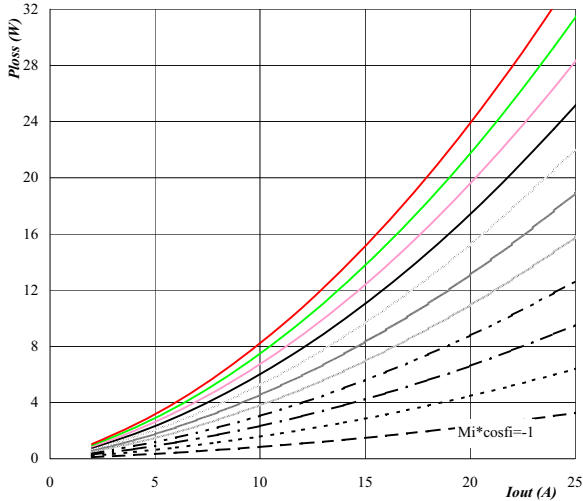


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Output inverter application

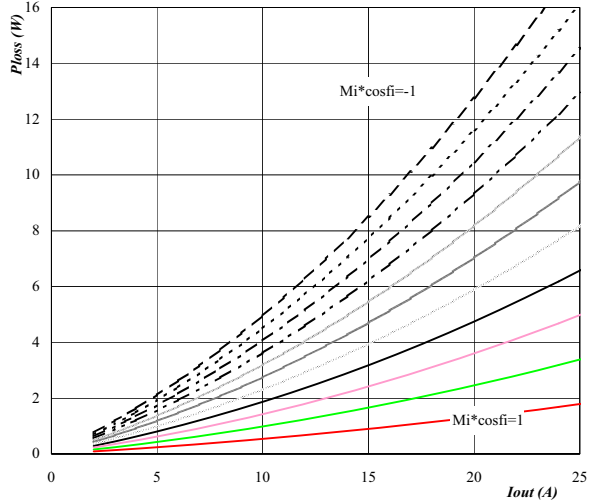
General conditions 3 phase SPWM, $V_{geon} = 15\text{ V}$ $V_{geoff} = 0\text{ V}$ $R_{gon} = 40\text{ ohms}$ $R_{goff} = 20\text{ ohms}$

Figure 1. Typical average static loss as a function of output current IGBT
 $P_{loss} = f(I_{out})$



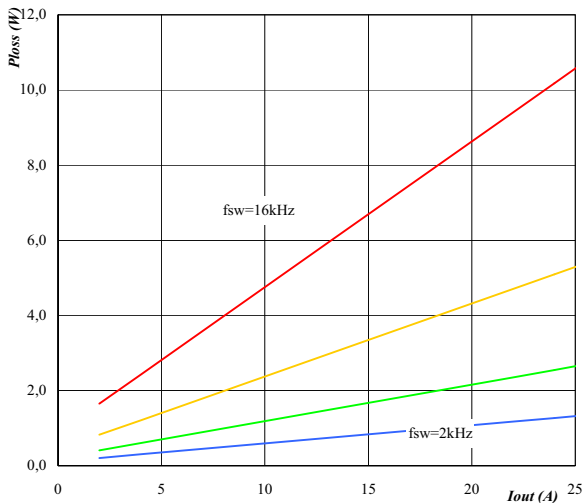
Conditions: $T_j = 125^\circ\text{C}$
 Modulation index * $\cos\phi$ parameter $Mi \cdot \cos\phi$ from -1,00 to 1,00 in 0,20 steps

Figure 2. Typical average static loss as a function of output current FRED
 $P_{loss} = f(I_{out})$



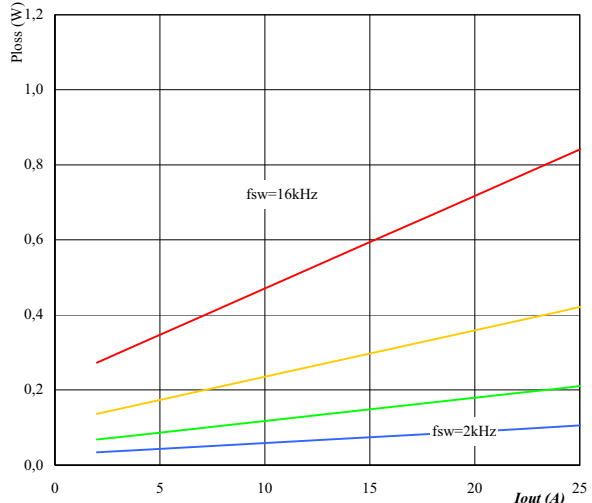
Conditions: $T_j = 125^\circ\text{C}$
 Modulation index * $\cos\phi$ parameter $Mi \cdot \cos\phi$ from -1,00 to 1,00 in 0,20 steps

Figure 3. Typical average switching loss as a function of output current IGBT
 $P_{loss} = f(I_{out})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Switching freq. f_{sw} from 2 kHz to 16 kHz in * 2 steps

Figure 4. Typical average switching loss as a function of output current FRED
 $P_{loss} = f(I_{out})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Switching freq. f_{sw} from 2 kHz to 16 kHz in * 2 steps

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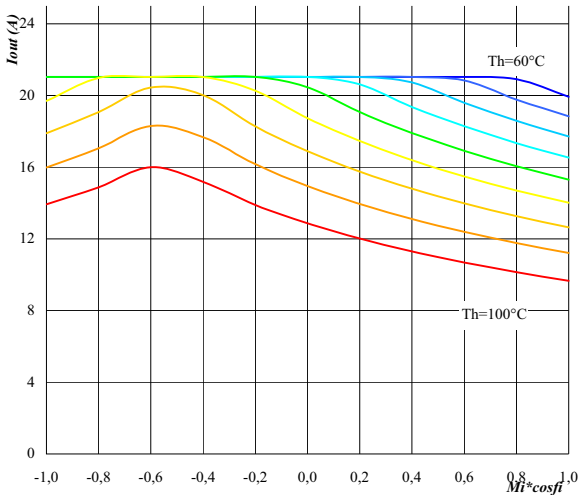
Output inverter application

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General conditions: 3 phase SPWM, $V_{geon} = 15\text{ V}$ $V_{geoff} = 0\text{ V}$ $R_{gon} = 40\text{ ohms}$ $R_{goff} = 20\text{ ohms}$

Figure 5. Typical available 50Hz output current as a function of $M_i \cdot \cos\phi_i$

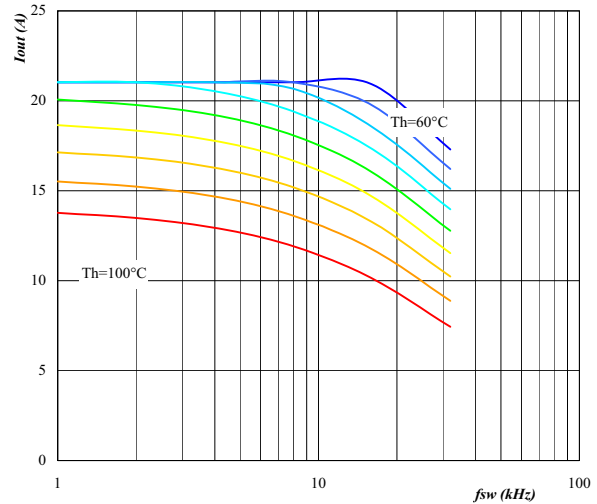
Phase $I_{out} = f(M_i \cdot \cos\phi_i)$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 $f_{sw} = 16\text{ kHz}$
 Heatsink temp. T_h from 60 °C to 100 °C
 parameter in 5 °C steps

Figure 6. Typical available 50Hz output current as a function of switching frequency

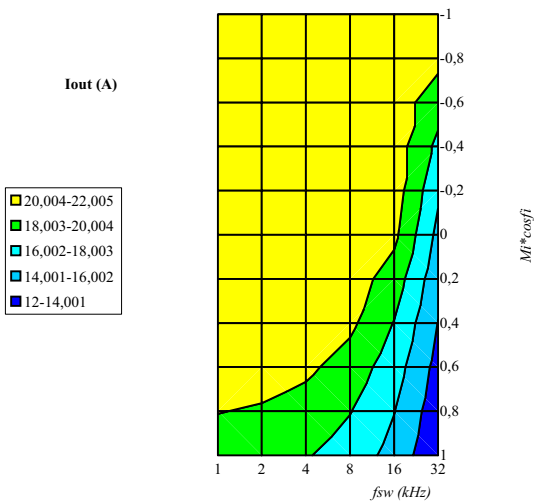
Phase $I_{out} = f(f_{sw})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 $M_i \cdot \cos\phi_i = 0,8$
 Heatsink temp. T_h from 60 °C to 100 °C
 parameter in 5 °C steps

Figure 7. Typical available 50Hz output current as a function of $M_i \cdot \cos\phi_i$ and f_{sw}

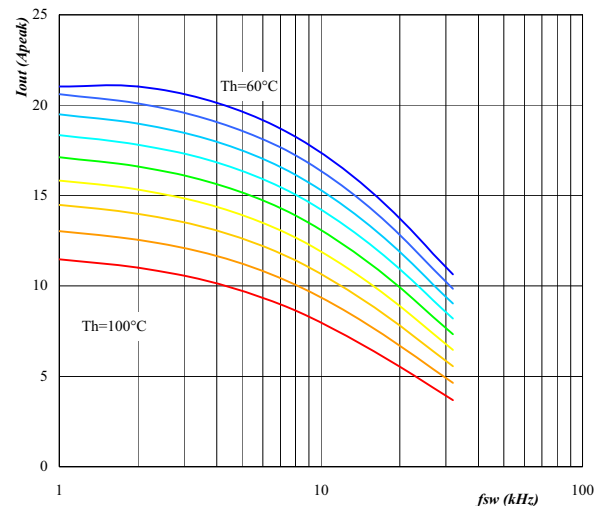
Phase $I_{out} = f(f_{sw}, M_i \cdot \cos\phi_i)$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 $T_h = 80^\circ\text{C}$

Figure 8. Typical available 0Hz output current as a function of switching frequency

Phase $I_{out\text{peak}} = f(f_{sw})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Heatsink temp. T_h from 60 °C to 100 °C
 parameter in 5 °C steps

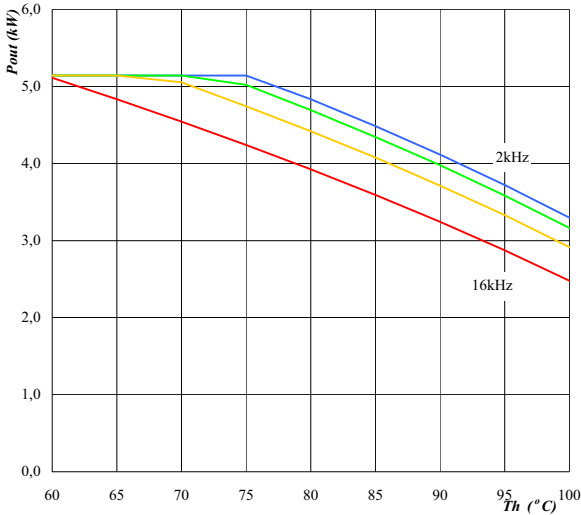
flowPIM[®]1, 600V

Output inverter application

General conditions: 3 phase SPWM, $V_{geon} = 15\text{ V}$ $V_{geoff} = 0\text{V}$ $R_{gon} = 40\text{ ohms}$ $R_{goff} = 20\text{ ohms}$

Figure 9. Typical available electric peak output power as a function of heatsink temperature

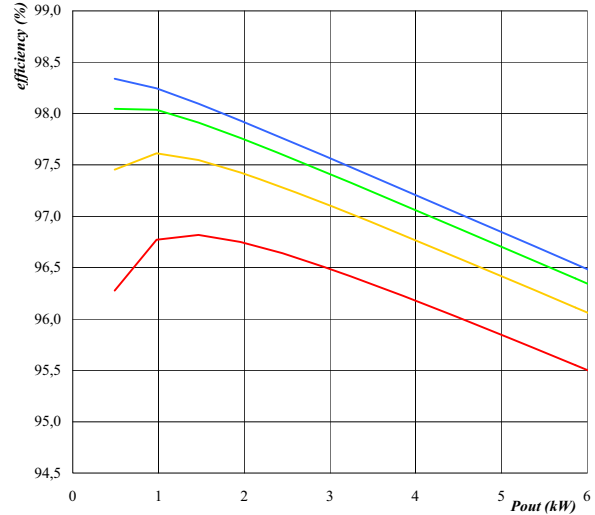
Inverter $P_{out} = f(T_h)$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Modulation index $M_i = 1$
 $\cos\phi_i = 0,80$
 Switching freq. parameter fsw from 2 kHz to 16 kHz in * 2 steps

Figure 10. Typical efficiency as a function of output power

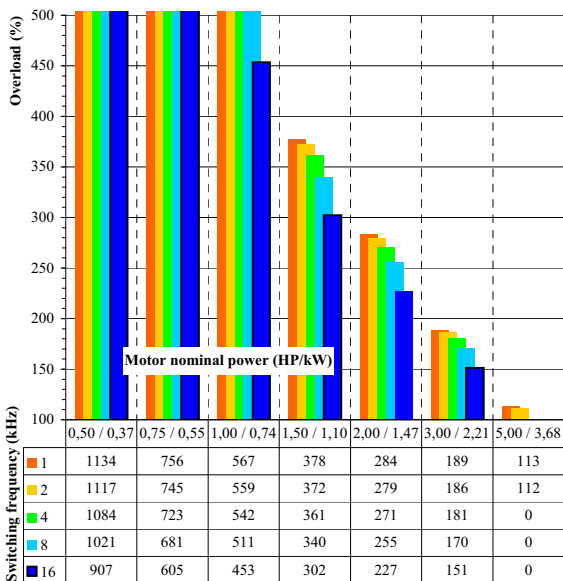
Inverter $\text{efficiency} = f(P_{out})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Modulation index $M_i = 1$
 $\cos\phi_i = 0,80$
 Switching freq. parameter fsw from 2 kHz to 16 kHz in * 2 steps

Figure 11. Typical available overload factor as a function of motor power and switching frequency

Inverter $P_{peak} / P_{nom} = f(P_{nom}, f_{sw})$



Conditions: $T_j = 125^\circ\text{C}$
 DC link = 320 V
 Modulation index $M_i = 1$
 $\cos\phi_i = 0,8$
 Switching freq. parameter fsw from 1 kHz to 16 kHz in * 2 steps
 Heatsink temperature = 80 °C
 Motor efficiency = 0,85