

$8M \times 4$ BANKS $\times 8$ BIT DDR SDRAM

Table of Contents-

10.

1.	GENERAL DESCRIPTION	3
2.	FEATURES	3
3.	KEY PARAMETERS	4
4.	PIN CONFIGURATION	5
5.	PIN DESCRIPTION	6
6.	BLOCK DIAGRAM	7
7.	ELECTRICAL CHARACTERISTICS	8
7.1	Absolute Maximum Ratings	8
7.2	Recommended DC Operating Conditions	8
7.3	Capacitance	9
7.4	Leakage and Output Buffer Characteristics	9
7.5	DC Characteristics	10
7.6	AC Characteristics and Operating Condition	11
7.7	AC Test Conditions	13
8.	Operation Mode	15
8.1	Simplified Truth Table	
8.2	Function Truth Table	
8.3	Function Truth Table for CKE	19
8.4	Simplified State Diagram	
9.	FUNCTIONAL DESCRIPTION	
9.1	Power Up Sequence	21
9.2	Command Function	21
9.3	Read Operation	
9.4	Write Operation	
9.5	Precharge	24
9.6	Burst Termination	
9.7	Refresh Operation	
9.8	Power Down Mode	
9.9	Mode Register Operation	25
TIMING	WAVEFORMS	29
10.1	Command Input Timing	29
10.2	Timing of the CLK Signals	29
10.3	Read Timing (Burst Length = 4)	
10.4	Write Timing (Burst Length = 4)	
10.5	DM, DATA MASK (W942508CH/W942504CH)	

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11.

12.

10.6	DM, DATA MASK (W942516CH)	. 32
10.7	Mode Register Set (MRS) Timing	. 33
10.8	Extend Mode Register Set (EMRS) Timing	. 34
10.9	Auto Precharge Timing (Read Cycle, CL = 2)	.35
10.10	Auto Precharge Timing (Write Cycle)	. 37
10.11	Read Interrupted by Read (CL = 2, BL = 2, 4, 8)	.38
10.12	Burst Read Stop (BL = 8)	. 38
10.13	Read Interrupted by Write & BST (BL = 8)	.39
10.14	Read Interrupted by Precharge (BL = 8)	.39
10.15	Write Interrupted by Write (BL = 2, 4, 8)	.40
10.16	Write Interrupted by Read (CL = 2, BL = 8)	40
10.17	Write Interrupted by Read (CL = 2.5, BL = 4)	.41
10.18	Write Interrupted by Precharge (BL = 8)	.41
10.19	2 Bank Interleave Read Operation (CL = 2, BL = 2)	42
10.20	2 Bank Interleave Read Operation (CL = 2, BL = 4)	42
10.21	4 Bank Interleave Read Operation (CL = 2, BL = 2)	43
10.22	4 Bank Interleave Read Operation (CL = 2, BL = 4)	43
10.23	Auto Refresh Cycle	.44
10.24	Active Power Down Mode Entry and Exit Timing	.44
10.25	Precharged Power Down Mode Entry and Exit Timing	.44
10.26	Self Refresh Entry and Exit Timing	45
PACKA	GE DIMENSION	46
11.1	TSOP 66I – 400 mil	.46
REVISI	ON HISTORY	47



1. GENERAL DESCRIPTION

W942508CH is a CMOS Double Data Rate synchronous dynamic random access memory (DDR SDRAM), organized as 8,388,608 words \times 4 banks \times 8 bits. Using pipelined architecture and 0.13 μm process technology, W942508CH delivers a data bandwidth of up to 400M words per second (-5). To fully comply with the personal computer industrial standard, W942508CH is sorted into four speed grades: -5, -6, -7, -75 The -5 is compliant to the 200MHz/CL2.5 & CL3 specification, The -6 is compliant to the 166MHz/CL2.5 specification, the -7 is compliant to the 143MHz/CL2.5 or DDR266/CL2 specification, the -75 is compliant to the DDR266/CL2.5 specification.

All Inputs reference to the positive edge of CLK (except for DQ, DM, and CKE). The timing reference point for the differential clock is when the CLK and $\overline{\text{CLK}}$ signals cross during a transition. And Write and Read data are synschronized with the both edges of DQS (Data Strobe).

By having a programmable Mode Register, the system can change burst length, latency cycle, interleave or sequential burst to maximize its performance. W942508CH is ideal for main memory in high performance applications.

2. FEATURES

- $2.5V \pm 0.2V$ Power Supply for DDR266
- $2.5V \pm 0.2V$ Power Supply for DDR333
- 2.6V \pm 0.1V Power Supply for DDR400
- Up to 200 MHz Clock Frequency
- Double Data Rate architecture; two data transfers per clock cycle
- Differential clock inputs (CLK and CLK)
- DQS is edge-aligned with data for Read; center-aligned with data for Write
- CAS Latency: 2, 2.5 and 3
- Burst Length: 2, 4 and 8
- Auto Refresh and Self Refresh
- Precharged Power Down and Active Power Down
- Write Data Mask
- Write Latency = 1
- 8K Refresh cycles / 64 mS
- Interface: SSTL-2
- Packaged in TSOP II 66-pin, 400 x 875mil, 0.65mm pin pitch



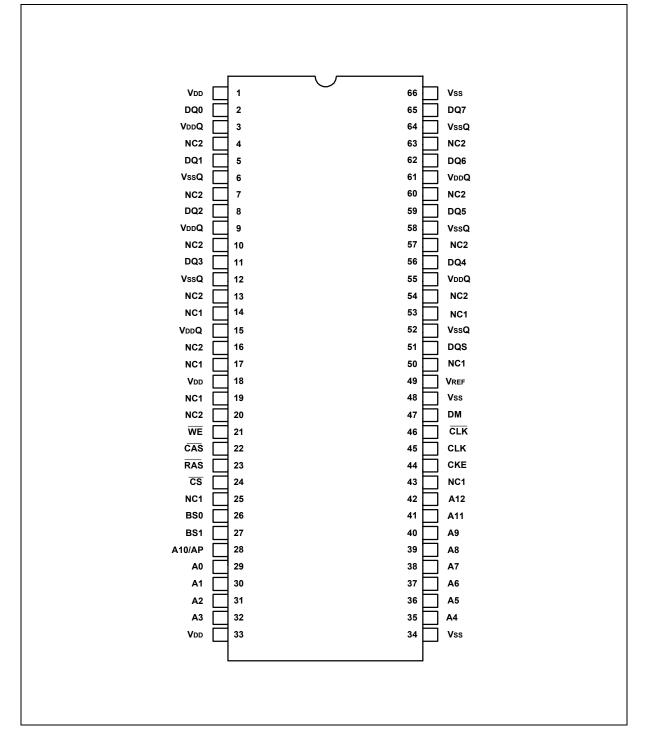
3. KEY PARAMETERS

SYMBOL	DESCRIPTION		MIN./MAX.	-7	-75
tск	Clock Cycle Time	CL = 2	Min.	7.5 nS	8 nS
ICK	Clock Cycle Time	CL = 2.5	Min.	7 nS	7.5 nS
tras	Active to Precharge Command Period		Min.	45 nS	45 nS
tRC	Active to Ref/Active Command Pe	eriod	Min.	65 nS	65 nS
IDD1	OPERATION CURRENT (SINGLE	E BANK)	Max.	120 mA	120 mA
IDD4	Burst Operation Current	irst Operation Current		165 mA	155 mA
IDD6	IDD6 SELF-REFRESH CURRENT		Max.	3 mA	3 mA

SYMBOL	DESCRIPTION		MIN./MAX.	-5	-6
tск	Clock Cycle Time	CL = 2.5	Min.	5 nS	6 nS
ICK		CL = 3	Min.	5 nS	6 nS
tras	Active to Precharge Command Period		Min.	40 nS	42 nS
tRC	Active to Ref/Active Command Pe	eriod	Min.	55 nS	60 nS
IDD1	OPERATION CURRENT (SINGLE	E BANK)	Max.	120 mA	120 mA
IDD4	Burst Operation Current		Max.	165 mA	165 mA
IDD6	SELF-REFRESH CURRENT		Max.	3 mA	3 mA



4. PIN CONFIGURATION



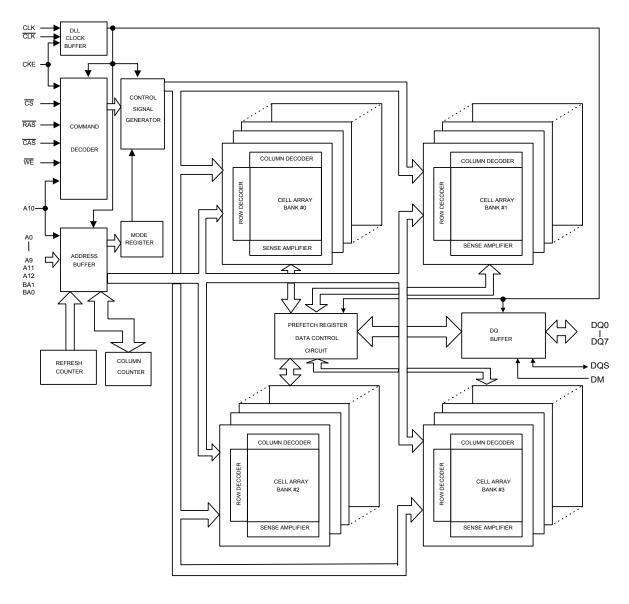


5. PIN DESCRIPTION

PIN NUMBER	PIN NAME	FUNCTION	DESCRIPTION
			Multiplexed pins for row and column address.
28 – 32, 35 – 42	A0 – A12	Address	Row address: A0 – A12.
00 12			Column address: A0 – A9. (A10 is used for Auto Precharge)
26, 27	BS0, BS1	Bank Select	Select bank to activate during row address latch time, or bank to read/write during column address latch time.
2, 5, 8, 11, 56, 59, 62, 65	DQ0 – DQ7	Data Input/ Output	The DQ0 – DQ7 input and output data are synchronized with both edges of DQS.
51	DQS	Data Strobe	DQS is Bi-directional signal. DQS is input signal during write operation and output signal during read operation. It is Edge- aligned with read data, Center-aligned with write data.
24	CS	Chip Select	Disable or enable the command decoder. When command decoder is disabled, new command is ignored and previous operation continues.
23, 22, 21	$\overline{RAS}, \ \overline{CAS}, \\ \overline{WE}$	Command Inputs	Command inputs (along with $\overline{\text{CS}}$) define the command being entered.
47	DM	Write Mask	When DM is asserted "high" in burst write, the input data is masked. DM is synchronized with both edges of DQS.
45, 46	CLK, CLK	Differential Clock Inputs	All address and control input signals are sampled on the crossing of the positive edge of CLK and negative edge of $\overline{\rm CLK}$.
44	CKE	Clock Enable	CKE controls the clock activation and deactivation. When CKE is low, Power Down mode, Suspend mode, or Self Refresh mode is entered.
49	VREF	Reference Voltage	VREF is reference voltage for inputs.
1, 18, 33	Vdd	Power (+2.5)	Power for logic circuit inside DDR SDRAM.
34, 48, 66	Vss	Ground	Ground for logic circuit inside DDR SDRAM.
3, 9, 15, 55, 61	Vddq	Power (+2.5V) for I/O Buffer	Separated power from VDD, used for output buffer, to improve noise.
6, 12, 52, 58, 64	Vssq	Ground for I/O Buffer	Separated ground from Vss, used for output buffer, to improve noise.
4, 7, 10, 13, 14, 16, 17, 19, 20, 25, 43, 50, 53, 54, 57, 60, 63	NC1, NC2	No Connection	No connection



6. BLOCK DIAGRAM



NOTE:

The cell array configuration is 8912 * 1024 * 8



7. ELECTRICAL CHARACTERISTICS

7.1 Absolute Maximum Ratings

PARAMETER	SYMBOL	RATING	UNIT
Input/Output Voltage	Vin, Vout	-0.3 - VDDQ +0.3	V
Power Supply Voltage	Vdd, Vddq	-0.3 - 3.6	V
Operating Temperature	Topr	0 – 70	°C
Storage Temperature	Tstg	-55 – 150	°C
Soldering Temperature (10s)	TSOLDER	260	°C
Power Dissipation	PD	1	W
Short Circuit Output Current	Ιουτ	50	mA

Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

7.2 Recommended DC Operating Conditions

SYMBOL	PARAMETER	MIN.	TYP.	MAX.	UNIT	NOTES
Vdd	Power Supply Voltage	2.3	2.5	2.7	V	2
Vddq	Power Supply Voltage (for I/O Buffer)	2.3	2.5	Vdd	V	2
VREF	Input reference Voltage	0.49 x Vddq	0.50 x VDDQ	0.51 x VDDQ	V	2, 3
Vtt	Termination Voltage (System)	VREF -0.04	VREF	VREF +0.04	V	2, 8
VIH (DC)	Input High Voltage (DC)	VREF +0.15	-	VDDQ +0.3	V	2
VIL (DC)	Input Low Voltage (DC)	-0.3	-	VREF -0.15	V	2
VICK (DC)	Differential Clock DC Input Voltage	-0.3	-	VDDQ +0.3	V	15
VID (DC)	Input Differential Voltage. CLK and CLK inputs (DC)	0.36	-	VDDQ +0.6	V	13, 15
VIH (AC)	Input High Voltage (AC)	VREF +0.31	-	-	V	2
VIL (AC)	Input Low Voltage (AC)	-	-	VREF -0.31	V	2
VID (AC)	Input Differential Voltage. CLK and CLK inputs (AC)	0.7	-	VDDQ +0.6	V	13, 15
VX (AC)	Differential AC input Cross Point Voltage	VDDQ/2 -0.2	-	VDDQ/2 +0.2	V	12, 15
VISO (AC)	Differential Clock AC Middle Point	VDDQ/2 -0.2	-	VDDQ/2 +0.2	V	14, 15

Notes: Undershoot Limit: VIL (min) = -0.9V with a pulse width \leq 5 nS

Overshoot Limit: VIH (max) = VDDQ +0.9V with a pulse width ≤ 5 nS

Vih(dc) and Vil(dc) are levels to maintain the current logic state.

VIH (AC) and VIL (AC) are levels to change to the new logic state.



7.3 Capacitance

SYMBOL	PARAMETER	MIN.	MAX.	DELTA (MAX.)	UNIT
CIN	Input Capacitance (except for CLK pins)	2.0	3.0	0.5	pF
CCLK	Input Capacitance (CLK pins)	2.0	3.0	0.25	pF
Cı/o	DQ, DQS, DM Capacitance	4.0	5.0	0.5	pF
CNC1	NC1 Pin Capacitance	-	1.5	-	pF
CNC2	NC2 Pin Capacitance	4.0	5.0	-	pF

(VDD = VDDQ = $2.5V \pm 0.2V$, f = 1 MHz, TA = 25 °C, VOUT (DC) = VDDQ/2, VOUT (Peak to Peak) = 0.2V)

Notes: These parameters are periodically sampled and not 100% tested.

The NC2 pins have additional capacitance for adjustment of the adjacent pin capacitance.

The NC2 pins have Power and Ground clamp.

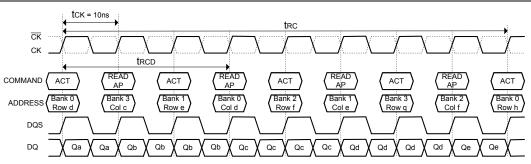
7.4 Leakage and Output Buffer Characteristics

SYMBOL	PARAMETER		MIN.	MAX.	UNITS	NOTES
lı(∟)	Input Leakage Current		-2	2		
п(с)	$(0V \le VIN \le VDDQ$, All other pins not uno	der test = 0V)	-2	2	μA	
IO(L)	Output Leakage Current		-5	5		
IO(L)	(Output disabled, $0V \leq VOUT \leq VDDQ$)		-5	5	μA	
Vон	Output High Voltage	Full Strength	V⊤⊤ +0.76	-	v v	
VON	(under AC test load condition)					
Vol	Output Low Voltage		_	Vtt		
VOL	(under AC test load condition)		_	-0.76		
IOH (DC)	Output Minimum Source DC Current		-15.2	-	mA	4, 6
IOL (DC)	Output Minimum Sink DC Current	Half Strength	15.2	-	mA	4, 6
IOH (DC)	Output Minimum Source DC Current		-10.4	-	mA	5
IOL (DC)	Output Minimum Sink DC Current		10.4	_	mA	5



7.5 DC Characteristics

SYM.	PARAMETER		MA	٩X.		UNIT	NOTES
5 T WI.			-6	-7	-75	UNIT	NOTES
IDD0	OPERATING CURRENT: One Bank Active-Precharge; tRc = tRc min; tck = tck min; DQ, DM and DQS inputs changing twice per clock cycle; Address and control inputs changing once per clock cycle	110	110	110	110		7
IDD1	OPERATING CURRENT: One Bank Active-Read-Precharge; Burst = 2; trc = trc min; CL = 2.5 ; tck = tck min; lout = 0 mA; Address and control inputs changing once per clock cycle.	120	120	120	120		7, 9
IDD2P	PRECHARGE-POWER-DOWN STANDBY CURRENT: All Banks Idle; Power down mode; CKE \leq VIL max; tck = tck min; Vin = VREF for DQ, DQS and DM	8	8	8	8		
IDD2F	IDLE FLOATING STANDBY CURRENT: $\overline{\text{CS}} \ge \text{V}_{\text{IH}} \text{ min}$; All Banks Idle; CKE \ge VIH min; Address and other control inputs changing once per clock cycle; Vin = Vref for DQ, DQS and DM	45	45	45	40		7
Idd2n	IDLE STANDBY CURRENT: $\overrightarrow{\text{CS}} \ge \text{V}_{\text{IH}}$ min; All Banks Idle; CKE \ge VIH min; tck = tck min; Address and other control inputs changing once per clock cycle; Vin \ge VIH min or Vin \le VIL max for DQ, DQS and DM	45	45	45	40		7
Idd2q	IDLE QUIET STANDBY CURRENT: $\overline{CS} \ge V_{IH}$ min; All Banks Idle; CKE $\ge V_{IH}$ min; tck = tck min; Address and other control inputs stable; Vin $\ge V_{REF}$ for DQ, DQS and DM	40	40	40	35	mA	7
IDD3P	ACTIVE POWER-DOWN STANDBY CURRENT: One Bank Active; Power down mode; CKE <u><</u> VI∟ max; tck = tck min	20	20	20	20		
Idd3n	ACTIVE STANDBY CURRENT: $\overrightarrow{\text{CS}} \ge \text{VIH min}$; $\text{CKE} \ge \text{VIH}$ min; One Bank Active-Precharge; $\text{trc} = \text{tras max}$; $\text{tck} = \text{tck min}$; DQ, DM and DQS inputs changing twice per clock cycle; Address and other control inputs changing once per clock cycle	70	70	70	65		7
Idd4r	OPERATING CURRENT: Burst = 2; Reads; Continuous burst; One Bank Active; Address and control inputs changing once per clock cycle; CL=2.5; tcκ = tcκ min; lout = 0mA	165	165	165	155		7, 9
Idd4w	OPERATING CURRENT: Burst = 2; Write; Continuous burst; One Bank Active; Address and control inputs changing once per clock cycle; CL = 2.5; tck = tck min; DQ, DM and DQS inputs changing twice per clock cycle	165	165	165	155		7
IDD5	AUTO REFRESH CURRENT: tRC = tRFC min	190	190	190	190		7
IDD6	SELF REFRESH CURRENT: CKE < 0.2V	9	9	9	9		
Idd7	RANDOM READ CURRENT: 4 Banks Active Read with activate every 20ns, Auto-Precharge Read every 20 nS; Burst = 4; tRcD = 3; lout = 0mA; DQ, DM and DQS inputs changing twice per clock cycle; Address changing once per clock cycle	270	270	270	270		



RANDOM READ CURRENT Timing (IDD7)



7.6 AC Characteristics and Operating Condition

(Notes: 10, 12)

SYM.	PARAMETER		-7		-75		UNITS	NOTES
			MIN.	MAX.	MIN.	MAX.	UNITS	NOTES
trc	Active to Ref/Active Command Period		65		65			
trfc	Ref to Ref/Active Command Period		75		75		1	
tras	Active to Precharge Command Period		45	100000	45	100000	nS	
trcd	Active to Read/Write Command Delay Time		20		20			
t RAP	Active to Read with Auto Precharge Enable		15		15			
tccD	Read/Write(a) to Read/Write(b) Command Pe	riod	1		1		tск	
tRP	Precharge to Active Command Period		20		20			
trrd	Active(a) to Active(b) Command Period		15		15			
twr	Write Recovery Time		15		15			
t DAL	Auto Precharge Write Recovery + Precharge	Time	30		30			
tor			7.5	15	8	15	nS	
tcĸ	CLK Cycle Time	= 2.5	7	15	7.5	15	110	
tac	Data Access Time from CLK, CLK		-0.75	0.75	-0.75	0.75		16
t DQSCK	DQS Output Access Time from CLK, CLK		-0.75	0.75	-0.75	0.75		10
tDQSQ	Data Strobe Edge to Output Data Edge Skew			0.5		0.5		
tсн	CLk High Level Width		0.45	0.55	0.45	0.55	tск	11
tc∟	CLK Low Level Width		0.45	0.55	0.45	0.55	ICK	11
tHP	CLK Half Period (minimum of actual tcH, tcL)		Min.		Min.			
ur			(tc∟,tcн)		(tc∟,tcн)		nS	
tqн	DQ Output Data Hold Time from DQS		Тнр -0.75		Тн⊵ -0.75			
tRPRE	DQS Read Preamble Time		0.9	1.1	0.9	1.1		
tRPST	DQS Read Postamble Time		0.4	0.6	0.4	0.6	tcĸ	11
tDS	DQ and DM Setup Time		0.5	0.0	0.5	0.0		
tDH	DQ and DM Hold Time		0.5		0.5		nS	
tDIPW	DQ and DM Input Pulse Width (for each input))	1.75		1.75			
tDQSH	DQS Input High Pulse Width	/	0.35		0.35			
tDQSL	DQS Input Low Pulse Width		0.35		0.35			
tDSS	DQS Falling Edge to CLK Setup Time		0.2		0.2		tcĸ	11
tDSH	DQS Falling Edge Hold Time from CLK		0.2		0.2			
twpres	Clock to DQS Write Preamble Set-up Time		0		0		nS	
twpre	DQS Write Preamble Time		0.25		0.25			
twpst	DQS Write Postamble Time		0.4		0.4			11
tDQSS	Write Command to First DQS Latching Transit	tion	0.75	1.25	0.75	1.25	tcĸ	
tDSSK	UDQS – LDQS Skew (x 16)		-0.25	0.25	-0.25	0.25		
tis	Input Setup Time		0.9		0.9			
tн	Input Hold Time		0.9		0.9			
tipw	Control & Address Input Pulse Width (for each	n input)	2.2	1	2.2		1	
tHZ	Data-out High-impedance Time from CLK, CLI	_	-0.75	0.75	-0.75	0.75	nS	
t∟z	Data-out Low-impedance Time from CLK, CLK	_	-0.75	0.75	-0.75	0.75	1	
t⊤(ss)	SSTL Input Transition		0.5	1.5	0.5	1.5		
twrr	Internal Write to Read Command Delay		1	-	1	-	tск	1
txsnr	Exit Self Refresh to non-Read Command		75		75		ns	
txsrd	Exit Self Refresh to Read Command		10		10		tcĸ	1
tREF	Refresh Time (8k)			64		64	mS	
tMRD	Mode Register Set Cycle Time		15		15		nS	

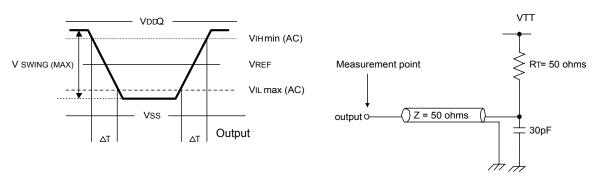


SYM.	DADAMETED		-	5	-	6	UNITS	NOTES
5 T IVI.	PARAMETER		MIN.	MAX.	MIN.	MAX.	UNITS	NULES
trc	Active to Ref/Active Command Period		55		60			
t RFC	Ref to Ref/Active Command Period		70		72			
tras	Active to Precharge Command Period		40	70000	42	100000	nS	
trcD	Active to Read/Write Command Delay Ti	me	15		18			
t RAP	Active to Read with Auto Precharge Enal		15		15			
tccD	Read/Write(a) to Read/Write(b) Commar		1		1		tск	
tRP	Precharge to Active Command Period		15		18			
trrd	Active(a) to Active(b) Command Period		10		12			
twr	Write Recovery Time		15		15			
t DAL	Auto Precharge Write Recovery + Precha	arge Time	30		30			
4		2.5	5	10	6	12	nS	
tcĸ	CLK Cycle Time	3	5	10	6	12	115	
tac	Data Access Time from CLK, CLK		-0.7	0.7	-0.7	0.7		16
t DQSCK	DQS Output Access Time from CLK, CL	-0.55	0.55	-0.6	0.6		10	
tDQSQ	Data Strobe Edge to Output Data Edge S	Skew		0.4		0.45	1	
tсн	CLk High Level Width	0.45	0.55	0.45	0.55	tск	11	
tc∟	CLK Low Level Width		0.45	0.55	0.45	0.55	ICK	11
tHP	CLK Half Daried (minimum of actual tou	min		Min,				
ιΗΡ	CLK Half Period (minimum of actual tch, tcl)		(tcl,tch)		(tcl,tch)		nS	
tqн	DQ Output Data Hold Time from DQS	DO DOS			tHP		113	
IQN			-0.5		-0.55			
t RPRE	DQS Read Preamble Time		0.9	1.1	0.9	1.1	tcĸ	11
t RPST	DQS Read Postamble Time	0.4	0.6	0.4	0.6	ton		
tDS	DQ and DM Setup Time		0.4		0.45			
tDH	DQ and DM Hold Time		0.4		0.45		nS	
t DIPW	DQ and DM Input Pulse Width (for each	input)	1.75		1.75			
t DQSH	DQS Input High Pulse Width		0.35		0.35			
t DQSL	DQS Input Low Pulse Width		0.35		0.35		tск	11
toss	DQS Falling Edge to CLK Setup Time		0.2		0.2		ton	
t DSH	DQS Falling Edge Hold Time from CLK		0.2		0.2			
twpres	Clock to DQS Write Preamble Set-up Tin	ne	0		0		nS	
twpre	DQS Write Preamble Time		0.25		0.25			
twpst	DQS Write Postamble Time		0.4	0.6	0.4	0.6	tск	11
tDQSS	Write Command to First DQS Latching T	ransition	0.72	1.28	0.75	1.25		
t DSSK	UDQS – LDQS Skew (x 16)		-0.25	0.25	-0.25	0.25		
tıs	Input Setup Time		0.6		0.75			
tн	Input Hold Time		0.6		0.75			
tipw	Control & Address Input Pulse Width (for each input)		2.2		2.2			
tнz	Data-out High-impedance Time from CLK, CLK			Max tac	-0.7	0.7	nS	
t∟z	Data-out Low-impedance Time from CLK	-0.7	0.7	-0.7	0.7			
t⊤(ss)	SSTL Input Transition	0.5	1.5	0.5	1.5			
twrr	Internal Write to Read Command Delay	2		2		tск		
txsnr	Exit Self Refresh to non-Read Command	Exit Self Refresh to non-Read Command					ns	
txsrd	Exit Self Refresh to Read Command		10		10		tск	
t REF	Refresh Time (8k)			64		64	mS	
tmrd	Mode Register Set Cycle Time		10		12		nS	



7.7 AC Test Conditions

PARAMETER	SYMBOL	VALUE	UNIT
Input High Voltage (AC)	Viн	VREF +0.31	V
Input Low Voltage (AC)	VIL	Vref -0.31	V
Input Reference Voltage	Vref	0.5 x VDDQ	V
Termination Voltage	Vtt	0.5 x Vddq	V
Input Signal Peak to Peak Swing	Vswing	1.0	V
Differential Clock Input Reference Voltage	Vr	V _× (AC)	V
Input Difference Voltage. CLK and \overline{CLK} Inputs (AC)	VID (AC)	1.5	V
Input Signal Minimum Slew Rate	SLEW	1.0	V/nS
Output Timing Measurement Reference Voltage	Votr	0.5 x VDDQ	V



SLEW = (VIHmin (AC) - VILmax (AC)) / ΔT

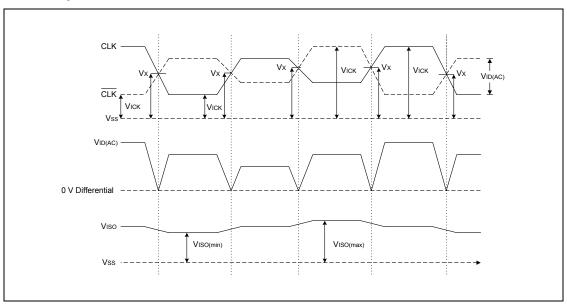


Notes:

- (1) Conditions outside the limits listed under "ABSOLUTE MAXIMUM RATINGS" may cause permanent damage to the device.
- (2) All voltages are referenced to Vss, Vssq.(2.6V±0.1V for DDR400)
- (3) Peak to peak AC noise on VREF may not exceed $\pm 2\%$ VREF(DC).
- (4) VOH = 1.95V, VOL = 0.35V
- (5) VOH = 1.9V, VOL = 0.4V
- (6) The values of IOH (DC) is based on VDDQ = 2.3V and VTT = 1.19V. The values of IOL (DC) is based on VDDQ = 2.3V and VTT = 1.11V.
- (7) These parameters depend on the cycle rate and these values are measured at a cycle rate with the minimum values of tck and tRc.

Field Field

- (8) VTT is not applied directly to the device. VTT is a system supply for signal termination resistors, is expected to be set equal to VREF and must track variations in the DC level of VREF.
- (9) These parameters depend on the output loading. Specified values are obtained with the output open.
- (10) Transition times are measured between VIH min.(AC) and VIL max.(AC).Transition (rise and fall) of input signals have a fixed slope.
- (11) IF the result of nominal calculation with regard to tcκ contains more than one decimal place, the result is rounded up to the nearest decimal place.
 (i.e., tboss = 0.75 × tcκ, Tck = 7.5 nS, 0.75 × 7.5 nS = 5.625 nS is rounded up to 5.6 nS.)
- (12) Vx is the differential clock cross point voltage where input timing measurement is referenced.
- (13) VID is magnitude of the difference between CLK input level and CLK input level.
- (14) VISO means {VICK(CLK)+VICK(CLK)}/2.
- (15) Refer to the figure below.



(16) tac and tDQSCK depend on the clock jitter. These timing are measured at stable clock.



8. OPERATION MODE

The following table shows the operation commands.

8.1 Simplified Truth Table

SYM.	COMMAND	DEVICE STATE	CKEN-1	CKEN	DM ⁽⁴⁾	BS0 BS1	A10	A12, A11, A9-A0	cs	RAS	CAS	WE
ACT	Bank Active	Idle ⁽³⁾	Н	Х	Х	V	V	V	L	L	Н	Н
PRE	Bank Precharge	Any ⁽³⁾	Н	Х	Х	V	L	х	L	L	Н	L
PREA	Precharge All	Any	н	Х	Х	Х	Н	х	L	L	Н	L
WRIT	Write	Active ⁽³⁾	н	Х	Х	V	L	V	L	Н	L	L
WRITA	Write with Auto Precharge	Active ⁽³⁾	н	x	х	V	н	V	L	Н	L	L
READ	Read	Active ⁽³⁾	Н	Х	Х	V	L	V	L	Н	L	Н
READA	Read with Auto Precharge	Active ⁽³⁾	н	х	х	V	н	V	L	Н	L	н
MRS	Mode Register Set	ldle	н	х	х	L, L	С	С	L	L	L	L
EMRS	Extended Mode Regiser Set	ldle	н	х	х	H, L	v	V	L	L	L	L
NOP	No Operation	Any	Н	Х	Х	Х	Х	х	L	н	Н	Н
BST	Burst Read Stop	Active	Н	Х	Х	Х	Х	х	L	Н	Н	L
DSL	Device Deselect	Any	Н	Х	Х	Х	Х	Х	Н	Х	Х	Х
AREF	Auto Refresh	Idle	Н	Н	Х	Х	Х	х	L	L	L	Н
SELF	Self Refresh Entry	Idle	Н	L	Х	Х	Х	х	L	L	L	Н
SELEX	Self Refresh Exit	Idle (Self	L	Н	х	x	x	х	Н	Х	Х	Х
OLLLA		Refresh)	–		~	~	^	~	L	Н	Н	Х
PD	Power Down	Idle/	н	L	х	x	x	х	Н	Х	Х	Х
10	Mode Entry	Active ⁽⁵⁾			~	~	~	~	L	Н	Н	Х
PDEX	Power Down	Any		н	х	x	x	x	Н	Х	Х	Х
FUEA	Mode Exit	(Power Down)	L		^	^	^	^	L	Н	Н	х
WDE	Data Write Enable	Active	Н	Х	L	Х	Х	х	Х	Х	Х	Х
WDD	Data Write Disable	Active	Н	х	Н	х	х	х	х	х	Х	х

Notes:

1. V = Valid X = Don't Care L = Low level H = High level

2. CKE_n signal is input level when commands are issued.

CKE_{n-1} signal is input level one clock cycle before the commands are issued.

- 3. These are state designated by the BS0, BS1 signals.
- 4. LDM, UDM (W942516CH)
- 5. Power Down Mode can not entry in the burst cycle.



8.2 Function Truth Table

(Note 1)

CURRENT STATE	CS	RAS	CAS	WE	ADDRESS	COMMAND	ACTION	NOTES
Idle	Н	х	Х	Х	Х	DSL	Nop	
	L	н	Н	Х	Х	NOP/BST	Nop	
	L	н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	3
	L	н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BS, RA	ACT	Row activating	
	L	L	Н	L	BS, A10	PRE/PREA	Nop	
	L	L	L	н	Х	AREF/SELF	Refresh or Self refresh	2
	L	L	L	L	Op-Code	MRS/EMRS	Mode register accessing	2
Row Active	Н	Х	Х	Х	Х	DSL	Nop	
	L	н	Н	Х	Х	NOP/BST	Nop	
	L	Н	L	Н	BS, CA, A10	READ/READA	Begin read: Determine AP	4
	L	н	L	L	BS, CA, A10	WRIT/WRITA	Begin write: Determine AP	4
	L	L	Н	н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	Precharge	5
	L	L	L	н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Read	Н	Х	Х	Х	Х	DSL	Continue burst to end	
	L	н	Н	Н	Х	NOP	Continue burst to end	
	L	н	Н	L	Х	BST	Burst stop	
	L	н	L	н	BS, CA, A10	READ/READA	Term burst, new read: Determine AP	6
	L	н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	Term burst, precharging	
	L	L	L	н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Write	Н	Х	Х	Х	Х	DSL	Continue burst to end	
	L	н	Н	н	Х	NOP	Continue burst to end	
	L	н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Н	BS, CA, A10	READ/READA	Term burst, start read: Determine AP	6, 7
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	Term burst, start read: Determine AP	6
	L	L	Н	н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	Term burst. precharging	8
	L	L	L	н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	



CURRENT STATE	cs	RAS	CAS	WE	ADDRESS	COMMAND	ACTION	NOTES
Read with	Н	Х	Х	Х	Х	DSL	Continue burst to end	
Auto Prechange	L	Н	Н	Η	Х	NOP	Continue burst to end	
Frechange	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	ILLEGAL	
	L	L	L	Н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Write with	Н	Х	х	Х	Х	DSL	Continue burst to end	
Auto	L	Н	Н	Н	х	NOP	Continue burst to end	
Precharge	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	ILLEGAL	3
	L	L	L	Н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Precharging	Н	Х	Х	Х	х	DSL	Nop-> Idle after tRP	
	L	Н	Н	Н	Х	NOP	Nop-> Idle after tRP	
	L	Н	Н	Г	Х	BST	ILLEGAL	
	L	Н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Η	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	Nop->Idle after tRP	
	L	L	L	Н	х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Row	Н	Х	Х	Х	х	DSL	Nop-> Row active after	
Activating	L	Н	Н	Н	х	NOP	Nop-> Row active after	
	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Η	BS, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	ILLEGAL	3
	L	L	L	Н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	

Function Truth Table, continued



CURRENT STATE	cs	RAS	CAS	WE	ADDRESS	COMMAND	ACTION	NOTES
Write	Н	Х	Х	Х	Х	DSL	Nop->Row active after twR	
Recovering	L	Н	Н	Н	Х	NOP	Nop->Row active after twR	
	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	ILLEGAL	3
	L	L	L	Н	х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Write	Н	Х	Х	Х	х	DSL	Nop->Enter precharge after twR	
Recovering with Auto	L	Н	Н	Н	х	NOP	Nop->Enter precharge after twR	
Precharge	L	Н	Η	L	Х	BST	ILLEGAL	
-	L	Н	L	Н	BS, CA, A10	READ/READA	ILLEGAL	3
	L	Н	L	L	BS, CA, A10	WRIT/WRITA	ILLEGAL	3
	L	L	Н	Н	BS, RA	ACT	ILLEGAL	3
	L	L	Н	L	BS, A10	PRE/PREA	ILLEGAL	3
	L	L	L	Н	Х	AREF/SELF	ILLEGAL	
	L	L	L	L	Op-Code	MRS/EMRS	ILLEGAL	
Refreshing	Н	Х	Х	Х	х	DSL	Nop->Idle after tRC	
	L	Н	Н	Н	Х	NOP	Nop->Idle after tRC	
	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	н	Х	READ/WRIT	ILLEGAL	
	L	L	Η	Х	Х	ACT/PRE/PREA	ILLEGAL	
	L	L	L	Х	Х	AREF/SELF/MRS/EM	ILLEGAL	
Mode	Н	Х	Х	х	х	DSL	Nop->Row after tmRD	
Register Accessing	L	Н	Н	Н	Х	NOP	Nop->Row after tmrD	
	L	Н	Н	L	Х	BST	ILLEGAL	
	L	Н	L	Х	Х	READ/WRIT	ILLEGAL	
	L	L	х	х	х	ACT/PRE/PREA/ARE F/SELF/MRS/EMRS	ILLEGAL	

Function Truth Table, continued

Notes:

1. All entries assume that CKE was active (High level) during the preceding clock cycle and the current clock cycle.

2. Illegal if any bank is not idle.

3. Illegal to bank in specified states; Function may be legal in the bank indicated by Bank Address (BS), depending on the state of that bank.

- 4. Illegal if tRCD is not satisfied.
- 5. Illegal if tRAS is not satisfied.
- 6. Must satisfy burst interrupt condition.
- 7. Must avoid bus contention, bus turn around, and/or satisfy write recovery requirements.
- 8. Must mask preceding data which don't satisfy twR

Remark: H = High level, L = Low level, X = High or Low level (Don't care), V = Valid data



CURRENT	CKE		CS	RAS	CAS	WE	ADDRESS	ACTION	NOTES
STATE	n-1	n	00	IXA5	CAU	VVC	ADDITEOU	Action	NOTED
H X X X X X X INVALID		INVALID							
	L	Н	Н	Х	Х	Х	Х	Exit Self Refresh->Idle after txsnR	
Self Refresh	L	Н	L	Н	Н	Х	Х	Exit Self Refresh->Idle after txsnR	
Sell Reliesh	L	Н	L	Н	L	Х	Х	ILLEGAL	
	L	Н	L	L	Х	Х	Х	ILLEGAL	
	L	L	Х	Х	Х	Х	Х	Maintain Self Refresh	
	Н	Х	Х	Х	Х	Х	Х	INVALID	
Power Down	L	Н	Х	Х	Х	Х	Х	Exit Power down->Idle after tis	
	L	L	Х	Х	Х	Х	Х	Maintain power down mode	
	Н	н	Х	Х	Х	Х	Х	Refer to Function Truth Table	
	Н	L	Н	Х	Х	Х	Х	Enter Power down	2
	Н	L	L	Н	Н	Х	Х	Enter Power down	2
All Banks Idle	Н	L	L	L	L	Н	Х	Self Refresh	1
	Н	L	L	Н	L	Х	Х	ILLEGAL	
	Н	L	L	L	Х	Х	Х	ILLEGAL	
	L	Х	Х	Х	Х	Х	Х	Power down	2
	Н	Н	Х	Х	Х	Х	Х	Refer to Function Truth Table	
	н	L	Н	Х	Х	Х	Х	Enter Power down	2
	Н	L	L	Н	Н	Х	Х	Enter Power down	2
Row Active	н	L	L	L	L	Н	Х	ILLEGAL	
	н	L	L	Н	L	Х	Х	ILLEGAL	
	н	L	L	L	Х	Х	Х	ILLEGAL	
	L	Х	Х	Х	Х	Х	Х	Power down	
Any State Other Than Listed Above	н	Н	х	х	х	x	Х	Refer to Function Truth Table	

8.3 Function Truth Table for CKE

Notes:

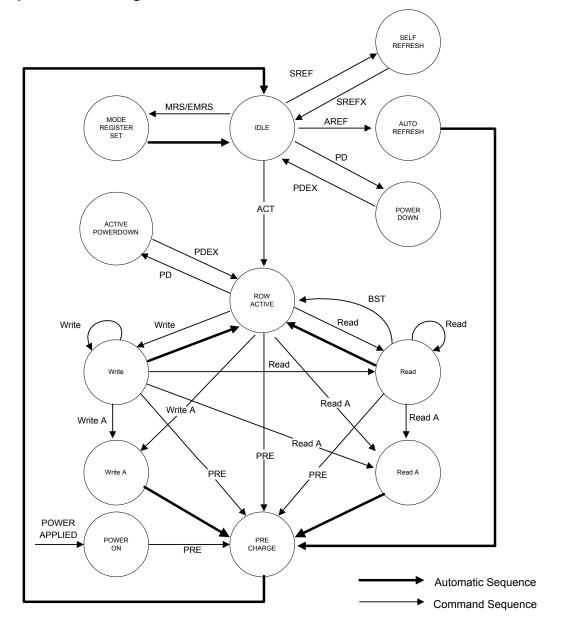
1. Self refresh can enter only from the all banks idle state.

2. Power down can enter only from bank idle or row active state.

Remark: H = High level, L = Low level, X = High or Low level (Don't care), V = Valid data



8.4 Simplified State Diagram





9. FUNCTIONAL DESCRIPTION

9.1 Power Up Sequence

- (1) Apply power and attempt to CKE at a low state ($\leq 0.2V$), all other inputs may be undefined 1) Apply VDD before or at the same time as VDDQ.
 - 2) Apply VDDQ before or at the same time as VTT and VREF.
- (2) Start Clock and maintain stable condition for 200 μ S (min.).
- (3) After stable power and clock, apply NOP and take CKE high.
- (4) Issue EMRS (Extended Mode Register Set) to enable DLL and establish Output Driver Type.
- (5) Issue MRS (Mode Register Set) to reset DLL and set device to idle with bit A8. (an additional 200 cycles(min) of clock are required for DLL Lock)
- (6) Issue precharge command for all banks of the device.
- (7) Issue two or more Auto Refresh commands.
- (8) Issue MRS-Initialize device operation.(If device operation mode is set at sequence 5, sequence 8 can be skipped.)

9.2 Command Function

1. Bank Activate Command

 $(\overline{RAS} = "L", \overline{CAS} = "H", \overline{WE} = "H", BS0, BS1 = Bank, A0 to A12 = Row Address)$

The Bank Activate command activates the bank designated by the BS (Bank address) signal. Row addresses are latched on A0 to A12 when this command is issued and the cell data is read out of the sense amplifiers. The maximum time that each bank can be held in the active state is specified as tRAS (max). After this command is issued, Read or Write operation can be executed.

2. Bank Precharge Command

 $(\overline{RAS} = "L", \overline{CAS} = "H", \overline{WE} = "L", BS0, BS1 = Bank, A10 = "L", A0 to A9, A11, A12 = Don't care)$

The Bank Precharge command percharges the bank designated by BS. The precharged bank is switched from the active state to the idle state.

3. Precharge All Command

 $(\overline{RAS} = "L", \overline{CAS} = "H", \overline{WE} = "L", BS0, BS1 = Don't care, A10 = "H", A0 to A9, A11, A12 = Don't care)$

The Precharge All command precharges all banks simultaneously. Then all banks are switched to the idle state.

4. Write Command

 $(\overline{RAS} = "H", \overline{CAS} = "L", \overline{WE} = "L", BS0, BS1 = Bank, A10 = "L", A0 to A9, A11 = Column Address)$

Electronics Corp.

The write command performs a Write operation to the bank designated by BS. The write data are latched at both edges of DQS. The length of the write data (Burst Length) and column access sequence (Addressing Mode) must be in the Mode Register at power-up prior to the Write operation.

5. Write with Auto Precharge Command

 $(\overline{RAS} = "H", \overline{CAS} = "L", \overline{WE} = "L", BS0, BS1 = Bank, A10= "H", A0 to A9, A11 = Column Address)$

The Write with Auto Precharge command performs the Precharge operation automatically after the Write operation. This command must not be interrupted by any other commands.

6. Read Command

 $(\overline{RAS} = "H", \overline{CAS} = "L", \overline{WE} = "H", BS0, BS1 = Bank, A10 = "L", A0 to A9, A11 = Column Address)$

The Read command performs a Read operation to the bank designated by BS. The read data are synchronized with both edges of DQS. The length of read data (Burst Length), Addressing Mode and \overline{CAS} Latency (access time from \overline{CAS} command in a clock cycle) must be programmed in the Mode Register at power-up prior to the Read operation.

7. Read with Auto Precharge Command

 $(\overline{RAS} = "H", \overline{CAS} = "L", \overline{WE} = "H", BS0, BS1 = Bank, A10 = "H", A0 to A9, A11 = Column Address)$

The Read with Auto precharge command automatically performs the Precharge operation after the Read operation.

1) READA \geq tRAS (min) - (BL/2) x tCK

Internal precharge operation begins after BL/2 cycle from Read with Auto Precharge command.

2) $tRCD(min) \leq READA < tRAS(min) - (BL/2) x tCK$

Data can be read with shortest latency, but the internal Precharge operation does not begin until after tRAS (min) has completed.

This command must not be interrupted by any other command.

8. Mode Register Set Command

```
(\overline{RAS} = "L", \overline{CAS} = "L", \overline{WE} = "L", BS0 = "L", BS1 = "L", A0 to A12 = Register Data)
```

The Mode Register Set command programs the values of \overline{CAS} latency, Addressing Mode, Burst Length and DLL reset in the Mode Register. The default values in the Mode Register after power-up are undefined, therefore this command must be issued during the power-up sequence. Also, this command can be issued while all banks are in the idle state. Refer to the table for specific codes.

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9. Extended Mode Register Set Command

 $(\overline{RAS} = "L", \overline{CAS} = "L", \overline{WE} = "L", BS0 = "H", BS1 = "L", A0 to A12 = Register data)$

The Extended Mode Register Set command can be implemented as needed for function extensions to the standard (SDR-SDRAM). Currently the only available mode in EMRS is DLL enable/disable, decoded by A0. The default value of the extended mode register is not defined; therefore this command must be issued during the power-up sequence for enabling DLL. Refer to the table for specific codes.

10. No-Operation Command

 $(\overline{RAS} = "H", \overline{CAS} = "H", \overline{WE} = "H")$

The No-Operation command simply performs no operation (same command as Device Deselect).

11. Burst Read Stop Command

 $(\overline{RAS} = "H", \overline{CAS} = "H", \overline{WE} = "L")$

The Burst stop command is used to stop the burst operation. This command is only valid during a Burst Read operation.

12. Device Deselect Command

 $(\overline{CS} = "H")$

The Device Deselect command disables the command decoder so that the \overline{RAS} , \overline{CAS} , \overline{WE} and Address inputs are ignored. This command is similar to the No-Operation command.

13. Auto Refresh Command

 $(\overline{RAS} = "L", \overline{CAS} = "L", \overline{WE} = "H", CKE = "L", BS0, BS1, A0 to A12 = Don't care)$

The Auto Refresh command is used to refresh the row address provided by the internal refresh counter. The Refresh operation must be performed 8192 times within 64ms. The next command can be issued after tREF from the end of the Auto Refresh command. When the Auto Refresh command is used, all banks must be in the idle state.

14. Self Refresh Entry Command

 $(\overline{RAS} = "L", \overline{CAS} = "L", \overline{WE} = "H", CKE = "L", BS0, BS1, A0 to A12 = don't care)$

The Self Refresh Entry command is used to enter Self Refresh mode. While the device is in Self Refresh mode, all input and output buffer (except the CKE buffer) are disabled and the Refresh operation is automatically performed. Self Refresh mode is exited by taking CKE "high" (the Self Refresh Exit command). During self refresh, DLLI is disable.

15. Self Refresh Exit Command

(CKE = "H", \overline{CS} = "H" or CKE = "H", \overline{RAS} = "H", \overline{CAS} = "H")

This command is used to exit from Self Refresh mode. Any subsequent commands can be issued after tXSNR (tXSRD for Read Command) from the end of this command.



16. Data Write Enable /Disable Command

(DM = "L/H" or LDM, UDM = "L/H")

During a Write cycle, the DM or LDM, UDM signal functions as Data Mask and can control every word of the input data. The LDM signal controls DQ0 to DQ7 and UDM signal controls DQ8 to DQ15.

9.3 Read Operation

Issuing the Bank Activate command to the idle bank puts it into the active state. When the Read command is issued after tRCD from the Bank Activate command, the data is read out sequentially, synchronized with both edges of DQS (Burst Read operation). The initial read data becomes available after \overline{CAS} latency from the issuing of the Read command. The \overline{CAS} latency must be set in the Mode Register at power-up.

When the Precharge Operation is performed on a bank during a Burst Read and operation, the Burst operation is terminated.

When the Read with Auto Precharge command is issued, the Precharge operation is performed automatically after the Read cycle, then the bank is switched to the idle state. This command cannot be interrupted by any other commands. Refer to the diagrams for Read operation.

9.4 Write Operation

Issuing the Write command after tRCD from the bank activate command. The input data is latched sequentially, synchronizing with both edges(rising &falling) of DQS after the Write command (Burst write operation). The burst length of the Write data (Burst Length) and Addressing Mode must be set in the Mode Register at power-up.

When the Precharge operation is performed in a bank during a Burst Write operation, the Burst operation is terminated.

When the Write with Auto Precharge command is issued, the Precharge operation is performed automatically after the Write cycle, then the bank is switched to the idle state, The Write with Auto Precharge command cannot be interrupted by any other command for the entire burst data duration.

Refer to the diagrams for Write operation.

9.5 Precharge

There are two Commands, which perform the precharge operation (Bank Precharge and Precharge All). When the Bank Precharge command is issued to the active bank, the bank is precharged and then switched to the idle state. The Bank Precharge command can precharge one bank independently of the other bank and hold the unprecharged bank in the active state. The maximum time each bank can be held in the active state is specified as tRAS (max). Therefore, each bank must be precharged within tRAS(max) from the bank activate command.

The Precharge All command can be used to precharge all banks simultaneously. Even if banks are not in the active state, the Precharge All command can still be issued. In this case, the Precharge operation is performed only for the active bank and the precharge bank is then switched to the idle state.

Electronics Corp.

9.6 Burst Termination

When the Precharge command is used for a bank in a Burst cycle, the Burst operation is terminated. When Burst Read cycle is interrupted by the Precharge command, read operation is disabled after clock cycle of (\overline{CAS} latency) from the Precharge command. When the Burst Write cycle is interrupted by the Precharge command . When the Burst Write cycle is interrupted by the Precharge command . the input circuit is reset at the same clock cycle at which the precharge command is issued. In this case, the DM signal must be asserted "high": during twn to prevent writing the invalided data to the cell array.

When the Burst Read Stop command is issued for the bank in a Burst Read cycle, the Burst Read operation is terminated. The Burst read Stop command is not supported during a write burst operation. Refer to the diagrams for Burst termination.

9.7 Refresh Operation

Two types of Refresh operation can be performed on the device: Auto Refresh and Self Refresh. By repeating the Auto Refresh cycle, each bank in turn refreshed automatically. The Refresh operation must be performed 8192 times(rows) within 64 mS. The period between the Auto Refresh command and the next command is specified by tRFC.

Self Refresh mode enter issuing the Self Refresh command (CKE asserted "low"). while all banks are in the idle state. The device is in Self Refresh mode for as long as cke held "low". In the case of 8192 burst Auto Refresh commands, 8192 burst Auto Refresh commands must be performed within 7.8 μ S before entering and after exiting the Self Refresh mode. In the case of distributed Auto Refresh commands, distributed auto refresh commands must be issued every 7.8 μ S and the last distributed Auto Refresh mode. After exiting from the Self Refresh mode, the refresh operation must be performed within 7.8 μ S. In Self Refresh mode, all input/output buffers are disable, resulting in lower power dissipation (except CKE buffer). Refer to the diagrams for Refresh operation.

9.8 Power Down Mode

Two types of Power Down Mode can be performed on the device: Active Standby Power Down Mode and Precharge Standby Power Down Mode.

When the device enters the Power Down Mode, all input/output buffers and DLL are disabled resulting in low power dissipation (except CKE buffer).

Power Down Mode enter asserting CKE "low" while the device is not running a burst cycle. Taking CKE: "high" can exit this mode. When CKE goes high, a No operation command must be input at next CLK rising edge. Refer to the diagrams for Power Down Mode.

9.9 Mode Register Operation

The mode register is programmed by the Mode Register Set command (MRS/EMRS) when all banks are in the idle state. The data to be set in the Mode Register is transferred using the A0 to A12 and BS0, BS1 address inputs.

The Mode Register designates the operation mode for the read or write cycle. The register is divided into five filed: (1) Burst Length field to set the length of burst data (2) Addressing Mode selected bit to designate the column access sequence in a Burst cycle (3) \overline{CAS} Latency field to set the assess time in clock cycle (4) DLL reset field to reset the dll (5) Regular/Extended Mode Register filed to select a



type of MRS (Regular/Extended MRS). EMRS cycle can be implemented the extended function (DLL enable/Disable mode)

The initial value of the Mode Register (including EMRS) after power up is undefined; therefore the Mode Register Set command must be issued before power operation.

(1) Burst Length field (A2 to A0)

This field specifies the data length for column access using the A2 to A0 pins and sets the Burst Length to be 2, 4, and 8 words.

A2	A1	A0	BURST LENGTH
0	0	0	Reserved
0	0	1	2 words
0	1	0	4 words
0	1	1	8 words
1	х	х	Reserved

(2) Addressing Mode Select (A3)

The Addressing Mode can be one of two modes; Interleave mode or Sequential Mode, When the A3 bit is "0", Sequential mode is selected. When the A3 bit is "1", Interleave mode is selected. Both addressing Mode support burst length 2, 4, and 8 words.

A3 ADDRESSING MODE	
0	Sequential
0	Interleave



• Address Sequence of Sequential Mode

A column access is performed by incrementing the column address input to the device. The address is varied by the Burst Length as the following.

DATA	ACCESS ADDRESS	BURST LENGTH
Data 0	n	2 words (address bits is A0)
Data 1	n + 1	not carried from A0 to A1
Data 2	n + 2	4 words (address bit A0, A1)
Data 3	n + 3	Not carried from A1 to A2
Data 4	n + 4	
Data 5	n + 5	8 words (address bits A2, A1 and A0)
Data 6	n + 6	Not carried from A2 to A3
Data 7	n + 7	γ

Addressing Sequence of Sequential Mode

• Addressing Sequence of Interleave Mode

A Column access is started from the inputted column address and is performed by interleaving the address bits in the sequence shown as the following.

DATA	ACCESS ADDRESS	BURST LENGTH
Data 0	A8 A7 A6 A5 A4 A3 A2 A1 A0	2 words
Data 1	A8 A7 A6 A5 A4 A3 A2 A1 A0	
Data 2	A8 A7 A6 A5 A4 A3 A2 A1 A0	4 words
Data 3	A8 A7 A6 A5 A4 A3 A2 A1 A0	
Data 4	A8 A7 A6 A5 A4 A3 A2 A1 A0	8 words
Data 5	A8 A7 A6 A5 A4 A3 A2 A1 A0	
Data 6	A8 A7 A6 A5 A4 A3 A2 A1 A0	
Data 7	A8 A7 A6 A5 A4 A3 A2 A1 A0	γ

9.9.1.1	Address Sequence for Interleave Mode
---------	--------------------------------------



(3) \overline{CAS} Latency field (A6 to A4)

This field specifies the number of clock cycles from the assertion of the Read command to the first data read. The minimum values of \overline{CAS} Latency depends on the frequency of CLK.

A6	A5	A 4	CAS LATENCY
0	0	0	Reserved
0	0	1	Reserved
0	1	0	2
0	1	1	3
1	0	0	Reserved
1	0	1	Reserved
1	1	0	2.5
1	1	1	Reserved

(4) DLL Reset bit (A8)

This bit is used to reset DLL. When the A8 bit is "1", DLL is reset.

- (5) Mode Register /Extended Mode register change bits (BS0, BS1)
 - These bits are used to select MRS/EMRS.

BS1	BS0	A12-A0	
0	0	Regular MRS Cycle	
0	1	Extended MRS Cycle	
1	х	Reserved	

- (6) Extended Mode Register field
 - 1) DLL Switch field (A0)

This bit is used to select DLL enable or disable

A0	DLL
0	Enable
1	Disable

2) Output Driver Size Control field (A1)

This bit is used to select Output Driver Size, both Full strength and Half strength are based on JEDEC standard.

A1	OUTPUT DRIVER	
0	Full Strength	
1	Half Strength	

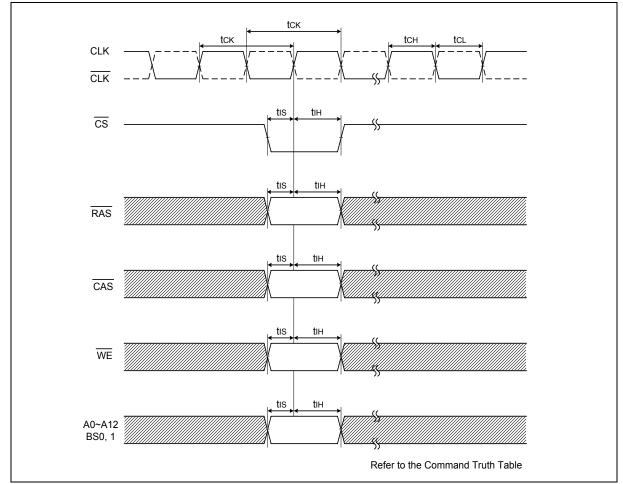
(7) Reserved field

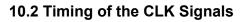
- Test mode entry bit (A7)
 This bit is used to enter Test mode and must be set to "0" for normal operation.
- Reserved bits (A9, A10, A11, A12)
 These bits are reserved for future operations. They must be set to "0" for normal operation.

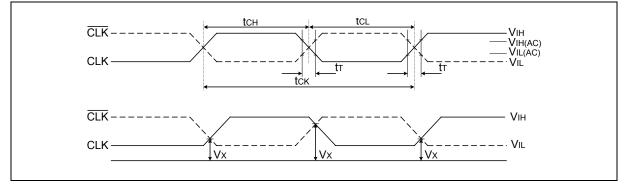


10. TIMING WAVEFORMS

10.1 Command Input Timing





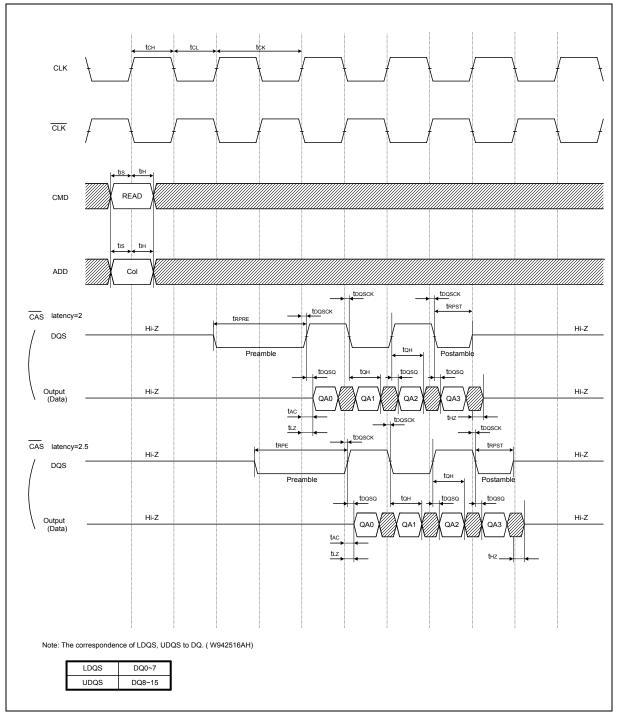


Publication Release Date: May 21, 2003 Revision A3



Timing Waveforms, continued

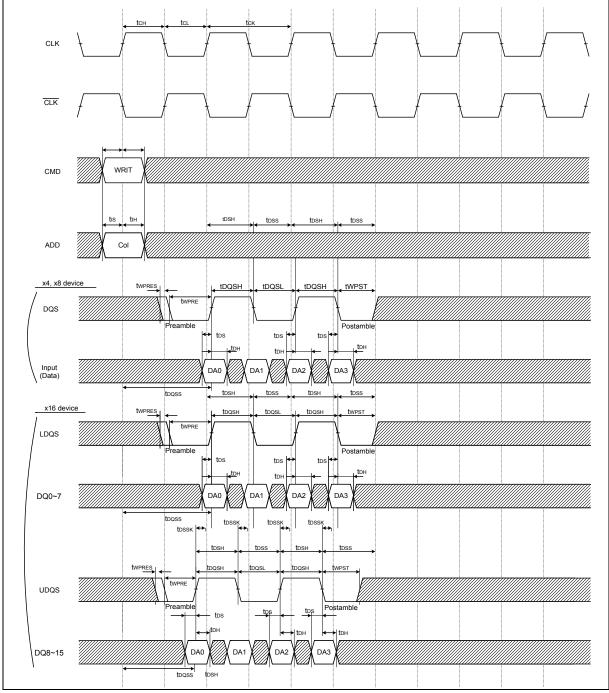
10.3 Read Timing (Burst Length = 4)





Timing Waveforms, continued

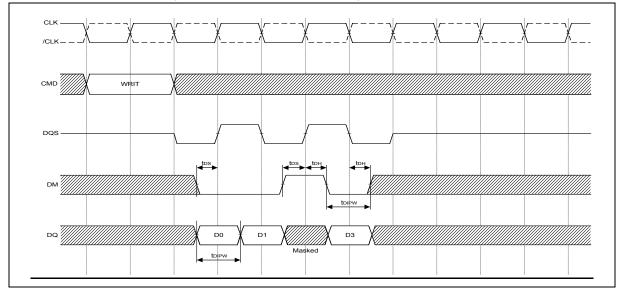
10.4 Write Timing (Burst Length = 4)



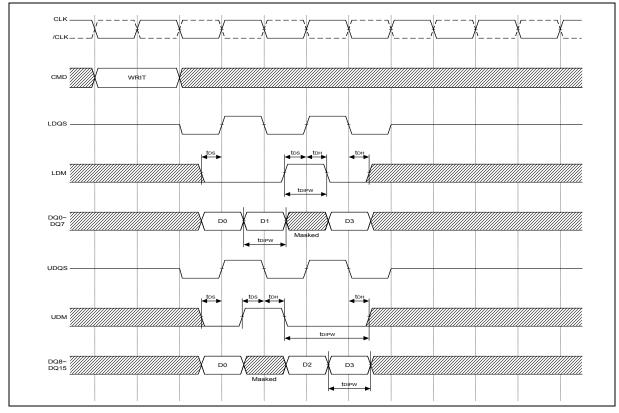
Note: x16 has 2DQS's (UDQS for uper byte and LDQS for lower byte). Even if one of the 2 bytes is not used, both UDQS and LDQS must be toggled.



10.5 DM, DATA MASK (W942508CH/W942504CH)



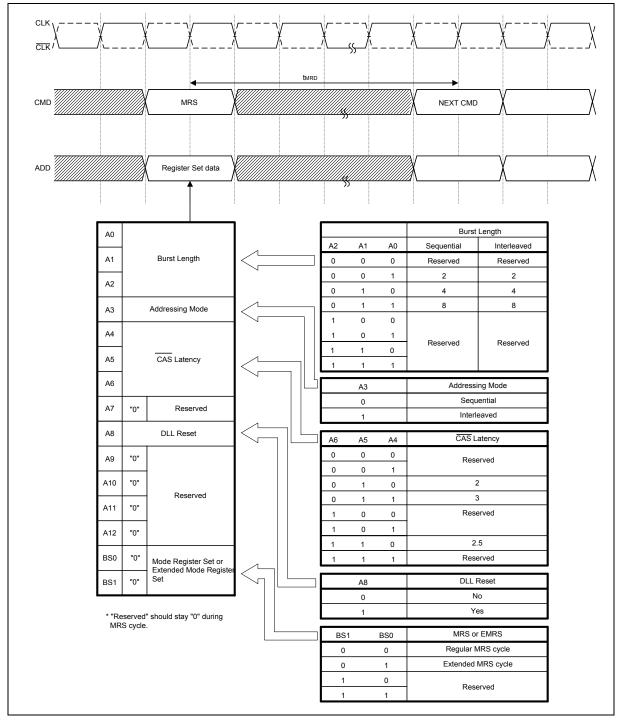
10.6 DM, DATA MASK (W942516CH)





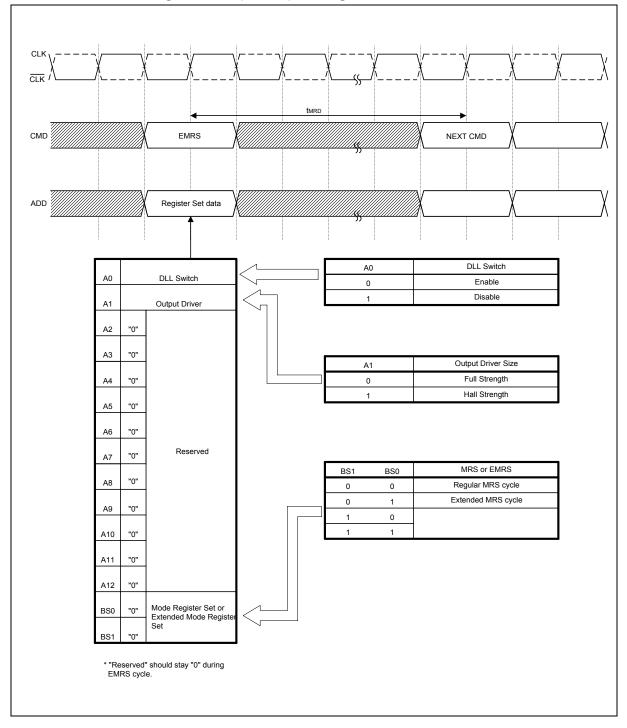
Timing Waveforms, continued

10.7 Mode Register Set (MRS) Timing





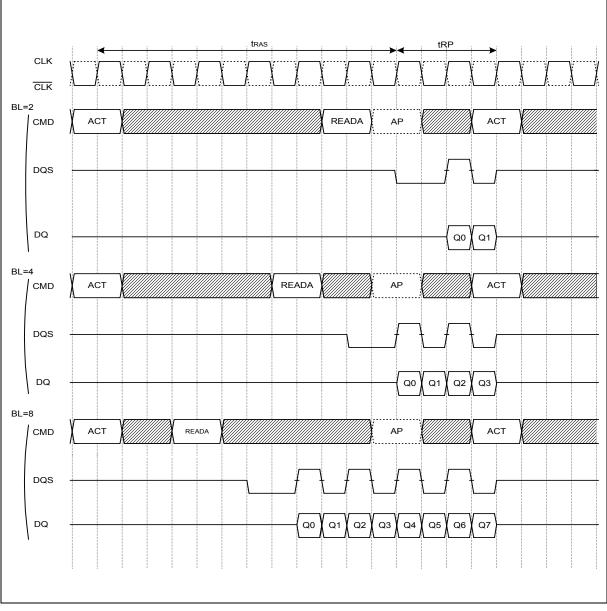
10.8 Extend Mode Register Set (EMRS) Timing





10.9 Auto Precharge Timing (Read Cycle, CL = 2)

1) tRCD (READA) \ge tRAS (min) – (BL/2) \times tCK



Notes: CL2 shown; same command operation timing with CL = 2.5

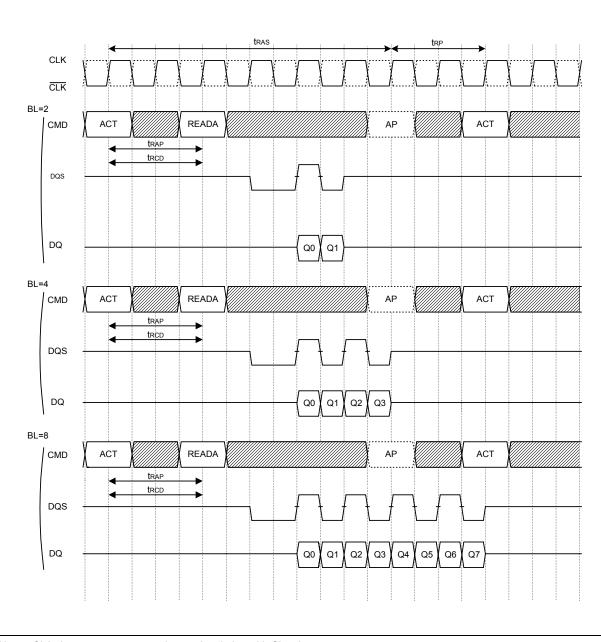
In this case , the internal precharge operation begin after BL/2 cycle from READA command.

(AP) represents the start of internal precharging .

The Read with Auto precharge command cannot be interrupted by any other command.



2) tRCD/RAP(min) \leq tRCD (READA) < tRAS (min) – (BL/2) \times tCK



Notes: CL2 shown; same command operation timing with CL = 2.5

In this case , the internal precharge operation does not begin until after tRAS (min) has command.

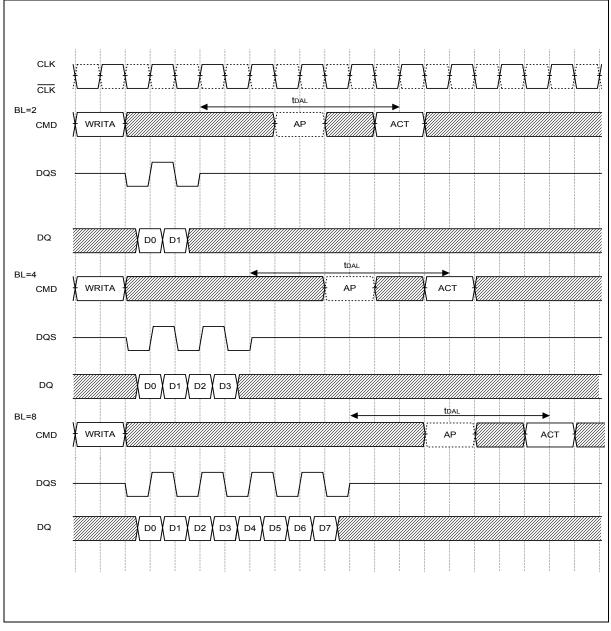
AP

represents the start of internal precharging .

The Read with Auto Precharge command cannot be interrupted by any other command.



10.10 Auto Precharge Timing (Write Cycle)



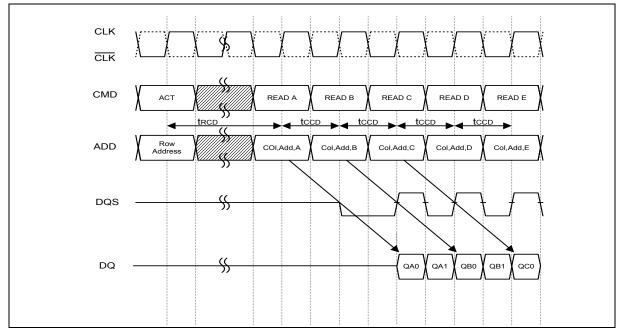
The Write with Auto Precharge command cannot be interrupted by any other command.

represents the start of internal precharging .

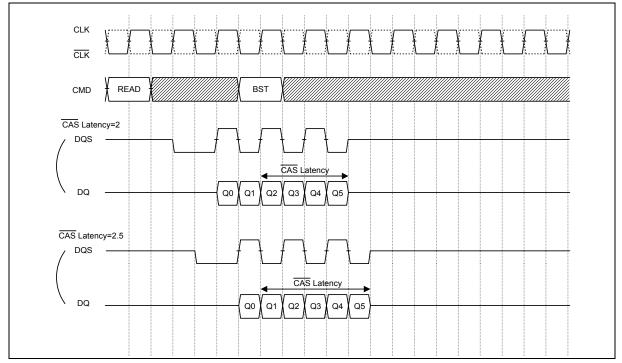
AP



10.11 Read Interrupted by Read (CL = 2, BL = 2, 4, 8)

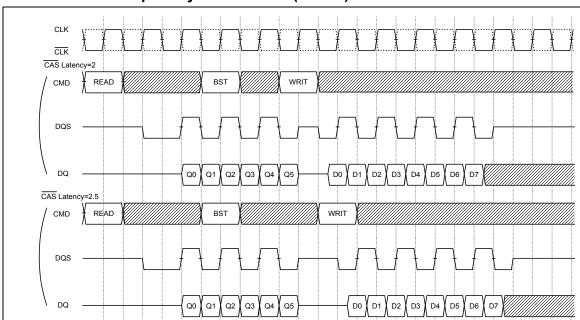


10.12 Burst Read Stop (BL = 8)



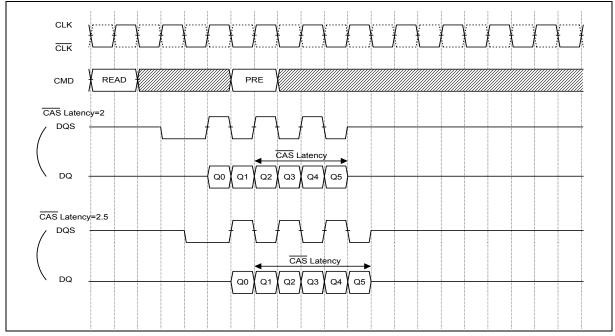


Timing Waveforms, continued



10.13 Read Interrupted by Write & BST (BL = 8)

Burst Read cycle must be terminated by BST Command to avoid I/O conflict.

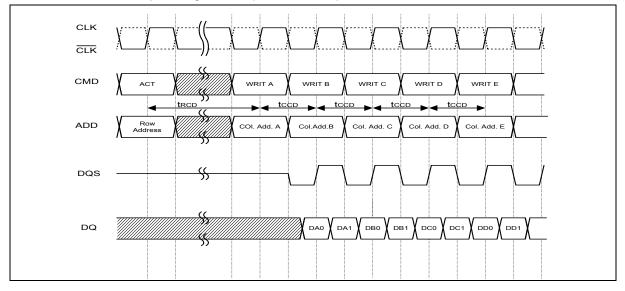


10.14 Read Interrupted by Precharge (BL = 8)

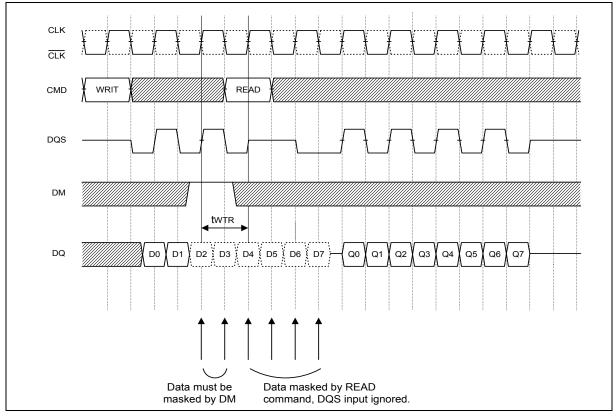


Timing Waveforms, continued

10.15 Write Interrupted by Write (BL = 2, 4, 8)

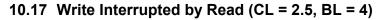


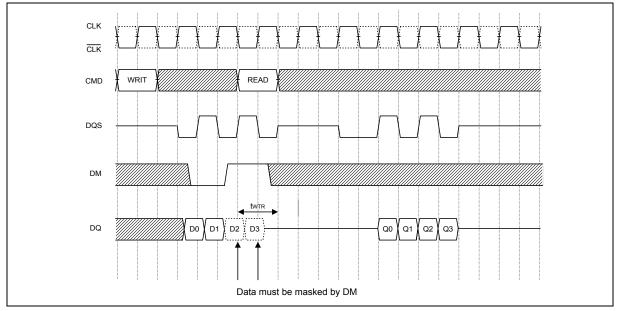
10.16 Write Interrupted by Read (CL = 2, BL = 8)



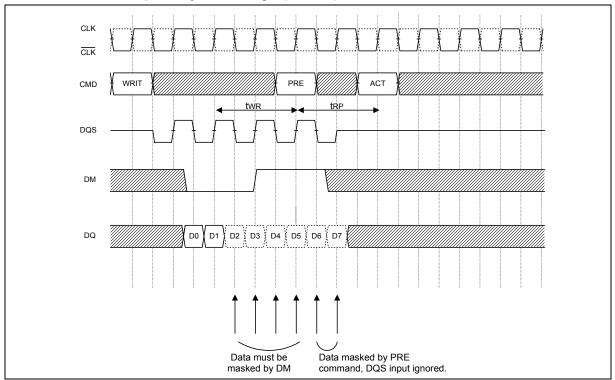


Timing Waveforms, continued





10.18 Write Interrupted by Precharge (BL = 8)

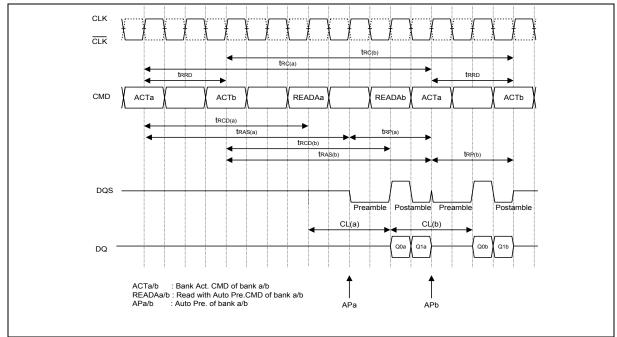




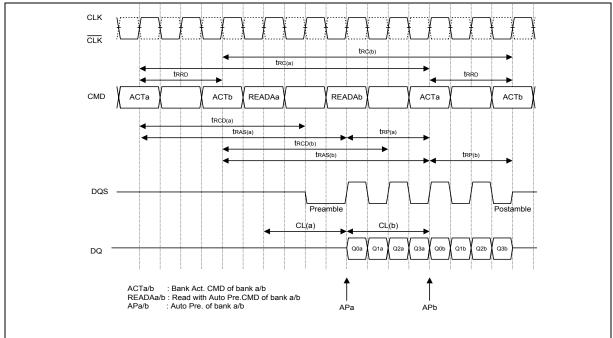
Timing Waveforms, continued

10.19 2 Bank Interleave Read Operation (CL = 2, BL = 2)

*tCK = 100 MHz

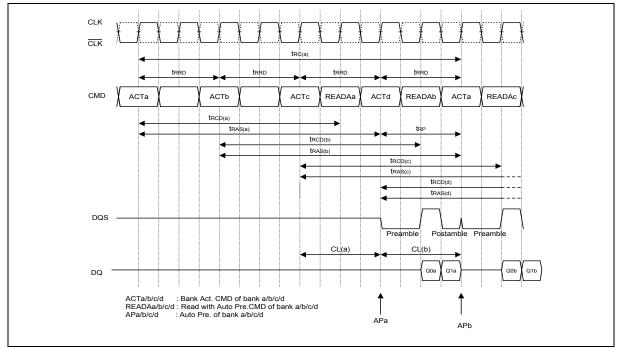


10.20 2 Bank Interleave Read Operation (CL = 2, BL = 4)

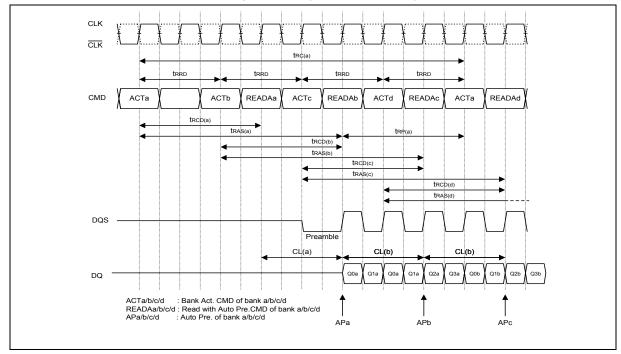




10.21 4 Bank Interleave Read Operation (CL = 2, BL = 2)

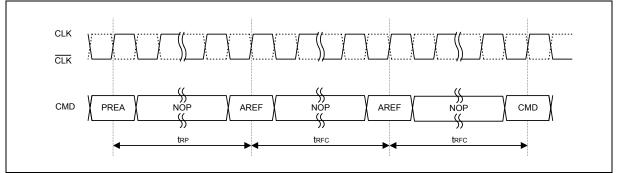


10.22 4 Bank Interleave Read Operation (CL = 2, BL = 4)



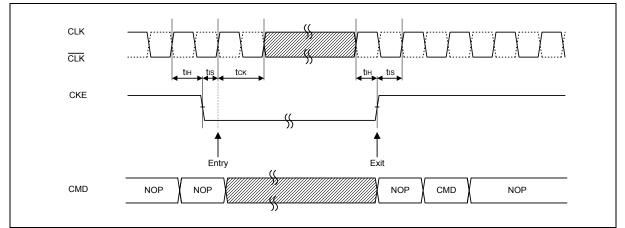


10.23 Auto Refresh Cycle

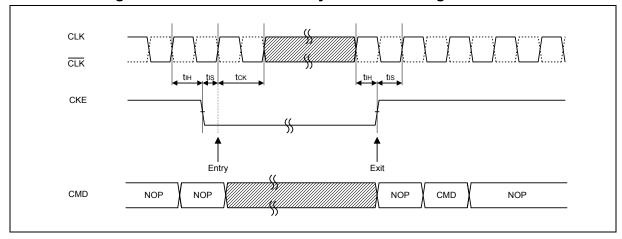


CKE has to be kept "High" level for Auto-Refresh cycle.

10.24 Active Power Down Mode Entry and Exit Timing

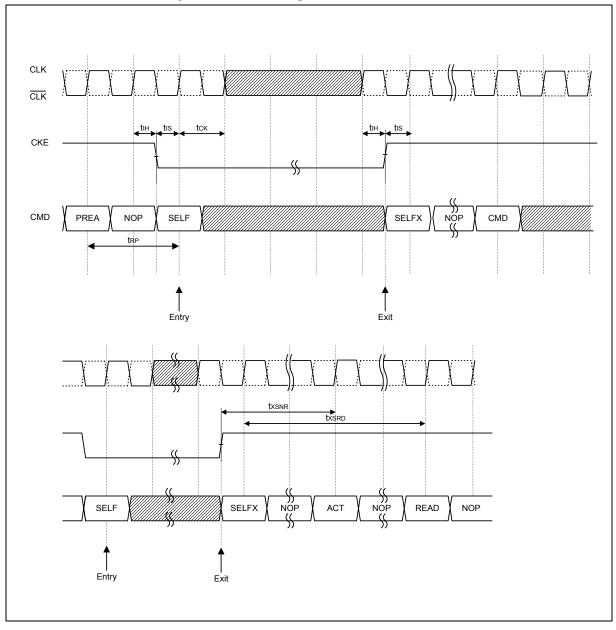


10.25 Precharged Power Down Mode Entry and Exit Timing





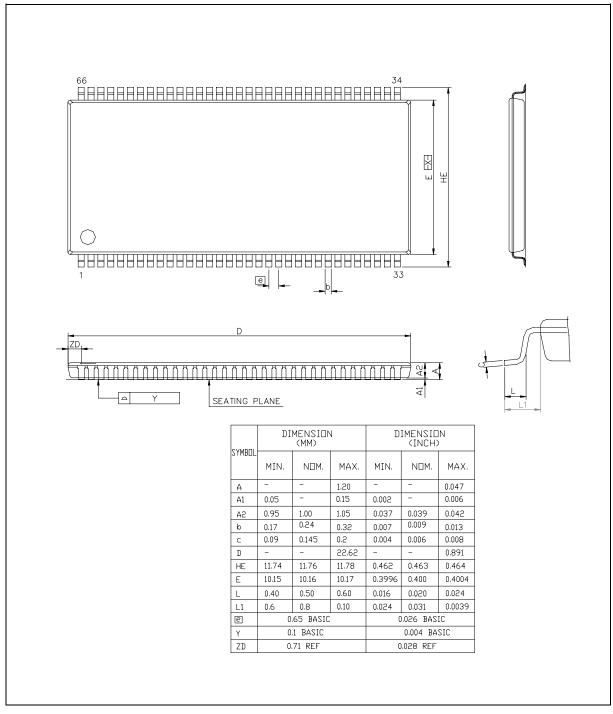
10.26 Self Refresh Entry and Exit Timing





11. PACKAGE DIMENSION

11.1 TSOP 66I – 400 mil





12. REVISION HISTORY

REVISION	DATE	PAGE	DESCRIPTION
A1	Aug. 28, 2002	-	Preliminary datasheet
	Jan. 9, 2003	28	Add CAS Latency = 3 option
	Feb. 14, 2003	-	Modified AC timing spec.
A2	Feb. 14, 2003	10	Change IDD2p current to 8 mA
			Change IDD6 current to 9 mA
A3	May 21, 2003		Add CL2.5 optional in DDR400



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