



TMC2011A/2111A

Variable-Length Shift Register

Features

- Low power CMOS
- TMC2011A is a pin compatible replacement for the TDC1011 and TMC2011
- TMC2211A is a pin compatible replacement for the TMC2111
- Inputs and outputs are TTL compatible
- DC-40MHz clock rate
- Selectable delay lengths (TMC2011A: 3 to 18 stages, TMC2111A: 1 to 16 stages)
- Special 4-bit wide mixed-delay mode (TMC2011A)
- Available in 24-pin CERDIP and plastic DIP and 28-lead Plastic Leadless Chip Carrier

Applications

- Video filtering
- High speed data registers
- Local storage registers
- Digital delay lines
- Television special effects
- Pipeline register

Description

The TMC2011A and TMC2111A are high-speed, byte-wide shift registers with programmable delay lengths.

The TMC2011A can be programmed to any length between 3 and 18 stages. It offers a special split-word mode which allows for mixed delay lengths. The TMC2011A, constructed in low-power CMOS, is pin and function compatible with the bipolar TDC1011.

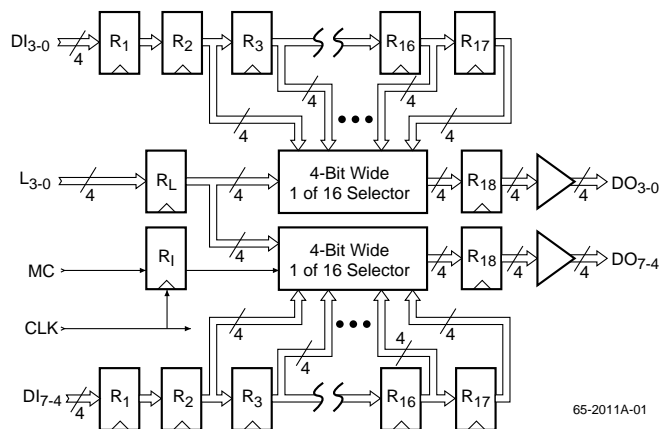
The TMC2111A is a byte-wide shift register that can be programmed to lengths of 1 to 16 stages.

The TMC2011A and TMC2111A are fully synchronous, with all operations controlled by a single master clock. Input and output registers are positive-edge triggered D-type flip-flops. The length and mode controls are also registered. Both devices operate with a maximum clock rate of 40 MHz.

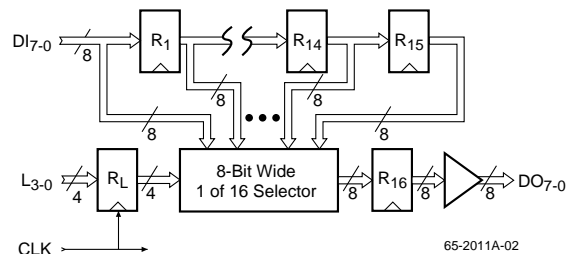
Fabricated in a submicron CMOS process, the TMC2011A and TMC2111A are TTL-compatible, and are available in 24-pin CERDIP and Plastic DIP packages as well as a 28-lead Plastic Leadless Chip Carrier.

Block Diagrams

TMC2011A



TMC2111A



65-2011A-02

65-2011A-01

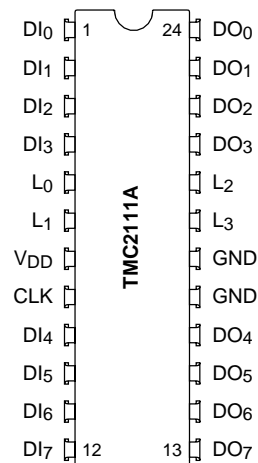
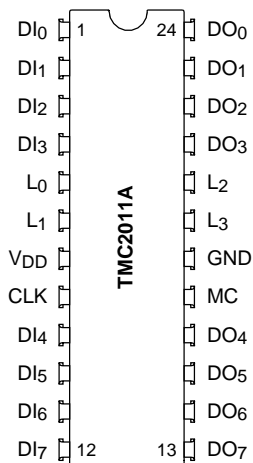
Functional Description

The TMC2011A consists of two 4-bit wide, programmable length shift registers. The TMC2111A consists of a single 8-bit wide, programmable length shift register. The internal

registers of each device share control signals and a common clock.

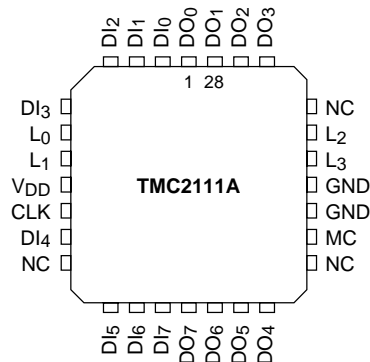
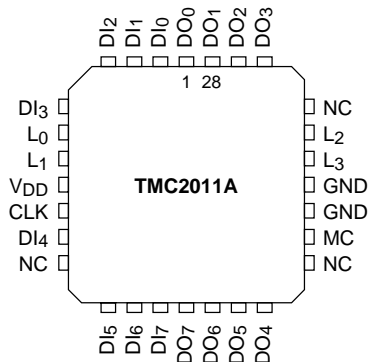
Pin Assignments

24 Lead DIP (B2, N2) Packages



65-2011A-03

28 Lead PLCC (R3) Package



65-2011A-04

Pin Descriptions – TMC2011A

Pin Name	Pin Number		Pin Function Description
	DIP	PLCC	
Power			
VDD	7	8	Supply Voltage. The TMC2011A and operates from a single +5V supply. All power and ground lines must be connected.
GND	18	21,22	Ground. The TMC2011A operates from a single +5V supply. All power and ground lines must be connected.
Data Inputs			
DI7-0	12,11,10, 9,4,3,2,1	14,13,12, 10,5,4,3,2	Data Input. Eight inputs are provided for the data, which pass through the shift register unchanged. The eight inputs on the TMC2011A are divided into two groups of four bits to allow mixed delay operation. The lengths of these two groups are different when the Mode Control (MC) is HIGH (see Table 1). When MC is LOW both groups have equal delays.
Data Outputs			
DO7-0	13,14,15, 16,21,22, 23,24	15,16,17, 18,26,27, 28,1	Data Output. The outputs of the shift register are delayed relative to the input signals. The amount of the delay is programmable (see Table 1). The outputs remain valid for a minimum of t _{HO} nanoseconds after the leading edge of CLK. This allow the data to be latched into circuits with non-zero hold time requirements.
Controls			
CLK	8	9	Master Clock. All inputs and outputs are synchronous and operate from a single master clock. All operations occur on the rising edge of the master clock.
L3-0	19,20,6,5	23,24,7,6	Length Select. The length select input is used to determine the register delay of the TMC2011A. This input is registered and affects the output t _{DO} after the clock edge after it is input to the device (see Timing Diagram). Delay lengths are specified in Table 1.
MC	17	20	Mode Control. The Mode Control is used to select the special 4-bit wide split mode. When HIGH, the delay on DO7-4 is fixed at 18 stages, while DO3-0 have the delay specified by the length select. When MC is LOW, all eight bits have equal delays as specified by the length select.

Pin Descriptions – TMC2111A

Pin Name	Pin Number		Pin Function Description
	DIP	PLCC	
Power			
VDD	7	8	Supply Voltage. The TMC2111A operates from a single +5V supply. All power and ground lines must be connected.
GND	17,18	20,21,22	Ground. The TMC2111A operates from a single +5V supply. All power and ground lines must be connected.
Data Inputs			
DI7-0	12,11,10, 9,4,3,2,1	14,13,12, 10,5,4,3,2	Data Input. Eight inputs are provided for the data, which pass through the shift register unchanged. The TMC2111A consists of a single group of eight bits with all data bits having equal delays.
Data Outputs			
DO7-0	13,14,15, 16,21,22, 23,24	15,16,17, 18,26,27, 28,1	Data Output. The outputs of the shift register are delayed relative to the input signals. The amount of the delay is programmable (see Table 1). The outputs remain valid for a minimum of t _{HO} nanoseconds after the leading edge of CLK. This allow the data to be latched into circuits with non-zero hold time requirements.
Controls			
CLK	8	9	Master Clock. All inputs and outputs are synchronous and operate from a single master clock. All operations occur on the rising edge of the master clock.
L3-0	19,20,6,5	23,24,7,6	Length Select. The length select input is used to determine the register delay of the TMC2111A. This input is registered and affects the output t _{DO} after the clock edge after it is input to the device (see Timing Diagram). Delay lengths are specified in Table 1.

Table 1. Programming Length Controls

Input Code				TMC2011A				TMC2111A
				Mode (MC) =0		Mode (MC) =1		
L3	L2	L1	L0	DO3-0 Length	DO7-4 Length	DO3-0 Length	DO7-4 Length	DO7-0 Length
0	0	0	0	3	3	3	18	1
0	0	0	1	4	4	4	18	2
0	0	1	0	5	5	5	18	3
0	0	1	1	6	6	6	18	4
0	1	0	0	7	7	7	18	5
0	1	0	1	8	8	8	18	6
0	1	1	0	9	9	9	18	7
0	1	1	1	10	10	10	18	8
1	0	0	0	11	11	11	18	9
1	0	0	1	12	12	12	18	10
1	0	1	0	13	13	13	18	11
1	0	1	1	14	14	14	18	12
1	1	0	0	15	15	15	18	13
1	1	0	1	16	16	16	18	14
1	1	1	0	17	17	17	18	15
1	1	1	1	18	18	18	18	16

Absolute Maximum Ratings

(beyond which the device may be damaged)¹

Parameter	Min	Typ	Max	Unit
Supply Voltage	-0.5		7.0	V
Input Voltage	-0.5		V _{DD} + 0.5	V
Output, Applied Voltage ²	-0.5		V _{DD} + 0.5	V
Output, Externally Forced Current ^{3,4}	-3.0		6.0	mA
Output, Short Circuit Duration (single output in HIGH state to ground)			1	sec
Operating, Ambient Temperature	-20		110	°C
Junction Temperature			140	°C
Storage Temperature	-65		150	°C
Lead Soldering (10 seconds)			300	°C

Notes:

1. Functional operation under any of these conditions is NOT implied. Performance and reliability are guaranteed only if Operating Conditions are not exceeded.
2. Applied voltage must be current limited to specified range.
3. Forcing voltage must be limited to specified range.
4. Current is specified as conventional current flowing into the device.

Operating Conditions

Parameter		Min	Nom	Max	Units
V _{DD}	Power Supply Voltage	4.75	5.0	5.25	V
f _{CLK}	Clock frequency	TMC2011A, 2111A		30	MHz
		TMC2011A-1, 2111A-1		40	
t _{PWH}	CLK pulse width, HIGH	12			ns
t _{PWL}	CLK pulse width, LOW	12			ns
t _S	Input Data Set-up Time	6			ns
t _H	Input Data Hold Time	1			ns
V _{IH}	Input Voltage, Logic HIGH	DI7-0, L3-0, MC	2.0		V
		CLK	2.6		
V _{IL}	Input Voltage, Logic LOW			0.8	V
I _{OH}	Output Current, Logic HIGH			-2.0	mA
I _{OL}	Output Current, Logic LOW			4.0	mA
T _A	Ambient Temperature, Still Air	0		70	°C

Electrical Characteristics

Parameter		Conditions	Min	Typ	Max	Units
IDDU	Power Supply Current, Unloaded	VDD = Max, fCLK=30 MHz			30	mA
		VDD = Max, fCLK=40 MHz			40	mA
IDDQ	Power Supply Current, Quiescent	VDD = Max, CLK = LOW			0.5	mA
CPIN	I/O Pin Capacitance			5		pF
I _{IH}	Input Current, HIGH	VDD = Max, V _{IN} = VDD			±10	μA
I _{IL}	Input Current, LOW	VDD = Max, V _{IN} = 0 V			±10	μA
I _{OS}	Short-Circuit Current				-100	mA
V _{OH}	Output Voltage, HIGH	DO7-0, I _{OH} = Max	2.4			V
V _{OL}	Output Voltage, LOW	DO7-0, I _{OL} = Max			0.4	V

Switching Characteristics

Parameter		Conditions	Min	Typ	Max	Units
t _{DO}	Output Delay Time	C _{LOAD} = 25 pF			15	ns
t _{HO}	Output Hold Time	C _{LOAD} = 25 pF	3			ns

Timing Diagrams

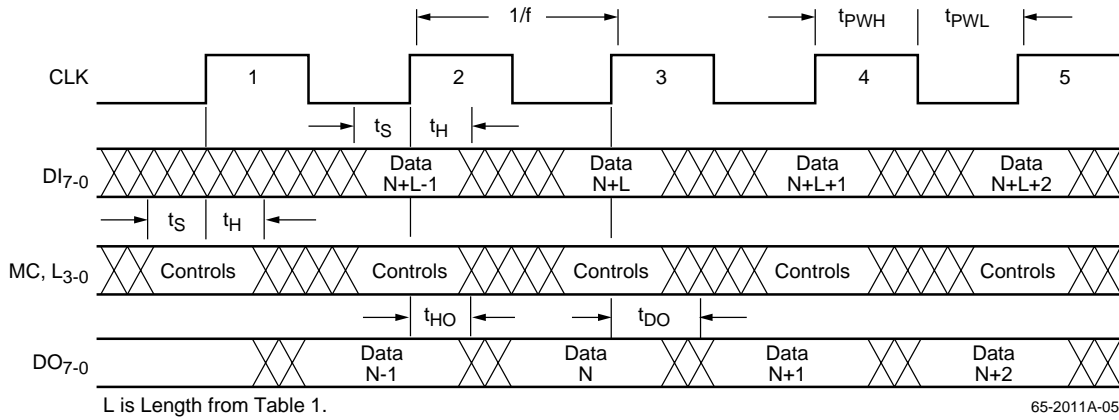


Figure 1. Preset Length Controls

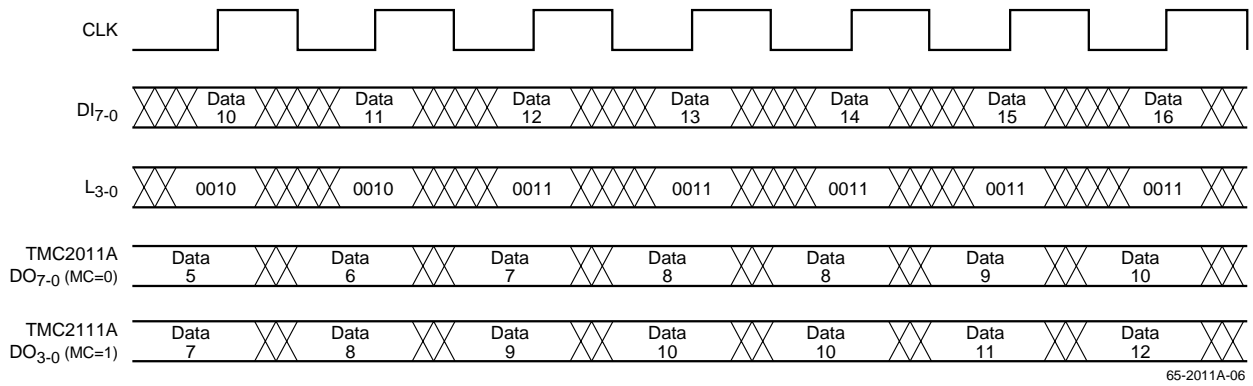


Figure 2. Length Control Operation

Equivalent Circuits

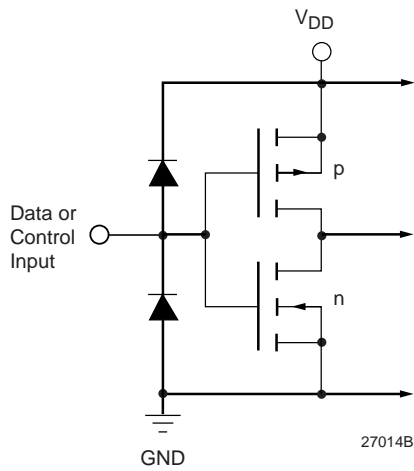


Figure 3. Equivalent Digital Input Circuit

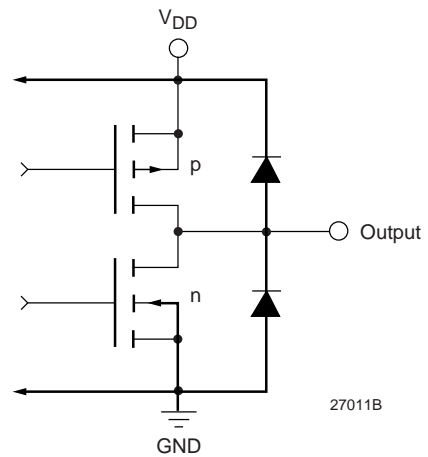


Figure 4. Equivalent Digital Output Circuit

Notes:

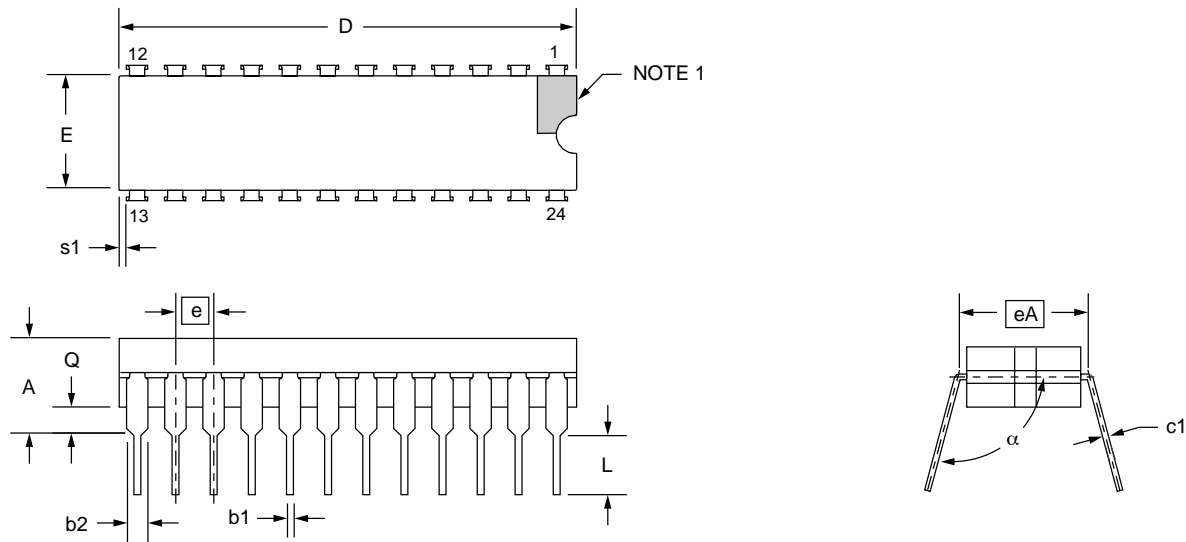
Mechanical Dimensions

24-Lead Ceramic DIP Package

Symbol	Inches		Millimeters		Notes
	Min.	Max.	Min.	Max.	
A	—	.200	—	5.08	
b1	.014	.023	.36	.58	8
b2	.045	.065	1.14	1.65	2, 8
c1	.008	.015	.20	.38	8
D	—	1.280	—	32.51	4
E	.220	.310	5.59	7.87	4
e	.100 BSC		2.54 BSC		5
eA	.300 BSC		7.62 BSC		7
L	.125	.200	3.18	5.08	
Q	.015	.060	.38	1.52	3
s1	.005	—	.13	—	6
α	90°	105°	90°	105°	

Notes:

1. Index area: a notch or a pin one identification mark shall be located adjacent to pin one. The manufacturer's identification shall not be used as pin one identification mark.
2. The minimum limit for dimension "b2" may be .023 (.58mm) for leads number 1, 12, 13 and 24 only.
3. Dimension "Q" shall be measured from the seating plane to the base plane.
4. This dimension allows for off-center lid, meniscus and glass overrun.
5. The basic pin spacing is .100 (2.54mm) between centerlines. Each pin centerline shall be located within $\pm .010$ (.25mm) of its exact longitudinal position relative to pins 1 and 24.
6. Applies to all four corners (leads number 1, 12, 13, and 24).
7. "eA" shall be measured at the center of the lead bends or at the centerline of the leads when " α " is 90°.
8. All leads – Increase maximum limit by .003 (.08mm) measured at the center of the flat, when lead finish applied.
9. Twenty-two spaces.



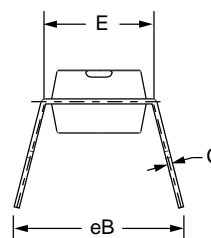
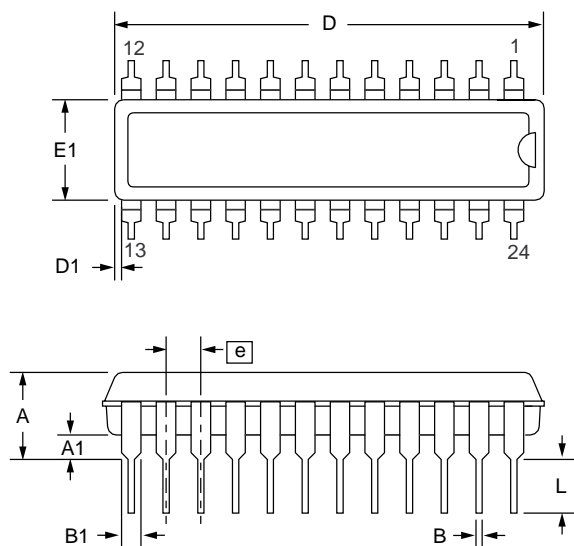
Mechanical Dimensions (continued)

24-Lead Plastic DIP Package

Symbol	Inches		Millimeters		Notes
	Min.	Max.	Min.	Max.	
A	—	.210	—	5.33	
A1	.015	—	.38	—	
A2	.115	.195	2.53	4.95	
B	.014	.022	.36	.56	
B1	.045	.070	1.14	1.78	
C	.008	.015	.20	.38	4
D	1.125	1.275	28.58	32.39	2
D1	.005	—	.13	—	
E	.300	.325	7.62	8.26	
E1	.240	.280	6.10	7.11	2
e	.100 BSC		2.54 BSC		
eB	—	.430	—	10.92	
L	.115	.160	2.92	4.06	
N	24		24		5

Notes:

1. Dimensioning and tolerancing per ANSI Y14.5M-1982.
2. "D" and "E1" do not include mold flashing. Mold flash or protrusions shall not exceed .010 inch (0.25mm).
3. Terminal numbers are shown for reference only.
4. "C" dimension does not include solder finish thickness.
5. Symbol "N" is the maximum number of terminals.



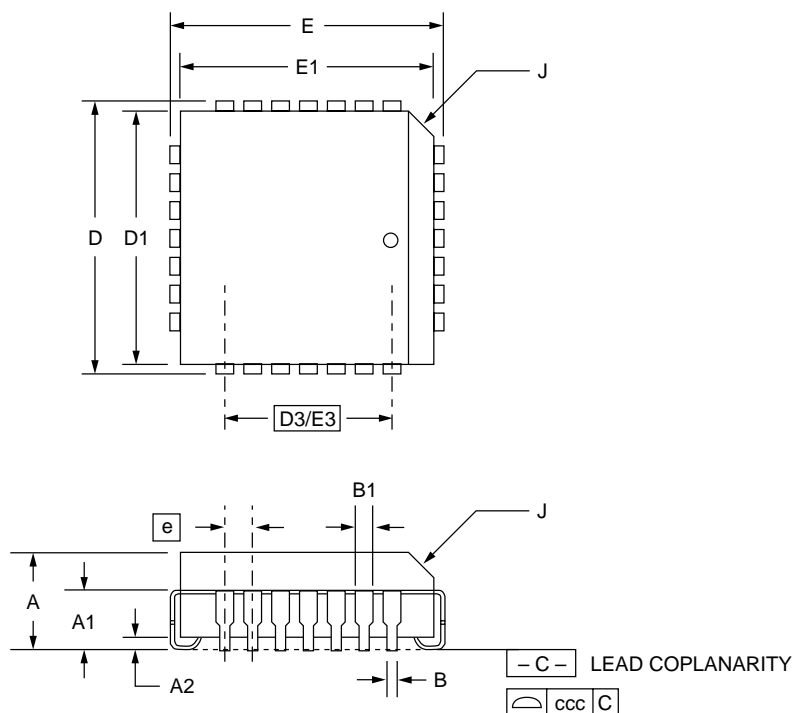
Mechanical Dimensions (continued)

28-Lead PLCC Package

Symbol	Inches		Millimeters		Notes
	Min.	Max.	Min.	Max.	
A	.165	.180	4.19	4.57	
A1	.090	.120	2.29	3.05	
A2	.020	—	.51	—	
B	.013	.021	.33	.53	
B1	.026	.032	.66	.81	
D/E	.485	.495	12.32	12.57	
D1/E1	.450	.456	11.43	11.58	3
D3/E3	.300 BSC		7.62 BSC		
e	.050 BSC		1.27 BSC		
J	.042	.048	1.07	1.22	2
ND/NE	7		7		
N	28		28		
ccc	—	.004	—	0.10	

Notes:

1. All dimensions and tolerances conform to ANSI Y14.5M-1982
2. Corner and edge chamfer (J) = 45°
3. Dimension D1 and E1 do not include mold protrusion. Allowable protrusion is .101" (.25mm)



Ordering Information

Product Number	Temperature Range	Speed Grade	Screening	Package	Package Marking
TMC2011AB2C	0°C to 70°C	30 MHz	Commercial	24 Pin 0.3" CerDIP	2011AB2C
TMC2011AB2C1	0°C to 70°C	40 MHz	Commercial	24 Pin 0.3" CerDIP	2011AB2C1
TMC2011AN2C	0°C to 70°C	30 MHz	Commercial	24 Pin 0.3" Plastic DIP	2011AN2C
TMC2011AN2C1	0°C to 70°C	40 MHz	Commercial	24 Pin 0.3" Plastic DIP	2011AN2C1
TMC2011AR3C	0°C to 70°C	30 MHz	Commercial	28 Lead PLCC	2011AR3C
TMC2011AR3C1	0°C to 70°C	40 MHz	Commercial	28 Lead PLCC	2011AR3C1
TMC2111AB2C	0°C to 70°C	30 MHz	Commercial	24 Pin 0.3" CerDIP	2111AB2C
TMC2111AB2C1	0°C to 70°C	40 MHz	Commercial	24 Pin 0.3" CerDIP	2111AB2C1
TMC2111AN2C	0°C to 70°C	30 MHz	Commercial	24 Pin 0.3" Plastic DIP	2111AN2C
TMC2111AN2C1	0°C to 70°C	40 MHz	Commercial	24 Pin 0.3" Plastic DIP	2111AN2C1
TMC2111AR3C	0°C to 70°C	30 MHz	Commercial	28 Lead PLCC	2111AR3C
TMC2111AR3C1	0°C to 70°C	40 MHz	Commercial	28 Lead PLCC	2111AR3C1

For Further Assistance:

Exar Corporation Headquarters and Sales Offices

48720 Kato Road
Fremont, CA 94538 - USA

Tel.: +1 (510) 668-7000
Fax: +1 (510) 668-7001
www.exar.com



A New Direction in Mixed-Signal

NOTICE

EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contained here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.

©2013 Exar Corporation