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# TLC59731

Technical

Documents

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# 3-Channel, 8-Bit, PWM LED Driver With Single-Wire Interface (EasySet)

# 1 Features

- Three Sink Current Channels
- Current Capability:
  - 50 mA per Channel
- Grayscale (GS) Control With PWM:
  - 8-Bit (256 Steps) With Simple Gamma Correction
- Single-Wire Interface (EasySet™)
- Power-Supply (VCC) Voltage Range:
  - No Internal Shunt Regulator Mode: 3 V to 5.5 V
  - Internal Shunt Regulator Mode: 3 V to 6 V
- OUT Terminals Maximum Voltage: Up to 21 V
- Integrated Shunt Regulator
- Data Transfer Maximum Rate:
  - Bits per Second (bps): 600 kbps
- Internal GS Clock Oscillator: 6 MHz (Typical)
- Display Repeat Rate: 3.1 kHz (Typical)
- Output Delay Switching to Prevent Inrush Current
- Unlimited Device Cascading
- Operating Temperature: -40°C to 85°C

# 2 Applications

Tools &

Software

RGB LED Cluster Lamp Displays

# 3 Description

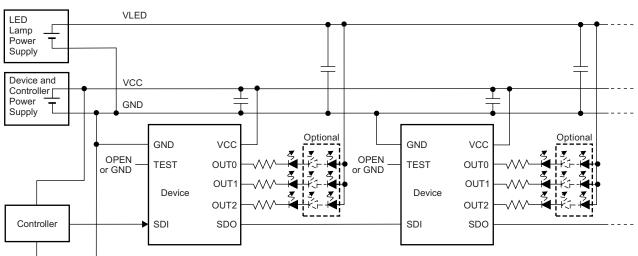
The TLC59731 device is an easy-to-use, 3-channel, 50-mA sink current LED driver. The single-wire, 600kbps serial interface (EasySet) provides a solution for minimizing wiring cost. The LED driver provides 8-bit pulse width modulation (PWM) resolution and a simple gamma correction feature. The display repeat rate is achieved at 3.1 kHz (typical) with an integrated 6-MHz grayscale (GS) clock oscillator. The driver also provides unlimited cascading capability.

Output sink current can be set by each external resistor connected to the OUTn terminal in series. The TLC59731 has an internal shunt regulator that can be used for higher VCC power-supply voltage applications.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TLC59731	SOIC (8)	4.90 mm × 3.91 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



# Typical Application Circuit Example (No Internal Shunt Regulator Mode)

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.



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## 4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### Changes from Revision B (October 2015) to Revision C

#### Page

_	<b>6 ( )</b>	
•	Deleted Constant Sink Current Value section	12
•	Changed the Grayscale (GS) Control description for clarity	13
•	Changed Grayscale (GS) Function (PWM Control) section: corrected number of bits throughout section and corrected Table 2 accordingly	14
•	Added 2nd sentence to 3rd paragraph of Grayscale (GS) Function (PWM Control) section	. 14
•	Changed the PWM Control section to account for a 24-bit GS data latch instead of a 36-bit data latch	. 15
•	Deleted the One-Wire Interface (EasySet) Data Writing Method section from the Device Functional Modes	. 15

#### Changes from Revision A (April 2013) to Revision B

Page

•	Added Pin Configuration and Functions section, ESD Ratings table, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device	
	and Documentation Support section, and Mechanical, Packaging, and Orderable Information section	1
•	Added Grayscale (GS) Control, EasySet and Shunt Regulator, and No Limit Cascading sections	. 13
•	Changed Connector Design title	13
•	Changed Figure 12: changed OUT <i>n</i> traces GSDATA = 4093 and GSDATA = 4094	15

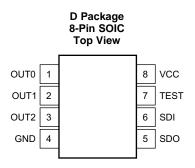
#### Changes from Original (February 2013) to Revision A

•	Added EasySet trademark	. 1
•	Changed bps value in Data Transfer Rate Features bullet	. 1
•	Changed bps value in Description section	. 1
•	Changed AC Characteristics, f <sub>CLK (SDI)</sub> parameter maximum specification in Recommended Operating Conditions table	. 5
•	Changed I <sub>CC1</sub> parameter test conditions in <i>Electrical Characteristics</i> table	. 6
•	Changed second paragraph of Grayscale (GS) Function (PWM Control) section	14
•	Changed Data Transfer Rate (t <sub>CYCLE</sub> ) Measurement Sequence section	16
•	Updated Figure 17	18
•	Updated Figure 20	20
•	Updated Table 3	20

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## 5 Pin Configuration and Functions



#### **Pin Functions**

PIN		1/0	DECODIDION	
NAME	NO.	- I/O	DESCRIPTION	
GND	4	_	Power ground	
OUT0	1	0	Sink driver outputs.	
OUT1	2	0	Multiple outputs can be configured in parallel to increase the sink drive current capability.	
OUT2	3	0	Different voltages can be applied to each output.	
SDI	6	I	erial data input. This pin is internally pulled down to GND with a 1-M $\Omega$ (typical) resistor.	
SDO	5	0	Serial data output	
TEST	7	_	TI internal test terminal. This pin must be connected to GND or left open.	
VCC	8	—	Power-supply voltage	

## 6 Specifications

## 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

			MIN	MAX	UNIT
	Supply, V <sub>CC</sub>	VCC	-0.3	7.0	
Voltage <sup>(2)</sup>	Input, V <sub>IN</sub>	SDI	-0.3	V <sub>CC</sub> + 1.2	V
Voltage	Output, V <sub>OUT</sub>	OUT0 to OUT2	-0.3	21	v
		SDO	-0.3	7.0	
Current	Output (DC), I <sub>OUT</sub>	OUT0 to OUT2	0	60	mA
Tomporatura	Operating junction, T <sub>J</sub>		-40	150	°C
Temperature	Storage temperature, T	- stg	-55	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages are with respect to network ground terminal.

## 6.2 ESD Ratings

			VALUE	UNIT
		Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±8000	
V <sub>(ESD)</sub>	Electrostatic discharge	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±2000	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 6.3 Recommended Operating Conditions

			MIN	NOM	MAX	UNIT
DC CHARA	CTERISTICS					
V <sub>CC</sub>	Supply voltage	No internal shunt regulator mode	3.0	5	5.5	V
		Internal shunt regulator mode			6	
Vo	Voltage applied to output	OUT0 to OUT2			21	V
V <sub>IH</sub>	High-level input voltage	SDI	$0.7 \times V_{CC}$		V <sub>CC</sub>	V
V <sub>IL</sub>	Low-level input voltage	SDI	GND		$0.3 \times V_{CC}$	V
V <sub>IHYST</sub>	Input voltage hysteresis	SDI		$0.2 \times V_{CC}$		V
I <sub>OH</sub>	High-level output current	SDO			-2	mA
	Low lovel output ourrent	SDO			2	~ ^
I <sub>OL</sub>	Low-level output current	OUT0 to OUT2			50	mA
I <sub>REG</sub>	Shunt regulator sink current	VCC			20	mA
T <sub>A</sub>	Operating free-air temperature range		-40		+85	°C
TJ	Operating junction temperature range		-40		+125	°C
AC CHARA	CTERISTICS					
f <sub>CLK (SDI)</sub>	Data transfer rate	SDI	20		600	kHz
t <sub>SDI</sub>	SDI input pulse duration	SDI	275		0.5 / f <sub>CLK</sub>	ns
t <sub>WH</sub>	Pulse duration, high	SDI	14			ns
t <sub>WL</sub>	Pulse duration, low	SDI	14			ns
t <sub>H0</sub>	Hold time: end of sequence (EOS)	SDI↑ to SDI↑	3.5 / f <sub>CLK</sub>		5.5 / f <sub>CLK</sub>	μs
t <sub>H1</sub>	Hold time: data latch (GSLAT)	SDI↑ to SDI↑	8 / f <sub>CLK</sub>			μs

### 6.4 Thermal Information

		TLC59731		
	THERMAL METRIC <sup>(1)</sup>	D (SOIC)	UNIT	
		8 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance	134.6	°C/W	
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	88.6	°C/W	
$R_{\theta JB}$	Junction-to-board thermal resistance	75.3	°C/W	
ΨJT	Junction-to-top characterization parameter	37.7	°C/W	
Ψјв	Junction-to-board characterization parameter	74.8	°C/W	
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	°C/W	

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

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### 6.5 Electrical Characteristics

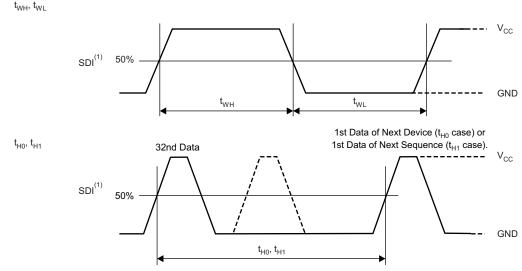
At  $T_A = -40^{\circ}$ C to +85°C,  $V_{CC} = 3$  V to 6.0 V, and  $C_{VCC} = 0.1 \mu$ F. Typical values at  $T_A = 25^{\circ}$ C and  $V_{CC} = 5.0$  V, unless otherwise noted.

	PARAMETER	TEST	CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OH</sub>	High-level output voltage (SDO)	I <sub>OH</sub> = -2 mA		$V_{CC} - 0.4$		V <sub>CC</sub>	V
V <sub>OL</sub>	Low-level output voltage (SDO)	$I_{OL} = 2 \text{ mA}$		0		0.4	V
V <sub>R</sub>	Shunt regulator output voltage (V <sub>CC</sub> )	I <sub>CC</sub> = 1 mA, SDI =	low		5.9		V
I <sub>CC0</sub>			SDI = low, all grayscale n = 0.6 V, SDO = 15 pF		2.3	3.5	mA
I <sub>CC1</sub>	Supply current (V <sub>CC</sub> )	$V_{CC} = 3 \text{ V to } 5.5 \text{V}$ , FFh, $V_{OUTn} = 0.6 \text{ V}$	SDI = 600 kHz, GS <i>n</i> = ', SDO = 15 pF		2.6	4.5	ША
I <sub>OL</sub>	LED output current (OUT0 to OUT2)	All OUT $n = \text{on}, V_{OU}$	<sub>JTn</sub> = 0.6 V	32	40		mA
		0.0	$T_J = -40^{\circ}C \text{ to } +85^{\circ}C$			0.1	
I <sub>OLKG</sub>	Output leakage current (OUT0 to OUT2)	GS <i>n</i> = 00h, V <sub>OUTn</sub> = 21 V	T <sub>J</sub> = +85°C to +125°C			0.2	μA
R <sub>PD</sub>	Internal pulldown resistance (SDI)	At SDI			1		MΩ

### 6.6 Switching Characteristics

At  $T_A = -40^{\circ}$ C to 85°C,  $V_{CC} = 3.0$  V to 5.5 V,  $C_L = 15$  pF,  $R_L = 110 \Omega$ , and  $V_{LED} = 5$  V, unless otherwise noted. Typical values are at  $T_A = 25^{\circ}$ C and  $V_{CC} = 5$  V.

	PARAMETER	TEST CONDITIONS	MIN	NOM	MAX	UNIT
t <sub>R0</sub>	Diag time	SDO	2	6	12	ns
t <sub>R1</sub>	Rise time	$OUTn$ (on $\rightarrow$ off)		200	400	ns
t <sub>F0</sub>	Fall time	SDO	2	6	12	ns
t <sub>F1</sub>	Fail unie	$OUTn$ (off $\rightarrow$ on)		200	400	ns
t <sub>D0</sub>		SDI↑ to SDO↑		30	50	ns
t <sub>D1</sub>	Propagation delay	OUT0↓ to OUT1↓, OUT1↓to OUT2↓, OUT0↑ to OUT1↑, OUT1↑to OUT2↑		25		ns
t <sub>WO</sub>	Shift data output one pulse duration	SDO↑ to SDO↓	75	125	250	ns
f <sub>OSC</sub>	Internal GS oscillator frequency		4	6	8	MHz

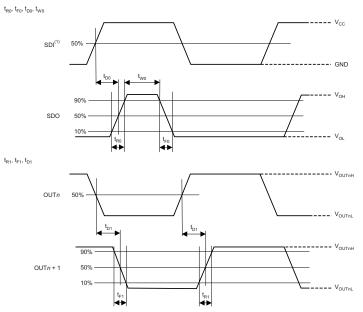


(1) Input pulse rise and fall time is 1 ns to 3 ns.

#### Figure 1. Input Timing

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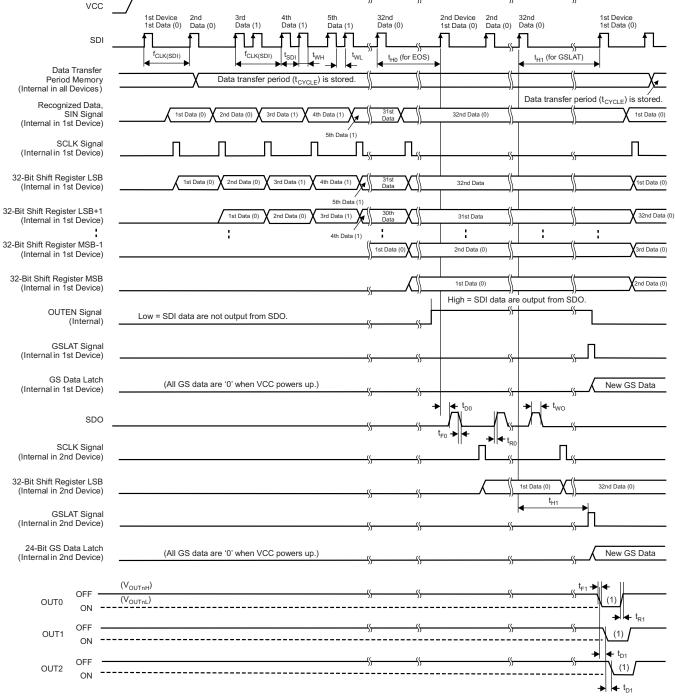




(1) Input pulse rise and fall time is 1 ns to 3 ns.

Figure 2. Output Timing





(1) OUT*n* ON-time changes, depending on the data in the 24-bit GS data latch.

Figure 3. Data Write and Outn Switching Timing

8



## 6.7 Typical Characteristics

at  $T_{\text{A}}$  = 25°C and  $V_{\text{CC}}$  = 12 V (unless otherwise noted)

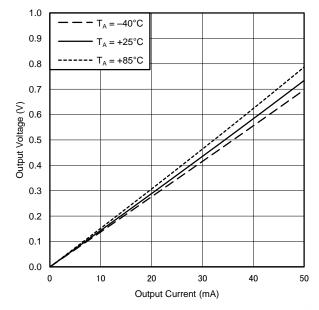
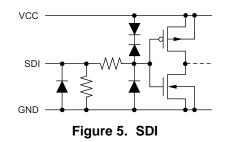
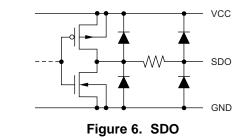


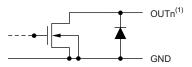
Figure 4. Output Current vs Output Voltage (Outn)

### 7 Parameter Measurement Information

### 7.1 Pin-Equivalent Input and Output Schematic Diagrams



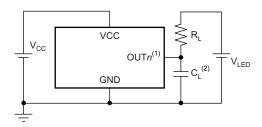








7.2 Test Circuits





(2) C<sub>L</sub> includes measurement probe and jig capacitance.

Figure 8. Rise Time and Fall Time Test Circuit for Out*n* 

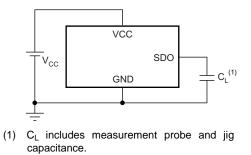


Figure 9. Rise Time and Fall Time Test Circuit for SDO



## 8 Detailed Description

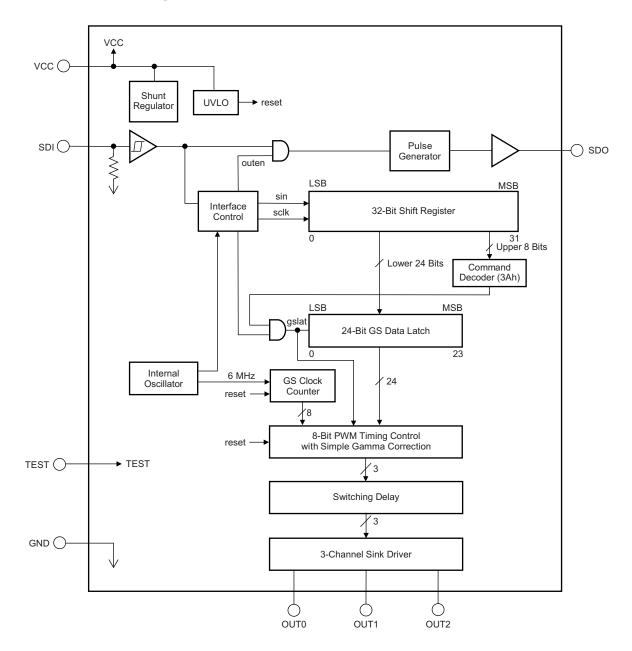
#### 8.1 Overview

The TLC59731 is a 3-channel constant-current sink driver. Each channel has an individually-adjustable, 256step, pulse-width modulation (PWM) grayscale (GS) brightness control. GS data are input through a serial singlewire interface port.

The TLC59731 has a 50-mA current capability. The maximum current value of each channel is determined by the external resistor. The TLC59731 can function without external CLK signals because the device is integrated with a 6-MHz internal oscillator.

The TLC59731 is integrated with a shunt regulator that can be used for higher VCC power-supply voltage applications.

### 8.2 Functional Block Diagram



#### 8.3 Feature Description

#### 8.3.1 Sink Current Value Setting

The typical sink current value of each channel ( $I_{OUTn}$ ) can be set by resistor ( $R_{Ln}$ ) that is placed between the LED cathode and OUT*n* pins; see Figure 10. The typical sink current value can be calculated by Equation 1 and the typical resistor value can be calculated by Equation 2.

$$I_{OUTn} (mA) = \frac{V_{LED} (V) - V_{F_{TOTAL}} (V) - V_{OUTn} (V)}{R_{Ln} (\Omega)}$$

where

$$\mathsf{R}_{\mathsf{Ln}}\left(\Omega\right) = \frac{\mathsf{V}_{\mathsf{LED}}\left(\mathsf{V}\right) - \mathsf{V}_{\mathsf{F}_{\mathsf{TOTAL}}}\left(\mathsf{V}\right) - \mathsf{V}_{\mathsf{OUTn}}\left(\mathsf{V}\right)}{\mathsf{I}_{\mathsf{OUTn}}\left(\mathsf{mA}\right)}$$

where

- n = 0 to 2
- V<sub>LED</sub> = the LED anode voltage
- V<sub>F TOTAL</sub> = the total LED forward voltage
- V<sub>OUTn</sub> = the OUT*n* output voltage

Note that the typical V<sub>OUTn</sub> value is 0.6 V with a 40-mA output current, as shown in Figure 4.

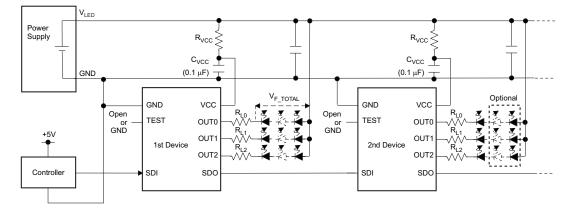


Figure 10. Internal Shunt Regulator Mode Application Circuit

#### 8.3.2 Resistor and Capacitor Value Setting for Shunt Regulator

The TLC59731 internally integrates a shunt regulator to regulate V<sub>CC</sub> voltage. Figure 4 shows an application circuit that uses the internal shunt regulator through a resistor,  $R_{VCC}$ . The recommended  $R_{VCC}$  value can be calculated by Equation 3.

$$\frac{V_{LED}(V) - 5.9 V}{8 \text{ mA}} < R_{VCC} < \frac{V_{LED}(V) - 5.9 V}{6 \text{ mA}}$$

(3)

Table 1 shows the typical resistor value for several V<sub>LED</sub> voltages. Note that the C<sub>VCC</sub> value must be 0.1 µF.

V <sub>LED</sub> (V)	R <sub>VCC</sub> (Ω)	<b>RESISTOR WATTAGE (W)</b>
9	470	0.02
12	910	0.04
18	1800	0.08
24	2700	0.12

(2)

(1)



#### 8.3.3 Grayscale (GS) Control

This control feature is an 8-bit (256-step) grayscale (GS) control that provides a wide range of color generation. Connect the LEDs to the device OUT*n* pins, as described in the *Layout Guidelines* section.

#### 8.3.4 EasySet and Shunt Regulator

This device includes a single-wire serial interface (EasySet) and a shunt regulator. The total number of wires for power supply and data write operations can be reduced with the EasySet and shunt regulator included in the design.

#### 8.3.5 No Limit Cascading

This feature results in no limitation on the number of total cascaded devices used in series in an application. This advantage is attained because a timing-adjusted pulse generator is implemented in the device.

#### 8.3.6 Connector Design

When the connector pin of the device application printed circuit board (PCB) is connected or disconnected to other PCBs, the power must be turned off to avoid device malfunction or failure. Furthermore, designing the connector GND pin to be longer than other pins (as shown in Figure 11) is preferable. This arrangement allows the GND line to either be connected first or disconnected last, which is imperative for proper device function.

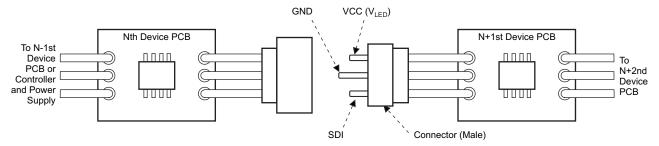


Figure 11. Connector Pin Design Application

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#### 8.4 Device Functional Modes

#### 8.4.1 Grayscale (GS) Function (PWM Control)

The TLC59731 can adjust the brightness of each output channel using a pulse width modulation (PWM) control scheme. The PWM data bit length for each output is 8 bits. The architecture of 8 bits per channel results in 256 brightness steps, from 0% to 99.98% ON-time duty cycle.

The PWM operation for OUT*n* is controlled by an 8-bit grayscale (GS) counter. The GS counter increments on each internal GS clock (GSCLK) rising edge. All OUT*n* are turned on when the GS count is '1', except when OUT*n* are programed to GS data '0' in the 24-bit GS data latch. After turning on, each output turns off when the GS counter value exceeds the programmed GS data for the output. The GS counter resets to 00h and all outputs are forced off when the GS data are written to the 24-bit GS data latch. Afterwards, the GS counter begins incrementing and PWM control is started from the next internal GS clock.

Table 2 summarizes the GS data values versus the output ideal ON-time duty cycle. The on-time duty cycle is not proportional to the GS data because a simple gamma correction is implemented in the TLC59731. Furthermore, actual ON-time differs from the ideal ON-time because the output drivers and control circuit have some timing delay. When the device is powered on, all outputs are forced off and remain off until the non-zero GS data are written to the 24-bit GS data latch.

GS	DATA	NO. OF GSCLKs	NO. OF GSCLKs	TOTAL IDEAL TIME	ON-TIME DUTY (%)		
DECIMAL	HEX	OUT <i>n</i> TURNS ON	OUT <i>n</i> TURNS OFF	(µs)			
0	0	Off	Off	0	0		
1	1	1	2	0.08	0.02		
2	2	1	4	0.17	0.05		
3	3	1	6	0.8	0.3		
—	—	_	—	—	—		
6	6	1	12	1.8	0.6		
7	7	1	14	2.2	0.7		
8	8	1	18	2.8	0.9		
9	9	1	22	3.5	1.1		
10	10	1	26	4.2	1.3		
_		_	_	_	_		
30	1E	1	106	17.5	5.5		
31	1F	1	110	18.2	5.7		
32	20	1	118	19.5	6.2		
33	21	1	126	20.8	6.6		
34	22	1	134	22.2	7.0		
—	—	—	—	—	—		
62	3E	1	358	59.5	18.8		
63	3F	1	366	60.8	19.2		
64	40	1	374	62.2	19.6		
65	41	1	382	63.5	20.0		
66	42	1	390	64.8	20.5		
_	_	_	_	_	_		
127	7F	1	878	146.2	46.1		
128	80	1	886	147.5	46.5		
129	81	1	894	148.8	47.0		
_	—	_	_	_	_		
253	FD	1	1886	314.2	99.1		
254	FE	1	1894	315.5	99.5		
255	FF	1	1902	316.8	99.9		

#### Table 2. Output Duty Cycle and Total ON-Time vs GS Data



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#### 8.4.1.1 PWM Control

The GS counter keeps track of the number of grayscale reference clocks (GSCLKs) from the internal oscillator. Each output stays on when the counter is less than or equal to the programmed GS value. Each output turns off when the GS counter is greater than the GS value in the 24-bit GS data latch. Figure 12 shows the PWM operation timing.

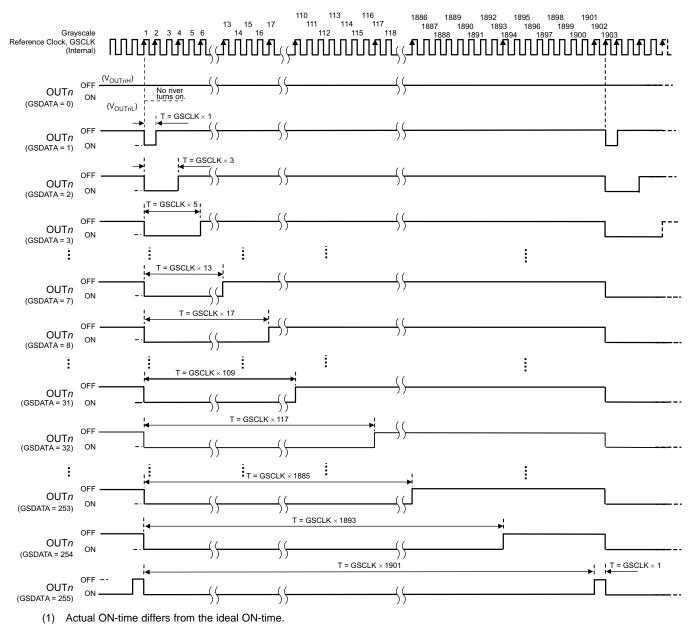


Figure 12. PWM Operation

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#### 8.5 Programming

#### 8.5.1 One-Wire Interface (EasySet) Data Writing Method

There are four sequences to write GS data into the TLC59731 through a single-wire interface. This section discusses each sequence in detail.

#### 8.5.1.1 Data Transfer Rate (T<sub>CYCLE</sub>) Measurement Sequence

The TLC59731 measures the time between the first and second SDI rising edges either after the device is powered up or when the GS data latch sequence is executed (as described in the GS Data Latch Sequence (GSLAT) section) and the time is internally stored as  $t_{CYCLE}$ .  $t_{CYCLE}$  serves as a base time used to recognize one complete data write operation, a 32-bit data write operation, and a GS data write operation to the GS data latch.  $t_{CYCLE}$  can be set between 1.66 µs and 50 µs ( $f_{CLK(SDI)} = 20$  kHz to 600 kHz). In this sequence, two instances of data 0 are written to the LSB side of the 32-bit shift register. Figure 13 shows the  $t_{CYCLE}$  measurement timing.

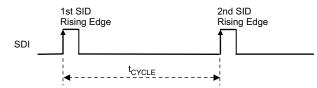


Figure 13. Data Transfer Rate (T<sub>CYCLE</sub>) Measurement

#### 8.5.1.2 Data 0 and Data 1 Write Sequence (Data Write Sequence)

When the second SDI rising edge is not input before 50% of  $t_{CYCLE}$  elapses from the first SDI rising edge input, the second rising edge is recognized as data 0. When the second SDI rising edge is input before 50% of  $t_{CYCLE}$  elapses from the first SDI rising edge input, the second rising edge is recognized as data 1. This write sequence must be repeated 30 times after the  $t_{CYCLE}$  measurement sequence to send the write command to the lower 6-bit (3Ah) and 24-bit GS data. Figure 14 shows the data 0 and 1 write timing.

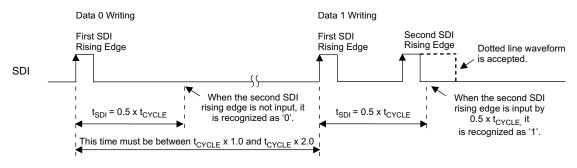


Figure 14. Data 0 and 1 Write Operation



#### **Programming (continued)**

#### 8.5.1.3 One Communication Cycle End of Sequence (EOS)

One communication cycle end of sequence (EOS) must be input after the 32-bit data are written because the TLC59731 does not count the number of input data. When SDI is held low for the EOS hold time ( $t_{H0}$ ), the 32-bit shift register values are locked and a buffered SDI signal is output from SDO to transfer GS data to the next device. Figure 15 shows the EOS timing.

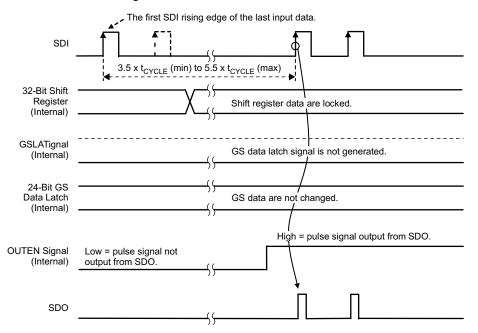


Figure 15. End of Sequence (EOS)



#### **Programming (continued)**

### 8.5.1.4 GS Data Latch (GSLAT) Sequence

A GS data latch (GSLAT) sequence must be input after the 32-bit data for all cascaded devices are written. When SDI is held low for the data latch hold time ( $t_{H1}$ ), the 32-bit shift register data in all devices are copied to the GS data latch in each device. Furthermore, PWM control starts with the new GS data at the same time. Figure 16 shows the GSLAT timing.

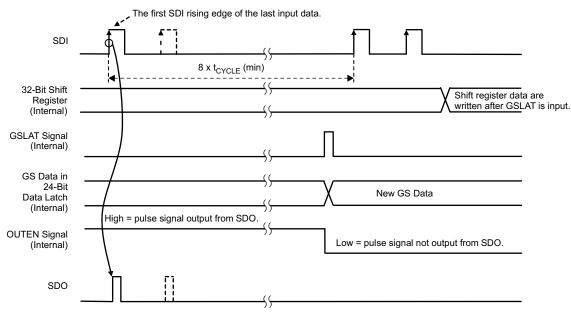
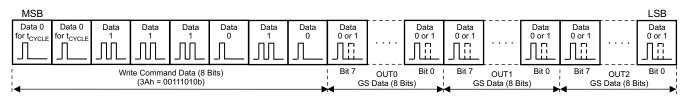


Figure 16. GS Data Latch Sequence (GSLAT)

#### 8.5.1.5 How to Control Devices Connected in Series

The 8-bit write command and 24-bit grayscale (GS) data for OUT0 to OUT2 (for a total of 32 bits of data) must be written to the device. Figure 17 shows the 32-bit data packet configuration. When multiple devices are cascaded (see Figure 18), *N* times the packet must be written into each TLC59731 in order to control all devices. There is no limit on how many devices can be cascaded, as long as proper VCC voltage is supplied. The packet for all devices must be written again whenever any GS data changes.







#### **Programming (continued)**

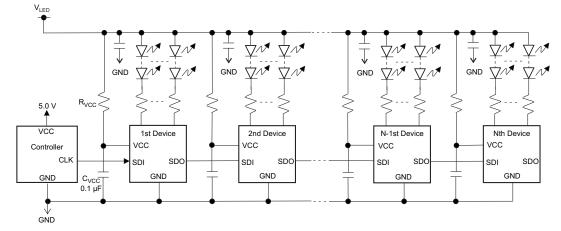


Figure 18. Cascade Connection of NTLC59731 Units (Internal Shunt Regulator Mode)

Figure 19 shows the 32-bit data packet, EOS, and GSLAT input timing of all devices. The function setting write procedure and display control is as follows:

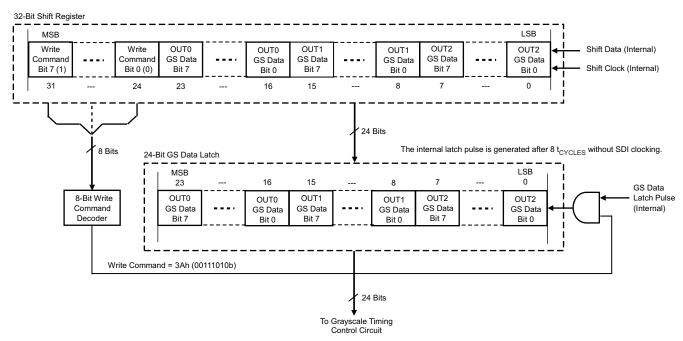
- 1. Power up VCC ( $V_{LED}$ ); all OUT*n* are off because GS data are not written yet.
- 2. Write the 32-bit data packet (MSB-first) for the first device using t<sub>CYCLE</sub> and the data write sequences illustrated in and . The first 8-bits of the 32-bit data packet are used as the write command. The write command must be 3Ah (00111010b); otherwise, the 24-bit GS data in the 32-bit shift register are not copied to the 24-bit GS data latch.
- 3. Execute one communication cycle EOS (refer to ) for the first device.
- 4. Write the 32-bit data packet for the second TLC59731 as described step 2. However, t<sub>CYCLE</sub> must be set to the same timing as the first device.
- 5. Execute one communication cycle EOS for the second device.
- 6. Repeat Steps 4 and 5 until all devices have GS data.
- 7. The number of total bits is 32 × N. After all data are written, execute a GSLAT sequence as described in in order to copy the 24-bit LSBs in the 32-bit shift resister to the 24-bit GS data latch in each device; PWM control starts with the written GS data at the same time.

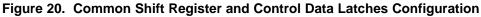
V <sub>LED</sub> Power								<del>_</del> }?						
	MSB	LSE	3	MSB	LS	SB	MSB	<i>, ,</i>	LSI	з і	MSB LSI	3	MSB	LSB
1st Device SDI		ata Packet t Device	EOS		Data Packe 2nd Device	t EO	S For 3rd Device	3	For N-1th	EOS	32-Bit Data Packet for Nth Device	GSLAT	Next Data for 1st D	
								,,						
1st Device SDO					Data Packe 2nd Device	t EO	S For 3rd Device	3	For N-1th	EOS	32-Bit Data Packet for Nth Device	GSLAT		
								,,						
N-2nd Device SDO							For 3rd Device	_(	For N-1st	EOS	32-Bit Data Packet for Nth Device	GSLAT		
								,,						
N-1st Device SDO											32-Bit Data Packet for Nth Device	GSLAT		
								),						
OUTn								_(					ontrol Starts v GS Data	
		Figur	e 19	. Dat	ta Pack	et In	put O	رر rde	er for		_C59731 Unit	S		

#### 8.6 Register Maps

### 8.6.1 Register and Data Latch Configuration

The TLC59731 has a 32-bit shift register and a 24-bit data latch that stores GS data. When the internal GS data latch pulse is generated and the data of the eight MSBs in the shift register are 3Ah, the lower 24-bit data in the 32-bit shift register are copied into the 24-bit GS data latch. If the data of the eight MSBs is not 3Ah, the 24-bit data are not copied into the 24-bit GS data latch. Figure 20 shows the shift register and GS data latch configurations. Table 3 shows the 32-bit shift register bit assignment.





BIT	BIT NAME	CONTROLLED CHANNEL AND FUNCTIONS
0 to 7	GSOUT2	GS data bits 0 to 7 for OUT2
8 to 15	GSOUT1	GS data bits 0 to 7 for OUT1
16 to 23	GSOUT0	GS data bits 0 to 7 for OUT0
24 to 32	WRTCMD	Data write command (3Ah) for GS data. The lower 24-bit GS data in the 32-bit shift register are copied to the GS data latch when the internal GS latch is generated (when these data bits are 3Ah, 00111010b).

#### Table 3. 32-Bit Shift Register Data Bit Assignment



## 9 Application and Implementation

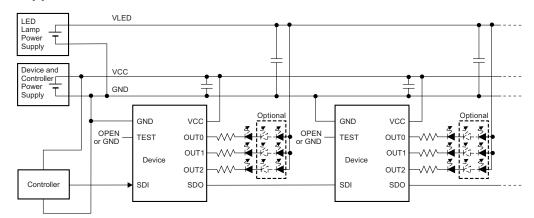
#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 9.1 Application Information

The device is a 3-channel, constant sink current, LED driver. This device can be connected in series to drive many LED lamps with only a few controller ports. Output current control data and PWM control data can be written from the SIN input terminal. The PWM timing reference clock can be supplied from the internal oscillation.

#### 9.2 Typical Application





#### 9.2.1 Design Requirements

For this design example, use Table 4 as the input parameters.

#### **Table 4. Design Parameters**

DESIGN PARAMETER	EXAMPLE VALUE				
VCC Input Voltage Range	3 V to 5.5 V				
LED Lamp (V <sub>LED</sub> ) Input Voltage Range	21 V Maximum				
SDI Voltage Range	Low Level = GND, High Level = VCC				

#### 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Define Basic Parameters

To begin the design process, a few parameters must be decided:

- Maximum output constant-current value for each color LED lamp
- Maximum LED forward voltage (Vf) and Maximum V<sub>LED</sub>
- Total LEDs and Cascaded IC Number

#### 9.2.2.2 Grayscale (GS) Data

32-bit GS data packets are sent through single-wire interface for the PWM control of three output channels. Select the GS data of each LED lamp and write the GS data to the register following the signal timing.

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#### TLC59731

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#### 9.2.3 Application Curve

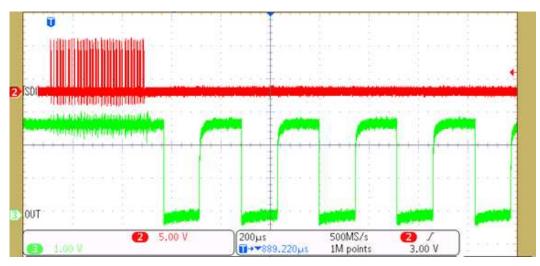
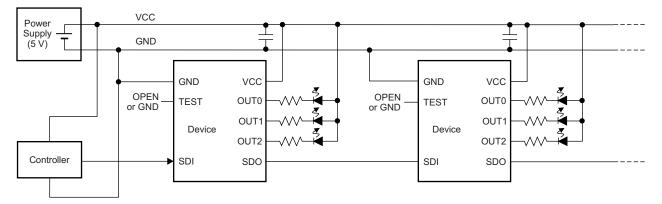
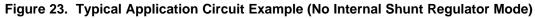


Figure 22. Output Waveform Without GS Data Latch Input

## 9.3 System Examples





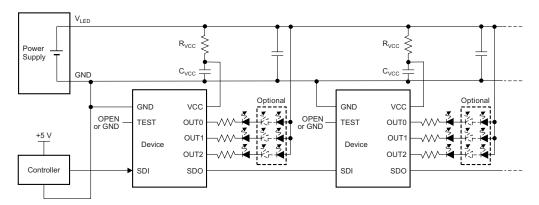


Figure 24. Typical Application Circuit Example (Internal Shunt Regulator Mode)



#### 9.4 Do's and Don'ts

When the connector pin of the device application printed-circuit-board (PCB) is connected or disconnected to other PCBs, the power must be turned off to avoid device malfunction or failure. Furthermore, designing the connector GND pin to be longer than other pins (as shown in Figure 25) is preferable. This arrangement allows the GND line to either be connected first or disconnected last, which is imperative for proper device function.

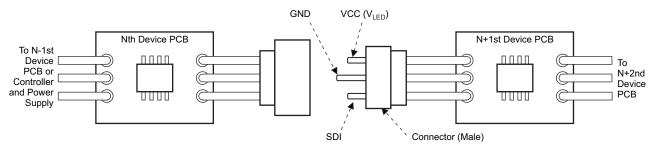


Figure 25. Connector Pin Design Application

## **10 Power Supply Recommendations**

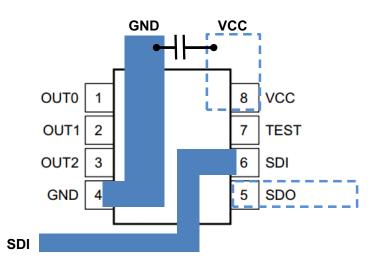
Decouple the  $V_{cc}$  power supply voltage by placing a 0.1-µF ceramic capacitor close to VCC pin and GND plane. Depending on panel size, several electrolytic capacitors must be placed on board equally distributed to get a well regulated LED supply voltage (V<sub>LED</sub>). V<sub>LED</sub> voltage ripple must be less than 5% of its nominal value.

### 11 Layout

#### 11.1 Layout Guidelines

- 1. Place the decoupling capacitor near the VCC pin and GND plane.
- 2. Route the GND pattern as widely as possible for large GND currents.
- 3. Routing wire between the LED cathode side and the device OUTn pin must be as short and straight as possible to reduce wire inductance.
- 4. When several ICs are chained, symmetric placements are recommended.

#### 11.2 Layout Example





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# **12 Device and Documentation Support**

# 12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

# 12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E<sup>™</sup> Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

## 12.3 Trademarks

EasySet, E2E are trademarks of Texas Instruments. All other trademarks are the property of their respective owners.

# 12.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# 12.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



11-Jan-2016

# PACKAGING INFORMATION

Orderable Device	Status	Package Type	•	Pins	•	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
TLC59731D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	59731	Samples
TLC59731DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-40 to 125	59731	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW**: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(<sup>6)</sup> Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE OPTION ADDENDUM

11-Jan-2016

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

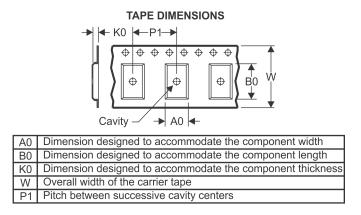
# PACKAGE MATERIALS INFORMATION

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## TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nomi
--------------------------

Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TLC59731DR	SOIC	D	8	2500	330.0	12.5	6.4	5.2	2.1	8.0	12.0	Q1

TEXAS INSTRUMENTS

www.ti.com

# PACKAGE MATERIALS INFORMATION

18-Oct-2016



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TLC59731DR	SOIC	D	8	2500	340.5	338.1	20.6

# D0008A



# **PACKAGE OUTLINE**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



#### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.

- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



# D0008A

# **EXAMPLE BOARD LAYOUT**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# D0008A

# **EXAMPLE STENCIL DESIGN**

# SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

9. Board assembly site may have different recommendations for stencil design.



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