

Double channel high-side driver with MultiSense analog feedback for automotive applications

Datasheet – production data

Features

Max transient supply voltage	V _{CC}	40 V
Operating voltage range	V _{CC}	4 to 28 V
Typ. on-state resistance (per Ch)	R _{ON}	22 mΩ
Current limitation (typ)	I _{LIMH}	63 A
Stand-by current (max)	I _{STBY}	0.5 µA

- General
 - Double channel smart high side driver with MultiSense analog feedback
 - Very low standby current
 - Compatible with 3 V and 5 V CMOS outputs
- MultiSense diagnostic functions
 - Multiplexed analog feedback of: load current with high precision proportional current mirror, V_{CC} supply voltage and T_{CHIP} device temperature
 - Overload and short to ground (power limitation) indication
 - Thermal shutdown indication
 - OFF-state open-load detection
 - Output short to V_{CC} detection
 - Sense enable/disable
- Protections
 - Undervoltage shutdown
 - Overvoltage clamp
 - Load current limitation
 - Self limiting of fast thermal transients
 - Configurable latch-off on overtemperature or power limitation with dedicated fault reset pin
 - Loss of ground and loss of V_{CC}
 - Reverse battery with external components
 - Electrostatic discharge protection



Applications

- All types of Automotive resistive, inductive and capacitive loads
- Specially intended for automotive turn indicators (up to 2x P27W or SAE1156 and R5W paralleled or LED rear combinations)

Description

The VND7020AJ-E is a double channel high-side driver manufactured using ST proprietary VIPower® M0-7 technology and housed in PowerSSO-16 package. The device is designed to drive 12 V automotive grounded loads through a 3 V and 5 V CMOS-compatible interface, providing protection and diagnostics.

The device integrates advanced protective functions such as load current limitation, overload active management by power limitation and overtemperature shutdown with configurable latch-off.

A FaultRST pin unlatches the output in case of fault or disables the latch-off functionality.

A dedicated multifunction multiplexed analog output pin delivers sophisticated diagnostic functions including high precision proportional load current sense, supply voltage feedback and chip temperature sense, in addition to the detection of overload and short circuit to ground, short to V_{CC} and OFF-state open-load.

A sense enable pin allows OFF-state diagnosis to be disabled during the module low-power mode as well as external sense resistor sharing among similar devices.

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1 Block diagram and pin description

Figure 1. Block diagram

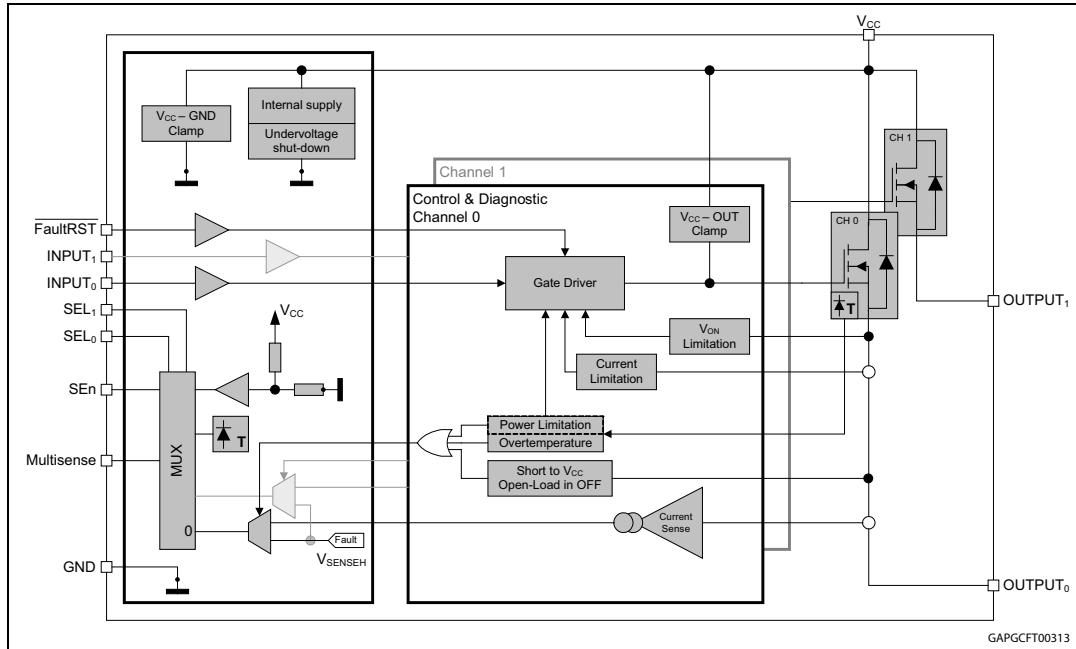
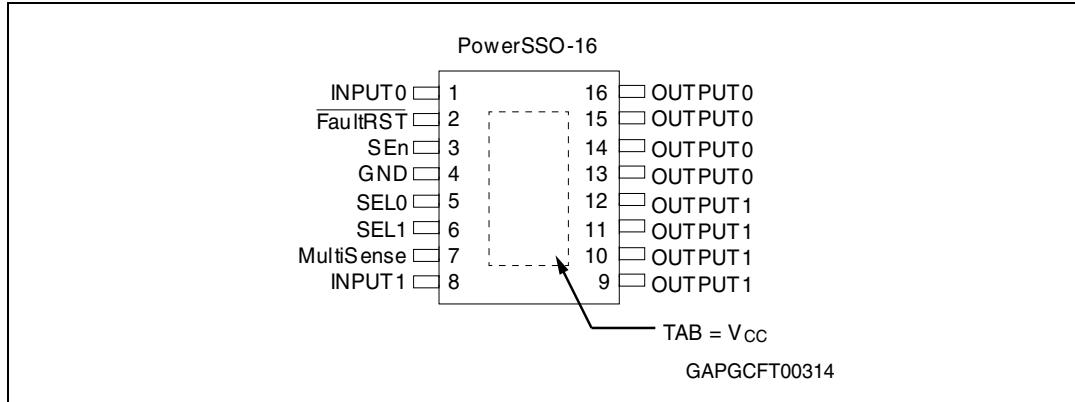


Table 1. Pin functions

Name	Function
V _{CC}	Battery connection.
OUTPUT _{0,1}	Power output.
GND	Ground connection. Must be reverse battery protected by an external diode / resistor network.
INPUT _{0,1}	Voltage controlled input pin with hysteresis, compatible with 3 V and 5 V CMOS outputs. It controls output switch state.
MultiSense	Multiplexed analog sense output pin; it delivers a current proportional to the selected diagnostic: load current, supply voltage or chip temperature
SEn	Active high compatible with 3 V and 5 V CMOS outputs pin; it enables the MultiSense diagnostic pin
SEL _{0,1}	Active high compatible with 3 V and 5 V CMOS outputs pin; they address the MultiSense multiplexer.
FaultRST	Active low compatible with 3 V and 5 V CMOS outputs pin; it unlatches the output in case of fault; If kept low, sets the outputs in auto-restart mode

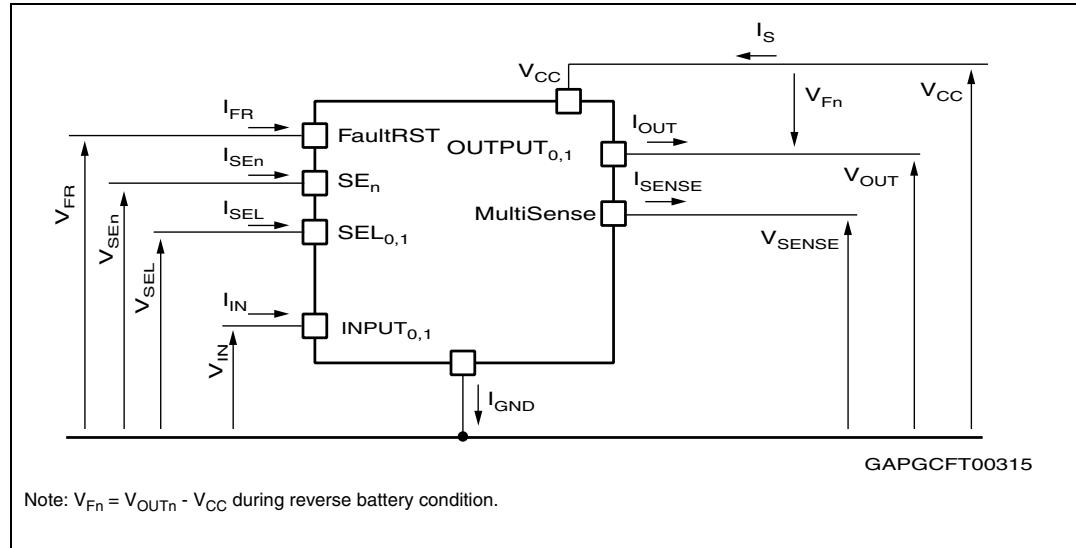
Figure 2. Configuration diagram (top view)**Table 2. Suggested connections for unused and not connected pins**

Connection / pin	MultiSense	N.C.	Output	Input	<u>SEn, SELx, FaultRST</u>
Floating	Not allowed	X ⁽¹⁾	X	X	X
To ground	Through 1 kΩ resistor	X	Not allowed	Through 10 kΩ resistor	Through 10 kΩ resistor

1. X: do not care.

2 Electrical specification

Figure 3. Current and voltage conventions



2.1 Absolute maximum ratings

Stressing the device above the rating listed in [Table 3](#) may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to the conditions in table below for extended periods may affect device reliability.

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit	
V_{CC}	DC supply voltage	38	V	
$-V_{CC}$	Reverse DC supply voltage	0.3		
V_{CCPK}	Maximum transient supply voltage (ISO7637-2:2004 Pulse 5b level IV clamped to 40V; $R_L = 4 \Omega$)	40	V	
V_{CCJS}	Maximum jump start voltage for single pulse short circuit protection	28	V	
$-I_{GND}$	DC reverse ground pin current	200	mA	
I_{OUT}	OUTPUT _{0,1} DC output current	Internally limited	A	
$-I_{OUT}$	Reverse DC output current	23		
I_{IN}	INPUT _{0,1} DC input current	-1 to 10		
I_{SEN}	SEn DC input current			
I_{SEL}	SEL _{0,1} DC input current			
I_{FR}	FaultRST DC input current			
V_{FR}	FaultRST DC input voltage	7.5	V	

Table 3. Absolute maximum ratings (continued)

Symbol	Parameter	Value	Unit
I_{SENSE}	MultiSense pin DC output current ($V_{GND} = V_{CC}$ and $V_{SENSE} < 0$ V)	-10	mA
	MultiSense pin DC output current in reverse ($V_{CC} < 0$ V)	-20	
E_{MAX}	Maximum switching energy (single pulse) ($L = 0.4$ mH; $R_L = 0$ Ω; $V_{CC} = 13.5$ V; $I_{OUT} = 15$ A; $T_{jstart} = 150$ °C)	64	mJ
V_{ESD}	Electrostatic discharge (JEDEC 22A-114F) – $INPUT_{0,1}$ – MultiSense – SEn , $SEL_{0,1}$, FaultRST – $OUTPUT_{0,1}$ – V_{CC}	4000 2000 4000 4000 4000	V V V V V
V_{ESD}	Charge device model (CDM-AEC-Q100-011)	750	V
T_j	Junction operating temperature	-40 to 150	°C
T_{stg}	Storage temperature	-55 to 150	

2.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Typ. value	Unit
$R_{thj-board}$	Thermal resistance junction-board (JEDEC JESD 51-5 / 51-8) ⁽¹⁾⁽²⁾	4.9	°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient (JEDEC JESD 51-5) ⁽¹⁾⁽³⁾	55.5	
$R_{thj-amb}$	Thermal resistance junction-ambient (JEDEC JESD 51-7) ⁽¹⁾⁽²⁾	21.5	

1. One channel ON.
2. Device mounted on four-layers 2s2p PCB
3. Device mounted on two-layers 2s0p PCB with 2 cm² heatsink copper trace

2.3 Main electrical characteristics

$7 \text{ V} < V_{CC} < 28 \text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$, unless otherwise specified.

All typical values refer to $V_{CC} = 13 \text{ V}$; $T_j = 25^\circ\text{C}$, unless otherwise specified.

Table 5. Power section

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V_{CC}	Operating supply voltage		4	13	28	V
V_{USD}	Undervoltage shutdown				4	
$V_{USDReset}$	Undervoltage shutdown reset				5	
$V_{USDhyst}$	Undervoltage shutdown hysteresis			0.3		
R_{ON}	On-state resistance ⁽¹⁾	$I_{OUT} = 3 \text{ A}; T_j = 25^\circ\text{C}$		22		$\text{m}\Omega$
		$I_{OUT} = 3 \text{ A}; T_j = 150^\circ\text{C}$			44	
		$I_{OUT} = 3 \text{ A}; V_{CC} = 4 \text{ V}; T_j = 25^\circ\text{C}$			30	
V_{clamp}	Clamp voltage	$I_S = 20 \text{ mA}; 25^\circ\text{C} < T_j < 150^\circ\text{C}$	41	46	52	V
		$I_S = 20 \text{ mA}; T_j = -40^\circ\text{C}$	38			V
I_{STBY}	Supply current in standby at $V_{CC} = 13 \text{ V}$ ⁽²⁾	$V_{CC} = 13 \text{ V}; V_{IN} = V_{OUT} = V_{FR} = V_{SEn} = 0 \text{ V}; V_{SEL0,1} = 0 \text{ V}; T_j = 25^\circ\text{C}$			0.5	μA
		$V_{CC} = 13 \text{ V}; V_{IN} = V_{OUT} = V_{FR} = V_{SEn} = 0 \text{ V}; V_{SEL0,1} = 0 \text{ V}; T_j = 85^\circ\text{C}$ ⁽³⁾			0.5	μA
		$V_{CC} = 13 \text{ V}; V_{IN} = V_{OUT} = V_{FR} = V_{SEn} = 0 \text{ V}; V_{SEL0,1} = 0 \text{ V}; T_j = 125^\circ\text{C}$			3	
t_{D_STBY}	Standby mode blanking time	$V_{CC} = 13 \text{ V}; V_{IN} = V_{OUT} = V_{FR} = V_{SEL0,1} = 0 \text{ V}; V_{SEn} = 5 \text{ V} \text{ to } 0 \text{ V}$	60	300	550	μs
$I_{S(ON)}$	Supply current	$V_{CC} = 13 \text{ V}; V_{SEn} = V_{FR} = V_{SEL0,1} = 0 \text{ V}; V_{IN0} = 5 \text{ V}; V_{IN1} = 5 \text{ V}; I_{OUT0} = 0 \text{ A}; I_{OUT1} = 0 \text{ A}$		5	8	mA
$I_{GND(ON)}$	Control stage current consumption in ON state. All channels active.	$V_{CC} = 13 \text{ V}; V_{SEn} = 5 \text{ V}; V_{FR} = V_{SEL0,1} = 0 \text{ V}; V_{IN0} = 5 \text{ V}; V_{IN1} = 5 \text{ V}; I_{OUT0} = 3 \text{ A}; I_{OUT1} = 3 \text{ A}$			12	mA
$I_{L(off)}$	Off-state output current at $V_{CC} = 13 \text{ V}$ ⁽¹⁾	$V_{IN} = V_{OUT} = 0 \text{ V}; V_{CC} = 13 \text{ V}; T_j = 25^\circ\text{C}$	0	0.01	0.5	μA
		$V_{IN} = V_{OUT} = 0 \text{ V}; V_{CC} = 13 \text{ V}; T_j = 125^\circ\text{C}$	0		3	
V_F	Output - V_{CC} diode voltage ⁽¹⁾	$-I_{OUT} = 3 \text{ A}; T_j = 150^\circ\text{C}$			0.7	V

1. For each channel

2. PowerMOS leakage included.
3. Parameter specified by design; not subject to production test.

Table 6. Switching ($V_{CC} = 13$ V; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$, unless otherwise specified)⁽¹⁾

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
$t_{d(on)}$	Turn-on delay time at $T_j = 25^\circ\text{C}$	$R_L = 4.3 \Omega$	10	60	120	μs
$t_{d(off)}$	Turn-off delay time at $T_j = 25^\circ\text{C}$		10	40	100	
$(dV_{OUT}/dt)_{on}$	Turn-on voltage slope at $T_j = 25^\circ\text{C}$	$R_L = 4.3 \Omega$	0.1	0.36	0.7	$\text{V}/\mu\text{s}$
$(dV_{OUT}/dt)_{off}$	Turn-off voltage slope at $T_j = 25^\circ\text{C}$		0.1	0.36	0.7	
W_{ON}	Switching energy losses at turn-on (t_{won})	$R_L = 4.3 \Omega$	—	0.38	0.49 ⁽²⁾	mJ
W_{OFF}	Switching energy losses at turn-off (t_{woff})	$R_L = 4.3 \Omega$	—	0.39	0.54 ⁽²⁾	mJ
t_{SKew}	Differential Pulse skew ($t_{PHL} - t_{PLH}$) see <i>Figure 4</i>	$R_L = 4.3 \Omega$	-75	-25	25	μs

1. See *Figure 4: Switching time and Pulse skew*

2. Parameter guaranteed by design and characterization; not subject to production test

Table 7. Logic Inputs (7 V $< V_{CC} < 28$ V; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
INPUT_{0,1} characteristics						
V_{IL}	Input low level voltage				0.9	V
I_{IL}	Low level input current	$V_{IN} = 0.9$ V	1			μA
V_{IH}	Input high level voltage		2.1			V
I_{IH}	High level input current	$V_{IN} = 2.1$ V			10	μA
$V_{I(hyst)}$	Input hysteresis voltage		0.2			V
V_{ICL}	Input clamp voltage	$I_{IN} = 1$ mA	5.3		7.2	V
		$I_{IN} = -1$ mA		-0.7		
FaultRST characteristics						
V_{FRL}	Input low level voltage				0.9	V
I_{FRL}	Low level input current	$V_{IN} = 0.9$ V	1			μA
V_{FRH}	Input high level voltage		2.1			V
I_{FRH}	High level input current	$V_{IN} = 2.1$ V			10	μA
$V_{FR(hyst)}$	Input hysteresis voltage		0.2			V
V_{FRCL}	Input clamp voltage	$I_{IN} = 1$ mA	5.3		7.5	V
		$I_{IN} = -1$ mA		-0.7		

Table 7. Logic Inputs (7 V < V_{CC} < 28 V; -40°C < T_j < 150°C) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
SEL_{0,1} characteristics (7 V < V_{CC} < 18 V)						
V _{SELL}	Input low level voltage				0.9	V
I _{SELL}	Low level input current	V _{IN} = 0.9 V	1			μA
V _{SELH}	Input high level voltage		2.1			V
I _{SELH}	High level input current	V _{IN} = 2.1 V			10	μA
V _{SEL(hyst)}	Input hysteresis voltage		0.2			V
V _{SELCL}	Input clamp voltage	I _{IN} = 1 mA	5.3		7.2	V
		I _{IN} = -1 mA		-0.7		
SEn characteristics (7 V < V_{CC} < 18 V)						
V _{SEnL}	Input low level voltage				0.9	V
I _{SEnL}	Low level input current	V _{IN} = 0.9 V	1			μA
V _{SEnH}	Input high level voltage		2.1			V
I _{SEnH}	High level input current	V _{IN} = 2.1 V			10	μA
V _{SEn(hyst)}	Input hysteresis voltage		0.2			V
V _{SEnCL}	Input clamp voltage	I _{IN} = 1 mA	5.3		7.2	V
		I _{IN} = -1 mA		-0.7		

Table 8. Protections (7 V < V_{CC} < 18 V; -40°C < T_j < 150°C)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
I _{LIMH}	DC short circuit current	V _{CC} = 13 V	45	63	90	A
		4 V < V _{CC} < 18 V ⁽¹⁾				
I _{LIML}	Short circuit current during thermal cycling	V _{CC} = 13 V; T _R < T _j < T _{TSD}		23		
T _{TSD}	Shutdown temperature		150	175	200	°C
T _R	Reset temperature ⁽¹⁾		T _{RS} + 1	T _{RS} + 7		
T _{RS}	Thermal reset of fault diagnostic indication	V _{FR} = 0 V; V _{SEn} = 5 V;	135			
T _{HYST}	Thermal hysteresis (T _{TSD} - T _R)			7		
ΔT _{J_SD}	Dynamic temperature	T _j = -40°C; V _{CC} = 13 V		60		K
t _{LATCH_RST} ⁽¹⁾	Fault reset time for output unlatch	V _{FR} = 5 V to 0 V; V _{SEn} = 5 V; – E.g. Ch ₀ : V _{IN0} = 5 V; V _{SEL0} = 0 V; V _{SEL1} = 0 V;	3	10	20	μs

Table 8. Protections (7 V < V_{CC} < 18 V; -40°C < T_j < 150°C) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V _{DEMAG}	Turn-off output voltage clamp	I _{OUT} = 2 A; L = 6 mH; T _j = -40°C	V _{CC} - 38			V
		I _{OUT} = 2 A; L = 6 mH; T _j = 25°C to 150°C	V _{CC} - 41	V _{CC} - 46	V _{CC} - 52	V
V _{ON}	Output voltage drop limitation	I _{OUT} = 0.5 A		20		mV

1. Parameter guaranteed by design and characterization; not subject to production test.

Table 9. MultiSense (7 V < V_{CC} < 18 V; -40°C < T_j < 150°C)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
V _{SENSE_CL}	MultiSense clamp voltage	V _{SENSE} = 0 V; I _{SENSE} = -1 mA	-17		-12	V
		V _{SENSE} = 0 V; I _{SENSE} = 1 mA		7		
Current sense characteristics						
K _{OL}	I _{OUT} /I _{SENSE}	I _{OUT} = 0.01 A; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	1020			
dK _{cal} /K _{cal}	Current sense ratio drift at calibration point	I _{OUT} = 0.01 A to 0.05 A; I _{cal} = 30 mA; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	-30		30	%
K _{LED}	I _{OUT} /I _{SENSE}	I _{OUT} = 0.1 A; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	1800	3450	5100	
dK _{LED} /K _{LED} ⁽¹⁾⁽²⁾	Current sense ratio drift	I _{OUT} = 0.1 A; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	-25		25	%
K ₀	I _{OUT} /I _{SENSE}	I _{OUT} = 0.5 A; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	2120	3020	3915	
dK ₀ /K ₀ ⁽¹⁾⁽²⁾	Current sense ratio drift	I _{OUT} = 0.5 A; V _{SENSE} = 0.5 V; V _{SENSE} = 5 V	-20		20	%
K ₁	I _{OUT} /I _{SENSE}	I _{OUT} = 1 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	2060	2875	3690	
dK ₁ /K ₁ ⁽¹⁾⁽²⁾	Current sense ratio drift	I _{OUT} = 1 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	-15		15	%
K ₂	I _{OUT} /I _{SENSE}	I _{OUT} = 3 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	2340	2755	3170	
dK ₂ /K ₂ ⁽¹⁾⁽²⁾	Current sense ratio drift	I _{OUT} = 3 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	-10		+10	%
K ₃	I _{OUT} /I _{SENSE}	I _{OUT} = 9 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	2550	2740	2950	
dK ₃ /K ₃ ⁽¹⁾⁽²⁾	Current sense ratio drift	I _{OUT} = 9 A; V _{SENSE} = 4 V; V _{SENSE} = 5 V	-5		5	%

Table 9. MultiSense ($7 \text{ V} < V_{CC} < 18 \text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
I_{SENSE0}	MultiSense leakage current	MultiSense disabled: $V_{SEN} = 0 \text{ V}$	0		0.5	μA
		MultiSense disabled: $-1 \text{ V} < V_{SEN} < 5 \text{ V}^{(1)}$	-0.5		0.5	
		MultiSense enabled: $V_{SEN} = 5 \text{ V}$; All channels ON; $I_{OUTX} = 0 \text{ A}$; Ch _x diagnostic selected; – E.g. Ch ₀ : $V_{IN0} = 5 \text{ V}$; $V_{IN1} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT0} = 0 \text{ A}$; $I_{OUT1} = 3 \text{ A}$	0		2	
		MultiSense enabled: $V_{SEN} = 5 \text{ V}$; Ch _x OFF; Ch _x diagnostic selected; – E.g. Ch ₀ : $V_{IN0} = 0 \text{ V}$; $V_{IN1} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT1} = 3 \text{ A}$	0		2	
$V_{OUT_MSD}^{(1)}$	Output Voltage for MultiSense shutdown	$V_{SEN} = 5 \text{ V}$; $R_{SENSE} = 2.7 \text{ k}\Omega$ – E.g. Ch ₀ : $V_{IN0} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT0} = 3 \text{ A}$		5		V
V_{SENSE_SAT}	Multisense saturation voltage	$V_{CC} = 7 \text{ V}$; $R_{SENSE} = 2.7 \text{ K}$; $V_{SEN} = 5 \text{ V}$; $V_{IN0} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT0} = 9 \text{ A}$; $T_j = 150^\circ\text{C}$	5			V
$I_{SENSE_SAT}^{(1)}$	CS saturation current	$V_{CC} = 7 \text{ V}$; $V_{SENSE} = 4 \text{ V}$; $V_{IN0} = 5 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $T_j = 150^\circ\text{C}$	4			mA
$I_{OUT_SAT}^{(1)}$	Output saturation current	$V_{CC} = 7 \text{ V}$; $V_{SENSE} = 4 \text{ V}$; $V_{IN0} = 5 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $T_j = 150^\circ\text{C}$	11.5			A
OFF-state diagnostic						
V_{OL}	OFF-state open-load voltage detection threshold	$V_{SEN} = 5 \text{ V}$; Ch _x OFF; Ch _x diagnostic selected – E.g: Ch ₀ $V_{IN0} = 0 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$;	2	3	4	V
$I_{L(off2)}$	OFF-state output sink current	$V_{IN} = 0 \text{ V}$; $V_{OUT} = V_{OL}$; $T_j = -40^\circ\text{C}$ to 125°C	-100		-15	μA

Table 9. MultiSense ($7 \text{ V} < V_{CC} < 18 \text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
t_{DSTKON}	OFF-state diagnostic delay time from falling edge of INPUT (see <i>Figure 7</i>)	$V_{SEN} = 5 \text{ V}$; Ch_X ON to OFF transition; Ch_X diagnostic selected – E.g: Ch_0 $V_{IN0} = 5 \text{ V}$ to 0 V ; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT0} = 0 \text{ A}$; $V_{OUT} = 4 \text{ V}$	100	350	700	μs
$t_{D_OL_V}$	Settling time for valid OFF-state open load diagnostic indication from rising edge of SEn	$V_{IN0} = 0 \text{ V}$; $V_{IN1} = 0 \text{ V}$; $V_{FR} = 0 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $V_{OUT0} = 4 \text{ V}$; $V_{SEN} = 0 \text{ V}$ to 5 V			60	μs
t_{D_VOL}	OFF-state diagnostic delay time from rising edge of V_{OUT}	$V_{SEN} = 5 \text{ V}$; Ch_X OFF; Ch_X diagnostic selected – E.g: Ch_0 $V_{IN0} = 0 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $V_{OUT} = 0 \text{ V}$ to 4 V		5	30	μs
Chip temperature analog feedback						
V_{SENSE_TC}	MultiSense output voltage proportional to chip temperature	$V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$; $T_j = -40^\circ\text{C}$	2.315	2.4	2.485	V
		$V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$; $T_j = 25^\circ\text{C}$	1.975	2.06	2.145	V
		$V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$; $T_j = 125^\circ\text{C}$	1.425	1.51	1.595	V
dV_{SENSE_TC}/dT	Temperature coefficient	$T_j = -40^\circ\text{C}$ to 150°C		-5.5		mV/K
Transfer function		$V_{SENSE_TC}(T) = V_{SENSE_TC}(T_0) + dV_{SENSE_TC}/dT * (T - T_0)$				
V_{CC} supply voltage analog feedback						
V_{SENSE_VCC}	MultiSense output voltage proportional to V_{CC} supply voltage	$V_{CC} = 13 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 5 \text{ V}$; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$	3.16	3.23	3.3	V
Transfer function ⁽³⁾		$V_{SENSE_VCC} = V_{CC} / 4$				
Fault diagnostic feedback (see <i>Table 10</i>)						
V_{SENSEH}	MultiSense output voltage in fault condition	$V_{CC} = 13 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$ – E.g: Ch_0 in open load $V_{IN0} = 0 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $I_{OUT0} = 0 \text{ A}$; $V_{OUT} = 4 \text{ V}$	5		6.5	V
I_{SENSEH}	MultiSense output current in fault condition	$V_{CC} = 13 \text{ V}$; $V_{SENSE} = 5 \text{ V}$	7	20	30	mA

Table 9. MultiSense ($7 \text{ V} < V_{CC} < 18 \text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
MultiSense timings (current sense mode - see <i>Figure 5</i>)						
$t_{DSENSE1H}$	Current sense settling time from rising edge of SEN	$V_{IN} = 5 \text{ V}; V_{SEN} = 0 \text{ V to } 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega; R_L = 4.3 \text{ }\Omega$			60	μs
$t_{DSENSE1L}$	Current sense disable delay time from falling edge of SEN	$V_{IN} = 5 \text{ V}; V_{SEN} = 5 \text{ V to } 0 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega; R_L = 4.3 \text{ }\Omega$		5	20	μs
$t_{DSENSE2H}$	Current sense settling time from rising edge of INPUT	$V_{IN} = 0 \text{ V to } 5 \text{ V}; V_{SEN} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega; R_L = 4.3 \text{ }\Omega$		100	250	μs
$\Delta t_{DSENSE2H}$	Current sense settling time from rising edge of I_{OUT} (dynamic response to a step change of I_{OUT})	$V_{IN} = 5 \text{ V}; V_{SEN} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega; I_{SENSE} = 90 \% \text{ of } I_{SENSEMAX}; R_L = 4.3 \text{ }\Omega$			100	μs
$t_{DSENSE2L}$	Current sense turn-off delay time from falling edge of INPUT	$V_{IN} = 5 \text{ V to } 0 \text{ V}; V_{SEN} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega; R_L = 4.3 \text{ }\Omega$		50	250	μs
MultiSense timings (chip temperature sense mode - see <i>Figure 6</i>)						
$t_{DSENSE3H}$	V_{SENSE_TC} settling time from rising edge of SEN	$V_{SEN} = 0 \text{ V to } 5 \text{ V}; V_{SEL0} = 0 \text{ V}; V_{SEL1} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega$			60	μs
$t_{DSENSE3L}$	V_{SENSE_TC} disable delay time from falling edge of SEN	$V_{SEN} = 5 \text{ V to } 0 \text{ V}; V_{SEL0} = 0 \text{ V}; V_{SEL1} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega$			20	μs
MultiSense timings (V_{CC} voltage sense mode - see <i>Figure 6</i>)						
$t_{DSENSE4H}$	V_{SENSE_VCC} settling time from rising edge of SEN	$V_{SEN} = 0 \text{ V to } 5 \text{ V}; V_{SEL0} = 5 \text{ V}; V_{SEL1} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega$			60	μs
$t_{DSENSE4L}$	V_{SENSE_VCC} disable delay time from falling edge of SEN	$V_{SEN} = 5 \text{ V to } 0 \text{ V}; V_{SEL0} = 5 \text{ V}; V_{SEL1} = 5 \text{ V}; R_{SENSE} = 1 \text{ k}\Omega$			20	μs
MultiSense timings (Multiplexer transition times)⁽⁴⁾						
t_{D_XtoY}	MultiSense transition delay from Ch _X to Ch _Y	$V_{IN0} = 5 \text{ V}; V_{IN1} = 5 \text{ V}; V_{SEN} = 5 \text{ V}; V_{SEL1} = 0 \text{ V}; V_{SEL0} = 0 \text{ V to } 5 \text{ V}; I_{OUT0} = 0 \text{ A}; I_{OUT1} = 3 \text{ A}; R_{SENSE} = 1 \text{ k}\Omega$			20	μs
t_{D_CStoTC}	MultiSense transition delay from current sense to T_C sense	$V_{IN0} = 5 \text{ V}; V_{SEN} = 5 \text{ V}; V_{SEL0} = 0 \text{ V}; V_{SEL1} = 0 \text{ V to } 5 \text{ V}; I_{OUT0} = 1.5 \text{ A}; R_{SENSE} = 1 \text{ k}\Omega$			60	μs

Table 9. MultiSense ($7 \text{ V} < V_{CC} < 18 \text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$) (continued)

Symbol	Parameter	Test conditions	Min.	Typ.	Max.	Unit
t_{D_TCtoCS}	MultiSense transition delay from T_C sense to current sense	$V_{IN0} = 5 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$; $V_{SEL1} = 5 \text{ V}$ to 0 V ; $I_{OUT0} = 1.5 \text{ A}$; $R_{SENSE} = 1 \text{ k}\Omega$			20	μs
$t_{D_CStoVCC}$	MultiSense transition delay from current sense to V_{CC} sense	$V_{IN1} = 5 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 5 \text{ V}$; $V_{SEL1} = 0 \text{ V}$ to 5 V ; $I_{OUT1} = 1.5 \text{ A}$; $R_{SENSE} = 1 \text{ k}\Omega$			60	μs
$t_{D_VCCtoCS}$	MultiSense transition delay from V_{CC} sense to current sense	$V_{IN1} = 5 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 5 \text{ V}$; $V_{SEL1} = 5 \text{ V}$ to 0 V ; $I_{OUT1} = 1.5 \text{ A}$; $R_{SENSE} = 1 \text{ k}\Omega$			20	μs
$t_{D_TCtoVCC}$	MultiSense transition delay from T_C sense to V_{CC} sense	$V_{CC} = 13 \text{ V}$; $T_j = 125^\circ\text{C}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 0 \text{ V}$ to 5 V ; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$			20	μs
$t_{D_VCCtoTC}$	MultiSense transition delay from V_{CC} sense to T_C sense	$V_{CC} = 13 \text{ V}$; $T_j = 125^\circ\text{C}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL0} = 5 \text{ V}$ to 0 V ; $V_{SEL1} = 5 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$			20	μs
$t_{D_CStoVSENSEH}$	MultiSense transition delay from stable current sense on Ch_x to V_{SENSEH} on Ch_y	$V_{IN0} = 5 \text{ V}$; $V_{IN1} = 0 \text{ V}$; $V_{SEN} = 5 \text{ V}$; $V_{SEL1} = 0 \text{ V}$; $V_{SEL0} = 0 \text{ V}$ to 5 V ; $I_{OUT0} = 3 \text{ A}$; $V_{OUT1} = 4 \text{ V}$; $R_{SENSE} = 1 \text{ k}\Omega$			20	μs

1. Parameter guaranteed by design and characterization; not subject to production test.

2. All values refer to $V_{CC} = 13 \text{ V}$; $T_j = 25^\circ\text{C}$, unless otherwise specified

3. V_{CC} sensing and T_C sensing are referred to GND potential

4. Transition delay are measured up to +/- 10% of final conditions.

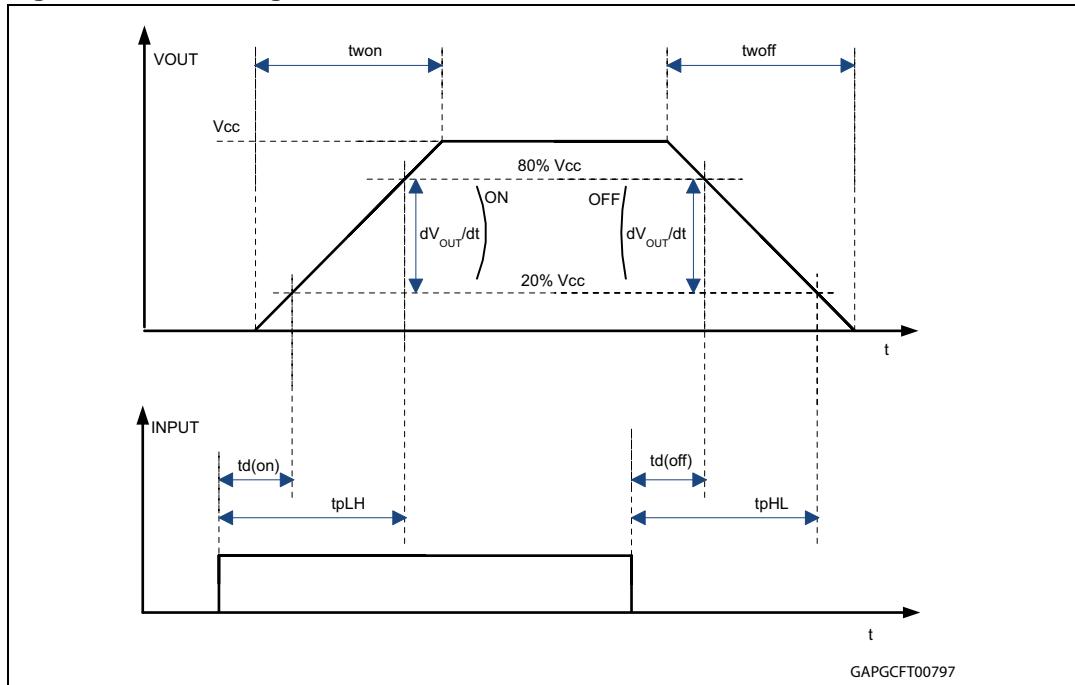
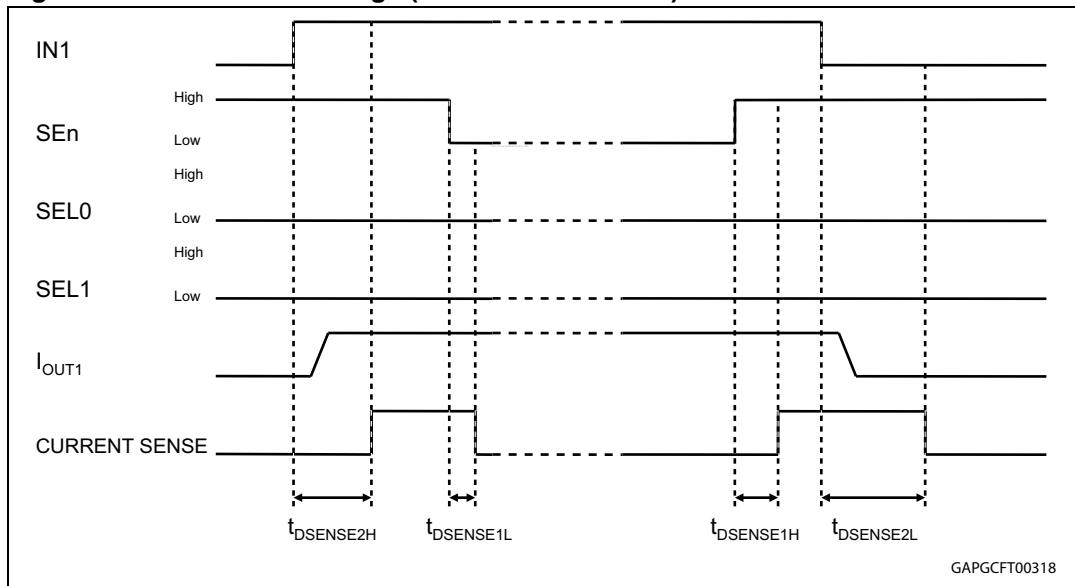
Figure 4. Switching time and Pulse skew**Figure 5. MultiSense timings (current sense mode)**

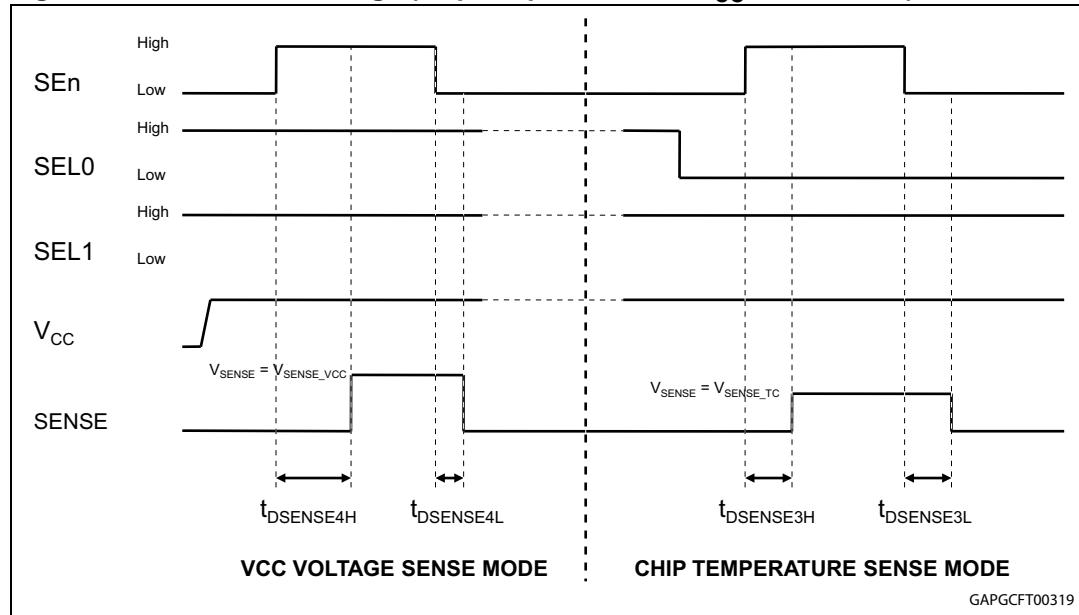
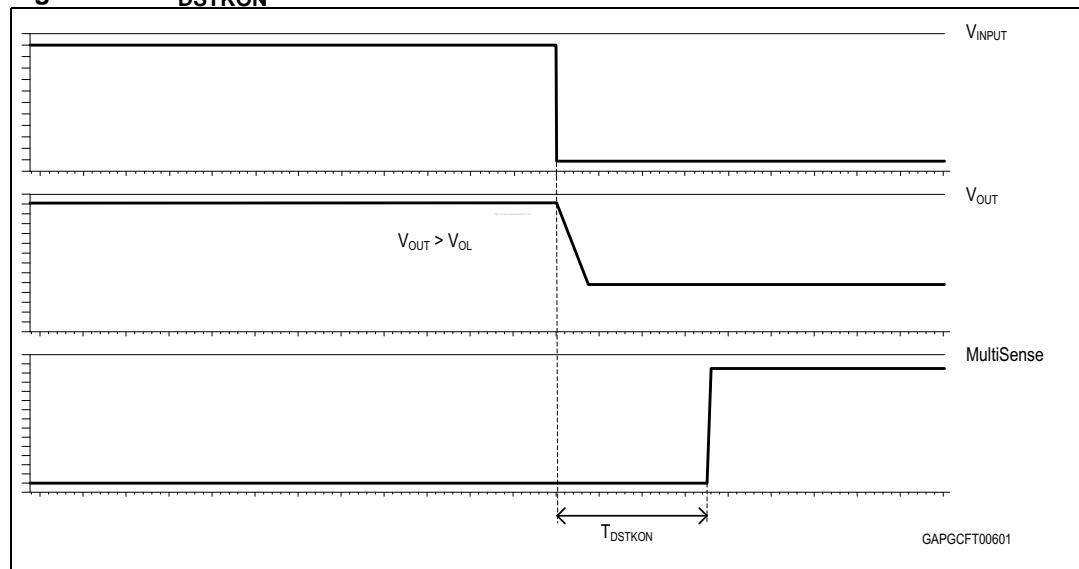
Figure 6. Multisense timings (chip temperature and V_{CC} sense mode)**Figure 7. T_{DSTKON}** 

Table 10. Truth table

Mode	Conditions	IN _X	FR	SEn	SEL _X	OUT _X	MultiSense	Comments
Stand by	All logic inputs low	L	L	L	L	L	Hi-Z	Low quiescent current consumption
Normal	Nominal load connected; T _j < 150 °C	L	X	Refer to <i>Table 11</i>	Refer to <i>Table 11</i>	L	Refer to <i>Table 11</i>	
		H	L			H		Outputs configured for auto-restart
		H	H			H		Outputs configured for Latch-off
Overload	Overload or short to GND causing: T _j > T _{TSD} or ΔT _j > ΔT _{J_TSD}	L	X	Refer to <i>Table 11</i>	Refer to <i>Table 11</i>	L	Refer to <i>Table 11</i>	
		H	L			H		Output cycles with temperature hysteresis
		H	H			L		Output latches-off
Undervoltage	V _{CC} < V _{USD} (falling)	X	X	X	X	L L	Hi-Z Hi-Z	Re-start when V _{CC} > V _{USD} + V _{USDhyst} (rising)
OFF-state diagnostics	Short to V _{CC}	L	X	Refer to <i>Table 11</i>	Refer to <i>Table 11</i>	H	Refer to <i>Table 11</i>	
	Open-load	L	X			H		External pull-up
Negative output voltage	Inductive loads turn-off	L	X	Refer to <i>Table 11</i>	< 0 V	Refer to <i>Table 11</i>		

Table 11. MultiSense multiplexer addressing

SEn	SEL ₁	SEL ₀	MUXchannel	MultiSense output			
				Nomal mode	Overload	OFF-state diag. ⁽¹⁾	Negative output
L	X	X		Hi-Z			
H	L	L	Channel 0 diagnostic	I _{SENSE} = 1/K * I _{OUT0}	V _{SENSE} = V _{SENSEH}	V _{SENSE} = V _{SENSEH}	0
H	L	H	Channel 1 diagnostic	I _{SENSE} = 1/K * I _{OUT1}	V _{SENSE} = V _{SENSEH}	V _{SENSE} = V _{SENSEH}	0
H	H	L	T _{CHIP} Sense	V _{SENSE} = V _{SENSE_TC}			
H	H	H	V _{CC} Sense	V _{SENSE} = V _{SENSE_VCC}			

1. In case the output channel corresponding to the selected MUX channel is latched off while the relevant input is low, Multisense pin delivers feedback according to OFF-State diagnostic.

Example 1: FR = 1; IN₀ = 0; OUT₀ = L (latched); MUX channel = channel 0 diagnostic; Mutisense = 0
 Example 2: FR = 1; IN₀ = 0; OUT₀ = latched, V_{OUT0} > V_{OL}; MUX channel = channel 0 diagnostic;
 Mutisense = V_{SENSEH}

Table 12. Electrical transient requirements (part 1/3)

ISO 7637-2: 2004(E) test pulse	Test levels ⁽¹⁾		Number of pulses or test times	Burst cycle / pulse repetition time		Delays and Impedance
	III	IV		Min.	Max.	
1	-75V	-100V	5000 pulses	0.5s	5s	2 ms, 10Ω
2a	+37V	+50V	5000 pulses	0.2s	5s	50µs, 2Ω
3a	-100V	-150V	1h	90ms	100ms	0.1µs, 50Ω
3b	+75V	+100V	1h	90ms	100ms	0.1µs, 50Ω
4	-6V	-7V	1 pulse			100ms, 0.01Ω
5b ⁽²⁾	+65V	+87V	1 pulse			400ms, 2Ω

1. The above test levels must be referred to $V_{CC} = 13.5$ V except for pulse 5b.
2. Valid in case of external load dump clamp: 40V maximum referred to ground ($-40^{\circ}\text{C} < T_j < 150^{\circ}\text{C}$).

Table 13. Electrical transient requirements (part 2/3)

ISO 7637-2: 2004E test pulse	Test level results	
	III	VI
1	C	C
2a	C	C
3a	C	C
3b	C	C
4	C	C
5b ⁽¹⁾	C	C

1. Valid in case of external load dump clamp: 40V maximum referred to ground ($-40^{\circ}\text{C} < T_j < 150^{\circ}\text{C}$).

Table 14. Electrical transient requirements (part 3/3)

Class	Contents
C	All functions of the device performed as designed after exposure to disturbance.
E	One or more functions of the device did not perform as designed after exposure to disturbance and cannot be returned to proper operation without replacing the device.

2.4 Waveforms

Figure 8. Latch functionality - behavior in hard short circuit condition ($T_{AMB} \ll T_{TSD}$)

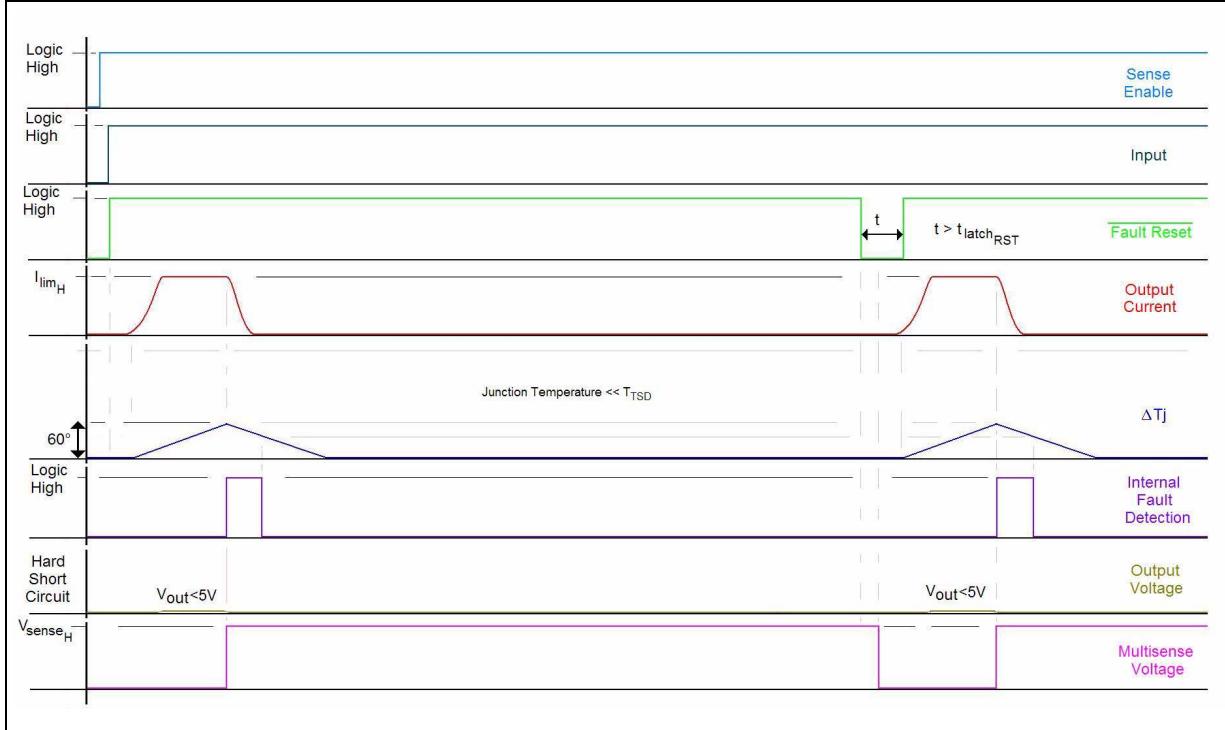


Figure 9. Latch functionality - behavior in hard short circuit condition

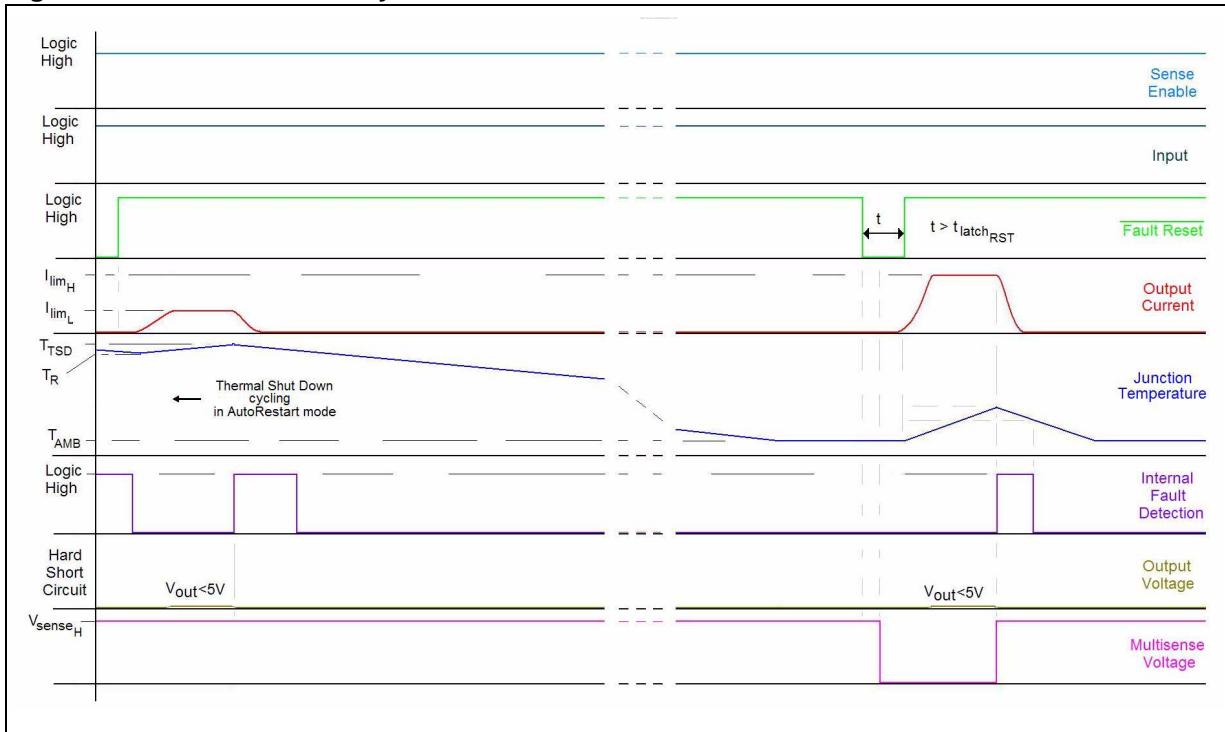


Figure 10. Latch functionality - behavior in hard short circuit condition (autorestart mode + latch off)

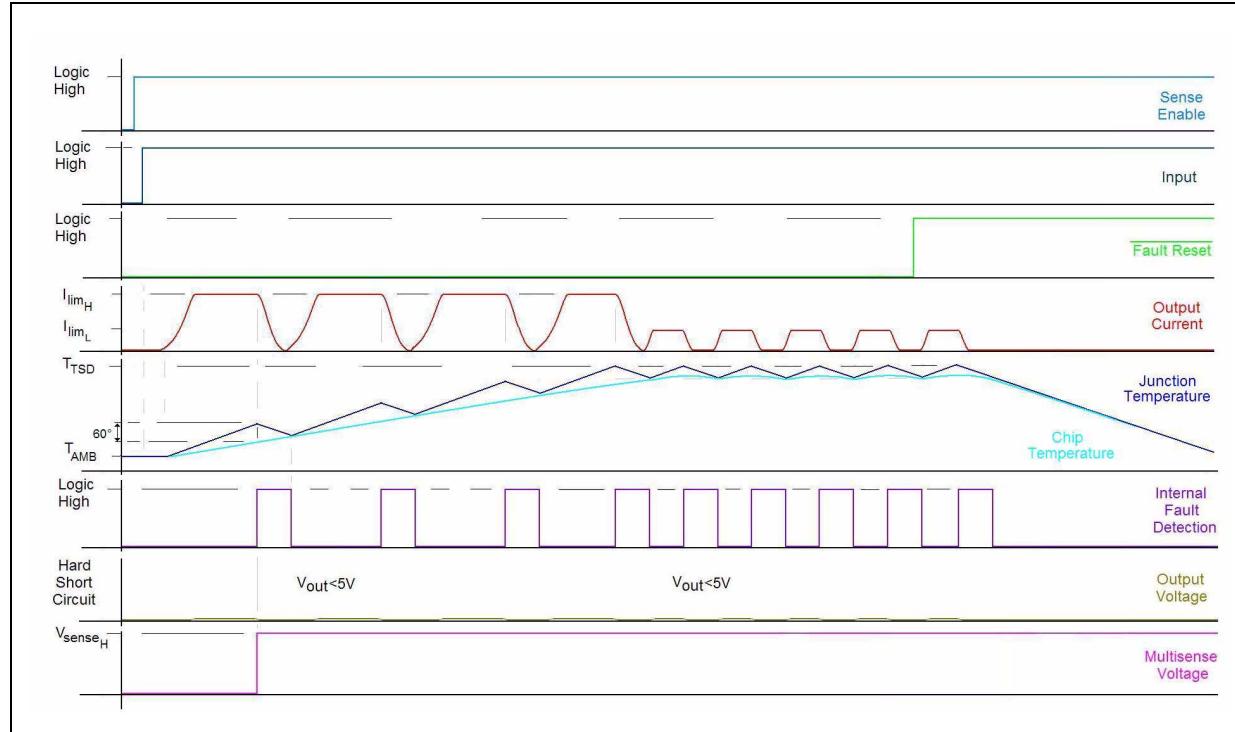


Figure 11. Standby mode activation

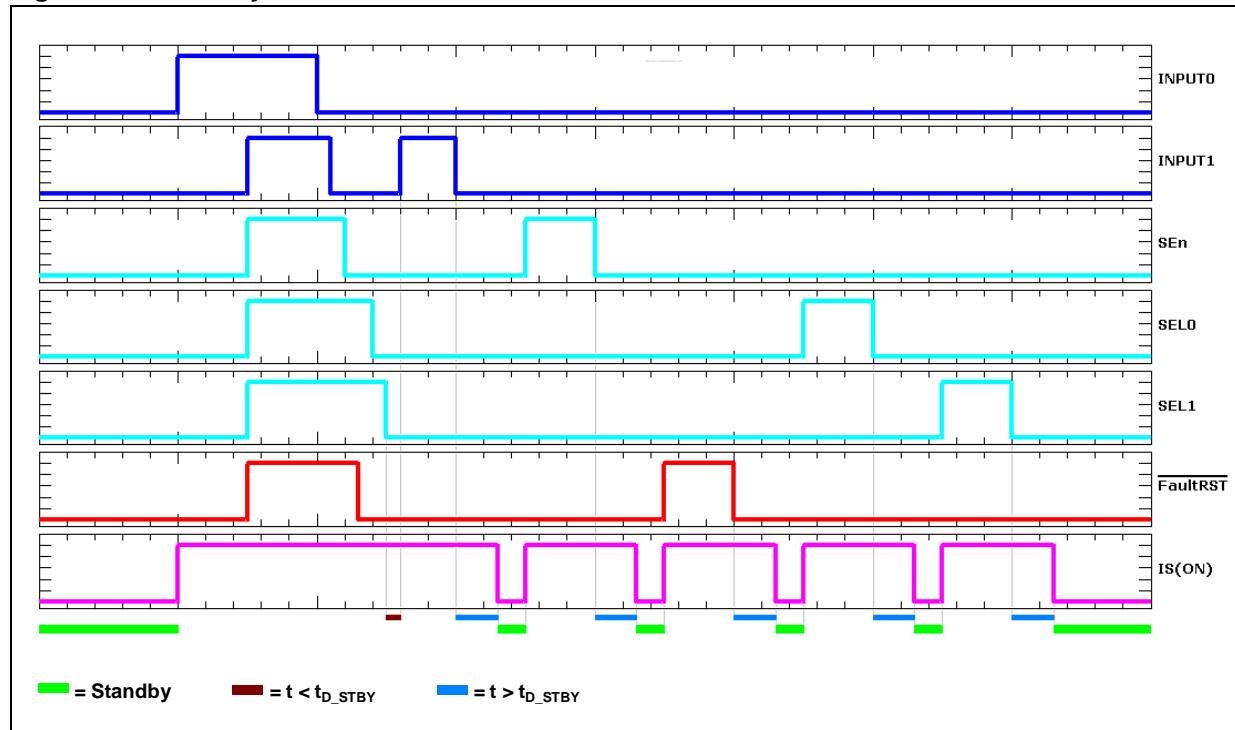
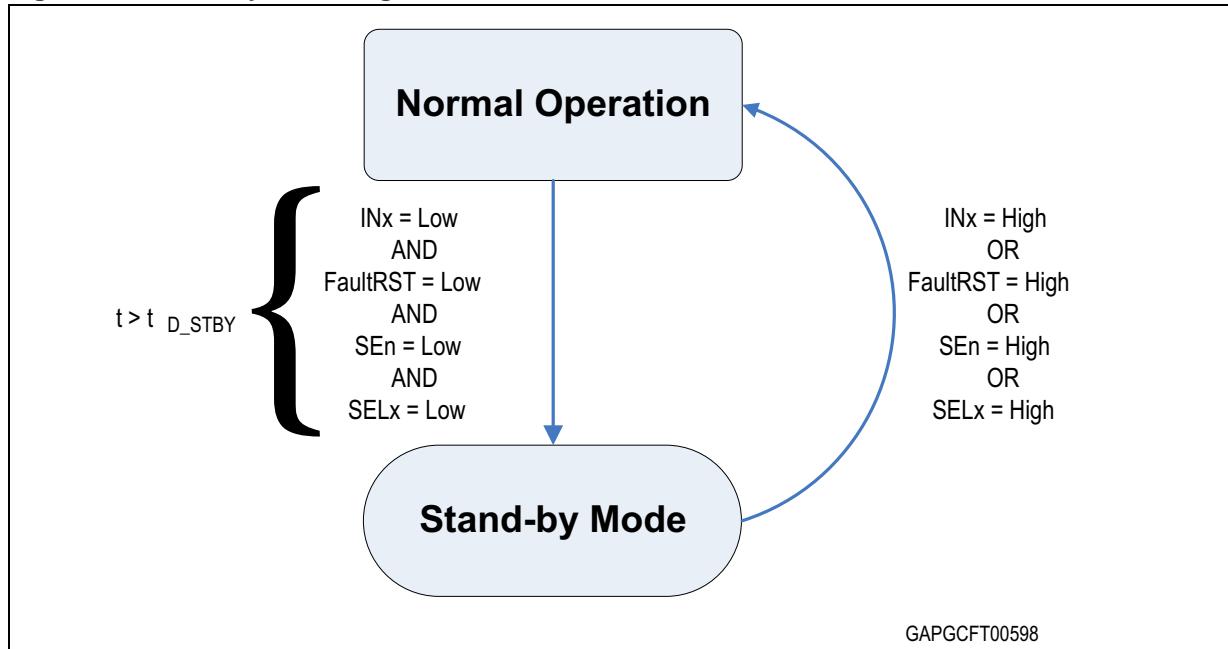


Figure 12. Standby state diagram

3 Protections

3.1 Power limitation

The basic working principle of this protection consists of an indirect measurement of the junction temperature swing ΔT_j through the direct measurement of the spatial temperature gradient on the device surface in order to automatically shut off the output MOSFET as soon as ΔT_j exceeds the safety level of 60 K. According to the voltage level on the FaultRST pin, the output MOSFET switches on and cycles with a thermal hysteresis according to the maximum instantaneous power which can be handled (FaultRST = Low) or remains off (FaultRST = High). The protection prevents fast thermal transient effects and, consequently, reduces thermo-mechanical fatigue.

3.2 Thermal shutdown

In case the junction temperature of the device exceeds the maximum allowed threshold (typically 175°C), it automatically switches off and the diagnostic indication is triggered. According to the voltage level on the FaultRST pin, the device switches on again as soon as its junction temperature drops to T_{RS} (see [Table 8](#), FaultRST = Low) or remains off (FaultRST = High).

3.3 Current limitation

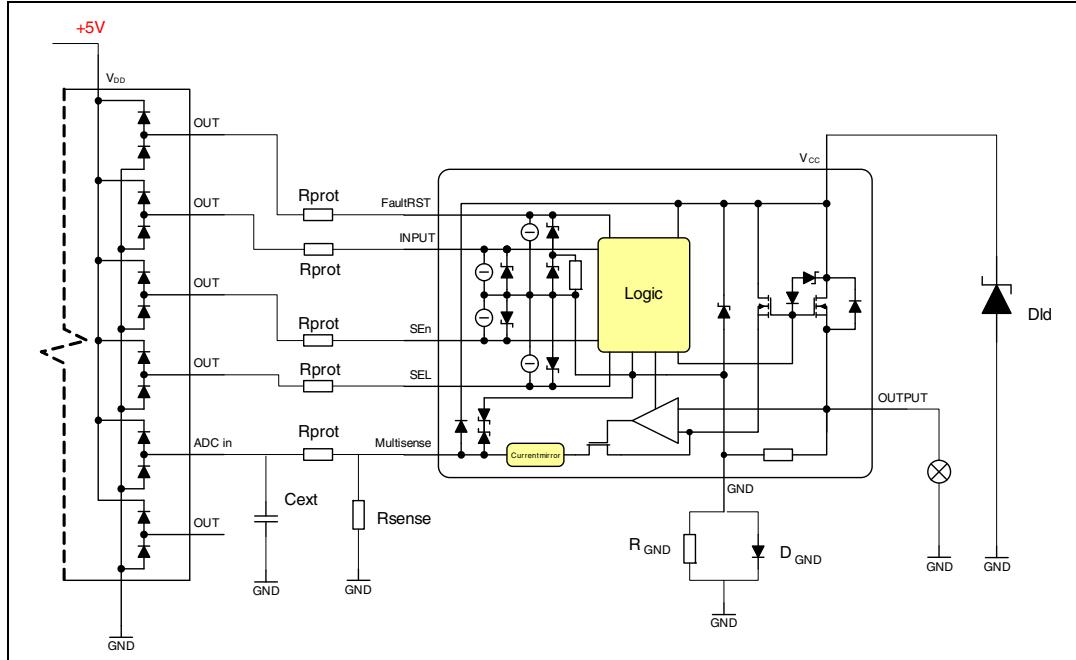
The device is equipped with an output current limiter in order to protect the silicon as well as the other components of the system (e.g. bonding wires, wiring harness, connectors, loads, etc.) from excessive current flow. Consequently, in case of short circuit, overload or during load power-up, the output current is clamped to a safety level, I_{LIMH} , by operating the output power MOSFET in the active region.

3.4 Negative voltage clamp

In case the device drives inductive load, the output voltage reaches negative value during turn off. A negative voltage clamp structure limits the maximum negative voltage to a certain value, V_{CLAMP} (see [Table 5](#)), allowing the inductor energy to be dissipated without damaging the device.

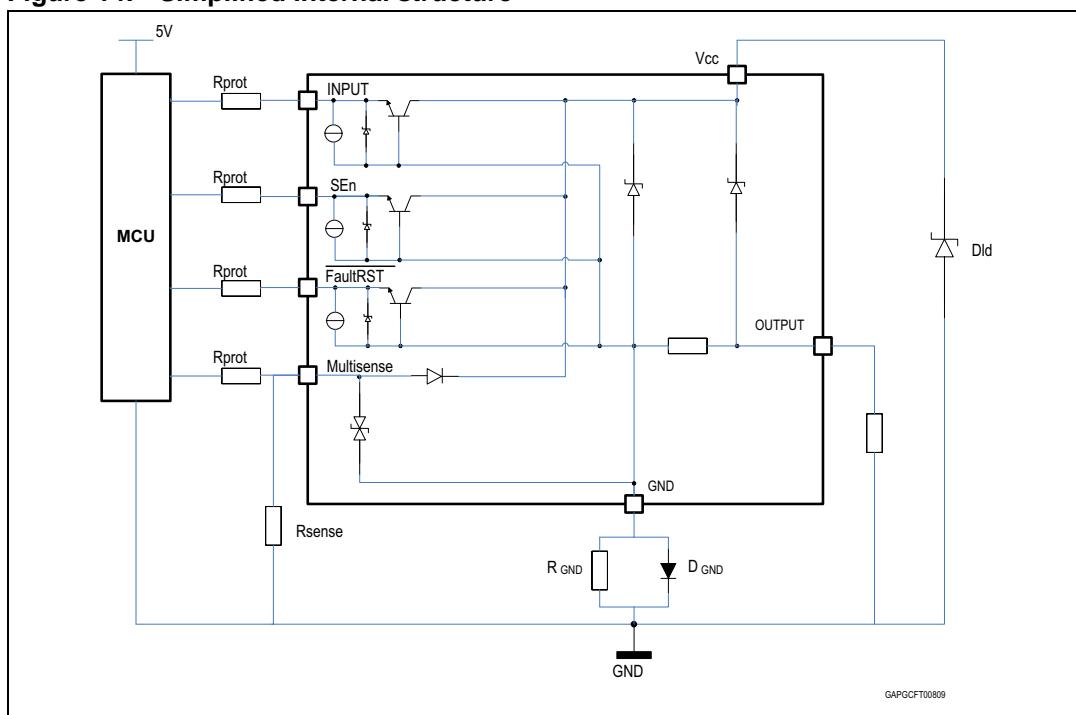
4 Application information

Figure 13. Application diagram



4.1 GND protection network against reverse battery

Figure 14. Simplified internal structure



4.1.1 Diode (D_{GND}) in the ground line

A resistor (typ. $R_{GND} = 1 \text{ k}\Omega$) should be inserted in parallel to D_{GND} if the device drives an inductive load.

This small signal diode can be safely shared amongst several different HSDs. Also in this case, the presence of the ground network produces a shift ($\approx 600 \text{ mV}$) in the input threshold and in the status output values if the microprocessor ground is not common to the device ground. This shift does not vary if more than one HSD shares the same diode/resistor network.

4.2 Load dump protection

D_{ld} is necessary (voltage transient suppressor) if the load dump peak voltage exceeds pulse 5b, from [Table 12: Electrical transient requirements \(part 1/3\)](#) according to ISO7637-2:2004(E), clamped at 40 V. The same applies if the device is subject to transients on the V_{CC} line that are greater than the ones shown in the ISO T/R 7637/1 table.

4.3 MCU I/Os protection

If a ground protection network is used and negative transients are present on the V_{CC} line, the control pins will be pulled negative. ST suggests to insert a resistor (R_{prot}) in line both to prevent the microcontroller I/O pins to latch-up and to protect the HSD inputs.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of microcontroller I/Os.

Equation 1

$$V_{CCpeak}/I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

Calculation example:

For $V_{CCpeak} = -150 \text{ V}$; $I_{latchup} \geq 20 \text{ mA}$; $V_{OH\mu C} \geq 4.5 \text{ V}$

$$7.5 \text{ k}\Omega \leq R_{prot} \leq 140 \text{ k}\Omega$$

Recommended values: $R_{prot} = 15 \text{ k}\Omega$

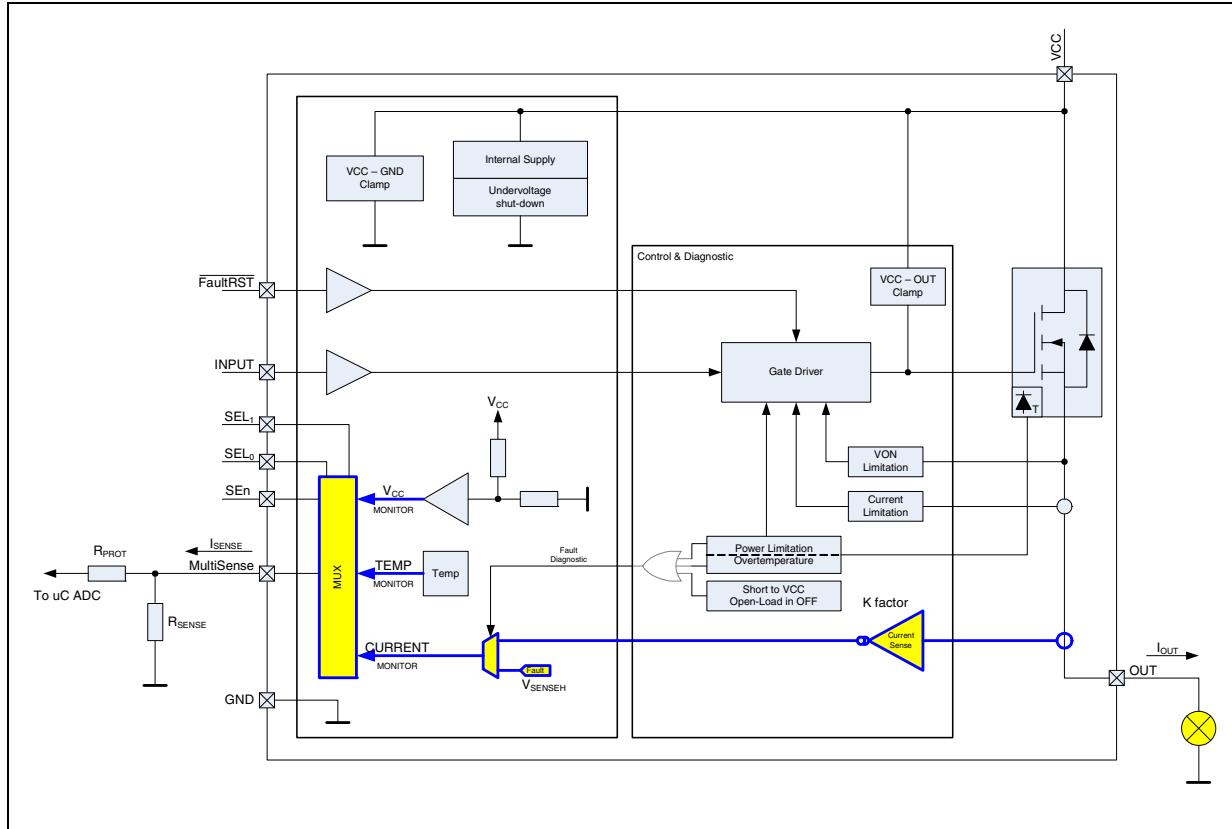
4.4 Multisense - analog current sense

Diagnostic information on device and load status are provided by an analog output pin (Multisense) delivering the following signals:

- Current monitor: current mirror of channel output current
- V_{CC} monitor: voltage proportional to V_{CC}
- T_{CASE} : voltage proportional to chip temperature

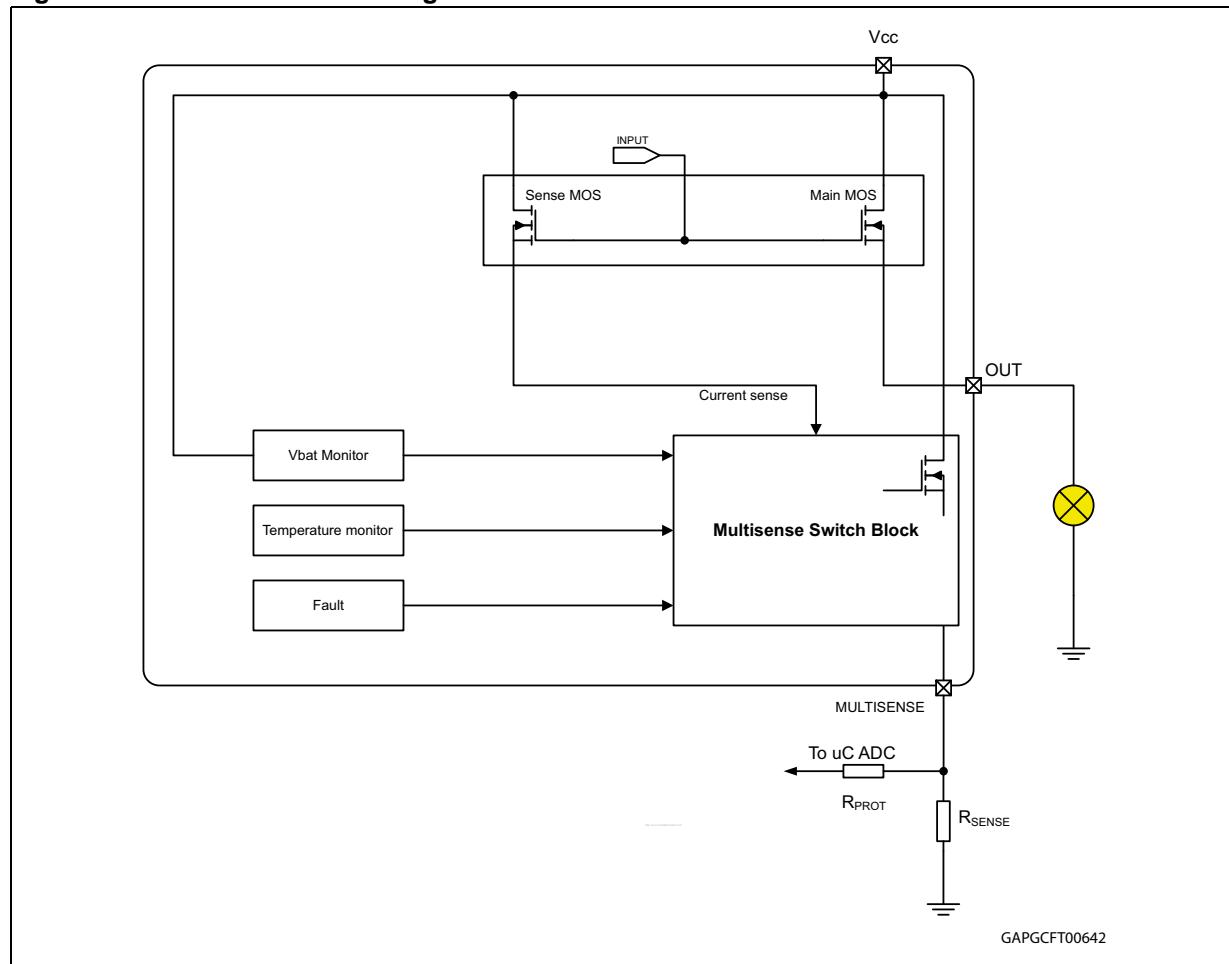
Those signals are routed through an analog multiplexer which is configured and controlled by means of SELx and SEn pins, according to the address map in [Table 11](#).

Figure 15. Multisense and diagnostic – block diagram



4.4.1 Principle of Multisense signal generation

Figure 16. Multisense block diagram



- **Current monitor**

During **no fault conditions** ($V_{OUT} > V_{OUT_MSD}$ - see [Table 9](#)), current flowing through Main MOS is mirrored through Sense MOS. Sense MOS is a scaled down copy of the Main MOS according to a defined geometric ratio. Current is passed through M1 and amplified by current mirror M2, M3. Following current mirror (consisting from M4, M5) is used to fully decouple Multisense signal from output current.

In **fault conditions**, internal logic switch Multisense mode to deliver constant voltage on the output (typically V_{SENSEH}).

- **Temperature, V_{BAT} monitor**

Internal logic is switched to voltage output mode, applying output voltage corresponding to temperature or V_{CC} sensor (according to the selected signal).

Current monitor

When current mode is selected in the Multisense, this output is capable to provide:

- **Current mirror proportional to the load current in normal operation**, delivering current proportional to the load according to known ratio named **K**
- **Diagnostics flag in fault conditions** delivering fixed voltage V_{SENSEH}

The current delivered by the current sense circuit, I_{SENSE} , can be easily converted to a voltage V_{SENSE} by using an external sense resistor, R_{SENSE} , allowing continuous load monitoring and abnormal condition detection.

Normal operation (channel ON, no fault, SEn active)

While device is operating in normal conditions (no fault intervention), V_{SENSE} calculation can be done using simple equations

Current provided by Multisense output: $I_{SENSE} = I_{OUT}/K$

Voltage on R_{SENSE} : $V_{SENSE} = R_{SENSE} \cdot I_{SENSE} = R_{SENSE} \cdot I_{OUT}/K$

Where :

- V_{SENSE} is voltage measurable on R_{SENSE} resistor
- I_{SENSE} is current provided from Multisense pin in current output mode
- I_{OUT} is current flowing through output
- K factor represent the ratio between PowerMOS cells and SenseMOS cells; its spread includes geometric factor spread, current sense amplifier offset and process parameters spread of overall circuitry specifying ratio between I_{OUT} and I_{SENSE} .

Failure flag indication

In case of power limitation/overtemperature, the fault is indicated by the Multisense pin which is switched to a “current limited” voltage source, V_{SENSEH} (see [Table 9](#)).

In any case, the current sourced by the Multisense in this condition is limited to I_{SENSEH} (see [Table 9](#)).

The typical behavior in case of overload or hard short circuit is shown in [Figure 8](#), [Figure 9](#) and [Figure 10](#).

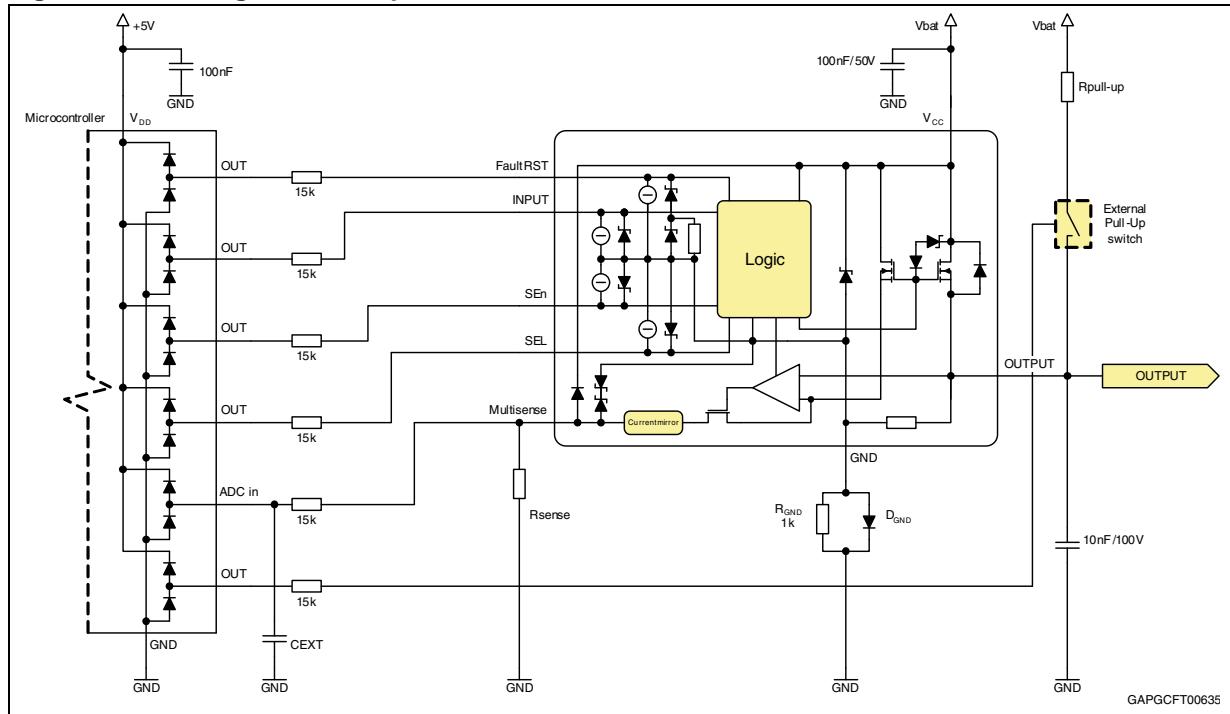
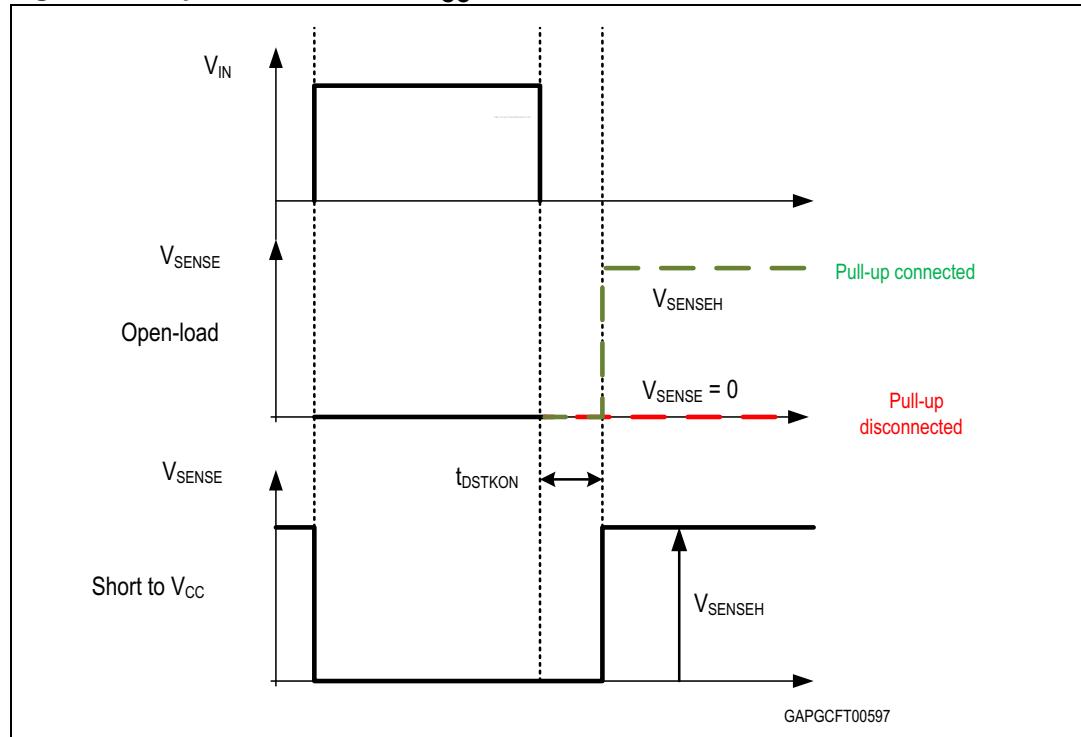
Figure 17. Analogue HSD – open-load detection in off-state**Figure 18.** Open-load / short to V_{CC} condition

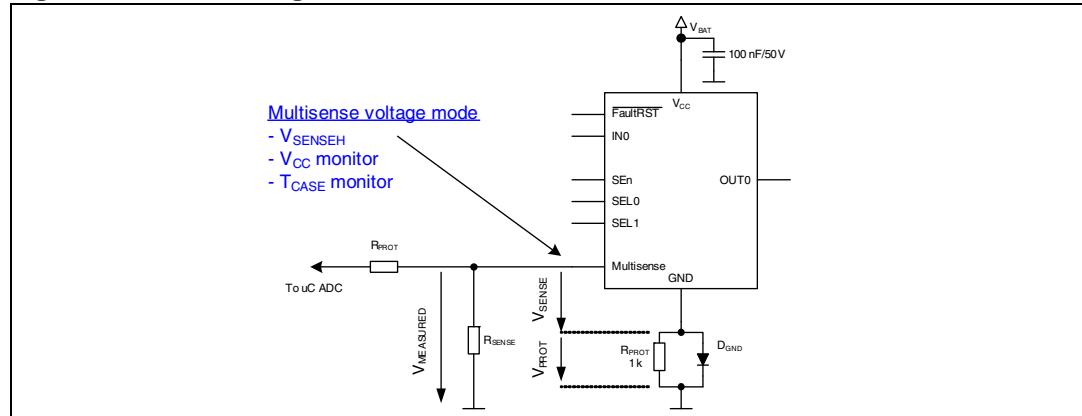
Table 15. Multisense pin levels in off-state

Condition	Pull up	Multisense	SEn
Open-load	Yes	0	L
		V_{SENSEH}	H
	No	0	L
		0	H
Short to V_{CC}	Yes	0	L
		V_{SENSEH}	H
	No	0	L
		V_{SENSEH}	H
Nominal	Yes	0	L
		0	H
	No	0	L
		0	H

4.4.2 T_{CASE} and V_{CC} monitor

In this case, MultiSense output operates in voltage mode and output level is referred to device GND. Care must be taken in case a GND network protection is used, because of a voltage shift is generated between device GND and the microcontroller input GND reference.

Figure 19 shows link between $V_{MEASURED}$ and real V_{SENSE} signal.

Figure 19. GND voltage shift

V_{CC} monitor

Battery monitoring channel provides $V_{SENSE} = V_{CC} / 4$.

Case temperature monitor

Case temperature monitor is capable to provide information about actual device temperature. Since diode is used for temperature sensing, following equation describe link between temperature and output V_{SENSE} level:

$$V_{SENSE_TC}(T) = V_{SENSE_TC}(T_0) + dV_{SENSE_TC} / dT * (T - T_0)$$

where $dV_{SENSE_TC} / dT \sim$ typically -5.5 mV/K (for temperature range $(-40^\circ\text{C} \text{ to } +150^\circ\text{C})$.

4.4.3 Short to V_{CC} and OFF-state open-load detection

Short to V_{CC}

A short circuit between V_{CC} and output is indicated by the relevant current sense pin set to V_{SENSEH} during the device off-state. Small or no current is delivered by the current sense during the on-state depending on the nature of the short circuit.

OFF-state open-load with external circuitry

Detection of an open-load in off mode requires an external pull-up resistor R_{PU} connecting the output to a positive supply voltage V_{PU} .

It is preferable V_{PU} to be switched off during the module standby mode in order to avoid the overall standby current consumption to increase in normal conditions, i.e. when load is connected.

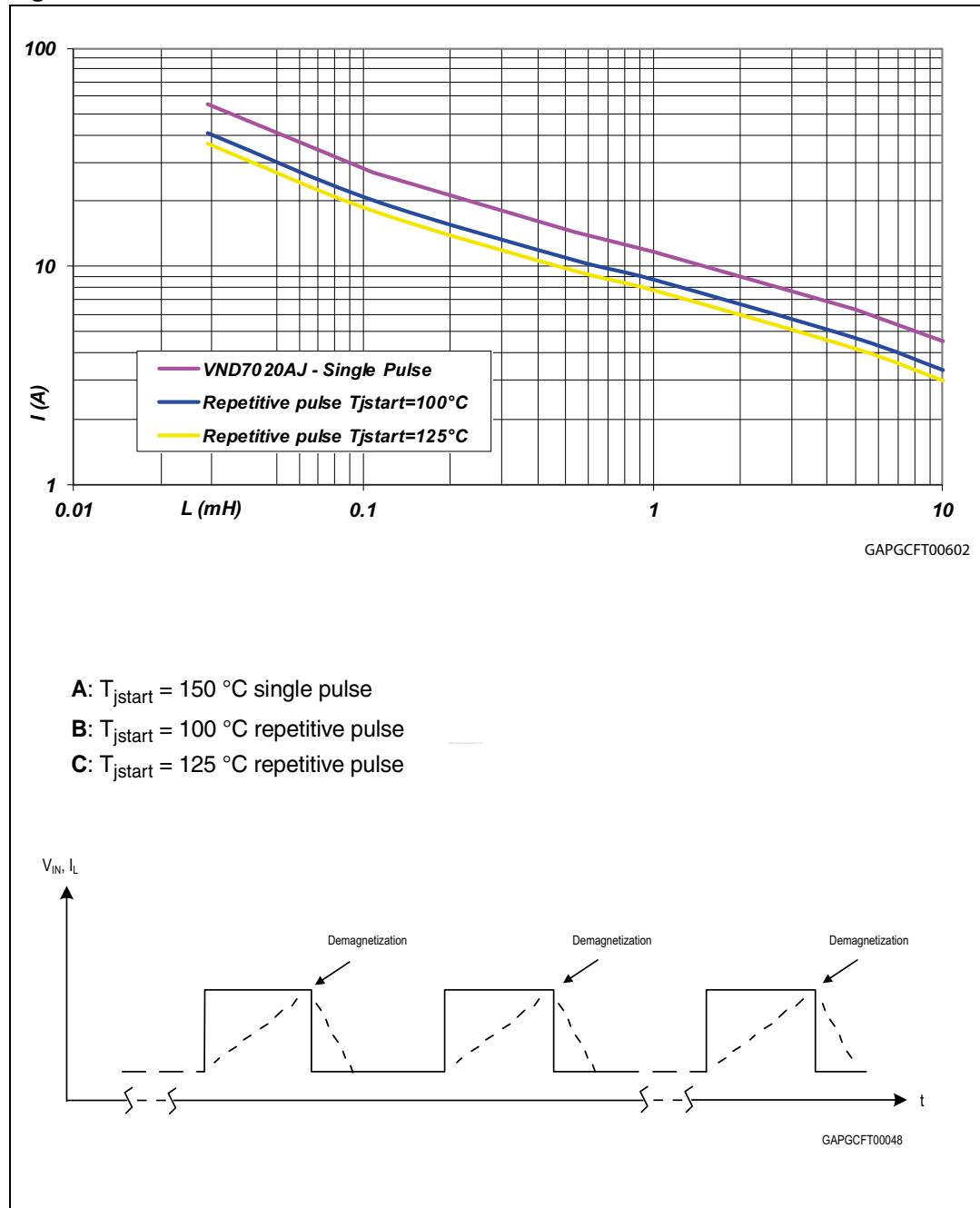
R_{PU} must be selected in order to ensure $V_{OUT} > V_{OLmax}$ in accordance with to following equation:

Equation 2

$$R_{PU} < \frac{V_{PU} - 4}{I_{L(off2)min @ 4V}}$$

4.5 Maximum demagnetization energy ($V_{CC} = 13.5$ V)

Figure 20. Maximum turn off current versus inductance⁽¹⁾

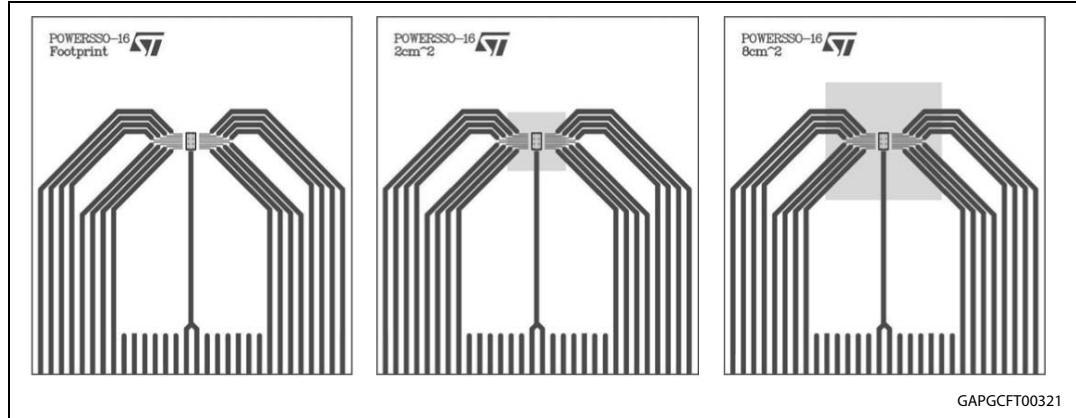


1. Values are generated with $R_L = 0 \Omega$.
In case of repetitive pulses, T_{jstart} (at the beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves A and B.

5 Package and PCB thermal data

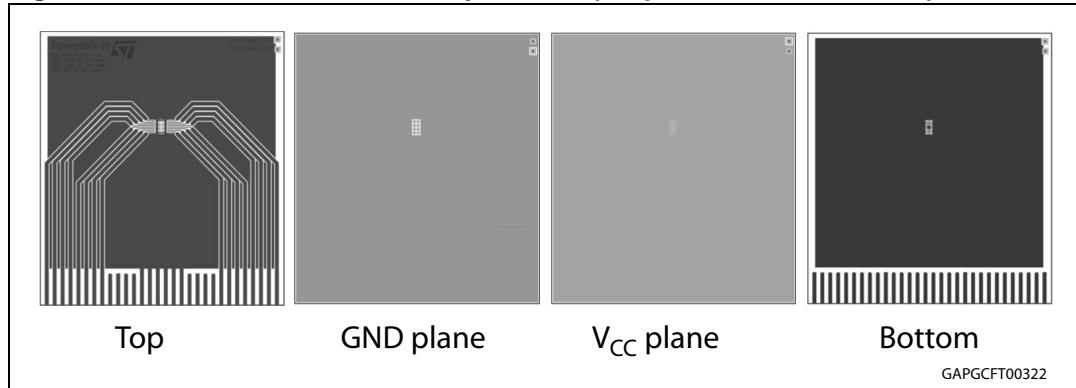
5.1 PowerSSO-16 thermal data

Figure 21. PowerSSO-16 on two-layers PCB (2s0p to JEDEC JESD 51-5)



GAPGCFT00321

Figure 22. PowerSSO-16 on four-layers PCB (2s2p to JEDEC JESD 51-7)



GAPGCFT00322

Table 16. PCB properties

Dimension	Value
Board finish thickness	0.6 mm +/- 10%
Board dimension	77 mm x 86 mm
Board Material	FR4
Copper thickness (top and bottom layers)	0.070 mm
Copper thickness (inner layers)	0.035 mm
Thermal vias separation	1.2 mm
Thermal via diameter	0.3 mm +/- 0.08 mm
Copper thickness on vias	0.025 mm
Footprint dimension (top layer)	2.2 mm x 3.9 mm
Heatsink copper area dimension (bottom layer)	Footprint, 2 cm ² or 8 cm ²

Figure 23. $R_{thj\text{-amb}}$ vs PCB copper area in open box free air condition (one channel on)

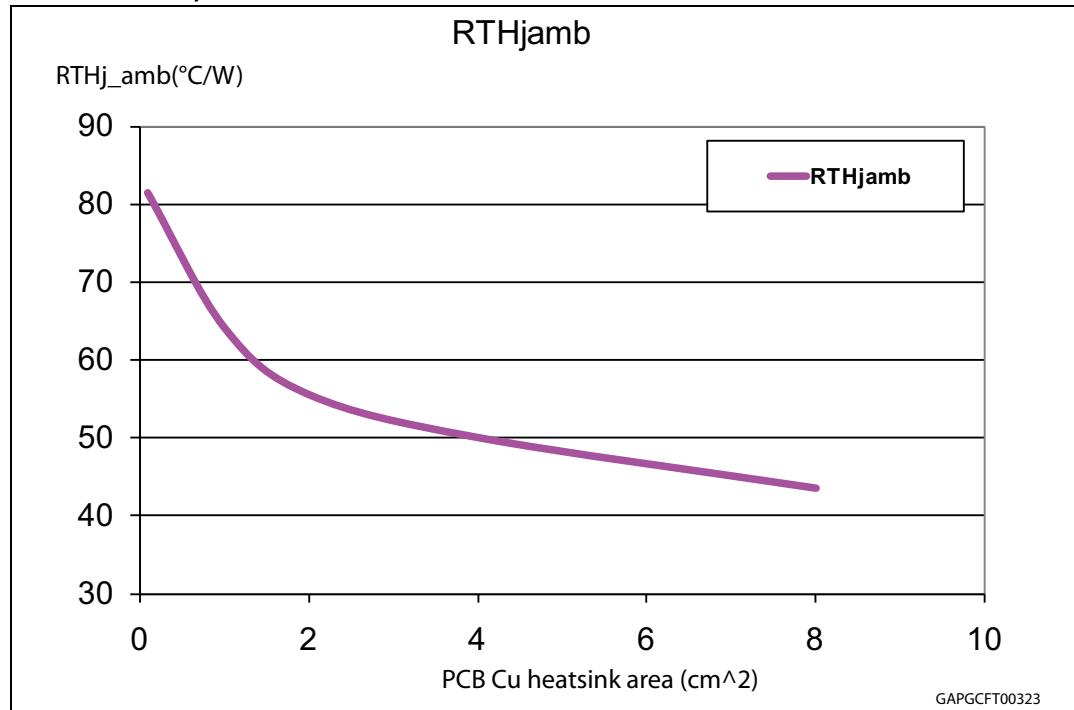
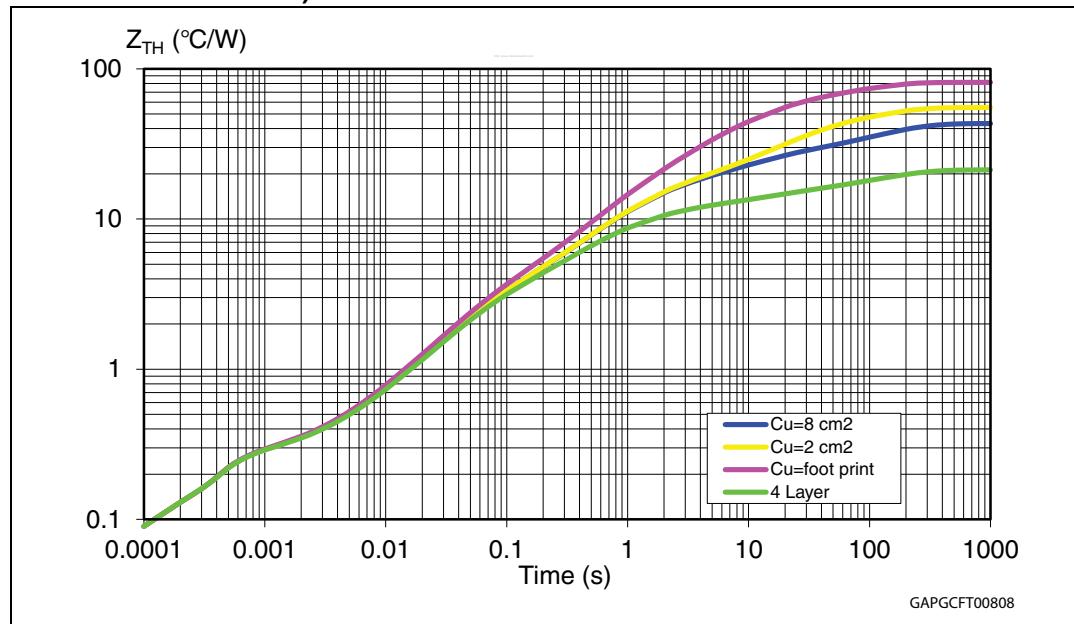


Figure 24. PowerSSO-16 thermal impedance junction ambient single pulse (one channel on)

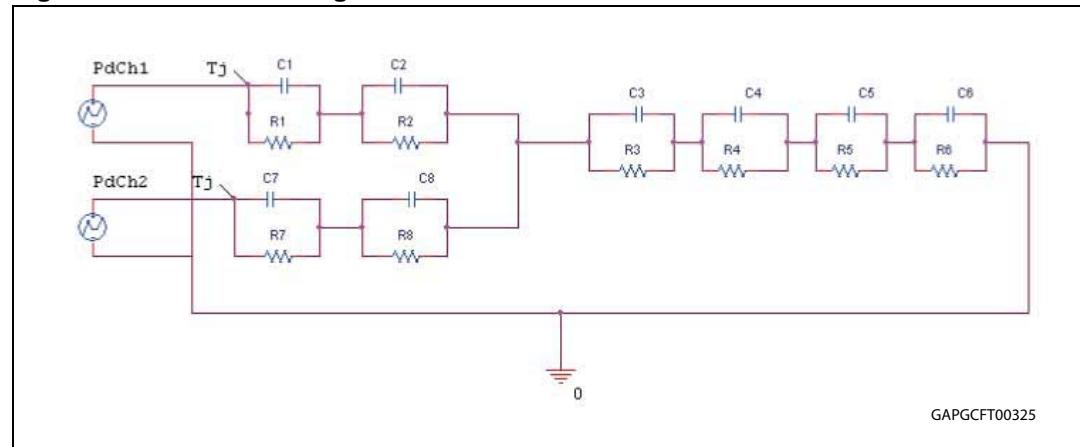


Equation 3: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where $\delta = t_p/T$

Figure 25. Thermal fitting model of a double-channel HSD in PowerSSO-16⁽¹⁾



1. The fitting model is a simplified thermal tool and is valid for transient evolutions where the embedded protections (power limitation or thermal cycling during thermal shutdown) are not triggered.

Table 17. Thermal parameters

Area/island (cm ²)	Footprint	2	8	4L
R1 = R7 (°C/W)	0.25			
R2 = R8 (°C/W)	2			
R3 (°C/W)	7	7	7	5
R4 (°C/W)	16	6	6	4
R5 (°C/W)	30	20	10	3
R6 (°C/W)	26	20	18	7
C1 = C7 (W.s/°C)	0.001			
C2 = C8 (W.s/°C)	0.025			
C3 (W.s/°C)	0.1			
C4 (W.s/°C)	0.2	0.3	0.3	0.4
C5 (W.s/°C)	0.4	1	1	4
C6 (W.s/°C)	3	5	7	18

6 Package information

6.1 ECOPACK®

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com.

ECOPACK® is an ST trademark.

6.2 PowerSSO-16 package information

Figure 26. PowerSSO-16 package dimensions

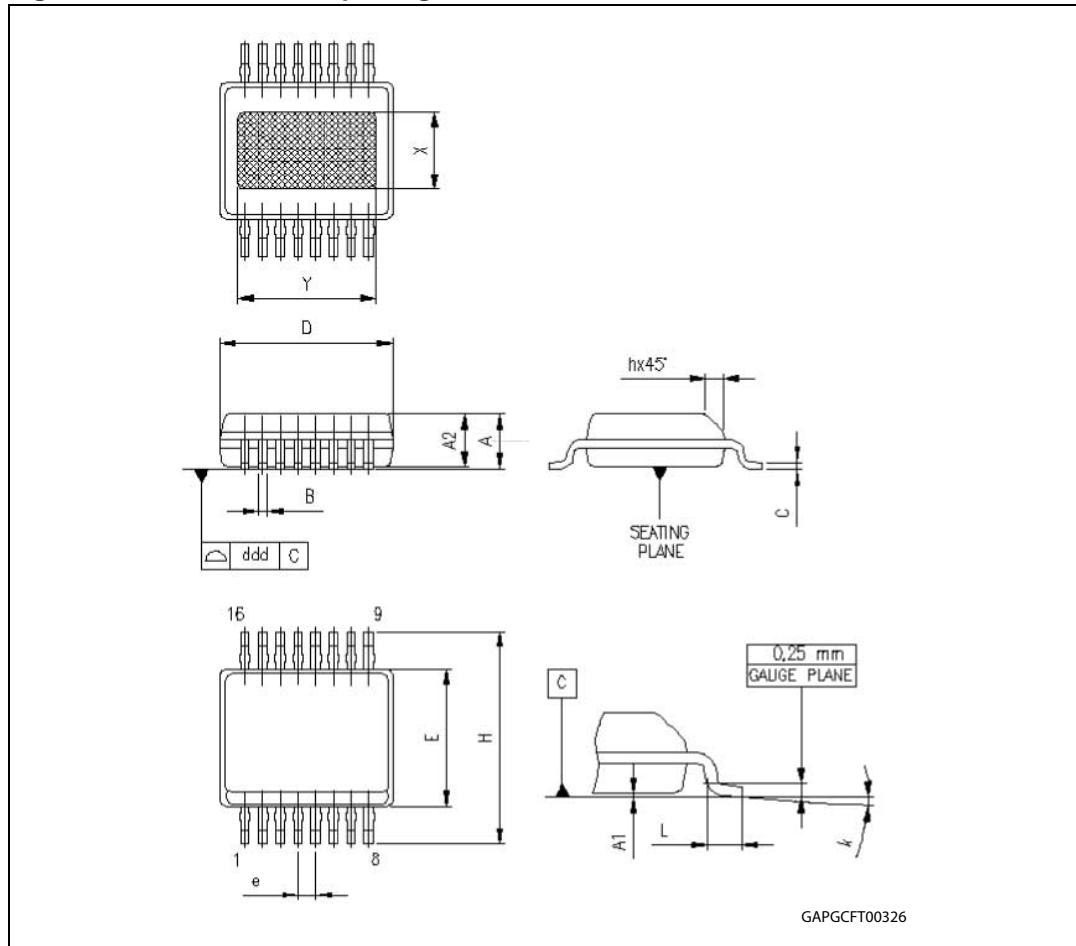


Table 18. PowerSSO-16 mechanical data

Symbol	Millimeters		
	Min.	Typ.	Max.
A	1.25		1.72
A1	0.00		0.10
A2	1.10		1.62
B	0.18		0.36
C	0.19		0.25
D	4.80		5.00
E	3.80		4.00
e		0.50	
H	5.80		6.20
h	0.25		0.50
L	0.40		1.27
k	0d		8d
X	1.90		2.50
Y	3.60		4.20
ddd			0.10

- Note:
- 1 *Dimensions D does not include mold Flash protrusions or gate burrs.
Mold Flash protrusions or gate burrs shall not exceed 0.15mm in total (both side).*
 - 2 *Drawings dimensions include Single and Matrix versions.*

7 Order codes

Table 19. Device summary

Package	Order codes	
	Tube	Tape and reel
PowerSSO-16	VND7020AJ-E	VND7020AJTR-E

8 Revision history

Table 20. Revision history

Date	Revision	Changes
02-May-2011	1	Initial release.
14-Mar-2012	2	<p>Updated Table 2: Suggested connections for unused and not connected pins</p> <p>Table 3: Absolute maximum ratings:</p> <ul style="list-style-type: none"> – V_{FR}, $-I_{OUT}$: updated value – $-V_{SENSE}$: removed row – V_{ESD}: updated parameter <p>Table 5: Power section:</p> <ul style="list-style-type: none"> – $V_{USDReset}$: added row – $I_{GND(ON)}$: added test condition – V_{clamp}: removed test condition – t_{D_STBY}: updated min, typ and max values <p>Updated Table 6: Switching ($VCC = 13\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$, unless otherwise specified)</p> <p>Table 7: Logic Inputs ($7\text{ V} < VCC < 28\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</p> <ul style="list-style-type: none"> – V_{ICL}, V_{SELCL}, V_{SEnCL}, V_{FRCL}: updated max value <p>Table 8: Protections ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</p> <ul style="list-style-type: none"> – V_{DEMAG}: updated min value – t_{LATCH_RST}: updated min, typ and max values <p>Updated Table 9: MultiSense ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$)</p> <p>Updated Figure 4: Switching time and Pulse skew</p> <p>Table 10: Truth table: updated test condition for Overload mode</p> <p>Updated Section 2.4: Waveforms</p> <p>Added following section:</p> <ul style="list-style-type: none"> – Section 4.1: GND protection network against reverse battery – Section 4.2: Load dump protection – Section 4.3: MCU I/Os protection – Section 4.4: Multisense - analog current sense <p>Updated Table 17: Thermal parameters</p>

Table 20. Revision history

Date	Revision	Changes
27-Jun-2012	3	<p><i>Table 3: Absolute maximum ratings:</i></p> <ul style="list-style-type: none"> – I_{SENSE}: updated parameter description – V_{ESD}: updated values <p>Updated <i>Table 4: Thermal data</i></p> <p><i>Table 5: Power section:</i></p> <ul style="list-style-type: none"> – V_{clamp}: added test condition – $I_{GND(ON)}$: updated test condition <p><i>Table 6: Switching ($VCC = 13\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$, unless otherwise specified):</i></p> <ul style="list-style-type: none"> – W_{ON}, W_{OFF}, t_{SKew}: updated values <p><i>Table 8: Protections ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</i></p> <ul style="list-style-type: none"> – I_{LIMH}, T_R: added note – V_{ON}: updated test condition <p><i>Table 9: MultiSense ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</i></p> <ul style="list-style-type: none"> – K_{OL}, dK_{cal}/K_{cal}, K_{LED}, dK_{LED}/K_{LED}, K_0, dK_0/K_0, K_1, dK_1/K_1, K_2, dK_2/K_2, K_3, dK_3/K_3: updated test condition – $I_{L(off2)}$, V_{SENSE_TC}, V_{SENSE_VCC}, I_{SENSEH}, I_{SENSE0}, V_{SENSE_SAT}, I_{SENSE_SAT}, V_{SENSEH}: updated values – I_{OUT_SAT}: added row <p>Updated <i>Figure 4: Switching time and Pulse skew</i></p> <p>Removed figure <i>Pulse skew</i></p> <p><i>Table 11: MultiSense multiplexer addressing:</i> added note</p> <p>Updated <i>Figure 14: Simplified internal structure</i> and <i>Figure 24: PowerSSO-16 thermal impedance junction ambient single pulse (one channel on)</i></p> <p>Updated <i>Table 17: Thermal parameters</i></p>
13-Sep-2012	4	<p><i>Table 8: Protections ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</i></p> <ul style="list-style-type: none"> – T_{LATCH_RST}: added note <p><i>Table 9: MultiSense ($7\text{ V} < VCC < 18\text{ V}$; $-40^\circ\text{C} < T_j < 150^\circ\text{C}$):</i></p> <ul style="list-style-type: none"> – dK_{LED}/K_{LED}, dK_0/K_0, dK_1/K_1, dK_2/K_2, dK_3/K_3, I_{SENSE_SAT}, I_{OUT_SAT}: added note

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