

### CMOS 16-bit Microcontrollers

#### TMP96C041AF

#### 1. Outline and Device Characteristics

The TMP96C041AF are high-speed advanced 16-bit microcontrollers developed for controlling medium to large-scale equipment. The TMP96C041AF has the improved bus release function, serial interface and RAMless for TMP96C141AF. Otherwise, the devices function in the same way.

The TMP96C041AF is housed in an 80-pin flat package and is pin compatible with TMP96C141F except the P92 (CTS0/SCLK0). Device characteristics are as follows:

(1) Original 16-bit CPU

- TLCS-90 instruction mnemonic upward compatible.
- 16M-byte linear address space
- General-purpose registers and register bank system
- 16-bit multiplication/division and bit transfer/arithmetic instructions
- High-speed micro DMA
  - 4 channels (1.6μs/2 bytes @ 20MHz)

(2) Minimum instruction execution time

- 200ns @ 20MHz

(3) Internal RAM: None

Internal ROM: None

(4) External memory expansion

- Can be expanded up to 16M bytes (for both programs and data).
- Can mix 8- and 16-bit external data buses.

(5) 8-bit timers: 2 channels

(6) 8-bit PWM timers: 2 channels

(7) 16-bit timers: 2 channels

(8) Pattern generators: 4 bits, 2 channels

(9) Serial interface: 2 channels

(10) 10-bit A/D converter: 4 channels

(11) Watchdog timer

(12) Chip select/wait controller: 3 blocks

(13) Interrupt functions

- 3 CPU interrupts: SWI instruction, privileged violation, and Illegal instruction
  - 14 internal interrupts
  - 6 external interrupts
- 7-level priority can be set.

(14) I/O ports

- 47pins

(15) Standby function : 3 halt modes (RUN, IDLE, STOP)

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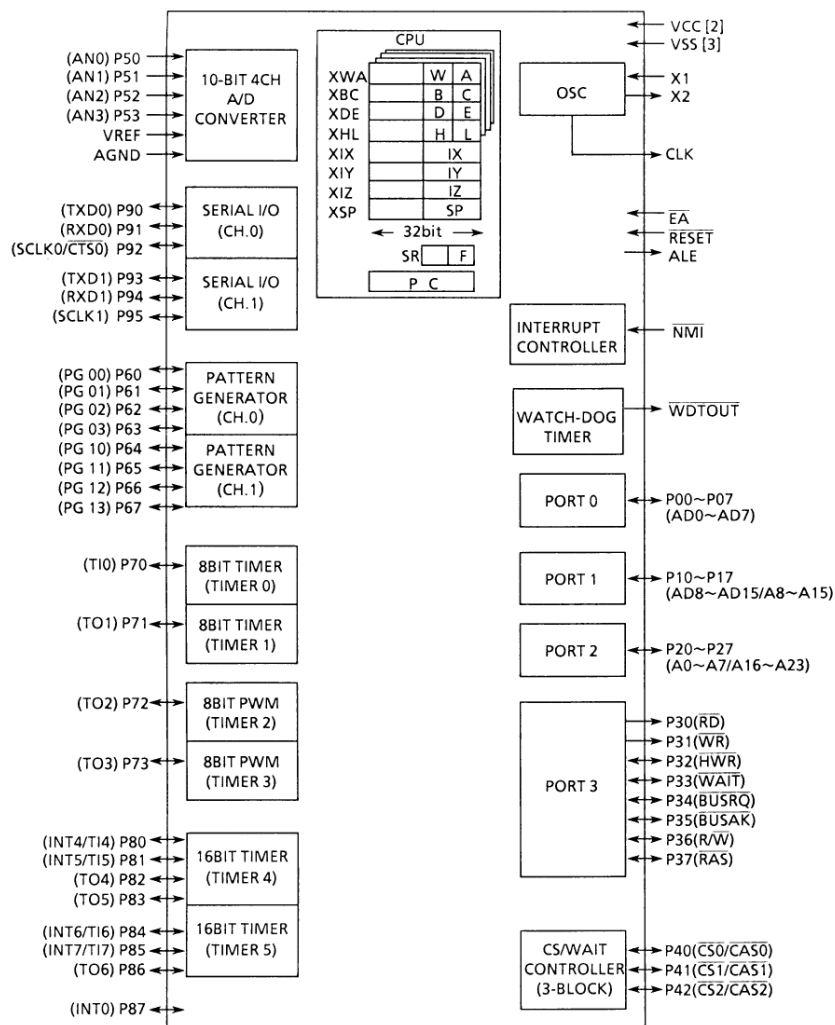


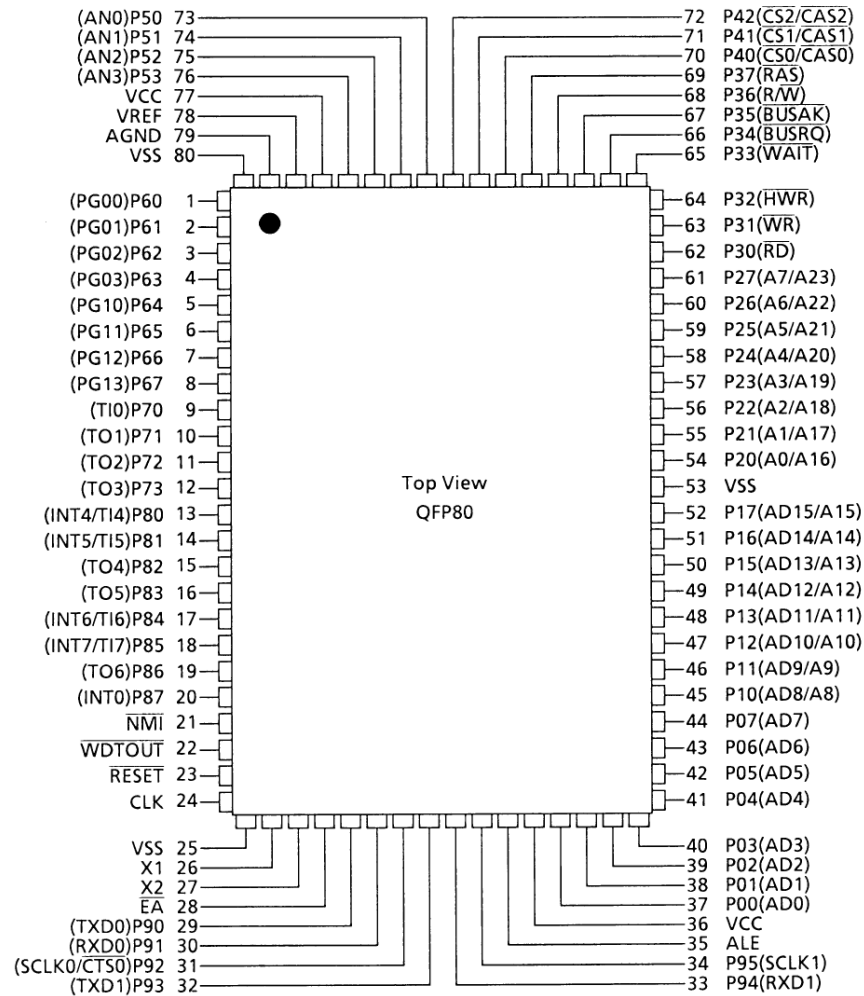
Figure 1. TMP96C041AF Block Diagram

## 2. Pin Assignment and Functions

The assignment of input/output pins for TMP96C041AF, their name and outline functions are described below.

### 2.1 Pin Assignment

Figure 2.1 shows pin assignment of TMP96C041AF.



Note : Because the TMP96C041AF has an external ROM, P00 to P17 pins are fixed to AD0 to AD15; P30 to  $\overline{RD}$ ; and P31 to  $\overline{WR}$ .

Figure 2.1. Pin Assignment (80-pin QFP)

## 2.2 Pin Names and Functions

The names of input/output pins and their functions are described below.

**Table 2.2. Pin Names and Functions**

| Pin Name                            | Number of Pins | I/O                        | Functions                                                                                                                                                                                                                                                                                                                        |
|-------------------------------------|----------------|----------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| P00 ~ P07<br>AD0 ~ AD7              | 8              | I/O<br>Tri-state           | Port 0: I/O port that allows I/O to be selected on a bit basis<br>Address / data (lower): 0 - 7 for address / data bus                                                                                                                                                                                                           |
| P10 ~ P17<br>AD8 ~ AD15<br>A8 ~ A15 | 8              | I/O<br>Tri-state<br>Output | Port 1: I/O port that allows I/O to be selected on a bit basis<br>Address data (upper): 8 - 15 for address / data bus<br>Address: 8 to 15 for address bus                                                                                                                                                                        |
| P20 ~ P27<br>A0 ~ A7<br>A16 ~ A23   | 8              | I/O<br>Output<br>Output    | Port 2: I/O port that allows selection of I/O on a bit basis (with pull-down resistor)<br>Address: 0 - 7 for address bus<br>Address: 16 - 23 for address bus                                                                                                                                                                     |
| P30<br>RD                           | 1              | Output<br>Output           | Port 30: Output port<br>Read: Strobe signal for reading external memory                                                                                                                                                                                                                                                          |
| P31<br>WR                           | 1              | Output<br>Output           | Port 31: Output port<br>Write: Strobe signal for writing data on pins AD0 -7                                                                                                                                                                                                                                                     |
| P32<br>HWR                          | 1              | I/O<br>Output              | Port 32: I/O port (with pull-up resistor)<br>High write: Strobe signal for writing data on pins AD8 - 15                                                                                                                                                                                                                         |
| P33<br>WAIT                         | 1              | I/O<br>Input               | Port 33: I/O port (with pull-up resistor)<br>Wait: Pin used to request CPU bus wait                                                                                                                                                                                                                                              |
| P34<br>BUSRQ                        | 1              | I/O<br>Input               | Port 34: I/O port (with pull-up resistor)<br>Bus request: Signal used to request high impedance for AD0 - 15, A0 - 23, $\overline{RD}$ , $\overline{WR}$ , $\overline{HWR}$ , $R/\overline{W}$ , $\overline{RAS}$ , $\overline{CS0}$ , $\overline{CS1}$ , and $\overline{CS2}$ pins. (For external DMAC)                         |
| P35<br>BUSAK                        | 1              | I/O<br>Output              | Port 35: I/O (with pull-up resistor)<br>Bus acknowledge: Signal indicating that AD0 - 15, A0 - 23, $\overline{RD}$ , $\overline{WR}$ , $\overline{HWR}$ , $R/\overline{W}$ , $\overline{RAS}$ , $\overline{CS0}$ , $\overline{CS1}$ , and $\overline{CS2}$ pins are at high impedance after receiving BUSRQ. (For external DMAC) |
| P36<br>R/W                          | 1              | I/O<br>Output              | Port 36: I/O port (with pull-up resistor)<br>Read/write: 1 represents read or dummy cycle; 0, write cycle.                                                                                                                                                                                                                       |
| P37<br>RAS                          | 1              | I/O<br>Output              | Port 37: I/O port (with pull-up resistor)<br>Row address strobe: Outputs RAS strobe for DRAM.                                                                                                                                                                                                                                    |
| P40<br>$\overline{CS0}$<br>CAS0     | 1              | I/O<br>Output<br>Output    | Port 40: I/O port (with pull-up resistor)<br>Chip select 0: Outputs 0 when address is within specified address area.<br>Column address strobe 0: Outputs CAS strobe for DRAM when address is within specified address area.                                                                                                      |

Note: With the external DMA controller, this device's built-in memory or built-in I/O cannot be accessed using the  $\overline{BUSRQ}$  and  $\overline{BUSAK}$  pins.

| Pin Name                         | Number of Pins | I/O                     | Functions                                                                                                                                                                                                                      |
|----------------------------------|----------------|-------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| P41<br><u>CS1</u><br><u>CAS1</u> | 1              | I/O<br>Output<br>Output | Port 41: I/O port (with pull-up resistor)<br>Chip select 1: Outputs 0 if address is within specified address area.<br>Column address strobe 1: Outputs <u>CAS</u> strobe for DRAM if address is within specified address area. |
| P42<br><u>CS2</u><br><u>CAS2</u> | 1              | I/O<br>Output<br>Output | Port 42: I/O port (with pull-up resistor)<br>Chip select 2: Outputs 0 if address is within specified address area.<br>Column address strobe 2: Outputs <u>CAS</u> strobe for DRAM if address is within specified address area. |
| P50 ~ P53<br>AN0 ~ AN3           | 4              | Input<br>Input          | Port 5: Input port<br>Analog input: Input to A/D converter                                                                                                                                                                     |
| VREF                             | 1              | Input                   | Pin for reference voltage input to A/D converter                                                                                                                                                                               |
| AGND                             | 1              | Input                   | Ground pin for A/D converter                                                                                                                                                                                                   |
| P60 ~ P63<br>PG00 ~ PG03         | 4              | I/O<br>Output           | Ports 60 - 63: I/O ports that allow selection of I/O on a bit basis (with pull-up resistor)<br>Pattern generator ports: 00 - 03                                                                                                |
| P64 ~ P67<br>PG10 ~ PG13         | 4              | I/O<br>Output           | Ports 64 - 67: I/O ports that allow selection of I/O on a bit basis (with pull-up resistor)<br>Pattern generator ports: 10 - 13                                                                                                |
| P70<br>T10                       | 1              | I/O<br>Input            | Port 70: I/O port (with pull-up resistor)<br>Timer input 0: Timer 0 input                                                                                                                                                      |
| P71<br>T01                       | 1              | I/O<br>Output           | Port 71: I/O port (with pull-up resistor)<br>Timer output 1: Timer 0 or 1 output                                                                                                                                               |
| P72<br>T02                       | 1              | I/O<br>Output           | Port 72: I/O port (with pull-up resistor)<br>PWM output 2: 8-bit PWM timer 2 output                                                                                                                                            |
| P73<br>T03                       | 1              | I/O<br>Output           | Port 73: I/O port (with pull-up resistor)<br>PWM output 3: 8-bit PWM timer 3 output                                                                                                                                            |
| P80<br>T14<br>INT4               | 1              | I/O<br>Input<br>Input   | Port 80: I/O port (with pull-up resistor)<br>Timer input 4: Timer 4 count/capture trigger signal input<br>Interrupt request pin 4: Interrupt request pin with programmable rising/falling edge                                 |
| P81<br>T15<br>INT5               | 1              | I/O<br>Input<br>Input   | Port 81: I/O port (with pull-up resistor)<br>Timer input 5: Timer 4 count/capture trigger signal input<br>Interrupt request pin 5: Interrupt request pin with rising edge                                                      |
| P82<br>T04                       | 1              | I/O<br>Output           | Port 82: I/O port (with pull-up resistor)<br>Timer output 4: Timer 4 output pin                                                                                                                                                |
| P83<br>T05                       | 1              | I/O<br>Output           | Port 83: I/O port (with pull-up resistor)<br>Timer output 5: Timer 4 output pin                                                                                                                                                |

Note 1: Case of the settable CS2 and CAS2; when TMP96C041AF is bus release, this pin is not added the internal pull-down resistor but is added the internal pull-up resistor.

| Pin Name             | Number of Pins | I/O                   | Functions                                                                                                                                                                                      |
|----------------------|----------------|-----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| P84<br>TI6<br>INT6   | 1              | I/O<br>Input<br>Input | Port 84: I/O port (with pull-up resistor)<br>Timer input 6: Timer 5 count/capture trigger signal input<br>Interrupt request pin 6: Interrupt request pin with programmable rising/falling edge |
| P85<br>TI7<br>INT7   | 1              | I/O<br>Input<br>Input | Port 85: I/O port (with pull-up resistor)<br>Timer input 7: Timer 5 count/capture trigger signal input<br>Interrupt request pin 7: Interrupt request pin with rising edge                      |
| P86<br>TO6           | 1              | I/O<br>Output         | Port 86: I/O port (with pull-up resistor)<br>Timer output 6: Timer 5 output pin                                                                                                                |
| P87<br>INT0          | 1              | I/O<br>Input          | Port 87: I/O port (with pull-up resistor)<br>Interrupt request pin 0: Interrupt request pin with programmable level/rising edge                                                                |
| P90<br>TXD0          | 1              | I/O<br>Output         | Port 90: I/O port (with pull-up resistor)<br>Serial send data 0                                                                                                                                |
| P91<br>RXD0          | 1              | I/O<br>Input          | Port 91: I/O port (with pull-up resistor)<br>Serial receive data 0                                                                                                                             |
| P92<br>CTS0<br>SCLK0 | 1              | I/O<br>Input          | Port 92: I/O port (with pull-up resistor)<br>Serial data send enable 0 (Clear to Send)<br>Serial clock I/O 0                                                                                   |
| P93<br>TXD1          | 1              | I/O<br>Output         | Port 93: I/O port (with pull-up resistor)<br>Serial send data 1                                                                                                                                |
| P94<br>RXD1          | 1              | I/O<br>Input          | Port 94: I/O port (with pull-up resistor)<br>Serial receive data 1                                                                                                                             |
| P95<br>SCLK1         | 1              | I/O<br>I/O            | Port 95: I/O port (with pull-up resistor)<br>Serial clock I/O 1                                                                                                                                |
| WDTOUT               | 1              | Output                | Watchdog timer output pin                                                                                                                                                                      |
| NMI                  | 1              | Input                 | Non-maskable interrupt request pin: Interrupt request pin with falling edge.<br>Can also be operated at rising edge by program.                                                                |
| CLK                  | 1              | Output                | Clock output: Outputs $\lceil X1 \div 4 \rceil$ clock. Pulled-up during reset.                                                                                                                 |
| $\overline{EA}$      | 1              | Input                 | External access: 0 should be inputted with TMP96C041AF.                                                                                                                                        |
| ALE                  | 1              | Output                | Address latch enable                                                                                                                                                                           |
| $\overline{RESET}$   | 1              | Input                 | Reset: Initializes LSI. (With pull-up resistor)                                                                                                                                                |
| X1/X2                | 2              | I/O                   | Oscillator connecting pin                                                                                                                                                                      |
| VCC                  | 2              |                       | Power supply pin (+5V)                                                                                                                                                                         |
| VSS                  | 3              |                       | GND pin (0V)                                                                                                                                                                                   |

Note: Pull-up/pull-down resistor can be released from the pin by software (except the  $\overline{RESET}$  pin).

### 3. Operation

This section describes in blocks the functions and basic operations of the TMP96C041AF device.

Check the chapter Guidelines and Restrictions for proper care of the device.

#### 3.1 CPU

The TMP96C041AF device has a built-in high-performance 16-bit CPU. (For CPU operation, see TLCS-900 CPU in the book Core Architecture User Manual.)

#### 3.2 Memory Map

The TMP96C041AF has two register modes. One is minimum mode; in this mode, the area of program memory is 64K bytes maximum. The other is maximum mode; in this mode, the area of the program memory is 16M bytes maximum.

Both minimum and maximum modes are the data memory area 16M bytes maximum.

That is, the program memory can locate 0H ~ FFFFFFFH in maximum mode.

##### (1) Internal /O Devices

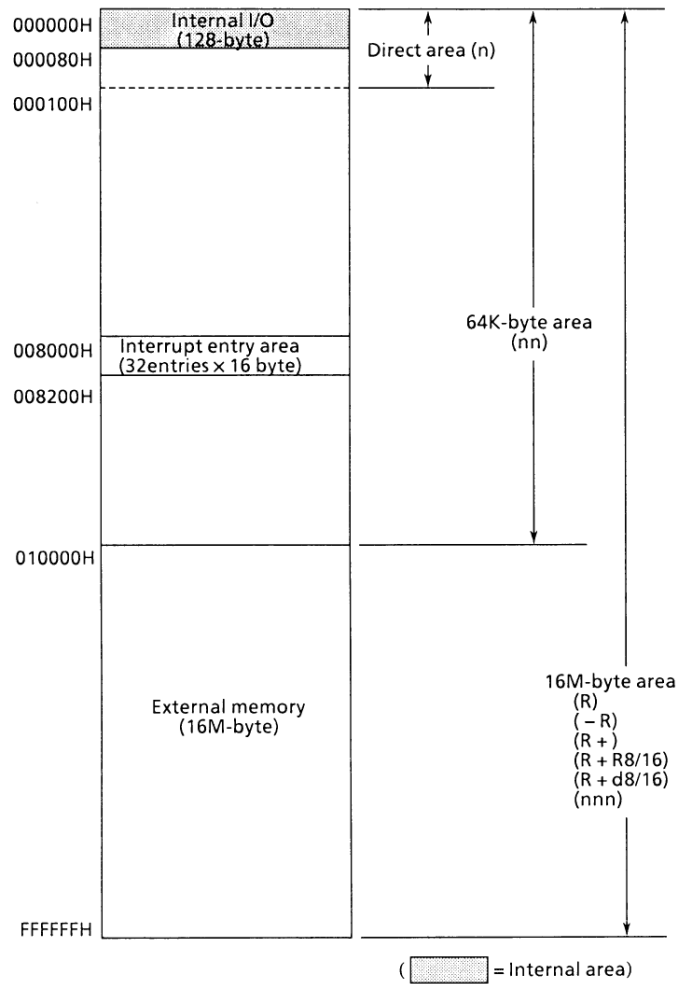
The TMP96C041AF uses the address space of 128 bytes for the internal I/O devices area. This area is located to 0H ~ 7FH.

The CPU can access the internal I/O devices area with using short instruction code of direct addressing mode.

Check the access area of each addressing mode and the memory map in Fig. 3.2 (1).

3.2 Memory Map

Figure 3.2 is a memory map of the TMP96C041AF.



Note: The start address after reset is 8000H. Resetting sets the stack pointer (XSP) on the system mode side to 100H.

Figure 3.2. Memory Map

(2)  $\overline{CS1}$  Area (Chip Select/Wait Controller)

address area for  $\overline{CS1}$  (only B1C1.0 = "00"). Show the address area of  $\overline{CS1}$  in Fig. 3.2 (2).

The TMP96C041AF is expanded the part of the

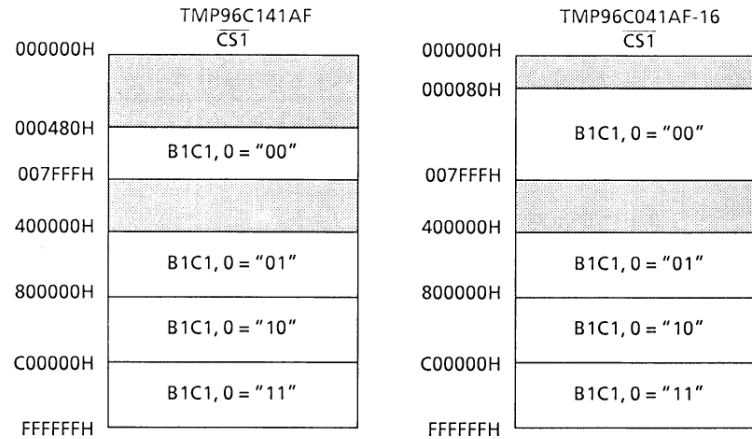


Fig. 3.2 (2).  $\overline{CS1}$  Address Area

### 3.3 Bus Release Function

The TMP96C041AF has the internal pull-up and pull down resistors to fix the bus control signals at bus release.

Show the table 3.3 of pin condition at bus release ( $\overline{BUSA} = 0$ ).

Table 3.3 Pin Condition at Bus Release ( $\overline{BUSA} = "L"$ )

| Pin Name                                                                                   | Pin state at bus release                          |                                                                                                                                                                    |
|--------------------------------------------------------------------------------------------|---------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                                                            | Port Mode                                         | Function Mode                                                                                                                                                      |
| P00 - P07<br>(AD0 - AD7)<br>P10 - P17<br>(AD8 - 15/AD8 - 15)                               | The status is no-change (these pins are not "Hz") | These pins are "Hz".                                                                                                                                               |
| P30 ( $\overline{RD}$ )<br>P31 ( $\overline{WR}$ )                                         | ↑                                                 | These pins are "Hz".<br>("Hz" stays after these pins driven high level)                                                                                            |
| P32 ( $\overline{HWR}$ )<br>P37 (RAS)                                                      | ↑                                                 | The output buffer is "OFF" after these pins driven high.<br>These pins are added the internal resistor of pull-up. It's no relation for the value of output latch. |
| P36 ( $\overline{R/W}$ )<br>P40 ( $\overline{CS0/CAS0}$ )<br>P41 ( $\overline{CS1/CAS1}$ ) | ↑                                                 | ↑                                                                                                                                                                  |
| P20 - P27<br>(A16 - A23)<br>P42 ( $\overline{CS2/CAS2}$ )                                  | ↑                                                 | (*) ↑                                                                                                                                                              |
| P20 - P27<br>(A16 - A23)                                                                   | ↑                                                 | The output buffer is "OFF" after these pins driven low.<br>These pins are added the internal resistor of pull-up. It's no relation for the value of output latch.  |

That is, when it is used for bus release ( $\overline{BUSA} = 0$ ), the pins of below need pull-up or pull-down resistor for an external circuit.

P00 - P07 (AD0 AD7)  
P10 - P17 (AD8 AD15)

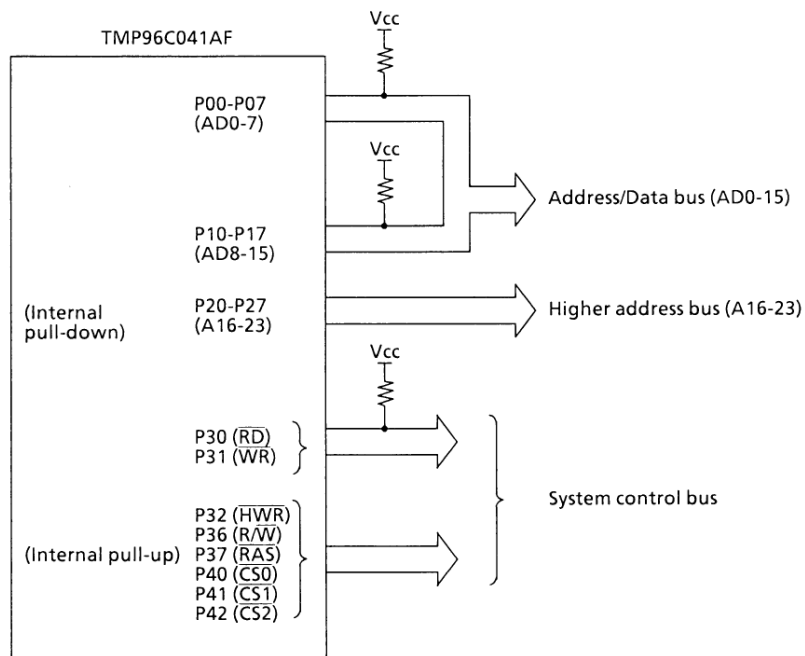
P30 ( $\overline{RD}$ )  
P31 ( $\overline{WR}$ )

(\*) P42 has the resistor of programmable pull-down, but when the bus are released, P42 pin is added a resistor of pull-up.

For the bus release function; show a sample of external bus interface in the Figure 3.3 (1).

When the bus is released, both internal memory and internal I/O cannot be accessed. But the internal I/O continues

to run. So, the watchdog timer also continues to run. Therefore, be careful about bus releasing time and set the detection time of WDT.



**Figure 3.3 (1). Example of the Interface Circuit (Bus Releasing Function)**

## 3.4 Serial Function

The TMP96C041AF has two Serial I/O devices. But channel 0 and channel 1 are same function except the handshake (CTS0

pin) function of the channel 0 and can use I/O interface mode. Show the part of TMP96C41AF in detail.

## 4. Electrical Characteristics

### 4.1 Absolute Maximum (TMP96C041AF)

| Symbol          | Parameter                                      | Rating                | Unit             |
|-----------------|------------------------------------------------|-----------------------|------------------|
| $V_{CC}$        | Power Supply Voltage                           | -0.5 ~ 6.5            | V                |
| $V_{IN}$        | Input Voltage                                  | -0.5 ~ $V_{CC} + 0.5$ | V                |
| $\Sigma I_{OL}$ | Output Current (total)                         | 100                   | mA               |
| $\Sigma I_{OH}$ | Output Current (total)                         | -100                  | mA               |
| PD              | Power Dissipation ( $T_a = 70^\circ\text{C}$ ) | 600                   | mW               |
| T SOLDER        | Soldering Temperature (10s)                    | 260                   | $^\circ\text{C}$ |
| T STG           | Storage Temperature                            | -65 ~ 150             | $^\circ\text{C}$ |
| T OPR           | Operating Temperature                          | -20 ~ 70              | $^\circ\text{C}$ |

#### 4.2 DC Characteristics (TMP96C041AF)

$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ C$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ C$  (4 ~ 20MHz)  
(Typical values are for  $T_A = 25^\circ C$  and  $V_{CC} = 5V$ )

| Symbol | Parameter                                                           | Min            | Max            | Unit       | Test Condition                               |
|--------|---------------------------------------------------------------------|----------------|----------------|------------|----------------------------------------------|
| V IL   | Input Low Voltage (AD0-15)                                          | -0.3           | 0.8            | V          |                                              |
| V IL1  | P2, P3, P4, P5, P6, P7, P8, P9                                      | -0.3           | $0.3V_{CC}$    | V          |                                              |
| V IL2  | $\overline{RESET}$ , $\overline{NMI}$ , INTO (P87)                  | -0.3           | $0.25V_{CC}$   | V          |                                              |
| V IL3  | $\overline{EA}$                                                     | -0.3           | 0.3            | V          |                                              |
| V IL4  | X1                                                                  | -0.3           | $0.2V_{CC}$    | V          |                                              |
| V IH   | Input High Voltage (AD0-15)                                         | 2.2            | $V_{CC} + 0.3$ | V          |                                              |
| V IH1  | P2, P3, P4, P5, P6, P7, P8, P9                                      | $0.7V_{CC}$    | $V_{CC} + 0.3$ | V          |                                              |
| V IH2  | $\overline{RESET}$ , $\overline{NMI}$ , INTO (P87)                  | $0.75V_{CC}$   | $V_{CC} + 0.3$ | V          |                                              |
| V IH3  | $\overline{EA}$                                                     | $V_{CC} - 0.3$ | $V_{CC} + 0.3$ | V          |                                              |
| V IH4  | X1                                                                  | $0.8V_{CC}$    | $V_{CC} + 0.3$ | V          |                                              |
| V OL   | Output Low Voltage                                                  |                | 0.45           | V          | I OL = 1.6mA                                 |
| V OH   | Output High Voltage                                                 | 2.4            |                | V          | I OH = -400 $\mu$ A                          |
| V OH1  |                                                                     | $0.75V_{CC}$   |                | V          | I OH = -100 $\mu$ A                          |
| V OH2  |                                                                     | $0.9V_{CC}$    |                | V          | I OH = -20 $\mu$ A                           |
| I DAR  | Darlington Drive Current<br>(8 Output Pins max.)                    | -1.0           | -3.5           | mA         | V EXT = 1.5V<br>R EXT = 1.1K $\Omega$        |
| I LI   | Input Leakage Current                                               | TBD (Typ)      | $\pm 5$        | $\mu$ A    | $0.0 \leq V_{in} \leq V_{CC}$                |
| I LO   | Output Leakage Current                                              | TBD (Typ)      | $\pm 10$       | $\mu$ A    | $0.2 \leq V_{in} \leq V_{CC} - 0.2$          |
| I CC   | Operating Current (RUN)                                             | TBD (Typ)      | TBD            | mA         | $t_{osc} = 20MHz$                            |
|        | IDLE                                                                | TBD (Typ)      | 10             | mA         |                                              |
|        | STOP ( $T_A = -20 \sim 70^\circ C$ )                                | TBD (Typ)      | 50             | $\mu$ A    | $0.2 \leq V_{in} \leq V_{CC} - 0.2$          |
|        | STOP ( $T_A = 0 \sim 50^\circ C$ )                                  | TBD (Typ)      | 10             | $\mu$ A    | $0.2 \leq V_{in} \leq V_{CC} - 0.2$          |
| V STOP | Power Down Voltage<br>(@STOP, RAM Back up)                          | 2.0            | 6.0            | V          | V IL2 = $0.2V_{CC}$ ,<br>V IH2 = $0.8V_{CC}$ |
| R RST  | RESET Pull Up Register                                              | 50             | 150            | K $\Omega$ |                                              |
| C IO   | Pin Capacitance                                                     |                | 10             | pF         | $t_{osc} = 1MHz$                             |
| V TH   | Schmitt Width<br>$\overline{RESET}$ , $\overline{NMI}$ , INTO (P87) | 0.4            | TBD (Typ)      | V          |                                              |
| R K    | Pull Down/Up Register                                               | 50             | 150            | K $\Omega$ |                                              |

Note: I-DAR is guaranteed for a total of up to 8 ports.

## 4.3 AC Electrical Characteristics (TMP96C041AF)

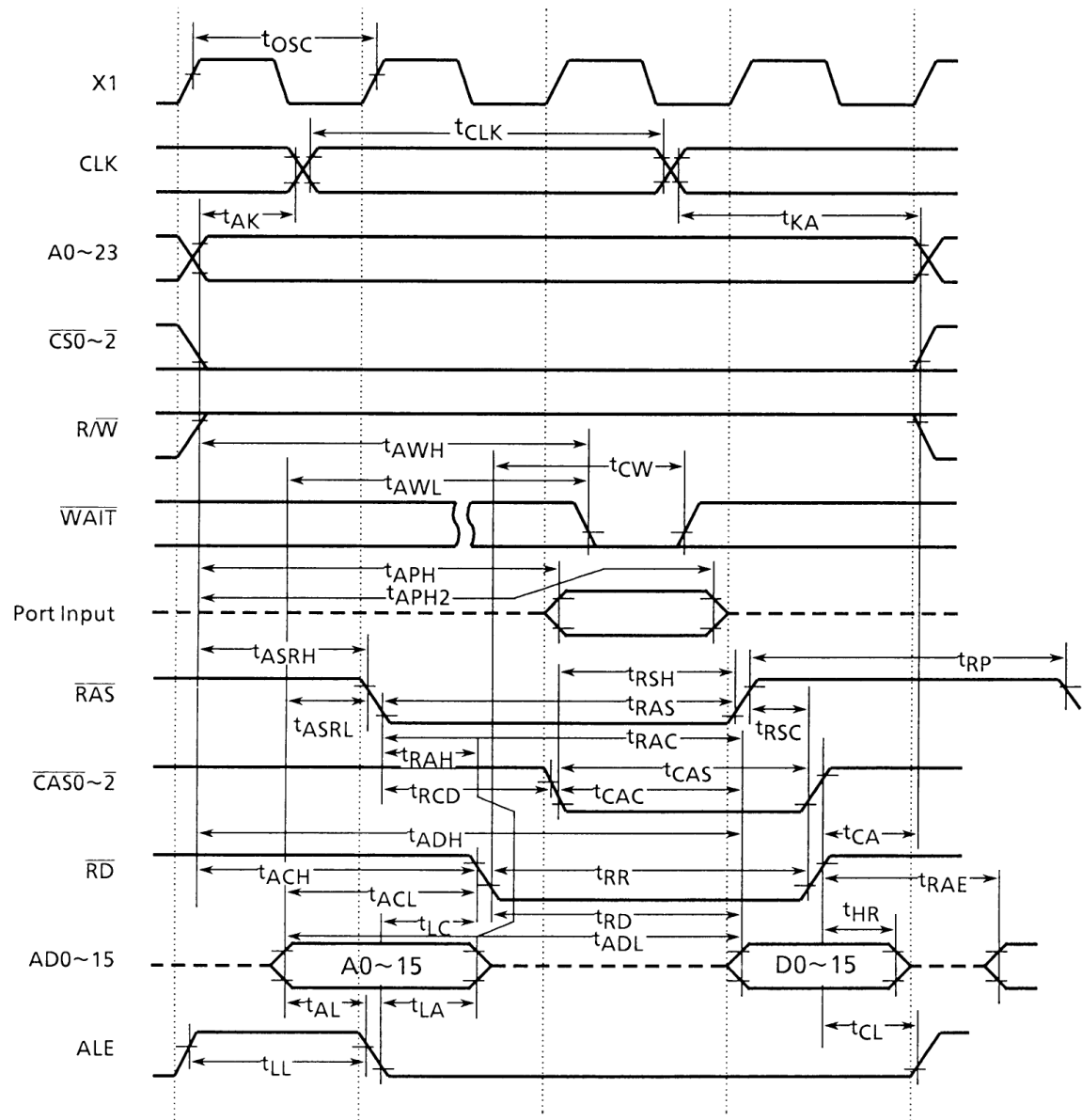
 $V_{CC} = 5V \pm 10\%$  TA = -40 ~ 85°C (4 ~ 16MHz) TA = -20 ~ 70°C (4MHz ~ 20MHz)

| No. | Symbol     | Parameter                                                                   | Variable  |            | 16MHz |     | 20MHz |     | Unit |
|-----|------------|-----------------------------------------------------------------------------|-----------|------------|-------|-----|-------|-----|------|
|     |            |                                                                             | Min       | Max        | Min   | Max | Min   | Max |      |
| 1   | $t_{OSC}$  | Osc. Period (= x)                                                           | 50        | 250        | 62.5  |     | 50    |     | ns   |
| 2   | $t_{CLK}$  | CLK width                                                                   | 2x - 40   |            | 85    |     | 60    |     | ns   |
| 3   | $t_{AK}$   | A0 - 23 Valid→CLK Hold                                                      | 0.5x - 20 |            | 11    |     | 5     |     | ns   |
| 4   | $t_{KA}$   | CLK Valid→A0 - 23 Hold                                                      | 1.5x - 70 |            | 24    |     | 5     |     | ns   |
| 5   | $t_{AL}$   | A0-15 Valid→ALE fall                                                        | 0.5x - 15 |            | 16    |     | 10    |     | ns   |
| 6   | $t_{LA}$   | ALE fall→A0 - 15 Hold                                                       | 0.5x - 15 |            | 16    |     | 10    |     | ns   |
| 7   | $t_{LL}$   | ALE High width                                                              | x - 40    |            | 23    |     | 10    |     | ns   |
| 8   | $t_{LC}$   | ALE fall→ $\overline{RD}/\overline{WR}$ fall                                | 0.5x - 30 |            | 1     |     | -5    |     | ns   |
| 9   | $t_{CL}$   | $\overline{RD}/\overline{WR}$ rise→ALE rise                                 | 0.5x - 20 |            | 11    |     | 5     |     | ns   |
| 10  | $t_{ACL}$  | A0 - 15 Valid→ $\overline{RD}/\overline{WR}$ fall                           | x - 25    |            | 38    |     | 25    |     | ns   |
| 11  | $t_{ACH}$  | A0 - 23 Valid→ $\overline{RD}/\overline{WR}$ fall                           | 1.5x - 50 |            | 44    |     | 25    |     | ns   |
| 12  | $t_{CA}$   | $\overline{RD}/\overline{WR}$ rise→A0 - 23 Hold                             | 0.5x - 20 |            | 11    |     | 5     |     | ns   |
| 13  | $t_{ADL}$  | A0 - 15 Valid→D0 - 15 input                                                 |           | 3.0x - 45  |       | 143 |       | 105 | ns   |
| 14  | $t_{ADH}$  | A0 - 23 Valid→D0 - 15 input                                                 |           | 3.5x - 65  |       | 154 |       | 110 | ns   |
| 15  | $t_{RD}$   | $\overline{RD}$ fall→D0 - 15 input                                          |           | 2.0x - 50  |       | 75  |       | 50  | ns   |
| 16  | $t_{RR}$   | $\overline{RD}$ Low width                                                   | 2.0x - 40 |            | 85    |     | 60    |     | ns   |
| 17  | $t_{HR}$   | $\overline{RD}$ rise→D0 - 15 Hold                                           | 0         |            | 0     |     | 0     |     | ns   |
| 18  | $t_{RAE}$  | $\overline{RD}$ rise→A0 - 15 output                                         | x - 15    |            | 48    |     | 35    |     | ns   |
| 19  | $t_{WW}$   | $\overline{WR}$ Low width                                                   | 2.0x - 40 |            | 85    |     | 60    |     | ns   |
| 20  | $t_{DW}$   | D0 - 15 Valid→ $\overline{WR}$ rise                                         | 2.0x - 50 |            | 75    |     | 50    |     | ns   |
| 21  | $t_{WD}$   | $\overline{WR}$ rise→D0 - 15 Hold                                           | 0.5x - 10 |            | 21    |     | 15    |     | ns   |
| 22  | $t_{AEH}$  | A0 - 23 Valid→ $\overline{WAIT}$ input (1WAIT + n mode)                     |           | 3.5x - 90  |       | 129 |       | 85  | ns   |
| 23  | $t_{AWL}$  | A0 - 15 Valid→ $\overline{WAIT}$ input (1WAIT + n mode)                     |           | 3.0x - 80  |       | 108 |       | 70  | ns   |
| 24  | $t_{CW}$   | $\overline{RD}/\overline{WR}$ fall→ $\overline{WAIT}$ Hold (1WAIT + n mode) | 2.0x + 0  |            | 125   |     | 100   |     | ns   |
| 25  | $t_{APH}$  | A0 - 23 Valid→PORT input                                                    |           | 2.5x - 120 |       | 80  |       | 36  | ns   |
| 26  | $t_{APH2}$ | A0 - 23 Valid→PORT Hold                                                     | 2.5x + 50 |            | 206   |     | 175   |     | ns   |
| 27  | $t_{CP}$   | $\overline{WR}$ rise→PORT Valid                                             |           | 200        |       | 200 |       | 200 | ns   |
| 28  | $t_{ASRH}$ | A0 - 23 Valid→ $\overline{RAS}$ fall                                        | 1.0x - 40 |            | 23    |     | 10    |     | ns   |
| 29  | $t_{ASRL}$ | A0 - 15 Valid→ $\overline{RAS}$ fall                                        | 0.5x - 15 |            | 16    |     | 10    |     | ns   |
| 30  | $t_{RAC}$  | $\overline{RAS}$ fall→D0 - 15 input                                         |           | 2.5x - 70  |       | 130 |       | 86  | ns   |
| 31  | $t_{RAH}$  | $\overline{RAS}$ fall→A0 - 15 Hold                                          | 0.5x - 15 |            | 16    |     | 10    |     | ns   |
| 32  | $t_{RAS}$  | $\overline{RAS}$ Low width                                                  | 2.0x - 40 |            | 85    |     | 60    |     | ns   |
| 33  | $t_{RP}$   | $\overline{RAS}$ High width                                                 | 2.0x - 40 |            | 85    |     | 60    |     | ns   |
| 34  | $t_{RSH}$  | $\overline{CAS}$ fall→ $\overline{RAS}$ rise                                | 1.0x - 35 |            | 28    |     | 15    |     | ns   |
| 35  | $t_{RSC}$  | $\overline{RAS}$ rise→ $\overline{CAS}$ rise                                | 0.5x - 25 |            | 6     |     | 0     |     | ns   |
| 36  | $t_{RCD}$  | $\overline{RAS}$ fall→ $\overline{CAS}$ fall                                | 1.0x - 40 |            | 23    |     | 10    |     | ns   |
| 37  | $t_{CAC}$  | $\overline{CAS}$ fall→D0 - 15 input                                         |           | 1.5x - 65  |       | 29  |       | 10  | ns   |
| 38  | $t_{CAS}$  | $\overline{CAS}$ Low width                                                  | 1.5x - 30 |            | 64    |     | 40    |     | ns   |
| 39  | $t_{DS}$   | D0 - 15 valid→ $\overline{CAS}$ fall                                        | 0.5x - 15 |            | 16    |     | 10    |     | ns   |

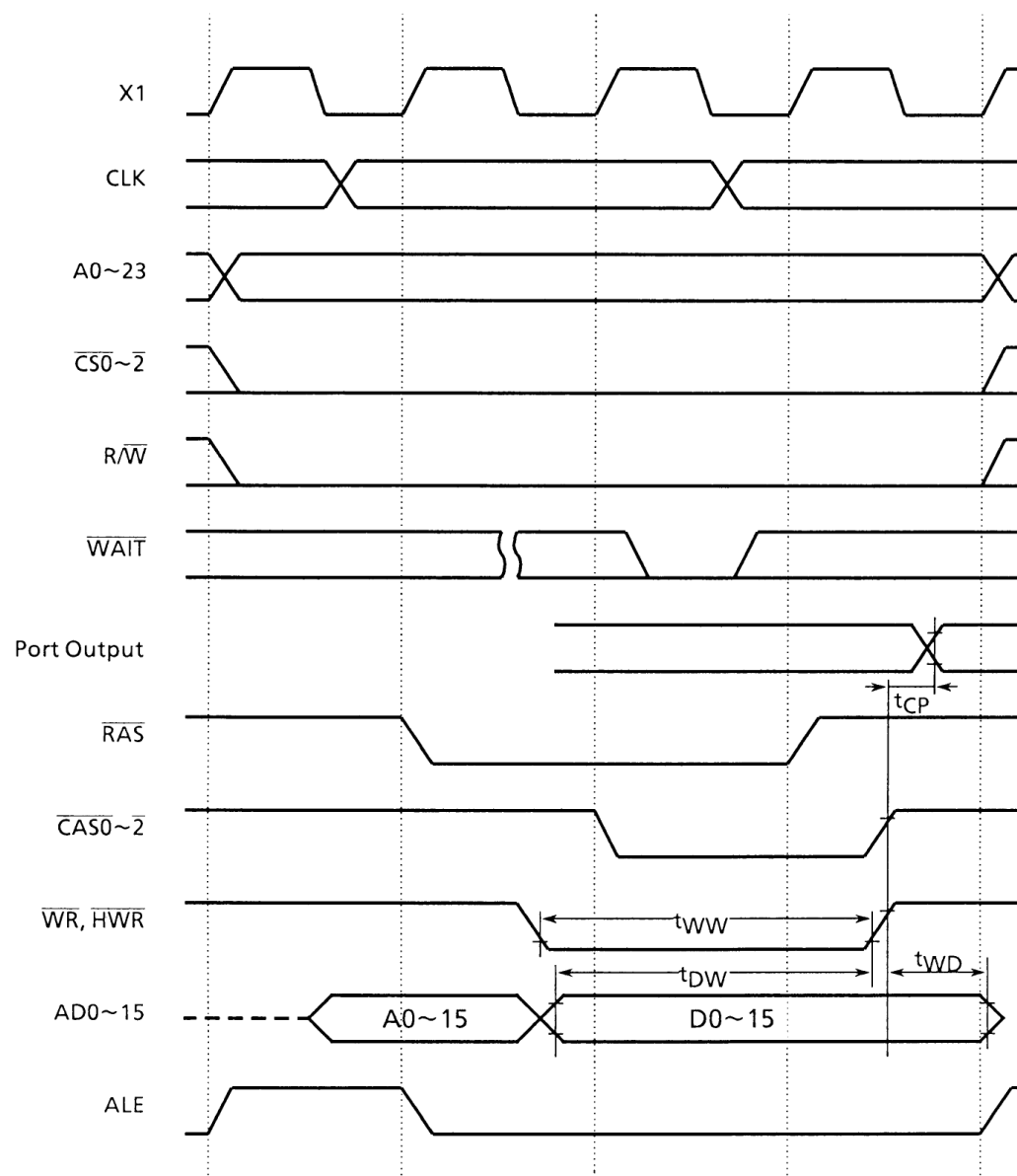
## AC Measuring Conditions

- Output Level: High 2.2V /Low 0.8V, CL50pF  
(However CL = 100pF for AD0 ~ AD15, AD0 ~ AD23, ALE,  $\overline{RD}$ ,  $\overline{WR}$ ,  $\overline{HWR}$ ,  $\overline{R}/\overline{W}$ , CLK,  $\overline{RAS}$ ,  $\overline{CAS0}$  ~  $\overline{CAS2}$ )
- Input Level: High 2.4V /Low 0.45V (AD0 ~ AD15)  
High 0.8V<sub>CC</sub> /Low 0.2V<sub>CC</sub> (Except for AD0 ~ AD15)

(1) Read Cycle



## (2) Write Cycle



#### 4.4 A/D Conversion Characteristics (TMP96C041AF)

$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ C$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ C$  (4 ~ 20MHz)

| Symbol                                                  | Parameter                                   |                            | Min            | Typ | Max       | Unit |
|---------------------------------------------------------|---------------------------------------------|----------------------------|----------------|-----|-----------|------|
| $V_{REF}$                                               | Analog reference voltage                    |                            | $V_{CC} - 1.5$ |     | $V_{CC}$  | V    |
| $A_{GND}$                                               | Analog reference voltage                    |                            | $V_{SS}$       |     | $V_{SS}$  |      |
| $V_{AIN}$                                               | Analog input voltage range                  |                            | $V_{SS}$       |     | $V_{CC}$  |      |
| $I_{REF}$                                               | Analog current for analog reference voltage |                            |                | TBD | 1.5       | mA   |
| Error<br>(Quantize error of $\pm 0.5$ LSB not included) | $4 \leq f_c \leq 16\text{MHz}$              | High speed conversion mode |                | TBD | $\pm 4.0$ | LSB  |
|                                                         |                                             | Low speed conversion mode  |                | TBD | $\pm 6.0$ |      |
|                                                         | $16 \leq f_c \leq 20\text{MHz}$             | High speed conversion mode |                | TBD | $\pm 4.0$ |      |
|                                                         |                                             | Low speed conversion mode  |                | TBD | $\pm 8.0$ |      |

#### 4.5 Serial Channel Timing - I/O Interface Mode

$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ C$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ C$  (4 ~ 20MHz)

(1) SCLK Input Mode

| Symbol    | Parameter                             | Variable              |                      | 16MHz |     | 20MHz |     | Unit    |
|-----------|---------------------------------------|-----------------------|----------------------|-------|-----|-------|-----|---------|
|           |                                       | Min                   | Max                  | Min   | Max | Min   | Max |         |
| $t_{SCY}$ | SCLK cycle                            | 16x                   |                      | 1     |     | 0.8   |     | $\mu s$ |
| $t_{OSS}$ | Output Data→Rising edge of SCLK       | $t_{SCY}/2 - 5x - 50$ |                      | 137   |     | 100   |     | ns      |
| $t_{OHS}$ | SCLK rising edge→Output Data hold     | $5x - 100$            |                      | 212   |     | 150   |     | ns      |
| $t_{HSR}$ | SCLK rising edge→Input Data hold      | 0                     |                      | 0     |     | 0     |     | ns      |
| $t_{SRD}$ | SCLK rising edge→effective data input |                       | $t_{SCY} - 5x - 100$ |       | 587 |       | 450 | ns      |

$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ C$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ C$  (4 ~ 20MHz)

(2) SCLK Output Mode

| Symbol    | Parameter                             | Variable             |                      | 16MHz |     | 20MHz |       | Unit    |
|-----------|---------------------------------------|----------------------|----------------------|-------|-----|-------|-------|---------|
|           |                                       | Min                  | Max                  | Min   | Max | Min   | Max   |         |
| $t_{SCY}$ | SCLK cycle (programmable)             | 16x                  | 8192x                | 1     | 512 | 0.8   | 409.6 | $\mu s$ |
| $t_{OSS}$ | Output Data→Rising edge of SCLK       | $t_{SCY} - 2x - 150$ |                      | 725   |     | 550   |       | ns      |
| $t_{OHS}$ | SCLK rising edge→Output Data hold     | $2x - 80$            |                      | 45    |     | 20    |       | ns      |
| $t_{HSR}$ | SCLK rising edge→Input Data hold      | 0                    |                      | 0     |     | 0     |       | ns      |
| $t_{SRD}$ | SCLK rising edge→effective data input |                      | $t_{SCY} - 2x - 150$ |       | 725 |       | 550   | ns      |

#### 4.6 Timer/Counter Input Clock (TI0, TI4, TI5, TI6, TI7)

$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ C$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ C$  (4 ~ 20MHz)

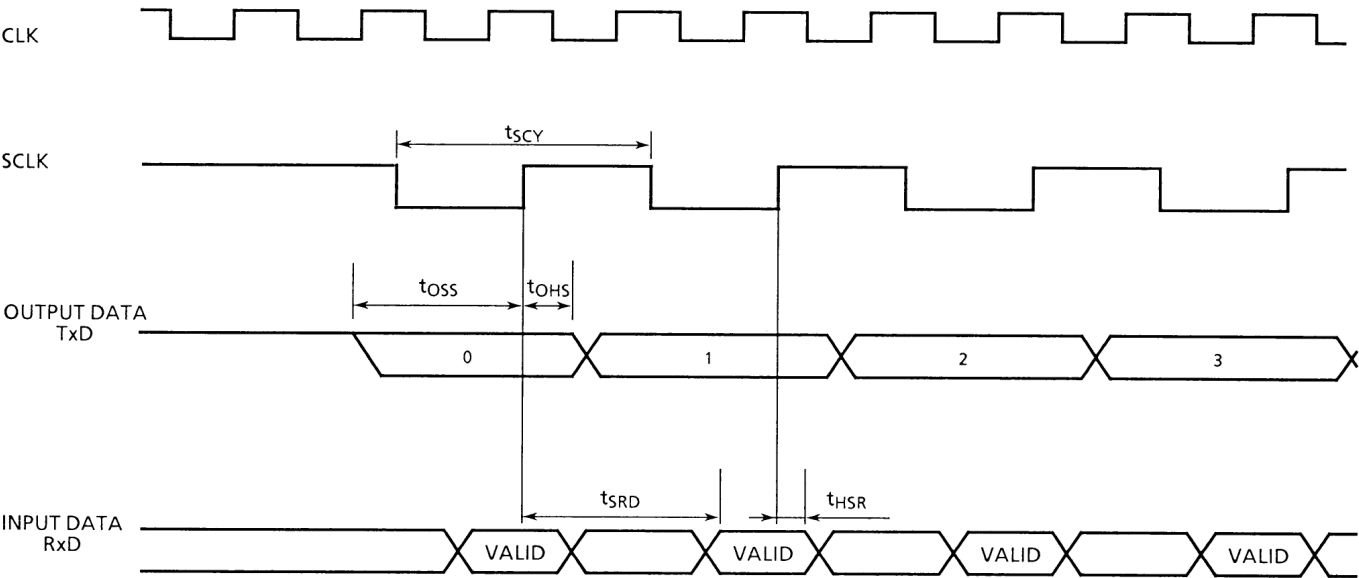
| Symbol     | Parameter                    | Variable   |     | 16MHz |     | 20MHz |     | Unit |
|------------|------------------------------|------------|-----|-------|-----|-------|-----|------|
|            |                              | Min        | Max | Min   | Max | Min   | Max |      |
| $t_{VCK}$  | Clock cycle                  | $8x + 100$ |     | 600   |     | 500   |     | ns   |
| $t_{VCKL}$ | Low level clock pulse width  | $4x + 40$  |     | 290   |     | 240   |     | ns   |
| $t_{VCKH}$ | High level clock pulse width | $4x + 40$  |     | 290   |     | 240   |     | ns   |

## 4.7 Interrupt Operation

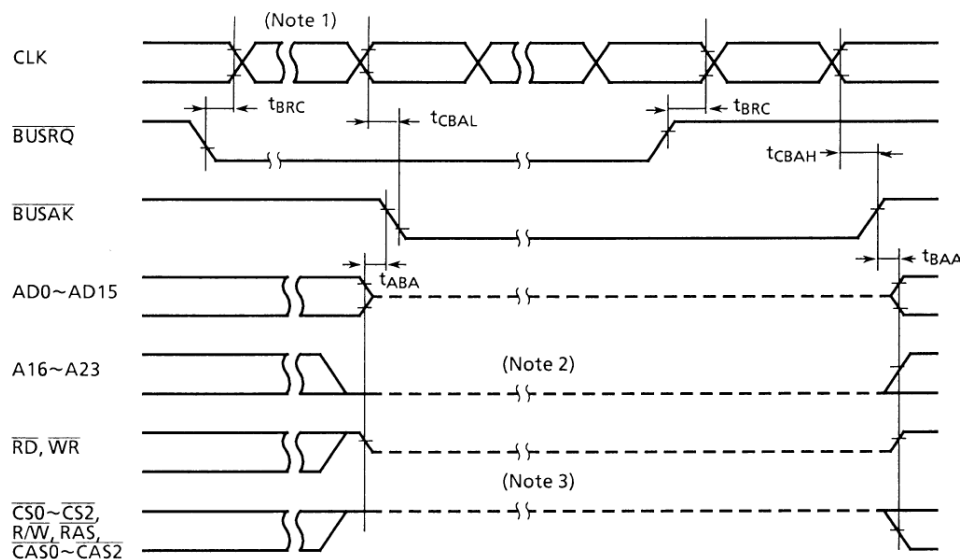
$V_{CC} = 5V \pm 10\%$ ,  $T_A = -40 \sim 85^\circ\text{C}$  (4 ~ 16MHz)  $T_A = -20 \sim 70^\circ\text{C}$  (4 ~ 20MHz)

| Symbol      | Parameter                                      | Variable   |     | 16MHz |     | 20MHz |     | Unit |
|-------------|------------------------------------------------|------------|-----|-------|-----|-------|-----|------|
|             |                                                | Min        | Max | Min   | Max | Min   | Max |      |
| $t_{INTAL}$ | $\overline{NMI}$ , INT0 Low level pulse width  | 4x         |     | 250   |     | 200   |     | ns   |
| $t_{INTAH}$ | $\overline{NMI}$ , INT0 High level pulse width | 4x         |     | 250   |     | 200   |     | ns   |
| $t_{INTBL}$ | INT4 ~ INT7 Low level pulse width              | $8x + 100$ |     | 600   |     | 500   |     | ns   |
| $t_{INTBH}$ | INT4 ~ INT7 High level pulse width             | $8x + 100$ |     | 600   |     | 500   |     | ns   |

4.8 Timing Chart for I/O Interface Mode



#### 4.9 Timing Chart for Bus Request ( $\overline{\text{BUSRQ}}$ )/BUS Acknowledge ( $\overline{\text{BUSAK}}$ )



| Symbol            | Parameter                                         | Variable |              | 16MHz |     | 20MHz |     | Unit |
|-------------------|---------------------------------------------------|----------|--------------|-------|-----|-------|-----|------|
|                   |                                                   | Min      | Max          | Min   | Max | Min   | Max |      |
| $t_{\text{BRC}}$  | $\overline{\text{BUSRQ}}$ setup time for CLK      | 120      |              | 120   |     | 120   |     | ns   |
| $t_{\text{CBAL}}$ | CLK→ $\overline{\text{BUSAK}}$ falling edge       |          | $1.5x + 120$ |       | 245 |       | 220 | ns   |
| $t_{\text{CBAH}}$ | CLK→ $\overline{\text{BUSAK}}$ rising edge        |          | $0.5x + 40$  |       | 71  |       | 65  | ns   |
| $t_{\text{ABA}}$  | Output buffer is off to $\overline{\text{BUSAK}}$ | 0        | 80           | 0     | 80  | 0     | 80  | ns   |
| $t_{\text{BAA}}$  | $\overline{\text{BUSAK}}$ output buffer is on.    | 0        | 80           | 0     | 80  | 0     | 80  | ns   |

Note 1: The Bus will be released after the  $\overline{\text{WAIT}}$  request is inactive, when the  $\overline{\text{BUSRQ}}$  is set to "0" during "Wait" cycle.

Note 2: The internal programmable pull-up/pull-down resistance is added.

The internal programmable pull-up/pull-up resistance is added.

But the CS2/CAS2 pin does not have the internal programmable pull-up resistor. And in the condition of release, this pin is added the internal pull-up resistor.

5. Differences Between TMP96C141AF and  
TMP96C041AF

The devices TMP96C141AF and TMP96C041AF have much the same function, but they are different from following points.

| Parameter                                           | TMP96C141AF                   | TMP96C041AF                   |
|-----------------------------------------------------|-------------------------------|-------------------------------|
| Internal RAM                                        | 1K byte                       | Does not exist                |
| Pin condition at bus release                        | TMP96C141AF<br>see Figure 3.3 | TMP96C041AF<br>see Figure 3.3 |
| Mapping area of CS1 default setting<br>(B1C1/0: 00) | 480H ~ 7FFFH                  | 80H ~ 7FFFH                   |