---|
| REN | RLM | ROI | RDL | PG | MB | DFT | HFT | | |
| 0 1 | | | | | | | | Remocon Function disabled Remocon Function enabled | * |
| | 0 1 | | | | | | | Remocon output in transparent mode Remocon output in latched mode | * |
| | | 0 1 | | | | | | Remocon output not inverted Remocon output inverted | * |
| | | | 0 1 | | | | | Remocon detection latch reset by μ P Remocon detection latch set by internal logic | * |
| | | | | 0 1 | | | | 20dB preamplifier gain 0dB preamplifier gain | * |
| | | | | | 0 1 | | | MBIAS output disabled MBIAS output enabled | * |
| | | | | | | 0 0 1 1 | 0 1 0 1 | Standard Frequency Tone Range Halved Frequency Tone Range Doubled Frequency Tone Range Forbidden | * |

(*) Default values inserted into the Register at Power On.

Table 13. Control Register CR11 Functions

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | Function | |
|--------|--------|-----|-----|-----|-----|-----|-----|--|---|
| BE | BI | BZ5 | BZ4 | BZ3 | BZ2 | BZ1 | BZ0 | | |
| 0 1 | | | | | | | | Buzzer output disabled (set to 0) Buzzer output enabled | * |
| | 0 1 | | | | | | | Duty Cycle is intended as the relative width of logic 1 Duty cycle is intended as the relative width of logic 0 | * |
| | | msb | | | | | lsb | Binary equivalent of the decimal number used to calculate the duty cycle. | |

* state at power on initialization

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CONTROL REGISTER CR0

First byte of a READ or a WRITE instruction to Control Register CR0 is as shown in TABLE 1. Second byte is as shown in TABLE 2.

Master Clock / Auxiliary Clock Frequency Selection

A master clock must be provided to STw5093 to activate all the functions. In the case MCLK is absent, AUXCLK can be provide to STw5093 for activating tone or buzzer functions only.

MCLK or AUXCLK frequency can be either 512 kHz, 1.536 MHz, 2.048 MHz or 2.56 MHz..

Bit F1 (7) and F0 (6) must be set during initialization to select the correct internal divider. Default value is 512 kHz. Any clock different from the default one must be selected prior a Power-Up instruction.

Coding Law Selection

Bits MA (4) and IA (3) permit selection of Mu-255 law or A law coding with or without even bit inversion if companded code (bit CM = 1) is selected. Bits MA(4) and IA(3) permit selection of 2-complement, 1-complement or sign and magnitude if linear code (bit CM = 0) is selected.

Coding Selection

Bit CM (5) permits selection either of linear coding (14-bit) or companded coding (8-bit). Default value is linear coding.

Digital Interface format (1)

Bit FF(2) = 0 selects digital interface in Format 1 where B1 and B2 channel are consecutive. FF=1 selects Format 2 where B1 and B2 channel are separated by two bits. (See digital interface format section.)

56+8 selection (1)

Bit 'B7' (1) selects capability for STw5093 to take into account only the seven most significant bits of the PCM data byte selected.

When 'B7' is set, the LSB bit on DR is ignored and LSB bit on DX is high impedance. This function allows connection of an external "in band" data generator directly connected on the Digital Interface.

Digital loopback

Digital loopback mode is entered by setting DL bit(0) equal 1.

In Digital Loopback mode, data written into Receive PCM Data Register from the selected received time-slot is read-back from that Register in the selected transmit time-slot on D_X.

No PCM decoding or encoding takes place in this mode. Transmit and Receive amplifier stages are muted.

CONTROL REGISTER CR1

First byte of a READ or a WRITE instruction to Control Register CR1 is as shown in TABLE 1. Second byte is as shown in TABLE 3.

Digital Interface Timing

Bit DM1(7) = 0 selects digital interface in delayed timing mode, while DM1 = 1 and DM0 = 0 selects non-delayed normal data timing mode, and DM1 = 1 and DM0 = 1 selects non-delayed reverse data timing mode. Default is delayed data timing.

(1) Significant in companded mode only

Latch output control

Bit DO controls directly logical status of latch output LO: ie, a "ZERO" written in bit DO puts the output LO at logical 1, while a "ONE" written in bit DO sets the output LO to zero.

Microwire access to B channel on receive path (1)

Bit MR (4) selects access from MICROWIRE Register CR2 to Receive path. When bit MR is set high, data written to register CR2 is decoded each frame, sent to the receive path and data input at DR is ignored. In the other direction, current PCM data input received at DR can be read from register CR2 each frame.

Microwire access to B channel on transmit path (1)

Bit MX (3) selects access from MICROWIRE write only Register CR3 to DX output. When bit MX is set high, data written to CR3 is output at DX every frame and the output of PCM encoder is ignored.

| | Mu 255 law | | | | | | | | True A law even bit inversion | | | | | | | | A law without even bit inversion | | | | | | | | | |
|--------------------|------------|---|---|---|-----|---|---|---|-------------------------------|---|---|---|-----|---|---|---|----------------------------------|---|---|---|-----|---|---|---|---|---|
| | msb | | | | lsb | | | | msb | | | | lsb | | | | msb | | | | lsb | | | | | |
| Vin = + full scale | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| Vin = 0V | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Vin = - full scale | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

MSB is always the first PCM bit shifted in or out of: STW5093.

Transmit/Receive enabling/disabling

Bit 'EN' (2) enables or disables voice data transfer on DX and DR pins. When disabled, PCM data from DR is not decoded and PCM time-slots are high impedance on DX. Default value is disabled.

B-channel selection (1)

Bit TS(1) permits selection between B1 or B2 channels. Default value is B1 channel.

Clock Selection

Bit SLC(0) allows the selection between MCLK and AUXCLK. Default value is MCLK.

CONTROL REGISTER CR2(1)

Data sent to receive path or data received from DR input. Refer to bit MR(4) in "Control Register CR1" paragraph.

CONTROL REGISTER CR3 (1)

DX data transmitted. Refer to bit MX(3) in "Control Register CR1" paragraph.

CONTROL REGISTER CR4

First byte of a READ or a WRITE instruction to Control Register CR4 is as shown in TABLE 1. Second byte is as shown in TABLE 6.

(1) Significant in companded mode only



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Transmit Input Selection

MIC1 or MIC2 or MIC3 or transmit mute can be selected with bits 6 and 7 (VS and TE). Transmit gain can be adjusted within a 22.5 dB range in 1.5 dB step with Register CR5.

Sidetone Selection

Bit "SI" (5) enables or disables Sidetone circuitry. When enabled, sidetone gain can be adjusted with Register (CR5). When Transmit path is disabled, sidetone circuit is also disabled.

Output Driver Selection

Bits OE1(4) and OE2(3) provide the selection among the earpiece output or the extra amplifier output or both outputs muted. OE1 = 1 and OE2 = 1 is not allowed.

Ring/Tone signal selection

Bit RTE (2) provide select capability to connect on-chip Ring/Tone generator either to an extra amplifier input or to earpiece amplifier input.

Receiver High Pass Filter Selection

Bit HPB(1) provides the selection of the receiver high pass filter cutoff frequency.

PCM receive data selection

Bits "SE" (0) provide select capability to connect received speech signal either to an extra amplifier input or to earpiece amplifier input.

CONTROL REGISTER CR5

First byte of a READ or a WRITE instruction to Control Register CR5 is as shown in TABLE 1. Second byte is as shown in TABLE 7.

Transmit gain selection

Transmit amplifier can be programmed for a gain from 0dB to 22.5dB in 1.5dB step with bits 4 to 7. 0 dBmO level at the output of the transmit amplifier (A reference point) is 0.492 Vrms (overload voltage is 0.707 Vrms).

Sidetone attenuation selection

Transmit signal picked up after the switched capacitor low pass filter may be fed back into both Receive amplifiers.

Attenuation of the signal at the output of the sidetone attenuator can be programmed from \bar{A} 12.5dB to -27.5dB relative to reference point A in 1 dB step with bits 0 to 3.

CONTROL REGISTER CR6

First byte of a READ or a WRITE instruction to Control Register CR6 is as shown in TABLE 1. Second byte is as shown in TABLE 8.

Earpiece amplifier gain selection:

Earpiece Receive gain can be programmed in 2 dB step from 0 dB to -30 dB relative to the maximum with bits 4 to 7.

0 dBmO voltage at the output of the amplifier on pin VFr is 0.9825 Vrms when 0dB gain is selected down to 30.925 Vrms when -30dB gain is selected.

Extra amplifier gain selection:

Extra Receive amplifier gain can be programmed in 2 dB step from 0 dB to -30 dB relative to the maximum with bits 0 to 3.

0 dBmO voltage on the output of the amplifier on pins V_{Lr+} and V_{Lr-} 1.965 Vrms when 0 dB gain is selected down to 61.85 mVrms when -30 dB gain is selected.

CONTROL REGISTER CR7:

First byte of a READ or a WRITE instruction to Control Register CR7 is as shown in TABLE 1. Second byte is as shown in TABLE 9.

Tone/Ring amplifier gain selection

Output level of Ring/Tone generator, before attenuation by programmable attenuator is 1.6 Vpk-pk when f1 generator is selected alone or summed with the f2 generator and 1.26 Vpk-pk when f2 generator is selected alone. Selected output level can be attenuated down to -27 dB by programmable attenuator by setting bits 4 to 7.

Frequency mode selection

Bits 'F1' (3) and 'F2' (2) permit selection of f1 and/or f2 frequency generator according to TABLE 9.

When f1 (or f2) is selected, output of the Ring/Tone is a squarewave (or a sinewave) signal at the frequency selected in the CR8 (or CR9) Register.

When f1 and f2 are selected in summed mode, output of the Ring/Tone generator is a signal where f1 and f2 frequency are summed.

In order to meet DTMF specifications, f2 output level is attenuated by 2dB relative to the f1 output level.

Frequency temporization must be controlled by the microcontroller.

Waveform selection

Bit 'SN' (1) selects waveform of the output of the Ring/Tone generator. Sinewave or squarewave signal can be selected.

DTMF selection

Bit DE (0) permits connection of Ring/Tone/DTMF generator on the Transmit Data path instead of the Transmit Amplifier output. Earpiece or extra receive output feed-back may be provided by sidetone circuitry by setting bit SI or directly by setting bit RTE in Register CR4. Loudspeaker feed-back may be provided directly by setting bit RTL in Register CR4.

CONTROL REGISTERS CR8 AND CR9

First byte of a READ or a WRITE instruction to Control Register CR8 or CR9 is as shown in TABLE 1. Second byte is respectively as shown in TABLE 10 and 11.

If "standard frequency tone range" is selected, Tone or Ring signal frequency value is defined by the formula:

$$f1 = CR8 / 0.128 \text{ Hz}$$

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and

$$f2 = CR9 / 0.128 \text{ Hz}$$

where CR8 and CR9 are decimal equivalents of the binary values of the CR8 and CR9 registers respectively. Thus, any frequency between 7.8 Hz and 1992 Hz may be selected in 7.8 Hz step.

If "halved frequency tone range" is selected, Tone or Ring signal frequency value is defined by the formula:

$$f1 = CR8 / 0.256 \text{ Hz}$$

and

$$f2 = CR9 / 0.256 \text{ Hz}$$

This any frequency between 3.9Hz and 996Hz may be selected in 3.9Hz step.

If "doubled frequency tone range" is selected, Tone or Ring signal frequency value is defined by the formula:

$$f1 = CR8 / 0.064 \text{ Hz}$$

and

$$f2 = CR9 / 0.064 \text{ Hz}$$

Thus any frequency between 15.6Hz and 3984Hz may be selected in 15.6Hz step.

TABLE 12 gives examples for the main frequencies usual for Tone or Ring generation.

CONTROL REGISTER CR10**Remocon Function Enable**

Bit REN(7) enables or disables the RemoconFunction. Default value is disabled.

Remocon Mode Selection

Bit RLM(6) is used to select between a transparent pressed button information and a latched pressed button information at REMOUT. In both cases a debounce circuit (50ms max.) is active.

Remocon Output Inversion

Bit ROI(5) is used to invert or not the information at REMOUT. Default value is not inverted (i.e. pressed button information is a logic 1 at REMOUT).

Remocon Detection Latch

Bit RDL(4) is set by the internal Remocon Function logic, after the debounce time, when a low level on REMIN is detected. It can be reset by the mP writing CR10.

Preamplifier Gain Selection

Bit PG(3) provides the selection between 0dB and 20dB gain of the preamplifier. Default value is 20dB.

Microphone Bias Disabling/Enabling

Bit MB (2) enables or disables a switch for microphone biasing. Default value is disabled.

Tone Frequency Range Selection

Bit DFT(1) and HFT(0) permits the selection among "standard frequency tone range" (i.e. from 7.8Hz to 1992Hz in 7.8Hz step), "halved frequency tone range" (i.e. from 3.9Hz to 996Hz in 3.9Hz step), and "doubled frequency

tone range" (i.e. from 15.6Hz to 3984Hz in 15.6Hz step) according to the values described in CONTROL REGISTER CR8 and CR9.

CONTROL REGISTER CR11

Bit BE(7) permits connection of a f1 squarewave PWM Ring signal, amplitude modulated or not by a f2 squarewave signal, to buzzer driver output BZ. Bits BZ5 to BZ0 define the duty cycle of the PWM squarewave, according to the following formula:

$$\text{Duty Cycle} = \text{CR11}(5 \text{ to } 0) \times 0.78125\%$$

where CR11(5 to 0) is the decimal equivalent of the binary value BZ5 to BZ0.

When BE = 1, if bits F1 = 1 and F2 = 0 in register CR7, a f1 PWM ring signal is present at the buzzer output, while if bits F1 = 1 and F2 = 1 in register CR7 the f1 PWM ring signal is also amplitude modulated by a f2 squarewave frequency. Bit BI (6) allows to chose the logic level at which the duty cycle is referred: BI = 0 means that duty cycle is intended as the relative width of the logic1, while BI = 1 means that duty cycle is intended as the relative width of the logic 0. When BE = 0 (or during power down) BZ = 0 if BI = 0 or BZ = 1 if BI = 1.

Table 14. Examples of Usual Frequency Selection (Standard frequency tone range)

| Description | f1 value (decimal) | Theoretic value (Hz) | Typical value (Hz) | Error% |
|--------------|--------------------|----------------------|--------------------|--------|
| Tone 250 Hz | 32 | 250 | 250 | -0.0 |
| Tone 330 Hz | 42 | 330 | 328.2 | -0.56 |
| Tone 425 Hz | 54 | 425 | 421.9 | -0.73 |
| Tone 440 Hz | 56 | 440 | 437.5 | -0.56 |
| Tone 800 Hz | 102 | 800 | 796.9 | -0.39 |
| Tone 1330 Hz | 170 | 1330 | 1328.1 | -0.14 |
| DTMF 697Hz | 89 | 697 | 695.3 | -0.24 |
| DTMF 770 Hz | 99 | 770 | 773.4 | +0.44 |
| DTMF 852 Hz | 109 | 852 | 851.6 | -0.05 |
| DTMF 941 Hz | 120 | 941 | 937.5 | -0.37 |
| DTMF 1209 Hz | 155 | 1209 | 1210.9 | +0.16 |
| DTMF 1336 Hz | 171 | 1336 | 1335.9 | -0.01 |
| DTMF 1477 Hz | 189 | 1477 | 1476.6 | .00 |
| DTMF 1633 Hz | 209 | 1633 | 1632.8 | .00 |
| SOL | 50 | 392 | 390.6 | -0.30 |
| LA | 56 | 440 | 437.5 | -0.56 |
| SI | 63 | 494 | 492.2 | -0.34 |
| DO | 67 | 523.25 | 523.5 | +0.04 |
| RE | 75 | 587.33 | 586.0 | -0.23 |
| MI flat | 80 | 622.25 | 625.0 | +0.45 |
| MI | 84 | 659.25 | 656.3 | -0.45 |
| FA | 89 | 698.5 | 695.3 | -0.45 |
| FA sharp | 95 | 740 | 742.2 | +0.30 |
| SOL | 100 | 784 | 781.3 | -0.34 |
| SOL sharp | 106 | 830.6 | 828.2 | -0.29 |
| LA | 113 | 880 | 882.9 | +0.33 |
| SI | 126 | 987.8 | 984.4 | -0.34 |
| DO | 134 | 1046.5 | 1046.9 | +0.04 |
| RE | 150 | 1174.66 | 1171.9 | -0.23 |
| MI | 169 | 1318.5 | 1320.4 | +0.14 |

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TIMING DIAGRAM

Figure 2. Non Delayed Data Timing Mode (Normal) (*)

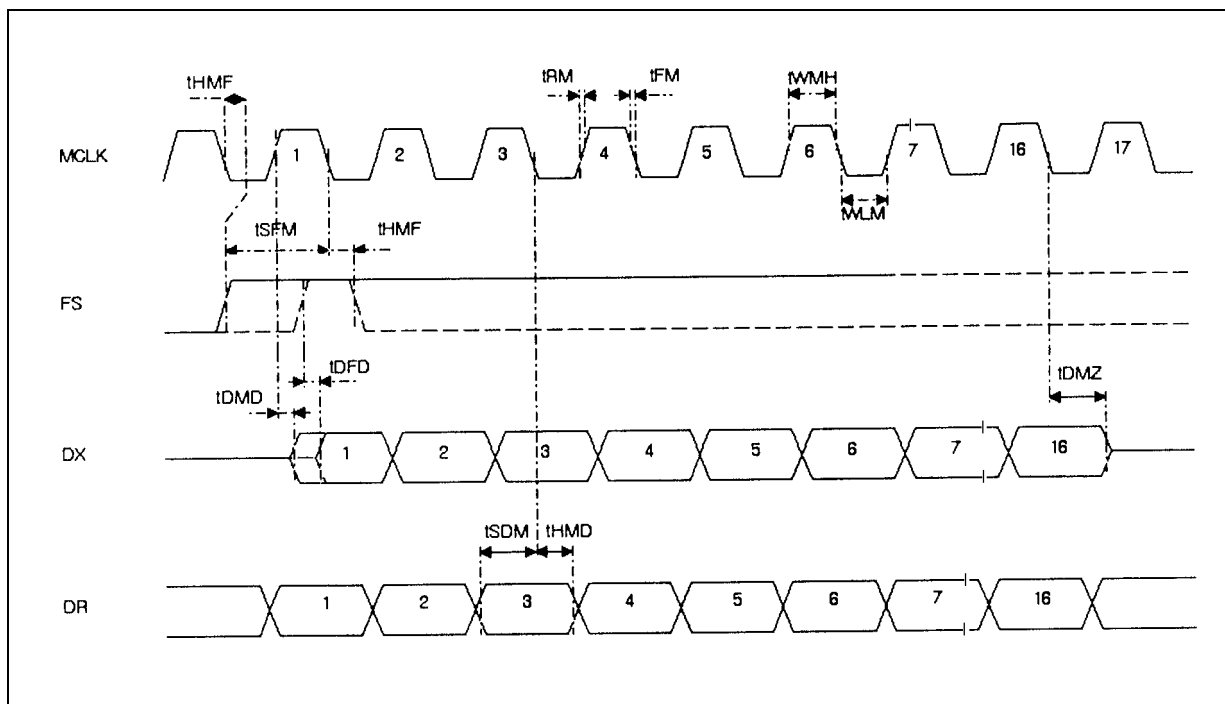
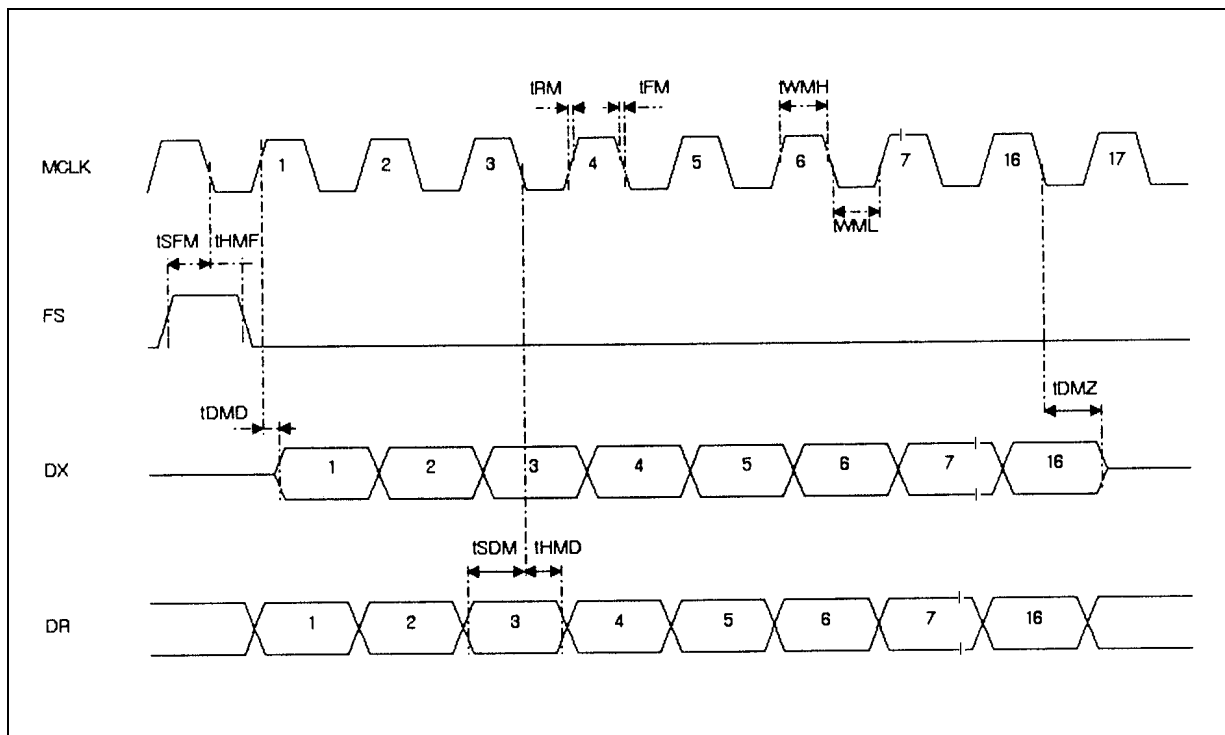


Figure 3. Delayed Data Timing Mode (*)

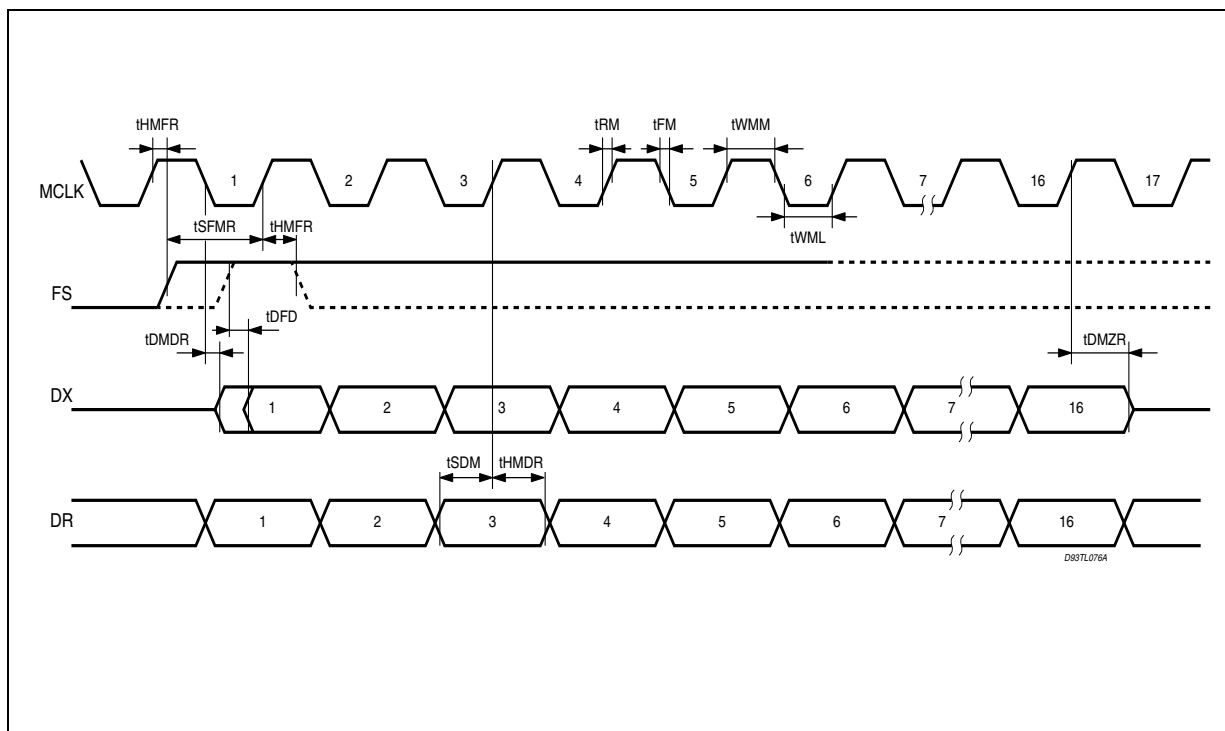


(*) In the case of companded code the timing is applied to 8 bits instead of 16 bits.



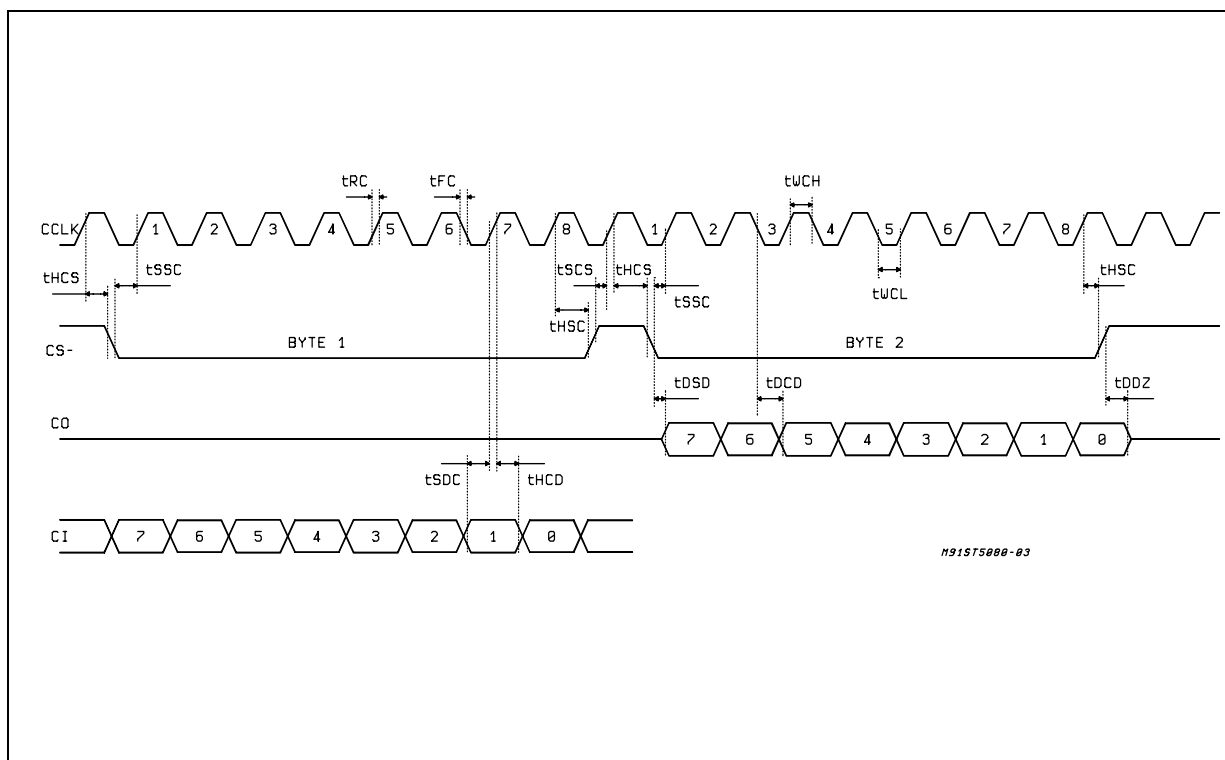
TIMING DIAGRAM

Figure 4. Non Delayed Reverse Data Timing Mode (*)



(*) In the case of companded code the timing is applied to 8 bits instead of 16 bits.

Figure 5. Serial Control Timing (MICROWIRE MODE)



STw5093**ABSOLUTE MAXIMUM RATINGS**

| Parameter | Value | Unit |
|--|-------------------------------------|------|
| V _{CC} to GND | 4.6 | V |
| Voltage at MIC (V _{CC} ≤ 3.3V) | V _{CC} +0.5 to GND -0.5 | V |
| Current at V _{Fr} and V _{Lr} | ± 100 | mA |
| Current at any digital output | ± 50 | mA |
| Voltage at any digital input (V _{CCIO} ≤ 3.3V); limited at ± 50mA | V _{CCIO} + 0.5 to GND -0.5 | V |
| Storage temperature range | - 65 to + 150 | °C |
| Lead Temperature (wave soldering, 10s) | + 260 | °C |

OPERATIVE SUPPLY VOLTAGES

| Symbol | Min. | Max. | Unit |
|---|------|-----------------|------|
| V _{CC} = V _{CCA} = V _{CCP} | 2.7 | 3.3 | V |
| V _{CCIO} | 1.8 | V _{CC} | V |

TIMING SPECIFICATIONS (unless otherwise specified, V_{CCIO} = 1.8V to 3.3V, T_{amb} = -30°C to 85°C ; typical characteristics are specified at V_{CCIO} = 3.0V, T_{amb} = 25°C; all signals are referenced to GND, see Note 5 for timing definitions)

NOTICE: All timing specifications can be changed.

MASTER CLOCK TIMING

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|---------------------|--|------|--------------------------------|------|--------------------------|
| f _{MCLK} | Frequency of MCLK | Selection of frequency is programmable (see table 2) | | 512 1.536 2.048 2.560 | | kHz MHz MHz MHz |
| t _{WMH} | Period of MCLK high | Measured from V _{IH} to V _{IH} | 150 | | | ns |
| t _{WML} | Period of MCLK low | Measured from V _{IL} to V _{IL} | 150 | | | ns |
| t _{RM} | Rise Time of MCLK | Measured from V _{IL} to V _{IH} | | | 30 | ns |
| t _{FM} | Fall Time of MCLK | Measured from V _{IH} to V _{IL} | | | 30 | ns |

PCM INTERFACE TIMING

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|------------------|-------------------------------------|----------------|------|------|------|------|
| t _{HMF} | Hold Time MCLK low to FS low | | 0 | | | ns |
| t _{SFM} | Setup Time, FS high to MCLK low | | 30 | | | ns |
| t _{DMD} | Delay Time, MCLK high to data valid | Load = 20pF | | | 100 | ns |

TIMING SPECIFICATIONS (continued)**PCM INTERFACE TIMING** (continued)

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|--|--|------|------|------|------|
| t _{DMZ} | Delay Time, MCLK low to DX disabled | | 10 | | 100 | ns |
| t _{DFD} | Delay Time, FS high to data valid | Load = 20pF; Applies only if FS rises later than MCLK rising edge in Non Delayed Mode only | | | 100 | ns |
| t _{SDM} | Setup Time, DR valid to MCLK receive edge | | 20 | | | ns |
| t _{HMD} | Hold Time, MCLK low to D _R invalid | | 10 | | | ns |
| t _{HMFR} | Hold Time MCLK High to FS low | | 30 | | | ns |
| t _{SFMR} | Setup Time, FS high to MCLK High | | 30 | | | ns |
| t _{DMDR} | Delay Time, MCLK low to data valid | Load = 20pF | | | 100 | ns |
| t _{DMZR} | Delay Time, MCLK High to DX disabled | | 10 | | 100 | ns |
| t _{HMDR} | Hold Time, MCLK High to D _R invalid | | 20 | | | ns |

SERIAL CONTROL PORT TIMING

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-----------------------------|---------------------------------------|--|------|------|-------|------|
| f _{CCLK} | Frequency of CCLK | | | | 2.048 | MHz |
| t _{WCH} | Period of CCLK high | Measured from V _{IH} to V _{IH} | 160 | | | ns |
| t _{WCL} | Period of CCLK low | Measured from V _{IL} to V _{IL} | 160 | | | ns |
| t _{RC} | Rise Time of CCLK | Measured from V _{IL} to V _{IH} | | | 50 | ns |
| t _{FC} | Fall Time of CCLK | Measured from V _{IH} to V _{IL} | | | 50 | ns |
| t _{HCS} | Hold Time, CCLK high to CS- low | | 10 | | | ns |
| t _{SSC} | Setup Time, CS- low to CCLK high | | 50 | | | ns |
| t _{SDC} | Setup Time, CI valid to CCLK high | | 50 | | | ns |
| t _{HCD} | Hold Time, CCLK high to CI invalid | | 50 | | | ns |
| t _{D_{CD}} | Delay Time, CCLK low to CO data valid | Load = 20pF | | | 80 | ns |
| t _{D_{SD}} | Delay Time, CS-low to CO data valid | | | | 50 | ns |

STw5093**TIMING SPECIFICATIONS** (continued)**SERIAL CONTROL PORT TIMING** (continued)

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|------------------|---|----------------|------|------|------|------|
| t _{DDZ} | Delay Time CS-high or 8th CCLK low to CO high impedance whichever comes first | | 10 | | 80 | ns |
| t _{HSC} | Hold Time, 8th CCLK high to CS-high | | 100 | | | ns |
| t _{SCS} | Set up Time, CS- high to CCLK high | | 100 | | | ns |

Note 5:

A signal is valid if it is above V_{IH} or below V_{IL} and invalid if it is between V_{IL} and V_{IH}. For the purposes of this specification the following conditions apply:

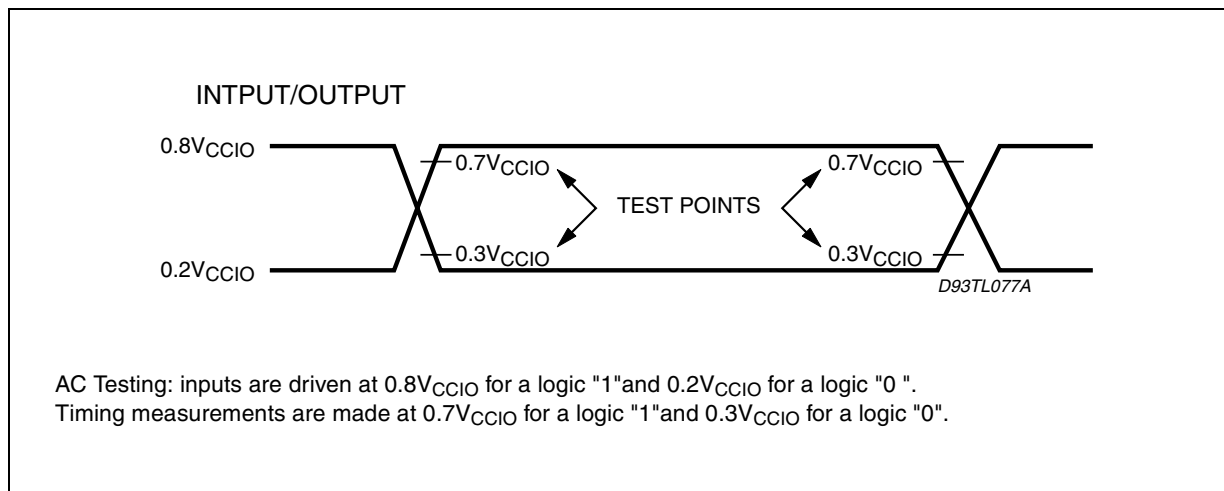
- All input signal are defined as: V_{IL} = 0.2V_{CCIO}, V_{IH} = 0.8V_{CCIO}, t_R < 10ns, t_F < 10ns.
- Delay times are measured from the inputs signal valid to the output signal valid.
- Setup times are measured from the data input valid to the clock input invalid.
- Hold times are measured from the clock signal valid to the data input invalid.

ELECTRICAL CHARACTERISTICS (unless otherwise specified, V_{CCIO} = 1.8V to 3.3V, T_{amb} = -30°C to 85°C; typical characteristic are specified at V_{CCIO} = 3.0V, T_{amb} = 25°C ; all signals are referenced to GND)

DIGITAL INTERFACES

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------------------|--|---|--|------|--|--------|
| V _{IL} | Input Low Voltage | All digital inputs except REMIN DC AC | | | 0.3V _{CCIO} 0.2V _{CCIO} | V V |
| V _{IH} | Input High Voltage | All digital inputs except REMIN DC AC | 0.7V _{CCIO} 0.8V _{CCIO} | | | V V |
| V _{ILREM} | Input Low Voltage | REMIN input | | | 0.5 | V |
| V _{IHREM} | Input High Voltage | REMIN input | 1.4 | | | V |
| V _{OL} | Output Low Voltage | All digital outputs, I _L = 10μA All digital outputs, I _L = 2mA | | | 0.1 0.4 | V V |
| V _{OH} | Output High Voltage | All digital outputs, I _L = 10μA All digital outputs, I _L = 2mA | V _{CCIO} -0.1 V _{CCIO} -0.4 | | | V V |
| I _{IL} | Input Low Current | Any digital input, GND < V _{IN} < V _{IL} | -10 | | 10 | μA |
| I _{IH} | Input High Current | Any digital input, V _{IH} < V _{IN} < V _{CCIO} | -10 | | 10 | μA |
| I _{OZ} | Output Current in High impedance (Tri-state) | DX and CO | -10 | | 10 | μA |

Figure 6. A.C. TESTING INPUT, OUTPUT WAVEFORM



ANALOG INTERFACES

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------|--|--|------|------|------|------------|
| R_{MBIAS} | Switch Resistance for Microphone bias | MBIAS 100mV under V_{CC} | | | 150 | Ω |
| I_{MIC} | Input Leakage | $GND < V_{MIC} < V_{CC}$ | -100 | | +100 | μA |
| R_{MIC} | Input Resistance | $GND < V_{MIC} < V_{CC}$ | 50 | | | k Ω |
| R_{LVFr} | Load Resistance | | 30 | | | Ω |
| C_{LVFr} | Load Capacitance | | | 50 | | nF |
| R_{OVr0} | Output Resistance | Steady zero PCM code applied to DR; $I = \pm 1mA$ | | 1.0 | | Ω |
| R_{LVLr} | Load Resistance | V_{Lr+} to V_{Lr-} | 8 | | | Ω |
| C_{LVLr} | Load Capacitance | from V_{Lr+} to V_{Lr-} | | 50 | | nF |
| R_{OLVr0} | Output Resistance | Steady zero PCM code applied to DR; $I \pm 1mA$ | | 1 | | Ω |
| V_{OSVr0} | Differential offset Voltage at V_{Lr+} , V_{Lr-} | Alternating \pm zero PCM code applied to DR maximum receive gain; $R_L = 50\Omega$ | -50 | | +50 | mV |

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TRANSMISSION CHARACTERISTICS (unless otherwise specified, $V_{CC} = 2.7V$ to $3.3V$, $T_{amb} = -30^{\circ}C$ to $85^{\circ}C$; typical characteristics are specified at $V_{CC} = 3.0V$, $T_{amb} = 25^{\circ}C$, $MIC1/2/3 = 0dBm_0$, $D_R = -6dBm_0$ PCM code, $f = 1015.625$ Hz; all signal are referenced to GND)

AMPLITUDE RESPONSE (Maximum, Nominal, and Minimum Levels)

Transmit path - Absolute levels at MIC1 / MIC2 / MIC3

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------|--------------------------|---|------|-------|------|-------------------|
| | 0 dBm ₀ level | Transmit Amps connected for 20dB gain | | 49.26 | | mV _{RMS} |
| | Overload level | | | 70.71 | | mV _{RMS} |
| | 0 dBm ₀ level | Transmit Amps connected for 42.5dB gain | | 3.694 | | mV _{RMS} |
| | Overload level | | | 5.302 | | mV _{RMS} |

AMPLITUDE RESPONSE (Maximum, Nominal, and Minimum Levels)Receive path - Absolute levels at V_{Fr}

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------|--------------------------|---|------|--------|------|-------------------|
| | 0 dBm ₀ level | Receive Amp programmed for 0dB attenuation | | 0.9825 | | V _{RMS} |
| | 0 dBm ₀ level | Receive Amp programmed for 30dB attenuation | | 30.925 | | mV _{RMS} |

AMPLITUDE RESPONSE (Maximum, Nominal, and Minimum Levels)Receive path - Absolute levels at V_{Lr} (Differentially measured)

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------|--------------------------|---|------|-------|------|-------------------|
| | 0 dBm ₀ level | Receive Amp programmed for 0dB attenuation | | 1.965 | | V _{RMS} |
| | 0 dBm ₀ level | Receive Amp programmed for 30dB attenuation | | 61.85 | | mV _{RMS} |

AMPLITUDE RESPONSE

Transmit path

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-----------|--|--|------|------|------|------|
| G_{XA} | Transmit Gain Absolute Accuracy | Transmit Gain Programmed for minimum. Measure deviation of Digital PCM Code from ideal 0dB _{m0} PCM code at D_x | -0.5 | | 0.5 | dB |
| G_{XAG} | Transmit Gain Variation with programmed gain | Measure Transmit Gain over the range from Maximum to minimum setting. Calculate the deviation from the programmed gain relative to G_{XA} , i.e. $G_{XAG} = G_{actual} - G_{prog.} - G_{XA}$ | -0.5 | | 0.5 | dB |
| G_{XAT} | Transmit Gain Variation with temperature | Measured relative to G_{XA} . min. gain < G_x < Max. gain | -0.1 | | 0.1 | dB |
| G_{XAV} | Transmit Gain Variation with supply | Measured relative to G_{XA} $G_x =$ Minimum gain | -0.1 | | 0.1 | dB |

AMPLITUDE RESPONSE(continued)
 Transmit path (continued)

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|------------------|---|---|------|------|------|------|
| G _{XAF} | Transmit Gain Variation with frequency | Relative to 1015,625 Hz, multitone test technique used.min. gain < G _X < Max. gain f = 60 Hz f = 100 Hz f = 200 Hz f = 300 Hz f = 400 Hz to 3000 Hz f = 3400 Hz f = 4000 Hz f = 4600 Hz (*) f = 8000 Hz (*) | | | | |
| | | | | | -30 | dB |
| | | | | | -20 | dB |
| | | | | | -6 | dB |
| | | | -1.5 | | 0.5 | dB |
| | | | -0.5 | | 0.5 | dB |
| | | | -1.5 | | 0.0 | dB |
| | | | | | -14 | dB |
| | | | | | -35 | dB |
| | | | | | -47 | dB |
| G _{XAL} | Transmit Gain Variation with signal level | Sinusoidal Test method.Reference Level = -10 dBm0 V _{MIC} = -40 dBm0 to +3 dBm0 V _{MIC} = -50 dBm0 to -40 dBm0 V _{MIC} = -55 dBm0 to -50 dBm0 | | | | |
| | | | -0.5 | | 0.5 | dB |
| | | | -0.5 | | 0.5 | dB |
| | | | -1.2 | | 1.2 | dB |

(*) The limit at frequencies between 4600Hz and 8000Hz lies on a straight line connecting the two frequencies on a linear (dB) scale versus log (Hz) scale.

Receive path

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|---|---|------|------|------|------|
| G _{RAE} | Receive Gain Absolute Accuracy | Receive gain programmed for maximum Apply -6 dBm0 PCM code to DR Measure V _{Fr} | -0.5 | | 0.5 | dB |
| G _{RAL} | Receive Gain Absolute Accuracy | Receive gain programmed for maximum Apply -6 dBm0 PCM code to DR Measure V _{Lr±} | -0.5 | | 0.5 | dB |
| G _{RAGE} | Receive Gain Variation with programmed gain | Measure V _{Fr} Gain over the range from Maximum to minimum setting. Calculate the deviation from the programmed gain relative to G _{RAE} , i.e. G _{RAGE} = G _{actual} - G _{prog.} - G _{RAE} | -0.5 | | 0.5 | dB |
| G _{RAGL} | Receive Gain Variation with programmed gain | Measure V _{Lr} Gain over the range from Maximum to minimum setting.Calculate the deviation from the programmed gain relative to G _{RAL} , i.e. G _{RAGL} = G _{actual} - G _{prog.} - G _{RAL} | -0.5 | | 0.5 | dB |
| G _{RAT} | Receive Gain Variation with temperature | Measured relative to GRA. (V _{Lr} and V _{Fr}) min. gain < G _R < Max. gain | -0.1 | | 0.1 | dB |

STw5093**AMPLITUDE RESPONSE**(continued)

Receive path (continued)

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------------------|---|---|----------------------|------|--|--|
| G _{RAV} | Receive Gain Variation with Supply | Measured relative to G _{RA} . (V _{LR} and V _{FR}) G _R = Maximum Gain | -0.1 | | 0.1 | dB |
| G _{RAF} | Receive Gain Variation with frequency (V _{LR} and V _{FR}) HPB = 0 | Relative to 1015,625 Hz, multitone test technique used. min. gain < G _R < Max. gain f = 60Hz f = 100Hz f = 200 Hz f = 300 Hz f = 400 Hz to 3000 Hz f = 3400 Hz f = 4000 Hz | | | -20 -12 -2 0.5 0.5 0.0 -14 | dB dB dB dB dB dB dB |
| | Receive Gain Variation with frequency (V _{LR} and V _{FR}) HPB = 1 | Relative to 1015,625 Hz, multitone test technique used. Min. gain < G _R < Max. gain f = 50Hz f = 100 Hz to 3000 Hz f = 3400 Hz f = 4000 Hz | -1.5 -0.5 -1.5 | | 0.5 0.5 0.0 -14 | dB dB dB dB |
| G _{RAL E} | Receive Gain Variation with signal level (V _{FR}) | Sinusoidal Test Method Reference Level = -10 dBm0 D _R = -40 dBm0 to -3 dBm0 | -0.5 | | 0.5 | dB |
| | | D _R = -50 dBm0 to -40 dBm0 | -0.5 | | 0.5 | dB |
| | | D _R = -55 dBm0 to -50 dBm0 | -1.2 | | 1.2 | dB |
| G _{RAL L} | Receive Gain Variation with signal level (V _{LR}) | Sinusoidal Test Method Reference Level = -10 dBm0 D _R = -40 dBm0 to -3 dBm0 | -0.5 | | 0.5 | dB |
| | | D _R = -50 dBm0 to -40 dBm0 | -0.5 | | 0.5 | dB |
| | | D _R = -55 dBm0 to -50 dBm0 | -1.2 | | 1.2 | dB |

ENVELOPE DELAY DISTORTION WITH FREQUENCY

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------|--------------------|--------------------|------|------|------|------|
| DXA | Tx Delay, Absolute | f = 1600 Hz | | 320 | | µs |
| DXR | Tx Delay, Relative | f = 500 - 600 Hz | | 290 | | µs |
| | | f = 600 - 800 Hz | | 180 | | µs |
| | | f = 800 - 1000 Hz | | 50 | | µs |
| | | f = 1000 - 1600 Hz | | 20 | | µs |
| | | f = 1600 - 2600 Hz | | 55 | | µs |
| | | f = 2600 - 2800 Hz | | 80 | | µs |
| | | f = 2800 - 3000 Hz | | 180 | | µs |
| DRA | Rx Delay, Absolute | f = 1600 Hz | | 280 | | µs |
| DRR | Rx Delay, Relative | f = 500 - 600 Hz | | 200 | | µs |
| | | f = 600 - 800 Hz | | 110 | | µs |
| | | f = 800 - 1000 Hz | | 50 | | µs |
| | | f = 1000 - 1600 Hz | | 20 | | µs |
| | | f = 1600 - 2600 Hz | | 65 | | µs |
| | | f = 2600 - 2800 Hz | | 100 | | µs |
| | | f = 2800 - 3000 Hz | | 220 | | µs |

NOISE

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|--------|---|---|----------|------|-------------------|----------------|
| NXP | Tx Noise, P weighted (up to 35dB) | V _{MIC} = 0V, DE = 0 | | -75 | -70 | dBmOp |
| NRP | Rx Noise, linear weighted (*) (max. gain) | Receive PCM code = Positive Zero SI = 0 and RTE = 0 | | 120 | 150 | µVrms |
| NRS | Noise, Single Frequency | MIC = 0V, Loop-around measurement from f = 0 Hz to 100 kHz | | -50 | | dBm0 |
| PPSRx | PSRR, Tx | MIC = 0V, V _{CC} = 3.0 V _{DC} + 50 mVrms; f = 100Hz to 50KHz | 30 | | | dB |
| PPSRp | PSRR, Rx | PCM Code equals Positive Zero, V _{CC} = 3.0VDC + 50 mVrms, f = 100 Hz - 4 kHz f = 4 kHz - 50 kHz | 30 30 | | | dB dB |
| SOS | Spurious Out-Band signal at the output | DR input set to -6 dBm0 PCM code 300 - 3400 Hz Input PCM Code applied at D _R 4600 Hz - 5600 Hz 5600 Hz - 7600 Hz 7600 Hz - 8400 Hz | | | -40 -50 -50 | dB dB dB |

(*) 300 to 3400Hz bandwidth

CROSSTALK

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|---------------------|--|------|------|------|------|
| C _{Tx-r} | Transmit to Receive | Transmit Level = 0 dBm0, f = 300 - 3400 Hz D _R = Quiet PCM Code | | -100 | -65 | dB |
| C _{Tr-x} | Receive to Transmit | Receive Level = -6 dBm0, f = 300 - 3400 Hz MIC = 0V | | -80 | -65 | dB |



STw5093**DISTORTION**

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-----------------------|---|---|------|------|------|------|
| S _{TDX} (*) | Signal to Total Distortion (up to 35dB gain) Typical values are measured with 30.5dB gain | Sinusoidal Test Method (measured using linear 300 to 3400 weighting) Level = 0 dBm0 Level = -6 dBm0 Level = -10 dBm0 Level = -20 dBm0 Level = -30 dBm0 Level = -40 dBm0 Level = -45 dBm0 Level = -55 dBm0 | | # | | |
| | | | 56 | 56 | 65 | dB |
| | | | 50 | 50 | 64 | dB |
| | | | 48 | 48 | 61 | dB |
| | | | 43 | 43 | 52 | dB |
| | | | 38 | 37.5 | 42 | dB |
| | | | 29 | 28.5 | 31 | dB |
| | | | 24 | 23 | 26 | dB |
| 15 | 13 | 16 | dB | | | |
| S _{DFx} | Single Frequency Distortion transmit | 0 dBm0 input signal | | -80 | -56 | dB |
| S _{TDRE} (*) | Signal to Total Distortion (V _{Fr}) (up to 20dB attenuation) Typical values are measured with 20dB attenuation. | Sinusoidal Test Method (measured using linear 300 to 3400 weighting) Level = -6 dBm0 Level = -10 dBm0 Level = -20 dBm0 Level = -30 dBm0 Level = -40 dBm0 Level = -45 dBm0 Level = -55 dBm0 | | | | |
| | | | 50 | 64 | dB | |
| | | | 48 | 62 | dB | |
| | | | 43 | 53 | dB | |
| | | | 38 | 43 | dB | |
| | | | 29 | 33 | dB | |
| | | | 24 | 28 | dB | |
| | | | 15 | 18 | dB | |
| S _{DFr} | Single Frequency Distortion receive (V _{Fr}) | -6 dBm0 input signal | | -80 | -50 | dB |
| S _{TDRL} (*) | Signal to Total Distortion (V _{Lr}) (up to 20dB attenuation) Typical values are measured with 20dB attenuation | Sinusoidal Test Method (measured using linear 300 to 3400 weighting) Level = -6 dBm0 Level = -10 dBm0 Level = -20 dBm0 Level = -30 dBm0 Level = -40 dBm0 Level = -45 dBm0 Level = -55 dBm0 | | | | |
| | | | 50 | 64 | dB | |
| | | | 48 | 62 | dB | |
| | | | 43 | 53 | dB | |
| | | | 38 | 43 | dB | |
| | | | 29 | 33 | dB | |
| | | | 24 | 28 | dB | |
| | | | 15 | 18 | dB | |
| S _{DLr} | Single Frequency Distortion receive (V _{Lr}) | -6 dBm0 input signal | | -80 | -50 | dB |
| MD | Intermodulation | Loop-around measurement Voltage at MIC = -10 dBm0 to -27 dBm0, 2 Frequencies in the range 300 - 3400 Hz | | -75 | -46 | dB |

(*) The limit curve shall be determined by straight lines joining successive coordinates given in the table.

(#) Lower limits used during the automatic testing to avoid unrealistic yield loss due to ±2dB imprecision of time-limited noise measurements.

POWER DISSIPATION

| Symbol | Parameter | Test Condition | Min. | Typ. | Max. | Unit |
|-------------------|--------------------|---|------|------|------|------|
| I _{CC0} | Power down Current | CCLK, CI = 0.1V; CS- = V _{CCIO} -0.1V REMOCON function disabled (REN = 0) | | 0.4 | 5 | µA |
| I _{CC0R} | Power down Current | CCLK, CI = 0.1V; CS- = V _{CCIO} -0.1V REMOCON function enabled (REN = 1) REMIN = V _{ILREM} or REMIN = V _{IHREM} | | 2 | 10 | µA |
| I _{CC1} | Power Up Current | V _{Lr+} , V _{Lr-} and V _{Fr} not loaded | | 5 | 8 | mA |

AUDIO CODEC APPLICATIONS

Figure 7. Application Note for Microphone Connections.

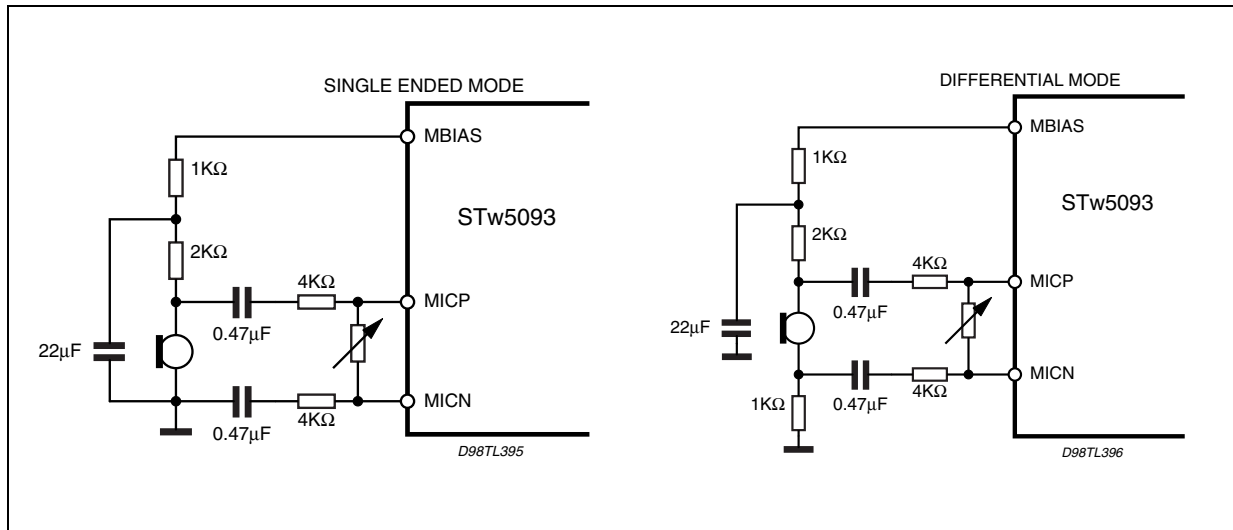


Figure 8. Application Note for V_{Lr} Connections.

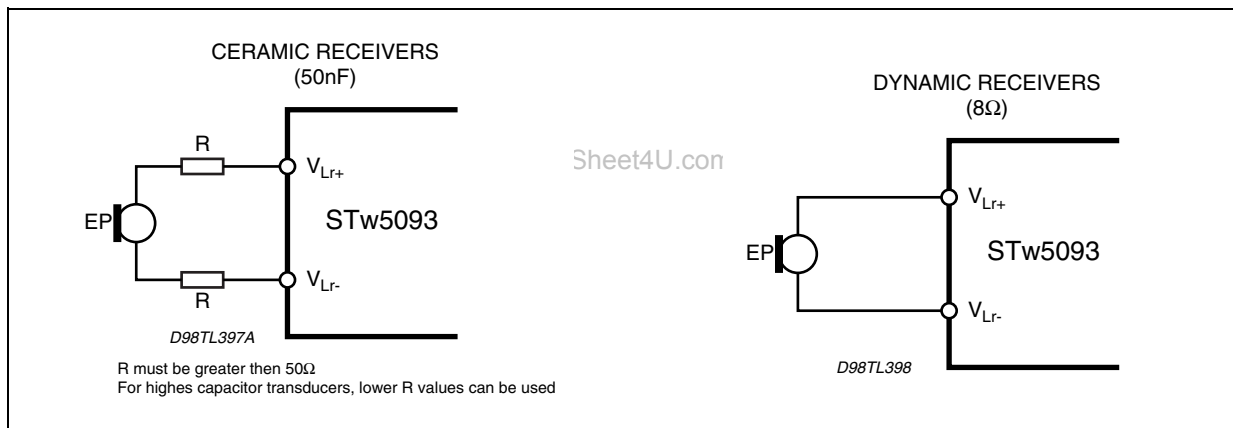
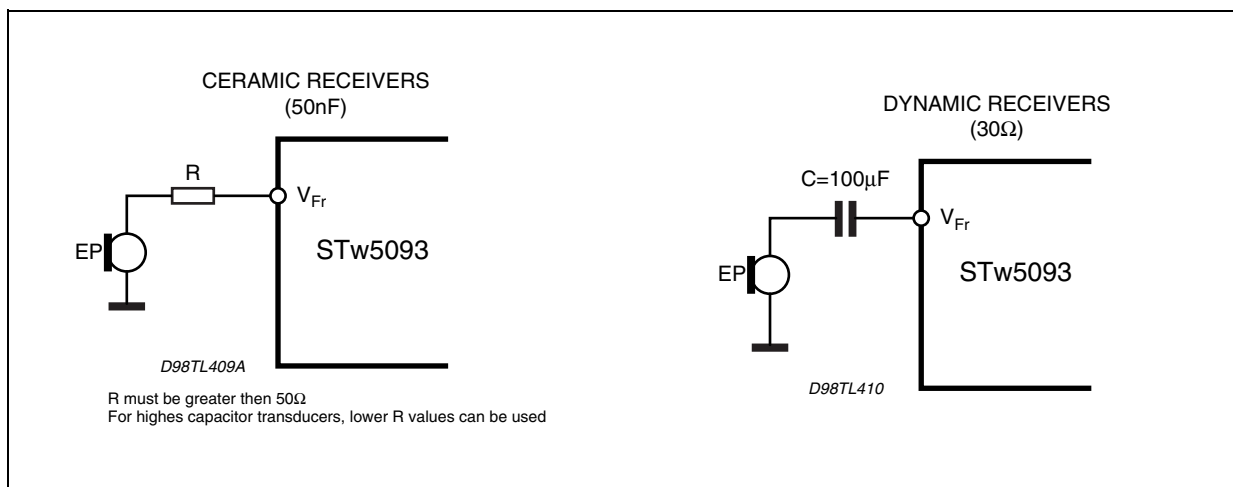


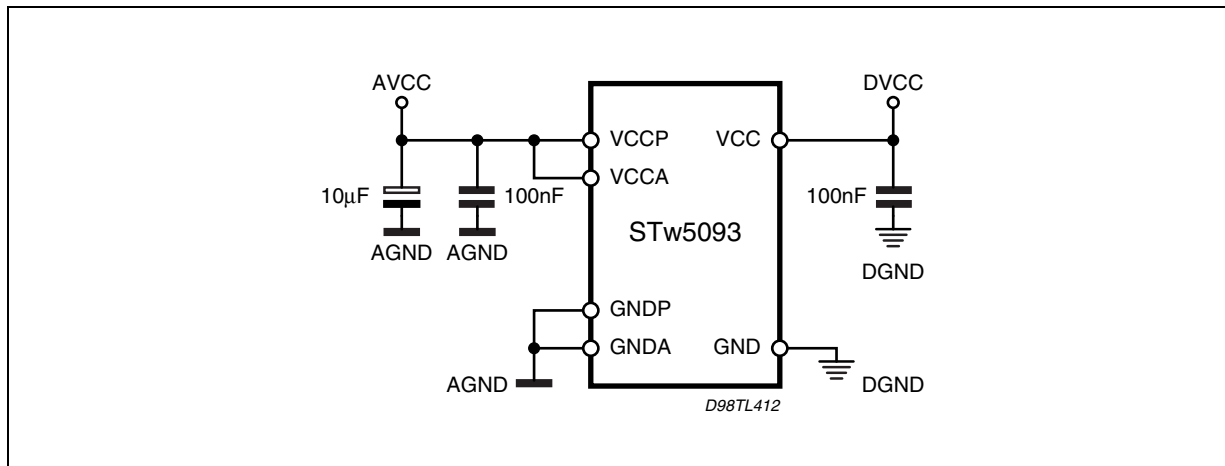
Figure 9. Application Note for V_{Fr} Connections.



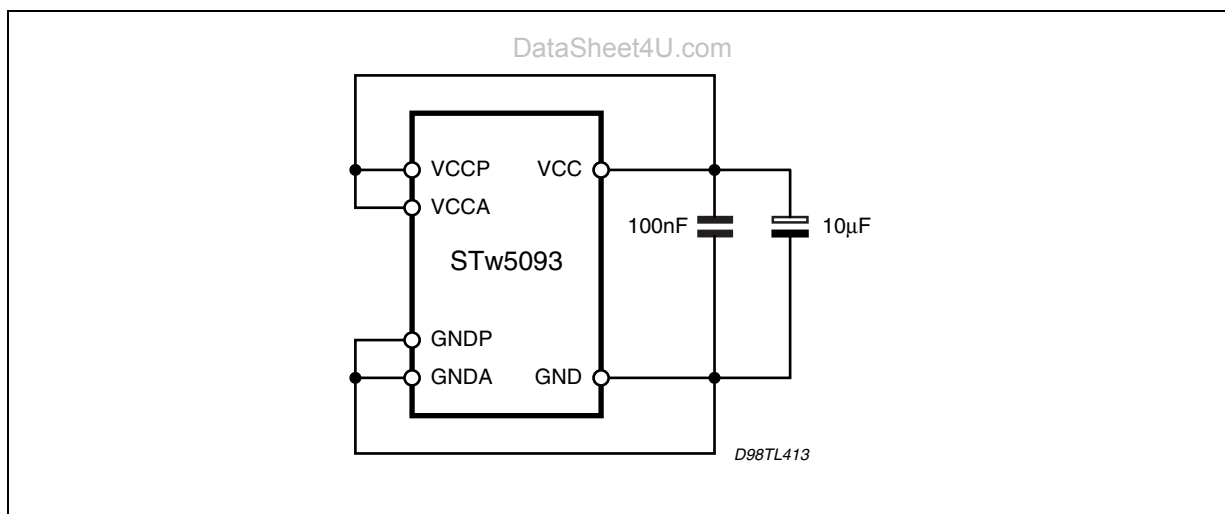
STw5093**POWER SUPPLY NOTES**

Two different strategies can be used to minimize power supply noise/interference.

- a) Recommended strategy: keep analog and digital power supply rails separate. This requires to use two sets of capacitors, one from AVCC to AGND and the other from DVCC to DGND.

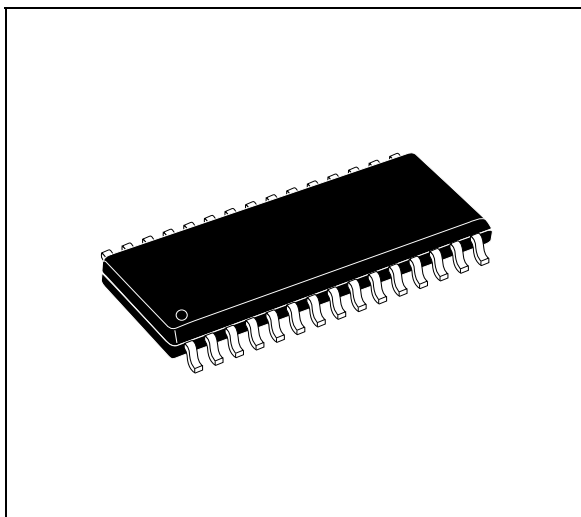
Figure 10.

- b) Low cost strategy: tie analog and digital power supplies together as close as possible to GND and VCC pins. This allows to use only one set of capacitors between VCC and GND.

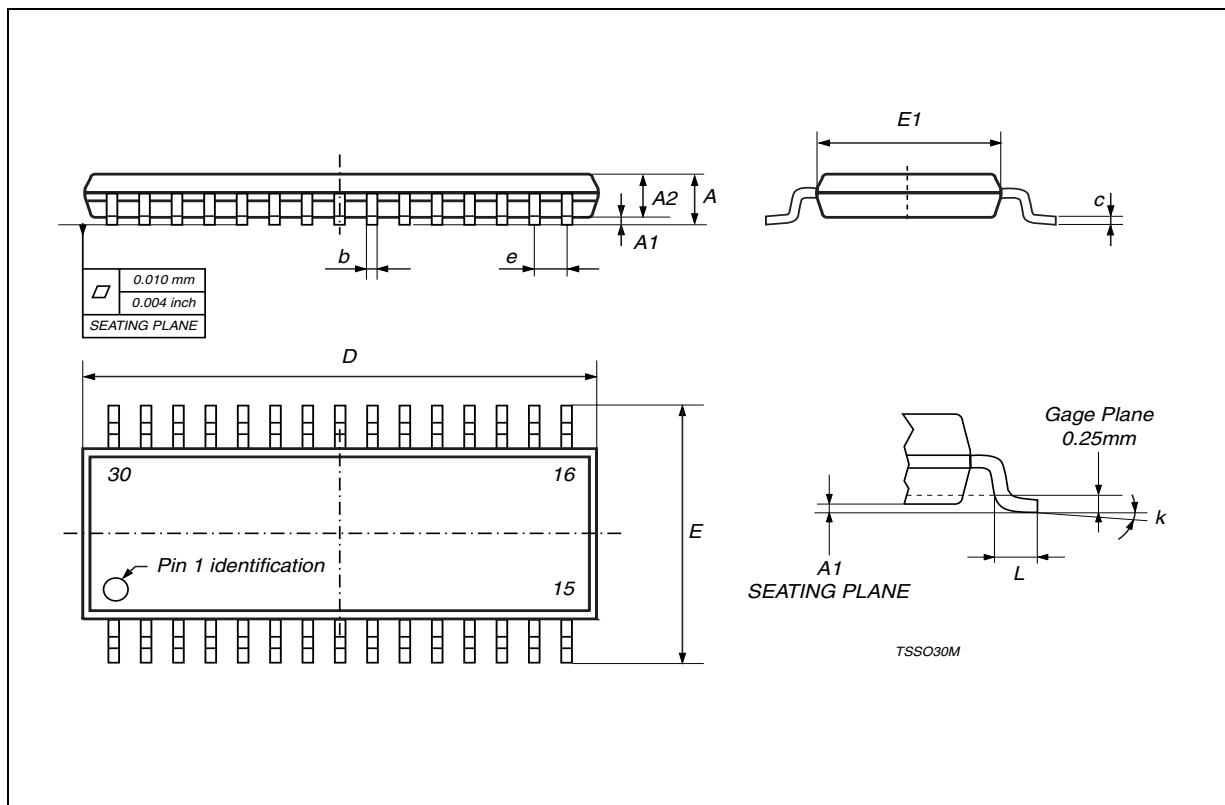
Figure 11.

| DIM. | mm | | | inch | | |
|------|---------------------|------|------|-------|--------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | | | 1.10 | | | 0.043 |
| A1 | 0.05 | | 0.15 | 0.002 | | 0.006 |
| A2 | 0.85 | 0.90 | 0.95 | 0.033 | 0.035 | 0.037 |
| b | 0.17 | | 0.27 | 0.007 | | 0.011 |
| c | 0.09 | | 0.20 | 0.004 | | 0.008 |
| D | 7.70 | 7.80 | 7.90 | 0.303 | 0.307 | 0.311 |
| E | | 6.40 | | | 0.252 | |
| e | | 0.50 | | | 0.0197 | |
| E1 | 4.30 | 4.40 | 4.50 | 0.169 | 0.173 | 0.177 |
| L | 0.50 | 0.60 | 0.70 | 0.020 | 0.024 | 0.028 |
| K | 0° (min.) 8° (max.) | | | | | |

OUTLINE AND MECHANICAL DATA



TSSOP30 (Thin Shrink)



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