

TMR7204-C

Split Core Low Temperature Coefficient Current Sensor

Description

TMR7204-C is a TMR array current sensor for accurate measurement of DC, AC, pulsed current and arbitrary waveform current with galvanic isolation between primary and secondary circuits.



Features and Benefits

- Low temperature coefficient
- Galvanic isolation
- High immunity to external interference
- RoHS & REACH compliant

Applications

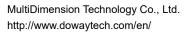
- DC motor drives
- Inverter and variable frequency drives (VFD)
- Uninterruptible power supplies (UPS)
- Power supplies for welding application
- Switching power supplies

Selection Guide

Model	Primary Nominal Current	Primary Current Measuring Range		
TMR7204-2001C	2000 A	±4000 A		

Insulation and Environmental Characteristics

Parameters	Symbol	Typical	Unit	
Dielectric Strength	V _D	5	kV(50Hz, 1min)	
Insulation Resistance	R _{is}	1000	ΜΩ	
Creepage Distance	d _{CP}	31	mm	
Clearance	d _{CL}	14	mm	
Ambient Operating Temperature	T _A	-40 to +70	°C	
Ambient Storage Temperature	T _{STG}	-40 to +70	°C	
Mass	m	200	g	







Catalogue

1. Specifications	03
2. Parameters Definition and Formula	04
3. Dimensions	05
4. Application Information	06



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1. Specifications

T_{A} = +25 °C, V_{CC} = ±15 V, R_{L} = 10 k $\Omega,$ unless otherwise noted

Parameter	Symbol	Conditions		Min.	Тур.	Max.	Unit		
General Electrical Data									
Primary Nominal Current	I _{PN}	TMR7204-2001C		-	2000	-	A		
Primary Current Measuring Range	I _{PM}	TMR7204-2001C		-4000	-	4000	А		
Sensitivity	S	$I_P = 0$ to $\pm I_{PN}$	TMR7204-2001C	-	2.00	-	mV/A		
Output Voltage	V _{OUT}	$I_{\rm P} = 0$ to $\pm I_{\rm PM}$		-	V_{OE} + S × I _P	-	V		
Supply Voltage	V _{cc}	±5 %		-	±15	-	V		
Current Consumption	I _c	I _P = 0		-	+25/-5	-	mA		
Load Resistance	R_{L}	$I_{\rm P} = 0$ to $\pm I_{\rm PN}$		1	10	-	kΩ		
Load Capacitance	CL	$I_{P} = 0$ to $\pm I_{PN}$		-	100	-	pF		
		St	atic Performance Data						
Accuracy	X _G	$T_A = +25 \text{ °C}, I_P = 0 \text{ to } \pm I_{PN}$		-1	±0.5	1			
		$T_A = -40 \text{ °C to } +105 \text{ °C}, I_P = 0 \text{ to } \pm I_{PN}$ -3 ± 1.5 3		3	– % I _{PN}				
Linearity Error	٤	$T_A = -40$ °C to +105 °C, $I_P = 0$ to $\pm I_{PN}$		-	±0.5	-	% I _{PN}		
Symmetry	ε _{sym}	$T_A = -40$ °C to +105 °C, $I_P = 0$ to $\pm I_{PN}$		99	100	100	%		
Sensitivity Error	ε _s	$T_A = -40$ °C to +105 °C, $I_P = 0$ to $\pm I_{PN}$		-2	-	2	%		
Offset Error	V _{OE}	$T_A = +25 \text{ °C}, I_P = 0$ -30 ±10		±10	30				
		T _A = -40 °C	c to +105 °C, I _P = 0	-50	±20	50	— mV		
Hysteresis	V _{OH}	$I_{\rm P}=\pm I_{\rm PN}\to 0$		-10	±5	10	mV		
Dynamic Performance Data									
Response Time	t _R	di/dt > 50 A/µs, 10% to 90% of $I_{\mbox{\tiny PN}}$		-	5	-	μs		
Bandwidth	BW	-3 dB		DC	50	-	kHz		



.



2. Parameters Definition and Formula

1) Output Voltage

$$V_{OUT} = V_{OE} + S \times I_P$$

 V_{OUT} stands for current sensor output voltage at given primary current, V_{OE} stands for offset error, S stands for sensitivity, I_P stands for primary current.

2) Accuracy

$$X_{G} = \max_{I_{P} \in [-I_{PN}, I_{PN}]} \left(\frac{V_{OUT} - (S \times I_{P})}{S \times I_{PN}} \times 100\% \right)$$

 $I_{\text{PN}}\,$ stands for nominal primary current

3) Sensitivity

$$S = \frac{V_{OUT_{(@ I_{PN})}} - V_{OUT_{(@ -I_{PN})}}}{2 \times I_{PN}}$$

 $V_{OUT_{\left(\textcircled{0}^{l}I_{PN} \right)}}$ and $V_{OUT_{\left(\textcircled{0}^{-l}PN \right)}}$ stand for the voltage output at I_{PN} and $-I_{PN}$ respectively.

4) Linearity

$$\epsilon_{L} = \underset{I_{P} \in [-I_{PN}, I_{PN}]}{MAX} \left(\frac{V_{OUT} - \left(\overline{V}_{OE} + \overline{S} \times I_{P}\right)}{S \times I_{PN}} \times 100\% \right)$$

 \overline{S} and \overline{V}_{OE} stand for the average values of the sensitivity and offset error.

5) Symmetry

$$\varepsilon_{\text{SYM}} = \left| \frac{V_{\text{OUT}(@ I_{\text{PN}})} - \overline{V}_{\text{OE}}}{V_{\text{OUT}(@ -I_{\text{PN}})} - \overline{V}_{\text{OE}}} \right| \times 100\%$$

6) Hysteresis

V_{OH} = MAX ΔH

 ΔH is the maximum residual voltage between full scale positive and negative nominal current.





3. Dimensions

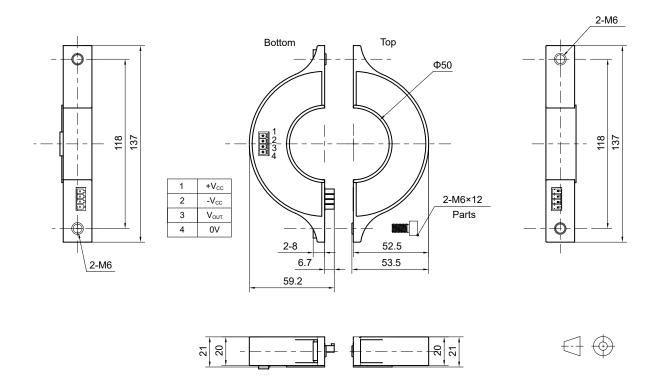


Figure 1. Dimension (unit: mm, tolerances for unmarked scales ±1 mm)

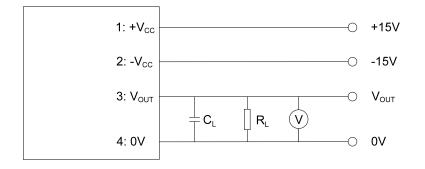


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4. Application Information

Electrical Connection





Mounting Recommendation

- 1. Mounting method:
- 2 × M6 copper or SS304 screws (Recommended torque 2.5 N·m) Φ 50mm 2. Primary through hole dimensions: 3. Secondary electrical connection: PHOENIXCONTACT MCV 1,5/ 4-G-3,81 PHOENIXCONTACT FMC 1,5/ 4-ST-3,81 Mating connection: Wire dimension: $\leq 1.5 \text{ mm}^2$

Remarks

- 1. V_{OUT} is positive when the primary current (I_P) is in the same direction as the arrow indication on the label and vice versa.
- 2. Accuracy of the current sensor may be compromised when improper conductor is used such that primary through hole is partially filled.
- 3. Improper connection may result in permanent damage of the sensor.
- 4. Excessive capacitive load may result in distortion of output signals when measuring high frequency primary signal.
- 5. Dynamic performances (di/dt and response time) are best with a single busbar completely filling the primary through hole.
- 6. Sensor is customizable upon request.



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