

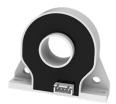
TMR7553-B

Unibody Precision Current Sensor

Description

TMR7553-B is a close loop current sensor for accurate measurement of DC, AC, pulsed current and arbitrary waveform current with galvanic isolation between primary and secondary circuits.





Features and Benefits

- High accuracy
- Excellent linearity
- · Ultra low temperature drift
- · Fast response time
- Galvanic isolation
- · High immunity to external interference

Applications

- DC motor drives
- Inverter and variable frequency drives (VFD)
- Uninterruptible power supplies (UPS)
- · Power supplies for welding application
- · Switching power supplies

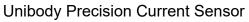
Selection Guide

Part Number	Primary Nominal Current	Primary Current Measuring Range	
TMR7553-1000B	100 A	±200 A	
TMR7553-2000B	200 A	±400 A	
TMR7553-3000B	300 A	±600 A	

Insulation and Environmental Characteristics

Parameters	Symbol	Тур.	Unit	
Dielectric Strength	V _D	5	kV(50 Hz, 1 min)	
Insulation Resistance	R _{IS}	1000	ΜΩ	
Creepage Distance	d _{CP}	19	mm	
Clearance	d _{CL}	12	mm	
Ambient Operating Temperature	T _A	-40 to +85	°C	
Ambient Storage Temperature	T_{STG}	-40 to +85	°C	
Mass	m	75	g	







Catalogue

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1. Specifications

 $\rm T_A$ = +25 °C, $\rm V_{CC}$ = ±15 V, $\rm R_M$ = 5 $\Omega,$ unless otherwise noted

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
		General Electrical Data				
Primary Nominal Current	I _{PN}	TMR7553-1000B	-	100	-	A
		TMR7553-2000B	-	200	-	
		TMR7553-3000B	-	300	-	
Primary Current Measuring Range	I _{PM}	TMR7553-1000B	-200	-	200	A
		TMR7553-2000B	-400	-	400	
		TMR7553-3000B	-600	-	600	
Sensitivity	S	$I_P = 0 \text{ to } \pm I_{PN}$	-	500	-	μA/A
Number of Secondary Turns	Ns	-	-	2000	-	-
Output Current	I _{out}	$I_P = 0 \text{ to } \pm I_{PM}$	-	I _{OE} + S × I _P	-	V
Supply Voltage	V _{CC}	±5 %	±12	±15	±20	V
Current Consumption	I _C	I _P = 0	-	±12	-	mA
Secondary Coil Resistance	R _s	T _A = +25 °C	-	-	23	Ω
Measuring Resistance	R _M	For maximum measuring resistance value, please refer to Figure 2, 3 and 4	0	-	-	Ω
	1	Static Performance Data		'		1
Accuracy	X _G	$T_A = +25 ^{\circ}\text{C}, I_P = 0 \text{ to } \pm I_{PN}$	-0.6	±0.3	0.6	% I _{PN}
		$T_A = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}, I_P = 0 \text{ to } \pm I_{PN}$	-1	±0.5	1	
Linearity Error	٤	$T_A = -40 ^{\circ}\text{C}$ to +85 $^{\circ}\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-	±0.1	-	% I _{PN}
Symmetry	ε _{SYM}	$T_A = -40 ^{\circ}\text{C} \text{ to } +85 ^{\circ}\text{C}, I_P = 0 \text{ to } \pm I_{PN}$	99.5	100	100.5	%
Sensitivity Error	ε _S	$T_A = -40 ^{\circ}\text{C}$ to +85 $^{\circ}\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-0.8	-	0.8	%
Electric Offset	I _{OE}	T _A = +25 °C, I _P = 0	-200	±100	200	μA
Hysteresis	I _{OH}	$I_P = \pm I_{PN} \rightarrow 0$	-200	-	200	μA
		Dynamic Performance Data				
Response Time	t _R	di/dt > 50 A/µs, 10% to 90% of I _{PN}	-	1	-	μs
Bandwidth	BW	-3 dB	DC	100	-	kHz



2. Typical Output Characteristics

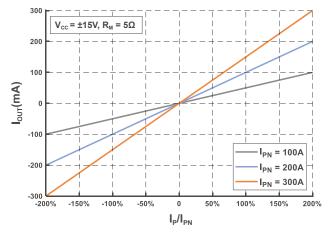


Figure 1. Output Voltage vs Primary Current

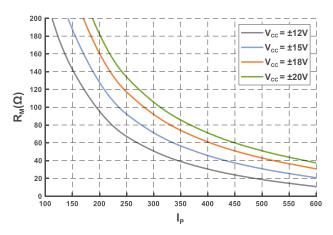


Figure 3. Measuring Resistance (@T_A = 70 °C)

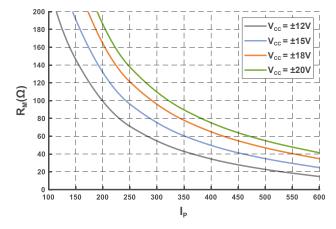


Figure 5. Measuring Resistance (@T_A = 25 °C)

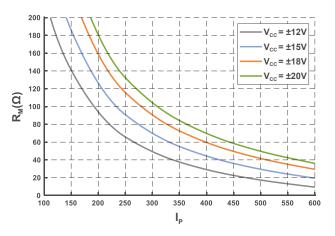


Figure 2. Measuring Resistance (@T_A = 85 °C)

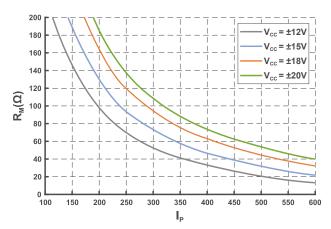
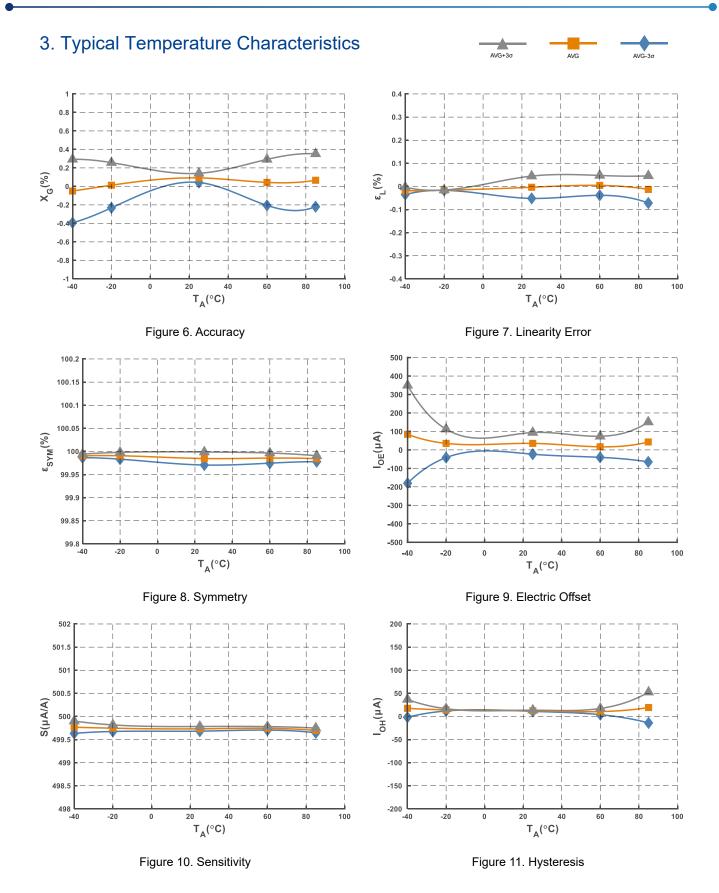


Figure 4. Measuring Resistance (@ T_A = 50 °C)







4. Parameters Definition And Formula

1) Output Current

$$I_{OUT} = I_{OE} + S \times I_{P}$$

 I_{OUT} stands for current sensor output current at given primary current, I_{OE} stands for electric offset, S stands for sensitivity, I_P stands for primary current.

2) Accuracy

$$X_{G} = \underset{I_{P} \in [-I_{PN}, I_{PN}]}{\text{MAX}} \left(\frac{I_{OUT} - (S \times I_{P})}{S \times I_{PN}} \times 100\% \right)$$

I_{PN} stands for nominal primary current

3) Sensitivity

$$S = \frac{I_{OUT(@ I_{PN})} - I_{OUT(@ -I_{PN})}}{2 \times I_{PN}}$$

 $I_{OUT_{(@\ I_{PN})}}$ and $I_{OUT_{(@\ I_{PN})}}$ stand for the current output at I_{PN} and $-I_{PN}$ respectively.

4) Linearity

$$\epsilon_{L} = \underset{I_{P} \in \left[-I_{PN}, \ I_{PN} \right]}{MAX} \left(\frac{I_{OUT} - \left(\overline{I}_{OE} + \overline{S} \times I_{P} \right)}{S \times I_{PN}} \times 100\% \right)$$

 \bar{S} and \bar{I}_{OE} stand for the average values of the sensitivity and electric offset.

5) Symmetry

$$\epsilon_{\text{SYM}} = \left| \frac{I_{\text{OUT}(@ I_{PN})} - \bar{I}_{\text{OE}}}{I_{\text{OUT}(@ -I_{PN})} - \bar{I}_{\text{OE}}} \right| \times 100\%$$

6) Hysteresis

$$I_{OH}$$
 = MAX ΔH

ΔH is the maximum residual output current between full scale positive and negative nominal current.

7) Measuring Resistance

$$R_{M MAX} = N_S \times \frac{V_{CC} - 0.7V}{I_P} - R_S \times \frac{234.5 + T_A}{234.5 + 25}$$

 $R_{M\ MAX}$ is the maximum measuring resistance, N_S is the number of turns of the secondary coil winding and T_A stands for ambient operating temperature



5. Application Information

Electrical Connection

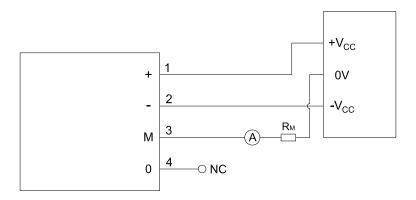


Figure 12. Electrical Connection

Mounting Recommendation

1. Mounting method: $1 \times \Phi$ 4.2 mm hole and $1 \times \Phi$ 4.2 mm slotted hole

2 × M4 copper or SS304 screws (Recommended torque 1.2 N·m)

Or

 $2 \times \Phi$ 5.4 mm hole

2 × M5 copper or SS304 screws (Recommended torque 1.2 N·m)

2. Primary through hole dimensions: Φ 20 mm

3. Secondary electrical connection: JST B4B-XH-A

Crimp Housing: JST XHP-4

Crimping Terminal: JST SXH-001T-P0.6

Remarks

- 1. I_{OUT} is positive when the primary current (I_P) is in the same direction as the arrow indication on the label and vice versa.
- 2. Improper connection may result in permanent damage of the sensor.
- 3. Excessive capacitive load may result in distortion of output signals when measuring high frequency primary signal. Please refer to Output Voltage vs Load Capacitance Curve.
- 4. Dynamic performances (di/dt and response time) are best with a single busbar completely filling the primary through hole.
- 5. Sensor is customizable upon request.



6. Dimensions

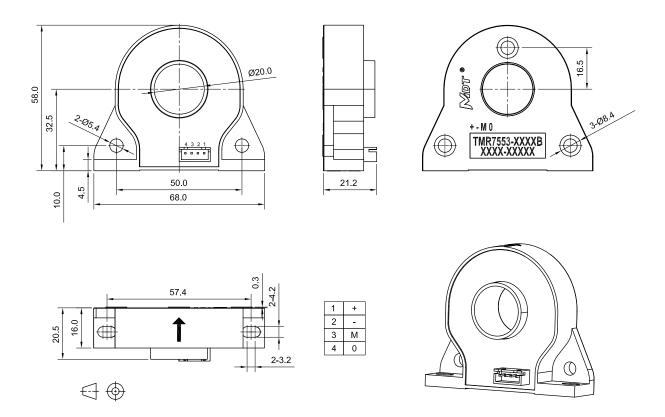


Figure 13. Dimension (unit: mm, tolerances for unmarked scales ±1 mm)

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