

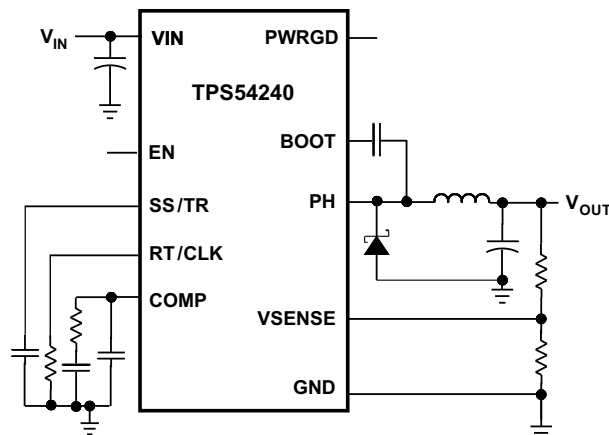
# 3.5-V to 42-V STEP-DOWN SWIFT™ DC/DC CONVERTER WITH Eco-mode™ CONTROL SCHEME

Check for Samples: [TPS54240-Q1](#)

## FEATURES

- Qualified for Automotive Applications
- AEC Q100 Qualified With the Following Results:
  - Device Temperature Grade 1: –40°C to 125°C Ambient Operating Temperature Range
  - Device HBM ESD Classification Level H2
  - Device CDM ESD Classification Level C6
- 3.5-V to 42-V Input Voltage Range
- 200-mΩ High-Side MOSFET
- High Efficiency at Light Loads With a Pulse-Skipping Eco-mode™ Control Scheme
- 138-μA Operating Quiescent Current
- 1.3-μA Shutdown Current
- 100-kHz to 2.5-MHz Switching Frequency
- Synchronizes to External Clock
- Adjustable Slow Start/Sequencing
- UV and OV Power-Good Output
- Adjustable UVLO Voltage and Hysteresis
- 0.8-V Internal Voltage Reference
- MSOP10 PowerPAD™ Package
- Supported by SwitcherPro™ Software Tool (<http://focus.ti.com/docs/toolsw/folders/print/switcherpro.html>)
- For SWIFT™ Documentation, See the TI Web site at <http://www.ti.com/swift>

### SIMPLIFIED SCHEMATIC



## APPLICATIONS

- 12-V and 24-V Industrial and Commercial Low-Power Systems
- GSM, GPRS Modules in Fleet Management, E-Meters, and Security Systems

## DESCRIPTION

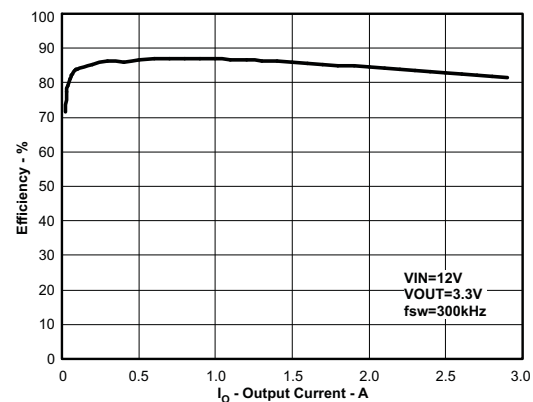
The TPS54240-Q1 device is a 42-V, 2.5-A, step-down regulator with an integrated high-side MOSFET. Current-mode control provides simple external compensation and flexible component selection. A low-ripple pulse-skip mode reduces the no-load, regulated-output supply current to 138 μA. Using the enable pin, shutdown supply current is reduced to 1.3 μA when the enable pin is low.

Undervoltage lockout is internally set at 2.5 V, but can be increased using the enable pin. The output voltage start-up ramp is controlled by the slow-start pin that can also be configured for sequencing/tracking. An open-drain power-good signal indicates the output is within 94% to 107% of its nominal voltage.

A wide switching-frequency range allows efficiency and external component size to be optimized. Frequency foldback and thermal shutdown protects the part during an overload condition.

The TPS54240-Q1 is available in a 10-pin thermally enhanced MSOP PowerPAD package.

### EFFICIENCY vs LOAD CURRENT



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

Eco-mode, PowerPAD, SwitcherPro, SWIFT are trademarks of Texas Instruments.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

Over operating temperature range (unless otherwise noted).

		VALUE		UNITS	
		MIN	MAX		
Input voltage	VIN	-0.3	47	V	
	EN <sup>(2)</sup>	-0.3	5		
	BOOT		55		
	VSENSE	-0.3	3		
	COMP	-0.3	3		
	PWRGD	-0.3	6		
	SS/TR	-0.3	3		
	RT/CLK	-0.3	3.6		
Output voltage	BOOT-PH		8		
	PH		-0.6		47
		200 ns	-1		47
		30 ns	-2		47
	Maximum dc voltage, T <sub>J</sub> = -40°C		-0.85		
Voltage difference	PAD to GND		±200	mV	
Source current	EN		100	µA	
	BOOT		100	mA	
	VSENSE		10	µA	
	PH		Current limit		
	RT/CLK		100	µA	
Sink current	VIN		Current limit		
	COMP		100	µA	
	PWRGD		10	mA	
	SS/TR		200	µA	
Operating junction temperature		-40	150	°C	
Storage temperature		-65	150		
Electrostatic discharge (ESD) rating	Human-body model (HBM) AEC-Q100 Classification Level H2		2	kV	
	Charged-device model (CDM) AEC-Q100 Classification Level C6		1000	V	

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) See the [Enable and Adjusting Undervoltage Lockout](#) section of this datasheet for details.

### RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
T <sub>A</sub>	Operating ambient temperature	-40		125	°C

**THERMAL INFORMATION**

THERMAL METRIC <sup>(1)(2)</sup>		TPS54240-Q1		UNIT
		DGQ		
		10 PINS		
$\theta_{JA}$	Junction-to-ambient thermal resistance (standard board)	62.5		°C/W
$\theta_{JA}$	Junction-to-ambient thermal resistance (custom board) <sup>(3)</sup>	57		
$\theta_{JCTop}$	Junction-to-case (top) thermal resistance	83		
$\theta_{JB}$	Junction-to-board thermal resistance	28		
$\Psi_{JT}$	Junction-to-top characterization parameter	1.7		
$\Psi_{JB}$	Junction-to-board characterization parameter	20.1		
$\theta_{JCbott}$	Junction-to-case (bottom) thermal resistance	21		

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).
- (2) Power rating at a specific ambient temperature  $T_A$  should be determined with a junction temperature of 150°C. This is the point where distortion starts to increase substantially. See [Power-Dissipation Estimate](#) in the *Application Information* section of this data sheet for more information.
- (3) Test board conditions:
- 3 in × 3 in (7,62 mm × 7,62 mm), 2 layers, thickness: 0.062 in (1,59 mm)
  - 2-oz (0,071-mm thick) copper traces located on the top of the PCB
  - 2-oz (0,071-mm thick) copper ground plane, bottom layer
  - 6 13-mil (0,33-mm) thermal vias located under the device package

**ELECTRICAL CHARACTERISTICS**
 $T_J = -40^\circ\text{C}$  to  $150^\circ\text{C}$ ,  $V_{IN} = 3.5\text{ V}$  to  $42\text{ V}$  (unless otherwise noted)

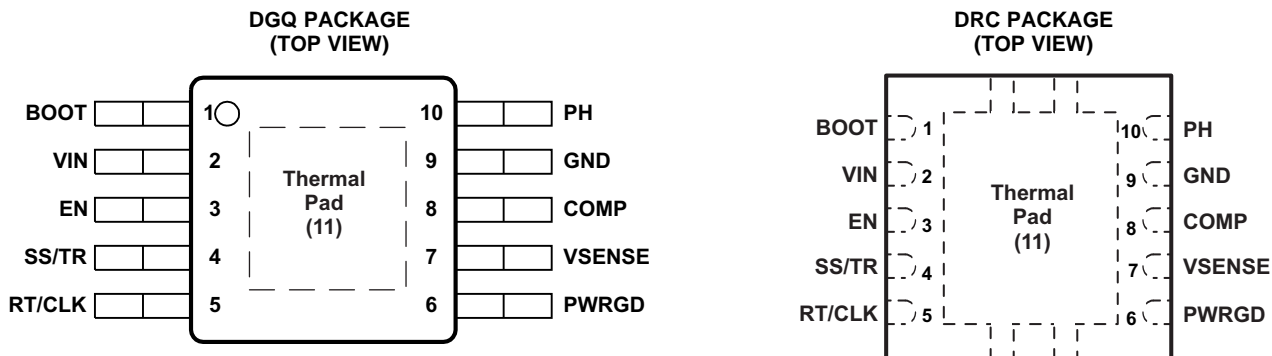
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SUPPLY VOLTAGE (VIN PIN)</b>					
Operating input voltage		3.5		42	V
Internal undervoltage lockout threshold	No voltage hysteresis, rising and falling		2.5		V
Shutdown supply current	$EN = 0\text{ V}$ , $25^\circ\text{C}$ , $3.5\text{ V} \leq V_{IN} \leq 42\text{ V}$		1.3	4	$\mu\text{A}$
Operating: nonswitching supply current	$V_{SENSE} = 0.83\text{ V}$ , $V_{IN} = 12\text{ V}$ , $25^\circ\text{C}$		138	200	
<b>ENABLE AND UVLO (EN PIN)</b>					
Enable threshold voltage	No voltage hysteresis, rising and falling, $25^\circ\text{C}$	1.15	1.25	1.36	V
Input current	Enable threshold 50 mV		-3.8		$\mu\text{A}$
	Enable threshold -50 mV		-0.9		
Hysteresis current			-2.9		$\mu\text{A}$
<b>VOLTAGE REFERENCE</b>					
Voltage reference	$T_J = 25^\circ\text{C}$	0.792	0.8	0.808	V
		0.784	0.8	0.816	
<b>HIGH-SIDE MOSFET</b>					
On-resistance	$V_{IN} = 3.5\text{ V}$ , $BOOT-PH = 3\text{ V}$		300		m $\Omega$
	$V_{IN} = 12\text{ V}$ , $BOOT-PH = 6\text{ V}$		200	410	
<b>ERROR AMPLIFIER</b>					
Input current			50		nA
Error amplifier transconductance ( $g_m$ )	$-2\text{ }\mu\text{A} < I_{COMP} < 2\text{ }\mu\text{A}$ , $V_{COMP} = 1\text{ V}$		310		$\mu\text{Mhos}$
Error amplifier transconductance ( $g_m$ ) during slow start	$-2\text{ }\mu\text{A} < I_{COMP} < 2\text{ }\mu\text{A}$ , $V_{COMP} = 1\text{ V}$ , $V_{SENSE} = 0.4\text{ V}$		70		$\mu\text{Mhos}$
Error amplifier dc gain	$V_{SENSE} = 0.8\text{ V}$		10,000		V/V
Error amplifier bandwidth			2700		kHz
Error amplifier source/sink	$V_{(COMP)} = 1\text{ V}$ , 100 mV overdrive		$\pm 27$		$\mu\text{A}$
COMP to switch current transconductance			10.5		A/V

**ELECTRICAL CHARACTERISTICS (continued)**T<sub>J</sub> = –40°C to 150°C, V<sub>IN</sub> = 3.5 V to 42 V (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>CURRENT LIMIT</b>						
Current limit threshold		V <sub>IN</sub> = 12 V, T <sub>J</sub> = 25°C	3.5	6.1		A
<b>THERMAL SHUTDOWN</b>						
Thermal shutdown				182		°C
<b>TIMING RESISTOR AND EXTERNAL CLOCK (RT/CLK PIN)</b>						
Switching-frequency range using RT mode			100		2500	kHz
f <sub>SW</sub>	Switching frequency	R <sub>T</sub> = 200 kΩ	450	581	720	kHz
Switching frequency range using CLK mode			300		2200	kHz
Minimum CLK input pulse duration				40		ns
RT/CLK high threshold				1.9	2.2	V
RT/CLK low threshold			0.5	0.7		V
RT/CLK falling edge to PH rising edge delay		Measured at 500 kHz with RT resistor in series		60		ns
PLL lock-in time		Measured at 500 kHz		100		μs
<b>SLOW START AND TRACKING (SS/TR)</b>						
Charge current		V <sub>SS/TR</sub> = 0.4 V		2		μA
SS/TR-to-VSENSE matching		V <sub>SS/TR</sub> = 0.4 V		45		mV
SS/TR-to-reference crossover		98% nominal		1.15		V
SS/TR discharge current (overload)		VSENSE = 0 V, V(SS/TR) = 0.4 V		382		μA
SS/TR discharge voltage		VSENSE = 0 V		54		mV
<b>POWER GOOD (PWRGD PIN)</b>						
V <sub>VSENSE</sub>	VSENSE threshold	VSENSE falling		92%		
		VSENSE rising		94%		
		VSENSE rising		109%		
		VSENSE falling		107%		
Hysteresis		VSENSE falling		2%		
Output-high leakage		VSENSE = VREF, V(PWRGD) = 5.5 V, 25°C		10		nA
On-resistance		I(PWRGD) = 3 mA, VSENSE < 0.79 V		50		Ω
Minimum V <sub>IN</sub> for defined output		V(PWRGD) < 0.5 V, I(PWRGD) = 100 μA		0.95	1.5	V

## DEVICE INFORMATION

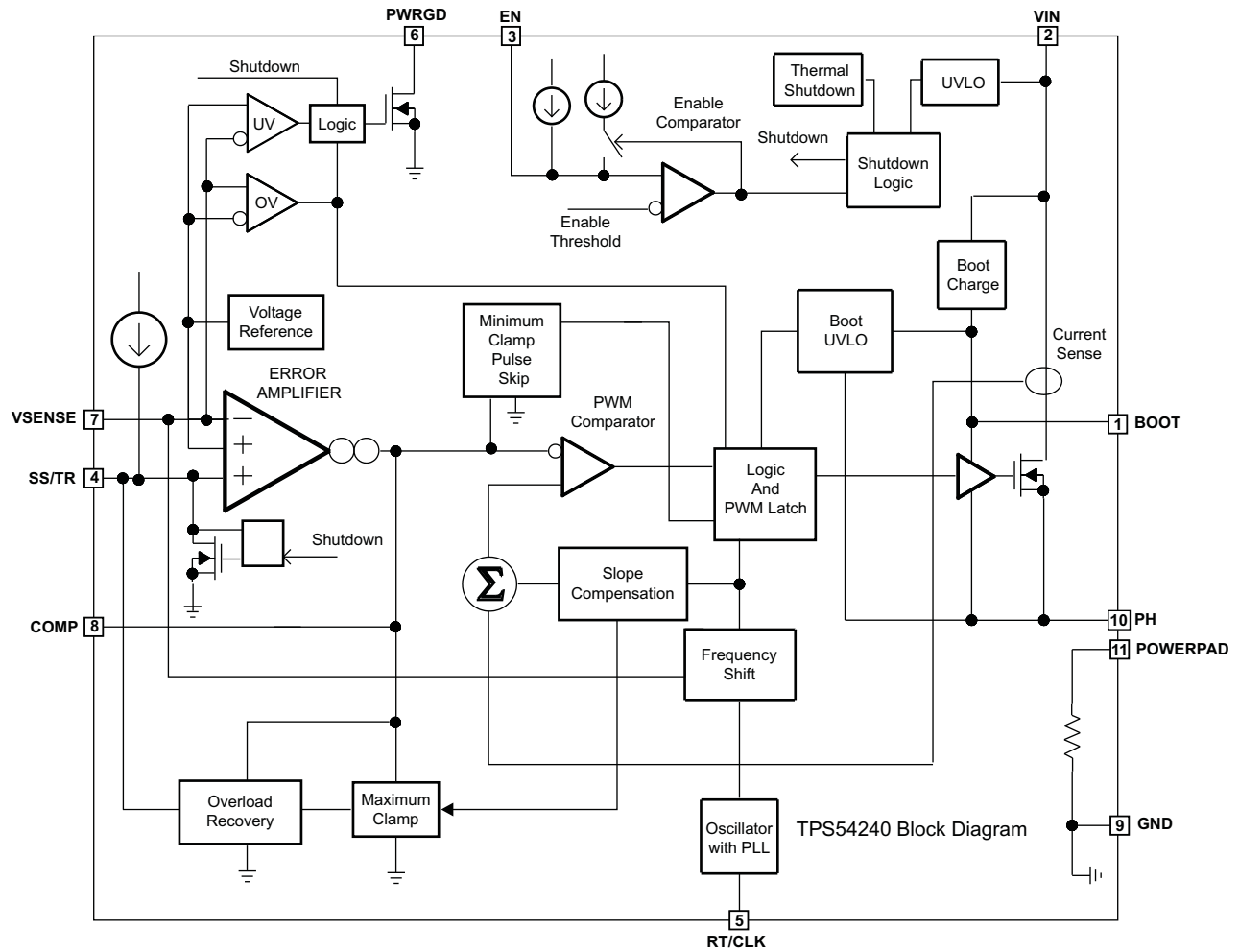
### PIN CONFIGURATION



### PIN FUNCTIONS

PIN		I/O	DESCRIPTION
NAME	NO.		
BOOT	1	O	Connect a bootstrap capacitor between BOOT and PH. If the voltage on this mandatory capacitor is below the minimum required by the output device, the output is forced to switch off until the capacitor is refreshed.
COMP	8	O	Error amplifier output, and input to the output switch current comparator. Connect frequency compensation components to this pin.
EN	3	I	Enable pin, internal pullup current source. Pull below 1.2 V to disable. Float to enable. Adjust the input undervoltage lockout with two resistors.
GND	9	–	Ground
PH	10	I	The source of the internal high-side power MOSFET
PWRGD	6	O	An open-drain output, asserts low if output voltage is low due to thermal shutdown, dropout, overvoltage or EN shutdown.
RT/CLK	5	I	Resistor timing and external clock. An internal amplifier holds this pin at a fixed voltage when using an external resistor to ground to set the switching frequency. If the pin is pulled above the PLL upper threshold, a mode change occurs and the pin becomes a synchronization input. The internal amplifier is disabled and the pin is a high-impedance clock input to the internal PLL. If clocking edges stop, the internal amplifier is re-enabled and the mode returns to a resistor-set function.
SS/TR	4	I	Slow-start and tracking. An external capacitor connected to this pin sets the output rise time. Because the voltage on this pin overrides the internal reference, it can be used for tracking and sequencing.
VIN	2	I	Input supply voltage, 3.5 V to 42 V
VSENSE	7	I	Inverting node of the transconductance ( $g_m$ ) error amplifier
Thermal pad	(11)	–	GND pin must be electrically connected to the exposed pad on the printed circuit board for proper operation.

**FUNCTIONAL BLOCK DIAGRAM**



TYPICAL CHARACTERISTICS

ON-RESISTANCE vs JUNCTION TEMPERATURE

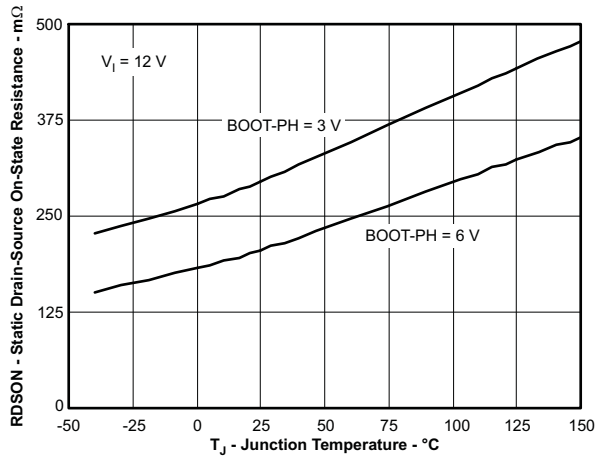


Figure 1.

VOLTAGE REFERENCE vs JUNCTION TEMPERATURE

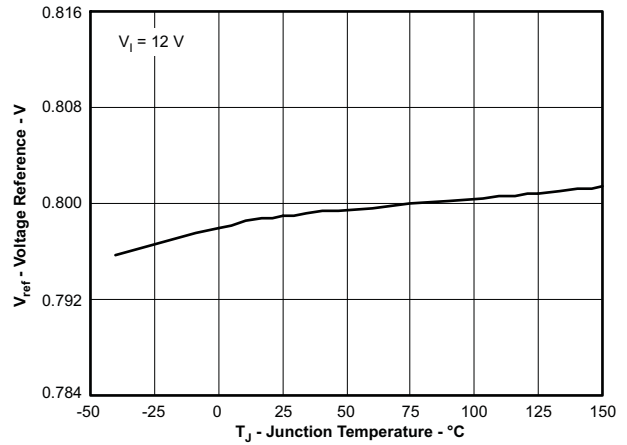


Figure 2.

SWITCH CURRENT LIMIT vs JUNCTION TEMPERATURE

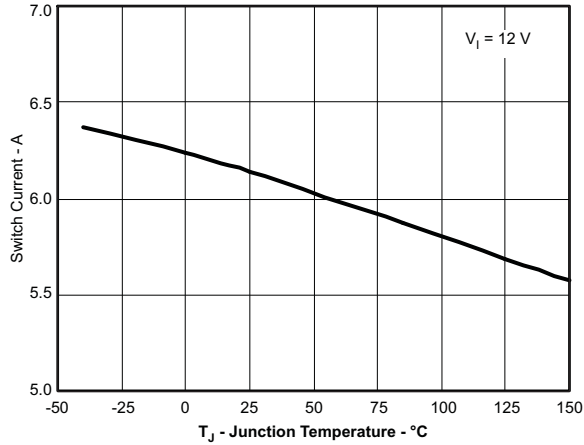


Figure 3.

SWITCHING FREQUENCY vs JUNCTION TEMPERATURE

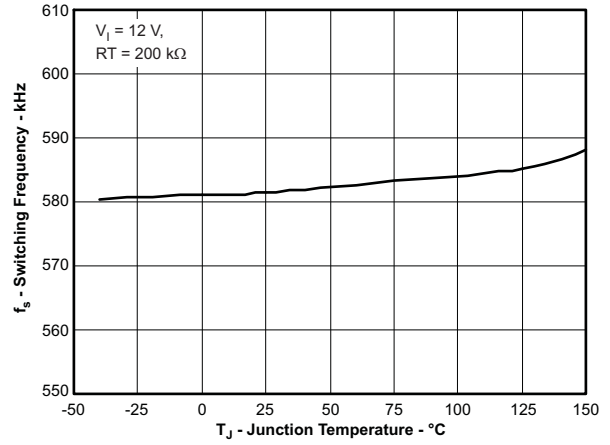


Figure 4.

SWITCHING FREQUENCY vs RT/CLK RESISTANCE, HIGH-FREQUENCY RANGE

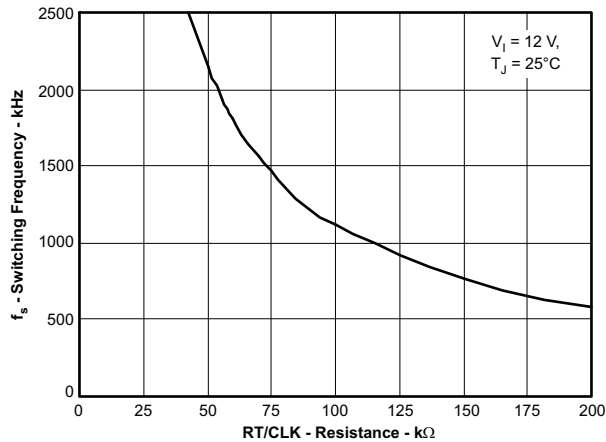


Figure 5.

SWITCHING FREQUENCY vs RT/CLK RESISTANCE, LOW-FREQUENCY RANGE

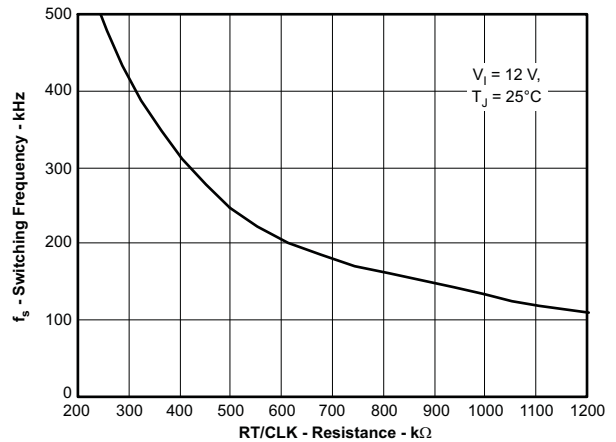


Figure 6.

**TYPICAL CHARACTERISTICS (continued)**

**EA TRANSCONDUCTANCE DURING SLOW START vs JUNCTION TEMPERATURE**

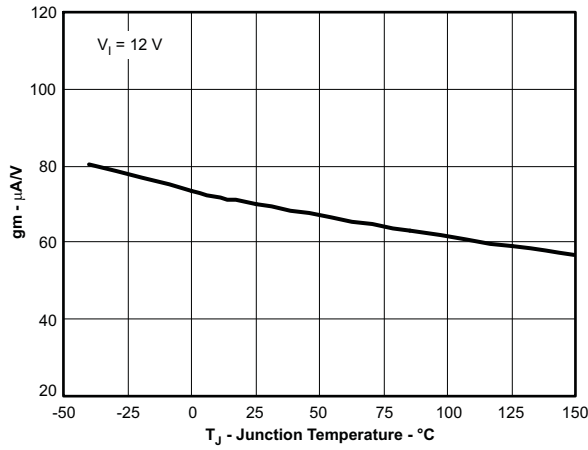


Figure 7.

**EA TRANSCONDUCTANCE vs JUNCTION TEMPERATURE**

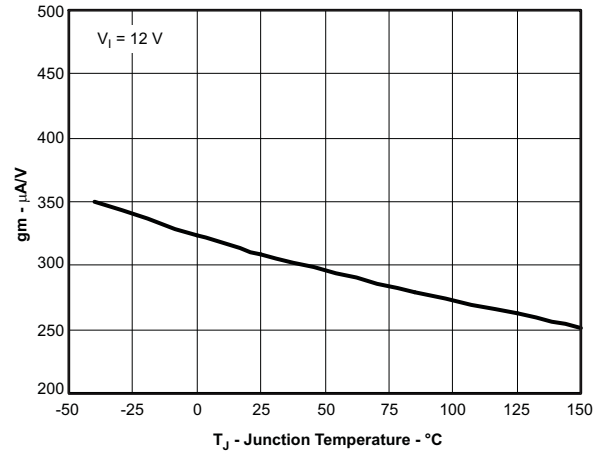


Figure 8.

**EN PIN VOLTAGE vs JUNCTION TEMPERATURE**

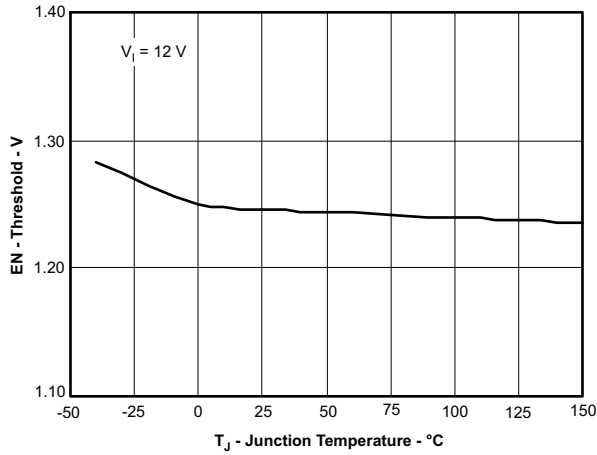


Figure 9.

**EN PIN CURRENT vs JUNCTION TEMPERATURE**

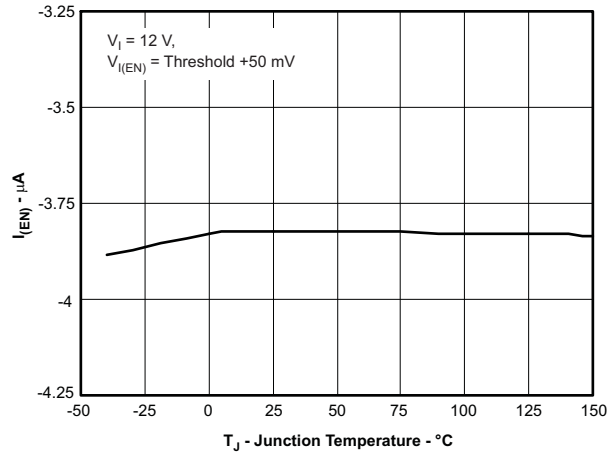


Figure 10.

**EN PIN CURRENT vs JUNCTION TEMPERATURE**

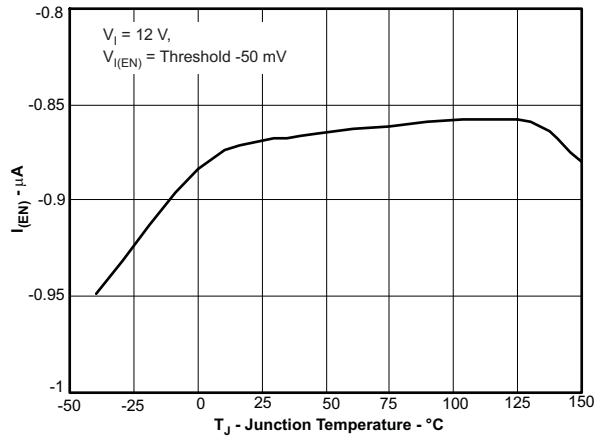


Figure 11.

**SS/TR CHARGE CURRENT vs JUNCTION TEMPERATURE**

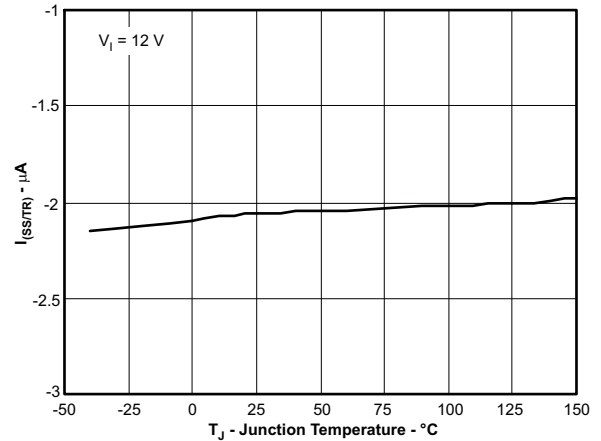


Figure 12.



**TYPICAL CHARACTERISTICS (continued)**

**SS/TR DISCHARGE CURRENT vs JUNCTION TEMPERATURE**

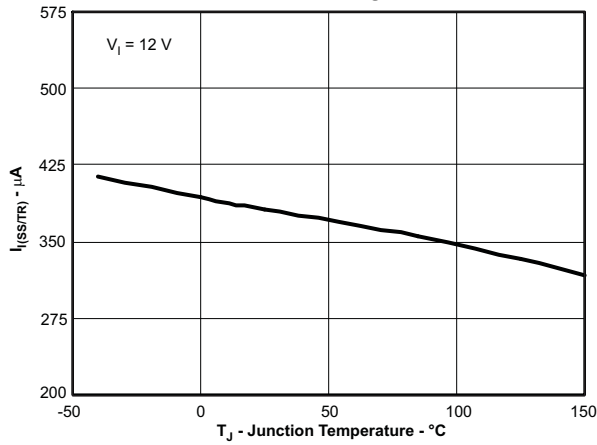


Figure 13.

**SWITCHING FREQUENCY vs VSENSE**

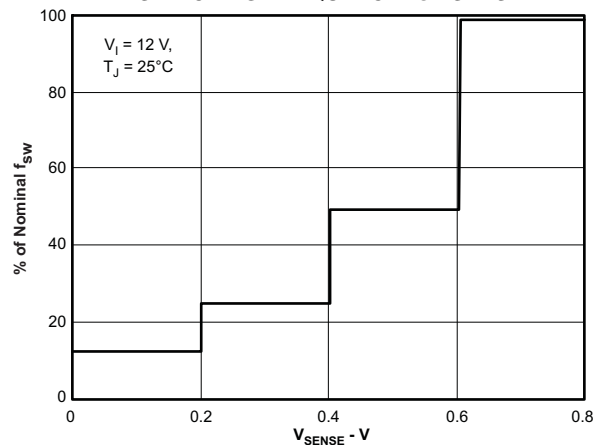


Figure 14.

**SHUTDOWN SUPPLY CURRENT vs JUNCTION TEMPERATURE**

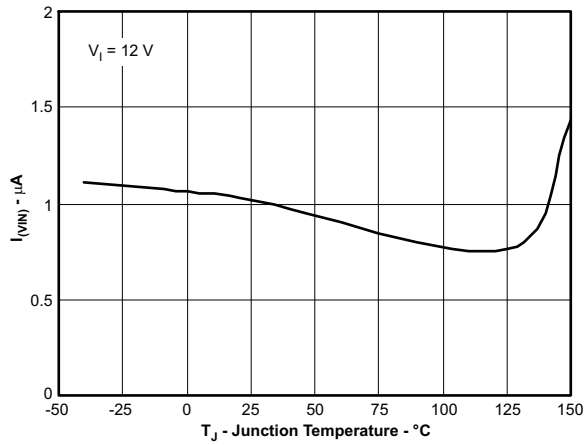


Figure 15.

**SHUTDOWN SUPPLY CURRENT vs INPUT VOLTAGE (VIN)**

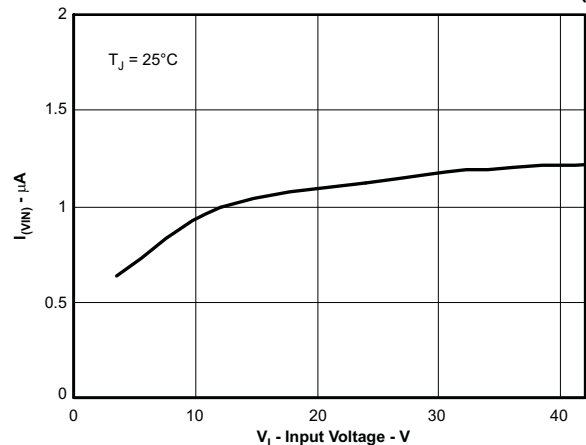


Figure 16.

**VIN SUPPLY CURRENT vs JUNCTION TEMPERATURE**

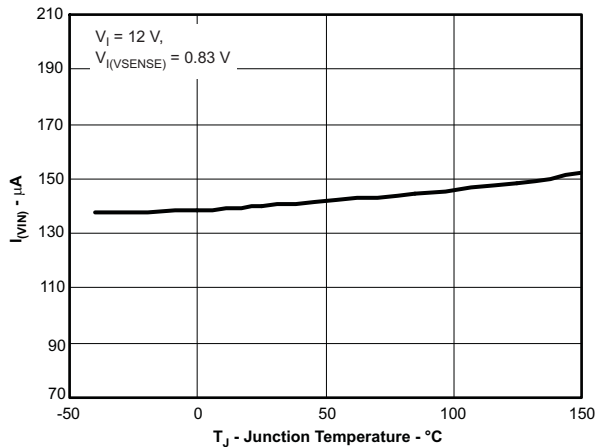


Figure 17.

**VIN SUPPLY CURRENT vs INPUT VOLTAGE**

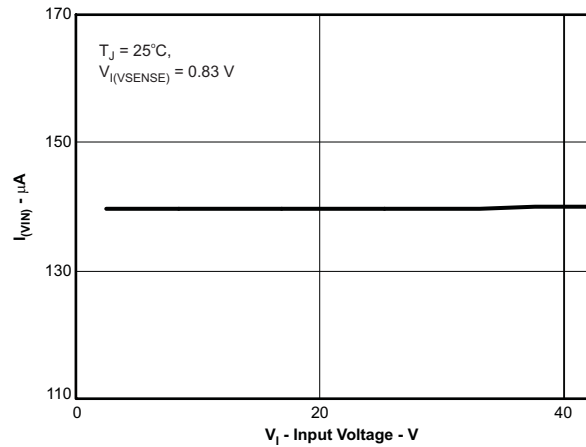


Figure 18.

**TYPICAL CHARACTERISTICS (continued)**

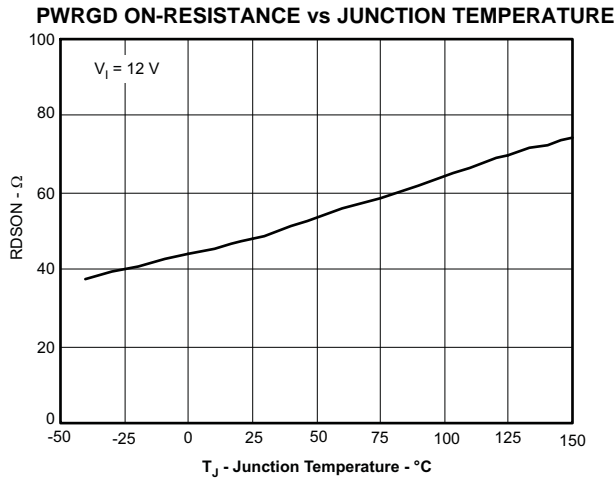


Figure 19.

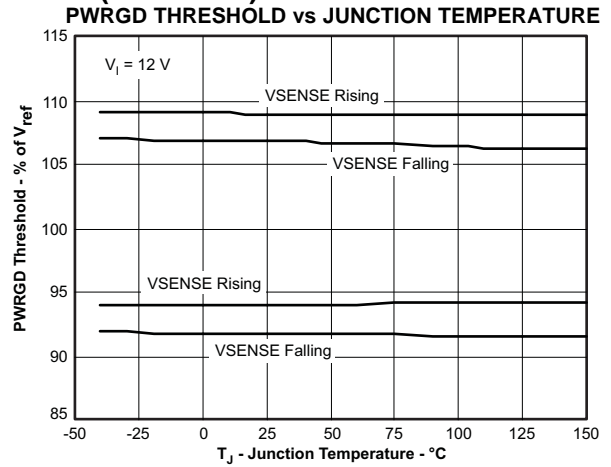


Figure 20.

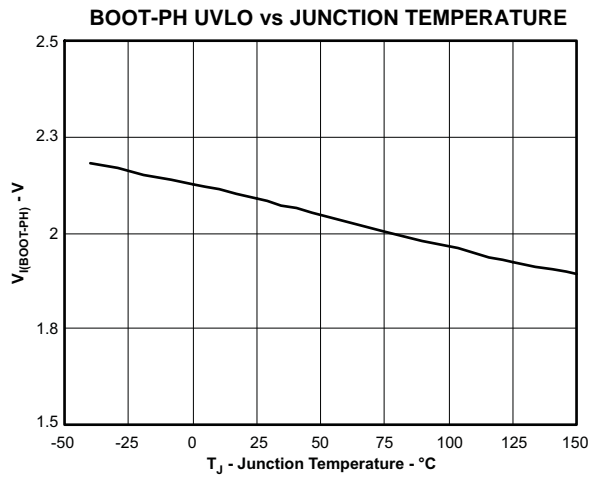


Figure 21.

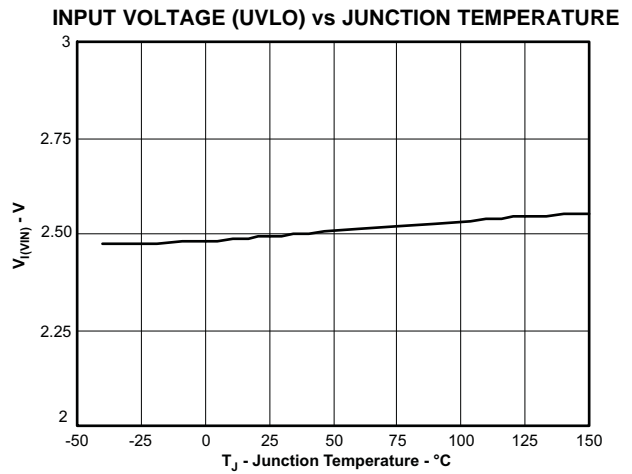


Figure 22.

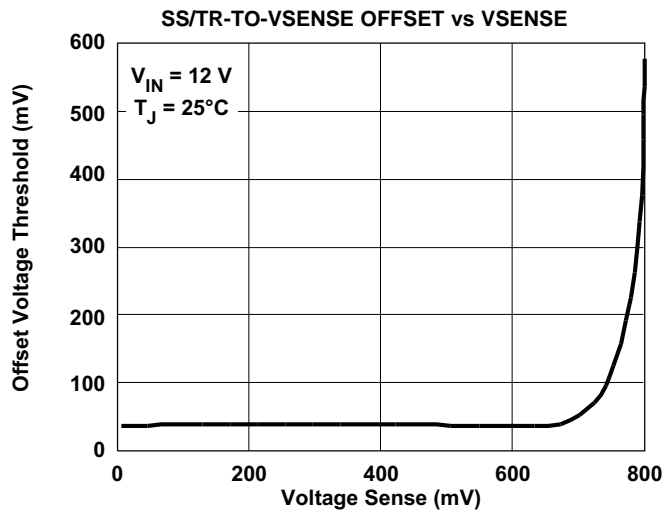


Figure 23.

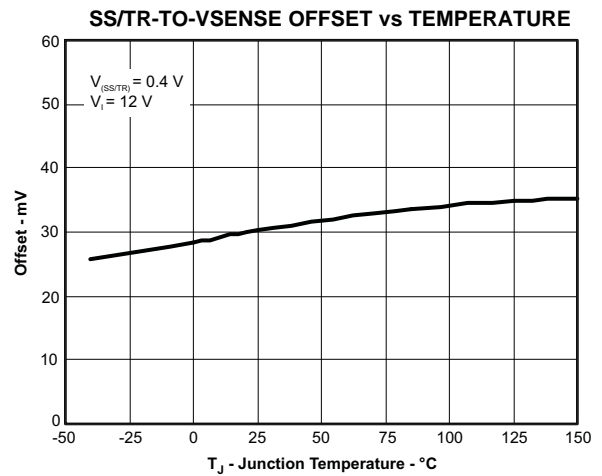


Figure 24.

## OVERVIEW

The TPS54240-Q1 device is a 42-V, 2.5-A, step-down (buck) regulator with an integrated high-side n-channel MOSFET. To improve performance during line and load transients, the device implements a constant-frequency, current-mode control which reduces output capacitance and simplifies external frequency compensation design. The wide switching frequency of 100 kHz to 2500 kHz allows for efficiency and size optimization when selecting the output-filter components. The switching frequency is adjusted using a resistor to ground on the RT/CLK pin. The device has an internal phase-lock loop (PLL) on the RT/CLK pin that is used to synchronize the power switch turnon to a falling edge of an external system clock.

The TPS54240-Q1 has a default start-up voltage of approximately 2.5 V. The EN pin has an internal pullup current source that is used to adjust the input undervoltage lockout (UVLO) threshold with two external resistors. In addition, the pullup current provides a default condition. When the EN pin is floating the device operates. The operating current is 138  $\mu$ A when not switching and under no load. When the device is disabled, the supply current is 1.3  $\mu$ A.

The integrated 200-m $\Omega$  high-side MOSFET allows for high-efficiency power-supply designs capable of delivering 2.5 A of continuous current to a load. The TPS54240-Q1 reduces the external component count by integrating the boot recharge diode. The bias voltage for the integrated high-side MOSFET is supplied by a capacitor between the BOOT and PH pins. The boot capacitor voltage is monitored by a UVLO circuit and turns the high-side MOSFET off when the boot voltage falls below a preset threshold. The TPS54240-Q1 operates at high duty cycles because of the boot UVLO. The output voltage can be stepped down to as low as the 0.8 V reference.

The TPS54240-Q1 has a power-good comparator (PWRGD) which asserts when the regulated output voltage is less than 92% or greater than 109% of the nominal output voltage. The PWRGD pin is an open-drain output which deasserts when the VSENSE pin voltage is between 94% and 107% of the nominal output voltage, allowing the pin to transition high when a pullup resistor is used.

The TPS54240-Q1 minimizes excessive output overvoltage (OV) transients by taking advantage of the OV power-good comparator. When the OV comparator is activated, the high-side MOSFET is turned off and masked from turning on until the output voltage is lower than 107%.

The SS/TR (slow start/tracking) pin is used to minimize inrush currents or provide power-supply sequencing during power up. A small-value capacitor should be coupled to the pin to adjust the slow-start time. A resistor divider can be coupled to the pin for critical power-supply sequencing requirements. The SS/TR pin is discharged before the output powers up. This discharging ensures a repeatable restart after an overtemperature fault, UVLO fault or a disabled condition.

The TPS54240-Q1 also discharges the slow-start capacitor during overload conditions with an overload recovery circuit. The overload recovery circuit slow-starts the output from the fault voltage to the nominal regulation voltage once a fault condition is removed. A frequency foldback circuit reduces the switching frequency during startup and overcurrent fault conditions to help control the inductor current.

## DETAILED DESCRIPTION

### Fixed-Frequency PWM Control

The TPS54240-Q1 uses an adjustable fixed-frequency, peak-current-mode control. The output voltage is compared through external resistors on the VSENSE pin to an internal voltage reference by an error amplifier which drives the COMP pin. An internal oscillator initiates the turnon of the high-side power switch. The error amplifier output is compared to the high-side power-switch current. When the power-switch current reaches the level set by the COMP voltage, the power switch is turned off. The COMP pin voltage increases and decreases as the output current increases and decreases. The device implements a current limit by clamping the COMP pin voltage to a maximum level. The Eco-mode™ control scheme is implemented with a minimum clamp on the COMP pin.

### Slope Compensation Output Current

The TPS54240-Q1 adds a compensating ramp to the switch-current signal. This slope compensation prevents sub-harmonic oscillations. The available peak inductor current remains constant over the full duty cycle range.

### Pulse-Skip Eco-mode Control Scheme

The TPS54240-Q1 operates in a pulse-skip Eco-mode at light load currents to improve efficiency by reducing switching and gate drive losses. The TPS54240-Q1 is designed so that if the output voltage is within regulation and the peak switch current at the end of any switching cycle is below the pulse skipping current threshold, the device enters Eco-mode. This current threshold is the current level corresponding to a nominal COMP voltage or 500 mV.

When in Eco-mode, the COMP pin voltage is clamped at 500 mV and the high-side MOSFET is inhibited. Further decreases in load current or in output voltage cannot drive the COMP pin below this clamp voltage level.

Because the device is not switching, the output voltage begins to decay. As the voltage control loop compensates for the falling output voltage, the COMP pin voltage begins to rise. At this time, the high-side MOSFET is enabled and a switching pulse initiates on the next switching cycle. The peak current is set by the COMP pin voltage. The output voltage recharges the regulated value, then the peak switch current starts to decrease, and eventually falls below the Eco-mode threshold, at which time the device again enters Eco-mode.

For Eco-mode operation, the TPS54240-Q1 senses peak current, not average or load current, so the load current where the device enters Eco-mode is dependent on the output inductor value. For example, the circuit in [Figure 50](#) enters Eco-mode at about 5 mA of output current. When the load current is low and the output voltage is within regulation, the device enters a sleep mode and draws only 138  $\mu$ A of input quiescent current. The internal PLL remains operating when in sleep mode. When operating at light load currents in the pulse-skip mode, the switching transitions occur synchronously with the external clock signal.

### Low-Dropout Operation and Bootstrap Voltage (BOOT)

The TPS54240-Q1 has an integrated boot regulator, and requires a small ceramic capacitor between the BOOT and PH pins to provide the gate-drive voltage for the high-side MOSFET. The BOOT capacitor is refreshed when the high-side MOSFET is off and the low-side diode conducts. The value of this ceramic capacitor should be 0.1  $\mu$ F. A ceramic capacitor with an X7R or X5R grade dielectric with a voltage rating of 10 V or higher is recommended because of the stable characteristics over temperature and voltage.

To improve dropout, the TPS54240-Q1 is designed to operate at 100% duty cycle as long as the BOOT-to-PH pin voltage is greater than 2.1 V. When the voltage from BOOT to PH drops below 2.1 V, the high-side MOSFET is turned off using an UVLO circuit, which allows the low side diode to conduct and refresh the charge on the BOOT capacitor. Because the supply current sourced from the BOOT capacitor is low, the high-side MOSFET can remain on for more switching cycles than are required to refresh the capacitor; thus, the effective duty cycle of the switching regulator is high.

The effective duty cycle during dropout of the regulator is mainly influenced by the voltage drops across the power MOSFET, inductor resistance, low-side diode, and printed circuit board resistance. During operating conditions in which the input voltage drops and the regulator is operating in continuous-conduction mode, the high-side MOSFET can remain on for 100% of the duty cycle to maintain output regulation, until the BOOT-to-PH-voltage falls below 2.1 V.

### DETAILED DESCRIPTION (continued)

Attention must be taken in maximum-duty-cycle applications which experience extended time periods with light loads or no load. When the voltage across the BOOT capacitor falls below the 2.1-V UVLO threshold, the high-side MOSFET is turned off, but there may not be enough inductor current to pull the PH pin down to recharge the BOOT capacitor. The high-side MOSFET of the regulator stops switching because the voltage across the BOOT capacitor is less than 2.1 V. The output capacitor then decays until the difference in the input voltage and output voltage is greater than 2.1 V, at which point the BOOT UVLO threshold is exceeded, and the device starts switching again until the desired output voltage is reached. This operating condition persists until the input voltage and/or the load current increases. TI recommends to adjust the VIN stop voltage greater than the BOOT UVLO trigger condition at the minimum load of the application using the adjustable VIN UVLO feature with resistors on the EN pin.

The start and stop voltages for typical 3.3-V and 5-V output applications are shown in Figure 25 and Figure 26. The voltages are plotted versus load current. The start voltage is defined as the input voltage needed to regulate the output within 1%. The stop voltage is defined as the input voltage at which the output drops by 5% or stops switching.

During high-duty-cycle conditions, the inductor current ripple increases while the BOOT capacitor is being recharged, resulting in an increase in ripple voltage on the output. This is due to the recharge time of the boot capacitor being longer than the typical high-side off-time, when switching occurs every cycle.

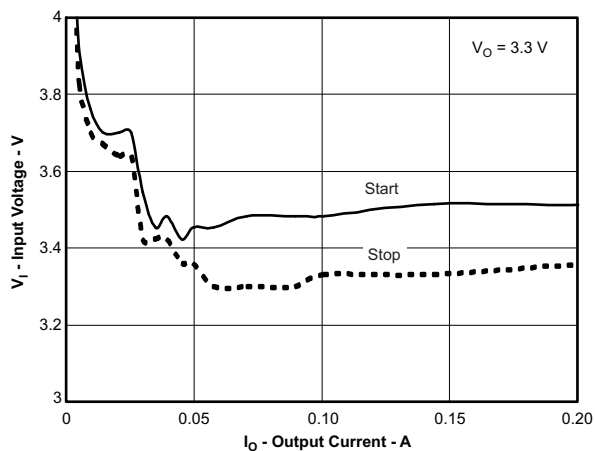


Figure 25. 3.3-V Start/Stop Voltage

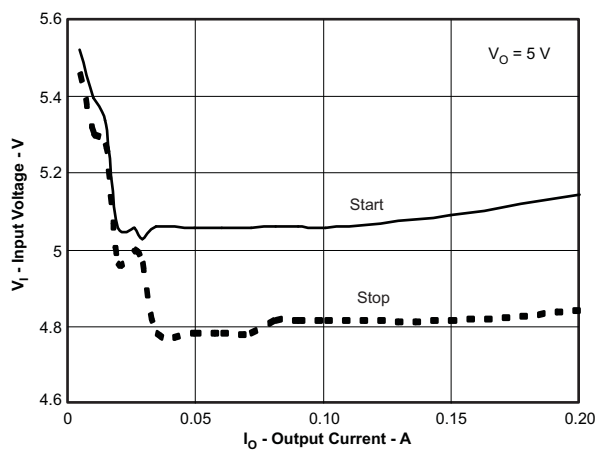


Figure 26. 5-V Start/Stop Voltage

### Error Amplifier

The TPS54240-Q1 has a transconductance amplifier for the error amplifier. The error amplifier compares the VSENSE voltage to the lower of the SS/TR pin voltage or the internal 0.8-V voltage reference. The transconductance ( $g_m$ ) of the error amplifier is 310  $\mu\text{A/V}$  during normal operation. During the slow-start operation, the transconductance is a fraction of the normal operating  $g_m$ . When the voltage of the VSENSE pin is below 0.8 V and the device is regulating using the SS/TR voltage, the  $g_m$  is 70  $\mu\text{A/V}$ .

The frequency-compensation components (capacitor, series resistor, and capacitor) are added from the COMP pin to ground.

### Voltage Reference

The voltage reference system produces a precise  $\pm 2\%$  voltage reference over temperature by scaling the output of a temperature-stable band-gap circuit.

### Adjusting the Output Voltage

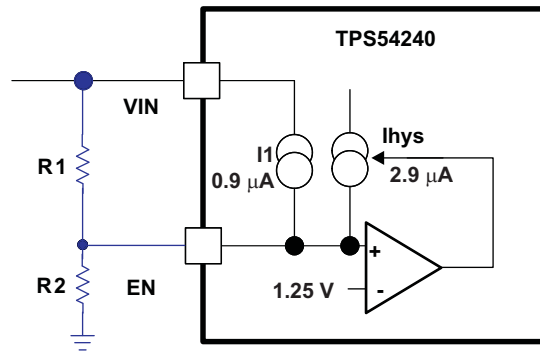
The output voltage is set with a resistor divider from the output node to the VSENSE pin. TI recommends to use 1% tolerance or better divider resistors. Start with 10 k $\Omega$  for the R2 resistor and use Equation 1 to calculate R1. To improve efficiency at light loads, consider using larger-value resistors. If the values are too high, the regulator is more susceptible to noise, and voltage errors from the VSENSE input current are noticeable.

**DETAILED DESCRIPTION (continued)**

$$R1 = R2 \times \left( \frac{V_{out} - 0.8V}{0.8V} \right) \tag{1}$$

**Enable and Adjusting Undervoltage Lockout**

The TPS54240-Q1 is disabled when the VIN pin voltage falls below 2.5 V. If an application requires a higher undervoltage lockout (UVLO), use the EN pin as shown in Figure 27 to adjust the input voltage UVLO by using the two external resistors. Though it is not necessary to use the UVLO adjust registers, for operation it is highly recommended to provide consistent power-up behavior. The EN pin has an internal pullup current source, I1, of 0.9 μA that provides the default condition of the TPS54240-Q1 operating when the EN pin floats. Once the EN pin voltage exceeds 1.25 V, an additional 2.9 μA of hysteresis, I<sub>hys</sub>, is added. This additional current facilitates input voltage hysteresis. Use Equation 2 to set the external hysteresis for the input voltage. Use Equation 3 to set the input start voltage.

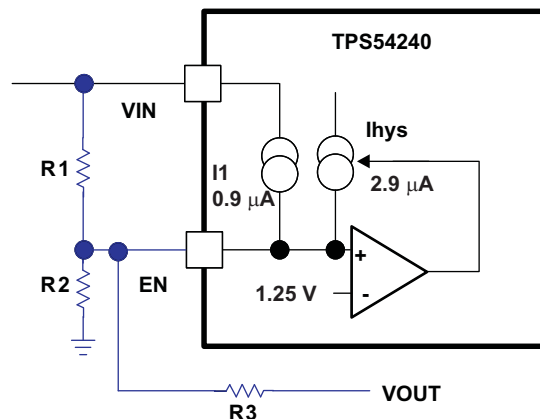


**Figure 27. Adjustable Undervoltage Lockout (UVLO)**

$$R1 = \frac{V_{START} - V_{STOP}}{I_{HYS}} \tag{2}$$

$$R2 = \frac{V_{ENA}}{\frac{V_{START} - V_{ENA}}{R1} + I_1} \tag{3}$$

Another technique to add input voltage hysteresis is shown in Figure 28. This method may be used if the resistance values are high from the previous method and a wider voltage hysteresis is needed. Resistor R3 sources additional hysteresis current into the EN pin.



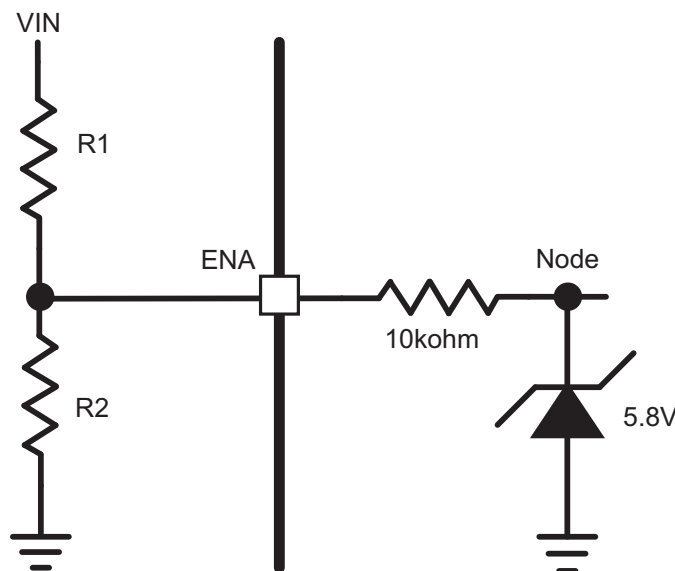
**Figure 28. Adding Additional Hysteresis**

**DETAILED DESCRIPTION (continued)**

$$R1 = \frac{V_{START} - V_{STOP}}{I_{HYS} + \frac{V_{OUT}}{R3}} \tag{4}$$

$$R2 = \frac{V_{ENA}}{\frac{V_{START} - V_{ENA}}{R1} + I_1 - \frac{V_{ENA}}{R3}} \tag{5}$$

Do not place a low-impedance voltage source with greater than 5 V directly on the EN pin. Do not place a capacitor directly on the EN pin if  $V_{EN} > 5$  V when using a voltage divider to adjust the start and stop voltage. The node voltage, (see Figure 29) must remain equal to or less than 5.8 V. The Zener diode can sink up to 100  $\mu$ A. The EN pin voltage can be greater than 5 V if the  $V_{IN}$  voltage source has a high impedance and does not source more than 100  $\mu$ A into the EN pin.



**Figure 29. Node Voltage**

**Slow Start/Tracking Pin (SS/TR)**

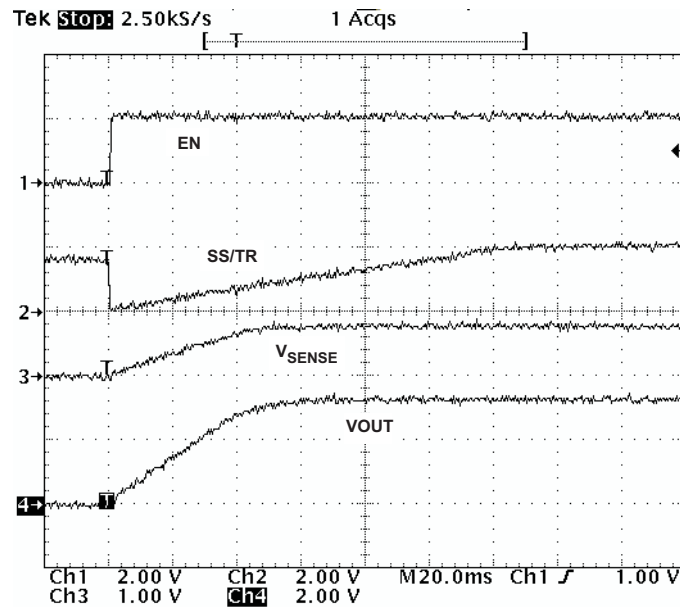
The TPS54240-Q1 effectively uses the lower voltage of the internal voltage reference or the SS/TR pin voltage as the power-supply reference voltage and regulates the output accordingly. A capacitor on the SS/TR pin to ground implements a slow-start time. The TPS54240-Q1 has an internal pullup current source of 2  $\mu$ A that charges the external slow-start capacitor. The calculations for the slow-start time (10% to 90%) are shown in Equation 6. The voltage reference ( $V_{REF}$ ) is 0.8 V and the slow-start current ( $I_{SS}$ ) is 2  $\mu$ A. The slow-start capacitor should remain lower than 0.47  $\mu$ F and greater than 0.47 nF.

$$C_{SS}(nF) = \frac{T_{ss}(ms) \times I_{ss}(\mu A)}{V_{ref}(V) \times 0.8} \tag{6}$$

At power up, the TPS54240-Q1 does not start switching until the slow start pin is discharged to less than 40 mV to ensure a proper power up, see Figure 30.

Also, during normal operation, the TPS54240-Q1 stops switching and the SS/TR must be discharged to 40 mV, when the  $V_{IN}$  UVLO is exceeded, EN pin pulled below 1.25 V, or a thermal shutdown event occurs.

The  $V_{SENSE}$  voltage follows the SS/TR pin voltage with a 45 mV offset up to 85% of the internal voltage reference. When the SS/TR voltage is greater than 85% on the internal reference voltage the offset increases as the effective system reference transitions from the SS/TR voltage to the internal voltage reference (see Figure 23). The SS/TR voltage ramps linearly until clamped at 1.7 V.

**DETAILED DESCRIPTION (continued)****Figure 30. Operation of SS/TR Pin When Starting****Overload Recovery Circuit**

The TPS54240-Q1 has an overload recovery (OLR) circuit. The OLR circuit slow starts the output from the overload voltage to the nominal regulation voltage once the fault condition is removed. The OLR circuit discharges the SS/TR pin to a voltage slightly greater than the VSENSE pin voltage using an internal pull down of 382  $\mu$ A when the error amplifier is changed to a high voltage from a fault condition. When the fault condition is removed, the output slow starts from the fault voltage to nominal output voltage.

**Sequencing**

Many of the common power supply sequencing methods can be implemented using the SS/TR, EN and PWRGD pins. The sequential method can be implemented using an open drain output of a power on reset pin of another device. The sequential method is illustrated in [Figure 31](#) using two TPS54240-Q1 devices. The power good is coupled to the EN pin on the TPS54240-Q1 which enables the second power supply once the primary supply reaches regulation. If needed, a 1nF ceramic capacitor on the EN pin of the second power supply provides a 1-ms start-up delay. [Figure 32](#) shows the results of [Figure 31](#).



DETAILED DESCRIPTION (continued)

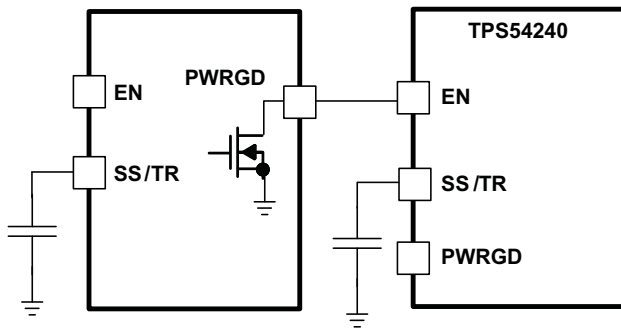


Figure 31. Schematic for Sequential Start-Up Sequence

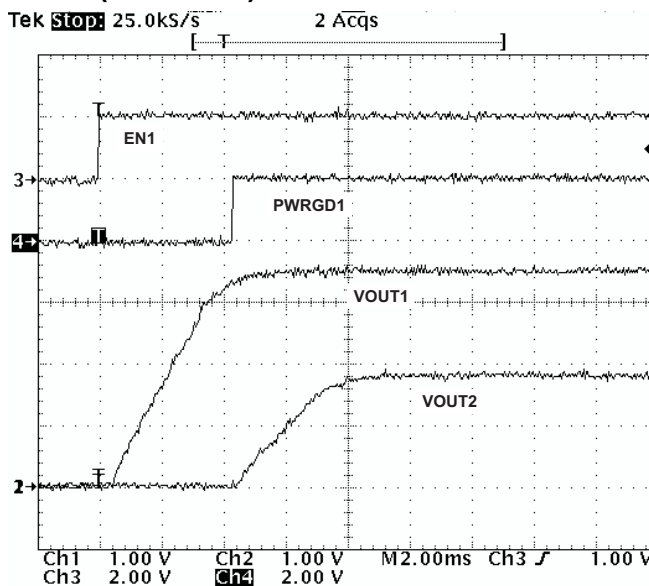


Figure 32. Sequential Startup using EN and PWRGD

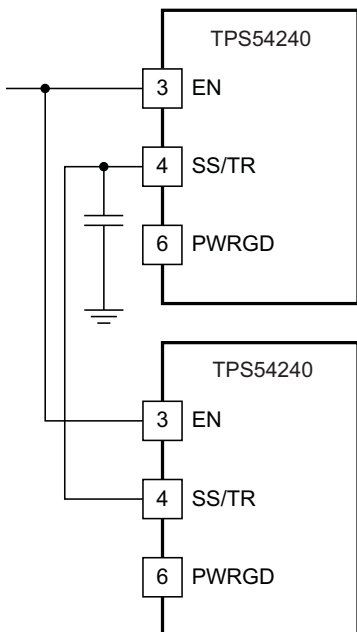


Figure 33. Schematic for Ratiometric Startup Using Coupled SS/TR Pins

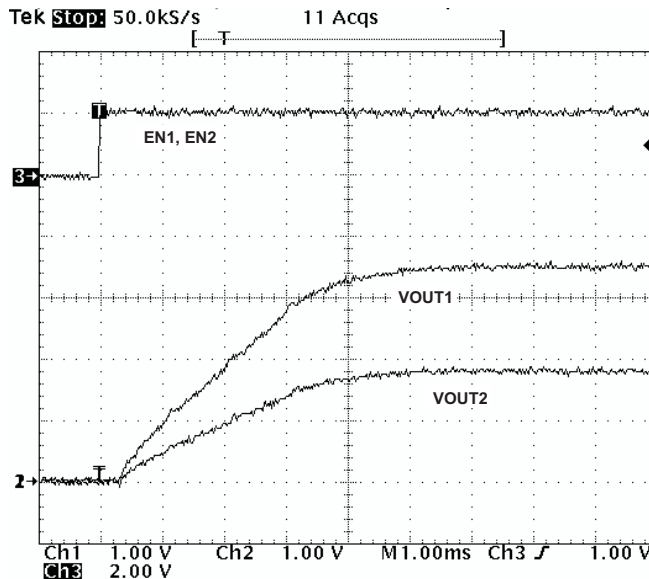
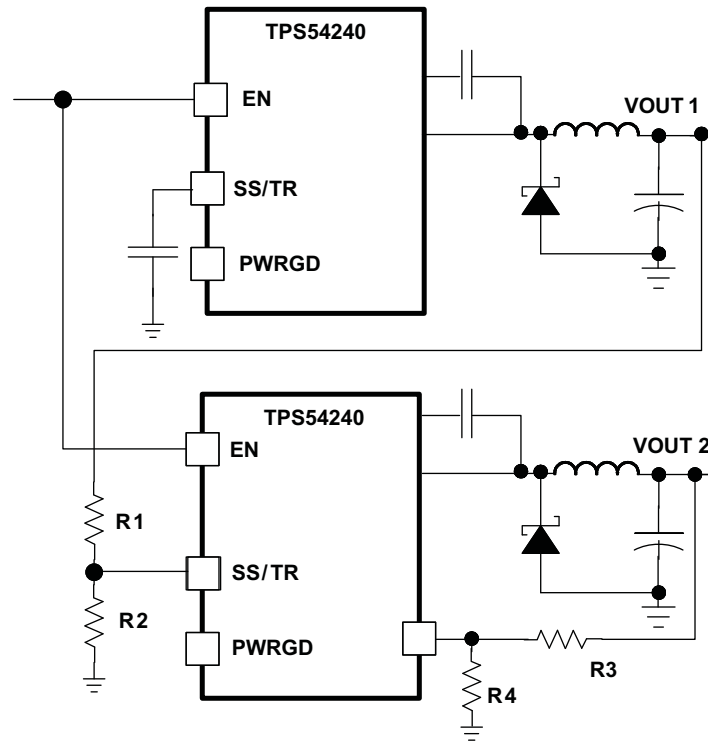


Figure 34. RatioMetric Startup Using Coupled SS/TR pins

Figure 33 shows a method for ratiometric startup sequence by connecting the SS/TR pins together. The regulator outputs ramps up and reaches regulation at the same time. When calculating the slow start time the pull up current source must be doubled in Equation 6. Figure 34 shows the results of Figure 33.

**DETAILED DESCRIPTION (continued)****Figure 35. Schematic for Ratiometric and Simultaneous Start-Up Sequence**

Ratiometric and simultaneous power supply sequencing is implemented by connecting the resistor network of R1 and R2 shown in [Figure 35](#) to the output of the power supply that needs to be tracked or another voltage reference source. Using [Equation 7](#) and [Equation 8](#), the tracking resistors can be calculated to initiate the Vout2 slightly before, after or at the same time as Vout1. [Equation 9](#) is the voltage difference between Vout1 and Vout2 at the 95% of nominal output regulation.

The deltaV variable is zero volts for simultaneous sequencing. To minimize the effect of the inherent SS/TR to VSENSE offset (V<sub>ssoffset</sub>) in the slow start circuit and the offset created by the pullup current source (I<sub>ss</sub>) and tracking resistors, the V<sub>ssoffset</sub> and I<sub>ss</sub> are included as variables in the equations.

To design a ratio-metric start up in which the Vout2 voltage is slightly greater than the Vout1 voltage when Vout2 reaches regulation, use a negative number in [Equation 7](#) through [Equation 9](#) for deltaV. [Equation 9](#) results in a positive number for applications which the Vout2 is slightly lower than Vout1 when Vout2 regulation is achieved.

Because the SS/TR pin must be pulled below 40mV before starting after an EN, UVLO or thermal shutdown fault, careful selection of the tracking resistors is needed to ensure the device restarts after a fault. Make sure the calculated R1 value from [Equation 7](#) is greater than the value calculated in [Equation 10](#) to ensure the device can recover from a fault.

As the SS/TR voltage becomes more than 85% of the nominal reference voltage the V<sub>ssoffset</sub> becomes larger as the slow start circuits gradually handoff the regulation reference to the internal voltage reference. The SS/TR pin voltage needs to be greater than 1.3 V for a complete handoff to the internal voltage reference as shown in [Figure 23](#).

$$R1 = \frac{V_{out2} + \Delta V}{V_{REF}} \times \frac{V_{ssoffset}}{I_{ss}} \quad (7)$$

$$R2 = \frac{V_{REF} \times R1}{V_{out2} + \Delta V - V_{REF}} \quad (8)$$

$$\Delta V = V_{out1} - V_{out2} \quad (9)$$

$$R1 > 2800 \times V_{out1} - 180 \times \Delta V \quad (10)$$

DETAILED DESCRIPTION (continued)

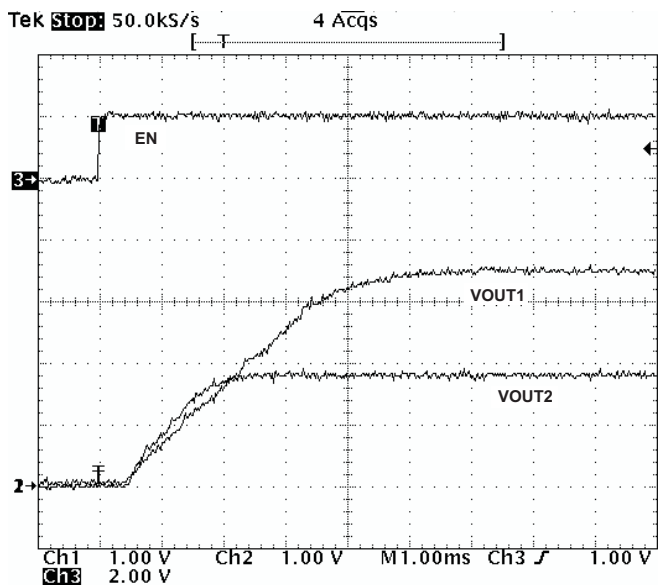


Figure 36. Ratiometric Startup With VOUT2 Leading VOUT1

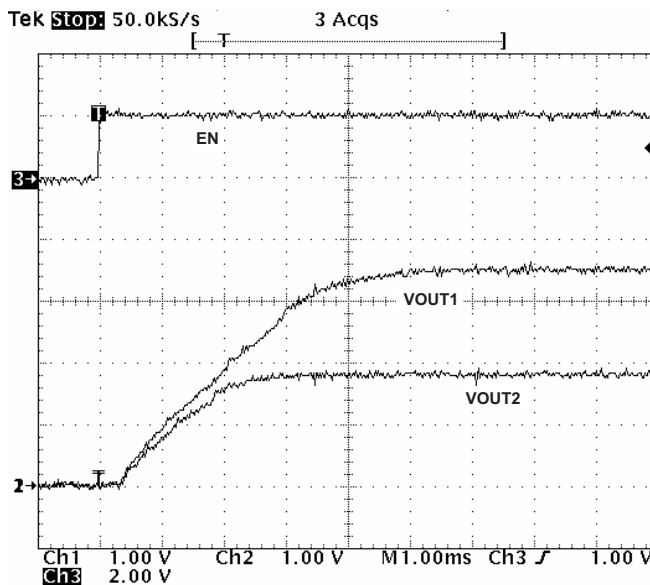


Figure 37. Ratiometric Startup With VOUT1 Leading VOUT2

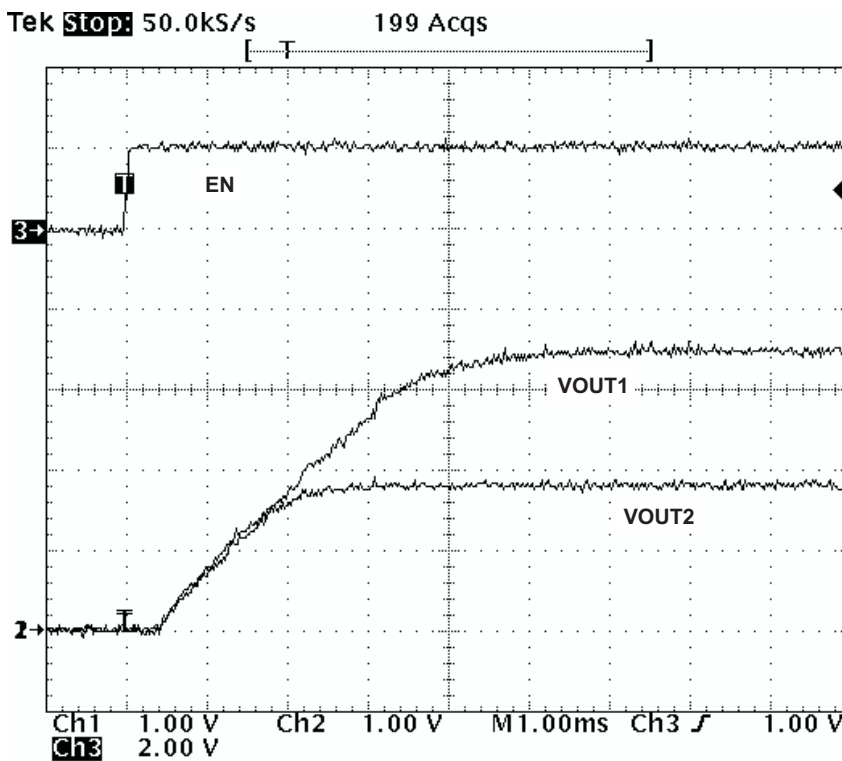


Figure 38. Simultaneous Startup With Tracking Resistor

**DETAILED DESCRIPTION (continued)**

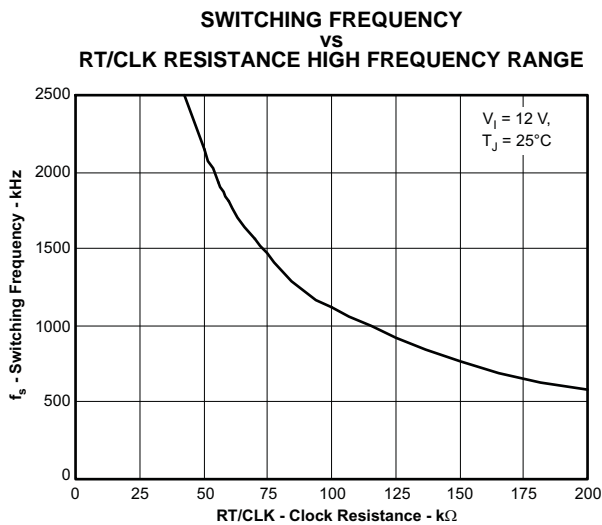
**Constant Switching Frequency and Timing Resistor (RT/CLK Pin)**

The switching frequency of the TPS54240-Q1 is adjustable over a wide range from approximately 100 kHz to 2500 kHz by placing a resistor on the RT/CLK pin. The RT/CLK pin voltage is typically 0.5 V and must have a resistor to ground to set the switching frequency. To determine the timing resistance for a given switching frequency, use Equation 11 or the curves in Figure 39 or Figure 40. To reduce the solution size one would typically set the switching frequency as high as possible, but tradeoffs of the supply efficiency, maximum input voltage and minimum controllable on time should be considered.

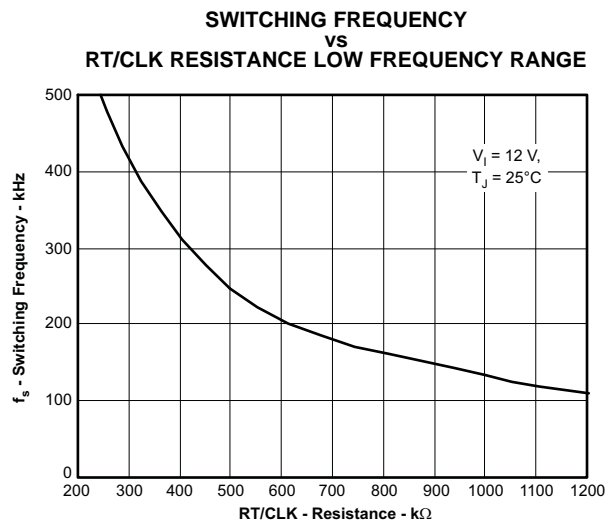
The minimum controllable on time is typically 135 ns and limits the maximum operating input voltage.

The maximum switching frequency is also limited by the frequency shift circuit. More discussion on the details of the maximum switching frequency is located below.

$$RT \text{ (k}\Omega\text{)} = \frac{206033}{f_{sw} \text{ (kHz)}^{1.0888}} \tag{11}$$



**Figure 39. High-Range RT**



**Figure 40. Low-Range RT**

**Overcurrent Protection and Frequency Shift**

The TPS54240-Q1 implements current mode control which uses the COMP pin voltage to turn off the high side MOSFET on a cycle by cycle basis. Each cycle the switch current and COMP pin voltage are compared, when the peak switch current intersects the COMP voltage, the high side switch is turned off. During overcurrent conditions that pull the output voltage low, the error amplifier responds by driving the COMP pin high, increasing the switch current. The error amplifier output is clamped internally, which functions as a switch current limit.

To increase the maximum operating switching frequency at high input voltages the TPS54240-Q1 implements a frequency shift. The switching frequency is divided by 8, 4, 2, and 1 as the voltage ramps from 0 to 0.8 V on VSENSE pin.

The device implements a digital frequency shift to enable synchronizing to an external clock during normal startup and fault conditions. Because the device can only divide the switching frequency by 8, there is a maximum input voltage limit in which the device operates and still have frequency shift protection.

During short-circuit events (particularly with high input voltage applications), the control loop has a finite minimum controllable on time and the output has a low voltage. During the switch on time, the inductor current ramps to the peak current limit because of the high input voltage and minimum on time. During the switch off time, the inductor would normally not have enough off time and output voltage for the inductor to ramp down by the ramp up amount. The frequency shift effectively increases the off time allowing the current to ramp down.

## DETAILED DESCRIPTION (continued)

### Selecting the Switching Frequency

The switching frequency that is selected should be the lower value of the two equations, Equation 12 and Equation 13. Equation 12 is the maximum switching frequency limitation set by the minimum controllable on time. Setting the switching frequency above this value causes the regulator to skip switching pulses.

Equation 13 is the maximum switching frequency limit set by the frequency shift protection. To have adequate output short circuit protection at high input voltages, the switching frequency should be set to be less than the  $f_{sw(maxshift)}$  frequency. In Equation 13, to calculate the maximum switching frequency one must take into account that the output voltage decreases from the nominal voltage to 0 V, the  $f_{div}$  integer increases from 1 to 8 corresponding to the frequency shift.

In Figure 41, the solid line illustrates a typical safe operating area regarding frequency shift and assumes the output voltage is zero volts, and the resistance of the inductor is 0.13  $\Omega$ , FET on resistance of 0.2  $\Omega$  and the diode voltage drop is 0.5 V. The dashed line is the maximum switching frequency to avoid pulse skipping. Enter these equations in a spreadsheet or other software or use the SwitcherPro design software to determine the switching frequency.

$$f_{SW(maxskip)} = \left( \frac{1}{t_{ON}} \right) \times \left( \frac{(I_L \times R_{dc} + V_{OUT} + V_d)}{(V_{IN} - I_L \times R_{hs} + V_d)} \right) \quad (12)$$

$$f_{SW(shift)} = \frac{f_{div}}{t_{ON}} \times \left( \frac{(I_L \times R_{dc} + V_{OUTSC} + V_d)}{(V_{IN} - I_L \times R_{hs} + V_d)} \right) \quad (13)$$

$I_L$	inductor current
$R_{dc}$	inductor resistance
$V_{IN}$	maximum input voltage
$V_{OUT}$	output voltage
$V_{OUTSC}$	output voltage during short
$V_d$	diode voltage drop
$R_{DS(on)}$	switch on resistance
$t_{ON}$	controllable on time
$f_{DIV}$	frequency divide equals (1, 2, 4, or 8)

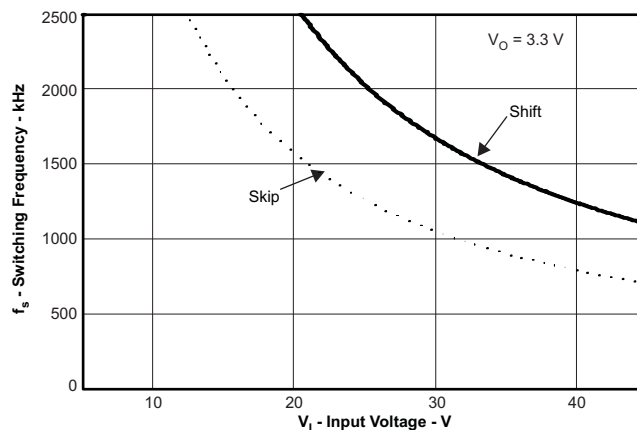


Figure 41. Maximum Switching Frequency Versus Input Voltage

## DETAILED DESCRIPTION (continued)

### How to Interface to RT/CLK Pin

The RT/CLK pin is used to synchronize the regulator to an external system clock. To implement the synchronization feature connect a square wave to the RT/CLK pin through the circuit network shown in Figure 42. The square wave amplitude must transition lower than 0.5 V and higher than 2.2 V on the RT/CLK pin and have an on time greater than 40 ns and an off time greater than 40 ns. The synchronization frequency range is 300 kHz to 2200 kHz. The rising edge of the PH is synchronized to the falling edge of RT/CLK pin signal. The external synchronization circuit should be designed in such a way that the device has the default frequency set resistor connected from the RT/CLK pin to ground should the synchronization signal turn off. TI recommends to use a frequency set resistor connected as shown in Figure 42 through a 50-Ω resistor to ground. The resistor should set the switching frequency close to the external CLK frequency. TI recommends to ac couple the synchronization signal through a 10-pF ceramic capacitor to RT/CLK pin and a 4kΩ series resistor. The series resistor reduces PH jitter in heavy load applications when synchronizing to an external clock and in applications which transition from synchronizing to RT mode. The first time the CLK is pulled above the CLK threshold the device switches from the RT resistor frequency to PLL mode. The internal 0.5-V voltage source is removed and the CLK pin becomes high impedance as the PLL starts to lock onto the external signal. Because there is a PLL on the regulator the switching frequency can be higher or lower than the frequency set with the external resistor. The device transitions from the resistor mode to the PLL mode and then increases or decreases the switching frequency until the PLL locks onto the CLK frequency within 100 ms.

When the device transitions from the PLL to resistor mode the switching frequency slows down from the CLK frequency to 150 kHz, then reapply the 0.5-V voltage and the resistor then sets the switching frequency. The switching frequency is divided by 8, 4, 2, and 1 as the voltage ramps from 0 to 0.8 V on VSENSE pin. The device implements a digital frequency shift to enable synchronizing to an external clock during normal startup and fault conditions. Figure 43, Figure 44 and Figure 45 show the device synchronized to an external system clock in continuous conduction mode (CCM) discontinuous conduction (DCM) and pulse skip mode (psm).

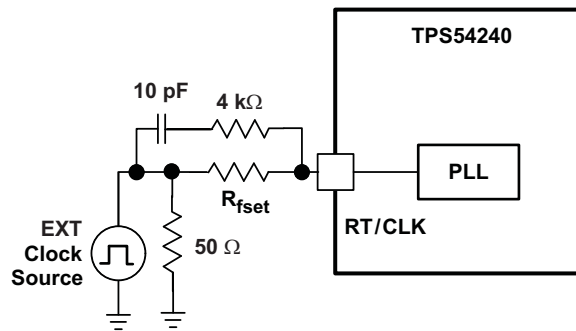


Figure 42. Synchronizing to a System Clock

DETAILED DESCRIPTION (continued)

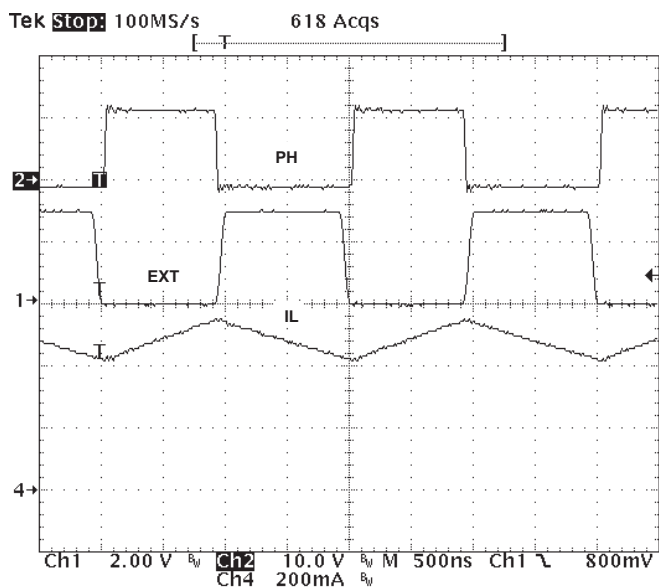


Figure 43. Plot of Synchronizing in CCM

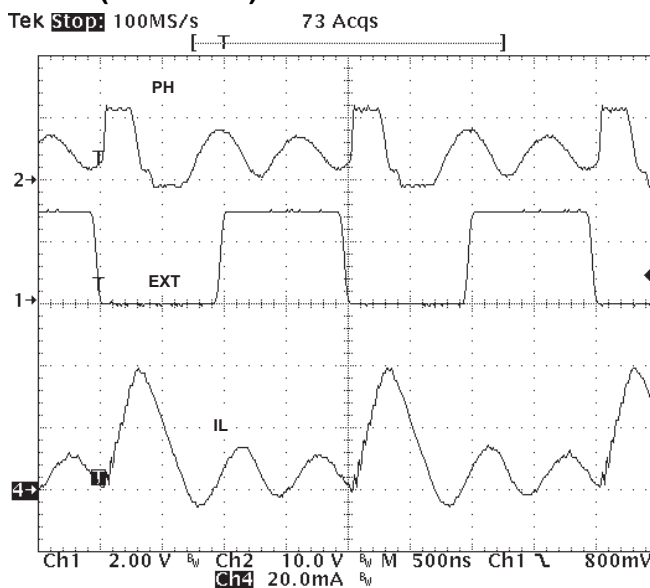


Figure 44. Plot of Synchronizing in DCM

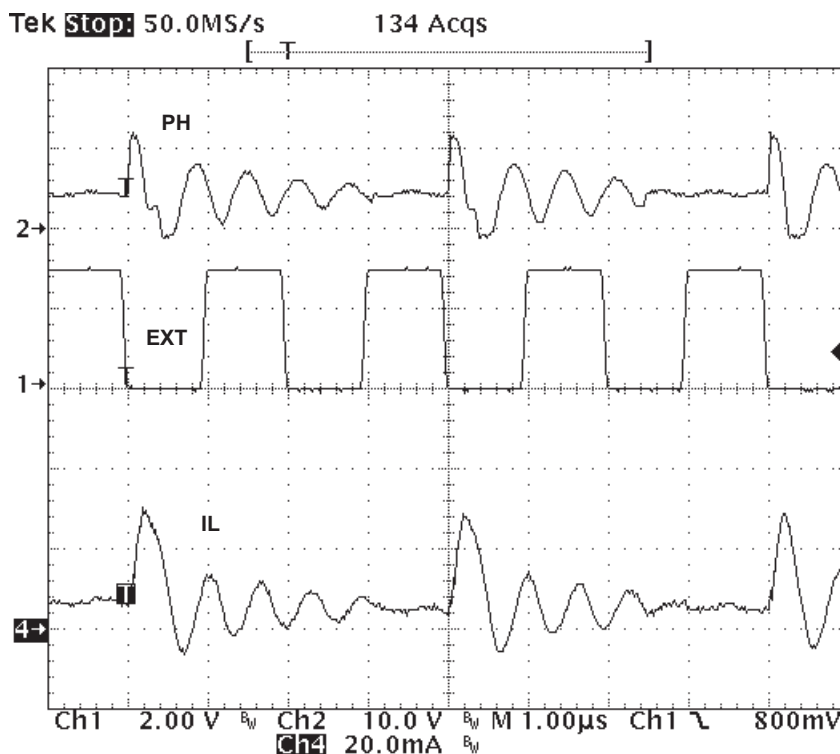


Figure 45. Plot of Synchronizing in PSM

Power Good (PWRGD Pin)

The PWRGD pin is an open drain output. Once the VSENSE pin is between 94% and 107% of the internal voltage reference the PWRGD pin is de-asserted and the pin floats. TI recommends to use a pull-up resistor between the values of 1 kΩ and 100 kΩ to a voltage source that is 5.5 V or less. The PWRGD is in a defined state once the VIN input voltage is greater than 1.5 V but with reduced current sinking capability. The PWRGD achieves full current sinking capability as VIN input voltage approaches 3 V.

### DETAILED DESCRIPTION (continued)

The PWRGD pin is pulled low when the VSENSE is lower than 92% or greater than 109% of the nominal internal reference voltage. Also, the PWRGD is pulled low, if the UVLO or thermal shutdown are asserted or the EN pin pulled low.

#### Overvoltage Transient Protection

The TPS54240-Q1 incorporates an overvoltage transient protection (OVTP) circuit to minimize voltage overshoot when recovering from output fault conditions or strong unload transients on power supply designs with low value output capacitance. For example, when the power supply output is overloaded the error amplifier compares the actual output voltage to the internal reference voltage. If the VSENSE pin voltage is lower than the internal reference voltage for a considerable time, the output of the error amplifier responds by clamping the error amplifier output to a high voltage. Thus, requesting the maximum output current. Once the condition is removed, the regulator output rises and the error amplifier output transitions to the steady state duty cycle. In some applications, the power supply output voltage can respond faster than the error amplifier output can respond, this actuality leads to the possibility of an output overshoot. The OVTP feature minimizes the output overshoot, when using a low value output capacitor, by implementing a circuit to compare the VSENSE pin voltage to OVTP threshold which is 109% of the internal voltage reference. If the VSENSE pin voltage is greater than the OVTP threshold, the high side MOSFET is disabled preventing current from flowing to the output and minimizing output overshoot. When the VSENSE voltage drops lower than the OVTP threshold, the high side MOSFET is allowed to turn on at the next clock cycle.

#### Thermal Shutdown

The device implements an internal thermal shutdown to protect itself if the junction temperature exceeds 182°C. The thermal shutdown forces the device to stop switching when the junction temperature exceeds the thermal trip threshold. Once the die temperature decreases below 182°C, the device reinitiates the power up sequence by discharging the SS/TR pin.

#### Small Signal Model for Loop Response

Figure 46 shows an equivalent model for the TPS54240-Q1 control loop which can be modeled in a circuit simulation program to check frequency response and dynamic load response. The error amplifier is a transconductance amplifier with a  $g_{mEA}$  of 310  $\mu A/V$ . The error amplifier can be modeled using an ideal voltage controlled current source. The resistor  $R_o$  and capacitor  $C_o$  model the open loop gain and frequency response of the amplifier. The 1-mV ac voltage source between the nodes a and b effectively breaks the control loop for the frequency response measurements. Plotting c/a shows the small signal response of the frequency compensation. Plotting a/b shows the small signal response of the overall loop. The dynamic loop response can be checked by replacing  $R_L$  with a current source with the appropriate load step amplitude and step rate in a time domain analysis. This equivalent model is only valid for continuous conduction mode designs.



DETAILED DESCRIPTION (continued)

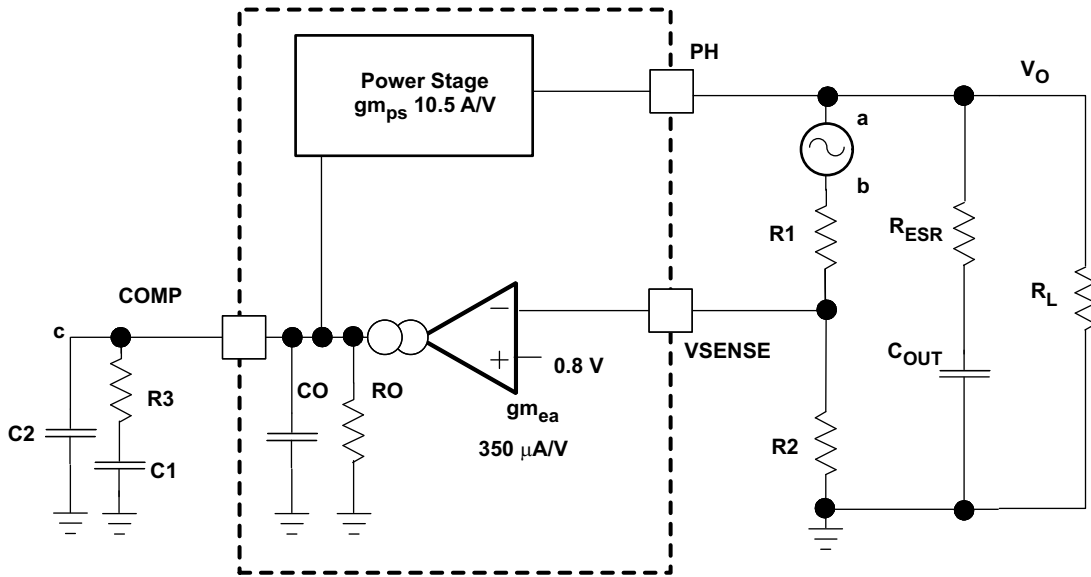


Figure 46. Small-Signal Model for Loop Response

Simple Small Signal Model for Peak Current Mode Control

Figure 47 describes a simple small signal model that can be used to understand how to design the frequency compensation. The TPS54240-Q1 power stage is approximated to a voltage-controlled current source (duty cycle modulator) supplying current to the output capacitor and load resistor. The control to output transfer function is shown in Equation 14 and consists of a dc gain, one dominant pole, and one ESR zero. The quotient of the change in switch current and the change in COMP pin voltage (node c in Figure 46) is the power stage transconductance. The  $g_{mPS}$  for the TPS54240-Q1 is 10.5 A/V. The low-frequency gain of the power stage frequency response is the product of the transconductance and the load resistance as shown in Equation 15.

As the load current increases and decreases, the low-frequency gain decreases and increases, respectively. This variation with the load may seem problematic at first glance, but fortunately the dominant pole moves with the load current (see Equation 16). The combined effect is highlighted by the dashed line in the right half of Figure 47. As the load current decreases, the gain increases and the pole frequency lowers, keeping the 0-dB crossover frequency the same for the varying load conditions which makes it easier to design the frequency compensation. The type of output capacitor chosen determines whether the ESR zero has a profound effect on the frequency compensation design. Using high ESR aluminum electrolytic capacitors may reduce the number frequency compensation components needed to stabilize the overall loop because the phase margin increases from the ESR zero at the lower frequencies (see Equation 17).

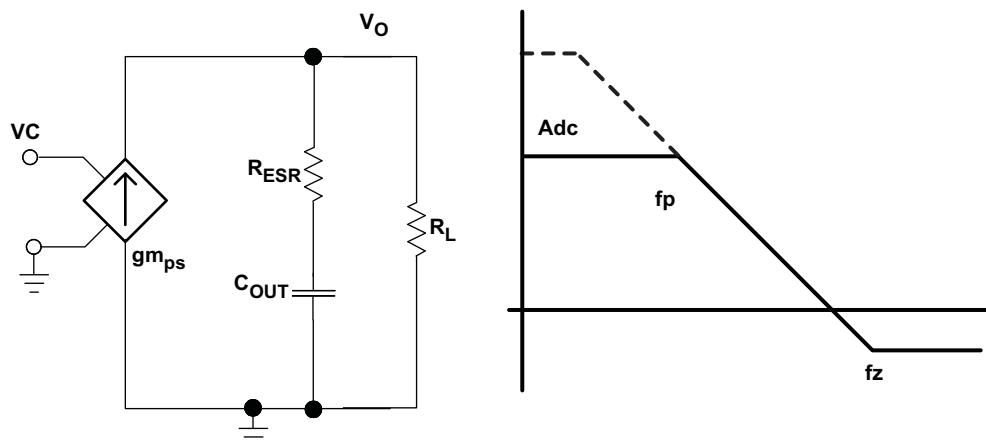


Figure 47. Simple Small-Signal Model and Frequency Response for Peak Current-Mode Control

**DETAILED DESCRIPTION (continued)**

$$\frac{V_{OUT}}{V_C} = A_{dc} \times \frac{\left(1 + \frac{s}{2\pi \times f_Z}\right)}{\left(1 + \frac{s}{2\pi \times f_P}\right)} \tag{14}$$

$$A_{dc} = g_{m_{ps}} \times R_L \tag{15}$$

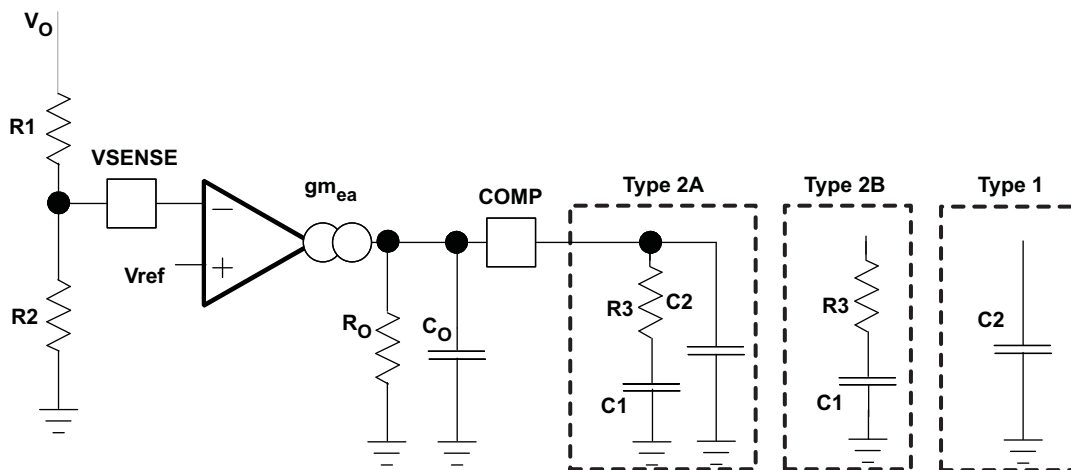
$$f_P = \frac{1}{C_{OUT} \times R_L \times 2\pi} \tag{16}$$

$$f_Z = \frac{1}{C_{OUT} \times R_{ESR} \times 2\pi} \tag{17}$$

**Small-Signal Model for Frequency Compensation**

The TPS54240-Q1 uses a transconductance amplifier for the error amplifier and readily supports three of the commonly-used frequency compensation circuits. Compensation circuits Type 2A, Type 2B, and Type 1 are shown in Figure 48. Type 2 circuits most likely implemented in high bandwidth power-supply designs using low ESR output capacitors. The Type 1 circuit is used with power-supply designs with high-ESR aluminum electrolytic or tantalum capacitors. Equation 18 and Equation 19 show how to relate the frequency response of the amplifier to the small signal model in Figure 48. The open-loop gain and bandwidth are modeled using the  $R_O$  and  $C_O$  shown in Figure 48. See the application section for a design example using a Type 2A network with a low ESR output capacitor.

Equation 18 through Equation 27 are provided as a reference for those who prefer to compensate using the preferred methods. Those who prefer to use prescribed method use the method outlined in the application section or use switched information.



**Figure 48. Types of Frequency Compensation**

DETAILED DESCRIPTION (continued)

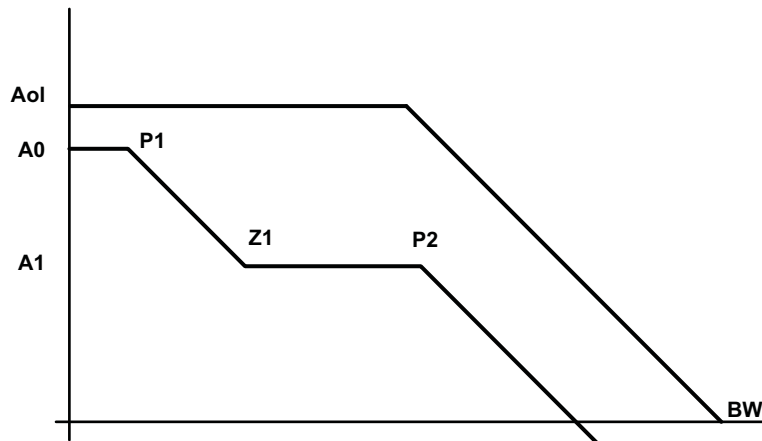


Figure 49. Frequency Response of the Type 2A and Type 2B Frequency Compensation

$$R_o = \frac{A_{ol}(V/V)}{g_{m_{ea}}} \quad (18)$$

$$C_o = \frac{g_{m_{ea}}}{2\pi \times BW \text{ (Hz)}} \quad (19)$$

$$EA = A_0 \times \frac{\left(1 + \frac{s}{2\pi \times f_{Z1}}\right)}{\left(1 + \frac{s}{2\pi \times f_{P1}}\right) \times \left(1 + \frac{s}{2\pi \times f_{P2}}\right)} \quad (20)$$

$$A_0 = g_{m_{ea}} \times R_o \times \frac{R_2}{R_1 + R_2} \quad (21)$$

$$A_1 = g_{m_{ea}} \times R_o || R_3 \times \frac{R_2}{R_1 + R_2} \quad (22)$$

$$P_1 = \frac{1}{2\pi \times R_o \times C_1} \quad (23)$$

$$Z_1 = \frac{1}{2\pi \times R_3 \times C_1} \quad (24)$$

$$P_2 = \frac{1}{2\pi \times R_3 || R_o \times (C_2 + C_o)} \text{ type 2a} \quad (25)$$

$$P_2 = \frac{1}{2\pi \times R_3 || R_o \times C_o} \text{ type 2b} \quad (26)$$

$$P_2 = \frac{1}{2\pi \times R_o \times (C_2 + C_o)} \text{ type 1} \quad (27)$$

## APPLICATION INFORMATION

### Design Guide — Step-By-Step Design Procedure

This example details the design of a high frequency switching regulator design using ceramic output capacitors. A few parameters must be known in order to start the design process. These parameters are typically determined at the system level. For this example, use the following known parameters:

Output Voltage	3.3 V
Transient Response 0- to 1.5-A load step	$\Delta V_{out} = 3\%$
Maximum Output Current	2.5 A
Input Voltage	12 V (nom) 10.8 V to 13.2 V
Output Voltage Ripple	1% of $V_{out}$
Start Input Voltage (rising $V_{IN}$ )	6 V
Stop Input Voltage (falling $V_{IN}$ )	5.5 V

### Selecting the Switching Frequency

The first step is to decide on a switching frequency for the regulator. Typically, the user chooses the highest switching frequency possible because it produces the smallest solution size. The high switching frequency allows for lower valued inductors and smaller output capacitors compared to a power supply that switches at a lower frequency. The switching frequency that can be selected is limited by the minimum on-time of the internal power switch, the input voltage and the output voltage and the frequency shift limitation.

[Equation 12](#) and [Equation 13](#) must be used to find the maximum switching frequency for the regulator, choose the lower value of the two equations. Switching frequencies higher than these values result in pulse skipping or the lack of overcurrent protection during a short circuit.

The typical minimum on time,  $t_{onmin}$ , is 135 ns for the TPS54240-Q1. For this example, the output voltage is 3.3 V and the maximum input voltage is 13.2 V, which allows for a maximum switch frequency up to 2247 kHz when including the inductor resistance, on resistance output current and diode voltage in [Equation 12](#). To ensure overcurrent runaway is not a concern during short circuits in your design use [Equation 13](#) or the solid curve in [Figure 41](#) to determine the maximum switching frequency. With a maximum input voltage of 13.2 V, assuming a diode voltage of 0.7 V, inductor resistance of 26 m $\Omega$ , switch resistance of 200 m $\Omega$ , a current limit value of 3.5 A and a short circuit output voltage of 0.2 V. The maximum switching frequency is approximately 4449 kHz.

For this design, a much lower switching frequency of 300 kHz is used. To determine the timing resistance for a given switching frequency, use [Equation 11](#) or the curve in [Figure 40](#).

The switching frequency is set by resistor  $R_3$  shown in [Figure 50](#) For 300 kHz operation a 412 k $\Omega$  resistor is required.

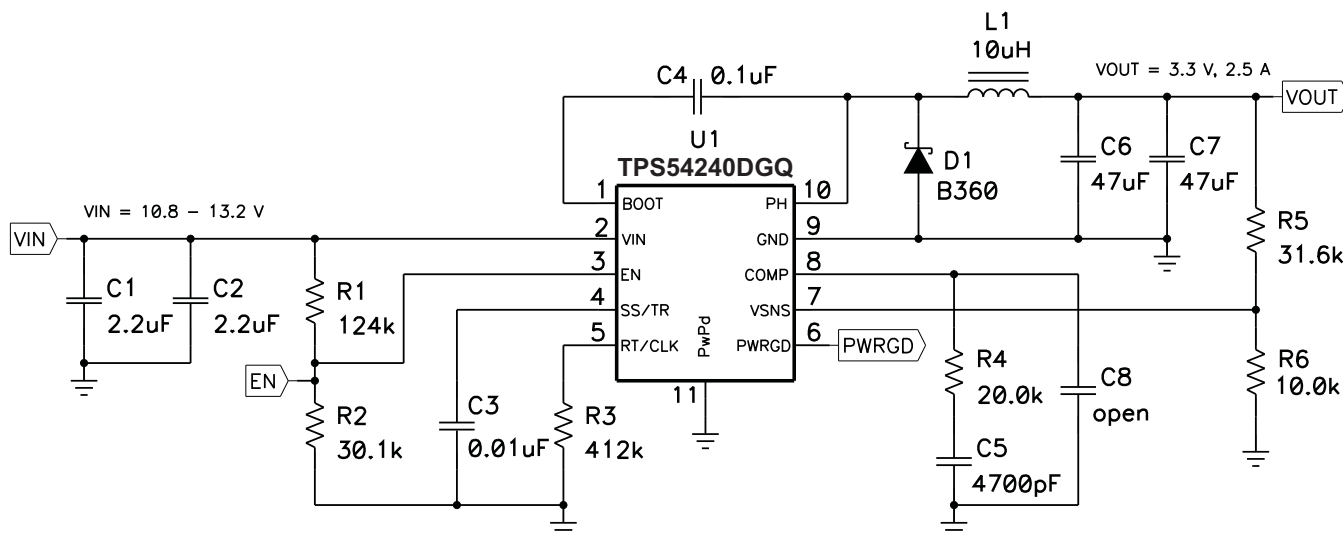


Figure 50. 3.3-V Output TPS54240-Q1 Design Example.

### Output Inductor Selection ( $L_o$ )

To calculate the minimum value of the output inductor, use [Equation 28](#).

$K_{IND}$  is a coefficient that represents the amount of inductor ripple current relative to the maximum output current.

The inductor ripple current is filtered by the output capacitor. Therefore, choosing high inductor ripple currents impact the selection of the output capacitor because the output capacitor must have a ripple current rating equal to or greater than the inductor ripple current. In general, the inductor ripple value is at the discretion of the designer; however, the following guidelines may be used.

For designs using low ESR output capacitors such as ceramics, a value as high as  $K_{IND} = 0.3$  may be used. When using higher ESR output capacitors,  $K_{IND} = 0.2$  yields better results. Because the inductor ripple current is part of the PWM control system, the inductor ripple current should always be greater than 150 mA for dependable operation. In a wide input voltage regulator, it is best to choose an inductor ripple current on the larger side. This allows the inductor to still have a measurable ripple current with the input voltage at its minimum.

For this design example, use  $K_{IND} = 0.3$  and the minimum inductor value is calculated to be 11  $\mu\text{H}$ . For this design, a nearest standard value was chosen: 10  $\mu\text{H}$ . For the output filter inductor, it is important that the RMS current and saturation current ratings not be exceeded. The RMS and peak inductor current can be found from [Equation 30](#) and [Equation 31](#).

For this design, the RMS inductor current is 2.51 A and the peak inductor current is 2.913 A. The chosen inductor is a Coilcraft MSS1038-103NLB . It has a saturation current rating of 4.52 A and an RMS current rating of 4.05 A.

As the equation set demonstrates, lower ripple currents reduce the output voltage ripple of the regulator but require a larger value of inductance. Selecting higher ripple currents increases the output voltage ripple of the regulator but allow for a lower inductance value.

The current flowing through the inductor is the inductor ripple current plus the output current. During power up, faults or transient load conditions, the inductor current can increase above the calculated peak inductor current level calculated above. In transient conditions, the inductor current can increase up to the switch current limit of the device. For this reason, the most conservative approach is to specify an inductor with a saturation current rating equal to or greater than the switch current limit rather than the peak inductor current.

$$L_o \text{ min} = \frac{V_{in\text{max}} - V_{out}}{I_o \times K_{IND}} \times \frac{V_{out}}{V_{in\text{max}} \times f_{sw}} \quad (28)$$

$$I_{\text{RIPPLE}} = \frac{V_{\text{OUT}} \times (V_{\text{inmax}} - V_{\text{OUT}})}{V_{\text{inmax}} \times L_{\text{O}} \times f_{\text{SW}}} \quad (29)$$

$$I_{\text{L(rms)}} = \sqrt{(I_{\text{O}})^2 + \frac{1}{12} \times \left( \frac{V_{\text{OUT}} \times (V_{\text{inmax}} - V_{\text{OUT}})}{V_{\text{inmax}} \times L_{\text{O}} \times f_{\text{SW}}} \right)^2} \quad (30)$$

$$I_{\text{Lpeak}} = I_{\text{out}} + \frac{I_{\text{ripple}}}{2} \quad (31)$$

## Output Capacitor

There are three primary considerations for selecting the value of the output capacitor. The output capacitor determines the modulator pole, the output voltage ripple, and how the regulators responds to a large change in load current. The output capacitance needs to be selected based on the more stringent of these three criteria.

The desired response to a large change in the load current is the first criteria. The output capacitor needs to supply the load with current when the regulator can not. This situation would occur if there are desired hold-up times for the regulator where the output capacitor must hold the output voltage above a certain level for a specified amount of time after the input power is removed. The regulator also is temporarily not able to supply sufficient output current if there is a large, fast increase in the current needs of the load such as transitioning from no load to a full load. The regulator usually needs two or more clock cycles for the control loop to see the change in load current and output voltage and adjust the duty cycle to react to the change. The output capacitor must be sized to supply the extra current to the load until the control loop responds to the load change. The output capacitance must be large enough to supply the difference in current for two clock cycles while only allowing a tolerable amount of droop in the output voltage. Equation 32 shows the minimum output capacitance necessary to accomplish this.

Where  $\Delta I_{\text{out}}$  is the change in output current,  $f_{\text{sw}}$  is the regulators switching frequency and  $\Delta V_{\text{out}}$  is the allowable change in the output voltage. For this example, the transient load response is specified as a 3% change in  $V_{\text{out}}$  for a load step from 1.5 A to 2.5 A (full load). For this example,  $\Delta I_{\text{out}} = 2.5 - 1.5 = 1$  A and  $\Delta V_{\text{out}} = 0.03 \times 3.3 = 0.099$  V. Using these numbers gives a minimum capacitance of 67  $\mu\text{F}$ . This value does not take the ESR of the output capacitor into account in the output voltage change. For ceramic capacitors, the ESR is usually small enough to ignore in this calculation. Aluminum electrolytic and tantalum capacitors have higher ESR that should be taken into account.

The catch diode of the regulator can not sink current so any stored energy in the inductor produces an output voltage overshoot when the load current rapidly decreases, see Figure 51. The output capacitor must also be sized to absorb energy stored in the inductor when transitioning from a high load current to a lower load current. The excess energy that gets stored in the output capacitor increases the voltage on the capacitor. The capacitor must be sized to maintain the desired output voltage during these transient periods. Equation 33 is used to calculate the minimum capacitance to keep the output voltage overshoot to a desired value. Where  $L$  is the value of the inductor,  $I_{\text{OH}}$  is the output current under heavy load,  $I_{\text{OL}}$  is the output under light load,  $V_{\text{f}}$  is the final peak output voltage, and  $V_{\text{i}}$  is the initial capacitor voltage. For this example, the worst case load step is from 2.5 A to 1.5 A. The output voltage increases during this load transition and the stated maximum in our specification is 3% of the output voltage. This makes  $V_{\text{f}} = 1.03 \times 3.3 = 3.399$ .  $V_{\text{i}}$  is the initial capacitor voltage which is the nominal output voltage of 3.3 V. Using these numbers in Equation 33 yields a minimum capacitance of 60  $\mu\text{F}$ .

Equation 34 calculates the minimum output capacitance needed to meet the output voltage ripple specification. Where  $f_{\text{sw}}$  is the switching frequency,  $V_{\text{ripple}}$  is the maximum allowable output voltage ripple, and  $I_{\text{ripple}}$  is the inductor ripple current. Equation 34 yields 12  $\mu\text{F}$ .

Equation 35 calculates the maximum ESR an output capacitor can have to meet the output voltage ripple specification. Equation 35 indicates the ESR should be less than 36 m $\Omega$ .

The most stringent criteria for the output capacitor is 67  $\mu\text{F}$  of capacitance to keep the output voltage in regulation during an load transient.

Additional capacitance de-ratings for aging, temperature and dc bias should be factored in which increases this minimum value. For this example,  $2 \times 47$   $\mu\text{F}$ , 10 V ceramic capacitors with 3 m $\Omega$  of ESR is used. The derated capacitance is 72.4  $\mu\text{F}$ , above the minimum required capacitance of 67  $\mu\text{F}$ .

Capacitors generally have limits to the amount of ripple current they can handle without failing or producing excess heat. An output capacitor that can support the inductor ripple current must be specified. Some capacitor data sheets specify the Root Mean Square (RMS) value of the maximum ripple current. Equation 36 can be used to calculate the RMS ripple current the output capacitor needs to support. For this application, Equation 36 yields 238 mA.

$$C_{out} = \frac{2 \times \Delta I_{out}}{f_{sw} \times \Delta V_{out}} \quad (32)$$

$$C_{out} > L_o \times \frac{((I_{oh})^2 - (I_{ol})^2)}{(V_f)^2 - (V_i)^2} \quad (33)$$

$$C_{out} > \frac{1}{8 \times f_{sw}} \times \frac{1}{\frac{V_{ORIPPLE}}{I_{RIPPLE}}} \quad (34)$$

$$R_{ESR} < \frac{V_{ORIPPLE}}{I_{RIPPLE}} \quad (35)$$

$$I_{corms} = \frac{V_{out} \times (V_{in\ max} - V_{out})}{\sqrt{12} \times V_{in\ max} \times L_o \times f_{sw}} \quad (36)$$

### Catch Diode

The TPS54240-Q1 requires an external catch diode between the PH pin and GND. The selected diode must have a reverse voltage rating equal to or greater than  $V_{inmax}$ . The peak current rating of the diode must be greater than the maximum inductor current. The diode should also have a low forward voltage. Schottky diodes are typically a good choice for the catch diode due to their low forward voltage. The lower the forward voltage of the diode, the higher the efficiency of the regulator.

Typically, the higher the voltage and current ratings the diode has, the higher the forward voltage is. Although the design example has an input voltage up to 13.2 V, a diode with a minimum of 60-V reverse voltage is selected.

For the example design, the B360B-13-F Schottky diode is selected for its lower forward voltage and it comes in a larger package size which has good thermal characteristics over small devices. The typical forward voltage of the B360B-13-F is 0.70 volts.

The diode must also be selected with an appropriate power rating. The diode conducts the output current during the off-time of the internal power switch. The off-time of the internal switch is a function of the maximum input voltage, the output voltage, and the switching frequency. The output current during the off-time is multiplied by the forward voltage of the diode which equals the conduction losses of the diode. At higher switch frequencies, the ac losses of the diode need to be taken into account. The ac losses of the diode are due to the charging and discharging of the junction capacitance and reverse recovery. Equation 37 is used to calculate the total power dissipation, conduction losses plus ac losses, of the diode.

The B360B-13-F has a junction capacitance of 200 pF. Using Equation 37, the selected diode dissipates 1.32 Watts.

If the power supply spends a significant amount of time at light load currents or in sleep mode consider using a diode which has a low leakage current and slightly higher forward voltage drop.

$$P_d = \frac{(V_{in\ max} - V_{out}) \times I_{out} \times V_{fd}}{V_{in\ max}} + \frac{C_j \times f_{sw} \times (V_{in} + V_{fd})^2}{2} \quad (37)$$

### Input Capacitor

The TPS54240-Q1 requires a high quality ceramic, type X5R or X7R, input decoupling capacitor of at least 3  $\mu$ F of effective capacitance and in some applications a bulk capacitance. The effective capacitance includes any dc bias effects. The voltage rating of the input capacitor must be greater than the maximum input voltage. The capacitor must also have a ripple current rating greater than the maximum input current ripple of the TPS54240-Q1. The input ripple current can be calculated using Equation 38.

The value of a ceramic capacitor varies significantly over temperature and the amount of dc bias applied to the capacitor. The capacitance variations due to temperature can be minimized by selecting a dielectric material that is stable over temperature. X5R and X7R ceramic dielectrics are usually selected for power regulator capacitors because they have a high capacitance to volume ratio and are fairly stable over temperature. The output capacitor must also be selected with the dc bias taken into account. The capacitance value of a capacitor decreases as the dc bias across a capacitor increases.

For this example design, a ceramic capacitor with at least a 60-V voltage rating is required to support the maximum input voltage. Common standard ceramic capacitor voltage ratings include 4 V, 6.3 V, 10 V, 16 V, 25 V, 50 V or 100 V so a 100-V capacitor should be selected. For this example, two 2.2-μF 100-V capacitors in parallel have been selected. Table 1 shows a selection of high voltage capacitors. The input capacitance value determines the input ripple voltage of the regulator. The input voltage ripple can be calculated using Equation 39. Using the design example values, I<sub>outmax</sub> = 2.5 A, C<sub>in</sub> = 4.4μF, f<sub>sw</sub> = 300 kHz, yields an input voltage ripple of 206 mV and a rms input ripple current of 1.15 A.

$$I_{cirms} = I_{out} \times \sqrt{\frac{V_{out}}{V_{in\ min}} \times \frac{(V_{in\ min} - V_{out})}{V_{in\ min}}} \tag{38}$$

$$\Delta V_{in} = \frac{I_{out\ max} \times 0.25}{C_{in} \times f_{sw}} \tag{39}$$

**Table 1. Capacitor Types**

VENDOR	VALUE (μF)	EIA Size	VOLTAGE	DIELECTRIC	COMMENTS	
Murata	1 to 2.2	1210	100 V	X7R	GRM32 series	
	1 to 4.7		50 V			
	1	1206	100 V		GRM31 series	
	1 to 2.2		50 V			
Vishay	1 10 1.8	2220	50 V		VJ X7R series	
	1 to 1.2		100 V			
	1 to 3.9	2225	50 V			
	1 to 1.8		100 V			
TDK	1 to 2.2	1812	100 V			C series C4532
	1.5 to 6.8		50 V			
	1 to 2.2	1210	100 V			C series C3225
	1 to 3.3		50 V			
AVX	1 to 4.7	1210	50 V	X7R dielectric series		
	1		100 V			
	1 to 4.7	1812	50 V			
	1 to 2.2		100 V			

### Slow-Start Capacitor

The slow-start capacitor determines the minimum amount of time it takes for the output voltage to reach its nominal programmed value during power up. This is useful if a load requires a controlled voltage slew rate. This is also used if the output capacitance is large and would require large amounts of current to quickly charge the capacitor to the output voltage level. The large currents necessary to charge the capacitor may make the TPS54240-Q1 reach the current limit or excessive current draw from the input power supply may cause the input voltage rail to sag. Limiting the output voltage slew rate solves both of these problems.

The slow start time must be long enough to allow the regulator to charge the output capacitor up to the output voltage without drawing excessive current. Equation 40 can be used to find the minimum slow start time, t<sub>ss</sub>, necessary to charge the output capacitor, C<sub>out</sub>, from 10% to 90% of the output voltage, V<sub>out</sub>, with an average slow start current of I<sub>ssavg</sub>. In the example, to charge the effective output capacitance of 72.4 μF up to 3.3 V while only allowing the average output current to be 1 A would require a 0.19 ms slow start time.



Once the slow start time is known, the slow start capacitor value can be calculated using [Equation 6](#). For the example circuit, the slow start time is not too critical because the output capacitor value is  $2 \times 47\mu\text{F}$  which does not require much current to charge to 3.3 V. The example circuit has the slow start time set to an arbitrary value of 3.5 ms which requires a 8.75 nF slow start capacitor. For this design, the next larger standard value of 10 nF is used.

$$T_{ss} > \frac{C_{out} \times V_{out} \times 0.8}{I_{ssavg}} \quad (40)$$

### Bootstrap Capacitor Selection

A 0.1- $\mu\text{F}$  ceramic capacitor must be connected between the BOOT and PH pins for proper operation. TI recommends to use a ceramic capacitor with X5R or better grade dielectric. The capacitor should have a 10 V or higher voltage rating.

### Undervoltage Lockout Set Point

The Under Voltage Lock Out (UVLO) can be adjusted using an external voltage divider on the EN pin of the TPS54240-Q1. The UVLO has two thresholds, one for power up when the input voltage is rising and one for power down or brown outs when the input voltage is falling. For the example design, the supply should turn on and start switching once the input voltage increases above 6 V (enabled). After the regulator starts switching, it should continue to do so until the input voltage falls below 5.5 V (UVLO stop).

The programmable UVLO and enable voltages are set using the resistor divider of R1 and R2 between  $V_{in}$  and ground to the EN pin. [Equation 2](#) through [Equation 3](#) can be used to calculate the resistance values necessary. For the example application, a 124 k $\Omega$  between  $V_{in}$  and EN (R1) and a 30.1 k $\Omega$  between EN and ground (R2) are required to produce the 6 and 5.5 volt start and stop voltages.

### Output Voltage and Feedback Resistors Selection

The voltage divider of R5 and R6 is used to set the output voltage. For the example design, 10 k $\Omega$  was selected for R6. Using [Equation 1](#), R5 is calculated as 31.25 k $\Omega$ . The nearest standard 1% resistor is 31.6 k $\Omega$ . Due to current leakage of the VSENSE pin, the current flowing through the feedback network should be greater than 1  $\mu\text{A}$  in order to maintain the output voltage accuracy. This requirement makes the maximum value of R2 equal to 800 k $\Omega$ . Choosing higher resistor values decrease quiescent current and improve efficiency at low output currents but may introduce noise immunity problems.

### Compensation

There are several methods used to compensate DC/DC regulators. The method presented here is easy to calculate and ignores the effects of the slope compensation that is internal to the device. Because the slope compensation is ignored, the actual cross over frequency is usually lower than the cross over frequency used in the calculations. This method assumes the crossover frequency is between the modulator pole and the esr zero and the esr zero is at least 10 times greater the modulator pole. Use SwitcherPro software for a more accurate design.

To get started, the modulator pole,  $f_{pmod}$ , and the esr zero,  $f_{z1}$  must be calculated using [Equation 41](#) and [Equation 42](#). For  $C_{out}$ , use a derated value of 40  $\mu\text{F}$ . Use equations [Equation 43](#) and [Equation 44](#), to estimate a starting point for the crossover frequency,  $f_{co}$ , to design the compensation. For the example design,  $f_{pmod}$  is 1206 Hz and  $f_{zmod}$  is 530.5 kHz. [Equation 43](#) is the geometric mean of the modulator pole and the ESR zero and [Equation 44](#) is the mean of modulator pole and the switching frequency. [Equation 43](#) yields 25.3 kHz and [Equation 44](#) gives 13.4 kHz. Use the lower value of [Equation 43](#) or [Equation 44](#) for an initial crossover frequency. For this example, a higher  $f_{co}$  is desired to improve transient response. the target  $f_{co}$  is 35.0 kHz. Next, the compensation components are calculated. A resistor in series with a capacitor is used to create a compensating zero. A capacitor in parallel to these two components forms the compensating pole.

$$f_{p\ mod} = \frac{I_{outmax}}{2 \times \pi \times V_{out} \times C_{out}} \quad (41)$$

$$f_{z\ mod} = \frac{1}{2 \times \pi \times R_{esr} \times C_{out}} \quad (42)$$

$$f_{co} = \sqrt{f_{p\ mod} \times f_{z\ mod}} \quad (43)$$

$$f_{co} = \sqrt{f_p \text{ mod} \times \frac{f_{sw}}{2}} \quad (44)$$

To determine the compensation resistor, R4, use [Equation 45](#). Assume the power stage transconductance,  $g_{mps}$ , is 10.5 A/V. The output voltage,  $V_o$ , reference voltage,  $V_{REF}$ , and amplifier transconductance,  $g_{mea}$ , are 3.3 V, 0.8 V and 310  $\mu\text{A/V}$ , respectively. R4 is calculated to be 20.2 k $\Omega$ , use the nearest standard value of 20 k $\Omega$ . Use [Equation 46](#) to set the compensation zero to the modulator pole frequency. [Equation 46](#) yields 4740 pF for compensating capacitor C5, a 4700 pF is used for this design.

$$R4 = \left( \frac{2 \times \pi \times f_{co} \times C_{out}}{g_{mps}} \right) \times \left( \frac{V_{out}}{V_{ref} \times g_{mea}} \right) \quad (45)$$

$$C5 = \frac{1}{2 \times \pi \times R4 \times f_p \text{ mod}} \quad (46)$$

A compensation pole can be implemented if desired using an additional capacitor C8 in parallel with the series combination of R4 and C5. Use the larger value of [Equation 47](#) and [Equation 48](#) to calculate the C8, to set the compensation pole. C8 is not used for this design example.

$$C8 = \frac{C_o \times R_{esr}}{R4} \quad (47)$$

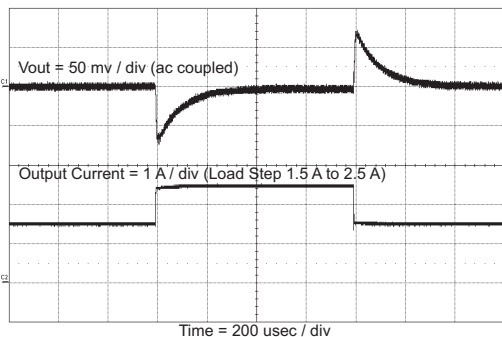
$$C8 = \frac{1}{R4 \times f_{sw} \times \pi} \quad (48)$$

### Discontinuous Mode and Eco-mode Boundary

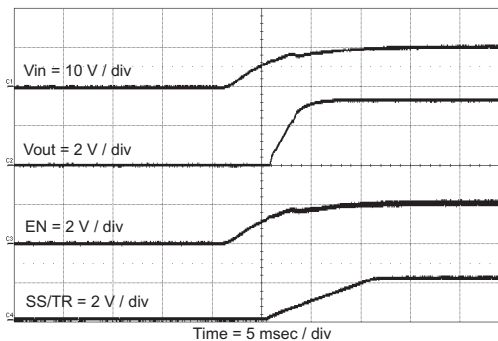
With an input voltage of 12 V, the power supply enters discontinuous mode when the output current is less than 337 mA. The power supply enters Eco-mode when the output current is lower than 5 mA.

The input current draw at no load is 392  $\mu\text{A}$ .

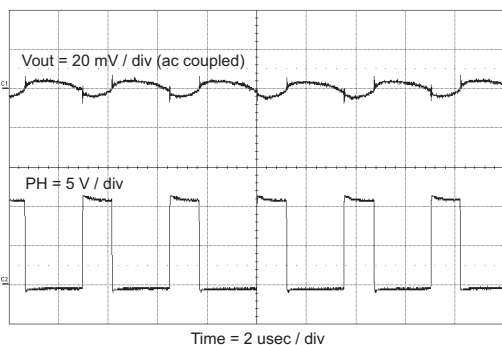
**APPLICATION CURVES**



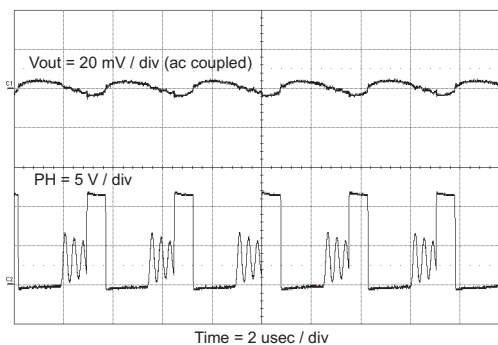
**Figure 51. Load Transient**



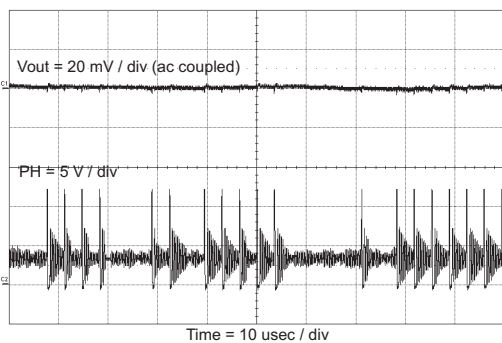
**Figure 52. Startup With VIN**



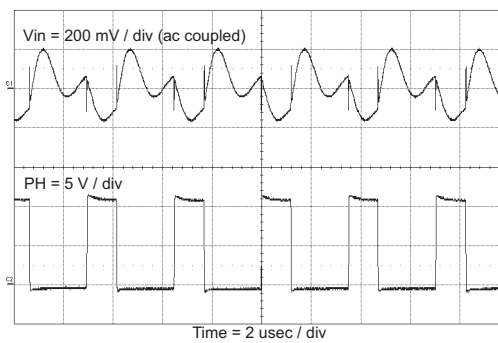
**Figure 53. Output Ripple, CCM**



**Figure 54. Output Ripple, DCM**



**Figure 55. Output Ripple, PSM**



**Figure 56. Input Ripple, CCM**

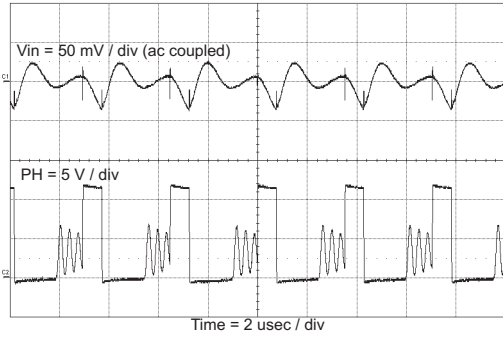


Figure 57. Input Ripple, DCM

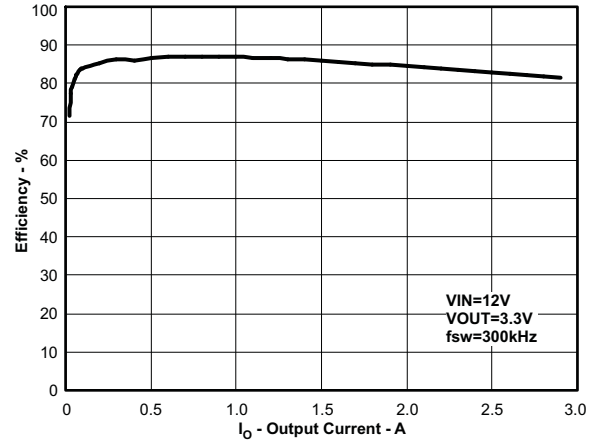


Figure 58. Efficiency Versus Load Current

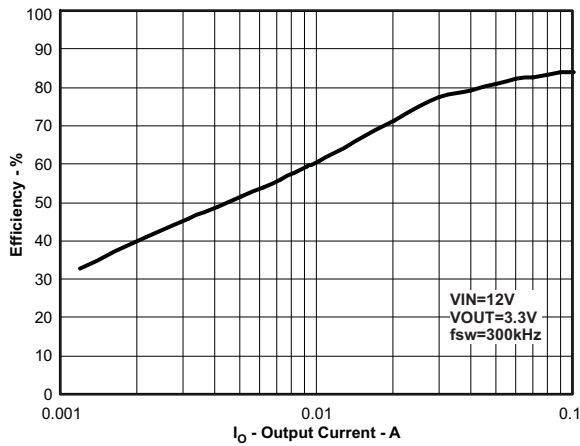


Figure 59. Light-Load Efficiency

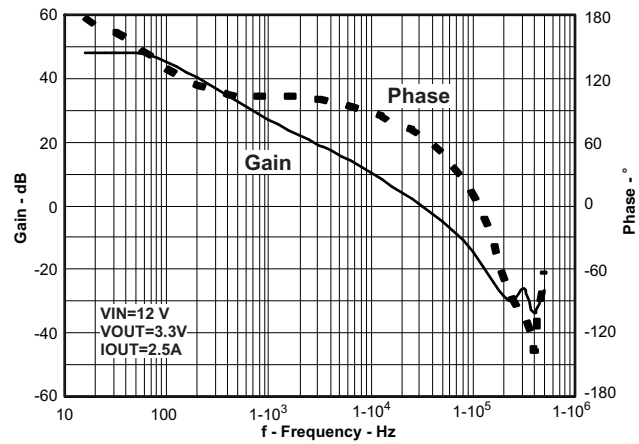


Figure 60. Overall Loop-Frequency Response

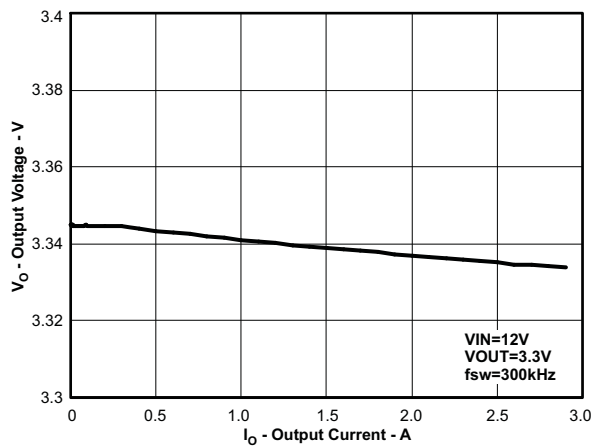


Figure 61. Regulation Versus Load Current

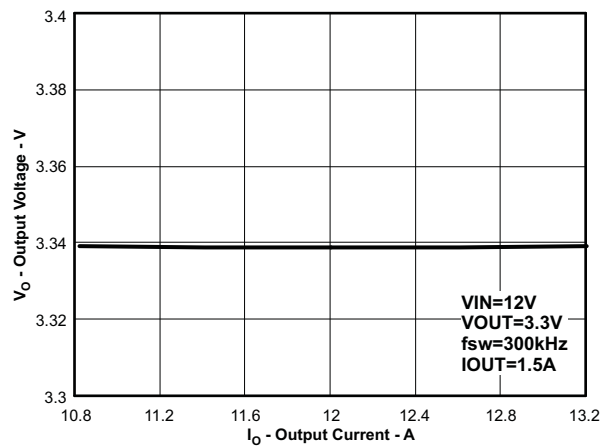


Figure 62. Regulation Versus Input Voltage

## Power-Dissipation Estimate

The following formulas show how to estimate the IC power dissipation under continuous conduction mode (CCM) operation. These equations should not be used if the device is working in discontinuous conduction mode (DCM).

The power dissipation of the IC includes conduction loss (Pcon), switching loss (Psw), gate drive loss (Pgd) and supply current (Pq).

$$P_{con} = I_o^2 \times R_{DS(on)} \times \frac{V_{out}}{V_{in}} \quad (49)$$

$$P_{sw} = V_{in}^2 \times f_{sw} \times I_o \times 0.25 \times 10^{-9} \quad (50)$$

$$P_{gd} = V_{in} \times 3 \times 10^{-9} \times f_{sw} \quad (51)$$

$$P_q = 116 \times 10^{-6} \times V_{in}$$

Where:

- IO<sub>UT</sub> is the output current (A)
  - R<sub>DS(on)</sub> is the on-resistance of the high-side MOSFET (Ω)
  - V<sub>OUT</sub> is the output voltage (V)
  - V<sub>IN</sub> is the input voltage (V)
  - f<sub>sw</sub> is the switching frequency (Hz)
- (52)

So

$$P_{tot} = P_{con} + P_{sw} + P_{gd} + P_q \quad (53)$$

For given T<sub>A</sub>,

$$T_J = T_A + R_{th} \times P_{tot} \quad (54)$$

For given T<sub>JMAX</sub> = 150°C

$$T_{Amax} = T_{Jmax} - R_{th} \times P_{tot}$$

Where:

- P<sub>tot</sub> is the total device power dissipation (W)
  - T<sub>A</sub> is the ambient temperature (°C)
  - T<sub>J</sub> is the junction temperature (°C)
  - R<sub>th</sub> is the thermal resistance of the package (°C/W)
  - T<sub>JMAX</sub> is maximum junction temperature (°C)
  - T<sub>AMAX</sub> is maximum ambient temperature (°C)
- (55)

There is additional power losses in the regulator circuit due to the inductor ac and dc losses, the catch diode and trace resistance that impacts the overall efficiency of the regulator.

### Layout

Layout is a critical portion of good power supply design. There are several signals paths that conduct fast changing currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise or degrade the power supplies performance. To help eliminate these problems, the VIN pin should be bypassed to ground with a low ESR ceramic bypass capacitor with X5R or X7R dielectric. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the VIN pin, and the anode of the catch diode. See Figure 63 for a PCB layout example. The GND pin should be tied directly to the power pad under the IC and the power pad.

The power pad should be connected to any internal PCB ground planes using multiple vias directly under the IC. The PH pin should be routed to the cathode of the catch diode and to the output inductor. Because the PH connection is the switching node, the catch diode and output inductor should be located close to the PH pins, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. For operation at full rated load, the top side ground area must provide adequate heat dissipating area. The RT/CLK pin is sensitive to noise so the RT resistor should be located as close as possible to the IC and routed with minimal lengths of trace. The additional external components can be placed approximately as shown. It may be possible to obtain acceptable performance with alternate PCB layouts, however this layout has been shown to produce good results and is meant as a guideline.

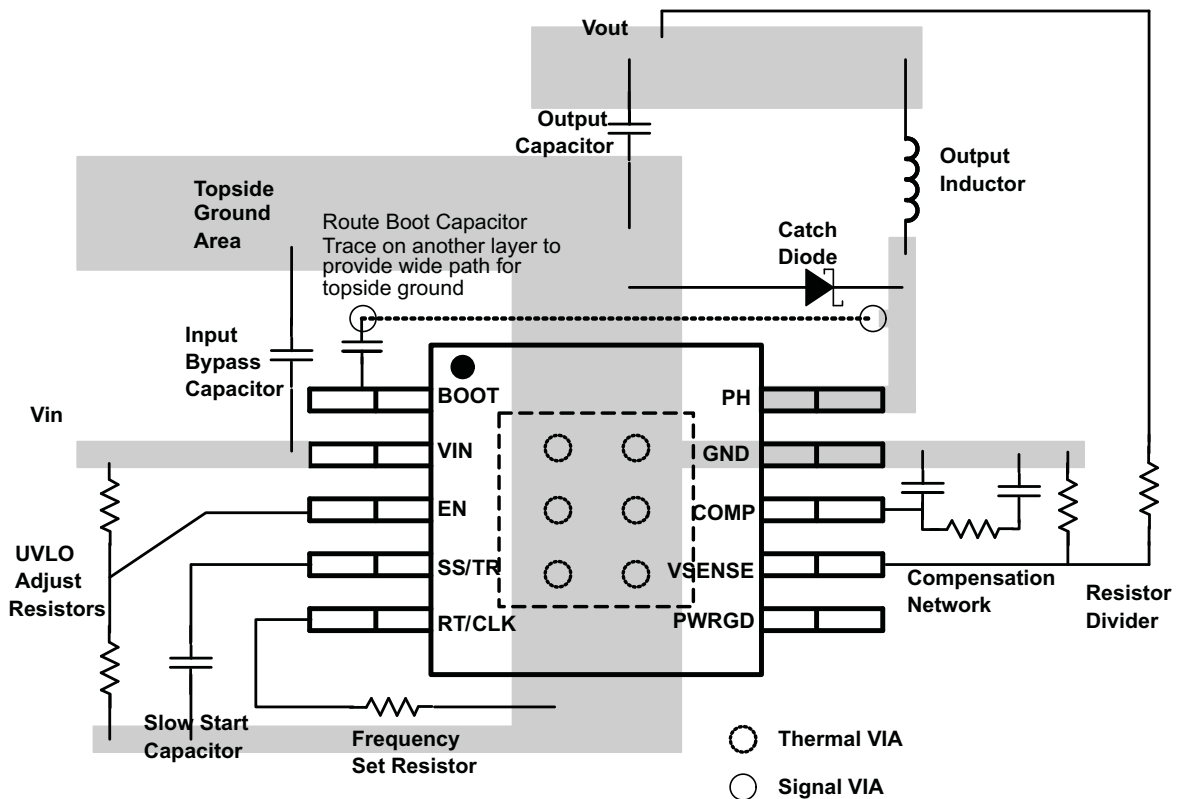


Figure 63. PCB Layout Example

### Estimated Circuit Area

The estimated printed circuit board area for the components used in the design of [Figure 50](#) is 0.55 in<sup>2</sup>. This area does not include test points or connectors.

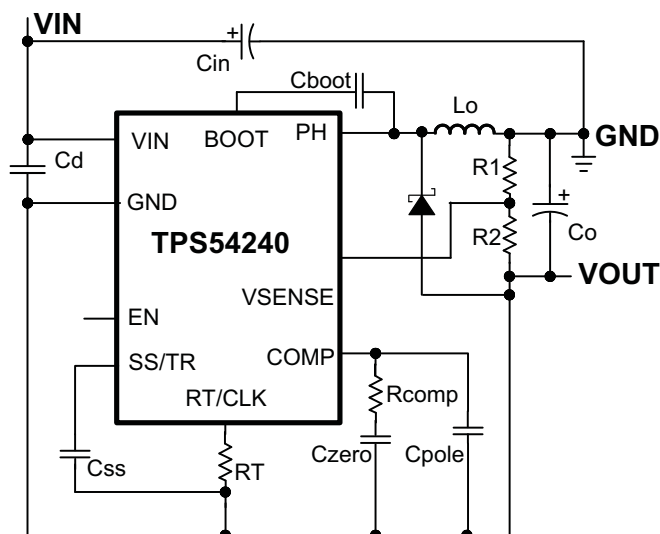


Figure 64. TPS54240-Q1 Inverting Power Supply from Application Note [SLVA317](#)

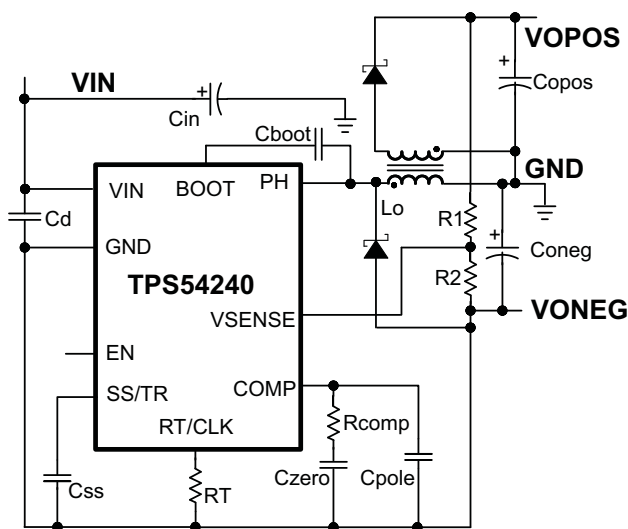
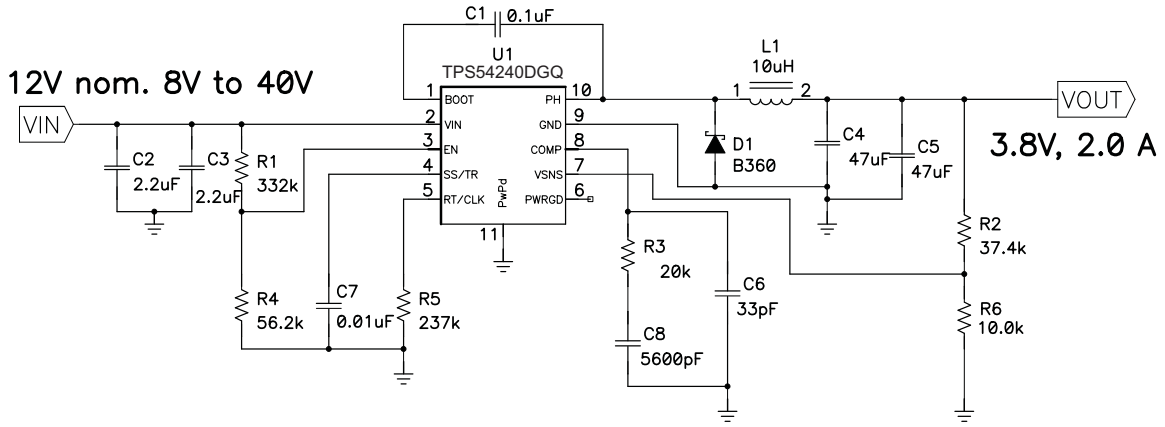
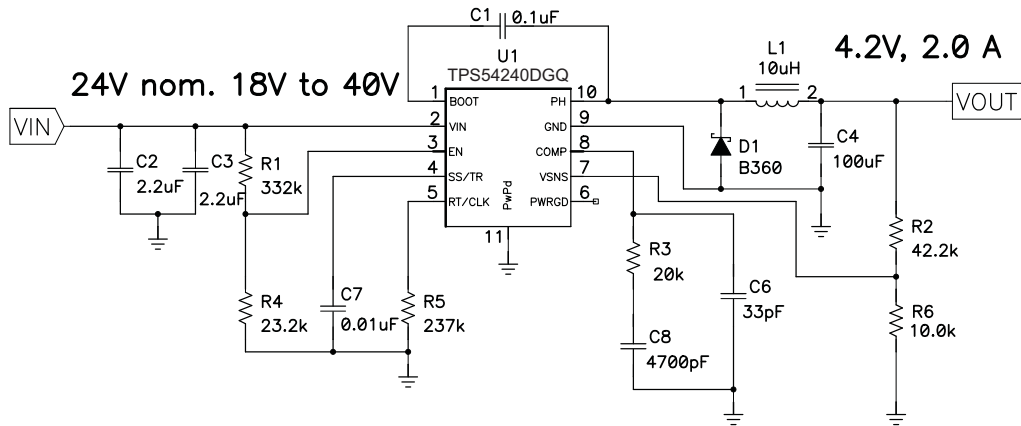


Figure 65. TPS54240-Q1 Split Rail Power Supply Based on Application Note [SLVA369](#)



L1: MSS1260-103  
 C4, C5: 47uF 10V X5R

Figure 66. 12-V to 3.8-V GSM Power Supply



L1: MSS1260-103  
 C4: 100uF 10V X5R

Figure 67. 24-V to 4.2-V GSM Power Supply



## REVISION HISTORY

Changes from Revision A (April 2011) to Revision B	Page
• Added AEC qualification text and results for temperature grade and HBM/CDM classifications to FEATURES .....	1
• Changed <i>ABSOLUTE MAXIMUM RATINGS</i> table and added HBM/CDM classification levels .....	2
• Added DRC package to <i>PIN CONFIGURATION</i> .....	5
• Changed Power Good resistance from 10 to 1 k $\Omega$ in <i>Power Good (PWRGD Pin)</i> section .....	23

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS54240QDGQRQ1	ACTIVE	HVSSOP	DGQ	10	2500	Green (RoHS & no Sb/Br)	NIPDAU	Level-3-260C-168 HR	-40 to 125	5424Q	<a href="#">Samples</a>
TPS54240QDRCRQ1	ACTIVE	VSON	DRC	10	3000	Green (RoHS & no Sb/Br)	NIPDAU	Level-3-260C-168 HR	-40 to 125	5424Q	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBsolete:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:**The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**OTHER QUALIFIED VERSIONS OF TPS54240-Q1 :**

- Catalog: [TPS54240](#)

## NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

## TAPE AND REEL INFORMATION



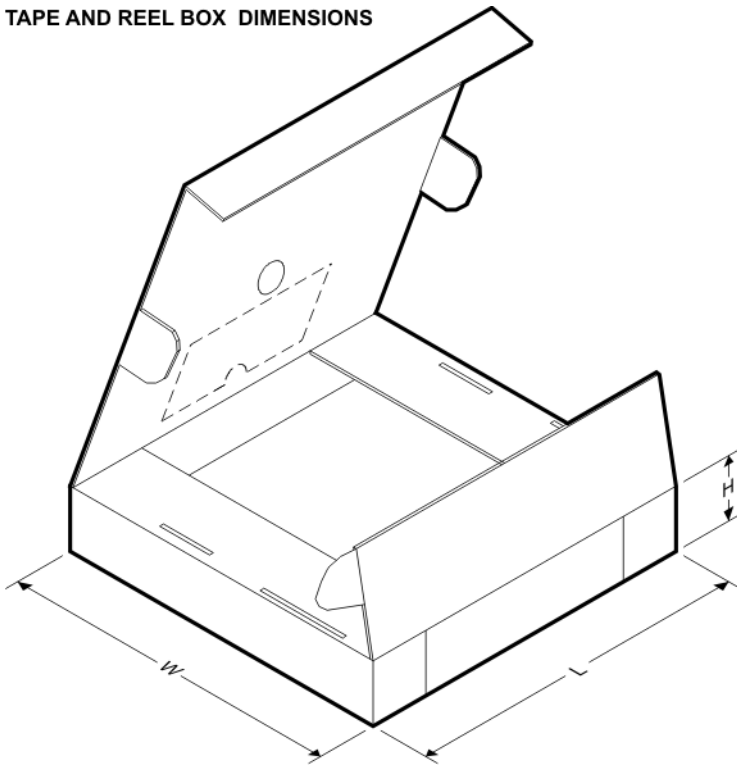
### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS54240QDGQRQ1	HVSSOP	DGQ	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS

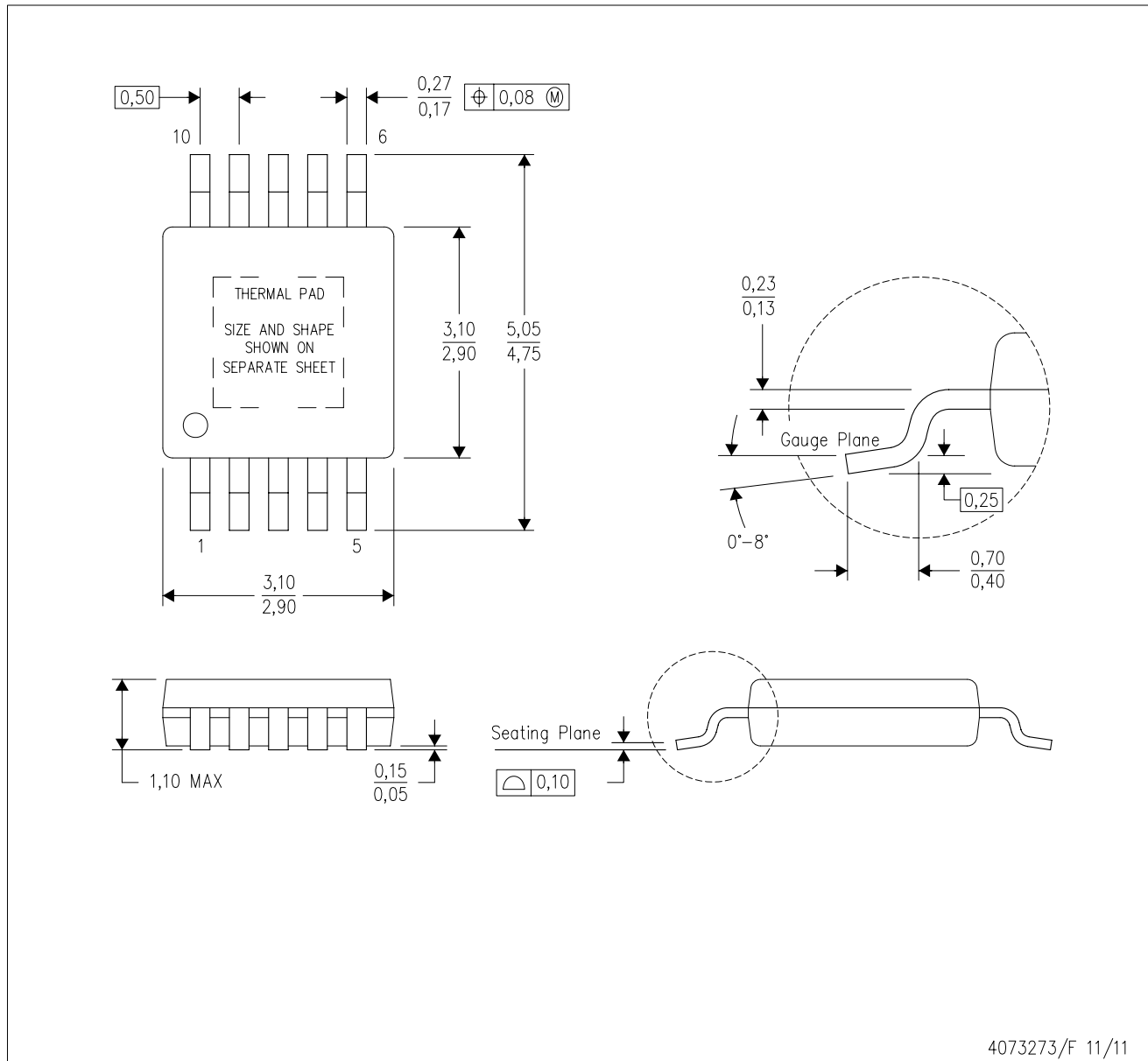


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS54240QDGQRQ1	HVSSOP	DGQ	10	2500	370.0	355.0	55.0

DGQ (S-PDSO-G10)

PowerPAD™ PLASTIC SMALL OUTLINE



4073273/F 11/11

- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
  - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
  - F. Falls within JEDEC MO-187 variation BA-T.

PowerPAD is a trademark of Texas Instruments.

DGQ (S-PDSO-G10)

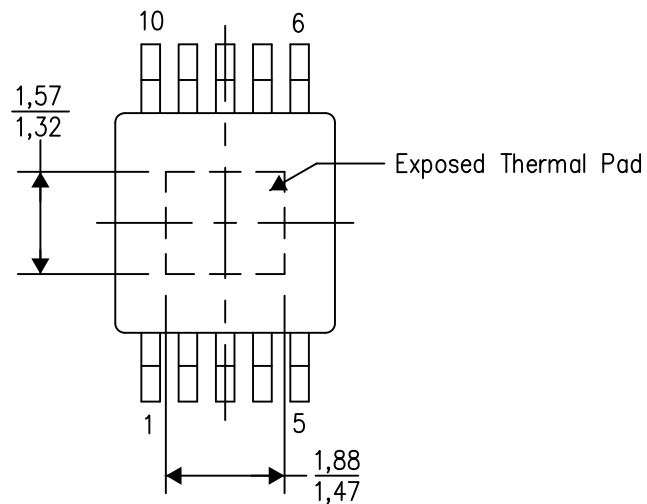
PowerPAD™ PLASTIC SMALL OUTLINE

## THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



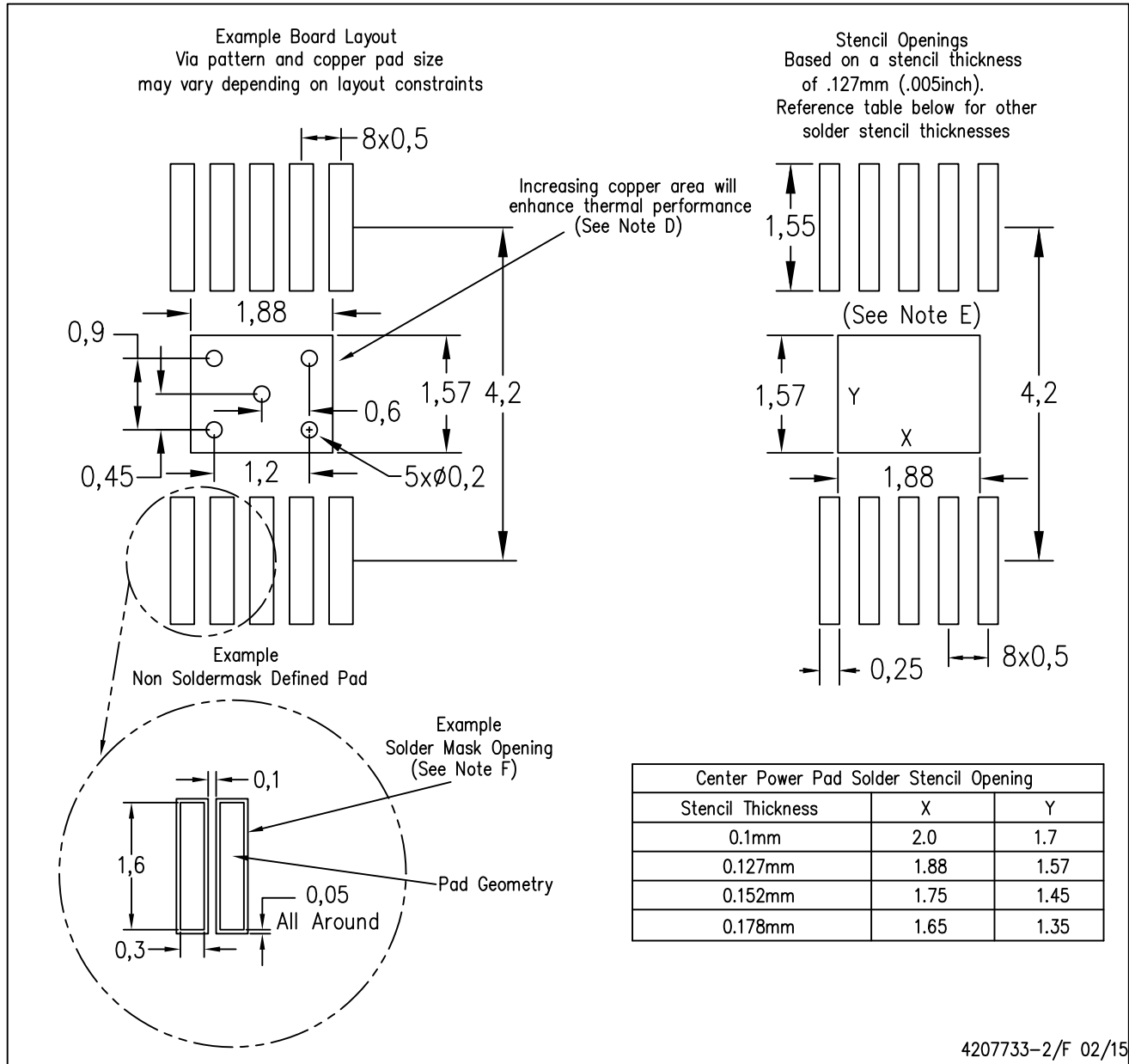
Top View

Exposed Thermal Pad Dimensions

4206324-2/H 12/14

NOTE: A. All linear dimensions are in millimeters

PowerPAD is a trademark of Texas Instruments



- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
  - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
  - Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

PowerPAD is a trademark of Texas Instruments

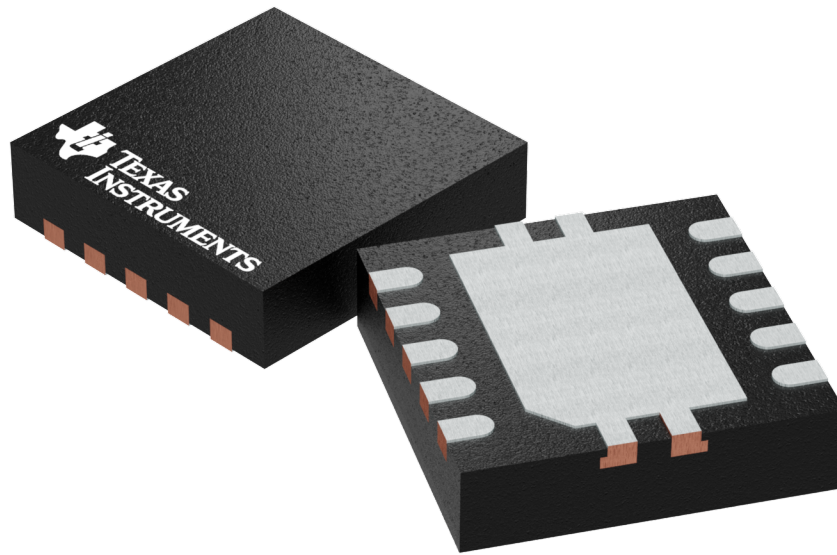


## GENERIC PACKAGE VIEW

DRC 10

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4204102-3/M

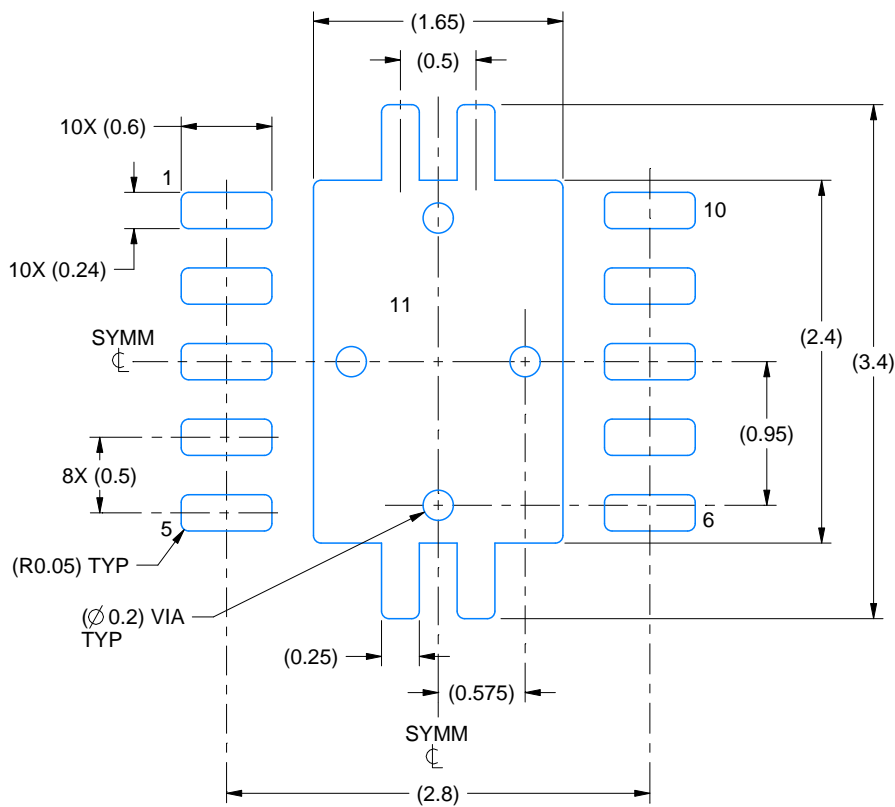


# EXAMPLE BOARD LAYOUT

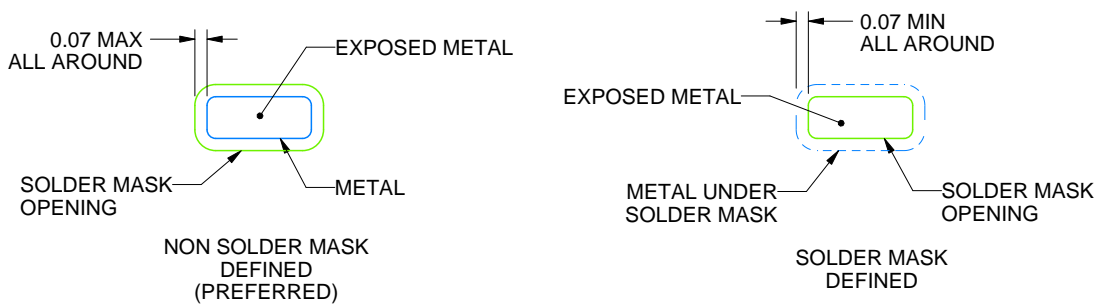
DRC0010J

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:20X



SOLDER MASK DETAILS

4218878/B 07/2018

NOTES: (continued)

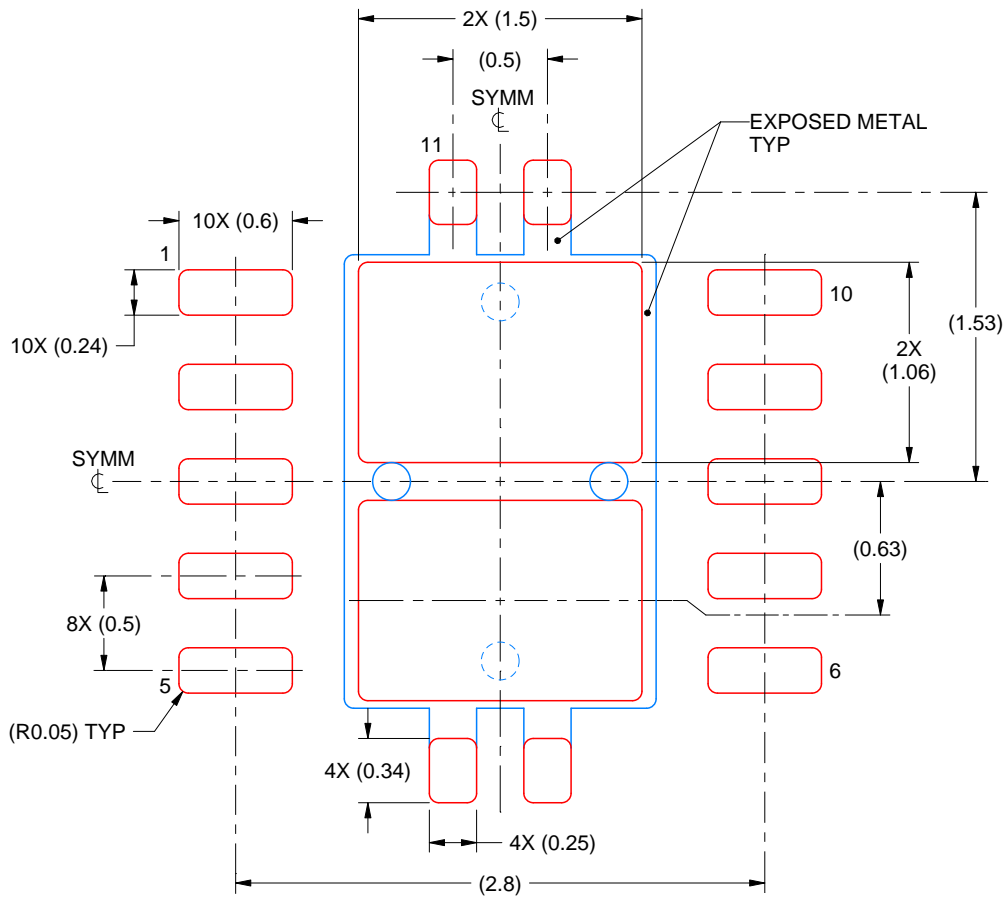
4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 ([www.ti.com/lit/sluea271](http://www.ti.com/lit/sluea271)).
5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

# EXAMPLE STENCIL DESIGN

DRC0010J

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL

EXPOSED PAD 11:  
80% PRINTED SOLDER COVERAGE BY AREA  
SCALE:25X

4218878/B 07/2018

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

## IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale ([www.ti.com/legal/termsofsale.html](http://www.ti.com/legal/termsofsale.html)) or other applicable terms available either on [ti.com](http://ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265  
Copyright © 2020, Texas Instruments Incorporated