

# IMXRT1060XCEC

## i.MX RT1060X Crossover Processors for Consumer Products

Rev. 1 — 06/2022

Data Sheet: Technical Data

MIMXRT1062DVN6B



### Package Information

#### Plastic Package

225-pin BGA, 13 x 13 mm, 0.8 mm pitch

### Ordering Information

See [Table 1](#)

# Contents

<b>1</b>	<b>i.MX RT1060X Introduction.....</b>	<b>3</b>	4.5.2	FlexSPI parameters.....	44
1.1	Features.....	3	4.6	Display and graphics.....	50
1.2	Ordering information.....	6	4.6.1	CMOS Sensor Interface (CSI) timing parameters.....	50
<b>2</b>	<b>Architectural Overview.....</b>	<b>7</b>	4.6.2	LCD Controller (LCDIF) timing parameters..	52
2.1	Block diagram.....	7	4.7	Audio.....	53
<b>3</b>	<b>Modules List.....</b>	<b>9</b>	4.7.1	SAI/I2S switching specifications.....	53
3.1	Special signal considerations.....	16	4.7.2	SPDIF timing parameters.....	55
3.2	Recommended connections for unused analog interfaces.....	18	4.8	Analog.....	56
<b>4</b>	<b>Electrical Characteristics.....</b>	<b>18</b>	4.8.1	DCDC.....	56
4.1	Chip-Level conditions.....	18	4.8.2	A/D converter.....	57
4.1.1	Absolute maximum ratings.....	19	4.8.3	ACMP .....	63
4.1.2	Thermal resistance.....	20	4.9	Communication interfaces.....	64
4.1.3	Operating ranges.....	20	4.9.1	LPSPi timing parameters.....	65
4.1.4	External clock sources.....	22	4.9.2	LPI2C module timing parameters.....	67
4.1.5	Maximum supply currents.....	23	4.9.3	Ultra High Speed SD/SDIO/MMC Host Interface (uSDHC) AC timing.....	68
4.1.6	Low power mode supply currents.....	23	4.9.4	Ethernet controller (ENET) AC electrical specifications.....	72
4.1.7	USB PHY current consumption.....	24	4.9.5	Flexible Controller Area Network (FLEXCAN) AC electrical specifications.....	75
4.2	System power and clocks.....	25	4.9.6	LPUART electrical specifications.....	75
4.2.1	Power supplies requirements and restrictions .....	25	4.9.7	USB PHY parameters.....	75
4.2.2	Integrated LDO voltage regulator parameters .....	26	4.10	Timers.....	76
4.2.3	PLL's electrical characteristics.....	28	4.10.1	Pulse Width Modulator (PWM) characteristics .....	76
4.2.4	Arm PLL.....	29	4.10.2	Quad timer timing.....	76
4.2.5	On-chip oscillators.....	29	<b>5</b>	<b>Boot mode configuration.....</b>	<b>77</b>
4.3	I/O parameters.....	30	5.1	Boot mode configuration pins.....	77
4.3.1	I/O DC parameters.....	30	5.2	Boot device interface allocation.....	78
4.3.2	I/O AC parameters.....	34	<b>6</b>	<b>Package information and contact assignments .....</b>	<b>83</b>
4.3.3	Output buffer impedance parameters.....	35	6.1	13 x 13 mm package information.....	83
4.4	System modules.....	37	6.1.1	13 x 13 mm, 0.8 mm pitch, ball matrix.....	83
4.4.1	Reset timings parameters.....	37	6.1.2	13 x 13 mm supplies contact assignments and functional contact assignments.....	85
4.4.2	WDOG reset timing parameters.....	37	6.1.3	13 x 13 mm, 0.8 mm pitch, ball map.....	95
4.4.3	SCAN JTAG Controller (SJC) timing parameters.....	38		Legal information.....	98
4.4.4	Debug trace timing specifications.....	40			
4.5	External memory interface.....	41			
4.5.1	SEMC specifications.....	41			

# 1 i.MX RT1060X Introduction

The i.MX RT1060X is a new processor family featuring NXP's advanced implementation of the Arm Cortex®-M7 core, which operates at speeds up to 600 MHz to provide high CPU performance and best real-time response.

The i.MX RT1060X processor has 1 MB on-chip RAM. 512 KB can be flexibly configured as TCM or general purpose on-chip RAM, while the other 512 KB is general-purpose on-chip RAM. The i.MX RT1060X integrates advanced power management module with DCDC and LDO that reduces complexity of external power supply and simplifies power sequencing. The i.MX RT1060X also provides various memory interfaces, including SDRAM, RAW NAND FLASH, NOR FLASH, SD/eMMC, Quad SPI, and a wide range of other interfaces for connecting peripherals, such as WLAN, Bluetooth™, GPS, displays, and camera sensors. The i.MX RT1060X has rich audio and video features, including LCD display, basic 2D graphics, camera interface, SPDIF, and I2S audio interface. The i.MX RT1060X has analog interfaces, such as ADC, ACMP, and TSC.

The i.MX RT1060X is specifically useful for applications such as:

- Industrial Human Machine Interfaces (HMI)
- Motor Control
- Home Appliance

## 1.1 Features

The i.MX RT1060X processors are based on Arm Cortex-M7 Core Platform, which has the following features:

- Supports single Arm Cortex-M7 Core with:
  - 32 KB L1 Instruction Cache
  - 32 KB L1 Data Cache
  - Full featured Floating Point Unit (FPU) with support of the VFPv5 architecture
  - Support the Armv7-M Thumb instruction set
- Integrated MPU, up to 16 individual protection regions
- Tightly coupled GPIOs, operating at the same frequency as Arm Core
- Up to 512 KB I-TCM and D-TCM in total
- Frequency of 600 MHz
- Cortex M7 CoreSight™ components integration for debug
- Frequency of the core, as per [Table 9](#).

The SoC-level memory system consists of the following additional components:

- Boot ROM (128 KB)
- On-chip RAM (1 MB)
  - 512 KB OCRAM shared between ITCM/DTCM and OCRAM
  - Dedicate 512 KB OCRAM
- External memory interfaces:
  - 8/16-bit SDRAM, up to SDRAM-133/SDRAM-166
  - 8/16-bit SLC NAND FLASH, with ECC handled in software
  - SD/eMMC
  - SPI NOR/NAND FLASH
  - Parallel NOR FLASH with XIP support
  - Two single/dual channel Quad SPI FLASH with XIP support

- Timers and PWMs:
  - Two General Programmable Timers (GPT)
    - 4-channel generic 32-bit resolution timer for each
    - Each support standard capture and compare operation
  - Four Periodical Interrupt Timers (PIT)
    - Generic 32-bit resolution timer
    - Periodical interrupt generation
  - Four Quad Timers (QTimer)
    - 4-channel generic 16-bit resolution timer for each
    - Each support standard capture and compare operation
    - Quadrature decoder integrated
  - Four FlexPWMs
    - Up to 8 individual PWM channels per each
    - 16-bit resolution PWM suitable for Motor Control applications
  - Four Quadrature Encoder/Decoders

Each i.MX RT1060X processor enables the following interfaces to external devices (some of them are muxed and not available simultaneously):

- Display Interface:
  - Parallel RGB LCD interface
    - Support 8/16/24 bit interface
    - Support up to WXGA resolution
    - Support Index color with 256 entry x 24 bit color LUT
    - Smart LCD display with 8/16-bit MPU/8080 interface
- Audio:
  - S/PDIF input and output
  - Three synchronous audio interface (SAI) modules supporting I2S, AC97, TDM, and codec/DSP interfaces
  - MQS interface for medium quality audio via GPIO pads
- Generic 2D graphics engine:
  - BitBlit
  - Flexible image composition options—alpha, chroma key
  - Porter-duff blending
  - Image rotation (90°, 180°, 270°)
  - Image size
  - Color space conversion
  - Multiple pixel format support (RGB, YUV444, YUV422, YUV420, YUV400)
  - Standard 2D-DMA operation
- Camera sensors:
  - Support 24-bit, 16-bit, and 8-bit CSI input

- Connectivity:
  - Two USB 2.0 OTG controllers with integrated PHY interfaces
  - Two Ultra Secure Digital Host Controller (uSDHC) interfaces
    - MMC 4.5 compliance with HS200 support up to 200 MB/sec
    - SD/SDIO 3.0 compliance with 200 MHz SDR signaling to support up to 100 MB/sec
    - Support for SDXC (extended capacity)
  - Two 10/100M Ethernet controllers with support for IEEE1588
  - Eight universal asynchronous receiver/transmitter (UARTs) modules
  - Four I<sup>2</sup>C modules
  - Four SPI modules
  - Two FlexCAN modules
  - One FlexCAN (with Flexible Data-Rate supported)
  - Three FlexIO modules
- GPIO and Pin Multiplexing:
  - General-purpose input/output (GPIO) modules with interrupt capability
  - Input/output multiplexing controller (IOMUXC) to provide centralized pad control

The i.MX RT1060X processors integrate advanced power management unit and controllers:

- Full PMIC integration, including on-chip DCDC and LDO
- Temperature sensor with programmable trim points
- GPC hardware power management controller

The i.MX RT1060X processors support the following system debug:

- Arm CoreSight debug and trace architecture
- Trace Port Interface Unit (TPIU) to support off-chip real-time trace
- Cross Triggering Interface (CTI)
- Support for 5-pin (JTAG) and SWD debug interfaces

The i.MX RT1060X processors support the following analog interfaces:

- Two Analog-Digital-Converters (ADC), 16-channel for each, 20-channel in total
- Four Analog Comparators (ACMP)

Security functions are enabled and accelerated by the following hardware:

- High Assurance Boot (HAB)
- Data Co-Processor (DCP):
  - AES-128, ECB, and CBC mode
  - SHA-1 and SHA-256
  - CRC-32
- Bus Encryption Engine (BEE)
  - AES-128, ECB, and CTR mode
  - On-the-fly QSPI Flash decryption
- True random number generation (TRNG)

- Secure Non-Volatile Storage (SNVS)
  - Secure real-time clock (RTC)
  - Zero Master Key (ZMK)
- Secure JTAG Controller (SJC)

**NOTE**

The actual feature set depends on the part numbers as described in [Table 1](#). Functions such as display and camera interfaces, connectivity interfaces, and security features are not offered on all derivatives.

## 1.2 Ordering information

[Table 1](#) provides examples of orderable part numbers covered by this Data Sheet.

**Table 1. Ordering information**

Part Number	Features		Package	Junction Temperature T <sub>J</sub> (°C)
MIMXRT1062DVN6B	<ul style="list-style-type: none"> <li>• 600 MHz, commercial grade for general purpose, with MPU/FPU</li> <li>• eDMA</li> <li>• Boot ROM (128 KB)</li> <li>• On-chip RAM (1 MB)</li> <li>• SEMC</li> <li>• GPT x2</li> <li>• 4-channel PIT</li> <li>• Qtimer x4</li> <li>• PWM x4</li> <li>• ENC x4</li> <li>• WDOG x4</li> <li>• LCD/CSI/PXP</li> <li>• SPDIF x1</li> <li>• SAI x3</li> <li>• MQS x1</li> <li>• USB OTG x2</li> <li>• eMMC 4.5/SD 3.0 x2</li> </ul>	<ul style="list-style-type: none"> <li>• Ethernet x2</li> <li>• UART x8</li> <li>• I<sup>2</sup>C x4</li> <li>• FlexSPI x2</li> <li>• CAN x2</li> <li>• FlexCAN (with Flexible Data-Rate supported)</li> <li>• FlexIO x3</li> <li>• 149 GPIOs (146 tightly coupled)</li> <li>• HAB/DCP/BEE</li> <li>• TRNG</li> <li>• SNVS</li> <li>• SJC</li> <li>• ADC x2</li> <li>• ACMP x4</li> <li>• TSC</li> <li>• DCDC</li> <li>• Temperature sensor</li> <li>• GPC hardware power management controller</li> </ul>	13 x 13 mm, 0.8 mm pitch, 225-pin BGA	0 to +95 °C

[Figure 1](#) describes the part number nomenclature so that characteristics of a specific part number can be identified (for example, cores, frequency, temperature grade, fuse options, and silicon revision). The primary characteristic which describes which data sheet applies to a specific part is the temperature grade (junction) field.

Ensure to have the proper data sheet for specific part by verifying the temperature grade (junction) field and matching it to the proper data sheet. If there are any questions, visit the web page [nxp.com/IMXRT](http://nxp.com/IMXRT) or contact an NXP representative for details.

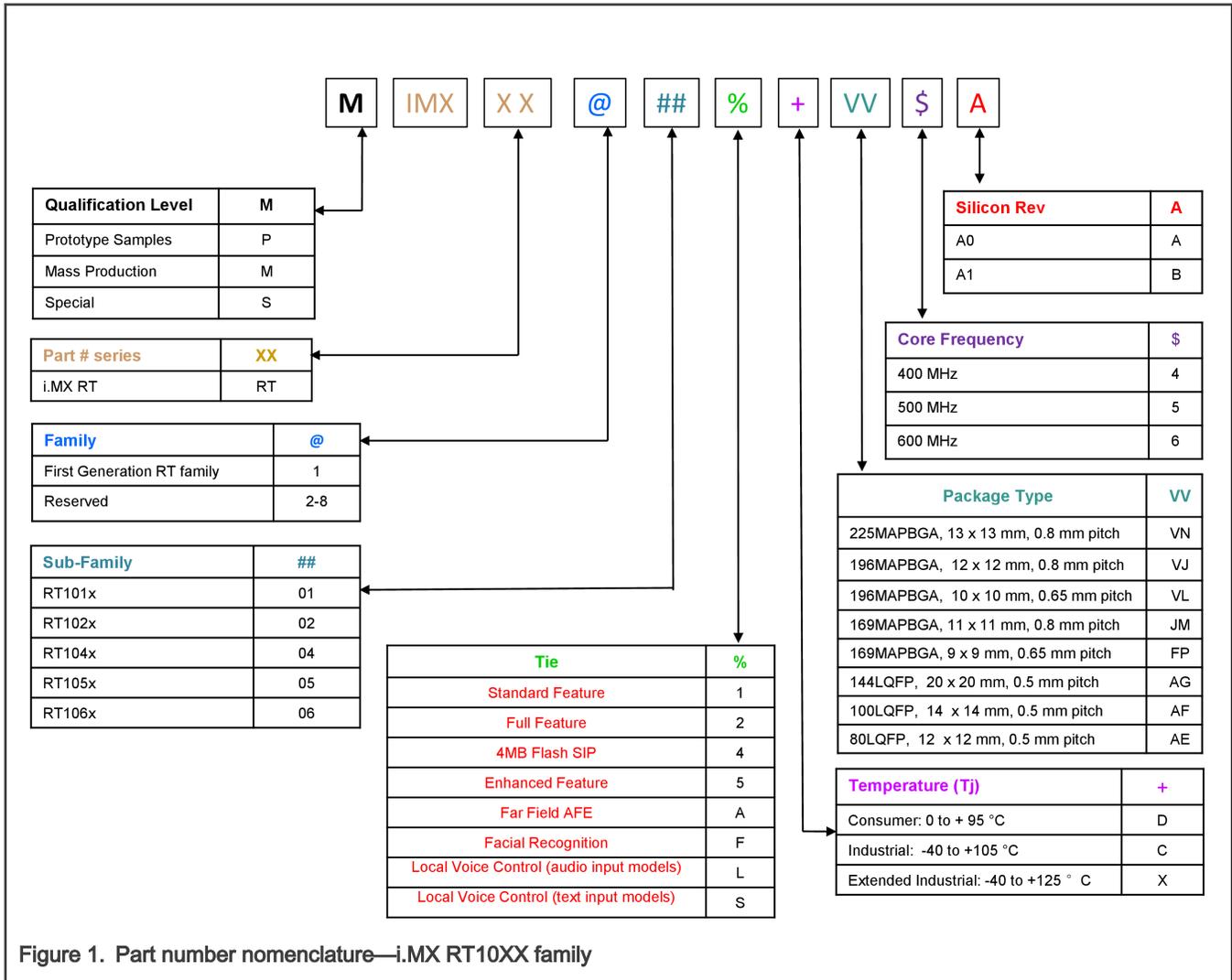


Figure 1. Part number nomenclature—i.MX RT10XX family

## 2 Architectural Overview

The following subsections provide an architectural overview of the i.MX RT1060X processor system.

### 2.1 Block diagram

Figure 2 shows the functional modules in the i.MX RT1060X processor system<sup>[1]</sup>.

[1] Some modules shown in this block diagram are not offered on all derivatives. See Table 9 for details.

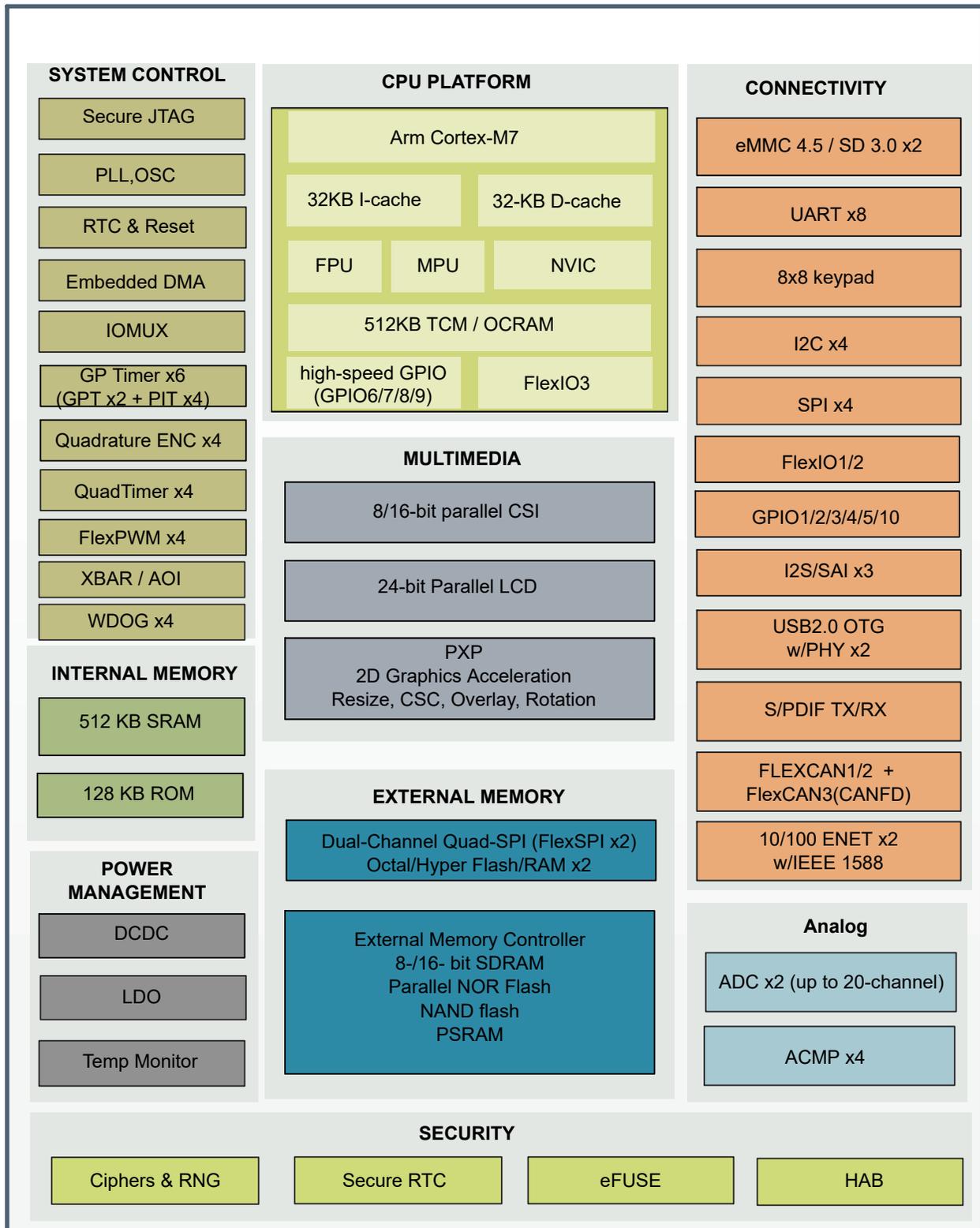


Figure 2. i.MX RT1060X system block diagram

### 3 Modules List

The i.MX RT1060X processors contain a variety of digital and analog modules. [Table 2](#) describes these modules in alphabetical order.

**Table 2. i.MX RT1060X modules list**

Block Mnemonic	Block Name	Subsystem	Brief Description
ACMP1 ACMP2 ACMP3 ACMP4	Analog Comparator	Analog	The comparator (CMP) provides a circuit for comparing two analog input voltages. The comparator circuit is designed to operate across the full range of the supply voltage (rail-to-rail operation).
ADC1 ADC2	Analog to Digital Converter	Analog	The ADC is a 12-bit general purpose analog to digital converter.
AOI	And-Or-Inverter	Cross Trigger	The AOI provides a universal boolean function generator using a four term sum of products expression with each product term containing true or complement values of the four selected inputs (A, B, C, D).
Arm	Arm Platform	Arm	The Arm Core Platform includes one Cortex-M7 core. It includes associated sub-blocks, such as Nested Vectored Interrupt Controller (NVIC), Floating-Point Unit (FPU), Memory Protection Unit (MPU), and CoreSight debug modules.
BEE	Bus Encryption Engine	Security	On-The-Fly FlexSPI Flash Decryption
CCM GPC SRC	Clock Control Module, General Power Controller, System Reset Controller	Clocks, Resets, and Power Control	These modules are responsible for clock and reset distribution in the system, and also for the system power management.
CSI	Parallel CSI	Multimedia Peripherals	The CSI IP provides parallel CSI standard camera interface port. The CSI parallel data ports are up to 24 bits. It is designed to support 24-bit RGB888/YUV444, CCIR656 video interface, 8-bit YCbCr, YUV or RGB, and 8-bit/10-bit/16-bit Bayer data input.
CSU	Central Security Unit	Security	The Central Security Unit (CSU) is responsible for setting comprehensive security policy within the i.MX RT1060X platform.
DAP	Debug Access Port	System Control Peripherals	The DAP provides real-time access for the debugger without halting the core to: <ul style="list-style-type: none"> <li>• System memory and peripheral registers</li> <li>• All debug configuration registers</li> </ul>

*Table continues on the next page...*

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
			The DAP also provides debugger access to JTAG scan chains. The DAP module is internal to the Cortex-M7 Core Platform.
DCDC	DCDC Converter	Analog	<p>The DCDC module is used for generating power supply for core logic. Main features are:</p> <ul style="list-style-type: none"> <li>• Adjustable high efficiency regulator</li> <li>• Supports 3.3 V input voltage</li> <li>• Supports nominal run and low power standby modes</li> <li>• Supports at 0.9 ~ 1.3 V output in run mode</li> <li>• Supports at 0.9 ~ 1.0 V output in standby mode</li> <li>• Over current and over voltage detection</li> </ul>
eDMA	enhanced Direct Memory Access	System Control Peripherals	<p>There is an enhanced DMA (eDMA) engine and two DMA_MUX.</p> <ul style="list-style-type: none"> <li>• The eDMA is a 32 channel DMA engine, which is capable of performing complex data transfers with minimal intervention from a host processor.</li> <li>• The DMA_MUX is capable of multiplexing up to 128 DMA request sources to the 32 DMA channels of eDMA.</li> </ul>
ENC	Quadrature Encoder/Decoder	Timer Peripherals	The enhanced quadrature encoder/decoder module provides interfacing capability to position/speed sensors. There are five input signals: PHASEA, PHASEB, INDEX, TRIGGER, and HOME. This module is used to decode shaft position, revolution count, and speed.
ENET	Ethernet Controller	Connectivity Peripherals	The Ethernet Media Access Controller (MAC) is designed to support 10/100 Mbit/s Ethernet/IEEE 802.3 networks. An external transceiver interface and transceiver function are required to complete the interface to the media. The module has dedicated hardware to support the IEEE 1588 standard. See the ENET chapter of the reference manual for details.
EWM	External Watchdog Monitor	Timer Peripherals	The EWM modules is designed to monitor external circuits, as well as the software flow. This provides a back-up mechanism to the internal WDOG that can reset the system. The EWM differs from the internal WDOG in that it does not reset the system. The EWM, if allowed to time-out, provides an independent trigger pin that when asserted resets or places an external circuit into a safe mode.

*Table continues on the next page...*

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
FLEXCAN1 FLEXCAN2	Flexible Controller Area Network	Connectivity Peripherals	The CAN protocol was primarily, but not only, designed to be used as a vehicle serial data bus, meeting the specific requirements of this field: real-time processing, reliable operation in the Electromagnetic interference (EMI) environment of a vehicle, cost-effectiveness and required bandwidth. The FlexCAN module is a full implementation of the CAN protocol specification, Version 2.0 B, which supports both standard and extended message frames.
FLEXCAN (FD)	Flexible Controller Area Network	Connectivity Peripherals	The CAN with Flexible Data-Rate protocol and the CAN 2.0 version B protocol supports both standard and extended message frames, both of them have long payloads up to 64 bytes transferred at faster rates up to 8 Mbps.
FlexIO1 FlexIO2	Flexible Input/output	Connectivity and Communications	The FlexIO is capable of supporting a wide range of protocols including, but not limited to: UART, I2C, SPI, I2S, camera interface, display interface, PWM waveform generation, etc. The module can remain functional when the chip is in a low power mode provided the clock it is using remain active.
FlexPWM1 FlexPWM2 FlexPWM3 FlexPWM4	Pulse Width Modulation	Timer Peripherals	The pulse-width modulator (PWM) contains four PWM sub-modules, each of which is set up to control a single half-bridge power stage. Fault channel support is provided. The PWM module can generate various switching patterns, including highly sophisticated waveforms.
FlexRAM	RAM	Memories	The i.MX RT1060X has 1 MB of on-chip RAM which could be flexible allocated to I-TCM, D-TCM, and on-chip RAM (OCRAM) in a 32 KB granularity. The FlexRAM is the manager of the on-chip RAM array. Major functions of this blocks are: interfacing to I-TCM and D-TCM of Arm core and OCRAM controller; dynamic RAM arrays allocation for I-TCM, D-TCM, and OCRAM.
FlexSPI	Quad Serial Peripheral Interface	Connectivity and Communications	FlexSPI acts as an interface to one or two external serial flash devices, each with up to four bidirectional data lines.
GPIO1 GPIO2 GPIO3 GPIO4 GPIO5	General Purpose I/O Modules	System Control Peripherals	Used for general purpose input/output to external ICs. Each GPIO module supports up to 32 bits of I/O.

*Table continues on the next page...*

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
GPT1 GPT2	General Purpose Timer	Timer Peripherals	Each GPT is a 32-bit "free-running" or "set and forget" mode timer with programmable prescaler and compare and capture register. A timer counter value can be captured using an external event and can be configured to trigger a capture event on either the leading or trailing edges of an input pulse. When the timer is configured to operate in "set and forget" mode, it is capable of providing precise interrupts at regular intervals with minimal processor intervention. The counter has output compare logic to provide the status and interrupt at comparison. This timer can be configured to run either on an external clock or on an internal clock.
KPP	Keypad Port	Human Machine Interfaces	The KPP is a 16-bit peripheral that can be used as a keypad matrix interface or as general purpose input/output (I/O). It supports 8 x 8 external key pad matrix. Main features are: <ul style="list-style-type: none"> <li>• Multiple-key detection</li> <li>• Long key-press detection</li> <li>• Standby key-press detection</li> <li>• Supports a 2-point and 3-point contact key matrix</li> </ul>
LCDIF	LCD interface	Multimedia Peripherals	The LCDIF is a general purpose display controller used to drive a wide range of display devices varying in size and capabilities. The LCDIF is designed to support dumb (synchronous 24-bit Parallel RGB interface) and smart (asynchronous parallel MPU interface) LCD devices.
LPI2C1 LPI2C2 LPI2C3 LPI2C4	Low Power Inter-integrated Circuit	Connectivity and Communications	The LPI2C is a low power Inter-Integrated Circuit (I2C) module that supports an efficient interface to an I2C bus as a master.  The I2C provides a method of communication between a number of external devices. For detailed information, see <a href="#">LPI2C module timing parameters</a> .
LPSP1 LPSP2 LPSP3 LPSP4	Low Power Serial Peripheral Interface	Connectivity and Communications	The LPSP1 is a low power Serial Peripheral Interface (SPI) module that support an efficient interface to an SPI bus as a master and/or a slave. <ul style="list-style-type: none"> <li>• It can continue operating while the chip is in stop modes, if an appropriate clock is available</li> <li>• Designed for low CPU overhead, with DMA off loading of FIFO register access</li> </ul>
LPUART1 LPUART2	UART Interface	Connectivity Peripherals	Each of the UART modules support the following serial data transmit/receive protocols and configurations: <ul style="list-style-type: none"> <li>• 7- or 8-bit data words, 1 or 2 stop bits, programmable</li> </ul>

Table continues on the next page...

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
LPUART3 LPUART4 LPUART5 LPUART6 LPUART7 LPUART8			<p>parity (even, odd or none)</p> <ul style="list-style-type: none"> <li>• Programmable baud rates up to 20 Mbps.</li> </ul>
MQS	Medium Quality Sound	Multimedia Peripherals	MQS is used to generate 2-channel medium quality PWM-like audio via two standard digital GPIO pins.
PXP	Pixel Processing Pipeline	Multimedia Peripherals	<p>A high-performance pixel processor capable of 1 pixel/clock performance for combined operations, such as color-space conversion, alpha blending, and rotation. The PXP is enhanced with features specifically for gray scale applications. In addition, the PXP supports traditional pixel/frame processing paths for still-image and video processing applications.</p>
QuadTimer1 QuadTimer2 QuadTimer3 QuadTimer4	QuadTimer	Timer Peripherals	The quad-timer provides four time channels with a variety of controls affecting both individual and multi-channel features. Specific features include up/down count, cascading of counters, programmable module, count once/repeated, counter preload, compare registers with preload, shared use of input signals, prescaler controls, independent capture/compare, fault input control, programmable input filters, and multi-channel synchronization.
ROMCP	ROM Controller with Patch	Memories and Memory Controllers	The ROMCP acts as an interface between the Arm advanced high-performance bus and the ROM. The on-chip ROM is only used by the Cortex-M7 core during boot up. Size of the ROM is 96 KB.
RTC OSC	Real Time Clock Oscillator	Clock Sources and Control	The RTC OSC provides the clock source for the Real-Time Clock module. The RTC OSC module, in conjunction with an external crystal, generates a 32.768 kHz reference clock for the RTC.
RTWDOG	Watch Dog	Timer Peripherals	The RTWDG module is a high reliability independent timer that is available for system to use. It provides a safety feature to ensure software is executing as planned and the CPU is not stuck in an infinite loop or executing unintended code. If the WDOG module is not

*Table continues on the next page...*

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
			serviced (refreshed) within a certain period, it resets the MCU. Windowed refresh mode is supported as well.
SAI1 SAI2 SAI3	Synchronous Audio Interface	Multimedia Peripherals	The SAI module provides a synchronous audio interface (SAI) that supports full duplex serial interfaces with frame synchronization, such as I2S, AC97, TDM, and codec/DSP interfaces.
SA-TRNG	Standalone True Random Number Generator	Security	The SA-TRNG is hardware accelerator that generates a 512-bit entropy as needed by an entropy consuming module or by other post processing functions.
SEMC	Smart External Memory Controller	Memory and Memory Controller	The SEMC is a multi-standard memory controller optimized for both high-performance and low pin-count. It can support multiple external memories in the same application with shared address and data pins. The interface supported includes SDRAM, NOR Flash, SRAM, and NAND Flash, as well as 8080 display interface.
SJC	System JTAG Controller	System Control Peripherals	<p>The SJC provides JTAG interface, which complies with JTAG TAP standards, to internal logic. The i.MX RT1060X processors use JTAG port for production, testing, and system debugging. In addition, the SJC provides BSR (Boundary Scan Register) standard support, which complies with IEEE 1149.1 and IEEE 1149.6 standards.</p> <p>The JTAG port is accessible during platform initial laboratory bring-up, for manufacturing tests and troubleshooting, as well as for software debugging by authorized entities. The i.MX RT1060X SJC incorporates three security modes for protecting against unauthorized accesses. Modes are selected through eFUSE configuration.</p>
SNVS	Secure Non-Volatile Storage	Security	Secure Non-Volatile Storage, including Secure Real Time Clock, Security State Machine, Master Key Control, Violation, and reporting.
SPDIF	Sony Philips Digital Interconnect Format	Multimedia Peripherals	A standard audio file transfer format, developed jointly by the Sony and Phillips corporations. Has Transmitter and Receiver functionality.
Temp Monitor	Temperature Monitor	Analog	The temperature sensor implements a temperature sensor/conversion function based on a temperature-dependent voltage to time conversion.
TSC	Touch Screen	Human Machine Interfaces	With touch controller to support 4-wire and 5-wire resistive touch panel.

*Table continues on the next page...*

Table 2. i.MX RT1060X modules list (continued)

Block Mnemonic	Block Name	Subsystem	Brief Description
USBO2	Universal Serial Bus 2.0	Connectivity Peripherals	<p>USBO2 (USB OTG1 and USB OTG2) contains:</p> <ul style="list-style-type: none"> <li>Two high-speed OTG 2.0 modules with integrated HS USB PHYs</li> <li>Support eight Transmit (TX) and eight Receive (Rx) endpoints, including endpoint 0</li> </ul>
uSDHC1 uSDHC2	SD/MMC and SDXC Enhanced Multi-Media Card / Secure Digital Host Controller	Connectivity Peripherals	<p>i.MX RT1060X specific SoC characteristics:</p> <p>All four MMC/SD/SDIO controller IPs are identical and are based on the uSDHC IP. They are:</p> <ul style="list-style-type: none"> <li>Fully compliant with MMC command/response sets and Physical Layer as defined in the Multimedia Card System Specification, v4.5/4.2/4.3/4.4/4.41/ including high-capacity (size &gt; 2 GB) cards HC MMC.</li> <li>Fully compliant with SD command/response sets and Physical Layer as defined in the SD Memory Card Specifications, v3.0 including high-capacity SDXC cards up to 2 TB.</li> <li>Fully compliant with SDIO command/response sets and interrupt/read-wait mode as defined in the SDIO Card Specification, Part E1, v3.0</li> </ul> <p>Two ports support:</p> <ul style="list-style-type: none"> <li>1-bit or 4-bit transfer mode specifications for SD and SDIO cards up to UHS-I SDR104 mode (104 MB/s max)</li> <li>1-bit, 4-bit, or 8-bit transfer mode specifications for MMC cards up to 52 MHz in both SDR and DDR modes (104 MB/s max)</li> <li>4-bit or 8-bit transfer mode specifications for eMMC chips up to 200 MHz in HS200 mode (200 MB/s max)</li> </ul>
WDOG1 WDOG2	Watch Dog	Timer Peripherals	<p>The watchdog (WDOG) Timer supports two comparison points during each counting period. Each of the comparison points is configurable to evoke an interrupt to the Arm core, and a second point evokes an external event on the WDOG line.</p>
XBAR	Cross BAR	Cross Trigger	<p>Each crossbar switch is an array of muxes with shared inputs. Each mux output provides one output of the crossbar. The number of inputs and the number of muxes/outputs are user configurable and registers are provided to select which of the shared inputs are routed to each output.</p>

### 3.1 Special signal considerations

Table 3 lists special signal considerations for the i.MX RT1060X processors. The signal names are listed in alphabetical order.

The package contact assignments can be found in [Package information and contact assignments](#). Signal descriptions are provided in the *i.MX RT1060X Reference Manual* (IMXRT1060XRM).

Table 3. Special signal considerations

Signal Name	Remarks
CCM_CLK1_P/ CCM_CLK1_N	<p>One general purpose differential high speed clock Input/output (LVDS I/O) is provided.</p> <p>It can be used:</p> <ul style="list-style-type: none"> <li>To feed external reference clock to the PLLs and further to the modules inside SoC.</li> <li>To output internal SoC clock to be used outside the SoC as either reference clock or as a functional clock for peripherals.</li> </ul> <p>See the <i>i.MX RT1060X Reference Manual</i> (IMXRT1060XRM) for details on the respective clock trees.</p> <p>Alternatively one may use single ended signal to drive CLK1_P input. In this case corresponding CLK1_N input should be tied to the constant voltage level equal 1/2 of the input signal swing.</p> <p>Termination should be provided in case of high frequency signals.</p> <p>ph&gt;</p> <p>After initialization, the CLK1 input/output can be disabled (if not used). If unused either or both of the CLK1_N/P pairs may remain unconnected.</p>
DCDC_PSWITCH	<p>PAD is in DCDC_IN domain and connected the ground to bypass DCDC.</p> <p>To enable DCDC function, assert to DCDC_PSWITCH with at least 1ms delay for DCDC_IN rising edge.</p>
RTC_XTALI/RTC_XTALO	<p>If the user wishes to configure RTC_XTALI and RTC_XTALO as an RTC oscillator, a 32.768 kHz crystal, (<math>\leq 100</math> k<math>\Omega</math> ESR, 10 pF load) should be connected between RTC_XTALI and RTC_XTALO. Keep in mind the capacitors implemented on either side of the crystal are about twice the crystal load capacitor. To hit the exact oscillation frequency, the board capacitors need to be reduced to account for board and chip parasitics. The integrated oscillation amplifier is self biasing, but relatively weak. Care must be taken to limit parasitic leakage from RTC_XTALI and RTC_XTALO to either power or ground (<math>&gt;100</math> M<math>\Omega</math>). This will debias the amplifier and cause a reduction of start-up margin. Typically RTC_XTALI and RTC_XTALO should bias to approximately 0.5 V.</p> <p>If it is desired to feed an external low frequency clock into RTC_XTALI the RTC_XTALO pin must remain unconnected or driven with a complimentary signal. The logic level of this forcing clock should not exceed VDD_SNV5_CAP level and the frequency should be <math>&lt;100</math> kHz under typical conditions.</p> <p>In case when high accuracy real time clock are not required system may use internal low frequency ring oscillator. It is recommended to connect RTC_XTALI to GND and keep RTC_XTALO unconnected.</p>
XTALI/XTALO	<p>A 24.0 MHz crystal should be connected between XTALI and XTALO.</p> <p>The crystal must be rated for a maximum drive level of 250 <math>\mu</math>W. An ESR (equivalent series resistance) up to 80 <math>\Omega</math> and CL less than 12pF is recommended. NXP SDK software requires 24 MHz on XTALI/XTALO.</p>

Table continues on the next page...

Table 3. Special signal considerations (continued)

Signal Name	Remarks
	<p>The crystal can be eliminated if an external 24 MHz oscillator is available in the system. In this case, XTALO must be directly driven by the external oscillator and XTALI mounted with 18 pF capacitor. The logic level of this forcing clock cannot exceed NVCC_PLL level.</p> <p>If this clock is used as a reference for USB, then there are strict frequency tolerance and jitter requirements. See OSC24M chapter and relevant interface specifications chapters for details.</p>
GPANAIO	This signal is reserved for NXP manufacturing use only. This output must remain unconnected.
JTAG_####	<p>The JTAG interface is summarized in <a href="#">Table 4</a>. Use of external resistors is unnecessary. However, if external resistors are used, the user must ensure that the on-chip pull-up/down configuration is followed. For example, do not use an external pull down on an input that has on-chip pull-up.</p> <p>JTAG_TDO is configured with a keeper circuit such that the non-connected condition is eliminated if an external pull resistor is not present. An external pull resistor on JTAG_TDO is detrimental and should be avoided.</p> <p>JTAG_MOD is referenced as SJC_MOD in the i.MX RT1060X reference manual (IMXRT1060XRM). Both names refer to the same signal. JTAG_MOD must be externally connected to GND for normal operation. Termination to GND through an external pull-down resistor (such as 1 kΩ) is allowed. JTAG_MOD set to hi configures the JTAG interface to mode compliant with IEEE1149.1 standard. JTAG_MOD set to low configures the JTAG interface for common SW debug adding all the system TAPs to the chain.</p>
NC	These signals are No Connect (NC) and should be disconnected by the user.
POR_B	<p>This cold reset negative logic input resets all modules and logic in the IC.</p> <p>May be used in addition to internally generated power on reset signal (logical AND, both internal and external signals are considered active low).</p>
ONOFF	ONOFF can be configured in debounce, off to on time, and max time-out configurations. The debounce and off to on time configurations supports 0, 50, 100 and 500 ms. Debounce is used to generate the power off interrupt. While in the ON state, if ONOFF button is pressed longer than the debounce time, the power off interrupt is generated. Off to on time supports the time it takes to request power on after a configured button press time has been reached. While in the OFF state, if ONOFF button is pressed longer than the off to on time, the state will transition from OFF to ON. Max time-out configuration supports 5, 10, 15 seconds and disable. Max time-out configuration supports the time it takes to request power down after ONOFF button has been pressed for the defined time.
TEST_MODE	TEST_MODE is for NXP factory use. The user can leave this signal floating or tie it to ground.
WAKEUP	A GPIO powered by SNVS domain power supply which can be configured as wakeup source in SNVS mode.

**Table 4. JTAG Controller interface summary**

JTAG	I/O Type	On-chip Termination
JTAG_TCK	Input	100 kΩ pull-down
JTAG_TMS	Input	47 kΩ pull-up
JTAG_TDI	Input	47 kΩ pull-up
JTAG_TDO	3-state output	Keeper
JTAG_TRSTB	Input	47 kΩ pull-up
JTAG_MOD	Input	100 kΩ pull-down

### 3.2 Recommended connections for unused analog interfaces

Table 5 shows the recommended connections for unused analog interfaces.

**Table 5. Recommended connections for unused analog interfaces**

Module	Pad Name	Recommendations if Unused
CCM	CCM_CLK1_N, CCM_CLK1_P	Not connected
USB	USB_OTG1_CHD_B, USB_OTG1_DN, USB_OTG1_DP, USB_OTG1_VBUS, USB_OTG2_DN, USB_OTG2_DP, USB_OTG2_VBUS	Not connected
ADC	VDDA_ADC_3P3	VDDA_ADC_3P3 must be powered even if the ADC is not used.

## 4 Electrical Characteristics

This section provides the device and module-level electrical characteristics for the i.MX RT1060X processors.

### 4.1 Chip-Level conditions

This section provides the device-level electrical characteristics for the IC. See Table 6 for a quick reference to the individual tables and sections.

**Table 6. i.MX RT1060X chip-Level conditions**

For these characteristics, refer to
<a href="#">Absolute maximum ratings</a>
<a href="#">Thermal resistance</a>
<a href="#">Operating ranges</a>

*Table continues on the next page...*

**Table 6. i.MX RT1060X chip-Level conditions (continued)**

For these characteristics, refer to
External clock sources
Maximum supply currents
Low power mode supply currents
USB PHY current consumption

### 4.1.1 Absolute maximum ratings

**NOTE**

Stress beyond those listed under [Table 7](#) may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

[Table 7](#) shows the absolute maximum operating ratings.

**Table 7. Absolute maximum ratings**

Parameter Description	Symbol	Min	Max	Unit
Core supplies input voltage	VDD_SOC_IN	-0.3	1.6	V
VDD_HIGH_IN supply voltage	VDD_HIGH_IN	-0.3	3.7	V
Power for DCDC	DCDC_IN	-0.3	3.6	V
Supply input voltage to Secure Non-Volatile Storage and Real Time Clock	VDD_SNVS_IN	-0.3	3.6	V
USB VBUS supply	USB_OTG1_VBUS USB_OTG2_VBUS	—	5.5	V
Supply for 12-bit ADC	VDDA_ADC	-0.3	3.6	V
IO supply for GPIO in SDIO1 bank (3.3 V mode)	NVCC_SD0	-0.3	3.6	V
IO supply for GPIO in SDIO1 bank (1.8 V mode)		-0.3	1.95	V
IO supply for GPIO in SDIO2 bank (3.3 V mode)	NVCC_SD1	-0.3	3.6	V
IO supply for GPIO in SDIO2 bank (1.8 V mode)		-0.3	1.95	V
IO supply for GPIO in EMC bank (3.3 V mode)	NVCC_EMCC	-0.3	3.6	V
IO supply for GPIO in EMC bank (1.8 V mode)		-0.3	1.95	V
ESD damage Immunity: Human Body Model (HBM)	Vesd	—	1000	V
		—	500	

*Table continues on the next page...*

**Table 7. Absolute maximum ratings (continued)**

Parameter Description	Symbol	Min	Max	Unit
Charge Device Model (CDM)				
Input/Output Voltage range	$V_{in}/V_{out}$	-0.5	OVDD + 0.3 <sup>1</sup>	V
Storage Temperature range	$T_{STORAGE}$	-40	150	°C

1. OVDD is the I/O supply voltage.

### 4.1.2 Thermal resistance

#### 4.1.2.1 13 x 13 mm thermal resistance

Table 8 shows the 13 x 13 mm package thermal resistance data.

**Table 8. 13 x 13 mm thermal resistance data**

Rating	Board type <sup>1</sup>	Symbol	Value	Unit
Junction to Ambient Thermal resistance <sup>2</sup>	JESD51-9, 2s2p	$R_{\theta JA}$	36	°C/W
Junction to Package Top Thermal resistance <sup>2</sup>	JESD51-9, 2s2p	$\Psi_{JT}$	0.5	°C/W

1. Thermal test board meets JEDEC specification for this package (JESD51-9).
2. Determined in accordance to JEDEC JESD51-2A natural convection environment. Thermal resistance data in this report is solely for a thermal performance comparison of one package to another in a standardized specified environment. It is not meant to predict the performance of a package in an application-specific environment.

### 4.1.3 Operating ranges

Table 9 provides the operating ranges of the i.MX RT1060X processors. For details on the chip's power structure, see the "Power Management Unit (PMU)" chapter of the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

**Table 9. Operating ranges**

Parameter Description	Symbol	Operating Conditions	Min	Typ	Max <sup>1</sup>	Unit	Comment
Run Mode	VDD_SOC_IN	Overdrive	1.25	—	1.3	V	—
	VDD_SOC_IN	M7 core at 528 MHz	1.15	—	1.3	V	—
		M7 core at 132 MHz	1.15	—	1.3		
		M7 core at 24 MHz	0.925	—	1.3		

Table continues on the next page...

Table 9. Operating ranges (continued)

Parameter Description	Symbol	Operating Conditions	Min	Typ	Max <sup>1</sup>	Unit	Comment
IDLE Mode	VDD_SOC_IN	M7 core operation at 528 MHz or below	1.15	—	1.3	V	—
SUSPEND (DSM) Mode	VDD_SOC_IN	—	0.925	—	1.3	V	Refer to <a href="#">Table 12</a> current and power consumption
SNVS Mode	VDD_SOC_IN	—	0	—	1.3	V	—
Power for DCDC	DCDC_IN	—	3.0	—	3.6	V	—
VDD_HIGH internal Regulator	VDD_HIGH_IN <sup>2</sup>	—	3.0	—	3.6	V	Must match the range of voltages that the rechargeable backup battery supports.
Backup battery supply range	VDD_SNVS_IN <sup>3</sup>	—	2.40	—	3.6	V	Can be combined with VDD_HIGH_IN, if the system does not require keeping real time and other data on OFF state.
USB supply voltages	USB_OTG1_VBUS	—	4.40	—	5.5	V	—
	USB_OTG2_VBUS	—	4.40	—	5.5	V	—
GPIO supplies	NVCC_GPIO	—	3.0	3.3	3.6	V	All digital I/O supplies (NVCC_xxxx) must be powered (unless otherwise specified in this data sheet) under normal conditions whether the associated I/O pins are in use or not.
			1.65	1.8	1.95	V	
	3.0	3.3	3.6	V			
	NVCC_SD1	—	1.65	1.8	1.95	V	
			3.0	3.3	3.6	V	
	NVCC EMC	—	1.65	1.8	1.95	V	
3.0			3.3	3.6	V		
A/D converter	VDDA_ADC_3P3	—	3.0	3.3	3.6	V	VDDA_ADC_3P3 must be powered even if the ADC is not used.  VDDA_ADC_3P3 cannot be powered when the other SoC supplies (except VDD_SNVS_IN) are off.
System frequency /Bus frequency	F <sub>SYS</sub> /F <sub>BUS</sub>	—	24/ 24	528/ 132	600/ 150	MHz	—

Table continues on the next page...

Table 9. Operating ranges (continued)

Parameter Description	Symbol	Operating Conditions	Min	Typ	Max <sup>1</sup>	Unit	Comment
Temperature Operating Ranges							
Junction temperature	T <sub>j</sub>	Standard Commercial	0-40	—	9510 5	°C	See the application note, i.MX RT1060X Product Lifetime Usage Estimates for information on product lifetime (power-on years) for this processor.

1. Applying the maximum voltage results in maximum power consumption and heat generation. NXP recommends a voltage set point = (V<sub>min</sub> + the supply tolerance). This result in an optimized power/speed ratio.
2. Applying the maximum voltage results in shorten lifetime. 3.6 V usage limited to < 1% of the use profile. Reset of profile limited to below 3.49 V.
3. In setting VDD\_SNVS\_IN voltage with regards to Charging Currents and RTC, refer to the *i.MX RT1060 Hardware Development Guide* (IMXRT1060HDG).

#### 4.1.4 External clock sources

Each i.MX RT1060X processor has two external input system clocks: a low frequency (RTC\_XTALI) and a high frequency (XTALI).

The RTC\_XTALI is used for low-frequency functions. It supplies the clock for wake-up circuit, power-down real time clock operation, and slow system and watch-dog counters. The clock input can be connected to either external oscillator or a crystal using internal oscillator amplifier. Additionally, there is an internal ring oscillator, which can be used instead of the RTC\_XTALI if accuracy is not important.

The system clock input XTALI is used to generate the main system clock. It supplies the PLLs and other peripherals. The system clock input can be connected to either external oscillator or a crystal using internal oscillator amplifier.

Table 10 shows the interface frequency requirements.

Table 10. External input clock frequency

Parameter Description	Symbol	Min	Typ	Max	Unit
RTC_XTALI Oscillator <sup>1,2</sup>	f <sub>ckil</sub>	—	32.768 <sup>3</sup> /32.0	—	kHz
XTALI Oscillator <sup>2,4</sup>	f <sub>xtal</sub>	—	24	—	MHz

1. External oscillator or a crystal with internal oscillator amplifier.
2. The required frequency stability of this clock source is application dependent.
3. Recommended nominal frequency 32.768 kHz.
4. External oscillator or a fundamental frequency crystal with internal oscillator amplifier.

The typical values shown in Table 10 are required for use with NXP SDK to ensure precise time keeping and USB operation. For RTC\_XTALI operation, two clock sources are available.

- On-chip 40 kHz ring oscillator—this clock source has the following characteristics:
  - Approximately 25 μA more I<sub>dd</sub> than crystal oscillator
  - Approximately ±50% tolerance
  - No external component required
  - Starts up quicker than 32 kHz crystal oscillator
- External crystal oscillator with on-chip support circuit:

- At power up, ring oscillator is utilized. After crystal oscillator is stable, the clock circuit switches over to the crystal oscillator automatically.
- Higher accuracy than ring oscillator
- If no external crystal is present, then the ring oscillator is utilized

The decision of choosing a clock source should be taken based on real-time clock use and precision time-out.

#### 4.1.5 Maximum supply currents

The data shown in [Table 11](#) represent a use case designed specifically to show the maximum current consumption possible. All cores are running at the defined maximum frequency and are limited to L1 cache accesses only to ensure no pipeline stalls. Although a valid condition, it would have a very limited practical use case, if at all, and be limited to an extremely low duty cycle unless the intention were to specifically show the worst case power consumption.

See the *i.MX RT1060X Power Consumption Measurement Application Note* for more details on typical power consumption under various use case definitions.

**Table 11. Maximum supply currents**

Power Rail	Conditions	Max Current	Unit
DCDC_IN	Max power for chip at 95 °C with core mark run on FlexRAM	110	mA
VDD_HIGH_IN	Include internal loading in analog	50	mA
VDD_SNVS_IN	—	250	µA
USB_OTG1_VBUS USB_OTG2_VBUS	25 mA for each active USB interface	50	mA
VDDA_ADC_3P3	3.3 V power supply for 12-bit ADC, 600 µA typical, 750 µA max, for each ADC. 100 Ohm max loading for touch panel, cause 33 mA current.	40	mA
NVCC_GPIO NVCC_SD0 NVCC_SD1 NVCC_EMC NVCC_SPI0 NVCC_SPI1	$I_{max} = N \times C \times V \times (0.5 \times F)$ Where: N—Number of IO pins supplied by the power line C—Equivalent external capacitive load V—IO voltage (0.5 x F)—Data change rate. Up to 0.5 of the clock rate (F) In this equation, I <sub>max</sub> is in Amps, C in Farads, V in Volts, and F in Hertz.		

#### 4.1.6 Low power mode supply currents

[Table 12](#) shows the current core consumption (not including I/O) of i.MX RT1060X processors in selected low power modes.

**Table 12. Low power mode current and power consumption**

Mode	Test Conditions	Supply	Typical <sup>1</sup>	Units
------	-----------------	--------	----------------------	-------

*Table continues on the next page...*

**Table 12. Low power mode current and power consumption (continued)**

SYSTEM IDLE	<ul style="list-style-type: none"> <li>LDO_2P5 set to 2.5 V, LDO_1P1 set to 1.1 V</li> <li>CPU in WFI, CPU clock gated</li> <li>24 MHz XTAL is ON</li> <li>System PLL is active, other PLLs are power down</li> <li>Peripheral clock gated, but remain powered</li> <li>1024 KB RAM retention</li> </ul>	DCDC_IN (3.3 V)	4.04	mA
		VDD_HIGH_IN (3.3 V)	7.66	
		VDD_SNVS_IN (3.3 V)	0.032	
		Total	38.72	mW
LOW POWER IDLE	<ul style="list-style-type: none"> <li>LDO_2P5 and LDO_1P1 are set to Weak mode</li> <li>WFI, half FlexRAM power down in power gate mode</li> <li>All PLLs are power down</li> <li>24 MHz XTAL is off, 24 MHz RCOSC used as clock source</li> <li>Peripheral clock gated, but remain powered</li> <li>1024 KB RAM retention</li> </ul>	DCDC_IN (3.3 V)	1.11	mA
		VDD_HIGH_IN (3.3 V)	0.309	
		VDD_SNVS_IN (3.3 V)	0.048	
		Total	4.84	mW
SUSPEND (DSM)	<ul style="list-style-type: none"> <li>LDO_2P5 and LDO_1P1 are shut off</li> <li>CPU in Power Gate mode</li> <li>All PLLs are power down</li> <li>24 MHz XTAL is off, 24 MHz RCOSC is off</li> <li>All clocks are shut off, except 32 kHz RTC</li> <li>Peripheral clock gated, but remain powered</li> <li>64 KB RAM retention</li> </ul>	DCDC_IN (3.3 V)	0.19	mA
		VDD_HIGH_IN (3.3 V)	0.029	
		VDD_SNVS_IN (3.3 V)	0.020	
		Total	0.789	mW
SNVS (RTC)	<ul style="list-style-type: none"> <li>All SOC digital logic, analog module are shut off</li> <li>32 kHz RTC is alive</li> </ul>	DCDC_IN (0 V)	0	mA
		VDD_HIGH_IN (0 V)	0	
		VDD_SNVS_IN (3.3 V)	0.02	
		Total	0.066	mW

1. The typical values shown here are for information only and are not guaranteed. These values are average values measured on a typical process wafer at 25°C.

## 4.1.7 USB PHY current consumption

### 4.1.7.1 Power down mode

In power down mode, everything is powered down, including the USB VBUS valid detectors in typical condition. [Table 13](#) shows the USB interface current consumption in power down mode.

**Table 13. USB PHY current consumption in power down mode**

	VDD_USB_CAP (3.0 V)	VDD_HIGH_CAP (2.5 V)	NVCC_PLL (1.1 V)
Current	5.1 $\mu$ A	1.7 $\mu$ A	< 0.5 $\mu$ A

**NOTE**

The currents on the VDD\_HIGH\_CAP and VDD\_USB\_CAP were identified to be the voltage divider circuits in the USB-specific level shifters.

## 4.2 System power and clocks

This section provide the information about the system power and clocks.

### 4.2.1 Power supplies requirements and restrictions

The system design must comply with power-up sequence, power-down sequence, and steady state guidelines as described in this section to guarantee the reliable operation of the device. Any deviation from these sequences may result in the following situations:

- Excessive current during power-up phase
- Prevention of the device from booting
- Irreversible damage to the processor (worst-case scenario)

#### 4.2.1.1 Power-up sequence

The below restrictions must be followed:

- VDD\_SNVS\_IN supply must be turned on before any other power supply or be connected (shorted) with VDD\_HIGH\_IN supply.
- If a coin cell is used to power VDD\_SNVS\_IN, then ensure that it is connected before any other supply is switched on.
- An RC delay circuit is recommended for providing the delay between DCDC\_IN stable and DCDC\_PSWITCH. The total RC delay should be 5-15 ms.
- DCDC\_IN must reach a minimum 3.0 V within  $0.3 \times RC$ .
- Delay from DCDC\_IN stable at 3.0 V min to DCDC\_PSWITCH reaching  $0.5 \times DCDC\_IN$  (1.5 V) must be at least 1 ms.
- Power up slew rate specification for other power domains is 360V/s – 36kV/s.

**NOTE**

The POR\_B input (if used) must be immediately asserted at power-up and remain asserted until after the last power rail reaches its working voltage. In the absence of an external reset feeding the POR\_B input, the internal POR module takes control. See the *i.MX RT1060X Reference Manual* (IMXRT106X0RM) for further details and to ensure that all necessary requirements are being met.

**NOTE**

Need to ensure that there is no back voltage (leakage) from any supply on the board towards the 3.3 V supply (for example, from the external components that use both the 1.8 V and 3.3 V supplies).

**NOTE**

USB\_OTG1\_VBUS, USB\_OTG2\_VBUS, and VDDA\_ADC\_3P3 are not part of the power supply sequence and may be powered at any time.

#### 4.2.1.2 Power-down sequence

The following restrictions must be followed:

- VDD\_SNVS\_IN supply must be turned off after any other power supply or be connected (shorted) with VDD\_HIGH\_IN supply.
- If a coin cell is used to power VDD\_SNVS\_IN, then ensure that it is removed after any other supply is switched off.

### 4.2.1.3 Power supplies usage

All I/O pins should not be externally driven while the I/O power supply for the pin (NVCC\_XXX) is OFF. This can cause internal latch-up and malfunctions due to reverse current flows. For information about I/O power supply of each pin, see "Power Rail" columns in pin list tables of [Package information and contact assignments](#).

## 4.2.2 Integrated LDO voltage regulator parameters

Various internal supplies can be powered ON from internal LDO voltage regulators. All the supply pins named \*\_CAP must be connected to external capacitors. The on-board LDOs are intended for internal use only and should not be used to power any external circuitry. See the *i.MX RT1060X Reference Manual* (IMXRT1060XRM) for details on the power tree scheme.

### NOTE

The \*\_CAP signals should not be powered externally. These signals are intended for internal LDO operation only.

### 4.2.2.1 Digital regulators (LDO\_SNVS)

There are one digital LDO regulator ("Digital", because of the logic loads that they drive, not because of their construction). The advantages of the regulator is to reduce the input supply variation because of its input supply ripple rejection and its on-die trimming. This translates into more stable voltage for the on-chip logics.

The regulator has two basic modes:

- Power Gate. The regulation FET is switched fully off limiting the current draw from the supply. The analog part of the regulator is powered down here limiting the power consumption.
- Analog regulation mode. The regulation FET is controlled such that the output voltage of the regulator equals the target voltage.

For additional information, see the *i.MX RT1060X Reference Manual* (IMXRT1060XRM).

### 4.2.2.2 Regulators for analog modules

#### 4.2.2.2.1 LDO\_1P1

The LDO\_1P1 regulator implements a programmable linear-regulator function from VDD\_HIGH\_IN (see [Table 9](#) for minimum and maximum input requirements). Typical Programming Operating Range is 1.0 V to 1.2 V with the nominal default setting as 1.1 V. The LDO\_1P1 supplies the USB PHY, and PLLs. A programmable brown-out detector is included in the regulator that can be used by the system to determine when the load capability of the regulator is being exceeded to take the necessary steps. Current-limiting can be enabled to allow for in-rush current requirements during start-up, if needed. Active-pull-down can also be enabled for systems requiring this feature.

For additional information, see the *i.MX RT1060X Reference Manual* (IMXRT1060XRM).

#### 4.2.2.2.2 LDO\_2P5

The LDO\_2P5 module implements a programmable linear-regulator function from VDD\_HIGH\_IN (see [Table 9](#) for minimum and maximum input requirements). Typical Programming Operating Range is 2.25 V to 2.75 V with the nominal default setting as 2.5 V. LDO\_2P5 supplies the USB PHY, E-fuse module, and PLLs. A programmable brown-out detector is included in the regulator that can be used by the system to determine when the load capability of the regulator is being exceeded, to take the necessary steps. Current-limiting can be enabled to allow for in-rush current requirements during start-up, if needed. Active-pull-down can also be enabled for systems requiring this feature. An alternate self-biased low-precision weak-regulator is included that can be enabled for applications needing to keep the output voltage alive during low-power modes where the main regulator driver and its associated global bandgap reference module are disabled. The output of the weak-regulator is not programmable and is a function

of the input supply as well as the load current. Typically, with a 3 V input supply the weak-regulator output is 2.525 V and its output impedance is approximately 40  $\Omega$ .

For additional information, see the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

**Table 14. LDO\_2P5 Voltage Regulator Electrical Specifications**

Parameter	Symbol	Min	Typ	Max	Unit
Input Analog Supply		2.7	3	3.3	V
Input Digital Supply		1.0	1	1.1	V
Typical Current Consumption			0.75		mA
Typical Low Power Current Consumption			0.05		mA
Regulator Maximum Output Current (at 500 mV drop-out)		350			mA
Regulator Output Programming Range (default 2.5 V)		2		2.75	V
Regulator Output Programming Step Size			25		mV
Regulator Brown-out Offset Programming Range (default 75 mV)		0		75	mV
Regulator Brown-out Offset Programming Step Size			25		mV
Minimum External Decoupling Capacitor (Low-ESR)			1		$\mu$ F

#### 4.2.2.2.3 LDO\_USB

The LDO\_USB module implements a programmable linear-regulator function from the USB VBUS voltages (4.4 V–5.5 V) to produce a nominal 3.0 V output voltage. A programmable brown-out detector is included in the regulator that can be used by the system to determine when the load capability of the regulator is being exceeded, to take the necessary steps. This regulator has a built in power-mux that allows the user to select to run the regulator from either USB VBUS supply, when both are present. If only one of the USB VBUS voltages is present, then, the regulator automatically selects this supply. Current limit is also included to help the system meet in-rush current targets.

For additional information, see the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

#### 4.2.2.2.4 DCDC

DCDC can be configured to operate on power-save mode when the load current is less than 50 mA. During the power-save mode, the converter operates with reduced switching frequency in PFM mode and with a minimum quiescent current to maintain high efficiency.

DCDC can detect the peak current in the P-channel switch. When the peak current exceeds the threshold, DCDC will give an alert signal, and the threshold can be configured. By this way, DCDC can roughly detect the current loading.

DCDC also includes the following protection functions:

- Over current protection. In run mode, DCDC shuts down when detecting abnormal large current in the P-type power switch.

- Over voltage protection. DCDC shuts down when detecting the output voltage is too high.
- Low voltage detection. DCDC shuts down when detecting the input voltage is too low.

For additional information, see the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

The following table shows the LDO\_USB Voltage Regulator Electrical Specifications.

### 4.2.3 PLL's electrical characteristics

This section provides PLL electrical characteristics.

#### 4.2.3.1 Audio/Video PLL's electrical parameters

Table 15. Audio/Video PLL's electrical parameters

Parameter	Value
Clock output range	650 MHz ~1.3 GHz
Reference clock	24 MHz
Lock time	< 11250 reference cycles

#### 4.2.3.2 System PLL

Table 16. System PLL's electrical parameters

Parameter	Value
Clock output range	528 MHz PLL output
Reference clock	24 MHz
Lock time	< 11250 reference cycles

#### 4.2.3.3 Ethernet PLL

Table 17. Ethernet PLL's electrical parameters

Parameter	Value
Clock output range	1 GHz
Reference clock	24 MHz
Lock time	< 11250 reference cycles

#### 4.2.3.4 USB PLL

Table 18. USB PLL's electrical parameters

Parameter	Value
Clock output range	480 MHz PLL output

*Table continues on the next page...*

**Table 18. USB PLL's electrical parameters (continued)**

Parameter	Value
Reference clock	24 MHz
Lock time	< 383 reference cycles

#### 4.2.4 Arm PLL

**Table 19. Arm PLL's electrical parameters**

Parameter	Value
Clock output range	648 MHz ~ 1296 MHz
Reference clock	24 MHz
Lock time	< 2250 reference cycles

#### 4.2.5 On-chip oscillators

##### 4.2.5.1 OSC24M

This block implements an amplifier that when combined with a suitable quartz crystal and external load capacitors implement an oscillator. The oscillator is powered from NVCC\_PLL.

The system crystal oscillator consists of a Pierce-type structure running off the digital supply. A straight forward biased-inverter implementation is used.

##### 4.2.5.2 OSC32K

This block implements an amplifier that when combined with a suitable quartz crystal and external load capacitors implement a low power oscillator. It also implements a power mux such that it can be powered from either a ~3 V backup battery (VDD\_SNVS\_IN) or VDD\_HIGH\_IN such as the oscillator consumes power from VDD\_HIGH\_IN when that supply is available and transitions to the backup battery when VDD\_HIGH\_IN is lost.

In addition, if the clock monitor determines that the OSC32K is not present, then the source of the 32 K will automatically switch to a crude internal ring oscillator. The frequency range of this block is approximately 10–45 kHz. It highly depends on the process, voltage, and temperature.

The OSC32k runs from VDD\_SNVS\_CAP supply, which comes from the VDD\_HIGH\_IN/VDD\_SNVS\_IN. The target battery is a ~3 V coin cell. Proper choice of coin cell type is necessary for chosen VDD\_HIGH\_IN range. Appropriate series resistor (Rs) must be used when connecting the coin cell. Rs depends on the charge current limit that depends on the chosen coin cell. For example, for Panasonic ML621:

- Average Discharge Voltage is 2.5 V
- Maximum Charge Current is 0.6 mA

For a charge voltage of 3.2 V,  $R_s = (3.2-2.5)/0.6 \text{ m} = 1.17 \text{ k}$ .

**Table 20. OSC32K main characteristics**

	Min	Typ	Max	Comments
Fosc	—	32.768 kHz	—	This frequency is nominal and determined mainly by the crystal selected. 32.0 K would work as well.
Current consumption	—	4 $\mu$ A	—	The 4 $\mu$ A is the consumption of the oscillator alone (OSC32k). Total supply consumption will depend on what the digital portion of the RTC consumes. The ring oscillator consumes 1 $\mu$ A when ring oscillator is inactive, 20 $\mu$ A when the ring oscillator is running. Another 1.5 $\mu$ A is drawn from vdd_rtc in the power_detect block. So, the total current is 6.5 $\mu$ A on vdd_rtc when the ring oscillator is not running.
Bias resistor	—	14 M $\Omega$	—	This integrated bias resistor sets the amplifier into a high gain state. Any leakage through the ESD network, external board leakage, or even a scope probe that is significant relative to this value will debias the amp. The debiasing will result in low gain, and will impact the circuit's ability to start up and maintain oscillations.
<b>Crystal Properties</b>				
Cload	—	10 pF	—	Usually crystals can be purchased tuned for different Cloads. This Cload value is typically 1/2 of the capacitances realized on the PCB on either side of the quartz. A higher Cload will decrease oscillation margin, but increases current oscillating through the crystal.
ESR	—	50 k $\Omega$	100 k $\Omega$	Equivalent series resistance of the crystal. Choosing a crystal with a higher value will decrease the oscillating margin.

### 4.3 I/O parameters

This section provide parameters on I/O interfaces.

#### 4.3.1 I/O DC parameters

This section includes the DC parameters of the following I/O types:

- XTALI and RTC\_XTALI (Clock Inputs) DC Parameters
- General Purpose I/O (GPIO)
- LVDS I/O DC Parameters

**NOTE**

The term 'NVCC\_XXXX' in this section refers to the associated supply rail of an input or output.

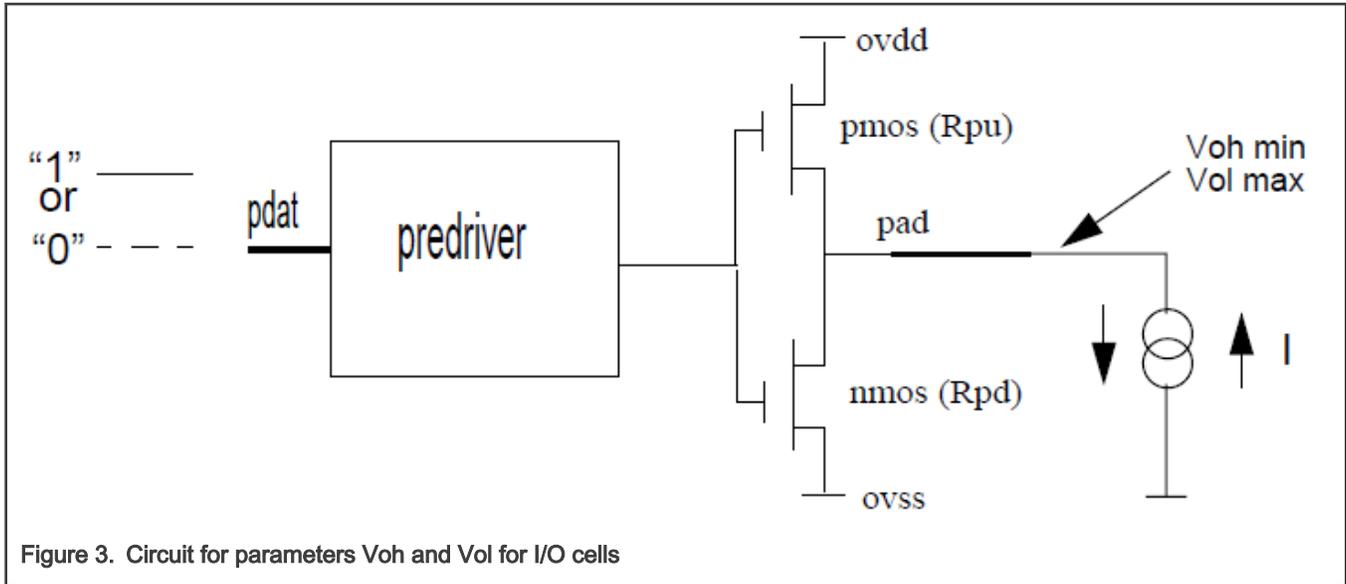


Figure 3. Circuit for parameters Voh and Vol for I/O cells

4.3.1.1 XTALI and RTC\_XTALI (clock inputs) DC parameters

Table 21 shows the DC parameters for the clock inputs.

Table 21. XTALI and RTC\_XTALI DC parameters<sup>1</sup>

Parameter	Symbol	Test Conditions	Min	Max	Unit
XTALI high-level DC input voltage	Vih	—	0.8 x NVCC_PLL	NVCC_PLL	V
XTALI low-level DC input voltage	Vil	—	0	0.2	V
RTC_XTALI high-level DC input voltage	Vih	—	0.8	1.1	V
RTC_XTALI low-level DC input voltage	Vil	—	0	0.2	V

1. The DC parameters are for external clock input only.

4.3.1.2 Single voltage general purpose I/O (GPIO) DC parameters

Table 22 shows DC parameters for GPIO pads. The parameters in Table 22 are guaranteed per the operating ranges in Table 9, unless otherwise noted.

Table 22. Single voltage GPIO DC parameters

Parameter	Symbol	Test Conditions	Min	Typical	Max	Units
High-level output voltage <sup>1</sup>	VOH	loh= -0.1mA (ipp_dse=001,010) loh= -1mA (ipp_dse=011,100,101,110,111)	NVCC_XXX X-0.15	—	—	V
Low-level output voltage <sup>1</sup>	VOL	lol= 0.1mA (ipp_dse=001,010) lol= 1mA	—	—	0.15	V

Table continues on the next page...

Table 22. Single voltage GPIO DC parameters (continued)

Parameter	Symbol	Test Conditions	Min	Typical	Max	Units
		(ipp_dse=011,100,101,110,111 )				
High-level output current	I <sub>OH</sub>	V <sub>DDE</sub> = 3.3 V, V <sub>OH</sub> = V <sub>DDE</sub> - 0.45 V, ipp_dse as follows: 001 010 011 110 101 110 111	—	-1 -1 -2 -2 -4 -4	—	mA
Low-level output current	I <sub>OL</sub>	V <sub>DDE</sub> = 3.3 V, V <sub>OL</sub> = 0.45 V, ipp_dse as follows: 001 010 011 110 101 110 111	—	1 1 2 2 4 4	—	mA
High-Level input voltage <sup>1,2</sup>	V <sub>IH</sub>	—	0.7 x NVCC_XXX X	—	NVCC_XX XX	V
Low-Level input voltage <sup>1,2</sup>	V <sub>IL</sub>	—	0	—	0.3 x NVCC_XX XX	V
Input Hysteresis (NVCC_XXXX= 1.8V)	VHYS_LowV DD	NVCC_XXXX=1.8V	250	—	—	mV
Input Hysteresis (NVCC_XXXX=3.3V)	VHYS_High VDD	NVCC_XXXX=3.3V	250	—	—	mV
Schmitt trigger VT <sup>+2,3</sup>	V <sub>TH+</sub>	—	0.5 x NVCC_XXX X	—	—	mV

Table continues on the next page...

**Table 22. Single voltage GPIO DC parameters (continued)**

Parameter	Symbol	Test Conditions	Min	Typical	Max	Units
Schmitt trigger VT <sup>2,3</sup>	VTH-	—	—	—	0.5 x NVCC_XX XX	mV
Pull-up resistor (22_kΩ PU)	RPU_22K	Vin=0V	—	—	212	μA
Pull-up resistor (22_kΩ PU)	RPU_22K	Vin=NVCC_XXXX	—	—	1	μA
Pull-up resistor (47_kΩ PU)	RPU_47K	Vin=0V	—	—	100	μA
Pull-up resistor (47_kΩ PU)	RPU_47K	Vin=NVCC_XXXX	—	—	1	μA
Pull-up resistor (100_kΩ PU)	RPU_100K	Vin=0V	—	—	48	μA
Pull-up resistor (100_kΩ PU)	RPU_100K	Vin=NVCC_XXXX	—	—	1	μA
Pull-down resistor (100_kΩ PD)	RPD_100K	Vin=NVCC_XXXX	—	—	48	μA
Pull-down resistor (100_kΩ PD)	RPD_100K	Vin=0V	—	—	1	μA
Input current (no PU/PD)	IIN	VI = 0, VI = NVCC_XXXX	-1	—	1	μA
Keeper Circuit Resistance	R_Keeper	VI = 0.3 x NVCC_XXXX, VI = 0.7 x NVCC_XXXX	105	—	175	kΩ

1. Overshoot and undershoot conditions (transitions above NVCC\_XXXX and below GND) on switching pads must be held below 0.6 V, and the duration of the overshoot/undershoot must not exceed 10% of the system clock cycle. Overshoot/undershoot must be controlled through printed circuit board layout, transmission line impedance matching, signal line termination, or other methods. Non-compliance to this specification may affect device reliability or cause permanent damage to the device.
2. To maintain a valid level, the transition edge of the input must sustain a constant slew rate (monotonic) from the current DC level through to the target DC level, Vil or Vih. Monotonic input transition time is from 0.1 ns to 1 s.
3. Hysteresis of 250 mV is guaranteed over all operating conditions when hysteresis is enabled.

**4.3.1.3 LVDS I/O DC parameters**

The LVDS interface complies with TIA/EIA 644-A standard. See TIA/EIA STANDARD 644-A, "Electrical Characteristics of Low Voltage Differential Signaling (LVDS) Interface Circuits" for details.

Table 23 shows the Low Voltage Differential Signaling (LVDS) I/O DC parameters.

**Table 23. LVDS I/O DC characteristics<sup>1</sup>**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Output Differential Voltage	VOD	Rload-100 Ω Diff	250	350	450	mV
Output High Voltage	VOH	IOH = 0 mA	1.25	1.375	1.6	V

*Table continues on the next page...*

**Table 23. LVDS I/O DC characteristics<sup>1</sup> (continued)**

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Output Low Voltage	VOL	IOL = 0 mA	0.9	1.025	1.25	V
Offset Voltage	VOS	—	1.125	1.2	1.375	V

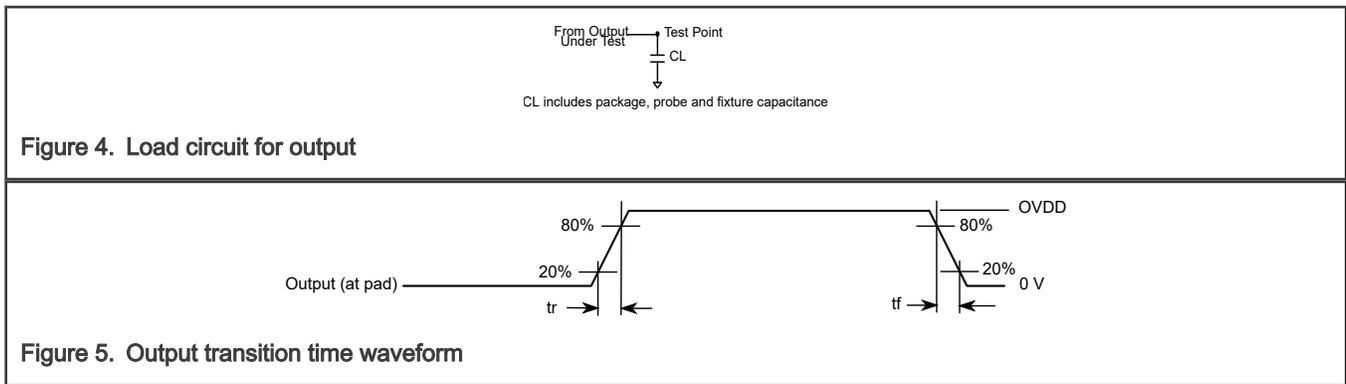
1. The LVDS interface is limited to CCM\_CLK1\_P and CCM\_CLK1\_N.

### 4.3.2 I/O AC parameters

This section includes the AC parameters of the following I/O types:

- General Purpose I/O (GPIO)

Figure 4 shows load circuit for output, and Figure 5 shows the output transition time waveform.



#### 4.3.2.1 General purpose I/O AC parameters

The I/O AC parameters for GPIO in slow and fast modes are presented in the Table 24 and Table 25, respectively. Note that the fast or slow I/O behavior is determined by the appropriate control bits in the IOMUXC control registers.

**Table 24. General purpose I/O AC parameters 1.8 V mode**

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Pad Transition Times, rise/fall (Max Drive, ipp_dse=111)	tr, tf	15 pF Cload, slow slew rate	—	—	2.72/2.79	ns
		15 pF Cload, fast slew rate	—	—	1.51/1.54	
Output Pad Transition Times, rise/fall (High Drive, ipp_dse=101)	tr, tf	15 pF Cload, slow slew rate	—	—	3.20/3.36	
		15 pF Cload, fast slew rate	—	—	1.96/2.07	
Output Pad Transition Times, rise/fall (Medium Drive, ipp_dse=100)	tr, tf	15 pF Cload, slow slew rate	—	—	3.64/3.88	
		15 pF Cload, fast slew rate	—	—	2.27/2.53	
Output Pad Transition Times, rise/fall (Low Drive, ipp_dse=011)	tr, tf	15 pF Cload, slow slew rate	—	—	4.32/4.50	
		15 pF Cload, fast slew rate	—	—	3.16/3.17	
Input Transition Times <sup>1</sup>	trm	—	—	—	25	ns

1. Hysteresis mode is recommended for inputs with transition times greater than 25 ns.

Table 25. General purpose I/O AC parameters 3.3 V mode

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output Pad Transition Times, rise/fall (Max Drive, ipp_dse=101)	tr, tf	15 pF Cload, slow slew rate	—	—	1.70/1.79	ns
		15 pF Cload, fast slew rate	—	—	1.06/1.15	ns
Output Pad Transition Times, rise/fall (High Drive, ipp_dse=011)	tr, tf	15 pF Cload, slow slew rate	—	—	2.35/2.43	
		15 pF Cload, fast slew rate	—	—	1.74/1.77	
Output Pad Transition Times, rise/fall (Medium Drive, ipp_dse=010)	tr, tf	15 pF Cload, slow slew rate	—	—	3.13/3.29	
		15 pF Cload, fast slew rate	—	—	2.46/2.60	
Output Pad Transition Times, rise/fall (Low Drive, ipp_dse=001)	tr, tf	15 pF Cload, slow slew rate	—	—	5.14/5.57	
		15 pF Cload, fast slew rate	—	—	4.77/5.15	
Input Transition Times <sup>1</sup>	trm	—	—	—	25	ns

1. Hysteresis mode is recommended for inputs with transition times greater than 25 ns.

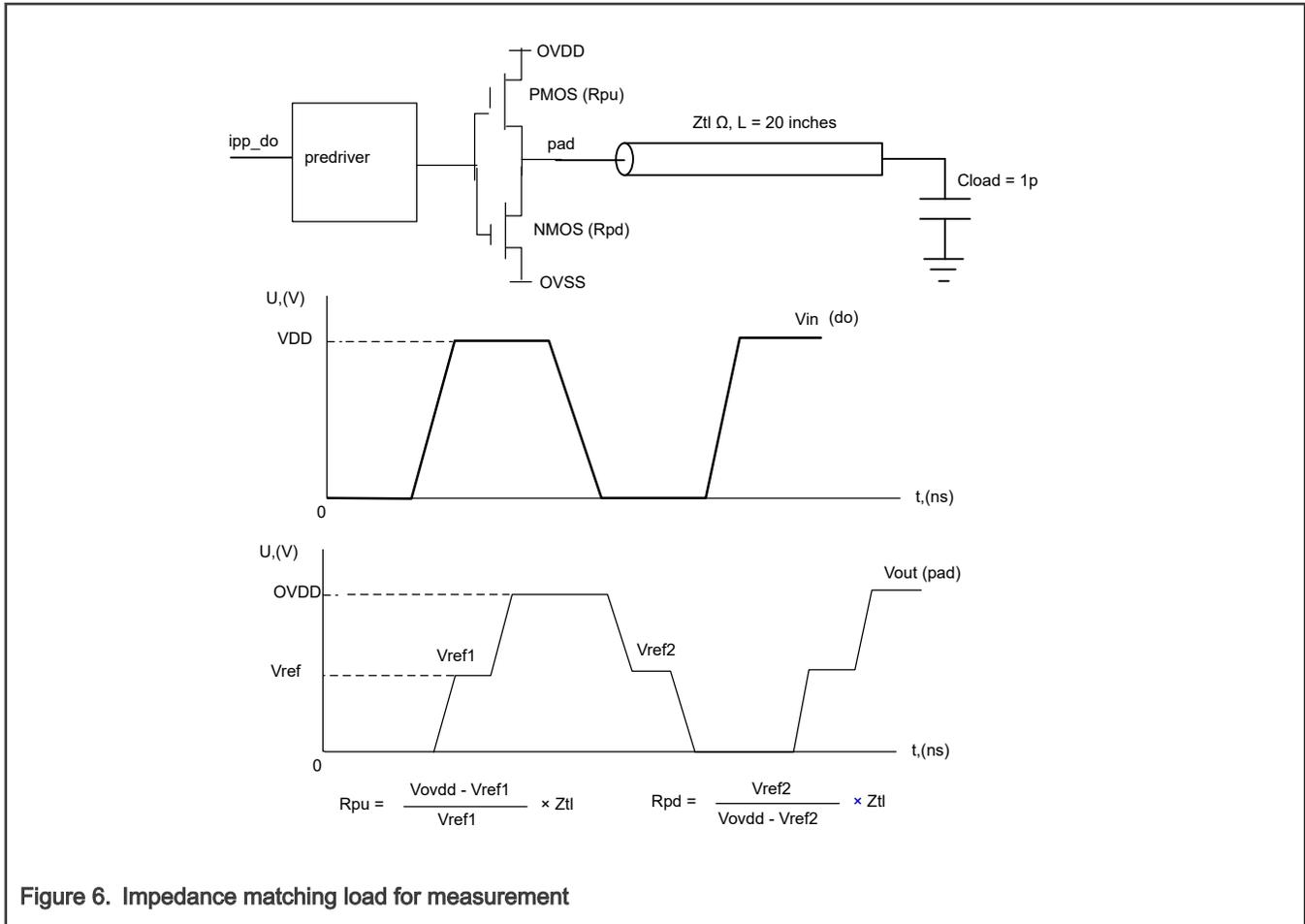
### 4.3.3 Output buffer impedance parameters

This section defines the I/O impedance parameters of the i.MX RT1060X processors for the following I/O types:

- Single Voltage General Purpose I/O (GPIO)

#### NOTE

GPIO I/O output driver impedance is measured with "long" transmission line of impedance  $Z_{tl}$  attached to I/O pad and incident wave launched into transmission line.  $R_{pu}/R_{pd}$  and  $Z_{tl}$  form a voltage divider that defines specific voltage of incident wave relative to  $NVCC\_XXXX$ . Output driver impedance is calculated from this voltage divider (see [Figure 6](#)).



#### 4.3.3.1 Single voltage GPIO output buffer impedance

Table 26 shows the GPIO output buffer impedance (NVCC\_XXXX 1.8 V).

Table 26. GPIO output buffer average impedance (NVCC\_XXXX 1.8 V)

Parameter	Symbol	Drive Strength (DSE)	Typ Value	Unit
Output Driver Impedance	Rdrv	001	260	Ω
		010	130	
		011	88	
		100	65	
		101	52	
		110	43	
		111	37	

Table 27 shows the GPIO output buffer impedance (NVCC\_XXXX 3.3 V).

Table 27. GPIO output buffer average impedance (NVCC\_XXXX 3.3 V)

Parameter	Symbol	Drive Strength (DSE)	Typ Value	Unit
Output Driver Impedance	Rdrv	001	157	Ω
		010	78	
		011	53	
		100	39	
		101	32	
		110	26	
		111	23	

### 4.4 System modules

This section contains the timing and electrical parameters for the modules in the i.MX i.MX RT1060X processor.

#### 4.4.1 Reset timings parameters

Figure 7 shows the reset timing and Table 28 lists the timing parameters.

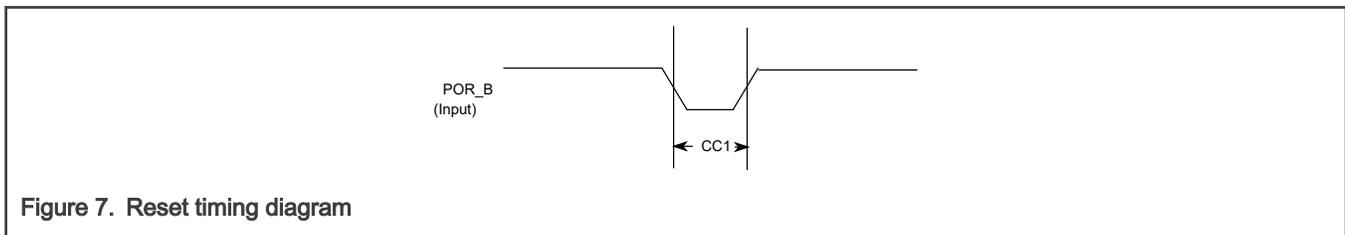


Figure 7. Reset timing diagram

Table 28. Reset timing parameters

ID	Parameter	Min	Max	Unit
CC1	Duration of POR_B to be qualified as valid.	1	—	RTC_XTALI cycle

#### 4.4.2 WDOGn reset timing parameters

Figure 8 shows the WDOGn reset timing and Table 29 lists the timing parameters.

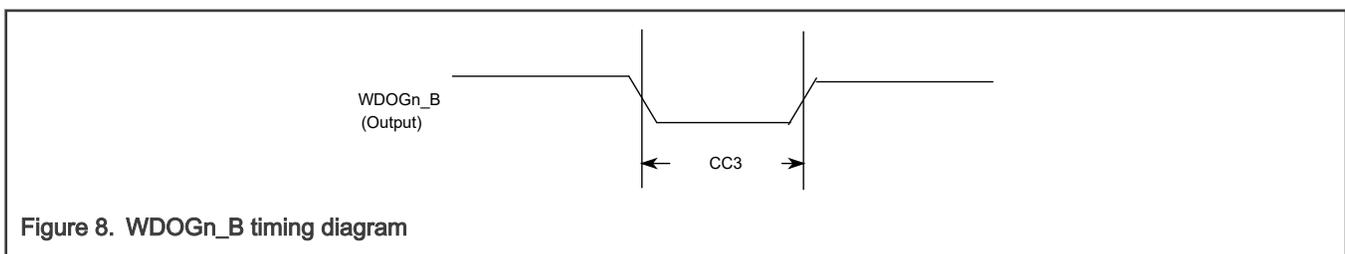


Figure 8. WDOGn\_B timing diagram

Table 29. WDOGn\_B timing parameters

ID	Parameter	Min	Max	Unit
CC3	Duration of WDOGn_B Assertion	1	—	RTC_XTALI cycle

**NOTE**

RTC\_XTALI is approximately 32 kHz. RTC\_XTALI cycle is one period or approximately 30  $\mu$ s.

**NOTE**

WDOGn\_B output signals (for each one of the Watchdog modules) do not have dedicated pins, but are muxed out through the IOMUX. See the IOMUX manual for detailed information.

**4.4.3 SCAN JTAG Controller (SJC) timing parameters**

Figure 9 depicts the SJC test clock input timing. Figure 10 depicts the SJC boundary scan timing. Figure 11 depicts the SJC test access port. Signal parameters are listed in Table 30.

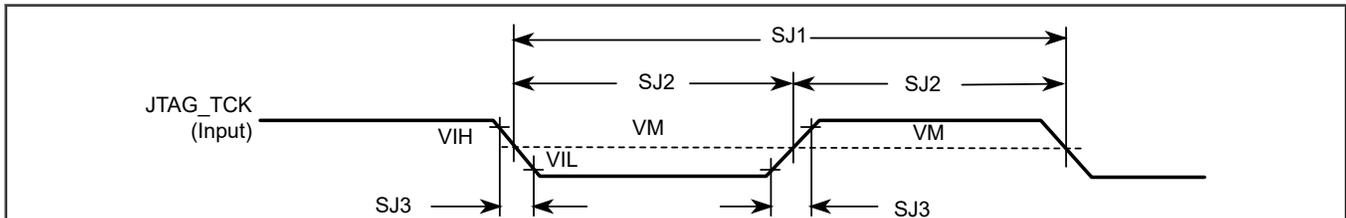


Figure 9. Test clock input timing diagram

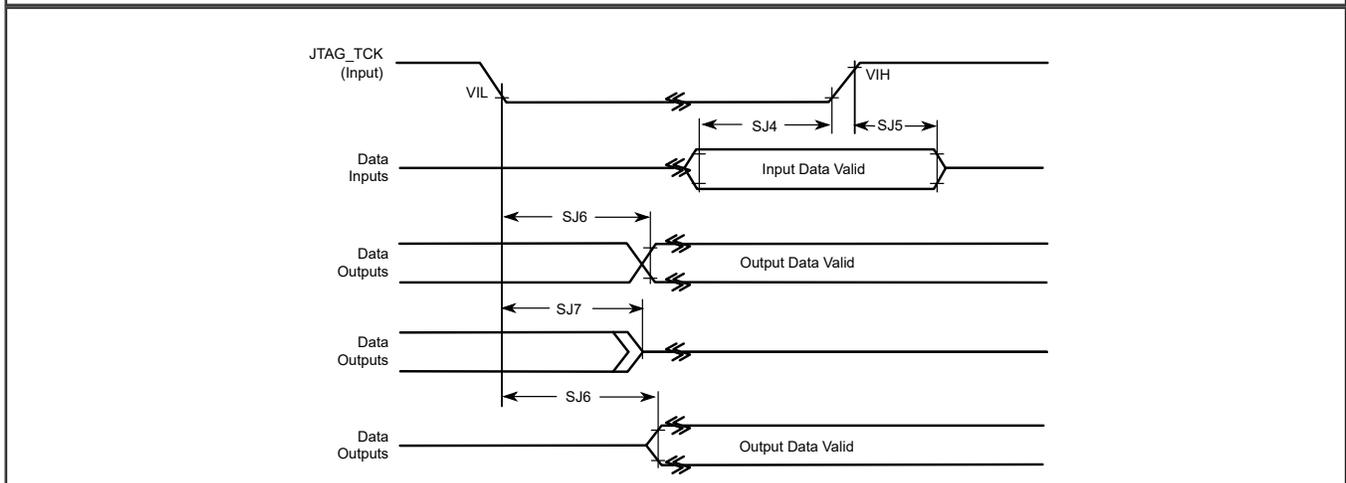


Figure 10. Boundary Scan (JTAG) timing diagram

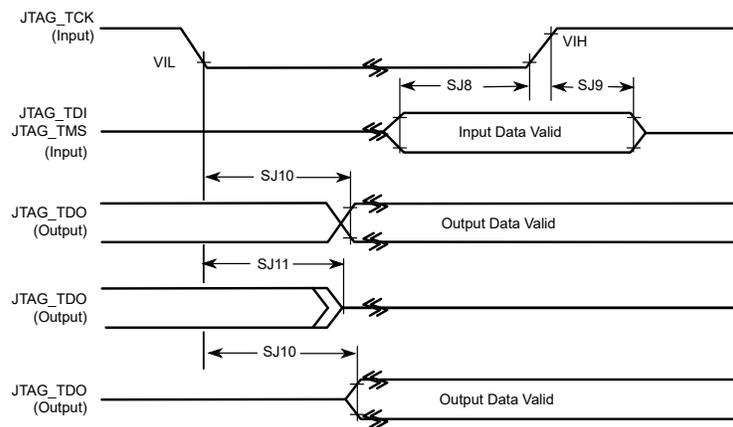


Figure 11. Test access port timing diagram

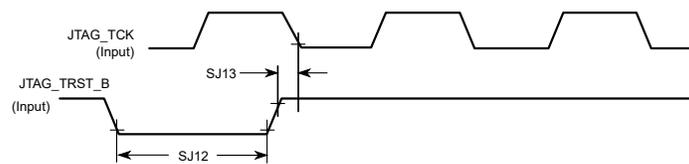


Figure 12. JTAG\_TRST\_B timing diagram

Table 30. JTAG timing

ID	Parameter <sup>1,2</sup>	All Frequencies		Unit
		Min	Max	
SJ0	JTAG_TCK frequency of operation $1/(3 \cdot T_{DC})^1$	0.001	22	MHz
SJ1	JTAG_TCK cycle time in crystal mode	45	—	ns
SJ2	JTAG_TCK clock pulse width measured at $V_M^2$	22.5	—	ns
SJ3	JTAG_TCK rise and fall times	—	3	ns
SJ4	Boundary scan input data set-up time	5	—	ns
SJ5	Boundary scan input data hold time	24	—	ns
SJ6	JTAG_TCK low to output data valid	—	40	ns
SJ7	JTAG_TCK low to output high impedance	—	40	ns
SJ8	JTAG_TMS, JTAG_TDI data set-up time	5	—	ns
SJ9	JTAG_TMS, JTAG_TDI data hold time	25	—	ns
SJ10	JTAG_TCK low to JTAG_TDO data valid	—	44	ns

Table continues on the next page...

Table 30. JTAG timing (continued)

ID	Parameter <sup>1,2</sup>	All Frequencies		Unit
		Min	Max	
SJ11	JTAG_TCK low to JTAG_TDO high impedance	—	44	ns
SJ12	JTAG_TRST_B assert time	100	—	ns
SJ13	JTAG_TRST_B set-up time to JTAG_TCK low	40	—	ns

1.  $T_{DC}$  = target frequency of SJC
2.  $V_M$  = mid-point voltage

#### 4.4.4 Debug trace timing specifications

Table 31. Debug trace operating behaviors

Symbol	Description	Min	Max	Unit
T1	ARM_TRACE_CLK frequency of operation	—	70	MHz
T2	ARM_TRACE_CLK period	1/T1	—	MHz
T3	Low pulse width	6	—	ns
T4	High pulse width	6	—	ns
T5	Clock and data rise time	—	1	ns
T6	Clock and data fall time	—	1	ns
T7	Data setup	2	—	ns
T8	Data hold	0.7	—	ns

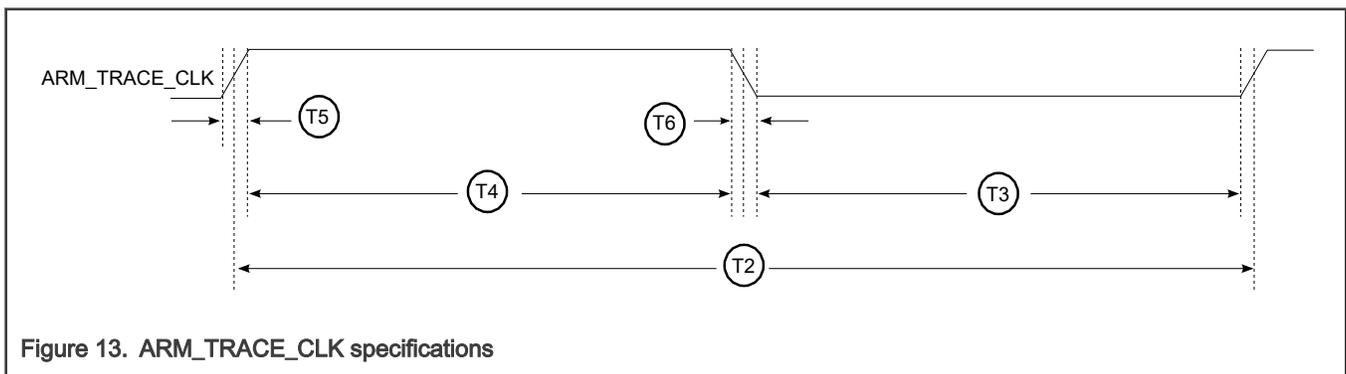


Figure 13. ARM\_TRACE\_CLK specifications

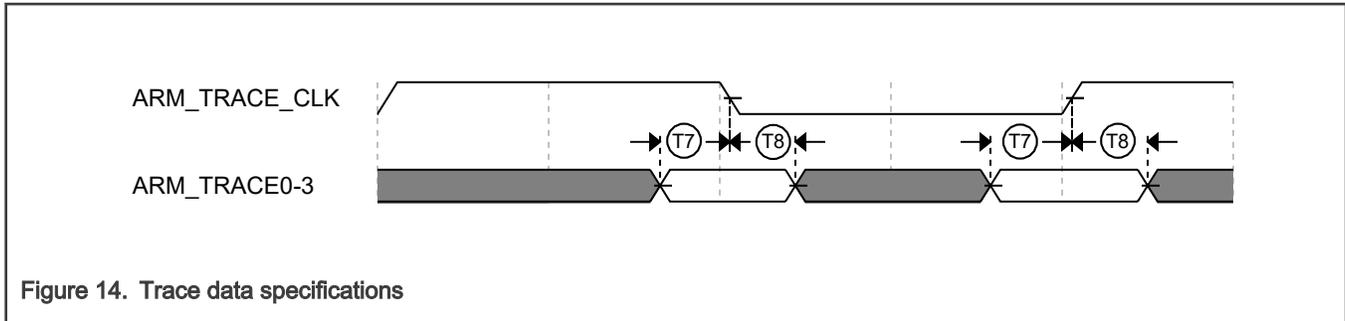


Figure 14. Trace data specifications

## 4.5 External memory interface

The following sections provide information about external memory interfaces.

### 4.5.1 SEMC specifications

The following sections provide information on SEMC interface.

Measurements are with a load of 15 pf and an input slew rate of 1 V/ns.

#### 4.5.1.1 SEMC output timing

There are ASYNC and SYNC mode for SEMC output timing.

##### 4.5.1.1.1 SEMC output timing in ASYNC mode

Table 32 shows SEMC output timing in ASYNC mode.

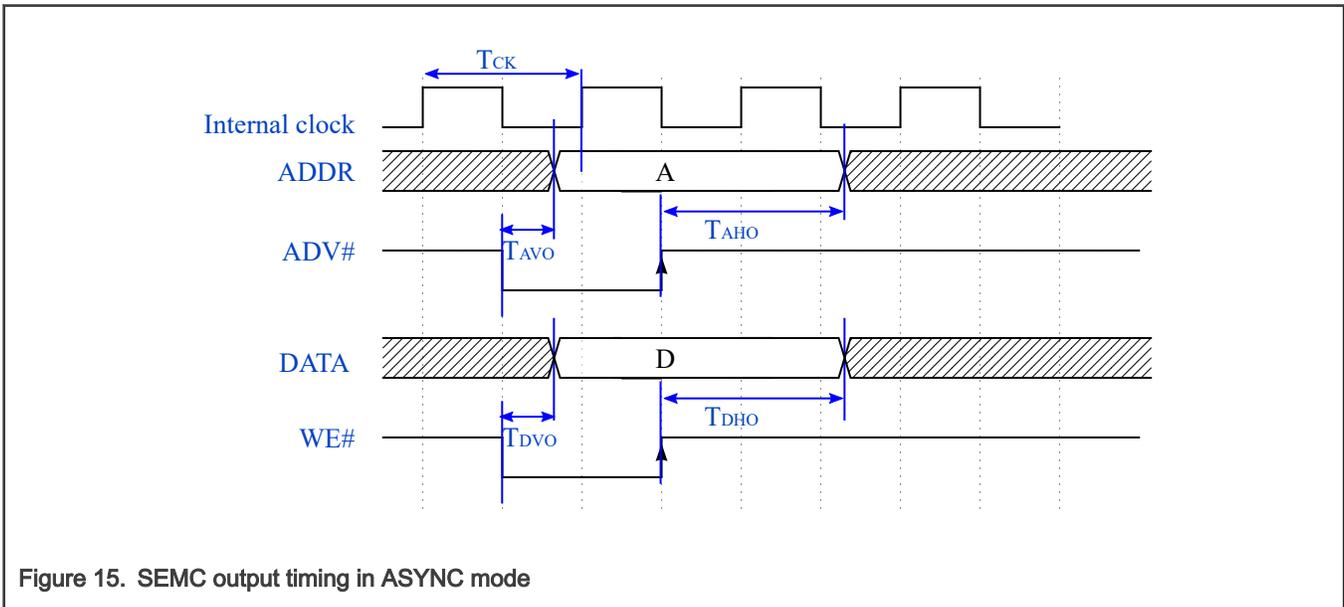
Table 32. SEMC output timing in ASYNC mode

Symbol	Parameter	Min.	Max.	Unit	Comment
	Frequency of operation	—	166	MHz	
T <sub>CK</sub>	Internal clock period	6	—	ns	
T <sub>AVO</sub>	Address output valid time	—	2	ns	These timing parameters apply to Address and ADV# for NOR/PSRAM in ASYNC mode.
T <sub>AHO</sub>	Address output hold time	(T <sub>CK</sub> - 2) <sup>1</sup>	—	ns	
T <sub>ADVL</sub>	ADV# low time	(T <sub>CK</sub> - 1) <sup>2</sup>			
T <sub>DVO</sub>	Data output valid time	—	2	ns	These timing parameters apply to Data/CLE/ALE and WE# for NAND, apply to Data/DM/CRE for NOR/PSRAM, apply to Data/DCX and WRX for DBI interface.
T <sub>DHO</sub>	Data output hold time	(T <sub>CK</sub> - 2) <sup>3</sup>	—	ns	
T <sub>WEL</sub>	WE# low time	(T <sub>CK</sub> - 1) <sup>4</sup>		ns	

1. Address output hold time is configurable by SEMC\_\*CR0.AH. AH field setting value is 0x0 in above table. When AH is set with value N, T<sub>AHO</sub> min time should be ((N + 1) × T<sub>CK</sub>). See the *i.MX RT1060X Reference Manual (IMXRT1060XRM)* for more detail about SEMC\_\*CR0.AH register field.
2. ADV# low time is configurable by SEMC\_\*CR0.AS. AS field setting value is 0x0 in above table. When AS is set with value N, T<sub>ADL</sub> min time should be ((N + 1) × T<sub>CK</sub> - 1). See the *i.MX RT1060X Reference Manual (IMXRT1060XRM)* for more detail about SEMC\_\*CR0.AS register field.
3. Data output hold time is configurable by SEMC\_\*CR0.WEH. WEH field setting value is 0x0 in above table. When WEH is set with value N, T<sub>DHO</sub> min time should be ((N + 1) × T<sub>CK</sub>). See the *i.MX RT1060X Reference Manual (IMXRT1060XRM)* for more detail about SEMC\_\*CR0.WEH register field.

- WE# low time is configurable by SEMC\_\*CR0.WEL. WEL field setting value is 0x0 in above table. When WEL is set with value N,  $T_{WEL}$  min time should be  $((N + 1) \times T_{CK} - 1)$ . See the *i.MX RT1060X Reference Manual (IMXRT1060XRM)* for more detail about SEMC\_\*CR0.WEL register field.

Figure 15 shows the output timing in ASYNC mode.



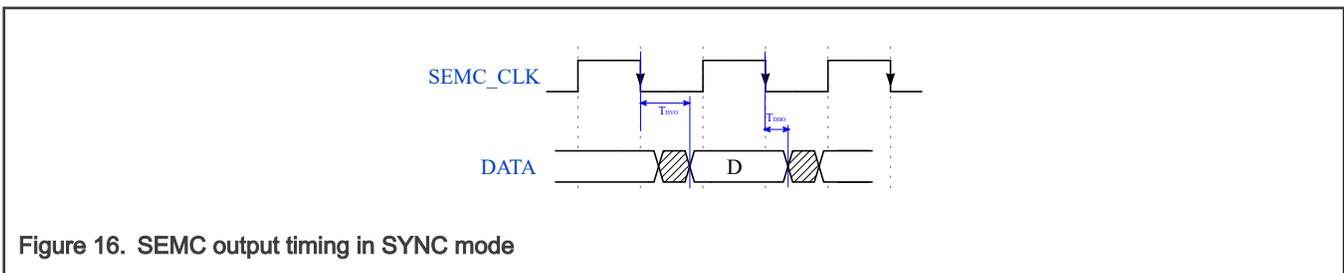
#### 4.5.1.1.2 SEMC output timing in SYNC mode

Table 33 shows SEMC output timing in SYNC mode.

Table 33. SEMC output timing in SYNC mode

Symbol	Parameter	Min.	Max.	Unit	Comment
	Frequency of operation	—	166	MHz	—
$T_{CK}$	Internal clock period	6	—	ns	—
$T_{DVO}$	Data output valid time	—	1	ns	These timing parameters apply to Address/Data/DM/CKE/ control signals with SEMC_CLK for SDRAM.
$T_{DHO}$	Data output hold time	-1	—	ns	

Figure 16 shows the output timing in SYNC mode.



### 4.5.1.2 SEMC input timing

There are ASYNC and SYNC mode for SEMC input timing.

#### 4.5.1.2.1 SEMC input timing in ASYNC mode

Table 34 shows SEMC output timing in ASYNC mode.

Table 34. SEMC output timing in ASYNC mode

Symbol	Parameter	Min.	Max.	Unit	Comment
$T_{IS}$	Data input setup	8.67	—	ns	For NAND/NOR/PSRAM/DBI, these timing parameters apply to RE# and Read Data.
$T_{IH}$	Data input hold	0	—	ns	

Figure 17 shows the input timing in ASYNC mode.

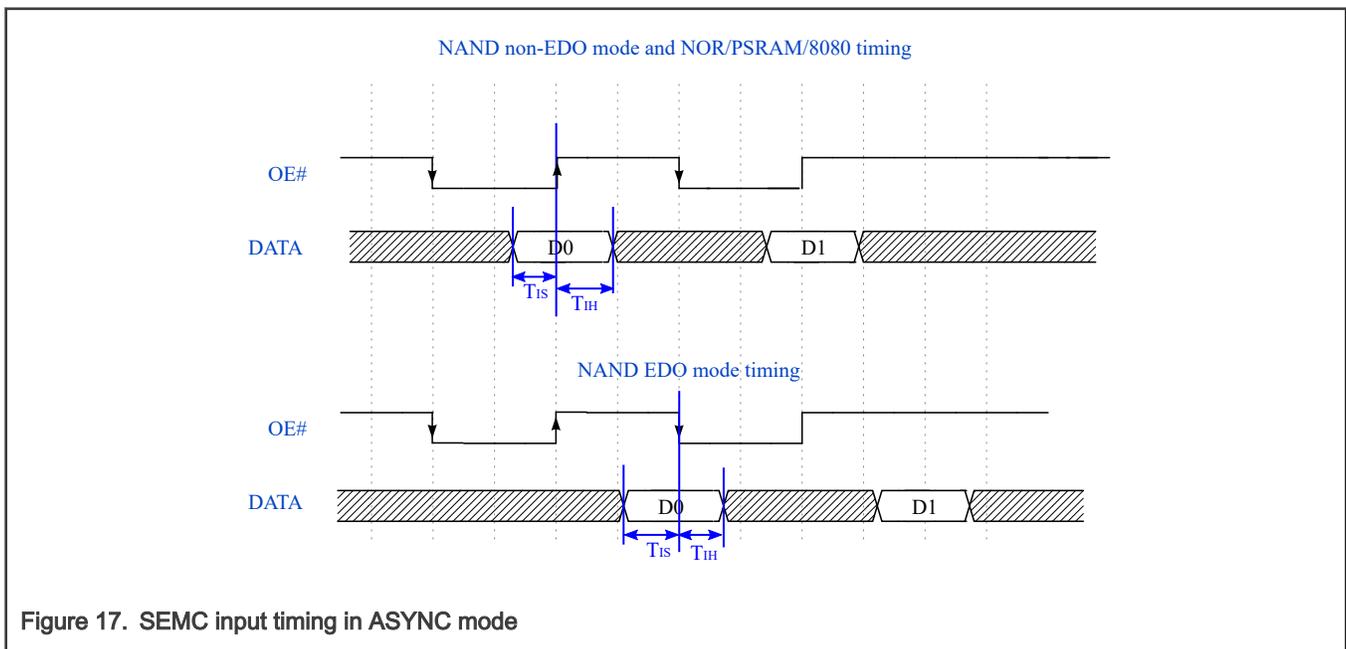


Figure 17. SEMC input timing in ASYNC mode

#### 4.5.1.2.2 SEMC input timing in SYNC mode

Table 35 and Table 36 show SEMC input timing in SYNC mode.

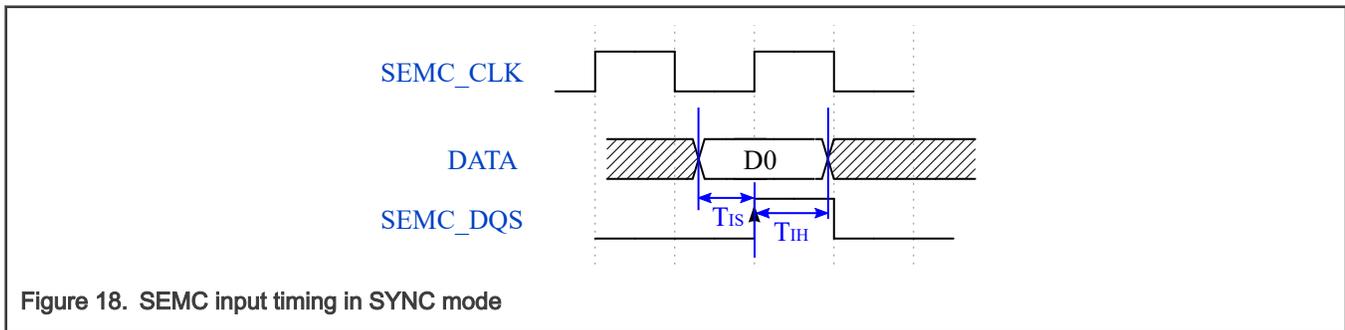
Table 35. SEMC input timing in SYNC mode (SEMC\_MCR.DQSMD = 0x0)

Symbol	Parameter	Min.	Max.	Unit	Comment
$T_{IS}$	Data input setup	8.67	—	ns	—
$T_{IH}$	Data input hold	0	—	ns	

**Table 36. SEMC input timing in SYNC mode (SEMC\_MCR.DQSMD = 0x1)**

Symbol	Parameter	Min.	Max.	Unit	Comment
T <sub>IS</sub>	Data input setup	0.6	—	ns	—
T <sub>IH</sub>	Data input hold	1	—	ns	

Figure 18 shows the input timing in SYNC mode.



### 4.5.2 FlexSPI parameters

Measurements are with a load 15 pf and input slew rate of 1 V/ns.

#### 4.5.2.1 FlexSPI input/read timing

There are four sources for the internal sample clock for FlexSPI read data:

- Dummy read strobe generated by FlexSPI controller and looped back internally (FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x0)
- Dummy read strobe generated by FlexSPI controller and looped back through the DQS pad (FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x1)
- Read strobe provided by memory device and input from DQS pad (FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x3)

The following sections describe input signal timing for each of these four internal sample clock sources.

##### 4.5.2.1.1 SDR mode with FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x0, 0x1

**Table 37. FlexSPI input timing in SDR mode where FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x0**

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	60	MHz
T <sub>IS</sub>	Setup time for incoming data	8.67	—	ns
T <sub>IH</sub>	Hold time for incoming data	0	—	ns

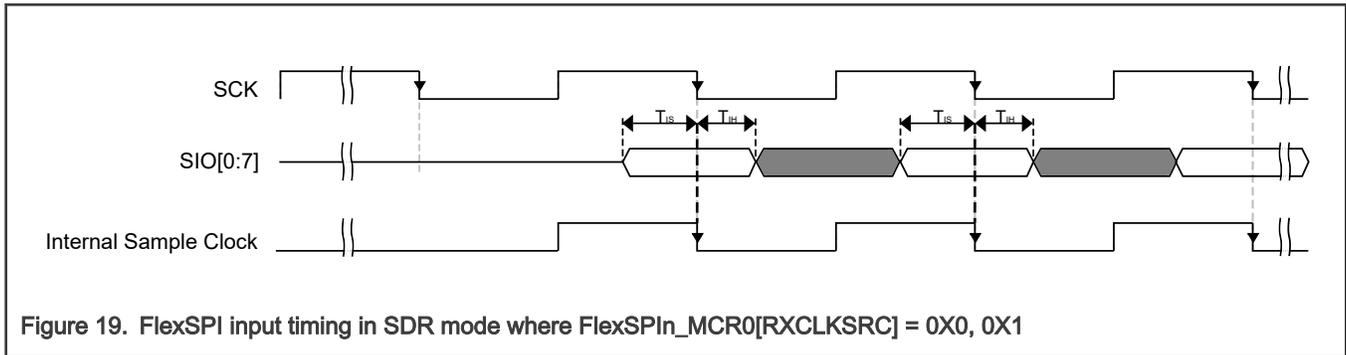
**Table 38. FlexSPI input timing in SDR mode where FlexSPI<sub>n</sub>\_MCR0[RXCLKSRC] = 0x1**

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	133	MHz

Table continues on the next page...

**Table 38. FlexSPI input timing in SDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0X1 (continued)**

Symbol	Parameter	Min	Max	Unit
$T_{IS}$	Setup time for incoming data	2	—	ns
$T_{IH}$	Hold time for incoming data	1	—	ns



**NOTE**

Timing shown is based on the memory generating read data on the SCK falling edge, and FlexSPI controller sampling read data on the falling edge.

**4.5.2.1.2 SDR mode with FlexSPIn\_MCR0[RXCLKSRC] = 0x3**

There are two cases when the memory provides both read data and the read strobe in SDR mode:

- A1—Memory generates both read data and read strobe on SCK rising edge (or falling edge)
- A2—Memory generates read data on SCK falling edge and generates read strobe on SCK rising edge

**Table 39. FlexSPI input timing in SDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x3 (case A1)**

Symbol	Parameter	Value		Unit
		Min	Max	
	Frequency of operation	—	166	MHz
$T_{SCKD}$	Time from SCK to data valid	—	—	ns
$T_{SCKDQS}$	Time from SCK to DQS	—	—	ns
$T_{SCKD} - T_{SCKDQS}$	Time delta between $T_{SCKD}$ and $T_{SCKDQS}$	-2	2	ns

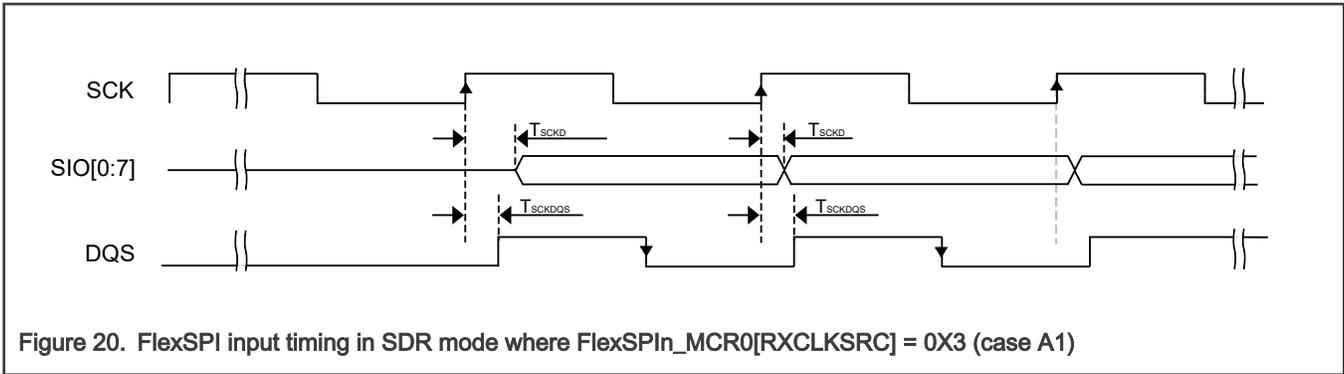


Figure 20. FlexSPI input timing in SDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0X3 (case A1)

**NOTE**

Timing shown is based on the memory generating read data and read strobe on the SCK rising edge. The FlexSPI controller samples read data on the DQS falling edge.

Table 40. FlexSPI input timing in SDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x3 (case A2)

Symbol	Parameter	Value		Unit
		Min	Max	
	Frequency of operation	—	166	MHz
$T_{SCKD}$	Time from SCK to data valid	—	—	ns
$T_{SCKDQS}$	Time from SCK to DQS	—	—	ns
$T_{SCKD} - T_{SCKDQS}$	Time delta between $T_{SCKD}$ and $T_{SCKDQS}$	-2	2	ns

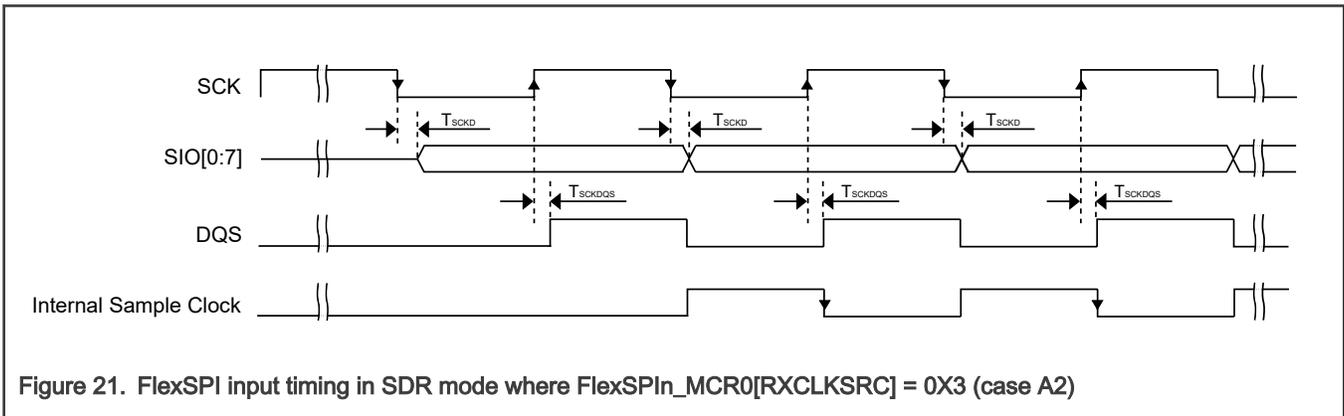


Figure 21. FlexSPI input timing in SDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0X3 (case A2)

**NOTE**

Timing shown is based on the memory generating read data on the SCK falling edge and read strobe on the SCK rising edge. The FlexSPI controller samples read data on a half cycle delayed DQS falling edge.

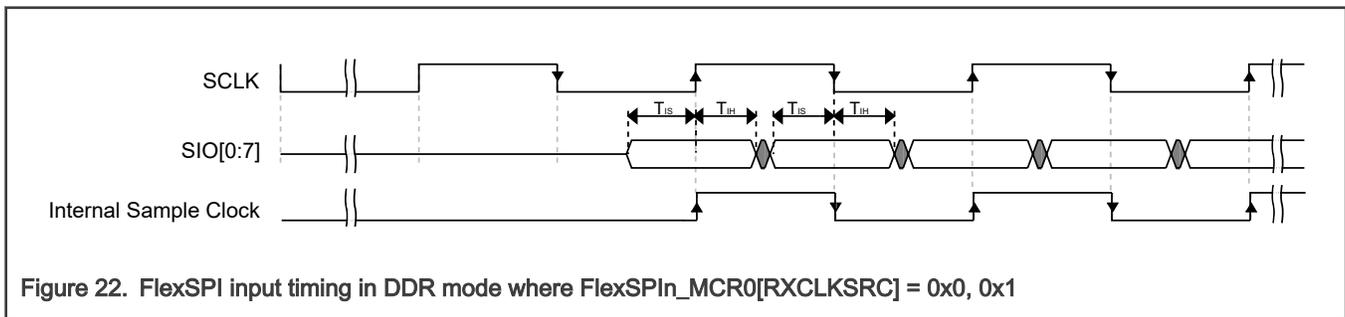
4.5.2.1.3 DDR mode with FlexSPIn\_MCR0[RXCLKSRC] = 0x0, 0x1

Table 41. FlexSPI input timing in DDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x0

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	30	MHz
T <sub>IS</sub>	Setup time for incoming data	8.67	—	ns
T <sub>IH</sub>	Hold time for incoming data	0	—	ns

Table 42. FlexSPI input timing in DDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x1

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	66	MHz
T <sub>IS</sub>	Setup time for incoming data	2	—	ns
T <sub>IH</sub>	Hold time for incoming data	1	—	ns



4.5.2.1.4 DDR mode with FlexSPIn\_MCR0[RXCLKSRC] = 0x3

There are two cases when the memory provides both read data and the read strobe in DDR mode:

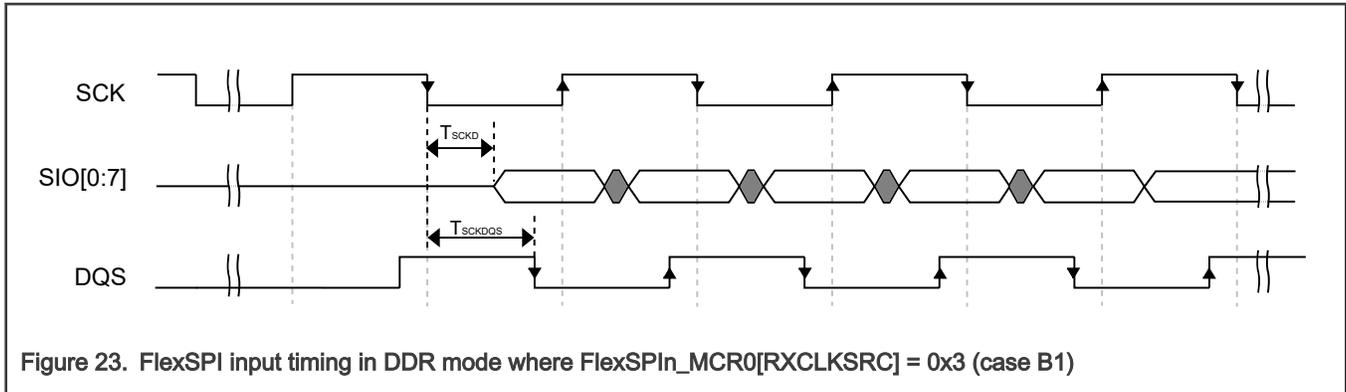
- B1—Memory generates both read data and read strobe on SCK edge
- B2—Memory generates read data on SCK edge and generates read strobe on SCK2 edge

**NOTE**

RT1060X supports two FlexSPI controllers. When FlexSPI2 is accessed through GPIO\_SPI\_B0/1\_XX, the clock supports up to 133 MHz (both for DDR and SDR mode).

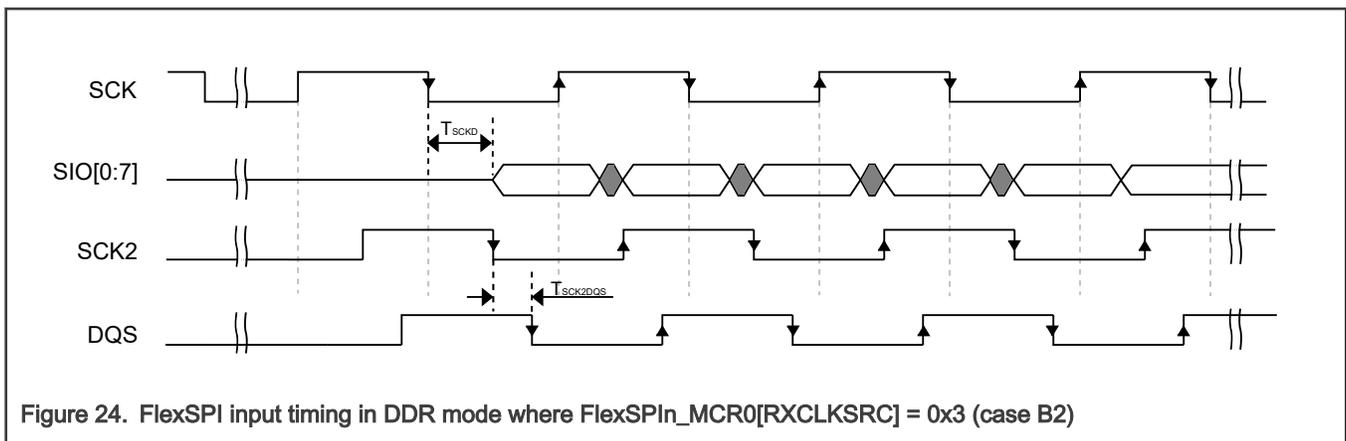
Table 43. FlexSPI input timing in DDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x3 (case B1)

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	166	MHz
T <sub>SCKD</sub>	Time from SCK to data valid	—	—	ns
T <sub>SCKDQS</sub>	Time from SCK to DQS	—	—	ns
T <sub>SCKD</sub> - T <sub>SCKDQS</sub>	Time delta between T <sub>SCKD</sub> and T <sub>SCKDQS</sub>	-1	1	ns



**Table 44. FlexSPI input timing in DDR mode where FlexSPIn\_MCR0[RXCLKSRC] = 0x3 (case B2)**

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	166	MHz
$T_{SCKD}$	Time from SCK to data valid	—	—	ns
$T_{SCKD} - T_{SCKDQS}$	Time delta between $T_{SCKD}$ and $T_{SCKDQS}$	-1	1	ns



### 4.5.2.2 FlexSPI output/write timing

The following sections describe output signal timing for the FlexSPI controller including control signals and data outputs.

#### 4.5.2.2.1 SDR mode

**Table 45. FlexSPI output timing in SDR mode**

Symbol	Parameter	Min	Max	Unit
	Frequency of operation	—	166 <sup>1</sup>	MHz
$T_{ck}$	SCK clock period	6.0	—	ns
$T_{DVO}$	Output data valid time	—	1	ns

*Table continues on the next page...*

Table 45. FlexSPI output timing in SDR mode (continued)

Symbol	Parameter	Min	Max	Unit
$T_{DHO}$	Output data hold time	-1	—	ns
$T_{CSS}$	Chip select output setup time	$3 \times T_{CK} - 1$	—	ns
$T_{CSH}$	Chip select output hold time	$3 \times T_{CK} + 2$	—	ns

- The actual maximum frequency supported is limited by the FlexSPI $_n$ \_MCR0[RXCLKSRC] configuration used. Please refer to the FlexSPI SDR input timing specifications.

**NOTE**

$T_{CSS}$  and  $T_{CSH}$  are configured by the FlexSPI $_n$ \_FLSHAxCR1 register, the default values are shown above. See more details in the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

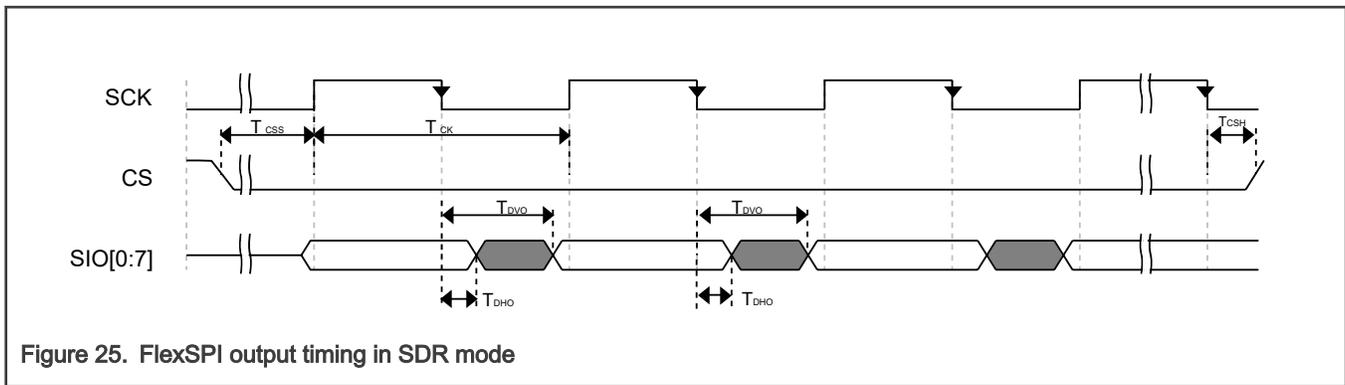


Figure 25. FlexSPI output timing in SDR mode

4.5.2.2.2 SDR mode

Table 46. FlexSPI output timing in SDR mode

Symbol	Parameter	Min	Max	Unit
	Frequency of operation <sup>1</sup>	—	166	MHz
$T_{ck}$	SCK clock period (FlexSPI $_n$ _MCR0[RXCLKSRC] = 0x0)	6.0	—	ns
$T_{DVO}$	Output data valid time	—	2.2	ns
$T_{DHO}$	Output data hold time	0.8	—	ns
$T_{CSS}$	Chip select output setup time	$3 \times T_{CK} / 2 - 0.7$	—	ns
$T_{CSH}$	Chip select output hold time	$3 \times T_{CK} / 2 + 0.8$	—	ns

- The actual maximum frequency supported is limited by the FlexSPI $_n$ \_MCR0[RXCLKSRC] configuration used. Please refer to the FlexSPI SDR input timing specifications.

**NOTE**

$T_{CSS}$  and  $T_{CSH}$  are configured by the FlexSPI $_n$ \_FLSHAxCR1 register, the default values are shown above. See more details in the *i.MX RT1060X Reference Manual (IMXRT1060XRM)*.

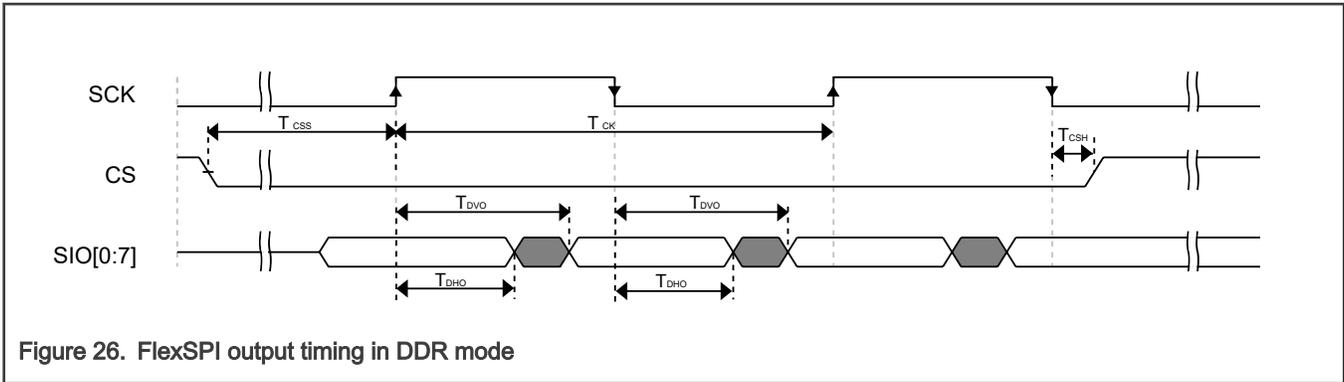


Figure 26. FlexSPI output timing in DDR mode

## 4.6 Display and graphics

The following sections provide information on display and graphic interfaces.

### 4.6.1 CMOS Sensor Interface (CSI) timing parameters

The following sections describe the CSI timing in gated and ungated clock modes.

#### 4.6.1.1 Gated clock mode timing

Figure 27 and Figure 28 shows the gated clock mode timings for CSI, and Table 47 describes the timing parameters (P1–P7) shown in the figures. A frame starts with a rising/falling edge on CSI\_VSYNC (VSYNC), then CSI\_HSYNC (HSYNC) is asserted and holds for the entire line. The pixel clock, CSI\_PIXCLK (PIXCLK), is valid as long as HSYNC is asserted.

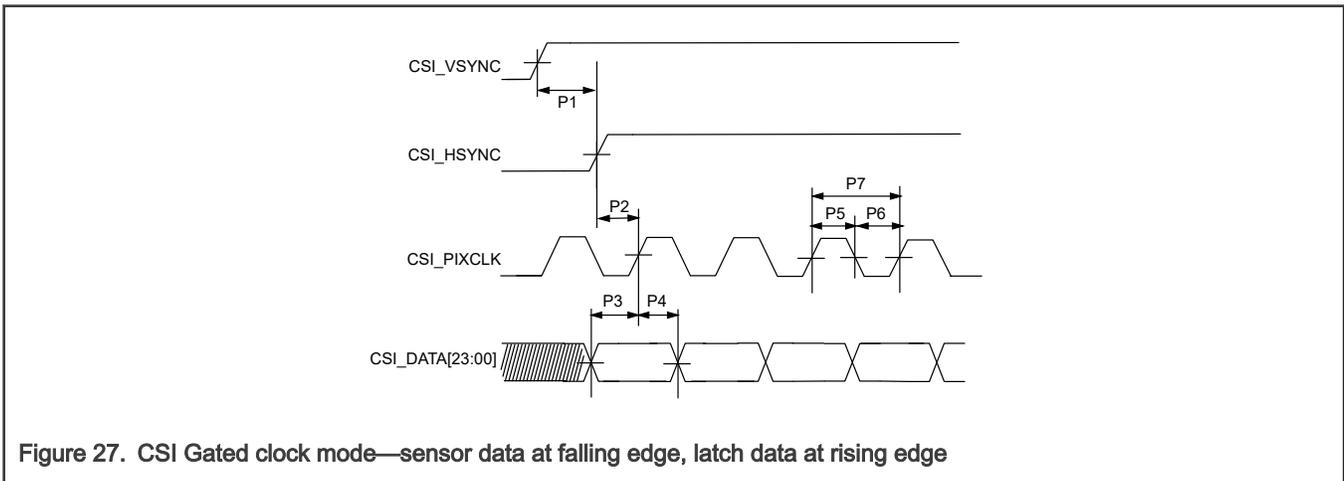


Figure 27. CSI Gated clock mode—sensor data at falling edge, latch data at rising edge

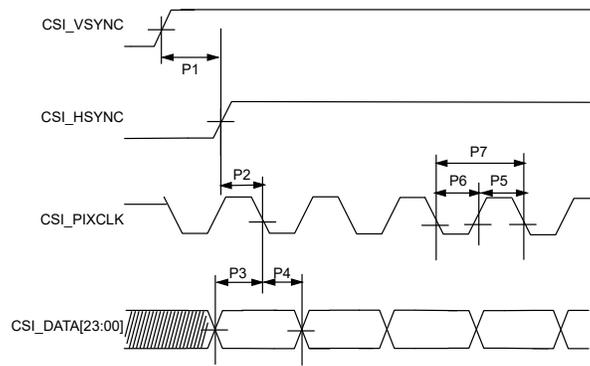


Figure 28. CSI Gated clock mode—sensor data at rising edge, latch data at falling edge

Table 47. CSI gated clock mode timing parameters

ID	Parameter	Symbol	Min.	Max.	Units
P1	CSI_VSYNC to CSI_HSYNC time	tV2H	33.5	—	ns
P2	CSI_HSYNC setup time	tHsu	1	—	ns
P3	CSI DATA setup time	tDsu	1	—	ns
P4	CSI DATA hold time	tDh	1	—	ns
P5	CSI pixel clock high time	tCLKh	3.75	—	ns
P6	CSI pixel clock low time	tCLKl	3.75	—	ns
P7	CSI pixel clock frequency	fCLK	—	80	MHz

#### 4.6.1.2 Ungated clock mode timing

Figure 29 shows the ungated clock mode timings of CSI, and Table 48 describes the timing parameters (P1–P6) that are shown in the figure. In ungated mode the CSI\_VSYNC and CSI\_PIXCLK signals are used, and the CSI\_HSYNC signal is ignored.

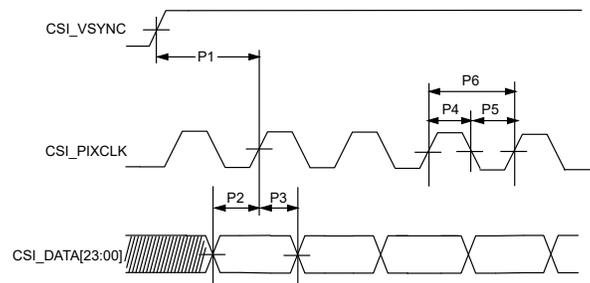


Figure 29. CSI ungated clock mode—sensor data at falling edge, latch data at rising edge

**Table 48. CSI ungated clock mode timing parameters**

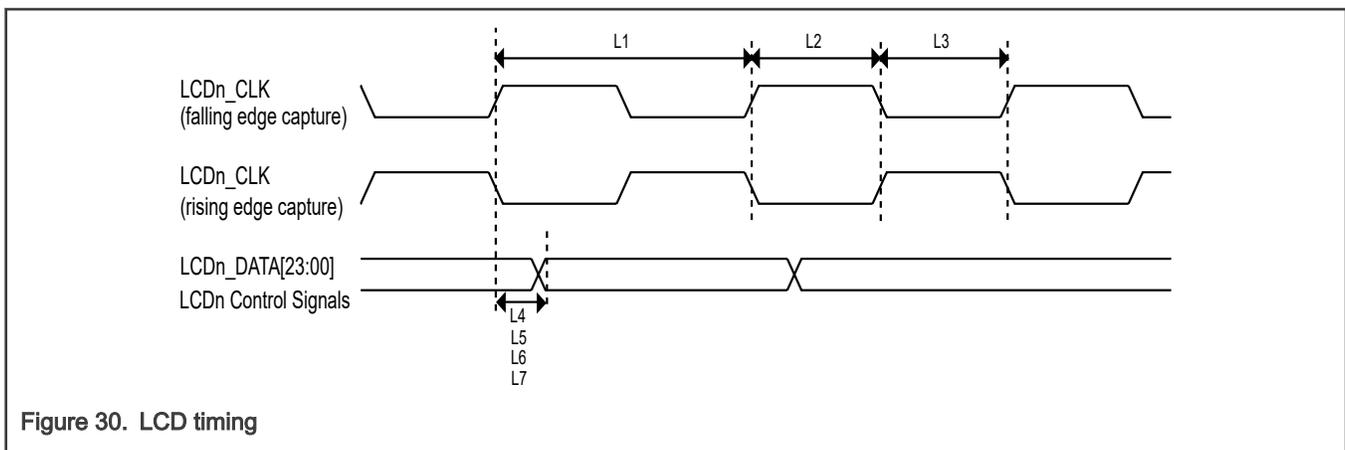
ID	Parameter	Symbol	Min.	Max.	Units
P1	CSI_VSYNC to pixel clock time	tVSYNC	33.5	—	ns
P2	CSI DATA setup time	tDsu	1	—	ns
P3	CSI DATA hold time	tDh	1	—	ns
P4	CSI pixel clock high time	tCLKh	3.75	—	ns
P5	CSI pixel clock low time	tCLKl	3.75	—	ns
P6	CSI pixel clock frequency	fCLK	—	80	MHz

The CSI enables the chip to connect directly to external CMOS image sensors, which are classified as dumb or smart as follows:

- Dumb sensors only support traditional sensor timing (vertical sync (VSYNC) and horizontal sync (HSYNC)) and output-only Bayer and statistics data.
- Smart sensors support CCIR656 video decoder formats and perform additional processing of the image (for example, image compression, image pre-filtering, and various data output formats).

### 4.6.2 LCD Controller (LCDIF) timing parameters

Figure 30 shows the LCDIF timing and Table 49 lists the timing parameters.



**Figure 30. LCD timing**

**Table 49. LCD timing parameters**

ID	Parameter	Symbol	Min	Max	Unit
L1	LCD pixel clock frequency	tCLK(LCD)	—	75	MHz
L2	LCD pixel clock high (falling edge capture)	tCLKH(LCD)	3	—	ns
L3	LCD pixel clock low (rising edge capture)	tCLKL(LCD)	3	—	ns
L4	LCD pixel clock high to data valid (falling edge capture)	td(CLKH-DV)	-1	1	ns

*Table continues on the next page...*

**Table 49. LCD timing parameters (continued)**

L5	LCD pixel clock low to data valid (rising edge capture)	td(CLKL-DV)	-1	1	ns
L6	LCD pixel clock high to control signal valid (falling edge capture)	td(CLKH-CTRLV)	-1	1	ns
L7	LCD pixel clock low to control signal valid (rising edge capture)	td(CLKL-CTRLV)	-1	1	ns

## 4.7 Audio

This section provide information about SAI/I2S and SPDIF.

### 4.7.1 SAI/I2S switching specifications

This section provides the AC timings for the SAI in master (clocks driven) and slave (clocks input) modes. All timings are given for non-inverted serial clock polarity (SAI\_TCR[TSCKP] = 0, SAI\_RCR[RSCKP] = 0) and non-inverted frame sync (SAI\_TCR[TFSI] = 0, SAI\_RCR[RFSI] = 0). If the polarity of the clock and/or the frame sync have been inverted, all the timings remain valid by inverting the clock signal (SAI\_BCLK) and/or the frame sync (SAI\_FS) shown in the figures below.

**Table 50. Master mode SAI timing**

Num	Characteristic	Min	Max	Unit
S1	SAI_MCLK cycle time	15	—	ns
S2	SAI_MCLK pulse width high/low	40%	60%	MCLK period
S3	SAI_BCLK cycle time	40	—	ns
S4	SAI_BCLK pulse width high/low	40%	60%	BCLK period
S5	SAI_BCLK to SAI_FS output valid	—	15	ns
S6	SAI_BCLK to SAI_FS output invalid	0	—	ns
S7	SAI_BCLK to SAI_TXD valid	—	15	ns
S8	SAI_BCLK to SAI_TXD invalid	0	—	ns
S9	SAI_RXD/SAI_FS input setup before SAI_BCLK	15	—	ns
S10	SAI_RXD/SAI_FS input hold after SAI_BCLK	0	—	ns

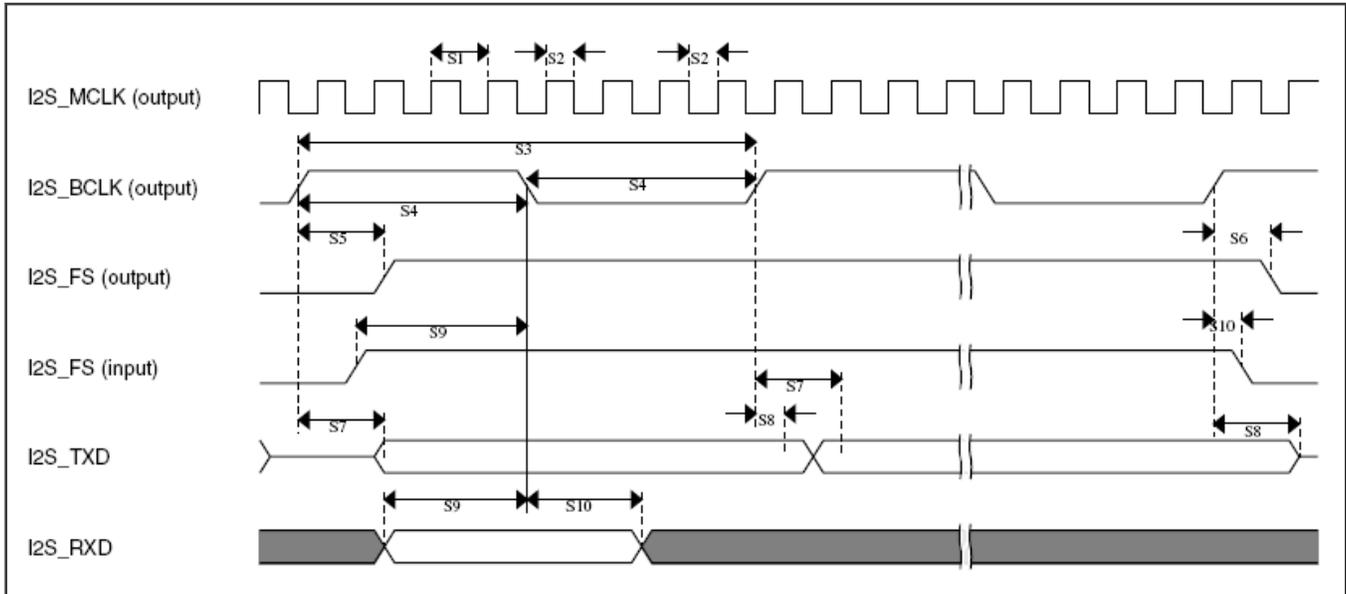
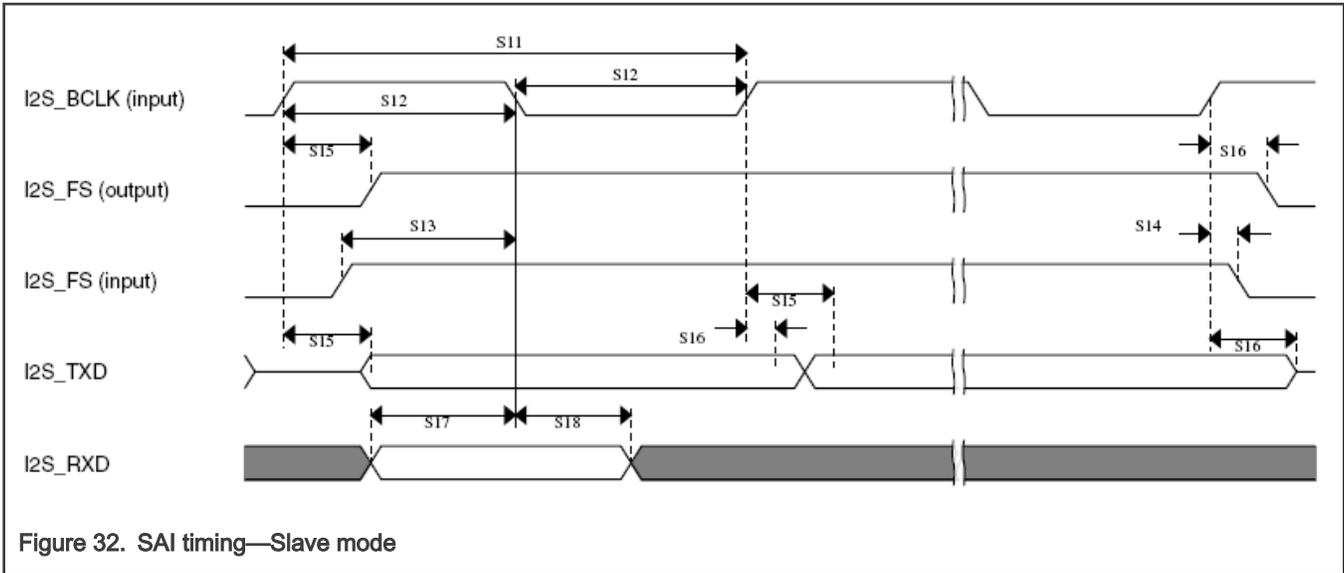


Figure 31. SAI timing—Master modes

Table 51. Slave mode SAI timing

Num	Characteristic	Min	Max	Unit
S11	SAI_BCLK cycle time (input)	40	—	ns
S12	SAI_BCLK pulse width high/low (input)	40%	60%	BCLK period
S13	SAI_FS input setup before SAI_BCLK	10	—	ns
S14	SAI_FA input hold after SAI_BCLK	2	—	ns
S15	SAI_BCLK to SAI_TXD/SAI_FS output valid	—	20	ns
S16	SAI_BCLK to SAI_TXD/SAI_FS output invalid	0	—	ns
S17	SAI_RXD setup before SAI_BCLK	10	—	ns
S18	SAI_RXD hold after SAI_BCLK	2	—	ns



### 4.7.2 SPDIF timing parameters

The Sony/Philips Digital Interconnect Format (SPDIF) data is sent using the bi-phase marking code. When encoding, the SPDIF data signal is modulated by a clock that is twice the bit rate of the data signal.

Table 52, Figure 33, and Figure 34 show SPDIF timing parameters for the Sony/Philips Digital Interconnect Format (SPDIF), including the timing of the modulating Rx clock (SPDIF\_SR\_CLK) for SPDIF in Rx mode and the timing of the modulating Tx clock (SPDIF\_ST\_CLK) for SPDIF in Tx mode.

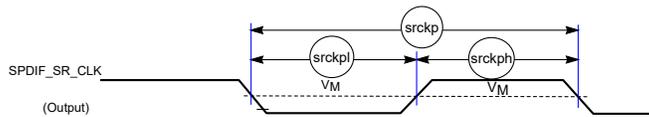
**Table 52. SPDIF timing parameters**

Characteristics	Symbol	Timing Parameter Range		Unit
		Min	Max	
SPDIF_IN Skew: asynchronous inputs, no specs apply	—	—	0.7	ns
SPDIF_OUT output (Load = 50pf)	—	—	1.5	ns
• Skew	—	—	24.2	
• Transition rising	—	—	31.3	
• Transition falling	—	—		
SPDIF_OUT1 output (Load = 30pf)	—	—	1.5	ns
• Skew	—	—	13.6	
• Transition rising	—	—	18.0	
• Transition falling	—	—		
Modulating Rx clock (SPDIF_SR_CLK) period	srckp	40.0	—	ns
SPDIF_SR_CLK high period	srckph	16.0	—	ns
SPDIF_SR_CLK low period	srckpl	16.0	—	ns

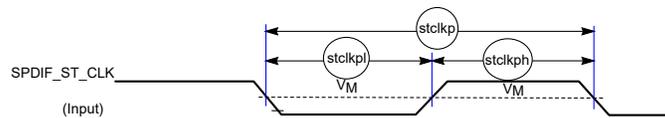
Table continues on the next page...

**Table 52. SPDIF timing parameters (continued)**

Characteristics	Symbol	Timing Parameter Range		Unit
		Min	Max	
Modulating Tx clock (SPDIF_ST_CLK) period	stclkp	40.0	—	ns
SPDIF_ST_CLK high period	stclkph	16.0	—	ns
SPDIF_ST_CLK low period	stclkpl	16.0	—	ns



**Figure 33. SPDIF\_SR\_CLK timing diagram**



**Figure 34. SPDIF\_ST\_CLK timing diagram**

## 4.8 Analog

The following sections provide information about analog interfaces.

### 4.8.1 DCDC

Table 53 introduces the DCDC electrical specifications.

**Table 53. DCDC electrical specifications**

Mode	Buck mode, one output	Notes
Input voltage	3.3 V	Min = 2.8 V, Max = 3.6 V
Output voltage	1.1 V	Configurable 0.8 - 1.575 with 25 mV one step in Run mode
Max loading	500 mA	—
Loading in low power modes	200 $\mu$ A ~ 30 mA	—
Efficiency	90% max	@150 mA
Low power mode	Open loop mode	Ripple is about 15 mV in Run mode
Run mode	<ul style="list-style-type: none"> <li>Always continuous mode</li> </ul>	Configurable by register

*Table continues on the next page...*

**Table 53. DCDC electrical specifications (continued)**

Mode	Buck mode, one output	Notes
	<ul style="list-style-type: none"> <li>Support discontinuous mode</li> </ul>	
Inductor	4.7 $\mu$ H	—
Capacitor	33 $\mu$ F	—
Over voltage protection	1.55 V	Detect VDDSOC, when the voltage is higher than 1.6 V, shutdown DCDC.
Over Current protection	1 A	Detect the peak current <ul style="list-style-type: none"> <li>Run mode: when the current is larger than 1 A, shutdown DCDC.</li> </ul>
Low DCDC_IN detection	2.6 V	Detect the DCDC_IN, when battery is lower than 2.6 V, shutdown DCDC.

## 4.8.2 A/D converter

This section introduces information about A/D converter.

### 4.8.2.1 12-bit ADC electrical characteristics

The section provide information about 12-bit ADC electrical characteristics.

#### 4.8.2.1.1 12-bit ADC operating conditions

**Table 54. 12-bit ADC operating conditions**

Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Supply voltage	Absolute	V <sub>DDA</sub>	3.0	-	3.6	V	—
	Delta to VDDA_ADC_3P3 (VDD-VDDA) <sup>2</sup>	$\Delta$ V <sub>DDA</sub>	-100	0	100	mV	—
Ground voltage	Delta to VSS (VSS-VSSAD)	$\Delta$ V <sub>SSAD</sub>	-100	0	100	mV	—
Ref Voltage High	—	V <sub>DDA</sub>	1.13	V <sub>DDA</sub>	V <sub>DDA</sub>	V	—
Ref Voltage Low	—	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	V	—
Input Voltage	—	V <sub>ADIN</sub>	V <sub>SS</sub>	—	V <sub>DDA</sub>	V	—
Input Capacitance	8/10/12 bit modes	C <sub>ADIN</sub>	—	1.5	2	pF	—
Input Resistance	ADLPC=0, ADHSC=1	R <sub>ADIN</sub>	—	5	7	kohms	—
	ADLPC=0, ADHSC=0		—	12.5	15	kohms	—

*Table continues on the next page...*

Table 54. 12-bit ADC operating conditions (continued)

Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
	ADLPC=1, ADHSC=0		—	25	30	kohms	—
Analog Source Resistance	12 bit mode $f_{ADCK} = 40$ MHz ADLSMP=0, ADSTS=10, ADHSC=1	$R_{AS}$	—	—	1	kohms	$T_{\text{samp}}=150$ ns
$R_{AS}$ depends on Sample Time Setting (ADLSMP, ADSTS) and ADC Power Mode (ADHSC, ADLPC). See charts for Minimum Sample Time vs $R_{AS}$							
ADC Conversion Clock Frequency	ADLPC=0, ADHSC=1 12 bit mode	$f_{ADCK}$	4	—	40	MHz	—
	ADLPC=0, ADHSC=0 12 bit mode		4	—	30	MHz	—
	ADLPC=1, ADHSC=0 12 bit mode		4	—	20	MHz	—

1. Typical values assume  $V_{DDAD} = 3.0$  V, Temp = 25°C,  $f_{ADCK}=20$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. DC potential differences

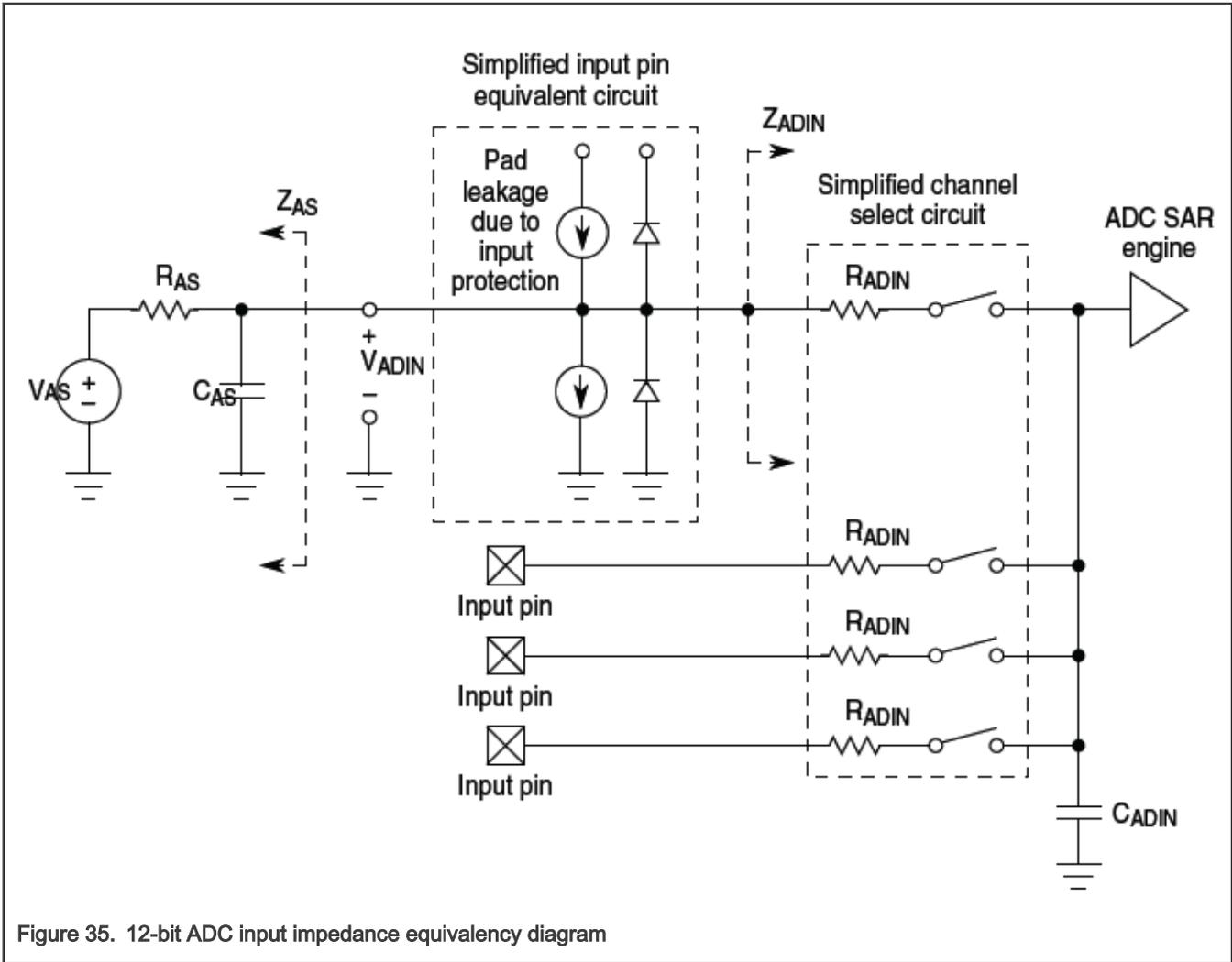


Figure 35. 12-bit ADC input impedance equivalency diagram

4.8.2.1.1.1 12-bit ADC characteristics

Table 55. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSAD}$ )

Characteristic	Conditions <sup>1</sup>	Symb	Min	Typ <sup>2</sup>	Max	Unit	Comment
Supply Current	ADLPC=1, ADHSC=0	$I_{DDA}$	—	350	—	$\mu A$	ADLSMP=0 ADSTS=10 ADCO=1
	ADLPC=0, ADHSC=0			460			
	ADLPC=0, ADHSC=1			750			
Supply Current	Stop, Reset, Module Off	$I_{DDA}$	—	1.4	2	$\mu A$	—
ADC Asynchronous Clock Source	ADHSC=0	$f_{ADACK}$	—	10	—	MHz	$t_{ADACK} = 1/f_{ADACK}$

Table continues on the next page...

**Table 55. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSAD}$ ) (continued)**

Characteristic	Conditions <sup>1</sup>	Symb	Min	Typ <sup>2</sup>	Max	Unit	Comment
	ADHSC=1		—	20	—		
Sample Cycles	ADLSMP=0, ADSTS=00	Csamp	—	2	—	cycles	—
	ADLSMP=0, ADSTS=01			4			
	ADLSMP=0, ADSTS=10			6			
	ADLSMP=0, ADSTS=11			8			
	ADLSMP=1, ADSTS=00			12			
	ADLSMP=1, ADSTS=01			16			
	ADLSMP=1, ADSTS=10			20			
	ADLSMP=1, ADSTS=11			24			
Conversion Cycles	ADLSMP=0 ADSTS=00	Cconv	—	28	—	cycles	—
	ADLSMP=0 ADSTS=01			30			
	ADLSMP=0 ADSTS=10			32			
	ADLSMP=0 ADSTS=11			34			
	ADLSMP=1 ADSTS=00			38			
	ADLSMP=1 ADSTS=01			42			
	ADLSMP=1 ADSTS=10			46			
	ADLSMP=1, ADSTS=11			50			

*Table continues on the next page...*

**Table 55. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSAD}$ ) (continued)**

Characteristic	Conditions <sup>1</sup>	Symb	Min	Typ <sup>2</sup>	Max	Unit	Comment
Conversion Time	ADLSMP=0 ADSTS=00	Tconv	—	0.7	—	µs	Fadc=40 MHz
	ADLSMP=0 ADSTS=01		—	0.75	—		
	ADLSMP=0 ADSTS=10		—	0.8	—		
	ADLSMP=0 ADSTS=11		—	0.85	—		
	ADLSMP=1 ADSTS=00		—	0.95	—		
	ADLSMP=1 ADSTS=01		—	1.05	—		
	ADLSMP=1 ADSTS=10		—	1.15	—		
	ADLSMP=1, ADSTS=11		—	1.25	—		
Total Unadjusted Error	12 bit mode	TUE	—	3.4	—	LSB 1 LSB = ( $V_{REFH} - V_{REFL}$ )/2 N	AVGE = 1, AVGS = 11
	10 bit mode		—	1.5	—		
	8 bit mode		—	1.2	—		
Differential Non-Linearity	12 bit mode	DNL	—	0.76	—	LSB	AVGE = 1, AVGS = 11
	10bit mode		—	0.36	—		
	8 bit mode		—	0.14	—		
Integral Non-Linearity	12 bit mode	INL	—	2.78	—	LSB	AVGE = 1, AVGS = 11
	10bit mode		—	0.61	—		
	8 bit mode		—	0.14	—		
Zero-Scale Error	12 bit mode	E <sub>ZS</sub>	—	-1.14	—	LSB	AVGE = 1, AVGS = 11
	10bit mode		—	-0.25	—		
	8 bit mode		—	-0.19	—		

Table continues on the next page...

**Table 55. 12-bit ADC characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSAD}$ ) (continued)**

Characteristic	Conditions <sup>1</sup>	Symb	Min	Typ <sup>2</sup>	Max	Unit	Comment
Full-Scale Error	12 bit mode	E <sub>FS</sub>	—	-1.06	—	LSB	AVGE = 1, AVGS = 11
	10bit mode		—	-0.03	—		
	8 bit mode		—	-0.02	—		
Effective Number of Bits	12 bit mode	ENOB	10.1	10.7	—	Bits	AVGE = 1, AVGS = 11
Signal to Noise plus Distortion	See ENOB	SINAD	SINAD = 6.02 x ENOB + 1.76			dB	AVGE = 1, AVGS = 11

1. All accuracy numbers assume the ADC is calibrated with  $V_{REFH} = V_{DDAD}$
2. Typical values assume  $V_{DDAD} = 3.0\text{ V}$ , Temp = 25°C,  $F_{adck} = 20\text{ MHz}$  unless otherwise stated. Typical values are for reference only and are not tested in production.

**NOTE**

The ADC electrical spec is met with the calibration enabled configuration.

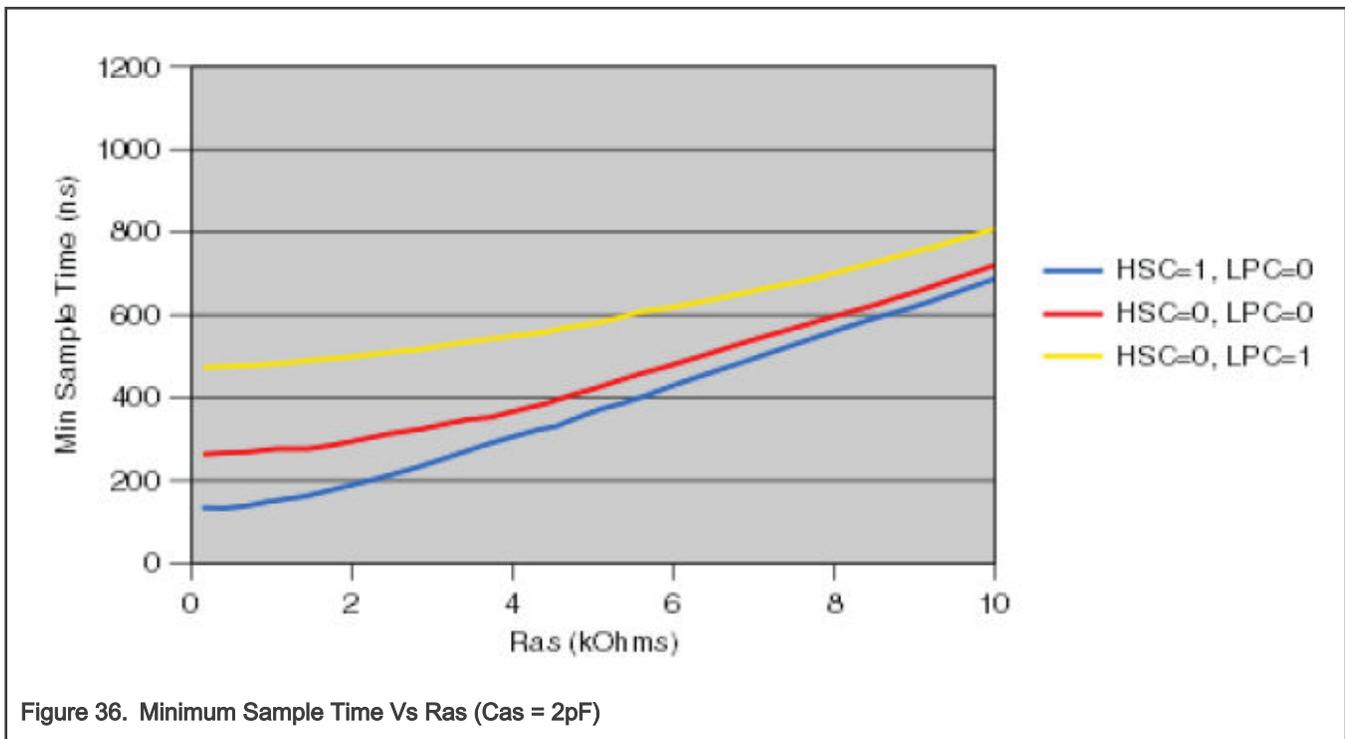


Figure 36. Minimum Sample Time Vs Ras (Cas = 2pF)

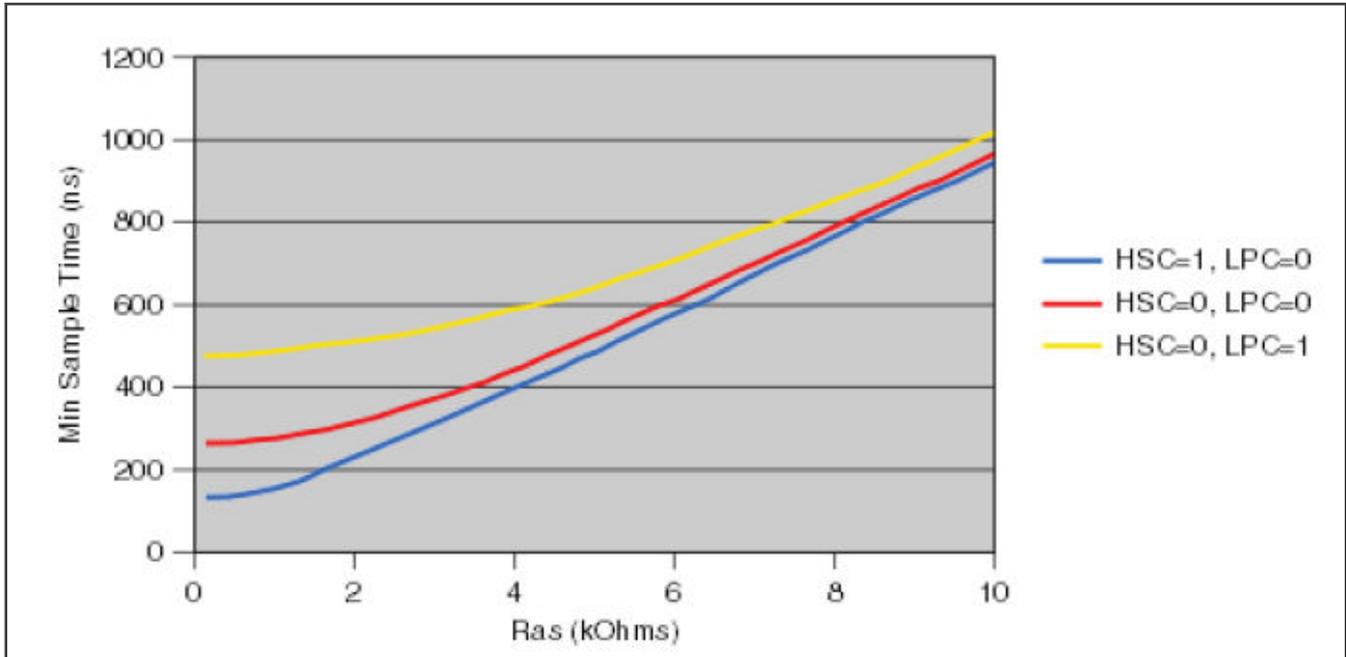


Figure 37. Minimum Sample Time Vs Ras (Cas = 5 pF)

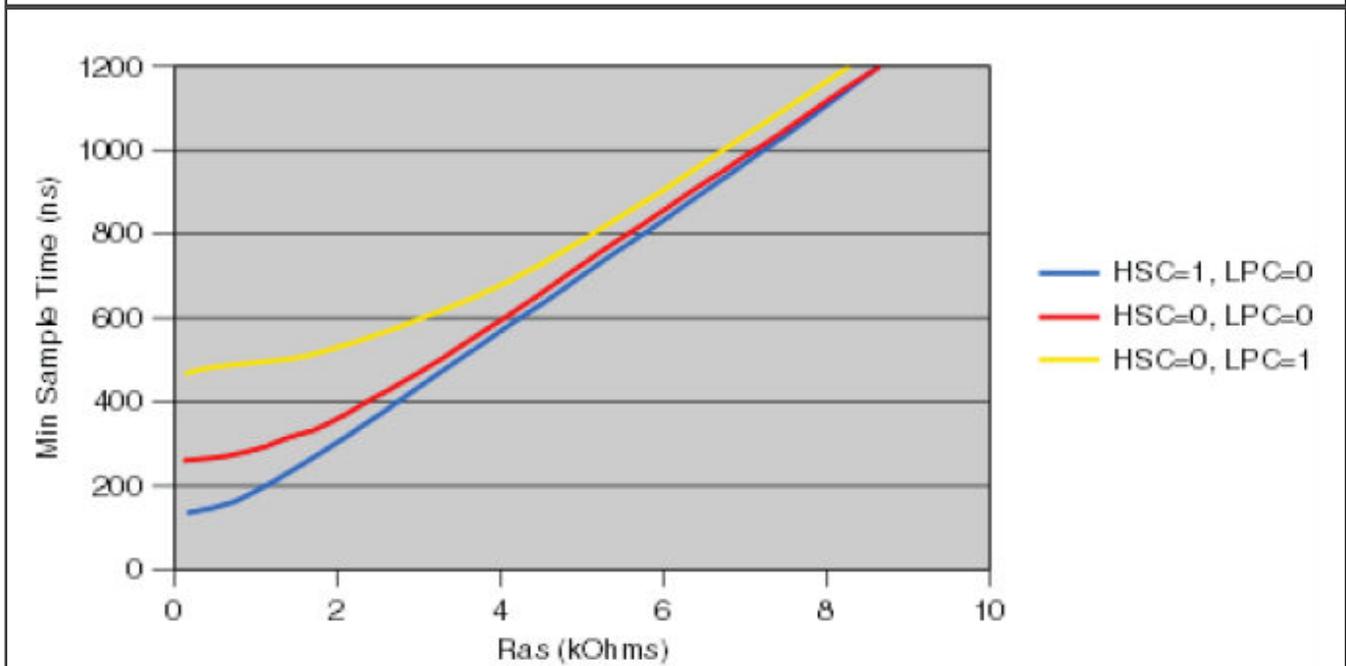


Figure 38. Minimum Sample Time Vs Ras (Cas = 10 pF)

### 4.8.3 ACMP

Table 56 lists the ACMP electrical specifications.

Table 56. Comparator and 6-bit DAC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
$V_{DD}$	Supply voltage	3.0	—	3.6	V
$I_{DDHS}$	Supply current, High-speed mode (EN = 1, PMODE = 1)	—	347	—	$\mu$ A
$I_{DDL}$	Supply current, Low-speed mode (EN = 1, PMODE = 0)	—	42	—	$\mu$ A
$V_{AIN}$	Analog input voltage	$V_{SS}$	—	$V_{DD}$	V
$V_{AIO}$	Analog input offset voltage	—	—	21	mV
$V_H$	Analog comparator hysteresis <sup>1</sup>				mV
	• CR0[HYSTCTR] = 00	—	1	2	
	• CR0[HYSTCTR] = 01	—	21	54	
	• CR0[HYSTCTR] = 10	—	42	108	
	• CR0[HYSTCTR] = 11	—	64	184	
$V_{CMPOH}$	Output high	$V_{DD} - 0.5$	—	—	V
$V_{CMPOI}$	Output low	—	—	0.5	V
$t_{DHS}$	Propagation delay, high-speed mode (EN = 1, PMODE = 1)	—	25	40	ns
$t_{DLS}$	Propagation delay, low-speed mode (EN = 1, PMODE = 0) <sup>2</sup>	—	50	90	ns
$t_{Dinit}$	Analog comparator initialization delay <sup>3</sup>	—	1.5	—	$\mu$ s
$I_{DAC6b}$	6-bit DAC current adder (enabled)	—	5	—	$\mu$ A
$R_{DAC6b}$	6-bit DAC reference inputs	—	$V_{DD}$	—	V
$INL_{DAC6b}$	6-bit DAC integral non-linearity	-0.3	—	0.3	LSB <sup>4</sup>
$DNL_{DAC6b}$	6-bit DAC differential non-linearity	-0.15	—	0.15	LSB <sup>4</sup>

1. Typical hysteresis is measured with input voltage range limited to 0.7 to  $V_{DD} - 0.7$  V in high speed mode.

2. Signal swing is 100 mV.

3. Comparator initialization delay is defined as the time between software writes to the enable comparator module and the comparator output setting to a stable level.

4. 1 LSB =  $V_{reference} / 64$

## 4.9 Communication interfaces

The following sections provide the information about communication interfaces.

### 4.9.1 LPSPI timing parameters

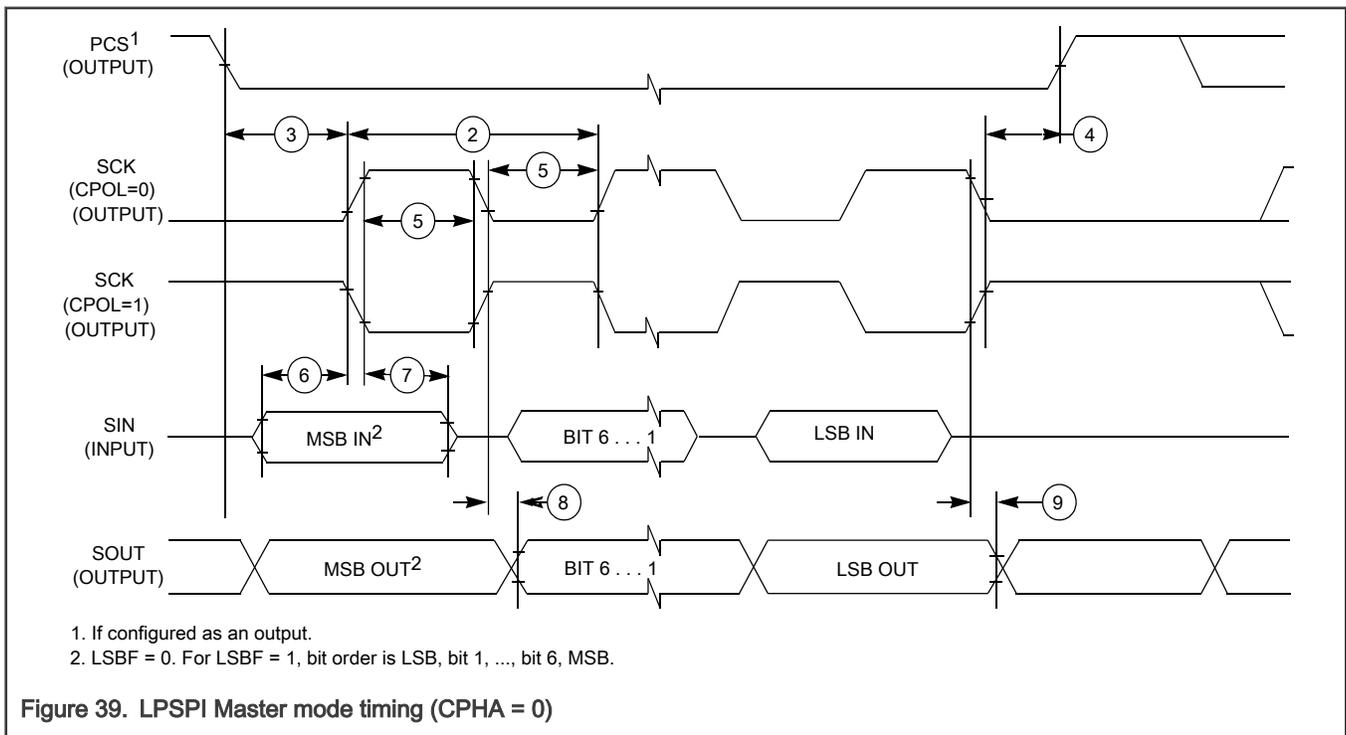
The Low Power Serial Peripheral Interface (LPSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The following tables provide timing characteristics for classic LPSPI timing modes.

All timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  thresholds, unless noted, as well as input signal transitions of 3 ns and a 30 pF maximum load on all LPSPI pins.

Table 57. LPSPI Master mode timing

Number	Symbol	Description	Min.	Max.	Units	Note
1	$f_{SCK}$	Frequency of operation	—	$f_{periph} / 2$	Hz	1
2	$t_{SCK}$	SCK period	$2 \times t_{periph}$	—	ns	2
3	$t_{Lead}$	Enable lead time	1	—	$t_{periph}$	—
4	$t_{Lag}$	Enable lag time	1	—	$t_{periph}$	—
5	$t_{wSCK}$	Clock (SCK) high or low time	$t_{SCK} / 2 - 3$	—	ns	—
6	$t_{SU}$	Data setup time (inputs)	10	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	2	—	ns	—
8	$t_v$	Data valid (after SCK edge)	—	8	ns	—
9	$t_{HO}$	Data hold time (outputs)	0	—	ns	—

1. Absolute maximum frequency of operation (fop) is 30 MHz. The clock driver in the LPSPI module for  $f_{periph}$  must be guaranteed this limit is not exceeded.
2.  $t_{periph} = 1 / f_{periph}$



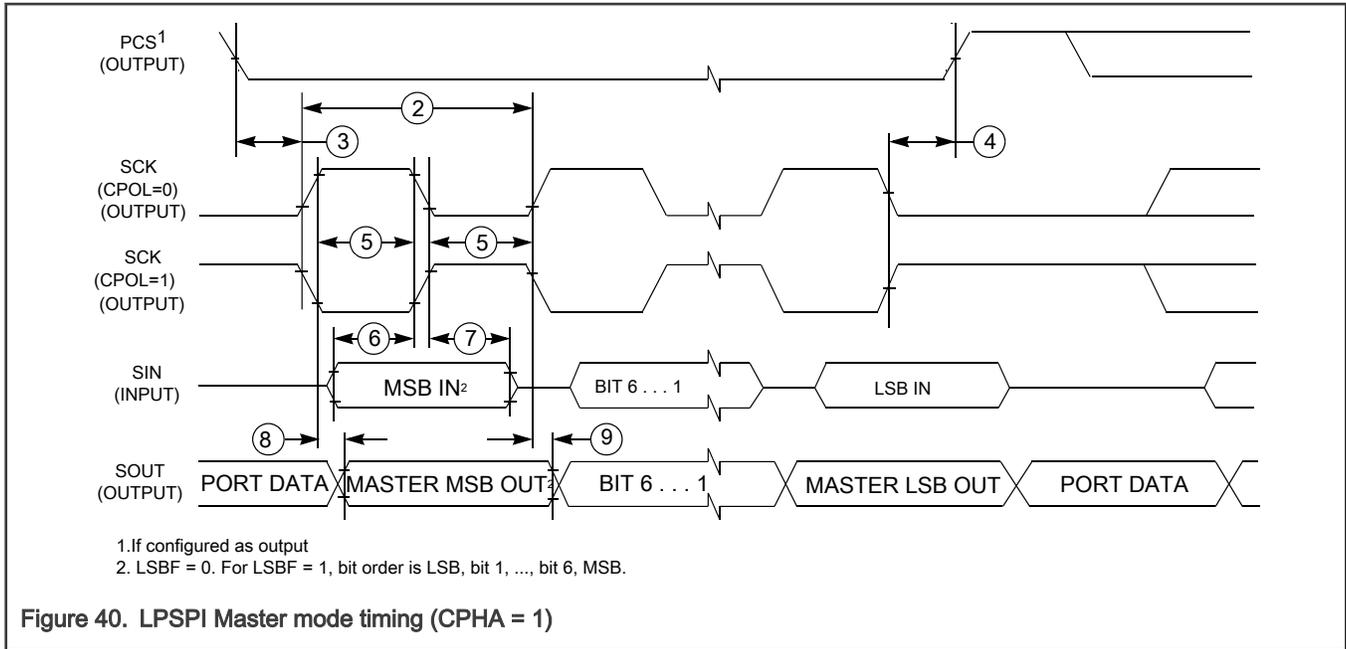


Table 58. LPSPI Slave mode timing

Number	Symbol	Description	Min.	Max.	Units	Note
1	$f_{SCK}$	Frequency of operation	0	$f_{periph} / 2$	Hz	1
2	$t_{SCK}$	SCK period	$2 \times t_{periph}$	—	ns	2
3	$t_{Lead}$	Enable lead time	1	—	$t_{periph}$	—
4	$t_{Lag}$	Enable lag time	1	—	$t_{periph}$	—
5	$t_{wSCK}$	Clock (SCK) high or low time	$t_{SCK} / 2 - 5$	—	ns	—
6	$t_{SU}$	Data setup time (inputs)	2.7	—	ns	—
7	$t_{HI}$	Data hold time (inputs)	3.8	—	ns	—
8	$t_a$	Slave access time	—	$t_{periph}$	ns	3
9	$t_{dis}$	Slave MISO disable time	—	$t_{periph}$	ns	4
10	$t_v$	Data valid (after SCK edge)	—	14.5	ns	—
11	$t_{HO}$	Data hold time (outputs)	0	—	ns	—

1. Absolute maximum frequency of operation ( $f_{op}$ ) is 30 MHz. The clock driver in the LPSPI module for  $f_{periph}$  must be guaranteed this limit is not exceeded.
2.  $t_{periph} = 1 / f_{periph}$
3. Time to data active from high-impedance state
4. Hold time to high-impedance state

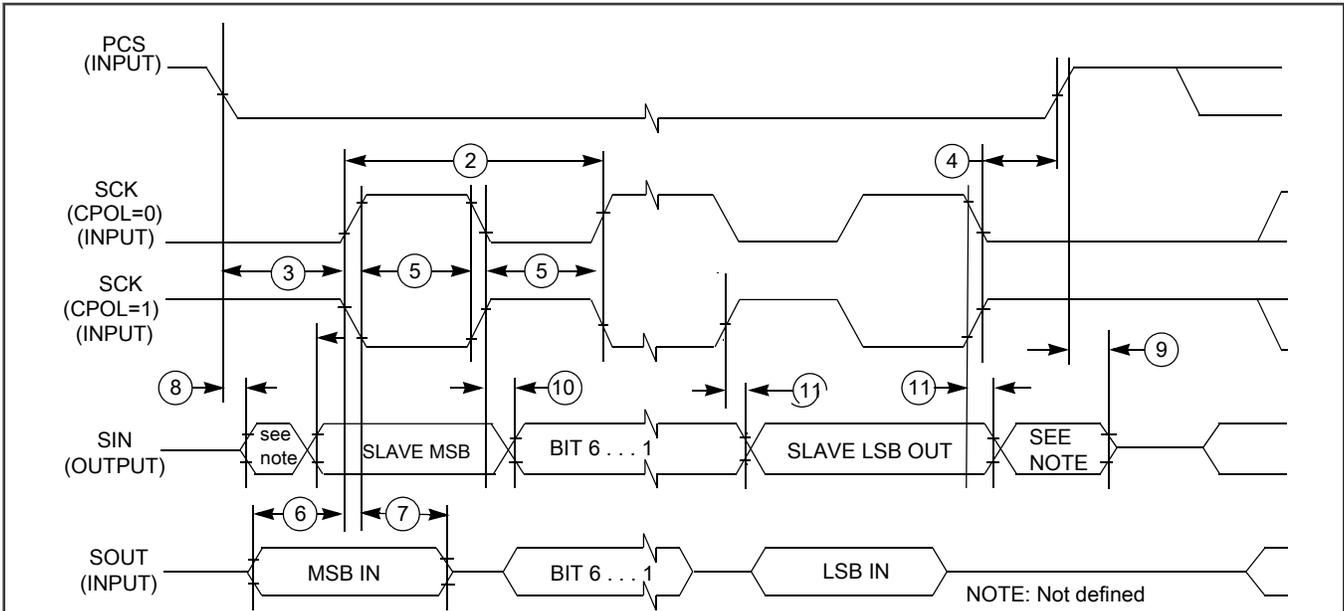


Figure 41. LPSPI Slave mode timing (CPHA = 0)

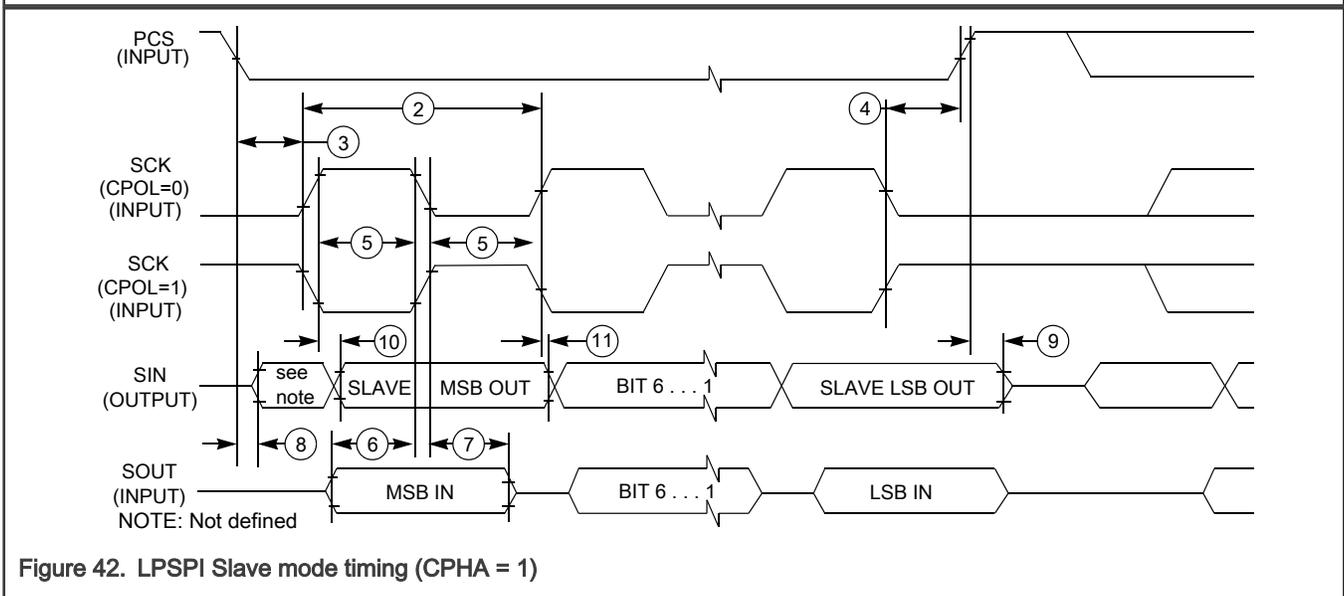


Figure 42. LPSPI Slave mode timing (CPHA = 1)

### 4.9.2 LPI2C module timing parameters

This section describes the timing parameters of the LPI2C module.

Table 59. LPI2C module timing parameters

Symbol	Description		Min	Max	Unit	Notes
f <sub>SCL</sub>	SCL clock frequency	Standard mode (Sm)	0	100	kHz	1, 2
		Fast mode (Fm)	0	400		
		Fast mode Plus (Fm+)	0	1000		

Table continues on the next page...

**Table 59. LPI2C module timing parameters (continued)**

Symbol	Description	Min	Max	Unit	Notes
	Ultra Fast mode (UFm)	0	5000		
	High speed mode (Hs-mode)	0	3400		

1. Hs-mode is only supported in slave mode.
2. See General switching specifications.

### 4.9.3 Ultra High Speed SD/SDIO/MMC Host Interface (uSDHC) AC timing

This section describes the electrical information of the uSDHC, which includes SD/eMMC4.3 (Single Data Rate) timing, eMMC4.4/4.41/4.5 (Dual Data Rate) timing and SDR104/50(SD3.0) timing.

#### 4.9.3.1 SD/eMMC4.3 (single data rate) AC timing

Figure 43 depicts the timing of SD/eMMC4.3, and Table 60 lists the SD/eMMC4.3 timing characteristics.

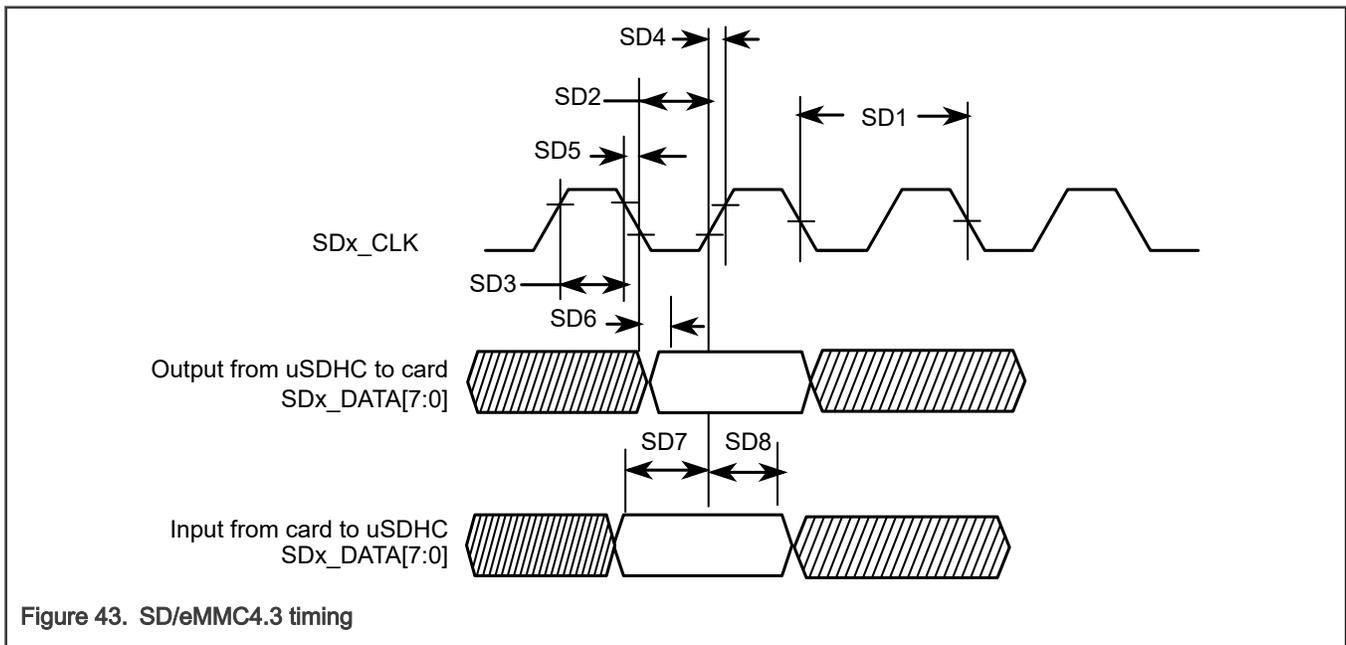


Figure 43. SD/eMMC4.3 timing

**Table 60. SD/eMMC4.3 interface timing specification**

ID	Parameter	Symbols	Min	Max	Unit
<b>Card Input Clock</b>					
SD1	Clock Frequency (Low Speed)	$f_{PP}^1$	0	400	kHz
	Clock Frequency (SD/SDIO Full Speed/High Speed)	$f_{PP}^2$	0	25/50	MHz
	Clock Frequency (MMC Full Speed/High Speed)	$f_{PP}^3$	0	20/52	MHz
	Clock Frequency (Identification Mode)	$f_{OD}$	100	400	kHz

Table continues on the next page...

Table 60. SD/eMMC4.3 interface timing specification (continued)

ID	Parameter	Symbols	Min	Max	Unit
SD2	Clock Low Time	$t_{WL}$	7	—	ns
SD3	Clock High Time	$t_{WH}$	7	—	ns
SD4	Clock Rise Time	$t_{TLH}$	—	3	ns
SD5	Clock Fall Time	$t_{THL}$	—	3	ns
<b>uSDHC Output/Card Inputs SD_CMD, SDx_DATAx (Reference to CLK)</b>					
SD6	uSDHC Output Delay	$t_{OD}$	-6.6	3.6	ns
<b>uSDHC Input/Card Outputs SD_CMD, SDx_DATAx (Reference to CLK)</b>					
SD7	uSDHC Input Setup Time	$t_{ISU}$	2.5	—	ns
SD8	uSDHC Input Hold Time <sup>4</sup>	$t_{IH}$	1.5	—	ns

1. In low speed mode, card clock must be lower than 400 kHz, voltage ranges from 2.7 to 3.6 V.
2. In normal (full) speed mode for SD/SDIO card, clock frequency can be any value between 0–25 MHz. In high-speed mode, clock frequency can be any value between 0–50 MHz.
3. In normal (full) speed mode for MMC card, clock frequency can be any value between 0–20 MHz. In high-speed mode, clock frequency can be any value between 0–52 MHz.
4. To satisfy hold timing, the delay difference between clock input and cmd/data input must not exceed 2 ns.

4.9.3.2 eMMC4.4/4.41 (dual data rate) AC timing

Figure 44 depicts the timing of eMMC4.4/4.41. Table 61 lists the eMMC4.4/4.41 timing characteristics. Be aware that only DATA is sampled on both edges of the clock (not applicable to CMD).

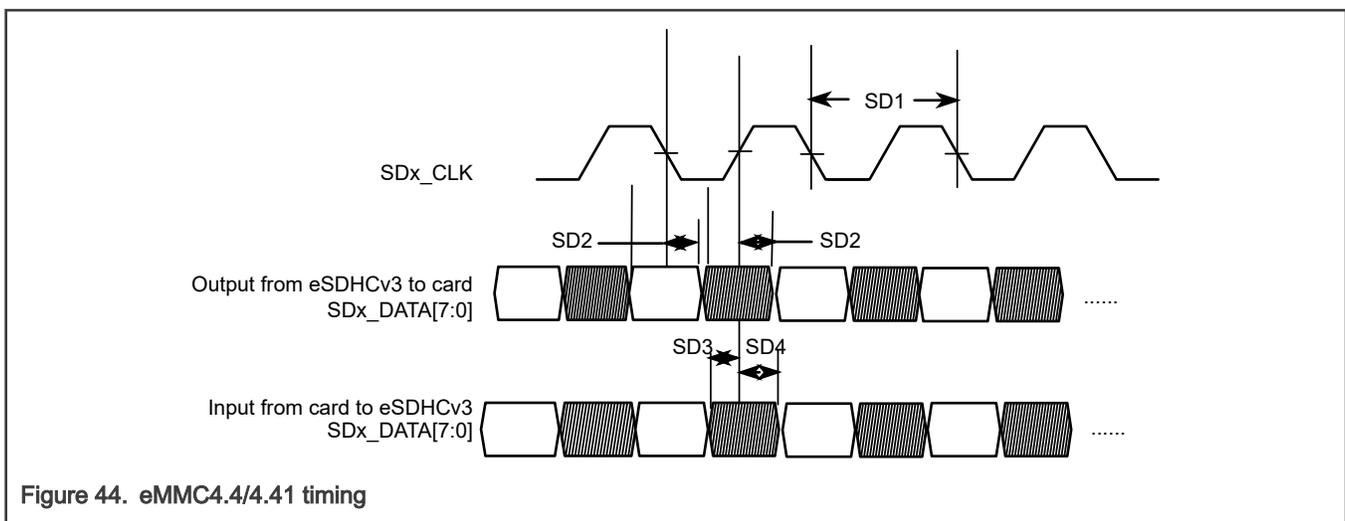


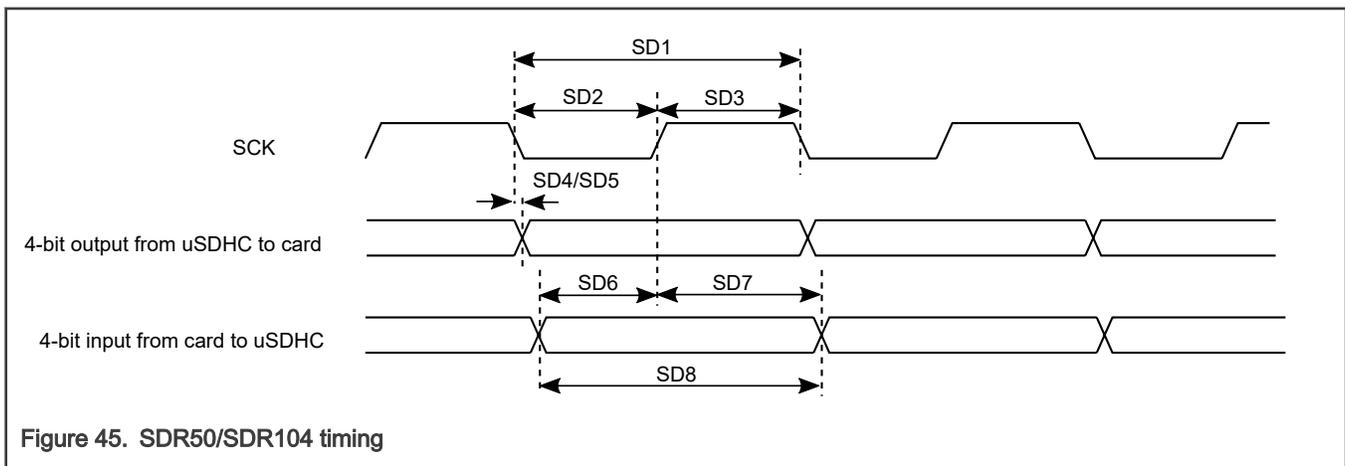
Figure 44. eMMC4.4/4.41 timing

**Table 61. eMMC4.4/4.41 interface timing specification**

ID	Parameter	Symbols	Min	Max	Unit
<b>Card Input Clock</b>					
SD1	Clock Frequency (eMMC4.4/4.41 DDR)	$f_{PP}$	0	52	MHz
SD1	Clock Frequency (SD3.0 DDR)	$f_{PP}$	0	50	MHz
<b>uSDHC Output / Card Inputs SD_CMD, SDx_DATAx (Reference to CLK)</b>					
SD2	uSDHC Output Delay	$t_{OD}$	2.5	7.1	ns
<b>uSDHC Input / Card Outputs SD_CMD, SDx_DATAx (Reference to CLK)</b>					
SD3	uSDHC Input Setup Time	$t_{ISU}$	1.7	—	ns
SD4	uSDHC Input Hold Time	$t_{IH}$	1.5	—	ns

**4.9.3.3 SDR50/SDR104 AC timing**

Figure 45 depicts the timing of SDR50/SDR104, and Table 62 lists the SDR50/SDR104 timing characteristics.



**Figure 45. SDR50/SDR104 timing**

**Table 62. SDR50/SDR104 interface timing specification**

ID	Parameter	Symbols	Min	Max	Unit
<b>Card Input Clock</b>					
SD1	Clock Frequency Period	$t_{CLK}$	5.0	—	ns
SD2	Clock Low Time	$t_{CL}$	$0.46 \times t_{CLK}$	$0.54 \times t_{CLK}$	ns
SD3	Clock High Time	$t_{CH}$	$0.46 \times t_{CLK}$	$0.54 \times t_{CLK}$	ns
<b>uSDHC Output/Card Inputs SD_CMD, SDx_DATAx in SDR50 (Reference to CLK)</b>					
SD4	uSDHC Output Delay	$t_{OD}$	-3	1	ns

*Table continues on the next page...*

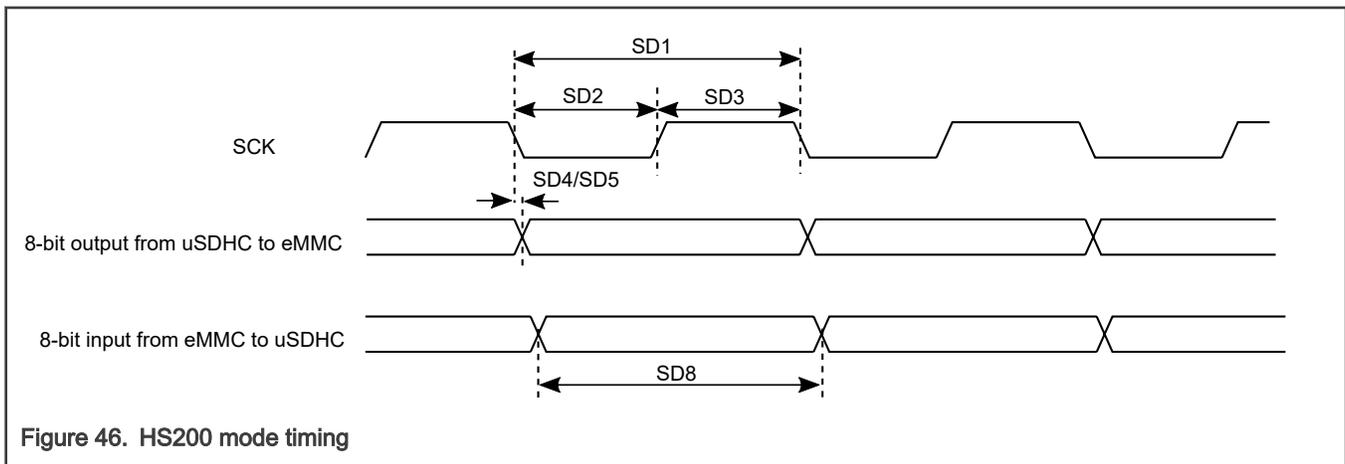
**Table 62. SDR50/SDR104 interface timing specification (continued)**

ID	Parameter	Symbols	Min	Max	Unit
<b>uSDHC Output/Card Inputs SD_CMD, SDx_DATAx in SDR104 (Reference to CLK)</b>					
SD5	uSDHC Output Delay	$t_{OD}$	-1.6	1	ns
<b>uSDHC Input/Card Outputs SD_CMD, SDx_DATAx in SDR50 (Reference to CLK)</b>					
SD6	uSDHC Input Setup Time	$t_{ISU}$	2.5	—	ns
SD7	uSDHC Input Hold Time	$t_{IH}$	1.5	—	ns
<b>uSDHC Input/Card Outputs SD_CMD, SDx_DATAx in SDR104 (Reference to CLK)<sup>1</sup></b>					
SD8	Card Output Data Window	$t_{ODW}$	$0.5 \times t_{CLK}$	—	ns

1. Data window in SDR104 mode is variable.

#### 4.9.3.4 HS200 mode timing

Figure 46 depicts the timing of HS200 mode, and Table 63 lists the HS200 timing characteristics.



**Figure 46. HS200 mode timing**

**Table 63. HS200 interface timing specification**

ID	Parameter	Symbols	Min	Max	Unit
<b>Card Input Clock</b>					
SD1	Clock Frequency Period	$t_{CLK}$	5.0	—	ns
SD2	Clock Low Time	$t_{CL}$	$0.46 \times t_{CLK}$	$0.54 \times t_{CLK}$	ns
SD3	Clock High Time	$t_{CH}$	$0.46 \times t_{CLK}$	$0.54 \times t_{CLK}$	ns
<b>uSDHC Output/Card Inputs SD_CMD, SDx_DATAx in HS200 (Reference to CLK)</b>					
SD5	uSDHC Output Delay	$t_{OD}$	-1.6	0.74	ns

Table continues on the next page...

**Table 63. HS200 interface timing specification (continued)**

ID	Parameter	Symbols	Min	Max	Unit
<b>uSDHC Input/Card Outputs SD_CMD, SDx_DATAx in HS200 (Reference to CLK)<sup>1</sup></b>					
SD8	Card Output Data Window	$t_{ODW}$	$0.5 \times t_{CLK}$	—	ns

1. HS200 is for 8 bits while SDR104 is for 4 bits.

**4.9.3.5 Bus operation condition for 3.3 V and 1.8 V signaling**

Signaling level of SD/eMMC4.3 and eMMC4.4/4.41 modes is 3.3 V. Signaling level of SDR104/SDR50 mode is 1.8 V. The DC parameters for the NVCC\_SD1 supply are identical to those shown in [Table 22](#).

**4.9.4 Ethernet controller (ENET) AC electrical specifications**

The following timing specs are defined at the chip I/O pin and must be translated appropriately to arrive at timing specs/constraints for the physical interface.

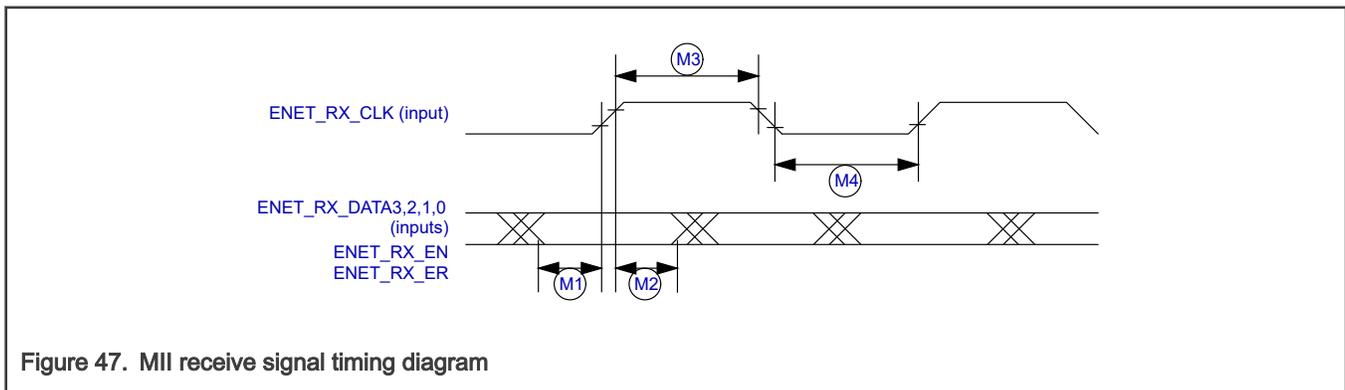
**4.9.4.1 ENET MII mode timing**

This subsection describes MII receive, transmit, asynchronous inputs, and serial management signal timings.

**4.9.4.1.1 MII receive signal timing (ENET\_RX\_DATA3,2,1,0, ENET\_RX\_EN, ENET\_RX\_ER, and ENET\_RX\_CLK)**

The receiver functions correctly up to an ENET\_RX\_CLK maximum frequency of 25 MHz + 1%. There is no minimum frequency requirement. Additionally, the processor clock frequency must exceed twice the ENET\_RX\_CLK frequency.

[Figure 47](#) shows MII receive signal timings. [Table 64](#) describes the timing parameters (M1–M4) shown in the figure.



**Figure 47. MII receive signal timing diagram**

**Table 64. MII receive signal timing**

ID	Characteristic <sup>1</sup>	Min.	Max.	Unit
M1	ENET_RX_DATA3,2,1,0, ENET_RX_EN, ENET_RX_ER to ENET_RX_CLK setup	5	—	ns
M2	ENET_RX_CLK to ENET_RX_DATA3,2,1,0, ENET_RX_EN, ENET_RX_ER hold	5	—	ns
M3	ENET_RX_CLK pulse width high	35%	65%	ENET_RX_CLK period
M4	ENET_RX_CLK pulse width low	35%	65%	ENET_RX_CLK period

<sup>1</sup> ENET\_RX\_EN, ENET\_RX\_CLK, and ENET0\_RXD0 have the same timing in 10 Mbps 7-wire interface mode.

#### 4.9.4.1.2 MII transmit signal timing (ENET\_TX\_DATA3,2,1,0, ENET\_TX\_EN, ENET\_TX\_ER, and ENET\_TX\_CLK)

The transmitter functions correctly up to an ENET\_TX\_CLK maximum frequency of 25 MHz + 1%. There is no minimum frequency requirement. Additionally, the processor clock frequency must exceed twice the ENET\_TX\_CLK frequency.

Figure 48 shows MII transmit signal timings. Table 65 describes the timing parameters (M5–M8) shown in the figure.

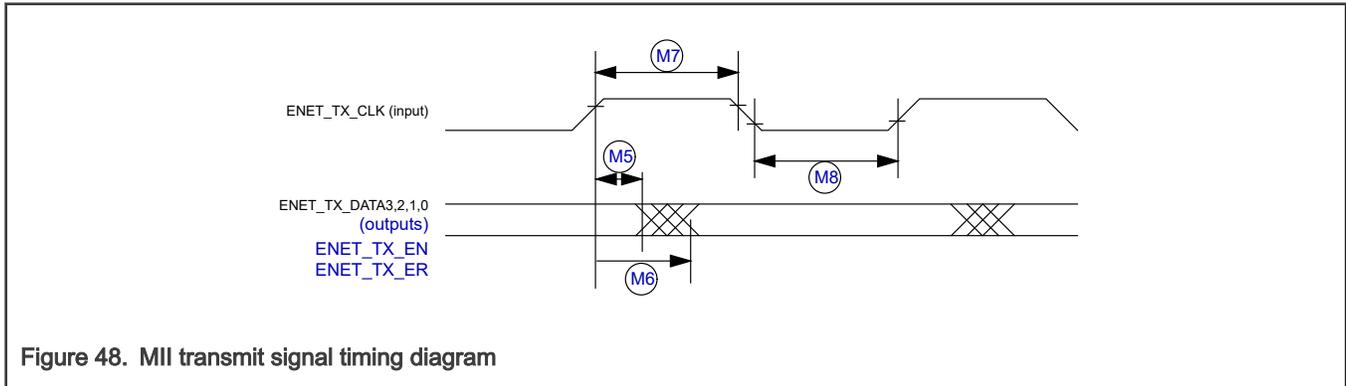


Table 65. MII transmit signal timing

ID	Characteristic <sup>1</sup>	Min.	Max.	Unit
M5	ENET_TX_CLK to ENET_TX_DATA3,2,1,0, ENET_TX_EN, ENET_TX_ER invalid	5	—	ns
M6	ENET_TX_CLK to ENET_TX_DATA3,2,1,0, ENET_TX_EN, ENET_TX_ER valid	—	20	ns
M7	ENET_TX_CLK pulse width high	35%	65%	ENET_TX_CLK period
M8	ENET_TX_CLK pulse width low	35%	65%	ENET_TX_CLK period

<sup>1</sup> ENET\_TX\_EN, ENET\_TX\_CLK, and ENET0\_TXD0 have the same timing in 10-Mbps 7-wire interface mode.

#### 4.9.4.1.3 MII asynchronous inputs signal timing (ENET\_CRS and ENET\_COL)

Figure 49 shows MII asynchronous input timings. Table 66 describes the timing parameter (M9) shown in the figure.

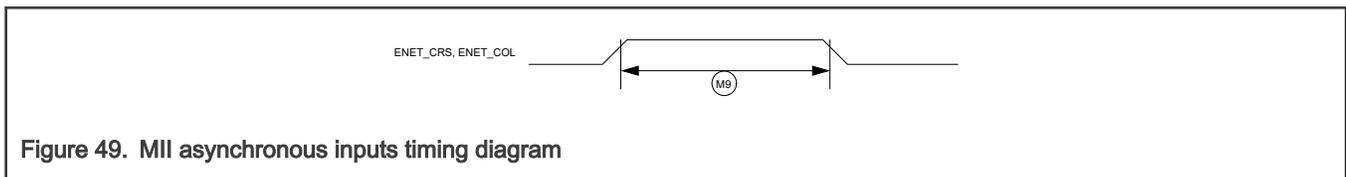


Table 66. MII asynchronous inputs signal timing

ID	Characteristic	Min.	Max.	Unit
M9 <sup>1</sup>	ENET_CRS to ENET_COL minimum pulse width	1.5	—	ENET_TX_CLK period

1. ENET\_COL has the same timing in 10-Mbit 7-wire interface mode.

#### 4.9.4.1.4 MII serial management channel timing (ENET\_MDIO and ENET\_MDC)

The MDC frequency is designed to be equal to or less than 2.5 MHz to be compatible with the IEEE 802.3 MII specification. However the ENET can function correctly with a maximum MDC frequency of 15 MHz.

Figure 50 shows MII asynchronous input timings. Table 67 describes the timing parameters (M10–M15) shown in the figure.

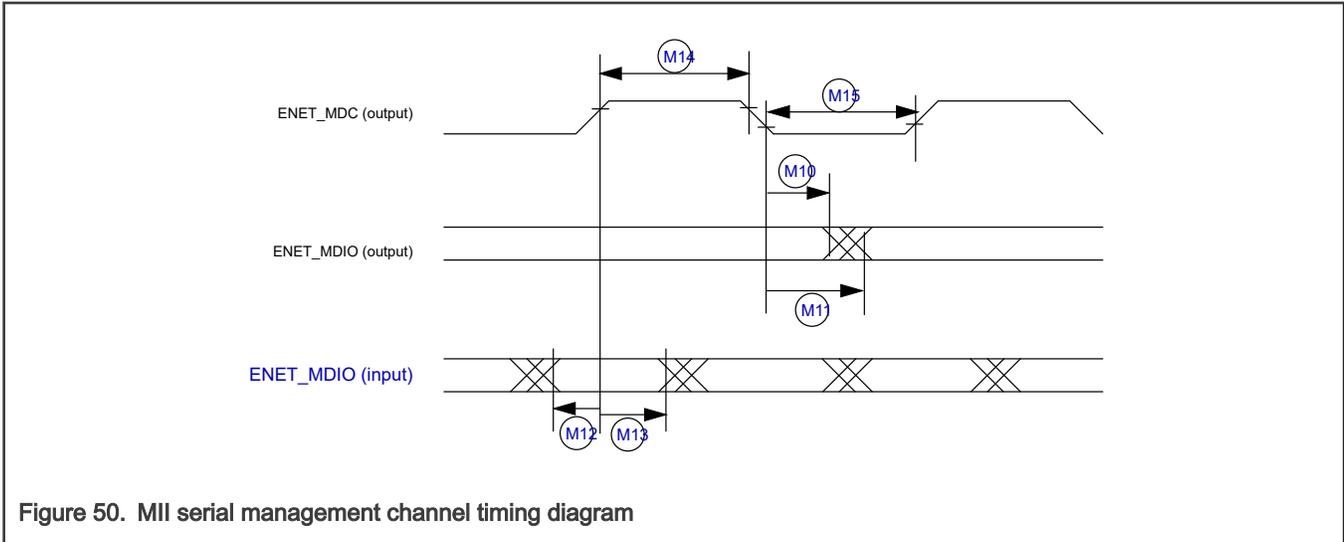


Figure 50. MII serial management channel timing diagram

Table 67. MII serial management channel timing

ID	Characteristic	Min.	Max.	Unit
M10	ENET_MDC falling edge to ENET_MDIO output invalid (min. propagation delay)	0	—	ns
M11	ENET_MDC falling edge to ENET_MDIO output valid (max. propagation delay)	—	5	ns
M12	ENET_MDIO (input) to ENET_MDC rising edge setup	18	—	ns
M13	ENET_MDIO (input) to ENET_MDC rising edge hold	0	—	ns
M14	ENET_MDC pulse width high	40%	60%	ENET_MDC period
M15	ENET_MDC pulse width low	40%	60%	ENET_MDC period

#### 4.9.4.2 RMII mode timing

In RMII mode, ENET\_CLK is used as the REF\_CLK, which is a 50 MHz ± 50 ppm continuous reference clock. ENET\_RX\_EN is used as the ENET\_RX\_EN in RMII. Other signals under RMII mode include ENET\_TX\_EN, ENET\_TX\_DATA[1:0], ENET\_RX\_DATA[1:0] and ENET\_RX\_ER.

Figure 51 shows RMII mode timings. Table 68 describes the timing parameters (M16–M21) shown in the figure.

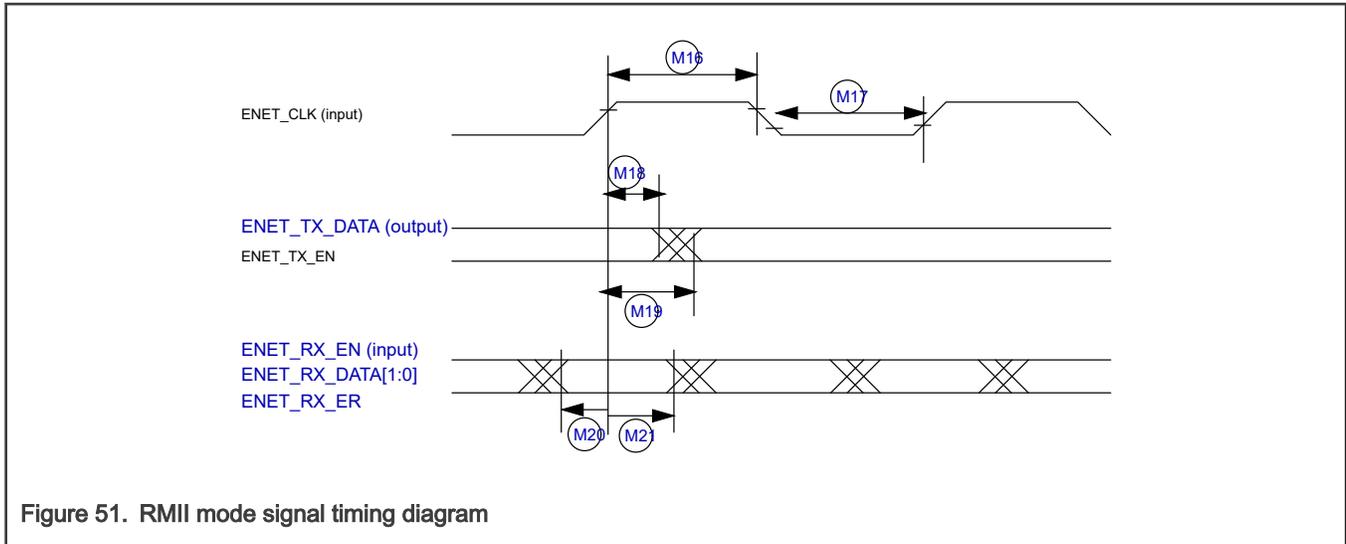


Figure 51. RMII mode signal timing diagram

Table 68. RMII signal timing

ID	Characteristic	Min.	Max.	Unit
M16	ENET_CLK pulse width high	35%	65%	ENET_CLK period
M17	ENET_CLK pulse width low	35%	65%	ENET_CLK period
M18	ENET_CLK to ENET0_TXD[1:0], ENET_TX_DATA invalid	4	—	ns
M19	ENET_CLK to ENET0_TXD[1:0], ENET_TX_DATA valid	—	13	ns
M20	ENET_RX_DATAD[1:0], ENET_RX_EN(ENET_RX_EN), ENET_RX_ER to ENET_CLK setup	2	—	ns
M21	ENET_CLK to ENET_RX_DATAD[1:0], ENET_RX_EN, ENET_RX_ER hold	2	—	ns

#### 4.9.5 Flexible Controller Area Network (FLEXCAN) AC electrical specifications

Please refer to [General purpose I/O AC parameters](#).

#### 4.9.6 LPUART electrical specifications

Please refer to [General purpose I/O AC parameters](#).

#### 4.9.7 USB PHY parameters

This section describes the USB-OTG PHY parameters.

The USB PHY meets the electrical compliance requirements defined in the Universal Serial Bus Revision 2.0 OTG with the following amendments.

- USB ENGINEERING CHANGE NOTICE
  - Title: 5V Short Circuit Withstand Requirement Change
  - Applies to: Universal Serial Bus Specification, Revision 2.0
- Errata for USB Revision 2.0 April 27, 2000 as of 12/7/2000
- USB ENGINEERING CHANGE NOTICE

- Title: Pull-up/Pull-down resistors
- Applies to: Universal Serial Bus Specification, Revision 2.0
- USB ENGINEERING CHANGE NOTICE
  - Title: Suspend Current Limit Changes
  - Applies to: Universal Serial Bus Specification, Revision 2.0
- USB ENGINEERING CHANGE NOTICE
  - Title: USB 2.0 Phase Locked SOFs
  - Applies to: Universal Serial Bus Specification, Revision 2.0
- On-The-Go and Embedded Host Supplement to the USB Revision 2.0 Specification
  - Revision 2.0 plus errata and ecn June 4, 2010
- Battery Charging Specification (available from USB-IF)
  - Revision 1.2, December 7, 2010
  - Portable device only

## 4.10 Timers

This section provides information on timers.

### 4.10.1 Pulse Width Modulator (PWM) characteristics

This section describes the electrical information of the PWM.

Table 69. PWM timing parameters

Parameter	Symbol	Min	Typ	Max	Unit
PWM Clock Frequency	—	—	—	150	MHz

### 4.10.2 Quad timer timing

Table 70 listed the timing parameters.

Table 70. Quad timer timing

Characteristic	Symbol	Min <sup>1</sup>	Max	Unit	See Figure
Timer input period	T <sub>IN</sub>	2T + 6	—	ns	
Timer input high/low period	T <sub>INHL</sub>	1T + 3	—	ns	
Timer output period	T <sub>OUT</sub>	33	—	ns	
Timer output high/low period	T <sub>OUTHL</sub>	16.7	—	ns	

1. T = clock cycle. For 60 MHz operation, T = 16.7 ns.

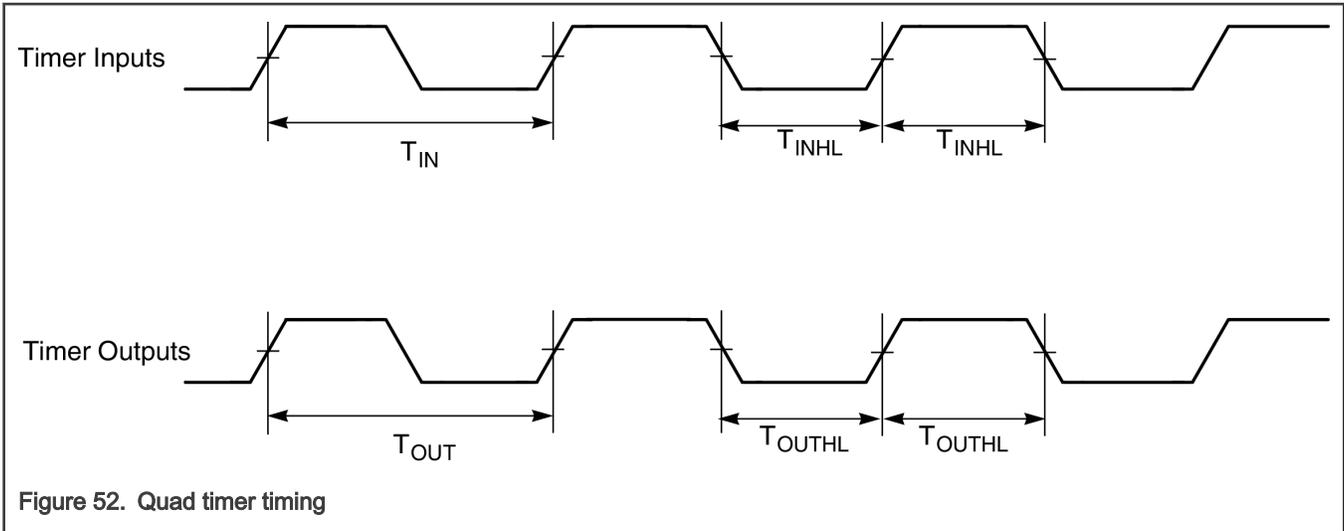


Figure 52. Quad timer timing

## 5 Boot mode configuration

This section provides information on boot mode configuration pins allocation and boot devices interfaces allocation.

### 5.1 Boot mode configuration pins

Table 71 provides boot options, functionality, fuse values, and associated pins. Several input pins are also sampled at reset and can be used to override fuse values, depending on the value of BT\_FUSE\_SEL fuse. The boot option pins are in effect when BT\_FUSE\_SEL fuse is '0' (cleared, which is the case for an unblown fuse). For detailed boot mode options configured by the boot mode pins, see the i.MX RT1060X Fuse Map document and the System Boot chapter in *i.MX RT1060X Reference Manual* (IMXRT1060XRM).

Table 71. Fuses and associated pins used for boot

Pad	Default setting on reset	eFuse name	Details
GPIO_AD_B0_04	100 K pull-down	BOOT_MODE0	
GPIO_AD_B0_05	100 K pull-down	BOOT_MODE1	
GPIO_B0_04	100 K pull-down	BT_CFG[0]	Boot Options, Pin value overrides fuse settings for BT_FUSE_SEL = '0'. Signal Configuration as Fuse Override Input at Power Up.  These are special I/O lines that control the boot up configuration during product development. In production, the boot configuration can be controlled by fuses.
GPIO_B0_05	100 K pull-down	BT_CFG[1]	
GPIO_B0_06	100 K pull-down	BT_CFG[2]	
GPIO_B0_07	100 K pull-down	BT_CFG[3]	
GPIO_B0_08	100 K pull-down	BT_CFG[4]	
GPIO_B0_09	100 K pull-down	BT_CFG[5]	
GPIO_B0_10	100 K pull-down	BT_CFG[6]	
GPIO_B0_11	100 K pull-down	BT_CFG[7]	

Table continues on the next page...

**Table 71. Fuses and associated pins used for boot (continued)**

Pad	Default setting on reset	eFuse name	Details
GPIO_B0_12	100 K pull-down	BT_CFG[8]	
GPIO_B0_13	100 K pull-down	BT_CFG[9]	
GPIO_B0_14	100 K pull-down	BT_CFG[10]	
GPIO_B0_15	100 K pull-down	BT_CFG[11]	

## 5.2 Boot device interface allocation

The following tables list the interfaces that can be used by the boot process in accordance with the specific boot mode configuration. The tables also describe the interface’s specific modes and IOMUXC allocation, which are configured during boot when appropriate.

**Table 72. Boot through NAND**

PAD Name	IO Function	ALT	Comments
GPIO_EMC_00	semc.DATA[0]	ALT 0	—
GPIO_EMC_01	semc.DATA[1]	ALT 0	—
GPIO_EMC_02	semc.DATA[2]	ALT 0	—
GPIO_EMC_03	semc.DATA[3]	ALT 0	—
GPIO_EMC_04	semc.DATA[4]	ALT 0	—
GPIO_EMC_05	semc.DATA[5]	ALT 0	—
GPIO_EMC_06	semc.DATA[6]	ALT 0	—
GPIO_EMC_07	semc.DATA[7]	ALT 0	—
GPIO_EMC_30	semc.DATA[8]	ALT 0	—
GPIO_EMC_31	semc.DATA[9]	ALT 0	—
GPIO_EMC_32	semc.DATA[10]	ALT 0	—
GPIO_EMC_33	semc.DATA[11]	ALT 0	—
GPIO_EMC_34	semc.DATA[12]	ALT 0	—
GPIO_EMC_35	semc.DATA[13]	ALT 0	—
GPIO_EMC_36	semc.DATA[14]	ALT 0	—
GPIO_EMC_37	semc.DATA[15]	ALT 0	—

*Table continues on the next page...*

**Table 72. Boot through NAND (continued)**

GPIO_EMC_18	semc.ADDR[9]	ALT 0	—
GPIO_EMC_19	semc.ADDR[11]	ALT 0	—
GPIO_EMC_20	semc.ADDR[12]	ALT 0	—
GPIO_EMC_22	semc.BA1	ALT 0	—
GPIO_EMC_41	semc.CSX[0]	ALT 0	—

**Table 73. Boot trough NOR**

PAD Name	IO Function	ALT	Comments
GPIO_EMC_00	semc.DATA[0]	ALT 0	—
GPIO_EMC_01	semc.DATA[1]	ALT 0	—
GPIO_EMC_02	semc.DATA[2]	ALT 0	—
GPIO_EMC_03	semc.DATA[3]	ALT 0	—
GPIO_EMC_04	semc.DATA[4]	ALT 0	—
GPIO_EMC_05	semc.DATA[5]	ALT 0	—
GPIO_EMC_06	semc.DATA[6]	ALT 0	—
GPIO_EMC_07	semc.DATA[7]	ALT 0	—
GPIO_EMC_30	semc.DATA[8]	ALT 0	—
GPIO_EMC_31	semc.DATA[9]	ALT 0	—
GPIO_EMC_32	semc.DATA[10]	ALT 0	—
GPIO_EMC_33	semc.DATA[11]	ALT 0	—
GPIO_EMC_34	semc.DATA[12]	ALT 0	—
GPIO_EMC_35	semc.DATA[13]	ALT 0	—
GPIO_EMC_36	semc.DATA[14]	ALT 0	—
GPIO_EMC_37	semc.DATA[15]	ALT 0	—
GPIO_EMC_09	semc.ADDR[0]	ALT 0	—
GPIO_EMC_10	semc.ADDR[1]	ALT 0	—
GPIO_EMC_11	semc.ADDR[2]	ALT 0	—

*Table continues on the next page...*

**Table 73. Boot trough NOR (continued)**

GPIO_EMC_12	semc.ADDR[3]	ALT 0	—
GPIO_EMC_13	semc.ADDR[4]	ALT 0	—
GPIO_EMC_14	semc.ADDR[5]	ALT 0	—
GPIO_EMC_15	semc.ADDR[6]	ALT 0	—
GPIO_EMC_16	semc.ADDR[7]	ALT 0	—
GPIO_EMC_19	semc.ADDR[11]	ALT 0	—
GPIO_EMC_20	semc.ADDR[12]	ALT 0	—
GPIO_EMC_21	semc.BA0	ALT 0	—
GPIO_EMC_22	semc.BA1	ALT 0	—
GPIO_EMC_41	semc.CSX[0]	ALT 0	—

**Table 74. Boot through FlexSPI**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B1_00	flexspi.B_DATA[3]	ALT 1	—
GPIO_SD_B1_01	flexspi.B_DATA[2]	ALT 1	—
GPIO_SD_B1_02	flexspi.B_DATA[1]	ALT 1	—
GPIO_SD_B1_03	flexspi.B_DATA[0]	ALT 1	—
GPIO_SD_B1_04	flexspi.B_SCLK	ALT 1	—
GPIO_SD_B0_05	flexspi.B_DQS	ALT 4	—
GPIO_SD_B0_04	flexspi.B_SS0_B	ALT 4	—
GPIO_SD_B0_01	flexspi.B_SS1_B	ALT 6	—
GPIO_SD_B1_05	flexspi.A_DQS	ALT 1	—
GPIO_SD_B1_06	flexspi.A_SS0_B	ALT 1	—
GPIO_SD_B0_00	flexspi.A_SS1_B	ALT 6	—
GPIO_SD_B1_07	flexspi.A_SCLK	ALT 1	—
GPIO_SD_B1_08	flexspi.A_DATA[0]	ALT 1	—
GPIO_SD_B1_09	flexspi.A_DATA[1]	ALT 1	—

*Table continues on the next page...*

**Table 74. Boot through FlexSPI (continued)**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B1_10	flexspi.A_DATA[2]	ALT 1	—
GPIO_SD_B1_11	flexspi.A_DATA[3]	ALT 1	—

**Table 75. Boot through SD1**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B0_00	usdhc1.CMD	ALT 0	—
GPIO_SD_B0_01	usdhc1.CLK	ALT 0	—
GPIO_SD_B0_02	usdhc1.DATA0	ALT 0	—
GPIO_SD_B0_03	usdhc1.DATA1	ALT 0	—
GPIO_SD_B0_04	usdhc1.DATA2	ALT 0	—
GPIO_SD_B0_05	usdhc1.DATA3	ALT 0	—

**Table 76. Boot through SD2**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B1_00	usdhc2.DATA3	ALT 0	—
GPIO_SD_B1_01	usdhc2.DATA2	ALT 0	—
GPIO_SD_B1_02	usdhc2.DATA1	ALT 0	—
GPIO_SD_B1_03	usdhc2.DATA0	ALT 0	—
GPIO_SD_B1_04	usdhc2.CLK	ALT 0	—
GPIO_SD_B1_05	usdhc2.CMD	ALT 0	—
GPIO_SD_B1_06	usdhc2.RESET_B	ALT 0	—
GPIO_SD_B1_08	usdhc2.DATA4	ALT 0	—
GPIO_SD_B1_09	usdhc2.DATA5	ALT 0	—
GPIO_SD_B1_10	usdhc2.DATA6	ALT 0	—
GPIO_SD_B1_11	usdhc2.DATA7	ALT 0	—

**Table 77. Boot through SPI-1**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B0_00	lpspi1.SCK	ALT 4	—
GPIO_SD_B0_02	lpspi1.SDO	ALT 4	—
GPIO_SD_B0_03	lpspi1.SDI	ALT 4	—
GPIO_SD_B0_01	lpspi1.PCS0	ALT 4	—

**Table 78. Boot through SPI-2**

PAD Name	IO Function	Mux Mode	Comments
GPIO_SD_B1_07	lpspi2.SCK	ALT 4	—
GPIO_SD_B1_08	lpspi2.SDO	ALT 4	—
GPIO_SD_B1_09	lpspi2.SDI	ALT 4	—
GPIO_SD_B1_06	lpspi2.PCS0	ALT 4	—

**Table 79. Boot through SPI-3**

PAD Name	IO Function	Mux Mode	Comments
GPIO_AD_B0_00	lpspi3.SCK	ALT 7	—
GPIO_AD_B0_01	lpspi3.SDO	ALT 7	—
GPIO_AD_B0_02	lpspi3.SDI	ALT 7	—
GPIO_SD_B0_03	lpspi3.PCS0	ALT 7	—

**Table 80. Boot through SPI-4**

PAD Name	IO Function	Mux Mode	Comments
GPIO_B0_03	lpspi4.SCK	ALT 3	—
GPIO_B0_02	lpspi4.SDO	ALT 3	—
GPIO_B0_01	lpspi4.SDI	ALT 3	—
GPIO_B0_00	lpspi4.PCS0	ALT 3	—

**Table 81. Boot through UART1**

PAD Name	IO Function	Mux Mode	Comments
GPIO_AD_B0_12	lpuart1.TX	ALT 2	—
GPIO_AD_B0_13	lpuart1.RX	ALT 2	—

## 6 Package information and contact assignments

This section includes the contact assignment information and mechanical package drawing.

### 6.1 13 x 13 mm package information

#### 6.1.1 13 x 13 mm, 0.8 mm pitch, ball matrix

[Figure 53](#) shows the top, bottom, and side views of the 13 x 13 mm MAPBGA package.

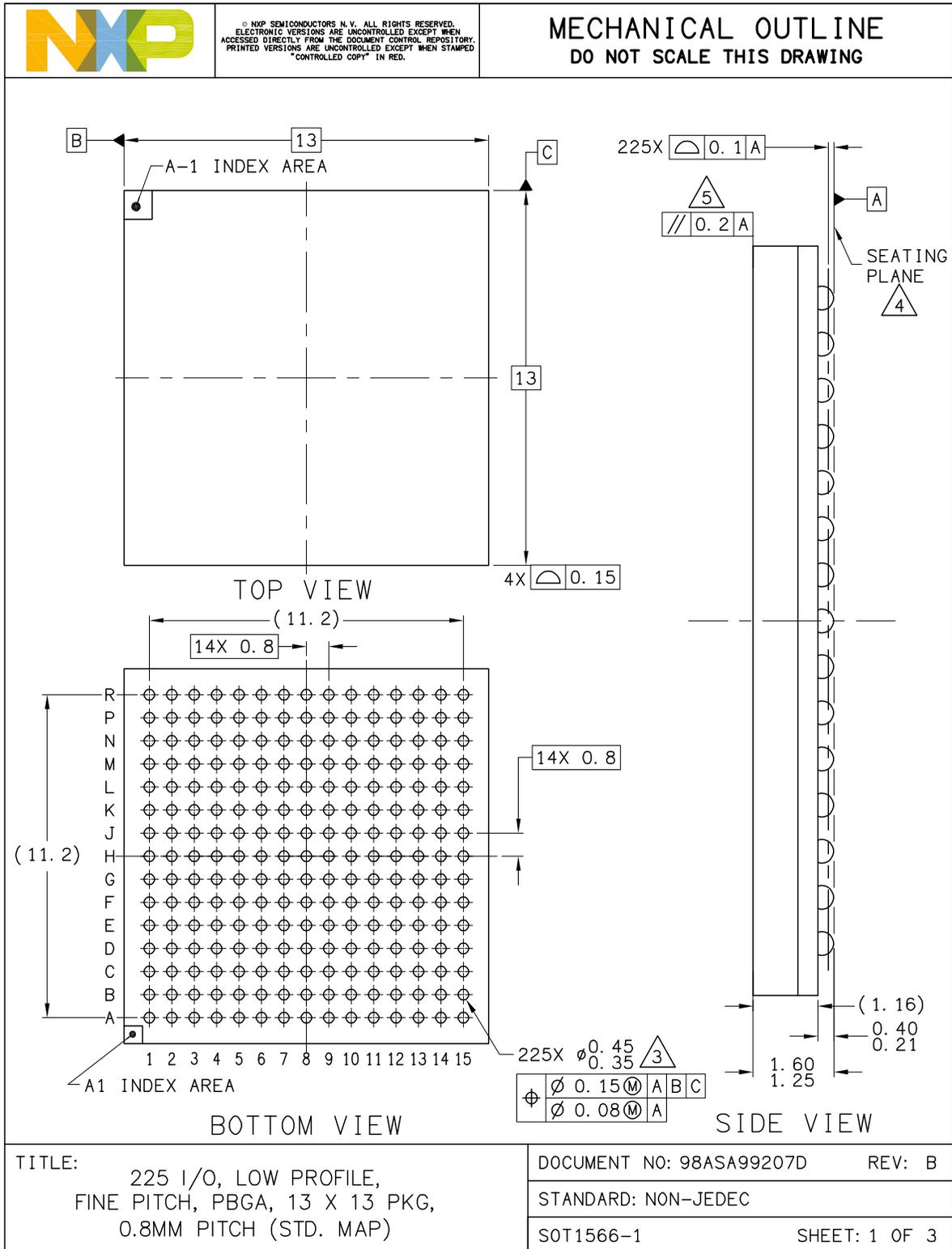


Figure 53. 13 x 13 mm BGA, case x package top, bottom, and side Views

### 6.1.2 13 x 13 mm supplies contact assignments and functional contact assignments

Table 82 shows the device connection list for ground, sense, and reference contact signals.

Table 82. 13 x 13 mm supplies contact assignment

Supply Rail Name	Ball(s) Position(s)	Remark
DCDC_IN	M1, M2	—
DCDC_IN_Q	L2	—
DCDC_GND	P1, P2	—
DCDC_LP	N1, N2	—
DCDC_PSWITCH	L3	—
DCDC_SENSE	K5	—
GPANAIO	P11	—
NGND_KEL0	L10	—
NVCC_EMC	G5, F5	—
NVCC_GPIO	E10, F11, J10	—
NVCC_PLL	R11	—
NVCC_SD0	J4	—
NVCC_SD1	L6	—
NVCC_SPI0	F7	—
NVCC_SPI1	K8	—
VDDA_ADC_3P3	M11	—
VDD_HIGH_CAP	N10	—
VDD_HIGH_IN	R13	—
VDD_SNVS_CAP	M10	—
VDD_SNVS_IN	N11	—
VDD_SOC_IN	F6, F8, F9, F10, G6, G10, H6, H10, J6, K6, K7	—
VDD_USB_CAP	K10	—
VSS	A1, A15, D6, D10, E4, E12, G7, G8, G9, H7, H8, H9, J7, J8, J9, K4, K12, M5, M6, M9, R1, R15	—

Table 83 shows an alpha-sorted list of functional contact assignments for the 13 x 13 mm package.

**Table 83. 13 x 13 mm functional contact assignments**

Ball Name	12 x 12 Ball	Power Group	Ball Type	Default Setting			Default setting on Reset		
				Default Mode	Default Function	Input/Output	Value	Input/Output	Value
CCM_CLK1_N	R14	—	—	—	CCM_CLK1_N	—	—	—	—
CCM_CLK1_P	P14	—	—	—	CCM_CLK1_P	—	—	—	—
GPIO_AD_B0_00	M14	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[0]	Input	Keeper	Input	Keeper
GPIO_AD_B0_01	H11	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[1]	Input	Keeper	Input	Keeper
GPIO_AD_B0_02	P15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[2]	Input	Keeper	Input	Keeper
GPIO_AD_B0_03	J13	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[3]	Input	Keeper	Input	Keeper
GPIO_AD_B0_04	G13	NVCC_GPIO	Digital GPIO	ALT0	SRC.BOOT.MOD E[0]	Input	100 K PD	Input	100 K PD
GPIO_AD_B0_05	H14	NVCC_GPIO	Digital GPIO	ALT0	SRC.BOOT.MOD E[1]	Input	100 K PD	Input	100 K PD
GPIO_AD_B0_06	G15	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.TMS	Input	47 K PU	Input	47 K PU
GPIO_AD_B0_07	G14	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.TCK	Input	47 K PU	Input	100 K PD
GPIO_AD_B0_08	H13	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.MOD	Input	100 K PU	Input	100 K PD
GPIO_AD_B0_09	H15	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.TDI	Input	47 K PU	Input	47 K PU
GPIO_AD_B0_10	H12	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.TDO	Input	Keeper	Input	Keeper
GPIO_AD_B0_11	G11	NVCC_GPIO	Digital GPIO	ALT0	JTAG.MUX.TRSTB	Input	47 K PU	Input	47 K PU
GPIO_AD_B0_12	L14	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[12]	Input	Keeper	Input	Keeper
GPIO_AD_B0_13	M15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[13]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_AD_B0_14	J15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[14]	Input	Keeper	Input	Keeper
GPIO_AD_B0_15	N12	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[15]	Input	Keeper	Input	Keeper
GPIO_AD_B1_00	J11	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[16]	Input	Keeper	Input	Keeper
GPIO_AD_B1_01	M12	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[17]	Input	Keeper	Input	Keeper
GPIO_AD_B1_02	L11	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[18]	Input	Keeper	Input	Keeper
GPIO_AD_B1_03	N13	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[19]	Input	Keeper	Input	Keeper
GPIO_AD_B1_04	L12	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[20]	Input	Keeper	Input	Keeper
GPIO_AD_B1_05	M13	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[21]	Input	Keeper	Input	Keeper
GPIO_AD_B1_06	N15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[22]	Input	Keeper	Input	Keeper
GPIO_AD_B1_07	K11	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[23]	Input	Keeper	Input	Keeper
GPIO_AD_B1_08	J14	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[24]	Input	Keeper	Input	Keeper
GPIO_AD_B1_09	N14	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[25]	Input	Keeper	Input	Keeper
GPIO_AD_B1_10	L13	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[26]	Input	Keeper	Input	Keeper
GPIO_AD_B1_11	L15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[27]	Input	Keeper	Input	Keeper
GPIO_AD_B1_12	K13	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[28]	Input	Keeper	Input	Keeper
GPIO_AD_B1_13	K15	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[29]	Input	Keeper	Input	Keeper
GPIO_AD_B1_14	J12	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[30]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_AD_B1_15	K14	NVCC_GPIO	Digital GPIO	ALT5	GPIO1.IO[31]	Input	Keeper	Input	Keeper
GPIO_B0_00	D9	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[0]	Input	Keeper	Input	Keeper
GPIO_B0_01	C10	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[1]	Input	Keeper	Input	Keeper
GPIO_B0_02	C11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[2]	Input	Keeper	Input	Keeper
GPIO_B0_03	B10	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[3]	Input	Keeper	Input	Keeper
GPIO_B0_04	E9	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[4]	Input	Keeper	Input	100 K PD
GPIO_B0_05	A11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[5]	Input	Keeper	Input	100 K PD
GPIO_B0_06	B11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[6]	Input	Keeper	Input	100 K PD
GPIO_B0_07	A12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[7]	Input	Keeper	Input	100 K PD
GPIO_B0_08	B12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[8]	Input	Keeper	Input	100 K PD
GPIO_B0_09	D11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[9]	Input	Keeper	Input	100 K PD
GPIO_B0_10	C12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[10]	Input	Keeper	Input	100 K PD
GPIO_B0_11	A13	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[11]	Input	Keeper	Input	100 K PD
GPIO_B0_12	D12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[12]	Input	Keeper	Input	100 K PD
GPIO_B0_13	E11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[13]	Input	Keeper	Input	100 K PD
GPIO_B0_14	E13	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[14]	Input	Keeper	Input	100 K PD
GPIO_B0_15	E14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[15]	Input	Keeper	Input	100 K PD

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_B1_00	A11	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[16]	Input	Keeper	Input	Keeper
GPIO_B1_01	A14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[17]	Input	Keeper	Input	Keeper
GPIO_B1_02	F12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[18]	Input	Keeper	Input	Keeper
GPIO_B1_03	D13	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[19]	Input	Keeper	Input	Keeper
GPIO_B1_04	G12	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[20]	Input	Keeper	Input	Keeper
GPIO_B1_05	F13	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[21]	Input	Keeper	Input	Keeper
GPIO_B1_06	D14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[22]	Input	Keeper	Input	Keeper
GPIO_B1_07	C13	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[23]	Input	Keeper	Input	Keeper
GPIO_B1_08	B14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[24]	Input	Keeper	Input	Keeper
GPIO_B1_09	B15	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[25]	Input	Keeper	Input	Keeper
GPIO_B1_10	C14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[26]	Input	Keeper	Input	Keeper
GPIO_B1_11	C15	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[27]	Input	Keeper	Input	Keeper
GPIO_B1_12	F14	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[28]	Input	Keeper	Input	Keeper
GPIO_B1_13	F15	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[29]	Input	Keeper	Input	Keeper
GPIO_B1_14	E15	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[30]	Input	Keeper	Input	Keeper
GPIO_B1_15	D15	NVCC_GPIO	Digital GPIO	ALT5	GPIO2.IO[31]	Input	Keeper	Input	Keeper
GPIO_EMC_00	D2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[0]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_EMC_01	E2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[1]	Input	Keeper	Input	Keeper
GPIO_EMC_02	F4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[2]	Input	Keeper	Input	Keeper
GPIO_EMC_03	G4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[3]	Input	Keeper	Output	Keeper
GPIO_EMC_04	H3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[4]	Input	Keeper	Input	Keeper
GPIO_EMC_05	H4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[5]	Input	Keeper	Input	Keeper
GPIO_EMC_06	J5	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[6]	Input	Keeper	Input	Keeper
GPIO_EMC_07	G3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[7]	Input	Keeper	Input	Keeper
GPIO_EMC_08	H5	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[8]	Input	Keeper	Input	Keeper
GPIO_EMC_09	F1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[9]	Input	Keeper	Input	Keeper
GPIO_EMC_10	H1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[10]	Input	Keeper	Input	Keeper
GPIO_EMC_11	H2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[11]	Input	Keeper	Input	Keeper
GPIO_EMC_12	J1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[12]	Input	Keeper	Input	Keeper
GPIO_EMC_13	B4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[13]	Input	Keeper	Input	Keeper
GPIO_EMC_14	A4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[14]	Input	Keeper	Input	Keeper
GPIO_EMC_15	B1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[15]	Input	Keeper	Input	Keeper
GPIO_EMC_16	C4	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[16]	Input	Keeper	Input	Keeper
GPIO_EMC_17	A3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[17]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_EMC_18	C1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[18]	Input	Keeper	Input	Keeper
GPIO_EMC_19	A2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[19]	Input	Keeper	Input	Keeper
GPIO_EMC_20	B3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[20]	Input	Keeper	Input	Keeper
GPIO_EMC_21	D1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[21]	Input	Keeper	Input	Keeper
GPIO_EMC_22	G1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[22]	Input	Keeper	Input	Keeper
GPIO_EMC_23	G2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[23]	Input	Keeper	Input	Keeper
GPIO_EMC_24	E3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[24]	Input	Keeper	Input	Keeper
GPIO_EMC_25	E1	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[25]	Input	Keeper	Input	Keeper
GPIO_EMC_26	B2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[26]	Input	Keeper	Input	Keeper
GPIO_EMC_27	C2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[27]	Input	100 K PD	Input	100 K PD
GPIO_EMC_28	F2	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[28]	Input	Keeper	Input	Keeper
GPIO_EMC_29	F3	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[29]	Input	Keeper	Input	Keeper
GPIO_EMC_30	C6	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[30]	Input	Keeper	Input	Keeper
GPIO_EMC_31	C5	NVCC_EMC	Digital GPIO	ALT5	GPIO4.IO[31]	Input	Keeper	Input	Keeper
GPIO_EMC_32	E6	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[18]	Input	Keeper	Input	Keeper
GPIO_EMC_33	D5	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[19]	Input	Keeper	Input	Keeper
GPIO_EMC_34	C3	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[20]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_EMC_35	D3	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[21]	Input	Keeper	Input	Keeper
GPIO_EMC_36	E5	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[22]	Input	Keeper	Input	Keeper
GPIO_EMC_37	D4	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[23]	Input	Keeper	Input	Keeper
GPIO_EMC_38	B5	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[24]	Input	Keeper	Input	Keeper
GPIO_EMC_39	A5	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[25]	Input	Keeper	Input	Keeper
GPIO_EMC_40	B6	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[26]	Input	Keeper	Input	Keeper
GPIO_EMC_41	E7	NVCC_EMC	Digital GPIO	ALT5	GPIO3.IO[27]	Input	Keeper	Input	Keeper
GPIO_SD_B0_00	J3	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[12]	Input	Keeper	Input	Keeper
GPIO_SD_B0_01	K3	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[13]	Input	Keeper	Input	Keeper
GPIO_SD_B0_02	K1	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[14]	Input	Keeper	Input	Keeper
GPIO_SD_B0_03	L1	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[15]	Input	Keeper	Input	Keeper
GPIO_SD_B0_04	J2	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[16]	Input	Keeper	Input	Keeper
GPIO_SD_B0_05	K2	NVCC_SD0	Digital GPIO	ALT5	GPIO3.IO[17]	Input	Keeper	Input	Keeper
GPIO_SD_B1_00	M7	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[0]	Input	Keeper	Input	Keeper
GPIO_SD_B1_01	N6	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[1]	Input	Keeper	Input	Keeper
GPIO_SD_B1_02	M3	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[2]	Input	Keeper	Input	Keeper
GPIO_SD_B1_03	L4	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[3]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_SD_B1_04	N3	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[4]	Input	Keeper	Input	Keeper
GPIO_SD_B1_05	N4	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[5]	Input	Keeper	Input	Keeper
GPIO_SD_B1_06	L5	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[6]	Input	Keeper	Input	Keeper
GPIO_SD_B1_07	M4	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[7]	Input	Keeper	Input	Keeper
GPIO_SD_B1_08	P3	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[8]	Input	Keeper	Input	Keeper
GPIO_SD_B1_09	N5	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[9]	Input	Keeper	Input	Keeper
GPIO_SD_B1_10	R2	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[10]	Input	Keeper	Input	Keeper
GPIO_SD_B1_11	R3	NVCC_SD1	Digital GPIO	ALT5	GPIO3.IO[11]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_00	A10	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[0]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_01	C9	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[1]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_02	D8	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[2]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_03	A9	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[3]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_04	B9	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[4]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_05	C8	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[5]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_06	E8	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[6]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_07	D7	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[7]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_08	B8	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[8]	Input	Keeper	Input	Keeper

*Table continues on the next page...*

**Table 83. 13 x 13 mm functional contact assignments (continued)**

GPIO_SPI_B0_09	A8	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[9]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_10	C7	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[10]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_11	B7	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[11]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_12	A7	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[12]	Input	Keeper	Input	Keeper
GPIO_SPI_B0_13	A6	NVCC_SPI0	Digital GPIO	ALT5	GPIO10.IO[13]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_00	L8	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[14]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_01	N7	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[15]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_02	R5	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[16]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_03	P6	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[17]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_04	L7	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[18]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_05	R4	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[19]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_06	P5	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[20]	Input	Keeper	Input	Keeper
GPIO_SPI_B1_07	P4	NVCC_SPI1	Digital GPIO	ALT5	GPIO10.IO[21]	Input	Keeper	Input	Keeper
ONOFF	R6	VDD_SNVS_I N	Digital GPIO	ALT0	ONOFF	Input	100 K PU	Input	100 K PU
PMIC_ON_REQ	K9	VDD_SNVS_I N	Digital GPIO	ALT0	SNVS_LP.PMIC_ ON_REQ	Output	100 K PU	Output	100 K PU
PMIC_STBY_RE Q	R9	VDD_SNVS_I N	Digital GPIO	ALT0	CCM.PMIC_VST BY_REQ	Output	100 K PU (PKE disabled)	Output	100 K PU (PKE disabled )

Table continues on the next page...

**Table 83. 13 x 13 mm functional contact assignments (continued)**

POR_B	P9	VDD_SNVN_I N	Digital GPIO	ALT0	SRC.POR_B	Input	100 K PU	Input	100 K PU
RTC_XTALI	P10	—	—	—	—	—	—	—	—
RTC_XTALO	R10	—	—	—	—	—	—	—	—
TEST_MODE	M8	VDD_SNVN_I N	Digital GPIO	ALT0	TCU.TEST_MOD E	Input	100 K PU	Input	100 K PU
USB_OTG1_CHD _B	P13	—	—	—	—	—	—	—	—
USB_OTG1_DN	P8	—	—	—	—	—	—	—	—
USB_OTG1_DP	R8	—	—	—	—	—	—	—	—
USB_OTG1_VBU S	N9	—	—	—	—	—	—	—	—
USB_OTG2_DN	P7	—	—	—	—	—	—	—	—
USB_OTG2_DP	R8	—	—	—	—	—	—	—	—
USB_OTG2_VBU S	N8	—	—	—	—	—	—	—	—
XTALI	R12	—	—	—	—	—	—	—	—
XTALO	P12	—	—	—	—	—	—	—	—
WAKEUP	L9	VDD_SNVN_I N	Digital GPIO	ALT5	GPIO5.IO[0]	Input	100 K PU	Input	100 K PU

**6.1.3 13 x 13 mm, 0.8 mm pitch, ball map**

Table 84 shows the 13 x 13 mm, 0.8 mm pitch ball map for the i.MX RT1060X.

**Table 84. 13 x 13 mm, 0.8 mm pitch, ball map**

	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9</b>	<b>10</b>	<b>11</b>	<b>12</b>	<b>13</b>	<b>14</b>	<b>15</b>	
<b>A</b>	VSS	GPIO _EM C_19	GPIO _EM C_17	GPIO _EM C_14	GPIO _EM C_39	GPIO _EM _SPI _B0_ 13	GPIO _EM _SPI _B0_ 12	GPIO _EM _SPI _B0_ 09	GPIO _EM _SPI _B0_ 03	GPIO _EM _SPI _B0_ 00	GPIO _EM _B0_ 05	GPIO _EM _B0_ 07	GPIO _EM _B0_ 11	GPIO _EM _B1_ 01	VSS	A
<b>B</b>	GPIO _EM C_15	GPIO _EM C_26	GPIO _EM C_20	GPIO _EM C_13	GPIO _EM C_38	GPIO _EM C_40	GPIO _EM _SPI _B0_ 11	GPIO _EM _SPI _B0_ 08	GPIO _EM _SPI _B0_ 04	GPIO _EM _B0_ 03	GPIO _EM _B0_ 06	GPIO _EM _B0_ 08	GPIO _EM _B1_ 00	GPIO _EM _B1_ 08	GPIO _EM _B1_ 09	B

Table continues on the next page...

**Table 84. 13 x 13 mm, 0.8 mm pitch, ball map (continued)**

<b>C</b>	GPIO _EM C_18	GPIO _EM C_27	GPIO _EM C_34	GPIO _EM C_16	GPIO _EM C_31	GPIO _EM C_30	GPIO _SPI _B0_10	GPIO _SPI _B0_05	GPIO _SPI _B0_01	GPIO _B0_01	GPIO _B0_02	GPIO _B0_10	GPIO _B1_07	GPIO _B1_10	GPIO _B1_11	<b>C</b>
<b>D</b>	GPIO _EM C_21	GPIO _EM C_00	GPIO _EM C_35	GPIO _EM C_37	GPIO _EM C_33	VSS	GPIO _SPI _B0_07	GPIO _SPI _B0_02	GPIO _B0_00	VSS	GPIO _B0_09	GPIO _B0_12	GPIO _B1_03	GPIO _B1_06	GPIO _B1_15	<b>D</b>
<b>E</b>	GPIO _EM C_25	GPIO _EM C_01	GPIO _EM C_24	VSS	GPIO _EM C_36	GPIO _EM C_32	GPIO _EM C_41	GPIO _SPI _B0_06	GPIO _B0_04	NVC C_G PIO	GPIO _B0_13	VSS	GPIO _B0_14	GPIO _B0_15	GPIO _B1_14	<b>E</b>
<b>F</b>	GPIO _EM C_09	GPIO _EM C_28	GPIO _EM C_29	GPIO _EM C_02	NVC C_E MC	VDD _SO C_IN	NVC C_SP I0	VDD _SO C_IN	VDD _SO C_IN	VDD _SO C_IN	NVC C_G PIO	GPIO _B1_02	GPIO _B1_05	GPIO _B1_12	GPIO _B1_13	<b>F</b>
<b>G</b>	GPIO _EM C_22	GPIO _EM C_23	GPIO _EM C_07	GPIO _EM C_03	NVC C_E MC	VDD _SO C_IN	VSS	VSS	VSS	VDD _SO C_IN	GPIO _AD_ B0_1 1	GPIO _B1_04	GPIO _AD_ B0_0 4	GPIO _AD_ B0_0 7	GPIO _AD_ B0_0 6	<b>G</b>
<b>H</b>	GPIO _EM C_10	GPIO _EM C_11	GPIO _EM C_04	GPIO _EM C_05	GPIO _EM C_08	VDD _SO C_IN	VSS	VSS	VSS	VDD _SO C_IN	GPIO _AD_ B0_0 1	GPIO _AD_ B0_1 0	GPIO _AD_ B0_0 8	GPIO _AD_ B0_0 5	GPIO _AD_ B0_0 9	<b>H</b>
<b>J</b>	GPIO _EM C_12	GPIO _SD_ B0_0 4	GPIO _SD_ B0_0 0	NVC C_S D0	GPIO _EM C_06	VDD _SO C_IN	VSS	VSS	VSS	NVC C_G PIO	GPIO _AD_ B1_0 0	GPIO _AD_ B1_1 4	GPIO _AD_ B0_0 3	GPIO _AD_ B1_0 8	GPIO _AD_ B0_1 4	<b>J</b>
<b>K</b>	GPIO _SD_ B0_0 2	GPIO _SD_ B0_0 5	GPIO _SD_ B0_0 1	VSS	DCD C_SE NSE	VDD _SO C_IN	VDD _SO C_IN	NVC C_SP I1	PMIC _ON_ REQ	VDD _USB _CAP	GPIO _AD_ B1_0 7	VSS	GPIO _AD_ B1_1 2	GPIO _AD_ B1_1 5	GPIO _AD_ B1_1 3	<b>K</b>
<b>L</b>	GPIO _SD_ B0_0 3	DCD C_IN _Q	DCD C_PS WITC H	GPIO _SD_ B1_0 3	GPIO _SD_ B1_0 6	NVC C_S D1	GPIO _SPI _B1_04	GPIO _SPI _B1_00	WAK EUP	NGN D_KE L0	GPIO _AD_ B1_0 2	GPIO _AD_ B1_0 4	GPIO _AD_ B1_1 0	GPIO _AD_ B0_1 2	GPIO _AD_ B1_1 1	<b>L</b>
<b>M</b>	DCD C_IN	DCD C_IN	GPIO _SD_ B1_0 2	GPIO _SD_ B1_0 7	VSS	VSS	GPIO _SD_ B1_0 0	TEST _MO DE	VSS	VDD _SNV S_CA P	VDD A_AD C_3P 3	GPIO _AD_ B1_0 1	GPIO _AD_ B1_0 5	GPIO _AD_ B0_0 0	GPIO _AD_ B0_1 3	<b>M</b>
<b>N</b>	DCD C_LP	DCD C_LP	GPIO _SD_ B1_0 4	GPIO _SD_ B1_0 5	GPIO _SD_ B1_0 9	GPIO _SD_ B1_0 1	GPIO _SPI _B1_01	USB_ OTG 2_VB US	USB_ OTG 1_VB US	VDD _HIG H_C AP	VDD _SNV S_IN	GPIO _AD_ B0_1 5	GPIO _AD_ B1_0 3	GPIO _AD_ B1_0 9	GPIO _AD_ B1_0 6	<b>N</b>

Table continues on the next page...

**Table 84. 13 x 13 mm, 0.8 mm pitch, ball map (continued)**

<b>P</b>	DCD C_G ND	DCD C_G ND	GPIO _SD_ B1_0 8	GPIO _SPI_ _B1_ 07	GPIO _SPI_ _B1_ 06	GPIO _SPI_ _B1_ 03	USB_ OTG 2_DN	USB_ OTG 1_DN	POR _B	RTC_ XTAL I	GPA NAIO	XTAL O	USB_ OTG 1_CH D_B	CCM _CLK 1_P	GPIO _AD_ B0_0 2	<b>P</b>
<b>R</b>	VSS	GPIO _SD_ B1_1 0	GPIO _SD_ B1_1 1	GPIO _SPI_ _B1_ 05	GPIO _SPI_ _B1_ 02	ONO FF	USB_ OTG 2_DP	USB_ OTG 1_DP	PMIC _STB Y_RE Q	RTC_ XTAL O	NVC C_PL L	XTAL I	VDD _HIG H_IN	CCM _CLK 1_N	VSS	<b>R</b>
	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9</b>	<b>10</b>	<b>11</b>	<b>12</b>	<b>13</b>	<b>14</b>	<b>15</b>	

## Legal information

### Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

### Definitions

**Draft** — A draft status on a document indicates that the content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included in a draft version of a document and shall have no liability for the consequences of use of such information.

**Short data sheet** — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

**Product specification** — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

### Disclaimers

**Limited warranty and liability** — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

**Right to make changes** — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Suitability for use** — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

**Limiting values** — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

**Terms and conditions of commercial sale** — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nxp.com/profile/terms>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

**No offer to sell or license** — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

**Hazardous voltage** — Although basic supply voltages of the product may be much lower, circuit voltages up to 60 V may appear when operating this product, depending on settings and application. Customers incorporating or otherwise using these products in applications where such high voltages may appear during operation, assembly, test etc. of such application, do so at their own risk. Customers agree to fully indemnify NXP Semiconductors for any damages resulting from or in connection with such high voltages. Furthermore, customers are drawn to safety standards (IEC 950, EN 60 950, CENELEC, ISO, etc.) and other (legal) requirements applying to such high voltages.

**Bare die** — All die are tested on compliance with their related technical specifications as stated in this data sheet up to the point of wafer sawing and are handled in accordance with the NXP Semiconductors storage and transportation conditions. If there are data sheet limits not guaranteed, these will be separately indicated in the data sheet. There are no post-packing tests performed on individual die or wafers.

NXP Semiconductors has no control of third party procedures in the sawing, handling, packing or assembly of the die. Accordingly, NXP Semiconductors assumes no liability for device functionality or performance of the die or systems after third party sawing, handling, packing or assembly of the die. It is the responsibility of the customer to test and qualify their application in which the die is used.

All die sales are conditioned upon and subject to the customer entering into a written die sale agreement with NXP Semiconductors through its legal department.

**Quick reference data** — The Quick reference data is an extract of the product data given in the Limiting values and Characteristics sections of this document, and as such is not complete, exhaustive or legally binding.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

**Suitability for use in non-automotive qualified products** — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

**Translations** — A non-English (translated) version of a document, including the legal information in that document, is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

**Security** — Customer understands that all NXP products may be subject to unidentified vulnerabilities or may support established security standards or specifications with known limitations. Customer is responsible for the design and operation of its applications and products throughout their lifecycles to reduce the effect of these vulnerabilities on customer's applications and products. Customer's responsibility also extends to other open and/or proprietary technologies supported by NXP products for use in customer's applications. NXP accepts no liability for any vulnerability. Customer should regularly check security updates from NXP and follow up appropriately.

Customer shall select products with security features that best meet rules, regulations, and standards of the intended application and make the ultimate design decisions regarding its products and is solely responsible for compliance with all legal, regulatory, and security related requirements concerning its products, regardless of any information or support that may be provided by NXP.

NXP has a Product Security Incident Response Team (PSIRT) (reachable at [PSIRT@nxp.com](mailto:PSIRT@nxp.com)) that manages the investigation, reporting, and solution release to security vulnerabilities of NXP products.

## Trademarks

Notice: All referenced brands, product names, service names, and trademarks are the property of their respective owners.

**NXP** — wordmark and logo are trademarks of NXP B.V.

**AMBA, Arm, Arm7, Arm7TDMI, Arm9, Arm11, Artisan, big.LITTLE, Cordio, CoreLink, CoreSight, Cortex, DesignStart, DynamIQ, Jazelle, Keil, Mali, Mbed, Mbed Enabled, NEON, POP, RealView, SecurCore, Socrates, Thumb, TrustZone, ULINK, ULINK2, ULINK-ME, ULINK-PLUS, ULINKpro, µVision, Versatile** — are trademarks or registered trademarks of Arm Limited (or its subsidiaries) in the US and/or elsewhere. The related technology may be protected by any or all of patents, copyrights, designs and trade secrets. All rights reserved.

**Airfast** — is a trademark of NXP B.V.

**Bluetooth** — the Bluetooth wordmark and logos are registered trademarks owned by Bluetooth SIG, Inc. and any use of such marks by NXP Semiconductors is under license.

**Cadence** — the Cadence logo, and the other Cadence marks found at [www.cadence.com/go/trademarks](http://www.cadence.com/go/trademarks) are trademarks or registered trademarks of Cadence Design Systems, Inc. All rights reserved worldwide.

**CodeWarrior** — is a trademark of NXP B.V.

**ColdFire** — is a trademark of NXP B.V.

**ColdFire+** — is a trademark of NXP B.V.

**CoolFlux** — is a trademark of NXP B.V.

**DESFire** — is a trademark of NXP B.V.

**EdgeLock** — is a trademark of NXP B.V.

**EdgeScale** — is a trademark of NXP B.V.

**eIQ** — is a trademark of NXP B.V.

**Embrace** — is a trademark of NXP B.V.

**Freescale** — is a trademark of NXP B.V.

**GreenChip** — is a trademark of NXP B.V.

**HITAG** — is a trademark of NXP B.V.

**ICODE and I-CODE** — are trademarks of NXP B.V.

**Immersiv3D** — is a trademark of NXP B.V.

**JCOP** — is a trademark of NXP B.V.

**Kinetis** — is a trademark of NXP B.V.

**Layerscape** — is a trademark of NXP B.V.

**Mantis** — is a trademark of NXP B.V.

**MCCI** — is a trademark of NXP B.V.

**MIFARE** — is a trademark of NXP B.V.

**MIFARE Classic** — is a trademark of NXP B.V.

**MIFARE Flex** — is a trademark of NXP B.V.

**MIFARE4Mobile** — is a trademark of NXP B.V.

**MIFARE Plus** — is a trademark of NXP B.V.

**MIFARE Ultralight** — is a trademark of NXP B.V.

**MIGLO** — is a trademark of NXP B.V.

**MOBILEGT** — is a trademark of NXP B.V.

**Mobileye** — M, M Mobileye and other Mobileye trademarks or logos appearing herein are trademarks of Mobileye Vision Technologies Ltd. in the United States, the EU and/or other jurisdictions.

**NTAG** — is a trademark of NXP B.V.

**NXP SECURE CONNECTIONS FOR A SMARTER WORLD** — is a trademark of NXP B.V.

**Oracle and Java** — are registered trademarks of Oracle and/or its affiliates.

**PEG** — is a trademark of NXP B.V.

**Plus X** — is a trademark of NXP B.V.

**POR** — is a trademark of NXP B.V.

**PowerQUICC** — is a trademark of NXP B.V.

**Processor Expert** — is a trademark of NXP B.V.

**QorIQ** — is a trademark of NXP B.V.

**QorIQ Qonverge** — is a trademark of NXP B.V.

**RoadLink** — wordmark and logo are trademarks of NXP B.V.

**SafeAssure** — is a trademark of NXP B.V.

**SafeAssure** — logo is a trademark of NXP B.V.

**SmartLX** — is a trademark of NXP B.V.

**SmartMX** — is a trademark of NXP B.V.

**StarCore** — is a trademark of NXP B.V.

**SuperFlash** This product uses SuperFlash® technology. SuperFlash® is a registered trademark of Silicon Storage Technology, Inc.

**Symphony** — is a trademark of NXP B.V.

**Synopsys & Designware** — are registered trademarks of Synopsys, Inc.

**Synopsys** — Portions Copyright © 2021 Synopsys, Inc. Used with permission.  
All rights reserved.

**Tower** — is a trademark of NXP B.V.

**UCODE** — is a trademark of NXP B.V.

**VortiQa** — is a trademark of NXP B.V.

**Vybrid** — is a trademark of NXP B.V.

arm

---

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

---

© NXP B.V. 2022.

All rights reserved.

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: [salesaddresses@nxp.com](mailto:salesaddresses@nxp.com)

Date of release: 06/2022

Document identifier: IMXRT1060XCEC