

TOSHIBA**TB1230AN**

TENTATIVE

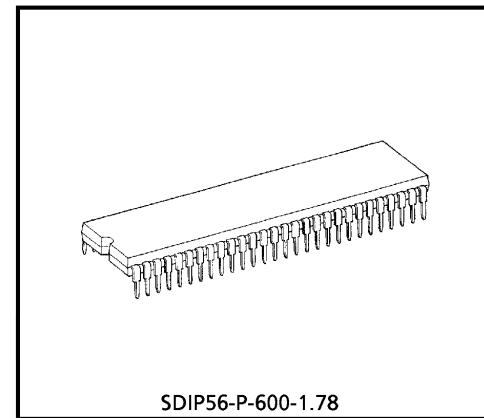
TOSHIBA Bi-CMOS INTEGRATED CIRCUIT SILICON MONOLITHIC

T B 1 2 3 0 A N**VIDEO, CHROMA AND SYNCHRONIZING SIGNALS PROCESSING IC FOR
PAL / NTSC SYSTEM COLOR TV**

TB1230AN that is a signal processing IC for the PAL / NTSC color TV system integrates video, chroma and synchronizing signal processing circuits together in a 56-pin shrink DIP plastic package.

TB1230AN incorporates a high performance picture quality compensation circuit in the video section, an automatic PAL / NTSC discrimination circuit in the chroma section, and an automatic 50 / 60Hz discrimination circuit in the synchronizing section. Besides a crystal oscillator that internally generates 4.43MHz, 3.58MHz and M / N-PAL clock signals for color demodulation, there is a horizontal PLL circuit built in the IC. The PAL demodulation circuit which is an adjustment-free circuit incorporates a 1H DL circuit inside for operating the base band signal processing system.

Also, TB1230AN makes it possible to set or control various functions through the built-in I²C bus line.



SDIP56-P-600-1.78

Weight : 5.55g (Typ.)

FEATURES

Video section

- Built-in trap filter
- Black expansion circuit
- Variable DC regeneration rate
- Y delay line
- Sharpness control by aperture control
- γ correction
- VSM output

Chroma section

- Built-in 1H Delay circuit
- PAL base band demodulation system
- One crystal color demodulation circuit (4.43MHz, 3.58MHz, M / N-PAL)
- Automatic system discrimination, system forced mode
- 1H delay line also serves as comb filter in NTSC demodulation
- Built-in band-pass filter
- Color limiter circuit
- Fsc output

Synchronizing deflecting section

- Built-in horizontal VCO resonator
- Adjustment-free horizontal / vertical oscillation by count-down circuit
- Double AFC circuit
- Vertical frequency automatic discrimination circuit
- Horizontal / vertical holding adjustment
- Vertical ramp output
- Vertical amplitude adjustment
- Vertical linearity / S-shaped curve adjustment
- SCP (Sand Castle Pulse) output

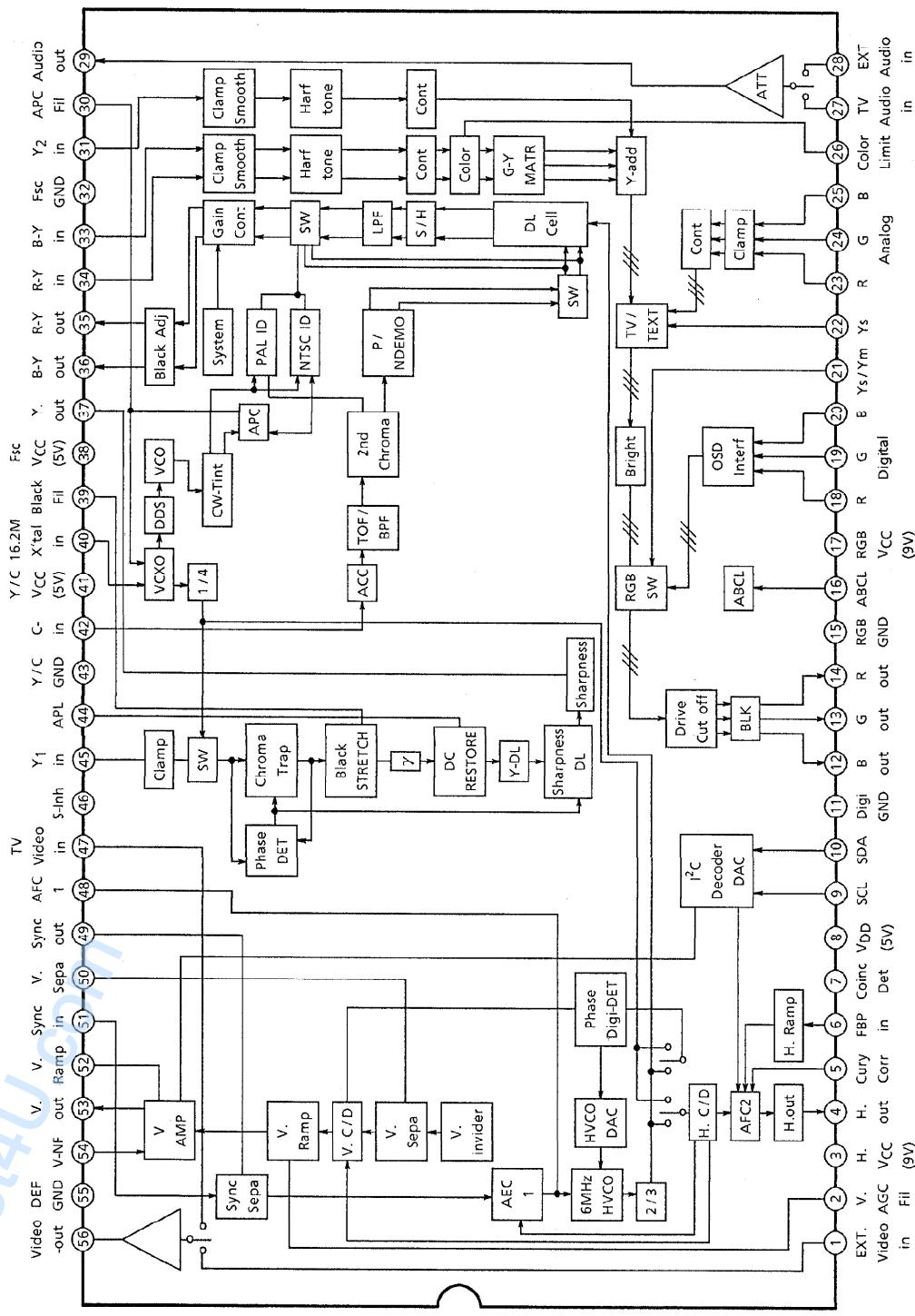
Text section

- Linear RGB input
- OSD RGB input
- Cut / off-drive adjustment
- RGB primary signal output

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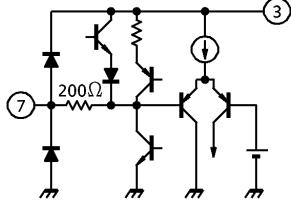
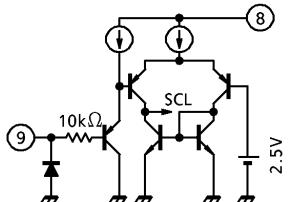
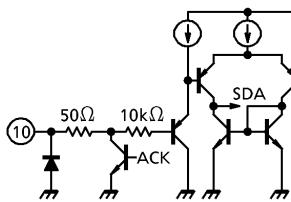
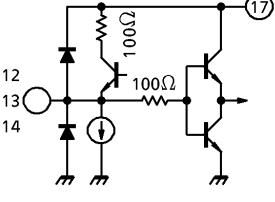
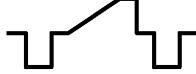
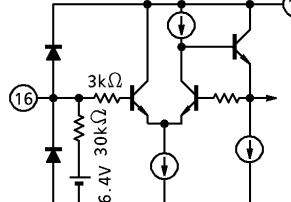
BLOCK DIAGRAM

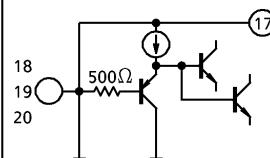
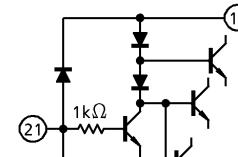
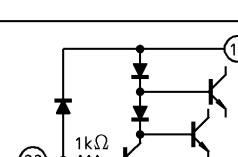
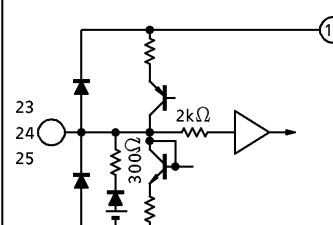
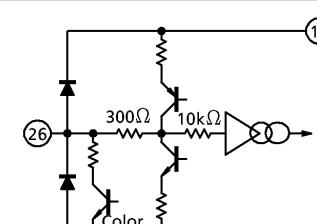
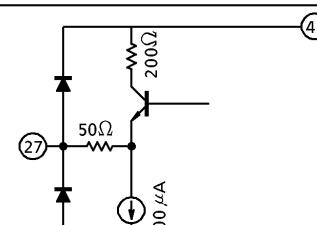


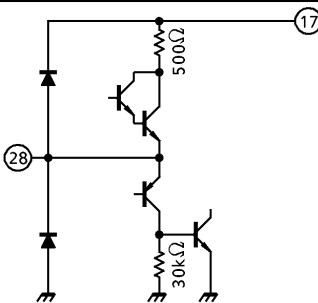
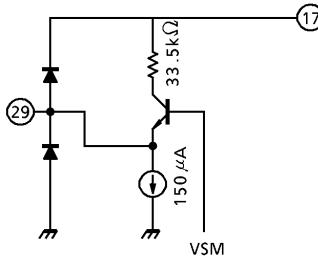
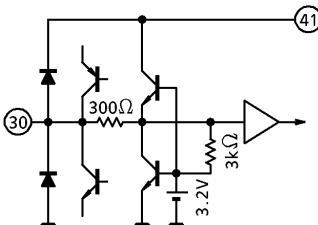
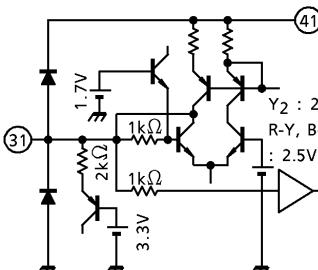
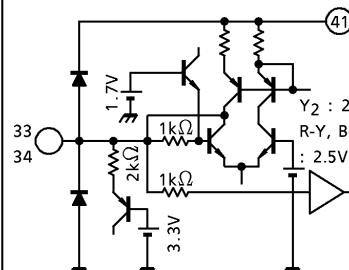
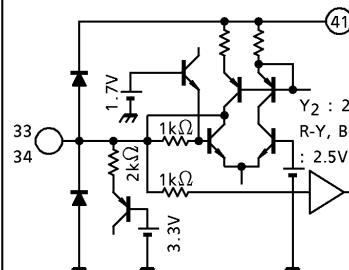
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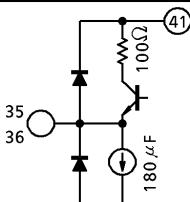
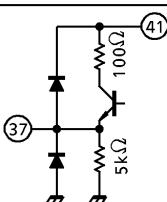
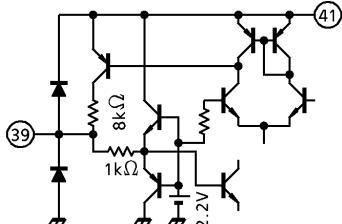
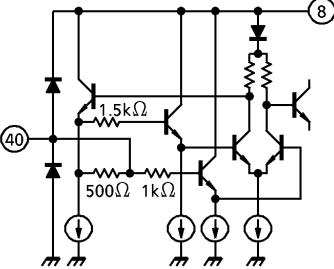
TERMINAL FUNCTIONS

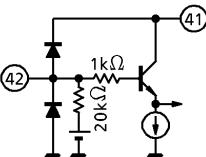
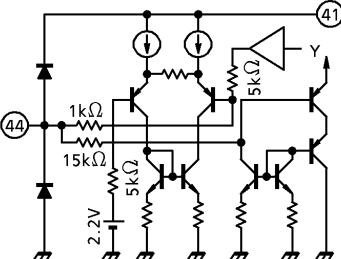
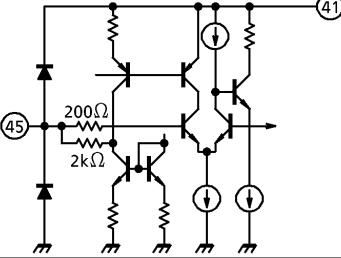
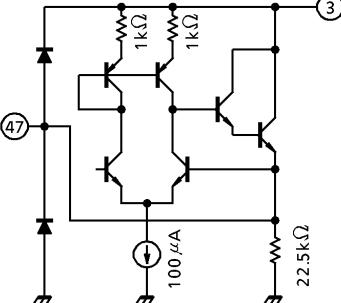
PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
1	SCP OUTPUT	Output terminal of Sand Castle Pulse. (SCP) To connect drive resistor for SCP.		
2	V-AGC	Controls pin 52 to maintain a uniform V-ramp output. Connect a current smoothing capacitor to this pin.		—
3	H-VCC (9V)	V _{CC} for the DEF block (deflecting system). Connect 9V (Typ.) to this pin.	—	—
4	Horizontal Output	Horizontal output terminal.		
5	Picture Distortion Correction	Corrects picture distortion in high voltage variation. Input AC component of high voltage variation. For inactivating the picture distortion correction function, connect 0.01μF capacitor between this pin and GND.		4.5V at Open
6	FBP Input	FBP input for generating horizontal AFC2 detection pulse and horizontal blanking pulse. The threshold of Horizontal AFC2 detection is set H.VCC-2Vf ($V_f \approx 0.75V$). Confirming the power supply voltage, determine the high level of FBP.		

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
7	Coincident Det.	To connect filter for detecting presence of H. synchronizing signal or V. synchronizing signal.		—
8	V _{DD} (5V)	V _{DD} terminal of the LOGIC block. Connect 5V (Typ.) to this pin.	—	—
9	SCL	SCL terminal of I ² C bus.		—
10	SDA	SDA terminal of I ² C bus.		—
11	Digital GND	Grounding terminal of LOGIC block.	—	—
12	B Output			
13	G Output	R, G, B output terminals.		
14	R Output			
15	TEXT GND	Grounding terminal of TEXT block.	—	—
16	ABCL	External unicolor brightness control terminal. Sensitivity and start point of ABL can be set through the bus.		6.4V at Open
17	RGB-V _{CC} (9V)	V _{CC} terminal of TEXT block. Connect 9V (Typ.) to this pin.	—	—

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
18	Digital R Input	Input terminals of digital R, G, B signals. Input DC directly to these pins.		OSD — 3.0V TEXT — 2.0V — GND
19	Digital G Input			
20	Digital B Input	OSD or TEXT signal can be input to these pins.		
21	Digital YS / YM	Selector switch of halftone / internal RGB signal / digital RGB (pins 18, 19, 20).		OSD — 3.0V TEXT — 2.0V H.T. — 1.0V TV — GND
22	Analog YS	Selector switch of internal RGB signal or analog RGB (pins 23, 24, 25).		Analog RGB — 0.5V TV — GND
23	Analog R Input	Analog R, G, B input terminals. Input signal through the clamping capacitor.		Standard input level : 0.5V _{p-p} (100 IRE). 100IRE = 0.5V _{p-p} 4.6V — GND
24	Analog G Input			
25	Analog B Input			
26	Color Limiter	To connect filter for detecting color limit.		—
27	FSC Output	Output terminal of FSC.		3.58MHz Other 500mV _{p-p}

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
28	1Bit DAC Output Terminal	Enable to change slave address to 8Ah by a connecting V_{CC} with this terminal.		4.5V (Date : (1)) 2.0V (Date : (0))
29	VSM Output Terminal	Power output the signal that is primary differentiated Y signal. Enable to change output amplifier and phase by the Bus.		—
30	APC Filter	To connect APC filter for chroma demodulation.		DC 3.2V
31	Y ₂ Input	Input terminal of processed Y signal. Input Y signal through clamping capacitor. Standard input level : 0.7V _{p-p}		0.7V _{p-p} 2.0V GND
32	Fsc GND	Grounding terminal of VCXO block. Insert a decoupling capacitor between this pin and pin 38 (Fsc V _{DD}) at the shortest distance from both.	—	—
33	B-Y Input	Input terminal of B-Y or R-Y signal. Input signal through a clamping capacitor.		DC 2.5V
34	R-Y Input			AC B-Y : 650mV _{p-p} R-Y : 510mV _{p-p} (with input of PAL-75% color bar signal)

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
35	R-Y Output	Output terminal of demodulated R-Y or B-Y signal. There is an LPF for removing carrier built in this pin.		DC 1.9V AC B-Y : 650mV _{p-p} R-Y : 510mV _{p-p} (with input of PAL-75% color bar signal)
36	B-Y Output			
37	Y Output	Output terminal of processed Y signal. Standard output level : 0.7V _{p-p}		0.7V _{p-p} 2.3V GND
38	Fsc VDD	V _{DD} terminal of V _{DSS} block. Insert a decoupling capacitor between this pin and pin 32 (Fsc GND) at the shortest distance from both. If decoupling capacitor is inserted at a distance from the pins, it may cause spurious deterioration.		—
39	Black Stretch	To connect filter for controlling black expansion gain of the black expansion circuit. Black expansion gain is determined by voltage of this pin.		DC 1.6V
40	16.2MHz X'tal	To connect 16.2MHz crystal clock for generating sub-carrier. Lowest resonance frequency (f_0) of the crystal oscillation can be varied by changing DC capacity. Adjust f_0 of the oscillation frequency with the board pattern.		DC 4.1V

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
41	Y/C V _{CC} (5V)	V _{CC} terminal of Y/C signal processing block.	—	—
42	Chroma Input	Chroma signal input terminal. Input negative 1.0V _{p-p} sync composite video signal to this pin through a coupling capacitor.		DC 2.4V AC : 300mV _{p-p} burst
43	Y/C GND	Grounding terminal of Y/C signal processing block.	—	—
44	APL	To connect filter for DC regeneration compensation. Y signal after black expansion can be monitored by opening this pin.		DC 2.2V
45	Y ₁ Input	Input terminal of Y signal. Input negative 1.0V _{p-p} sync composite video signal to this pin through a clamping capacitor.		1.0V _{p-p} 2.2V GND
47	DC Output Terminal For V Centering	Enable to control output DC voltage by the bus.		DC 2.7~6.3V

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
48	AFC1 Filter	To connect filter for horizontal AFC1 detection. Horizontal frequency is determined by voltage of this pin.		DC 5.0V
49	Sync Output	Output terminal of synchronizing signal separated by sync separator circuit. Connect a pull-up resistor to this pin because it is an open-collector output type.		
50	V-Sepa.	To connect filter for vertical synchronizing separation.		DC 5.9V
51	Sync Input	Input terminal of synchronizing separator circuit. Input signal through a clamping capacitor to this pin. Negative 1.0V _{p-p} sync.		
52	V-Ramp	To connect filter for generating V-ramp waveform.		

PIN No.	PIN NAME	FUNCTION	INTERFACE CIRCUIT	INPUT / OUTPUT SIGNAL
53	Vertical Output	Output terminal of vertical ramp signal.		
54	V-NF	Input terminal of vertical NF signal.		
55	DEF GND	Grounding terminal of DEF (deflection) block.	—	—
56	V BLK Output	Output terminal of V blanking		

BUS CONTROL MAP
WRITE DATA
Slave address : 88H

BLOCK	SUB ADDR	MSB 7	6	5	4	3	2	1	LSB 0	PRESET
	00					Uni-Color			1 0 0 0 0 0 0 0 0 0	
	01					BRIGHT			1 0 0 0 0 0 0 0 0 0	
	02					COLOR			1 0 0 0 0 0 0 0 0 0	
VIDEO / TEXT	03	AV SW				TINT			0 1 0 0 0 0 0 0 0 0	
	04	P / N KIL	ND SW			SHARPNESS			0 0 1 0 0 0 0 0 0 0	
	05	DTrp-SW	R-Mon	B-Mon		Y SUB CONTRAST			1 0 0 1 0 0 0 0 0 0	
	06					RGB CONTRAST			1 0 0 0 0 0 0 0 0 0	
A ATT	07	A MUTE				Audio-ATT Gain			1 0 0 0 0 0 0 0 0 0	
VIDEO / TEXT	08	Y Y	WPL SW	0	BLUE BACK MODE		Y-DL SW		0 0 0 0 0 1 0 0 0 0	
	09					G DRIVE GAIN			1 0 0 0 0 0 0 0 0 0	
	0A					B DRIVE GAIN			1 0 0 0 0 0 0 0 0 0	
DEF	0B			HORIZONTAL POSITION		AFC MODE	H-CK SW		1 0 0 0 0 0 0 0 0 1	
	0C					R CUT OFF			0 0 0 0 0 0 0 0 0 0	
	0D					G CUT OFF			0 0 0 0 0 0 0 0 0 0	
TEXT (P / N)	0E					B CUT OFF			0 0 0 0 0 0 0 0 0 0	
	0F	B. S. OFF	C-TRAP	OFST SW	C-TOF	P / N GP	CLL SW	WBK SW	WMUT SW	0 0 0 0 0 0 0 0 0 0
SYSTEM	10	1	358 Trap	F-B / W		Xtal MODE			COLOR SYSTEM	0 0 0 0 0 0 0 0 0 0
	11			R-Y BLACK OFFSET			B-Y BLACK OFFSET			1 0 0 0 1 0 0 0 0 0
P/N	12		CLL LEVEL		PN CD ATT		TOF Q	TOF FO		1 0 0 1 0 1 0 1 0 0
Vi/C	13	V-MODE	*	*	*	C-TRAP Q		C-TRAP FO		1 0 1 1 0 1 0 1 0
VIDEO (DEF)	14		BLACK STRETCH POINT			DC TRAN RATE		APA-CON FO / SW		1 0 0 0 0 0 1 0 0 0
	15		ABL POINT			ABL GAIN		HALF TONE SW		0 0 0 0 0 0 0 0 0 0
	16		H BLK PHASE		V FREQ			V OUT PHASE		0 0 0 0 0 0 0 0 0 0
GEOME TRY	17			V-AMPLITUDE						
	18	*	*	*	*	*	*	COINCIDENT DET		1 0 0 0 0 0 1 0 0 0
	19			V S-CORRECTION				DRG SW		1 0 0 0 0 0 0 0 0 0
	1A			V LINEARITY		V-CD MD	DRV CNT	VAGC SP		0 0 0 0 0 0 0 0 0 1
DEF-V	1B	MUTE MODE				WIDE V-BLK START PHASE				0 1 1 1 1 1 1 1 1 1
	1C	BLK SW				WIDE V-BLK STOP PHASE				0 0 0 0 0 0 0 0 0 0
	1D	NOISE DET LEVEL				WIDE P-MUTE START PHASE				1 0 1 1 1 1 1 1 1 1
	1E	N COMB				WIDE P-MUTE STOP PHASE				0 0 0 0 0 0 0 0 0 0

(Note) * : Data is ignored.

READ-IN DATA

Slave address : 89H (Pin28-High : 8BH)

	MSB 7	6	5	4	3	2	1	LSB 0
00	PORES	COLOR SYSTEM		X'tal	V-FREQ	V-STD	N-DET	
01	LOCK	RGBOUT	Y ₁ -IN	UV-IN	Y ₂ -IN	H	V	V-GUARD

BUS CONTROL FUNCTION**WRITE FUNCTION**

ITEM	DESCRIPTION	NUMBER OF BITS	VARIABLE RANGE	PRESET VALUE
UNI-COLOR	—	8bit	-18dB~0dB	80h MAX - 5.0dB
BRIGHT	—	8bit	-1V~1V	80h 0V
COLOR	—	8bit	~0dB	80h - 6dB
TINT	—	7bit	-45°~45°	40h 0°
P/N KIL	P/N KILLER sensitivity control	1bit	Normal / Low	00h NORMAL
SHARPNESS	—	6bit	-6dB~12dB	20h +3dB
DTrp-SW	Trap ON/OFF	1bit	ON/OFF	01h OFF
R-Mon	TEXT-11 dB pre-amplification UV output	1bit	Normal / Monitor	00h Normal
B-Mon	(Pin 35 : Bo, Pin 36 : Ro)	1bit	Normal / Monitor	00h Normal
Y SUB CONTRAST	—	5bit	-3dB~+3dB	10h 0dB
RGB-CONTRAST	EXT RGB UNI-COLOR control	8bit	-18dB~0dB	80h MAX - 5.0dB
Y _γ	γ ON/OFF	1bit	OFF / 95 IRE	00h ON
WPL SW	White peak limit level	1bit	130 IRE / OFF	00h 130 IRE
BLUE BACK MODE	Luminance selector switch	2bit	IRE ; OFF, 40, 50, 50	00h OFF
Y-DL SW	Y-DL TIME (28, 33, 38, 43, 48)	3bit	280~480ns after Y IN	04h 480ns
G DRIVE GAIN	—	8bit	-5dB~3dB	80h 0dB
B DRIVE GAIN	—	8bit	-5dB~3dB	80h 0dB
HORIZONTAL POSITION	Horizontal position adjustment	5bit	-3μs~+3μs	10h 0μs

ITEM	DESCRIPTION	NUMBER OF BITS	VARIABLE RANGE	PRESET VALUE
AFC MODE	AFC1 detection sensitivity selector	2bit	dB ; AUTO, 0, -10, -10	00h AUTO
H-CK SW	HOUT generation clock selector	1bit	384fh-VCO, FSC-VCXO	01h FSC-VCXO
R CUT OFF	—	8bit	-0.5~0.5V	00h -0.5V
G CUT OFF	—	8bit	-0.5~0.5V	00h -0.5V
B CUT OFF	—	8bit	-0.5~0.5V	00h -0.5V
B. S. OFF	Black expansion ON/OFF	1bit	ON/OFF	00h ON
C-TRAP	Chroma Trap ON/OFF SW	1bit	ON/OFF	00h ON
FST SW	Adjustment of Black level of color difference	1bit	OFF/ON	00h OFF
C-TOF	P/N TOF ON/OFF SW	1bit	ON/OFF	00h ON
P/N GP	PAL GATE position	1bit	Standard / 0.5μs delay	00h Standard
CL-L SW	COLOR LIMIT ON/OFF	1bit	ON/OFF	00h ON
WBLK SW	WIDE V-BLK ON/OFF	1bit	OFF/ON	00h OFF
WMUT SW	WIDE Picture-MUTE ON/OFF	1bit	OFF/ON	00h OFF
3.58 Trap	C Trap-f ₀ , force 3.58MHz switch	1bit	AUTO/Forced 3.58MHz	00h AUTO
F-B/W	Force B/W switch	1bit	AUTO/Forced B/W	00h AUTO
X'tal MODE	APC oscillation frequency selector switch	3bit	000 ; European system AUTO, 001 ; 3N 010 ; 4P, 011 ; 4P (N inhibited) 100 ; S.American system AUTO, 101 ; 3N, 110 ; MP, 111 ; NP	00h European system AUTO
COLOR SYSTEM	Chroma system selection	2bit	AUTO, PAL, NTSC	00h AUTO
R-Y BLACK OFFSET	R-Y color difference output black offset adjustment	4bit	-24~21mV STEP 3mV	08h 0mV
B-Y BLACK OFFSET	B-Y color difference output black offset adjustment	4bit	-24~21mV STEP 3mV	08h 0mV
CLL LEVEL	Color limit level adjustment	2bit	91, 100, 108, 116%	02h 108%

(Note) 3N ; 3.58-NTSC, 4P ; 4.43-PAL, MP ; M-PAL, NP ; N-PAL
 European system auto ; 4.43-PAL, 4.43-NTSC, 3.58-NTSC
 S. American system auto ; 3.58-NTSC, M-PAL, N-PAL

ITEM	DESCRIPTION	NUMBER OF BITS	VARIABLE RANGE	PRESET VALUE
PN CD ATT	P/N color difference amplitude adjustment	2bit	+1~-2dB STEP 1dB	01h 0dB
TOF Q	TOF Q adjustment	2bit	1.0, 1.5, 2.0, 2.5	02h 2.0
TOF F ₀	TOF f ₀ adjustment	2bit	kHz ; 0, 500, 600, 700	02h 600kHz
VSM PHASE	VSM output phase	2bit	+20ns, +20ns, 0ns, 0ns	02h 0ns
VSM GAIN	VSM output gain	2bit	0dB, 0dB, -6dB, OFF	03h OFF
C-TRAP Q	Chroma trap Q control	2bit	1.0, 1.5, 2.0, 2.5	02h 2.0
C-TRAP F ₀	Chroma trap f ₀ control	2bit	kHz ; -100, -50, 0, +50	02h 0kHz
BLACK STRETCH POI	Black expansion start point setting	3bit	28~70% IRE × 0.4	05h 56% IRE
DC TRAN RATE	Direct transmission compensation degree selection	3bit	100~130% APL	00h 100%
APA-CON PEAK F ₀	Sharpness peak frequency selection	2bit	kHz ; 2.5, 3.1, 4.2, OFF	02h 4.2kHz
ABL POINT	ABL detection voltage	3bit	ABL point ; 6.5V~5.9V	00h 6.5V
ABL GAIN	ABL sensitivity	3bit	Brightness ; 0~-2V	00h 0V
HALF TONE SW	Halftone gain selection	2bit	-3dB, -6dB, OFF, OFF	00h -3dB
H BLK PHASE	Horizontal blanking end position	3bit	0~3.5μs step 0.5μs	00h 0μs
V FREQ	Vertical frequency	2bit	AUTO, 60Hz, Forced 60, 50, 60	00h AUTO
V OUT PHASE	Vertical position adjustment	3bit	0~7H STEP 1H	00h 0H
V-AMPLITUDE	Vertical amplitude selection	7bit	-50~50%	40h 0%
1bit DAC	1bit DAC output	1bit	LOW, HIGH	00h LOW
V CENTERING	V Centering	6bit	1~4V	20h 2.5V
COINCIDENT MODE	Discriminator output signal selection	2bit	00 ; DSYNC 01 ; DSYNC × AFC 10 ; Field counting 11 ; VP is present.	02h Field counting
V S-CORRECTION	Vertical S-curve correction	7bit	Reverse S-curve, S-curve	40h —
V-MODE	Force Sync Mode Selection	1bit	TELETEXT / Normal	01h Normal
DRG SW	Drive reference axis selection	1bit	R / G	00h R
V LINEARITY	Vertical linearity correction	5bit	(one side)	00h —
ND SW	Noise Det SW	1bit	Normal, Low	00h Normal
V-CD MD	Vertical count-down mode selection	1bit	AUTO / Force synchronization	00h AUTO

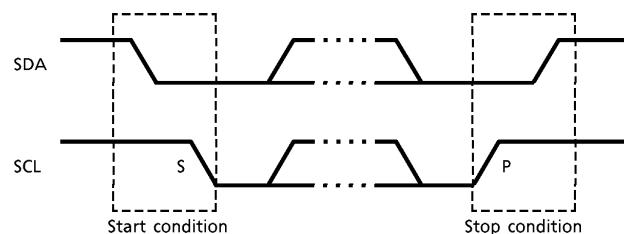
ITEM	DESCRIPTION	NUMBER OF BITS	VARIABLE RANGE	PRESET VALUE
DRV CNT	All drive gains forced centering switch	1bit	OFF / Force centering	00h OFF
VAGC SP	Vertical ramp time constant selection	1bit	Normal / High speed	01h High speed
MUTE MODE	OFF, RGB mute, Y mute, transverse	2bit	OFF, RGB, Y, Transverse	01h RGB
WIDE V-BLK START PH	Vertical pre-position selection	6bit	- 64~ - 1H STEP 1H	3Fh - 1H
BLK SW	Blanking ON / OFF	1bit	ON / OFF	00h ON
WIDE V-BLK STOP PH	Vertical post-position selection	7bit	0~128H STEP 1H	00h 0H
NOISE DET LEVEL	Noise detection level selection	2bit	ND SW Normal : 0.15, 0.125, 0.1, 0.075 Low : 0.5, 0.475, 0.45, 0.425	02h 0.1
WIDE P-MUTE START PH	Video mute pre-position selection	6bit	- 64~ - 1H STEP 1H	3Fh - 1H
N COMB	1H addition selection	1bit	OFF / ADD	00h OFF
WIDE P-MUTE STOP PH	Video mute post-position selection	7bit	0~128H STEP 1H	00h 0H

READ-IN FUNCTION

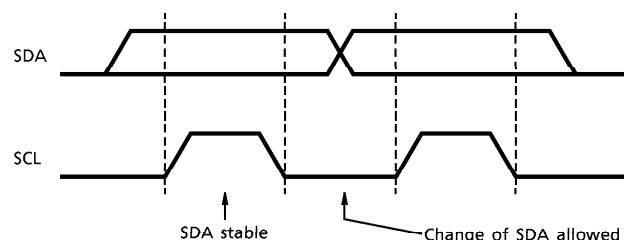
ITEM	DESCRIPTION	NUMBER OF BITS
PONRES	0 : POR cancel, 1 : POR ON	1bit
COLOR SYSTEM	00 : B / W, 01 : PAL 10 : NTSC, 11 :	2bit
X'tal	00 : 4.433619MHz 01 : 3.579545MHz 10 : 3.575611MHz (M-PAL) 11 : 3.582056MHz (N-PAL)	2bit
V-FREQ	0 : 50Hz, 1 : 60Hz	1bit
V-STD	0 : NON-STD, 1 : STD	1bit
N-DET	0 : Low, 1 : High	1bit
LOCK	0 : UN-LOCK, 1 : LOCK	1bit
RGBOUT, Y ₁ -IN UV-IN, Y ₂ -IN, H, V	Self-diagnosis 0 : NG, 1 : OK	1bit each
V-GUARD	Detection of breaking neck 0 : Abnormal, 1 : Normal	1bit

DATA TRANSFER FORMAT VIA I²C BUS

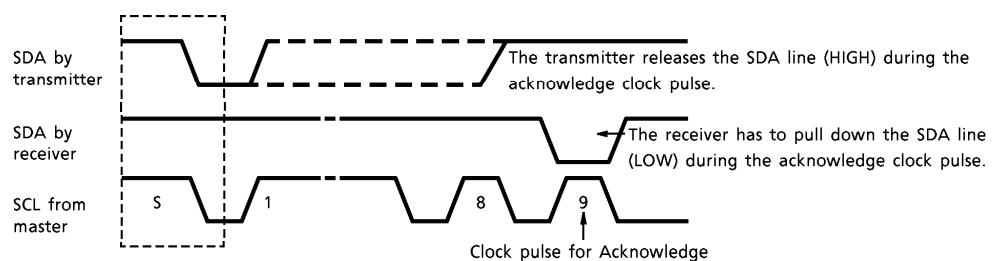
Start and stop condition

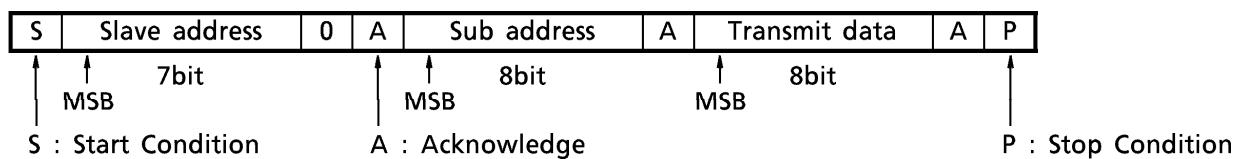
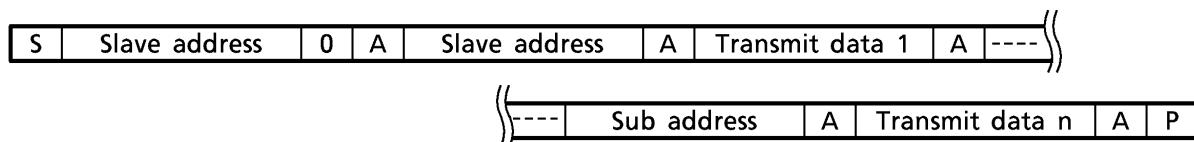
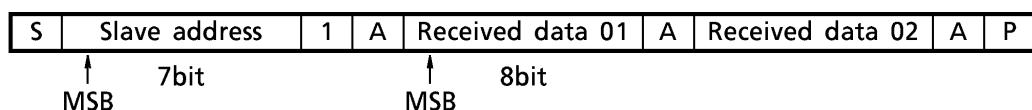


Bit transfer



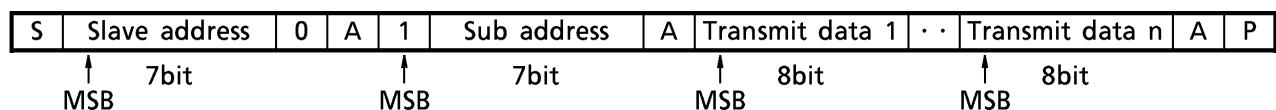
Acknowledge



Data transmit format 1**Data transmit format 2****Data receive format**

At the moment of the first acknowledge, the master transmitter becomes a master receiver and the slave receiver becomes a slave transmitter. This acknowledge is still generated by the slave.

The STOP condition is generated by the master.

Optional data transmit format : Automatic increment mode

In this transmission method, data is set on automatically incremented sub-address from the specified sub-address.

Purchase of TOSHIBA I²C components conveys a license under the Philips I²C Patent Rights to use these components in an I²C system, provided that the system conforms to the I²C Standard Specification as defined by Philips.

MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Supply Voltage	V _{CCMAX}	12	V
Permissible Loss	P _{DMAX}	2190 (Note)	mW
Power Consumption Declining Degree	1 / Q _{ja}	17.52	mW / °C
Input Terminal Voltage	V _{in}	GND - 0.3 ~ V _{CC} + 0.3	V
Input Signal Voltage	e _{in}	7	V _{p-p}
Operating Temperature	T _{opr}	-20 ~ 65	°C
Conserving Temperature	T _{stg}	-55 ~ 150	°C

(Note) In the condition that IC is actually mounted. See the diagram below.

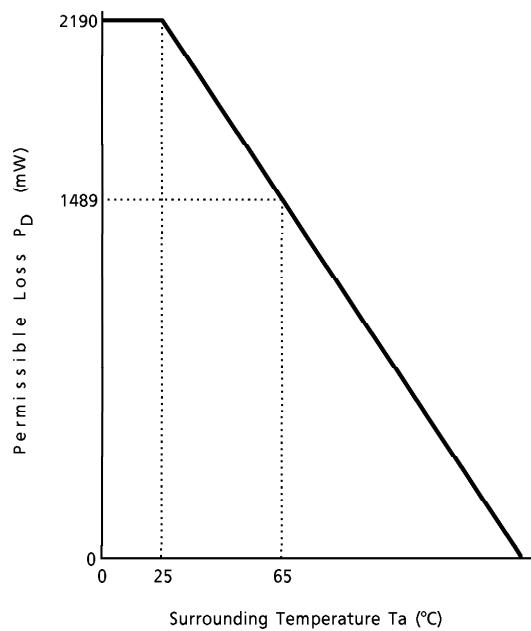


Fig. Power consumption declining curve relative to temperature change

RECOMMENDED OPERATING CONDITION

CHARACTERISTIC	DESCRIPTION	MIN.	TYP.	MAX.	UNIT
Supply Voltage	Pin 3, pin 17	8.50	9.0	9.25	V
	Pin 8, pin 38, pin 41	4.75	5.0	5.25	
Video Input Level	100% white, negative sync	0.9	1.0	1.1	V _{p-p}
Chroma Input Level		0.9	1.0	1.1	
Sync Input Level		0.9	1.0	2.2	
FBP Width	—	11	12	13	μs
Incoming FBP Current (Note)	—	—	—	1.5	mA
H. Output Current	—	—	—	1.0	
RGB Output Current	—	—	—	2.0	V
Analog RGB Input Level	—	—	—	0.7	
OSD RGB Input Level	In TEXT input	0.7	1.0	1.3	
	In OSD input	—	4.2	5.0	
Incoming Current to Pin 49	Sync-out	—	0.5	1.0	mA

(Note) The threshold of horizontal AFC2 detection is set H.V_{CC}-2V_f (V_f≈0.75V).
Confirming the power supply voltage, determine the high level of FBP.

ELECTRICAL CHARACTERISTIC

(Unless otherwise specified, H, RGB V_{CC}=0V, V_{DD}, Fsc V_{DD},
Y/C V_{CC}=5V, Ta = 25 ± 3°C)

CURRENT CONSUMPTION

PIN No.	CHARACTERISTIC	SYMBOL	TEST CIRCUIT	MIN.	TYP.	MAX.	UNIT
3	H.V _{CC} (9V)	I _{CC1}	—	16.0	19.0	23.5	mA
8	V _{DD} (5V)	I _{CC2}	—	8.8	11.0	14.0	
17	RGB V _{CC} (9V)	I _{CC3}	—	25.0	31.5	39.0	
38	Fsc V _{CC} (5V)	I _{CC4}	—	6.8	8.5	11.0	
41	Y/C V _{CC} (9V)	I _{CC5}	—	80	100	130	

TERMINAL VOLTAGE

PIN No.	PIN NAME	SYMBOL	TEST CIRCUIT	MIN.	TYP.	MAX.	UNIT
16	ABCL	V ₁₆	—	5.9	6.4	6.9	V
18	OSD R Input	V ₁₈	—	—	0	0.3	V
19	OSD G Input	V ₁₉	—	—	0	0.3	V
20	OSD B Input	V ₂₀	—	—	0	0.3	V
21	Digital Ys	V ₂₁	—	—	0	0.3	V
22	Analog Ys	V ₂₂	—	—	0	0.3	V
23	Analog R Input	V ₂₃	—	4.2	4.6	5.0	V
24	Analog G Input	V ₂₄	—	4.2	4.6	5.0	V
25	Analog B Input	V ₂₅	—	4.2	4.6	5.0	V
28	DAC	V ₂₈	—	1.7	2.0	2.3	V
31	Y ₂ Input	V ₃₁	—	1.7	2.0	2.3	V
33	B-Y Input	V ₃₃	—	2.2	2.5	2.8	V
34	R-Y Input	V ₃₄	—	2.2	2.5	2.8	V
35	R-Y Output	V ₃₅	—	1.5	1.9	2.3	V
36	B-Y Output	V ₃₆	—	1.5	1.9	2.3	V
37	Y ₁ Output	V ₃₇	—	1.9	2.3	2.7	V
40	16.2MHz X'tal Oscillation	V ₄₀	—	3.6	4.1	4.6	V
42	Chroma Input	V ₄₂	—	2.0	2.4	2.8	V
50	V-Sep.	V ₅₀	—	5.4	5.9	6.4	V

AC CHARACTERISTIC
Video section

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Y Input Pedestal Clamping Voltage	VYclp	—	(Note) Y ₁	2.0	2.2	2.4	V
Chroma Trap Frequency	ftr3	—	(Note) Y ₂	3.429	3.58	3.679	MHz
	ftr4	—		4.203	4.43	4.633	
Chroma Trap Attenuation (3.58MHz) (4.43MHz) (D-Trap)	Gtr3a	—	(Note) Y ₃	20	26	52	dB
	Gtr3f	—		20	26	52	
	Gtr4	—	(Note) Y ₄	18	26	52	
	Gtrs	—	(Note) Y ₅	90	95	99	
Y _γ Correction Point	γp	—	(Note) Y ₆	-2.6	-2.0	-1.3	dB
Y _γ Correction Curve	γc	—	(Note) Y ₇	15	20	25	kΩ
APL Terminal Output Impedance	Zo44	—	(Note) Y ₈	0.11	0.13	0.15	times
DC Transmission Compensation Amplifier Gain	Adrmax	—	(Note) Y ₉	0.44	0.06	0.08	
	Adrcnt	—		1.20	1.5	1.65	
Maximum Gain of Black Expansion Amplifier	Ake	—	(Note) Y ₁₀	65	77.5	80	IRE
Black Expansion Start Point	VBS9MX	—	(Note) Y ₁₁	55	62.5	70	
	VBS9CT	—		48	55.5	63	
	VBS9MN	—		35	42.5	50	
	VBS2MX	—		25	31.5	38	
	VBS2CT	—		19	25.5	32	
	VBS2MN	—		15	16	17	
Black Peak Detection Period (Horizontal)	TbpH	—	(Note) Y ₁₂	33	34	35	H
(Vertical)	TbpV	—		1.5	2.5	3.4	MHz
Picture Quality Control Peaking Frequency	fp25	—	(Note) Y ₁₃	1.9	3.1	4.3	
	fp31	—		3.0	4.2	5.4	
	fp42	—		12.0	14.5	17.0	dB
Picture Quality Control Maximum Characteristic	GS25MX	—	(Note) Y ₁₄	12.0	14.5	17.0	
	GS31MX	—		10.6	13.5	16.4	
	GS42MX	—		-22.0	-19.5	-17.0	
Picture Quality Control Minimum Characteristic	GS25MN	—	(Note) Y ₁₅	-22.0	-19.5	-17.0	
	GS31MN	—		-19.5	-16.5	-13.5	
	GS42MN	—		6.0	8.5	11.0	
Picture Quality Control Center Characteristic	GS25CT	—	(Note) Y ₁₆	6.0	8.5	11.0	
	GS31CT	—		4.6	7.5	10.4	
	GS42CT	—		-1.0	0	1.6	
Y Signal Gain	Gy	—	(Note) Y ₁₇	-6.5	0	1.0	V
Y Signal Frequency Characteristic	Gfy	—	(Note) Y ₁₈	0.9	1.2	1.5	
Y Signal Maximum Input Range	Vyd	—	(Note) Y ₁₉				

Chroma section

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MIN.	UNIT
ACC Characteristic $f_o = 3.58$	3NeAT	—	(Note) C ₁	30	35	90	mV _{p-p}
	3NF1T	—		68	85	105	
	3NAT	—		0.9	1.0	1.1	times
	3NeAE	—		18	35	—	
	3NF1E	—		71	85	102	
	3NAE	—		0.9	1.0	1.1	
	4NeAT	—		18	35	—	mV _{p-p}
	4NF1T	—		71	85	102	
	4NAT	—		0.9	1.0	1.1	times
	4NeAE	—		18	35	—	
Band Pass Filter Characteristic $f_o = 3.58$	4NF1E	—		71	85	102	
	4NAE	—		0.9	1.0	1.1	
	3Nf _o 0	—	(Note) C ₂	3.43	3.579	3.73	MHz
	3Nf _o 500	—		3.93	4.079	4.23	
	3Nf _o 600	—		4.03	4.179	4.33	
	3Nf _o 700	—		4.13	4.279	4.43	
	4Nf _o 0	—		4.28	4.433	4.58	
	4Nf _o 500	—		4.78	4.933	4.58	
Band Pass Filter, -3dB Band Characteristic $f_o = 3.58$	4Nf _o 600	—		4.88	5.033	5.18	
	4Nf _o 700	—		4.98	5.133	5.28	
	f _o 0	—	(Note) C ₃	1.64	1.79	1.94	
	f _o 500	—		2.07	2.22	2.37	
	f _o 600	—		—	—	—	
	f _o 700	—		—	—	—	
	f _o 0	—		—	—	—	
	f _o 500	—		—	—	—	
Band Pass Filter, Q Characteristic Check $f_o = 3.58$	f _o 600	—		—	—	—	
	f _o 700	—		—	—	—	
	Q ₁	—	(Note) C ₄	—	3.58	—	
	Q _{1.5}	—		—	2.39	—	
	Q _{2.0}	—		1.64	1.79	1.94	
	Q _{2.5}	—		—	1.43	—	
	Q ₁	—		—	4.43	—	
	Q _{1.5}	—		—	2.95	—	
Band Pass Filter, Q Characteristic Check $f_o = 4.43$	Q _{2.0}	—		2.07	2.22	2.37	
	Q _{2.5}	—		—	1.77	—	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
1 / 2 f_c Trap Characteristic $f_o = 3.58$	f_{o0}	—	(Note) C ₅	1.45	1.60	1.75	MHz
	f_{o500}	—		1.70	1.85	2.00	
	f_{o600}	—		1.75	1.90	2.06	
	f_{o700}	—		1.80	1.95	2.10	
	f_{o0}	—		1.85	2.00	2.15	
	f_{o500}	—		2.00	2.15	2.30	
	f_{o600}	—		2.05	2.20	2.35	
	f_{o700}	—		2.10	2.25	2.40	
Tint Control Range ($f_o = 600\text{kHz}$)	$3N\Delta\theta 1$	—	(Note) C ₆	35.0	45.0	55.0	°
	$3N\Delta\theta 2$	—		- 55.0	- 45.0	- 35.0	
	$4N\Delta\theta 1$	—		35.0	45.0	55.0	
	$4N\Delta\theta 2$	—		70.0	90.0	110.0	
Tint Control Variable Range ($f_o = 600\text{kHz}$)	$3T\theta T_{in}$	—	(Note) C ₇	39	40	47	bit
	$3E\theta T_{in}$	—		73	80	87	Step
	$3N\Delta T_{in}$	—		39	40	47	bit
	$4T\theta T_{in}$	—		73	80	87	Step
	$4E\theta T_{in}$	—		350	500	1500	Hz
	$4N\Delta T_{in}$	—		- 350	- 500	- 1500	
APC Lead-In Range (Lead-In Range)	4.433PH	—	(Note) C ₉	350	500	1700	
	4.433PL	—		- 350	- 500	- 1700	
	3.579PH	—		400	500	1100	
	3.579PL	—		- 400	- 500	- 1100	
	4.433HH	—		400	500	1100	
	4.433HL	—		- 400	- 500	- 1100	
	3.579HH	—		400	500	1100	
	3.579HL	—		- 400	- 500	- 1100	
APC Control Sensitivity	$3.58\beta 3$	—	(Note) C ₁₀	1.50	2.2	2.90	—
	$4.43\beta 3$	—		1.70	2.4	3.10	
	M-PAL βM	—		1.50	2.2	2.90	
	N-PAL βN	—		—	—	—	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Killer Operation Input Level	3N-VTK1	—	(Note) C11	1.8	2.5	3.2	mV _{p-p}
	3N-VTC1	—		2.2	3.2	4.0	
	3N-VTK2	—		2.5	3.6	4.5	
	3N-VTC2	—		3.2	4.5	5.6	
	4N-VTK1	—		1.8	2.5	3.2	
	4N-VTC1	—		2.2	3.2	4.0	
	4N-VTK2	—		2.5	3.6	4.5	
	4N-VTC2	—		3.2	4.5	5.6	
	4P-VTK1	—		1.8	2.5	3.2	
	4P-VTC1	—		2.2	3.2	4.0	
	4P-VTK2	—		2.5	3.6	4.5	
	4P-VTC2	—		3.2	4.5	5.6	
	MP-VTK1	—		1.8	2.5	3.2	
	MP-VTC1	—		2.2	3.2	4.0	
	MP-VTK2	—		2.5	3.6	4.5	
	MP-VTC2	—		3.2	4.5	5.6	
	NP-VTK1	—		1.8	2.5	3.2	
	NP-VTC1	—		2.2	3.2	4.0	
	NP-VTK2	—		2.5	3.6	4.5	
	NP-VTC2	—		3.2	4.5	5.6	
Color Difference Output (Rainbow Color Bar)	3NeB-Y	—	(Note) C12	320	380	460	
	3NeR-Y	—		240	290	350	
	4NeB-Y	—		320	380	460	
	4NeR-Y	—		240	290	350	
	4PeB-Y	—		360	430	520	
	4PeR-Y	—		200	240	290	
(75% Color Bar)	4Peb-y	—		540	650	780	
	4Per-y	—		430	510	610	
Demodulation Relative Amplitude	3NGR / B	—	(Note) C13	0.69	0.77	0.86	times
	4NGR / B	—		0.70	0.77	0.85	
	4PGR / B	—		0.49	0.56	0.64	
Demodulation Relative Phase	3NθR-B	—	(Note) C14	85	93	100	°
	4NθR-B	—		87	93	99	
	4PθR-B	—		85	90	95	
Demodulation Output Residual Carrier	3N-SCB	—	(Note) C15	0	5	15	mV _{p-p}
	3N-SCR	—					
	4N-SCB	—					
	4N-SCR	—					

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Demodulation Output Residual Higher Harmonic	3N-HCB	—	(Note) C16	0	10	30	mV _{p-p}
	3N-HCR	—					
	4N-HCB	—					
	4N-HCR	—					
Color Difference Output ATT Check	B-Y - 1dB	—	(Note) C17	-1.20	-0.9	-0.60	dB
	B-Y - 2dB	—		-2.30	-1.7	-1.55	
	B-Y + 1dB	—		0.60	0.8	1.20	
16.2MHz Oscillation Frequency	ΔfoF	—	(Note) C18	-2.0	0	2.0	kHz
16.2MHz Oscillation Start Voltage	Vfon1	—	(Note) C19	3.0	3.2	3.4	V
f _{sc} Free-Run Frequency (3.58M)	3fr	—	(Note) C20	-100	50	200	Hz
	4fr	—		-125	25	175	
	Mfr	—		-140	10	160	
	Nfr	—					
f _{sc} Output Amplitude	4.43e27	—	(Note) C21	420	500	580	mV _{p-p}
	3.58e27	—					
f _{sc} Output DC Voltage	3.58eV27	—	—	2.6	2.9	3.2	V
	0th V27	—		1.6	1.9	2.2	

DEF section

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
H. Reference Frequency	FHVCO	—	(Note) DH1	5.95	6.0	6.10	MHz
H. Reference Oscillation Start Voltage	VSHVCO	—	(Note) DH2	2.3	2.6	2.9	V
H. Output Frequency 1	fH1	—	(Note) DH3	15.5	15.625	15.72	kHz
H. Output Frequency 2	fH2	—	(Note) DH4	15.62	15.734	15.84	
H. Output Duty 1	H _φ 1	—	(Note) DH5	39	41	43	%
H. Output Duty 2	H _φ 2	—	(Note) DH6	35	37	39	
H. Output Duty Switching Voltage 1	V5-1	—	(Note) DH7	1.2	1.5	1.8	V
H. Output Voltage	VHH	—	(Note) DH8	4.5	5.0	5.5	
	VHL	—		—	—	0.5	
H. Output Oscillation Start Voltage	VHS	—	(Note) DH9	—	5.0	—	μs
H. FBP Phase	φFBP	—	(Note) DH10	6.2	6.9	7.6	
H. Picture Position, Maximum	HSFTmax	—	(Note) DH11	17.7	18.4	19.1	
H. Picture Position, Minimum	HSFTmin	—	(Note) DH12	12.4	13.1	13.8	
H. Picture Position Control Range	ΔHSFT	—	(Note) DH13	4.5	5.3	6.1	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
H. Distortion Correction Control Range	ΔHCC	—	(Note) DH14	0.5	1.0	1.5	$\mu s/V$
H. BLK Phase	ϕBLK	—	(Note) DH15	6.2	6.9	7.6	μs
H. BLK Width, Minimum	BLKmin	—	(Note) DH16	9.8	10.5	11.3	
H. BLK Width, Maximum	BLKmax	—	(Note) DH17	13.2	14.0	14.7	
P/N-GP Start Phase 1	SPGP1	—	(Note) DH18	3.45	3.68	3.90	
P/N-GP Start Phase 2	SPGP2	—	(Note) DH19	3.95	4.18	4.40	
P/N-GP Gate Width 1	PGPW1	—	(Note) DH20	1.65	1.75	1.85	
P/N-GP Gate Width 2	PGPW2	—	(Note) DH21	1.70	1.75	1.85	
Noise Detection Level 1	NL1	—	(Note) DH22	0.15	0.2	0.25	V
Noise Detection Level 2	NL2	—	(Note) DH23	0.1	0.18	0.26	
Noise Detection Level 3	NL3	—	(Note) DH24	0.1	0.15	0.2	
Noise Detection Level 4	NL4	—	(Note) DH25	0.08	0.13	0.2	
V. Ramp Amplitude	Vramp	—	(Note) DV1	1.62	2.0	2.08	V_{p-p}
V. NF Maximum Amplitude	VNFmax	—	(Note) DV2	3.2	3.5	3.8	
V. NF Minimum Amplitude	VNFmin	—	(Note) DV3	0.8	1.0	1.2	
V. Amplification Degree	GVA	—	(Note) DV4	20	26	32	dB
V. Amplifier Max. Output	Vvmax	—	(Note) DV5	5.0	—	—	V
V. Amplifier Min. Output	Vvmin	—	(Note) DV6	0	—	1.5	
V. S-Curve Correction, Max. Correction Quantity	V _S	—	(Note) DV7	9	11	13	%
V. Reverse S-Curve Correction, Max. Correction Quantity	V _{SR}	—	(Note) DV8				
V. Linearity Max. Correction Quantity	V _L	—	(Note) DV9	9	20	31	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
AFC-MASK Start Phase	ϕ AFCf	—	(Note) DV10	2.6	3.2	3.8	H
AFC-MASK Stop Phase	ϕ AFCe	—	(Note) DV11	4.4	5.0	5.6	
VNFB phase	ϕ VNFB	—	(Note) DV12	0.45	0.75	1.05	
V. Output Maximum Phase	$V\phi_{max}$	—	(Note) DV13	7.3	8.0	8.7	
V. Output Minimum Phase	$V\phi_{min}$	—	(Note) DV14	0.5	1.0	1.5	
V. Output Phase Variable Range	$\Delta V\phi$	—	(Note) DV15	6.3	7.0	7.7	
50 System VBLK Start Phase	V50BLKf	—	(Note) DV16	0.4	0.55	0.7	
50 System VBLK Stop Phase	V50BLKe	—	(Note) DV17	20	23	26	
60 System VBLK Start Phase	V60BLKf	—	(Note) DV18	0.4	0.55	0.7	
60 System VBLK Stop Phase	V60BLKe	—	(Note) DV19	15	18	21	
Pin 56 VBLK Max Voltage	V56H	—		4.7	5.0	5.3	V
Pin 56 VBLK Min Voltage	V56L	—		0	—	0.3	
V. Lead-In Range 1	VAcaL	—	(Note) DV20	—	232.5	—	Hz
	VAcaH	—		—	344.5	—	
V. Lead-In Range 2	V60caL	—	(Note) DV21	—	232.5	—	
	V60caH	—		—	294.5	—	
W-VBLK Start Phase	SWVB	—	(Note) DV22	9	—	88	H
W-PMUTE Start Phase	SWP	—	(Note) DV23		—	—	
W-VBLK Stop Phase	STWVB	—	(Note) DV24	10	—	120	
W-PMUTE Stop Phase	STWP	—	(Note) DV25		—	—	
V Centering Center Voltage	V51	—	(Note) DV26		4.55		V
V Centering Max Voltage	V51Max	—	(Note) DV27		6.30		
V Centering Min Voltage	V51Min	—	(Note) DV28		2.75		
Pin 28 DAC Output Voltage (High)	V28H	—		4.0	4.5	5.0	
Pin 28 DAC Output Voltage (Low)	V28L	—		—	0	0.1	

1H DL section

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
1HDL Dynamic Range, Direct	VNBD	—	(Note) H1	0.8	1.2	—	V
	VNRD	—					
1HDL Dynamic Range, Delay	VPBD	—	(Note) H2	0.8	1.2	—	V
	VPRD	—					
1HDL Dynamic Range, Direct + Delay	VSBD	—	(Note) H3	0.9	1.2	—	V
	VSRD	—					
Frequency Characteristic, Direct	GHB1	—	(Note) H4	-3.0	-2.0	0.5	dB
	GHR1	—					
Frequency Characteristic, Delay	GHB2	—	(Note) H5	-8.2	-6.5	-4.3	dB
	GHR2	—					
AC Gain, Direct	GBY1	—	(Note) H6	-2.0	-0.5	2.0	dB
	GRY1	—					
AC Gain, Delay	GBY2	—	(Note) H7	-2.4	-0.5	1.1	dB
	GRY2	—					
Direct-Delay AC Gain Difference	GBYD	—	(Note) H8	-1.0	0.0	1.0	dB
	GRYD	—					
Color Difference Output DC Stepping	VBD	—	(Note) H9	-5	0.0	5	mV
	VRD	—					
1H Delay Quantity	BDt	—	(Note) H10	63.7	64.0	64.4	μs
	RDt	—					
Color Difference Output	Bomin	—	(Note) H11	22	36	55	mV
DC-Offset Control	Bomax	—		-55	-36	-22	
Bus-Min Data	Romin	—		22	36	55	
Bus-Max Data	Romax	—		-55	-36	-22	
Color Difference Output DC-Offset Control / Min. Control Quantity	Bo1	—	(Note) H12	1	4	8	mV
	Ro1	—					
NTSC Mode Gain / NTSC-COM Gain	GNB	—	(Note) H13	-0.90	0	1.20	dB
	GNR	—		0.92	0	1.58	

Text section

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Y Color Difference Clamping Voltage	Vcp31	—	(Note) T1	1.7	2.0	2.3	V
	Vcp33	—		2.2	2.5	2.8	
	Vcp34	—					
Contrast Control Characteristic	Vc12mx	—	(Note) T2	2.50	3.00	3.50	
	Vc12mn	—		0.21	0.31	0.47	
	D12c80	—		0.83	1.24	1.86	
	Vc13mx	—		2.50	3.00	3.50	
	Vc13mn	—		0.21	0.31	0.47	
	D13c80	—		0.83	1.24	1.86	
	Vc14mx	—		2.50	3.00	3.50	
	Vc14mn	—		0.21	0.31	0.47	
	D14c80	—		0.83	1.24	1.86	
AC Gain	Gr	—	(Note) T3				times
	Gg	—		2.8	4.0	5.2	
	Gb	—					
Frequency Characteristic	Gf	—	(Note) T4	—	-1.0	-3.0	dB
Y Sub-Contrast Control Characteristic	ΔVscnt	—	(Note) T5	3.0	6.0	9.0	V
Y ₂ Input Range	Vy2d	—	(Note) T6	0.7	—	—	
Unicolor Control Characteristic	Vn12mx	—	(Note) T7	1.6	2.3	4.3	
	Vn12mn	—		0.17	0.35	0.42	
	D12n80	—		0.67	1.16	1.68	
	Vn13mx	—		1.6	2.3	4.3	
	Vn13mn	—		0.17	0.35	0.42	
	D13n80	—		0.67	1.16	1.68	
	Vn14mx	—		1.6	2.3	4.3	
	Vn14mn	—		0.17	0.26	0.42	
	D14n80	—		0.67	1.16	1.68	
Relative Amplitude (NTSC)	ΔV13un	—		16	20	24	dB
	Mnr-b	—	(Note) T8	0.70	0.77	0.85	times
Relative Phase (NTSC)	Mng-b	—		0.30	0.34	0.38	
	θnr-b	—	(Note) T9	87	93	99	°
Relative Amplitude (PAL)	θng-b	—		235	241.5	248	
	Mpr-b	—	(Note) T10	0.50	0.56	0.63	times
Relative Phase (PAL)	Mpg-b	—		0.30	0.34	0.38	
	θpr-b	—	(Note) T11	86	90	94	°
	θpg-b	—		232	237	242	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Color Control Characteristic	Vcmx	—	(Note) T ₁₂	1.50	1.80	2.10	V _{p-p}
	e _{col}	—		80	128	160	step
	Δ _{col}	—		142	192	242	
Color Control Characteristic, Residual Color	e _{cr}	—	(Note) T ₁₃	0	12.5	25	mV _{p-p}
	e _{cg}	—					
	e _{cb}	—					
Chroma Input Range	V _{cr}	—	(Note) T ₁₄	700	—	—	
Brightness Control Characteristic	V _{brmx}	—	(Note) T ₁₅	3.05	3.45	3.85	V
	V _{brmn}	—		1.05	1.35	1.65	
Brightness Center Voltage	V _{bcnt}	—	(Note) T ₁₆	2.05	2.30	2.55	
Brightness Data Sensitivity	ΔV _{brt}	—	(Note) T ₁₇	6.3	7.8	9.4	
RGB Output Voltage Axes Difference	ΔV _{bct}	—	(Note) T ₁₈	-150	0	150	mV
White Peak Limit Level	V _{wpl}	—	(Note) T ₁₉	2.63	3.25	3.75	
Cutoff Control Characteristic	V _{comx}	—	(Note) T ₂₀	2.55	2.75	2.95	V
	V _{comm}	—		1.55	1.75	1.95	
Cutoff Center Level	V _{coc}	—	(Note) T ₂₁	2.05	2.3	2.55	
Cutoff Variable Range	ΔD _{cut}	—	(Note) T ₂₂	2.3	3.9	5.5	mV
Drive Variable Range	DR +	—	(Note) T ₂₃	2.7	3.85	5.0	dB
	DR -	—		-6.5	-5.6	-4.7	
DC Regeneration	T _{DC}	—	(Note) T ₂₄	0	50	100	mV
RGB Output S/N Ratio	S _{No}	—	(Note) T ₂₅	—	-50	-45	dB
Blanking Pulse Output Level	V _v	—	(Note) T ₂₆	0.7	1.0	1.3	V
	V _h	—		—	—	—	
Blanking Pulse Delay Time	t _{don}	—	(Note) T ₂₇	0.05	0.25	0.45	μs
	t _{doff}	—		0.05	0.35	0.85	
RGB Min. Output Level	V _{mn}	—	(Note) T ₂₈	0.8	1.0	1.2	
RGB Max. Output Level	V _{mx}	—	(Note) T ₂₉	6.85	7.15	7.45	V
Halftone Ys Level	V _{thtl}	—	(Note) T ₃₀	0.7	0.9	1.1	
Halftone Gain 1	G _{3htl3}	—	(Note) T ₃₁	-4.5	-3.0	-1.5	dB
Halftone Gain 2	G _{6htl3}	—	(Note) T ₃₂	-7.5	-6.0	-4.5	
Text ON Ys Level	V _{ttxl}	—	(Note) T ₃₃	1.8	2.0	2.2	
Text/OSD Output, Low Level	V _{txl13}	—	(Note) T ₃₄	-0.45	-0.25	-0.05	
Text RGB Output, High Level	V _{m13}	—	(Note) T ₃₅	1.15	1.4	1.85	
OSD Ys ON Level	V _{tosl}	—	(Note) T ₃₆	2.8	3.0	3.2	V
OSD RGB Output, High Level	V _{mos13}	—	(Note) T ₃₇	1.75	2.15	2.55	
Text Input Threshold Level	V _{txtg}	—	(Note) T ₃₈	0.7	1.0	1.3	
OSD Input Threshold Level	V _{osdg}	—	(Note) T ₃₉	1.7	2.0	2.3	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
OSD Mode Switching Rise-Up Time	τ_{Rosr}	—	(Note) T40	—	40	100	ns
	τ_{Rosg}	—					
	τ_{Rosb}	—					
OSD Mode Switching Rise-Up Transfer Time	t_{PRosr}	—	(Note) T41	—	40	100	ns
	t_{PRosg}	—					
	t_{PRosb}	—					
OSD Mode Switching Rise-Up Transfer Time, 3 Axes Difference	Δt_{PRos}	—	(Note) T42	—	15	40	ns
OSD Mode Switching Breaking Time	τ_{Fosr}	—	(Note) T43	—	30	100	ns
	τ_{Fosg}	—					
	τ_{Fosb}	—					
OSD Mode Switching Breaking Transfer Time	t_{PFosr}	—	(Note) T44	—	30	100	ns
	t_{PFosg}	—					
	t_{PFosb}	—					
OSD Mode Switching Breaking Transfer Time, 3 Axes Difference	Δt_{Fros}	—	(Note) T45	—	20	40	ns
OSD Hi DC Switching Rise-Up Time	τ_{Roshr}	—	(Note) T46	—	20	100	ns
	τ_{Roshg}	—					
	τ_{Roshb}	—					
OSD Hi DC Switching Rise-Up Transfer Time	t_{PRohr}	—	(Note) T47	—	20	100	ns
	t_{PRohg}	—					
	t_{PRohb}	—					
OSD Hi DC Switching Rise-Up Transfer Time, 3 Axes Difference	Δt_{PRoh}	—	(Note) T48	—	0	40	ns
OSD Hi DC Switching Breaking Time	τ_{Foshr}	—	(Note) T49	—	20	100	ns
	τ_{Foshg}	—					
	τ_{Foshb}	—					
OSD Hi DC Switching Breaking Transfer Time	t_{PFohr}	—	(Note) T50	—	20	100	ns
	t_{PFohg}	—					
	t_{PFohb}	—					
OSD Hi DC Switching Breaking Transfer Time, 3 Axes Difference	Δt_{PFoh}	—	(Note) T51	—	0	40	ns

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
RGB Contrast Control Characteristic	Vc12mx	—	(Note) T ₅₂	2.10	2.5	2.97	V
	Vc12mn	—		0.21	0.31	0.47	
	D12c80	—		0.84	1.25	1.87	
	Vc13mx	—		2.10	2.5	2.97	
	Vc13mn	—		0.21	0.31	0.47	
	D13c80	—		0.84	1.25	1.87	
	Vc14mx	—		2.10	2.5	2.97	
	Vc14mn	—		0.21	0.31	0.47	
	D14c80	—		0.84	1.25	1.87	
Analog RGB AC Gain	G _{ag}	—	(Note) T ₅₃	4.0	5.1	6.3	times
Analog RGB Frequency Characteristic	G _{fg}	—	(Note) T ₅₄	-0.5	-1.75	-3.0	dB
Analog RGB Dynamic Range	D _{r24}	—	(Note) T ₅₅	0.5	—	—	V
RGB Brightness Control Characteristic	V _{bfrm_xg}	—	(Note) T ₅₆	3.05	3.25	3.45	
	V _{bfrm_ng}	—		1.05	1.25	1.45	
RGB Brightness Center Voltage	V _{bcntg}	—	(Note) T ₅₇	2.05	2.25	2.45	
RGB Brightness Data Sensitivity	ΔV _{brtg}	—	(Note) T ₅₈	6.3	7.8	9.4	mV
Analog RGB Mode ON Voltage	V _a nath	—	(Note) T ₅₉	0.8	1.0	1.2	V
Analog RGB Switching Rise-Up Time	τ _{Ranr}	—	(Note) T ₆₀	—	50	100	ns
	τ _{Rang}	—		—	20	100	
	τ _{Ranb}	—		—	0	40	
Analog RGB Switching Rise-Up Transfer Time	t _{pRanr}	—	(Note) T ₆₁	—	50	100	
	t _{pRang}	—		—	20	100	
	t _{pRanb}	—		—	0	40	
Analog RGB Switching Rise-Up Transfer Time, 3 Axes Difference	Δt _{pRas}	—	(Note) T ₆₂	—	50	100	
Analog RGB Switching Breaking Time	τ _{Fanr}	—	(Note) T ₆₃	—	20	100	
	τ _{Fang}	—		—	10	40	
	τ _{Fanb}	—		—	0	20	
Analog RGB Switching Breaking Transfer Time	t _{pFanr}	—	(Note) T ₆₄	—	30	100	
	t _{pFang}	—		—	10	40	
	t _{pFanb}	—		—	0	20	
Analog RGB Switching Breaking Transfer Time, 3 Axes Difference	Δt _{pFas}	—	(Note) T ₆₅	—	30	100	

CHARACTERISTIC	SYMBOL	TEST CIR-CUIT	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Analog RGB Hi Switching Rise-Up Time	τ_{Ranhr}	—	(Note) T ₆₆	—	50	100	ns
	τ_{Ranhg}	—					
	τ_{Ranhb}	—					
Analog RGB Hi Switching Rise-Up Transfer Time	t_{PRahr}	—	(Note) T ₆₇	—	20	100	
	t_{PRahg}	—					
	t_{PRahb}	—					
Analog RGB Hi Switching Rise-Up Transfer Time, 3 Axes Difference	Δt_{PRah}	—	(Note) T ₆₈	—	0	40	
Analog RGB Hi Switching Breaking Time	t_{Fanhr}	—	(Note) T ₆₉	—	50	100	
	t_{Fanhg}	—					
	t_{Fanhb}	—					
Analog RGB Hi Switching Breaking Transfer Time	t_{PFahr}	—	(Note) T ₇₀	—	20	100	
	t_{PFahg}	—					
	t_{PFahb}	—					
Analog RGB Hi Switching Breaking Transfer Time, 3 Axes Difference	Δt_{PFah}	—	(Note) T ₇₁	—	0	40	
TV-Analog RGB Crosstalk	Crvag	—	(Note) T ₇₂	-80	-50	-40	dB
Analog RGB-TV Crosstalk	Crantg	—	(Note) T ₇₃				
ABL Point Characteristic	Vablpl	—	(Note) T ₇₄	5.5	5.6	5.7	V
	Vablpc	—		5.7	5.8	5.9	
	Vablph	—		5.9	6.0	6.1	
ACL Characteristic	Vcal	—	(Note) T ₇₅	-19	-16	-13	dB
ABL Gain Characteristic	Vabll	—	(Note) T ₇₆	-0.3	0	0.3	V
	Vablc	—		-1.3	-1.0	-0.7	
	Vablh	—		-2.3	-2.0	-1.7	

TEST CONDITION
VIDEO SECTION

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB $V_{CC} = 9V$; $V_{DD}, Fsc V_{DD}, Y/C V_{CC} = 5V$; $T_a = 25 \pm 3^\circ C$)										MEASURING METHOD
		SW MODE		SUB-ADDRESS & BUS DATA								
S39	S42	S44	S45	S51	04H	08H	0FH	10H	13H	14H		
Y1	Y Input Pedestal Clamping Voltage	A	C	B	A	A	20H	04H	80H	00H	BAH	03H
Y2	Chroma Trap Frequency	↑	↑	A	B	↑	↑	↑	↑	↑	↑	↑
Y3	Chroma Trap Attenuation (3.58MHz)	↑	↑	↑	↑	↑	↑	↑	↑	↑	Vari-Vari-Vari- able able	↑

- (1) Short circuit pin 45 (Y_1 IN) in AC coupling.
 (2) Input synchronizing signal to pin 51 (SYNC IN).
 (3) Measure DC voltage at pin 45, and express the measurement result as V_{Yclip} .
- (1) Set the 358 TRAP mode to AUTO by setting the bus data.
 (2) Set the bus data so that chroma trap is ON and f_0 is 0.
 (3) Input TG7 sine wave signal whose frequency is 3.58MHz (NTSC) and video amplitude is 0.5V to pin 45 (Y_1 IN).
 (4) While observing waveform at pin 37 (Y_{1out}), find a frequency with minimum amplitude of the waveform. The obtained frequency shall be expressed as f_{IR3} .
 (5) Change the frequency of the signal 1 to 4.43MHz (PAL) and perform the same measurement as the preceding step 4. The obtained frequency shall be expressed as f_{IR4} .
- (1) Set the 358 TRAP mode to AUTO by setting bus data.
 (2) Set the bus data so that Q of chroma trap is 1.5.
 (3) Set the bus data so that f_0 of chroma trap is 0.
 (4) Input TG7 sine wave signal whose frequency is 3.58MHz (NTSC) and video amplitude is 0.5V to pin 45 (Y_1 IN).
 (5) While turning on and off the chroma trap by controlling the bus, measure chroma amplitude (V_{Ton}) at pin 37 (Y_{1out}) with the chroma trap being turned on and measure chroma amplitude (V_{Toff}) at pin 37 (Y_{1out}) with the chroma trap being turned off.
 $Gtr = 20 \log (V_{Toff}/V_{Ton})$
 (6) Change f_0 of the chroma trap to -100kHz, -50kHz, 0 and +50kHz, and perform the same measurement as the preceding steps 4 and 5 with the respective f_0 settings.
 (7) Change Q of the chroma trap to 1, 1.5, 2 and 2.5, and perform the same measurement as the preceding steps 4 through 6. The maximum Gtr shall be expressed as $Gtr3a$.
 (8) Set the 358 TRAP mode to the forces 358 mode by setting bus data, and perform the same measurement as the preceding steps 2 through 7 ($Gtr3f$).

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)										
		SW MODE		SUB-ADDRESS & BUS DATA		MEASURING METHOD						
		S39	S42	S44	S45	S51	04H	08H	0FHF	10H	13H	14H
Y ₄	Chroma Trap Attenuation (4.43MHz)	A	C	A	B	A	20H	04H	Vari-Vari-Vari-Vari able-able-able-able	03H		
Y ₅	Chroma Trap Attenuation (SECAM)											
Y ₆	Yγ Correction Point											
Y ₇	Yγ Correction Curve											

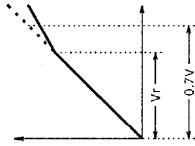
(1) Set the 358 TRAP mode to AUTO by setting bus data.
(2) Set the bus data so that Q of chroma trap is 1.5.
(3) Set the bus data so that f₀ of chroma trap is 0.
(4) Input TG7 sine wave signal whose frequency is 4.43MHz and video amplitude is 0.5V to pin 45 (Y₁ IN).
(5) Perform the same measurement as the steps 5 through 7 of the preceding item Y₃. The measurement result shall be expressed as Grtr4.

(1) Set the bus data so that the 358 TRAP mode is AUTO and the Dtrap is ON.
(2) Set the bus data so that Q of chroma trap is 1.5.
(3) Set the bus data so that f₀ of chroma trap is 0.
(4) Input SECAM signal whose amplitude in video period is 0.5V to pin 45 (Y₁ IN).
(5) Perform the same measurement as the steps 5 through 7 of the preceding item Y₃ to find the maximum attenuation (Grtrs).

(1) Connect the power supply to pin 45 (Y₁ IN).
(2) Turn off Y_γ by setting the bus data.
(3) While raising the supply voltage from the level measured in the preceding item Y₁, measure voltage change characteristic of Y₁ output at pin 37.
(4) Set the bus data to turn on Y_γ.
(5) Perform the same measurement as the above step 3.
(6) Find a gamma (γ) point from the measurement results of the steps 3 and 5.

$\gamma P = V_r \div 0.7V$

From the measurement in the above item Y₆, find gain of the portion that the γ correction has an effect on.



**TEST CONDITION
VIDEO SWITCH SECTION**

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , F _{SC} , V _{DD} , Y/C V _{CC} =5V ; T _a =25±3°C)				MEASURING METHOD	
		SW MODE	SUB-ADDRESS & BUS DATA				
		S1	S ₄₇	S ₅₁	03H		
V ₁	Min. Linear Video Input				40H ↓ B0H	(1) While supplying DC voltage to pin 47 (TVin), measure voltage change at pin 56 (Video Out) to find values of Vd1 and Vd2. (2) Find dynamic range from Vd1 and Vd2. $VdA = Vd1 - Vd2$ (3) Perform the same measurement in the EXT. mode as well as the TV mode. (EXT. IN : pin 1).	(Note) T = TV mode, E = EXT. mode
V ₂	Max. Linear Video Input	B	B	A		(1) In the same measurement as the preceding item V ₁ , find minimum output voltage (Vdo1) and maximum output voltage (Vdo2) at pin 56 (Video OUT). (2) Perform the same measurement in the EXT. mode as well as the TV mode. (EXT. IN : pin 1).	
V ₃	Video Input Dynamic Range				40H ↓ B0H	(1) Input 10kHz, 0.5V _{p-p} TG7 sine wave signal to pin 47 (TV IN). (2) Measure amplitude of video output at pin 56. (3) Calculate gain of the input and output (output / input). Calculation result shall be expressed as Gv1. $Gv1 = V56 / V47$	
V ₄	Min. Output	↑	↑	↑	40H ↓ B0H	(4) Perform the same measurement and calculation in the EXT. mode as well as the TV mode. (EXT. IN : pin 1)	
V ₅	Max. Output					(1) Input 100kHz, 0.5V _{p-p} and 6MHz, 0.5V _{p-p} TG7 sine wave signals to pin 47 (TV IN). (2) Measure amplitude of the respective video output at pin 56. Measurement results shall be expressed as V100k and V6M respectively, and difference in the frequency characteristic between those outputs shall be expressed as Gf1. $Gf1 = 20\log (V6M / V100k)$	
V ₆	AC Gain	A	A	↑	40H ↓ B0H	(3) Perform the same measurement in the EXT. mode as well as the TV mode. (EXT. IN : pin 1)	
V ₇	Frequency Characteristic	↑	↑	↑	40H ↓ B0H	(1) Input 3MHz, 0.7V (video portion) TG7 sine wave signal to pin 47 (TV IN). (2) Short circuit pin 1 (EXT. IN) in AC coupling. (3) Measure amplitude of the video output at pin 56 in both the TV mode and EXT. mode, and express the measurement results as VTV and VEXT respectively. $Vcr = 20\log (VEXT / VTV)$ (5) Perform the same measurement in the EXT. mode as well as the TV mode. (EXT. IN : pin 1)	
V ₈	Crosstalk between TV and EXT.	B ↓ A	B ↓ A	A	40H ↓ B0H		

VIDEO SECTION		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; VDD, Fsc V _{DD} , Y/C V _{CC} =5V ; Ta = 25 ± 3°C)											
NOTE	ITEM	SW MODE		SUB-ADDRESS & BUS DATA		MEASURING METHOD							
S39	S42	S44	S45	S51	04H 08H 0FH 10H 13H 14H								
Y1	Y Input Pedestal Clamping Voltage	A	C	B	A	20H 04H 80H 00H BAH 03H	(1) Short circuit pin 45 (Y1 IN) in AC coupling. (2) Input synchronizing signal to pin 51 (SYNC IN). (3) Measure DC voltage at pin 45, and express the measurement result as VYclip.						
Y2	Chroma Trap Frequency	↑	↑	A	B	↑ ↑ ↑ ↑ ↑ ↑	(1) Set the 358 TRAP mode to AUTO by setting the bus data. (2) Set the bus data so that chroma trap is ON and f0 is 0. (3) Input TG7 sine wave signal whose frequency is 3.58MHz (NTSC) and video amplitude is 0.5V to pin 45 (Y1 IN). (4) While observing waveform at pin 37 (Y1out), find a frequency with minimum amplitude of the waveform. The obtained frequency shall be expressed as fir3. (5) Change the frequency of the signal 1 to 4.43MHz (PAL) and perform the same measurement as the preceding step 4. The obtained frequency shall be expressed as fir4.						
Y3	Chroma Trap Attenuation (3.58MHz)	↑	↑	↑	↑	↑ ↑ ↑ ↑ ↑ ↑	(1) Set the 358 TRAP mode to AUTO by setting bus data. (2) Set the bus data so that Q of chroma trap is 1.5. (3) Set the bus data so that f0 of chroma trap is 0. (4) Input TG7 sine wave signal whose frequency is 3.58MHz (NTSC) and video amplitude is 0.5V to pin 45 (Y1 IN). (5) While turning on and off the chroma trap by controlling the bus, measure chroma amplitude (VTon) at pin 37 (Y1out) with the chroma trap being turned on and measure chroma amplitude (VToff) at pin 37 (Y1out) with the chroma trap being turned off. Gtr = 20log (VToff / VTon) (6) Change f0 of the chroma trap to -100kHz, -50kHz, 0 and +50kHz, and perform the same measurement as the preceding steps 4 and 5 with the respective f0 settings. (7) Change Q of the chroma trap to 1, 1.5, 2 and 2.5, and perform the same measurement as the preceding steps 4 through 6. The maximum Gtr shall be expressed as Gtr3a. (8) Set the 358 TRAP mode to the forces 358 mode by setting bus data, and perform the same measurement as the preceding steps 2 through 7 (Gtr3f).						

		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} = 5V ; Ta = 25 ± 3°C)									
NOTE	ITEM	SW MODE		SUB-ADDRESS & BUS DATA		MEASURING METHOD					
S ₃₉	S ₄₂	S ₄₄	S ₄₅	S ₅₁	04H 08H 0FH 10H 13H 14H						
Y ₄	Chroma Trap Attenuation (4.43MHz)	A	C	A	B	A	20H 04H	Vari-Vari-Vari- able able able able	03H		
Y ₅	Chroma Trap Attenuation (SECAM)	↑	↑	↑	↑	↑	↑	↑	↑	↑	
Y ₆	YY Correction Point	↑	↑	↑	↑	↑	↑	↑	↑	↑	Vari- able
Y ₇	YY Correction Curve	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑

(1) Set the 358 TRAP mode to AUTO by setting bus data.
(2) Set the bus data so that Q of chroma trap is 1.5.
(3) Set the bus data so that f₀ of chroma trap is 0.
(4) Input TG7 sine wave signal whose frequency is 4.43MHz and video amplitude is 0.5V to pin 45 (Y₁ IN).
(5) Perform the same measurement as the steps 5 through 7 of the preceding item Y₃. The measurement result shall be expressed as Gtr4.

(1) Set the bus data so that the 358 TRAP mode is AUTO and the Dtrap is ON.
(2) Set the bus data so that Q of chroma trap is 1.5.
(3) Set the bus data so that f₀ of chroma trap is 0.
(4) Input SECAM signal whose amplitude in video period is 0.5V to pin 45 (Y₁ IN).
(5) Perform the same measurement as the steps 5 through 7 of the preceding item Y₃ to find the maximum attenuation (Gtrs).

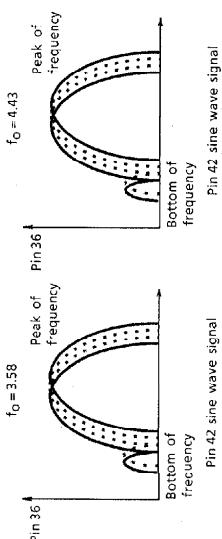
(1) Connect the power supply to pin 45 (Y₁ IN).
(2) Turn off Y₇ by setting the bus data.
(3) While raising the supply voltage from the level measured in the preceding item Y₁, measure voltage change characteristic of Y₁ output at pin 37.
(4) Set the bus data to turn on Y₇
(5) Perform the same measurement as the above step 3.
(6) Find a gamma (γ) point from the measurement results of the steps 3 and 5.
 $\gamma_p = V_r \div 0.7V$

From the measurement in the above item Y₆, find gain of the portion that the γ correction has an effect on.

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{CC} = 5V ; T _a = 25 ± 3°C)								MEASURING METHOD
		SW MODE		SUB-ADDRESS & BUS DATA						
		S39	S42	S44	S45	S51	04H 08H	0FFH 10H	13H 14H	
Y13	Picture Quality Control Peaking Frequency	A	C	A	B	A	3FH 04H	80H 00H	BAH Variable	(1) Set the bus data so that picture quality control frequency is 2.5MHz. (2) Input TG7 sine wave (sweeper) signal whose video level is 0.1V to pin 45 (Y ₁ IN) and pin 51 (Sync. IN). (3) Maximize the picture quality control data. (4) While observing Y _{1out} of pin 37, find an SG frequency as the waveform amplitude is maximum (fp25). (5) Set the bus data so that picture quality control frequency is 3.1MHz and 4.2MHz, and perform the same measurement as the above steps 2 through 4 at the respective frequencies (fp31, fp42). (1) Input TG7 sine wave (sweeper) signal whose video level is 0.1V to pin 45 (Y ₁ IN) and pin 51 (Sync. IN). (2) Set the picture quality control data to maximum. (3) Set the picture quality control frequency is 2.5MHz by setting the bus data. (4) Measure amplitude (Y100k) of the output of pin 37 (Y ₁ OUT) as the SG frequency is 100kHz, and the amplitude (Yp25) of the same as the SG frequency is 2.5MHz. GS25MX = 20log (Yp25 / V100k) (5) Set the picture quality control frequency data to 3.1MHz by setting the bus data. (6) Measure amplitude (Y100k) of the output of pin 37 (Y ₁ OUT) as the SG frequency is 100kHz, and the amplitude (Yp31) of the same as the SG frequency is 3.1MHz. GS31MX = 20log (Yp31 / V100k) (7) Set the picture quality control frequency to 4.2MHz by setting the bus data. (8) Measure amplitude (Y100k) of the output of pin 37 (Y ₁ OUT) as the SG frequency is 100kHz, and the amplitude (Yp42) of the same as the SG frequency is 4.2MHz. GS42MX = 20log (Yp42 / V100k)
Y14	Picture Quality Control Maximum Characteristic	↑	↑	↑	↑	↑	↑	↑	↑	

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; VDD, Fsc V _{DD} , Y/C V _{CC} =5V ; Ta = 25 ± 3°C)										MEASURING METHOD
		SW MODE		SUB-ADDRESS & BUS DATA								
S39	S42	S44	S45	S51	04H	08H	0FH	10H	13H	14H		
Y15	Picture Quality Control Minimum Characteristic	A	C	A	B	A	00H	04H	80H	00H BAH	Variable	(1) In the condition of the Note Y14, set the picture quality control bus data to minimum. (2) Perform the same measurement as the steps 3 through 8 of the Note Y14 to find respective gains as the picture quality control frequency is set to 2.5MHz, 3.1MHz and 4.2MHz. GS25MN = 20log (Vp25 / V100k) GS31MN = 20log (Vp31 / V100k) GS42MN = 20log (Vp42 / V100k)
Y16	Picture Quality Control Center Characteristic	↑	↑	↑	↑	↑	20H	↑	↑	↑	↑	(1) In the condition of the Note Y14, set the picture quality control bus data to center. (2) Perform the same measurement as the steps 3 through 8 of the Note Y14 to find respective gains as the picture quality control frequency is set to 2.5MHz, 3.1MHz and 4.2MHz. GS25CT = 20log (Vp25 / V100k) GS31CT = 20log (Vp31 / V100k) GS42CT = 20log (Vp42 / V100k)
Y17	Y Signal Gain	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	(1) Set the bus data so that black expansion is off, picture quality control is off and DC transmission compensation is minimum. (2) Input TG7 sine wave signal whose frequency is 100kHz and video level is 0.5V to pin 45 (Y1 IN) and pin 51 (Sync. IN). (Vy100) (3) Measure amplitude of Y ₁ output at pin 37 (Yout). Gy = 20log (Vyout / Vy100)
Y18	Y Signal Frequency Characteristic	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	(1) Set the bus data so that black expansion is off, picture quality control is off and DC transmission compensation is minimum. (2) Input TG7 sine wave signal whose frequency is 6MHz and video level is 0.5V to pin 45 (Y1 IN) and pin 51 (Sync. IN). (Vyo6M) (3) Measure amplitude of Y ₁ output at pin 37 (Vyo6M). Gy6M = 20log (Vyo6M / Vy6M) (4) Find Gy from the result of the Note Y17. Gfy = Gy6M - Gy

TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)									
NOTE	ITEM	SW MODE		SUB-ADDRESS & BUS DATA		MEASURING METHOD			
		S39	S42	S44	S45	S51	04H 08H 0FH 10H 13H 14H	(1) Set the bus data so that black expansion is off, picture quality control is off and DC transmission compensation is minimum.	(2) Input TG7 sine wave signal whose frequency is 100kHz to pin 45 (Y ₁ IN) and pin 51 (Sync. IN).
Y19	Y Signal Maximum Input Range	A	C	A	B	A	20H 04H 80H 00H BAH 03H	(3) While increasing the amplitude V _{yd} of the signal in the video period, measure V _{yd} just before the waveform of Y ₁ output (pin 37) is distorted.	

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{CC} =5V ; Ta = 25±3°C)									MEASURING METHOD
		S26	S1	S31	S33	S34	S39	S42	S44	S45	
C ₂	Band Pass Filter Characteristic	ON	A	B	B	A	B	A	A	B	(1) Activate the test mode (S26-ON, Sub Add 012 ; 01h). (2) Set as follows : band pass filter Q = 2, crystal clock = conforming to 3.579 / 4.43MHz, gate = normal status. (3) Input 3N composite sine wave signal (1Vpp) to pin 42 (Chroma IN). (4) Measure frequency characteristic of B-Y output of pin 36 and measure the peak frequency, too. (5) Changing f ₀ to 0, 500, 600 and 700 by the bus control and measure peak frequencies respectively with different f ₀ . (6) For measuring frequency characteristic as f ₀ is 4.43, use 4.43MHz crystal clock. Measure the following items in the same manner.
											

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} =5V ; Ta = 25 ± 3°C)										MEASURING METHOD			
		SW MODE					S ₂₆	S ₁	S ₃₁	S ₃₃	S ₃₄	S ₃₉	S ₄₂	S ₄₄	S ₄₅
C ₉	APC Lead-In Range	OFF ↓ ON	A	B	B	A	A	A	↓	C	A	B	A	A	B
C ₁₀	APC Control Sensitivity	ON	↑	↑	↑	↑	↑	↑	↑	c	↑	↑	↑	↑	↑

(1) Connect band pass filter (Q = 2), set to TV mode ($f_0 = 600\text{kHz}$) with X'tal clock conforming to European, Asian system.
(2) Set the gate to normal status.
(3) Input 3N CW signal of 100mV_{p-p} to pin 42 of the chroma input terminal.
(4) While changing frequency of the CW (continuous waveform) signal, measure its frequency when B-Y color difference signal of pin 36 is colored.
(5) Input 4N CW (continuous waveform) 100mV_{p-p} signal to pin 42 (Chroma IN).
(6) While changing frequency of the CW signal, measure frequencies when B-Y color difference output of pin 36 is colored and discolored. Find difference between the measured frequency and f_c (4.433619MHz) and express the differences as f_{PH} and f_{PL} , which show the APC lead-in range.
(7) Variable frequency of VCXO is used to cope with lead-in of 3.582MHz / 3.575MHz PAL system.
(8) Activate the test mode (\$26-ON, Sub Add 02 : 02h).
(9) Input nothing to pin 42 (Chroma IN).
(10) While varying voltage of pin 30 (APC Filter), measure variable frequency of VCXO at pin 35 (R-Y OUT) while observing color and discoloring of R-Y color difference signal. Express difference between the high frequency (f_H) and f_0 center as 3.582MHz, and difference between the low frequency (f_L) and f_0 center as 3.582MHz. Perform the same measurement for the NP system (3.575MHz PAL).
(1) Activate the test mode (\$26-ON, Sub Add 02 : 02h).
(2) Connect band pass filter as same as the Note C₉.
(3) Change the X'tal mode properly to the system.
(4) Input nothing to pin 42 (Chroma IN).
(5) When V₃₀'s APC voltage ±50mV is impressed to pin 30 (APC Filter) while its voltage is being varied, measure frequency change of pin 35 output signal as f_{RH} or f_{RL} and calculate sensitivity according to the following equation.
 $b = (f_{RH} - f_{RL}) / 100$

		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)										
NOTE	ITEM	SW MODE										MEASURING METHOD
		S ₂₆	S ₁	S ₃₁	S ₃₃	S ₃₄	S ₃₉	S ₄₂	S ₄₄	S ₄₅	S ₅₁	
C ₁₂	Color Difference Output	ON	A	B	B	A	A	A	A	A	B	(1) Activate the test mode (S26-ON, Sub Add 02 ; 08h). (2) Connect band pass filter (Q = 2), set to TV mode (f _o = 600kHz) with 0dB attenuation. (3) Set the crystal mode to conform to European, Asian system and set the gate to normal status. (4) Input 3N, 4N and 4P rainbow color bar signals having 100mV _{p-p} burst to pin 42 of the chroma input terminal one after another. (5) Measure amplitudes of color difference signals of pin 36 (B-Y) and pin 35 (R-Y) respectively, and express them as 3NeB-Y / R-Y, 4NeB-Y / R-Y and 4PeB-Y / R-Y respectively. (6) While inputting 4P 75% color bar signal (100mV _{p-p} burst) to pin 42 of the chroma input terminal, measure amplitudes of color difference signals of pin 36 (B-Y OUT) and pin 35 (R-Y OUT) respectively. (1) Activate the test mode (S26-ON, Sub Add 02 ; 08h). (2) Connect band pass filter (Q = 2), set to TV mode (f _o = 600kHz) with 0dB attenuation. (3) Set the crystal mode to conform to European, Asian system and set the gate to normal status.
C ₁₃	Demodulation Relative Amplitude	↑	↑	↑	↑	↑	↑	↑	↑	↑	↑	(4) Input 3N, 4N and 4P rainbow color bar signals having 100mV _{p-p} burst to pin 42 of the chroma input terminal one after another. (5) Measure amplitudes of color difference signals of pin 36 (B-Y) and pin 35 (R-Y) respectively, and express ratio between the two amplitudes as 3NG R/B, 4NG R/B and 4PG R/B respectively. (Note) Relative amplitude of G-Y color difference signal shall be checked later in the Text section.

		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)									
NOTE	ITEM	SW MODE					MEASURING METHOD				
		S26	S1	S31	S33	S34	S39	S42	S44	S45	S51
C14	Demodulation Relative Phase	ON	A	B	B	A	A	A	A	B	
C15	Demodulation Output Residual Carrier	↑	↑	↑	↑	↑	↑	↑	↑	↑	

(1) Activate the test mode (S26-ON, Sub Add 02 ; 08h).
(2) Connect band pass filter (Q = 2), set to TV mode ($f_0 = 600\text{kHz}$) with 0dB attenuation.
(3) Set the crystal mode to conform to European, Asian system and set the gate to normal status.
(4) Input 3N, 4N and 4P rainbow color bar signals having 100mV_{p-p} burst to pin 42 of the chroma input terminal one after another.
(5) Measure phases of color difference signals of pin 36 (B-Y) and pin 35 (R-Y) respectively, and express them as 3Nθ/R-B, 4Nθ/R-B and 4Pθ/R-B respectively.
(6) For measuring with 3N and 4N color bar signals in NTSC system, set six bars of the B-Y color difference waveform to the peak level with the Tint control and measure its phase difference from phase of R-Y color difference signal of pin 35 (R-Y OUT).
(Note) Relative phase of G-Y color difference signal shall be checked later in the Text section.

(1) Activate the test mode (S26-ON, Sub Add 02 ; 08h).
(2) Connect band pass filter (Q = 2), set to TV mode ($f_0 = 600\text{kHz}$) with 0dB attenuation.
(3) Set the crystal mode to conform to European, Asian system.
(4) Set the gate to normal status.
(5) Input 3N and 4N rainbow color bar signals having 100mV_{p-p} burst to pin 42 of the chroma input terminal one after another.
(6) Measure subcarrier leak of 3N and 4N color bar signals appearing in color difference signals of pin 36 (B-Y OUT) and pin 35 (R-Y OUT) respectively, and express those leaks as 3N-SCB/R and 4N-SCB/R.

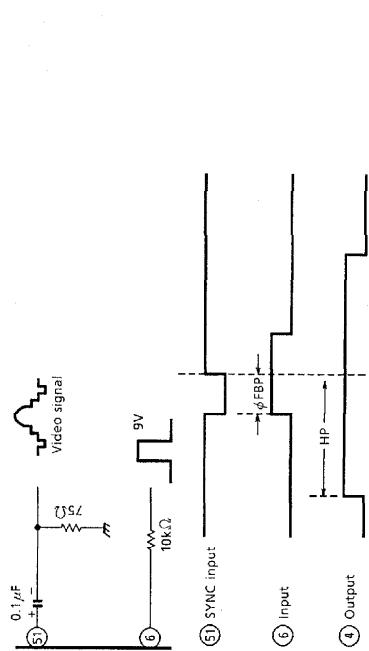
		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)										
NOTE	ITEM	SW MODE										MEASURING METHOD
		S26	S1	S31	S33	S34	S39	S42	S44	S45	S51	
C16	Demodulation Output Residual Higher Harmonic	ON	A	B	B	A	A	A	A	B		(1) Activate the test mode (S26-ON, Sub Add 02 ; 08h). (2) Connect band pass filter (Q = 2), set to TV mode ($f_o = 600\text{kHz}$) with 0dB attenuation. (3) Set the crystal mode to conform to European, Asian system and set the gate to normal status. (4) Input 3N and 4N rainbow color bar signals having 100mV _{p-p} burst to pin 42 of the chroma input terminal one after another. (5) Measure higher harmonic ($2f_c = 7.16\text{MHz}$ or 8.87MHz) of 3N and 4N color bar signals appearing in color difference signals of pin 36 (B-Y OUT) and pin 35 (R-Y OUT) respectively, and express them as 3N-HCB / R and 4N-HCB / R.
C17	Color Difference Output ATT Check											(1) Activate the test mode (S26-ON, Sub Add 02 ; 08h). (2) Connect band pass filter (Q = 2) and set bus data for the TV mode ($f_o = 600\text{kHz}$). (3) Set the Xtal clock mode to conform to European, Asian system and set the gate to normal status. (4) Input 3N rainbow color bar signal whose burst is 100mV _{p-p} to pin 42 of the chroma input terminal. (5) Measure amplitude of color difference output signal of pin 36 (B-Y OUT) with 0dB attenuation set by the bus control. Set the amplitude of the color difference output of pin 36 (B-Y OUT) to 0dB, and measure amplitude of the same signal with different attenuation of -2dB, -1dB and +1dB set by the bus control.

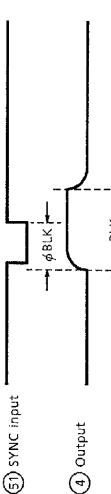
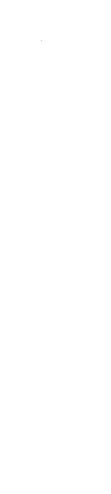
NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{sc} V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C)								MEASURING METHOD						
		BUS : TEST MODE				BUS : NORMAL CONTROL MODE										
	S	02H	07H	10H	D ₅	D ₂	D ₁	D ₀	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀	OTHER CONDITION	
C18	16.2MHz Oscillation Frequency	ON	0	0	1	0	0	0	0	0	0	0	0	0	—	(1) Input nothing to pin 42. (2) Measure frequency of CW signal of pin 35 as f _r , and find oscillation frequency by the following equation. $\Delta foF = (f_r - 0.05\text{MHz}) \times 4$
C19	16.2MHz Oscillation Start Voltage	ON	0	0	1	0	0	0	0	0	0	0	0	0	—	While raising voltage of pin 38, measure voltage when oscillation waveform appears at pin 40.
C20	f _{sc} Free-Run Frequency	ON	0	0	1	0	0	0	Variable	0	0	0	0	0	—	(1) Input nothing to pin 42. (2) Change setting of SUB (10H) D ₄ , D ₃ and D ₂ according to respective frequency modes, and measure frequency of CW signal of pin 35. Detail of D ₄ , D ₃ and D ₂ 3.58M = 1 : (001), 4.43M = 2 : (010) M-PAL = 6 : (110), N-PAL = 7 : (111)
C21	f _{sc} Output Amplitude	OFF	0	0	0	0	0	0	0	0	1	↓	0	0	—	(1) Input nothing to pin 42. (2) Change setting of SUB (10H) D ₄ , D ₃ and D ₂ according to respective frequency modes. Measure the amplitude of output signal of pin 27.

DEF SECTION NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , F _{sc} V _{DD} , Y / C V _{CC} =5V ; T _A =25±3°C ; BUS = preset value ; pin 51 input video signal = 50 system (Note) "x" in the data column represents preset value at power ON.)									
		SUB-ADDRESS & BUS DATA					MEASURING METHOD				
DH1	H. Reference Frequency	Sub 02H	0	0	0	0	0	0	0	1	(1) Supply 5V to pin 26. (2) Set bus data as indicated on the left. (3) Measure the frequency of sync. output of pin 49.
DH2	H. Oscillation Start Voltage	Sub 02H	0	0	0	0	0	0	0	1	In the test condition of the Note DH1, turning down the voltage supplied to pin 26 from 5V, measure the voltage when oscillation of pin 49 stops.
DH3	H. Output Frequency 1	Sub 10H	x	x	x	x	x	x	0	1	(1) Set bus data as indicated on the left. (2) In the condition of the above step 1, measure frequency (TH1) at pin 4.
DH4	H. Output Frequency 2	Sub 10H	x	x	x	x	x	x	1	0	(1) Set the input video signal of pin 51 to the 60 system. (2) Set bus data as indicated on the left. (3) In the above-mentioned condition, measure frequency (TH2) at pin 4.
DH5	H. Output Duty 1	—	—	—	—	—	—	—	—	—	(1) Supply 4.5V DC to pin 5 (or, make pin 5 open-circuited). (2) Measure duty of pin 4 output.
DH6	H. Output Duty 2	—	—	—	—	—	—	—	—	—	(1) Make a short circuit between pin 5 and ground. (2) Measure duty of pin 4 output.
DH7	H. Output Duty Switching Voltage	—	—	—	—	—	—	—	—	—	Supply 2V DC to pin 5. While turning down the voltage from 2V, measure voltage when the output duty ratio becomes 41 to 37%.
DH8	H. Output Voltage	—	—	—	—	—	—	—	—	—	Measure the low voltage and high voltage of pin 4 output whose waveform is shown below.
DH9	H. Output Oscillation Start Voltage	—	—	—	—	—	—	—	—	—	While raising H. V _{CC} (pin 3) from 0V, measure voltage when pin 4 starts oscillation.

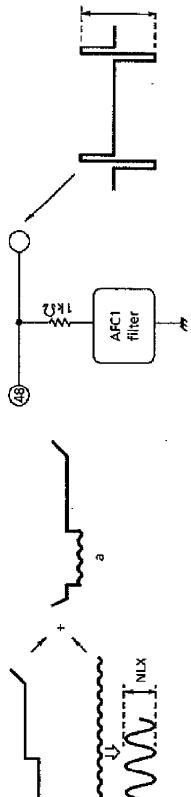


NOTE	ITEM	TEST CONDITION Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; BUS = preset value ; (Note) "x" in the data column represents preset value at power ON.											
		SUB-ADDRESS & BUS DATA											
MEASURING METHOD													
DH10	H. FBP Phase												
DH11	H. Picture Position, Maximum												
DH12	H. Picture Position, Minimum	0	0	0	0	x	x	x	x	x	x	x	x
DH13	H. Picture position Control Range	Sub 0BH	0	0	0	0	x	x	x	x	x	x	x
DH14	H. Distortion Correction Control Range		1	1	1	1	x	x	x	x	x	x	x

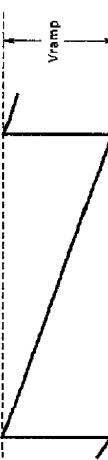


NOTE	ITEM	SUB-ADDRESS & BUS DATA										TEST CONDITION	
		(Note) "x" in the data column represents preset value at power ON.										(Note) Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta = 25±3°C ; BUS = preset value ;)	
DH15	H. BLK Phase	Sub 02H	0	0	0	0	0	1	0	0	0	(1) In the condition of the steps 1 through 4 of the Note DH10, perform the following measurement. (2) Supply 5V DC to pin 26. (3) Set bus data as indicated on the left. (4) Measure phase difference between pin 51 and pin 49 as shown below. (5) Change the bus data as shown on the left and measure BLK width.	
DH16	H. BLK Width, Minimum	Sub 16H	0	0	x	x	x	x	x	x	x		
DH17	H. BLK Width, Maximum		1	1	x	x	x	x	x	x	x		
DH18	P/N-GP Start Phase 1											(1) Supply 5V to pin 26. (2) Set bus data as indicated on the left. (3) With the respective bus data settings mentioned above, measure the phase and gate width as shown in the figure below.	
DH19	P/N-GP Start Phase 2												
DH20	P/N-GP Gate Width 1	Sub 0FH	x	x	x	0	x	x	x	x	x		
DH21	P/N-GP Gate Width 2		x	x	x	1	x	x	x	x	x		

NOTE	ITEM	TEST CONDITION								MEASURING METHOD
		(Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; BUS=preset value ; Pin 51 input video signal= 50 System (Note) "x" in the data column represents preset value at power ON.)								
SUB-ADDRESS & BUS DATA										(1) Input such a signal as shown by "a" of the following figure to pin 51. (2) Set bus data as indicated in the first line of the left table. (3) Measure NLX when amplitude of pin 41 changes. → NL1 (4) Set bus data as indicated in the second line of the left table. (5) Measure NLX when amplitude of pin 41 changes. → NL2 (6) Set bus data as indicated in the third line of the left table. (7) Measure NLX when amplitude of pin 41 changes. → NL3 (8) Set bus data as indicated in the fourth line of the left table. (9) Measure NLX when amplitude of pin 41 changes. → NL4
DH22	Noise Detection Level 1	0 0	x	x	x	x	x	x	x	
DH23	Noise Detection Level 2	0 1	x	x	x	x	x	x	x	
DH24	Noise Detection Level 3	Sub 1DH	1 0	x	x	x	x	x	x	
DH25	Noise Detection Level 4		1 1	x	x	x	x	x	x	
DV1	V. Ramp Amplitude									
DV2	V. NF Maximum Amplitude	Sub 17H	1 1	1	1	1	1	1	x	
DV3	V. NF Minimum Amplitude	Sub 17H	0 0	0	0	0	0	0	x	

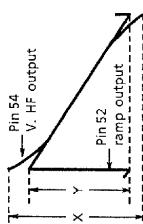
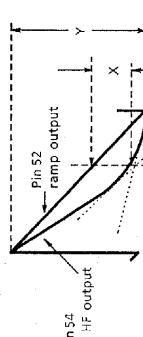


(1) Measure amplitude of V. ramp waveform of pin 52.



- (1) Set data bus as indicated on the left.
- (2) Measure amplitude of pin 54's signal.
- (1) Set data bus as indicated on the left.
- (2) Measure amplitude of pin 54's signal.

NOTE	ITEM	TEST CONDITION Unless otherwise specified : H, RGB VCC=9V ; VDD, Fsc VDD, Y/C VCC=5V ; TA = 25 ± 3°C ; BUS = preset value ; (Note) "x" in the data column represents preset value at power ON.	SUB-ADDRESS & BUS DATA	MEASURING METHOD
DV4	V. Amplification Degree	(1) Set bus data as indicated on the left. (2) Change 5.0V of pin 54 voltage by +0.1V and -0.1V, and measure V53 output (3) Find GVA shown in the figure below. (4) Measure Vvmax and Vvmin shown in the figure below.		
DV5	V. Amplifier Max. Output			(1) Adjust the oscilloscope's amplitude with the UNCAL so that pin 52 and pin 54 waveforms overlap each other as the bus data is set to the preset value. (2) Change the bus data as indicated on the left, and measure values of X and Y shown in the figure below.
DV6	V. Amplifier Min. Output			(3) Find VS according to the equation that $VS = (X / Y) \times 100\%$.
DV7	V. S-Curve Correction, Max. Quantity			

NOTE	ITEM	TEST CONDITION Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} =5V ; Ta = 25 ± 3°C ; BUS = preset value ; pin 51 input video signal = 50 system (Note) "x" in the data column represents preset value at power ON.	SUB-ADDRESS & BUS DATA	MEASURING METHOD
DV8	V. Reverse S-Curve Correction, Max. Quantity	Sub 19H 0 0 0 0 0 x	(1) Adjust the oscilloscope's amplitude with the UNCAL so that pin 52 and pin 54 waveforms overlap each other as the bus data is set to the preset value. (2) Change the bus data as indicated on the left, and measure values of X and Y shown in the figure below. (3) Find V _S according to the equation that V _S =(X/Y)×100%.	
DV9	V. Linearity Max. Correction Quantity	Sub 1AH 1 1 1 x x x	(1) Adjust the oscilloscope's amplitude with the UNCAL so that pin 52 and pin 54 waveforms overlap each other as the bus data is set to the preset value. (2) Change the bus data as indicated on the left, and measure values of X and Y shown in the figure below. (3) Find V _S according to the equation that V _S =(X/2Y)×100%.	

NOTE	ITEM	TEST CONDITION Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} =5V ; Ta = 25 ± 3°C ; BUS = preset value ; pin 51 input video signal = 50 system (Note) "x" in the data column represents preset value at power ON.									
		SUB-ADDRESS & BUS DATA MEASURING METHOD									
DV10	AFC-MASK Start Phase	Sub 02H	0	0	0	0	0	0	1		
DV11	AFC-MASK Stop Phase	Sub 16H	x	x	x	x	0	0	0		
DV12	VNFB Phase										
DV13	V. Output Maximum Phase										
DV14	V. Output Minimum Phase	Sub 16H	x	x	x	x	0	0	0		
DV15	V. Output Phase Variable Range										

(Note) "x" in the data column represents preset value at power ON.

MEASURING METHOD

(1)

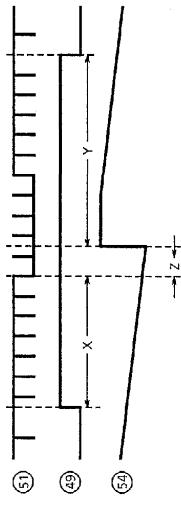
Supply 5V DC to pin 26.

(2) Set bus data as indicated on the left and activate the test mode.

(3) Measure the AFC-MASK start phase (X) and AFC-MASK stop phase (Y) of pin 49.

(4) Set the Sub 16H as indicated on the left.

(5) Measure the VNFB start phase (Z) of pin 54.



(1) Input video signal to pin 51.

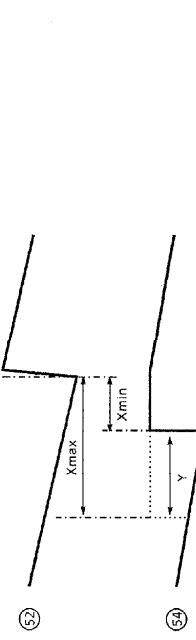
(2) Measure both phases (Xmax, Xmin) of pin 52 and pin 54 with the respective bus data settings shown on the left.

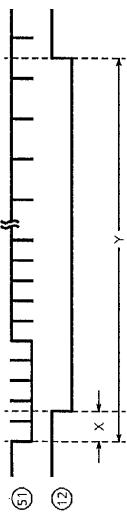
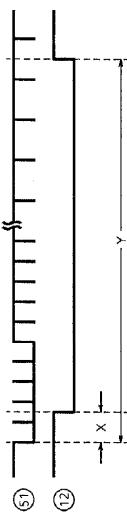
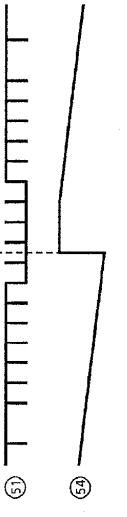
(3) Find difference between the two phases measured in the above step 2.
$$Y = X_{\text{max}} - X_{\text{min}}$$

DV13 V. Output Maximum Phase

DV14 V. Output Minimum Phase

DV15 V. Output Phase Variable Range

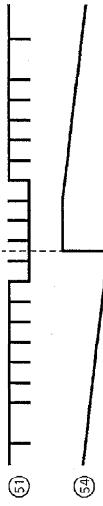


NOTE	ITEM	SUB-ADDRESS & BUS DATA										TEST CONDITION	
		(Note) "x" in the data column represents preset value at power ON.										Pin 51 input video signal = 50 system	
DV16	50 System VBLK Start Phase	Sub 1BH	0	x	x	x	x	x	x	x	x	(1) Input such a video signal of the 50 system as shown in the figure to pin 51. (2) Set bus data as indicated on the left. (3) Measure the VBLK start phase (X) and VBLK stop phase (Y) of pin 12.	
DV17	50 System VBLK Stop Phase	Sub 1CH	0	x	x	x	x	x	x	x	x		
DV18	60 System VBLK Start Phase	Sub 1BH	0	1	x	x	x	x	x	x	x	(1) Input such a video signal of the 60 system as shown in the figure to pin 51. (2) Set bus data as indicated on the left. (3) Measure the VBLK start phase (X) and VBLK stop phase (Y) of pin 12.	
DV19	60 System VBLK Stop Phase	Sub 1CH	0	x	x	x	x	x	x	x	x		
DV20	V. Lead-In Range 1	Sub 16H	x	x	0	0	0	0	0	0	0	(1) Set bus data as indicated on the left. (2) Input 262.5 H video signal to pin 51. (3) Set a certain number of field lines in which signals of pin 51 and pin 54 completely synchronize with each other as shown in the figure below. (4) Decrease the field lines in number and measure number of lines in which pin 51 and pin 54 signals do not synchronize with each other. (5) Again set a certain number of field lines in which pin 51 and pin 52 signals synchronize with each other. (6) Increase the field lines in number and measure number of lines in which pin 51 and pin 52 signals do not synchronize with each other.	

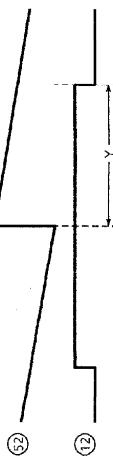
NOTE	ITEM	TEST CONDITION Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} =5V ; Ta = 25 ± 3°C ; BUS = preset value ; pin 51 input video signal = 50 system (Note) "x" in the data column represents preset value at power ON.							
		SUB-ADDRESS & BUS DATA							
DV21	V. Lead-In Range 2 Sub 16H	x	x	0	1	0	0	0	0
DV22	W-VBLK Start Phase	x	x	0	0	0	0	0	0
DV23	W-PMUTE Start Phase	Sub 1BH	x	1	1	1	1	1	1
	(Note) Only the 60 system is subject to evaluation.	Sub 1DH	x	0	0	0	0	0	0
			x	1	1	1	1	1	1

MEASURING METHOD

(1) Set bus data as indicated on the left.
(2) Input 262.5 H video signal to pin 51.
(3) Set a certain number of field lines in which signals of pin 51 and pin 54 completely synchronize with each other as shown in the figure below.
(4) Decrease the field lines in number and measure number of lines in which pin 51 and pin 54 signals do not synchronize with each other.
(5) Again set a certain number of field lines in which pin 51 and pin 52 signals synchronize with each other.
(6) Increase the field lines in number and measure number of lines in which pin 51 and pin 52 signals do not synchronize with each other.




NOTE	ITEM	SUB-ADDRESS & BUS DATA								MEASURING METHOD
		(Note) "x" in the data column represents preset value at power ON.								
DV24	W-vBLK Stop Phase	Sub 1CH	x	0	0	0	0	0	0	(1) Set bus data as specified for the Sub 1CH in the left columns, and measure the value of Y shown in the figure below. W-vBLK stop phase : MAX, MIN
DV25	W-PMUTE Stop Phase	Sub 1EH	x	1	1	1	1	1	1	(2) Set bus data as specified for the Sub 1EH in the left columns, and measure the value of Y shown in the figure below. W-PMUTE stop phase : MAX, MIN
	(Note) Only the 60 system is subject to evaluation.	Sub 1EH	x	0	0	0	0	0	0	
DV26	V Centering Center Voltage		1	0	0	0	0	x	x	(1) Set bus data as indicated on the left. (2) Measure the voltage of pin 47 with respective bus data settings.
DV27	V Centering Max Voltage	Sub 18H	1	1	1	1	1	x	x	
DV28	V Centering Min Voltage		0	0	0	0	0	x	x	



1H DL SECTION

		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _D , F _C V _{DD} , Y/C V _{CC} = 5V ; Ta = 25±3°C ; BUS = preset value ; pin3 = 9V ; pin8-38-41 = 5V)			
NOTE	ITEM	SW MODE	SUB ADDRESS & DATA	MEASURING METHOD	
		\$26	07H 0FH	11H	
H1	1HDL Dynamic Range Direct	ON	94H	—	(1) Input waveform 1 to pin 33 (B-Yin), and measure VNBD, that pin 36 (B-Yout) is saturated input level. (2) Measure VNRD of R-Y input in the same way as VNBD.
H2	1HDL Dynamic Range Delay	↑	8CH	—	(1) Input waveform 1 to pin 33 (B-Yin), and measure VPBD, that pin 36 (B-Yout) is saturated input level. (2) Measure VPRD of R-Y input in the same way as VPBD.
H3	1HDL Dynamic Range, Direct+Delay	↑	A4H	—	(1) Input waveform 1 to pin 33 (B-Yin), and measure VSBD, that pin 36 (B-Yout) is saturated input level. (2) Measure VNRD of R-Y input in the same way as VSBD.
H4	Frequency Characteristic, Direct	↑	94H	—	(1) In the same measuring as H1, set waveform 1 to 0.3V _{p-p} and f = 100kHz. Measure VB100, that is pin 36 (B-Yout) level. And set waveform 1 to f = 700kHz. Measure VB700, that is pin 36 (B-Yout) level. GHB1 = 20log (VB700 / VB100) (2) Measure GHR1 of R-Y out in the same way as GHB1.
H5	Frequency Characteristic, Delay	↑	8CH	—	(1) In the same measuring as H1, set waveform 1 to 0.3V _{p-p} and f = 100kHz. Measure VB100, that is pin 36 (B-Yout) level. And set waveform 1 to f = 700kHz. Measure VB700, that is pin 36 (B-Yout) level. GHB2 = 20log (VB700 / VB100) (2) Measure GHR2 of R-Y out in the same way as GHB2.
H6	AC Gain Direct	↑	94H	—	(1) In the same measuring as H1, set waveform 1 to 0.7V _{p-p} . Measure VByt1, that is pin 36 (B-Yout) level. GBY1 = 20log (VByt1 / 0.7) (2) Measure GRY1 of R-Y out in the same way as GBY1.
H7	AC Gain Delay	↑	8CH	—	(1) In the same measuring as H1, set waveform 1 to 0.7V _{p-p} . Measure VByt2, that is pin 36 (B-Yout) level. GBY2 = 20log (VByt2 / 0.7) (2) Measure GRY2 of R-Y out in the same way as GBY2.

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C ; BUS = preset value ; pin3 = 9V ; pin8:38:41 = 5V)				MEASURING METHOD
		SUB ADDRESS & DATA				
		S26	07H	0FH	11H	
H8	Direct-Delay AC Gain Difference	↑	94H 8CH	—	—	(1) GBYD = GBY1 - GBY2 (2) GRYD = GRY1 - GRY2
H9	Color Difference Output DC Stepping	↑	8CH	—	—	(1) Measure pin 36 (B-Yout) DC stepping of the picture period. (2) Measure pin 35 (R-Yout) DC stepping of the picture period.
H10	1H Delay Quantity	ON	8CH	—	—	(1) Input waveform 2 to pin 33 (B-Yin). And measure the time difference BDt of pin 36 (B-Yout). (2) Input waveform 2 to pin 34 (R-Yin). And measure the time difference RDt of pin 36 (B-Yout).
H11	Color Difference Output DC-Offset Control	↑	8CH	20H	00H 88H FFH	(1) Set Sub-Address 11h ; data 88h. Measure the pin 36 DC voltage, that is BDC1. (2) Set Sub-Address 11h ; data 88h. Measure the pin 35 DC voltage, that is RDC1. (3) Set Sub-Address 11h ; data 00h. Measure the pin 36 DC voltage, that is BDC2. (4) Set Sub-Address 11h ; data 00h. Measure the pin 35 DC voltage, that is RDC2. (5) Set Sub-Address 11h ; data FFh. Measure the pin 36 DC voltage, that is BDC3. (6) Set Sub-Address 11h ; data FFh. Measure the pin 35 DC voltage, that is RDC3. (7) Bomin = BDC2 - BDC1, Bomax = BDC3 - BDC1, Romin = RDC2 - RDC1, Romax = RDC3 - RDC1
H12	Color Difference Output DC-Offset Control / Min. Control Quantity	↑	A4H	00H	89H	(1) Measure the pin 36 DC voltage, that is BDC4. (2) Measure the pin 35 DC voltage, that is RDC4. (3) Bo1 = BDC4 - BDC1, Ro1 = RDC4 - RDC1
H13	NTSC Mode Gain / NTSC-COM Gain	↑	94H	80H	—	(1) Input waveform 1, that is set 0.3V _{p-p} and f = 100kHz, to pin 33. Measure pin 36 output level, that is VBNC. (2) GNB = 20log (VBNC/VB100) (3) In the same way as (1) and (2), measure the pin 36 output level, that is VRNC. GNR = 20log (VRNC/VR100)

TEXT SECTION		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} = 5V ; T _a = 25±3°C ; BUS = preset value)										MEASURING METHOD		
NOTE	ITEM	SW MODE					SUB ADDRESS & BUS DATA							
		S21	S22	S31	S33	S34	S51	—	—	00H	02H	—	—	—
T ₁	Y Color Difference Clamping Voltage	B	B	B	B	A	—	—	FFH	00H	—	—	—	(1) Short circuit pin 31 (Y IN), pin 34 (R-Y IN) and pin 33 (B-Y IN) in AC coupling. (2) Input 0.3V synchronizing signal to pin 51 (Sync IN). (3) Measure voltage at pin 31, pin 34 and pin 33 (Vcp31, Vcp34, Vcp33). (1) Input TG7 sine wave signal whose frequency is 100kHz and video amplitude is 0.7V to pin 31 (Y IN). (2) Input 0.3V Synchronizing Signal to pin 51 (Sync IN). (3) Connect both pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (4) Set bus data so that Y sub contrast and drive are set at each center value and color is minimum. (5) Varying data on contrast from maximum (FF) to minimum (00), measure maximum and minimum amplitudes of respective outputs of pin 14 (R OUT), pin 13 (G OUT) and pin 12 (B OUT) in video period, and read values of bus data at the same time. Also, measure the respective amplitudes with the bus data set to the center value (80). (Vc12mx, Vc12mn, D12c80) (Vc13mx, Vc13mn, D13c80) (Vc14mx, Vc14mn, D14c80) (6) Find ratio between amplitude with maximum unicolor and that with minimum unicolor in conversion into decibel (AV13ct).
T ₂	Contrast Control Characteristic	↑	↑	↑	↑	↑	—	—	—	80H	00H	—	—	In the test condition of Note T ₂ , find output/input gain (double) with maximum contrast. $G = Vc13mx / 0.7V$
T ₃	AC Gain	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; T _a = 25 ± 3°C ; BUS = preset value)										MEASURING METHOD
		SW MODE					SUB ADDRESS & BUS DATA					
S21	S22	S31	S33	S34	S51	—	—	00H	02H	—	—	—
T ₄	Frequency Characteristic	B	B	B	B	A	—	—	FFH	00H	—	—

(1) Input T₇ sine wave signal whose frequency is 6MHz and video amplitude is 0.7V to pin 31 (Y IN).
(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(3) Connect both pin 21 (Digital Y_s) and pin 22 (Analog Y_s) to ground.
(4) Set bus data so that contrast is maximum, Y sub contrast and drive are set at each center value and color is minimum.
(5) Measure amplitude of pin 13 signal (G OUT) and find the output / input gain (double) (G6M).
(6) From the results of the above step 5 and the Note T₃, find the frequency characteristic.
 $G_f = 20\log (G6M / G)$

		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C ; BUS = preset value)										
NOTE	ITEM	SW MODE					SUB ADDRESS & BUS DATA					MEASURING METHOD
		S21	S22	S31	S33	S34	S51	S42	—	00H 02H 05H	1BH 08H	
T5	Y Sub-Contrast Control Characteristic	B	B	B	B	A	—	—	FFH 00H	1FH 00H	—	(1) Connect both pin 21 (Digital Y _S) and pin 22 (Analog Y _S) to ground. (2) Input TG7 sine wave signal whose frequency is 100kHz and video amplitude is 0.7V to pin 31 (Y IN). (3) Input 0.3V synchronizing signal to pin 51 (Sync IN). (4) Set bus data so that contrast is maximum, drive is set at center value and color is minimum. (5) Set bus data on Y sub contrast at maximum (FF) and measure amplitude (V _{scmx}) of pin 14 output (R OUT). Then, set data on Y sub contrast at minimum (00), measure the same (V _{scmn}). (6) From the results of the above step 5, find ratio between V _{scmx} and V _{scmn} in conversion into decibel (ΔV_{scnt}). (1) Set bus data so that contrast is maximum, Y sub contrast and drive are at each center value. (2) Input 0.3V synchronizing signal to pin 51 while inputting TG7 sine wave signal whose frequency is 100kHz to pin 31 (Y IN). (3) While increasing the amplitude of the sine wave signal, measure video amplitude of signal 1 just before R output of pin 14 is distorted. (V _{y2d})
T6	Y ₂ Input Level	↑	↑	↑	↑	↑	—	—	↑	—	—	BFH 44H —

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} = 5V ; T _a = 25±3°C ; BUS = preset value)								SUB ADDRESS & BUS DATA				MEASURING METHOD
		SW MODE				SUB ADDRESS & BUS DATA								
S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₃₄	S ₅₁	S ₄₂	—	00H	02H	05H	1BH	08H	—	
T ₇	Unicolor Control Characteristic	B	B	B	A	—	—	FFH	—	BFH	—	—	—	(1) Input 0.3V synchronizing signal to pin 51 (Sync IN). (2) Input 100kHz, 0.3V p-p sine wave signal to both pin 33 (B-Y IN) and pin 34 (R-Y IN). (3) Connect pin 21 (Digital Y _S) and pin 22 (Analog Y _S) to ground. (4) Set bus data so that drive is at center value and Y mute is on. (5) While changing bus data on unicolor from maximum (FF) to minimum (00), measure maximum and minimum amplitudes of pin 13 (G OUT) and pin 12 (B OUT) in video period respectively, and read the bus data together with., Also, measure respective amplitudes as unicolor data is set at center value (80). (V _{n12mx} , V _{n12mn} , D _{12h80}) (V _{n13mx} , V _{n13mn} , D _{13n80}) (V _{n14mx} , V _{n14mn} , D _{14n80}) (6) Find ratio between amplitude with maximum unicolor data and that with minimum unicolor data in conversion into decibel ($\Delta V13un$).
T ₈	Relative Amplitude (NTSC)	↑	↑	A	A	↑	A	—	FFH	—	—	↑	—	While inputting rainbow color bar signal (3.58MHz for NTSC) to pin 42 and 0.3V synchronizing signal to pin 51 so that video amplitude of pin 33 is 0.38V _{p-p} , find the relative amplitude. (M _{nr-b} = V _{u14mx} / V _{u12mx} , M _{ng-b} = V _{u13mx} / V _{u12mx}) (1) In the test condition of the Note T ₈ , adjust bus data on tint so that output of pin 12 (B OUT) has the peak level in the 6th bar. (2) Regarding the phase of pin 12 (B OUT) as a reference phase, find comparative phase differences of pin 14 (R OUT) and pin 13 (G OUT) from the reference phase respectively (θ_{nr-b} , θ_{ng-b}).
T ₉	Relative Phase (NTSC)	↑	↑	↑	↑	↑	↑	—	—	↑	—	—	↑	—

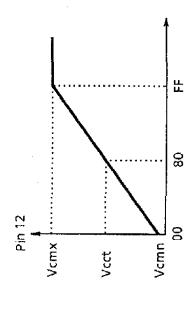
NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} = 5V ; T _a =25±3°C ; BUS = preset value)										MEASURING METHOD	
		SW MODE					SUB-ADDRESS & BUS DATA						
		S21	S22	S31	S33	S34	S51	S42	—	—	00H	02H	1BH
T ₁₀	Relative Amplitude (PAL)	B	B	A	A	A	A	—	FFH	—	BFH	—	—
T ₁₁	Relative Phase (PAL)	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—
T ₁₂	Color Control Characteristic	↑	↑	B	B	↑	—	—	↑	FFH	↑	—	—
T ₁₃	Color Control Characteristic, Residual Color	↑	↑	↑	↑	↑	—	—	↑	00H	↑	—	—

While inputting rainbow color bar signal (4.43MHz for PAL) to pin 42 and 0.3V synchronizing signal to pin 51 so that video amplitude of pin 33 is 0.38V_{p-p}, find the relative amplitude. (M_{pr-b} = Vu14mx/Vu12mx, M_{pg-b} = Vu13mx/Vu12mx)

(1) In the test condition of the Note T₁₀, adjust bus data on tint so that output of pin 12 (B OUT) has the peak level in the 6th bar.

(2) Regarding the phase of pin 12 (B OUT) as a reference phase, find comparative phase differences of pin 14 (R OUT) and pin 13 (G OUT) from the reference phase respectively (θ_{pr-b} , θ_{pg-b}).

(1) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(2) Input 100kHz, 0.1V_{p-p} sine wave signal to both pin 33 (B-Y IN) and pin 34 (R-Y IN).
(3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground.
(4) Set bus data so that unicolor is maximum, drive is at center value and Y mute is on.
(5) Measure amplitude of pin 12 (B OUT) as bus data on color is set maximum (FF). (V_{cmx})
(6) Read bus data when output level of pin 12 is 10%, 50% and 90% of V_{cmx} respectively (Dc10, Dc50, Dc90).
(7) From results of the above step 6, calculate number of steps from Dc10 to Dc90 (Δcol) and that from 00 to Dc50 (ecol).
(8) Measure respective amplitudes of pin 12 (B OUT), pin 13 (G OUT) with color data set at minimum, and regard the results as color residuals (ecb, ecg, ecr).



		TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y / C V _{CC} = 5V ; T _a = 25 ± 3°C ; BUS = preset value ; pin3 = 9V ; pin8-38-41 = 5V)										MEASURING METHOD	
NOTE	ITEM	SW MODE					SUB ADDRESS & BUS DATA						
		S21	S22	S31	S33	S34	S51	S42	—	—	COH 02H 1BH	—	—
T ₁₄	Chroma Input Range	B	B	A	A	A	A	A	—	FFH	88H BFH	—	—

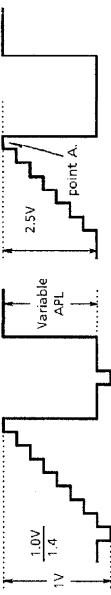
- (1) Input rainbow color bar signal (3.58MHz for NTSC or 4.43MHz for PAL) to pin 42 (C IN) and 0.3V synchronizing signal to pin 51 (Sync IN).
- (2) Connect pin 36 (B-Y OUT) and pin 33 (B-Y IN), pin 35 (R-Y OUT) and pin 34 (R-Y IN) in AC coupling respectively.
- (3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground.
- (4) Set bus data so that unicolor is maximum, drive and color are set at each center value (80) and mute is on.
- (5) While increasing amplitude of chroma signal input to pin 42, measure amplitude just before any of pin 12 (B OUT), pin 13 (G OUT) and pin 14 (R OUT) output signals is distorted (Vcr).

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} =5V ; T _a =25±3°C ; BUS=preset value)								MEASURING METHOD		
		SW MODE				SUB ADDRESS & BUS DATA						
S21	S22	S31	S33	S34	S51	—	—	01H	05H	—	—	—
T15	Brightness Control Characteristic	B	B	B	A	—	—	FFH	10H	—	—	(1) Short circuit pin 31 (Y IN), pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling.
										—	—	(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
										—	—	(3) Set bus data so that R, G, B cut off data are set at center value.
										—	—	(4) Connect pin 21 (Digital Y _s) and pin 22 (Analog Y _s) to ground.
										—	—	(5) While changing bus data on brightness from maximum to minimum, measure video voltage of pin 13 (G OUT) to find maximum and minimum voltages (max : V _{brightx, min} : V _{brightm}).
										—	—	(6) With bus data on brightness set at center value, measure video voltage of pin 13 (G OUT) (V _{bright}).
										—	—	(7) On the condition that bus data with which V _{brightx} is obtained in measurement of the above step 5 is Dbrmx and bus data with which V _{brightm} is obtained in measurement of the above step 5 is Dbrmn, calculate sensitivity of brightness data (ΔV_{bright}).
										—	—	$\Delta V_{bright} = (V_{brightxg} - V_{brightmg}) / (Dbrmx - Dbrmn)$
T16	Brightness Center Voltage	↑	↑	↑	↑	—	—	80H	↑	—	—	(1) In the same manner as the Note T16, measure video voltage of pin 12 (B OUT) with bus data on brightness set at center value.
										—	—	(2) Find maximum axes difference in the brightness center voltage.
T17	Brightness Data Sensitivity	↑	↑	↑	↑	—	—	—	—	—	—	(1) Set bus data so that contrast and Y sub contrast are maximum and brightness is minimum.
										—	—	(2) Input TG7 sine wave signal whose frequency is 100kHz and amplitude in video period is 0.9V to pin 31 (Y IN).
										—	—	(3) Connect pin 21 (Digital Y _s) and pin 22 (Analog Y _s) to ground.
										—	—	(4) While turning on / off WPL with bus, measure video amplitude of pin 14 (R OUT) with WPL being activated (V _{wpl}).
T18	RGB Output Voltage Axes Difference	↑	↑	↑	↑	—	—	—	—	—	—	Pin 14 output waveform
T19	White Peak Limit Level	↑	↑	↑	↑	—	—	—	00H	1FH	—	—

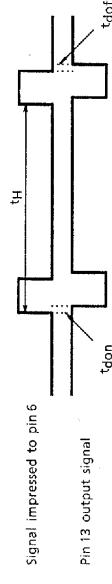
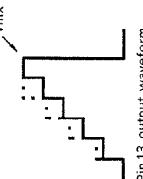
NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25±3°C ; BUS = preset value)										MEASURING METHOD				
		SW MODE					SUB ADDRESS & BUS DATA									
		S21	S22	S31	S33	S34	S51	—	—	09H	0AH	0CH	0DH	0EH	—	
T20	Cutoff Control Characteristic	B	B	B	B	A	—	—	80H	80H	FFH	FFH	FFH	—	(1) Short circuit pin 31 (Y IN), pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling. (2) Input 0.3V synchronizing signal to pin 51 (Sync IN). (3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (4) Set bus data on brightness at center value. (5) While changing data on cutoff from maximum to minimum, measure video voltage of pin 13 (G OUT) to find maximum and minimum values (max : V _{drcx} , min : V _{comm}). (6) Set cutoff data at center value and measure video voltage of pin 13 (G OUT) (V _{cuct}). (7) On the condition that bus data with which V _{comm} is obtained in measurement of the above step 5 is Dcomx and bus data with which V _{comm} is obtained in the same is Dcomm, calculate number of steps (Δ Dcut). Δ Dcut = Dcomx - Dcomm	
T21	Cutoff Center Level	↑	↑	↑	↑	↑	↑	—	—	↑	80H	80H	80H	—		
T22	Cutoff Variable Range	↑	↑	↑	↑	↑	—	—	—	—	—	—	—	—		
T23	Drive Variable Range	↑	↑	↑	↑	↑	↑	—	—	FFH	FFH	80H	80H	80H	—	(1) Short circuit pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling. (2) Input a stepping signal whose amplitude in video period is 0.3V to pin 31 (Y IN). (3) Input 0.3V synchronizing signal to pin 51 (Sync IN). (4) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (5) Set bus data so that contrast is maximum and Y sub contrast is minimum. (6) While changing drive data from minimum to maximum, measure video amplitude of pin 13 (G OUT) to find maximum and minimum values (max : V _{drcx} , min : V _{drcm}). (7) Set drive data at center value and measure video amplitude of pin 13 (G OUT) (V _{drcx}). Calculate amplitude ratio of the measured value to the maximum and minimum amplitudes measured in the above step 6 respectively (DR+, DR-).

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB $V_{CC} = 9V$; $V_{DD}, Fsc V_{DD}, Y/C V_{CC} = 5V$; $T_a = 25 \pm 3^\circ C$; BUS = preset value)										MEASURING METHOD	
		SUB-ADDRESS & BUS DATA		SW MODE									
S21	S22	S31	S33	S34	S51	S45	S39	S44	—	—	—	—	—
T24	DC Regeneration	B	B	A	B	A	B	A	—	—	—	—	—
T25	RGB Output S/N Ratio	↑	↑	B	↑	↑	↑	—	—	—	—	—	—

(1) Short circuit pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling.
(2) Input such the step-up signal as shown below to pin 45 (Y IN) and pin 51 (Sync IN).
(3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground.
(4) Set bus data so that contrast is maximum and DC transmission correction factor is minimum.
(5) Adjust data on Y sub contrast so that video amplitude of pin 13 (G OUT) is 2.5V.
(6) While varying APL of the step-up signal from 10% to 90%, measure change in voltage at the point A.



(1) Short circuit pin 31 (Y IN), pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling.
(2) Input synchronizing signal of 0.3V in amplitude to pin 51 (Sync IN).
(3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground.
(4) Set bus data on contrast at maximum.
(5) Set bus data on Y sub contrast at center value (no).
(6) Measure video noise level of pin 13 (G OUT) with oscilloscope
 $SNo = -20\log (2.5 / (1/5) \times no)$

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V : V _{DD} , F _{SC} V _{DD} , Y/C V _{CC} = 5V ; T _a = 25 ± 3°C ; BUS = preset value)										MEASURING METHOD			
		SW MODE					SUB ADDRESS & BUS DATA								
		S21	S22	S31	S33	S34	S51	—	—	01H	05H	08H	0CH	0DH	0EH
T26	Blanking Pulse Output Level	B	B	B	B	A	—	—	80H	10H	04H	80H	80H	(1) Input synchronizing signal of 0.3V in amplitude to pin 51 (Sync IN). (2) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (3) Set bus data so that blanking is on. (4) Measure voltage of pin 13 (G OUT) in V. blanking period (V _y). (5) Measure voltage of pin 13 (G OUT) in H. blanking period (V _h). In the setting condition of the Note T26, find "t _{d'on} " and "t _{d'off} " (see figure below) between the signal impressed to pin 6 (BFP IN) and output signal of pin 13 (G OUT).	
T27	Blanking Pulse Delay Time	↑	↑	↑	↑	↑	—	—	↑	↑	↑	↑	↑		
T28	RGB Min. Output Level	↑	↑	↑	↑	↑	—	—	00H	↑	↑	00H	00H	(1) Short circuit pin 31 (Y IN), pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling. (2) Input synchronizing signal of 0.3V in amplitude to pin 51 (Sync IN). (3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (4) Set bus data so that brightness and RGB cutoff are minimum. (5) Measure video voltage of pin 13 (G OUT) (V _{mn}). (1) Short circuit pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling. (2) Input stepping signal to pin 31 (Y IN) and synchronizing signal of 0.3V in amplitude to pin 51 (Sync IN). (3) Connect pin 21 (Digital Ys) and pin 22 (Analog Ys) to ground. (4) Set bus data so that contrast and Y sub contrast are maximum. (5) While increasing amplitude of the stepping signal, measure maximum output level just before video signal of pin 13 (G OUT) is distorted (V _{mn}).	
T29	RGB Max. Output Level	↑	↑	↑	↑	↑	—	—	80H	1fH	44H	80H	80H		

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; EU5 = preset value)												MEASURING METHOD
		SW MODE			SUB-ADDRESS & BUS DATA									
S18	S19	S20	S21	S22	S31	S33	S34	S51	15H	1CH	—	—	—	—
T30	Halftone Ys Level	B	B	A	B	B	B	A	00H	80H	—	—	—	—
T31	Halftone Gain 1	↑	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	(1) Input stepping signal whose amplitude is 0.3V in video period to pin 31 (Y IN) and pin 51 (Sync IN). (2) Set bus data so that blanking is off and halftone is -3dB in on status. (3) Connect power supply to pin 21 (Digital Ys). While impressing 0V to it, measure amplitude and pedestal level of pin 13 (G OUT) in video period (Vm13, Vp13). (4) Raising supply voltage to pin 21 gradually from 0V, measure level (Vtht1) of pin 21 when amplitude of pin 13 output signal changes. At the same time, measure amplitude and pedestal level of pin 13 in video period after the pin 13 output signal changed in amplitude. (Vm13b, Vp13b) (5) According to results of the above steps 3 and 4, calculate gain of -3dB halftone and variation of pedestal level. G3ht13 = 20log (Vm13b / Vm13) (6) Set bus data so that halftone is -6dB in on status, and perform the same measurement as the above steps 4 and 5 to find gain of -6dB halftone and variation of pedestal level (G6ht13). (7) Raising supply voltage to pin 21 further from Vtht1, measure level (Vtx1) of pin 21 when output signal of pin 13 (G OUT) changes in amplitude and DC level of pin 13 after the change of its output (Vtx13). (8) From results of the above steps 3 and 7, calculate low level of the output in the text mode. Vtxl13 = Vtx13 - Vp13 (9) Raising supply voltage to pin 21 by 3V from that in the above step 7, confirm that there is no change in output level of pin 13.
T32	Halftone Gain 2	↑	↑	↑	↑	↑	↑	↑	01H	↑	—	—	—	—
T33	Text ON Ys, Low Level	↑	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—
T34	Text/OSD Output, Low Level	↑	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; T _a =25±3°C ; BUS = preset value)										MEASURING METHOD	
		SW MODE					SUB ADDRESS & BUS DATA						
S ₈	S ₁₉	S ₂₀	S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₅₁	—	15H	1CH	—	—	—
T35	Text RGB Output, High Level	A	A	A	B	B	B	—	02H	80H	—	—	—
T36	OSD Ys ON, Low Level	↑	↑	↑	↑	↑	↑	—	↑	↑	—	—	—
T37	OSD RGB Output, High Level	↑	↑	↑	↑	↑	↑	↑	—	↑	↑	—	—

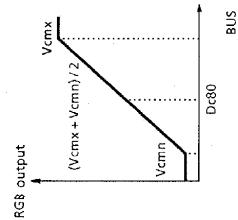
(1) Input stepping signal whose amplitude is 0.3V in video period to pin 31 (Y IN) and pin 51 (Sync IN).
 (2) Set bus data so that blanking and halftone are off.
 (3) Connect power supply to pin 21 (Digital Ys). While impressing 0V to it, measure pedestal level of pin 13 output signal (G OUT) (V_{p13}).
 (4) Connect power supply to pin 19 (Digital G IN) and impress it with 2V.
 (5) Raising supply voltage to pin 21 gradually from 0V, measure video level of pin 21 after output signal of pin 13 changed (V_{lx13}).
 (6) From measurement results of the above steps 3 and 5, calculate high level in the test mode.
 $V_{mt13} = V_{lx13} - V_{pt13}$
 (7) Raising supply voltage to pin 21 further from that in the step 5, measure level (V_{host}) of pin 21 when the level of pin 13 output signal changes from that in the step 5 to -6dB as halftone data is set to ON (the 6th step of Notes T30 to T34).
 (8) In the condition of the above step 7, raise voltage impressed to pin 19 to 3V and measure output voltage of pin 13 (V_{ost13}).
 (9) From results of the above steps 3 and 7, calculate high level of the output in the OSD mode.
 $V_{mos13} = V_{os13} - V_{pt13}$

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; T _a = 25±3°C ; BUS = preset value)												MEASURING METHOD
		SW MODE			SUB-ADDRESS & BUS DATA									
S ₁₈	S ₁₉	S ₂₀	S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₃₄	S ₅₁	—	—	—	—	—	
T38	Text Input Threshold Level	A	A	A	B	B	B	A	—	—	—	—	—	(1) Connect power supply to pin 21 (Digital Y _s) and impress 1.5V to it. (2) Connect power supply to pin 19 (Digital G IN). While raising supply voltage gradually from 0V, measure supply voltage when output signal of pin 13 (G OUT) changes (V _{txt}). (3) Raising the supply voltage to pin 19 furthermore to 4V, confirm that there is no change in the output signal of pin 13 (G OUT).
T39	OSD Input Threshold Level	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	(1) Connect power supply to pin 21 (Digital Y _s) and impress 2.5V to it. (2) Connect power supply to pin 19 (Digital G IN). While raising supply voltage gradually from 0V, measure supply voltage when output signal of pin 13 (G OUT) changes (V _{osd}). (3) Raising the supply voltage to pin 19 furthermore to 4V, confirm that there is no change in the output signal of pin 13 (G OUT).

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; BUS = preset value)										SUB-ADDRESS & BUS DATA	MEASURING METHOD	
		S ₁₈	S ₁₉	S ₂₀	S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₃₄	S ₅₁	—	—	—	
T40	OSD Mode Switching Rise-Up Time	A	A	B	B	B	A	—	—	—	—	—	—	(1) Input a Signal Shown by (a) in the following figure to pin 21 (Digital Ys).
T41	OSD Mode Switching Rise-Up Transfer Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(2) According to (b) in the figure, measure τ_{ROS} , t_{PROs} , τ_{FOS} and t_{PFos} for output signals of pin 14 (R OUT), pin 13 (G OUT) and pin 12 (B OUT) respectively.
T42	OSD Mode Switching Rise-Up Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(3) Find maximum values of t_{PRos} and t_{PFos} respectively (Δt_{PFos}).
T43	OSD Mode Switching Breaking Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(a)
T44	OSD Mode Switching Breaking Transfer Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(b)
T45	OSD Mode Switching Breaking Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(c)

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y / C V _{CC} = 5V ; T _a = 25 ± 3°C ; EUS = preset value)										SUB-ADDRESS & BUS DATA	MEASURING METHOD	
		SW MODE												
S18	S19	S20	S21	S22	S31	S33	S34	S51	—	—	—	—	—	—
T46	OSD Hi DC Switching Rise-Up Time	A	A	A	B	B	B	A	—	—	—	—	—	(1) Supply pin 21 (Digital Y5) with 2.5V. (2) Input 5V _{p-p} signal shown by (a) in the figure to pin 18 (Digital R IN).
T47	OSD Hi DC Switching Rise-Up Transfer Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(3) Referring to (b) of the following figure, measure τ_{Roh} , t_{Roh} , τ_{Foh} and t_{Foh} for output signal of pin 14 (R OUT). (4) Input 5V _{p-p} signal shown by (a) in the figure to pin 19 (Digital G IN).
T48	OSD Hi DC Switching Rise-Up Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(5) Perform the same measurement as the above step 3 for pin 13 output (G OUT) referring to (b) of the following figure. (6) Input 5V _{p-p} signal shown by (a) in the figure to pin 20 (Digital I B IN). (7) Perform the same measurement as the above step 3 for pin 12 output (B OUT) referring to (b) of the following figure. (8) Find maximum axes differences in t_{Roh} and t_{Foh} among the three outputs (Δt_{Roh} , Δt_{Foh}).
T49	OSD Hi DC Switching Breaking Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(a)
T50	OSD Hi DC Switching Breaking Transfer Time	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	(b)
T51	OSD Hi DC Switching Breaking Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C ; BUS = preset value)										MEASURING METHOD
		SW MODE					SUB-ADDRESS & BUS DATA					
S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₃₄	S ₅₁	—	—	06H	—	—	—	—
T52	RGB Contrast Control Characteristic	B	A	B	B	A	—	FFH	—	—	—	(1) Input 0.3V synchronizing signal to pin 51 (Sync IN). (2) Supply 5V of external supply voltage to pin 22 (Analog Y _S). (3) Set bus data on drive at center value. (4) Input TG7 sine wave signal (f = 100kHz, video amplitude = 0.5V) to pin 23 (Analog R IN). (5) While changing data on RGB contrast from maximum (FF) to minimum (00), measure maximum and minimum amplitudes of pin 14 (R OUT) in video period. At the same time, measure video amplitude of pin 14 when the bus data is set at the center value (80). (Vc14mx, Vc14mn, D14c80) (6) In the same manner as the above steps 4 and 5, measure output signal of pin 13 with input of the same external power supply to pin 24 (Analog G IN), and measure output signal of pin 12 with input of the same power supply to pin 25 (Analog B IN). (Vc12mx, Vc12mn, D12c80). (7) Find amplitude ratio between signal with maximum unicolor data and signal with minimum unicolor data in conversion into decibel (ΔV_{13ct}).



NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , F _{SC} V _{DD} , Y / C V _{CC} = 5V ; Ta = 25 ± 3°C ; EUS = preset value)										MEASURING METHOD
		SW MODE					SUB-ADDRESS & BUS DATA					
S ₂₁	S ₂₂	S ₃₁	S ₃₃	S ₃₄	S ₅₁	—	—	06H	—	—	—	—
T53	Analog RGB AC Gain	B	A	B	B	A	—	—	—	—	—	—
T54	Analog RGB Frequency Characteristic	↑	↑	↑	↑	↑	↑	—	—	FFH	—	—

In the setting condition of the Note T52, calculate output/input gain (double) with contrast data being set maximum.
 $G = V_{C13} \text{mV} / 0.5V$

(1) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(2) Supply 5V of external supply voltage to pin 22 (Analog Y_s).
(3) Input TG7 sine wave signal ($f = 100\text{kHz}$, video amplitude = 0.5V) to pin 24 (Analog G IN).
(4) Set bus data so that contrast is maximum and drive is set at center value.
(5) Measure video amplitude of pin 13 (G OUT) and calculate output / input gain (double) (G6M).
(6) From measurement results of the above step 5 and the preceding Note 53, find frequency characteristic.
 $G_f = 20\log(G6M/G_f)$

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; BUS=preset value)										MEASURING METHOD
		SW MODE					SUB-ADDRESS & BUS DATA					
\$21	\$22	\$31	\$33	\$34	\$51	—	—	01H	06H	—	—	—
T55	Analog RGB Dynamic Range	B	A	B	B	A	—	—	00H	—	—	—
T56	RGB Brightness Control Characteristic	↑	↑	↑	↑	↑	—	—	FFH	—	—	—
T57	RGB Brightness Center Voltage	↑	↑	↑	↑	↑	—	—	00H	—	—	—
T58	RGB Brightness Data Sensitivity	↑	↑	↑	↑	↑	—	—	80H	—	—	—
T59	Analog RGB Mode ON Voltage	↑	↑	↑	↑	↑	—	—	—	—	—	—

(1) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(2) Supply 5V of external supply voltage to pin 22 (Analog Ys).
(3) Set bus data so that contrast is minimum and drive is set at center value.
(4) While inputting stepping signal to pin 24 (Analog G IN), increase video amplitude gradually from 0.
(5) Measure video amplitude of pin 24 when video voltage of pin 13 (G OUT) does not change.

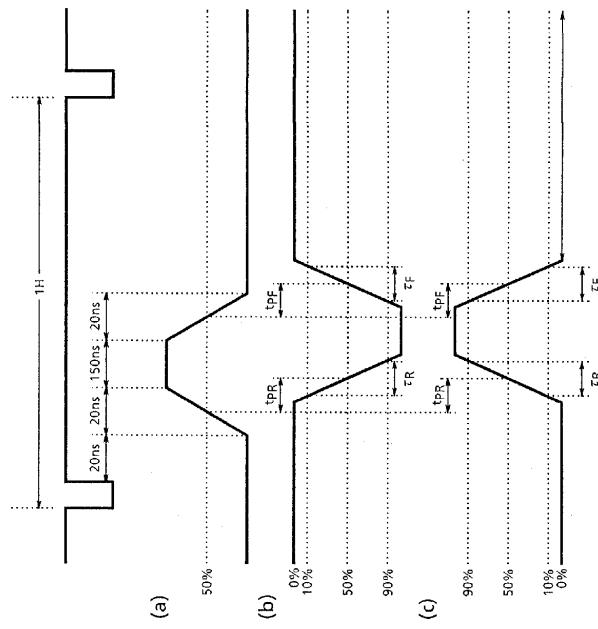
(1) Short circuit pin 31 (Y IN), pin 33 (B-Y IN) and pin 34 (R-Y IN) in AC coupling.
(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(3) Set bus data on RGB cutoff at center value.
(4) Supply 5V of external supply voltage to pin 22 (Analog Ys).
(5) While changing data brightness from maximum to minimum, measure maximum and minimum voltages of pin 13 (G OUT) in video period. (max : V_{bright}, min : V_{bright})
(6) Set bus data on brightness at center value and measure video voltage of pin 13 (G OUT) (V_{bright}).
(7) On the condition that bus data with which V_{bright} is obtained in measurement of the above step 5 is D_{bright} and bus data with which V_{bright} is obtained in measurement of the above step 5 is D_{bright}, calculate sensitivity of brightness data (ΔV_{bright}).

$$\Delta V_{bright} = (V_{bright} - V_{bright}) / (D_{bright} - D_{bright})$$

(1) Input TG7 sine wave signal (f = 100kHz, video amplitude = 0.3V) to pin 23 (Analog R IN).
(2) Supply 5V of external supply voltage to pin 22 (Analog Ys) and raise the voltage gradually from 0V.
(3) Measure voltage at pin 22 when signal 1 is output from pin 14 (R OUT) (V_{bright}).

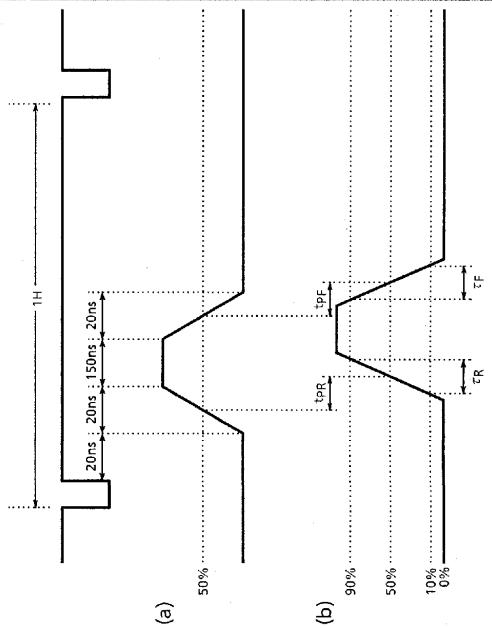
NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} = 9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} = 5V ; T _a = 25 ± 3°C ; BUS = preset value)										SUB-ADDRESS & BUS DATA	MEASURING METHOD	
		SW MODE												
		S ₂₁	S ₂₂	S ₃₁	S ₃₂	S ₃₃	S ₃₄	S ₅₁	—	—	—	—	—	—
T60	Analog RGB Switching Rise-Up Time	B	A	B	B	A	—	—	—	—	—	—	—	—
T61	Analog RGB Switching Rise-Up Transfer Time	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T62	Analog RGB Switching Rise-Up Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T63	Analog RGB Switching Breaking Time	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T64	Analog RGB Switching Breaking Transfer Time	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T65	Analog RGB Switching Breaking Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—

- (1) Supply signal (2V_{p-p}) shown by (a) in the following figure to pin 22 (Analog Y_s).
- (2) Referring to (b) of the following figure, measure τ_{Ran} , τ_{PRan} , τ_{Fan} and τ_{PFan} for outputs of pin 14 (R OUT), pin 13 (G OUT) and pin 12 (B OUT).
- (3) Find maximum values of τ_{PRan} and τ_{PFan} respectively ($\Delta\tau_{PRan}$, $\Delta\tau_{PFan}$).



NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta = 25±3°C ; BUS = preset value)												MEASURING METHOD	
		SW MODE				SUB-ADDRESS & BUS DATA									
		S21	S22	S31	S32	S33	S34	S51	—	—	—	—	—	—	—
T66	Analog RGB Hi Switching Rise-Up Time	B	A	B	B	A	—	—	—	—	—	—	—	—	—
T67	Analog RGB Hi Switching Rise-Up Transfer Time	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T68	Analog RGB Hi Switching Rise-Up Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T69	Analog RGB Hi Switching Breaking Time	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T70	Analog RGB Hi Switching Breaking Transfer Time	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T71	Analog RGB Hi Switching Breaking Transfer Time, 3 Axes Difference	↑	↑	↑	↑	↑	↑	↑	—	—	—	—	—	—	—

(1) Supply 2V to pin 22 (Analog Ys).
(2) Input 0.5V_{p-p} signal shown by (a) in the following figure to pin 23 (Analog R IN).
(3) Referring to (b) of the following figure, measure τ_{Ranh} , t_{PR} , τ_{Fanh} and t_{PFah} for output of pin 14 (R OUT).
(4) Input 0.5V_{p-p} signal shown by (a) in the following figure to pin 24 (Analog G IN).
(5) Referring to (b) of the following figure, perform the same measurement as the above step 3 for output of pin 13 (G OUT).
(6) Input 0.5V_{p-p} signal shown by (a) in the following figure to pin 25 (Analog B IN).
(7) Referring to (b) of the following figure, perform the same measurement as the above step 3 for output of pin 12 (B OUT).
(8) Find maximum axes difference in t_{PR} and t_{PF} among the three outputs (Δt_{PR} , Δt_{PF}).



NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y / C V _{CC} =5V ; Ta = 25±3°C ; BUS = preset value)										MEASURING METHOD
		SW MODE					SUB-ADDRESS & BUS DATA					
S21	S22	S31	S33	S34	S51	—	—	—	—	—	—	(1) Input TG7 sine wave signal ($f=4MHz$, video amplitude = 0.5V) to pin 31 (Y2 IN).
T72	TV-Analog RGB Crosstalk	B	A	B	B	A	—	—	—	—	—	(2) Short circuit pin 25 (Analog G IN) in AC coupling.
T73	Analog RGBTV Crosstalk	↑	↑	↑	↑	↑	—	—	—	—	—	(3) Input 0.3V synchronizing signal to pin 51 (Sync IN).
												(4) Set bus data so that contrast is maximum, Y sub contrast and drive are set at center value.
												(5) Supply pin 22 (Analog Ys) with 0V of external power supply.
												(6) Measure video voltage of output signal of pin 13 (G OUT) (Vtg).
												(7) Supply pin 22 (Analog Ys) with 2V of external power supply.
												(8) Measure video voltage of output signal of pin 13 (G OUT) (Vana).
												(9) From measurement results of the above steps 5 and 7, calculate crosstalk from TV to analog RGB.
												$C_{rtv} = 20 \log \left(\frac{V_{ana}}{V_{tv}} \right)$
												(1) Short circuit pin 31 (Y2 IN), pin 34 (R-Y IN) and pin 33 (B-Y IN) in AC coupling.
												(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
												(3) Set bus data so that contrast is maximum and drive is set at center value.
												(4) Input TG7 sine wave signal ($f=4MHz$, video amplitude = 0.5V) to pin 24 (Analog G IN).
												(5) Supply pin 22 (Analog Ys) with 0V of external power supply.
												(6) Measure video voltage of output signal of pin 13 (G OUT) (Vant).
												(7) Supply pin 22 (Analog Ys) with 2V of external power supply.
												(8) Measure video voltage of output signal of pin 13 (G OUT) (Vtan).
												(9) From measurement results of the above steps 6 and 8, calculate crosstalk from analog RGB to TV.
												$C_{rant} = 20 \log \left(\frac{V_{ant}}{V_{tan}} \right)$

NOTE	ITEM	TEST CONDITION (Unless otherwise specified : H, RGB V _{CC} =9V ; V _{DD} , Fsc V _{DD} , Y/C V _{CC} =5V ; Ta=25±3°C ; EUS = preset value)										MEASURING METHOD	
		SW MODE					SUB ADDRESS & BUS DATA						
		\$21	\$22	\$31	\$33	\$34	\$31	—	—	10H	01H	15H	—
T74	ABL Point Characteristic	B	B	B	B	A	—	—	FFH	90H	—	—	—
									FOH				
T75	ACL Characteristic	↑	↑	↑	↑	↑	—	—	—	—	—	—	—
T76	ABL Gain Characteristic	↑	↑	↑	↑	↑	↑	↑	—	—	FFH	10H	—
									00H	—	—	1CH	—

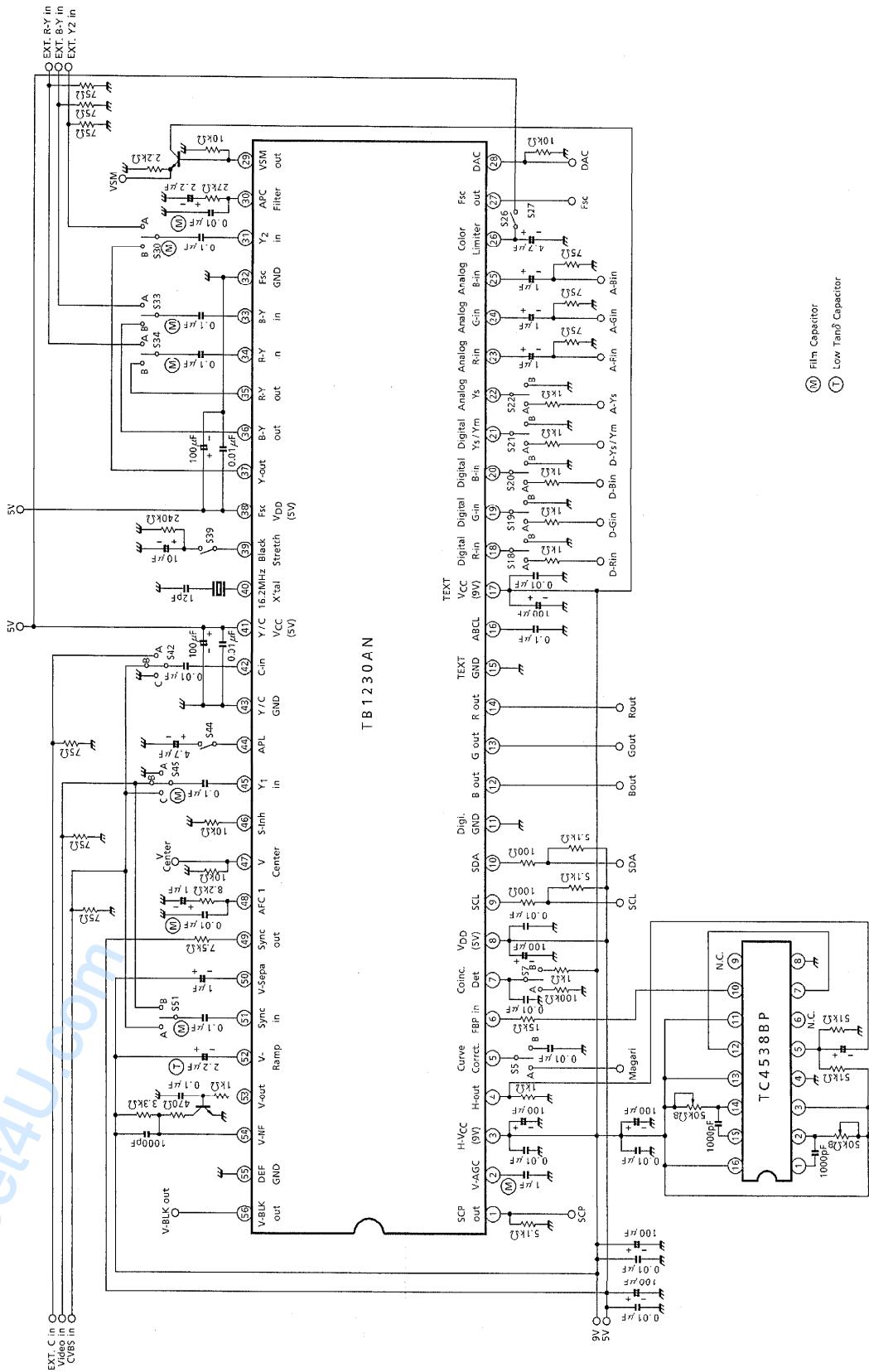
(1) Input TG7 sine wave signal ($f = 4\text{MHz}$, video amplitude = 0.5V) to pin 31 (Y₂ IN).
(2) Short circuit pin 23 (Analog R IN), pin 25 (Analog G IN) and pin 26 (Analog B IN) in AC coupling.
(3) Set bus data so that brightness is maximum and ABL gain is at center value, and supply pin 16 with external supply voltage. While turning down voltage supplied to pin 16 gradually from 7V, measure voltage at pin 16 when the voltage supplied to pin 12 decreases by 0.3V in three conditions that data on ABL point is set at minimum, center and maximum values respectively. (Vabl1, Vablpc, Vabiph)

(1) Input TG7 sine wave signal ($f = 4\text{MHz}$, video amplitude = 0.5V) to pin 31 (Y₂ IN).
(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(3) Measure video amplitude at pin 12. (Vacl1)
(4) Measure DC voltage at pin 16 (ABCL).
(5) Supply pin 16 with a voltage that the voltage measured in the above step 4 minus 2V.
(6) Measure video amplitude at pin 12 (Vacl2) and its ratio to the amplitude measured in the above step 3.
 $Vacl = 20\log(Vacl2/Vacl1)$

(1) Short circuit pin 31 (Y₂ IN), pin 34 (R-Y IN) and pin 33 (B-Y IN) in AC coupling.
(2) Input 0.3V synchronizing signal to pin 51 (Sync IN).
(3) Set bus data on brightness at maximum and measure video DC voltage at pin 12 (Vmax).
(4) Measure voltage at pin 16 which is being supplied with the voltage measured in the step 5 of the preceding Note 75.
(5) Changing setting of bus data on ABL gain at minimum, center and maximum values one after another, measure video DC voltage at pin 12. (Vabl1, Vabl2, Vabl3)
(6) Find respective differences of Vabl1, Vabl2 and Vabl3 from the voltage measured in the above step 3.

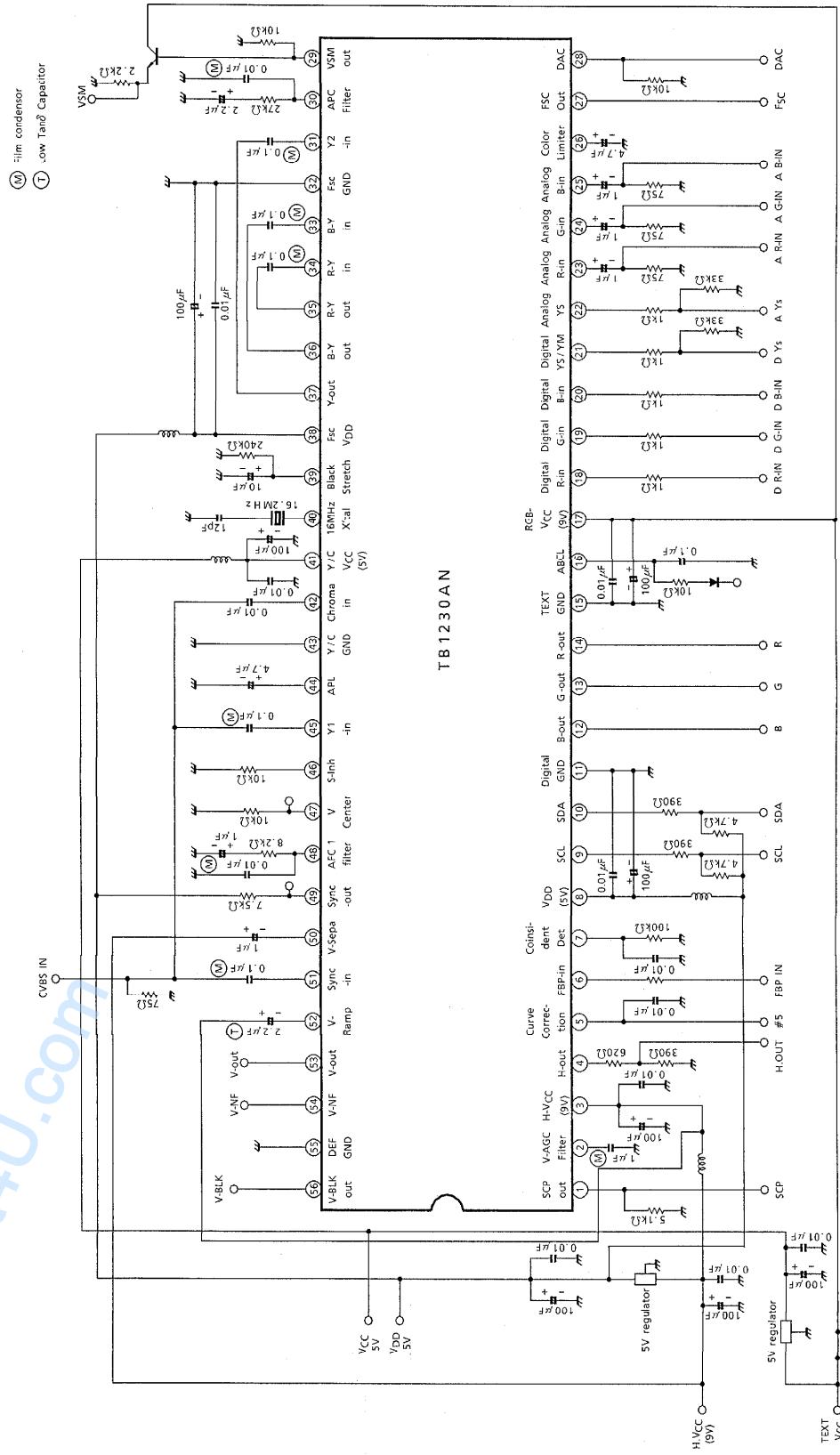
$Vabl1 = Vmax - Vabl1$
 $Vabl2 = Vmax - Vabl2$
 $Vabl3 = Vmax - Vabl3$

TEST CIRCUIT



TB1230AN - 86

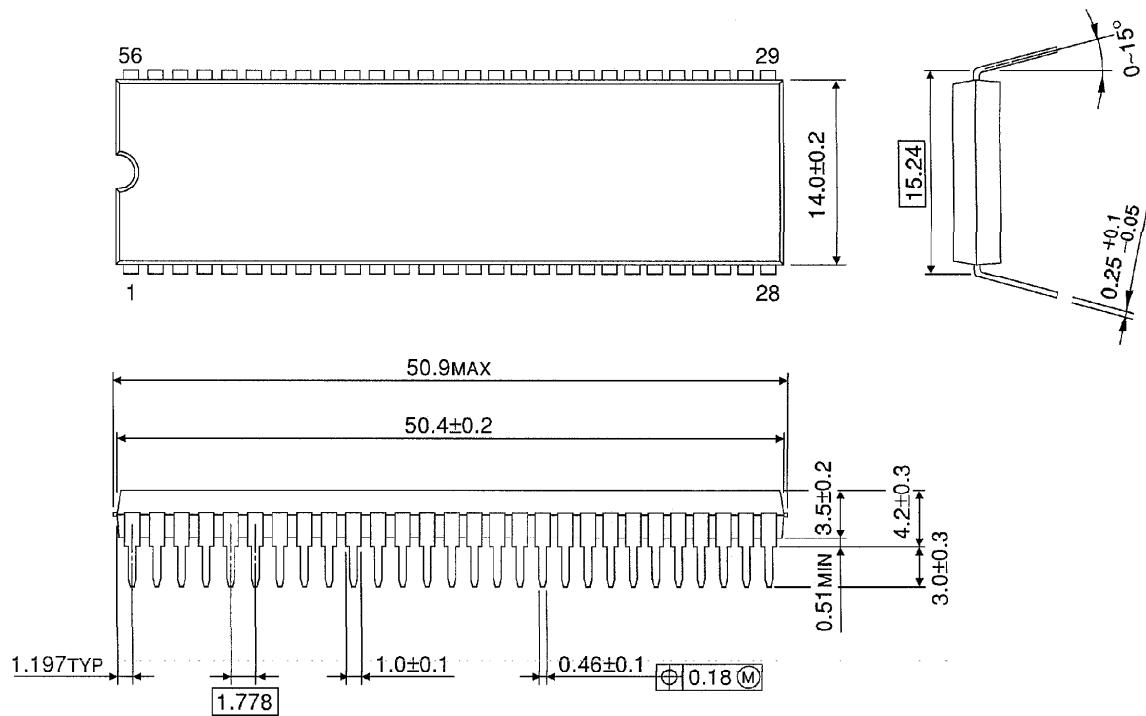
APPLICATION CIRCUIT



OUTLINE DRAWING

SDIP56-P-600-1.78

Unit : mm



Weight : 5.55 (Typ.)