

### General Description

The SQ33604A is a fully-featured PWM controller integrated high voltage start-up circuit that operates over a wide input range up to 100V.

The SQ33604A adopts current mode, quasi constant-frequency control to avoid sub-harmonic oscillation with no need of slope compensation. The SQ33604A is specifically designed for both low cost, small size, high efficiency isolated solution with primary-side regulates (PSR) Flyback and Secondary-side regulates (SSR) Flyback application. Additional features include precision reference, output diode Compensation compensation (in PSR), over-voltage protection (in PSR) , line under-voltage lockout, cycle by cycle current limit, frequency modulation, soft-start, external programmable thermal shutdown and internal OTP.

The SQ33604A is available in a MSOP10 package.

### Features

- Integrated 100V HV Start-up circuit
- Flexible Topology:
  - Primary-Side Regulated (PSR) Flyback (250kHz/400kHz Selectable)
  - Secondary-Side Regulated (SSR) Flyback (Programmable Frequency)
- Precision Voltage Reference
- Output Diode Compensation in PSR Mode
- Source/Sink=0.5A/0.9A GATE Drivers
- Programmable Soft-start
- Programmable Line Under Voltage Lockout (UVLO) with Adjustable Hysteresis
- External Programmable Thermal Shutdown
- OLP compensation for wide-input range
- Cycle-by-Cycle Current Sense Limit
- Frequency Modulation for EMI reduction
- Hiccup Protection for OLP, SCP, OVP and Thermal Shutdown

### Applications

- Telecom Systems Isolated Power Supplies
- Industrial Isolated Power Supplies
- PoE (Power over Ethernet)/PD(Powered Device)

### Typical Application

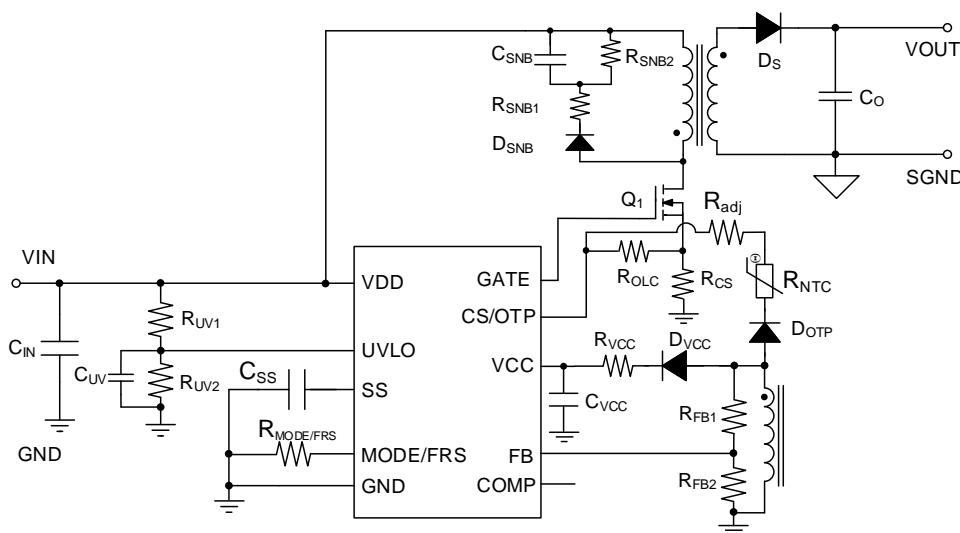


Fig.1 Typical Application-Isolated PSR Flyback Converter

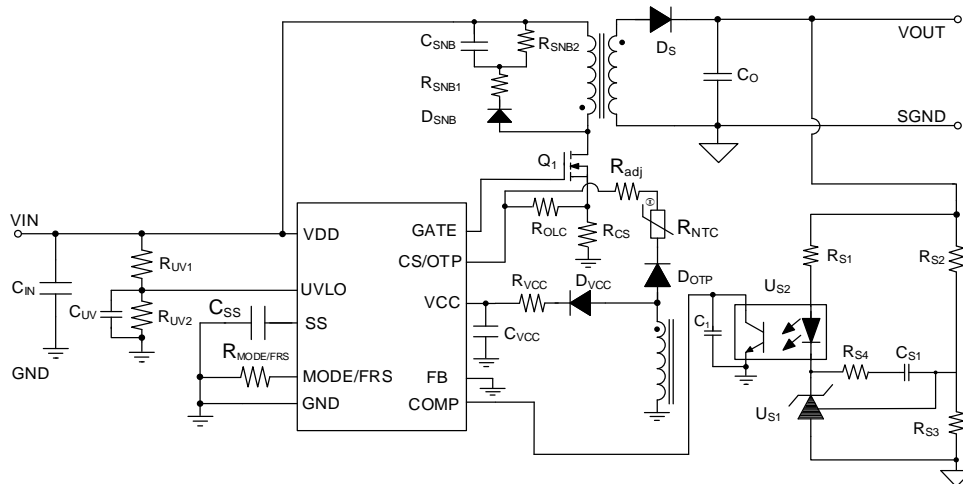


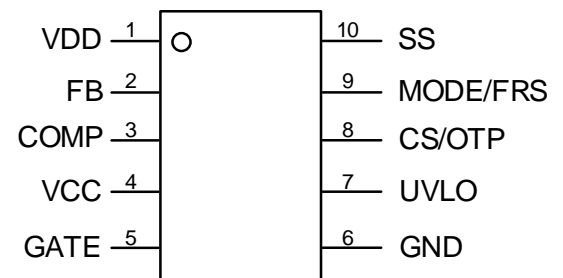
Fig.2 Typical Application-Isolated SSR Flyback Converter

## Ordering Information

Ordering Part Number	Package type	Top Mark
SQ33604AFBP	MSOP10 RoHS-Compliant and Halogen-Free	AAHMxyz

x = year code, y = week code, z = lot number code

## Pinout (top view)



## Pin Description

Pin No	Pin Name	Pin Description
1	VDD	Positive power supply terminal for controller input power rail.
2	FB	Output voltage feedback pin. Connect one resistor divider from sensing winding to regulate output voltage in PSR mode. In SSR mode, the FB should be connected to GND.
3	COMP	Loop compensation pin. Let it float in PSR mode, and internally pulled up to 3.3V through 10k resistor in SSR mode.
4	VCC	DC-DC internal circuit supply pin. Connect a bypass capacitor between this pin to GND.
5	GATE	Flyback MOSFET gate driver pin.
6	GND	Flyback controller ground.
7	UVLO	Input undervoltage detector. The input voltage is scaled down and sampled using a resistor divider. The controller is enabled once $V_{UVLO}$ exceeds the enable threshold.
8	CS/OTP	Current sense and external over-temperature protection pin.
9	MODE/FRS	PSR/SSR mode setting and SSR frequency setting pin. Connect a resistor from FRS to GND to program the converter switching frequency in SSR Mode.
10	SS	Soft-start setting pin. A capacitor from SS to GND pin sets the soft-start ( $I_{SSC}$ charge current) for the DC-DC converter.

## Block Diagram

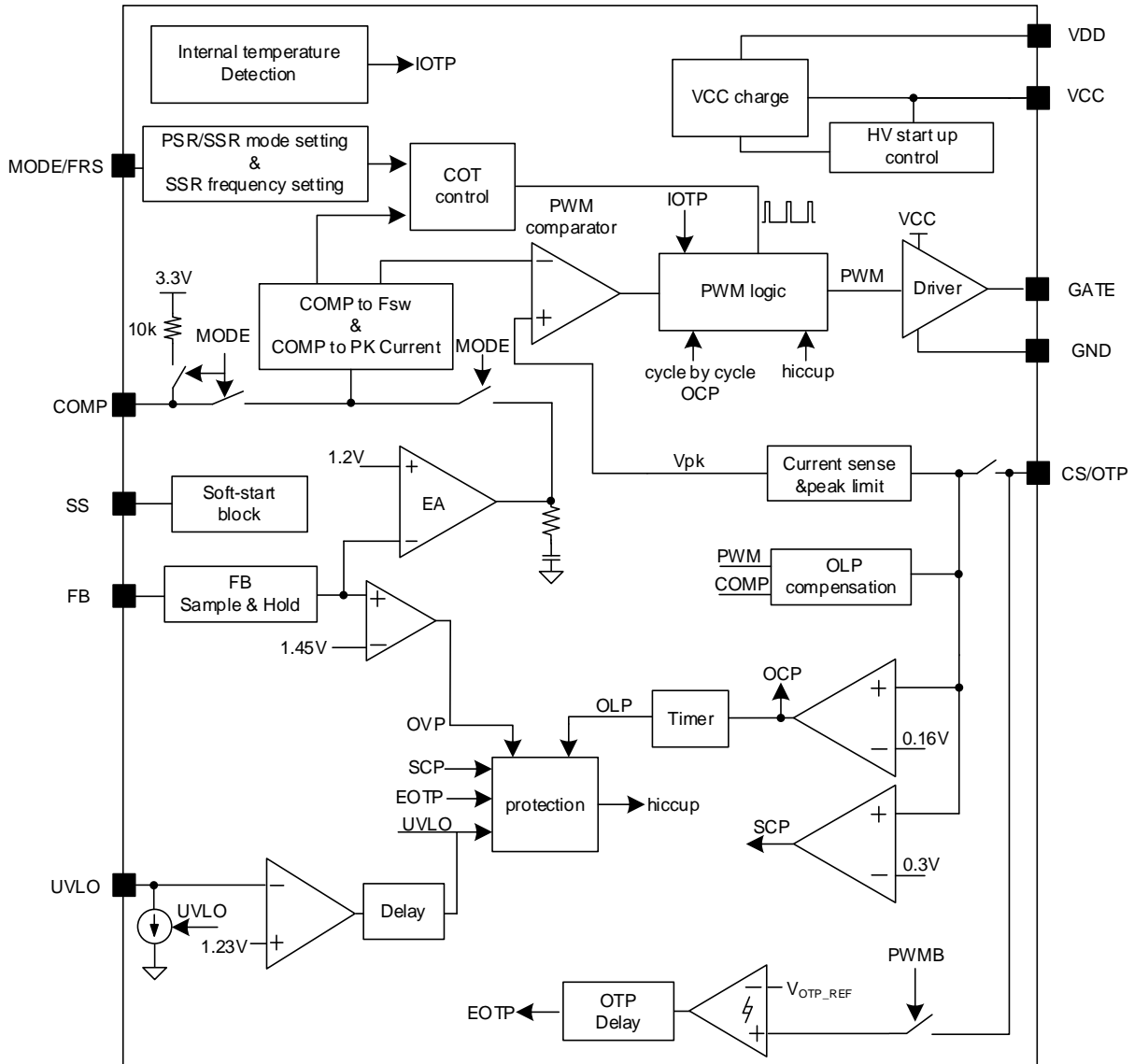


Fig.3 Block Diagram

## Absolute Maximum Ratings

Parameter (Note 1)		Min	Max	Unit
<b>Pins Voltage Respects to GND</b>				
VDD		-0.3	100	V
VCC, GATE		-0.3	20	
UVLO		-0.3	16	
FB, MODE/FRS, CS/OTP		-0.3	3.3	
SS, COMP		-0.3	3.6	
Junction Temperature, Operating		-45	150	°C
Lead Temperature (Soldering, 10 sec.)			260	
Storage Temperature		-65	150	
VESD Electrostatic Discharge	Human-body model(HBM), per ANSI/ESDA/JEDEC JS-001-2023		±2000	V
	Charged-device model(CDM), per ANSI/ESDA/JEDEC JS-001-2022		±750	

## Thermal Information

Parameter (Note 2)	Min	Max	Unit
$\theta_{JA}$ Junction-to-ambient Thermal Resistance		263	°C/W
$\theta_{JC}$ Junction-to-case Thermal Resistance		33	
$\theta_{JB}$ Junction-to-Board Thermal Resistance		140	
$P_D$ Power Dissipation $T_A = 25^\circ\text{C}$		0.38	W

## Recommended Operating Conditions

Parameter(Note 3)	Min	Max	Unit
VDD	9	75	V
VCC, GATE	8	15	
Junction Temperature $T_J$	-40	125	°C

## Electrical Characteristics

(All voltages are referred to GND. T<sub>J</sub>=-40°C to +125°C, typical values are tested at T<sub>J</sub>=25°C, unless otherwise specified(Note 4).)

Parameter		Symbol	Test conditions	Min	Typ	Max	Unit
Power Supply	VCC Turn on Threshold	V <sub>VCC_ON</sub>	V <sub>VCC</sub> rising	6.5	7	7.5	V
	VCC min Voltage	V <sub>VCC_MIN</sub>	V <sub>VCC</sub> falling	5.5	6	6.5	
	VCC Turn off Threshold	V <sub>VCC_OFF</sub>	V <sub>VCC</sub> falling	4.5	5	5.5	
	VCC OVP Threshold	V <sub>VCC_OVP</sub>	V <sub>VCC</sub> rising	18	19	20	
	Minimum Startup Voltage	V <sub>START(min)</sub>	the voltage of C <sub>VCC</sub> can be charged up to V <sub>VCC_ON</sub>	7.7	8.0	8.4	mA
	Quiescent Current	I <sub>Q</sub>	PSR , f <sub>SW</sub> = F <sub>SW_MIN</sub>	0.8	1.25	1.35	
			SSR , COMP=0	0.85	1.1	1.45	
HV Start-up Current	I <sub>VC</sub>	V <sub>VDD</sub> ≥ 18V, V <sub>VCC</sub> = 0 V	8	18			
		V <sub>VDD</sub> =10V, V <sub>VCC</sub> =0V	5	13			
Voltage Feedback	FB Reference Voltage	V <sub>REF</sub>	T <sub>J</sub> = 25°C	1.188	1.2	1.212	V
			T <sub>J</sub> = -40°C to +125°C	1.182	1.2	1.218	
	FB OVP Threshold	V <sub>FB_OVP</sub>		1.35	1.45	1.55	ns
	FB sample blanking	T <sub>blanking</sub>	PSR mode, F <sub>sw</sub> =250kHz, start from PWM downward edge	390	517	645	
			PSR mode, F <sub>sw</sub> =400kHz, start from PWM downward edge	280	365	450	
FB sample period	T <sub>sample</sub>	PSR mode, F <sub>sw</sub> =250kHz/400kHz,	100	135	175		
COMP	COMP Open Circuit Voltage		SSR mode, float COMP		3.3		V
	COMP Internal Pull up Resistor		SSR mode		10		kΩ
PWM Switching <sup>(Note 6)</sup>	Switching Frequency in SSR Mode	F <sub>SW</sub>	R <sub>FRS</sub> =7.5k Ω	-10%	500	+10%	kHz
	Switching Frequency in PSR mode	F <sub>SW_PSR</sub>	R <sub>MODE</sub> =0Ω	-10%	250	+10%	
			R <sub>MODE</sub> =open	-10%	400	+10%	
	Minimum fold-back frequency in PSR mode	F <sub>SW_MIN</sub>	In PSR Mode, Internal COMP=0V		4		
	Maximum ON time in PSR mode		PSR		5		us
Maximum DUTY in SSR mode		SSR		83		%	
Soft start	Soft Start Charge Current	I <sub>SSC</sub>		8.7	10	13.8	μA
Gate Driver	Peak Source Current	I <sub>SOURCE</sub>	V <sub>VCC</sub> =10V, V <sub>GATE</sub> = 0 V, pulsed measurement		0.5		A
	Peak Sink Current	I <sub>SINK</sub>	V <sub>VCC</sub> =10V, V <sub>GATE</sub> =10 V, pulsed measurement		0.9		A
Current Sense	Maximum Current Sense Limit	V <sub>CS_MAX</sub>		145	160	185	mV
	Low Threshold Current Limit	V <sub>CS_MIN</sub>	In PSR mode		42.5		mV

Parameter		Symbol	Test conditions	Min	Typ	Max	Unit	
Current Sense	SCP Limit	$V_{CS\_SCP}$		200	250	300	mV	
	Current Limit Leading Edge Blanking Time, same as $T_{ON-MIN}$	$T_{LEB}$		150	200	250	ns	
MODE/FRS	MODE pin detection current	$I_{MODE}$		31	40	49	$\mu A$	
	MODE pin detection period(Note 5)	$T_{MODE}$			100		$\mu s$	
	MODE pin detection threshold voltage	$V_{MODE}$	Voltage level 1 range (PSR Mode,FRS=250kHz)				0.09	V
			Voltage level 2 range (SSR Mode,Programmable FRS:100kHz~500kHz)	0.2		1.85	V	
Voltage level 3 range (PSR Mode,FRS=400kHz)			2.1			V		
UVLO	UVLO Enable Threshold	$V_{ENABLE}$	$V_{UVLO}$ rising		1.25		V	
	UVLO Protection Threshold	$V_{UVP}$		1.17	1.2	1.23	V	
	Pull down Current in UVLO Protection Mode	$I_{UVLO\_hys}$	$V_{UVLO} = V_{ENABLE} - 0.1V$	16	20	24	$\mu A$	
External OTP	Over-temperature Protection Threshold	$V_{OTP\_REF}$	$V_{OTP}$ rising	0.96	1	1.04	V	
	Over-temperature Protection Hysteresis	$V_{OTP\_HYS}$	$V_{OTP}$ falling		80		mV	
	OTP Delay	$T_{OTP\_Delay}$	$V_{OTP} = V_{OTP\_REF} + 20mV$		4		PWM cycle s	
Protection (Note 5)	Over Load Protection Hiccup on Time				4		ms	
	Protection Hiccup off Time				64			
	Thermal Shutdown Temperature	$T_{SD}$			160		$^{\circ}C$	
	Thermal Shutdown Hysteresis	$T_{HYS}$			20			

**Note 1:** Stresses beyond the “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Note 2:**  $\theta_{JA}$  is measured in natural convection at  $T_A = 25^{\circ}C$  on a 1oz two-layer Silergy evaluation board. Case temperature  $\theta_{JC}$  is measured at pin 5.

**Note 3:** The device is not guaranteed to function outside its operating conditions.

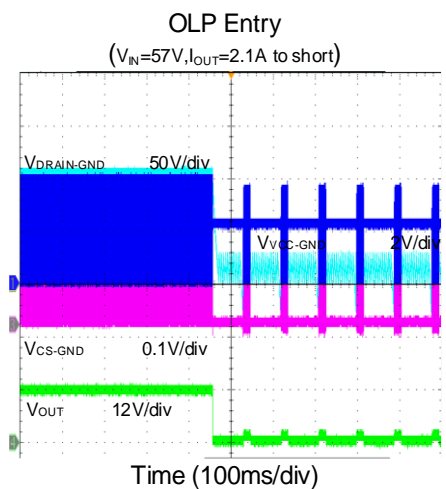
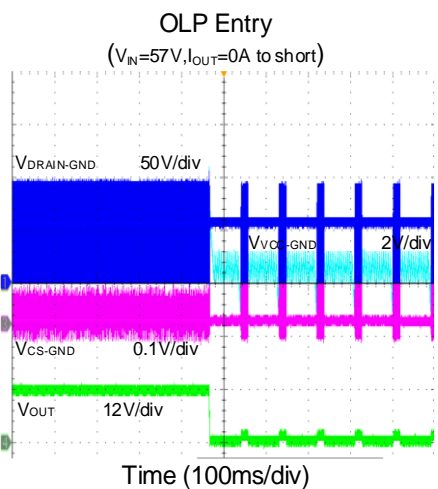
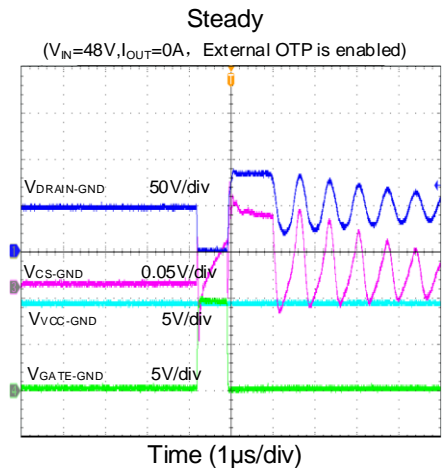
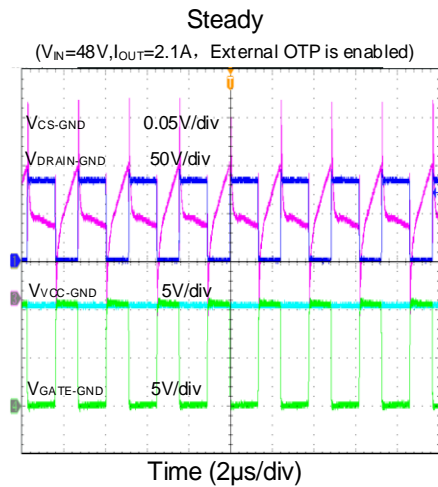
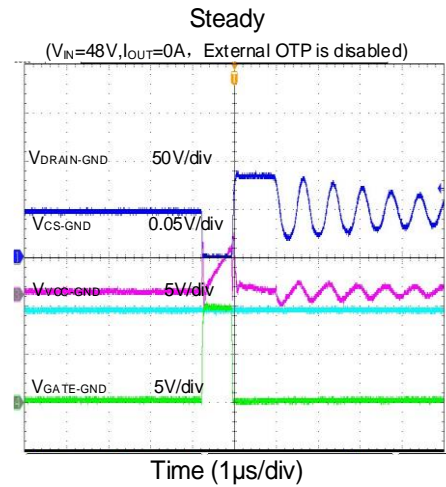
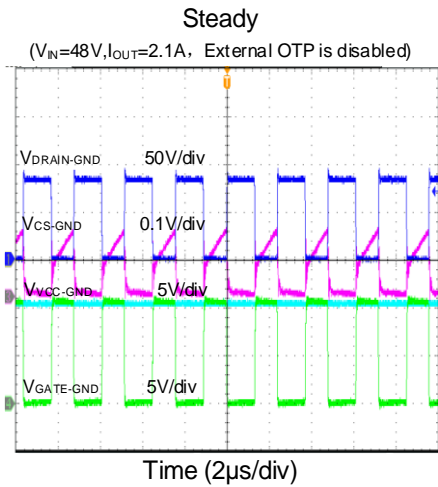
**Note 4:** Unless otherwise stated, limits are 100% production tested under pulsed load conditions such that  $T_A \cong T_J = 25^{\circ}C$ . Limits over the operating temperature range (See recommended operating conditions) and relevant voltage range(s) are guaranteed by design, test, or statistical correlation.

**Note 5:** Guaranteed by design or statistical correlation and not production tested.

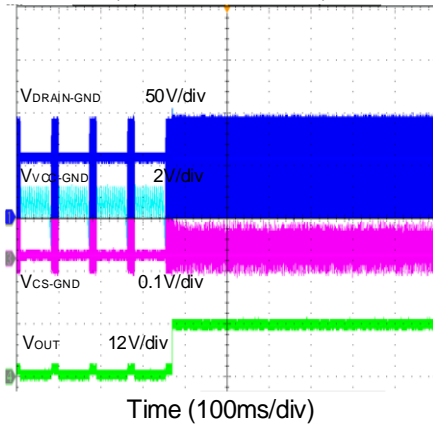
**Note 6:** Frequency and duty cycle are not including the range of jitter frequency.

## Typical Performance Characteristics

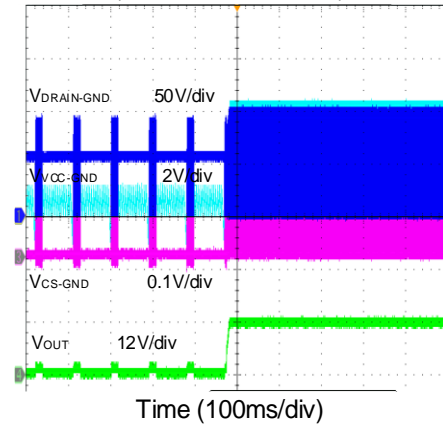
(DC Input Range : 42.5V~57V, output spec: 12Vdc/2.1A, Ambient temperature: 25±5°C. )



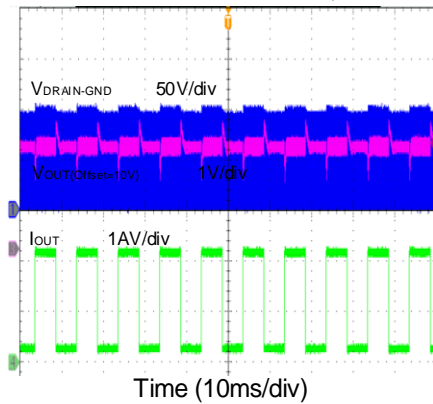
OLP Recovery  
( $V_{IN}=57V, I_{OUT}=\text{short to } 0A$ )



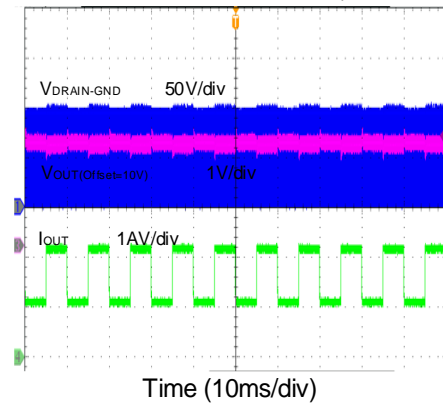
OLP Recovery  
( $V_{IN}=57V, I_{OUT}=\text{short to } 2.1A$ )



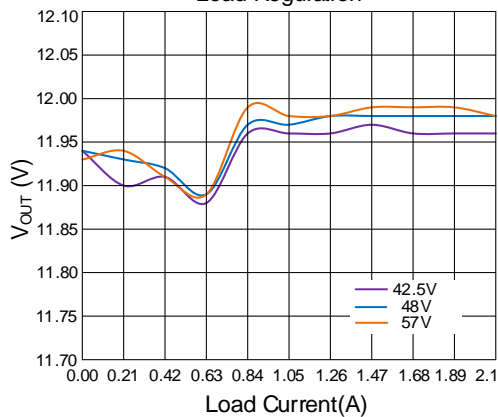
Load Transient  
( $V_{IN}=48V, I_{OUT}:0.21 \rightarrow 2.1A$ ,  
slew rate=2.5A/us, F=100Hz)



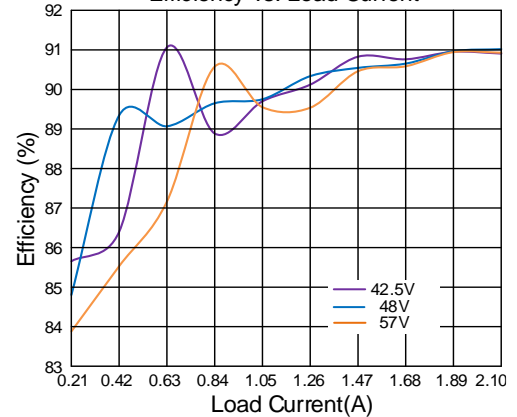
Load Transient  
( $V_{IN}=48V, I_{OUT}:0.21 \rightarrow 1.05A$ ,  
slew rate=2.5A/us, F=100Hz)



Load Regulation



Efficiency vs. Load Current



## Detailed Description

### Start-up Operation

After power supply, the capacitor across VCC and GND pins,  $C_{VCC}$  will be charged by the VDD voltage through the internal start-up circuit. Once the VCC voltage reaches  $V_{VCC\_ON}$ , the start-up charge current will be turned off, and if there is no fault and MODE/FRS pin detection is complete, the DC/DC converter will start operating. The start-up charge current will be turned on again if VCC decreases to  $V_{VCC\_MIN}$  (~6V) due to the power consumption until the auxiliary winding of Flyback transformer can supply sufficient energy to maintain  $V_{VCC}$  above  $V_{VCC\_MIN}$ .

If faults happen, the PWM switching stops, and the device switches to hiccup mode operation. In this mode, the hiccup off timer (64ms) will start, the start-up charge current will be turned on as needed to maintain the  $V_{VCC}$  between 7V and 6V. When the hiccup off time is over, the start-up charge current will be turned off, and when  $V_{VCC}$  decreases to 5V, the device enters the re-start sequence.

The device operation is shown in Fig.4.

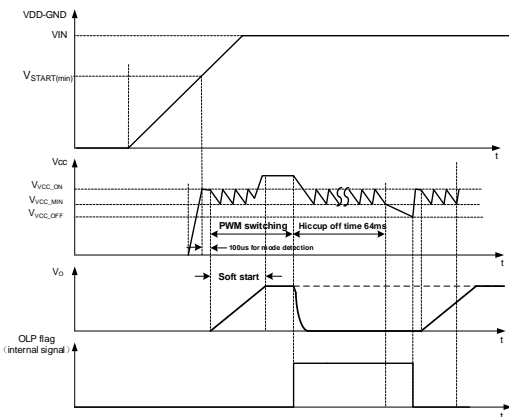


Fig.4 VCC Startup

### Work Mode Detection

After being enabled, the SQ33604A will source a 40μA current to MODE/FRS pin to detect the resistor setting. There are three operating modes which can be selected by setting the resistance value between MODE/FRS pin and GND. Refer to the table below for details.

Table 2. MODE Pin Program Options

MODE/FRS to GND Resistance			Working Mode
Min	Typical	Max	
0	0	1.8kΩ	PSR, 250kHz
7.5kΩ		37.5kΩ	SSR, $F_{SW}=3750/R_{mode}$ (kΩ)
68kΩ	open		PSR, 400kHz

### Output Voltage Control in PSR Mode

In order to achieve the primary side constant voltage control, the output voltage is detected by measuring the auxiliary winding voltage using the FB pin during the secondary side output diode conduction period. As shown in Fig.5 and Fig.6, When the secondary-side diode is conducting, the FB voltage can be calculated using equation (1).

$$V_{FB} = V_{AUX} * \frac{R_{FBD}}{R_{FBU} + R_{FBD}} = (V_{OUT} + V_{D\_F}) * \frac{N_{AUX}}{N_S} * \frac{R_{FBD}}{R_{FBU} + R_{FBD}} \quad (1)$$

Where  $N_{AUX}$  is the turns of auxiliary winding;  $N_S$  is the turns of secondary winding;  $V_{D\_F}$  is the forward voltage drop of the secondary-side diode.  $R_{FBD}$  and  $R_{FBU}$  are part of the the resistor divider used for FB sampling.

Fig.5 shows the FB sample control in discontinuous conduction mode (DCM), Fig.6 shows the FB sample control in continuous conduction mode (CCM).

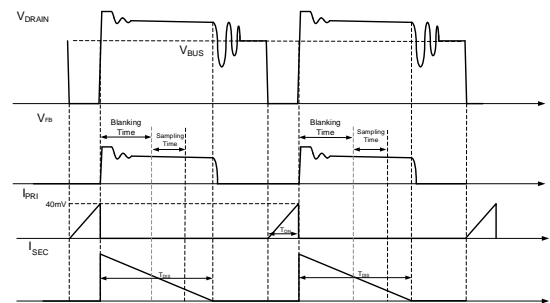


Fig.5 FB Sampling in DCM

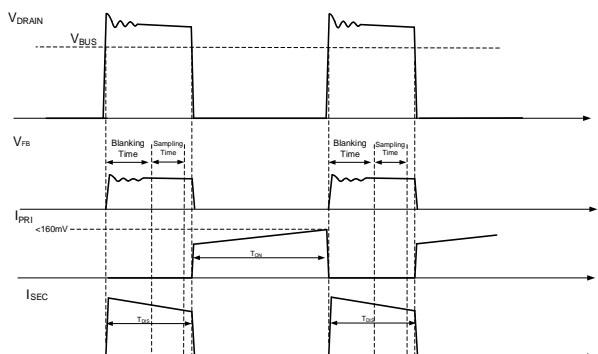


Fig.6 FB Sampling in CCM

The SQ33604A regulates the primary side MOSFET switching to ensure a peak current always  $\geq V_{CS\_MIN}/R_{CS}$  in PSR mode, and will start sampling the auxiliary-winding voltage after the power MOSFET is turned off. A blanking time is added to avoid measurement during the ringing caused by the leakage inductance. To guarantee long enough FB sample period, the output diode current conduction time ( $T_{DIS}$  in Fig.5 and Fig.6) should always be longer than 600ns in PSR 400kHz mode, and be longer than 800ns in PSR 250kHz mode.

In SSR mode, FB pin should be connected to GND and the voltage sampling function is disabled.

### Output Voltage Compensation in PSR Mode

To get good load regulation in PSR mode, the secondary diode voltage drop and the voltage drop on winding resistance are compensated. A sink current in FB pin which varies as the peak current is used for compensation during the FB sampling period.

The compensation current can be calculated using the equation (2).

$$I_{FB\_SINK} = 5\mu A * \frac{V_{CS} - 40mV}{100mV} \quad (2)$$

In SSR mode, this voltage compensation function is disabled.

### Current Sense, Over Current Protection (OCP) and Short Circuit Protection (SCP)

The SQ33604A uses a peak current mode Flyback control loop. The current through the external MOSFET is sensed through a sense resistor that is connected in series with the MOSFET source.

The voltage sensed at the CS/OTP pin during ON time is fed to the high-speed current comparator for current mode control.

If the voltage sensed at the CS/OTP pin is above the  $V_{CS\_MAX}$ , the comparator will turn off the MOSFET for the current cycle and keep it off until the internal oscillator starts the next cycle and senses the current again, resulting in a cycle-by-cycle current limit.

If the load continues increasing after the OCP protection is triggered, the output voltage will decrease, the COMP voltage will rise, and the peak current will trigger OCP every cycle. The SQ33604A sets the overload detection by continuously monitoring the  $V_{CS/OTP}$  voltage. Once the soft-start finishes, the over load protection (OLP) is enabled. If the OCP signal is detected continuously, and lasts more than 4ms, the DC/DC controller turns off the GATE driver and registers the event as overload protection (OLP). After 64ms hiccup off time, the SQ33604A will re-start with a new start-up cycle.

If the peak current cannot be limited by COMP in every cycle due to the minimum gate on time, the current may further increase and transformer may run into saturation. If the monitored  $V_{CS}$  voltage reaches 0.25V once, the off time will be forced to max toff, then if  $V_{CS}$  reaches 0.25V for the second time, the DC/DC controller registers it as short circuit protection (SCP), it will immediately terminate PWM switching and run into hiccup mode with 64ms hiccup off time, until the condition is removed.

### Over Load Protection (OLP) Compensation

The higher input voltage will always lead to higher over-load current limit when the peak current limit is constant, especially in wide input range applications, such as  $V_{IN}=9V\sim 57V$ . To solve this problem, an over-load compensation is used as shown in Fig.7

The over-load compensation current flows out of CS/OTP pin, with a compensation voltage generated across the external compensating resistor  $R_{OLC}$ . This is superimposed on the current sensing voltage and the sum is used to drive the input of peak current comparator.

The over-load compensation current is controlled by the internally derived  $T_{off}$  duty cycle signal. The control curve is shown in Fig.8. Adjusting the external resistor  $R_{OLC}$  enables selecting the proper compensation amplitude.

The over-load compensation is only needed when the current sensing voltage is close to the maximum allowed value. Under the light-load conditions, the compensation current  $I_{OLC}$  is disabled.

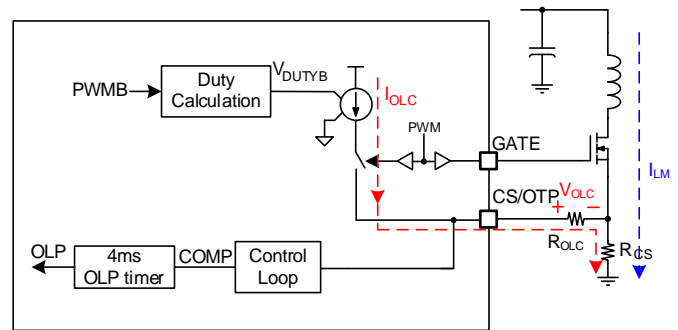


Fig.7 Over Load Compensation

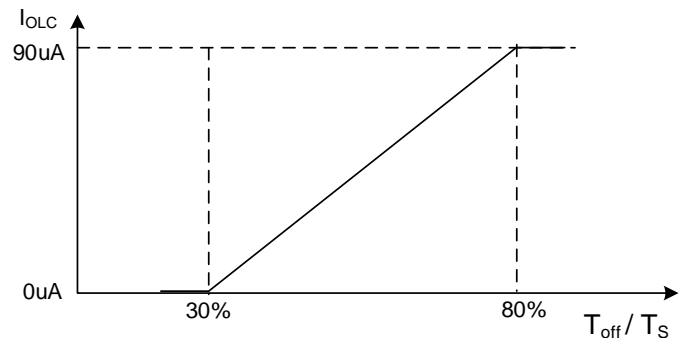


Fig.8  $T_{off}$  Duty Cycle VS.  $I_{OLC}$

### Soft Start

The SQ33604A provides a soft-start circuit based on charging an external capacitor with an internally generated constant current. Adjusting the external soft-start capacitor enables adjusting the soft-start time. The soft-start capacitor will be discharged completely when protections are triggered or during thermal shutdown.

The SS signal clamps COMP voltage in SSR mode, and it clamps internal  $V_{REF}$  in PSR mode.

## Clock Frequency Modulation

The device integrates a spread spectrum clock frequency modulation circuit to minimize EMI emissions. The modulation period is 4ms and the modulation range is  $\pm 6\%$  of the switching frequency.

## Line Undervoltage Detector

The SQ33604A monitors the line voltage and enables the controller when the input voltage is within the required range. The input voltage is sampled using a resistor divider connected to the UVLO pin. A small decoupling capacitor is recommended for noise filtering.

The controller transitions into the enable mode once  $V_{UVLO}$  exceeds  $V_{enable}$ . Once in enable mode, the controller is allowed to start if no other faults are present. An internal pull-down current source  $I_{UVLO-hys}$ , with a typical value of 20  $\mu A$  provides hysteresis.  $I_{UVLO-hys}$  turns off once the controller is enabled, allowing  $V_{UVLO}$  to rise above  $V_{enable}$  by the hysteresis level set by  $R_{UV1}$ . The controller is disabled if  $V_{UVLO}$  falls below  $V_{UVP}$ , at which point  $I_{UVLO-hys}$  is re-enabled creating a voltage drop on the UVLO pin.

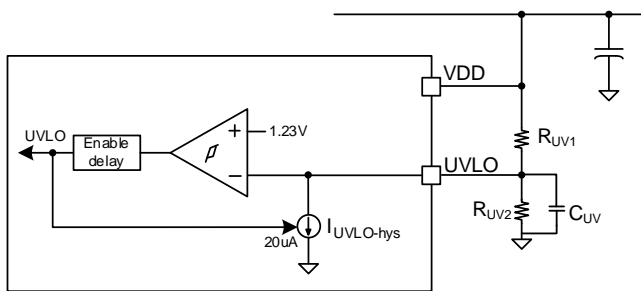


Fig.9 UVLO Block Diagram

## Output Over Voltage Protection in PSR Mode

In PSR mode, if the sampled voltage at FB pin exceeds 120% of  $V_{REF}$  for 4 consecutive switching cycles, which means OVP condition has been occurred, the device stops switching and enters hiccup mode immediately. After the 64ms hiccup off time, the device will attempt to restart. It returns to normal operation as soon as the condition disappears.

## External OTP

If temperature monitoring of the external MOSFET or transformer is needed, an external NTC resistor placed close to the component can be used. The NTC resistor forms a voltage divider with  $R_{OLC}+R_{CS}$  during secondary diode conduction period, as shown in Fig.10. When the temperature increases, the NTC resistance becomes lower and the CS/OTP pin voltage increases.

When the detected voltage exceeds 1V for 4 consecutive cycles, the device registers the event as an external OTP. The switching stops immediately and the device enters hiccup mode. When the detected voltage falls below 0.92V, the device resumes normal operation.

A resistor  $R_{adj}$  connected in series with NTC can be used to adjust the divider ratio and therefore adjust the OTP threshold.

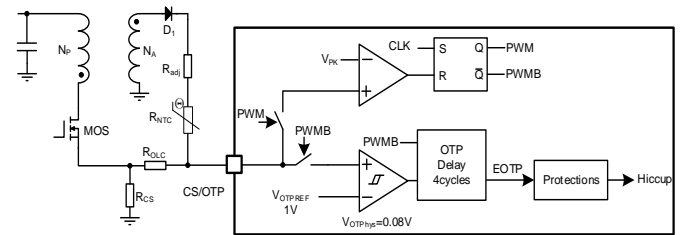


Fig.10 External OTP

## VCC Over Voltage Protection

When the VCC voltage exceeds the  $V_{VCC\_OVP}$  threshold, the device stops switching and enters hiccup mode. After 64ms hiccup off time ends, the device will restart. It will continue to operate in this mode until the overvoltage condition disappears.



D <sub>VCC</sub>	250V/250mA,Diode,SOD-123	BAV21W	Jingdao
D <sub>OTP</sub>	75V/150mA,Diode,SOD-123	1N4148	Jingdao
Q1	150V/52mΩ/ 21A, NMOS,PG-TDSON-8	BSC520N15NS3 G	Infineon
DS1	10A/80V,Schottky Diode, TO-277	PT10L80SP	PFC Device
DS2	250V/250mA,Diode,SOD-123	BAV21W	Jingdao
R <sub>UV1</sub>	360k, ±1%,0603	RC0603FR-07360KL	YAGEO
R <sub>UV2</sub>	20k, ±1%,0603	RC0603FR-0720KL	YAGEO
R <sub>SNB1</sub>	20k, ±1%,0805	RT0805BRD0720KL	YAGEO
R <sub>SNB2</sub>	NC	/	/
R <sub>SNB3</sub>	10, ±1%,0805	RC0805FR-0710RL	YAGEO
R <sub>gate</sub>	10, ±1%,0805	RC0805FR-0710RL	YAGEO
R <sub>OLC</sub>	620, ±1%,0603	RC0603FR-07620RL	YAGEO
R <sub>CS1</sub>	0.12, ±1%,1206	RL1206FR-7W0R12L	YAGEO
R <sub>CS2</sub>	0.12, ±1%,1206	RL1206FR-7W0R12L	YAGEO
R <sub>adj</sub>	2.4k, ±1%,0603	RC0603FR-072K4L	YAGEO
R <sub>NTC</sub>	NTC Thermistor,0603 (2.4k/0603@125°C ,100k/0603@25°C)	DNT1608X104□3950◎TF	Sunlord
R <sub>VCC</sub>	10, ±1%,0603	RT0603BRD0710KL	YAGEO
R <sub>FBU</sub>	39k, ±1%,0603	RC0603FR-0739KL	YAGEO
R <sub>FBD</sub>	5.1k, ±1%,0603	RC0603FR-075K1L	YAGEO
RS1	51k, ±1%,1206	RC1206FR-0751KL	YAGEO
RS2	2.4k, ±1%,1206	RC1206FR-072K4L	YAGEO
L <sub>1</sub>	shorted	/	/
T1	L <sub>M</sub> =42uH,EP13 N <sub>Pri</sub> :N <sub>Sec</sub> :N <sub>Aux</sub> =21:7:6	750345603	Wurth Elektronik
U1	100V high Efficiency PSR/SSR Flyback Controller	SQ33604A	SILERGY

## Design Procedure and Example

A design example of typical PSR application is shown below step by step.

### Design Notice:

1. At any condition, the secondary diode conduction time should be longer than 600ns (400kHz PSR)/800ns (250kHz PSR) for sufficient sampling time.
2.  $R_{FBU}$  is the upper resistor of the divider. Normally, its value is recommended between 18k $\Omega$ ~51k $\Omega$ .

### Identify Design Specification

Design Specification			
$V_{IN}$	42.5V~57V	$\eta$	88%
$V_{OUT}$	12V	$I_{OUT}$	2.1A

### Transformer $N_{PS}$ and $L_M$ Selection

$N_{PS}$  is limited by the breakdown voltage of the power MOSFET:

$$N_{PS} \leq \frac{V_{MOS\_ (BR)DS} \times 90\% - V_{DC\_MAX} - \Delta V_S}{V_{OUT} + V_{D\_F}} \quad (3)$$

Where  $V_{MOS\_ (BR)DS}$  is the breakdown voltage of the power MOSFET.

In constant frequency, continuous conduction mode, each switching period cycle  $t_s$  consists of two parts: current rising time  $T_{ON}$ , current falling time  $T_{DIS}$ , as shown in Fig.6.

For a selected turns ratio, the duty cycle can be calculated with equation (4)

$$\text{Duty Cycle} = \frac{N_{PS} * V_{OUT}}{V_{IN} + N_{PS} * V_{OUT}} \quad (4)$$

The maximum duty cycle means minimum  $T_{DIS}$ , so the duty cycle at the lowest input voltage should be checked to ensure long enough sampling time.

The primary-side inductance affects the input current ripple factor. A high inductance results in a large transformer size and high cost; a low inductance results in high switching peak current and RMS current, which causes a decrease in efficiency. Choose a primary-side inductance to make the current ripple ratio factor around 30% ~ 50%. Estimate the primary-side inductance with:

$$L_M = \frac{(V_{IN} * D)^2}{2 * f_{sw} * P_{IN} * k_{RF}} \quad (5)$$

Where  $k_{RF}$  is the current ripple factor,  $P_{IN}$  is the input power, and  $L_M$  is the primary inductance.

Calculate  $L_M$  based on the minimum input voltage condition.

The leakage inductance leads to power loss and voltage stress on the MOSFET. Normally, the leakage inductance should be controlled to be below 3% of the transformer inductance.

Once the CCM frequency  $f_{sw}$  and  $K_{RP}$  is set, the inductance of the transformer can be calculated:

Conditions			
$V_{IN\_MIN}$	42.5V	$V_{IN\_MAX}$	57V
$\Delta V_S$	30V	$V_{MOS\_ (BR)DS}$	150V
$P_{OUT} (max)$	25.2W	$V_{D\_F}$	0.5V
Ripple factor	0.4	$f_{sw}$	400kHz

(a) Compute turns ratio  $N_{PS}$  first

$$N_{PS} \leq \frac{V_{MOS\_ (BR)DS} \times 90\% - V_{DC\_MAX} - \Delta V_S}{V_{OUT} + V_{D\_F}} = \frac{150 * 0.9 - 57 - 30}{12.5} = 3.84$$

$N_{PS}$  is set to

$$N_{PS} = 3$$

(b) Compute maximum duty cycle and check the min  $T_{DIS}$  in heavy load (frequency accuracy and jitter need to be considered)

$$D_{MAX} = \frac{N_{PS} * (V_{OUT} + V_{D\_F})}{V_{IN\_MIN} + N_{PS} * (V_{OUT} + V_{D\_F})} = \frac{3 * (12 + 0.5)}{42.5 + 3 * (12 + 0.5)} = 0.469$$

$$T_{DIS\_MIN} = (1 - D_{MAX}) * T_{SW} = (1 - 0.469) * 2.5us * 90\% * 94\% = 1.123us > 600ns$$

(c) Compute inductor  $L_M$

$$L_M = \frac{(V_{IN\_MIN} * D_{MAX})^2}{2 * f_{sw} * P_{IN} * k_{RF}} = \frac{(42.5 * 0.469)^2}{2 * 400k * \frac{25.2}{0.88} * 0.4} = 43.31uH$$

Set:  $L_M = 42.0uH$

### MOSFET and DIODE Setting

The maximum voltage rating of the MOSFET and power diode are calculated at the maximum input voltage and full load.

$$V_{MOS\_DS\_MAX} = V_{DC\_MAX} + N_{PS} * (V_{OUT} + V_{D\_F}) + \Delta V_S \quad (6)$$

$$V_{D\_R\_MAX} = \frac{V_{DC\_MAX}}{N_{PS}} + V_{OUT} \quad (7)$$

Where  $V_{DC\_MAX}$  is maximum input DC voltage;  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the rated output voltage;  $V_{D\_F}$  is the forward voltage of secondary power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber during OFF time.

The maximum current rating of the MOSFET and power diode are calculated using minimum input voltage and full load:

$$I_{MOS\_PK\_MAX} = I_{P\_PK\_MAX} \quad (8)$$

$$I_{MOS\_RMS\_MAX} = I_{P\_RMS\_MAX} \quad (9)$$

$$I_{D\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} \quad (10)$$

$$I_{D\_AVG} = I_{OUT} \quad (11)$$

Where  $I_{P\_PK\_MAX}$  and  $I_{P\_RMS\_MAX}$  are maximum primary peak current and RMS current, which will be introduced later.

After setting the turns ratio and transformer inductance, the current stress of the MOSFET, diode and transformer winding can be calculated with:

$$I_{MOS\_PK\_MAX} = I_{P\_PK\_MAX} = \frac{P_{IN}}{Duty} * (1 + k_{RF}) \quad (12)$$

$$I_{MOS\_RMS\_MAX} = I_{P\_RMS\_MAX} = \sqrt{\int_0^{D*Ts} \left[ \frac{P_{IN}}{D} \frac{V_{IN\_MIN}}{V_{IN\_MIN} * (1 - k_{RF}) + \frac{V_{IN\_MIN}}{L_M} * t} \right]^2 dt} \quad (13)$$

$$I_{D\_PK\_MAX} = I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} \quad (14)$$

$$I_{D\_PK\_MAX} = I_{S\_RMS\_MAX} = \sqrt{\int_{D*Ts}^{Ts} \left[ \frac{N_{PS} * P_{IN}}{V_{IN\_MIN} * D} (1 + k_{RF}) - \frac{V_{OUT}}{L_M / N_{PS}^2} * (t - D * Ts) \right]^2 dt} \quad (15)$$

**(d)** Compute maximum primary peak current  $I_{P\_PK\_MAX}$ , primary RMS current  $I_{P\_RMS\_MAX}$ , secondary peak current  $I_{S\_PK\_MAX}$ , secondary RMS current  $I_{S\_RMS\_MAX}$ .

$$I_{P\_PK\_MAX} = \frac{P_{IN}}{D_{MAX}} * (1 + k_{RF}) = \frac{25.2}{0.469} * 0.88 (1 + 0.4) = 2.03A$$

$$I_{P\_RMS\_MAX} = \sqrt{\int_0^{D_{MAX} * Ts} \left[ \frac{P_{IN}}{D_{MAX}} \frac{V_{IN\_MIN}}{V_{IN\_MIN} * (1 - k_{RF}) + \frac{V_{IN\_MIN}}{L_M} * t} \right]^2 dt}$$

$$= \sqrt{\int_0^{1.1725\mu} \left[ \frac{0.862 + \frac{42.5}{42\mu} * t \right]^2 dt}$$

$$= 1.023A$$

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} = 3 * 2.03 = 6.09A$$

$$I_{S\_RMS\_MAX} = \sqrt{\int_{D_{MAX} * Ts}^{Ts} \left[ N_{PS} * I_{P\_PK\_MAX} - \frac{V_{OUT}}{L_M / N_{PS}^2} * (t - D_{MAX} * Ts) \right]^2 dt}$$

$$= \sqrt{\int_{1.1725\mu}^{2.5\mu} \left[ 6.09 - \frac{12}{4.67\mu} * (t - 1.1725\mu) \right]^2 dt}$$

$$= 2.977A$$

**(e)** Select secondary power diode

Refer to Power Device Design

Known conditions at this step			
$V_{DC\_MAX}$	57V	$N_{PS}$	3
$V_{OUT}$	12V	$V_{D\_F}$	0.5V

Compute the voltage and the current stress of secondary power diode

$$V_{D\_R\_MAX} = \frac{V_{DC\_MAX}}{N_{PS}} + V_{OUT} + \Delta V_S$$

$$= \frac{57V}{3} + 12V + 15V$$

$$= 46V$$

$$I_{D\_PK\_MAX} = N_{PS} * I_{P\_PK\_MAX} = 2.03 * 3 = 6.09A$$

$$I_{D\_PK\_MAX} = I_{S\_RMS\_MAX} = 2.977A$$

Set:

Secondary power diode: 10A/80V, Schottky Diode.

### Current Sense Resistor Selection

The current sense resistor can be used to limit the switching peak current. The current sense voltage at full load should be around 80% of the  $V_{CS\_MAX}$ , so the resistance can be calculated with:

$$R_{CS} = \frac{0.8 * V_{CS\_MAX}}{I_{P\_PK\_MAX}} \quad (16)$$

**(f)** Compute current sense resistor

$$R_{CS} = \frac{0.8 * V_{CS\_MAX}}{I_{P\_PK\_MAX}} = \frac{0.8 * 0.16}{2.03} = 0.063\Omega$$

Set:

$$R_{CS} = 60m\Omega$$

Then, check the  $T_{DIS}$  in no load:

$$T_{DIS\_MIN} = \frac{V_{CS\_MIN} * 0.90 * L_M * 0.95}{R_{CS} * 1.01 * N_{PS} * (V_{OUT} + V_{D\_F})} = 632ns > 600ns$$

## RCD Snubber for MOSFET

The power stored in leakage inductance is evaluated first.

$$P_{Lk} = 0.5 \cdot L_{Lk} \cdot I_{P\_PK\_MAX}^2 \times F_{sw} \quad (17)$$

Where  $L_{Lk}$  is the leakage inductance of the flyback transformer;  $I_{P\_PK}$  is the peak current of primary side.

The power of the leakage inductance will consume by the resistor  $R_{RCD}$ ,

$$R_{RCD} = \frac{[N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_S]^2}{P_{Lk}} \quad (18)$$

Where  $N_{PS}$  is the turns ratio of the flyback transformer;  $V_{OUT}$  is the output voltage;  $V_{D\_F}$  is the forward voltage of the power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber;

The  $C_{RCD}$  is related with the voltage ripple of the snubber  $\Delta V_{C\_RCD}$ .

$$C_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_S}{R_{RCD} \times f_S \times \Delta V_{C\_RCD}} \quad (19)$$

**(g)** Set RCD snubber.

Suppose the leakage inductance is 1% of the primary inductance.

$$V_{RCD} = N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_S = 57.5V$$

$$P_{RCD} = 0.5 \times 42\mu \times 0.01 \times 2.03^2 \times 400k = 0.346W$$

$$R_{RCD} = \frac{57.5^2}{0.346} = 9.55k\Omega$$

Select two 20k $\Omega$  resistors in parallel as  $R_{RCD}$ .

$$C_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_S}{R_{RCD} \times f_S \times \Delta V_{C\_RCD}} = \frac{57.5V}{20k \times 400k \times 0.3 \times 20V} \approx 2.2nF$$

## Transformer Turns Selection

The key transformer parameters are shown below:

Necessary parameters	
Primary to Secondary Turns ratio	$N_{PS}$
Inductance	$L_M$
Primary maximum current	$I_{P\_PK\_MAX}$
Primary maximum RMS current	$I_{P\_RMS\_MAX}$
Secondary maximum RMS current	$I_{S\_RMS\_MAX}$

The design rules are as followed:

**(S1)** Select the magnetic core style, identify the effective cross-sectional area  $A_e$ . There select EP13 for compute example. Its  $A_e$  is 19.50 mm<sup>2</sup>. The EP13 can be replaced by other reasonable magnetic core style.

**(S2)** Preset the maximum magnetic flux density  $\Delta B$  is 0.26T at minimum BUS voltage and full load condition:

Usually  $\Delta B = 0.2T \sim 0.3T$ , set  $\Delta B = 0.2$

**(S3)** Compute primary turn  $N_P$

$$N_P = \frac{L_M \cdot I_{P\_PK\_MAX}}{\Delta B \cdot A_e} = \frac{42\mu H \times 2.03}{0.20T \times 19.50mm^2} = 21.86$$

$N_P$  is set to 21

Where  $A_e$  is effective cross-sectional area of core

**(S4)** Compute secondary turn  $N_S$

$$N_S = \frac{N_P}{N_{PS}} = \frac{21}{3} = 7$$

$N_S$  is set to 7

**(S5)** Compute auxiliary turn  $N_{AUX}$

Generally, minimum VCC pin voltage should be guaranteed to be above VCC\_MIN, so set VCC=10V. Turns of auxiliary winding can be initially calculated as below equation:

$$N_{AUX} = N_S \cdot \frac{V_{VCC}}{V_{OUT}} = 7 \times \frac{10}{12} = 5.83$$

$N_{AUX}$  is set to 6

**(S6)** Select an appropriate wire diameter

With  $I_{P\_RMS\_MAX}$  and  $I_{S\_RMS\_MAX}$ , select appropriate wire to achieve the current density from 4A/mm<sup>2</sup> to 10A/mm<sup>2</sup>.

**Primary wire diameter selection:** current density  $j$  is set to 12A/mm<sup>2</sup>. The compute primary wire cross-sectional area:

$$S_{Pri} = \frac{I_{P\_RMS\_MAX}}{j} = \frac{1.023}{10} = 0.1023mm^2$$

Selected wire diameter, set  $D1 = 0.15mm$

Number of wire to be paralleled,

$$N_{P\_wire} = \frac{S_{Pri}}{\pi \cdot \left(\frac{D1}{2}\right)^2} = \frac{0.1023}{\pi \cdot \left(\frac{0.15}{2}\right)^2} = 5.79$$

Set  $N_{P\_wire} = 6$

**Secondary wire diameter selection:** current density  $j$  is set to 12A/mm<sup>2</sup>. The compute secondary wire cross-sectional area:

$$S_{SEC} = \frac{I_{S\_RMS\_MAX}}{j} = \frac{2.977}{12} = 0.2481mm^2$$

Selected wire diameter, set  $D2 = 0.20mm$

Number of wire to be paralleled,

$$N_{S\_wire}' = \frac{S_{SEC}}{\pi * (\frac{D2}{2})^2} = \frac{0.2481}{\pi * (\frac{D2}{2})^2} = 7.90$$

Set  $N_{S\_wire}=8$

Consider transformer style, the actual primary and secondary wire diameter can be adjusted for best production.

**(S7)** If the window area of the core and bobbin is not enough, reselect the core style, go to (S1) and redesign the transformer until the ideal transformer is achieved.

**(S8)** The transformer final parameters are shown below

Item	Specification	Remark
EP13 (42.5VDC~57VDC, 25.2W)		
Primary-Side Inductance	42uH±5%	40kHz, 1V, 25±5 °C, Hum:65 ±25%
Primary-Side Leakage Inductance	1.20µH Maximum	Short One of Secondary Winding
$N_P$	21(0.15mm*6)	
$N_S$	7(0.20mm*8)	
$N_A$	6(0.15mm*1)	

### Set MODE/FRS Pin

Let MODE/FRS pin float to set 400kHz PSR mode operation.

### Set FB Pin

Refer to Output Voltage Control in PSR Mode part.

Available from the previous design:  $N_S=7, N_{AUX}=6$

First identify  $R_{FBU}$  need for line regulation.

Parameters Designed			
$R_{FBU}$	39kΩ		

Then compute  $R_{FBD}$

Conditions			
$V_{OUT}$	12V	$V_{FB\_REF}$	1.2V

$R_{FBU}$	39kΩ		
-----------	------	--	--

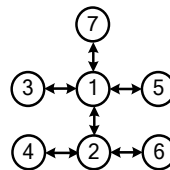
$$R_{FBD} = \frac{R_{FBU}}{\frac{V_{OUT} * N_{AUX}}{V_{FB\_REF} * N_S} - 1} = \frac{39k}{\frac{12V * 6}{1.2V * 7} - 1} \approx 5.1k$$

## Layout

(a) To achieve better EMI performance and reduce the line frequency ripple, the output of the bridge rectifier should be connected to the BUS line capacitor first, then to the switching circuit.

(b) The circuit loop of all switching loops should be kept small: primary power loop, secondary loop and auxiliary power loop.

(c) The connection of primary ground is recommended as shown below:



Ground ①: ground of BUS capacitor.

Ground ②: ground of bias supply capacitor.

Ground ③: ground node of auxiliary winding.

Ground ④: ground node of resistor divider.

Ground ⑤: primary ground node of Y capacitor.

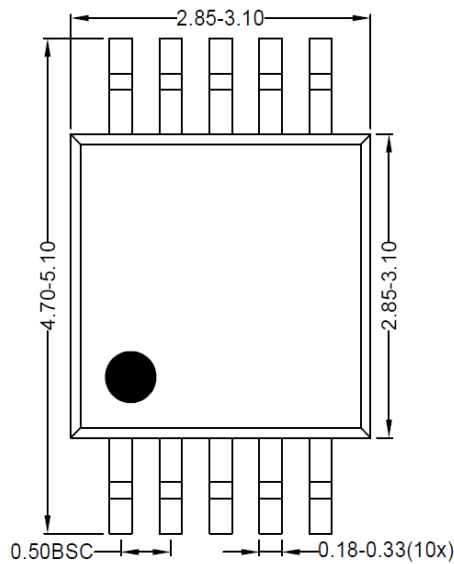
Ground ⑥: device GND.

Ground ⑦: ground of current sense resistor.

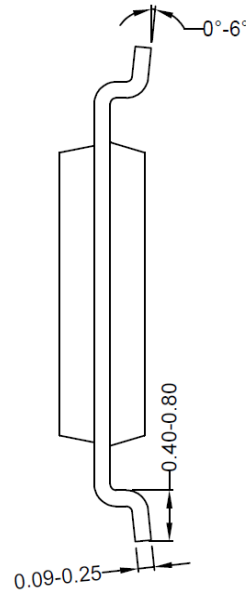
(d) Bias supply trace should be connected to the bias supply capacitor first instead of GND pin. The bias supply capacitor should be put beside the IC.

(e) Place the FB resistor divider near the the IC.

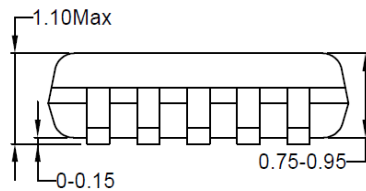
# MSOP10 Package outline & PCB layout



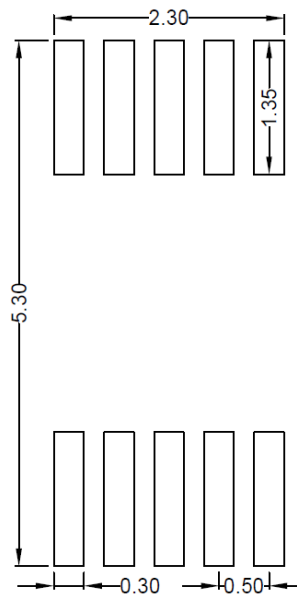
**Top view**



**Side view**



**Front view**



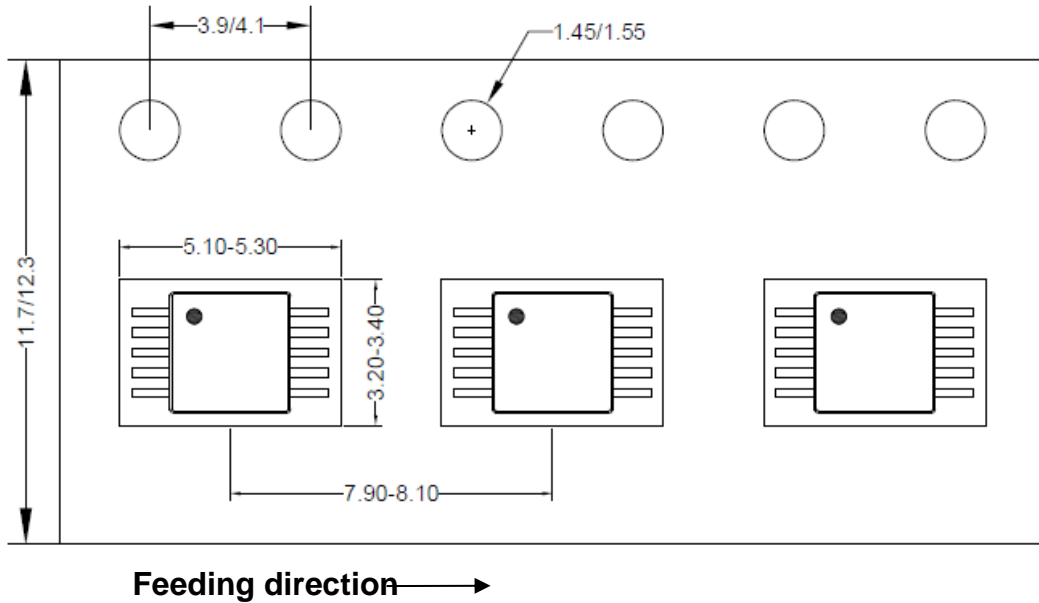
**Recommended Pad Layout  
(reference only)**

**Notes: All dimension in millimeter and exclude mold flash & metal burr.**

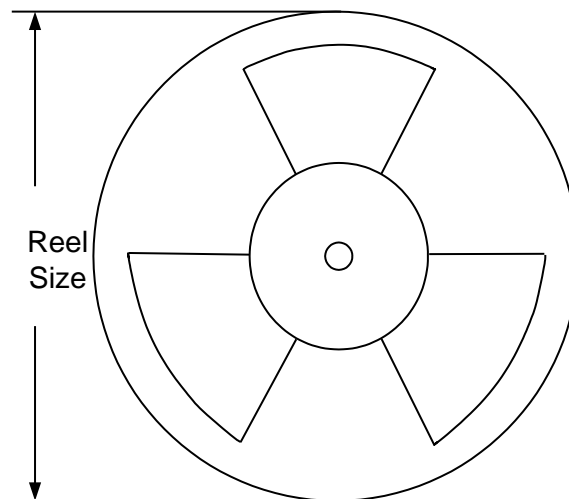
## Taping & Reel Specification

### 1. Taping Orientation

MSOP10



### 2. Carrier Tape & Reel Specification for Packages



Package types	Tape width (mm)	Pocket pitch(mm)	Reel size (Inch)	Trailer length(mm)	Leader length (mm)	Qty per reel
MSOP10	12	8	13"	400	400	3000

### 3. Others: NA

## Revision History

The revision history provided is for informational purpose only and is believed to be accurate, however, not warranted. Please make sure that you have the latest revision.

<b>Date</b>	<b>Revision</b>	<b>Change</b>
October 28, 2024	Revision 1.0	Initial Release

## IMPORTANT NOTICE

1. **Right to make changes.** Silergy and its subsidiaries (hereafter Silergy) reserve the right to change any information published in this document, including but not limited to circuitry, specification and/or product design, manufacturing or descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products are sold subject to Silergy's standard terms and conditions of sale.

2. **Applications.** Application examples that are described herein for any of these products are for illustrative purposes only. Silergy makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification. Buyers are responsible for the design and operation of their applications and products using Silergy products. Silergy or its subsidiaries assume no liability for any application assistance or designs of customer products. It is customer's sole responsibility to determine whether the Silergy product is suitable and fit for the customer's applications and products planned. To minimize the risks associated with customer's products and applications, customer should provide adequate design and operating safeguards. Customer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Silergy assumes no liability related to any default, damage, costs or problem in the customer's applications or products, or the application or use by customer's third-party buyers. Customer will fully indemnify Silergy, its subsidiaries, and their representatives against any damages arising out of the use of any Silergy components in safety-critical applications. It is also buyers' sole responsibility to warrant and guarantee that any intellectual property rights of a third party are not infringed upon when integrating Silergy products into any application. Silergy assumes no responsibility for any said applications or for any use of any circuitry other than circuitry entirely embodied in a Silergy product.

3. **Limited warranty and liability.** Information furnished by Silergy in this document is believed to be accurate and reliable. However, Silergy makes no representation or warranty, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. In no event shall Silergy be liable for any indirect, incidental, punitive, special or consequential damages, including but not limited to lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges, whether or not such damages are based on tort or negligence, warranty, breach of contract or any other legal theory. Notwithstanding any damages that customer might incur for any reason whatsoever, Silergy's aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Standard Terms and Conditions of Sale of Silergy.

4. **Suitability for use.** Customer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of Silergy components in its applications, notwithstanding any applications-related information or support that may be provided by Silergy. Silergy products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an Silergy product can reasonably be expected to result in personal injury, death or severe property or environmental damage. Silergy assumes no liability for inclusion and/or use of Silergy products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

5. **Terms and conditions of commercial sale.** Silergy products are sold subject to the standard terms and conditions of commercial sale, as published at <http://www.silergy.com/stdterms>, unless otherwise agreed in a valid written individual agreement specifically agreed to in writing by an authorized officer of Silergy. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. Silergy hereby expressly objects to and denies the application of any customer's general terms and conditions with regard to the purchase of Silergy products by the customer.

6. **No offer to sell or license.** Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights. Silergy makes no representation or warranty that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right. Information published by Silergy regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from Silergy under the patents or other intellectual property of Silergy.

For more information, please visit: [www.silergy.com](http://www.silergy.com)

©2024 Silergy Corp.

All Rights Reserved.