

# Ultra-Low Power Stereo CODEC with Audio Enhancement DSP, 2W Stereo Class D Speaker Drivers and Ground Referenced Headphone Drivers

#### DESCRIPTION

The WM8963 is a low power, high performance stereo CODEC designed for portable digital audio applications.

An integrated charge pump provides a ground referenced output which removes the need for DC-blocking capacitors on the headphone outputs, and uses the Wolfson 'Class-W' amplifier techniques—incorporating an innovative dual-mode charge pump architecture—to optimise efficiency and power consumption during playback. A DC Servo is used to reduce DC ground offsets. This improves power consumption and minimises pops and clicks.

Stereo class D speaker drivers provide 2W per channel into  $4\Omega$  loads with a 5V supply. Low leakage, excellent PSRR and pop/click suppression mechanisms also allow direct battery connection to the speaker supply. Flexible speaker boost settings allow speaker output power to be maximised while minimising other analogue supply currents.

Control sequences for audio path setup can be pre-loaded and executed by an integrated sequencer to reduce software driver development and eliminate pops and clicks via Cirrus Logic's SilentSwitch™ technology.

Flexible input configuration: four stereo or eight mono analogue inputs on Left or Right ADC. A two-channel digital microphone interface is also supported. External component requirements are drastically reduced as no separate microphone, speaker or headphone amplifiers are required. Advanced on-chip digital signal processing performs automatic level control for the microphone or line input.

Stereo 24-bit sigma-delta ADCs and DACs are used with low power over-sampling digital interpolation and decimation filters and a flexible digital audio interface.

A programmable audio enhancement DSP is included with multiple preset algorithms. Virtual Surround Sound (VSS) widens the stereo speaker audio image, and ReTune™ can be used to flatten the frequency response of an external speaker. The Multi-band Compressor (MBC) can maximize the loudness of an audio signal, without overdriving the speaker. The configurable DSP also includes 3D widening for recording, a 5-band parametric EQ, and Dynamic Range Controller.

A high performance Frequency Locked Loop (FLL) is provided, to enable flexible system clocking. An internal oscillator (using external crystal) is also provided. Clock output signals, derived from the FLL, can also be enabled to support synchronous clocking of external circuits.

The WM8963 supports 1.8V external supplies. 1.2V digital core supply is supported, for low power operation. Speaker supplies up to 5.5V (including direct connection to a battery) enable maximum speaker output power. Unused functions can be disabled using software control to save power.

The WM8963 is supplied in a very small W-CSP package, ideal for use in hand-held and portable systems.

#### **FEATURES**

- DAC SNR 98dB ('A' weighted), THD -84dB at 48kHz, 1.8V
- ADC SNR 94dB ('A' weighted), THD -85dB at 48kHz, 1.8V
- Stereo Class D Speaker Driver
  - 2W per channel into  $4\Omega$  BTL speakers
  - 2W mono mode (for improved THD)
  - Flexible internal switching clock
- Wolfson 'Class-W' ultra-low power headphone driver
  - Up to 31mW per channel output power at 1% THD+N
  - Support for 2 stereo headphone outputs
  - Ground Referenced
  - Low offset (+/- 1.4mV)
  - Pop and click suppression
- Microphone Interface
  - Four stereo, single-ended analogue inputs
  - Digital microphone interface
  - Integrated low noise MICBIAS
  - Integrated LDO to generate MICVDD supply
  - Programmable ALC / Limiter and Noise Gate
- Programmable Audio Enhancement DSP with Presets
  - Virtual Surround Sound
  - ReTune<sup>™</sup> frequency linearisation
  - Multi-Band Compression (MBC)
- Fixed Audio Processing DSP
  - LPF/HPF
  - 3D stereo widening
  - 5-band Parametric EQ
  - Dynamic range controller
  - Beep generator
- Integrated FLL for flexible audio system clocking
  - External clock outputs from FLL
- Low power consumption
  - 5.0mW headphone playback
  - 6.1mW analogue record mode
  - 1.8V analogue & digital I/O supplies
  - 1.2V digital core supply, for low power operation.
     1.7V (min) required for full range of clocking ratios
  - 5.5V (max) speaker supply for high power output
- 2-wire I2C and 3- or 4-wire SPI serial control interface
- Standard sample rates from 8kHz to 96kHz
- W-CSP, 3.6mm x 3.9mm, 49-pin

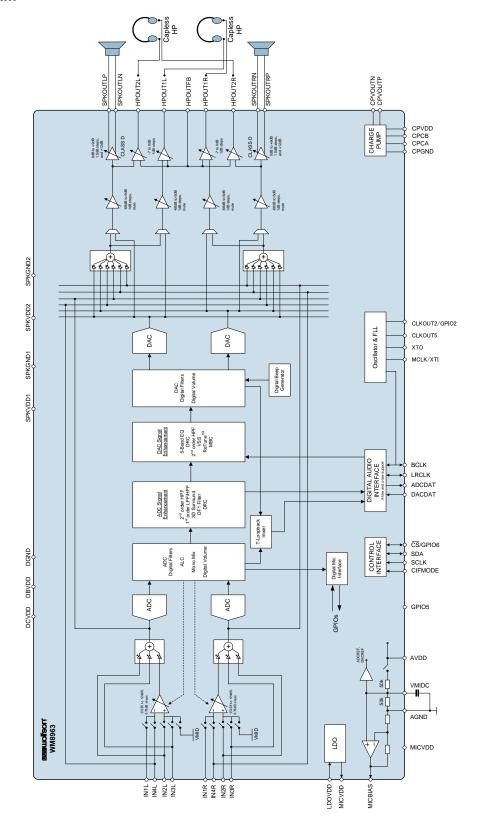
#### **APPLICATIONS**

- Portable gaming
- Voice recorders
- Mobile multimedia
- Stereo DSC-Camcorder





# **BLOCK DIAGRAM**





# **TABLE OF CONTENTS**

FEATURES	
APPLICATIONS	1
BLOCK DIAGRAM	2
TABLE OF CONTENTS	3
PIN CONFIGURATION	
ORDERING INFORMATION	
PIN DESCRIPTIONABSOLUTE MAXIMUM RATINGS	
RECOMMENDED OPERATING CONDITIONS	
ELECTRICAL CHARACTERISTICS	
TERMINOLOGY	
TYPICAL POWER CONSUMPTION	
SIGNAL TIMING REQUIREMENTS	23
MASTER CLOCK	23
AUDIO INTERFACE TIMING	24
DIGITAL MICROPHONE (DMIC) INTERFACE TIMING	
DIGITAL AUDIO INTERFACE - MASTER MODE	
DIGITAL AUDIO INTERFACE - SLAVE MODE	26
DIGITAL AUDIO INTERFACE - TDM MODE	
CONTROL INTERFACE TIMING	28
2-WIRE (I2C) CONTROL MODE	28
3-WIRE (SPI) CONTROL MODE	29
4-WIRE (SPI) CONTROL MODE	
POWER ON RESET TIMING	
DEVICE DESCRIPTION	
INTRODUCTION	
INPUT SIGNAL PATH	
MICROPHONE INPUT CONNECTION	35
LINE INPUT CONNECTION	
MICROPHONE BIAS CONTROL	36
MICROPHONE BIAS CONTROLMICBIAS CURRENT DETECT	36 37
MICROPHONE BIAS CONTROL MICBIAS CURRENT DETECT MICBIAS CURRENT DETECT FILTERING	36 37 39
MICROPHONE BIAS CONTROL MICBIAS CURRENT DETECT MICBIAS CURRENT DETECT FILTERING MICROPHONE HOOK SWITCH DETECTION	36 37 39
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE	36 37 39 40
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION	36 37 40 41
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL	36 37 40 41 42
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE.	363740414242
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION.  INPUT PGA ENABLE.  INPUT PGA CONFIGURATION.  INPUT PGA VOLUME CONTROL.  INPUT MIXER ENABLE.  INPUT MIXER CONFIGURATION AND VOLUME CONTROL.	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION.  INPUT PGA ENABLE.  INPUT PGA CONFIGURATION.  INPUT PGA VOLUME CONTROL.  INPUT MIXER ENABLE.  INPUT MIXER CONFIGURATION AND VOLUME CONTROL.  AUTOMATIC LEVEL CONTROL (ALC)	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION.  INPUT PGA ENABLE  INPUT PGA CONFIGURATION.  INPUT PGA VOLUME CONTROL.  INPUT MIXER ENABLE.  INPUT MIXER CONFIGURATION AND VOLUME CONTROL.  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE.  ALC GAIN CONTROL.	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING.  MICROPHONE HOOK SWITCH DETECTION.  INPUT PGA ENABLE.  INPUT PGA CONFIGURATION.  INPUT PGA VOLUME CONTROL.  INPUT MIXER ENABLE.  INPUT MIXER CONFIGURATION AND VOLUME CONTROL.  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE.  ALC GAIN CONTROL.  ALC DYNAMIC CHARACTERISTICS.	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE  ALC GAIN CONTROL  ALC DYNAMIC CHARACTERISTICS  PEAK LIMITER  ALC NOISE GATE  ALC STATUS READBACK	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE  ALC GAIN CONTROL  ALC DYNAMIC CHARACTERISTICS  PEAK LIMITER  ALC NOISE GATE  ALC STATUS READBACK  DIGITAL MICROPHONE INTERFACE	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE  ALC GAIN CONTROL  ALC DYNAMIC CHARACTERISTICS  PEAK LIMITER  ALC NOISE GATE  ALC STATUS READBACK	
MICROPHONE BIAS CONTROL  MICBIAS CURRENT DETECT  MICBIAS CURRENT DETECT FILTERING  MICROPHONE HOOK SWITCH DETECTION  INPUT PGA ENABLE  INPUT PGA CONFIGURATION  INPUT PGA VOLUME CONTROL  INPUT MIXER ENABLE  INPUT MIXER CONFIGURATION AND VOLUME CONTROL  AUTOMATIC LEVEL CONTROL (ALC)  LIMITER MODE  ALC GAIN CONTROL  ALC DYNAMIC CHARACTERISTICS  PEAK LIMITER  ALC NOISE GATE  ALC STATUS READBACK  DIGITAL MICROPHONE INTERFACE	
MICROPHONE BIAS CONTROL MICBIAS CURRENT DETECT MICBIAS CURRENT DETECT FILTERING MICROPHONE HOOK SWITCH DETECTION INPUT PGA ENABLE INPUT PGA CONFIGURATION INPUT PGA VOLUME CONTROL INPUT MIXER ENABLE INPUT MIXER CONFIGURATION AND VOLUME CONTROL AUTOMATIC LEVEL CONTROL (ALC) LIMITER MODE ALC GAIN CONTROL ALC DYNAMIC CHARACTERISTICS PEAK LIMITER ALC NOISE GATE ALC STATUS READBACK DIGITAL MICROPHONE INTERFACE ANALOGUE TO DIGITAL CONVERTER (ADC)	



ADC MONOMIXDSP SIGNAL ENHANCEMENTS	
ENABLE SEQUENCE - ENHANCEMENTS INITIALLY DISABLED	
ENABLE / DISABLE SEQUENCE - ENHANCEMENTS INITIALLY ENABLED	
DISABLE ALL SOUND ENHANCEMENTS SEQUENCE	
UPDATE / READBACK SEQUENCE - ENHANCEMENTS INITIALLY ENABLED	
UPDATE / READBACK SEQUENCE - ENHANCEMENTS INITIALLY DISABLED	
ADC SIGNAL PATH ENHANCEMENTS	
ADC SECOND ORDER HIGH-PASS FILTER	
LOW-PASS / HIGH-PASS FILTER (LPF/HPF)	
3D SURROUND	
DF1 FILTER	
DYNAMIC RANGE CONTROL (DRC)	
DIGITAL MIXING	
DIGITAL MIXING PATHS	
DIGITAL SIDETONE	
T-LOOPBACK	
DAC SIGNAL PATH ENHANCEMENTS	
5-BAND EQ	
DYNAMIC RANGE CONTROL (DRC)	
DAC SECOND ORDER HIGH-PASS FILTER	
VIRTUAL SURROUND SOUND (VSS)	
DAC RETUNE	
MULTIBAND COMPRESSOR (MBC)	
DIGITAL-TO-ANALOGUE CONVERTER (DAC)	101
DAC CLOCKING CONTROL	
DAC DIGITAL VOLUME CONTROL	
DAC SOFT MUTE AND UN-MUTE	104
DAC AUTO-MUTE	
DAC MONO MIX	106
DAC DE-EMPHASIS	107
DAC OVERSAMPLING RATIO (OSR)	107
DIGITAL BEEP GENERATOR	108
OUTPUT SIGNAL PATH	109
OUTPUT SIGNAL PATHS ENABLE	110
HEADPHONE SIGNAL PATHS ENABLE	111
SPEAKER MIXER CONTROL	
HEADPHONE OUTPUT PGA CONTROL	118
SPEAKER OUTPUT PGA CONTROL	
ANALOGUE OUTPUTS	
SPEAKER OUTPUT CONFIGURATIONS	
HEADPHONE OUTPUT CONFIGURATIONS	
CHARGE PUMP	
DC SERVO	
DC SERVO ENABLE AND START-UP	129
DC SERVO ACTIVE MODES	
REFERENCE VOLTAGES AND BIAS CONTROL	132
ANALOGUE REFERENCE AND MASTER BIAS	
INPUT SIGNAL PATH BIAS CONTROL SETTINGS	
OUTPUT SIGNAL PATH BIAS CONTROL SETTINGS	
DIGITAL AUDIO INTERFACE	
MASTER AND SLAVE MODE OPERATION	
OPERATION WITH TDM	
BCLK FREQUENCY	
AUDIO DATA FORMATS (NORMAL MODE)	137

# **WM8963**



AUDIO DATA FORMATS (TDM MODE)	
DIGITAL AUDIO INTERFACE CONTROL	
AUDIO INTERFACE TRI-STATE	
BCLK AND LRCLK CONTROL	
COMPANDING	
LOOPBACK	
CLOCKING AND SAMPLE RATES	
SYSCLK CONTROL	
AUTOMATIC CLOCKING CONFIGURATION	
DSP, ADC, DAC CLOCK CONTROL	
CLASS D, 256K, DC SERVO CLOCK CONTROL	
OPCLK CONTROL	
TOCLK, DBCLK CONTROL	
BCLK AND LRCLK CONTROL	
CONTROL INTERFACE CLOCKING	
INTERNAL / EXTERNAL CLOCK GENERATION	
START-UP OPTIONS FOR INTERNAL / EXTERNAL CLOCK GENERATION	
INTERNAL OSCILLATOR CONTROL	
CLKOUT CONTROL	
FREQUENCY LOCKED LOOP (FLL)	
FREE-RUNNING FLL CLOCK	
EXAMPLE FLL CALCULATIONGENERAL PURPOSE INPUT/OUTPUT (GPIO)	
· · · · · · · · · · · · · · · · · · ·	
INTERRUPTS CONTROL INTERFACE	
SELECTION OF CONTROL INTERFACE MODE	
2-WIRE (I2C) CONTROL MODE	
3-WIRE (SPI) CONTROL MODE	
CONTROL WRITE SEQUENCER	
INITIATING A SEQUENCE	
PROGRAMMING A SEQUENCE	
DEFAULT SEQUENCES	
THERMAL SHUTDOWN	
SOFTWARE RESET AND CHIP ID	
REGISTER MAP REGISTER BITS BY ADDRESS	
DIGITAL FILTER CHARACTERISTICS	
DAC FILTER RESPONSES	
ADC FILTER RESPONSES	
ADC HIGH PASS FILTER RESPONSES	
DE-EMPHASIS FILTER RESPONSES	
APPLICATIONS INFORMATION	
RECOMMENDED EXTERNAL COMPONENTS	
ANALOGUE INPUT PATHS	
MICROPHONE BIAS CIRCUIT	
INTERNAL LDO FOR MICBIAS CIRCUIT	
CHARGE PUMP COMPONENTS	
RECOMMENDED EXTERNAL COMPONENTS DIAGRAM	275

# **WM8963**



PCB LAYOUT CONSIDERATIONS	277
MIC DETECTION SEQUENCE USING MICBIAS CURRENT	278
PACKAGE DIMENSIONS	280
IMPORTANT NOTICE	281
REVISION HISTORY	282



# **PIN CONFIGURATION**

	1	2	3	4	5	6	7
Α	SPKGND1	SPKVDD1	MICVDD	MICBIAS	HPOUTFB	CPVOUTP	CPVOUTN
В	SPKVDD2	SPKOUTRP	SPKOUTLP	(HPOUT2R)	(HPOUT1R)	CPCA	СРСВ
С	SPKGND2	SPKOUTRN	SPKOUTLN	HPOUT2L	(HPOUT1L)	CPVDD	CPGND
D	SCLK	SDA	CIFMODE	IN3R	IN3L IN3L	AVDD	AGND
E	LRCLK	DACDAT	OSCENA/ GPIO5	IN2L	V V IVIO	LDOVDD	(IN1L
F	BCLK	ADCDAT	CS/GPIO6	IN2R	IN4R	VMIDC	IN1R
G	DGND	DCVDD	DBVDD	CLKOUT2/ GPIO2	CLKOUT5	MCLK/XTI	хто

# **ORDERING INFORMATION**

ORDER CODE	TEMPERATURE RANGE	PACKAGE	MOISTURE SENSITIVITY LEVEL	PEAK SOLDERING TEMPERATURE
WM8963ECSN/R	-40 to +85°C	49-ball W-CSP	MSL1	260°C

Note:

Reel quantity = 5000



# **PIN DESCRIPTION**

A description of each pin on the WM8963 is provided below.

Note that, where multiple pins share a common name, these pins should be tied together on the PCB.

PIN NO	NAME	TYPE	DESCRIPTION
F2	ADCDAT	Digital Output	ADC digital audio data
D7	AGND	Supply	Analogue ground (return path for AVDD and MICVDD)
D6	AVDD	Supply	Analogue supply
F1	BCLK	Digital Input / Output	Audio interface bit clock
D3	CIFMODE	Digital Input	Selects 2-wire or 3 / 4-wire control wire interface
G4	CLKOUT2/GPIO2	Digital Output	Clock output / General purpose output
G5	CLKOUT5	Digital Output	Clock output
B6	CPCA	Analogue Input	Charge pump fly-back capacitor pin
B7	СРСВ	Analogue Input	Charge pump fly-back capacitor pin
C7	CPGND	Supply	Charge pump ground (return path for CPVDD)
C6	CPVDD	Supply	Charge pump power supply
A7	CPVOUTN	Supply	Charge pump negative supply output
A6	CPVOUTP	Supply	Charge pump positive supply output
F3	CS/GPIO6	Digital Input / Output	CS input / General purpose input/output
E2	DACDAT	Digital Input	DAC digital audio data
G3	DBVDD	Supply	Digital Buffer Supply
G2	DCVDD	Supply	Digital Core Supply
G1	DGND	Supply	Digital ground
C5	HPOUT1L	Analogue Output	Left output 1 (Line or headphone)
B5	HPOUT1R	Analogue Output	Right output 1 (Line or headphone)
C4	HPOUT2L	Analogue Output	Left output 2 (Line or headphone)
B4	HPOUT2R	Analogue Output	Right output 2 (Line or headphone)
A5	HPOUTFB	Analogue Input	HPOUT1L/R and HPOUT2L/R ground loop noise rejection feedback
E7	IN1L	Analogue Input	Left channel single-ended input 1
F7	IN1R	Analogue Input	Right channel single-ended input 1
E4	IN2L	Analogue Input	Left channel single-ended input 2
F4	IN2R	Analogue Input	Right channel single-ended input 2
D5	IN3L	Analogue Input	Left channel single-ended input 3
D4	IN3R	Analogue Input	Right channel single-ended input 3
E5	IN4L	Analogue Input	Left channel single-ended input 4
F5	IN4R	Analogue Input	Right channel single-ended input 4
E6	LDOVDD	Supply	LDO Supply
E1	LRCLK	Digital Input / Output	Audio interface left / right clock
G6	MCLK/XTI	Digital Input	Master clock input / crystal input
A4	MICBIAS	Reference	Microphone bias
A3	MICVDD	Supply	Microphone bias amp supply
E3	OSCENA/GPIO5	Digital Input / Output	Oscillator control input / General purpose input/output
D1	SCLK	Digital Input	Control interface clock input
D2	SDA	Digital Input / Output	Control interface data input / acknowledge output
A1	SPKGND1	Supply	Ground for left speaker drivers
C1	SPKGND2	Supply	Ground for right speaker drivers
C3	SPKOUTLN	Analogue Output	Left speaker negative output
В3	SPKOUTLP	Analogue Output	Left speaker positive output
C2	SPKOUTRN	Analogue Output	Right speaker negative output
B2	SPKOUTRP	Analogue Output	Right speaker positive output
A2	SPKVDD1	Supply	Supply for left speaker drivers
B1	SPKVDD2	Supply	Supply for right speaker drivers



PIN NO NAME TYPE			DESCRIPTION		
F6	VMIDC	Reference	Midrail voltage (AVDD/2) decoupling capacitor pin		
G7	XTO	Analogue Output	Crystal output		

# **ABSOLUTE MAXIMUM RATINGS**

Absolute Maximum Ratings are stress ratings only. Permanent damage to the device may be caused by continuously operating at or beyond these limits. Device functional operating limits and guaranteed performance specifications are given under Electrical Characteristics at the test conditions specified.



ESD Sensitive Device. This device is manufactured on a CMOS process. It is therefore generically susceptible to damage from excessive static voltages. Proper ESD precautions must be taken during handling and storage of this device.

Cirrus Logic tests its package types according to IPC/JEDEC J-STD-020 for Moisture Sensitivity to determine acceptable storage conditions prior to surface mount assembly. These levels are:

MSL1 = unlimited floor life at <30°C / 85% Relative Humidity. Not normally stored in moisture barrier bag.

MSL2 = out of bag storage for 1 year at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag.

MSL3 = out of bag storage for 168 hours at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag.

The Moisture Sensitivity Level for each package type is specified in Ordering Information.

CONDITION	MIN	MAX
DCVDD, AVDD	-0.3V	+2.5V
MICVDD, DBVDD	-0.3V	+4.5V
LDOVDD, SPKVDD1, SPKVDD2	-0.3V	+7.0V
CPVDD	-0.3V	+2.2V
Voltage range digital inputs	DGND - 0.3V	DBVDD + 0.3V
Voltage range analogue inputs	AGND - 0.3V	AVDD + 0.3V
Voltage range analogue outputs (HPOUT1/2L, HPOUT1/2R)	-CPVDD - 0.3V	+CPVDD + 0.3V
Temperature Range, T <sub>A</sub>	-40°C	+85°C
Junction Temperature, T <sub>JMAX</sub>	-40°C	+150°C
Storage temperature after soldering	-65°C	+150°C

#### Notes:

- 1. Analogue, digital and speaker grounds must always be within 0.3V of each other.
- 2. All digital and analogue supplies are completely independent from each other (i.e. not internally connected).
- 3. AVDD must be less than or equal to MICVDD.
- 4. AVDD must be less than or equal to SPKVDD1 and SPKVDD2.



#### RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Digital core supply range (see notes 1, 7)	DCVDD	1.14	1.2	2.0	V
Digital I/O supply range	DBVDD	1.62	1.8	3.6	V
Microphone bias supply (see notes 2, 4)	MICVDD	1.7	2.5	3.6	V
Analogue supplies range (see note 7)	AVDD	1.7	1.8	2.0	V
LDO supply range (see notes 3, 4)	LDOVDD	2.7	5.0	5.5	V
Charge pump supply range (see note 7)	CPVDD	1.7	1.8	2.0	V
Speaker supply range (see note 5)	SPKVDD1, SPKVDD2	1.7	5.0	5.5	V
Ground	DGND, AGND, CPGND, SPKGND1, SPKGND2		0		V

#### Notes:

- 1. Note that some clocking configuration options are only valid for DCVDD  $\geq$  1.7V.
- 2. An internal LDO (powered by LDOVDD) can be used to provide the MICVDD supply.
- 3. If the LDO is not used, then the MICVDD and LDOVDD pins should be tied together. In this case, the MICVDD operating limits are applicable to both pins.
- 4. The MICVDD and LDOVDD supplies are not required if the MICBIAS generator is disabled, but these pins must be connected to 0V (not floating) in this case.
- 5. SPKVDD1 and SPKVDD2 must be high enough to support the peak output voltage when using CLASSD\_VOL function, to avoid output waveform clipping. Peak output voltage is AVDD\*CLASSD\_VOL.
- 6. The supply domains can be enabled or disabled in any order when starting up or shutting down the device; there are no power sequencing requirements.
- To minimise leakage currents, the AVDD, DCVDD and CPVDD supplies must either all be present or all be removed (0V or disconnected) when the device is not in use.



# **ELECTRICAL CHARACTERISTICS**

#### **Test Conditions**

 $\label{eq:DCVDD} DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO), \\$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Analogue Inputs (IN1L, IN1R, IN4L	, IN4R) to Inp	out PGA				
Full-scale Input Signal Level – note this changes in proportion to AVDD	V <sub>INFS</sub>	Single-ended PGA input		500 -6.02		mVrms dBV
Input resistance		+24dB PGA gain		3.6		kΩ
		0dB PGA gain		30.0		
		-23.25dB PGA gain		56.5		
Input capacitance	Cin			65		pF
Analogue Inputs (IN2L, IN2R, IN3L	., IN3R) to Inp	out PGA				
Full-scale Input Signal Level – note this changes in proportion to AVDD	V <sub>INFS</sub>	Single-ended PGA input		500 -6.02		mVrms dBV
Input resistance		All gain settings		60		kΩ
Input Programmable Gain Amplific	er (PGA)			<u> </u>		
Minimum programmable gain				-23.25		dB
Maximum programmable gain				24		dB
Programmable Gain Step Size		Guaranteed monotonic		0.75		dB
PGA Noise (referred to input)		A-weighted		-113		dBV
Mute Attenuation				100		dB
Selectable Input Gain Boost (from	Input PGA)					
Gain Boost Steps		Input from PGA		0, 6, 13, 18, 20, 24, 27, 29		dB
Mute Attenuation				95		dB
Selectable Input Gain Boost (from	IN2, IN3)					
Gain Boost Steps		Input from IN2 or IN3		-12, -9, -6, -3, 0, 3, 6		dB
Mute Attenuation				95		dB



DCVDD = 1.2V, DBVDD = CPVDD = AVDD = 1.8V, LDOVDD = SPKVDD1 = SPKVDD2 = 5V, MICVDD = 2.45V (powered from internal LDO),

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Analogue Inputs (IN1L, IN1R) to	ADC out via Ir	nput PGA and Input Gain Boost				
Signal to Noise Ratio (A-weighted)	SNR	ADC_HP=0 MIXIN_BIAS=100		91		dB
Total Harmonic Distortion Plus Noise (-1dBFS input)	THD+N	INPGA_BIAS=100  'Option 1' (low power) bias		-70		dB
		settings - see Note 2.				
Signal to Noise Ratio (A-weighted)	SNR	ADC_HP=0 MIXIN_BIAS=011		91		dB
Total Harmonic Distortion Plus Noise (-1dBFS input)	THD+N	INPGA_BIAS=100		-75		dB
		'Option 2' bias settings - see Note 2.				
Signal to Noise Ratio (A-weighted)	SNR	ADC_HP=0 MIXIN_BIAS=000	81	91		dB
Total Harmonic Distortion Plus Noise (-1dBFS input)	THD+N	INPGA_BIAS=100		-82	-72	dB
		'Option 3' bias settings - see Note 2.				
Signal to Noise Ratio (A-weighted)	SNR	ADC_HP=1 MIXIN_BIAS=000		93		dB
Total Harmonic Distortion Plus Noise (-1dBFS input)	THD+N	INPGA_BIAS=000		-82		dB
		'Option 4' (high performance) bias settings - see Note 2.				
ADC Channel Separation		1kHz		95		dB
		10kHz		97		
PSRR (AVDD)		100mV (peak-peak) 1kHz		60		dB
		100mV(peak-peak) 20kHz		40		
Channel Matching		1kHz signal		+/-0.5		dB



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Analogue Inputs (IN2L, IN2R, IN3I	L, IN3R) to A	DC out via Input Gain (Input PG	A Bypasse	d)		
Signal to Noise Ratio	SNR	ADC_HP=0		91		dB
(A-weighted)		MIXIN_BIAS=100				
Total Harmonic Distortion Plus	THD+N	INPGA_BIAS=100		-70		dB
Noise (-1dBFS input)						
		'Option 1' (low power) bias				
		settings - see Note 2.				
Signal to Noise Ratio	SNR	ADC_HP=0		91		dB
(A-weighted)		MIXIN_BIAS=011				
Total Harmonic Distortion Plus	THD+N	INPGA_BIAS=100		-75		dB
Noise (-1dBFS input)		'Ontion 2' higg pattings				
		'Option 2' bias settings - see Note 2.				
Signal to Noise Ratio	SNR	ADC HP=0		91		dB
(A-weighted)	SIVIX	MIXIN_BIAS=000		31		ub
Total Harmonic Distortion Plus	THD+N	INPGA BIAS=100		-82		dB
Noise (-1dBFS input)	I HD+N	1141 G/_B//(G=100		-02		uБ
relea ( rez. o mpal)		'Option 3' bias settings -				
		see Note 2.				
Signal to Noise Ratio	SNR	ADC_HP=1		94		dB
(A-weighted)		MIXIN_BIAS=000				
Total Harmonic Distortion Plus	THD+N	INPGA_BIAS=000		-85		dB
Noise (-1dBFS input)						
		'Option 4' (high performance)				
		bias settings - see Note 2.				
ADC Channel Separation		1kHz		95		dB
		10kHz		87		
PSRR (AVDD)		100mV (peak-peak) 1kHz		60		dB
		100mV(peak-peak) 20kHz		40		
Analogue Inputs (IN4L, IN4R) to F			with 10 kΩ,	50pF load:		
Low Power headphone playback	mode (Note :	3)			1	
Input resistance		+6dB Speaker Mixer gain		7		kΩ
		0dB Speaker Mixer gain		10		
		-15dB Speaker Mixer gain		19		
Signal to Noise Ratio	SNR	A-weighted		97		dB
Total Harmonic Distortion Plus	THD+N	10kΩ, 50pF load		-80		dB
Noise		, , , , , , , , , , , , , , , , , , , ,				
ADC Input Path Crosstalk	-		•			
IN1 / IN4 ADC input path crosstalk		1kHz		-98		dB
• •		10kHz		-79		
IN2 / IN3 ADC input path crosstalk		1kHz		-85		dB
		10kHz		-65		1 "
IN2 / IN4 ADC input noth grootells		1kHz		-90	1	dB
IN2 / IN4 ADC input path crosstalk		10kHz			1	- ub
INIO / INIA ADO immedia alle accessione				-69	1	
IN3 / IN4 ADC input path crosstalk		1kHz 10kHz		-75		dB
				-55		



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
HPOUTL/R_VOL						
Minimum programmable gain				-68		dB
Maximum programmable gain				6		dB
Volume Gain Step Size		Guaranteed monotonic		1		dB
Mute Attenuation				94		dB
HP1L/R_VOL, HP2L/R_VOL	•				•	•
Minimum programmable gain				-7		dB
Maximum programmable gain				0		dB
Volume Gain Step Size		Guaranteed monotonic		1		dB
DAC to HPOUT1/2L, HPOUT1/2R Low Power headphone playback Full scale output voltage	•	. ,	· 	0.96	<u> </u>	Vrms
1 0	SNR	_	87	97		
Signal to Noise Ratio		A-weighted	87			dB
Total Harmonic Distortion Plus Noise	THD+N			-84	-70	dB
Channel Separation		1kHz full scale signal		93		dB
		10kHz full scale signal		86		
PSRR (AVDD)		100mV(peak-peak) 1kHz		70		dB
		100mV(peak-peak) 20kHz		65		
DC offset		DC servo is enabled	0		+/-1.4	mV
DAC to HPOUT1/2L, HPOUT1/2R High Performance headphone p			:			
Signal to Noise Ratio	SNR	A-weighted		98		dB
Total Harmonic Distortion Plus Noise	THD+N			-84		dB



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DAC to Headphone Output (HPC Low Power headphone playback						
Output Power at 1% THD+N	Po	R <sub>L</sub> =32Ω		26		mW
·		R <sub>L</sub> =16Ω		31		
Total Harmonic Distortion Plus	THD+N	$R_L=32\Omega$ , $P_O=2mW$		-79		dB
Noise				0.011		%
		$R_L=32\Omega$ , $P_O=3.5$ mW		-79		
				0.011		
		$R_L=32\Omega$ , $P_O=12mW$		-78		
				0.013		
		$R_L=16\Omega$ , $P_O=2mW$		-78		
				0.013		
		$R_L=16\Omega$ , $P_O=22mW$		-80	-70	
				0.010	0.032	
Output Noise Level				-97	-85	dBV
DC offset		DC servo is enabled	0		+/-1.4	mV
Channel Separation		1kHz full scale signal		95		dB
		10kHz full scale signal		84		
DAC to Headphone Output (HPC High Performance headphone p	•	, .				
Total Harmonic Distortion Plus	THD+N	$R_L=32\Omega$ , $P_O=12$ mW		-84		dB
Noise				0.0063		%
		$R_L=16\Omega$ , $P_O=22$ mW		-81		
				0.0089		
Output Noise Level				-98		dBV



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SPKOUTL/R_VOL						
Minimum programmable gain				-68		dB
Maximum programmable gain				6		dB
Volume Gain Step Size		Guaranteed monotonic		1		dB
Mute Attenuation				92		dB
DAC to Stereo Speaker Output (	SPKOUTLP, S	PKOUTLN, SPKOUTRP, SPKO	UTRN) witl	n stereo 8 $\Omega$ b	ridge tied lo	ad
Output Power	Po	1% THD+N, $R_L = 8\Omega$ , SPKVDD1=SPKVDD2=5.5V		1.26		W
		1% THD+N, $R_L = 8\Omega$ , SPKVDD1=SPKVDD2=1.7V		0.08		
Total Harmonic Distortion Plus Noise	THD+N	$P_{\text{O}} = 200 \text{mW}, R_{\text{L}} = 8\Omega,$ SPKVDD1=SPKVDD2=3.3V, AVDD=1.8V		-68 0.040		dB %
		$\begin{aligned} &P_{\text{O}} = &320\text{mW}, \ R_{\text{L}} = &8\Omega, \\ &\text{SPKVDD1} = &\text{SPKVDD2} = &3.3\text{V}, \\ &\text{AVDD} = &1.8\text{V} \end{aligned}$		-72 0.025		
		$\begin{aligned} &P_{\text{O}} = &320\text{mW}, \ R_{\text{L}} = 8\Omega, \\ &\text{SPKVDD1} = &\text{SPKVDD2} = &5\text{V}, \\ &\text{AVDD} = &1.8\text{V} \end{aligned}$		-67 0.045	-55 0.178	
		$\begin{split} P_{\text{O}} = &1\text{W, R}_{\text{L}} = 8\Omega, \\ \text{SPKVDD1} = &\text{SPKVDD2} = &5\text{V,} \\ \text{AVDD} = &1.8\text{V,} \\ \text{CLASSD\_VOL} = &110 \\ \text{DACL/R\_VOL} = &\text{C1h} \end{split}$		-61 0.089		
Signal to Noise Ratio (A-weighted) (DAC to speaker outputs)	SNR	SPKVDD1=SPKVDD2=3.3V, AVDD=1.8V, $R_L = 8\Omega$ , Output signal=2.0Vrms		90		dB
(		SPKVDD1=SPKVDD2=5V, AVDD=1.8V, $R_L = 8\Omega$ , Output signal=2.8Vrms	83	93		
PSRR (SPKVDD1/SPKVDD2)	PSRR	100mV(peak-peak) 217Hz		78		dB
		100mV(peak-peak) 1kHz		78		1
DAC to Stereo Speaker Output (	SPKOUTLP, S	PKOUTLN, SPKOUTRP, SPKO	UTRN) witl	n stereo 4 $\Omega$ b	ridge tied lo	ad
Output Power	Po	1% THD+N, $R_L = 4\Omega$ , SPKVDD1=SPKVDD2=5V		1.75		W
		10% THD+N, $R_L = 4\Omega$ , SPKVDD1=SPKVDD2=5V		2.20		
Total Harmonic Distortion Plus Noise	THD+N	$P_O$ =1W, $R_L$ = $4\Omega$ , SPKVDD1=SPKVDD2=5V		-67 0.045		dB %
		$P_O$ =2W, $R_L$ = $4\Omega$ , SPKVDD1=SPKVDD2=5V		-25 5.5		
Signal to Noise Ratio (A-weighted) (DAC to speaker outputs)	SNR	$\label{eq:spkvdd} \begin{array}{c} \text{SPKVDD1=SPKVDD2=3.3V}, \\ R_{\text{L}} = 4\Omega, \\ \text{Output signal=2.0Vrms} \end{array}$		90		dB
		$\label{eq:SPKVDD1=SPKVDD2=5V} \begin{split} \text{SPKVDD1=SPKVDD2=5V}, \\ \text{R}_{\text{L}} = 4\Omega, \\ \text{Output signal=2.8Vrms} \end{split}$		93		



DCVDD = 1.2V, DBVDD = CPVDD = AVDD = 1.8V, LDOVDD = SPKVDD1 = SPKVDD2 = 5V, MICVDD = 2.45V (powered from internal LDO),

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DAC to Mono Speaker Output (S	PKOUTLP/RP	, SPKOUTLN/RN) with mono 49	Ω bridge tie	ed load, SPK	MONO=1	
Output Power	Po	1% THD+N, $R_L = 4\Omega$ , SPKVDD1=SPKVDD2=5.5V		2.45		W
		1% THD+N, $R_L = 4\Omega$ , SPKVDD1=SPKVDD2=1.7V		0.15		
Total Harmonic Distortion Plus Noise	THD+N	$P_O$ =400mW, $R_L$ = $4\Omega$ , SPKVDD1=SPKVDD2=3.3V		-64 0.063		dB %
		$P_O$ =640mW, $R_L$ = 4 $\Omega$ , SPKVDD1=SPKVDD2=3.3V		-63 0.071		
		$P_0$ =640mW, $R_L$ = 4 $\Omega$ , SPKVDD1=SPKVDD2=5V		-67 0.044		
		$\begin{aligned} P_{\text{O}} = & 2W,  R_{\text{L}} = 4\Omega, \\ & \text{SPKVDD1=SPKVDD2=5V}, \\ & \text{CLASSD\_VOL=110} \\ & \text{DACL/R\_VOL=C1h} \end{aligned}$		-61 0.089		
Signal to Noise Ratio (A-weighted) (DAC to speaker outputs)	SNR	$ \begin{array}{c} \text{SPKVDD1=SPKVDD2=3.3V}, \\ R_{\text{L}} = 4\Omega, \\ \text{Output signal=2.0Vrms} \end{array} $		90		dB
, , ,		$\label{eq:SPKVDD1=SPKVDD2=5V} \begin{split} \text{SPKVDD1=SPKVDD2=5V}, \\ \text{$R_{\text{L}}=4\Omega$,} \\ \text{Output signal=2.8Vrms} \end{split}$		93		



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Analogue Reference Levels						
Mid-rail Reference Voltage	VMIDC		-3%	AVDD/2	+3%	V
Microphone Bias						
Bias Voltage (Note that MICVDD must be at least 300mV higher than V <sub>MICBIAS</sub> . If MICVDD is powered from the	V <sub>MICBIAS</sub>	MICVDD=2.5V, 2mA load current, MICBIAS_EVR=00, MICBIAS_LVL=0	-4%	0.828 × AVDD	+4%	V
internal LDO, the minimum MICVDD is 250mV above the desired $V_{\mbox{\scriptsize MICBIAS}}$ voltage.)		MICVDD=2.5V, 2mA load current, MICBIAS_EVR=00, MICBIAS_LVL=1	-4%	1.156 × AVDD	+4%	
		MICVDD=3.3V, 2mA load current, MICBIAS_EVR=10		1.34 × AVDD		
		MICVDD=3.3V, 2mA load current, MICBIAS_EVR=01		1.63 × AVDD		
PSRR (MICVDD)	PSRR	100mV (peak-peak) 1kHz, 74 MICBIAS_EVR=00, MICBIAS_LVL=1		dB		
PSRR (AVDD)	PSRR	100mV (peak-peak) 1kHz, 52 MICBIAS_EVR=00, MICBIAS_LVL=1			dB	
Maximum Bias Current Source	I <sub>MICBIAS</sub>			2		mA
Output Noise spectral density @1kHz	Vst	MICBIAS_EVR=00, MICBIAS_LVL=0		63		nV/√Hz
		MICBIAS_EVR=00, MICBIAS_LVL=1		85		
		MICBIAS_EVR=10		96		
		MICBIAS_EVR=01		116		
MICBIAS Current Detect Functio	n (see Note 1)		1			
Current Detect Threshold		MICDET_THR = 000		64		μΑ
		MICDET_THR = 001		166		
		MICDET_THR = 010		358		
		MICDET_THR = 011		461		
		MICDET_THR = 100		563		
		MICDET_THR = 101	-20%	666	+20%	
		MICDET_THR = 110		858		
		MICDET_THR = 111		960		
Delay Time for Current Detect Interrupt	t <sub>DET</sub>			1.6		ms
MICBIAS Short Circuit (Hook Sw	itch) Detect Fu	ınction (see Note 1)				
Short Circuit Detect Threshold		MICSHORT_THR = 00		510		μΑ
		MICSHORT_THR = 01		653		
		MICSHORT_THR = 10		1040		
		MICSHORT_THR = 11		1200		
Delay Time for Short Circuit Detect Interrupt	t <sub>SHORT</sub>			47		ms



 $DCVDD = 1.2V, \ DBVDD = CPVDD = AVDD = 1.8V, \ LDOVDD = SPKVDD1 = SPKVDD2 = 5V, \\ MICVDD = 2.45V \ (powered from internal LDO),$ 

 $T_A = +25$ °C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
LDO					•	•
LDO output voltage (Note that LDOVDD must be at	V <sub>MICVDD</sub>	LDO_VOUT_SEL=0		1.36 x AVDD		V
least 250mV higher than V <sub>MICVDD</sub> )		LDO_VOUT_SEL=1		1.78 x AVDD		
Frequency Locked Loop (FLL)					•	•
Input frequency	F <sub>REF</sub>	FLL_REFCLK_DIV = 00	0.032		13.5	MHz
		FLL_REFCLK_DIV = 01	0.064		27	
		FLL_REFCLK_DIV = 10	0.128		36.864	
Output frequency	Fout		1.875		50	MHz
Start-Up time				220		μS
Frequency synthesis error				0		ppm
Start-Up time (free-running mode)				0.75		μS
Frequency accuracy (free-running mode)		Reference clock supplied Initially		+/-10		%
		No reference clock provided		+/-30		%
Crystal Oscillator					•	•
External crystal frequency				24		MHz
Oscillator load capacitance		XTI and XTO pins		10.5		pF
Start-Up time		Measured from OSC_ENA rising edge until Crystal Oscillator output is stable.		1.5		ms
Charge Pump						
Maximum Charge Pump switching frequency	CP <sub>FREQ</sub>			1		MHz
Flyback capacitor (between CPCA and CPCB pins)	C <sub>FB</sub>	at 2V	1			μF
CPVOUTP capacitor		at 2V	2			μF
CPVOUTN capacitor		at 2V	2			μF
Charge pump start-up time				190		μs
Digital Input / Output						
Input HIGH Level	V <sub>IH</sub>		0.7 × DBVDD			V
Input LOW Level	V <sub>IL</sub>				0.3 × DBVDD	V
Output HIGH Level	V <sub>OH</sub>	I <sub>OH</sub> = 1mA	0.9 × DBVDD			V
Output LOW Level	V <sub>OL</sub>	I <sub>OL</sub> = -1mA			0.1 × DBVDD	V
Input capacitance				15		pF
Input leakage			-0.9		0.9	μA



DCVDD = 1.2V, DBVDD = CPVDD = AVDD = 1.8V, LDOVDD = SPKVDD1 = SPKVDD2 = 5V, MICVDD = 2.45V (powered from internal LDO).

T<sub>A</sub> = +25°C, 1kHz signal, fs = 48kHz, PGA gain = 0dB, 24-bit audio data unless otherwise stated.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Current Consumption						
AVDD	I <sub>AVDD</sub>	OFF: power applied, all sub-		40	50	μA
DCVDD	I <sub>DCVDD</sub>	blocks powered off Thermal shutdown enabled.		3	10	μA
DBVDD	I <sub>DBVDD</sub>			0.5	5	μA
CPVDD	I <sub>CPVDD</sub>			0.5	10	μA
SPKVDD1	I <sub>SPKVDD1</sub>			1	10	μA
SPKVDD2	I <sub>SPKVDD2</sub>			1	10	μA
LDOVDD	I <sub>LDOVDD</sub>			1	5	μΑ
Leakage Current						
Standby Mode leakage current	I <sub>SPKVDD1</sub>	SPKVDD = 4.2V		0.2	5	μA
	I <sub>SPKVDD2</sub>	LDOVDD = 4.2V		0.2	5	μA
	I <sub>LDOVDD</sub>	Other supplies Hi-Z All clocks stopped		0.2	1	μΑ

#### Note:

- 1. If AVDD ≠ 1.8, current threshold values should be multiplied by (AVDD/1.8)
- 2. Four different bias configurations are supported for ADC input paths see "Reference Voltages and Bias Control" section.
- Two different bias configurations are supported for the DAC / Headphone output paths see "Reference Voltages and Bias Control".

#### **TERMINOLOGY**

- 1. Signal-to-Noise Ratio (dB) SNR is a measure of the difference in level between the maximum full scale output signal and the output with no input signal applied. (Note that this is measured without any mute function enabled.)
- 2. Total Harmonic Distortion (dB) THD is the ratio of the RMS sum of the harmonic distortion products in the specified bandwidth (see note below) relative to the RMS amplitude of the fundamental (ie. test frequency) output.
- 3. Total Harmonic Distortion plus Noise (dB) THD+N is the ratio of the RMS sum of the harmonic distortion products plus noise in the specified bandwidth (see note below) relative to the RMS amplitude of the fundamental (ie. test frequency) output.
- 4. Channel Separation (L/R) (dB) left-to-right and right-to-left channel separation is the measured signal level in the idle channel at the test signal frequency relative to the signal level at the output of the active channel. The active channel is configured and supplied with an appropriate input signal to drive a full scale output, with signal measured at the output of the associated idle channel.
- 5. Input Path Crosstalk (dB) The ADC path is enabled from one input pin, and a -6dBV test signal is applied to a different (disabled) input pin; the Crosstalk is the measured signal level at the ADC output relative to the ADC output level of the same test signal applied to an enabled input path.
- 6. Mute Attenuation This is a measure of the difference in level between the full scale output signal and the output with mute applied.
- 7. All performance measurements carried out with 20kHz low-pass filter, and where noted an A-weighted filter. Failure to use such a filter will result in higher THD and lower SNR readings than are found in the Electrical Characteristics. The low-pass filter removes out of band noise.



#### TYPICAL POWER CONSUMPTION

Analogue Input (IN1L, IN1R) to ADC out via Input PGA and Input Gain boost; DC Servo enabled.

Quiescent input, default register conditions unless otherwise stated.

MCLK = 12.288MHz, fs = 48kHz, MCLK rate = 256fs, 24-bit I2S, Slave mode,

INL ENA = 1, INR ENA = 1,

INPGAL\_MUTE = 0, INPGAR\_MUTE = 0,

ADCL\_ENA = 1, ADCR\_ENA = 1,

VMID\_SEL = 01, VMID\_BUF\_ENA = 1, BIAS\_ENA = 1,

INL\_DCS\_ENA =1, INR\_DCS\_ENA = 1.

See "Reference Voltages and Bias Control" for details of the bias configuration registers.

	DCVDD 1.2V	DBVDD 1.8V	AVDD 1.8V	LDOVDD 5.0V	CPVDD 1.8V	SPKVDD 5.0V	TOTAL
Option 3 bias settings (default), LDO and MICBIAS disabled	1.7mA	0.02mA	3.2mA	0.002mA	0.001mA	0.002mA	7.9mW
Option 1 bias settings, LDO and MICBIAS disabled	1.7mA	0.02mA	2.5mA	0.002mA	0.001mA	0.002mA	6.6mW
Option 3 bias settings, LDO and MICBIAS enabled	1.7mA	0.02mA	3.2mA	0.4mA	0.001mA	0.002mA	9.7mW

#### Analogue Input (IN2L, IN2R) to ADC out via Input Gain boost (Input PGA bypassed).

Quiescent input, default register conditions unless otherwise stated.

MCLK = 12.288MHz, fs = 48kHz, MCLK rate = 256fs, 24-bit I2S, Slave mode,

MIXINL\_ENA = 1, MIXINR\_ENA = 1, IN2L\_TO\_MIXINL = 1, IN2R\_TO\_MIXINR = 1,

IN1L\_TO\_INPGAL = 0, IN1R\_TO\_INPGAR = 0, INPGAL\_TO\_MIXINL = 0, INPGAR\_TO\_MIXINR = 0,

ADCL\_ENA = 1, ADCR\_ENA = 1,

VMID\_SEL = 01, VMID\_BUF\_ENA = 1, BIAS\_ENA = 1,

See "Reference Voltages and Bias Control" for details of the bias configuration registers.

	DCVDD 1.2V	DBVDD 1.8V	AVDD 1.8V	LDOVDD 5.0V	CPVDD 1.8V	SPKVDD 5.0V	TOTAL
Option 3 bias settings (default)	1.7mA	0.02mA	2.9mA	0.002mA	0.001mA	0.002mA	7.3mW
Option 1 bias settings	1.7mA	0.02mA	2.2mA	0.002mA	0.001mA	0.002mA	6.1mW

#### Stereo DAC Playback to Headphone (HPOUT1L, HPOUT1R) - 16Ω load.

Quiescent output, default register conditions unless otherwise stated.

Default DAC to Headphone 1 Power Up sequence completed.

CP\_DYN\_PWR = 1, fs = 48kHz, 24-bit I2S, Slave mode,

VMID\_SEL = 01, HPOUTL\_VOL = 79h (0dB), HPOUTR\_VOL = 79h (0dB).

See "Reference Voltages and Bias Control" for details of the performance mode configuration registers.

ood residence residence as a place of	itioi ioi aotaii	o oo poo		oornigaraor	og.oto. o.		
	DCVDD	DBVDD	AVDD	LDOVDD	CPVDD	SPKVDD	TOTAL
	1.2V	1.8V	1.8V	5.0V	1.8V	5.0V	
Low power playback mode (default)	1.0mA	0.002mA	1.7mA	0.002mA	0.4mA	0.002mA	5.0mW
MCLK = 6.144MHz,							
MCLK rate = 128fs.							
$HP1L_VOL = 111 (0dB),$							
HP1R_VOL = 111 (0dB),							
High performance playback mode,	1.5mA	0.003mA	2.5mA	0.002mA	0.4mA	0.002mA	7.0mW
MCLK = 12.288MHz,							
MCLK rate = 256fs.							
$HP1L_VOL = 000 (-7dB),$							
HP1R_VOL = 000 (-7dB),							



Stereo DAC Playback to Speaker (SPKOUTLP, SPKOUTRN, SPKOUTRN) - 8.2Ω, 2.2μH load.

Quiescent output, default register conditions unless otherwise stated.

DAC\_MUTE = 0, DACL\_ENA = 1, DACR\_ENA = 1,

SPKOUTL\_ENA = 1, SPKOUTL\_PGA\_ENA = 1,

SPKOUTR\_ENA = 1, SPKOUTR\_PGA\_ENA = 1,

 $SPKOUTL_VOL = 79h (0dB), SPKOUTR_VOL = 79h (0dB),$ 

CLASSD\_VOL = 110 (+9dB), VMID\_SEL = 01, VMID\_BUF\_ENA = 1, BIAS\_ENA = 1.

fs = 48kHz, 24-bit I2S, Slave mode.

	DCVDD 1.2V	DBVDD 1.8V	AVDD 1.8V	LDOVDD 5.0V	CPVDD 1.8V	SPKVDD 5.0V	TOTAL
MCLK = 12.288MHz, MCLK rate = 256fs,	1.5mA	0.003mA	2.6mA	0.002mA	0.001mA	1.7mA	15.1mW
MCLK = 24.576MHz, MCLK rate = 512fs, DSP Sound Enhancement Enabled	11.0mA	0.006mA	2.6mA	0.002mA	0.001mA	1.7mA	26.5mW

#### **Clocking Configurations**

Default register conditions unless otherwise stated.

CLKREG\_OVD = 1, CLKOUT2\_OE = 0, CLKOUT5\_OE = 0,

FLL\_REFCLK\_SRC = 10, FLL\_OSC\_ENA = 1, FLL\_ENA = 1,

MCLK\_SRC = 01, VMID\_SEL = 01, BIAS\_ENA = 1.

	DCVDD	DBVDD	AVDD	LDOVDD	CPVDD	SPKVDD	TOTAL
	1.2V	1.8V	1.8V	5.0V	1.8V	5.0V	
24MHz crystal oscillator enabled	0.63mA	0.05mA	1.52mA	0.002mA	0.001mA	0.002mA	3.60mW
24MHz crystal oscillator enabled, FLL enabled, FLL output = 12.288MHz	1.33mA	0.05mA	1.73mA	0.002mA	0.001mA	0.002mA	4.82mW

#### Notes:

- 1. SPKVDD = SPKVDD1 = SPKVDD2.
- 2.  $I_{SPKVDD} = I_{SPKVDD1} + I_{SPKVDD2}$ .
- 3. Speaker load inductance will affect the power consumption; reduced inductance will increase power consumption.



# SIGNAL TIMING REQUIREMENTS MASTER CLOCK

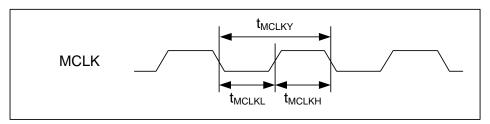


Figure 1 Master Clock Timing

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNIT
Master Clock Timing						
MCLK cycle time	T <sub>MCLKY</sub>		20.3			ns
MCLK duty cycle	T <sub>MCLKH</sub> : T <sub>MCLKL</sub>		60:40		40:60	



# **AUDIO INTERFACE TIMING**

# **DIGITAL MICROPHONE (DMIC) INTERFACE TIMING**

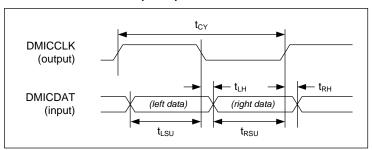


Figure 2 Digital Microphone Interface Timing

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Digital Microphone Interface Timing					
DMICCLK cycle time	t <sub>CY</sub>	320			ns
DMICCLK duty cycle		45:55		55:45	
DMICDAT (Left) setup time to falling DMICCLK edge	t <sub>LSU</sub>	15			ns
DMICDAT (Left) hold time from falling DMICCLK edge	t <sub>LH</sub>	0			ns
DMICDAT (Right) setup time to rising DMICCLK edge	t <sub>RSU</sub>	15			ns
DMICDAT (Right) hold time from rising DMICCLK edge	t <sub>RH</sub>	0			ns



#### **DIGITAL AUDIO INTERFACE - MASTER MODE**

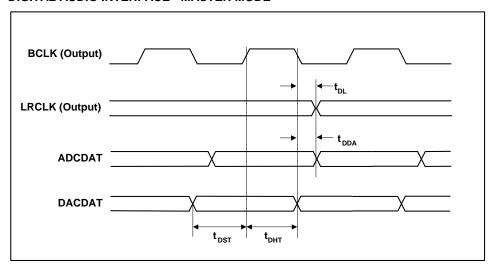


Figure 3 Audio Interface Timing - Master Mode

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Audio Interface Timing - Master Mode					
LRCLK propagation delay from BCLK falling edge	t <sub>DL</sub>			10	ns
ADCDAT propagation delay from BCLK falling edge	t <sub>DDA</sub>			14	ns
DACDAT setup time to BCLK rising edge	t <sub>DST</sub>	10			ns
DACDAT hold time from BCLK rising edge	t <sub>DHT</sub>	10			ns



#### **DIGITAL AUDIO INTERFACE - SLAVE MODE**

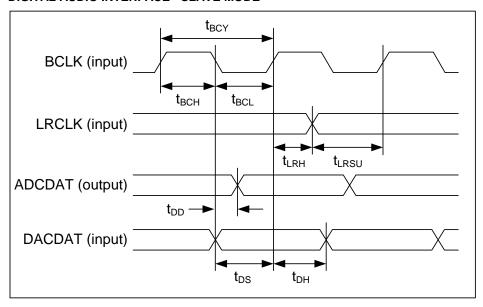


Figure 4 Audio Interface Timing - Slave Mode

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Audio Interface Timing - Slave Mode					
BCLK cycle time	t <sub>BCY</sub>	50			ns
BCLK pulse width high	t <sub>BCH</sub>	20			ns
BCLK pulse width low	t <sub>BCL</sub>	20			ns
LRCLK set-up time to BCLK rising edge	t <sub>LRSU</sub>	16			ns
LRCLK hold time from BCLK rising edge	t <sub>LRH</sub>	10			ns
DACDAT hold time from BCLK rising edge	t <sub>DH</sub>	10			ns
ADCDAT propagation delay from BCLK falling edge	t <sub>DD</sub>			14	ns
DACDAT set-up time to BCLK rising edge	t <sub>DS</sub>	10			ns

#### Note:

BCLK period should always be greater than or equal to MCLK period.



# **DIGITAL AUDIO INTERFACE - TDM MODE**

In TDM mode, it is important that two devices do not attempt to drive the ADCDAT pin simultaneously. The timing of the WM8963 ADCDAT pin tri-stating at the start and end of the data transmission is described below.

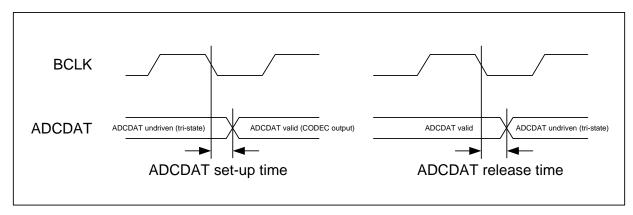


Figure 5 Audio Interface Timing - TDM Mode

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Audio Interface Timing - TDM Mode					
ADCDAT setup time from BCLK falling edge			4		ns
ADCDAT release time from BCLK falling edge			25		ns



# **CONTROL INTERFACE TIMING**

# 2-WIRE (I2C) CONTROL MODE

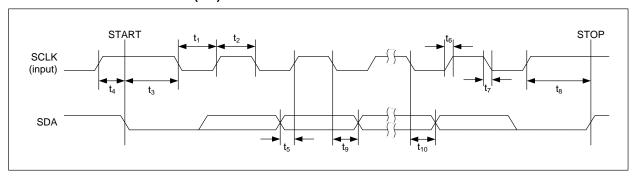


Figure 6 Control Interface Timing - 2-wire (I2C) Control Mode

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
Program Register Input Information		-	•	•	
SCLK Frequency				526	kHz
SCLK Low Pulse-Width	t <sub>1</sub>	1.3			us
SCLK High Pulse-Width	t <sub>2</sub>	600			ns
Hold Time (Start Condition)	t <sub>3</sub>	600			ns
Setup Time (Start Condition)	$t_4$	600			ns
SDA, SCLK Rise Time	t <sub>6</sub>			300	ns
SDA, SCLK Fall Time	t <sub>7</sub>			300	ns
Setup Time (Stop Condition)	t <sub>8</sub>	600			ns
SDA Setup Time (data input)	t <sub>5</sub>	100			ns
SDA Hold Time (input/output)	t <sub>9</sub>	0			ns
SDA Valid Time (data/ACK output)	t <sub>10</sub>			900	ns
Pulse width of spikes that will be suppressed	t <sub>ps</sub>	0		5	ns



# 3-WIRE (SPI) CONTROL MODE

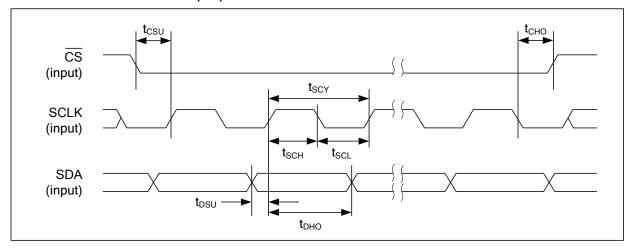


Figure 7 Control Interface Timing - 3-wire (SPI) Control Mode (Write Cycle)

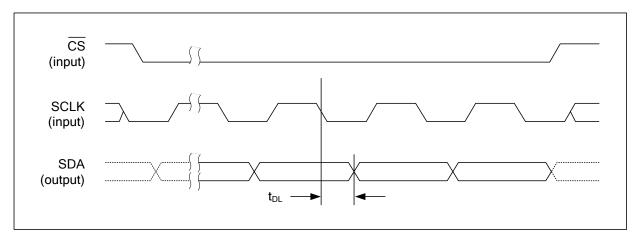


Figure 8 Control Interface Timing - 3-wire (SPI) Control Mode (Read Cycle)

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
CS falling edge to SCLK rising edge	t <sub>csu</sub>	40			ns
SCLK falling edge to CS rising edge	t <sub>cho</sub>	10			ns
SCLK pulse cycle time	t <sub>SCY</sub>	200			ns
SCLK pulse width low	t <sub>SCL</sub>	80			ns
SCLK pulse width high	t <sub>SCH</sub>	80			ns
SDA to SCLK set-up time	t <sub>DSU</sub>	40			ns
SDA to SCLK hold time	$t_{DHO}$	10			ns
Pulse width of spikes that will be suppressed	$t_ps$	0		5	ns
SCLK falling edge to SDA output transition	t <sub>DL</sub>			40	ns



# 4-WIRE (SPI) CONTROL MODE

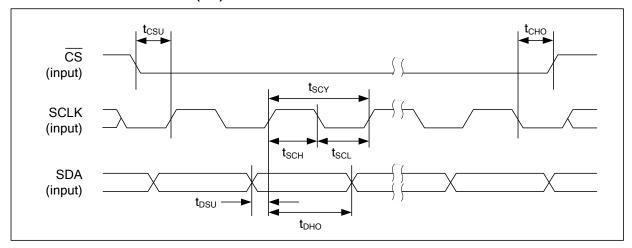


Figure 9 Control Interface Timing - 4-wire (SPI) Control Mode (Write Cycle)

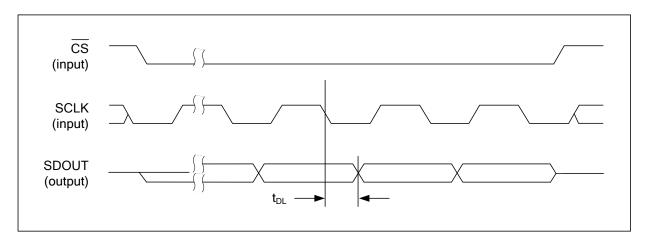


Figure 10 Control Interface Timing - 4-wire (SPI) Control Mode (Read Cycle)

#### **Test Conditions**

The following timing information is valid across the full range of recommended operating conditions.

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT
CS falling edge to SCLK rising edge	t <sub>CSU</sub>	40			ns
SCLK falling edge to CS rising edge	t <sub>сно</sub>	10			ns
SCLK pulse cycle time	t <sub>SCY</sub>	200			ns
SCLK pulse width low	t <sub>SCL</sub>	80			ns
SCLK pulse width high	t <sub>scн</sub>	80			ns
SDA to SCLK set-up time	t <sub>DSU</sub>	40			ns
SDA to SCLK hold time	$t_{DHO}$	10			ns
Pulse width of spikes that will be suppressed	$t_{ps}$	0		5	ns
SCLK falling edge to SDOUT transition	t <sub>DL</sub>			40	ns



# **POWER ON RESET TIMING**

The WM8963 includes an internal Power-On-Reset (POR) circuit, which is used to reset the digital logic into a default state after power up. The POR circuit is powered from AVDD and monitors DCVDD. The internal POR signal is asserted low when AVDD and DCVDD are below minimum thresholds.

The specific behaviour of the circuit will vary, depending on the relative timing of the supply voltages. Typical scenarios are illustrated in Figure 11 and Figure 12.

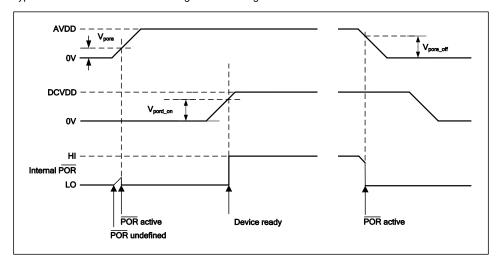


Figure 11 Power On Reset Timing - AVDD enabled first

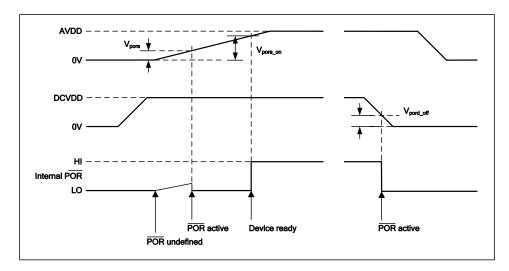


Figure 12 Power On Reset Timing - DCVDD enabled first



The POR signal is undefined until AVDD has exceeded the minimum threshold,  $V_{pora}$  Once this threshold has been exceeded, POR is asserted low and the chip is held in reset. In this condition, all writes to the control interface are ignored. Once AVDD and DCVDD have reached their respective power on thresholds, POR is released high, all registers are in their default state, and writes to the control interface may take place.

Note that a minimum power-on reset period, T<sub>POR</sub>, applies even if AVDD and DCVDD have zero rise time. (This specification is guaranteed by design rather than test.)

On power down, POR is asserted low when any of AVDD or DCVDD falls below their respective power-down thresholds.

Typical Power-On Reset parameters for the WM8963 are defined in Table 1.

SYMBOL	DESCRIPTION	TYP	UNIT
$V_{pora}$	AVDD threshold below which POR is undefined	0.5	V
$V_{pora\_on}$	Power-On threshold (AVDD)	1.1	V
$V_{pora\_off}$	Power-Off threshold (AVDD)	1.1	V
$V_{pord\_on}$	Power-On threshold (DCVDD)	0.9	V
$V_{pord\_off}$	Power-Off threshold (DCVDD)	0.65	V
$T_POR$	Minimum Power-On Reset period	9.5	μS

Table 1 Typical Power-On Reset Parameters

#### Notes:

- If AVDD and DCVDD suffer a brown-out (i.e. drop below the minimum recommended operating level but do not go below V<sub>pora\_off</sub> or V<sub>pord\_off</sub>) then the chip does not reset and resumes normal operation when the voltage is back to the recommended level again.
- The chip enters reset at power down when AVDD or DCVDD falls below V<sub>pora\_off</sub> or V<sub>pord\_off</sub>. This
  may be important if the supply is turned on and off frequently by a power management system.
- 3. The minimum  $T_{POR}$  period is maintained even if DCVDD and AVDD have zero rise time. This specification is guaranteed by design rather than test.



# DEVICE DESCRIPTION INTRODUCTION

The WM8963 is a low power audio CODEC offering a combination of high quality audio, advanced features, low power and small size. These characteristics make it ideal for portable digital audio applications with stereo speaker and headphone outputs such as games consoles, portable media players and multimedia phones.

A flexible input configuration supports a single-ended stereo microphone interface and a digital microphone interface. A boost amplifier is available for additional gain on the analogue microphone inputs. A programmable gain amplifier (PGA) with an automatic level control (ALC) function can be used to maintain a constant microphone recording volume.

Stereo class D speaker drivers can provide up to 2W per channel into  $4\Omega$  BTL loads. It is also possible to configure the speaker drivers as a mono output, giving enhanced performance.

Highly flexible output speaker boost settings provide fully internal level-shifting of analogue output signals, allowing speaker output power to be maximised while minimising other analogue supply currents, and requiring no additional components.

A dual mode (Level Shifting or Inverting Mode) charge pump generates split supplies for the headphone output amplifiers allowing these to be ground referenced.

A DC servo to remove offsets from the headphone outputs, low leakage and a user controlled power-up/power-down Control Sequencer provides powerful pop and click suppression mechanisms which enable direct battery connection. These anti-pop/click mechanisms, and no requirement for any external DC blocking capacitors to the headphone, results in a reduced external component count and reduced power consumption in portable battery-powered applications.

The hi-fi quality stereo ADC and DAC uses a 24-bit, low-order over-sampling architecture to deliver optimum performance. ADC and DAC operate at the same sample rate.

The integrated audio enhancement DSP provides powerful benefits in audio processing. Virtual Surround Sound (VSS) widens the stereo speaker audio image, and ReTune<sup>TM</sup> can be used to flatten the frequency response of an external speaker. The Multi-band Compressor (MBC) can maximize the loudness of an audio signal, without overdriving the speaker. Further audio enhancements are provided in a fixed function, configurable DSP; these include 3D widening for recording, a 5-band parametric EQ, and a Dynamic Range Controller.

The WM8963 has a highly flexible digital audio interface, supporting a number of protocols, including I2S, DSP, MSB-first left/right justified, and can operate in master or slave modes. PCM operation is supported in the DSP mode. A-law and  $\mu$ -law companding are also supported. Time division multiplexing (TDM) is available to allow multiple devices to stream data simultaneously on the same bus, saving space and power.

The internal system clock (SYSCLK) can be derived from an external clock input, or from the integrated crystal oscillator. A Frequency Locked Loop (FLL) is available to support flexible clocking configurations. All MCLK frequencies typically used in portable systems are supported for sample rates between 8kHz and 96kHz. The ADC and DAC must be configured to operate at the same sample rate. A flexible switching clock for the class D speaker drivers (synchronous with the audio DSP clocks for best performance) is also derived from SYSCLK.

The WM8963 can generate outputs from the FLL or crystal oscillator, to provide clocking for external circuits. General purpose output functions (eg. clock, interrupt, and status flags) are also supported on up to three GPIO pins.

To allow full software control over all its features, the WM8963 supports 2-wire (I2C) and 3- or 4-wire (SPI) serial control interface modes, with full read-back capability on all registers. The WM8963 is fully compatible with, and an ideal partner to, a wide range of industry standard microprocessors, controllers and DSPs. Unused functions can be disabled via software to save power, while low leakage currents extend standby and off time in portable battery-powered applications.



#### **INPUT SIGNAL PATH**

The WM8963 has many analogue input channels, configurable in any combination of up to eight mono or four stereo inputs.

Any of the analogue inputs may be connected to the input PGA on the associated left or right channel. (Note that only one analogue input can be connected to the PGA at any time; the PGA does not perform any signal mixing.)

The left and right analogue inputs IN2 and IN3 can be connected to the input boost mixer on the associated left or right channel, bypassing the input PGA.

Note that the input signal path audio performance is affected by the choice of signal path. Best performance is achieved using analogue inputs IN2 or IN3 connected directly to the input boost mixer. The performance of the input signal paths are ranked as described in the list below (best performance first).

- IN2 or IN3 connected directly to the input boost mixer
- IN1 or IN4 connected via the input PGA
- IN2 or IN3 connected via the input PGA

The left and right analogue inputs IN4 can be connected directly to the output signal mixers, which drive the headphone or speaker outputs.

The input signal paths and the control registers are shown in Figure 13.

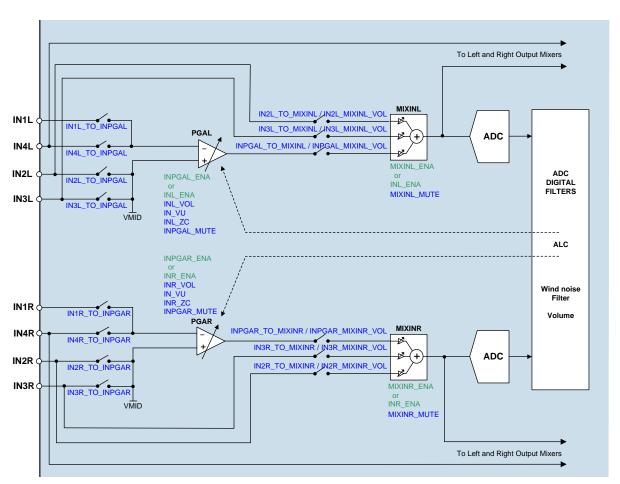


Figure 13 Analogue Input Signal Path



#### MICROPHONE INPUT CONNECTION

The WM8963 supports analogue and digital microphone input. Refer to the "Digital Microphone Interface" section for details of the digital microphone input.

The input PGAs use single-ended or pseudo-differential connections, depending on the selected input pin. A microphone bias generator is provided, suitable for powering electret condenser microphones.

Single-ended analogue microphone input using IN1L, IN1R, IN4L or IN4R is configured as shown in Figure 14.

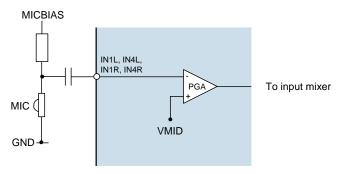


Figure 14 Microphone Input IN1 or IN4

Pseudo-differential microphone input, using IN2L, IN2R, IN3L or IN3R as an input to the PGA, is configured as shown in Figure 15. The inverting (or 'noisy ground') signal is connected to the respective IN1 pin (IN1L or IN1R), using an external capacitor, as shown.

When IN2L, IN2R, IN3L or IN3R is selected as an input to the PGA (using the register bits described in Table 5), the respective IN1 pin (IN1L or IN1R) is automatically connected to the PGA in order to support the capacitor requirement described above.

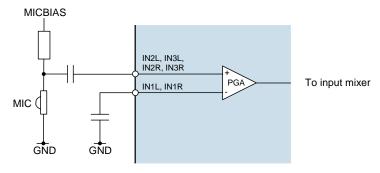


Figure 15 Microphone Input IN2 or IN3

#### **LINE INPUT CONNECTION**

Single-ended line inputs may be connected to the left or right channel analogue inputs IN1, IN2, IN3 or IN4, and routed to the input mixers or output signal paths as illustrated in Figure 13.

Note that, if IN2L, IN2R, IN3L or IN3R is selected as an input to the PGA, then the PGA is automatically configured in pseudo-differential mode, and the respective IN1 pin (IN1L or IN1R) must be connected to ground via an external capacitor, as shown in Figure 15.



#### MICROPHONE BIAS CONTROL

The WM8963 incorporates a MICBIAS generator, which provides low noise reference voltages suitable for biasing electret condenser (ECM) type microphones via an external resistor. The input connection to the MICBIAS generator is via the MICVDD pin.

The WM8963 also provides an LDO regulator, which can be used to generate a suitable MICVDD supply for the MICBIAS generator. The LDO supply is provided via the LDOVDD pin. The LDO input is suitable for direct connection to a battery.

The LDO and MICBIAS circuits are illustrated in Figure 16. Refer to the "Applications Information" section for the recommended external connections and components.

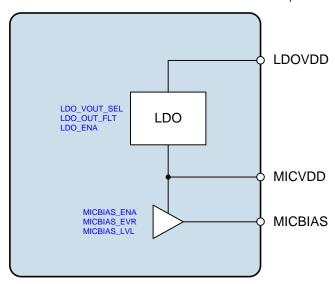


Figure 16 LDO and MICBIAS

The LDO is enabled using the LDO\_ENA register bit.

When the LDO is enabled, the MICVDD voltage can be selected using the LDO\_VOUT\_SEL bit. The LDOVDD supply voltage must be at least 250mV higher than the desired MICVDD output voltage.

When the LDO is disabled, the MICVDD pin can be configured to be floating or to be actively discharged. This is selected using the LDO\_OUT\_FLT register bit.

When the LDO is used to generate the MICVDD supply, there should be no external connections to the MICVDD pin. Note that, in this configuration, the MICVDD must not be left floating at any time; the LDO OUT FLT register bit should be set to '0' in this case.

If the LDO is not used, then the MICVDD and LDOVDD pins should be tied together, and connected to a suitable MICVDD supply. Under these conditions, the default LDO register settings must be used (LDO\_ENA=0, LDO\_OUT\_FLT=1).

The MICBIAS generator is powered from MICVDD, which can be supplied internally or externally, as described above.

The MICBIAS output is enabled using the MICBIAS\_ENA register bit. The MICBIAS voltage is selected using the MICBIAS\_LVL and MICBIAS\_EVR register fields, as detailed in Table 2.

The MICVDD voltage must be at least 300mV higher than the desired MICBIAS output voltage. If the LDO is used to generate the MICVDD supply, the minimum MICVDD requirement can be reduced to 250mV above the desired MICBIAS output voltage.

Note that an external decoupling capacitor is required on the MICBIAS output. A suitable capacitor must be connected whenever the MICBIAS output is enabled. Additional filtering of the MICBIAS output, to reduce noise and interference, may be implemented as described in the "Applications Information" section, if required.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	1	MICBIAS_ENA	0	Microphone Bias Enable 0 = OFF (high impedance output) 1 = ON
R29 (1Dh) Micbias	1:0	MICBIAS_EVR [1:0]	00	Microphone Bias Voltage Control 00 = Controlled by MICBIAS_LVL 10 = 1.34 x AVDD (approx.) X1 = 1.63 x AVDD (approx.)
R48 (30h) MICBIAS	0	MICBIAS_LVL	1	Microphone Bias Voltage Control 0 = 0.828 x AVDD (approx.) 1 = 1.156 x AVDD (approx.) Only valid when MICBIAS_EVR=00. In other cases, the Microphone Bias voltage is controlled by MICBIAS_EVR alone.
R176 (B0h) LDO	2	LDO_VOUT_SEL	0	LDO output voltage level setting.  0 = 1.36 x AVDD  1 = 1.78 x AVDD
	1	LDO_OUT_FLT	1	LDO Output Float setting, effective when LDO_ENA==0 0 = LDO output is clamped to ground 1 = LDO output is floating (default)
	0	LDO_ENA	0	LDO Enable 0 = Disabled (default) 1 = Enabled

**Table 2 Microphone Bias Control** 

Note that the maximum source current capability for MICBIAS is 2.0mA. The external biasing resistance must be large enough to limit the MICBIAS current to 2.0mA across the full microphone impedance range.

## **MICBIAS CURRENT DETECT**

A MICBIAS Current Detect function is provided for external accessory detection. This is provided in order to detect the insertion/removal of a microphone or the pressing/releasing of the microphone 'hook' switch; these events will cause a significant change in MICBIAS current flow, which can be detected and used to generate a signal to the host processor.

The MICBIAS current detect function is enabled by setting the MICDET\_ENA register bit. When this function is enabled, two current thresholds can be defined, using the MICDET\_THR and MICSHORT\_THR registers. When a change in MICBIAS current which crosses either threshold is detected, then an interrupt event can be generated. In a typical application, accessory insertion would be detected when the MICBIAS current exceeds MICDET\_THR, and microphone hookswitch operation would be detected when the MICBIAS current exceeds MICSHORT\_THR.

The current detect threshold functions are both inputs to the Interrupt control circuit and can be used to trigger an Interrupt event when either threshold is crossed. The status flags MICDET\_STS or MICSHORT\_STS are asserted whenever the relevant current threshold is exceeded.

The current detect thresholds are enabled and controlled using the registers described in Table 3 Performance parameters for this circuit block can be found in the "Electrical Characteristics" section.

Filtering is also provided in both current detect circuits to improve reliability in conditions where AC current spikes are present due to ambient noise conditions. This feature is described in the following section. Further guidance on the usage of the MICBIAS current monitoring features is also described in the following pages.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R48 (30h) Additional Control (4)	14:12	MICDET_THR [2:0]	000	MICBIAS Current Detect Threshold (AVDD = 1.8V) 000 = 64uA 001 = 166uA 010 = 358uA 011 = 461uA 100 = 563uA 101 = 666uA 110 = 858uA 111 = 960uA Note that the value scales with AVDD. The value quoted is correct for AVDD=1.8V.
	11:10	MICSHORT_THR [1:0]	00	MICBIAS Short Circuit Threshold (AVDD = 1.8V) 00 = 510uA 01 = 653uA 10 = 1040uA 11 = 1200uA Note that the value scales with AVDD. The value quoted is correct for AVDD=1.8V.
	9	MICDET_ENA	0	MICBIAS Current and Short Circuit Detect Enable 0 = Disabled 1 = Enabled
	7	MICDET_STS	0	MICBIAS Current Detection status  0 = Current Detect threshold not exceeded  1 = Current Detect threshold exceeded
	6	MICSHORT_STS	0	MICBIAS Short Circuit status  0 = Short Circuit threshold not exceeded  1 = Short Circuit threshold exceeded

**Table 3 MICBIAS Current Detect** 



### MICBIAS CURRENT DETECT FILTERING

The function of the filtering is to ensure that AC current spikes caused by ambient noise conditions near the microphone do not lead to incorrect signalling of the microphone insertion/removal status or the microphone hookswitch status.

Digital filtering of the hookswitch status ensures that the MICBIAS Short Circuit detection event is only signalled if the MICSHORT THR threshold condition has been met for 10 consecutive measurements.

In a typical application, microphone insertion would be detected when the MICBIAS current exceeds the Current Detect threshold set by MICDET\_THR.

When the MICD\_IRQ\_POL interrupt polarity bit is set to 0, then microphone insertion detection will cause the MICD\_EINT interrupt status register to be set. (See "Interrupts" for details of these register bits.)

For detection of microphone removal, the MICD\_IRQ\_POL bit should be set to 1. When the MICD\_IRQ\_POL interrupt polarity bit is set to 1, then microphone removal detection will cause the MICD\_EINT interrupt status register to be set.

The detection of these events is bandwidth limited for best noise rejection, and is subject to detection delay time  $t_{DET}$ , as specified in the "Electrical Characteristics" section. Provided that the MICDET\_THR field has been set appropriately, each insertion or removal event is guaranteed to be detected within the delay time  $t_{DET}$ .

It is likely that the microphone socket contacts will have mechanical "bounce" when a microphone is inserted or removed, and hence the resultant control signal will not be a clean logic level transition. Since  $t_{\text{DET}}$  has a range of values, it is possible that the interrupt will be generated before the mechanical "bounce" has ceased. Hence after a mic insertion or removal has been detected, a time delay should be applied before re-configuring the MICD\_IRQ\_POL bit. The maximum possible mechanical bounce times for mic insertion and removal must be understood by the software programmer.

Microphone hook switch operation is detected when the MICBIAS current exceeds the Short Circuit Detect threshold set by MICSHORT\_THR. Using the digital filtering, the hook switch detection event is only signalled if the MICSHORT\_THR threshold condition has been met for 10 consecutive measurements.

When the MICSCD\_IRQ\_POL interrupt polarity bit is set to 0, then hook switch operation will cause the MICSCD\_EINT interrupt status register to be set. (See "Interrupts" for details of these register bits.)

For detection of microphone removal, the MICSCD\_IRQ\_POL bit should be set to 1. When the MICSCD\_IRQ\_POL interrupt polarity bit is set to 1, then hook switch release will cause the MICSCD\_EINT interrupt status register to be set.

The hook switch detection measurement frequency and the detection delay time  $t_{SHORT}$  are detailed in the "Electrical Characteristics" section.

The WM8963 Interrupt function is described in the "Interrupts" section. Example control sequences for configuring the Interrupts functions for MICBIAS current detection events are described in the "Applications Information" section.

A clock is required for the digital filtering function. This requires:

- MCLK is present or the FLL is selected as the SYSCLK source in free-running mode
- SYSCLK\_ENA = 1

Any MICBIAS Current Detect event (accessory insertion/removal or hookswitch press/release) which happens while one or more of the clocking criteria is not satisfied (for example during a low power mode where the CPU has disabled MCLK) will still be detected, but only after the clocking conditions are met. An example is illustrated in Figure 17, where the mic is inserted while MCLK is stopped.

Note that the interrupts and digital filtering can be supported in the absence of an external clock by using the FLL in free-running mode and selecting the FLL as the clock source, as described in "Clocking and Sample Rates".



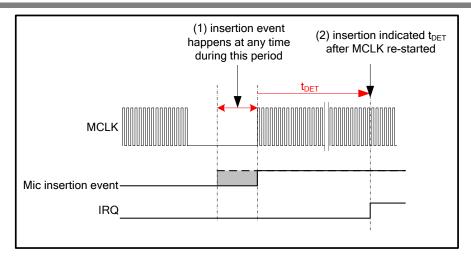


Figure 17 MICBIAS Detection Events without MCLK

### MICROPHONE HOOK SWITCH DETECTION

The possibility of spurious hook switch interrupts due to ambient noise conditions can be removed by detailed understanding of microphone behaviour under extremely high sound pressure levels or during mechanical shock, and by correct selection of the MICBIAS resistor value; these factors will affect the level of the MICBIAS AC current spikes.

In applications where the Current Detect threshold is close to the level of the current spikes, the probability of false detections is reduced by the digital filtering described above.

Note that the filtering algorithm provides only limited rejection of very high current spikes at frequencies less than or equal to the hook switch detect measurement frequency, or at frequencies equal to harmonics of the hook switch detect measurement frequency.

The MICBIAS Hook Switch detection filtering is illustrated in Figure 18. Example control sequences for configuring the Interrupts functions for MICBIAS current detection events are described in the ""Applications Information" section.

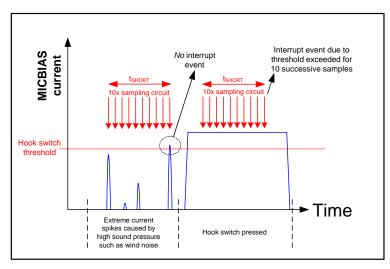


Figure 18 MICBIAS Hook Switch Detection Filtering



## **INPUT PGA ENABLE**

The input PGAs (Programmable Gain Amplifiers) are enabled using register bits INL\_ENA, INR\_ENA, INPGAR\_ENA and INPGAL\_ENA, as described in Table 4.

These PGAs provide adjustable gain control from -23.25dB to +24.0dB in 0.75dB increments as shown in Table 7.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h)	5	INL_ENA	0	Left Input PGA and Mixer Enable.
Pwr Mgmt (1)				0 = Disabled
				1 = Enabled
	4	INR_ENA	0	Right Input PGA and Mixer Enable.
				0 = Disabled
				1 = Enabled
R37 (25h)	4	INPGAL_ENA	0	Left Input PGA Enable.
Left Input PGA				0 = Disabled
Control				1 = Enabled
				Note that the Left Input PGA is also
				enabled when INL_ENA is set
R38 (26h)	4	INPGAR_ENA	0	Right Input PGA Enable
Right Input				0 = Disabled
PGA Control				1 = Enabled
				Note that the Right Input PGA is
				also enabled when INR_ENA is set

Table 4 Input PGA Enable

To enable the input PGAs, the reference voltage VMID and the bias current must also be enabled. See "Reference Voltages and Bias Control" for details of the associated controls VMID\_SEL and BIAS\_ENA.



## **INPUT PGA CONFIGURATION**

Each of the PGAs operates in a single-ended mode. Configuration of the PGA inputs to the WM8963 input pins is controlled using the register bits shown in Table 5.

The maximum available attenuation on any of these input paths is achieved by using register bits shown in Table 5 to disconnect the input pins from the applicable PGA.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R37 (25h) Left input PGA control	3	IN1L_TO_INPGAL	1	Selects the IN1L pin as an input to the Left PGA 0 = Disabled 1 = Enabled
	2	IN2L_TO_INPGAL	0	Selects the IN2L pin as an input to the Left PGA 0 = Disabled 1 = Enabled
	1	IN3L_TO_INPGAL	0	Selects the IN3L pin as an input to the Left PGA 0 = Disabled 1 = Enabled
	0	IN4L_TO_INPGAL	0	Selects the IN4L pin as an input to the Left PGA 0 = Disabled 1 = Enabled
R38 (26h) Right input PGA control	3	IN1R_TO_INPGA R	1	Selects the IN1R pin as an input to the Right PGA 0 = Disabled 1 = Enabled
	2	IN2R_TO_INPGA R	0	Selects the IN2R pin as an input to the Right PGA 0 = Disabled 1 = Enabled
	1	IN3R_TO_INPGA R	0	Selects the IN3R pin as an input to the Right PGA 0 = Disabled 1 = Enabled
	0	IN4R_TO_INPGA R	0	Selects the IN4R pin as an input to the Right PGA 0 = Disabled 1 = Enabled

**Table 5 Input PGA Configuration** 

### **INPUT PGA VOLUME CONTROL**

Each of the two Input PGAs has an independently controlled gain range of -23.25dB to +24dB in 0.75dB steps. Each Input PGA can be independently muted using the PGA mute bits as described in Table 6, with maximum mute attenuation achieved by simultaneously disabling the corresponding inputs described in Table 5.

To prevent "zipper noise", a zero-cross function is provided on the input PGAs. When this feature is enabled, volume updates will not take place until a zero-crossing is detected. In the case of a long period without zero-crossings, a timeout function is provided. When the zero-cross function is enabled, the volume will update after the timeout period if no earlier zero-cross has occurred. The timeout clock is enabled using TOCLK\_ENA, the timeout period is set by TOCLK\_DIV. See "Clocking and Sample Rates" for more information on these fields.



The IN\_VU bits control the loading of the input PGA volume data and the PGA mute functions. When IN\_VU is set to 0, the PGA volume data will be loaded into the respective control register, but will not actually change the gain setting. The INL and INR volume settings are both updated when a 1 is written to either IN\_VU bit. Similarly, the INPGAL\_MUTE and INPGAR\_MUTE settings are only effective when a 1 is written to either IN\_VU bit. This makes it possible to update the gain/mute of the left and right signal paths simultaneously.

Note that the Input PGA control has a dependency on the correct sequencing of the ALC and ADC Enable control registers; if the correct sequences are not followed, then the Input PGA gain settings may become fixed. See "Automatic Level Control (ALC)" for further details.

The Input PGA Volume Control register fields are described in Table 6 and Table 7.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R0 (0h) Left input volume	8	IN_VU	N/A	Input PGA Volume and Mute Update Writing a 1 to this bit will cause the INL and INR volume and mute settings to be updated simultaneously
	7	INPGAL_M UTE	1	Left input PGA Mute 0 = Unmuted 1 = Muted
	6	INL_ZC	0	INL PGA Zero Cross Detector  0 = Change gain immediately  1 = Change gain on zero cross only
	5:0	INL_VOL [5:0]	1Fh	Left input PGA Volume -23.25dB to +24.00dB in 0.75dB steps.  00h = -23.25dB 01h = -22.50dB 02h = -21.75dB(0.75dB steps) 1Fh = 0dB 3Fh = 24dB See Table 7 for volume range.
R1 (1h) Right input volume	8	IN_VU	N/A	Input PGA Volume and Mute Update Writing a 1 to this bit will cause the INL and INR volume and mute settings to be updated simultaneously
	7	INPGAR_M UTE	1	Right input PGA Mute 0 = Unmuted 1 = Muted
	6	INR_ZC	0	INR PGA Zero Cross Detector  0 = Change gain immediately  1 = Change gain on zero cross only
	5:0	INR_VOL [5:0]	1Fh	Right input PGA Volume -23.25dB to +24.00dB in 0.75dB steps.  00h = -23.25dB  01h = -22.50dB  02h = -21.75dB (0.75dB steps)  1Fh = 0dB   3Fh = 24dB  See Table 7 for volume range.

**Table 6 Input PGA Volume Control** 





INL_VOL[5:0], INR_VOL[5:0]	VOLUME (dB)	INL_VOL[5:0], INR_VOL[5:0]	VOLUME (dB)
00h	-23.25	20h	0.75
01h	-22.50	21h	1.50
02h	-21.75	22h	2.25
03h	-21.00	23h	3.00
04h	-20.25	24h	3.75
05h	-19.50	25h	4.50
06h	-18.75	26h	5.25
07h	-18.00	27h	6.00
08h	-17.25	28h	6.75
09h	-16.50	29h	7.50
0Ah	-15.75	2Ah	8.25
0Bh	-15.00	2Bh	9.00
0Ch	-14.25	2Ch	9.75
0Dh	-13.50	2Dh	10.50
0Eh	-12.75	2Eh	11.25
0Fh	-12.00	2Fh	12.00
10h	-11.25	30h	12.75
11h	-10.50	31h	13.50
12h	-9.75	32h	14.25
13h	-9.00	33h	15.00
14h	-8.25	34h	15.75
15h	-7.50	35h	16.50
16h	-6.75	36h	17.25
17h	-6.00	37h	18.00
18h	-5.25	38h	18.75
19h	-4.50	39h	19.50
1Ah	-3.75	3Ah	20.25
1Bh	-3.00	3Bh	21.00
1Ch	-2.25	3Ch	21.75
1Dh	-1.50	3Dh	22.50
1Eh	-0.75	3Eh	23.25
1Fh	0.00	3Fh	24.00

Table 7 Input PGA Volume Range



### **INPUT MIXER ENABLE**

The WM8963 has two analogue input mixers, each of which has an integrated boost function that allows the Input PGA signal, and IN2/IN3 'direct' inputs, to be boosted before being sent to the ADCs. These boost mixers have a gain range of 0dB to 29dB, as well as Mute.

The input mixers MIXINL and MIXINR are enabled by the MIXINL\_ENA and MIXINR\_ENA register bits, as described in Table 8. Note that these input mixers are also controlled by INL\_ENA and INR\_ENA, as described in Table 4.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R31 (1Fh) Input mixer control (1)	1	MIXINL_ENA	0	Left Input Mixer Enable  0 = Disabled  1 = Enabled  Note that the Left Input Mixer is also enabled when INL_ENA is set
	0	MIXINR_ENA	0	Right Input Mixer Enable 0 = Disabled 1 = Enabled Note that the Right Input Mixer is also enabled when INR_ENA is set

**Table 8 Input Boost-Mixer Enable** 

### INPUT MIXER CONFIGURATION AND VOLUME CONTROL

The analogue input mixers MIXINL and MIXINR can be configured to take input from the input PGAs and also directly from the IN2 and IN3 input pins.

The Input Boost Mixer configuration and volume controls are described in Table 9 for the Left input boost-mixer (MIXINL) and Table 10 for the Right input boost-mixer (MIXINR).

Note that the available mixer gain settings for the IN2 and IN3 paths are different to the input PGA signal paths. The IN2 and IN3 signal paths can be controlled from -12dB to +6dB. The input PGA signal paths can be controlled from 0dB to +29dB.

To prevent pop noise, it is recommended that gain and mute controls for the input boost mixers are not modified while the signal paths are active. If volume control is required on these signal paths, it is recommended that this is implemented using the input PGA volume controls or the ADC volume controls. The ADC volume controls are described in the "Analogue To Digital Converter (ADC)" section.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R31 (1Fh) Input mixer control (1)	3	MIXINL_MUTE	0	Left input boost-mixer mute 0 = Un-mute 1 = Mute
R32 (20h) Left input mixer volume	8:6	IN2L_MIXINL_VOL [2:0]	101	Left input IN2L to Left input Boost-Mixer Gain 000 = -12dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
	5:3	INPGAL_MIXINL_VOL [5:3]	000	Left input PGA to Left input Boost-Mixer Gain 000 = 0dB 001 = +6dB 010 = +13dB 011 = +18dB 100 = +20dB 101 = +24dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				110 = +27dB 111 = +29dB
	2:0	IN3L_MIXINL_VOL [2:0]	101	Left input IN3L to Left input Boost-Mixer Gain 000 = -12dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
R34 (22h) Input mixer control (2)	5	IN2L_TO_MIXINL	0	Left Input IN2L to Left input Boost-Mixer Select 0 = Disabled 1 = Enabled
	4	IN3L_TO_MIXINL	0	Left Input IN3L to Left input Boost-Mixer Select 0 = Disabled 1 = Enabled
	3	INPGAL_TO_MIXINL	1	Left Input PGA to Left input Boost-Mixer Select 0 = Disabled 1 = Enabled

Table 9 Left Input Mixer (MIXINL) Volume Control

REGISTER ADDRESS	ВІТ	LABEL	DEFAULT	DESCRIPTION
R31 (1Fh) Input mixer control (1)	2	MIXINR_MUTE	0	Right input boost-mixer mute 0 = Un-mute 1 = Mute
R33 (21h) Right input mixer volume	8:6	IN2R_MIXINR_VOL [2:0]	101	Right input IN2R to Right input Boost-Mixer Gain 000 = -12dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
	5:3	INPGAR_MIXINR_VOL [5:3]	000	Right input PGA to Right input Boost-Mixer Gain 000 = 0dB 001 = +6dB 010 = +13dB 011 = +18dB 100 = +20dB 101 = +24dB 110 = +27dB 111 = +29dB
	2:0	IN3R_MIXINR_VOL [2:0]	101	Right input IN3R to Right input Boost-Mixer Gain 000 = -12dB 001 = -12dB 010 = -9dB 011 = -6dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
R34 (22h) Input mixer control (2)	2	IN2R_TO_MIXINR	0	Right input IN2R to Right input Boost-Mixer Select 0 = Disabled 1 = Enabled
	1	IN3R_TO_MIXINR	0	Right input IN3R to Right input Boost-Mixer Select 0 = Disabled 1 = Enabled
	0	INPGAR_TO_MIXINR	1	Right input PGA to Right input Boost-Mixer Select 0 = Disabled 1 = Enabled

Table 10 Right Input Mixer (MIXINR) Volume Control

# **AUTOMATIC LEVEL CONTROL (ALC)**

The WM8963 has an automatic PGA gain control circuit that keeps a constant recording volume irrespective of the input signal level. This is achieved by continuously adjusting the input PGA gain so that the signal level at the ADC input remains constant.

A digital peak detector monitors the ADC output and changes the PGA gain if necessary.

The ALC has two modes selected by the ALC\_MODE register. See "Limiter Mode" for further details on the ALC Modes.

The ALC also has a Noise Gate function, which provides additional control of low level input signals. This means that the signal path is quiet when no signal is present, giving an improvement in background noise level.

The Automatic Level Control (ALC) can be enabled on either the left channel, or the right channel, or on both channels, using the ALCL\_ENA and ALCR\_ENA fields respectively. The monitoring of the signal is performed at the ADC. Note that the ALC (Left) function requires the Left and Right ADCs to be enabled; the ALC (Right) function only requires the Right ADC to be enabled.

Note that, when disabling the input signal path, the ALC must be disabled before the respective ADCs are disabled. If this sequence is not followed, then the Input PGA gain settings may become fixed.

The ALC should not be enabled when using the IN2 or IN3 inputs connected directly to the input boost mixer; this is because these paths will bypass the PGAs where the ALC gain adjustment is performed.

ALC can be set to Active Mode or to Monitor Mode. When ALC is in Active Mode (ALC\_INACTIVE\_ENA = 0), the gain of the analogue PGAs is controlled by the ALC bit settings, and not by the INL\_VOL or the INR\_VOL fields. When ALC is in Monitor Mode (ALC\_INACTIVE\_ENA=1), ALC monitors the signal levels without doing any of the level control that it would otherwise perform. Details on readback of the ALC status are in the "ALC Status Readback" section.

When the ALC is enabled, a target level for the analogue input signal at the ADC is determined by the ALC\_LVL setting. There are two ranges (high or low) from which the ALC\_LVL target value can be taken. The target values in each of these ranges are shown in Table 12. Two ranges can be selected using ALC\_LVL\_MODE. Set ALC\_LVL\_MODE to 0 to use the low range (-28.5dBFS to -6dBFS), or set ALC\_LVL\_MODE to 1 to use the higher range (-22.5dBFS to -1.5dBFS).





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R17 (11h) ALC1	10	ALC_INACTIVE_ENA	0	Select whether the ALC is in Active Mode (that is, ALC is controlling the PGA gain) or in Monitor Mode (the analogue controls are disabled). Note that at least one of ALCL_ENA and ALCR_ENA must also be enabled 0 = ALC is in Active Mode 1 = ALC is in Monitor Mode
	9	ALC_LVL_MODE	0	Select the range of the ALC target level.  0 = -28.5dBFS to -6dBFS in 1.5dB steps  1 = -22.5dBFS to -1.5dBFS in 1.5dB steps
	8	ALCL_ENA	0	Select ALC on the Left channel 0 = Disabled (PGA gain set by INL_VOL) 1 = Enabled Note that in stereo mode, the left and right PGA volumes, and left and right boost mixer volumes, must be the same before setting ALCL_ENA = 1 and ALCR_ENA = 1
	7	ALCR_ENA	0	Select ALC on the Right channel 0 = Disabled (PGA gain set by INR_VOL) 1 = Enabled Note that in stereo mode, the left and right PGA volumes, and left and right boost mixer volumes, must be the same before setting ALCL_ENA = 1 and ALCR_ENA = 1
	3:0	ALC_LVL [3:0]	1011	Set the Target signal level at the ADC input.  Note that the target level is also determined by ALC_LVL_MODE.  ALC_LVL_MODE = 0 0000 = -28.5dBFS 0001 = -27.0dBFSin 1.5dB steps to 1111 = -6dBFS  ALC_LVL_MODE = 1 0000 = -22.5dBFS 0001 = -21.0dBFSin 1.5dB steps to 1110 = -1.5dBFS 1111 = -1.5dBFS  See Table 12 for the range of possible values.

**Table 11 Automatic Level Control** 



ALC_LVL	ALC_LVL_MODE = 0 (dBFS)	ALC_LVL_MODE = 1 (dBFS)
0000	-28.5	-22.5
0001	-27.0	-21.0
0010	-25.5	-19.5
0011	-24.0	-18.0
0100	-22.5	-16.5
0101	-21.0	-15.0
0110	-19.5	-13.5
0111	-18.0	-12.0
1000	-16.5	-10.5
1001	-15.0	-9.0
1010	-13.5	-7.5
1011	-12.0	-6.0
1100	-10.5	-4.5
1101	-9.0	-3.0
1110	-7.5	-1.5
1111	-6.0	-1.5

**Table 12 ALC Target Level Values** 

## **LIMITER MODE**

In Normal Mode (ALC\_MODE = 0), the ALC will attempt to maintain a constant signal level by increasing or decreasing the gain of the PGA. This is illustrated in Figure 19.

In Limiter Mode (ALC\_MODE = 1), the ALC will reduce peaks that go above the threshold level, but will not increase the PGA gain beyond the starting level. (The starting level is defined as the gain setting of the PGA at the time when the ALC is enabled.) This is illustrated in Figure 20.

Note that ALC\_MODE should not be changed while the ALC is active. ALCL\_ENA and ALCR\_ENA must both be set to 0 before changing ALC\_MODE.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R19 (13h) ALC3	8	ALC_MODE	0	ALC Mode  0 = Normal ALC Mode  1 = Limiter Mode  Note that ALCL_ENA and ALCR_ENA must both be set to 0 before changing ALC_MODE, otherwise unexpected behaviour may result.

Table 13 ALC Mode Switch (ALC\_MODE)

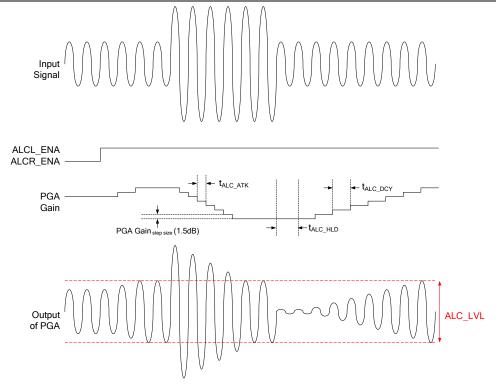


Figure 19 ALC Normal Mode Operation

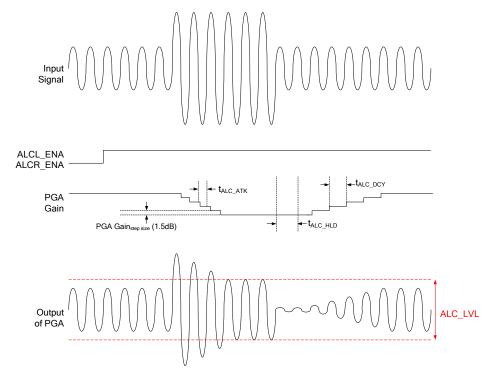


Figure 20 ALC Limiter Mode Operation



#### **ALC GAIN CONTROL**

The minimum and maximum gain applied by the ALC is set by register fields ALC\_MINGAIN and ALC\_MAXGAIN respectively. These limits can be used to alter the ALC response from that illustrated in Figure 19 and Figure 20. If the range between maximum and minimum gain is reduced, then the extent of the automatic level control is reduced.

Note that, when the ALC is first enabled, the PGA gain (in dB) must be less than the ALC\_MAXGAIN setting. The PGA gain is controlled by the INL\_VOL and INR\_VOL registers, as described in Table 6.

The minimum gain in the ALC response is set by ALC\_MINGAIN. The minimum gain limit can be used to prevent excessive attenuation of the signal path.

The maximum gain limit set by ALC\_MAXGAIN can be used to prevent quiet signals (or silence) from being excessively amplified. Note that the Noise Gate function also affects quiet signals. See the "ALC Noise Gate" section (below) for further details on the Noise Gate.

To prevent "zipper noise", a zero-cross function is provided within the ALC. When this feature is enabled, volume updates will not take place until a zero-crossing is detected. In the case of a long period without zero-crossings, a timeout function is provided. When the zero-cross function is enabled, the volume will update after the timeout period if no earlier zero-cross has occurred. The timeout clock is enabled using TOCLK\_ENA. See "Clocking and Sample Rates" for the definition of this bit. Note that the zero-cross function can be supported without TOCLK enabled, but the timeout function will not be provided in this case.

When operating in stereo, the peak detector takes the maximum of left and right channel peak values, and any new gain setting is applied equally to both left and right PGAs so that the stereo image is preserved. The input PGA and Input Mixer gain settings should be identical when entering ALC stereo mode in order for gain updates to be applied correctly.

The ALC function can also be enabled on one channel only. In this case, only one PGA is controlled by the ALC mechanism, while the other channel runs independently with its PGA gain set through the control register.

When one ALC channel is unused, the peak detector disregards that channel.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R17 (11h) ALC1	6:4	ALC_MAXGAIN [3:0]	111	Maximum ALC gain 000 = -18dB 001 = -12dB 010 = -6dB 011 = 0dB 100 = +6dB 101 = +12dB
				110 = +18dB 111 = +24dB
R18 (12h) ALC2	7	ALC_ZC	0	ALC Zero Cross Detector 0 = Change gain immediately 1 = Change gain on zero cross only
	6:4	ALC_MINGAIN [3:0]	000	Minimum ALC gain 000 = -23.25dB 001 = -17.25dB 010 = -11.25dB 011 = -5.25dB 100 = +0.75dB 101 = +6.75dB 110 = +12.75dB 111 = +18.75dB

Table 14 ALC Gain Limits



### **ALC DYNAMIC CHARACTERISTICS**

The dynamic behaviour determines how quickly the ALC responds to changing signal levels. Note that the ALC responds to the average (RMS) signal amplitude over a period of time.

The ALC\_HLD field selects a delay between the detection of a peak signal level that is below the ALC target level, and the start of the PGA gain ramping up. ALC\_HLD can be set to any of the times shown in Table 15. ALC\_HLD only affects the gain ramp-up on a low level signal. There is no delay in ramping the gain down when the signal level is above the target level. Note that it is only the start of the gain ramp-up that is affected by the ALC\_HLD setting; once the ramp-up has started, it proceeds at the pace dictated by the ALC\_DCY setting.

The ALC\_DCY field determines how quickly the ALC gain increases when the signal amplitude is low. The times specified are for the time taken per step of applied gain. The actual time taken for the recording level to return to its target level therefore depends on both the decay rate and the gain adjustment required. If the required gain change is small, then the total decay time will be shorter than when a larger gain change is required.

The ALC\_ATK field determines how quickly the ALC gain decreases when the signal amplitude is high. The times specified are for the time taken per step of applied attenuation. The actual time taken for the recording level to return to its target level therefore depends on both the attack rate and the gain adjustment required. If the required gain change is small, then the total decay time will be shorter than when a larger gain change is required.

These register fields are described in Table 15.

The SAMPLE\_RATE register field must be set correctly to ensure that the ALC attack, decay and hold times are correct for the chosen sample rate. See the "Clocking and Sample Rates" section for further details of this register.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R18 (12h)	3:0	ALC_HLD [3:0]	0000	ALC Hold time before the gain
ALC2				ramp-up starts
				0000 = 0.00ms
				0001 = 2.67ms
				0010 = 5.33ms
				0011 = 10.7ms
				0100 = 21.3ms
				0101 = 42.7ms
				0110 = 85.3ms
				0111 = 171ms
				1000 = 341ms
				1001 = 683ms
				1010 = 1.37s
				1011 = 2.73s
				1100 = 5.46s
				1101 = 10.9s
				1110 = 21.8s
				1111 = 43.7s



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R19 (13h) ALC3	7:4	ALC_DCY [3:0]	0011	Sets the Gain Decay Rate (measured in time per 1.5dB step).
				If ALC_MODE = 0 0000 = 0.41ms / step 0001 = 0.82ms / stepdoubling with each step to 1010 = 420ms / step 1011 = 840ms / step 1100 to 1111 = Reserved  If ALC_MODE = 1 0000 = 0.082ms / step 0001 = 0.164ms / stepdoubling with each step to 1010 = 83.9ms / step 1011 = 168ms / step 1100 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Gain
				Decay time is defined as for the ALC_MODE=0 case above. See Table 16 for further details.
	3:0	ALC_ATK [3:0]	0010	Sets the Gain Attack Rate (measured in time per 1.5dB step).  If ALC_MODE = 0 0000 = 0.104ms / step 0001 = 0.208ms / stepdoubling with each step to 1010 = 106ms / step 1011 to 1111 = Reserved  If ALC_MODE = 1 0000 = 0.020ms / step 0001 = 0.041ms / stepdoubling with each step to 1010 = 21.0ms / step 1011 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Gain
				Attack time is defined as for the ALC_MODE=0 case above. See Table 17 for further details.

Table 15 ALC Time Constants



ALC_DCY, ALC_NGATE_DCY	ALC_MODE = 0	ALC_MODE = 1, SAMPLE RATE ≤ 48kHz	ALC_MODE = 1, SAMPLE RATE > 48kHz
0000	0.41ms	0.082ms	0.41ms
0001	0.82ms	0.164ms	0.82ms
0010	1.64ms	0.328ms	1.64ms
0011	3.28ms	0.655ms	3.28ms
0100	6.56ms	1.31ms	6.56ms
0101	13.1ms	2.62ms	13.1ms
0110	26.2ms	5.24ms	26.2ms
0111	52.5ms	10.5ms	52.5ms
1000	105ms	21.0ms	105ms
1001	210ms	41.9ms	210ms
1010	420ms	83.9ms	420ms
1011	840ms	168ms	840ms

Table 16 ALC Decay Rate (Time per 1.5dB Gain Step)

ALC_ATK, ALC_NGATE_ATK	ALC_MODE = 0	ALC_MODE = 1, SAMPLE_RATE ≤ 48kHz	ALC_MODE = 1, SAMPLE RATE > 48kHz
0000	0.104ms	0.020ms	0.104ms
0001	0.208ms	0.041ms	0.208ms
0010	0.416ms	0.082ms	0.416ms
0011	0.832ms	0.164ms	0.832ms
0100	1.66ms	0.328ms	1.66ms
0101	3.33ms	0.655ms	3.33ms
0110	6.66ms	1.31ms	6.66ms
0111	13.3ms	2.62ms	13.3ms
1000	26.6ms	5.24ms	26.6ms
1001	53.2ms	10.5ms	53.2ms
1010	106ms	21.0ms	106ms

Table 17 ALC Attack Rate (Time per 1.5dB Gain Step)

## **PEAK LIMITER**

To prevent clipping when a large signal occurs just after a period of quiet, the ALC circuit includes a limiter function. If the ADC input signal exceeds 87.5% of full scale (–1.16dBFS), the PGA gain is ramped down at the maximum attack rate (as when ALC\_ATK = 0000), until the signal level falls below 87.5% of full scale. This function is automatically enabled whenever the ALC is in Active Mode, but has no effect when ALC is in Monitor Mode.

Note that if ALC\_ATK = 0000, then the peak limiter makes no difference to the operation of the ALC; ALC\_ATK is already at 0000 and the ALC is therefore already ramping down at its maximum rate. The Peak Limiter is designed to prevent clipping when long attack times are used.



### **ALC NOISE GATE**

To avoid 'noise pumping' when the signal is very quiet and consists mainly of noise, the ALC function has a noise gate function. This prevents noise pumping by comparing the signal level at the input pins against a noise gate threshold, ALC\_NGATE\_THR. The noise gate cuts in when:

Signal level at ADC [dB] < ALC\_NGATE\_THR [dB] + PGA gain [dB] + Input Mixer gain [dB]

This is equivalent to:

Signal level at input pin [dB] < ALC\_NGATE\_THR [dB]

Whenever the signal level at the input pins drops below the Noise Gate Threshold (ALC\_NGATE\_THR), the ALC Noise Gate is activated in one of three modes. The Noise Gate Mode is selected by ALC\_NGATE\_MODE. As soon as the peak input signal level drops below the Noise Gate Threshold, control of the PGA gain is passed from the ALC to the Noise Gate system.

The Noise Gate modes are:

 Mode 00: The PGA Gain remains static while the input signal is below the ALC Noise Gate Threshold (ALC\_NGATE\_THR) level.

As soon as the input signal rises back above the ALC Noise Gate Threshold, PGA gain is once again controlled by the ALC.

Mode 01: The PGA Gain is muted while the input signal is below the ALC Noise Gate
Threshold (ALC\_NGATE\_THR) level. The muting of the PGA Gain is immediate (a hard
mute), and is performed by setting ADCL\_VOL or ADCR\_VOL or both to zero. Note that
with Mode 01, it is the ADCL\_VOL and ADCR\_VOL registers that are muted, and not the
INL\_VOL and INR\_VOL registers that are changed in the other modes.

As soon as the input signal rises back above the ALC Noise Gate Threshold, ADCL\_VOL and ADCR\_VOL are restored to their previous values. Again this is immediate (a hard unmute).

 Mode 10: The PGA Gain is either ramped down to the ALC\_NGATE\_GAIN at a rate determined by ALC\_NGATE\_ATK, or ramped up to the ALC\_NGATE\_GAIN level at a rate determined by ALC\_NGATE\_DCY.

As soon as the input signal rises back above the ALC Noise Gate Threshold, PGA gain is once again controlled by the ALC. The PGA gain is ramped up (or down) at a rate determined by ALC\_DCY (or ALC\_ATK).

The noise gate control register is described in Table 18. The ALC\_NGATE\_THR variable sets the Noise Gate threshold with respect to the ADC full-scale range. The threshold is adjusted in 1.5dB steps. Levels at the extremes of the range may cause inappropriate operation, so care should be taken with set—up of the function. Note that the Noise Gate only works in conjunction with the ALC function, and always operates on the same channel(s) as the ALC (left, right, both, or none).



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R19 (13h) ALC3	12:10	ALC_NGATE_GAIN [2:0]	111	Noise Gate Gain level. This is the PGA gain level used within the ALC Noise Gate function.  000 = -23.25dB  001 = -18dB  010 = -12dB  011 = -6dB  100 = 0dB  101 = +6dB  110 = +12dB  111 = +18dB
R20 (14h) Noise Gate	15:12	ALC_NGATE_DCY [3:0]	0011	Sets the Noise Gate Gain Decay Rate (time taken to ramp up to the ALC_NGATE_GAIN level), measured in time per 1.5dB step.  If ALC_MODE = 0 0000 = 0.41ms / step 0001 = 0.82ms / stepdoubling with each step to 1010 = 420ms / step 1011 = 840ms / step 1100 to 1111 = Reserved  If ALC_MODE = 1 0000 = 0.082ms / step 0001 = 0.164ms / stepdoubling with each step to 1010 = 83.9ms / step 1010 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Noise Gate Gain Decay time is defined as for the ALC_MODE=0 case above. See Table 16 for further details.
	11:8	ALC_NGATE_ATK [3:0]	0010	Sets the Gain Attack Rate (time taken to ramp down to the ALC_NGATE_GAIN level), measured in time per 1.5dB step.  If ALC_MODE = 0 0000 = 0.10ms / step 0001 = 0.21ms / stepdoubling with each step to 1010 = 106ms / step 1011 to 1111 = Reserved  If ALC_MODE = 1 0000 = 0.020ms / step 0001 = 0.041ms / stepdoubling with each step to 1010 = 21.0ms / step 1011 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Noise



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				Gain Attack time is defined as for the ALC_MODE=0 case above.  See Table 17 for further details.
	7:3	ALC_NGATE_THR [4:0]	0_0000 (-76.5dBFS)	Noise Gate Threshold. If the input signal falls below this level, the Noise Gate function is triggered76.5dB to -30dB in 1.5dB steps. 00h = -76.5dB 01h = -75.0dB 02h = -73.5dB(1.5dB steps) 1Eh = -31.5dB 1Fh = -30.0dB See Table 19 for further details.
	2:1	ALC_NGATE_MODE [1:0]	00	Noise gate mode  00 = Hold PGA gain static when noise gate triggers  01 = Mute ADC output immediately when noise gate triggers.  10 = Ramp PGA Gain to ADC_NGATE_GAIN level when Noise Gate triggers.  11 = Reserved
	0	ALC_NGATE_ENA	0	Noise Gate function enable 0 = Disable 1 = Enable

Table 18 ALC Noise Gate Control



ALC_NGATE_THR [4:0]	THRESHOLD (dBFS)
00h	-76.5
01h	-75.0
02h	-73.5
03h	-72.0
04h	-70.5
05h	-69.0
06h	-67.5
07h	-66.0
08h	-64.5
09h	-63.0
0Ah	-61.5
0Bh	-60.0
0Ch	-58.5
0Dh	-57.0
0Eh	-55.5
0Fh	-54.0
10h	-52.5
11h	-51.0
12h	-49.5
13h	-48.0
14h	-46.5
15h	-45.0
16h	-43.5
17h	-42.0
18h	-40.5
19h	-39.0
1Ah	-37.5
1Bh	-36.0
1Ch	-34.5
1Dh	-33.0
1Eh	-31.5
1Fh	-30.0

Table 19 ALC Noise Gate Threshold (ALC\_NGATE\_THR) Settings



## **ALC STATUS READBACK**

There are five ALC status registers provide monitoring of the Automatic Level Control (ALC). These are particularly useful when ALC is in Monitor Mode (ALC\_INACTIVE\_ENA = 1), and the PGA Gains are not being changed by the ALC.

These five Register bits and their settings are summarised in Table 20.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R18 (12h) ALC2	15	ALC_LOCK_ST S	0	Readback of the ALC Lock Status.  Set when ADC signal = ALC_LVL
	14	ALC_THRESH_ STS	0	Readback of the ALC Threshold Level status (when ALC_LOCK_STS = 0) 0 = ADC signal < ALC_LVL 1 = ADC signal > ALC_LVL
	13	ALC_SAT_STS	0	Readback of the ALC saturation status.  0 = ADC signal = ALC_LVL  1 = ADC signal < ALC_LVL but maximum ALC Gain has been reached
	12	ALC_PKOVR_S TS	0	Readback of the ALC Peak Limiter Overload status. Set when ADC input signal exceeds -1.16dBFS
	11	ALC_NGATE_S TS	0	Readback of the ALC Noise Gate status.  0 = ADC input signal level > ALC_NGATE_THR  1 = ADC input signal level < ALC_NGATE_THR

Table 20 ALC Status Readback



## **DIGITAL MICROPHONE INTERFACE**

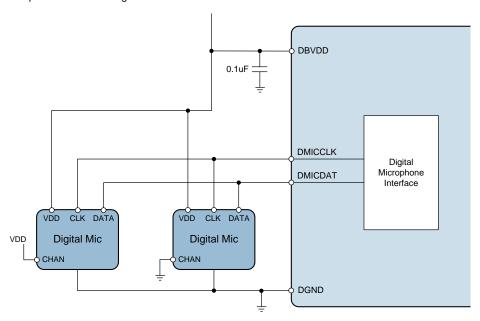
The WM8963 supports a stereo digital microphone interface. Two channels of audio data are multiplexed on a GPIO pin configured for digital microphone input.

The digital microphone data input (DMICDAT) is provided on GPIO5 or GPIO6 by setting the respective GPn\_FN register to 14h. The associated clock (DMICCLK) is provided on a separate GPIO pin by setting the respective GPn\_FN register to 13h. See "General Purpose Input/Output (GPIO)" section for details on these registers.

Note that care must be taken to ensure that the respective digital logic levels of the microphone are compatible with the digital input thresholds of the WM8963. The digital input thresholds are referenced to DBVDD, as defined in "Electrical Characteristics". It is recommended to power the digital microphones from DBVDD.

When digital microphone input is enabled, the WM8963 outputs a clock signal (DMICCLK) on the Digital Microphone Clock Output pin (this must be configured on one of the GPIO pins). The clock frequency for all supported digital microphone clocking modes is described later in this section.

A pair of digital microphones is connected as illustrated in Figure 21. The microphones must be configured to ensure that the Left mic transmits a data bit when DMICCLK is high, and the Right mic transmits a data bit when DMICCLK is low. The WM8963 samples the digital microphone data at the end of each DMICCLK phase. Each microphone must tri-state its data output when the other microphone is transmitting.



DMICCLK is available on GPIO2, GPIO5 and GPIO6 DMICDAT is supported on GPIO5 and GPIO6

Figure 21 Digital Microphone Input

The digital microphone signal paths are enabled using the DMIC\_ENA register. When DMIC\_ENA is set, the ADC path is disconnected and the digital microphone data is routed to the digital core, as illustrated in the "Digital Mixing" section.

Two microphone channels are interleaved on DMICDAT; the timing is illustrated in Figure 22. Each microphone must tri-state its data output when the other microphone is transmitting.

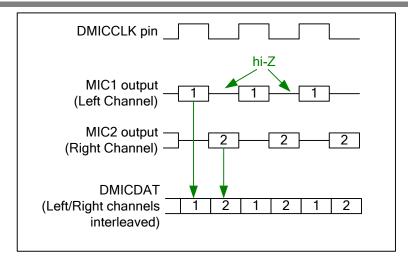


Figure 22 Digital Microphone Interface Timing

The digital microphone interface control fields are described in Table 21. Note that the ADCs must be enabled and the sample rate must be set in order to ensure correct operation of all DSP functions associated with the digital microphone. Volume control for the Digital Microphone Interface signals is provided using the ADC Digital Volume Control.

See "Analogue To Digital Converter (ADC)" for details of the ADC Enable and ADC Digital Volume control functions. See "General Purpose Input/Output (GPIO)" for details of configuring the DMICCLK and DMICDAT functions. See "Clocking and Sample Rates" for details of the sample rate control.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	10	DMIC_ENA	0	Enables Digital Microphone mode.  0 = Audio DSP input is from ADC  1 = Audio DSP input is from digital microphone interface  Note that, when the digital microphone interface is selected, the ADCL_ENA and ADCR_ENA registers must also be set to enable the left and right digital microphone channels respectively.
	3	ADCL_ENA	0	Left ADC Enable 0 = Disabled 1 = Enabled
	2	ADCR_ENA	0	Right ADC Enable 0 = Disabled 1 = Enabled

**Table 21 Digital Microphone Interface Control** 

Note that, in addition to setting the DMIC\_ENA bit as described in Table 21, the pins GPIO2, GPIO5 or GPIO6 must also be configured to provide the digital microphone interface function. See "General Purpose Input/Output (GPIO)" for details.



Clocking for the digital microphone interface is derived from SYSCLK. The DMICCLK frequency is configured automatically, according to the SAMPLE\_RATE, MCLK\_RATE, and ADC\_HP registers. (See "Clocking and Sample Rates" for further details of the system clocks and control registers.)

The DMICCLK is enabled whenever a digital microphone input path is enabled on the GPIO2, GPIO5 or GPIO6 pins. Note that the SYSCLK\_ENA register must also be set.

The DMICCLK frequency is as described in Table 22 (for ADC\_HP=0) and Table 23 (for ADC\_HP=1). The ADC\_HP bit is set to 0 by default, giving reduced power consumption.

The only valid DMICCLK configurations are the ones listed in Table 22 and Table 23. Note that some combinations of Sample Rate and MCLK / fs ratio have a dependency on the DCVDD supply voltage. The marked (\*) combinations are only valid for DCVDD  $\geq$  1.7V.

The system clock, SYSCLK, must be present and enabled when using the digital microphone interface.

SAMPLE RATE	MCLK RATE (MCLK / fs ratio)								
(kHz)	256	384	512	768	1024	1536	3072	6144	
8	1.024		1.024	1.024	1.024	1.024	1.024	1.024*	
11.025	1.4112		1.4112	1.4112	1.4112	1.4112	1.4112*		
12	1.536		1.536	1.536	1.536	1.536	1.536*		
16	1.024	1.024	1.024	1.024	1.024	1.024	1.024*		
22.05	1.4112	1.4112	1.4112	1.4112	1.4112	1.4112*			
24	1.536	1.536	1.536	1.536	1.536	1.536*			
32	2.048	2.048	2.048	2.048	2.048*	2.048*			
44.1	2.8224	1.4112	2.8224	1.4112*	2.8224*				
48	3.072	1.536	3.072	1.536*	3.072*				
88.2	2.8224		2.8224*						
96	3.072		3.072*						

When ADC\_HP=0, digital microphone operation is only supported for the above configurations. Digital microphone operation is not supported for 64fs, 128fs or 192fs MCLK ratios. Note - the configurations marked (\*) are only valid for DCVDD  $\geq$  1.7V.

Table 22 DMICCLK Frequency (MHz) - ADC\_HP = 0 (Default)

SAMPLE RATE	MCLK RATE (MCLK / fs ratio)								
(kHz)	256	384	512	768	1024	1536	3072	6144	
8	1.024		2.048		2.048	2.048	2.048	2.048*	
11.025	1.4112		2.8224		2.8224				
12	1.536		3.072		3.072				
16	2.048			2.048	2.048	2.048	2.048*		
22.05	2.8224		2.8224		2.8224				
24	3.072		3.072		3.072				
32	2.048		2.048		2.048*				
44.1	2.8224		2.8224		2.8224*				
48	3.072		3.072		3.072*				
88.2	2.8224		2.8224*						
96	3.072		3.072*						

When ADC\_HP=1, digital microphone operation is only supported for the above configurations. Digital microphone operation is not supported for 64fs, 128fs or 192fs MCLK ratios. Note - the configurations marked (\*) are only valid for DCVDD ≥ 1.7V.

Table 23 DMICCLK Frequency (MHz) - ADC\_HP = 1



# ANALOGUE TO DIGITAL CONVERTER (ADC)

The WM8963 uses stereo 24-bit, 128x oversampled sigma-delta ADCs. The use of multi-bit feedback and high oversampling rates reduces the effects of jitter and high frequency noise. The ADC full scale input level is proportional to AVDD - see "Electrical Characteristics". Any input signal greater than full scale may overload the ADC and cause distortion.

The ADCs are enabled by the ADCL\_ENA and ADCR\_ENA register bits. Note that when disabling the ADC, the digital volume controls ADCL\_VOL and ADCR\_VOL should be muted before clearing ADCL\_ENA or ADCR\_ENA to 0. This ensures that the last ADC code does not appear at the Audio Interface (ADCDAT) pin when ADCL\_ENA or ADCR\_ENA are cleared.

The system clock, SYSCLK, must be configured and enabled before either of the ADCs is enabled. See "Clocking and Sample Rates" for details of the system clocks.

Note that, when reconfiguring or disabling SYSCLK, the ADCs and DACs must be disabled before setting SYSCLK\_ENA=0.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	3	ADCL_ENA	0	Left ADC Enable 0 = Disabled 1 = Enabled
	2	ADCR_ENA	0	Right ADC Enable 0 = Disabled 1 = Enabled

**Table 24 ADC Enable Control** 

### ADC CLOCKING CONTROL

Clocking for the ADCs is derived from SYSCLK. The required clock is enabled when the SYSCLK\_ENA register is set.

The ADC clock rate is configured automatically, according to the SAMPLE\_RATE and MCLK\_RATE registers. See "Clocking and Sample Rates" for further details of the system clocks and associated control registers.

Note that the ADC and the ADC signal path enhancements functions are only supported under specific clocking configurations. The valid clocking ratios for ADC operation are identified in Table 92. See also Table 93 for details of the supported functions for different MCLK / fs ratios.



## **ADC DIGITAL VOLUME CONTROL**

The output of the ADCs can be digitally amplified or attenuated over a range from -71.625dB to +23.625dB in 0.375dB steps. The volume of each channel can be controlled separately. The gain for a given eight-bit code X is given by:

 $0.375 \times (X-192) \text{ dB for } 1 \le X \le 255;$  MUTE for X = 0

The ADC\_VU bit controls the loading of digital volume control data. When ADC\_VU is set to 0, the ADCL\_VOL or ADCR\_VOL control data will be loaded into the respective control register, but will not actually change the digital gain setting. Both left and right gain settings are updated when a 1 is written to ADC\_VU. This makes it possible to update the gain of both channels simultaneously.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R21 (15h) Left ADC Volume	8	ADC_VU	N/A	ADC Volume Update Writing a 1 to this bit will cause left and right ADC volume to be updated simultaneously
	7:0	ADCL_VOL [7:0]	C0h (0dB)	Left ADC Digital Volume  00h = mute  01h = -71.625dB  02h = -71.250dB 0.375dB steps  C0h = 0dB (default)   FFh = 23.625dB  (See Table 26 for volume range)
R22 (16h) Right ADC Volume	8	ADC_VU	N/A	ADC Volume Update Writing a 1 to this bit will cause left and right ADC volume to be updated simultaneously
	7:0	ADCR_VOL [7:0]	C0h (0dB)	Right ADC Digital Volume  00h = mute  01h = -71.625dB  02h = -71.250dB 0.375dB steps  C0h = 0dB (default)   FFh = 23.625dB  (See Table 26 for volume range)

**Table 25 ADC Digital Volume Control** 



1001 1/01		4501 1/01		4501 1/01		4001 1/01	
ADCL_VOL or	\/-\(.ID\	ADCL_VOL or	\(\( - \) \(	ADCL_VOL or	V-1 (4D)	ADCL_VOL or	\( \( \)
ADCR_VOL	Volume (dB)	ADCR_VOL	Volume (dB)	ADCR_VOL	Volume (dB)	ADCR_VOL	Volume (dB)
00	MUTE	40	-48.000	80	-24.000	C0	0.000
01	-71.625	41	-47.625	81	-23.625	C1	0.375
02	-71.250	42	-47.250	82	-23.250	C2	0.750
03	-70.875	43	-46.875	83	-22.875	C3	1.125
04	-70.500	44	-46.500	84	-22.500	C4	1.500
05	-70.125	45	-46.125	85	-22.125	C5	1.875
06	-69.750	46	-45.750	86	-21.750	C6	2.250
07	-69.375	47	-45.375	87	-21.375	C7	2.625
08	-69.000 -68.625	48	-45.000	88	-21.000	C8 C9	3.000
09		49	-44.625	89	-20.625	CA	3.375
0A	-68.250	4A 4B	-44.250	8A	-20.250	CB	3.750
0B 0C	-67.875 -67.500	4B 4C	-43.875 -43.500	8B 8C	-19.875 -19.500	CC	4.125
0D		4C 4D		8D		CD	4.500
0E	-67.125	4E	-43.125	8E	-19.125	CE	4.875 5.250
0E 0F	-66.750 -66.375	4E 4F	-42.750 -42.375	8F	-18.750 -18.375	CF	5.625
10	-66.000	50	-42.000	90	-18.000	D0	6.000
11	-65.625	51	-41.625	91	-17.625	D1	6.375
12	-65.250	52	-41.250	92	-17.250	D2	6.750
13	-64.875	53	-40.875	93	-16.875	D3	7.125
14	-64.500	54	-40.500	94	-16.500	D3	7.500
15	-64.125	54 55	-40.125	95	-16.125	D5	7.875
16	-64.125 -63.750	56	-39.750	96	-16.125 -15.750	D6	8.250
17	-63.375	57	-39.375	97	-15.375	D7	8.625
18	-63.000	58	-39.000	98	-15.000	D8	9.000
19	-62.625	59	-38.625	99	-14.625	D9	9.375
19 1A	-62.250	5A	-38.250	9A	-14.250	DA	9.750
1B	-61.875	5B	-37.875	9B	-13.875	DB	10.125
1C	-61.500	5C	-37.500	9C	-13.500	DC	10.500
1D	-61.125	5D	-37.125	9D	-13.125	DD	10.875
1E	-60.750	5E	-36.750	9E	-12.750	DE	11.250
1F	-60.375	5F	-36.375	9F	-12.375	DF	11.625
20	-60.000	60	-36.000	A0	-12.000	E0	12.000
21	-59.625	61	-35.625	A1	-11.625	E1	12.375
22	-59.250	62	-35.250	A2	-11.250	E2	12.750
23	-58.875	63	-34.875	A3	-10.875	E3	13.125
24	-58.500	64	-34.500	A4	-10.500	E4	13.500
25	-58.125	65	-34.125	A5	-10.125	E5	13.875
26	-57.750	66	-33.750	A6	-9.750	E6	14.250
27	-57.375	67	-33.375	A7	-9.375	E7	14.625
28	-57.000	68	-33.000	A8	-9.000	E8	15.000
29	-56.625	69	-32.625	A9	-8.625	E9	15.375
2A	-56.250	6A	-32.250	AA	-8.250	EA	15.750
2B	-55.875	6B	-31.875	AB	-7.875	EB	16.125
2C	-55.500	6C	-31.500	AC	-7.500	EC	16.500
2D	-55.125	6D	-31.125	AD	-7.125	ED	16.875
2E	-54.750	6E	-30.750	AE	-6.750	EE	17.250
2F	-54.375	6F	-30.375	AF	-6.375	EF	17.625
30	-54.000	70	-30.000	В0	-6.000	F0	18.000
31	-53.625	71	-29.625	B1	-5.625	F1	18.375
32	-53.250	72	-29.250	B2	-5.250	F2	18.750
33	-52.875	73	-28.875	B3	-4.875	F3	19.125
34	-52.500	74	-28.500	B4	-4.500	F4	19.500
35	-52.125	75	-28.125	B5	-4.125	F5	19.875
36	-51.750	76	-27.750	B6	-3.750	F6	20.250
37	-51.375	77	-27.375	B7	-3.375	F7	20.625
38	-51.000	78	-27.000	B8	-3.000	F8	21.000
39	-50.625	79	-26.625	B9	-2.625	F9	21.375
3A	-50.250	7A	-26.250	BA	-2.250	FA	21.750
3B	-49.875	7B	-25.875	BB	-1.875	FB	22.125
3C	-49.500	7C	-25.500	BC	-1.500	FC	22.500
3D	-49.125	7D	-25.125	BD	-1.125	FD	22.875
3E	-48.750	7E	-24.750	BE	-0.750	FE	23.250
3F	-48.375	7F	-24.375	BF	-0.375	FF	23.625

Table 26 ADC Digital Volume Range



## **ADC OVERSAMPLING RATIO (OSR)**

The ADC oversampling rate is programmable to allow power consumption versus audio performance trade-offs. The default oversampling rate is low for reduced power consumption; using the higher OSR setting improves the DAC signal-to-noise performance.

See the "Reference Voltages and Bias Control" section for details of the supported bias control settings for the input signal paths.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R23 (17h) Additional control (1)	5	ADC_HP	0	ADC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)

Table 27 ADC Oversampling Ratio

## **ADC MONOMIX**

A mono mix of the Left and Right channels can be created by setting the ADC\_MONOMIX register bit, as described in Table 28. When ADC\_MONOMIX is set, 3D Surround must be disabled (THREED\_ENA = 0, as described Table 33) for the ADC\_MONOMIX setting to be effective. An attenuation of -6dB is applied to the sum of the Left and Right channels in order to avoid clipping.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R268 (010Ch) THREED1	6	ADC_MONOMIX	0	ADC Monomix enable  0 = Disabled  1 = Enabled  Note that THREED_ENA (see Table  33) must be disabled for  ADC_MONOMIX to be effective.

**Table 28 ADC Monomix** 



## **DSP SIGNAL ENHANCEMENTS**

The WM8963 incorporates several advanced signal enhancement features within the digital audio signal paths, as illustrated in Figure 23.

The ADC signal path incorporates a 2<sup>nd</sup> order High-Pass Filter (HPF), 1<sup>st</sup> order Low/High-Pass Filter (LPF/HPF), 3D surround, DF1 Filter and Dynamic Range Control (DRC).

The DAC signal path incorporates a 5-Band EQ, Dynamic Range Control (DRC), 2<sup>nd</sup> order High-Pass Filter (HPF), Virtual Surround Sound (VSS), ReTune<sup>™</sup> and Multiband Compressor (MBC).

Dynamic Range Control (DRC) can be enabled on either the ADC path or on the DAC path, but not on both at the same time.

Note that specific sequences must be followed when enabling or configuring DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, and MBC functions. Different control sequences are applicable, depending on whether any of the advanced signal enhancements is initially enabled or not.

The configuration parameters in registers R16896 (4200h) to R19603 (4C93h) are 24-bit words, arranged within the 16-bit register address space. Each 24-bit word must be written to the register map in full, MSBs first, before attempting to read back the value. Failure to do this may give incorrect read/write behaviour.

When updating the configuration parameters for any DSP feature(s), it is recommended to write all of the associated registers, in incremental address order, before reading back any values.

### **ENABLE SEQUENCE - ENHANCEMENTS INITIALLY DISABLED**

When enabling any of DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, or MBC, the following sequence is required.

Note that this sequence assumes that, under initial conditions, all of these enhancement functions are disabled. A separate sequence is described for use when sound enhancement is initially enabled.

- 1. MCLK must be present and configured at >= 512 fs (see Table 95)
- Set ADCL\_VOL = 00h in Register R21 (15h), and ADCR\_VOL = 00h in Register R22 (16h) (see Table 25)
- Set ADCL\_ENA = 0 and ADCR\_ENA = 0 in Register R25 (19h) (see Table 24)
- Set DAC\_MUTE = 1 in Register R5 (5h) (see Table 61)
- 5. Set DACL ENA = 0 and DACR ENA = 0 in Register R26 (1Ah) (see Table 58)
- 6. Set DSP2\_ENA = 1 in Register R768 (300h) (see Table 29)
- 7. Set the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 8. Readback the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 9. Set DSP2\_RUNR = 1 in Register R1037 (40Dh) (see Table 29)
- 10. Set the enable bits in Register R16389 (4005h) for any required sound enhancement

RTN\_DAC\_ENA
HPF1\_ENA (see note below)
HPF2\_ENA (see note below)
VSS\_ENA
MBC\_ENA

- 11. Set ADCL\_ENA = 1 and ADCR\_ENA = 1 in Register R25 (19h), if required (see Table 24)
- Set ADCL\_VOL in Register R21 (15h), and ADCR\_VOL in Register R22 (16h), to their previous values
- 13. Set DACL\_ENA = 1 and DACR\_ENA = 1 in Register R26 (1Ah), if required (see Table 58)
- 14. Set DAC\_MUTE = 0 in Register R5 (5h) (see Table 61)



Note that the DAC high pass filters cannot be enabled unless one or more other sound enhancement functions is enabled. If HPF1\_ENA = 1 or HPF2\_ENA = 1, then at least one other of the enable bits in Register R16389 must also be set (ie. RTN\_DAC\_ENA, MBC\_ENA or VSS\_ENA).

Note that DSP2\_ENA in Register R768 (300h) must remain asserted whenever any of the sound enhancement functions listed above is being used.

#### **ENABLE / DISABLE SEQUENCE - ENHANCEMENTS INITIALLY ENABLED**

When enabling or disabling any of DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, or MBC, the following sequence is required.

Note that this sequence assumes that, under initial conditions, one or more of these enhancement functions is enabled. A separate sequence is described for use when the sound enhancements are initially disabled.

Note that this sequence assumes that the applicable enhancement functions have already been configured (using default settings or otherwise). This sequence is only for enabling/disabling the selected functions. Separate sequences are described for configuring any of the sound enhancement functions.

- Set ADCL\_VOL = 00h in Register R21 (15h), and ADCR\_VOL = 00h in Register R22 (16h) (see Table 25)
- 2. Set DAC\_MUTE = 1 in Register R5 (5h) (see Table 61)
- Set the enable bits in Register R16389 (4005h) for any required sound enhancement

RTN DAC ENA

HPF1\_ENA (see note below)

HPF2\_ENA (see note below)

VSS\_ENA

MBC\_ENA

- Set ADCL\_VOL in Register R21 (15h), and ADCR\_VOL in Register R22 (16h), to their previous values
- 5. Set DAC\_MUTE = 0 in Register R5 (5h) (see Table 61)

Note that the DAC high pass filters cannot be enabled unless one or more other sound enhancement functions is enabled. If HPF1\_ENA = 1 or HPF2\_ENA = 1, then at least one other of the enable bits in Register R16389 must also be set (ie. RTN\_DAC\_ENA, MBC\_ENA or VSS\_ENA).

Note that DSP2\_ENA in Register R768 (300h) must remain asserted whenever any of the sound enhancement functions listed above is being used.

To disable all sound enhancement functions, refer to the control sequence described in the next section ("Disable All Sound Enhancements").



## **DISABLE ALL SOUND ENHANCEMENTS SEQUENCE**

When disabling all of the sound enhancement functions (DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, and MBC), the following sequence is required:

- Set ADCL\_VOL = 00h in Register R21 (15h), and ADCR\_VOL = 00h in Register R22 (16h) (see Table 25)
- 2. Set DAC\_MUTE = 1 in Register R5 (5h) (see Table 61)
- 3. Set the enable bits in Register R16389 (4005h) to 0 for all sound enhancements

RTN\_DAC\_ENA = 0
HPF1\_ENA = 0
HPF2\_ENA = 0
VSS\_ENA = 0
MBC\_ENA = 0

- Set ADCL\_VOL in Register R21 (15h), and ADCR\_VOL in Register R22 (16h), to their previous values
- 5. Set DAC\_MUTE = 0 in Register R5 (5h) (see Table 61)
- 6. Set DSP2\_STOP = 1 in Register R1037 (40Dh) (see Table 29)
- 7. Set DSP2\_ENA = 0 in Register R768 (300h) (see Table 29).



## **UPDATE / READBACK SEQUENCE - ENHANCEMENTS INITIALLY ENABLED**

The required control sequence to update or read back the configuration parameters differs according to whether one or more of the sound enhancements is enabled under the initial conditions.

If DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, or MBC is already enabled, then the following sequence is required when updating or reading back the configuration parameters:

- Set ADCL\_VOL = 00h in Register R21 (15h), and ADCR\_VOL = 00h in Register R22 (16h) (see Table 25)
- 2. Set ADCL\_ENA = 0 and ADCR\_ENA = 0 in Register R25 (19h) (see Table 24)
- 3. Set DAC\_MUTE = 1 in Register R5 (5h) (see Table 61)
- 4. Set DACL\_ENA = 0 and DACR\_ENA = 0 in Register R26 (1Ah) (see Table 58)
- 5. Disable all sound enhancement registers in Register R16389 (4005h)

```
RTN_DAC_ENA = 0

HPF2_ENA = 0

HPF1_ENA = 0

VSS_ENA = 0

MBC_ENA = 0
```

- 6. Set DSP2\_STOP = 1 in Register R1037 (40Dh) (see Table 29)
- 7. Set the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 8. Readback the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 9. Set DSP2\_RUNR = 1 in Register R1037 (40Dh) (see Table 29)
- 10. Set the enable bits in Register R16389 (4005h) for any required sound enhancement

```
RTN_DAC_ENA
HPF1_ENA
HPF2_ENA
VSS_ENA
MBC_ENA
```

- 11. Set ADCL\_ENA = 1 and ADCR\_ENA = 1 in Register R25 (19h), if required (see Table 24)
- 12. Set ADCL\_VOL in Register R21 (15h), and ADCR\_VOL in Register R22 (16h), to their previous values
- 13. Set DACL\_ENA = 1 and DACR\_ENA = 1 in Register R26 (1Ah), if required (see Table 58)
- 14. Set DAC\_MUTE = 0 in Register R5 (5h) (see Table 61)



## UPDATE / READBACK SEQUENCE - ENHANCEMENTS INITIALLY DISABLED

The required control sequence to update or read back the configuration parameters differs according to whether one or more of the sound enhancements is enabled under the initial conditions.

If DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, or MBC are all disabled, then the following sequence is required when updating or reading back the configuration parameters:

- 1. MCLK must be present and configured at >= 512 fs (see Table 95)
- Set ADCL\_VOL = 00h in Register R21 (15h), and ADCR\_VOL = 00h in Register R22 (16h) (see Table 25)
- 3. Set ADCL\_ENA = 0 and ADCR\_ENA = 0 in Register R25 (19h) (see Table 24)
- 4. Set DAC\_MUTE = 1 in Register R5 (5h) (see Table 61)
- 5. Set DACL\_ENA = 0 and DACR\_ENA = 0 in Register R26 (1Ah) (see Table 58)
- 6. Set DSP2\_ENA = 1 in Register R768 (300h) (see Table 29)
- 7. Set the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 8. Readback the configuration parameters in registers R16896 (4200h) to R19603 (4C93h)
- 9. Set DSP2\_ENA = 0 in Register R768 (300h) (see Table 29)
- 10. Set ADCL\_ENA = 1 and ADCR\_ENA = 1 in Register R25 (19h), if required (see Table 24)
- 11. Set ADCL\_VOL in Register R21 (15h), and ADCR\_VOL in Register R22 (16h), to their previous values
- 12. Set DACL\_ENA = 1 and DACR\_ENA = 1 in Register R26 (1Ah), if required (see Table 58)
- 13. Set DAC\_MUTE = 0 in Register R5 (5h) (see Table 61)

The DSP2 audio processor control registers are described in Table 29. Other registers associated with DAC ReTune, DAC 2<sup>nd</sup> order HPF, VSS, or MBC are described in the respective sections in the following pages.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (R300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of  DAC ReTune, DAC HPF, VSS or  MBC is enabled. It must remain set  whenever any of these functions is enabled.
R1037 (40Dh) DSP2_ExecC ontrol	2	DSP2_STOP	N/A	Stop the DSP2 audio processor Writing a 1 to this bit will cause the DSP2 processor to stop processing audio data
	1	DSP2_RUNR	N/A	Start the DSP2 audio processor Writing a 1 to this bit will cause the DSP2 processor to start processing audio data

Table 29 DSP Signal Enhancement Control



## ADC SIGNAL PATH ENHANCEMENTS

The ADC signal path incorporates a number of sound enhancement features, as illustrated in Figure 23. These features are described more fully in the following sections.

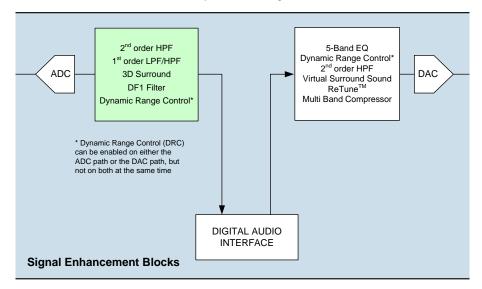
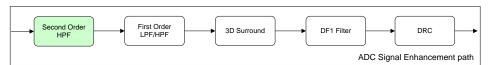


Figure 23 ADC Signal Path Enhancements

## **ADC SECOND ORDER HIGH-PASS FILTER**



A digital high-pass filter is enabled by default in the ADC path to remove DC offsets. This filter can also be used to remove low frequency noise in voice applications (e.g. wind noise or mechanical vibration). The filter can be disabled by setting the ADC\_HPF\_DIS register bit.

The filter operates in one of two modes, selected by ADC\_HPF\_MODE.

The ADC\_HPF\_SR register should be set according to the selected ADC sample rate. See "Clocking and Sample Rates" for details of the ADC sample rate.

In Hi-Fi mode, the high-pass filter is optimised for removing DC offsets without degrading the bass response and has a cut-off frequency of 3.5Hz when the sample rate (fs) = 44.1kHz.

In Application mode, the HPF cut-off frequency is set using ADC\_HPF\_CUT. This mode is intended for voice communication; it is recommended to set the cut-off frequency below 300Hz (e.g.  $ADC_HPF_CUT = 101$  when fs = 8kHz or  $ADC_HPF_CUT = 101$  when fs = 16kHz).



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC and DAC Control 1	0	ADC_HPF_DIS	0	ADC High-Pass Filter Disable 0 = Enable 1 = Disable
R6 (06h) ADC and DAC Control 2	13:12	ADC_HPF_SR	10	ADC High-Pass Filter Sample rate 00 = 8k, 11.025k, 12k 01 = 16k, 22.025k, 24k 10 = 32k, 44.1, 48k 11 = 88.2k, 96k This field is for read-back only; it is set automatically and cannot be adjusted.
	10	ADC_HPF_MODE	0	ADC High-Pass Filter Mode select 0 = Hi-Fi mode (1st order) 1 = Application mode (2nd order)
	9:7	ADC_HPF_CUT[2:0]	000	ADC High-Pass Filter Cutoff Note that the cut-off frequency scales with sample rate. See Table 31for cut-off frequencies at all supported sample rates

Table 30 ADC High-Pass Filter

		CUT-OFF FREQUENCY (Hz)							
			API	PLICATIO	N MODE	/ ADC_H	PF_CUT[	2:0]	
SAMPLE FREQUENCY (kHz)	HI-FI MODE	000	001	010	011	100	101	110	111
8.000	3.0	80.5	100.5	129.0	160.5	200.5	256.5	320.5	400.5
11.025	4.5	111.0	138.5	177.5	221.0	276.5	353.0	442.0	551.5
12.000	4.5	120.5	151.0	193.0	240.5	300.5	384.5	481.0	600.5
16.000	3.0	80.0	101.0	129.0	161.0	200.5	256.5	321.0	401.0
22.050	4.5	110.5	139.0	177.5	221.5	276.0	353.5	442.0	552.5
24.000	4.5	120.5	151.5	193.5	241.5	300.5	385.0	481.5	601.0
32.000	2.5	80.0	101.5	129.0	160.5	200.0	257.5	320.0	401.0
44.100	3.5	110.0	139.5	177.5	221.0	275.5	355.0	441.0	552.5
48.000	4.0	119.5	152.0	193.0	240.5	300.0	386.5	480.0	601.0
88.200	3.5	112.5	139.0	177.0	220.0	274.0	355.0	442.0	551.0
96.000	4.0	122.5	151.5	192.5	239.5	298.0	386.5	481.0	600.0

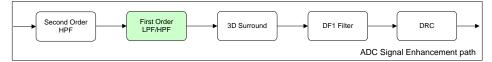
Note: 'Hi-Fi Mode' refers to the mode when ADC\_HPF\_MODE = 0 (first order filtering and a cutoff frequency of 3.5Hz at a sample rate of 44.1kHz); 'Application Mode' refers to the mode when ADC\_HPF\_MODE = 1 (second order filtering and the cut-off frequency set by ADC\_HPF\_CUT)

Table 31 ADC High-Pass Filter Cut-Off Frequencies

The high-pass filter characteristics are shown in the "Digital Filter Characteristics" section.



# LOW-PASS / HIGH-PASS FILTER (LPF/HPF)



The Low-Pass / High-Pass filter is part of the ADC Signal Enhancement path.

This first-order filter can be configured to be high-pass or low-pass. It can be used to remove unwanted 'out of band' noise from the ADC signal path. The filter is enabled using the LHPF\_ENA register bit defined in Table 32. The default setting is bypass (OFF). The High-Pass or Low-Pass configuration is selected using the LHPF\_MODE register bit.

The filter can be programmed using the LHPF\_COEFF register field (R265). For the derivation of this parameter, refer to the WISCE™ configuration tool supplied with the WM8963 Evaluation Kit.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R264 (0108h) LHPF1	1	LHPF_MODE	0	Low/High-Pass Filter mode select 0 = Low-Pass 1 = High-Pass
	0	LHPF_ENA	0	Low/High-Pass Filter 0 = Disable 1 = Enable

Table 32 Low-Pass / High-Pass Filter Control

Example plots of the Low-pass / High-pass filter response are shown in Figure 24.

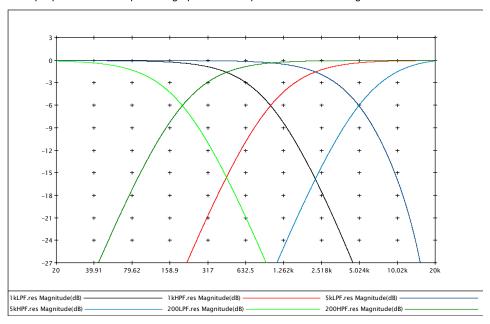
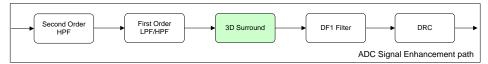


Figure 24 Low-pass / High-pass Filter Responses



### **3D SURROUND**



The 3D Surround function is part of the ADC Signal Enhancement path.

The 3D Surround processing can be used in ADC record applications to select between a directional or wide-angle microphone response. Depending on the target application, the stereo widening capability could be selected manually, or else could be configured automatically for different operational modes, for example.

Note that the stereo widening is most effective at frequencies above 2kHz; lower frequencies may be attenuated by the phase cancellation process employed by the 3D Surround function. The DF1 filter (also part of the the ADC Signal Enhancement path) can be used to compensate for the attenuation of low frequencies; a low-shelf filter can be implemented in the DF1, as described later.

The 3D Surround effect is programmable; it uses time delays and controlled cross-talk mechanisms to adjust the depth or width of the stereo audio. The 3D Surround effect includes programmable highpass or low-pass filtering to limit the effect to specific frequency bands if required. The structure of the 3D Surround processing is illustrated in Figure 25.

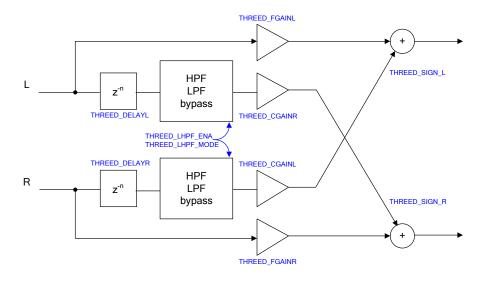


Figure 25 3D Surround Processing

The 3D Surround effect is enabled using the THREED\_ENA register. Note that enabling 3D Surround will cause any ADC\_MONOMIX settings to be ignored.

When 3D Surround is enabled, the left and right audio channels connect to the outputs using forward (same channel) paths and cross-feed (opposite channel) paths. The forward gain levels are determined by the THREED\_FGAINL and THREED\_FGAINR registers; the cross-feed gain levels are set by THREED\_CGAINL (for right-to-left cross-feed) and THREED\_CGAINR (for left-to-right cross-feed).

The polarity of the cross-feed mixing is controlled by the THREED\_SIGN\_L and THREED\_SIGN\_R register bits. If THREED\_SIGN\_L = 1 or THREED\_SIGN\_R = 1, then the respective cross-feed signal is subtracted from the main signal. If THREED\_SIGN\_L = 0 or THREED\_SIGN\_R = 0, then the respective cross-feed signal is added to the forward path signal.

A time delay can be applied to the cross-feed signals; this is selected using the THREED\_DELAYL and THREED\_DELAYR registers for the left and right channels respectively. The signals can be delayed up to a maximum of 8 samples.

High-Pass or Low-Pass filtering can be applied to the cross-feed signals. This is enabled by the THREED\_LHPF\_ENA register. The High-Pass or Low-Pass configuration is selected using the



THREED\_LHPF\_MODE register bit. This is typically used to filter out fixed-frequency noise or resonances.

The 3D Surround High-Pass / Low-Pass filter can be programmed using the THREED\_LHPF\_COEFF register field (R270). For the derivation of this parameter, refer to the WISCE $^{\text{TM}}$  configuration tool supplied with the WM8963 Evaluation Kit.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R268 (010Ch) THREED1	5	THREED_SIGNL	0	3D Left Cross mixing polarity (from the right channel to the left) 0 = Positive 1 = Negative
	4	THREED_SIGNR	0	3D Right Cross mixing polarity (from the left channel to the right) 0 = Positive 1 = Negative
	2	THREED_LHPF_ MODE	0	3D Low/High-Pass filter mode 0 = Low-Pass 1 = High-Pass
	1	THREED_LHPF_ ENA	0	3D Low/High-Pass filter enable 0 = Disabled 1 = Enabled
	0	THREED_ENA	0	3D Surround Sound enable 0 = Disabled 1 = Enabled Note that setting THREED_ENA will cause any ADC_MONOMIX setting to be ignored
R269 (010Dh) THREED2	15:11	THREED_FGAIN L [4:0]	00000	3D Left Forward Gain 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB See Table 34 for a full list of gain settings
	10:6	THREED_CGAIN L [4:0]	00000	3D Left Cross Gain (from the right channel to the left)  00000 = Mute  00001 = -11.25dB  00010 = -10.875dB  (in steps of -0.375dB)  11110 = -0.375dB  11111 = 0.0dB  See Table 34 for a full list of gain settings
	5:2	THREED_DELAY L [3:0]	0000	3D Left Filter Delay (measured from the sample rate)  0000 = 0 samples  0001 = 1 samples  0010 = 2 samples  0011 = 3 samples  0100 = 4 samples  0101 = 5 samples  0110 = 6 samples  0111 = 7 samples  1000 = 8 samples  1001 to 1111 = Reserved



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R271 (010Fh) THREED4	15:11	THREED_FGAIN R [4:0]	00000	3D Right Forward Gain 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB See Table 34 for a full list of gain settings
	10:6	THREED_CGAIN R [4:0]	00000	3D Right Cross Gain (from the left channel to the right) 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB See Table 34 for a full list of gain settings
	5:2	THREED_DELAY R [3:0]	0000	3D Filter Delay (measured from the sample rate)  0000 = 0 samples  0001 = 1 samples  0010 = 2 samples  0011 = 3 samples  0100 = 4 samples  0101 = 5 samples  0110 = 6 samples  0111 = 7 samples  1000 = 8 samples  1001 to 1111 = Reserved

Table 33 3D Surround Processing



THREED_FGAINL [4:0], THREED_CGAINL [4:0], THREED_FGAINR [4:0], THREED_CGAINR [4:0]	GAIN (dB)	THREED_FGAINL [4:0], THREED_CGAINL [4:0], THREED_FGAINR [4:0], THREED_CGAINR [4:0]	GAIN (dB)
0_0000	Mute	1_0000	-5.625
0_0001	-11.250	1_0001	-5.250
0_0010	-10.875	1_0010	-4.875
0_0011	-10.500	1_0011	-4.500
0_0100	-10.125	1_0100	-4.125
0_0101	-9.750	1_0101	-3.750
0_0110	-9.375	1_0110	-3.375
0_0111	-9.000	1_0111	-3.000
0_1000	-8.625	1_1000	-2.625
0_1001	-8.250	1_1001	-2.250
0_1010	-7.875	1_1010	-1.875
0_1011	-7.500	1_1011	-1.500
0_1100	-7.125	1_1100	-1.125
0_1101	-6.750	1_1101	-0.750
0_1110	-6.375	1_1110	-0.375
0_1111	-6.000	1_1111	0.000

Table 34 3D Surround Forward Gain and Cross Gain Range

### **DF1 FILTER**



The DF1 Filter function is implemented in the ADC Signal Enhancement path.

The Direct-Form 1 (DF1) filter can be used to implement a wide variety of user-defined algorithms. Typical applications of this function include low-shelf, high-shelf or all-pass filters. (A low-shelf filter boosts or attenuates low frequencies; a high-shelf filter boosts or attenuates high frequencies. All-pass filters can be defined which pass all frequencies, but adjust the phase response of the signal.)

One of the recommended uses for the DF1 filter is as a low-shelf filter compensating for low frequency effects in the 3D Surround function. In this case, the DF1 filter should provide gain at low frequencies (eg. below 2kHz). An example low-shelf filter response is illustrated in Figure 26.

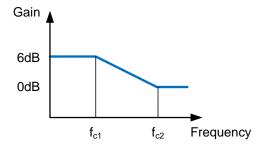


Figure 26 DF1 Low Shelf Filter Response



The Direct-Form 1 (DF1) standard filter is illustrated in Figure 27. All of the filter coefficients are programmable for the left and right channels independently, but DF1 can also be configured for both channels to share the filter coefficients from one or other of the channels. The default coefficients give a transparent filter response.

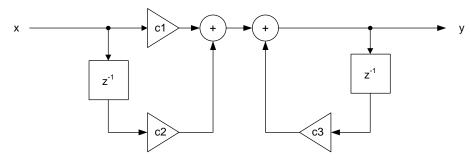


Figure 27 Direct-Form 1 Standard Filter Structure

The DF1 response is defined by the following equations:

$$y[n] = c_1 x[n] + c_2 x[n-1] + c_3 y[n-1]$$

$$H = \frac{y}{x} = \frac{c_1 + c_2 z^{-1}}{1 - c_3 z^{-1}}$$

The DF1 filter is enabled on the ADC signal path using the DF1\_ENA register bit defined in Table 35.

The DF1 filter can be configured for both channels to use the same filter coefficients; this is selected by setting the DF1\_SHARED\_COEFF register bit. When this bit is set, then the applicable coefficients are selected using DF1\_SHARED\_COEFF\_SEL; it is possible to select either the left or right channel coefficients.

The DF1 filter can be used to implement very complex response patterns, with specific phase and gain responses at different frequencies. Typical applications of this type of filter include refinements or compensations to the 3D Surround, or other user-selected filters.

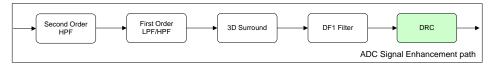
For the derivation of the DF1 Filter coefficients (registers R257 to R259 and for the left channel, R260 to R262 for the right channel), refer to the WISCE™ configuration tool supplied with the WM8963 Evaluation Kit.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R256 (0100h) DF1	2	DF1_SHARED_ COEFF	0	DF1 Shared Coefficients Enable 0 = Disabled 1 = Enabled
	1	DF1_SHARED_ COEFF_SEL	0	DF1 Shared Coefficients Select 0 = Both channels use left coefficients 1 = Both channels use right coefficients
	0	DF1_ENA	0	DF1 Enable in ADC path 0 = Disabled 1 = Enabled

Table 35 Direct Form 1 (DF1) Filtering



### **DYNAMIC RANGE CONTROL (DRC)**



The dynamic range controller (DRC) is a circuit which can be enabled in either the digital record (ADC) or the digital playback (DAC) path of the WM8963. Note that the DRC cannot be enabled in both signal paths at the same time.

The function of the DRC is to adjust the signal gain in conditions where the input amplitude is unknown or varies over a wide range, e.g. when recording from microphones built into a handheld system.

The DRC can apply Compression and Automatic Level Control to the signal path. It incorporates 'anti-clip' and 'quick release' features for handling transients in order to improve intelligibility in the presence of loud impulsive noises.

The DRC also incorporates a Noise Gate function, which provides additional attenuation of very low-level input signals. This means that the signal path is quiet when no signal is present, giving an improvement in background noise level under these conditions.

The DRC is enabled using DRC\_ENA, as described in Table 36. The DRC is selected in the ADC signal path by setting DRC\_MODE = 0.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC 1	1	DRC_MODE	0	DRC path select 0 = ADC path 1 = DAC path
	0	DRC_ENA	0	DRC Enable 0 = Disabled 1 = Enabled

Table 36 DRC Mode and Enable

# DRC COMPRESSION / EXPANSION / LIMITING

The DRC supports two different compression regions, separated by a "Knee" at a specific input amplitude. In the region above the knee, the compression slope DRC\_HI\_COMP applies; in the region below the knee, the compression slope DRC LO COMP applies.

The DRC also supports a noise gate region, where low-level input signals are heavily attenuated. This function can be enabled or disabled according to the application requirements. The DRC response in this region is defined by the expansion slope DRC\_NG\_EXP.

For additional attenuation of signals in the noise gate region, an additional "knee" can be defined (shown as "Knee2" in Figure 28). When this knee is enabled, this introduces an infinitely steep dropoff in the DRC response pattern between the DRC\_LO\_COMP and DRC\_NG\_EXP regions.

The overall DRC compression characteristic in "steady state" (i.e. where the input amplitude is near-constant) is illustrated in Figure 28.

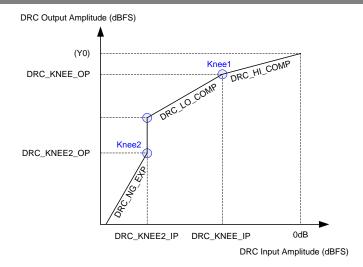


Figure 28 DRC Response Characteristic

The slope of the DRC response is determined by register fields DRC\_HI\_COMP and DRC\_LO\_COMP. A slope of 1 indicates constant gain in this region. A slope less than 1 represents compression (i.e. a change in input amplitude produces only a smaller change in output amplitude). A slope of 0 indicates that the target output amplitude is the same across a range of input amplitudes; this is infinite compression.

When the noise gate is enabled, the DRC response in this region is determined by the DRC\_NG\_EXP register. A slope of 1 indicates constant gain in this region. A slope greater than 1 represents expansion (i.e. a change in input amplitude produces a larger change in output amplitude).

When the DRC\_KNEE2\_OP knee is enabled ("Knee2" in Figure 28), this introduces the vertical line in the response pattern illustrated, resulting in infinitely steep attenuation at this point in the response.

The DDC n		~ " ~	liatad	:	Table	27
The DRC pa	arameters	are	listea	111	rabie	<b>31.</b>

REF	PARAMETER	DESCRIPTION			
1	DRC_KNEE_IP	Input level at Knee1 (dB)			
2	DRC_KNEE_OP	Output level at Knee2 (dB)			
3	DRC_HI_COMP	Compression ratio above Knee1			
4	DRC_LO_COMP	Compression ratio below Knee1			
5	DRC_KNEE2_IP	Input level at Knee2 (dB)			
6	DRC_NG_EXP	Expansion ratio below Knee2			
7	DRC_KNEE2_OP	Output level at Knee2 (dB)			

Table 37 DRC Response Parameters

The noise gate is enabled when the DRC\_NG\_ENA register is set. When the noise gate is disabled, parameters 5, 6, and 7 above are ignored, and the DRC\_LO\_COMP slope applies to all input signal levels below Knee1.

The DRC\_KNEE2\_OP knee is enabled when the DRC\_KNEE2\_OP\_ENA register is set. When this bit is not set, then parameter 7 above is ignored, and the Knee2 position always coincides with the low end of the DRC\_LO\_COMP region.

The "Knee1" point in Figure 28 is determined by register fields DRC\_KNEE\_IP and DRC\_KNEE\_OP.

Parameter Y0, the output level for a 0dB input, is not specified directly, but can be calculated from the other parameters, using the equation:

Y0 = DRC\_KNEE\_OP - (DRC\_KNEE\_IP x DRC\_HI\_COMP)

The DRC Compression / Expansion / Limiting parameters are defined in Table 38.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC1	7	DRC_NG_ENA	0	DRC Noise Gate Enable 0 = Disabled 1 = Enabled
	4	DRC_KNEE2_O P_ENA	0	DRC_KNEE2_OP Enable 0 = Disabled 1 = Enabled
R278 (0116h) DRC 3	7:6	DRC_NG_EXP [1:0]	00	Noise Gate slope 00 = 1 (no expansion) 01 = 2 10 = 4 11 = 8
	5:3	DRC_HI_COMP [2:0]	011	Compressor slope (upper region)  000 = 1 (no compression)  001 = 1/2  010 = 1/4  011 = 1/8 (default)  100 = 1/16  101 = 0 (ALC Mode)  110 = Reserved  111 = Reserved
	2:0	DRC_LO_COMP [2:0]	000	Compressor slope (lower region) 000 = 1 (no compression) 001 = 1/2 010 = 1/4 011 = 1/8 100 = 0 101 to 111 = Reserved
R279 (0117h) DRC 4	10:5	DRC_KNEE_IP [5:0]	000000	Input signal level at the Compressor 'Knee'.  000000 = 0dB  000001 = -0.75dB  000010 = -1.5dB  (-0.75dB steps)  111100 = -45dB  111101 to 111111 = Reserved
	4:0	DRC_KNEE_OP [4:0]	00000	Output signal at the Compressor 'Knee'.  00000 = 0dB  00001 = -0.75dB  00010 = -1.5dB  (-0.75dB steps)  11110 = -22.5dB  11111 = Reserved
R280 (0117h) DRC 4	9:5	DRC_KNEE2_IP [4:0]	00000	Input signal level at the Noise Gate threshold 'Knee2'.  00000 = -36dB  00001 = -37.5dB  00010 = -39dB  (-1.5dB steps)  11110 = -81dB  11111 = -82.5dB  Only applicable when DRC_NG_ENA = 1.
	4:0	DRC_KNEE2_O P [4:0]	00000	Output signal at the Noise Gate threshold 'Knee2'. 00000 = -30dB 00001 = -31.5dB 00010 = -33dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				(-1.5dB steps) 11110 = -75dB 11111 = -76.5dB
				Only applicable when DRC_KNEE2_OP_ENA = 1.

Table 38 DRC Control Registers

### **DRC GAIN LIMITS**

The minimum and maximum gain applied by the DRC is set by register fields DRC\_MINGAIN, DRC\_MAXGAIN and DRC\_NG\_MINGAIN. These limits can be used to alter the DRC response from that illustrated in Figure 28. If the range between maximum and minimum gain is reduced, then the extent of the dynamic range control is reduced.

The minimum gain in the Compression regions of the DRC response is set by DRC\_MINGAIN. The minimum gain in the Noise Gate region is set by DRC\_NG\_MINGAIN. The minimum gain limit prevents excessive attenuation of the signal path.

The maximum gain limit set by DRC\_MAXGAIN prevents quiet signals (or silence) from being excessively amplified.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R277 (0115h) DRC 2	4:2	DRC_MINGAIN [2:0]	001	Minimum gain the DRC can use to attenuate audio signals 000 = 0dB 001 = -12dB (default) 010 = -18dB 011 = -24dB 100 = -36dB 101 to 111 = Reserved
	1:0	DRC_MAXGAIN [1:0]	01	Maximum gain the DRC can use to boost audio signals (dB) $00 = 12dB$ $01 = 18dB (default)$ $10 = 24dB$ $11 = 36dB$
R278 (0116h) DRC 3	15:12	DRC_NG_MING AIN [3:0]	0000	Minimum gain the DRC can use to attenuate audio signals when the noise gate is active.  0000 = -36dB  0001 = -30dB  0010 = -24dB  0011 = -18dB  0100 = -12dB  0110 = -6dB  0110 = 0dB  0111 = 6dB  1000 = 12dB  1001 = 18dB  1010 = 24dB  1011 = 30dB  1100 to 1111 = Reserved

Table 39 DRC Gain Limits



### DRC DYNAMIC CHARACTERISTICS

The dynamic behaviour determines how quickly the DRC responds to changing signal levels. Note that the DRC responds to the average (RMS) signal amplitude over a period of time.

The DRC\_ATK determines how quickly the DRC gain decreases when the signal amplitude is high. The DRC\_DCY determines how quickly the DRC gain increases when the signal amplitude is low.

These register fields are described in Table 15. Note that the register defaults are suitable for general purpose microphone use.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R277 (0115h)	12:9	DRC_ATK [3:0]	0100	Gain attack rate (seconds/6dB)
DRC Control 2				0000 = Reserved
				0001 = 181us
				0010 = 363us
				0011 = 726us
				0100 = 1.45ms
				0101 = 2.9ms
				0110 = 5.8ms
				0111 = 11.6ms
				1000 = 23.2ms
				1001 = 46.4ms
				1010 = 92.8ms
				1011 = 185.6ms
				1100-1111 = Reserved
	8:5	DRC_DCY [3:0]	1001	Gain decay rate (seconds/6dB)
				0000 = 1.45ms
				0001 = 2.9ms
				0010 = 5.8ms
				0011 = 11.6ms
				0100 = 23.25ms
				0101 = 46.5ms
				0110 = 93ms
				0111 = 186ms
				1000 = 372ms
				1001 = 743ms (default)
				1010 = 1.49s
				1011 = 2.97s
				1100 = 5.94s
				1101 = 11.89s
				1110 = 23.78s
				1111 = 47.56s

Table 40 DRC Time Constants



#### DRC ANTI-CLIP CONTROL

The DRC includes an Anti-Clip feature to avoid signal clipping when the input amplitude rises very quickly. This feature uses a feed-forward technique for early detection of a rising signal level. Signal clipping is avoided by dynamically increasing the gain attack rate when required. The Anti-Clip feature is enabled using the DRC\_ANTICLIP bit.

Note that the feed-forward processing increases the latency in the input signal path. The DRC Anti-Clip control is described in Table 41.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h)	2	DRC_ANTICLIP	1	DRC Anti-clip Enable
DRC Control 1				0 = Disabled
				1 = Enabled

Table 41 DRC Anti-Clip Control

Note that the Anti-Clip feature operates entirely in the digital domain. It cannot be used to prevent signal clipping in the analogue domain nor in the source signal. Analogue clipping can only be prevented by reducing the analogue signal gain or by adjusting the source signal.

# DRC QUICK-RELEASE CONTROL

The DRC includes a Quick-Release feature to handle short transient peaks that are not related to the intended source signal. For example, in handheld microphone recording, transient signal peaks sometimes occur due to user handling, key presses or accidental tapping against the microphone. The Quick Release feature ensures that these transients do not cause the intended signal to be masked by the longer time constants of DRC\_DCY.

The Quick-Release feature is enabled by setting the DRC\_QR bit. When this bit is enabled, the DRC measures the crest factor (peak to RMS ratio) of the input signal. A high crest factor is indicative of a transient peak that may not be related to the intended source signal. If the crest factor exceeds the level set by DRC\_QR\_THR, then the normal decay rate (DRC\_DCY) is ignored and a faster decay rate (DRC\_QR\_DCY) is used instead.

The DRC Quick-Release control bits are described in Table 42.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC 1	3	DRC_QR	1	DRC Quick-release Enable 0 = Disabled 1 = Enabled
R278 (0116h) DRC 3	11:10	DRC_QR_THR [1:0]	00	DRC Quick-release threshold (crest factor in dB) $00 = 12dB$ $01 = 18dB$ $10 = 24dB$ $11 = 30dB$
	9:8	DRC_QR_DCY [1:0]	00	DRC Quick-release decay rate (seconds/6dB) 00 = 0.725ms 01 = 1.45ms 10 = 5.8ms 11 = reserved

Table 42 DRC Quick-Release Control



### **DRC SIGNAL ACTIVITY DETECT**

The DRC incorporates a configurable signal detect function, allowing the signal level at the DRC input to be monitored and to be used to trigger other events. This can be used to detect the presence of a microphone signal on an ADC channel, or can be used to detect an audio signal received over the digital audio interface.

The Peak signal level or the RMS signal level of the DRC input can be selected as the detection threshold. When the threshold condition is exceeded, an interrupt can be generated. See "Interrupts" for further details.

When the DRC is enabled, then signal activity detection can be enabled by setting the DRC\_SIG\_DET register bit. The applicable threshold can be defined either as a Peak level (Crest Factor) or an RMS level, depending on the DRC\_SIG\_DET\_MODE register bit. When Peak level is selected, the threshold is determined by DRC\_SIG\_DET\_PK, which defines the applicable Crest Factor (Peak to RMS ratio) threshold. If RMS level is selected, then the threshold is set using DRC\_SIG\_DET\_RMS. These register fields are described in Table 43.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC1	14:10	DRC_SIG_DET_ RMS [4:0]	00000	DRC Signal Detect RMS Threshold. This is the RMS signal level for signal detect to be indicated when DRC_SIG_DET_MODE=1.  00000 = -27dB  00001 = -28.5dB (1.5dB steps)  11110 = -72dB  11111 = -73.5dB
	9:8	DRC_SIG_DET_ PK [1:0]	00	DRC Signal Detect Peak Threshold. This is the Peak/RMS ratio, or Crest Factor, level for signal detect to be indicated when DRC_SIG_DET_MODE=0. 00 = 14dB 01 = 20dB 10 = 26dB 11 = 32dB
	6	DRC_SIG_DET_ MODE	0	DRC Signal Detect Mode 0 = Peak threshold mode 1 = RMS threshold mode
	5	DRC_SIG_DET	0	DRC Signal Detect Enable 0 = Disabled 1 = Enabled

Table 43 DRC Signal Activity Detect Interrupt Control



# **DIGITAL MIXING**

The ADC and DAC data can be combined in various ways to support a range of different usage modes.

Under default conditions, data from the Left and Right ADCs is routed to the Left and Right channels respectively of the digital audio interface. The channels can be swapped if required and digital inversion of either signal is also possible. See "Digital Audio Interface" for more information on the audio interface.

By default, the Left and Right input channels of the digital audio interface are routed to the Left and Right DACs respectively on the WM8963. The channels can be swapped if required and digital inversion of either signal is also possible.

A mono mix of the two audio channels into a single DAC can be selected, as described in the "Digital-to-Analogue Converter (DAC)" section.

Digital sidetone from the ADCs can also be selectively mixed into the DAC output path, as described later in this section.

#### **DIGITAL MIXING PATHS**

Figure 29 shows the digital mixing paths available in the WM8963 digital core.

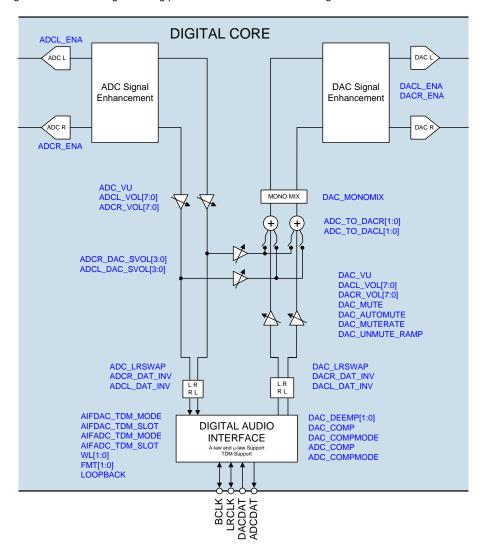


Figure 29 Digital Mixing Paths



The polarity of each ADC output signal can be changed under software control using the ADCR\_DAT\_INV and ADCL\_DAT\_INV register bits. The ADC\_LRSWAP register bit may be used to swap the left and right digital audio interface data. These register bits are described in Table 44.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC and DAC Control 1	6	ADCR_DAT_INV	0	Right ADC Invert 0 = Right ADC output not inverted 1 = Right ADC output inverted
	5	ADCL_DAT_INV	0	Left ADC Invert  0 = Left ADC output not inverted  1 = Left ADC output inverted
R7 (07h) Audio Interface 0	8	ADC_LRSWAP	0	Swap left/right ADC data on the interface 0 = Normal 1 = ADCDAT channels swapped

Table 44 ADC Routing and Control

The input data source for each DAC can be controlled using the DAC\_LRSWAP register bit; this swaps the left and right channel input data within the digital audio interface. The polarity of each DAC input may also be modified using register bits DACR\_DAT\_INV and DACL\_DAT\_INV. These register bits are described in Table 45.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R6 (06h) ADC and DAC Control 2	6	DACR_DAT_INV	0	Right DAC Invert 0 = Right DAC input not inverted 1 = Right DAC input inverted
	5	DACL_DAT_INV	0	Left DAC Invert  0 = Left DAC input not inverted  1 = Left DAC input inverted
R7 (07h) Audio Interface 0	5	DAC_LRSWAP	0	Swap left/right DAC data on the interface 0 = Normal 1 = DACDAT channels swapped

Table 45 DAC Routing and Control

### **DIGITAL SIDETONE**

Digital sidetone mixing (from ADC output into DAC input) is available. Digital data from either left or right ADC can be mixed with the audio interface data on the left and right DAC channels. Sidetone data is taken from the ADC high-pass filter output, to reduce low frequency noise in the sidetone (e.g. wind noise or mechanical vibration).

When using the digital sidetone, it is recommended that the ADCs are enabled before un-muting the DACs to prevent pop noise. The DAC volumes and sidetone volumes should be set to an appropriate level to avoid clipping at the DAC input.

When digital sidetone is used, it is recommended that the Charge Pump operates in Register Control mode only (CP\_DYN\_PWR = 0). If Dynamic Control mode (CP\_DYN\_PWR = 1) is used, the headphone output may be clipped. See "Charge Pump" for details.

The digital sidetone is controlled as shown in Table 46.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R57 (39h) DAC DSP Mixing (1)	7:4	ADCR_DAC_SV OL [3:0]	0000	Right ADC Digital Sidetone Volume $0000 = -36 dB$ $0001 = -33 dB$ $( 3dB steps)$ $1011 = -3 dB$ $11XX = 0 dB$ (See Table 47 for volume range)
	3:2	ADC_TO_DACR [1:0]	00	Right DAC Digital Sidetone Source 00 = No sidetone 01 = Left ADC 10 = Right ADC 11 = No sidetone
R58 (3Ah) DAC DSP Mixing (2)	7:4	ADCL_DAC_SV OL [3:0]	0000	Left ADC Digital Sidetone Volume $0000 = -36dB$ $0001 = -33dB$ $( 3dB steps)$ $1011 = -3dB$ $11XX = 0dB$ (See Table 47 for volume range)
	3:2	ADC_TO_DACL [1:0]	00	Left DAC Digital Sidetone Source  00 = No sidetone  01 = Left ADC  10 = Right ADC  11 = No sidetone

**Table 46 Digital Sidetone Control** 

The digital sidetone volume settings are shown in Table 47.

ADCR_DAC_SVOL, ADCL_DAC_SVOL	SIDETONE VOLUME
0000	-36
0001	-33
0010	-30
0011	-27
0100	-24
0101	-21
0110	-18
0111	-15
1000	-12
1001	-9
1010	-6
1011	-3
1100	0
1101	0
1110	0
1111	0

Table 47 Digital Sidetone Volume



### **T-LOOPBACK**

The T-Loopback function provides a specialised mode for use in communications applications such as VOIP handset configurations. The T-Loopback configuration provides a mono ADC and mono DAC signal to be output via the Digital Audio Interface transmit path. This allows Acoustic Echo Cancellation to be performed using difference algorithms implemented on an external processor.

T-Loopback is enabled by setting the TLB ENA register bit, as described in Table 49.

When T-Loopback is enabled, the Digital Audio Interface outputs are configured according to the TLB\_MODE bit, as described below.

DESCRIPTION	LEFT AIF OUTPUT	RIGHT AIF OUTPUT
TLB_MODE = 0	Left ADC	(Left DAC + Right DAC)/2
TLB_MODE = 1	(Left DAC + Right DAC)/2	Right ADC

**Table 48 T-Loopback Mode Select** 

Note that the Left ADC and Right ADC signals can be digitally mixed, if required. This enables the sum of the Left and Right ADC channels to be output in T-Loopback. The ADC Monomix feature is described in the "ADC Monomix" section.

Note that the Left DAC and Right DAC signals used in the T-Loopback are also controlled by the DAC Digital Volume controls (see "Digital-to-Analogue Converter (DAC)". It is possible to output just a single DAC channel in T-Loopback mode by setting the Digital Volume to zero in the unwanted channel.

The register bits associated with T-Loopback are described in Table 49.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R285 (011Dh) Tloopback	1	TLB_ENA	0	T-Loopback Enable 0 = Disabled 1 = Enabled
	0	TLB_MODE	0	T-Loopback Mode Select  0: Left AIF Output = Left ADC; Right AIF Output = (Left DAC + Right DAC) / 2  1: Left AIF Output = (Left DAC + Right DAC) / 2; Right AIF Output = Right ADC

Table 49 T-Loopback Control

The affected signal paths when T-Loopback is enabled (TLB\_ENA = 1, TLB\_MODE=1) are illustrated in Figure 30.



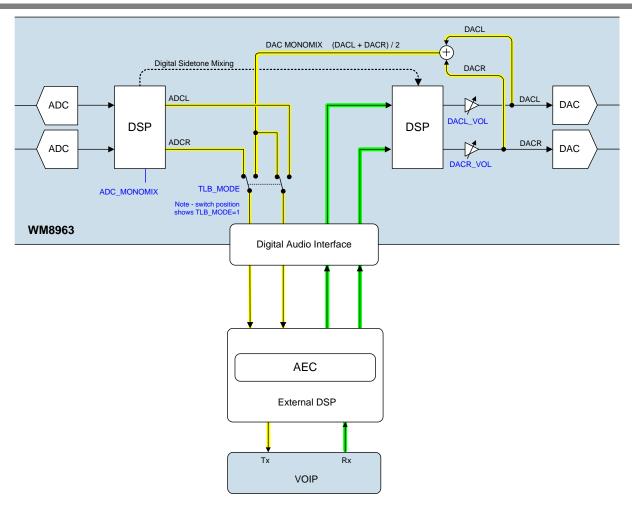


Figure 30 T-Loopback Signal Paths



# **DAC SIGNAL PATH ENHANCEMENTS**

The DAC signal path incorporates a number of sound enhancement features, as illustrated in Figure 31. These features are described more fully in the following sections.

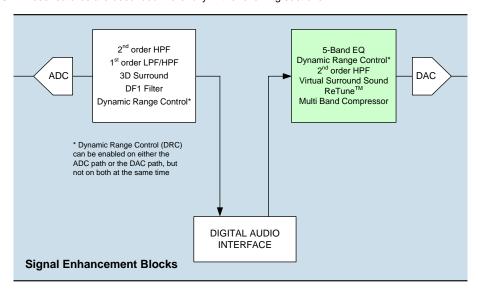
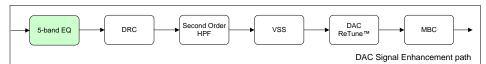


Figure 31 DAC Signal Enhancements

### 5-BAND EQ



The 5-band EQ function is implemented in the DAC Signal Enhancement path.

The 5-band EQ can be used to support user preferences for different music types, such as allowing selection of 'rock', 'dance', 'classical' or other user-defined EQ profiles. The 5-band EQ can also be used to provide compensation for imperfect characteristics of other components in the audio chain, such as the loudspeaker in portable applications in particular.

Note that the functionality of the 5-band EQ has similarities to some of the other DAC signal enhancements; it is important to select the most appropriate processing block for each requirement. The 5-band EQ provides a basic level of signal control, whilst the other enhancements can provide superior performance in many cases.

Frequency compensation of loudspeakers and other components can be implemented using the DAC ReTune function, which provides a more powerful capability to normalise the frequency response; this is achieved through the use of calibrated measurement procedures. The 5-band EQ provides a simpler and coarser type of signal control.

Reduction of bass frequencies (removing signal content that the speaker is unable to reproduce) can be implemented using the 2<sup>nd</sup> order High Pass Filter (DAC HPF); this provides greater attenuation of the bass frequencies, without affecting the desired pass-band.

Note that, when using the 5-band EQ to boost any frequency band, it is recommended to take care not to introduce distortion, taking into account the gain that may be applied by other audio enhancement functions.

The 5-band EQ allows the gain within five frequency bands to be controlled. The upper and lower frequency bands are controlled by low-pass and high-pass filters respectively. The middle three frequency bands are notch filters.

The 5-band EQ is enabled by setting the EQ\_ENA register as described in Table 51.

In default mode, the cut-off / centre frequencies are fixed as described in Table 50. The filter bandwidths are also fixed in this mode. The gain of the individual bands (-12dB to +12dB) can be controlled as described in Table 52.



The cut-off / centre frequencies noted in Table 50 are applicable to a sample rate of 48kHz. Note that, when using other sample rates, these frequencies will be scaled in proportion to the selected sample rate (see "Clocking and Sample Rates").

EQ BAND	CUT-OFF/CENTRE FREQUENCY
1	100 Hz
2	300 Hz
3	875 Hz
4	2400 Hz
5	6900 Hz

Table 50 EQ Band Cut-off / Centre Frequencies

The gain for each of the five EQ bands on each of the channels is individually programmable using the register bits described in Table 51. The gain in each band on each channel is controllable in 1dB steps from -12dB to +12dB.

The 5-band EQ can be configured for both channels to use the same configuration settings; this is selected by setting the EQ\_SHARED\_COEFF register bit. When this bit is set, then the applicable coefficients are selected using EQ\_SHARED\_COEFF\_SEL; it is possible to select either the left or right channel coefficients.

It is also possible for the user to define the cut-off/centre frequencies and the filter bandwidth for each EQ band, in addition to the gain controls already defined. This enables the EQ to be accurately customised for a specific transducer characteristic or desired sound profile.

For the derivation of the 5-Band EQ configuration parameters in registers R338 to R355 (Left channel) and R358 to R375 (Right channel), refer to the WISCE™ configuration tool supplied with the WM8963 Evaluation Kit.





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R335 (014Fh) EQ1	2	EQ_SHARED_C OEFF	1	5-Band EQ Shared Coefficient enable 0 = Right and Left channels use unique coefficients 1 = Left and right channels share filter coefficients
	1	EQ_SHARED_C OEFF_SEL	0	5-Band EQ Shared Coefficient select 0 = Both channels use the left channel filter coefficients 1 = Both channels use the right channel filter coefficients
	0	EQ_ENA	0	5-Band EQ Enable 0 = Disabled 1 = Enabled
R336 (0150h) EQ2	15:11	EQL_B1_GAIN [4:0]	01100	Left Channel Band 1 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range
	10:6	EQL_B2_GAIN [4:0]	01100	Left Channel Band 2 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range
	5:1	EQL_B3_GAIN [4:0]	01100	Left Channel Band 3 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range
R337 (0151h) EQ2	15:11	EQL_B4_GAIN [4:0]	01100	Left Channel Band 4 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved  See Table 52 for the full range
	10:6	EQL_B5_GAIN [4:0]	01100	Left Channel Band 5 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range
R356 (0164h) EQ2	15:11	EQR_B1_GAIN [4:0]	01100	Right Channel Band 1 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved  See Table 52 for the full range



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	10:6	EQR_B2_GAIN [4:0]	01100	Right Channel Band 2 EQ Gain 0_0000 = -12dB 0_0001 = -11dB 1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved
	5:1	EQR_B3_GAIN [4:0]	01100	See Table 52 for the full range  Right Channel Band 3 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved  See Table 52 for the full range
R357 (0165h) EQ2	15:11	11 EQR_B4_GAIN 01100 [4:0]		Right Channel Band 4 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range
	10:6	EQR_B5_GAIN [4:0]	01100	Right Channel Band 5 EQ Gain 0_0000 = -12dB 0_0001 = -11dB 1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved See Table 52 for the full range

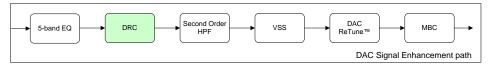
Table 51 5-Band EQ Control

5-BAND EQ GAIN	GAIN (dB)	5-BAND EQ GAIN	GAIN (dB)
0_0000	-12	0_1101	+1
0_0001	-11	0_1110	+2
0_0010	-10	0_1111	+3
0_0011	-9	1_0000	+4
0_0100	-8	1_0001	+5
0_0101	-7	1_0010	+6
0_0110	-6	1_0011	+7
0_0111	-5	1_0100	+8
0_1000	-4	1_0101	+9
0_1001	-3	1_0110	+10
0_1010	-2	1_0111	+11
0_1011	-1	1_1000	+12
0_1100	0	1_1001 to 1_1111	Reserved

Table 52 5-Band EQ Gain Range



### **DYNAMIC RANGE CONTROL (DRC)**



The dynamic range controller (DRC) is a circuit which can be enabled in either the digital record (ADC) or the digital playback (DAC) path of the WM8963. Note that the DRC cannot be enabled in both signal paths at the same time.

The function of the DRC is to adjust the signal gain in conditions where the input amplitude is unknown or varies over a wide range, e.g. when recording from microphones built into a handheld system.

The DRC can apply Compression and Automatic Level Control to the signal path. It incorporates 'anti-clip' and 'quick release' features for handling transients in order to improve intelligibility in the presence of loud impulsive noises.

The DRC also incorporates a Noise Gate function, which provides additional attenuation of very low-level input signals. This means that the signal path is quiet when no signal is present, giving an improvement in background noise level under these conditions.

The DRC is enabled using DRC\_ENA, as described in Table 53. The DRC is selected in the DAC signal path by setting DRC\_MODE = 1.

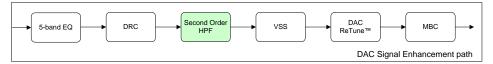
Additional registers for configuring the DRC are described in the "ADC Signal Path Enhancements" section.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC 1	h) 1 DRC_MODE 0		0	DRC path select 0 = ADC path 1 = DAC path
	0	DRC_ENA	0	DRC Enable 0 = Disabled 1 = Enabled

Table 53 DRC Mode and Enable



#### DAC SECOND ORDER HIGH-PASS FILTER



The 2<sup>nd</sup> order High-Pass Filter (HPF) is part of the DAC Signal Enhancement path.

The DAC High-Pass filter is provided to remove DC offsets and low frequencies from the DAC signal path. This is an important function as DC offsets in the audio signal will reduce the signal headroom and increase power consumption. DC offsets and low frequency signals that are outside the capabilities of the loudspeaker will result in audible distortion and can cause damage to speakers or headphones.

The cut-off frequency of the DAC High-Pass filter should be set to attenuate the frequencies that the speaker cannot reproduce, but without unnecessarily removing higher frequencies that can be supported. The 2<sup>nd</sup> order cut-off slope of 12dB per octave provides good selectivity between the frequencies to be cut and the frequencies to be retained.

The DAC High-Pass filter is particularly recommended for use with the VSS, DAC ReTune, and MBC functions in order to prevent distortion and speaker damage.

Before the DAC High-Pass filter is enabled, it must be initialised and configured using the DSP2\_ENA bit described in Table 54. Note that this bit only needs to be enabled once before using any or all of DAC ReTune, DAC HPF, VSS or MBC.

Note that specific sequences must be followed when enabling or configuring DAC ReTune, DAC HPF, VSS and MBC functions (see "DSP Signal Enhancements").

The 2<sup>nd</sup> order High Pass Filter comprises two 1<sup>st</sup> order filters, which are enabled using the HPF1\_ENA and HPF2\_ENA register bits as described in Table 54. Either one of the filters, or both filters, may be enabled. Each filter provides a cut-off slope of 6dB per octave; when both filters are enabled together, the combined effect is a second-order filter, with a cut-off slope of 12dB per octave.

Note that the DAC high pass filters cannot be enabled unless one or more other sound enhancement functions is enabled. If HPF1\_ENA = 1 or HPF2\_ENA = 1, then at least one other of the enable bits in Register R16389 must also be set (ie. RTN\_DAC\_ENA, VSS\_ENA or MBC\_ENA).

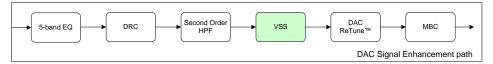
For the derivation of the High-Pass Filter configuration parameters in registers R17408 and R17409, refer to the WISCE™ configuration tool supplied with the WM8963 Evaluation Kit. Note that both filters (HPF1 and HPF2) use the same configuration parameters.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (R300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of  DAC ReTune, DAC HPF, VSS or  MBC is enabled. It must remain set whenever any of these functions is enabled.
R16389 (4005h) SOUNDSTAGE _ENABLES_0	2	HPF2_ENA	0	High-Pass Filter (HPF2) enable 0 = Disabled 1 = Enabled
	1	HPF1_ENA	0	High Pass Filter (HPF1) enable 0 = Disabled 1 = Enabled

Table 54 DAC High Pass Filter Enable



### VIRTUAL SURROUND SOUND (VSS)



The Virtual Surround Sound (VSS) function is part of the DAC Signal Enhancement path.

Virtual Sound Sound (VSS) is a digital processing function that creates a perception of wider speaker separation, generating a rich and immersive listening experience. It is aimed at portable applications, but is effective on larger systems also. Note that VSS is not suited to single-speaker systems, nor to headphone outputs.

Portable applications, where the speaker separation is small, suffer from significant acoustic crosstalk, where the Right speaker output is heard strongly in the Left ear, and vice versa. The VSS algorithms are designed to minimise these crosstalk effects, thus increasing the stereo experience. The VSS process is finely tuned to produce a compelling three-dimensional experience, but without the listening fatigue associated with some other stereo enhancement systems.

The VSS algorithms (and the user perception) are most effective at high frequencies; low frequency content is therefore configured to bypass the VSS crosstalk processing. The crossover frequency (for the low-frequency bypass) is adjustable, enabling the user to trade-off the stereo widening effect against the required degree of integrity in the original audio.

The VSS algorithms are programmable and can be optimised for specific application or user geometries. It is recommended to use the DAC HPF in conjunction with VSS in order to prevent distortion and speaker damage.

Before VSS is enabled, it must be initialised and configured using the DSP2\_ENA bit described in Table 55. Note that this bit only needs to be enabled once before using any or all of DAC ReTune, DAC HPF, VSS or MBC.

Note that specific sequences must be followed when enabling or configuring DAC ReTune, DAC HPF, VSS and MBC functions (see "DSP Signal Enhancements").

VSS is enabled using the VSS\_ENA register bit as described in Table 55.

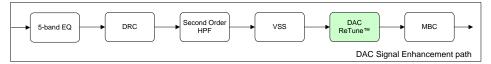
It is possible to configure the VSS function to create a stereo effect that is optimised and tailored specifically for a particular application. For the derivation of the VSS configuration parameters in registers R19456 to R19603, refer to the WISCE™ configuration tool supplied with the WM8963 Evaluation Kit. Note that DSP2\_ENA must be enabled before there is any type of access of any of the parameters associated with VSS.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (R300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of DAC ReTune, DAC HPF, VSS or MBC is enabled. It must remain set whenever any of these functions is enabled.
R16389 (4005h) SOUNDSTAG E_ENABLES_ 0	0	VSS_ENA	0	Virtual Surround Sound (VSS) enable 0 = Disabled 1 = Enabled

Table 55 Virtual Surround Sound (VSS) Enable



### **DAC RETUNE**



The ReTune function is part of the DAC Signal Enhancement paths. Unique coefficient sets are supported.

ReTune™ is an advanced feature that is intended to perform frequency linearisation according to the particular needs of the application microphone, loudspeaker or housing. The ReTune algorithms can provide acoustic equalisation and selective phase (delay) control of specific frequency bands. In a typical application, ReTune™ is used to flatten the response across the audio frequency band. ReTune™ can also be configured to achieve other response patterns if required.

It is particularly recommended to use ReTune™ to flatten the DAC signal path response when using the VSS or MBC functions. The signal processing algorithms of the VSS and MBC functions assume a flat system response, and the performance of these enhancements will be compromised if the speaker response is poor or uncalibrated.

Note that, when using ReTune™ to boost any frequency band, it is recommended to take care not to introduce distortion, taking into account the gain that may be applied by other audio enhancement functions.

It is recommended to use the DAC HPF in conjunction with DAC ReTune in order to prevent distortion and speaker damage.

Before ReTune<sup>™</sup> is enabled, it must be initialised and configured using the DSP2\_ENA bit described in Table 56. Note that this bit only needs to be enabled once before using any or all of DAC ReTune, DAC HPF, VSS or MBC.

Note that specific sequences must be followed when enabling or configuring DAC ReTune, DAC HPF, VSS and MBC functions (see "DSP Signal Enhancements").

The ReTune function is enabled on the DAC path using the RTN\_DAC\_ENA register bit as described in Table 56. Under default conditions, the Left and Right channels each use unique tuning coefficients. When the DAC\_RETUNE\_SCV register is set, then both channels are controlled by the Right channel coefficients.

For the derivation of DAC ReTune configuration parameters in registers R17920 to R19007, the Cirrus Logic WISCE™ software must be used to analyse the requirements of the application (refer to WISCE™ for further information.) If desired, one or more sets of register coefficients might be derived for different operating scenarios, and these may be recalled and written to the CODEC registers as required in the target application. The DAC ReTune configuration procedure involves the generation and analysis of test signals as outlined below. Note that DSP2\_ENA must be enabled before there is any type of access of any of the parameters associated with DAC ReTune.

To determine the characteristics of the loudspeaker in an application, a test signal is applied to the target application. A reference microphone is positioned in the normal acoustic path of the loudspeaker, and the received signal is analysed to determine how accurately the loudspeaker has reproduced the test signal.

Note that the ReTune configuration coefficients are specific to a particular speaker or microphone; it is therefore required that the part-to-part variation in these components is small.

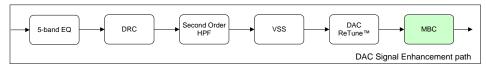


DAC ReTune is controlled	ed using the register hits	as described in Table 56.
	eu usiilu lile redistei bits	as described in Table 50.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (R300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of DAC ReTune, DAC HPF, VSS or MBC is enabled. It must remain set whenever any of these functions is enabled.
R16386 (4002h) RETUNEDAC _SHARED_C OEFF_1	7	DAC_RETUNE_ SCV	0	DAC ReTune Coefficient sharing 0 = Left and Right channels each use unique coefficients 1 = Both channels use the Right Channel coefficients
R16389 (4005h) SOUNDSTAG E_ENABLES_ 0	4	RTN_DAC_ENA	0	DAC ReTune enable 0 = disabled 1 = enabled

Table 56 DAC ReTune Enable

### **MULTIBAND COMPRESSOR (MBC)**



The Multiband Compressor (MBC) function is part of the DAC Signal Enhancement path.

The MBC uses selective processing of the audio signal to control the loudness; independent gain control algorithms are applied to different audio frequency bands. The effect of this is to increase the perceived loudness of the audio path, producing an enhanced audio signal without overdriving the output transducers (eg. loudspeakers).

The most significant advantage of multiband compression is that a signal peak in one frequency band will not cause gain reduction in another frequency band. Similarly, gain can be applied to one frequency band without boosting (and potentially distorting) another. This provides a powerful capability to maximise the loudness of the signal path.

It is recommended to use the DAC HPF in conjunction with the MBC in order to prevent distortion and speaker damage.

Before the MBC is enabled, it must be initialised and configured using the DSP2\_ENA bit described in Table 57. Note that this bit only needs to be enabled once before using any or all of DAC ReTune, DAC HPF, VSS or MBC.

Note that specific sequences must be followed when enabling or configuring DAC ReTune, DAC HPF, VSS and MBC functions (see "DSP Signal Enhancements").

MBC is enabled using the MBC\_ENA register bit as described in Table 57.

The MBC is pre-configured with a default set of parameters, but alternative settings can also be configured. The multiband crossover frequencies, and gain/compression parameters are all adjustable.

For the derivation of the MBC configuration parameters in registers R16896 to R16955, refer to the WISCE<sup>TM</sup> configuration tool supplied with the WM8963 Evaluation Kit. Note that DSP2\_ENA must be enabled before there is any type of access of any of the parameters associated with MBC.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (R300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of DAC ReTune, DAC HPF, VSS or MBC is enabled. It must remain set whenever any of these functions is enabled.
R16389 (4005h) SOUNDSTAGE _ENABLES_0	3	MBC_ENA	0	MBC Enable 0 = Disabled 1 = Enabled

**Table 57 Multiband Compressor Control** 

# **DIGITAL-TO-ANALOGUE CONVERTER (DAC)**

The WM8963 DACs receive digital input data from the digital audio interface. The digital audio data is converted to oversampled bit-streams in the on-chip, true 24-bit digital interpolation filters. The bit-stream data enters two multi-bit, sigma-delta DACs, which convert them to high quality analogue audio signals.

The DACs provide digital volume control with soft mute / un-mute. Digital mono mix and de-emphasis filtering is also supported.

The DACs are enabled by the DACL\_ENA and DACR\_ENA register bits.

The system clock, SYSCLK, must be configured and enabled before either of the DACs is enabled. See "Clocking and Sample Rates" for details of the system clocks.

Note that, when reconfiguring or disabling SYSCLK, the ADCs and DACs must be disabled before setting SYSCLK\_ENA=0.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION	
R26 (1Ah) Pwr Mgmt (2)	8	DACL_ENA	0	Left DAC Enable  0 = Disabled  1 = Enabled  Note that DACL_ENA must be set to 1 when processing left channel data from the DAC or Digital Beep Generator.	
	7	DACR_ENA	0	Right DAC Enable  0 = Disabled  1 = Enabled  Note that DACR_ENA must be set to 1 when processing right channed data from the DAC or Digital Beep Generator.	

Table 58 DAC Enable Control

### **DAC CLOCKING CONTROL**

Clocking for the DACs is derived from SYSCLK. The required clock is enabled when the SYSCLK\_ENA register is set.

The DAC clock rate is configured automatically, according to the SAMPLE\_RATE and MCLK\_RATE registers. See "Clocking and Sample Rates" for further details of the system clocks and associated control registers.

Note that the DAC and the DAC signal path enhancements functions are only supported under specific clocking configurations. The valid clocking ratios for DAC operation are identified in Table 92. See also Table 93 for details of the supported functions for different MCLK / fs ratios.



### **DAC DIGITAL VOLUME CONTROL**

The output level (digital volume) of each DAC can be controlled digitally over a range from -71.625dB to +23.625dB in 0.375dB steps. The level of attenuation for an eight-bit code X is given by:

 $0.375 \times (X-192) \text{ dB for } 1 \le X \le 255;$  MUTE for X = 0

The DAC\_VU bit controls the loading of digital volume control data. When DAC\_VU is set to 0, the DACL\_VOL or DACR\_VOL control data will be loaded into the respective control register, but will not actually change the digital gain setting. Both left and right gain settings are updated when a 1 is written to DAC\_VU. This makes it possible to update the gain of both channels simultaneously.

See "DAC Digital Volume Control" section for a description of the volume update function, the zero cross function and the timeout operation.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R10 (0Ah) Left DAC volume	8	DAC_VU	N/A	DAC Volume Update Writing a 1 to this bit will cause left and right DAC volume to be updated simultaneously
	7:0	DACL_VOL [7:0]	C0h (0dB)	Left DAC Digital Volume Control  00h = Digital Mute  01h = -71.625dB  02h = -71.250dB  0.375dB steps up to  C0h = 0dB (default)   FFh = 23.625dB  (See Table 60 for volume range)
R11 (0Bh) Right DAC volume	8	DAC_VU	N/A	DAC Volume Update Writing a 1 to this bit will cause left and right DAC volume to be updated simultaneously
	7:0	DACR_VOL [7:0]	C0h (0dB)	Right DAC Digital Volume Control  00h = Digital Mute  01h = -71.625dB  02h = -71.250dB  0.375dB steps up to  C0h = 0dB (default)   FFh = 23.625dB  (See Table 60 for volume range)

**Table 59 Digital Volume Control** 



DACL_VOL or		DACL_VOL or	\( -   (-ID)	DACL_VOL or	\/ - I (-ID)	DACL_VOL or	\(\frac{1}{2} \cdot \cdo
DACR_VOL	Volume (dB)	DACR_VOL	Volume (dB)	DACR_VOL	Volume (dB)	DACR_VOL	Volume (dB)
00	MUTE	40 41	-48.000	80	-24.000	C0 C1	0.000
01 02	-71.625 -71.250	42	-47.625 -47.250	81 82	-23.625 -23.250	C2	0.375 0.750
02		43	-47.250 -46.875	83		C3	
03	-70.875 -70.500	43	-46.500	83 84	-22.875 -22.500	C3 C4	1.125 1.500
05	-70.500 -70.125	45	-46.125	85	-22.125	C5	1.875
06	-69.750	46	-45.750	86	-21.750	C6	2.250
06	-69.750 -69.375	47	-45.375	87	-21.750 -21.375	C6 C7	2.625
08	-69.000	48	-45.000	88	-21.000	C8	3.000
09	-68.625	49	-44.625	89	-20.625	C9	3.375
0A	-68.250	4A	-44.250	8A	-20.250	CA	3.750
0B	-67.875	4B	-43.875	8B	-19.875	CB	4.125
0C	-67.500	4C	-43.500	8C	-19.500	CC	4.500
0D	-67.125	4D	-43.125	8D	-19.125	CD	4.875
0E	-66.750	4E	-42.750	8E	-18.750	CE	5.250
0F	-66.375	4F	-42.375	8F	-18.375	CF	5.625
10	-66.000	50	-42.000	90	-18.000	D0	6.000
11	-65.625	51	-41.625	91	-17.625	D1	6.375
12	-65.250	52	-41.250	92	-17.250	D2	6.750
13	-64.875	53	-40.875	93	-16.875	D3	7.125
14	-64.500	54	-40.500	94	-16.500	D4	7.500
15	-64.125	55	-40.125	95	-16.125	D5	7.875
16	-63.750	56	-39.750	96	-15.750	D6	8.250
17	-63.375	57	-39.375	97	-15.375	D7	8.625
18	-63.000	58	-39.000	98	-15.000	D8	9.000
19	-62.625	59	-38.625	99	-14.625	D9	9.375
1A	-62.250	5A	-38.250	9A	-14.250	DA	9.750
1B	-61.875	5B	-37.875	9B	-13.875	DB	10.125
1C	-61.500	5C	-37.500	9C	-13.500	DC	10.500
1D	-61.125	5D	-37.125	9D	-13.125	DD	10.875
1E	-60.750	5E	-36.750	9E	-12.750	DE	11.250
1F	-60.375	5F	-36.375	9F	-12.375	DF	11.625
20	-60.000	60	-36.000	A0	-12.000	E0	12.000
21	-59.625	61	-35.625	A1	-11.625	E1	12.375
22	-59.250	62	-35.250	A2	-11.250	E2	12.750
23	-58.875	63	-34.875	A3	-10.875	E3	13.125
24	-58.500	64	-34.500	A4	-10.500	E4	13.500
25	-58.125	65	-34.125	A5	-10.125	E5	13.875
26	-57.750	66	-33.750	A6	-9.750	E6	14.250
27	-57.375	67	-33.375	A7	-9.375	E7	14.625
28	-57.000	68	-33.000	A8	-9.000	E8	15.000
29	-56.625	69	-32.625	A9	-8.625	E9	15.375
2A	-56.250	6A	-32.250	AA	-8.250	EA	15.750
2B	-55.875	6B	-31.875	AB	-7.875 7.500	EB	16.125
2C 2D	-55.500	6C 6D	-31.500	AC AD	-7.500 -7.125	EC ED	16.500
2E	-55.125 54.750	6E	-31.125	AE AE	-7.125 -6.750	EE	16.875 17.250
2F	-54.750 -54.375	6F	-30.750 -30.375	AE AF	-6.750 -6.375	EF	17.250
30	-54.000	70	-30.000	B0	-6.000	F0	18.000
31	-53.625	70	-29.625	B1	-5.625	F1	18.375
32	-53.250	72	-29.250	B2	-5.250	F2	18.750
33	-52.875	73	-28.875	B3	-4.875	F3	19.125
34	-52.500	74	-28.500	B4	-4.500	F4	19.500
35	-52.125	75	-28.125	B5	-4.125	F5	19.875
36	-51.750	76	-27.750	B6	-3.750	F6	20.250
37	-51.375	77	-27.375	B7	-3.375	F7	20.625
38	-51.000	78	-27.000	B8	-3.000	F8	21.000
39	-50.625	79	-26.625	B9	-2.625	F9	21.375
3A	-50.250	7A	-26.250	BA	-2.250	FA	21.750
3B	-49.875	7B	-25.875	BB	-1.875	FB	22.125
3C	-49.500	7C	-25.500	BC	-1.500	FC	22.500
3D	-49.125	7D	-25.125	BD	-1.125	FD	22.875
3E	-48.750	7E	-24.750	BE	-0.750	FE	23.250
3F	-48.375	7F	-24.375	BF	-0.375	FF	23.625
	,,,,,	•				· · · · · · · · · · · · · · · · · · ·	

Table 60 DAC Digital Volume Range



### DAC SOFT MUTE AND UN-MUTE

The WM8963 has both hard and soft mute functions. If DAC\_MUTE\_RAMP=0, any muting of the output volume is instantaneous.

The WM8963 also has a soft mute function which, when enabled (DAC\_MUTE\_RAMP=1), gradually attenuates the volume of the digital signal to zero. When soft mute is disabled, the gain will either gradually ramp back up to the digital gain setting, or return instantly to the digital gain setting, depending on the DAC\_UNMUTE\_RAMP register bit.

The DAC is soft-muted by default. To play back an audio signal, this function must first be disabled by setting the DAC\_MUTE bit to zero.

DAC\_UNMUTE\_RAMP would typically be enabled when using soft mute during playback of audio data so that when soft mute is then disabled, the sudden volume increase will not create pop noise by jumping immediately to the previous volume level (e.g. resuming playback after pausing during a track).

DAC\_UNMUTE\_RAMP would typically be disabled when un-muting at the start of a digital music file, so that the first part of the track is not attenuated (e.g. when starting playback of a new track, or resuming playback after pausing between tracks).

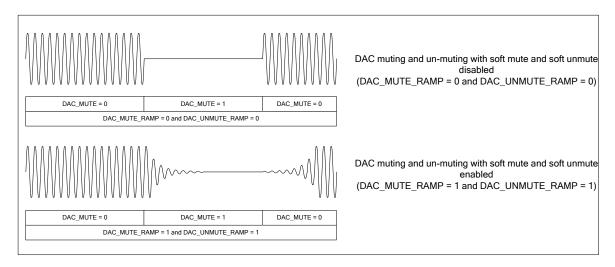


Figure 32 DAC Mute Control



The volume ramp rate during soft mute and un-mute is controlled by the DAC\_MUTERATE bit as shown in Table 61.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC and DAC Control 1	4	DAC_MUTE_RAMP	1	DAC Soft Mute Control 0 = Muting the DAC (DAC_MUTE = 1) will cause the volume to change immediately to mute. 1 = Muting the DAC (DAC_MUTE = 1) will cause the volume to ramp down gradually to mute.
	3	DAC_MUTE	1	Digital DAC Mute  0 = Un-mute  1 = Mute  Note that this bit also exists in  R49. Reading or writing to either location has the same effect.
R49 (31h) Class D Control (1)	4	DAC_MUTE	1	Digital DAC Mute  0 = Un-mute  1 = Mute  Note that this bit also exists in  R5. Reading or writing to either location has the same effect.
R6 (06h) ADC and DAC Control 2	3	DAC_UNMUTE_RAMP	1	DAC Soft Unmute Control 0 = Unmuting the DAC (DAC_MUTE = 0) will cause the volume to change immediately to the DACL_VOL/DACR_VOL settings. 1 = Unmuting the DAC (DAC_MUTE = 0) will cause the volume to ramp up gradually to the DACL_VOL/DACR_VOL settings.
	2	DAC_MUTERATE	0	DAC Soft Mute Ramp Rate  0 = Fast ramp (maximum ramp time 10.7ms)  1 = Slow ramp (maximum ramp time 171ms).  Note that the ramp rate scales with sample rate (fs). Quoted values are correct for fs = 48kHz.

Table 61 DAC Soft-Mute Control



### **DAC AUTO-MUTE**

The DAC digital mute and volume controls are described earlier in Table 59 and Table 61.

The DAC also incorporates a digital auto-mute monitor, which is enabled by setting DAC\_AUTOMUTE. When the auto-mute is enabled, and a number (DAC\_AUTOMUTE\_SAMPLES) of consecutive zero-samples is detected, the AUTOMUTE\_STS flag is asserted.

The WM8963 supports the option to automatically power-down the speaker path when the DAC Auto-Mute is triggered, and to re-enable the speaker path when audio data is detected. This feature has been designed to work around the Write Sequencer, which mutes and unmutes the speakers in a controlled manner using the Speaker Sleep (see Table 123) and Speaker Wake (see Table 124) write sequences. Auto-mute is enabled by setting the WSEQ\_AUTOSEQ\_ENA bit in Register R87. See Table 62 for details of this and other Auto-mute register bits.

The status of DAC Auto-Mute can be read back from the AUTOMUTE\_STS bit.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R9 (09h) Audio Interface 0	11	AUTOMUTE_STS	0	Readback of the DAC automute status 0 = Automute not detected 1 = Automute detected
	9:8	DAC_AUTOMUT E_SAMPLES [1:0]	11	Selects the number of consecutive zero DAC samples that will be interpreted as an Automute.  00 = 128 samples  01 = 256 samples  10 = 512 samples  11 = 1024 samples
	7	DAC_AUTOMUT E	0	DAC Auto-Mute Control 0 = Disabled 1 = Enabled
R87 (57h) Write Sequencer Control 1	7	WSEQ_AUTOSE Q_ENA	0	Write Sequencer Auto-Sequence Enable (controls the Class D driver via DAC Auto-Mute function) 0 = Disabled 1 = Enabled

Table 62 DAC Auto Mute

# **DAC MONO MIX**

A DAC digital mono-mix mode can be enabled using the DAC\_MONOMIX register bit. This mono mix will be output on whichever DAC is enabled. To prevent clipping, a -6dB attenuation is automatically applied to the mono mix.

The mono mix is only supported when one or other DAC is disabled. When the mono mix is selected, then the mono mix is output on the enabled DAC only; there is no output from the disabled DAC. If DACL\_ENA and DACR\_ENA are both set, then stereo operation applies.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R57(39h) DAC DSP Mixing (1)	9	DAC_MONOMIX	0	DAC Mono Mix  0 = Stereo  1 = Mono (Mono mix output on enabled DAC)  Mono Mix is only supported when one or other DAC is disabled.  When Mono mix is enabled, 6dB attenuation is applied.

Table 63 DAC Mono Mix



### **DAC DE-EMPHASIS**

Digital de-emphasis can be applied to the DAC playback data (e.g. when the data comes from a CD with pre-emphasis used in the recording). De-emphasis filtering is available for sample rates of 48kHz, 44.1kHz and 32kHz.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC and DAC Control 1	2:1	DAC_DEEMP [1:0]	00	De-Emphasis Control  00 = No de-emphasis 01 = De-emphasis for 32kHz sample rate 10 = De-emphasis for 44.1kHz sample rate 11 = De-emphasis for 48kHz sample rate

Table 64 DAC De-Emphasis Control

# **DAC OVERSAMPLING RATIO (OSR)**

The DAC oversampling rate is programmable to allow power consumption versus audio performance trade-offs. The default oversampling rate is low for reduced power consumption; using the higher OSR setting improves the DAC signal-to-noise performance.

See the "Reference Voltages and Bias Control" section for details of the supported bias control settings for the output signal paths.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	0	DAC LID	0	DAC Overson line a Detic
R6 (06h)	U	DAC_HP	0	DAC Oversampling Ratio
ADC and DAC				0 = Low Power (typically 64 x fs)
Control 2				1 = High Performance (typically 128 x
				fs)

**Table 65 DAC Oversampling Control** 



# **DIGITAL BEEP GENERATOR**

The WM8963 provides a digital signal generator which can be used to inject an audio tone (beep) into the DAC signal path. The output of the beep generator is digitally mixed with the DAC outputs, after the DAC digital volume.

The beep is enabled using BEEP\_ENA. The beep function creates an approximation of a Sine wave. The audio frequency is set using BEEP\_RATE, and is dependent on the SAMPLE\_RATE\_INT\_MODE and the SAMPLE\_RATE settings (see "Clocking and Sample Rates" section). The beep volume is set using BEEP\_GAIN. Note that the volume of the digital beep generator is not affected by the DAC volume or DAC mute controls.

The digital beep generator control fields are described in Table 66.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R110 (6Eh) Beep Generator (1)	7:4	BEEP_GAIN [3:0]	0000	Digital Beep Volume Control 0000 = mute 0001 = -90dB 0010 = -84dB (6dB steps) 1111 = -6dB
	2:1	BEEP_RATE [1:0]	01	Digital Beep Waveform Control If SAMPLE_RATE_INT_MODE = 1 00 = 500Hz 01 = 1000Hz 10 = 2000Hz 11 = 4000Hz If SAMPLE_RATE_INT_MODE = 0 00 = 499Hz - 502Hz 01 = 999Hz - 1003Hz 10 = 1998Hz - 2005Hz 11 = 3997Hz - 4009Hz
	0	BEEP_ENA	0	Digital Beep Enable  0 = Disabled  1 = Enabled  Note that the DAC and associated signal path needs to be enabled when using the digital beep.

Table 66 Digital Beep Generator



# **OUTPUT SIGNAL PATH**

The WM8963 provides two stereo Headphone Output drivers and a pair of Speaker Output drivers. The speaker output mixers, and associated multiplexers, provide a high degree of flexibility, allowing multiple signal paths through the device to the outputs.

The output signal paths and associated control registers are illustrated in Figure 33.

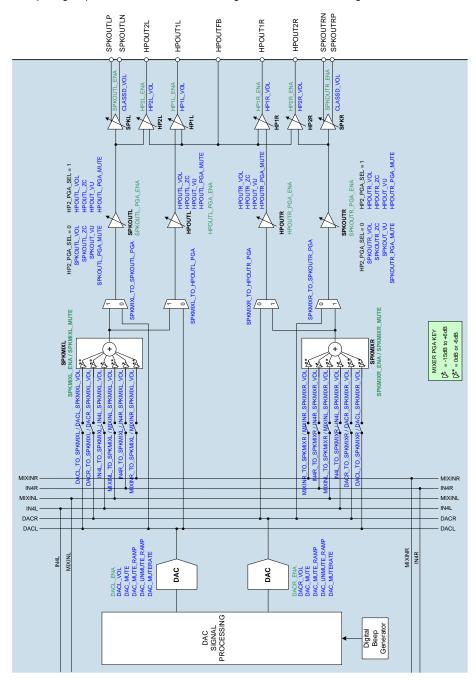


Figure 33 Output Signal Paths



## **OUTPUT SIGNAL PATHS ENABLE**

The speaker output mixers, and each analogue output pin and associated PGA can be independently enabled or disabled using the register bits described in Table 67.

The Class D speaker driver is controlled using SPKOUTL\_ENA and SPKOUTR\_ENA. The headphone drivers are controlled by HP1L\_ENA and HP1R\_ENA, and by HP2L\_ENA and HP2R\_ENA (described in Table 70).

To enable the output PGAs, the reference voltage VMID and the bias current must also be enabled. See "Reference Voltages and Bias Control" for details of the associated controls VMID\_SEL and BIAS\_ENA.

SPKOUTL and SPKOUTR are driven by the left and right speaker PGAs respectively.

HPOUT1L and HPOUT1R are driven by the left and right headphone PGAs respectively.

The input signal to the each of the PGAs is selectable between one of the speaker output mixers and a direct output from one of the DACs.

Note that HPOUT2L and HPOUT2R are driven by the left and right speaker PGAs, but can be configured to use the same controls as the headphone PGAs, in order to save register writes when configuring two headphone outputs simultaneously. This is illustrated in Figure 33.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R26 (1Ah) Pwr Mgmt (2)	6	HPOUTL_PGA_E NA	0	Headphone Left PGA enable 0 = Disabled 1 = Enabled Note that this must be set for HPOUT1L output. Note that this must also be set for HPOUT2L output if HP2_PGA_SEL=1.
	5	HPOUTR_PGA_E NA	0	Headphone Right PGA enable  0 = Disabled  1 = Enabled  Note that this must be set for  HPOUT1R output.  Note that this must also be set for  HPOUT2R output if  HP2_PGA_SEL=1.
	4	SPKOUTL_PGA_ ENA	0	Speaker Left PGA enable  0 = Disabled  1 = Enabled  Note that this must be set for  SPKOUTL, and for HPOUT2L  output if HP2_PGA_SEL=0.
	3	SPKOUTR_PGA_ ENA	0	Speaker Right PGA enable 0 = Disabled 1 = Enabled Note that this must be set for SPKOUTR, and for HPOUT2R output if HP2_PGA_SEL=0.
R49 (31h) Class D Control (1)	7	SPKOUTR_ENA	0	Right channel class D Speaker Enable 0 = Disabled 1 = Enabled
	6	SPKOUTL_ENA	0	Left channel class D Speaker Enable 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R99 (63h) Mixer Enables	1	SPKMIXL_ENA	0	Left Speaker Mixer Enable 0 = Disabled 1 = Enabled
	0	SPKMIXR_ENA	0	Right Speaker Mixer Enable 0 = Disabled 1 = Enabled

**Table 67 Output Signal Paths Enable** 

## **HEADPHONE SIGNAL PATHS ENABLE**

The Headphone output paths can be actively switched to AGND through internal resistors if desired. This is desirable at start-up in order to achieve a known condition prior to enabling the output. This is also desirable in shutdown to prevent the external connections from being affected by the internal circuits. The ground-referenced Headphone outputs are shorted to AGND by default; the short circuit is removed on each of these paths by setting the applicable fields HP1L\_RMV\_SHORT, HP1R\_RMV\_SHORT, HP2L\_RMV\_SHORT or HP2R\_RMV\_SHORT.

The ground-referenced Headphone output drivers are designed to suppress pops and clicks when enabled or disabled. However, it is necessary to control the drivers in accordance with a defined sequence in start-up and shut-down to achieve the pop suppression. It is also necessary to schedule the DC Servo offset correction at the appropriate point in the sequence (see "DC Servo"). Table 68 and Table 69 describe the recommended sequences for enabling and disabling these output drivers.

SEQUENCE	HPOUT1 ENABLE	HPOUT2 ENABLE
Step 1	HP1L_ENA = 1	HP2L_ENA = 1
	HP1R_ENA = 1	HP2R_ENA = 1
Step 2	20μs delay	20µs delay
Step 3	HP1L_ENA_DLY = 1	HP2L_ENA_DLY = 1
	HP1R_ENA_DLY = 1	HP2R_ENA_DLY = 1
Step 4	DC offset correction	DC offset correction
Step 5	HP1L_ENA_OUTP = 1	HP2L_ENA_OUTP = 1
	HP1R_ENA_OUTP = 1	HP2R_ENA_OUTP = 1
Step 6	20μs delay	20μs delay
Step 7	HP1L_RMV_SHORT = 1 HP1R_RMV_SHORT = 1	HP2L_RMV_SHORT = 1 HP2R_RMV_SHORT = 1

**Table 68 Headphone Output Enable Sequence** 

SEQUENCE	HPOUT1 DISABLE	HPOUT2 DISABLE
Step 1	HP1L_RMV_SHORT = 0	HP2L_RMV_SHORT = 0
	HP1R_RMV_SHORT = 0	HP2R_RMV_SHORT = 0
Step 2	20µs delay	20µs delay
Step 3	HP1L_ENA = 0	HP2L_ENA = 0
	HP1L_ENA_DLY = 0	HP2L_ENA_DLY = 0
	HP1L_ENA_OUTP = 0	HP2L_ENA_OUTP = 0
	HP1R_ENA = 0	HP2R_ENA = 0
	HP1R_ENA_DLY = 0	HP2R_ENA_DLY = 0
	HP1R_ENA_OUTP = 0	HP2R_ENA_OUTP = 0

**Table 69 Headphone Output Disable Sequence** 



The register bits relating to pop suppression control are defined in Table 70.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R69 (45h) Analogue HP 0	7	HP1L_RMV_SHO RT	0	Removes HP1L short  0 = HP1L short enabled  1 = HP1L short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP1L Enable sequence.
	6	HP1L_ENA_OUT P	0	Enables HP1L output stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	5	HP1L_ENA_DLY	0	Enables HP1L intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled  This bit should be set with at least 20us delay after HP1L ENA.
	4	HP1L_ENA	0	Enables HP1L input stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 as the first stage of the HP1L Enable sequence.
	3	HP1R_RMV_SHO RT	0	Removes HP1R short  0 = HP1R short enabled  1 = HP1R short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP1R Enable sequence.
	2	HP1R_ENA_OUT P	0	Enables HP1R output stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	1	HP1R_ENA_DLY	0	Enables HP1R intermediate stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled This bit should be set with at least 20us delay after HP1R_ENA.
	0	HP1R_ENA	0	Enables HP1R input stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set as the first stage of the HP1R Enable sequence.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R96 (60h) Analogue HP 3	7	HP2L_RMV_SHO RT	0	Removes HP2L short  0 = HP2L short enabled  1 = HP2L short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP2L Enable sequence.
	6	HP2L_ENA_OUT P	0	Enables HP2L output stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	5	HP2L_ENA_DLY	0	Enables HP2L intermediate stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled This bit should be set with at least 20us delay after HP2L_ENA.
	4	HP2L_ENA	0	Enables HP2L input stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set as the first stage of the HP2L Enable sequence.
	3	HP2R_RMV_SHO RT	0	Removes HP2R short  0 = HP2R short enabled  1 = HP2R short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP2R Enable sequence.
	2	HP2R_ENA_OUT P	0	Enables HP2R output stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	1	HP2R_ENA_DLY	0	Enables HP2R intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled This bit should be set with at least 20us delay after HP2R_ENA.
	0	HP2R_ENA	0	Enables HP2R input stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set as the first stage of the HP2R Enable sequence.

Table 70 Headphone Output Signal Paths Control



#### SPEAKER MIXER CONTROL

Two speaker output mixers, SPKMIXL and SPKMIXR, are provided on the output signal paths. Each of these performs configurable mixing of the DAC outputs, the Input Mixer signals, and the bypass paths directly from the IN4L/IN4R pins.

The speaker output mixers can be selected as the source for the speaker PGAs or the headphone PGAs. Alternatively, a direct path from one of the DACs can be selected as the source of the respective PGAs, as illustrated in Figure 34.

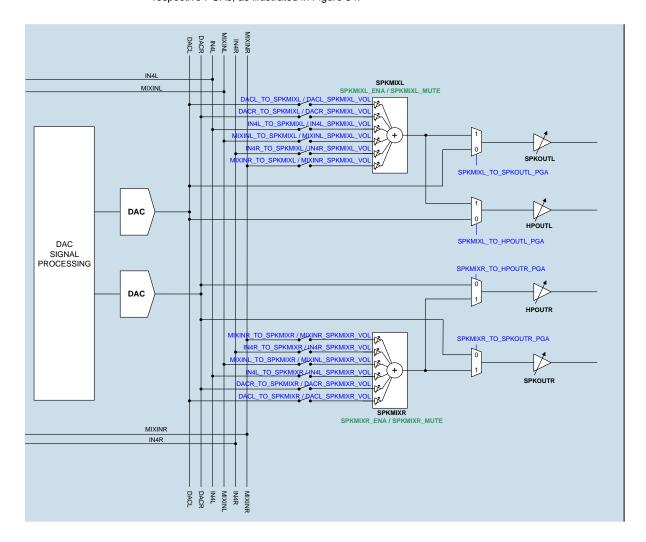


Figure 34 Speaker Output Mixer paths

Each of the inputs to the speaker output mixers is enabled independently, using the register bits described in Table 71 and Table 72.

A selectable 0dB/-6dB volume control is provided on each of the DAC signals to the speaker output mixer. A selectable 0dB/+6dB volume control is provided on each of the Input Mixer signals. In the case of the IN4L and IN4R inputs, eight different levels of gain (-15dB to +6dB) can be selected. These controls allow the signal levels to be balanced, and can also be used to help avoid signal clipping.

The output of each mixer can be enabled or muted, using the SPKMIXL\_MUTE and SPKMIXR\_MUTE bits.

The input source for each of the PGAs is selectable between one of the speaker output mixers and a direct output from one of the DACs.

The register bits associated with the Speaker Output mixers are described in Table 71 and Table 72.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R100 (64h) Headphone Mixer (1)	7	SPKMIXL_TO_H POUTL_PGA	0	Left Headphone PGA Path Select 0 = DACL Output 1 = SPKMIXL Output
R105 (69h) Speaker Mixer (1)	7	SPKMIXL_TO_SP KOUTL_PGA	0	Left Speaker PGA Path Select 0 = DACL Output 1 = SPKMIXL Output
	5	DACL_TO_SPKM IXL	0	Left DAC to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	4	DACR_TO_SPKM IXL	0	Right DAC to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	3	MIXINL_TO_SPK MIXL	0	Left Input Mixer to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	2	MIXINR_TO_SPK MIXL	0	Right Input Mixer to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	1	IN4L_TO_SPKMI XL	0	Input IN4L to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	0	IN4R_TO_SPKMI XL	0	Input IN4R to Left Speaker Mixer select 0 = Disabled 1 = Enabled
R107 (6Bh) Speaker Mixer (3)	8	SPKMIXL_MUTE	1	Left Speaker Mixer Mute 0 = Unmuted 1 = Muted
	7	MIXINL_SPKMIX L_VOL	0	Left Input Mixer to Left Speaker Mixer volume 0 = +6dB 1 = 0dB
	6	MIXINR_SPKMIX L_VOL	0	Right Input Mixer to Left Speaker Mixer volume 0 = +6dB 1 = 0dB
	5:3	IN4L_SPKMIXL_ VOL [2:0]	111	Input IN4L to Left Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	2:0	IN4R_SPKMIXL_ VOL [2:0]	111	Input IN4R to Left Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
R109 (6Dh) Speaker Mixer (5)	7	DACL_SPKMIXL_ VOL	0	Left DAC to Left Speaker Mixer volume 0 = 0dB 1 = -6dB
	6	DACR_SPKMIXL _VOL	0	Right DAC to Left Speaker Mixer volume $0 = 0 dB$ $1 = -6 dB$

Table 71 Left Speaker Mixer Control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R101 (65h) Headphone Mixer (2)	7	SPKMIXR_TO_H POUTR_PGA	0	Right Headphone PGA Path Select 0 = DACR Output 1 = SPKMIXR Output
R106 (6Ah) Speaker Mixer (2)	7	SPKMIXR_TO_S PKOUTR_PGA	0	Right Speaker PGA Path Select 0 = DACR Output 1 = SPKMIXR Output
	5	DACL_TO_SPKM IXR	0	Left DAC to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	4	DACR_TO_SPKM IXR	0	Right DAC to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	3	MIXINL_TO_SPK MIXR	0	Left Input Mixer to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	2	MIXINR_TO_SPK MIXR	0	Right Input Mixer to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	1	IN4L_TO_SPKMI XR	0	Input IN4L to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	0	IN4R_TO_SPKMI XR	0	Input IN4R to Right Speaker Mixer select 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R108 (6Ch) Speaker Mixer (4)	8	SPKMIXR_MUTE	1	Right Speaker Mixer Mute 0 = Unmuted 1 = Muted
	7	MIXINL_SPKMIX R_VOL	0	Left Input Mixer to Right Speaker Mixer volume 0 = +6dB 1 = 0dB
	6	MIXINR_SPKMIX R_VOL	0	Right Input Mixer to Right Speaker Mixer volume 0 = +6dB 1 = 0dB
	5:3	IN4L_SPKMIXR_ VOL [2:0]	111	Input IN4L to Right Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
	2:0	IN4R_SPKMIXR_ VOL [2:0]	111	Input IN4R to Right Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
R109 (6Dh) Speaker Mixer (5)	5	DACL_SPKMIXR _VOL	0	Left DAC to Right Speaker Mixer volume 0 = 0dB 1 = -6dB
	4	DACR_SPKMIXR _VOL	0	Right DAC to Right Speaker Mixer volume 0 = 0dB 1 = -6dB

Table 72 Right Speaker Mixer Control



#### **HEADPHONE OUTPUT PGA CONTROL**

The input signal to the headphone output PGAs is selectable between one of the speaker output mixers and a direct output from one of the DACs. The applicable sources are selected using the SPKMIXL\_TO\_HPOUTL\_PGA and SPKMIXR\_TO\_HPOUTR\_PGA register bits for the Left and Right channels respectively. See Table 71 and Table 72 for descriptions of these bits.

There are six headphone output PGAs – two primary (HPOUTL and HPOUTR), and four secondary (HP1L, HP1R, HP2L, and HP2R). The headphone outputs are each controlled by a primary PGA and a secondary PGA in series.

The HPOUT PGAs give a high degree of control from -68dB to +6dB in 1dB steps, and are common to the HPOUT1 and HPOUT2 outputs. Dedicated secondary PGAs are provided for each of the HPOUT1 and HPOUT2 output channels. The secondary PGAs (HP1 and HP2) provide control from -7dB to 0dB in 1dB steps on each channel. See Figure 33 for a diagrammatic representation of this layout.

The HPOUT PGAs are controlled using the HPOUTL\_VOL and HPOUTR\_VOL registers, providing fine volume control to the HPOUT1 and HPOUT2 paths.

To prevent "zipper noise", a zero-cross function is provided on the HPOUTL and HPOUTR output PGAs. When this feature is enabled, volume updates will not take place until a zero-crossing is detected. In the case of a long period without zero-crossings, a timeout function is provided. When the zero-cross function is enabled, the volume will update after the timeout period if no earlier zero-cross has occurred. The timeout clock is enabled using TOCLK\_ENA; the timeout period is set by TOCLK\_DIV. See "Clocking and Sample Rates" for more information on these fields.

It is recommended that only HPOUTL PGA and HPOUTR PGA are modified while the output signal path is active as these are the only Headphone PGAs with the zero-cross function. It is recommended that the other gain controls on the signal paths should not be modified while the signal path is active.

The left and right channels on each of the HPOUT outputs can also be attenuated independently using the HP1L\_VOL, HP1R\_VOL, HP2L\_VOL and HP2R\_VOL registers. Note that there is no zero-cross function associated with these registers.

The headphone output signal can be muted using the HPOUTL\_PGA\_MUTE and HPOUTR\_PGA\_MUTE registers. The headphone outputs are un-muted by default.

The HPOUT\_VU bits control the loading of the Headphone Output PGA volume data and the PGA mute functions. When HPOUT\_VU is set to 0, the volume control data will be loaded into the respective control register, but will not actually change the gain setting. The left and right Headphone Output PGA volume settings are both updated when a 1 is written to any of the HPOUT\_VU bits. Similarly, the HPOUTL\_PGA\_MUTE and HPOUTR\_PGA\_MUTE settings are only effective when a 1 is written to either HPOUT\_VU bit. This makes it possible to update the gain of the left and right output paths simultaneously.

Note that the HP1L\_VOL, HP1R\_VOL, HP2L\_VOL and HP2R\_VOL registers are effective immediately when updated; the HPOUT\_VU bits have no control over the Secondary PGA volume registers. For best performance, the Secondary PGA volume registers should be set to 000b (-7dB). See "Reference Voltages and Bias Control" for further details of the High Performance headphone playback configuration.

HP2\_PGA\_SEL allows HPOUT2 to be controlled by the SPKOUT PGAs instead of the HPOUT PGAs. See the "Speaker Output PGA Control" section for further details.



REGISTER ADDRESS	ВІТ	LABEL	DEFAULT	DESCRIPTION
R2 (2h) HPOUTL volume	8	HPOUT_VU	N/A	Headphone Output PGA Volume and Mute Update. Writing 1 to this bit will cause the HPOUTL and HPOUTR volume and mute settings to be updated simultaneously.
	7	HPOUTL_ZC	0	Left Headphone Output PGA Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	HPOUTL_VOL [6:0]	00h (Mute)	Left Headphone Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB  7Fh = 6dB (See Table 75 for full volume control range)
R3 (2h) HPOUTR volume	8	HPOUT_VU	N/A	Headphone Output PGA Volume and Mute Update Writing 1 to this bit will cause the HPOUTL and HPOUTR volume and mute settings to be updated simultaneously.
	7	HPOUTR_ZC	0	Right Headphone Output PGA Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	HPOUTR_VOL [6:0]	OOh (Mute)	Right Headphone Output PGA Volume Mute, or -68dB to +6dB in 1dB steps. 00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB (See Table 75 for full volume control range)
R26 (1A) Pwr Mgmt (2)	1	HPOUTL_PGA_MUTE	0	HPOUTL_VOL (Left Headphone Output PGA) Mute 0 = Un-mute 1 = Mute
	0	HPOUTR_PGA_MUTE	0	HPOUTR_VOL (Right Headphone Output PGA) Mute 0 = Un-mute 1 = Mute



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R71 (47h) Analogue HP 2	8:6	HP1L_VOL [2:0]	111	Headphone 1 Left Secondary PGA volume.  000 = -7dB 001 = -6dB 010 = -5dB 011 = -4dB 100 = -3dB 101 = -2dB 110 = -1dB 111 = 0dB (default)
	5:3	HP1R_VOL [2:0]	111	Headphone 1 Right Secondary PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB  100 = -3dB  101 = -2dB  110 = -1dB  111 = 0dB (default)
R97 (61h) Analogue HP 4	7	HP2_PGA_SEL	1	Headphone 2 PGA configure  0 = HPOUT2 controlled by Speaker PGA settings (SPKOUTL_VOL, SPKOUTR_VOL)  1 = HPOUT2 controlled by Headphone PGA settings (HPOUTL_VOL, HPOUTR_VOL)  Only valid when HP2L_ENA=1 or HP2R_ENA=1. If the HP2 outputs are both disabled, then the Speaker PGA is controlled independently.
	5:3	HP2L_VOL [2:0]	111	Headphone 2 Secondary Left PGA volume.  000 = -7dB 001 = -6dB 010 = -5dB 011 = -4dB 100 = -3dB 101 = -2dB 110 = -1dB 111 = 0dB (default)
	2:0	HP2R_VOL [2:0]	111	Headphone 2 Right Secondary PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB  100 = -3dB  101 = -2dB  110 = -1dB  111 = 0dB (default)

Table 73 Headphone Output PGA (HPOUTL\_VOL, HPOUTR\_VOL) Control



#### SPEAKER OUTPUT PGA CONTROL

The input signal to the speaker output PGAs is selectable between one of the speaker output mixers and a direct output from one of the DACs. The applicable sources are selected using the SPKMIXL\_TO\_SPKOUTL\_PGA and SPKMIXR\_TO\_SPKOUTR\_PGA register bits for the Left and Right channels respectively. See Table 71 and Table 72 for descriptions of these bits.

The volume control of the left and right Speaker PGAs can be independently adjusted using the SPKOUTL\_VOL and SPKOUTR\_VOL register fields as described in Table 74. The gain range is -68dB to +6dB in 1dB steps.

To prevent "zipper noise", a zero-cross function is provided on the Speaker PGAs. When this feature is enabled, volume updates will not take place until a zero-crossing is detected. In the case of a long period without zero-crossings, a timeout function is provided. When the zero-cross function is enabled, the volume will update after the timeout period if no earlier zero-cross has occurred. The timeout clock is enabled using TOCLK\_ENA. See "Clocking and Sample Rates" for the definition of this bit.

The SPK\_VU bits control the loading of the Speaker PGA volume data. When SPK\_VU is set to 0, the volume control data will be loaded into the respective control register, but will not actually change the gain setting. The left and right Speaker PGA volume settings are both updated when a 1 is written to any of the SPK\_VU bits. This makes it possible to update the gain of the left and right output paths simultaneously.

The Speaker PGA volume control register fields are described in Table 74.

Note that, when HP2L\_ENA=1 or HP2R\_ENA=1, the HP2\_PGA\_SEL bit (described in Table 73) affects the Speaker PGA behaviour, as described below.

When  $HP2\_PGA\_SEL = 0$ , the register fields described in Table 74 control both the HPOUT2 and SPKOUT outputs.

When HP2\_PGA\_SEL = 1, the register fields described in Table 74 have no effect; in this case, the HPOUT2 and SPKOUT outputs are both controlled using the Headphone Output PGA registers described in Table 73.

The HP2\_PGA\_SEL function is only valid when HP2L\_ENA=1 or HP2R\_ENA=1; if the HP2 outputs are both disabled, then the Speaker PGA is controlled independently, as described in Table 74.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R40 (28h) SPKOUTL volume	8	SPKOUT_VU	N/A	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	7	SPKOUTL_ZC	0	SPKOUTL_VOL (Left Speaker Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	SPKOUTL_VOL [6:0]	00h (Mute)	Left Speaker Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB (See Table 75 for output PGA volume control range)





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R41 (29h) SPKOUTR volume	8	SPKOUT_VU	N/A	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	7	SPKOUTR_ZC	0	SPKOUTR_VOL (Right Speaker Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	SPKOUTR_VOL [6:0]	00h (Mute)	Right Speaker Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB  7Fh = 6dB (See Table 75 for output PGA volume control range)
R49 (31h) Class D Control 1	2	SPKOUT_VU	N/A	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	1	SPKOUTL_PGA_MUTE	0	SPKOUTL_VOL (Left Speaker Output PGA) Mute 0 = Mute 1 = Un-mute
	0	SPKOUTR_PGA_MUTE	0	SPKOUTR_VOL (Right Speaker Output PGA) Mute 0 = Mute 1 = Un-mute

Table 74 Speaker Output PGA (SPKOUTL\_VOL, SPKOUTR\_VOL) Control



HPOUTL_VOL [6:0], HPOUTR_VOL [6:0], SPKOUTL_VOL [6:0] or SPKOUTR_VOL [6:0]	VOLUME (dB)	HPOUTL_VOL [6:0], HPOUTR_VOL [6:0], SPKOUTL_VOL [6:0] or SPKOUTR_VOL [6:0]	VOLUME (dB)
000_0000 to 010_1111	Mute	101_1010	-31
011_0000 to 011_0101	-68	101_1011	-30
011_0110	-67	101_1100	-29
011_0111	-66	101_1101	-28
011_1000	-65	101_1110	-27
011_1001	-64	101_1111	-26
011_1010	-63	110_0000	-25
011_1011	-62	110_0001	-24
011_1100	-61	110_0010	-23
011_1101	-60	110_0011	-22
011_1110	-59	110_0100	-21
011_1111	-58	110_0101	-20
100_0000	-57	110_0110	-19
100_0001	-56	110_0111	-18
100_0010	-55	110_1000	-17
100_0011	-54	110_1001	-16
100_0100	-53	110_1010	-15
100_0101	-52	110_1011	-14
100_0110	-51	110_1100	-13
100_0111	-50	110_1101	-12
100_1000	-49	110_1110	-11
100_1001	-48	110_1111	-10
100_1010	-47	111_0000	-9
100_1011	-46	111_0001	-8
100_1100	-45	111_0010	-7
100_1101	-44	111_0011	-6
100_1110	-43	111_0100	-5
100_1111	-42	111_0101	-4
101_0000	-41	111_0110	-3
101_0001	-40	111_0111	-2
101_0010	-39	111_1000	-1
101_0011	-38	111_1001	0
101_0100	-37	111_1010	+1
101_0101	-36	111_1011	+2
101_0110	-35	111_1100	+3
101_0111	-34	111_1101	+4
101_1000	-33	111_1110	+5
101_1001	-32	111_1111	+6

Table 75 Headphone PGA and Speaker PGA Volume Range



## **ANALOGUE OUTPUTS**

#### SPEAKER OUTPUT CONFIGURATIONS

Fine volume control is available on the speaker paths using the SPKOUTL\_VOL and SPKOUTR\_VOL PGAs. A boost function is available on both the speaker paths.

The speaker outputs SPKOUTL and SPKOUTR operate in a BTL configuration in Class D amplifier mode. The speaker outputs are capable of supporting up to 1W per channel into stereo  $8\Omega$  BTL loads.

The speaker outputs can be configured as a pair of stereo outputs, or as a single mono output. Note that, for applications requiring only a single speaker output, it is possible to improve the THD performance by configuring the speaker outputs in mono mode. See "Electrical Characteristics" for further details.

The mono configuration is selected using the SPK\_MONO register bit, as described in Table 76. In mono mode, the P channels, SPKOUTLP and SPKOUTRP should be connected together on the PCB, and similarly with the N channels, SPKOUTLN and SPKOUTRN, as illustrated in Figure 35. In this configuration, both left and right speaker drivers should be enabled (SPKOUTL\_ENA=1 and SPKOUTR\_ENA=1), but both drivers will output the left speaker path signal only.

The connections for stereo and mono speaker configurations are shown in Figure 35.

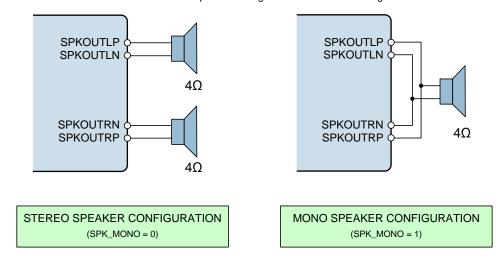


Figure 35 Stereo and Mono Speaker Output Configuration

Eight levels of AC signal boost are provided in order to deliver maximum output power for many commonly-used SPKVDD/AVDD combinations. The AC boost levels from 0dB to +12dB are selected using register bit CLASSD\_VOL, which boosts left and right channels equally. To prevent pop noise, CLASSD\_VOL should not be modified while the speaker outputs are enabled. Figure 36 illustrates the speaker outputs and the mixing and gain/boost options available.

Ultra-low leakage and high PSRR allow the speaker supply SPKVDD to be directly connected to a lithium battery. Note that an appropriate SPKVDD supply voltage must be provided to prevent waveform clipping when speaker boost is used.

DC gain is applied automatically in class D mode with a shift from VMID to SPKVDD/2. This provides optimum signal swing for maximum output power.



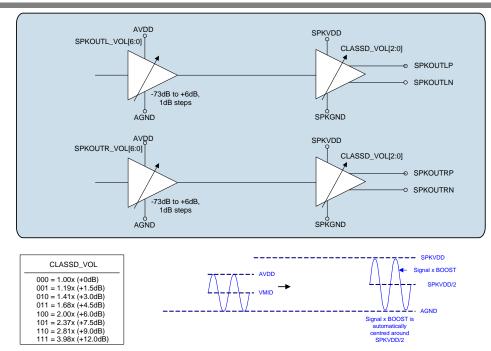


Figure 36 Speaker Output Configuration and AC Boost Operation

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R51 (33h) Class D Control 2	6	SPK_MONO	0	Mono Speaker Configuration enable 0 = Default (stereo) 1 = Mono mode When SPK_MONO is set to '1', both speakers output the signal from the left channel. Note that the user must tie the outputs together for mono use
	2:0	CLASSD_VOL	011	AC Speaker Gain Boost. Note that both left and right channels are boosted equally 000 = 1.00x boost (+0dB) 001 = 1.19x boost (+1.5dB) 010 = 1.41x boost (+3.0dB) 011 = 1.68x boost (+4.5dB) 100 = 2.00x boost (+6.0dB) 101 = 2.37x boost (+7.5dB) 110 = 2.81x boost (+9.0dB) 111 = 3.98x boost (+12.0dB)

Table 76 Class D Speaker Driver Control



#### **HEADPHONE OUTPUT CONFIGURATIONS**

The headphone outputs HPOUT1L and HPOUT1R are driven by the headphone output PGAs HPOUTL and HPOUTR. The inputs to these PGAs are the DAC outputs DACL and DACR.

A pair of secondary PGAs – HP1L and HP1R – operate in series with the HPOUT1L and HPOUT1R PGAs respectively.

The headphone outputs HPOUT2L and HPOUT2R are driven by the speaker output PGAs SPKOUTL and SPKOUTR. The inputs to these PGAs are the DAC outputs DACL and DACR. Note that these PGAs are controlled by the headphone PGA registers (when HP2\_PGA\_SEL = 1), or by the speaker PGA registers (when HP2\_PGA\_SEL = 0).

A pair of secondary PGAs – HP2L and HP2R – operate in series with either the HPOUT1L and HPOUT1R PGAs, or with the SPKOUTL and SPKOUTR PGAs respectively.

The headphone output driver is capable of driving up to 25 mW into a  $16 \Omega$  or  $32 \Omega$  load such as a stereo headset or headphones. The outputs are ground-referenced, eliminating any requirement for AC coupling capacitors. This is achieved by having separate positive and negative supply rails powered by an on-chip charge pump. A DC Servo circuit removes any DC offset from the headphone outputs, suppressing 'pop' noise and minimising power consumption. The Charge Pump and DC Servo are described separately (see "Charge Pump" and "DC Servo" respectively).

It is recommended to connect a zobel network to the headphone output pins HPOUT1L, HPOUT1R, HPOUT2L and HPOUT2R for best audio performance in all applications. The components of the zobel network have the effect of dampening high frequency oscillations or instabilities that can arise outside the audio band under certain conditions. Possible sources of these instabilities include the inductive load of a headphone coil or an active load in the form of an external line amplifier. The capacitance of lengthy cables or PCB tracks can also lead to amplifier instability. The zobel network should comprise of a  $20\Omega$  resistor and 100nF capacitor in series with each other, as illustrated in Figure 37.

Note that the zobel network may be unnecessary in some applications; it depends upon the characteristics of the connected load. It is recommended to include these components for best audio quality and amplifier stability in all cases.

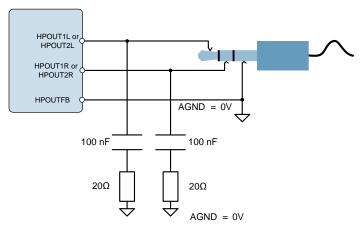


Figure 37 Zobel Network Components for HPOUT1L, HPOUT1R, HPOUT2L and HPOUT2R

The headphone output incorporates a common mode, or ground loop, feedback path which provides rejection of system-related ground noise. The return path is via HPOUTFB. This pin must be connected to ground for normal operation of the headphone output. No register configuration is required.



## **CHARGE PUMP**

The WM8963 incorporates a dual-mode Charge Pump which generates the supply rails for the headphone output drivers, HPOUT1L, HPOUT1R, HPOUT2L and HPOUT2R. The Charge Pump has a single supply input, CPVDD, and generates split rails CPVOUTP and CPVOUTN according to the selected mode of operation. The Charge Pump connections are illustrated in Figure 38 (see "Electrical Characteristics" for external component values). An input decoupling capacitor may also be required at CPVDD, depending upon the system configuration.

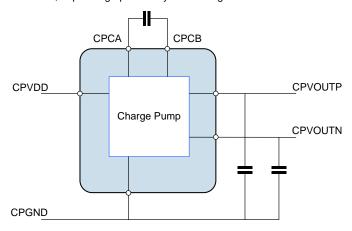


Figure 38 Charge Pump External Connections

The Charge Pump is enabled by setting the CP\_ENA bit. When enabled, the charge pump adjusts the output voltages (CPVOUTP and CPVOUTN) as well as the switching frequency in order to optimise the power consumption according to the operating conditions. This can take two forms, which are selected using the CP\_DYN\_PWR register bit.

- Register control (CP\_DYN\_PWR = 0)
- Dynamic control (CP\_DYN\_PWR = 1)

Under Register control, the HPOUTL\_VOL and HPOUTR\_VOL register settings are used to control the charge pump mode of operation.

Under Dynamic control, the audio signal level in the DAC is also used to control the charge pump mode of operation. This is the Wolfson 'Class W' mode, which allows the power consumption to be optimised in real time.

When selecting Register control (CP\_DYN\_PWR = 0), a '1' must be written to the HPOUT\_VU bit to complete the mode change. HPOUT\_VU is defined in the "Output Signal Path" section (Table 73).

Note that, when selecting Dynamic control (CP\_DYN\_PWR = 1), the Charge Pump mode change is implemented immediately when CP\_DYN\_PWR is updated.

When digital sidetone is used (see "Digital Mixing"), it is recommended that the Charge Pump operates in Register Control mode only (CP\_DYN\_PWR = 0). This is because the Dynamic Control mode (Class W) does not measure the sidetone signal level and hence the Charge Pump configuration cannot be optimised for all signal conditions when digital sidetone is enabled; this could lead to signal clipping.

When Virtual Surround Sound (VSS), Multiband Compression (MBC) or DAC ReTune is used (see "DAC Signal Path Enhancements"), it is recommended that the Charge Pump operates in Register Control mode only (CP\_DYN\_PWR = 0). This is because the Dynamic Control mode (Class W) does not measure the DSP Signal Enhancements level and hence the Charge Pump cannot be optimised for all signal conditions when VSS, MBC or DAC ReTune is enabled; this could lead to signal clipping.

Under the recommended usage conditions of the WM8963, the Charge Pump will be enabled by running the default headphone Start-Up sequence as described in the "Control Write Sequencer" section. (Similarly, it will be disabled by running the Shut-Down sequence.) In these cases, the user does not need to write to the CP\_ENA bit. The Charge Pump operating mode defaults to Register control; Dynamic control may be selected by setting the CP\_DYN\_PWR register bit, if appropriate.



The SYSCLK signal must be present for the charge pump to function. The clock division from MCLK is handled transparently by the WM8963 without user intervention, as long as SYSCLK and sample rates are set correctly (see "Clocking and Sample Rates" section). The clock divider ratio depends on the SAMPLE\_RATE[2:0] and MCLK\_RATE[3:0] register settings.

The Charge Pump control fields are described in Table 77.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R72 (48h) Charge Pump 1	0	CP_ENA	0	Enable charge-pump digits  0 = disable  1 = enable
R82 (52h) Charge Pump B	0	CP_DYN_PWR	0	Enable dynamic charge pump power control  0 = Charge pump controlled by volume register settings (Class G)  1 = Charge pump controlled by real-time audio level (Class W)  Class W is recommended for lowest power consumption  When selecting CP_DYN_PWR=0, a '1' must be written to the HPOUT_VU bit (Register R2 or R3) to complete the mode change.

**Table 77 Charge Pump Control** 



## DC SERVO

The WM8963 provides six DC servo circuits - two on the headphone outputs HPOUT1L and HPOUT1R, two on the headphone outputs HPOUT2L and HPOUT2R, and two on the analogue input paths INL and INR. The DC servo circuits remove offset from these signal paths.

Removal of DC offset on the headphone outputs is important because any deviation from GND at the output pin will cause current to flow through the load under quiescent conditions, resulting in increased power consumption. Additionally, the presence of DC offsets can result in audible pops and clicks at power up and power down. The DC servo ensures that the DC level on the headphone outputs is within 1.4mV of GND.

Removal of DC offset on the input paths is important because any deviation from VMID at the ADC input will prevent correct operation of the zero-cross detection and may also restrict the maximum analogue input signal level. (Zero-cross detection is available for PGA volume updates, including when the PGA is controlled by the ALC control.)

The recommended usage of the DC Servo is initialised by running the default Start-Up sequence as described in the "Control Write Sequencer" section. The default Start-Up sequence executes a series of DC offset corrections, after which the measured offset correction is maintained on the headphone output channels.

Updates to the DC Servo correction can also be scheduled using register writes, including during audio playback. The relevant control fields are described in the following paragraphs and are defined in Table 78.

#### DC SERVO ENABLE AND START-UP

The DC Servo circuits are enabled on HPOUT1L and HPOUT1R by setting HP1L\_DCS\_ENA and HP1R\_DCS\_ENA respectively. Equivalent registers are provided for HPOUT2L, HPOUT2R, and for the analogue input paths INL and INR. When the DC Servo is enabled, the DC offset correction can be commanded in different ways, as described below.

Writing a logic 1 to HP1L\_DCS\_STARTUP initiates a series of DC offset measurements and applies the necessary correction to the HPOUT1L output. On completion, the output will be within 1.4mV of AGND. This is the DC Servo mode selected by the default Start-Up sequence. Completion of this DC offset correction is indicated by the DCS\_STARTUP\_DONE\_HP1L, as described in Table 78.

The DC Servo Start-Up function is supported on all six DC Servo channels; individual register control is provided for each channel. The DC Servo Start-Up can be commanded on multiple channels simultaneously if required. Typically, this operation takes 24ms per channel.

The DC Servo control fields associated with start-up operation are described in Table 78. For Headphone output DC offset correction, it is important to note that the DC Servo Start-Up mode should be commanded as part of a control sequence which includes muting and shorting of the headphone outputs; a suitable sequence is defined in the default Start-Up sequence (see "Control Write Sequencer"). See also the "Output Signal Path" section for the details of the recommended Headphone Enable/Disable sequence.

Note that, once the DC offset correction has been performed, the measured offset will be maintained in memory, even when the associated signal path is disabled. This means that, if required, the DC offset correction can be performed on all channels during start-up, and each channel may then be disabled or enabled when required, without having to re-schedule the DC offset correction.

The DC Servo circuit uses the Charge Pump power supply. The Charge Pump must be enabled by setting the CP\_ENA register bit and ensuring that a suitable clock (eg. MCLK) is present. If these conditions are not met, then DC offset correction cannot be performed. See "Charge Pump" and "Clocking and Sample Rates" for details of the associated controls.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R60 (3Ch) DC Servo 0	7	INL_DCS_ENA	0	DC Servo enable for Left input signal path 0 = Disabled 1 = Enabled
	6	INL_DCS_START UP	0	Writing 1 to this bit selects Start-Up DC Servo mode for Left input signal path
	3	INR_DCS_ENA	0	DC Servo enable for Right input signal path 0 = Disabled 1 = Enabled
	2	INR_DCS_START UP	0	Writing 1 to this bit selects Start-Up DC Servo mode for Right input signal path
R61 (3Dh) DC Servo 1	7	HP1L_DCS_ENA	0	DC Servo enable for HPOUT1L 0 = Disabled 1 = Enabled
	6	HP1L_DCS_STA RTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT1L
	3	HP1R_DCS_ENA	0	DC Servo enable for HPOUT1R 0 = Disabled 1 = Enabled
	2	HP1R_DCS_STA RTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT1R
R62 (3Eh) DC Servo 2	7	HP2L_DCS_ENA	0	DC Servo enable for HPOUT2R 0 = Disabled 1 = Enabled
	6	HP2L_DCS_STA RTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT2R
	3	HP2R_DCS_ENA	0	DC Servo enable for HPOUT2R  0 = Disabled  1 = Enabled
	2	HP2R_DCS_STA RTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT2R
R66 (42h) DC Servo 6	10	DCS_STARTUP_ DONE_IN1L	0	DC Servo Start-Up Status (Left Input) 0 = Not complete 1 = Complete
	9	DCS_STARTUP_ DONE_IN1R	0	DC Servo Start-Up Status (Right Input) 0 = Not complete 1 = Complete
	8	DCS_STARTUP_ DONE_HP1L	0	DC Servo Start-Up Status (HPOUT1L) 0 = Not complete 1 = Complete
	7	DCS_STARTUP_ DONE_HP1R	0	DC Servo Start-Up Status (HPOUT1R) 0 = Not complete 1 = Complete
	6	DCS_STARTUP_ DONE_HP2L	0	DC Servo Start-Up Status (HPOUT2L) 0 = Not complete 1 = Complete
	5	DCS_STARTUP_ DONE_HP2R	0	DC Servo Start-Up Status (HPOUT2R) 0 = Not complete 1 = Complete

Table 78 DC Servo Enable and Start-Up Modes



#### DC SERVO ACTIVE MODES

The DC Servo Start-Up mode described above is suitable for initialising the DC offset correction circuit on the input or output signal paths as part of a controlled start-up sequence which is executed before the signal path is fully enabled. The WM8963 also supports DC offset measurement and correction on the HP output paths whilst the signal path is active; this may be of benefit following a large change in signal gain, which can lead to a change in DC offset level.

Writing a logic 1 to HP1L\_DCS\_SYNC initiates a series of DC offset measurements and applies the necessary correction to the HP0UT1L output. Writing a logic 1 to HP1R\_DCS\_SYNC initiates a series of DC offset measurements and applies the necessary correction to the HP0UT1R output. Equivalent register controls are provided for the HP0UT2L and HP0UT2R outputs.

The number of DC Servo operations performed is determined by HP1\_DCS\_SYNC\_STEP (for HPOUT1L and HPOUT1R) or HP2\_DCS\_SYNC\_STEP (for HPOUT2L and HPOUT2R). A maximum of 127 operations may be selected, though a much lower value will be sufficient in most applications. The DC Servo uses filtering to measure the DC offset in the presence of any audio that may be present; this requires a longer time to perform the correction process than in the Start-Up mode, and means that the DC Servo may be operating for several seconds after the process was initiated.

The DC Servo Sync mode described above is supported on the HPOUT1 and HPOUT2 DC Servo channels; individual register control is provided for each channel. It is recommended that the DC Servo Sync mode is scheduled whenever a large change in signal gain (eg. >6dB) is applied in the output signal path. Note that the DC Servo Sync mode is not required on the input signal paths as the DC offset in these paths does not change with gain, and only the Start-Up correction is necessary.

The DC Servo control fields associated with Sync mode (suitable for use on a signal path that is in active use) are described in Table 79.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R61 (3Dh) DC Servo 1	4	HP1L_DCS_SYN C	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT1L
	0	HP1R_DCS_SYN C	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT1R
R62 (3Eh) DC Servo 2	4	HP2L_DCS_SYN C	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT2L
	0	HP2R_DCS_SYN C	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT2R
R64 (40h) DC Servo 4	13:7	HP1_DCS_SYNC _STEPS [6:0]	10h	Number of DC Servo updates to perform in a series event (HPOUT1L and HPOUT1R)  00h to 0Fh = Reserved  10h = 16 (default)  11h = 17  7Fh = 127
R65 (41h) DC Servo 5	6:0	HP2_DCS_SYNC _STEPS [6:0]	10h	Number of DC Servo updates to perform in a series event (HPOUT2L and HPOUT2R)  00h to 0Fh = Reserved  10h = 16 (default)  11h = 17   7Fh = 127

Table 79 DC Servo Active Modes



## REFERENCE VOLTAGES AND BIAS CONTROL

This section describes the analogue reference voltage and bias current controls. It also describes the VMID soft-start circuit for pop suppressed start-up and shut-down. Note that, under the recommended usage conditions of the WM8963, these features will be configured by running the default Start-Up and Shut-Down sequences as described in the "Control Write Sequencer" section. In these cases, the user does not need to set these register fields directly.

#### **ANALOGUE REFERENCE AND MASTER BIAS**

The analogue circuits in the WM8963 require a mid-rail analogue reference voltage, VMID. This reference is generated from AVDD via a programmable resistor chain. The VMID reference generator requires a bias current, which is enabled by STARTUP\_BIAS\_ENA. Together with the external VMID decoupling capacitor, the programmable VMID resistor chain results in a slow, normal or fast charging characteristic on VMID. This is controlled by the VMID\_SEL register, and can be used to optimise the reference for normal operation, low power standby or for fast start-up as described in Table 80. For normal operation, the VMID\_SEL field should be set to 01.

A soft-start circuit is provided in order to control the switch-on of the VMID reference; this is enabled by setting VMID\_RAMP. When the soft-start circuit is enabled prior to enabling VMID\_SEL, the VMID reference rises smoothly, without any step change that could otherwise occur.

The analogue circuits in the WM8963 require a bias current. The normal bias current is enabled by setting BIAS\_ENA. Note that the normal bias current source requires VMID to be enabled also.

The analogue inputs to the WM8963 are biased to VMID in normal operation. In order to avoid audible pops caused by a disabled signal path dropping to AGND, the WM8963 can maintain these connections at VMID when the relevant input stage is disabled. This is achieved by connecting a buffered VMID reference to the input or output. The buffered VMID reference is enabled by setting VMID\_BUF\_ENA.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	8:7	VMID_SEL [1:0]	00	VMID Divider Enable and Select  00 = VMID disabled (for OFF mode)  01 = 2 x 50k divider (for normal operation)  10 = 2 x 250k divider (for low power standby)  11 = 2 x 5k divider (for fast start-up)
	6	BIAS_ENA	0	Enables the Normal bias current generator (for all analogue functions)  0 = Disabled  1 = Enabled
R28 (1Ch) Anti-pop	4	STARTUP_B IAS_ENA	0	Enables the Start-Up bias current generator 0 = Disabled 1 = Enabled
	3	VMID_BUF_ ENA	0	VMID Buffer Enable 0 = Disabled 1 = Enabled
	2	VMID_RAMP	0	Enables VMID soft ramp-up 0 = Disabled 1 = Enabled

Table 80 Reference Voltages and Master Bias Enable



## **INPUT SIGNAL PATH BIAS CONTROL SETTINGS**

All the analogue circuits of the WM8963 require a bias current. The bias current in the input signal path circuits can be controlled using the register bits described in Table 81.

When adjusting the bias settings, there is always a trade-off between performance and power. Selecting a lower bias can be used to reduce power consumption, but may have a marginal impact on audio performance in some usage modes. Selecting a higher bias offers a performance improvement, but also an increase in power consumption.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R23 (17h) Additional Control (1)	5	ADC_HP	0	ADC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)
R35 (23h) Input bias control	5:3	MIXIN_BIAS [2:0]	000	Input Boost-Mixer Bias Control 000 = x 2.0 (default) 001 = Reserved 010 = Reserved 011 = x 1.0 100 = x 0.67 101 to 111 = Reserved
	2:0	INPGA_BIAS [2:0]	100	Input PGA Bias Control $000 = x 2.0$ $001 = Reserved$ $010 = Reserved$ $011 = Reserved$ $100 = x 0.67 (default)$ $101 to 111 = Reserved$

Table 81 Input Signal Path Bias Control Settings

It is recommended that the input signal path bias control settings are selected only from the supported combinations listed in Table 82.

DESCRIPTION	ADC_HP	MIXIN_BIAS	INPGA_BIAS	NOTES
Option 1	0	100	100	Lowest power consumption
Option 2	0	011	100	
Option 3 (default)	0	000	100	
Option 4	1	000	000	Highest performance

Table 82 Recommended Bias Control Settings (Input Signal Path)



#### **OUTPUT SIGNAL PATH BIAS CONTROL SETTINGS**

All the analogue circuits of the WM8963 require a bias current. The bias current in the output signal path circuits can be controlled using the register bits described in Table 83.

When adjusting the bias settings, there is always a trade-off between performance and power. Selecting a lower bias can be used to reduce power consumption, but may have a marginal impact on audio performance in some usage modes. Selecting a higher bias offers a performance improvement, but also an increase in power consumption.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R6 (06h) ADC & DAC Control 2	0	DAC_HP	0	DAC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)
R68 (44h) Analogue PGA Bias	2:0	HP_PGAS_BIAS [2:0]	011	Headphone PGA Boost Bias $000 = x 2.0$ $001 = Reserved$ $010 = Reserved$ $011 = x 1.0 (default)$ $100 to 111 = Reserved$
R71 (47h) Analogue HP 2	2:0	HP_BIAS_BOOST [2:0]	011	Headphone Driver Boost Bias $000 = x 2.0$ $001 = Reserved$ $010 = Reserved$ $011 = x 1.0 (default)$ $100 to 111 = Reserved$

**Table 83 Output Signal Path Bias Control Settings** 

It is recommended that the output signal path bias control settings are selected only from the supported combinations listed in Table 84.

Note that, for the specified performance in 'High Performance' mode, the headphone output secondary PGAs must be set to -7dB attenuation. See "Output Signal Path" for details of the associated registers.

DESCRIPTION	DAC_HP	HP_PGAS_BIAS	HP_BIAS_BOOST	HP1L_VOL, HP1R_VOL, HP2L_VOL, HP2R_VOL
Low Power headphone playback mode	0	011	011	XXX
High Performance headphone playback mode	1	000	000	000

Table 84 Recommended Bias Control Settings (Output Signal Path)

Note that power consumption in the WM8963 can be optimised in real time using the adaptive Charge Pump that provides the supply rails to the headphone driver. The Dynamic control mode of the Charge Pump provides lowest power consumption, and may be selected in Low Power or High Performance headphone playback modes.

Note that there are some operating conditions in which the Dynamic control mode should not be selected; these are described in the "Charge Pump" section.



## **DIGITAL AUDIO INTERFACE**

The digital audio interface is used for inputting DAC data to the WM8963 and outputting ADC data from it. The digital audio interface uses four pins:

ADCDAT: ADC data outputDACDAT: DAC data input

LRCLK: Left/Right data alignment clock

BCLK: Bit clock, for synchronisation

The clock signals BCLK and LRCLK can be outputs when the WM8963 operates as a master, or inputs when it is a slave (see "Master and Slave Mode Operation", below).

Four different audio data formats are supported:

- Left justified
- Right justified
- I<sup>2</sup>S
- DSP mode

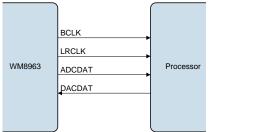
All four of these modes are MSB first. Data words are encoded in 2's complement format. Each of the audio interface modes is described in the following sections. Refer to the "Signal Timing Requirements" section for timing information.

Time Division Multiplexing (TDM) is available in all four data format modes. The WM8963 can be programmed to send and receive data in one of two time slots.

PCM operation is supported using the DSP mode.

#### **MASTER AND SLAVE MODE OPERATION**

The WM8963 digital audio interface can operate as a master or slave as shown in Figure 39 and Figure 40.



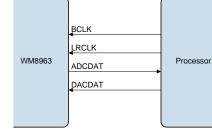


Figure 39 Master Mode

Figure 40 Slave Mode

The Audio Interface output control is illustrated above. The MSTR control register determines whether the WM8963 generates the clock signals. The MSTR register field is defined in Table 85.

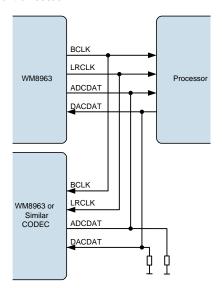
REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R7 (07h)	6	MSTR	0	Audio Interface Mode Select
Audio				0 = Slave mode
Interface 0				1 = Master mode

Table 85 Audio Interface Master/Slave Control



## **OPERATION WITH TDM**

Time division multiplexing (TDM) allows multiple devices to transfer data simultaneously on the same bus. The WM8963 ADCs and DACs support TDM in master and slave modes for all data formats and word lengths. TDM is enabled and configured using register bits defined in the "Digital Audio Interface Control" section.



WM8963 or Similar CODEC

WM8963 or DACDAT

DACDAT

DACDAT

DACDAT

DACDAT

DACDAT

Figure 41 TDM with WM8963 as Master

Figure 42 TDM with Other CODEC as Master

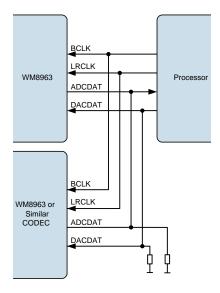


Figure 43 TDM with Processor as Master

**Note:** The WM8963 is a 24-bit device. If the user operates the WM8963 in 32-bit mode then the 8 LSBs will be ignored on the receiving side and not driven on the transmitting side. It is therefore recommended to add a pull-down resistor, if necessary, to the DACDAT line and the ADCDAT line in TDM mode.



#### **BCLK FREQUENCY**

The BCLK frequency is controlled relative to SYSCLK by the BCLK\_DIV divider. Internal clock divide and phase control mechanisms ensure that the BCLK and LRCLK edges will occur in a predictable and repeatable position relative to each other and relative to the data for a given combination of DAC/ADC sample rate and BCLK\_DIV settings.

BCLK\_DIV is defined in the "Digital Audio Interface Control" section. See also "Clocking and Sample Rates" section for more information.

## **AUDIO DATA FORMATS (NORMAL MODE)**

In Right Justified mode, the LSB is available on the last rising edge of BCLK before a LRCLK transition. All other bits are transmitted before (MSB first). Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles after each LRCLK transition.

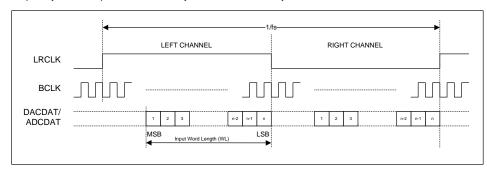


Figure 44 Right Justified Audio Interface (assuming n-bit word length)

In Left Justified mode, the MSB is available on the first rising edge of BCLK following a LRCLK transition. The other bits up to the LSB are then transmitted in order. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles before each LRCLK transition.

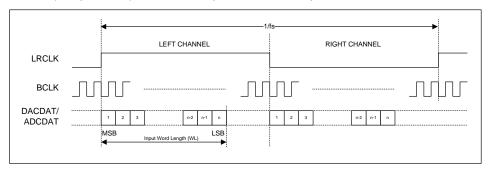


Figure 45 Left Justified Audio Interface (assuming n-bit word length)

In  $l^2S$  mode, the MSB is available on the second rising edge of BCLK following a LRCLK transition. The other bits up to the LSB are then transmitted in order. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles between the LSB of one sample and the MSB of the next.

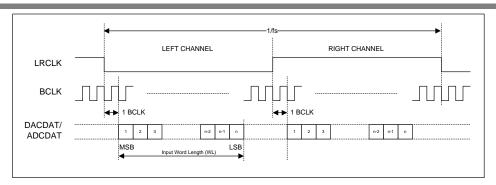


Figure 46 I2S Justified Audio Interface (assuming n-bit word length)

In DSP mode, the left channel MSB is available on either the 1<sup>st</sup> (mode B) or 2<sup>nd</sup> (mode A) rising edge of BCLK (selectable by LRCLK\_INV) following a rising edge of LRCLK. Right channel data immediately follows left channel data. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles between the LSB of the right channel data and the next sample.

In device master mode, the LRC output will resemble the frame pulse shown in Figure 47 and Figure 48. In device slave mode, Figure 49 and Figure 50, it is possible to use any length of frame pulse less than 1/fs, providing the falling edge of the frame pulse occurs greater than one BCLK period before the rising edge of the next frame pulse.

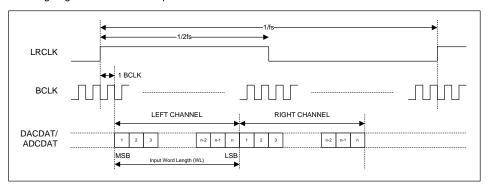


Figure 47 DSP Mode Audio Interface (mode A, LRCLK\_INV=0, Master)

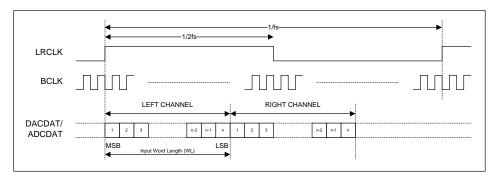


Figure 48 DSP Mode Audio Interface (mode B, LRCLK\_INV=1, Master)

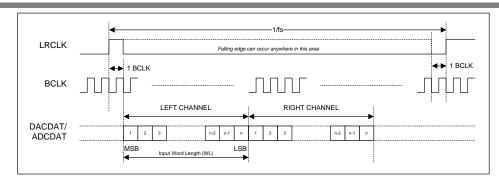


Figure 49 DSP Mode Audio Interface (mode A, LRCLK\_INV=0, Slave)

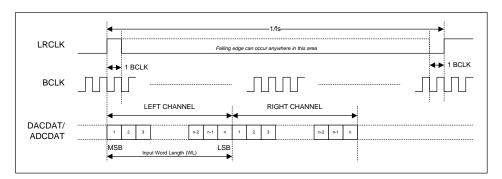


Figure 50 DSP Mode Audio Interface (mode B, LRCLK\_INV=1, Slave)

PCM operation is supported in DSP interface mode. WM8963 ADC data that is output on the Left Channel will be read as mono PCM data by the receiving equipment. Mono PCM data received by the WM8963 will be treated as Left Channel data. This data may be routed to the Left/Right DACs as described in the "Digital Mixing" section.

#### **AUDIO DATA FORMATS (TDM MODE)**

TDM is supported in master and slave mode and is enabled by register bits AIFADC\_TDM\_MODE and AIFDAC\_TDM\_MODE. All audio interface data formats support time division multiplexing (TDM) for ADC and DAC data.

Two time slots are available (Slot 0 and Slot 1), selected by register bits AIFADC\_TDM\_SLOT and AIFDAC\_TDM\_SLOT which control time slots for the ADC data and the DAC data.

When TDM is enabled, the ADCDAT pin will be tri-stated immediately before and immediately after data transmission, to allow another ADC device to drive this signal line for the remainder of the sample period. Note that it is important that two ADC devices do not attempt to drive the data pin simultaneously. A short circuit may occur if the transmission time of the two ADC devices overlap with each other. See "Audio Interface Timing" for details of the ADCDAT output relative to BCLK signal. Note that it is possible to ensure a gap exists between transmissions by setting the transmitted word length to a value higher than the actual length of the data. For example, if 32-bit word length is selected where only 24-bit data is available, then the WM8963 interface will tri-state after transmission of the 24-bit data, ensuring a gap after the WM8963's TDM slot.

When TDM is enabled, BCLK frequency must be high enough to allow data from both time slots to be transferred. The relative timing of Slot 0 and Slot 1 depends upon the selected data format as shown in Figure 51 to Figure 55.



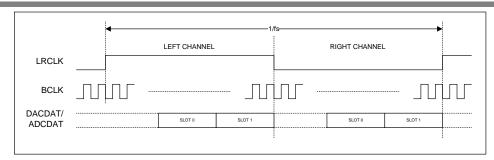


Figure 51 TDM in Right-Justified Mode

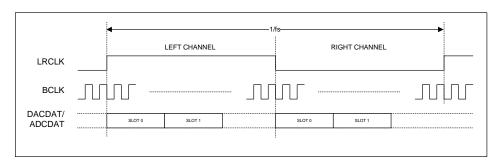


Figure 52 TDM in Left-Justified Mode

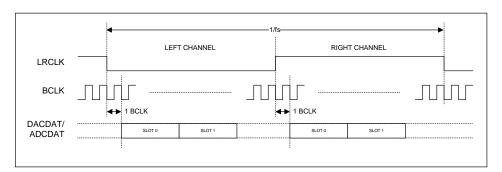


Figure 53 TDM in I2S Mode

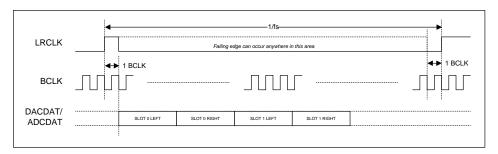


Figure 54 TDM in DSP Mode A



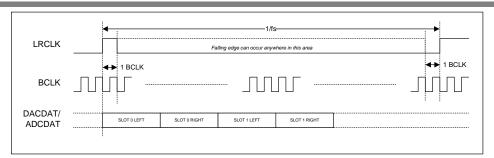


Figure 55 TDM in DSP Mode B

# **DIGITAL AUDIO INTERFACE CONTROL**

The register bits controlling audio data format, word length, left/right channel data configuration and TDM are summarised in Table 86.

REGISTER ADDRESS	ВІТ	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC and DAC	6	ADCR_DAT_IN V	0	Right ADC Invert 0 = Right ADC output not inverted 1 = Right ADC output inverted
Control 1	5	ADCL_DAT_INV	0	Left ADC Invert  0 = Left ADC output not inverted  1 = Left ADC output inverted
R6 (06h) ADC and DAC	6	DACR_DAT_IN V	0	Right DAC Invert 0 = Right DAC input not inverted 1 = Right DAC input inverted
Control 2	5	DACL_DAT_INV	0	Left DAC Invert  0 = Left DAC input not inverted  1 = Left DAC input inverted
R7 (07h) Audio Interface 0	12	AIFDAC_TDM_ MODE	0	DAC TDM Mode Select  0 = Normal DACDAT operation (1 stereo slot)  1 = TDM enabled on DACDAT (2 stereo slots)
	11	AIFDAC_TDM_ SLOT	0	DACDAT TDM Slot Select 0 = DACDAT data input on slot 0 1 = DACDAT data input on slot 1
	10	AIFADC_TDM_ MODE	0	ADC TDM Mode Select  0 = Normal ADCDAT operation (1 stereo slot)  1 = TDM enabled on ADCDAT (2 stereo slots)
	9	AIFADC_TDM_ SLOT	0	ADCDAT TDM Slot Select 0 = ADCDAT data input on slot 0 1 = ADCDAT data input on slot 1
	8	ADC_LRSWAP	0	Swap left/right ADC data on the interface 0 = Normal 1 = ADCDAT channels swapped
	7	BCLK_INV	0	BCLK Invert 0 = BCLK not inverted 1 = BCLK inverted
	5	DAC_LRSWAP	0	Swap left/right DAC data on the interface 0 = Normal 1 = DACDAT channels swapped



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	4	LRCLK_INV	0	Right, left and I <sup>2</sup> S modes – LRCLK polarity 0 = normal LRCLK polarity 1 = invert LRCLK polarity
				DSP Mode – mode A/B select  0 = MSB is available on 2nd BCLK rising edge after LRCLK rising edge (mode A)  1 = MSB is available on 1st BCLK rising edge after LRCLK rising edge (mode B)
	3:2	WL [1:0]	10	Digital Audio Interface Word Length  00 = 16 bits  01 = 20 bits  10 = 24 bits  11 = 32 bits  Note - see "Companding" for the selection of 8-bit mode.
	1:0	FMT [1:0]	10	Digital Audio Interface Format  00 = Right justified  01 = Left justified  10 = I <sup>2</sup> S Format  11 = DSP Mode

Table 86 Digital Audio Interface Data Control

## **AUDIO INTERFACE TRI-STATE**

Register bit AIF\_TRI can be used to tri-state the audio interface pins as described in Table 87. All digital audio interface pins will be tri-stated by this function, regardless of the state of other registers which control these pin configurations.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R24 (18h) Additional Control (2)	3	AIF_TRI	0	Audio Interface Tristate  0 = Audio interface pins operate normally  1 = ADCDAT is tri-stated; BCLK and LRCLK are set as inputs

Table 87 Digital Audio Interface Tri-State Control

## **BCLK AND LRCLK CONTROL**

The audio interface can be programmed to operate in master mode or slave mode using the MSTR register bit.

In master mode, the BCLK and LRCLK signals are generated by the WM8963 when any of the ADCs or DACs is enabled. In slave mode, the BCLK and LRCLK clock outputs are disabled by default to allow another digital audio interface to drive these pins. Refer to "Clocking and Sample Rates" for specific operating constraints in this configuration.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R7 (07h)	6	MSTR	0	Audio Interface Mode Select
Audio				0 = Slave mode
Interface 0				1 = Master mode
R8 (08h)	3:0	BCLK_DIV	0100	BCLK Rate
Clocking2				0000 = DSPCLK
				0001 = Reserved
				0010 = DSPCLK / 2
				0011 = DSPCLK / 3
				0100 = DSPCLK / 4 (default)
				0101 = Reserved
				0110 = DSPCLK / 6
				0111 = DSPCLK / 8
				1000 = Reserved
				1001 = DSPCLK / 12
				1010 = DSPCLK / 16
				1011 = DSPCLK / 24
				1100 = Reserved
				1101 = DSPCLK / 32
				1110 = DSPCLK / 32
				1111 = DSPCLK / 32
R14 (0Eh)	10:0	AIF_RATE	040h	LRCLK Rate
Audio		[10:0]		LRCLK clock output =
Interface 2				BCLK / AIF_RATE
				Integer (LSB = 1)
				Valid from 42047
				Default (040h) = 64 BCLKs per LRCLK

Table 88 Digital Audio Interface Clock Control

# **COMPANDING**

The WM8963 supports A-law and  $\mu$ -law companding on both transmit (ADC) and receive (DAC) sides as shown in Table 89.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R9 (09h) Audio Interface 1	4	DAC_COMP	0	DAC Companding Enable 0 = disabled 1 = enabled
	3	DAC_COMPMODE	0	DAC Companding Type $0 = \mu\text{-law}$ $1 = A\text{-law}$
	2	ADC_COMP	0	ADC Companding Enable 0 = disabled 1 = enabled
	1	ADC_COMPMODE	0	ADC Companding Type $0 = \mu\text{-law}$ $1 = A\text{-law}$

**Table 89 Companding Control** 



Companding involves using a piecewise linear approximation of the following equations (as set out by ITU-T G.711 standard) for data compression:

 $\mu$ -law (where  $\mu$ =255 for the U.S. and Japan):

$$F(x) = \ln(1 + \mu |x|) / \ln(1 + \mu)$$
  $-1 \le x \le 1$ 

A-law (where A=87.6 for Europe):

F(x) = A|x| / (1 + InA)  $x \le 1/A$ F(x) = (1 + InA|x|) / (1 + InA)  $1/A \le x \le 1$ 

The companded data is also inverted as recommended by the G.711 standard (all 8 bits are inverted for  $\mu$ -law, all even data bits are inverted for A-law). The data will be transmitted as the first 8 MSBs of data.

Companding converts 13 bits ( $\mu$ -law) or 12 bits (A-law) to 8 bits using non-linear quantization. This provides greater precision for low amplitude signals than for high amplitude signals, resulting in a greater usable dynamic range than 8 bit linear quantization. The companded signal is an 8-bit word comprising sign (1 bit), exponent (3 bits) and mantissa (4 bits).

8-bit mode is selected whenever DAC\_COMP=1 or ADC\_COMP=1. The use of 8-bit data allows samples to be passed using as few as 8 BCLK cycles per LRCLK frame. When using DSP mode B, 8-bit data words may be transferred consecutively every 8 BCLK cycles.

8-bit mode (without Companding) may be enabled by setting DAC\_COMPMODE=1 or ADC\_COMPMODE=1, when DAC\_COMP=0 and ADC\_COMP=0.

BIT7	BIT[6:4]	BIT[3:0]
SIGN	EXPONENT	MANTISSA

Table 90 8-bit Companded Word Composition

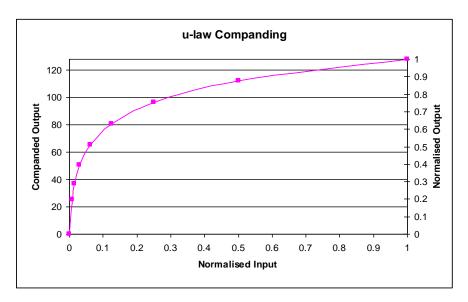


Figure 56 µ-Law Companding

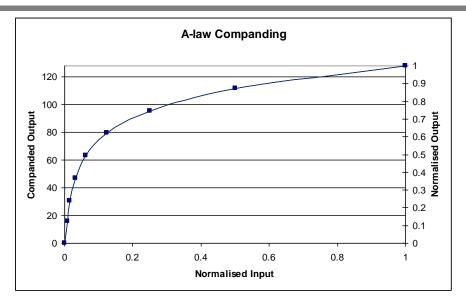


Figure 57 A-Law Companding

## **LOOPBACK**

Setting the LOOPBACK register bit enables digital loopback. When this bit is set, the ADC digital data output is routed to the DAC digital data input path. The digital audio interface input (DACDAT) is not used when LOOPBACK is enabled.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R9 (09h)	0	LOOPBACK	0	Digital Loopback Function
Audio				0 = No loopback
Interface (2)				1 = Loopback enabled (ADC data output
				is directly input to DAC data input).

**Table 91 Loopback Control** 

**Note:** When the digital sidetone is enabled, ADC data will also be added to DAC digital data input path within the Digital Mixing circuit. This applies regardless of whether LOOPBACK is enabled.



## **CLOCKING AND SAMPLE RATES**

The internal clocks for the WM8963 are all derived from a common internal clock source, SYSCLK. This clock is the reference for the ADCs, DACs, DSP core functions, digital audio interface, Class D switching amplifier, DC servo control and other internal functions.

SYSCLK can either be derived directly from MCLK, or may be generated from the Frequency Locked Loop (FLL), or from the crystal oscillator. Many commonly-used audio sample rates can be derived directly from typical MCLK frequencies; the FLL provides additional flexibility for a wide range of reference frequencies. To avoid audible glitches, all clock configurations must be set up before enabling playback. The FLL can be used to generate a free-running clock in the absence of an external reference source; see "Frequency Locked Loop (FLL)" for further details of the FLL circuit.

The WM8963 supports automatic clocking configuration. The programmable dividers associated with the ADCs, DACs, DSP core functions, Class D switching and DC servo are configured automatically, with values determined from the MCLK\_RATE and SAMPLE\_RATE fields. The user must also configure the OPCLK (if required), the TOCLK (if required) and the digital audio interface.

ADC/DAC oversample rates of 64fs or 128fs are supported (based on a 48kHz sample rate).

A 256kHz clock, supporting a number of internal functions, is derived from SYSCLK.

The Class D switching amplifier and DC servo control circuits are clocked from SYSCLK.

A GPIO Clock, OPCLK, can be derived from SYSCLK and output on the GPIO2 pin to provide clocking to other devices. This clock is enabled by OPCLK\_ENA and controlled by OPCLK\_DIV.

A slow clock, TOCLK, is used to set the timeout period for volume updates when zero-cross detect is used. This clock is enabled by TOCLK\_ENA and controlled by TOCLK\_DIV. A de-bounce clock, DBCLK, is used to control the de-bouncing of button/accessory detect GPIO input and selected interrupt inputs. This clock is enabled automatically whenever GPIO or interrupt de-bouncing is selected. The de-bounce clock frequency is controlled by DBCLK\_DIV.

In master mode, BCLK is derived from DSPCLK via a programmable divider set by BCLK\_DIV. In master mode, the LRCLK is derived from BCLK via a programmable divider AIF\_RATE.

In Slave mode, BCLK and LRCLK are inputs to the WM8963, allowing another digital audio interface to drive these pins. See the "BCLK and LRCLK Control" sub-section for specific operating constraints in this configuration.

The control registers associated with Clocking and Sample Rates are shown in Table 94 to Table 99.

The overall clocking scheme for the WM8963 is illustrated in Figure 58.



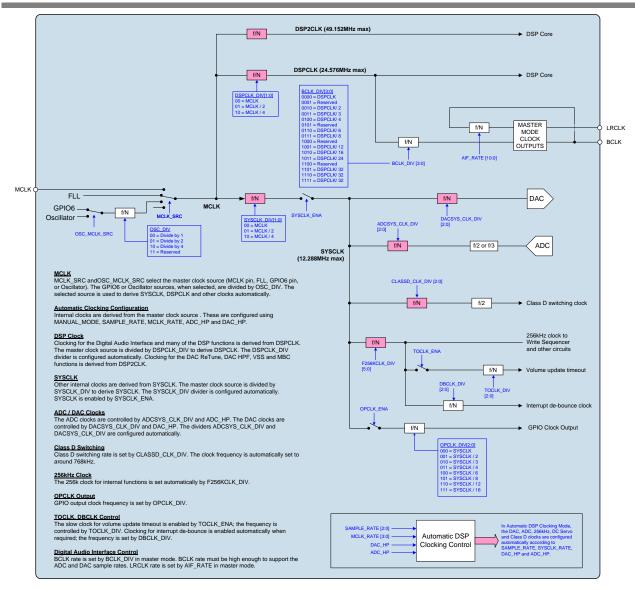


Figure 58 SYSCLK and Internal Clocking Scheme



#### SYSCLK CONTROL

The MCLK\_SRC and OSC\_MCLK\_SRC registers are used to select the source for MCLK. The source may be either the MCLK pin, FLL, GPIO6 pin, or Oscillator. The GPIO6 or Oscillator sources, when selected, are controlled by the OSC\_DIV divider.

The selected source may be adjusted by the programmable divider SYSCLK\_DIV; this is configured automatically by the WM8963 to ensure that SYSCLK <= 12.288MHz. (Note that the SYSCLK\_DIV divider is a read-only register; it cannot be written to.)

The MCLK\_SRC register is controlled automatically under certain circumstances, as described below. The associated control register, CLKREG\_OVD, is defined in the following section ("Automatic Clocking Configuration").

When a logic 1 is applied on the GPIO5 pin, the MCLK\_SRC register is set to 01b, selecting FLL as the source. In this case, the MCLK\_SRC register is locked to prevent accidental writes to this register. The MCLK\_SRC register can be unlocked by setting the CLKREG\_OVD bit.

When a logic 0 is applied on the GPIO5 pin, the MCLK\_SRC register defaults to 00b, selecting MCLK as the source. In this case, the default (00b) is selected on the falling edge of GPIO5; other settings can then be selected by writing to the MCLK\_SRC register as normal.

Note that it is important that the GPIO5 input is held in a defined logic state (logic '0' or logic '1') during start-up; it must not be left floating. If normal GPIO functionality is required on the GPIO5 pin, then the CLKREG\_OVD bit must be set to '1' in order to select normal read/write control of all the clocking registers, and to permit GPIO functions. The GPIO5 pin must be held in a defined logic state (logic '0' or logic '1') whenever the pin is configured as an input, including whenever CLKREG\_OVD = 0 (default).

See "Internal / External Clock Generation" for more details of the FLL and Crystal Oscillator.

The SYSCLK signal is enabled by register bit SYSCLK\_ENA. This bit should be set to 0 when reconfiguring clock sources. Note that, when reconfiguring or disabling SYSCLK, the ADCs and DACs must be disabled before setting SYSCLK\_ENA=0.

The following operating frequency limits are recommended when configuring SYSCLK. Failure to observe these limits may result in degraded noise performance.

- MCLK ≥ 3MHz
- If DAC\_HP = 1, then MCLK ≥ 6MHz

The valid clocking ratios for DAC and/or ADC operation are identified in Table 92. See also Table 93 for details of the supported functions for each combination of Sample Rate and MCLK / fs ratio.

Note that, in some cases, the combination of Sample Rate and MCLK / fs ratio has a dependency on the DCVDD supply voltage. The marked (\*) combinations are only valid for DCVDD  $\geq$  1.7V.

SAMPLE	MCLK RATE (MCLK / fs					K/fsra	atio)				
RATE (kHz)	64	128	192	256	384	512	768	1024	1536	3072	6144
8	1	2	3	4	5	6	6	6	6	6	6*
11.025	1	2	3	4	5	6	6	6	6	6*	
12	1	2	3	4	5	6	6	6	6	6*	
16	1	2	3	4	5	6	6	6	6	6*	
22.05	1	2	3	4	5	6	6	6	6*		
24	1	2	3	4	5	6	6	6	6*		
32	1	2	3	4	5	6	6	6*	6*		
44.1	1	2	3	4	5	6	5*	6*			
48	1	2	3	4	5	6	5*	6*			
88.2	1	2	3	4	3*	4*					
96	1	2	3	4	3*	4*					
Note - the clos	cking co	Note - the clocking configurations marked (*) are only valid for DCVDD ≥ 1.7V.									

Table 92 MCLK / Sample Rate Availability



CODE	DAC/ADC Configuration	ADC Signal Path Enhancements	DAC Signal Path Enhancements		
		HPF, LPF/HPF, DF1 Filter, 3D Surround, Dynamic Range Control (DRC)	Dynamic Range Control (DRC)	5-band EQ	Virtual Surround Sound (VSS), ReTune, DAC HPF, Multiband Compressor (MBC)
1	Mono DAC				
2	Stereo DAC				
3	Stereo DAC		✓	✓	
4	Stereo CODEC	✓	✓		
	or Stereo DAC		✓	✓	
5	Stereo CODEC	✓	✓	✓	
6	Stereo CODEC	✓	✓	✓	✓

Table 93 DAC/ADC and Audio Enhancements Availability

The supported MCLK frequency range is defined in the "Signal Timing Requirements".

The MCLK / fs ratio is set using the MCLK\_RATE register. See "Automatic Clocking Configuration" for details of this register.

The MCLK and SYSCLK control register fields are defined in Table 94.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4 (04h) Clocking1	2:1	SYSCLK_DIV	00	SYSCLK Divider  00 = MCLK  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.  Note that the division is applied to the selected MCLK source, including the FLL or Oscillator, when applicable.
R8 (08h) Clocking2	10:9	MCLK_SRC	00	MCLK source select  00 = MCLK pin  01 = FLL output  10 = GPIO6 or Oscillator (selected by OSC_MCLK_SRC)  11 = Reserved  If CLKREG_OVD = 0, then MCLK_SRC is controlled by the GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 1, then MCLK_SRC = 01 (FLL) and MCLK_SRC cannot be changed by the Control Interface.  If CLKREG_OVD = 0 and GPIO5 = 0, then MCLK_SRC = 00 (MCLK) by default, but the value can be changed via the Control Interface.  If CLKREG_OVD = 1 then MCLK_SRC = 00 (MCLK) by default, but the value can be changed via the Control Interface.
	5	SYSCLK_ENA	1	SYSCLK enable 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R125 (7Dh) Analogue Clocking2	4:3	OSC_DIV	01	GPIO6 / Oscillator to MCLK divider 00 = Divide by 1 01 = Divide by 2 10 = Divide by 4 11 = Reserved
R152 (98h) Analogue Clocking 4	4	OSC_MCLK_SR C	0	GPIO6 / Oscillator to MCLK source 0 = Oscillator 1 = GPIO6 This field selects the MCLK source, when MCLK_SRC =10.

Table 94 MCLK and SYSCLK Control

## **AUTOMATIC CLOCKING CONFIGURATION**

The WM8963 supports a wide range of standard audio sample rates from 8kHz to 96kHz. The Automatic Clocking Configuration mode simplifies the configuration of the clock dividers in the WM8963 by deriving most of the necessary parameters from a minimum number of user registers.

In Automatic mode, the SAMPLE\_RATE field selects the sample rate, fs, of the ADC and DAC. The SAMPLE\_RATE\_INT\_MODE bit should be set according to the selected SAMPLE\_RATE, as described in Table 95. Note that, in Automatic mode, the same sample rate always applies to the ADC and DAC.

In Automatic mode, the MCLK\_RATE field must be set according to the ratio of MCLK to fs. (Note that the MCLK source is selected by MCLK\_SRC - see Table 94.)

Selectable modes of ADC / DAC operation are available using the ADC\_HP and DAC\_HP register bits. The automatic clocking configuration uses DAC\_HP to determine the applicable clock divider settings.

The WM8963 is designed to support specific internal and external clocking configurations. Under default conditions, the GPIO5 pin has control over selected clocking registers, and normal read/write access to some registers is not supported. When the CLKREG\_OVD register is set to 1, the affected clocking registers are controlled as normal via the Control Interface. The registers that are affected by CLKREG\_OVD are noted in Table 100.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R6 (06h) ADC and DAC Control 2	0	DAC_HP	0 DAC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 126)	
R8 (08h) Clocking2	11	CLKREG_OVD	0	Clock Configuration Override  0 = MCLK_SRC, OSC_ENA and  CLKOUT5_SEL registers are controlled by the GPIO5 pin; CLKOUT2_DIV and  CLKOUT5_DIV registers are locked to fixed values.  1 = Clocking registers are controlled as normal via Control Interface.  This bit must be set to 1 to support GPIO functionality on GPIO5.
R23 (17h) Additional Control (1)	5	ADC_HP	0	ADC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)
R27 (1Bh) Additional Control (3)	4	SAMPLE_RATE _INT_MODE	1	Selects the Integer or Fractional value of the SAMPLE_RATE register. 0 = 11.025k, 22.05k, 44.1k or 88.2kHz 1 = 8k, 12k, 16k, 24k, 32k, 48k or 96kHz



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	2:0	SAMPLE_RATE [2:0]	000	Selects the Sample Rate (fs) 000 = 44.1kHz, 48kHz 001 = 32kHz 010 = 22.05kHz, 24kHz 011 = 16kHz 100 = 11.025kHz, 12kHz 101 = 8kHz 110 = 88.2kHz, 96kHz 111 = Reserved
R56 (38h) Clocking 4	4:1	MCLK_RATE [3:0]	0011	Selects the MCLK / fs ratio. (Note that the MCLK source is selected by MCLK_SRC.) 0000 = 64 0001 = 128 0010 = 192 0011 = 256 (default) 0100 = 384 0101 = 512 0110 = 768 0111 = 1024 1000 = Reserved 1001 = 1536 1010 = 3072 1011 = 6144 If DAC ReTune, DAC HPF, VSS or MBC is enabled, then MCLK_RATE must be 512 or higher.

**Table 95 Automatic Clocking Configuration Control** 



# DSP, ADC, DAC CLOCK CONTROL

The clocking of the DSP is derived from MCLK. The clocking of the ADC and DAC circuits is derived from SYSCLK. The associated dividers are configured automatically by the WM8963.

The DSP clocking rate is controlled by DSPCLK\_DIV. In automatic clocking mode, this is configured automatically by the WM8963 to ensure DSPCLK <= 24.576MHz. (Note that the DSPCLK\_DIV divider is a read-only register; it cannot be written to.)

The ADC clocking rate is controlled by ADCSYS\_CLK\_DIV. In automatic clocking mode, the WM8963 uses this divider to derive the most suitable SYSCLK / fs ratio, where fs is the ADC sampling rate.

The DAC clocking rate is controlled by DACSYS\_CLK\_DIV. In automatic clocking mode, the WM8963 uses this divider to derive the most suitable SYSCLK / fs ratio, where fs is the DAC sampling rate.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4 (04h) Clocking 1	10:9	DSPCLK_DIV [1:0]	00	DSP Clock Divider  00 = MCLK  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.
	8:6	ADCSYS_CLK_ DIV [2:0]	000	ADC Sample Rate Divider  000 = SYSCLK  001 = Reserved  010 = SYSCLK / 2  011 = SYSCLK / 3  100 = SYSCLK / 4  101 = Reserved  110 = SYSCLK / 6  111= Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.
	5:3	DACSYS_CLK_ DIV [2:0]	100	DAC Sample Rate Divider  000 = SYSCLK  001 = Reserved  010 = SYSCLK / 2  011 = SYSCLK / 3  100 = SYSCLK / 4  101 = Reserved  110 = SYSCLK / 6  111= Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.

Table 96 DSP, ADC, DAC Clock Control



# CLASS D, 256K, DC SERVO CLOCK CONTROL

The clocking of the Class D amplifier, DC Servo and other functions is derived from SYSCLK. The associated dividers are configured automatically by the WM8963.

The Class D amplifier switching frequency is controlled by CLASSD\_CLK\_DIV. In automatic clocking mode, the WM8963 uses this divider to generate a Class D clock that is approximately 768kHz. (Note that there is an additional divide by two in the output stage producing a 384kHz switching frequency.)

A 256kHz clock is required for other circuits, including the Control Write Sequencer. In automatic clocking mode, the WM8963 uses F256KCLK\_DIV to generate a clock that is approximately 256kHz.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R8 (08h)	8:6	CLASSD_CLK_	111	Class D Clock Divider
Clocking2		DIV [2:0]		000 = SYSCLK
				001 = SYSCLK / 2
				010 = SYSCLK / 3
				011 = SYSCLK / 4
				100 = SYSCLK / 6
				101 = SYSCLK / 8
				110 = SYSCLK / 12
				111= SYSCLK / 16
				This field is for read-back only; it is set
				automatically and cannot be adjusted.
R30 (1Eh)	6:1	F256KCLK_DIV	2Fh	256kHz Clock Divider
Clocking 3		[5:0]		0d = SYSCLK
				1d = SYSCLK / 2
				2d = SYSCLK / 3
				63d = SYSCLK / 64
				This field is for read-back only; it is set
				automatically and cannot be adjusted

Table 97 Class D, 256k, DC Servo Clock Control

# **OPCLK CONTROL**

A clock output (OPCLK) derived from SYSCLK may be output on the GPIO2 pin. This clock is enabled by register bit OPCLK\_ENA, and its frequency is controlled by OPCLK\_DIV.

This output of this clock is also dependent upon the GPIO register settings described in the "General Purpose Input/Output (GPIO)" section.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	9	OPCLK_ENA	0	GPIO Clock Output Enable 0 = Disabled 1 = Enabled
R30 (1Eh) Clocking 3	12:10	OPCLK_DIV [2:0]	000	GPIO Output Clock Divider  000 = SYSCLK  001 = SYSCLK / 2  010 = SYSCLK / 3  011 = SYSCLK / 4  100 = SYSCLK / 6  101 = SYSCLK / 8  110 = SYSCLK / 12  111 = SYSCLK / 16  000 = SYSCLK / 16

**Table 98 OPCLK Control** 

## TOCLK, DBCLK CONTROL

A slow clock (TOCLK) is derived from the internally generated 256kHz clock to enable input debouncing and volume update timeout functions. This clock is enabled by register bit TOCLK\_ENA, and its frequency is controlled by TOCLK\_DIV.

A de-bounce clock, DBCLK, is used to control the de-bouncing of GPIO inputs and selected interrupt inputs. This clock is enabled automatically whenever GPIO or interrupt de-bouncing is selected. The de-bounce clock frequency is controlled by DBCLK\_DIV.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R23 (17h) Additional Control(1)	0	TOCLK_ENA	0	TOCLK Enable 0 = Disabled 1 = Enabled
R30 (1Eh) Clocking 3	15:13	DBCLK_DIV [2:0]	000	DBCLK Rate Divider (divides the 256kHz clock; nominal frequency is quoted in brackets) 000 = f / 256 (1kHz) 001 = f / 2048 (125Hz) 010 = f / 4096 (62.5Hz) 011 = f / 8192 (31.2Hz) 100 = f / 16384 (15.6Hz) 101 = f / 32768 (7.8Hz) 110 = f / 64536 (3.9Hz) 111 = f / 131072 (1.95Hz)
	9:7	TOCLK_DIV [2:0]	000	TOCLK Rate Divider (divides the 256kHz clock; nominal frequency is quoted in brackets) 000 = f / 256 (1kHz) 001 = f / 512 (500Hz) 010 = f / 1024 (250Hz) 011 = f / 2048 (125Hz) 100 = f / 4096 (62.5Hz) 101 = f / 8192 (31.2Hz) 110 = f / 16384 (15.6Hz) 111 = f / 32768 (7.8Hz)

Table 99 TOCLK, DBCLK Control



#### **BCLK AND LRCLK CONTROL**

In master mode, BCLK is derived from DSPCLK via a programmable division set by BCLK\_DIV.

In master mode, LRCLK is derived from BCLK via a programmable division set by AIF\_RATE.

See "Digital Audio Interface Control" for details of these fields.

In Slave mode, BCLK/LRCLK should not be stopped whilst a DAC to Speaker playback path is active unless SYSCLK is also stopped. Failure to meet this requirement may result in a DC output at the speaker outputs, and possible speaker damage.

In Slave mode, if BCLK/LRCLK may stop during DAC to Speaker playback then it is recommended to use a SYSCLK source that will also stop at the same time as BCLK/LRCLK. It is important to note that the FLL will continue to run even when its input reference is removed; if the FLL is selected as the SYSCLK source, then SYSCLK will not stop if BCLK/LRCLK is stopped.

If SYSCLK is stopped whenever BCLK/LRCLK is stopped, or if the audio interface is operating in Master mode, then no specific action is required in relation to BCLK/LRCLK stopping.

If BCLK/LRCLK may stop during DAC to Speaker playback, with SYSCLK still running, then it is recommended to disable the Speaker output (see "Output Signal Path") before stopping BCLK/LRCLK.

If it is not possible to change the WM8963 settings before BCLK/LRCLK are stopped (ie. the BCLK/LRCLK inputs may stop unpredictably), then the DAC 2<sup>nd</sup> order HPF should be enabled in order to remove DC offsets in the output signal. See "DAC Signal Path Enhancements" for details of this feature.

## **CONTROL INTERFACE CLOCKING**

Register map access is possible with or without a system clock (SYSCLK). The source for SYSCLK may be either the MCLK pin or the FLL output, as described above in the "SYSCLK Control" section.

When SYSCLK\_ENA = 1, then an active clock source for SYSCLK must be present for control interface clocking. If the SYSCLK source is stopped, then SYSCLK\_ENA must be set to 0 for control register access.



# **INTERNAL / EXTERNAL CLOCK GENERATION**

The WM8963 provides many features to generate clocks for internal and external use. The internal SYSCLK is either generated from MCLK directly, or can be generated using the FLL and/or the crystal oscillator.

The WM8963 Clock Generation options are illustrated in Figure 59.

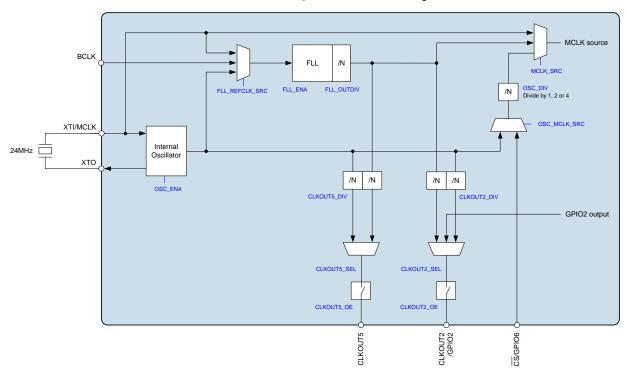


Figure 59 Clock Generation Block Diagram

The MCLK pin supports clock input from an external source; this provides a reference for clocking the WM8963 internal circuits via SYSCLK. The WM8963 also provides an internal oscillator circuit, using an external crystal connected to the MCLK pin.

The output of the oscillator can be output directly on the CLKOUT2 or CLKOUT5 pins.

The WM8963 incorporates a Frequency Locked Loop (FLL). The input reference to the FLL is selectable; it can be either the MCLK or BCLK pin directly, or else the internal oscillator. The FLL can be used to generate SYSCLK.

The output of the FLL can also be output directly on the CLKOUT2 or CLKOUT5 pins;

The CLKOUT2 pin can alternatively be used for GPIO functions.



#### START-UP OPTIONS FOR INTERNAL / EXTERNAL CLOCK GENERATION

The default (start-up) conditions of the WM8963 can be selected using the GPIO5 pin as a hardware control input. The logic state of the GPIO5 pin during start-up determines the initial value of the clocking control registers, causing different functionality to be selected for each logic state.

Under specific conditions, some of the registers that are controlled by the GPIO5 pin are locked to prevent accidental writes to the affected bit(s). In some cases, the GPIO5 pin determines the initial condition, but the register can still be updated via the Control Interface.

It is possible to unlock all of the clocking control registers, giving full flexibility of the clocking configuration and to enable GPIO functionality on the GPIO5 pin.

The start-up options for the WM8963 are summarised below. The behaviour of the associated clocking control registers is summarised in Table 100.

The WM8963 can be configured to generate a CLKOUT5 output as a default start-up condition. Under default register conditions, with a logic '1' applied to the GPIO5 pin, the CLKOUT5 pin will default to a Clock output that is derived from the Crystal Oscillator. In this configuration, the Oscillator is enabled by default, and the CLKOUT5 frequency is the oscillator frequency divided by 2.

Under default register conditions, with a logic '0' applied to the GPIO5 pin, the crystal oscillator is disabled by default, and no clocks will be present on any of the CLKOUT*n* pins on start-up.

For full configuration flexibility of the WM8963 Clocking functions, the CLKREG\_OVD bit must be set to '1' in order to select normal read/write access to all clocking control registers.

Note that the GPIO5 pin must be held in a defined logic state (logic '0' or logic '1') during start-up; it must not be left floating. Normal GPIO5 functionality can be enabled after start-up, after setting the CLKREG\_OVD bit to '1'. The GPIO5 pin must be held in a defined logic state (logic '0' or logic '1') whenever the pin is configured as an input, including whenever CLKREG\_OVD = 0.

REGISTER	CLKREG	CLKREG_OVD=1			
	GPIO5=0	GPIO5=1			
MCLK_SRC	00 (MCLK)	00 (MCLK)			
OSC_ENA	0 (Disabled) *	1 (Enabled)	1 (Enabled)		
CLKOUT5_SEL	1 (FLL) *	0 (Oscillator)	0 (Oscillator)		
CLKOUT2_DIV	1 (Divide	1 (Divide by 2) *			
CLKOUT5_DIV	1 (Divide	0 (Divide by 1)			
Note - The register settings marked (*) are locked to prevent accidental writes to these registers.					

Table 100 Start-Up Options for Internal / External Clock Generation

The register settings described in Table 100 are the initial/default values corresponding to each GPIO5 condition and each CLKREG\_OVD condition. (Note that other clocking configuration registers, which have no dependency on GPIO5 or CLKREG\_OVD, are not listed in Table 100.)

When CLKREG\_OVD=0, then the register settings marked (\*) are locked to prevent accidental writes to the associated registers.

When CLKREG\_OVD=1, then all of the clocking control fields can be written via the Control Interface.

The MCLK\_SRC register is described in the "Clocking and Sample Rates" section. The other registers referenced above are described later in this section.



#### INTERNAL OSCILLATOR CONTROL

The internal oscillator is enabled by OSC\_ENA. The oscillator is suitable for operation at 24MHz, using a suitable external crystal. The oscillator should be enabled when an external crystal is connected to MCLK to provide clocking; it should be disabled when an external clock is connected to MCLK.

The OSC\_ENA register is controlled automatically under certain circumstances, as described below. The associated control register, CLKREG\_OVD, is defined in the "Automatic Clocking Configuration" section, (see "Clocking and Sample Rates").

When a logic 0 is applied on the GPIO5 pin, the OSC\_ENA register is set 0. In this case, the OSC\_ENA register is locked to prevent accidental writes to this register. The OSC\_ENA register can be unlocked by setting the CLKREG\_OVD bit.

When a logic 1 is applied on the GPIO5 pin, the OSC\_ENA register defaults to 1. In this case, the default (1) is selected on the rising edge of GPIO5; other settings can then be selected by writing to the OSC\_ENA register as normal.

Note that, if GPIO functionality is required on the GPIO5 pin, then the CLKREG\_OVD bit must be set to '1' in order to select normal read/write control of the OSC\_ENA register.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R129 (81h) PLL 2	7	OSC_ENA	0	Internal Oscillator Enable  0 = Disabled  1 = Enabled  If CLKREG_OVD = 0, then OSC_ENA is controlled by the GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 0, then OSC_ENA = 0 and cannot be changed by the Control Interface.  If CLKREG_OVD = 0 and GPIO5 = 1, then OSC_ENA = 1 by default, but the value can be changed via the Control Interface.  If CLKREG_OVD = 1 then OSC_ENA = 1 by default, but the value can be changed via the Control Interface.

**Table 101 Internal Oscillator Enable** 

The crystal oscillator requires an external crystal on the XTI and XTO pins The WM8963 provides internal loading capacitors for the crystal, removing the need for any external capacitors, as shown in Figure 60.

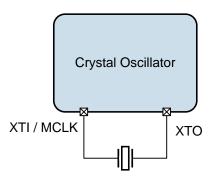


Figure 60 Crystal Oscillator

The internal loading capacitance is detailed in the "Electrical Characteristics". Selection of the correct crystal component is important to ensure best accuracy and stability of the oscillator.

In cases where the internal loading capacitance differs from the required value (eg. due to characteristics of the chosen crystal, or due to additional capacitive effects of PCB tracks), it is possible to compensate for this within the WM8963, using the control registers described below.



The compensation in internal loading capacitance (with respect to the default value) must be configured on the XTI and XTO pins individually. The combined effect of the compensation is as per series-connected capacitors; therefore, if the overall difference required is -1pF, then an adjustment of -2pF must be made on each of the XTI and XTO pins. Note that this sum assumes that the difference is the same for both pins.

To apply the capacitive correction, the combined difference (-2pF in the above example) should be applied to XTI\_CAP\_SEL and XTO\_CAP\_SEL registers.

It is necessary to ensure that the values written to the XTI\_CAP\_SEL and XTO\_CAP\_SEL registers do not cause internal limits to be exceeded; this requires the oscillator trim registers to be read, in order to confirm the amount of calibration already configured to match the specified Electrical Characteristics.

The value written to XTI\_CAP\_SEL, when summed with the trim value OSC\_TRIM\_XTI, must not result in a value outside the limits of OSC\_TRIM\_XTI. The sum of the XTI\_CAP\_SEL and OSC\_TRIM\_XTI settings must be between 8pF and 23.5pF.

The value written to XTO\_CAP\_SEL, when summed with the trim value OSC\_TRIM\_XTO, must not result in a value outside the limits of OSC\_TRIM\_XTO. The sum of the XTO\_CAP\_SEL and OSC\_TRIM\_XTO settings must be between 8pF and 23.5pF.

As an example, if the read value of OSC\_TRIM\_XTI is 21.5pF, then it is not possible to increase the XTI capacitance by more than 2pF - a larger value would exceed the 23.5pF limit.

Note that the description provided here assumes that the difference in capacitance (with respect to the recommended value) is the same for both pins (XTI and XTO).

The relevant registers are described in Table 102.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R115 (73h) Oscillator Trim (3)	4:0	OSC_TRIM_XTI [4:0]		Trimmed Oscillator XTI capacitance  00h = 14pF  01h = 14.5pF  0.5pF steps  15h = 24.5pF  16h = 25pF  17h to1Fh = 25.5pF  This field is for read-back only; it is set automatically and cannot be adjusted.  See Table 103 for details.
R116 (74h) Oscillator Trim (4)	4:0	OSC_TRIM_XT O [4:0]		Trimmed Oscillator XTO capacitance  00h = 14pF  01h = 14.5pF  0.5pF steps  15h = 24.5pF  16h = 25pF  17h to1Fh = 25.5pF  This field is for read-back only; it is set automatically and cannot be adjusted.  See Table 103 for details.
R119 (77h) Oscillator Trim (7)	7:4	XTO_CAP_SEL [3:0]	0000	XTO load capacitance adjustment Two's complement format, LSB = 0.5pF Range is -4.0pF to +3.5pF see Table 104 for details
	3:0	XTI_CAP_SEL [3:0]	0000	XTI load capacitance adjustment Two's complement format, LSB = 0.5pF Range is -4.0pF to +3.5pF see Table 104 for details

**Table 102 Oscillator Trim Control** 



OSC_TRIM_XTI, OSC_TRIM_XTO	DESCRIPTION	OSC_TRIM_XTI, OSC_TRIM_XTO	DESCRIPTION
00000	14.0pF	10000	22.0pF
00001	14.5pF	10001	22.5pF
00010	15.0pF	10010	23.0pF
00011	15.5pF	10011	23.5pF
00100	16.0pF	10100	24.0pF
00101	16.5pF	10101	24.5pF
00110	17.0pF	10110	25.0pF
00111	17.5pF	10111	25.5pF
01000	18.0pF	11000	25.5pF
01001	18.5pF	11001	25.5pF
01010	19.0pF	11010	25.5pF
01011	19.5pF	11011	25.5pF
01100	20.0pF	11100	25.5pF
01101	20.5pF	11101	25.5pF
01110	21.0pF	11110	25.5pF
01111	21.5pF	11111	25.5pF

Table 103 Oscillator Trim Register Readback

XTI_CAP_SEL, XTO_CAP_SEL	DESCRIPTION	XTI_CAP_SEL, XTO_CAP_SEL	DESCRIPTION
0000	0.0pF	1000	-4.0pF
0001	+0.5pF	1001	-3.5pF
0010	+1.0pF	1010	-3.0pF
0011	+1.5pF	1011	-2.5pF
0100	+2.0pF	1100	-2.0pF
0101	+2.5pF	1101	-1.5pF
0110	+3.0pF	1110	-1.0pF
0111	+3.5pF	1111	-0.5pF

**Table 104 Oscillator Trim Adjustment Settings** 



## **CLKOUT CONTROL**

The WM8963 provides two CLKOUT pins for FLL or Oscillator output. The selected function of each is determined by the CLKOUT2\_SEL and CLKOUT5\_SEL registers, as described in Table 105.

The CLKOUT5\_SEL register is controlled automatically under certain circumstances, as described below. The associated control register, CLKREG\_OVD, is defined in the "Automatic Clocking Configuration" section, (see "Clocking and Sample Rates").

When a logic 0 is applied on the GPIO5 pin, the CLKOUT5\_SEL register is set 1, selecting the FLL as the source. In this case, the CLKOUT5\_SEL register is locked to prevent accidental writes to this register. The CLKOUT5\_SEL register can be unlocked by setting the CLKREG\_OVD bit.

When a logic 1 is applied on the GPIO5 pin, the CLKOUT5\_SEL register defaults to 0, selecting the Oscillator as the source. In this case, the default (0) is selected on the rising edge of GPIO5; other settings can then be selected by writing to the CLKOUT5\_SEL register as normal.

Note that, if GPIO functionality is required on the GPIO5 pin, then the CLKREG\_OVD bit must be set to '1' in order to select normal read/write control of the CLKOUT5\_SEL register.

Each of the CLKOUT pins can be enabled or tri-stated using the CLKOUTn\_OE registers. When a pin is tri-stated, it does not support either the FLL output or the GPIO function. See "General Purpose Input/Output (GPIO)" for more details of the GPIO functions.

A selectable divider is available on each of the CLKOUT pins. When the  $CLKOUT_n_DIV$  bit is set, then the respective Clock output is divided by two.

The CLKOUT2\_DIV and CLKOUT5\_DIV registers are controlled automatically under certain circumstances, as noted in Table 105. The associated control register, CLKREG\_OVD, is defined in the "Automatic Clocking Configuration" section, (see "Clocking and Sample Rates").

The CLKOUT control registers are described in Table 105.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R124 (7Ch) Analogue Clocking1	6:5	CLKOUT2_SEL [1:0]	00	CLKOUT2 Output Select  00 = FLL  01 = GPIO2  10 = Internal Oscillator  11 = Reserved
	0	CLKOUT5_SEL	1	CLKOUT5 Output Select  0 = Internal oscillator  1 = FLL  If CLKREG_OVD = 0, then  CLKOUT5_SEL is controlled by the  GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 0,  then CLKOUT5_SEL = 1 (FLL) and  cannot be changed by the Control  Interface.  If CLKREG_OVD = 0 and GPIO5 = 1,  then CLKOUT5_SEL = 0 (Oscillator) by  default, but the value can be changed  via the Control Interface.  If CLKREG_OVD = 1 then  CLKOUT5_SEL = 0 (Oscillator) by  default, but the value can be changed  via the Control Interface.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R125 (7Dh) Analogue Clocking2	1	CLKOUT2_DIV	1	CLKOUT2 Output Divide  0 = Divide by 1  1 = Divide by 2  If CLKREG_OVD = 0, then CLKOUT2_DIV = 1 (Divide by 2) and cannot be changed by the Control Interface.  If CLKREG_OVD = 1, then CLKOUT2_DIV = 0 by default, but the value can be changed via the Control Interface.
	0	CLKOUT5_DIV	1	CLKOUT5 Output Divide  0 = Divide by 1  1 = Divide by 2  If CLKREG_OVD = 0, then  CLKOUT5_DIV = 1 (Divide by 2) and cannot be changed by the Control Interface.  If CLKREG_OVD = 1, then  CLKOUT5_DIV = 0 by default, but the value can be changed via the Control Interface.
R126 (7Eh) Analogue Clocking3	3	CLKOUT2_OE	1	CLKOUT2 Output Enable 0 = Disabled (tri-state) 1 = Enabled
	0	CLKOUT5_OE	1	CLKOUT5 Output Enable 0 = Disabled (tri-state) 1 = Enabled

**Table 105 CLKOUT Control** 

## FREQUENCY LOCKED LOOP (FLL)

The WM8963 incorporates a Frequency Locked Loop (FLL) circuit. The FLL uses a highly accurate and configurable circuit to generate internal or external clocks from a number of different reference sources and frequencies.

The FLL input reference may be a high frequency (eg. 36.864MHz) or low frequency (eg. 32,768kHz). The FLL is tolerant of jitter and may be used to generate a stable SYSCLK from a less stable input signal. The FLL characteristics are summarised in "Electrical Characteristics".

Note that the FLL can be used to generate a free-running clock in the absence of an external reference source. This is described in the "Free-Running FLL Clock" section below. This feature enables clocked functions (such as microphone/accessory detection interrupts) to be supported when the external reference clock or crystal oscillator is not enabled.

The input reference to the FLL is selected by FLL\_REFCLK\_SRC. The available options are MCLK, BCLK, or the internal oscillator.

The FLL control registers are illustrated in Figure 61.

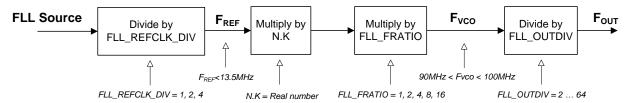


Figure 61 FLL Configuration

The FLL is enabled using the FLL\_ENA register bit. Note that, when changing FLL settings, it is recommended that the digital circuit be disabled via FLL\_ENA and then re-enabled after the other



register settings have been updated. When changing the input reference frequency  $F_{REF}$ , it is recommended the FLL be reset by setting FLL\_ENA to 0.

The field FLL\_REFCLK\_DIV provides the option to divide the input reference (MCLK, BCLK or Internal Oscillator) by 1, 2 or 4. This field should be set to bring the reference down to 13.5MHz or below. For best performance, it is recommended that the highest possible frequency - within the 13.5MHz limit - should be selected.

The FLL output frequency is directly determined from FLL\_FRATIO, FLL\_OUTDIV and the real number represented by N.K.

The integer value, N, is held in the FLL\_N register field, and is used in both Integer and Fractional Modes. The fractional portion, K, is only valid in Fractional Mode when enabled by the field FLL\_FRAC. The value of K is determined by the ratio FLL\_THETA / FLL\_LAMBDA.

It is recommended that FLL Fractional mode is enabled at all times (FLL\_FRAC = 1). Power consumption in the FLL is reduced in integer mode (FLL\_FRAC = 0). However, the performance may also be reduced, with increased noise or jitter on the output.

The FLL output frequency is generated according to the following equation:

$$F_{OUT} = (F_{VCO} / FLL_OUTDIV)$$

The FLL operating frequency, F<sub>VCO</sub> is set according to the following equation:

$$F_{VCO} = (F_{REF} \times N.K \times FLL_FRATIO)$$

F<sub>REF</sub> is the input frequency, as determined by FLL\_REFCLK\_DIV.

 $F_{VCO}$  must be in the range 90-100 MHz. Frequencies outside this range cannot be supported.

Note that the output frequencies that do not lie within the ranges quoted above cannot be guaranteed across the full range of device operating temperatures.

In order to follow the above requirements for  $F_{VCO}$ , the value of FLL\_OUTDIV should be selected according to the desired output  $F_{OUT}$ . The FLL\_OUTDIV register must be set so that  $F_{VCO}$  is in the range 90-100MHz. The available ratios are integers from 2 to 64. Some typical settings of FLL\_OUTDIV are noted in Table 106.

OUTPUT FREQUENCY F <sub>OUT</sub>	FLL_OUTDIV
1.875 MHz - 2.0833 MHz	101111 (F <sub>OUT</sub> clock ratio = 48)
2.8125 MHz - 3.125 MHz	011111 (F <sub>OUT</sub> clock ratio = 32)
3.75 MHz - 4.1667 MHz	010111 (F <sub>OUT</sub> clock ratio = 24)
5.625 MHz - 6.25 MHz	001111 (F <sub>OUT</sub> clock ratio = 16)
11.25 MHz - 12.5 MHz	000111 (F <sub>OUT</sub> clock ratio = 8)
18 MHz - 20 MHz	000100 (F <sub>OUT</sub> clock ratio = 5)
22.5 MHz - 25 MHz	000011 (F <sub>OUT</sub> clock ratio = 4)
40 MHz - 50 MHz	000001 (F <sub>OUT</sub> clock ratio = 2)

Table 106 Selection of FLL\_OUTDIV



The value of FLL FRATIO should be selected as described in Table 107.

REFERENCE FREQUENCY F <sub>REF</sub>	FLL_FRATIO
1MHz - 13.5MHz	0h (F <sub>VCO</sub> clock ratio = 1)
256kHz - 1MHz	1h (F <sub>VCO</sub> clock ratio = 2)
128kHz - 256kHz	2h (F <sub>VCO</sub> clock ratio = 4)
64kHz - 128kHz	3h (F <sub>VCO</sub> clock ratio = 8)
Less than 64kHz	4h (F <sub>VCO</sub> clock ratio = 16)

Table 107 Selection of FLL\_FRATIO

In order to determine the remaining FLL parameters, the FLL operating frequency,  $F_{VCO}$ , must be calculated, as given by the following equation:

$$F_{VCO} = (F_{OUT} x FLL\_OUTDIV)$$

The value of N.K can then be determined as follows:

$$N.K = F_{VCO} / (FLL_FRATIO x F_{REF})$$

Note that, in the above equations:

FLL\_OUTDIV is the F<sub>OUT</sub> clock ratio (2...64).

F<sub>REF</sub> is the input frequency, after division by FLL\_REFCLK\_DIV, where applicable.

FLL\_FRATIO is the  $F_{VCO}$  clock ratio (1, 2, 4, 8 or 16).

The value of N is held in the FLL\_N register field.

The value of K is determined by the ratio FLL\_THETA / FLL\_LAMBDA.

The FLL\_N, FLL\_THETA and FLL\_LAMBDA fields are all coded as integers (LSB = 1).

Note that FLL\_LAMBDA must be set to a non-zero value in Integer and Fractional modes.

In Fractional Mode (FLL\_FRAC = 1), the register fields FLL\_THETA and FLL\_LAMBDA can be calculated as follows:

Calculate GCD(FLL) using the greatest common denominator function:

 $GCD(FLL) = GCD(FLL\_FRATIO \times F_{REF}, F_{VCO})$ 

where GCD(x, y) is the greatest common denominator of x and y

Next, calculate FLL\_THETA and FLL\_LAMBDA using the following equations:

 $FLL\_THETA = (F_{VCO} - (FLL\_N x FLL\_FRATIO x F_{REF})) / GCD(FLL)$ 

 $FLL_LAMBDA = (FLL_FRATIO \times F_{REF}) / GCD(FLL)$ 

Note that, in Fractional Mode, the values of FLL\_THETA and FLL\_LAMBDA must be co-prime (ie. not divisible by any common integer). The calculation above ensures that the values will be co-prime.

The value of K must be a fraction less than 1 (ie. FLL\_THETA must be less than FLL\_LAMBDA).

For best performance, a non-integer value of N.K must be used. If necessary, it is recommended to adjust  $FLL_n$ \_OUTDIV in order to obtain a non-integer value of N.K. Care must always be taken to ensure that the FLL operating frequency,  $F_{VCO}$ , is within its recommended limits of 90-100 MHz.

The FLL control registers are described in Table 108. An example FLL calculation is shown on the following page.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R155 (9Bh) FLL Control (1)	6:5	FLL_REFCLK_S RC [1:0]	00	FLL Clock Source 00 = MCLK 01 = BCLK 10 = Internal Oscillator 11 = Reserved
	3		1	Reserved - Do not change
	2	FLL_FRAC	1	FLL Fractional Mode enable 0 = Integer Mode 1 = Fractional Mode Fractional Mode (FLL_FRAC=1) is
				recommended in all cases
	0	FLL_ENA	0	FLL Enable 0 = Disabled 1 = Enabled
R156 (9Ch) FLL Control (2)	8:3	FLL_OUTDIV [5:0]	000111	FLL F <sub>OUT</sub> clock ratio 000000 = Reserved 000001 = 2 000010 = 3 000011 = 4 000100 = 5 000101 = 6  111110 = 63 111111 = 64 (F <sub>OUT</sub> = F <sub>VCO</sub> / FLL_OUTDIV)
	1:0	FLL_REFCLK_D IV [1:0]	01	FLL Clock Reference Divider  00 = MCLK / 1  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  MCLK (or other input reference) must be divided down to <=13.5MHz.  For lower power operation, the reference clock can be divided down further if desired.
R157 (9Dh)	8:4		11000	Reserved - Do not change
FLL Control (3)	2:0	FLL_FRATIO [2:0]	000	FLL $F_{VCO}$ clock ratio 000 = 1 001 = 2 010 = 4 011 = 8 1XX = 16 000 recommended for $F_{REF} > 1MHz$ $011$ recommended for $F_{REF} < 64kHz$
R158 (9Eh) FLL Control (4)	3:0		0000	Reserved - Do not change
R160 (A0h) FLL Control (6)	15:0	FLL_THETA [15:0]	0018h	FLL Fractional multiply for F <sub>REF</sub> . Only valid when FLL_FRAC = 1. This field sets the numerator (multiply) part of the FLL_THETA / FLL_LAMBDA ratio. It is coded as LSB = 1.





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R161 (A1h) FLL Control (7)	15:0	FLL_LAMBDA [15:0]	007Dh	FLL Fractional multiply for F <sub>REF</sub> . Only valid when FLL_FRAC = 1. This field sets the denominator (dividing) part of the FLL_THETA / FLL_LAMBDA ratio. It is coded as LSB = 1. Note that it is required that FLL_LAMBDA > 0 in all cases (Integer and Fractional modes).
R162 (A2h) FLL Control (8)	9:0	FLL_N [9:0]	008h	FLL Integer multiply for F <sub>REF</sub> (LSB = 1)

**Table 108 FLL Register Controls** 



## FREE-RUNNING FLL CLOCK

The Frequency Locked Loop (FLL) can generate a clock signal even when no external reference is available. However, it should be noted that the accuracy of this clock is reduced, and an external reference source should always be used where possible. Note that, in free-running modes, the FLL is not sufficiently accurate for hi-fi ADC or DAC applications. However, the free-running modes are suitable for clocking most other functions, including the Write Sequencer, Charge Pump, DC Servo and Class D loudspeaker driver. Note that the free-running FLL mode enables microphone/accessory detection interrupts to be supported without external clocking.

If an accurate reference clock is initially available, then the FLL should be configured as described above. The FLL will continue to generate a stable output clock after the reference input is stopped or disconnected.

If no reference clock is available at the time of starting up the FLL, then an internal clock frequency of approximately 12MHz can be generated by implementing the following sequence:

- Enable the FLL Analogue Oscillator (FLL\_OSC\_ENA = 1)
- Set the F<sub>OUT</sub> clock divider to divide by 8 (FLL\_OUTDIV = 000111)
- Configure the oscillator frequency by setting FLL\_FRC\_NCO = 1 and FLL\_FRC\_NCO\_VAL = 19h

Note that the free-running FLL mode is not suitable for hi-fi CODEC applications. In the absence of any reference clock, the FLL output is subject to a very wide tolerance; see "Electrical Characteristics" for details of the FLL accuracy.

Note that the free-running FLL clock is selected as SYSCLK using the registers noted in Figure 59.

The free-running FLL clock may be used to support analogue functions, for which the digital audio interface is not used, and there is no applicable Sample Rate (fs). When SYSCLK is required for circuits such the Class D, DC Servo, Control Write Sequencer or Charge Pump, then valid Sample Rate register settings (SAMPLE\_RATE and MCLK\_RATE) are still required, even though the digital audio interface is not active.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R155 (009Bh) FLL Control (1)	1	FLL_OSC_ENA	0	FLL Oscillator enable 0 = Disabled 1 = Enabled (Note that this field is required for free-running FLL modes only)
R159 (009Fh) FLL Control (5)	6:1	FLL_FRC_NCO _VAL	19h	FLL Forced oscillator value Valid range is 000000 to 111111 0x19h (011001) = 12MHz approx (Note that this field is required for free- running FLL modes only)
	0	FLL_FRC_NCO	0	FLL Forced control select 0 = Normal 1 = FLL oscillator controlled by FLL_FRC_NCO_VAL (Note that this field is required for free- running FLL modes only)

Table 109 FLL Free-Running Mode



## **EXAMPLE FLL CALCULATION**

The following example illustrates how to derive the FLL registers to generate 12.288 MHz output  $(F_{OUT})$  from a 13.000 MHz reference clock  $(F_{REF})$ :

- Set FLL\_REFCLK\_DIV in order to generate F<sub>REF</sub> <=13.5MHz: FLL\_REFCLK\_DIV = 00 (divide by 1)
- Set FLL\_OUTDIV for the required output frequency as shown in Table 106:-F<sub>OUT</sub> = 12.288 MHz, therefore FLL\_OUTDIV = 07h (F<sub>OUT</sub> clock ratio = 8)
- Set FLL\_FRATIO for the given reference frequency as shown in Table 107:
   F<sub>REF</sub> = 13MHz, therefore FLL\_FRATIO = 0h (F<sub>VCO</sub> clock ratio = 1)
- Calculate F<sub>VCO</sub> as given by F<sub>VCO</sub> = F<sub>OUT</sub> x FLL\_OUTDIV:-F<sub>VCO</sub> = 12.288 x 8 = 98.304MHz
- Calculate N.K as given by N.K = F<sub>VCO</sub> / (FLL\_FRATIO x F<sub>REF</sub>): N.K = 98.304 / (1 x 13) = 7.561846
- Determine FLL\_N from the integer portion of N.K:-FLL\_N = 7.
- Determine GCD(FLL), as given by GCD(FLL) = GCD(FLL\_FRATIO x F<sub>REF</sub>, F<sub>VCO</sub>): GCD(FLL) = GCD(1 x 13000000, 98304000) = 8000
- Determine FLL\_THETA, as given by FLL\_THETA = (F<sub>VCO</sub> - (FLL\_N x FLL\_FRATIO x F<sub>REF</sub>)) / GCD(FLL): FLL\_THETA = (98304000 - (7 x 1 x 13000000)) / 8000 FLL\_THETA = 913 (0391h)
- Determine FLL\_LAMBDA, as given by FLL\_LAMBDA = (FLL\_FRATIO x F<sub>REF</sub>) / GCD(FLL): FLL\_LAMBDA = (1 x 13000000) / 8000 FLL\_LAMBDA = 1625 (0659h)



# **GENERAL PURPOSE INPUT/OUTPUT (GPIO)**

The WM8963 provides a multi-function pin which can be configured to provide a number of different functions. These pins provide input and output functions on the DBVDD power domain.

- CLKOUT2/GPIO2
- OSCENA/GPIO5
- CS / GPIO6

Note that, under default conditions, the GPIO5 pin is used as an input to the clocking control functions. The affected registers are described in the "Clocking and Sample Rates" and "Internal / External Clock Generation" sections. It is important that this input is held in a defined logic state (logic '0' or logic '1') during start-up; it must not be left floating. Normal GPIO5 functionality can be enabled after start-up, as described below.

If GPIO functionality is required on the GPIO5 pin, then the CLKREG\_OVD bit must be set to '1' in order to select normal read/write control of all the clocking registers, and to permit GPIO functions.

If the CLKREG\_OVD bit is set to '0' (default), then the GPIO5 control register (R516) must not be changed from the default value. The GPIO5 pin must be held in a defined logic state (logic '0' or logic '1') whenever the pin is configured as an input, including whenever CLKREG\_OVD = 0.

Under default conditions, the GPIO2 pin is configured as the CLKOUT2 function, supporting the FLL or Oscillator output. For GPIO2 functionality, set CLKOUT2\_SEL=01 and CLKOUT2\_OE=1.

See "Internal / External Clock Generation" for details of the CLKOUTn\_SEL and CLKOUTn\_OE registers.

For pins GPIO5 and GPIO6, the pin direction, set by GPn\_DIR, must be set according to the function selected by GP5\_FN or GP6\_FN. The GPIO6 pin can be used to provide the SYSCLK input, as illustrated in Figure 58; the GP6\_DIR bit must be set to '1' (input) in this case.

The characteristics of pins GPIO5 or GPIO6, if selected as an output, may be controlled by setting GPn\_OP\_CFG - an output pin may be either CMOS or Open-Drain. When a pin is configured as a GPIO output, its level can be set to logic 0 or logic 1 using the GPn\_LVL field.

GPIO5 and GPIO6 pins can be configured as GPIO inputs, and can be used to trigger an Interrupt event. This input may be configured as active high or active low using the IRQ\_POL field. Debouncing of this input may be enabled using the GPn\_DB field. Internal pull-up and pull-down resistors may be enabled using the GPn\_PU and GPn\_PD fields. (Note that if GPn\_PU and GPn\_PD are both set for any GPIO pin, then the pull-up and pull-down will be disabled.)

The register fields that control the GPIO pins are described in Table 110.

For each GPIO pin, the selected function is determined by the  $GPn_FN$  field, where 'n' identifies the GPIO pin (2, 5 or 6). The polarity of the GPIO outputs can be selected using the  $GPn_FOL$  register bits

When a pin is configured as a Logic Level output ( $GPn_DIR = 0$ ,  $GPn_FN = 01h$ ), its level can be set to logic 0 or logic 1 using the  $GPn_LVL$  field.

When the GPIO5 or GPIO6 pin is configured as a Logic Level input ( $GPn_DIR = 1$ ,  $GPn_FN = 01h$ ), its level can be read using the  $GPn_LVL$  field.

Note that for FLL or Oscillator output (CLKOUT) on GPIO2, the CLKOUT2\_SEL register must be set to 00 or 10 (see Table 105 for further details). Setting GP2\_FN = 00h is recommended in this case, but it should be noted that the FLL / Oscillator output is only possible using the CLKOUT2\_SEL registers.





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R513 (0201h) GPIO 2	10	GP2_POL	0	GPIO 2 Polarity 0 = Not inverted 1 = Inverted
	6	GP2_LVL	0	GPIO 2 Output Level (when GP2_FN = 00001) 0 = Logic 0 1 = Logic 1 Note that this is a Write-Only register; the Readback value is undefined.
	4:0	GP2_FN[4:0]	00h	GPIO 2 Pin Function select  00h = CLKOUT (FLL) - see note below  01h = Logic 0/1 (set by GP2_LVL)  02h = SDOUT  03h = IRQ  04h = Temperature shutdown  09h = FLL Lock  0Ah = DRC Activity detect  0Bh = Write Sequencer done  0Ch = ALC Noise Gate active  0Dh = ALC Peak Limiter overload  0Eh = ALC Saturation  0Fh = ALC level threshold  10h = ALC Level lock  11h = FIFO error indicator  12h = OPCLK  13h = DMICCLK output  15h = Mic Detect flag  16h = Mic Short Circuit flag  All other codes are Reserved  Note that FLL or Oscillator CLKOUT is enabled using CLKOUT2_SEL. Setting  GP2_FN = 00h is recommended in this case.
R516 (0204h) GPIO 5	15	GP5_DIR	1	GPIO5 Direction 0 = Output 1 = Input
	14	GP5_PU	0	GPIO5 pull-up resistor enable 0 = pull-up disabled 1 = pull-up enabled
	13	GP5_PD	0	GPIO5 pull-down resistor enable 0 = pull-up disabled 1 = pull-down enabled
	10	GP5_POL	0	GPIO5 Polarity 0 = Not inverted 1 = Inverted
	9	GP5_OP_CFG	0	GPIO5 Output pin configuration 0 = CMOS 1 = Open-drain
	8	GP5_DB	1	GPIO5 input de-bounce 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6	GP5_LVL	0	GPIO 5 Level (when GP5_FN = 01h) 0 = Logic 0 1 = Logic 1 Write to this bit to set the GPIO5 output. Read from this bit to read GPIO input level. Note that, when GPIO5 is configured as an output (GP5_DIR=0), this is a Write-Only register; the Readback value is undefined.
	4:0	GP5_FN[4:0]	00h	GPIO5 Pin Function select  00h = Unused  01h = Logic 0/1 (set by GP5_LVL)  02h = SDOUT  03h = IRQ  04h = Temperature shutdown  09h = FLL Lock  0Ah = DRC Activity detect  0Bh = Write Sequencer done  0Ch = ALC Noise Gate active  0Dh = ALC Peak Limiter overload  0Eh = ALC Saturation  0Fh = ALC level threshold  10h = ALC Level lock  11h = FIFO error indicator  12h = OPCLK  13h = DMICCLK output  14h = DMICDAT input  15h = Mic Detect flag  16h = Mic Short Circuit flag  All other codes are Reserved  Note that GPIO5 functions are only supported when CLKREG_OVD=1.  When CLKREG_OVD=0, the contents of Register R516 must not be changed from the default value.
R517 (0205h) GPIO 6	15	GP6_DIR	1	GPIO6 Direction 0 = Output 1 = Input
	14	GP6_PU	0	GPIO6 pull-up resistor enable 0 = pull-up disabled 1 = pull-up enabled
	13	GP6_PD	0	GPIO6 pull-down resistor enable 0 = pull-up disabled 1 = pull-down enabled
	10	GP6_POL	0	GPIO6 Polarity 0 = Not inverted 1 = Inverted
	9	GP6_OP_CFG	0	GPIO6 Output pin configuration 0 = CMOS 1 = Open-drain
	8	GP6_DB	1	GPIO6 input de-bounce 0 = Disabled 1 = Enabled





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6	GP6_LVL	0	GPIO 6 Level (when GP6_FN = 01h) 0 = Logic 0 1 = Logic 1 Write to this bit to set the GPIO6 output. Read from this bit to read GPIO input level. Note that, when GPIO6 is configured as an output (GP6_DIR=0), this is a Write-Only register; the Readback value is undefined.
	4:0	GP6_FN[4:0]	0_0000	GPIO6 Pin Function select  00h = CS input (SDI interface)  01h = Logic 0/1 (set by GP6_LVL)  03h = IRQ  04h = Temperature shutdown  09h = FLL Lock  0Ah = DRC Activity detect  0Bh = Write Sequencer done  0Ch = ALC Noise Gate active  0Dh = ALC Peak Limiter overload  0Eh = ALC Saturation  0Fh = ALC level threshold  10h = ALC Level lock  11h = FIFO error indicator  12h = OPCLK  13h = DMICCLK output  14h = DMICDAT input  15h = Mic Detect flag  16h = Mic Short Circuit flag  All other codes are Reserved

Table 110 GPIO Control



## **INTERRUPTS**

The Interrupt Controller has multiple inputs, including the GPIO input, ALC status, Microphone Detect status and FLL lock. Any combination of these inputs can be used to trigger an Interrupt (IRQ) event.

There is an Interrupt Status field associated with each of the IRQ inputs. These are contained in the Interrupt Status Register (R561), as described in Table 111. The status of the IRQ inputs can be read from this register at any time.

Each of the IRQ inputs can be individually masked or enabled as an input to the Interrupt function, using the bits contained in the Interrupt Status Mask register (R569). Note that the Interrupt Status fields remain valid, even when masked, but the masked bits will not cause the Interrupt Output to be asserted.

The Interrupt Output represents the logical 'OR' of all the unmasked IRQ inputs, as illustrated in Figure 62. The bits within the Interrupt Status register (R561) are latching fields and, once they are set, they are not reset until a '1' is written to the respective register bit in the Interrupt Status registers. The Interrupt (IRQ) output is not reset until each of the unmasked IRQ inputs has been reset. Note that, if the condition that caused the IRQ input to be asserted is still valid, then the Interrupt Output will remain set even after the Status register has been written to.

The FLL\_LOCK\_EINT and TEMP\_SHUT\_EINT inputs to the Interrupt Controller can be de-bounced to avoid false detections. The timeout clock (TOCLK) is required for this function. The de-bounce is enabled on these inputs using the bits in Register R584. The de-bounce clock is enabled automatically whenever interrupt de-bouncing is selected. The de-bounce clock frequency is controlled by DBCLK DIV as described in "Clocking and Sample Rates".

By default, the Interrupt Output is Active High. The polarity can be inverted using IRQ\_POL.

The WM8963 Interrupt Controller circuit is illustrated in Figure 54. The associated control fields are described in Table 111.

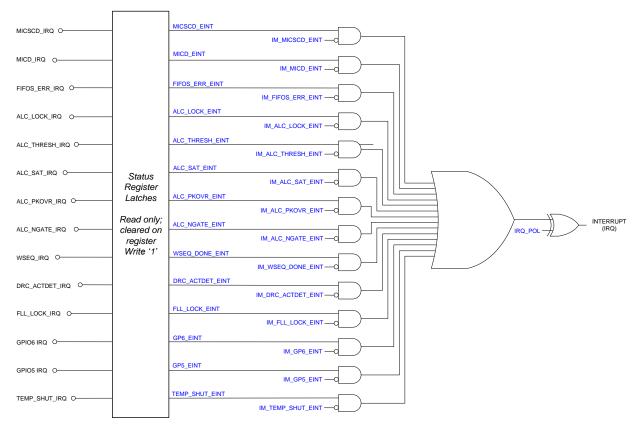


Figure 62 Interrupt Controller





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R560 (0230h) Interrupt Status 1	5	GP6_EINT	0	GPIO6 IRQ status  0 = GPIO6 IRQ not set  1 = GPIO6 IRQ set  Note: cleared when a '1' is written
	4	GP5_EINT	0	GPIO5 IRQ status 0 = GPIO5 IRQ not set 1 = GPIO5 IRQ set Note: cleared when a '1' is written
R561 (0231h) Interrupt Status 2	15	MICSCD_EINT	0	Mic Short Circuit Interrupt Status 0 = MICSCD IRQ not set 1 = MICSCD IRQ set Note: cleared when a '1' is written
	14	MICD_EINT	0	Mic Detect Interrupt Status  0 = MICD IRQ not set  1 = MICD IRQ set  Note: cleared when a '1' is written
	13	FIFOS_ERR_EI NT	0	FIFO error IRQ status 0 = FIFO error IRQ not set 1 = FIFO error IRQ set Note: cleared when a '1' is written
	12	ALC_LOCK_EIN T	0	ALC level lock IRQ status 0 = ALC level lock IRQ not set 1 = ALC level lock IRQ set Note: cleared when a '1' is written
	11	ALC_THRESH_ EINT	0	ALC level threshold IRQ status  0 = ALC level threshold IRQ not set  1 = ALC level threshold IRQ set  Note: cleared when a '1' is written
	10	ALC_SAT_EINT	0	ALC saturation IRQ status 0 = ALC saturation IRQ not set 1 = ALC saturation IRQ set Note: cleared when a '1' is written
	9	ALC_PKOVR_EI NT	0	ALC peak overload detector IRQ status 0 = ALC pk. overload det. IRQ not set 1 = ALC pk. Overload det. IRQ set Note: cleared when a '1' is written
	8	ALC_NGATE_EI NT	0	ALC Noise Gate active IRQ status 0 = ALC Noise Gate IRQ not set 1 = ALC Noise Gate IRQ set Note: cleared when a '1' is written
	7	WSEQ_DONE_ EINT	0	Write Sequencer done IRQ status 0 = Write Sequencer IRQ not set 1 = Write Sequencer IRQ set Note: cleared when a '1' is written
	6	DRC_ACTDET_ EINT	0	DRC Activity IRQ status  0 = DRC Activity IRQ not set  1 = DRC Activity IRQ set  Note: cleared when a '1' is written
	5	FLL_LOCK_EIN T	0	FLL Lock IRQ status  0 = FLL lock IRQ not set  1 = FLL lock IRQ set  Note: cleared when a '1' is written



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	0	TEMP_SHUT_EI NT	0	Temperature Shutdown IRQ status 0 = Temperature Shutdown IRQ not set 1 = Temperature Shutdown IRQ set Note: cleared when a '1' is written
R568 (0238h) Interrupt Status 1 Mask	5	IM_GP6_EINT	1	Interrupt mask for GPIO6 0 = Not masked 1 = Masked
	4	IM_GP5_EINT	1	Interrupt mask for GPIO5 0 = Not masked 1 = Masked
R569 (0239h) Interrupt Status 2 Mask	15	IM_MICSCD_EI NT	0	Interrupt mask for Mic Short Circuit 0 = Not masked 1 = Masked
	14	IM_MICD_EINT	0	Interrupt mask for Mic Detect 0 = Not masked 1 = Masked
	13	IM_FIFOS_ERR _EINT	1	Interrupt mask for FIFOS Error 0 = Not masked 1 = Masked
	12	IM_ALC_LOCK_ EINT	1	Interrupt mask for ALC Lock 0 = Not masked 1 = Masked
	11	IM_ALC_THRES H_EINT	1	Interrupt mask for ALC Threshold 0 = Not masked 1 = Masked
	10	IM_ALC_SAT_EI NT	1	Interrupt mask for ALC Saturation 0 = Not masked 1 = Masked
	9	IM_ALC_PKOV R_EINT	1	Interrupt mask for ALC Peak Detector overload 0 = Not masked 1 = Masked
	8	IM_ALC_NGATE _EINT	1	Interrupt mask for ALC Noise Gate active 0 = Not masked 1 = Masked
	7	IM_WSEQ_DON E_EINT	1	Interrupt mask for Write Sequencer done 0 = Not masked 1 = Masked
	6	IM_DRC_ACTD ET_EINT	1	Interrupt mask for DRC Activity detect 0 = Not masked 1 = Masked
	5	IM_FLL_LOCK_ EINT	1	Interrupt mask for FLL Lock 0 = Not masked 1 = Masked
	0	IM_TEMP_SHU T_EINT	1	Interrupt mask for Temperature Shutdown 0 = Not masked 1 = Masked
R576 (0240h) Interrupt Control	0	IRQ_POL	0	Interrupt Output polarity 0 = Active high 1 = Active low





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R584 (0248h) IRQ Debounce	5	FLL_LOCK_DB	1	Debounce Enable on FLL Lock 0 = Disabled 1 = Enabled
	0	TEMP_SHUT_D B	1	Debounce Enable on Temperature Shutdown 0 = Disabled 1 = Enabled
R586 (024Ah) MICINT Source Pol	15	MICSCD_IRQ_P OL	0	Mic Short Circuit Interrupt Polarity 0 = Active high (IRQ asserted when MICSHORT_THR is exceeded) 1 = Active low (IRQ asserted when MICSHORT_THR not exceeded)
	14	MICD_IRQ_POL	0	Mic Detect Interrupt Polarity  0 = Active high (IRQ asserted when MICDET_THR is exceeded)  1 = Active low (IRQ asserted when MICDET_THR not exceeded)

Table 111 Interrupt Control



## CONTROL INTERFACE

The WM8963 is controlled by writing to its control registers. Readback is available for all registers. The Control Interface can operate as either a 2-, 3- or 4-wire interface:

- 2-wire (I2C) mode uses pins SCLK and SDA
- 3-wire (SPI) mode uses pins CS/GPIO6, SCLK and SDA
- 4-wire (SPI) mode uses the CS/GPIO6, SCLK and SDA pins; the SDOUT function is provided on a GPIO pin

Readback is provided on the bi-directional pin SDA in 2-/3-wire modes. In 4-wire mode, the SDOUT readback function must be enabled on one of the GPIO pins - see "General Purpose Input/Output (GPIO)".

In 3-wire and 4-wire SPI modes, the CS function is provided using the CS/GPIO6 pin. In these control interface modes, GPIO6 must be configured as CS by setting GP6\_FN = 00h and GP6\_DIR = 1. Note that this is the default setting of GPIO6.

The WM8963 uses 16-bit register addresses and 16-bit data in 2-wire (I2C) mode; the WM8963 uses 15-bit register addresses in 3-wire and 4-wire (SPI) modes.

The configuration parameters in registers R16896 (4200h) to R19603 (4C93h) are 24-bit words, arranged within the 16-bit register address space. Each 24-bit word must be written to the register map in full, MSBs first, before attempting to read back the value. Failure to do this may give incorrect read/write behaviour.

When updating the configuration parameters for any DSP feature(s), it is recommended to write all of the associated registers, in incremental address order, before reading back any values.

Note that the Control Interface function can be supported with or without system clocking. Where possible, the register map access is synchronised with SYSCLK in order to ensure predictable operation of cross-domain functions. See "Clocking and Sample Rates" for further details of Control Interface clocking.

### **SELECTION OF CONTROL INTERFACE MODE**

The WM8963 Control Interface Mode is determined by the logic level on the CIFMODE pin, as shown in Table 112.

CIFMODE	INTERFACE FORMAT				
Low	2 wire (I2C) Mode				
High	3- or 4- wire (SPI) Modes				

**Table 112 Control Interface Mode Selection** 

In 2-wire (I2C) Control Interface mode, Auto-Increment mode may be selected. This enables multiple write and multiple read operations to be scheduled faster than is possible with single register operations, and is illustrated in Figure 67, Figure 68, and Figure 69. The auto-increment option is enabled when the AUTO\_INC register bit is set. This bit is defined in Table 113. Auto-increment is enabled by default.

In SPI modes, 3-wire or 4-wire operation may be selected using the SPI\_4WIRE register bit.

In SPI modes, the Continuous Read mode may be selected using the SPI\_CONTRD bit. This enables multiple register read operations to be scheduled faster than is possible with single register operations. When SPI\_CONTRD is set, the WM8963 will readback from incremental register addresses as long as CS is held low and SCLK is toggled.

In 3-wire (SPI) mode, register readback is provided using the bi-directional pin SDA. During data output, the SDA pin can be configured as CMOS or Open Drain, using the SPI\_CFG register bit.

In 4-wire (SPI) mode, register readback is provided using SDOUT, which must be configured on one of the GPIO pins.

When GPIO5 is configured as SDOUT, it may be configured as CMOS or as 'Wired OR' using the SPI\_CFG bit. In CMOS mode, SDOUT is driven low when not outputting register data. In 'Wired OR' mode, SDOUT is un-driven (high impedance) when not outputting register data bits. Note that the



SDOUT function on GPIO2 is not configurable using SPI\_CFG; on this pin, SDOUT is a CMOS output at all times.

The Control Interface configuration bits are described in Table 113.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R94 (005Eh) Control Interface	6	SPI_CONTRD	0	Enable continuous read mode in SPI (3-wire/4-wire) modes 0 = Disabled 1 = Enabled
	5	SPI_4WIRE	0	SPI control mode select 0 = 3-wire using bidirectional SDA 1 = 4-wire using SDOUT
	4	SPI_CFG	0	SDA/SDOUT pin configuration  In 3-wire mode (SPI_4WIRE=0): 0 = SDA output is CMOS 1 = SDA output is Open Drain  In 4-wire mode (SPI_4WIRE=1): 0 = SDOUT output is CMOS 1 = SDOUT output is Wired 'OR'. Note that only GPIO5 can be configured as Wired 'OR'. This bit has no effect on GPIO2.
R252 (00FCh)	0	AUTO_INC	1	Enables address auto-increment (applies to 2-wire I2C mode only) 0 = Disabled 1 = Enabled

Table 113 Control Interface Configuration

# 2-WIRE (I2C) CONTROL MODE

In 2-wire (I2C) mode, the WM8963 is a slave device on the control interface; SCLK is a clock input, while SDA is a bi-directional data pin. To allow arbitration of multiple slaves (and/or multiple masters) on the same interface, the WM8963 transmits logic 1 by tri-stating the SDA pin, rather than pulling it high. An external pull-up resistor is required to pull the SDA line high so that the logic 1 can be recognised by the master.

In order to allow many devices to share a single 2-wire control bus, every device on the bus has a unique 8-bit device ID (this is not the same as the address of each register in the WM8963). The WM8963 device ID is 0011\_0100 (34h). The LSB of the device ID is the Read/Write bit; this bit is set to logic 1 for "Read" and logic 0 for "Write".

The WM8963 operates as a slave device only. The controller indicates the start of data transfer with a high to low transition on SDA while SCLK remains high. This indicates that a device ID, register address and data will follow. The WM8963 responds to the start condition and shifts in the next eight bits on SDA (8-bit device ID including Read/Write bit, MSB first). If the device ID received matches the device ID of the WM8963, then the WM8963 responds by pulling SDA low on the next clock pulse (ACK). If the device ID is not recognised or the R/W bit is set incorrectly, the WM8963 returns to the idle condition and waits for a new start condition and valid address.

If the device ID matches the device ID of the WM8963, the data transfer continues as described below. The controller indicates the end of data transfer with a low to high transition on SDA while SCLK remains high. After receiving a complete address and data sequence the WM8963 returns to the idle state and waits for another start condition. If a start or stop condition is detected out of sequence at any point during data transfer (i.e. SDA changes while SCLK is high), the device returns to the idle condition.



The WM8963 supports the following read and write operations:

- Single write
- Single read
- Multiple write using auto-increment
- Multiple read using auto-increment

Note that the following protocol descriptions illustrate a 16-bit register address protocol. In the case of 8-bit register addresses, the Most Significant Word (MSW, containing A15 - A8), and the following ACK cycle is omitted.

The sequence of signals associated with a single register write operation is illustrated in Figure 63.

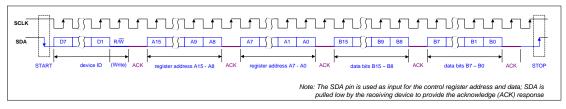


Figure 63 Control Interface Register Write

The sequence of signals associated with a single register read operation is illustrated in Figure 64.

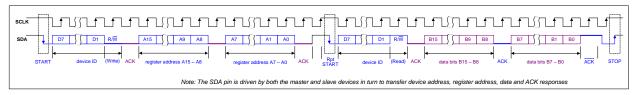


Figure 64 Control Interface Register Read

The Control Interface also supports other register operations, as listed above. The interface protocol for these operations is summarised below. The terminology used in the following figures is detailed in Table 114.

Note that, for multiple write and multiple read operations, the auto-increment option must be enabled. This feature is enabled by default, as noted in Table 113.

TERMINOLOGY	DESCR	IPTION			
S	Start Co	ndition			
Sr	Repeated start				
А	Acknowledge	e (SDA Low)			
Ā	Not Acknowled	ge (SDA High)			
Р	Stop Co	ondition			
R/W	ReadNotWrite	0 = Write 1 = Read			
[White field]	Data flow from bus master to WM8963				
[Grey field]	Data flow from WM8963 to bus master				

**Table 114 Control Interface Terminology** 





Figure 65 Single Register Write to Specified Address

S	Device ID RW A	MSByte Address	Α	LSByte Address	A Sr	Device ID	RW A	MSByte Data	Α	LSByte Data	Ā	Р
	(0)				(1)							

Figure 66 Single Register Read from Specified Address

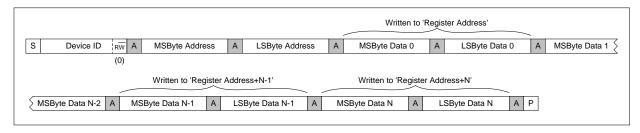


Figure 67 Multiple Register Write to Specified Address using Auto-increment

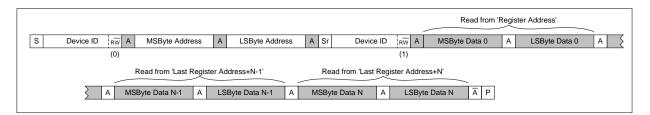


Figure 68 Multiple Register Read from Specified Address using Auto-increment

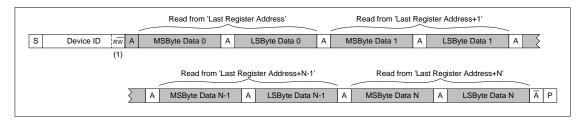


Figure 69 Multiple Register Read from Last Address using Auto-increment

Multiple Write and Multiple Read operations enable the host processor to access sequential blocks of the data in the WM8963 register map faster than is possible with single register operations. The auto-increment option is enabled when the AUTO\_INC register bit is set. This bit is defined in Table 113. Auto-increment is enabled by default.



## 3-WIRE (SPI) CONTROL MODE

The 3-wire control interface uses the CS, SCLK and SDA pins.

In 3-wire control mode, a control word consists of 32 bits. The first bit is the read/write bit (R/W), which is followed by 15 address bits (A14 to A0) that determine which control register is accessed. The remaining 16 bits (B15 to B0) are data bits, corresponding to the 16 bits in each control register.

In 3-wire mode, every rising edge of SCLK clocks in one data bit from the SDA pin. A rising edge on CS latches in a complete control word consisting of the last 32 bits.

In Write operations (R/W=0), all SDA bits are driven by the controlling device.

In Read operations (R/W=1), the SDA pin is driven by the controlling device to clock in the register address, after which the WM8963 drives the SDA pin to output the applicable data bits.

During data output, the SDA pin can be configured as CMOS or Open Drain, using the SPI\_CFG register bit, as described in Table 113. In Open Drain configuration, an external pull-up resistor is required to pull the SDA line high so that the logic 1 can be recognised by the master.

When SPI Continuous Read mode is enabled (SPI\_CONTRD = 1), the WM8963 will readback from incremental register addresses as long as CS is held low and SCLK is toggled. In this mode, the WM8963 will increment the readback address after the first 32 clock cycles, and will output data from the next register address, and successive register addresses, MSB first, for as long as CS is held low and SCLK is toggled.

The 3-wire control mode timing is illustrated in Figure 70.

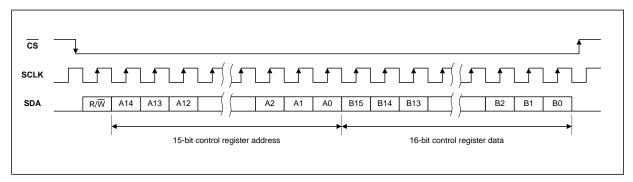


Figure 70 3-Wire Serial Control Interface



#### 4-WIRE (SPI) CONTROL MODE

The 4-wire control interface uses the CS, SCLK, SDA and SDOUT pins.

The SDOUT function must be enabled on one of the GPIO pins - see "General Purpose Input/Output (GPIO)".

When GPIO5 is configured as the Data Output pin, SDOUT, it can be configured as CMOS or 'Wired OR', as described in Table 113. In CMOS mode, SDOUT is driven low when not outputting register data bits. In 'Wired OR' mode, SDOUT is undriven (high impedance) when not outputting register data bits. Note that the SDOUT function on GPIO2 is not configurable using SPI\_CFG; on this pin, SDOUT is a CMOS output at all times

In Write operations (R/W=0), this mode is the same as 3-wire mode described above.

In Read operations (R/W=1), the SDA pin is ignored following receipt of the valid register address. SDOUT is driven by the WM8963.

When SPI Continuous Read mode is enabled (SPI\_CONTRD = 1), the WM8963 will readback from incremental register addresses as long as CS is held low and SCLK is toggled. In this mode, the WM8963 will increment the readback address after the first 32 clock cycles, and will output data from the next register address, and successive register addresses, MSB first, for as long as CS is held low and SCLK is toggled.

The 4-wire control mode timing is illustrated in Figure 71 and Figure 72.

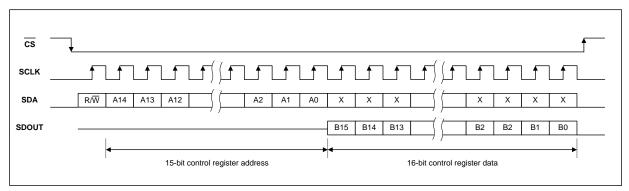


Figure 71 4-Wire Readback (CMOS)

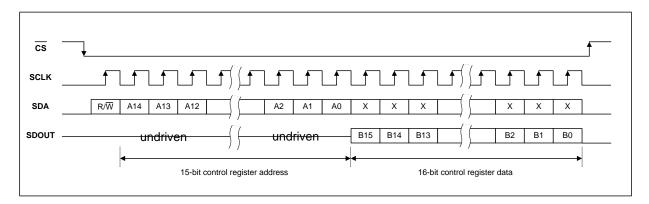


Figure 72 4-Wire Readback (Wired-'OR')



#### CONTROL WRITE SEQUENCER

The Control Write Sequencer is a programmable unit that forms part of the WM8963 control interface logic. It provides the ability to perform a sequence of register write operations with the minimum of demands on the host processor - the sequence may be initiated by a single operation from the host processor and then left to execute independently.

Default sequences for Start-Up of each output driver and Shut-Down are provided (see "Default Sequences" section). It is recommended that these default sequences are used unless changes become necessary.

When a sequence is initiated, the sequencer performs a series of pre-defined register writes. The host processor informs the sequencer of the start index of the required sequence within the sequencer's memory. At each step of the sequence, the contents of the selected register fields are read from the sequencer's memory and copied into the WM8963 control registers. This continues sequentially through the sequencer's memory until an "End of Sequence" bit is encountered; at this point, the sequencer stops and an Interrupt status flag is asserted. For cases where the timing of the write sequence is important, a programmable delay can be set for specific steps within the sequence.

Note that the Control Write Sequencer's internal clock is derived from the internal clock SYSCLK which must be enabled as described in "Clocking and Sample Rates". The clock division from SYSCLK is handled transparently by the WM8963 without user intervention, provided that SYSCLK is configured as specified in "Clocking and Sample Rates".

#### **INITIATING A SEQUENCE**

The Register fields associated with running the Control Write Sequencer are described in Table 115. Note that the operation of the Control Write Sequencer also requires the internal clock SYSCLK to be configured as described in "Clocking and Sample Rates".

The Write Sequencer is enabled by setting the WSEQ\_ENA bit. The start index of the required sequence must be written to the WSEQ\_START\_INDEX field.

The Write Sequencer stores up to 128 register write commands. These are defined in Registers R4096 to R4607. There are 4 registers used to define each of the 128 possible commands. The value of WSEQ\_START\_INDEX selects the registers applicable to the first write command in the selected sequence.

Setting the WSEQ\_START bit initiates the sequencer at the given start index. The Write Sequencer can be interrupted by writing a logic 1 to the WSEQ\_ABORT bit.

The current status of the Write Sequencer can be read using two further register fields - when the WSEQ\_BUSY bit is asserted, this indicates that the Write Sequencer is busy. Note that, whilst the Control Write Sequencer is running a sequence (indicated by the WSEQ\_BUSY bit), full read/write operations to the Control Registers cannot be supported. (Register access to the Control Write Sequencer registers and Software Reset registers is still supported while the Control Write Sequencer is running. Unsuccessful I2C interface commands will be indicated to the host processor by the WM8963 failing to provide the acknowledge, 'ACK', indication.)

The index of the current step in the Write Sequencer can be read from the WSEQ\_CURRENT\_INDEX field; this is an indicator of the sequencer's progress. On completion of a sequence, this field holds the index of the last step within the last commanded sequence.

When the Write Sequencer reaches the end of a sequence, it asserts the WSEQ\_DONE\_EINT flag in Register R561 (see "Interrupts"). This flag can be used to generate an Interrupt Event on completion of the sequence. Note that the WSEQ\_DONE\_EINT flag is asserted to indicate that the WSEQ is NOT Busy.

The WM8963 supports the option to automatically power-down the Class D speaker drivers when the DAC Auto-Mute is triggered, and to re-enable the speaker drivers when audio data is detected. This is implemented using the Control Write Sequencer, and enabled by setting the WSEQ\_AUTOSEQ\_ENA bit. When this bit is set, and the conditions for DAC Auto-Mute are satisfied, the default "Speaker Sleep" sequence is triggered. When the DAC is un-muted following an Auto-Mute event, the "Speaker Wake" sequence is triggered. See "Default Sequences" for details of these sequences.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R87 (57h) Write Sequencer Control 1	7	WSEQ_AUTOS EQ_ENA	0	Write Sequencer Auto-Sequence Enable (controls the Class D driver via DAC Auto-Mute function) 0 = Disabled 1 = Enabled
	5	WSEQ_ENA	0	Write Sequencer Enable.  0 = Disabled  1 = Enabled
R90 (5Ah) Write Sequencer Control 2	8	WSEQ_ABORT	0	Writing a 1 to this bit aborts the current sequence and returns control of the device back to the serial control interface.
	7	WSEQ_START	0	Writing a 1 to this bit starts the write sequencer at the index location selected by WSEQ_START_INDEX. The sequence continues until it reaches an "End of sequence" flag. At the end of the sequence, this bit will be reset by the Write Sequencer.
	6:0	WSEQ_START_ INDEX [6:0]	000_0000	Sequence Start Index. This field determines the memory location of the first command in the selected sequence. There are 127 Write Sequencer RAM addresses:  00h = WSEQ_ADDR0 (R4096)  01h = WSEQ_ADDR1 (R4100)  02h = WSEQ_ADDR2 (R4104)   7Fh = WSEQ_ADDR127 (R4604)
R93 (5Dh) Write Sequencer Control 3	9:3	WSEQ_CURRE NT_INDEX [6:0] (read only)	000_0000	Sequence Current Index. This indicates the memory location of the most recently accessed command in the write sequencer memory.  Coding is the same as WSEQ_START_INDEX.
	0	WSEQ_BUSY (read only)	0	Sequencer Busy flag (Read Only).  0 = Sequencer idle  1 = Sequencer busy  Note: it is not possible to write to control registers via the control interface while the Sequencer is Busy.

Table 115 Write Sequencer Control - Initiating a Sequence

## **PROGRAMMING A SEQUENCE**

A sequence consists of write operations to data bits (or groups of bits) within the control registers. Each write operation is defined by a block of 4 registers, which contain 6 fields as described in this section.

The block of 4 registers is the same for up to 128 steps held in the sequencer memory. Multiple sequences can be held in the memory at the same time; each sequence occupies its own range within the 128 available register blocks.

The following 6 fields are replicated 128 times - one for each of the sequencer's 128 steps. In the following descriptions, the term 'n' is used to denote the step number, from 0 to 127.

 $WSEQ\_ADDRn$  is a 14-bit field containing the Control Register Address in which the data should be written. Note that the Control Write Sequencer cannot be used to access the Write Sequencer registers R87, R90 and R93.



WSEQ\_DATA*n* is an 8-bit field which contains the data to be written to the selected Control Register. The WSEQ\_DATA\_WIDTH*n* field determines how many of these bits are written to the selected register; the most significant bits (above the number indicated by WSEQ\_DATA\_WIDTH*n*) are ignored.

WSEQ\_DATA\_STARTn is a 4-bit field which identifies the LSB position within the selected Control Register to which the data should be written. For example, setting WSEQ\_DATA\_STARTn = 0100 will select bit 4 as the LSB position; in this case, 4-bit data would be written to bits 7:4.

WSEQ\_DATA\_WIDTH*n* is a 3-bit field which identifies the width of the data block to be written. This enables selected portions of a Control Register to be updated without any concern for other bits within the same register, eliminating the need for read-modify-write procedures. Values of 0 to 7 correspond to data widths of 1 to 8 respectively. For example, setting WSEQ\_DATA\_WIDTH*n* = 010 will cause a 3-bit data block to be written. Note that the maximum value of this field corresponds to an 8-bit data block; writing to register fields greater than 8 bits wide must be performed using two separate operations of the Control Write Sequencer.

WSEQ\_DELAYn is a 4-bit field which controls the waiting time between the current step and the next step in the sequence i.e. the delay occurs after the write in which it was called. The total delay time per step (including execution) is defined below, giving a useful range of execution/delay times from  $562\mu s$  up to 2.048s per step:

```
T = k \times (2 \text{ WSEQ\_DELAY} + 8) where k = 62.5 \( \mu \) s (if SAMPLE_RATE_INT_MODE = 1) and k = 68.1 \( \mu \) s (if SAMPLE_RATE_INT_MODE = 0)
```

Note that the sequencer execution/delay time varies between integer and fractional values of the SAMPLE\_RATE register; see "Clocking and Sample Rates" for details of the associated registers.

WSEQ\_EOSn is a 1-bit field which indicates the End of Sequence. If this bit is set, then the Control Write Sequencer will automatically stop after this step has been executed.

The register definitions for Step 0 are described in Table 116. The equivalent definitions also apply to Step 1 through to Step 127, in the subsequent register address locations.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4096 (1000h) Write Sequencer 0	13:0	WSEQ_ADDR 0 [13:0]	001Ch	Control Register Address to be written to in this sequence step.
R4097 (1001h) Write Sequencer 1	7:0	WSEQ_DATA 0 [7:0]	03h	Data to be written in this sequence step. When the data width is less than 8 bits, then one or more of the MSBs of WSEQ_DATAn are ignored. It is recommended that unused bits be set to 0.
R4098 (1002h) Write Sequencer 2	10:8	WSEQ_DATA _WIDTH0 [2:0]	001	Width of the data block written in this sequence step.  000 = 1 bit  001 = 2 bits  010 = 3 bits  011 = 4 bits  100 = 5 bits  101 = 6 bits  110 = 7 bits  111 = 8 bits
	3:0	WSEQ_DATA _START0 [3:0]	0011	Bit position of the LSB of the data block written in this sequence step.  0000 = Bit 0  1111 = Bit 15



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4099 (1003h) Write Sequencer 3	8	WSEQ_EOS0	0	End of Sequence flag. This bit indicates whether the Control Write Sequencer should stop after executing this step.  0 = Not end of sequence  1 = End of sequence (Stop the sequencer after this step).
	3:0	WSEQ_DELA Y0 [3:0]	0000	Time delay after executing this step.  Total time per step (including execution) $= k \times (2^{\text{WSEQ\_DELAY}} + 8)$ $k = 62.5 \mu s$ (SAMPLE_RATE_INT_MODE = 1), $k = 68.1 \mu s$ (SAMPLE_RATE_INT_MODE = 0),

Table 116 Write Sequencer Control - Programming a Sequence

Note that a 'Dummy' write can be inserted into a control sequence by commanding the sequencer to write a value of 0 to bit 0 of Register R254 (00FEh). This is effectively a write to a non-existent register location. This can be used in order to create placeholders ready for easy adaptation of a control sequence. For example, a sequence could be defined to power-up a mono signal path from DACL to headphone, with a 'dummy' write included to leave space for easy modification to a stereo signal path configuration. Dummy writes can also be used in order to implement additional time delays between register writes.

In summary, the Control Register to be written is set by the WSEQ\_ADDR*n* field. The data bits that are written are determined by a combination of WSEQ\_DATA\_START*n*, WSEQ\_DATA\_WIDTH*n* and WSEQ\_DATA*n*. This is illustrated below for an example case of writing to the DAC\_DEEMP field within Register R5 (0005h).

In this example, the Start Position is bit 01 (WSEQ\_DATA\_STARTn = 0001b) and the Data width is 2 bits (WSEQ\_DATA\_WIDTHn = 0001b). With these settings, the Control Write Sequencer would update the Control Register R5 [2:1] with the contents of WSEQ\_DATAn [1:0].

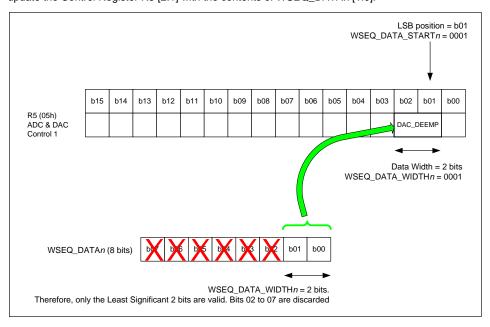


Figure 73 Control Write Sequencer Example



#### **DEFAULT SEQUENCES**

When the WM8963 is powered up, a number of Control Write Sequences are available through default settings in the sequencer memory locations. The pre-programmed default settings include Start-Up and Shut-Down sequences for each of the output drivers. Note that the default sequences do not include audio signal path or gain setting configuration; this must be implemented prior to scheduling any of the default Start-Up sequences.

The entire sequencer memory may be programmed to users' own settings at any time, as described in "Programming a Sequence". Users' own settings remain in memory regardless of WSEQ\_ENA, and are not affected by software resets (i.e. writing to Register R15). However, any non-default sequences are lost when the device is powered down.

The following default control sequences are provided:

- DAC to Headphone 1 Power Up This sequence powers up the HPOUT1 headphone driver and charge pump. It commands the DC Servo to perform offset correction. It enables the master bias required for analogue functions. This sequence is intended for enabling the headphone output after initial power-on.
- 2. Analogue Input Power Up This sequence powers up the analogue input (IN1L and IN1R) signal paths to the ADC output. The MICBIAS is enabled for powering electret condenser microphones connected to IN1L and IN1R. The DC Servo performs offset correction on the input signal paths. The intended usage of this sequence assumes that the "DAC to Headphone 1 Power Up" sequence has been run previously. LDO is not enabled in this sequence.
- 3. Chip Power Down This sequence shuts down all of the WM8963 input paths, output drivers, DC Servo, charge pump and analogue bias circuits.
- 4. DAC to Headphone 1 and 2 Power Up This sequence powers up the HPOUT1 and HPOUT2 headphone drivers and charge pump. It commands the DC Servo to perform offset correction on all outputs. It enables the master bias required for analogue functions. This sequence is similar to the DAC to Headphone 1 power up sequence, except that Headphone 2 is enabled also.
- 5. Headphone 1 to Headphone 2 Switchover This sequence disables the HPOUT1 headphone output and enables the HPOUT2 output. This sequence is intended for implementing a switchover from HPOUT1 to HPOUT2, assuming that DC offset correction has already been performed and is enabled on both headphone outputs. It is recommended to command a DAC mute (DAC\_MUTE = 1) before scheduling this sequence. (Note that he DAC will be automatically un-muted in the final step of this sequence.)
- 6. Headphone 2 to Headphone 1 Switchover This sequence disables the HPOUT2 headphone output and enables the HPOUT1 output. It is the reverse of the Headphone 1 to Headphone 2 switchover sequence described above.
- 7. Speaker Sleep This sequence mutes the DAC output and Class D speaker output, and disabled the Class D output driver. This is intended for use as a power saving feature during quiescent DAC conditions. When the WSEQ\_AUTOSEQ\_ENA register bit is set, this sequence is automatically triggered whenever quiescent DAC playback conditions are detected.
- Speaker Wake This sequence enables the Class D speaker driver output and un-mutes
  the DAC output and Class D speaker path. When the WSEQ\_AUTOSEQ\_ENA register bit
  is set, this sequence is automatically triggered whenever a non-zero DAC sample is
  detected following an AUTOMUTE event.

Specific details of each of these sequences are provided below.



## DAC to Headphone 1 Power Up

The DAC to Headphone 1 Power Up sequence is initiated by writing 0080h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 0 (00h).

This sequence takes up to 93ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
0 (00h)	R28 (1Ch)	2 bits	Bit 3	03h	0h	0b	STARTUP_BIAS_ENA = 1b
							VMID_BUF_ENA = 1b
1 (01h)	R25 (19h)	3 bits	Bit 6	07h	0h	0b	VMID_SEL [1:0] = 11b
							BIAS_ENA = 1b
2 (02h)	R72 (48h)	1 bit	Bit 0	01b	6h	0b	CP_ENA = 1b
							(time delay inserted)
3 (03h)	R26 (1Ah)	4 bits	Bit 5	0Fh	0h	0b	DACL_ENA = 1b
							DACR_ENA = 1b
							HPOUTL_PGA_ENA = 1b
							HPOUTR_PGA_ENA = 1b
4 (04h)	R69 (45h)	5 bits	Bit 0	11h	0h	0b	HP1L_ENA = 1b
							HP1R_ENA = 1b
5 (05h)	R69 (45h)	5 bits	Bit 1	19h	0h	0b	HP1L_ENA_DLY = 1b
							HP1R_ENA_DLY = 1b
6 (06h)	R2 (2h)	7 bits	Bit 0	30h	0h	0b	HPOUTL_VOL [6:0] = 30h
7 (07h)	R3 (3h)	7 bits	Bit 0	30h	0h	0b	HPOUTR_VOL [6:0] = 30h
8 (08h)	R3 (3h)	1 bit	Bit 8	01h	0h	0b	HPOUT_VU = 1b
9 (09h)	R61 (3Dh)	6 bits	Bit 2	33h	Ah	0b	HP1L_DCS_ENA = 1b
							HP1L_DCS_STARTUP = 1b
							HP1R_DCS_ENA = 1b
							HP1R_DCS_STARTUP = 1b
							(time delay inserted)
10 (0Ah)	R254 (FEh)	1 bit	Bit 0	00h	0h	0b	Dummy Write for expansion
11 (0Bh)	R7 (7h)	2 bits	Bit 2	00h	0h	0b	WL [1:0] = 00
12 (0Ch)	R69 (45h)	5 bits	Bit 2	1Dh	0h	0b	HP1L_ENA_OUTP = 1
							HP1R_ENA_OUTP = 1
13 (0Dh)	R69 (45h)	5 bits	Bit 3	1Fh	0h	0b	HP1L_RMV_SHORT = 1
							HP1R_RMV_SHORT = 1
14 (0Eh)	R254 (FEh)	1 bit	Bit 0	00h	0h	0b	Dummy Write for expansion
15 (0Fh)	R5 (5h)	1 bit	Bit 3	00h	7h	1b	DAC_MUTE = 0
							(time delay inserted)

Table 117 DAC to Headphone 1 Power Up Sequence



## **Analogue Input Power Up**

The Analogue Input Power Up sequence is initiated by writing 0092h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 18 (12h).

This sequence takes up to 75ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
18 (12h)	R32 (20h)	3 bits	Bit 3	07h	0h	0b	INPGAL_MIXINL_VOL [2:0] = 111b
19 (13h)	R33 (21h)	3 bits	Bit 3	07h	0h	0b	INPGAR_MIXINR_VOL [2:0] = 111b
20 (14h)	R25 (19h)	5 bits	Bit 1	19h	0h	0b	INL_ENA = 1 INR_ENA = 1 MICBIAS_ENA = 1
21 (15h)	R60 (3Ch)	6 bits	Bit 2	33h	Ah	0b	INL_DCS_ENA = 1 INL_DCS_STARTUP = 1 INR_DCS_ENA = 1 INR_DCS_STARTUP = 1 (time delay inserted)
22 (16h)	R254 (FEh)	1 bit	Bit 0	00h	0h	0b	Dummy Write for expansion
23 (17h)	R25 (19h)	2 bits	Bit 2	03h	0h	0b	ADCL_ENA = 1 ADCR_ENA = 1
24 (18h)	R32 (20h)	3 bits	Bit 3	00h	0h	0b	INPGAL_MIXINL_VOL [2:0] = 000
25 (19h)	R33 (21h)	3 bits	Bit 3	00h	0h	1b	INPGAR_MIXINR_VOL [2:0] = 000

Table 118 Analogue Input Power Up Sequence

#### **Chip Power Down**

The Chip Power Down sequence is initiated by writing 009Bh to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 27 (1Bh).

This sequence takes up to 32ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
27 (1Bh)	R5 (5h)	1 bit	Bit 3	01h	8h	0b	DAC_MUTE = 1b
							(time delay inserted)
28 (1Ch)	R0 (0h)	1 bit	Bit 7	01h	0h	0b	INPGAL_MUTE = 1b
29 (1Dh)	R1 (1h)	2 bits	Bit 7	03h	0h	0b	INVU = 1b
							INPGAR_MUTE = 1b
30 (1Eh)	R69 (45h)	5 bits	Bit 3	0Eh	0h	0b	HP1L_RMV_SHORT = 0b
							HP1R_RMV_SHORT = 0b
31 (1Fh)	R96 (60h)	5 bits	Bit 3	0Eh	0h	0b	HP2L_RMV_SHORT = 0b
							HP2R_RMV_SHORT = 0b
32 (20h)	R2 (2h)	7 bits	Bit 0	00h	0h	0b	HPOUTL_VOL [6:0] = 00h
33 (21h)	R3 (3h)	7 bits	Bit 0	00h	0h	0b	HPOUTR_VOL [6:0] = 00h
34 (22h)	R3 (3h)	1 bit	Bit 8	01h	0h	0b	HPOUTVU = 1b
35 (23h)	R40 (28h)	7 bits	Bit 0	00h	0h	0b	SPKOUTL_VOL [6:0] = 00h
36 (24h)	R41 (29h)	7 bits	Bit 0	00h	0h	0b	SPKOUTR_VOL [6:0] = 00h
37 (25h)	R41 (29)	1 bit	Bit 8	01h	0h	0b	SPKOUT_VU = 1b
38 (26h)	R60 (3Ch)	5 bits	Bit 3	00h	0h	0b	INL_DCS_ENA = 0b
							INR_DCS_ENA = 0b
39 (27h)	R61 (3Dh)	5 bits	Bit 3	00h	0h	0b	HP1L_DCS_ENA = 0b
							HP1R_DCS_ENA = 0b
40 (28h)	R62 (3Eh)	5 bits	Bit 3	00h	0h	0b	HP2L_DCS_ENA = 0b
							HP2R_DCS_ENA = 0b



WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
41 (29h)	R69 (45h)	8 bits	Bit 0	00h	0h	0b	HP1L_ENA_OUTP = 0b
							HP1L_ENA_DLY = 0b
							HP1L_ENA = 0b
							HP1R_ENA_OUTP = 0b
							HP1R_ENA_DLY = 0b
							HP1R_ENA = 0b
42 (2Ah)	R96 (60h)	8 bits	Bit 0	00h	0h	0b	HP2L_ENA_OUTP = 0b
							HP2L_ENA_DLY = 0b
							HP2L_ENA = 0b
							HP2R_ENA_OUTP = 0b
							HP2R_ENA_DLY = 0b
							HP2R_ENA = 0b
43 (2Bh)	R49 (31h)	2 bits	Bit 6	00h	0h	0b	SPKOUTR_ENA = 0b
							SPKOUTL_ENA = 0b
44 (2Ch)	R99 (63h)	4 bits	Bit 0	00h	0h	0b	
45 (2Dh)	R26 (1Ah)	6 bits	Bit 3	00h	0h	0b	DACL_ENA = 0b
							DACR_ENA = 0b
							HPOUTL_PGA_ENA = 0b
							HPOUTR_PGA_ENA = 0b
							SPKOUTL_PGA_ENA = 0b
							SPKOUTR_PGA_ENA = 0b
46 (2Eh)	R72 (48h)	1 bit	Bit 0	00h	0h	0b	CP_ENA = 0b
47 (2Fh)	R25 (19h)	6 bits	Bit 1	00h	0h	0b	BIAS_ENA = 0b
							INL_ENA = 0b
							INR_ENA = 0b
							ADCL_ENA = 0b
							ADCR_ENA = 0b
							MICBIAS_ENA = 0b
48 (30h)	R28 (1Ch)	2 bits	Bit 3	00h	0h	0b	STARTUP_BIAS_ENA = 0b
							VMID_BUF_ENA = 0b
49 (31h	R25 (19h)	2 bits	Bit 7	00h	0h	1b	VMID_SEL [1:0] = 00b

Table 119 Chip Power Down Sequence

## DAC to Headphone 1 and 2 Power Up

The DAC to Headphone 1 and 2 Power Up sequence is initiated by writing 00B4h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 52 (34h).

This sequence takes up to 174ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
52 (34h)	R28 (1Ch)	2 bits	Bit 3	11	0h	0b	STARTUP_BIAS_ENA = 1b VMID_BUF_ENA = 1b
53 (35h)	R25 (19h)	3 bits	Bit 6	111	0h	0b	VMID_SEL [1:0] = 11b BIAS_ENA = 1b
54 (36h)	R72 (48h)	1 bit	Bit 0	1	6h	0b	CP_ENA = 1b (time delay inserted)
55 (37h)	R26 (1Ah)	4 bits	Bit 5	1111	0h	0b	DACL_ENA = 1b DACR_ENA = 1b HPOUTL_PGA_ENA = 1b HPOUTR_PGA_ENA = 1b
56 (38h)	R69 (45h)	5 bits	Bit 0	10001	0h	0b	HP1L_ENA = 1b HP1R_ENA = 1b
57 (39h)	R69 (45h)	5 bits	Bit 1	11001	0h	0b	HP1L_ENA_DLY = 1b HP1R_ENA_DLY = 1b



WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
58 (3Ah)	R96 (60h)	5 bits	Bit 0	10001	0h	0b	HP2L_ENA = 1b
							HP2R_ENA = 1b
59 (3Bh)	R96 (60h)	5 bits	Bit 1	11001	0h	0b	HP2L_ENA_DLY = 1b
							HP2R_ENA_DLY = 1b
60 (3Ch)	R2 (2h)	7 bits	Bit 0	0110000	0h	0b	HPOUTL_VOL = 30h
61 (3Dh)	R3 (3h)	7 bits	Bit 0	0110000	0h	0b	HPOUTR_VOL = 30h
62 (3Eh)	R3 (3h)	1 bit	Bit 8	1	0h	0b	HPOUTR_ZC = 1b
63 (3Fh)	R61 (3Dh)	6 bits	Bit 2	110011	Ah	0b	HP1L_DCS_ENA = 1b
							HP1L_DCS_STARTUP = 1b
							HP1R_DCS_ENA = 1b
							HP1R_DCS_STARTUP = 1b
							(time delay inserted)
64 (40h)	R62 (3Eh)	6 bits	Bit 2	110011	Ah	0b	HP2L_DCS_ENA = 1b
							HP2L_DCS_STARTUP = 1b
							HP2R_DCS_ENA = 1b
							HP2R_DCS_STARTUP = 1b
							(time delay inserted)
65 (41h)	R7 (7h)	2 bits	Bit 2	00	0h	0b	WL [1:0] = 00
66 (42h)	R69 (45h)	5 bits	Bit 2	11101	0h	0b	HP1L_ENA_OUTP = 1b
							HP1R_ENA_OUTP = 1b
67 (43h)	R69 (45h)	5 bits	Bit 3	11111	0h	0b	HP1L_RMV_SHORT = 1b
							HP1R_RMV_SHORT = 1b
68 (44h)	R96 (60h)	5 bits	Bit 2	11101	0h	0b	HP2L_ENA_OUTP = 1b
							HP2R_ENA_OUTP = 1b
69 (45h)	R96 (60h)	5 bits	Bit 3	11111	0h	0b	HP2L_RMV_SHORT = 1b
				<u> </u>			HP2R_RMV_SHORT = 1b
70 (46h)	R5 (5h)	1 bit	Bit 3	0	8h	1b	DAC_MUTE = 0b
							(time delay inserted)

Table 120 DAC to Headphone 1 and 2 Power Up Sequence

#### Headphone 1 to Headphone 2 Switchover

The Headphone 1 to Headphone 2 Switchover sequence is initiated by writing 00C8h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 72 (48h).

This sequence takes up to 7ms to run. Note that, if the DAC soft un-mute mode is selected (DAC\_UNMUTE\_RAMP = 1), then the DAC playback volume will be ramped up over a period of up to 10ms after completion of this sequence.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
72 (48h)	R69 (45h)	5 bits	Bit 3	01110	0h	0b	HP1L_RMV_SHORT = 0 HP1R_RMV_SHORT = 0
73 (49h)	R26 (1Ah)	2 bits	Bit 0	11	0h	0b	HPOUTL_PGA_MUTE = 1 HPOUTR_PGA_MUTE = 1
74 (4Ah)	R2 (2h)	1 bit	Bit 8	1	0h	0b	HPOUT_VU = 1
75 (4Bh)	R69 (45h)	8 bits	Bit 0	0000000	0h	0b	HP1L_ENA_OUTP = 0b HP1L_ENA_DLY = 0b HP1L_ENA = 0b HP1R_ENA_OUTP = 0b HP1R_ENA_DLY = 0b HP1R_ENA_DLY = 0b
76 (4Ch)	R96 (60h)	5 bits	Bit 0	10001	0h	0b	HP2L_ENA = 1b HP2R_ENA = 1b
77 (4Dh)	R96 (60h)	5 bits	Bit 1	11001	0h	0b	HP2L_ENA_DLY = 1b HP2R_ENA_DLY = 1b



WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
78 (4Eh)	R26 (1Ah)	2 bits	Bit 0	00	0h	0b	HPOUTL_PGA_MUTE = 0b HPOUTR_PGA_MUTE = 0b
79 (4Fh)	R2 (2h)	1 bit	Bit 8	1	0h	0b	HPOUT_VU = 1b
80 (50h)	R96 (60h)	5 bits	Bit 2	11101	0h	0b	HP2L_ENA_OUTP = 1b HP2R_ENA_OUTP = 1b
81 (51h)	R96 (60h)	5 bits	Bit 3	11111	0h	0b	HP2L_RMV_SHORT = 1b HP2R_RMV_SHORT = 1b
82 (52h)	R5 (5h)	1 bit	Bit 3	0	0h	1b	DAC_MUTE = 0b

Table 121 Headphone 1 to Headphone 2 Switchover Sequence

#### Headphone 2 to Headphone 1 Switchover

The Headphone 2 to Headphone 1 Switchover sequence is initiated by writing 00D4h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 84 (54h).

This sequence takes up to 7ms to run. Note that, if the DAC soft un-mute mode is selected (DAC\_UNMUTE\_RAMP = 1), then the DAC playback volume will be ramped up over a period of up to 10ms after completion of this sequence.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
84 (54h)	R96 (60h)	5 bits	Bit 3	01110	0h	0b	HP2L_RMV_SHORT = 0b HP2R_RMV_SHORT = 0b
85 (55h)	R26 (1Ah)	2 bits	Bit 0	11	0h	0b	HPOUTL_PGA_MUTE = 1b HPOUTR_PGA_MUTE = 1b
86 (56h)	R2 (2h)	1 bit	Bit 8	1	0h	0b	HPOUT_VU = 1b
87 (57h)	R96 (60h)	8 bits	Bit 0	00000000	0h	0b	HP2L_ENA_OUTP = 0b HP2L_ENA_DLY = 0b HP2L_ENA = 0b HP2R_ENA_OUTP = 0b HP2R_ENA_DLY = 0b HP2R_ENA_DLY = 0b
88 (58h)	R69 (45h)	5 bits	Bit 0	10001	0h	0b	HP1L_ENA = 1b HP1R_ENA = 1b
89 (59h)	R69 (45h)	5 bits	Bit 1	11001	0h	0b	HP1L_ENA_DLY = 1b HP1R_ENA_DLY = 1b
90 (5Ah)	R26 (1Ah)	2 bits	Bit 0	00	0h	0b	HPOUTL_PGA_MUTE = 0b HPOUTR_PGA_MUTE = 0b
91 (5Bh)	R2 (2h)	1 bit	Bit 8	1	0h	0b	HPOUT_VU = 1b
92 (5Ch)	R69 (45h)	5 bits	Bit 2	11101	0h	0b	HP1L_ENA_OUTP = 1b HP1R_ENA_OUTP = 1b
93 (5Dh)	R69 (45h)	5 bits	Bit 3	11111	0h	0b	HP1L_RMV_SHORT = 1b HP1R_RMV_SHORT = 1b
94 (5Eh)	R5 (5h)	1 bit	Bit 3	0	0h	1b	DAC_MUTE = 0b

Table 122 Headphone 2 to Headphone 1 Switchover Sequence



#### Speaker Sleep

The Speaker Sleep sequence is initiated by writing 00E4h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 100 (64h).

This sequence takes up to 2ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
100 (64h)	R49 (31h)	1 bit	Bit 4	01h	0h	0b	DAC_MUTE = 1
101 (65h)	R49 (31h)	3 bits	Bit 0	07h	0h	0b	SPKOUT_VU = 1 SPKOUTL_PGA_MUTE = 1 SPKOUTR_PGA_MUTE = 1
102 (66h)	R49 (31h)	2 bits	Bit 6	00h	0h	1b	SPKOUTR_ENA = 0 SPKOUTL_ENA = 0

Table 123 Speaker Sleep Sequence

## Speaker Wake

The Speaker Wake sequence is initiated by writing 00E8h to Register 90 (5Ah). This single operation starts the Control Write Sequencer at Index Address 104 (68h).

This sequence takes up to 2ms to run.

WSEQ INDEX	REGISTER ADDRESS	WIDTH	START	DATA	DELAY	EOS	DESCRIPTION
104 (68h)	R49 (31h)	2 bits	Bit 6	03h	0h	0b	SPKOUTR_ENA = 1 SPKOUTL_ENA = 1
105 (69h)	R49 (31h)	3 bits	Bit 0	04h	0h	0b	SPKOUT_VU = 1 SPKOUTL_PGA_MUTE = 0 SPKOUTR_PGA_MUTE = 0
106 (6Ah)	R49 (31h)	1 bit	Bit 4	00h	0h	1b	DAC_MUTE = 0

Table 124 Speaker Wake Sequence



#### THERMAL SHUTDOWN

The WM8963 incorporates a temperature sensor on each of the headphone circuit and the speaker circuit. These detect when the device temperature is within normal limits, or the device is approaching a hazardous temperature condition (above 125°C and below 145°C), or if the device has exceeded a hazardous temperature condition (>145°C). The temperature sensors can be configured to automatically disable the audio outputs of the WM8963 in response to an over-temperature condition (approximately 145°C) on either the headphone or the speaker circuits.

The temperature sensor can be used to generate Interrupt events, as described in the "Interrupts" section.

The temperature sensors are enabled on the headphone and the speaker circuits by setting the TEMP\_ENA\_HP and the TEMP\_ENA\_SPK register bits respectively.

Temperature warnings are flagged at 125°C by asserting the TEMP\_WARN\_HP (headphones) and TEMP\_WARN\_SPK (speakers) register bits. Potentially hazardous over-temperature conditions are flagged by the setting of the TEMP\_ERR\_HP (headphones) and TEMP\_ERR\_SPK (speakers) registers.

When the THERR\_ACT register is also set, then a device over-temperature condition in either sensor (TEMP\_ERR\_HP or TEMP\_ERR\_SPK asserted) will cause the speaker outputs (SPKOUTL and SPKOUTR) to be disabled by setting SPKL\_ENA and SPKR\_ENA to 0, and the headphone outputs to be disabled by setting CP\_ENA to 0. This response is likely to prevent any damage to the device attributable to the large currents of the output drivers. Note that headphone and speaker audio outputs are both disabled when either of the TEMP\_ERR\_HP or TEMP\_ERR\_SPK register bits is set.

When the audio circuits are disabled by THERR\_ACT after reaching a temperature of 145°C, they will be reset to their previous setting once the temperature drops again.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R23 (17h) Additional control(1)	8	THERR_ACT [15:0]	1	Speaker and Headphone over-temperature shutdown enable.  0 = Disabled 1 = Enabled Note that TEMP_ENA_HP or TEMP_ENA_SPK or both must be enabled for Automatic Shutdown to work
R47 (2Fh) Thermal Shutdown Status	3	TEMP_ERR_ HP	0	Headphone temperature error status (triggered at 145°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field
	2	TEMP_WARN _HP	0	Headphone temperature warning status (triggered at 125°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field
	1	TEMP_ERR_ SPK	0	Speaker temperature error status (triggered at 145°C) 0 = Not triggered 1 = Triggered Note that this is a Read Only field
	0	TEMP_WARN _SPK	0	Speaker temperature warning status (triggered at 125°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R48 (30h)	2	TEMP_ENA_ HP	1	Headphone temperature sensor enable 0 = Disabled 1 = Enabled
	1	TEMP_ENA_S PK	1	Speaker temperature sensor enable 0 = Disabled 1 = Enabled

**Table 125 Temperature Sensor Control** 

## **SOFTWARE RESET AND CHIP ID**

A Software Reset can be commanded by writing to Register R15. This is a read-only register field and the contents will not be affected by writing to this Register. Note that the oscillator and external clocking control registers R115 to R152 are not affected by this reset mechanism; a separate Reset function exists for these registers.

A reset of Registers R115 to R152 can be commanded by writing to Register R127.

The Customer ID and Chip Revision ID can be read back from Register R1 (01h), as described in Table 126.

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R1 (01h) Right Input	15:12	CUST_ID [3:0]	0001	Reading from this register will indicate the Customer ID.
volume	11:9	CHIP_REV [2:0]		Reading from this register will indicate the Chip Revision ID.  000 = Rev A
R15 (0Fh) Software Reset	15:0	SW_RESET [15:0]	1804h	Writing to this register resets the WM8963 registers to their default state. Note that the oscillator external clocking control registers R115 (73h) to R152 (98h) are not affected by this reset. Reading from this register will indicate Chip ID 1804h.
R127 (7Fh) CLKGEN Software Reset	15:0	SW_RESET_ CLKGEN [15:0]	0000h	Writing to this register resets the oscillator and external clocking control registers to their default state. This affects R115 (73h) to R152 (98h) only.

Table 126 Software Reset and Chip ID



# **REGISTER MAP**

The complete register map is shown below. The detailed description can be found in the relevant text of the device description. The WM8963 can be configured using the Control Interface. All registers not listed and all unused bits should not be changed.

Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
R0 (0h)	Left Input volume	0	0	0	0	0	0	0	IN_VU	INPGA L_MUT E	INL_ZC			INL_V	OL [5:0]	ı		009Fh
R1 (1h)	Right Input volume		CUST_	ID [3:0]		CH	IP_REV [	2:0]	IN_VU	INPGA R_MUT E	INR_Z C			INR_V	OL [5:0]			1X9Fh
R2 (2h)	HPOUTL volume	0	0	0	0	0	0	0	HPOUT _VU	HPOUT L_ZC			HPO	UTL_VOL	_ [6:0]			0000h
R3 (3h)	HPOUTR volume	0	0	0	0	0	0	0	HPOUT _VU	HPOUT R_ZC			HPO	UTR_VOI	L [6:0]			0000h
R4 (4h)	Clocking1	0	0	0	0	0		_K_DIV :0]	ADCSY	S_CLK_I	DIV [2:0]	DACSY	S_CLK_I	DIV [2:0]		LK_DIV :0]	0	0020h
R5 (5h)	ADC & DAC Control 1	0	0	0	0	0	0	0	0	0	ADCR_ DAT_IN V	ADCL_ DAT_IN V		DAC_M UTE	_	DEEMP :0]	ADC_H PF_DIS	0018h
R6 (6h)	ADC & DAC Control 2	0	0		IPF_SR :0]	0	ADC_H PF_MO DE	ADC_	HPF_CU	T [2:0]	DACR_ DAT_IN V	DACL_ DAT_IN V	0		DAC_M UTERA TE		DAC_H P	2008h
R7 (7h)	Audio Interface 0	0	0	0	AIFDA C_TDM _MODE	AIFDA C_TDM _SLOT	AIFAD C_TDM _MODE		_	BCLK_I NV	MSTR	DAC_L RSWA P	LRCLK _INV	WL	[1:0]	FM	Γ [1:0]	000Ah
R8 (8h)	Clocking2	0	0	0	0	CLKRE G_OVD		(_SRC :0]	CLASS	D_CLK_[	OIV [2:0]	SYSCL K_ENA	0		BCLK_I	DIV [3:0]		01E4h
R9 (9h)	Audio Interface 1	0	0	0	0	AUTO MUTE_ STS	0	E_SAI	JTOMUT MPLES :0]	DAC_A UTOM UTE	0	0	DAC_C OMP	OMPM OMP OMPM ACK ODE				
R10 (Ah)	Left DAC volume	0	0	0	0	0	0	0	DAC_V U				DACL_\	/OL [7:0]				00C0h
R11 (Bh)	Right DAC volume	0	0	0	0	0	0	0	DAC_V U				DACR_	VOL [7:0]				00C0h
R14 (Eh)	Audio Interface 2	0	0	0	0	0					AIF	_RATE [	[0:0]					0040h
R15 (Fh)	Software Reset								SW_RES	SET [15:0	]							1804h
R17 (11h)	ALC1	0	0	0	0	0	ALC_IN ACTIV E_ENA	ALC_L VL_MO DE	ALCL_ ENA	ALCR_ ENA	ALC_	MAXGAI	N [2:0]		ALC_L	VL [3:0]		007Bh
R18 (12h)	ALC2		ALC_T HRESH _STS			ALC_N GATE_ STS	0	0	0	ALC_Z C	ALC_	_MINGAII	N [2:0]		ALC_H	LD [3:0]		0000h
R19 (13h)	ALC3	0	0	0	ALC_N	GATE_G/	AIN [2:0]	0	ALC_M ODE		ALC_D	CY [3:0]			ALC_A	TK [3:0]		1C32h
R20 (14h)	Noise Gate	AL	C_NGAT	E_DCY [	3:0]	AL	C_NGAT	E_ATK [	3:0]							3200h		
R21 (15h)	Left ADC volume	0	0	0	0	0	0	0	ADC_V U		ADCL_VOL [7:0]						00C0h	
R22 (16h)	Right ADC volume	0	0	0	0	0	0	0	ADC_V U		ADCR_VOL [7:0]					00C0h		
R23 (17h)	Additional control(1)	0	0	0	0	0	0	0	THERR _ACT	0	0	ADC_H P	0	0	0	0	TOCLK _ENA	0100h
R24 (18h)	Additional control(2)	0	0	0	0	0	0	0	0	0	0	0	0	AIF_TR I	0	0	0	0000h



Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
R25 (19h)	Pwr Mgmt (1)	0	0	0	0	0	DMIC_ ENA	OPCLK _ENA	VMID_S	SEL [1:0]	BIAS_E NA	INL_EN A	INR_E NA	ADCL_ ENA	ADCR_ ENA	MICBIA S_ENA	0	0000h
R26 (1Ah)	Pwr Mgmt (2)	0	0	0	0	0	0	0	DACL_ ENA	DACR_ ENA	HPOUT L_PGA _ENA		SPKOU TL_PG A_ENA	SPKOU TR_PG A_ENA	0	_	HPOUT R_PGA _MUTE	0000h
R27 (1Bh)	Additional Control (3)	0	0	0	0	0	0	0	0	0	0	0	SAMPL E_RAT E_INT_ MODE	0	SAMF	PLE_RAT	E [2:0]	0010h
R28 (1Ch)	Anti-pop	0	0	0	0	0	0	0	0	0	0	0	START UP_BIA S_ENA	VMID_ BUF_E NA	VMID_ RAMP	0	0	0000h
R29 (1Dh)	Micbias	0	0	0	0	0	0	0	0	0	0	0	0	0	0		S_EVR :0]	0000h
R30 (1Eh)	Clocking 3	DBC	CLK_DIV	[2:0]	OPO	CLK_DIV	[2:0]	TOO	CLK_DIV	[2:0]		F	256KCL	(_DIV [5:0	0]		0	005Eh
R31 (1Fh)	Input mixer control (1)	0	0	0	0	0	0	0	0	0	0	0	0	MIXINL _MUTE	MIXINR _MUTE		MIXINR _ENA	0000h
R32 (20h)	Left input mixer volume	0	0	0	0	0	0	0	IN2L_M	IIXINL_V	OL [2:0]	INPGA	L_MIXIN [2:0]	L_VOL	IN3L_N	IIXINL_V	OL [2:0]	0145h
R33 (21h)	Right input mixer volume	0	0	0	0	0	0	0	IN2R_M	IIXINR_V	OL [2:0]	INPGA	R_MIXIN [2:0]	R_VOL		IIXINR_V		0145h
R34 (22h)	Input mixer control (2)	0	0	0	0	0	0	0	0	0	0	IN2L_T O_MIXI NL	IN3L_T O_MIXI NL	INPGA L_TO_ MIXINL	_	IN3R_T O_MIXI NR	_	0009h
R35 (23h)	Input bias control	0	0	0	0	0	0	0	0	0	0	MIX	IN_BIAS	[2:0]	INPO	GA_BIAS	[2:0]	0004h
R37 (25h)	Left input PGA control	0	0	0	0	0	0	0	0	0	0	0	INPGA L_ENA	IN1L_T O_INP GAL	IN2L_T O_INP GAL	IN3L_T O_INP GAL	IN4L_T O_INP GAL	0008h
R38 (26h)	Right input PGA control	0	0	0	0	0	0	0	0	0	0	0	INPGA R_ENA	IN1R_T O_INP GAR	IN2R_T O_INP GAR	IN3R_T O_INP GAR	IN4R_T O_INP GAR	0008h
R40 (28h)	SPKOUTL volume	0	0	0	0	0	0	0	SPKOU T_VU	SPKOU TL_ZC			SPKC	UTL_VO	L [6:0]			0000h
R41 (29h)	SPKOUTR volume	0	0	0	0	0	0	0	SPKOU T_VU	SPKOU TR_ZC			SPKO	UTR_VO	L [6:0]			0000h
R47 (2Fh)	Thermal Shutdown Status	0	0	0	0	0	0	0	0	0	0	0	0	TEMP_ ERR_H P	TEMP_ WARN _HP	TEMP_ ERR_S PK	TEMP_ WARN _SPK	0000h
R48 (30h)	Additional Control (4)	1	MICE	ET_THR	R [2:0]	MICSHO R [	_	MICDE T_ENA	0		MICSH ORT_S TS	1	0	0	TEMP_ ENA_H P	TEMP_ ENA_S PK	MICBIA S_LVL	8027h
R49 (31h)	Class D Control 1	0	0	0	0	0	0	0	0		SPKOU TL_EN A	0	DAC_M UTE	0	SPKOU T_VU	TL_PG	SPKOU TR_PG A_MUT E	
R51 (33h)	Class D Control 2	0	0	0	0	0	0	0	0	0	SPK_M ONO	0	0	0	CLAS	SSD_VOL	[2:0]	0003h
R56 (38h)	Clocking 4	0	0	0	0	0	1	0	1	0	0	0		MCLK_R	ATE [3:0]		0	0506h
R57 (39h)	DAC DSP Mixing (1)	0	0	0	0	0	0	DAC_M ONOMI X	0	AD	CR_DAC	S_SVOL [	3:0]		D_DACR :0]	0	0	0000h
R58 (3Ah)	DAC DSP Mixing (2)	0	0	0	0	0	0	0	0	ΑC	OCL_DAC	_SVOL [3	3:0]	ADC_TO	D_DACL :0]	0	0	0000h
R60 (3Ch)	DC Servo 0	0	0	0	0	0	0	0	0		INL_DC S_STA RTUP	0	0	INR_D CS_EN A	INR_D CS_ST ARTUP	0	0	0000h





Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
R61 (3Dh)	DC Servo 1	0	0	0	0	0	0	0	0	HP1L	HP1L_	0	HP1L	HP1R_	HP1R_	0	HP1R_	0000h
Tto I (obil)	DO OCIVO I				·	U				DCS_E			_	DCS_E	DCS_S		DCS_S	000011
										NA	TARTU P		YNC	NA	TARTU P		YNC	
R62 (3Eh)	DC Servo 2	0	0	0	0	0	0	0	0	HP2L_	HP2L	0	HP2L_	HP2R	HP2R	0	HP2R_	0000h
NOZ (SLII)	DC 361V0 2	U	U	U	U	U	"	0	U	_	DCS_S	U		DCS_E	_	0	DCS_S	000011
										NA	TARTU		YNC	NA	TARTU		YNC	
											Р				Р			
R64 (40h)	DC Servo 4	0	0				_SYNC_S			T	0	0	1	0	0	0	0	0810h
R65 (41h)	DC Servo 5	0	0	0	0	0	0	0	0	0				_SYNC_S		T		0010h
R66 (42h)	DC Servo 6	0	0	0	0	0		DCS_S					0	0	0	0	0	0000h
							TARTU P DON	P_DON			TARTU P DON							
							E_INL		E_HP1		E_HP2							
									L	R	L	R						
R68 (44h)	Analogue PGA Bias	0	0	0	0	0	0	0	0	0	0	0	1	1	HP_P	GAS_BIA	AS [2:0]	001Bh
R69 (45h)	Analogue HP 0	0	0	0	0	0	0	0	0	HP1L_	HP1L_	HP1L_	HP1L_	HP1R_	HP1R_	HP1R_	HP1R_	0000h
										_	ENA_O	_	ENA	RMV_S	_	ENA_D	ENA	
						_	_	_		HORT	UTP	LY		HORT	UTP	LY		
R71 (47h)	Analogue HP 2	0	0	0	0	0	0	0		1L_VOL			1R_VOL	<del>`                                    </del>		AS_BOO		01FBh
R72 (48h)	Charge Pump 1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	CP_EN A	0000h
R82 (52h)	Charge Pump B	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	CP_DY N_PW	0004h
																	R	
R87 (57h)	Write Sequencer	0	0	0	0	0	0	0	0	WSEQ	0	WSEQ	0	0	0	0	0	0000h
	Control 1									_AUTO		_ENA						
										SEQ_E NA								
R90 (5Ah)	Write Sequencer	0	0	0	0	0	0	0	WSEQ	WSEQ			NSEO S	TART_IN	IDEX (6·0	11		0000h
1100 (0/11)	Control 2			· ·	v	0			_ABOR	_STAR			WOLK_C	,	IDEX [0.0	<b>'</b> 1		000011
									T	T								
R93 (5Dh)	Write Sequencer	0	0	0	0	0	0		W	SEQ_CU	RRENT_	INDEX [6	:0]		0	0	WSEQ	0000h
D04 (551)	Control 3	_	_	_	_	_	_	_			001.0	001.4	001.05		_	_	_BUSY	22221
R94 (5Eh)	Control Interface	0	0	0	0	0	0	0	0	0	SPI_C ONTRD		SPI_CF G	0	0	0	0	0000h
R96 (60h)	Analogue HP 3	0	0	0	0	0	0	0	0	HP2L_	HP2L_	HP2L_	HP2L_	HP2R_	HP2R_	HP2R_	HP2R_	0000h
	_										ENA_O		ENA	RMV_S	ENA_O	ENA_D	ENA	
										HORT	UTP	LY		HORT	UTP	LY		
R97 (61h)	Analogue HP 4	0	0	0	0	0	0	0	0	HP2_P	0	HP:	2L_VOL	[2:0]	HP:	2R_VOL	[2:0]	00BFh
										GA_SE L								
R99 (63h)	Mixer Enables	0	0	0	0	0	0	0	0	0	0	0	0	0	0	SPKMI	SPKMI	0000h
																	XR_EN	
																Α	Α	
R100 (64h)	Headphone	0	0	0	0	0	0	0	0	SPKMI	0	0	0	0	0	0	0	0000h
	Mixer (1)									XL_TO _HPOU								
										TL_PG								
										Α								
R101 (65h)	Headphone	0	0	0	0	0	0	0	0	SPKMI	0	0	0	0	0	0	0	0000h
	Mixer (2)									XR_TO								
										_HPOU TR_PG								
										A A								
	I		I				1		I			I						





Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default		
R105 (69h)	Speaker Mixer (1)	0	0	0	0	0	0	0	0	SPKMI XL_TO _SPKO UTL_P GA	0	DACL_ TO_SP KMIXL	DACR_ TO_SP KMIXL	MIXINL _TO_S	MIXINR _TO_S PKMIX L	IN4L_T O_SPK	IN4R_T	0000h		
R106 (6Ah)	Speaker Mixer (2)	0	0	0	0	0	0	0	0	SPKMI XR_TO _SPKO UTR_P GA	0	DACL_ TO_SP KMIXR	DACR_ TO_SP KMIXR	_TO_S	MIXINR _TO_S PKMIX R	IN4L_T O_SPK MIXR		0000h		
R107 (6Bh)	Speaker Mixer (3)	0	0	0	0	0	0	0	SPKMI XL_MU TE		_	IN4L_	SPKMIXI [2:0]	L_VOL	IN4R_	SPKMIX [2:0]	L_VOL	013Fh		
R108 (6Ch)	Speaker Mixer (4)	0	0	0	0	0	0	0	SPKMI XR_MU TE		MIXINR _SPKM IXR_V OL	IN4L_	SPKMIXI [2:0]	R_VOL	IN4R_	SPKMIX [2:0]	R_VOL	013Fh		
R109 (6Dh)	Speaker Mixer (5)	0	0	0	0	0	0	0	0	DACL_ SPKMI XL_VO L	DACR_ SPKMI XL_VO L	DACL_ SPKMI XR_VO L	DACR_ SPKMI XR_VO L	0	0	1	1	0003h		
R110 (6Eh)	Beep Generator (1)	0	0	0	0	0	0	0	0		BEEP_G	AIN [3:0]		0		_RATE :0]	BEEP_ ENA	0002h		
R115 (73h)	Oscillator Trim (3)	0	0	0	0	0	0	0	0	0	0	0		OSC_	TRIM_X	TI [4:0]		0000h		
R116 (74h)	Oscillator Trim (4)	0	0	0	0	0	0	0	0	0	0	1								
R119 (77h)	Oscillator Trim (7)	0	0	0	0	0	0	0	0	Х	TO_CAP	_SEL [3:	0]	,	XTI_CAP	_SEL [3:0	0]	0000h		
R124 (7Ch)	Analogue Clocking1	0	0	0	0	0	0	0	0	0	CLKOU [1	T2_SEL :0]	1	0	0	0	CLKOU T5_SE L	0011h		
R125 (7Dh)	Analogue Clocking2	0	0	0	0	0	0	0	0	0	1	0	080_[	DIV [1:0]	0	CLKOU T2_DIV		004Bh		
R126 (7Eh)	Analogue Clocking3	0	0	0	0	0	0	0	0	0	0	0	1	CLKOU T2_OE	1	1	CLKOU T5_OE	001Fh		
R127 (7Fh)	CLKGEN Software Reset							SW_	RESET_0	CLKGEN	[15:0]							0000h		
R129 (81h)	PLL2	0	0	0	0	0	0	0	0	OSC_E NA	0	0	0	0	0	0	1	0001h		
R152 (98h)	Analogue Clocking 4	0	0	0	0	0	0	0	0	1	1	0	OSC_M CLK_S RC	0	0	0	0	00C0h		
R155 (9Bh)	FLL Control (1)	0	0	0	0	0	0	0	0	0	<del>-                                     </del>						000Ch			
R156 (9Ch)	FLL Control (2)	0	0	0	0	0	0	0		IV [1:0]							0039h			
R157 (9Dh)	FLL Control (3)	0	0	0	0	0	0	0	1	1	0	0	0	0	FLL	_FRATIO	[2:0]	0180h		
R159 (9Fh)	FLL Control (5)	0	0	0	0	0	0	0	0	0 0 FLL_FRC_NCO_VAL [5:0] FLL_F 000 RC_NC 0										
R160 (A0h)	FLL Control (6)								FLL_THE	TA [15:0								0018h		
R161 (A1h)	FLL Control (7)		1					F	LL_LAM	BDA [15:0	0]							007Dh		
R162 (A2h)	FLL Control (8)	0	0	0	0	0	0					FLL_	N [9:0]					0008h		





	.,	45	- 44	40	40	- 44	40			T -		_						5 ( )
Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
R176 (B0h)	LDO	0	0	0	0	0	0	0	0	0	0	0	0	0	LDO_V OUT_S EL	LDO_O UT_FL T	LDO_E NA	0002h
R252 (FCh)	General test 1	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	AUTO_ INC	0005h
R256 (100h)	DF1	0	0	0	0	0	0	0	0	0	0	0	0	0	DF1_S HARED _COEF F	DF1_S HARED _COEF F_SEL	DF1_E NA	0000h
R257 (101h)	DF2							DI	-1_COEF	F_L0 [15	:0]							0000h
R258 (102h)	DF3							DI	-1_COEF	F_L1 [15	:0]							0000h
R259 (103h)	DF4							DI	-1_COEF	F_L2 [15	:0]							0000h
R260 (104h)	DF5							DF	1_COEF	F_R0 [15	:0]							0000h
R261 (105h)	DF6							DF	1_COEF	F_R1 [15	:0]							0000h
R262 (106h)	DF7							DF	1_COEF	F_R2 [15	:0]							0000h
R264 (108h)	LHPF1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	LHPF_ MODE	LHPF_ ENA	0000h
R265 (109h)	LHPF2		T			T		L	HPF_CC	EFF [15:	0]				T	T	T	0000h
R268 (10Ch)	THREED1	0	0	0	0	0	0	0	0	0	ADC_M ONOMI X	THREE D_SIG N_L		0	D_LHP	THREE D_LHP F_ENA		0000h
R269 (10Dh)	THREED2		THREE	D_FGAII	VI [4·0]	<u> </u>		THREE	D_CGAI	NI [4·0]		TH	REED D	ELAYL [3		0	0	0000h
R270 (10Eh)	THREED3			.b_i	12 [1.0]				_	F_COEFF	[15:0]		TREED_D		3.01		ı	0000h
R271 (10Fh)	THREED4		THREE	D FGAI	NR [4·0]						[10.0]	TH	RFFD D	FI AYR [	3:01	0	0	0000h
R276 (114h)	DRC 1													000Ch				
( ,		0 DRC_SIG_DET_RMS [4:0] DRC_SIG_DET_ DRC_N DRC_S DRC_S DRC_K DRC_Q DRC_A DRC_M DRC_E PK [1:0] G_ENA G_																
R277 (115h)	DRC 2	0	0	0		DRC_A	TK [3:0]			DRC_D	CY [3:0]		DRC_	MINGAII	N [2:0]		AXGAIN :0]	0925h
R278 (116h)	DRC 3	DR	C_NG_M	ingain [	3:0]	DRC_Q [1	R_THR :0]	DRC_Q [1		DRC_N	_	DRC_	HI_COM	P [2:0]	DRC_	LO_COM	IP [2:0]	0000h
R279 (117h)	DRC 4	0	0	0	0	0			RC_KNE	EE_IP [5:0	)]			DRC_	KNEE_O	P [4:0]		0000h
R280 (118h)	DRC 5	0	0	0	0	0	0		DRC_	KNEE2_I	P [4:0]			DRC_I	KNEE2_C	OP [4:0]		0000h
R285 (11Dh)	Tloopback	0	0	0	0	0	0	0	0	0	0	0	0	0	0	TLB_E NA	TLB_M ODE	0000h
R335 (14Fh)	EQ1	0	0	0	0	0	0	0	0	0	0	0	0	0	ARED_	EQ_SH ARED_ COEFF _SEL	EQ_EN A	0004h
R336 (150h)	EQ2		EQL_	B1_GAIN	N [4:0]			EQL_	B2_GAIN	N [4:0]			EQL_	B3_GAIN	N [4:0]		0	6318h
R337 (151h)	EQ3		EQL_	B4_GAIN	N [4:0]			EQL_	B5_GAIN	N [4:0]		0	0	0	0	0	0	6300h
R338 (152h)	EQ4								EQL_B1	_A [15:0]								0FCAh
R339 (153h)	EQ5								EQL_B1	_B [15:0]								0400h
R340 (154h)	EQ6								EQL_B1_	_PG [15:0	]							00D8h
R341 (155h)	EQ7								EQL_B2	A [15:0]								1EB5h
R342 (156h)	EQ8								EQL_B2	LB [15:0]								F145h
R343 (157h)	EQ9								EQL_B2	_C [15:0]								0B75h
R344 (158h)	EQ10								EQL_B2	_PG [15:0	]							01C5h
R345 (159h)	EQ11								EQL_B3	_A [15:0]								1C58h
R346 (15Ah)	EQ12								EQL_B3	_B [15:0]								F373h
R347 (15Bh)	EQ13								EQL_B3	_C [15:0]								0A54h
R348 (15Ch)	EQ14								EQL_B3_	_PG [15:0	]							0558h



Don	Nama	45	44	42	42	44	40	9	8	7	6	_	4	3	2	1	0	Default
Reg R349 (15Dh)	Name EQ15	15	14	13	12	11	10	9		/ _A [15:0]		5	4	3	2	1	J 0	Default 168Eh
R350 (15Eh)	EQ16									_B [15:0]								F829h 07ADh
R351 (15Fh) R352 (160h)	EQ17 EQ18								EQL_B4 EQL_B4_	_C [15:0]								1103h
R353 (161h)	EQ19									_A [15:0]								0564h
R354 (162h)	EQ20									_B [15:0]								0559h
R355 (163h)	EQ21		FOR	D4 CAI	1.14.01				EQL_B5_		]	1	FOR	D2 O41	1 [4.01			4000h
R356 (164h)	EQ22			_B1_GAIN					_B2_GAII					_B3_GAII	<del>' ' '</del>	Ι.	0	6318h
R357 (165h)	EQ23		EQR_	_B4_GAII	N [4:0]			EQR_	_B5_GAII			0	0	0	0	0	0	6300h
R358 (166h)	EQ24									_A [15:0]								0FCAh
R359 (167h)	EQ25									_B [15:0]								0400h
R360 (168h)	EQ26								EQR_B1	•	•							00D8h
R361 (169h)	EQ27								EQR_B2	_A [15:0]								1EB5h
R362 (16Ah)	EQ28								EQR_B2	_B [15:0]								F145h
R363 (16Bh)	EQ29									_C [15:0]								0B75h
R364 (16Ch)	EQ30								EQR_B2	_PG [15:0	)]							01C5h
R365 (16Dh)	EQ31								EQR_B3	_A [15:0]								1C58h
R366 (16Eh)	EQ32									_B [15:0]								F373h
R367 (16Fh)	EQ33								EQR_B3	_C [15:0]								0A54h
R368 (170h)	EQ34								EQR_B3_	_PG [15:0	)]							0558h
R369 (171h)	EQ35	EQR_B4_A [15:0]  EQR_B4_B [15:0]  EQR_B4_C [15:0]															168Eh	
R370 (172h)	EQ36	EQR_B4_B [15:0] EQR_B4_C [15:0]															F829h	
R371 (173h)	EQ37																	07ADh
R372 (174h)	EQ38		EQR_B4_C [15:0] EQR_B4_PG [15:0]															1103h
R373 (175h)	EQ39																	0564h
R374 (176h)	EQ40								EQR_B5	_B [15:0]								0559h
R375 (177h)	EQ41								EQR_B5	_PG [15:0	)]							4000h
R513 (201h)	GPIO 2	0	0	0	0	0	GP2_P OL	0	0	0	GP2_L VL	0		G	P2_FN [4	:0]		0000h
R516 (204h)	GPIO 5	GP5_DI R	GP5_P U	GP5_P D	0	0	GP5_P OL	GP5_O P_CFG	GP5_D B	0	GP5_L VL	0		G	P5_FN [4	:0]		8100h
R517 (205h)	GPIO 6	GP6_DI R	GP6_P U	GP6_P D	0	0	GP6_P OL	GP6_O P_CFG	GP6_D	0	GP6_L VL	0		G	P6_FN [4	:0]		8100h
R560 (230h)	Interrupt Status	0	0	0	0	0	0	0	0	0	0	GP6_EI NT	GP5_EI NT	0	0	0	0	0000h
R561 (231h)	Interrupt Status	MICSC	MICD	FIFOS_	ALC_L	ALC_T	ALC_S	ALC: P	ALC_N	WSFO	DRC_A		0	0	0	0	TEMP	0000h
11001 (2011)	2	D_EINT		ERR_E	OCK_E		AT_EIN		GATE_		CTDET		ľ			ľ	SHUT_	000011
				INT	INT	_EINT	T	EINT	EINT	_EINT	_EINT	INT					EINT	
R568 (238h)	Interrupt Status 1 Mask	0	0	0	0	0	0	0	0	0	0	IM_GP 6_EINT	IM_GP 5_EINT	0	0	0	0	0030h
R569 (239h)	Interrupt Status		IM_MIC		IM_AL	IM_AL	IM_AL	IM_AL	IM_AL		IM_DR		1	1	1	1	IM_TE	FFFFh
	2 Mask	SCD_E INT	D_EINT	OS_ER R_EINT		ESH_EI		C_PKO VR_EI	TE_EIN	NE_EI	DET_EI						MP_SH UT_EIN	
R576 (240h)	Interrupt Control	Introl         O <td>0000h</td>												0000h				
													OL OL					
R584 (248h)	IRQ Debounce	0	0	0	0	0	0	0	0	0	0	FLL_L OCK_D B	C_D SHUT_					003Fh
R586 (24Ah)	MICINT Source	MICSC D IRQ	MICD_I RQ_PO	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000h
		_POL	L L															
R768 (300h)	DSP2 Power Management	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	DSP2_ ENA	0000h





Des	Name	45	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
<b>Reg</b> R1037	DSP2 ExecCon	<b>15</b> 0	0	0	0	0	0	0	0	0	0	DSP2	DSP2	DSP2	DSP2	DSP2	DSP2	0000h
(40Dh)	trol	0	U	0	0	0	U	0	U	0	0		_	STOPI	STOP	RUNR	RUN	000011
R4096 (1000h)	Write Sequencer 0	0	0						W	/SEQ_AD	DR0 [13:	:0]						001Ch
R4097 (1001h)	Write Sequencer 1	0	0	0	0	0	0	0	0			١	WSEQ_D	ATA0 [7:0	0]			0003h
R4098 (1002h)	Write Sequencer 2	0	0	0	0	0	WSEQ	_DATA_\ [2:0]	VIDTH0	0	0	0	0	WSE	Q_DATA	_START(	(3:0]	0103h
R4099 (1003h)	Write Sequencer 3	0	0	0	0	0	0	0	WSEQ _EOS0	0	0	0	0	W	/SEQ_DI	ELAY0 [3:	0]	0000h
R4100 (1004h)	Write Sequencer 4	0	0						W	/SEQ_AD	DR1 [13:	:0]						0019h
R4101 (1005h)	Write Sequencer 5	0	0	0	0	0	0	0	0			1	WSEQ_D	ATA1 [7:0	0]			0007h
R4102 (1006h)	Write Sequencer 6	0	0	0	0	0	WSEQ.	_DATA_\ [2:0]	WIDTH1	0	0	0	0	WSE	Q_DATA	_START	1 [3:0]	0206h
R4103 (1007h)	Write Sequencer 7	0	0	0	0	0	0	0	WSEQ _EOS1	0	0	0	0	W	/SEQ_DI	ELAY1 [3:	0]	0000h
R4104 (1008h)	Write Sequencer 8																	
				Re	gister Ad	dresses l	R4104 (10	008h) to	contain R	4603 (11F	Bh) Writ	e Sequer	cer Cont	rol Regist	ers			
R4603 (11FBh)	Write Sequencer 507																	
R4604 (11FCh)	Write Sequencer 508															0000h		
R4605 (11FDh)	Write Sequencer 509															0000h		
R4606 (11FEh)	Write Sequencer 510	0	0	0	0	0	WSEQ_	DATA_V 7 [2:0]	VIDTH12	0	0	0	0	WSEC	)_DATA_	START12	27 [3:0]	0000h
R4607 (11FFh)	Write Sequencer 511	0	0	0	0	0	0	0	WSEQ _EOS1 27	0	0	0	0	WS	SEQ_DE	LAY127 [3	3:0]	0000h
R16386 (4002h)	RETUNEDAC_S HARED_COEFF _1	0	0	0	0	0	0	0	0	DAC_R ETUNE _SCV		RETUNE	DAC_SH	HARED_C	OEFF_2	3_16 [6:0]	]	0000h
R16387 (4003h)	RETUNEDAC_S HARED_COEFF _0						RETU	JNEDAC	_SHARE	D_COEFI	_15_00	[15:0]						0000h
R16388 (4004h)	SOUNDSTAGE _ENABLES_1	0	0	0	0	0	0	0	0		S	OUNDS	ΓAGE_EN	NABLES_	23_16 [7	:0]		0000h
R16389 (4005h)	SOUNDSTAGE _ENABLES_0			S	OUNDST	AGE_EN	IABLES_	15_06 [9	0]			0	AC_EN	MBC_E NA	HPF2_ ENA	HPF1_ ENA	VSS_E NA	0000h
R16896 (4200h)	MBC Band 1 K												А					003Fh
	(1)				Registe	er Addres	ses R168	96 (4200	h) to R16	955 (423	Bh) conta	in MBC (	Control R	egisters				
R16955 (423Bh)	MBC RMS Limit				. tog.ott	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		.00 (1200	, 10	(120	J., 00							8C4Bh
R17408 (4400h)	HPF_C_1																	0083h
				Regist	ter Addre	sses R17	408 (440	0h) to R1	7409 (44	01h) cont	ain DAC	High Pas	s Filter C	ontrol Re	gisters			
R17409 (4401h)	HPF_C_0			-														98ADh
R17920 (4600h)	DACL_RETUNE _C1_1			Re	egister Ad	Idresses	R17920 (	4600h) to	R19007	(4A3Fh)	contain D	AC ReTu	une Contr	ol Registe	ers			007Fh



Reg	Name	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Default
R19007 (4A3Fh)	DACR_RETUN E_C32_0													0000h				
R19456 (4C00h)	VSS_XHD2_1																	008Ch
					Registe	r Addres	ses R194	56 (4C00	h) to R19	603 (4C9	3h) conta	ain VSS (	Control R	egisters				
R19603 (4C93h)	VSS_XTS32_0																	8580h

## **REGISTER BITS BY ADDRESS**

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R0 (00h) Left Input volume	8	IN_VU	0	Input PGA Volume and Mute Update Writing a 1 to this bit will cause the INL and INR volume and mute settings to be updated simultaneously
	7	INPGAL_MUTE	1	Left input PGA Mute 0 = Unmuted 1 = Muted
	6	INL_ZC	0	INL PGA Zero Cross Detector 0 = Change gain immediately 1 = Change gain on zero cross only
	5:0	INL_VOL [5:0]	01_1111	Left input PGA Volume -23.25dB to +24.00dB in 0.75dB steps.  00h = -23.25dB 01h = -22.50dB 02h = -21.75dB(0.75dB steps) 1Fh = 0dB 3Fh = 24dB

Register 00h Left Input volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R1 (01h)	15:12	CUST_ID [3:0]	0001	Reading from this register will indicate the Customer ID.
Right Input volume	11:9	CHIP_REV [2:0]		Reading from this register will indicate the Chip Revision ID. 000 = Rev A
	8	IN_VU	0	Input PGA Volume and Mute Update Writing a 1 to this bit will cause the INL and INR volume and mute settings to be updated simultaneously
	7	INPGAR_MUTE	1	Right input PGA Mute 0 = Unmuted 1 = Muted
	6	INR_ZC	0	INR PGA Zero Cross Detector 0 = Change gain immediately 1 = Change gain on zero cross only
	5:0	INR_VOL [5:0]	01_1111	Right input PGA Volume -23.25dB to +24.00dB in 0.75dB steps.  00h = -23.25dB 01h = -22.50dB 02h = -21.75dB(0.75dB steps) 1Fh = 0dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				3Fh = 24dB

Register 01h Right Input volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R2 (02h) HPOUTL volume	8	HPOUT_VU	0	Headphone Output PGA Volume and Mute Update. Writing 1 to this bit will cause the HPOUTL and HPOUTR volume and mute settings to be updated simultaneously.
	7	HPOUTL_ZC	0	HPOUTL_VOL (Left Headphone Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	HPOUTL_VOL [6:0]	000_0000	Left Headphone Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB

Register 02h HPOUTL volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R3 (03h) HPOUTR volume	8	HPOUT_VU	0	Headphone Output PGA Volume and Mute Update. Writing 1 to this bit will cause the HPOUTL and HPOUTR volume and mute settings to be updated simultaneously.
	7	HPOUTR_ZC	0	HPOUTR_VOL (Right Headphone Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	HPOUTR_VOL [6:0]	000_0000	Right Headphone Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB

Register 03h HPOUTR volume



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4 (04h) Clocking1	10:9	DSPCLK_DIV [1:0]	00	DSP Clock Divider  00 = MCLK  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.
	8:6	ADCSYS_CLK_DI V [2:0]	000	ADC Sample Rate Divider  000 = SYSCLK  001 = Reserved  010 = SYSCLK / 2  011 = SYSCLK / 3  100 = SYSCLK / 4  101 = Reserved  110 = SYSCLK / 6  111 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.
	5:3	DACSYS_CLK_DI V [2:0]	100	DAC Sample Rate Divider  000 = SYSCLK  001 = Reserved  010 = SYSCLK / 2  011 = SYSCLK / 3  100 = SYSCLK / 4  101 = Reserved  110 = SYSCLK / 6  111 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.
	2:1	SYSCLK_DIV [1:0]	00	SYSCLK Divider  00 = MCLK  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  This field is for read-back only; it is set automatically and cannot be adjusted.  Note that the division is applied to the selected MCLK source, including the FLL or Oscillator, when applicable.

Register 04h Clocking1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R5 (05h) ADC & DAC Control 1	6	ADCR_DAT_INV	0	Right ADC Invert 0 = Right ADC output not inverted 1 = Right ADC output inverted
	5	ADCL_DAT_INV	0	Left ADC Invert  0 = Left ADC output not inverted  1 = Left ADC output inverted
	4	DAC_MUTE_RAM P	1	DAC Soft Mute Control 0 = Muting the DAC (DAC_MUTE = 1) will cause the volume to change immediately to mute. 1 = Muting the DAC (DAC_MUTE = 1) will cause the volume to ramp down gradually to mute.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	3	DAC_MUTE	1	Digital DAC Mute
				0 = Un-mute
				1 = Mute
				Note that this bit also exists in R49. Reading or writing to either location has the same effect.
	2:1	DAC_DEEMP [1:0]	00	De-Emphasis Control
				00 = No de-emphasis
				01 = De-emphasis for 32kHz sample rate
				10 = De-emphasis for 44.1kHz sample rate
				11 = De-emphasis for 48kHz sample rate
	0	ADC_HPF_DIS	0	ADC High-Pass Filter Disable
				0 = Enable
				1 = Disable

Register 05h ADC & DAC Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R6 (06h) ADC & DAC Control 2	13:12	ADC_HPF_SR [1:0]	10	ADC High-Pass Filter Sample rate $00 = 8k, 11.025k, 12k$ $01 = 16k, 22.025k, 24k$ $10 = 32k, 44.1, 48k$ $11 = 88.2k, 96k$ This field is for read-back only; it is set automatically and cannot be adjusted.
	10	ADC_HPF_MODE	0	ADC High-Pass Filter Mode select 0 = Hi-Fi mode (1st order) 1 = Application mode (2nd order)
	9:7	ADC_HPF_CUT [2:0]	000	ADC High-Pass Filter Cutoff  Note that the cut-off frequency scales with sample rate.
	6	DACR_DAT_INV	0	Right DAC Invert 0 = Right DAC input not inverted 1 = Right DAC input inverted
	5	DACL_DAT_INV	0	Left DAC Invert  0 = Left DAC input not inverted  1 = Left DAC input inverted
	3	DAC_UNMUTE_ RAMP	1	DAC Soft Unmute Control 0 = Unmuting the DAC (DAC_MUTE = 0) will cause the volume to change immediately to the DACL_VOL/DACR_VOL settings. 1 = Unmuting the DAC (DAC_MUTE = 0) will cause the volume to ramp up gradually to the DACL_VOL/DACR_VOL settings.
	2	DAC_MUTERATE	0	DAC Soft Mute Ramp Rate 0 = Fast ramp (maximum ramp time 10.7ms) 1 = Slow ramp (maximum ramp time 171ms). Note that the ramp rate scales with sample rate (fs). Quoted values are correct for fs = 48kHz.
	0	DAC_HP	0	DAC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)

Register 06h ADC & DAC Control 2



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R7 (07h) Audio Interface 0	12	AIFDAC_TDM_ MODE	0	DAC TDM Mode Select 0 = Normal DACDAT operation (1 stereo slot) 1 = TDM enabled on DACDAT (2 stereo slots)
	11	AIFDAC_TDM_ SLOT	0	DACDAT TDM Slot Select 0 = DACDAT data input on slot 0 1 = DACDAT data input on slot 1
	10	AIFADC_TDM_ MODE	0	ADC TDM Mode Select 0 = Normal ADCDAT operation (1 stereo slot) 1 = TDM enabled on ADCDAT (2 stereo slots)
	9	AIFADC_TDM_ SLOT	0	ADCDAT TDM Slot Select 0 = ADCDAT data input on slot 0 1 = ADCDAT data input on slot 1
	8	ADC_LRSWAP	0	Swap left/right ADC data on the interface 0 = Normal 1 = ADCDAT channels swapped
	7	BCLK_INV	0	BCLK Invert 0 = BCLK not inverted 1 = BCLK inverted
	6	MSTR	0	Audio Interface Mode Select 0 = Slave mode 1 = Master mode
	5	DAC_LRSWAP	0	Swap left/right DAC data on the interface 0 = Normal 1 = DACDAT channels swapped
	4	LRCLK_INV	0	Right, left and I2S modes – LRCLK polarity 0 = normal LRCLK polarity 1 = invert LRCLK polarity  DSP Mode – mode A/B select
				0 = MSB is available on 2nd BCLK rising edge after LRCLK rising edge (mode A) 1 = MSB is available on 1st BCLK rising edge after LRCLK rising edge (mode B)
	3:2	WL [1:0]	10	Digital Audio Interface Word Length  00 = 16 bits  01 = 20 bits  10 = 24 bits  11 = 32 bits
	1:0	FMT [1:0]	10	Digital Audio Interface Format  00 = Right justified  01 = Left justified  10 = I2S Format  11 = DSP Mode

Register 07h Audio Interface 0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R8 (08h) Clocking2	11	CLKREG_OVD	0	Clock Configuration Override  0 = MCLK_SRC, OSC_ENA and CLKOUT5_SEL registers are controlled by the GPIO5 pin; CLKOUT2_DIV and CLKOUT5_DIV registers are locked to fixed values.  1 = Clocking registers are controlled as normal via Control Interface.  This bit must be set to 1 to support GPIO functionality on GPIO5.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	10:9	MCLK_SRC [1:0]	00	MCLK source select  00 = MCLK pin  01 = FLL output  10 = GPIO6 or Oscillator (selected by OSC_MCLK_SRC)  11 = Reserved  If CLKREG_OVD = 0, then MCLK_SRC is controlled by the GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 1, then MCLK_SRC = 01 (FLL) and MCLK_SRC cannot be changed by the Control Interface.  If CLKREG_OVD = 0 and GPIO5 = 0, then MCLK_SRC = 00 (MCLK) by default, but the value can be changed via the Control Interface.  If CLKREG_OVD = 1 then MCLK_SRC = 00 (MCLK) by default, but the value can be changed via the Control Interface.
	8:6	CLASSD_CLK_ DIV [2:0]	111	Class D Clock Divider  000 = SYSCLK  001 = SYSCLK / 2  010 = SYSCLK / 3  011 = SYSCLK / 4  100 = SYSCLK / 6  101 = SYSCLK / 8  110 = SYSCLK / 12  111= SYSCLK / 16  This field is for read-back only; it is set automatically and cannot be adjusted.
	5	SYSCLK_ENA	1	SYSCLK enable 0 = Disabled 1 = Enabled
	3:0	BCLK_DIV [3:0]	0100	BCLK Rate  0000 = DSPCLK  0001 = Reserved  0010 = DSPCLK / 2  0011 = DSPCLK / 3  0100 = DSPCLK / 4 (default)  0101 = Reserved  0110 = DSPCLK / 6  0111 = DSPCLK / 8  1000 = Reserved  1001 = DSPCLK / 12  1010 = DSPCLK / 16  1011 = DSPCLK / 24  1100 = Reserved  1101 = DSPCLK / 32  1111 = DSPCLK / 32

Register 08h Clocking2



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R9 (09h) Audio Interface 1	11	AUTOMUTE_STS	0	Readback of the DAC automute status  0 = Automute not detected  1 = Automute detected
	9:8	DAC_ AUTOMUTE_ SAMPLES [1:0]	11	Selects the number of consecutive zero DAC samples that will be interpreted as an Automute.  00 = 128 samples 01 = 256 samples 10 = 512 samples 11 = 1024 samples
	7	DAC_AUTOMUTE	0	DAC Auto-Mute Control 0 = Disabled 1 = Enabled
	4	DAC_COMP	0	DAC Companding Enable 0 = disabled 1 = enabled
	3	DAC_COMPMODE	0	DAC Companding Type 0 = μ-law 1 = A-law
	2	ADC_COMP	0	ADC Companding Enable 0 = disabled 1 = enabled
	1	ADC_COMPMODE	0	ADC Companding Type 0 = μ-law 1 = A-law
	0	LOOPBACK	0	Digital Loopback Function  0 = No loopback  1 = Loopback enabled (ADC data output is directly input to DAC data input).

Register 09h Audio Interface 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R10 (0Ah) Left DAC volume	8	DAC_VU	0	DAC Volume Update Writing a 1 to this bit will cause left and right DAC volume to be updated simultaneously
	7:0	DACL_VOL [7:0]	1100_0000	Left DAC Digital Volume Control  00h = Digital Mute  01h = -71.625dB  02h = -71.250dB  0.375dB steps up to  C0h = 0dB (default)   FFh = 23.625dB

Register 0Ah Left DAC volume



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R11 (0Bh) Right DAC volume	8	DAC_VU	0	DAC Volume Update Writing a 1 to this bit will cause left and right DAC volume to be updated simultaneously
	7:0	DACR_VOL [7:0]	1100_0000	Right DAC Digital Volume Control  00h = Digital Mute  01h = -71.625dB  02h = -71.250dB  0.375dB steps up to  C0h = 0dB (default)   FFh = 23.625dB

Register 0Bh Right DAC volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R14 (0Eh) Audio Interface 2	10:0	AIF_RATE [10:0]	000_0100_0000	LRCLK Rate LRCLK clock output = BCLK / AIF_RATE Integer (LSB = 1) Valid from 42047 Default (040h) = 64 BCLKs per LRCLK

Register 0Eh Audio Interface 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R15 (0Fh) Software Reset	15:0	SW_RESET [15:0]	0001_1000_ 0000_0100	Writing to this register resets the WM8963 registers to their default state.  Note that the oscillator external clocking control registers R115 (73h) to R152 (98h) are not affected by this reset.  Reading from this register will indicate Chip ID 1804h.

Register 0Fh Software Reset

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R17 (11h) ALC1	10	ALC_INACTIVE_ ENA	0	Select whether the ALC is in Active Mode (that is, ALC is controlling the PGA gain) or in Monitor Mode (the analogue controls are disabled). Note that at least one of ALCL_ENA and ALCR_ENA must also be enabled  0 = ALC is in Active Mode  1 = ALC is in Monitor Mode
	9	ALC_LVL_MODE	0	Select the range of the ALC target level.  0 = -28.5dBFS to -6dBFS in 1.5dB steps  1 = -22.5dBFS to -1.5dBFS in 1.5dB steps
	8	ALCL_ENA	0	Select ALC on the Left channel 0 = Disabled (PGA gain set by INL_VOL) 1 = Enabled Note that in stereo mode, the left and right PGA volumes, and left and right boost mixer volumes, must be the same before setting ALCL_ENA = 1 and ALCR_ENA = 1
	7	ALCR_ENA	0	Select ALC on the Right channel



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				0 = Disabled (PGA gain set by INR_VOL) 1 = Enabled Note that in stereo mode, the left and right PGA volumes, and left and right boost mixer volumes, must be the same before setting ALCL_ENA = 1 and ALCR_ENA = 1
	6:4	ALC_MAXGAIN [2:0]	111	Maximum ALC gain 000 = -18dB 001 = -12dB 010 = -6dB 011 = 0dB 100 = +6dB 101 = +12dB 110 = +18dB 111 = +24dB
	3:0	ALC_LVL [3:0]	1011	Set the Target signal level at the ADC input.  Note that the target level is also determined by ALC_LVL_MODE.  ALC_LVL_MODE = 0 0000 = -28.5dBFS 0001 = -27.0dBFSin 1.5dB steps to 1111 = -6dBFS  ALC_LVL_MODE = 1 0000 = -22.5dBFS 0001 = -21.0dBFSin 1.5dB steps to 1110 = -1.5dBFS 1111 = -1.5dBFS

## Register 11h ALC1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R18 (12h) ALC2	15	ALC_LOCK_STS	0	Readback of the ALC Lock Status. Set when ADC signal = ALC_LVL
	14	ALC_THRESH_ STS	0	Readback of the ALC Threshold Level status (when ALC_LOCK_STS = 0)  0 = ADC signal < ALC_LVL  1 = ADC signal > ALC_LVL
	13	ALC_SAT_STS	0	Readback of the ALC saturation status.  0 = ADC signal = ALC_LVL  1 = ADC signal < ALC_LVL but maximum ALC Gain has been reached
	12	ALC_PKOVR_ STS	0	Readback of the ALC Peak Limiter Overload status. Set when ADC input signal exceeds -1.16dBFS
	11	ALC_NGATE_ STS	0	Readback of the ALC Noise Gate status.  0 = ADC input signal level > ALC_NGATE_THR  1 = ADC input signal level < ALC_NGATE_THR
	7	ALC_ZC	0	ALC Zero Cross Detector  0 = Change gain immediately  1 = Change gain on zero cross only



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6:4	ALC_MINGAIN	000	Minimum ALC gain
		[2:0]		000 = -23.25 dB
				001 = -17.25dB
				010 = -11.25dB
				011 = -5.25dB
				100 = +0.75dB
				101 = +6.75dB
				110 = +12.75dB
				111 = +18.75dB
	3:0	ALC_HLD [3:0]	0000	ALC Hold time before the gain ramp-up starts
				0000 = 0.00ms
				0001 = 2.67ms
				0010 = 5.33ms
				0011 = 10.7ms
				0100 = 21.3ms
				0101 = 42.7ms
				0110 = 85.3ms
				0111 = 171ms
				1000 = 341ms
				1001 = 683ms
				1010 = 1.37s
				1011 = 2.73s
				1100 = 5.46s
				1101 = 10.9s 1110 = 21.8s
				1111 = 43.7s

Register 12h ALC2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R19 (13h) ALC3	12:10	ALC_NGATE_ GAIN [2:0]	111	Noise Gate Gain level. This is the PGA gain level used within the ALC Noise Gate function.  000 = -23.25dB  001 = -18dB  010 = -12dB  011 = -6dB  100 = 0dB  101 = +6dB  110 = +12dB  111 = +18dB
	8	ALC_MODE	0	ALC Mode  0 = Normal ALC Mode  1 = Limiter Mode  Note that ALCL_ENA and ALCR_ENA must both be set to 0 before changing ALC_MODE, otherwise unexpected behaviour may result.
	7:4	ALC_DCY [3:0]	0011	Sets the Gain Decay Rate (measured in time per 1.5dB step).  If ALC_MODE = 0  0000 = 0.41ms / step  0001 = 0.82ms / step doubling with each step to  1010 = 420ms / step  1011 = 840ms / step  1100 to 1111 = Reserved  If ALC_MODE = 1



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
ADDRESS				0000 = 0.082ms / step
				0001 = 0.164ms / step
				···doubling with each step to
				1010 = 83.9ms / step
				1011 = 168ms / step
				1100 to 1111 = Reserved
				Note that when 88.2kHz or 96kHz sample rate is selected, the Gain Decay time is defined as for the ALC_MODE=0 case above.
	3:0	ALC_ATK [3:0]	0010	Sets the Gain Attack Rate (measured in time per 1.5dB step).
				If ALC_MODE = 0
				0000 = 0.104ms / step
				0001 = 0.208ms / step
				···doubling with each step to
				1010 = 106ms / step
				1011 to 1111 = Reserved
				If ALC_MODE = 1
				0000 = 0.020ms / step
				0001 = 0.041ms / step
				···doubling with each step to
				1010 = 21.0ms / step
				1011 to 1111 = Reserved
				Note that when 88.2kHz or 96kHz sample rate is selected, the
				Gain Attack time is defined as for the ALC_MODE=0 case
				above.

Register 13h ALC3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R20 (14h) Noise Gate	15:12	ALC_NGATE_ DCY [3:0]	0011	Sets the Noise Gate Gain Decay Rate (time taken to ramp up to the ALC_NGATE_GAIN level), measured in time per 1.5dB step.  If ALC_MODE = 0 0000 = 0.41ms / step 0001 = 0.82ms / stepdoubling with each step to 1010 = 420ms / step 1101 = 840ms / step 1100 to 1111 = Reserved  If ALC_MODE = 1 0000 = 0.082ms / step 0001 = 0.164ms / stepdoubling with each step to 1010 = 83.9ms / step 1011 = 168ms / step 1100 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Noise Gate Gain Decay time is defined as for the ALC_MODE=0 case above.
	11:8	ALC_NGATE_ ATK [3:0]	0010	Sets the Gain Attack Rate (time taken to ramp down to the ALC_NGATE_GAIN level), measured in time per 1.5dB step.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				If ALC_MODE = 0  0000 = 0.10ms / step  0001 = 0.21ms / step doubling with each step to  1010 = 106ms / step  1011 to 1111 = Reserved  If ALC_MODE = 1  0000 = 0.020ms / step  0001 = 0.041ms / step doubling with each step to  1010 = 21.0ms / step  1011 to 1111 = Reserved  Note that when 88.2kHz or 96kHz sample rate is selected, the Noise Gate Gain Attack time is defined as for the ALC_MODE=0 case above.
	7:3	ALC_NGATE_ THR [4:0]	0_0000	Noise Gate Threshold. If the input signal falls below this level, the Noise Gate function is triggered.  -76.5dB to -30dB in 1.5dB steps.  00h = -76.5dB  01h = -75.0dB  02h = -73.5dB (1.5dB steps)  1Eh = -31.5dB  1Fh = -30.0dB
	2:1	ALC_NGATE_ MODE [1:0]	00	Noise gate mode  00 = Hold PGA gain static when noise gate triggers  01 = Mute ADC output immediately when noise gate triggers.  10 = Ramp PGA Gain to ADC_NGATE_GAIN level when  Noise Gate triggers.  11 = Reserved
	0	ALC_NGATE_ ENA	0	Noise Gate function enable 0 = Disable 1 = Enable

Register 14h Noise Gate

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R21 (15h) Left ADC volume	8	ADC_VU	0	ADC Volume Update Writing a 1 to this bit will cause left and right ADC volume to be updated simultaneously
	7:0	ADCL_VOL [7:0]	1100_0000	Left ADC Digital Volume  00h = mute  01h = -71.625dB  02h = -71.250dB 0.375dB steps  C0h = 0dB (default)  FFh = 23.625dB

Register 15h Left ADC volume



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R22 (16h) Right ADC volume	8	ADC_VU	0	ADC Volume Update Writing a 1 to this bit will cause left and right ADC volume to be updated simultaneously
	7:0	ADCR_VOL [7:0]	1100_0000	Right ADC Digital Volume  00h = mute  01h = -71.625dB  02h = -71.250dB 0.375dB steps  C0h = 0dB (default)  FFh = 23.625dB

Register 16h Right ADC volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R23 (17h) Additional control(1)	8	THERR_ACT	1	Speaker and Headphone over temperature shutdown enable.  0 = Disabled  1 = Enabled  Note that TEMP_ENA_HP or TEMP_ENA_SPK or both must be enabled for Automatic Shutdown to work
	5	ADC_HP	0	ADC Oversampling Ratio 0 = Low Power (typically 64 x fs) 1 = High Performance (typically 128 x fs)
	0	TOCLK_ENA	0	TOCLK Enable 0 = Disabled 1 = Enabled

Register 17h Additional control(1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R24 (18h) Additional control(2)	3	AIF_TRI	0	Audio Interface Tristate  0 = Audio interface pins operate normally  1 = ADCDAT is tri-stated; BCLK & LRCLK are set as inputs

Register 18h Additional control(2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R25 (19h) Pwr Mgmt (1)	10	DMIC_ENA	0	Enables Digital Microphone mode.  0 = Audio DSP input is from ADC  1 = Audio DSP input is from digital microphone interface  Note that, when the digital microphone interface is selected, the ADCL_ENA and ADCR_ENA registers must also be set to enable the left and right digital microphone channels respectively.
	9	OPCLK_ENA	0	GPIO Clock Output Enable 0 = Disabled 1 = Enabled
	8:7	VMID_SEL [1:0]	00	VMID Divider Enable and Select  00 = VMID disabled (for OFF mode)  01 = 2 x 50k divider (for normal operation)  10 = 2 x 250k divider (for low power standby)  11 = 2 x 5k divider (for fast start-up)



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6	BIAS_ENA	0	Enables the Normal bias current generator (for all analogue functions)  0 = Disabled  1 = Enabled
	5	INL_ENA	0	Left Input PGA and Mixer Enable.  0 = Disabled  1 = Enabled
	4	INR_ENA	0	Right Input PGA and Mixer Enable.  0 = Disabled  1 = Enabled
	3	ADCL_ENA	0	Left ADC Enable 0 = Disabled 1 = Enabled
	2	ADCR_ENA	0	Right ADC Enable 0 = Disabled 1 = Enabled
	1	MICBIAS_ENA	0	Microphone Bias Enable 0 = OFF (high impedance output) 1 = ON

Register 19h Pwr Mgmt (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R26 (1Ah) Pwr Mgmt (2)	8	DACL_ENA	0	Left DAC Enable  0 = Disabled  1 = Enabled  Note that DACL_ENA must be set to 1 when processing left channel data from the DAC or Digital Beep Generator.
	7	DACR_ENA	0	Right DAC Enable 0 = Disabled 1 = Enabled Note that DACR_ENA must be set to 1 when processing right channel data from the DAC or Digital Beep Generator.
	6	HPOUTL_PGA_ ENA	0	Headphone Left PGA enable  0 = Disabled  1 = Enabled  Note that this must be set for HPOUT1L output.  Note that this must also be set for HPOUT2L output if HP2_PGA_SEL=1.
	5	HPOUTR_PGA_ ENA	0	Headphone Right PGA enable  0 = Disabled  1 = Enabled  Note that this must be set for HPOUT1R output.  Note that this must also be set for HPOUT2R output if HP2_PGA_SEL=1.
	4	SPKOUTL_PGA_ ENA	0	Speaker Left PGA enable 0 = Disabled 1 = Enabled Note that this must be set for SPKOUTL, and for HPOUT2L output if HP2_PGA_SEL=0.
	3	SPKOUTR_PGA_ ENA	0	Speaker Right PGA enable 0 = Disabled 1 = Enabled Note that this must be set for SPKOUTR, and for HPOUT2R output if HP2_PGA_SEL=0.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	1	HPOUTL_PGA_ MUTE	0	HPOUTL_VOL (Left Headphone Output PGA) Mute 0 = Un-mute 1 = Mute
	0	HPOUTR_PGA_ MUTE	0	HPOUTR_VOL (Right Headphone Output PGA) Mute 0 = Un-mute 1 = Mute

Register 1Ah Pwr Mgmt (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R27 (1Bh) Additional Control (3)	4	SAMPLE_RATE_ INT_MODE	1	Selects the Integer or Fractional value of the SAMPLE_RATE register.  0 = 11.025k, 22.05k, 44.1k or 88.2kHz  1 = 8k, 12k, 16k, 24k, 32k, 48k or 96kHz
	2:0	SAMPLE_RATE [2:0]	000	Selects the Sample Rate (fs) 000 = 44.1kHz, 48kHz 001 = 32kHz 010 = 22.05kHz, 24kHz 011 = 16kHz 100 = 11.025kHz, 12kHz 101 = 8kHz 110 = 88.2kHz, 96kHz 111 = Reserved

Register 1Bh Additional Control (3)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R28 (1Ch) Anti-pop	4	STARTUP_BIAS_ ENA	0	Enables the Start-Up bias current generator 0 = Disabled 1 = Enabled
	3	VMID_BUF_ENA	0	VMID Buffer Enable 0 = Disabled 1 = Enabled
	2	VMID_RAMP	0	Enables VMID soft ramp-up 0 = Disabled 1 = Enabled

Register 1Ch Anti-pop

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R29 (1Dh) Micbias	1:0	MICBIAS_EVR [1:0]		Microphone Bias Voltage Control 00 = Controlled by MICBIAS_LVL 10 = 1.34 x AVDD (approx.) X1 = 1.63 x AVDD (approx.)

Register 1Dh Micbias



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R30 (1Eh) Clocking 3	15:13	DBCLK_DIV [2:0]	000	DBCLK Rate Divider (divides the 256kHz clock; nominal frequency is quoted in brackets) 000 = f / 256 (1kHz) 001 = f / 2048 (125Hz) 010 = f / 4096 (62.5Hz) 011 = f / 8192 (31.2Hz) 100 = f / 16384 (15.6Hz) 101 = f / 32768 (7.8Hz) 110 = f / 64536 (3.9Hz) 111 = f / 131072 (1.95Hz)
	12:10	OPCLK_DIV [2:0]	000	GPIO Output Clock Divider  000 = SYSCLK  001 = SYSCLK / 2  010 = SYSCLK / 3  011 = SYSCLK / 4  100 = SYSCLK / 6  101 = SYSCLK / 8  110 = SYSCLK / 12  111 = SYSCLK / 16  000 = SYSCLK / 16
	9:7	TOCLK_DIV [2:0]	000	TOCLK Rate Divider (divides the 256kHz clock; nominal frequency is quoted in brackets) 000 = f / 256 (1kHz) 001 = f / 512 (500Hz) 010 = f / 1024 (250Hz) 011 = f / 2048 (125Hz) 100 = f / 4096 (62.5Hz) 101 = f / 8192 (31.2Hz) 110 = f / 16384 (15.6Hz) 111 = f / 32768 (7.8Hz)
	6:1	F256KCLK_DIV [5:0]	10_1111	256kHz Clock Divider  0d = SYSCLK  1d = SYSCLK / 2  2d = SYSCLK / 3   63d = SYSCLK / 64  This field is for read-back only; it is set automatically and cannot be adjusted.

Register 1Eh Clocking 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R31 (1Fh) Input mixer control (1)	3	MIXINL_MUTE	0	Left input boost mixer mute 0 = Un-mute 1 = Mute
	2	MIXINR_MUTE	0	Right input boost mixer mute 0 = Un-mute 1 = Mute
	1	MIXINL_ENA	0	Left Input Mixer Enable 0 = Disabled 1 = Enabled Note that the Left Input Mixer is also enabled when INL_ENA is set



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	0	MIXINR_ENA	0	Right Input Mixer Enable 0 = Disabled 1 = Enabled Note that the Right Input Mixer is also enabled when INR_ENA is set

Register 1Fh Input mixer control (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R32 (20h) Left input mixer volume	8:6	IN2L_MIXINL_VOL [2:0]	101	Left input IN2L to Left input Boost-Mixer Gain  000 = -12dB  001 = -12dB  010 = -9dB  011 = -6dB  100 = -3dB  101 = 0dB  110 = +3dB  111 = +6dB
	5:3	INPGAL_MIXINL_ VOL [2:0]	000	Left input PGA to Left input Boost Mixer Gain  000 = 0dB  001 = +6dB  010 = +13dB  011 = +18dB  100 = +20dB  101 = +24dB  110 = +27dB  111 = +29dB
	2:0	IN3L_MIXINL_VOL [2:0]	101	Left input IN3L to Left input Boost-Mixer Gain  000 = -12dB  001 = -12dB  010 = -9dB  011 = -6dB  100 = -3dB  101 = 0dB  110 = +3dB  111 = +6dB

Register 20h Left input mixer volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R33 (21h) Right input mixer volume	8:6	IN2R_MIXINR_VOL [2:0]	101	Right input IN2R to Right input Boost-Mixer Gain  000 = -12dB  001 = -12dB  010 = -9dB  011 = -6dB  100 = -3dB  101 = 0dB  110 = +3dB  111 = +6dB
	5:3	INPGAR_MIXINR_ VOL [2:0]	000	Right input PGA to Right input Boost Mixer Gain $000 = 0dB$ $001 = +6dB$ $010 = +13dB$ $011 = +18dB$



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				100 = +20dB 101 = +24dB 110 = +27dB 111 = +29dB
	2:0	IN3R_MIXINR_VOL [2:0]	101	Right input IN3R to Right input Boost-Mixer Gain 000 = -12dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB

Register 21h Right input mixer volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R34 (22h) Input mixer control (2)	5	IN2L_TO_MIXINL	0	Left Input IN2L to Left input Boost-Mixer Select 0 = Disabled 1 = Enabled
	4	IN3L_TO_MIXINL	0	Left Input IN3L to Left input Boost-Mixer Select 0 = Disabled 1 = Enabled
	3	INPGAL_TO_MIXINL	1	Left Input PGA to Left input Boost Mixer Select 0 = Disabled 1 = Enabled
	2	IN2R_TO_MIXINR	0	Right input IN2R to Right input Boost-Mixer Select 0 = Disabled 1 = Enabled
	1	IN3R_TO_MIXINR	0	Right input IN3R to Right input Boost-Mixer Select 0 = Disabled 1 = Enabled
	0	INPGAR_TO_MIXIN R	1	Right input PGA to Right input Boost Mixer Select 0 = Disabled 1 = Enabled

Register 22h Input mixer control (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R35 (23h) Input bias control	5:3	MIXIN_BIAS [2:0]	000	Input Boost-Mixer Bias Control $000 = x 2.0 \text{ (default)}$ $001 = \text{Reserved}$ $010 = \text{Reserved}$ $011 = x 1.0$ $100 = x 0.67$ $101 \text{ to } 111 = \text{Reserved}$
	2:0	INPGA_BIAS [2:0]	100	Input PGA Bias Control $000 = x 2.0$ $001 = Reserved$ $010 = Reserved$ $011 = Reserved$ $100 = x 0.67 (default)$ $101 to 111 = Reserved$



Register 23h Input bias control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R37 (25h) Left input PGA control	4	INPGAL_ENA	0	Left Input PGA Enable.  0 = Disabled  1 = Enabled  Note that the Left Input PGA is also enabled when INL_ENA is set
	3	IN1L_TO_INPGAL	1	Selects the IN1L pin as an input to the left PGA 0 = Disabled 1 = Enabled
	2	IN2L_TO_INPGAL	0	Selects the IN2L pin as an input to the Left PGA  0 = Disabled  1 = Enabled
	1	IN3L_TO_INPGAL	0	Selects the IN3L pin as an input to the Left PGA 0 = Disabled 1 = Enabled
	0	IN4L_TO_INPGAL	0	Selects the IN4L pin as an input to the left PGA 0 = Disabled 1 = Enabled

Register 25h Left input PGA control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R38 (26h) Right input PGA control	4	INPGAR_ENA	0	Right Input PGA Enable 0 = Disabled 1 = Enabled Note that the Right Input PGA is also enabled when INR_ENA is set
	3	IN1R_TO_INPGAR	1	Selects the IN1R pin as an input to the right PGA 0 = Disabled 1 = Enabled
	2	IN2R_TO_INPGAR	0	Selects the IN2L pin as an input to the right PGA 0 = Disabled 1 = Enabled
	1	IN3R_TO_INPGAR	0	Selects the IN3L pin as an input to the right PGA 0 = Disabled 1 = Enabled
	0	IN4R_TO_INPGAR	0	Selects the IN4R pin as an input to the right PGA 0 = Disabled 1 = Enabled

Register 26h Right input PGA control

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R40 (28h) SPKOUTL volume	8	SPKOUT_VU	0	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	7	SPKOUTL_ZC	0	SPKOUTL_VOL (Left Speaker Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6:0	SPKOUTL_VOL [6:0]	000_0000	Left Speaker Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB

Register 28h SPKOUTL volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R41 (29h) SPKOUTR volume	8	SPKOUT_VU	0	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	7	SPKOUTR_ZC	0	SPKOUTR_VOL (Right Speaker Output PGA) Zero Cross Enable 0 = Zero cross disabled 1 = Zero cross enabled
	6:0	SPKOUTR_VOL [6:0]	000_0000	Right Speaker Output PGA Volume Mute, or -68dB to +6dB in 1dB steps.  00h to 2Fh = Mute 30h to 35h = -68dB 36h = -67dB 37h = -66dB(1dB steps) 79h = 0dB 7Fh = 6dB

Register 29h SPKOUTR volume

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R47 (2Fh) Thermal Shutdown Status	3	TEMP_ERR_HP	0	Headphone temperature error status (triggered at 145°C) 0 = Not triggered 1 = Triggered Note that this is a Read Only field
	2	TEMP_WARN_HP	0	Headphone temperature warning status (triggered at 125°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field
	1	TEMP_ERR_SPK	0	Speaker temperature error status (triggered at 145°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field
	0	TEMP_WARN_SPK	0	Speaker temperature warning status (triggered at 125°C)  0 = Not triggered  1 = Triggered  Note that this is a Read Only field

Register 2Fh Thermal Shutdown Status



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R48 (30h)	15	Reserved	1	Reserved - do not change
Additional Control (4)	14:12	MICDET_THR [2:0]	000	MICBIAS Current Detect Threshold (AVDD = 1.8V)  000 = 64uA  001 = 166uA  010 = 358uA  011 = 461uA  100 = 563uA  101 = 666uA  110 = 858uA  111 = 960uA  Note that the value scales with AVDD. The value quoted is correct for AVDD=1.8V.
	11:10	MICSHORT_THR [1:0]	00	MICBIAS Short Circuit Threshold (AVDD = 1.8V) 00 = 510uA 01 = 653uA 10 = 1040uA 11 = 1200uA Note that the value scales with AVDD. The value quoted is correct for AVDD=1.8V.
	9	MICDET_ENA	0	MICBIAS Current and Short Circuit Detect Enable 0 = Disabled 1 = Enabled
	7	MICDET_STS	0	MICBIAS Current Detection status 0 = Current Detect threshold not exceeded 1 = Current Detect threshold exceeded
	6	MICSHORT_STS	0	MICBIAS Short Circuit status 0 = Short Circuit threshold not exceeded 1 = Short Circuit threshold exceeded
	5	Reserved	1	Reserved - do not change
	2	TEMP_ENA_HP	1	Headphone temperature sensor enable 0 = Disabled 1 = Enabled
	1	TEMP_ENA_SPK	1	Speaker temperature sensor enable 0 = Disabled 1 = Enabled
	0	MICBIAS_LVL	1	Microphone Bias Voltage Control 0 = 0.828 x AVDD (approx.) 1 = 1.156 x AVDD (approx.) Only valid when MICBIAS_EVR=00. In other cases, the Microphone Bias voltage is controlled by MICBIAS_EVR alone.

Register 30h Additional Control (4)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R49 (31h) Class D Control 1	7	SPKOUTR_ENA	0	Right channel class D Speaker Enable 0 = Disabled 1 = Enabled
	6	SPKOUTL_ENA	0	Left channel class D Speaker Enable 0 = Disabled 1 = Enabled
	4	DAC_MUTE	1	Digital DAC Mute 0 = Un-mute 1 = Mute



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				Note that this bit also exists in R5. Reading or writing to either location has the same effect.
	2	SPKOUT_VU	0	Speaker Output PGA Volume Update Writing a 1 to this bit will update SPKOUTL_VOL and SPKOUTR_VOL volumes simultaneously.
	1	SPKOUTL_PGA_ MUTE	0	SPKOUTL_VOL (Left Speaker Output PGA) Mute 0 = Un-mute 1 = Mute
	0	SPKOUTR_PGA_ MUTE	0	SPKOUTR_VOL (Right Speaker Output PGA) Mute 0 = Un-mute 1 = Mute

Register 31h Class D Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R51 (33h) Class D Control 2	6	SPK_MONO	0	Mono Speaker Configuration enable 0 = Default (stereo) 1 = Mono mode When SPK_MONO is set to '1', both speakers output the signal from the left channel. Note that the user must tie the outputs together for mono use
	2:0	CLASSD_VOL [2:0]	011	AC Speaker Gain Boost. Note that both left and right channels are boosted equally 000 = 1.00x boost (+0dB) 001 = 1.19x boost (+1.5dB) 010 = 1.41x boost (+3.0dB) 011 = 1.68x boost (+4.5dB) 100 = 2.00x boost (+6.0dB) 101 = 2.37x boost (+7.5dB) 110 = 2.81x boost (+9.0dB) 111 = 3.98x boost (+12.0dB)

Register 33h Class D Control 2

REGISTER	BIT	LABEL	DEFAULT	DESCRIPTION
ADDRESS				
R56 (38h)	4:1	MCLK_RATE [3:0]	0011	Selects the MCLK / fs ratio.
Clocking 4				(Note that the MCLK source is selected by MCLK_SRC.)
				0000 = 64
				0001 = 128
				0010 = 192
				0011 = 256 (default)
				0100 = 384
				0101 = 512
				0110 = 768
				0111 = 1024
				1000 = Reserved
				1001 = 1536
				1010 = 3072
				1011 = 6144
				1100 - 1111 = Reserved
				If DAC ReTune, DAC HPF, VSS or MBC is enabled, then
				MCLK_RATE must be 512 or higher

Register 38h Clocking 4



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R57 (39h) DAC DSP Mixing (1)	9	DAC_MONOMIX	0	DAC Mono Mix  0 = Stereo  1 = Mono (Mono mix output on enabled DAC)  Mono Mix is only supported when one or other DAC is disabled.  When Mono mix is enabled, 6dB attenuation is applied.
	7:4	ADCR_DAC_SVOL [3:0]	0000	Right ADC Digital Sidetone Volume $0000 = -36 dB$ $0001 = -33 dB$ $( 3dB steps)$ $1011 = -3 dB$ $11XX = 0 dB$
	3:2	ADC_TO_DACR [1:0]	00	Right DAC Digital Sidetone Source 00 = No sidetone 01 = Left ADC 10 = Right ADC 11 = No sidetone

Register 39h DAC DSP Mixing (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R58 (3Ah) DAC DSP Mixing (2)	7:4	ADCL_DAC_SVOL [3:0]	0000	Left ADC Digital Sidetone Volume 0000 = -36dB 0001 = -33dB ( 3dB steps) 1011 = -3dB 11XX = 0dB
	3:2	ADC_TO_DACL [1:0]	00	Left DAC Digital Sidetone Source  00 = No sidetone  01 = Left ADC  10 = Right ADC  11 = No sidetone

Register 3Ah DAC DSP Mixing (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R60 (3Ch) DC Servo 0	7	INL_DCS_ENA	0	DC Servo enable for Left input signal path 0 = Disabled 1 = Enabled
	6	INL_DCS_STARTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for Left input signal path
	3	INR_DCS_ENA	0	DC Servo enable for Right input signal path 0 = Disabled 1 = Enabled
	2	INR_DCS_STARTU P	0	Writing 1 to this bit selects Start-Up DC Servo mode for Right input signal path

Register 3Ch DC Servo 0



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R61 (3Dh) DC Servo 1	7	HP1L_DCS_ENA	0	DC Servo enable for HPOUT1L 0 = Disabled 1 = Enabled
	6	HP1L_DCS_ STARTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT1L
	4	HP1L_DCS_SYNC	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT1L
	3	HP1R_DCS_ENA	0	DC Servo enable for HPOUT1R 0 = Disabled 1 = Enabled
	2	HP1R_DCS_ STARTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT1R
	0	HP1R_DCS_SYNC	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT1R

Register 3Dh DC Servo 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R62 (3Eh) DC Servo 2	7	HP2L_DCS_ ENA	0	DC Servo enable for HPOUT2L 0 = Disabled 1 = Enabled
	6	HP2L_DCS_ STARTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT2L
	4	HP2L_DCS_ SYNC	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT2L
	3	HP2R_DCS_ ENA	0	DC Servo enable for HPOUT2R 0 = Disabled 1 = Enabled
	2	HP2R_DCS_ STARTUP	0	Writing 1 to this bit selects Start-Up DC Servo mode for HPOUT2R
	0	HP2R_DCS_ SYNC	0	Writing 1 to this bit selects a series of DC offset corrections for HPOUT2R

Register 3Eh DC Servo 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R64 (40h) DC Servo 4	13:7	HP1_DCS_ SYNC_STEPS [6:0]	001_0000	Number of DC Servo updates to perform in a series event (HPOUT1L and HPOUT1R)  00h to 0Fh = Reserved  10h = 16 (default)  11h = 17   7Fh = 127

Register 40h DC Servo 4



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R65 (41h) DC Servo 5	6:0	HP2_DCS_SYNC_ STEPS [6:0]	001_0000	Number of DC Servo updates to perform in a series event (HPOUT2L and HPOUT2R)  00h to 0Fh = Reserved  10h = 16 (default)  11h = 17   7Fh = 127

Register 41h DC Servo 5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R66 (42h) DC Servo 6	10	DCS_STARTUP_ DONE_INL	0	DC Servo Start-Up Status (Left Input) 0 = Not complete 1 = Complete
	9	DCS_STARTUP_ DONE_INR	0	DC Servo Start-Up Status (Right Input) 0 = Not complete 1 = Complete
	8	DCS_STARTUP_ DONE_HP1L	0	DC Servo Start-Up Status (HPOUT1L)  0 = Not complete  1 = Complete
	7	DCS_STARTUP_ DONE_HP1R	0	DC Servo Start-Up Status (HPOUT1R) 0 = Not complete 1 = Complete
	6	DCS_STARTUP_ DONE_HP2L	0	DC Servo Start-Up Status (HPOUT2L) 0 = Not complete 1 = Complete
	5	DCS_STARTUP_ DONE_HP2R	0	DC Servo Start-Up Status (HPOUT2R) 0 = Not complete 1 = Complete

Register 42h DC Servo 6

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R68 (44h)	4	Reserved	1	Reserved - do not change
Analogue	3	Reserved	1	Reserved - do not change
PGA Bias	2:0	HP_PGAS_BIAS [2:0]	011	Headphone PGA Boost Bias  000 = x 2.0  001 = Reserved  010 = Reserved  011 = x 1.0 (default)  100 to 111 = Reserved

Register 44h Analogue PGA Bias

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R69 (45h) Analogue HP 0	7	HP1L_RMV_SHORT	0	Removes HP1L short  0 = HP1L short enabled  1 = HP1L short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP1L Enable sequence.
	6	HP1L_ENA_OUTP	0	Enables HP1L output stage



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	5	HP1L_ENA_DLY	0	Enables HP1L intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled This bit should be set with at least 20us delay after HP1L_ENA.
	4	HP1L_ENA	0	Enables HP1L input stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set as the first stage of the HP1L Enable sequence.
	3	HP1R_RMV_SHORT	0	Removes HP1R short  0 = HP1R short enabled  1 = HP1R short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP1R Enable sequence.
	2	HP1R_ENA_OUTP	0	Enables HP1R output stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	1	HP1R_ENA_DLY	0	Enables HP1R intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC  Offset cancellation is scheduled This bit should be set with at least 20us delay after HP1R_ENA.
	0	HP1R_ENA	0	Enables HP1R input stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set as the first stage of the HP1R Enable sequence.

Register 45h Analogue HP 0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R71 (47h) Analogue HP 2	8:6	HP1L_VOL [2:0]	111	Headphone 1 Left Secondary PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB  100 = -3dB  101 = -2dB  110 = -1dB  111 = 0dB (default)
	5:3	HP1R_VOL [2:0]	111	Headphone 1 Right Secondary PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				100 = -3dB 101 = -2dB 110 = -1dB 111 = 0dB (default)
	2:0	HP_BIAS_BOOST [2:0]	011	Headphone Driver Boost Bias  000 = x 2.0  001 = Reserved  010 = Reserved  011 = x 1.0 (default)  100 to 111 = Reserved

Register 47h Analogue HP 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R72 (48h) Charge Pump 1	0	CP_ENA	0	Enable charge-pump digits 0 = disable 1 = enable

Register 48h Charge Pump 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R82 (52h) Charge Pump B	0	CP_DYN_PWR	0	Enable dynamic charge pump power control  0 = Charge pump controlled by volume register settings (Class G)  1 = Charge pump controlled by real-time audio level (Class W) Class W is recommended for lowest power consumption When selecting CP_DYN_PWR=0, a '1' must be written to the HPOUT_VU bit (Register R2 or R3) to complete the mode change.

Register 52h Charge Pump B

REGISTER	BIT	LABEL	DEFAULT	DESCRIPTION
ADDRESS				
R87 (57h) Write Sequencer Control 1	7	WSEQ_AUTOSEQ_ ENA	0	Write Sequencer Auto-Sequence Enable (controls the Class D driver via DAC Auto-Mute function) 0 = Disabled 1 = Enabled
	5	WSEQ_ENA	0	Write Sequencer Enable.  0 = Disabled  1 = Enabled

Register 57h Write Sequencer Control 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R90 (5Ah) Write	8	WSEQ_ABORT	0	Writing a 1 to this bit aborts the current sequence and returns control of the device back to the serial control interface.
Sequencer Control 2	7	WSEQ_START	0	Writing a 1 to this bit starts the write sequencer at the index location selected by WSEQ_START_INDEX. The sequence continues until it reaches an "End of sequence" flag. At the end of the sequence, this bit will be reset by the Write Sequencer.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6:0	WSEQ_START_ INDEX [6:0]	000_0000	Sequence Start Index. This field determines the memory location of the first command in the selected sequence. There are 127 Write Sequencer RAM addresses:  00h = WSEQ_ADDR0 (R4096)  01h = WSEQ_ADDR1 (R4100)  02h = WSEQ_ADDR2 (R4104)   7Fh = WSEQ_ADDR127 (R4604)

Register 5Ah Write Sequencer Control 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R93 (5Dh) Write Sequencer Control 3	9:3	WSEQ_CURRENT_ INDEX [6:0]	000_0000	Sequence Current Index. This indicates the memory location of the most recently accessed command in the write sequencer memory.  Coding is the same as WSEQ_START_INDEX.
	0	WSEQ_BUSY	0	Sequencer Busy flag (Read Only).  0 = Sequencer idle  1 = Sequencer busy  Note: it is not possible to write to control registers via the control interface while the Sequencer is Busy.

Register 5Dh Write Sequencer Control 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R94 (005Eh) Control Interface	6	SPI_CONTRD	0	Enable continuous read mode in SPI (3-wire/4-wire) modes 0 = Disabled 1 = Enabled
	5	SPI_4WIRE	0	SPI control mode select 0 = 3-wire using bidirectional SDA 1 = 4-wire using SDOUT
	4	SPI_CFG	0	SDA/SDOUT pin configuration  In 3-wire mode (SPI_4WIRE=0): 0 = SDA output is CMOS 1 = SDA output is Open Drain  In 4-wire mode (SPI_4WIRE=1): 0 = SDOUT output is CMOS 1 = SDOUT output is Wired 'OR'.  Note that only GPIO5 can be configured as Wired 'OR'. This bit has no effect on GPIO2.

Register 5Eh Control Interface

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R96 (60h) Analogue HP 3	7	HP2L_RMV_SHORT	0	Removes HP2L short  0 = HP2L short enabled  1 = HP2L short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP2L Enable sequence.
	6	HP2L_ENA_OUTP	0	Enables HP2L output stage



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	5	HP2L_ENA_DLY	0	Enables HP2L intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC Offset cancellation is scheduled This bit should be set with at least 20us delay after HP2L_ENA.
	4	HP2L_ENA	0	Enables HP2L input stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set as the first stage of the HP2L Enable sequence.
	3	HP2R_RMV_SHORT	0	Removes HP2R short  0 = HP2R short enabled  1 = HP2R short removed  For pop-free operation, this bit should be set to 1 as the final step in the HP2R Enable sequence.
	2	HP2R_ENA_OUTP	0	Enables HP2R output stage 0 = Disabled 1 = Enabled For pop-free operation, this bit should be set to 1 after the DC offset cancellation has been performed.
	1	HP2R_ENA_DLY	0	Enables HP2R intermediate stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set to 1 after the output signal path has been configured, and before the DC  Offset cancellation is scheduled This bit should be set with at least 20us delay after HP2R_ENA.
	0	HP2R_ENA	0	Enables HP2R input stage  0 = Disabled  1 = Enabled  For pop-free operation, this bit should be set as the first stage of the HP2R Enable sequence.

Register 60h Analogue HP 3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R97 (61h) Analogue HP 4	7	HP2_PGA_SEL	1	Headphone 2 PGA configure  0 = HPOUT2 controlled by Speaker PGA settings (SPKOUTL_VOL, SPKOUTR_VOL)  1 = HPOUT2 controlled by Headphone PGA settings (HPOUTL_VOL, HPOUTR_VOL)  Only valid when HP2L_ENA=1 or HP2R_ENA=1. If the HP2 outputs are both disabled, then the Speaker PGA is controlled independently.
	5:3	HP2L_VOL [2:0]	111	Headphone 2 Secondary Left PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				100 = -3dB 101 = -2dB 110 = -1dB 111 = 0dB (default)
	2:0	HP2R_VOL [2:0]	111	Headphone 2 Right Secondary PGA volume.  000 = -7dB  001 = -6dB  010 = -5dB  011 = -4dB  100 = -3dB  101 = -2dB  110 = -1dB  111 = 0dB (default)

Register 61h Analogue HP 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R99 (63h) Mixer Enables	1	SPKMIXL_ENA	0	Left Speaker Mixer Enable 0 = Disabled 1 = Enabled
	0	SPKMIXR_ENA	0	Right Speaker Mixer Enable 0 = Disabled 1 = Enabled

Register 63h Mixer Enables

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R100 (64h) Headphone Mixer (1)	7	SPKMIXL_TO_HPO UTL_PGA	0	Left Headphone PGA Path Select 0 = DACL Output 1 = SPKMIXL Output

Register 64h Headphone Mixer (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R101 (65h) Headphone Mixer (2)	7	SPKMIXR_TO_HPO UTR_PGA		Right Headphone PGA Path Select 0 = DACR Output 1 = SPKMIXR Output

Register 65h Headphone Mixer (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R105 (69h) Speaker Mixer (1)	7	SPKMIXL_TO_SPK OUTL_PGA	0	Left Speaker PGA Path Select 0 = DACL Output 1 = SPKMIXL Output
	5	DACL_TO_SPKMIXL	0	Left DAC to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	4	DACR_TO_SPKMIX L	0	Right DAC to Left Speaker Mixer select 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	3	MIXINL_TO_SPKMI XL	0	Left Input Mixer to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	2	MIXINR_TO_SPKMI XL	0	Right Input Mixer to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	1	IN4L_TO_SPKMIXL	0	Input IN4L to Left Speaker Mixer select 0 = Disabled 1 = Enabled
	0	IN4R_TO_SPKMIXL	0	Input IN4R to Left Speaker Mixer select 0 = Disabled 1 = Enabled

Register 69h Speaker Mixer (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R106 (6Ah) Speaker Mixer (2)	7	SPKMIXR_TO_SPK OUTR_PGA	0	Right Speaker PGA Path Select 0 = DACR Output 1 = SPKMIXR Output
	5	DACL_TO_SPKMIX R	0	Left DAC to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	4	DACR_TO_SPKMIX R	0	Right DAC to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	3	MIXINL_TO_SPKMI XR	0	Left Input Mixer to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	2	MIXINR_TO_SPKMI XR	0	Right Input Mixer to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	1	IN4L_TO_SPKMIXR	0	Input IN4L to Right Speaker Mixer select 0 = Disabled 1 = Enabled
	0	IN4R_TO_SPKMIXR	0	Input IN4R to Right Speaker Mixer select 0 = Disabled 1 = Enabled

Register 6Ah Speaker Mixer (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R107 (6Bh) Speaker Mixer (3)	8	SPKMIXL_MUTE	1	Left Speaker Mixer Mute 0 = Unmuted 1 = Muted
	7	MIXINL_SPKMIXL_V OL	0	Left Input Mixer to Left Speaker Mixer volume $0 = +6dB$ $1 = 0dB$
	6	MIXINR_SPKMIXL_ VOL	0	Right Input Mixer to Left Speaker Mixer volume 0 = +6dB 1 = 0dB
	5:3	IN4L_SPKMIXL_VOL [2:0]	111	Input IN4L to Left Speaker Mixer Volume control 000 = -15dB



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
ADDICEGO	2:0	IN4R_SPKMIXL_VO L [2:0]	111	001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB Input IN4R to Left Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB
				110 = +3dB 111 = +6dB

Register 6Bh Speaker Mixer (3)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R108 (6Ch) Speaker Mixer (4)	8	SPKMIXR_MUTE	1	Right Speaker Mixer Mute 0 = Unmuted 1 = Muted
	7	MIXINL_SPKMIXR_ VOL	0	Left Input Mixer to Right Speaker Mixer volume  0 = +6dB  1 = 0dB
	6	MIXINR_SPKMIXR_ VOL	0	Right Input Mixer to Right Speaker Mixer volume 0 = +6dB 1 = 0dB
	5:3	IN4L_SPKMIXR_VO L [2:0]	111	Input IN4L to Right Speaker Mixer Volume control 000 = -15dB 001 = -12dB 010 = -9dB 011 = -6dB 100 = -3dB 101 = 0dB 110 = +3dB 111 = +6dB
	2:0	IN4R_SPKMIXR_VO L [2:0]	111	Input IN4R to Right Speaker Mixer Volume control  000 = -15dB  001 = -12dB  010 = -9dB  011 = -6dB  100 = -3dB  101 = 0dB  110 = +3dB  111 = +6dB

Register 6Ch Speaker Mixer (4)



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R109 (6Dh) Speaker Mixer (5)	7	DACL_SPKMIXL_VO L	0	Left DAC to Left Speaker Mixer volume 0 = 0dB 1 = -6dB
	6	DACR_SPKMIXL_V OL	0	Right DAC to Left Speaker Mixer volume 0 = 0dB 1 = -6dB
	5	DACL_SPKMIXR_V OL	0	Left DAC to Right Speaker Mixer volume 0 = 0dB 1 = -6dB
	4	DACR_SPKMIXR_V OL	0	Right DAC to Right Speaker Mixer volume 0 = 0dB 1 = -6dB
	1	Reserved	1	Reserved - do not change
	0	Reserved	1	Reserved - do not change

Register 6Dh Speaker Mixer (5)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R110 (6Eh) Beep Generator (1)	7:4	BEEP_GAIN [3:0]	0000	Digital Beep Volume Control $0000 = \text{mute}$ $0001 = -90\text{dB}$ $0010 = -84\text{dB}$ (6dB steps) $1111 = -6\text{dB}$
	2:1	BEEP_RATE [1:0]	01	Digital Beep Waveform Control  If SAMPLE_RATE_INT_MODE = 1  00 = 500Hz  01 = 1000Hz  10 = 2000Hz  11 = 4000Hz  If SAMPLE_RATE_INT_MODE = 0  00 = 499Hz - 502Hz  01 = 999Hz - 1003Hz  10 = 1998Hz - 2005Hz  11 = 3997Hz - 4009Hz
	0	BEEP_ENA	0	Digital Beep Enable  0 = Disabled  1 = Enabled  Note that the DAC and associated signal path needs to be enabled when using the digital beep.

Register 6Eh Beep Generator (1)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R115 (73h) Oscillator Trim (3)	4:0	OSC_TRIM_XTI [4:0]		Trimmed Oscillator XTI capacitance  00h = 14pF  01h = 14.5pF  0.5pF steps  15h = 24.5pF  16h = 25pF  17h to1Fh = 25.5pF  This field is for read-back only; it is set automatically and cannot be adjusted.

Register 73h Oscillator Trim (3)



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R116 (74h) Oscillator Trim (4)	4:0	OSC_TRIM_XTO [4:0]		Trimmed Oscillator XTO capacitance  00h = 14pF  01h = 14.5pF  0.5pF steps  15h = 24.5pF  16h = 25pF  17h to1Fh = 25.5pF  This field is for read-back only; it is set automatically and cannot be adjusted.

Register 74h Oscillator Trim (4)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R119 (77h) Oscillator Trim (7)	7:4	XTO_CAP_SEL [3:0]	0000	XTO load capacitance adjustment Two's complement format, LSB = 0.5pF Range is -4.0pF to +3.5pF
	3:0	XTI_CAP_SEL [3:0]	0000	XTI load capacitance adjustment Two's complement format, LSB = 0.5pF Range is -4.0pF to +3.5pF

Register 77h Oscillator Trim (7)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R124 (7Ch) Analogue Clocking1	6:5	CLKOUT2_SEL [1:0]	00	CLKOUT2 Output Select  00 = FLL  01 = GPIO2  10 = Internal Oscillator  11 = Reserved
	4	Reserved	1	Reserved - do not change
	0	CLKOUT5_SEL	1	CLKOUT5 Output Select  0 = Internal oscillator  1 = FLL  If CLKREG_OVD = 0, then CLKOUT5_SEL is controlled by the GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 0, then CLKOUT5_SEL = 1 (FLL) and cannot be changed by the Control Interface.  If CLKREG_OVD = 0 and GPIO5 = 1, then CLKOUT5_SEL = 0 (Oscillator) by default, but the value can be changed via the Control Interface.  If CLKREG_OVD = 1 then CLKOUT5_SEL = 0 (Oscillator) by default, but the value can be changed via the Control Interface.

Register 7Ch Analogue Clocking1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R125 (7Dh)	6	Reserved	1	Reserved - do not change
Analogue Clocking2	4:3	OSC_DIV	01	GPIO6 / Oscillator to MCLK divider 00 = Divide by 1



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				01 = Divide by 2 10 = Divide by 4 11 = Reserved
	1	CLKOUT2_DIV	1	CLKOUT2 Output Divide  0 = Divide by 1  1 = Divide by 2  If CLKREG_OVD = 0, then CLKOUT2_DIV = 1 (Divide by 2) and cannot be changed by the Control Interface.  If CLKREG_OVD = 1, then CLKOUT2_DIV = 0 by default, but the value can be changed via the Control Interface.
	0	CLKOUT5_DIV	1	CLKOUT5 Output Divide  0 = Divide by 1  1 = Divide by 2  If CLKREG_OVD = 0, then CLKOUT5_DIV = 1 (Divide by 2)  and cannot be changed by the Control Interface.  If CLKREG_OVD = 1, then CLKOUT5_DIV = 0 by default, but the value can be changed via the Control Interface.

Register 7Dh Analogue Clocking2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R126 (7Eh)	4	Reserved	1	Reserved - do not change
Analogue Clocking3	3	CLKOUT2_OE	1	CLKOUT2 Output Enable 0 = Disabled (tri-state) 1 = Enabled
	2	Reserved	1	Reserved - do not change
	1	Reserved	1	Reserved - do not change
	0	CLKOUT5_OE	1	CLKOUT5 Output Enable 0 = Disabled (tri-state) 1 = Enabled

Register 7Eh Analogue Clocking3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R127 (7Fh) CLKGEN Software Reset	15:0	SW_RESET_ CLKGEN [15:0]	0000_0000 _0000_0000	Writing to this register resets the oscillator and external clocking control registers to their default state. This affects R115 (73h) to R152 (98h) only.

Register 7Fh CLKGEN Software Reset



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R129 (81h) PLL 2	7	OSC_ENA	0	Internal Oscillator Enable  0 = Disabled  1 = Enabled  If CLKREG_OVD = 0, then OSC_ENA is controlled by the GPIO5 pin.  If CLKREG_OVD = 0 and GPIO5 = 0, then OSC_ENA = 0 and cannot be changed by the Control Interface.  If CLKREG_OVD = 0 and GPIO5 = 1, then OSC_ENA = 1 by default, but the value can be changed via the Control Interface.  If CLKREG_OVD = 1 then OSC_ENA = 1 by default, but the value can be changed via the Control Interface.
	0	Reserved	1	Reserved - do not change

Register 81h PLL 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R152 (98h)	7	Reserved	1	Reserved - do not change
Analogue	6	Reserved	1	Reserved - do not change
Clocking 4	4	OSC_MCLK_SRC	0	GPIO6 / Oscillator to MCLK source 0 = Oscillator 1 = GPIO6 This field selects the MCLK source, when MCLK_SRC =10.

Register 98h Analogue Clocking 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R155 (9Bh)	6:5	FLL_REFCLK_SRC	00	FLL Clock Source
FLL Control		[1:0]		00 = MCLK
(1)				01 = BCLK
				10 = Internal Oscillator
				11 = Reserved
	3	Reserved	1	Reserved - do not change
	2	FLL_FRAC	1	FLL Fractional Mode enable
				0 = Integer Mode
				1 = Fractional Mode
				Fractional Mode (FLL_FRAC=1) is recommended in all cases
	1	FLL_OSC_ENA	0	FLL Oscillator enable
				0 = Disabled
				1 = Enabled
				(Note that this field is required for free-running FLL modes
				only)
	0	FLL_ENA	0	FLL Enable
				0 = Disabled
				1 = Enabled

Register 9Bh FLL Control (1)



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R156 (9Ch) FLL Control (2)	8:3	FLL_OUTDIV [5:0]	00_0111	FLL FOUT clock ratio 000000 = Reserved 000001 = 2 000010 = 3 000011 = 4 000100 = 5 000101 = 6  111110 = 63 111111 = 64
	1:0	FLL_REFCLK_DIV [1:0]	01	(FOUT = FVCO / FLL_OUTDIV)  FLL Clock Reference Divider  00 = MCLK / 1  01 = MCLK / 2  10 = MCLK / 4  11 = Reserved  MCLK (or other input reference) must be divided down to <=13.5MHz.  For lower power operation, the reference clock can be divided down further if desired.

Register 9Ch FLL Control (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R157 (9Dh)	8	Reserved	1	Reserved - do not change
FLL Control	7	Reserved	1	Reserved - do not change
(3)	2:0	FLL_FRATIO [2:0]	000	FLL FVCO clock ratio  000 = 1  001 = 2  010 = 4  011 = 8  1XX = 16  000 recommended for FREF > 1MHz  011 recommended for FREF < 64kHz

Register 9Dh FLL Control (3)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R159 (9Fh) FLL Control (5)	6:1	FLL_FRC_NCO_VAL [5:0]	01_1001	FLL Forced oscillator value  Valid range is 000000 to 111111  0x19h (011001) = 12MHz approx  (Note that this field is required for free-running FLL modes only)
	0	FLL_FRC_NCO	0	FLL Forced control select  0 = Normal  1 = FLL oscillator controlled by FLL_FRC_NCO_VAL  (Note that this field is required for free-running FLL modes only)

Register 9Fh FLL Control (5)



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R160 (A0h) FLL Control (6)	15:0	FLL_THETA [15:0]		FLL Fractional multiply for FREF. Only valid when FLL_FRAC = 1. This field sets the numerator (multiply) part of the FLL_THETA / FLL_LAMBDA ratio. It is coded as LSB = 1.

Register A0h FLL Control (6)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R161 (A1h) FLL Control (7)	15:0	FLL_LAMBDA [15:0]		FLL Fractional multiply for FREF. Only valid when FLL_FRAC = 1. This field sets the denominator (dividing) part of the FLL_THETA / FLL_LAMBDA ratio. It is coded as LSB = 1. Note that it is required that FLL_LAMBDA > 0 in all cases (Integer and Fractional modes).

Register A1h FLL Control (7)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R162 (A2h) FLL Control (8)	9:0	FLL_N [9:0]	00_0000_100	FLL Integer multiply for FREF (LSB = 1)

Register A2h FLL Control (8)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R176 (B0h) LDO	2	LDO_VOUT_SEL	0	LDO output voltage level setting.  0 = 1.36 x AVDD  1 = 1.78 x AVDD
	1	LDO_OUT_FLT	1	LDO Output Float setting, effective when LDO_ENA==0 0 = LDO output is clamped to ground 1 = LDO output is floating (default)
	0	LDO_ENA	0	LDO Enable 0 = Disabled (default) 1 = Enabled

Register B0h LDO

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R252 (FCh)	2	Reserved	1	Reserved - do not change
General test 1	0	AUTO_INC	1	Enables address auto-increment (applies to 2-wire I2C mode only) 0 = Disabled 1 = Enabled

Register FCh General test 1



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R256 (0100h) DF1	2	DF1_SHARED_ COEFF	0	DF1 Shared Coefficients Enable 0 = Disabled 1 = Enabled
	1	DF1_SHARED_ COEFF_SEL	0	DF1 Shared Coefficients Select 0 = Both channels use left coefficients 1 = Both channels use right coefficients
	0	DF1_ENA	0	DF1 Enable in ADC path 0 = Disabled 1 = Enabled

Register 0100h DF1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R257 (0101h) DF2	15:0	DF1_COEFF_L0 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Left 0

Register 0101h DF2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R258 (0102h) DF3	15:0	DF1_COEFF_L1 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Left 1

Register 0102h DF3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R259 (0103h) DF4	15:0	DF1_COEFF_L2 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Left 2

Register 0103h DF4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R260 (0104h) DF5	15:0	DF1_COEFF_R0 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Right 0

Register 0104h DF5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R261 (0105h) DF6	15:0	DF1_COEFF_R1 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Right 1

Register 0105h DF6



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R262 (0106h) DF7	15:0	DF1_COEFF_R2 [15:0]	0000_0000_ 0000_0000	DF1 Filter Coefficient Right 2

#### Register 0106h DF7

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R264 (0108h) LHPF1	1	LHPF_MODE	0	Low/High-Pass Filter mode select 0 = Low-Pass 1 = High-Pass
	0	LHPF_ENA	0	Low/High-Pass Filter 0 = Disable 1 = Enable

# Register 0108h LHPF1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R265 (0109h) LHPF2	15:0	LHPF_COEFF [15:0]	0000_0000_ 0000_0000	LHPF Coefficient

### Register 0109h LHPF2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R268 (010Ch) THREED1	6	ADC_MONOMIX	0	ADC Monomix enable  0 = Disabled  1 = Enabled  Note that THREED_ENA must be disabled for  ADC_MONOMIX to be effective.
	5	THREED_SIGN_L	0	3D Left Cross mixing polarity (from the right channel to the left) 0 = Positive 1 = Negative
	4	THREED_SIGN_R	0	3D Right Cross mixing polarity (from the left channel to the right) 0 = Positive 1 = Negative
	2	THREED_LHPF_MO DE	0	3D Low/High-Pass filter mode 0 = Low-Pass 1 = High-Pass
	1	THREED_LHPF_EN A	0	3D Low/High-Pass filter enable 0 = Disabled 1 = Enabled
	0	THREED_ENA	0	3D Surround Sound enable 0 = Disabled 1 = Enabled Note that setting THREED_ENA will cause any ADC_MONOMIX setting to be ignored

Register 010Ch THREED1



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R269 (010Dh) THREED2	15:11	THREED_FGAINL [4:0]	0_0000	3D Left Forward Gain 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB
	10:6	THREED_CGAINL [4:0]	0_0000	3D Left Cross Gain (from the right channel to the left) 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB
	5:2	THREED_DELAYL [3:0]	0000	3D Left Filter Delay (measured from the sample rate)  0000 = 0 samples  0001 = 1 samples  0010 = 2 samples  0011 = 3 samples  0100 = 4 samples  0101 = 5 samples  0110 = 6 samples  0111 = 7 samples  1000 = 8 samples  1001 to 1111 = Reserved

Register 010Dh THREED2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R270 (010Eh) THREED3	15:0	THREED_LHPF_ COEFF [15:0]	0000_0000_ 0000_0000	3D LHPF coefficient

Register 010Eh THREED3

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R271 (010Fh) THREED4	15:11	THREED_FGAINR [4:0]	0_0000	3D Right Forward Gain 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB
	10:6	THREED_CGAINR [4:0]	0_0000	3D Right Cross Gain (from the left channel to the right) 00000 = Mute 00001 = -11.25dB 00010 = -10.875dB (in steps of -0.375dB) 11110 = -0.375dB 11111 = 0.0dB
	5:2	THREED_DELAYR [3:0]	0000	3D Filter Delay (measured from the sample rate) 0000 = 0 samples 0001 = 1 samples 0010 = 2 samples



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				0011 = 3 samples
				0100 = 4 samples
				0101 = 5 samples
				0110 = 6 samples
				0111 = 7 samples
				1000 = 8 samples
				1001 to 1111 = Reserved

Register 010Fh THREED4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R276 (0114h) DRC 1	14:10	DRC_SIG_DET_ RMS [4:0]	0_0000	DRC Signal Detect RMS Threshold. This is the RMS signal level for signal detect to be indicated when DRC_SIG_DET_MODE=1. 00000 = -27dB 00001 = -28.5dB (1.5dB steps) 11110 = -72dB 11111 = -73.5dB
	9:8	DRC_SIG_DET_ PK [1:0]	00	DRC Signal Detect Peak Threshold. This is the Peak/RMS ratio, or Crest Factor, level for signal detect to be indicated when DRC_SIG_DET_MODE=0. 00 = 14dB 01 = 20dB 10 = 26dB 11 = 32dB
	7	DRC_NG_ENA	0	DRC Noise Gate Enable 0 = Disabled 1 = Enabled
	6	DRC_SIG_DET_ MODE	0	DRC Signal Detect Mode 0 = Peak threshold mode 1 = RMS threshold mode
	5	DRC_SIG_DET	0	DRC Signal Detect Enable 0 = Disabled 1 = Enabled
	4	DRC_KNEE2_ OP_ENA	0	DRC_KNEE2_OP Enable 0 = Disabled 1 = Enabled
	3	DRC_QR	1	DRC Quick-release Enable 0 = Disabled 1 = Enabled
	2	DRC_ANTICLIP	1	DRC Anti-clip Enable 0 = Disabled 1 = Enabled
	1	DRC_MODE	0	DRC path select 0 = ADC path 1 = DAC path
	0	DRC_ENA	0	DRC Enable 0 = Disabled 1 = Enabled

Register 0114h DRC 1



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R277 (0115h) DRC 2	12:9	DRC_ATK [3:0]	0100	Gain attack rate (seconds/6dB)  0000 = Reserved  0001 = 181us  0010 = 363us  0011 = 726us  0100 = 1.45ms  0101 = 2.9ms  0110 = 5.8ms  0111 = 11.6ms  1000 = 23.2ms  1001 = 46.4ms  1010 = 92.8ms  1011 = 185.6ms  1100-1111 = Reserved
	8:5	DRC_DCY [3:0]	1001	Gain decay rate (seconds/6dB)  0000 = 1.45ms  0001 = 2.9ms  0010 = 5.8ms  0011 = 11.6ms  0100 = 23.25ms  0101 = 46.5ms  0110 = 93ms  0111 = 186ms  1000 = 372ms  1001 = 743ms (default)  1010 = 1.49s  1011 = 2.97s  1100 = 5.94s  1101 = 11.89s  1110 = 23.78s  1111 = 47.56s
	4:2	DRC_MINGAIN [2:0]	001	Minimum gain the DRC can use to attenuate audio signals 000 = 0dB 001 = -12dB (default) 010 = -18dB 011 = -24dB 100 = -36dB 101 to 111 = Reserved
	1:0	DRC_MAXGAIN [1:0]	01	Maximum gain the DRC can use to boost audio signals (dB) $00 = 12dB$ $01 = 18dB (default)$ $10 = 24dB$ $11 = 36dB$

Register 0115h DRC 2



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R278 (0116h) DRC 3	15:12	DRC_NG_MINGAIN [3:0]	0000	Minimum gain the DRC can use to attenuate audio signals when the noise gate is active.  0000 = -36dB 0001 = -30dB 0010 = -24dB 0011 = -18dB 0010 = -12dB 0101 = -6dB 0110 = 0dB 0111 = 6dB 1100 = 12dB 1001 = 18dB 1000 = 12dB 1001 = 18dB 1010 = 24dB 1011 = 30dB 1100 to 1111 = Reserved
	11:10	DRC_QR_THR [1:0]	00	DRC Quick-release threshold (crest factor in dB)  00 = 12dB  01 = 18dB  10 = 24dB  11 = 30dB
	9:8	DRC_QR_DCY [1:0]	00	DRC Quick-release decay rate (seconds/6dB) $00 = 0.725 ms$ $01 = 1.45 ms$ $10 = 5.8 ms$ $11 = reserved$
	7:6	DRC_NG_EXP [1:0]	00	Noise Gate slope 00 = 1 (no expansion) 01 = 2 10 = 4 11 = 8
	5:3	DRC_HI_COMP [2:0]	000	Compressor slope (upper region)  000 = 1 (no compression)  001 = 1/2  010 = 1/4  011 = 1/8 (default)  100 = 1/16  101 = 0 (ALC Mode)  110 = Reserved  111 = Reserved
	2:0	DRC_LO_COMP [2:0]	000	Compressor slope (lower region)  000 = 1 (no compression)  001 = 1/2  010 = 1/4  011 = 1/8  100 = 0  101 to 111 = Reserved

Register 0116h DRC 3



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R279 (0117h) DRC 4	10:5	DRC_KNEE_IP [5:0]	00_0000	Input signal level at the Compressor 'Knee'.  000000 = 0dB  000001 = -0.75dB  000010 = -1.5dB  (-0.75dB steps)  111100 = -45dB  111101 to 111111 = Reserved
	4:0	DRC_KNEE_OP [4:0]	0_0000	Output signal at the Compressor 'Knee'.  00000 = 0dB  00001 = -0.75dB  00010 = -1.5dB  (-0.75dB steps)  11110 = -22.5dB  11111 = Reserved

Register 0117h DRC 4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R280 (0118h) DRC 5	9:5	DRC_KNEE2_IP [4:0]	0_0000	Input signal level at the Noise Gate threshold 'Knee2'.  00000 = -36dB  00001 = -37.5dB  00010 = -39dB  (-1.5dB steps)  11110 = -81dB  11111 = -82.5dB  Only applicable when DRC_NG_ENA = 1.
	4:0	DRC_KNEE2_OP [4:0]	0_0000	Output signal at the Noise Gate threshold 'Knee2'.  00000 = -30dB  00001 = -31.5dB  00010 = -33dB  (-1.5dB steps)  11110 = -75dB  11111 = -76.5dB  Only applicable when DRC_KNEE2_OP_ENA = 1.

Register 0118h DRC 5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R285 (011Dh) Tloopback	1	TLB_ENA	0	T-Loopback Enable 0 = Disabled 1 = Enabled
	0	TLB_MODE	0	T-Loopback Mode Select  0: Left AIF Output = Left ADC; Right AIF Output = (Left DAC + Right DAC) / 2  1: Left AIF Output = (Left DAC + Right DAC) / 2; Right AIF Output = Right ADC

Register 011Dh Tloopback



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R335 (014Fh) EQ1	2	EQ_SHARED_ COEFF	1	5-Band EQ Shared Coefficient enable 0 = Right and Left channels use unique coefficients 1 = Left and right channels share filter coefficients
	1	EQ_SHARED_ COEFF_SEL	0	5-Band EQ Shared Coefficient select 0 = Both channels use the left channel filter coefficients 1 = Both channels use the right channel filter coefficients
	0	EQ_ENA	0	5-Band EQ Enable 0 = Disabled 1 = Enabled

Register 014Fh EQ1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R336 (0150h) EQ2	15:11	EQL_B1_GAIN [4:0]	0_1100	Left Channel Band 1 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB
	10:6	EQL_B2_GAIN [4:0]	0_1100	1_1001 to 1_1111 reserved  Left Channel Band 2 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved
	5:1	EQL_B3_GAIN [4:0]	0_1100	Left Channel Band 3 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved

Register 0150h EQ2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R337 (0151h) EQ3	15:11	EQL_B4_GAIN [4:0]	0_1100	Left Channel Band 4 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved
	10:6	EQL_B5_GAIN [4:0]	0_1100	Left Channel Band 5 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved

Register 0151h EQ3



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R338 (0152h) EQ4	15:0	EQL_B1_A [15:0]	0000_1111_ 1100_1010	5 Band EQ Band 1 coefficient A

#### Register 0152h EQ4

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R339 (0153h) EQ5	15:0	EQL_B1_B [15:0]	0000_0100_ 0000_0000	5 Band EQ Band 1 coefficient B

# Register 0153h EQ5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R340 (0154h) EQ6	15:0	EQL_B1_PG [15:0]	0000_0000_ 1101_1000	5 Band EQ Band 1 coefficient PG

### Register 0154h EQ6

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R341 (0155h) EQ7	15:0	EQL_B2_A [15:0]	0001_1110_ 1011_0101	5 Band EQ Band 2 coefficient A

# Register 0155h EQ7

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R342 (0156h) EQ8	15:0	EQL_B2_B [15:0]	1111_0001_ 0100_0101	5 Band EQ Band 2 coefficient B

# Register 0156h EQ8

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R343 (0157h) EQ9	15:0	EQL_B2_C [15:0]	0000_1011_ 0111_0101	5 Band EQ Band 2 coefficient C

# Register 0157h EQ9

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R344 (0158h) EQ10	15:0	EQL_B2_PG [15:0]	0000_0001_ 1100_0101	5 Band EQ Band 2 coefficient PG

Register 0158h EQ10



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R345 (0159h) EQ11	15:0	EQL_B3_A [15:0]	0001_1100_ 0101_1000	5 Band EQ Band 3 coefficient A

### Register 0159h EQ11

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R346 (015Ah) EQ12	15:0	EQL_B3_B [15:0]	1111_0011_ 0111_0011	5 Band EQ Band 3 coefficient B

# Register 015Ah EQ12

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R347 (015Bh) EQ13	15:0	EQL_B3_C [15:0]	0000_1010_ 0101_0100	5 Band EQ Band 3 coefficient C

# Register 015Bh EQ13

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R348 (015Ch) EQ14	15:0	EQL_B3_PG [15:0]	0000_0101_ 0101_1000	5 Band EQ Band 3 coefficient PG

### Register 015Ch EQ14

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R349 (015Dh) EQ15	15:0	EQL_B4_A [15:0]	0001_0110_ 1000_1110	5 Band EQ Band 4 coefficient A

### Register 015Dh EQ15

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R350 (015Eh) EQ16	15:0	EQL_B4_B [15:0]	1111_1000_ 0010_1001	5 Band EQ Band 4 coefficient B

### Register 015Eh EQ16

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R351 (015Fh) EQ17	15:0	EQL_B4_C [15:0]	0000_0111_ 1010_1101	5 Band EQ Band 4 coefficient C

### Register 015Fh EQ17



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R352 (0160h) EQ18	15:0	EQL_B4_PG [15:0]	0001_0001_ 0000_0011	5 Band EQ Band 2 coefficient PG

#### Register 0160h EQ18

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R353 (0161h) EQ19	15:0	EQL_B5_A [15:0]	0000_0101_ 0110_0100	5 Band EQ Band 5 coefficient A

# Register 0161h EQ19

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R354 (0162h) EQ20	15:0	EQL_B5_B [15:0]	0000_0101_ 0101_1001	5 Band EQ Band 5 coefficient B

### Register 0162h EQ20

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R355 (0163h) EQ21	15:0	EQL_B5_PG [15:0]	0100_0000_ 0000_0000	5 Band EQ Band 5 coefficient PG

# Register 0163h EQ21

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R356 (0164h) EQ22	15:11	EQR_B1_GAIN [4:0]	0_1100	Right Channel Band 1 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved
	10:6	EQR_B2_GAIN [4:0]	0_1100	Right Channel Band 2 EQ Gain  0_0000 = -12dB  0_0001 = -11dB  ···1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved
	5:1	EQR_B3_GAIN [4:0]	0_1100	Right Channel Band 3 EQ Gain 0_0000 = -12dB 0_0001 = -11dB1dB steps to 1_1000 = +12dB 1_1001 to 1_1111 reserved

Register 0164h EQ22



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R357 (0165h) EQ23	15:11	EQR_B4_GAIN [4:0]	0_1100	Right Channel Band 4 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved
	10:6	EQR_B5_GAIN [4:0]	0_1100	Right Channel Band 5 EQ Gain  0_0000 = -12dB  0_0001 = -11dB 1dB steps to  1_1000 = +12dB  1_1001 to 1_1111 reserved

Register 0165h EQ23

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R358 (0166h) EQ24	15:0	EQR_B1_A [15:0]	0000_1111_ 1100_1010	5 Band EQ Band 1 coefficient A

Register 0166h EQ24

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R359 (0167h) EQ25	15:0	EQR_B1_B [15:0]	0000_0100_ 0000_0000	5 Band EQ Band 1 coefficient B

Register 0167h EQ25

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R360 (0168h) EQ26	15:0	EQR_B1_PG [15:0]	0000_0000_ 1101_1000	5 Band EQ Band 1 coefficient PG

Register 0168h EQ26

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R361 (0169h) EQ27	15:0	EQR_B2_A [15:0]	0001_1110_ 1011_0101	5 Band EQ Band 2 coefficient A

Register 0169h EQ27

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R362 (016Ah) EQ28	15:0	EQR_B2_B [15:0]	1111_0001_ 0100_0101	5 Band EQ Band 2 coefficient B

Register 016Ah EQ28



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R363 (016Bh) EQ29	15:0	EQR_B2_C [15:0]	0000_1011_ 0111_0101	5 Band EQ Band 2 coefficient C

## Register 016Bh EQ29

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R364 (016Ch) EQ30	15:0	EQR_B2_PG [15:0]	0000_0001_ 1100_0101	5 Band EQ Band 2 coefficient PG

#### Register 016Ch EQ30

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R365 (016Dh) EQ31	15:0	EQR_B3_A [15:0]	0001_1100_ 0101_1000	5 Band EQ Band 3 coefficient A

## Register 016Dh EQ31

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R366 (016Eh) EQ32	15:0	EQR_B3_B [15:0]	1111_0011_ 0111_0011	5 Band EQ Band 3 coefficient B

## Register 016Eh EQ32

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R367 (016Fh) EQ33	15:0	EQR_B3_C [15:0]	0000_1010_ 0101_0100	5 Band EQ Band 3 coefficient C

## Register 016Fh EQ33

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R368 (0170h) EQ34	15:0	EQR_B3_PG [15:0]	0000_0101_ 0101_1000	5 Band EQ Band 3 coefficient PG

## Register 0170h EQ34

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R369 (0171h) EQ35	15:0	EQR_B4_A [15:0]	0001_0110_ 1000_1110	5 Band EQ Band 4 coefficient A

## Register 0171h EQ35



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R370 (0172h) EQ36	15:0	EQR_B4_B [15:0]	1111_1000_ 0010_1001	5 Band EQ Band 4 coefficient B

## Register 0172h EQ36

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R371 (0173h) EQ37	15:0	EQR_B4_C [15:0]	0000_0111_ 1010_1101	5 Band EQ Band 4 coefficient C

## Register 0173h EQ37

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R372 (0174h) EQ38	15:0	EQR_B4_PG [15:0]	0001_0001_ 0000_0011	5 Band EQ Band 2 coefficient PG

## Register 0174h EQ38

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R373 (0175h) EQ39	15:0	EQR_B5_A [15:0]	0000_0101_ 0110_0100	5 Band EQ Band 5 coefficient A

## Register 0175h EQ39

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R374 (0176h) EQ40	15:0	EQR_B5_B [15:0]	0000_0101_ 0101_1001	5 Band EQ Band 5 coefficient B

## Register 0176h EQ40

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R375 (0177h) EQ41	15:0	EQR_B5_PG [15:0]	0100_0000_ 0000_0000	5 Band EQ Band 5 coefficient PG

## Register 0177h EQ41

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R513 (0201h) GPIO 2	10	GP2_POL	0	GPIO 2 Polarity 0 = Not inverted 1 = Inverted
	9	GP2_LVL	0	GPIO 2 Output Level (when GP2_FN = 00001) 0 = Logic 0 1 = Logic 1 Note that this is a Write-Only register; the Readback value is undefined



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	4:0	GP2_FN [4:0]	0_0000	00h = CLKOUT (FLL) - see note below 01h = Logic 0/1 (set by GP2_LVL) 02h = SDOUT 03h = IRQ 04h = Temperature shutdown 09h = FLL Lock 0Ah = DRC Activity detect 0Bh = Write Sequencer done 0Ch = ALC Noise Gate active 0Dh = ALC Peak Limiter overload 0Eh = ALC Saturation 0Fh = ALC level threshold 10h = ALC Level lock 11h = FIFO error indicator 12h = OPCLK 13h = DMICCLK output 15h = Mic Detect flag 16h = Mic Short Circuit flag All other codes are Reserved Note that FLL or Oscillator CLKOUT is enabled using CLKOUT2_SEL. Setting GP2_FN = 00h is recommended in this case.

Register 0201h GPIO 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R516 (0204h) GPIO 5	15	GP5_DIR	1	GPIO5 Direction 0 = Output 1 = Input
	14	GP5_PU	0	GPIO5 pull-up resistor enable 0 = pull-up disabled 1 = pull-up enabled
	13	GP5_PD	0	GPIO5 pull-down resistor enable 0 = pull-up disabled 1 = pull-down enabled
	10	GP5_POL	0	GPIO5 Polarity 0 = Not inverted 1 = Inverted
	9	GP5_OP_CFG	0	GPIO5 Output pin configuration 0 = CMOS 1 = Open-drain
	8	GP5_DB	1	GPIO5 input de-bounce 0 = Disabled 1 = Enabled
	6	GP5_LVL	0	GPIO 5 Level (when GP5_FN = 01h) 0 = Logic 0 1 = Logic 1 Write to this bit to set the GPIO5 output. Read from this bit to read GPIO input level. Note that, when GPIO5 is configured as an output (GP5_DIR=0), this is a Write-Only register; the Readback value is undefined.



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	4:0	GP5_FN[4:0]	00h	GPIO5 Pin Function select 00h = Unused
				01h = Logic 0/1 (set by GP5_LVL)
				02h = SDOUT
				03h = IRQ
				04h = Temperature shutdown
				09h = FLL Lock
				0Ah = DRC Activity detect
				0Bh = Write Sequencer done
				0Ch = ALC Noise Gate active
				0Dh = ALC Peak Limiter overload
				0Eh = ALC Saturation
				0Fh = ALC level threshold
				10h = ALC Level lock
				11h = FIFO error indicator
				12h = OPCLK
				13h = DMICCLK output
				14h = DMICDAT input
				15h = Mic Detect flag
				16h = Mic Short Circuit flag
				All other codes are Reserved
				Note that GPIO5 functions are only supported when CLKREG_OVD=1.
				When CLKREG_OVD=0, the contents of Register R516 must not be changed from the default value.

Register 0204h GPIO 5

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R517 (0205h) GPIO 6	15	GP6_DIR	1	GPIO6 Direction 0 = Output 1 = Input
	14	GP6_PU	0	GPIO6 pull-up resistor enable 0 = pull-up disabled 1 = pull-up enabled
	13	GP6_PD	0	GPIO6 pull-down resistor enable 0 = pull-up disabled 1 = pull-down enabled
	10	GP6_POL	0	GPIO6 Polarity 0 = Not inverted 1 = Inverted
	9	GP6_OP_CFG	0	GPIO6 Output pin configuration 0 = CMOS 1 = Open-drain
	8	GP6_DB	1	GPIO6 input de-bounce 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	6	GP6_LVL	0	GPIO 6 Level (when GP6_FN = 01h) 0 = Logic 0 1 = Logic 1 Write to this bit to set the GPIO6 output. Read from this bit to read GPIO input level. Note that, when GPIO6 is configured as an output (GP6_DIR=0), this is a Write-Only register; the Readback value is undefined.
	4:0	GP6_FN[4:0]	0_0000	GPIO6 Pin Function select  00h = CS input (SDI interface)  01h = Logic 0/1 (set by GP6_LVL)  03h = IRQ  04h = Temperature shutdown  09h = FLL Lock  0Ah = DRC Activity detect  0Bh = Write Sequencer done  0Ch = ALC Noise Gate active  0Dh = ALC Peak Limiter overload  0Eh = ALC Saturation  0Fh = ALC level threshold  10h = ALC Level lock  11h = FIFO error indicator  12h = OPCLK  13h = DMICCLK output  14h = DMICDAT input  15h = Mic Detect flag  All other codes are Reserved

Register 0205h GPIO 6

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R560 (0230h) Interrupt Status 1	5	GP6_EINT	0	GPIO6 IRQ status 0 = GPIO6 IRQ not set 1 = GPIO6 IRQ set Note: cleared when a '1' is written
	4	GP5_EINT	0	GPIO5 IRQ status 0 = GPIO5 IRQ not set 1 = GPIO5 IRQ set Note: cleared when a '1' is written

Register 0230h Interrupt Status 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R561 (0231h) Interrupt Status 2	15	MICSCD_EINT	0	Mic Short Circuit Interrupt Status  0 = MICSCD IRQ not set  1 = MICSCD IRQ set  Note: cleared when a '1' is written
	14	MICD_EINT	0	Mic Detect Interrupt Status 0 = MICD IRQ not set 1 = MICD IRQ set Note: cleared when a '1' is written
	13	FIFOS_ERR_EINT	0	FIFO error IRQ status



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
				0 = FIFO error IRQ not set 1 = FIFO error IRQ set Note: cleared when a '1' is written
	12	ALC_LOCK_EINT	0	ALC level lock IRQ status  0 = ALC level lock IRQ not set  1 = ALC level lock IRQ set  Note: cleared when a '1' is written
	11	ALC_THRESH_EINT	0	ALC level threshold IRQ status  0 = ALC level threshold IRQ not set  1 = ALC level threshold IRQ set  Note: cleared when a '1' is written
	10	ALC_SAT_EINT	0	ALC saturation IRQ status 0 = ALC saturation IRQ not set 1 = ALC saturation IRQ set Note: cleared when a '1' is written
	9	ALC_PKOVR_EINT	0	ALC peak overload detector IRQ status 0 = ALC pk. overload det. IRQ not set 1 = ALC pk. Overload det. IRQ set Note: cleared when a '1' is written
	8	ALC_NGATE_EINT	0	ALC Noise Gate active IRQ status  0 = ALC Noise Gate IRQ not set  1 = ALC Noise Gate IRQ set  Note: cleared when a '1' is written
	7	WSEQ_DONE_EINT	0	Write Sequencer done IRQ status 0 = Write Sequencer IRQ not set 1 = Write Sequencer IRQ set Note: cleared when a '1' is written
	6	DRC_ACTDET_EINT	0	DRC Activity IRQ status  0 = DRC Activity IRQ not set  1 = DRC Activity IRQ set  Note: cleared when a '1' is written
	5	FLL_LOCK_EINT	0	FLL lock IRQ status 0 = FLL lock IRQ not set 1 = FLL lock IRQ set Note: cleared when a '1' is written
	0	TEMP_SHUT_EINT	0	Temperature Shutdown IRQ status 0 = Temperature Shutdown IRQ not set 1 = Temperature Shutdown IRQ set Note: cleared when a '1' is written

Register 0231h Interrupt Status 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R568 (0238h) Interrupt Status 1	5	IM_GP6_EINT	1	Interrupt mask for GPIO6 0 = Not masked 1 = Masked
Mask	4	IM_GP5_EINT	1	Interrupt mask for GPIO5 0 = Not masked 1 = Masked

Register 0238h Interrupt Status 1 Mask



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R569 (0239h) Interrupt Status 2	15	IM_MICSCD_ EINT	1	Interrupt mask for Mic Short Circuit 0 = Not masked 1 = Masked
Mask	14	IM_MICD_EINT	1	Interrupt mask for Mic Detect 0 = Not masked 1 = Masked
	13	IM_FIFOS_ERR_ EINT	1	Interrupt mask for FIFOS Error  0 = Not masked  1 = Masked
	12	IM_ALC_LOCK_ EINT	1	Interrupt mask for ALC Lock  0 = Not masked  1 = Masked
	11	IM_ALC_ THRESH_EINT	1	Interrupt mask for ALC Threshold 0 = Not masked 1 = Masked
	10	IM_ALC_SAT_ EINT	1	Interrupt mask for ALC Saturation 0 = Not masked 1 = Masked
	9	IM_ALC_ PKOVR_EINT	1	Interrupt mask for ALC Peak Detector overload  0 = Not masked  1 = Masked
	8	IM_ALC_NGATE _EINT	1	Interrupt mask for ALC Noise Gate active 0 = Not masked 1 = Masked
	7	IM_WSEQ_ DONE_EINT	1	Interrupt mask for Write Sequencer done 0 = Not masked 1 = Masked
	6	IM_DRC_ ACTDET_EINT	1	Interrupt mask for DRC Activity detect 0 = Not masked 1 = Masked
	5	IM_FLL_LOCK_EINT	1	Interrupt mask for FLL Lock 0 = Not masked 1 = Masked
	4	Reserved	1	Reserved - do not change
	3	Reserved	1	Reserved - do not change
	2	Reserved	1	Reserved - do not change
	1	Reserved	1	Reserved - do not change
	0	IM_TEMP_ SHUT_EINT	1	Interrupt mask for Temperature Shutdown 0 = Not masked 1 = Masked

Register 0239h Interrupt Status 2 Mask

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R576 (0240h) Interrupt Control	0	IRQ_POL	0	Interrupt Output polarity  0 = Active high  1 = Active low

Register 0240h Interrupt Control



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R584 (0248h) IRQ Debounce	5	FLL_LOCK_DB	1	Debounce Enable on FLL Lock 0 = Disabled 1 = Enabled
	4	Reserved	1	Reserved - do not change
	3	Reserved	1	Reserved - do not change
	2	Reserved	1	Reserved - do not change
	1	Reserved	1	Reserved - do not change
	0	TEMP_SHUT_DB	1	Debounce Enable on Temperature Shutdown 0 = Disabled 1 = Enabled

Register 0248h IRQ Debounce

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R586 (024Ah) MICINT Source Pol	15	MICSCD_IRQ_ POL	0	Mic Short Circuit Interrupt Polarity 0 = Active high (IRQ asserted when MICSHORT_THR is exceeded) 1 = Active low (IRQ asserted when MICSHORT_THR not exceeded)
	14	MICD_IRQ_POL	0	Mic Detect Interrupt Polarity  0 = Active high (IRQ asserted when MICDET_THR is exceeded)  1 = Active low (IRQ asserted when MICDET_THR not exceeded)

Register 024Ah MICINT Source Pol

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R768 (0300h) DSP2 Power Management	0	DSP2_ENA	0	DSP2 Audio Processor Enable.  0 = Disabled  1 = Enabled  This bit must be set before any of DAC ReTune, DAC HPF,  VSS or MBC is enabled. It must remain set whenever any of these functions is enabled.

Register 0300h DSP2 Power Management

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R1037	5	DSP2_STOPC	0	[No description available]
(040Dh)	4	DSP2_STOPS	0	[No description available]
DSP2_ ExecControl	3	DSP2_STOPI	0	[No description available]
ZXCCCINIO	2	DSP2_STOP	0	Stop the DSP2 audio processor. Writing a 1 to this bit will cause the DSP2 processor to stop processing audio data.
	1	DSP2_RUNR	0	Start the DSP2 audio processor Writing a 1 to this bit will cause the DSP2 processor to start processing audio data
	0	DSP2_RUN	0	[No description available]

Register 040Dh DSP2\_ExecControl



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4096 (1000h) Write Sequencer 0	13:0	WSEQ_ADDR0 [13:0]	00_0000_ 0001_1100	Control Register Address to be written to in this sequence step.

Register 1000h Write Sequencer 0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4097 (1001h) Write Sequencer 1	7:0	WSEQ_DATA0 [7:0]	0000_0011	Data to be written in this sequence step. When the data width is less than 8 bits, then one or more of the MSBs of WSEQ_DATAn are ignored. It is recommended that unused bits be set to 0.

Register 1001h Write Sequencer 1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4098 (1002h) Write Sequencer 2	10:8	WSEQ_DATA_ WIDTH0 [2:0]	001	Width of the data block written in this sequence step.  000 = 1 bit  001 = 2 bits  010 = 3 bits  011 = 4 bits  100 = 5 bits  101 = 6 bits  110 = 7 bits  111 = 8 bits
	3:0	WSEQ_DATA_ START0 [3:0]	0011	Bit position of the LSB of the data block written in this sequence step.  0000 = Bit 0  1111 = Bit 15

Register 1002h Write Sequencer 2

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4099 (1003h) Write Sequencer 3	8	WSEQ_EOS0	0	End of Sequence flag. This bit indicates whether the Control Write Sequencer should stop after executing this step.  0 = Not end of sequence  1 = End of sequence (Stop the sequencer after this step).
	3:0	WSEQ_DELAY0 [3:0]	0000	Time delay after executing this step.  Total time per step (including execution)  = k x (2^WSEQ_DELAY + 8)  k = 62.5µs (SAMPLE_RATE_INT_MODE = 1),  k = 68.1µs (SAMPLE_RATE_INT_MODE = 0),

Register 1003h Write Sequencer 3



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R4100 (1004h) Write Sequencer 4				[Write Sequencer Control Registers]
То				
R4607 (11FFh) Write Sequencer 511				

Register 1004h Write Sequencer 4 to Register 11FFh Write Sequencer 511

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16386 (4002h) RETUNEDAC_ SHARED_	7	DAC_RETUNE_SCV	0	DAC ReTune Coefficient sharing 0 = Left and Right channels each use unique coefficients 1 = Both channels use the Right Channel coefficients
COEFF_1	6:0	RETUNEDAC _SHARED_COEFF_ 23_16 [6:0]	000_0000	[No description available]

Register 4002h RETUNEDAC\_SHARED\_COEFF\_1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16387 (4003h) RETUNEDAC_ SHARED_ COEFF_0	15:0	RETUNEDAC_ SHARED_COEFF_ 15_00 [15:0]	0000_0000_ 0000_0000	[No description available]

Register 4003h RETUNEDAC\_SHARED\_COEFF\_0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16388 (4004h) SOUNDSTAGE_ ENABLES_1	7:0	SOUNDSTAGE_ ENABLES_23_ 16 [7:0]	0000_0000	[No description available]

Register 4004h SOUNDSTAGE\_ENABLES\_1

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16389 (4005h) SOUNDSTAGE_ ENABLES_0	15:6	SOUNDSTAGE_ ENABLES_15_06 [9:0]	00_0000_000	[No description available]
	4	RTN_DAC_ENA	0	DAC ReTune enable 0 = Disabled 1 = Enabled
	3	MBC_ENA	0	MBC Enable 0 = Disabled 1 = Enabled



REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
	2	HPF2_ENA	0	High-Pass Filter (HPF2) enable 0 = Disabled 1 = Enabled
	1	HPF1_ENA	0	High-Pass Filter (HPF1) enable 0 = Disabled 1 = Enabled
	0	VSS_ENA	0	Virtual Surround Sound (VSS) enable 0 = Disabled 1 = Enabled

Register 4005h SOUNDSTAGE\_ENABLES\_0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R16896 (4200h) MBC Band 1 K (1)				[MBC Control Registers]
То				
R16955 (423Bh) MBC RMS Limit (2)				

Register 4200h MBC Band 1 K (1) to Register 423Bh MBC RMS Limit (2)

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R17408 (4400h) HPF_C_1				[DAC High Pass Filter Control Registers]
То				
R17409 (4401h) HPF_C_0				

Register 4400h HPF\_C\_1 to Register 4401h HPF\_C\_0

REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R17920 (4600h) DACL_RETUNE _C1_1				[DAC ReTune Control Registers]
То				
R19007 (4A3Fh) DACR_RETUNE				
C32_0				

Register 4600h DACL\_RETUNE\_C1\_1 to Register 4A3Fh DACR\_RETUNE\_C32\_0





REGISTER ADDRESS	BIT	LABEL	DEFAULT	DESCRIPTION
R19456 (4C00h) VSS_XHD2_1				[VSS Control Registers]
То				
R19603 (4C93h) VSS_XTS32_0				

Register 4600h DACL\_RETUNE\_C1\_1 to Register 4C93h VSS\_XTS32\_0



# **DIGITAL FILTER CHARACTERISTICS**

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
ADC Filter	•				
Passband				0.454 fs	
	-3dB		0.5 fs		
Passband Ripple	f < 0.454 fs			+/- 0.05	dB
Stopband		0.546 fs			
Stopband Attenuation	f > 0.546 fs	60			dB
DAC Normal Filter	•				
Passband				0.454 fs	
	-6dB		0.5 fs		
Passband Ripple	f < 0.454 fs			+/- 0.05	dB
Stopband		0.546 fs			
Stopband Attenuation	0.546 fs < f < 30 fs	50			dB
DAC Sloping Stopband Filte	r				
Passband				0.454 fs	
	-9dB		0.5 fs		
Passband Ripple	f < 0.25 fs			+/- 0.05	dB
	0.25 fs < f < 0.454 fs			+/- 1	
Stopband 1		0.546 fs		0.7 fs	
Stopband 1 Attenuation	f > 0.546 fs	60			dB
Stopband 2		0.7 fs		1.4 fs	
Stopband 2 Attenuation	f > 0.7 fs	85			dB
Stopband 3		1.4 fs			
Stopband 3 Attenuation	1.4 fs < f < 30 fs	53			dB

DAC FI	LTERS	ADC FILTERS			
Mode	Group Delay	Mode Group Delay			
Normal	16.5 / fs	Normal	15 / fs		
Sloping Stopband	18 / fs				

## **TERMINOLOGY**

- 1. Stop Band Attenuation (dB) the degree to which the frequency spectrum is attenuated (outside audio band)
- 2. Pass-band Ripple any variation of the frequency response in the pass-band region

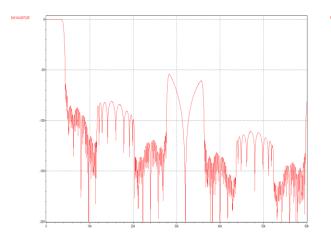


## **DAC FILTER RESPONSES**

This series of plots shows the filter response for the entire DAC channel for different signal rates. The full path, has a nominal gain of 3.01dB (1V input, 1.414V output), this means that the highest nodes in the 48kHz case are at 47.5dB (rather than below the 50dB specification).

SAMPLE RATE (KHZ)	SLOPING STOP-BAND	MCLK RECOMMENDED RATE FOR DAC ONLY PLAYBACK (CODEC MODE) (HZ)
8	Yes	3072000 (3072000)
11.025	Yes	2822400 (2822400)
12	Yes	3072000 (3072000)
16	Yes	2048000 (6144000)
22.05	Yes	2822400 (5644800)
24	Yes	3072000 (6144000)
32	No	2048000 (8192000)
44.1	No	2822400 (11289600)
48	No	3072000 (12288000)

**Table 127 Recommended Filter Configurations for Supported Sample Rates** 



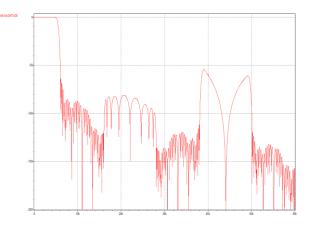
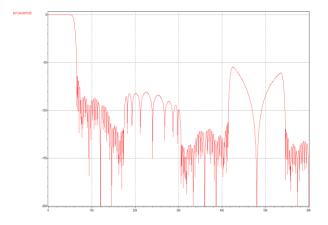


Figure 74 DAC Filter Response 8k Sampling Rate

Figure 75 DAC Filter Response for 11.025k Sample Rate



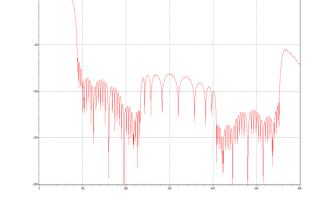
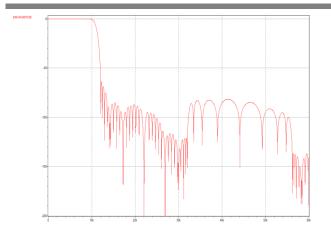


Figure 76 DAC Filter Response for 12k Sample Rate

Figure 77 DAC Filter Response for 16k Sample Rate





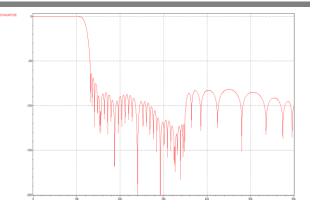
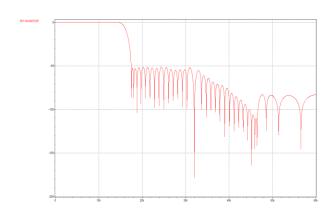


Figure 78 DAC Filter Response 22.05k Sample Rate

Figure 79 DAC Playback Filter Response for 24k Sample Rate



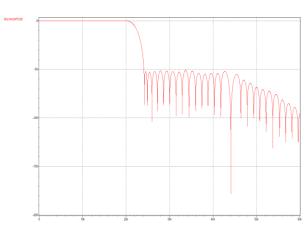
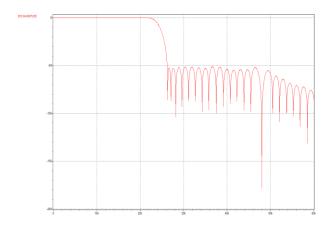


Figure 80 DAC Playback Filter Response for 32k Sample Rate

Figure 81 DAC Playback Filter Response for 44.1k Sample Rate



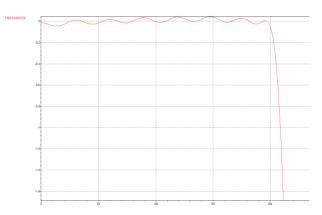


Figure 82 DAC Playback Filter Response for 48k Sample Rate

Figure 83 DAC Playback Filter Passband Ripple for 44.1k Sample Rate (MCLK=11.2896MHZ)



# **ADC FILTER RESPONSES**

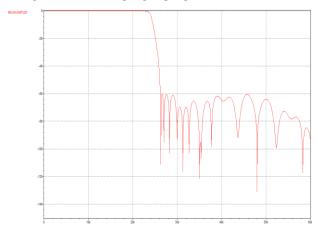


Figure 84 ADC Digital Filter Frequency Response (128OSR)

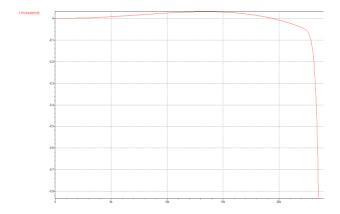


Figure 85 ADC Digital Filter Passband Ripple (128OSR)



#### **ADC HIGH PASS FILTER RESPONSES**

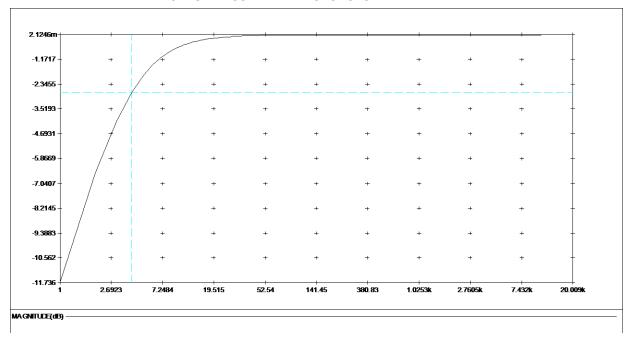


Figure 86 ADC Digital High Pass Filter Frequency Response (48kHz, Hi-Fi Mode, ADC\_HPF\_CUT[1:0]=00)

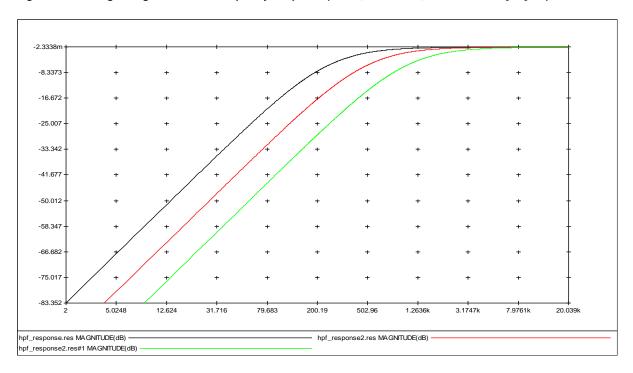
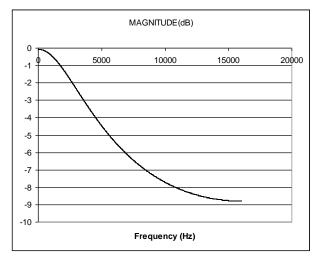


Figure 87 ADC Digital High Pass Filter Ripple (48kHz, Voice Mode, ADC\_HPF\_CUT=01, 10 and 11)



## **DE-EMPHASIS FILTER RESPONSES**



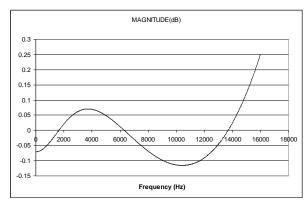


Figure 88 De-Emphasis Digital Filter Response (32kHz)

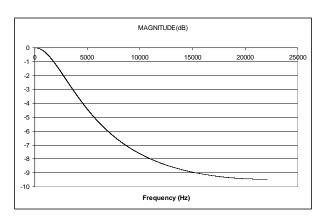


Figure 89 De-Emphasis Error (32kHz)

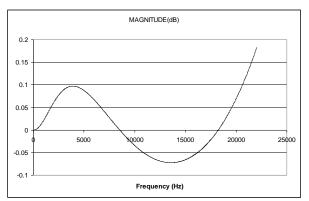


Figure 90 De-Emphasis Digital Filter Response (44.1kHz)

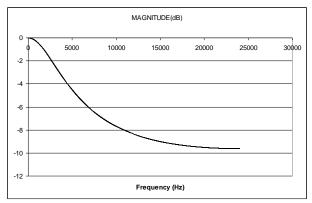
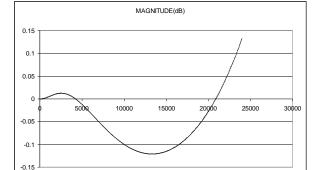


Figure 92 De-Emphasis Digital Filter Response (48kHz)



Frequency (Hz)

Figure 93 De-Emphasis Error (48kHz)

Figure 91 De-Emphasis Error (44.1kHz)



#### APPLICATIONS INFORMATION

#### RECOMMENDED EXTERNAL COMPONENTS

#### **ANALOGUE INPUT PATHS**

The WM8963 provides up to 8 analogue audio input paths. Each of these inputs is referenced to the internal DC reference, VMID. A DC blocking capacitor is required for each analogue input pin used in the target application. The choice of capacitor is determined by the filter that is formed between that capacitor and the impedance of the input pin. The circuit is illustrated in Figure 94.

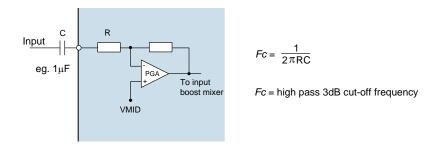


Figure 94 Audio Input Path DC Blocking Capacitor

In accordance with the WM8963 input pin resistance, it is recommended that a  $1\mu F$  capacitance will give good results in most cases. Note that the input impedance, R, changes with the PGA gain setting, as described in the "Electrical Characteristics".

A single capacitor is required for line or microphone input connection. Tantalum electrolytic capacitors are particularly suitable as they offer high stability in a small package size.

Ceramic equivalents are a cost effective alternative to the superior tantalum packages, but care must be taken to ensure the desired capacitance is maintained at the AVDD operating voltage. Also, ceramic capacitors may show microphonic effects, where vibrations and mechanical conditions give rise to electrical signals. This is particularly problematic for microphone input paths where a large signal gain is required.

The external connections for electret condenser microphones, incorporating the WM8963 microphone bias circuit, are shown later in the "Microphone Bias Circuit" section below.

#### **MICROPHONE BIAS CIRCUIT**

The WM8963 is designed to interface easily with analogue microphones. An electret condenser microphone (ECM) requires a bias current; this can be provided by the MICBIAS output on the WM8963.

An electret condenser microphone may be connected in single-ended configuration, as illustrated in Figure 95.

A decoupling capacitor is required on the MICBIAS output. A suitable capacitor must be connected whenever the MICBIAS output is enabled.

A current-limiting resistor is also required for the ECM; the resistance should be chosen according to the minimum operating impedance of the microphone and MICBIAS voltage so that the maximum bias current of the WM8963 is not exceeded.

A  $2.2k\Omega$  current-limiting resistor is recommended; this provides compatibility with a wide range of microphone components.

Note that the MICBIAS output can also be used to power an analogue silicon microphone. In this case, the MICBIAS connects directly to the VDD pin of the microphone - a current-limiting resistor is not required in this case.

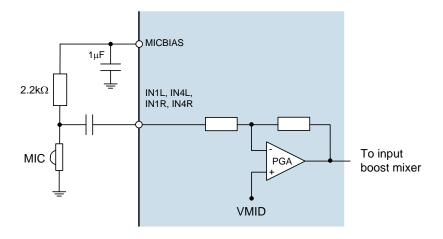


Figure 95 Single Ended Microphone Connection

Additional filtering of the MICBIAS output, to reduce noise and interference, may be implemented using the configuration illustrated in Figure 96.

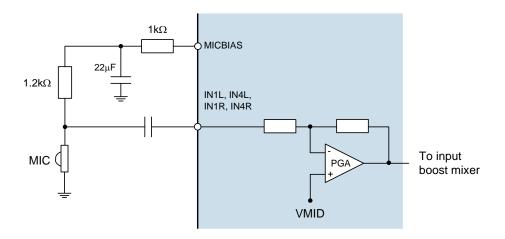


Figure 96 Microphone Connection, with MICBIAS Filter Components



#### INTERNAL LDO FOR MICBIAS CIRCUIT

The WM8963 provides an internal LDO regulator, which can be used to generate a suitable MICVDD supply for the MICBIAS generator. The LDO supply is provided via the LDOVDD pin. The LDO input is suitable for direct connection to a battery.

When the LDO is used to generate the MICVDD supply, there should be no external connections to the MICVDD pin. The recommended connections are illustrated in Figure 97.

The LDOVDD supply voltage must be at least 250mV higher than the desired MICVDD output voltage.

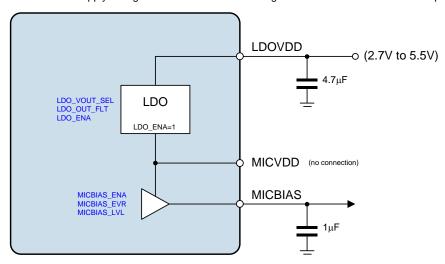


Figure 97 LDO Connection for MICBIAS

When the LDO is not used, then the MICVDD and LDOVDD pins should be tied together, and connected to a suitable MICVDD supply. The recommended connections are illustrated in Figure 98.

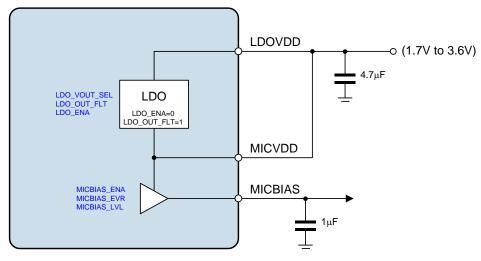


Figure 98 LDO Connections (LDO not used)



#### **CHARGE PUMP COMPONENTS**

The WM8963 incorporates a Charge Pump circuit, which generates the CPVOUTP and CPVOUTN supply rails for the ground-referenced headphone drivers.

Decoupling capacitors are required on each of the Charge Pump outputs. A fly-back capacitor is also required. The recommended Charge Pump capacitors for WM8963 are detailed below in Table 128.

DESCRIPTION	CAPACITOR
CPVOUTP decoupling	Required capacitance is 2.0μF at 2V. Suitable component typically 4.7μF.
CPVOUTN decoupling	Required capacitance is 2.0μF at 2V. Suitable component typically 4.7μF.
Charge Pump fly-back (connect between CPCA and CPCB)	Required capacitance is 1.0μF at 2V. Suitable component typically 2.2μF.

**Table 128 Charge Pump External Capacitors** 

Ceramic capacitors are recommended for these Charge Pump requirements. Note that, due to the wide tolerance of many types of ceramic capacitors, care must be taken to ensure that the selected components provide the required capacitance across the required temperature and voltage ranges in the intended application. Ceramic capacitors with X5R dielectric are recommended.

The positioning of the Charge Pump capacitors is important, particularly the fly-back capacitors. These capacitors should be placed as close as possible to the WM8963.



#### SPKVDD2 LDOVDD DBVDD CPVDD AVDD AGND DGND CPGND AVDD SPKGND1 DBVDD SPKGND2 DCVDD CPVDD VMIDC SPKVDD1 SPKVDD2 LDOVDD 4.7μF 0.1μF 0.1μ**F** 4.7μF Note: No connection to MICVDD when LDO is enabled. MICVDD O MICVDD should be connected to LDOVDD when LDO is not used. MICBIAS SCLK Control Interface CIFMODE MCLK/XTI CS/GPI06 Crystal Oscillator хто 24MHz BCLK HPOUTFB\* LRCLK HPOUT1R Headset Audio Interface WM8963 DACDAT HPOUT1L ADCDAT 0.1μF 0.1μF (Note: HPOUTFB ground connection close to headset jack) 200 200 GPIO / CLKOUT2/GPIO2 OSCENA/GPIO5 HPOUTFB\* CLKOUT5 HPOUT2R Headset Note that GPIO5 must be in a defined HPOUT2L state (logic '0' or logic '1') during start-up; it must not be left floating. 0.1μF 0.1μF (Note: HPOUTFB ground 20Ω \* The HPOUTFB pin is common to HPOUT1 and HPOUT2 outputs $1\mu\text{F}$ SPKOUTLN Loudspeaker SPKOUTLP Analogue Audio (Mic / Line) Inputs SPKOUTRN Loudspeaker SPKOUTRP CPCA СРСВ CPVOUTN CPVOUTP Note that the optimum input capacitance will vary according to the required frequency response and the applicable input impedance.

RECOMMENDED EXTERNAL COMPONENTS DIAGRAM

Figure 99 WM8963 Recommended External Components



#### Notes:

#### 1. Power Supply Decoupling Capacitors

X5R ceramic capacitor is recommended for the power supply decoupling capacitors.

The decoupling capacitors on VMIDC, MICBIAS, CPVOUTP and CPVOUTN should be as close to the WM8963 as possible.

#### 2. Charge Pump Capacitors

Specific recommendations for Charge Pump capacitors are provided in Table 129. Note that two different recommendations are provided for CPVOUTP and CPVOUTN; either of these components is suitable, depending upon size requirements and availability.

The positioning of the flyback capacitor is very important - this should be as close to the WM8963 as possible.

It is important to select a suitable capacitor type for the Charge Pump. Note that the capacitance may vary with DC voltage; care is required to ensure that required capacitance is achieved at the applicable operating voltage, as specified in Figure 99. The capacitor datasheet should be consulted for this information.

COMPONENT	REQUIRED CAPACITANCE	VALUE	PART NUMBER	VOLTAGE	TYPE	SIZE
Charge Pump Flyback (CPCA to CPCB)	≥ 1µF at 2VDC	2.2μF	Kemet C0402C225M9PAC	6.3v	X5R	0402
CPVOUTN		2.2μF	MuRata GRM188R61A225KE34D	10v	X5R	0603
decoupling, CPVOUTP decoupling	≥ 2µF at 2VDC	4.7μF	MuRata GRM155R60J475M_EIA	6.3v	X5R	0402

**Table 129 Charge Pump Capacitors** 

#### 3. Zobel Networks

The Zobel network shown in Figure 99 is required on HPOUT1L, HPOUT1R, HPOUT2L and HPOUT2R whenever that output is enabled. Stability of these ground-referenced outputs across all process corners cannot be guaranteed without the Zobel network components. (Note that, if any ground-referenced output pin is not required, the Zobel network components can be omitted from the output pin, and the pin can be left floating.) The Zobel network requirement is detailed further in the applications note WAN\_0212 "Class W Headphone Impedance Compensation".

Zobel networks should be positioned reasonably close to the WM8963.

#### 4. AGND Connections

The AGND connections must be tied together as close as possible to the WM8963.



## **PCB LAYOUT CONSIDERATIONS**

Poor PCB layout will degrade the performance and be a contributory factor in EMI, ground bounce and resistive voltage losses. All external components should be placed as close to the WM8963 device as possible, with current loop areas kept as small as possible.

The following layout priorities should be observed. (All these components should be as close to the WM8963 as possible; item 1. is the highest priority).

- 1. Charge pump capacitors
- 2. AVDD, DCVDD, DBVDD decoupling
- 3. VMIDC, MICBIAS decoupling
- 4. Other decoupling
- 5. Zobel network components



#### MIC DETECTION SEQUENCE USING MICBIAS CURRENT

This section details an example sequence which summarises how the host processor can configure and detect the events supported by the MICBIAS current detect function.

- Mic insertion/removal
- · Hook switch press/release

Figure 100 shows an example of how the MICBIAS current flow varies versus time, during mic insertion and hook switch events. The Y axis is annotated with the Mic detection thresholds, and the X axis is annotated with the stages of an example sequence as detailed in Table 130, to illustrate how the host processor can implement mic insertion and hook switch detection.

The sequence assumes that the microphone insertion and hook switch detection functions are monitored by polling the interrupt flags using the control interface. Note that the maximum mechanical bounce times for mic insertion and removal must be fully understood by the software programmer.

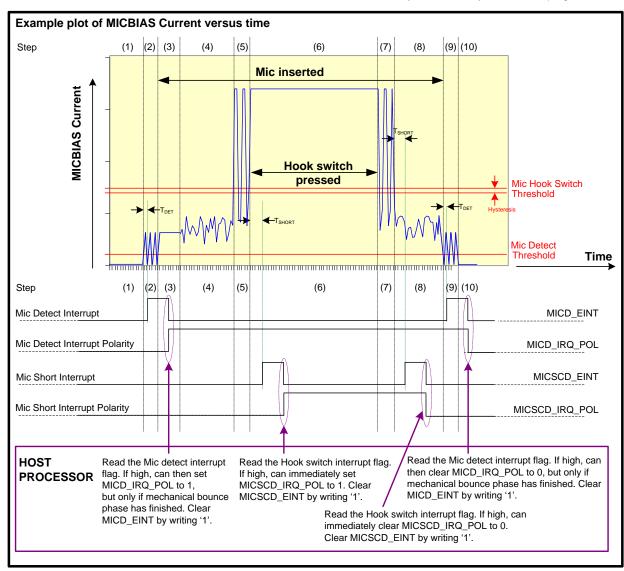


Figure 100 Mic Insert and Hook Switch Detect: Example MICBIAS Current Plot

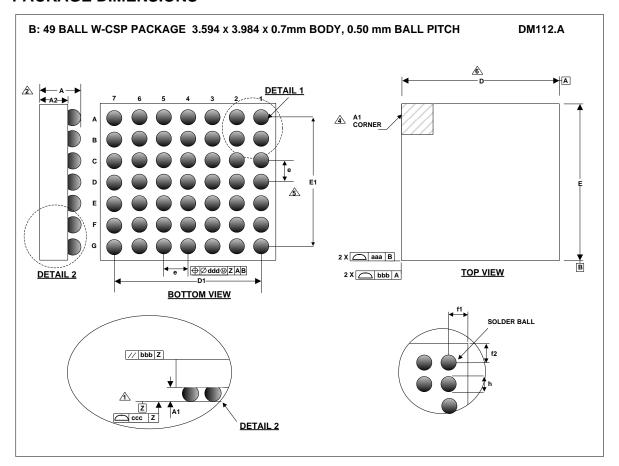


STEP	DETAILS					
1	Mic not inserted. To detect mic insertion, Host processor must initialise interrupts and clear MICD_IRQ_POL = 0. At every step, the host processor should poll the interrupt status register.					
	Note that Mic Insertion de-bounce circuitry is automatically enabled.					
2	Mechanical bounce of jack socket during Mic insertion. Host processor may already detect a mic insertion interrupt (MICD_EINT) during this step. Once detected, the host processor can set MICD_IRQ_POL = 1 and then clear the interrupt, unless mechanical bounce can last longer than the shortest possible T <sub>DET</sub> , in which case the host processor should wait until step 3.					
3	Mic fully inserted. If not already set, the host processor must now set MICD_IRQ_POL = 1. If not already cleared, the host processor must now clear the MICD_EINT interrupt. To detect Hook switch press, the host processor must clear MICSCD_IRQ_POL = 0. At this step, the diagram shows no AC current swing, due to a very low ambient noise level.					
4	Mic fully inserted. Diagram shows AC current swing due to high levels of background noise (such as wind).					
5	Mechanical bounce during hook switch press. The hook switch interrupt is unlikely to be set during this step, because 10 successive samples of the MICBIAS current exceeding the hook switch threshold have not yet been sampled.  Note that Hook Switch de-bounce circuitry is automatically enabled.					
6	Hook switch is fully pressed down. After T <sub>SHORT</sub> , 10 successive samples of the MICBIAS current exceeding the hook switch threshold have been detected, hence a hook switch interrupt (MISCD_EINT) will be generated. Once detected, the host processor can immediately set MICSCD_IRQ_POL = 1 and then clear the MICSCD_EINT interrupt.					
7	Mechanical bounce during hook switch release. The hook switch interrupt is unlikely to be set during this step, because 10 successive samples of the MICBIAS current lower than the hook switch threshold have not yet been sampled.					
8	Hook switch fully released. After T <sub>SHORT</sub> , 10 successive samples of the MICBIAS current lower than the hook switch threshold have been detected, hence a hook switch interrupt (MICSCD_EINT) will be generated. Once detected, the host processor can immediately clear MICSCD_IRQ_POL = 0 and then clear the MICSCD_EINT interrupt.					
9	Mechanical bounce of jack socket during Mic removal. Host processor may already detect a mic removal interrupt (MICD_EINT) during this step. Once detected, the host processor can clear MICD_IRQ_POL = 0 and then clear the interrupt, unless mechanical bounce can last longer than the shortest possible T <sub>DET</sub> , in which case the host processor should wait until step 10.					
10	Mic fully removed. If not already cleared, the host processor must now clear MICD_IRQ_POL = 0. If not already cleared, the host processor must now clear the MICD_EINT interrupt.					

Table 130 Mic Insert and Hook Switch Detect: Example Sequence



## **PACKAGE DIMENSIONS**



Symbols	Dimensions (mm)					
	MIN	NOM	MAX	NOTE		
Α	0.661	0.700	0.739			
A1	0.207	0.244	0.281			
A2	0.443	0.456	0.469			
D	3.569	3.594	3.619			
D1		3.00 BSC				
E	3.959	3.984	4.009			
E1		3.00 BSC				
е		0.50 BSC		5		
f1	0.285					
f2	0.480					
h	0.264	0.314	0.364			
aaa		0.025				
bbb		0.060				
ccc		0.030				
ddd		0.015				

- NOTES:

  1. PRIMARY DATUM -Z- AND SEATING PLANE ARE DEFINED BY THE SPHERICAL CROWNS OF THE SOLDER BALLS.

  2. THIS DIMENSION INCLUDES STAND-OFF HEIGHT 'A1' AND BACKSIDE COATING.

  3. AT CORNER IS IDENTIFIED BY INKLASER MARK ON TOP PACKAGE.

  4. BILATERAL TOLERANCE ZONE IS APPLIED TO EACH SIDE OF THE PACKAGE BODY.

  5. 'e' REPRESENTS THE BASIC SOLDER BALL GRID PITCH.

  6. THIS DRAWING IS SUBJECT TO CHANGE WITHOUT NOTICE.

  7. FOLLOWS JEDEC DESIGN GUIDE MO-211-C.



#### IMPORTANT NOTICE

# **Contacting Cirrus Logic Support**

For all product questions and inquiries, contact a Cirrus Logic Sales Representative. To find one nearest you, go to www.cirrus.com.

The products and services of Cirrus Logic International (UK) Limited; Cirrus Logic, Inc.; and other companies in the Cirrus Logic group (collectively either "Cirrus Logic" or "Cirrus") are sold subject to Cirrus Logic's terms and conditions of sale supplied at the time of order acknowledgment, including those pertaining to warranty, indemnification, and limitation of liability. Software is provided pursuant to applicable license terms. Cirrus Logic reserves the right to make changes to its products and specifications or to discontinue any product or service without notice. Customers should therefore obtain the latest version of relevant information from Cirrus Logic to verify that the information is current and complete. Testing and other quality control techniques are utilized to the extent Cirrus Logic deems necessary. Specific testing of all parameters of each device is not necessarily performed. In order to minimize risks associated with customer applications, the customer must use adequate design and operating safeguards to minimize inherent or procedural hazards. Cirrus Logic is not liable for applications assistance or customer product design. The customer is solely responsible for its selection and use of Cirrus Logic products. Use of Cirrus Logic products may entail a choice between many different modes of operation, some or all of which may require action by the user, and some or all of which may be optional. Nothing in these materials should be interpreted as instructions or suggestions to choose one mode over another. Likewise, description of a single mode should not be interpreted as a suggestion that other modes should not be used or that they would not be suitable for operation. Features and operations described herein are for illustrative purposes only.

CERTAIN APPLICATIONS USING SEMICONDUCTOR PRODUCTS MAY INVOLVE POTENTIAL RISKS OF DEATH, PERSONAL INJURY, OR SEVERE PROPERTY OR ENVIRONMENTAL DAMAGE ("CRITICAL APPLICATIONS"). CIRRUS LOGIC PRODUCTS ARE NOT DESIGNED, AUTHORIZED OR WARRANTED FOR USE IN PRODUCTS SURGICALLY IMPLANTED INTO THE BODY, AUTOMOTIVE SAFETY OR SECURITY DEVICES, NUCLEAR SYSTEMS, LIFE SUPPORT PRODUCTS OR OTHER CRITICAL APPLICATIONS. INCLUSION OF CIRRUS LOGIC PRODUCTS IN SUCH APPLICATIONS IS UNDERSTOOD TO BE FULLY AT THE CUSTOMER'S RISK AND CIRRUS LOGIC DISCLAIMS AND MAKES NO WARRANTY, EXPRESS, STATUTORY OR IMPLIED, INCLUDING THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR PARTICULAR PURPOSE, WITH REGARD TO ANY CIRRUS LOGIC PRODUCT THAT IS USED IN SUCH A MANNER. IF THE CUSTOMER OR CUSTOMER'S CUSTOMER USES OR PERMITS THE USE OF CIRRUS LOGIC PRODUCTS IN CRITICAL APPLICATIONS, CUSTOMER AGREES, BY SUCH USE, TO FULLY INDEMNIFY CIRRUS LOGIC, ITS OFFICERS, DIRECTORS, EMPLOYEES, DISTRIBUTORS AND OTHER AGENTS FROM ANY AND ALL LIABILITY, INCLUDING ATTORNEYS' FEES AND COSTS, THAT MAY RESULT FROM OR ARISE IN CONNECTION WITH THESE USES.

This document is the property of Cirrus Logic and by furnishing this information, Cirrus Logic grants no license, express or implied, under any patents, mask work rights, copyrights, trademarks, trade secrets or other intellectual property rights. Any provision or publication of any third party's products or services does not constitute Cirrus Logic's approval, license, warranty or endorsement thereof. Cirrus Logic gives consent for copies to be made of the information contained herein only for use within your organization with respect to Cirrus Logic integrated circuits or other products of Cirrus Logic, and only if the reproduction is without alteration and is accompanied by all associated copyright, proprietary and other notices and conditions (including this notice). This consent does not extend to other copying such as copying for general distribution, advertising or promotional purposes, or for creating any work for resale. This document and its information is provided "AS IS" without warranty of any kind (express or implied). All statutory warranties and conditions are excluded to the fullest extent possible. No responsibility is assumed by Cirrus Logic for the use of information herein, including use of this information as the basis for manufacture or sale of any items, or for infringement of patents or other rights of third parties. Cirrus Logic, Cirrus, the Cirrus Logic logo design, SoundClear, WISCE, ReTune, and SilentSwitch are among the trademarks of Cirrus Logic. Other brand and product names may be trademarks or service marks of their respective owners.

Copyright © 2013-2016 Cirrus Logic, Inc. All rights reserved.

SPI is a trademark of Motorola.



# **REVISION HISTORY**

DATE	REV	DESCRIPTION OF CHANGES	PAGE	CHANGED BY
23/05/13	2.0	First Release		PH
28/08/13	3.0	Recommended operating conditions updated regarding AVDD, DCVDD, CPVDD constraints when device is powered down.  LDO requirements updated, to ensure MICVDD is not left floating.  Electrical Characteristics updated.  Input mixer to Speaker mixer gain controls updated.		PH
20/02/14	4.0	Minimum DCVDD for restricted clocking configurations changed to 1.7V.  Maximum current consumption figures updated.  Electrical Characteristics updated.  Amendments to recommended DSP control sequences.  Additional requirements for writing 24-bit DSP configuration registers.  Digital Core block diagram updated, consistent with ADC Enhancements functions (Second Order Filter is included within ADC Enhancements).		PH
22/07/14	4.1	DF1 filter as input to DRC is deleted	67, 79, 80, 96	PH
13/01/16	4.1	Minimum MICVDD requirements amended	18, 36	PH
05/08/16	4.2	Correction to OSC_TRIM_XTI and OSC_TRIM_XTO field definitions	159	PH