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- Organization:
 - TM4SP64KPU . . . 4 194 304 x 64 Bits
 - TM8SP64KPU . . . 8 388 608 x 64 Bits
- Single 3.3-V Power Supply (±10% Tolerance)
- Designed for 66-MHz 4-Clock Systems
- JEDEC 168-Pin Dual-In-Line Memory Module (DIMM) Without Buffer for Use With Socket
- TM4SP64KPU Uses Four 64M-Bit Synchronous Dynamic RAMs (SDRAMs) (4M × 16-Bit) in Plastic Thin Small-Outline Packages (TSOPs)
- TM8SP64KPU Uses Eight 64M-Bit SDRAMs (4M × 16-Bit) in Plastic TSOPs
- Byte-Read/Write Capability
- Performance Ranges:

	SYNCHE	RONOUS	ACCES	S TIME	REFRESH
	CLOCK	CYCLE	CLO	CK TO	INTERVAL
	TII	ME	OUT	PUT	
	tCK3	tCK2	t _{AC3}	t _{AC3}	t _{REF}
'xSP64KPU-10	10 ns	15 ns	9 ns	9 ns	04
'xSP64KPU-12	12 ns	15 ns	9.5 ns	9.5 ns	64 ms

- High-Speed, Low-Noise Low-Voltage TTL (LVTTL) Interface
- Read Latencies 2 and 3 Supported
- Support Burst-Interleave and Burst-Interrupt Operations
- Burst Length Programmable to 1, 2, 4, 8, and Full Page
- Four Banks for On-Chip Interleaving (Gapless Access)
- Ambient Temperature Range 0°C to 70°C
- Gold-Plated Contacts
- Pipeline Architecture
- Serial Presence-Detect (SPD) Using EEPROM

description

The TM4SP64KPU is a 32M-byte, 168-pin dual-in-line memory module (DIMM). The DIMM is composed of fourTMS664164DGE, 4194304 x 16-bit SDRAMs, each in a 400-mil, 54-pin plastic thin small-outline package (TSOP) mounted on a substrate with decoupling capacitors. See the TMS664164 data sheet (literature number SMOS690).

The TM8SP64KPU is a 64M-byte, 168-pin DIMM. The DIMM is composed of eight TMS664164DGE, 4194304 x 16-bit SDRAMs, each in a 400-mil, 54-pin plastic TSOP mounted on a substrate with decoupling capacitors. See the TMS664164 data sheet (literature number SMOS690).

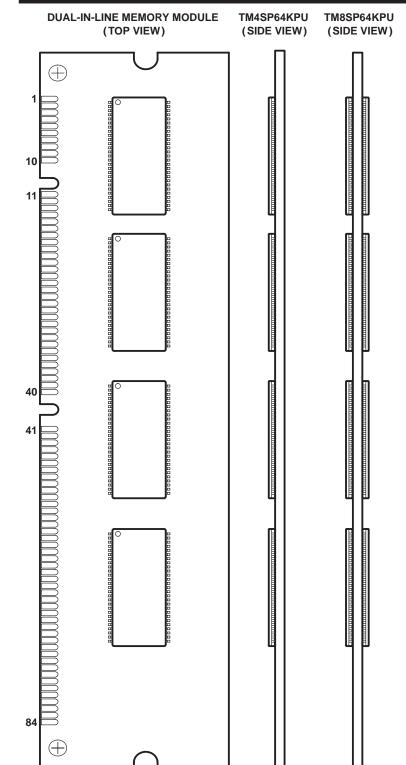
operation

The TM4SP64KPU operates as four TMS664164DGE devices that are connected as shown in the TM4SP64KPU functional block diagram. The TM8SP64KPU operates as eight TMS664164DGE devices connected as shown in the TM8SP64KPU functional block diagram.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





PIN NOMENCLATURE							
A[0:11]	Row Address Inputs						
A[0:7]	Column Address Inputs						
A13/BA0	Bank-Select Zero						
A12/BA1	Bank-Select One						
CAS	Column-Address Strobe						
CKE[0:1]	Clock Enable						
CK[0:3]	System Clock						
DQ[0:63]	Data-In/Data-Out						
DQMB[0:7]	Data-In/Data-Out						
	Mask Enable						
NC	No Connect						
RAS	Row-Address Strobe						
S[0:3]	Chip-Select						
SA[0:2]	Serial Presence-Detect (SPD)						
	Device Address Input						
SCL	SPD Clock						
SDA	SPD Address/Data						
V_{DD}	3.3-V Supply						
<u>Vss</u>	Ground						
WE	Write Enable						

Pin Assignments

	DIN	П	DIN	1	DIN	11	DIN
NO.	PIN NAME	NO.	PIN NAME	NO.	PIN NAME	NO.	PIN NAME
1	V _{SS}	43	VSS	85	V _{SS}	127	V _{SS}
2	DQ0	44	NC	86	DQ32	128	CKE0
3	DQ1	45	S2	87	DQ33	129	S3
4	DQ2	46	DQMB2	88	DQ34	130	DQMB6
5	DQ3	47	DQMB3	89	DQ35	131	DQMB7
6	V _{DD}	48	NC	90	V _{DD}	132	NC
7	DQ4	49	V _{DD}	91	DQ36	133	V_{DD}
8	DQ5	50	NC	92	DQ37	134	NC
9	DQ6	51	NC	93	DQ38	135	NC
10	DQ7	52	NC	94	DQ39	136	NC
11	DQ8	53	NC	95	DQ40	137	NC
12	V _{SS}	54	V _{SS}	96	V _{SS}	138	V _{SS}
13	DQ9	55	DQ16	97	DQ41	139	DQ48
14	DQ10	56	DQ17	98	DQ42	140	DQ49
15	DQ11	57	DQ18	99	DQ43	141	DQ50
16	DQ12	58	DQ19	100	DQ44	142	DQ51
17	DQ13	59	V_{DD}	101	DQ45	143	V_{DD}
18	V_{DD}	60	DQ20	102	V_{DD}	144	DQ52
19	DQ14	61	NC	103	DQ46	145	NC
20	DQ15	62	NC	104	DQ47	146	NC
21	NC	63	CKE1	105	NC	147	NC
22	NC	64	Vss	106	NC	148	V _{SS}
23	V _{SS}	65	DQ21	107	V _{SS}	149	DQ53
24	NC	66	DQ22	108	NC	150	DQ54
25	NC	67	DQ23	109	NC	151	DQ55
26	V_{DD}	68	VSS	110	V_{DD}	152	V _{SS}
27	WE	69	DQ24	111	CAS	153	DQ56
28	DQMB0	70	DQ25	112	DQMB4	154	DQ57
29	DQMB1	71	DQ26	113	DQMB5	155	DQ58
30	<u>S0</u>	72	DQ27	114	S1	156	DQ59
31	NC	73	V_{DD}	115	RAS	157	V_{DD}
32	V _{SS}	74	DQ28	116	V_{SS}	158	DQ60
33	A0	75	DQ29	117	A1	159	DQ61
34	A2	76	DQ30	118	A3	160	DQ62
35	A4	77	DQ31	119	A5	161	DQ63
36	A6	78	VSS	120	A7	162	VSS
37	A8	79	CK2	121	A9	163	CK3
38	A10	80	NC	122	A13/BA0	164	NC
39	A12/BA1	81	NC	123	A11	165	SA0
40	V_{DD}	82	SDA	124	V_{DD}	166	SA1
41	V_{DD}	83	SCL	125	CK1	167	SA2
42	CK0	84	V_{DD}	126	NC	168	V_{DD}



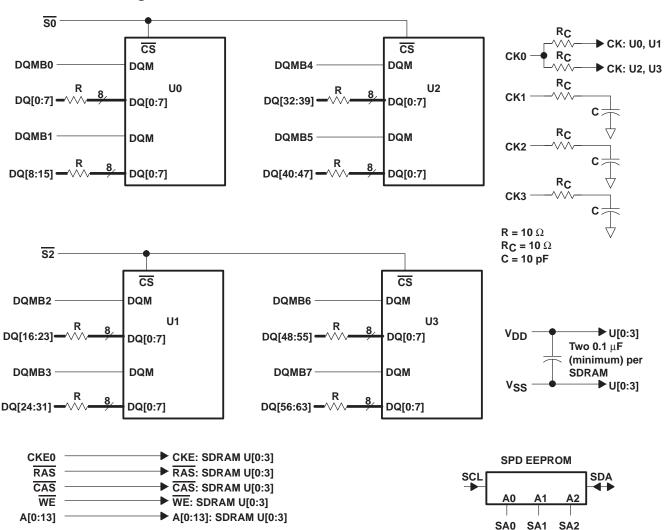
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dual-in-line memory module and components

The dual-in-line memory module and components include:

- PC substrate: 1,27 ± 0,1 mm (0.05 inch) nominal thickness; 0.005 inch/inch maximum warpage
- Bypass capacitors: Multilayer ceramic
- Contact area: Nickel plate and gold plate over copper

functional block diagram for the TM4SP64KPU

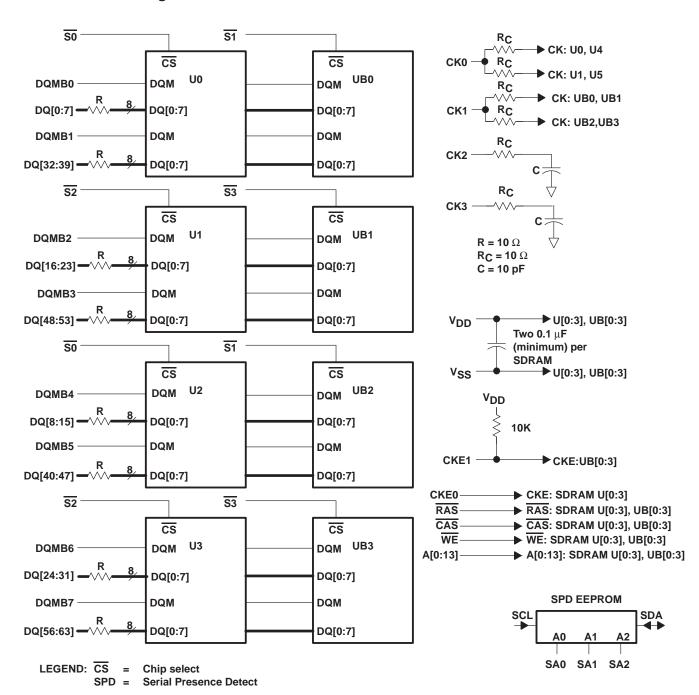


LEGEND: CS = Chip select

SPD = Serial Presence Detect



functional block diagram for the TM8SP64KPU



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absolute maximum ratings over ambient temperature range (unless otherwise noted)[†]

Supply voltage range, V _{DD}	
Voltage range on any pin (see Note 1) –	0.5 V to 4.6 V
Short-circuit output current	50 mA
Power dissipation: TM4SP64KPU	4 W
TM8SP64KPU	8 W
Ambient temperature range, T _A	. 0°C to 70°C
Storage temperature range, T _{stg} – 5	55°C to 125°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage values are with respect to VSS.

recommended operating conditions

		MIN	NOM	MAX	UNIT
V_{DD}	Supply voltage	3	3.3	3.6	V
VSS	Supply voltage		0		V
VIH	High-level input voltage	2		V _{DD} + 0.3	V
VIH-SPD	High-level input voltage for SPD device	2		5.5	V
V_{IL}	Low-level input voltage	-0.3		0.8	V
TA	Ambient temperature	0		70	°C

capacitance over recommended ranges of supply voltage and ambient temperature, f = 1 MHz (see Note 2)

	DARAMETER	TM4SP6	4KPU	TM8SP6	4KPU	
	PARAMETER	MIN	MAX	MIN	MAX	UNIT
C _{i(CK)}	Input capacitance, CK input		22		22	pF
C _{i(AC)}	Input capacitance, address and control inputs: A0 – A13, RAS, CAS, WE		22		42	pF
C _{i(CKE)}	Input capacitance, CKE input		22		22	pF
Co	Output capacitance		10		16	pF
C _{i(DQMBx)}	Input capacitance, DQMBx input		7		12	pF
C _{i(Sx)}	Input capacitance, Sx input		12		12	pF
C _{i/o(SDA)}	Input/output capacitance, SDA input		9		9	pF
C _{i(SPD)}	Input capacitance, SA0, SA1, SA2, SCL inputs		7		7	pF

NOTE 2: V_{DD} = 3.3 V \pm 0.3 V. Bias on pins under test is 0 V.



electrical characteristics over recommended ranges of supply voltage and ambient temperature (unless otherwise noted) (see Note 3)

TM4SP64KPU

PARAMETER Va.: Limb level output voltoge		TEST CONDITIONS		'4SP64K	PU-10	'4SP64k	(PU-12	
		TEST CONDIT	IONS	MIN	MAX	MIN	MAX	UNIT
Vон	High-level output voltage	I _{OH} = -2 mA		2.4		2.4		V
VOL	Low-level output voltage	$I_{OL} = 2 \text{ mA}$			0.4		0.4	V
lį	Input current (leakage)	$0 \text{ V} < \text{V}_{\text{I}} < \text{V}_{\text{DD}} + 0.3 \text{ V},$ All other pins = 0 V to V _{DD}			±10		±10	μΑ
IO	Output current (leakage)	0 V < V _O < V _{DD} +0.3 V, Output disabled			±10		±10	μΑ
loo.	Operating current	Burst length = 1, t _{RC} ≥ t _{RC} MIN,	CAS latency = 2		480		460	mA
ICC1	Operating current	I _{OH} /I _{OL} = 0 mA (See Notes 4, 5, and 6)	CAS latency = 3		540		480	mA
ICC2P	Precharge standby current in	CKE \leq V _{IL} MAX, t _{CK} = 15 ns	(see Note 7)		8		8	mA
I _{CC2PS}	power-down mode	CKE and CK ≤ V _{IL} MAX, t _{CK}	= ∞ (see Note 8)		8		8	mA
ICC2N	Active standby current in	CKE \geq V _{IH} MIN, t _{CK} = 15 ns (see Note 7)			160		160	mA
ICC2NS	non-power-down mode	t _{CK} = ∞ (see Note 8)			12		12	mA
ICC3P	A ative at a allow assument in	CKE \leq V _{IL} MAX, t _{CK} = 15 ns	(see Notes 4 and 7)		40		40	mA
ICC3PS	Active standby current in power-down mode	CKE and CK ≤ V _{IL} MAX, t _{CK} (see Notes 4 and 8)	= ∞		40		40	mA
ICC3N	Donale and the state of the sta	CKE ≥ V _{IH} MIN, t _{CK} = 15 ns	(see Notes 4 and 7)		280		260	mA
ICC3NS	Precharge standby current in non-power-down mode	CKE ≥ V _{IH} MIN, CK ≤ V _{IL} MA (see Notes 4 and 8)	√X, tCK = ∞		80		80	mA
l	Durat ourrent	Page burst, I _{OH} /I _{OL} = 0 mA All banks activated,	CAS latency = 2	·	580		560	mA
ICC4	Burst current	n _{CCD} = one cycle (see Notes 9 and 10)	CAS latency = 3		860		720	mA
loos	Auto-refresh current	t _{RC} ≤ t _{RC} MIN	CAS latency = 2		660		640	mA
ICC5	Auto-refresh current	(see Notes 5 and 8)	CAS latency = 3		780		640	mA
ICC6	Self-refresh current	CKE ≤ V _{IL} MAX			8		8	mA

NOTES: 3. All specifications apply to the device after power-up initialization. All control and address inputs must be stable and valid..

- 4. Only one bank is activated.
- 5. $t_{RC} \ge MIN$
- 6. Control and address inputs change state only twice during t_{RC}.
- 7. Control and address inputs change state only once every 30 ns.
- 8. Control and address inputs do not change (stable).
- 9. Control and address inputs change only once every cycle.
- 10. Continuous burst access, n_{CCD} = 1 cycle

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electrical characteristics over recommended ranges of supply voltage and ambient temperature (unless otherwise noted) (see Note 3)

TM8SP64KPU

PARAMETER		TEST COMPLET	10110	'8SP64K	PU-10	'8SP64H	(PU-12	
	PARAMETER	TEST CONDIT	IONS	MIN MAX		MIN	MAX	UNIT
Vон	High-level output voltage	I _{OH} = -2 mA		2.4		2.4		V
VOL	Low-level output voltage	$I_{OL} = 2 \text{ mA}$			0.4		0.4	V
lį	Input current (leakage)	$0 \text{ V} < \text{V}_{\text{I}} < \text{V}_{\text{DD}} + 0.3 \text{ V},$ All other pins = 0 V to V _{DD}			±20		±20	μА
IO	Output current (leakage)	0 V < V _O < V _{DD} +0.3 V, Output disabled			±20		±20	μА
loor	Operating current	Burst length = 1, t _{RC} ≥ t _{RC} MIN	CAS latency = 2		488		468	mA
ICC1	Operating current	I _{OH} /I _{OL} = 0 mA (See Notes 4, 5, and 6)	CAS latency = 3		548		488	mA
ICC2P	Precharge standby current in	CKE \leq V _{IL} MAX, t _{CK} = 15 ns	(see Note 7)		16		16	mA
I _{CC2PS}	power-down mode	CKE and CK \leq V _{IL} MAX, t _{CK}	= ∞ (see Note 8)		16		16	mA
ICC2N	Precharge standby current in	CKE \geq V _{IH} MIN, t _{CK} = 15 ns	(see Note 7)		320		320	mA
ICC2NS	non-power-down mode	t _{CK} = ∞ (see Note 8)			24		24	mA
ICC3P	A ativa — atamathu — ayunant in	CKE \leq V _{IL} MAX, t _{CK} = 15 ns	(see Notes 4 and 7)		80		80	mA
ICC3PS	Active standby current in power-down mode	CKE and CK \leq V _{IL} MAX, t _{CK} (see Notes 4 and 8)	= ∞		80		80	mA
ICC3N	A ativa — atamathu — ayunant in	$CKE \ge V_{IH} MIN$, $t_{CK} = 15 ns$	(see Notes 4 and 7)		560		520	mA
ICC3NS	Active standby current in non-power-down mode	$CKE \ge V_{IH} MIN, CK \le V_{IL} MA$ (see Notes 4 and 8)	XX, tCK = ∞		160		160	mA
laa	Burst current	Page burst, I _{OH} /I _{OL} = 0 mA All banks activated,	CAS latency = 2		588		568	mA
ICC4	Duist current	n _{CCD} = one cycle (see Notes 9 and 10)	CAS latency = 3		868		728	mA
loos	Auto-refresh current	$t_{RC} \le t_{RC} MIN$	CAS latency = 2		668		648	mA
ICC5	Auto-renesh current	(see Notes 5 and 8)	CAS latency = 3		788		648	mA
I _{CC6}	Self-refresh current	CKE ≤ V _{IL} MAX			16		16	mA

NOTES: 3. All specifications apply to the device after power-up initialization. All control and address inputs must be stable and valid.

- 4. Only one bank is activated.
- 5. $t_{RC} \ge MIN$
- 6. Control, DQ, and address inputs change state twice during t_{RC}.
- 7. Control, DQ, and address inputs change state once every 30 ns.
- 8. Control, DQ, and address inputs do not change.
- 9. Control, DQ, and address inputs change once every cycle.
- 10. Continuous burst access, n_{CCD} = 1 cycle



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ac timing requirements†

			'xSP64KPU-10		'xSP64k	(PU-12	
			MIN	MAX	MIN	MAX	UNIT
tCK2	Cycle time, CK	CAS latency = 2	15		15		ns
tCK3	Cycle time, CK	CAS latency = 3	10		12		ns
^t CH	Pulse duration, CK high		3		4		ns
tCL	Pulse duraction, CK low		3		4		ns
tAC2	Access time, CK high to data out (see Note 11)	CAS latency = 2		9		9.5	ns
tAC3	Access time, CK high to data out (see Note 11)	CAS latency = 3		7.5		8	ns
tOH	Hold time, CK high to data out		3		3		ns
tLZ	Delay time, CK high to DQ in low-impedance state (see Note 12)		2		2		ns
^t HZ	Delay time, CK high to DQ in high-impedance state (see Note 13)			8		8	ns
tis	Setup time, address, control, and data input		3		3		ns
tIH	Hold time, address, control, and data input		1		1		ns
tCESP	Power down/self-refresh exit time		10		12		ns
tRAS	Delay time, ACTV command to DEAC or DCAB command		50		60		ns
tRC	Delay time, ACTV,MRS,REFR,or SLFR to ACTV,MRS,REFR,or SL	FR command	80		90		ns
tRCD	Delay time ACTV command to READ,READ-P,WRT,or WR (see Note 14)	T-P command	30		30		ns
t _{RP}	Delay time, DEAC or DCAB command to ACTV,MRS,REFR, or SLI	FR command	30		30		ns
t _{RRD}	Delay time, ACTV command in one bank to ACTV command in the	other bank	20		24		ns
tRSA	Delay time,MRS command to ACTV,MRS,REFR,or SLFR comman	d	20		24		ns
tAPR	Final data out of READ-P operation to ACTV,MRS,SLFR,or REFR	command	t	RP -(CL	-1)*tCK		ns
tAPW	Final data in of WRT-P operation to ACTV,MRS,SLFR,or REFR co	mmand		t _{RP} +	1 t _{CK}		ns
tWR	Delay time, final data in of WRT operation to DEAC or DCAB comm	nand	10		12		ns
t _T	Transition time		1	5	1	5	ms

† All references are made to the rising transition of CK unless otherwise noted.

- NOTES: 11. t_{AC} is referenced from the rising transition of CK that precedes the data-out cycle. For example, the first data out t_{AC} is referenced from the rising transition of ck that is read latency (one cycle after the READ command). Access time is measured at output reference level 1.4 V.
 - 12. t_{\subseteq z} is measured from the rising transition of ck that is read latency (one cycle after the READ command).
 - 13. t_{HZ} (max) defines the time at which the outputs are no longer driven and is not referenced to output voltage levels.
 - 14. For read or write operations with automatic deactivate, t_{RCD} must be set to satisfy minimum t_{RAS}.



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clock timing requirements[†]

			'xSP64k	P64KPU-10 'xSP64KPU-12		+	
			MIN	MAX	MIN	MAX	UNIT [‡]
tREF	Refresh interval			64		64	ms
nCCD	Delay time, READ or WRT command to an interrupting comman	nd	1		1		cycle
nCDD	Delay time, CS low or high to input enabled or inhibited		0	0	0	0	cycle
n _{CLE}	Delay time, CKE high or low to CK enabled or disabled		1	1	1	1	cycle
n _{CWL}	Delay time, final data in of WRT operation to READ, READ-P, V	VRT, or WRT-P	1		1		cycle
nDID	Delay time, ENBL or MASK command to enabled or masked da	ata in	0	0	0	0	cycle
nDOD	Delay time, ENBL or MASK command to enabled or masked da	ata out	2	2	2	2	cycle
nHZP2	Delay time, DEAC or DCAB, command to DQ in high-impedance state	CAS latency = 2		2		2	cycle
nHZP3	Delay time, DEAC or DCAB, command to DQ in high-impedance state	CAS latency = 3		3		3	cycle
nWCD	Delay time, WRT command to first data in		0	0	0	0	cycle

[†] All references are made to the rising transition of CK unless otherwise noted.



[‡] A CK cycle can be considered as contributing to a timing requirement for those parameters defined in cycle units only when not gated by CKE (those CK cycles occurring during the time when CKE is asserted low).

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serial presence detect

The serial presence detect (SPD) is contained in a 2K-bit serial EEPROM located on the module. The SPD nonvolatile EEPROM contains various data such as module configuration, SDRAM organization, and timing parameters (see tables below). Only the first 128 bytes are programmed by Texas Instruments, while the remaining 128 bytes are available for customer use. Programming is done through an IIC bus using the clock (SCL) and data (SDA) signals. All Texas Instruments modules comply with the current JEDEC SPD Standard. See the *Texas Instruments Serial Presence Detect Technical Reference* (literature number SMMU001) for further details.

Tables in this section list the SPD contents as follows:

Table 1-TM4SP64KPU Table 2-TM8SP64KPU

Table 1. Serial Presence-Detect Data for the TM4SP64KPU

BYTE		TM4SP64KP	U-10	TM4SP64KP	U-12
NO.	DESCRIPTION OF FUNCTION	ITEM	DATA	ITEM	DATA
0	Defines number of bytes written into serial memory during module manufacturing	128 bytes	80h	128 bytes	80h
1	Total number of bytes of SPD memory device	256 bytes	08h	256 bytes	08h
2	Fundamental memory type (FPM, EDO, SDRAM,)	SDRAM	04h	SDRAM	04h
3	Number of row addresses on this assembly	12	0Ch	12	0Ch
4	Number of column addresses on this assembly	8	08h	8	08h
5	Number of module banks on this assembly	1 bank	01h	1 bank	01h
6	Data width of this assembly	64 bits	40h	64 bits	40h
7	Data width continuation		00h		00h
8	Voltage interface standard of this assembly	LVTTL	01h	LVTTL	01h
9	SDRAM cycle time at maximum supported CAS latency (CL), CL = X	t _{CK} = 10 ns	A0h	t _{CK} = 12 ns	C0h
10	SDRAM access from clock at CL = X	t _{AC} = 7.5 ns	75h	t _{AC} = 8 ns	80h
11	DIMM configuration type (non-parity, parity, error correcting code [ECC])	Non-Parity	00h	Non-Parity	00h
12	Refresh rate/type	15.6 μs/ self-refresh	80h	15.6 μs/ self-refresh	80h
13	SDRAM width, primary DRAM	x16	10h	x16	10h
14	Error-checking SDRAM data width	N/A	00h	N/A	00h
15	Minimum clock delay, back-to-back random column addresses	1 CK cycle	01h	1 CK cycle	01h
16	Burst lengths supported	1, 2, 4, 8, full page	8Fh	1, 2, 4, 8, full page	8Fh
17	Number of banks on each SDRAM device	4 banks	04h	4 banks	04h
18	CAS latencies supported	2, 3	06h	2, 3	06h
19	CS latency	0	01h	0	01h
20	Write latency	0	01h	0	01h
21	SDRAM module attributes	Non-buffered/ Non-registered	00h	Non-buffered/ Non-registered	00h
22	SDRAM device attributes: general	V _{DD} tolerance = (+/-10%) Burst read/write, precharge all, auto precharge	0Eh	V _{DD} tolerance = (+/-10%) Burst read/write, precharge all, auto precharge	0Eh
23	Minimum clock cycle time at CL = X − 1	t _{CK} = 15 ns	F0h	t _{CK} = 15 ns	F0h



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serial presence detect (continued)

Table 1. Serial Presence-Detect Data for the TM4SP64KPU (Continued)

BYTE		TM4SP64K	PU-10	TM4SP64KPU-12		
NO.	DESCRIPTION OF FUNCTION	ITEM	DATA	ITEM	DATA	
24	Maximum data-access time from clock at CL = X - 1	$t_{AC} = 9 \text{ ns}$	90h	$t_{AC} = 9.5 \text{ ns}$	95h	
25	Minimum clock cycle time at CL = X - 2	N/A	00h	N/A	00h	
26	Maximum data-access time from clock at CL = X - 2	N/A	00h	N/A	00h	
27	Minimum row precharge time	t _{RP} = 30 ns	1Eh	t _{RP} = 30ns	1Eh	
28	Minimum row-active to row-active delay	t _{RRD} = 20 ns	14h	t _{RRD} = 24 ns	18h	
29	Minimum RAS-to-CAS delay	$t_{RCD} = 30 \text{ ns}$	1Eh	t _{RCD} = 30 ns	1Eh	
30	Minimum RAS pulse width	$t_{RAS} = 50 \text{ ns}$	32h	t _{RAS} = 60 ns	3Ch	
31	Density of each bank on module	32M Bytes	08h	32M Bytes	08h	
32-61	Superset features (may be used in the future)					
62	SPD revision	Rev. 1	01h	Rev. 1	01h	
63	Checksum for byte 0 – 62	60	3Ch	122	7Ah	
64-71	Manufacturer's JEDEC ID code per JEP-106E	97h	970000h	97h	970000h	
72	Manufacturing location [†]	TBD		TBD		
73-90	Manufacturer's part number†	TBD		TBD		
91	Die revision code [†]	TBD		TBD		
92	PCB revision code [†]	TBD		TBD		
93-94	Manufacturing date [†]	TBD		TBD		
95-98	Assembly serial number [†]	TBD		TBD		
99-125	Manufacturer specific data†	TBD		TBD		
126-127	Vendor specific data [†]	TBD		TBD		
128–166	System integrator's specific data‡	TBD		TBD		
167–255	Open					

[†] TBD indicates values are determined at manufacturing time and are module dependent.



[‡]These TBD values are determined and programmed by the customer (optional).

serial presence detect (continued)

Table 2. Serial Presence-Detect Data for the TM8SP64KPU

BYTE	DESCRIPTION OF FUNCTION	TM8SP64KPU-10		TM8SP64KPU-12	
NO.		ITEM	DATA	ITEM	DATA
0	Defines number of bytes written into serial memory during module manufacturing	128 bytes	80h	128 bytes	80h
1	Total number of bytes of SPD memory device	256 bytes	08h	256 bytes	08h
2	Fundamental memory type (FPM, EDO, SDRAM,)	SDRAM	04h	SDRAM	04h
3	Number of row addresses on this assembly	12	0Ch	12	0Ch
4	Number of column addresses on this assembly	8	08h	8	08h
5	Number of module banks on this assembly	2 banks	02h	2 banks	02h
6	Data width of this assembly	64 bits	40h	64 bits	40h
7	Data width continuation		00h		00h
8	Voltage interface standard of this assembly	LVTTL	01h	LVTTL	01h
9	SDRAM cycle time at maximum supported CAS latency (CL), CL = X	t _{CK} = 10 ns	A0h	t _{CK} = 12 ns	C0h
10	SDRAM access from clock at CL = X	t _{AC} = 7.5 ns	75h	t _{AC} = 8 ns	80h
11	DIMM configuration type (non-parity, parity, error correcting code [ECC])	Non-Parity	00h	Non-Parity	00h
12	Refresh rate/type	15.6 μs/ self-refresh	80h	15.6 μs/ self-refresh	80h
13	SDRAM width, primary DRAM	x16	10h	x16	10h
14	Error-checking SDRAM data width	N/A	00h	N/A	00h
15	Minimum clock delay, back-to-back random column addresses	1 CK cycle	01h	1 CK cycle	01h
16	Burst lengths supported	1, 2, 4, 8, full page	8Fh	1, 2, 4, 8, full page	8Fh
17	Number of banks on each SDRAM device	4 banks	04h	4 banks	04h
18	CAS latencies supported	2, 3	06h	2, 3	06h
19	CS latency	0	01h	0	01h
20	Write latency	0	01h	0	01h
21	SDRAM module attributes	Non-buffered/ Non-registered	00h	Non-buffered/ Non-registered	00h
22	SDRAM device attributes: general	V _{DD} tolerance = (+/-10%) Burst read/write, precharge all, auto precharge	0Eh	V _{DD} tolerance = (+10%), Burst read/write, precharge all, auto precharge	0Eh
23	Minimum clock cycle time at CL = X − 1	t _{CK} = 15 ns	F0h	t _{CK} = 15 ns	F0h
24	Maximum data-access time from clock at CL = X - 1	t _{AC} = 9 ns	90h	t _{AC} = 9.5 ns	95h
25	Minimum clock cycle time at CL = X − 2	N/A	00h	N/A	00h
26	Maximum data-access time from clock at CL = X − 2	N/A	00h	N/A	00h

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serial presence detect (continued)

Table 2. Serial Presence-Detect Data for the TM8SP64KPU (Continued)

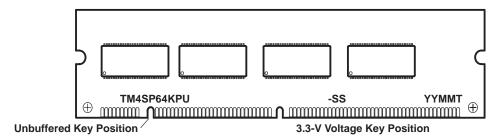
BYTE NO.	DESCRIPTION OF FUNCTION	TM8SP64KPU-10		TM8SP64KPU-12	
		ITEM	DATA	ITEM	DATA
27	Minimum row precharge time	t _{RP} = 30 ns	1Eh	$t_{RP} = 30 \text{ ns}$	1Eh
28	Minimum row-active to row-active delay	t _{RRD} = 20 ns	14h	t _{RRD} = 24 ns	18h
29	Minimum RAS-to-CAS delay	t _{RCD} = 30 ns	1Eh	t _{RCD} = 30 ns	1Eh
30	Minimum RAS pulse width	t _{RAS} =50 ns	32h	t _{RAS} = 60 ns	3Ch
31	Density of each bank on module	32M Bytes	08h	32M Bytes	08h
32–61	Superset features (may be used in the future)				
62	SPD revision	Rev. 1	01h	Rev. 1	01h
63	Checksum for byte 0 – 62	61	3Dh	123	7Bh
64-71	Manufacturer's JEDEC ID code per JEP-106E	97h	970000h	97h	970000h
72	Manufacturing location [†]	TBD		TBD	
73-90	Manufacturer's part number†	TBD		TBD	
91	Die revision code†	TBD		TBD	
92	PCB revision code [†]	TBD		TBD	
93-94	Manufacturing date [†]	TBD		TBD	
95-98	Assembly serial number [†]	TBD		TBD	
99-125	Manufacturer specific data [†]	TBD		TBD	
126-127	Vendor specific data [†]	TBD		TBD	
128–166	System integrator's specific data‡	TBD		TBD	
167–255	Open				

[†] TBD indicates values are determined at manufacturing time and are module dependent.



[‡] These TBD values are determined and programmed by the customer (optional).

device symbolization (TM4SP64KPU)



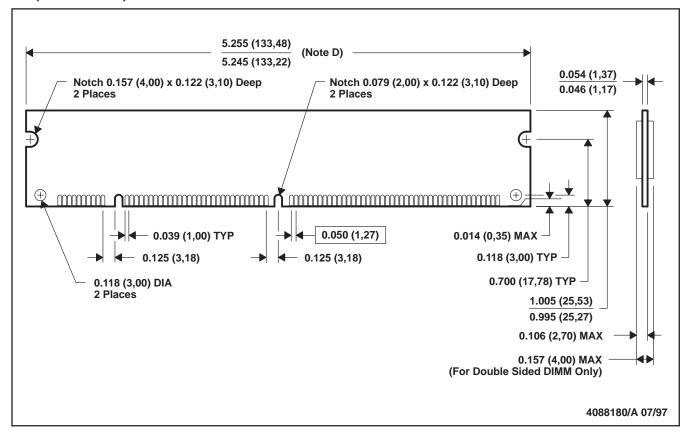
YY = Year Code = Month Code = Assembly Site Code -SS = Speed Code

NOTE A: Location of symbolization may vary.

MECHANICAL DATA

BR (R-PDIM-N168)

DUAL IN-LINE MEMORY MODULE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MO-161
- D. Dimension includes de-panelization variations; applies between notch and tab edge.
- E. Outline may vary above notches to allow router/panelization irregularities.



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