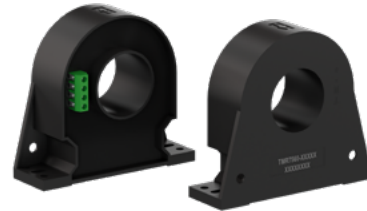


TMR7560-P

Unibody Precision Current Sensor

Description

TMR7560-P is a close loop current sensor for accurate measurement of DC, AC, pulsed current and arbitrary waveform current with galvanic isolation between primary and secondary circuits.



Features and Benefits

- High accuracy
- Excellent linearity
- Ultra low temperature drift
- Fast response time
- Galvanic isolation
- High immunity to external interference
- Anti-CAF
- RoHS and REACH compliant

Applications

- DC motor drives
- Inverter and variable frequency drives (VFD)
- Uninterruptible power supplies (UPS)
- Power supplies for welding application
- Switching power supplies

Selection Guide

Part Number	Primary Nominal Current	Primary Current Measuring Range
TMR7560-3000P	300 A	±500 A
TMR7560-6000P	600 A	±700 A

Insulation and Environmental Characteristics

Parameters	Symbol	Typ.	Unit
Dielectric Strength	V_D	5	kV(50 Hz, 1 min)
Insulation Resistance	R_{IS}	1000	$M\Omega$
Creepage Distance	d_{CP}	21	mm
Clearance	d_{CL}	8	mm
Ambient Operating Temperature	T_A	-40 to +85	$^{\circ}C$
Ambient Storage Temperature	T_{STG}	-40 to +85	$^{\circ}C$
Mass	m	300	g

Catalogue

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1. Specifications

$T_A = +25\text{ }^\circ\text{C}$, $V_{CC} = \pm 15\text{ V}$, $R_M = 5\text{ }\Omega$, unless otherwise noted

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
General Electrical Data						
Primary Nominal Current	I_{PN}	TMR7560-3000P	-	300	-	A
		TMR7560-6000P	-	600	-	
Primary Current Measuring Range	I_{PM}	TMR7560-3000P	-500	-	500	A
		TMR7560-6000P	-700	-	700	
Sensitivity	S	$I_P = 0$ to $\pm I_{PN}$	-	0.333	-	mA/A
Number of Secondary Turns	N_S	-	-	3000	-	-
Output Current	I_{OUT}	$I_P = 0$ to $\pm I_{PM}$	-	$I_{OE} + S \times I_P$	-	V
Supply Voltage	V_{CC}	$\pm 5\%$	± 15	± 18	± 20	V
Current Consumption	I_C	$I_P = 0$	-	± 20	-	mA
Secondary Coil Resistance	R_S	$T_A = +25\text{ }^\circ\text{C}$	-	-	38	Ω
Measuring Resistance	R_M	For maximum measuring resistance value, please refer to Figure 2, 3, 4, 5	0	-	-	Ω
Static Performance Data						
Accuracy	X_G	$T_A = +25\text{ }^\circ\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-0.2	± 0.08	0.2	% I_{PN}
		$T_A = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-0.6	± 0.2	0.6	
Linearity Error	ϵ_L	$T_A = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-	± 0.05	-	% I_{PN}
Symmetry	ϵ_{SYM}	$T_A = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$, $I_P = 0$ to $\pm I_{PN}$	99.2	100	100.2	%
Sensitivity Error	ϵ_S	$T_A = -40\text{ }^\circ\text{C}$ to $+85\text{ }^\circ\text{C}$, $I_P = 0$ to $\pm I_{PN}$	-0.5	-	0.5	%
Offset Error	I_{OE}	$T_A = +25\text{ }^\circ\text{C}$, $I_P = 0$	-0.1	± 0.05	0.1	mA
Hysteresis	I_{OH}	$I_P = \pm I_{PN} \rightarrow 0$	-0.1	-	0.1	mA
Dynamic Performance Data						
Response Time	t_R	$di/dt > 50\text{ A}/\mu\text{s}$, 10% to 90% of I_{PN}	-	1	-	μs
Bandwidth	BW	-3 dB	DC	100	-	kHz

2. Typical Output Characteristics

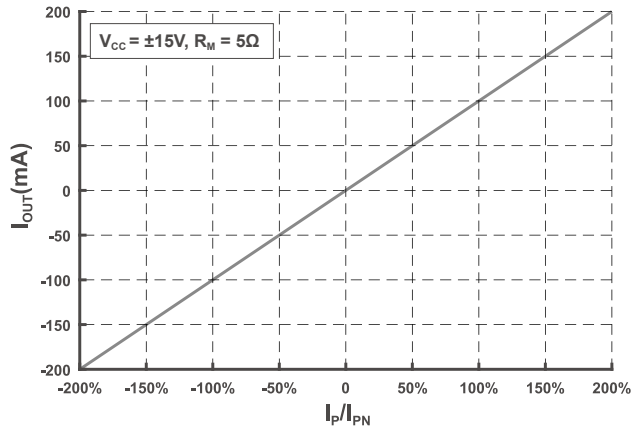


Figure 1. Output Voltage vs Primary Current

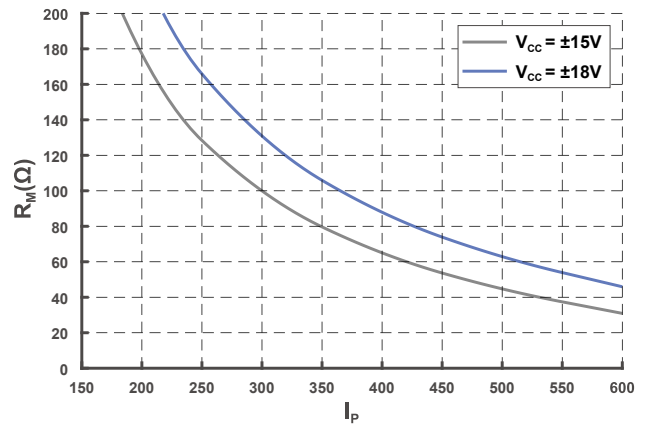


Figure 2. Measuring Resistance (@ $T_A = 85\text{ °C}$)

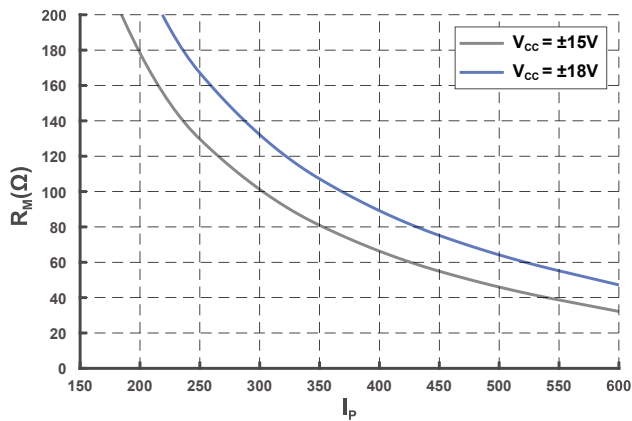


Figure 3. Measuring Resistance (@ $T_A = 70\text{ °C}$)

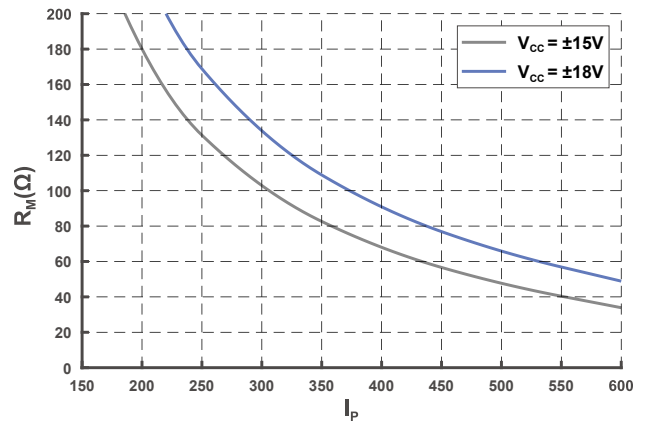


Figure 4. Measuring Resistance (@ $T_A = 50\text{ °C}$)

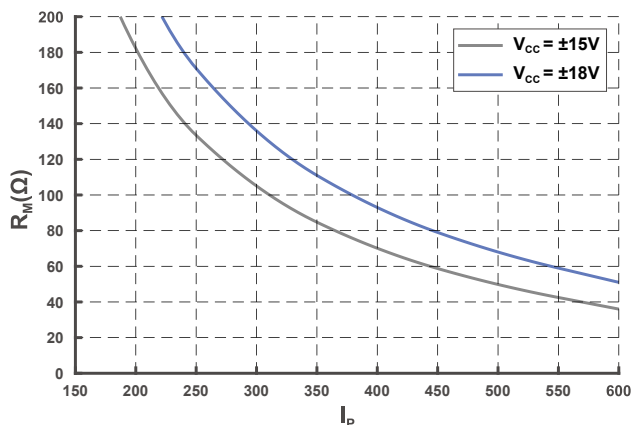


Figure 5. Measuring Resistance (@ $T_A = 25\text{ °C}$)

3. Parameters Definition and Formula

1) Output Current

$$I_{OUT} = I_{OE} + S \times I_P$$

I_{OUT} stands for current sensor output current at given primary current, I_{OE} stands for offset error, S stands for sensitivity, I_P stands for primary current.

2) Accuracy

$$X_G = \text{MAX}_{I_P \in [-I_{PN}, I_{PN}]} \left(\frac{I_{OUT} - (S \times I_P)}{S \times I_{PN}} \times 100\% \right)$$

I_{PN} stands for nominal primary current.

3) Sensitivity

$$S = \frac{I_{OUT(@ I_{PN})} - I_{OUT(@ -I_{PN})}}{2 \times I_{PN}}$$

$I_{OUT(@ I_{PN})}$ and $I_{OUT(@ -I_{PN})}$ stand for the current output at I_{PN} and $-I_{PN}$ respectively.

4) Linearity

$$\varepsilon_L = \text{MAX}_{I_P \in [-I_{PN}, I_{PN}]} \left(\frac{I_{OUT} - (\bar{I}_{OE} + \bar{S} \times I_P)}{S \times I_{PN}} \times 100\% \right)$$

\bar{S} and \bar{I}_{OE} stand for the average values of the sensitivity and offset error.

5) Symmetry

$$\varepsilon_{SYM} = \frac{|I_{OUT(@ I_{PN})} - \bar{I}_{OE}|}{|I_{OUT(@ -I_{PN})} - \bar{I}_{OE}|} \times 100\%$$

6) Hysteresis

$$I_{OH} = \text{MAX } \Delta H$$

ΔH is the maximum residual output current between full scale positive and negative nominal current.

7) Measuring Resistance

$$R_{M \text{ MAX}} = N_S \times \frac{V_{CC} - 3.7V}{I_P} - 4 - R_S \times \frac{234.5 + T_A}{234.5 + 25}$$

$R_{M \text{ MAX}}$ is the maximum measuring resistance, N_S is the number of turns of the secondary coil winding and T_A stands for ambient operating temperature.

4. Application Information

Electrical Connection

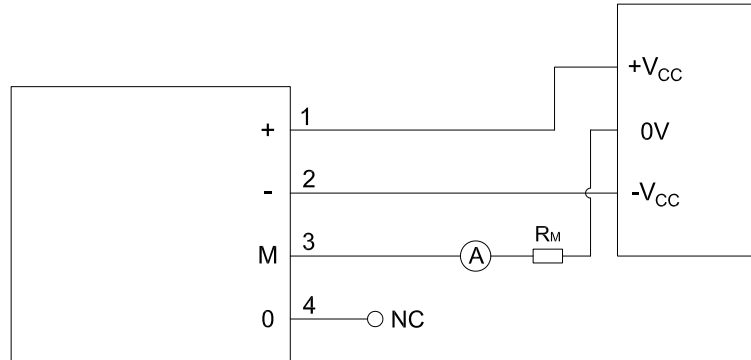


Figure 6. Electrical Connection

Mounting Recommendation

1. Mounting method:
 - 2 × Φ 5.3 mm holes
 - 2 × M5 copper or SS304 screws (Recommended torque 1.2 N·m)
 - Or
 - 2 × Φ 4.5 mm slotted holes
 - 2 × M4 copper or SS304 screws (Recommended torque 1.2 N·m)
 - Or
 - 4 × Φ 4.5 mm holes
 - 4 × M4 copper or SS304 screws (Recommended torque 1.2 N·m)
2. Primary through hole dimensions: Φ 35 mm
3. Secondary electrical connection: JTB450-00 screw PCB terminal
Max conductor dimension 1.5 mm²

Remarks

1. I_{OUT} is positive when the primary current (I_P) is in the same direction as the arrow indication on the label and vice versa.
2. Improper connection may result in permanent damage of the sensor.
3. Sensor secondary circuitry must be powered prior primary current is being added and when depowering secondary circuitry, primary current must be close to 0A. Improper procedure may result in worse accuracy or result in permanent damage of the sensor.
4. Dynamic performances (di/dt and response time) are best with a single busbar completely filling the primary through hole.
5. Sensor is customizable upon request.

5. Dimensions

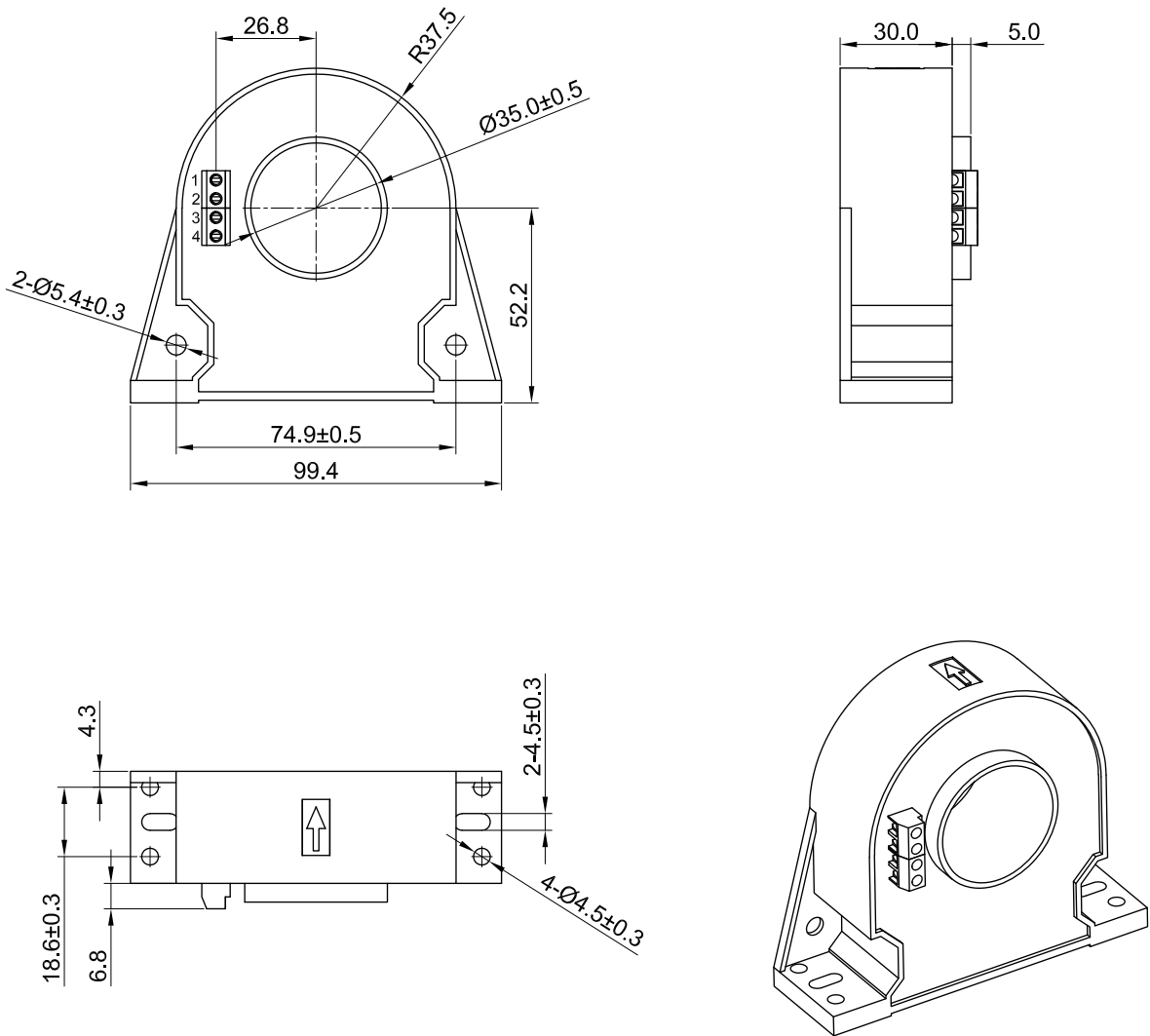


Figure 7. Dimension (unit: mm, tolerances for unmarked scales ± 1 mm)

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