NEC

NEC Electronics Inc.

μPD7823x Advanced, 8-Bit Real-Time Control Microcomputers With A/D and D/A Converters

January 1990

Description

The μPD78233, μPD78234, and μPD78P238 are high-performance, 8-bit, single-chip microcomputers. They contain extended addressing capabilities for up to 1M byte of external memory. The devices also integrate sophisticated analog and digital peripherals as well as two low-power standby modes that make them ideal for low-power/battery backup applications.

The μPD7823x family focuses on embedded control with features like hardware multiply and divide, two levels of interrupt response, four banks of main registers for multitasking, and macroservice for processor-independent peripheral and memory DMA. Augmenting this high-performance core are advanced components like high-precision A/D and D/A converters, two independent serial interfaces, several counter/timers, PWM outputs as well as a real-time output port. On board memory includes up to 1K bytes of RAM and 32K bytes of mask ROM or OTP ROM.

The macroservice routine allows data to be transferred between any combination of memory and peripherals independent of the current program execution. The four banks of processor registers allow simplified context switching to be performed. Both features combined with powerful on-chip peripherals make this part ideal for a wide variety of embedded control applications.

Features

- ☐ Complete single-chip microcomputer
  - — 8-bit ALU
  - — 16K ROM
  - — 640 bytes RAM
  - — Both 1-bit and 8-bit logic
- ☐ Instruction prefetch queue
- ☐ Hardware multiply and divide
- ☐ Memory expansion
  - — 8085 bus-compatible
  - — 64K program address space
  - — 1M data address space
- ☐ Large I/O capacity: up to 64 I/O port lines
- ☐ Two 12-bit PWM outputs
- ☐ Eight-input 8-bit A/D converters
- ☐ Two-output 8-bit D/A converters
- ☐ Extensive timer/counter functions
  - — One 16-bit timer/counter/event counter
  - — Three 8-bit timer/counter/event counter
- ☐ Four timer-controlled PWM channels
- ☐ Two 4-bit real-time output ports
- ☐ Extensive interrupt handler
  - — Vectored interrupt handling
  - — Programmable priority
  - — Macroservice mode
- ☐ Two independent serial ports
- ☐ Software pullup options
- ☐ Refresh output for pseudostatic RAM
- ☐ On-chip clock generator
  - — 12-MHz maximum CPU clock frequency
  - — 0.33-μs instruction cycle
- ☐ CMOS silicon gate technology
- ☐ 5-volt power supply

Ordering Information

Part Number	ROM	Package
μPD78233GC-3B9	ROMless	80-pin plastic QFP
μPD78233L		84-pin PLCC
μPD78233GJ-5B6		94-pin plastic QFP
μPD78234GC-3B9	16K Mask ROM	80-pin plastic QFP
μPD78234L		84-pin PLCC
μPD78234GJ-5B6		94-pin plastic QFP
μPD78P238GC-3B9	32K OTP ROM	80-pin plastic QFP
μPD78P238L		84-pin PLCC
μPD78P238GJ-5B6		94-pin plastic QFP

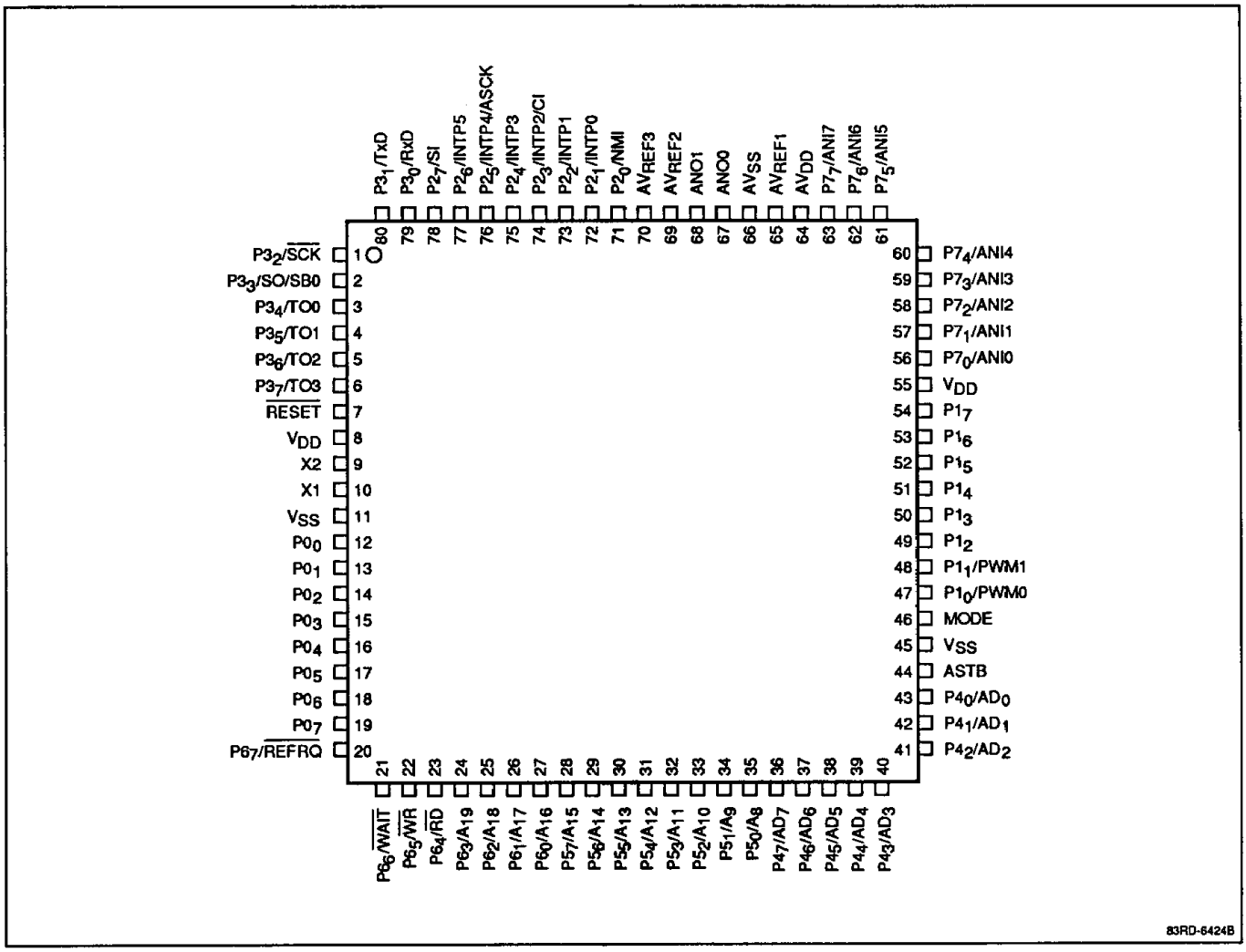
Pin Identification

Symbol	Function
$P0_0$-$P0_7$	Output port 0
$P1_0$-$P1_1$/PWM0-PWM1	I/O port 1/Pulse-width modulated outputs
$P1_2$-$P1_7$	I/O port 1
$P2_0$/NMI	Input port 2/Non-maskable interrupt input
$P2_1$-$P2_2$/INTP0-INTP1	Input port 2/External interrupt input/timer trigger
$P2_3$/INTP2/CI	Input port 2/External interrupt input/ Clock input
$P2_4$/INTP3	Input port 2/External interrupt input/timer trigger
$P2_5$/INTP4/ASCK	Input port 2/External interrupt input/ Asynchronous serial clock
$P2_6$/INTP5	Input port 2/External interrupt input
$P2_7$/SI	Input port 2/Serial input
$P3_0$/RxD	I/O port 3/Serial receive input
$P3_1$/TxD	I/O port 3/Serial transmit output
$P3_2$/$\overline{SCK}$	I/O port 3/Serial clock input/output
$P3_3$/SO/SB0	I/O port 3/Serial output/Serial bus I/O
$P3_4$-$P3_7$/TO0-TO3	I/O port 3/Timer output
$P4_0$-$P4_7$/AD_0-AD_7	I/O port 4/Lower address byte/data bus

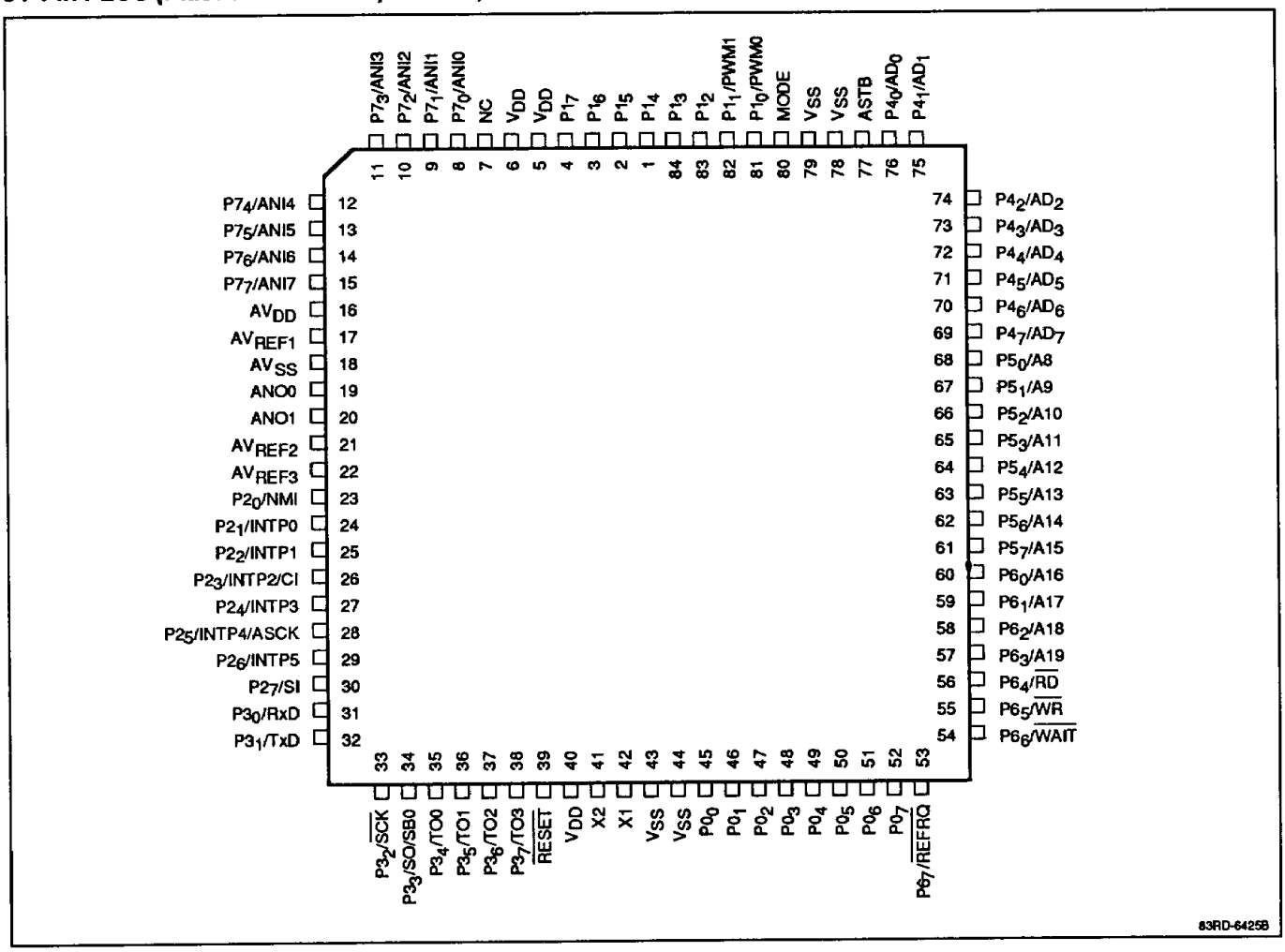
Symbol	Function
$P5_0$-$P5_7$/A_8-A_{15}	I/O port 5/Upper address byte
$P6_0$-$P6_3$/A_{16}-A_{19}	Output port 6/Extended address nibble
$P6_4$/$\overline{RD}$	I/O port 6/Read strobe output
$P6_5$/$\overline{WR}$	I/O port 6/Write strobe output
$P6_6$/$\overline{WAIT}$	I/O port 6/Wait input
$P6_7$/$\overline{REFRQ}$	I/O port 6/Refresh output
$P7_0$-$P7_7$/ANI0-ANI7	Input port 7/A/D converter inputs
ANO0-ANO1	D/A converter output
ASTB	Address strobe output
$\overline{RESET}$	External reset input
$\overline{MODE}$	External memory access control input
X1, X2	External crystal or external clock input
AV_{REF1}	A/D converter reference voltage
AV_{REF2}, AV_{REF3}	D/A converter reference voltages
AV_{SS}	Analog ground
V_{DD}	Positive power supply input
AV_{DD}	Positive power supply input; analog section
V_{SS}	Power return; normally ground
NC	No connection

Pin Configurations

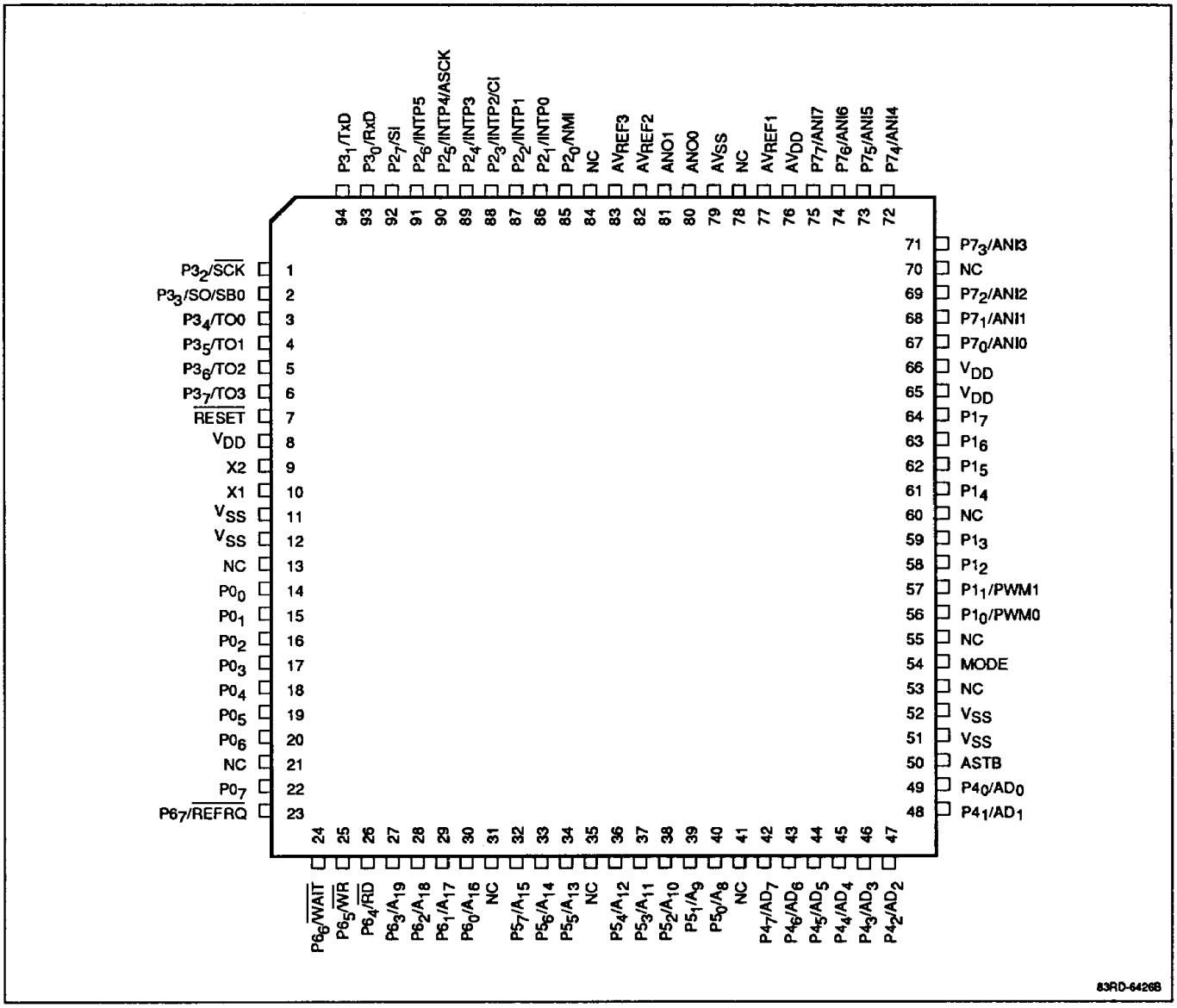
80-Pin Plastic QFP



84-Pin PLCC (Plastic Leaded Chip Carrier)



94-Pin Plastic QFP



Pin Functions

$P0_0$-$P0_7$. Port 0 is an 8-bit, tristate output port with direct transistor drive capability. Port 0 can also be configured as two 4-bit, real-time (timer-controlled) output ports.

$P1_0$-$P1_7$. Port 1 is an 8-bit input/output port with the programmable pullup option. Port 1 has direct LED drive capability.

PWM0-PWM1. These are pulse-width modulated outputs for dc motor control.

$P2_0$-$P2_7$. Port 2 is an 8-bit input port with the programmable pullup option except for $P2_0$ and $P2_1$.

NMI. Non-maskable interrupt input.

INTP0-INTP5. External interrupt inputs. INTP0, INTP1, and INTP3 are timer capture trigger inputs.

CI. External clock input to the timer.

ASCK. Asynchronous serial clock input.

SI. Serial data input for three-wire serial I/O mode.

$P3_0$-$P3_7$. Port 3 is an 8-bit tristate I/O port with the programmable pullup option.

RxD. Receive serial data input.

TxD. Transmit serial data output.

$\overline{SCK}$. Serial shift clock output.

SO. Serial data output for three-wire serial I/O mode.

SB0. I/O bus for the clocked serial interface.

TO0-TO3. Timer flip-flop outputs.

$P4_0$-$P4_7$. Port 4 is an 8-bit, bidirectional tristate port with the programmable pullup option. Port 4 has direct LED drive capability.

AD_0-AD_7. Multiplexed address/data bus used with external memory or expanded I/O.

$P5_0$-$P5_7$. Port 5 is an 8-bit, bidirectional tristate port with the programmable pullup option. Port 5 has direct LED drive capability.

A_8-A_{15}. Upper-order address bus used with external memory or expanded I/O.

$P6_0$-$P6_3$. Pins $P6_0$-$P6_3$ of port 6 are outputs.

A_{16}-A_{19}. Extended-order address bus used with external memory.

$P6_4$-$P6_7$. Pins $P6_4$-$P6_7$ of port 6 are tristate I/Os with the programmable pullup option.

$\overline{RD}$. Read strobe output used by external memory (or data registers) to place data on the I/O bus during a read operation.

$\overline{WR}$. Write strobe output used by external memory (or data registers) to latch data from the I/O bus during a write operation.

$\overline{WAIT}$. Wait signal input.

$\overline{REFRQ}$. Refresh pulse output used by external pseudo-static memory.

$P7_0$-$P7_7$. Port 7 is an 8-bit input port.

ANI0-ANI7. Analog voltage inputs to A/D converter.

ANO1, ANO2. Analog voltage outputs from D/A converters.

ASTB. Address strobe output used by external circuitry to latch the low-order 8 address bits during the first part of a read or write cycle.

$\overline{RESET}$. A low level on this external reset input sets all registers to their specified reset values. This pin, together with $P2_0$/NMI, sets the μPD78P234 in the PROM programming mode.

MODE. Control signal input that selects external memory or internal ROM as the program memory. When MODE is low, μPD78234 is set in ROMless mode and external memory is accessed.

X1, X2. For frequency control of the internal clock oscillator, a crystal is connected to X1 and X2. If the clock is supplied by an external source, the clock signal is connected to X1 and the inverted clock signal is connected to X2.

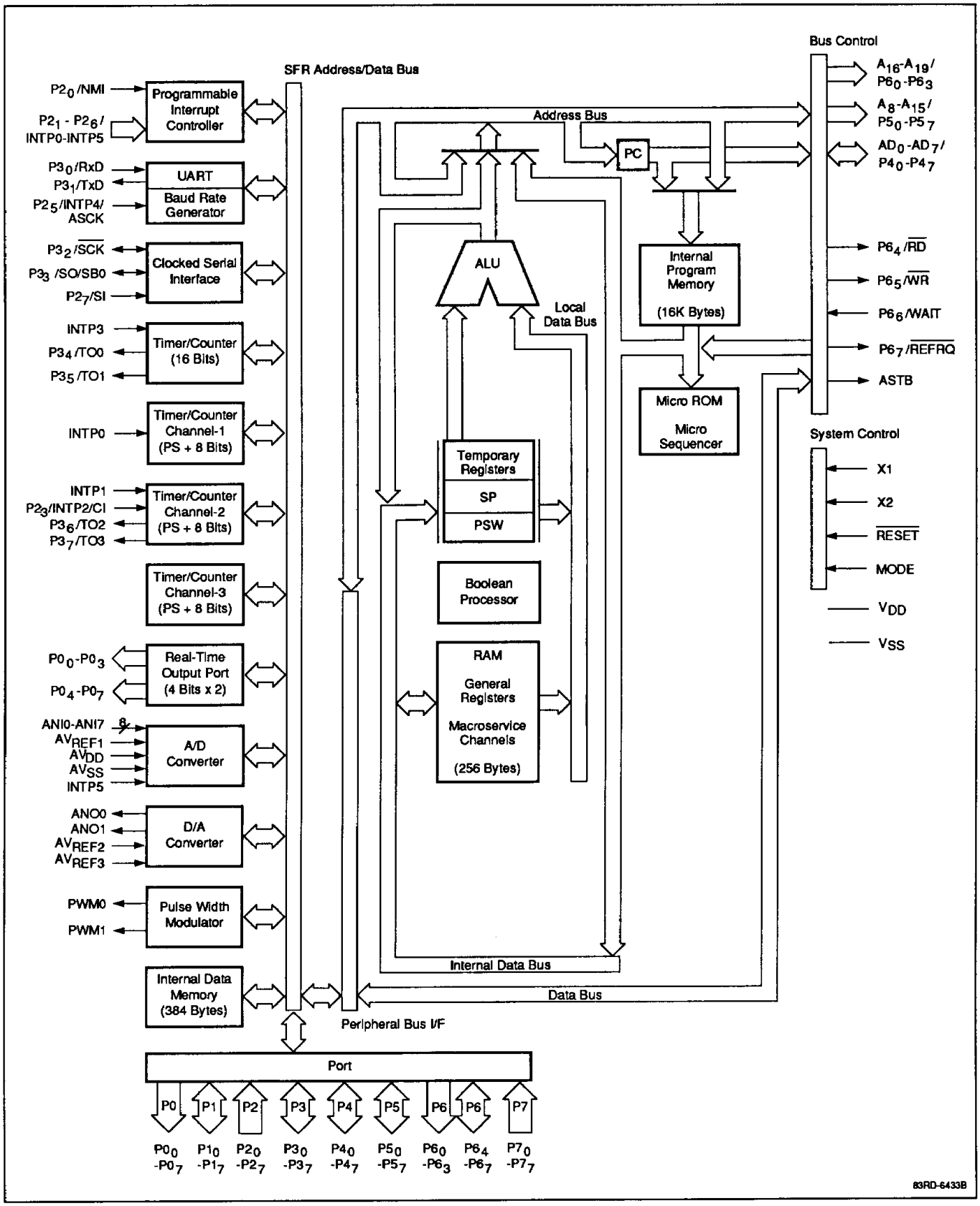
AV_{REF1}. A/D converter reference voltage.

AV_{REF2}, AV_{REF3}. D/A converter reference voltage.

AV_{DD}. A/D converter supply voltage.

AV_{SS}. A/D converter ground.

μPD7823x Block Diagram



FUNCTIONAL DESCRIPTION

Timing

The maximum clock frequency is 12 MHz. The clock is derived from an external crystal or an external oscillator. The internal processor clock is two-phase and the machine states are executed at a rate of 6 MHz. The shortest instructions require two states (333 ns). The CPU contains a one-byte instruction prefetch. This allows a subsequent instruction to be fetched during the execution of an instruction that does not reference memory.

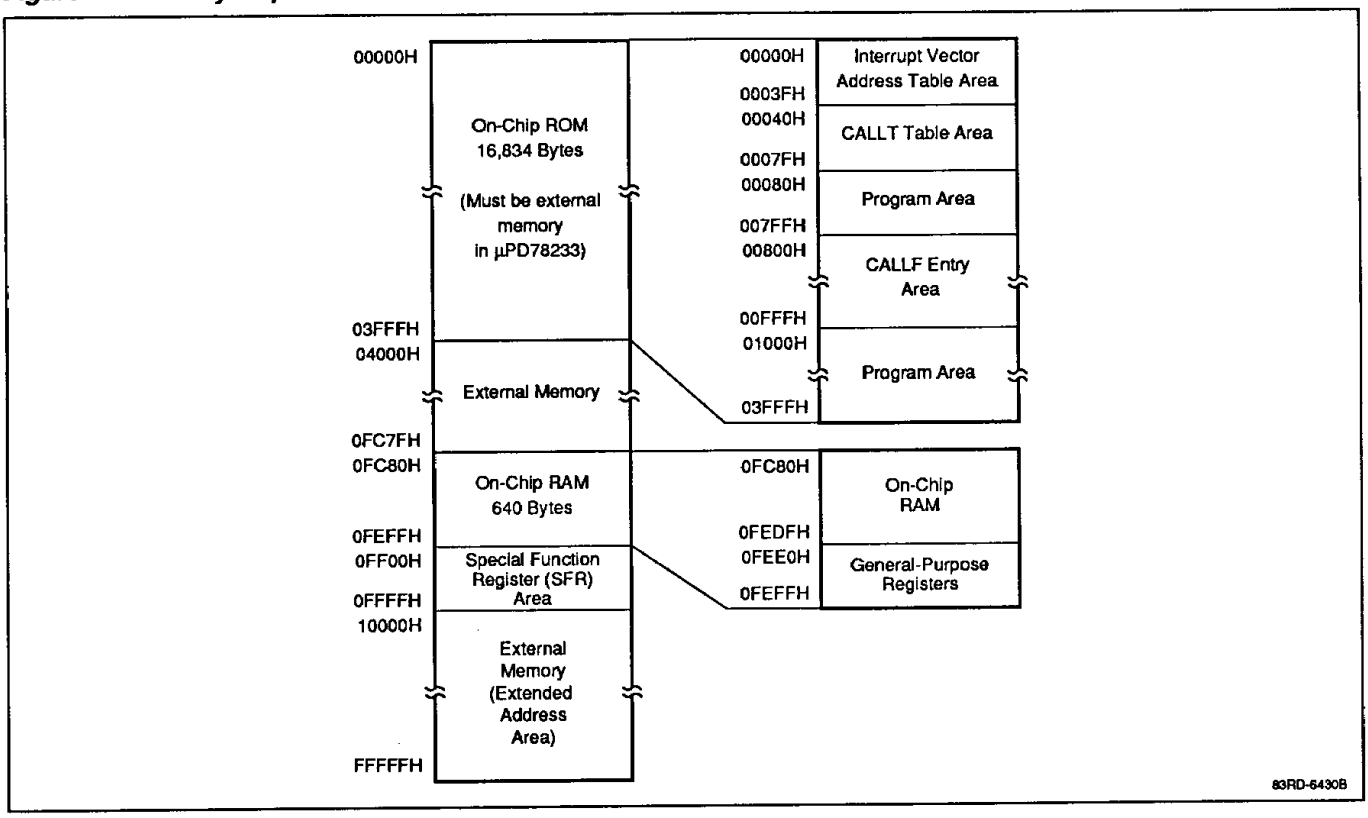
Memory Map

The μPD7823x has 1M byte of address space. This address space is partitioned into 64K bytes of program memory starting at address 00000H. (See figure 1.) The remainder of the 1M bytes can be accessed as data memory space.

External memory is supported by I/O port 4, an 8-bit multiplexed address/data bus. The memory mapping register controls the size of external memory as well as the number of added wait states. The upper address byte is derived from port 5, and the extended address nibble is derived from port 6.

The μPD78234 has on-chip mask ROM occupying the space from 00000H to 03FFFH. When the ROM is used and no other program or data space is required, ports 4, 5, and 6 are available as additional I/O ports.

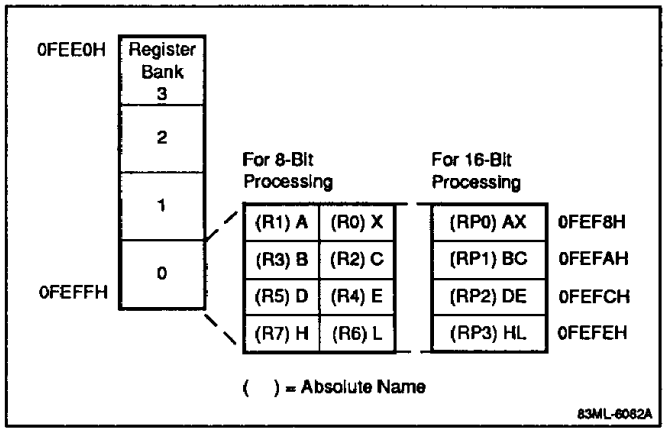
Figure 1. Memory Map



General-Purpose Registers

The general-purpose registers are mapped into specific addresses in data memory. They are made up of four banks, each bank consisting of eight 8-bit or four 16-bit registers. The register bank used is specified by a CPU instruction. This can be checked by reading RBS0 and RBS1 in the program status word (PSW).The general-purpose register configuration is shown in figure 2.

Figure 2. Register Mapping



Special Registers

There are three different special registers. The first is a 16-bit binary counter that holds the next program address to be executed and is named the program counter. The stack pointer is the second special 16-bit register. The stack pointer holds the address of the stack area (a last in, first out system). The third special register is an 8-bit program status word. This register contains various flags that are set or reset depending on the results of instruction execution. The program status word format is as follows:

7							0
IE	Z	RBS1	AC	RBS0	0	ISP	CY

CY	Carry flag
ISP	Interrupt priority status flag
RBS0, RBS1	Register bank selection flags
AC	Auxiliary carry flag
Z	Zero flag
IE	Interrupt request enable flag

Special Function Registers

These registers are assigned to special functions such as the mode and control registers for on-chip peripheral hardware. They are mapped into the 256-byte memory space from 0FF00H to 0FFFFH. Table 1 is a list of special function registers.

Table 1. Special Function Registers

Address	Special Function Register (SFR) Name	Symbol	R/W	Handleable Bit Unit 1 Bit	8 Bit	16 Bit	On Reset
0FF00H	Port 0	P0	R/W	o	o	–	Indeterminate
0FF01H	Port 1	P1	R/W	o	o	–	Indeterminate
0FF02H	Port 2	P2	R	o	o	–	Indeterminate
0FF03H	Port 3	P3	R/W	o	o	–	Indeterminate
0FF04H	Port 4	P4	R/W	o	o	–	Indeterminate
0FF05H	Port 5	P5	R/W	o	o	–	Indeterminate
0FF06H	Port 6	P6	R/W	o	o	–	x0H
0FF07H	Port 7	P7	R	o	o	–	Indeterminate
0FF0AH	Port 0 buffer register (low)	P0L	R/W	o	o	–	Indeterminate
0FF0BH	Port 0 buffer register (high)	P0H	R/W	o	o	–	Indeterminate
0FF0CH	Real-time output port control register	RTPC	R/W	o	o	–	00H
0FF10H, 0FF11H	16-bit compare register 0 (16-bit timer/counter)	CR00	R/W	–	–	o	Indeterminate
0FF12H, 0FF13H	16-bit compare register 1 (16-bit timer/counter)	CR01	R/W	–	–	o	Indeterminate
0FF14H	8-bit compare register (8-bit timer/counter 1)	CR10	R/W	–	o	–	Indeterminate
0FF15H	8-bit compare register (8-bit timer/counter 2)	CR20	R/W	–	o	–	Indeterminate
0FF16H	8-bit compare register (8-bit timer/counter 2)	CR21	R/W	–	o	–	Indeterminate
0FF17H	8-bit compare register (8-bit timer/counter 3)	CR30	R/W	–	o	–	Indeterminate
0FF18H, 0FF19H	16-bit capture register (16-bit timer/counter)	CR02	R	–	–	o	Indeterminate
0FF1AH	8-bit capture register (8-bit timer/counter 2)	CR22	R	–	o	–	Indeterminate
0FF1CH	8-bit capture/compare register (8-bit timer/counter 1)	CR11	R/W	–	o	–	Indeterminate
0FF20H	Port 0 mode register	PM0	W	–	o	–	FFH
0FF21H	Port 1 mode register	PM1	R	–	o	–	FFH
0FF23H	Port 3 mode register	PM3	W	–	o	–	FFH
0FF25H	Port 5 mode register	PM5	W	–	o	–	FFH
0FF26H	Port 6 mode register	PM6	R/W	–	o	–	FxH
0FF30H	Capture/compare control register 0	CRC0	W	–	o	–	10H
0FF31H	Timer output control register	TOC	W	–	o	–	00H
0FF32H	Capture/compare control register 1	CRC1	W	–	o	–	00H
0FF34H	Capture/compare control register 2	CRC2	W	–	o	–	00H
0FF40H	Pull-up option register	PUO	R/W	o	o	–	00H
0FF43H	Port 3 mode control register	PMC3	R/W	o	o	–	00H
0FF50H, 0FF51H	16-bit timer register 0	TM0	R	–	–	o	0000H
0FF52H	8-bit timer register 1	TM1	R	–	o	–	00H

Table 1. Special Function Registers (cont)

Address	Special Function Register (SFR) Name	Symbol	R/W	Handleable Bit Unit 1 Bit	8 Bit	16 Bit	On Reset
0FF54H	8-bit timer register 2	TM2	R	–	o	–	00H
0FF56H	8-bit timer register 3	TM3	R	–	o	–	00H
0FF5CH	Prescaler mode register 0	PRM0	W	–	o	–	00H
0FF5DH	Timer control register 0	TMC0	R/W	–	o	–	00H
0FF5EH	Prescaler mode register 1	PRM1	W	–	o	–	00H
0FF5FH	Timer control register 1	TMC1	R/W	–	o	–	00H
0FF60H	D/A converter value setting register 0	DACS0	R/W	–	o	–	00H
0FF61H	D/A converter value setting register 1	DACS1	R/W	–	o	–	00H
0FF68H	A/D converter mode register	ADM	R/W	o	o	–	00H
0FF6AH	A/D conversion result register	ADCR	R	–	o	–	Indeterminate
0FF70	PWM control register	PWMC	R/W	–	o	–	05H
0FF72H, 0FF73H	PWM modulo register 0	PWM0	W	–	–	o	Indeterminate
0FF74H, 0FF75H	PWM modulo register 1	PWM1	W	–	–	o	Indeterminate
0FF7DH	One-shot pulse output control register	OSPC	R/W	o	o	–	00H
0FF80H	Clocked serial interface mode register	CSIM	R/W	o	o	–	00H
0FF82H	Serial bus interface control register	SBIC	R/W	o	o	–	00H
0FF86H	Serial shift register	SIO	R/W	–	o	–	Indeterminate
0FF88H	Asynchronous serial interface mode register	ASIM	R/W	o	o	–	80H
0FF8AH	Asynchronous serial interface status register	ASIS	R	o	o	–	00H
0FF8CH	Serial receive buffer: UART	RxB	R	–	o	–	Indeterminate
0FF8EH	Serial send shift register: UART	TxS	W	–	o	–	Indeterminate
0FF90H	Baud rate generator control register	BRGC	W	–	o	–	00H
0FFC0H	Standby control register	STBC	R/W	–	o	–	0000 x 000B
0FFC4H	Memory expansion mode register	MM	R/W	o	o	–	20H
0FFC5H	Programmable wait control register	PW	R/W	o	o	–	80H
0FFC6H	Refresh mode register	RFM	R/W	o	o	–	00H
0FFCFH	Memory size control register	IMS	W	–	o	–	Indeterminate
0FFE0H	Interrupt request flag register L	IF0L IF0	R/W	o	o	o	0000H
0FFE1H	Interrupt request flag register H	IF0H	R/W	o	o		0000H
0FFE4H	Interrupt mask flag register L	MK0L MK0	R/W	o	o	o	FFFFH
0FFE5H	Interrupt mask flag register H	MK0H	R/W	o	o		FFFFH
0FFE8H	Priority specification flag register L	PR0L PR0	R/W	o	o	o	FFFFH
0FFE9H	Priority specification flag register H	PR0H	R/W	o	o		FFFFH
0FFECH	Interrupt service mode specification flag register L	ISM0L ISM0	R/W	o	o	o	0000H
0FFECH	Interrupt service mode specification flag register L	ISM0L ISM0	R/W	o	o	o	0000H
0FFEDH	Interrupt service mode specification flag register H	ISM0H	R/W	o	o		0000H
0FFF4H	External interrupt mode register 0	INTM0	R/W	o	o	–	00H
0FFF5H	External interrupt mode register 1	INTM1	R/W	o	o	–	00H
0FFF8H	Interrupt status register	IST	R/W	o	o	–	00H

Input/Output Ports

Port 0 is a byte programmable tristate output port. Port 1 is bit programmable as input or output pins. Port 2 is bit selectable as input or control pins. Port 3 is bit programmable as input, output, or control pins. Port 4 is byte programmable as an I/O port or as the external address/data bus. Port 5 is bit programmable as I/O or the upper address byte. Port 6 is bit programmable as I/O, control pins, or the extended address nibble. Port 7 is an input only port.

Real-Time Output Port

The real-time output port (figure 3) shares pins with port 0. The high and low nibbles may be treated separately or together. In the real-time output function, data stored beforehand in the buffer register is transferred to the output latch simultaneously with the generation of either a timer interrupt or external interrupt. Using the real-time output function in conjunction with the macroservice function enables port 0 to output preprogrammed patterns at preprogrammed variable time intervals.

A/D Converter

The μPD7823x A/D converter (figure 4) uses the successive-approximation method of converting any or all of the eight multiplexed analog inputs into 8-bit digital data. This data is stored in a result register that can be accessed at any time. The conversion time is 30 μs at 12-MHz operation. Quantization error is ±1/2 LSB; maximum full-scale error is 0.4%.

There are two methods for starting the A/D conversion operation. Conversion may be started by hardware by using an external interrupt as a trigger. The second method of starting conversion is with a software command.

There are also two methods by which the μPD7823x will operate after conversion has begun. The first, the scan method, selects several analog input signals sequentially and obtains data from each pin producing an interrupt with each conversion. The converted data can be successively transferred to memory by using the macroservice function. The second, the select mode, chooses any one input and the result is updated continuously, with or without interrupt generation depending on the chosen start method.

Figure 3. Real-Time Output Port

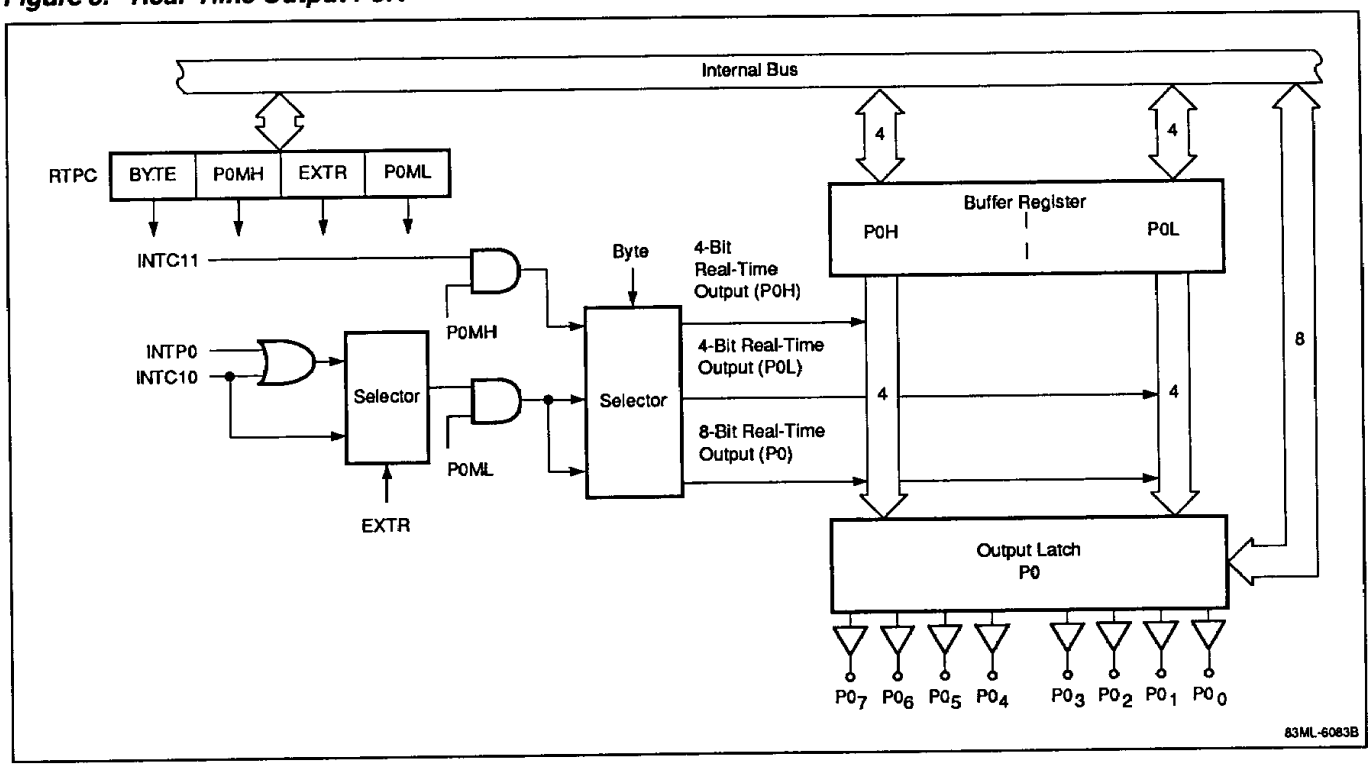
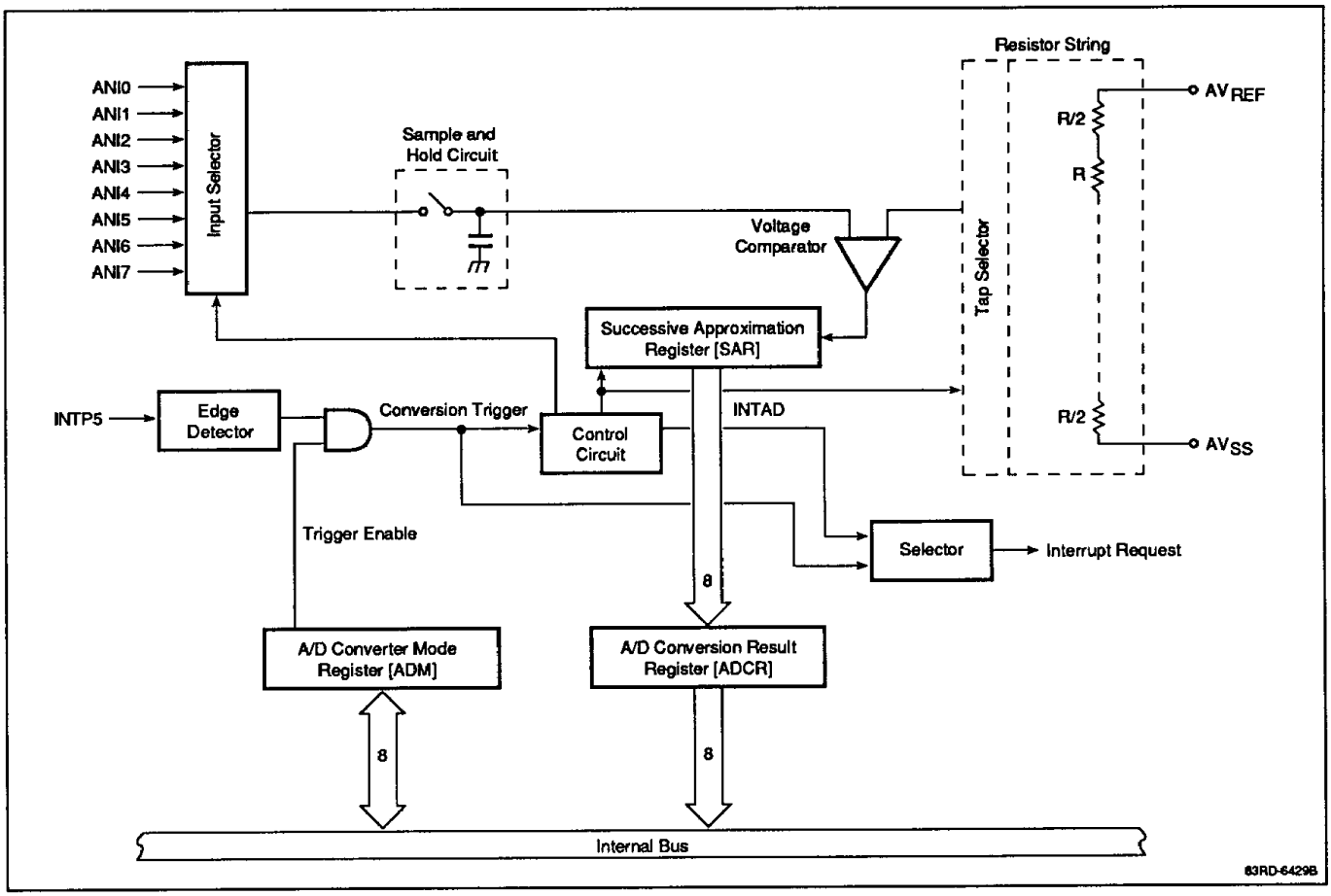


Figure 4. Analog-to-Digital Converter



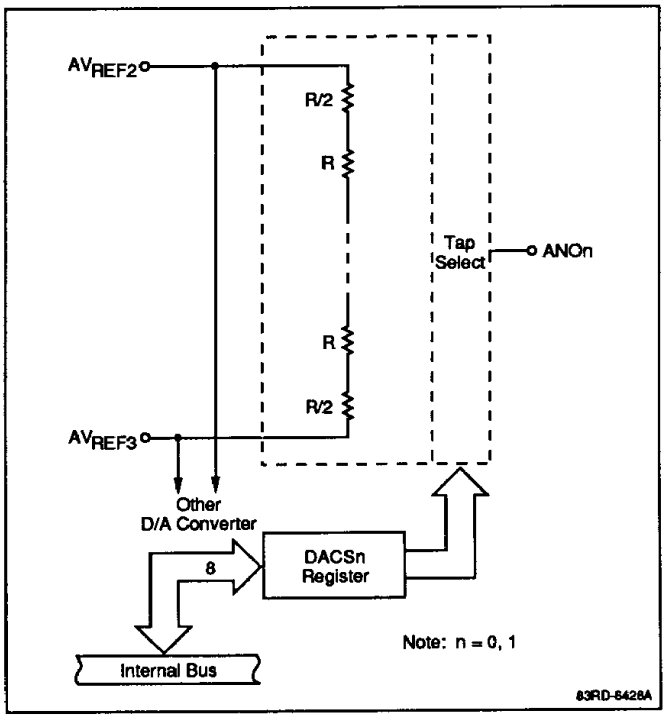
D/A Converter

The μPD7823x has two D/A converters as shown in figure 5. The 8-bit digital input, written to the DACSn register (n = 0, 1), selects one of 256 taps on a resistor ladder between reference voltages AV_{REF2} and AV_{REF3}. The selected voltage becomes the analog output at the ANOn pin.

Because of the high impedance at ANOn, an external buffer is required to drive a low-impedance load.

The ANOn pin is high impedance also while the RESET signal is active. After reset clears, the DACSn register is loaded with 0s.

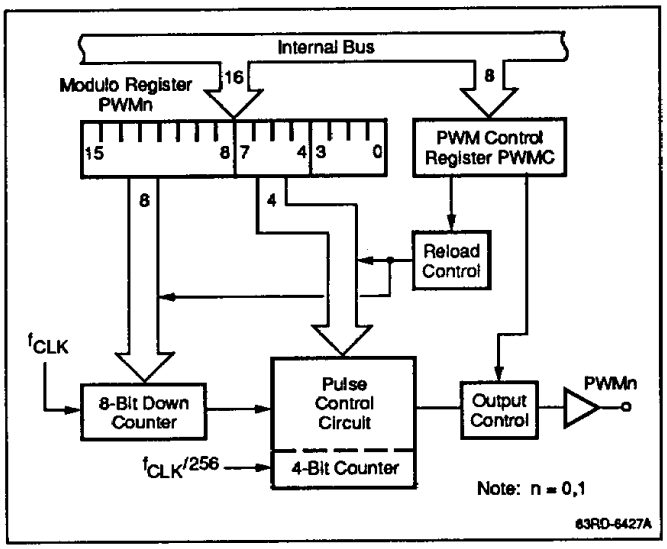
Figure 5. Digital-to-Analog Converter



PWM Output

The two pulse-width modulators of the μPD7823x (figure 6) have 12-bit resolution. Designed for dc motor speed control, the outputs at PWMn (n = 0, 1) are selectable independently as active low or high.

Figure 6. Pulse-Width Modulator



Serial Interface

The μPD7823x has two independent serial interfaces.

- Asynchronous serial interface (UART) (figure 7)
- Clock-synchronized serial interface (figure 8)

A universal asynchronous receiver transmitter (UART) is used as an asynchronous serial interface. This interface transfers one byte of data following a start bit. The μPD7823x contains a baud rate generator. This allows data to be transferred over a wide range of transfer rates. Transfer rates may also be defined by dividing the clock input to the ASCK pin. Transfer rates may also be generated by 8-bit timer counter 3.

The clock-synchronized serial interface has two different modes of operation:

- Three-line serial I/O mode.
  In this mode, data 8 bits long is transferred along three lines: a serial clock (SCK) line and two serial bus lines (SO and SI). This mode is convenient when the μPD7823x is connected to peripheral I/Os and display controllers that have the conventional clock-synchronized serial interface.
- Serial bus interface mode (SBI).
  In this mode the μPD7823x can communicate data with several devices using the serial clock (SCK) and the serial data bus (SBO) lines. This mode conforms to NEC's serial bus format. In SBI mode, addresses that select a device to communicate with, commands that direct the device, and actual data are output to the serial data bus. A handshake line, which was required for connecting several devices in the conventional clock-synchronized serial interface, is not needed.

Figure 7. Asynchronous Serial Interface

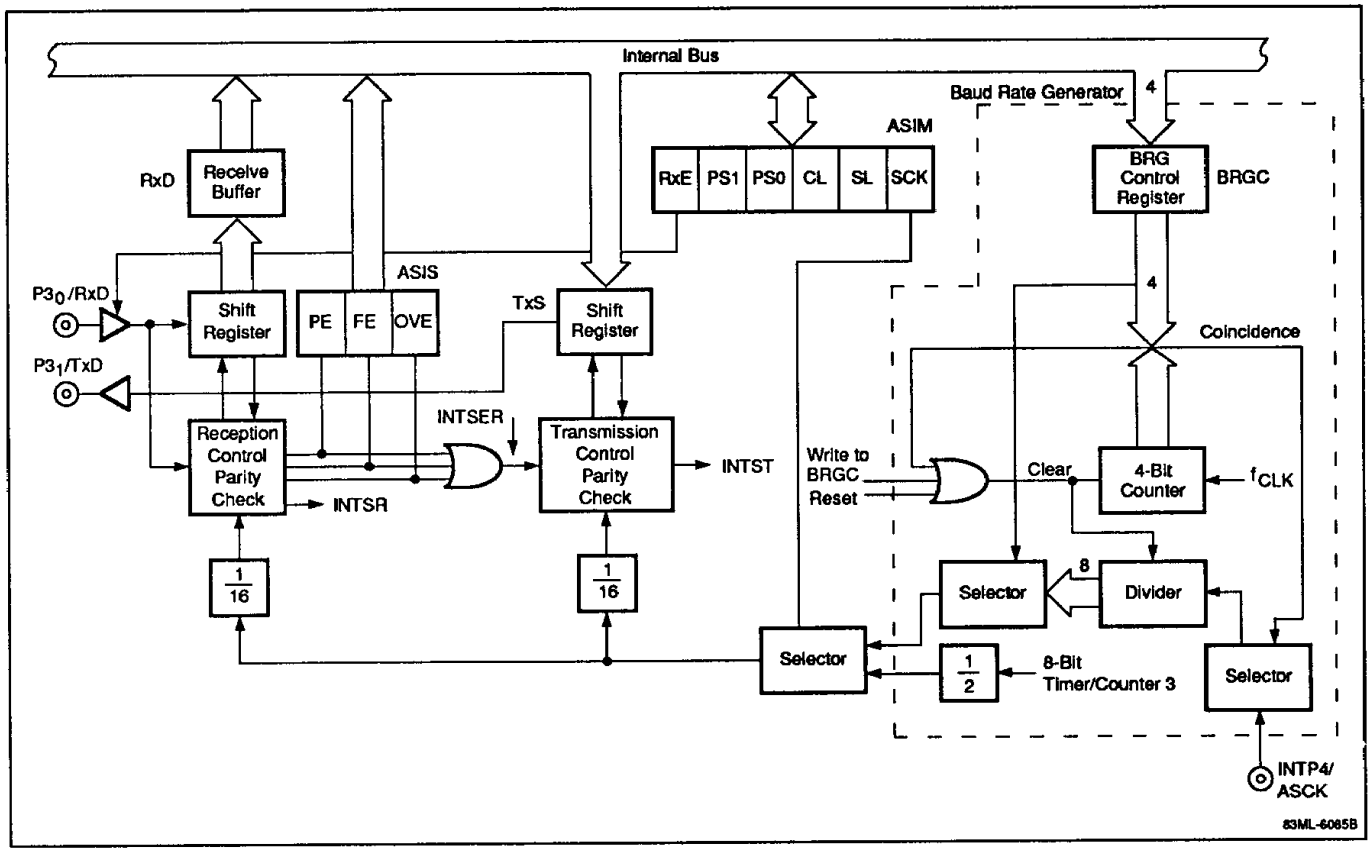
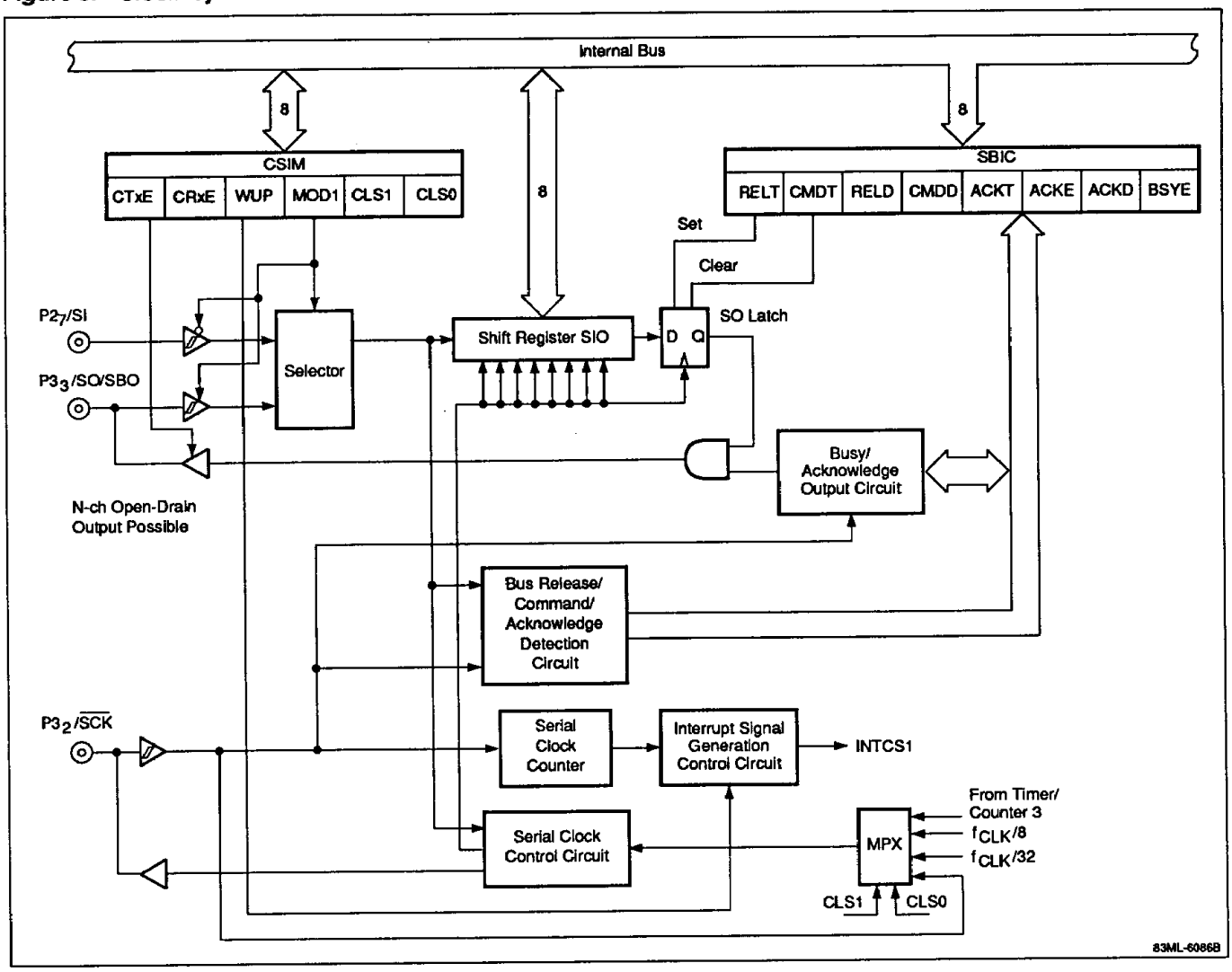


Figure 8. Clock-Synchronized Serial Interface



Timer/Counters

The μPD7823x has four timer/counters: one 16-bit and three 8-bit. The 16-bit timer/counter (figure 9) has the basic functionality of an interval timer, a programmable square-wave output, and a pulse width measurer. These functions can provide a digital delayed one-shot output, a pulse width modulated output, and a cycle measurer.

The first two 8-bit timer/counters can provide the basic functions of an interval timer and a pulse width measurer. Timer/counter 1 can also be used as a timer for output trigger generation for the real-time output port. Timer/counter 2 can also provide an external event counter, a one-shot timer, a programmable square-wave output, a pulse-width modulated output, and a cycle measurer. Timer/counter 3 can operate as an internal timer or as a counter to generate clocks for a baud rate generator. See figures 10, 11, and 12.

Figure 9. 16-Bit Timer/Counter

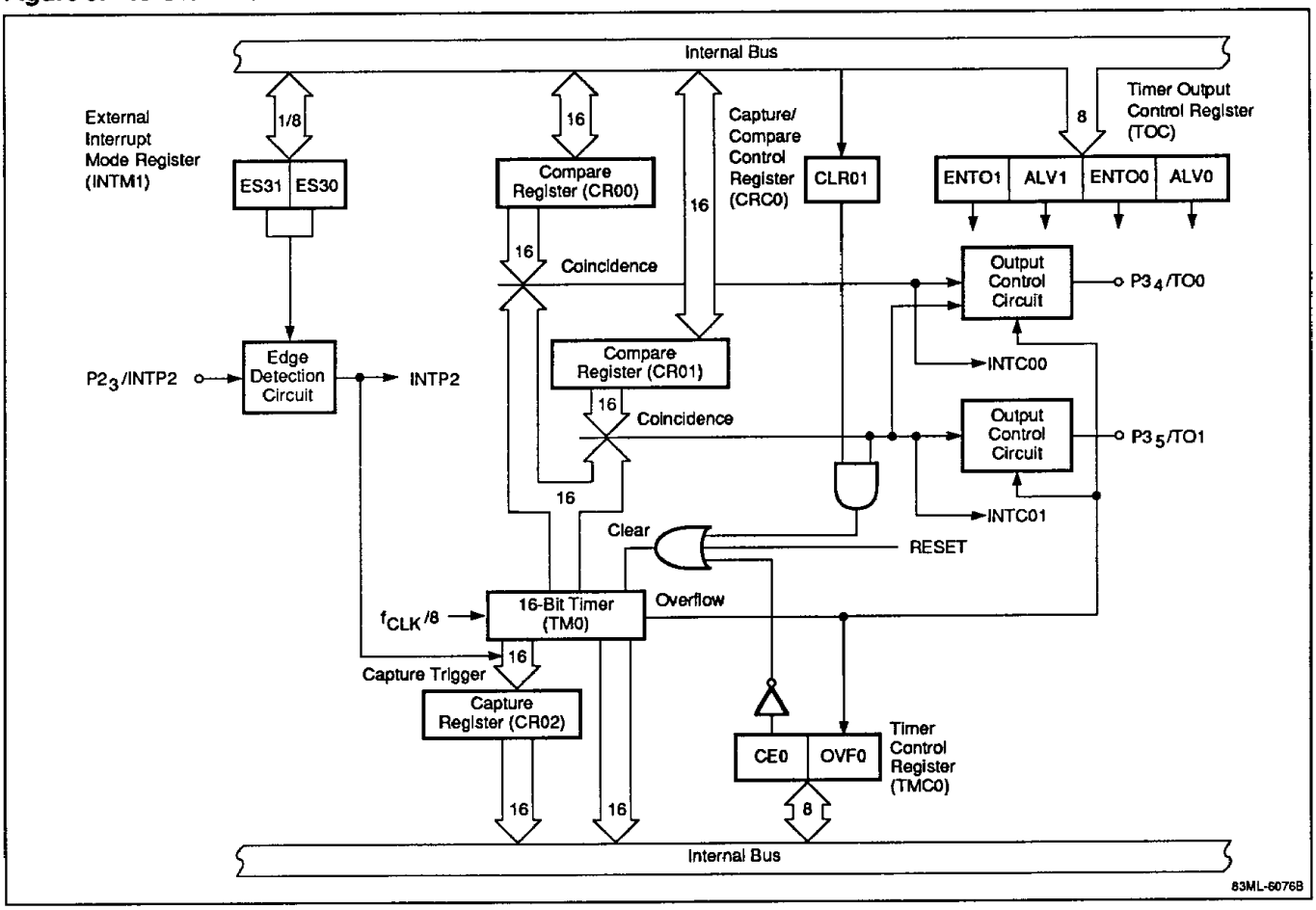


Figure 10. 8-Bit Timer/Counter 1

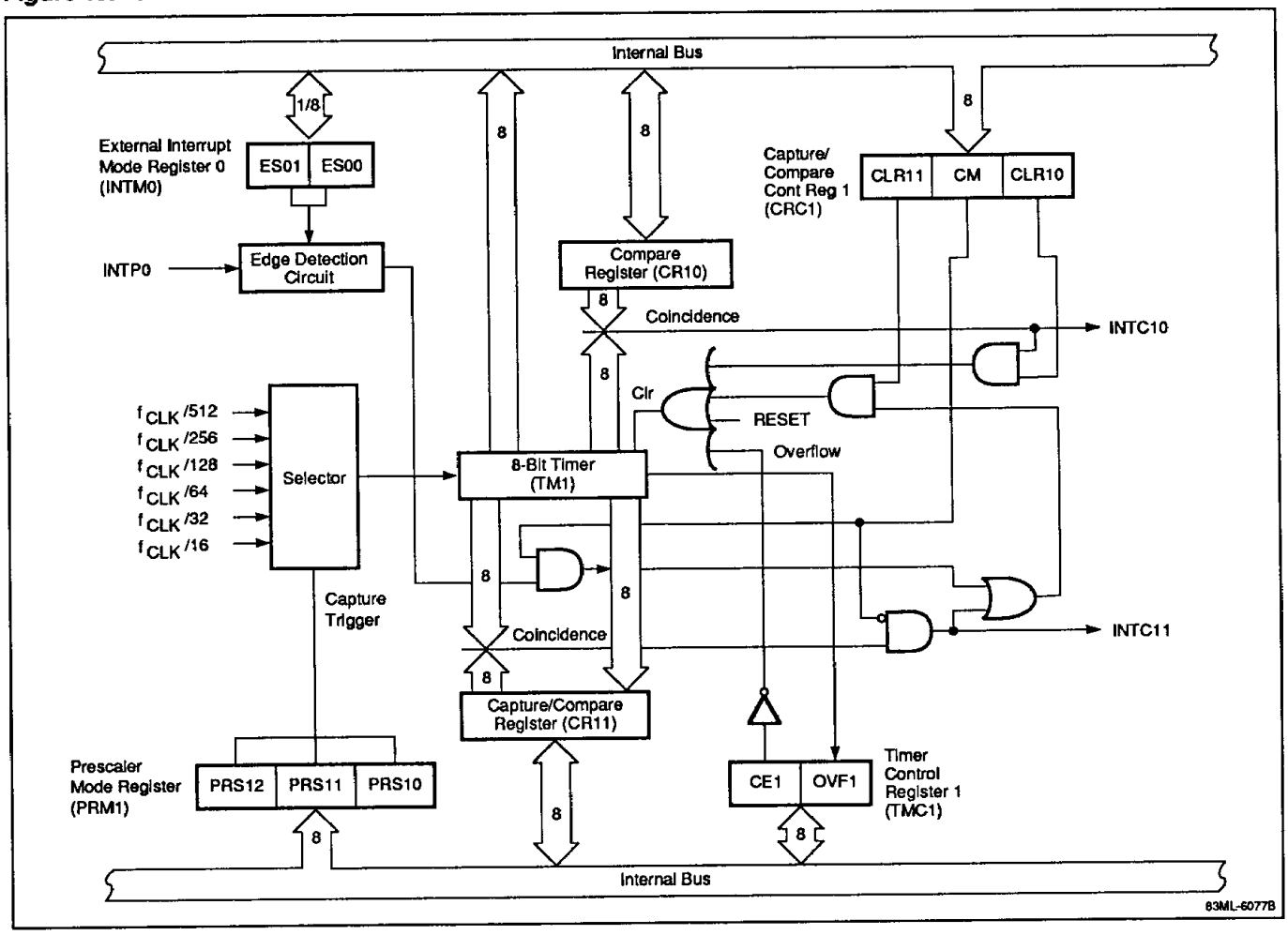
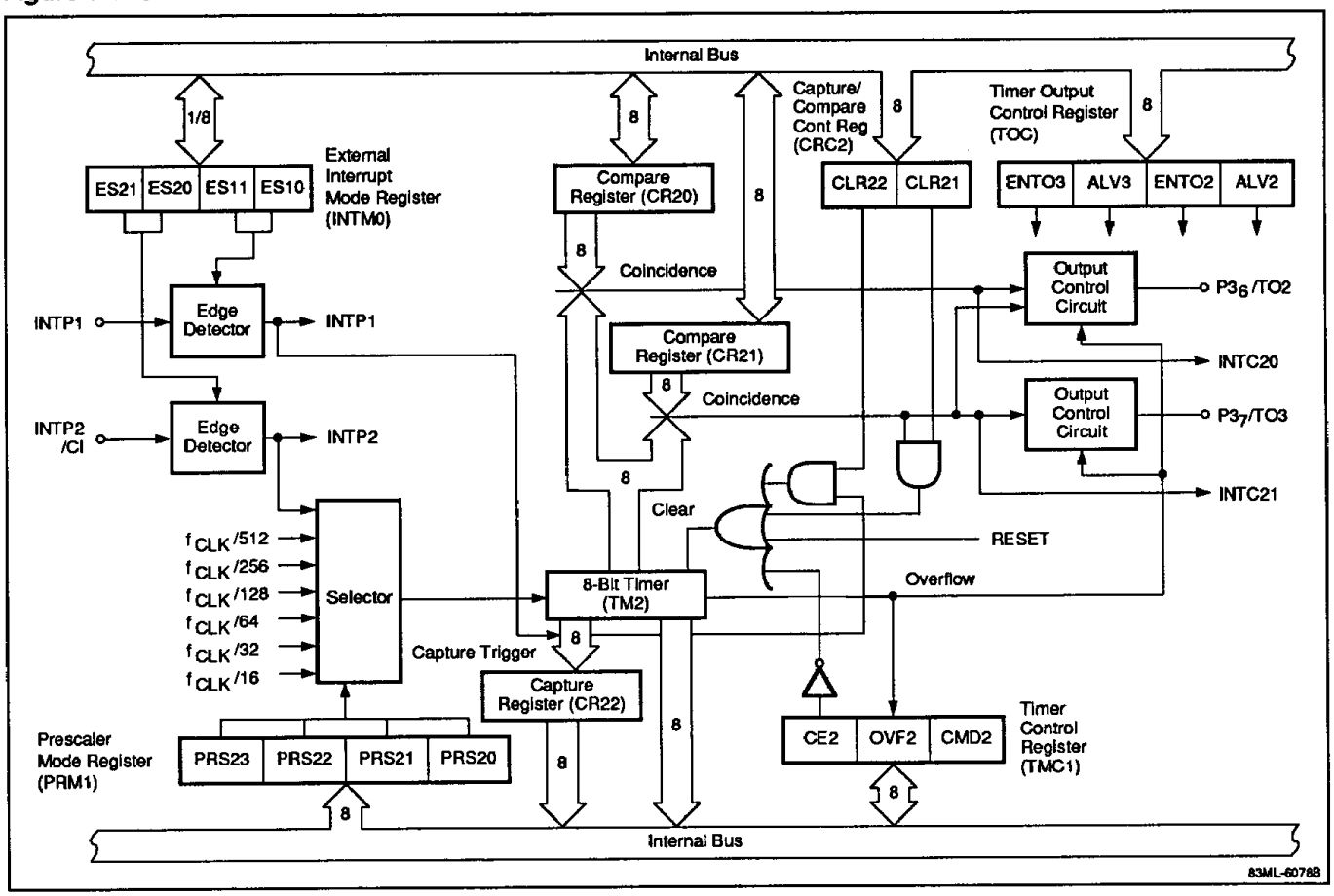


Figure 11. 8-Bit Timer/Counter 2



Interrupts

There are 20 interrupt request sources; each source is allocated a location in the vector table. (See table 2.) There is one software interrupt request and one of the remaining 19 interrupts is non-maskable. The software interrupt and the non-maskable interrupt are unconditionally received even in the DI state. These two interrupts possess the maximum priority. The maskable interrupt requests are subject to mask control by the setting of the interrupt mask flag.

There are default priorities associated with each maskable interrupt and these can be assigned to either of two programmable priority levels. Interrupts may be serviced by the vectored interrupt method where a branch to a desired service program is executed. Interrupts may also be handled by the macroservice function where a preassigned process is performed without program intervention.

Figure 12. 8-Bit Timer/Counter 3

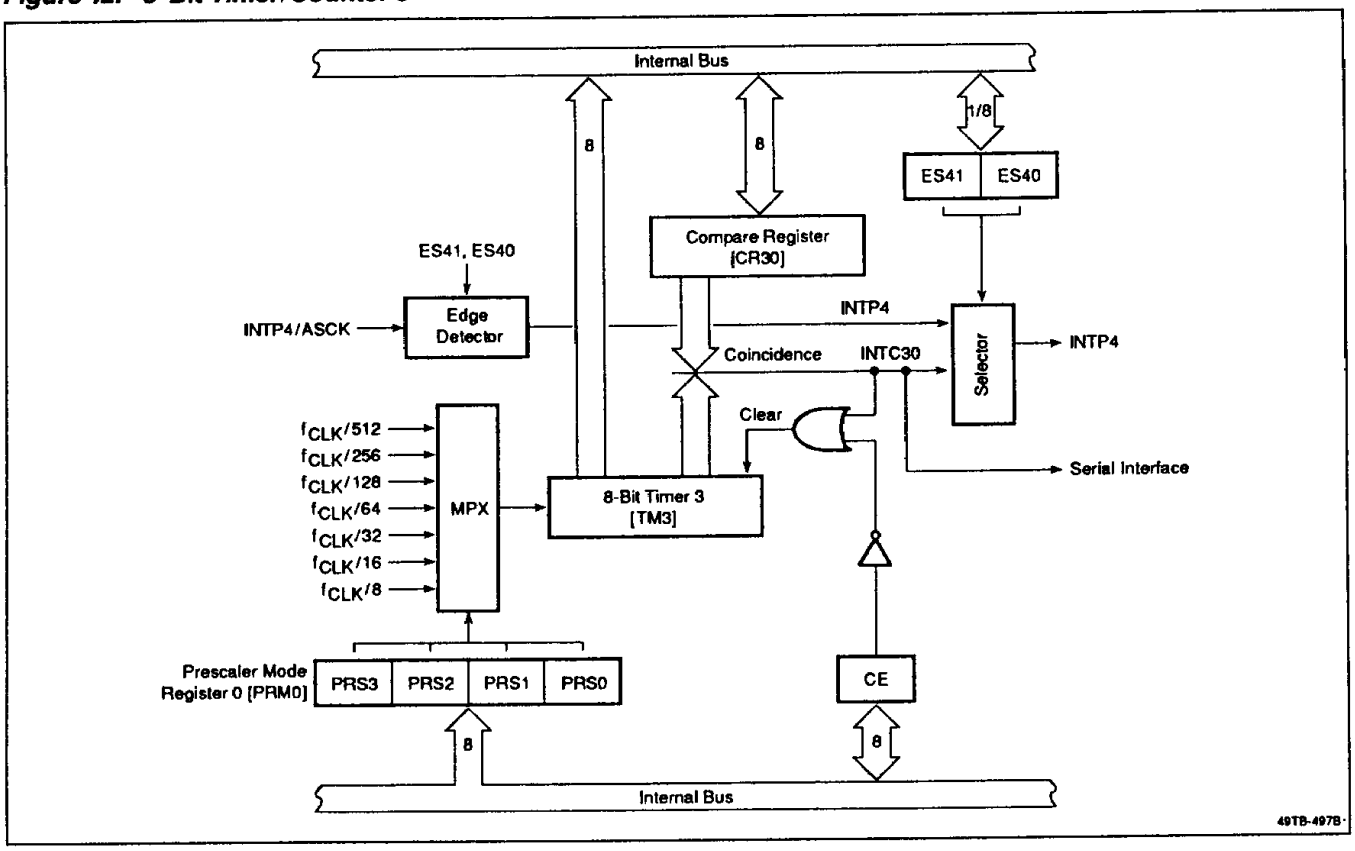


Table 2. Interrupt Sources and Vector Addresses

Interrupt Request Type	Default Priority	Interrupt Request Generation Source	Macroservice Mode	Vector Table Address
Software	None	BRK instruction execution	–	003EH
Non-maskable	None	NMI (pin input edge detection)	–	0002H
Maskable	0	INTP0 (pin input edge detection)	Yes	0006H
	1	INTP1 (pin input edge detection)	Yes	0008H
	2	INTP2 (pin input edge detection)	Yes	000AH
	3	INTP3 (pin input edge detection)	Yes	000CH
	4	INTC00 (TM0-CR00 coincidence signal generation)	Yes	0014H
	5	INTC01 (TM0-CR01 coincidence signal generation)	Yes	0016H
	6	INTC10 (TM1-CR10 coincidence signal generation)	Yes	0018H
	7	INTC11 (TM1-CR11 coincidence signal generation)	Yes	001AH
	8	INTC21 (TM2-CR21 coincidence signal generation)	Yes	001CH
	9	INTP4 (pin input edge detection)/INTC30 (TM3-CR30 coincidence signal generation)	Yes	000EH
	10	INTP5 (pin input edge detection)/INTAD (end of A/D conversion)	Yes	0010H
	11	INTC20 (TM2-CR20 coincidence signal generation)	Yes	0012H
	12	INTSER (generation of asynchronous serial interface receive error)	–	0020H
	13	INTSR (end of asynchronous serial interface reception)	Yes	0022H
	14	INTST (end of asynchronous serial interface transmission)	Yes	0024H
	15	INTCSI (end of clocked serial interface transmission)	Yes	0026H

Macroservice

The macroservice function can be programmed to transfer data from a special function register to memory or from memory to a special function register. Transfer events are triggered by interrupt requests and take place without software intervention. There are 17 interrupt requests where macroservicing can be executed. The macroservice function is controlled by the macroservice mode register and the macroservice channel pointer. The macroservice mode register assigns the macroservicing mode and the macroservice channel pointer indicates the address of the memory location pointers. The location of each register and its corresponding interrupt is shown in figure 13.

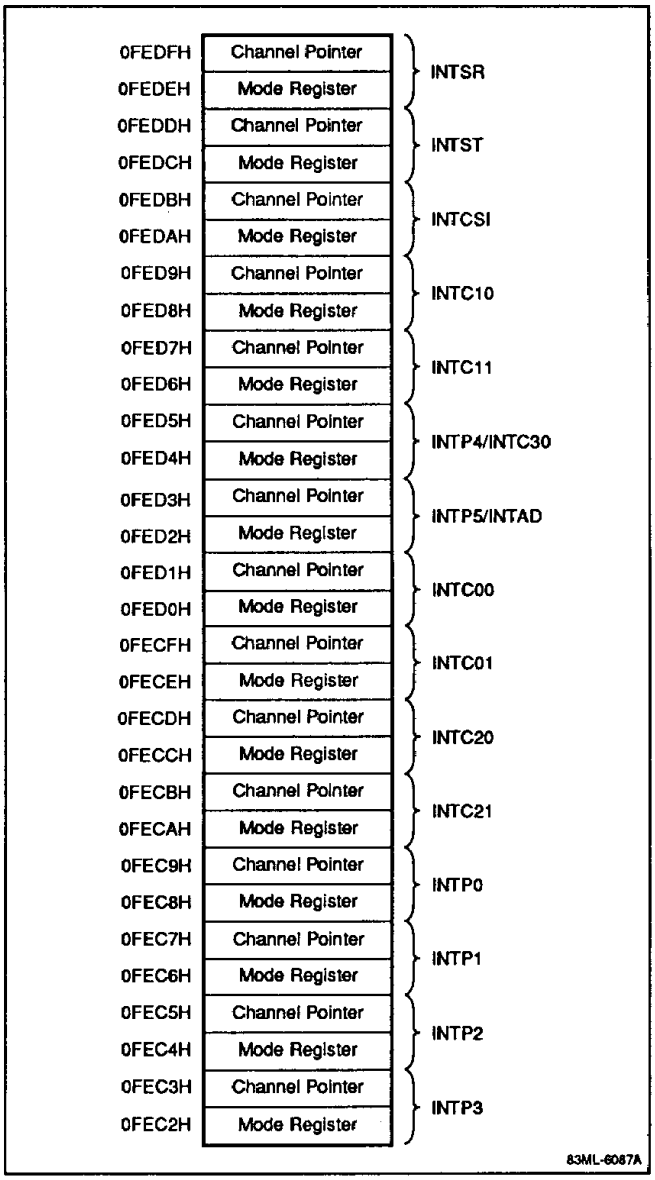
Refresh

The refresh signal is used with a pseudostatic RAM. The refresh cycle can be set to one of four intervals ranging from 2.6 to 21.3 μs. The refresh is timed to follow a read or write operation so there is no interference.

Standby Modes

Halt and stop functions reduce system power consumption. In the halt mode, the CPU stops and the system clock continues to run. A release of the halt mode is initiated by an unmasked interrupt request, an NMI, or a $\overline{\text{RESET}}$ input. In the stop mode, the CPU and system clock are both stopped, reducing the power consumption even further. The stop mode is released by an NMI input or a $\overline{\text{RESET}}$ input.

Figure 13. Macroservice Control Word Map



ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

T_A = +25°C.

Item	Symbol	Conditions	Rating	Unit
Power supply voltages	V_{DD}		−0.5 to +7.0	V
	AV_{DD}		AV_{SS} to V_{DD} + 0.5	V
	AV_{SS}		−0.5 to +0.5	V
Input voltage	V_{I1}		−0.5 to AV_{REF1} + 0.5	V
Output voltage	V_O		−0.5 to V_{DD} + 0.5	V
Low-level output current	I_{OL}	One output pin	15	mA
		All output pins total	100	mA
High-level output current	I_{OH}	One output pin	−10	mA
		All output pins total	−50	mA
A/D converter reference input voltage	AV_{REF1}		−0.5 to AV_{DD} +0.3	V
D/A converter reference input voltage	AV_{REF2}		−0.5 to V_{DD} + 0.3	V
	AV_{REF3}		−0.5 to V_{DD} + 0.3	V
Operating temperature	T_{OPT}		−40 to +85	°C
Storage temperature	T_{STG}		−65 to +150	°C

Operating Frequency

Oscillation Frequency	T_A	V_{DD}
f_{XX} = 4 to 12 MHz	−40 to +85°C	+5V ± 10%

Capacitance

T_A = +25°C; V_{DD} = V_{SS} = 0 V.

Item	Symbol	Typ	Max	Unit	Conditions
Input capacitance	C_I		20	pF	f = 1 MHz; pins not used for measurement are at 0 V
Output capacitance	C_O		20	pF	
Input/output capacitance	C_{IO}		20	pF	

DC Characteristics

$T_A = -40$ to $+85°C$; $V_{DD} = +5\ V \pm 10\%$; $V_{SS} = AV_{SS} = 0\ V$.

Item	Symbol	Conditions	Min	Typ	Max	Unit
Low-level input voltage	V_{IL}		0		0.8	V
High-level input voltage	V_{IH1}	Except pins in Note 1	2.2		V_{DD}	V
	V_{IH2}	Pins in Note 1	$0.8\ V_{DD}$		V_{DD}	V
Low-level output voltage	V_{OL1}	$I_{OL} = 2.0$ mA			0.45	V
	V_{OL2}	$I_{OL} = 8.0$ mA (pins in Note 2)			1.0	V
High-level output voltage	V_{OH1}	$I_{OH} = -1.0$ mA	$V_{DD}-1.0$			V
	V_{OH2}	$I_{OH} = -100\ \mu A$	$V_{DD}-0.5$			V
	V_{OH3}	$I_{OH} = -5.0$ mA (pins in Note 3)	2.0			V
Input leakage current	I_{LI}	$0V \le V_I \le V_{DD}$			±10	μA
Output leakage current	I_{LO}	$0V \le V_O \le V_{DD}$			±10	μA
AV_{REF} current	AI_{REF}	Operating mode, $f_{XX} = 12$ MHz		1.5	5.0	mA
V_{DD} power supply current	I_{DD1}	Operating mode, $f_{XX} = 12$ MHz		20	40	mA
	I_{DD2}	HALT mode, $f_{XX} = 12$ MHz		7	20	mA
Data retention voltage	V_{DDDR}	STOP mode	2.5		5.5	V
Data retention current	I_{DDDR}	STOP mode $V_{DDDR} = 2.5$ V		2	20	μA
		$V_{DDDR} = 5\ V \pm 10\%$		5	50	μA
Pullup resistor	R_L	$V_I = 0$ V	15	40	80	kΩ

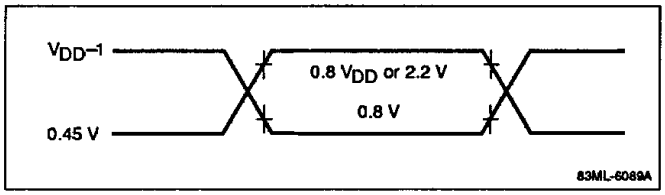
Notes:

(1) X1, X2, $\overline{RESET}$, $P2_0$/NMI, $P2_1$/INTP0, $P2_2$/INTP1, $P2_3$/INTP2/CI, $P2_4$/INTP3, $P2_5$/INTP4/ASCK, $P2_6$/INTP5, $P2_7$/SI, $P3_2/\overline{SCK}$, $P3_3$/SO/SB0, and $\overline{EA}$ pins.

(2) Pins $P1_0$-$P1_7$, $P4_0$-$P4_7/AD_0$-AD_7 and $P5_0$-$P5_7/A_8$-A_{15}.

(3) Pins $P0_0$-$P0_7$.

Figure 14. Voltage Thresholds for Timing Measurements



Read/Write Operation

T_A = −40 to +85°C; V_{DD} = +5 V ±10%; V_{SS} = 0 V; f_{XX} = 12 MHz; C_L = 100 pF. See figures 15, 16, and 17.

Item	Symbol	Conditions	Min	Max	Unit
X1 input clock cycle time	t_{CYX}		82	250	ns
Address setup time to ASTB ↓	t_{SAST}		52		ns
Address hold time from ASTB ↓ (Note 1)	t_{HSTA}	R_L = 5 kΩ, C_L = 50 pF	25		ns
Address to $\overline{RD}$ ↓ delay time	t_{DAR}		129		ns
Address float time from $\overline{RD}$ ↓	t_{FAR}		11		ns
Address to data input time	t_{DAID}			228	ns
ASTB ↓ to data input time	t_{DSTID}			181	ns
$\overline{RD}$ ↓ to data input time	t_{DRID}			99	ns
ASTB ↓ to $\overline{RD}$ ↓ delay time	t_{DSTR}		52		ns
Data hold time from $\overline{RD}$ ↑	t_{HRID}		0		ns
$\overline{RD}$ ↑ to address active time	t_{DRA}		124		ns
$\overline{RD}$ ↑ to ASTB ↑ delay time	t_{DRST}		124		ns
$\overline{RD}$ low-level width	t_{WRL}		124		ns
ASTB high-level width	t_{WSTH}		52		ns
Address to $\overline{WR}$ ↓ delay time	t_{DAW}		129		ns
$\overline{ASTB}$ ↓ to data output time	t_{DSTOD}			142	ns
$\overline{WR}$ ↓ to data output time	t_{DWOD}			60	ns
ASTB ↓ to $\overline{WR}$ ↓ delay time	t_{DSTW1}		52		ns
	t_{DSTW2}	Refresh mode	129		ns
Data setup time to WR ↑	t_{SODWR}		146		ns
Data setup time to $\overline{WR}$ ↓ (Note 1)	t_{SODWF}	Refresh mode	22		ns
Data hold time from $\overline{WR}$ ↑	t_{HWOD}		20		ns
$\overline{WR}$ ↑ to ASTB ↑ delay time	t_{DWST}		42		ns
WR low-level width	t_{WWL1}		196		ns
	t_{WWL2}	Refresh mode	114		ns
Address to $\overline{WAIT}$ ↓ input time	t_{DAWT}			146	ns
ASTB ↓ to $\overline{WAIT}$ ↓ input time	t_{DSTWT}			84	ns
$\overline{WAIT}$ hold time from X1 ↓	t_{HWTX}		0		ns
$\overline{WAIT}$ setup time to X1 ↑	t_{SWTX}		0		ns

Notes:

(1) The hold time includes the time during which V_{OH} and V_{OL} are retained under the following load conditions: C_L = 100 pF and R_L = 2 kΩ.

Figure 15. Read Operation Timing

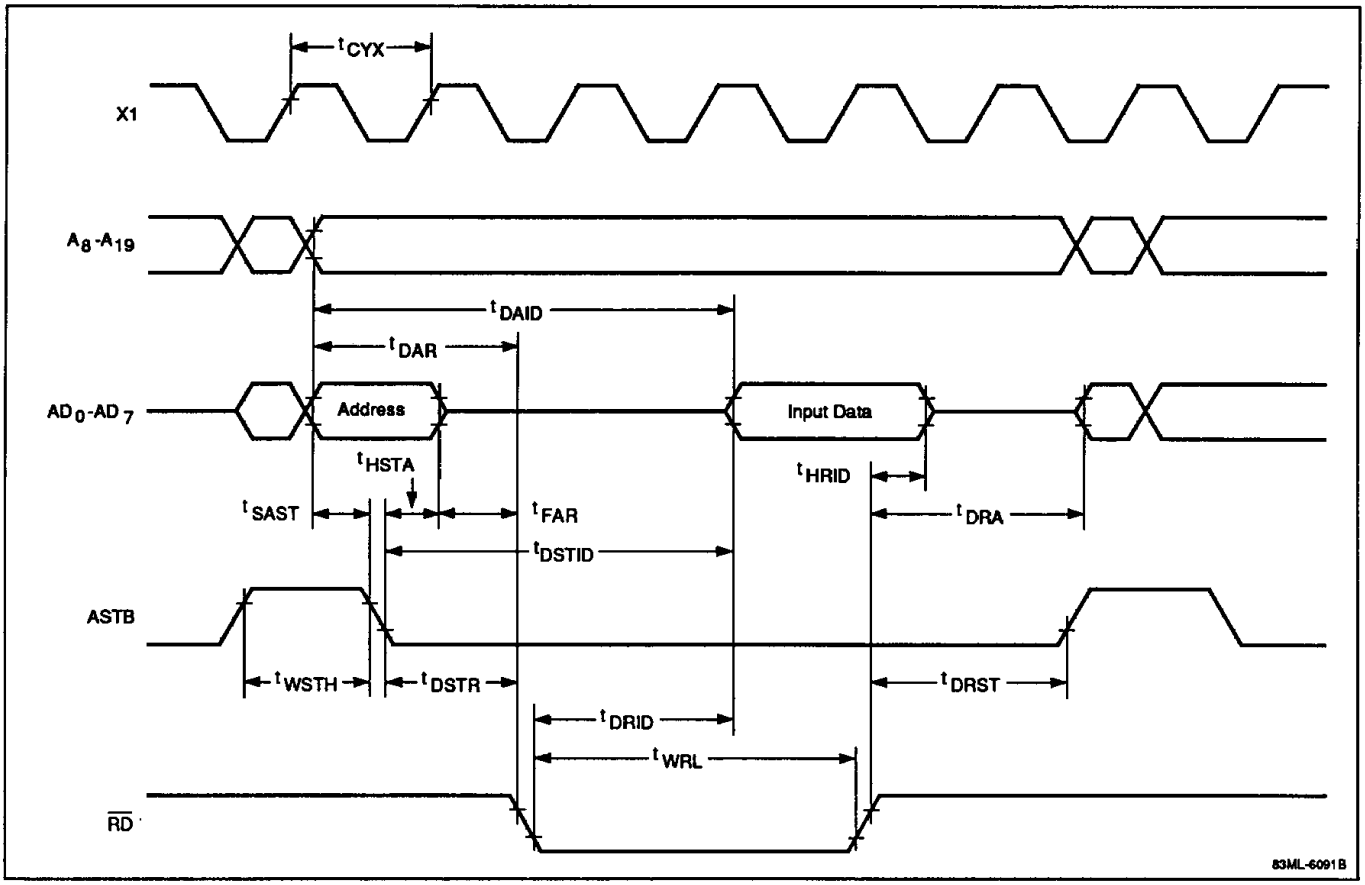


Figure 16. Write Operation Timing

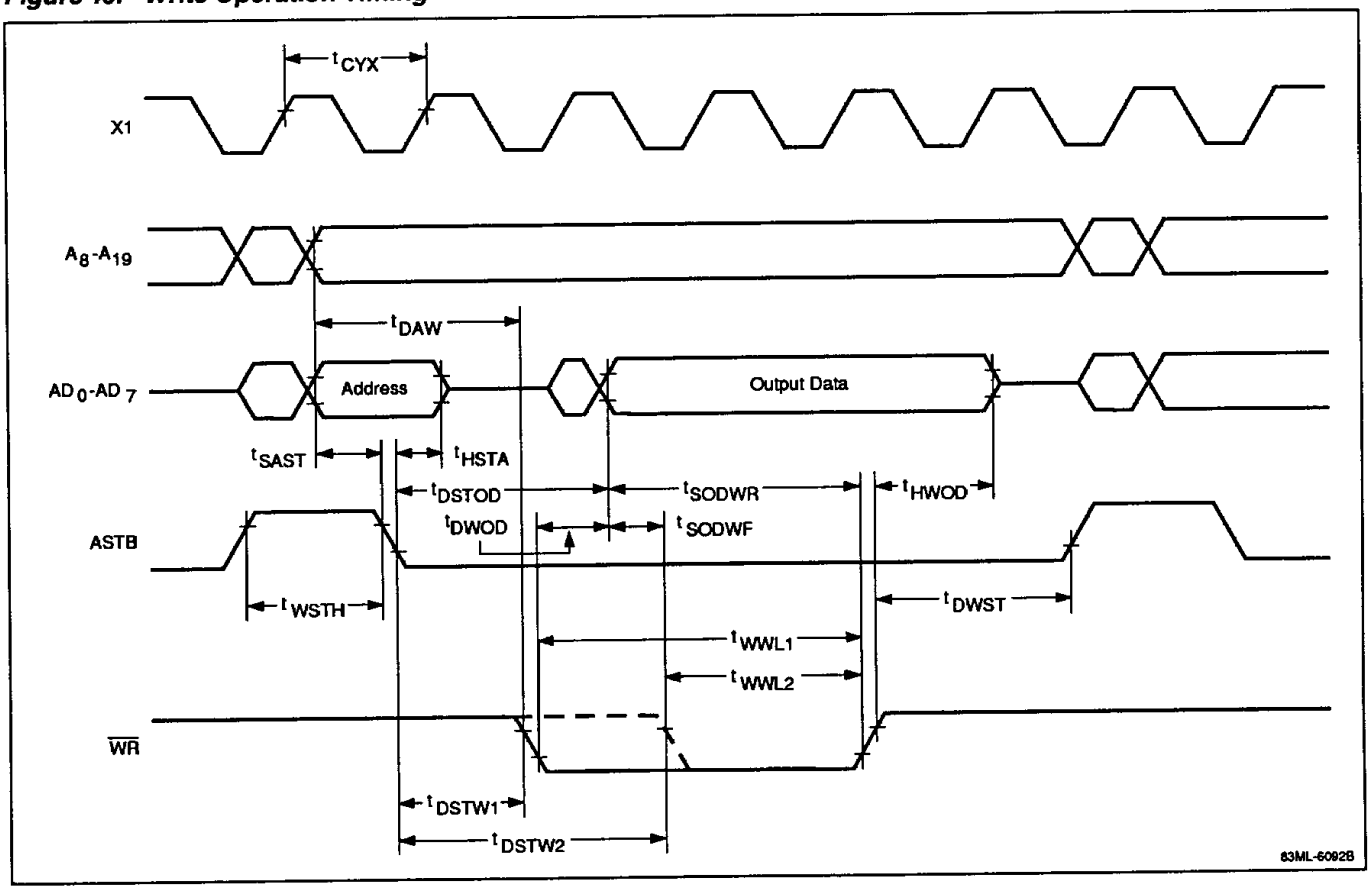
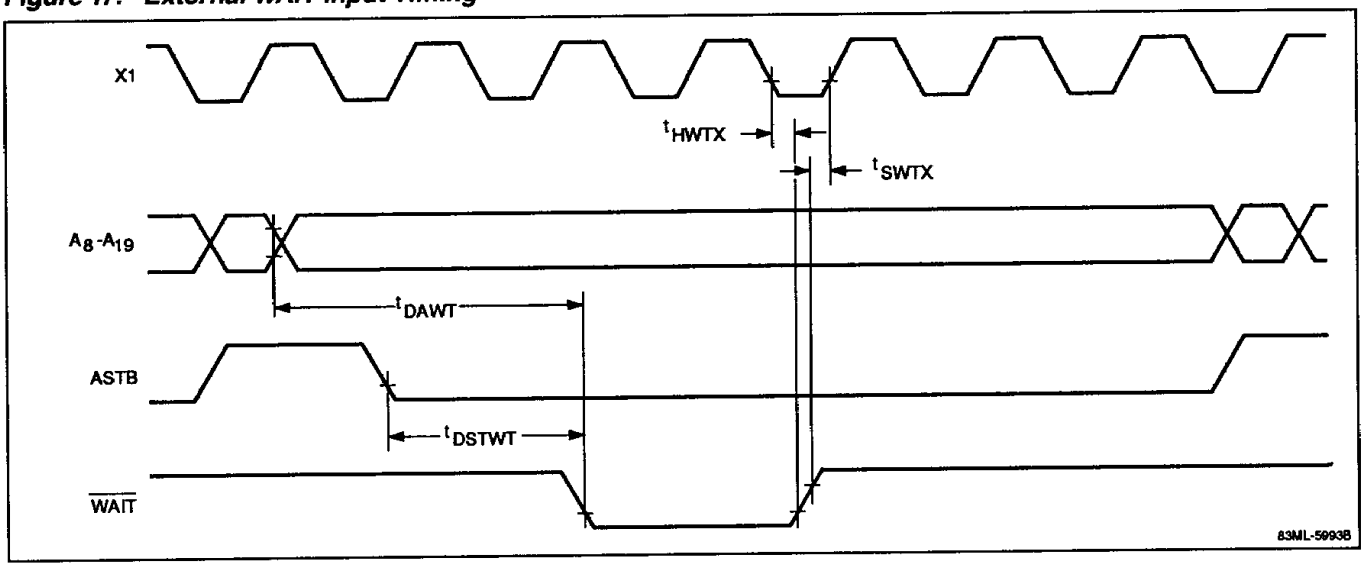


Figure 17. External WAIT Input Timing



Serial Port Operation

T_A = −40 to +85°C; V_{DD} = +5 V ± 10%; V_{SS} = 0 V; f_{XX} = 12 MHz; C_L = 100 pF. See figures 18, 19, and 20.

Item	Symbol	Conditions		Min	Max	Unit
Serial clock cycle time	t_{CYSK}	Input	External clock	1.0		μs
		Output	Internal clock/16	1.3		μs
			Internal clock/64	5.3		μs
Serial clock low-level width	t_{WSKL}	Input	External clock	420		ns
		Output	Internal clock/16	556		ns
			Internal clock/64	2.5		μs
Serial clock high-level width	t_{WSKH}	Input	External clock	420		ns
		Output	Internal clock/16	556		ns
			Internal clock/64	2.5		μs
SI, SB0 setup time to $\overline{SCK}$ ↑	t_{SSSK}			150		ns
SI, SB0 hold time from $\overline{SCK}$ ↑	t_{HSSK}			400		ns
SO/SB0 output delay time from $\overline{SCK}$ ↓	t_{DSBSK1}	CMOS push-pull output (3-line serial I/O mode)		0	300	ns
	t_{DSBSK2}	Open-drain output (SBI mode), R_L = 1 kΩ		0	800	ns
SB0 high, hold time from $\overline{SCK}$ ↑	t_{HSBSK}	SBI mode		4		t_{CYX}
SB0 low, setup time to $\overline{SCK}$ ↓	t_{SSBSK}	SBI mode		4		t_{CYX}
SB0 low-level width	t_{WSBL}			4		t_{CYX}
SB0 high-level width	t_{WSBH}			4		t_{CYX}
RxD setup time to $\overline{SCK}$ ↑	t_{SRXSK}			80		ns
RxD hold time after $\overline{SCK}$ ↑	t_{HSKRX}			80		ns
$\overline{SCK}$ ↓ to TxD delay time	t_{DSKTX}				210	ns

Figure 18. Clock-Synchronized Serial Interface Timing; Three-Line I/O Mode

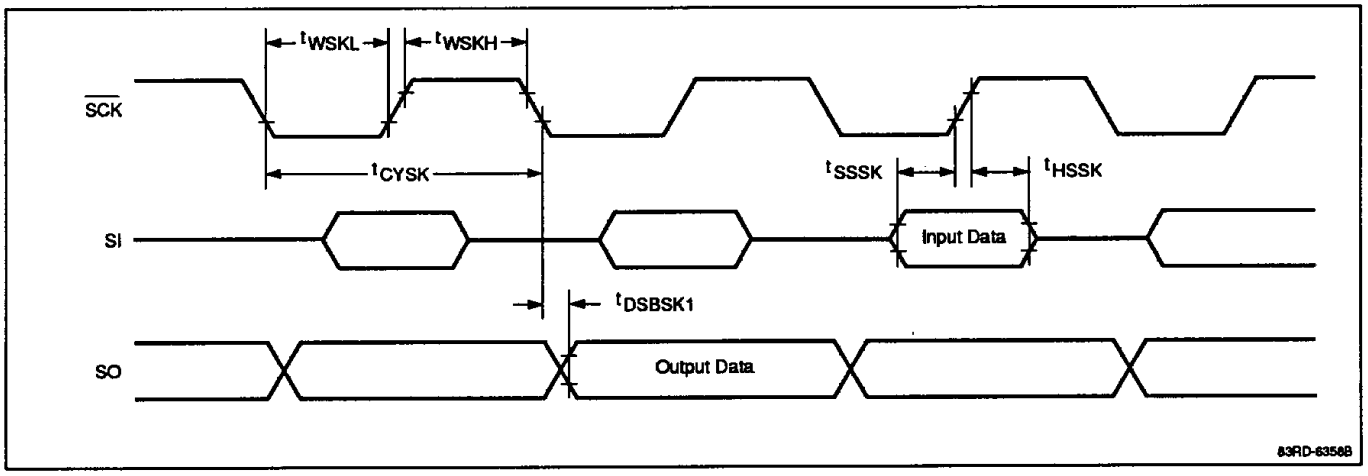


Figure 19. Clock-Synchronized Serial Interface Timing; SBI Mode

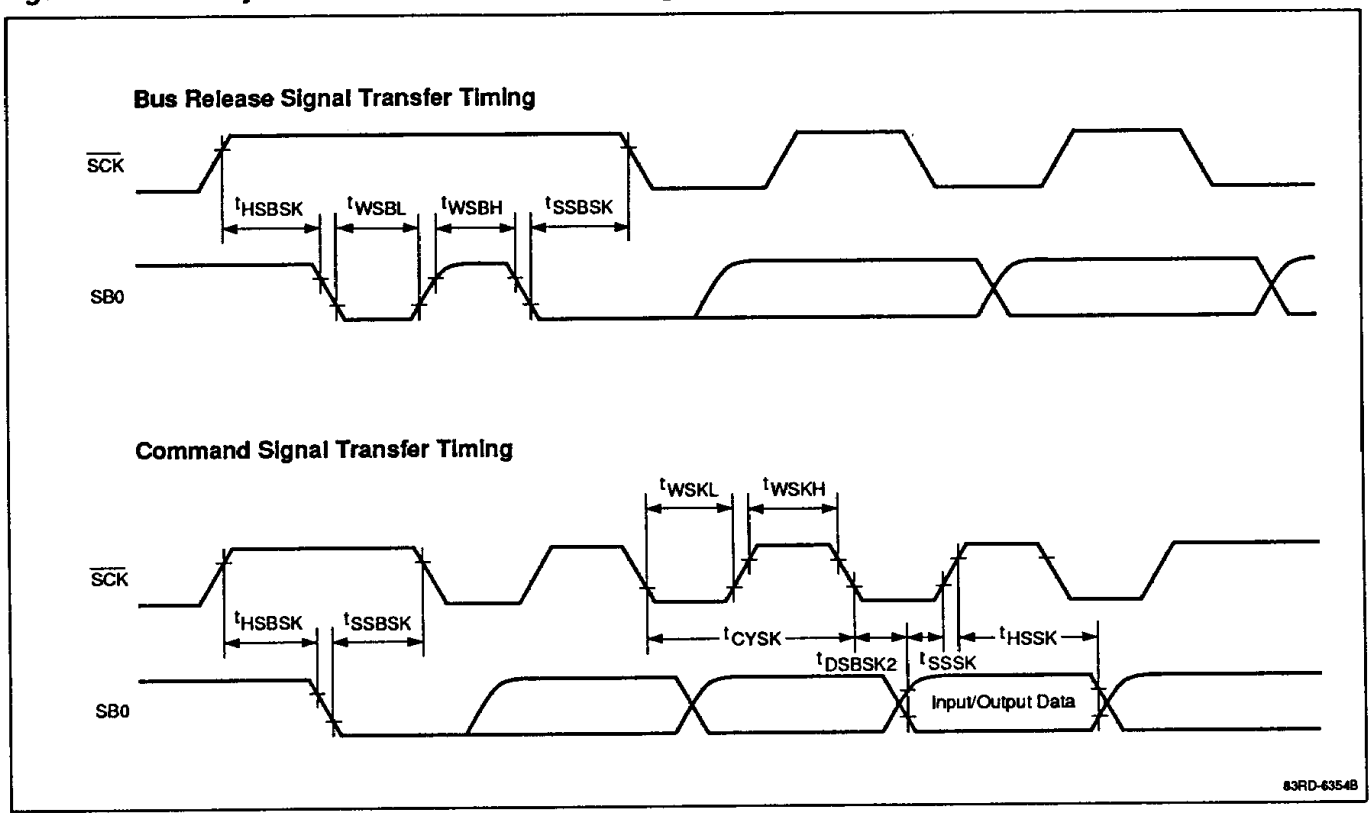
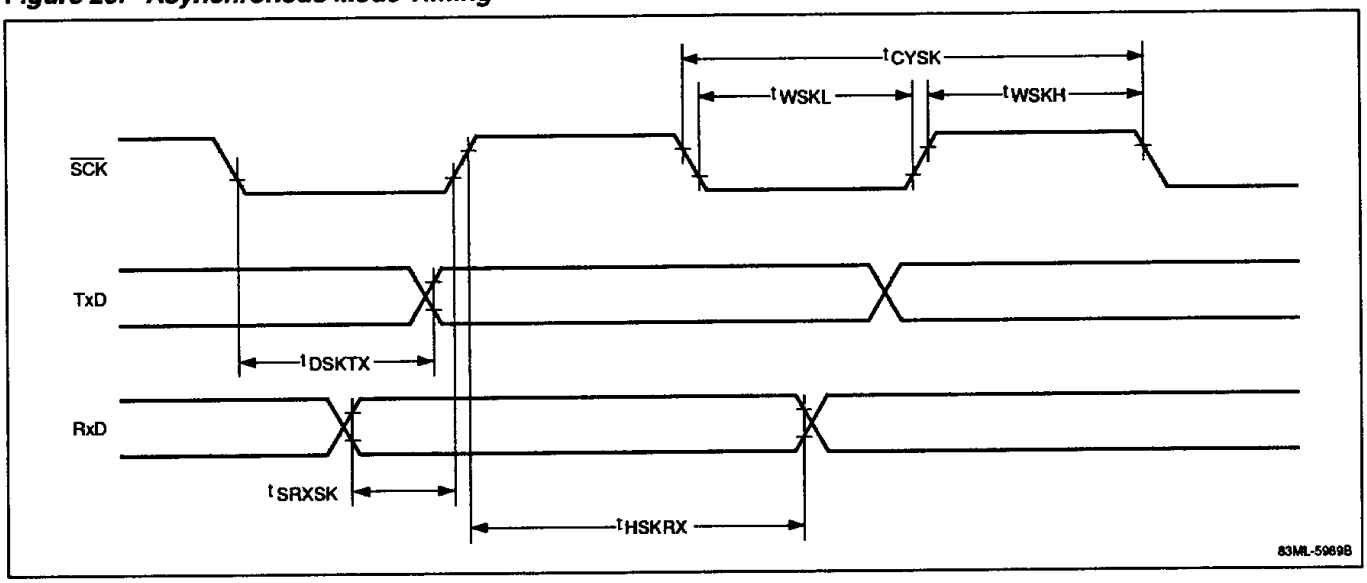


Figure 20. Asynchronous Mode Timing



A/D Converter Operation

T_A = −40 to +85°C; V_{DD} = + 5 V ±10%; V_{SS} = AV_{SS} = 0 V.

Item	Symbol	Conditions	Min	Typ	Max	Unit
Resolution			8			Bit
Full-scale error		AV_{REF} = 4.0 V to V_{DD}; T_A = −10 to +70°C			0.4	%
		AV_{REF} = 3.4 V to V_{DD}; T_A = −10 to +70°C			0.8	%
		AV_{REF} = 4.0 V to V_{DD}			0.8	%
Quantization error					±1/2	LSB
Conversion time	t_{CONV}	83 ns ≦ t_{CYX} ≦ 125 ns	360			t_{CYX}
		125 ns ≦ t_{CYX} ≦ 250 ns	240			t_{CYX}
Sampling time	t_{SAMP}	83 ns ≦ t_{CYX} ≦ 125 ns	72			t_{CYX}
		125 ns ≦ t_{CYX} ≦ 250 ns	48			t_{CYX}
Analog input voltage	V_{IAN}		0		AV_{REF}	V
Input impedance	R_{AN}			1000		MΩ
Analog reference voltage	AV_{REF}		3.4		V_{DD}	V
AV_{REF} current	AI_{REF}	Operating mode, f_{XX} = 12 MHz		1.5	5.0	mA
		STOP mode		0.2	1.5	mA

D/A Converter Operation

T_a = −40 to +85°C; AV_{REF2} = V_{DD} = +5 V ±10%; AV_{REF3} = V_{SS} = 0 V.

Item	Symbol	Conditions	Min	Typ	Max	Unit
Resolution					8	Bit
Absolute accuracy		AV_{REF2} = V_{DD} = 5 V; AV_{REF3} = V_{SS} = 0 V; Load conditions: 2 MΩ, 30 pF			1	LSB
		AV_{REF2} = 0.75 V_{DD}; AV_{REF3} = 0.25 V_{DD}; Load conditions: 2 MΩ, 30 pF				LSB
Settling time	Undefined				10	μs
Analog reference voltage	V_{AVREF2}		0.75 V_{DD}		V_{DD}	V
Analog reference voltage	V_{AVREF3}		0		0.25 V_{DD}	V
Reference power input current	AI_{REF2}		0		5	mA
Reference power input current	AI_{REF3}		−5.0		0	mA
Output resistance	R_O			24		kΩ

Interrupt Timing Operation

Item	Symbol	Conditions	Min	Max	Unit
NMI low-level width	t_{WNIL}		10		μs
NMI high-level width	t_{WNIH}		10		μs
INTP0-INTP5 low-level width	t_{WITL}		24		t_{CYX}
INTP0-INTP5 high-level width	t_{WITH}		24		t_{CYX}
$\overline{\text{RESET}}$ low-level width	t_{WRSL}		10		μs
$\overline{\text{RESET}}$ high-level width	t_{WRSH}		10		μs

Note: See figures 21 and 22.

Figure 21. Interrupt Input Timing

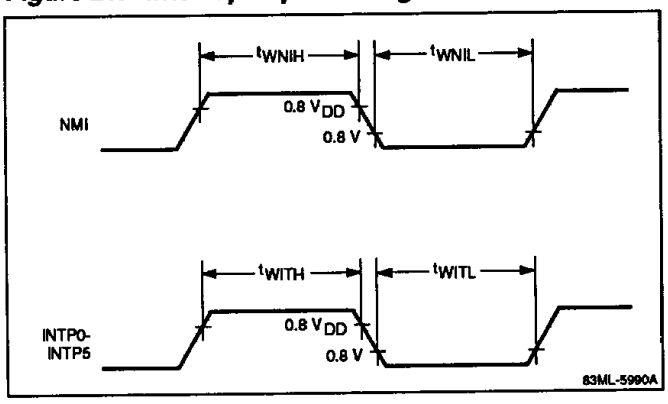
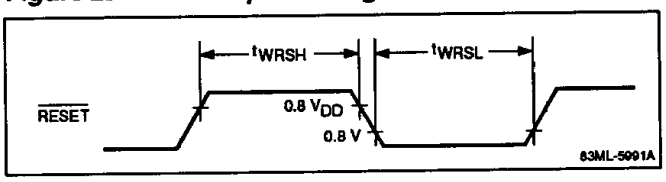


Figure 22. Reset Input Timing



Data Retention Characteristics

$T_A = -40$ to $+85$°C.

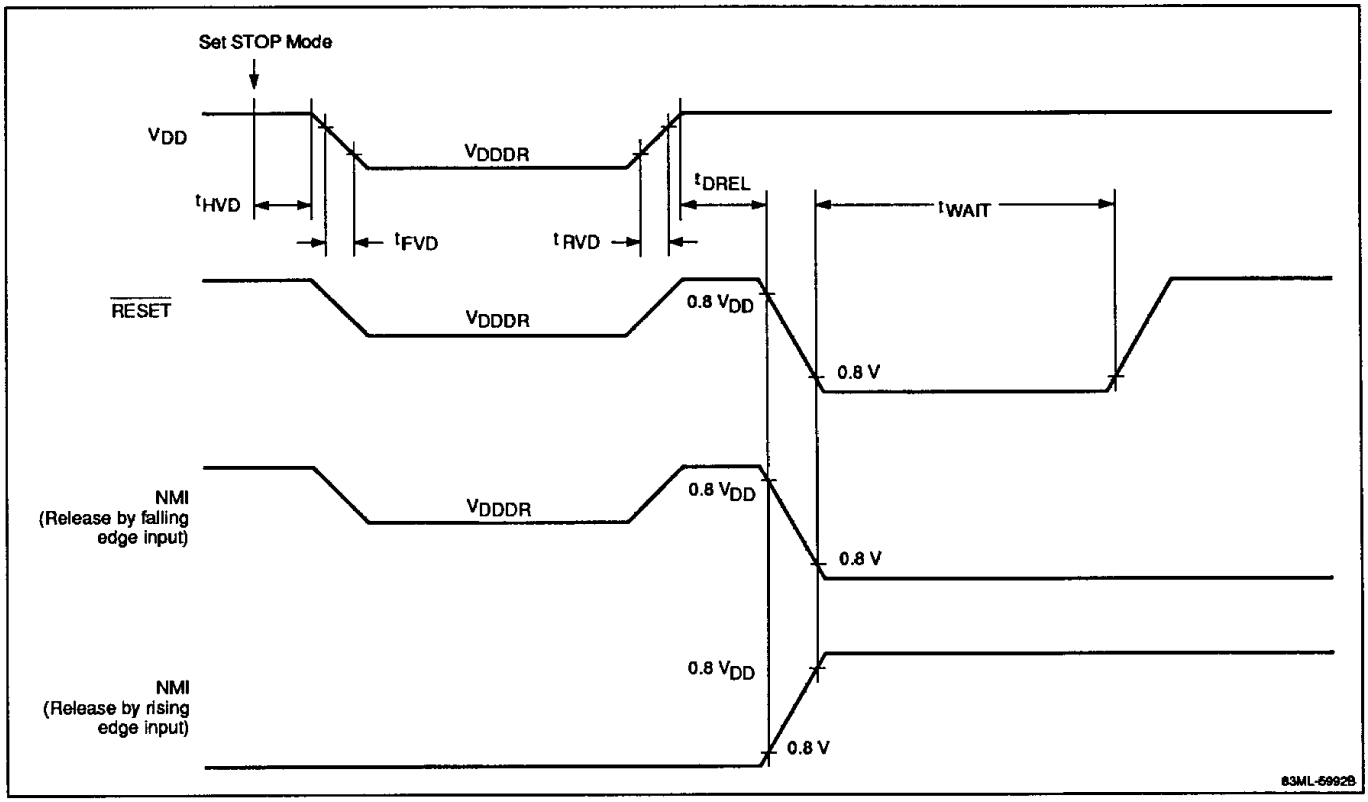
Item	Symbol	Conditions	Min	Typ	Max	Unit
Data retention voltage	V_{DDDR}	STOP mode	2.5		5.5	V
Data retention current	I_{DDDR}	V_{DDDR} = 2.5 V		2	15	μA
		V_{DDDR} = 5 V ± 10%		5	20	μA
V_{DD} rise time	t_{RVD}		200			μs
V_{DD} fall time	t_{FVD}		200			μs
V_{DD} retention time (for STOP mode setup)	t_{HVD}		0			ms
STOP release signal input time	t_{DREL}		0			ms
Oscillation stabilization wait time	t_{WAIT}	Crystal oscillator	30			ms
		Ceramic resonator	5			ms
Low-level input voltage	V_{IL}	Specified pins (Note 1)	0		0.1 V_{DDDR}	V
High-level input voltage	V_{IH}		0.9 V_{DDDR}		V_{DDDR}	V

Notes:

(1) $\overline{\text{RESET}}$, $P2_0$/NMI, $P2_1$/INTP0, $P2_2$/INTP1, $P2_3$/INTP2/CI, $P2_4$/INTP3, $P2_5$/INTP4/ASCK, $P2_6$/INTP5, $P2_7$/SI, $P3_2$/$\overline{\text{SCK}}$, $P3_3$/SO/SB0, and $\overline{\text{EA}}$ pins.

(2) See figure 23.

Figure 23. Data Retention Characteristics



Timing Dependent on t_{CYX}

Item	Symbol	Calculation Formula	Min/Max	12 MHz	Unit
X1 input clock cycle time	t_{CYX}		Min	82	ns
Address setup time to ASTB ↓	t_{SAST}	$t_{CYX}-30$	Min	52	ns
Address to $\overline{RD}$ ↓ delay time	t_{DAR}	$2t_{CYX}-35$	Min	129	ns
Address float time from $\overline{RD}$ ↓	t_{FAR}	$t_{CYX}/2-30$	Min	11	ns
Address to data input time	t_{DAID}	$(4+2n)\,t_{CYX}-100$	Max	228	ns
ASTB ↓ to data input time	t_{DSTID}	$(3+2n)\,t_{CYX}-65$	Max	181	ns
$\overline{RD}$ ↓ to data input time	t_{DRID}	$(2+2n)\,t_{CYX}-65$	Max	99	ns
ASTB ↓ to $\overline{RD}$ ↓ delay time	t_{DSTR}	$t_{CYX}-30$	Min	52	ns
$\overline{RD}$ ↑ to address active time	t_{DRA}	$2t_{CYX}-40$	Min	124	ns
$\overline{RD}$ ↑ to ASTB ↑ delay time	t_{DRST}	$2t_{CYX}-40$	Min	124	ns
$\overline{RD}$ low-level width	t_{WRL}	$(2+2n)\,t_{CYX}-40$	Min	124	ns
ASTB high-level width	t_{WSTH}	$t_{CYX}-30$	Min	52	ns
Address to $\overline{WR}$ ↓ delay time	t_{DAW}	$2t_{CYX}-35$	Min	129	ns
ASTB ↓ to data output time	t_{DSTOD}	$t_{CYX}+60$	Max	142	ns
ASTB ↓ to $\overline{WR}$ ↓ delay time	t_{DSTW1}	$t_{CYX}-30$	Min	52	ns
	t_{DSTW2}	$2t_{CYX}-35$ (refresh mode)	Min	129	ns
Data setup time to $\overline{WR}$ ↑	t_{SODWR}	$(3+2n)\,t_{CYX}-100$	Min	146	ns
Data setup time to $\overline{WR}$ ↓	t_{SODWF}	$t_{CYX}-60$ (refresh mode)	Min	22	ns
$\overline{WR}$ ↑ to ASTB ↑ delay time	t_{DWST}	$t_{CYX}-40$	Min	42	ns
$\overline{WR}$ low-level width	t_{WWL1}	$(3+2n)\,t_{CYX}-50$	Min	196	ns
	t_{WWL2}	$(2+2n)\,t_{CYX}-50$ (refresh mode)	Min	114	ns
Address to $\overline{WAIT}$ ↓ input time	t_{DAWT}	$3t_{CYX}-100$	Max	146	ns
ASTB ↓ to $\overline{WAIT}$ ↓ input time	t_{DSTWT}	$2t_{CYX}-80$	Max	84	ns

Notes:
(1) n indicates the number of wait states.

Figure 24. Recommended Oscillator Circuit

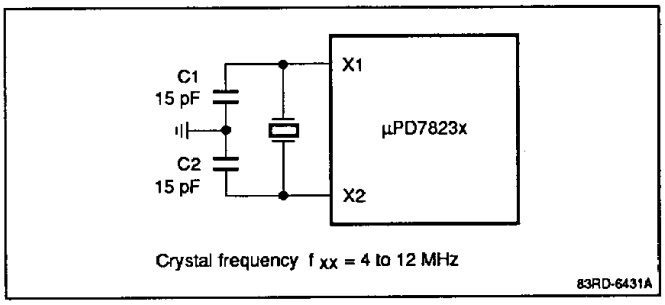
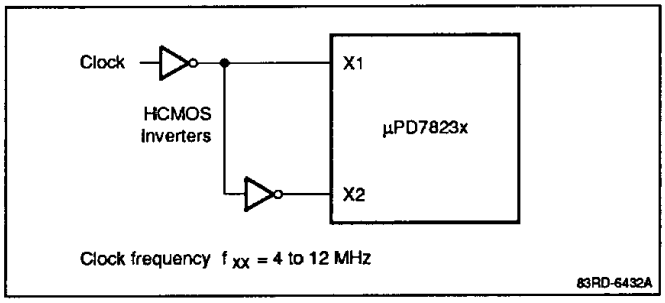


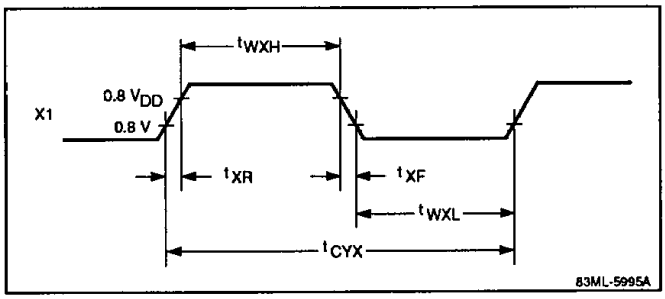
Figure 25. Recommended External Clock Circuit



External Clock Operation

Item	Symbol	Conditions	Min	Max	Unit
X1 input low-level width	t_{WXL}		30	130	ns
X1 input high-level width	t_{WXH}		30	130	ns
X1 input rise time	t_{XR}		0	30	ns
X1 input fall time	t_{XF}		0	30	ns
X1 input clock cycle time	t_{CYX}		82	250	ns

Figure 26. External Clock Timing



μPD78P238 PROGRAMMING

In the 78P238, the mask ROM of 78234 is replaced by a one-time programmable ROM (OTP ROM). The ROM is 32K × 8 bits and can be programmed using a general-purpose PROM writer with a μPD27C256A programming mode.

The PA-78P238GC/GJ/L are the socket adaptors used for configuring the μPD78P238 to fit a standard PROM socket.

Refer to tables 3 through 6 and figures 27 and 28 for special information applicable to PROM programming.

Table 3. Pin Functions During EPROM Programming

Pin		Function
$P0_0$-$P0_7$	A_0-A_7	Input pins for PROM write/verify operations
$P5_0/A_8$	A_8	Input pin for PROM write/verify operation
$P2_1$/INTP0	A_9	Input pin for PROM write/verify operation
$P5_2$-$P5_6/A_{10}$-A_{14}	A_{10}-A_{14}	Input pins for PROM write/verify operations
$P4_0$-$P4_7/AD_0$-AD_7	D_0-D_7	Data pins for PROM write/verify operations
$P6_5/\overline{WR}$	$\overline{CE}$	Strobe data into the PROM
$P6_4/\overline{RD}$	$\overline{OE}$	Enable a data read from the PROM
$P2_0$/NMI	NMI	PROM programming mode is entered by applying a high voltage to this pin
$\overline{RESET}$	$\overline{RESET}$	PROM programming mode requires applying a low voltage to this pin
$\overline{EA}$	V_{PP}	High voltage applied to this pin for program write/verify
V_{DD}	V_{DD}	Positive power supply pin
V_{SS}	V_{SS}	Ground

Table 4. Summary of Operation Modes for PROM Programming

Mode	NMI	RESET	CE	OE	V_{pp}	V_{DD}	D_0-D_7
Program write	+12.5 V	L	L	H	+12.5 V	+6 V	Data input
Program verify	+12.5 V	L	H	L	+12.5 V	+6 V	Data output
Program inhibit	+12.5 V	L	H	H	+12.5 V	+6 V	High Z
Read out	+12.5 V	L	L	L	+5 V	+5 V	Data output
Output disable	+12.5 V	L	L	H	+5 V	+5 V	High Z
Standby	+12.5 V	L	H	L/H	+5 V	+5 V	High Z

Notes:
When +12.5 V is applied to V_{pp} and +6 V to V_{DD}, both $\overline{CE}$ and $\overline{OE}$ cannot be set to low level (L) simultaneously.

Table 5. DC Programming Characteristics

T_A = 25 ±5°C, V_{IP} = 12.5 ±0.5 V applied to NMI pin, V_{SS} = 0 V.

Parameter	Symbol	Symbol*	Condition	Min	Typ	Max	Unit
High-level input voltage	V_{IH}	V_{IH}		2.4		V_{DDP} +0.3	V
Low-level input voltage	V_{IL}	V_{IL}		−0.3		0.8	V
Input leakage current	V_{LIP}	V_{LI}	$0 \le V_I \le V_{DDP}$			10	μA
High-level output voltage	V_{OH1}	V_{OH}	I_{OH} = −400 μA	2.4			V
	V_{OH2}	V_{OH2}	I_{OH} = −100 μA	V_{DD} −0.7			V
Low-level output voltage	V_{OL}	V_{OL}	I_{OH} = 2.1 mA			0.45	V
Output leakage current	I_{LO}		$0 \le V_O \le V_{DPP}$, $\overline{OE} = V_{IH}$			10	μA
NMI pin high-voltage input current	I_{IP}					±10	μA
V_{DDP} power voltage	V_{DDP}	V_{CC}	Program memory write mode	5.75	6.0	6.25	V
			Program memory read mode	4.5	5.0	5.5	V
V_{PP} power voltage	V_{PP}	V_{PP}	Program memory write mode	12.2	12.5	12.8	V
			Program memory read mode		$V_{PP} = V_{DDP}$		V
V_{DDP} power current	I_{DD}	I_{CC}	Program memory write mode		5	30	mA
			Program memory read mode $\overline{CE} = V_{IL}$, $V_I = V_{IH}$		5	30	mA
V_{PP} power current	I_{PP}	I_{PP}	Program memory write mode $\overline{CE} = V_{IL}$, $\overline{OE} = V_{IH}$		5	30	mA
			Program memory read mode		1	100	μA

* Corresponding symbols of the μPD27C256A.

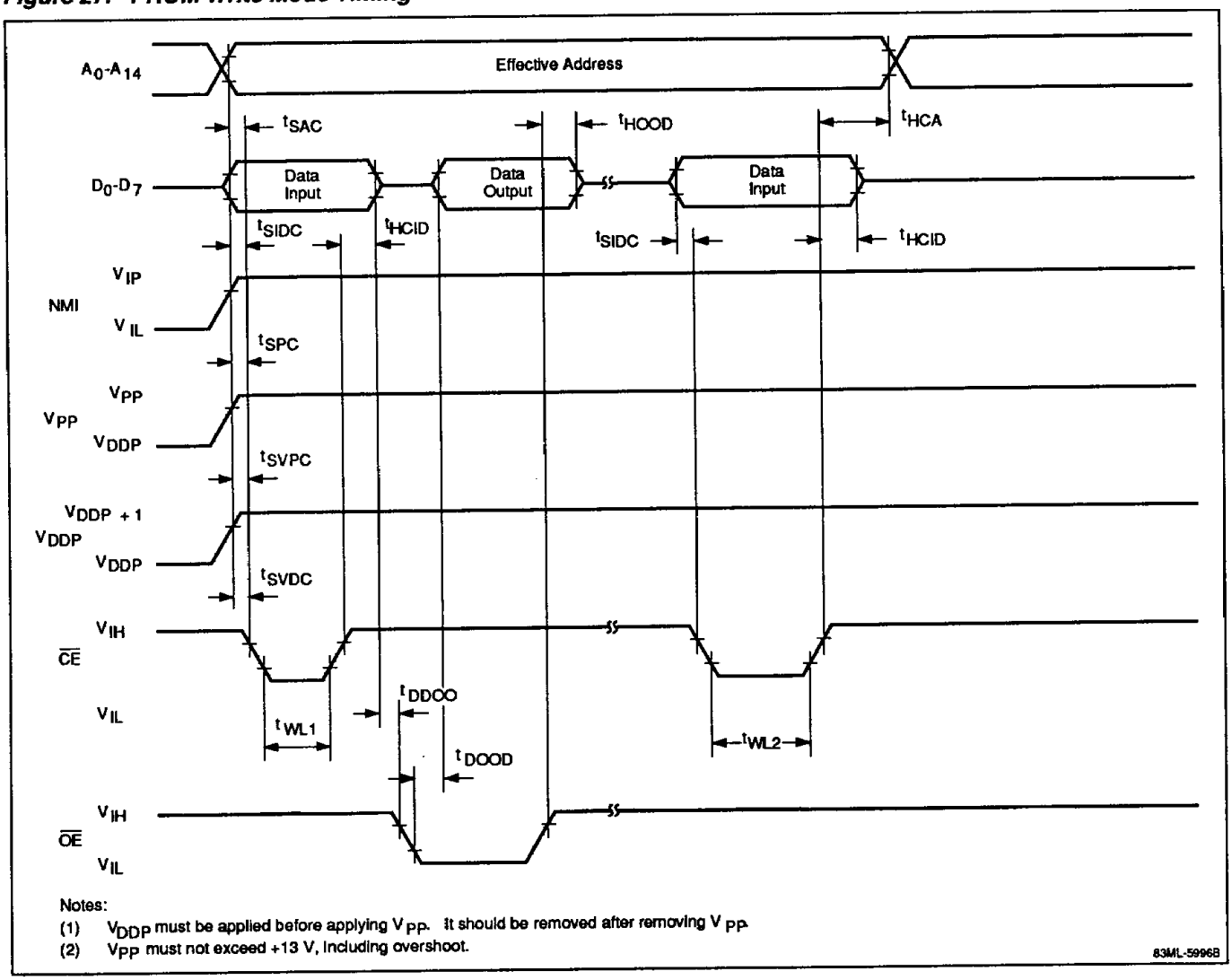
Table 6. AC Programming Characteristics

T_A = 25 ±5°C, V_{IP} = 12.5 ±0.5 V applied to NMI pin, V_{SS} = 0 V, V_{DD} = 6 ±0.25 V, V_{PP} = 12.5 ±0.3 V.

Parameter	Symbol	Symbol*	Condition	Min	Typ	Max	Unit
Address setup time to $\overline{CE}$ ↓	t_{SAC}	t_{AS}		2			μs
Data to $\overline{OE}$ ↓ delay time	t_{DDOO}	t_{OES}		2			μs
Input data setup time to $\overline{CE}$ ↓	t_{SIDC}	t_{DS}		2			μs
Address hold time from $\overline{CE}$ ↑	t_{HCA}	t_{AH}		2			μs
Input data hold time from $\overline{CE}$ ↑	t_{HCID}	t_{DH}		2			μs
Output data hold time to $\overline{OE}$ ↑	t_{HOOD}	t_{DF}		0		130	ns
V_{PP} setup time to $\overline{CE}$ ↓	t_{SVPC}	t_{VPS}		1			ms
V_{DDP} setup time to $\overline{CE}$ ↓	t_{SVDC}	t_{VDS}		1			ms
Initial program pulse width	t_{WL1}	t_{PW}		0.95	1.0	1.05	ms
Additional program pulse width	t_{WL2}	t_{OPW}		2.85		78.75	ms
NMI high-voltage input setup time (vs. $\overline{CE}$ ↓)	t_{SPC}			2			μs
Address to data output time	t_{DAOD}	t_{ACC}	$\overline{CE} = \overline{OE} = V_{IL}$			200	ns
$\overline{CE}$ ↓ to data output time	t_{DCOD}	t_{CE}	$\overline{OE} = V_{IL}$			200	ns
$\overline{OE}$ ↓ to data output time	t_{DOOD}	t_{OE}	$\overline{CE} = V_{IL}$			75	ns
Data hold time from $\overline{OE}$ ↑	t_{HCOD}	t_{DF}	$\overline{CE} = V_{IL}$	0		60	ns
Data hold time from address	t_{HAOD}	t_{OH}	$\overline{CE} = \overline{OE} = V_{IL}$	0			ns

* Corresponding symbols of the μPD27C256A.

Figure 27. PROM Write Mode Timing



Notes:
(1) V_{DDP} must be applied before applying V_{PP}. It should be removed after removing V_{PP}.
(2) V_{PP} must not exceed +13 V, including overshoot.

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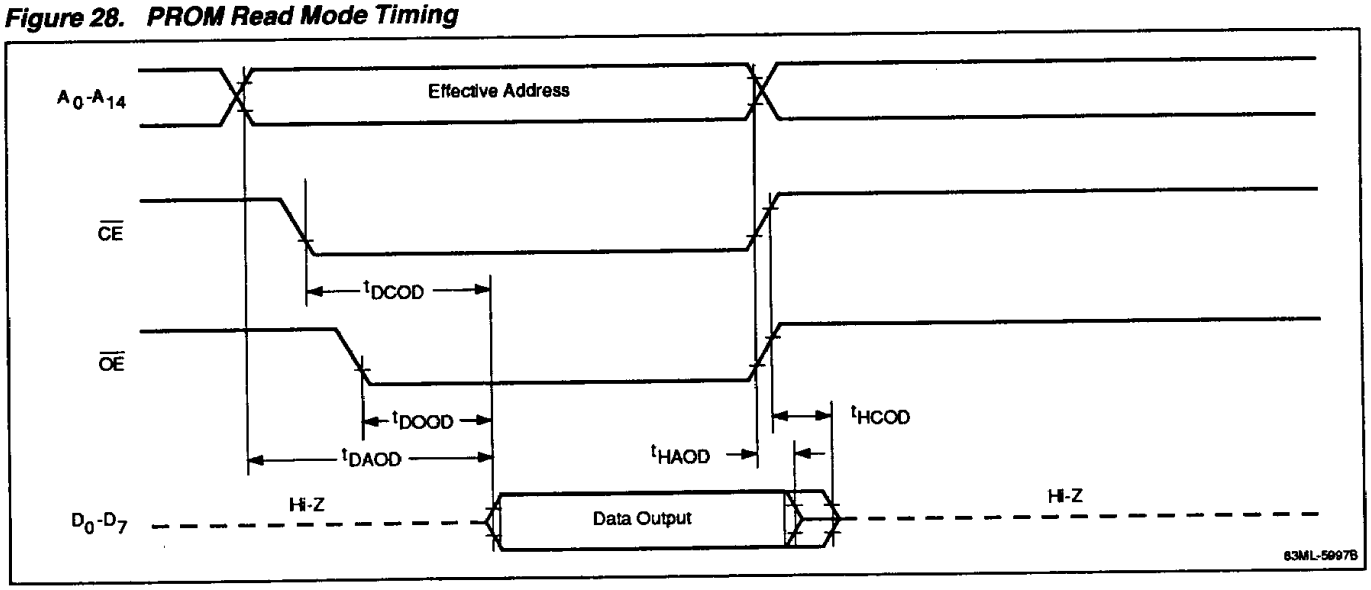
Figure 28. PROM Read Mode Timing



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PROM Write Procedure

(1) Connect the $\overline{\text{RESET}}$ pin to a low level and apply +12.5 V to the NMI pin.

(2) Apply +6 V to the V_{DD} pin and +12.5 V to the V_{pp} pin.

(3) Provide the initial address.

(4) Provide write data.

(5) Provide 1-ms program pulse (active low) to the $\overline{\text{CE}}$ pin.

(6) This bit is now verified with a pulse (active low) to the $\overline{\text{OE}}$ pin. If the data has been written, proceed to step 8; if not, repeat steps 4 to 6. If the data cannot be correctly written after 25 attempts, go to step 7.

(7) Classify as defective and stop write operation.

(8) Provide write data and supply program pulse (for additional writing) for 3 ms times the number of repeats performed between steps 4 to 6.

(9) Increment the address.

(10) Repeat steps 4 to 9 until the end address.

PROM Read Procedure

(1) Fix the $\overline{\text{RESET}}$ pin to a low level and apply +12.5 V to the NMI pin.

(2) Apply +5 V to the V_{DD} and V_{pp} pins.

(3) Input the address of the data to be read to pins A_0-A_{14}.

(4) Read mode is entered with a pulse (active low) on both the $\overline{\text{CE}}$ and $\overline{\text{OE}}$ pins.

(5) Data is output to the D_0 to D_7 pins.

INSTRUCTION SET

All microcomputers in the μPD7823x family have a 1-byte instruction lookahead buffer. This allows the first byte of the next opcode in program memory to be fetched while the current opcode is being executed. This pipeline architecture allows instruction fetch and excute cycles to overlap. An instruction can be fetched from program memory while data is being read from or written to RAM or an I/O port.

The advantage of the pipeline is that one instruction can be executed while another is being fetched, virtually halving the time required for these two operations and thereby reducing overall program execution time.

Operands and Operations

Refer to tables 7 and 8 for the meanings of symbols in the operand and operations columns of the Instruction Set table.

Specify operands in accordance with the rules of operand representation; for details, refer to the assembler specifications. If two or more description methods are available, select one. The symbols +, –, #, !, $, /, [ ], and & are keywords and must be used in conjunction with each instruction.

When describing immediate data as a label, use one of the following modifiers: +, –, #, !, $, /, [ ], and &. Symbols r and rp can be described in both the function name and absolute name.

Table 7. Operands

Symbol	Meaning
+	Autoincrement
–	Autodecrement
#	Immediate data
!	Absolute address
$	Relative address
/	Bit inversion
[ ]	Indirect addressing
&	Subbank
r	Register Function name: X, A, C, B, E, D, L, H Absolute name: R0 to R7
r1	Register group 1: C, B
rp	Register pair Function name: AX, BC, DE, HL Absolute name: RP0 to RP3
sfr	Special function register: P0, P2-P7, P0H, P0L, RTPC, CR10, CR11, CR20, CR21, CR22, CR30, PM0, PM3, PM5, PM6, PMC3, PUO, CRC0-CRC2, TOC, TM1-TM3, TMC0, TMC1, PRM0, PRM1, ADM, ADCR, CSIM, SBIC, SIO, ASIM, ASIS, RxB, TxS, BRGC, STBC (dedicated instruction only), MM, PW, RFM, IF0L, IF0H, MK0L, MK0H, PR0L, PR0H, ISM0L, ISM0H, INTM0, INTM1, IST

Table 7. Operands (cont)

Symbol	Meaning
sfrp	Special function register pair: CR00-CR02, TM0, IF0, MK0, PR0, ISM0
mem	Memory address indirectly addressed Register indirect mode: [DE], [HL], [DE+], [HL+], [DE–], [HL–] Base mode: [DE+byte], [HL+byte], [SP+byte] Indexed mode: word[A], word[B], word[DE], word[HL]
mem1	Memory address addressed by means of indirect addressing group 1: [DE], [HL]
saddr	Memory address indirectly addressed: FE20H-FF1FH immediate data or label
saddrp	Memory address addressed by means of direct addressing pair: FE20H-FF1EH immediate data (LSB=0; odd address) or label
addr16	16-bit address: 0000H-FEFFH immediate data or label
addr11	11-bit address: 800H-FFFH immediate data or label
addr5	5-bit address: 40H-7EH immediate data or label
word	16-bit data: 16-bit immediate data or label
byte	8-bit data: 8-bit immediate data or label
bit	3-bit data: 3-bit immediate data or label
n	Number of shift bits: 3-bit immediate data (0-7)
RBn	Register bank: RB0-RB3

Table 8. Registers and Flags

Symbol	Meaning
A	A register; 8-bit accumulator
X	X register
B	B register
C	C register
D	D register
E	E register
H	H register
L	L register
R0-R7	Registers 0 to 7 (absolute names)
AX	Register pair (AX); 16-bit accumulator
BC	Register pair (BC)
DE	Register pair (DE)
HL	Register pair (HL)
RP0-RP3	Register pairs 0 to 3 (absolute names)
PC	Program counter
SP	Stack pointer
PSW	Program status word
CY	Carry flag
AC	Auxiliary flag
Z	Zero flag
RBS1-RBS0	Register bank select flags
IE	Interrupt enable flag
STBC	Standby control register

Table 8. Registers and Flags (cont)

Symbol	Meaning
( )	Memory contents indicated by address or register contents in ( )
xxH	Hexadecimal number
x_H, x_L	Higher 8 bits and lower 8 bits of 16-bit register pair

Clocks

The clock field specifies the number of clocks required under the conditions defined by the four column headings as follows:

IROM Program in internal ROM is executed.

IRAM Program in external ROM is executed and internal RAM is accessed.

SFR Program in external ROM is executed and special function register is accessed.

EMEM Program in external ROM is executed and external memory is accessed.

In a shift/rotate instruction, n in the clock field indicates the number of bits by which data is shifted.

The hyphen (-) indicates a range of values; for example 10-13 means 10, 11, 12, or 13.

The virgule symbol (/) means either/or; for example, a/b means either a or b.

The number of clocks when execution is branched by a conditional branch instruction is shown after the symbol (/).

The number of clocks for instruction having the saddr or saddrp operand and when an SFR is accessed with FF00H to FFFFH described as saddr or saddrp is shown after the symbol (/).

Bytes and Clocks

The number of bytes and clocks for instructions with a mem or &mem operand depends on the particular instruction and the memory addressing mode (register indirect, base, or indexed). Table 9 is applicable when the program in internal ROM is executed (ROM clock column of the Instruction Set table). Table 10 is applicable when the program in external ROM is executed (IRAM, SFR, and EMEM clock columns).

Flags

The symbols in the flag field have the following meanings.

Blank No change
0 Cleared to 0
1 Set to 1
x Set or cleared depending on the result
R Value previously saved is restored

Operation Codes

Table 11 defines the symbols used in the operation code field.

Registers and Register Pairs. The r, rl, and rp operands are specified in the opcode by one or more bits as shown in figure 29. For example, 001 as bits $R_2R_1R_0$ (or $R_6R_5R_4$) specifies register A.

In the first and second operands are registers or register pairs; the higher 4 bits of the register specification byte define the first operand and the lower 4 bits define the second operand. For example, in the MOV A,L instruction (transfer L register contents to register A), the second byte of the opcode is obtained from figure 29 as shown below.

Instruction	Opcode, Bytes 1 and 2
MOV r,r	0 0 1 0 0 1 0 0
	0 $R_6R_5R_4$ 0 $R_2R_1R_0$
MOV A,L	0 0 1 0 0 1 0 0
	0 0 0 1 0 1 1 0

Memory Addressing Modes. The 3-bit mem code and the 5-bit mod code are selected from figure 30 according to the description of mem in the operand field (table 7).

A MOV instruction with register indirect mode specified for mem is a special 1-byte instruction. When base mode or indexed mode is specified for mem, the 8-bit or 16-bit offset data corresponding to byte and word, respectively, is added from the third byte onward.

The opcode for an &mem or &mem1 operand is modified by inserting a 01H code as the first byte preceding the first-byte code listed in the Instruction Set table. Subsequent bytes are as shown in the table.

Figure 29. Opcodes for Registers (r, r1, rp)

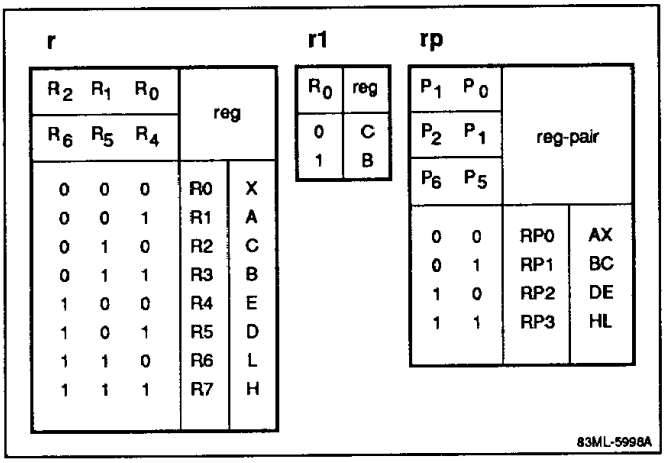


Figure 30. Opcodes for Memory Addressing Modes (mem, mod)

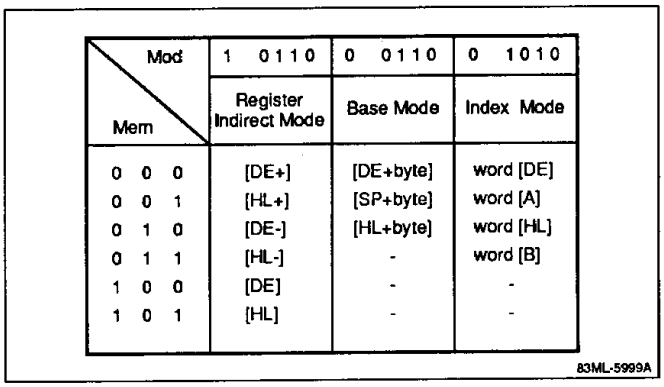


Table 9. Bytes and Clocks for Instructions With "mem" and "&mem" Operands; Internal ROM (IROM)

	Instruction		Register Indirect Mode		Base Mode		Indexed Mode
			[DE+] [HL+] [DE–] [HL–]	[DE] [HL]	[DE+byte] [HL+byte]	[SP+byte]	word[A] word[B] word[DE] word[HL]
Bytes		mem	1/2*	1/2*	3	3	4
		&mem	2/3*	2/3*	4	4	5
Clock Cycles	MOV	A, mem	6/8	6/8	8-11	9-12	8-11
		mem, A					
		A, &mem	8/10	8/10	10-13	11-14	10-13
		&mem, A					
	XCH	A, mem	11-15	9-13	10-15	11-16	10-15
		A, &mem	13-17	11-15	12-17	13-18	12-17
	ADD, ADDC, SUB, SUBC, AND, OR, XOR, CMP	A, mem	10/12	8/12	9/12	10-13	9-12
		A, &mem	12/14	10/14	11/14	12-15	11-14

* When internal RAM is accessed with an instruction having a mem operand, the number of bytes is the number before the symbol (/). When the external memory (including the SFR area) is accessed, the number of bytes is the number after the symbol (/).

Table 10. Bytes and Clocks for Instructions With "mem" and "&mem" Operands; External ROM (IRAM, SFR, EMEM)

	Instruction		Register Indirect Mode		Base Mode		Indexed Mode
			[DE+] [HL+] [DE–] [HL–]	[DE] [HL]	[DE+byte] [HL+byte]	[SP+byte]	word[A] word[B] word[DE] word[HL]
Bytes		mem	2*	2*	3	3	4
		&mem	3*	3*	4	4	5
Clock Cycles	MOV	A, mem	9/11	6/8	11/13	12/14	14/16
		mem, A					
		A, &mem	12/14	9/11	14/16	15/17	17/19
		&mem, A					
	XCH	A, mem	14/18	12/16	13/17	14/18	16/20
		A, &mem	17/21	15/19	16/20	17/21	19/23
	ADD, ADDC, SUB, SUBC, AND, OR, XOR, CMP	A, mem	13/15	11/13	12/14	13/15	15/17
		A, &mem	16/18	14/16	15/17	16/18	18/20

* When [DE], [HL], [DE+], [HL+], [DE–], or [HL–] is specified as the mem operand of a MOV instruction, the instruction is used as a dedicated 1-byte type. When the operand is &mem, the instruction is 2-byte.

Table 11. Opcode Symbols

Symbol	Meaning
Bn	Immediate data corresponding to bit
Nn	Immediate data corresponding to n
Data	8-bit immediate data corresponding to byte
Low/High Byte	16-bit immediate data corresponding to word
Saddr-offset	Lower 8-bit offset data of 16-bit address corresponding to saddr
Sfr-offset	Lower 8-bit offset data of 16-bit address of special function register (sfr)
Low/High Offset	16-bit offset data corresponding to word in indexed addressing
Low/High Addr	16-bit immediate data corresponding to addr16
jdisp	Signed 2's complement data (8 bits) indicating relative address distance between first address of next instruction and branch destination address
fa	Lower 11 bits of immediate data corresponding to addr11
ta	Lower 5 bits of immediate data corresponding to (addr5xdis)

Instruction Set

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Data Transfer									
MOV	r,#byte	r ← byte	2	2	6				1 0 1 1 1 R_2 R_1 R_0
									Data
	saddr,#byte	(saddr) ← byte	3	3/5	9	9	12		0 0 1 1 1 0 1 0
									Saddr-offset
									Data
	sfr,#byte	sfr ← byte	3	5		9	12		0 0 1 0 1 0 1 1
									Sfr-offset
									Data
	r,r	r ← r	2	2	6				0 0 1 0 0 1 0 0
									0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,r	A ← r	1	2	3				1 1 0 1 0 R_2 R_1 R_0
	A,saddr	A ← (saddr)	2	2/4	6	6	9		0 0 1 0 0 0 0 0
									Saddr-offset
	saddr,A	(saddr) ← A	2	3/5	6	8			0 0 1 0 0 0 1 0
									Saddr-offset
	saddr, saddr	(saddr) ← (saddr)	3	3-7	9				0 0 1 1 1 0 0 0
									Saddr-offset
									Saddr-offset
	A,sfr	A ← sfr	2	4		6			0 0 0 1 0 0 0 0
									Sfr-offset
	sfr,A	sfr ← A	2	5		6			0 0 0 1 0 0 1 0
									Sfr-offset
	A,mem	A ← (mem)	1-4	6-12	6-14	8-16	8-16		* 0 1 0 1 1 mem
									0 0 0 mod
									0 mem 0 0 0 0
									Low Offset
									High Offset
	A,&mem	A ← (&mem)	2-5	8-14	9-17	11-19	11-19		* 0 0 0 0 0 0 0 1
									0 1 0 1 1 mem
									0 0 0 0 0 0 0 1
									0 0 0 mod
									0 mem 0 0 0 0
									Low Offset
									High Offset

Note:

* If [DE], [HL], [DE+], [DE–], [HL+] or [HL–] is described as mem, these instructions are used as dedicated 1-byte codes. If the register name is described as &mem, the instructions are used as dedicated 2-byte codes.

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	IRAM	SFR	EMEM	Flags Z	AC	CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Data Transfer (cont)											
MOV	mem,A	(mem) ← A	1-4	6-12	6-14	8-16*	8-16				* 0 1 0 1 0 mem
											0 0 0 mod
											1 mem 0 0 0 0
											Low Offset
											High Offset
	&mem,A	(&mem) ← A	2-5	8-14	9-17	11-19	11-19				* 0 0 0 0 0 0 0 1
											0 1 0 1 0 mem
											0 0 0 0 0 0 0 1
											0 0 0 mod
											1 mem 0 0 0 0
											Low Offset
											High Offset
	A,!addr16	A ← (!addr16)	4	6/8	14		16				0 0 0 0 1 0 0 1
											1 1 1 1 0 0 0 0
											Low Addr
											High Addr
	A,&!addr16	A ← (&!addr16)	5	8/10			19				0 0 0 0 0 0 0 1
											0 0 0 0 1 0 0 1
											1 1 1 1 0 0 0 0
											Low Addr
											High Addr
	!addr16, A	(!addr16) ← A	4	6/8	14		17				0 0 0 0 1 0 0 1
											1 1 1 1 0 0 0 1
											Low Addr
											High Addr
	&!addr16,A	(&!addr16) ← A	5	8/10			20				0 0 0 0 0 0 0 1
											0 0 0 0 1 0 0 1
											1 1 1 1 0 0 0 1
											Low Addr
											High Addr
	PSW,#byte	PSW ← byte	3	3	9	9	9	x	x	x	0 0 1 0 1 0 1 1
											1 1 1 1 1 1 1 0
											Data
	PSW,A	PSW ← A	2	2	6	6	6	x	x	x	0 0 0 1 0 0 1 0
											1 1 1 1 1 1 1 0
	A,PSW	A ← PSW	2	2	6	6	6				0 0 0 1 0 0 0 0
											1 1 1 1 1 1 1 0

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Data Transfer (cont)									
XCH	A,r	A ⟷ r	1	4	4				1 1 0 1 1 R_2 R_1 R_0
	r,r	r ⟷ r	2	3	6				0 0 1 0 0 1 0 1 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,mem	A ⟷ (mem)	2-4	9-16	12-16		16-20		0 0 0 mod 0 mem 0 1 0 0 Low Offset High Offset
	A,&mem	A ⟷ (&mem)	3-5	11-18	15-19		19-23		0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 0 1 0 0 Low Offset High Offset
	A,saddr	A ⟷ (saddr)	2	4/8	6				0 0 1 0 0 0 0 1 Saddr-offset
	A,sfr	A ⟷ sfr	3	6/10		13			0 0 0 0 0 0 0 1 0 0 1 0 0 0 0 1 Sfr-offset
	saddr,saddr	(saddr) ⟷ (saddr)	3	6-14		10			0 0 1 1 1 0 0 1 Saddr-offset Saddr-offset
16-Bit Data Transfer									
MOVW	rp,#word	rp ← word	3	3	9				0 1 1 0 0 P_2 P_1 0 Low Byte High Byte
	saddrp,#word	(saddrp) ← word	4	4/8	12	12	18		0 0 0 0 1 1 0 0 Saddr-offset Low Byte High Byte
	sfrp,#word	sfrp ← word	4	8		12			0 0 0 0 1 0 1 1 Saddr-offset Low Byte High Byte
	rp,rp	rp ← rp	2	4	6				0 0 1 0 0 1 0 0 0 P_6 P_5 0 1 P_2 P_1 0
	AX,saddrp	AX ← (saddrp)	2	6/10	8	12			0 0 0 1 1 1 0 0 Saddr-offset
	saddrp,AX	(saddrp) ← AX	2	5/9	8	12			0 0 0 1 1 0 1 0 Saddr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
16-Bit Data Transfer (cont)									
MOVW	AX,sfrp	AX ← sfrp	2	10		12			0 0 0 1 0 0 0 1
									Sfr-offset
	sfrp,AX	sfrp ← AX	2	9		12			0 0 0 1 0 0 1 1
									Sfr-offset
	AX,mem1	AX ← (mem1)	2	9-15	12	16	16		0 0 0 0 0 1 0 1
									1 1 1 0 0 0 1 R_0
	AX,&mem1	AX ← (&mem1)	3	11-17	15	19	19		0 0 0 0 0 0 0 1
									0 0 0 0 0 1 0 1
									1 1 1 0 0 0 1 R_0
	mem1, AX	(mem1) ← AX	2	8-14	11	15	15		0 0 0 0 0 1 0 1
									1 1 1 0 0 1 1 R_0
	&mem1,AX	(&mem1) ← AX	3	10-16	14	18	18		0 0 0 0 0 0 0 1
									0 0 0 0 0 1 0 1
									1 1 1 0 0 1 1 R_0
8-Bit Operation									
ADD	A,#byte	A,CY ← A + byte	2	2	6			x x x	1 0 1 0 1 0 0 0
									Data
	saddr,#byte	(saddr),CY ← (saddr) + byte	3	3/7	9	11		x x x	0 1 1 0 1 0 0 0
									Saddr-offset
									Data
	sfr,#byte	sfr,CY ← sfr + byte	4	9		14		x x x	0 0 0 0 0 0 0 1
									0 1 1 0 1 0 0 0
									Sfr-offset
									Data
	r,r	r,CY ← r + r	2	3	7			x x x	1 0 0 0 1 0 0 0
									0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A,CY ← A + (saddr)	2	3/5	6	7	8	x x x	1 0 0 1 1 0 0 0
									Saddr-offset
	A,sfr	A,CY ← A + sfr	3	7		10		x x x	0 0 0 0 0 0 0 1
									1 0 0 1 1 0 0 0
									Sfr-offset
	saddr,saddr	(saddr),CY ← (saddr) + (saddr)	3	3-9	9	11		x x x	0 1 1 1 1 0 0 0
									Saddr-offset
									Saddr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)											
ADD	A,mem	A,CY ← A + (mem)	2-4	8-13	11-15	13-17	13-17	x	x	x	0 0 0 mod 0 mem 1 0 0 0 Low Offset High Offset
	A,&mem	A,CY ← A + (&mem)	3-5	10-15	14-18	16-20	16-20	x	x	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 0 0 0 Low Offset High Offset
ADDC	A,#byte	A,CY ← A + byte + CY	2	2	6			x	x	x	1 0 1 0 1 0 0 1 Data
	saddr,#byte	(saddr),CY ← (saddr) + byte + CY	3	3/7	9	11		x	x	x	0 1 1 0 1 0 0 1 Saddr-offset Data
	sfr,#byte	sfr,CY ← sfr + byte + CY	4	9		14		x	x	x	0 0 0 0 0 0 0 1 0 1 1 0 1 0 0 1 Sfr-offset Data
	r,r	r,CY ← r + r + CY	2	3	7			x	x	x	1 0 0 1 1 0 0 1 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A,CY ← A + (saddr) + CY	2	2/5	6	7	8	x	x	x	1 0 0 1 1 0 0 1 Saddr-offset
	A,sfr	A,CY ← A + sfr + CY	3	7		10		x	x	x	0 0 0 0 0 0 0 1 1 0 0 1 1 0 0 1 Sfr-offset
	saddr,saddr	(saddr),CY ← (saddr) + (saddr) + CY	3	3-9	9	11		x	x	x	0 1 1 1 1 0 0 1 Saddr-offset Saddr-offset
	A,mem	A,CY ← A + (mem) + CY	2-4	8-13	11-15	13-17	13-17	x	x	x	0 0 0 mod 0 mem 1 0 0 1 Low Offset High Offset
	A,&mem	A,CY ← A + (&mem) + CY	3-5	10-15	14-18	16-20	16-20	x	x	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 0 0 0 Low Offset High Offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)											
SUB	A,#byte	A,CY ← A−byte	2	2	6			x	x	x	1 0 1 0 1 0 1 0 Data
	saddr,#byte	(saddr),CY ← (saddr)−(byte)	3	3/7	9	11		x	x	x	0 1 1 0 1 0 1 0 Saddr-offset Data
	sfr,#byte	sfr,CY ← sfr−byte	4	9		14		x	x	x	0 0 0 0 0 0 0 1 0 1 1 0 1 0 1 0 Sfr-offset Data
	r,r	r,CY ← r−r	2	3	7			x	x	x	1 0 0 0 1 0 1 0 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A,CY ← A−(saddr)	2	3/5	6	7	8	x	x	x	1 0 0 1 1 0 1 0 Saddr-offset
	A,sfr	A,CY ← A−sfr	3	7		10		x	x	x	0 0 0 0 0 0 0 1 1 0 0 1 1 0 1 0 Sfr-offset
	saddr,saddr	(saddr),CY ← (saddr) − (saddr)	3	3-9	9	11		x	x	x	0 1 1 1 1 0 1 0 Saddr-offset Saddr-offset
	A,mem	A,CY ← A−(&mem)	2-4	8-13	11-15	13-17	13-17	x	x	x	0 0 0 mod 0 mem 1 0 1 0 Low Offset High Offset
	A,&mem	A,CY ← A−(&mem)	3-5	10-15	14-18	16-20	16-20	x	x	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 0 1 0 Low Offset High Offset
SUBC	A,#byte	A,CY ← A−byte−CY	2	2	6			x	x	x	1 0 1 0 1 0 1 1 Data
	saddr,#byte	(saddr),CY ← (saddr)−byte−CY	3	3/7	9	11		x	x	x	0 1 1 0 1 0 1 1 Saddr-offset Data
	sfr,#byte	sfr,CY ← sfr−byte−CY	4	9		14		x	x	x	0 0 0 0 0 0 0 1 0 1 1 0 1 0 1 1 Sfr-offset Data

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	IRAM	SFR	EMEM	Flags Z	AC	CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)											
SUBC	r,r	r,CY ← r−r−CY	2	3	7			x	x	x	1 0 0 0 1 0 1 1 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A,CY ← A−(saddr)−CY	2	3/5	6	7	8	x	x	x	1 0 0 1 1 0 1 1 Saddr-offset
	A,sfr	A,CY ← A−sfr−CY	3	7		10		x	x	x	0 0 0 0 0 0 0 1 1 0 0 1 1 0 1 1 Sfr-offset
	saddr,saddr	(saddr),CY ← (saddr)−(saddr)−CY	3	3-9	9	11		x	x	x	0 1 1 1 1 0 1 1 Saddr-offset Saddr-offset
	A,mem	A,CY ← A−(mem)−CY	2-4	8-13	11-15	13-17	13-17	x	x	x	0 0 0 mod 0 mem 1 0 1 1 Low Offset High Offset
	A,&mem	A,CY ← A−(&mem)−CY	3-5	10-15	14-18	16-20	16-20	x	x	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 0 1 1 Low Offset High Offset
AND	A,#byte	A ← A∧byte	2	2	6			x			1 0 1 0 1 1 0 0 Data
	saddr,#byte	(saddr) ← (saddr)∧byte	3	3/7	9	11		x			0 1 1 0 1 1 0 0 Saddr-offset Data
	sfr,#byte	sfr ← sfr∧byte	4	9		14		x			0 0 0 0 0 0 0 1 0 1 1 0 1 1 0 0 Sfr-offset Data
	r,r	r ← r∧r	2	3	7			x			1 0 0 0 1 1 0 0 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A ← A∧(saddr)	2	3/5	6	7	8	x			1 0 0 1 1 1 0 0 Saddr-offset
	A,sfr	A ← A∧(sfr)	3	7		10		x			0 0 0 0 0 0 0 1 1 0 0 1 1 1 0 0 Sfr-offset
	saddr,saddr	(saddr) ← (saddr)∧(saddr)	3	3-9	9	11		x			0 1 1 1 1 1 0 0 Saddr-offset Saddr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)									
AND	A,mem	A ← A∧(mem)	2-4	8-13	11-15	13-17	13-17	x	0 0 0 mod 0 mem 1 1 0 0 Low Offset High Offset
	A,&mem	A ← A∧(&mem)	3-5	10-15	14-18	16-20	16-20	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 1 0 0 Low Offset High Offset
OR	A,#byte	A ← A∨byte	2	2	6			x	1 0 1 0 1 1 1 0 Data
	saddr,#byte	(saddr) ← (saddr)∨byte	3	3/7	9	11		x	0 1 1 0 1 1 1 0 Saddr-offset Data
	sfr,#byte	sfr ← sfr∨byte	4	9		14		x	0 0 0 0 0 0 0 1 0 1 1 0 1 1 1 0 Sfr-offset Data
	r,r	r ← r∨r	2	3	7			x	1 0 0 0 1 1 1 0 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A ← A∨(saddr)	2	3/5	6	7	8	x	1 0 0 1 1 1 1 0 Saddr-offset
	A,sfr	A ← A∨sfr	3	7		10		x	0 0 0 0 0 0 0 1 1 0 0 1 1 1 1 0 Sfr-offset
	saddr,saddr	(saddr) ← (saddr)∨(saddr)	3	3-9	9	11		x	0 1 1 1 1 1 1 0 Saddr-offset Saddr-offset
	A,mem	A ← A∨(mem)	2-4	8-13	11-15	13-17	13-17	x	0 0 0 mod 0 mem 1 1 1 0 Low Offset High Offset
	A,&mem	A ← A∨(&mem)	3-5	10-15	14-18	16-20	16-20	x	0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 1 1 0 Low Offset High Offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)											
XOR	A,#byte	A ← A∀byte	2	2	6			x			1 0 1 0 1 1 0 1 Data
	saddr,#byte	(saddr) ← (saddr)∀byte	3	3/5	9	11		x			0 1 1 0 1 1 0 1 Saddr-offset Data
	sfr,#byte	sfr ← sfr∀byte	4	7		14		x			0 0 0 0 0 0 0 1 0 1 1 0 1 1 0 1 Sfr-offset Data
	r,r	r ← r∀r	2	3	7			x			1 0 0 0 1 1 0 1 0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A ← A∀(saddr)	2	3/5	6	7	8	x			1 0 0 1 1 1 0 1 Saddr-offset
	A,sfr	A ← A∀(sfr)	3	7		10		x			0 0 0 0 0 0 0 1 1 0 0 1 1 1 0 1 Sfr-offset
	saddr,saddr	(saddr) ← (saddr)∀(saddr)	3	3-9	9	11		x			0 1 1 1 1 1 0 1 Saddr-offset Saddr-offset
	A,mem	A ← A∀(mem)	2-4	8-13	11-15	13-17	13-17	x			0 0 0 mod 0 mem 1 1 0 1 Low Offset High Offset
	A,&mem	A ← A∀(&mem)	3-5	10-15	14-18	16-20	16-20	x			0 0 0 0 0 0 0 1 0 0 0 mod 0 mem 1 1 0 1 Low Offset High Offset
CMP	A,#byte	A−byte	2	2	6			x	x	x	1 0 1 0 1 1 1 1 Data
	saddr,#byte	(saddr)−byte	3	3/5	9	11		x	x	x	0 1 1 0 1 1 1 1 Saddr-offset Data
	sfr,#byte	sfr−byte	4	7		14		x	x	x	0 0 0 0 0 0 0 1 0 1 1 0 1 1 1 1 Sfr-offset Data

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	IRAM	SFR	EMEM	Flags Z	AC	CY	Operation Code (Bits 7-0) Bytes B1 thru B5
8-Bit Operation (cont)											
CMP	r,r	r−r	2	3	7			x	x	x	1 0 0 0 1 1 1 1
											0 R_6 R_5 R_4 0 R_2 R_1 R_0
	A,saddr	A−(saddr)	2	3/5	6	7	8	x	x	x	1 0 0 1 1 1 1 1
											Saddr-offset
	A,sfr	A−sfr	3	7		10		x	x	x	0 0 0 0 0 0 0 1
											1 0 0 1 1 1 1 1
											Sfr-offset
	saddr,saddr	(saddr)−(saddr)	3	3-7	9	11		x	x	x	0 1 1 1 1 1 1 1
											Saddr-offset
											Saddr-offset
	A,mem	A−(mem)	2-4	8-13	11-15	13-17	13-17	x	x	x	0 0 0 mod
											0 mem 1 1 1 1
											Low Offset
											High Offset
	A,&mem	A−(&mem)	3-5	10-15	14-18	16-20	16-20	x	x	x	0 0 0 0 0 0 0 1
											0 0 0 mod
											0 mem 1 1 1 1
											Low Offset
											High Offset
16-Bit Operation											
ADDW	AX,#word	AX,CY ← AX + word	3	4	9			x	x	x	0 0 1 0 1 1 0 1
											Low Byte
											High Byte
	AX,rp	AX,CY ← AX + rp	2	6	8			x	x	x	1 0 0 0 1 0 0 0
											0 0 0 0 1 P_2 P_1 0
	AX,saddrp	AX,CY ← AX + (saddrp)	2	7/11	9	13		x	x	x	0 0 0 1 1 1 0 1
											Saddr-offset
	AX,sfrp	AX,CY ← AX + sfrp	3	13		16		x	x	x	0 0 0 0 0 0 0 1
											0 0 0 1 1 1 0 1
											Sfr-offset
SUBW	AX,#word	AX,CY ← AX−word	3	4	9			x	x	x	0 0 1 0 1 1 1 0
											Low Byte
											High Byte
	AX,rp	AX,CY ← AX−rp	2	6	8			x	x	x	1 0 0 0 1 0 1 0
											0 0 0 0 1 P_2 P_1 P_0
	AX,saddrp	AX,CY ← AX−(saddrp)	2	7/11	9	13		x	x	x	0 0 0 1 1 1 1 0
											Saddr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
16-Bit Operation (cont)											
SUBW	AX,sfrp	AX,CY ← AX − sfrp	3	13		16		x	x	x	0 0 0 0 0 0 0 1
											0 0 0 1 1 1 1 0
											Sfr-offset
CMPW	AX,#word	AX − word	3	3	9			x	x	x	0 0 1 0 1 1 1 1
											Low Byte
											High Byte
	AX,rp	AX − rp	2	5	7			x	x	x	1 0 0 0 1 1 1 1
											0 0 0 0 1 P_2 P_1 0
	AX,saddrp	AX − (saddrp)	2	6/10	8	12		x	x	x	0 0 0 1 1 1 1 1
											Saddr-offset
	AX,sfrp	AX − sfrp	3	12		15		x	x	x	0 0 0 0 0 0 0 1
											0 0 0 1 1 1 1 1
											Sfr-offset
Multiplication/Division											
MULU	r	AX ← Axr	2	22	24						0 0 0 0 0 1 0 1
											0 0 0 0 1 R_2 R_1 R_0
DIVUW	r	AX(quotient), r (remainder) ← AX ÷ r	2	71	76						0 0 0 0 0 1 0 1
											0 0 0 1 1 R_2 R_1 R_0
Increment/Decrement											
INC	r	r ← r + 1	1	2	3			x	x		1 1 0 0 0 R_2 R_1 R_0
	saddr	(saddr) ← (saddr) + 1	2	2/6	6	7		x	x		0 0 1 0 0 1 1 0
											Saddr-offset
DEC	r	r ← r − 1	1	2	3			x	x		1 1 0 0 1 R_2 R_1 R_0
	saddr	(saddr) ← (saddr) − 1	2	2/6	6	7		x	x		0 0 1 0 0 1 1 1
											Saddr-offset
INCW	rp	rp ← rp + 1	1	3	3						0 1 0 0 0 1 P_1 P_0
DECW	rp	rp ← rp − 1	1	3	3						0 1 0 0 1 1 P_1 P_0
Shift/Rotate											
ROR	r,n	(CY,r_7 ← r_0, r_{m-1} ← r_m) xn times, n=0-7	2	3+2n	5+2n					x	0 0 1 1 0 0 0 0
											0 1 N_2 N_1 N_0 R_2 R_1 R_0
ROL	r,n	(CY,r_0 ← r_7, r_{m+1} ← r_m) xn times, n=0-7	2	3+2n	5+2n					x	0 0 1 1 0 0 0 1
											0 1 N_2 N_1 N_0 R_2 R_1 R_0

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Shift/Rotate (cont)											
RORC	r,n	(CY ← r_0, r_7 ← CY, r_{m-1} ← r_m) xn times, n=0-7	2	3+2n	5+2n					x	0 0 1 1 0 0 0 0 0 0 N_2 N_1 N_0 R_2 R_1 R_0
ROLC	r,n	(CY ← r_7, r_0 ← CY, r_{m+1} ← r_m) xn times, n=0-7	2	3+2n	5+2n					x	0 0 1 1 0 0 0 1 0 0 N_2 N_1 N_0 R_2 R_1 R_0
SHR	r,n	(CY ← r_0, r_7 ← 0, r_{m-1} ← r_m) xn times, n=0-7	2	3+2n	5+2n			x	0	x	0 0 1 1 0 0 0 0 1 0 N_2 N_1 N_0 R_2 R_1 R_0
SHL	r,n	(CY ← r_7, r_0 ← 0, r_{m+1} ← r_m) xn times, n=0-7	2	3+2n	5+2n			x	0	x	0 0 1 1 0 0 0 1 1 0 N_2 N_1 N_0 R_2 R_1 R_0
SHRW	rp,n	(CY ← rp_0, rp_{15} ← 0, rp_{m-1} ← rp_m) xn times, n=0-7	2	3+3n	5+3n			x	0	x	0 0 1 1 0 0 0 0 1 1 N_2 N_1 N_0 R_2 R_1 R_0
SHLW	rp,n	(CY ← rp_{15}, rp_0 ← 0, rp_{m+1} ← rp_m) xn times, n=0-7	2	3+3n	5+3n			x	0	x	0 0 1 1 0 0 0 1 1 1 N_2 N_1 N_0 R_2 R_1 R_0
ROR4	mem1	A_{3-0} ← $(mem1)_{3-0}$, $(mem1)_{7-4}$ ← A_{3-0}, $(mem1)_{3-0}$ ← $(mem1)_{7-4}$	2	24	26	34	34				0 0 0 0 0 1 0 1 1 0 0 0 1 1 R_1 0
	&mem1	A_{3-0} ← $(\&mem1)_{3-0}$, $(\&mem1)_{7-4}$ ← A_{3-0}, $(\&mem1)_{3-0}$ ← $(\&mem1)_{7-4}$	3	26	29	37	37				0 0 0 0 0 0 0 1 0 0 0 0 0 1 0 1 1 0 0 0 1 1 R_1 0
ROL4	mem1	A_{3-0} ← $(mem1)_{7-4}$, $(mem1)_{3-0}$ ← A_{3-0}, $(mem1)_{7-4}$ ← $(mem1)_{3-0}$	2	25	27	35	35				0 0 0 0 0 1 0 1 1 0 0 1 1 1 R_1 0
	&mem1	A_{3-0} ← $(\&mem1)_{7-4}$, $(\&mem1)_{3-0}$ ← A_{3-0}, $(\&mem1)_{7-4}$ ← $(\&mem1)_{3-0}$	3	27	30	38	38				0 0 0 0 0 0 0 1 0 0 0 0 0 1 0 1 1 0 0 1 1 1 R_1 0

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	IRAM	SFR	EMEM	Flags Z	AC	CY	Operation Code (Bits 7-0) Bytes B1 thru B5
BCD Adjustment											
ADJBA		Decimal adjust accumulator after addition	1	3		3		x	x	x	0 0 0 0 1 1 1 0
ADJBS		Decimal adjust accumulator after addition	–1	3		3		x	x	x	0 0 0 0 1 1 1 1
Bit Manipulation											
MOV1	CY,saddr.bit	CY ← (saddr bit)	3	5/7	9	9	11			x	0 0 0 0 1 0 0 0 0 0 0 0 0 B_2 B_1 B_0 Saddr-offset
	CY,sfr.bit	CY ← sfr.bit	3	7		9				x	0 0 0 0 1 0 0 0 0 0 0 0 1 B_2 B_1 B_0 Sfr-offset
	CY,A.bit	CY ← A.bit	2	5	7					x	0 0 0 0 0 0 1 1 0 0 0 0 1 B_2 B_1 B_0
	CY,X.bit	CY ← X.bit	2	5	7					x	0 0 0 0 0 0 1 1 0 0 0 0 0 B_2 B_1 B_0 Sfr-offset
	CY,PSW.bit	CY ← PSW.bit	2	5		7				x	0 0 0 0 0 0 1 0 0 0 0 0 0 B_2 B_1 B_0
	saddr.bit,CY	(saddr bit) ← CY	3	8/12	12	14	14				0 0 0 0 1 0 0 0 0 0 0 1 0 B_2 B_1 B_0 Saddr-offset
	sfr.bit,CY	sfr.bit ← CY	3	12		14					0 0 0 0 1 0 0 0 0 0 0 1 1 B_2 B_1 B_0 Sfr-offset
	A.bit,CY	A.bit ← CY	2	8	10						0 0 0 0 0 0 1 1 0 0 0 1 1 B_2 B_1 B_0
	X.bit,CY	X.bit ← CY	2	8	10						0 0 0 0 0 0 1 1 0 0 0 1 0 B_2 B_1 B_0 Sfr-offset
	PSW.bit,CY	PSW.bit ← CY	2	7		9		x	x		0 0 0 0 0 0 1 0 0 0 0 1 0 B_2 B_1 B_0
AND1	CY,saddr.bit	CY ← CY ∧ (saddr.bit)	3	5/7	9	11				x	0 0 0 0 1 0 0 0 0 0 1 0 0 B_2 B_1 B_0 Saddr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	IRAM	SFR	EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Bit Manipulation (cont)									
AND1	CY,/saddr.bit	CY ← CY ∧ ($\overline{saddr.bit}$)	3	5/7	9	11		x	0 0 0 0 1 0 0 0 0 0 1 1 0 B_2 B_1 B_0 Sfr-offset
	CY,sfr.bit	CY ← CY ∧ sfr.bit	3	7		11		x	0 0 0 0 1 0 0 0 0 0 1 0 1 B_2 B_1 B_0 Sfr-offset
	CY,/sfr.bit	CY ← CY ∧ $\overline{sfr.bit}$	3	7		11		x	0 0 0 0 1 0 0 0 0 0 1 1 1 B_2 B_1 B_0
	CY,A.bit	CY ← CY ∧ A.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 0 1 0 1 B_2 B_1 B_0
	CY,/A.bit	CY ← CY ∧ $\overline{A.bit}$	2	5	7			x	0 0 0 0 0 0 1 1 0 0 1 1 1 B_2 B_1 B_0
	CY,X.bit	CY ← CY ∧ X.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 0 1 0 0 B_2 B_1 B_0
	CY,/X.bit	CY ← CY ∧ $\overline{X.bit}$	2	5	7			x	0 0 0 0 0 0 1 1 0 0 1 1 0 B_2 B_1 B_0
	CY,PSW.bit	CY ← CY ∧ PSW.bit	2	5		7		x	0 0 0 0 0 0 1 0 0 0 1 0 0 B_2 B_1 B_0
	CY,/PSW.bit	CY ← CY ∧ $\overline{PSW.bit}$	2	5		7		x	0 0 0 0 0 0 1 0 0 0 1 1 0 B_2 B_1 B_0
OR1	CY,saddr.bit	CY ← CY ∨ (saddr.bit)	3	5/7	9	11		x	0 0 0 0 1 0 0 0 0 1 0 0 0 B_2 B_1 B_0 Saddr-offset
	CY,/saddr.bit	CY ← CY ∨ ($\overline{saddr.bit}$)	3	5/7	9	11		x	0 0 0 0 1 0 0 0 0 1 0 1 0 B_2 B_1 B_0 Sfr-offset
	CY,sfr.bit	CY ← CY ∨ sfr.bit)	3	7		11		x	0 0 0 0 1 0 0 0 0 1 0 1 1 B_2 B_1 B_0 Sfr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Bit Manipulation (cont)									
OR1	CY/sfr.bit	CY ← CY V $\overline{\text{sfr.bit}}$	3	7		11		x	0 0 0 0 1 0 0 0 0 1 0 1 1 B_2 B_1 B_0
	CY,A.bit	CY ← CY V A.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 1 0 0 1 B_2 B_1 B_0
	CY,/A.bit	CY ← CY V $\overline{\text{A.bit}}$	2	5	7			x	0 0 0 0 0 0 1 1 0 1 0 1 1 B_2 B_1 B_0
	CY,X.bit	CY ← CY V X.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 1 0 0 0 B_2 B_1 B_0
	CY,/X.bit	CY ← CY V $\overline{\text{X.bit}}$	2	5	7			x	0 0 0 0 0 0 1 1 0 1 0 1 0 B_2 B_1 B_0
	CY,PSW.bit	CY ← CY V PSW.bit	2	5		7		x	0 0 0 0 0 0 1 0 0 1 0 0 0 B_2 B_1 B_0
	CY,/PSW.bit	CY ← CY V $\overline{\text{PSW.bit}}$	2	5		7		x	0 0 0 0 0 0 1 0 0 1 0 1 0 B_2 B_1 B_0
XOR1	CY,saddr.bit	CY ← CY ∀ (saddr.bit)	3	5/7	9	11		x	0 0 0 0 1 0 0 0 0 1 1 0 0 B_2 B_1 B_0 Saddr-offset
	CY,sfr.bit	CY ← CY ∀ sfr.bit	3	7		11		x	0 0 0 0 1 0 0 0 0 1 1 0 1 B_2 B_1 B_0 Sfr-ofset
	CY,A.bit	CY ← CY ∀ A.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 1 1 0 1 B_2 B_1 B_0
	CY,X.bit	CY ← CY ∀ X.bit	2	5	7			x	0 0 0 0 0 0 1 1 0 1 1 0 0 B_2 B_1 B_0
	CY,PSW.bit	CY ← CY ∀ PSW.bit	2	5		7		x	0 0 0 0 0 0 1 0 0 1 1 0 0 B_2 B_1 B_0
SET1	saddr.bit	(saddr.bit) ← 1	2	3/7	6				1 0 1 1 0 B_2 B_1 B_0 Saddr-offset
	sfr.bit	sfr.bit ← 1	3	10		14			0 0 0 0 1 0 0 0 1 0 0 0 1 B_2 B_1 B_0 Sfr-offset

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Bit Manipulation (cont)											
SET1	A.bit	A.bit ← 1	2	6	8						0 0 0 0 0 0 1 1
											1 0 0 0 1 B_2 B_1 B_0
	X.bit	X.bit ← 1	2	6	8						0 0 0 0 0 0 1 1
											1 0 0 0 0 B_2 B_1 B_0
	PSW.bit	PSW.bit ← 1	2	5		7		x	x	x	0 0 0 0 0 0 1 0
											1 0 0 0 0 B_2 B_1 B_0
CLR1	saddr.bit	(saddr.bit) ← 0	2	6/10	6						1 0 1 0 0 B_2 B_1 B_0
											Saddr-offset
	sfr.bit	sfr.bit ← 0	3	10		14					0 0 0 0 1 0 0 0
											1 0 0 1 1 B_2 B_1 B_0
											Sfr-offset
	A.bit	A.bit ← 0	2	6	8						0 0 0 0 0 0 1 1
											1 0 0 1 1 B_2 B_1 B_0
	X.bit	X.bit ← 0	2	6	8						0 0 0 0 0 0 1 1
											1 0 0 1 0 B_2 B_1 B_0
	PSW.bit	PSW.bit ← 0	2	5		7		x	x	x	0 0 0 0 0 0 1 0
											1 0 0 1 0 B_2 B_1 B_0
NOT1	saddr.bit	(saddr.bit) ← 0 $\overline{(saddr.bit)}$	3	6/10	10	14					0 0 0 0 1 0 0 0
											0 1 1 1 0 B_2 B_1 B_0
											Saddr-offset
	sfr.bit	sfr.bit ← $\overline{sfr.bit}$	3	10		14					0 0 0 0 1 0 0 0
											0 1 1 1 1 B_2 B_1 B_0
											Sfr-offset
	A.bit	A.bit ← $\overline{A.bit}$	2	6	8						0 0 0 0 0 0 1 1
											0 1 1 1 1 B_2 B_1 B_0
	X.bit	X.bit ← $\overline{X.bit}$	2	6	8						0 0 0 0 0 0 1 1
											0 1 1 1 0 B_2 B_1 B_0
	PSW.bit	PSW.bit ← $\overline{PSW.bit}$	2	5		7		x	x	x	0 0 0 0 0 0 1 0
											0 1 1 1 0 B_2 B_1 B_0
SET1	CY	CY ← 1	1	2		3				1	0 1 0 0 0 0 0 1
CLR1	CY	CY ← 0	1	2		3				0	0 1 0 0 0 0 0 0
NOT1	CY	CY ← $\overline{CY}$	1	2		3				x	0 1 0 0 0 0 1 0

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Call/Return											
CALL	!addr16	$(SP-1) \leftarrow (PC+3)_H$, $(SP-2) \leftarrow (PC+3)_L$, $PC \leftarrow$!addr16, $SP \leftarrow SP-2$	3	10-15	17		21				0 0 1 0 1 0 0 0 Low Addr High Addr
	rp	$(SP-1) \leftarrow (PC+2)_H$, $(SP-2) \leftarrow (PC+2)_L$, $PC_H \leftarrow rp_H$, $PC_L \leftarrow rp_L$, $SP \leftarrow SP-2$	2	12-17	15		19				0 0 0 0 0 1 0 1 0 1 0 1 1 P_2 P_1 0
CALLF	!addr11	$(SP-1) \leftarrow (PC+2)_H$, $(SP-2) \leftarrow (PC+2)_L$, $PC_{15+11} \leftarrow 00001$, $PC_{10-0} \leftarrow$!addr11, $SP \leftarrow SP-2$	2	10-15	14		18				1 0 0 1 0 ← fa →
CALLT	[addr5]	$(SP-1) \leftarrow (PC+1)_H$, $(SP-2) \leftarrow (PC+1)_L$, $PC_H \leftarrow$ (00000000, addr5 + 1), $PC_L \leftarrow$ (00000000, addr5), $SP \leftarrow SP-2$	1	14-20	20		24				1 1 1 ← ta →
BRK		$(SP-1) \leftarrow PSW$, $(SP-2) \leftarrow (PC+1)_H$, $(SP-3) \leftarrow (PC+1)_L$, $PC_H \leftarrow$ (003FH), $PC_H \leftarrow$ (003FH), $SP \leftarrow SP-3$, $IE \leftarrow 0$	1	16-26	22		28				0 1 0 1 1 1 1 0
RET		$PC_L \leftarrow (SP)$, $PC_H \leftarrow (SP+1)$, $SP \leftarrow SP+2$	1	10-15	11		15				0 1 0 1 0 1 1 0
RETI		$PC_L \leftarrow (SP)$, $PC_H \leftarrow (SP+1)$, $PSW \leftarrow (SP+2)$, $SP \leftarrow SP+3$, $NMIS \leftarrow 0$	1	12-20	15		21	R	R	R	0 1 0 1 0 1 1 1
RETB		$PC_L \leftarrow (SP)$, $PC_H \leftarrow (SP+1)$, $PSW \leftarrow (SP+2)$, $SP \leftarrow SP+3$	1	12-20	13		19	R	R	R	0 1 0 1 1 1 1 1
Stack Manipulation											
PUSH	PSW	$(SP-1) \leftarrow PSW$, $SP \leftarrow SP-1$	1	4-8	5		7				0 1 0 0 1 0 0 1
	sfr	$(SP-1) \leftarrow$ sfr, $SP \leftarrow SP-1$	2	7-9	9		12				0 0 1 0 1 0 0 1 Sfr-offset
	rp	$(SP-1) \leftarrow rp_H$ $(SP-2) \leftarrow rp_L$, $SP \leftarrow SP-2$	1	8-13	8		12				0 0 1 1 1 1 P_1 P_0

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks IROM	Clocks IRAM	Clocks SFR	Clocks EMEM	Flags Z	Flags AC	Flags CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Stack Manipulation (cont)											
POP	PSW	PSW ← (SP), SP ← SP + 1	1	4-8	6		8	R	R	R	0 1 0 0 1 0 0 0
	sfr	sfr ← (SP), SP ← SP + 1	2	9-11	9		12				0 1 0 0 0 0 1 1
											Sfr-offset
	rp	rp_L ← (SP), rp_H ← (SP + 1), SP ← SP +2	1	10-15	11		15				0 0 1 1 0 1 P_1 P_0
MOVW	SP,#word	SP ← word	4	8		12					0 0 0 0 1 0 1 1
											1 1 1 1 1 1 0 0
											Low Byte
											High Byte
	SP,AX	SP ← AX	2	9		11					0 0 0 1 0 0 1 1
											1 1 1 1 1 1 0 0
	AX,SP	AX ← SP	2	10		12					0 0 0 1 0 0 0 1
											1 1 1 1 1 1 0 0
INCW	SP	SP ← SP + 1	2	5		7					0 0 0 0 0 1 0 1
											1 1 0 0 1 0 0 0
DECW	SP	SP ← SP – 1	2	5		7					0 0 0 0 0 1 0 1
											1 1 0 0 1 0 0 1

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks: Int ROM	Clocks: Branch	Clocks: No Branch	Flags: Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Unconditional Branch								
BR	!addr16	PC ← !addr16	3	5	11			0 0 1 0 1 1 0 0
								Low Addr
	rp	$PC_H \leftarrow rp_H, PC_L \leftarrow rp_L$	2	6	10			0 0 0 0 0 1 0 1
								0 1 0 0 1 P_2 P_1 0
	$addr16	PC ← $addr16	2	4	9			0 0 0 1 0 1 0 0
								jdisp
Conditional Branch								
BC	$addr16	PC ← $addr16 if CY = 1	2	2/4	9	6		1 0 0 0 0 0 1 1
BL								jdisp
BNC	$addr16	PC ← $addr16 if CY = 0	2	2/4	9	6		1 0 0 0 0 0 1 0
BNL								jdisp
BZ	$addr16	PC ← $addr16 if Z = 1	2	2/4	9	6		1 0 0 0 0 0 0 1
BE								jdisp
BNZ	$addr16	PC ← $addr16 if Z = 0	2	2/4	9	6		1 0 0 0 0 0 0 0
BNE								jdisp
BT	saddr.bit, $addr16	PC ← $addr16 if (saddr.bit) = 1	3	5-9	12	9		0 1 1 1 0 B_2 B_1 B_0
								Saddr-offset
								jdisp
	sfr.bit, $addr16	PC ← $addr16 if sfr.bit = 1	4	7/9	16	13		0 0 0 0 1 0 0 0
								1 0 1 1 1 B_2 B_1 B_0
								Sfr-offset
								jdisp
	A.bit,$addr16	PC ← $addr16 if A.bit = 1	3	5/7	12	9		0 0 0 0 0 0 1 1
								1 0 1 1 1 B_2 B_1 B_0
								jdisp
	X.bit,$addr16	PC ← $addr16 if X.bit = 1	3	5/7	12	9		0 0 0 0 0 0 1 1
								1 0 1 1 0 B_2 B_1 B_0
								jdisp
	PSW.bit,$addr16	PC ← $addr16 if PSW.bit = 1	3	5/7	12	9		0 0 0 0 0 0 1 0
								1 0 1 1 0 B_2 B_1 B_0
								jdisp

Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks: Int ROM	Clocks: Branch	Clocks: No Branch	Flags: Z	Flags: AC	Flags: CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Conditional Branch (cont)										
BF	saddr.bit,$addr16	PC ← $addr16 if (saddr.bit) = 0	4	5-9	15	12				0 0 0 0 1 0 0 0 1 0 1 0 1 B_2 B_1 B_0 Saddr-offset jdisp
	sfr.bit,$addr16	PC ← $addr16 if sfr.bit = 0	4	7/9	16	13				0 0 0 0 1 0 0 0 1 0 1 0 1 B_2 B_1 B_0 Sfr-offset jdisp
	A.bit,$addr16	PC ← $addr16 if A.bit = 0	3	5/7	12	9				0 0 0 0 0 0 1 1 1 0 1 0 1 B_2 B_1 B_0 jdisp
	X.bit,$addr16	PC ← $addr16 if X.bit = 0	3	5/7	12	9				0 0 0 0 0 0 1 1 1 0 1 0 0 B_2 B_1 B_0 jdisp
	PSW.bit,$addr16	PC ← $addr16 if PSW.bit = 0	3	5/7	12	9				0 0 0 0 0 0 1 0 1 0 1 0 0 B_2 B_1 B_0 jdisp
BTCLR	saddr.bit,$addr16	PC ← $addr16 if (saddr.bit) = 1 then reset (saddr.bit)	4	5-13	15	12				0 0 0 0 1 0 0 0 1 1 0 1 1 B_2 B_1 B_0 Saddr-offset jdisp
	sfr.bit,$addr16	PC ← $addr16 if sfr.bit = 1 then reset sfr.bit	4	7/13	18	13				0 0 0 0 1 0 0 0 1 1 0 1 1 B_2 B_1 B_0 Sfr-offset jdisp
	A.bit,$addr16	PC ← $addr16 if A.bit = 1 then reset A.bit	3	5/9	12	9				0 0 0 0 0 0 1 1 1 1 0 1 1 B_2 B_1 B_0 jdisp
	X.bit,$addr16	PC ← $addr16 if X.bit = 1 then reset X.bit	3	5/9	12	9				0 0 0 0 0 0 1 1 1 1 0 1 0 B_2 B_1 B_0 jdisp
	PSW.bit,$addr16	PC ← $addr16 if PSW.bit = 1 then reset PSW.bit	3	5/8	12	9	x	x	x	0 0 0 0 0 0 1 0 1 1 0 1 0 B_2 B_1 B_0 jdisp

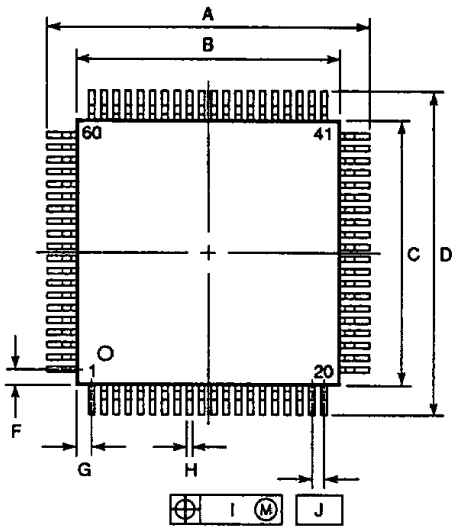
Instruction Set (cont)

Mnemonic	Operand	Operation	Bytes	Clocks: Int ROM	Clocks: Branch	Clocks: No Branch	Flags: Z AC CY	Operation Code (Bits 7-0) Bytes B1 thru B5
Conditional Branch (cont)								
DBNZ	rl,$addr16	rl ← rl – 1, then PC ← $addr16 if rl ≠ 0	2	3/5	9	6		0 0 1 1 0 0 1 R_0 jdisp
	saddr,$addr16	(saddr) ← (saddr) – 1, then PC ← $addr16 if (saddr) ≠ 0	3	4-10	12	9		0 0 1 1 1 0 1 1 Saddr-offset jdisp
CPU Control								
MOV	STBC,#byte	STBC ← byte	4	10		15		0 0 0 0 1 0 0 1 1 1 0 0 0 0 0 0 Data Data
SEL	RBn	RBS1–0 ← n, n = 0–3	2	2		6		0 0 0 0 0 1 0 1 1 0 1 0 1 0 N_1 N_0
NOP		No Operation	1	2		3		0 0 0 0 0 0 0 0
EI		IE ← 1 (Enable Interrupt)	1	2		3		0 1 0 0 1 0 1 1
DI		IE ← 0 (Disable Interrupt)	1	2		3		0 1 0 0 1 0 1 0

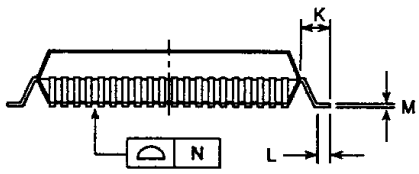
PACKAGE DRAWINGS

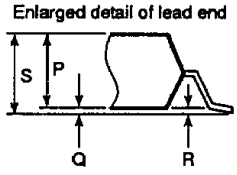
80-Pin Plastic QFP

Item	Millimeters	Inches
A	17.2 ±0.4	.677 ±.016
B	14.0 ±0.2	.551 $^{+.009}_{-.008}$
C	14.0 ±0.2	.551 $^{+.009}_{-.008}$
D	17.2 ±0.4	.677 ±.016
F	0.8	.031
G	0.8	.031
H	0.30 ±0.10	.012 $^{+.004}_{-.005}$
I	0.13	.005
J	0.65 (TP)	.026 (TP)
K	1.6 ±0.2	.063 ±.008
L	0.8 ±0.2	.031 $^{+.009}_{-.008}$
M	0.15 $^{+0.10}_{-0.05}$	.006 $^{+.004}_{-.003}$
N	0.15	.006
P	2.7	.106
Q	0.1 ±0.1	.004 ±.004
R	0.1 ±0.1	.004 ±.004
S	3.0 max	.119 max



37.691



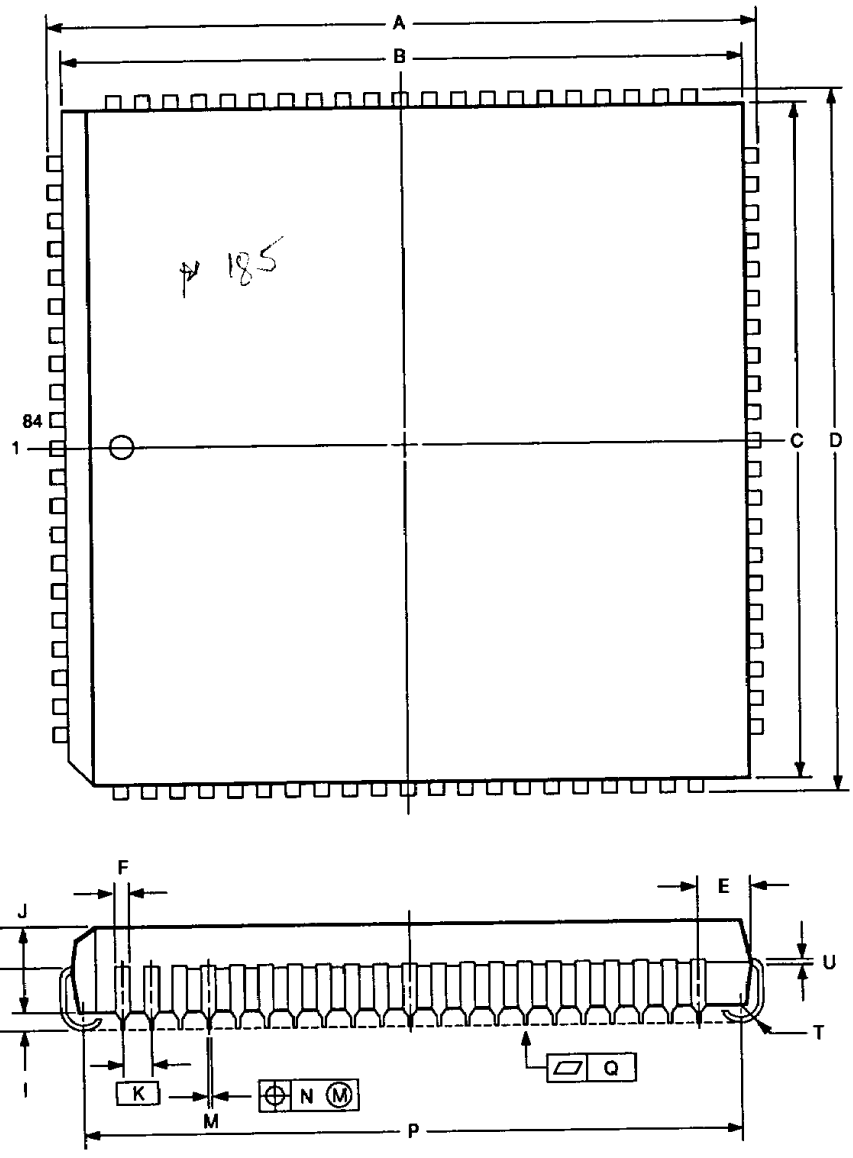


S80GC-65-3B9

49NR-591B (9/89)

84-Pin PLCC

Item	Millimeters	Inches
A	30.2 ±0.2	1.189 ±.008
B	29.28	1.153
C	29.28	1.153
D	30.2 ±0.2	1.189 ±.008
E	1.94 ±0.15	.076 ±.006
F	0.6	.024
G	4.4 ±0.2	.173 ±.008
H	2.8 ±0.2	.110 ±.008
I	0.9 min	.035 min
J	3.4	.134
K	1.27 (TP)	.050 (TP)
M	0.40 ±0.10	.016 ±.004
N	0.12	.005
P	28.20 ±0.20	1.110 ±.008
Q	0.15	.006
T	0.8 radius	.031 radius
U	$0.20^{+0.10}_{-0.05}$	$.008^{+.004}_{-.002}$

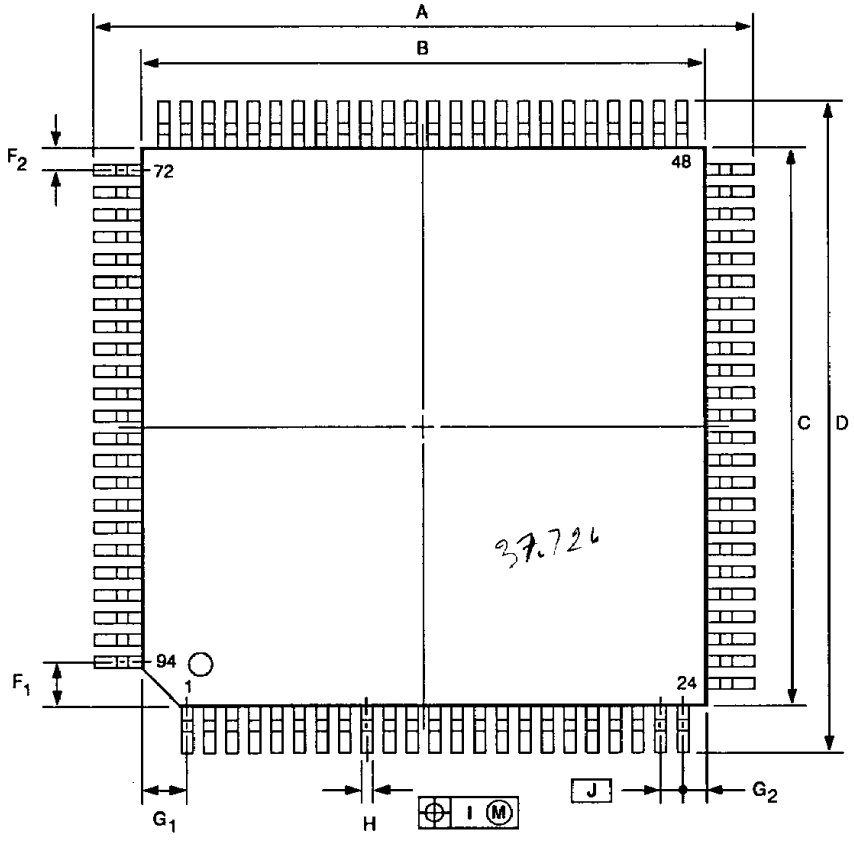


P84L-50A3

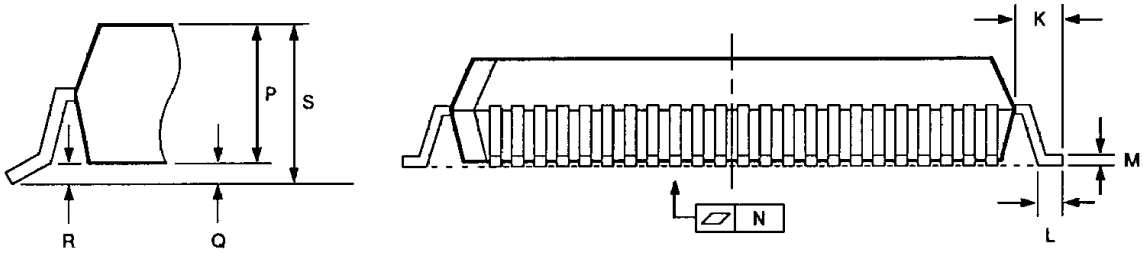
(6/89)
83YL-5806B

94-Pin Plastic QFP

Item	Millimeters	Inches
A	23.2 ±0.4	.913 +.017 −.016
B	20.0 ±0.2	.787 +.009 −.008
C	20.0 ±0.2	.787 +.009 −.008
D	23.2 ±0.4	.913 +.017 −.016
F_1	1.6	.063
F_2	0.8	.031
G_1	1.6	.063
G_2	0.8	.031
H	0.35 ±0.10	.014 +.004 −.005
I	0.15	.006
J	0.8 (TP)	.031 (TP)
K	1.6 ±0.2	.063 ±.008
L	0.8 ±0.2	.031 +.009 −.008
M	0.15 +0.10 −0.05	.006 +.004 −.003
N	0.15	.006
P	3.7	.146
Q	0.1 ±0.1	.004 ±.004
R	0.1 ±0.1	.004 ±.004
S	4.0 max	.158 max



Detail of lead end



S94GJ-80-5BG

6/89
83YL-5810B

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