



XTR60010

High Temperature Crystal Oscillator Driver

Rev 3 – August 2021 (DS-00228-12)

Data Sheet



PRODUCTION



DIP8
XTR60012



DIP16
XTR60011



FEATURES

- Supply voltage from 2.5V to 5.5V.
- Operational beyond the -60°C to +230°C temperature range.
- Monolithic crystal oscillator driver controller.
- Operational from 32kHz to 25MHz.
- Automatically adapts to used crystal.
- Integrated capacitors for reduced Bill-of-Material
- Selectable low-power mode.
- Selectable 1/128 prescaler.
- Programmable Freq/1, Freq/2, Freq/4, Freq/8 divider.
- Stand-by functionality with output buffer in High-Z state.
- Separate oscillator and buffer supply pins for low-noise operation.
- Latch-up free.
- Ruggedized SMT and thru-hole packages.
- Also available as bare die.

APPLICATIONS

- Reliability-critical, Automotive, Aeronautics & Aerospace, Down-hole.
- Crystal oscillators, clock generation, time-base generator, precision timing.

DESCRIPTION

XTR60010 is a family of small footprint high-temperature, extended lifetime crystal oscillator drivers offering extended functional features and designed for extreme reliability applications such as crystal oscillators, clock and time-base generators. Being able to operate from supply voltages from 2.5V to 5.5V, the XTR60010 crystal oscillator driver can operate with crystals from 32kHz to 25MHz.

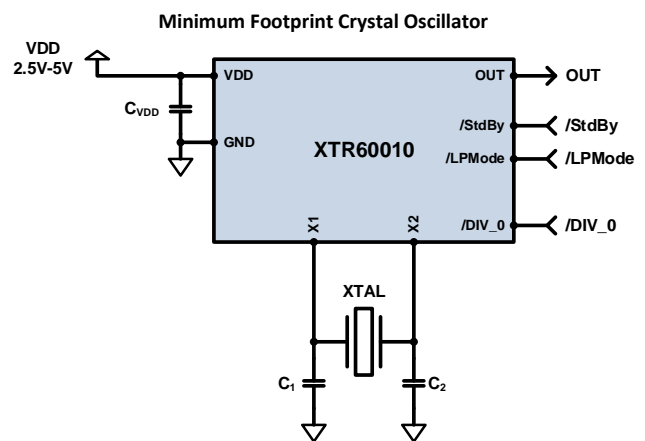
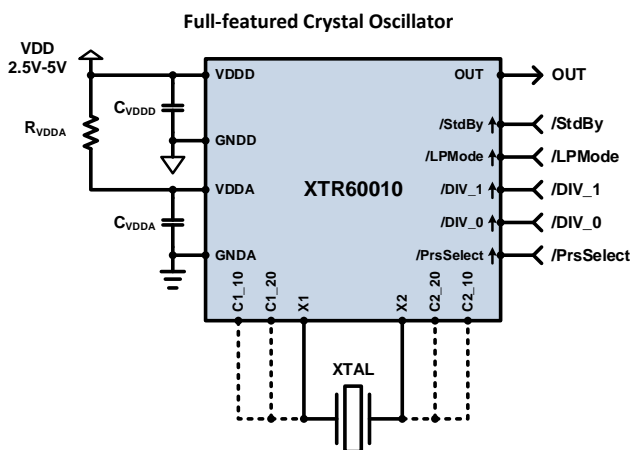
Functionality features include selectable prescaler (1/128), programmable frequency divider (1/2/4/8), operation in low-power mode for low frequency crystals, integrated capacitors for crystal loading and stand-by mode which stops oscillations and sets the output buffer to the high-Z state. Using the internal prescaler and frequency divider, division factors from 1 to 1024 can be obtained. The internal crystal driver has automatic gain control to be able to accommodate to the used crystal, with no intervention needed from the customer, as required by some competing products.

Special design techniques were used allowing the XTR60010 parts to offer a precise, robust and reliable operation in critical applications. Full functionality is guaranteed from -60°C to +230°C, though operation well below and above this temperature range is achieved.

XTR60010 family parts have been designed to reduce system cost and ease adoption by reducing the learning curve and providing smart and easy to use features.

Parts from the XTR60010 family are available in ruggedized SMT and thru-hole packages. Parts are also available as bare dies.

PRODUCT HIGHLIGHT



ORDERING INFORMATION



Product Reference	Temperature Range	Package	Pin Count	Marking
XTR60010-BD	-60°C to +230°C	Bare Die		
XTR60011-D	-60°C to +230°C	Ceramic side brazed DIP	16	XTR60011
XTR60012-D	-60°C to +230°C	Ceramic side brazed DIP	8	XTR60012

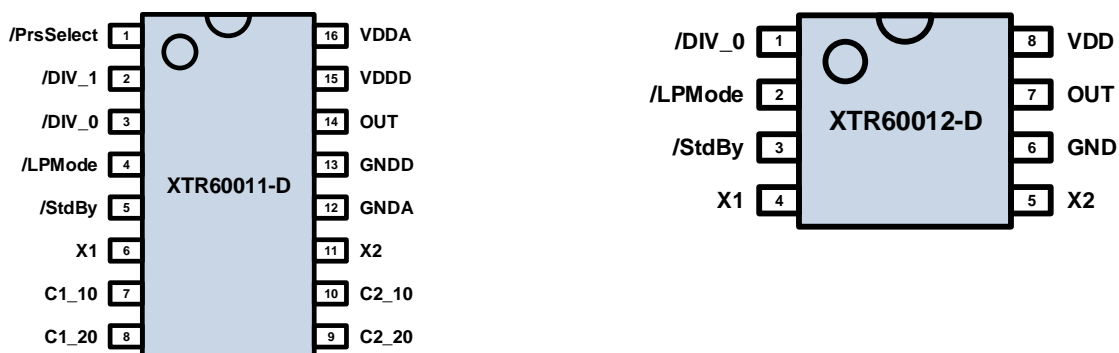
Other packages and packaging configurations possible upon request. For some packages or packaging configurations, MOQ may apply.

ABSOLUTE MAXIMUM RATINGS

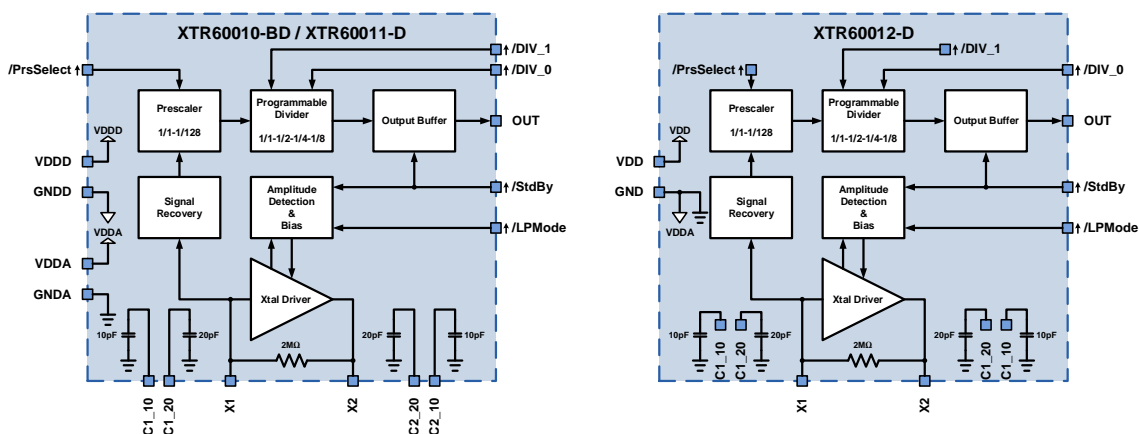
Voltage on VDDA and VDD to GNDA and GNDD	-0.5 to 6.0V
Voltage on any pin to GNDA or GNDD	-0.5 to 6.0V
Maximum difference VDDA - VDDD	0.5V
Maximum difference GNDA - GNDD	0.5V
Storage Temperature Range	-70°C to +230°C
Operating Junction Temperature Range	-70°C to +300°C
ESD Classification	2kV HBM MIL-STD-883

Caution: Stresses beyond those listed in "ABSOLUTE MAXIMUM RATINGS" may cause permanent damage to the device. These are stress ratings only and functionality of the device at these or any other condition beyond those indicated in the operational sections of the specifications is not implied. Exposure to "ABSOLUTE MAXIMUM RATINGS" conditions for extended periods may permanently affect device reliability.

PACKAGING



BLOCK DIAGRAM



Arrows aside pin names indicate whether the input is internally pulled up or down.

PADS DESCRIPTION

XTR60011		
Pin Number	Name	Description
1	/PrsSelect	Selects prescaler division (128) when driven LOW.
2	/DIV_1	MSB of internal programmable divider. Negative logic. See Function Table.
3	/DIV_0	LSB of internal programmable divider. Negative logic. See Function Table.
4	/LPMode	Sets low-power operation mode when driven LOW.
5	/StdBy	Sets stand-by mode (oscillation stopped and high impedance output) when driven LOW.
6	X1	Input of crystal driver. It can also be used as input of an external clock.
7	C1_10	Top plate of a ground referenced, internal 10pF capacitor. To be used as crystal load.
8	C1_20	Top plate of a ground referenced, internal 20pF capacitor. To be used as crystal load.
9	C2_20	Top plate of a ground referenced, internal 20pF capacitor. To be used as crystal load.
10	C2_10	Top plate of a ground referenced, internal 10pF capacitor. To be used as crystal load.
11	X2	Output of crystal driver.
12	GND A	Analog ground.
13	GND D	Digital and output buffer ground.
14	OUT	Oscillator output.
15	VDD D	Digital and output buffer supply voltage.
16	VDD A	Analog supply voltage.

XTR60012		
Pin Number	Name	Description
1	/DIV_0	Controls internal programmable divider. Divides by 2 when driven LOW.
2	/LPMode	Sets low-power operation mode when driven LOW.
3	/StdBy	Sets stand-by mode (oscillation stopped and high impedance output) when driven LOW.
4	X1	Input of crystal driver. It can also be used as input of an external clock.
5	X2	Output of crystal driver.
6	GND	Ground.
7	OUT	Oscillator output.
8	VDD	Supply voltage.

FUNCTION TABLE

/StdBy	/PrsSelect	/DIV_1	/DIV_0	Division Factor	OUT
0 (osc. stopped)	X	X	X	X	High Z
1	1	1	1	1	Freq
1	1	1	0	2	Freq/2
1	1	0	1	4	Freq/4
1	1	0	0	8	Freq/8
1	0	1	1	128	Freq/128
1	0	1	0	256	Freq/256
1	0	0	1	512	Freq/512
1	0	0	0	1024	Freq/1024

RECOMMENDED OPERATING CONDITIONS

Parameter	Min	Typ	Max	Units
Supply voltage V_{DDA}, V_{DDD} ¹	2.5 ²		5.5	V
Voltage on X1, X2, C1_xx and C2_xx to GNDA	0		V _{DDA}	V
Voltage on /DIV_0, /DIV_1, /PrsSelect, /LPMode, /StdBy to GNDD	0		V _{DDD}	V
Crystal Frequencies F_o	0.03 ³		25	MHz
Junction Temperature ⁴ T_j	-60		230	°C

¹ V_{DDA} and V_{DDD} must be the same voltage.

² For operation frequencies above 20MHz, minimum supply voltage is 2.8V, depending on the used crystal.

³ For operation frequencies below 1MHz, /LPMode must be LOW.

⁴ Operation beyond the specified temperature range is achieved.

ELECTRICAL SPECIFICATIONS

Unless otherwise stated, specification applies for V_{DDA}=V_{DDD}=5V, -60°C<T_j<230°C.

Parameter	Condition	Min	Typ	Max	Units
Supply Current					
Analog stand-by supply current I_{VDDASB}	/StdBy=0V. No switching. T _c =-60°C T _c =85°C T _c =230°C		33 47 60	50 70 100	μA
Digital stand-by supply current I_{VDDDSB}	/StdBy=0V. No switching. T _c =85°C T _c =230°C		0.001 3.5	0.02 10	μA
Analog dynamic supply current I_{VDDA}	V _{DDA} =V _{DDD} =2.5V, F _o <1MHz, /LPMode=0 T _c =-60°C T _c =85°C T _c =230°C		0.16 0.26 0.33	0.25 0.40 0.50	mA
	V _{DDA} =V _{DDD} =2.5V, F _o =1MHz, /LPMode=1 T _c =-60°C T _c =85°C T _c =230°C		0.33 0.56 0.82	0.50 0.90 1.2	
	V _{DDA} =V _{DDD} =2.5V, F _o =20MHz, /LPMode=1 T _c =-60°C T _c =85°C T _c =230°C		0.33 0.58 0.88	0.50 0.90 1.3	
	V _{DDA} =V _{DDD} =5.5V, F _o <1MHz, /LPMode=0 T _c =-60°C T _c =85°C T _c =230°C		0.48 0.53 0.61	0.75 0.80 0.9	
	V _{DDA} =V _{DDD} =5.5V, F _o =1MHz, /LPMode=1 T _c =-60°C T _c =85°C T _c =230°C		1.70 1.85 1.90	2.50 2.7 2.80	
	V _{DDA} =V _{DDD} =5.5V, F _o =20MHz, /LPMode=1 T _c =-60°C T _c =85°C T _c =230°C		1.68 1.69 1.76	2.50 2.6 2.60	
	Power dissipation capacitance C_{P_VDDO}	I _{VDDO} = (C _{P_VDDO} + C _L) x Freq _{OUT} x V _{DDO} C _L is the total load capacitance connected to OUT.		35	

ELECTRICAL SPECIFICATIONS (CONTINUED)

Unless otherwise stated, specification applies for $V_{DDA}=V_{DDD}=5V$, $-60^{\circ}C < T_j < 230^{\circ}C$.

Digital Inputs (/LPMode, /PrsSelect, /StdBy, /DIV_0, /DIV_1)					
HIGH level input voltage V_{T+}		3.0	3.3	3.6	V
LOW level input voltage V_{T-}		1.55	1.8	2.05	V
Hystereris voltage ($V_{T+}-V_{T-}$) V_{Hys}		1.2	1.5	1.8	V
Input leakage current I_{IL}	Inputs connected to VDD for pulled-up inputs. $T_C=85^{\circ}C$ $T_C=230^{\circ}C$		0.01 1.9	0.05 5	μA
Pull-up strength I_{PU}	Pulled-up inputs connected to GND. $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		6.5 11	10 15	μA
Output Buffer					
Peak output current I_{OUT_peak}	$T_C=-60^{\circ}C$ $T_C=85^{\circ}C$ $T_C=230^{\circ}C$	± 60 ± 45 ± 30	± 85 ± 55 ± 38		mA
HIGH level output voltage V_{OH}	$I_{OUT}=10mA$ (sourcing), $T_C=230^{\circ}C$.	3.6	4.05		V
LOW level output voltage V_{OL}	$I_{OUT}=-10mA$ (sinking), $T_C=230^{\circ}C$.		0.51	0.7	V
Output rise time t_r	$0.1xV_{DDD}$ to $0.9xV_{DDD}$; $C_{load}=13pF$, $T_C=230^{\circ}C$.		2.5	4	ns
Output fall time t_f	$0.9xV_{DDD}$ to $0.1xV_{DDD}$; $C_{load}=13pF$, $T_C=230^{\circ}C$.		2.2	4	ns
Crystal Driver Stage					
Driver transconductance G_{m_LP}	/LPMode=0 $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		1.1 0.6		mS
Driver transconductance G_{m_HP}	/LPMode=1 $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		8.5 5.3		mS
Driver output impedance R_{o_LP}	/LPMode=0 $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		20 25		K Ω
Driver output impedance R_{o_HP}	/LPMode=1 $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		1.6 2.5		K Ω
Oscillation stable after VDDA goes up $t_{power_up\ 32kHz}$	$V_{DDA}=2.8V$ for $F_0=32kHz$ $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		50 70		ms
Oscillation stable after VDDA goes up $t_{power_up\ 20MHz}$	$V_{DDA}=2.8V$ for $F_0=20MHz$ $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		4.5 6		ms
Oscillation stable after /StdBy goes up $t_{start_up\ 32kHz}$	$V_{DDA}=2.8V$ for $F_0=32kHz$ $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		35 50		ms
Oscillation stable after /StdBy goes up $t_{start_up\ 20MHz}$	$V_{DDA}=2.8V$ for $F_0=20MHz$ $T_C=-60^{\circ}C$ $T_C=230^{\circ}C$		3 4		ms
Internal Load Capacitors					
Accuracy	$T_j=25^{\circ}C$		± 16		%
Linear temperature coefficient $TC1$	$C(T)=C(T_0) \times [1 + TC1 \times (T-T_0) + TC2 \times (T-T_0)^2]$		23		ppm/K
Quadratic temperature coefficient $TC2$			0.013		ppm/K ²
Total variation with temperature ΔC	$\Delta T=290K$ (from $-60^{\circ}C$ to $230^{\circ}C$)		0.8		%

TYPICAL PERFORMANCE

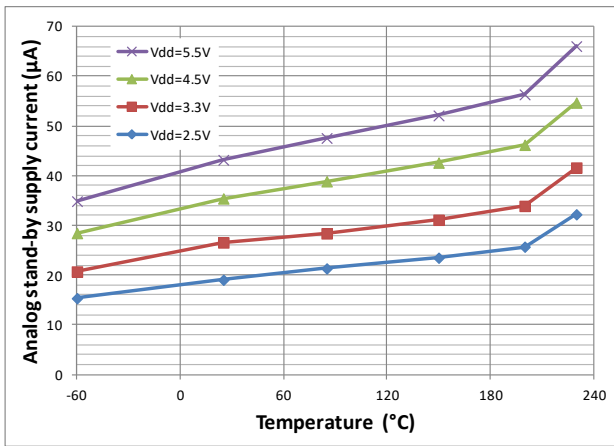


Figure 1. Analog stand-by supply current (I_{VDDASB}) vs. temperature for different supply voltages.

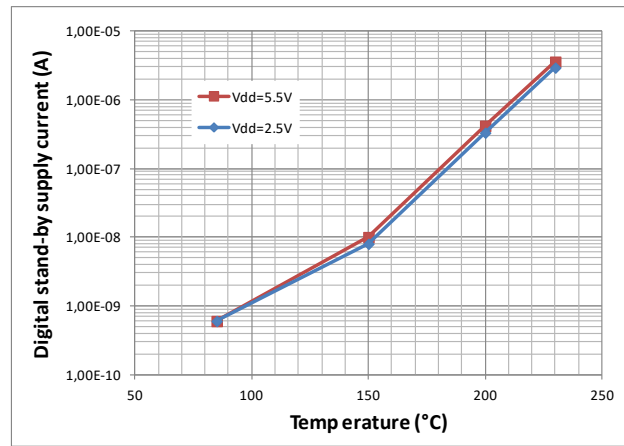


Figure 2. Digital stand-by supply current (I_{VDDDBS}) vs. temperature for different supply voltages.

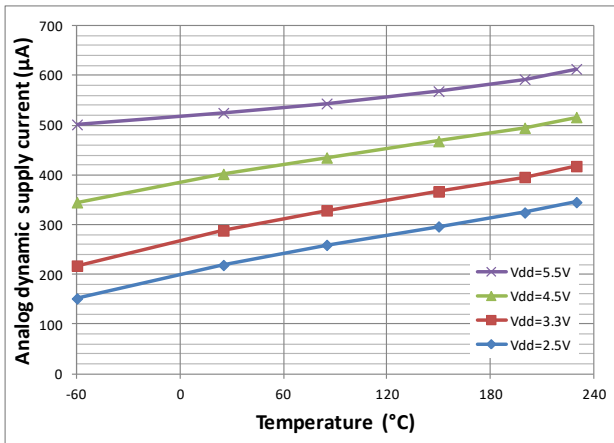


Figure 3. Analog dynamic supply current (I_{VDDA}) vs. temperature for different supply voltages in low-power mode ($LPM=0$). Freq=32kHz.

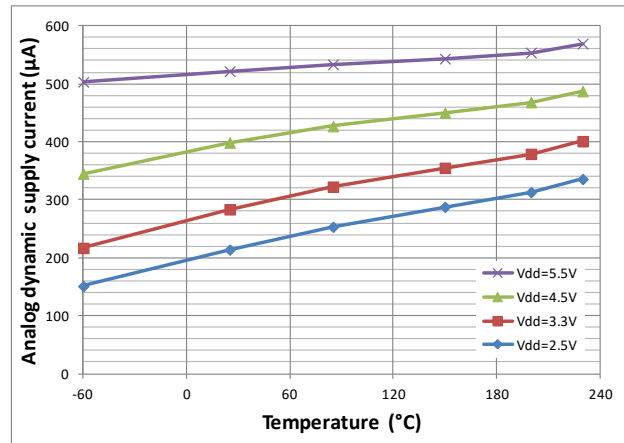


Figure 4. Analog dynamic supply current (I_{VDDA}) vs. temperature for different supply voltages in low-power mode ($LPM=0$). Freq=1MHz.

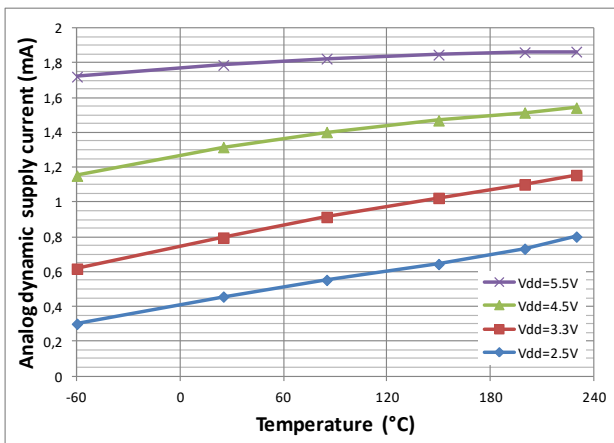


Figure 5. Analog dynamic supply current (I_{VDDA}) vs. temperature for different supply voltages in full-speed mode ($LPM=1$). Freq=1MHz.

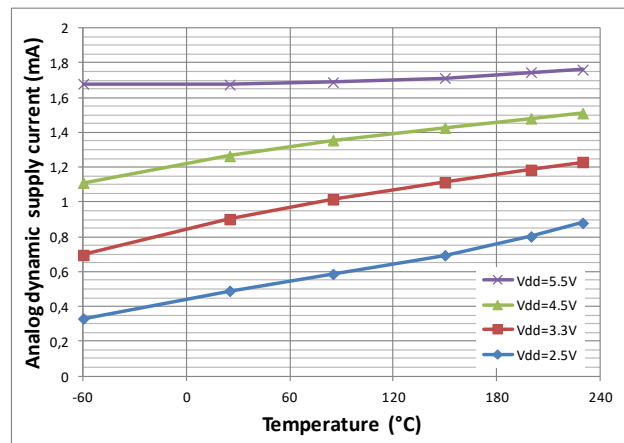


Figure 6. Analog dynamic supply current (I_{VDDA}) vs. temperature for different supply voltages in full-speed mode ($LPM=1$). Freq=20MHz.

TYPICAL PERFORMANCE (CONTINUED)

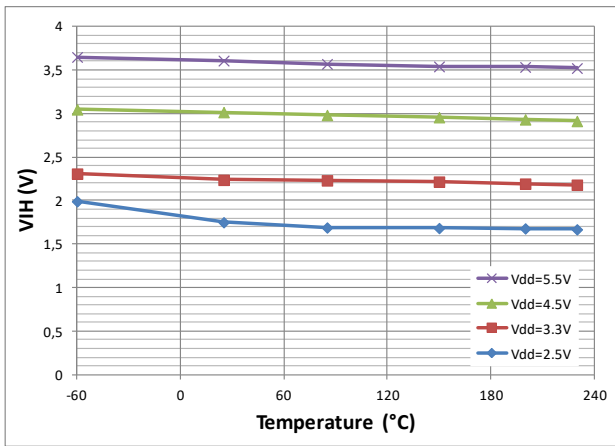


Figure 7. HIGH level input voltage (V_{IH}) vs. temperature for different supply voltages.

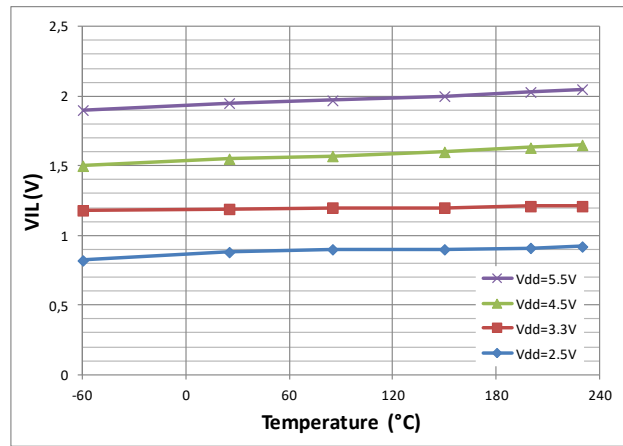


Figure 8. LOW level input voltage (V_{IL}) vs. temperature for different supply voltages.

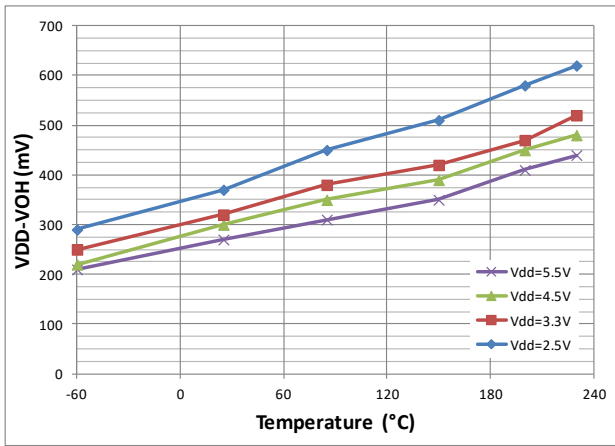


Figure 9. HIGH level output voltage (V_{OH}) vs. temperature for different supply voltages and $I_{out}=5mA$.

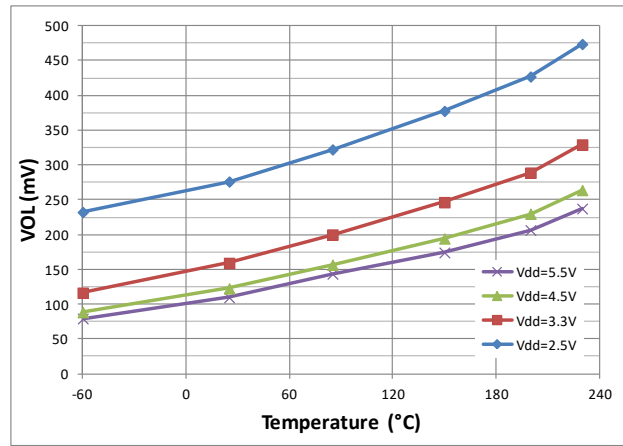


Figure 10. LOW level output voltage (V_{OL}) vs. temperature for different supply voltages and $I_{out}=-5mA$.

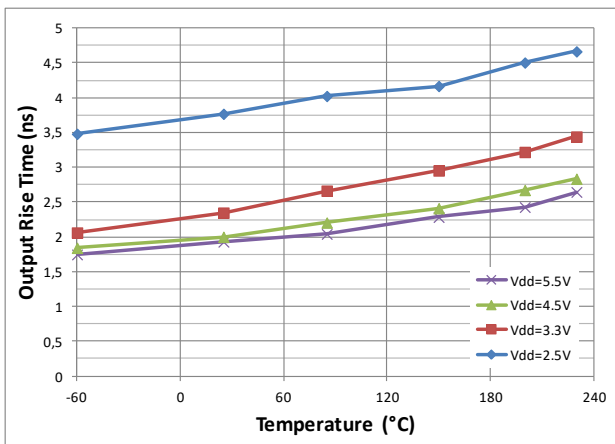


Figure 11. Output rise time (t_r) vs. temperature for different supply voltages and $C_{load}= 13pF$.

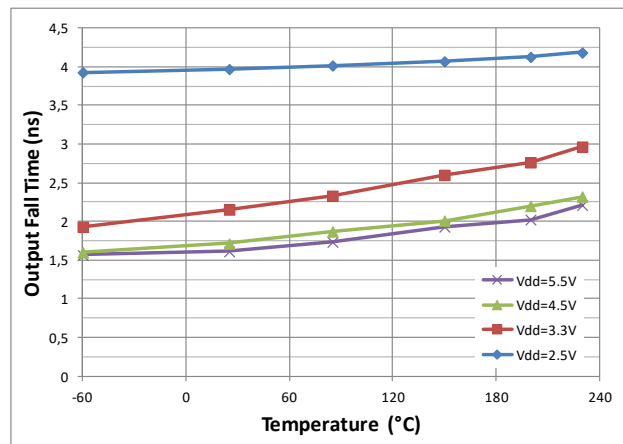


Figure 12. Output fall time (t_f) vs. temperature for different supply voltages and $C_{load}= 13pF$.

TYPICAL PERFORMANCE (CONTINUED)

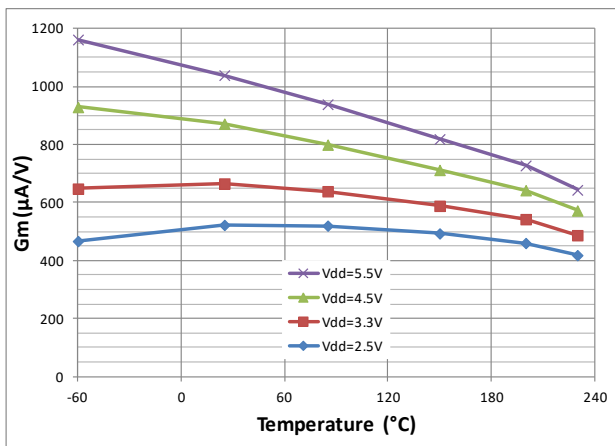


Figure 13. Driver transconductance (G_{m_LP}) vs. temperature for different supply voltages in low-power mode (LPMODE=0).

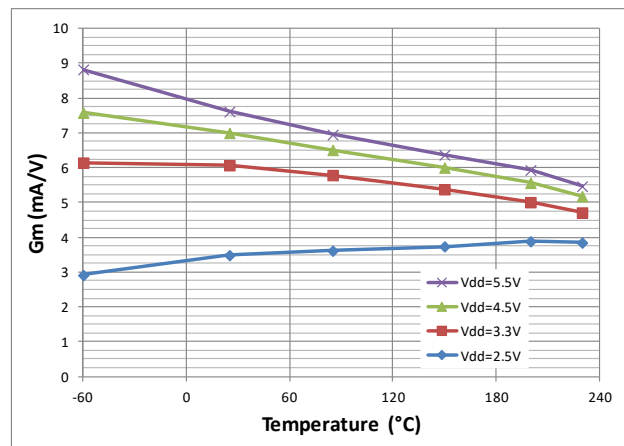


Figure 14. Driver transconductance (G_{m_HP}) vs. temperature for different supply voltages in full-speed mode (LPMODE=1).

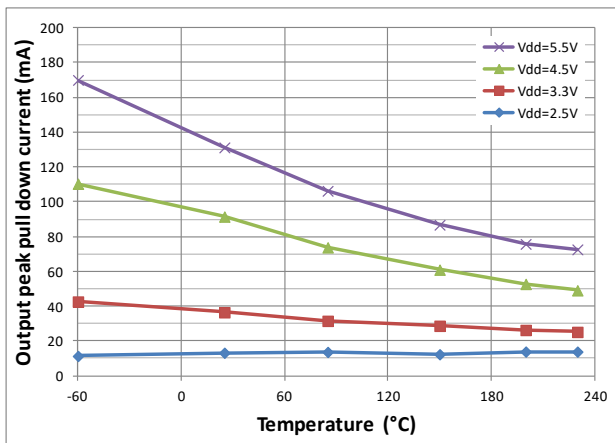


Figure 15. Output Peak pull down output current (I_{OUT_peak}) vs. temperature for different supply voltages.

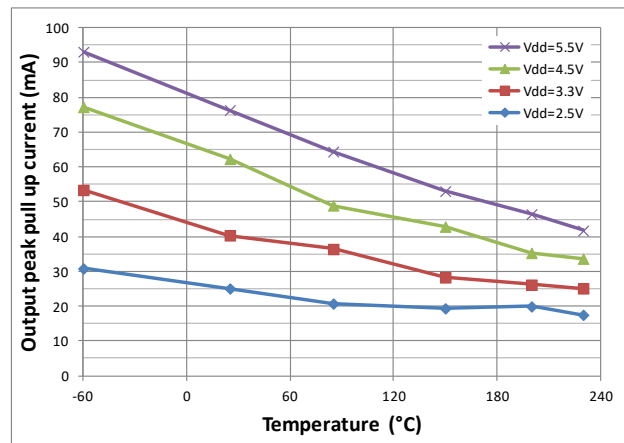


Figure 16. Output Peak pull up output current (I_{OUT_peak}) vs. temperature for different supply voltages.

THEORY OF OPERATION

Introduction

The XTR60010 is a family of high-temperature, extended lifetime crystal oscillator drivers. Operation is guaranteed from -60°C to +230°C and for supply voltages from 2.5V to 5.5V.

Integrated functional features include selectable prescaler (1/128), programmable frequency divider (1/2/4/8), operation in low-power mode for low frequency crystals, integrated capacitors for crystal loading and stand-by mode which stops oscillations and sets the output buffer to the high-Z state. Using the internal prescaler and frequency divider, division factors from 1 to 1024 can be obtained. The internal crystal driver has automatic gain control to be able to accommodate to the used crystal, with no intervention needed from the customer, as required by some competing products.

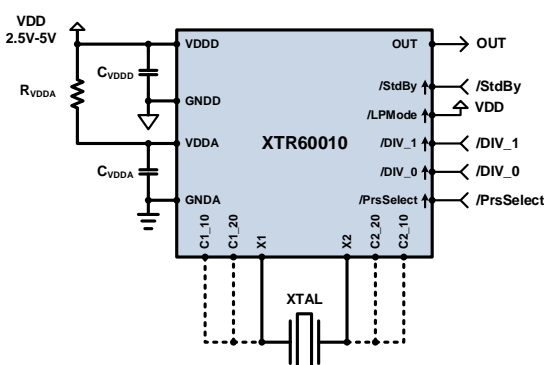
Operation Modes

Full speed mode

This mode, selected by setting /LPMMode=1, is intended for oscillation frequencies in the range 1MHz to 25MHz.

In this case, the crystal driver adjusts its own gain so that the oscillation amplitude at X1 is constant at about 300-500mV.

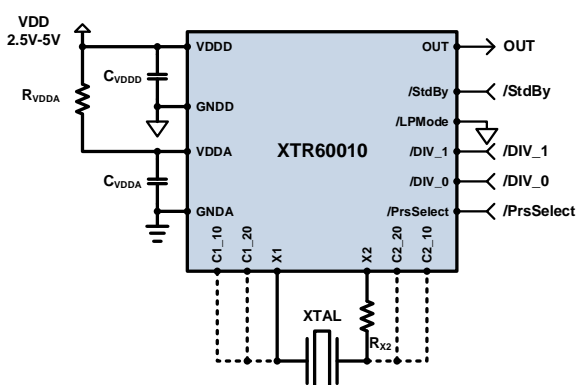
The following image shows a typical application schematic in full-speed mode. Separate decoupling capacitors are recommended on VDDA and VDDD in order to reduce any possible noise coupling from the digital part of the circuit onto the analog part.



Low-power mode

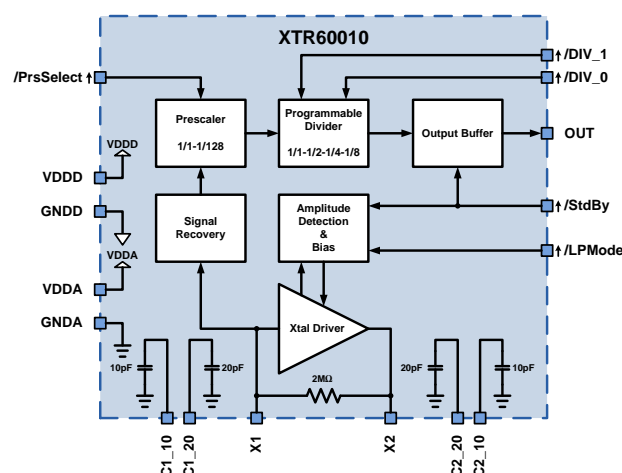
Low-power mode, selected by setting /LPMMode=0, is intended for operation at frequencies below 10MHz. In particular, this mode should be selected to operate at 32.768kHz.

In this mode, the crystal driver operates at fixed gain.



Internal Blocks and Functional Features

The block diagram of the XTR60010 die is shown here below. Arrows beside input signal names indicate that the inputs are internally pulled up.



The XTR60010 has two power supply domains. The analog supply domain between VDDA and GNDA concerns the crystal driver, the amplitude detection block and the signal recovery block. The digital domain supplies the prescaler, frequency divider and output buffer.

Digital inputs

All digital inputs of the XTR60010 (/LPMMode, /PrsSelect, /DIV_0, /DIV_1 and /StdBy) are Schmitt trigger type and are internally pulled up.

Crystal driver and amplitude detection block

The crystal driver operates in two different modes depending upon the status of /LPMMode.

For /LPMMode=1, the driver operates in full-speed mode and crystals up to 25MHz can be used. In this mode an amplitude detection block changes the driver gain so that a stable oscillation is obtained on X1 with amplitude between 300mV to 500mV depending on supply voltage and temperature.

When /LPMMode=0, the driver operates in low-power mode, which is intended for low oscillation frequencies. In this mode the driver operates at fixed transconductance.

The /StdBy signal is used to stop the oscillation and to set the crystal driver and the amplitude detection block into a low quiescent current state. This also sets the output buffer of the circuit at hi-Z state.

Signal recovery block

The oscillation signal is recovered on terminal X1, which in general presents a much more symmetrical shape than the signal on X2. This fact is used in order to provide at the output a signal with a duty-ratio as close to 50% as possible.

Prescaler and programmable frequency divider

Two separate blocks are offered to the user in order to obtain eight possible division factors.

A prescaler, with a division factor of 1/128 can be inserted in the signal path by setting /PrsSelect=0.

Additionally to the prescaler, a programmable frequency divider can be used to obtain four binary weighted division factors.

The following table summarizes the total division factor obtained as a function of /PrsSelect, /DIV_0 and /DIV_1.

/PrsSelect	/DIV_1	/DIV_0	Division Factor
1	1	1	1
1	1	0	2
1	0	1	4
1	0	0	8
0	1	1	128
0	1	0	256
0	0	1	512
0	0	0	1024

Output buffer

The output buffer provides a neat clock signal with duty-ratio close to 50% and is able to operate on loads of up to 50pF at 25MHz. A ruggedized architecture is used in order to be tolerant to impedance mismatches with respect to the load. However, for signal integrity reasons, good load matching is recommended.

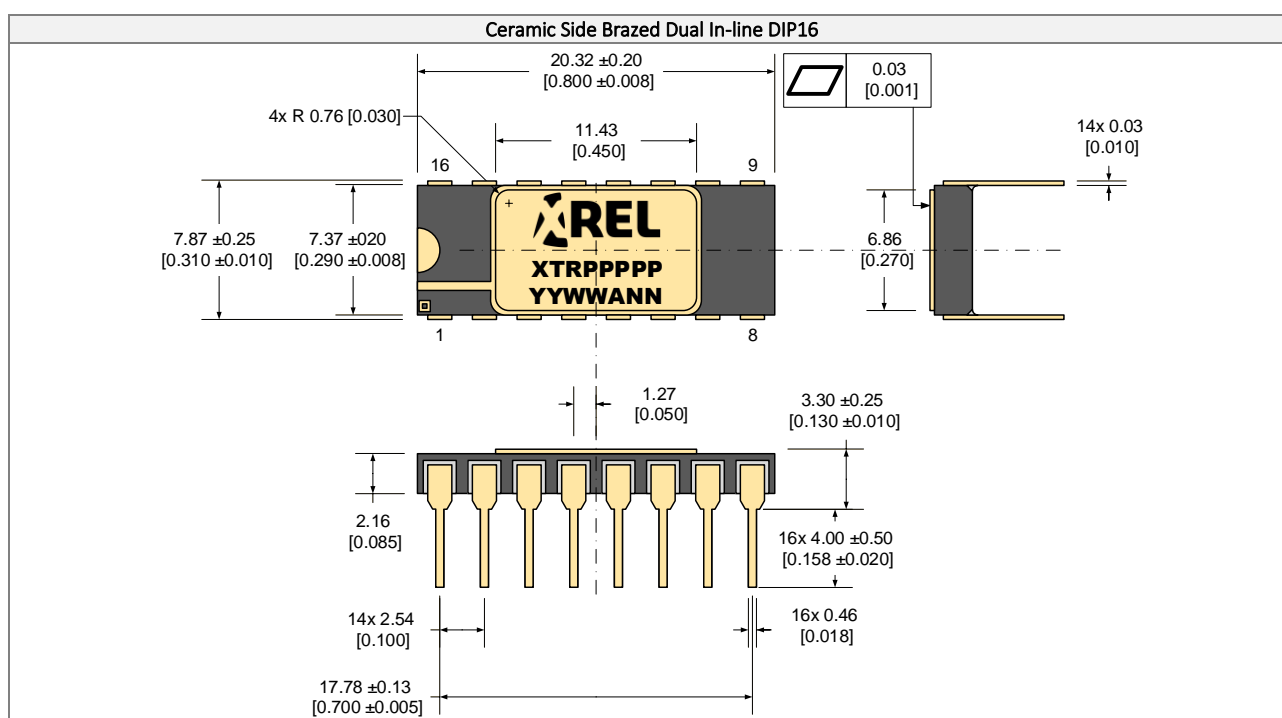
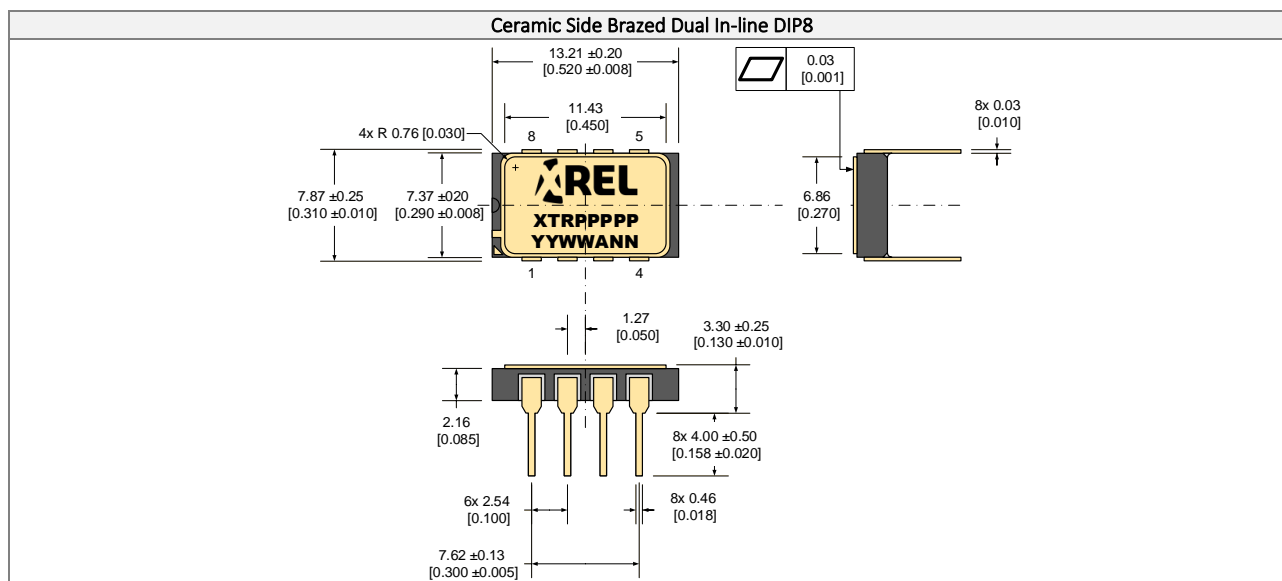
The output buffer is responsible for the most of the digital current consumption of the part. In order to reduce the intrinsic current consumption, cross-conduction avoidance techniques were used in the

output buffer. As a reminder, the digital current consumption can be written as $C.f.V_{DD}$, where C is the total equivalent capacitance (internal + load), f is the operating frequency and V_{DD} is the supply voltage.

When /StdBy=0, besides stopping oscillation of the crystal driver, the XTR60010 presents a hi-Z state on the output buffer.

PACKAGE OUTLINES

Dimensions shown in mm [inches]. Tolerances ± 0.13 mm [± 0.005 in] unless otherwise stated.



Part Marking Convention

Part Reference: XTRPPPPP	
XTR	X-REL Semiconductor, high-temperature, high-reliability product (XTRM Series).
PPPPP	Part number (0-9, A-Z).
Unique Lot Assembly Code: YYWWANN	
YY	Two last digits of assembly year (e.g. 11 = 2011).
WW	Assembly week (01 to 52).
A	Assembly location code.
NN	Assembly lot code (01 to 99).

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