## eSL Series

## 16 Bits DSP Sound Processor

# Product Specification

Doc. Version 1.5

**ELAN MICROELECTRONICS CORP.** 

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#### **Specification Revision History**

Doc. Version	Revision Description	Date
1.0	1. Modified the Pin description in Section 5	2006/10/31
1.0	2. Modified the Operating temperature Range in Section 6.2	2000/10/31
	1. Added a comment after the Selection table in Section 4	
1.1	2. Modified the Application Circuits diagram in Section 7	2007/04/12
	3. Modified the Sampleing Rate Range in Section 4	
	1. Added eSL032	
	2. Modified the Temperature Range in Section 6.2	
1.2	3. Modified the Power Supply voltage in Section 6.3	2007/08/10
	<ol> <li>Added algorithm suuport such as beat tracking, sound location, speech control, pitch control in Section 2 and 4</li> </ol>	
1.3	Added package information in Section 4      Added package information in Section 4	2007/11/10
	Modified the Application Circuits in Section 7	
1.4	1. Modified the PWM current in Section 6.3	2008/01/10
	2. Added Port C DC Characteristics in Section 6.3	
1.5	1. Modified the Application Circuits Diagram in Section 7	2008/12/04
	2. Modified the Algorithm support in Sections 2 and 4	



#### 1 General Description

The ELAN eSL Series IC is a 16-bit DSP Sound Processor with multi-channel speech and instrument playback. It is based on ELAN 16-bit DSP platform. The series has a powerful 16-bit DSP architecture that handles most of the speech/melody functions. Speech and melody can be played back simultaneously. The speech synthesis is implemented by software, and it supports a wide range of compression bit rates and various volume levels. The ELAN eSL Series provides real instrument waveform to obtain good quality melody. The ELAN eSL peripheral includes ADC, RTC, Timer, WDT, SPI, DAC, PWM, etc.

The ELAN eSL Series IC offers Fast, Sleep, Green, and Slow modes of operation. The use of Green/Slow mode will further reduce the power consumption. Green mode also provides RTC function for wake-up purposes.

The ELAN eSL Series enhanced features make it suitable for versatile voice and sound effect product applications. These enhanced versatile features allow users to create products with a wide variety of new fancy ideas.

The ELAN eSL Series has extreme high performance in speech application based on powerful DSP architecture and good algorithm in audio compression. Up to 2-channel speech with different channel sample rate or a single channel speech + 8-channel melody are provided.

#### 2 Features

- MCU
  - 16-bit RISC CPU architecture
  - CPU clock: 20 MHz @ 3.3V
  - Programmable PLL
  - Four CPU operation modes: Fast, Slow, Green, Sleep
  - Powerful DSP Instruction Set supports multiplication, division, repeat, loop and soft interrupt instructions.
  - Saturation mode is supported for multimedia applications.
  - 8 general purpose registers (GPR)
  - 21 interrupt sources with 2-level priority
- Memory
  - 32K-word Program Memory
  - 2K-word Data RAM
  - 032/128/256/512K-word Data ROM



#### Peripherals

- Real Time Clock (RTC) with wake-up function
- Four 8-bit timers, two general purpose timers, two multiple-function timers
- 8-bit Watchdog Timer (WDT) with general purpose timer capability
- 40 GPIO + 8 Outputs
- Serial Peripheral Interface (SPI)
- 12-bit Analog to Digital Converter (ADC) with touch panel and MIC inputs
- 12-bit current-steering Digital to Analog Converter (DAC)
- 10-bit resolution Pulse Width Modulation (PWM)

#### Algorithm

- Built-in software voice synthesizer (0.8K ~ 96Kbps @ 8kHz)
- Multiple Flash with volume level option
- Directly controls port output value by waveform (waveform control port).
- Supports mark number in waveform with ROM optimized configuration.
- Up to 2-channel speech with different channel sample rate or 1-channel speech + 8-channel melody
- Voice recording in 12, 16, 20, and 32 Kbps @ 8kHz
- Supports beat tracking function to detect music tempo.
- Supports speed control to adjust playback speed.
- Supports pitch control to change voice pitch.
- Supports sound source detection function to detect the angle of sound position.
- Supports speaker dependent recognition to recognize voice command and control function which is dependent on the speaker.
- Supports speaker independent recognition to recognize voice command and control function which is independent on the speaker.
- Supports handwriting recognition engine to recognize characters, numerals, symbols, and gestures.



#### 3 Block Diagram

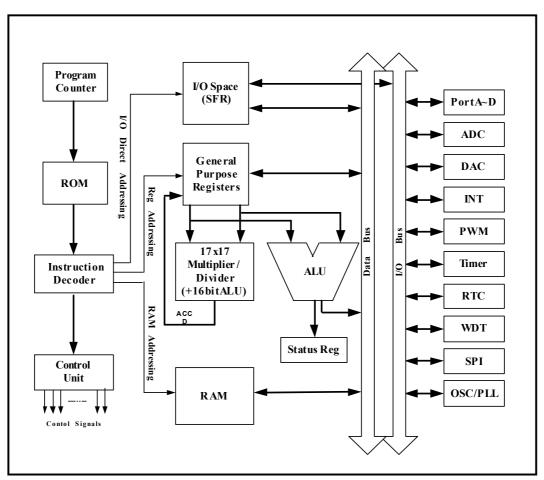


Figure 3-1 ELAN eSL System Block Diagram



#### 4 Selection Table

The ELAN eSL Series integrates an extensive range of features, most of which are common to all devices, except for some distinctive features like, Data ROM, I/O count and Coding Type. For user convenience in the choice of the most suitable product for their application, the following table is provided, which enumerates the main features of each device.

Product No.	eSL032	eSL128	eSL256	eSL512	eSL032 A/B*	eSL128 A/B*	eSL256 A/B*	eSL512 A/B/C*	
Pin Count				81					
Program ROM				32K×	<16				
Data RAM				2K×	16				
Data ROM	32Kx16	128K×16	256K×16	512K×16	32Kx16	128K×16	256K×16	512K×16	
Timer				4 × 8-bit	timers				
Watchdog	Yes								
PWM	10-bit								
A/D Converter	12-bit								
Current D/A	12-bit								
SPI	1 set								
I/O	40 I/O ports + 8 Output ports								
Audio**	Up to 2-channel speech with different channel sample rate or 1-channel speech + 8-channel melody								
Coding Type**	12K/16K/20K/24K/32K/40K/48K/96K bps @ 0.8K~96K bps @ 8kHz***							**	
Sampling Rate Range**				6kHz ~ 4	48kHz				
Algorithm		no	one				**		

<sup>\*</sup> The product number "A, B, C" means advanced audio algorithm is supported.

For more detailed information, refer to the Assembler Reference Manual, C Macro Reference Manual and related Application Notes.

<sup>\*\*\*</sup>eSL512C Coding Type is 12K/16K/20K/24K/32K/40K/48K/96K bps @ 8kHz, the same with eSL.



#### 5 Pin Description

#### 5.1 Power Supply

Name	Туре	Supply	Description
- Name	Туре	Voltage	Description
VDD_CPU	Р	3V	Positive power supply for CPU, digital peripheral and DRAM
VDD_PM	Р	3V	Positive power supply for PROM, DROM and POR
VDD_OSC	Р	3V	Positive power supply for Oscillator system and PLL
IOVDD_PWM	Р	3V, 5V	Positive power supply for Port D and PWM I/O pad
IOVDD_PB	Р	3V, 5V	Positive power supply for Port A.2~15 and Port B I/O pad
IOVDD_PC	Р	3V, 5V	Positive power supply for Port C I/O pad
VSS_CPU	Р	GND	Negative power supply for CPU, digital peripheral and DRAM
VSS_PM	Р	GND	Negative power supply for PROM, DROM and POR
VSS_OSC	Р	GND	Negative power supply for Oscillator system and PLL
IOVSS_PWM	Р	GND	Negative power supply for Port D and PWM I/O pad
IOVSS_PB	Р	GND	Negative power supply for Port A.2~15 and Port B I/O pad
IOVSS_PC	Р	GND	Negative power supply for Port C I/O pad
AVDD_AD	Р	3V	Positive power supply for A/D
AVDD_DA	Р	3V	Positive power supply for D/A
AVSS_AD	Р	GND	Negative power supply for A/D
AVSS_DA	Р	GND	Negative power supply for D/A
VREF	Р	3V	External reference voltage input pin for A/D and MIC
RVIN	Р	5V	Regulator voltage input
RVOUT	Р	3V	Regulator voltage output 3.0V

#### NOTE

The AVDD\_AD, VREF are analog voltage input that need to be separated with the other digital voltage input to reduce noise interference. For example, you can use an on-chip regulator to be the analog voltage source. Or you can refer to the development board reference circuit.



#### **5.2 System Control**

Name	Туре	Description
RSTB	1	RSTB is the low active global reset input *
TEST	I	Test mode select pin (High active). Internal pull down. For chip internal test only, normally connect to VSS.
OSCI	I	Crystal or RC oscillator connecting pin RC or Crystal selection is by OSCS pin
osco	0	Crystal oscillator connecting pin
oscs	I	RC or Crystal selection: <b>0</b> = RC <b>1</b> = Crystal
PLLC	I	PLL loop filter capacitor **

<sup>\*</sup> This pin has an internal pull-up 150 K $\Omega$  resistor. Refer to the Application Circuits.

#### 5.3 DAC Output

Name	Туре	Description
DACO	0	Current D/A output pin

#### 5.4 2-stage Amplifier and Touchpad Positioning

Name	Туре	Description
AMPO	0	Post Amplifier output
MIC	I	Microphone signal input (AC coupling from microphone signal)
AGC	I	Automatic Level Control adjustment pin
Xn	I	Touch Pad positioning for X axis under negative voltage level
Yn	1	Touch Pad positioning for Y axis under negative voltage level
XP/ADIN0	I	Touch Pad positioning for X axis under positive voltage level Analog input channel 0
YP/ADIN1	I	Touch Pad positioning for Y axis under positive voltage level Analog input channel 1

<sup>\*\*</sup> This pin must be connected to a 47nF capacitor and to ground. Refer to the Application Circuits.



#### 5.5 I/O Port

#### Port A Attributes and Definitions

Name	Function	Туре	Description
DAIO	GPIO	I/O	General-purpose I/O function
PA[0]	PWM0	0	PWM Output 0
DAIAI	GPIO I/O General-purpose I/O function PWM0 O PWM Output 0  GPIO I/O General-purpose I/O function PWM1 O PWM Output 1  GPIO I/O General-purpose I/O function GPIO I/O General-purpose I/O function GPIO I/O General-purpose I/O function TEX12 I External Timer 2 clock input GPIO I/O General-purpose I/O function TEX13 I External Timer 3 clock input GPIO I/O General-purpose I/O function TCCP2 I/O Timer 2 capture input or compound or com	General-purpose I/O function	
PA[1]	PWM1	0	General-purpose I/O function  PWM Output 0  General-purpose I/O function  PWM Output 1  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  External Timer 2 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  General-purpose I/O function  Timer 2 capture input or compare output  General-purpose I/O function  Timer 3 capture input or compare output  General-purpose I/O function  External Interrupt 0 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function with programmable high current  SPI function  In Slave mode: used as chip select input  In Master mode: used as I/O pin with programmable high current  General-purpose I/O function with programmable high current  SPI function (Master output / Slave input) with programmable high current  SPI function (Master output / Slave input) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function (Master input / Slave output) with programmable high current
PA[2]	GPIO	I/O	General-purpose I/O function
PA[3]	GPIO	I/O	General-purpose I/O function
DAIAI	GPIO	I/O	General-purpose I/O function
PA[4]	TEX12	I	External Timer 2 clock input
DAISI	GPIO	I/O	General-purpose I/O function
PA[5]	TEX13	I	External Timer 3 clock input
PA [6]	GPIO	I/O	General-purpose I/O function
PA [7]	GPIO	I/O	General-purpose I/O function
D	GPIO	I/O	General-purpose I/O function
PA [8]	TCCP2	I/O	eneral-purpose I/O function WM Output 0 eneral-purpose I/O function WM Output 1 eneral-purpose I/O function with programmable igh current
DV [0]	GPIO	I/O	General-purpose I/O function  PWM Output 0  General-purpose I/O function  PWM Output 1  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  External Timer 2 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  Timer 2 capture input or compare output  General-purpose I/O function  Timer 3 capture input or compare output  General-purpose I/O function  External Interrupt 0 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function with programmable high current  SPI function  In Slave mode: used as chip select input  In Master mode: used as I/O pin with programmable high current  SPI function (Master output / Slave input) with programmable high current  General-purpose I/O function with programmable high current  SPI function (Master output / Slave input) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function with programmable high current  General-purpose I/O function with programmable high current  SPI function with programmable high current  In Master mode: used as serial clock output
PA [9]	TCCP3	I/O	PWM Output 0  General-purpose I/O function  PWM Output 1  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  External Timer 2 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  Timer 2 capture input or compare output  General-purpose I/O function  Timer 3 capture input or compare output  General-purpose I/O function  External Interrupt 0 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function with programmable nigh current  SPI function  In Slave mode: used as chip select input In Master mode: used as I/O pin with programmable nigh current  General-purpose I/O function with programmable nigh current  SPI function (Master output / Slave input) with programmable high current  General-purpose I/O function with programmable nigh current  General-purpose I/O function with programmable nigh current  SPI function (Master input / Slave output) with programmable high current  General-purpose I/O function with programmable nigh current  General-purpose I/O function with programmable nigh current  SPI function (Master input / Slave output) with programmable high current  General-purpose I/O function with programmable nigh current  SPI function with programmable high current  SPI function with programmable high current  SPI function with programmable high current  In Master mode: used as serial clock output
DA [40]	GPIO	I/O	General-purpose I/O function  PWM Output 0  General-purpose I/O function  PWM Output 1  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  External Timer 2 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  External Timer 3 clock input  General-purpose I/O function  General-purpose I/O function  General-purpose I/O function  Timer 2 capture input or compare output  General-purpose I/O function  Timer 3 capture input or compare output  General-purpose I/O function  External Interrupt 0 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function  External Interrupt 1 input  General-purpose I/O function with programmable high current  SPI function  In Slave mode: used as chip select input  In Master mode: used as I/O pin with programmable high current  General-purpose I/O function with programmable high current  SPI function (Master output / Slave input) with programmable high current  SPI function (Master output / Slave output) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function (Master input / Slave output) with programmable high current  SPI function with programmable high current  In Master mode: used as serial clock output
PA [10]	EXINT0	I	
DA [44]	GPIO	I/O	I/O General-purpose I/O function O PWM Output 0 I/O General-purpose I/O function O PWM Output 1 I/O General-purpose I/O function I/O General-purpose I/O function I/O General-purpose I/O function I/O General-purpose I/O function I External Timer 2 clock input I/O General-purpose I/O function I External Timer 3 clock input I/O General-purpose I/O function I/O General-purpose I/O function I/O General-purpose I/O function I/O General-purpose I/O function I/O Timer 2 capture input or compare output I/O General-purpose I/O function I/O Timer 3 capture input or compare output I/O General-purpose I/O function I/O Timer 3 capture input or compare output I/O General-purpose I/O function I External Interrupt 0 input I/O General-purpose I/O function I External Interrupt 1 input I/O General-purpose I/O function I External Interrupt 1 input I/O General-purpose I/O function with programmable high current I/O General-purpose I/O sunction with programmable high current I/O General-purpose I/O sunction with programmable high current I/O General-purpose I/O sunction with programmable high current
PA [11]	EXINT1	I	
	GPIO	I/O	General-purpose I/O function with programmable high current
PA [12]	/SS	I	In Slave mode: used as chip select input In Master mode: used as I/O pin with programmable
DA [42]	GPIO	I/O	
PA [13]	MOSI	I/O	
DA [44]	GPIO	I/O	
PA [14]	MISO	I/O	
	GPIO	I/O	
PA [15]	SCK	I/O	In Master mode: used as serial clock output



#### Port B Attributes and Definitions

Name	Function	Туре	Description
DD [7:0]	GPIO	I/O	General-purpose I/O function
PB [7:0]	GPIO	I	Wake-up function with programmable pull-up resistor
PB [15:8]	GPIO	I/O	General-purpose I/O function
	GPIO	1	Wake-up function with programmable pull-up resistor

#### Port C Attributes and Definitions

Name	Function	Туре	Description
DC [1:0]	GPIO	I/O	General-purpose I/O function
PC [1:0]	GPIO	I	Input with programmable pull-up resistor
	GPIO	I/O	General-purpose I/O function
PC [7:2]		I	Input with programmable pull-up resistor
	ADIN2~7	I	Analog Input channels

**Note:** Port C [7:2] is pin-shared with ADC input. There is no **Schmitt Trigger Input** when input is from Port C [7:2]

#### ■ Port D Attributes and Definitions

Name	Function	Туре	Description
PD [0]	GPO	0	General-purpose output function with high drive current (1 * Tg delay) *
PD [1]	GPO	0	General-purpose output function with high drive current (5 * Tg delay) *
PD [2]	GPO	0	General-purpose output function with high drive current (2 * Tg delay) *
PD [3]	GPO	0	General-purpose output function with high drive current (6 * Tg delay) *
PD [4]	GPO	0	General-purpose output function with high drive current (3 * Tg delay) *
PD [5]	GPO	0	General-purpose output function with high drive current (7 * Tg delay) *
PD [6] GPO		0	General-purpose output function with high drive current (4 * Tg delay) *
PD [7]	GPO	0	General-purpose output function with high drive current (8 * Tg delay)

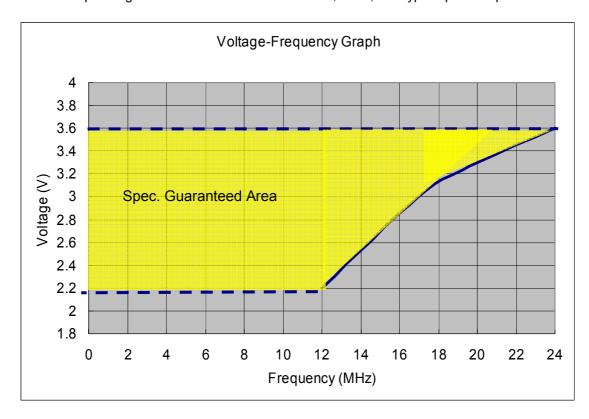
Tg = 4 nano-second for low noise design consideration



#### 6 Electrical Characteristics

#### 6.1 CPU Voltage - Frequency Graph

The speed of a MOS device depends on voltage, temperature, and process variation. Performance analysis is based on a combination of these three factors. The central operating condition is characterized at 3.3V, 25°C, and typical process parameters.





#### **6.2 Absolute Maximum Ratings**

Parameter	Pins	Symbol	Condition	Rated Value	Unit
Power supply voltage	VDD	$V_{DD}$	T <sub>A</sub> =25°C	-0.3 to +6.0	V
Input voltage	All Input	V <sub>IN</sub>	T <sub>A</sub> =25°C	-0.3 to VDD+0.3	
Operating temperature range	-	T <sub>A</sub>	-	-40 to +85	°C
Storage temperature range	-	T <sub>STR</sub>	-	-65 to +150	

#### 6.3 DC Characteristics

Standard operation conditions: VDD = 3V, GND=0V,  $T_A = 25^{\circ}C$ 

Parameter	Pins	Symbol	Condition	Ra	Unit			
				Min.	Тур.	Max.	Offic	
Power supply voltage	VDD <sup>1</sup>	V <sub>DD</sub>	2 batteries	2.2	3.0	3.6		
			3 batteries	3.6	4.5	5.5		
Input voltage	-	V <sub>IN1</sub>	-	VDD×0.7	ı	VDD	V	
	-	V <sub>IN2</sub>	-	0	-	VDD×0.3		
Input threshold voltage (Schmitt Trigger)	-	-	-	0.5×VDD	ı	0.75×VDD		
	-	ı	-	0.2×VDD	ı	0.4×VDD		
Pull-up resistor	PC [7:0]	V <sub>PU0L</sub>	Vin=GND	500	1000	1500		
	PC [7:0]	V <sub>PU0H</sub>	Vin=2V	80	100	120	kΩ	
	/RESET	V <sub>PU1L</sub>	Vin=GND	500	1000	1500		
	/RESET	V <sub>PU1H</sub>	Vin=2V	80	100	120		
Pull-down resistor	TEST	R <sub>PD</sub>	Vin=1V	80	100	120		

<sup>&</sup>lt;sup>1</sup> Refer to the User Manual Voltage Regulator section for details.



Dovomotor	Pins	Symbol	0	Rated Value			11.14	
Parameter			Condition	Min.	Тур.	Max.	Unit	
Ports A, B,C output high current	IOH0	IOH0	VDD=3V VOH=2.4V	-2	-3	-		
Ports A, B,C output low current	IOL0	IOL0	VDD=3V VOL=0.4V	2	3	-		
Port D output high current	IOH1	IOH1	VDD=3V VOH=2.4V	-7	-10	-		
Port D output low current	IOL1	IOL1	VDD=3V VOL=0.4V	7	10	-	mA	
Port A[12:15] high current (HD enabled)	IOH2	IOH2	VDD=3V VOH=2.4V	-7	-10	-		
Port A[12:15] low current (HD enabled)	IOL2	IOL2	VDD=3V VOL=0.4V	7	10	-		
PWM output high current	PWM0 PWM1	IPWMH	VDD=3V VOH=VDD/2 Max. volume	-140	-150	-		
PWM output low current	PWM0 PWM1	IPWML VDD=3V VOL=VDD/2 Max. volume		140	150	-		
DAC output current	DACO	IDAC	VDD=2.2~3.3V	2.5	3	-		
Regulator output current	RVOUT	IOUT	RVIN=4.5V RVOUT=3.0V Fast, Slow mode	70	-	-		
			RVIN = 4.5V RVOUT = 3.0V Green, Sleep mode	7	-	-		
Fast mode current consumption increment per MHz	-	IFAST	VDD=3V .ST No load DAC off		700	800		
Slow mode current consumption	-	ISLOW	VDD=3V No load DAC off	-	70	80	μΑ	
Green mode current consumption	-	IGREEN	VDD=3V	-	8	10		
Sleep mode current consumption	-	ISLEEP	VDD=3V Regulator on	-	1.5	2	-	
			VDD = 3V Regulator off	-	1	1.2		
CPU operation frequency	-	Fsys	VDD = 3V	14	16	-	MHz	



#### 7 Application Circuits

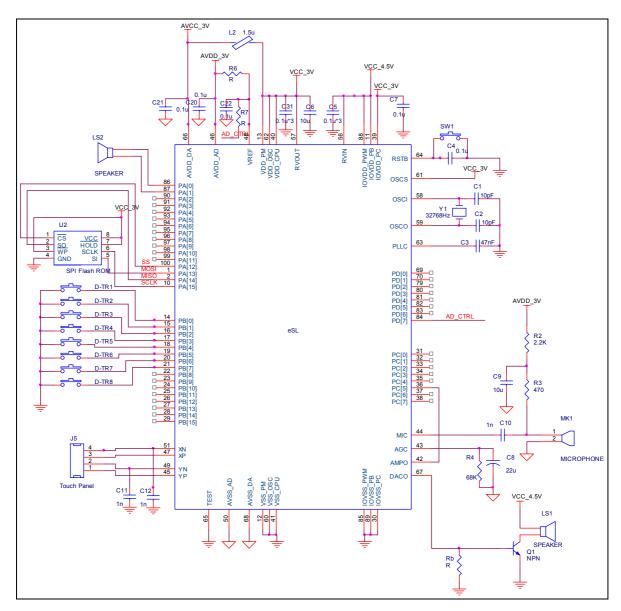


Figure 7-1 ELAN eSL Series Application Circuit Diagram with A/D, D/A using BJT, SPI and PWM for 3V/5V Support

#### NOTE

The AVDD\_AD, VREF are analog voltage input that need to be separated with the other digital voltage input to reduce noise interference. For example, you can use an on-chip regulator to be the analog voltage source. Or you can refer to the development board reference circuit.



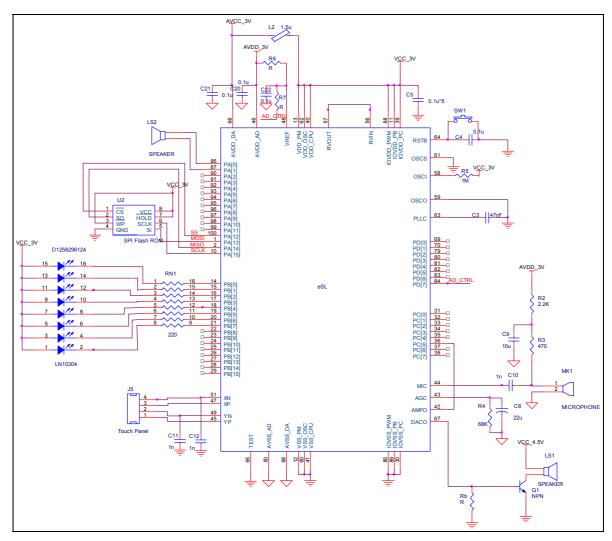


Figure 7-2 ELAN eSL Series Application Circuit Diagram with A/D, D/A using BJT, SPI and PWM for 3V Support

#### **NOTE**

- The AVDD\_AD, VREF are analog voltage input that need to be separated with the other digital voltage input to reduce noise interference. For example, you can use an on-chip regulator to be the analog voltage source. Or you can refer to the development board reference circuit.
- For different package type, the system characteristics, such as power consumption due to I/O pad floating must be controlled by software. For example, if user does not implement bonding of the I/O pad, user must set it in such a way that the I/O pad type is input with pull-up resistor or output to prevent power consumption.

