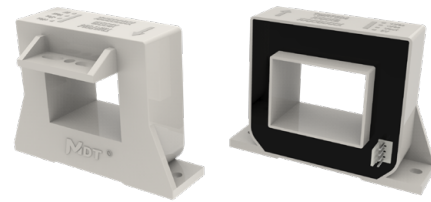


# TMR7504-B

## Unibody Low Temperature-Drift Current Sensor

### Description

TMR7504-B is an open loop current sensor for accurate measurement of DC, AC, pulsed current and arbitrary waveform current with galvanic isolation between primary and secondary circuits.



### Features and Benefits

- Low temperature drift
- Galvanic isolation
- High immunity to external interference

### Applications

- DC motor drives
- Inverter and variable frequency drives (VFD)
- Uninterruptible power supplies (UPS)
- Power supplies for welding application
- Switching power supplies

### Selection Guide

Model	Primary Nominal Current	Primary Current Measuring Range
TMR7504-2000B	200 A	±600 A
TMR7504-4000B	400 A	±1200 A
TMR7504-5000B	500 A	±1500 A
TMR7504-6000B	600 A	±1800 A
TMR7504-8000B	800 A	±2400 A
TMR7504-1001B	1000 A	±2500 A
TMR7504-1201B	1200 A	±2500 A
TMR7504-1501B	1500 A	±2500 A

### Insulation and Environmental Characteristics

Parameters	Symbol	Typical	Unit
Dielectric Strength	$V_D$	5	kV(50Hz, 1min)
Insulation Resistance	$R_{IS}$	1000	MΩ
Creepage Distance	$d_{CP}$	15	mm
Clearance	$d_{CL}$	7	mm
Ambient Operating Temperature	$T_A$	-40 to +105	°C
Ambient Storage Temperature	$T_{STG}$	-40 to +105	°C
Mass	$m$	320	g

## Catalogue

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## 1. Specifications

$T_A = +25\text{ }^\circ\text{C}$ ,  $V_{CC} = \pm 15\text{ V}$ ,  $R_L = 10\text{ k}\Omega$ , unless otherwise noted

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Unit	
General Electrical Data							
Primary Nominal Current	$I_{PN}$	TMR7504-2000B	-	200	-	A	
		TMR7504-4000B	-	400	-		
		TMR7504-5000B	-	500	-		
		TMR7504-6000B	-	600	-		
		TMR7504-8000B	-	800	-		
		TMR7504-1001B	-	1000	-		
		TMR7504-1201B	-	1200	-		
Primary Current Measuring Range	$I_{PM}$	TMR7504-2000B	-600	-	600	A	
		TMR7504-4000B	-1200	-	1200		
		TMR7504-5000B	-1500	-	1500		
		TMR7504-6000B	-1800	-	1800		
		TMR7504-8000B	-2400	-	2400		
		TMR7504-1001B	-2500	-	2500		
		TMR7504-1201B	-2500	-	2500		
Sensitivity	S	$I_P = 0\text{ to } \pm I_{PN}$	TMR7504-2000B	-	20.00	-	mV/A
			TMR7504-4000B	-	10.00	-	
			TMR7504-5000B	-	8.00	-	
			TMR7504-6000B	-	6.67	-	
			TMR7504-8000B	-	5.00	-	
			TMR7504-1001B	-	4.00	-	
			TMR7504-1201B	-	3.33	-	
Output Voltage	$V_{OUT}$	$I_P = 0\text{ to } \pm I_{PM}$	-	$V_{OE} + S \times I_P$	-	V	
Supply Voltage	$V_{CC}$	$\pm 5\%$	-	$\pm 15$	-	V	
Current Consumption	$I_C$	$I_P = 0$	-	+25/-5	-	mA	
Load Resistance	$R_L$	$I_P = 0\text{ to } \pm I_{PN}$	1	10	-	k $\Omega$	
Load Capacitance	$C_L$	$I_P = 0\text{ to } \pm I_{PN}$	-	100	-	pF	
Static Performance Data							
Accuracy	$X_G$	$T_A = +25\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-1	$\pm 0.5$	1	% $I_{PN}$	
		$T_A = -40\text{ }^\circ\text{C to } +40\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-2	$\pm 0.5$	2		
		$T_A = +40\text{ }^\circ\text{C to } +85\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-3	-	1		
		$T_A = +85\text{ }^\circ\text{C to } +105\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-4.5	-	1		
Linearity Error	$\epsilon_L$	$T_A = -40\text{ }^\circ\text{C to } +105\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-	$\pm 0.2$	-	% $I_{PN}$	
Symmetry	$\epsilon_{SYM}$	$T_A = -40\text{ }^\circ\text{C to } +105\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	99	100	100	%	
Sensitivity Error	$\epsilon_S$	$T_A = -40\text{ }^\circ\text{C to } +105\text{ }^\circ\text{C}$ , $I_P = 0\text{ to } \pm I_{PN}$	-4	-	1.5	%	
Electric Offset	$V_{OE}$	$T_A = +25\text{ }^\circ\text{C}$ , $I_P = 0$	-20	$\pm 10$	20	mV	
		$T_A = -40\text{ }^\circ\text{C to } +85\text{ }^\circ\text{C}$ , $I_P = 0$	-35	$\pm 20$	35		
		$T_A = +85\text{ }^\circ\text{C to } +105\text{ }^\circ\text{C}$ , $I_P = 0$	-40	$\pm 20$	40		
Hysteresis	$V_{OH}$	$I_P = \pm I_{PN} \rightarrow 0$	-10	$\pm 5$	10	mV	
Dynamic Performance Data							
Response Time	$t_R$	$di/dt > 50\text{ A}/\mu\text{s}$ , 10% to 90% of $I_{PN}$	-	5	-	$\mu\text{s}$	
Bandwidth	BW	-3 dB	DC	25	-	kHz	

## 2. Typical Output Characteristics

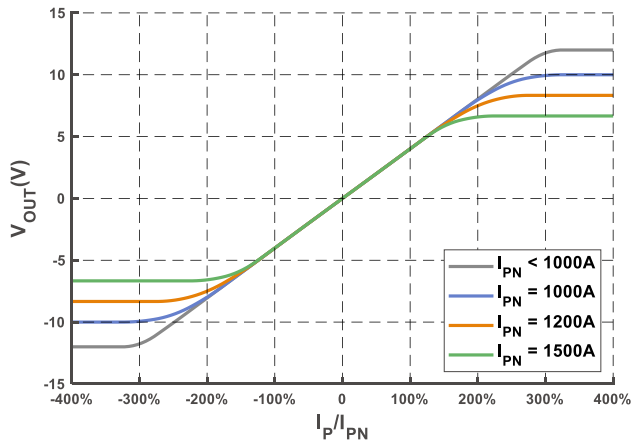


Figure 1. Output Voltage vs Primary Current

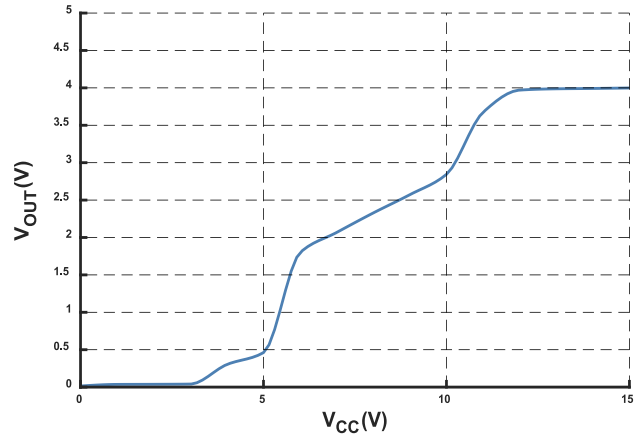


Figure 2. Output Voltage vs Supply Voltage (@ $I_P = I_{PN}$ )

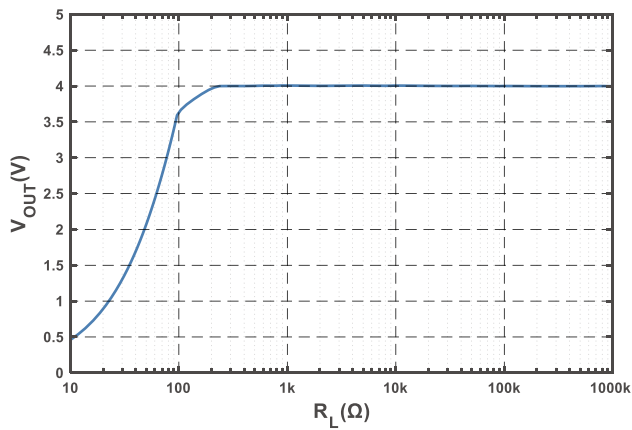


Figure 3. Output Voltage vs Load Resistance  
(@ $I_P = I_{PN}$ )

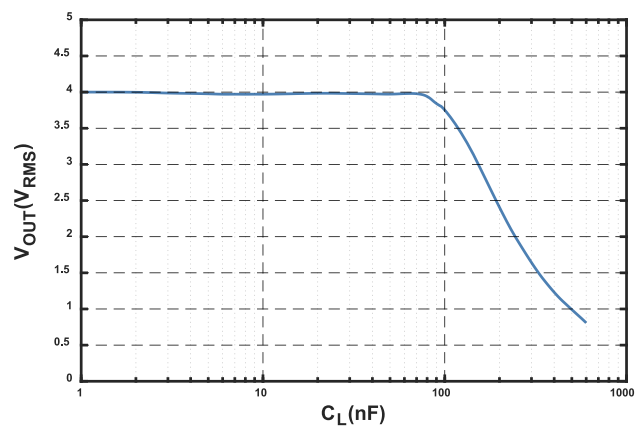


Figure 4. Output Voltage vs Load Capacitance  
(@ $I_P = I_{PN}$ )

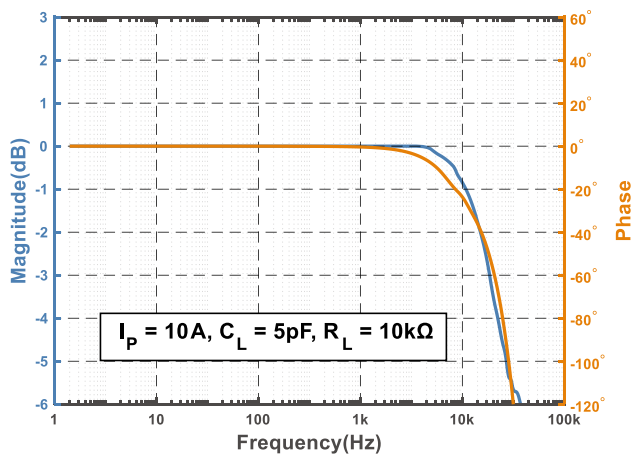


Figure 5. Bode Plot

### 3. Typical Temperature Characteristics

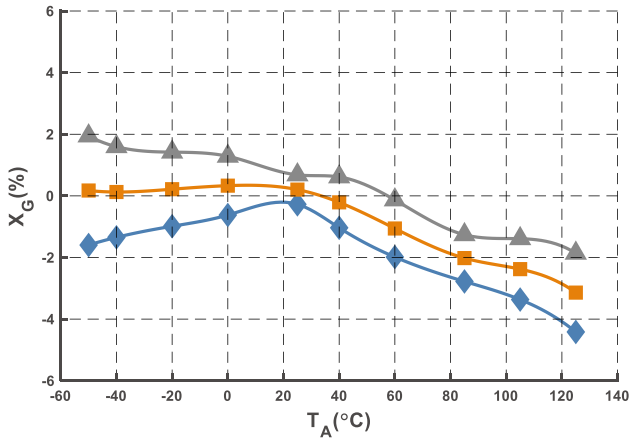


Figure 6. Accuracy

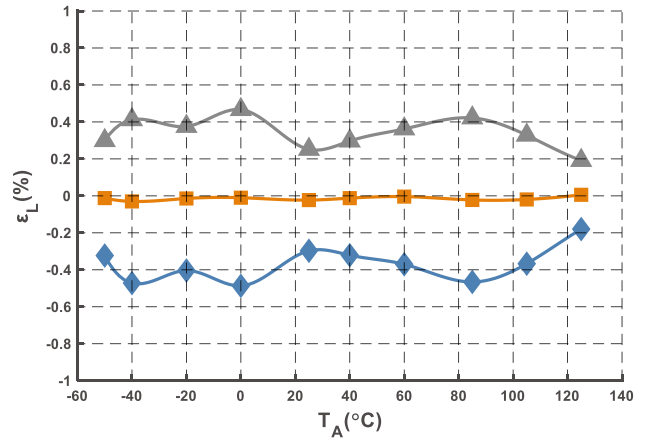


Figure 7. Linearity Error

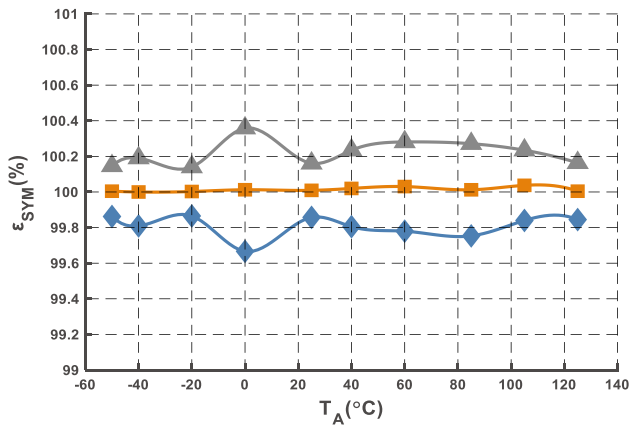


Figure 8. Symmetry

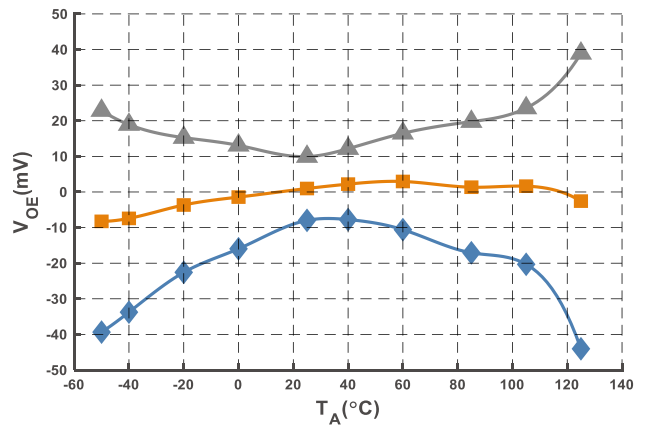


Figure 9. Electric Offset

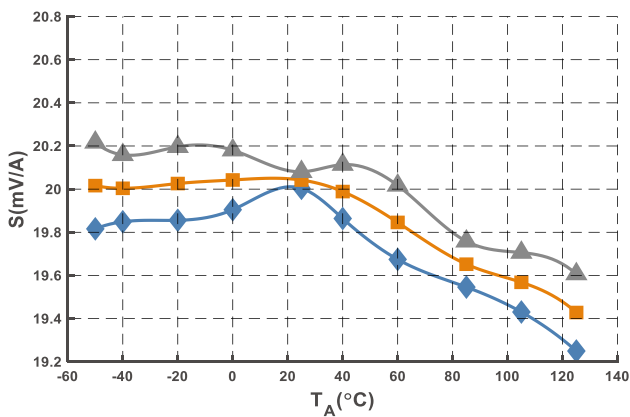


Figure 10. Sensitivity (@ $I_{PN} = 200$  A)

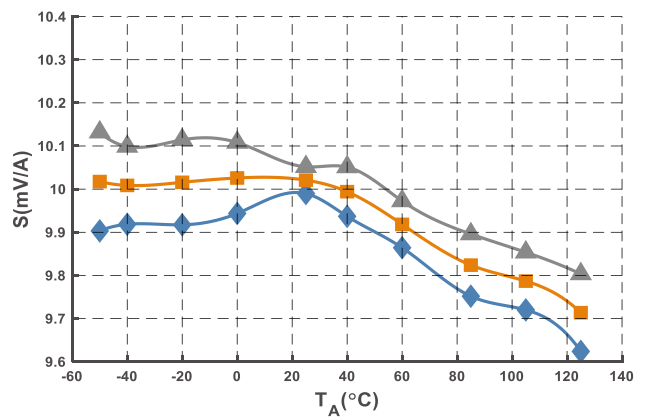


Figure 11. Sensitivity (@ $I_{PN} = 400$  A)

Typical Temperature Characteristics

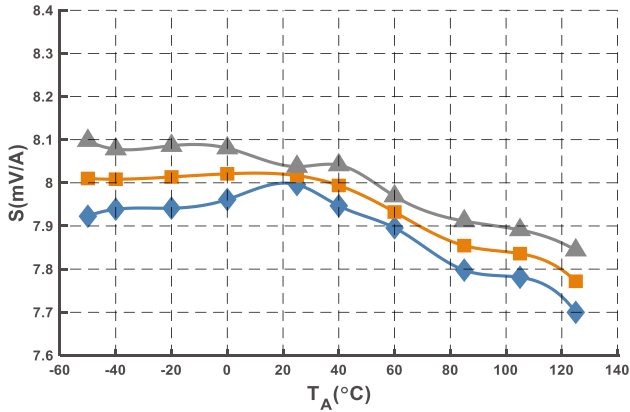


Figure 12. Sensitivity (@I<sub>PN</sub> = 500 A)

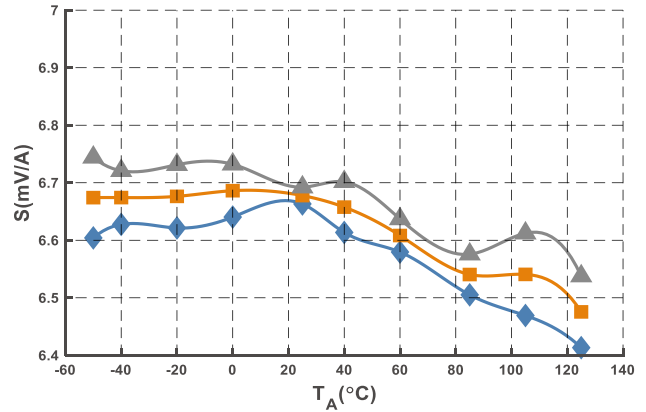


Figure 13. Sensitivity (@I<sub>PN</sub> = 600 A)

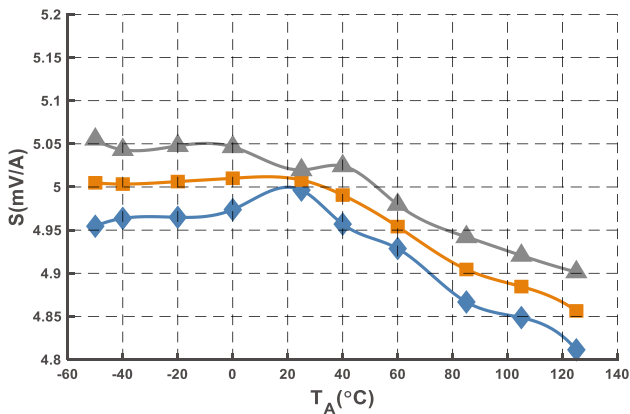


Figure 14. Sensitivity (@I<sub>PN</sub> = 800 A)

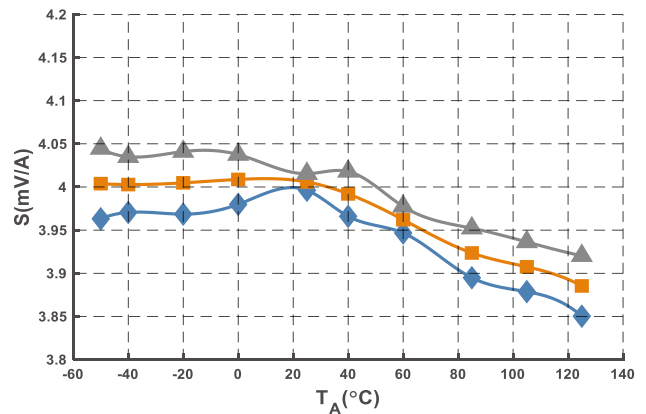


Figure 15. Sensitivity (@I<sub>PN</sub> = 1000 A)

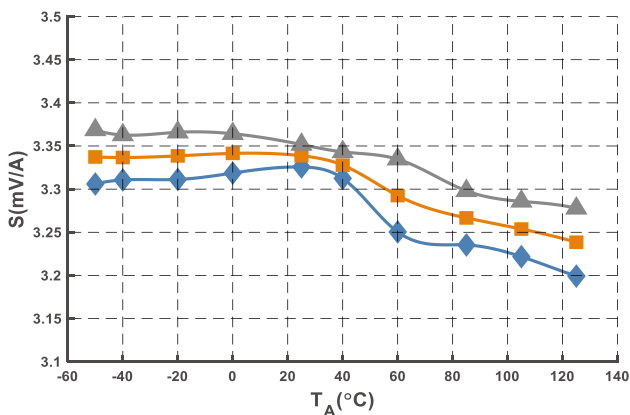


Figure 16. Sensitivity (@I<sub>PN</sub> = 1200 A)

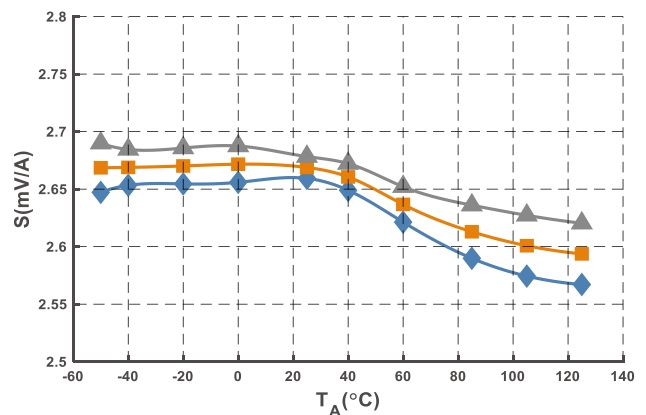


Figure 17. Sensitivity (@I<sub>PN</sub> = 1500 A)

Typical Temperature Characteristics

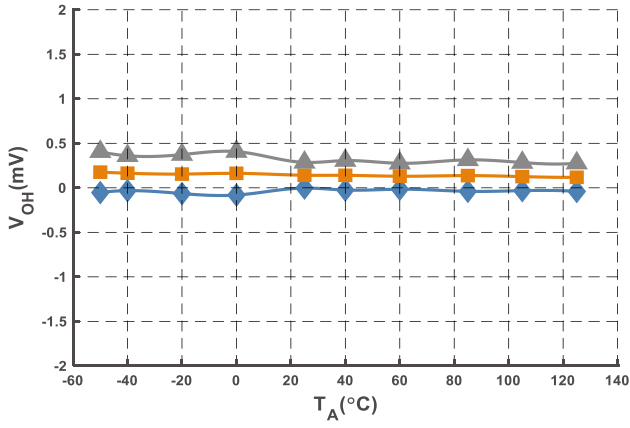


Figure 18. Hysteresis

## 4. Parameters Definition And Formula

### 1) Output Voltage

$$V_{OUT} = V_{OE} + S \times I_P$$

$V_{OUT}$  stands for current sensor output voltage at given primary current,  $V_{OE}$  stands for electric offset,  $S$  stands for sensitivity,  $I_P$  stands for primary current.

### 2) Accuracy

$$X_G = \text{MAX}_{I_P \in [-I_{PN}, I_{PN}]} \left( \frac{V_{OUT} - (S \times I_P)}{S \times I_{PN}} \times 100\% \right)$$

$I_{PN}$  stands for nominal primary current

### 3) Sensitivity

$$S = \frac{V_{OUT(@ I_{PN})} - V_{OUT(@ -I_{PN})}}{2 \times I_{PN}}$$

$V_{OUT(@ I_{PN})}$  and  $V_{OUT(@ -I_{PN})}$  stand for the voltage output at  $I_{PN}$  and  $-I_{PN}$  respectively.

### 4) Linearity

$$\epsilon_L = \text{MAX}_{I_P \in [-I_{PN}, I_{PN}]} \left( \frac{V_{OUT} - (\bar{V}_{OE} + \bar{S} \times I_P)}{S \times I_{PN}} \times 100\% \right)$$

$\bar{S}$  and  $\bar{V}_{OE}$  stand for the average values of the sensitivity and electric offset.

### 5) Symmetry

$$\epsilon_{SYM} = \left| \frac{V_{OUT(@ I_{PN})} - \bar{V}_{OE}}{V_{OUT(@ -I_{PN})} - \bar{V}_{OE}} \right| \times 100\%$$

### 6) Hysteresis

$$V_{OH} = \text{MAX } \Delta H$$

$\Delta H$  is the maximum residual voltage between full scale positive and negative nominal current.



## 5. Application Information

### Electrical Connection

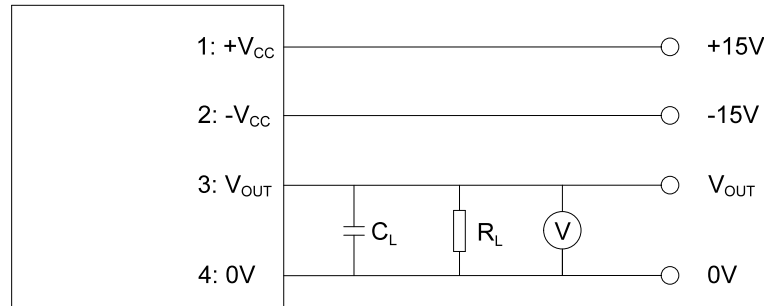


Figure 20. Electrical Connection

### Mounting Recommendation

1. Mounting method:
  - 1 × Φ 4.5 mm hole and 1 × Φ 4.5 mm slotted hole
  - 2 × M4 copper or SS304 screws (Recommended torque 1.2 N·m)
  - Or
  - 1 × Φ 4.5 mm hole and 2 × Φ 4.5 mm slotted holes (Fixed to the busbar)
  - 3 × M4 copper or SS304 screws (Recommended torque 1.2 N·m)
2. Primary through hole dimensions: 40 mm × 30 mm
3. Secondary electrical connection:
  - Molex 22041041 (old PN: Molex 5045-04A)
  - Crimp Housing: Molex 22011042
  - Crimping Terminal: Molex 08500113

### Remarks

1. V<sub>OUT</sub> is positive when the primary current (I<sub>p</sub>) is in the same direction as the arrow indication on the label and vice versa.
2. Improper connection may result in permanent damage of the sensor.
3. Excessive capacitive load may result in distortion of output signals when measuring high frequency primary signal. Please refer to Output Voltage vs Load Capacitance Curve.
4. Dynamic performances (di/dt and response time) are best with a single busbar completely filling the primary through hole.
5. Sensor is customizable upon request.

6. Dimensions

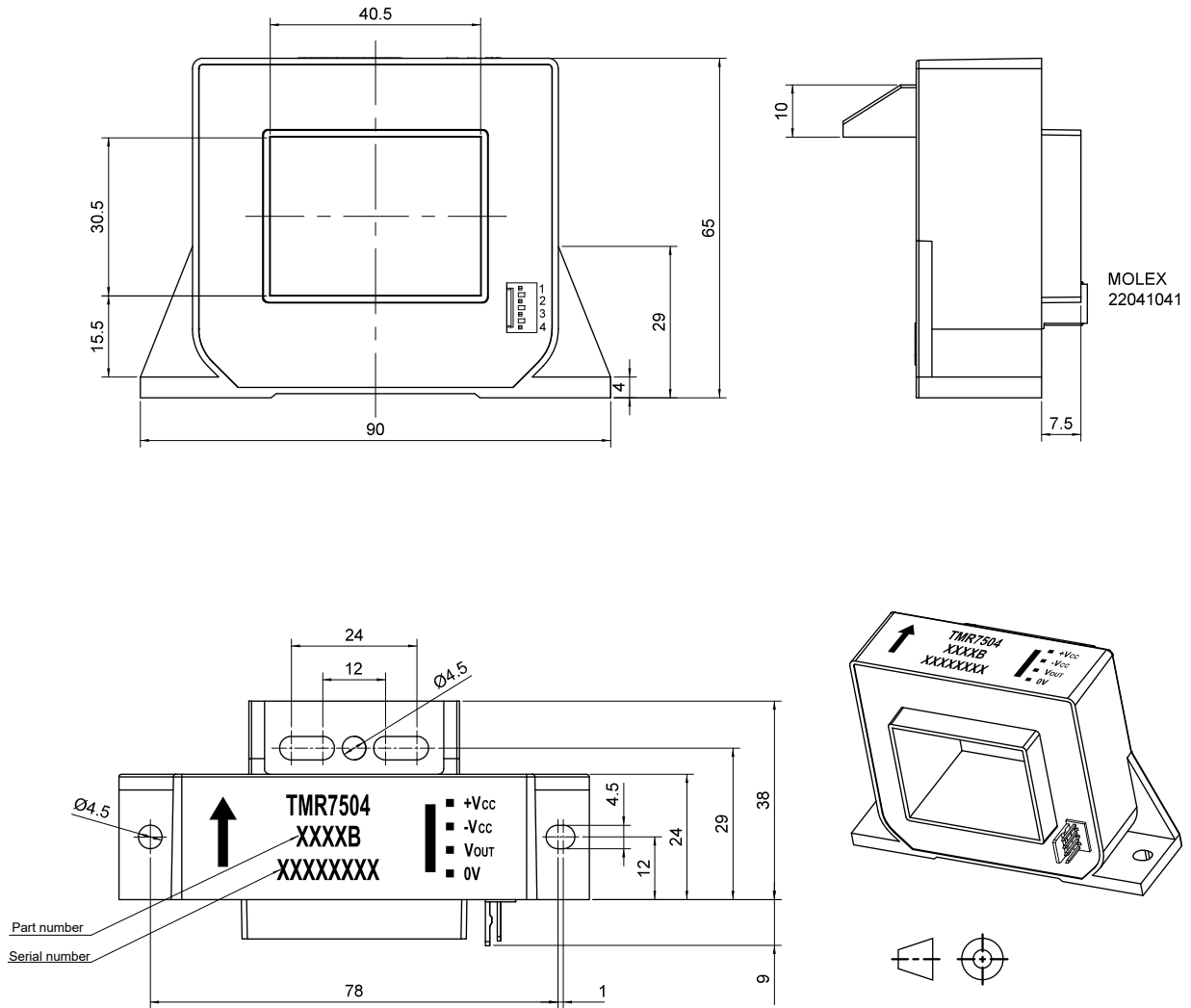


Figure 19. Dimension (unit: mm, tolerances for unmarked scales  $\pm 1$  mm)

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